# TPS65910 User Guide for OMAPL-137, OMAPL-138, and TMS320C674x Family of Processors

# **User's Guide**



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# TPS65910 User Guide For OMAPL-137, OMAPL-138, and TMS320C674x Family of Processors

This user's guide can be used as a reference for connectivity between the TPS65910 power-management integrated circuit (PMIC) and TI OMAPL, TMS320C674x processors.

#### 1 Introduction

This user's guide can be used as a reference for connectivity between the TPS65910 PMIC and TI OMAPL, TMS320C674x processors. This user guide does not provide details about the power resources or the functionality of the device. For such information, refer to the full specification document, *TPS65910 Data Manual*.



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### 2 Platform Connection

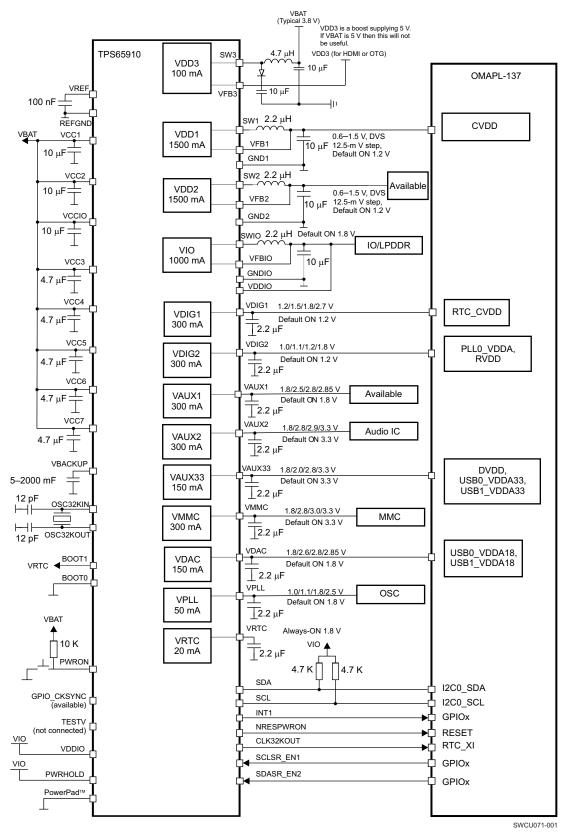
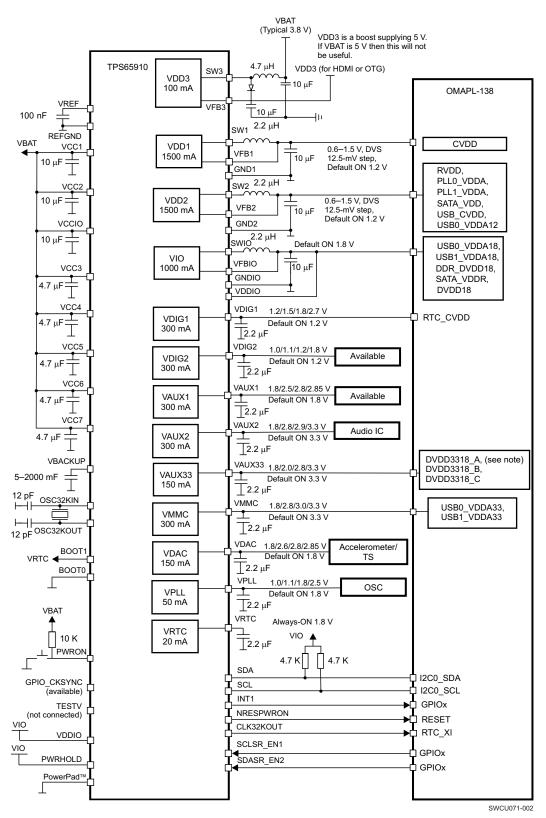


Figure 1. OMAPL-137 Power Supply Connections With TPS65910

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NOTE: If only 1.8 V operation is required, then these domains can be merged with 1.8 V on VIO.

Figure 2. OMAPL-138, TMS320C6742/6/8 Power Connections With TPS65910

At power up, the maximum current capability (default setting) of the DCDC converters is as follows:

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- VIO(max) = 500 mA
- VDD1(max) = 1000 mA
- VDD2(max) = 1000 mA

To have the maximum current capability, the user must program the following register bits:

- VIO REG[ILMAX] = b01 for 1 A
- $VDD1_REG[ILMAX] = b1 \text{ for } 1.5 \text{ A}$
- VDD2\_REG[ILMAX] = b1 for 1.5 A

#### 3 **Power-Up Sequencing**

#### Power-Up Sequence for OMAPL-138 and TMS320C6742/6/8 Processors 3.1

The following sections show the power-up sequence requirement for OMAPL-138 and TMS320C6742/6/8 processors. To power on the system, the user must press and release the PWRON switch (generating a negative pulse). The BOOT pads on the TPS65910 must be connected as follows:

- BOOT0 = 0
- BOOT1 = 1

Table 1 lists the power rail requirements for OMAPL-138, TMS320C6742/6/8.

Table 1. Power Rail Requirements for OMAPL-138, TMS320C6742/6/8

Power Domain	Pin Name	I <sub>max</sub> (mA)	Voltage (V)	Sequence
I/O	RTC_CVDD	1	1.2	1 <sup>(1)</sup>
Core	CVDD <sup>(2)</sup>	600	1.0/1.1/1.2	2
I/O	RVDD, PLL0_VDDA, PLL1_VDDA, SATA_VDD, USB_CVDD, USB0_VDDA12	200	1.2	3
I/O	USB0_VDDA18, USB1_VDDA18, DDR_DVDD18, SATA_VDDR, DVDD18	180	1.8	4
I/O	USB0_VDDA33, USB1_VDDA33 <sup>(3)(4)</sup>	24	3.3	5
I/O	DVDD3318_A, DVDD3318_B, DVDD3318_C	90 <sup>(5)</sup>	3.3	5

<sup>(1)</sup> If RTC is not used/maintained on a separate supply, it can be included in the STATIC12 (fixed 1.2 V) group.

#### 3.2 Power-Up Sequence for OMAPL-137 Processor

Table 2 lists the power rail requirements for OMAPL-137.

Table 2. Power Rail Requirements for OMAPL-137

Power Domain	Pin Name	I <sub>max</sub> (mA)	Voltage (V) <sup>(2)</sup>	Sequence
Core	RTC_CVDD <sup>(1)</sup>	0.1	1.2	1
	CVDD	600	1.2	2
	PLL0_VDDA, RVDD	60	1.2	3
I/O	USB0_VDDA18, USB1_VDDA18	50	1.8	5
I/O	DVDD, USB0VDDA33, USB1_VDDA33	115	3.3	4

<sup>(2)</sup> If using CVDD at fixed 1.2 V, all 1.2-V rails may be combined. CVDD can support 1.3 V; in this case SMPS (VDD1) supplying CVDD core can be set to 1.3-V after initial power up.

<sup>(3)</sup> If 1.8-V LVCMOS is used, power rails up with the 1.8-V rails. If 3.3-V LVCMOS is used, power it up with the ANALOG33 rails (VDDA33\_USB0/1).

<sup>(4)</sup> There is no specific required voltage ramp rate for any of the supplies LVCMOS33 (USB0\_VDDA33, USB1\_VDDA33) that never exceeds STATIC18 by more than 2 V.

If DVDD3318\_A, B, and C are powered independently, maximum power for each rail will be 1/3 the above maximum power. These rails can be connected independently to 1.8 or 3.3 V.



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(1) RTC\_CVDD can be combined with PLL and RAM 1.2-V supplies if desired to turn off RTC when device is off. Otherwise, power RTC\_CVDD separately with a dedicated power source.

#### (2) Sequencing 1.2-V supplies:

- (a) RTC (RTC\_CVDD) may be powered from an external device (such as a battery) before all other supplies are applied. If the RTC is not used, RTC\_CVDD must be connected to CVDD.
- (b) Group 2a: CVDD core logic supply. CVDD can support 1.3 V, in this case SMPS (VDD1) supplying CVDD core can be set to 1.3 V after initial power up.
- (c) Group 2b: Other 1.2-V logic supplies (RVDD, PLL0\_VDDA). Groups 2a and 2b may be powered up together or 2a first followed by 2b.

NOTE: To correctly power on the device, the PWRHOLD signal must be high after PWRON is pressed. In this configuration the PWRHOLD signal on TPS65910 is connected to VIO. PWRHOLD transitions to high when VIO powers up.

#### 3.3 Power-Up Sequence for TPS65910

To satisfy the power-up requirements for the OMAPL-138 and TMS320C6742/4/6 processorsprocessor, the TPS65910 powers up with the default sequence when in the EEPROM boot mode configuration (BOOT0 = 0 and BOOT1 = 1) (see Table 3). The correct power-up sequence is configured in the EEPROM (factory programmable only).

Apart from the main power rails required by the processors, all other rails are also powered up at initial power up to support other system peripherals.

Figure 3 shows a typical power-up timing diagram.

Table 3 shows the power-up sequence.

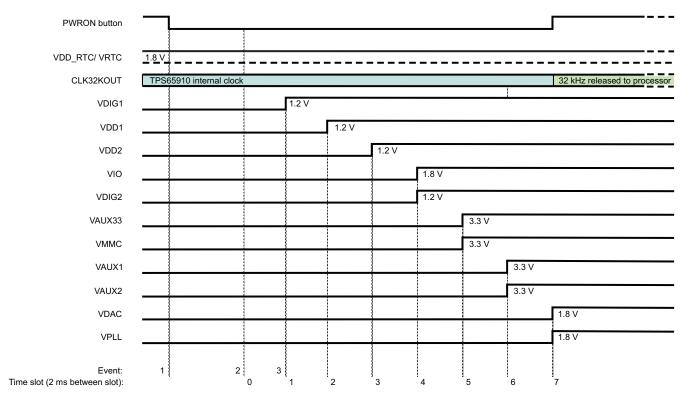
Table 3. Power-Up Sequence for TPS65910

TPS65910 Power Rail	Voltage (V)	Sequence Number	Delay (ms)
PWRON <sup>(1)</sup>	-	_	
VDIG1	1.2	1	2
VDD1	1.2	2	2
VDD2	1.2	3	2
VIO	1.8	4	2
VDIG2	1.2	4	0
VAUX33	3.3	5	2
VMMC	3.3	5	0
VAUX1	1.8	6	2
VAUX2	3.3	6	0
VDAC	1.8	7	2
VPLL	1.8	7	0

The PWRON signal is the start-on event. All timings listed are with respect to the previous event.



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Event description:

- 1 PWRON button press falling edge
- 2 Valid press after debounce
- 3 First step of power-up sequence available for DCDC, LDO activation. Time slot 0 is for internal use.
- Note: PWRON press must be maintained until PWRHOLD acknowledge, or, for shorter PWRON press,

PWRHOLD must go high within 984 ms of valid PWRON press (event 2). To ensure this, PWRHOLD is tied to VIO.

SWCU071-003

Figure 3. Power-Up Timing Diagram

**Table 4. EEPROM Configuration for TPS65910** 

Register	Bit	Description	Option Selected
VDD1_OP_REG	SEL	VDD1 voltage level selection for boot	1.2 V
VDD1_REG	VGAIN_SEL	VDD1 gain selection, x1 or x2	x1
EEPROM		VDD1 time slot selection	2
DCDCCTRL_REG	VDD1_PSKIP	VDD1 pulse skip mode enable	Skip enabled
VDD2_OP_REG / VDD2_SR_REG	SEL	VDD2 voltage level selection for boot	1.2 V
VDD2_REG	VGAIN_SEL	VDD2 gain selection, x1 or x3	x1
EEPROM		VDD2 time slot selection	3
DCDCCTRL_REG	VDD2_PSKIP	VDD2 pulse skip mode enable	Skip enabled
VIO_REG	SEL	VIO voltage selection	1.8 V
EEPROM		VIO time slot selection	4
DCDCCTRL_REG	VIO_PSKIP	VIO pulse skip mode enable	Skip enabled
EEPROM		VDD3 time slot	OFF
VDIG1_REG	SEL	LDO voltage selection	1.2
EEPROM		LDO time slot	1
VDIG2_REG	SEL	LDO voltage selection	1.2 V
EEPROM		LDO time slot	4
VDAC_REG	SEL	LDO voltage selection	1.8 V
EEPROM		LDO time slot	7



Table 4. EEPROM Configuration for TPS65910 (continued)

Register	Bit	Description	Option Selected
VPLL_REG	SEL	LDO voltage selection	1.8 V
EEPROM		LDO time slot	7
VAUX1_REG	SEL	LDO voltage selection	1.8 V
EEPROM		LDO time slot	6
VMMC_REG	SEL	LDO voltage selection	3.3 V
EEPROM		LDO time slot	5
VAUX33_REG	SEL	LDO voltage selection	3.3 V
EEPROM		LDO time slot	5
VAUX2_REG	SEL	LDO voltage selection	3.3 V
EEPROM		LDO time slot	6
CLK32KOUT pin		CLK32KOUT time slot	7
NRESPWRON pin		NRESPWRON time slot	7 + 1
VRTC_REG	VRTC_OFFMASK	0 = VRTC LDO will be in low-power mode during OFF state. 1 = VRC LDO will be in full-power mode during OFF state.	Low-power mode
DEVCTRL_REG	RTC_PWDN	0 = RTC in normal power mode 1 = Clock gating of RTC register and logic, low-power mode	1
DEVCTRL_REG	CK32K_CTRL	0 = Clock source is crystal/external clock. 1 = Clock source is internal RC oscillator.	Crystal
DEVCTRL2_REG	TSLOT_LENGTH	Boot sequence time slot duration: 0 = 0.5 ms 1 = 2 ms	2 ms
DEVCTRL2_REG	IT_POL	0 = INT1 signal will be active low. 1 = INT1 signal will be active high.	1
INT_MSK_REG	VMBHI_IT_MSK	0 = Device automatically switches on at NO SUPPLY-to-OFF or BACKUP-to-OFF transition. 1 = Start-up reason is required before switch-on.	0 = Automatic switch on from supply insertion
VMBCH_REG	VMBCH_SEL[1:0]	Select threshold for main battery comparator threshold VMBCH.	3 V

# 4 Getting Started With TPS65910 and OMAPL-137, OMAPL-138, and TMS320C6742/6/8 Processors

#### 4.1 First Initialization

# 4.1.1 I/O Polarity/Muxing Configuration

Program DEVCTRL2\_REG.SLEEPSIG\_POL according to the GPIO from the processor. This can be set to active low or active high for SLEEP transition. Software configuration allows specific power resources to enter low consumption state.

Set DEVCTRL\_REG.DEV\_SLP = 1 to allow SLEEP transition when requested.

Update the GPIO0 configuration (GPIO0\_REG) based on your needs.

# 4.1.2 Define Wake-Up/Interrupt Event (SLEEP or OFF)

Select the appropriate bits in the INT\_MSK\_REG and INT\_MSK2\_REG registers to activate an interrupt to the processor on the INT1 line.



# 4.1.3 Backup Battery Configuration

If the system has a backup battery, set the BBCHEN bit to 1 in the BBCH\_REG register, to enable backup battery charging. The maximum voltage to which the backup battery is charged is set by the BBSEL bits.

## 4.1.4 DCDC and Voltage Scaling Resource Configuration

Set DEVCTRL\_REG[SR\_CTL\_I2C\_REG] = 1 to control register using the control I<sup>2</sup>C interface. Using the SCLSR\_EN1 and SDASR\_EN2 signals, the user can control the power resources. For OMAPL series, the following example is provided:

- SMPS control:
  - Configure two operating voltages for DCDC1 and DCDC2:
    - VDDx\_OP\_REG.SEL= Roof voltage (ENx ball high)
    - VDDx\_SR\_REG.SEL = Floor voltage (ENx ball low)
  - Assign control for VDD1 to SCLSR\_EN1:
    - Set EN1\_SMPS\_ASS\_REG.VDD1\_EN1 = 1
    - Set SLEEP\_KEEP\_RES\_ON\_REG.VDD1\_KEEPON = 1 (allow low-power mode)
- LDO control:
  - Assign control for VMMC regulator (for example, can be used for any other set of registers).
  - Set EN2\_LDO\_ASS\_REG.VMMC EN2 = 1
  - When SDASR\_EN2 control signal is high then the regulator output depends on SLEEP\_KEEP\_LDO\_ON setting.
  - SDASR\_EN2 = 1, VMMC status is active.
  - SDASR\_EN2 = 0 then:
    - SLEEP\_KEEP\_LDO\_ON[VMMC\_KEEPON] = 0, VMMC output is off.
    - SLEEP KEEP LDO ON[VMMC KEEPON] = 1, VMMC output is on in LOW-POWER state.

### 4.1.5 Sleep Platform Configuration

Configure the state of the LDOs when the SLEEP signal is used (by default all resources go into SLEEP state; in SLEEP state the LDO voltage is maintained but transient and load capability are reduced).

Resources that must provide full load capability must be set in the SLEEP KEEP LDO ON REG register.

Resources that can be set off in SLEEP state to optimize power consumption must be set in the SLEEP\_SET\_LDO\_OFF\_REG register.

# 4.2 Event Management Through Interrupts

#### 4.2.1 INT STS REG.VMBHI IT

INT\_STS\_REG.VMBHI\_IT indicates that the supply (VBAT) is connected (leaving the BACKUP or NO SUPPLY state), the system must be initialized. (See Section 4.1, First Initialization.)

## 4.2.2 INT\_STS\_REG.PWRON\_IT

INT\_STS\_REG.PWRON\_IT is triggered when the PWRON button is pressed. If device is in OFF or SLEEP state, then this acts as a wake-up event and resources are reinitialized.

#### 4.2.3 INT STS REG.PWRON LP IT

INT\_STS\_REG.PWRON\_LP\_IT is the PWRON long-press interrupt. This interrupt is generated when the PWRON button is pressed for 6 seconds. The application processor can make a decision to acknowledge the interrupt. If this interrupt is not acknowledged in the next 2 seconds then the device interprets this as a power-down event.



#### 4.2.4 INT STS REG.HOTDIE IT

INT\_STS\_REG.HOTDIE\_IT indicates that the temperature of die is reaching the limit. Software must take action to decrease the power consumption before automatic shutdown.

#### 4.2.5 INT STS REG.VMBDCH IT

INT\_STS\_REG.VMBDCH\_IT idicates that the input supply is low and the processor must prepare a shutdown to prevent losing data. This interrupt is linked to VBAT but does not apply to a system where PMIC is connect to 5-V rails and not directly to VBAT.

## 4.2.6 INT STS2 REG.GPIO R/F IT

INT\_STS2\_REG.GPIO\_R/F\_IT is the GPIO interrupt event and can be used to wake up the device from SLEEP state. This can be an interrupt coming from any peripheral device or alike.

NOTE: This wake-up event is not valid for a transition from OFF state.

# 4.2.7 INT\_STS\_REG. RTC\_ALARM\_IT

INT\_STS\_REG. RTC\_ALARM\_IT is triggered when the RTC alarm set time is reached.



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# **Revision History**

Changes from A Revision (#IMPLIED) to B Revision		
•	Updated VAUX2 to 300 mA in Figure 1 and Figure 2	!
•	Updated Table 4 to replace DEVCTRL2_REG option selected "Active Low" by 1.	

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

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#### FCC Interference Statement for Class B EVM devices

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- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- · Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

#### 3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210

#### **Concerning EVMs Including Radio Transmitters:**

This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

#### Concernant les EVMs avec appareils radio:

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Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

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Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur

#### 3.3 Japan

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- Use EVMs in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
- 2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
- 3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

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  - 4.2 User must read and apply the user guide and other available documentation provided by TI regarding the EVM prior to handling or using the EVM, including without limitation any warning or restriction notices. The notices contain important safety information related to, for example, temperatures and voltages.
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  - 4.4 User assumes all responsibility and liability to determine whether the EVM is subject to any applicable international, federal, state, or local laws and regulations related to User's handling and use of the EVM and, if applicable, User assumes all responsibility and liability for compliance in all respects with such laws and regulations. User assumes all responsibility and liability for proper disposal and recycling of the EVM consistent with all applicable international, federal, state, and local requirements.
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