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ABSTRACT

The F280025C controlCARD (TMDSCNCD280025C) from Texas Instruments (TI) provides a great way to learn and experiment with F28002x devices. The F28002x devices are members of TI's C2000™ family of microcontrollers (MCUs). This 120-pin controlCARD is intended to provide a well-filtered robust design that is capable of working in most environments. This document provides the hardware details of the F280025C controlCARD and explains the functions, locations of jumpers, and connectors present on the board.

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1 Introduction

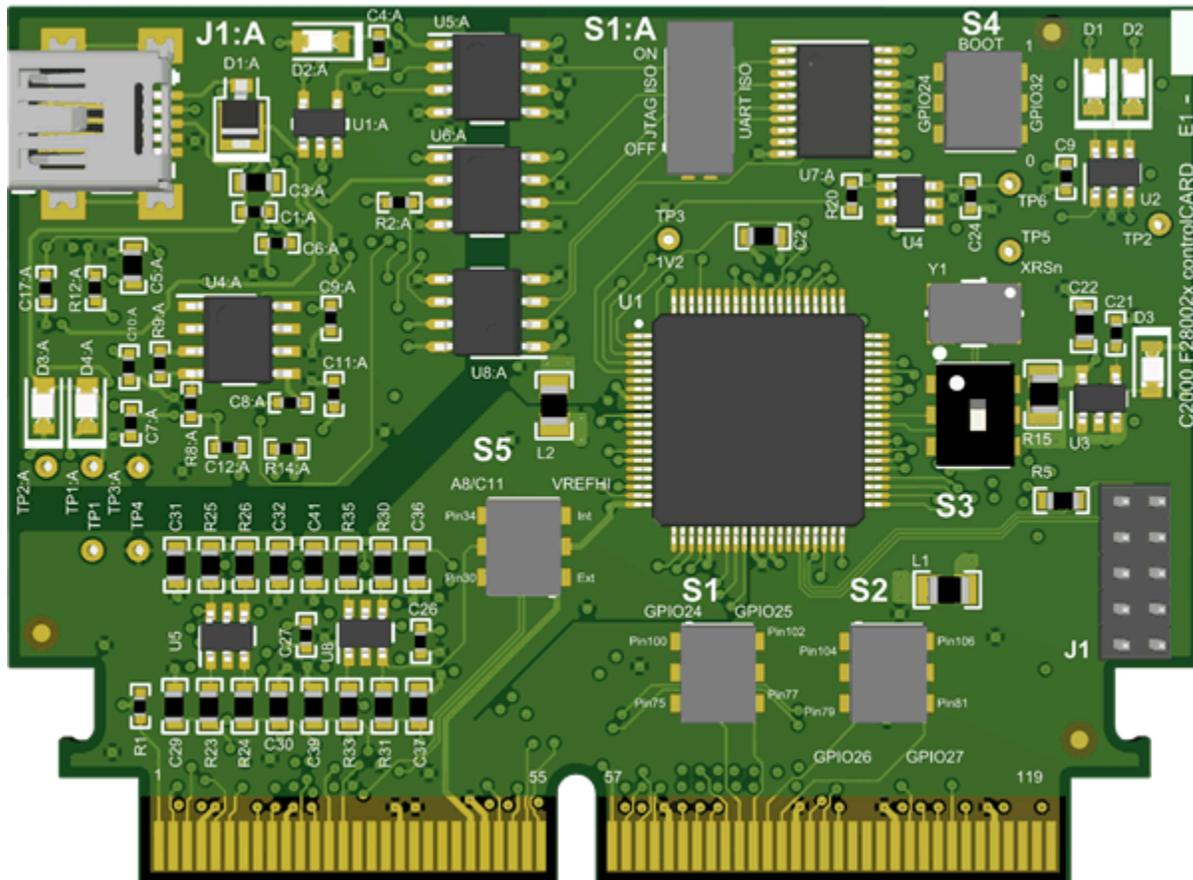


Figure 1-1. F280025C controlCARD

Each controlCARD comes with a Hardware Developer's Kit, which is a full set of files necessary to evaluate and develop with a C2000 device. These files include:

- Schematics – Designed in Altium
- Bill of Materials (BOM)
- Layout PCB files - Designed in Altium
- Gerber files

The Hardware Developer's Kit for the controlCARD can be found in the C2000Ware at the following location:

- <install_directory>\c2000\C2000Ware_x_xx_xx_xx\boards\controlCARDs\TMDSCNCD280025C\Revx

Note

This kit is designed to explore the functionality of F28002x microcontrollers. The controlCARD can be treated as a good reference design; it is not intended to be a complete customer design. Full compliance to safety, EMI/EMC, and other regulations are left to the designer of the customer's system.

2 Hardware Quick Setup Guide

WARNING

When the controlCARD is used in a high-voltage setup, it is the user's responsibility to confirm that the voltages and isolation requirements are identified and understood prior to energizing the board or simulation. When energized, the controlCARD or components connected to the controlCARD should not be touched. Furthermore, the capacitor C26:A should be removed to minimize the possibility of leakage current flowing across the isolation barrier of the controlCARD.

1. Connect and power embedded emulator.
 - a. Connect USB-B "mini" connector to J1:A
2. Provide power to the isolated F280025C device.
 - a. Insert the TMDSCNCD280025C controlCARD into a [TMDSHSECDOCK](#), or other compatible docking station.
 - b. Connect USB-B "mini" connector to J17 of the [TMDSHSECDOCK](#).
 - c. Flip S1 to the "USB-ON" position. D3 of the controlCARD should illuminate.
3. For a detailed explanation of the hardware configuration, see [Section 4.3](#).

3 Errata

Current revision of controlCARD as of 3/20/2020: PCB rev - A , ASSY rev - none

3.1 Warnings, Notes, and Errata

- The F280025C Experimenter's Kit ships with a USB cable and is designed to be powered via USB. However, in extreme cases the board/controlCARD may require more power than the 5 V @ 500 mA (USB 3.0 - 900 mA) that a computer's USB port can provide. This is especially true when additional circuitry has been added to the docking station. In such cases, it is recommended to use an external 5 V power supply (2.5 mm inner diameter x 5.5 mm outer diameter) and plug it into J1. A compatible supply such as:
 - Phihong PSAC05R-050(P)-R-C2 + Phihong RPBAG

3.2 Warnings About Specific controlCARD Revisions

MCU072E1

- 1.2-V and 3.3-V monitor pins (HSEC pins 118 and 119, respectively) were not implemented

MCU072A

- None

4 Getting Familiar With the controlCARD

4.1 F280025C controlCARD Features

- **F280025C Microcontroller** – High performance C2000 microcontroller is located on the controlCARD.
- **120-pin HSEC8 Edge Card Interface** – Allows for compatibility with all of C2000’s 180-pin controlCARD-based application kits and controlCARDs. Compatibility with 100-pin controlCARDs can be accomplished using the TMD SADAP180TO100 adapter card (sold separately).
- **Built-in Isolated JTAG Emulation** – An XDS100v2 emulator provides a convenient interface to Code Composer Studio™ without additional hardware. Flipping a switch allows an external JTAG emulator to be used.
- **Connectivity** – The controlCARD contains connectors that allow the user to experiment with isolated universal asynchronous receiver/transmitter (UART)/SCI with the F280025C MCU.
- **Key Signal Breakout** – Most GPIO, analog-to-digital converter (ADC) and other key signals routed to hard gold connector fingers.
- **Robust Power Supply Filtering** – Single 5 V input supply powers an on-card 3.3 V LDO. All MCU inputs are then decoupled using LC filters near the device.
- **ADC Clamping** – ADC inputs are clamped by protection diodes.
- **Anti-Aliasing Filters** – Noise filters (small RC filters) can be easily added on ADC input pins.

4.2 Assumed Operating Conditions

This kit is assumed to run at standard room conditions. Standard ambient temperature and pressure (SATP) with moderate-to-low humidity is assumed.

4.3 Using the controlCARD

In order for the controlCARD to operate, the controlCARD’s MCU must be powered. This is most often done by inputting 5 V through the HSEC connector via an accompanying baseboard. For example, if using a TMD SHSECDOCK docking station baseboard, 5 V DC should be input into the docking station’s J1 or J17. Then, S1 needs to be toggled to the appropriate position.

Based on the way the controlCARD is used, additional hardware settings will be necessary (see [Table 4-1](#)).

WARNING

When the controlCARD is used in a high-voltage setup, it is the user’s responsibility to confirm that the voltages and isolation requirements are identified and understood prior to energizing the board or simulation. When energized, the controlCARD or components connected to the controlCARD should not be touched. Furthermore, the capacitor C26:A should be removed to minimize the possibility of leakage current flowing across the isolation barrier of the controlCARD.

Table 4-1. Emulator Switch Selections

	Debug Using CCS and the On-Card XDS100v2 Emulator	Debug Using CCS and an External Emulator via the Baseboard	Standalone (Boot From FLASH or Other Boot Mode)
S1:A	Position 1: ON (up)	Position 1: OFF (down)	Position 1: OFF (down)
J1:A	Connect a mini USB cable between J1:A and your computer. In CCS, use this target configuration: TMS320F280025C device with an XDS100v2 emulator.	---	---
S4	Position 1: up- Logic 1 Position 2: down- Logic 0 Putting the C2000 device into Wait Mode can reduce the risk of connectivity issues.	Position 1: down- Logic 1 Position 2: up- Logic 0 Putting the C2000 device into Wait Mode can reduce the risk of connectivity issues.	Set S4 as desired
Baseboard’s JTAG connector (J2 on Docking Station)	---	Connect an external emulator.	---

Code Composer Studio is an Integrated Development Environment (IDE) used to debug and develop software for the C2000 series of MCUs. It can be downloaded from the following link: <https://www.ti.com/tool/ccstudio>.

The following PDF documents are provided, as part of C2000Ware, to describe where each of the F280025C MCU's pins will appear on the controlCARD connector/docking station:

- **TMDSCNCD280025C_120cCARD_map**– Tells where each MCU pin will go on the HSEC controlCARD connector or the 120/180-pin controlCARD docking station.
- **TMDSCNCD280025C_100DIM_map** – Tells where each MCU pin will go to on the DIM100 controlCARD connector or the DIM100 docking station. This assumes that the TMD SADAP180TO100 adapter card is used.

More information on the controlCARD docking station can be found at the following location:

- <install directory>\c2000\C2000Ware_x_xx_xx_xx\boards\controlCARDs\TMDSCNCD280025C\Rx_x

4.4 Experimentation Software

[Code Composer Studio \(CCS\) Integrated Development Environment \(IDE\)](#) is recommended for developing and debugging software for the C2000 series of MCUs. CCS is free to download and use with the controlCARD. Introductory videos for CCS are available at training.ti.com.

[C2000Ware](#) contains a full suite of example software designed to work with the F280025C controlCARD.

This software package includes many example projects that allow the user to experiment with the ADC, PWM, and other C2000 peripherals.

Support files for both register-level and driver-level programming are included with C2000Ware:

- Register header files are located at: \ti\c2000\C2000Ware_XXXX\device_support\F28002x\examples
- Driverlib programming examples are located at: \ti\c2000\C2000Ware_XXXX\driverlib\F28002x\examples

For users new to C2000's F28002x series of devices and CCS, TI's [C2000 Academy](#) provides several easy-to-follow training modules and hands-on lab exercises to help users get started quickly.

5 Special Notes

5.1 XDS100v2 Emulator and SCI (UART) Connectivity

The F280025C controlCARD provides emulation and USB-to-UART adapter functionality on the controlCARD. This allows for a convenient method to debug and demonstrate the F280025C MCU.

Note that the FTDI chip, its support circuitry, and associated isolation components are placed in Macro A (the left section of the controlCARD). Each of these components contains an additional “:A” within the component reference designator (that is, R2:A for resistor 2 in Macro A) (see [Figure 6-2](#)).

The configuration of the switches on S1:A determine if the on-board emulator is active, if an external emulator can be used, or if the device will boot from FLASH/peripherals (see [Table 4-1](#)).

5.2 Clocking Methodology

This controlCARD is required to support a broad range of TI's baseboards. Several designs rely on GPIO18 and GPIO19 for SPIA, while others require these GPIO to be utilized as a precision clock input source. To accommodate both of these systems a switch (S3) has been added to the design. This methodology should not be used in a final system as it increases EMI emissions and creates robustness susceptibilities. It is up to the system designer to choose the best way to implement the clocking circuitry for a given system.

5.3 Evaluation of the Analog-to-Digital Converters (ADCs)

When using the F280025C on-chip ADCs there are some useful guideline to follow to realize the performance numbers listed in the data sheet. This is especially true for the AC parameters such as: SNR, THD, and SINAD. Furthermore, it can also be shown that there is a direct correlation between the SNR of the ADC result and the spread of ADC codes seen for a DC input; as such these tips will improve the range and standard deviation of a DC input as well. Finally, while topics addressed will be with respect to the controlCARD, they are applicable to other implementations using the F280025C MCU as well.

On-board resistors and capacitors: By default all inline resistors to the ADC pins are a simple 0-Ω shunt and all capacitors to the ground plane are not populated. While this circuit can be used to supply the ADC inputs with a voltage, likely both the resistor(R) and capacitor(C) will need to be populated based on the voltage source's characteristics. Referring to the ADC Input Model in the [TMS320F28002x Real-Time Microcontrollers](#) data sheet, the ADC input has its own RC network made up of the internal sample and hold capacitor, switch resistance, and parasitic capacitance. By changing the inline resistance and parallel capacitor we can optimize the input circuit to assist with settling time and/or filtering the input signal. Finally, it is recommended in general to use Negative-Positive 0 PPM/°C (NP0/C0G) capacitors as these have better stability over temperature and across input frequencies than other types of capacitors.

Voltage source and drive circuitry: While the on-chip ADCs are 12-bit architecture (4096 distinct output codes when converting an analog signal to the digital domain); the translation will only be as precise as the input provided to the ADC. The typical rule of thumb when defining the source resolution to realize the full specification of an ADC is to have a 1-bit better source than the converter. In this case that would mean that ideally the analog input should be accurate to 13-bits.

Typically voltage supplies or regulators are not designed to be precise, but rather accommodate a wide range of current loads within a certain tolerance and for this reason are not ideal to show the performance of a higher bit ADC, like the one on the F280025C. This does also not take into account that many times the supply in question is providing the main voltage to power the MCU itself; which also introduces noise and other artifacts into the signal.

In addition to the quality of the input signal there is also the aspect of the load presented to the ADC when it samples the input. Ideally an input to an ADC would have zero impedance so as not to impact the internal R/C network when the sampling event takes place. In many applications, however, the voltages that are sampled by the ADC are derived from a series of resistor networks, often large in value to decrease the active current consumption of the system. A solution to isolate the source impedance from the ADC sampling network is to place an operational amplifier in the signal path. Not only does this isolate the impedance of the signal from the ADC, it also shields the source itself from any effects the sampling network may have on the system.

Recommended source for evaluation: The [Precision Signal Injector \(PSI\) EVM](#) from TI was used to validate the ADC performance on the F280025C ControlCARD. This EVM supports both single ended as well as

differential ended outputs using a [16-bit DAC](#) as the signal source then passed through a [high precision op-amp](#) with post amplifier filtering. The EVM is powered and controlled through a standard USB connection from a host PC and includes a GUI to control its output. The outputs are routed through single or dual SMA type connectors; it is highly recommended to place an additional female SMA connector ([Figure 5-1](#)) on the controlCARD docking station to receive the signal via SMA for best noise immunity. For the local RC network 30- Ω resistors and 300pF capacitors were used. Using this setup the ADC parameters were observed to be consistent with the numbers in the data sheet.



Figure 5-1. Female SMA Connector

6 Hardware References

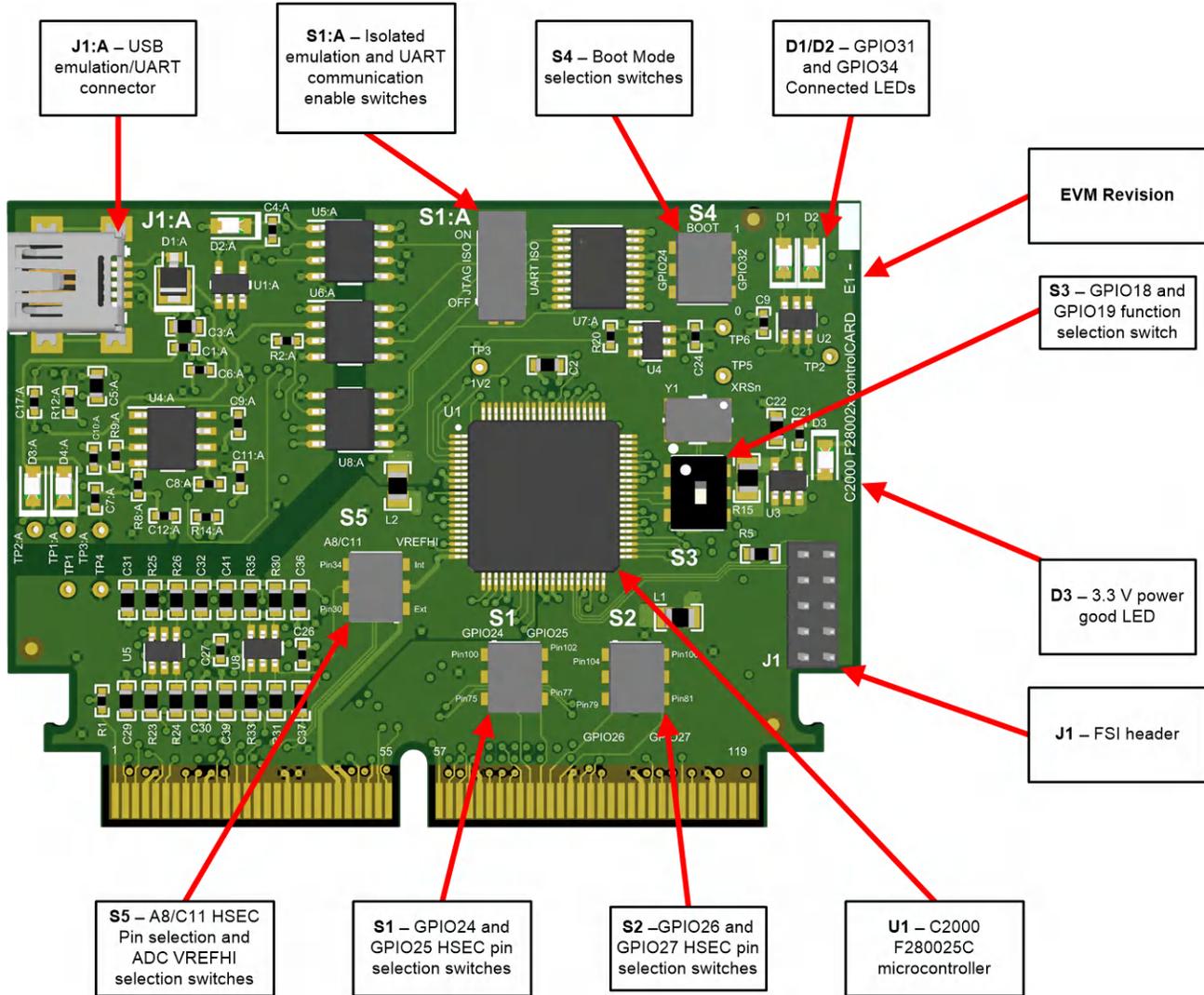


Figure 6-1. Key Components on the controlCARD - Front

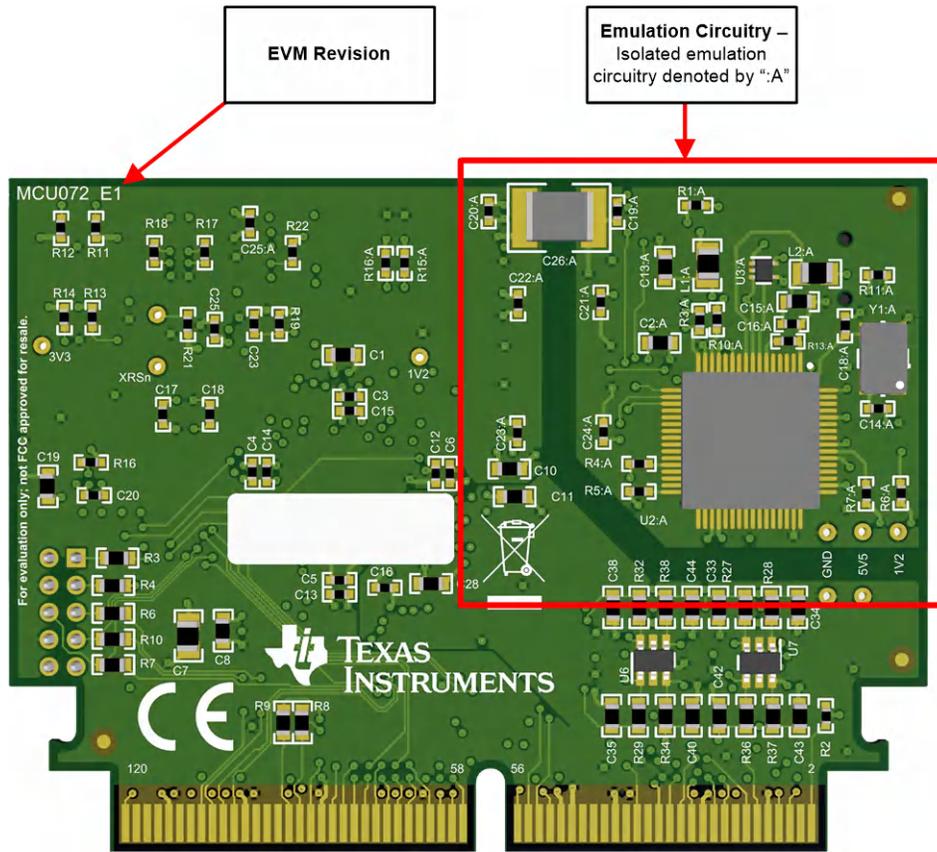


Figure 6-2. Key Components on the controlCARD - Back

WARNING

When the controlCARD is used in a high-voltage setup, it is the user’s responsibility to confirm that the voltages and isolation requirements are identified and understood prior to energizing the board or simulation. When energized, the controlCARD or components connected to the controlCARD should not be touched. Furthermore, the capacitor C26:A should be removed to minimize the possibility of leakage current flowing across the isolation barrier of the controlCARD.

Table 6-1. Hardware Connections

Connectors	
J1:A	Emulation/UART connector - USB mini A connector used to provide XDS100v2 emulation and USB-to-UART (SCI) communication through FTDI logic. S1:A determines which connections are enabled to the MCU.
J1	FSI Header – Updated over previous designs. This header is now keyed, contains 2 data lines, and has 3.3 V power.
LEDs	
D2:A	Turns on when ISO JTAG logic is powered on (green)
D3:A	JTAG/UART RX toggle indicator (blue)
D4:A	JTAG/UART TX toggle indicator (blue)
D1	Controlled by GPIO–31 with negative logic (red)
D2	Controlled by GPIO–34 with negative logic (red)
D3	Turns on when the controlCARD is powered ON (green)

Resistors and Capacitors	
R23-R38	ADC RC input filter resistors: Series resistors which can be used to create an RC filter on the ADC's input.
C29-C44	ADC RC input filter capacitors: Optional capacitors, not populated by default, for the ADC input's RC filters.

Switches	
S1:A	Isolated emulation and UART communication enable switches: S1:A Position 1 – JTAG Enable: <ul style="list-style-type: none"> ON – All signals between the XDS100v2 emulation logic and the MCU will be connected. This setting is valid when the MCU is being debugged or programmed via the on-card XDS100v2 emulator. OFF – The XDS100v2 emulation logic will NOT be connected to the MCU. This setting is valid when the device will boot from FLASH, boot from a peripheral directly, or when an external JTAG emulator will be used. S1:A Position 2 – ISO UART communication enable: <ul style="list-style-type: none"> ON – The C2000 MCU's GPIO-28 (and pin 76 of the 180-pin controlCARD connector) will be coupled to the FTDI's USB-to-Serial adapter. This allows UART communication to a computer via the FTDI chip. However, in this position, GPIO-28 will be forced high by the FTDI chip. Functionality of pin 76 of the connector will be limited. OFF – The C2000 MCU will NOT be connected to the FTDI USB-to-Serial adapter. Pin 76 of the 180-pin controlCARD connector will be directly connected to GPIO-28.
S1	QEP and SPIB selection switch: This switch allows GPIO24 and GPIO25 to be routed to one of two locations on the HSEC connector.
S2	QEP and SPIB selection switch: This switch allows GPIO26 and GPIO27 to be routed to one of two locations on the HSEC connector.
S3	SPIA or external crystal selection switch: This switch enables the use of SPIA or an external crystal. This methodology was required to support the full range of TI's baseboards and is not recommended in a production system. For full details, see Section 5.2 .
S4	Boot Mode Switch: Controls the Boot Options of the F280025C device, see Table 6-2 . For a full description, see the device-specific data sheet.
S5	Analog Configuration Switch: S4 Position 1 (left switch) – ADC channel A8/C11 HSEC pin selection <ul style="list-style-type: none"> Upward position – Channel A8/C11 goes to HSEC pin 34 Downward Position – Channel A8/C11 goes to HSEC pin 30 Position 2 (right switch) - ADC voltage reference selection. <ul style="list-style-type: none"> Upward position – Internal voltage reference Downward Position – External voltage reference Note that additional software configuration is required to enable the ADC's internal or external voltage reference.

Test Points	
TP1:A	Emulator 5.0 V input: This power domain is isolated from the other 5.0V domain.
TP2:A	Emulator 3.3 V input: This power domain is isolated from the other 3.3 V domains.
TP3:A	Emulator ground
TP1	HSEC 5.0 V input: 5.0 V input provided to the 3.3 V voltage regulator to create the unfiltered 3.3 V power.
TP2	Unfiltered 3.3 V: Provides power to the F280025C device.
TP3	MCU 1.2 V: VDD 'core supply' to the F280025C device. Note that this controlCARD has been designed to use the internal voltage regulator.
TP4	Device Ground
TP5	XRSn of F280025C device: Connected to the undervoltage output from the 3.3 V voltage supervisor.
TP6	Overvoltage output: Connected to the overvoltage output from the 3.3 V voltage supervisor.

Note

On the front of the controlCARD test points are indicated by their TPx number.

On the back of the controlCARD test points are indicated by their signal.

Table 6-2. S4, Bootmode Selection Table

Mode	Switch Position 1 (left switch, GPIO-24)	Switch Position 2 (right switch, GPIO-32)	Boot From
00	0 (down)	0 (down)	Parallel I/O
01	1 (up)	0 (down)	SCI/Wait Boot
02	0 (down)	1 (up)	CAN
03	1 (up)	1 (up)	Flash/USB

7 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision A (March 2020) to Revision B (June 2022)	Page
• Changed document title from <i>F280025 controlCARD Information Guide</i> to <i>TMS320F280025C controlCARD Information Guide</i>	1
• Global: Changed "F280025 controlCARD" to "F280025C controlCARD".....	1
• Global: Changed "F280025 MCU" and "F28002x MCU" to "F280025C MCU". Changed "F280025 microcontroller" to "F280025C microcontroller".....	1
• Section 1 (Introduction): Updated section.....	2
• Section 2 (Hardware Quick Setup Guide): Added WARNING about using controlCARD in a high-voltage setup. Updated section.....	3
• Section 3.1 (Warnings, Notes, and Errata): Changed "F280025 Experimenter's Kit" to "F280025C Experimenter's Kit".....	4
• Section 4.3 (Using the controlCARD): Added WARNING about using controlCARD in a high-voltage setup. Updated section.....	5
• Section 4.4 (Experimentation Software): Updated section.....	6
• Section 5.3 (Evaluation of the Analog-to-Digital Converters (ADCs)): Updated section.....	7
• Section 6 (Hardware References): Added WARNING about using controlCARD in a high-voltage setup.....	9

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NOTE:

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3.1.1 Notice applicable to EVMs not FCC-Approved:

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3.1.2 For EVMs annotated as FCC – FEDERAL COMMUNICATIONS COMMISSION Part 15 Compliant:

CAUTION

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

FCC Interference Statement for Class A EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

FCC Interference Statement for Class B EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210 or RSS-247

Concerning EVMs Including Radio Transmitters:

This device complies with Industry Canada license-exempt RSSs. Operation is subject to the following two conditions:

(1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Concerning EVMs Including Detachable Antennas:

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.

3.3 Japan

3.3.1 *Notice for EVMs delivered in Japan:* Please see http://www.tij.co.jp/lstds/ti_ja/general/eStore/notice_01.page 日本国内に輸入される評価用キット、ボードについては、次のところをご覧ください。
http://www.tij.co.jp/lstds/ti_ja/general/eStore/notice_01.page

3.3.2 *Notice for Users of EVMs Considered "Radio Frequency Products" in Japan:* EVMs entering Japan may not be certified by TI as conforming to Technical Regulations of Radio Law of Japan.

If User uses EVMs in Japan, not certified to Technical Regulations of Radio Law of Japan, User is required to follow the instructions set forth by Radio Law of Japan, which includes, but is not limited to, the instructions below with respect to EVMs (which for the avoidance of doubt are stated strictly for convenience and should be verified by User):

1. Use EVMs in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

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1. 電波法施行規則第6条第1項第1号に基づく平成18年3月28日総務省告示第173号で定められた電波暗室等の試験設備でご使用いただく。
2. 実験局の免許を取得後ご使用いただく。
3. 技術基準適合証明を取得後ご使用いただく。

なお、本製品は、上記の「ご使用にあたっての注意」を譲渡先、移転先に通知しない限り、譲渡、移転できないものとします。

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東京都新宿区西新宿 6 丁目 2 4 番 1 号
西新宿三井ビル

3.3.3 *Notice for EVMs for Power Line Communication:* Please see http://www.tij.co.jp/lstds/ti_ja/general/eStore/notice_02.page
電力線搬送波通信についての開発キットをお使いになる際の注意事項については、次のところをご覧ください。http://www.tij.co.jp/lstds/ti_ja/general/eStore/notice_02.page

3.4 European Union

3.4.1 *For EVMs subject to EU Directive 2014/30/EU (Electromagnetic Compatibility Directive):*

This is a class A product intended for use in environments other than domestic environments that are connected to a low-voltage power-supply network that supplies buildings used for domestic purposes. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

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- 4 *EVM Use Restrictions and Warnings:*
 - 4.1 EVMS ARE NOT FOR USE IN FUNCTIONAL SAFETY AND/OR SAFETY CRITICAL EVALUATIONS, INCLUDING BUT NOT LIMITED TO EVALUATIONS OF LIFE SUPPORT APPLICATIONS.
 - 4.2 User must read and apply the user guide and other available documentation provided by TI regarding the EVM prior to handling or using the EVM, including without limitation any warning or restriction notices. The notices contain important safety information related to, for example, temperatures and voltages.
 - 4.3 *Safety-Related Warnings and Restrictions:*
 - 4.3.1 User shall operate the EVM within TI's recommended specifications and environmental considerations stated in the user guide, other available documentation provided by TI, and any other applicable requirements and employ reasonable and customary safeguards. Exceeding the specified performance ratings and specifications (including but not limited to input and output voltage, current, power, and environmental ranges) for the EVM may cause personal injury or death, or property damage. If there are questions concerning performance ratings and specifications, User should contact a TI field representative prior to connecting interface electronics including input power and intended loads. Any loads applied outside of the specified output range may also result in unintended and/or inaccurate operation and/or possible permanent damage to the EVM and/or interface electronics. Please consult the EVM user guide prior to connecting any load to the EVM output. If there is uncertainty as to the load specification, please contact a TI field representative. During normal operation, even with the inputs and outputs kept within the specified allowable ranges, some circuit components may have elevated case temperatures. These components include but are not limited to linear regulators, switching transistors, pass transistors, current sense resistors, and heat sinks, which can be identified using the information in the associated documentation. When working with the EVM, please be aware that the EVM may become very warm.
 - 4.3.2 EVMs are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems. User assumes all responsibility and liability for proper and safe handling and use of the EVM by User or its employees, affiliates, contractors or designees. User assumes all responsibility and liability to ensure that any interfaces (electronic and/or mechanical) between the EVM and any human body are designed with suitable isolation and means to safely limit accessible leakage currents to minimize the risk of electrical shock hazard. User assumes all responsibility and liability for any improper or unsafe handling or use of the EVM by User or its employees, affiliates, contractors or designees.
 - 4.4 User assumes all responsibility and liability to determine whether the EVM is subject to any applicable international, federal, state, or local laws and regulations related to User's handling and use of the EVM and, if applicable, User assumes all responsibility and liability for compliance in all respects with such laws and regulations. User assumes all responsibility and liability for proper disposal and recycling of the EVM consistent with all applicable international, federal, state, and local requirements.
 5. *Accuracy of Information:* To the extent TI provides information on the availability and function of EVMs, TI attempts to be as accurate as possible. However, TI does not warrant the accuracy of EVM descriptions, EVM availability or other information on its websites as accurate, complete, reliable, current, or error-free.
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 - 6.1 EXCEPT AS SET FORTH ABOVE, EVMS AND ANY MATERIALS PROVIDED WITH THE EVM (INCLUDING, BUT NOT LIMITED TO, REFERENCE DESIGNS AND THE DESIGN OF THE EVM ITSELF) ARE PROVIDED "AS IS" AND "WITH ALL FAULTS." TI DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED, REGARDING SUCH ITEMS, INCLUDING BUT NOT LIMITED TO ANY EPIDEMIC FAILURE WARRANTY OR IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF ANY THIRD PARTY PATENTS, COPYRIGHTS, TRADE SECRETS OR OTHER INTELLECTUAL PROPERTY RIGHTS.
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8.1 *General Limitations.* IN NO EVENT SHALL TI BE LIABLE FOR ANY SPECIAL, COLLATERAL, INDIRECT, PUNITIVE, INCIDENTAL, CONSEQUENTIAL, OR EXEMPLARY DAMAGES IN CONNECTION WITH OR ARISING OUT OF THESE TERMS OR THE USE OF THE EVMS , REGARDLESS OF WHETHER TI HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. EXCLUDED DAMAGES INCLUDE, BUT ARE NOT LIMITED TO, COST OF REMOVAL OR REINSTALLATION, ANCILLARY COSTS TO THE PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES, RETESTING, OUTSIDE COMPUTER TIME, LABOR COSTS, LOSS OF GOODWILL, LOSS OF PROFITS, LOSS OF SAVINGS, LOSS OF USE, LOSS OF DATA, OR BUSINESS INTERRUPTION. NO CLAIM, SUIT OR ACTION SHALL BE BROUGHT AGAINST TI MORE THAN TWELVE (12) MONTHS AFTER THE EVENT THAT GAVE RISE TO THE CAUSE OF ACTION HAS OCCURRED.

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