

Enhancing Accuracy and Narrow Pulse Detection in Automotive and Industrial LiDAR with LVDS Comparators

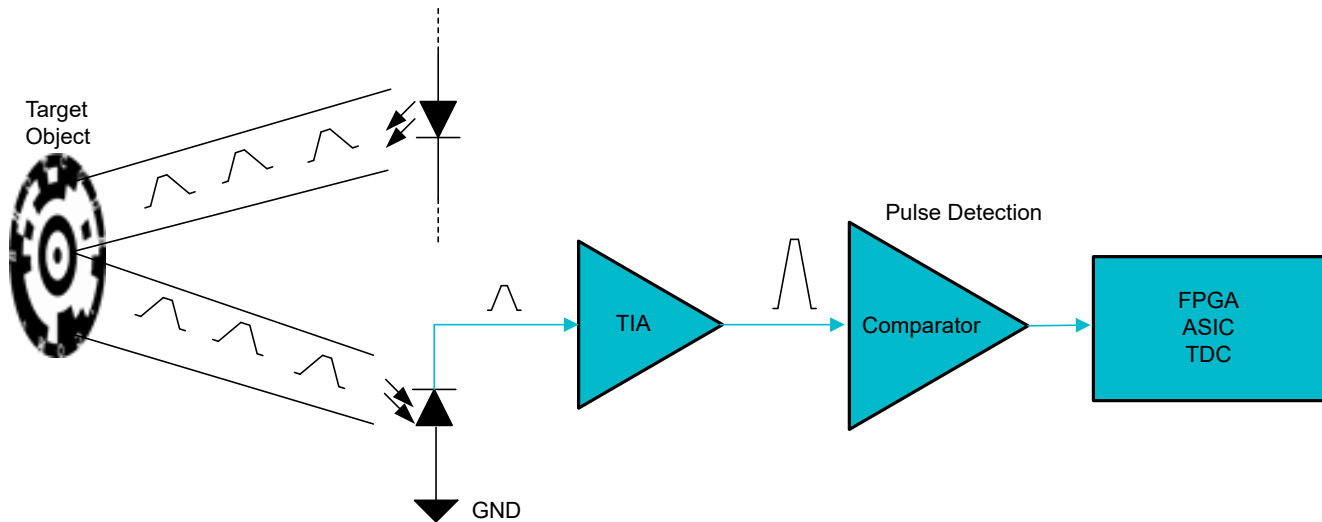


Figure 1. Concept Diagram for Time-of-Flight Pulse Detection with Comparator

See more about this use case in [How to design with high speed comparators in automotive and industrial systems](#) and our [Intro to high speed comparators: ToF distance measurements with LVDS comparator](#) videos.

Design Challenges

- Depending on the reflectivity or distance of an object, the received pulse amplitude can be reduced.
- To maintain consistent propagation delay regardless of pulse amplitude.
- Measuring distances from far away objects requires higher amplitudes and narrower pulses to maintain power, as described in [When to Use High-Speed Comparators or ADCs for Distance Measurements in Optical Time-of-Flight Systems](#).

How High Speed Comparators Benefit the System

- Low overdrive dispersion contributes to consistent measurements by reducing pulse amplitude sensitivity.
- Super-fast propagation delay enables time sensitive measurements to occur.
- Narrow pulse width detection capability makes possible detecting objects at farther distances.
- LVDS and single-ended comparator output options are available depending on downstream device requirements.

Part Number	Output Type	Min. Pulse Width	t_{PD}	$t_{OD_DISPERSION}$	Supply Range (V)
TLV3801/11 , TLV3801-Q1	LVDS	240ps	225ps	5ps	2.7 to 5.25
TLV3601/2/3 , TLV3601/2/3-Q1	Push-Pull	1.25ns	2.5ns	600ps	2.4 to 5.5
TLV3604 , TLV3605	LVDS	600ps	800ps	350ps	2.4 to 5.5
TLV3901 (Preliminary)	CML	80ps	150ps	5ps	3.1 to 5.5

If you have more questions please ask them on [TI's E2E forum](#).

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