

DRV8000-Q1 Evaluation Module



Description

The DRV8000-Q1 evaluation module (EVM) allows for easy evaluation of the DRV8000-Q1 device. The EVM has been programmed and configured to work out of the box and begin driving loads right away. The EVMs showcase an integrated driver with a H-bridge gate driver, six integrated half-bridges, six integrated high-side drivers, one external high-side gate driver for heater, one external high-side gate driver for electrochromic charge and one integrated low-side driver for electrochromic load discharge. The device features protection features such as under and over voltage monitors, offline open load and short circuit diagnostics, and zone-based thermal monitoring and shutdown protection. The device also has a muxable sense output (IPROPI) and integrate current regulation (ITRIP). The EVM is accompanied by a GUI application for easy control of the motor driver.

Get Started

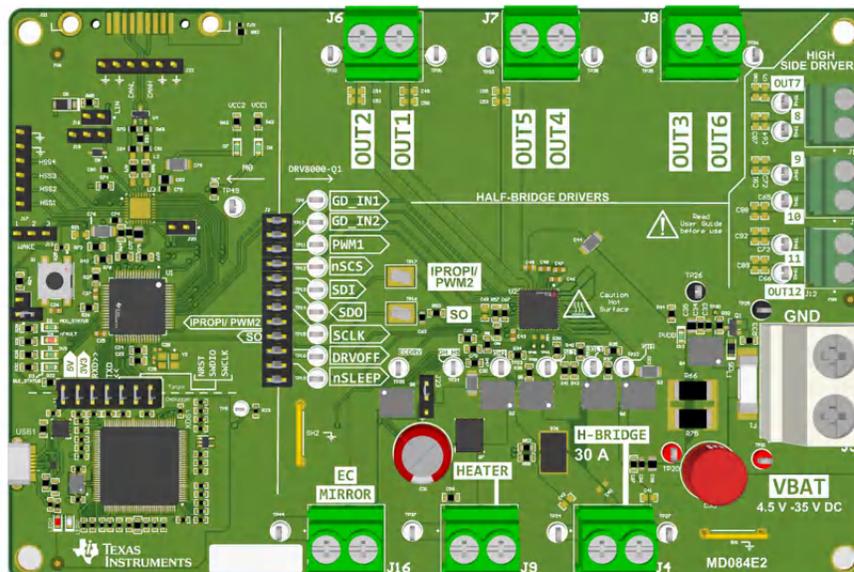
1. Order the EVM from tools page on ti.com ([DRV8000EVM](#))
2. Use the web-based GUI: <https://dev.ti.com/gallery/view/MotorDriversBSM/DRV800x-Q1/>
3. Connect USB and external power supply
4. Launch DRV800x-EVM-GUI and select the EVM variant on the home page

Features

- XDS110 USB-based on-board emulator for ease of programming and debugging MSPM0 microcontroller
- Main signal header with removable shunts to disconnect main signals going to the motor driver IC from the MCU
- GUI software to control EVM and DRV IC

Applications

- [Door module](#)
- [Body control modules](#)
- [Zonal module](#)



DRV8000-Q1EVM

1 Evaluation Module Overview

1.1 Introduction

The DRV8000-Q1 devices integrate multiple types of drivers intended for multiple functions: driving and diagnosing motor (inductive), resistive and capacitive loads. This document is provided with the DRV8000-Q1 evaluation modules (EVM) as a supplement to the DRV8000-Q1 data sheets. This user's guide covers EVM hardware setup instructions, GUI installation, and usage instructions.

1.2 Kit Contents

[Table 1-1](#) lists the contents of the EVM kit. Contact the nearest [Texas Instruments Product Information Center](#) if any component is missing.

Table 1-1. Kit Contents

| ITEM | QUANTITY |
|------------------------------------|----------|
| DRV8000-Q1EVM | 1 |
| 3ft White USB-A to Micro-USB Cable | 1 |

1.3 Specification

The DRV8000-Q1 EVM connects to a local computer USB port through a USB-A to Micro-USB cable. An onboard XDS110 USB emulator allows for programming and debugging the main MSPM0 microcontroller without the need for an external debugger. A 3.3V LDO generates a 3.3V rail from the USB 5V supply. This 3.3V is used to power the XDS110 MCU, main MSPM0, and motor driver DVDD pin. J2 signal header uses removable shunts to pass the signals from the MCU to the motor driver. Remove any of these shunts to easily jump in the control signals to the driver. Provide an external motor power supply to the J5 screw terminal within the operating range of the device. DRV8000-Q1 support supply voltage range 4.5V to 35V.

1.4 Device Information

The DRV8000-Q1 devices integrate multiple types of drivers intended for multiple functions: driving and diagnosing motor (inductive), resistive and capacitive loads. The device features two half-bridge gate drivers, 6 integrated half-bridges, 6 integrated highside drivers, one external high-side gate driver for heater, one external high-side gate driver for electrochromic charge and one integrated low-side driver for electrochromic load discharge.

The documents in [Table 1-2](#) provide information regarding Texas Instruments integrated circuits used in the assembly of the EVM. This user's guide is available from the TI web site under literature number SLVUCZ2. Any letter appended to the literature number corresponds to the document revision that is current at the time of the writing of this document. Newer revisions are available from the TI web site at www.ti.com, or call the Texas Instruments Literature Response Center at (800) 477-8924 or the Product Information Center at (972) 644-5580. When ordering, identify the document by both title and literature number

Table 1-2. Related Device Documentation

| Description | Data Sheet |
|----------------|-----------------------------|
| XDS110 MCU | MSP432E401Y |
| Main MSPM0 MCU | MSPM0G3507 |
| Motor Driver | DRV8000-Q1 |

2 Hardware

2.1 Headers and Test Points Information

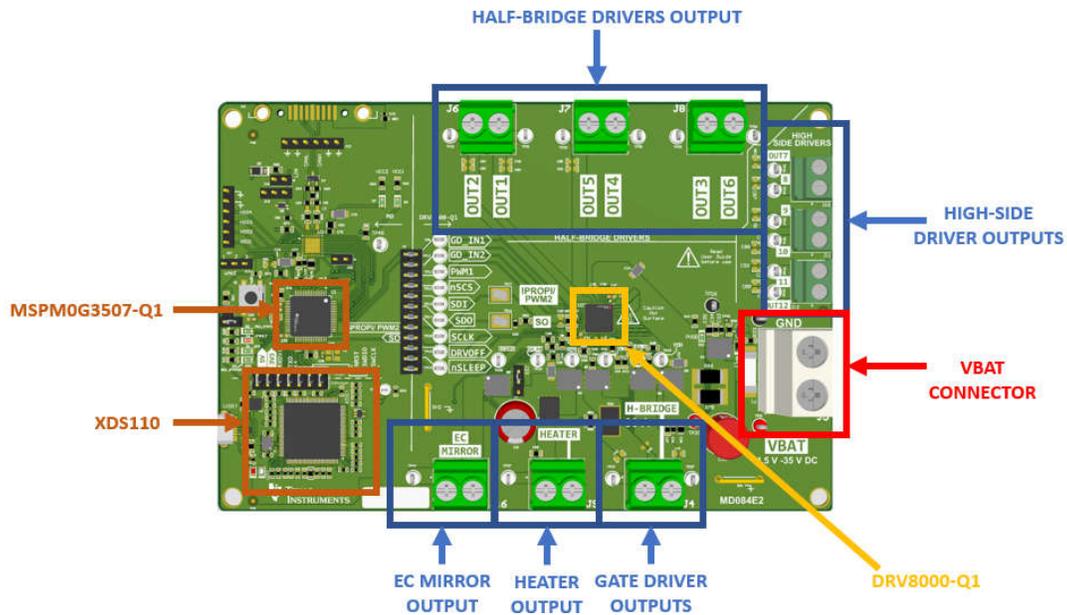


Figure 2-1. DRV8000-Q1EVM (MD084-001) (Top View)

CAUTION

Hot surface temperature. The EVM can have high surface temperatures marked by the FIRE triangular symbol on the EVM. Avoid touching the marked hot surface area when driving high currents to prevent potential burn damage.

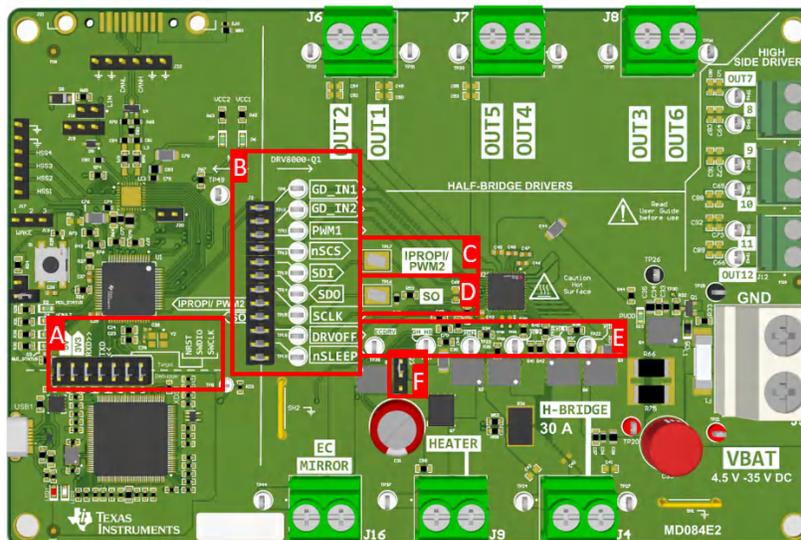


Figure 2-2. DRV8000-Q1EVM Header and Test Point Information

Table 2-1. Header and Test Point Description - DRV8000-Q1EVM

| Component label | Description |
|-----------------|--|
| Aee | XDS110 header between MSP432E401Y and MSPM0G3507 . |
| B | <p>Main signal header:</p> <ul style="list-style-type: none"> • GD_IN1: Half-bridge and H-bridge control input 1. • GD_IN2: Half-bridge and H-bridge control input 2. • PWM1: PWM input 1 for regulation of all drivers except electrochrome. • nSCS: Serial chip select. A logic low on this pin enables serial interface communication. Internal pullup resistor. • SDI: Serial data input. Data is captured on the falling edge of the SCLK pin. Internal pulldown resistor. • SDO: Serial data output. Data is shifted out on the rising edge of the SCLK pin. Push-pull output. • SCLK: Serial clock input. Serial data is shifted out and captured on the corresponding rising and falling edge on this pin. • DRVOFF: Gate driver shutdown pin. Logic high to pull down both high-side and low-side gate driver outputs. Internal pull-down Resistor. • nSLEEP: Device enable pin. Logic low to shutdown the device and enter sleep mode. Internal pulldown resistor. |
| C | IPROPI/ PWM2 - Sense output is multiplexed from any of driver load current feedback, PVDD voltage feedback, or thermal cluster temperature feedback. Can also be configured as second PWM pin input for half-bridge drivers. |
| D | SO - Shunt amplifier output. |
| E | <p>Gate Driver, EC Driver, Heater Test points (Left to Right):</p> <ul style="list-style-type: none"> • ECDRV - For EC control, pin controls the gate of external MOSFET for EC voltage regulation • GH_HS - Gate driver output for heater MOSFET. Connected to gate of high-side MOSFET • GH2 - High-side gate driver output. Connected to the gate of the high-side MOSFET. • GL2 - Low-side gate driver output. Connected to the gate of the low-side MOSFET • GL1 - Low-side gate driver output. Connected to the gate of the low-side MOSFET • GH1 - High-side gate driver output. Connect to the gate of the high-side MOSFET |
| F | <p>Drain of external EC voltage regulation FET (Top to Bottom):</p> <ul style="list-style-type: none"> • OUT11 - If jumper is set between OUT11 and EC FET Drain then OUT11 is the drain of the EC FET • EC FET Drain • PVDD - If jumper is set between PVDD and EC FET Drain, then PVDD is the drain of the EC FET |

2.2 Connector Information

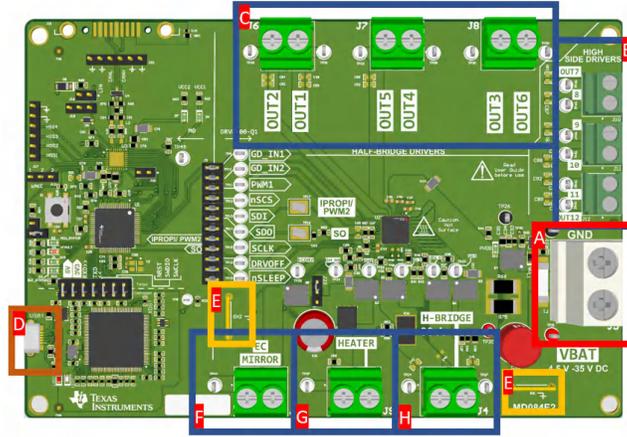


Figure 2-3. Connectors

Table 2-2. Connectors Description

| Component Label | Description |
|-----------------|--|
| A | Input power supply connector. Power cables can be directly connected to the screw terminals or clipped to the test points on either side of the connector. |
| B | High-side driver output connectors |
| C | Half-bridge output connectors |
| D | USB connector |
| E | Ground strap can be used as ground for probes and other connectors. |
| F | EC mirror output and ground. Ground located on the right side of terminal block. |
| G | Heater output and ground. Ground located on the right side of terminal block. |
| H | H-Bridge outputs. SH1 and SH2 are right side and left side of the terminal blocks respectively. |

2.3 Indicator LEDs

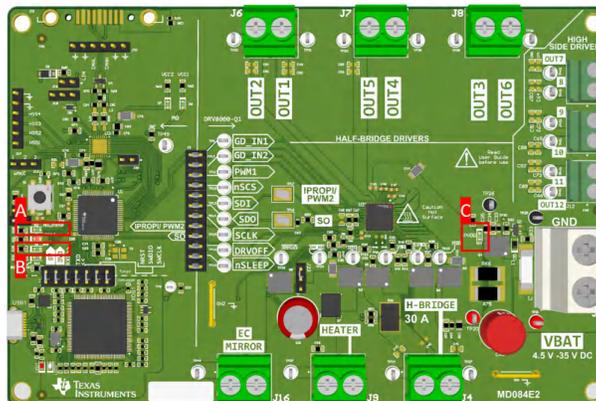


Figure 2-4. LED Indicators

| LED | Function |
|--------|--|
| A/D2 | MCU_STATUS: LED toggles at a rate of around 1s when MCU is active. Unplug and reconnect the EVM to the computer if this stops flashing. |
| B/ D1 | 3V3: OFF when 3.3V is not active. ON when 3.3V is active |
| C/ D10 | PVDD: OFF when PVDD is not provided. ON when PVDD is provided |

2.4 Hardware Setup

The EVM hardware is designed and kitted to simplify setup and begin spinning motors. The EVM comes with the jumpers placed at the appropriate location in the headers. The location of the jumpers, also called shunts, are shown in [Figure 2-1](#).

Note

Before using the EVM, check that the shunt location matches the location shown in [Figure 2-1](#).

Before connecting the EVM to the GUI software, follow these steps:

1. Make sure all the jumpers are populated on J1 and J2 if using the GUI with the EVM controller. If users are not using the GUI and TI firmware, then users can remove all the jumpers from J2 except the bottom most jumper DVDD. Users can remove the DVDD jumper if the DVDD voltage is supplied externally and not from the onboard MCU.
2. If using the EC driver, then make sure J23 is set to the desired position.
3. Connect the micro-USB cable to micro-USB receptacle in the **XDS110 section**. LED2 illuminates.
4. Provide VBAT voltage through VBAT connector.
5. Set up is now complete. See [Figure 2-5](#) for setup image.

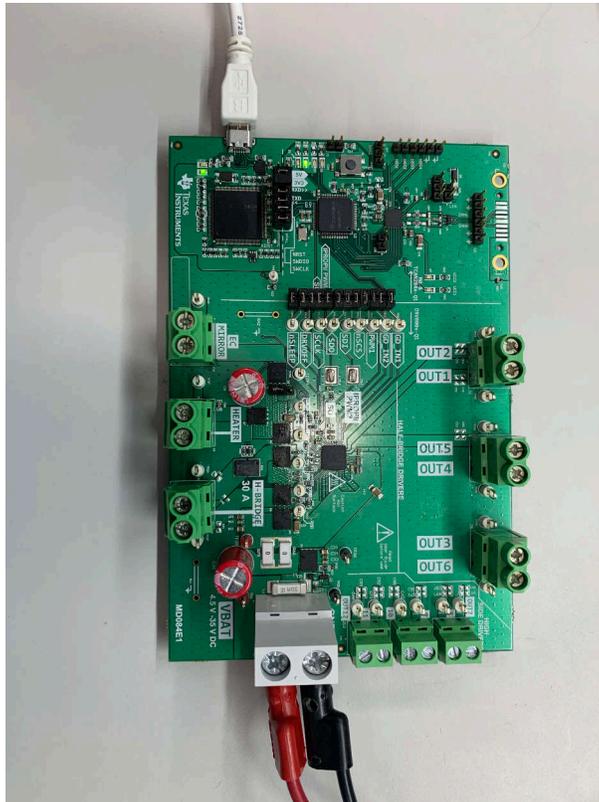


Figure 2-5. Hardware Setup

3 Software

3.1 Web GUI Access or Local GUI Installation

The EVM is controlled via a GUI application and can be used via a chrome-based browser or installed locally to a PC. Download the latest GUI installer [here](#) or use web-based GUI [here](#).

To use the Web GUI (recommended), follow these steps:

1. Open the latest version of the GUI at this link: <https://dev.ti.com/gallery/view/MotorDriversBSM/DRV800x-Q1/>
 - a. Alternatively, log into <https://dev.ti.com/gallery/> and search for *DRV800x* sorting by *Recently updated*.
 - b. Click on the title or blank space of the first search result to open the Web-Based GUI.



Figure 3-1. TI GUI Composer Gallery Results for Launching or Downloading Local Installer

To install the GUI locally follow these steps:

1. Log in to <https://dev.ti.com/gallery/> using myTI log in credentials. Note that the GUI composer log in searches for a very specific username match including case input at the time of sign up.
2. Open the latest version of the GUI at this link: <https://dev.ti.com/gallery/view/MotorDriversBSM/DRV800x-Q1/>
 - a. Alternatively, search for *DRV800x* sorting by *Recently updated*.
3. Hover the mouse over the *Download* icon and select the installer for the relevant operating system from the top list. Refer back to the previous section for a visual depiction of the gallery page.
4. Extract the ZIP folder with the installer and run the installer. The installer contents is self-explanatory and look slightly different for each OS.
5. Click *Next* and then agree to the terms and conditions on the following page.
6. Keep the application and runtime directory to the default locations. Click *Next* to install GUI.
7. Select *Download from Web* to download the GUI Composer Runtime if prompted, then click *Next*.
 - a. If a network firewall prevents Runtime download from the web, then the Runtime installer can be downloaded [here](#).
8. Check the box to create a desktop shortcut and click *Finish* to complete installation.
9. GUI is now installed.

3.2 Connecting EVM to GUI

Now that the EVM hardware setup and GUI installation is complete, the EVM can now be connected to the GUI. The following steps outline how to connect the EVM to GUI:

1. With the EVM connected to the PC, open the GUI. The home page is shown in [Figure 3-2](#).

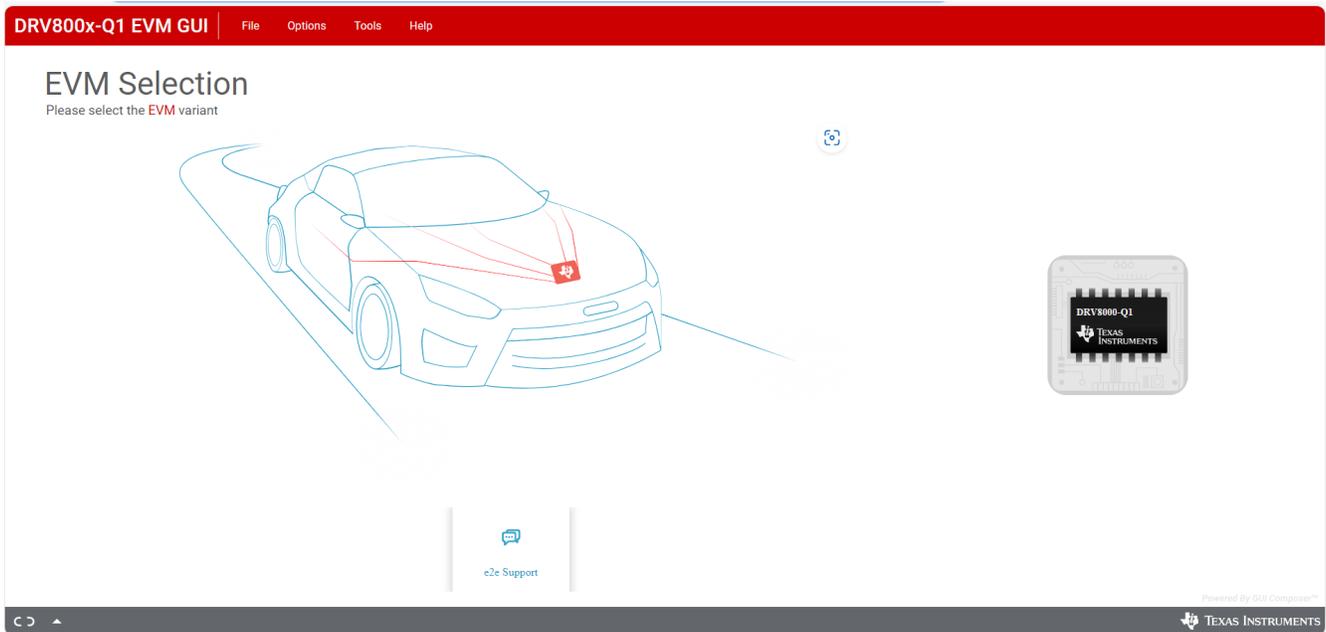


Figure 3-2. GUI Landing Page

2. Program EVM with latest software by clicking on *File -> Program Device*. (See [Figure 3-3](#)).

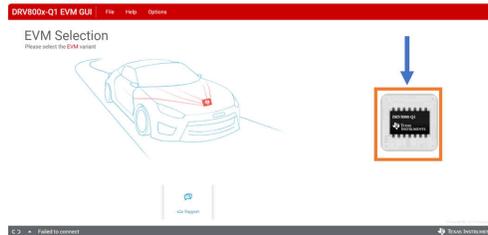
This needs to be done the first time the user sets up the EVM, as a software update can have been released since the EVM was initially programmed.



a.

Figure 3-3. Program Device

3. Select the appropriate GUI variant from the five options for the EVM ([Figure 3-3](#)).



a.

Figure 3-4. Select EVM Variant

4. The GUI attempts to connect with EVM. The GUI displays the following once successfully connected. If there is no successful connection, then double check hardware setup is correct following steps in [Section 2.4](#).



a.

Figure 3-5. Successful GUI connection

5. The GUI setup is now complete. The following section provides an overview of the GUI and how to use the GUI to control EVM.

3.3 GUI Overview

These following sections provides an overview for DRV8000-Q1EVM GUI.

3.4 DRV8000-Q1EVM

The DRV8000-Q1EVM GUIs has five main pages: *Half Bridge Controls*, *High Side Driver Controls*, *EC and Heater Controls*, *Gate Driver Controls* and *Register Map*. Each controls page gives the important register settings and hardware control to configure the respective peripheral. Each page does not offer all the controls for the peripheral; for full control, the *Register Map* page is recommended after setting basic configurations in the controls page. There is also a *I²C & Diagnostics* panel that can be expanded from any GUI screen.

Access the I²C & Diagnostics pane at any time by clicking the blue control on the right side of the screen. [Figure 3-6](#) below shows the pane opened.

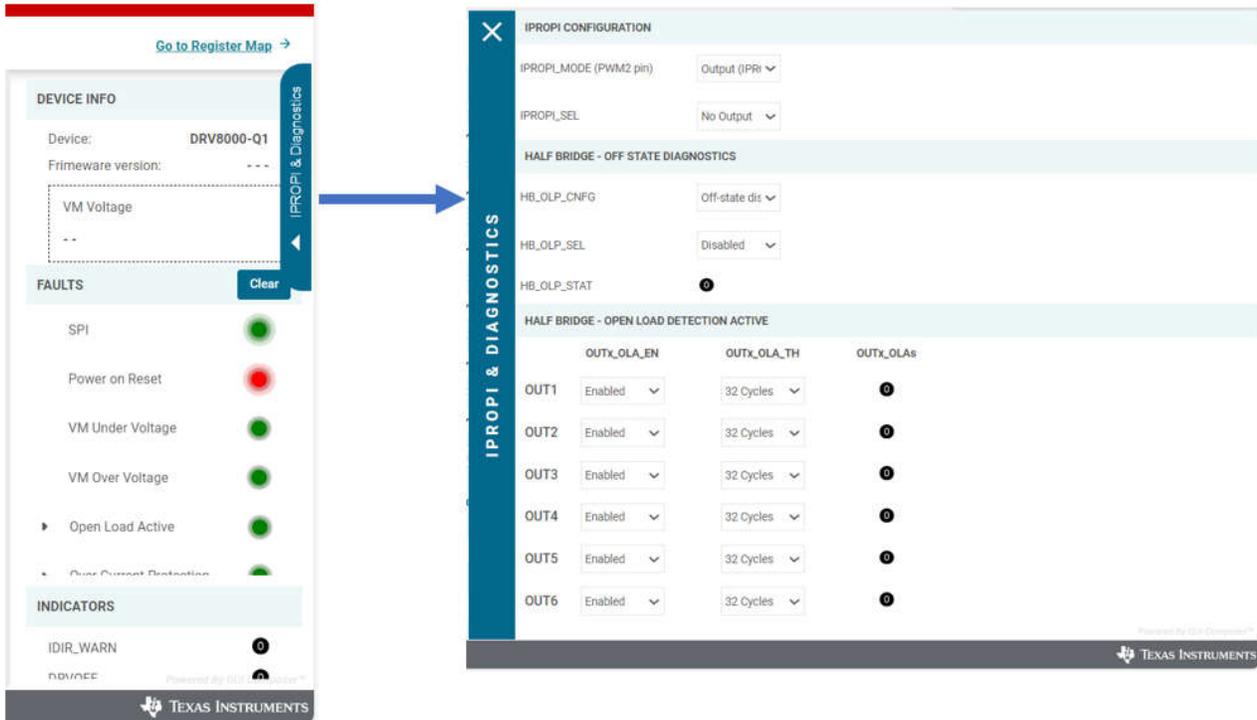


Figure 3-6. Driver Control Panel

3.4.1 Register Map

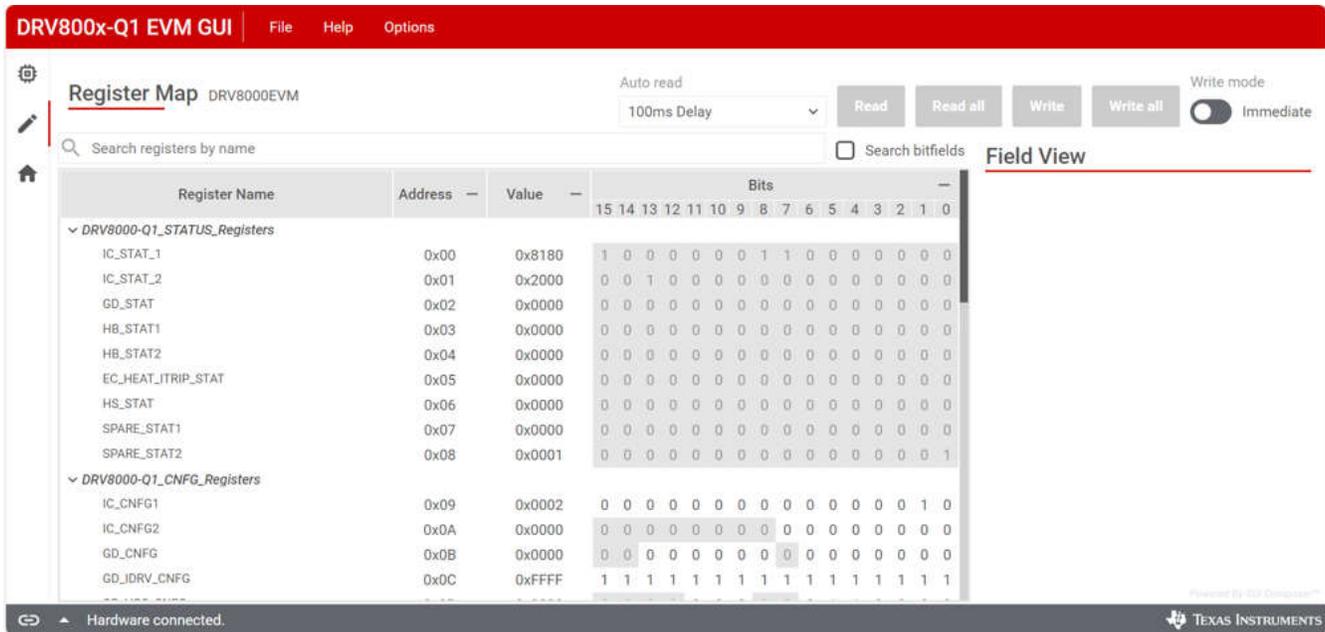


Figure 3-7. Register Map Page

The register map page is shown in Figure 3-7. The register names, address, and values are on the left hand side. The right hand side is the Field View, which provides more information regarding the bit fields of each register. The Auto Read widget sets how often the GUI reads back the register from the motor driver. The fastest option *Fast* is 500ms and the delay can be increase up to 1 minute. Setting Auto Read *Off* allows manual reading of either all registers at once or individually.

Saving and Loading Register Configurations

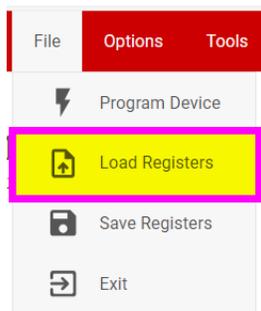


Figure 3-8. Load and Save Registers

The GUI has a built-in feature to save the current register configurations as a .json file which loads to the GUI. The following steps outline the procedure for saving and loading register configurations.

1. After writing the desired register values or using the GUI to configure the device, click on the *File* tab and click *Save Registers*. A save file pop-up window appears so the user can name and save the .json file.
2. To recall the register configurations, click on the *File* tab and then the click *Load Registers*. Select the saved .json file to load the register values.

4 Hardware Design Files

4.1 Schematics

Figure 4-1 shows the schematics for DRV8000-Q1EVM.

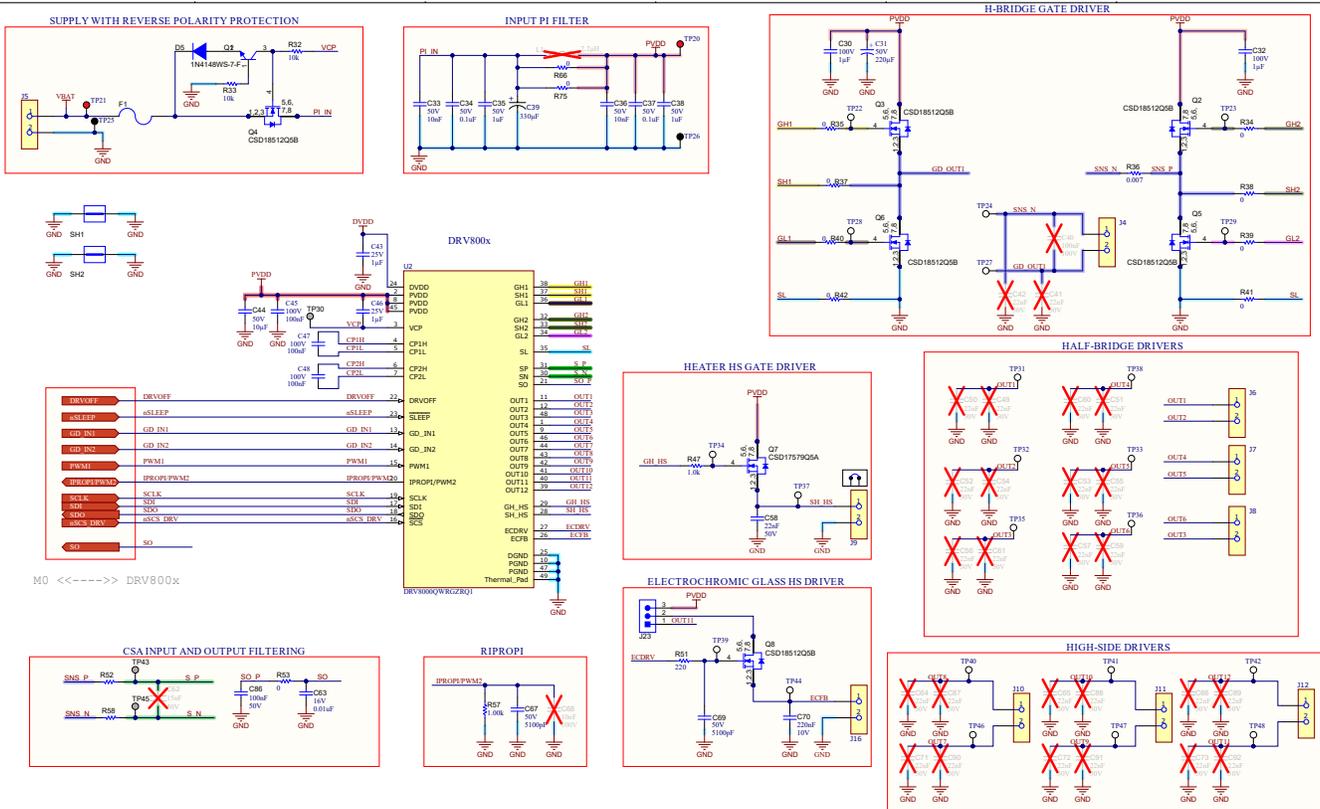


Figure 4-1. Motor Driver DRV8000-Q1

4.2 PCB Layout

Figure 4-3 through Figure 4-6 show the PCB layers of the EVM. The Altium source files can be downloaded in the aforementioned *Hardware Design Files* for a given EVM.

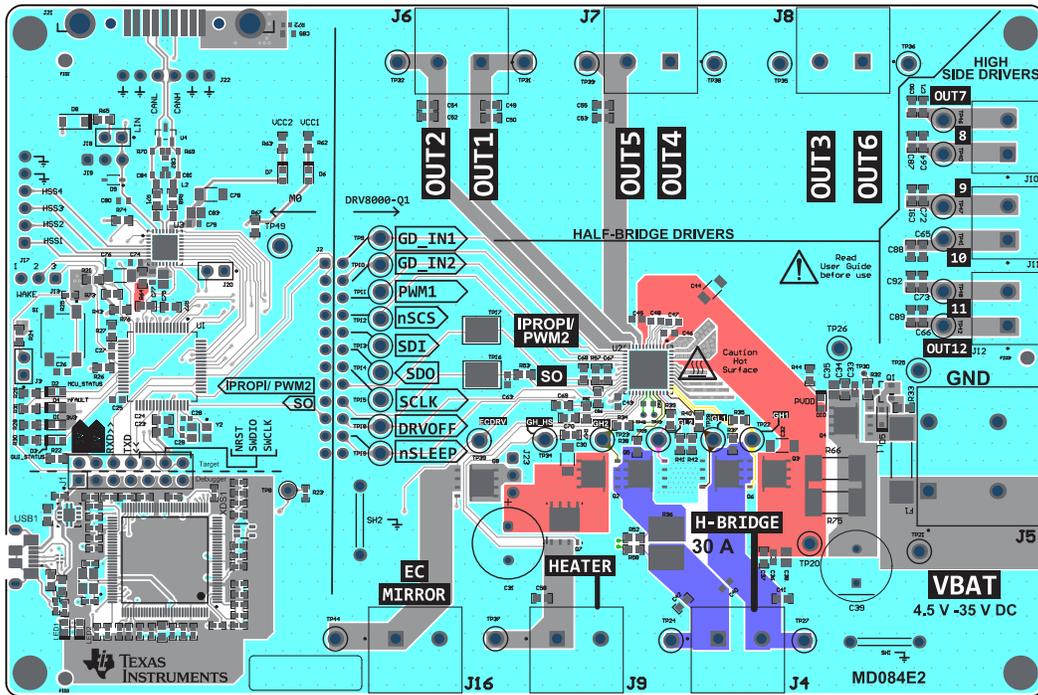


Figure 4-3. Top View

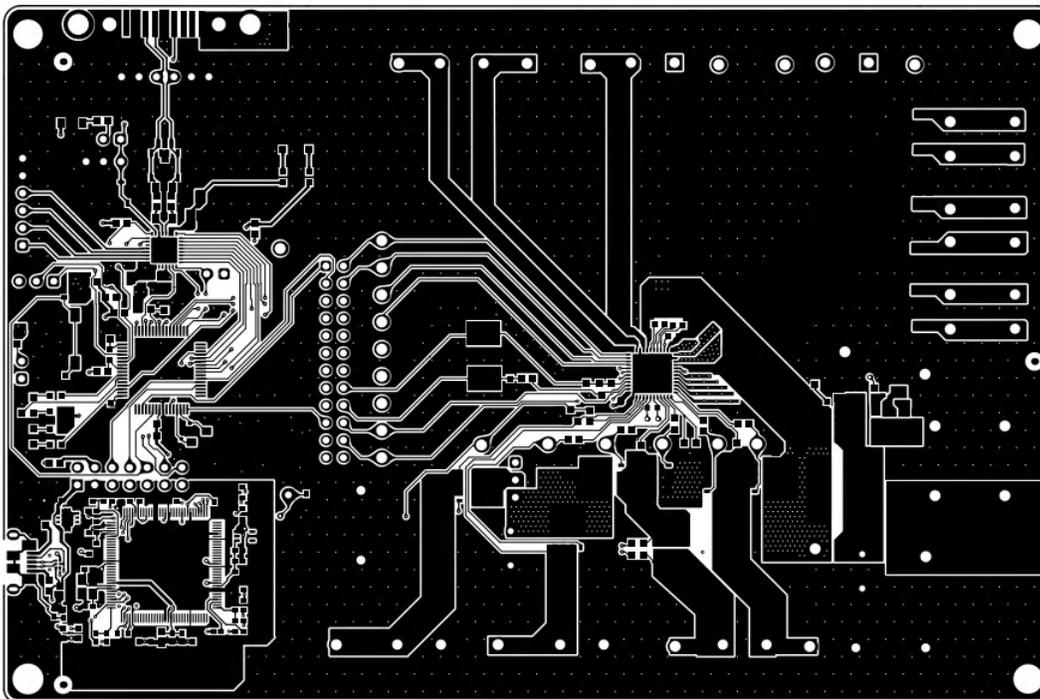


Figure 4-4. Top Layer

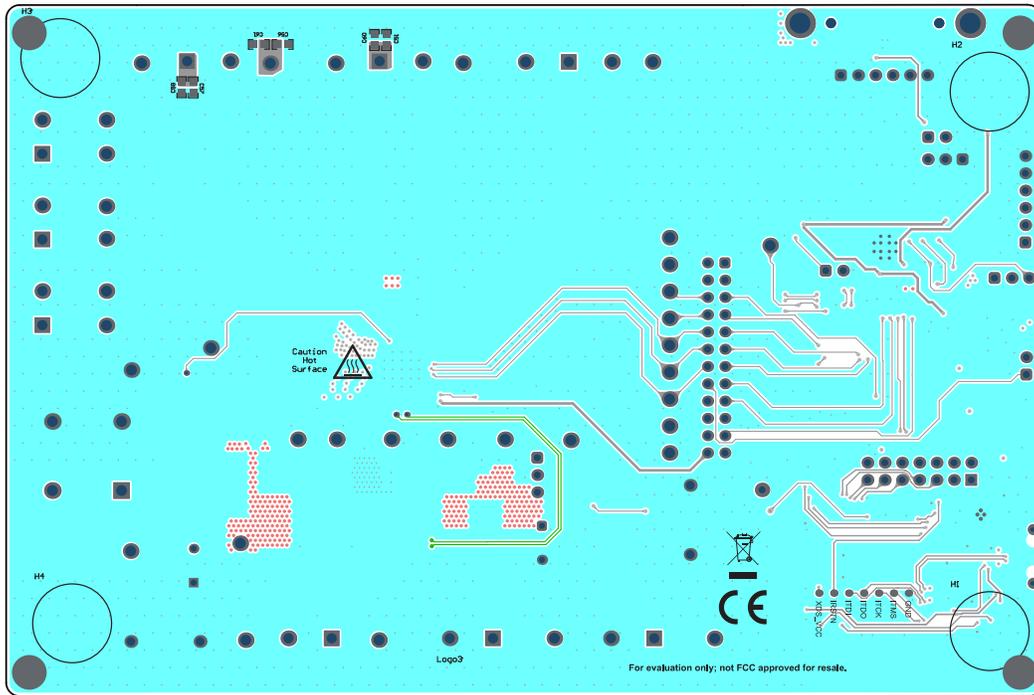


Figure 4-5. Bottom View

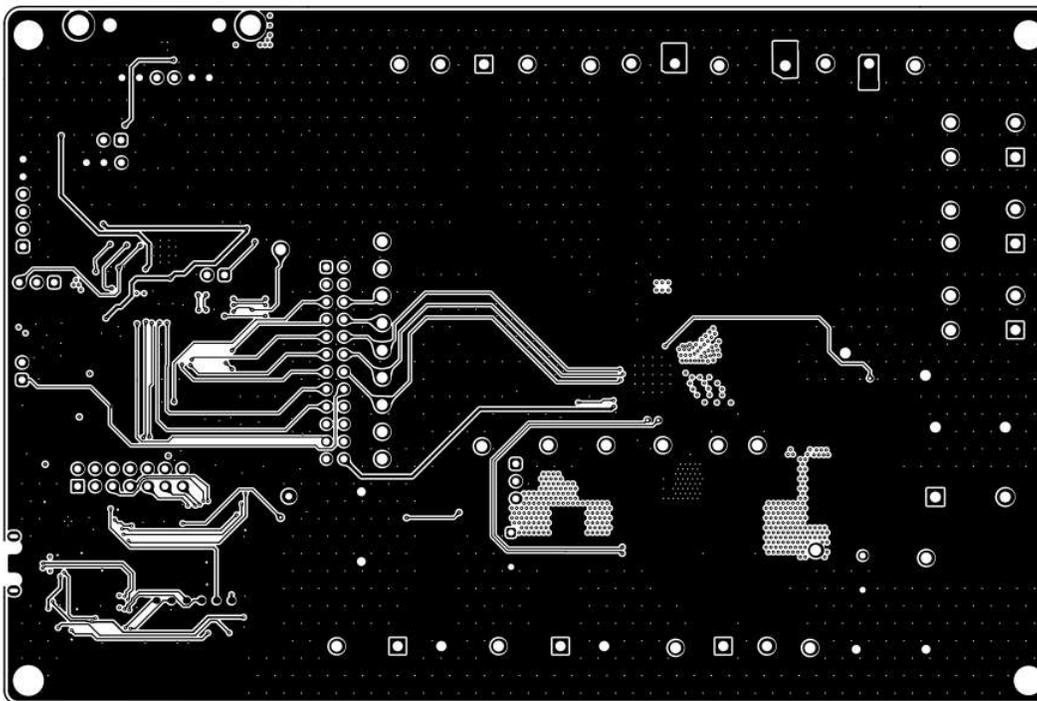


Figure 4-6. Bottom Layers

4.3 Bill of Materials (BOM)

Table 4-1 provides the parts list for DRV8000-Q1EVM.

Table 4-1. Bill of Materials

| Designator | Quantity | Value | Description | Package Reference | Part Number | Manufacturer |
|---------------------------------|----------|--------|---|-------------------|---------------------|------------------|
| !PCB1 | 1 | | Printed Circuit Board | | MD084 | Any |
| C1, C15 | 2 | 2.2uF | CAP, CERM, 2.2uF, 10V, +/- 10%, X5R, 0603 | 0603 | C0603C225K8PACTU | Kemet |
| C2 | 1 | 3300pF | CAP, CERM, 3300pF, 50V, +/- 10%, X7R, 0402 | 0402 | GRM155R71H332KA01D | MuRata |
| C3, C10, C13, C17 | 4 | 1uF | CAP, CERM, 1uF, 25V, +/- 10%, X5R, 0402 | 0402 | C1005X5R1E105K050BC | TDK |
| C4 | 1 | 2.2uF | CAP, CERM, 2.2uF, 6.3V, +/- 10%, X5R, 0402 | 0402 | CL05A225KQ5NNNC | Samsung |
| C5, C6, C7, C14, C20 | 5 | 0.01uF | CAP, CERM, 0.01uF, 25V, +/- 10%, X7R, 0402 | 0402 | GRM155R71E103KA01D | MuRata |
| C8, C9, C11, C12, C16, C21, C22 | 7 | 0.1uF | CAP, CERM, 0.1uF, 6.3V, +/- 10%, X7R, 0402 | 0402 | GRM155R70J104KA01D | MuRata |
| C18, C19 | 2 | 12pF | CAP, CERM, 12pF, 50V, +/- 5%, C0G/NP0, 0402 | 0402 | GRM1555C1H120JA01D | MuRata |
| C23 | 1 | 10uF | CAP, CERM, 10uF, 25V, +/- 10%, X5R, 0603 | 0603 | GRM188R61E106KA73D | MuRata |
| C24, C34, C37, C86 | 4 | 0.1uF | CAP, CERM, 0.1uF, 50V, +/- 10%, X7R, 0603 | 0603 | 8.85012E+11 | Würth Elektronik |
| C25 | 1 | 470nF | WCAP-CSGP Multilayer Ceramic Chip Capacitor, General Purpose, size 0603, X7R Class II, 470nF, 25VDC | 0603 | 885012206075R | Würth Elektronik |
| C26 | 1 | 10nF | WCAP-CSGP Multilayer Ceramic Chip Capacitor, General Purpose, size 0603, X7R, 10nF, 25VDC | 0603 | 8.85012E+11 | Würth Elektronik |
| C27 | 1 | 1uF | WCAP-CSGP Multilayer Ceramic Chip Capacitor, General Purpose, size 0603, X7R, 1uF, 50VDC | 0603 | 8.85012E+11 | Würth Elektronik |
| C28, C29 | 2 | 22pF | WCAP-CSGP Multilayer Ceramic Chip Capacitor, General Purpose, size 0402, NP0, 22pF, 50VDC | 0402 | 8.85012E+11 | Würth Elektronik |
| C30, C32 | 2 | 1uF | CAP, CERM, 1uF, 100V, +/- 10%, X7R, 1206 | 1206 | CC1206KKX7R0BB105 | Yageo America |
| C31 | 1 | 220uF | WCAP-ATG5 Aluminum Electrolytic Capacitor, Radial, THT, D10 x H12.5mm, 220uF, 50V | | 8.60021E+11 | Würth Elektronik |
| C33, C36 | 2 | 0.01uF | CAP, CERM, 0.01uF, 50V, +/- 10%, X7R, 0603 | 0603 | 8.85012E+11 | Würth Elektronik |

Table 4-1. Bill of Materials (continued)

| Designator | Quantity | Value | Description | Package Reference | Part Number | Manufacturer |
|-------------------------|----------|---------|---|-------------------|----------------------|-------------------|
| C35, C38 | 2 | 1uF | CAP, CERM, 1uF, 50V, +/- 10%, X7R, 0805 | 0805 | 8.85012E+11 | Würth Elektronik |
| C39 | 1 | | Electrolytic Capacitor, 330uF, 50V, WCAP-ATG5 Series, 20%, Radial Leaded, 10mm | RADIAL | 8.60021E+11 | Würth Electronics |
| C43, C46 | 2 | 1μF | WCAP-CSGP Multilayer Ceramic Chip Capacitor, General Purpose, size 0603, X7R, 1μF, 25VDC | 0603 | 8.85012E+11 | Würth Elektronik |
| C44 | 1 | 10uF | CAP, CERM, 10μF, 50V, +/- 20%, X5R, 1206 | 1206 | 8.85012E+11 | Würth Elektronik |
| C45, C47, C48 | 3 | 100nF | WCAP-CSGP Multilayer Ceramic Chip Capacitor, General Purpose, size 0603, X7R, 100nF, 100VDC | 0603 | 8.85012E+11 | Würth Elektronik |
| C58 | 1 | 0.022uF | CAP, CERM, 0.022uF, 50V, +/- 10%, X7R, 0603 | 0603 | 8.85012E+11 | Würth Elektronik |
| C63 | 1 | 0.01uF | CAP, CERM, 0.01uF, 16V, +/- 10%, X7R, 0603 | 0603 | 8.85012E+11 | Würth Elektronik |
| C67, C69 | 2 | 5100pF | CAP, CERM, 5100pF, 50V, +/- 5%, C0G/NP0, 0603 | 0603 | C0603C512J5GAC7867 | Kemet |
| C70 | 1 | 0.22uF | CAP, CERM, 0.22μF, 10V, +/- 10%, X7R, 0603 | 0603 | 8.85012E+11 | Würth Elektronik |
| C74, C77, C79 | 3 | 0.1uF | CAP, CERM, 0.1uF, 50V, +/- 10%, X7R, 0603 | 0603 | C1608X7R1H104K080AA | TDK |
| C75, C83 | 2 | 4.7uF | CAP, CERM, 4.7μF, 16V, +/- 10%, X7R, AEC-Q200 Grade 1, 0805 | 0805 | CGA4J3X7R1C475K125AE | TDK |
| C76, C78 | 2 | 10uF | CAP, CERM, 10uF, 50V, +/- 10%, X7R, 1206 | 1206 | CL31B106KBHNNNE | Samsung |
| C80 | 1 | 220pF | CAP, CERM, 220pF, 50V, +/- 1%, C0G/NP0, 0603 | 0603 | 06035A221FAT2A | AVX |
| C81, C84 | 2 | 20pF | CAP, CERM, 20pF, 100V, +/- 5%, C0G/NP0, 0603 | 0603 | GRM1885C2A200JA01D | MuRata |
| C82 | 1 | 4700pF | CAP, CERM, 4700pF, 100V, +/- 10%, X7R, 0603 | 0603 | 06031C472KAT2A | AVX |
| C85 | 1 | 0.01uF | CAP, CERM, 0.01uF, 100V, +/- 10%, X7R, 0603 | 0603 | C0603X103K1RACTU | Kemet |
| D1, D2, D3, D6, D7, D10 | 6 | Green | LED, Green, SMD | LED_0603 | 150060VS75000 | Würth Elektronik |
| D4 | 1 | Red | LED, Red, SMD | LED_0603 | 150060RS75000 | Würth Elektronik |

Table 4-1. Bill of Materials (continued)

| Designator | Quantity | Value | Description | Package Reference | Part Number | Manufacturer |
|-------------------------|----------|-------|---|--------------------------|-----------------|-----------------------------|
| D5 | 1 | 75V | Diode, Switching, 75V, 0.15A, AEC-Q101, SOD-323 | SOD-323 | 1N4148WS-7-F | Diodes Inc. |
| D8 | 1 | 100V | Diode, Switching, 100V, 0.15A, SOD-123 | SOD-123 | 1N4148W-TP | Micro Commercial Components |
| D9 | 1 | | 24V, 1-Channel ESD Protection Diode | SOD323 | ESD1LIN24DYFR | Texas Instruments |
| F1 | 1 | | Fuse, 30A, 250 VAC, 100 VDC, SMD | 10.1x3.12mm | 0463030.ER | Littelfuse |
| FID1, FID2, FID3 | 3 | | Fiducial mark. There is nothing to buy or mount. | N/A | N/A | N/A |
| H1, H2, H3, H4 | 4 | | Bumpon, Hemisphere, 0.44 X 0.20, Clear | Transparent Bumpon | SJ-5303 (CLEAR) | 3M |
| IC1 | 1 | | 4-Channel ESD Protection Array for High-Speed Data Interfaces, DRY0006A (USON-6) | DRY0006A | TPD4E004DRYR | Texas Instruments |
| IC2 | 1 | | 500mA, Adjustable, Low Quiescent Current, Low-Noise, High-PSRR, Single-Output LDO Regulator, DRB0008A (VSON-8) | DRB0008A | TPS73533DRBT | Texas Instruments |
| IC3 | 1 | | Precision Micropower Shunt Voltage Reference, 0.5% accuracy, 2.5V, 15ppm / °C, 15mA, -40°C to 85°C, 5-pin SC70 (DCK), Green (RoHS & no Sb/Br) | DCK0005A | LM4040C25IDCKR | Texas Instruments |
| J1 | 1 | | Header, 100mil, 7x2, Gold, TH | 7x2 Header | TSW-107-07-G-D | Samtec |
| J2 | 1 | | Header, 2.54mm, 12x2, Gold, TH | Header, 2.54mm, 12x2, TH | TSW-112-08-G-D | Samtec |
| J3, J18, J20 | 3 | | Header, 100mil, 2x1, Gold, TH | 2x1 Header | TSW-102-07-G-S | Samtec |
| J4, J6, J7, J8, J9, J16 | 6 | | 2 Position Wire to Board Terminal Block Horizontal with Board 0.250" (6.35mm) Through Hole | CONN_TERM_BLOCK2 | 6.91251E+11 | Würth Electronics |
| J5 | 1 | | 2 Position Wire to Board Terminal Block Horizontal with Board 0.400" (10.16mm) Through Hole | HDR2 | 6.91257E+11 | Würth |
| J10, J11, J12 | 3 | | 2 Position Wire to Board Terminal Block Horizontal with Board 0.197" (5.00mm) Through Hole | HDR2 | 6.91217E+11 | Würth Electronics |
| J13, J19, J23 | 3 | | Header, 100mil, 3x1, Gold, TH | 3x1 Header | TSW-103-07-G-S | Samtec |
| J17, J22 | 2 | | Header, 100mil, 6x1, Gold, TH | 6x1 Header | TSW-106-07-G-S | Samtec |

Table 4-1. Bill of Materials (continued)

| Designator | Quantity | Value | Description | Package Reference | Part Number | Manufacturer |
|---|----------|---------|--|------------------------------|------------------|-------------------|
| LBL1 | 1 | | Thermal Transfer Printable Labels, 0.650" W x 0.200" H - 10,000 per roll | PCB Label 0.650 x 0.200 inch | THT-14-423-10 | Brady |
| LED1 | 1 | Red | LED, Red, SMD | Red LED, 1.6x0.8x0.8mm | LTST-C190KRKT | Lite-On |
| LED2 | 1 | Green | LED, Green, SMD | 1.6x0.8x0.8mm | LTST-C190GKT | Lite-On |
| Q1 | 1 | 65V | Transistor, NPN, 65V, 0.1A, SOT-23 | SOT-23 | BC846BLT1G | ON Semiconductor |
| Q2, Q3, Q4, Q5, Q6, Q8 | 6 | 40V | MOSFET, N-CH, 40V, 100A, DNK0008A (VSON-CLIP-8) | DNK0008A | CSD18512Q5B | Texas Instruments |
| Q7 | 1 | 30V | MOSFET, N-CH, 30V, 25A, DQJ0008A (VSONP-8) | DQJ0008A | CSD17579Q5A | Texas Instruments |
| R1 | 1 | 330k | RES, 330 k, 1%, 0.0625 W, 0402 | 0402 | RC0402FR-07330KL | Yageo America |
| R2, R5, R22, R26, R27, R34, R35, R37, R38, R39, R40, R41, R42, R52, R53, R58, R64, R68, R71 | 19 | 0 | RES, 0, 5%, 0.1 W, 0603 | 0603 | RC0603JR-070RL | Yageo |
| R3 | 1 | 220k | RES, 220 k, 1%, 0.0625 W, 0402 | 0402 | RC0402FR-07220KL | Yageo America |
| R4 | 1 | 3.30k | RES, 3.30 k, 1%, 0.1 W, AEC-Q200 Grade 0, 0402 | 0402 | ERJ-2RKF3301X | Panasonic |
| R6 | 1 | 1.00Meg | RES, 1.00M, 1%, 0.063 W, AEC-Q200 Grade 0, 0402 | 0402 | CRCW04021M00FKED | Vishay-Dale |
| R7, R8, R14 | 3 | 10k | RES, 10 k, 5%, 0.063 W, AEC-Q200 Grade 0, 0402 | 0402 | CRCW040210K0JNED | Vishay-Dale |
| R9, R10, R11, R12, R17 | 5 | 1.0k | RES, 1.0 k, 5%, 0.063 W, AEC-Q200 Grade 0, 0402 | 0402 | CRCW04021K00JNED | Vishay-Dale |
| R13, R16 | 2 | 100 | RES, 100, 5%, 0.063 W, AEC-Q200 Grade 0, 0402 | 0402 | CRCW0402100RJNED | Vishay-Dale |
| R15 | 1 | 4.87k | RES, 4.87 k, 1%, 0.063 W, AEC-Q200 Grade 0, 0402 | 0402 | CRCW04024K87FKED | Vishay-Dale |
| R18 | 1 | 51 | RES, 51, 5%, 0.063 W, AEC-Q200 Grade 0, 0402 | 0402 | CRCW040251R0JNED | Vishay-Dale |
| R19, R20 | 2 | 470 | RES, 470, 5%, 0.063 W, AEC-Q200 Grade 0, 0402 | 0402 | CRCW0402470RJNED | Vishay-Dale |

Table 4-1. Bill of Materials (continued)

| Designator | Quantity | Value | Description | Package Reference | Part Number | Manufacturer |
|---|----------|---------|--|------------------------------------|------------------|---------------------------|
| R23, R25 | 2 | 47k | RES, 47 k, 5%, 0.063 W, AEC-Q200 Grade 0, 0402 | 0402 | CRCW040247K0JNED | Vishay-Dale |
| R24, R43, R73, R74 | 4 | 3.3k | RES, 3.3 k, 5%, 0.1 W, 0603 | 0603 | RC0603JR-073K3L | Yageo |
| R28, R29, R30, R31, R63 | 5 | 330 | RES, 330, 5%, 0.1 W, 0603 | 0603 | RC0603JR-07330RL | Yageo |
| R32, R33, R67 | 3 | 10k | RES, 10 k, 5%, 0.1 W, 0603 | 0603 | RC0603JR-0710KL | Yageo |
| R36 | 1 | 0.007 | RES, 0.007, 1%, 7 W, AEC-Q200 Grade 0, 7.1x4.6mm | 7.1x4.6mm | WSHM28187L000FEA | Vishay-Dale |
| R44 | 1 | 16k | RES, 16 k, 5%, 0.1 W, 0603 | 0603 | RC0603JR-0716KL | Yageo |
| R47, R65 | 2 | 1.0k | RES, 1.0 k, 5%, 0.1 W, 0603 | 0603 | RC0603JR-071KL | Yageo |
| R51 | 1 | 220 | RES, 220, 1%, 0.1 W, 0603 | 0603 | RC0603FR-07220RL | Yageo |
| R57 | 1 | 1.00k | RES, 1.00 k, 1%, 0.1 W, 0603 | 0603 | RC0603FR-071KL | Yageo |
| R62 | 1 | 560 | RES, 560, 5%, 0.1 W, 0603 | 0603 | RC0603JR-07560RL | Yageo |
| R66, R75 | 2 | 0 | RES, 0, 0.05%, 2 W, AEC-Q200 Grade 0, 2512 | 2512 | HCJ2512ZT0R00 | Stackpole Electronics Inc |
| R69, R70 | 2 | 60.4 | RES, 60.4, 1%, 0.1 W, 0603 | 0603 | RC0603FR-0760R4L | Yageo |
| R72 | 1 | 1.00Meg | RES, 1.00M, 1%, 0.1 W, 0402 | 0402 | ERJ-2RKF1004X | Panasonic |
| R76 | 1 | 20k | RES, 20 k, 5%, 0.1 W, 0603 | 0603 | RC0603JR-0720KL | Yageo |
| R77 | 1 | 1.8k | RES, 1.8 k, 5%, 0.1 W, 0603 | 0603 | RC0603JR-071K8L | Yageo |
| S1 | 1 | | Tactile Switch SPST-NO Top Actuated Surface Mount | SMT_SW_6MM2_6MM2 | 4.30481E+11 | Würth Electronics |
| SH1, SH2 | 2 | | 1mm Uninsulated Shorting Plug, 10.16mm spacing, TH | Shorting Plug, 10.16mm spacing, TH | D3082-05 | Harwin |
| SH-J1, SH-J2, SH-J3, SH-J4, SH-J5, SH-J6, SH-J7, SH-J8, SH-J9, SH-J10, SH-J11, SH-J12, SH-J13, SH-J14, SH-J15, SH-J16, SH-J17, SH-J18, SH-J19, SH-J20, SH-J21 | 21 | | Shunt, 2.54mm, Gold, Black | Shunt, 2.54mm, Black | 60900213421 | Würth Elektronik |

Table 4-1. Bill of Materials (continued)

| Designator | Quantity | Value | Description | Package Reference | Part Number | Manufacturer |
|---|----------|-------|---|---|----------------------------|----------------------|
| TP8 | 1 | | Test Point, Miniature, White, TH | White Miniature Test point | 5002 | Keystone Electronics |
| TP9, TP10, TP11, TP12, TP13, TP14, TP15, TP18, TP19, TP22, TP23, TP24, TP27, TP28, TP29, TP31, TP32, TP33, TP34, TP35, TP36, TP37, TP38, TP39, TP40, TP41, TP42, TP44, TP46, TP47, TP48, TP49 | 32 | | Test Point, Multipurpose, White, TH | White Multipurpose Test point | 5012 | Keystone Electronics |
| TP16, TP17 | 2 | | Test Point, Compact, SMT | Test point_Keystone_Compact | 5016 | Keystone Electronics |
| TP20, TP21 | 2 | | Test Point, Multipurpose, Red, TH | Red Multipurpose Test point | 5010 | Keystone Electronics |
| TP25, TP26 | 2 | | Test Point, Multipurpose, Black, TH | Black Multipurpose Test point | 5011 | Keystone Electronics |
| U1 | 1 | | Mixed-Signal Microcontrollers With CAN-FD Interface LQFP64 | LQFP64 | MSPM0G3507SPM | Texas Instruments |
| U2 | 1 | | Automotive Multi-function Driver with Integrated Half-bridges & HighSide and Current Sensing & Advanced Diagnostics | VQFN48 | DRV8000QWRGZRQ1 | Texas Instruments |
| U4 | 1 | | 24V, 2-Channel ESD Protection Diode for In-Vehicle Networks | SOT-23-3 | ESD2CAN24DBZR | Texas Instruments |
| USB1 | 1 | | Receptacle, USB 2.0, Micro B, 5 Position, R/A, SMT | Receptacle, USB 2.0, Micro B, 5 Pos, 0.65mm Pitch, R/A, SMT | 1051640001 | Molex |
| XDS1 | 1 | | MSP432E401YTPDT, PDT0128A (TQFP-128) | PDT0128A | MSP432E401YTPDTR | Texas Instruments |
| Y1 | 1 | | Crystal, 16MHz, 8pF, SMD | 3.2x0.75x2.5mm | NX3225GA-16.000M-STD-CRG-1 | NDK |
| C40 | 0 | | WCAP-CSGP Multilayer Ceramic Chip Capacitor, General Purpose, size 0603, X7R, 100nF, 100VDC | | | Würth Elektronik |

Table 4-1. Bill of Materials (continued)

| Designator | Quantity | Value | Description | Package Reference | Part Number | Manufacturer |
|--|----------|---------|---|--------------------------------|---------------------|-------------------|
| C41, C42, C49, C50, C51, C52, C53, C54, C55, C56, C57, C59, C60, C61, C64, C65, C66, C71, C72, C73, C87, C88, C89, C90, C91, C92 | 0 | 0.022uF | CAP, CERM, 0.022uF, 50V, +/- 10%, X7R, 0603 | 0603 | 8.85012E+11 | Würth Elektronik |
| C62 | 0 | | CAP CER 0.015UF 50V X7R 0603 | 0603 | 8.85012E+11 | Würth Electronics |
| C68 | 0 | 0.01uF | CAP, CERM, 0.01uF, 100V, +/- 10%, X7R, 0603 | 0603 | 8.85012E+11 | Würth Elektronik |
| J21 | 0 | | Receptacle, D-Sub, 9 Position, R/A, SMT | 30.81x10.28x10.10 mm | 190-009-263R001 | NorComp |
| L1 | 0 | | FIXED IND 2.2UH 16A 2.2 MOHM | IND_SMT_11MM6_10MM5 | 74439369022 | Würth Electronics |
| L2 | 0 | 100uH | Inductor, Ferrite, 100 uH, 0.15A, 2 ohm, SMD | SMD, 4-Leads, Body 4.7 x 3.7mm | ACT45B-101-2P-TL003 | TDK |
| R21 | 0 | 0 | RES, 0, 5%, 0.1 W, 0603 | 0603 | RC0603JR-070RL | Yageo |
| Y2 | 0 | | Crystal 40MHz ±10ppm (Tol) ±20ppm (Stability) 12pF FUND 40Ohm 4-Pin Mini-CSMD T/R | TSX-3225 | X1E0000210179 | Seiko Epson |

5 Additional Information

5.1 Trademarks

All trademarks are the property of their respective owners.

STANDARD TERMS FOR EVALUATION MODULES

1. *Delivery:* TI delivers TI evaluation boards, kits, or modules, including any accompanying demonstration software, components, and/or documentation which may be provided together or separately (collectively, an "EVM" or "EVMs") to the User ("User") in accordance with the terms set forth herein. User's acceptance of the EVM is expressly subject to the following terms.
 - 1.1 EVMs are intended solely for product or software developers for use in a research and development setting to facilitate feasibility evaluation, experimentation, or scientific analysis of TI semiconductors products. EVMs have no direct function and are not finished products. EVMs shall not be directly or indirectly assembled as a part or subassembly in any finished product. For clarification, any software or software tools provided with the EVM ("Software") shall not be subject to the terms and conditions set forth herein but rather shall be subject to the applicable terms that accompany such Software
 - 1.2 EVMs are not intended for consumer or household use. EVMs may not be sold, sublicensed, leased, rented, loaned, assigned, or otherwise distributed for commercial purposes by Users, in whole or in part, or used in any finished product or production system.
2. *Limited Warranty and Related Remedies/Disclaimers:*
 - 2.1 These terms do not apply to Software. The warranty, if any, for Software is covered in the applicable Software License Agreement.
 - 2.2 TI warrants that the TI EVM will conform to TI's published specifications for ninety (90) days after the date TI delivers such EVM to User. Notwithstanding the foregoing, TI shall not be liable for a nonconforming EVM if (a) the nonconformity was caused by neglect, misuse or mistreatment by an entity other than TI, including improper installation or testing, or for any EVMs that have been altered or modified in any way by an entity other than TI, (b) the nonconformity resulted from User's design, specifications or instructions for such EVMs or improper system design, or (c) User has not paid on time. Testing and other quality control techniques are used to the extent TI deems necessary. TI does not test all parameters of each EVM. User's claims against TI under this Section 2 are void if User fails to notify TI of any apparent defects in the EVMs within ten (10) business days after delivery, or of any hidden defects with ten (10) business days after the defect has been detected.
 - 2.3 TI's sole liability shall be at its option to repair or replace EVMs that fail to conform to the warranty set forth above, or credit User's account for such EVM. TI's liability under this warranty shall be limited to EVMs that are returned during the warranty period to the address designated by TI and that are determined by TI not to conform to such warranty. If TI elects to repair or replace such EVM, TI shall have a reasonable time to repair such EVM or provide replacements. Repaired EVMs shall be warranted for the remainder of the original warranty period. Replaced EVMs shall be warranted for a new full ninety (90) day warranty period.

WARNING

Evaluation Kits are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems.

User shall operate the Evaluation Kit within TI's recommended guidelines and any applicable legal or environmental requirements as well as reasonable and customary safeguards. Failure to set up and/or operate the Evaluation Kit within TI's recommended guidelines may result in personal injury or death or property damage. Proper set up entails following TI's instructions for electrical ratings of interface circuits such as input, output and electrical loads.

NOTE:

EXPOSURE TO ELECTROSTATIC DISCHARGE (ESD) MAY CAUSE DEGRADATION OR FAILURE OF THE EVALUATION KIT; TI RECOMMENDS STORAGE OF THE EVALUATION KIT IN A PROTECTIVE ESD BAG.

3 Regulatory Notices:

3.1 United States

3.1.1 Notice applicable to EVMs not FCC-Approved:

FCC NOTICE: This kit is designed to allow product developers to evaluate electronic components, circuitry, or software associated with the kit to determine whether to incorporate such items in a finished product and software developers to write software applications for use with the end product. This kit is not a finished product and when assembled may not be resold or otherwise marketed unless all required FCC equipment authorizations are first obtained. Operation is subject to the condition that this product not cause harmful interference to licensed radio stations and that this product accept harmful interference. Unless the assembled kit is designed to operate under part 15, part 18 or part 95 of this chapter, the operator of the kit must operate under the authority of an FCC license holder or must secure an experimental authorization under part 5 of this chapter.

3.1.2 For EVMs annotated as FCC – FEDERAL COMMUNICATIONS COMMISSION Part 15 Compliant:

CAUTION

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

FCC Interference Statement for Class A EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

FCC Interference Statement for Class B EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210 or RSS-247

Concerning EVMs Including Radio Transmitters:

This device complies with Industry Canada license-exempt RSSs. Operation is subject to the following two conditions:

(1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Concerning EVMs Including Detachable Antennas:

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.

3.3 Japan

3.3.1 *Notice for EVMs delivered in Japan:* Please see http://www.tij.co.jp/lstds/ti_ja/general/eStore/notice_01.page 日本国内に輸入される評価用キット、ボードについては、次のところをご覧ください。

<https://www.ti.com/ja-jp/legal/notice-for-evaluation-kits-delivered-in-japan.html>

3.3.2 *Notice for Users of EVMs Considered "Radio Frequency Products" in Japan:* EVMs entering Japan may not be certified by TI as conforming to Technical Regulations of Radio Law of Japan.

If User uses EVMs in Japan, not certified to Technical Regulations of Radio Law of Japan, User is required to follow the instructions set forth by Radio Law of Japan, which includes, but is not limited to, the instructions below with respect to EVMs (which for the avoidance of doubt are stated strictly for convenience and should be verified by User):

1. Use EVMs in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

【無線電波を送信する製品の開発キットをお使いになる際の注意事項】 開発キットの中には技術基準適合証明を受けていないものがあります。技術適合証明を受けていないものご使用に際しては、電波法遵守のため、以下のいずれかの措置を取っていただく必要がありますのでご注意ください。

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2. 実験局の免許を取得後ご使用いただく。
3. 技術基準適合証明を取得後ご使用いただく。

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ンスツルメンツ株式会社

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西新宿三井ビル

3.3.3 *Notice for EVMs for Power Line Communication:* Please see http://www.tij.co.jp/lstds/ti_ja/general/eStore/notice_02.page

電力線搬送波通信についての開発キットをお使いになる際の注意事項については、次のところをご覧ください。 <https://www.ti.com/ja-jp/legal/notice-for-evaluation-kits-for-power-line-communication.html>

3.4 European Union

3.4.1 *For EVMs subject to EU Directive 2014/30/EU (Electromagnetic Compatibility Directive):*

This is a class A product intended for use in environments other than domestic environments that are connected to a low-voltage power-supply network that supplies buildings used for domestic purposes. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

-
- 4 *EVM Use Restrictions and Warnings:*
 - 4.1 EVMS ARE NOT FOR USE IN FUNCTIONAL SAFETY AND/OR SAFETY CRITICAL EVALUATIONS, INCLUDING BUT NOT LIMITED TO EVALUATIONS OF LIFE SUPPORT APPLICATIONS.
 - 4.2 User must read and apply the user guide and other available documentation provided by TI regarding the EVM prior to handling or using the EVM, including without limitation any warning or restriction notices. The notices contain important safety information related to, for example, temperatures and voltages.
 - 4.3 *Safety-Related Warnings and Restrictions:*
 - 4.3.1 User shall operate the EVM within TI's recommended specifications and environmental considerations stated in the user guide, other available documentation provided by TI, and any other applicable requirements and employ reasonable and customary safeguards. Exceeding the specified performance ratings and specifications (including but not limited to input and output voltage, current, power, and environmental ranges) for the EVM may cause personal injury or death, or property damage. If there are questions concerning performance ratings and specifications, User should contact a TI field representative prior to connecting interface electronics including input power and intended loads. Any loads applied outside of the specified output range may also result in unintended and/or inaccurate operation and/or possible permanent damage to the EVM and/or interface electronics. Please consult the EVM user guide prior to connecting any load to the EVM output. If there is uncertainty as to the load specification, please contact a TI field representative. During normal operation, even with the inputs and outputs kept within the specified allowable ranges, some circuit components may have elevated case temperatures. These components include but are not limited to linear regulators, switching transistors, pass transistors, current sense resistors, and heat sinks, which can be identified using the information in the associated documentation. When working with the EVM, please be aware that the EVM may become very warm.
 - 4.3.2 EVMs are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems. User assumes all responsibility and liability for proper and safe handling and use of the EVM by User or its employees, affiliates, contractors or designees. User assumes all responsibility and liability to ensure that any interfaces (electronic and/or mechanical) between the EVM and any human body are designed with suitable isolation and means to safely limit accessible leakage currents to minimize the risk of electrical shock hazard. User assumes all responsibility and liability for any improper or unsafe handling or use of the EVM by User or its employees, affiliates, contractors or designees.
 - 4.4 User assumes all responsibility and liability to determine whether the EVM is subject to any applicable international, federal, state, or local laws and regulations related to User's handling and use of the EVM and, if applicable, User assumes all responsibility and liability for compliance in all respects with such laws and regulations. User assumes all responsibility and liability for proper disposal and recycling of the EVM consistent with all applicable international, federal, state, and local requirements.
 5. *Accuracy of Information:* To the extent TI provides information on the availability and function of EVMs, TI attempts to be as accurate as possible. However, TI does not warrant the accuracy of EVM descriptions, EVM availability or other information on its websites as accurate, complete, reliable, current, or error-free.
 6. *Disclaimers:*
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