

# Subsystem Design

## 5-V Interface



### Description

This example demonstrates how to interface with signals up to 5 V using open-drain IOs (ODIOs) on an MSPM0 device. With the use of external pullup resistors, the open-drain IOs allow for communication across multiple voltage domains at voltage levels higher than the MSPM0  $V_{DD}$  supply voltage.

Figure 1-1 displays a functional block diagram of the peripherals used in this example.

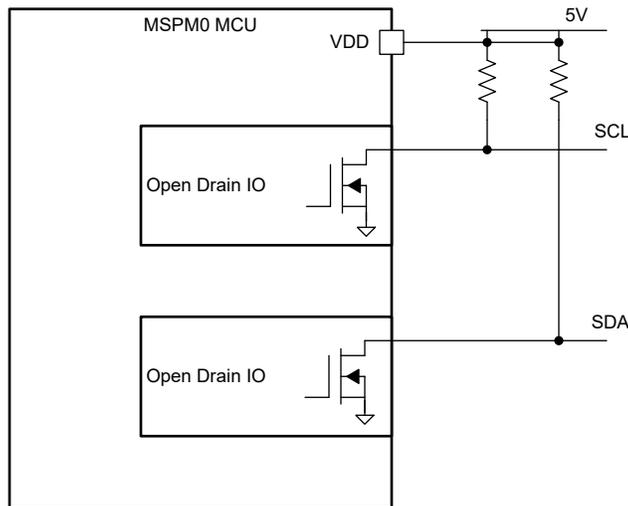


Figure 1-1. Subsystem Functional Block Diagram

### Required Peripherals

This application can use up to two open-drain IOs.

Table 1-1.

Sub-block Functionality	Peripheral Use	Notes
IO	2 GPIO pins	PA0 and PA1, can only use 5-V tolerant open-drain IOs

### Compatible devices

Based on the requirements in Table 1-1, this example is compatible with the devices in Table 1-2. The corresponding EVM can be used for prototyping.

Table 1-2.

Compatible Devices	EVM
MSPM0Lxxx	<a href="#">LP-MSPM0L1306</a>
MSPM0Gxxx	<a href="#">LP-MSPM0G3507</a>

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### Design steps

1. Connect appropriate jumpers.
2. Determine the pullup resistance needed for your application.
  - a. The required pullup strength depends on the timing requirements of your application and the capacitance of your connections. For greater capacitance, you need to have a stronger (that is, low resistance) pullup. A discussion on determining the exact resistance of a pullup is beyond the scope of this document but can be found in the [I2C Bus Pullup Resistor Calculation application note](#).
3. Configure peripherals that are used on these pins in software (for example, UART, I2C, or Timer) in [SysConfig](#).
4. Write application code, dependent on peripherals used.

### Design considerations

1. Pullup resistor: A pullup resistor is required to output high for I2C and UART functions on ODIOs.
2. Drive strength control: This is not available for ODIO types.

### Additional Resources

- [Download the MSPM0 SDK](#)
- [Learn more about SysConfig](#)
- [MSPM0L LaunchPad](#)
- [MSPM0G LaunchPad](#)

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