

Table of Contents

1 Features	1	7.4 Device Functional Modes.....	13
2 Applications	1	8 Application and Implementation	14
3 Description	1	8.1 Application Information.....	14
4 Device Comparison	3	8.2 Typical Application.....	15
5 Pin Configuration and Functions	4	9 Device and Documentation Support	24
6 Specifications	5	9.1 Device Support.....	24
6.1 Absolute Maximum Ratings.....	5	9.2 Documentation Support.....	24
6.2 ESD Ratings.....	5	9.3 Receiving Notification of Documentation Updates.....	24
6.3 Recommended Operating Conditions.....	5	9.4 Support Resources.....	24
6.4 Thermal Information.....	6	9.5 Trademarks.....	24
6.5 Electrical Characteristics.....	6	9.6 Electrostatic Discharge Caution.....	24
6.6 Typical Characteristics.....	8	9.7 Glossary.....	25
7 Detailed Description	10	10 Revision History	25
7.1 Overview.....	10	11 Mechanical, Packaging, and Orderable Information	25
7.2 Functional Block Diagram.....	10		
7.3 Feature Description.....	11		

4 Device Comparison

Table 4-1. Device Performance Improvements

PARAMETER	UC284xAQ/UC284xA-Q1	UC284xL-Q1
V _{CC} max	30V	36V
CS-OUT delay	150ns	100ns
Rise/fall time max	150ns	75ns
OUT low level at 200mA	1.5V	0.5V
OUT high level at 200mA, V _{CC} = 15V	12V	13.1V
Startup current	0.3mA	0.25mA
Operating current max	17mA	15mA

5 Pin Configuration and Functions

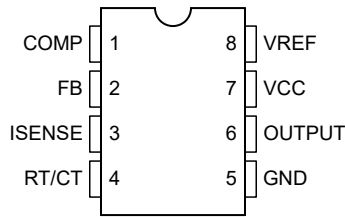


Figure 5-1. D Package, 8-Pin SOIC (Top View)

Table 5-1. Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
COMP	1	O	Outputs the low impedance 1MHz internal error amplifier that is also the input to the peak current limit or PWM comparator, with an open-loop gain (AVOL) of 80dB. This pin is capable of sinking a maximum of 6mA and is not internally current limited.
FB	2	I	Input to the error amplifier that can be used to control the power converter voltage-feedback loop for stability.
GND	5	—	This is the controller signal ground.
ISENSE	3	I	Input to the peak current limit, PWM comparator of the UC284xL-Q1 controller. When used in conjunction with a current sense resistor, the error amplifier output voltage controls the power systems cycle-by-cycle peak current limit. The maximum peak current sense signal is internally clamped to 1V. See Section 7.2 .
OUTPUT	6	O	Output of 1A totem pole gate driver. This pin can sink and source up to 1A of gate driver current. A gate driver resistor must be used to limit the gate driver current.
RT/CT	4	I	Input to the internal oscillator that is programmed with an external timing resistor (RT) and timing capacitor (CT). See Section 7.3.5 for information on properly selecting these timing components. TI recommends using capacitance values from 470pF to 4.7nF. TI also recommends that the timing resistor values chosen be from 5kΩ to 100kΩ.
VCC	7	I	Bias input to the gate driver. This pin must have a biasing capacitor that is at least 10 times greater than the gate capacitance of the main switching FET used in the design.
VREF	8	O	Reference voltage output of the PWM controller. This pin must supply no more than 10mA under normal operation. This output is short-circuit protected at roughly 100mA. This reference is also used for internal comparators and needs a high frequency bypass capacitor of 1μF. The VCC capacitor also must be at least 10 times greater than the capacitor on the VREF pin.

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾

		MIN	MAX	UNIT
Supply voltage ⁽²⁾	V _{CC} pin		V _{CC} Zener Voltage	V
Supply current, I _{CC}			25	mA
Output current, I _{OUT}			±1	A
Output energy (capacitive load)			5	μJ
Analog inputs		−0.3	6.3	V
Maximum negative voltage	All pins	−0.3		V
Error amplifier output sink current, I _{COMP}			10	mA
Power dissipation at T _A ≤ 25°C			1	W
Lead temperature (soldering, 10s)			300	°C
Junction temperature, T _J		−55	150	°C
Storage temperature, T _{stg}		−65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under [Section 6.3](#). Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) In normal operation V_{CC} is driven from a low impedance source through current limiting resistor. The resistor must be sized so that the V_{CC} voltage under all operating conditions is between V_{CC} Zener clamp voltage and undervoltage lockout threshold. Absolute maximum V_{CC} is defined based on internal Zener clamp voltage in [Electrical Characteristics](#) such that I_{CC} does not exceed 25mA. Failure to limit V_{CC} and I_{CC} to these limits may result in permanent damage of the device.

6.2 ESD Ratings

		VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human-body model (HBM), per AEC Q100-002 ⁽¹⁾	±2000
		Charged-device model (CDM), per AEC Q100-011	±1500

- (1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specifications.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
V _{CC}	Bias supply voltage	UC2844L-Q1		18	30	V
		UC2843L-Q1, UC2845L-Q1		10	30	
V _{FB} , V _{RC} , V _{VFB}	Voltage on analog pins	FB, ISENSE, and RT/CT pins	−0.1		5	V
V _{OUT}	Gate driver output voltage		−0.1		V _{CC}	V
I _{VCC}	Supply bias current	VCC pin			25	mA
I _{VREF}	Output current	VREF pin			10	mA
f _{OSC}	Oscillator frequency				500	kHz
T _A	Operating free-air temperature		−40		125	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾		D (SOIC)	UNIT
		8 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	117.4	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	51.5	°C/W
R _{θJB}	Junction-to-board thermal resistance	61	°C/W
Ψ _{JT}	Junction-to-top characterization parameter	7.8	°C/W
Ψ _{JB}	Junction-to-board characterization parameter	60.2	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	—	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

6.5 Electrical Characteristics

Unless otherwise stated, these specifications apply for T_A = –40°C to 125°C, T_A = T_J; V_{CC} = 15V⁽⁴⁾; R_T = 10kΩ; C_T = 3.3nF.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
REFERENCE					
Output voltage	T _J = 25°C, I _O = 1mA	4.95	5	5.05	V
Line regulation	12V ≤ V _{IN} ≤ 25V		6	20	mV
Load regulation	1mA ≤ I _O ≤ 20mA		6	25	mV
Temperature stability	See ⁽¹⁾ ⁽⁶⁾		0.2	0.4	mV/°C
Total output variation	Line, Load, Temperature	4.9		5.1	V
Output noise voltage	10Hz ≤ f ≤ 10kHz; T _J = 25°C ⁽¹⁾		50		μV
Long-term stability	T _A = 125°C, 1000hrs ⁽¹⁾		5	25	mV
Output short circuit		–30	–100	–180	mA
OSCILLATOR					
Initial accuracy	T _J = 25°C ⁽⁵⁾	47	52	57	kHz
Voltage stability	12V ≤ V _{CC} ≤ 25V		0.2	1	%
Temperature stability	T _{MIN} ≤ T _A ≤ T _{MAX} ⁽¹⁾		5		%
Amplitude	V _{RT/CT} peak to peak ⁽¹⁾		1.7		V
Discharge current	V _{RT/CT} = 2V ⁽⁷⁾		8.3		mA
ERROR AMPLIFIER					
Input voltage	V _{COMP} = 2.5V	2.45	2.5	2.55	V
Input bias current			–0.3	–1	μA
			–0.3	–2	
A _{VOL} Open-loop gain	2V ≤ V _O ≤ 4V	65	90		dB
Unity gain bandwidth	T _J = 25°C ⁽¹⁾	0.7	1		MHz
CMRR Common mode rejection ratio	12V ≤ V _{CC} ≤ 25V	60	70		dB
Output sink current	V _{FB} = 2.7V, V _{COMP} = 1.1V	2	6		mA
Output source current	V _{FB} = 2.3V, V _{COMP} = 5V	–0.5	–0.8		mA
V _{OUT} high	V _{FB} = 2.3V, R _L = 15kΩ to ground	5	6		V
V _{OUT} low	V _{FB} = 2.7V, R _L = 15kΩ to VREF		0.7	1.1	V
CURRENT SENSE					
Gain	See ⁽²⁾ ⁽³⁾	2.85	3	3.15	V/V
Maximum input signal	V _{COMP} = 5V ⁽²⁾	0.9	1	1.1	V
PSRR Power supply rejection ratio	12V ≤ V _{CC} ≤ 25V ⁽²⁾		70		dB
Input bias current			–2	–10	μA

6.5 Electrical Characteristics (continued)

Unless otherwise stated, these specifications apply for $T_A = -40^{\circ}\text{C}$ to 125°C , $T_A = T_J$; $V_{CC} = 15\text{V}^{(4)}$; $R_T = 10\text{k}\Omega$; $C_T = 3.3\text{nF}$.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Delay to output	V _{ISENSE} = 0V to 2V ⁽¹⁾		100	200	ns
OUTPUT					
Output low level	I _{SINK} = 20mA		0.05	0.11	V
	I _{SINK} = 200mA		0.55	1.1	
Output high level	I _{SOURCE} = 20mA	13.2	13.6		V
	I _{SOURCE} = 200mA	13.1	13.5		
Rise time	T _J = 25°C, C _L = 1nF ⁽¹⁾		25	75	ns
Fall time	T _J = 25°C, C _L = 1nF ⁽¹⁾		25	75	ns
UVLO saturation	V _{CC} = 5V, I _{SINK} = 10mA		0.7	1.2	V
UNDERVOLTAGE LOCKOUT					
Start threshold	UC2844L-Q1	15	16	17	V
	UC2843L-Q1, UC2845L-Q1	7.8	8.4	9	
Minimum operation voltage after turn on	UC2844L-Q1	9	10	11	V
	UC2843L-Q1, UC2845L-Q1	7	7.6	8.2	
PWM					
Maximum duty cycle	UC2843L-Q1	92	96	100	%
	UC2844L-Q1, UC2845L-Q1	46	48	50	%
Minimum duty cycle				0	%
TOTAL STANDBY CURRENT					
Start-up current			0.25	0.5	mA
Operating supply current	V _{FB} = V _{ISENSE} = 0V		11	15	mA
V _{CC} Zener voltage	I _{CC} = 25mA	36			V

- (1) Ensured by design, but not 100% production tested.
- (2) Parameter measured at trip point of latch with $V_{FB} = 0\text{V}$.
- (3) Gain defined as: $A = \Delta V_{\text{COMP}} / \Delta V_{\text{ISENSE}}$; $0\text{V} \leq V_{\text{ISENSE}} \leq 0.8\text{V}$.
- (4) Adjust V_{CC} above the start threshold before setting at 15V.
- (5) Output frequency is one half oscillator frequency.
- (6) Temperature stability, sometimes referred to as *average temperature coefficient*, is described by: Temperature stability = $(V_{\text{REF(max)}} - V_{\text{REF(min)}}) / (T_{J(\text{max})} - T_{J(\text{min})})$. $V_{\text{REF(max)}}$ and $V_{\text{REF(min)}}$ are the maximum and minimum reference voltage measured over the appropriate temperature range. Note that the extremes in voltage do not necessarily occur at the extremes in temperature.
- (7) This parameter is measured with $R_T = 10\text{k}\Omega$ to V_{REF} . This contributes approximately 300 μA of current to the measurement. The total current flowing into the RT/CT pin is approximately 300 μA higher than the measured value.

6.6 Typical Characteristics

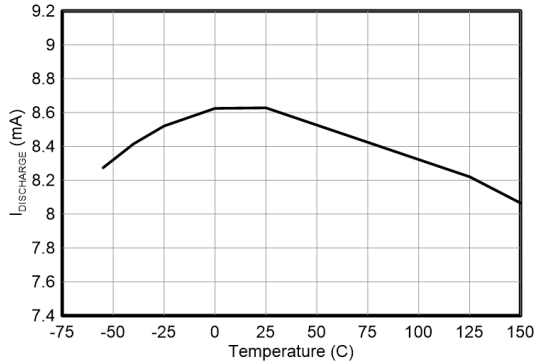


Figure 6-1. Oscillator Discharge Current vs Temperature for $V_{CC} = 15\text{ V}$ and $V_{RT/CT} = 2\text{ V}$

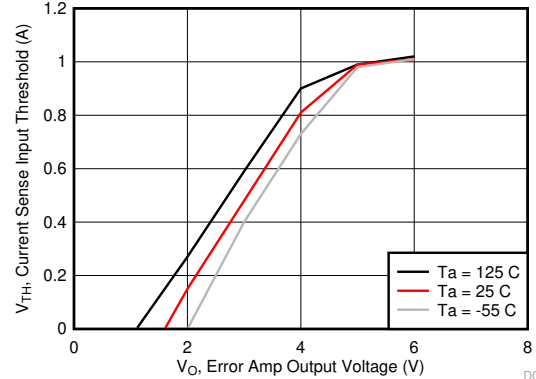


Figure 6-2. Current Sense Input Threshold vs Error Amplifier Output Voltage for $V_{CC} = 15\text{ V}$

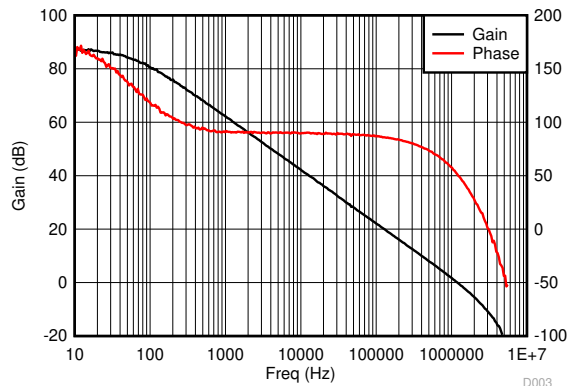


Figure 6-3. Error Amplifier Open-Loop Gain and Phase vs Frequency $V_{CC} = 15\text{ V}$, $R_L = 100\text{ k}\Omega$, and $T_A = 25\text{ }^\circ\text{C}$

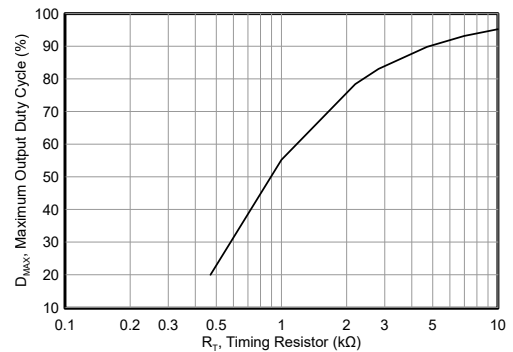


Figure 6-4. Max Output Duty Cycle vs Timing Resistor for $V_{CC} = 15$, $C_T = 3.3\text{ nF}$, $T_A = 25\text{ }^\circ\text{C}$

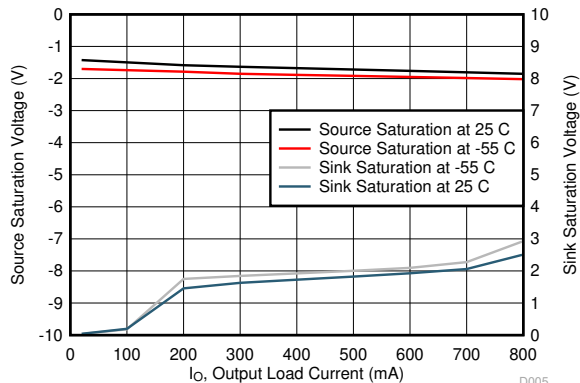


Figure 6-5. Output Saturation Voltage vs Load Current for $V_{CC} = 15\text{ V}$ with 5-ms Input Pulses

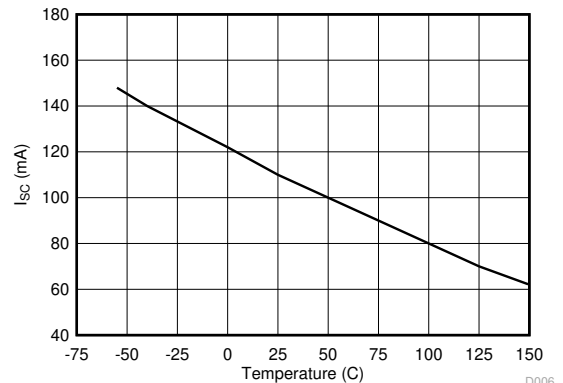


Figure 6-6. Reference Short Circuit Current vs Temperature for $V_{CC} = 15\text{ V}$

6.6 Typical Characteristics (continued)

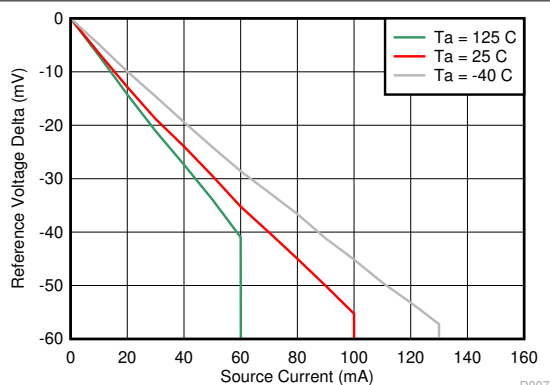


Figure 6-7. Reference Voltage vs Source Current

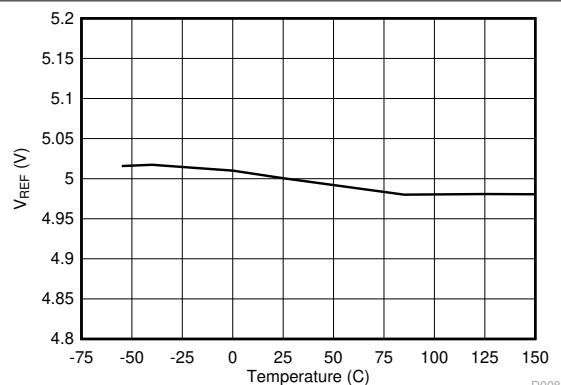


Figure 6-8. Reference Voltage vs Temperature

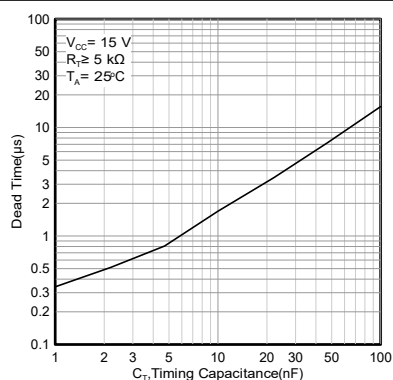


Figure 6-9. Dead Time vs Timing Capacitance

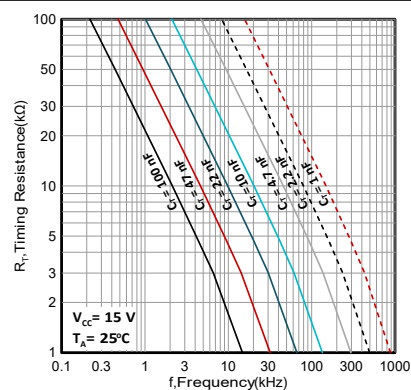


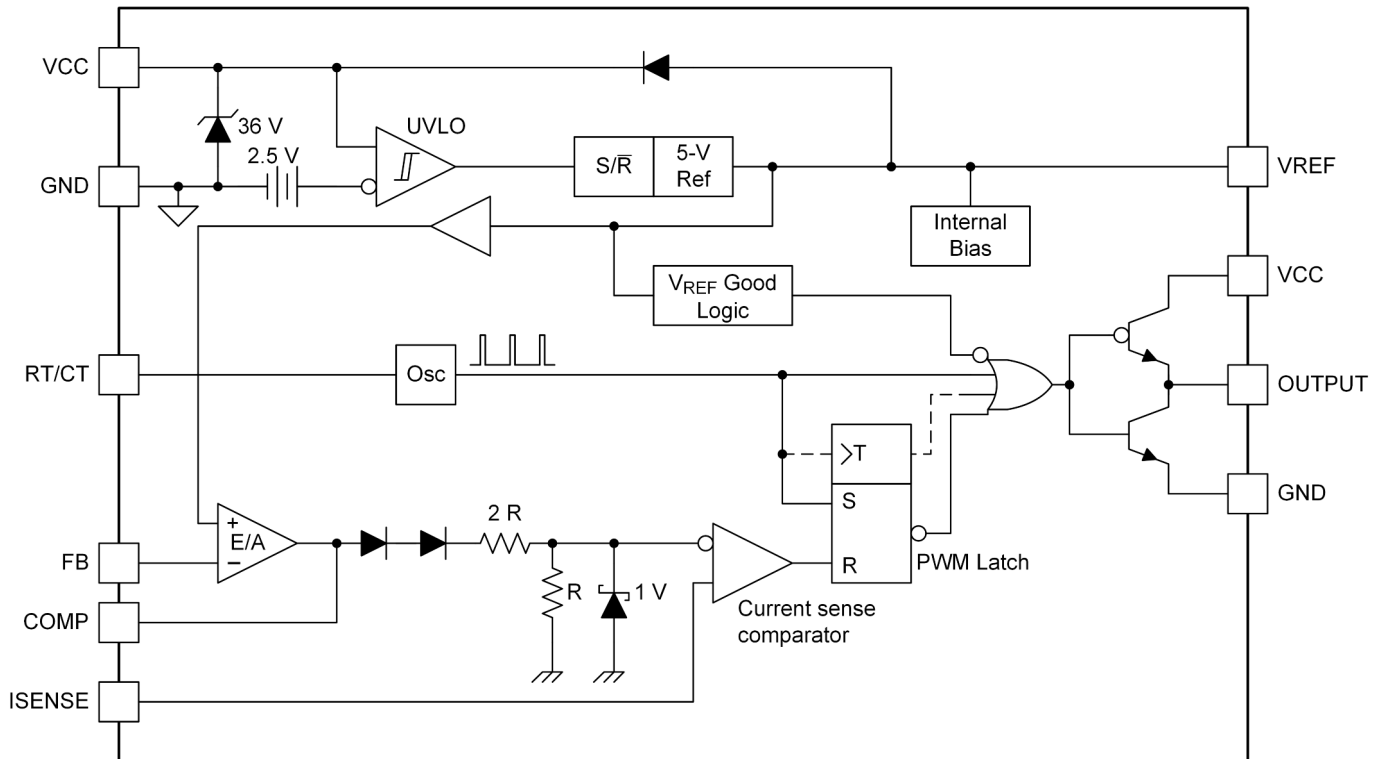
Figure 6-10. Timing Resistance vs Frequency

7 Detailed Description

7.1 Overview

The UC284xL-Q1 device is a fixed-frequency pulse-width-modulator (PWM) controller and designed to operate at switching frequencies of 500kHz. These controllers are designed for peak current mode (PCM) and can be used in isolated and non-isolated power supply designs. These controllers can drive FETs directly from the output, which is capable of sourcing and sinking up to 1A of gate driver current. These devices also have a built-in low-impedance amplifier that can be used in non-isolated designs to control the power supply output voltage and feedback loop.

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Pulse-by-Pulse Current Limiting

Pulse-by-pulse limiting is inherent in the current mode control scheme. An upper limit on the peak current can be established by simply clamping the error voltage. Accurate current limiting allows optimization of magnetic and power semiconductor elements while ensuring reliable supply operation.

7.3.2 Current Sense Circuit

Peak current (I_S) is determined by Equation 1:

$$I_{S(max)} \times \frac{1V}{R_S} \quad (1)$$

A small RC filter may be required to suppress switch transients.

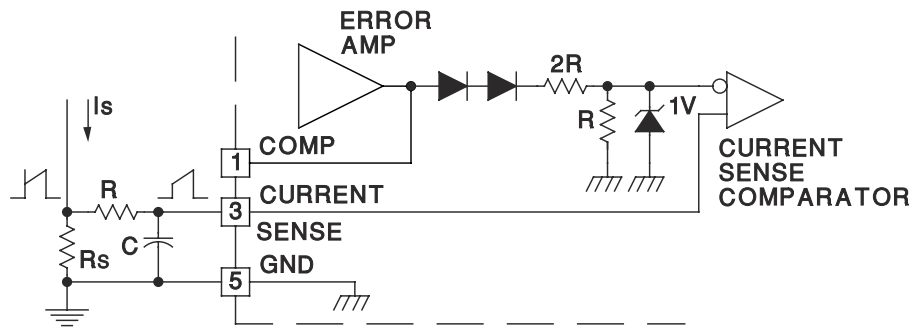


Figure 7-1. Current Sense Circuit Diagram

7.3.3 Error Amplifier Configuration

The error amplifier can source up to 0.8mA, and sink up to 6mA.

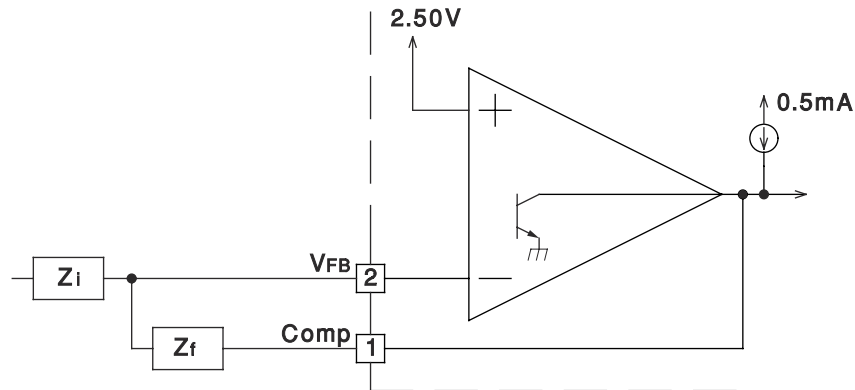


Figure 7-2. Error Amplifier Configuration Diagram

7.3.4 Undervoltage Lockout

The UC284xL-Q1 device is featured with undervoltage lockout protection circuits for controlled operation during power-up and power-down sequences.

During UVLO the IC draws typically 0.25mA of supply current. This lower VCC current than the UC284xAQ/UC284xA-Q1 families results in lower power drawn from the line. The reduced start-up current is of particular concern in off-line supplies where the IC is *powered-up* from the high-voltage DC rail, then bootstrapped to an auxiliary winding on the main transformer. Power is then dissipated in the start-up resistor which is sized by the IC's start-up current. Once crossing the turnon threshold the IC supply current increases typically to about 11mA. During undervoltage lockout, the UC284xL-Q1 prevents the power MOSFET from parasitically turning on due to the *Miller* effect at power-up. This improved design to the lower totem-pole transistor's operation during undervoltage lockout allows the IC to sink higher currents, up to 10mA, at saturation voltages as low as 0.7V.

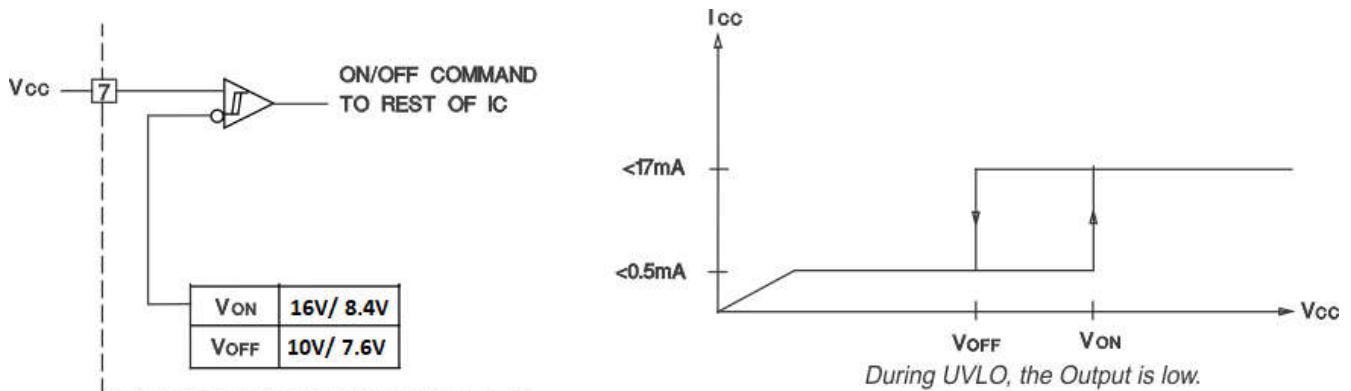


Figure 7-3. Undervoltage Lockout

7.3.5 Oscillator

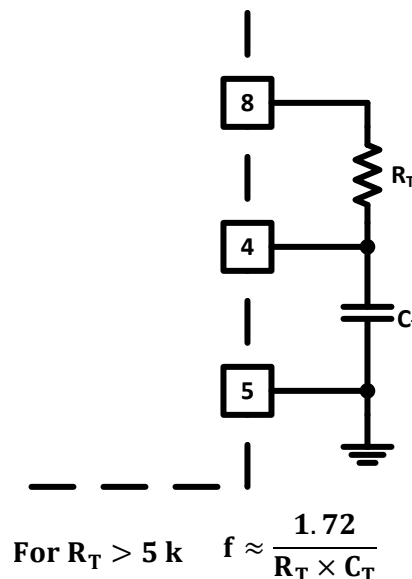


Figure 7-4. Oscillator Section

Precision operation at high frequencies with an accurate maximum duty cycle, see [Figure 6-10](#), can now be obtained with the UC284xL-Q1 family of devices due to the trimmed oscillator discharge current. This nullifies

the effects of production variations in the initial discharge current or dead time. Note the UC2844L-Q1 and UC2845L-Q1 OUTPUT frequency is half of the oscillator frequency and associated max duty cycle is 50%.

7.4 Device Functional Modes

7.4.1 Normal Operation

The IC can be used in peak current mode (PCM) control or voltage mode (VM) control. When the converter is operating in PCM, the voltage amplifier output will regulate the converter's peak current and duty cycle. When the IC is used in VM control, the voltage amplifier output will regulate the power converter's duty cycle. The regulation of the system's peak current and duty cycle can be achieved with the use of the integrated error amplifier and external feedback circuitry.

7.4.2 Undervoltage Lockout (UVLO) Start-Up

During system start-up, VCC voltage starts to rise from 0V. Before the VCC voltage reaches its corresponding start threshold, the IC is operating in UVLO mode. After the UVLO turn start-up threshold is met the device will become active and the reference will come up to 5V.

7.4.3 UVLO Turnoff Mode

If the bias voltage to VCC drops below the UVLO minimum operating voltage, PWM switching stops and the reference will become inactive, returning to 0V. The device can be restarted by applying a voltage greater than the UVLO start threshold to the VCC pin.

8 Application and Implementation

Note

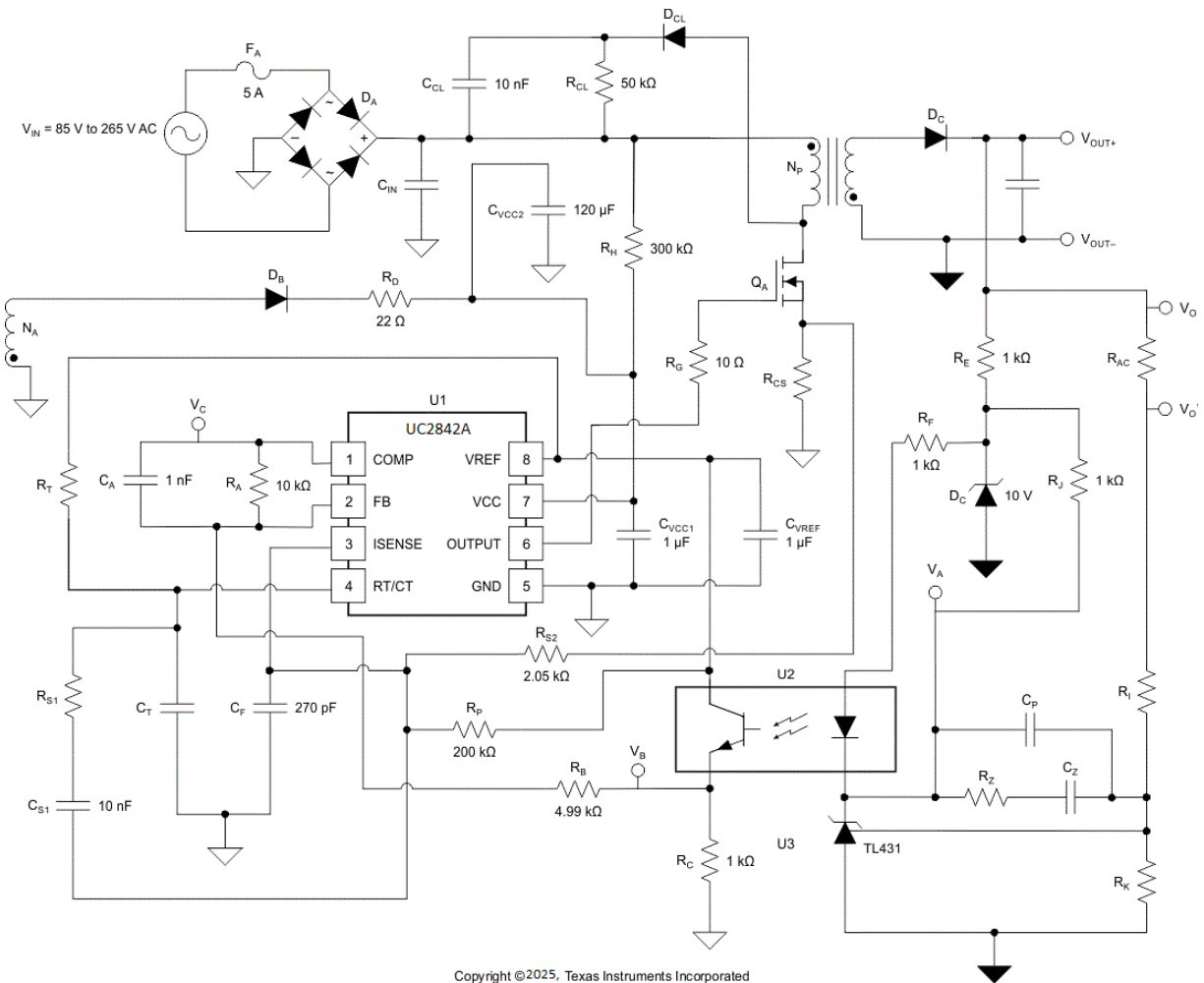
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

8.1 Application Information

The UC284xL-Q1 controller is a peak-current mode pulse-width modulator. The controller has an onboard amplifier and can be used in isolated or nonisolated power supply designs. There is an onboard totem-pole gate driver capable of delivering 1 A of peak current. This is a high-speed PWM capable of operating at switching frequencies up to 500 kHz. The typical applications is shown in [UC2842A data sheet](#), and can be found at www.ti.com/product/UC2842A or UCx84x/UCx84xA/UC284xAQ/TL284x/TL284xB families product pages, for details.

8.2 Typical Application

A typical application for the UC284xL-Q1 in an off-line flyback converter is shown in Figure 8-1. UC2842A is used as a design example here that can be applied to UC284xL-Q1: The UC2842A uses an inner current control loop that contains a small current sense resistor which senses the primary inductor current ramp. This current sense resistor transforms the inductor current waveform to a voltage signal that is input directly into the primary side PWM comparator. This inner loop determines the response to input voltage changes. An outer voltage control loop involves comparing a portion of the output voltage to a reference voltage at the input of an error amplifier. When used in an off-line isolated application, the voltage feedback of the isolated output is accomplished using a secondary-side error amplifier and adjustable voltage reference, such as the TL431. The error signal crosses the primary to secondary isolation boundary using an opto-isolator whose collector is connected to the VREF pin and the emitter is connected to FB. The outer voltage control loop determines the response to load changes.



Copyright © 2025, Texas Instruments Incorporated

Figure 8-1. Typical Flyback Application Circuit

8.2.1 Design Requirements

For this design example, use the parameters listed in [Table 8-1](#) as the input parameters.

Table 8-1. Design Parameters

PARAMETER	MIN	TYP	MAX	UNIT
INPUT CHARACTERISTICS				
V _{IN} Input voltage (RMS)	85		265	V
f _{LINE} Line frequency	47		63	Hz
OUTPUT CHARACTERISTICS				
V _{OUT} Output voltage	11.75	12	12.25	V
Output ripple voltage		50		mV _{PP}
I _{OUT} Output current		4	4.33	A
Load step	11.75		12.25	V
SYSTEMS CHARACTERISTICS				
η Maximum load efficiency	86%			

8.2.2 Detailed Design Procedure

8.2.2.1 Custom Design With WEBENCH® Tools

[Click here](#) to create a custom design using the UC284xA device (corresponding to equivalent GPN for UC284xL-Q1) with the WEBENCH® Power Designer.

1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

8.2.2.2 UC2842A (UC284xL-Q1) Design Procedure

This application design procedure shows how to setup and use the UC2842A peak current mode controller in an offline flyback converter, with universal input to a 12-V, 48-W regulated output. The same process can be applied to UC284xL-Q1 family.

Setting up and designing with the UC2842A peak current mode controller in a continuous mode flyback application requires knowing some things about the power stage. First, calculate the required input bulk capacitance (C_{IN}) based on output power level (P_{OUT}), efficiency (η), minimum input voltage (V_{IN(min)}), line frequency (f_{LINE}) and minimum bulk voltage. For this design example let V_{BULK(min)} = 95V.

$$V_{INripple} = \frac{2 \times \frac{P_{OUT}}{\eta} \times \left[0.25 + \frac{1}{\pi} \times \arcsin \left(\frac{V_{BULK(min)}}{\sqrt{2} \times V_{IN(min)}} \right) \right]}{\left(2 \times V_{IN(min)}^2 - V_{BULK(min)}^2 \right) \times f_{LINE}} \quad (2)$$

$$C_{IN} = \frac{2 \times \frac{P_{OUT}}{\eta} \times \left[0.25 + \frac{1}{\pi} \times \arcsin \left(\frac{V_{BULK(min)}}{\sqrt{2} \times V_{IN(min)}} \right) \right]}{(2 \times V_{IN(min)}^2 - V_{BULK(min)}^2) \times f_{LINE}} \approx 180 \mu F \quad (3)$$

The output capacitor (C_{OUT}) is sized so the output voltage does not droop more than 10% during a large-signal transient response. The voltage-loop crossover frequency (f_C) is estimated to be 2.5kHz at this point in the design.

$$C_{OUT} \geq \frac{\frac{I_{OUT}}{f_C}}{V_{OUT} \times 10\%} \approx 1.33mF \quad (4)$$

The C_{OUT} selected for the design is a 2200- μF capacitor, with an equivalent series resistance (ESR) of 45m Ω .

Next calculate the maximum primary to secondary turns ratio (N_{PS}) of the transformer, based on the minimum input voltage and output voltage.

$$N_{PS} \leq \frac{V_{IN(min)} \times \sqrt{2}}{V_{OUT}} = \frac{85 V \times \sqrt{2}}{12 V} \approx 10 \quad (5)$$

Next calculate the auxiliary to secondary turns ratio (N_{AS}) of the transformer, based on the output voltage and the bias voltage of the UC2842A.

$$N_{AS} \leq \frac{V_{VCC}}{V_{OUT}} = \frac{12\text{ V}}{12\text{ V}} = 1 \quad (6)$$

Once the transformer turns ratios have been determined, the minimum primary magnetizing inductance (L_{PM}) of the transformer can be calculated based on minimum bulk voltage, Duty Cycle (D), reflected output current and efficiency. The transformer used in this design has an L_{PM} of 1.7mH, $N_{PS} = 10$, and a $N_{AS} = 1$, $f_{sw} = 100\text{kHz}$

$$D = \frac{N_{PS} \times V_{OUT}}{V_{BULK(min)} + N_{PS} \times V_{OUT}} \approx 0.56 \quad (7)$$

$$L_{PM} \geq \frac{V_{BULK(min)} \times D}{\frac{70\% \times I_{OUT} \times f_{sw}}{\eta \times N_{PS}}} = 1.632\text{mH} \approx 1.7\text{mH} \quad (8)$$

After the transformer has been selected, the primary peak current (I_{LPK}) of the transformer can be calculated based on the primary magnetizing inductance ripple (I_{LPM}) and the reflected output current across the transformer.

$$I_{LPM} = \frac{V_{BULK(min)} \times D}{f_{SW} \times L_M} \approx 0.31\text{ A} \quad (9)$$

$$I_{LPK} = \frac{I_{OUT}}{N_{PS} \times (1-D)} + \frac{I_{LM}}{2} \approx 1.1\text{ A} \quad (10)$$

Once the primary peak current has been calculated the current sense resistor (R_{CS}) can be selected.

$$R_{CS} = \frac{1\text{ V}}{I_{LPK} \times 1.3} = 0.725\ \Omega \approx 0.75\ \Omega \quad (11)$$

Resistors R_{S1} and R_{S2} are used to set the slope compensation of the design. Capacitor C_{S1} is a DC blocking capacitor, and pull-up resistor R_P is used to provide some offset to the current sense signal for noise immunity. R_P and R_{S2} were preselected to add a DC offset of 50mV to the current sense signal.

R_{S1} is selected to set the slope compensation to one-half of the ripple current down slope of the flyback inductor. This can be accomplished by calculating the secondary magnetizing inductance (L_{SM}) and using the following calculation for R_{S1} . The 1.7V in the R_{S1} equation is the peak-to-peak ripple voltage amplitude of the oscillator.

$$R_{S1} = \frac{1.7\text{ V} \times R_{S2} \times f_{SW} \times (2 \times L_{SM} \times N_{PS})}{V_{OUT} \times (1-D) \times R_{CS}} - R_{S2} = 27.72\text{ k}\Omega \approx 27.4\text{ k}\Omega \quad (12)$$

where

- $R_{S2} = 2.05\text{ k}\Omega$

Resistors R_I and R_K are selected to the output reference and can be calculated by preselecting a value for R_K and knowing the TL431 reference voltage ($V_{TL431REF}$). After choosing 2.49 k Ω for R_K , R_I is calculated and a standard resistor value of 9.53k Ω is chosen for this resistor.

$$R_I = \frac{R_K \times (V_{OUT} - V_{TL431REF})}{V_{TL431REF}} = \frac{2.49 \text{ k}\Omega \times (12 \text{ V} - 2.5 \text{ V})}{2.5 \text{ V}} = 9.462 \text{ k}\Omega \approx 9.53 \text{ k}\Omega \quad (13)$$

This design using the UC3842A controller has an interesting control loop with many components. $G_{OPTO}(f)$ is the approximate transfer function across the opto isolator in the design. The pole frequency of the opto isolator is represented by f_p . The opto isolator used in this design has a current transfer ratio of 1 and pole frequency of roughly 5kHz. See [Figure 8-1](#) for component placement and node voltages. The voltage loop (f_c) must cross-over less than the opto isolator pole for simplified compensation.

$$s(f) = 2 \times \pi \times 1i \times f \quad (14)$$

$$f_p = 5 \text{ kHz} \quad (15)$$

$$G_{OPTO}(f) = \frac{\Delta V_B}{\Delta V_A} = \frac{R_C}{R_F} \times \frac{ctr}{\frac{s(f)}{2 \times \pi \times f_p} + 1} \quad (16)$$

$G_{BC}(f)$ is an estimate of the transfer function from the output of the opto isolator to the PWM's control voltage .

$$G_{BC}(f) = \frac{\Delta V_C}{\Delta V_B} = \frac{R_A}{R_B} \times \frac{1}{s(f) \times R_A \times C_A + 1} \quad (17)$$

The duty cycle varies with the bulk input voltage (V_{BULK}). V_{BULK} varies from 95V to 375V during normal operation. This causes the duty cycle to vary from 24% to 56%.

$$D = \frac{N_{PS} \times V_{OUT}}{V_{BULK} + N_{PS} \times V_{OUT}} = 0.24 \text{ to } 0.56 \quad (18)$$

$G_{CO}(f)$ is an estimate of the control (V_C) to output transfer function, where variable Q is the quality factor.

$$G_{CO}(f) = \frac{\Delta V_{OUT}}{\Delta V_C} = N_{PS} \times \frac{1-D}{1+D} \times \left[\frac{s(f) \times ESR \times C_{OUT} + 1}{s(f) \times R_{OUT} \times C_{OUT} + 1} \right] \times \left[1 - \frac{s(f) L_{SM} \times D}{R_{OUT} \times (1-D)^2} \right] \times \frac{\frac{1}{3}}{1 + \frac{s(f)}{2 \times \pi \times \frac{f_{SW}}{2} \times Q} + \left(\frac{s(f)}{2 \times \pi \times \frac{f_{SW}}{2}} \right)^2} \quad (19)$$

The quality factor (Q) is defined by the primary magnetizing inductance change in voltage (S_N) as a function of duty cycle; as well as, the added slope compensation (S_E).

$$S_N = \frac{V_{BULK} \times R_{CS}}{L_{PM}} \quad (20)$$

$$S_E = 1.7 \text{ V} \times \frac{R_{S2} \times f_{SW}}{R_{S1} + R_{S2}} \quad (21)$$

$$Q = \frac{1}{\pi \left[\left(1 + \frac{S_E}{S_N} \right) \times (1-D) - 0.5 \right]} \quad (22)$$

To ensure that the voltage loop is stable, the crossover frequency must be less than one half of the right-half-plane zero frequency (f_{RHPZ}) of the flyback converter. The right-half-plane zero frequency at the minimum bulk voltage would be roughly 9.8kHz. For this design example the target crossover of the voltage loop is at 1kHz. The actual f_c may be higher or lower than the target.

$$f_{RHPz} = \frac{(N_{PS})^2}{\frac{2 \times \pi \times L_{pm}}{R_{OUT}} \frac{D}{(1-D)^2}} \approx 9.8 \text{ kHz} \quad (23)$$

$$f_C \leq \frac{f_{RHPz}}{2} \approx 5 \text{ kHz} \quad (24)$$

The DC gain of $G_{CO}(f)$ moves with the bulk input voltage. Resistor R_Z is selected to crossover the voltage loop when input to the converter is at $V_{BULK(min)}$ and to crossover at 1/5th the maximum crossover frequency.

$$R_Z = \frac{R_I}{|G_{OPTO}(f_C/5) \times G_{BC}(f_C/5) \times G_O \times G_{CO}(f_C/5)|} = 23.95 \text{ k}\Omega, \text{ a } 23.7 \text{ k}\Omega \text{ was used} \quad (25)$$

Capacitor C_Z is selected to add 45° of phase margin at voltage loop crossover. For this design example a 6.8-nF capacitor was used.

$$C_Z = \frac{1}{2\pi \times \frac{f_C}{5} \times R_Z} \approx 6.7 \text{ nF} \quad (26)$$

Capacitor C_P is selected to attenuate the high frequency gain of the control loop.

$$C_P = \frac{C_Z}{10} = 680 \text{ pF} \quad (27)$$

$G_C(f)$ is the estimated transfer function of the TL431 compensation.

$$G_C(f) = \frac{\Delta V_C}{\Delta V_O} = \frac{s(f) \times R_Z \times C_Z + 1}{s(f) \times R_I \times (C_Z + C_P) \times \left(\frac{s(f) \times R_Z \times C_Z \times C_P}{C_Z + C_P} + 1 \right)} \quad (28)$$

$T_V(f)$ is the estimated theoretical transfer function of the close-loop gain of the system. The feedback loop response may be different in the actual circuit and may have to be adjusted with a network analyzer to meet actual circuit performance and reliability. The feedback loop response must be evaluated over worst case variations in design parameters.

$$T_V(f) = G_C(f) \times G_{OPTO}(f) \times G_{BC}(f) \times G_O \times G_{CO}(f_C) \quad (29)$$

For this application example, this design technique generated a theoretical feedback loop ($T_V(f)$) crossover at 1kHz with roughly 55° of phase margin at a minimum input bulk voltage of 95V. The theoretical voltage loop at high-line crossed over at 2.7kHz with a phase margin of 72°. See Figure 8-2 and Figure 8-3. $T_V(f)$ must be evaluated with a network analyzer and adjust the loop compensation as necessary based on the actual circuitry behavior. Also conduct transient testing to ensure that the device remains stable.

8.2.3 Application Curves

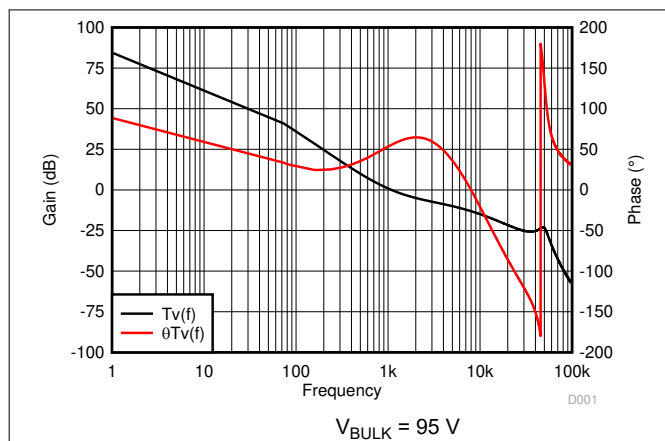


Figure 8-2. Voltage Loop Gain

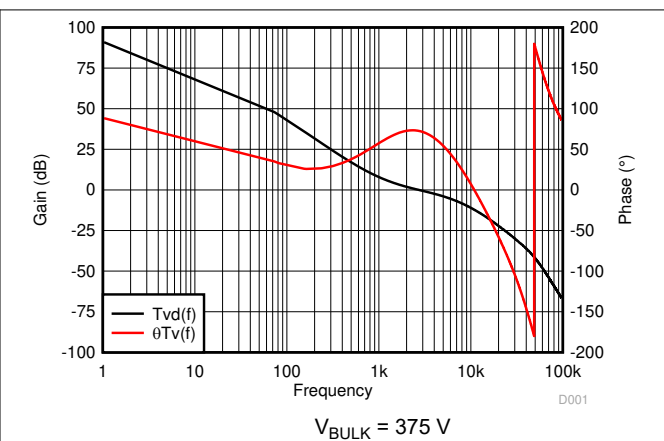


Figure 8-3. Voltage Loop Gain

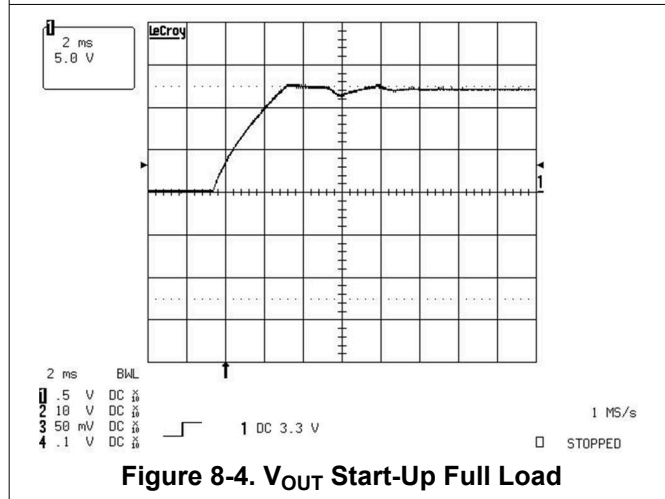


Figure 8-4. V_{OUT} Start-Up Full Load

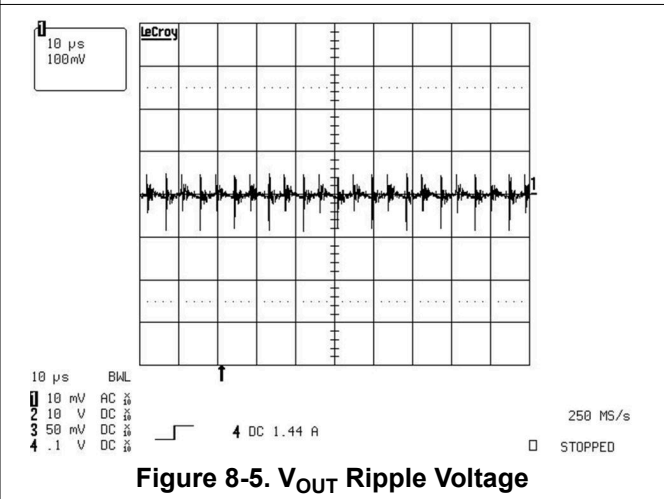


Figure 8-5. V_{OUT} Ripple Voltage

8.2.4 Power Supply Recommendations

TI recommends using the UC284xL-Q1 in isolated or non-isolated peak current mode control power supplies. The device can be used in buck, boost, flyback, and forwarded converter-based power supply topologies.

8.2.5 Layout

8.2.5.1 Layout Guidelines

- Star grounding techniques must be used.
- Current loops must be kept as short and narrow as possible.
- The IC ground and power ground must meet at the return for the input bulk capacitor. Ensure that high frequency and high current from the power stage does not go through the signal ground paths.
- A high-frequency bypass capacitor (C_{VCC1}) must be placed across VCC and GND pins as close as possible to the pins.
- Resistor R_{S2} and capacitor C_F form a low-pass filter for the current sense signal. C_F must be as close to CS and GND pins as possible.
- Capacitor C_{VREF} must be as close to VREF and GND pins as possible.
- [Figure 8-6](#) shows the SMD components arranged for wave-solder on a single-layer board. If multiple layers are used, some components may be rearranged for easier interconnection and reduced current-loop areas. If the solder process allows, placing the SMD components in perpendicular orientations may improve interconnections and loop areas.

8.2.5.2 Layout Example

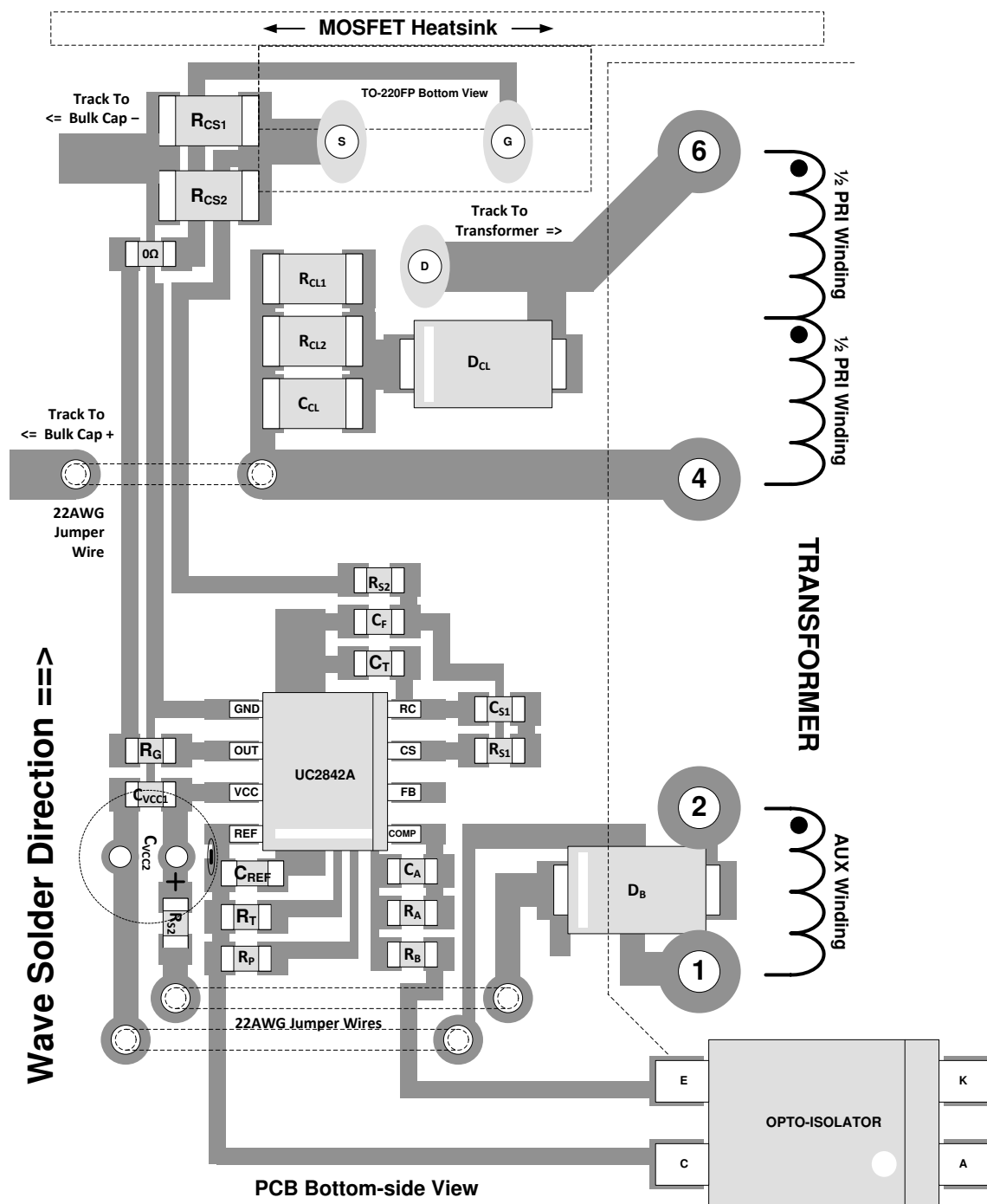


Figure 8-6. Layout Diagram

9 Device and Documentation Support

9.1 Device Support

9.1.1 Device Nomenclature

C_{IN}	Input bulk capacitance
C_{OUT}	Output capacitance
D	Duty cycle
ESR	Equivalent series resistance
$G_{BC}(f)$	An estimate of the transfer function from the output of the opto-isolator to the PWM control voltage.
G_O	The DC gain of the control to output transfer function.
$G_{OPTO}(f)$	The approximate transfer function across the opto-isolator in the design.
I_{LPM}	Transformer primary average current
I_{LpPK}	Peak transformer primary current
L_{PM}	Transformer primary magnetizing inductance
L_{SM}	Transformer secondary magnetizing inductance
N_{PS}	Primary to secondary transformer turns ratio
N_{AS}	Auxiliary to secondary transformer turns ratio
$T_V(f)$	is the feedback control loop transfer function.
$V_{INripple}$	Input ripple voltage

9.2 Documentation Support

9.2.1 Related Documentation

For related documentation see the following:

[Design Review: 150 Watt Current-Mode Flyback](#) (SLUP078)

[UCx84x/UCx84xA/UC284xAQ/TL284x/TL284xB](#) data sheets or product pages for more reference design

9.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](https://www.ti.com). Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

9.4 Support Resources

[TI E2E™ support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

9.5 Trademarks

TI E2E™ is a trademark of Texas Instruments.

All trademarks are the property of their respective owners.

9.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

9.7 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

10 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

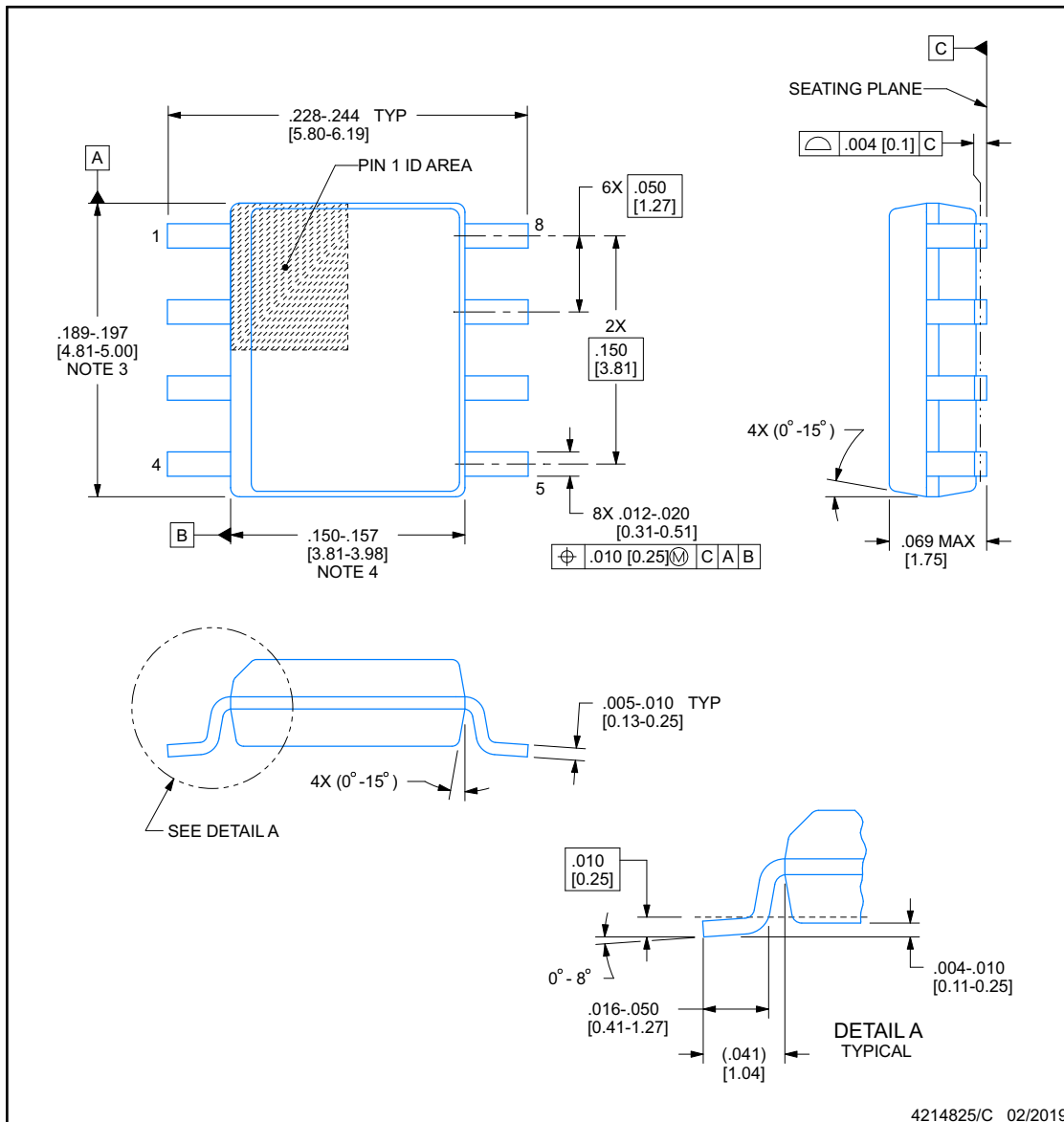
DATE	REVISION	NOTES
March 2025	*	Initial Release

11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

**D0008A****PACKAGE OUTLINE****SOIC - 1.75 mm max height**

SMALL OUTLINE INTEGRATED CIRCUIT



4214825/C 02/2019

NOTES:

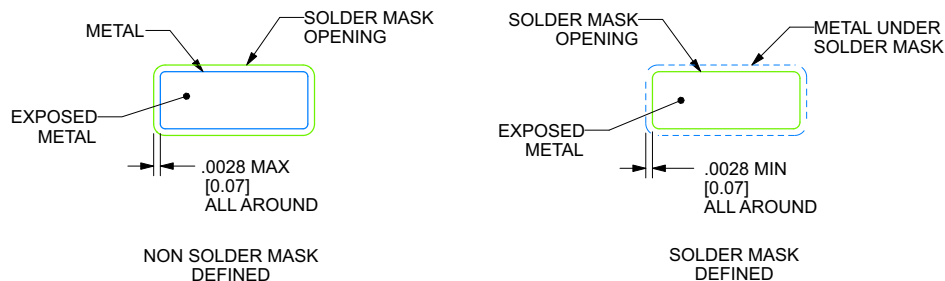
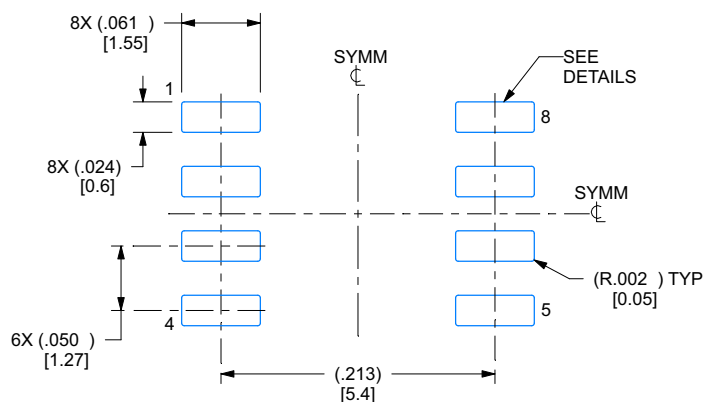
1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

EXAMPLE BOARD LAYOUT

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



4214825/C 02/2019

NOTES: (continued)

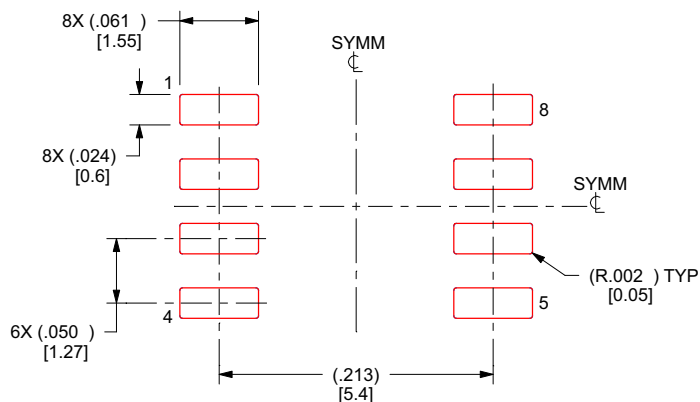
6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE
BASED ON .005 INCH [0.125 MM] THICK STENCIL
SCALE:8X

4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
UC2843ALQD8RQ1	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	843ALQ
UC2843ALQD8RQ1.A	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	843ALQ
UC2844ALQD8RQ1	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	844ALQ
UC2844ALQD8RQ1.A	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	844ALQ
UC2845ALQD8RQ1	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	845ALQ
UC2845ALQD8RQ1.A	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	845ALQ

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF UC2843L-Q1, UC2844L-Q1, UC2845L-Q1 :

- Catalog : [UC2843L](#), [UC2844L](#), [UC2845L](#)

NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product

TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
UC2843ALQD8RQ1	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
UC2844ALQD8RQ1	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
UC2845ALQD8RQ1	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
UC2843ALQD8RQ1	SOIC	D	8	2500	367.0	367.0	35.0
UC2844ALQD8RQ1	SOIC	D	8	2500	367.0	367.0	35.0
UC2845ALQD8RQ1	SOIC	D	8	2500	367.0	367.0	35.0



D0008A

PACKAGE OUTLINE

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



4214825/C 02/2019

NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

EXAMPLE BOARD LAYOUT

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:8X



SOLDER MASK DETAILS

4214825/C 02/2019

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE
BASED ON .005 INCH [0.125 MM] THICK STENCIL
SCALE:8X

4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#) or other applicable terms available either on [ti.com](https://www.ti.com) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2025, Texas Instruments Incorporated