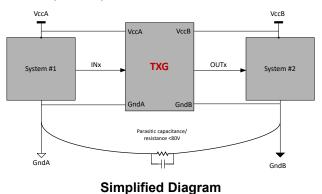


# TXG802x-Q1 2-bit, ±80V Ground-Level Translator

# 1 Features

- AEC-Q100 qualified for automotive applications
- Supports DC shifts up to ±80V
- AC Noise Rejection of 140V<sub>PP</sub> up to 1MHz
- CMTI of 250V/µs
- Low Prop Delay (<5ns) and Ch-Ch Skew (<0.20ns)
- Greater than 250Mbps
- Low power consumption (0.8mA per channel at 1Mbps, 1.8V)
- Fully configurable dual-rail design allows each port to operate from 1.71V to 5.5V
- 4, 2, 1 channel devices with multiple configurations will be available
- Two device variants:
  - TXG8020-Q1: 2 forward
  - TXG8021-Q1: 1 forward, 1 reverse
- Supports V<sub>CC</sub> disconnect feature (I/Os are forced into high-Z)
- Schmitt-trigger inputs allows for slow and noisy signals
- Inputs with integrated static pull-down resistors prevent channels from floating
- Operating temperature from –40°C to +125°C
- Latch-up performance exceeds 100mA per JESD 78, class II
  - ESD protection exceeds JESD 22
  - 4000V human-body model
  - 500V charged-device model
- Package options provided:
  - DSG (WSON-8)
  - DDF (SOT-8)
  - D (SOIC-8)



# 2 Applications

- Electric Power Steering
- Vehicle Control Unit
- Automotive Display
- Head Unit and Digital Cockpit

# **3 Description**

The TXG802x-Q1 is a 2-bit, fixed direction, nongalvanic based voltage and ground-level translator that can support both logic-level shifting between 1.71V to 5.5V and ground-level shifting up to  $\pm 80V$ . Compared to traditional level shifters, the TXG802x-Q1 family can solve the challenges of voltage translation across different ground levels. The Simplified Diagram shows a common use case where DC shift occurs between GNDA to GNDB due to parasitic resistance or capacitance.

 $V_{CCA}$  is referenced to GNDA and  $V_{CCB}$  is referenced to GNDB. Ax pins are referenced to  $V_{CCA}$  logic level while Bx pins are referenced to  $V_{CCB}$  logic levels. Both A port and B port can accept voltages from 1.71V to 5.5V. The leakage between GNDA and GNDB is <2µA when  $V_{CC}$  to GND is shorted.

The TXG802x-Q1 device helps improve noise immunity and power sequencing across different ground domains while providing low power consumption, latency and channel-to-channel skew. It can supress noise levels of  $140V_{PP}$  up to 1MHz (Figure 7-4). This device can support multiple interfaces such as UART, GPIO, and JTAG.

#### Package Information

PART NUMBER	PACKAGE (1)	BODY SIZE (NOM)
TXG8020-Q1 TXG8021-Q1	DSG (WSON-8)	2.0mm × 2.00mm
	DDF (SOT-8)	2.90mm × 1.60mm
	D (SOIC-8)	4.90mm × 3.90mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.





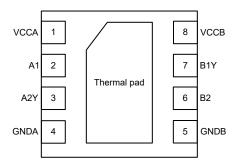
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# **4** Pin Configuration and Functions

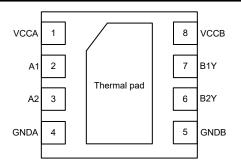


# Figure 4-1. TXGx021DSG Package 8-Pin WSON Top View

PI	PIN		DESCRIPTION
Name	TXGx021	I/O	BESCHIFTION
A1	2	I	Input A1. Referenced to V <sub>CCA</sub>
A2Y	3	0	Output A2. Referenced to V <sub>CCA</sub>
B1Y	7	0	Output B1. Referenced to V <sub>CCB</sub>
B2	6	I	Input B2. Referenced to V <sub>CCB</sub>
V <sub>CCA</sub>	1	—	A side supply voltage. 1.71V $\leq$ V <sub>CCA</sub> $\leq$ 5.5V
V <sub>CCB</sub>	8	—	B side supply voltage. $1.71V \le V_{CCB} \le 5.5V$
GNDA	4	—	Ground reference for V <sub>CCA</sub>
GNDB	5	—	Ground reference for V <sub>CCB</sub>
_	Thermal pad	—	Keep thermal pad floating.

## Table 4-1. TXGx021 DSG Pin Functions



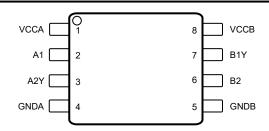


# Figure 4-2. TXGx020DSG Package 8-Pin WSON Top View

PIN		I/O	DESCRIPTION	
Name	TXGx020	1/0	DESCRIPTION	
A1	2	I	Input A1. Referenced to V <sub>CCA</sub>	
A2	3	I	Input A2. Referenced to V <sub>CCA</sub>	
B1Y	7	0	Output B1. Referenced to V <sub>CCB</sub>	
B2Y	6	0	Output B2. Referenced to V <sub>CCB</sub>	
V <sub>CCA</sub>	1	_	A side supply voltage. $1.71V \le V_{CCA} \le 5.5V$	
V <sub>CCB</sub>	8	—	B side supply voltage. $1.71V \le V_{CCB} \le 5.5V$	
GNDA	4	—	Ground reference for V <sub>CCA</sub>	
GNDB	5	_	Ground reference for V <sub>CCB</sub>	
—	Thermal pad	—	Keep thermal pad floating.	

#### Table 4-2. TXGx020 DSG Pin Functions



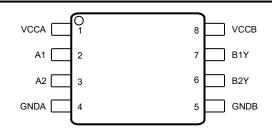


# Figure 4-3. TXGx021DDF 8-Pin SOT and TXGx021D 8-pin SOIC Top View

# Table 4-3. TXGx021 DDF and D Pin Functions

PI	PIN		DESCRIPTION
Name	TXGx021	I/O	DESCRIPTION
A1	2	I	Input A1. Referenced to V <sub>CCA</sub>
A2Y	3	0	Output A2. Referenced to V <sub>CCA</sub>
B1Y	7	0	Output B1. Referenced to V <sub>CCB</sub>
B2	6	I	Input B2. Referenced to V <sub>CCB</sub>
V <sub>CCA</sub>	1	—	A side supply voltage. $1.71V \le V_{CCA} \le 5.5V$
V <sub>CCB</sub>	8	—	B side supply voltage. $1.71V \le V_{CCB} \le 5.5V$
GNDA	4	_	Ground reference for V <sub>CCA</sub>
GNDB	5	—	Ground reference for V <sub>CCB</sub>





# Figure 4-4. TXGx020DDF 8-Pin SOT and TXGx020D 8-pin SOIC Top View

#### Table 4-4. TXGx020 DDF and D Pin Functions

PI	PIN		DESCRIPTION
Name	TXGx020	I/O	DESCRIPTION
A1	2	I	Input A1. Referenced to V <sub>CCA</sub>
A2	3	I	Input A2. Referenced to V <sub>CCA</sub>
B1Y	7	0	Output B1. Referenced to V <sub>CCB</sub>
B2Y	6	0	Output B2. Referenced to V <sub>CCB</sub>
V <sub>CCA</sub>	1	_	A side supply voltage. $1.71V \le V_{CCA} \le 5.5V$
V <sub>CCB</sub>	8	_	B side supply voltage. $1.71V \le V_{CCB} \le 5.5V$
GNDA	4	_	Ground reference for V <sub>CCA</sub>
GNDB	5		Ground reference for V <sub>CCB</sub>



# **5** Specifications

## 5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

			MIN	MAX	UNIT	
V <sub>CCA</sub> to V <sub>GNDA</sub>	Supply voltage A to Ground voltage A	-0.5	6.5	V		
V <sub>CCB</sub> to V <sub>GNDB</sub>	Supply voltage B to Ground voltage B		-0.5	6.5	V	
V <sub>GNDA</sub> to V <sub>GNDB</sub>	Voltage between GNDA and GNDB	Voltage between GNDA and GNDB	-82	82	V	
M.	Input Voltage <sup>(2)</sup>	I/O Ports (A Port) to V <sub>GNDA</sub>	-0.5	6.5	V	
V <sub>1</sub>	input voltage	I/O Ports (B Port) to V <sub>GNDB</sub>	-0.5	6.5	v	
VI	Input Voltage <sup>(2)</sup>	OE	-0.5	6.5	V	
. <i>.</i>	Voltage applied to any output in the high-impedance or power-off	A Port to V <sub>GNDA</sub>	-0.5	6.5	v	
V <sub>O</sub>	state <sup>(2)</sup>	B Port to V <sub>GNDB</sub>	-0.5	6.5		
\/	Value as emplied to environment in the binds as low state $\binom{2}{3}$	A Port to V <sub>GNDA</sub>	-0.5	V <sub>CCA</sub> + 0.5	- V	
Vo	Voltage applied to any output in the high or low state <sup>(2) (3)</sup>	B Port to V <sub>GNDB</sub>	-0.5	V <sub>CCB</sub> + 0.5		
I <sub>IK</sub>	Input clamp current	V <sub>1</sub> < 0	-20		mA	
I <sub>OK</sub>	Output clamp current V <sub>O</sub> < 0				mA	
I <sub>O</sub>	Continuous output current	-25	25	mA		
	Continuous current through V <sub>CC</sub> or GND	-100	100	mA		
Т <sub>ј</sub>	Junction Temperature		150	°C		
T <sub>stg</sub>	Storage temperature	-65	150	°C		

(1) Stresses beyond those listed under Section 5.1 may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Section 5.3 Exposure beyond the limits listed in Section 5.3 may affect device reliability.

(2) The input voltage and output negative-voltage ratings may be exceeded if the input and output current ratings are observed.

(3) The output positive-voltage rating may be exceeded up to 6.5V maximum if the output current rating is observed.

# 5.2 ESD Ratings

			VALUE	UNIT
V	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2500	V
V <sub>(ESD)</sub>	Electrostatic discriarge	Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup>	±500	v

(1) JEDEC document JEP155 states that 500V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250V CDM allows safe manufacturing with a standard ESD control process.



# **5.3 Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted) (1) (2) (3)

			MIN	TYP MAX	UNIT
V <sub>CCA</sub>	Supply voltage A - Relative to GNDA	1.71	5.5	V	
V <sub>CCB</sub>	Supply voltage B - Relative to GNDB		1.71	5.5	V
V <sub>GNDA</sub> to V <sub>GNDB</sub>	Voltage between GNDA and GNDB		-80	80	V
		V <sub>CCO</sub> = 1.71V	-4.5		- mA
	High-level output current	V <sub>CCO</sub> = 2.3V	-8		
I <sub>OH</sub>		V <sub>CCO</sub> = 3V	-10		
		V <sub>CCO</sub> = 4.5V	-12		
	Low-level output current	V <sub>CCO</sub> = 1.71V		4.5	mA
		V <sub>CCO</sub> = 2.3V		8	
I <sub>OL</sub>		V <sub>CCO</sub> = 3V		10	
		V <sub>CCO</sub> = 4.5V		12	
VI	Input voltage - Relative to GNDA		0	5.5	V
Vo	Output voltage - Relative to GNDB		0	V <sub>cco</sub>	V
T <sub>A</sub>	Operating free-air temperature	-40	125	°C	

(1)  $V_{CCI}$  is the  $V_{CC}$  associated with the input port.

(2)  $V_{CCO}$  is the  $V_{CC}$  associated with the output port. (3) All control inputs and data I/Os of this device ha

All control inputs and data I/Os of this device have weak pulldowns to ensure the line is not floating when undefined external to the device. The input leakage from these weak pulldowns is defined by the I<sub>I</sub> specification indicated under Section 5.4.



# **5.4 Electrical Characteristics**

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup> <sup>(2)</sup>

					Operating free-	air temperature (T <sub>A</sub> )	
	PARAMETER	TEST CONDITIONS	V <sub>CCA</sub>	V <sub>CCB</sub>	-40°C	C to 125°C	UNIT
					MIN	TYP MAX	
		I <sub>OH</sub> = -4.5mA	1.71V	1.71V	1.5		
V	High-level output voltage <sup>(3)</sup>	I <sub>OH</sub> = -8mA	2.3V	2.3V	2.0		V
V <sub>OH</sub>		I <sub>OH</sub> = -10mA	3V	3V	2.7		v
		I <sub>OH</sub> = -12mA	4.5V	4.5V	4.1		
		I <sub>OL</sub> = 4.5mA	1.71V	1.71V		0.16	
N/	1 (4)	I <sub>OL</sub> = 8mA	2.3V	2.3V		0.27	N/
V <sub>OL</sub>	Low-level output voltage <sup>(4)</sup>	I <sub>OL</sub> = 10mA	3V	3V		0.34	V
		I <sub>OL</sub> = 12mA	4.5V	4.5V		0.41	
			1.71V	1.71V		1.11	
		Data Inputs	2.3V	2.3V		1.40	V
V <sub>T+</sub>	Positive-going input- threshold voltage	(Ax, Bx) (Referenced to V <sub>CCI</sub> )	3V	3V		1.73	
			4.5V	4.5V		2.45	
			5.5V	5.5V		3.0	
			1.71V	1.71V	0.56		V
		Data Inputs	2.3V	2.3V	0.80		
V <sub>T-</sub>	Negative-going input- threshold voltage	(Ax, Bx)	3V	3V	1.15		
		(Referenced to V <sub>CCI</sub> )	4.5V	4.5V	1.59		
			5.5V	5.5V	2.0		
			1.71V	1.71V	0.3	0.55	
	Input-threshold hysteresis	Data Inputs	2.3V	2.3V	0.36	0.60	v
$\Delta V_T$	$(V_{T+} - V_{T-})$	(Ax, Bx) (Referenced to V <sub>CCI</sub> )	3V	3V	0.38	0.54	
			4.5V	4.5V	0.41	0.86	V
ΔV <sub>T</sub>	Input-threshold hysteresis $(V_{T+} - V_{T-})$	Data Inputs (Ax, Bx) (Referenced to V <sub>CCI</sub> )	5.5V	5.5V	0.40	0.96	V
I <sub>I</sub>	Input leakage current	Data Inputs (Ax, Bx) $V_I = V_{CCI}$ or GND	1.71V – 5.5V	1.71V – 5.5V	0.2	1.6	μΑ
	Floating supply Partial	A Port or B Port	Floating <sup>(5)</sup>	0V - 5.5V	0.26	1.55	
l <sub>off-float</sub>	power down current	$V_{I} = V_{CC}$	0V - 5.5V	Floating <sup>(5)</sup>	0.26	1.55	μA

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over operating free-air temperature range (unless otherwise noted)<sup>(1) (2)</sup>

					Operating free	air tempera	ture (T <sub>A</sub> )	
	PARAMETER	TEST CONDITIONS	V <sub>CCA</sub>	V <sub>CCB</sub>	-40°	C to 125°C		UNIT
					MIN	TYP	MAX	
Ci	Control Input Capacitance	$V_{I} = 3.3 V \text{ or } V_{GNDA}$	3.3V	3.3V			2	pF
C <sub>io</sub>	Data I/O Capacitance	V <sub>O</sub> = 1.71V DC +1MHz -16dBm sine wave	3.3V	3.3V	1.3		2.6	pF
C	Con botucon groundo	All channels combined (V <sub>CC</sub> both sides are powered on)					46	pF
C <sub>GND</sub>	Cap between grounds	All channels combined (V <sub>CC</sub> to GND shorted)					53	pF
		All channels combined (V <sub>CC</sub> both sides are powered on and inputs are all low)	1.71V – 5.5V	1.71V – 5.5V			1.8	μA
Leakage	Current Leakage between GndA to GndB	All channels combined (V <sub>CC</sub> both sides are powered on and inputs are all high)	1.71V – 5.5V	1.71V – 5.5V			32	μA
		All channels combined (V <sub>CC</sub> to GND shorted)	1.71V – 5.5V	1.71V – 5.5V			1.8	μA
СМТІ	Common Mode Transient Immunity	Input toggling at 100Mbps Ground shift up to 80V	1.71V – 5.5V	1.71V – 5.5V		250		V/µs
TXG8021					·		·	
			1.71V – 5.5V	1.71V – 5.5V	300		747	
		$V_{I} = V_{CCI}$ or GND $I_{O} = 0$	0V	5.5V	-2		12.5	
I <sub>CCA</sub>	V <sub>CCA</sub> supply current		5.5V	0V	349		589	μA
		V <sub>I</sub> = GND I <sub>O</sub> = 0	5.5V	Floating <sup>(5)</sup>	347		577	
			1.71V – 5.5V	1.71V – 5.5V	497		1077	
		$V_I = V_{CCI}$ or GND $I_O = 0$	0V	5.5V	546		919	
I <sub>CCB</sub>	V <sub>CCB</sub> supply current		5.5V	0V	-2		24.5	μΑ
		$V_I = GND$ $I_O = 0$	Floating <sup>(5)</sup>	5.5V	548		919	



over operating free-air temperature range (unless otherwise noted)<sup>(1) (2)</sup>

					Operating free-ai	r temperature (T <sub>A</sub> )	
	PARAMETER	TEST CONDITIONS	V <sub>CCA</sub>	V <sub>CCB</sub>	-40°C 1	o 125°C	UNIT
					MIN	TYP MAX	
			1.8V	1.8V	0.7	1.6	
			2.5V	2.5V	0.8	1.6	0
		$V_{I} = V_{CCI}$	3.3V	3.3V	0.8	1.7	mA
	Owner Do Owner		5V	5V	0.8	1.9	
I <sub>CCA</sub> + I <sub>CCB</sub>	Supply Current - DC Signal		1.8V	1.8V	0.7	1.6	
			2.5V	2.5V	0.8	1.6	0
		$V_1 = GND$	3.3V	3.3V	0.8	1.7	mA
			5V	5V	0.8	1.9	
			1.8V	1.8V	0.9	1.6	
		All channels switching with square wave	2.5V	2.5V	0.9	1.6	
		clock input; CL = 15pF, 1Mbps	3.3V	3.3V	0.9	1.7	mA
			5V	5V	1.1	2	
			1.8V	1.8V	4.6	6.3	
		All channels switching with square wave	2.5V	2.5V	5.5	7.3	
I <sub>CCA</sub> + I <sub>CCB</sub>	Supply Current - AC Signal	clock input; CL = 15pF, 50Mbps	3.3V	3.3V	6.8	8.2	mA
			5V	5V	8.7	10.7	
			1.8V	1.8V	8.5	10.6	
		All channels switching with square wave	2.5V	2.5V	10	13	0
		clock input; CL = 15pF, 100Mbps	3.3V	3.3V	12	14.7	mA
			5V	5V	16.6	20.2	
TXG8020							
			1.71V – 5.5V	1.71V – 5.5V	299	602	μA
		$V_I = V_{CCI}$ or GND $I_O = 0$	0V	5.5V	-2.5	1.2	μA
I <sub>CCA</sub>	V <sub>CCA</sub> supply current		5.5V	0V	302	602	μA
		V <sub>I</sub> = GND I <sub>O</sub> = 0	5.5V	Floating <sup>(5)</sup>	299	577	μA
			1.71V – 5.5V	1.71V – 5.5V	504	1225	μA
		$V_I = V_{CCI}$ or GND $I_O = 0$	0V	5.5V	486	906	μA
I <sub>CCB</sub>	V <sub>CCB</sub> supply current		5.5V	0V	-2	24.5	μA
		$V_{I} = GND$ $I_{O} = 0$	Floating <sup>(5)</sup>	5.5V	486	906	μA

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over operating free-air temperature range (unless otherwise noted)<sup>(1) (2)</sup>

					Operating free-	air temperature	(T <sub>A</sub> )	
	PARAMETER	TEST CONDITIONS	V <sub>CCA</sub>	V <sub>CCB</sub>	-40°0	C to 125°C		UNIT
	Supply Current - DC Sign				MIN	TYP M	IAX	
			1.8V	1.8V	0.7		1.6	mA
			2.5V	2.5V	0.8		1.6	mA
		V <sub>I</sub> = V <sub>CCI</sub>	3.3V	3.3V	0.8		1.7	mA
	Cumply Cumpat, DC Cinnel		5V	5V	0.8		1.9	mA
I <sub>CCA</sub> + I <sub>CCB</sub>	Supply Current - DC Signal		1.8V	1.8V	0.7		1.6	mA
			2.5V	2.5V	0.8		1.6	mA
		V <sub>I</sub> = GND	3.3V	3.3V	0.8		1.7	mA
			5V	5V	0.8		1.9	mA
			1.8V	1.8V	0.9		1.6	mA
		All channels switching with square wave	2.5V	2.5V	0.9		1.6	mA
		clock input; CL = 15pF, 1Mbps	3.3V	3.3V	0.9		1.7	mA
			5V	5V	1.1		2	mA
			1.8V	1.8V	4.5		6.3	mA
1 - 1	Supply Current - AC Signal	All channels switching with square wave	2.5V	2.5V	5.5		7.3	mA
I <sub>CCA</sub> + I <sub>CCB</sub>	Supply Current - AC Signal	clock input; CL = 15pF, 50Mbps	3.3V	3.3V	6.3		8	mA
			5V	5V	8.4		10.7	mA
			1.8V	1.8V	8.5		10.7	mA
		All channels switching with square wave	2.5V	2.5V	10		13	mA
		clock input; CL = 15pF, 100Mbps	3.3V	3.3V	12		14.7	mA
			5V	5V	16.6	:	20.2	mA
	Positive-Going	A Supply	1.71V – 5.5V				1.61	V
V <sub>UVLO+</sub>	Undervoltage Lockout Voltage	B Supply		1.71V – 5.5V			1.61	V
	Negative-Going	A Supply	1.71V – 5.5V		1.33			V
V <sub>UVLO-</sub>	Undervoltage Lockout Voltage	B Supply		1.71V – 5.5V	1.33			V
M	Undervoltage Lockout	A Supply	1.71V – 5.5V		0.12	0.15		V
V <sub>UVLO_Hys</sub>	Hysteresis	B Supply		1.71V – 5.5V	0.12	0.15		V

(1)

 $V_{CCI}$  is the  $V_{CC}$  associated with the input port and referenced to  $GND_A$   $V_{CCO}$  is the  $V_{CC}$  associated with the output port and referenced to  $GND_B$ (2)

(3) Tested at  $V_I = V_{T+(MAX)}$ 

Tested at  $V_I = V_{T-(MIN)}$ (4)



(5) Floating is defined as a node that is both not actively driven by an external device and has leakage not exceeding 10nA

# 5.5 Switching Characteristics, $V_{CCA} = 1.8 \pm 0.15V$

										B-Port S	Supply	Voltage	(V <sub>CCB</sub> )					
	PARAMETER	TEST CONDITIONS	FROM	то	TEMPERATURE	1.3	8 ± 0.15	v	2	.5 ± 0.2V	'	3	.3 ± 0.3\	/	5	.0 ± 0.5\	/	UNIT
						MIN	TYP	MAX	MIN	TYP	MAX	MIN			MIN	TYP	MAX	
			A	В	-40°C to 85°C	2.8		7.3	2.8		7.4	2.8		7.5	2.9		7.8	
+	Propagation delay	1Mbps all 4 channels	A	В	-40°C to 125°C	2.8		7.6	2.8		7.8	2.8		7.9	2.9		8.3	20
t <sub>pd</sub>	Flopagation delay	toggling	В	А	-40°C to 85°C	2.8		7.3	2.7		5.7	2.6		5.1	2.6		4.8	ns
			В	A	-40°C to 125°C	2.8		7.7	2.7		6	2.6		5.3	2.6		5.1	
			A	В	-40°C to 85°C	0.7		1.5	0.6		1.5	0.5		1.4	0.5		1.2	
PWD	Pulse width		A	В	-40°C to 125°C	0.7		1.5	0.6		1.5	0.5		1.4	0.5		1.2	20
PVU	distortion	t <sub>phi</sub> - t <sub>pih</sub>	В	А	-40°C to 85°C	0.7		1.5	0.6		1.5	0.5		1.4	0.5		1.2	ns
			В	A	-40°C to 125°C	0.7		1.5	0.6		1.5	0.5		1.4	0.4		1.2	
			A	В	-40°C to 85°C	0.5		1.3	0.5		1.35	0.5		1.4	0.5		1.6	
	Output signal rise		A	В	-40°C to 125°C	0.5		1.3	0.5		1.4	0.5		1.4	0.5		1.7	20
t <sub>r</sub>	time		В	A	-40°C to 85°C	0.5		1.2	0.5		1.3	0.5		1.2	0.5		1.3	ns
			В	A	-40°C to 125°C	0.5		1.3	0.5		1.4	0.5		1.3	0.5		1.3	
			A	В	-40°C to 85°C	0.4		1.3	0.4		1.3	0.4		1.5	0.5		1.7	
tf	Output signal fall		A	В	-40°C to 125°C	0.4		1.5	0.4		1.5	0.4		1.6	0.5		2	ns
u	time		В	A	-40°C to 85°C	0.4		1.3	0.4		1.4	0.4		1.3	0.4		1.3	115
			В	A	-40°C to 125°C	0.4		1.4	0.4		1.45	0.4		1.4	0.4		1.35	
	Default output delay	Measured from			-40°C to 85°C	6.1		10.6	6.1		10.4	6		10.3	5.9		9.9	
t <sub>DO</sub>	time from input power loss	the time V <sub>CC</sub> goes below 1.36V			-40°C to 125°C	6.1		10.6	6.1		10.4	6		10.3	5.9		9.9	μs
+	Time from ULVO to				-40°C to 85°C	21.1		64.3	4.3		69.1	4.5		76.6	55.3		99.4	110
t <sub>PU</sub>	valid output data				-40°C to 125°C	19.9		64.3	4.3		69.1	4.5		76.6	53.9		99.4	μs



# 5.6 Switching Characteristics, $V_{CCA} = 2.5 \pm 0.2V$

										B-Port	Supply	Voltage	(V <sub>CCB</sub> )					
	PARAMETER	TEST CONDITIONS	FROM	то	TEMPERATURE	1.	8 ± 0.15	v	2.	.5 ± 0.2\	/	3	.3 ± 0.3\	/	5	.0 ± 0.5V	'	UNIT
						MIN	TYP	MAX	MIN	TYP	MAX			MAX	MIN	TYP	MAX	
			A	В	-40°C to 85°C	2.7		5.7	2.7		5.8	2.7		5.9	2.8		6.3	
	Propagation delay	1Mbps all 4 channels	А	В	-40°C to 125°C	2.7		6	2.7		6.1	2.7		6.2	2.8		6.6	ns
t <sub>pd</sub>	Propagation delay	toggling	В	A	-40°C to 85°C	2.8		7.4	2.7		5.8	2.6		5.1	2.6		4.9	115
			В	А	-40°C to 125°C	2.8		7.7	2.7		6.1	2.6		5.5	2.6		5.2	
			A	В	-40°C to 85°C	0.1		1	0.1		0.8	0		0.7	-0.14		0.6	
PWD	Pulse width	14 4 1	А	В	-40°C to 125°C	0.1		1	0.1		0.8	0		0.7	-0.15		0.6	
PVU	distortion	t <sub>phl</sub> - t <sub>plh</sub>	В	А	-40°C to 85°C	0.1		1	0.1		0.8	0		0.7	-0.14		0.6	ns
			В	А	-40°C to 125°C	0.1		1	0.1		0.8	0		0.7	-0.15		0.6	
			A	В	-40°C to 85°C	0.5		1.3	0.5		1.3	0.5		1.4	0.5		1.6	
	Output signal rise		A	В	-40°C to 125°C	0.5		1.3	0.5		1.4	0.5		1.4	0.5		1.7	
ι <sub>r</sub>	time		В	A	-40°C to 85°C	0.5		1.3	0.4		1.3	0.5		1.3	0.4		1.3	ns
			В	А	-40°C to 125°C	0.5		1.3	0.4		1.3	0.5		1.3	0.4		1.4	
			A	В	-40°C to 85°C	0.4		1.4	0.4		1.3	0.4		1.5	0.5		1.7	
tf	Output signal fall		A	В	-40°C to 125°C	0.4		1.4	0.4		1.5	0.4		1.6	0.5		2	
u	time		В	A	-40°C to 85°C	0.4		1.3	0.4		1.3	0.4		1.35	0.4		1.3	ns
			В	A	-40°C to 125°C	0.4		1.5	0.4		1.5	0.4		1.4	0.4		1.5	
	Default output delay	Measured from			-40°C to 85°C	6.1		10.6	6.1		10.4	5.6		10.4	5.4		9.9	
t <sub>DO</sub>	time from input power loss	the time V <sub>CC</sub> goes below 1.36V			-40°C to 125°C	6.1		10.6	6.1		10.4	5.6		10.4	5.4		9.9	μs
+	Time from ULVO to				-40°C to 85°C	21.1		64.3	4.3		69.1	4.5		76.6	55.3		99.4	
t <sub>PU</sub>	valid output data				-40°C to 125°C	19.9		64.3	4.3		69.1	4.5		76.6	53.9		99.4	μs



# 5.7 Switching Characteristics, $V_{CCA}$ = 3.3 ± 0.3V

										B-Port	Supply	Voltage	(V <sub>CCB</sub> )					
	PARAMETER	TEST CONDITIONS	FROM	то	TEMPERATURE	1.	8 ± 0.15	V	2	.5 ± 0.2	/	3	.3 ± 0.3\	/	5	.0 ± 0.5\	/	UNIT
						MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
			A	В	-40°C to 85°C	2.6		5.1	2.7		5.2	2.7		5.3	2.8		5.8	
•	Dranagation dalou	1Mbps all 4 channels	A	В	-40°C to 125°C	2.6		5.3	2.7		5.5	2.7		5.7	2.8		6.3	
t <sub>pd</sub>	Propagation delay	toggling	В	А	-40°C to 85°C	2.8		7.5	2.7		5.9	2.7		5.3	2.6		5.1	ns
			В	А	-40°C to 125°C	2.8		7.9	2.7		6.2	2.7		5.7	2.6		5.4	
			A	В	-40°C to 85°C	-0.03		0.6	-0.09		0.5	-0.13		0.5	-0.3		0.4	
PWD	Pulse width		A	В	-40°C to 125°C	-0.11		0.6	-0.13		0.5	-0.18		0.5	-0.4		0.4	
PVVD	distortion	t <sub>phl</sub> - t <sub>plh</sub>	В	A	-40°C to 85°C	-0.03		0.6	-0.09		0.5	-0.13		0.5	-0.3		0.4	ns
			В	A	-40°C to 125°C	-0.11		0.6	-0.13		0.5	-0.18		0.5	-0.4		0.4	
			A	В	-40°C to 85°C	0.5		1.3	0.5		1.3	0.5		1.4	0.5		1.6	
	Output signal rise		A	В	-40°C to 125°C	0.5		1.3	0.5		1.4	0.5		1.4	0.5		1.6	
t <sub>r</sub>	time		В	A	-40°C to 85°C	0.5		1.3	0.5		1.3	0.5		1.4	0.5		1.4	ns
			В	A	-40°C to 125°C	0.5		1.35	0.5		1.4	0.5		1.4	0.5		1.5	
			A	В	-40°C to 85°C	0.4		1.3	0.4		1.4	0.4		1.5	0.5		1.7	
	Output signal fall		A	В	-40°C to 125°C	0.4		1.5	0.4		1.6	0.4		1.6	0.5		2	
tf	time		В	А	-40°C to 85°C	0.4		1.4	0.4		1.4	0.4		1.4	0.4		1.4	ns
			В	А	-40°C to 125°C	0.4		1.7	0.4		1.6	0.4		1.6	0.4		1.7	
	Default output delay	Measured from			-40°C to 85°C	6		10.6	5.8		10.4	5.8		10.3	5.8		10	μs
t <sub>DO</sub>	time from input power loss	the time V <sub>CC</sub> goes below 1.36V			-40°C to 125°C	6		10.6	5.8		10.4	5.8		10.3	5.8		10	μs
+	Time from ULVO to				-40°C to 85°C	21.1		64.3	4.3		69.1	4.5		76.6	57.8		99.4	μs
t <sub>PU</sub>	valid output data				-40°C to 125°C	19.9		64.3	4.3		69.1	4.5		76.6	53.9		99.4	μs

#### **TXG8020-Q1, TXG8021-Q1** SCES992 – MAY 2025



# 5.8 Switching Characteristics, $V_{CCA} = 5.0 \pm 0.5V$

										B-Port	Supply	Voltage	(V <sub>CCB</sub> )					
	PARAMETER	TEST CONDITIONS	FROM	то	TEMPERATURE	1.	8 ± 0.15	v	2.	.5 ± 0.2\	/	3	.3 ± 0.3\	/	5	.0 ± 0.5V	'	UNIT
						MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	
			A	В	-40°C to 85°C	2.6		4.8	2.6		5	2.7		5.1	2.8		5.6	
+	Propagation delay	1Mbps all 4 channels	A	В	-40°C to 125°C	2.6		5.1	2.6		5.3	2.7		5.4	2.8		5.9	ns
t <sub>pd</sub>	Propagation delay	toggling	В	A	-40°C to 85°C	3		7.9	2.8		6.2	2.7		5.9	2.7		5.6	115
			В	А	-40°C to 125°C	3		8.4	2.8		6.6	2.7		6.2	2.7		6	
			А	В	-40°C to 85°C	-0.22		0.4	-0.27		0.3	-0.32		0.3	-0.50		0.2	
PWD	Pulse width	14 4 1	A	В	-40°C to 125°C	-0.33		0.4	-0.37		0.3	-0.42		0.3	-0.60		0.2	
PVU	distortion	t <sub>phi</sub> - t <sub>pih</sub>	В	А	-40°C to 85°C	-0.22		0.4	-0.27		0.3	-0.32		0.3	-0.5		0.2	ns
			В	А	-40°C to 125°C	-0.33		0.4	-0.37		0.3	-0.42		0.3	-0.60		0.2	
			A	В	-40°C to 85°C	0.5		1.3	0.5		1.3	0.5		1.4	0.5		1.6	
	Output signal rise		A	В	-40°C to 125°C	0.5		1.3	0.5		1.4	0.5		1.4	0.5		1.6	
ι <sub>r</sub>	time		В	A	-40°C to 85°C	0.6		1.6	0.6		1.6	0.6		1.6	0.5		1.6	ns
			В	А	-40°C to 125°C	0.6		1.75	0.6		1.7	0.6		1.7	0.5		1.6	
			A	В	-40°C to 85°C	0.4		1.3	0.4		1.4	0.4		1.5	0.5		1.7	
tf	Output signal fall		A	В	-40°C to 125°C	0.4		1.4	0.4		1.5	0.4		1.6	0.5		2	
u	time		В	A	-40°C to 85°C	0.4		1.8	0.5		1.8	0.4		1.8	0.4		1.8	ns
			В	A	-40°C to 125°C	0.4		2.5	0.5		2	0.4		2	0.4		2	
	Default output delay	Measured from			-40°C to 85°C	5.5		10.7	5.6		10.5	5.7		10.6	5.9		10	
t <sub>DO</sub>	time from input power loss	the time V <sub>CC</sub> goes below 1.36V			-40°C to 125°C	5.5		10.7	5.6		10.5	5.7		10.6	5.9		10	μs
+	Time from ULVO to				-40°C to 85°C	21.1		64.3	4.3		69.1	4.5		76.6	55.3		99.4	
t <sub>PU</sub>	valid output data				-40°C to 125°C	19.9		64.3	4.3		69.1	4.5		76.6	53.9		99.4	μs



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# 5.9 Switching Characteristics: T<sub>sk</sub>, T<sub>MAX</sub>

over operating free-air temperature range (unless otherwise noted)

						ting free-air erature (T <sub>A</sub> )		
PARAMETER	TEST CON	DITIONS	V <sub>CCI</sub>	V <sub>cco</sub>	-40°0	C to 125°C		UNIT
					MIN	TYP	MAX	
	50% Duty Cycle Input		1.65V - 1.95V	1.65V - 1.95V	264			
T <sub>MAX</sub> - Maximum Data Rate	One channel switching	No Translation	2.3V - 2.7V	2.3V - 2.7V	220			Mhno
I MAX - MAXIMUM Data Rate	20% of pulse > $0.7*V_{CCO}$		3.0V - 3.6V	3.0V - 3.6V	220			Mbps
	20% of pulse < $0.3^*V_{CCO}$		4.5V - 5.5V	4.5V - 5.5V	176			
			1.65V - 1.95V	2.3V - 2.7V	264			
	50% Duty Cycle Input		1.65V - 1.95V	3.0V - 3.6V	264			
T Maximum Data Data	One channel switching	Lin Translation	1.65V - 1.95V	4.5V - 5.5V	264			Mana
T <sub>MAX</sub> - Maximum Data Rate	20% of pulse > $0.7*V_{CCO}$	Up Translation	2.3V - 2.7V	3.0V - 3.6V	220			Mbps
	20% of pulse < $0.3^*V_{CCO}$		2.3V - 2.7V	4.5V - 5.5V	220			
			3.0V - 3.6V	4.5V - 5.5V	176			
			2.3V - 2.7V	1.65V - 1.95V	264			
	EQU/ Duty Cycle Input		3.0V - 3.6V	2.3V - 2.7V	220			
T Maximum Data Data	50% Duty Cycle Input One channel switching	Davum Translatian	3.0V - 3.6V	1.65V - 1.95V	220			Mana
T <sub>MAX</sub> - Maximum Data Rate	20% of pulse > $0.7*V_{CCO}$	Down Translation	4.5V - 5.5V	3.0V - 3.6V	176			Mbps
	20% of pulse < $0.3^*V_{CCO}$		4.5 V - 5.5 V	1.65 V - 1.95 V	220			
			4.5V - 5.5V	1.65V - 1.95V	220			
	Timing alkow batwaan any		1.65V - 1.95V	1.65V - 1.95V			0.02	
	Timing skew between any switching outputs on the	No Translation	2.3V - 2.7V	2.3V - 2.7V			0.02	
t <sub>sk</sub> - Output skew	rising or falling edge (same	No Translation	3.0V - 3.6V	3.0V - 3.6V			0.02	ns
	direction channels)		4.5V - 5.5V	4.5V - 5.5V			0.04	
			1.65V - 1.95V	2.3V - 2.7V			0.02	
	Timing alkow batwaan area		1.65V - 1.95V	3.0V - 3.6V			0.02	
switchi	Timing skew between any switching outputs on the		1.65V - 1.95V	4.5V - 5.5V			0.02	
t <sub>sk</sub> - Output skew	rising or falling edge (same	Up Translation	2.3V - 2.7V	3.0V - 3.6V			0.02	ns
	direction channels)		2.3V - 2.7V	4.5V - 5.5V			0.02	
			3.0V - 3.6V	4.5V - 5.5V			0.02	

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over operating free-air temperature range (unless otherwise noted)

						ing free-a rature (T		
PARAMETER	TEST CONDITIONS V <sub>CCI</sub> V <sub>CCO</sub>	V <sub>cco</sub>	-40°C	to 125°C	;	UNIT		
					MIN	TYP	MAX	
			2.3V - 2.7V	1.65 V - 1.95 V			0.02	
	Timing allow batwoon any		3.0V - 3.6V	2.3V - 2.7V			0.02	
	Timing skew between any switching outputs on the	Down Translation	3.0V - 3.6V	1.65V - 1.95V			0.02	20
t <sub>sk</sub> - Output skew	rising or falling edge (same		4.5V - 5.5V	3.0V - 3.6V			0.04	ns
	direction channels)		4.5V - 5.5V	2.3V - 2.7V			0.04	
			4.5V - 5.5V	1.65V - 1.95V			0.04	

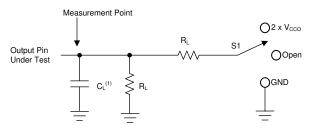


# **6** Parameter Measurement Information

# 6.1 Load Circuit and Voltage Waveforms

Unless otherwise noted, generators supply all input pulses that have the following characteristics:

- f = 1MHz
- $Z_{O} = 50\Omega$  $\Delta t/\Delta V \le 1$ ns/V

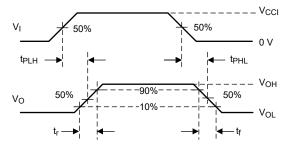


C<sub>L</sub> includes probe and jig capacitance. Α.

Figure 6-1. Load Circuit

**Table 6-1. Load Circuit Conditions** 

	Parameter	V <sub>cco</sub>	RL	CL	S <sub>1</sub>	V <sub>TP</sub>
t <sub>pd</sub>	Propagation (delay) time	1.71V – 5.5V	10kΩ	15pF	Open	N/A

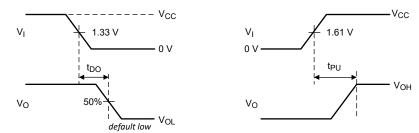


1. V<sub>CCI</sub> is the supply pin associated with the input port.

 $V_{\text{OH}}$  and  $V_{\text{OL}}$  are typical output voltage levels that occur with specified R<sub>L</sub>, C<sub>L</sub>, and S<sub>1</sub> 2.

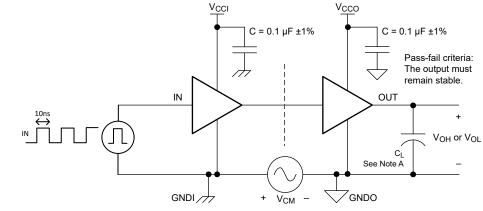
## Figure 6-2. Switching Characteristics Voltage Waveforms





- 1.  $V_{CCI}$  is the supply pin associated with the input port.
- 2.  $V_{OH}$  and  $V_{OL}$  are typical output voltage levels that occur with specified R<sub>L</sub>, C<sub>L</sub>, and S<sub>1</sub>

## Figure 6-3. Default Output Delay Time & Time from UVLO to Valid Output Voltage Waveform



1.  $C_L = 15pF$  and includes instrumentation and fixture capacitance within ±20%.

#### Figure 6-4. Common-Mode Transient Immunity Test Circuit



# 7 Detailed Description

# 7.1 Overview

The TXG802x-Q1 is a 2-bit ground-level translator that uses two individually configurable power-supply rails which allows it to translate across two different power domains. The device is operational with  $V_{CCA}$  and  $V_{CCB}$  supplies as low as 1.71V and as high as 5.5V. The A port is designed to track  $V_{CCA}$  and the B port is designed to track  $V_{CCB}$ . In addition to I/O level shifting, this translator can support a difference of -80V to +80V between GNDA and GNDB.  $V_{CCA}$  is referenced to GNDA and  $V_{CCB}$  is referenced to GNDA.

The TXG802x-Q1 device is designed for asynchronous communication between data buses, and transmits data with fixed direction from the A bus to the B bus on some channels and from the B bus to the A bus on the remaining channels.

The  $V_{CC}$  disconnect feature ensures that if  $V_{CC}$  is disconnected with the complementary supply within recommended operating conditions, outputs are disabled and set to the high-impedance state while the supply current is maintained. The I<sub>off-float</sub> circuitry ensures that no excessive current is drawn from or sourced into an input or output while the supply is floating.

Glitch-free power supply sequencing allows either supply rail to be powered on or off in any order while providing robust power sequencing performance.

## 7.2 Functional Block Diagram

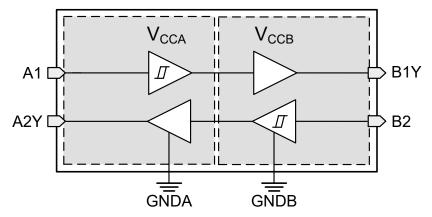


Figure 7-1. TXG8021-Q1 Functional Block Diagram



# 7.3 Feature Description

## 7.3.1 CMOS Schmitt-Trigger Inputs with Integrated Pulldowns

Standard CMOS inputs are high impedance and are typically modeled as a resistor in parallel with the input capacitance given in the Section 5.4. The worst case resistance is calculated with the maximum input voltage, given in the Section 5.1, and the maximum input leakage current, given in the Section 5.4, using ohm's law (R =  $V \div I$ ).

The Schmitt-trigger input architecture provides hysteresis as defined by  $\Delta V_T$  in the Section 5.4, which makes this device extremely tolerant to slow or noisy inputs. Driving the inputs slowly will increase dynamic current consumption of the device. See Understanding Schmitt Triggers for additional information regarding Schmitt-trigger inputs.

#### 7.3.1.1 Inputs with Integrated Static Pull-Down Resistors

This device has  $5M\Omega$  typical integrated weak pull-downs for each input. This feature allows all inputs to be left floating without the concern for unstable outputs or increased current consumption. This also helps to reduce external component count for applications where not all channels are used or need to be fixed low. If an external pull-up is required, it should be no larger than  $1M\Omega$  to avoid contention with the  $5M\Omega$  internal pull-down.

#### 7.3.2 Balanced High-Drive CMOS Push-Pull Outputs

A balanced output allows the device to sink and source similar currents. The high drive capability of this device creates fast edges into light loads, so routing and load conditions should be considered to prevent ringing. Additionally, the outputs of this device are capable of driving larger currents than the device can sustain without being damaged. Section 5.1 defines the electrical and thermal limits that must be followed at all times.

#### 7.3.3 V<sub>CC</sub> Disconnect

The outputs for this device are disabled and enter a high-impedance state when either supply is left floating (disconnected), and with the complementary supply within recommended operating conditions. It is recommended that the inputs are kept low before floating (disconnecting) either supply.

The  $I_{CCx(floating)}$  in the Section 5.4 specifies the maximum supply current. The  $I_{off(float)}$  in the Section 5.4 specifies the maximum leakage into or out of any input or output pin on the device.

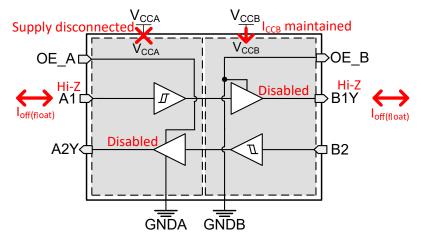


Figure 7-2. V<sub>CC</sub> Disconnect Feature

## 7.3.4 Over-Voltage Tolerant Inputs

Input signals to this device can be driven above the supply voltage so long as they remain below the maximum input voltage value specified in the *Section 5.3*.



#### 7.3.5 Glitch-Free Power Supply Sequencing

Either supply rail may be powered on or off in any order without producing a glitch on the inputs or outputs (that is, where the output erroneously transitions to  $V_{CC}$  when it should be held low or vice versa). Glitches of this nature can be misinterpreted by a peripheral as a valid data bit, which could trigger a false device reset of the peripheral, a false device configuration of the peripheral, or even a false data initialization by the peripheral.

#### 7.3.6 Negative Clamping Diodes

Figure 7-3 depicts the inputs and outputs to this device that have negative clamping diodes.

# Voltages beyond the values specified in the Section 5.1 table can cause damage to the device. The input negative-voltage and output voltage ratings may be exceeded if the input and output clamp-current ratings are observed.

CAUTION

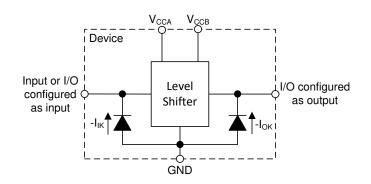


Figure 7-3. Electrical Placement of Clamping Diodes for Each Input and Output

## 7.3.7 Fully Configurable Dual-Rail Design

The V<sub>CCA</sub> and V<sub>CCB</sub> pins can be supplied at any voltage from 1.71V to 5.5V, making the device suitable for translating between any of the voltage nodes (1.8V, 2.5V, 3.3V, and 5.0V).

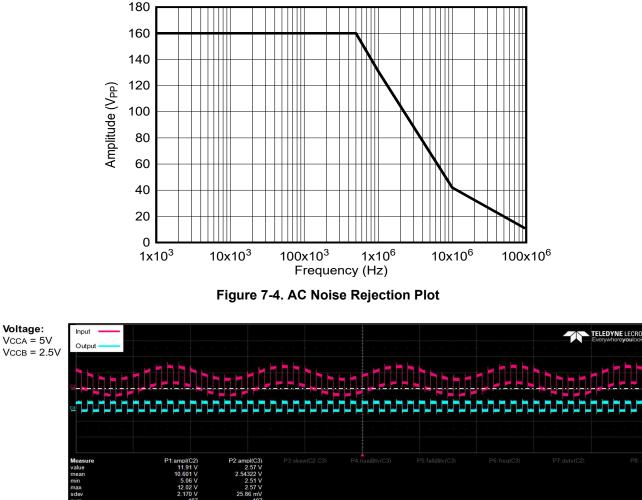
#### 7.3.8 Supports High-Speed Translation

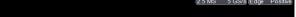
The TXG802x-Q1 device can support high data-rate applications. The translated signal data rate can be greater than 250Mbps when the signal is translated from 1.71V to 5.5V.



## 7.3.9 AC Noise Rejection

TXG802x-Q1 supports I/O voltage translation in environments with noisy grounds. The plot below illustrates the amount of noise that GNDA and GNDB can reject in terms peak-to-peak voltage over frequency without disrupting communication between two systems. As an example, Figure 7-5 below shows GNDA with a ground bounce of 2V<sub>PP</sub> at 10kHz but still effectively translating 5V to 2.5V without any degradation.





\*Note: Offset voltage on the output to show both signals side-by-side





# 7.4 Device Functional Modes

Table 7-1. Function Table						
Power Supply		Port Status				
VCCI	VCCO	Input	Output			
PU	PU	Н	н			
PU	PU	L	L			
PU	PU	Х	Hi-Z			
PU	PU	Open	L			
PD	PU	Х	L			
Х	PU	Х	High-Z			
Х	PU	Х	L			
Х	PD	Х	Undetermined			

#### In the table above: PU = Powered Up; PD = Powered Down; X = Irrelevant; H = High Level; L = Low Level; Open = Floating



# 8 Application and Implementation

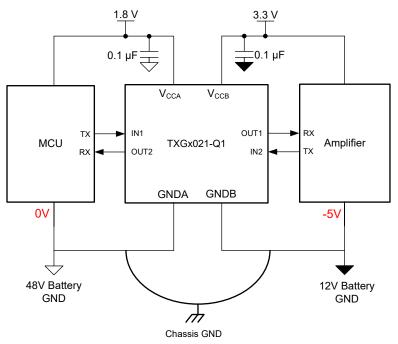
#### Note

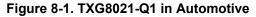
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

# 8.1 Application Information

The TXG802x-Q1 is used for level translation, enabling communication between devices or systems operating at different interface and ground voltages. The TXG802x-Q1 device is ideal for use in applications where a push-pull driver is connected to the data inputs. Figure 8-1 is an example of two systems that translate from 1.8V to 3.3V while also experiencing a ground shift of 5V. The ground shift occurs due to the parasitic resistance of the cable used to connect the 48V battery ground and 12V battery ground to the chassis of the car.

# 8.2 Typical Application





## 8.2.1 Design Requirements

Use the parameters listed in Table 8-1 for this design example.

#### Table 8-1. Design Parameters

DESIGN PARAMETERS	EXAMPLE VALUES		
Input voltage range	1.71V to 5.5V		
Output voltage range	1.71V to 5.5V		

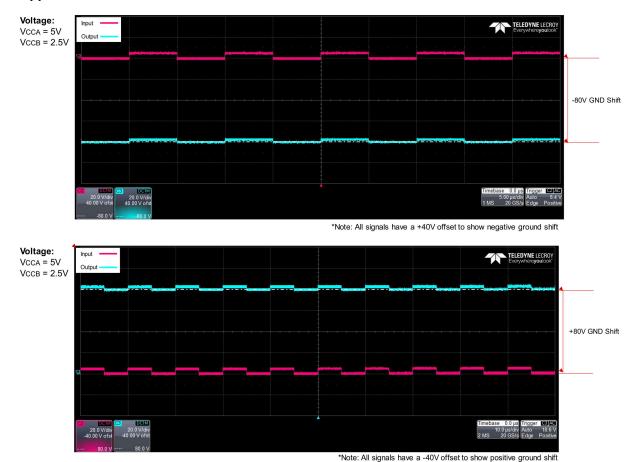
## 8.2.2 Detailed Design Procedure

To begin the design process, determine the following:

· Input voltage range



- Use the supply voltage of the device that is driving the TXG802x-Q1 device to determine the input voltage range. For a valid logic-high, the value must exceed the positive-going input-threshold voltage (V<sub>T+</sub>) of the input port. For a valid logic low the value must be less than the negative-going input-threshold voltage (V<sub>T-</sub>) of the input port.
- Output voltage range
  - Use the supply voltage of the device that the TXG802x-Q1 device is driving to determine the output voltage range.



#### 8.2.3 Application Curves

Figure 8-2. Waveform showing -80V (top) and +80V (bottom) Ground Shift with 5V to 2.5V I/O Translation



## 8.3 Power Supply Recommendations

Always apply a ground reference to the GND pins first. This device is designed for glitch free power sequencing without any supply sequencing requirements such as ramp order or ramp rate. Please make sure the difference between  $V_{CC}$  and GND remains at 6.5V max at all times.

## 8.4 Layout

#### 8.4.1 Layout Guidelines

To ensure reliability of the device, following common printed-circuit board layout guidelines are recommended:

- Use bypass capacitors on the power supply pins and place them as close to the device as possible. A 0.1µF capacitor is recommended, but transient performance can be improved by having 1µF and 0.1µF capacitors in parallel as bypass capacitors.
- The high drive capability of this device creates fast edges into light loads so routing and load conditions should be considered to prevent ringing.
- A 0.1µF capacitor can be added between GNDA and GNDB to improve performances of CMTI.

## 8.4.2 Layout Example

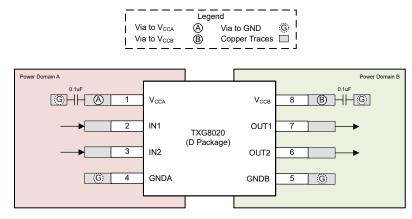


Figure 8-3. D Layout Example



# 9 Device and Documentation Support

## 9.1 Device Support

#### 9.1.1 Regulatory Requirements

No statutory or regulatory requirements apply to this device.

There are no special characteristics for this product.

## 9.2 Documentation Support

#### 9.2.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, Understanding Schmitt Triggers application report
- Texas Instruments, CMOS Power Consumption and C<sub>pd</sub> Calculation application report

## 9.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

## 9.4 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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#### 9.5 Trademarks

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#### 9.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## 9.7 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

# **10 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

DATE	REVISION	NOTES		
May 2025	*	Initial Release		

# 11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
PTXG8020QDRQ1	Active	Preproduction	SOIC (D)   8	3000   LARGE T&R	-	Call TI	Call TI	-40 to 125	
PTXG8021QDRQ1	Active	Preproduction	SOIC (D)   8	3000   LARGE T&R	-	Call TI	Call TI	-40 to 125	

<sup>(1)</sup> **Status:** For more details on status, see our product life cycle.

<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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# D0008A



# **PACKAGE OUTLINE**

# SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



#### NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.

- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



# D0008A

# **EXAMPLE BOARD LAYOUT**

# SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# D0008A

# **EXAMPLE STENCIL DESIGN**

# SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

9. Board assembly site may have different recommendations for stencil design.



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