



## TPS62590 1-A Step Down Converter in 2-mm x 2-mm WSON Package

### 1 Features

- Output Current up to 1000 mA
- Input Voltage Range from 2.5 V to 5.5 V
- Output Voltage Accuracy in PWM Mode  $\pm 2.5\%$
- Typical 15- $\mu$ A Quiescent Current
- 100% Duty Cycle for Lowest Dropout
- Available in a 2 mm x 2 mm x 0.8 mm WSON Package
- For Improved Features Set, See the TPS62290 device (SLVS764)

### 2 Applications

- Mobile Phones, Smart Phones
- Tablet PCs
- WLAN
- Low Power DSP Supply
- Point-of-Load (POL) Applications

### 3 Description

The TPS62590 device is a high-efficiency synchronous step down converter, optimized for battery powered portable applications. The device provides up to 1000-mA output current from batteries, such as single Li-Ion or other common chemistry AA and AAA cells.

With an input voltage range of 2.5 V to 5.5 V, the device is targeted to power a large variety of portable handheld equipment or POL applications.

The TPS62590 family operates at 2.25-MHz fixed switching frequency and enters a power save mode operation at light load currents to maintain a high efficiency over the entire load current range.

The power save mode is optimized for low output voltage ripple. For low noise applications, the device can be forced into fixed frequency pulse width modulation (PWM) mode by pulling the MODE pin high. In the shutdown mode the current consumption is reduced to less than 1  $\mu$ A. The TPS62590 allows the use of small inductors and capacitors to achieve a small solution size.

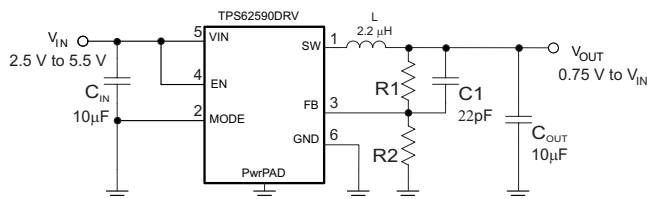
The TPS62590 is available in a 2-mm x 2-mm 6-pin WSON package.

#### Device Information<sup>(1)</sup>

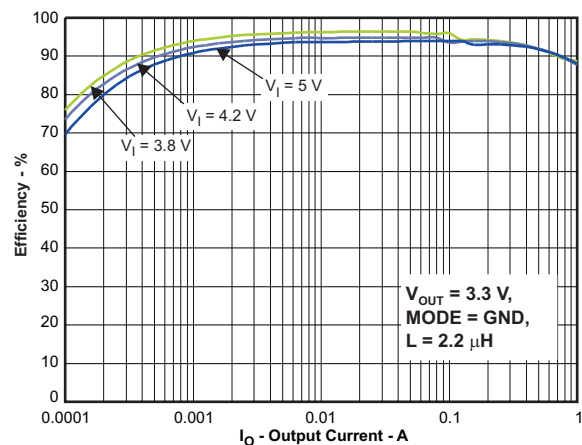
PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPS62590	WSON (6)	2.00 mm x 2.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

#### Typical Application Schematic



#### Efficiency vs Output Current



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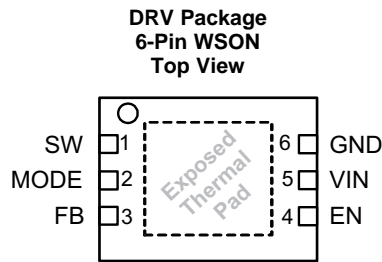
## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

<b>Changes from Revision B (April 2011) to Revision C</b>	<b>Page</b>
<ul style="list-style-type: none"> <li>Added <i>Pin Configuration and Functions</i> section, <i>ESD Ratings</i> table, <i>Feature Description</i> section, <i>Device Functional Modes</i>, <i>Application and Implementation</i> section, <i>Power Supply Recommendations</i> section, <i>Layout</i> section, <i>Device and Documentation Support</i> section, and <i>Mechanical, Packaging, and Orderable Information</i> section .....</li> </ul>	<b>1</b>

<b>Changes from Revision A (November 2009) to Revision B</b>	<b>Page</b>
<ul style="list-style-type: none"> <li>Replaced the DISSIPATION RATINGS with the THERMAL INFORMATION table.....</li> </ul>	<b>4</b>

## 5 Pin Configuration and Functions



### Pin Functions

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
EN	4	I	This is the enable pin of the device. Pulling this pin to low forces the device into shutdown mode. Pulling this pin to high enables the device. This pin must be terminated.
Exposed Thermal Pad	–	–	Must be soldered to achieve appropriate power dissipation. Should be connected to GND.
FB	3	I	Feedback pin for the internal regulation loop. Connect the external resistor divider to this pin. In case of fixed output voltage option, connect this pin directly to the output capacitor.
GND	6	P	GND supply pin
MODE	2	I	MODE pin = High forces the device to operate in fixed-frequency PWM mode. Mode pin = Low enables the power save mode with automatic transition from PFM mode to fixed-frequency PWM mode.
SW	1	O	This is the switch pin and is connected to the internal MOSFET switches. Connect the external inductor between this terminal and the output capacitor.
VIN	5	P	V <sub>IN</sub> power supply pin

(1) I = Input, O = Output, P = Power

## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
V <sub>IN</sub>	Input voltage <sup>(2)</sup>	−0.3	7	V
	Voltage at EN, MODE	−0.3	V <sub>IN</sub> + 0.3, ≤ 7	
	Voltage on SW	−0.3	7	
	Peak output current	Internally limited		A
T <sub>J</sub>	Maximum operating junction temperature	−40	125	°C
T <sub>stg</sub>	Storage temperature	−65	150	°C

- (1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under [Recommended Operating Conditions](#) is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to network ground terminal.

### 6.2 ESD Ratings

		VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	±2000
		Charged-device model (CDM), per JEDEC specification JESD22-C101, all pins <sup>(2)</sup>	±1000

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

		MIN	MAX	UNIT
V <sub>IN</sub>	Supply voltage	2.5	5.5	V
	Output voltage for adjustable voltage	0.75	V <sub>IN</sub>	V
T <sub>A</sub>	Operating ambient temperature	−40	85	°C
T <sub>J</sub>	Operating junction temperature	−40	125	°C

### 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		TPS62590	UNIT
		DRV (WSON)	
		6 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	67.8	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	88.5	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	37.2	°C/W
ψ <sub>JT</sub>	Junction-to-top characterization parameter	2.0	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	37.6	°C/W
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	7.9	°C/W

- (1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

## 6.5 Electrical Characteristics

Over full operating ambient temperature range, typical values are at  $T_A = 25^\circ\text{C}$ . Unless otherwise noted, specifications apply for condition  $V_{IN} = EN = 3.6\text{ V}$ . External components  $C_{IN} = 10\text{ }\mu\text{F}$  0603,  $C_{OUT} = 10\text{ }\mu\text{F}$  0603,  $L = 2.2\text{ }\mu\text{H}$ , refer to parameter measurement information.

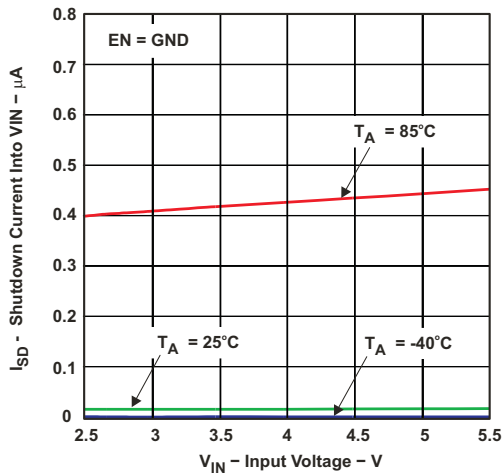
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY						
V <sub>IN</sub>	Input voltage range		2.5		5.5	V
I <sub>OUT</sub>	Output current	V <sub>IN</sub> 2.7 V to 5.5 V			1000	mA
		V <sub>IN</sub> 2.5 V to 2.7 V			600	
I <sub>Q</sub>	Operating quiescent current	I <sub>OUT</sub> = 0 mA, PFM mode enabled (MODE = GND) device not switching, see <sup>(1)</sup>		15		μA
		I <sub>OUT</sub> = 0 mA, switching with no load (MODE = V <sub>IN</sub> ) PWM operation, V <sub>OUT</sub> = 1.8 V, V <sub>IN</sub> = 3 V		3.8		mA
I <sub>SD</sub>	Shutdown current	EN = GND		0.5		μA
UVLO	Undervoltage lockout threshold	Falling		1.85		V
		Rising		1.95		
ENABLE, MODE						
V <sub>IH</sub>	High level input voltage, EN, MODE	2.5 V ≤ V <sub>IN</sub> ≤ 5.5 V	1		V <sub>IN</sub>	V
V <sub>IL</sub>	Low level input voltage, EN, MODE	2.5 V ≤ V <sub>IN</sub> ≤ 5.5 V	0		0.4	V
I <sub>IN</sub>	Input bias current, EN, MODE	EN, MODE = GND or V <sub>IN</sub>		0.01	1	μA
POWER SWITCH						
R <sub>DS(on)</sub>	High side MOSFET on-resistance	V <sub>IN</sub> = V <sub>GS</sub> = 3.6 V, T <sub>A</sub> = 25°C		250		mΩ
	Low side MOSFET on-resistance			190		
I <sub>LIMF</sub>	Forward current limit MOSFET high side and low side	V <sub>IN</sub> = V <sub>GS</sub> = 3.6 V	1.19	1.4	1.68	A
T <sub>SD</sub>	Thermal shutdown	Increasing junction temperature		140		°C
	Thermal shutdown hysteresis	Decreasing junction temperature		20		
OSCILLATOR						
f <sub>SW</sub>	Oscillator frequency	2.5 V ≤ V <sub>IN</sub> ≤ 5.5 V		2.25		MHz
OUTPUT						
V <sub>O</sub>	Adjustable output voltage range		0.75		V <sub>I</sub>	V
V <sub>REF</sub>	Reference voltage			600		mV
V <sub>FB(PWM)</sub>	Feedback voltage	MODE = V <sub>IN</sub> , PWM operation, 2.5 V ≤ V <sub>IN</sub> ≤ 5.5 V, see <sup>(2)</sup>	−2.5%	0%	2.5%	
V <sub>FB(PFM)</sub>	Feedback voltage PFM mode	MODE = GND, device in PFM mode, +1% voltage positioning active, see <sup>(1)</sup>		1%		
	Load regulation			−1		
t <sub>Start Up</sub>	Start-up time	Time from active EN to reach 95% of V <sub>OUT</sub>		500		μs
t <sub>Ramp</sub>	V <sub>OUT</sub> ramp-up time	Time to ramp from 5% to 95% of V <sub>OUT</sub>		250		μs
I <sub>lkg</sub>	Leakage current into SW pin	V <sub>IN</sub> = 3.6 V, V <sub>IN</sub> = V <sub>OUT</sub> = V <sub>SW</sub> , EN = GND, see <sup>(3)</sup>		0.1	1	μA

(1) In PFM mode, the internal reference voltage is set to typical  $1.01 \times V_{REF}$ . See the parameter measurement information.

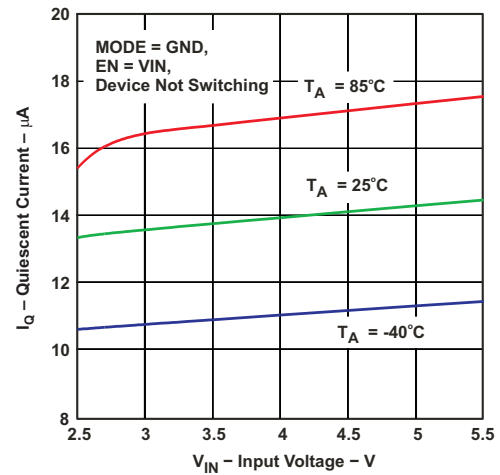
(2) For  $V_{IN} = V_{OUT} + 1\text{ V}$ .

(3) In fixed output voltage versions, the internal resistor divider network is disconnected from FB pin.

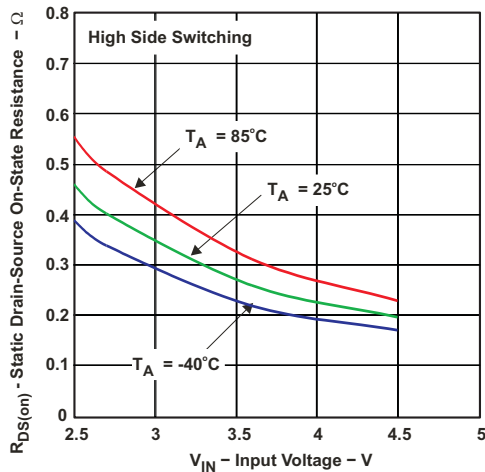
## 6.6 Typical Characteristics



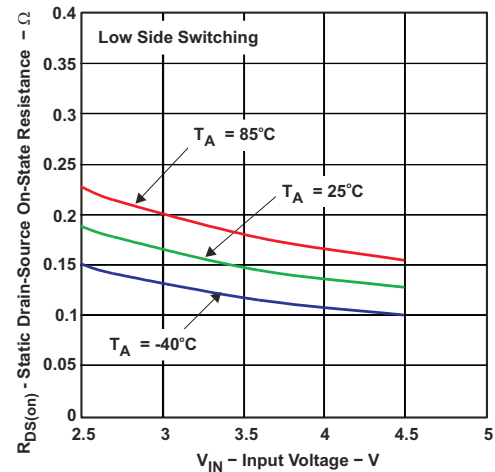
**Figure 1. Shutdown Current into VIN vs Input Voltage**



**Figure 2. Quiescent Current vs Input Voltage**



**Figure 3. Static Drain-Source ON-State Resistance vs Input Voltage**



**Figure 4. Static Drain-Source ON-State Resistance vs Input Voltage**

## 7 Detailed Description

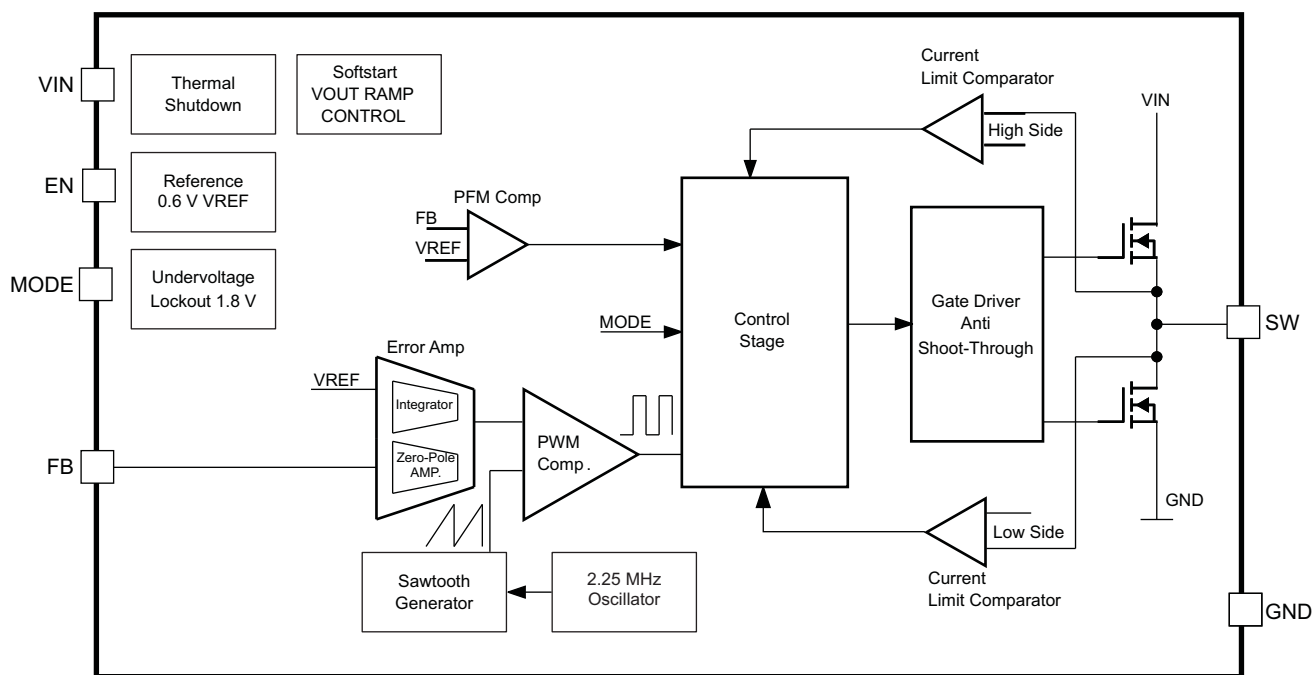
### 7.1 Overview

The TPS62590 step-down converter operates with typically 2.25-MHz fixed frequency pulse width modulation (PWM) at moderate to heavy load currents. At light load currents, the converter can automatically enter power save mode and operates then in pulse frequency modulation (PFM) mode.

During PWM operation, the converter use a unique fast response voltage mode controller scheme with input voltage feed-forward to achieve good line and load regulation allowing the use of small ceramic input and output capacitors. At the beginning of each clock cycle initiated by the clock signal, the high-side MOSFET switch is turned on. The current flows now from the input capacitor through the high-side MOSFET switch through the inductor to the output capacitor and load. During this phase, the current ramps up until the PWM comparator trips and the control logic turns off the switch. The current limit comparator also turns off the switch if the current limit of the high-side MOSFET switch is exceeded. After a dead time preventing shoot through current, the low-side MOSFET rectifier is turned on and the inductor current ramps down. The current flows now from the inductor to the output capacitor and to the load. It returns to the inductor through the low-side MOSFET rectifier. It returns to the inductor through the low-side MOSFET rectifier.

The next cycle is initiated by the clock signal again turning off the low-side MOSFET rectifier and turning on the high-side MOSFET switch.

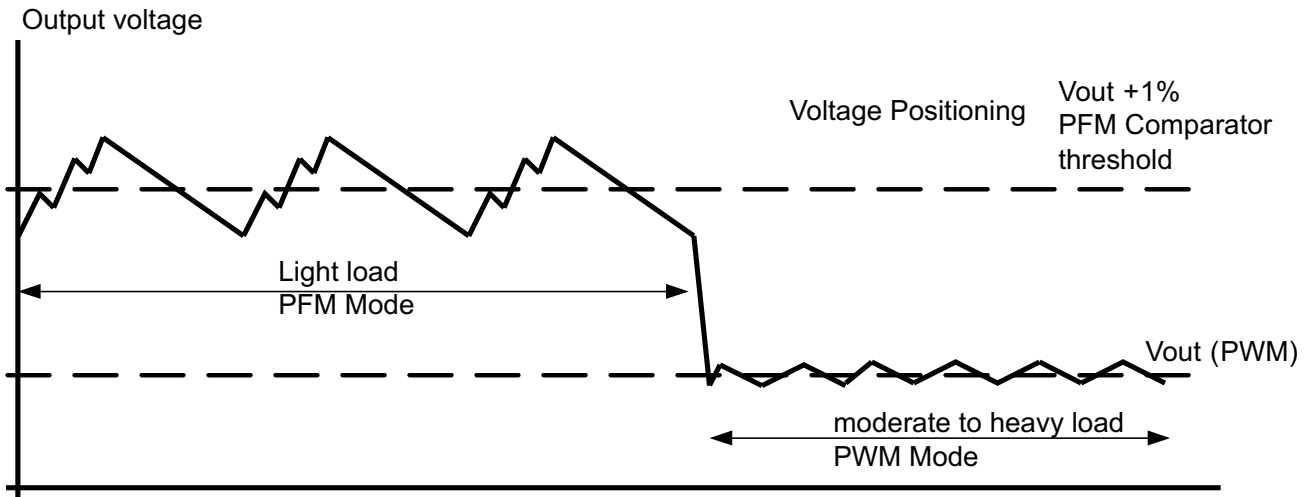
### 7.2 Functional Block Diagram



## 7.3 Feature Description

### 7.3.1 Dynamic Voltage Positioning

This feature reduces the voltage undershoots and overshoots at load steps from light to heavy load and vice versa. It is active in power-save mode and regulates the output voltage 1% higher than the nominal value. This provides more headroom for both the voltage drop at a load step, and the voltage increase at a load throw-off.



**Figure 5. Power-Save Mode Operation**

### 7.3.2 Undervoltage Lockout

The undervoltage lockout circuit prevents the device from malfunctioning at low input voltages and from excessive discharge of the battery and disables the output stage of the converter. The undervoltage lockout threshold is typically 1.85 V with falling  $V_{IN}$ .

### 7.3.3 Mode Selection

The MODE pin allows mode selection between forced PWM mode and power-save mode.

Connecting this pin to GND enables the power-save mode with automatic transition between PWM and PFM mode. Pulling the MODE pin high forces the converter to operate in fixed frequency PWM mode even at light load currents. This allows simple filtering of the switching frequency for noise-sensitive applications. In this mode, the efficiency is lower compared to the power-save mode during light loads.

The condition of the MODE pin can be changed during operation and allows efficient power management by adjusting the operation mode of the converter to the specific system requirements.

### 7.3.4 Enable

The device is enabled setting EN pin to high. During the start-up time  $t_{Start Up}$  the internal circuits are settled. Afterwards, the device activates the soft-start circuit. The EN input can be used to control power sequencing in a system with various DC-DC converters. The EN pin can be connected to the output of another converter, to drive the EN pin high and getting a sequencing of supply rails. With  $EN = GND$ , the device enters shutdown mode. In this mode, all circuits are disabled. In fixed output voltage versions, the internal resistor divider network is disconnected from FB pin.

### 7.3.5 Thermal Shutdown

As soon as the junction temperature  $T_J$  exceeds 140°C (typical) the device goes into thermal shutdown. In this mode, the high-side and low-side MOSFETs are turned off. The device continues its operation when the junction temperature falls below the thermal shutdown hysteresis.



## 7.4 Device Functional Modes

### 7.4.1 Soft-Start

The TPS62590 has an internal soft-start circuit that controls the ramp up of the output voltage. The output voltage ramps up from 5% to 95% of its nominal value within typical 250  $\mu$ s. This limits the inrush current in the converter during ramp up and prevents possible input voltage drops when a battery or high impedance power source is used. The soft start circuit is enabled within the start up time  $t_{Start Up}$ .

### 7.4.2 Power-Save Mode

The power-save mode is enabled with MODE pin set to low level. If the load current decreases, the converter will enter power save mode operation automatically. During power save mode the converter skips switching and operates with reduced frequency in PFM mode with a minimum quiescent current to maintain high efficiency. The converter will position the output voltage +1% above the nominal output voltage typically. This voltage positioning feature minimizes voltage drops caused by a sudden load step.

The transition from PWM mode to PFM mode occurs once the inductor current in the low-side MOSFET switch becomes zero, which indicates discontinuous conduction mode.

During the power-save mode the output voltage is monitored with a PFM comparator. As the output voltage falls below the PFM comparator threshold of  $V_{OUT}$  nominal +1%, the device starts a PFM current pulse. For this the high-side MOSFET switch will turn on and the inductor current ramps up. After the ON-time expires, the switch is turned off and the low-side MOSFET switch is turned on until the inductor current becomes zero.

The converter effectively delivers a current to the output capacitor and the load. If the load is below the delivered current, the output voltage will rise. If the output voltage is equal to or higher than the PFM comparator threshold, the device stops switching and enters a sleep mode with typical 15- $\mu$ A current consumption.

If the output voltage is still below the PFM comparator threshold, a sequence of further PFM current pulses are generated until the PFM comparator threshold is reached. The converter starts switching again once the output voltage drops below the PFM comparator threshold.

With a fast single threshold comparator, the output voltage ripple during PFM mode operation can be kept small. The PFM pulse is time controlled, which allows to modify the charge transferred to the output capacitor by the value of the inductor. The resulting PFM output voltage ripple and PFM frequency depend in first order on the size of the output capacitor and the inductor value. Increasing output capacitor values and inductor values will minimize the output ripple. The PFM frequency decreases with smaller inductor values and increases with larger values.

The PFM mode is left and PWM mode entered in case the output current can not longer be supported in PFM mode. The power save mode can be disabled through the MODE pin set to high. The converter will then operate in fixed frequency PWM mode.

### 7.4.3 100% Duty Cycle Low Dropout Operation

The device starts to enter 100% duty cycle mode once the input voltage comes close the nominal output voltage. To maintain the output voltage, the high-side MOSFET switch is turned on 100% for one or more cycles.

With further decreasing  $V_{IN}$  the high side MOSFET switch is turned on completely. In this case, the converter offers a low input-to-output voltage difference. This is particularly useful in battery-powered applications to achieve longest operation time by taking full advantage of the whole battery voltage range.

The minimum input voltage to maintain regulation depends on the load current and output voltage, and can be calculated by [Equation 1](#):

$$V_{INmin} = V_{OUTmax} + I_{OUTmax} \times R_{DS(on)max} + R_L$$

where

- $I_{OUTmax}$  = Maximum output current plus inductor ripple current
- $R_{DS(on)max}$  = Maximum P-channel switch  $R_{DS(on)}$
- $R_L$  = DC resistance of the inductor
- $V_{OUTmax}$  = Nominal output voltage plus maximum output voltage tolerance

(1)

## Device Functional Modes (continued)

### 7.4.4 Short-Circuit Protection

The high-side and low side MOSFET switches are short-circuit protected with maximum switch current equal to  $I_{LIMF}$ . The current in the switches is monitored by current limit comparators. Once the current in the high-side MOSFET switch exceeds the threshold of its current limit comparator, it turns off and the low-side MOSFET switch is activated to ramp down the current in the inductor and high-side MOSFET switch. The high-side MOSFET switch can only turn on again, once the current in the low-side MOSFET switch has decreased below the threshold of its current limit comparator.

## 8 Application and Implementation

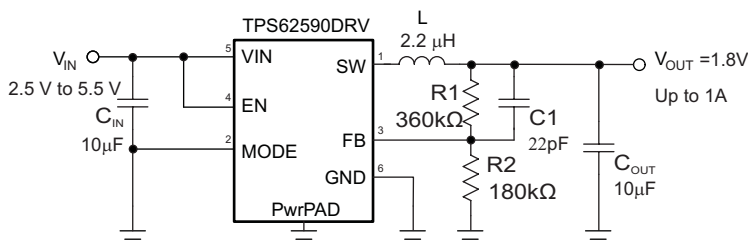
### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 8.1 Application Information

The TPS62590 device is a high-efficiency synchronous step-down DC–DC converter featuring power-save mode or 2.25-MHz fixed frequency operation.

### 8.2 Typical Application



**Figure 6. TPS62590DRV Adjustable 1.8 V**

#### 8.2.1 Design Requirements

The device operates over an input voltage range from 2.5 V to 5.5 V. The output voltage is adjustable using an external feedback divider.

#### 8.2.2 Detailed Design Procedure

##### 8.2.2.1 Output Voltage Setting

The output voltage can be calculated by [Equation 2](#) with the internal reference voltage  $V_{REF} = 0.6\text{ V}$  typically.

$$V_{OUT} = V_{REF} \times \left( 1 + \frac{R1}{R2} \right) \quad (2)$$

To minimize the current through the feedback divider network, R2 should be 180 kΩ or 360 kΩ. The sum of R1 and R2 should not exceed ~1 MΩ, to keep the network robust against noise. An external feed forward capacitor C1 is required for optimum load transient response. The value of C1 should be in the range between 22 pF and 33 pF.

Route the FB line away from noise sources, such as the inductor or the SW line.

##### 8.2.2.2 Output Filter Design (Inductor and Output Capacitor)

The TPS62590 is designed to operate with inductors in the range of 1.5 µH to 4.7 µH and with output capacitors in the range of 4.7 µF to 22 µF. The part is optimized for operation with a 2.2-µH inductor and 10-µF output capacitor. Larger or smaller inductor values can be used to optimize the performance of the device for specific operation conditions. For stable operation, the L and C values of the output filter may not fall below 1-µH effective inductance and 3.5-µF effective capacitance.

##### 8.2.2.2.1 Inductor Selection

The inductor value has a direct effect on the ripple current. The selected inductor has to be rated for its DC resistance and saturation current. The inductor ripple current ( $\Delta I_L$ ) decreases with higher inductance and increases with higher  $V_{IN}$  or  $V_{OUT}$ .

## Typical Application (continued)

The inductor selection has also impact on the output voltage ripple in PFM mode. Higher inductor values will lead to lower output voltage ripple and higher PFM frequency, lower inductor values will lead to a higher output voltage ripple but lower PFM frequency.

[Equation 3](#) calculates the maximum inductor current under static load conditions. The saturation current of the inductor should be rated higher than the maximum inductor current as calculated with [Equation 4](#). This is recommended because during heavy load transient the inductor current will rise above the calculated value.

$$\Delta I_L = V_{OUT} \times \frac{1 - \frac{V_{OUT}}{V_{IN}}}{L \times f} \quad (3)$$

$$I_{L\max} = I_{OUT\max} + \frac{\Delta I_L}{2}$$

where

- $f$  = Switching frequency (2.25 MHz typical)
  - $L$  = Inductor value
  - $\Delta I_L$  = Peak-to-peak inductor ripple current
  - $I_{L\max}$  = Maximum inductor current
- (4)

A more conservative approach is to select the inductor current rating just for the maximum switch current of the corresponding converter.

Accepting larger values of ripple current allows the use of low inductance values, but results in higher output voltage ripple, greater core losses, and lower output current capability.

The total losses of the coil have a strong impact on the efficiency of the DC–DC conversion and consist of both the losses in the DC resistance ( $R_{DC}$ ) and the following frequency-dependent components:

- The losses in the core material (magnetic hysteresis loss, especially at high switching frequencies)
- Additional losses in the conductor from the skin effect (current displacement at high frequencies)
- Magnetic field losses of the neighboring windings (proximity effect)
- Radiation losses

**Table 1. List of Inductors**

DIMENSIONS [mm <sup>3</sup> ]	INDUCTOR TYPE	SUPPLIER
3 × 3 × 1.5	LPS3015	Coilcraft
3 × 3 × 1.5	LQH3NPN2R2NM0	MURATA
3.2 × 2.6 × 1.2	MIPSA3226D2R2	FDK

### 8.2.2.2.2 Output Capacitor Selection

The advanced fast-response voltage mode control scheme of the TPS62590 allows the use of tiny ceramic capacitors. Ceramic capacitors with low ESR values have the lowest output voltage ripple and are recommended. The output capacitor requires either an X7R or X5R dielectric. Y5V and Z5U dielectric capacitors, aside from their wide variation in capacitance over temperature, become resistive at high frequencies.

At nominal load current, the device operates in PWM mode and the RMS ripple current is calculated by [Equation 5](#):

$$I_{RMS\,OUT} = V_{OUT} \times \frac{1 - \frac{V_{OUT}}{V_{IN}}}{L \times f} \times \frac{1}{2 \times \sqrt{3}} \quad (5)$$

At nominal load current, the device operates in PWM mode and the overall output voltage ripple is the sum of the voltage spike caused by the output capacitor ESR plus the voltage ripple caused by charging and discharging the output capacitor shown in [Equation 6](#):

$$\Delta V_{OUT} = V_{OUT} \times \frac{1 - \frac{V_{OUT}}{V_{IN}}}{L \times f} \times \left( \frac{1}{8 \times C_{OUT} \times f} + ESR \right) \quad (6)$$

At light load currents the converter operates in power save mode and the output voltage ripple is dependent on the output capacitor and inductor value. Larger output capacitor and inductor values minimize the voltage ripple in PFM mode and tighten DC output accuracy in PFM mode.

### 8.2.2.2.3 Input Capacitor Selection

The buck converter has a natural pulsating input current; therefore, a low ESR input capacitor is required for best input voltage filtering and minimizing the interference with other circuits caused by high input voltage spikes. For most applications, a 10-μF ceramic capacitor is recommended. The input capacitor can be increased without any limit for better input voltage filtering.

Take care when using only small ceramic input capacitors. When a ceramic capacitor is used at the input and the power is being supplied through long wires, such as from a wall adapter, a load step at the output or  $V_{IN}$  step on the input can induce ringing at the VIN pin. The ringing can couple to the output and be mistaken as loop instability or could even damage the part by exceeding the maximum ratings.

**Table 2. List of Capacitor**

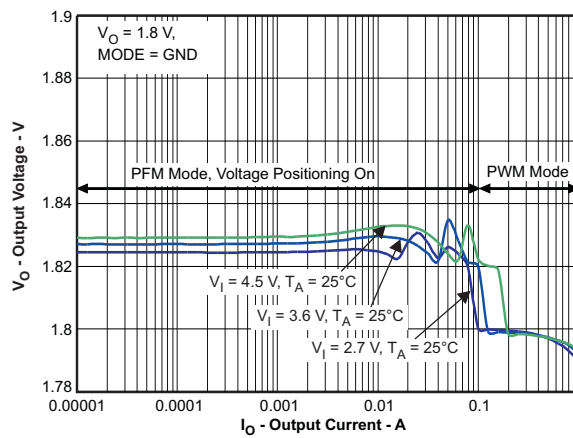
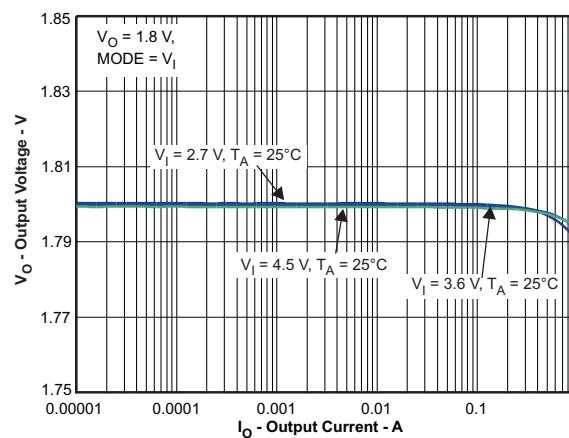
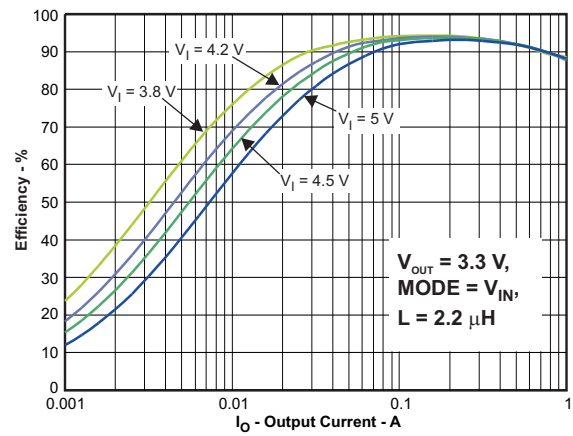
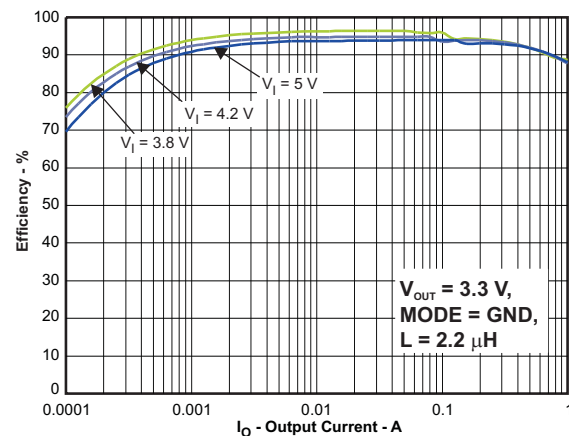
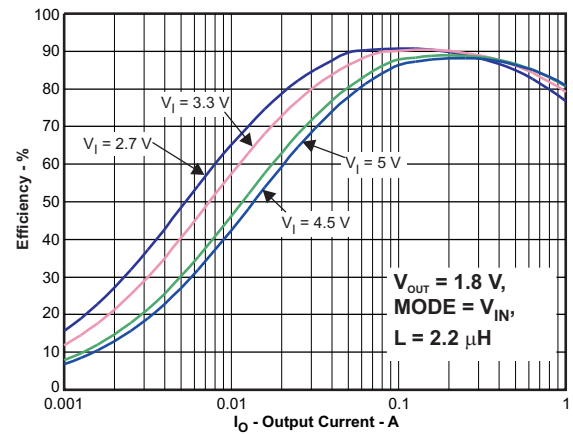
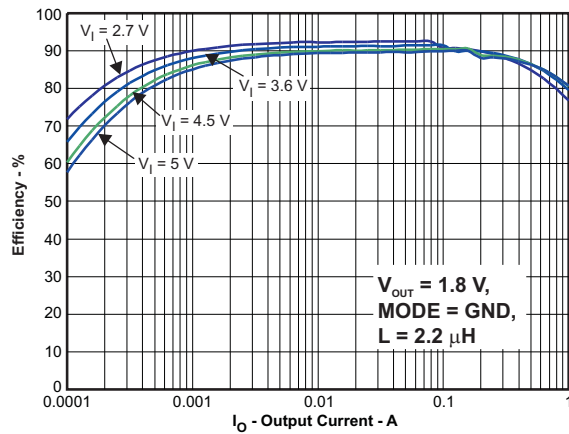
CAPACITANCE	TYPE	SIZE	SUPPLIER
10 μF	GRM188R60J106M69D	0603 1.6 × 0.8 × 0.8mm <sup>3</sup>	Murata

Table 3 shows the list of components for the [Application Curves](#).

**Table 3. List of Components**

COMPONENT REFERENCE	PART NUMBER	MANUFACTURER	VALUE
C <sub>IN</sub>	GRM188R60J106M	Murata	10 μF, 6.3-V. X5R Ceramic
C <sub>OUT</sub>	GRM188R60J106M	Murata	10 μF, 6.3-V. X5R Ceramic
C <sub>1</sub>		Murata	22-pF, COG Ceramic
L <sub>1</sub>	LPS3015	Coilcraft	2.2 μH, 110 mΩ
R <sub>1</sub> , R <sub>2</sub>	Values depending on the programmed output voltage		

## 8.2.3 Application Curves



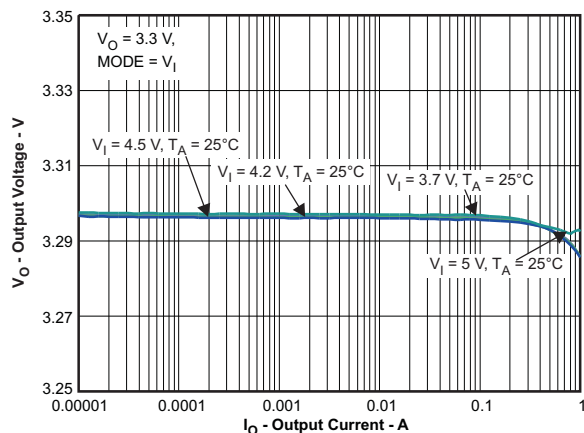


Figure 13. Output Voltage vs Output Current

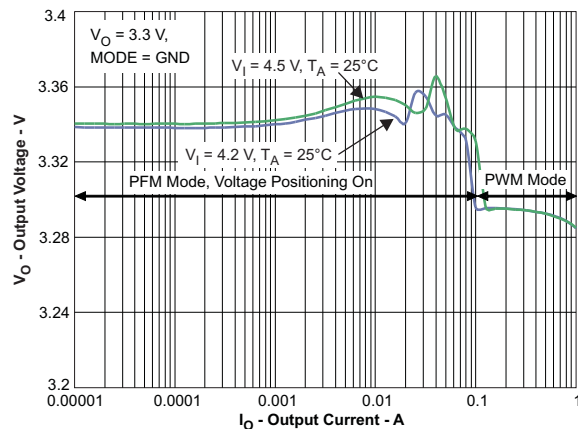
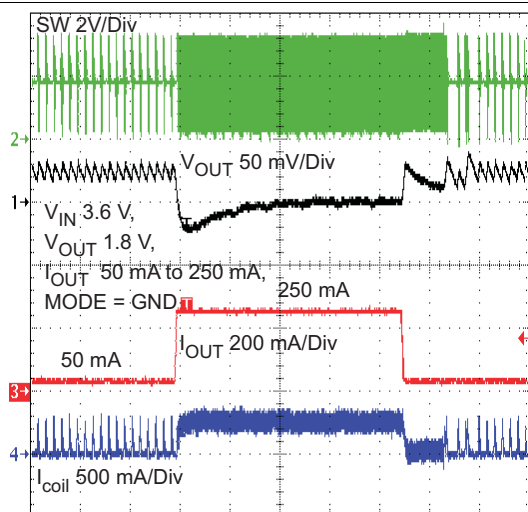
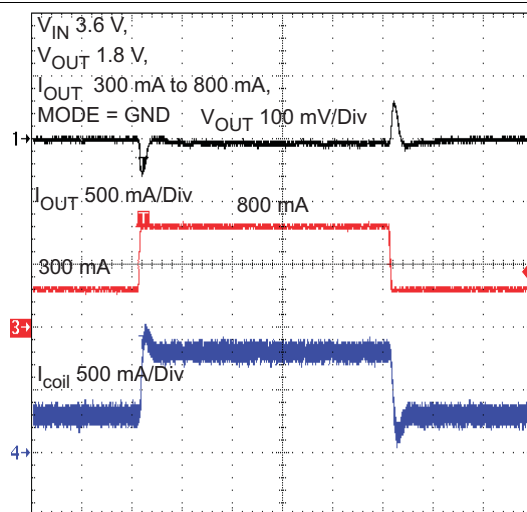


Figure 14. Output Voltage vs Output Current



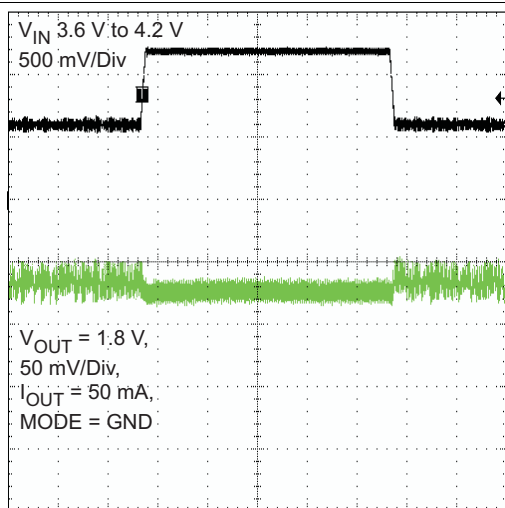
Time Base - 20  $\mu$ s/Div

Figure 15. PFM Load Transient



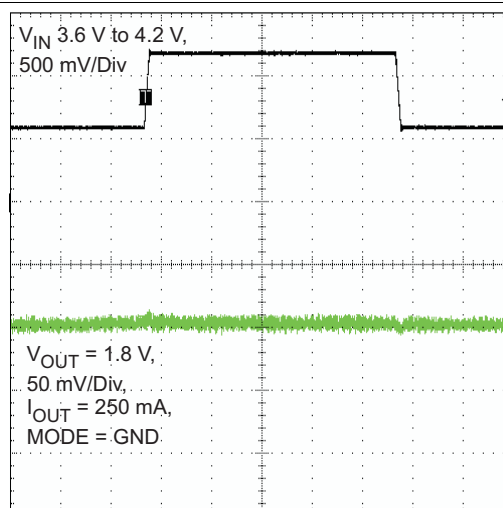
Time Base - 20  $\mu$ s/Div

Figure 16. PWM Load Transient



Time Base - 100  $\mu$ s/Div

Figure 17. PFM Line Transient



Time Base - 100  $\mu$ s/Div

Figure 18. PWM Line Transient

## TPS62590

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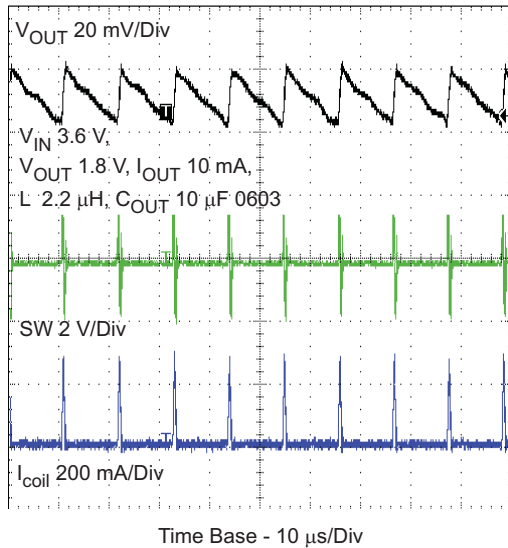


Figure 19. Typical Operation – PFM Mode

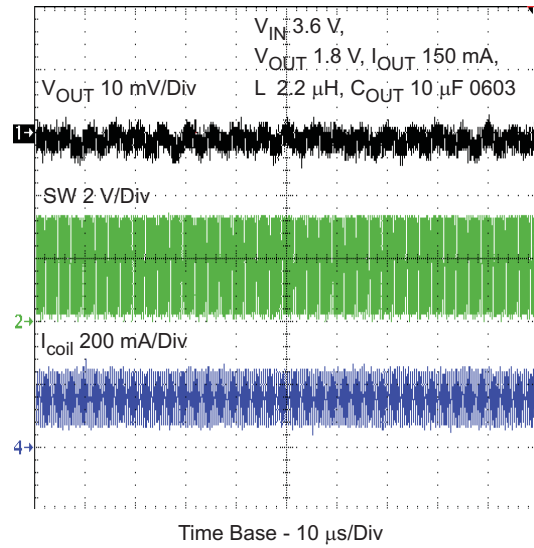


Figure 20. Typical Operation – PWM Mode

## 8.3 System Example

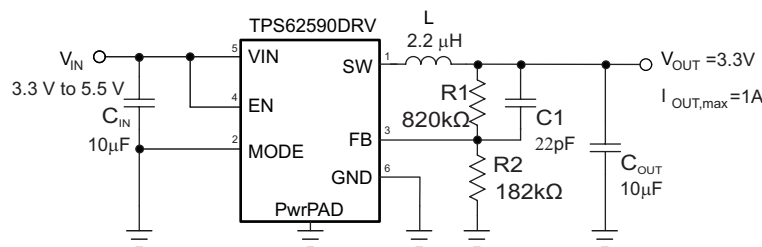


Figure 21. TPS62590DRV Adjustable 3.3 V

## 9 Power Supply Recommendations

The TPS62590 device has no special requirements for its input power supply. The output current of the input power supply needs to be rated according to the supply voltage, output voltage and output current of the TPS62590.



## 10 Layout

### 10.1 Layout Guidelines

As for all switching power supplies, the layout is an important step in the design. Proper function of the device demands careful attention to PCB layout. Take care in board layout to get the specified performance. If the layout is not carefully done, the regulator could show poor line and/or load regulation, stability issues as well as EMI problems. It is critical to provide a low inductance, impedance ground path. Therefore, use wide and short traces for the main current paths. The input capacitor should be placed as close as possible to the IC pins as well as the inductor and output capacitor.

Connect the GND pin of the device to the exposed thermal pad of the PCB and use this pad as a star point. Use a common power GND node and a different node for the signal GND to minimize the effects of ground noise. Connect these ground nodes together to the exposed thermal pad (star point) underneath the IC. Keep the common path to the GND pin, which returns the small signal components and the high current of the output capacitors as short as possible to avoid ground noise. The FB line should be connected right to the output capacitor and routed away from noisy components and traces (for example, the SW line).

### 10.2 Layout Example

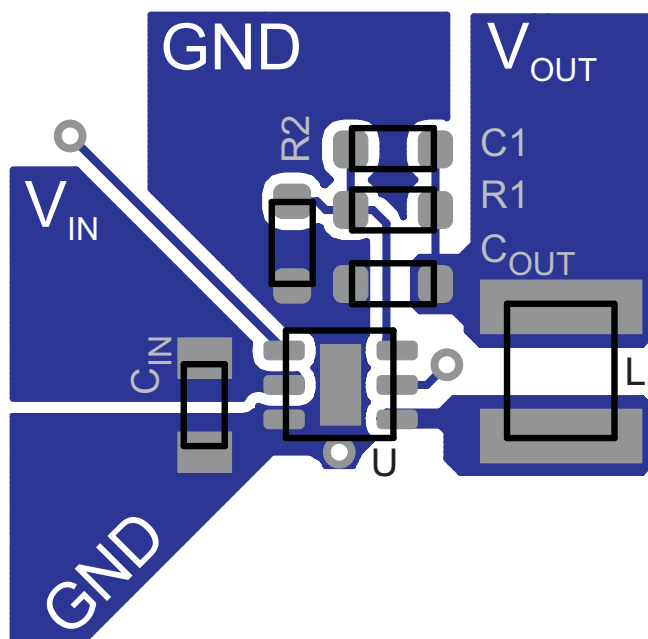


Figure 22. PCB Layout

## 11 Device and Documentation Support

### 11.1 Device Support

#### 11.1.1 Third-Party Products Disclaimer

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### 11.2 Documentation Support

#### 11.2.1 Related Documentation

For related documentation, see the following:

*TPS62290 2.25MHz 1A Step-Down Converter in 2x2mm SON Package*, [SLVS764](#)

### 11.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

**TI E2E™ Online Community** *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At [e2e.ti.com](#), you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

### 11.4 Trademarks

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All other trademarks are the property of their respective owners.

### 11.5 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### 11.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">TPS62590DRV</a>	Active	Production	WSON (DRV)   6	3000   LARGE T&R	Yes	Call TI   Nipdauag   Nipdau	Level-1-260C-UNLIM	-40 to 85	OAL
TPS62590DRV.A	Active	Production	WSON (DRV)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	OAL
TPS62590DRV.B	Active	Production	WSON (DRV)   6	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	OAL
<a href="#">TPS62590DRV</a>	Active	Production	WSON (DRV)   6	250   SMALL T&R	Yes	Call TI   Nipdauag   Nipdau	Level-1-260C-UNLIM	-40 to 85	OAL
TPS62590DRV.A	Active	Production	WSON (DRV)   6	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	OAL
TPS62590DRV.B	Active	Production	WSON (DRV)   6	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	OAL

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

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**OTHER QUALIFIED VERSIONS OF TPS62590 :**

- Automotive : [TPS62590-Q1](#)

NOTE: Qualified Version Definitions:

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

## TAPE AND REEL INFORMATION



\*All dimensions are nominal

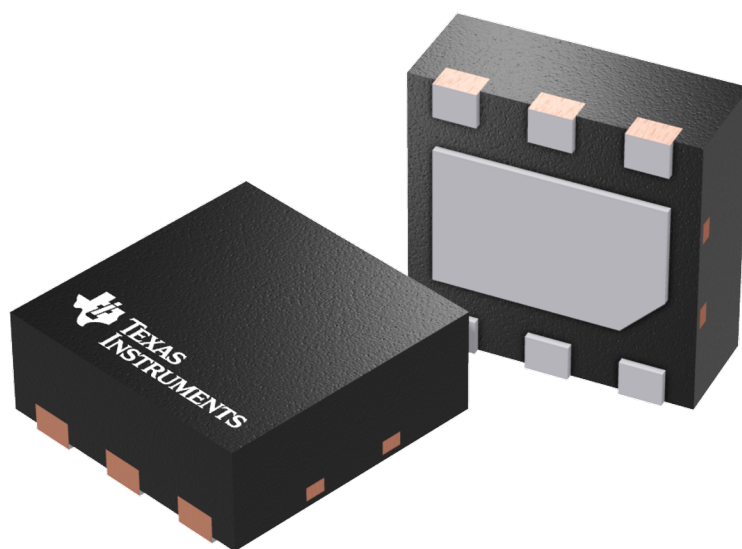
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS62590DRVR	WSO	DRV	6	3000	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2
TPS62590DRV	WSO	DRV	6	250	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS62590DRVR	WSO	DRV	6	3000	210.0	185.0	35.0
TPS62590DRV	WSO	DRV	6	250	210.0	185.0	35.0



Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

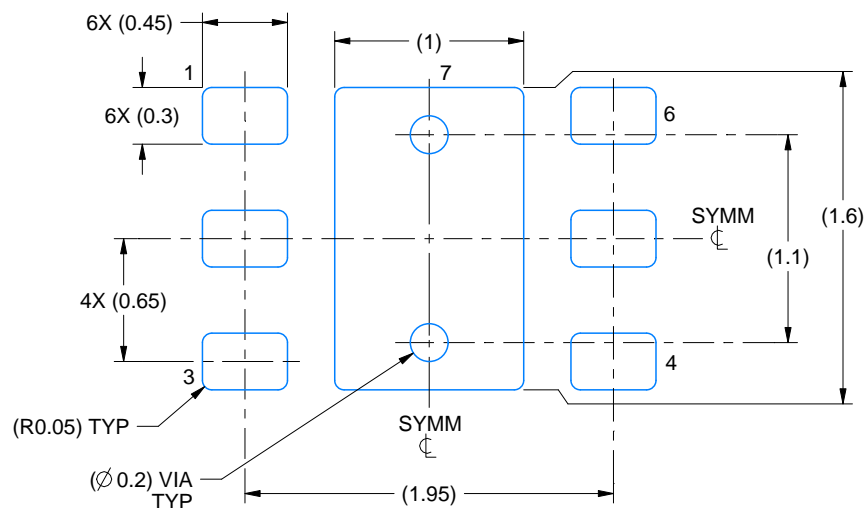




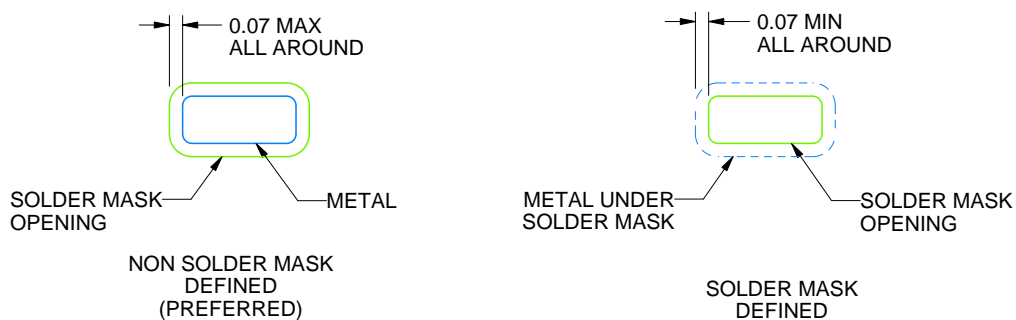
**DRV0006A**

**WSON - 0.8 mm max height**

PLASTIC SMALL OUTLINE - NO LEAD



LAND PATTERN EXAMPLE  
SCALE:25X



## SOLDER MASK DETAILS

4222173/B 04/2018

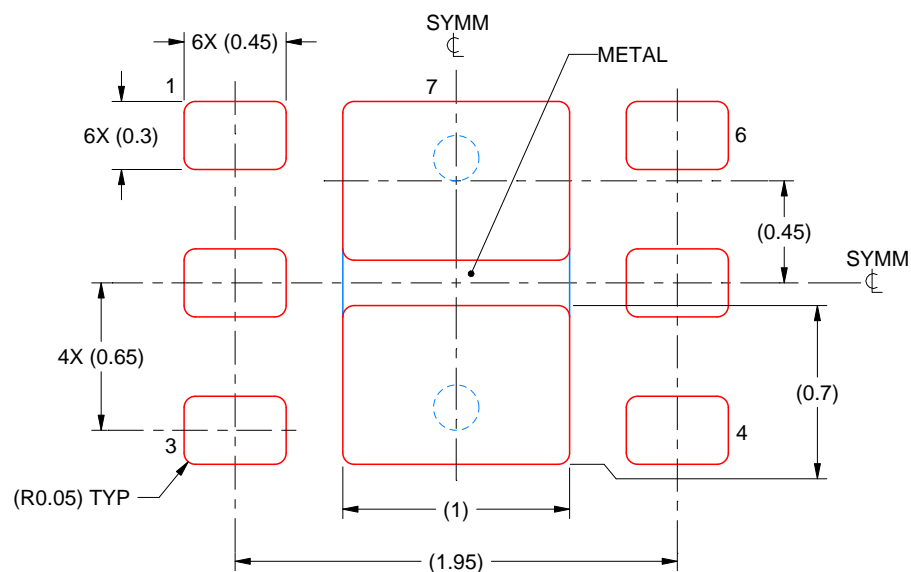
NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/slua271](http://www.ti.com/lit/slua271)).
5. Vias are optional depending on application, refer to device data sheet. If some or all are implemented, recommended via locations are shown.

**DRV0006A**

**WSON - 0.8 mm max height**

PLASTIC SMALL OUTLINE - NO LEAD



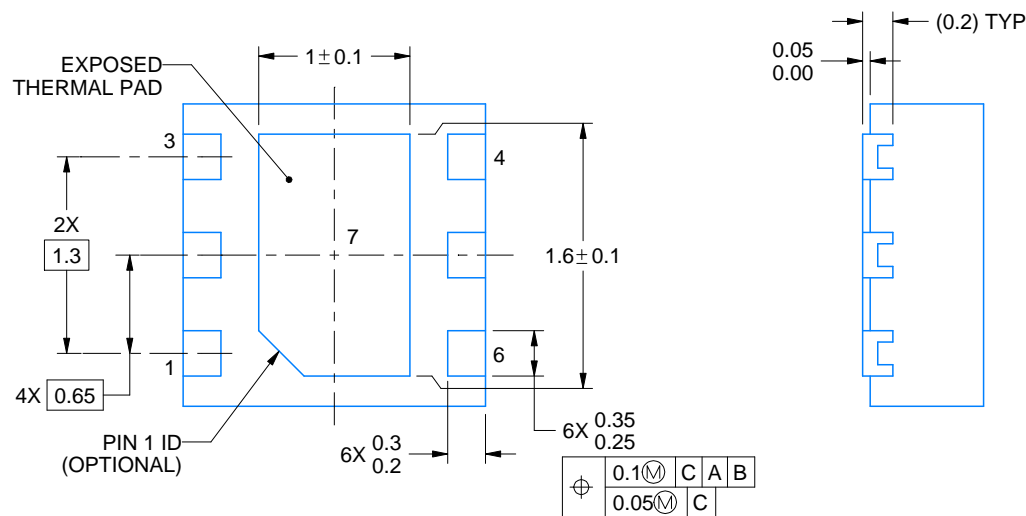
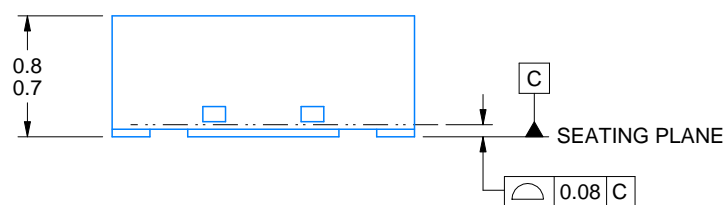
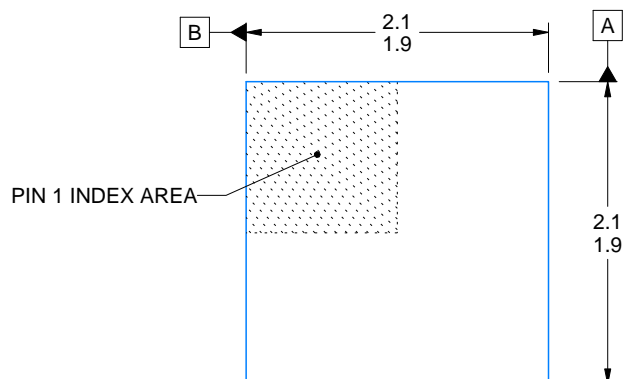
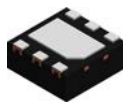
## SOLDER PASTE EXAMPLE BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD #7  
88% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE  
SCALE:30X

4222173/B 04/2018

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



4225563/A 12/2019

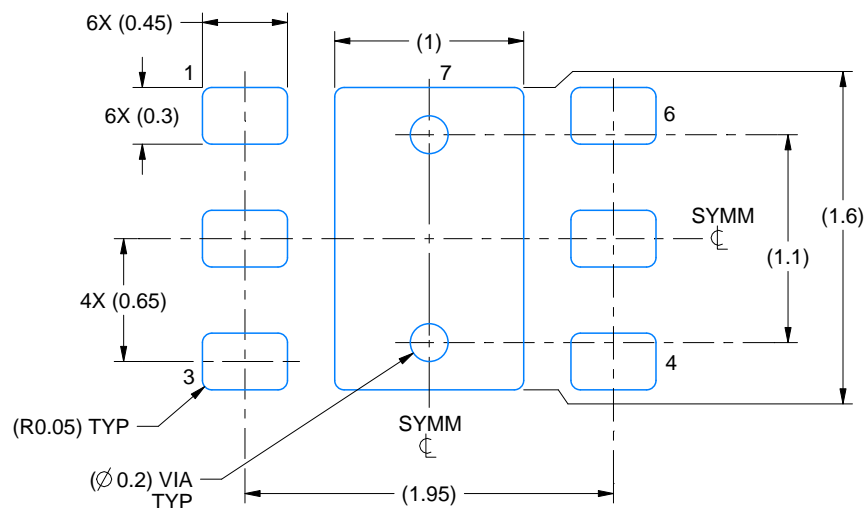
## NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

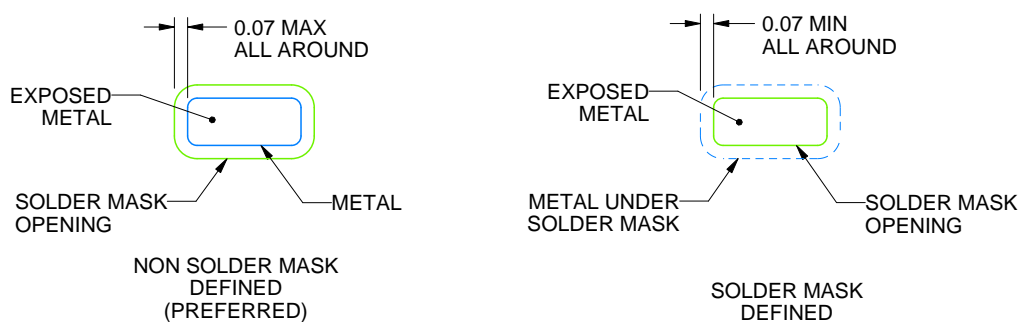
**DRV0006D**

**WSON - 0.8 mm max height**

PLASTIC SMALL OUTLINE - NO LEAD



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:25X



## SOLDER MASK DETAILS

4225563/A 12/2019

NOTES: (continued)

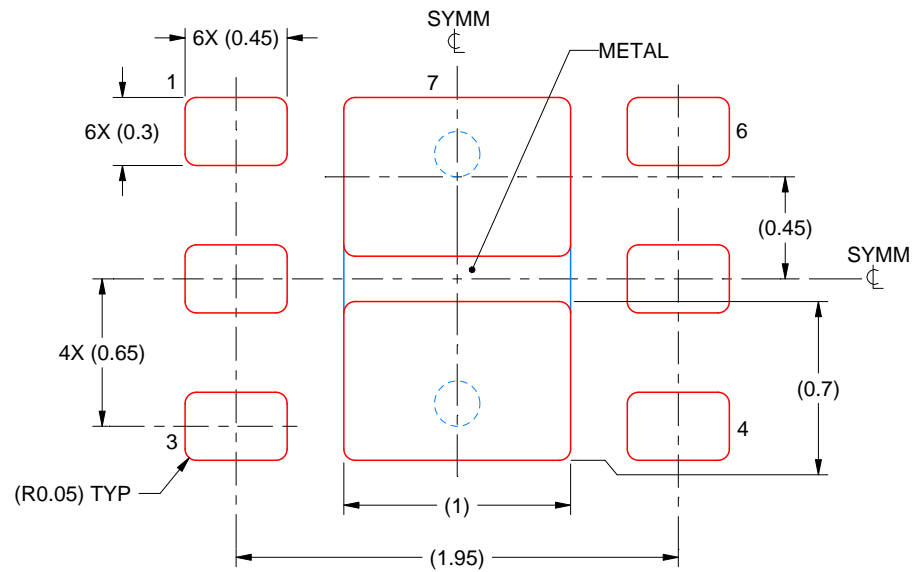
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/slua271](http://www.ti.com/lit/slua271)).
5. Vias are optional depending on application, refer to device data sheet. If some or all are implemented, recommended via locations are shown.

# EXAMPLE STENCIL DESIGN

DRV0006D

WSN - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD #7  
88% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE  
SCALE:30X

4225563/A 12/2019

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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