









TPS62406-Q1, TPS62407-Q1, TPS62422-Q1, TPS62423-Q1, TPS62424-Q1 SLVSCH9E – DECEMBER 2014 – REVISED MARCH 2022

## TPS624xx-Q1 Automotive 2.25-MHz Fixed VOUT Dual Step-Down Converter

## 1 Features

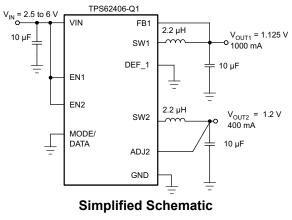
- Qualified for automotive applications
- AEC-Q100 qualified with the following results:
  - Device temperature grade 1: –40°C to 125°C operating junction temperature range
    - Device HBM ESD classification level 2
  - Device CDM ESD classification level C4B
- High efficiency—up to 95%
- V<sub>IN</sub> range from 2.5 V to 6 V
- 2.25-MHz fixed-frequency operation
- Output current TPS62406-Q1 1000 mA/400 mA
- Output current TPS62407-Q1 400 mA/600 mA
- Output current TPS62422-Q1 1000 mA/600 mA
- Output current TPS62423-Q1 800 mA/800 mA
- Output current TPS62424-Q1 800 mA/800 mA
- Fixed output voltages
- EasyScale<sup>™</sup> optional one-pin serial interface
- Power save mode at light load currents
- 180° out-of-phase operation
- Output-voltage accuracy in PWM mode ±1%
- Typical 32-µA quiescent current for both converters
- 100% duty cycle for lowest dropout

## 2 Applications

- · Automotive point-of-load regulator
- ADAS camera modules
- Mirror replacement (CMS)
- Infotainment and cluster

## 3 Description

The TPS624xx-Q1 family of devices are synchronous dual step-down DC-DC converters for Automotive



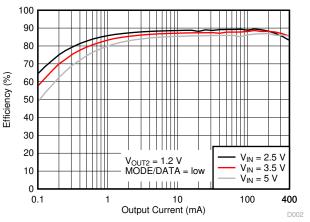
applications such as Advanced Driver Assistance Systems (ADAS). They provide two independent output voltage rails powered by a standard 3.3-V or 5-V voltage rail, with fixed output voltages optimized for powering the CMOS imager or serializer-deserializer in ADAS camera modules.

The EasyScale<sup>™</sup> serial interface allows outputvoltages modification during operation. The fixedoutput-voltage versions TPS624xx-Q1 support onepin-controlled simple dynamic voltage scaling for lowpower processors.

The TPS624xx-Q1 family of devices operates at 2.25-MHz fixed switching frequency and enters the powersave mode operation at light load currents to maintain high efficiency over the entire load-current range. For low-noise applications, one can force the devices into fixed-frequency PWM mode by pulling the MODE/ DATA pin high. The shutdown mode reduces the current consumption to 1.2-µA, typical. The devices allow the use of small inductors and capacitors to achieve a small solution size.

Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPS62406-Q1		
TPS62407-Q1		
TPS62422-Q1	VSON (10)	3.00 mm × 3.00 mm
TPS62423-Q1		
TPS62424-Q1		



TPS62406-Q1 Efficiency vs Output Current, V<sub>OUT2</sub>



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## **4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

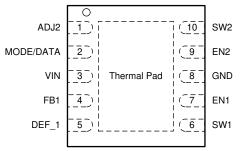
Changes from Revision D (August 2018) to Revision E (March 2022)	Page				
Updated the numbering format for tables, figures, and cross-references throughout the document Removed manual package option addendum, tape and reel information, and package drawings					
Changes from Revision * (December 2014) to Revision A (October 2015)	Page				
<ul> <li>Changed the I<sub>OUT1</sub> and I<sub>OUT2</sub> current for the TPS62406-Q1 device in the <i>Device Comparison Table</i></li> <li>Changed forward current limit PMOS and NMOS for the TPS62406-Q1</li> </ul>					



## **5** Device Comparison Table

PART NUMBER	DEFAULT OUTPUT VOLTAGE			OUTPUT	CURRENT	
	M	Fixed default	DEF_1 = High 1.125 V	I	1000 mA	
TPS62406-Q1	V <sub>OUT1</sub>	Fixed delault	DEF_1 = Low 1.125 V	I <sub>OUT1</sub>	1000 1114	
	V <sub>OUT2</sub>		Fixed default 1.2 V	I <sub>OUT2</sub>	400 mA	
	M	Fixed default	DEF_1 = High 1.225 V	I	400 mA	
TPS62407-Q1	V <sub>OUT1</sub>	Fixed delault	DEF_1 = Low 1.225 V	I <sub>OUT1</sub>	400 MA	
	V <sub>OUT2</sub>		Fixed default 1.85 V		600 mA	
	V <sub>OUT1</sub>	Fixed default	DEF_1 = High 1.8 V	I	1000 mA	
TPS62422-Q1		VOUT1	VOUT1	Fixed delault	DEF_1 = Low 1.15 V	I <sub>OUT1</sub>
	V <sub>OUT2</sub>		Fixed default 1.2V	I <sub>OUT2</sub>	600 mA	
	M	Fixed default	DEF_1 = High 1.5 V	I	800 mA	
TPS62423-Q1	V <sub>OUT1</sub>	Fixed delault	DEF_1 = Low 1.2 V	I <sub>OUT1</sub>	000 MA	
	V <sub>OUT2</sub>		Fixed default 1.8V		800 mA	
	M	Fixed default	DEF_1 = High 1.3 V	I	800 mA	
TPS62424-Q1	V <sub>OUT1</sub>	DEF_1 = Low 1.1 V	I <sub>OUT1</sub>	000 IIIA		
	V <sub>OUT2</sub>		Fixed default 1.8V	I <sub>OUT2</sub>	800 mA	

## **6** Pin Configuration and Functions



#### Figure 6-1. DRC Package 10-Pin VSON With Thermal Pad Top View

#### Table 6-1. Pin Functions

PIN	PIN I/O		DESCRIPTION		
NAME	NO.	1/0	DESCRIPTION		
ADJ2	1	I	Output voltage sense pin for the internal feedback divider. This pin must connect directly to the output. If using the EasyScale interface-on converter 2, this pin must also connect directly to the output.		
DEF_1	DEF_1 5 I This pin defines the output voltage of converter 1 and is a digital input, that selects between two fixed default output voltages. See Section 5 for output voltage setting of the different device options. For TPS62406-Q1 and TPS62407-Q1 the output voltage is same independent of DEF_1 pin level. This pin must be terminated.		default output voltages. See <u>Section 5</u> for output voltage setting of the different device options. For TPS62406-Q1 and TPS62407-Q1 the output voltage is same independent of DEF_1 pin level. This pin		
EN1	7	I	Enable input for converter 1, active-high. This pin must be terminated.		
EN2	EN2 9 I Enable input for converter 2, active-high. This pin must be terminated.		Enable input for converter 2, active-high. This pin must be terminated.		
FB1 4 I Output voltage sense pin for the internal feedback divider. This pin is connected to the output.		Output voltage sense pin for the internal feedback divider. This pin is connected to the output.			
GND	8		GND for both converters; connect this pin to the thermal pad.		



#### Table 6-1. Pin Functions (continued)

PIN NAME NO.		1/0	DESCRIPTION	
			DESCRIPTION	
			This pin has two functions:	
MODE/DATA	2	1/0	<ol> <li>Operation-mode selection: With low level, enables power-save mode where the device operates in PFM mode at light loads and automatically enters PWM mode at heavy loads. Pulling this PIN to high forces the device to operate in PWM mode over the whole load range.</li> </ol>	
	_		2. EasyScale interface function: One-wire serial interface to change the output voltage of both converters. The pin has an open-drain output to provide an acknowledge condition if requested. The current into the open-drain output stage may not exceed 500 µA. The EasyScale interface is active if either EN1 or EN2 is high.	
SW1	6	I/O	Switch pin of converter 1. Connect to inductor	
SW2	10	I/O	Switch pin of converter 2. Connect to inductor	
VIN 3		I	Input pin, connect to supply or battery voltage, 2.5 V to 6 V. Connect the input capacitor $C_{IN}$ as close as possible between VIN pin and GND pin.	
Thermal pad		_	Connect to GND	



## **7** Specifications

#### 7.1 Absolute Maximum Ratings

over operating junction temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
Input voltage <sup>(2)</sup>	VIN	-0.3	7	V
	EN, MODE/DATA, DEF_1	-0.3	$V_{\sf IN} + 0.3, \le 7$	V
Voltage <sup>(2)</sup>	SW1, SW2	-0.3	7	V
	ADJ2, FB1	-0.3	$V_{\sf IN} + 0.3, \le 7$	V
Current	MODE/DATA		≤ 0.5	mA
Maximum operating junction temp	perature, T <sub>J</sub> max		150	°C
Storage temperature, T <sub>stg</sub>		-65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to the network ground terminal.

#### 7.2 ESD Ratings

				VALUE	UNIT
		Human body model (HBM), per AEC Q10	0-002 <sup>(1)</sup>	±2000	V
V <sub>(ESD)</sub> Electrostatic discharge	Charged device model (CDM), per AEC	All pins	±500	V	
	discharge	Q100-011	Corner pins (1, 5, 6, and 10)	±750	v

(1) AEC Q100-002 indicates HBM stressing is done in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

#### 7.3 Recommended Operating Conditions

over operating junction temperature range (unless otherwise noted)

		MIN	MAX	UNIT
VII	N Supply voltage	2.5	6	V
TJ	Operating junction temperature	-40	125	°C

### 7.4 Thermal Information

		TPS624xx-Q1	
	THERMAL METRIC <sup>(1)</sup>	DRC (VSON)	UNIT
		10 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	42.7	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	46.9	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	18.1	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	0.5	°C/W
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	18.3	°C/W
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	3.1	°C/W

 For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

#### 7.5 Electrical Characteristics

 $V_{IN}$  = 3.6 V, EN1 = EN2 =  $V_{IN}$ , MODE = GND, L1 = L2 = 2.2  $\mu$ H,  $C_{OUT1}$  =  $C_{OUT2}$  = 20  $\mu$ F,  $T_{J}$  = -40°C to 125°C, typical values are at  $T_{J}$  = 25°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT
SUPPLY CURRENT						
V <sub>IN</sub> Input volt	age range		2.5		6	V

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 $V_{IN}$  = 3.6 V, EN1 = EN2 =  $V_{IN}$ , MODE = GND, L1 = L2 = 2.2 µH,  $C_{OUT1}$  =  $C_{OUT2}$  = 20 µF,  $T_J$  = -40°C to 125°C, typical values are at  $T_J$  = 25°C (unless otherwise noted)

	PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
			One converter, no load on the output. PFM mode enabled (MODE/DATA = GND) device not switching, EN1 = 1 or EN2 = 1		19	35	
IQ	Operating quiescent current		Two converters, no load on the output. PFM mode enabled (MODE/DATA = GND) device not switching, EN1 = EN2 = 1		32	50	μA
			No load on the output, MODE/DATA = GND, for one converter $^{(1)}$		23		
			No load on the output, MODE/DATA = V <sub>IN</sub> , for one converter <sup>(1)</sup>		3.6		mA
	Obuitdaum aumant		EN1, EN2 = GND, V <sub>IN</sub> = 3.6 V <sup>(2)</sup>		1.2	3	
I <sub>SD</sub>	Shutdown current		EN1, EN2 = GND, $V_{IN}$ ramped from 0 V to 3.6 V <sup>(3)</sup>		0.1	1.5	μA
V <sub>UVLO</sub>	Undervoltage lockout th	reshold	Falling		1.5	2.35	V
			Rising			2.4	
				1.0		V	V
V <sub>IH</sub>	High-level input voltage	-		1.2		V <sub>IN</sub>	V V
VIL	Low-level input voltage		EN1 EN2 = GND or V	0	0.05	0.4	
	Input bias current, EN1,	EINZ	EN1, EN2 = GND or V <sub>IN</sub>		0.05	1	μA
DEF_1 INPU		input voltago rongo		0.9		V	V
V <sub>DEF_1H</sub>	DEF_1 high-level digital		-	0.9		V <sub>IN</sub> 0.4	V
V <sub>DEF_1L</sub>	DEF_1 low-level digital Input bias current DEF	· · · ·	DEF_1 = GND or V <sub>IN</sub>	0	0.01	0.4	ν μA
IIN MODE/DAT		- <sup>1</sup>			0.01	'	μΑ
V <sub>IH</sub>	High-level input voltage			1.2		V <sub>IN</sub>	V
V <sub>IL</sub>	Low-level input voltage	-		0		0.4	V
	Input bias current, MOD	-	MODE/DATA = GND or V <sub>IN</sub>	0	0.01	1	μA
I <sub>IN</sub> V <sub>OH</sub>	•		Open drain, through external pullup resistor		0.01		μA V
V <sub>OL</sub>	Acknowledge output voltage high Acknowledge output voltage low		Open drain, sink current 500 µA	0		0.4	V
	<b>v</b> 1	lage low		0		0.4	v
r <sub>DS(on)</sub>	P-channel MOSFET on 1 and 2	-resistance, converter	V <sub>IN</sub> = V <sub>GS</sub> = 3.6 V		280	620	mΩ
ILK PMOS	P-channel leakage curre	ent	V <sub>DS</sub> = 6 V			1	μA
r <sub>DS(on)</sub>	N-channel MOSFET on 1 and 2	-resistance converter	V <sub>IN</sub> = V <sub>GS</sub> = 3.6 V		200	450	mΩ
I <sub>LK_SW1/SW2</sub>	Leakage current into SV	V1 or SW2 pin	Includes N-channel leakage current, $V_{IN}$ = open, $V_{SW}$ = 6 V, EN = GND <sup>(4)</sup>		6	7.5	μA
		TPS62406-Q1 V <sub>OUT1</sub>	$2.5 \text{ V} \le \text{V}_{\text{IN}} \le 6 \text{ V}$	1.18	1.4	1.61	
		TPS62406-Q1 V <sub>OUT2</sub>	$2.5 \text{ V} \le \text{V}_{\text{IN}} \le 6 \text{ V}$	0.68	0.8	0.92	
		TPS62407-Q1 V <sub>OUT1</sub>	$2.5 \text{ V} \le \text{V}_{\text{IN}} \le 6 \text{ V}$	0.68	0.8	0.92	
		TPS62407-Q1 V <sub>OUT2</sub>	$2.5 \text{ V} \le \text{V}_{\text{IN}} \le 6 \text{ V}$	0.75	1	1.15	
hur	Forward current limit	TPS62422-Q1 V <sub>OUT1</sub>	$2.5 \text{ V} \le \text{V}_{\text{IN}} \le 6 \text{ V}$	1.18	1.4	1.61	А
ILIMF	PMOS and NMOS	TPS62422-Q1 V <sub>OUT2</sub>	$2.5 \text{ V} \leq \text{V}_{\text{IN}} \leq 6 \text{ V}$	0.75	1	1.15	~
		TPS62423-Q1 V <sub>OUT1</sub>	$2.5 \text{ V} \le \text{V}_{\text{IN}} \le 6 \text{ V}$	1	1.2	1.38	
		TPS62423-Q1 V <sub>OUT2</sub>	$2.5 \text{ V} \le \text{V}_{\text{IN}} \le 6 \text{ V}$	1	1.2	1.38	
		TPS62424-Q1 V <sub>OUT1</sub>	$2.5 \text{ V} \le \text{V}_{\text{IN}} \le 6 \text{ V}$	1	1.2	1.38	
		TPS62424-Q1 V <sub>OUT2</sub>	$2.5 \text{ V} \leq \text{V}_{\text{IN}} \leq 6 \text{ V}$	1	1.2	1.38	

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# $V_{IN}$ = 3.6 V, EN1 = EN2 = $V_{IN}$ , MODE = GND, L1 = L2 = 2.2 $\mu$ H, $C_{OUT1}$ = $C_{OUT2}$ = 20 $\mu$ F, $T_J$ = -40°C to 125°C, typical values are at $T_J$ = 25°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
T <sub>SD</sub>	Thermal shutdown	Increasing junction temperature		150		°C
	Thermal shutdown hysteresis	Decreasing junction temperature		20		°C
OUTPUT						
V <sub>ref</sub>	Internal Reference voltage			600		mV
V <sub>OUTx(PFM)</sub>		$\begin{array}{l} \mbox{Voltage positioning active,} \\ \mbox{MODE/DATA} = \mbox{GND,} \\ \mbox{device operating in PFM mode,} \\ \mbox{V}_{IN} = 2.5 \mbox{ V to 5 } V^{(5)} \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	-1.5%	1%	2.5%	
V <sub>OUTx(PWM)</sub>	DC output voltage accuracy	$\begin{array}{l} \mbox{MODE/DATA} = \mbox{GND}; \\ \mbox{device operating in PWM mode}, \\ \mbox{V}_{IN} = 2.5 \mbox{ V to 6 } V^{(6)} \end{array}$	-1%	0%	1%	
		$ \begin{aligned} & V_{\text{IN}} = 2.5 \text{ V to } 6 \text{ V, MODE/DATA} = V_{\text{IN}}, \\ & \text{Fixed PWM operation,} \\ & 0 \text{ mA} < I_{\text{OUT1}} < 400 \text{ mA}; 0 \text{ mA} < I_{\text{OUT2}} < 600 \text{ mA}^{(7)} \end{aligned} $	-1%	0%	1%	
	DC output voltage load regulation	PWM operation mode			0.5	%/A

(1) Device is switching with no load on the output,  $L1 = L2 = 3.3 \mu$ H, value includes losses of the coil.

(2) These values are valid after enabling the device one time (EN1 or EN2 = high) and maintaining supply voltage  $V_{|N}$ .

(3) These values are valid when the device is disabled (EN1 and EN2 low) and supply voltage V<sub>IN</sub> is powered up. The values remain valid until enabling the device the first time (EN1 or EN2 = high). After the first enable, Note 3 becomes valid.

(4) An internal resistor of 1 M $\Omega$  connects pins SW1 and SW2 to GND.

(5) Configuration L1 or L2 typ. 2.2 μH, C<sub>OUTx</sub> typ 20 μF. See parameter measurement information, the output voltage ripple in PFM mode depends on the effective capacitance of the output capacitor; larger output capacitors lead to tighter output voltage tolerance.

(6) In power-save mode, the device typically enters PWM operation at  $I_{PSM} = V_{IN} / 32 \Omega$ .

(7) For  $V_{OUTx} > 2 V$ ,  $V_{IN} min = V_{OUTx} + 0.5 V$ 



## 7.6 Timing Requirements

			MIN	NOM MAX	UNIT
INTERFA	CE TIMING				
t <sub>Start</sub>	Start time		2		μs
t <sub>H_LB</sub>	High-time low bit, logic 0 detection	Signal level on MODE/DATA pin is > 1.2 V	2	200	μs
t <sub>L_LB</sub>	Low-time low bit, logic 0 detection	Signal level on MODE/DATA pin < 0.4 V	2 x t <sub>H_LB</sub>	400	μs
t <sub>L_HB</sub>	Low-time high bit, logic 1 detection	Signal level on MODE/DATA pin < 0.4 V	2	200	μs
t <sub>H_HB</sub>	High-time high bit, logic 1 detection	Signal level on MODE/DATA pin is > 1.2 V	2 x t <sub>L_HB</sub>	400	μs
t <sub>EOS</sub>	End of stream		2		μs
t <sub>ackn</sub>	Duration of acknowledge condition (MODE/DATE line pulled low by the device)	V <sub>IN</sub> 2.5 V to 6 V	400	520	μs
t <sub>valACK</sub>	Acknowledge valid time			2	μs
t <sub>timeout</sub>	Time-out for entering power-save mode	MODE/DATA pin changes from high to low		520	μs

### 7.7 Switching Characteristics

 $V_{IN}$  = 3.6 V, EN1 = EN2 =  $V_{IN}$ , MODE = GND, L1 = L2 = 2.2 µH,  $C_{OUT1}$  =  $C_{OUT2}$  = 20 µF,  $T_J$  = -40°C to 125°C, typical values are at  $T_J$  = 25°C (unless otherwise noted)

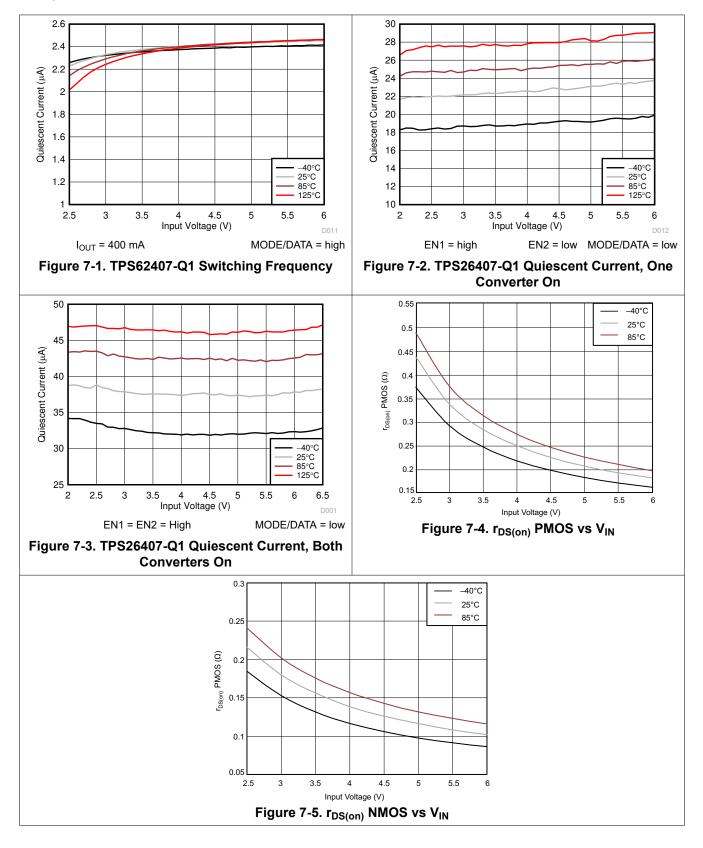
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT		
OSCILLATOR								
f <sub>SW</sub>	Oscillator frequency	$3 V \le V_{\rm IN} \le 6 V^{(1)}$	2	2.25	2.7	MHz		
OUTPUT								
t <sub>Start up</sub>	Start-up time	Activation time to start switching <sup>(2)</sup>		170		μs		
t <sub>Ramp</sub>	V <sub>OUTx</sub> ramp-up time	Time to ramp from 5% to 95% of V <sub>OUTx</sub>	750			μs		

(1) For  $V_{OUTx} > 2 V$ ,  $V_{IN} min = V_{OUTx} + 0.5 V$ 

(2) This time is valid if one converter turns from shutdown mode (EN2 = 0) to active mode (EN2 = 1) with the other converter already enabled (for example, EN1 = 1). In case both converters are turned from shutdown mode (EN1 and EN2 = 0) to active mode (EN1 and/or EN2 = 1), a typical value of typ 80 µs for ramp up of internal circuits must be added. After t<sub>Start</sub>, the converter starts switching and ramps V<sub>OUTx</sub>.



### 7.8 Typical Characteristics



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## 8 Detailed Description

#### 8.1 Overview

The TPS624xx-Q1 device includes two synchronous step-down converters. The converters operate with typically 2.25-MHz fixed-frequency pulse-width modulation (PWM) at moderate to heavy load currents. With the power-save mode enabled, the converters automatically enter power-save mode at light load currents and operate in PFM (pulse frequency modulation).

During PWM operation, the converters use a unique fast-response voltage-mode controller scheme with inputvoltage feed-forward to achieve good line and load regulation, allowing the use of small ceramic input and output capacitors. At the beginning of each clock cycle initiated by the clock signal, the P-channel MOSFET switch turns on and the inductor current ramps up until the comparator trips and the control logic turns off the switch.

Each converter integrates two current limits, one in the P-channel MOSFET and another one in the N-channel MOSFET. When the current in the P-channel MOSFET reaches its current limit, the P-channel MOSFET turns off and the N-channel MOSFET turns on. If the current in the N-channel MOSFET is above the N-MOS current limit threshold, the N-channel MOSFET remains on until the current drops below its current limit.

The two DC-DC converters operate synchronized to each other. A 180° phase shift between converter 1 and converter 2 decreases the input rms current.

#### 8.1.1 Converter 1

It is possible to change the output voltage of converter 1 with the EasyScale serial Interface. This makes the device very flexible for output-voltage adjustment. In this case, the device uses an internal resistor network.

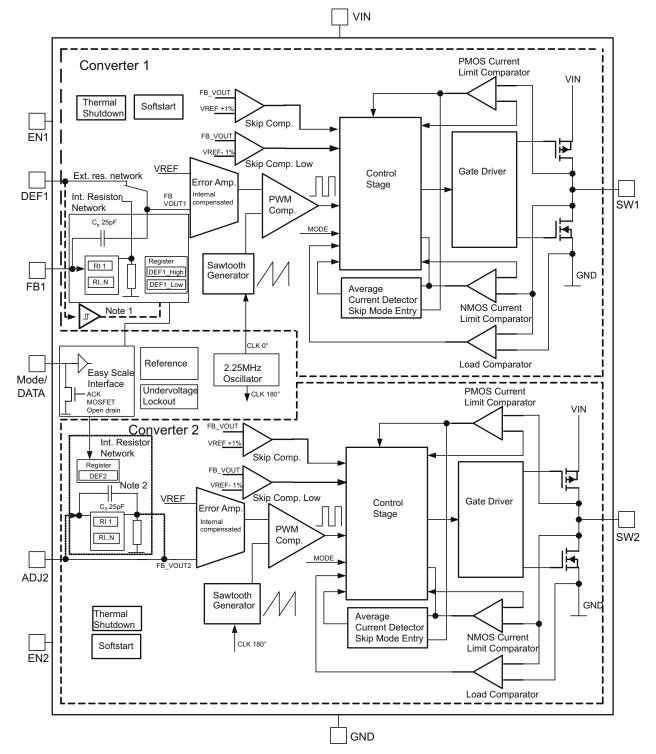
The output voltage can also be selected using the DEF\_1 pin configuration as a digital input. For these voltage version the DEF\_1 pin select the same output voltage for DEF\_1=high or DEF\_1=low.

#### 8.1.2 Converter 2

It is also possible to change the output voltage of converter 2 via the EasyScale interface.



#### 8.2 Functional Block Diagram



A. In the fixed output-voltage version, the DEF\_1 pin connects to an internal digital input and disconnects from the error amplifier.

B. To set the output voltage of converter 2 through the EasyScale<sup>TM</sup> interface, the ADJ2 pin must directly connect to V<sub>OUT2</sub>.



#### 8.3 Feature Description

#### 8.3.1 Enable

The device has a separate EN pin for each converter to start up each converter independently. If EN1 or EN2 is set to high, the corresponding converter starts up with soft start.

Pulling EN1 and EN2 pin low forces the device into shutdown, with a shutdown quiescent current of typically 1.2  $\mu$ A. In this mode, the P- and N-channel MOSFETs turn off and the entire internal control circuitry switches off. For proper operation, terminate the EN1 and EN2 pins, do not leave them floating.

#### 8.3.2 DEF\_1 Pin Function

The DEF\_1 pin, dedicated to converter 1, makes the output voltage selection very flexible to support dynamic voltage management. Having this pin tied to a low level sets the output voltage according to the value in register REG\_DEF\_1\_Low. The default voltage is 1.125 V for TPS62406-Q1. Having the pin tied to a high level sets the output voltage according to the value in register REG\_DEF\_1\_High. The default value in this case is 1.125 V as well. The level of the DEF\_1 pin selects between the two registers, REG\_DEF\_1\_Low and REG\_DEF\_1\_High, for the output-voltage setting. One can change the content of each register (and therefore output voltage) individually through the EasyScale interface. This makes the device very flexible in terms of output voltage setting; see Table 8-3

#### 8.3.3 180° Out-of-Phase Operation

In PWM mode, the converters operate with a 180° turn-on phase shift of the PMOS (high side) transistors. This prevents the high-side switches of both converters from turning on simultaneously, reducing the input current ripple. This feature reduces the surge current drawn from the supply.

#### 8.3.4 Short-Circuit Protection

Both outputs are short-circuit protected with maximum output current =  $I_{LIMF}$ (P-MOS and N-MOS). Once the PMOS switch reaches its current limit, it turns off and the NMOS switch turns on. The PMOS only turns on again once the current in the NMOS decreases below the NMOS current limit.

#### 8.3.5 Thermal Shutdown

As soon as the junction temperature,  $T_J$ , exceeds 150°C (typical) the device goes into thermal shutdown. In this mode, the P- and N-channel MOSFETs turn off. The device continues its operation when the junction temperature falls below the thermal-shutdown hysteresis.

#### 8.3.6 EasyScale Interface: One-Pin Serial Interface for Dynamic Output-Voltage Adjustment

#### 8.3.6.1 General

The EasyScale interface is a simple but very flexible one-pin interface to configure the output voltage of both DC-DC converters. A master-slave structure is the basis of the interface, where the master is typically a microcontroller or application processor. Figure 8-3 and Table 8-2 give an overview of the protocol. The protocol consists of a device-specific address byte and a data byte. The device-specific address byte is fixed to 4E hex. The data byte consists of five bits for information, two address bits, and the RFA bit. The RFA bit set to high indicates the request-for-acknowledge condition. The acknowledge condition only applies after correct reception of the protocol.

The advantage of the EasyScale interface compared to other one-pin interfaces is that its bit detection is to a large extent independent from the bit transmission rate. It can automatically detect bit rates between 1.7 kb/s and up to 160 kb/s. Furthermore, the interface shares the MODE/DATA pin and requires no additional pin.

#### 8.3.6.2 Protocol

Transmission of all bits is MSB first and LSB last. Figure 8-4 shows the protocol without the acknowledge request (bit RFA = 0), Figure 8-5 with the acknowledge request (bit RFA = 1).

Prior to both bytes, device address byte and data byte, one must apply a start condition. For this, pull the MODE/ DATA pin high for at least t<sub>Start</sub> before the bit transmission starts with the falling edge. In case the MODE/DATA



line was already at a high level (forced PWM mode selection), the device requires no start condition prior to the device address byte.

Close the transmission of each byte with an end-of-stream condition for at least  $t_{EOS}$ .

#### 8.4 Device Functional Modes

#### 8.4.1 Power-Save Mode

Setting the MODE/DATA pin to low for both converters enables power-save mode. If the load current of a converter decreases, this converter enters power-save-mode operation automatically. The transition of a converter to power-save mode is independent from the operating condition of the other converter. During power-save mode, the converter operates with reduced switching frequency in PFM mode and with a minimum quiescent current to maintain high efficiency. The converter positions the output voltage in PFM mode to typically 1% above nominal  $V_{OUTx}$ . This voltage positioning feature minimizes voltage drops caused by a sudden load step.

In order to optimize the converter efficiency at light load, the device monitors average inductor current. The device changes from PWM mode to power-save mode if in PWM mode the inductor current falls below a certain threshold. The typical output current threshold, which one can calculate using Equation 1 for each converter, depends on  $V_{IN}$ .

Equation 1: Average output current threshold to enter PFM mode

$$I_{OUT\_PFM\_enter} = \frac{VIN_{DCDC}}{32 \Omega}$$
(1)

Equation 2: Average output current threshold to leave PFM mode

$$I_{OUT\_PFM\_leave} = \frac{VIN_{DCDC}}{24 \Omega}$$
(2)

To keep the output-voltage ripple in power-save mode low, a single threshold comparator (skip comparator) monitors the output voltage. As the output voltage falls below the skip-comparator threshold (skip comp) of 1% above nominal  $V_{OUTx}$ , the corresponding converter starts switching for a minimum time period of typically 1 µs and provides current to the load and the output capacitor. Therefore, the output voltage increases and the device maintains switching until the output voltage trips the skip comparator threshold (skip comp) again. At this moment, all switching activity stops and the quiescent current reduces to minimum. The output capacitor supplies the load until the output voltage has dropped below the threshold again. Hereupon, the device starts switching again.

The converter leaves power-save mode and enters PWM mode if the output current exceeds the  $I_{OUT\_PFM\_leave}$  current or if the output voltage falls below a second comparator threshold, called the skip-comparator-low (Skip Comp Low) threshold. This skip-comparator-low threshold is 2% below nominal  $V_{OUTx}$  and enables a fast transition from power-save mode to PWM mode during a load step.

Power-save mode typically reduces the quiescent current to 19  $\mu$ A for one converter and 32  $\mu$ A for both converters active. This single-skip comparator threshold method in power-save mode results in a very low output-voltage ripple. The ripple depends on the comparator delay and the size of the output capacitor. Increasing output capacitor values minimizes the output ripple. One can disable the power-save mode by setting the MODE/DATA pin to high. Both converters then operate in fixed PWM mode. Power-save mode enable or disable applies to both converters.

#### 8.4.1.1 Dynamic Voltage Positioning

This feature reduces the voltage under- and overshoots at load steps from light to heavy load and from heavy to light load. Power-save-mode operation activates dynamic voltage positioning and provides more headroom for both the voltage drop at a load step and the voltage increase when a load is switched off, which improves load-transient behavior.

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At light loads, in which the converter operates in PFM mode, the output voltage regulation is typically 1% higher than the nominal value. In case of a load transient from light load to heavy load, the output voltage drops until it reaches the skip comparator low threshold set to 2% below the nominal value and enters PWM mode. During a load transition from heavy load to light load, the device also minimizes voltage overshoot because of active regulation turning on the N-channel switch.

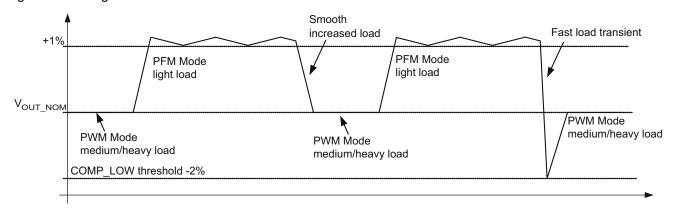
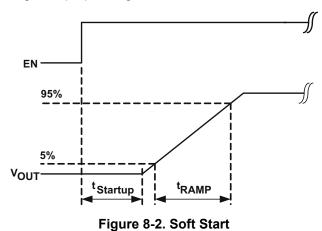


Figure 8-1. Dynamic Voltage Positioning

#### 8.4.1.2 Soft Start

The two converters have an internal soft-start circuit that limits the inrush current during startup. Figure 8-2 shows control of the output-voltage ramp-up during soft start.



#### 8.4.1.3 100% Duty-Cycle Low-Dropout Operation

The converters offer a low input-to-output voltage difference while still maintaining operation with the use of the 100% duty-cycle mode. In this mode, the P-channel switch is constantly on. This is particularly useful in battery-powered applications to achieve longest operation time by taking full advantage of the whole battery-voltage range. The minimum input voltage to maintain regulation depends on the load current and output voltage, which one can calculate as:

$$Vin_{min} = Vout_{max} + Iout_{max} \times (RDSon_{max} + R_L)$$

with

- I<sub>OUTxmax</sub> = maximum output current plus inductor ripple current
- r<sub>DS(on)max</sub> = maximum P-channel switch r<sub>DS(on)</sub>
- $R_L = dc$  resistance of the inductor
- V<sub>OUTxmax</sub> = nominal output voltage plus maximum output-voltage tolerance

(3)



With decreasing load current, the device automatically switches into pulse-skipping operation, in which the power stage operates intermittently based on load demand. Running cycles periodically minimizes the switching losses, and the device runs with a minimum quiescent current, maintaining high efficiency.

#### 8.4.1.4 Undervoltage Lockout

The undervoltage lockout circuit prevents the device from malfunction at low input voltages and from excessive discharge of the battery, and disables the converters. The undervoltage lockout threshold is typically 1.5 V; maximum of 2.35 V. In case the interface overwrites the default register values, the new values in the registers REG\_DEF\_1\_High, REG\_DEF\_1\_Low and REG\_DEF\_2 remain valid as long the supply voltage does not fall below the undervoltage lockout threshold, independent of disabling of the converters.

#### 8.4.2 Mode Selection

The MODE/DATA pin allows mode selection between forced PWM mode and power-save mode for both converters. Furthermore, this pin is a multipurpose pin and provides (besides mode selection) a one-pin interface to receive serial data from a host to set the output voltage, as described in the *EasyScale Interface* section.

Connecting this pin to GND enables the automatic PWM and power-save-mode operation. The converters operate in fixed-frequency PWM mode at moderate-to-heavy loads, and in the PFM mode during light loads, maintaining high efficiency over a wide load-current range.

Pulling the MODE/DATA pin high forces both converters to operate constantly in the PWM mode, even at light load currents. The advantage is that the converters operate with a fixed frequency, allowing simple filtering of the switching frequency for noise-sensitive applications. In this mode, the efficiency is lower compared to the power-save mode during light loads. For additional flexibility, it is possible to switch from power-save mode to forced PWM mode during operation. This allows efficient power management by adjusting the operation of the converter to the specific system requirements.

In the case of changing the operation mode from forced PWM mode (MODE/DATA = high) to power-save mode (MODE/DATA = 0), enabling the power-save mode occurs after a delay time of  $t_{timeout}$ , which is 520 µs maximum.

Setting the MODE/DATA to 1 enables forced-PWM-mode operation immediately.

#### 8.5 Programming

#### 8.5.1 Addressable Registers

Three registers with a data content of 5 bits are addressable. With 5-bit data content, 32 different values for each register are available. Table 8-1 shows the addressable registers to set the output voltage when the DEF\_1 pin works as a digital input. In this case, converter 1 has a related register for each DEF\_1 pin condition, and one register for converter 2. A high or low condition on pin DEF\_1 selects either the content of register REG\_DEF\_1\_High or REG\_DEF\_1\_Low, thus setting the output voltage of converter 1 according to the values in Selectable Output Voltage Converter 1, With Pin DEF\_1 as Digital Input. Use of a precise internal resistor divider network to generate these output voltages makes external resistors unnecessary (less board space) and provides higher output-voltage accuracy. Enabling at least one of the converters (EN1 or EN2 is high) activates the interface. After the startup time  $t_{Start}$  (170 µs), the interface is ready for data reception.

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DEVICE	REGISTER	DESCRIPTION	DEF_1 PIN	A1	A0	D4	D3	D2	D1	D0
	REG_DEF_1_High	Converter 1 output voltage setting for DEF_1 = High condition. The content of the register is active with the DEF_1 pin high.	High	0	1	Output voltage setting, see Ta			able 8-3	
TPS624xx-Q1,	REG_DEF_1_Low	Converter 1 output voltage setting for DEF_1 = Low condition.	Low	0	0	Output voltage setting, see Tab				able 8-3
	REG_DEF_2	Converter 2 output voltage	Not applicable	1	0	Output voltage setting, see			, see Ta	able 8-4
		Do not use		1	1					



#### 8.5.1.1 Bit Decoding

The bit detection is based on a PWM scheme, where the criterion is the relation between the low time and high time of the low or high bit ( $t_{L xB}$  and  $t_{H xB}$ ). Bit detection can be simplified to:

High bit:  $t_{H HB} > t_{L HB}$ , but with  $t_{H HB}$  at least 2×  $t_{L HB}$ , see Figure 8-3.

Low bit:  $t_{L B} > t_{H LB}$ , but with  $t_{L B}$  at least 2×  $t_{H LB}$ , see Figure 8-3.

The bit detection starts with a falling edge on the MODE/DATA pin and ends with the next falling edge. Detection of a 0 or 1 depends on the relation between  $t_{L xB}$  and  $t_{H xB}$ .

#### 8.5.1.2 Acknowledge

The device only applies the acknowledge condition if all of the following occurs:

- A set RFA bit requests an acknowledge
- The transmitted device address matches with the device address of the device
- Correct reception of 16 bits occurred

In this case, the device turns on the internal ACKN-MOSFET and pulls the MODE/DATA pin low for the time  $t_{ACKN}$ , which is 520 µs maximum. The acknowledge condition is valid after an internal delay time  $t_{valACK}$ . This means the internal ACKN-MOSFET turns on after  $t_{valACK}$ , on detection of the last falling edge of the protocol. The master controller keeps the line low during this time.

The master device can detect the acknowledge condition with its input by releasing the MODE/DATA pin after  $t_{valACK}$  and reading back a 0.

In case of an invalid device address, or not-correctly-received protocol, application of a no-acknowledge condition does not occur; thus, the internal MOSFET does not turn on, and the external pullup resistor pulls the MODE/DATA pin high after  $t_{valACK}$ . One can use the MODE/DATA pin again after the acknowledge condition ends.

#### Note

The master device must have an open-drain output in order to request the acknowledge condition.

In case of a push-pull output stage, TI recommends using a series resistor in the MODE/DATA line to limit the current to 500 µA in case of an accidentally requested acknowledge, to protect the internal ACKN-MOSFET.

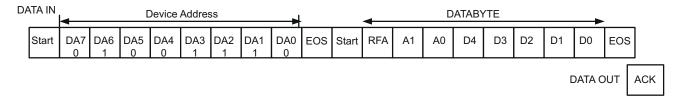
#### 8.5.1.3 Mode Selection

Use of the MODE/DATA pin for two functions, interface and mode selection, necessitates a determination of when to decode the bit stream or to change the operation mode.

The device enters forced PWM mode operation immediately whenever the MODE/DATA pin turns to high level. The device also stays in forced PWM mode during the entire protocol reception time.

With a falling edge on the MODE/DATA pin, the device starts bit decoding. If the MODE/DATA pin stays low for at least  $t_{timeout}$ , the device gets an internal time-out and enables power-save-mode operation.

The device ignores a protocol sent within this time because the first interpretation of a falling edge for the mode change is at the start of the first bit. In this case, TI recommends sending the protocol first, and then changing to power-save mode at the end of the protocol.







## Table 8-2. EasyScale Bit Description

BYTE	BIT NUMBER	NAME	TRANSMISSION DIRECTION	DESCRIPTION
Device	7	DA7	IN	0 MSB device address
address byte	6	DA6	IN	1
5 yie	5	DA5	IN	0
	4	DA4	IN	0
4E hex	3	DA3	IN	1
	2	DA2	IN	1
	1	DA1	IN	1
	0	DA0	IN	0 LSB device address
Data byte	7 (MSB)	RFA	IN	Request for acknowledge; if high, the device applies an acknowledge condition.
	6	A1		Address bit 1
	5	A0		Address bit 0
	4	D4		Data bit 4
	3	D3		Data bit 3
	2	D2		Data bit 2
	1	D1		Data bit 1
	0 (LSB)	D0		Data bit 0
		ACK	OUT	Acknowledge condition active 0, the device applies this condition only in the case of a set RFA bit. Open-drain output, the host must pull the line high with a pullup resistor.
				One can only use this feature if the master has an open-drain output stage. In case of a push-pull output stage, do not request an acknowledge condition.

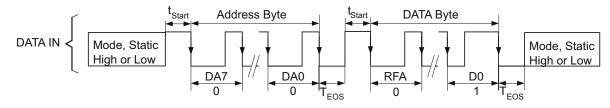
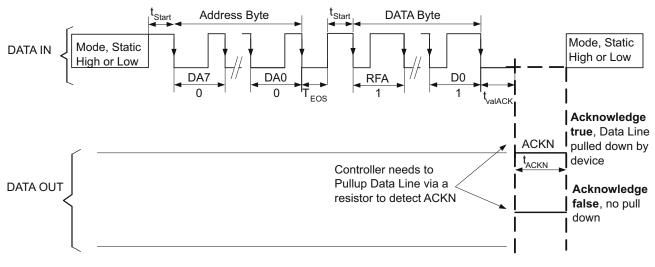


Figure 8-4. EasyScale Protocol Without Acknowledge







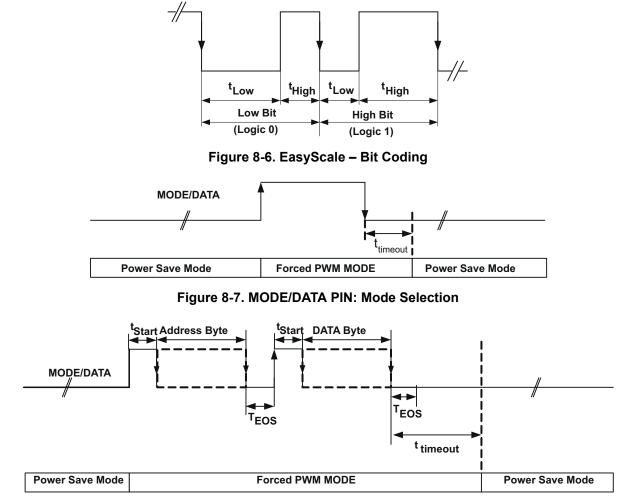


Figure 8-8. MODE/DATA Pin: Power-Save-Mode and Interface Communication

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#### Table 8-3. Selectable Output Voltages for Converter 1, With Pin DEF\_1 as Digital Input

	With Pin DEF_1 as Digital Input									
	TPS624xx-Q1 OUTPUT VOLTAGE [V] REGISTER REG_DEF_1_LOW	TPS624xx-Q1 VOLTAGE [V] REGISTER REG_DEF_1_HIGH	D4	D3	D2	D1	D0			
0	0.8	0.9	0	0	0	0	0			
1	0.825	0.925	0	0	0	0	1			
2	0.85	0.95	0	0	0	1	0			
3	0.875	0.975	0	0	0	1	1			
4	0.9	1.0	0	0	1	0	0			
5	0.925	1.025	0	0	1	0	1			
6	0.95	1.050	0	0	1	1	0			
7	0.975	1.075	0	0	1	1	1			
8	1.0	1.1	0	1	0	0	0			
9	1.025	1.125	0	1	0	0	1			
10	1.050	1.150	0	1	0	1	0			
11	1.075	1.175	0	1	0	1	1			
12	1.1	1.2	0	1	1	0	0			
13	1.125	1.225	0	1	1	0	1			
14	1.150	1.25	0	1	1	1	0			
15	1.175	1.275	0	1	1	1	1			
16	1.2	1.3	1	0	0	0	0			
17	1.225	1.325	1	0	0	0	1			
18	1.25	1.350	1	0	0	1	0			
19	1.275	1.375	1	0	0	1	1			
20	1.3	1.4	1	0	1	0	0			
21	1.325	1.425	1	0	1	0	1			
22	1.350	1.450	1	0	1	1	0			
23	1.375	1.475	1	0	1	1	1			
24	1.4	1.5	1	1	0	0	0			
25	1.425	1.525	1	1	0	0	1			
26	1.450	1.55	1	1	0	1	0			
27	1.475	1.575	1	1	0	1	1			
28	1.5	1.6	1	1	1	0	0			
29	1.525	1.7	1	1	1	0	1			
30	1.55	1.8	1	1	1	1	0			
31	1.575	1.9	1	1	1	1	1			



Table 8-4. Selectable Output Voltages for Converter 2,	
$(ADI2 Connected to V_{outp})$	

	(ADJ2 Connected to V <sub>OUT2</sub> ) OUTPUT VOLTAGE [V] FOR REGISTER REG_DEF_2	D4	D3	D2	D1	D0
0	0.6	0	0	0	0	0
1	0.85	0	0	0	0	1
2	0.9	0	0	0	1	0
3	0.95	0	0	0	1	1
4	1	0	0	1	0	0
5	1.05	0	0	1	0	1
6	1.1	0	0	1	1	0
7	1.15	0	0	1	1	1
8	1.2	0	1	0	0	0
9	1.25	0	1	0	0	1
10	1.3	0	1	0	1	0
11	1.35	0	1	0	1	1
12	1.4	0	1	1	0	0
13	1.45	0	1	1	0	1
14	1.5	0	1	1	1	0
15	1.55	0	1	1	1	1
16	1.6	1	0	0	0	0
17	1.7	1	0	0	0	1
18	1.8	1	0	0	1	0
19	1.85	1	0	0	1	1
20	2	1	0	1	0	0
21	2.1	1	0	1	0	1
22	2.2	1	0	1	1	0
23	2.3	1	0	1	1	1
24	2.4	1	1	0	0	0
25	2.5	1	1	0	0	1
26	2.6	1	1	0	1	0
27	2.7	1	1	0	1	1
28	2.8	1	1	1	0	0
29	2.85	1	1	1	0	1
30	3	1	1	1	1	0
31	3.3	1	1	1	1	1



### 9 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

#### 9.1 Application Information

#### 9.1.1 Application Information

The TPS624xx-Q1 family of devices are synchronous dual step-down DC-DC converters. The devices provide two independent output voltage rails. The following information provides guidance on selecting external components to complete the application design.

#### 9.2 Typical Application

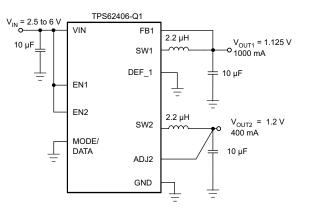


Figure 9-1. Typical Application Schematic

#### 9.2.1 Design Requirements

The step-down converter design can be adapted to different output voltage and load current needs. The following design procedure is adequate for whole  $V_{IN}$ ,  $V_{OUTx}$  and load current range of the TPS624xx-Q1 family of devices.

#### 9.2.2 Detailed Design Procedure

#### 9.2.2.1 Output Voltage Setting

#### 9.2.2.1.1 Converter 1 Fixed Default Output-Voltage Setting

The DEF\_1 pin selects output voltage Vout1.

#### Pin DEF\_1 = low:

- TPS62406-Q1, TPS62407-Q1 = 1.125 V
- TPS62422-Q1 = 1.15V
- TPS62423-Q1 = 1.2V
- TPS62424-Q1 = 1.1V

#### Pin DEF\_1 = high:

- TPS62406-Q1 = 1.125 V
- TPS62407-Q1 = 1.225 V
- TPS62422-Q1 = 1.8V
- TPS62423-Q1 = 1.5V
- TPS62424-Q1 = 1.3V

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#### 9.2.2.1.2 Converter 2 Fixed Default Output-Voltage Setting

ADJ2 pin must be directly connected with V<sub>OUT2</sub>:

- TPS62406-Q1, V<sub>OUT2</sub> default = 1.2 V
- TPS62407-Q1, V<sub>OUT2</sub> default = 1.85 V
- TPS62422-Q1, V<sub>OUT2</sub> default = 1.2 V
- TPS62423-Q1, V<sub>OUT2</sub> default = 1.8 V
- TPS62424-Q1, V<sub>OUT2</sub> default = 1.8 V

#### 9.2.2.2 Output Filter Design (Inductor and Output Capacitor)

The converters operate with a minimum inductance of 1.75  $\mu$ H and minimum capacitance of 6  $\mu$ F. The device operation is optimum with inductors of 2.2  $\mu$ H to 4.7  $\mu$ H and output capacitors of 10  $\mu$ F to 22  $\mu$ F.

#### 9.2.2.2.1 Inductor Selection

Select the inductor based on its ratings for dc resistance and saturation current. The dc resistance of the inductor directly influences the efficiency of the converter. Therefore, select an inductor with lowest dc resistance for highest efficiency.

Equation 4 calculates the maximum inductor current under static load conditions. The saturation-current rating of the inductor should be higher than the maximum inductor current as calculated with Equation 5. TI makes this recommendation because during heavy load transients the inductor current rises above the calculated value.

$$\Delta I_{L} = Vout \times \frac{1 - \frac{Vout}{Vin}}{L \times f}$$
(4)

where

- $\Delta I_1$  = Peak-to-peak inductor ripple current
- L = Inductor value
- f = Switching frequency (2.25 MHz typical)

$$I_{Lmax} = I_{outmax} + \frac{\Delta I_{L}}{2}$$
(5)

where

• I<sub>Lmax</sub> = Maximum inductor current

and the highest inductor current occurs at maximum VIN.

Open-core inductors have a soft saturation characteristic and they can usually handle higher inductor currents versus a comparable shielded inductor.

A more conservative approach is to select the inductor current rating just for the maximum switch current of the corresponding converter. Take into consideration that the core material from inductor to inductor differs, and this difference has an impact on the efficiency.

See Table 9-1 and the typical application circuit examples for possible inductors.

DIMENSIONS [mm]	INDUCTOR TYPE	SUPPLIER
3.2 × 2.6 × 1	MIPW3226	FDK
3 × 3 × 0.9	LPS3010	Coilcraft
2.8 × 2.6 × 1	VLF3010	TDK
2.8 x 2.6 × 1.4	VLF3014	TDK
3 × 3 × 1.4	LPS3015	Coilcraft



#### Table 9-1. List of Inductors (continued)

DIMENSIONS [mm]	INDUCTOR TYPE	SUPPLIER
3.9 × 3.9 × 1.7	LPS4018	Coilcraft

#### 9.2.2.2.2 Output-Capacitor Selection

The advanced fast-response voltage-mode control scheme of the converters allows the use of tiny ceramic capacitors with a typical value of 10  $\mu$ F to 22  $\mu$ F, without having large output-voltage under- and overshoots during heavy load transients. Ceramic capacitors with low ESR values result in lowest output-voltage ripple, and TI therefore recommends them. The output capacitor requires either X7R or X5R dielectric. TI does not recommend Y5V and Z5U dielectric capacitors because of their wide variation in capacitance.

If using ceramic output capacitors, the capacitor rms ripple-current rating always meets the application requirements. The rms ripple current calculation is:

$$I_{\text{RMSCout}} = \text{Vout} \times \frac{1 - \frac{\text{Vout}}{\text{Vin}}}{L \times f} \times \frac{1}{2 \times \sqrt{3}}$$
(6)

At nominal load current, the inductive converters operate in PWM mode and the overall output voltage ripple is the sum of the voltage spike caused by the output capacitor ESR, plus the voltage ripple caused by charging and discharging the output capacitor:

$$\Delta \text{Vout} = \text{Vout} \times \frac{1 - \frac{\text{Vout}}{\text{Vin}}}{\text{L} \times f} \times \left(\frac{1}{8 \times \text{Cout} \times f} + \text{ESR}\right)$$
(7)

where

The highest output-voltage ripple occurs at the highest input voltage, V<sub>IN</sub>.

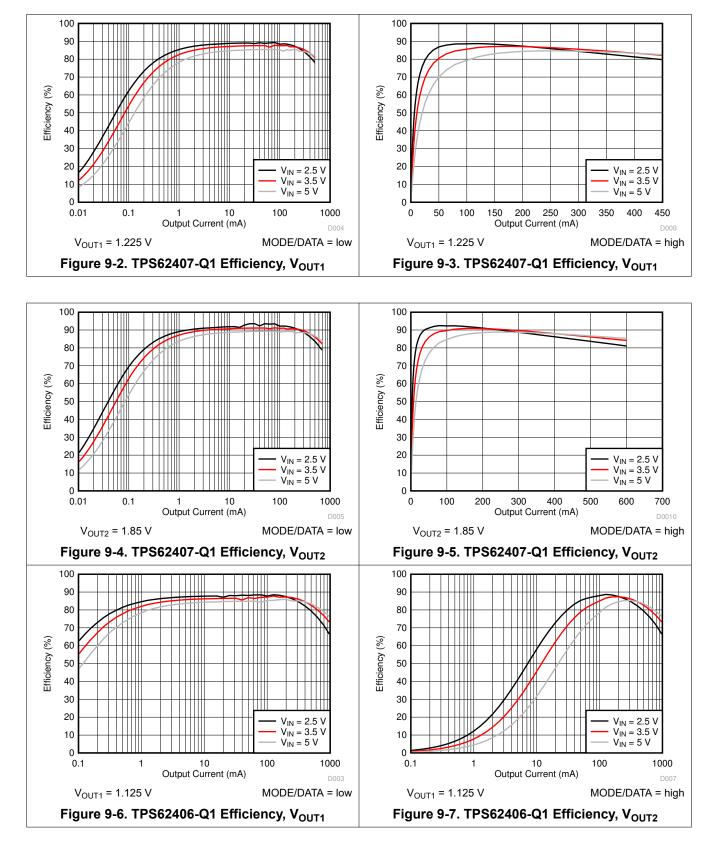
At light load currents, the converters operate in power-save mode and the output-voltage ripple depends on the output-capacitor value. The internal comparator delay and the external capacitor set the output-voltage ripple. Higher output capacitors like 22 µF values minimize the voltage ripple in PFM mode and tighten dc output accuracy in PFM mode.

#### 9.2.2.2.3 Input Capacitor Selection

Because of the nature of the buck converter having a pulsating input current, the device requires a low-ESR input capacitor to prevent large voltage transients that can cause misbehavior of the device or interference with other circuits in the system. An input capacitor of 10  $\mu$ F is sufficient.



#### 9.2.3 Application Curves

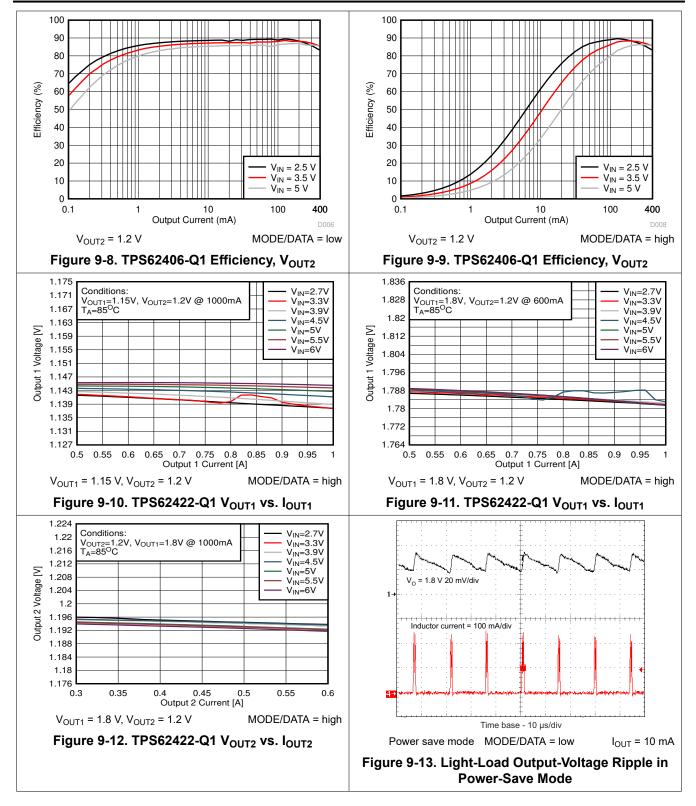


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Product Folder Links: TPS62406-Q1 TPS62407-Q1 TPS62422-Q1 TPS62423-Q1 TPS62424-Q1



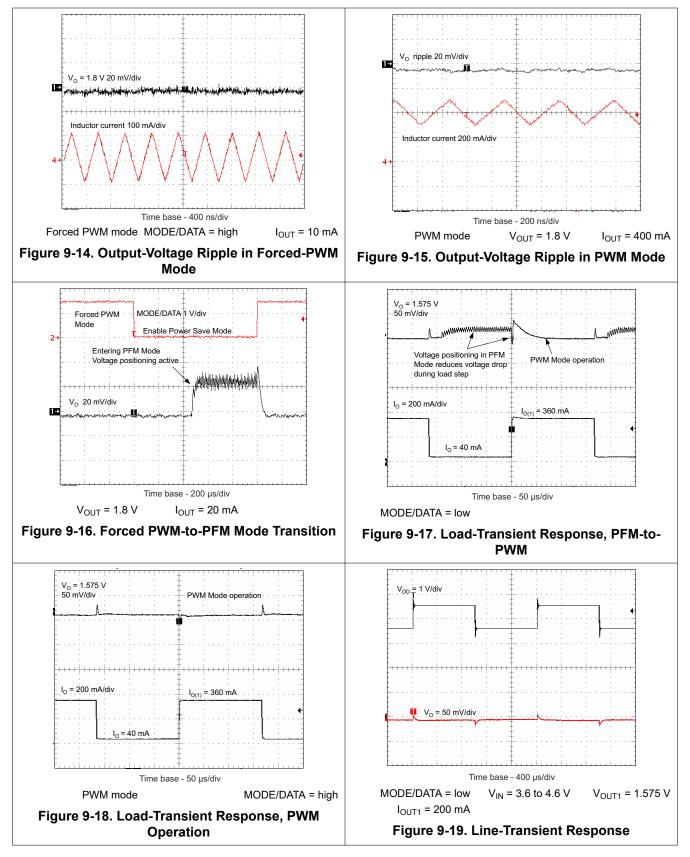
#### TPS62406-Q1, TPS62407-Q1, TPS62422-Q1, TPS62423-Q1, TPS62424-Q1 SLVSCH9E – DECEMBER 2014 – REVISED MARCH 2022



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#### **TPS62406-Q1, TPS62407-Q1, TPS62422-Q1, TPS62423-Q1, TPS62424-Q1** SLVSCH9E – DECEMBER 2014 – REVISED MARCH 2022

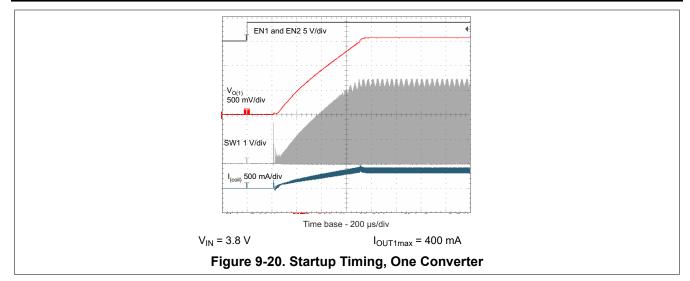




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Product Folder Links: TPS62406-Q1 TPS62407-Q1 TPS62422-Q1 TPS62423-Q1 TPS62424-Q1





## 9.3 System Examples

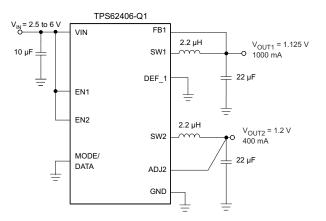
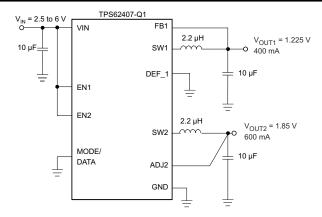


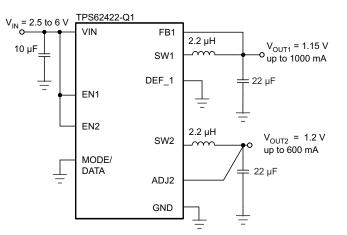
Figure 9-21. TPS62406-Q1 Fixed 1.125-V and 1.2-V Outputs

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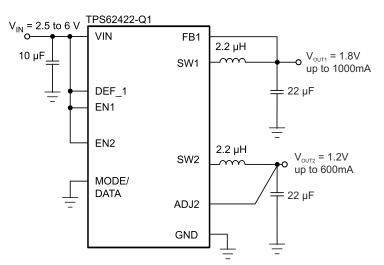


Figure 9-24. TPS62422-Q1 Fixed 1.8-V and 1.2-V Outputs

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## **10 Power Supply Recommendations**

This device has no special recommendation for the power supply. TI recommends to use the values listed in the *Section 7.3* table.



## 11 Layout

## **11.1 Layout Guidelines**

- As for all switching power supplies, the layout is an important step in the design. Proper function of the device demands careful attention to PCB layout.
- It is critical to provide a low-inductance, low-impedance ground path. Therefore, use wide and short traces for the main current paths as indicated in **bold** in Figure 11-1.
- Place the input capacitor as close as possible to the IC pins VIN and GND, the inductor and output capacitor as close as possible to the pins SW1 and GND.
- Connect the GND pin of the device to the PowerPAD of the PCB and use this pad as a star point. For each converter, use a common power GND node and a different node for the signal GND to minimize the effects of ground noise.
- Connect these ground nodes together to the PowerPAD (star point) underneath the IC. Keep the common path to the GND PIN, which returns the small signal components and the high current of the output capacitors, as short as possible to avoid ground noise.
- Connect the output voltage-sense lines (FB 1, DEF\_1, ADJ2) right to the output capacitor and route them away from noisy components and traces (for example, the SW1 and SW2 lines).
- If operating the EasyScale interface with high transmission rates, route the MODE/DATA trace away from the ADJ2 line to avoid capacitive coupling into the ADJ2 pin.
- A GND guard ring between the MODE/DATA pin and ADJ2 pin avoids potential noise coupling.

### 11.2 Layout Example

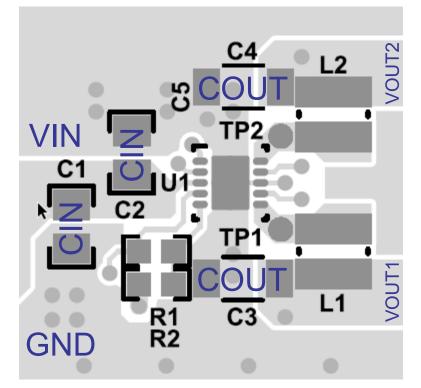


Figure 11-1. Layout Diagram



### 12 Device and Documentation Support

#### **12.1 Support Resources**

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

#### 12.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 12.3 Trademarks

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#### 12.4 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 12.5 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

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## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



#### **PACKAGING INFORMATION**

Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/	MSL rating/	Op temp (°C)	Part marking
	(1)	(2)			(3)	Ball material	Peak reflow		(6)
						(4)	(5)		
TPS62406QDRCRQ1	Active	Production	VSON (DRC)   10	3000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	2406Q
TPS62406QDRCRQ1.B	Active	Production	VSON (DRC)   10	3000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	2406Q
TPS62407QDRCRQ1	Active	Production	VSON (DRC)   10	3000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	SHU
TPS62407QDRCRQ1.B	Active	Production	VSON (DRC)   10	3000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	SHU
TPS62422QDRCRQ1	Active	Production	VSON (DRC)   10	3000   LARGE T&R	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 125	2422Q
TPS62422QDRCRQ1.B	Active	Production	VSON (DRC)   10	3000   LARGE T&R	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 125	2422Q
TPS62423QDRCRQ1	Active	Production	VSON (DRC)   10	3000   LARGE T&R	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 125	2423Q
TPS62423QDRCRQ1.B	Active	Production	VSON (DRC)   10	3000   LARGE T&R	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 125	2423Q
TPS62424QDRCRQ1	Active	Production	VSON (DRC)   10	3000   LARGE T&R	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 125	2424Q
TPS62424QDRCRQ1.B	Active	Production	VSON (DRC)   10	3000   LARGE T&R	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 125	2424Q

<sup>(1)</sup> **Status:** For more details on status, see our product life cycle.

<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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## PACKAGE OPTION ADDENDUM

23-May-2025

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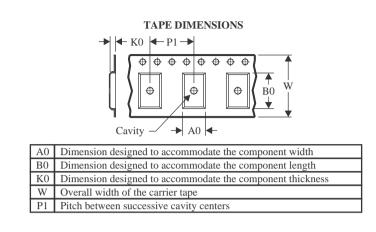
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STRUMENTS

### TAPE AND REEL INFORMATION





#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



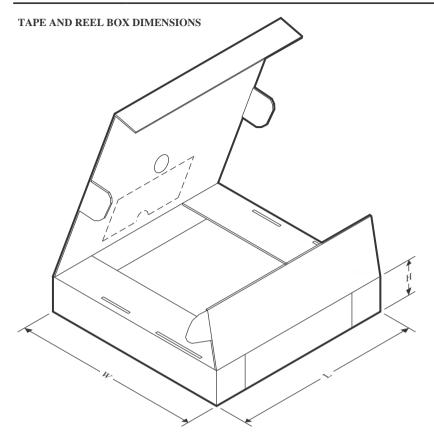
All dimensions are nominal												
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS62406QDRCRQ1	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62407QDRCRQ1	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62422QDRCRQ1	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62423QDRCRQ1	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS62424QDRCRQ1	VSON	DRC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2



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## PACKAGE MATERIALS INFORMATION

8-May-2023



*All	dimensions	are	nominal	
------	------------	-----	---------	--

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS62406QDRCRQ1	VSON	DRC	10	3000	346.0	346.0	33.0
TPS62407QDRCRQ1	VSON	DRC	10	3000	346.0	346.0	33.0
TPS62422QDRCRQ1	VSON	DRC	10	3000	338.0	355.0	50.0
TPS62423QDRCRQ1	VSON	DRC	10	3000	338.0	355.0	50.0
TPS62424QDRCRQ1	VSON	DRC	10	3000	338.0	355.0	50.0

## **DRC 10**

3 x 3, 0.5 mm pitch

## **GENERIC PACKAGE VIEW**

## VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.





## **DRC0010J**



## **PACKAGE OUTLINE**

## VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.

3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.



## DRC0010J

## **EXAMPLE BOARD LAYOUT**

## VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

 This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

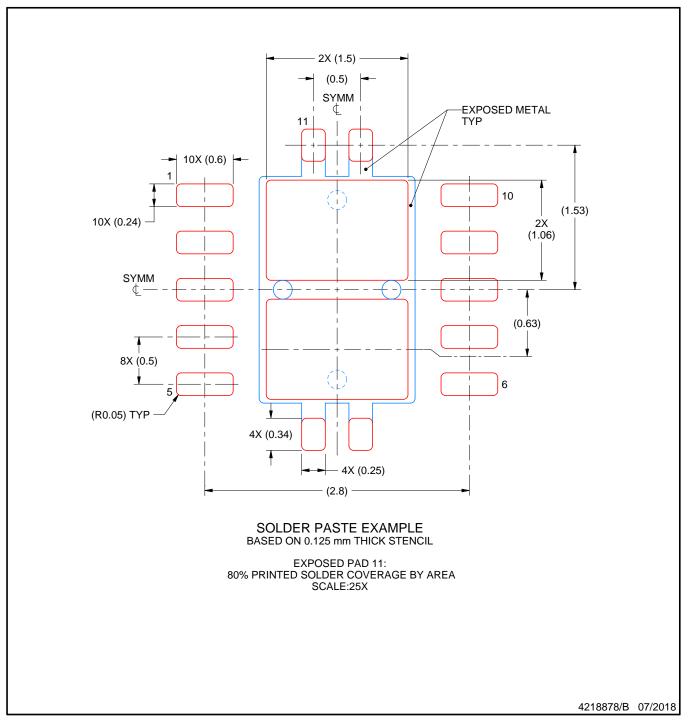


## DRC0010J

## **EXAMPLE STENCIL DESIGN**

## VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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