











**TPL5100** 

SNAS629C - JULY 2013-REVISED DECEMBER 2014

# **TPL5100 Nano-Power Programmable Timer With MOS Driver**

### **Features**

- Supply Voltage from 1.8 V to 5.0 V
- Selectable Timer Intervals, 16 to 1024 seconds
- Current Consumption 30 nA (typical, at 2.5 V)

# **Applications**

- **Battery-Powered Systems**
- **Energy Harvesting Systems**
- Remote Data-Logger
- Sensor Node
- **Power-Gating Applications**
- **Building Automation**
- Low-Power Wireless
- Consumer Electronics

# 3 Description

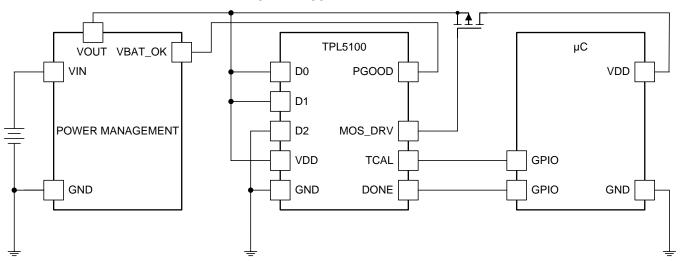
The TPL5100 is a long-term timer IC optimized for low-power applications. The TPL5100 can replace a microcontroller's internal timer, allowing microcontroller to stay completely off instead of running a timer, providing a total power consumption reduction of 60 to 80%. The TPL5100 is designed for use in power cycled applications and provides selectable timing from 16 seconds to 1024 seconds. TPL5100 can also monitor a battery management IC via a power-good digital input and power on the microcontroller only when a good supply voltage is present. The device is packaged in a 10-pin VSSOP package.

### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPL5100	VSSOP (10)	3.00 mm × 3.00 mm

<sup>(1)</sup> For all available packages, see the orderable addendum at the end of the datasheet.

### Simplified Application Schematic





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# 4 Revision History

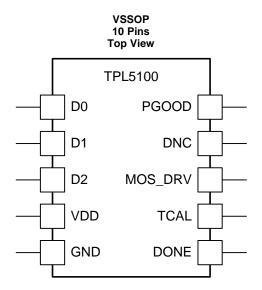
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Changes	from	Revision	В	(August	2013)	to	Revision (	C

Page

Added ESD Ratings table, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and Mechanical, Packaging, and Orderable Information section
 Removed T<sub>A</sub> value.



# **5 Pin Configuration and Functions**



**Pin Functions** 

PII	PIN		PIN		DESCRIPTION	ADDI ICATION INFORMATION
NAME	NO.	1/0	DESCRIPTION	APPLICATION INFORMATION		
D0	1	I	Logic Input to set period delay (t <sub>DP</sub> )	Connect to GND (low logic value) or to VDD (high logic value)		
D1	2	I	Logic Input to set period delay (t <sub>DP</sub> )	Connect to GND (low logic value) or to VDD (high logic value)		
D2	3	I	Logic Input to set period delay (t <sub>DP</sub> )	Connect to GND (low logic value) or to VDD (high logic value)		
VDD	4	Р	Supply voltage			
GND	5	G	Ground			
DONE	6	I	Logic input for Watchdog functionality			
TCAL	7	0	Short duration pulse output for estimation of TPL5100 timer delay.			
MOS_DRV	8	0	Drives external MOSFET to power cycle the remaining system.			
DNC	9	-	Do Not Connect	Leave this pin floating		
PGOOD	10	I	Digital power good input			



# 6 Specifications

# 6.1 Absolute Maximum Ratings<sup>(1)(2)</sup>

	MIN	MAX	UNIT
Supply Voltage (VDD-GND)	-0.3	6	V
Input voltage	-0.3	VDD+0.3	V
Voltage between any two pins (3)	-0.3	VDD+0.3	V
Input Current on any pin	-5	5	mA
Junction Temperature, T <sub>J</sub> <sup>(4)</sup>		150	°C
Storage temperature, T <sub>stg</sub>	-65	150	°C

- (1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltages referenced to ground unless otherwise noted.
- (3) When the input voltage (VIN) at any pin exceeds the power supply (VDD), the current on that pin must not exceed 5 mA and the voltage must also not exceed 6.0 V.
- (4) The maximum power dissipation is a function of TJ(MAX), Î,JA, and the ambient temperature, TA. The maximum allowable power dissipation at any ambient temperature is PDMAX = (TJ(MAX) TA)/ Î,JA. All numbers apply for packages soldered directly onto a PC board

# 6.2 ESD Ratings

			VALUE	UNIT
		Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 (1)	±2000	
V <sub>(ESD)</sub>	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Ratings

	MIN	MAX	UNIT
Supply Voltage (VDD-GND)	1.8	5.0	V
Temperature Range	-40	105	°C

### 6.4 Thermal Information

	TPL5100	
THERMAL METRIC <sup>(1)</sup>	VSSOP	UNIT
	10 PINS	
R <sub>θJA</sub> Junction-to-ambient thermal resistance	196.8	°C/W

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.



# 6.5 Electrical Characteristics<sup>(1)</sup>

Specifications are for  $T_A = T_J = 25$ °C, VDD-GND=2.5 V, unless otherwise stated.

	PARAMETER	TEST CONDITIONS	MIN <sup>(2)</sup>	TYP <sup>(3)</sup>	MAX <sup>(2)</sup>	UNIT
POWER SUP	PLY					
IVDD	Supply current <sup>(4)</sup>	PGOOD=VDD		30	50	nA
		PGOOD=GND		12		nA
TIMER			1			
t <sub>DP</sub>	Timer Delay Period			16, 32, 64, 100, 128, 256, 512, 1024		s
	Timer Delay Period drift over life time (5)			0.06 %		
	Timer Delay Period drift over temperature			400		ppm/°C
t <sub>CAL</sub>	Calibration pulse width		14.063	15.625	17.188	ms
	t <sub>DP</sub> to t <sub>CAL</sub> matching error <sup>(6)</sup>	VDD<=3.0 V			0.1%	
t <sub>DONE</sub>	DONE Pulse width (6)		100			ns
t <sub>MOS_DRV</sub>	MOS_DRV Pulse width			31.25		ms
DIGITAL LOG	GIC LEVELS		·			•
VIH	Logic High Threshold	PGOOD, DONE	0.7xVDD			V
VIL	Logic Low Threshold	PGOOD, DONE			0.3xVDD	V
VOL	La sia autout Hisb Laval	MOS_DRV, TCAL lout = 100 uA	VDD-0.3			V
VOH	Logic output High Level	MOS_DRV, TCAL lout = 1 mA	VDD-0.7			V
VOI	Large control Land	MOS_DRV, TCAL lout = -100 uA			0.3	٧
VOL	Logic output Low Level	MOS_DRV, TCAL lout = -1 mA			0.7	٧

<sup>(1)</sup> Electrical Characteristics table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ .

(2) Limits are specified by testing, design, or statisfical analysis at 25°C. Limits over the operating temperature range are specified through

correlations using statistical quality control (SQC) method.

<sup>(3)</sup> Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

The supply current doesn't take in account load and pull-up resistor current. Input pins are at GND or VDD.

Operational life time test procedure equivalent to 10 years.

<sup>(6)</sup> Ensured by design.



# 6.6 Timing Requirements TCAL, MOS\_DRV, DONE, PGOOD

			MIN NO	MAX	UNIT
tr <sub>TCAL</sub>	Rise Time TCAL	Capacitve load 15 pF	5	0	ns
tf <sub>TCAL</sub>	Fall Time TCAL	Capacitve load 15 pF	5	0	ns
tr <sub>MOS_DRV</sub>	Rise Time MOS_DRV	Capacitve load 50 pF		4	ns
tf <sub>MOS_DRV</sub>	Fall Time MOS_DRV	Capacitve load 50 pF	5	0	ns
		Min delay	10	0	ns
tD <sub>DONE</sub>	DONE to MOS_DRV delay	Max delay	t <sub>DP</sub> -5 :		ms
tD <sub>TCAL</sub>	TCAL to MOS_DRV delay		t <sub>CAL</sub> /	2	ms

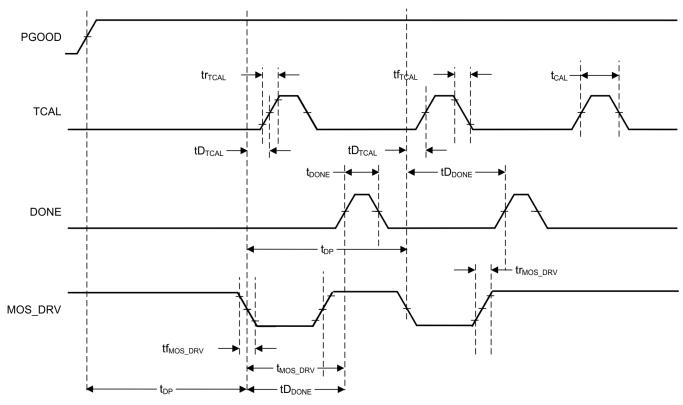
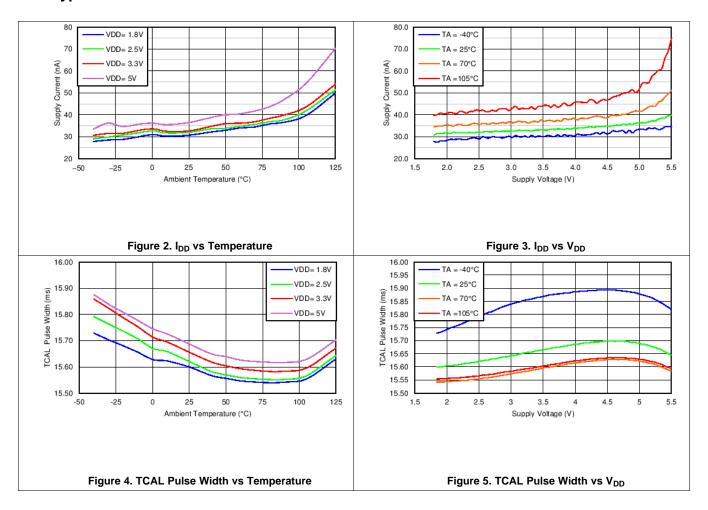


Figure 1. Timing Diagram

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# 6.7 Typical Characteristics



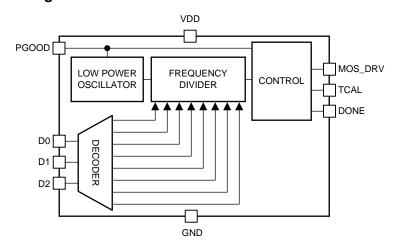


# 7 Detailed Description

#### 7.1 Overview

The TPL5100 is a long-term timer for low-power applications. The TPL5100 is designed for use in power cycled applications and provides selectable timing from 16 s to 1024 s. An additional feature is interfacing which is achieved through the TPL5100 to a power-management IC.

### 7.2 Functional Block Diagram



### 7.3 Feature Description

### 7.3.1 Supervisor Feature

A critical event that can corrupt the memory of a microcontroller is a voltage supply drop (supply lower than minimum operating range), and a reset of the microcontroller is mandatory if this occurs. Since the TPL5100 is the right choice in systems which stay most of the time in deep sleep or completely OFF, due to its ultra-low power consumption, it is fundamental that it takes into account the voltage drop events. The TPL5100 implements the supervisor feature when working with some power-management ICs, which indicate the status of the supply voltage with a power-good or battery-good output. The supervisory functionality is enabled by simply connecting the Battery management power-good output to the TPL5100 PGOOD pin. If this feature is not used connect the PGOOD pin to VDD.

In case the power-management IC detects a voltage drop while the microcontroller is OFF, consequently lowering the PGOOD line, the TPL5100 resets its internal counter and does not allow the micro to turn ON until the PGOOD is high again. This series of events allows the microcontroller to avoid working in an unsafe voltage supply condition. If the PGOOD signal is lowered while the microcontroller is ON, the TPL51000 turns the microcontroller OFF. The micro will be turned ON when PGOOD is high again and the selected delay is elapsed.

#### 7.3.2 Calibration Pulse

The TPL5100 is based on an ultra-low power oscillator, which has a relatively low frequency and low accuracy; however, it shows very good cycle-to-cycle repeatability and very low temperature drift. In most of the applications, the accuracy of the oscillator is enough, but if a more accurate measure of the delay period is required, it is possible to measure the base period of the internal oscillator. A single pulse, which has the same duration as the base period of the internal oscillator, is present at the TCAL pin of the TPL5100. This pulse starts after a half period of the internal oscillator, from the falling edge of the MOS\_DRV pulse.

A microcontroller-connected to the TPL5100 can routinely measure the width of the TCAL pulse, using a counter and an external crystal. Once the base period of the TPL5100 is measured, the actual time delay is calculated by multiplying the measured period by a factor, N (see Table 1), dependent upon the nominal selected time delay.

The resolution and the accuracy of the measurement depend upon the external crystal. Since the frequency of the internal oscillator of the TPL5100 is very stable, the measurement of the calibration pulse is suggested only when a high gradient of ambient temperature is observed. The measurement of the TCAL pulse is useful in battery-powered applications that implement a precise battery life counter in the microcontroller.



### **Feature Description (continued)**

### 7.3.2.1 Overview of the Timing Signals MOS DRV, TCAL, and DONE

Figure 6 shows the timing of PGOOD, MOS\_DRV, and TCAL with respect to DONE. The frame, A, shows a typical sequence after the PGOOD, low to high, transition. As soon as PGOOD is high, the internal oscillator is powered ON. At the end of the delay period (t<sub>DP</sub>), a MOS enable signal (MOS\_DRV), followed by a calibration pulse, TCAL, is sent out. The calibration pulse starts after a half period of the internal oscillator from the falling edge of the MOS\_DRV signal, and lasts one internal oscillator period. A "DONE" signal is received before the end of the MOS\_DRV pulse. As soon as the TPL5100 receives the DONE signal, the counter resets and MOS\_DRV and TCAL return to default conditions (MOS\_DRV signal high and TCAL signal low).

The frame, B, shows a non-standard sequence. A "DONE" signal has not been received before the end of the MOS\_DRV pulse. The MOS\_DRV signal stays low for 2 internal oscillator periods. The calibration pulse starts after a half period of the internal oscillator from the falling edge of the MOS\_DRV signal, and lasts one internal oscillator period. The external power gating MOS stays ON for 2 internal oscillator periods.

The frame, C, shows a standard sequence, but in this case, the TPL5100 receives the DONE signal when MOS\_DRV is high and TCAL pulse is still high. As soon as the TPL5100 recognizes the DONE signal, the counter resets and MOS\_DRV and TCAL return to default conditions (MOS\_DRV signal high and TCAL signal low). The external power-gating MOS stays ON for the execution time of the program of the connected microcontroller.

The frame, D, shows a typical PGOOD, high to low transition. As soon as PGOOD is low, the internal oscillator is powered OFF and the digital output pins, TCAL and MOS\_DRV, are asynchronously reset by the falling edge of the PGOOD signal, such that TCAL resets at low logical values, while MOS\_DRV resets at a high logical value. The external power gating MOS stays ON less than the execution time of the program of the connected microcontroller.

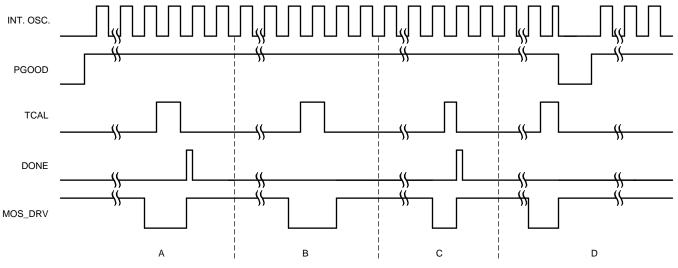


Figure 6. Timing MOS\_DRV, TCAL

## 7.3.3 Configuration and Interface

The time interval between 2 adjacent pulses is selectable through 3 digital input pins (D0, D1, D2) that can be strapped to either VDD (1) or GND (0). Eight possible time delays can be selected, as shown in Table 1.

**Table 1. Timer Delay Period** 

D2	D1	D0	Time (s)	Factor N
0	0	0	16	2 <sup>10</sup>
0	0	1	32	2 <sup>11</sup>
0	1	0	64	2 <sup>12</sup>
0	1	1	100	100*2 <sup>6</sup>



# **Feature Description (continued)**

# **Table 1. Timer Delay Period (continued)**

D2	D1	D0	Time (s)	Factor N
1	0	0	128	2 <sup>13</sup>
1	0	1	256	2 <sup>14</sup>
1	1	0	512	2 <sup>15</sup>
1	1	1	1024	2 <sup>16</sup>

### 7.4 Device Functional Modes

The TPL5100 is a long-term timer with a watchdog feature for low-power applications. The TPL5100 is designed for use in interrupt-driven applications and provides selectable timing from 1 s to 64 s. An additional supervisor feature is achieved through interfacing the TPL5100 to a power-management IC.



# 8 Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 8.1 Application Information

In battery powered applications the design of the system is driven by low-current consumption. The TPL5100 is suitable in the applications where there is the needs to monitor environment conditions in remote site at long fixed timer interval. Occasionally in these applications the micro is kept on to enable the watchdog and count the elapsed time. Often due to the high frequency clock of the microcontrollers, a special structure must be configured to count for several seconds. The TPL5100 can mimic the same job, by completely turning off the micro and sometimes the entire power channel; this results in burning only tens of nA.

### 8.2 Typical Application

The TPL5100 can be used in environment sensor nodes such as humidity and temperature sensor node. The sensor node has to measure the humidity and the temperature and transmit the data through a low power RF micro such as the CC2530. Since the temperature and the humidity in home application do not change so fast, the measurement and the transmission of the data can be done at very low rate, such as every 30 seconds. The RF micro should spend most of the time in counting the elapsed time, but using the TPL5100 it is possible to complete turn off the RF micro and enlarge the battery life. The TPL5100 will turn on the RF micro when the programmed timer interval elapses.

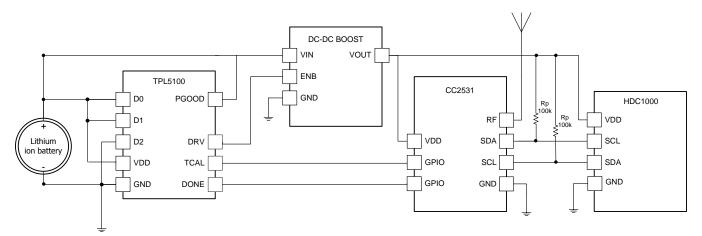


Figure 7. Sensor Node

#### 8.2.1 Design Requirements

The design is driven by the low current consumption constraint. The data are usually acquired at a rate between 30 s to 60 s. The highest necessity is the maximization of the battery life. The TPL5100 helps achieve this goal because it allows turning off the RF micro.

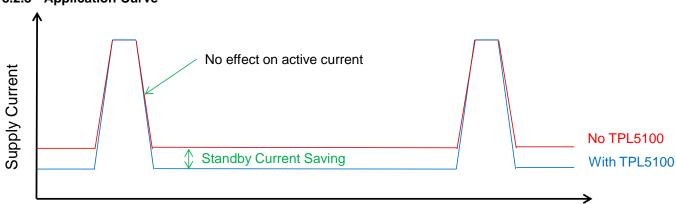
### 8.2.2 Detailed Design Procedure

When the focal constraint is the battery life, the selection of a low-power voltage regulator and low-leakage MOSFET to power gate the microcontroller is mandatory. The first step in the design is the calculation of the power consumption of each device in the different mode of operations. An example is the HDC1000, in measurement mode the RF micro is in normal operation and transmission. The different modes offer the possibility to select the appropriate timer interval which respect the application constraint and maximize the life of the battery.



# **Typical Application (continued)**

# 8.2.3 Application Curve



Time Figure 8. Effect of TPL5100 on Current Consumption



# 9 Power Supply Recommendations

The TPL5100 requires a voltage supply within 2.7 V and 5.5 V. A multilayer, ceramic-bypass X7R capacitor of 0.1µF between VDD and GND pin is recommended.

## 10 Layout

### 10.1 Layout Guidelines

The more sensitive pins of the TPL5100 are the digital input pins D0, D1, D2 to select the timer interval. It is mandatory to connect them to VDD or GND through short traces avoiding series resistance. Moreover, it is mandatory to keep these pins far from traces of high frequency signals, such as clock or communication bus. Signal integrity of DRV and TCAL signal is achieved reducing parasitic capacitance on the traces between the TPL5100 and the microcontroller.

# 10.2 Layout Example

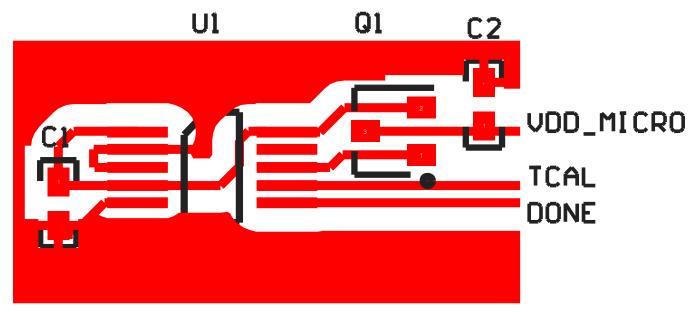


Figure 9. Board Layout

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Product Folder Links: *TPL5100* 



# 11 Device and Documentation Support

#### 11.1 Trademarks

All trademarks are the property of their respective owners.

### 11.2 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## 11.3 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

# 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

Product Folder Links: TPL5100

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#### PACKAGING INFORMATION

Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
						(4)	(5)		
TPL5100DGSR	Active	Production	VSSOP (DGS)   10	3500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	ASAA
TPL5100DGSR.A	Active	Production	VSSOP (DGS)   10	3500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	ASAA
TPL5100DGST	Active	Production	VSSOP (DGS)   10	250   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	ASAA
TPL5100DGST.A	Active	Production	VSSOP (DGS)   10	250   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	ASAA

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

# **PACKAGE MATERIALS INFORMATION**

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## TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPL5100DGSR	VSSOP	DGS	10	3500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
TPL5100DGST	VSSOP	DGS	10	250	177.8	12.4	5.3	3.4	1.4	8.0	12.0	Q1

# **PACKAGE MATERIALS INFORMATION**

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## \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPL5100DGSR	VSSOP	DGS	10	3500	367.0	367.0	35.0
TPL5100DGST	VSSOP	DGS	10	250	208.0	191.0	35.0



SMALL OUTLINE PACKAGE



### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187, variation BA.



SMALL OUTLINE PACKAGE



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE PACKAGE



NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



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