

# SM72501 SolarMagic Precision, CMOS Input, RRIO, Wide Supply Range Amplifier

Check for Samples: [SM72501](#)

## FEATURES

- Renewable Energy Grade
- Unless Otherwise noted, Typical values at  $V_S = 5V$
- Input Offset Voltage  $\pm 200 \mu V$  (max)
- Input Bias Current  $\pm 200 fA$
- Input Voltage Noise  $9 nV/\sqrt{Hz}$
- CMRR 130 dB
- Open Loop Gain 130 dB
- Temperature Range  $-40^\circ C$  to  $125^\circ C$
- Unity Gain Bandwidth 2.5 MHz
- Supply Current (SM72501)  $715 \mu A$
- Supply Voltage Range 2.7V to 12V
- Rail-to-rail Input and Output

## APPLICATIONS

- High Impedance Sensor Interface
- Battery Powered Instrumentation
- High Gain Amplifiers
- DAC Buffer
- Instrumentation Amplifier
- Active Filters

## DESCRIPTION

The SM72501 is a low offset voltage, rail-to-rail input and output precision amplifier with a CMOS input stage and a wide supply voltage range. The SM72501 is ideal for sensor interface and other instrumentation applications.

The low offset voltage of less than  $\pm 200 \mu V$  along with the low input bias current of less than  $\pm 1 pA$  makes the SM72501 ideal for precision applications. The SM72501 is built utilizing VIP50 technology, which allows the combination of a CMOS input stage and a 12V common mode and supply voltage range. This makes the SM72501 a great choice in many applications where conventional CMOS parts cannot operate under the desired voltage conditions.

The SM72501 has a rail-to-rail input stage that significantly reduces the CMRR glitch commonly associated with rail-to-rail input amplifiers. This is achieved by trimming both sides of the complimentary input stage, thereby reducing the difference between the NMOS and PMOS offsets. The output of the SM72501 swings within 40 mV of either rail to maximize the signal dynamic range in applications requiring low supply voltage.

The SM72501 is offered in the space saving 5-Pin SOT-23. This small package is an ideal solution for area constrained PC boards and portable electronics.

## Typical Application

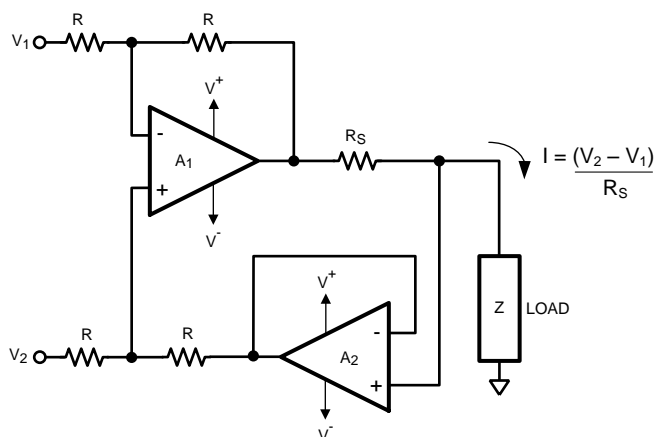


Figure 1. Precision Current Source



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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## Absolute Maximum Ratings<sup>(1)(2)</sup>

ESD Tolerance <sup>(3)</sup>	Human Body Model	2000V
	Machine Model	200V
Charge-Device Model		1000V
$V_{IN}$ Differential		±300 mV
Supply Voltage ( $V_S = V^+ - V^-$ )		13.2V
Voltage at Input/Output Pins		$V^+ + 0.3V, V^- - 0.3V$
Input Current		10 mA
Storage Temperature Range		-65°C to +150°C
Junction Temperature <sup>(4)</sup>		+150°C
Soldering Information	Infrared or Convection (20 sec)	235°C
	Wave Soldering Lead Temp. (10 sec)	260°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional. For specifications and the test conditions, see the Electrical Characteristics Tables.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC) Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).
- (4) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A) / \theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

## Operating Ratings<sup>(1)</sup>

Temperature Range <sup>(2)</sup>		-40°C to +125°C
Supply Voltage ( $V_S = V^+ - V^-$ )		2.7V to 12V
Package Thermal Resistance ( $\theta_{JA}$ ) <sup>(2)</sup>	5-Pin SOT-23	265°C/W

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional. For specifications and the test conditions, see the Electrical Characteristics Tables.
- (2) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A) / \theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

### 3V Electrical Characteristics<sup>(1)</sup>

Unless otherwise specified, all limits are specified for  $T_A = 25^\circ\text{C}$ ,  $V^+ = 3\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_{\text{CM}} = V^+/2$ , and  $R_L > 10\text{ k}\Omega$  to  $V^+/2$ .

**Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min <sup>(2)</sup>	Typ <sup>(3)</sup>	Max <sup>(2)</sup>	Units
$V_{\text{OS}}$	Input Offset Voltage			$\pm 37$	$\pm 200$ <b><math>\pm 500</math></b>	$\mu\text{V}$
$\text{TCV}_{\text{OS}}$	Input Offset Voltage Temperature Drift	See <sup>(4)</sup>		$\pm 1$	<b><math>\pm 5</math></b>	$\mu\text{V}/^\circ\text{C}$
$I_{\text{B}}$	Input Bias Current	See <sup>(4)(5)</sup> $-40^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$		$\pm 0.2$	$\pm 1$ <b><math>\pm 50</math></b>	pA
		See <sup>(4)(5)</sup> $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$		$\pm 0.2$	$\pm 1$ <b><math>\pm 400</math></b>	
$I_{\text{OS}}$	Input Offset Current			40		fA
CMRR	Common Mode Rejection Ratio	$0\text{V} \leq V_{\text{CM}} \leq 3\text{V}$	86 <b>80</b>	130		dB
PSRR	Power Supply Rejection Ratio	$2.7\text{V} \leq V^+ \leq 12\text{V}$ , $V_{\text{O}} = V^+/2$	86 <b>82</b>	98		dB
CMVR	Common Mode Voltage Range	CMRR $\geq 80\text{ dB}$ CMRR $\geq 77\text{ dB}$	-0.2 <b>-0.2</b>		3.2 <b>3.2</b>	V
$A_{\text{VOL}}$	Open Loop Voltage Gain	$R_L = 2\text{ k}\Omega$ $V_{\text{O}} = 0.3\text{V}$ to $2.7\text{V}$	100 <b>96</b>	114		dB
		$R_L = 10\text{ k}\Omega$ $V_{\text{O}} = 0.2\text{V}$ to $2.8\text{V}$	100 <b>96</b>	124		
$V_{\text{OUT}}$	Output Voltage Swing High	$R_L = 2\text{ k}\Omega$ to $V^+/2$		40	80 <b>120</b>	mV from $V^+$
		$R_L = 10\text{ k}\Omega$ to $V^+/2$		30	40 <b>60</b>	
	Output Voltage Swing Low	$R_L = 2\text{ k}\Omega$ to $V^+/2$		40	60 <b>80</b>	mV
		$R_L = 10\text{ k}\Omega$ to $V^+/2$		20	40 <b>50</b>	
$I_{\text{OUT}}$	Output Current <sup>(6)(7)</sup>	Sourcing $V_{\text{O}} = V^+/2$ $V_{\text{IN}} = 100\text{ mV}$	25 <b>15</b>	42		mA
		Sinking $V_{\text{O}} = V^+/2$ $V_{\text{IN}} = -100\text{ mV}$	25 <b>20</b>	42		
$I_{\text{S}}$	Supply Current			0.670	1.0 <b>1.2</b>	mA
SR	Slew Rate <sup>(8)</sup>	$A_V = +1$ , $V_{\text{O}} = 2 V_{\text{PP}}$ 10% to 90%		0.9		V/ $\mu\text{s}$
GBW	Gain Bandwidth			2.5		MHz
THD+N	Total Harmonic Distortion + Noise	$f = 1\text{ kHz}$ , $A_V = 1$ , $R_L = 10\text{ k}\Omega$		0.02		%
$e_{\text{n}}$	Input Referred Voltage Noise Density	$f = 1\text{ kHz}$		9		nV/ $\sqrt{\text{Hz}}$
$i_{\text{n}}$	Input Referred Current Noise Density	$f = 100\text{ kHz}$		1		fA/ $\sqrt{\text{Hz}}$

- (1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . Parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ .
- (2) Limits are 100% production tested at  $25^\circ\text{C}$ . Limits over the operating temperature range are specified through correlations using the Statistical Quality Control (SQC) method.
- (3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested on shipped production material.
- (4) This parameter is specified by design and/or characterization and is not tested in production.
- (5) Positive current corresponds to current flowing into the device.
- (6) The maximum power dissipation is a function of  $T_{\text{J(MAX)}}$ ,  $\theta_{\text{JA}}$ . The maximum allowable power dissipation at any ambient temperature is  $P_{\text{D}} = (T_{\text{J(MAX)}} - T_A) / \theta_{\text{JA}}$ . All numbers apply for packages soldered directly onto a PC Board.
- (7) The short circuit test is a momentary test.
- (8) The number specified is the slower of positive and negative slew rates.

## 5V Electrical Characteristics<sup>(1)</sup>

Unless otherwise specified, all limits are specified for  $T_A = 25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_{CM} = V^+/2$ , and  $R_L > 10\text{ k}\Omega$  to  $V^+/2$ .

**Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min <sup>(2)</sup>	Typ <sup>(3)</sup>	Max <sup>(2)</sup>	Units
$V_{OS}$	Input Offset Voltage			$\pm 37$	$\pm 200$ <b><math>\pm 500</math></b>	$\mu\text{V}$
$TCV_{OS}$	Input Offset Voltage Temperature Drift	See <sup>(4)</sup>		$\pm 1$	<b><math>\pm 5</math></b>	$\mu\text{V}/^\circ\text{C}$
$I_B$	Input Bias Current	See <sup>(4)(5)</sup> $-40^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$		$\pm 0.2$	$\pm 1$ <b><math>\pm 50</math></b>	pA
		See <sup>(4)(5)</sup> $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$		$\pm 0.2$	$\pm 1$ <b><math>\pm 400</math></b>	
$I_{OS}$	Input Offset Current			40		fA
CMRR	Common Mode Rejection Ratio	$0\text{V} \leq V_{CM} \leq 5\text{V}$	88 <b>83</b>	130		dB
PSRR	Power Supply Rejection Ratio	$2.7\text{V} \leq V^+ \leq 12\text{V}$ , $V_O = V^+/2$	86 <b>82</b>	100		dB
CMVR	Common Mode Voltage Range	CMRR $\geq 80\text{ dB}$ CMRR $\geq 78\text{ dB}$	-0.2 <b>-0.2</b>		5.2 <b>5.2</b>	V
$A_{VOL}$	Open Loop Voltage Gain	$R_L = 2\text{ k}\Omega$ $V_O = 0.3\text{V to } 4.7\text{V}$	100 <b>96</b>	119		dB
		$R_L = 10\text{ k}\Omega$ $V_O = 0.2\text{V to } 4.8\text{V}$	100 <b>96</b>	130		
$V_{OUT}$	Output Voltage Swing High	$R_L = 2\text{ k}\Omega$ to $V^+/2$		60	110 <b>130</b>	mV from $V^+$
		$R_L = 10\text{ k}\Omega$ to $V^+/2$		40	50 <b>70</b>	
	Output Voltage Swing Low	$R_L = 2\text{ k}\Omega$ to $V^+/2$		50	80 <b>90</b>	mV
		$R_L = 10\text{ k}\Omega$ to $V^+/2$		30	40 <b>50</b>	
$I_{OUT}$	Output Current <sup>(6)(7)</sup>	Sourcing $V_O = V^+/2$ $V_{IN} = 100\text{ mV}$	40 <b>28</b>	66		mA
		Sinking $V_O = V^+/2$ $V_{IN} = -100\text{ mV}$	40 <b>28</b>	76		
$I_S$	Supply Current			0.715	1.0 <b>1.2</b>	mA
SR	Slew Rate <sup>(8)</sup>	$A_V = +1$ , $V_O = 4\text{ V}_{PP}$ 10% to 90%		1.0		V/ $\mu\text{s}$
GBW	Gain Bandwidth			2.5		MHz
THD+N	Total Harmonic Distortion + Noise	$f = 1\text{ kHz}$ , $A_V = 1$ , $R_L = 10\text{ k}\Omega$		0.02		%
$e_n$	Input Referred Voltage Noise Density	$f = 1\text{ kHz}$		9		nV/ $\sqrt{\text{Hz}}$
$i_n$	Input Referred Current Noise Density	$f = 100\text{ kHz}$		1		fA/ $\sqrt{\text{Hz}}$

- (1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . Parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ .
- (2) Limits are 100% production tested at  $25^\circ\text{C}$ . Limits over the operating temperature range are specified through correlations using the Statistical Quality Control (SQC) method.
- (3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested on shipped production material.
- (4) This parameter is specified by design and/or characterization and is not tested in production.
- (5) Positive current corresponds to current flowing into the device.
- (6) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A) / \theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.
- (7) The short circuit test is a momentary test.
- (8) The number specified is the slower of positive and negative slew rates.

## ±5V Electrical Characteristics<sup>(1)</sup>

Unless otherwise specified, all limits are specified for  $T_A = 25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = -5\text{V}$ ,  $V_{CM} = 0\text{V}$ , and  $R_L > 10\text{ k}\Omega$  to  $0\text{V}$ .

**Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min <sup>(2)</sup>	Typ <sup>(3)</sup>	Max <sup>(2)</sup>	Units
$V_{OS}$	Input Offset Voltage			±37	±200 <b>±500</b>	μV
$TCV_{OS}$	Input Offset Voltage Temperature Drift	See <sup>(4)</sup>		±1	<b>±5</b>	μV/°C
$I_B$	Input Bias Current	See <sup>(4)(5)</sup> $-40^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$		±0.2	1 <b>±50</b>	pA
		See <sup>(4)(5)</sup> $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$		±0.2	1 <b>±400</b>	
$I_{OS}$	Input Offset Current			40		fA
CMRR	Common Mode Rejection Ratio	$-5\text{V} \leq V_{CM} \leq 5\text{V}$	92 <b>88</b>	138		dB
PSRR	Power Supply Rejection Ratio	$2.7\text{V} \leq V^+ \leq 12\text{V}$ , $V_O = 0\text{V}$	86 <b>82</b>	98		dB
CMVR	Common Mode Voltage Range	CMRR ≥ 80 dB CMRR ≥ 78 dB	-5.2 <b>-5.2</b>		5.2 <b>5.2</b>	V
$A_{VOL}$	Open Loop Voltage Gain	$R_L = 2\text{ k}\Omega$ $V_O = -4.7\text{V}$ to $4.7\text{V}$	100 <b>98</b>	121		dB
		$R_L = 10\text{ k}\Omega$ $V_O = -4.8\text{V}$ to $4.8\text{V}$	100 <b>98</b>	134		
$V_{OUT}$	Output Voltage Swing High	$R_L = 2\text{ k}\Omega$ to $0\text{V}$		90	150 <b>170</b>	mV from $V^+$
		$R_L = 10\text{ k}\Omega$ to $0\text{V}$		40	80 <b>100</b>	
	Output Voltage Swing Low	$R_L = 2\text{ k}\Omega$ to $0\text{V}$		90	130 <b>150</b>	mV from $V^-$
		$R_L = 10\text{ k}\Omega$ to $0\text{V}$		40	50 <b>60</b>	
$I_{OUT}$	Output Current <sup>(6)(7)</sup>	Sourcing $V_O = 0\text{V}$ $V_{IN} = 100\text{ mV}$	50 <b>35</b>	86		mA
		Sinking $V_O = 0\text{V}$ $V_{IN} = -100\text{ mV}$	50 <b>35</b>	84		
$I_S$	Supply Current			0.790	1.1 <b>1.3</b>	mA
SR	Slew Rate <sup>(8)</sup>	$A_V = +1$ , $V_O = 9\text{ V}_{PP}$ 10% to 90%		1.1		V/μs
GBW	Gain Bandwidth			2.5		MHz
THD+N	Total Harmonic Distortion + Noise	$f = 1\text{ kHz}$ , $A_V = 1$ , $R_L = 10\text{ k}\Omega$		0.02		%
$e_n$	Input Referred Voltage Noise Density	$f = 1\text{ kHz}$		9		nV/√Hz
$i_n$	Input Referred Current Noise Density	$f = 100\text{ kHz}$		1		fA/√Hz

(1) Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that  $T_J = T_A$ . Parametric performance is indicated in the electrical tables under conditions of internal self-heating where  $T_J > T_A$ .

(2) Limits are 100% production tested at  $25^\circ\text{C}$ . Limits over the operating temperature range are specified through correlations using the Statistical Quality Control (SQC) method.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested on shipped production material.

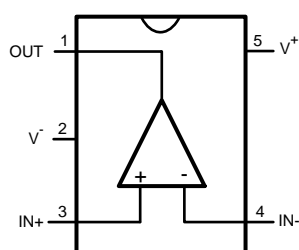
(4) This parameter is specified by design and/or characterization and is not tested in production.

(5) Positive current corresponds to current flowing into the device.

(6) The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A) / \theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

(7) The short circuit test is a momentary test.

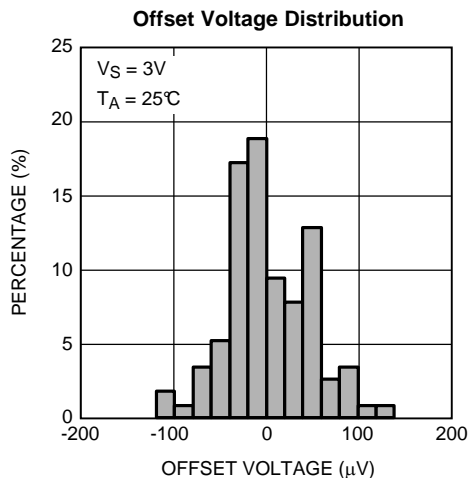
(8) The number specified is the slower of positive and negative slew rates.

**Connection Diagram**

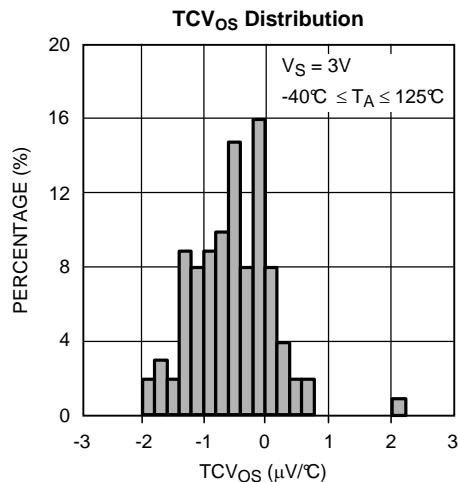
**Figure 2. 5-Pin SOT-23 - Top View**  
**See DBV Package**

## Typical Performance Characteristics

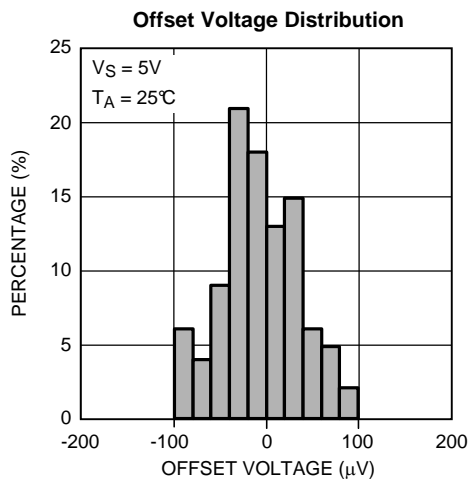
Unless otherwise noted:  $T_A = 25^\circ\text{C}$ ,  $V_{CM} = V_S/2$ ,  $R_L > 10\text{ k}\Omega$ .



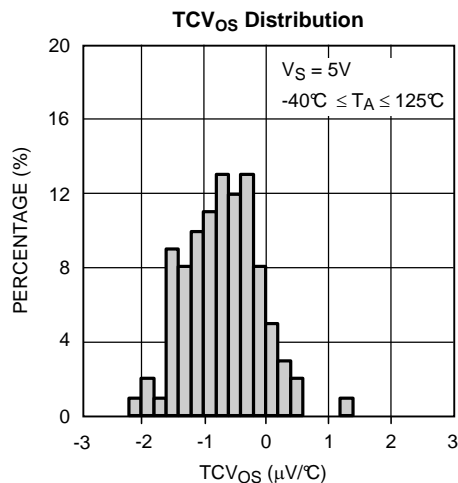
**Figure 3.**



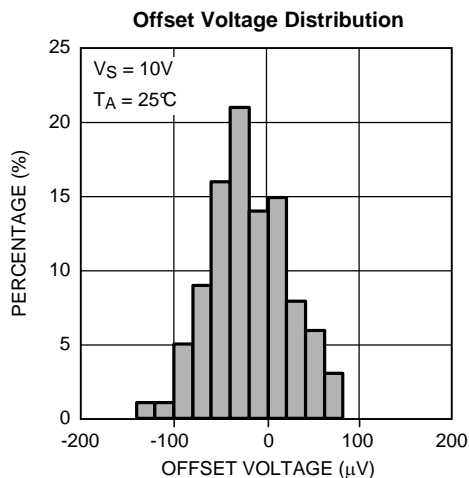
**Figure 4.**



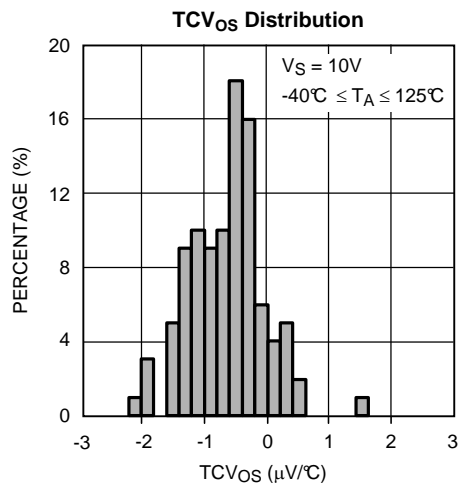
**Figure 5.**



**Figure 6.**



**Figure 7.**



**Figure 8.**

## Typical Performance Characteristics (continued)

Unless otherwise noted:  $T_A = 25^\circ\text{C}$ ,  $V_{CM} = V_S/2$ ,  $R_L > 10\text{ k}\Omega$ .

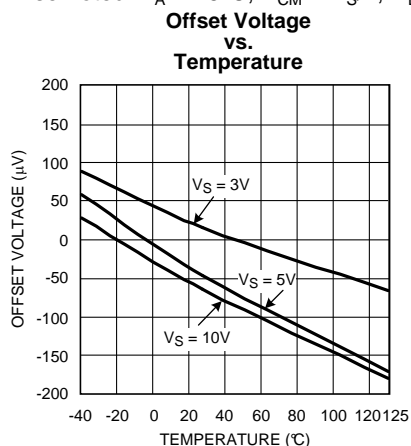


Figure 9.

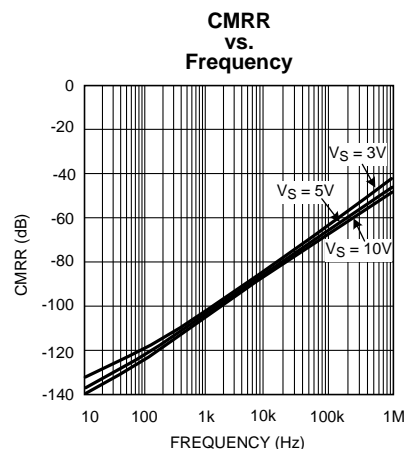


Figure 10.

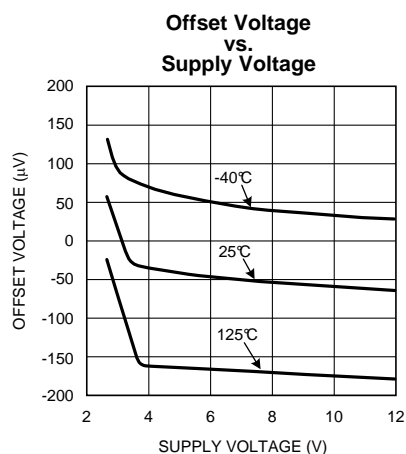


Figure 11.

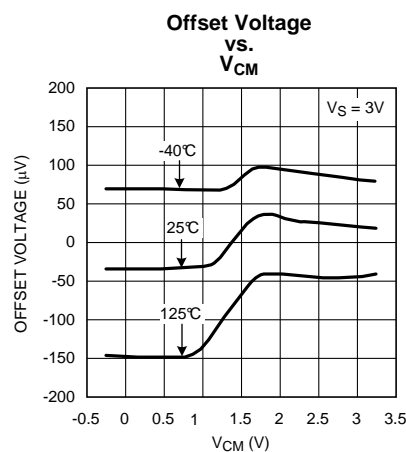


Figure 12.

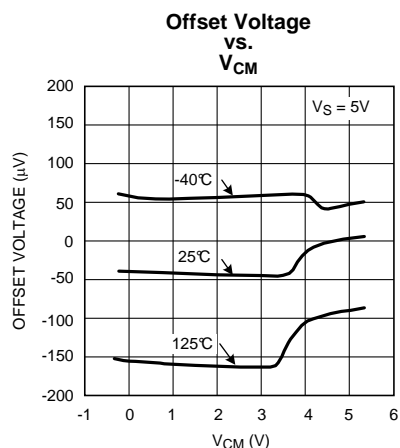


Figure 13.

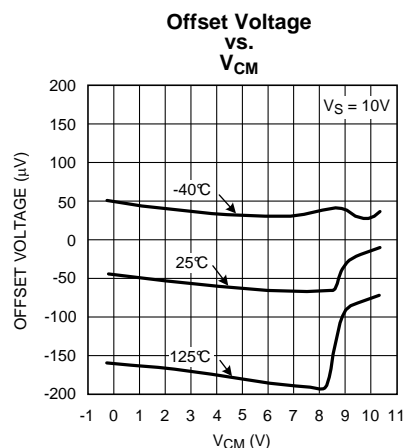


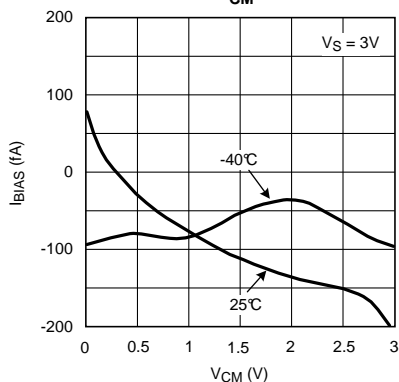
Figure 14.



## Typical Performance Characteristics (continued)

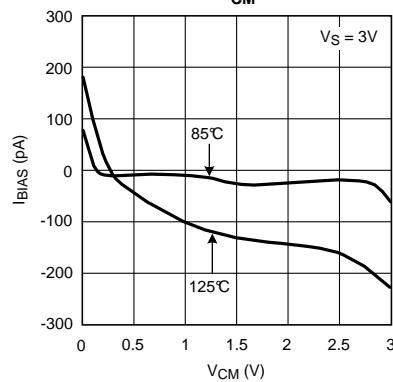
Unless otherwise noted:  $T_A = 25^\circ\text{C}$ ,  $V_{CM} = V_S/2$ ,  $R_L > 10\text{ k}\Omega$ .

**Input Bias Current  
vs.  
 $V_{CM}$**



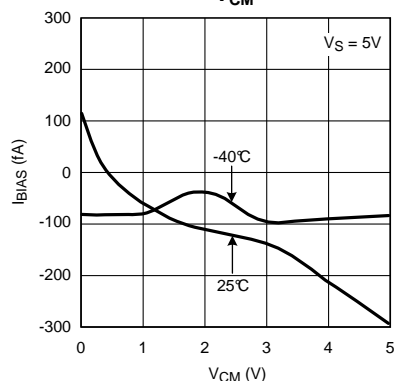
**Figure 15.**

**Input Bias Current  
vs.  
 $V_{CM}$**



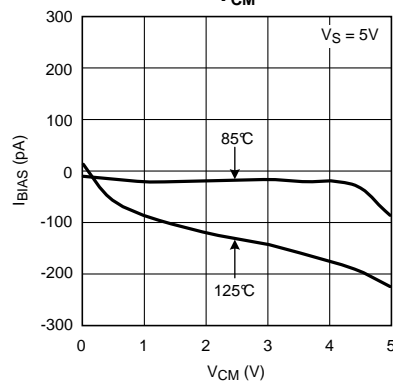
**Figure 16.**

**Input Bias Current  
vs.  
 $V_{CM}$**



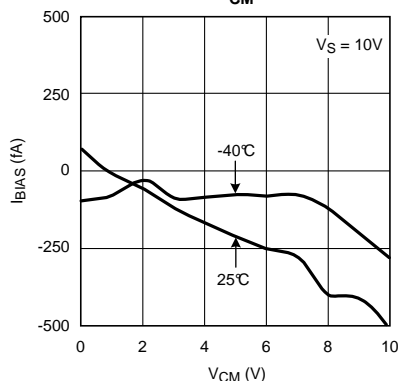
**Figure 17.**

**Input Bias Current  
vs.  
 $V_{CM}$**



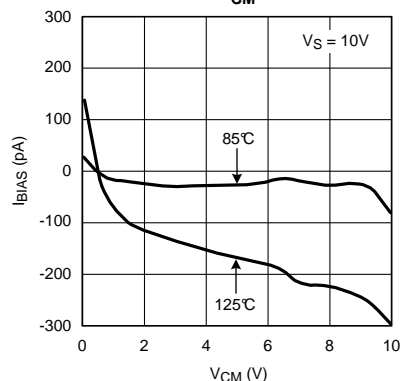
**Figure 18.**

**Input Bias Current  
vs.  
 $V_{CM}$**



**Figure 19.**

**Input Bias Current  
vs.  
 $V_{CM}$**



**Figure 20.**

## Typical Performance Characteristics (continued)

Unless otherwise noted:  $T_A = 25^\circ\text{C}$ ,  $V_{CM} = V_S/2$ ,  $R_L > 10\text{ k}\Omega$ .

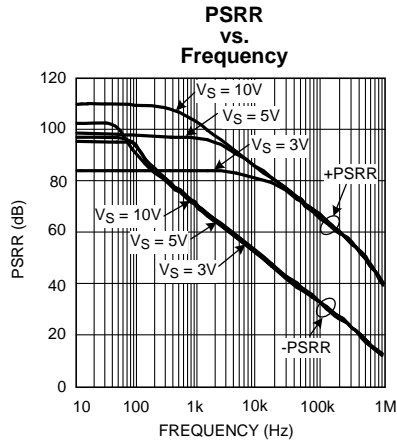


Figure 21.

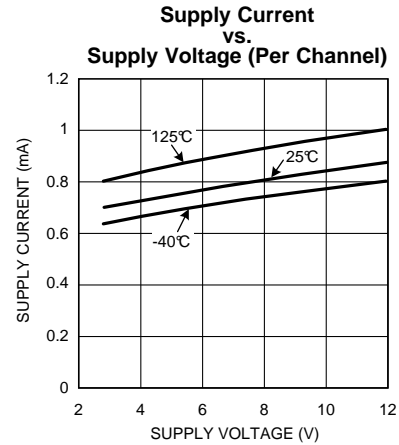


Figure 22.

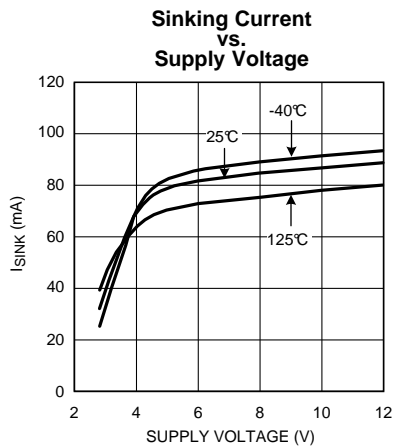


Figure 23.

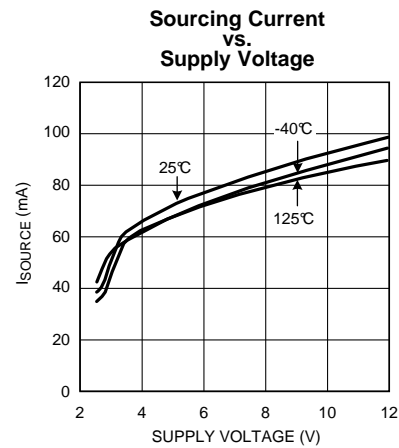


Figure 24.

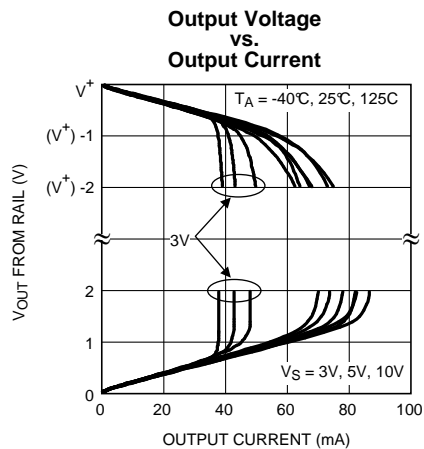


Figure 25.

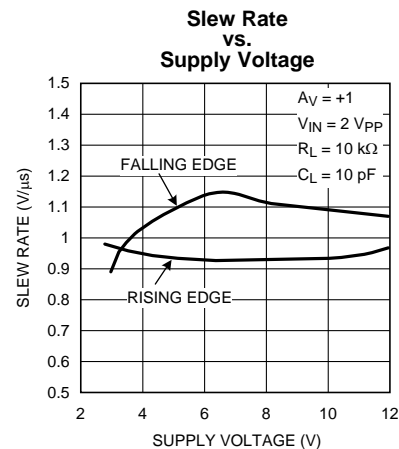


Figure 26.

## Typical Performance Characteristics (continued)

Unless otherwise noted:  $T_A = 25^\circ\text{C}$ ,  $V_{CM} = V_S/2$ ,  $R_L > 10\text{ k}\Omega$ .

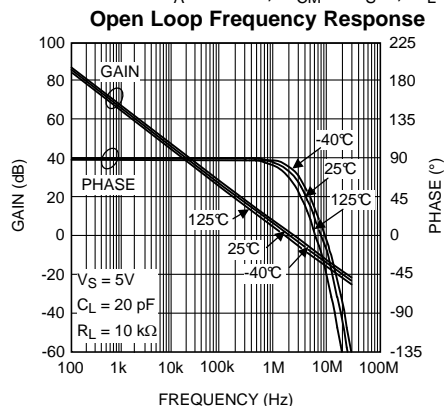


Figure 27.

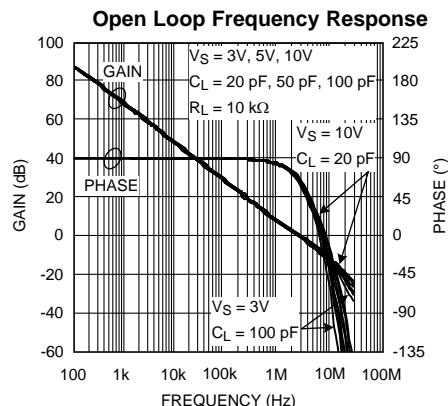


Figure 28.

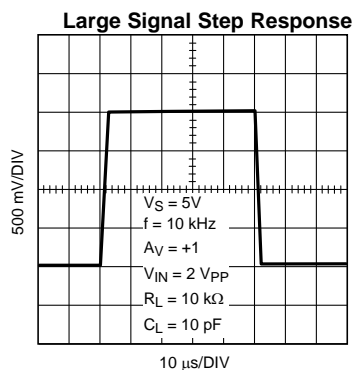


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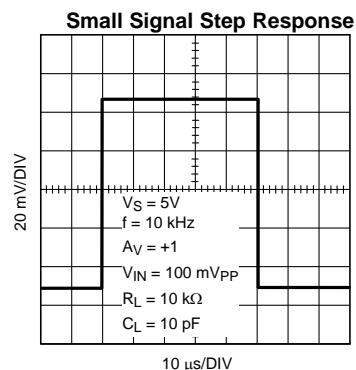


Figure 30.

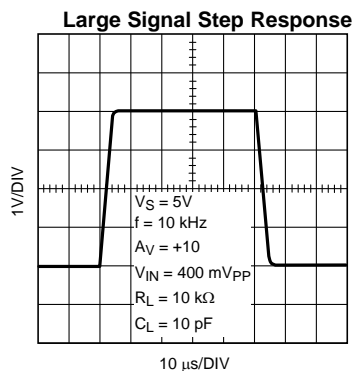


Figure 31.

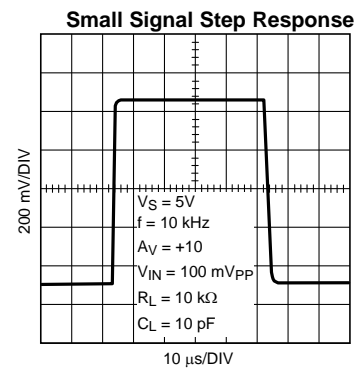


Figure 32.

## Typical Performance Characteristics (continued)

Unless otherwise noted:  $T_A = 25^\circ\text{C}$ ,  $V_{CM} = V_S/2$ ,  $R_L > 10\text{ k}\Omega$ .

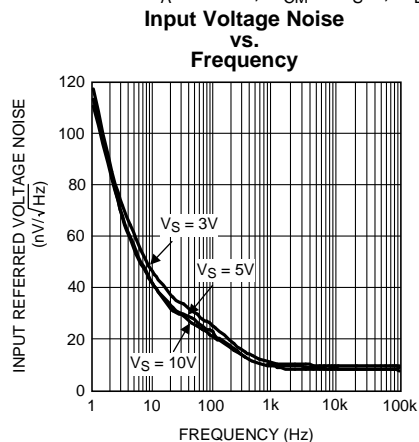


Figure 33.

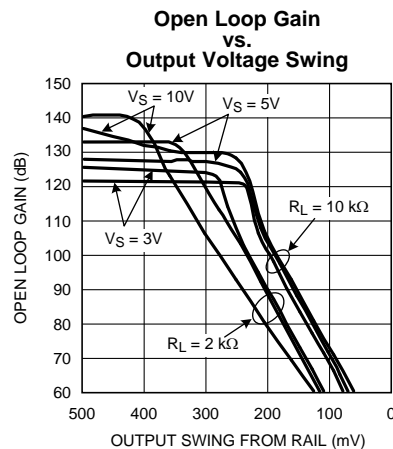


Figure 34.

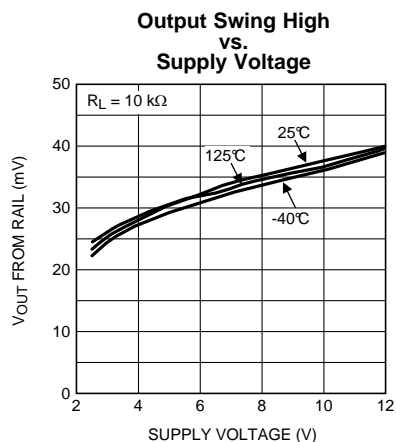


Figure 35.

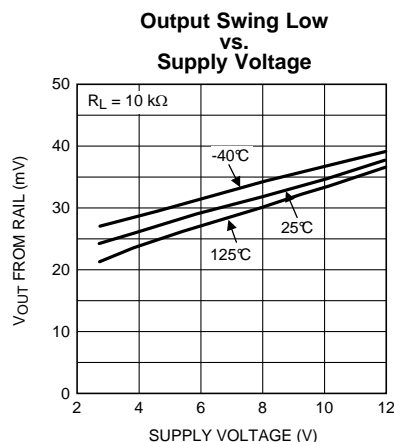


Figure 36.

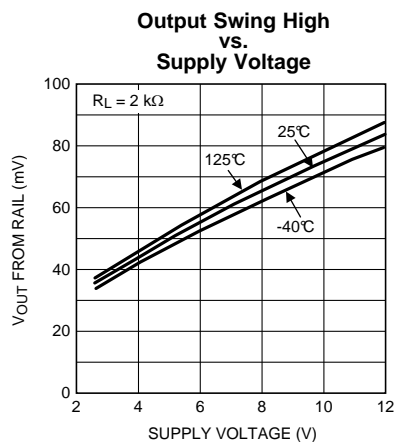


Figure 37.

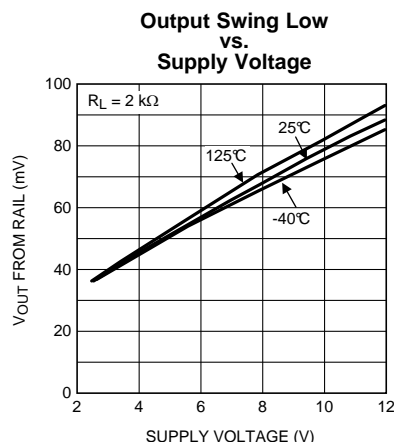
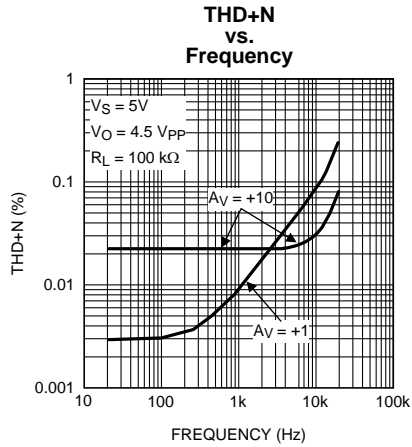


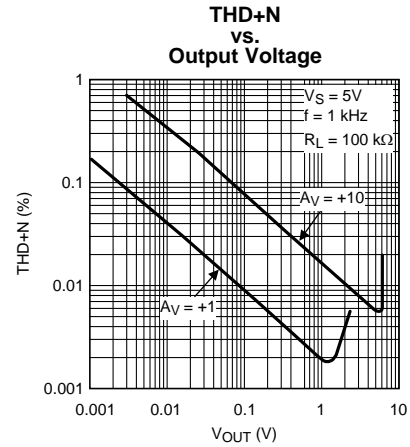
Figure 38.

## Typical Performance Characteristics (continued)

Unless otherwise noted:  $T_A = 25^\circ\text{C}$ ,  $V_{CM} = V_S/2$ ,  $R_L > 10\text{ k}\Omega$ .



**Figure 39.**



**Figure 40.**

## APPLICATION INFORMATION

### SM72501

The SM72501 is a low offset voltage, rail-to-rail input and output precision amplifier with a CMOS input stage and wide supply voltage range of 2.7V to 12V. The SM72501 has a very low input bias current of only  $\pm 200$  fA at room temperature.

The wide supply voltage range of 2.7V to 12V over the extensive temperature range of  $-40^{\circ}\text{C}$  to  $125^{\circ}\text{C}$  makes the SM72501 an excellent choice for low voltage precision applications with extensive temperature requirements.

The SM72501 has only  $\pm 37$   $\mu\text{V}$  of typical input referred offset voltage and this offset is specified to be less than  $\pm 500$   $\mu\text{V}$  over temperature. This minimal offset voltage allows more accurate signal detection and amplification in precision applications.

The low input bias current of only  $\pm 200$  fA along with the low input referred voltage noise of  $9 \text{ nV}/\sqrt{\text{Hz}}$  gives the SM72501 superiority for use in sensor applications. Lower levels of noise from the SM72501 means better signal fidelity and a higher signal-to-noise ratio.

Technical support and extensive characterization data is available for sensitive applications or applications with a constrained error budget.

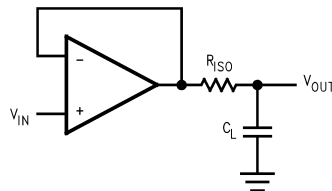
The SM72501 is offered in the space saving 5-Pin SOT-23. This small package is an ideal solution for area constrained PC boards and portable electronics.

### CAPACITIVE LOAD

The SM72501 can be connected as a non-inverting unity gain follower. This configuration is the most sensitive to capacitive loading.

The combination of a capacitive load placed on the output of an amplifier along with the amplifier's output impedance creates a phase lag which in turn reduces the phase margin of the amplifier. If the phase margin is significantly reduced, the response will be either underdamped or it will oscillate.

In order to drive heavier capacitive loads, an isolation resistor,  $R_{\text{ISO}}$ , in [Figure 41](#) should be used. By using this isolation resistor, the capacitive load is isolated from the amplifier's output, and hence, the pole caused by  $C_L$  is no longer in the feedback loop. The larger the value of  $R_{\text{ISO}}$ , the more stable the output voltage will be. If values of  $R_{\text{ISO}}$  are sufficiently large, the feedback loop will be stable, independent of the value of  $C_L$ . However, larger values of  $R_{\text{ISO}}$  result in reduced output swing and reduced output current drive.

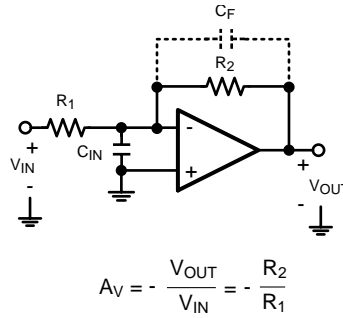


**Figure 41. Isolating Capacitive Load**

### INPUT CAPACITANCE

CMOS input stages inherently have low input bias current and higher input referred voltage noise. The SM72501 enhances this performance by having the low input bias current of only  $\pm 200$  fA, as well as, a very low input referred voltage noise of  $9 \text{ nV}/\sqrt{\text{Hz}}$ . In order to achieve this a larger input stage has been used. This larger input stage increases the input capacitance of the SM72501. The typical value of this input capacitance,  $C_{\text{IN}}$ , for the SM72501 is 25 pF. The input capacitance will interact with other impedances such as gain and feedback resistors, which are seen on the inputs of the amplifier, to form a pole. This pole will have little or no effect on the output of the amplifier at low frequencies and DC conditions, but will play a bigger role as the frequency increases. At higher frequencies, the presence of this pole will decrease phase margin and will also cause gain peaking. In order to compensate for the input capacitance, care must be taken in choosing the feedback resistors. In addition to being selective in picking values for the feedback resistor, a capacitor can be added to the feedback path to increase stability.

The DC gain of the circuit shown in [Figure 42](#) is simply  $-R_2/R_1$ .



**Figure 42. Compensating for Input Capacitance**

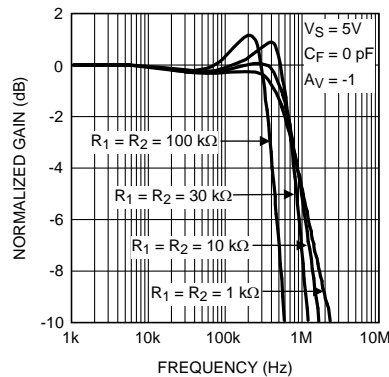
For the time being, ignore  $C_F$ . The AC gain of the circuit in Figure 42 can be calculated as follows:

$$\frac{V_{OUT}}{V_{IN}}(s) = \frac{-R_2/R_1}{1 + \frac{s}{\left(\frac{A_0 R_1}{R_1 + R_2}\right)} + \frac{s^2}{\left(\frac{A_0}{C_{IN} R_2}\right)}} \quad (1)$$

This equation is rearranged to find the location of the two poles:

$$P_{1,2} = \frac{-1}{2C_{IN}} \left[ \frac{1}{R_1} + \frac{1}{R_2} \pm \sqrt{\left(\frac{1}{R_1} + \frac{1}{R_2}\right)^2 - \frac{4A_0C_{IN}}{R_2}} \right] \quad (2)$$

As shown in Equation 2, as values of  $R_1$  and  $R_2$  are increased, the magnitude of the poles is reduced, which in turn decreases the bandwidth of the amplifier. Whenever possible, it is best to choose smaller feedback resistors. Figure 43 shows the effect of the feedback resistor on the bandwidth of the SM72501.

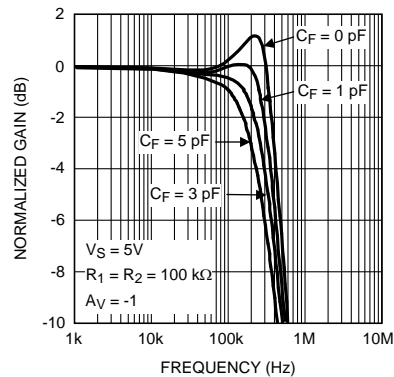


**Figure 43. Closed Loop Gain vs. Frequency**

Equation 2 has two poles. In most cases, it is the presence of pairs of poles that causes gain peaking. In order to eliminate this effect, the poles should be placed in Butterworth position, since poles in Butterworth position do not cause gain peaking. To achieve a Butterworth pair, the quantity under the square root in Equation 2 should be set to equal  $-1$ . Using this fact and the relation between  $R_1$  and  $R_2$ ,  $R_2 = -A_V R_1$ , the optimum value for  $R_1$  can be found. This is shown in Equation 3. If  $R_1$  is chosen to be larger than this optimum value, gain peaking will occur.

$$R_1 < \frac{(1 - A_V)^2}{2A_0A_VC_{IN}} \quad (3)$$

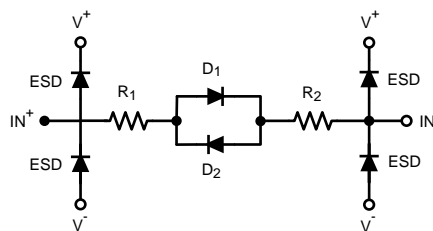
In Figure 42,  $C_F$  is added to compensate for input capacitance and to increase stability. Additionally,  $C_F$  reduces or eliminates the gain peaking that can be caused by having a larger feedback resistor. Figure 44 shows how  $C_F$  reduces gain peaking.



**Figure 44. Closed Loop Gain vs. Frequency with Compensation**

## DIODES BETWEEN THE INPUTS

The SM72501 has a set of anti-parallel diodes between the input pins, as shown in [Figure 45](#). These diodes are present to protect the input stage of the amplifier. At the same time, they limit the amount of differential input voltage that is allowed on the input pins. A differential signal larger than one diode voltage drop might damage the diodes. The differential signal between the inputs needs to be limited to  $\pm 300$  mV or the input current needs to be limited to  $\pm 10$  mA.

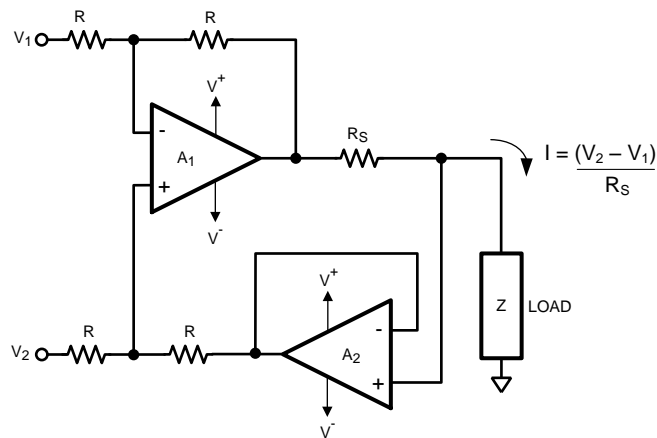


**Figure 45. Input of SM72501**

## PRECISION CURRENT SOURCE

The SM72501 can be used as a precision current source in many different applications. [Figure 46](#) shows a typical precision current source. This circuit implements a precision voltage controlled current source. Amplifier A1 is a differential amplifier that uses the voltage drop across  $R_S$  as the feedback signal. Amplifier A2 is a buffer that eliminates the error current from the load side of the  $R_S$  resistor that would flow in the feedback resistor if it were connected to the load side of the  $R_S$  resistor. In general, the circuit is stable as long as the closed loop bandwidth of amplifier A2 is greater than the closed loop bandwidth of amplifier A1. Note that if A1 and A2 are the same type of amplifiers, then the feedback around A1 will reduce its bandwidth compared to A2.





**Figure 46. Precision Current Source**

The equation for output current can be derived as follows:

$$\frac{V_2 R}{R + R} + \frac{(V_0 - I R_S) R}{R + R} = \frac{V_1 R}{R + R} + \frac{V_0 R}{R + R} \quad (4)$$

Solving for the current I results in the following equation:

$$I = \frac{V_2 - V_1}{R_S} \quad (5)$$

## LOW INPUT VOLTAGE NOISE

The SM72501 has a very low input voltage noise of  $9 \text{ nV}/\sqrt{\text{Hz}}$ . This input voltage noise can be further reduced by placing N amplifiers in parallel as shown in [Figure 47](#). The total voltage noise on the output of this circuit is divided by the square root of the number of amplifiers used in this parallel combination. This is because each individual amplifier acts as an independent noise source, and the average noise of independent sources is the quadrature sum of the independent sources divided by the number of sources. For N identical amplifiers, this means:

$$\begin{aligned} \text{REDUCED INPUT VOLTAGE NOISE} &= \frac{1}{N} \sqrt{e_{n1}^2 + e_{n2}^2 + \dots + e_{nN}^2} \\ &= \frac{1}{N} \sqrt{N e_n^2} = \frac{\sqrt{N}}{N} e_n \\ &= \frac{1}{\sqrt{N}} e_n \end{aligned} \quad (6)$$

[Figure 47](#) shows a schematic of this input voltage noise reduction circuit. Typical resistor values are:

$R_G = 10 \Omega$ ,  $R_F = 1 \text{ k}\Omega$ , and  $R_O = 1 \text{ k}\Omega$ .

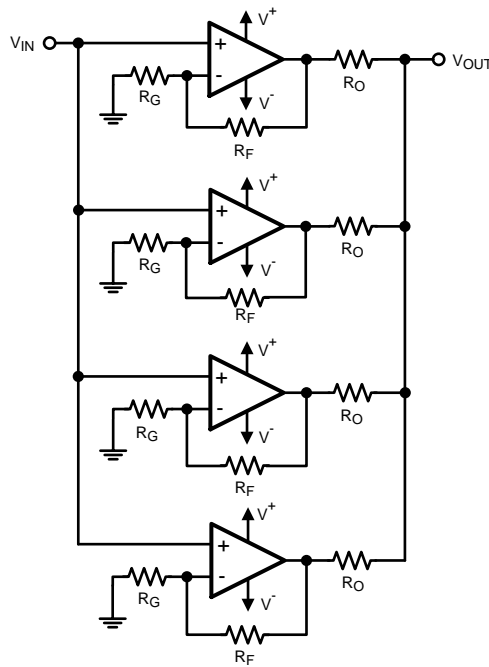


Figure 47. Noise Reduction Circuit

## TOTAL NOISE CONTRIBUTION

The SM72501 has very low input bias current, very low input current noise, and very low input voltage noise. As a result, these amplifiers are ideal choices for circuits with high impedance sensor applications.

Figure 48 shows the typical input noise of the SM72501 as a function of source resistance where:

$e_n$  denotes the input referred voltage noise

$e_i$  is the voltage drop across source resistance due to input referred current noise or  $e_i = R_S * i_n$

$e_t$  shows the thermal noise of the source resistance

$e_{ni}$  shows the total noise on the input.

Where:

$$e_{ni} = \sqrt{e_n^2 + e_i^2 + e_t^2} \quad (7)$$

The input current noise of the SM72501 is so low that it will not become the dominant factor in the total noise unless source resistance exceeds 300 MΩ, which is an unrealistically high value.

As is evident in Figure 48, at lower  $R_S$  values, total noise is dominated by the amplifier's input voltage noise. Once  $R_S$  is larger than a few kilo-Ohms, then the dominant noise factor becomes the thermal noise of  $R_S$ . As mentioned before, the current noise will not be the dominant noise factor for any practical application.

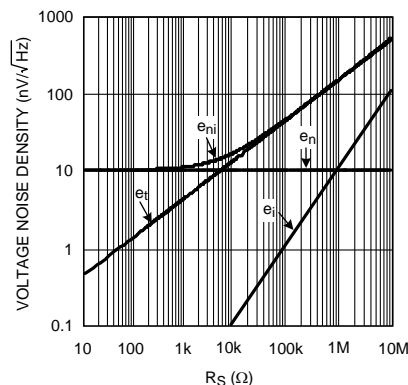


Figure 48. Total Input Noise

## HIGH IMPEDANCE SENSOR INTERFACE

Many sensors have high source impedances that may range up to 10 MΩ. The output signal of sensors often needs to be amplified or otherwise conditioned by means of an amplifier. The input bias current of this amplifier can load the sensor's output and cause a voltage drop across the source resistance as shown in Figure 49, where  $V_{IN+} = V_S - I_{BIAS} \cdot R_S$ .

The last term,  $I_{BIAS} \cdot R_S$ , shows the voltage drop across  $R_S$ . To prevent errors introduced to the system due to this voltage, an op amp with very low input bias current must be used with high impedance sensors. This is to keep the error contribution by  $I_{BIAS} \cdot R_S$  less than the input voltage noise of the amplifier, so that it will not become the dominant noise factor.

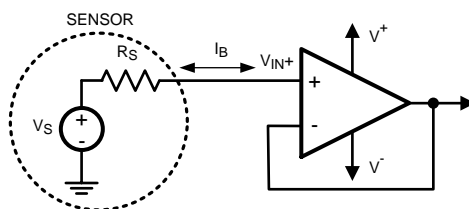


Figure 49. Noise Due to  $I_{BIAS}$

pH electrodes are very high impedance sensors. As their name indicates, they are used to measure the pH of a solution. They usually do this by generating an output voltage which is proportional to the pH of the solution. pH electrodes are calibrated so that they have zero output for a neutral solution, pH = 7, and positive and negative voltages for acidic or alkaline solutions. This means that the output of a pH electrode is bipolar and has to be level shifted to be used in a single supply system. The rate of change of this voltage is usually shown in mV/pH and is different for different pH sensors. Temperature is also an important factor in a pH electrode reading. The output voltage of the sensor will change with temperature.

Figure 50 shows a typical output voltage spectrum of a pH electrode. Note that the exact values of output voltage will be different for different sensors. In this example, the pH electrode has an output voltage of 59.15 mV/pH at 25°C.

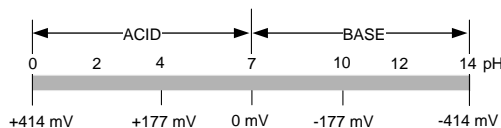
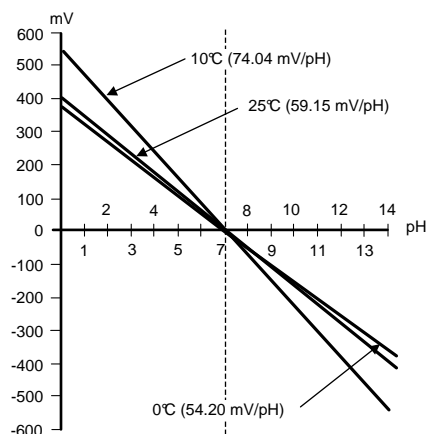


Figure 50. Output Voltage of a pH Electrode

The temperature dependence of a typical pH electrode is shown in Figure 51. As is evident, the output voltage changes with changes in temperature.



**Figure 51. Temperature Dependence of a pH Electrode**

The schematic shown in [Figure 52](#) is a typical circuit which can be used for pH measurement. The LM35 is a precision integrated circuit temperature sensor. This sensor is differentiated from similar products because it has an output voltage linearly proportional to Celsius measurement, without the need to convert the temperature to Kelvin. The LM35 is used to measure the temperature of the solution and feeds this reading to the Analog to Digital Converter, ADC. This information is used by the ADC to calculate the temperature effects on the pH readings. The LM35 needs to have a resistor,  $R_T$  in [Figure 52](#), to  $-V^+$  in order to be able to read temperatures below 0°C.  $R_T$  is not needed if temperatures are not expected to go below zero.

The output of pH electrodes is usually large enough that it does not require much amplification; however, due to the very high impedance, the output of a pH electrode needs to be buffered before it can go to an ADC. Since most ADCs are operated on single supply, the output of the pH electrode also needs to be level shifted. Amplifier A1 buffers the output of the pH electrode with a moderate gain of +2, while A2 provides the level shifting.  $V_{OUT}$  at the output of A2 is given by:  $V_{OUT} = -2V_{pH} + 1.024V$ .

The LM4140A is a precision, low noise, voltage reference used to provide the level shift needed. The ADC used in this application is the ADC12032 which is a 12-bit, 2 channel converter with multiplexers on the inputs and a serial output. The 12-bit ADC enables users to measure pH with an accuracy of 0.003 of a pH unit. Adequate power supply bypassing and grounding is extremely important for ADCs. Recommended bypass capacitors are shown in [Figure 52](#). It is common to share power supplies between different components in a circuit. To minimize the effects of power supply ripples caused by other components, the op amps need to have bypass capacitors on the supply pins. Using the same value capacitors as those used with the ADC are ideal. The combination of these three values of capacitors ensures that AC noise present on the power supply line is grounded and does not interfere with the amplifiers' signal.

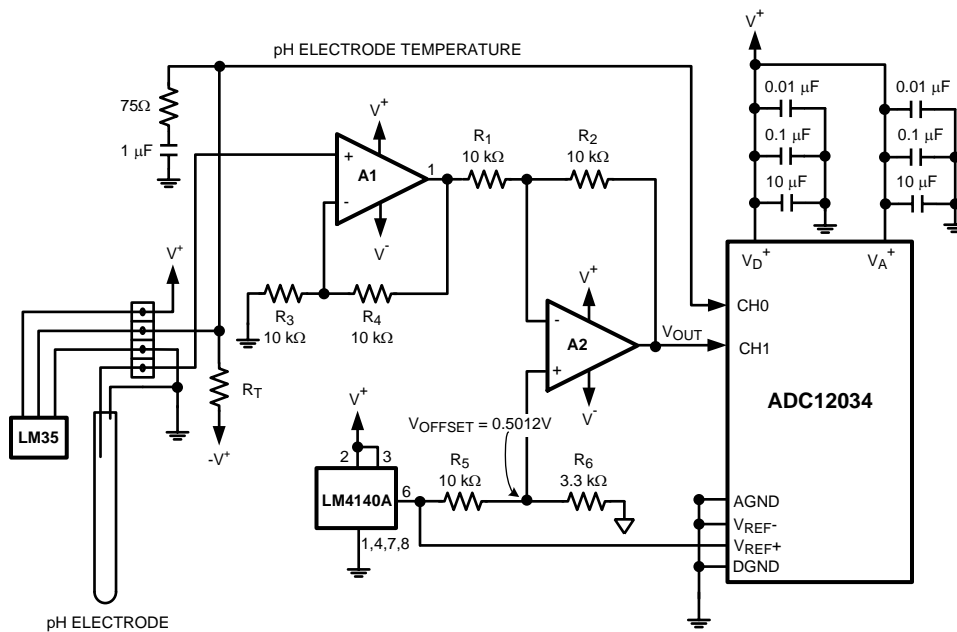


Figure 52. pH Measurement Circuit

REVISION HISTORY

Changes from Revision B (April 2013) to Revision C	Page
• Changed layout of National Data Sheet to TI format .....	<a href="#">21</a>

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
SM72501MF/NOPB	NRND	Production	SOT-23 (DBV)   5	1000   SMALL T&R	Yes	NIPDAU   SN	Level-1-260C-UNLIM	-40 to 125	S501
SM72501MF/NOPB.A	NRND	Production	SOT-23 (DBV)   5	1000   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	S501
SM72501MFE/NOPB	NRND	Production	SOT-23 (DBV)   5	250   SMALL T&R	Yes	NIPDAU   SN	Level-1-260C-UNLIM	-40 to 125	S501
SM72501MFE/NOPB.A	NRND	Production	SOT-23 (DBV)   5	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	S501
SM72501MFX/NOPB	NRND	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	NIPDAU   SN	Level-1-260C-UNLIM	-40 to 125	S501
SM72501MFX/NOPB.A	NRND	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	S501

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
SM72501MF/NOPB	SOT-23	DBV	5	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
SM72501MF/NOPB	SOT-23	DBV	5	1000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
SM72501MFE/NOPB	SOT-23	DBV	5	250	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
SM72501MFE/NOPB	SOT-23	DBV	5	250	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
SM72501MFX/NOPB	SOT-23	DBV	5	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
SM72501MFX/NOPB	SOT-23	DBV	5	3000	180.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3

## TAPE AND REEL BOX DIMENSIONS

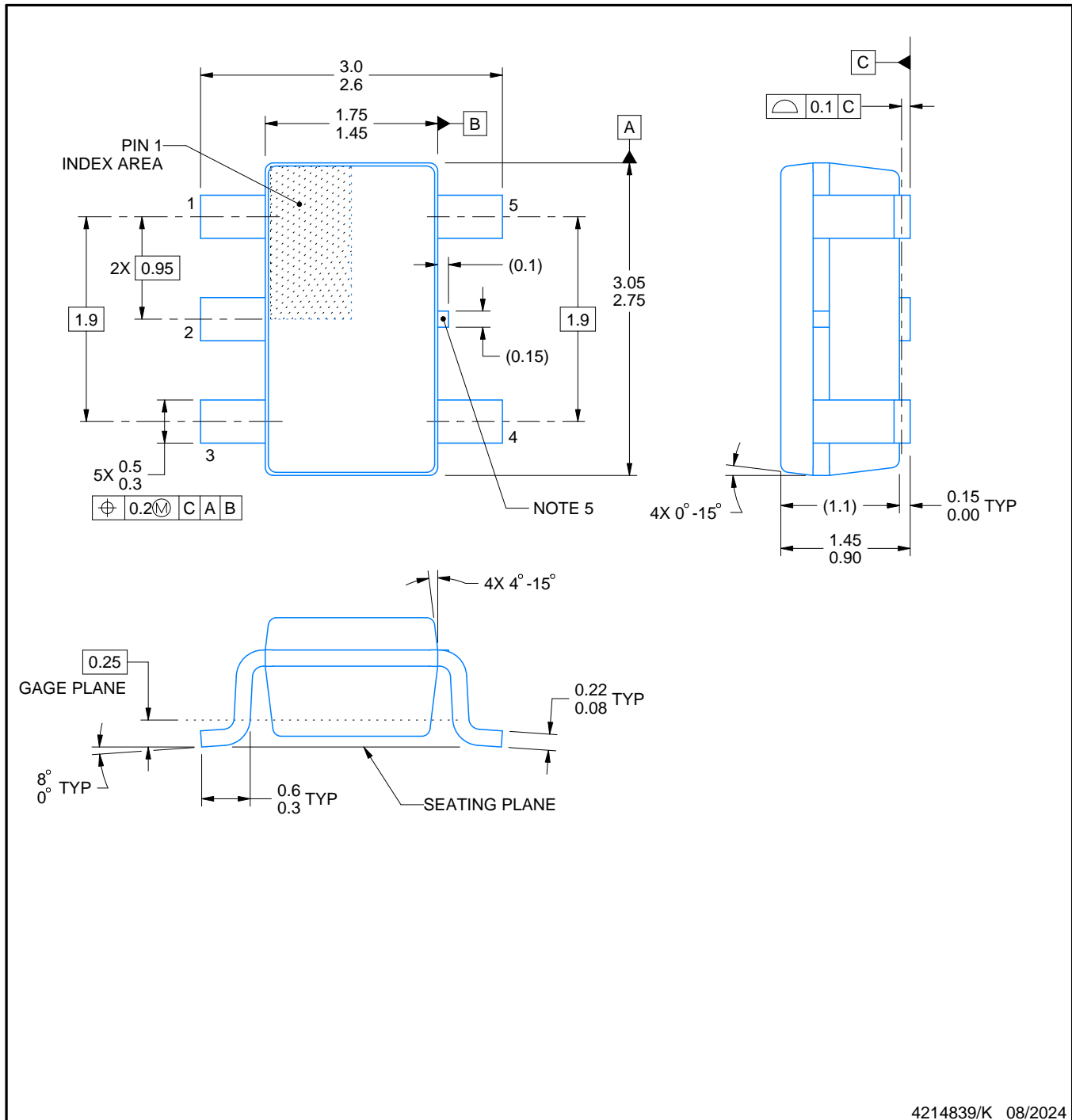


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
SM72501MF/NOPB	SOT-23	DBV	5	1000	208.0	191.0	35.0
SM72501MF/NOPB	SOT-23	DBV	5	1000	210.0	185.0	35.0
SM72501MFE/NOPB	SOT-23	DBV	5	250	208.0	191.0	35.0
SM72501MFE/NOPB	SOT-23	DBV	5	250	210.0	185.0	35.0
SM72501MFX/NOPB	SOT-23	DBV	5	3000	208.0	191.0	35.0
SM72501MFX/NOPB	SOT-23	DBV	5	3000	210.0	185.0	35.0

**DBV0005A****PACKAGE OUTLINE****SOT-23 - 1.45 mm max height**

SMALL OUTLINE TRANSISTOR

**NOTES:**

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Reference JEDEC MO-178.
4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
5. Support pin may differ or may not be present.

# EXAMPLE BOARD LAYOUT

DBV0005A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:15X



SOLDER MASK DETAILS

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NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

## EXAMPLE STENCIL DESIGN

DBV0005A

SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE:15X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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