



# Wideband, High Gain VOLTAGE LIMITING AMPLIFIER

## FEATURES

- HIGH LINEARITY NEAR LIMITING
- FAST RECOVERY FROM OVERDRIVE: 1ns
- LIMITING VOLTAGE ACCURACY:  $\pm 10\text{mV}$
- $-3\text{dB}$  BANDWIDTH ( $G = +6$ ): 260MHz
- GAIN BANDWIDTH PRODUCT: 1000MHz
- STABLE FOR  $G \geq +4\text{V/V}$
- SLEW RATE:  $1400\text{V}/\mu\text{s}$
- $\pm 5\text{V}$  AND  $+5\text{V}$  SUPPLY OPERATION
- LOW GAIN VERSION: OPA698

## DESCRIPTION

The OPA699 is a wideband, voltage-feedback op amp that offers bipolar output voltage limiting, and is stable for gains  $\geq +4$ . Two buffered limiting voltages take control of the output when it attempts to drive beyond these limits. This new output limiting architecture holds the limiter offset error to  $\pm 10\text{mV}$ . The op amp operates linearly to within 20mV of the limits.

The combination of narrow nonlinear range and low limiting offset allows the limiting voltages to be set within 100mV of the desired linear output range. A fast 1ns recovery from limiting ensures that overdrive signals will be transparent to

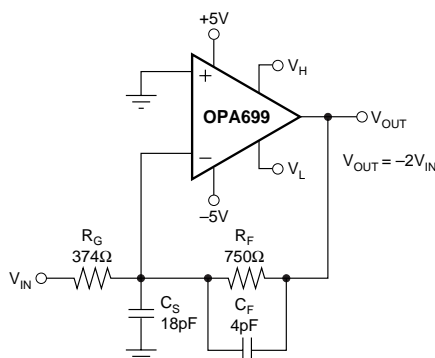
## APPLICATIONS

- TRANSIMPEDANCE WITH FAST OVERDRIVE RECOVERY
- FAST LIMITING ADC INPUT DRIVER
- LOW PROP DELAY COMPARATOR
- NONLINEAR ANALOG SIGNAL PROCESSING
- DIFFERENCE AMPLIFIER
- IF LIMITING AMPLIFIER
- OPA689 UPGRADE

the signal channel. Implementing the limiting function at the output, as opposed to the input, gives the specified limiting accuracy for any gain, and allows the OPA699 to be used in all standard op amp applications.

Nonlinear analog signal processing circuits will benefit from the OPA699 sharp transition from linear operation to output limiting. The quick recovery time supports high-speed applications.

The OPA699 is available in an industry-standard pinout in an SO-8 package. For lower gain applications requiring output limiting with fast recovery, consider the OPA698.



**Low Gain, Improved SFDR Amplifier with Output Limiting**



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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## ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

Supply Voltage .....	$\pm 6.5V$
Internal Power Dissipation .....	See Thermal Characteristics
Input Voltage Range .....	$\pm V_S$
Differential Input Voltage .....	$\pm V_S$
Limiter Voltage Range .....	$\pm(V_S - 0.7V)$
Storage Temperature Range: D .....	$-65^{\circ}C$ to $+125^{\circ}C$
Lead Temperature (SO-8, soldering, 3s) .....	$+260^{\circ}C$
Junction Temperature .....	$+150^{\circ}C$
ESD Resistance: HBM .....	2000V
MM .....	200V
CDM .....	1000V

NOTE: (1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability.



## ELECTROSTATIC DISCHARGE SENSITIVITY

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## RELATED PRODUCTS

	SINGLES	DUALS	DESCRIPTION
Output Limiting	OPA698		Unity Gain Stable, Wideband
Voltage Feedback	OPA690	OPA2690	High Slew, Unity Gain Stable

## PACKAGE/ORDERING INFORMATION<sup>(1)</sup>

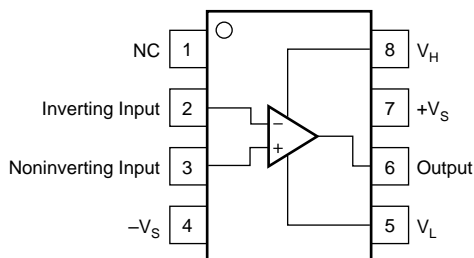
PRODUCT	PACKAGE-LEAD	PACKAGE DESIGNATOR	SPECIFIED TEMPERATURE RANGE	PACKAGE MARKING	ORDERING NUMBER	TRANSPORT MEDIA, QUANTITY
OPA699	SO-8	D	$-40^{\circ}C$ to $+85^{\circ}C$	OPA699ID	OPA699ID	Rails, 100
"	"	"	"	"	OPA699IDR	Tape and Reel, 2500

NOTE: (1) For the most current package and ordering information, see the Package Option Addendum located at the end of this document, or see the TI website at [www.ti.com](http://www.ti.com).

## PIN CONFIGURATION

Top View

SO



NC = No Connection

# ELECTRICAL CHARACTERISTICS: $V_S = \pm 5V$

**Boldface** limits are tested at **+25°C**.

$G = +6$ ,  $R_F = 750\Omega$ ,  $R_L = 500\Omega$ , and  $V_H = -V_L = 2V$ , (see Figure 1 for AC performance only), unless otherwise noted.

PARAMETER	CONDITIONS	OPA699ID						TEST LEVEL <sup>(3)</sup>
		TYP	MIN/MAX OVER TEMPERATURE					
		+25°C	+25°C <sup>(1)</sup>	0°C to 70°C <sup>(2)</sup>	−40°C to +85°C <sup>(2)</sup>	UNITS	MIN/MAX	
<b>AC PERFORMANCE (see Figure 1)</b>								
Small Signal Bandwidth (V <sub>O</sub> < 0.5V <sub>PP</sub> )	G = +6	260	220	215	210	MHz	min	B
	G = +12	86				MHz	typ	C
	G = −6	269				MHz	typ	C
Gain Bandwidth Product (G ≥ +20)	V <sub>O</sub> < 0.5V <sub>PP</sub> , G = +6	1000	820	800	750	MHz	min	B
Gain Peaking	V <sub>O</sub> < 0.5V <sub>PP</sub> , G = +4	7.5				dB	typ	C
0.1dB Gain Flatness Bandwidth	V <sub>O</sub> < 0.5V <sub>PP</sub>	30				MHz	typ	C
Large-Signal Bandwidth	V <sub>O</sub> = 4V <sub>PP</sub>	290	190	180	170	MHz	min	B
Step Response								
Slew Rate	4V Step	1400	1300	1200	1100	V/μs	min	B
Rise-and-Fall Time	0.5V Step	1.6	1.65	1.8	2	ns	max	B
Settling Time: 0.05%	2V Step	8				ns	typ	C
Spurious-Free Dynamic Range, Even	f = 5MHz, V <sub>O</sub> = 2V <sub>PP</sub>	67	64	62	60	dB	min	B
Odd	f = 5MHz, V <sub>O</sub> = 2V <sub>PP</sub>	87	85	84	80	dB	min	B
Differential Gain	NTSC, PAL, R <sub>L</sub> = 500Ω	0.012				%	typ	C
Differential Phase	NTSC, PAL, R <sub>L</sub> = 500Ω	0.008				°	typ	C
Input Noise Density								
Voltage Noise	f ≥ 1MHz	4.1	4.6	5.2	5.5	nV/√Hz	max	B
Current Noise	f ≥ 1MHz	2.0	2.5	2.7	2.9	pA/√Hz	max	B
<b>DC PERFORMANCE (V<sub>CM</sub> = 0V)</b>								
Open-Loop Voltage Gain (A <sub>OL</sub> )	V <sub>O</sub> = ±0.5V	66	<b>58</b>	56	55	dB	min	A
Input Offset Voltage		±1.5	<b>±5.0</b>	±6	±7	mV	max	A
Average Drift		—		±15	±20	μV/°C	max	B
Input Bias Current <sup>(4)</sup>		+3	<b>±10</b>	±11	±12	μA	max	A
Average Drift		—		±15	±20	nA/°C	max	B
Input Offset Current		±0.3	<b>±2</b>	±2.5	±3	μA	max	A
Average Drift		—		±10	±10	nA/°C	max	B
<b>INPUT</b>								
Common-Mode Rejection Ratio	Input Referred, V <sub>CM</sub> = ±0.5V	61	<b>55</b>	54	52	dB	min	A
Common-Mode Input Range <sup>(5)</sup>		±3.3	<b>±3.2</b>	±3.2	±3.1	V	min	A
Input Impedance								
Differential-Mode		0.32    1				MΩ    pF	typ	C
Common-Mode		3.5    1				MΩ    pF	typ	C
<b>OUTPUT</b>								
Output Voltage Range	V <sub>H</sub> = −V <sub>L</sub> = 4.3V	±4.1	<b>±3.9</b>	±3.9	±3.8	V	min	A
Current Output, Sourcing	R <sub>L</sub> ≥ 500Ω	+120	<b>+90</b>	+85	+80	mA	min	A
Sinking		−120	<b>−90</b>	−85	−80	mA	min	A
Closed-Loop Output Impedance	G = +4, f < 100kHz	0.8				Ω	typ	C
<b>POWER SUPPLY</b>								
Operating Voltage, Specified		±5				V	typ	C
Maximum		—	<b>±6</b>	±6	±6	V	max	A
Quiescent Current, Maximum	V <sub>S</sub> = ±5V	15.5	<b>15.9</b>	16.3	16.6	mA	max	A
Minimum	V <sub>S</sub> = ±5V	15.5	<b>15.2</b>	14.9	14.6	mA	min	A
Power-Supply Rejection Ratio +PSRR (Input Referred)	+V <sub>S</sub> = 4.5V to 5.5V	75	<b>68</b>	67	66	dB	min	A

NOTES: (1) Junction temperature = ambient temperature for low temperature limit and +25°C Test Level A specifications. Junction temperature = ambient temperature + 23°C at high temperature limit Test Level A specifications.

(2) Junction temperature = ambient at low temperature limit; junction temperature = ambient +1°C at high temperature limit for over-temperature tested specifications.

(3) Test Levels: (A) 100% tested at +25°C. Over temperature limits by characterization and simulation. (B) Limits set by characterization and simulation. (C) Typical value for information only.

(4) Current is considered positive out-of-node.

(5) CMIR tested as < 3dB degradation from minimum CMRR at specified limits.

(6)  $I_{VH}$  ( $V_H$  bias current) is positive, and  $I_{VL}$  ( $V_L$  bias current) is negative, under these conditions. See Note 3 and Figures 1 and 12.

(7) Limiter feedthrough is the ratio of the output magnitude to the sinewave added to  $V_H$  (or  $V_L$ ) when  $V_{IN} = 0$ .

# ELECTRICAL CHARACTERISTICS: $V_S = \pm 5V$ (Cont.)

**Boldface** limits are tested at **+25°C**.

$G = +6$ ,  $R_F = 750\Omega$ ,  $R_L = 500\Omega$ ,  $V_H = -V_L = 2V$ , (Figure 1 for AC performance only), unless otherwise noted.

PARAMETER	CONDITIONS	OPA699ID						TEST LEVEL <sup>(3)</sup>
		TYP	MIN/MAX OVER TEMPERATURE					
		+25°C	+25°C <sup>(1)</sup>	0°C to 70°C <sup>(2)</sup>	−40°C to +85°C <sup>(2)</sup>	UNITS	MIN/MAX	
OUTPUT VOLTAGE LIMITERS	Pins 5 and 8							
Output Voltage Limited Range		±3.8					typ	C
Default Limit Voltage, Upper	Limiter Pins Open	+3.5	+3.3	+3.2	+3.1	V	min	A
Lower		−3.5	−3.3	−3.2	−3.1	V	max	A
Minimum Limiter Separation (V <sub>H</sub> − V <sub>L</sub> )		400	400	400	400	mV	min	B
Maximum Limit Voltage		—	±4.3	±4.3	±4.3	V	max	B
Limiter Input Bias Current Magnitude <sup>(6)</sup>	V <sub>O</sub> = 0							
Maximum		50	60	62	64	μA	max	A
Minimum		50	40	38	36	μA	min	A
Average Drift		—		30	35	nA/°C	max	B
Limiter Input Impedance		3.4    1				MΩ    pF	typ	C
Limiter Feedthrough <sup>(7)</sup>	f = 5MHz	−60				dB	typ	C
DC Performance in Limit Mode	V <sub>IN</sub> = ±0.7V							
Limiter Offset Voltage	(V <sub>O</sub> − V <sub>H</sub> ) or (V <sub>O</sub> − V <sub>L</sub> )	±10	±30	±35	±40	mV	max	A
Op Amp Input Bias Current Shift <sup>(4)</sup>	Linear ↔ Limited Operation	3				μA	typ	C
AC Performance in Limit Mode								
Limiter Small-Signal Bandwidth	V <sub>IN</sub> = ±0.7V, V <sub>O</sub> < 0.02V <sub>PP</sub>	600				MHz	typ	C
Limiter Slew Rate <sup>(8)</sup>		125				V/μs	typ	C
Limited Step Response								
Overshoot	V <sub>IN</sub> = 0V to ±0.7V Step	250				mV	typ	C
Recovery Time	V <sub>IN</sub> = ±0.7V to 0V Step	1	1.9	2	2.1	ns	max	B
Linearity Guardband <sup>(9)</sup>	f = 5MHz, V <sub>O</sub> = 2V <sub>PP</sub>	30				mV	typ	C
THERMAL CHARACTERISTICS								
Temperature Range	Specification, I	−40 to +85				°C	typ	C
Thermal Resistance	Junction-to-Ambient	125				°C/W	typ	C
D SO-8								

NOTES: (1) Junction temperature = ambient temperature for low temperature limit and +25°C Test Level A specifications. Junction temperature = ambient temperature +23°C at high temperature limit Test Level A specifications.

(2) Junction temperature = ambient at low temperature limit; junction temperature = ambient +1°C at high temperature limit for over-temperature tested specifications.

(3) Test Levels: (A) 100% tested at +25°C. Over temperature limits by characterization and simulation. (B) Limits set by characterization and simulation. (C) Typical value for information only.

(4) Current is considered positive out-of-node.

(5) CMIR tested as < 3dB degradation from minimum CMRR at specified limits.

(6)  $I_{VH}$  ( $V_H$  bias current) is positive, and  $I_{VL}$  ( $V_L$  bias current) is negative, under these conditions. See Note 3 and Figures 1 and 12.

(7) Limiter feedthrough is the ratio of the output magnitude to the sinewave added to  $V_H$  (or  $V_L$ ) when  $V_{IN} = 0$ .

(8)  $V_H$  slew rate conditions are:  $V_{IN} = +0.7V$ ,  $G = +6$ ,  $V_L = -2V$ ,  $V_H =$  step between 2V and 0V.  $V_L$  slew rate conditions are similar.

(9) Linearity Guardband is defined for an output sinusoid ( $f = 1MHz$ ,  $V_O = 2V_{PP}$ ) centered between the limiter levels ( $V_H$  and  $V_L$ ). It is the difference between the limiter level and the peak output voltage where SFDR decreases by 3dB (see Figure 8).

# ELECTRICAL CHARACTERISTICS: $V_S = +5V$

**Boldface** limits are tested at **+25°C**.

$G = +6$ ,  $R_F = 750\Omega$ ,  $R_L = 500\Omega$  tied to  $V_{CM} = +2.5V$ ,  $V_L = V_{CM} - 1.2V$ , and  $V_H = V_{CM} + 1.2V$ , (see Figure 2 for AC performance only), unless otherwise noted.

PARAMETER	CONDITIONS	OPA699ID						TEST LEVEL <sup>(3)</sup>
		TYP	MIN/MAX OVER TEMPERATURE					
		+25°C	+25°C <sup>(1)</sup>	0°C to 70°C <sup>(2)</sup>	−40°C to +85°C <sup>(2)</sup>	UNITS	MIN/MAX	
<b>AC PERFORMANCE (see Figure 2)</b>								
Small Signal Bandwidth (V <sub>O</sub> < 0.5V <sub>PP</sub> )	G = +6	234	200	190	180	MHz	min	B
	G = +12	83				MHz	typ	C
	G = −6	242				MHz	typ	C
Gain Bandwidth Product (G ≥ +20)	V <sub>O</sub> < 0.5V <sub>PP</sub>	880	700	650	600	MHz	min	B
Gain Peaking	V <sub>O</sub> < 0.5V <sub>PP</sub> , G = +4	8				dB	typ	C
0.1dB Gain Flatness Bandwidth	V <sub>O</sub> < 0.5V <sub>PP</sub> , G = +6	30				MHz	typ	C
Large-Signal Bandwidth	V <sub>O</sub> = 2V <sub>PP</sub>	250	200	190	180	MHz	min	B
Step Response								
Slew Rate	2V Step	1050	850	800	700	V/μs	min	B
Rise-and-Fall Time	0.5V Step	1.75	1.8	1.9	2.1	ns	max	B
Settling Time: 0.05%	2V Step	8				ns	typ	C
Spurious-Free Dynamic Range, Even	f = 5MHz, V <sub>O</sub> = 2V <sub>PP</sub>	64	61	60	58	dB	min	B
Odd	f = 5MHz, V <sub>O</sub> = 2V <sub>PP</sub>	70	69	67	65	dB	min	B
Input Noise								
Voltage Noise Density	f ≥ 1MHz	4.2	4.6	5.2	5.6	nV/√Hz	max	B
Current Noise Density	f ≥ 1MHz	2.1	2.6	2.8	3.0	pA/√Hz	max	B
<b>DC PERFORMANCE</b>								
Open-Loop Voltage Gain (A <sub>OL</sub> )	V <sub>O</sub> = V <sub>CM</sub> ± 0.5V	66	<b>56</b>	54	53	dB	min	A
Input Offset Voltage		±2	<b>±6</b>	±7	±8	mV	max	A
Average Drift		—		±14	±14	μV/°C	max	B
Input Bias Current <sup>(4)</sup>		±3	<b>±10</b>	±11	±12	μA	max	A
Average Drift		—		±25	±25	nA/°C	max	B
Input Offset Current		±0.4	<b>±2</b>	±2.5	±3	μA	max	A
Average Drift		—		±15	±15	nA/°C	max	B
<b>INPUT</b>								
Common-Mode Rejection Ratio	Input Referred, V <sub>CM</sub> ±0.5V	58	<b>54</b>	53	52	dB	min	A
Common-Mode Input Range <sup>(5)</sup>		V <sub>CM</sub> ±0.8	<b>V<sub>CM</sub> ±0.7</b>	V <sub>CM</sub> ±0.7	V <sub>CM</sub> ±0.6	V	min	A
Input Impedance						MΩ    pF	typ	C
Differential-Mode		0.32    1						
Common-Mode		3.5    1				MΩ    pF	typ	C
<b>OUTPUT</b>								
Output Voltage Range	V <sub>H</sub> = V <sub>CM</sub> + 1.8V, V <sub>L</sub> = V <sub>CM</sub> − 1.8V	V <sub>CM</sub> ±1.6	<b>V<sub>CM</sub> ±1.4</b>	V <sub>CM</sub> ±1.4	V <sub>CM</sub> ±1.3	V	min	A
Current Output, Sourcing	R <sub>L</sub> ≥ 500Ω	+70	<b>+60</b>	+55	+50	mA	min	A
Sinking		−70	<b>−60</b>	−55	−50	mA	min	A
Closed-Loop Output Impedance	G = +4, f < 100kHz	0.2				Ω	typ	C
<b>POWER SUPPLY</b>								
Operating Voltage, Specified		5				V	typ	C
Maximum		—	<b>+12</b>	+12	+12	V	max	A
Quiescent Current, Maximum	V <sub>S</sub> = +5V	14.3	<b>14.9</b>	15.1	15.3	mA	max	A
Minimum	V <sub>S</sub> = +5V	14.3	<b>13.6</b>	13.4	13.2	mA	min	A
Power-Supply Rejection Ratio +PSRR (Input Referred)	V <sub>S</sub> = 4.5V to 5.5V	70				dB	typ	C

NOTES: (1) Junction temperature = ambient temperature for low temperature limit and +25°C Test Level A specifications. Junction temperature = ambient temperature +23°C at high temperature limit Test Level A specifications.

(2) Junction temperature = ambient at low temperature limit; junction temperature = ambient +1°C at high temperature limit for over-temperature tested specifications.

(3) Test Levels: (A) 100% tested at +25°C. Over temperature limits by characterization and simulation. (B) Limits set by characterization and simulation. (C) Typical value for information only.

(4) Current is considered positive out of node.

(5) CMIR tested as < 3dB degradation from minimum CMRR at specified limits.

(6)  $I_{VH}$  ( $V_H$  bias current) is negative, and  $I_{VL}$  ( $V_L$  bias current) is positive, under these conditions. See Note 3 and Figures 2 and 12.

(7) Limiter feedthrough is the ratio of the output magnitude to the sinewave added to  $V_H$  (or  $V_L$ ) when  $V_{IN} = 0$ .

(8)  $V_H$  slew rate conditions are:  $V_{IN} = V_{CM} + 0.4V$ ,  $G = +6$ ,  $V_L = V_{CM} - 1.2V$ ,  $V_H = \text{step between } V_{CM} + 1.2V \text{ and } V_{CM}$ .  $V_L$  slew rate conditions are similar.

(9) Linearity Guardband is defined for an output sinusoid ( $f = 5\text{MHz}$ ,  $V_O = V_{CM} \pm 1V_{PP}$ ) centered between the limiter levels ( $V_H$  and  $V_L$ ). It is the difference between the limiter level and the peak output voltage where SFDR decreases by 3dB (see Figure 8).

# ELECTRICAL CHARACTERISTICS: $V_S = +5V$ (Cont.)

**Boldface limits are tested at +25°C.**

$G = +6$ ,  $R_F = 750\Omega$ ,  $R_L = 500\Omega$  tied to  $V_{CM} = +2.5V$ ,  $V_L = V_{CM} - 1.2V$ , and  $V_H = V_{CM} + 1.2V$ , (see Figure 2 for AC performance only), unless otherwise noted.

PARAMETER	CONDITIONS	OPA699ID						TEST LEVEL <sup>(3)</sup>
		TYP	MIN/MAX OVER TEMPERATURE					
		+25°C	+25°C <sup>(1)</sup>	0°C to 70°C <sup>(2)</sup>	−40°C to +85°C <sup>(2)</sup>	UNITS	MIN/ MAX	
<b>OUTPUT VOLTAGE LIMITERS</b>								
Maximum Limited Voltage	Limiter Pins Open	+3.9	<b>V<sub>CM</sub> ±0.9</b>	V <sub>CM</sub> ±0.8	V <sub>CM</sub> ±0.7	V	typ	C
Minimum Limited Voltage		+1.1				V	typ	C
Default Limiter Voltage		V <sub>CM</sub> ±1.1				V	min	B
Minimum Limiter Separation (V <sub>H</sub> − V <sub>L</sub> )		400				400	mV	min
Maximum Limit Voltage	V <sub>O</sub> = 2.5V	—	V <sub>CM</sub> ±1.8	V <sub>CM</sub> ±1.8	V <sub>CM</sub> ±1.8	V	max	B
Limiter Input Bias Current Magnitude <sup>(6)</sup>		−15				μA	typ	C
Limiter Input Impedance		3.4    1				MΩ    pF	typ	C
Limiter Isolation <sup>(7)</sup>		f = 5MHz				−60	dB	typ
DC Performance in Limit Mode	V <sub>IN</sub> = V <sub>CM</sub> ±0.4V							
Limiter Voltage Accuracy	(V <sub>O</sub> − V <sub>H</sub> ) or (V <sub>O</sub> − V <sub>L</sub> )	±15	<b>±30</b>	±35	±40	mV	max	A
Op Amp Bias Current Shift <sup>(4)</sup>	Linear ↔ Limited Operation	5				μA	typ	C
AC Performance in Limit Mode								
Limiter Small-Signal Bandwidth	V <sub>IN</sub> = ±0.4V, V <sub>O</sub> < 0.02V <sub>PP</sub>	450				MHz	typ	C
Limiter Slew Rate <sup>(8)</sup>		100				V/μs	typ	C
Limited Step Response								
Overshoot	V <sub>IN</sub> = V <sub>CM</sub> to V <sub>CM</sub> ±0.4V Step	55				mV	typ	C
Recovery Time	V <sub>IN</sub> = V <sub>CM</sub> ±0.4V to V <sub>CM</sub> Step	3				ns	typ	C
Linearity Guardband <sup>(9)</sup>	f = 5MHz, V <sub>O</sub> = 2V <sub>PP</sub>	30				mV	typ	C
<b>THERMAL CHARACTERISTICS</b>								
Temperature Range	Specification, I	−40 to +85				°C	typ	C
Thermal Resistance	Junction-to-Ambient							
D SO-8		125				°C/W	typ	C

NOTES: (1) Junction temperature = ambient temperature for low temperature limit and +25°C Test Level A specifications. Junction temperature = ambient temperature +23°C at high temperature limit Test Level A specifications.

(2) Junction temperature = ambient at low temperature limit; junction temperature = ambient +1°C at high temperature limit for over-temperature tested specifications.

(3) Test Levels: (A) 100% tested at +25°C. Over temperature limits by characterization and simulation. (B) Limits set by characterization and simulation. (C) Typical value for information only.

(4) Current is considered positive out of node.

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(6)  $I_{VH}$  ( $V_H$  bias current) is negative, and  $I_{VL}$  ( $V_L$  bias current) is positive, under these conditions. See Note 3 and Figures 2 and 12.

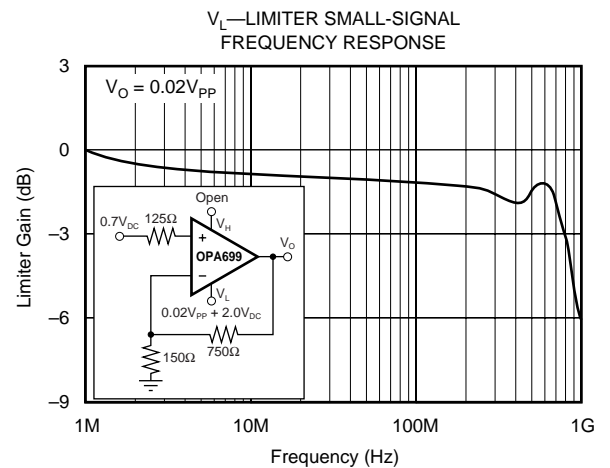
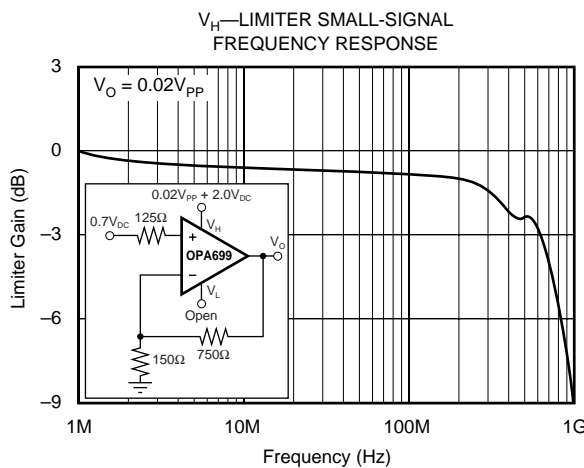
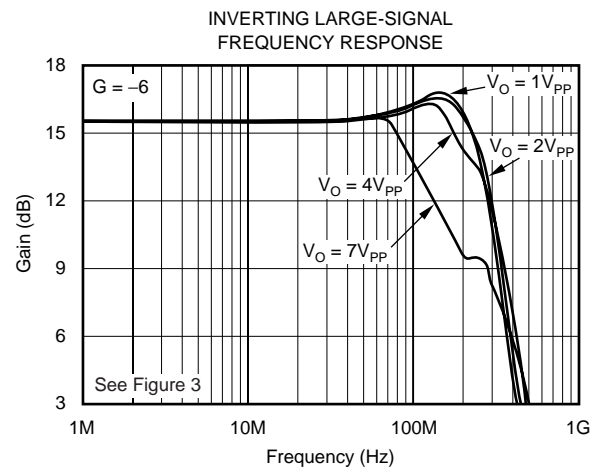
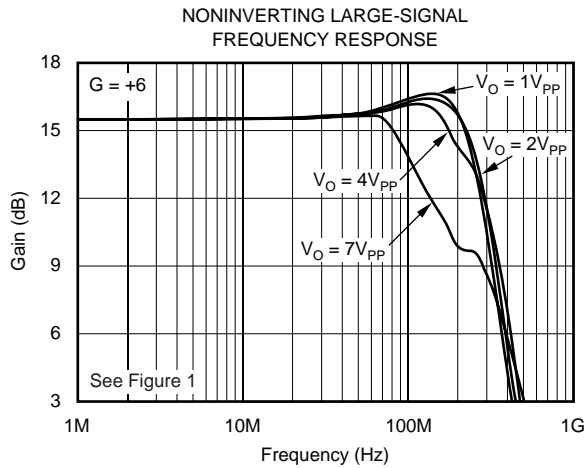
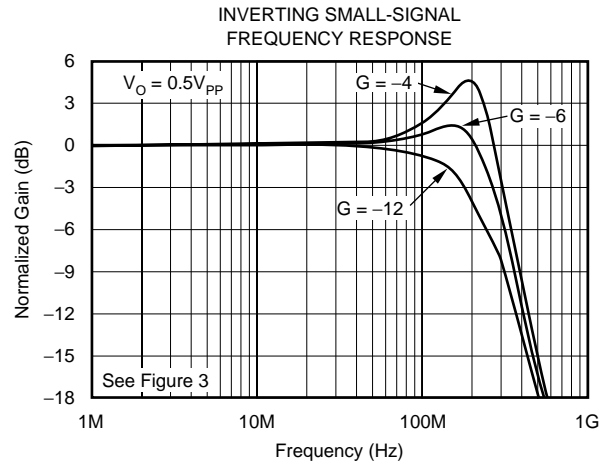
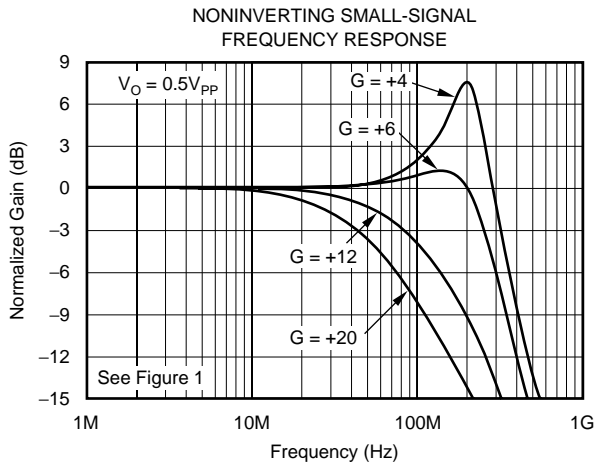
(7) Limiter feedthrough is the ratio of the output magnitude to the sinewave added to  $V_H$  (or  $V_L$ ) when  $V_{IN} = 0$ .

(8)  $V_H$  slew rate conditions are:  $V_{IN} = V_{CM} + 0.4V$ ,  $G = +6$ ,  $V_L = V_{CM} - 1.2V$ ,  $V_H =$  step between  $V_{CM} + 1.2V$  and  $V_{CM}$ .  $V_L$  slew rate conditions are similar.

(9) Linearity Guardband is defined for an output sinusoid ( $f = 5MHz$ ,  $V_O = V_{CM} \pm 1V_{PP}$ ) centered between the limiter levels ( $V_H$  and  $V_L$ ). It is the difference between the limiter level and the peak output voltage where SFDR decreases by 3dB (see Figure 8).

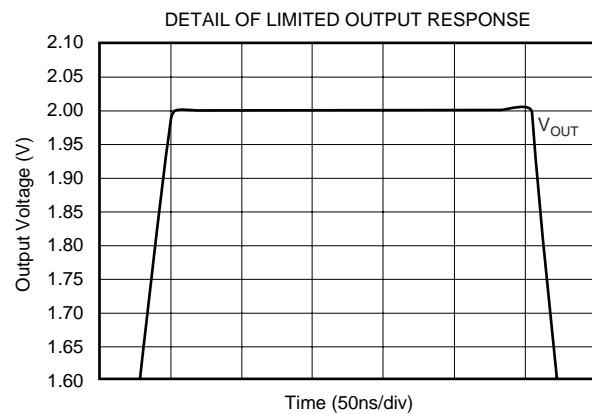
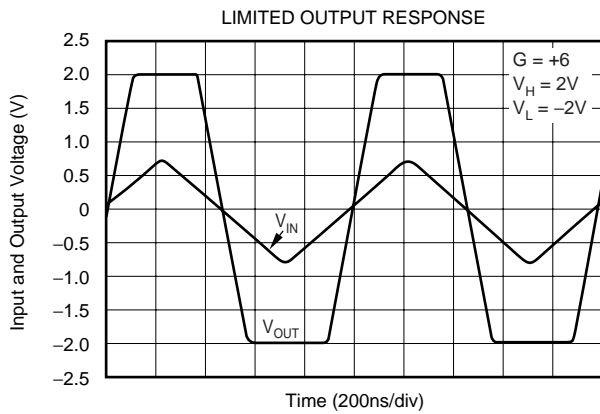
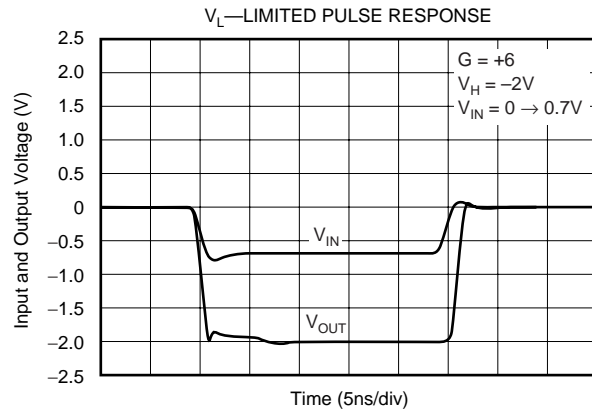
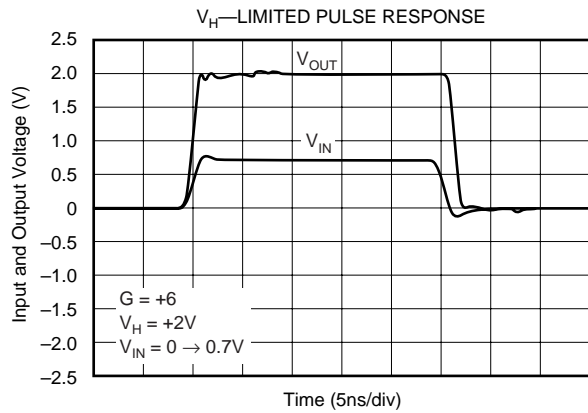
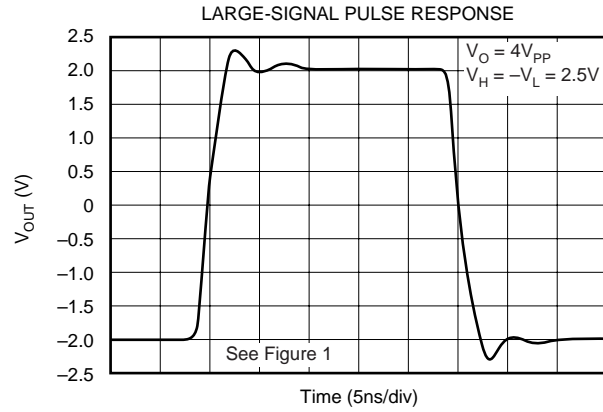
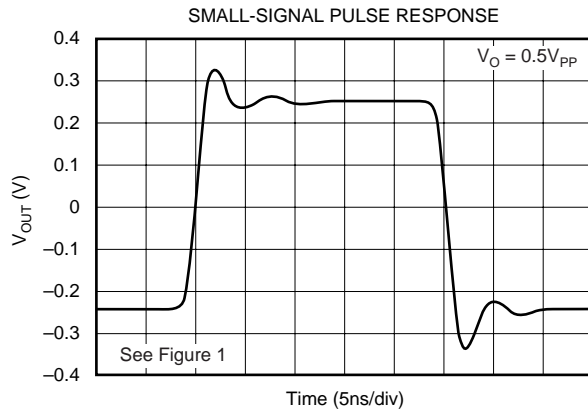
# TYPICAL CHARACTERISTICS: $V_S = \pm 5V$

$T_A = +25^\circ C$ ,  $G = +6$ ,  $R_F = 750\Omega$ , and  $R_L = 500\Omega$ ,  $V_H = -V_L = 2V$ , unless otherwise noted.



# TYPICAL CHARACTERISTICS: $V_S = \pm 5V$ (Cont.)

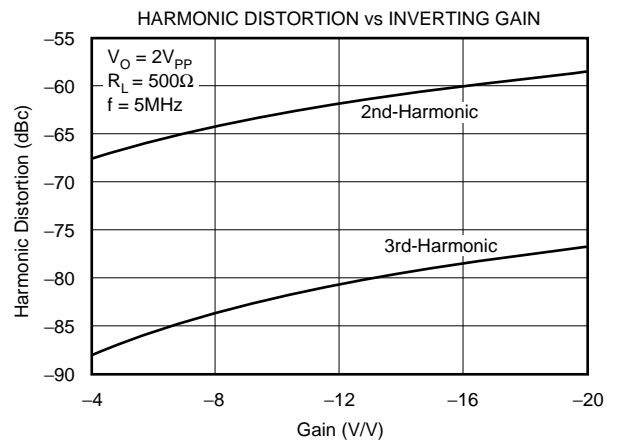
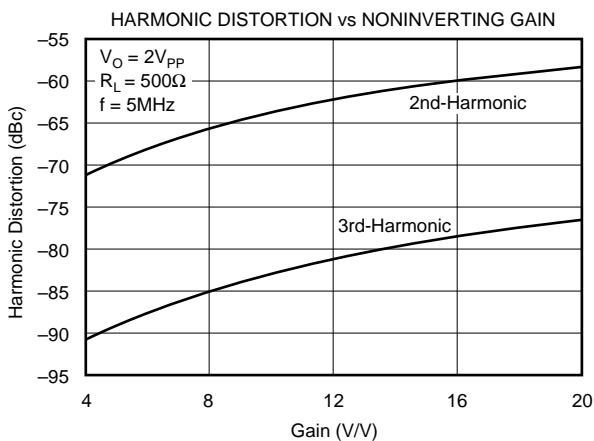
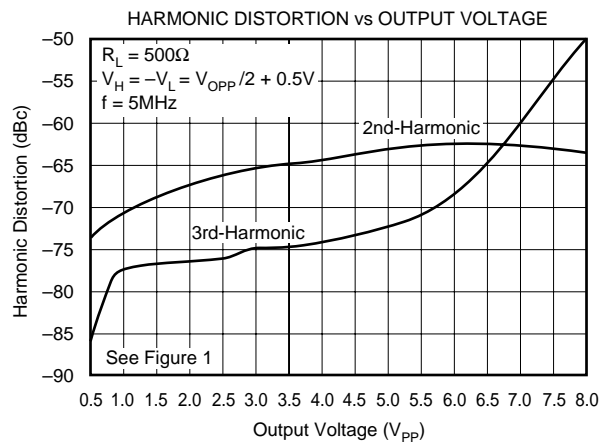
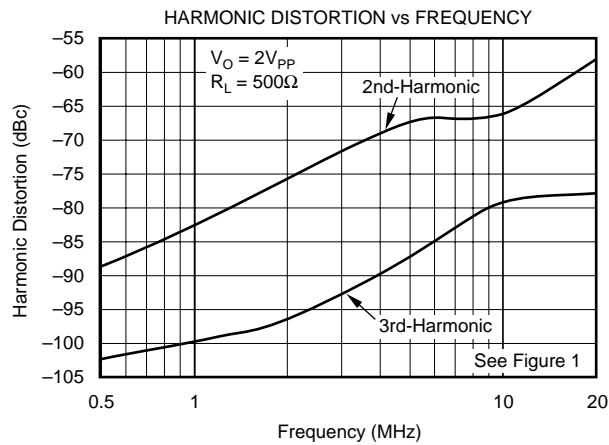
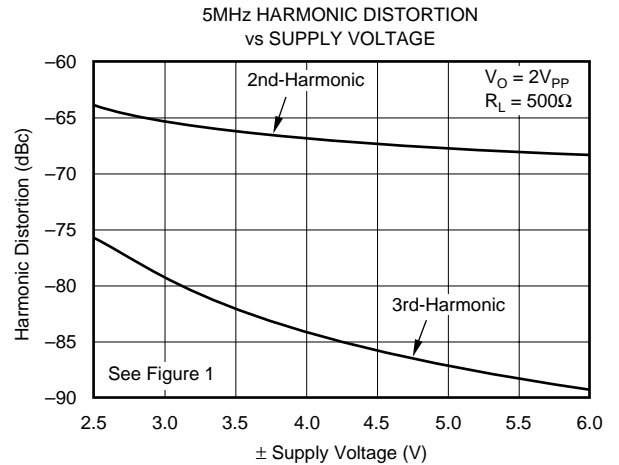
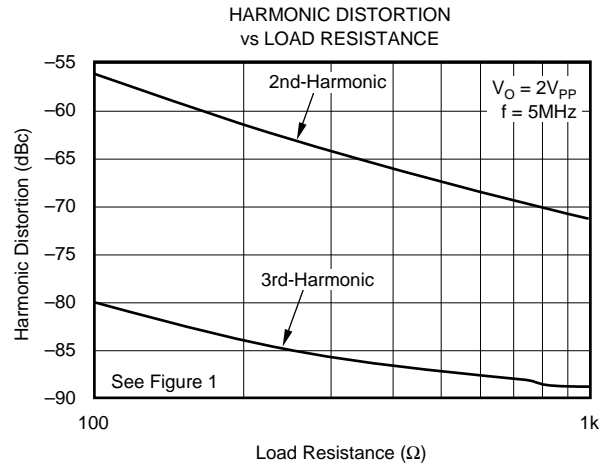
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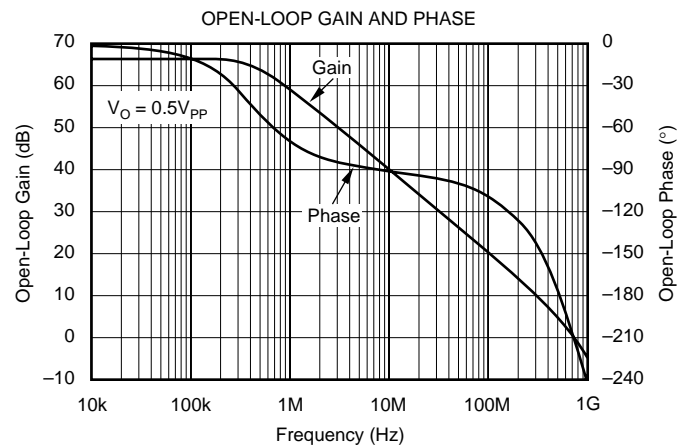
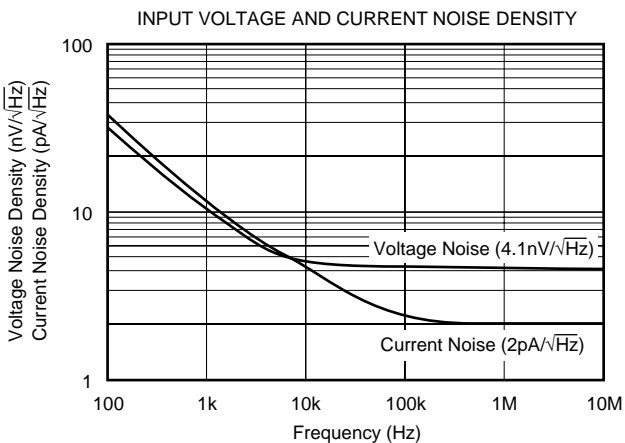
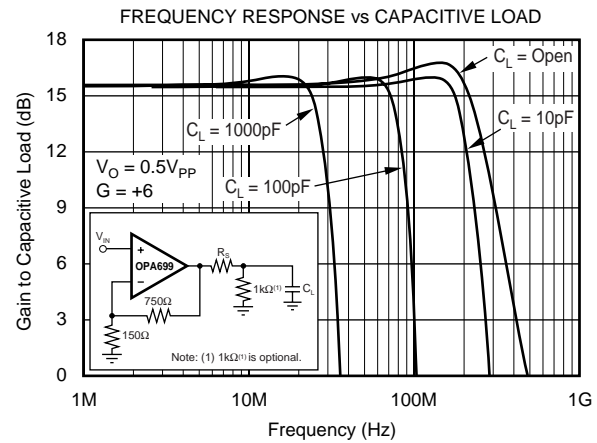
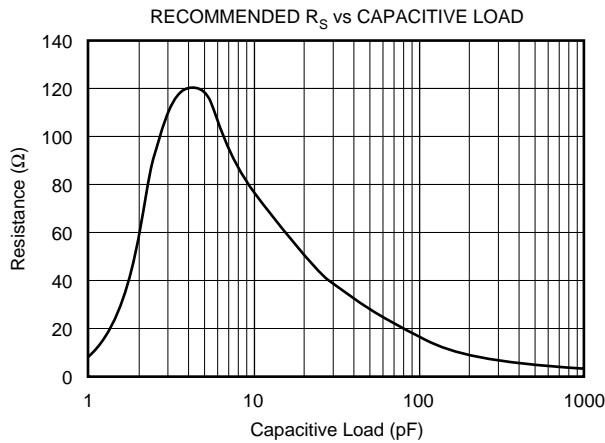
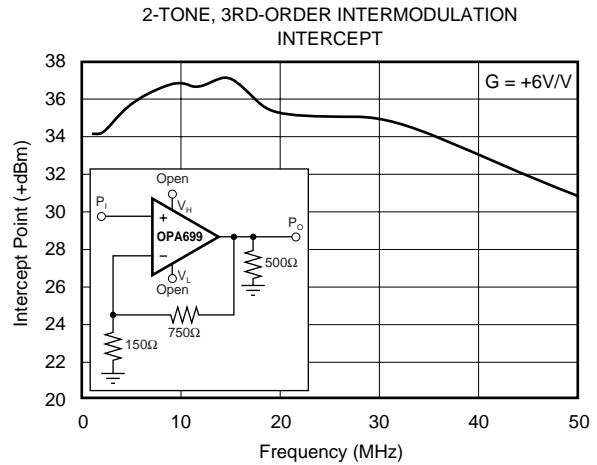
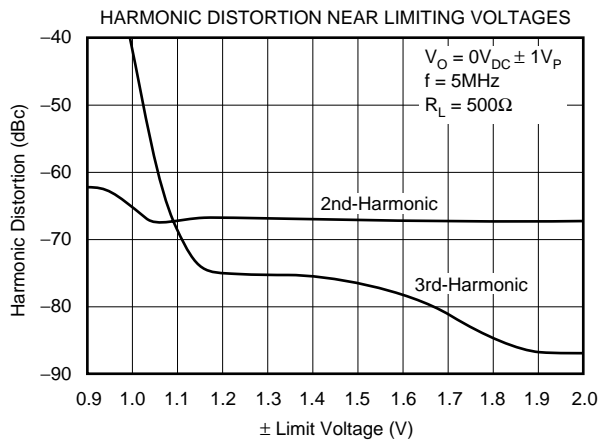
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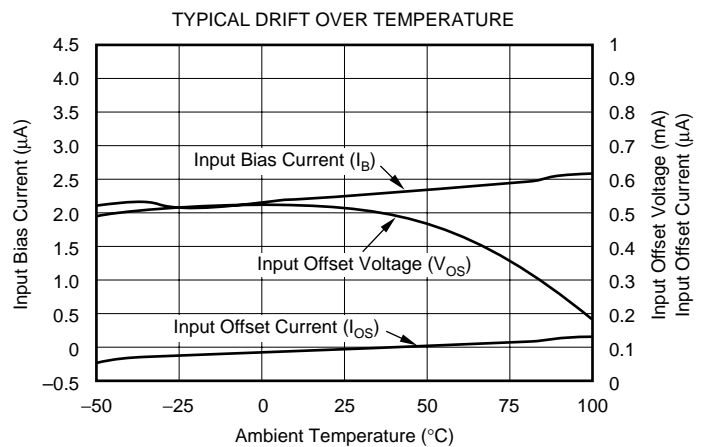
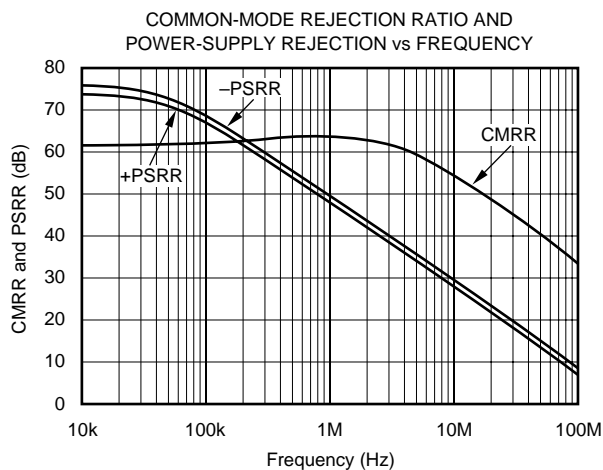
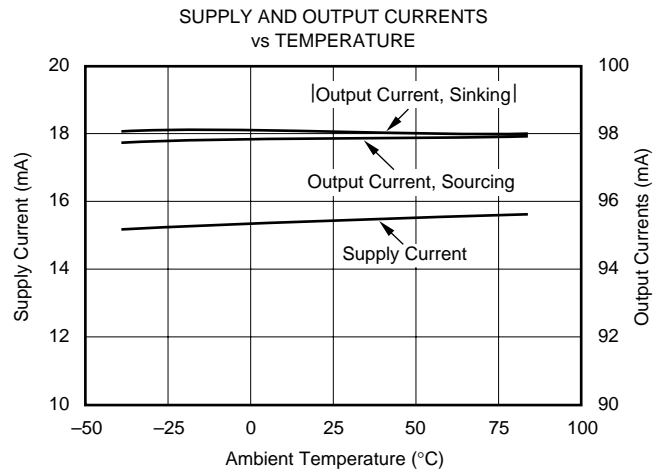
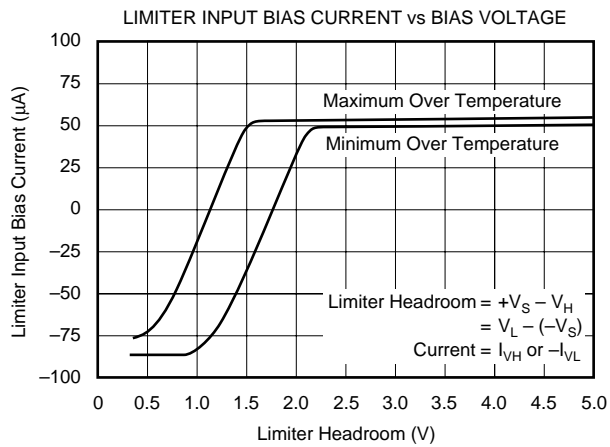
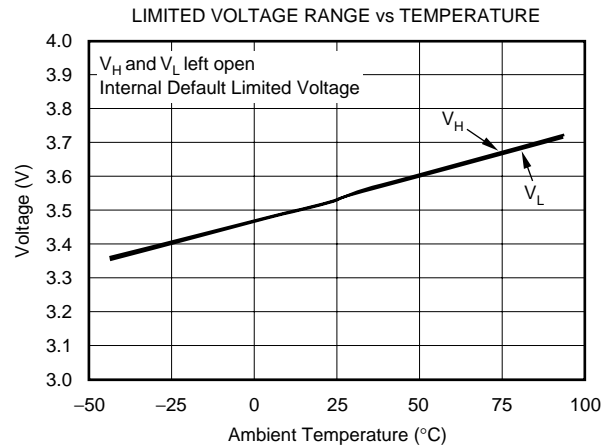
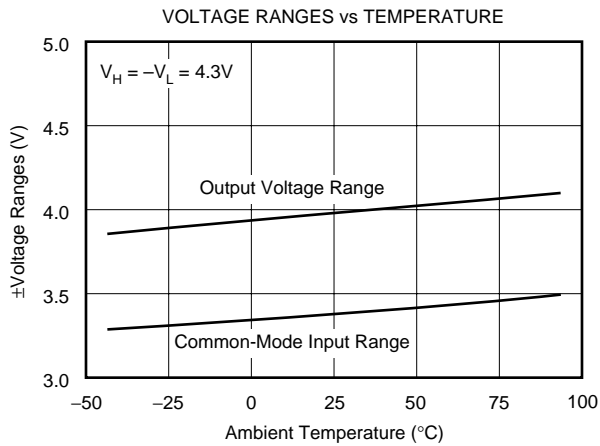
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$T_A = +25^\circ\text{C}$ ,  $G = +6$ ,  $R_F = 750\Omega$ , and  $R_L = 500\Omega$ ,  $V_H = -V_L = 2V$ , unless otherwise noted.



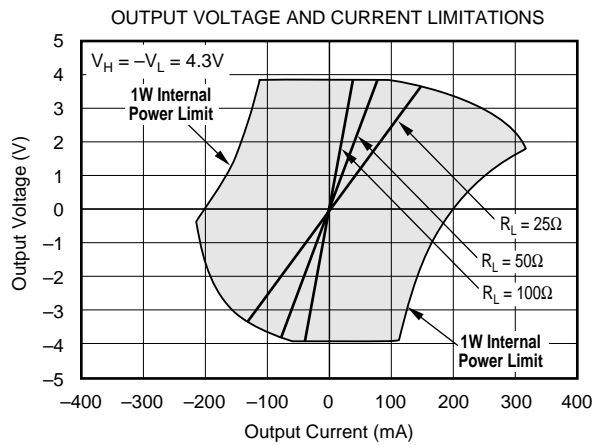
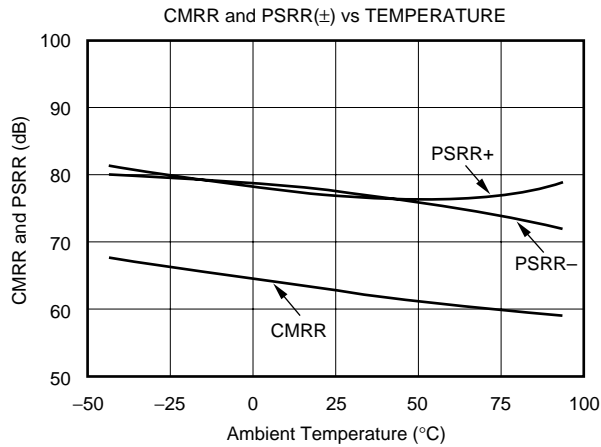
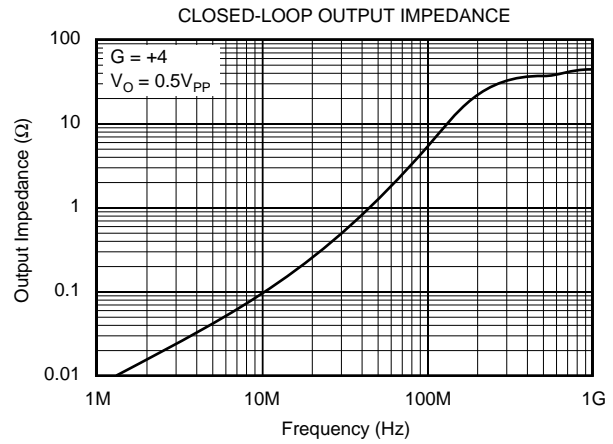
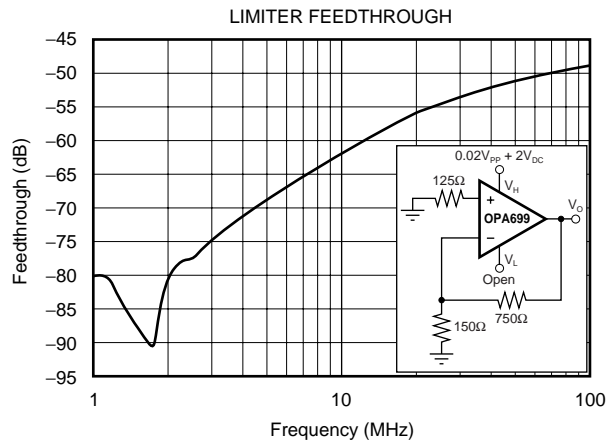
# TYPICAL CHARACTERISTICS: $V_S = \pm 5V$ (Cont.)

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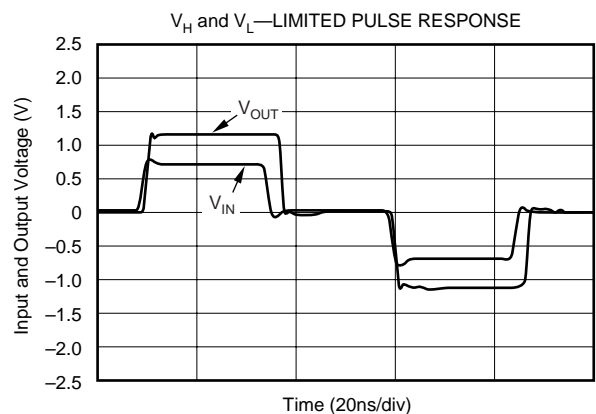
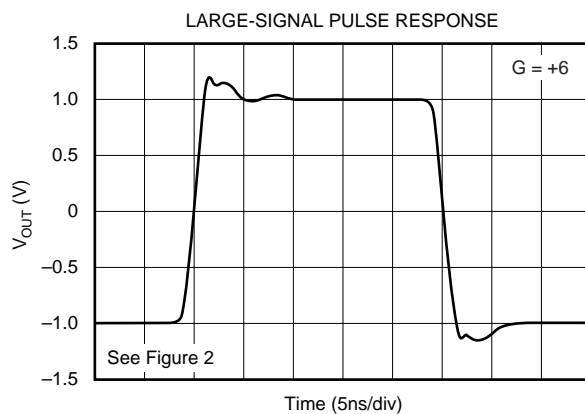
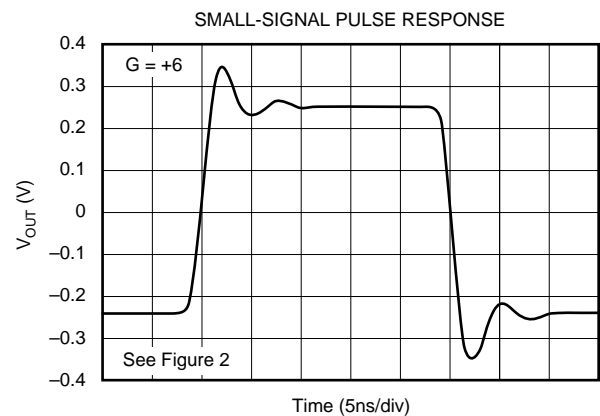
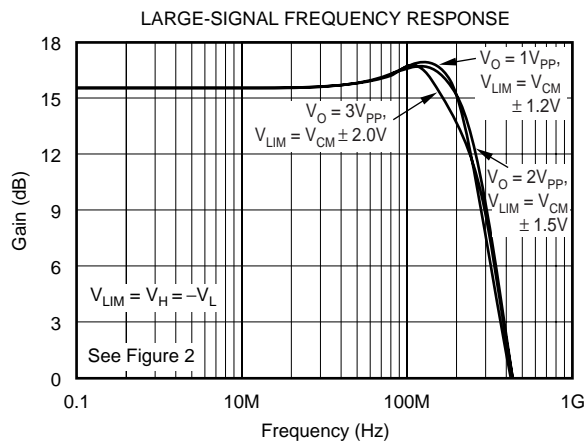
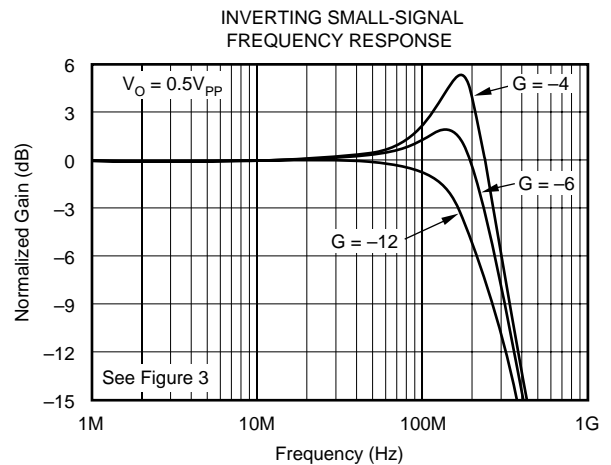
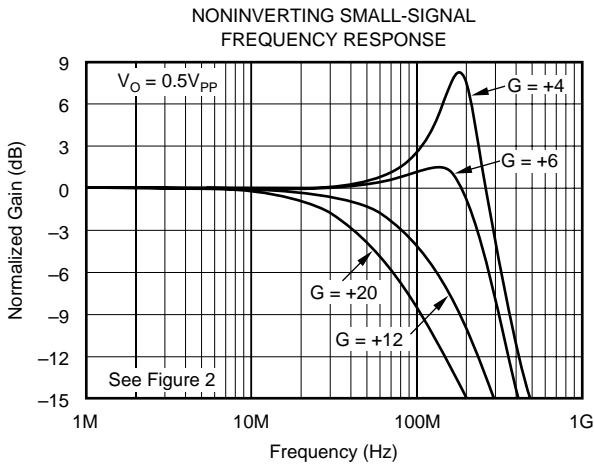
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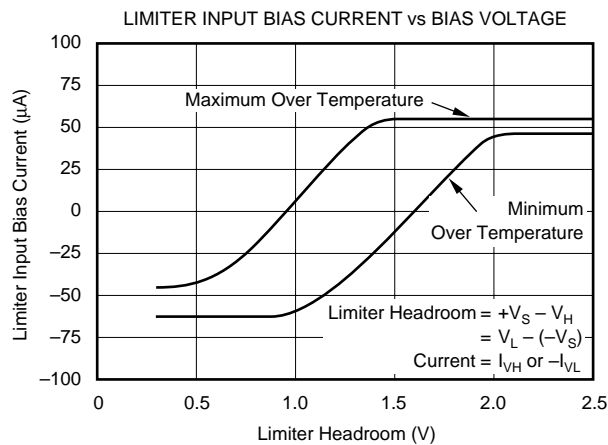
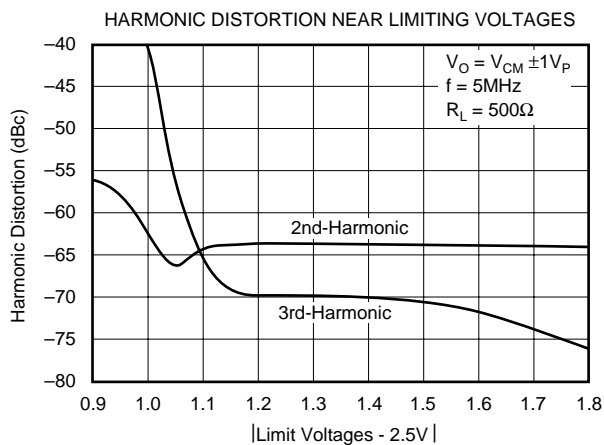
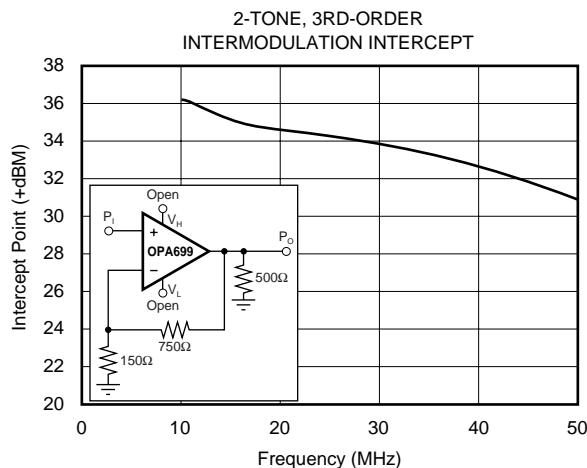
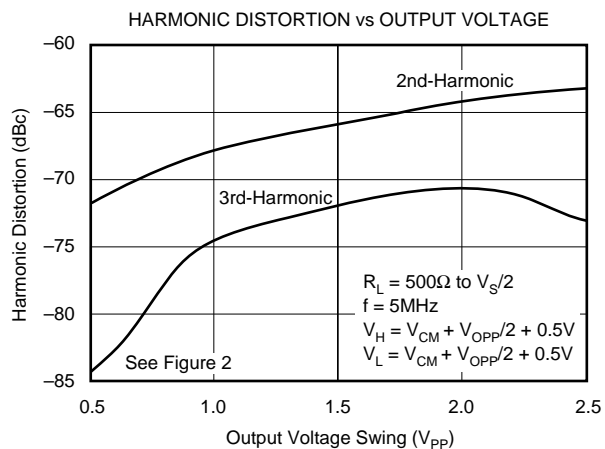
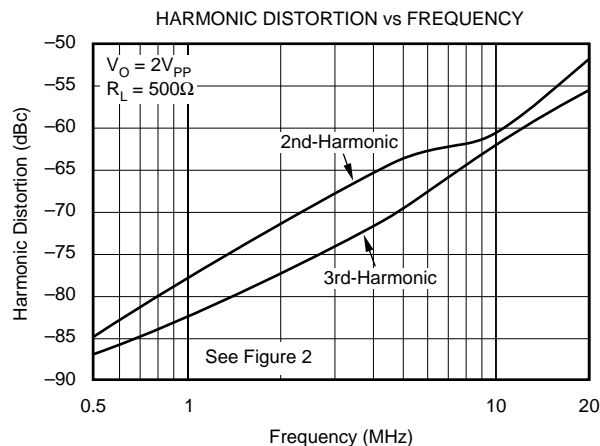
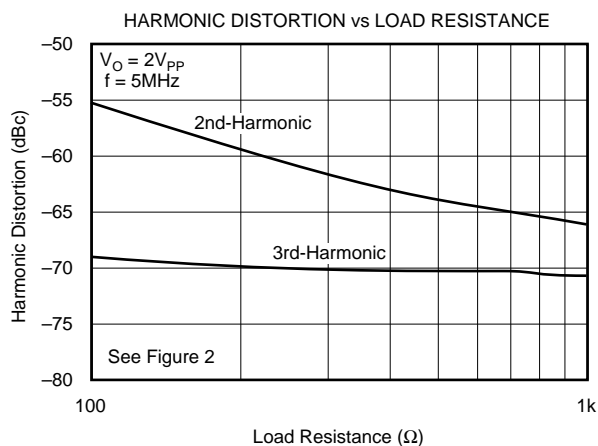
# TYPICAL CHARACTERISTICS: $V_S = +5V$

$T_A = +25^\circ\text{C}$ ,  $G = +6$ ,  $R_F = 750\Omega$ , and  $R_L = 500\Omega$  to  $V_{CM} = +2.5V$ ,  $V_L = V_{CM} - 1.2V$ ,  $V_H = V_{CM} + 1.2V$ , unless otherwise noted.



# TYPICAL CHARACTERISTICS: $V_S = +5V$ (Cont.)

$T_A = +25^\circ\text{C}$ ,  $G = +6$ ,  $R_F = 750\Omega$ , and  $R_L = 500\Omega$  to  $V_{CM} = +2.5V$ ,  $V_L = V_{CM} - 1.2V$ ,  $V_H = V_{CM} + 1.2V$ , unless otherwise noted.



# TYPICAL APPLICATIONS

## WIDEBAND VOLTAGE LIMITING OPERATION

The OPA699 is a gain voltage of  $+4\text{V/V}$ , voltage-feedback amplifier that combines features of a wideband, high slew rate amplifier with output voltage limiters. Its output can swing up to  $1\text{V}$  from each rail and can deliver up to  $120\text{mA}$ . These capabilities make it an ideal interface to drive an ADC while adding overdrive protection for the ADC inputs.

Figure 1 shows the DC-coupled, gain of  $+6\text{V/V}$ , dual power-supply circuit configuration used as the basis of the  $\pm 5\text{V}$  Electrical Characteristics and Typical Characteristics. For test purposes, the input impedance is set to  $50\Omega$  with a resistor to ground and the output is set to  $500\Omega$ . Voltage swings reported in the specifications are taken directly at the input and output pins. For the circuit of Figure 1, the total output load will be  $500\Omega \parallel 900\Omega = 321\Omega$ . The voltage limiting pins are set to  $\pm 2\text{V}$  through a voltage divider network between the  $+V_S$  and ground for  $V_H$ , and between  $-V_S$  and ground for  $V_L$ . These limiter voltages are adequately bypassed with a  $0.1\mu\text{F}$  ceramic capacitor to ground. The limiter voltages ( $V_H$  and  $V_L$ ) and the respective bias currents ( $I_{VH}$  and  $I_{VL}$ ) have the polarities shown. One additional component is included in Figure 1. An additional resistor ( $100\Omega$ ) is included in series with the noninverting input. Combined with the  $25\Omega$  DC source resistance looking back towards the signal generator, this gives an input bias current-canceling resistance that matches the  $125\Omega$  source resistance seen at the inverting input (see the DC accuracy and offset control section). The power-supply bypass for each

supply consists of two capacitors: one electrolytic  $2.2\mu\text{F}$  and one ceramic  $0.1\mu\text{F}$ . The power-supply bypass capacitors are shown explicitly in Figures 1 and 2, but will be assumed in the other figures. An additional  $0.01\mu\text{F}$  power-supply decoupling capacitor (not shown here) can be included between the two power-supply pins. In practical PC board layouts, this optional, added capacitor will typically improve the 2nd harmonic distortion performance by  $3\text{dB}$  to  $6\text{dB}$ .

## SINGLE-SUPPLY, NONINVERTING AMPLIFIER

Figure 2 shows an AC-coupled, noninverting gain amplifier for single  $+5\text{V}$  supply operation. This circuit was used for AC characterization of the OPA699, with a  $50\Omega$  source (which it matches) and a  $500\Omega$  load. The mid-point reference on the noninverting input is set by two  $1.5\text{k}\Omega$  resistors. This gives an input bias current-canceling resistance that matches the  $750\Omega$  DC source resistance seen at the inverting input (see the DC accuracy and offset control section). The power-supply bypass for the supply consists of two capacitors: one electrolytic  $2.2\mu\text{F}$  and one ceramic  $0.1\mu\text{F}$ . The power-supply bypass capacitors are shown explicitly in Figures 1 and 2, but will be assumed in the other figures. The limiter voltages ( $V_H$  and  $V_L$ ) and the respective bias currents ( $I_{VH}$  and  $I_{VL}$ ) have the polarities shown. These limiter voltages are adequately bypassed with a  $0.1\mu\text{F}$  ceramic capacitor to ground. Notice that the single-supply circuit can use three resistors to set  $V_H$  and  $V_L$ , where the dual-supply circuit usually uses four to reference the limit voltages to ground. While this circuit shows  $+5\text{V}$  operation, the same circuit may be used for single supplies up to  $+12\text{V}$ .

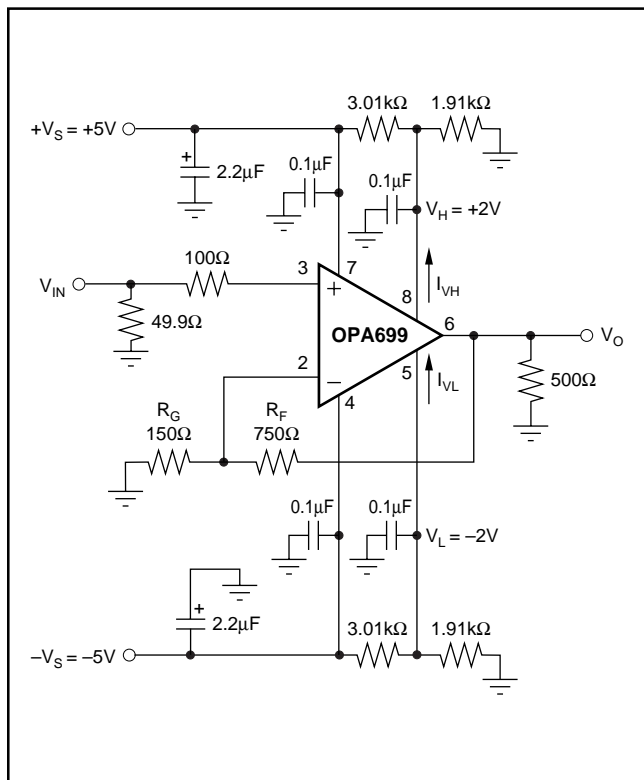


FIGURE 1. DC-Coupled, Dual-Supply Amplifier.

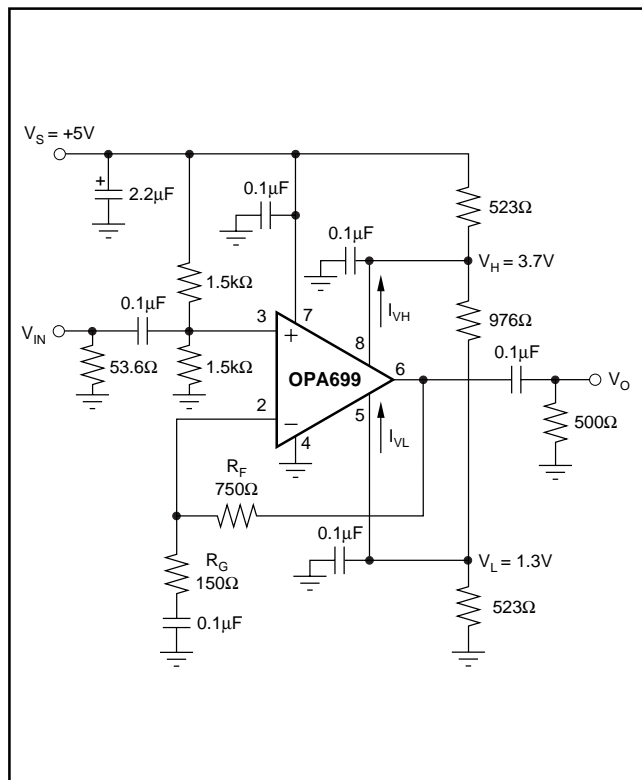


FIGURE 2. AC-Coupled, Single-Supply Amplifier.

## WIDEBAND INVERTING OPERATION

Operating the OPA699 as an inverting amplifier has several benefits and is particularly useful when a matched 50Ω source and input impedance are required. Figure 3 shows the inverting gain of  $-4\text{V/V}$  circuit used as the basis of the inverting mode typical characteristics.

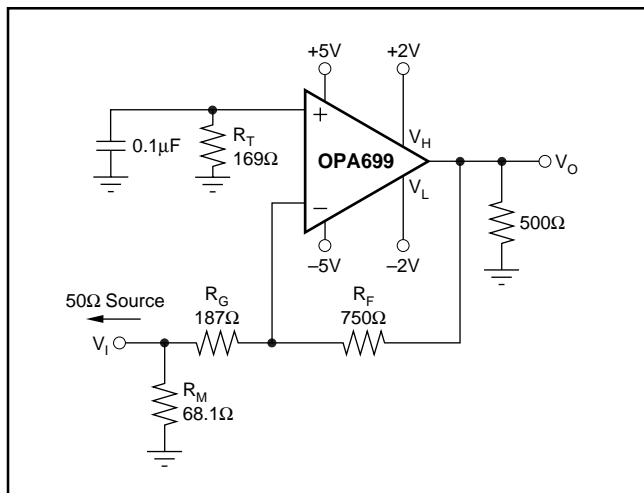


FIGURE 3. Inverting  $G = -4$  Specifications and Test Circuit.

In the inverting case, only the feedback resistor appears as part of the total output load in parallel with the actual load. For a 500Ω load used in the typical characteristics, this gives a total load of 329Ω in this inverting configuration. The gain resistor is set to get the desired gain (in this case, 187Ω for a gain of  $-4$ ) while an additional input resistor ( $R_M$ ) can be used to set the total input impedance equal to the source, if desired. In this case,  $R_M = 68.1\Omega$  in parallel with the 187Ω gain setting resistor gives a matched input impedance of 50Ω. This matching is only needed when the input needs to be matched to a source impedance, as in the characterization testing done using the circuit of Figure 3.

For bias current-cancellation matching, the noninverting input requires a 169Ω resistor to ground. The calculation for this resistor includes a DC-coupled 50Ω source impedance along with  $R_G$  and  $R_M$ . Although this resistor will provide cancellation for the bias current, it must be well-decoupled (0.1μF in Figure 3) to filter the noise contribution of the resistor and the input current noise.

As the required  $R_G$  resistor approaches 50Ω at higher gains, the bandwidth for the circuit in Figure 3 will far exceed the bandwidth at that same gain magnitude for the noninverting circuit of Figure 1. This occurs due to the lower noise gain for the circuit of Figure 3 when the 50Ω source impedance is included in the analysis. For instance, at a signal gain of  $-15$  ( $R_G = 50\Omega$ ,  $R_M = \text{open}$ ,  $R_F = 750\Omega$ ) the noise gain for the circuit of Figure 3 will be  $1 + 750\Omega/(50\Omega + 50\Omega) = 8.5$  due to the addition of the 50Ω source in the noise gain equation. This approach gives considerably higher bandwidth than the noninverting gain of  $+15$ . Using the 1GHz gain bandwidth product for the OPA699, an inverting gain of  $-15$  from a 50Ω source to a 50Ω  $R_G$  will give 140MHz bandwidth, whereas the noninverting gain of  $+8$  will give 55MHz, as shown in the measured results of Figure 4.

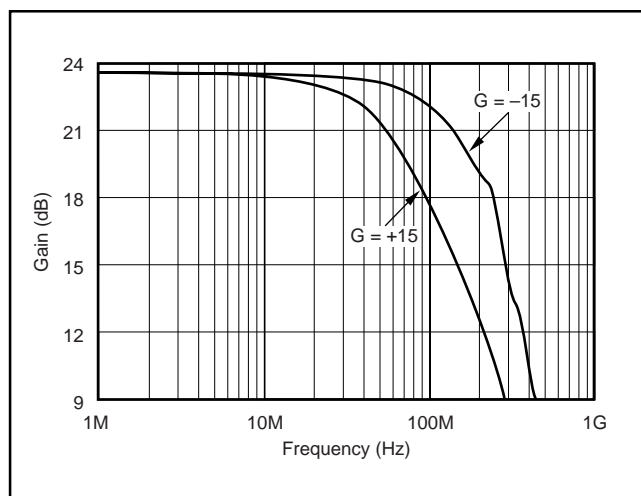


FIGURE 4.  $G = +15$  and  $-15$  Frequency Response.

## LOW-GAIN COMPENSATION FOR IMPROVED SFDR

Where a low gain is desired, and inverting operation is acceptable, a new external compensation technique can be used to retain the full slew rate and noise benefits of the OPA699, while giving increased loop gain and the associated distortion improvements offered by a non-unity-gain stable op amp. This technique shapes the loop gain for good stability, while giving an easily controlled 2nd-order low-pass frequency response. To set the compensation capacitors ( $C_S$  and  $C_F$ ), consider the half-circuit of Figure 5, where the 50Ω source is used.

Considering only the noise gain for the circuit of Figure 5, the low-frequency noise gain ( $N_{G1}$ ) is set by the resistor ratio, while the high-frequency noise gain ( $N_{G2}$ ) is set by the capacitor ratio. The capacitor values set both the transition frequencies and the high-frequency noise gain. If the high-frequency noise gain, determined by  $N_{G2} = 1 + C_S/C_F$ , is set to a value greater than the recommended minimum stable gain for the op amp, and the noise gain pole (set by  $1/R_FC_F$ ) is placed correctly, a very well controlled 2nd-order low-pass frequency response results.

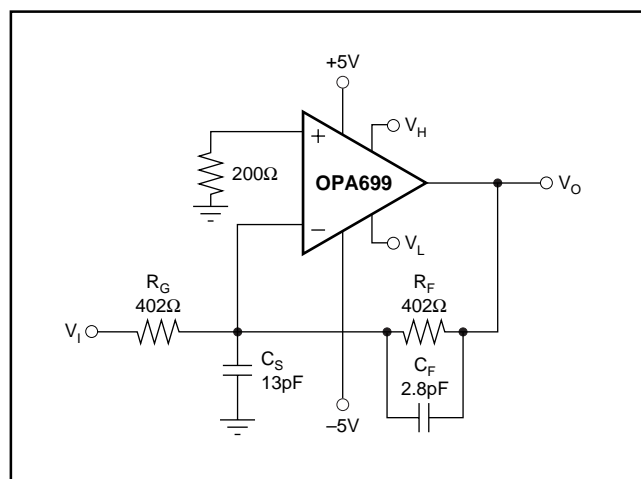


FIGURE 5. Broadband, Low-Inverting Gain External Compensation.



To choose the values for both  $C_S$  and  $C_F$ , two parameters and only three equations need to be solved. The first parameter is the target high-frequency noise gain ( $NG_2$ ), which should be greater than the minimum stable gain for the OPA699. Here, a target of  $NG_2 = 26$  is used. The second parameter is the desired low-frequency signal gain, which also sets the low-frequency noise gain ( $NG_1$ ). To simplify this discussion, we will target a maximally flat 2nd-order low-pass Butterworth frequency response ( $Q = 0.707$ ). The signal gain shown in Figure 5 sets the low-frequency noise gain to  $NG_1 = 1 + R_F/R_G (= 2$  in this example). Then, using only these two gains and the gain bandwidth product for the OPA699 (1000MHz), the key frequency in the compensation is set by Equation 1.

$$Z_O = \frac{GBP}{NG_1^2} \left[ \left( 1 - \frac{NG_1}{NG_2} \right) - \sqrt{1 - 2 \frac{NG_1}{NG_2}} \right] \quad (1)$$

Physically, this  $Z_O$  (22.3MHz for the values shown above) is set by  $1/(2\pi R_F(C_F + C_S))$  and is the frequency at which the rising portion of the noise gain would intersect the unity gain if projected back to a 0dB gain. The actual zero in the noise gain occurs at  $NG_1 \cdot Z_O$  and the pole in the noise gain occurs at  $NG_2 \cdot Z_O$ . That pole is physically set by  $1/(R_F C_F)$ . Since GBP is expressed in Hz, multiply  $Z_O$  by  $2\pi$  and use to get  $C_F$  by solving Equation 2.

$$C_F = \frac{1}{2\pi R_F Z_O NG_2} (= 3pF) \quad (2)$$

Finally, since  $C_S$  and  $C_F$  set the high-frequency noise gain, determine  $C_S$  using Equation 3 (solving for  $C_S$  by using  $NG_2 = 6$ ):

$$C_S = (NG_2 - 1)C_F \quad (3)$$

which gives  $C_S = 15pF$ .

Both of these calculated values have been reduced slightly in Figure 5 to account for parasitics. The resulting closed-loop bandwidth is approximately equal to Equation 4.

$$f_{-3dB} \approx \sqrt{Z_O \cdot GBP} \quad (4)$$

For the values shown in Figure 5,  $f_{-3dB}$  is approximately 149MHz. This is less than that predicted by simply dividing the Gain Bandwidth Product (GBP) product by  $NG_1$ . The compensation network controls the bandwidth to a lower value, while providing the full slew rate at the output and an improved distortion performance due to increased loop gain at frequencies below  $NG_1 \cdot Z_O$ .

### LOW DISTORTION, LIMITED OUTPUT, ADC INPUT DRIVER

Figure 6 shows a simple ADC driver that operates on a single supply, and gives excellent distortion performance. The limit voltages track the input range of the converter, completely protecting against input overdrive. Note that the limiting voltages have been set 100mV above/below the corresponding reference voltage from the converter. This circuit also implements an improved distortion for an inverting gain of  $-2$  using external compensation.

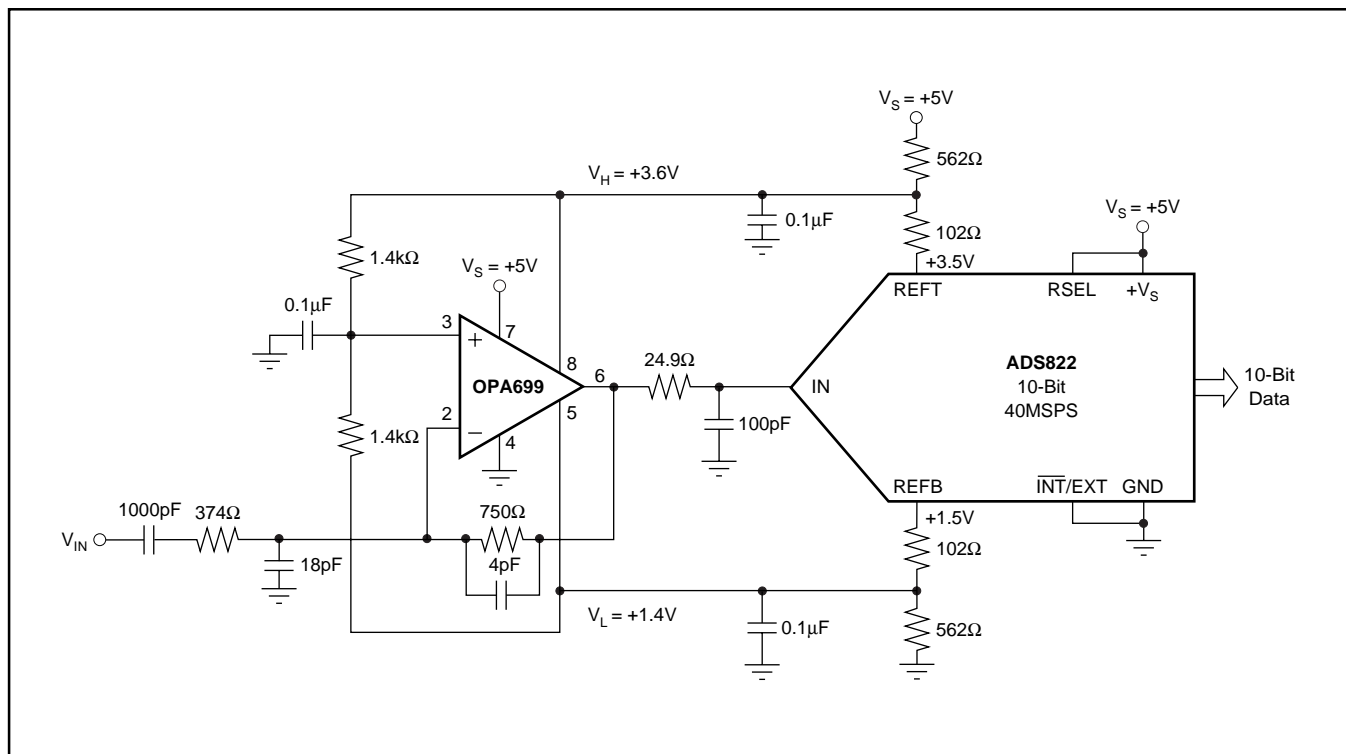


FIGURE 6. Single Supply, Limiting ADC Input Driver.

## LIMITED OUTPUT, DIFFERENTIAL ADC INPUT DRIVER

Figure 7 shows a differential ADC driver that takes advantage of the OPA699 limiters to protect the input of the ADC. Two OPA699s are used. The first one is an inverting configuration at a gain of  $-2$ . The second one is in a noninverting configuration at a gain of  $+2$ . Refer to the section, *Low Gain Compensation for Improved SFDR*, for a discussion of stability issues of the OPA699 operating at a gain less than 4. Each amplifier is swinging  $2V_{PP}$  providing a  $4V_{PP}$  differential signal to drive the input of the ADC. Limiters have been set  $100mV$  away from the magnitude of each amplifier maximum signal to provide input protection for the ADC while maintaining an acceptable distortion level.

## PRECISION HALF WAVE RECTIFIER

Figure 8 shows a half wave rectifier with outstanding precision and speed.  $V_H$  (pin 8) will default to a 3.5 typically if left open, while the negative limit is set to ground.

The gain for the circuit in Figure 8 is set at  $+6$ . Figure 9 shows input and output for  $\pm 0.5V$  100MHz input.

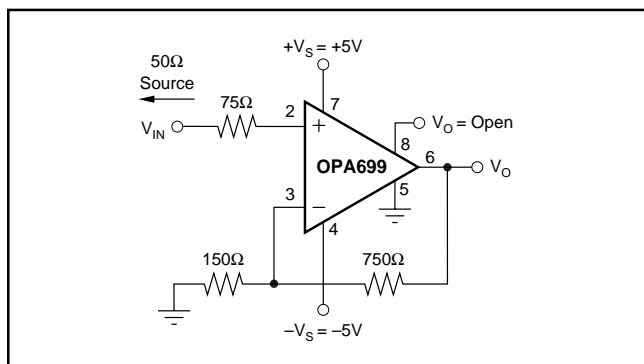


FIGURE 8. Precision Half-Wave Rectifier.

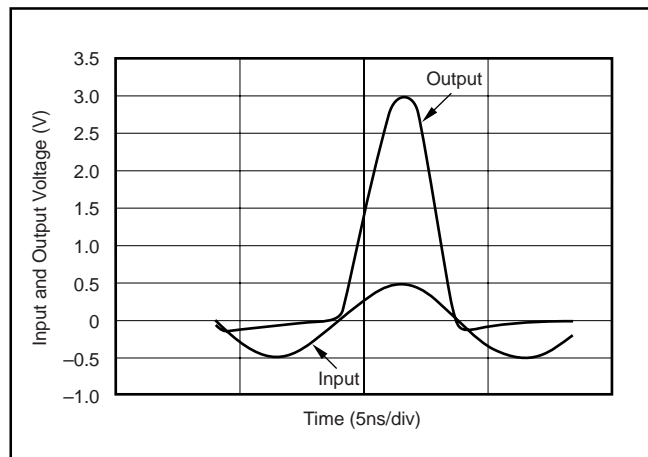


FIGURE 9. 100MHz Sinewave Rectified.

## VERY HIGH-SPEED SCHMITT TRIGGER

Figure 10 shows a very high-speed Schmitt Trigger. The output levels are precisely defined, and the switching time is exceptional. The output voltage swings between  $V_H$  and  $V_L$ .

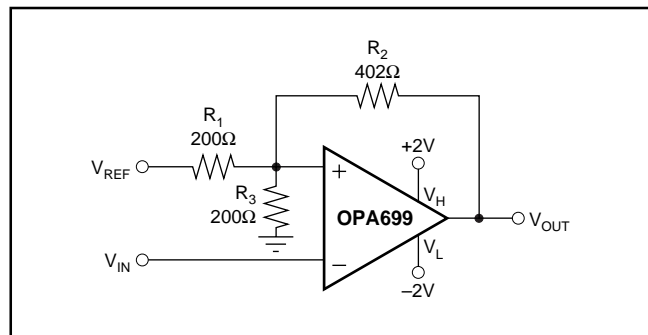


FIGURE 10. Very High-Speed Schmitt Trigger.

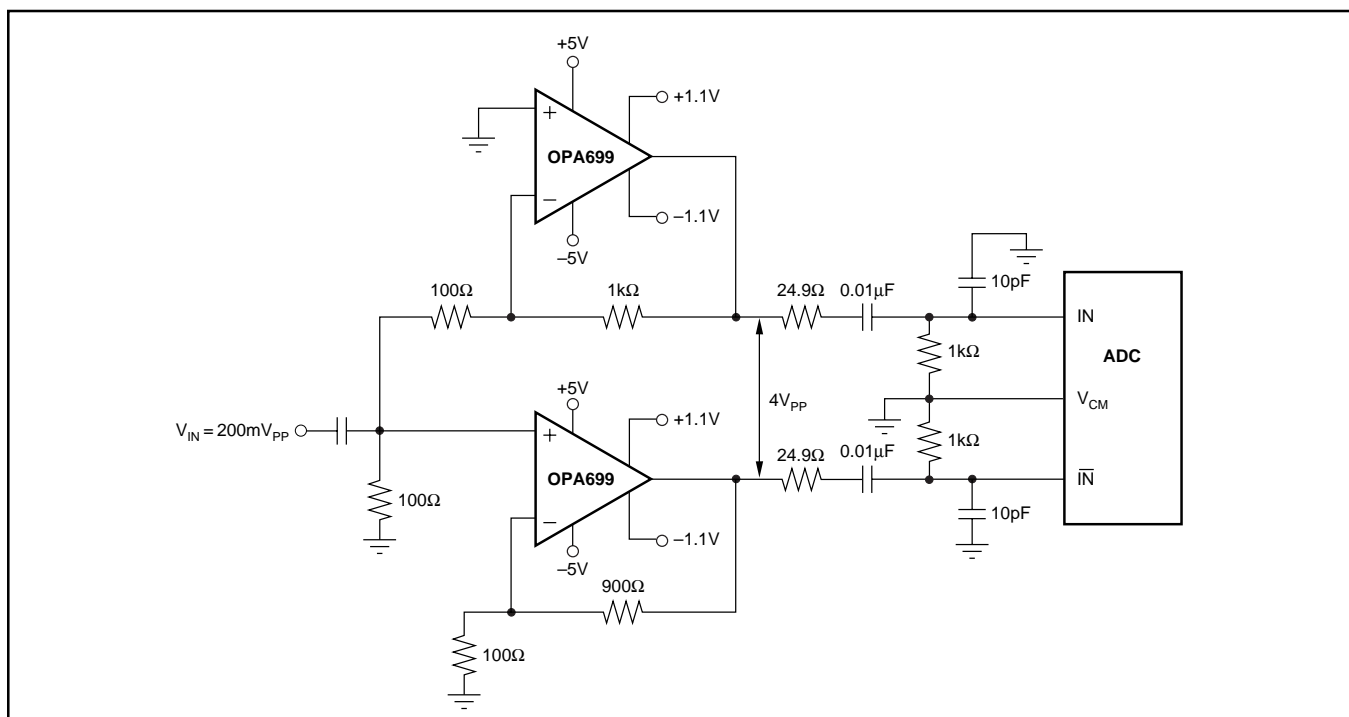


FIGURE 7. Single to Differential AC-Coupled, High Gain Output Limited ADC Driver.

The circuit operates as follows. When the input voltage is less than  $V_{HL}$  then the output is limiting at  $V_H$ . When the input is greater than  $V_{HH}$ , then the output is limiting at  $V_L$ , with  $V_{HL}$  and  $V_{HH}$  defined as the following:

$$V_{HL, HH} = \left( \frac{R_1 \parallel R_2 \parallel R_3}{R_1} \times V_{REF} \right) + \left( \frac{R_1 \parallel R_2 \parallel R_3}{R_2} \times V_{OUT} \right)$$

Due to the inverting function realized by the Schmitt Trigger,  $V_{HL}$  corresponds to  $V_{OUT} = V_H$ , and  $V_{HH}$  corresponds to  $V_{OUT} = V_L$ .

Figure 11 shows the Schmitt Trigger operating with  $V_{REF} = +5V$ . This gives us  $V_{HH} = 2.4V$  and  $V_{HL} = 1.6V$ . The propagation delay for the OPA699 in a Schmitt Trigger configuration is 4ns from high-to-low, and 4ns from low-to-high.

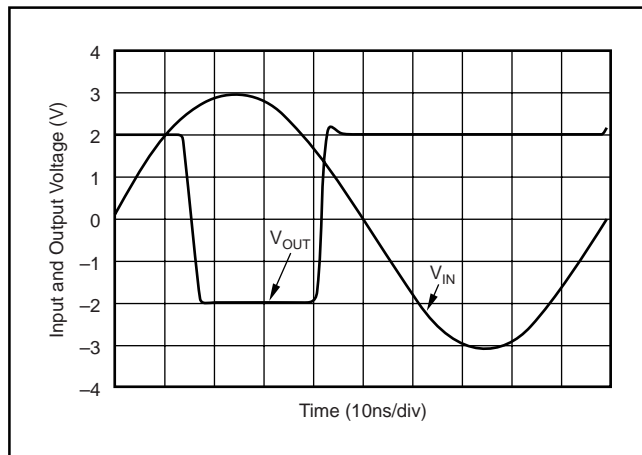


FIGURE 11. Schmitt Trigger Time Domain Response for a 10MHz Sinewave.

## DESIGN-IN TOOLS

### DEMONSTRATION FIXTURE

A printed circuit board (PCB) is available to assist in the initial evaluation of circuit performance using the OPA699. The fixture is offered free of charge as an unpopulated PCB, delivered with user's guide. The summary information for this fixture is shown in Table I.

PRODUCT	PACKAGE	ORDERING NUMBER	LITERATURE NUMBER
OPA699ID	SO-8	DEM-OPA-SO-1A	SBOU009

TABLE I. Demonstration Fixture.

The demonstration fixture can be requested at the Texas Instruments web site ([www.ti.com](http://www.ti.com)) through the OPA699 product folder.

## OPERATING SUGGESTIONS

### THEORY OF OPERATION

The OPA699 is a voltage-feedback, gain of +4V/V stable op amp. The output voltage is limited to a range set by the voltage on the limiter pins (5 and 8). When the input tries to overdrive the output, the limiters take control of the output buffer. This action from the limiters avoids saturating any part of the signal path, giving quick overdrive recovery and excellent limiter accuracy at any signal gain. The limiters have a very sharp transition from the linear region of operation to output limiting. This transition allows the limiter voltages to be set very near (< 100mV) the desired signal range. The distortion performance is also very good near the limiter voltages.

### OUTPUT LIMITERS

The output voltage is linearly dependent on the input(s) when it is between the limiter voltages  $V_H$  (pin 8) and  $V_L$  (pin 5). When the output tries to exceed  $V_H$  or  $V_L$ , the corresponding limiter buffer takes control of the output voltage and holds it at  $V_H$  or  $V_L$ . Because the limiters act on the output, their accuracy does not change with the gain. The transition from the linear region of operation to output limiting is very sharp—the desired output signal can safely come to within 30mV of  $V_H$  or  $V_L$  with no onset of non-linearity. The limiter voltages can be set to within 0.7V of the supplies ( $V_L \geq -V_S + 0.7V$ ,  $V_H \leq +V_S - 0.7V$ ). They must also be at least 400mV apart ( $V_H - V_L \geq 0.4V$ ). When pins 5 and 8 are left open,  $V_H$  and  $V_L$  go to the default voltage limit; the minimum values are given in the electrical specifications. Looking at Figure 12 for the zero bias current case shows the expected range of ( $V_S$  – default limit voltages) = headroom.

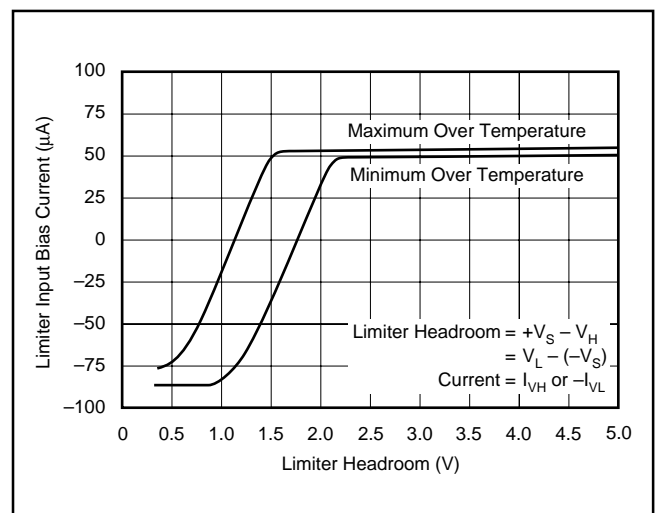


FIGURE 12. Limiter Bias Current vs Bias Voltage.

When the limiter voltages are more than 2.1V from the supplies ( $V_L \geq -V_S + 2.1V$  or  $V_H \leq +V_S - 2.1V$ ), you can use simple resistor dividers to set  $V_H$  and  $V_L$  (see Figure 1). Make sure to include the limiter input bias currents (Figure 8) in the calculations (that is,  $I_{VL} = 50\mu A$  into pin 5, and  $I_{VH} = +50\mu A$  out of pin 8). For good limiter voltage accuracy, run a minimum 1mA quiescent bias current through these resistors. When the limiter voltages need to be within 2.1V of the supplies ( $V_L \leq -V_S + 2.1V$  or  $V_H \geq +V_S - 2.1V$ ), consider using low impedance buffers to set  $V_H$  and  $V_L$  to minimize errors due to bias current uncertainty. This condition will typically be the case for single-supply operation ( $V_S = +5V$ ). Figure 2 runs 2.5mA through the resistive divider that sets  $V_H$  and  $V_L$ . This limits errors due to  $I_{VH}$  and  $I_{VL} < \pm 1\%$  of the target limit voltages. The limiters' DC accuracy depends on attention to detail. The two dominant error sources can be improved as follows:

- Power supplies, when used to drive resistive dividers that set  $V_H$  and  $V_L$ , can contribute large errors (for example,  $\pm 5\%$ ). Using a more accurate source, and bypassing pins 5 and 8 with good capacitors, will improve limiter PSRR.
- The resistor tolerances in the resistive divider can also dominate. Use 1% resistors.

Other error sources also contribute, but should have little impact on the limiters' DC accuracy:

- Reduce offsets caused by the Limiter Input Bias Currents. Select the resistors in the resistive divider(s) as described above.
- Consider the signal path DC errors as contributing to uncertainty in the useable output swing.
- The limiter offset voltage only slightly degrades limiter accuracy. Figure 13 shows how the limiters affect distortion performance. Virtually no degradation in linearity is observed for output voltage swinging right up to the limiter voltages. In this plot a fixed  $\pm 1V$  output swing is driven while the limiter voltages are reduced symmetrically. Until the limiters are reduced to  $\pm 1.1V$ , little distortion degradation is observed.

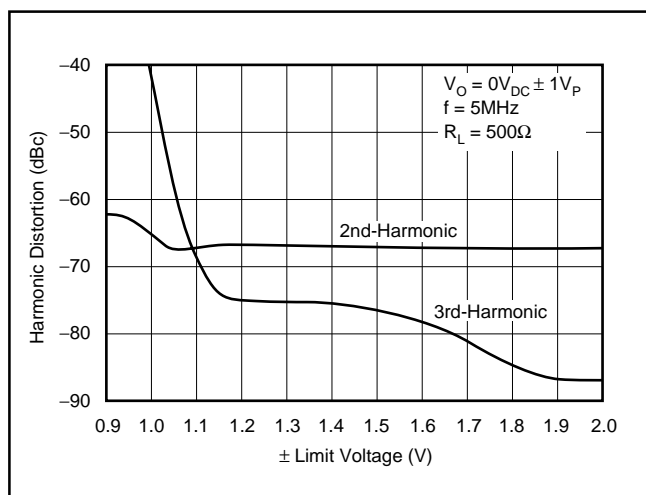


FIGURE 13. Harmonic Distortion Near Limit Voltages.

## OUTPUT DRIVE

The OPA699 has been optimized to drive 500Ω loads, such as ADCs. It still performs very well driving 100Ω loads; the specifications are shown for the 500Ω load. This makes the OPA699 an ideal choice for a wide range of high-frequency applications.

Many high-speed applications, such as driving ADCs, require op amps with low output impedance. As shown in the typical performance curve *Output Impedance vs Frequency*, the OPA699 maintains very low closed-loop output impedance over frequency. Closed-loop output impedance increases with frequency, since loop gain decreases with frequency.

## THERMAL CONSIDERATIONS

The OPA699 will not require heat sinking under most operating conditions. Maximum desired junction temperature will set a maximum allowed internal power dissipation as described below. In no case should the maximum junction temperature be allowed to exceed 150°C.

The total internal power dissipation ( $P_D$ ) is the sum of quiescent power ( $P_{DQ}$ ) and the additional power dissipated in the output stage ( $P_{DL}$ ) while delivering load power.  $P_{DQ}$  is simply the specified no-load supply current times the total supply voltage across the part.  $P_{DL}$  depends on the required output signals and loads. For a grounded resistive load, and equal bipolar supplies, it is at maximum when the output is at 1/2 either supply voltage. In this condition,  $P_{DL} = V_S^2 / (4R_L)$  where  $R_L$  includes the feedback network loading. Note that it is the power in the output stage, and not in the load, that determines internal power dissipation.

The operating junction temperature is:  $T_J = T_A + P_D \times \theta_{JA}$ , where  $T_A$  is the ambient temperature. For example, the maximum  $T_J$  for a OPA699ID with  $G = +6$ ,  $R_F = 750\Omega$ ,  $R_L = 500\Omega$ , and  $\pm V_S = \pm 5V$  at the maximum  $T_A = +85^\circ C$  is calculated as:

$$P_{DQ} = (10V \times 15.5mA) = 155mW$$

$$P_{DL} = \frac{(5V)^2}{4 \times (500\Omega \parallel 900\Omega)} = 19.4mW$$

$$P_D = 155mW + 19.4mW = 174.4mW$$

$$T_J = 85^\circ C + 174.4mW \times 125^\circ C / W = 107^\circ C$$

This would be the maximum  $T_J$  from  $V_O = \pm 2.5V_{DC}$ . Most applications will be at a lower output stage power and have a lower  $T_J$ .

## CAPACITIVE LOADS

Capacitive loads, such as the input to ADCs, will decrease the amplifier phase margin, which may cause high-frequency peaking or oscillations. Capacitive loads  $\geq 2pF$  should be isolated by connecting a small resistor in series with the output, as shown in Figure 14. Increasing the gain from +2 will improve the capacitive drive capabilities due to increased phase margin.

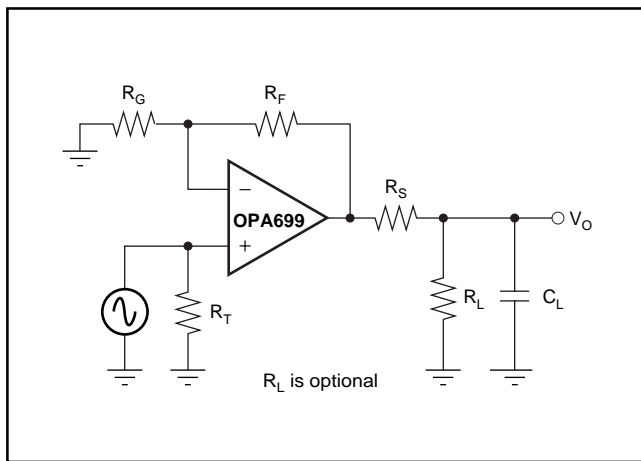


FIGURE 14. Driving Capacitive Loads.

In general, capacitive loads should be minimized for optimum high-frequency performance. The capacitance of coax cable (29pF/ft for RG-58) will not load the amplifier when the coaxial cable, or transmission line, is terminated in its characteristic impedance.

### FREQUENCY RESPONSE COMPENSATION

The OPA699 is internally compensated to be unity-gain stable, and has a nominal phase margin of  $60^\circ$  at a gain of +6. Phase margin and peaking improve at higher gains. Recall that an inverting gain of  $-5$  is equivalent to a gain of +6 for bandwidth purposes (that is, noise gain = 6). Standard external compensation techniques work with this device. For example, in the inverting configuration, the bandwidth may be limited without modifying the inverting gain by placing a series RC network to ground on the inverting node. This has the effect of increasing the noise gain at high frequencies, which limits the bandwidth.

If a unity-gain stable amplifier is needed, the OPA698 is recommended.

In applications where a large feedback resistor is required, such as a photodiode transimpedance amplifier, the parasitic capacitance from the inverting input to ground causes peaking or oscillations. To compensate for this effect, connect a small capacitor in parallel with the feedback resistor. The bandwidth will be limited by the pole that the feedback resistor and this capacitor create. In other high-gain applications, use a three-resistor *Tee* network to reduce the RC time constants set by the parasitic capacitances.

### PULSE SETTling TIME

The OPA699 is capable of an extremely fast settling time in response to a pulse input. Frequency response flatness and phase linearity are needed to obtain the best settling times. For capacitive loads, such as an ADC, use the recommended  $R_S$  in the typical performance curve *Recommended  $R_S$  vs Capacitive Load*. Extremely fine-scale settling (0.01%) requires close attention to ground return current in the supply decoupling capacitors.

The pulse settling characteristics, when recovering from overdrive, are extremely good as shown in the typical characteristics.

### DISTORTION

The OPA699 distortion performance is specified for a  $500\Omega$  load, such as an ADC. Driving loads with smaller resistance will increase the distortion, as illustrated in Figure 15. Remember to include the feedback network in the load resistance calculations.

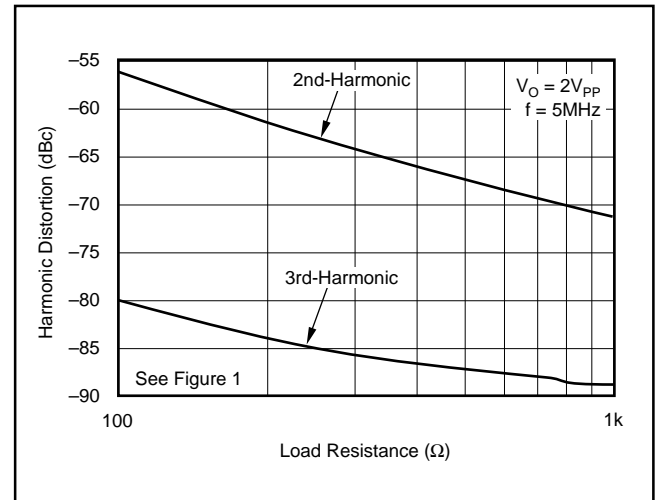


FIGURE 15. 5MHz Harmonic Distortion vs Load Resistance.

### NOISE PERFORMANCE

High slew rate, voltage-feedback op amps usually achieve their slew rate at the expense of a higher input noise voltage. The  $4.1\text{nV}/\sqrt{\text{Hz}}$  input voltage noise for the OPA699, however, is much lower than comparable amplifiers. The input-referred voltage noise, and the two input-referred current noise terms, combine to give low output noise under a wide variety of operating conditions. Figure 16 shows the op amp noise analysis model with all the noise terms included. In this model, all noise terms are taken to be noise voltage or current density terms in either  $\text{nV}/\sqrt{\text{Hz}}$  or  $\text{pA}/\sqrt{\text{Hz}}$ .

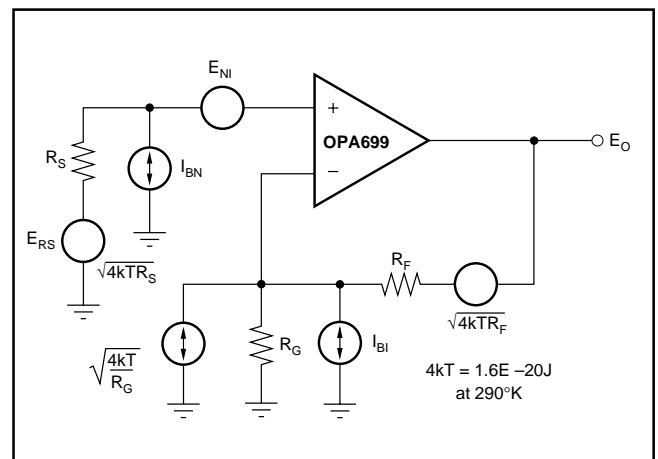


FIGURE 16. Op Amp Noise Analysis Model.



The total output spot noise voltage can be computed as the square root of the sum of all squared output noise voltage contributors. Equation 5 shows the general form for the output noise voltage using the terms shown in Figure 16.

(5)

$$E_O = \sqrt{(E_{NI}^2 + (I_{BN}R_S)^2 + 4kTR_S)NG^2 + (I_{BI}R_F)^2 + 4kTR_F NG}$$

Dividing this expression by the noise gain ( $NG = (1 + R_F/R_G)$ ) will give the equivalent input-referred spot noise voltage at the noninverting input, as shown in Equation 6.

(6)

$$E_N = \sqrt{E_{NI}^2 + (I_{BN}R_S)^2 + 4kTR_S + \left(\frac{I_{BI}R_F}{NG}\right)^2 + \frac{4kTR_F}{NG}}$$

Evaluating these two equations for the OPA699 circuit and component values (see Figure 1) will give a total output spot noise voltage of 27.4nV/√Hz and a total equivalent input spot noise voltage of 4.6nV/√Hz. This total input-referred spot noise voltage is only slightly higher than the 4.1nV/√Hz specification for the op amp voltage noise alone. This will be the case as long as the impedances appearing at each op amp input are limited to a maximum value of 300Ω. Keeping both ( $R_F \parallel R_G$ ) and the noninverting input source impedance less than 300Ω will satisfy both noise and frequency response flatness considerations. Since the resistor-induced noise is negligible, additional capacitive decoupling across the bias current cancellation resistor ( $R_T$ ) for the inverting op amp configuration of Figure 3 is not required, but is still desirable.

## DC ACCURACY AND OFFSET CONTROL

The balanced input stage of a wideband voltage feedback op amp allows good output DC accuracy in a large variety of applications. The power-supply current trim for the OPA699 gives even tighter control than comparable products. Although the high-speed input stage does require relatively high input bias current (typically 3μA at each input terminal), the close matching between them may be used to reduce the output DC error caused by this current. The total output offset voltage may be considerably reduced by matching the DC source resistances appearing at the two inputs. This reduces the output DC error due to the input bias currents to the offset current times the feedback resistor. Evaluating the configuration of Figure 1, using worst-case +25°C input offset voltage and current specifications, gives a worst-case output offset voltage, with  $NG =$  noninverting signal gain, equal to:

$$\begin{aligned} & \pm(NG \cdot V_{OS(MAX)}) \pm (R_F \cdot I_{OS(MAX)}) \\ & = \pm(2 \cdot 5mV) \pm (750\Omega \cdot 2.0\mu A) \\ & = \pm 11.5mV \end{aligned}$$

A fine-scale output offset null, or DC operating point adjustment, is often required. Numerous techniques are available for introducing DC offset control into an op amp circuit. Most of these techniques eventually reduce to adding a DC current

through the feedback resistor. In selecting an offset trim method, one key consideration is the impact on the desired signal path frequency response. If the signal path is intended to be noninverting, the offset control is best applied as an inverting summing signal to avoid interaction with the signal source. If the signal path is intended to be inverting, applying the offset control to the noninverting input may be considered. However, the DC offset voltage on the summing junction will set up a DC current back into the source which must be considered. Applying an offset adjustment to the inverting op amp input can change the noise gain and frequency response flatness. For a DC-coupled inverting amplifier, Figure 17 shows one example of an offset adjustment technique that has minimal impact on the signal frequency response. In this case, the DC offsetting current is brought into the inverting input node through resistor values that are much larger than the signal path resistors. This will insure that the adjustment circuit has minimal effect on the loop gain as well as the frequency response.

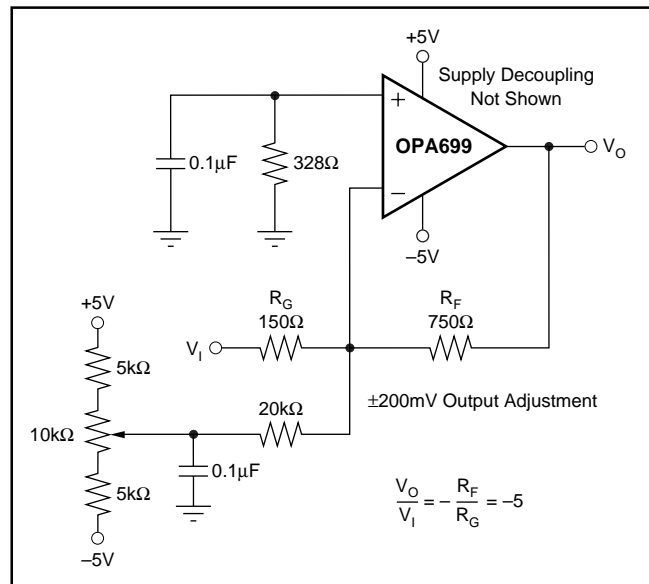


FIGURE 17. DC-Coupled, Inverting Gain of -5, with Offset Adjustment.

## BOARD LAYOUT GUIDELINES

Achieving optimum performance with the high-frequency OPA699 requires careful attention to layout design and component selection. Recommended PCB layout techniques and component selection criteria are:

- Minimize parasitic capacitance to any AC ground** for all of the signal I/O pins. Open a window in the ground and power planes around the signal I/O pins, and leave the ground and power planes unbroken elsewhere.
- Provide a high quality power supply.** Use linear regulators, ground plane and power planes to provide power. Place high frequency 0.1μF decoupling capacitors < 0.2" away from each power-supply pin. Use wide, short traces to connect to these capacitors to the ground and power planes. Also use larger (2.2μF to 6.8μF) high-frequency decoupling

capacitors to bypass lower frequencies. They may be somewhat further from the device, and be shared among several adjacent devices.

c) **Place external components close** to the OPA699. This minimizes inductance, ground loops, transmission line effects and propagation delay problems. Be extra careful with the feedback ( $R_F$ ), input and output resistors.

d) **Use high-frequency components** to minimize parasitic elements. Resistors should be a very low reactance type. Surface-mount resistors work best and allow a tighter layout. Metal film or carbon composition axially-leaded resistors can also provide good performance when their leads are as short as possible. Never use wirewound resistors for high-frequency applications. Remember that most potentiometers have large parasitic capacitances and inductances. Multi-layer ceramic chip capacitors work best and take up little space. Monolithic ceramic capacitors also work very well. Use  $R_F$  type capacitors with low ESR and ESL. The large power pin bypass capacitors ( $2.2\mu\text{F}$  to  $6.8\mu\text{F}$ ) should be tantalum for better high frequency and pulse performance.

e) **Choose low resistor values** to minimize the time constant set by the resistor and its parasitic parallel capacitance. Good metal film or surface mount resistors have approximately  $0.2\text{pF}$  parasitic parallel capacitance. For resistors  $> 1.5\text{k}\Omega$ , this adds a pole and/or zero below  $500\text{MHz}$ . Make sure that the output loading is not too heavy. The recommended  $750\Omega$  feedback resistor is a good starting point in most designs.

f) **Use short direct traces to other wideband devices** on the board. Short traces act as a lumped capacitive load. Wide traces (50 to 100 mils) should be used. Estimate the total capacitive load at the output, and use the series isolation resistor recommended in the typical performance curve, *Recommended  $R_S$  vs Capacitive Load*. Parasitic loads  $< 2\text{pF}$  may not need the isolation resistor.

g) **When long traces are necessary**, use transmission line design techniques (consult an ECL design handbook for microstrip and stripline layout techniques). A  $50\Omega$  transmission line is not required on board—a higher characteristic impedance will help reduce output loading. Use a matching series resistor at the output of the op amp to drive a transmission line, and a matched load resistor at the other end to make the line appear as a resistor. If the 6dB of attenuation that the matched load produces is not acceptable, and the line is not too long, use the series resistor at the source only. This will isolate the source from the reactive load presented by the line, but the frequency response will be degraded. Multiple destination devices are best handled as separate transmission lines, each with its own series source and shunt load terminations. Any parasitic impedances acting on the terminating resistors will alter the transmission line match, and can cause unwanted signal reflections and reactive loading.

h) **Do not use sockets** for high-speed parts like the OPA699. The additional lead length and pin-to-pin capacitance introduced by the socket creates an extremely troublesome parasitic network. Best results are obtained by soldering the part onto the board.

## POWER SUPPLIES

The OPA699 is nominally specified for operation using either  $\pm 5\text{V}$  supplies or a single  $+5\text{V}$  supply. The maximum specified total supply voltage of  $13\text{V}$  allows reasonable tolerances on the supplies. Higher supply voltages can break down internal junctions, possibly leading to catastrophic failure. Single-supply operation is possible as long as common mode voltage constraints are observed. The common-mode input and output voltage specifications can be interpreted as a required headroom to the supply voltage. Observing this input and output headroom requirement will allow design of non-standard or single-supply operation circuits. Figure 2 shows one approach to single-supply operation.

## INPUT AND ESD PROTECTION

The OPA699 is built using a very high-speed complementary bipolar process. The internal junction breakdown voltages are relatively low for these very small geometry devices. These breakdowns are reflected in the Absolute Maximum Ratings table. All device pins are protected with internal ESD protection diodes to the power supplies, as shown in Figure 18.

These diodes provide moderate protection to input overdrive voltages above the supplies as well. The protection diodes can typically support  $30\text{mA}$  continuous current. Where higher currents are possible (e.g., in systems with  $\pm 15\text{V}$  supply parts driving into the OPA699), current limiting series resistors should be added into the two inputs. Keep these resistor values as low as possible, since high values degrade both noise performance and frequency response.

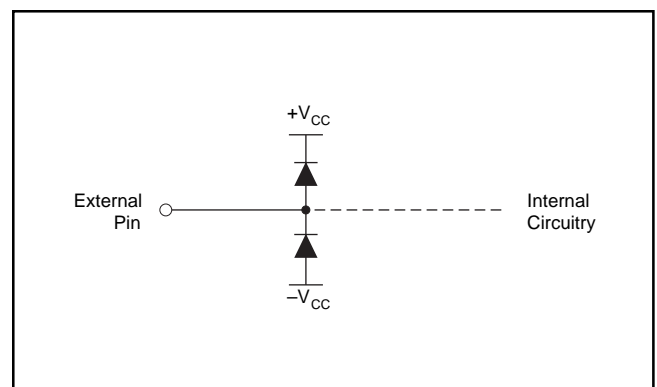


FIGURE 18. I/O Pin ESD Protection.

## Revision History

DATE	REVISION	PAGE	SECTION	DESCRIPTION
12/08	D	2	Absolute Maximum Ratings	Changed minimum Storage Temperature Range from –40°C to –65°C.
3/06	C	19	Design-In Tools	Board part number changed.

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.



## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">OPA699ID</a>	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	OPA 699
OPA699ID.A	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	OPA 699
<a href="#">OPA699IDR</a>	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	OPA 699
OPA699IDR.A	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	OPA 699

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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**OTHER QUALIFIED VERSIONS OF OPA699 :**

- Military : [OPA699M](#)

NOTE: Qualified Version Definitions:

- Military - QML certified for Military and Defense Applications

## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
OPA699IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
OPA699IDR	SOIC	D	8	2500	353.0	353.0	32.0

## TUBE



\*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
OPA699ID	D	SOIC	8	75	506.6	8	3940	4.32
OPA699ID.A	D	SOIC	8	75	506.6	8	3940	4.32



**D0008A**

# PACKAGE OUTLINE

**SOIC - 1.75 mm max height**

SMALL OUTLINE INTEGRATED CIRCUIT



4214825/C 02/2019

## NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

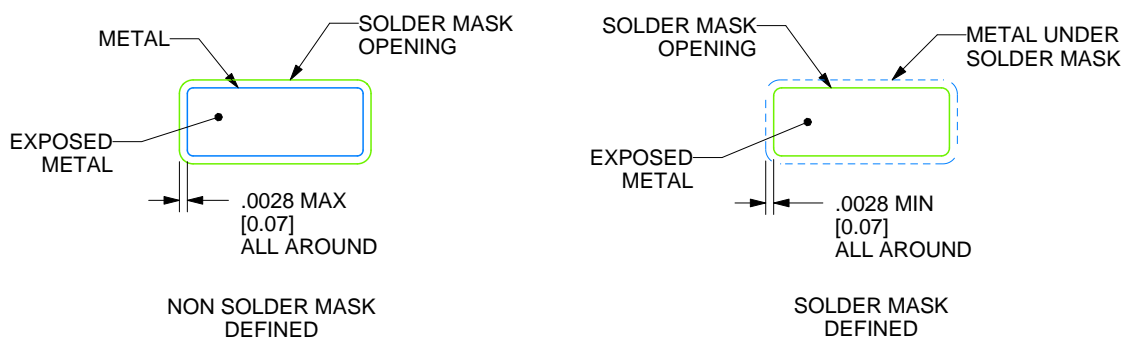
**D0008A**

### SOIC - 1.75 mm max height

## SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:8X



## SOLDER MASK DETAILS

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NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

## EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

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SOLDER PASTE EXAMPLE  
BASED ON .005 INCH [0.125 MM] THICK STENCIL  
SCALE:8X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.



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