







OPA191, OPA2191, OPA4191 SBOS701D - DECEMBER 2015 - REVISED AUGUST 2021

# OPAx191 36-V, Low-Power, Precision, CMOS, Rail-to-Rail Input/Output, Low Offset Voltage, Low Input Bias Current Op Amp

#### 1 Features

Low offset voltage: ±5 µV

Low offset voltage drift: ±0.1 µV/°C

Low noise: 15 nV/√ Hz at 1 kHz

High common-mode rejection: 140 dB

Low bias current: ±5 pA

Rail-to-rail input and output

Wide bandwidth: 2.5-MHz GBW

High slew rate: 5 V/µs

Low quiescent current: 140 µA per amplifier

Wide supply: ±2.25 V to ±18 V, 4.5 V to 36 V

EMI/RFI filtered inputs

Differential input voltage range to supply rail

High capacitive load drive capability: 1 nF

Industry standard packages:

Single in SOIC-8, SOT-5, and VSSOP-8

Dual in SOIC-8 and VSSOP-8

Quad in SOIC-14, TSSOP-14, and WQFN-16

# 2 Applications

- Analog input module
- Mixed module (AI, AO, DI, DO)
- Data acquisition (DAQ)
- Source measurement unit (SMU)
- Pressure transmitter
- Train control and management systems
- Lab and field instrumentation

# 3 Description

The OPAx191 family (OPA191, OPA2191, and OPA4191) is a new generation of 36-V, e-trim™ operational amplifiers.

These devices offer outstanding dc precision and ac performance, including rail-to-rail input/output, low offset voltage (±5 µV, typ), low offset drift (±0.2 µV/°C, typ), and 2-MHz bandwidth.

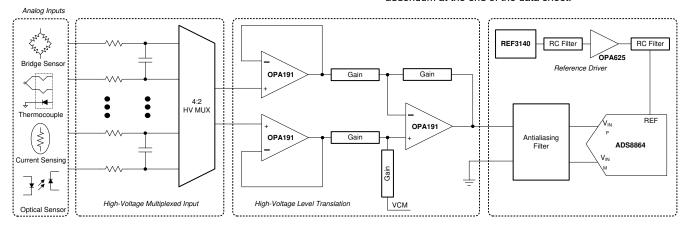
Unique features, such as differential input-voltage range to the supply rail, high output current (±65 mA), high capacitive load drive of up to 1 nF, and high slew rate (5 V/µs), make the OPAx191 a robust, highperformance operational amplifier for high-voltage industrial applications.

The OPAx191 family of op amps is available in standard packages and is specified from -40°C to +125°C.

#### **Device Information**

201.0001111411011							
PART NUMBER	PACKAGE <sup>(1)</sup>	BODY SIZE (NOM)					
	SOIC (8)	4.90 mm × 3.90 mm					
OPA191	SOT (5)	2.90 mm × 1.60 mm					
	VSSOP (8)	3.00 mm × 3.00 mm					
OPA2191	SOIC (8)	4.90 mm × 3.90 mm					
OPAZ 191	VSSOP (8)	3.00 mm × 3.00 mm					
	SOIC (14)	8.65 mm x 3.90 mm					
OPA4191	TSSOP (14)	5.00 mm x 4.40 mm					
	WQFN (16)	4.00 mm x 4.00 mm					

For all available packages, see the package option addendum at the end of the data sheet.



OPA191 in a High-Voltage, Multiplexed, Data-Acquisition System



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# **5 Pin Configuration and Functions**

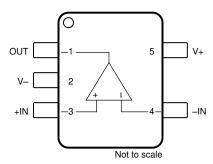


Figure 5-1. OPA191 DBV (5-Pin SOT) Package, Top View

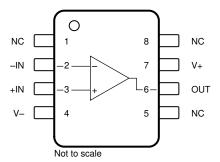


Figure 5-2. OPA191 D (8-Pin SOIC) and DGK (8-Pin VSSOP) Packages, Top View

# **Pin Functions: OPA191**

PIN				
NAME	OPA	191	I/O	DESCRIPTION
	D (SOIC), DGK (VSSOP)	DBV (SOT)		520011111111111111111111111111111111111
+IN	3	3	I	Noninverting input
-IN	2	4	I	Inverting input
NC	1, 5, 8	_	_	No internal connection (can be left floating)
OUT	6	1	0	Output
V+	7	5	_	Positive (highest) power supply
V-	4	2	_	Negative (lowest) power supply



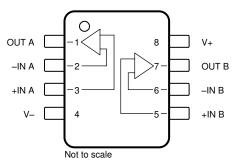


Figure 5-3. OPA2191 D (8-Pin SOIC) and DGK (8-Pin VSSOP) Packages, Top View

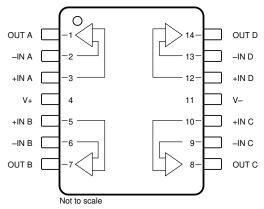


Figure 5-4. OPA4191 D (14-Pin SOIC) and PW (14-Pin TSSOP) Packages, Top View

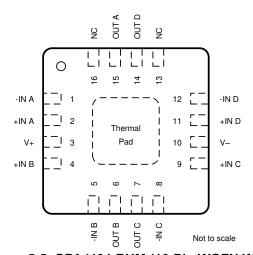


Figure 5-5. OPA4191 RUM (16-Pin WQFN With Exposed Thermal Pad) Package, Top View

## Pin Functions: OPA2191 and OPA4191

PIN						
	OPA2191 OPA4191		4191	] I/O	DESCRIPTION	
NAME	D (SOIC), DGK (VSSOP)	D (SOIC), PW (TSSOP)	RUM (QFN)		Jest Million	
+IN A	3	3	2	I	Noninverting input, channel A	
+IN B	5	5	4	I	Noninverting input, channel B	
+IN C	_	10	9	I	Noninverting input, channel C	
+IN D	_	12	11	I	Noninverting input, channel D	
–IN A	2	2	1	I	Inverting input, channel A	
–IN B	6	6	5	I	Inverting input, channel B	
–IN C	_	9	8	I	Inverting input,,channel C	
–IN D	_	13	12	I	Inverting input, channel D	
OUT A	1	1	15	0	Output, channel A	
OUT B	7	7	6	0	Output, channel B	
OUT C	_	8	7	0	Output, channel C	
OUT D	_	14	14	0	Output, channel D	
V+	8	4	3	_	Positive (highest) power supply	
V–	4	11	10	_	Negative (lowest) power supply	

# **6 Specifications**

# **6.1 Absolute Maximum Ratings**

over operating free-air temperature range (unless otherwise noted)(1)

		·	MIN	MAX	UNIT
Supply voltage, $V_S = (V+) - (V-)$			±20 (+40, single supply)	V	
Signal input pins	Voltage	Common-mode	(V-) - 0.5	(V+) + 0.5	V
	voltage	Differential		(V+) - (V-) + 0.2	v
	Current			±10	mA
Output short circuit <sup>(2)</sup>			Continuous	Continuous	Continuous
	Operating	Operating		150	
Temperature	Junction	Junction		150	°C
	Storage, T <sub>stg</sub>	Storage, T <sub>stg</sub>		150	

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### 6.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub> Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±3000		
	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>		v
- (E3D)		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup> , OPA4191IPW package only	±500	-

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

## **6.3 Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted)

	MIN	NOM MAX	UNIT
Supply voltage, $V_S = (V+) - (V-)$	4.5 (±2.25)	36 (±18)	V
Specified temperature	-40	125	°C

<sup>(2)</sup> Short-circuit to ground, one amplifier per package.

<sup>(2)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



## 6.4 Thermal Information: OPA191

THERMAL METRIC <sup>(1)</sup>			OPA191				
		D (SOIC)	DGK (VSSOP)	DBV (SOT)	UNIT		
		8 F	PINS	5 PINS			
$R_{\theta JA}$	Junction-to-ambient thermal resistance	115.8	180.4	158.8	°C/W		
R <sub>0JC(top)</sub>	Junction-to-case(top) thermal resistance	60.1	67.9	60.7	°C/W		
R <sub>0JB</sub>	Junction-to-board thermal resistance	56.4	102.1	44.8	°C/W		
ΨЈТ	Junction-to-top characterization parameter	12.8	10.4	1.6	°C/W		
ΨЈВ	Junction-to-board characterization parameter	55.9	100.3	4.2	°C/W		
$R_{\theta JC(bot)}$	Junction-to-case(bottom) thermal resistance	N/A	N/A	N/A	°C/W		

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

#### 6.5 Thermal Information: OPA2191

		OPA	OPA2191			
THERMAL METRIC(1)		D (SOIC)	DGK (VSSOP)	UNIT		
		8 P	8 PINS			
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	107.9	158	°C/W		
R <sub>0JC(top)</sub>	Junction-to-case(top) thermal resistance	53.9	48.6	°C/W		
$R_{\theta JB}$	Junction-to-board thermal resistance	48.9	78.7	°C/W		
ΨЈТ	Junction-to-top characterization parameter	6.6	3.9	°C/W		
ΨЈВ	Junction-to-board characterization parameter	48.3	77.3	°C/W		
R <sub>θJC(bot)</sub>	Junction-to-case(bottom) thermal resistance	N/A	N/A	°C/W		

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

#### 6.6 Thermal Information: OPA4191

			OPA4191				
	THERMAL METRIC <sup>(1)</sup>		PW (TSSOP)	RUM (QFN)	UNIT		
		14	PINS	16 PINS			
R <sub>0JA</sub>	Junction-to-ambient thermal resistance	86.4	108.1	33.0	°C/W		
R <sub>0JC(top)</sub>	Junction-to-case(top) thermal resistance	46.3	26.3	25.1	°C/W		
$R_{\theta JB}$	Junction-to-board thermal resistance	41.0	54.4	11.6	°C/W		
ΨЈТ	Junction-to-top characterization parameter	11.3	1.4	0.2	°C/W		
ΨЈВ	Junction-to-board characterization parameter	40.7	53.3	11.5	°C/W		
R <sub>0JC(bot)</sub>	Junction-to-case(bottom) thermal resistance	N/A	N/A	2.6	°C/W		

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.



# 6.7 Electrical Characteristics: $V_S = \pm 4 \text{ V to } \pm 18 \text{ V (V}_S = 8 \text{ V to } 36 \text{ V})$ at $T_A = \pm 25^{\circ}\text{C}$ . $V_{CM} = V_{CUT} = V_S / 2$ , and $R_V = 10 \text{ kO}$ connected to $V_S / 2$ (unless otherwise noted)

	PARAMETER	$V_S$ / 2, and $R_L$ = 10 kΩ connected to $V_S$ / 2 (unless of TEST CONDITIONS		MIN	TYP	MAX	UNIT	
OFFSET	VOLTAGE							
					±5	±25		
		V <sub>S</sub> = ±18 V	T <sub>A</sub> = 0°C to 85°C		±8	±75		
			$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±10	±125		
	$(V+) - 3.0 V < V_{CM} < (V+) - 1.5 V$	, A	See Typica	I Characte				
		Oil C		21	±10	±50		
Vos	Input offset voltage	$V_S = \pm 18 \text{ V},$	T <sub>A</sub> = 0°C to 85°C		±25	±150	μV	
		$V_{CM} = (V+) - 1.5 V$	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±50	±250		
					±5	±50		
		OPA4191 (RUM, PW), V <sub>S</sub> = ±18 V	T <sub>A</sub> = 0°C to 85°C		±10	±475		
		VCM = (V+) – 1.5 V	TA = -40°C to +125°C		±20	±740		
		V <sub>S</sub> = ±18 V, D and PW packages	T <sub>A</sub> = 0°C to 85°C		±0.1	±0.8		
		only	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±0.15	±1.2		
dV <sub>OS</sub> /dT	IV <sub>OS</sub> /dT Input offset voltage drift	V <sub>S</sub> = ±18 V, RUM, DGK and DBV	T <sub>A</sub> = 0°C to 85°C		±0.1	±0.9	μV/°C	
00		packages only	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±0.15	±1.3	•	
		V <sub>S</sub> = ±18 V, V <sub>CM</sub> = (V+) – 1.5 V	T <sub>A</sub> = -40°C to +125°C		±0.5			
PSRR	Power-supply rejection ratio	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$			±0.3	±1.0	μV/V	
INPLIT BI	AS CURRENT				-			
					±5	±20	pA	
I <sub>B</sub>	Input bias current	T <sub>A</sub> = -40°C to +125°C				±9	nA	
		14 10 0 to 120 0			±2	±20	pA	
los	Input offset current	T <sub>A</sub> = -40°C to +125°C				±2	nA	
NOISE								
		(V-) - 0.1 V < V <sub>CM</sub> < (V+) - 3 V	f = 0.1 Hz to 10 Hz		1.4			
En	Input voltage noise	$(V+) - 1.5 V < V_{CM} < (V+) + 0.1 V$	f = 0.1 Hz to 10 Hz		7		$\mu V_{PP}$	
			f = 100 Hz		18			
	Input voltage noise	$(V-) - 0.1 V < V_{CM} < (V+) - 3 V$	f = 1 kHz		15		-	
e <sub>n</sub>	density		f = 100 Hz		53		nV/√Hz	
		$(V+) - 1.5 V < V_{CM} < (V+) + 0.1 V$	f = 1 kHz		24			
i <sub>n</sub>	Input current noise density	f = 1 kHz			1.5		fA/√Hz	
INPUT VO								
	Common-mode voltage					04 ) 04		
V <sub>CM</sub>	range			(V–) – 0.1		(V+) + 0.1	V	
		$V_S = \pm 18 \text{ V},$ $(V-) - 0.1 \text{ V} < V_{CM} < (V+) - 3 \text{ V}$		120	140			
CMRR	Common-mode rejection	V <sub>S</sub> = ±18 V, (V-) < V <sub>CM</sub> < (V+) - 3 V	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$	114	126		dB	
CIVILAI	ratio	V <sub>S</sub> = ±18 V,		96	120		uБ	
		$(V+) - 1.5 V < V_{CM} < (V+)$	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$	86	100			
		$(V+) - 3 V < V_{CM} < (V+) - 1.5 V$	1	See Typica	l Characte	eristics		
INPUT IM	IPEDANCE							
Z <sub>ID</sub>	Differential			1	100    1.6		MΩ    pl	
Z <sub>IC</sub>	Common-mode				1    6.4		10 <sup>13</sup> Ω   pF	



# 6.7 Electrical Characteristics: $V_S = \pm 4 \text{ V}$ to $\pm 18 \text{ V}$ ( $V_S = 8 \text{ V}$ to 36 V) (continued)

at  $T_A = +25$ °C,  $V_{CM} = V_{OUT} = V_S / 2$ , and  $R_L = 10 \text{ k}\Omega$  connected to  $V_S / 2$  (unless otherwise noted)

	PARAMETER	TEST CO	NDITIONS	MIN	TYP	MAX	UNIT	
OPEN-LO	OOP GAIN							
		$V_S = \pm 18 \text{ V},$ $(V-) + 0.6 \text{ V} < V_O < (V+) - 0.6 \text{ V},$ $R_L = 2 \text{ k}\Omega$		124	134			
		$V_S = \pm 18 \text{ V},$ $(V-) + 0.8 \text{ V} < V_O < (V+) - 0.8 \text{ V},$ $R_L = 2 \text{ k}\Omega, \text{ RUM package}$		124	134			
^	Open leep veltage gain	$V_S = \pm 18 \text{ V},$ (V-) + 0.6 V < $V_O$ < (V+) - 0.6 V, $R_L = 2 \text{ k}\Omega$	T <sub>A</sub> = -40°C to +125°C	114	126		dB	
A <sub>OL</sub>	Open-loop voltage gain	$V_S = \pm 18 \text{ V},$ $(V-) + 0.8 \text{ V} < V_O < (V+) - 0.8 \text{ V},$ $R_L = 2 \text{ k}\Omega, \text{ RUM package}$	T <sub>A</sub> = -40°C to +125°C	114	126		ив	
		$V_S = \pm 18 \text{ V},$ $(V-) + 0.3 \text{ V} < V_O < (V+) - 0.3 \text{ V},$ $R_L = 10 \text{ k}\Omega$		126	140			
		$V_S = \pm 18 \text{ V},$ $(V-) + 0.3 \text{ V} < V_O < (V+) - 0.3 \text{ V},$ $R_L = 10 \text{ k}\Omega$	T <sub>A</sub> = -40°C to +125°C	120	134			
FREQUE	NCY RESPONSE							
GBW	Unity gain bandwidth				2.5		MHz	
SR	Slew rate	V <sub>S</sub> = ±18 V, G = 1, 10-V step	Falling		7.5		V/µs	
SK	Siew rate	V <sub>S</sub> = ±16 V, G = 1, 10-V step	Rising		5.5		ν/μ5	
		To 0.01%, C <sub>L</sub> = 20 pF	V <sub>S</sub> = ±18 V, G = 1, 2-V step		0.7			
t <sub>s</sub>	Settling time		V <sub>S</sub> = ±18 V, G = 1, 5-V step		1		μs	
's	Octaining arrice	To 0.001%, C <sub>L</sub> = 20 pF	V <sub>S</sub> = ±18 V, G = 1, 2-V step		1.8		μο	
			V <sub>S</sub> = ±18 V, G = 1, 5-V step		3.7			
t <sub>OR</sub>	Overload recovery time	$V_{IN} \times G = V_{S}$	From overload to negative rail		0.4		μs	
-010		- IIV 3	From overload to positive rail		11		r	
THD+N	Total harmonic distortion + noise	$G = 1$ , $f = 1$ kHz, $V_O = 3.5$ $V_{RMS}$			0.0012%			
	Crosstalk	OPA2191 and OPA4191, at dc			150		dB	
		OPA2191 and OPA4191, f = 100 kl	Hz		130		dB	
OUTPUT		T						
			No load		5	15		
		Positive rail	R <sub>L</sub> = 10 kΩ		50	110		
Vo	Voltage output swing from rail		$R_L = 2 k\Omega$		200	500	mV	
	IIOIII Iali		No load		5	15		
		Negative rail	R <sub>L</sub> = 10 kΩ		50	110		
	0	V .40V	$R_L = 2 k\Omega$		200	500		
I <sub>SC</sub>	Short-circuit current	V <sub>S</sub> = ±18 V			±65		mA	
CL	Capacitive load drive			See	Typical Chara	acteristics		
Z <sub>O</sub>	Open-loop output impedance	f = 1 MHz, I <sub>O</sub> = 0 A, See Typical Cl	naracteristics		700		Ω	
POWER	SUPPLY	I						
IQ	Quiescent current per amplifier	I <sub>O</sub> = 0 A	T <sub>A</sub> = -40°C to +125°C		140	200 250	μΑ	
TEMPER	ATURE	ı						
	Thermal protection				180		°C	
	Thermal hysteresis			-	30		°C	



# 6.8 Electrical Characteristics: $V_S = \pm 2.25 \text{ V}$ to $\pm 4 \text{ V}$ ( $V_S = 4.5 \text{ V}$ to 8 V)

at  $T_A$  = +25°C,  $V_{CM}$  =  $V_{OUT}$  =  $V_S$  / 2, and  $R_L$  = 10 k $\Omega$  connected to  $V_S$  / 2 (unless otherwise noted)

	PARAMETER TEST CONDITIONS			MIN	MAX	UNIT		
OFFSET	VOLTAGE							
					±5	±25		
		$V_S = \pm 2.25 \text{ V},$	T <sub>A</sub> = 0°C to 85°C		±8	±75		
		$V_{CM} = (V+) - 3 V$	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±10	±125		
		$(V+) - 3.0 V < V_{CM} < (V+) - 1.5 V$	See Typical	Characte	eristics			
	Input offset voltage	J. J			±10	±50		
V <sub>OS</sub>		$V_S = \pm 3 V$ ,	T <sub>A</sub> = 0°C to 85°C		±25	±150	μV	
		$V_{CM} = (V+) - 1.5 V$	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±50	±250		
			A		±10	±50		
		OPA4191 (RUM, PW), V <sub>S</sub> = ±3 V,	$T_A = -40^{\circ}\text{C to } +85^{\circ}\text{C}$		±90	±475		
		$V_{CM} = (V+) - 1.5 V$	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±150	±740		
		V - 10.05 V V - 0/1) 2 V	$T_A = 0^{\circ}C \text{ to } 85^{\circ}C$		±0.1	±0.8	μV/°C	
		$V_S = \pm 2.25 \text{ V}, V_{CM} = (V+) - 3 \text{ V},$ D and PW packages only	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±0.15	±1.2	μV/°C	
-1) / / !	Inner to effect to 11 125	$V_S = \pm 2.25 \text{ V}, V_{CM} = (V+) - 3$	$T_A = 0^{\circ}C \text{ to } 85^{\circ}C$		±0.13	±0.9	μ ν/ Ο	
dV <sub>OS</sub> /dT	Input offset voltage drift	V, RUM, DGK and DBV packages					\.//0.0	
		only	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±0.15	±1.3	μV/°C	
		$V_S = \pm 2.25 \text{ V}, V_{CM} = (V+) - 1.5 \text{ V}$	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$		±0.5		μV/V ±20 pA	
PSRR	Power-supply rejection ratio	$T_A = -40$ °C to +125°C, $V_{CM} = V_S / 2 - 0.75$ V ±1						
INPUT BI	AS CURRENT							
I <sub>B</sub>	Input bias current				±5	±20	pА	
'В	mpat blad darront	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$				±9	nA	
l	Input offset current			±2 ±20				
I <sub>OS</sub>	input onset current	$T_A = -40^{\circ}C \text{ to } +125^{\circ}C$			±2	nA		
NOISE								
	Input voltage noise	$(V-) - 0.1 V < V_{CM} < (V+) - 3 V$	f = 0.1 Hz to 10 Hz		1.4		\/	
En		(V+) - 1.5 V < V <sub>CM</sub> < (V+) + 0.1 V	f = 0.1 Hz to 10 Hz		7		$\mu V_{PP}$	
		$(V-) - 0.1 V < V_{CM} < (V+) - 3 V$ $(V+) - 1.5 V < V_{CM} < (V+) + 0.1 V$	f = 100 Hz		18			
	Input voltage noise density		f = 1 kHz		15		nV/√Hz	
e <sub>n</sub>			f = 100 Hz		53			
			f = 1 kHz		24			
i <sub>n</sub>	Input current noise density		f = 1 kHz		1.5		fA/√Hz	
INPUT VO	DLTAGE							
	Common-mode voltage			0/1) 04		()(1) . () 4		
V <sub>CM</sub>	range			(V-) - 0.1		(V+) + 0.1	V	
CMRR		$V_S = \pm 2.25 \text{ V},$ $(V-) - 0.1 \text{ V} < V_{CM} < (V+) - 3 \text{ V}$		96	110			
	Common-mode rejection	$V_S = \pm 2.25 \text{ V},$ $(V-) < V_{CM} < (V+) - 3 \text{ V}$	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$	90	104		٩D	
	ratio	V <sub>S</sub> = ±2.25 V,		96	120		dB	
		$(V+) - 1.5 V < V_{CM} < (V+)$	T <sub>A</sub> = -40°C to +125°C	84	100			
		(V+) – 3 V < V <sub>CM</sub> < (V+) – 1.5 V	,	See Typical		eristics		
INPUT IM	PEDANCE	3 ( )		7,				
Z <sub>ID</sub>	Differential			10	00    1.6		MΩ    pF	
	Common mad-						10 <sup>13</sup> Ω	
Z <sub>IC</sub>	Common-mode				1    6.4		pF	



# 6.8 Electrical Characteristics: $V_S = \pm 2.25 \text{ V}$ to $\pm 4 \text{ V}$ ( $V_S = 4.5 \text{ V}$ to 8 V) (continued)

at  $T_A$  = +25°C,  $V_{CM}$  =  $V_{OUT}$  =  $V_S$  / 2, and  $R_L$  = 10 k $\Omega$  connected to  $V_S$  / 2 (unless otherwise noted)

	PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNIT
OPEN-L	OOP GAIN						
A <sub>OL</sub>		$V_S = \pm 2.25 \text{ V},$ $(V-) + 0.6 \text{ V} < V_O < (V+) - 0.6 \text{ V},$ $R_L = 2 \text{ k}\Omega$		110	120		
	0		$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$	100	114		-ID
	Open-loop voltage gain	$V_S = \pm 2.25 \text{ V},$ $(V-) + 0.3 \text{ V} < V_O < (V+) - 0.3 \text{ V},$ $R_L = 10 \text{ k}\Omega$		110	126		dB
			$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$	106	120		
FREQU	ENCY RESPONSE					"	
GBW	Unity gain bandwidth				2.2		MHz
SR	Slew rate	V <sub>S</sub> = ±2.25 V, G = 1, 1-V step	Falling		6.5		V/µs
SK	Siew rate		Rising		5.5		v/µs
+	Overload recovery time	$V_{IN} \times G = V_{S}$	From overload to negative rail		0.4		ше
t <sub>OR</sub>	Overload recovery time	VIN ~ G - VS	From overload to positive rail		1		μs
	Crosstalk	OPA2191 and OPA4191, at dc		150			dB
	Olossiaik	OPA2191 and OPA4191, f = 100 k	00 kHz 130				dB
OUTPU	Т				·		
			No load		5	15	
	Voltage output swing from rail	Positive rail  e output swing from  Negative rail	$R_L = 10 \text{ k}\Omega$		15	110	
Vo			$R_L = 2 k\Omega$		60	500	mV
<b>v</b> 0			No load		5	15	1117
			$R_L = 10 \text{ k}\Omega$		15	110	
			$R_L = 2 k\Omega$		60	500	
I <sub>SC</sub>	Short-circuit current	$V_S = \pm 2.25 \text{ V}$			±30		mA
C <sub>L</sub>	Capacitive load drive		See 7				
Z <sub>O</sub>	Open-loop output impedance	f = 1 MHz, I <sub>O</sub> = 0 A, see Typical Cl	naracteristics		700		Ω
POWER	RSUPPLY						
IQ	Quiescent current per	I <sub>O</sub> = 0 A			140	200	μA
	amplifier	10 - 0 A	$T_A = -40^{\circ}\text{C to } +125^{\circ}\text{C}$			250	μΛ
TEMPE	RATURE						
	Thermal protection				180		°C
	Thermal hysteresis				30		°C



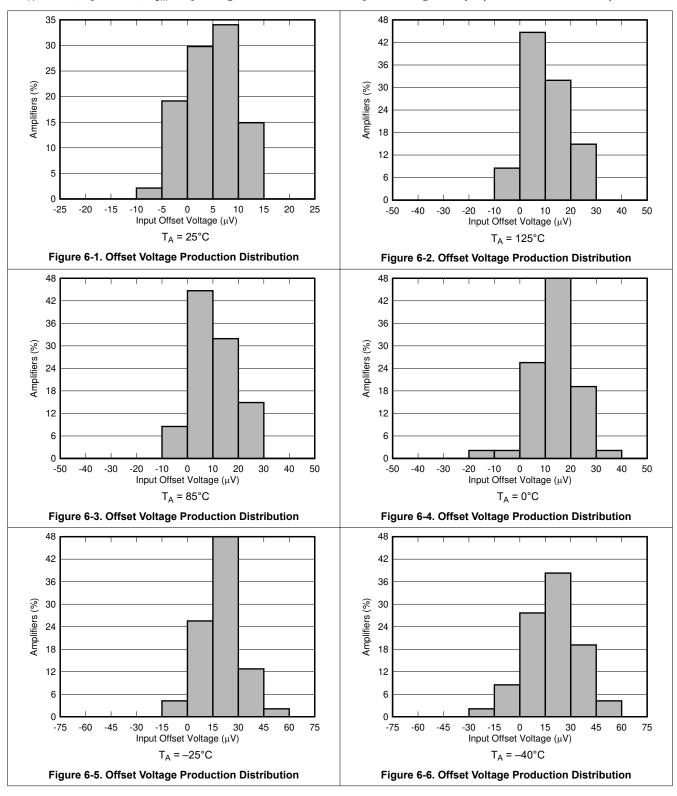
# **6.9 Typical Characteristics**

at  $T_A$  = 25°C,  $V_S$  = ±18 V,  $V_{CM}$  =  $V_S$  / 2,  $R_L$  = 10 k $\Omega$  connected to  $V_S$  / 2, and  $C_L$  = 100 pF (unless otherwise noted)

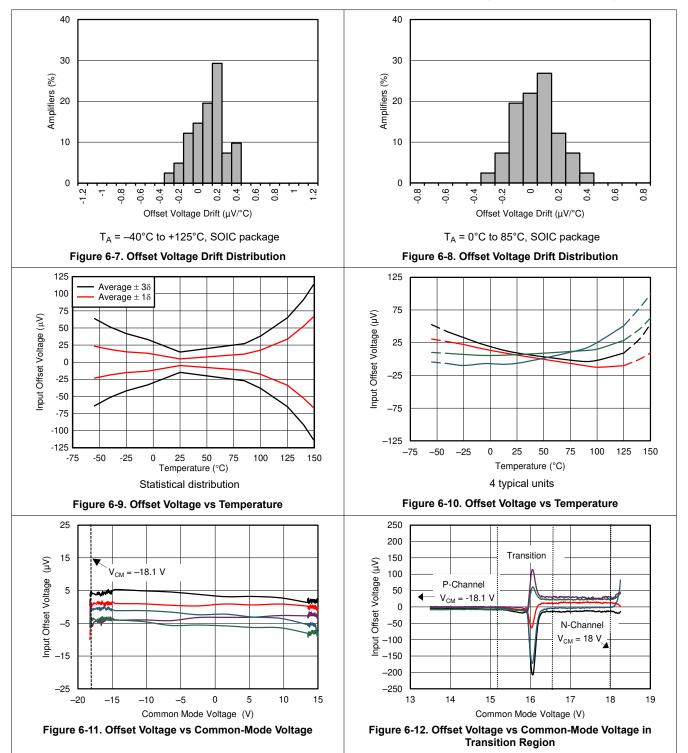
# **Table 6-1. Table of Graphs**

DESCRIPTION	FIGURE				
Offset Voltage Production Distribution	Figure 6-1, Figure 6-2, Figure 6-3, Figure 6-4, Figure 6-5, Figure 6-6				
Offset Voltage Drift Distribution	Figure 6-7, Figure 6-8,				
Offset Voltage vs Temperature	Figure 6-9, Figure 6-10				
Offset Voltage vs Common-Mode Voltage	Figure 6-11, Figure 6-12				
Offset Voltage vs Power Supply	Figure 6-13				
Open-Loop Gain and Phase vs Frequency	Figure 6-14				
Closed-Loop Gain and Phase vs Frequency	Figure 6-15				
Input Bias Current vs Common-Mode Voltage	Figure 6-16				
Input Bias Current vs Temperature	Figure 6-17				
Output Voltage Swing vs Output Current (maximum supply)	Figure 6-18, Figure 6-19				
CMRR and PSRR vs Frequency	Figure 6-20				
CMRR vs Temperature	Figure 6-21				
PSRR vs Temperature	Figure 6-22				
0.1-Hz to 10-Hz Noise	Figure 6-23				
Input Voltage Noise Spectral Density vs Frequency	Figure 6-24				
THD+N Ratio vs Frequency	Figure 6-25				
THD+N vs Output Amplitude	Figure 6-26				
Quiescent Current vs Supply Voltage	Figure 6-27				
Quiescent Current vs Temperature	Figure 6-28				
Open Loop Gain vs Temperature	Figure 6-29, Figure 6-30				
Open Loop Output Impedance vs Frequency	Figure 6-31				
Small Signal Overshoot vs Capacitive Load (100-mV output step)	Figure 6-32, Figure 6-33				
No Phase Reversal	Figure 6-34				
Overload Recovery	Figure 6-35				
Small-Signal Step Response (100 mV)	Figure 6-36, Figure 6-37				
Large-Signal Step Response	Figure 6-38, Figure 6-39				
Settling Time	Figure 6-40, Figure 6-41, Figure 6-42, Figure 6-43				
Short-Circuit Current vs Temperature	Figure 6-44				
Maximum Output Voltage vs Frequency	Figure 6-45				
Propagation Delay Rising Edge	Figure 6-46				
Propagation Delay Falling Edge	Figure 6-47				

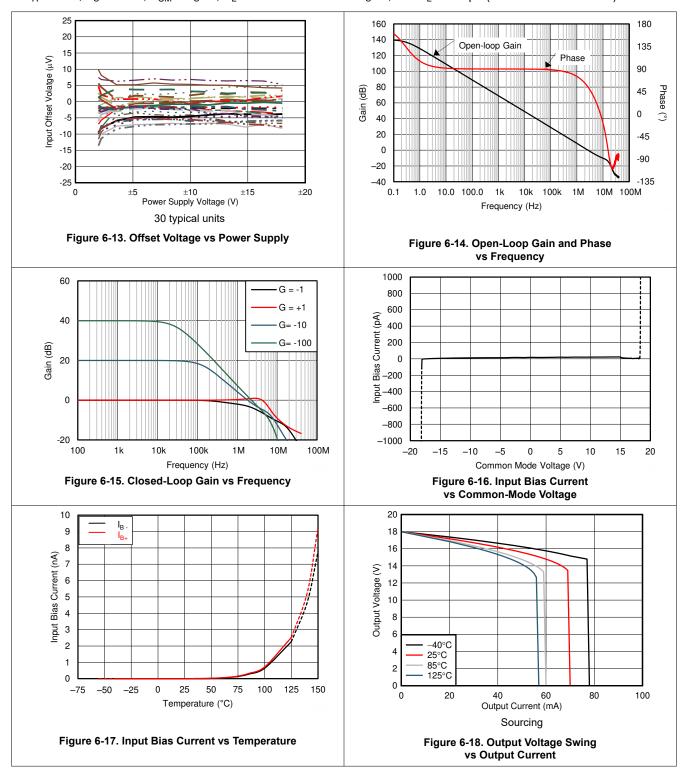




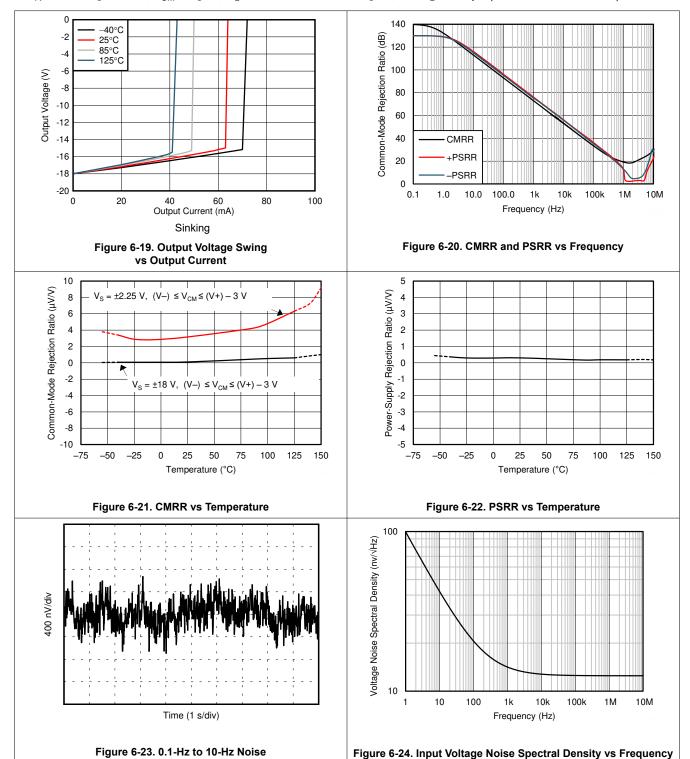




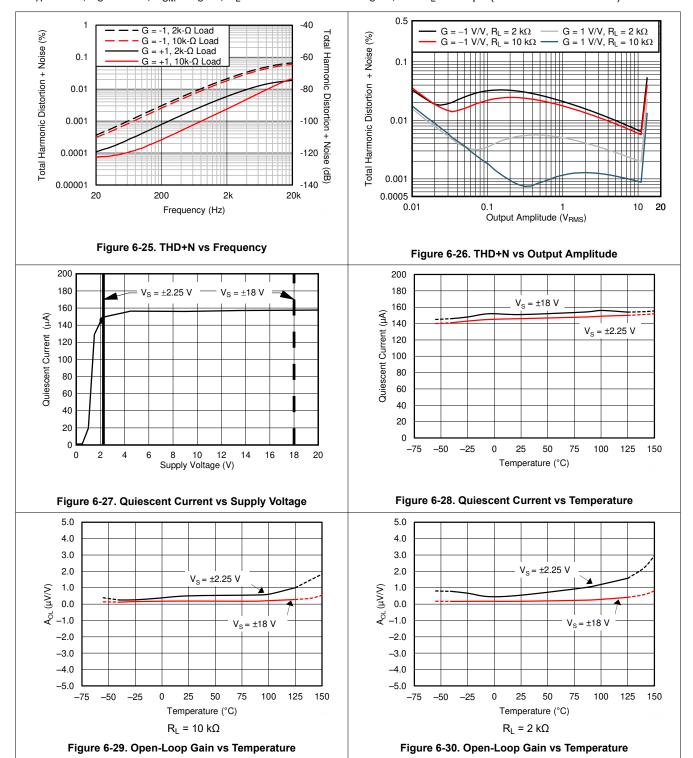




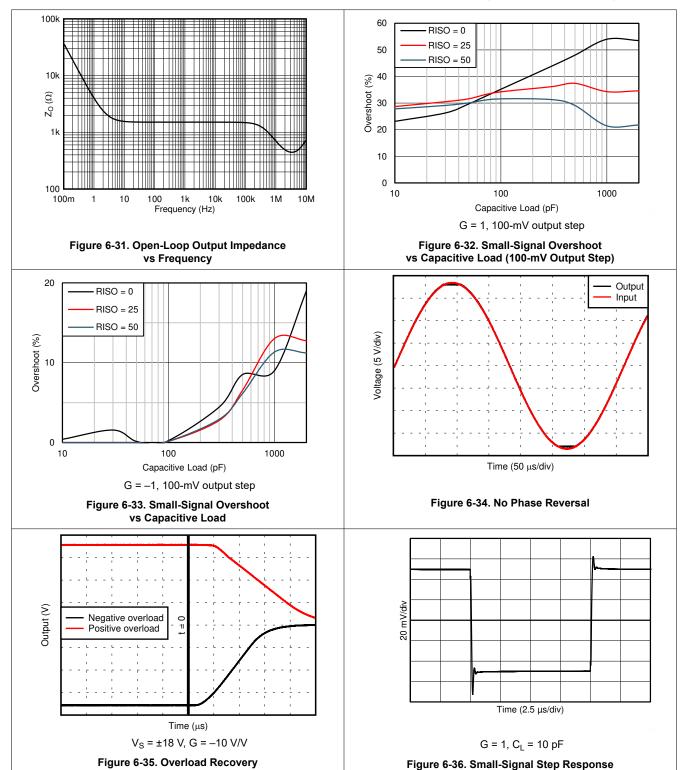




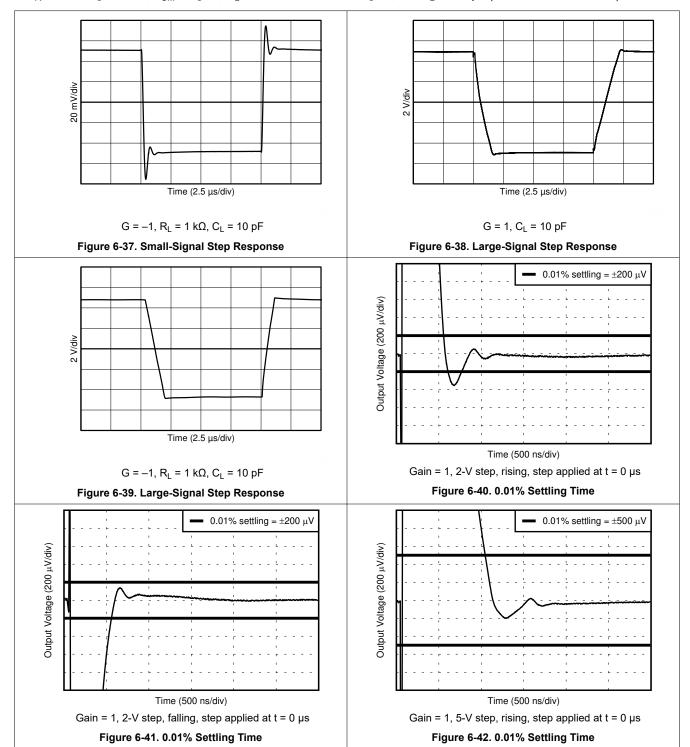














at  $T_A = 25$ °C,  $V_S = \pm 18$  V,  $V_{CM} = V_S / 2$ ,  $R_L = 10$  k $\Omega$  connected to  $V_S / 2$ , and  $C_L = 100$  pF (unless otherwise noted)

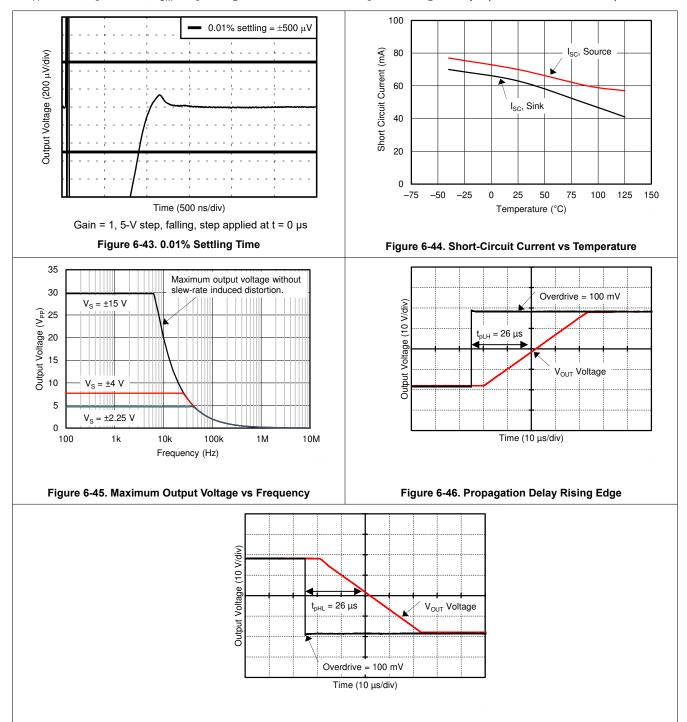


Figure 6-47. Propagation Delay Falling Edge

## 7 Parameter Measurement Information

# 7.1 Input Offset Voltage Drift

The OPAx191 family of operational amplifiers is manufactured using TI's *e-trim* operation amplifier technology. This *e-trim* operational amplifier technology is a TI proprietary method of trimming internal device parameters during either wafer probing or final testing. Each amplifier input offset voltage and input offset voltage drift is trimmed in production, thereby minimizing errors associated with input offset voltage and input offset voltage drift. When trimming input offset voltage drift, the systematic or linear drift error on each device is trimmed to zero. Figure 7-1 illustrates this concept.

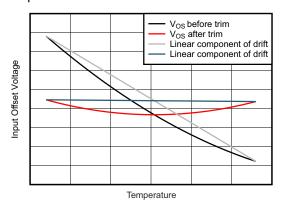


Figure 7-1. Input Offset Before and After Drift Trim

A common method of specifying input offset voltage drift is the *box method*. The box method estimates a maximum input offset drift by bounding an offset voltage versus temperature curve with a box and using the corners of this bounding box to determine the drift. The slope of the line connecting the diagonal corners of the box corresponds to the input offset voltage drift. Figure 7-2 illustrates the box method concept. The box method works particularly well when the input offset drift is dominated by the linear component of drift, but because the OPA191 family uses Tl's e-trim operational amplifier technology to remove the linear component input offset voltage drift, the box method is not a particularly useful method of accurately performing an error analysis. Shown in Figure 7-2 are 30 typical units of OPAx191 with the box method superimposed for illustrative purposes. The boundaries of the box are determined by the specified temperature range along the x-axis and the maximum specified input offset voltage across that same temperature range along the y-axis. Using the box method predicts an input offset voltage drift of 0.9  $\mu$ V/°C. As shown in Figure 7-2, the slopes of the actual input offset voltage versus temperature are much less than that predicted by the box method. The box method predicts a pessimistic value for the maximum input offset voltage drift and is not recommended when performing an error analysis.

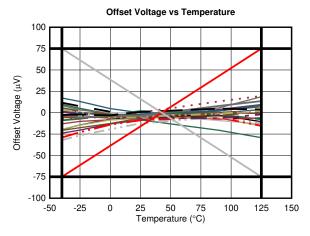


Figure 7-2. The Box Method

Instead of the box method, a convenient way to illustrate input offset drift is to compute the slopes of the input offset voltage versus temperature curve. This is the same as computing the input offset drift at each point along the input offset voltage versus temperature curve. The results for the OPAx191 family are illustrated in Figure 7-3.

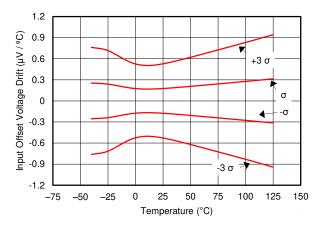


Figure 7-3. Input Offset Voltage Drift vs Temperature (SOIC Package)

As illustrated in Figure 7-3, the input offset drift is typically less than  $\pm 0.3~\mu\text{V}/^{\circ}\text{C}$  over the range from  $-40^{\circ}\text{C}$  to  $\pm 125^{\circ}\text{C}$ . When performing an error analysis over the full specified temperature range, use the typical and maximum values for input offset voltage drift as described in the *Electrical Characteristics* tables. If a reduced temperature range is applicable, use the information illustrated in Figure 7-3 when performing an error analysis. To determine the change in input offset voltage, use Equation 1:

$$\Delta V_{OS} = \Delta T \times dV_{OS}/dT \tag{1}$$

#### where

- ΔV<sub>OS</sub> = Change in input offset voltage
- ΔT = Change in temperature
- dV<sub>OS</sub>/dT = Input offset voltage drift

For example, determine the amount of OPA191ID input offset voltage change over the temperature range of 25°C to 75°C for 1  $\sigma$  (68%) of the units. As shown in Figure 7-3, the input offset drift is typically 0.25  $\mu$ V/°C. This input offset drift results in a typical input offset voltage change of (75°C – 25°C) × 0.25  $\mu$ V/°C = 12.5  $\mu$ V.

For 3  $\sigma$  (99.7%) of the units, Figure 7-3 shows a typical input offset drift of approximately 0.75  $\mu$ V/°C. This input offset drift results in a typical input offset voltage change of (75°C – 25°C) × 0.75  $\mu$ V/°C = 37.5  $\mu$ V.



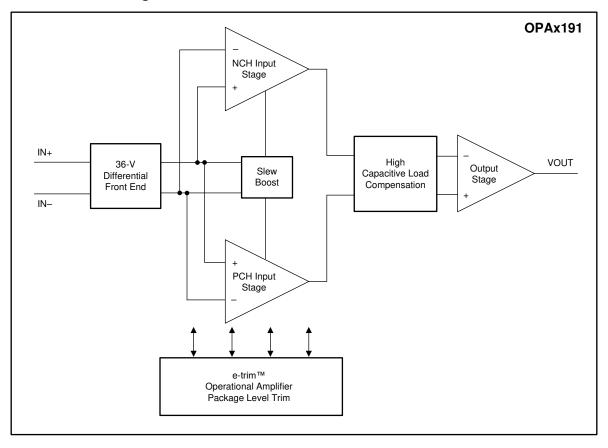
# 8 Detailed Description

#### 8.1 Overview

The OPAx191 family of e-trim operational amplifiers use a method of package-level trim for offset and offset temperature drift implemented during the final steps of manufacturing after the plastic molding process. This method minimizes the influence of inherent input transistor mismatch, as well as errors induced during package molding. The trim communication occurs on the output pin of the standard pinout, and after the trim points are set, further communication to the trim structure is permanently disabled. Section 8.2 shows the simplified diagram of the OPAx191.

Unlike previous e-trim operational amplifiers, the OPAx191 uses a patented two-temperature trim architecture to achieve a very low offset voltage and low voltage offset drift over the full specified temperature range. This level of precision performance at wide supply voltages makes these amplifiers useful for high-impedance industrial sensors, filters, and high-voltage data acquisition.

# 8.2 Functional Block Diagram



#### 8.3 Feature Description

## **8.3.1 Input Protection Circuitry**

The OPAx191 uses a unique input architecture to eliminate the need for input protection diodes but still provides robust input protection under transient conditions. Conventional input diode protection schemes shown in Figure 8-1 can be activated by fast transient step responses and can introduce signal distortion and settling time delays because of alternate current paths, as shown in Figure 8-2. For low-gain circuits, these fast-ramping input signals forward-bias back-to-back diodes that cause an increase in input current, resulting in extended settling time.

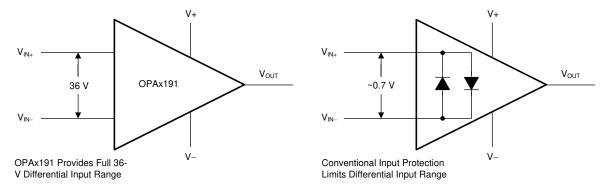


Figure 8-1. OPA191 Input Protection Does Not Limit Differential Input Capability

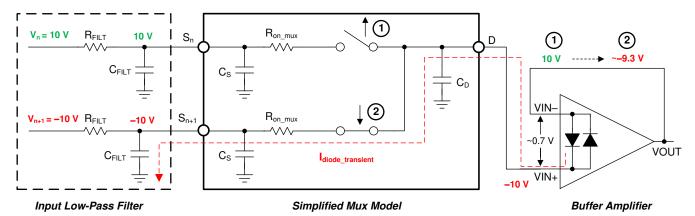


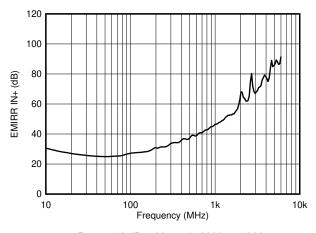
Figure 8-2. Back-to-Back Diodes Create Settling Issues

The OPAx191 family of operational amplifiers provides a true high-impedance differential input capability for high-voltage applications. This patented input protection architecture does not introduce additional signal distortion or delayed settling time, making the device an optimal op amp for multichannel, high-switched, input applications. The OPAx191 tolerates a maximum differential swing (voltage between inverting and noninverting pins of the op amp) of up to 36 V, making the device an excellent choice for use as a comparator or in applications with fast-ramping input signals such as multiplexed data-acquisition systems (see Figure 9-4).



#### 8.3.2 EMI Rejection

The OPAx191 uses integrated electromagnetic interference (EMI) filtering to reduce the effects of EMI from sources such as wireless communications and densely-populated boards with a mix of analog signal chain and digital components. EMI immunity can be improved with circuit design techniques; the OPAx191 benefits from these design improvements. Texas Instruments has developed the ability to accurately measure and quantify the immunity of an operational amplifier over a broad frequency spectrum extending from 10 MHz to 6 GHz. Figure 8-3 shows the results of this testing on the OPAx191. Table 8-1 shows the EMIRR IN+ values for the OPAx191 at particular frequencies commonly encountered in real-world applications. Applications listed in Table 8-1 may be centered on or operated near the particular frequency shown. Detailed information can also be found in the *EMI Rejection Ratio of Operational Amplifiers* application report, available for download from www.ti.com.



 $P_{RF} = -10 \text{ dBm}, V_S = \pm 15 \text{ V}, V_{CM} = 0 \text{ V}$ 

Figure 8-3. EMIRR Testing

Table 8-1. OPA191 EMIRR IN+ For Frequencies of Interest

FREQUENCY	APPLICATION OR ALLOCATION	EMIRR IN+
400 MHz	Mobile radio, mobile satellite, space operation, weather, radar, ultra-high frequency (UHF) applications	36 dB
900 MHz	Global system for mobile communications (GSM) applications, radio communication, navigation, GPS (to 1.6 GHz), GSM, aeronautical mobile, UHF applications	45 dB
1.8 GHz	GSM applications, mobile personal communications, broadband, satellite, L-band (1 GHz to 2 GHz)	57 dB
2.4 GHz	802.11b, 802.11g, 802.11n, Bluetooth®, mobile personal communications, industrial, scientific and medical (ISM) radio band, amateur radio and satellite, S-band (2 GHz to 4 GHz)	62 dB
3.6 GHz	Radiolocation, aero communication and navigation, satellite, mobile, S-band	76 dB
5.0 GHz	802.11a, 802.11n, aero communication and navigation, mobile communication, space and satellite operation, C-band (4 GHz to 8 GHz)	86 dB

#### 8.3.3 Phase Reversal Protection

The OPAx191 family has internal phase-reversal protection. Many op amps exhibit phase reversal when the input is driven beyond the linear common-mode range. This condition is most often encountered in noninverting circuits when the input is driven beyond the specified common-mode voltage range, causing the output to reverse into the opposite rail. The OPAx191 is a rail-to-rail input op amp, and therefore the common-mode range can extend up to the rails. Input signals beyond the rails do not cause phase reversal; instead, the output limits into the appropriate rail. This performance is shown in Figure 8-4.

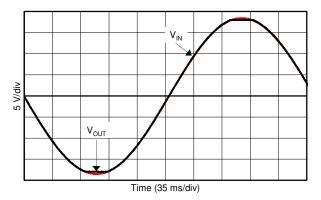


Figure 8-4. No Phase Reversal

#### 8.3.4 Thermal Protection

The internal power dissipation of any amplifier causes the internal (junction) temperature to rise. This phenomenon is called *self heating*. The OPAx191 has a thermal protection feature that prevents damage from self heating.

This thermal protection works by monitoring the temperature of the output stage and turning off the op amp output drive for temperatures above approximately 180°C. Thermal protection forces the output to a high-impedance state. The OPAx191 is also designed with approximately 30°C of thermal hysteresis. Thermal hysteresis prevents the output stage from cycling in and out of the high-impedance state. The OPAx191 returns to normal operation when the output stage temperature falls below approximately 150°C.

The absolute maximum junction temperature of the OPAx191 is 150°C. Exceeding the limits shown in *Section 6.1* may cause damage to the device. Thermal protection triggers at 180°C because of unit-to-unit variance, but does not interfere with device operation up to the absolute maximum ratings. This thermal protection is not designed to prevent this device from exceeding absolute maximum ratings, but rather from excessive thermal overload.

#### 8.3.5 Capacitive Load and Stability

The OPAx191 features a patented output stage capable of driving large capacitive loads, and in a unity-gain configuration, directly drives up to 1 nF of pure capacitive load. Increasing the gain enhances the ability of the amplifier to drive greater capacitive loads; see Figure 8-5. The particular op amp circuit configuration, layout, gain, and output loading are some of the factors to consider when establishing whether an amplifier will be stable in operation.

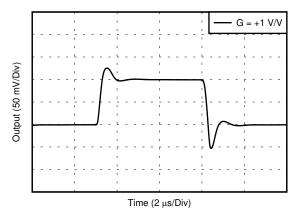


Figure 8-5. Transient Response with a Purely Capacitive Load of 1 nF

Like many low-power amplifiers, some ringing can occur even with capacitive loads less than 100 pF. In unity-gain configurations with no or very light dc loads, place an RC snubber circuit at the OPAx191 output to reduce any possibility of ringing in lightly-loaded applications. Figure 8-6 illustrates the recommended RC snubber circuit.

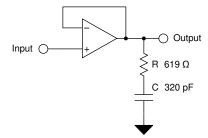


Figure 8-6. RC Snubber Circuit for Lightly-Loaded Applications in Unity Gain

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For additional drive capability in unity-gain configurations, improve capacitive load drive by inserting a small, 10-Ω to 20-Ω resistor ( $R_{ISO}$ ) in series with the output, as shown in Figure 8-7. This resistor significantly reduces ringing while maintaining dc performance for purely capacitive loads. However, if there is a resistive load in parallel with the capacitive load, a voltage divider is created, introducing a gain error at the output and slightly reducing the output swing. The error introduced is proportional to the ratio R<sub>ISO</sub> / R<sub>L</sub>, and is generally negligible at low output levels. A high capacitive load drive makes the OPA191 a great choice for applications such as reference buffers, MOSFET gate drives, and cable-shield drives. The circuit shown in Figure 8-7 uses RISO to stabilize the output of an op amp. R<sub>ISO</sub> modifies the open-loop gain of the system for increased phase margin. Results using the OPA191 are summarized in Table 8-2. For additional information on techniques to optimize and design using this circuit, TI Precision Design TIPD128, Capacitive Load Drive Verified Reference Design Using an Isolation Resistor, details complete design goals, simulation, and test results.

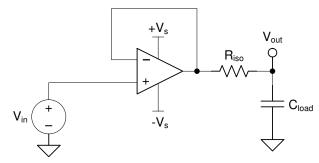


Figure 8-7. Extending Capacitive Load Drive With the OPA191

Table 8-2. OPA191 Capacitive Load Drive Solution Using Isolation Resistor Comparison of Calculated and Measured Results

***************************************									
PARAMETER	VALUE								
Capacitive Load	100 pF	100	0 pF	0.01 μF		0.1 μF		1 μF	
Phase Margin	45°	45°	60°	45°	60°	45°	60°	45°	60°
R <sub>ISO</sub> (Ω)	280	113	432	68	210	17.8	53.6	3.6	10
Measured Overshoot (%)	23	23	8	23	8	23	8	23	8

#### 8.3.6 Common-Mode Voltage Range

The OPAx191 is a 36-V, true rail-to-rail input operational amplifier with an input common-mode range that extends 100 mV beyond either supply rail. This wide range is achieved with paralleled complementary N-channel and P-channel differential input pairs, as shown in Figure 8-8. The N-channel pair is active for input voltages close to the positive rail, typically (V+) - 3 V to 100 mV above the positive supply. The P-channel pair is active for inputs from 100 mV below the negative supply to approximately (V+) - 1.5 V. There is a small transition region, typically (V+) - 3 V to (V+) - 1.5 V in which both input pairs are active. This transition region varies modestly with process variation. Within this region PSRR, CMRR, offset voltage, offset drift, noise, and THD performance are degraded compared to operation outside this region.

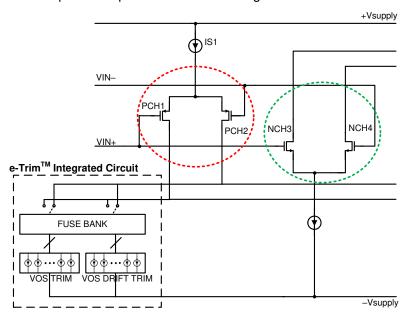


Figure 8-8. Rail-to-Rail Input Stage

To achieve the best performance for two-stage rail-to-rail input amplifiers, avoid the transition region when possible. The OPAx191 uses a precision trim for both the N-channel and P-channel regions. This technique enables significantly lower levels of offset than previous-generation devices, causing variance in the transition region of the input stages to appear exaggerated relative to offset over the full common-mode range, as shown in Figure 8-9.

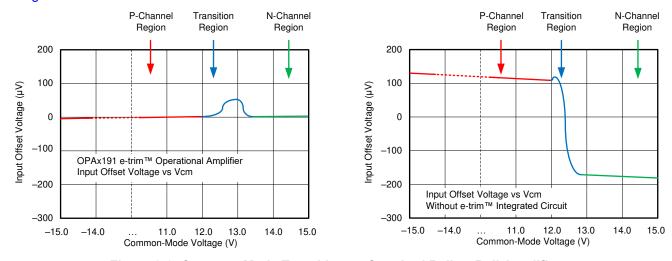


Figure 8-9. Common-Mode Transition vs Standard Rail-to-Rail Amplifiers

#### 8.3.7 Electrical Overstress

Designers often ask questions about the capability of an operational amplifier to withstand electrical overstress (EOS). These questions tend to focus on the device inputs, but may involve the supply voltage pins or even the output pin. Each of these different pin functions have electrical stress limits determined by the voltage breakdown characteristics of the particular semiconductor fabrication process and specific circuits connected to the pin. Additionally, internal electrostatic discharge (ESD) protection is built into these circuits to protect them from accidental ESD events both before and during product assembly.

Having a good understanding of this basic ESD circuitry and its relevance to an electrical overstress event is helpful. See Figure 8-10 for an illustration of the ESD circuits contained in the OPAx191 (indicated by the dashed line area). The ESD protection circuitry involves several current-steering diodes connected from the input and output pins and routed back to the internal power-supply lines, where the diodes meet at an absorption device or the power-supply ESD cell, internal to the operational amplifier. This protection circuitry is intended to remain inactive during normal circuit operation.

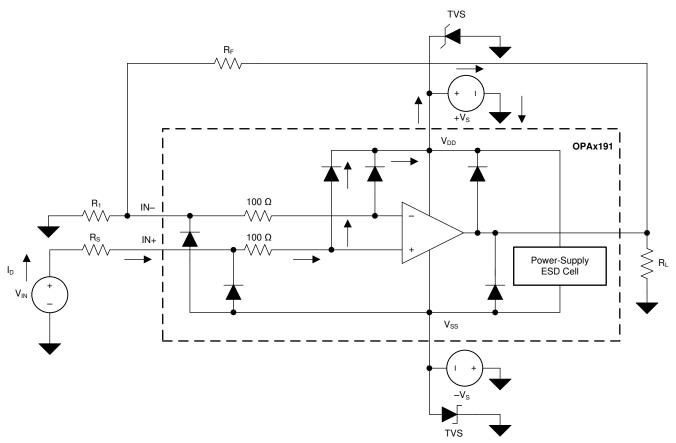


Figure 8-10. Equivalent Internal ESD Circuitry Relative to a Typical Circuit Application



An ESD event is very high voltage for a very short duration (for example, 1 kV for 100 ns); whereas, an EOS event is lower voltage for a longer duration (for example, 50 V for 100 ms). The ESD diodes are designed for out-of-circuit ESD protection (that is, during assembly, test, and storage of the device before being soldered to the PCB). During an ESD event, the ESD signal is passed through the ESD steering diodes to an absorption circuit labeled ESD power-supply circuit. The ESD absorption circuit clamps the supplies to a safe level.

Although this behavior is necessary for out-of-circuit protection, excessive current and damage is caused if activated in-circuit. A transient voltage suppressor (TVS) can be used to prevent against damage caused by turning on the ESD absorption circuit during an in-circuit ESD event. Using the appropriate current limiting resistors and TVS diodes allows for the use of device ESD diodes to protect against EOS events.

#### 8.3.8 Overload Recovery

Overload recovery is defined as the time required for the op amp output to recover from a saturated state to a linear state. The output devices of the op amp enter a saturation region when the output voltage exceeds the rated operating voltage, either due to the high input voltage or the high gain. After the device enters the saturation region, the charge carriers in the output devices require time to return back to the linear state. After the charge carriers return back to the linear state, the device begins to slew at the specified slew rate. Thus, the propagation delay in case of an overload condition is the sum of the overload recovery time and the slew time.

#### 8.4 Device Functional Modes

The OPAx191 has a single functional mode and is operational when the power-supply voltage is greater than 4.5 V ( $\pm 2.25 \text{ V}$ ). The maximum power supply voltage for the OPAx191 is 36 V ( $\pm 18 \text{ V}$ ).

# 9 Application and Implementation

#### **Note**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

## 9.1 Application Information

The OPAx191 family offers outstanding dc precision and ac performance. These devices operate up to 36-V supply rails and offer true rail-to-rail input/output, ultralow offset voltage and offset voltage drift, as well as 2-MHz bandwidth and high capacitive load drive. These features make the OPAx191 a robust, high-performance operational amplifier for high-voltage industrial applications.

## 9.2 Typical Applications

#### 9.2.1 Low-side Current Measurement

Figure 9-1 shows the OPA191 configured in a low-side current sensing application. For a full analysis of the circuit shown in Figure 9-1 including theory, calculations, simulations, and measured data, see TI Precision Design TIPD129, 0-A to 1-A Single-Supply Low-Side Current-Sensing Solution.

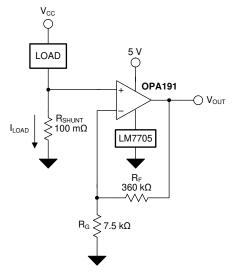


Figure 9-1. OPA191 in a Low-Side, Current-Sensing Application

#### 9.2.1.1 Design Requirements

The design requirements for this design are:

Load current: 0 A to 1 AOutput voltage: 4.9 V

Maximum shunt voltage: 100 mV



#### 9.2.1.2 Detailed Design Procedure

The transfer function of the circuit in Figure 9-1 is given in Equation 2

$$V_{OUT} = I_{LOAD} \times R_{SHUNT} \times Gain$$
 (2)

The load current ( $I_{LOAD}$ ) produces a voltage drop across the shunt resistor ( $R_{SHUNT}$ ). The load current is set from 0 A to 1 A. To keep the shunt voltage below 100 mV at maximum load current, the largest shunt resistor is defined using Equation 3.

$$R_{SHUNT} = \frac{V_{SHUNT\_MAX}}{I_{LOAD\_MAX}} = \frac{100mV}{1A} = 100m\Omega$$
(3)

Using Equation 3,  $R_{SHUNT}$  is calculated to be 100 m $\Omega$ . The voltage drop produced by  $I_{LOAD}$  and  $R_{SHUNT}$  is amplified by the OPA191 to produce an output voltage of 0 V to 4.9 V. The gain needed by the OPA191 to produce the necessary output voltage is calculated using Equation 4:

$$Gain = \frac{\left(V_{OUT\_MAX} - V_{OUT\_MIN}\right)}{\left(V_{IN\_MAX} - V_{IN\_MIN}\right)}$$
(4)

Using Equation 4, the required gain is calculated to be 49 V/V, which is set with resistors  $R_F$  and  $R_G$ . Equation 5 is used to size the resistors,  $R_F$  and  $R_G$ , to set the gain of the OPA191 to 49 V/V.

$$Gain = 1 + \frac{(R_F)}{(R_G)}$$
(5)

Choosing  $R_F$  as 360 k $\Omega$ ,  $R_G$  is calculated to be 7.5 k $\Omega$ .  $R_F$  and  $R_G$  were chosen as 360 k $\Omega$  and 7.5 k $\Omega$  because they are standard value resistors that create a 49:1 ratio. Other resistors that create a 49:1 ratio can also be used. Figure 2 shows the measured transfer function of the circuit shown in Figure 9-1.

#### 9.2.1.3 Application Curves

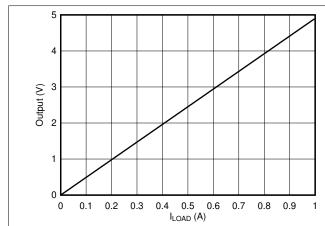


Figure 9-2. Low-Side, Current-Sense, Transfer Function

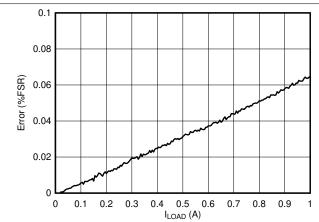


Figure 9-3. Low-Side, Current-Sense, Full-Scale Error

#### 9.2.2 16-Bit Precision Multiplexed Data-Acquisition System

Figure 9-4 shows a 16-bit, differential, 4-channel, multiplexed, data-acquisition system. This example is typical in industrial applications that require low distortion and a high-voltage differential input. The circuit uses the ADS8864, a 16-bit, 400-kSPS successive-approximation-resistor (SAR), analog-to-digital converter (ADC), along with a precision, high-voltage, signal-conditioning front-end, and a 4-channel differential multiplexer (mux). This application example shows the process for optimizing the precision, high-voltage, front-end drive circuit using the OPA191 and OPA140 to achieve excellent dynamic performance and linearity with the ADS8864. The full design can be found in TI Precision Design TIPD151, 16-Bit, 400-kSPS, Four-Channel MUX Data Acquisition System for High-Voltage Inputs.

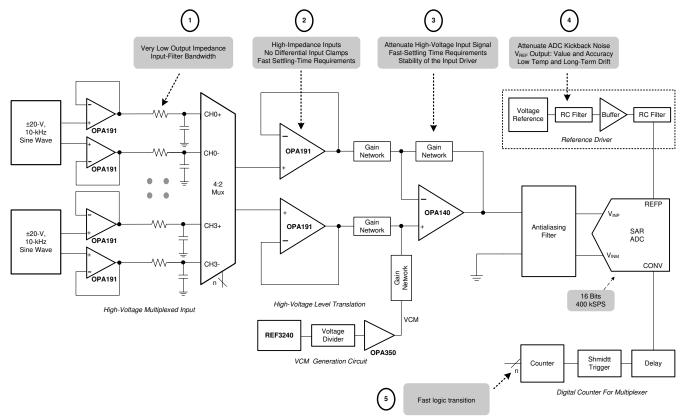


Figure 9-4. OPA191 in 16-Bit, 400-kSPS, 4-Channel, Multiplexed Data Acquisition System for High-Voltage Inputs With Lowest Distortion

#### 9.2.2.1 Design Requirements

The primary objective is to design a ±20-V, differential, 4-channel, multiplexed, data acquisition system with lowest distortion using the 16-bit ADS8864 at a throughput of 400 kSPS for a 10-kHz, full-scale, pure sine-wave input. The design requirements for this block design are:

- System supply voltage: ±15 V
- ADC supply voltage: 3.3 V
- ADC sampling rate: 400 kSPS
- ADC reference voltage (REFP): 4.096 V
- System input signal: A high-voltage differential input signal with a peak amplitude of 10 V and frequency (f<sub>IN</sub>) of 10 kHz are applied to each differential input of the mux.

#### 9.2.2.2 Detailed Design Procedure

The purpose of this application example is to design an optimal, high-voltage, multiplexed, data-acquisition system for highest system linearity and fast settling. The overall system block diagram is shown in Figure 9-4. The circuit is a multichannel, data-acquisition, signal chain consisting of an input low-pass filter, multiplexer (mux), mux output buffer, attenuating SAR ADC driver, digital counter for the mux, and the reference driver. The architecture allows fast sampling of multiple channels using a single ADC, providing a low-cost solution. The two primary design considerations to maximize the performance of a precision, multiplexed, data-acquisition system are the mux input analog front-end and the high-voltage, level translation, SAR ADC driver design. However, carefully design each analog circuit block based on the ADC performance specifications in order to achieve the fastest settling at 16-bit resolution and lowest distortion system. Figure 9-4 includes the most important specifications for each individual analog block.

This design systematically approaches each analog circuit block to achieve a 16-bit settling for a full-scale input stage voltage and linearity for a 10-kHz sinusoidal input signal at each input channel. The first step in the design is to understand the requirement for an extremely-low-impedance input-filter design for the mux. This understanding helps in the decision of an appropriate input filter and selection of a mux to meet the system settling requirements. The next important step is the design of the attenuating analog front-end (AFE) used to level translate the high-voltage input signal to a low-voltage ADC input while maintaining the amplifier stability. Then, the next step is to design a digital interface to switch the mux input channels with minimum delay. The final design challenge is to design a high-precision, reference-driver circuit that provides the required REFP reference voltage with low offset, drift, and noise contributions.

#### 9.2.3 Slew Rate Limit for Input Protection

In control systems for valves or motors, abrupt changes in voltages or currents can cause mechanical damages. By controlling the slew rate of the command voltages into the drive circuits, the load voltages ramps up and down at a safe rate. For symmetrical slew-rate applications (positive slew rate equals negative slew rate), one additional op amp provides slew-rate control for a given analog gain stage. The unique input protection and high output current and slew rate of the OPAx191 make the device an optimal amplifier to achieve slew rate control for both dual-supply and single-supply systems. Figure 9-5 shows the OPA191 in a slew-rate limit design. For step-by-step design procedure, circuit schematics, bill of materials, PCB files, simulation results, and test results, refer to TI Precision Design TIPD140, Single Op-Amp Slew Rate Limiter..

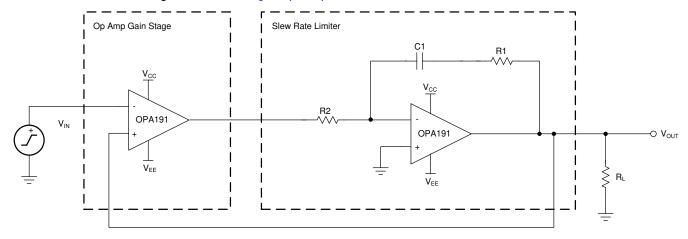


Figure 9-5. Slew Rate Limiter Uses One Op Amp

# 10 Power Supply Recommendations

The OPAx191 is specified for operation from 4.5 V to 36 V ( $\pm 2.25$  V to  $\pm 18$  V); many specifications apply from – 40°C to  $\pm 125$ °C. Parameters that can exhibit significant variance with regard to operating voltage or temperature are presented in Section 6.9.

#### **CAUTION**

Supply voltages larger than 40 V can permanently damage the device; see Section 6.1.

Place  $0.1-\mu F$  bypass capacitors close to the power-supply pins to reduce errors coupling in from noisy or high-impedance power supplies. For more detailed information on bypass capacitor placement, see Section 11.

# 11 Layout

## 11.1 Layout Guidelines

For best operational performance of the device, use good PCB layout practices, including:

- Connect low-ESR, 0.1-µF ceramic bypass capacitors between each supply pin and ground, placed as close to the device as possible. A single bypass capacitor from V+ to ground is applicable for single-supply applications.
  - Noise can propagate into analog circuitry through the power pins of the circuit as a whole and op amp itself. Bypass capacitors are used to reduce the coupled noise by providing low-impedance power sources local to the analog circuitry.
- Make sure to physically separate digital and analog grounds paying attention to the flow of the ground current. Separate grounding for analog and digital portions of circuitry is one of the simplest and mosteffective methods of noise suppression. One or more layers on multilayer PCBs are usually devoted to ground planes. A ground plane helps distribute heat and reduces EMI noise pickup. For more detailed information, refer to Circuit Board Layout Techniques.
- In order to reduce parasitic coupling, run the input traces as far away from the supply or output traces as possible. If these traces cannot be kept separate, crossing the sensitive trace perpendicular is much better as opposed to in parallel with the noisy trace.
- Place the external components as close to the device as possible. As shown in Figure 11-2, keeping RF and RG close to the inverting input minimizes parasitic capacitance.
- Keep the length of input traces as short as possible. Always remember that the input traces are the most sensitive part of the circuit.
- Consider a driven, low-impedance guard ring around the critical traces. A guard ring can significantly reduce leakage currents from nearby traces that are at different potentials.
- Clean the PCB following board assembly for best performance.
- Any precision integrated circuit may experience performance shifts due to moisture ingress into the plastic
  package. After any aqueous PCB cleaning process, bake the PCB assembly to remove moisture introduced
  into the device packaging during the cleaning process. A low-temperature, post-cleaning bake at 85°C for 30
  minutes is sufficient for most circumstances.

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# 11.2 Layout Example

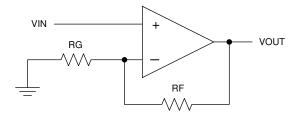


Figure 11-1. Schematic Representation

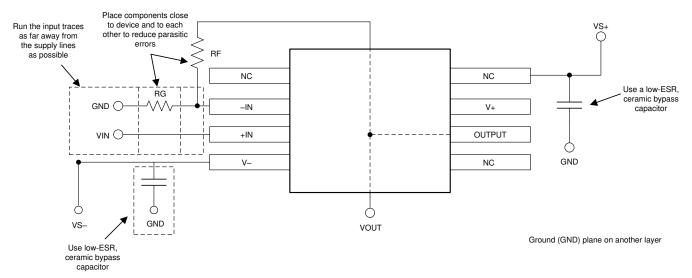


Figure 11-2. Operational Amplifier Board Layout for Noninverting Configuration

# 12 Device and Documentation Support

# 12.1 Device Support

## 12.1.1 Development Support

## 12.1.1.1 TINA-TI™ SImulation Software (Free Download)

TINA™ is a simple, powerful, and easy-to-use circuit simulation program based on a SPICE engine. TINA-TI simulation software is a free, fully-functional version of the TINA software, preloaded with a library of macro models in addition to a range of both passive and active models. TINA-TI simulation software provides all the conventional dc, transient, and frequency domain analysis of SPICE, as well as additional design capabilities.

Available as a free download from the Analog eLab Design Center, TINA-TI simulation software offers extensive post-processing capability that allows users to format results in a variety of ways. Virtual instruments offer the ability to select input waveforms and probe circuit nodes, voltages, and waveforms, creating a dynamic quick-start tool.

#### Note

These files require that either the TINA software (from DesignSoft<sup>™</sup>) or TINA-TI software be installed. Download the free TINA-TI software from the TINA-TI folder at http://www.ti.com/tool/tina-ti.

### 12.1.1.2 TI Precision Designs

TI Precision Designs, available online at <a href="http://www.ti.com/ww/en/analog/precision-designs/">http://www.ti.com/ww/en/analog/precision-designs/</a>, are analog solutions created by TI's precision analog applications experts and offer the theory of operation, component selection, simulation, complete PCB schematic and layout, bill of materials, and measured performance of many useful circuits.

# 12.2 Documentation Support

### 12.2.1 Related Documentation

- Texas Instruments, Circuit Board Layout Techniques
- Texas Instruments, Op Amps for Everyone design reference

## 12.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 12.4 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.



#### 12.5 Trademarks

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## 12.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

# 12.7 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

# 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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# **PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
OPA191ID	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	OPA191
OPA191ID.B	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	OPA191
OPA191IDBVR	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZAMV
OPA191IDBVR.B	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZAMV
OPA191IDBVRG4	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZAMV
OPA191IDBVRG4.B	Active	Production	SOT-23 (DBV)   5	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZAMV
OPA191IDBVT	Active	Production	SOT-23 (DBV)   5	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZAMV
OPA191IDBVT.B	Active	Production	SOT-23 (DBV)   5	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZAMV
OPA191IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZANV
OPA191IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZANV
OPA191IDGKRG4	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZANV
OPA191IDGKRG4.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZANV
OPA191IDGKT	Active	Production	VSSOP (DGK)   8	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZANV
OPA191IDGKT.B	Active	Production	VSSOP (DGK)   8	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	ZANV
OPA191IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	OPA191
OPA191IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	OPA191
OPA191IDRG4	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	OPA191
OPA191IDRG4.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	OPA191
OPA2191ID	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA2191ID.B	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA2191IDGKR	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA2191IDGKR.B	Active	Production	VSSOP (DGK)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA2191IDGKT	Active	Production	VSSOP (DGK)   8	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA2191IDGKT.B	Active	Production	VSSOP (DGK)   8	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA2191IDGKTG4	Active	Production	VSSOP (DGK)   8	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA2191IDGKTG4.B	Active	Production	VSSOP (DGK)   8	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA2191IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA2191IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA2191IDRG4	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191





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Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking
						(4)	(5)		
OPA2191IDRG4.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2191
OPA4191ID	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	OPA4191
OPA4191ID.B	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	OPA4191
OPA4191IDG4	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	OPA4191
OPA4191IDG4.B	Active	Production	SOIC (D)   14	50   TUBE	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	OPA4191
OPA4191IDR	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	OPA4191
OPA4191IDR.B	Active	Production	SOIC (D)   14	2500   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 125	OPA4191
OPA4191IPWR	Active	Production	TSSOP (PW)   14	2000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	OPA4191
OPA4191IPWR.B	Active	Production	TSSOP (PW)   14	2000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	OPA4191
OPA4191IPWT	Active	Production	TSSOP (PW)   14	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	OPA4191
OPA4191IPWT.B	Active	Production	TSSOP (PW)   14	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	OPA4191
OPA4191IRUMR	Active	Production	WQFN (RUM)   16	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	OPA 4191
OPA4191IRUMR.B	Active	Production	WQFN (RUM)   16	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	OPA 4191
OPA4191IRUMRG4	Active	Production	WQFN (RUM)   16	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	OPA 4191
OPA4191IRUMRG4.B	Active	Production	WQFN (RUM)   16	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	OPA 4191
OPA4191IRUMT	Active	Production	WQFN (RUM)   16	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	OPA 4191
OPA4191IRUMT.B	Active	Production	WQFN (RUM)   16	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 125	OPA 4191

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.



# PACKAGE OPTION ADDENDUM

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(5) MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

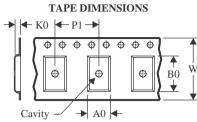
In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



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# TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
OPA191IDBVR	SOT-23	DBV	5	3000	180.0	8.4	3.23	3.17	1.37	4.0	8.0	Q3
OPA191IDBVRG4	SOT-23	DBV	5	3000	180.0	8.4	3.23	3.17	1.37	4.0	8.0	Q3
OPA191IDBVT	SOT-23	DBV	5	250	180.0	8.4	3.23	3.17	1.37	4.0	8.0	Q3
OPA191IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
OPA191IDGKRG4	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
OPA191IDGKT	VSSOP	DGK	8	250	177.8	12.4	5.3	3.4	1.4	8.0	12.0	Q1
OPA191IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
OPA191IDRG4	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
OPA2191IDGKR	VSSOP	DGK	8	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
OPA2191IDGKT	VSSOP	DGK	8	250	180.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
OPA2191IDGKTG4	VSSOP	DGK	8	250	180.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
OPA2191IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
OPA2191IDRG4	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
OPA4191IDR	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1
OPA4191IPWR	TSSOP	PW	14	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
OPA4191IPWT	TSSOP	PW	14	250	180.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1



# **PACKAGE MATERIALS INFORMATION**

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Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
OPA4191IRUMR	WQFN	RUM	16	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
OPA4191IRUMRG4	WQFN	RUM	16	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
OPA4191IRUMT	WQFN	RUM	16	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2



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\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
OPA191IDBVR	SOT-23	DBV	5	3000	213.0	191.0	35.0
OPA191IDBVRG4	SOT-23	DBV	5	3000	213.0	191.0	35.0
OPA191IDBVT	SOT-23	DBV	5	250	223.0	270.0	35.0
OPA191IDGKR	VSSOP	DGK	8	2500	346.0	346.0	29.0
OPA191IDGKRG4	VSSOP	DGK	8	2500	346.0	346.0	29.0
OPA191IDGKT	VSSOP	DGK	8	250	213.0	191.0	35.0
OPA191IDR	SOIC	D	8	2500	353.0	353.0	32.0
OPA191IDRG4	SOIC	D	8	2500	353.0	353.0	32.0
OPA2191IDGKR	VSSOP	DGK	8	2500	353.0	353.0	32.0
OPA2191IDGKT	VSSOP	DGK	8	250	213.0	191.0	35.0
OPA2191IDGKTG4	VSSOP	DGK	8	250	213.0	191.0	35.0
OPA2191IDR	SOIC	D	8	2500	353.0	353.0	32.0
OPA2191IDRG4	SOIC	D	8	2500	353.0	353.0	32.0
OPA4191IDR	SOIC	D	14	2500	353.0	353.0	32.0
OPA4191IPWR	TSSOP	PW	14	2000	353.0	353.0	32.0
OPA4191IPWT	TSSOP	PW	14	250	213.0	191.0	35.0
OPA4191IRUMR	WQFN	RUM	16	3000	367.0	367.0	35.0
OPA4191IRUMRG4	WQFN	RUM	16	3000	367.0	367.0	35.0



# PACKAGE MATERIALS INFORMATION

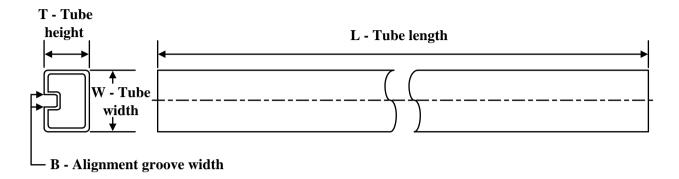
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Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
OPA4191IRUMT	WQFN	RUM	16	250	210.0	185.0	35.0

# **PACKAGE MATERIALS INFORMATION**

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# **TUBE**



\*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
OPA191ID	D	SOIC	8	75	506.6	8	3940	4.32
OPA191ID.B	D	SOIC	8	75	506.6	8	3940	4.32
OPA2191ID	D	SOIC	8	75	506.6	8	3940	4.32
OPA2191ID.B	D	SOIC	8	75	506.6	8	3940	4.32
OPA4191ID	D	SOIC	14	50	506.6	8	3940	4.32
OPA4191ID.B	D	SOIC	14	50	506.6	8	3940	4.32
OPA4191IDG4	D	SOIC	14	50	506.6	8	3940	4.32
OPA4191IDG4.B	D	SOIC	14	50	506.6	8	3940	4.32



SMALL OUTLINE TRANSISTOR



## NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
  2. This drawing is subject to change without notice.
  3. Reference JEDEC MO-178.

- 4. Body dimensions do not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.25 mm per side.
- 5. Support pin may differ or may not be present.



SMALL OUTLINE TRANSISTOR



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SMALL OUTLINE TRANSISTOR



- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.







## NOTES:

PowerPAD is a trademark of Texas Instruments.

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187.





- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.
- 9. Size of metal pad may vary due to creepage requirement.





- 11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 12. Board assembly site may have different recommendations for stencil design.







## NOTES:

- 1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm, per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.43 mm, per side.
- 5. Reference JEDEC registration MS-012, variation AB.





NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.





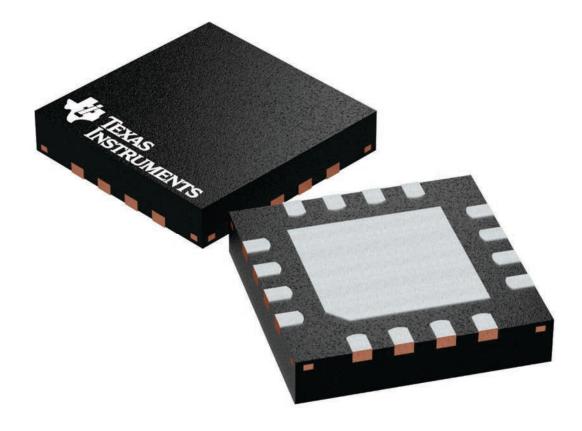
- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



4 x 4, 0.65 mm pitch

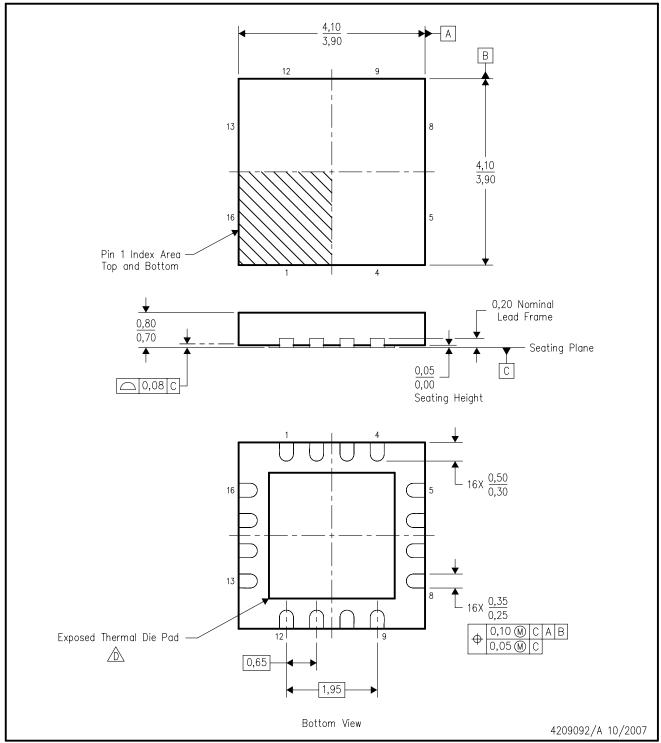
PLASTIC QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



# RUM (S-PQFP-N16)

# PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. QFN (Quad Flatpack No-Lead) package configuration.

The package thermal pad must be soldered to the board for thermal and mechanical performance.

See the Product Data Sheet for details regarding the exposed thermal pad dimensions.

E. Package complies to JEDEC MO-220 variation WGGC-3.



4209093-2/F 09/15

# RUM (S-PWQFN-N16)

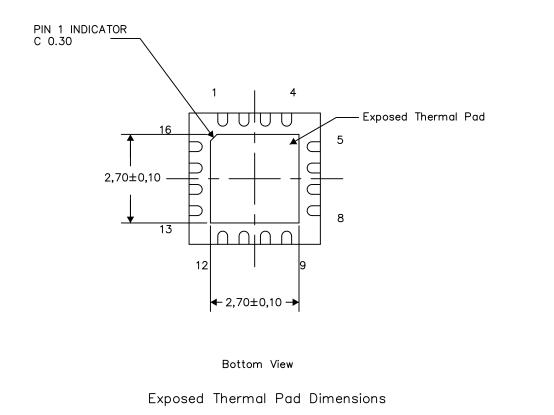
PLASTIC QUAD FLATPACK NO-LEAD

## THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No—Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



NOTES: All linear dimensions are in millimeters





# NOTES:

- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.





NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.





- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.







## NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-153.





NOTES: (continued)

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