

## LMH6611/LMH6612 Single Supply 345 MHz Rail-to-Rail Output Amplifiers

Check for Samples: [LMH6611](#), [LMH6612](#)

### FEATURES

- $V_S = 5V$ ,  $R_L = 1\text{ k}\Omega$ ,  $T_A = 25^\circ\text{C}$  and  $A_V = +1$ , Unless Otherwise Specified.
- Operating Voltage Range 2.7V to 11V
- Supply Current Per Channel 3.2 mA
- Small Signal Bandwidth 345 MHz
- Open Loop Gain 103 dB
- Input Offset Voltage (Limit at  $25^\circ\text{C}$ )  $\pm 1.5\text{ mV}$
- Slew Rate 460 V/ $\mu\text{s}$
- 0.1 dB Bandwidth 45 MHz
- Settling Time to 0.1% 67 ns
- Settling Time to 0.01% 100 ns
- SFDR ( $f = 100\text{ kHz}$ ,  $A_V = 2$ ,  $V_{OUT} = 2 V_{PP}$ ) 102 dBc
- Low Voltage Noise 10 nV/ $\sqrt{\text{Hz}}$
- Output current  $\pm 100\text{ mA}$
- CMVR  $-0.2V$  to  $3.8V$
- Rail-to-Rail Output
- $-40^\circ\text{C}$  to  $+125^\circ\text{C}$  Temperature Range

### APPLICATIONS

- ADC Driver
- DAC Buffer
- Active Filters
- High Speed Sensor Amplifier
- Current Sense Amplifier
- 1080i and 720p Analog Video Amplifier
- STB, TV Video Amplifier
- Video Switching and Muxing

### DESCRIPTION

The LMH6611 (single, with shutdown) and LMH6612 (dual) are 345 MHz rail-to-rail output amplifiers consuming just 3.2 mA of quiescent current per channel and designed to deliver high performance in power conscious single supply systems. The LMH6611 and LMH6612 have precision trimmed input offset voltages with low noise and low distortion performance as required for high accuracy video, test and measurement, and communication applications. The LMH6611 and LMH6612 are members of the PowerWise family and have an exceptional power-to-performance ratio.

With a trimmed input offset voltage of 0.022 mV and a high open loop gain of 103 dB the LMH6611 and LMH6612 meet the requirements of DC sensitive high speed applications such as low pass filtering in baseband I and Q radio channels. These specifications combined with a 0.01% settling time of 100 ns, a low noise of 10 nV/ $\sqrt{\text{Hz}}$  and better than 102 dBc SFDR at 100 kHz make these amplifiers particularly suited to driving 10, 12 and 14-bit high speed ADCs. The 45 MHz 0.1 dB bandwidth ( $A_V = 2$ ) driving  $2 V_{PP}$  into  $150\Omega$  allows the amplifiers to be used as output drivers in 1080i and 720p HDTV applications.

The input common mode range extends from 200 mV below the negative supply rail up to 1.2V from the positive rail. On a single 5V supply with a ground terminated  $150\Omega$  load the output swings to within 49 mV of the ground, while a mid-rail terminated  $1\text{ k}\Omega$  load will swing to 77 mV of either rail.



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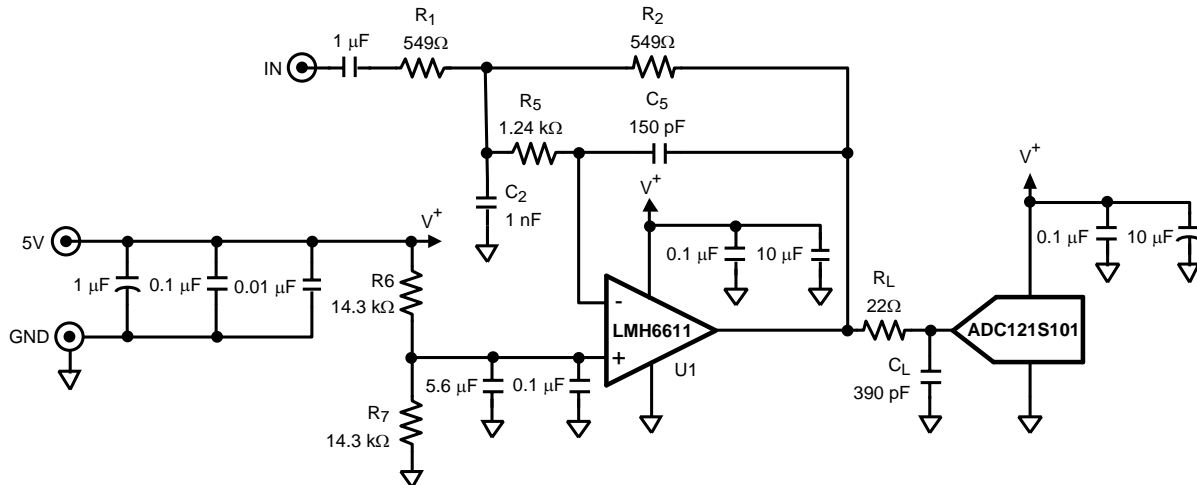
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## DESCRIPTION (CONTINUED)

The amplifiers will operate on a 2.7V to 11V single supply or  $\pm 1.35\text{V}$  to  $\pm 5.5\text{V}$  split supply. The LMH6611 single is available in 6-Pin SOT and has an independent active low disable pin which reduces the supply current to 120  $\mu\text{A}$ . The LMH6612 is available in 8-Pin SOIC. Both the LMH6611 and LMH6612 are available in  $-40^\circ\text{C}$  to  $+125^\circ\text{C}$  extended industrial temperature grade.

## Typical Application



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## Absolute Maximum Ratings<sup>(1)(2)</sup>

ESD Tolerance <sup>(3)</sup>	Human Body Model	For input pins only	2000V
		For all other pins	2000V
	Machine Model		200V
	Charge Device Model		1000V
Supply Voltage (V <sub>S</sub> = V <sup>+</sup> – V <sup>–</sup> )			12V
Junction Temperature <sup>(4)</sup>			150°C max

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC) Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).
- (4) The maximum power dissipation is a function of  $T_{J(\text{MAX})}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(\text{MAX})} - T_A) / \theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

## Operating Ratings<sup>(1)</sup>

Supply Voltage ( $V_S = V^+ - V^-$ )		2.7V to 11V
Ambient Temperature Range <sup>(2)</sup>		$-40^\circ\text{C}$ to $+125^\circ\text{C}$
Package Thermal Resistance ( $\theta_{JA}$ )	6-Pin SOT	231°C/W
	8-Pin SOIC	160°C/W

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications and the test conditions, see the Electrical Characteristics.
- (2) The maximum power dissipation is a function of  $T_{J(\text{MAX})}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(\text{MAX})} - T_A) / \theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

## +3V Electrical Characteristics

Unless otherwise specified, all limits are specified for  $T_J = +25^\circ\text{C}$ ,  $V^+ = 3\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_S = V^+ - V^-$ ,  $\overline{\text{DISABLE}} = 3\text{V}$ ,  $V_{CM} = V_O = V^+/2$ ,  $A_V = +1$ ,  $R_F = 0\Omega$ , when  $A_V \neq +1$  then  $R_F = 560\Omega$ ,  $R_L = 1\text{ k}\Omega$ . **Boldface** limits apply at temperature extremes.<sup>(1)</sup>

Symbol	Parameter	Condition	Min <sup>(2)</sup>	Typ <sup>(3)</sup>	Max <sup>(2)</sup>	Units
Frequency Domain Response						
SSBW	–3 dB Bandwidth Small Signal	A <sub>V</sub> = 1, R <sub>L</sub> = 1 kΩ, V <sub>OUT</sub> = 0.2 V <sub>PP</sub>		305		MHz
		A <sub>V</sub> = 2, –1, R <sub>L</sub> = 1 kΩ, V <sub>OUT</sub> = 0.2 V <sub>PP</sub>		115		
GBW	Gain Bandwidth (LMH6611)	A <sub>V</sub> = 10, R <sub>F</sub> = 2 kΩ, R <sub>G</sub> = 221Ω, R <sub>L</sub> = 1 kΩ, V <sub>OUT</sub> = 0.2 V <sub>PP</sub>	115	135		MHz
	Gain Bandwidth (LMH6612)	A <sub>V</sub> = 10, R <sub>F</sub> = 2 kΩ, R <sub>G</sub> = 221Ω, R <sub>L</sub> = 1 kΩ, V <sub>OUT</sub> = 0.2 V <sub>PP</sub>		130		
LSBW	–3 dB Bandwidth Large Signal	A <sub>V</sub> = 1, R <sub>L</sub> = 1 kΩ, V <sub>OUT</sub> = 1.5 V <sub>PP</sub>		90		MHz
		A <sub>V</sub> = –1, R <sub>L</sub> = 150Ω, V <sub>OUT</sub> = 2 V <sub>PP</sub>		85		
Peak	Peaking	A <sub>V</sub> = 1		1.0		dB
0.1 dB BW	0.1 dB Bandwidth	A <sub>V</sub> = 1, V <sub>OUT</sub> = 0.5 V <sub>PP</sub> , R <sub>L</sub> = 1 kΩ		33		MHz
		A <sub>V</sub> = 2, V <sub>OUT</sub> = 0.5 V <sub>PP</sub> , R <sub>L</sub> = 1 kΩ R <sub>F</sub> = R <sub>G</sub> = 560Ω		65		
		A <sub>V</sub> = 2, V <sub>OUT</sub> = 1.5 V <sub>PP</sub> , R <sub>L</sub> = 150Ω, R <sub>F</sub> = R <sub>G</sub> = 510Ω		47		
DG	Differential Gain	A <sub>V</sub> = 2, 4.43 MHz, 0.6V < V <sub>OUT</sub> < 2V, R <sub>L</sub> = 150Ω to V <sup>+</sup> /2		0.03		%
DP	Differential Phase	A <sub>V</sub> = 2, 4.43 MHz, 0.6V < V <sub>OUT</sub> < 2V, R <sub>L</sub> = 150Ω to V <sup>+</sup> /2		0.06		deg
Time Domain Response						
t <sub>r</sub> /t <sub>f</sub>	Rise & Fall Time	1.5V Step, A <sub>V</sub> = 1		2.8		ns
SR	Slew Rate	2V Step, A <sub>V</sub> = 1		330		V/μs
t <sub>s_0.1</sub>	0.1% Settling Time	2V Step, A <sub>V</sub> = –1		74		ns
t <sub>s_0.01</sub>	0.01% Settling Time	2V Step, A <sub>V</sub> = –1		116		
Noise and Distortion Performance						
SFDR	Spurious Free Dynamic Range	f <sub>C</sub> = 100 kHz, A <sub>V</sub> = –1, V <sub>OUT</sub> = 2 V <sub>PP</sub>		109		dBc
		f <sub>C</sub> = 1 MHz, A <sub>V</sub> = –1, V <sub>OUT</sub> = 2 V <sub>PP</sub>		97		
		f <sub>C</sub> = 5 MHz, A <sub>V</sub> = –1, V <sub>OUT</sub> = 2 V <sub>PP</sub>		80		
e <sub>n</sub>	Input Voltage Noise	f = 100 kHz		10		nV/√Hz
i <sub>n</sub>	Input Current Noise	f = 100 kHz		2		pA/√Hz
CT	Crosstalk (LMH6612)	f = 5 MHz, V <sub>IN</sub> = 2 V <sub>PP</sub>		71		dB
Input, DC Performance						
V <sub>OS</sub>	Input Offset Voltage (LMH6611)	V <sub>CM</sub> = 0.5V		0.022	±1.5 ±2	mV
	Input Offset Voltage (LMH6612)	V <sub>CM</sub> = 0.5V		–0.015	±1.5 ±2	
TCV <sub>OS</sub>	Input Offset Voltage Average Drift	See <sup>(4)</sup>		4		μV/°C
I <sub>B</sub>	Input Bias Current	V <sub>CM</sub> = 0.5V		–5.9	–10.1 –11.1	μA
I <sub>O</sub>	Input Offset Current			0.01	±0.5 ±0.7	μA
C <sub>IN</sub>	Input Capacitance			2.5		pF
R <sub>IN</sub>	Input Resistance			6		MΩ
CMVR	Input Voltage Range	DC, CMRR ≥ 76 dB	–0.2		1.8	V

(1) Boldface limits apply to temperature range of  $-40^\circ\text{C}$  to  $125^\circ\text{C}$

(2) Limits are 100% production tested at  $25^\circ\text{C}$ . Limits over the operating temperature range are ensured through correlations using the Statistical Quality Control (SQC) method.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

(4) Voltage average drift is determined by dividing the change in  $V_{OS}$  by temperature change.

### +3V Electrical Characteristics (continued)

Unless otherwise specified, all limits are specified for  $T_J = +25^\circ\text{C}$ ,  $V^+ = 3\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_S = V^+ - V^-$ ,  $\overline{\text{DISABLE}} = 3\text{V}$ ,  $V_{\text{CM}} = V_O = V^+/2$ ,  $A_V = +1$ ,  $R_F = 0\Omega$ , when  $A_V \neq +1$  then  $R_F = 560\Omega$ ,  $R_L = 1\text{ k}\Omega$ . **Boldface** limits apply at temperature extremes.<sup>(1)</sup>

Symbol	Parameter	Condition	Min <sup>(2)</sup>	Typ <sup>(3)</sup>	Max <sup>(2)</sup>	Units
CMRR	Common Mode Rejection Ratio	V <sub>CM</sub> Stepped from −0.1V to 1.7V	79	98		dB
A <sub>OL</sub>	Open Loop Gain	R <sub>L</sub> = 1 kΩ, V <sub>OUT</sub> = 2.7V to 0.3V	89	101		dB
		R <sub>L</sub> = 150Ω, V <sub>OUT</sub> = 2.5V to 0.5V	78	85		
Output DC Characteristics						
V <sub>O</sub>	Output Swing High (LMH6611) (Voltage from V <sup>+</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to V <sup>+</sup> /2		59	72 76	mV
		R <sub>L</sub> = 150Ω to V <sup>+</sup> /2		133	169 182	
	Output Swing Low (LMH6611) (Voltage from V <sup>−</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to V <sup>+</sup> /2		59	74 80	
		R <sub>L</sub> = 150Ω to V <sup>+</sup> /2		133	171 188	
		R <sub>L</sub> = 150Ω to V <sup>−</sup>		42	52 56	
	Output Swing High (LMH6612) (Voltage from V <sup>+</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to V <sup>+</sup> /2		58	68 73	
		R <sub>L</sub> = 150Ω to V <sup>+</sup> /2		131	157 172	
	Output Swing Low (LMH6612) (Voltage from V <sup>−</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to V <sup>+</sup> /2		61	71 79	
		R <sub>L</sub> = 150Ω to V <sup>+</sup> /2		139	168 187	
		R <sub>L</sub> = 150Ω to V <sup>−</sup>		43	51 56	
I <sub>OUT</sub>	Linear Output Current	V <sub>OUT</sub> = V <sup>+</sup> /2 <sup>(5)</sup>		±70		mA
R <sub>O</sub>	Output Resistance	f = 1 MHz		0.07		Ω
Enable Pin Operation						
	Enable High Voltage Threshold	Enabled <sup>(6)</sup>	2.0			V
	Enable Pin High Current	V <sub>DISABLE</sub> = 3V		0.001		μA
	Enable Low Voltage Threshold	Disabled <sup>(6)</sup>			1.0	V
	Enable Pin Low Current	V <sub>DISABLE</sub> = 0V		0.8		μA
t <sub>on</sub>	Turn-On Time			18		ns
t <sub>off</sub>	Turn-Off Time			50		ns
Power Supply Performance						
PSRR	Power Supply Rejection Ratio	DC, V <sub>CM</sub> = 0.5V, V <sub>S</sub> = 2.7V to 11V	81	96		dB
I <sub>S</sub>	Supply Current (LMH6611)	R <sub>L</sub> = ∞		3.0	3.4 3.8	mA
	Supply Current (LMH6612) (per channel)	R <sub>L</sub> = ∞		2.95	3.45 3.9	
I <sub>SD</sub>	Disable Shutdown Current (LMH6611)	DISABLE = 0V		101	132	μA

(5) Do not short circuit the output. Continuous source or sink currents larger than the  $I_{\text{OUT}}$  typical are not recommended as they may damage the part.

(6) This parameter is ensured by design and/or characterization and is not tested in production.

## +5V Electrical Characteristics

Unless otherwise specified, all limits are specified for  $T_J = +25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_S = V^+ - V^-$ ,  $\overline{\text{DISABLE}} = 5\text{V}$ ,  $V_{\text{CM}} = V_O = V^+/2$ ,  $A_V = +1$ ,  $R_F = 0\Omega$ , when  $A_V \neq +1$  then  $R_F = 560\Omega$ ,  $R_L = 1\text{ k}\Omega$ . **Boldface** limits apply at temperature extremes.

Symbol	Parameter	Condition	Min (1)	Typ (2)	Max (1)	Units
Frequency Domain Response						
SSBW	–3 dB Bandwidth Small Signal	$A_V = 1$ , $R_L = 1\text{ k}\Omega$ , $V_{OUT} = 0.2\text{ V}_{PP}$		345		MHz
		$A_V = 2$ , $-1$ , $R_L = 1\text{ k}\Omega$ , $V_{OUT} = 0.2\text{ V}_{PP}$		112		
GBW	Gain Bandwidth (LMH6611)	$A_V = 10$ , $R_F = 2\text{ k}\Omega$ , $R_G = 221\Omega$ , $R_L = 1\text{ k}\Omega$ , $V_{OUT} = 0.2\text{ V}_{PP}$	115	135		MHz
	Gain Bandwidth (LMH6612)	$A_V = 10$ , $R_F = 2\text{ k}\Omega$ , $R_G = 221\Omega$ , $R_L = 1\text{ k}\Omega$ , $V_{OUT} = 0.2\text{ V}_{PP}$		130		
LSBW	–3 dB Bandwidth Large Signal	$A_V = 1$ , $R_L = 1\text{ k}\Omega$ , $V_{OUT} = 2\text{ V}_{PP}$		77		MHz
		$A_V = 2$ , $R_L = 150\Omega$ , $V_{OUT} = 2\text{ V}_{PP}$		85		
Peak	Peaking	$A_V = 1$		0.3		dB
0.1 dBBW	0.1 dB Bandwidth	$A_V = 1$ , $V_{OUT} = 0.5\text{ V}_{PP}$ , $R_L = 1\text{ k}\Omega$		45		MHz
		$A_V = 2$ , $V_{OUT} = 0.5\text{ V}_{PP}$ , $R_L = 1\text{ k}\Omega$ $R_F = R_G = 680\Omega$		68		
		$A_V = 2$ , $V_{OUT} = 2\text{ V}_{PP}$ , $R_L = 150\Omega$ , $R_F = R_G = 665\Omega$		45		
DG	Differential Gain	$A_V = 2$ , 4.43 MHz, $0.6\text{V} < V_{OUT} < 2\text{V}$ , $R_L = 150\Omega$ to $V^+/2$		0.05		%
DP	Differential Phase	$A_V = 2$ , 4.43 MHz, $0.6\text{V} < V_{OUT} < 2\text{V}$ , $R_L = 150\Omega$ to $V^+/2$		0.06		deg
Time Domain Response						
$t_r/t_f$	Rise & Fall Time	2V Step, $A_V = 1$		3.6		ns
SR	Slew Rate	2V Step, $A_V = 1$		460		V/ $\mu\text{s}$
$t_{s\_0.1}$	0.1% Settling Time	2V Step, $A_V = -1$		67		ns
$t_{s\_0.01}$	0.01% Settling Time	2V Step, $A_V = -1$		100		
Distortion and Noise Performance						
SFDR	Spurious Free Dynamic Range	$f_C = 100\text{ kHz}$ , $A_V = 2$ , $V_{OUT} = 2\text{ V}_{PP}$		102		dBc
		$f_C = 1\text{ MHz}$ , $A_V = 2$ , $V_{OUT} = 2\text{ V}_{PP}$		96		
		$f_C = 5\text{ MHz}$ , $A_V = 2$ , $V_O = 2\text{ V}_{PP}$		82		
$e_n$	Input Voltage Noise	$f = 100\text{ kHz}$		10		nV/ $\sqrt{\text{Hz}}$
$i_n$	Input Current Noise	$f = 100\text{ kHz}$		2		pA/ $\sqrt{\text{Hz}}$
CT	Crosstalk (LMH6612)	$f = 5\text{ MHz}$ , $V_{IN} = 2\text{ V}_{PP}$		71		dB
Input, DC Performance						
$V_{OS}$	Input Offset Voltage (LMH6611)	$V_{CM} = 0.5\text{V}$		0.013	$\pm 1.5$ <b><math>\pm 2</math></b>	mV
	Input Offset Voltage (LMH6612)	$V_{CM} = 0.5\text{V}$		0.022	$\pm 1.5$ <b><math>\pm 2</math></b>	
$\text{TCV}_{OS}$	Input Offset Voltage Average Drift	See <sup>(3)</sup>		4		$\mu\text{V}/^\circ\text{C}$
$I_B$	Input Bias Current	$V_{CM} = 0.5\text{V}$		–6.3	–10.1 <b>–11.1</b>	$\mu\text{A}$
$I_O$	Input Offset Current			0.01	$\pm 0.5$ <b><math>\pm 0.7</math></b>	$\mu\text{A}$
$C_{IN}$	Input Capacitance			2.5		pF
$R_{IN}$	Input Resistance			6		M $\Omega$
CMVR	Input Voltage Range	DC, CMRR $\geq 78\text{ dB}$	–0.2		3.8	V

- (1) Limits are 100% production tested at  $25^\circ\text{C}$ . Limits over the operating temperature range are ensured through correlations using the Statistical Quality Control (SQC) method.
- (2) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.
- (3) Voltage average drift is determined by dividing the change in  $V_{\text{OS}}$  by temperature change.

**+5V Electrical Characteristics (continued)**

Unless otherwise specified, all limits are specified for  $T_J = +25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = 0\text{V}$ ,  $V_S = V^+ - V^-$ ,  $\overline{\text{DISABLE}} = 5\text{V}$ ,  $V_{\text{CM}} = V_O = V^+/2$ ,  $A_V = +1$ ,  $R_F = 0\Omega$ , when  $A_V \neq +1$  then  $R_F = 560\Omega$ ,  $R_L = 1\text{ k}\Omega$ . **Boldface** limits apply at temperature extremes.

Symbol	Parameter	Condition	Min (1)	Typ (2)	Max (1)	Units
CMRR	Common Mode Rejection Ratio	V <sub>CM</sub> Stepped from −0.1V to 3.7V	81	98		dB
A <sub>OL</sub>	Open Loop Gain	R <sub>L</sub> = 1 kΩ, V <sub>OUT</sub> = 4.6V to 0.4V	92	103		dB
		R <sub>L</sub> = 150Ω, V <sub>OUT</sub> = 4.4V to 0.6V	80	86		
Output DC Characteristics						
V <sub>O</sub>	Output Swing High (LMH6611) (Voltage from V <sup>+</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to V <sup>+</sup> /2		76	90 93	mV
		R <sub>L</sub> =150Ω to V <sup>+</sup> /2		195	239 256	
	Output Swing Low (LMH6611) (Voltage from V <sup>−</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to V <sup>+</sup> /2		74	92 98	
		R <sub>L</sub> =150Ω to V <sup>+</sup> /2		193	243 265	
		R <sub>L</sub> = 150Ω to V <sup>−</sup>		48	60 64	
	Output Swing High (LMH6612) (Voltage from V <sup>+</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to V <sup>+</sup> /2		75	86 91	
		R <sub>L</sub> =150Ω to V <sup>+</sup> /2		195	223 241	
	Output Swing Low (LMH6612) (Voltage from V <sup>−</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to V <sup>+</sup> /2		77	88 98	
		R <sub>L</sub> =150Ω to V <sup>+</sup> /2		202	234 261	
		R <sub>L</sub> = 150Ω to V <sup>−</sup>		49	58 64	
I <sub>OUT</sub>	Linear Output Current	V <sub>OUT</sub> = V <sup>+</sup> /2 <sup>(4)</sup>		±100		mA
R <sub>O</sub>	Output Resistance	f = 1 MHz		0.07		Ω
Enable Pin Operation						
	Enable High Voltage Threshold	Enabled <sup>(5)</sup>	3.0			V
	Enable Pin High Current	V <sub>DISABLE</sub> = 5V		1.2		μA
	Enable Low Voltage Threshold	Disabled <sup>(5)</sup>			2.0	V
	Enable Pin Low Current	V <sub>DISABLE</sub> = 0V		2.8		μA
t <sub>on</sub>	Turn-On Time			20		ns
t <sub>off</sub>	Turn-Off Time			60		ns
Power Supply Performance						
PSRR	Power Supply Rejection Ratio	DC, V <sub>CM</sub> = 0.5V, V <sub>S</sub> = 2.7V to 11V	81	96		dB
I <sub>S</sub>	Supply Current (LMH6611)	R <sub>L</sub> = ∞		3.2	3.6 4.0	mA
	Supply Current (LMH6612) (per channel)	R <sub>L</sub> = ∞		3.2	3.7 4.25	
I <sub>SD</sub>	Disable Shutdown Current (LMH6611)	DISABLE = 0V		120	162	μA

(4) Do not short circuit the output. Continuous source or sink currents larger than the  $I_{\text{OUT}}$  typical are not recommended as they may damage the part.

(5) This parameter is ensured by design and/or characterization and is not tested in production.

## ±5V Electrical Characteristics

Unless otherwise specified, all limits are specified for  $T_J = +25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = -5\text{V}$ ,  $V_S = V^+ - V^-$ ,  $\overline{\text{DISABLE}} = 5\text{V}$ ,  $V_{\text{CM}} = V_O = 0\text{V}$ ,  $A_V = +1$ ,  $R_F = 0\Omega$ , when  $A_V \neq +1$  then  $R_F = 560\Omega$ ,  $R_L = 1\text{ k}\Omega$ . **Boldface** limits apply at temperature extremes.

Symbol	Parameter	Condition	Min (1)	Typ (2)	Max (1)	Units
Frequency Domain Response						
SSBW	−3 dB Bandwidth Small Signal	$A_V = 1$ , $R_L = 1\text{ k}\Omega$ , $V_{OUT} = 0.2\text{ V}_{PP}$		365		MHz
		$A_V = 2$ , $-1$ , $R_L = 1\text{ k}\Omega$ , $V_{OUT} = 0.2\text{ V}_{PP}$		110		
GBW	Gain Bandwidth (LMH6611)	$A_V = 10$ , $R_F = 2\text{ k}\Omega$ , $R_G = 221\Omega$ , $R_L = 1\text{ k}\Omega$ , $V_{OUT} = 0.2\text{ V}_{PP}$	115	135		MHz
	Gain Bandwidth (LMH6612)	$A_V = 10$ , $R_F = 2\text{ k}\Omega$ , $R_G = 221\Omega$ , $R_L = 1\text{ k}\Omega$ , $V_{OUT} = 0.2\text{ V}_{PP}$		130		
LSBW	−3 dB Bandwidth Large Signal	$A_V = 1$ , $R_L = 1\text{ k}\Omega$ , $V_{OUT} = 2\text{ V}_{PP}$		85		MHz
		$A_V = 2$ , $R_L = 150\Omega$ , $V_{OUT} = 2\text{ V}_{PP}$		87		
Peak	Peaking	$A_V = 1$		0.01		dB
0.1 dBBW	0.1 dB Bandwidth	$A_V = 1$ , $V_{OUT} = 0.5\text{ V}_{PP}$ , $R_L = 1\text{ k}\Omega$		92		MHz
		$A_V = 2$ , $V_{OUT} = 0.5\text{ V}_{PP}$ , $R_L = 1\text{ k}\Omega$ $R_F = R_G = 750\Omega$		65		
		$A_V = 2$ , $V_{OUT} = 2\text{ V}_{PP}$ , $R_L = 150\Omega$ , $R_F = R_G = 680\Omega$		45		
DG	Differential Gain	$A_V = 2$ , 4.43 MHz, $0.6\text{V} < V_{OUT} < 2\text{V}$ , $R_L = 150\Omega$ to $V^+/2$		0.05		%
DP	Differential Phase	$A_V = 2$ , 4.43 MHz, $0.6\text{V} < V_{OUT} < 2\text{V}$ , $R_L = 150\Omega$ to $V^+/2$		0.05		deg
Time Domain Response						
$t_r/t_f$	Rise & Fall Time	2V Step, $A_V = 1$		3.5		ns
SR	Slew Rate	2V Step, $A_V = 1$		460		V/ $\mu\text{s}$
$t_{s\_0.1}$	0.1% Settling Time	2V Step, $A_V = -1$		60		ns
$t_{s\_0.01}$	0.01% Settling Time	2V Step, $A_V = -1$		100		
Noise and Distortion Performance						
SFDR	Spurious Free Dynamic Range	$f_C = 100\text{ kHz}$ , $A_V = 2$ , $V_{OUT} = 2\text{ V}_{PP}$		102		dBc
		$f_C = 1\text{ MHz}$ , $A_V = 2$ , $V_{OUT} = 2\text{ V}_{PP}$		100		
		$f_C = 5\text{ MHz}$ , $A_V = 2$ , $V_{OUT} = 2\text{ V}_{PP}$		81		
$e_n$	Input Voltage Noise	$f = 100\text{ kHz}$		10		nV/ $\sqrt{\text{Hz}}$
$i_n$	Input Current Noise	$f = 100\text{ kHz}$		2		pA/ $\sqrt{\text{Hz}}$
CT	Crosstalk (LMH6612)	$f = 5\text{ MHz}$ , $V_{IN} = 2\text{ V}_{PP}$		71		dB
Input DC Performance						
$V_{OS}$	Input Offset Voltage (LMH6611)	$V_{CM} = -4.5\text{V}$		0.074	$\pm 1.5$ $\pm 2$	mV
	Input Offset Voltage (LMH6612)	$V_{CM} = -4.5\text{V}$		0.095	$\pm 1.5$ $\pm 2$	
$TCV_{OS}$	Input Offset Voltage Average Drift	See <sup>(3)</sup>		4		$\mu\text{V}/^\circ\text{C}$
$I_B$	Input Bias Current	$V_{CM} = -4.5\text{V}$		−6.5	−10.1 −11.1	$\mu\text{A}$
$I_O$	Input Offset Current			0.01	$\pm 0.5$ $\pm 0.7$	$\mu\text{A}$
$C_{IN}$	Input Capacitance			2.5		pF
$R_{IN}$	Input Resistance			6		M $\Omega$
CMVR	Input Voltage Range	DC, CMRR $\geq 81\text{ dB}$	−5.2		3.8	V

(1) Limits are 100% production tested at  $25^\circ\text{C}$ . Limits over the operating temperature range are ensured through correlations using the Statistical Quality Control (SQC) method.

(2) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

(3) Voltage average drift is determined by dividing the change in  $V_{\text{OS}}$  by temperature change.

**±5V Electrical Characteristics (continued)**

Unless otherwise specified, all limits are specified for  $T_J = +25^\circ\text{C}$ ,  $V^+ = 5\text{V}$ ,  $V^- = -5\text{V}$ ,  $V_S = V^+ - V^-$ ,  $\overline{\text{DISABLE}} = 5\text{V}$ ,  $V_{\text{CM}} = V_O = 0\text{V}$ ,  $A_V = +1$ ,  $R_F = 0\Omega$ , when  $A_V \neq +1$  then  $R_F = 560\Omega$ ,  $R_L = 1\text{ k}\Omega$ . **Boldface** limits apply at temperature extremes.

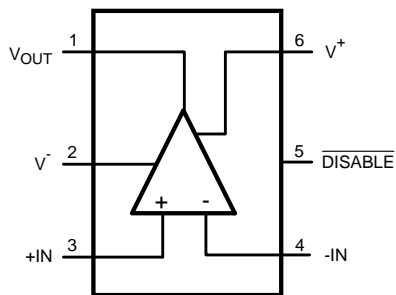
Symbol	Parameter	Condition	Min (1)	Typ (2)	Max (1)	Units
CMRR	Common Mode Rejection Ratio	V <sub>CM</sub> Stepped from −5.1V to 3.7V	81	98		dB
A <sub>OL</sub>	Open Loop Gain	R <sub>L</sub> = 1 kΩ, V <sub>OUT</sub> = +4.6V to −4.6V	96	103		dB
		R <sub>L</sub> = 150Ω, V <sub>OUT</sub> = +4.3V to −4.3V	80	87		
Output DC Characteristics						
V <sub>O</sub>	Output Swing High (LMH6611) (Voltage from V <sup>+</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to GND		107	125 130	mV
		R <sub>L</sub> = 150Ω to GND		339	402 433	
	Output Swing Low (LMH6611) (Voltage from V <sup>−</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to GND		103	123 132	
		R <sub>L</sub> = 150Ω to GND		332	404 445	
		R <sub>L</sub> = 150Ω to V <sup>−</sup>		54	70 74	
	Output Swing High (LMH6612) (Voltage from V <sup>+</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to GND		107	118 125	
		R <sub>L</sub> = 150Ω to GND		340	375 407	
	Output Swing Low (LMH6612) (Voltage from V <sup>−</sup> Supply Rail)	R <sub>L</sub> = 1 kΩ to GND		108	120 135	
		R <sub>L</sub> = 150Ω to GND		348	389 434	
		R <sub>L</sub> = 150Ω to V <sup>−</sup>		56	66 74	
I <sub>OUT</sub>	Linear Output Current	V <sub>OUT</sub> = GND <sup>(4)</sup>		±120		mA
R <sub>O</sub>	Output Resistance	f = 1 MHz		0.07		Ω
Enable Pin Operation						
	Enable High Voltage Threshold	Enabled <sup>(5)</sup>	0.5			V
	Enable Pin High Current	V <sub>DISABLE</sub> = +5V		17.0		μA
	Enable Low Voltage Threshold	Disabled <sup>(5)</sup>			−0.5	V
	Enable Pin Low Current	V <sub>DISABLE</sub> = −5V		18.6		μA
t <sub>on</sub>	Turn-On Time			19		ns
t <sub>off</sub>	Turn-Off Time			60		ns
Power Supply Performance						
PSRR	Power Supply Rejection Ratio	DC, V <sub>CM</sub> = −4.5V, V <sub>S</sub> = 2.7V to 11V	81	96		dB
I <sub>S</sub>	Supply Current (LMH6611)	R <sub>L</sub> = ∞		3.3	3.8 4.4	mA
	Supply Current (LMH6612) (per channel)	R <sub>L</sub> = ∞		3.45	4.05 4.85	
I <sub>SD</sub>	Disable Shutdown Current (LMH6611)	DISABLE = −5V		160	212	μA

(4) Do not short circuit the output. Continuous source or sink currents larger than the  $I_{\text{OUT}}$  typical are not recommended as they may damage the part.

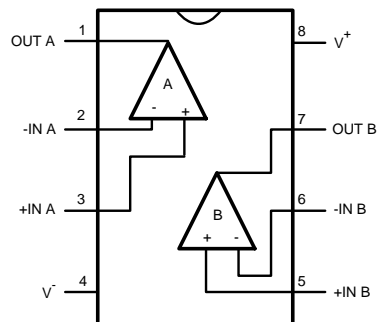
(5) This parameter is ensured by design and/or characterization and is not tested in production.



## Connection Diagram



**Figure 1. 6-Pin SOT  
Top View**



**Figure 2. 8-Pin SOIC  
Top View**

## Typical Performance Characteristics

At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

**Closed Loop Frequency Response for Various Supplies**

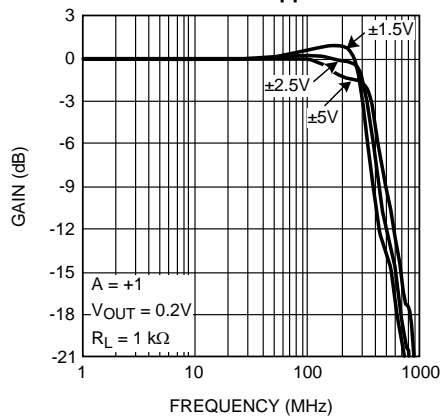


Figure 3.

**Closed Loop Frequency Response for Various Supplies**

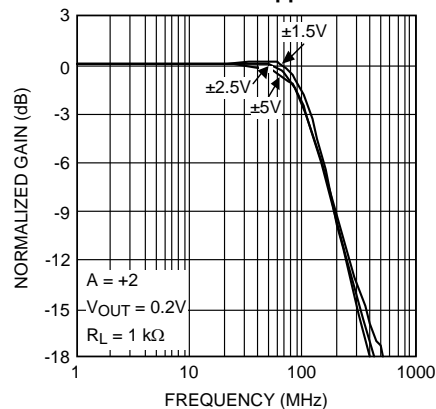


Figure 4.

**Closed Loop Frequency Response for Various Supplies**

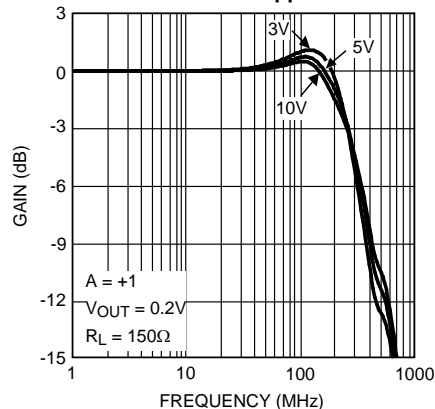


Figure 5.

**Closed Loop Frequency Response for Various Supplies (Gain = +2)**

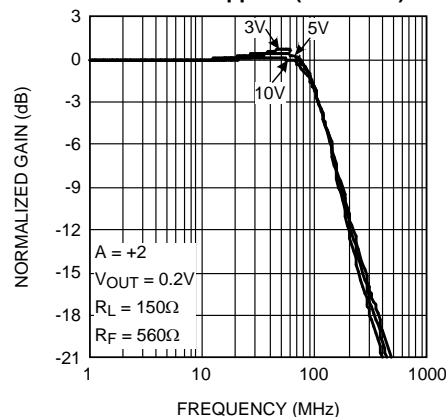


Figure 6.

**Closed Loop Gain vs. Frequency for Various Temperatures**

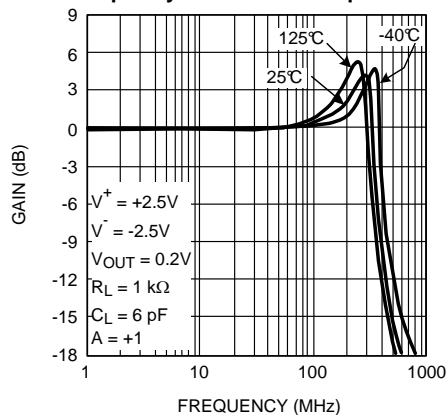


Figure 7.

**Closed Loop Gain vs. Frequency for Various Temperatures**

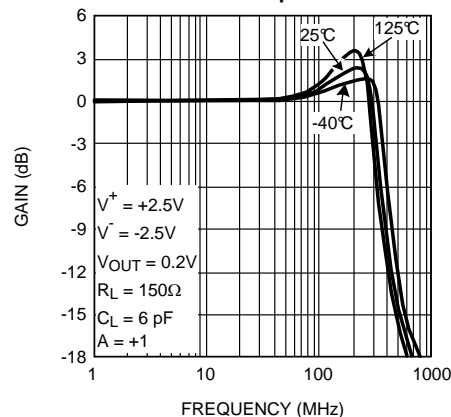


Figure 8.

## Typical Performance Characteristics (continued)

At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

**Closed Loop Gain  
vs.  
Frequency for  
Various Gains**

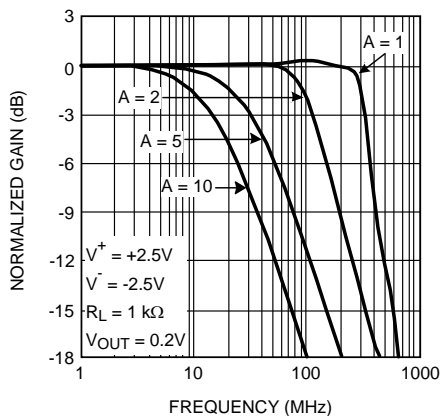


Figure 9.

**Large Signal Frequency Response**

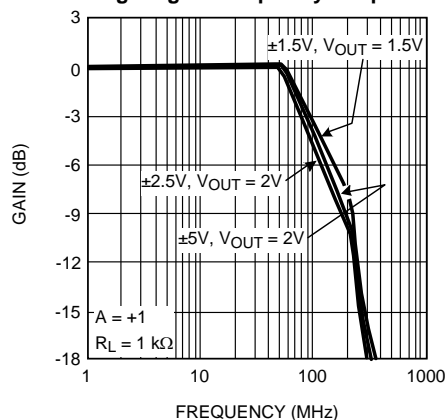


Figure 10.

**Large Signal Frequency Response**

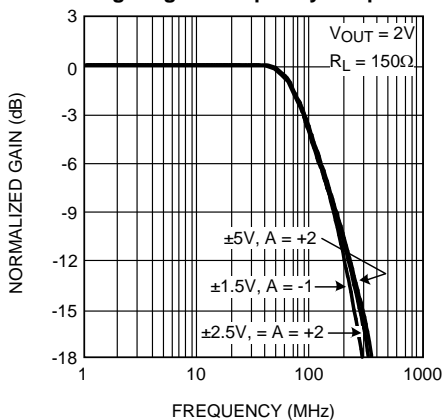


Figure 11.

**±0.1 dB Gain Flatness for Various Supplies**

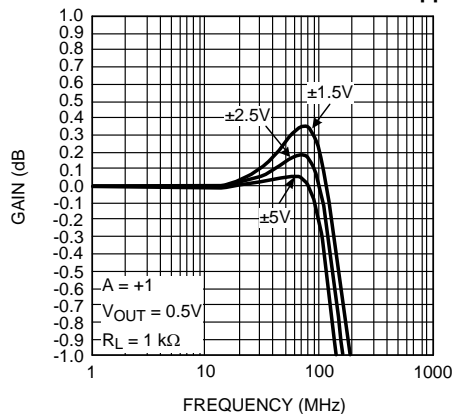


Figure 12.

**±0.1 dB Gain Flatness for Various Supplies**

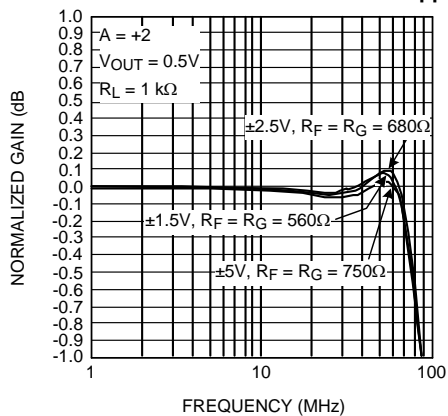


Figure 13.

**±0.1 dB Gain Flatness for Various Supplies**

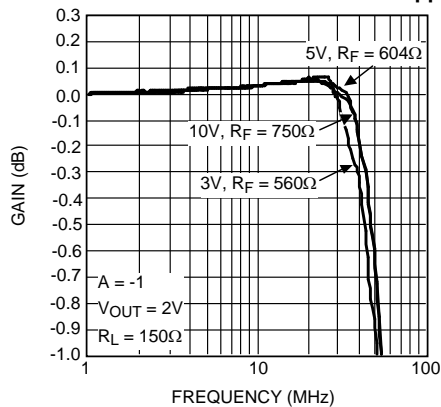


Figure 14.

## Typical Performance Characteristics (continued)

At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

**$\pm 0.1$  dB Gain Flatness for Various Supplies**

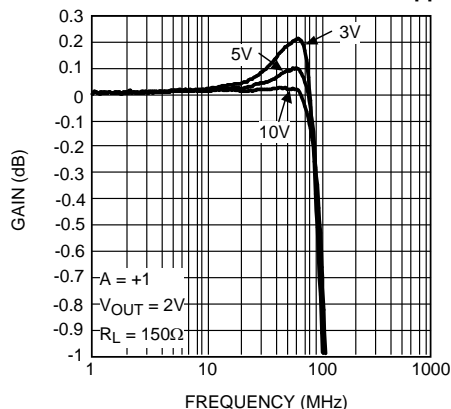


Figure 15.

**$\pm 0.1$  dB Gain Flatness for Various Supplies (Gain = +2)**

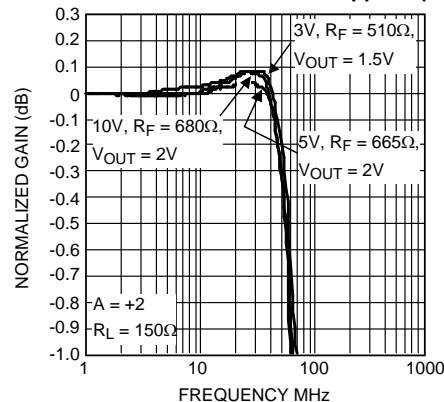


Figure 16.

**Small Signal Frequency Response with Various Capacitive Load**

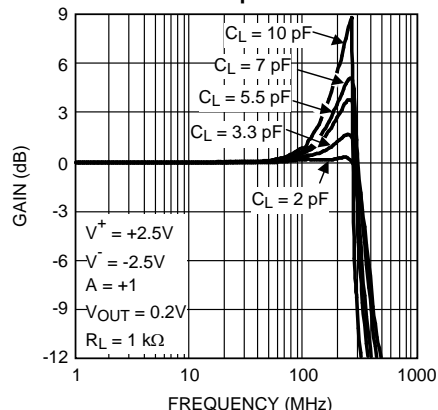


Figure 17.

**Small Signal Frequency Response with Capacitive Load and Various  $R_{ISO}$**

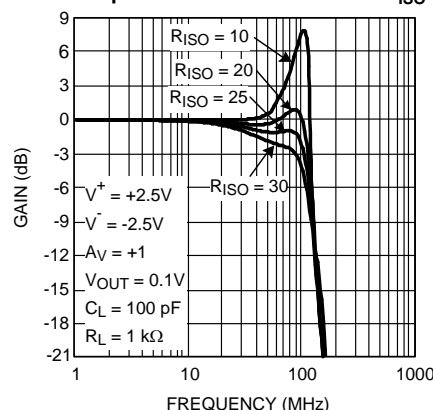


Figure 18.

**HD2 and HD3 vs. Frequency and Supply Voltage**

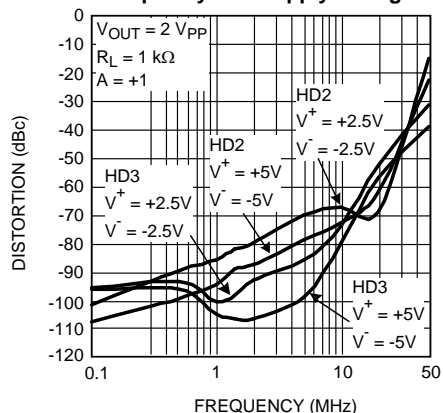


Figure 19.

**HD2 and HD3 vs. Frequency and Load**

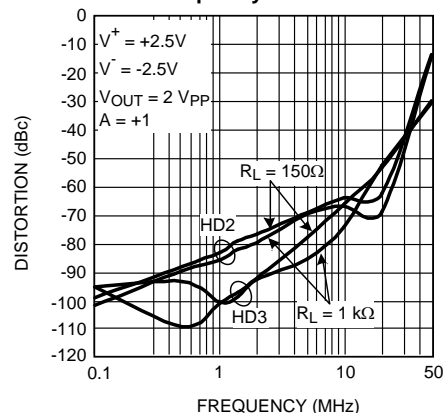


Figure 20.

## Typical Performance Characteristics (continued)

At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

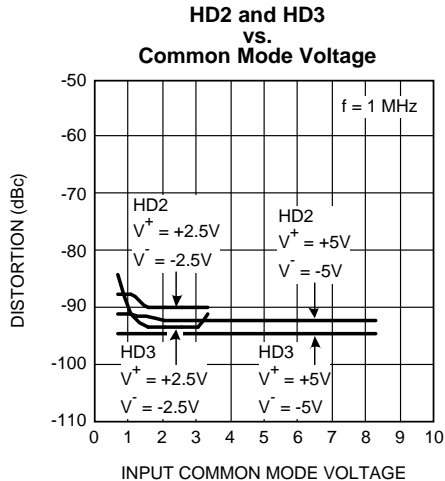


Figure 21.

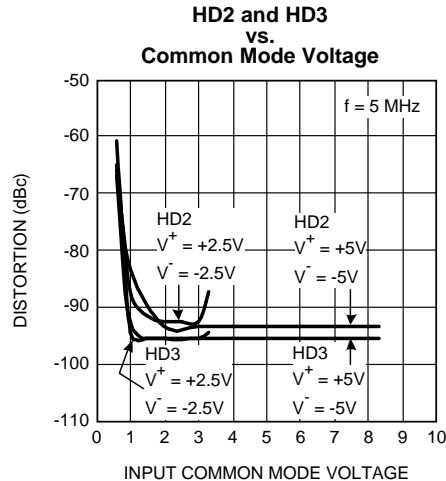


Figure 22.

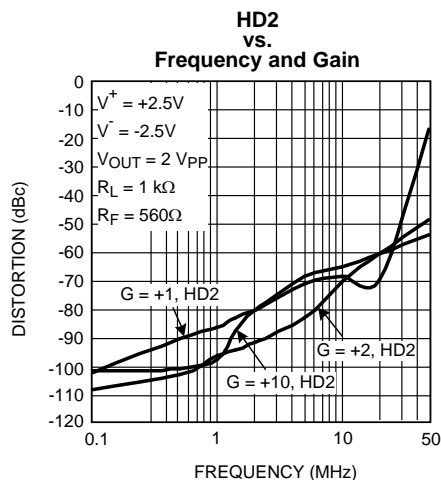


Figure 23.

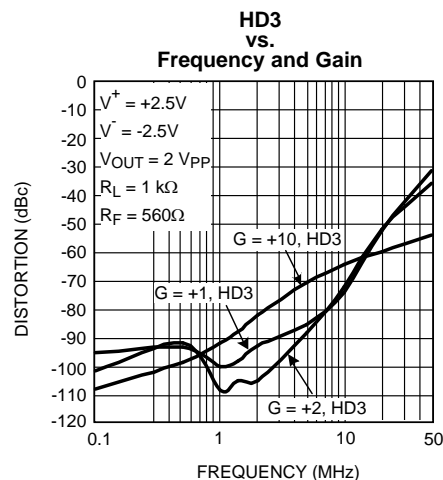


Figure 24.

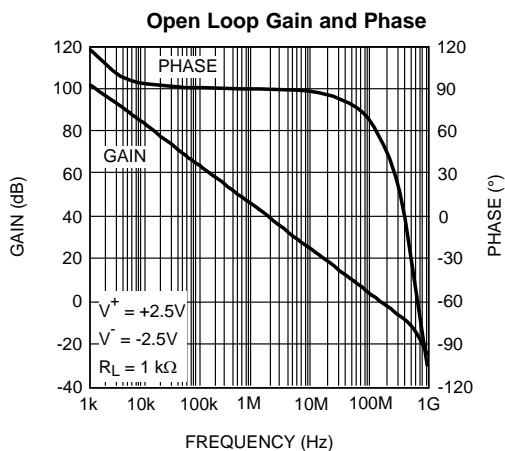


Figure 25.

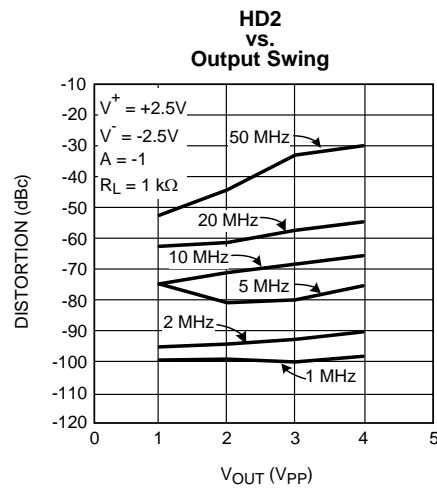


Figure 26.

### Typical Performance Characteristics (continued)

At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

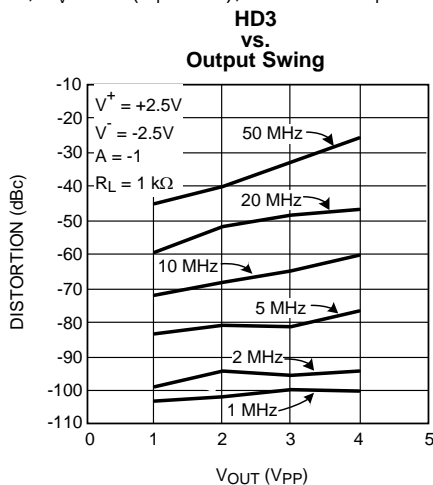


Figure 27.

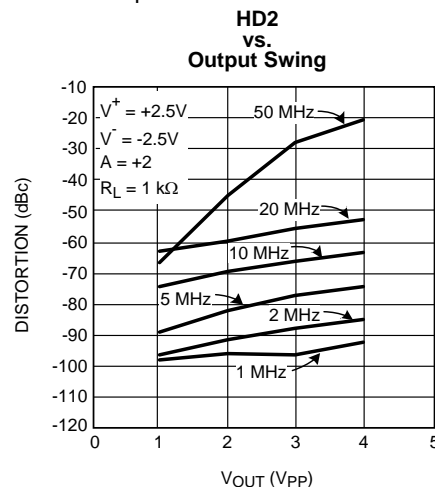


Figure 28.

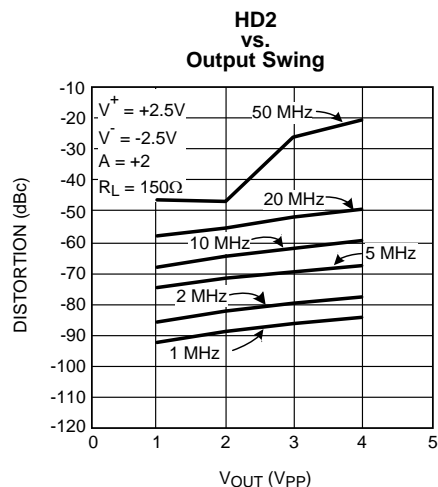


Figure 29.

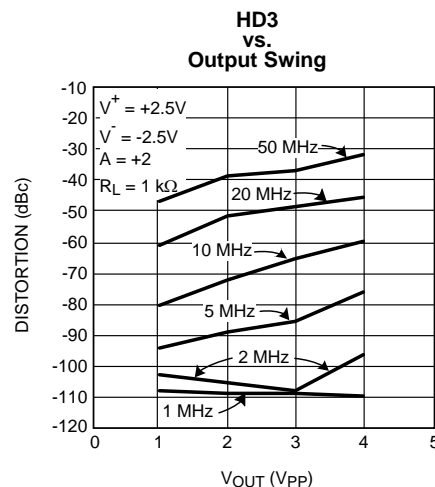


Figure 30.

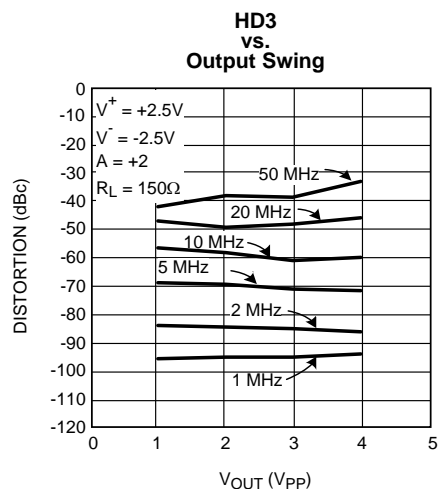


Figure 31.

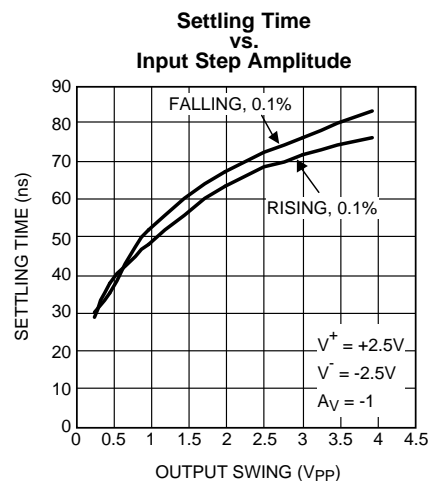


Figure 32.

## Typical Performance Characteristics (continued)

At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

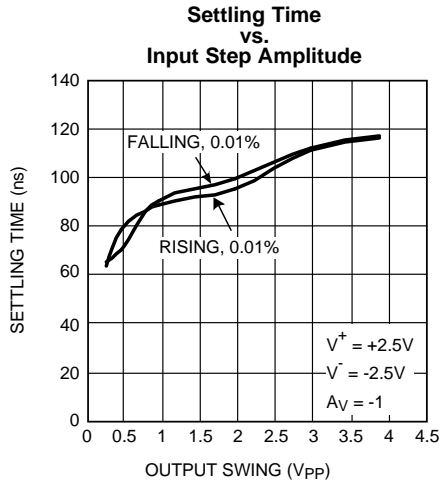


Figure 33.

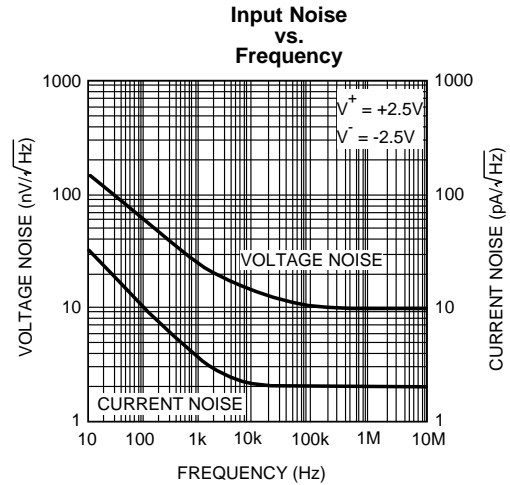


Figure 34.

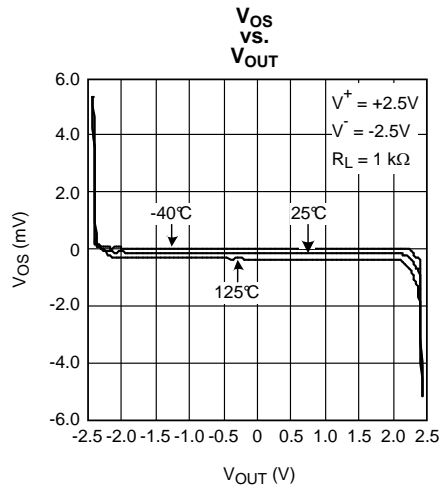


Figure 35.

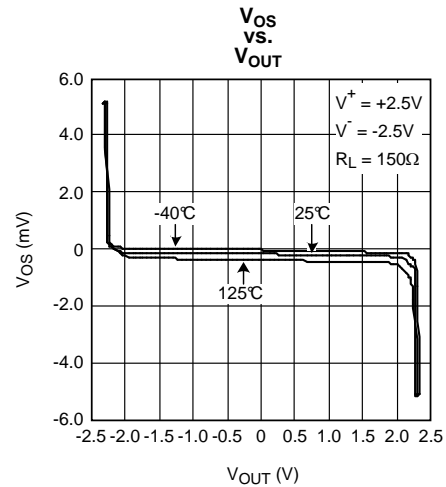


Figure 36.

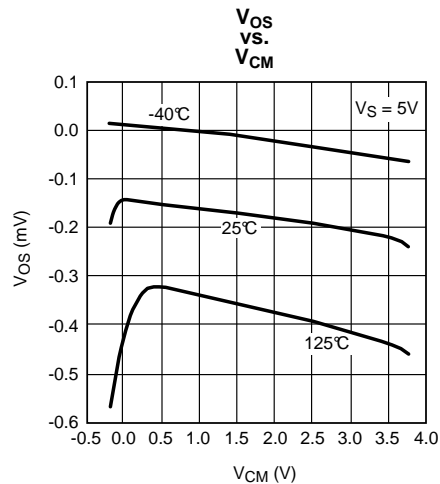


Figure 37.

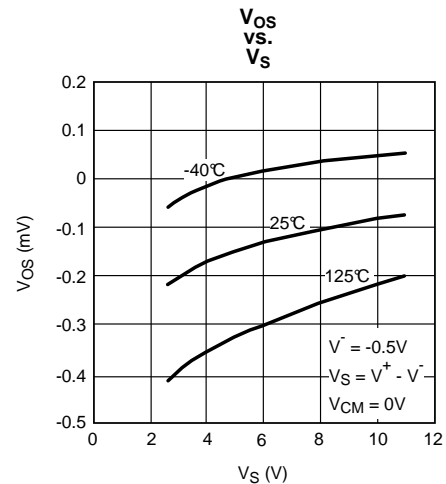


Figure 38.

### Typical Performance Characteristics (continued)

At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

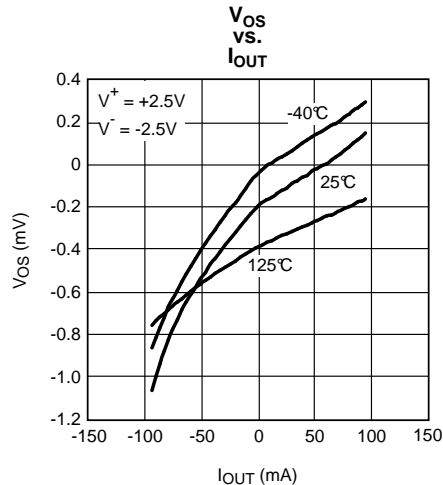


Figure 39.

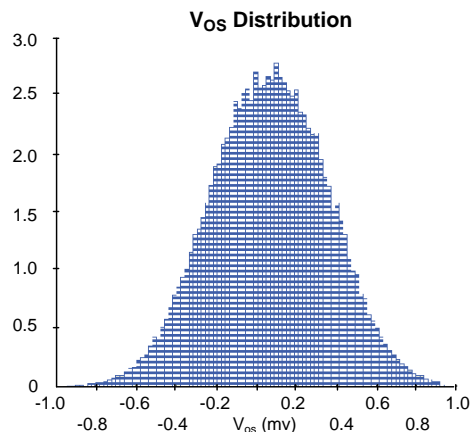


Figure 40.

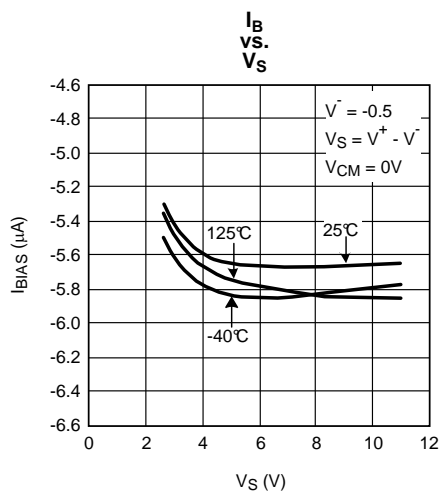


Figure 41.

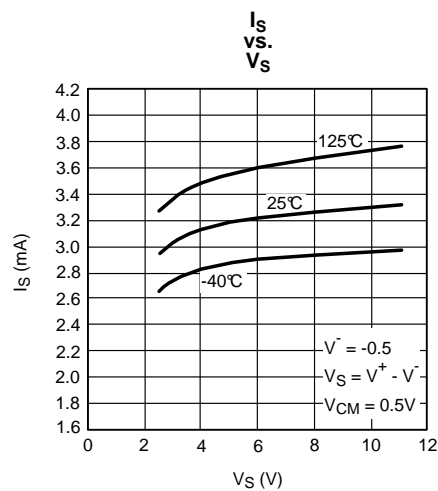


Figure 42.

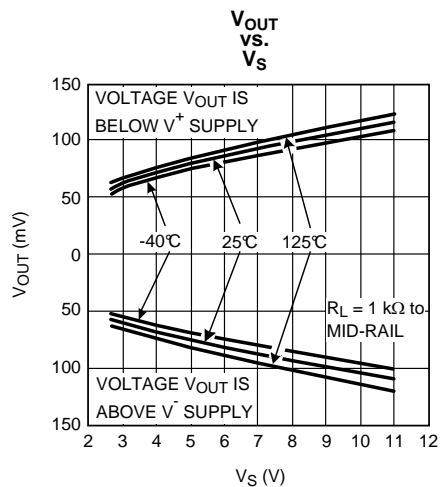


Figure 43.

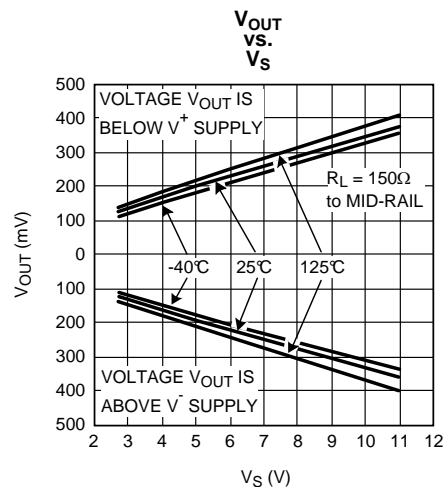


Figure 44.



## Typical Performance Characteristics (continued)

At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

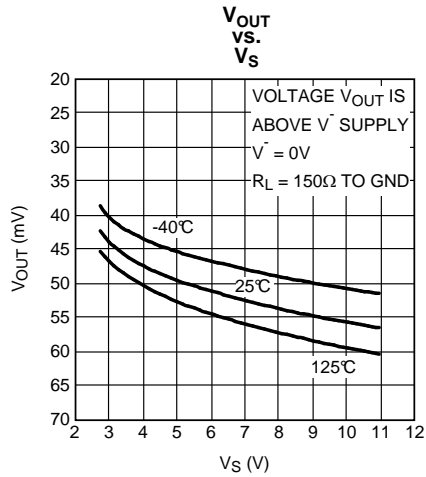


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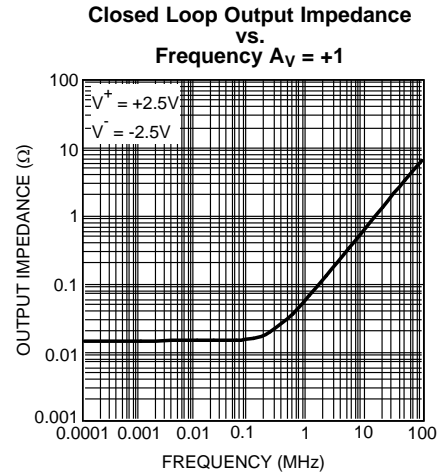


Figure 46.

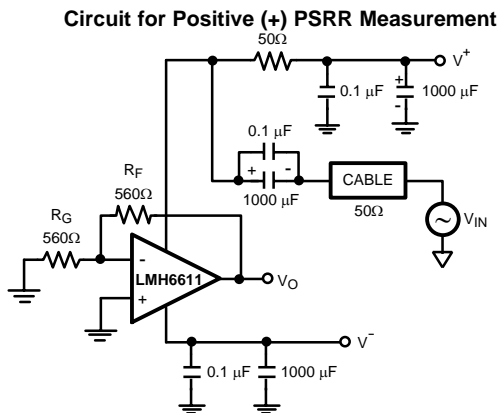


Figure 47.

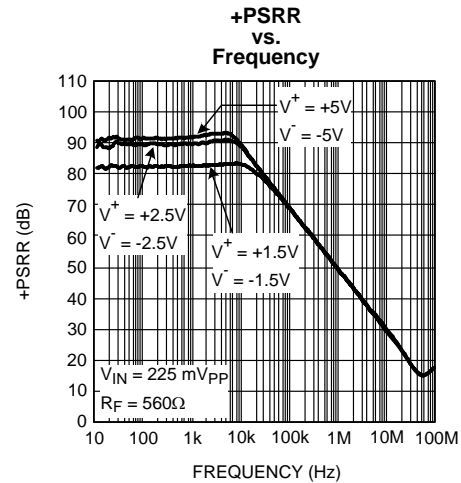


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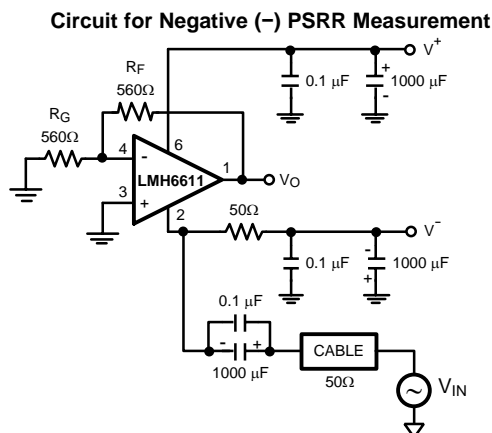


Figure 49.

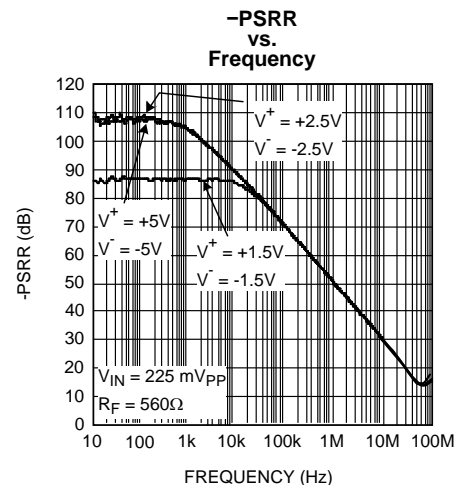


Figure 50.

### Typical Performance Characteristics (continued)

At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

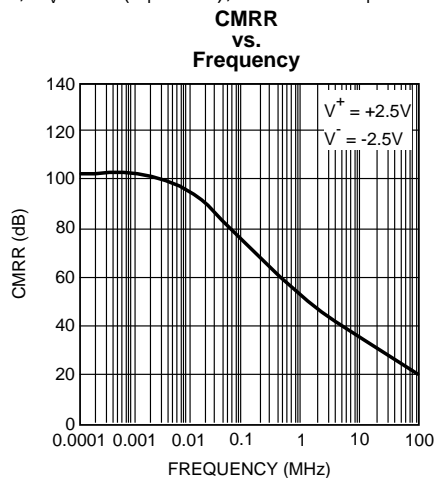


Figure 51.

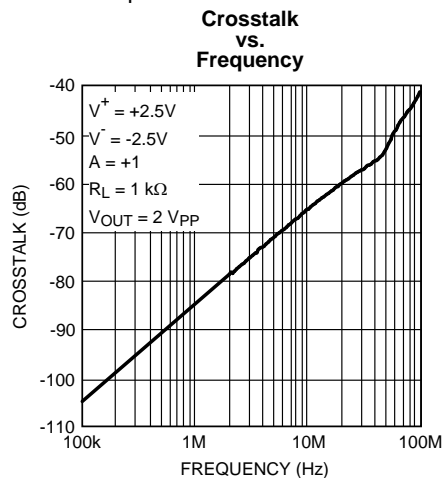


Figure 52.

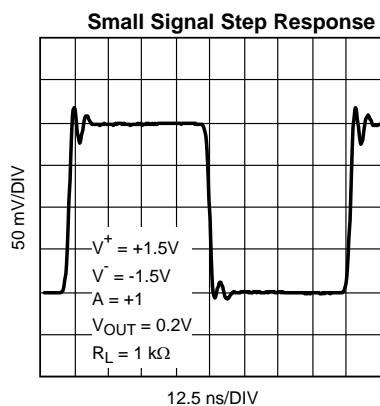


Figure 53.

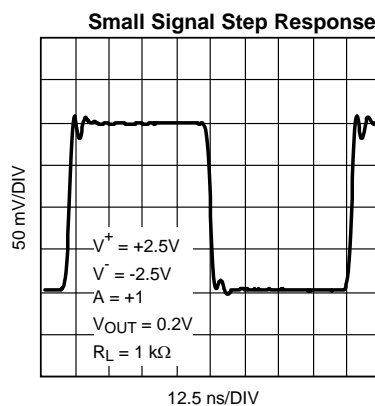


Figure 54.

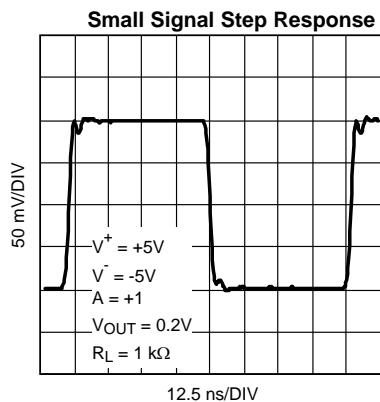


Figure 55.

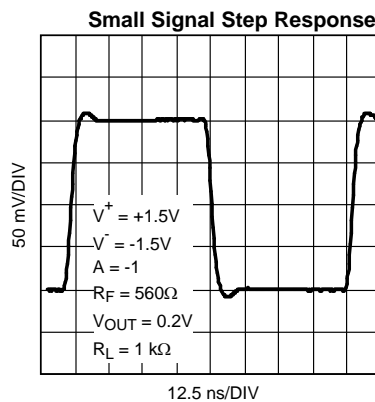
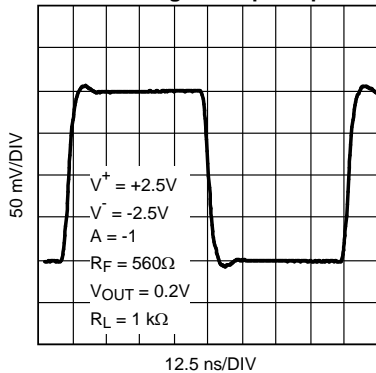


Figure 56.

## Typical Performance Characteristics (continued)

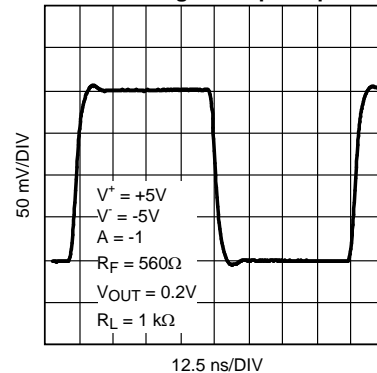
At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

**Small Signal Step Response**



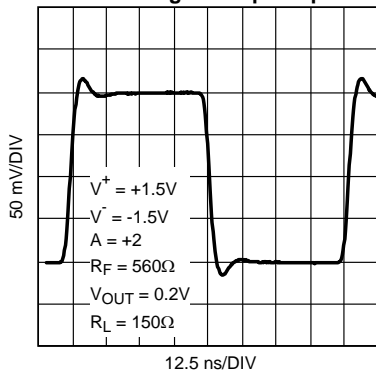
**Figure 57.**

**Small Signal Step Response**



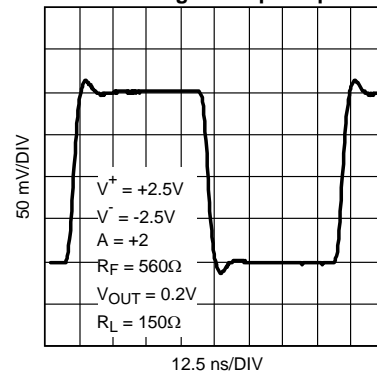
**Figure 58.**

**Small Signal Step Response**



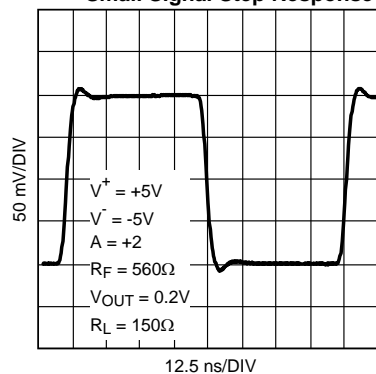
**Figure 59.**

**Small Signal Step Response**



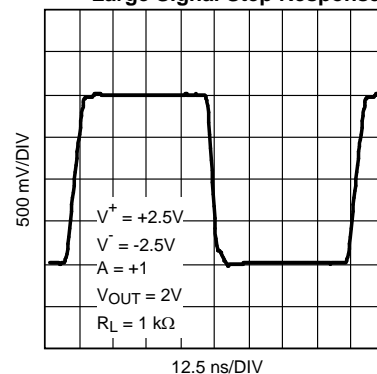
**Figure 60.**

**Small Signal Step Response**



**Figure 61.**

**Large Signal Step Response**



**Figure 62.**

### Typical Performance Characteristics (continued)

At  $T_J = 25^\circ\text{C}$ ,  $A_V = +1$  ( $R_F = 0\Omega$ ), otherwise  $R_F = 560\Omega$  for  $A_V \neq +1$ , unless otherwise specified.

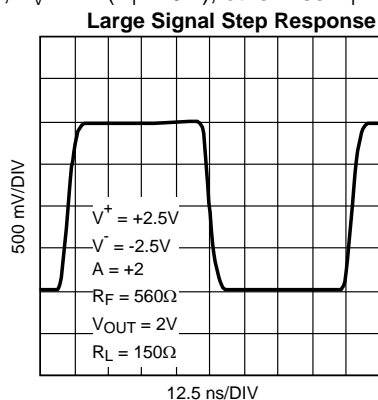


Figure 63.

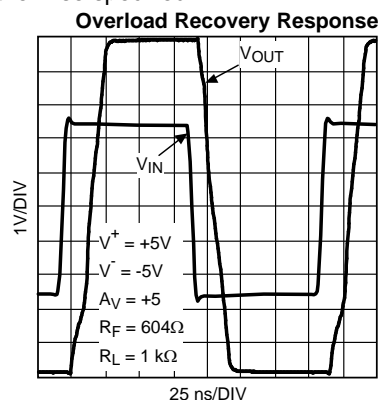


Figure 64.

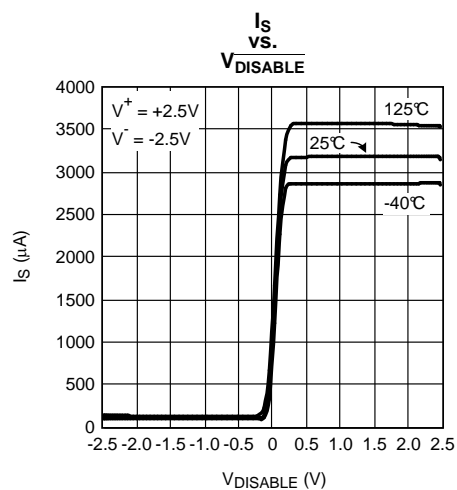


Figure 65.

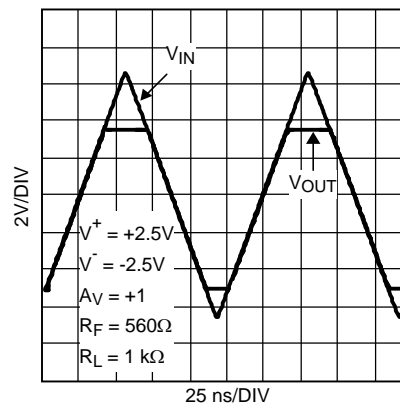
## APPLICATION INFORMATION

The LMH6611 and LMH6612 are based on proprietary VIP10 dielectrically isolated bipolar process. This device family architecture features the following:

- Complimentary bipolar devices with exceptionally high  $f_t$  (~8 GHz) even under low supply voltage (2.7V) and low bias current.
- Common emitter push-push output stage. This architecture allows the output to reach within millivolts of either supply rail.
- Consistent performance with little variation from any supply voltage (2.7V - 11V) for the most important specifications (BW, SR,  $I_{OUT}$ , for example.)
- Significant power saving compared to competitive devices on the market with similar performance.

With 3V supplies and a common mode input voltage range that extends beyond either supply rail, the LMH6611 is well suited to many low voltage/low power applications. Even with 3V supplies, the -3 dB BW (at  $A_V = +1$ ) is typically 305 MHz.

The LMH6611 and LMH6612 are designed to avoid output phase reversal. With input overdrive, the output is kept near the supply rail (or as close to it as mandated by the closed loop gain setting and the input voltage). [Figure 66](#) shows the input and output voltage when the input voltage significantly exceeds the supply voltages.



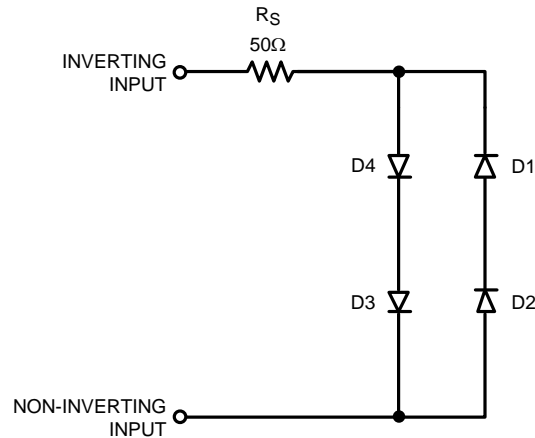
**Figure 66. Input and Output Shown with CMVR Exceeded**

If the input voltage range is exceeded by more than a diode drop beyond either rail, the internal ESD protection diodes will start to conduct. The current flow in these ESD diodes should be externally limited.

## SHUTDOWN CAPABILITY AND TURN ON/OFF BEHAVIOR

The LMH6611 can be shutdown by connecting the  $\overline{\text{DISABLE}}$  pin to a voltage 0.5V below the supply midpoint which will reduce the supply current to typically 120  $\mu\text{A}$ . The  $\overline{\text{DISABLE}}$  pin is "active low" and can be connected through a resistor to  $V^+$  or left floating for normal operation. Shutdown is specified when the  $\overline{\text{DISABLE}}$  pin is 0.5V below the supply midpoint at any operating supply voltage and temperature. Typical turn on time is 20 ns and the turn off time is 60 ns.

In the shutdown mode, essentially all internal device biasing is turned off in order to minimize supply current flow and the output goes into high impedance mode. During shutdown, the input stage has an equivalent circuit as shown in [Figure 67](#).



**Figure 67. Input Equivalent Circuit During Shutdown**

When the LMH6611 is shutdown, there may be current flow through the internal diodes shown, caused by input potential, if present. This current may flow through the external feedback resistor and result in an apparent output signal. In most shutdown applications the presence of this output is inconsequential. However, if the output is “forced” by another device, the other device will need to conduct the current described in order to maintain the output potential.

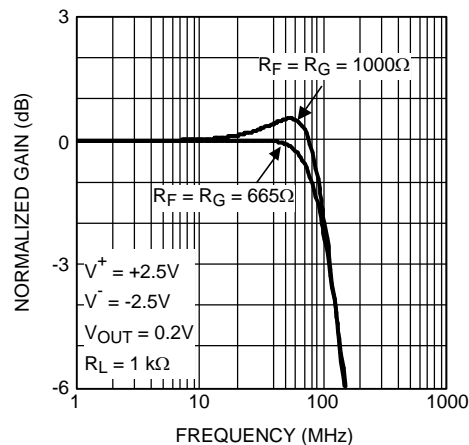
To keep the output at or near ground during shutdown when there is no other device to hold the output low, a switch using a transistor can be used to shunt the output to ground.

### SELECTION OF $R_F$ AND EFFECT ON STABILITY AND PEAKING

The peaking of the LMH6611 depends on the value of the  $R_F$ . From the graph shown in Figure 68, as the  $R_F$  value increases, the peaking increases.

For  $A_V = 2$ , at  $R_F = 1\text{ k}\Omega$ , the  $-3\text{ dB}$  bandwidth is 113 MHz and peaking is about 0.6 dB whereas at  $R_F = 665\Omega$ , the  $-3\text{ dB}$  bandwidth is about 110 MHz and peaking is 0 dB.  $R_F$  and the input capacitance form a pole in the amplifier’s response. If the time constant is too big, it will cause peaking and ringing.

Except for  $A_V = 1$  when  $R_F$  should be  $0\Omega$ , across all other gain settings it is recommended that  $R_F$  remain between  $500\Omega$  and  $1\text{ k}\Omega$  to ensure optimum performance.



**Figure 68. Closed Loop Gain vs. Frequency and  $R_F = R_G$**

$R_F = R_G$	f -3 dB (MHz)	Peaking (dB)
665	110	0
1000	113	0.6

## MINIMIZING NOISE

With a low input voltage noise of  $10 \text{ nV}/\sqrt{\text{Hz}}$  and an input current noise of  $2 \text{ pA}/\sqrt{\text{Hz}}$  the LMH6611 and LMH6612 are suitable for high accuracy applications. Still being able to reduce the frequency band of operation of the various noise sources (that is, op amp noise voltage, resistor thermal noise, input noise current) can further improve the noise performance of a system. In a non-inverting amplifier configuration inserting a capacitor,  $C_G$ , in series with the gain setting resistor,  $R_G$ , will reduce the gain of the circuit below frequency,  $f = 1/2\pi R_G C_G$ . This can be set to reduce the contribution of noise from the  $1/f$  region. Alternatively applying a feedback capacitor,  $C_F$ , in parallel with the feedback resistor,  $R_F$ , will introduce a pole into your system at  $f = 1/2\pi R_F C_F$  and create a low pass filter. This filter can be set to reduce high frequency noise and harmonics. Finally remember to keep resistor values as small as possible for a given application in order to reduce resistor thermal noise.

## POWER SUPPLY BYPASS

Since the LMH6611 and LMH6612 are wide bandwidth amplifiers, proper power supply bypassing is critical for optimum performance. Improper power supply bypassing can result in large overshoot, ringing or oscillation.  $0.1 \mu\text{F}$  capacitors should be connected from the supply pins,  $V^+$  and  $V^-$ , to ground, as close to the device as is practical. Additionally, a  $10 \mu\text{F}$  electrolytic capacitor should be connected from both supply pins to ground reasonably close to the device. Finally, near the device a  $0.1 \mu\text{F}$  ceramic capacitor between the supplies will provide the best harmonic distortion performance.

## INTERFACING HIGH PERFORMANCE OP AMPS WITH ADCs

These amplifiers are designed for ease of use in a wide range of applications requiring high speed, low supply current, low noise, and the ability to drive complex ADC and video loads.

The source that drives the modern high resolution analog-to-digital converters (ADCs) sees a high frequency AC load and a DC load of a few hundred ohms or more. Thus, a high performance op amp with high input impedance of a few mega ohms and low output impedance would be an ideal choice as an input ADC driver. The LMH6611/LMH6612 have the low output impedance of  $0.07\Omega$  at  $f = 1 \text{ MHz}$ . The ADC driver acts as a buffer and a low pass filter to reduce the overall system noise. To utilize the full dynamic range of the ADC, the ADC input has to be driven to full scale input voltage.

As signals travel through the traces of a printed circuit board (PCB) and long cables, system noise accumulates in the signals and a differential ADC rejects any signals noise that appears as a common mode voltage. There are a couple of advantages to using differential signals rather than single-ended signals. First, differential signals double the dynamic range of the ADC and second, they offer better harmonic distortion performance. There are several ways to produce differential signals from a dual op amp configuration. One method is to utilize the single-ended to differential conversion technique and the other is the differential to differential conversion technique. The first method requires a single input source and the second method requires differential input source.

A real world input source can have non-ideal impedance thus the buffer amplifier, with very low output impedance, is required to drive the input of the ADC. To minimize the droop in the input voltage, external shunt capacitance ( $C_L$ ) should be about ten times larger than the internal input capacitance of the ADC and external series resistance ( $R_L$ ) should be large enough to maintain the phase delay at the output of the op amp and hence maintain the stability (See [Figure 69](#)). Most applications benefit from the inclusion of a series isolation resistor connected between the op amp output and ADC input. This series resistor helps to limit the output current of the op amp. The value chosen for this series resistor is very important, as a higher value will increase the load impedance seen by the op amp and improve the total harmonic distortion (THD) performance of the op amp; however, the ADC prefers a low impedance source driving it. Thus, the optimum value for this series resistor must be found so that it will offer the best performance in terms of THD, SNR and SFDR of the combined op amp and ADC.

## Important Specifications of Op Amp and ADC

When interfacing an ADC with an op amp it is imperative to understand the specifications that are important to get the expected performance results. Modern ADC AC specifications such as THD, SNR, settling time and SFDR are critical for filtering, test and measurement, video and reconstruction applications. The high performance op amp's settling time, THD, and noise performance must be better than that of the ADC it is driving to maintain the proper system accuracy with minimal or no error.

Some system applications require low THD, low SFDR and wide dynamic range (SNR), whereas some system applications require high SNR and they may sacrifice THD and SFDR to focus on the noise performance.

Noise is a very important specification for both the op amp and the ADC. There are three main sources of noise that contribute to the overall performance of the ADC: Quantization noise, noise generated by the ADC itself (particularly at higher frequencies) and the noise generated by the application circuit. The impedance of the input source affects the noise performance of the op amp. Theoretically, an ADC's signal to noise ratio (SNR) can be found from the equation:

$$\text{SNR (in dB)} = 6.02 \cdot N + 1.72 \quad (1)$$

where N is the resolution of the ADC. For example, according to this equation a 12-bit ADC has an SNR of 74 dB. However, the practical SNR number would be about 72 dB. In order to achieve better SNR, the ADC driver noise should be as small as possible. The LMH6611/LMH6612 have the low voltage noise of only 10 nV/√Hz.

The combined settling time of the op amp and the ADC must be within 1 LSB. The 0.01% settling time of the LMH6611/LMH6612 is 100 ns.

The ADC driver's THD should be inherently lower than that of the ADC. The LMH6611/LMH6612 have an SFDR of 96 dBc at 2 V<sub>PP</sub> output and 1 MHz input frequency.

Signal to Noise and Distortion (SINAD) is a parameter which is the combination of the SNR and THD specifications. SINAD is defined as the RMS value of the output signal to the RMS value of all of the other spectral components below half the clock frequency, including harmonics but excluding DC. It can be calculated from SNR and THD according to the equation:

$$\text{SINAD} = 20 \cdot \text{LOG} \sqrt{\frac{-\text{SNR}}{10^{10}} + \frac{\text{THD}}{10^{10}}} \quad (2)$$

Because SINAD compares all undesired frequency components with the input frequency, it is an overall measure of an ADC's dynamic performance. The following sections will discuss the three different ADC driver architectures in detail.

## SINGLE TO SINGLE ADC DRIVER

This architecture has a single-ended input source connected to the input of the op amp and the single-ended output of the op amp is then fed to the single-ended input of the ADC. The low noise of only 10 nV/√Hz and a wide bandwidth of 345 MHz make the LMH6611 an excellent choice for driving the 12-bit ADC121S101 500 KSPS to 1 MSPS ADC, which has a successive approximation architecture with internal sample and hold circuits. [Figure 67](#) shows the schematic of the LMH6611 in a 2nd order multiple-feedback with gain of -1 (inverting) configuration, driving an ADC121S101. The inverting configuration is preferred over the non-inverting configuration, as it offers more linear output response. [Table 1](#) shows the performance data of the LMH6611 combined with the ADC121S101. The ADC driver's cutoff frequency of 500 kHz is found from the equation:

$$f_0 = \frac{1}{2\pi} \times \sqrt{\frac{1}{R_2 \times R_5 \times C_2 \times C_5}} \quad (3)$$

The op amp's gain is set by the equation:

$$\text{GAIN} = - \frac{R_2}{R_1} \quad (4)$$



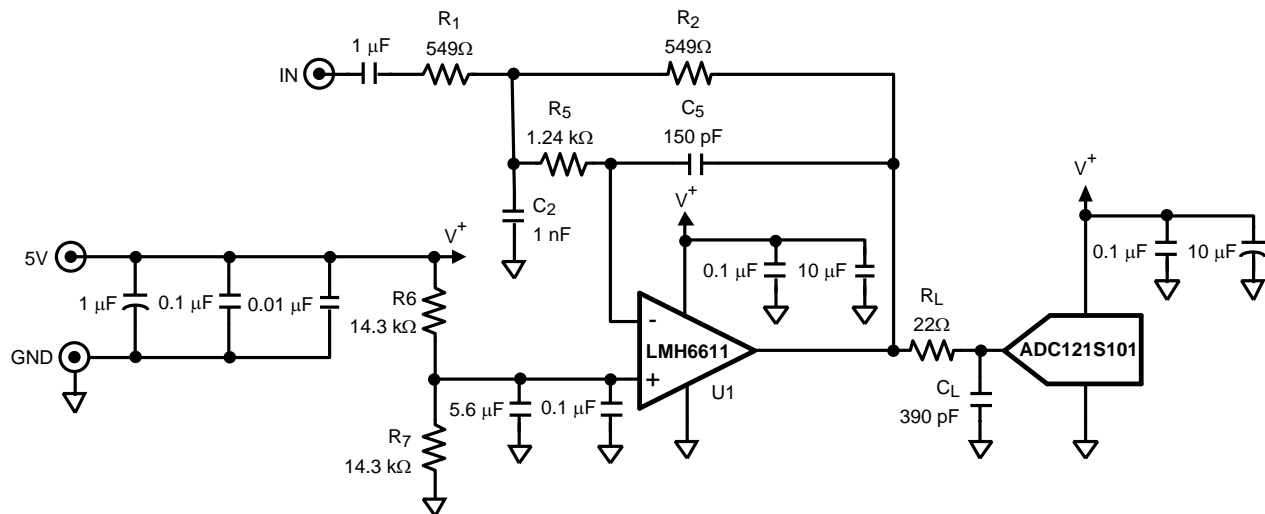


Figure 69. Single to Single ADC Driver

Table 1. Performance of the LMH6611 Combined with the ADC121S101

Amplifier Output/ADC Input	SINAD	SNR	THD	SFDR	ENOB	Notes
	(dB)	(dB)	(dB)	(dBc)		
4	70.2	71.6	-75.7	77.6	11.4	ADC121S101 @ f = 200 kHz

When the op amp and the ADC are using the same supply, it is important that both devices are well bypassed. A 0.1 μF ceramic capacitor and a 10 μF tantalum capacitor should be located as close as possible to each supply pin. A sample layout is shown in Figure 70. The 0.1 μF capacitors (C13 and C6) and the 10 μF capacitors (C11 and C5) are located very close to the supply pins of the LMH6611 and the ADC121S101.

The following are recommendations for the design of PCB layout in order to obtain the optimum high frequency performance:

- Place ADC and amplifier as close together as possible.
- Put the supply bypassing capacitors as close as possible to the device (<1").
- Utilize surface mount instead of through-hole components and ground and power planes.
- Keep the traces short where possible.
- Use terminated transmission lines for long traces.

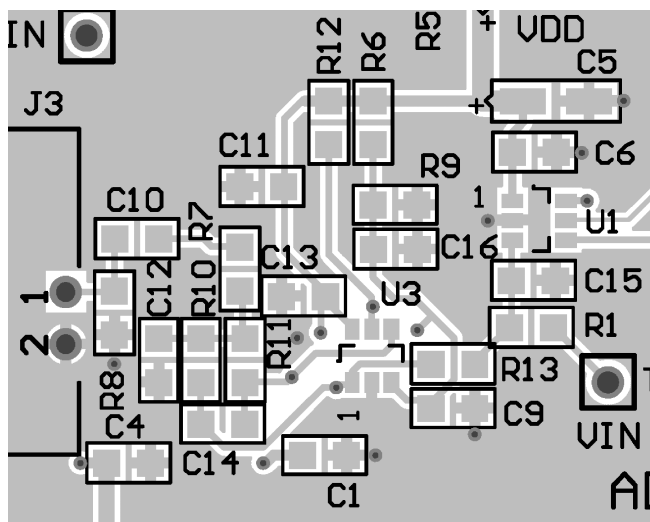


Figure 70. LMH6611 and ADC121S101 Layout

## SINGLE-ENDED TO DIFFERENTIAL ADC DRIVER

The single-ended to differential ADC driver in Figure 68 utilizes an LMH6612 dual op amp to buffer a single-ended source to drive an ADC with differential inputs. One of the op amps is configured as a unity gain buffer that drives the inverting (IN-) input of the op amp U2 and non-inverting (IN+) input of the ADC121S625. U2 inverts the input signal and drives the inverting input of the ADC121S625. The ADC driver is configured for a gain of +2 to reduce the noise without sacrificing THD performance. The common mode voltage of 2.5V is set up at the non-inverting inputs of both op amps U1 and U2. This configuration produces differential  $\pm 2.5 V_{PP}$  output signals, when the single-ended input signal of 0 to  $V_{REF}$  is AC coupled into the non-inverting terminal of the op amp and each non-inverting terminal of the op amp is biased at the mid-scale of 2.5V. The two output RC anti-aliasing filters are used between both the outputs of U1 and U2 and the input of the ADC121S625 to minimize the effect of undesired high frequency noise coming from the input source. Each RC filter has the cutoff frequency of approximately 22 MHz.

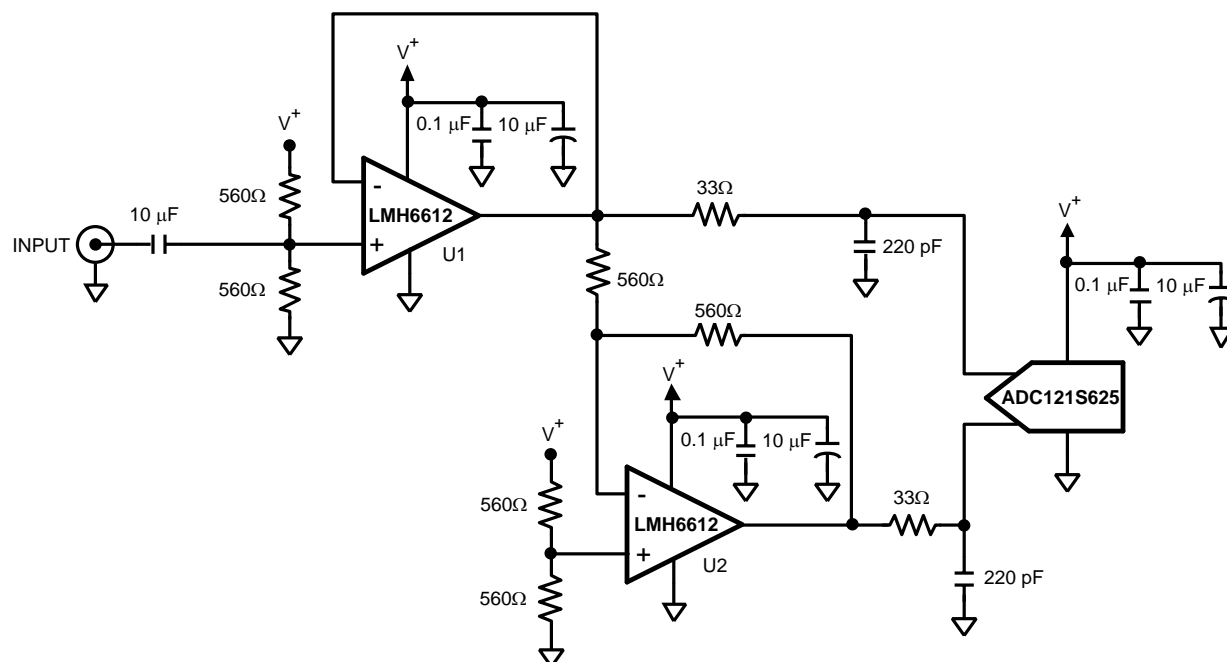


Figure 71. Single-Ended to Differential ADC Driver

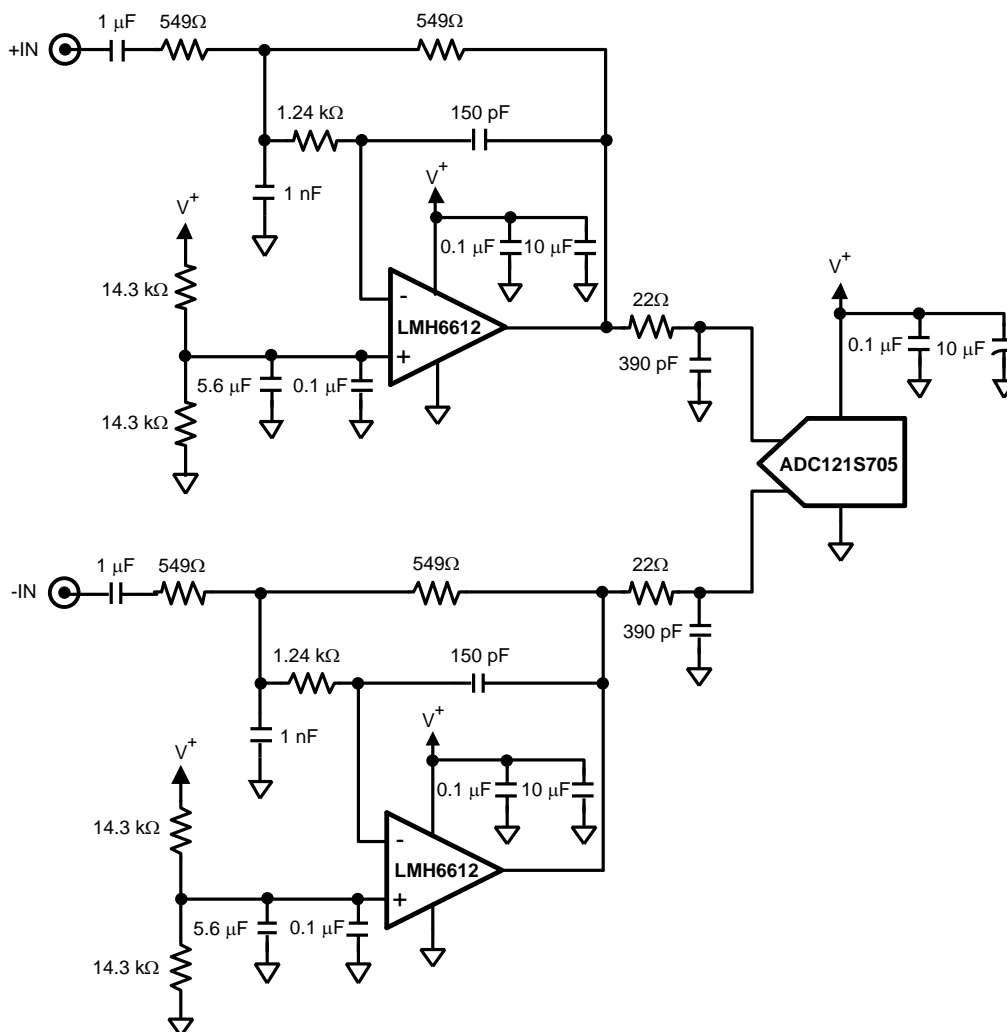
The performance of the LMH6612 with the ADC121S625 is shown in [Table 2](#).

**Table 2. Performance of the LMH6612 Combined with the ADC121S625**

Amplifier Output/ADC Input	SINAD	SNR	THD	SFDR	ENOB	Notes
	(dB)	(dB)	(dB)	(dBc)		
2.5	68.8	69	-81.5	75.1	11.2	ADC121S625 @ f = 20 kHz

## DIFFERENTIAL TO DIFFERENTIAL ADC DRIVER

The LMH6612 dual op amp can be configured as a differential to differential ADC driver to buffer a differential source to a differential input ADC as shown in [Figure 72](#). The differential to differential ADC driver can be formed using two single to single ADC drivers. Each output from these drivers goes to a separate input of the differential ADC. Here, each single to single ADC driver uses the same components and is configured for a gain of -1 (inverting).

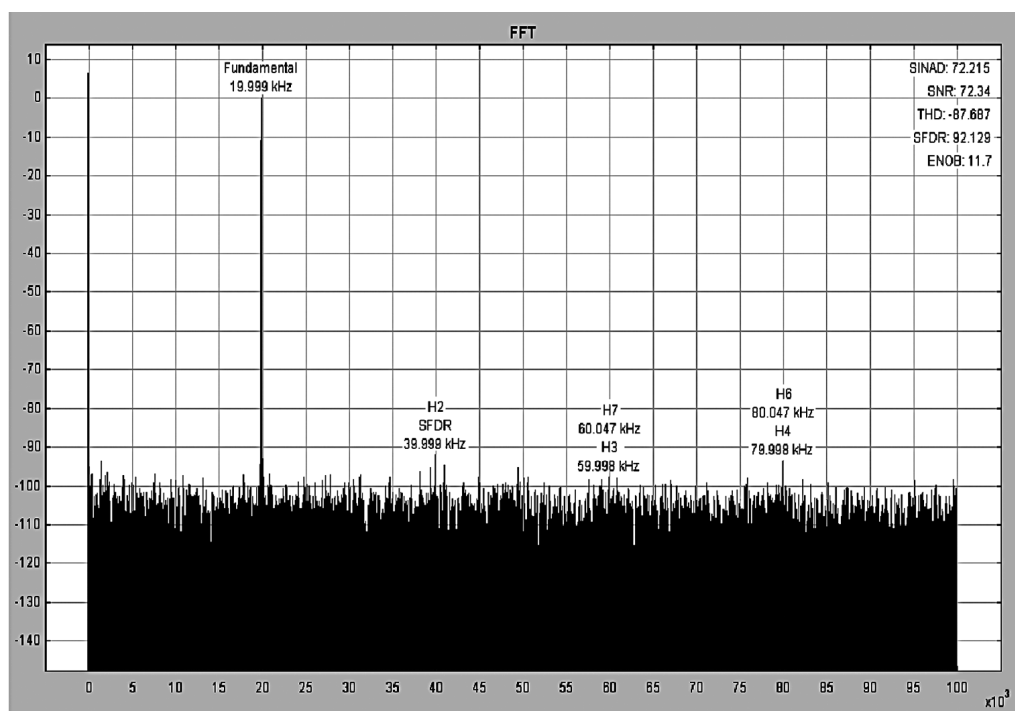


**Figure 72. Differential to Differential ADC Driver**

The following table summarizes the performance of the LMH6612 combined with the ADC121S625 at two different frequencies. In order to utilize the full dynamic range of the ADC, the maximum input of 2.5 V<sub>PP</sub> is applied to the ADC input. [Figure 73](#) shows the FFT plot of the LMH6612 and ADC121S625 combination tested at f = 20 kHz input frequency.

**Table 3. Performance of the LMH6612 Combined with the ADC121S625**

Amplifier Output/ADC Input	SINAD	SNR	THD	SFDR	ENOB	Notes
	(dB)	(dB)	(dB)	(dBc)		
2.5	72.2	72.3	-87.7	92.1	11.7	ADC121S625 @ f = 20 kHz
2.5	72.2	72.2	-87.8	90.8	11.7	ADC121S625 @ f = 200 kHz

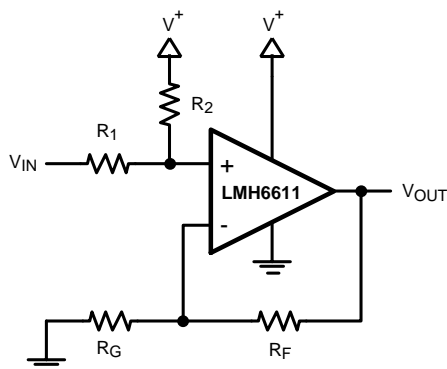
**Figure 73. The FFT Plot of Differential to Differential ADC Driver**

## DC LEVEL SHIFTING

Often a signal must be both amplified and level shifted while using a single supply for the op amp. The circuit in [Figure 74](#) can do both of these tasks. The procedure for specifying the resistor values is as follows.

1. Determine the input voltage.
2. Calculate the input voltage midpoint,  $V_{INMID} = V_{INMIN} + (V_{INMAX} - V_{INMIN})/2$ .
3. Determine the output voltage needed.
4. Calculate the output voltage midpoint,  $V_{OUTMID} = V_{OUTMIN} + (V_{OUTMAX} - V_{OUTMIN})/2$ .
5. Calculate the gain needed,  $gain = (V_{OUTMAX} - V_{OUTMIN})/(V_{INMAX} - V_{INMIN})$
6. Calculate the amount the voltage needs to be shifted from input to output,  $\Delta V_{OUT} = V_{OUTMID} - gain \times V_{INMID}$ .
7. Set the supply voltage to be used.
8. Calculate the noise gain,  $noise\ gain = gain + \Delta V_{OUT}/V_S$ .
9. Set  $R_F$ .
10. Calculate  $R_1$ ,  $R_1 = R_F/gain$ .
11. Calculate  $R_2$ ,  $R_2 = R_F/(noise\ gain - gain)$ .
12. Calculate  $R_G$ ,  $R_G = R_F/(noise\ gain - 1)$ .

Check that both the  $V_{IN}$  and  $V_{OUT}$  are within the voltage ranges of the LMH6611.



**Figure 74. DC Level Shifting**

The following example is for a  $V_{IN}$  of 0V to 1V with a  $V_{OUT}$  of 2V to 4V.

1.  $V_{IN} = 0V$  to  $1V$
2.  $V_{INMID} = 0V + (1V - 0V)/2 = 0.5V$
3.  $V_{OUT} = 2V$  to  $4V$
4.  $V_{OUTMID} = 2V + (4V - 2V)/2 = 3V$
5.  $Gain = (4V - 2V)/(1V - 0V) = 2$
6.  $\Delta V_{OUT} = 3V - 2 \times 0.5V = 2$
7. For the example the supply voltage will be +5V.
8.  $Noise\ gain = 2 + 2/5V = 2.4$
9.  $R_F = 2\ k\Omega$
10.  $R_1 = 2\ k\Omega/2 = 1\ k\Omega$
11.  $R_2 = 2\ k\Omega/(2.4 - 2) = 5\ k\Omega$
12.  $R_G = 2\ k\Omega/(2.4 - 1) = 1.43\ k\Omega$

#### 4<sup>th</sup> ORDER MULTIPLE FEEDBACK LOW-PASS FILTER

Figure 75 shows the LMH6612 used as the amplifier in a multiple feedback low pass filter. This filter is set up to have a gain of +1 and a -3 dB point of 1 MHz. Values can be determined by using the WEBENCH® Active Filter Designer found at [www.ti.com/amplifiers](http://www.ti.com/amplifiers)

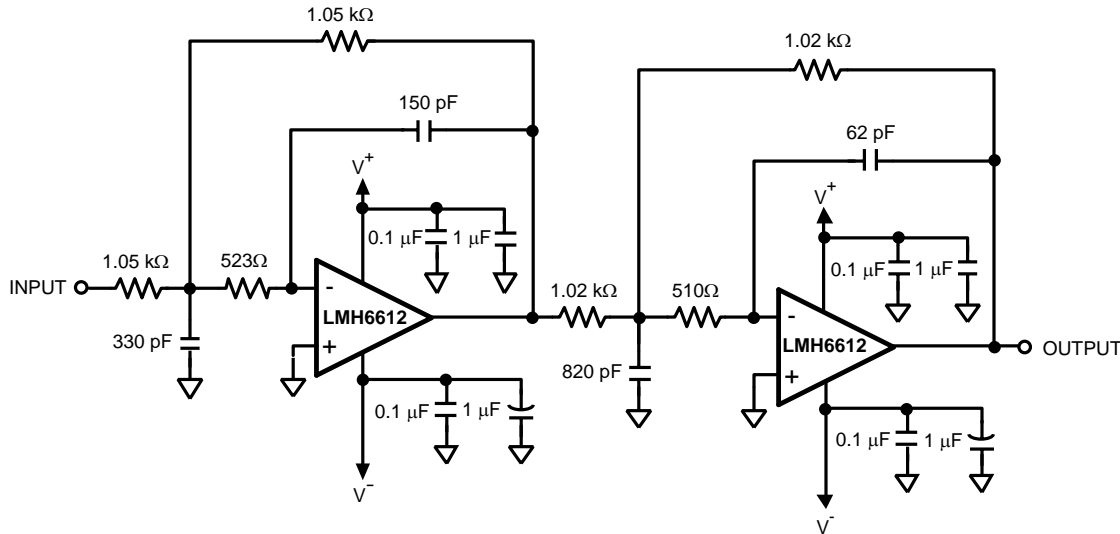


Figure 75. 4<sup>th</sup> Order Multiple Feedback Low-Pass Filter

#### CURRENT SENSE AMPLIFIER AND OPTIMIZING ACCURACY IN PRECISION APPLICATIONS

With its rail-to-rail output capability, low  $V_{OS}$ , and low  $I_B$  the LMH6611 is an ideal choice for a current sense amplifier application. Figure 76 shows the schematic of the LMH6611 set up in a low-side sense configuration which provides a conversion gain of 2V/A. Voltage error due to  $V_{OS}$  can be calculated to be  $V_{OS} \times (1 + R_F/R_G)$  or  $1.5 \text{ mV} \times 21 = 31.5 \text{ mV}$ . Voltage error due to  $I_O$  is  $I_O \times R_F$  or  $0.5 \mu\text{A} \times 1 \text{ k}\Omega = 0.5 \text{ mV}$ . Hence worst case total voltage error is  $12.6 \text{ mV} + 0.5 \text{ mV}$  or  $13.1 \text{ mV}$  which translates into a current error of  $13.1 \text{ mV} / (2 \text{ V/A}) = 6.55 \text{ mA}$ .

This circuit employs DC source resistance matching at the two input terminals in order to minimize the output DC error caused by input bias current. Another technique to reduce output offset in a non-inverting amplifier configuration is to introduce a DC offset current into the inverting input of the amplifier. To ensure minimal impact on frequency response be sure to inject the DC offset current through large resistors. Conversely if optimizing an inverting amplifier configuration simply apply offset adjustment to the non-inverting input.

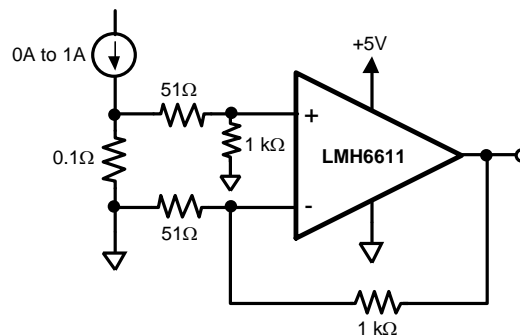


Figure 76. Current Sense Amplifier

## TRANSIMPEDANCE AMPLIFIER

By definition, a photodiode produces either a current or voltage output from exposure to a light source. A Transimpedance Amplifier (TIA) is utilized to convert this low-level current to a usable voltage signal. The TIA often will need to be compensated to insure proper operation.

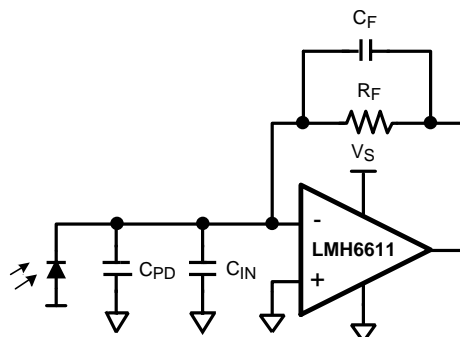


Figure 77. Photodiode Modeled with Capacitance Elements

Figure 77 shows the LMH6611 modeled with photodiode and the internal op amp capacitances. The LMH6611 allows circuit operation of a low intensity light due to its low input bias current by using larger values of gain ( $R_F$ ). The total capacitance ( $C_T$ ) on the inverting terminal of the op amp includes the photodiode capacitance ( $C_{PD}$ ) and the input capacitance of the op amp ( $C_{IN}$ ). This total capacitance ( $C_T$ ) plays an important role in the stability of the circuit. The noise gain of this circuit determines the stability and is defined by:

$$NG = \frac{1 + sR_F(C_T + C_F)}{1 + sC_F R_F} \quad (5)$$

$$\text{Where, } f_z \cong \frac{1}{2\pi R_F C_T} \text{ and } f_p = \frac{1}{2\pi R_F C_F} \quad (6)$$

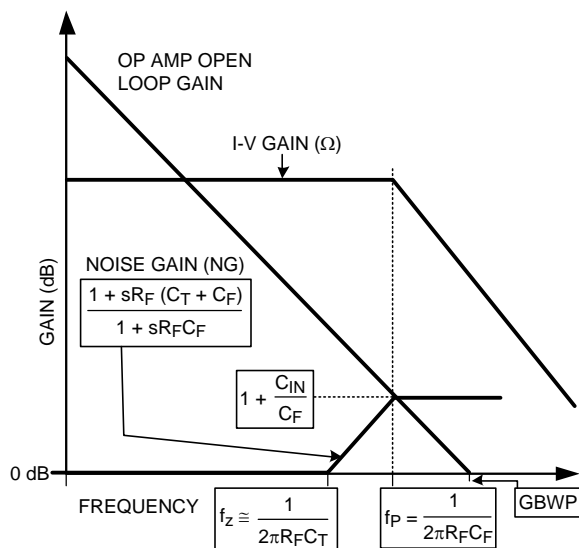


Figure 78. Bode Plot of Noise Gain Intersecting with Op Amp Open Loop Gain

Figure 78 shows the bode plot of the noise gain intersecting the op amp open loop gain. With larger values of gain,  $C_T$  and  $R_F$  create a zero in the transfer function. At higher frequencies the circuit can become unstable due to excess phase shift around the loop.

A pole at  $f_p$  in the noise gain function is created by placing a feedback capacitor ( $C_F$ ) across  $R_F$ . The noise gain slope is flattened by choosing an appropriate value of  $C_F$  for optimum performance.

Theoretical expressions for calculating the optimum value of  $C_F$  and the expected  $-3$  dB bandwidth are:

$$C_F = \sqrt{\frac{C_T}{2\pi R_F(\text{GBWP})}} \quad (7)$$

$$f_{-3\text{ dB}} = \sqrt{\frac{\text{GBWP}}{2\pi R_F C_T}} \quad (8)$$

Equation 8 indicates that the  $-3$  dB bandwidth of the TIA is inversely proportional to the feedback resistor. Therefore, if the bandwidth is important then the best approach would be to have a moderate transimpedance gain stage followed by a broadband voltage gain stage.

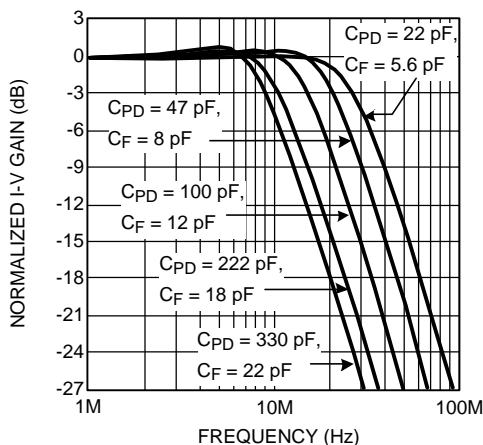
Table 4 shows the measurement results of the LMH6611 with different photodiodes having various capacitances ( $C_{PD}$ ) and a feedback resistance ( $R_F$ ) of  $1\text{ k}\Omega$ .

**Table 4. TIA (Figure 66) Compensation and Performance Results<sup>(1)</sup>**

$C_{PD}$ (pF)	$C_T$ (pF)	$C_F$ CAL (pF)	$C_F$ USED (pF)	$f_{-3\text{ dB}}$ CAL (MHz)	$f_{-3\text{ dB}}$ MEAS (MHz)	Peaking (dB)
22	24	5.42	5.6	29.3	27.1	0.5
47	49	7.75	8	20.5	21	0.5
100	102	11.15	12	14.2	15.2	0.5
222	224	20.39	18	9.6	10.7	0.5
330	332	20.2	22	7.9	9	0.8

(1)  $\text{GBWP} = 130\text{ MHz}$ ,  $C_T = C_{PD} + C_{IN}$ ,  $C_{IN} = 2\text{ pF}$ ,  $V_S = \pm 2.5\text{ V}$

Figure 79 shows the frequency response for the various photodiodes in Table 4.



**Figure 79. Frequency Response for Various Photodiode and Feedback Capacitors**

When analyzing the noise at the output of the TIA, it is important to note that the various noise sources (that is, op amp noise voltage, feedback resistor thermal noise, input noise current, photodiode noise current) do not all operate over the same frequency band. Therefore, when the noise at the output is calculated, this should be taken into account. The op amp noise voltage will be gained up in the region between the noise gain's zero and pole ( $f_z$  and  $f_p$  in Figure 78). The higher the values of  $R_F$  and  $C_T$ , the sooner the noise gain peaking starts and therefore its contribution to the total output noise will be larger. It is advantageous to minimize  $C_{IN}$  by proper choice of op amp or by applying a reverse bias across the diode but this will be at the expense of excess dark current and noise.



## EVALUATION BOARD

TI provides the following evaluation board as a guide for high frequency layout and as an aid in device testing and characterization. Many of the datasheet plots were measured with this board:

Device	Package	Board Part #
LMH6611MK	SOT	LMH730216
LMH6612MA	SOIC	LMH730036

REVISION HISTORY

Changes from Revision I (March 2013) to Revision J Page

- Changed layout of National Data Sheet to TI format ..... [33](#)

Changes from Revision J (September 2013) to Revision K Page

- Changed from 0.1 uV/°C to 4 μV/°C ..... [3](#)
- Changed from 0.1 uV/°C to 4 μV/°C ..... [5](#)
- Changed from 0.4 uV/°C to 4 μV/°C ..... [7](#)

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">LMH6611MK/NOPB</a>	Active	Production	SOT-23-THIN (DDC)   6	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	AX4A
LMH6611MK/NOPB.A	Active	Production	SOT-23-THIN (DDC)   6	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	AX4A
<a href="#">LMH6611MKE/NOPB</a>	Active	Production	SOT-23-THIN (DDC)   6	250   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	AX4A
LMH6611MKE/NOPB.A	Active	Production	SOT-23-THIN (DDC)   6	250   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	AX4A
<a href="#">LMH6611MKX/NOPB</a>	Active	Production	SOT-23-THIN (DDC)   6	3000   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	AX4A
LMH6611MKX/NOPB.A	Active	Production	SOT-23-THIN (DDC)   6	3000   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	AX4A
LMH6611MKX/NOPB.B	Active	Production	SOT-23-THIN (DDC)   6	3000   LARGE T&R	-	SN	Level-1-260C-UNLIM	-40 to 125	AX4A
<a href="#">LMH6612MA/NOPB</a>	Active	Production	SOIC (D)   8	95   TUBE	Yes	SN	Level-1-260C-UNLIM	-40 to 125	LMH6612MA
LMH6612MA/NOPB.A	Active	Production	SOIC (D)   8	95   TUBE	Yes	SN	Level-1-260C-UNLIM	-40 to 125	LMH6612MA
<a href="#">LMH6612MAX/NOPB</a>	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	LMH6612MA
LMH6612MAX/NOPB.A	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	LMH6612MA
LMH6612MAX/NOPB.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	-	SN	Level-1-260C-UNLIM	-40 to 125	LMH6612MA

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMH6611MK/NOPB	SOT-23-THIN	DDC	6	1000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMH6611MKE/NOPB	SOT-23-THIN	DDC	6	250	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMH6611MKX/NOPB	SOT-23-THIN	DDC	6	3000	178.0	8.4	3.2	3.2	1.4	4.0	8.0	Q3
LMH6612MAX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

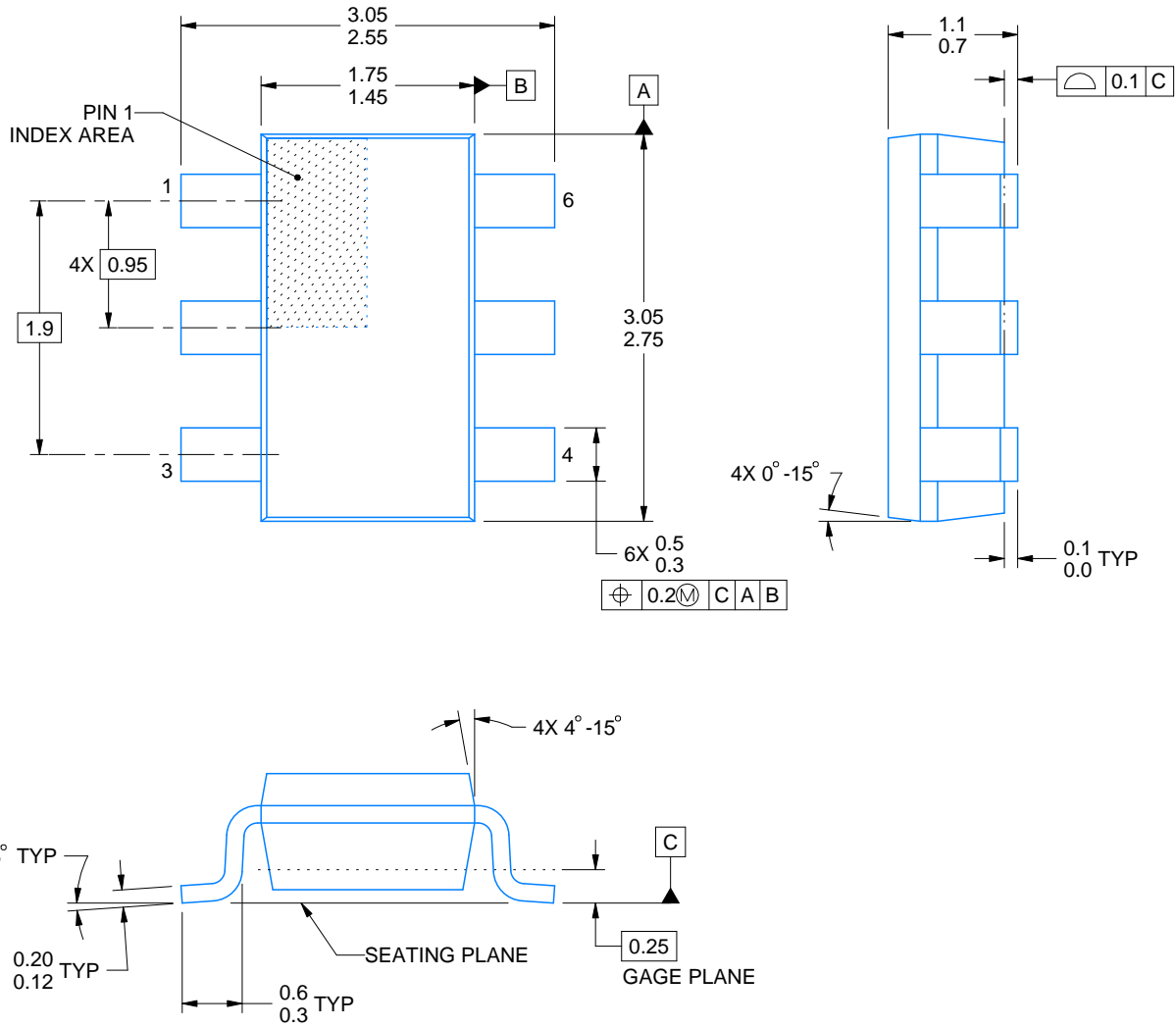
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMH6611MK/NOPB	SOT-23-THIN	DDC	6	1000	208.0	191.0	35.0
LMH6611MKE/NOPB	SOT-23-THIN	DDC	6	250	208.0	191.0	35.0
LMH6611MKX/NOPB	SOT-23-THIN	DDC	6	3000	208.0	191.0	35.0
LMH6612MAX/NOPB	SOIC	D	8	2500	367.0	367.0	35.0

## TUBE



\*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
LMH6612MA/NOPB	D	SOIC	8	95	495	8	4064	3.05
LMH6612MA/NOPB.A	D	SOIC	8	95	495	8	4064	3.05



4214841/E 08/2024

## NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. Reference JEDEC MO-193.

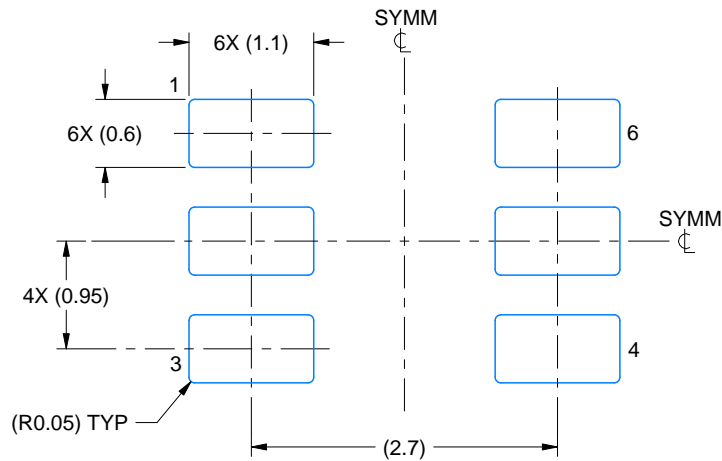


# EXAMPLE BOARD LAYOUT

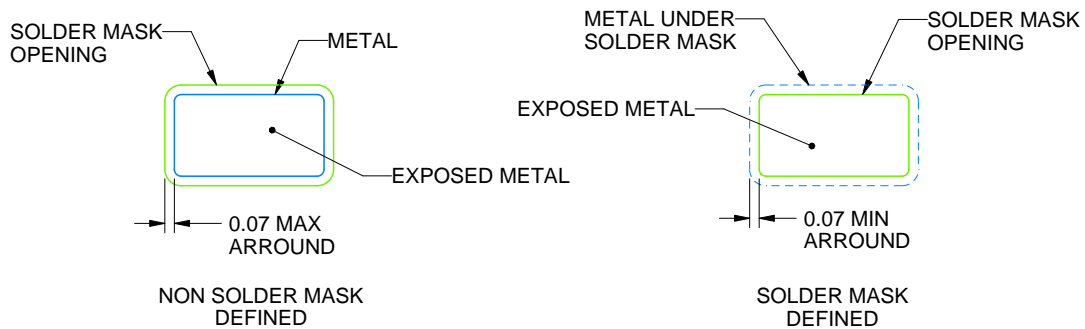
DDC0006A

SOT-23 - 1.1 max height

SMALL OUTLINE TRANSISTOR



LAND PATTERN EXAMPLE  
EXPLODED METAL SHOWN  
SCALE:15X



SOLDERMASK DETAILS

4214841/E 08/2024

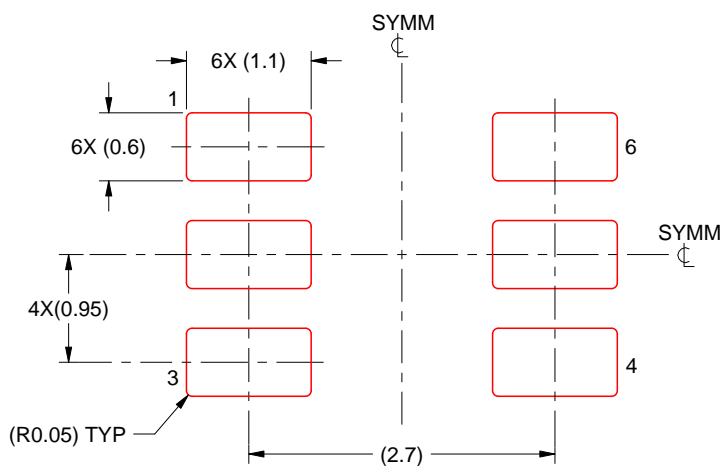
NOTES: (continued)

4. Publication IPC-7351 may have alternate designs.
5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

DDC0006A

**SOT-23 - 1.1 max height**

## SMALL OUTLINE TRANSISTOR

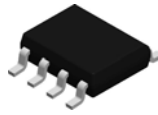


**SOLDER PASTE EXAMPLE**  
**BASED ON 0.125 THICK STENCIL**  
**SCALE:15X**

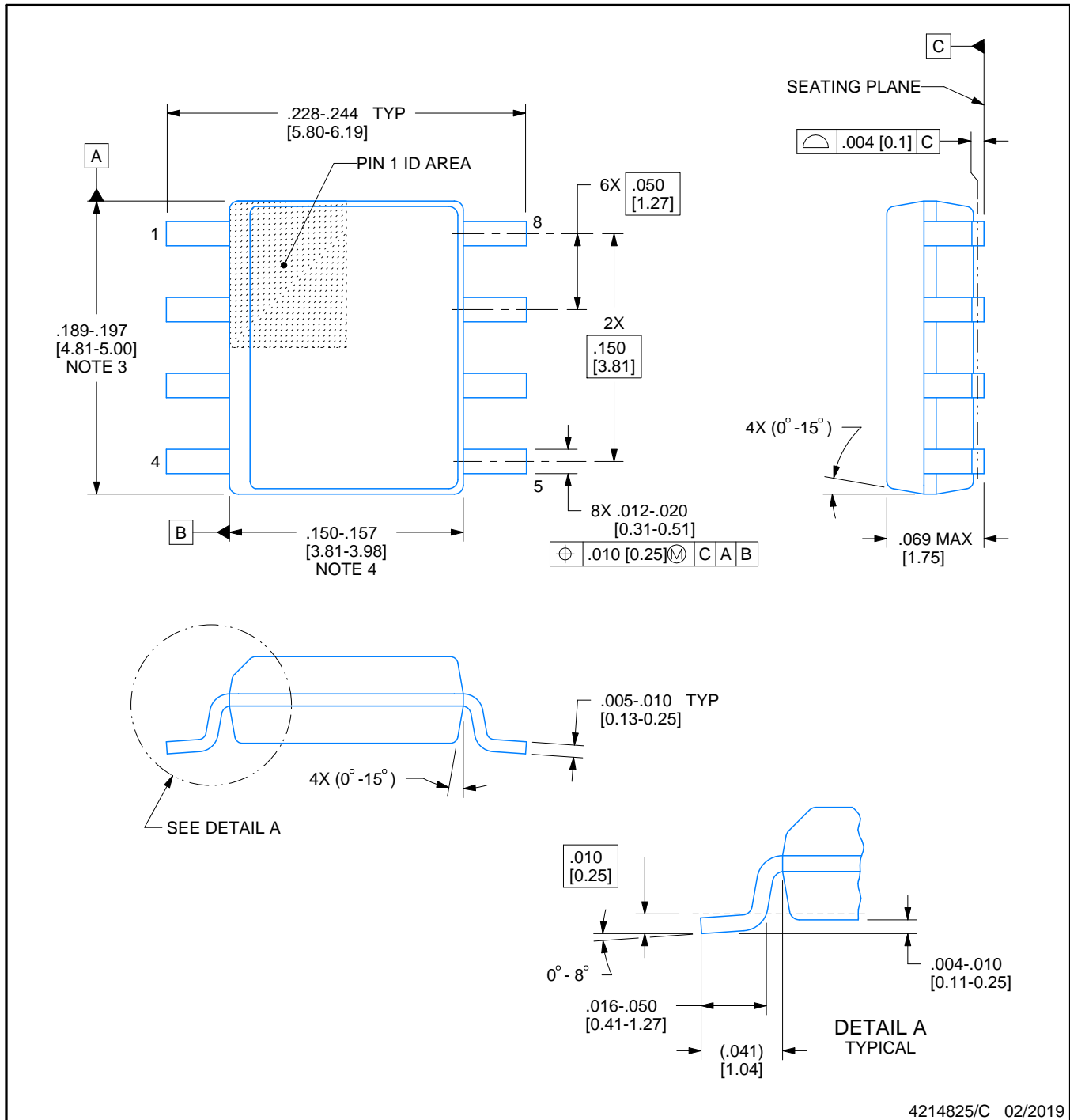
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NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
7. Board assembly site may have different recommendations for stencil design.

**D0008A****PACKAGE OUTLINE****SOIC - 1.75 mm max height**

SMALL OUTLINE INTEGRATED CIRCUIT



4214825/C 02/2019

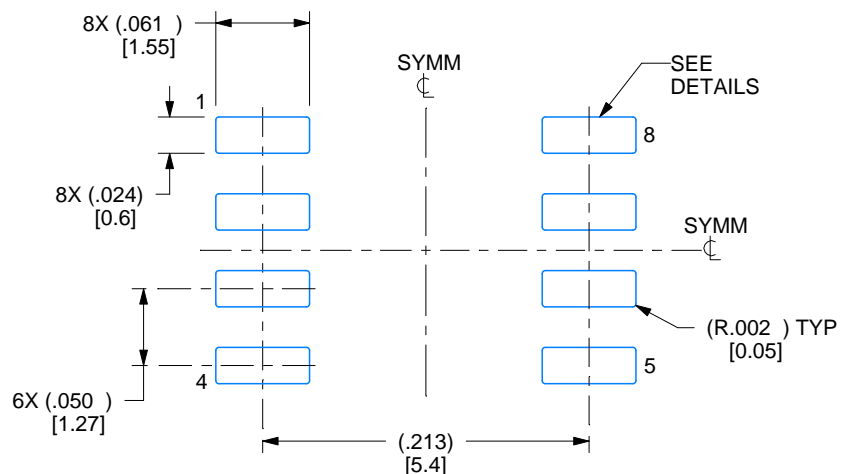
**NOTES:**

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

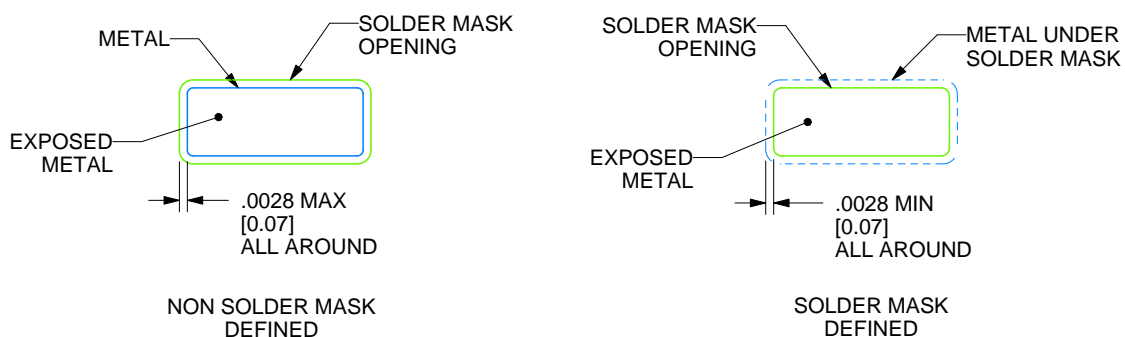
**D0008A**

### SOIC - 1.75 mm max height

## SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:8X



## SOLDER MASK DETAILS

4214825/C 02/2019

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

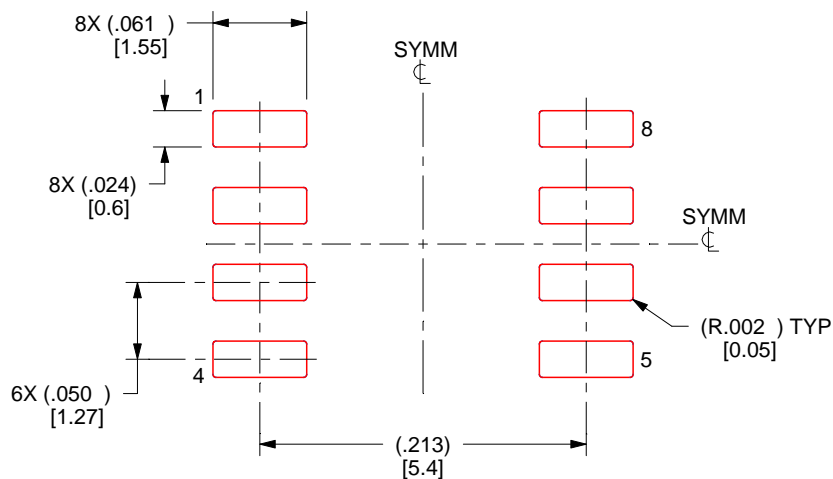
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

## EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE  
BASED ON .005 INCH [0.125 MM] THICK STENCIL  
SCALE:8X

4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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