

# LMH12x9 12G UHD Long Reach Cable Equalizer with Integrated Reclocker

### 1 Features

- Adaptive cable equalizer with integrated reclocker
- Supports ST-2082-1(12G), ST-2081-1(6G), ST-424(3G), ST-292(HD), and ST-259(SD)
- Compatible with DVB-ASI and AES10 (MADI)
- Integrated referenceless reclocker locks to SMPTE rates: 11.88Gbps, 5.94Gbps, 2.97Gbps, 1.485Gbps, or divide-by-1.001 sub-rates, 270Mbps
- Typical cable reach (Belden 1694A), PRBS-9 pattern:
  - 100m at 11.88Gbps (4Kp60 UHD)
  - 150m at 5.94Gbps (UHD)
  - 220m at 2.97Gbps (FHD)
  - 300m at 1.485Gbps (HD)
  - 600m at 270Mbps (SD)
- Typical cable reach (Belden 1694A), pathological pattern<sup>1</sup>:
  - 90m at 11.88Gbps (4Kp60 UHD)
  - 140m at 5.94Gbps (UHD)
  - 220m at 2.97Gbps (FHD)
  - 300m at 1.485Gbps (HD)
  - 600m at 270Mbps (SD)
- On-chip  $75\Omega$  termination and return loss compensation network
- Input cable equalizer and reclocker features:
  - Improved cable reach with stress patterns
  - Programmable CDR loop bandwidth settings
  - $2:1.75\Omega$  input mux (LMH1239 only)
- Output driver features:
  - 1:2  $100\Omega$  fanout output with de-emphasis
  - Reclocked 75Ω loop-through output with cable fault detection (up to 600m)
- Built-in PRBS generator and checker
- Internal eye opening monitor
- Single 2.5V supply
- Low power: 350mW (typical)
- Power Save mode: 70mW
- Configurable by control pins, SPI, or SMBus interface
- 5mm × 5mm 32-pin WQFN package
- Operating temperature range: -40°C to +85°C

## 2 Applications

- SMPTE compatible serial digital interface
- UHDTV/4K/8K/HDTV/SDTV video
- Broadcast video routers, switchers, distribution amplifiers, and monitors
- Digital video processing and editing

# 3 Description

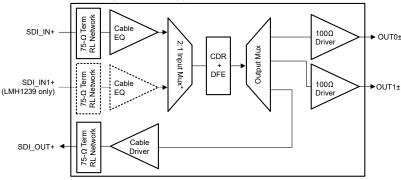
The LMH12x9 (LMH1229, LMH1239) is a long reach adaptive cable equalizer with integrated reclocker, dual outputs, and  $75\Omega$  loop-through output. The device is designed to equalize data transmitted over  $75\Omega$  coaxial cable and operates across SMPTE data rates ranging from 125Mbps to 11.88Gbps.

The adaptive equalizer at the SDI input enables automatic loss compensation for up to 100m Belden 1694A cable reach in 4K/8K video applications where 12G-SDI (11.88Gbps) is used. The integrated reclocker attenuates high frequency jitter and fully regenerates the data using a clean, low-jitter clock. The loop filter of the reclocker is adjustable with optional external capacitor to reduce the CDR loop bandwidth.

#### **Device Information**

PART NUMBER	2:1 75Ω INPUT MUX INCLUDED?	PACKAGE (1)	PACKAGE SIZE (2)
LMH1229	No	No RTV (QFN, 32)	
LMH1239	Yes	1(1 V (Q(11, 32)	5mm x 5mm

- (1) For more information, see Section 10.
- (2)The package size (length × width) is a nominal value and includes pins, where applicable.



\*2:1 Input mux is only applicable with the LMH1239 variant. For LMH1229, SDI\_IN+

#### Simplified Block Diagram

<sup>1</sup> For details about SDI pathological implementation, refer to A Study of the SDI Pathological Data Pattern application note



For routing simplicity and debug, the LMH12x9 features a 1:3 output mux consisting of two  $100\Omega$  fanouts with VOD and de-emphasis control and one  $75\Omega$  loop-through SDI output. The  $75\Omega$  loop-through output is provided to extend the signal reach or enable system-level diagnostics.

The LMH12x9 features internal integrated return loss networks that meet stringent SMPTE specifications across all data rates. The LMH12x9 also has an internal eye opening monitor and a programmable pin for CDR lock indication, input carrier detect, cable fault detection, or hardware interrupts to support system diagnostics and board bring-up.

The LMH1229 is pin compatible with the LMH1297 (12G UHD-SDI bidirectional I/O with integrated reclocker) when used in cable equalizer applications. For system-level redundancy, the LMH1239 is offered with an additional integrated SDI input mux.



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# 4 Pin Configuration and Functions

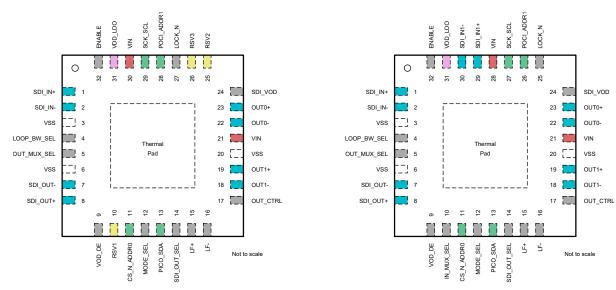


Figure 4-1. LMH1229 RTV Package, 32-Pin QFN (Top View)

Figure 4-2. LMH1239 RTV Package, 32-Pin QFN (Top View)

Legend					
High Speed Signals Serial Control Interface (SPI or SMBus) Pins Reserved Pins					
Control Pins	Power (2.5V)	LDO Output (1.8V)	GND		

**Table 4-1. Pin Functions** 

	PIN					
NAME	LMH1229 NO.	LMH1239 NO.	TYPE <sup>(1)</sup>	DESCRIPTION		
HIGH SPEED DIFF	ERENTIAL	I/Os				
SDI_IN+	1	1	I, Analog	Single-ended complementary inputs with on-chip 75Ω termination at SDI_IN+		
SDI_IN-	2	2	I, Analog	and SDI_IN Either SDI_IN+ or SDI_IN- can be used as the 75 $\Omega$ input port of the adaptive cable equalizer for SMPTE video applications. SDI_IN± include integrated return loss networks designed to meet the SMPTE input and output return loss requirements. Connect either SDI_IN+ or SDI_IN- to a BNC through a 4.7 $\mu$ F AC coupling capacitor. AC terminate the unused polarity (SDI_IN- or SDI_IN+, respectively) with external 4.7 $\mu$ F and 75 $\Omega$ to GND.		
SDI_IN1+	N/A	29	I, Analog	Redundant single-ended complementary inputs with on-chip 75Ω termination		
SDI_IN1-	N/A	30	I, Analog	at SDI_IN1+ and SDI_IN1 Either SDI_IN1+ or SDI_IN1- can be used as a secondary 75Ω input port of the adaptive cable equalizer for SMPTE video applications. SDI_IN1± include integrated return loss networks designed to meet the SMPTE input and output return loss requirements. Connect either SDI_IN1+ or SDI_IN1- to a BNC through a 4.7μF AC coupling capacitor. AC terminate the unused polarity (SDI_IN- or SDI_IN+, respectively) with external 4.7μF and 75Ω to GND.		
SDI_OUT+	8	8	O, Analog	Single-ended complementary loop-through cable driver outputs with on-chip		
SDI_OUT-	7	7	O, Analog	75Ω termination at SDI_OUT+ and SDI_OUT SDI_OUT± include integrated return loss networks designed to meet the SMPTE output return loss requirements.  Connect either SDI_OUT+ or SDI_OUT- to a BNC through a 4.7μF AC coupling capacitor.  AC terminate the unused polarity (SDI_IN- or SDI_IN+, respectively) with external 4.7μF and 75Ω to GND.  Note that Cable Fault Detection is only available when using the SDI_OUT+ polarity.		

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# **Table 4-1. Pin Functions (continued)**

PIN			14010 -1-11	Pin Functions (continued)	
NAME	LMH1229 NO.	LMH1239 NO.	TYPE <sup>(1)</sup>	DESCRIPTION	
OUT0+	23	23	O, Analog	Differential complementary outputs with $100\Omega$ internal termination. Requires	
OUT0-	22	22	O, Analog	external 4.7µF AC coupling capacitors. Output driver OUT0± can be disabled under user control.	
OUT1+	19	19	O, Analog	Differential complementary outputs with $100\Omega$ internal termination. Requires	
OUT1-	18	18	O, Analog	external 4.7μF AC coupling capacitors. Output driver OUT1± can be disabled under user control.	
CONTROL PINS					
LOOP_BW_SEL	4	4	I, 4-Level	LOOP_BW_SEL enables 4-level CDR loop bandwidth control. Additional CDR loop bandwidth settings are available by register override.	
IN_MUX_SEL	N/A	10	I, 4-Level	LMH1239 Only: IN_MUX_SEL selects between SDI_IN or SDI_IN1. This pin setting can be overridden by register control.  See Table 6-2 for details.	
OUT_MUX_SEL	5	5	I, 4-Level	OUT_MUX_SEL controls OUT0± and OUT1± enable behavior. This pin setting can be overridden using register control.  See Table 6-3 for details.	
VOD_DE	9	9	I, 4-Level	VOD_DE selects the driver output amplitude and de-emphasis level for both OUT0± and OUT1±. This pin setting can be overridden by register control. See Table 6-8 for details.	
MODE_SEL	12	12	I, 4-Level	MODE_SEL enables SPI or SMBus serial control interface. See Table 6-9 for details.	
SDI_OUT_SEL	14	14	I, LVCMOS	SDI_OUT_SEL enables the use of the 75 $\Omega$ output driver at SDI_OUT±. SDI_OUT_SEL is internally pulled high. The SDI_OUT± is turned off by default. See Table 6-4 for details.	
LF+	15	15	I, Analog	Optional 470nF external loop filter capacitor connected between LF+ and LF-	
LF-	16	16	I, Analog	for reduced CDR loop bandwidth settings. If reduced CDR loop bandwidth is not required, these pins can either be left floating (no connect) or, if connected, programmed with the desired CDR loop bandwidth settings by register control.	
OUT_CTRL	17	17	I, 4-Level	OUT_CTRL selects the signal flow from the SDI input (either SDI_IN± or SDI_IN1±) to OUT0± and OUT1±. The pin selects reclocked data, reclocked data and clock, or bypassed reclocker data (equalized data to output driver). Register control can override the pin settings.  See Table 6-6 for details.	
SDI_VOD	24	24	I, 4-Level	SDI_VOD selects one of four output amplitudes for the cable drivers at SDI_IO± and SDI_OUT±. See Table 6-7 for details.	
LOCK_N	27	25	O, LVCMOS, OD	LOCK_N is the reclocker lock indicator for the selected input. LOCK_N is pulled LOW when the reclocker has acquired locking condition. LOCK_N is an open drain output, 3.3V tolerant, and requires an external $2k\Omega$ to $5k\Omega$ pullup resistor to logic supply. LOCK_N pin can be re-configured to indicate CD_N (Carrier Detect), Cable Fault Detect (CFD_N), or INT_N (Interrupt) for the selected SDI input through register programming.	
ENABLE	32	32	I, LVCMOS	ENABLE controls device operation. A logic-low on ENABLE configures device in power down state. A logic-high on ENABLE configures the device in normal operation. ENABLE has an internal weak pull up.	
SERIAL CONTRO	L INTERFA	CE			
CS_N_ADDR0	11	11	SPI Mode: I, LVCMOS SMBus Mode: Strap, 4-Level	SPI Mode (MODE_SEL = F): CS_N CS_N is the Chip Select. When CS_N is at logic Low, the pin enables SPI access to the LMH12x9 peripheral device. CS_N is a LVCMOS input pulled high by default.  SMBus Mode (MODE_SEL = L): ADDR0 ADDR[1:0] are SMBus address straps to select one of the 16 supported SMBus addresses. ADDR[1:0] are 4-level straps and are read into the device at power up. See Table 6-10 for details.	



## **Table 4-1. Pin Functions (continued)**

	PIN			Thir undiana (continuou)
NAME	LMH1229 NO.	LMH1239 NO.	TYPE <sup>(1)</sup>	DESCRIPTION
POCI_ADDR1	28	26	SPI Mode: O, LVCMOS SMBus Mode: Strap, 4-Level	SPI Mode (MODE_SEL = F): POCI POCI "Peripheral Output Controller Input" is the SPI control serial data output from the LMH12x9 peripheral device. POCI is a LVCMOS output referenced to VIN. SMBus Mode (MODE_SEL = L): ADDR1 ADDR[1:0] are SMBus address straps to select one of the 16 supported SMBus addresses. ADDR[1:0] are 4-level straps and are read into the device at power up. See Table 6-10 for details.
PICO_SDA	13	13	SPI Mode: I, LVCMOS SMBus Mode: IO, LVCMOS, OD	SPI Mode (MODE_SEL = F): PICO PICO "Peripheral Input Controller Output" is used as the SPI control serial data input to the LMH12x9 peripheral device. PICO is LVCMOS input referenced to VIN SMBus Mode (MODE_SEL = L): SDA SDA is the SMBus bi-directional open drain SDA data line to or from the LMH12x9 target device. SDA is an open drain IO and 3.3V tolerant. SDA requires an external $2k\Omega$ to $5k\Omega$ pullup resistor to the SMBus termination voltage.
SCK_SCL	29	27	SPI Mode: I, LVCMOS SMBus Mode: I, LVCMOS, OD	SPI Mode (MODE_SEL = F): SCK SCK is the SPI serial input clock to the LMH12x9 peripheral device. SCK is LVCMOS referenced to VIN. SMBus Mode (MODE_SEL = L): SCL SCL is the SMBus input clock to the LMH12x9 target device when SMBus is enabled. The pin is driven by a LVCMOS open drain driver from the SMBus controller and is 3.3V tolerant. SCL requires an external $2k\Omega$ to $5k\Omega$ pullup resistor to the SMBus termination voltage.
RESERVED				
RSV1	10	N/A		
RSV2	25	N/A	N/A	Reserved pins. Do not connect.
RSV3	26	N/A		
POWER				
VSS	3, 6, 20	3, 6, 20	I, Ground	Ground reference.
VIN	30, 21	28, 21	I, Power	Connect the VIN to the same external 2.5V $\pm$ 5% power supply. TI recommends to place decoupling capacitors as close as possible to both VIN pins.
VDD_LDO	31	31	O, Power	VDD_LDO is the output of the internal 1.8V LDO regulator. VDD_LDO output requires an external 1µF and 0.1µF bypass capacitor to VSS. The internal LDO is designed to power internal circuitry only.
EP			I, Ground	EP is the exposed pad at the bottom of the QFN package. The exposed pad must be connected to the ground plane through a 3x3 via array.

<sup>(1)</sup> I = Input, O = Output, IO = Input or Output, OD = Open Drain, LVCMOS = 2-State Logic, 4-LEVEL = 4-State Logic

# 5 Specifications

# 5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

	,	MIN	MAX	UNIT
2.5V supply voltage (VIN)		-0.5	2.75	V
4-level input		-0.5	2.75	V
2-level LVCMOS input		-0.5	2.75	V
SMBus input/output	SDA, SCL	-0.5	4	V
High-speed inputs/output voltage	SDI_IN±, SDI_IN1±, SDI_OUT±, OUT0±, OUT1±	-0.5	2.75	V
High-speed input current	SDI_IN±, SDI_IN1±	-30	30	mA
Junction temperature	TJ	-40	125	°C
Storage temperature	T <sub>stg</sub>	-65	150	°C

<sup>(1)</sup> Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

# 5.2 ESD Ratings

				VALUE	UNIT
V	E	Human body model (HBM), per ANSI/ ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	All pins including high-speed pins <sup>(2)</sup>	±6000	V
V <sub>(ESD)</sub>	Electrostatic discharge	Charged device model (CDM), per JEDEC specification JS-002, all pins <sup>(3)</sup>		±1500	<b>V</b>

- (1) JEDEC document JEP155 states that 500V HBM allows safe manufacturing with a standard ESD control process
- (2) High speed I/O pins include: SDI\_IN±, SDI\_OUT±, OUT0±, and OUT1±.
- (3) JEDEC document JEP157 states that 250V CDM allows safe manufacturing with a standard ESD control process.

### 5.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	NOM	MAX	UNIT
	VIN		2.375	2.5	2.625	V
VDD <sub>SMBUS</sub>	SDA, SCL		2.375		3.6	V
V <sub>SDI_INx_LAUNCH</sub>	SDI_IN±, SDI_IN1±		720	800	880	mVpp
T <sub>J</sub>	Operating junction temperature				110	°C
T <sub>RampVCC</sub>	VCC supply ramp time	From 0V to 2.5V	0.150		100	ms
T <sub>A</sub>	Ambient temperature		-40	25	85	°C
NT	Maximum supply noise tolerance <sup>(1)</sup>	50Hz to 1MHz, sinusoidal		<20		mVpp
NT <sub>psmax</sub>	Maximum supply holse tolerance	1.1MHz to 6GHz, sinusoidal	<10			mVpp

<sup>(1)</sup> The sum of the DC supply voltage and AC supply noise should not exceed the recommended supply voltage range.

#### 5.4 Thermal Information

	THERMAL METRIC(1)	RTV (QFN)	LIMIT
	I HERMAL ME I RIC	32 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	30.6	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	18.4	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	11.6	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	0.2	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	11.5	°C/W



	THERMAL METRIC(1)	RTV (QFN) 32 PINS	UNIT
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	2.0	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application note.

## 5.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER						
		SDI_OUT± disabled OUT0± enabled OUT1± disabled		350	466	mW
DD.	Power dissipation, measured	SDI_OUT± disabled OUT0± enabled OUT1± enabled		380	517	mW
PD <sub>ACTIVE</sub>	with PRBS10, CDR locked to 11.88Gbps, VOD = default	SDI_OUT± enabled OUT0± enabled OUT1± disabled		480	640	mW
		SDI_OUT± enabled OUT0± enabled OUT1± enabled		520	688	mW
$PD_Z$	Power dissipation, power save mode	MODE_SEL = High		70	110	mW
PDZ	Power dissipation, power save mode with no signal	No signal applied at SDI_IN+, MODE_SEL = F or MODE_SEL = Low		75	115	mW
IDD <sub>ACTIVE</sub>	Current consumption, measured with PRBS10, CDR locked to 11.88Gbps, VOD = default	SDI_OUT± disabled OUT0± enabled OUT1± disabled		140	177	mA
		SDI_OUT± disabled OUT0± enabled OUT1± enabled		152	197	mA
		SDI_OUT± enabled OUT0± enabled OUT1± disabled		192	244	mA
		SDI_OUT± enabled OUT0± enabled OUT1± enabled		208	262	mA
IDD <sub>Z</sub>	Current consumption, power save mode	No signal applied at SDI_IN+		28	42	mA
		SDI_OUT± disabled OUT0± enabled OUT1± disabled		210	268	mA
IDD	Current consumption, CDR	SDI_OUT± disabled OUT0± enabled OUT1± enabled		230	287	mA
IDD <sub>TRANS</sub>	acquiring lock	SDI_OUT± enabled OUT0± enabled OUT1± disabled		270	333	mA
		SDI_OUT± enabled OUT0± enabled OUT1± enabled		280	353	mA
LVCMOS DC SI	PECIFICATIONS				<u> </u>	
V <sub>IH</sub>	Logic high input voltage	2-Level input (CS_N, SCK, PICO, SDI_OUT_SEL, ENABLE)	0.72 × VIN	V	IN + 0.3	V
		2-Level input (SCL, SDA)	0.7 × VIN		3.6	V

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	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>IL</sub>	Logic Low input voltage	2-Level input (CS_N, SCK, PICO, SDI_OUT_SEL, ENABLE, SCL, SDA)	0		0.3 × VIN	V
V <sub>OH</sub>	Logic high output voltage	$I_{OH} = -2mA$ , (POCI)	0.8 × VIN		VIN	V
\ /	Lania laurantantualtana	I <sub>OL</sub> = 2mA, (POCI)	0		0.2 × VIN	V
$V_{OL}$	Logic low output voltage	I <sub>OL</sub> = 3mA, (LOCK_N, SDA)			0.4	V
		LVCMOS (SDI_OUT_SEL, ENABLE)			15	μA
I <sub>IH</sub>	Input high leakage current (Vinput = VIN)	SPI mode: LVCMOS (CS_N, SCK, PICO)			15	μA
	(Vilipat VIII)	SMBus mode: LVCMOS (SCL, SDA)			15	μA
		LVCMOS (SDI_OUT_SEL, ENABLE)	-50			μΑ
	Input low leakage current	SPI mode: LVCMOS (SCK, PICO)	-15			μA
I <sub>IL</sub>	(Vinput = GND)	SPI mode: LVCMOS (CS_N)	-50			μΑ
		SMBus mode: LVCMOS (SCL, SDA)	-10			μΑ
4-LEVEL LOGIC	DC SPECIFICATIONS (APPLY TO	ALL 4-LEVEL INPUT CONTROL PINS)				
$V_{LVL_LH}$	LEVEL-H input voltage	Measured voltage at 4-level pin with external $1k\Omega$ to VIN		VIN		V
$V_{LVL_F}$	LEVEL-F default voltage	Measured voltage 4-level pin at default		2/3 × VIN		V
V <sub>LVL_R</sub>	LEVEL-R input voltage	Measured voltage at 4-level pin with external 20kΩ to VSS	1/3 × VIN			V
V <sub>LVL_L</sub>	LEVEL-L input voltage	Measured voltage at 4-level pin with external 1kΩ to VSS		0		V
I <sub>IH</sub>	Input high leakage current (Vinput = VIN)	4-Levels (LOOP_BW_SEL, IN_MUX_SEL, OUT_MUX_SEL, VOD_DE, MODE_SEL, OUT_CTRL, SDI_VOD)	20	45	80	μΑ
		SMBus mode: 4-levels (ADDR0, ADDR1)	20	45	80	μA
I <sub>IL</sub>	Input low leakage current (Vinput = GND)	4-Levels (LOOP_BW_SEL, IN_MUX_SEL, OUT_MUX_SEL, VOD_DE, MODE_SEL, OUT_CTRL, SDI_VOD)	-160	-90	-40	μΑ
		SMBus mode: 4-Levels (ADDR0, ADDR1)	-160	-90	-40	μΑ
SDI RECEIVER S	PECIFICATIONS (SDI_IN+(4))		ı		U.	
R <sub>SDI_IN_TERM</sub>	DC input single-ended termination	SDI_IN+ and SDI_IN– to internal common-mode bias	63	75	87	Ω
		S11, 5MHz to 1.485GHz		-30		dB
	Input Return Loss at SDI IN+	S11, 1.485GHz to 3GHz		-25		dB
RL <sub>SDI_IN_S11</sub>	reference to $75\Omega^{(1)}$	S11, 3GHz to 6GHz		-16		dB
		S11, 6GHz to 12GHz		-13		dB
V <sub>SDI_IN_CM</sub>	SDI_IN+ DC common-mode voltage	Input DC common-mode voltage at SDI_IN+ or SDI_IN– to GND		1.4		V
		SD, input signal at SDI_IN+, input launch amplitude = 800mVpp		150		mVpp
V <sub>SDI_IN_WANDER</sub>	Input DC wander tolerance	HD, 3G, 6G, 12G, input signal at SDI_IN+, input launch amplitude = 800mVpp		50		mVpp



	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input cable reach with		Measured at OUT0±, PRBS9 (BER ≤ 1E-12), TX launch amplitude = 800mVpp before cable 11.88Gbps ± 1000ppm (12G-SDI)		100		m
	B1694A, measured with LMH1239EVM, OUT1± and	5.94Gbps ± 1000ppm (6G-SDI)		150		m
	SDI_OUT+ disabled	2.97Gbps ± 1000ppm (3G)		220		m
		1.485Gbps ± 1000ppm (HD)		300		m
		270Mbps ± 1000ppm (SD)		600		m
Reach <sub>PRBS9</sub>	Input cable reach with	Measured at OUT0±, PRBS9 (BER ≤ 1E-12), TX launch amplitude = 800mVpp before cable 11.88Gbps ± 1000ppm (12G-SDI)		90		m
	B1694A, measured with LMH1239EVM, OUT1± and	5.94Gbps ± 1000ppm (6G-SDI)		140		m
	SDI_OUT+ enabled	2.97Gbps ± 1000ppm (3G)		220		m
		1.485Gbps ± 1000ppm (HD)		300		m
		270Mbps ± 1000ppm (SD)		600		m
	Input cable reach with B1694A, measured with LMH1239EVM, OUT1± and SDI_OUT+ disabled  Input cable reach with B1694A, measured with	Measured at OUT0±, Pathological Pattern (BER ≤ 1E-12), TX launch amplitude = 800mVpp before cable 11.88Gbps (12G-SDI) Test with SDI_IN1+		90		m
		5.94Gbps (6G-SDI)		140		m
		2.97Gbps (3G)		220		m
		1.485Gbps (HD)		300		m
		270Mbps (SD)		600		m
Reach <sub>PATH</sub>		Measured at OUT0±, Pathological Pattern (BER ≤ 1E-12), TX launch amplitude = 800mVpp before cable 11.88Gbps (12G-SDI) Test with SDI_IN+		80		m
	LMH1239EVM, OUT1± and	5.94Gbps (6G-SDI)		140		m
	SDI_OUT+ enabled	2.97Gbps (3G)		220		m
		1.485Gbps (HD)		300		m
		270Mbps (SD)		600		m
RECLOCKER CL	OCK AND DATA RECOVERY SPE	CIFICATIONS				
		SMPTE 12G, /1		11.88		Gbps
		SMPTE 12G, /1.001		11.868		Gbps
		SMPTE 6G, /1		5.94		Gbps
		SMPTE 6G, /1.001		5.934		Gbps
LOCK <sub>RATE</sub>	Reclocker lock data rates	SMPTE 3G, /1		2.97		Gbps
		SMPTE 3G, /1.001		2.967		Gbps
		SMPTE HD, /1		1.485		Gbps
		SMPTE HD, /1.001		1.4835		Gbps
		SMPTE SD, /1		270		Mbps
BYPASS <sub>RATE</sub>	Reclocker automatically goes to bypass <sup>(6)</sup>	MADI		125		Mbps

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	PARAMETER	TEST CONDITIONS	MIN TYP MAX	UNIT
		Applied 0.2UI input sinusoidal jitter, measure –3dB bandwidth on input-to- output jitter transfer 11.88Gbps	7	MHz
	PLL bandwidth, LOOP BW SEL=F (default)	5.94Gbps	7	MHz
	EGGI _BW_GEE I (dolddir)	2.97Gbps	5	MHz
		1.485Gbps	3	MHz
		270Mbps	0.8	MHz
		Applied 0.2UI input sinusoidal jitter, measure –3dB bandwidth on input-to-output jitter transfer 11.88Gbps	7	MHz
	PLL bandwidth, LOOP_BW_SEL=H <sup>(5)</sup>	5.94Gbps	7	MHz
		2.97Gbps	5	MHz
		1.485Gbps	3	MHz
DIM		270Mbps	0.8	MHz
BW <sub>PLL</sub>		Applied 0.2UI input sinusoidal jitter, measure –3dB bandwidth on input-to-output jitter transfer 11.88Gbps	0.70	MHz
	PLL bandwidth, LOOP_BW_SEL=R <sup>(5)</sup>	5.94Gbps	0.60	MHz
	2001 2011 2011	2.97Gbps	0.46	MHz
		1.485Gbps	0.24	MHz
		270Mbps	0.05	MHz
		Applied 0.2UI input sinusoidal jitter, measure –3dB bandwidth on input-to-output jitter transfer 11.88Gbps	0.35	MHz
	PLL bandwidth, LOOP_BW_SEL=L <sup>(5)</sup>	5.94Gbps	0.30	MHz
		2.97Gbps	0.23	MHz
		1.485Gbps	0.12	MHz
		270Mbps	0.03	MHz
J <sub>PEAK</sub>	PLL jitter peaking	12G/6G/3G/HD/SD	<0.3	dB
J <sub>TOL_SDI</sub>	SDI_IN+ input jitter tolerance	Sinusoidal jitter, tested at 12G/6G/3G SJ amplitude swept from 1MHz to 80MHz, tested at BER ≤ 1E-12, cable equalizer at SDI_IN+ bypassed	0.55	UI
T <sub>LOCK</sub>	CDR Lock Time	SMPTE supported data rates, includes EQ coarse adaptation. Does not include SSLMS adaptation. No external LF capacitor applied.	1.2 4.5	ms
T <sub>ADAPT</sub>	EQ adapt time	SMPTE supported data rates, includes CDR lock time. No external LF capacitor applied.	1.6	ms
TEMP <sub>LOCK</sub>	VCO temperature lock range	Measured with temperature ramp of 5°C per min, ramp up and down, –40°C to 85°C operating range at 11.88Gbps	125	°C



	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
		Measured from SDI_IN+ to OUT0, all supported data rates, CDR enabled and locked	2	2.1 UI + 270		ps
		Measured from SDI_IN+ to SDI_OUT+, all supported data rates, CDR enabled and locked	2	2.1 UI + 255		ps
T <sub>LATENCY</sub>	Input-to-output latency (propagation delay)	Measured from SDI_IN+ to OUT0, all supported data rates, raw mode (CDR bypassed)		270		ps
		Measured from SDI_IN+ to SDI_OUT+, 12G/6G/3G/HD, raw mode (CDR bypassed), OUT_CTRL = L		255		ps
		Measured from SDI_IN+ to SDI_OUT+, SD, raw mode (CDR bypassed), OUT_CTRL = L		900		ps
RECLOCKER D	IFFERENTIAL OUTPUT JITTER (	OUT0±, OUT1±)				
Total jitter (BER ≤ 1E-12), reclocked output with SDI_OUT disabled <sup>(1)</sup> (3)	Measured at OUT0±, PRBS9, TX launch amplitude = 800mVpp before cable 11.88Gbps: 100m Belden 1694A		0.12	0.20		
		5.94Gbps: 150m Belden 1694A		0.08		UI
		2.97Gbps: 220m Belden 1694A		0.07		
		1.485Gbps: 300m Belden 1694A		0.05		
		270Mbps: 600m Belden 1694A		0.11		
TJ <sub>DIFF_OUT</sub>		Measured at OUT0±, PRBS9, TX launch amplitude = 800mVpp before cable 11.88Gbps: 90m Belden 1694A		0.12	0.20	
	Total jitter (BER ≤ 1E-12), reclocked output with	5.94Gbps: 140m Belden 1694A		0.08		UI
	SDI_OUT enabled <sup>(1)</sup> (3)	2.97Gbps: 220m Belden 1694A		0.07		O1
		1.485Gbps: 300m Belden 1694A		0.05		
		270Mbps: 600m Belden 1694A		0.11		
	Measured at OUT0±, Pl amplitude = 800mVpp b SDI_IN+	Measured at OUT0±, PRBS9, TX launch amplitude = 800mVpp before cable to SDI_IN+ 11.88Gbps: 100m Belden 1694A		35	80	
	1E-12), reclocked output with	5.94Gbps: 150m Belden 1694A		26		mUI
	SDI_OUT disabled <sup>(1) (3)</sup>	2.97Gbps: 220m Belden 1694A		16		
		1.485Gbps: 300m Belden 1694A		20		
DJ <sub>DIFF_OUT</sub>		270Mbps: 600m Belden 1694A		23		
	Deterministic jitter (BER ≤	Measured at OUT0±, PRBS9, TX launch amplitude = 800mVpp before cable to SDI_IN+ 11.88Gbps: 90m Belden 1694A		35	80	
	1E-12), reclocked output with	5.94Gbps: 140m Belden 1694A		26		mUI
	SDI_OUT enabled <sup>(1) (3)</sup>	2.97Gbps: 220m Belden 1694A		16		
		1.485Gbps: 300m Belden 1694A		20		
		270Mbps: 600m Belden 1694A		23		

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Random jitter (BER ≤	Measured at OUT0±, PRBS9, TX launch amplitude = 800mVpp before cable to SDI_IN+ 11.88Gbps: 100m Belden 1694A		6.2	11	
	1E-12), reclocked output with	5.94Gbps: 150m Belden 1694A		5.3		mUIrms
	SDI_OUT disabled <sup>(1)</sup> (3)	2.97Gbps: 220m Belden 1694A		5.3		
		1.485Gbps: 300m Belden 1694A		4.5		
		270Mbps: 600m Belden 1694		7.8		
RJ <sub>DIFF_OUT</sub>	Random jitter (BER ≤	Measured at OUT0±, PRBS9, TX launch amplitude = 800mVpp before cable to SDI_IN+ 11.88Gbps: 90m Belden 1694A		6.2	11	
	1E-12), reclocked output with	5.94Gbps: 1540m Belden 1694A		5.3		mUIrms
	SDI_OUT enabled <sup>(1) (3)</sup>	2.97Gbps: 220m Belden 1694A		5.3		
		1.485Gbps: 300m Belden 1694A		4.5		
		270Mbps: 600m Belden 1694A		7.8		
TJ <sub>RAW</sub>	Total jitter (BER ≤1E-12) with CDR bypassed	Measured at OUT0±, PRBS9, TX launch amplitude = 800mVpp before cable to SDI_IN+ 125Mbps: 600m Belden 1694A		0.2		UI
RECLOCKER SDI	OUTPUT JITTER (SDI_OUT+)					
AJ <sub>SDI_OUT</sub>	Alignment jitter <sup>(1)</sup>	Measured with 12G-SDI at SDI_OUT+ OUT0± and OUT1± disabled		0.14		UI
TMJ <sub>SDI_OUT</sub>	Timing jitter <sup>(1)</sup>	Measured with 12G-SDI at SDI_OUT+ OUT0± and OUT1± disabled		0.45		UI
DIFFERENTIAL D	RIVER OUTPUT (OUT0±, OUT1±)					
R <sub>DIFF_OUT_TERM</sub>	DC output differential termination	Measured across OUT0+ and OUT0-	80	100	120	Ω
	Output differential voltage	Measured with 8T pattern at 11.88Gbps VOD_DE = H		410		mVpp
VOD <sub>DIFF_OUT</sub>		VOD_DE = F	485	560	635	mVpp
		VOD_DE = R		635		mVpp
		VOD_DE = L		810		mVpp
		Measured with 8T pattern at 11.88Gbps VOD_DE = H		410		mVpp
VOD <sub>DIFF_OUT_DE</sub>	Output de-emphasis level	VOD_DE = F		500		mVpp
5001_52		VOD_DE = R		480		mVpp
		VOD_DE = L		400		mVpp
t <sub>R</sub> /t <sub>F</sub>	Output rise/fall time	Measured with 8T Pattern at 11.88Gbps, 20%-80% amplitude		45		ps
RL <sub>DIFF_OUT-SDD22</sub>	Output differential return loss <sup>(1)</sup>	Measured with the device powered up and outputs a 10MHz clock signal SDD22, 10MHz to 2.8GHz		-26		dB
N-DIFF_OUT-SDD22	_ aspas amoronida rotain 1000	SDD22, 2.8GHz to 6GHz		-18		dB
		SDD22, 6GHz to 11.1GHz		-13		dB
RL <sub>DIFF_OUT-SCC22</sub>	Output common-mode return loss <sup>(1)</sup>	Measured with the device powered up and outputs a 10MHz clock signal. SCC22, 10MHz to 4.75GHz		-14		dB
		SCC22, 4.75GHz to 11.1GHz		-16		dB
V <sub>DIFF_OUT_CM</sub>	AC common-mode voltage on OUT0± <sup>(1)</sup>	Default setting, PRBS9, 11.88Gbps		7		mVrms

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SDI DRIVER OUT	TPUT (SDI_OUT+)					
R <sub>OUT_TERM</sub>	DC output single-ended termination	SDI_OUT+ and SDI_OUT- to VIN	63	75	87	Ω
VOD <sub>CD_OUTP</sub>	Output single-ended output voltage	Measure AC signal at SDI_OUT+, with SDI_OUT- AC terminated with 75Ω.  Measured with color bar on Phabrix Qx with 1m B1694A at 11.88Gbps SDI_VOD=H		840		mVpp
	Voltage	SDI_VOD=F <sup>(3)</sup>	720	800	880	mVpp
		SDI_VOD=R		880		mVpp
		SDI_VOD=L		760		mVpp
VOD <sub>CD_OUTN</sub>	Output single-ended output voltage	Measure AC signal at SDI_OUT-, with SDI_OUT+ AC terminated with 75Ω. Measured with color bar on Phabrix Qx with 1m B1694A at 11.88Gbps SDI_VOD=H		840		mVpp
_	Voltage	SDI_VOD=F <sup>(3)</sup>	720	800	880	mVpp
		SDI_VOD=R		880		mVpp
		SDI_VOD=L		760		mVpp
PRE <sub>CD_OUTP</sub>	Output pre-emphasis	Output pre-emphasis boost amplitude at SDI_OUT+, programmed to maximum setting through register, measured at SDI_VOD=F with 8T pattern at 11.88Gbps		2.5		dB
PRE <sub>CD_OUTP_</sub> T	Output pre-emphasis duration	Output pre-emphasis time duration, measured after 0.5" trace, BNC connector, and 1m B1694A cable with 8T pattern at 11.88Gbps		83		ps
PRE <sub>CD_OUTN</sub>	Output pre-emphasis	Output pre-emphasis boost amplitude at SDI_OUT-, programmed to maximum setting through register, measured at SDI_VOD=F with 8T pattern at 11.88Gbps	2.5			dB
PRE <sub>CD_OUTN_</sub> T	Output pre-emphasis duration	Output pre-emphasis time duration, measured after 0.5" trace, BNC connector, and 1m B1694A cable with 8T pattern at 11.88Gbps	83			ps
		Measured with color bar on Phabrix Qx, default VOD, default pre-emphasis 11.88Gbps		36		ps
t <sub>R_F_SDI</sub>	Output rise and fall time <sup>(1)</sup>	5.94Gbps		36		ps
1(_1 _30)		2.97Gbps		60		ps
		1.485Gbps		60		ps
		270Mbps		520		ps
		Measured with color bar on Phabrix Qx, default VOD, default pre-emphasis 11.88Gbps		5		ps
t <sub>R_F_DELTA</sub>	Output rise/fall time	5.94Gbps		8		ps
	mismatch <sup>(1)</sup>	2.97Gbps		13		ps
		1.485Gbps		53		ps
		270Mbps		75		ps
V <sub>OVERSHOOT</sub>	Output overshoot or undershoot <sup>(2)</sup>	Measured with color bar on Phabrix Qx with 1m B1694A at SDI_OUT+, default VOD, default pre-emphasis, 12G		8		%

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>DC_OFFSET</sub>	DC offset	Measured with Phabrix Qx with 1m B1694A at SDI_OUT+, 12G/6G/3G/HD/SD		±0.2		V
V <sub>DC_WANDER</sub>	DC wander	Measured with real-time scope with 1m B1694A at SDI_OUT+, 12G/6G/3G/HD with pathological pattern		13		mV
		S22, 5MHz to 1.485GHz		-23		dB
DI	Output return loss at	S22, 1.485GHz to 3GHz		-16		dB
RL <sub>CD_S22</sub>	SDI_OUT+ reference to $75\Omega^{(1)}$	S22, 3GHz to 6GHz		-16		dB
		S22, 6GHz to 12GHz		-15		dB

- (1) This parameter is measured with the LMH1239EVM (Evaluation board for LMH12x9).
- (2) V<sub>OVERSHOOT</sub> overshoot/undershoot maximum measurements are largely affected by the PCB layout and input test pattern. The maximum value specified in Electrical Characteristics for V<sub>OVERSHOOT</sub> is based on bench evaluation across temperature and supply voltages with the LMH1239EVM.
- (3) This limit is ensured by bench characterization and is not production tested.
- (4) All specifications characterized with SDI IN± on LMH1229 are applicable to both SDI IN± and SDI IN1± on LMH1239.
- (5) External loop filter capacitor required between LF+ and LF- to implement reduced PLL bandwidth.
- (6) Reclocker automatically goes into bypass when the LMH12x9 does not lock to a valid LOCK<sub>RATE</sub> data rate. When bypassed, LMH12x9 EQ adaptation is disabled and EQ index must be programmed manually (for more information, refer to the LMH12x9 Programming Guide).

### 5.6 Timing Requirements for Serial Management (SM) Bus Interface

over recommended operating supply and temperature range (unless otherwise noted)(1) (2)

		MIN	NOM MAX	UNIT
F <sub>SCL</sub>	SMBus SCL frequency		400	kHz
T <sub>BUF</sub>	Bus free time between stop and start condition	1.3		μs
T <sub>HD:STA</sub>	Hold time after (repeated) start condition. After this period, the first clock is generated.	0.6		μs
T <sub>SU:STA</sub>	Repeated start condition setup time	0.6		μs
T <sub>SU:STO</sub>	Stop condition setup time	0.6		μs
T <sub>HD:DAT</sub>	Data hold time	0		ns
T <sub>SU:DAT</sub>	Data setup time	100		ns
T <sub>LOW</sub>	Clock low period	1.3		μs
T <sub>HIGH</sub>	Clock high period	0.6		μs
T <sub>R</sub>	Clock/data rise time		300	ns
T <sub>F</sub>	Clock/data fall time		300	ns
T <sub>POR</sub>	SMBus ready time after POR. Time from minimum VIN to SMBus valid write/read access.		50	ms

- (1) These parameters support SMBus 2.0 specifications.
- (2) For explanation of parameters, refer to SMBus timing parameter figures.



# 5.7 Timing Requirements for Serial Parallel Interface (SPI) Interface

over recommended operating supply and temperature range (unless otherwise noted)(1) (2)

	1 0 11 7 1 0 1	MIN	NOM	MAX	UNIT
F <sub>SCK</sub>	SPI SCK frequency			10	MHz
T <sub>PH</sub>	SCK pulse width high	40			% SCK period
T <sub>PL</sub>	SCK pulse width low	40			% SCK period
T <sub>SU</sub>	PICO setup time	4			ns
T <sub>H</sub>	PICO hold time	4			ns
T <sub>SSSU</sub>	SS setup time	14			ns
T <sub>SSH</sub>	SS hold time	4			ns
T <sub>SSOF</sub>	SS off time	1			μs
T <sub>ODZ</sub>	POCI driven-to-tristate time		20		ns
T <sub>OZD</sub>	POCI tristate-to-driven time		10		ns
T <sub>OD</sub>	POCI output delay time		15		ns

<sup>(1)</sup> Typical SPI load capacitance is 2 pF.

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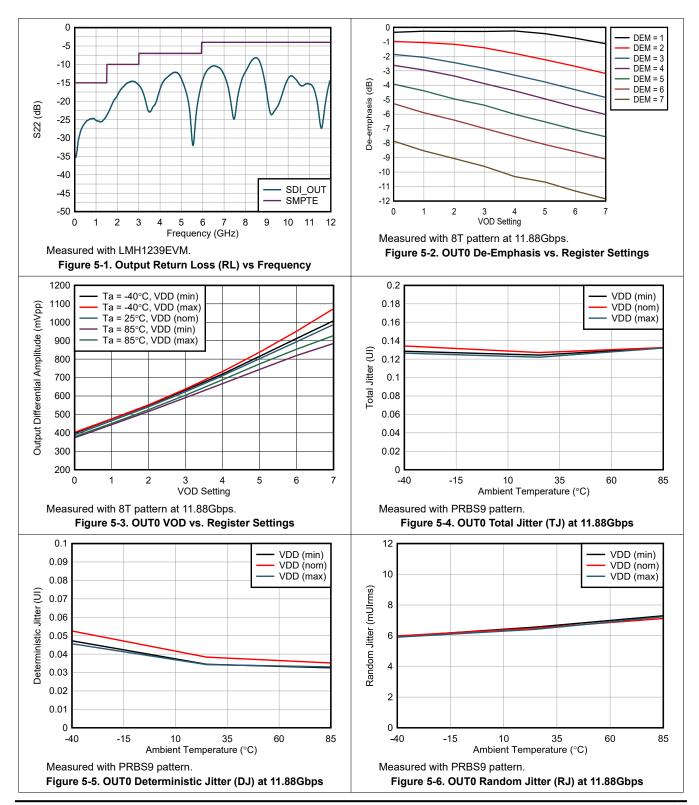
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<sup>(2)</sup> For explanation of parameters, refer to SPI timing parameter figures.

### 5.8 Typical Characteristics

#### 5.8.1 TX Characteristics

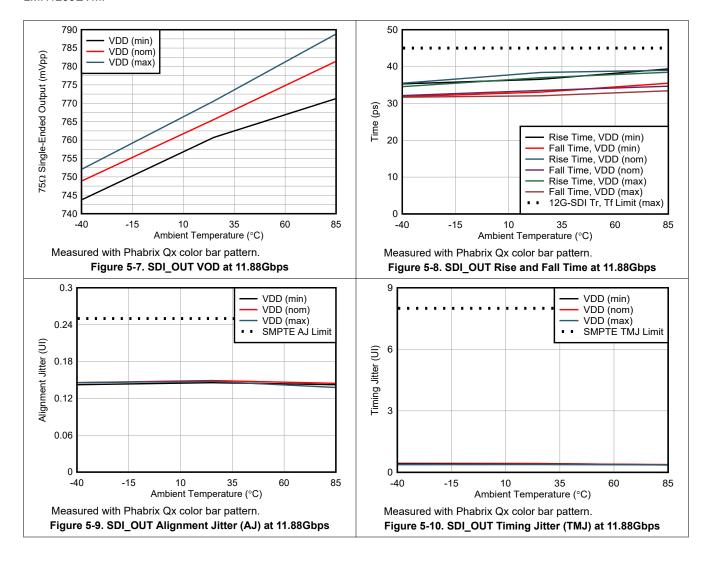
The following conditions apply (unless otherwise noted):  $T_A = 25$ °C; VDD = 2.5V, All measurements performed with LMH1239EVM.





### 5.8.1 TX Characteristics (continued)

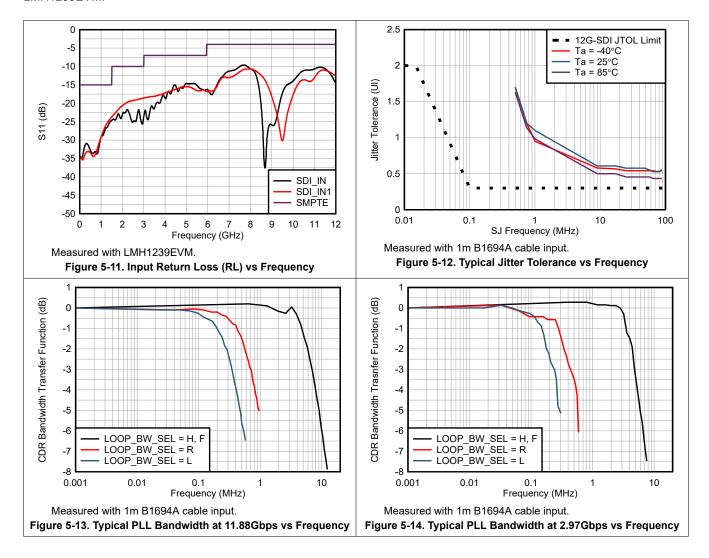
The following conditions apply (unless otherwise noted):  $T_A = 25^{\circ}C$ ; VDD = 2.5V, All measurements performed with LMH1239EVM.





#### 5.8.2 RX Characteristics

The following conditions apply (unless otherwise noted):  $T_A = 25^{\circ}C$ ; VDD = 2.5V, All measurements performed with LMH1239EVM.



# **6 Detailed Description**

### 6.1 Overview

The LMH12x9 is Tl's second generation long-reach 12G UHD-SDI adaptive cable equalizer with integrated reclocker, supporting all SMPTE video rates up to 11.88Gbps. The LMH12x9 has a  $75\Omega$  cable equalizer input capable of equalizing up to 100m Belden 1694A cable.

The  $75\Omega$  cable equalizer input features an internal  $75\Omega$  termination and compensation network to meet stringent SMPTE return loss requirements. The  $75\Omega$  cable equalizer input passes through a multi-rate reclocker with a programmable loop filter.

The on-chip reclocker attenuates high-frequency jitter and fully regenerates the data using a clean, low-jitter clock. The reclocker has a built-in loop filter and does not require any input reference clock. The LMH12x9 also has an internal eye opening monitor and a programmable pin for CDR lock indication, input carrier detect, or hardware interrupts to support system diagnostics and board bring-up.

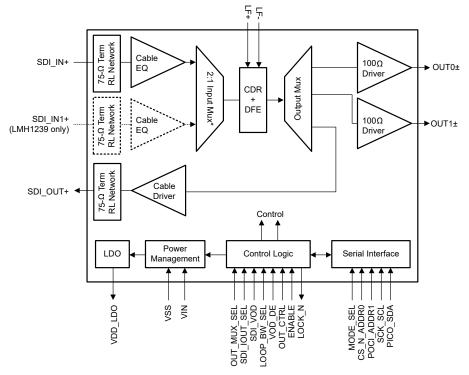
After the reclocker is a 1:3 fan-out mux. Two of the outputs are  $100\Omega$  drivers with de-emphasis for PCB routing of data or clock signals, while the third output is a  $75\Omega$  driver with pre-emphasis for reclocked SDI loop-through data in cascaded applications.

The LMH12x9 is offered in a 5mm × 5mm 32-pin WQFN package with two pinout variants:

- LMH1229: Pin-to-pin drop-in replacement for LMH1297 12G-SDI Bidirectional I/O (Equalizer mode)
- LMH1239: Unique pinout with additional 2:1 75Ω input mux included for system redundancy

The LMH12x9 is powered from a single 2.5V supply with an on-chip 1.8V LDO regulator. The operating state of the LMH12x9 can be configured through control pins, SPI, or SMBus serial control interface. In the absence of an input signal, the LMH12x9 automatically goes into Power Save mode. Users can also manually force the LMH12x9 into Power Save mode through the ENABLE control pin. The LMH1297 is offered in a small 5mm × 5mm, 32-pin QFN package.

### 6.2 Functional Block Diagram



\*2:1 Input mux is only applicable with the LMH1239 variant. For LMH1229, SDI\_IN+data path is routed directly to the CDR.

### **6.3 Feature Description**

The LMH12x9 consists of several key blocks, which are as follows:

- 4-Level Input Configuration Pins
- Input and Output Signal Flow Control
- Input Carrier Detect
- Adaptive Cable Equalizer (SDI\_IN±, SDI\_IN1±)
- · Clock and Data (CDR) Recovery
- CDR Loop Bandwidth Control
- Output Function Control
- Output Driver Control
- · Debug and Diagnostic Features

### 6.3.1 4-Level Input Pins and Thresholds

The 4-level input configuration pins use a resistor divider to provide four logic states for each control pin. There is an internal  $30k\Omega$  pullup and a  $60k\Omega$  pulldown connected to the control pin that sets the default voltage at 2/3 x VIN. These resistors, together with the external resistor, combine to achieve the desired voltage level. By using the  $1k\Omega$  pulldown,  $20k\Omega$  pulldown, no connect, and  $1k\Omega$  pullup, the optimal voltage levels for each of the four input states are achieved as provided in Table 6-1.

Table 6-1. 4-Level Control Pin Settings

LEVEL	SETTING	RESULTING PIN VOLTAGE
Н	Tie 1 kΩ to VIN	VIN
F	Float (leave pin open)	2/3 × VIN
R	Tie 20 kΩ to VSS	1/3 × VIN
L	Tie 1 kΩ to VSS	0

Typical 4-Level Input Thresholds:

- Internal Threshold between L and R = 0.2 × VIN
- Internal Threshold between R and F = 0.5 × VIN
- Internal Threshold between F and H = 0.8 × VIN

### 6.3.2 Input and Output Signal Flow Control

The input and output signal flow of the LMH12x9 is determined by the IN\_MUX\_SEL (LMH1239 only), OUT MUX SEL, and SDI OUT SEL pins.

#### 6.3.2.1 Input Mux Selection (LMH1239 Only)

The LMH12x9 receives a  $75\Omega$  SDI input signal. For the LMH1229, the input is provided on SDI\_IN+. For the LMH1239, the input setting can be between SDI\_IN± and SDI\_IN1± based on the IN\_MUX\_SEL pin logic settings provided in Table 6-2. These settings can be overridden through register control by applying the appropriate override bit values. For more information, refer to the LMH12x9 Programming Guide.

Table 6-2. IN MUX SEL Pin Settings

LEVEL <sup>(1)</sup>	DEFINITION
Н	Select SDI IN±
F	Gelect ODI_INT
R	Select SDI IN1±
L	JORICH SDI_IIVIT

 See Pin Configurations and Functions for LMH12x9 pin mapping details.

#### Note

Either positive (+) or negative (-) polarity can be used for SDI IN± and SDI IN1± for the 75Ω SDI input signal. The unused polarity should be AC terminated with external  $4.7\mu F$  and  $75\Omega$  to GND.

#### 6.3.2.2 Output Mux and SDI OUT Selection

The OUT MUX SEL and SDI OUT SEL pins select the LMH12x9 output data-path routes. Table 6-3 and Table 6-4 show how to configure the output signal path for various configurations.

Table 6-3. OUT MUX SEL Pin Settings

LEVEL <sup>(1)</sup>	DEFINITION
Н	Disable OUT0± Disable OUT1±
F	Enable OUT0± Disable OUT1±
R	Enable OUT0± Enable OUT1±
L	Enable OUT0± Disable OUT1±

See Pin Configurations and Functions for LMH12x9 pin mapping details.

Table 6-4. SDI\_OUT\_SEL Pin Settings

LEVEL <sup>(1)</sup>	DEFINITION					
Н	Disable SDI_OUT±					
L	Enable SDI_OUT±					

See Pin Configurations and Functions for LMH12x9 pin mapping details.

### 6.3.3 Input Carrier Detect

The LMH12x9 has a carrier detect circuit to monitor the presence or absence of an input signal. When the input signal amplitude for the selected input exceeds the carrier detect assert threshold, the LMH12x9 operates in normal operation mode.

In the absence of an input signal, the LMH12x9 automatically goes into Power Save mode to conserve power dissipation. When a valid signal is detected, the LMH12x9 automatically exits Power Save mode and returns to the normal operation mode. If the ENABLE pin is pulled low, the LMH12x9 is forced into Power-Down mode. In Power Save mode, both the carrier detect circuit and the serial interface remain active. In Power-Down mode, only the serial interface (SMBus or SPI based on MODE SEL pin) remains active.

Users can monitor the status of the carrier detect through register programming. This can be done either by configuring the LOCK N pin to output the CD N status or by monitoring the carrier detect status register.

#### 6.3.4 Adaptive Cable Equalizer (SDI IN±, SDI IN1±)

The LMH12x9 receiver features an adaptive continuous-time linear equalizer (CTLE) and a continuously adaptive three-tap decision feedback equalizer (DFE).

- CTLE: Compensates for frequency-dependent loss due to the transmission media prior to the device input. The CTLE accomplishes this by applying variable gain to the input signal, thereby boosting higher frequencies more than lower frequencies. The CTLE block extends the signal bandwidth, restores the signal amplitude, and reduces ISI caused by the transmission medium. The CTLE adapts once following each signal detection event.
- Three-tap DFE: Works in tandem with the CTLE to provide additional insertion loss compensation alongside crosstalk and reflection tolerance. The DFE is continuously-adaptive to compensate for temperature-related variations in the channel.

Product Folder Links: LMH1229 LMH1239

#### Note

The CTLE can be manually overridden through register control. Manual override is not recommended for data rates where reclocker is enabled (see Table 6-5).

Adaptive cable equalization is enabled by default. The LMH12x9 SDI\_input (SDI\_IN, SDI\_IN1) has an on-chip  $75-\Omega$  termination to the input common-mode voltage and includes a series return loss compensation network for meeting stringent SMPTE return loss requirements. The cable equalizer is designed with high gain and low noise circuitry to compensate for the insertion loss of a coaxial cable (such as Belden 1694A), which is widely used in broadcast video infrastructures.

#### Note

Adaptation is not applied for data rate inputs where the relocker is bypassed (including MADI). When operating with the reclocker bypassed, the appropriate EQ index must be programmed manually.

### 6.3.5 Clock and Data (CDR) Recovery

After the input signal passes through the adaptive cable equalizer, the equalized data is fed into the clock and data recovery (CDR) block. Using an internal PLL, the CDR locks to the incoming equalized data and recovers a clean internal clock to re-sample the equalized data. The LMH12x9 CDR is able to tolerate high input jitter, tracking low-frequency input jitter below the PLL bandwidth while reducing high-frequency input jitter above the PLL bandwidth. The supported data rates are listed in Table 6-5.

Table 6-5. Supported Data Rates

INPUT	DATA RATE	RECLOCKER
SDI IN+ or SDI IN1+	11.88Gbps, 5.94Gbps, 2.97Gbps, 1.485Gbps, 270Mbps <sup>(1)</sup>	Enable
3DI_INT 01 3DI_INT+	All other data rates (including 125Mbps)	Bypass

<sup>(1)</sup> The LMH12x9 supports divide-by-1.001 lock rates for 11.88Gbps, 5.94Gbps, 2.97Gbps, and 1.485Gbps.

#### 6.3.6 CDR Loop Bandwidth Control

A key characteristic of CDR operation is the loop bandwidth. Input jitter at frequencies above the -3dB CDR loop bandwidth are attenuated by the CDR, while input jitter at frequencies below the -3dB CDR loop bandwidth are tracked but not attenuated at the CDR output. Depending on the input jitter present at the LMH12x9 input and application needs for the LMH12x9 output jitter, the CDR loop bandwidth can be adjusted.

The LMH12x9 features a highly configurable CDR loop bandwidth that can be controlled by either pin or register settings.

#### Note

The default LMH12x9 CDR loop bandwidth (no external capacitor on LF+ and LF- pins) are comparable to previous generation LMH1219 and LMH1297 (EQ Mode) devices. To enable a lower CDR loop bandwidth, an external 470nF capacitor on LF+ and LF- is required.

#### 6.3.7 Output Function Control

The LMH12x9 output function control for data routed to outputs SDI\_OUT, OUT0, and OUT1 is configured by the OUT\_CTRL pin. The OUT\_CTRL pin determines whether to bypass the input cable equalizer, reclocker, or both. In normal operation (OUT\_CTRL = F), both input equalizer and reclocker are enabled.

Table 6-6 lists the OUT\_CTRL pin logic settings. These settings can be overridden through register control by applying the appropriate override bit values. For more information, refer to the LMH12x9 Programming Guide.



Table 6-6, OUT CTRL Settings for Bypass Modes

OUT_CTRL <sup>(1)</sup> SDI INPUT CABLE EQUALIZER		RECLOCKER	DEFINITION
H, F	Enable	Enable	Normal operation OUT0, SDI_OUT, and OUT1: Recovered Data, Cable EQ (CTLE, DFE) and reclocker enabled
R	R Enable Enable		OUT0 and SDI_OUT: Recovered Data, Cable EQ (CTLE, DFE) and reclocker enabled OUT1: Full-Rate Recovered Clock if Data Rate ≤ 2.97Gbps. 297MHz Recovered Clock if Data Rate > 2.97Gbps
L	Enable	Bypass	Debug Only OUT0, SDI_OUT, and OUT1: Equalized Data, Cable EQ (CTLE, DFE) enabled and reclocker bypassed <sup>(2)</sup>

- See Pin Configurations and Functions for LMH12x9 pin mapping details.
- When OUT CTRL = L, the reclocker is bypassed but not powered down (that is, still locked), as the reclocker is needed for the DFE to function properly.

#### 6.3.8 Output Driver Control

### 6.3.8.1 Line-Side 75Ω Output Cable Driver (SDI\_OUT±)

The LMH12x9 has one output cable driver (CD) block for SDI OUT. The SDI output is designed to drive 75Ω single-ended coaxial cables at data rates up to 11.88Gbps. SDI OUT features an integrated 75Ω termination and return loss compensation network for meeting stringent SMPTE return loss requirements.

#### 6.3.8.1.1 Output Amplitude (VOD)

SDI\_OUT serves as a loop-through output and is designed for transmission across  $75\Omega$  single-ended impedance. The nominal SDI cable driver output amplitude (VOD) is 800mVpp single-ended. In the presence of long output cable lengths or crosstalk, the SDI VOD pin can be used to optimize the cable driver output with respect to the nominal amplitude. Table 6-7 details VOD settings that can be applied to SDI OUT. The SDI VOD pin can be overridden through register control. In addition, the nominal VOD amplitude can be changed by register control. For more information, refer to the LMH12x9 Programming Guide.

Table 6-7. SDI VOD Settings for Line-Side Output **Amplitude** 

SDI_VOD(1)	DESCRIPTION
Н	about +5% of nominal
F	800mVpp (nominal)
R	about +10% of nominal
L	about –5% of nominal

See Pin Configurations and Functions for LMH12x9 pin mapping details.

#### 6.3.8.1.2 Output Pre-Emphasis

In addition to SDI cable driver VOD control, the LMH12x9 can add pre-emphasis on the cable driver output to improve output signal integrity when the reclocker recovers a UHD (12G, 6G) or HD (3G, 1.5G) input data rate. By default, pre-emphasis is enabled for 12G and 6G data rates, and is disabled for all other data rates. When pre-emphasis is disabled, the effects of crosstalk on SDI IN are minimized at SDI OUT. When enabled, the amount of pre-emphasis applied to the cable driver output is determined by register control. If the reclocker is bypassed or if the user desires to disable automatic pre-emphasis, pre-emphasis can be enabled manually through register control. For more information, refer to the LMH12x9 Programming Guide.

#### 6.3.8.1.3 Output Slew Rate

SMPTE specifications require different output driver rise and fall times depending on the operating data rate. To meet these requirements, the output edge rate of SDI OUT is automatically programmed according to the signal recovered by the reclocker. Typical edge rates at the cable driver output are shown in the Electrical Characteristics table.

Product Folder Links: LMH1229 LMH1239

If the reclocker is bypassed, users must program the desired edge rate manually through register control. For more information, refer to the LMH12x9 Programming Guide.

#### 6.3.8.1.4 Output Polarity Inversion

Polarity inversion is supported on the SDI OUT output through register control.

# 6.3.8.2 Host-Side 100Ω Output Driver (OUT0±, OUT1±)

OUT0 and OUT1 are host-side  $100\Omega$  driver outputs from the SDI input cable equalizer. Both OUT0 and OUT1 also support polarity inversion.

The driver offers the capability to select higher output amplitude and de-emphasis levels for longer board trace that connects the drivers to their downstream receivers. Driver de-emphasis provides transmitter equalization to reduce the ISI caused by the board trace.

The VOD\_DE pin determines the output amplitude (VOD) and de-emphasis levels applied to the OUT0 and OUT1 PCB driver. These settings can be changed through register control if finer resolution in settings is desired.

Table 6-8 details the OUT0 and OUT1 VOD and de-emphasis settings that can be applied. The VOD\_DE pin settings can be overridden by register control. When these parameters are controlled by registers, the VOD and de-emphasis levels can be programmed independently. For more information, refer to the LMH12x9 Programming Guide.

Table 6-6. VOD_DE 1 III Settings									
VOD_DE(1)	OUT0± and OUT1± VOD (mVpp)	OUT0± and OUT1± DEM (dB)	RECOMMENDED BOARD TRACE AT OUT0± and OUT1±(2)						
Н	410	0	< 1 inch						
F	560	-1.0	1-2 inches						
R	635	-2.4	4-5 inches						
L	810	-6.1	8-10 inches						

Table 6-8. VOD DE Pin Settings

#### 6.3.9 Debug and Diagnostic Features

# 6.3.9.1 Internal Eye Opening Monitor (EOM)

The LMH12x9 has an on-chip eye opening monitor (EOM) that can be used to analyze, monitor, and diagnose the post-equalized waveform, just prior to the CDR reclocker.

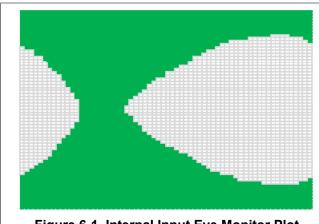
The EOM monitors the post-equalized waveform in a time window that spans one unit interval and a configurable voltage range that spans up to  $\pm 400$ mV. The time window and voltage range are divided into 64 steps, so the result of the eye capture is a 64 × 64 matrix of hits, where each point represents a specific voltage and phase offset relative to the main data sampler. The number of hits registered at each point needs to be taken in context with the total number of bits observed at that voltage and phase offset to determine the corresponding probability for that point.

The resulting 64 × 64 matrix produced by the EOM can be processed by software and visualized in a number of ways. Figure 6-1 and Figure 6-2 show two common ways to visualize this data. These diagrams depict examples of eye monitor plots implemented by software. The first plot is an example using the EOM data to plot a basic eye using ASCII characters, which can be useful for diagnostic software. The second plot shows the first derivative of the EOM data, revealing the density of hits and the actual waveforms and crossings that comprise the eye.

<sup>(1)</sup> See Pin Configurations and Functions for LMH12x9 pin mapping details.

<sup>(2)</sup> Recommended board trace at 11.88Gbps.





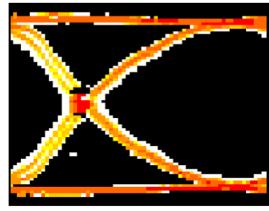


Figure 6-1. Internal Input Eye Monitor Plot

Figure 6-2. Internal Eye Monitor Hit Density Plot

A common measurement performed by the EOM is the horizontal and vertical eye opening. The horizontal eye opening (HEO) represents the width of the post-equalized eye at 0V differential amplitude, measured in unit intervals or picoseconds (ps). The vertical eye opening (VEO) represents the height of the post-equalized eye, measured midway between the mean zero crossing of the eye. This position in time approximates the CDR sampling phase. HEO and VEO measurements can be read back through register control.

#### 6.3.9.2 PRBS Generator, Error Checker, and Error Injector

Each LMH12x9 transmitter output can be configured independently to output a PRBS-7, PRBS-9, PRBS-23, or PRBS-31 for debug purposes. To output a PRBS signal, the LMH12x9 input must be CDR locked to a valid incoming signal at the same rate as the desired PRBS output generated rate.

The LMH12x9 SDI receiver input (SDI\_IN or SDI\_IN1) can be configured as a PRBS error checker, capable of identifying and tracking PRBS-7, PRBS-9, PRBS-23, or PRBS-31 signals for errors for debug purposes. To enable PRBS error checker functionality, the LMH12x9 must be locked to a valid SDI data rate.

To check the accuracy of the PRBS error checker, each transmitter, when configured as a PRBS generator, can be programmed to inject a single bit error through register control. This error injection ability allows users to verify that the PRBS generator is outputting correctly and that PRBS error checker is functioning as expected.

### 6.3.9.3 Status Indicators and Interrupts

The LOCK\_N pin is a 3.3V tolerant, active-low, open-drain output. An external resistor to the logic supply is required. The LOCK\_N pin can be configured to indicate reclocker lock, input carrier detect, cable fault detection, or an interrupt event.

### 6.3.9.3.1 LOCK\_N (Lock Indicator)

By default, LOCK\_N is the reclocker lock indicator, and this pin asserts low when the LMH12x9 achieves lock to a valid SMPTE data rate. The LOCK\_N pin functionality can also be configured through register control to indicate CD\_N (carrier detect) or INT\_N (interrupt) events. For more information about how to reconfigure the LOCK N pin functionality, refer to the LMH12x9 Programming Guide.

### 6.3.9.3.2 CD\_N (Carrier Detect)

The LOCK\_N pin can be reconfigured through register control to indicate a CD\_N (carrier detect) event. When configured as a CD\_N output, the pin asserts low at the end of adaptation after a valid signal is detected by the carrier detect circuit of the selected input. For more information about how to configure the LOCK\_N pin for CD\_N functionality, refer to the LMH12x9 Programming Guide.

### 6.3.9.3.3 Cable Fault Detection (SDI OUT+ Only)

The LMH12x9 features cable fault detection to indicate when no cable is connected to the SDI\_OUT+ output. Cable fault detection can determine a fault for up to 600m of Belden 1694A cable at SDI\_OUT+. This feature allows a method for users to react to cable attachment and removal.

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When SDI\_OUT\_SEL is enabled, the LMH12x9 senses the SDI\_OUT+ amplitude. If the output is not properly terminated (through a terminated cable or local termination), the cable fault detection signal asserts. The cable fault detection signal deasserts when a proper  $75\Omega$  termination is applied.

If cable fault detection is used to power down the LMH12x9 through the ENABLE pin, periodic polling with the LMH12x9 momentarily powered up is recommended to monitor the SDI\_OUT+ termination.

#### Note

Cable Fault Detection is only available when using the SDI OUT+ polarity.

#### 6.3.9.3.4 INT N (Interrupt)

The LOCK\_N pin can be configured to indicate an INT\_N (interrupt) event. When configured as an INT\_N output, the pin asserts low when an interrupt occurs, according to the programmed interrupt masks. Four separate masks can be programmed through register control as interrupt sources:

- If there is a loss of signal (LOS) event on the SDI input, irrespective of the input channel (SDI\_IN± or SDI\_IN1±) selected (two separate masks).
- If a CDR Lock event has occurred (two separate masks).

INT\_N is a sticky bit, meaning that the bit flags after an interrupt occurs and will not clear until read-back. After the Interrupt Status Register is read, the INT\_N pin asserts high again. For more information about how to configure the LOCK N pin for INT N functionality, refer to the LMH12x9 Programming Guide.

#### 6.3.9.4 Additional Programmability

The LMH12x9 supports extended programmability through SPI or SMBus serial control interface. Such added programmability includes:

- Cable EQ Index (CEI)
- Digital MUTE<sub>REE</sub>

#### 6.3.9.4.1 Cable EQ Index (CEI)

The Cable EQ Index (CEI) indicates the cable EQ boost index used at SDI\_IN+. CEI is accessible through register control. The 6-bit setting ranges in decimal value from 0 to 55 (000000'b to 110111'b in binary), with higher values corresponding to larger gain applied at the SDI input.

## 6.3.9.4.2 Digital MUTE<sub>REF</sub>

Digital MUTE<sub>REF</sub> sets the threshold for the maximum cable length at the SDI input to be equalized before muting the outputs. The MUTE<sub>REF</sub> register value is directly proportional to the cable length being equalized. MUTE<sub>REF</sub> is data rate dependent. Refer to the LMH12x9 Programming Guide to set the MUTE<sub>REF</sub> threshold for any desired SDI rate.



## **6.4 Device Functional Modes**

The LMH12x9 operates in one of two modes: System Management Bus (SMBus) or Serial Peripheral Interface (SPI) mode. To determine the mode of operation, the proper setting must be applied to the MODE\_SEL pin at power-up, as detailed in Table 6-9.

Table 6-9. MODE\_SEL Pin Settings

	<u> </u>						
LEVEL <sup>(1)</sup>	DEFINITION						
H <sup>(2)</sup>	Forced Power Save Mode, only SPI is enabled (all other circuitry powered down)						
F	Select SPI for register access						
R	Reserved for factory testing – do not use						
L	Select SMBus Interface for register access						

- (1) See Pin Configurations and Functions for LMH12x9 pin mapping details.
- (2) For pin compatibility, note that the LMH1297 pin configuration defines Level H as "Reserved for factory testing – do not use."

### 6.4.1 System Management Bus (SMBus) Mode

The SMBus interface can also be used to control the device. If MODE\_SEL = Low (1 k $\Omega$  to VSS), PICO\_SDA and SCK\_SCL pins are configured as SDA and SCL. CS\_N\_ADDR0 and POCI\_ADDR1 pins are address straps ADDR0 and ADDR1 during power up. The maximum operating speed supported on the SMBus pins is 400kHz.

Table 6-10. SMBus Device Target Addresses (1)

ADDR0 (LEVEL)	ADDR1 (LEVEL)	7-BIT TARGET ADDRESS [HEX]	8-BIT WRITE COMMAND [HEX]
L	L	3D	7A
L	R	3E	7C
L	F	3F	7E
L	Н	40	80
R	L	41	82
R	R	42	84
R	F	43	86
R	Н	44	88
F	L	45	8A
F	R	46	8C
F	F	47	8E
F	Н	48	90
Н	L	49	92
Н	R	4A	94
Н	F	4B	96
Н	Н	4C	98

<sup>(1)</sup> The 8-bit write command consists of the 7-bit target address (Bits 7:1) with 0 appended to the LSB to indicate an SMBus write. For example, if the 7-bit target address is 0x3D (011 1101'b), the 8-bit write command is 0x7A (0111 1010'b).

Product Folder Links: LMH1229 LMH1239

#### 6.4.1.1 SMBus Read and Write Transaction

SMBus is a two-wire serial interface through which various system component chips can communicate with the controller. Target devices are identified by having a unique device address. The two-wire serial interface consists of SCL and SDA signals. SCL is a clock output from the controller to all of the target devices on the bus. SDA is a bidirectional data signal between the controller and target devices. The LMH12x9 SMBus SCL and SDA signals are open-drain and require external pullup resistors.

#### Start and Stop:

The controller generates Start and Stop patterns at the beginning and end of each transaction.

- Start: High to low transition (falling edge) of SDA while SCL is high.
- · Stop: Low to high transition (rising edge) of SDA while SCL is high.

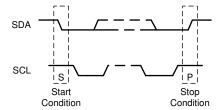


Figure 6-3. Start and Stop Conditions

The controller generates nine clock pulses for each byte transfer. The 9th clock pulse constitutes the ACK cycle. The transmitter releases SDA to allow the receiver to send the ACK signal. An ACK is recorded when the device pulls SDA low, while a NACK is recorded if the line remains high.

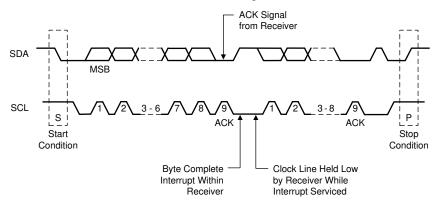


Figure 6-4. Acknowledge (ACK)

#### 6.4.1.1.1 SMBus Write Operation Format

Writing data to a target device consists of three parts, as illustrated in Figure 6-5:

- 1. The controller begins with a start condition followed by the target device address with the R/ $\overline{W}$  bit set to 0'b.
- 2. After an ACK from the target device, the 8-bit register word address is written.
- 3. After an ACK from the target device, the 8-bit data is written, followed by a stop condition.

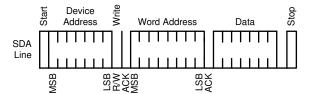


Figure 6-5. SMBus Write Operation

#### 6.4.1.1.2 SMBus Read Operation Format

SMBus read operation consists of four parts, as illustrated in Figure 6-6:

- 1. The controller begins with a start condition, followed by the target device address with the R/ W bit set to 0'b.
- 2. After an ACK from the target device, the 8-bit register word address is written.
- 3. After an ACK from the target device, the controller initiates a restart condition, followed by the Target address with the R/ $\overline{W}$  bit set to 1'b.
- 4. After an ACK from the target device, the 8-bit data is read-back. The last ACK is high if there are no more bytes to read, and the last read is followed by a stop condition.

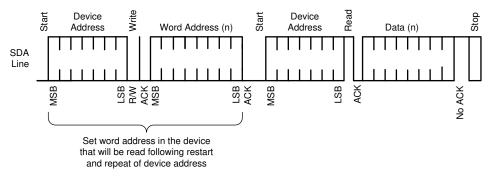


Figure 6-6. SMBus Read Operation

### 6.4.2 Serial Peripheral Interface (SPI) Mode

If MODE\_SEL = F or H, the LMH12x9 is in SPI mode. In SPI mode, the following pins are used for SPI bus communication:

- · PICO SDA: Peripheral Input Controller Output
- POCI ADDR1: Peripheral Output Controller Input
- CS N ADDR0: Chip Select (Active Low)
- SCK SCL: Serial Clock (Input to the LMH12x9 peripheral device)

#### 6.4.2.1 SPI Read and Write Transactions

Each SPI transaction to a single device is 17 bits long and is framed by CS\_N when asserted low. The PICO input is ignored, and the POCI output is floated whenever CS N is deasserted (high).

The bits are shifted in left-to-right. The first bit is R/ $\overline{W}$ , which is 1'b for *read* and 0'b for *write*. Bits A7-A0 are the 8-bit register address, and bits D7-D0 are the 8-bit read or write data. The previous SPI command, address, and data are shifted out on POCI as the current command, address, and data are shifted in on PICO. In all SPI transactions, the POCI output signal is enabled asynchronously when CS\_N asserts low. The contents of a single PICO or POCI transaction frame are shown in Table 6-11.

Table 6-11. 17-Bit Single SPI Transaction Frame																
R/W	A7	A6	A5	A4	A3	A2	A1	A0	D7	D6	D5	D4	D3	D2	D1	D0

#### 6.4.2.1.1 SPI Write Transaction Format

For SPI writes, the R/W bit is 0'b. SPI write transactions are 17 bits per device, and the command is executed on the rising edge of CS N. The SPI transaction always starts on the rising edge of the clock.

The signal timing for a SPI Write transaction is shown in Figure 6-7. The *prime* values on POCI (for example, A7') reflect the contents of the shift register from the previous SPI transaction and are do not care for the current transaction.

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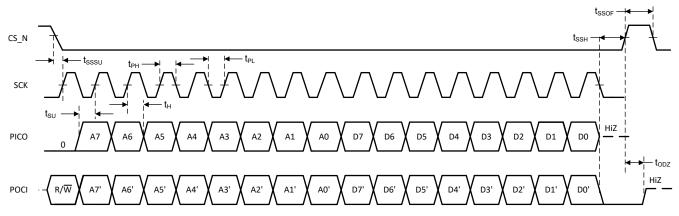


Figure 6-7. Signal Timing for a SPI Write Transaction

#### 6.4.2.1.2 SPI Read Transaction Format

A SPI read transaction is 34 bits per device and consists of two 17-bit frames. The first 17-bit read transaction frame shifts in the address to be read, followed by a dummy transaction second frame to shift out 17-bit read data. The R/W bit is 1'b for the read transaction, as shown in Figure 6-8.

The first 17 bits from the read transaction specifies 1-bit of R/W and 8-bits of address A7-A0 in the first 8 bits. The eight 1's following the address are ignored. The second dummy transaction acts like a read operation on address 0xFF and needs to be ignored. However, the transaction is necessary to shift out the read data D7-D0 in the last 8 bits of the POCI output. As with the SPI Write, the *prime* values on POCI during the first 16 clocks are listed as do not care for this portion of the transaction. The values shifted out on POCI during the last 17 clocks reflect the read address and 8-bit read data for the current transaction.

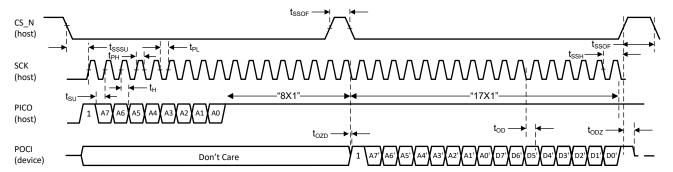


Figure 6-8. Signal Timing for a SPI Read Transaction

#### 6.4.2.2 SPI Daisy Chain

The LMH12x9 supports SPI daisy-chaining among multiple devices, as shown in Figure 6-9.

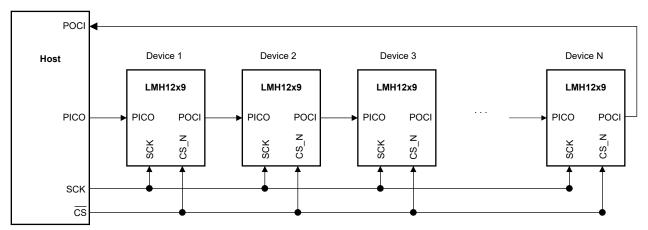


Figure 6-9. Daisy-Chain Configuration

Each LMH12x9 device is directly connected to the SCK and CS\_N pins of the host. The first LMH12x9 device in the chain is connected to the host's PICO pin, and the last device in the chain is connected to the host's POCI pin. The PICO pin of each intermediate LMH12x9 device in the chain is connected to the POCI pin of the previous LMH12x9 device, thereby creating a serial shift register. In a daisy-chain configuration of N  $\times$  LMH12x9 devices, the host conceptually sees a shift register of length 17  $\times$  N for a basic SPI transaction, during which CS\_N is asserted low for 17  $\times$  N clock cycles.

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# 7 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

# 7.1 Application Information

### 7.1.1 SMPTE Requirements and Specifications

SMPTE specifies several key requirements for the Serial Digital Interface to transport digital video over coaxial cables. Such requirements include return loss, AC coupling, and data rate dependency with rise and fall times.

- 1. **Return Loss:** This specification details how closely the port resembles 75Ω impedance across a specified frequency band. The LMH12x9 features a built-in 75Ω return-loss network on SDI\_IN, SDI\_IN1, and SDI\_OUT to minimize parasitics and improve overall signal integrity.
- 2. **AC Coupling:** AC-coupling capacitors are required for transporting uncompressed serial data streams with heavy low-frequency content. The use of 4.7μF, AC-coupling capacitors is recommended to avoid low-frequency DC wander.
- 3. **Rise/Fall Time:** Output 75Ω signals are required to meet data dependent rise and fall timing. This improves the eye opening observed for the receiving device. The LMH12x9 SDI\_OUT cable driver features automatic edge rate adjustment to meet SMPTE rise and fall time requirements.

TI recommends placing the LMH12x9 as close as possible (approximately 1 inch) to the  $75\Omega$  BNC ports to meet SMPTE specifications.

### 7.1.2 Optimizing the Time to Adapt and Lock

When carrier detect is asserted, the LMH12x9 adapts the cable equalizer to the optimal CTLE and DFE settings and locks to the determined SDI data rate. In applications where not all SDI rates are used, the time required to adapt the equalizer and achieve CDR lock to the incoming signal can be optimized by manually programming the LMH12x9 to lock only to the expected data rates. Refer to the LMH12x9 Programming Guide for more details.

#### 7.1.3 Optimized Loop Bandwidth Settings for Diagnostic or Cascade Applications

The LMH12x9 default loop bandwidth setting is optimized for a wide variety of applications. For diagnostic or cascade applications, the SDI\_OUT cable driver output can be used for monitoring, fanout, or cable extender purposes. To minimize the impact of jitter peaking caused by multiple cascaded devices having the same CDR loop bandwidth setting, the LMH12x9 CDR loop bandwidth can be increased or decreased from the default setting by pin strap (LOOP\_BW\_SEL) or by register control. Refer to CDR Loop Bandwidth Control for information regarding CDR loop bandwidth control. For more granular loop bandwidth control than the LOOP\_BW\_SEL pin strap options, refer to the LMH12x9 Programming Guide.

#### 7.1.4 LMH1229 and LMH1297 (EQ Mode) Pin-to-Pin Compatibility

The LMH1229 pinout and footprint is compatible with the LMH1297 (12G-SDI Bidirectional I/O with Integrated Reclocker) when the LMH1297 is used in EQ mode. This pin compatibility enables an easy upgrade path for improved SDI cable reach performance. A summary of pinout differences is shown in Figure 7-1.



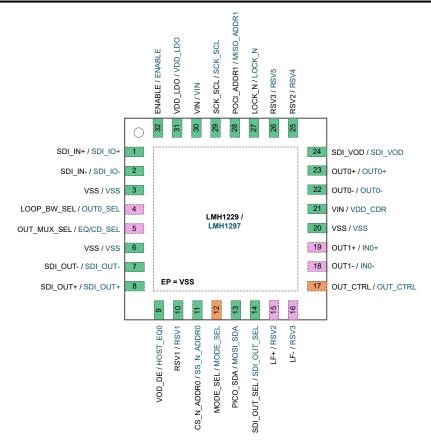


Figure 7-1. LMH1219 vs. LMH1297 Pinout Differences



For a detailed comparison of device pin functionality, refer to Table 7-1.

Table 7-1. LMH1229 vs. LMH1297 (EQ Mode) Pin-to-Pin Comparison

PIN NO.	LMH1229	LMH1297	DIFFERENCE SUMMARY <sup>(1)</sup>		
1	SDI_IN+	SDI_IO+	- None		
2	SDI_IN-	SDI_IO-	Note		
8	SDI_OUT+	SDI_OUT+	- None		
7	SDI_OUT-	SDI_OUT-	Notice		
23	OUT0+	OUT0+	No.		
22	OUT0-	OUT0-	None		
19	OUT1+	IN0+	LMH1229: Secondary 100Ω PCB output.		
18	OUT1-	INO-	LMH1297: Don't care. Pins are unused in EQ mode. For pin compatible functionality: Leave floating.		
4	LOOP_BW_SEL	OUT0_SEL	LMH1229: 4-level CDR loop bandwidth control.  LMH1297: Don't care. OUT0 always enabled in EQ mode.  For pin compatible functionality: Leave floating (Level F).		

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Table 7-1. LMH1229 vs. LMH1297 (EQ Mode) Pin-to-Pin Comparison (continued)

	14510 7 11 2111111220 101 2111		Transfer (Eq. mode) i in to i in companicon (continued)				
PIN NO.	LMH1229	LMH1297	DIFFERENCE SUMMARY <sup>(1)</sup>				
5	OUT_MUX_SEL	EQ/CD_SEL	LMH1229: 4-level output mux select control.  LMH1297: Tie low for EQ mode  For pin compatible functionality: Tie low for 100Ω OUT0 PCB output only.				
9	VOD_DE	HOST_EQ0	None				
12	MODE_SEL	MODE_SEL	LMH1229: Level H forces Power save mode (SPI enabled). LMH1297: Level H reserved. For pin compatible functionality: Use Levels F, R, or L only.				
14	SDI_OUT_SEL	SDI_OUT_SEL	None				
15	LF+	RSV2	LMH1229: Optional external loop filter cap (do not connect for default operation).				
16	LF-	RSV3	LMH1297: Reserved (do not connect). For pin compatible functionality: Leave floating.				
17	OUT_CTRL	OUT_CTRL	LMH1229: Selects bypass mode operation for OUT0, OUT1, and SDI_OUT.  LMH1297: Selects bypass mode operation for OUT0 only  For pin compatible functionality: Leave floating (Level F).				
24	SDI_VOD	SDI_VOD	None				
27	LOCK_N	LOCK_N	None				
32	ENABLE	ENABLE	None				
11	CS_N_ADDR0	SS_N_ADDR0	None Note: There are differences in LMH1229 vs. LMH1297 SMBus mode device addresses.				
28	POCI_ADDR1	MISO_ADDR1	None Note: There are differences in LMH1229 vs. LMH1297 SMBus mode device addresses.				
13	PICO_SDA	MOSI_SDA	None				
29	SCK_SCL	SCK_SCL	None				
10	RSV1	RSV1	None				
25	RSV2	RSV4	None				
26	RSV3	RSV5	None				
3, 6, 20	VSS	VSS	None				
30	VIN	VIN	None				
21	VIN	VDD_CDR	None. Connect to same supply as Pin 30 (VIN) externally.				
			· · · · · · · · · · · · · · · · · · ·				

<sup>(1)</sup> In the difference summary, LMH1297 is assumed to be operating in EQ mode.

# 7.2 Typical Application

The LMH12x9 is a long-reach cable equalizer with integrated reclocker that supports SDI data rates up to 11.88Gbps.

This device supports multiple configurations and can be used either as a pin-compatible upgrade to the previous generation LMH1297 in EQ mode (LMH1229) or a robust cable equalizer with redundant SDI inputs (LMH1239). Figure 7-2 shows a typical application circuit for the LMH1229.

Specific examples of typical applications for the LMH12x9 are detailed in the following subsections.

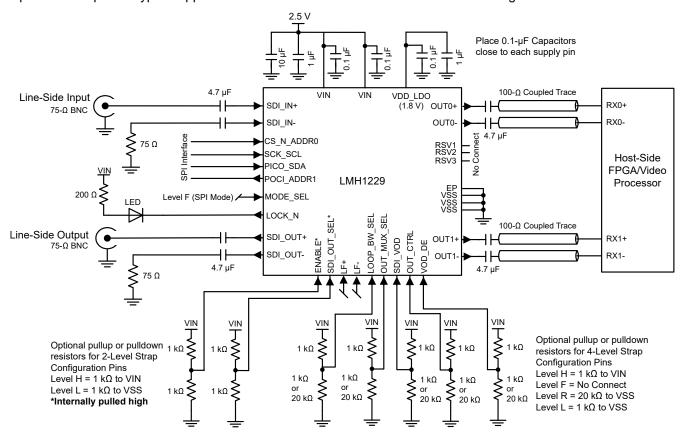


Figure 7-2. LMH12x9 SPI mode Connection Diagram

# 7.2.1 Cable Equalizer With Loop-Through

The LMH12x9 can be configured as a cable equalizer with loop-through output. The LMH12x9 takes in SDI data at the SDI\_IN adaptive cable equalizer input and outputs the reclocked SDI signal at OUT0 (primary output) and OUT1 (optional secondary output). Meanwhile, a redundant reclocked loop-through SDI signal is output on SDI\_OUT for system monitoring or cascade purposes.

Figure 7-3 shows a typical application of an LMH12x9 as a cable loop-through device. In this example, the LMH12x9 provides an SDI signal to the SDI FPGA on both OUT0 and OUT1. Concurrently, the equalized and reclocked SDI\_IN signal is sent to the loop-through SDI\_OUT cable driver output. Meanwhile, the FPGA sends post-processed SDI data out on an LMH1228 dual cable driver with integrated reclocker.

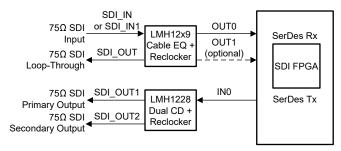


Figure 7-3. LMH12x9 Cable Loop-Through Application

### 7.2.1.1 Design Requirements

For general LMH12x9 design requirements, reference the guidelines in Table 7-2.

For cable equalizer with loop-through application-specific requirements, reference the guidelines in Table 7-3.

Table 7-2. General Design Requirements

DESIGN PARAMETER	REQUIREMENTS					
SDI_IN+, SDI_IN1+ (LMH1239 only), SDI_OUT+ AC-coupling capacitors	4.7μF 0402 surface mount ceramic capacitors recommended.					
SDI_IO-, SDI_IN1- (LMH1239 only), SDI_OUT-AC-coupling capacitors	4.7 $\mu$ F 0402 surface mount ceramic capacitors recommended, AC terminated with 75 $\Omega$ to VSS. Negative polarity can be used if positive polarity is AC terminated with 75 $\Omega$ to VSS.					
OUT0± and OUT1± AC-coupling capacitors	4.7μF 0402 surface mount ceramic capacitors recommended.					
Input and output terminations	Input and output terminations provided internally. Do <b>not</b> add external terminations.					
High-speed OUT0± and OUT1± trace impedance	Route the OUT0± and OUT1± with coupled board traces and 100 $\Omega$ differential impedance.					
SMPTE return loss	Place BNC within 1 inch of the LMH12x9 and consult BNC vendor for recommended BNC landing pattern to meet SMPTE requirements.					
SDI_IN+ and SDI_OUT+ crosstalk	When a long length coax cable is connected to SDI_IN+, the signal amplitude at SDI_IN+ can be just a few mVpp. Layout precautions must be taken to minimize crosstalk from adjacent devices or from adjacent output port SDI_OUT+. To reduce cross coupling effects, keep SDI_OUT+ traces as far from SDI_IN+ as possible. When SDI_OUT+ is not used, TI recommends to turn off the output (SDI_OUT_SEL = H) for best results.  Note: When using the LMH1239, the same design requirements are applicable for SDI_IN1+ and SDI_OUT+ too.					
DC power supply decoupling capacitors	10μF and 1μF bulk capacitors: place close to each device. 0.1μF capacitor: place close to each supply pin.					
VDD_LDO decoupling capacitors	1μF and 0.1μF capacitors: place as close as possible to the device VDD_LDO pin. Do <b>not</b> use VDD_LDO as a 1.8V power supply source to external components.					
MODE_SEL Pin	SPI: Leave MODE_SEL unconnected (Level F) SMBus: Connect 1kΩ to VSS (Level L)					
Input SDI Reclocked Data Rate	11.88Gbps, 5.94Gbps, 2.97Gbps, 1.485Gbps, or Divide-by-1.001 sub-rates and 270Mbps. For all other input data rates, the reclocker is automatically bypassed.					



Table 7-3. Cable Equalizer with Loop-Through Requirements

DESIGN PARAMETER	REQUIREMENTS
OUT_MUX_SEL Pin	$1k\Omega$ to VSS (Level L) or float (Level F) to enable OUT0± only. $20k\Omega$ to VSS (Level R) to enable both OUT0± and OUT1±.
LOOP_BW_SEL Pin	$1k\Omega$ to VIN (Level H) or float (Level F) for default CDR loop bandwidth operation (no external capacitor on LF±). $20k\Omega$ to VSS (Level R) or $1k\Omega$ to VSS (Level L) for decreased loop bandwidth (external capacitor required on LF±).
SDI_OUT_SEL Pin	1 k $\Omega$ to VSS (Level L) to enable cable loop-through SDI_OUT. 1 k $\Omega$ to VIN (Level H) to disable cable loop-through SDI_OUT.

### 7.2.1.2 Detailed Design Procedure

The design procedure for cable equalizer with loop-through applications is as follows:

- 1. Select a power supply that meets the DC and AC requirements in *Recommended Operating Conditions*.
- 2. Choose small 0402 surface mount ceramic capacitors for AC-coupling capacitors to maintain characteristic impedance.
- 3. Choose a high-quality,  $75\Omega$  BNC connector that is capable of supporting 11.88Gbps applications. Consult a BNC supplier regarding insertion loss, impedance specifications, and recommended footprint for meeting SMPTE return loss.
- 4. Follow detailed high-speed layout recommendations provided in *Layout Guidelines* to ensure optimal signal quality when interconnecting  $75\Omega$  and  $100\Omega$  signals to the LMH12x9.
- 5. Determine whether SPI or SMBus communication is necessary. If the LMH12x9 must be programmed with settings other than what is offered by pin control, users must use SPI or SMBus mode for additional programming.
- 6. Configure all two-level and four-level pins according to the desired use case. Note that pin settings can be overridden by register control.
- 7. Tune the VOD\_DE 100Ω driver control pin to equalize the PCB output trace following OUT0± and OUT1± (if used). Use register control for more tuning options if necessary.
- 8. If SDI\_OUT is used for diagnostic or cascade applications, tune the SDI\_VOD output amplitude control pin for optimal signal quality depending on the cable length attached at SDI\_OUT+. Use register control for more tuning options if necessary.

### 7.2.1.3 Application Curves

The LMH12x9 output eye performance was measured with the test setups shown in Figure 7-4 and Figure 7-5.

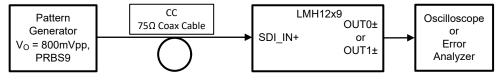


Figure 7-4. Test Setup for LMH12x9 PCB Output (OUT0±, OUT1±)

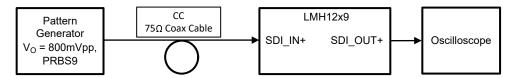


Figure 7-5. Test Setup for LMH12x9 Loop-Through (SDI\_OUT+)

The eye diagrams measured on the LMH1239EVM in this subsection show the LMH12x9  $100\Omega$  differential PCB output at OUT0± and OUT1± (Figure 7-7 - Figure 7-8) and LMH12x9  $75\Omega$  loop-through cable output at SDI OUT+ (Figure 7-9).

Additionally, LMH12x9 BER (bit error rate) performance was measured with the test setup shown in Figure 7-6. Phabrix Qx BER results on the LMH1239EVM are shown in Figure 7-10.

Product Folder Links: LMH1229 LMH1239

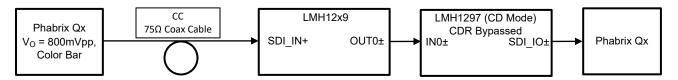
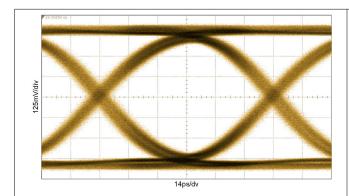
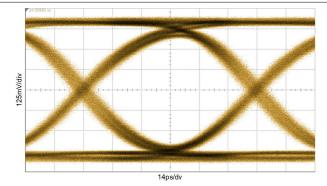


Figure 7-6. Test Setup for LMH12x9 BER Performance (OUT0±)



VOD\_DE = F, SDI\_OUT\_SEL = H, OUT\_CTRL = F Figure 7-7. OUT0± at 11.88 Gbps (12G-SDI), CC = 100m Belden 1694A, Reclocked



VOD\_DE = F, SDI\_OUT\_SEL = H, OUT\_CTRL = F Figure 7-8. OUT1± at 11.88 Gbps (12G-SDI), CC = 100m Belden 1694A, Reclocked

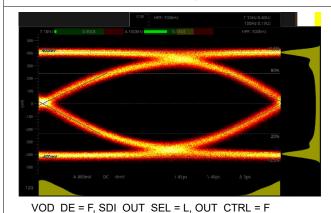
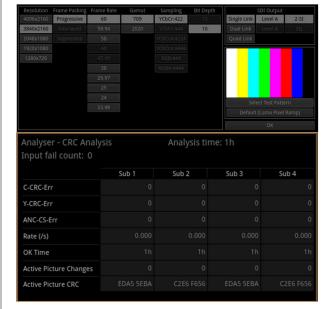


Figure 7-9. SDI\_OUT+ at 11.88Gbps (12G-SDI), CC = 90m Belden 1694A, Reclocked



VOD\_DE = F, SDI\_OUT\_SEL = H, OUT\_CTRL = F

Figure 7-10. OUT0± BER at 11.88Gbps (12G-SDI), CC = 100m Belden 1694A, Reclocked

### 7.2.2 Cable Equalizer With Redundant SDI Input (LMH1239 only)

The LMH1239 can be configured as a cable equalizer with redundant SDI input for applications requiring system robustness and routing flexibility. The SDI input data is selected from either SDI\_IN or SDI\_IN1 by the 2:1 input mux. The chosen SDI input is then fed through the adaptive cable equalizer, and the reclocked SDI signal is output on OUT0 (primary output) and OUT1 (optional secondary output). Meanwhile, a redundant reclocked loop-through SDI signal is output on SDI\_OUT for system monitoring or cascade purposes.

Figure 7-11 shows a typical application of a LMH1239 with redundant SDI input. In this example, the LMH1239 selects between a primary BNC input (SDI\_IN) and a back-up BNC input (SDI\_IN1). In this use case, SDI\_IN1 is only used if issues are found at SDI\_IN. The LMH1239 provides an SDI signal to the SDI FPGA on both OUT0 and OUT1.

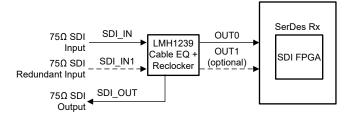


Figure 7-11. LMH1239 Cable Equalizer with Redundant SDI Input Application

#### 7.2.2.1 Design Requirements

See *Design Requirements* for general LMH12x9 design requirements.

For LMH1239 cable equalizer with redundant SDI input application-specific requirements, reference the guidelines in Table 7-4.

Table 7-4. LMH1239 Cable Equalizer with Redundant SDI Input Requirements

DESIGN PARAMETER	REQUIREMENTS				
IN_MUX_SEL Pin	$1$ kΩ to VIN (Level H) or leave floating (Level F) to select SDI_IN $20$ kΩ or $1$ kΩ to VSS (Level R, L) to select SDI_IN1				

#### 7.2.2.2 Detailed Design Procedure

See *Detailed Design Procedure* and follow all steps. Refer to additional steps below for redundant SDI input applications.

- 1. Determine the desired primary and secondary SDI input. For additional immunity in cable loop-through applications (SDI\_OUT\_SEL = L), SDI\_IN1 is recommended as the primary to maximize physical isolation (and minimize degradation from crosstalk) between SDI input and SDI output (SDI\_OUT).
- 2. Configure IN MUX SEL 4-level input according to the desired SDI input.

### 7.2.2.3 Application Curves

The LMH1239 output eye performance was measured with the test setup shown in Figure 7-12.

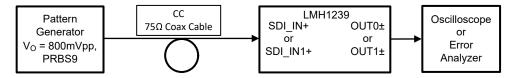


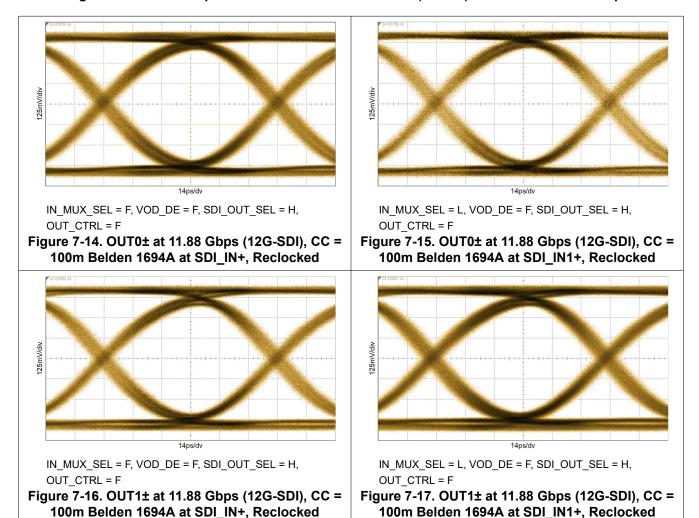
Figure 7-12. Test Setup for LMH1239 PCB Output with Redundant SDI Input

The eye diagrams measured on the LMH1239EVM in this subsection show the LMH1239  $100\Omega$  differential PCB output at OUT0± and OUT1± (Figure 7-14 - Figure 7-17).

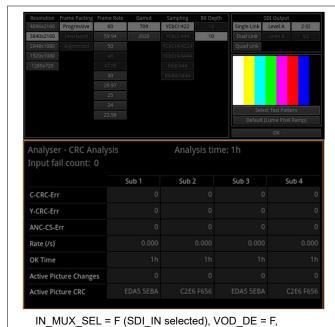
Additionally, LMH1239 BER (bit error rate) performance was measured with the test setup shown in Figure 7-13. Phabrix Qx BER results on the LMH1239EVM are shown in Figure 7-18 and Figure 7-19.

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Figure 7-13. Test Setup for LMH1239 BER Performance (OUT0±) with Redundant SDI Input

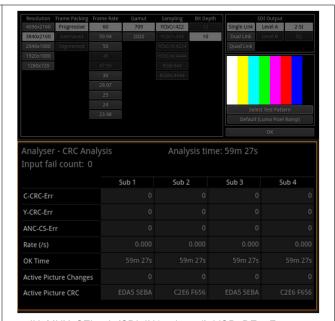






SDI\_OUT\_SEL = H, OUT\_CTRL = F

Figure 7-18. OUT0± BER at 11.88Gbps (12G-SDI), CC = 100m Belden 1694A, Reclocked



IN\_MUX\_SEL = L (SDI\_IN1 selected), VOD\_DE = F, SDI\_OUT\_SEL = H, OUT\_CTRL = F

Figure 7-19. OUT0± BER at 11.88Gbps (12G-SDI), CC = 100m Belden 1694A, Reclocked

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### 7.3 Power Supply Recommendations

The LMH12x9 requires decoupling capacitors to ensure a stable power supply. For power supply decoupling,  $0.1\mu F$  surface-mount ceramic capacitors must be placed close to each VDD\_LDO and VIN supply pin to VSS. Larger bulk capacitors (for example,  $10\mu F$  and  $1\mu F$ ) are recommended for VIN.

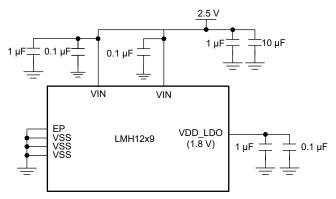


Figure 7-20. Recommended Power Supply Decoupling

Good supply bypassing requires low inductance capacitors. This can be achieved through an array of multiple small body size surface-mount bypass capacitors to keep low supply impedance. Better results can be achieved through the use of a buried capacitor formed by a VDD and VSS plane separated by 2mil to 4mil dielectric in a printed circuit board.

### 7.4 Layout

### 7.4.1 Layout Guidelines

The following guidelines are recommended to optimize the board layout for the LMH12x9.

#### 7.4.1.1 Board Stack-Up and Ground References

- Choose a suitable board stack-up that supports  $75\Omega$  single-ended trace and  $100\Omega$  differential trace routing on the top layer of the board. This is typically done with a Layer 2 ground plane reference for the  $100\Omega$  differential traces and a Layer 3 ground plane reference for the  $75\Omega$  single-end traces.
- Maintain a distance of at least 5 times the trace width between signal trace and ground reference if the signal trace and ground are on the same layer. This prevents unwanted changes in the characteristic impedance.
- Maintain a consistent ground plane reference for each high-speed trace from source to endpoint. Ground reference discontinuities lead to characteristic impedance mismatch.

### 7.4.1.2 High-Speed PCB Trace Routing and Coupling

Observe the following general high-speed recommendations for high-speed trace routing:

- For differential pairs, maintain a uniform width and gap for each differential pair where possible. When traces
  must diverge (for example, due to AC-coupling capacitors), ensure that the traces branch out or merge
  uniformly.
- To prevent reflections due to trace routing, ensure that trace bends are at most 45°. Implement right angle bends with at least two 45° corners. Radial bends are ideal.
- Avoid using signal vias. If signal vias must be used, a return path (GND) via must be placed near the signal
  via to provide a consistent ground reference and minimize impedance discontinuities.
- Avoid via stubs by back-drilling as necessary.

### 7.4.1.2.1 SDI IN± and SDI OUT±:

- Use an uncoupled trace with 75Ω single-ended impedance for signal routing to SDI\_IN± and SDI\_OUT±.
- The trace width is typically 8-10 mils with reference to a Layer-3 ground plane.
- The same layout guidelines are relevant to SDI\_IN1± when using the LMH1239.

#### 7.4.1.2.2 OUT0± and OUT1±:

- Use coupled traces with 100Ω differential impedance for signal routing to OUT0± and OUT1±.
- The trace width is typically 5-8 mils with reference to a Layer-2 ground plane.

#### 7.4.1.3 Anti-Pads

• Place anti-pads (ground relief) on the power and ground planes directly under the 4.7µF, AC-coupling capacitor and IC landing pads to minimize parasitic capacitance. The size of the anti-pad and the number of layers to use the anti-pad depend on the board stack-up and can be determined by a 3-dimension electromagnetic simulation tool.

### 7.4.1.4 BNC Connector Layout and Routing

- Use a well-designed BNC footprint to ensure the signal landing pad of the BNC achieves 75Ω characteristic impedance. BNC suppliers usually provide recommendations on BNC footprint for best results.
- Keep trace length short between the BNC and SDI\_IN±. Keep the trace routing for SDI\_IN+ and SDI\_INas symmetrical as possible, with approximately equal lengths and equal loading. The same is true for
  SDI\_OUT+ and SDI\_OUT-.
- The same layout guidelines are relevant to SDI\_IN1± when using the LMH1239.

### 7.4.1.5 Power Supply and Ground Connections

- Connect each supply pin (VIN, VDD\_LDO) directly to the power or ground planes with a short via. The via is usually placed tangent to the landing pads of the supply pins with the shortest trace possible.
- Make sure the power supply decoupling capacitors are a small physical size (0402 or smaller) and placed close to the supply pins to minimize inductance. The capacitors are commonly placed on the bottom layer and share the ground of the EP (Exposed Pad).

### 7.4.1.6 Footprint Recommendations

- Stencil parameters for the EP (Exposed Pad) such as aperture area ratio and the fabrication process have
  a significant impact on paste deposition. Inspection of the stencil prior to placement of the QFN package is
  highly recommended to improve board assembly yields. If the via and aperture openings are not carefully
  monitored, the solder can flow unevenly through the EP. Stencil parameters for aperture opening and via
  locations are shown in the RTV package drawing in the Mechanical, Packaging, and Orderable Information.
- The EP of the package must be connected to the ground plane through a 3 × 3 via array. These vias are solder-masked to avoid solder flowing into the plated-through holes during the board manufacturing process. Details about via dimensions are also shown in the RTV package drawing in *Mechanical*, *Packaging*, and Orderable Information.

More information on the QFN style package is provided in QFN/SON PCB Attachment application note.

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### 7.4.2 Layout Example

The example shown in Figure 7-21 demonstrates the layout guidelines highlighted in *Layout Guidelines* for the LMH1229. For layouts with the LMH1239, the same layout guidelines that apply to SDI\_IN+ are applicable to SDI\_IN1+. Refer to the LMH1239EVM User's Guide for more details.

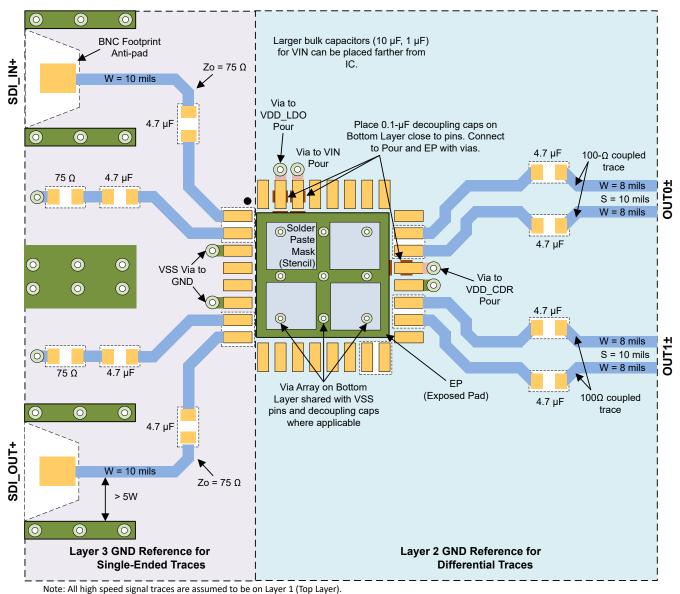


Figure 7-21. LMH12x9 High-Speed Trace Layout Example

# 8 Device and Documentation Support

# 8.1 Documentation Support

#### 8.1.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, A Study of the SDI Pathological Data Pattern application note
- Texas Instruments, QFN/SON PCB Attachment application note

### 8.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

# 8.3 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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#### 8.4 Trademarks

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## 8.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 8.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

# 9 Revision History

### Changes from Revision \* (June 2024) to Revision A (October 2024)

Page

Changed data sheet status from: Advanced Information to: Production Data......

# 10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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#### PACKAGING INFORMATION

Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking
	(1)	(2)			(3)	(4)	(5)		(6)
LMH1229RTVR	Active	Production	WQFN (RTV)   32	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	L1229
LMH1229RTVR.B	Active	Production	WQFN (RTV)   32	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	L1229
LMH1229RTVT	Active	Production	WQFN (RTV)   32	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	L1229
LMH1229RTVT.B	Active	Production	WQFN (RTV)   32	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	L1229
LMH1239RTVR	Active	Production	WQFN (RTV)   32	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	L1239
LMH1239RTVR.B	Active	Production	WQFN (RTV)   32	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	See LMH1239RTVR	L1239
LMH1239RTVT	Active	Production	WQFN (RTV)   32	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	L1239
LMH1239RTVT.B	Active	Production	WQFN (RTV)   32	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	See LMH1239RTVT	L1239

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

# **PACKAGE OPTION ADDENDUM**

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

# **PACKAGE MATERIALS INFORMATION**

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# TAPE AND REEL INFORMATION





	-
A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

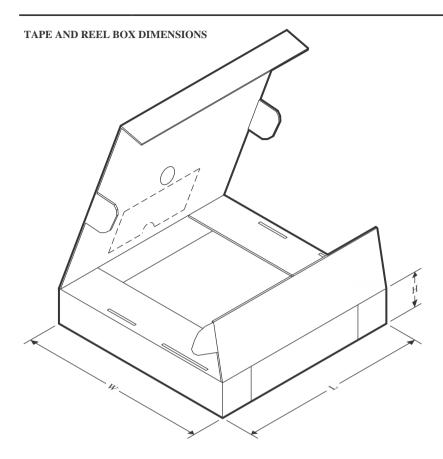


#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMH1229RTVR	WQFN	RTV	32	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
LMH1229RTVT	WQFN	RTV	32	250	180.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
LMH1239RTVR	WQFN	RTV	32	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2
LMH1239RTVT	WQFN	RTV	32	250	180.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2



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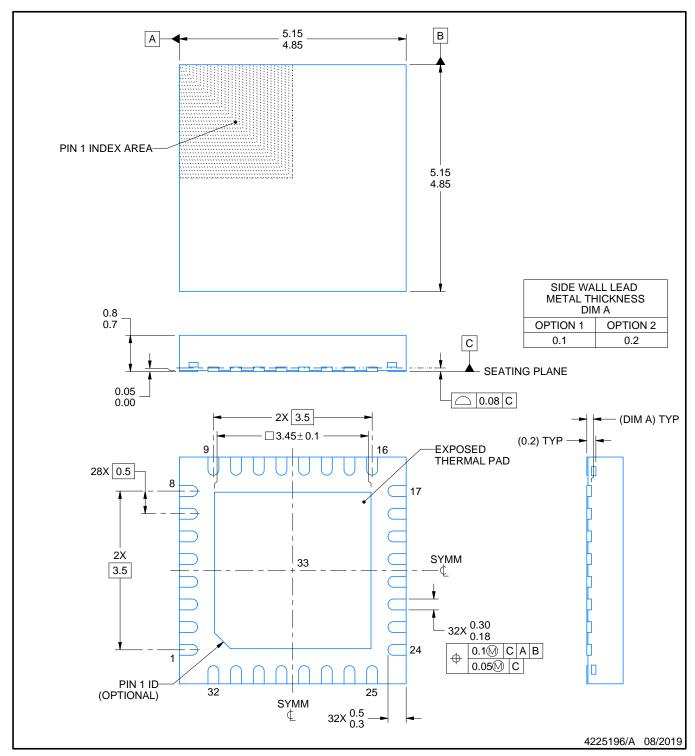


### \*All dimensions are nominal

	7 III dilitorio di o Tioriinidi									
	Device	Package Type Package Drawing		Pins	SPQ	Length (mm)	Width (mm)	Height (mm)		
	LMH1229RTVR	WQFN	RTV	32	3000	367.0	367.0	35.0		
ı	LMH1229RTVT	WQFN	RTV	32	250	210.0	185.0	35.0		
	LMH1239RTVR	WQFN	RTV	32	3000	367.0	367.0	35.0		
	LMH1239RTVT	WQFN	RTV	32	250	210.0	185.0	35.0		



PLASTIC QUAD FLATPACK - NO LEAD

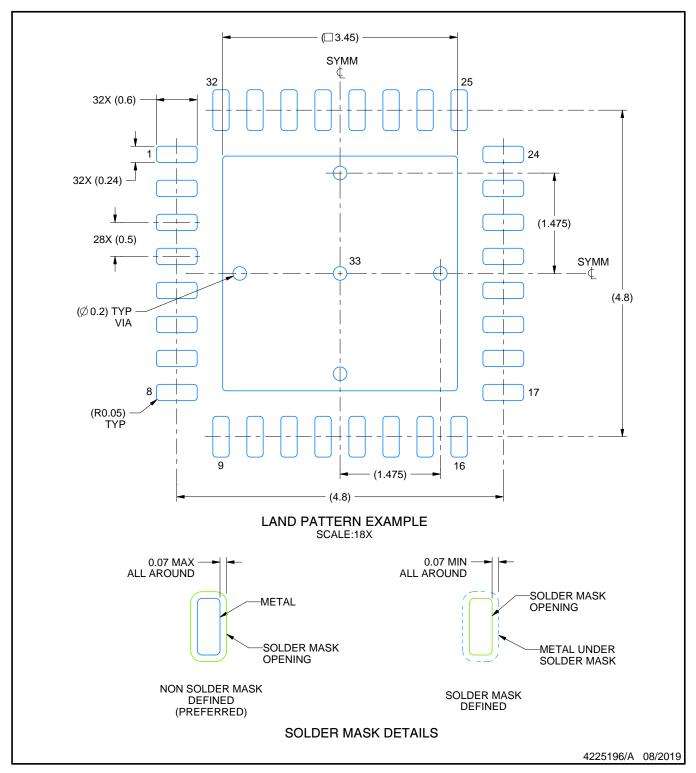


### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
  2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



PLASTIC QUAD FLATPACK - NO LEAD

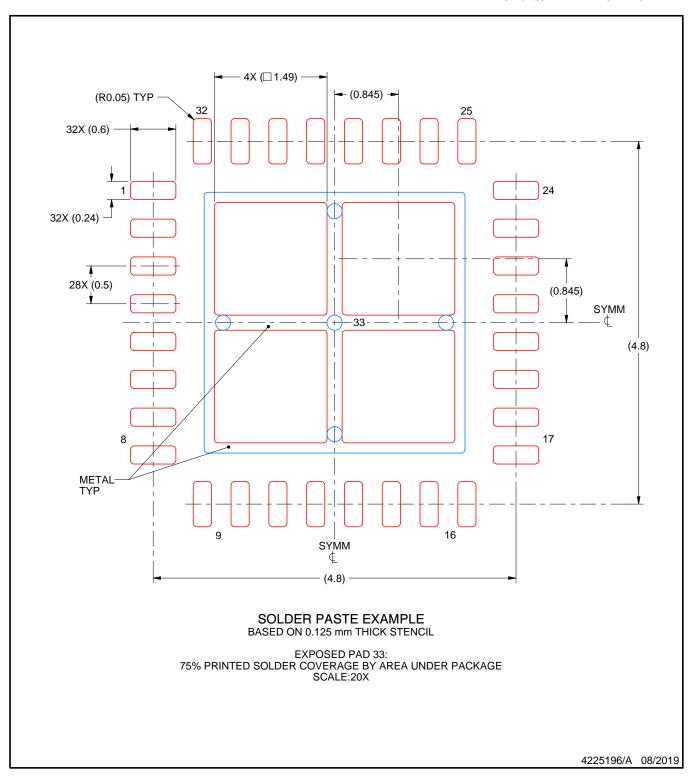


NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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