

# DAC082S085 8-Bit Micro Power DUAL Digital-to-Analog Converter With Rail-to-Rail Output

## 1 Features

- Ensured Monotonicity
- Low Power Operation
- Rail-to-Rail Voltage Output
- Power-On Reset to 0 V
- Simultaneous Output Updating
- Wide Power Supply Range: 2.7 V to 5.5 V
- Industry's Smallest Package
- Power-Down Modes
- Key Specifications:
  - Resolution: 8 Bits
  - INL:  $\pm 0.5$  LSB (Maximum)
  - DNL: 0.18 /  $-0.13$  LSB (Maximum)
  - Settling Time: 4.5  $\mu$ s (Maximum)
  - Zero Code Error: 15 mV (Maximum)
  - Full-Scale Error:  $-0.75\%$  FS (Maximum)
  - Supply Power:
    - Normal: 0.6 mW (3 V) / 1.6 mW (5 V) (Typical)
    - Power Down: 0.3  $\mu$ W (3 V) / 0.8  $\mu$ W (5 V) (Typical)

## 2 Applications

- Battery-Powered Instruments
- Digital Gain and Offset Adjustment
- Programmable Voltage and Current Sources
- Programmable Attenuators

## 3 Description

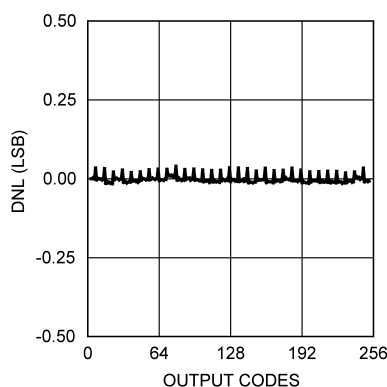
The DAC082S085 device is a full-featured, general-purpose, DUAL, 8-bit, voltage-output, digital-to-analog converter (DAC) that can operate from a single 2.7-V to 5.5-V supply and consumes 0.6 mW at 3 V and 1.6 mW at 5 V. The DAC082S085 is packaged in 10-pin SON and VSSOP packages. The 10-pin WSON package makes the DAC082S085 the smallest DUAL DAC in its class. The on-chip output amplifier allows rail-to-rail output swing, and the three-wire serial interface operates at clock rates up to 40 MHz over the entire supply voltage range. Competitive devices are limited to 25-MHz clock rates at supply voltages in the 2.7 V to 3.6 V range. The serial interface is compatible with standard SPI™, QSPI, MICROWIRE, and DSP interfaces.

### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
DAC082S085	VSSOP (10)	3.00 mm x 3.00 mm
	WSON (10)	3.00 mm x 3.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

**DNL at  $V_A = 3$  V**



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## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision F (March 2013) to Revision G	Page
<ul style="list-style-type: none"> <li>Added <i>ESD Ratings</i> table, <i>Feature Description</i> section, <i>Device Functional Modes</i>, <i>Application and Implementation</i> section, <i>Power Supply Recommendations</i> section, <i>Layout</i> section, <i>Device and Documentation Support</i> section, and <i>Mechanical, Packaging, and Orderable Information</i> section .....</li> <li>Changed <i>Thermal Information</i> table .....</li> </ul>	 1 6

Changes from Revision E (March 2013) to Revision F	Page
<ul style="list-style-type: none"> <li>Changed layout of National Data Sheet to TI format .....</li> </ul>	22

## 5 Description (continued)

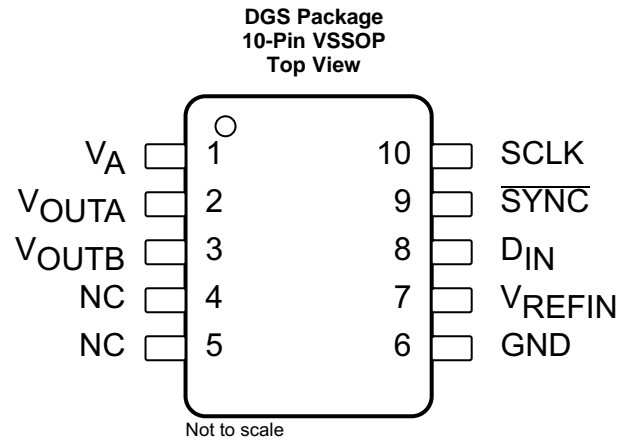
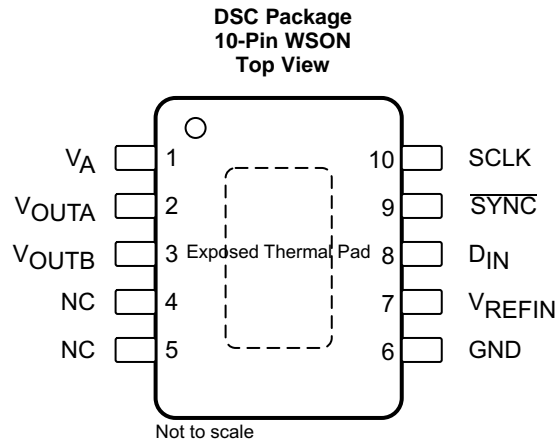
The reference for the DAC082S085 serves both channels and can vary in voltage between 1 V and  $V_A$ , providing the widest possible output dynamic range. The DAC082S085 has a 16-bit input shift register that controls the outputs to be updated, the mode of operation, the power-down condition, and the binary input data. Both outputs can be updated simultaneously or individually depending on the setting of the two mode of operation bits.

A power-on reset circuit ensures that the DAC output powers up to 0 V and remains there until there is a valid write to the device. A power-down feature reduces power consumption to less than a microWatt with three different termination options.

The low power consumption and small packages of the DAC082S085 make it an excellent choice for use in battery-operated equipment.

The DAC082S085 is one of a family of pin-compatible DACs, including the 10-bit DAC102S085 and the 12-bit DAC124S085. The DAC082S085 operates over the extended industrial temperature range of  $-40^{\circ}\text{C}$  to  $105^{\circ}\text{C}$ .

## 6 Pin Configuration and Functions



### Pin Functions

PIN		TYPE	DESCRIPTION
NO.	NAME		
1	$V_A$	Supply	Power supply input. Must be decoupled to GND.
2	$V_{OUTA}$	Analog Output	Channel A analog output voltage.
3	$V_{OUTB}$	Analog Output	Channel B analog output voltage.
4	NC	—	Not connected
5	NC	—	Not connected
6	GND	Ground	Ground reference for all on-chip circuitry.
7	$V_{REFIN}$	Analog Input	Unbuffered reference voltage shared by all channels. Must be decoupled to GND.
8	$D_{IN}$	Digital Input	Serial data input. Data is clocked into the 16-bit shift register on the falling edges of SCLK after the fall of SYNC.
9	$\overline{SYNC}$	Digital Input	Frame synchronization input for the data input. When this pin goes low, it enables the input shift register and data is transferred on the falling edges of SCLK. The DAC is updated on the 16th clock cycle unless SYNC is brought high before the 16th clock, in which case the rising edge of SYNC acts as an interrupt and the write sequence is ignored by the DAC.
10	SCLK	Digital Input	Serial clock input. Data is clocked into the input shift register on the falling edges of this pin.
PAD	PAD	Ground	Exposed die attach pad can be connected to ground or left floating. Soldering the pad to the PCB offers optimal thermal performance and enhances package self-alignment during reflow.

## 7 Specifications

### 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)(2)(3)</sup>

	MIN	MAX	UNIT
Supply voltage, $V_A$		6.5	V
Voltage on any input pin	–0.3	6.5	V
Input current at any pin <sup>(4)</sup>		10	mA
Package input current <sup>(4)</sup>		20	mA
Power consumption at $T_A = 25^\circ\text{C}$	See <sup>(5)</sup>		
Junction temperature, $T_J$		150	$^\circ\text{C}$
Storage temperature, $T_{\text{stg}}$	–65	150	$^\circ\text{C}$

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltages are measured with respect to GND = 0 V, unless otherwise specified.
- (3) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.
- (4) When the input voltage at any pin exceeds 5.5 V or is less than GND, the current at that pin must be limited to 10 mA. The 20-mA maximum package input current rating limits the number of pins that can safely exceed the power supplies with an input current of 10 mA to two.
- (5) The absolute maximum junction temperature ( $T_{J\text{max}}$ ) for this device is  $150^\circ\text{C}$ . The maximum allowable power dissipation is dictated by  $T_{J\text{max}}$ , the junction-to-ambient thermal resistance ( $R_{\theta JA}$ ), and the ambient temperature ( $T_A$ ), and can be calculated using the formula  $P_{D\text{MAX}} = (T_{J\text{max}} - T_A) / R_{\theta JA}$ . The values for maximum power dissipation is reached only when the device is operated in a severe fault condition (for example, when input or output pins are driven beyond the operating ratings, or the power supply polarity is reversed).

### 7.2 ESD Ratings

	VALUE	UNIT
$V_{\text{(ESD)}}$ Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)(2)</sup>	$\pm 2500$
	Machine model (MM)	$\pm 250$

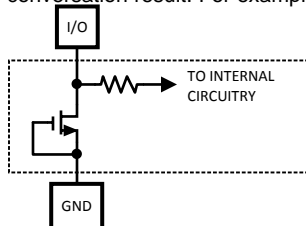
- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) Human-body model is 100-pF capacitor discharged through a 1.5-k $\Omega$  resistor. Machine model is 220 pF discharged through 0  $\Omega$ .

### 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

	MIN	MAX	UNIT
Operating temperature, $T_A$	–40	105	$^\circ\text{C}$
Supply voltage, $V_A$	2.7	5.5	V
Reference voltage, $V_{\text{REFIN}}$	1	$V_A$	V
Digital input voltage <sup>(2)</sup>	0	5.5	V
Output load	0	1500	pF
SCLK frequency		Up to 40	MHz

- (1) All voltage are measured with respect to GND = 0 V, unless otherwise specified.
- (2) The inputs are protected as shown below. Input voltage magnitudes up to 5.5 V, regardless of  $V_A$ , does not cause errors in the conversation result. For example, if  $V_A$  is 3 V, the digital input pins can be driven with a 5-V logic device.



## DAC082S085

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### 7.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		DAC082S085		UNIT
		DGS (VSSOP)	DSC (WSON)	
		10 PINS	10 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	240	250	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	53.3	40.7	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	78.9	23.7	°C/W
ψ <sub>JT</sub>	Junction-to-top characterization parameter	4.8	0.4	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	77.6	23.8	°C/W
R <sub>θJC(bottom)</sub>	Junction-to-case (bottom) thermal resistance	N/A	4.7	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

### 7.5 Electrical Characteristics

The following specifications apply for V<sub>A</sub> = 2.7 V to 5.5 V, V<sub>REFIN</sub> = V<sub>A</sub>, C<sub>L</sub> = 200 pF to GND, f<sub>SCLK</sub> = 30 MHz, input code range 3 to 252. All limits are at T<sub>A</sub> = 25°C, unless otherwise specified.<sup>(1)</sup>

PARAMETER		TEST CONDITIONS			MIN	TYP <sup>(2)</sup>	MAX	UNIT	
STATIC PERFORMANCE									
Resolution		T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>			8			Bits	
Monotonicity		T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>			8			Bits	
INL	Integral non-linearity	T <sub>A</sub> = 25°C				±0.14		LSB	
		T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>				±0.5			
DNL	Differential non-linearity	V <sub>A</sub> = 2.7 V to 5.5 V	T <sub>A</sub> = 25°C	Max		0.04		LSB	
				Min		-0.02			
			T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>				-0.13		0.18
ZE	Zero code error	I <sub>OUT</sub> = 0	T <sub>A</sub> = 25°C			4		mV	
			T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>			15			
FSE	Full-scale error	I <sub>OUT</sub> = 0	T <sub>A</sub> = 25°C			-0.1		%FSR	
			T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>			-0.75			
GE	Gain error	All ones Loaded to DAC register	T <sub>A</sub> = 25°C			-0.2		%FSR	
			T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>			-1			
ZCED	Zero code error drift					-20		μV/°C	
TC GE	Gain error tempco	V <sub>A</sub> = 3 V					-0.7		ppm/°C
		V <sub>A</sub> = 5 V					-1		
OUTPUT CHARACTERISTICS									
Output voltage <sup>(3)</sup>		T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>			0		V <sub>REFIN</sub>	V	
I <sub>OZ</sub>	High-impedance output leakage current <sup>(3)</sup>	T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>					±1	μA	
ZCO	Zero code output	V <sub>A</sub> = 3 V, I <sub>OUT</sub> = 200 μA				1.3		mV	
		V <sub>A</sub> = 3 V, I <sub>OUT</sub> = 1 mA				6			
		V <sub>A</sub> = 5 V, I <sub>OUT</sub> = 200 μA				7			
		V <sub>A</sub> = 5 V, I <sub>OUT</sub> = 1 mA				10			
FSO	Full-scale output	V <sub>A</sub> = 3 V, I <sub>OUT</sub> = 200 μA				2.984		V	
		V <sub>A</sub> = 3 V, I <sub>OUT</sub> = 1 mA				2.934			
		V <sub>A</sub> = 5 V, I <sub>OUT</sub> = 200 μA				4.989			
		V <sub>A</sub> = 5 V, I <sub>OUT</sub> = 1 mA				4.958			
I <sub>OS</sub>	Output short-circuit current (source)	V <sub>A</sub> = 3 V, V <sub>OUT</sub> = 0 V, Input Code = FFh				-56		mA	
		V <sub>A</sub> = 5 V, V <sub>OUT</sub> = 0 V, Input Code = FFh				-69			
	Output short-circuit current (sink)	V <sub>A</sub> = 3 V, V <sub>OUT</sub> = 3 V, Input Code = 00h				52		mA	
		V <sub>A</sub> = 5 V, V <sub>OUT</sub> = 5 V, Input Code = 00h				75			
I <sub>O</sub>	Continuous output current <sup>(3)</sup>	Available on each DAC output		T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>			11	mA	
C <sub>L</sub>	Maximum load capacitance	R <sub>L</sub> = ∞				1500		pF	
		R <sub>L</sub> = 2 kΩ				1500			

(1) To ensure accuracy, it is required that V<sub>A</sub> and V<sub>REFIN</sub> be well bypassed.

(2) Typical figures are at T<sub>J</sub> = 25°C, and represent most likely parametric norms. Test limits are specified to AOQL (Average Outgoing Quality Level).

(3) This parameter is specified by design or characterization and is not tested in production.

## Electrical Characteristics (continued)

The following specifications apply for  $V_A = 2.7\text{ V}$  to  $5.5\text{ V}$ ,  $V_{REFIN} = V_A$ ,  $C_L = 200\text{ pF}$  to GND,  $f_{SCLK} = 30\text{ MHz}$ , input code range 3 to 252. All limits are at  $T_A = 25^\circ\text{C}$ , unless otherwise specified.<sup>(1)</sup>

PARAMETER		TEST CONDITIONS		MIN	TYP <sup>(2)</sup>	MAX	UNIT
$Z_{OUT}$	DC output impedance				7.5		$\Omega$
<b>REFERENCE INPUT CHARACTERISTICS</b>							
$V_{REFIN}$	Input range minimum	$T_A = 25^\circ\text{C}$			0.2		V
		$T_{MIN} \leq T_A \leq T_{MAX}$		1			
	Input range maximum	$T_{MIN} \leq T_A \leq T_{MAX}$				$V_A$	
	Input impedance				60		k $\Omega$
<b>LOGIC INPUT CHARACTERISTICS</b>							
$I_{IN}$	Input current <sup>(3)</sup>	$T_{MIN} \leq T_A \leq T_{MAX}$				$\pm 1$	$\mu\text{A}$
$V_{IL}$	Input low voltage <sup>(3)</sup>	$V_A = 3\text{ V}$	$T_A = 25^\circ\text{C}$		0.9		V
			$T_{MIN} \leq T_A \leq T_{MAX}$			0.6	
		$V_A = 5\text{ V}$	$T_A = 25^\circ\text{C}$		1.5		
			$T_{MIN} \leq T_A \leq T_{MAX}$			0.8	
$V_{IH}$	Input high voltage <sup>(3)</sup>	$V_A = 3\text{ V}$	$T_A = 25^\circ\text{C}$		1.4		V
			$T_{MIN} \leq T_A \leq T_{MAX}$	2.1			
		$V_A = 5\text{ V}$	$T_A = 25^\circ\text{C}$		2.1		
			$T_{MIN} \leq T_A \leq T_{MAX}$	2.4			
$C_{IN}$	Input capacitance <sup>(3)</sup>	$T_{MIN} \leq T_A \leq T_{MAX}$				3	pF
<b>POWER REQUIREMENTS</b>							
$V_A$	Supply voltage minimum	$T_{MIN} \leq T_A \leq T_{MAX}$		2.7			V
	Supply voltage maximum	$T_{MIN} \leq T_A \leq T_{MAX}$				5.5	
$I_N$	Normal supply current (output unloaded)	$f_{SCLK} = 30\text{ MHz}$	$V_A = 2.7\text{ V to }3.6\text{ V}$	$T_A = 25^\circ\text{C}$		210	$\mu\text{A}$
				$T_{MIN} \leq T_A \leq T_{MAX}$		270	
			$V_A = 4.5\text{ V to }5.5\text{ V}$	$T_A = 25^\circ\text{C}$		320	
				$T_{MIN} \leq T_A \leq T_{MAX}$		410	
		$f_{SCLK} = 0$	$V_A = 2.7\text{ V to }3.6\text{ V}$			190	
						290	
$I_{PD}$	Power down supply current (output unloaded, SYNC = DIN = 0 V after PD mode loaded)	All PD Modes <sup>(3)</sup>	$V_A = 2.7\text{ V to }3.6\text{ V}$	$T_A = 25^\circ\text{C}$		0.1	$\mu\text{A}$
				$T_{MIN} \leq T_A \leq T_{MAX}$		1	
			$V_A = 4.5\text{ V to }5.5\text{ V}$	$T_A = 25^\circ\text{C}$		0.15	$\mu\text{A}$
				$T_{MIN} \leq T_A \leq T_{MAX}$		1	
$P_N$	Normal supply power (output unloaded)	$f_{SCLK} = 30\text{ MHz}$	$V_A = 2.7\text{ V to }3.6\text{ V}$	$T_A = 25^\circ\text{C}$		0.6	mW
				$T_{MIN} \leq T_A \leq T_{MAX}$		1	
			$V_A = 4.5\text{ V to }5.5\text{ V}$	$T_A = 25^\circ\text{C}$		1.6	
				$T_{MIN} \leq T_A \leq T_{MAX}$		2.3	
		$f_{SCLK} = 0$	$V_A = 2.7\text{ V to }3.6\text{ V}$			0.6	
						1.5	
$P_{PD}$	Power down supply current (output unloaded, SYNC = DIN = 0 V after PD mode loaded)	All PD Modes <sup>(3)</sup>	$V_A = 2.7\text{ V to }3.6\text{ V}$	$T_A = 25^\circ\text{C}$		0.3	$\mu\text{W}$
				$T_{MIN} \leq T_A \leq T_{MAX}$		3.6	
			$V_A = 4.5\text{ V to }5.5\text{ V}$	$T_A = 25^\circ\text{C}$		0.8	
				$T_{MIN} \leq T_A \leq T_{MAX}$		5.5	

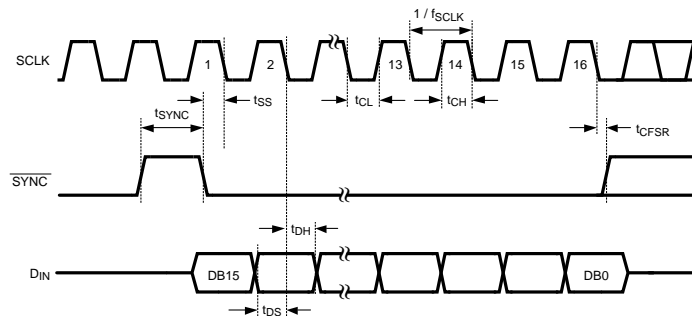
## 7.6 Timing Requirements

The following specifications apply for  $V_A = +2.7V$  to  $+5.5V$ ,  $V_{REFIN} = V_A$ ,  $C_L = 200$  pF to GND,  $f_{SCLK} = 30$  MHz, input code range 3 to 252. All other limits are at  $T_A = 25^\circ C$ , unless otherwise specified. <sup>(1)</sup>

			MIN	TYP	MAX	UNIT
$f_{SCLK}$	SCLK frequency	$T_A = 25^\circ C$		40		MHz
		$T_{MIN} \leq T_A \leq T_{MAX}$			30	
$t_s$	Output voltage settling time <sup>(2)</sup>	40h to C0h code change $R_L = 2$ k $\Omega$ , $C_L = 200$ pF	$T_A = 25^\circ C$ $T_{MIN} \leq T_A \leq T_{MAX}$	3		$\mu s$
					4.5	
SR	Output slew rate			1		V/ $\mu s$
	Glitch Impulse	Code change from 80h to 7Fh		12		nV-sec
	Digital feedthrough			0.5		nV-sec
	Digital crosstalk			1		nV-sec
	DAC-to-DAC crosstalk			3		nV-sec
	Multiplying bandwidth	$V_{REFIN} = 2.5$ V $\pm$ 0.1 Vpp		160		kHz
	Total harmonic distortion	$V_{REFIN} = 2.5$ V $\pm$ 1 Vpp input frequency = 10 kHz		70		dB
$t_{WU}$	Wake-up time	$V_A = 3$ V		6		$\mu s$
		$V_A = 5$ V		39		
$1/f_{SCLK}$	SCLK cycle time	$T_A = 25^\circ C$		25		ns
		$T_{MIN} \leq T_A \leq T_{MAX}$	33			
$t_{CH}$	SCLK high time	$T_A = 25^\circ C$		7		ns
		$T_{MIN} \leq T_A \leq T_{MAX}$	10			
$t_{CL}$	SCLK low time	$T_A = 25^\circ C$		7		ns
		$T_{MIN} \leq T_A \leq T_{MAX}$	10			
$t_{SS}$	$\overline{SYNC}$ setup time prior to SCLK falling edge	$T_A = 25^\circ C$		4		ns
		$T_{MIN} \leq T_A \leq T_{MAX}$	10			
$t_{DS}$	Data setup time prior to SCLK falling edge	$T_A = 25^\circ C$		1.5		ns
		$T_{MIN} \leq T_A \leq T_{MAX}$	3.5			
$t_{DH}$	Data hold time after SCLK falling edge	$T_A = 25^\circ C$		1.5		ns
		$T_{MIN} \leq T_A \leq T_{MAX}$	3.5			
$t_{CFSR}$	$\overline{SCLK}$ fall prior to rise of $\overline{SYNC}$	$T_A = 25^\circ C$		0		ns
		$T_{MIN} \leq T_A \leq T_{MAX}$	3			
$t_{SYNC}$	$\overline{SYNC}$ high time	$T_A = 25^\circ C$		6		ns
		$T_{MIN} \leq T_A \leq T_{MAX}$	10			

(1) Typical figures are at  $T_J = 25^\circ C$ , and represent most likely parametric norms. Test limits are specified to AOQL (Average Outgoing Quality Level).

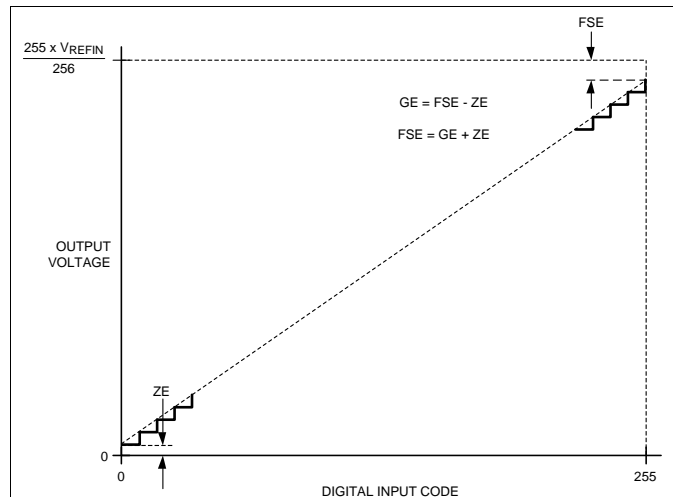
(2) This parameter is specified by design or characterization and is not tested in production.



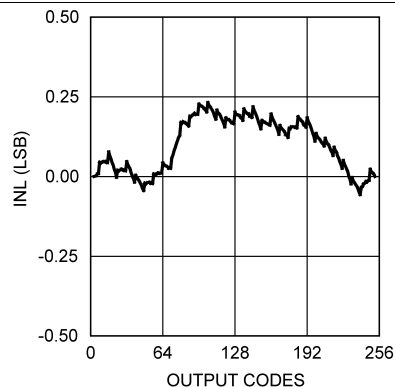
**Figure 1. Serial Timing Diagram**

## 7.7 Typical Characteristics

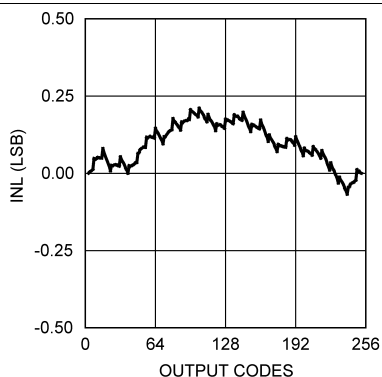
$V_{REF} = V_A$ ,  $f_{SCLK} = 30$  MHz,  $T_A = 25^\circ\text{C}$ , Input Code Range 3 to 252, unless otherwise stated



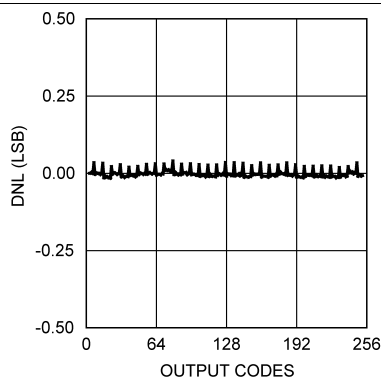
**Figure 2. Input and Output Transfer Characteristic**



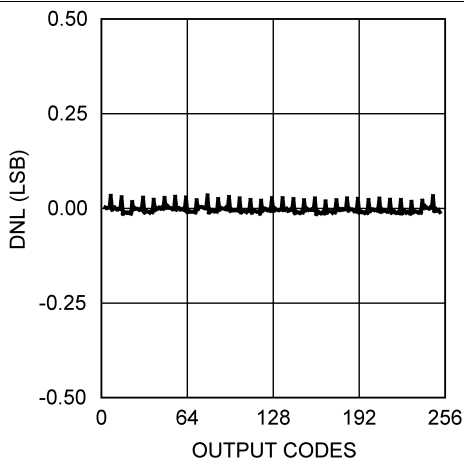
**Figure 3. INL at  $V_A = 3$  V**



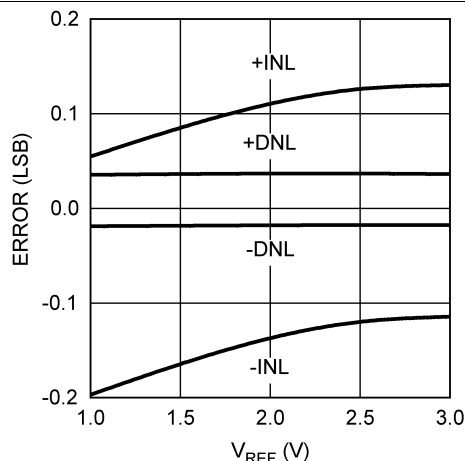
**Figure 4. INL at  $V_A = 5$  V**



**Figure 5. DNL at  $V_A = 3$  V**



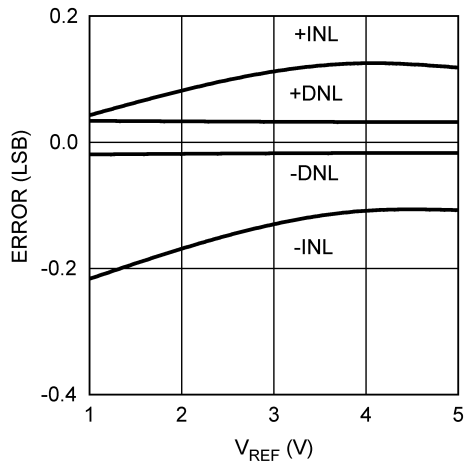
**Figure 6. DNL at  $V_A = 5$  V**



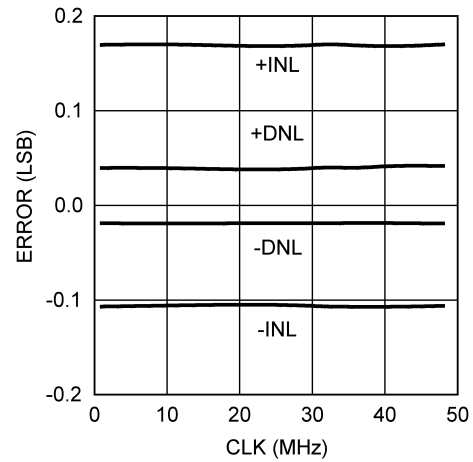
**Figure 7. INL/DNL vs  $V_{REFIN}$  at  $V_A = 3$  V**

## Typical Characteristics (continued)

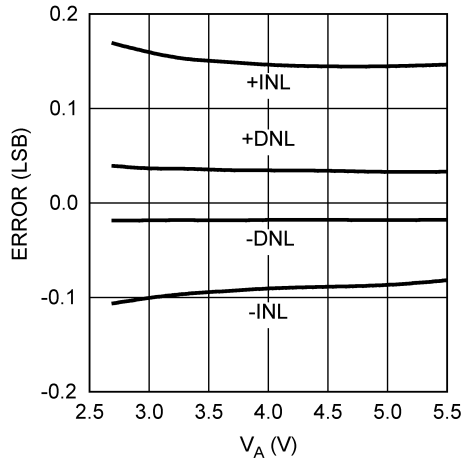
$V_{REF} = V_A$ ,  $f_{SCLK} = 30$  MHz,  $T_A = 25^\circ\text{C}$ , Input Code Range 3 to 252, unless otherwise stated



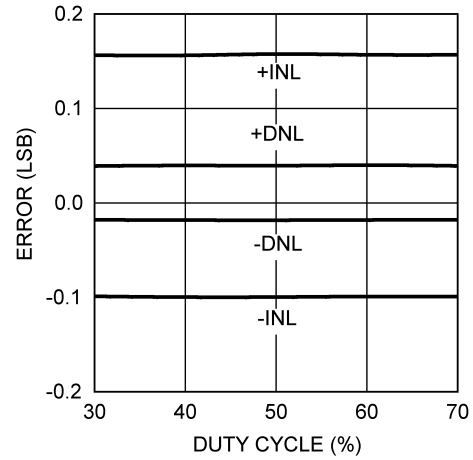
**Figure 8. INL/DNL vs  $V_{REF}$  at  $V_A = 5$  V**



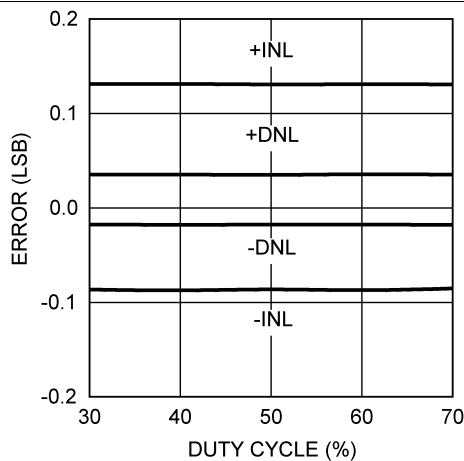
**Figure 9. INL/DNL vs  $f_{SCLK}$  at  $V_A = 2.7$  V**



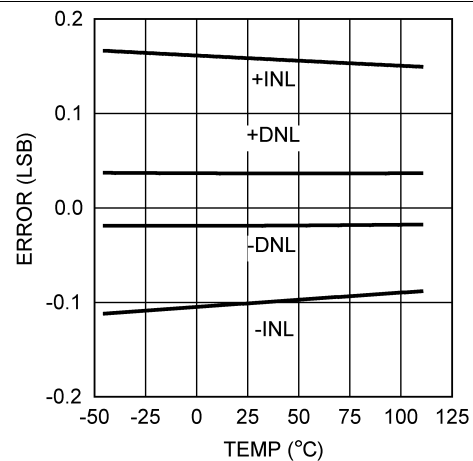
**Figure 10. INL/DNL vs  $V_A$**



**Figure 11. INL/DNL vs Clock Duty Cycle at  $V_A = 3$  V**



**Figure 12. INL/DNL vs Clock Duty Cycle at  $V_A = 5$  V**



**Figure 13. INL/DNL vs Temperature at  $V_A = 3$  V**

## Typical Characteristics (continued)

$V_{REF} = V_A$ ,  $f_{SCLK} = 30$  MHz,  $T_A = 25^\circ\text{C}$ , Input Code Range 3 to 252, unless otherwise stated

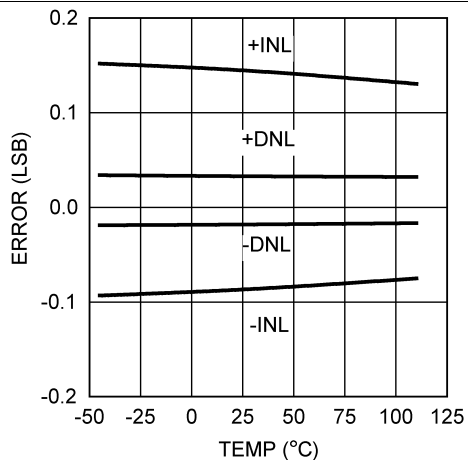


Figure 14. INL/DNL vs Temperature at  $V_A = 5$  V

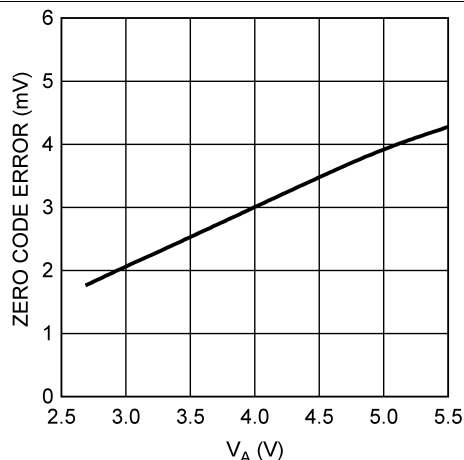


Figure 15. Zero Code Error vs  $V_A$

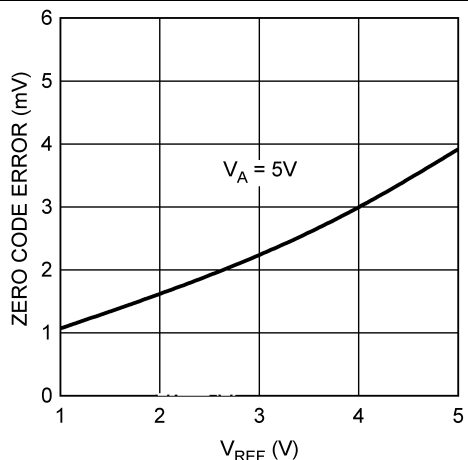


Figure 16. Zero Code Error vs  $V_{REFIN}$

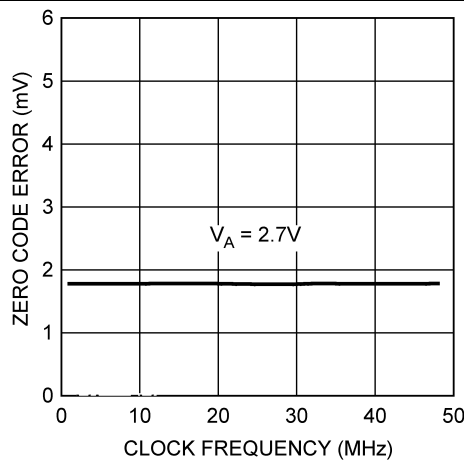


Figure 17. Zero Code Error vs  $f_{SCLK}$

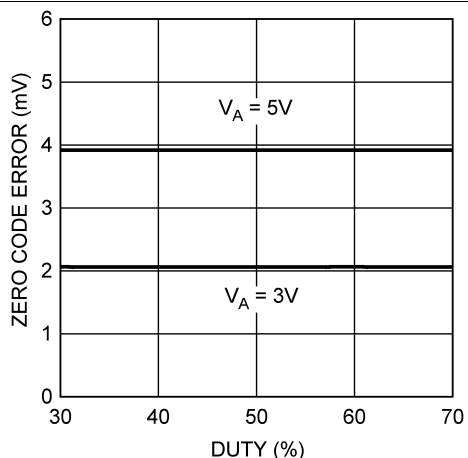


Figure 18. Zero Code Error vs Clock Duty Cycle

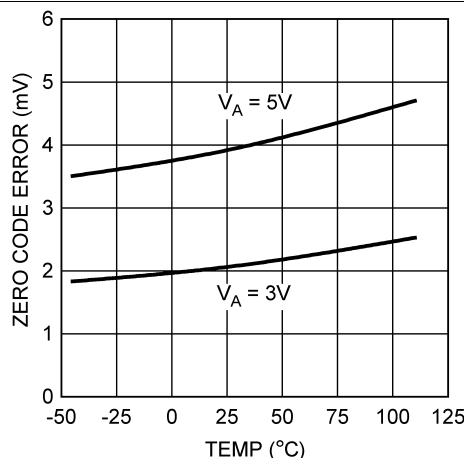


Figure 19. Zero Code Error vs Temperature

## Typical Characteristics (continued)

$V_{REF} = V_A$ ,  $f_{SCLK} = 30$  MHz,  $T_A = 25^\circ\text{C}$ , Input Code Range 3 to 252, unless otherwise stated

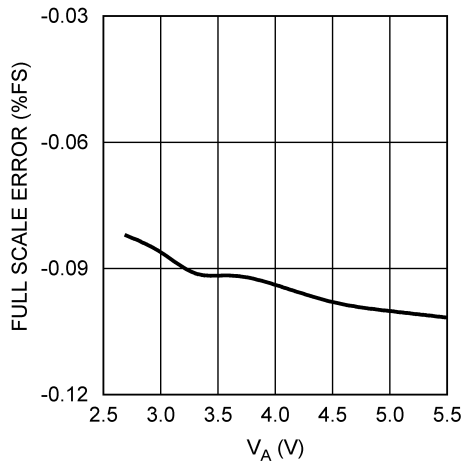


Figure 20. Full-Scale Error vs  $V_A$

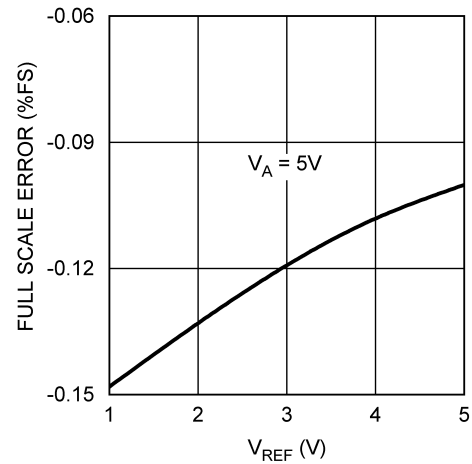


Figure 21. Full-Scale Error vs  $V_{REFIN}$

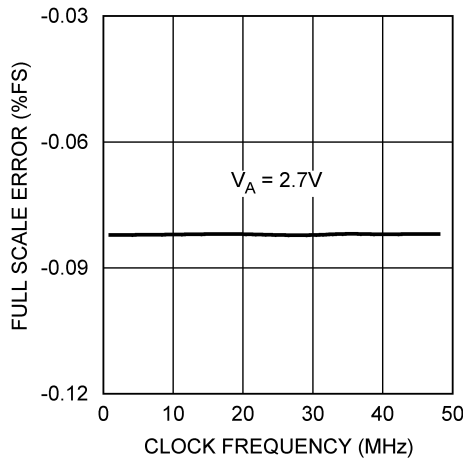


Figure 22. Full-Scale Error vs  $f_{SCLK}$

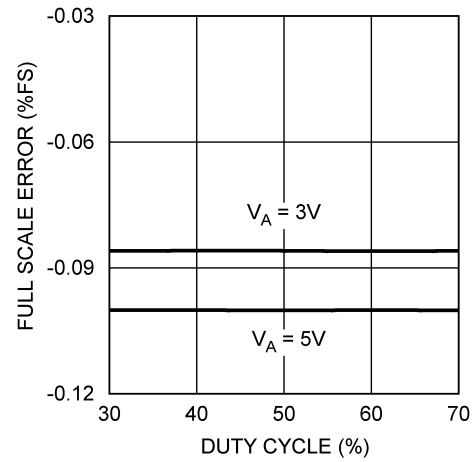


Figure 23. Full-Scale Error vs Clock Duty Cycle

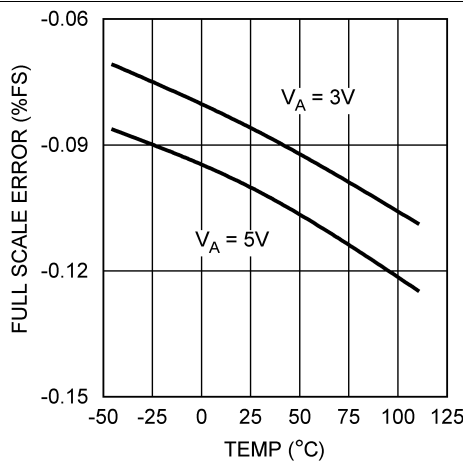


Figure 24. Full-Scale Error vs Temperature

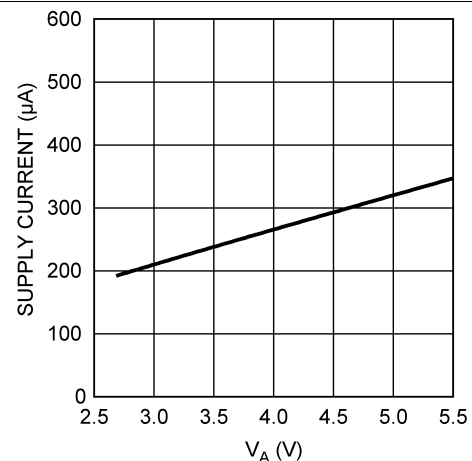
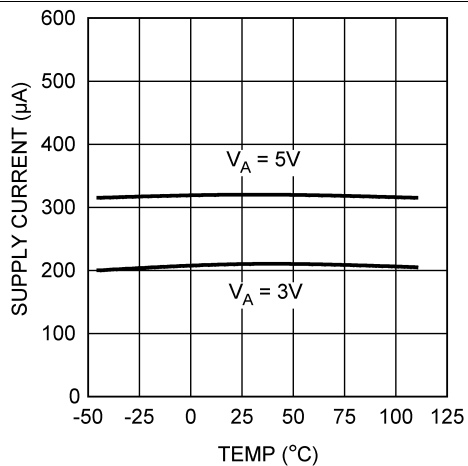


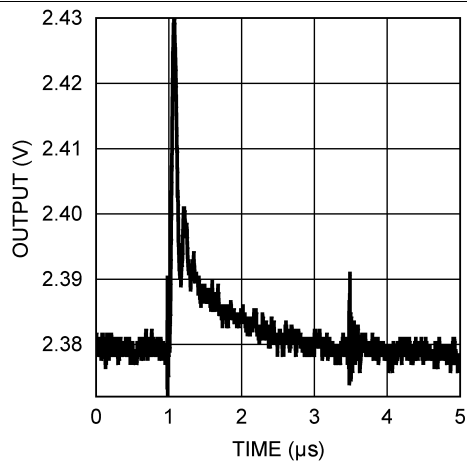
Figure 25. Supply Current vs  $V_A$

## Typical Characteristics (continued)

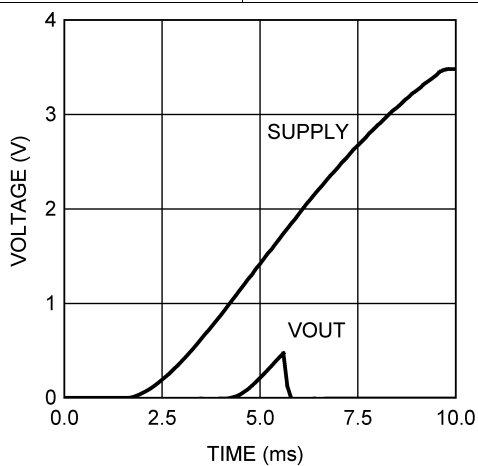
$V_{REF} = V_A$ ,  $f_{SCLK} = 30$  MHz,  $T_A = 25^\circ\text{C}$ , Input Code Range 3 to 252, unless otherwise stated



**Figure 26. Supply Current vs Temperature**



**Figure 27. 5-V Glitch Response**



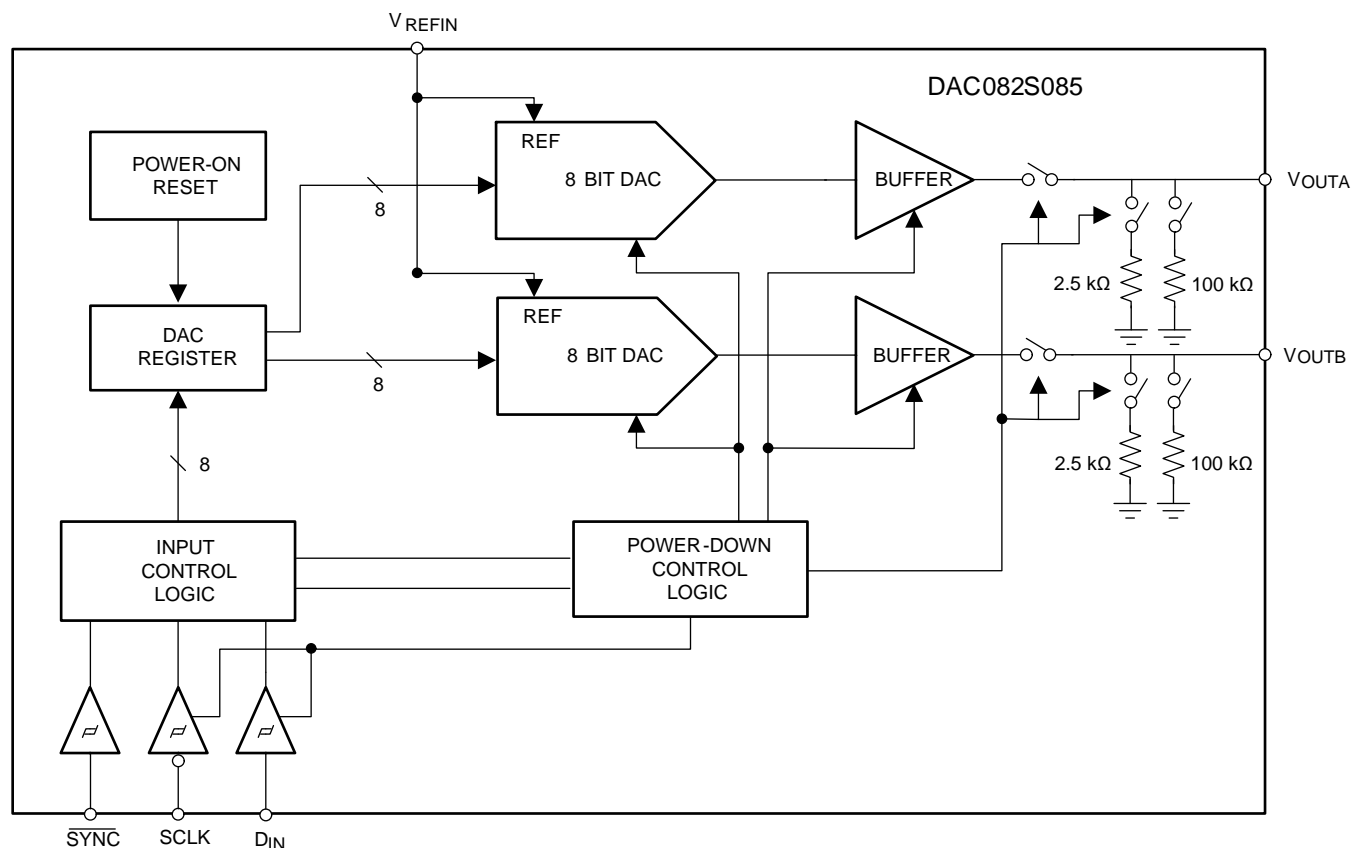
**Figure 28. Power-On Reset**

## 8 Detailed Description

### 8.1 Overview

The DAC082S085 is fabricated on a CMOS process with an architecture that consists of switches and resistor strings that are followed by an output buffer.

### 8.2 Functional Block Diagram



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#### 8.2.1 Feature Description

##### 8.2.1.1 DAC Architecture

The DAC082S085 is fabricated on a CMOS process with an architecture that consists of switches and resistor strings that are followed by an output buffer. The reference voltage is externally applied at  $V_{REFIN}$  and is shared by both DACs.

For simplicity, a single resistor string is shown in Figure 29. This string consists of 256 equal valued resistors with a switch at each junction of two resistors, plus a switch to ground. The code loaded into the DAC register determines which switch is closed, connecting the proper node to the amplifier. The input coding is straight binary with an ideal output voltage calculated in Equation 1:

$$V_{OUTA,B} = V_{REFIN} \times (D / 256)$$

where

- D is the decimal equivalent of the binary code that is loaded into the DAC register. (D can take on any value between 0 and 255. This configuration ensures that the DAC is monotonic.) (1)

## Functional Block Diagram (continued)

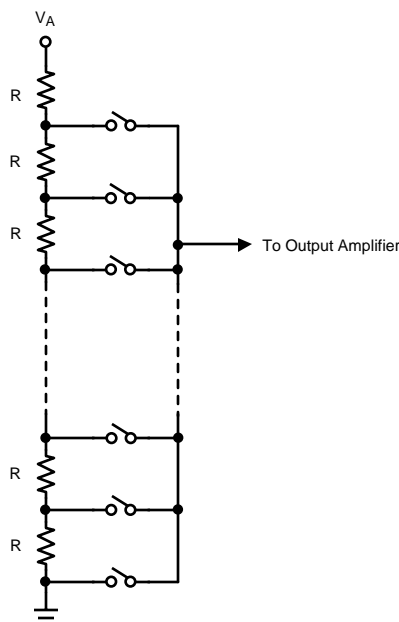


Figure 29. DAC Resistor String

### 8.2.1.2 Output Amplifiers

The output amplifiers are rail-to-rail, providing an output voltage range of 0 V to  $V_A$  when the reference is  $V_A$ . All amplifiers, even rail-to-rail types, exhibit a loss of linearity as the output approaches the supply rails (0 V and  $V_A$ , in this case). For this reason, linearity is specified over less than the full output range of the DAC. However, if the reference is less than  $V_A$ , there is only a loss in linearity in the lowest codes. The output capabilities of the amplifier are described in [Electrical Characteristics](#).

The output amplifiers are capable of driving a load of 2 k $\Omega$  in parallel with 1500 pF to ground or to  $V_A$ . The zero-code and full-scale outputs for given load currents are available in the [Electrical Characteristics](#).

### 8.2.1.3 Reference Voltage

The DAC082S085 uses a single external reference that is shared by both channels. The reference pin,  $V_{REFIN}$ , is not buffered and has an input impedance of 60 k $\Omega$ . TI recommends that  $V_{REFIN}$  be driven by a voltage source with low output impedance. The reference voltage range is 1 V to  $V_A$ , providing the widest possible output dynamic range.

### 8.2.1.4 Power-On Reset

The power-on reset circuit controls the output voltages of both DACs during power-up. Upon application of power, the DAC registers are filled with zeros and the output voltages are 0 V. The outputs remain at 0 V until a valid write sequence is made to the DAC.

## 8.3 Device Functional Modes

### 8.3.1 Power-Down Modes

The DAC082S085 has four power-down modes, two of which are identical. In power-down mode, the supply current drops to 20  $\mu$ A at 3 V and 30  $\mu$ A at 5 V. The DAC082S085 is set in power-down mode by setting OP1 and OP0 to 11. Because this mode powers down both DACs, the first two bits of the shift register are used to select different output terminations for the DAC outputs. Setting A1 and A0 to 00 or 11 causes the outputs to be tri-stated (a high impedance state). While setting A1 and A0 to 01 or 10 causes the outputs to be terminated by 2.5 k $\Omega$  or 100 k $\Omega$  to ground respectively (see [Table 1](#)).

## Device Functional Modes (continued)

**Table 1. Power-Down Modes**

A1	A0	OP1	OP0	OPERATING MODE
0	0	1	1	High-Z outputs
0	1	1	1	2.5 kΩ to GND
1	0	1	1	100 kΩ to GND
1	1	1	1	High-Z outputs

The bias generator, output amplifiers, resistor strings, and other linear circuitry are all shut down in any of the power-down modes. However, the contents of the DAC registers are unaffected when in power-down. Each DAC register maintains its value prior to the DAC082S085 being powered down unless it is changed during the write sequence which instructed it to recover from power down. Minimum power consumption is achieved in the power-down mode with  $\overline{\text{SYNC}}$  and  $\text{D}_{\text{IN}}$  idled low and SCLK disabled. The time to exit power-down (Wake-Up Time) is typically  $t_{\text{WU}}$   $\mu\text{s}$  as stated in [Timing Requirements](#).

## 8.4 Programming

### 8.4.1 Serial Interface

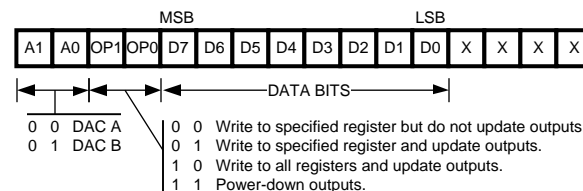
The three-wire interface is compatible with SPI™, QSPI, and MICROWIRE, as well as most DSPs and operates at clock rates up to 40 MHz. See [Figure 1](#) for information on a write sequence.

A write sequence begins by bringing the  $\overline{\text{SYNC}}$  line low. Once  $\overline{\text{SYNC}}$  is low, the data on the  $\text{D}_{\text{IN}}$  line is clocked into the 16-bit serial input register on the falling edges of SCLK. To avoid misclocking data into the shift register, it is critical that  $\overline{\text{SYNC}}$  not be brought low simultaneously with a falling edge of SCLK (see [Figure 1](#)). On the 16th falling clock edge, the last data bit is clocked in and the programmed function (a change in the DAC channel address, mode of operation or register contents) is executed. At this point the  $\overline{\text{SYNC}}$  line may be kept low or brought high. Any data and clock pulses after the 16th falling clock edge are ignored. In either case,  $\overline{\text{SYNC}}$  must be brought high for the minimum specified time before the next write sequence is initiated with a falling edge of  $\overline{\text{SYNC}}$ .

Because the  $\overline{\text{SYNC}}$  and  $\text{D}_{\text{IN}}$  buffers draw more current when they are high, they must be idled low between write sequences to minimize power consumption.

### 8.4.2 Input Shift Register

The input shift register, [Figure 30](#), has sixteen bits. The first bit must be set to 0 and the second bit is an address bit. The address bit determines whether the register data is for DAC A or DAC B. This bit is followed by two bits that determine the mode of operation (writing to a DAC register without updating the outputs of both DACs, writing to a DAC register and updating the outputs of both DACs, writing to the register of both DACs and updating their outputs, or powering down both outputs). The final twelve bits of the shift register are the data bits. The data format is straight binary (MSB first, LSB last), with all 0s corresponding to an output of 0 V and all 1s corresponding to a full-scale output of  $V_{\text{REFIN}} - 1$  LSB. The contents of the serial input register are transferred to the DAC register on the sixteenth falling edge of SCLK. See [Figure 1](#).


**Figure 30. Input Register Contents**

Normally, the  $\overline{\text{SYNC}}$  line is kept low for at least 16 falling edges of SCLK and the DAC is updated on the 16th SCLK falling edge. However, if  $\overline{\text{SYNC}}$  is brought high before the 16th falling edge, the data transfer to the shift register is aborted and the write sequence is invalid. Under this condition, the DAC register is not updated and there is no change in the mode of operation or in the DAC output voltages.

## Programming (continued)

### 8.4.3 DSP and Microprocessor Interfacing

Interfacing the DAC082S085 to microprocessors and DSPs is quite simple. The following guidelines are offered to hasten the design process.

#### 8.4.3.1 ADSP-2101/ADSP2103 Interfacing

Figure 31 shows a serial interface between the DAC082S085 and the ADSP-2101/ADSP2103. The DSP must be set to operate in the SPORT Transmit Alternate Framing Mode. It is programmed through the SPORT control register and must be configured for Internal Clock Operation, Active Low Framing and 16-bit Word Length. Transmission is started by writing a word to the TX register after the SPORT mode has been enabled.

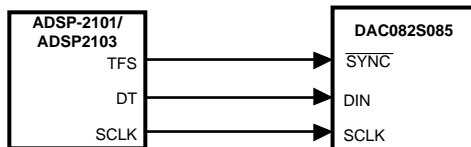


Figure 31. ADSP-2101/2103 Interface

#### 8.4.3.2 80C51/80L51 Interface

A serial interface between the DAC082S085 and the 80C51/80L51 microcontroller is shown in Figure 32. The SYNC signal comes from a bit-programmable pin on the microcontroller. The example shown here uses port line P3.3. This line is taken low when data is transmitted to the DAC082S085. Because the 80C51/80L51 transmits 8-bit bytes, only eight falling clock edges occur in the transmit cycle. To load data into the DAC, the P3.3 line must be left low after the first eight bits are transmitted. A second write cycle is initiated to transmit the second byte of data, after which port line P3.3 is brought high. The 80C51/80L51 transmit routine must recognize that the 80C51/80L51 transmits data with the LSB first while the DAC082S085 requires data with the MSB first.

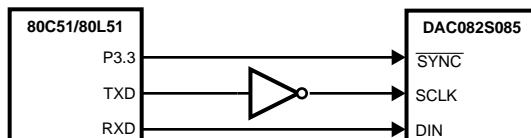


Figure 32. 80C51/80L51 Interface

#### 8.4.3.3 68HC11 Interface

A serial interface between the DAC082S085 and the 68HC11 microcontroller is shown in Figure 33. The SYNC line of the DAC082S085 is driven from a port line (PC7 in the figure), similar to the 80C51/80L51.

The 68HC11 must be configured with its CPOL bit as a zero and its CPHA bit as a one. This configuration causes data on the MOSI output to be valid on the falling edge of SCLK. PC7 is taken low to transmit data to the DAC. The 68HC11 transmits data in 8-bit bytes with eight falling clock edges. Data is transmitted with the MSB first. PC7 must remain low after the first eight bits are transferred. A second write cycle is initiated to transmit the second byte of data to the DAC, after which PC7 must be raised to end the write sequence.

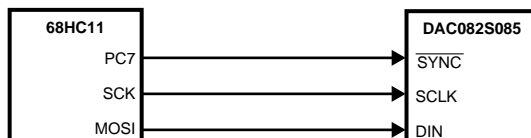
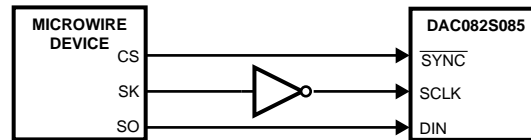


Figure 33. 68HC11 Interface

## Programming (continued)

### 8.4.3.4 Microwire Interface

Figure 34 shows an interface between a Microwire-compatible device and the DAC082S085. Data is clocked out on the rising edges of the SK signal. As a result, the SK of the Microwire device must be inverted before driving the SCLK of the DAC082S085.



**Figure 34. Microwire Interface**

## 9 Application and Implementation

### NOTE

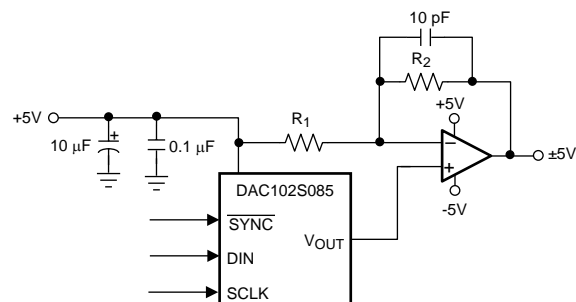
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 9.1 Application Information

The DAC082S085 is designed for single-supply operation and thus has a unipolar output. However, a bipolar output may be obtained with the circuit in Figure 35. This circuit provides an output voltage range of  $\pm 5$  V. A rail-to-rail amplifier must be used if the amplifier supplies are limited to  $\pm 5$  V.

### 9.2 Typical Application

#### 9.2.1 Bipolar Operation



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**Figure 35. Bipolar Operation**

#### 9.2.1.1 Design Requirements

- The DAC082S085 uses a single supply.
- The output is required to be bipolar with a voltage range of  $\pm 5$  V.
- Dual supplies are used for the output amplifier.

## Typical Application (continued)

### 9.2.1.2 Detailed Design Procedure

The output voltage of this circuit for any code is found to be

$$V_O = (V_A \times (D / 256) \times ((R1 + R2) / R1) - V_A \times R2 / R1) \quad (2)$$

$$V_O = (10 \times D / 256) - 5 \text{ V}$$

where

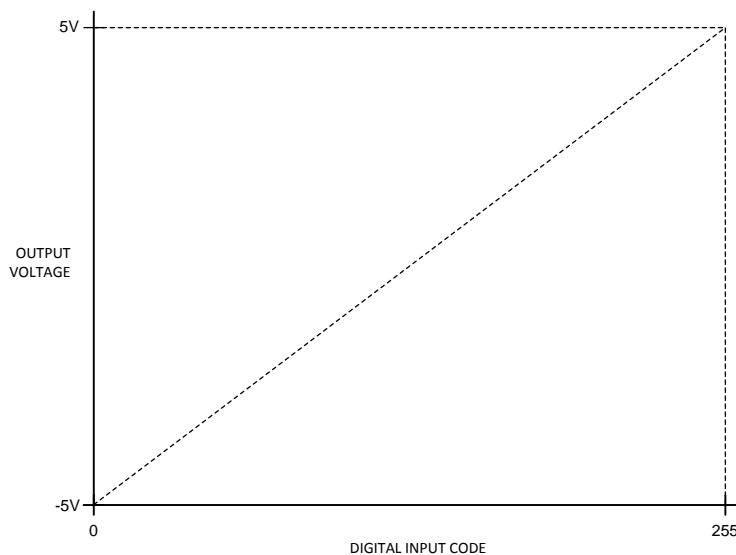
- D is the input code in decimal form (With  $V_A = 5 \text{ V}$  and  $R1 = R2$ ) (3)

Table 2 lists the rail-to-rail amplifiers suitable for this application.

**Table 2. Some Rail-to-Rail Amplifiers**

AMP	PKGS	TYP $V_{OS}$	TYP $I_{SUPPLY}$
LMC7111	8-pin PDIP, 5-pin SOT-23	0.9 mV	25 $\mu\text{A}$
LM7301	8-pin SO, 5-pin SOT-23	0.03 mV	620 $\mu\text{A}$
LM8261	5-pin SOT-23	0.7 mV	1 mA

### 9.2.1.3 Application Curve



**Figure 36. Bipolar Input / Output Transfer Characteristic**

## 10 Power Supply Recommendations

While the simplicity of the DAC082S085 implies ease of use, it is important to recognize that the path from the reference input ( $V_{REFIN}$ ) to the  $V_{OUT}$ s has essentially zero Power Supply Rejection Ratio (PSRR). Therefore, it is necessary to provide a noise-free supply voltage to  $V_{REFIN}$ . To use the full dynamic range of the DAC082S085, the supply pin ( $V_A$ ) and  $V_{REFIN}$  can be connected together and share the same supply voltage.

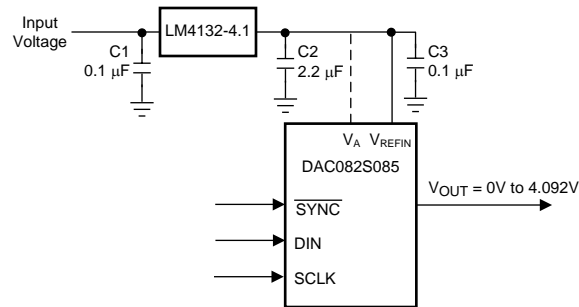
### 10.1 Using References as Power Supplies

Because the DAC082S085 consumes very little power, a reference source may be used as the reference input or the supply voltage. The advantages of using a reference source over a voltage regulator are accuracy and stability. Some low noise regulators can also be used. Listed below are a few reference and power supply options for the DAC082S085.

## Using References as Power Supplies (continued)

### 10.1.1 LM4130

The LM4130, with its 0.05% accuracy over temperature, is a good choice as a reference source for the DAC082S085. The 4.096-V version is useful if a 0 to 4.095-V output range is desirable or acceptable. Bypassing the LM4130 VIN pin with a 0.1-μF capacitor and the VOUT pin with a 2.2-μF capacitor improves stability and reduces output noise. The LM4130 comes in a space-saving, 5-pin SOT-23.

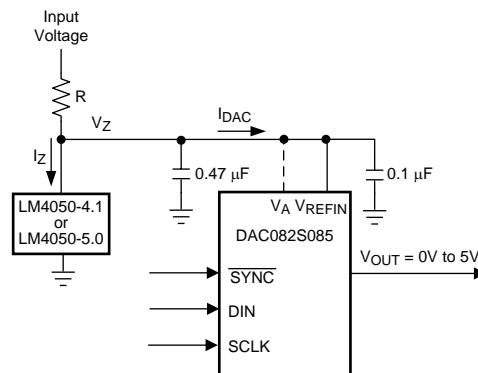


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**Figure 37. The LM4130 as a Power Supply**

### 10.1.2 LM4050

Available with accuracy of 0.44%, the LM4050 shunt reference is also a good choice as a reference for the DAC082S085. It is available in 4.096-V and 5-V versions and comes in a space-saving, 3-pin SOT-23.



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**Figure 38. The LM4050 as a Power Supply**

The minimum resistor value in the circuit of [Figure 38](#) must be chosen such that the maximum current through the LM4050 does not exceed its 15-mA rating. The conditions for maximum current include the input voltage at its maximum, the LM4050 voltage at its minimum, and the DAC082S085 drawing zero current. The maximum resistor value must allow the LM4050 to draw more than its minimum current for regulation plus the maximum DAC082S085 current in full operation. The conditions for minimum current include the input voltage at its minimum, the LM4050 voltage at its maximum, the resistor value at its maximum due to tolerance, and the DAC082S085 draws its maximum current. These conditions can be summarized in [Equation 4](#) and [Equation 5](#):

$$R(\min) = (V_{IN}(\max) - V_Z(\min)) / I_Z(\max) \quad (4)$$

$$R(\max) = (V_{IN}(\min) - V_Z(\max)) / (I_{DAC}(\max) + I_Z(\min))$$

where

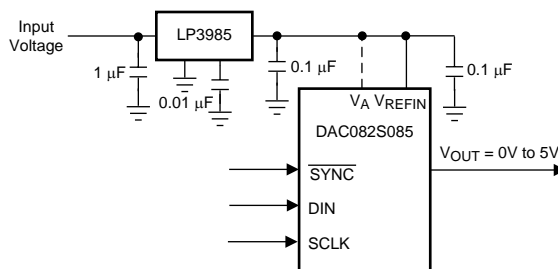
- $V_Z(\min)$  and  $V_Z(\max)$  are the nominal LM4050 output voltages  $\pm$  the LM4050 output tolerance over temperature

## Using References as Power Supplies (continued)

- $I_Z(\text{max})$  is the maximum allowable current through the LM4050
  - $I_Z(\text{min})$  is the minimum current required by the LM4050 for proper regulation
  - $I_{\text{DAC}}(\text{max})$  is the maximum DAC082S085 supply current
- (5)

### 10.1.3 LP3985

The LP3985 is a low-noise, ultra-low dropout voltage regulator with a 3% accuracy over temperature. It is a good choice for applications that do not require a precision reference for the DAC082S085. It comes in 3-V, 3.3-V, and 5-V versions, among others, and sports a low 30- $\mu\text{V}$  noise specification at low frequencies. Because low frequency noise is relatively difficult to filter, this specification could be important for some applications. The LP3985 comes in a space-saving, 5-pin SOT-23 and 5-bump DSBGA packages.



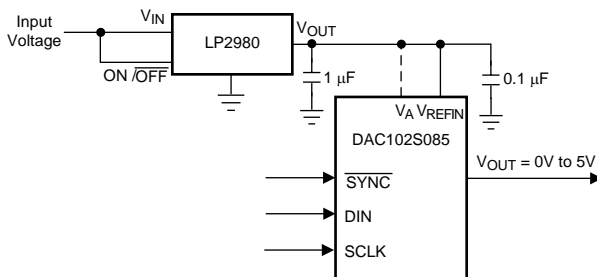
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Figure 39. Using the LP3985 Regulator

An input capacitance of 1  $\mu\text{F}$  without any ESR requirement is required at the LP3985 input, while a 1- $\mu\text{F}$  ceramic capacitor with an ESR requirement of 5 m $\Omega$  to 500 m $\Omega$  is required at the output. Careful interpretation and understanding of the capacitor specification is required to ensure correct device operation.

### 10.1.4 LP2980

The LP2980 is an ultra-low dropout regulator with a 0.5% or 1% accuracy over temperature, depending upon grade. It is available in 3-V, 3.3-V, and 5-V versions, among others.



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Figure 40. Using the LP2980 Regulator

Like any low dropout regulator, the LP2980 requires an output capacitor for loop stability. This output capacitor must be at least 1- $\mu\text{F}$  over temperature, but values of 2.2  $\mu\text{F}$  or more provide even better performance. The ESR of this capacitor must be within the range specified in the LP2980 data sheet. Surface-mount solid tantalum capacitors offer a good combination of small size and ESR. Ceramic capacitors are attractive due to their small size but generally have ESR values that are too low for use with the LP2980. Aluminum electrolytic capacitors are typically not a good choice due to their large size and have ESR values that may be too high at low temperatures.

## 11 Layout

### 11.1 Layout Guidelines

For best accuracy and minimum noise, the printed-circuit board containing the DAC082S085 must have separate analog and digital areas. The areas are defined by the locations of the analog and digital power planes. Both of these planes must be placed in the same board layer. There should be a single ground plane. A single ground plane is preferred if digital return current does not flow through the analog ground area. Frequently a single ground plane design uses a *fencing* technique to prevent the mixing of analog and digital ground current. Separate ground planes must only be used when the fencing technique is inadequate. The separate ground planes must be connected in one place, preferably near the DAC082S085. Take special care to ensure that digital signals with fast edge rates do not pass over split ground planes. They must always have a continuous return path below their traces.

The DAC082S085 power supply must be bypassed with a 10- $\mu$ F and a 0.1- $\mu$ F capacitor as close as possible to the device with the 0.1  $\mu$ F right at the device supply pin. The 10- $\mu$ F capacitor must be a tantalum type and the 0.1- $\mu$ F capacitor must be a low ESL, low ESR type. The power supply for the DAC082S085 must only be used for analog circuits.

Avoid crossover of analog and digital signals and keep the clock and data lines on the component side of the board. The clock and data lines must have controlled impedances.

### 11.2 Layout Example

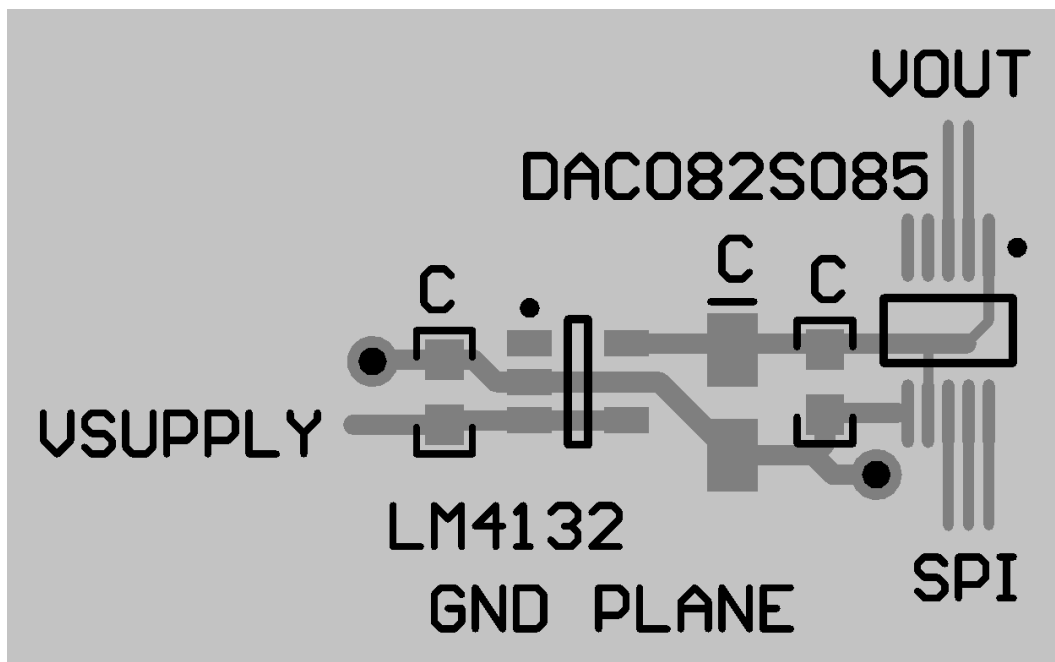


Figure 41. DAC082S085 Layout Example

## 12 Device and Documentation Support

### 12.1 Device Support

#### 12.1.1 Device Nomenclature

##### 12.1.1.1 Specification Definitions

**DIFFERENTIAL NON-LINEARITY (DNL)** is the measure of the maximum deviation from the ideal step size of 1 LSB, which is  $V_{REF} / 256 = V_A / 256$ .

**DAC-to-DAC CROSSTALK** is the glitch impulse transferred to a DAC output in response to a full-scale change in the output of another DAC.

**DIGITAL CROSSTALK** is the glitch impulse transferred to a DAC output at mid-scale in response to a full-scale change in the input register of another DAC.

**DIGITAL FEEDTHROUGH** is a measure of the energy injected into the analog output of the DAC from the digital inputs when the DAC outputs are not updated. It is measured with a full-scale code change on the data bus.

**FULL-SCALE ERROR** is the difference between the actual output voltage with a full scale code (FFFh) loaded into the DAC and the value of  $V_A \times 255 / 256$ .

**GAIN ERROR** is the deviation from the ideal slope of the transfer function. It can be calculated from Zero and Full-Scale Errors as  $GE = FSE - ZE$ , where GE is Gain error, FSE is Full-Scale Error and ZE is Zero Error.

**GLITCH IMPULSE** is the energy injected into the analog output when the input code to the DAC register changes. It is specified as the area of the glitch in nanovolt-seconds.

**INTEGRAL NON-LINEARITY (INL)** is a measure of the deviation of each individual code from a straight line through the input to output transfer function. The deviation of any given code from this straight line is measured from the center of that code value. The end point method is used. INL for this product is specified over a limited range, per the electrical tables.

**LEAST SIGNIFICANT BIT (LSB)** is the bit that has the smallest value or weight of all bits in a word. This value is

$$LSB = V_{REF} / 2^n$$

where

- $V_{REF}$  is the supply voltage for this product
- $n$  is the DAC resolution in bits, which is 8 for the DAC082S085

(6)

**MAXIMUM LOAD CAPACITANCE** is the maximum capacitance that can be driven by the DAC with output stability maintained.

**MONOTONICITY** is the condition of being monotonic, where the DAC has an output that never decreases when the input code increases.

**MOST SIGNIFICANT BIT (MSB)** is the bit that has the largest value or weight of all bits in a word. Its value is  $1/2$  of  $V_A$ .

**MULTIPLYING BANDWIDTH** is the frequency at which the output amplitude falls 3 dB below the input sine wave on  $V_{REFIN}$  with a full-scale code loaded into the DAC.

**POWER EFFICIENCY** is the ratio of the output current to the total supply current. The output current comes from the power supply. The difference between the supply and output currents is the power consumed by the device without a load.

**SETTLING TIME** is the time for the output to settle to within  $1/2$  LSB of the final value after the input code is updated.

**TOTAL HARMONIC DISTORTION (THD)** is the measure of the harmonics present at the output of the DACs with an ideal sine wave applied to  $V_{REFIN}$ . THD is measured in dB.

**WAKE-UP TIME** is the time for the output to exit power-down mode. This is the time from the falling edge of the 16th SCLK pulse to when the output voltage deviates from the power-down voltage of 0 V.

## Device Support (continued)

**ZERO CODE ERROR** is the output error, or voltage, present at the DAC output after a code of 000h has been entered.

### 12.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 12.3 Community Resource

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

**TI E2E™ Online Community** *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

### 12.4 Trademarks

E2E is a trademark of Texas Instruments.

SPI is a trademark of Motorola, Inc..

All other trademarks are the property of their respective owners.

### 12.5 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### 12.6 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
DAC082S085C1MM/NO.A	Active	Production	VSSOP (DGS)   10	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	X76C
<a href="#">DAC082S085C1MM/NOPB</a>	Active	Production	VSSOP (DGS)   10	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	X76C
DAC082S085C1MMX/NO.A	Active	Production	VSSOP (DGS)   10	3500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	X76C
<a href="#">DAC082S085C1MMX/NOPB</a>	Active	Production	VSSOP (DGS)   10	3500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	X76C
DAC082S085C1SD/NO.A	Active	Production	WSON (DSC)   10	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	X77C
<a href="#">DAC082S085C1SD/NOPB</a>	Active	Production	WSON (DSC)   10	1000   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	X77C
DAC082S085C1SDX/NO.A	Active	Production	WSON (DSC)   10	4500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	X77C
<a href="#">DAC082S085C1SDX/NOPB</a>	Active	Production	WSON (DSC)   10	4500   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 105	X77C

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

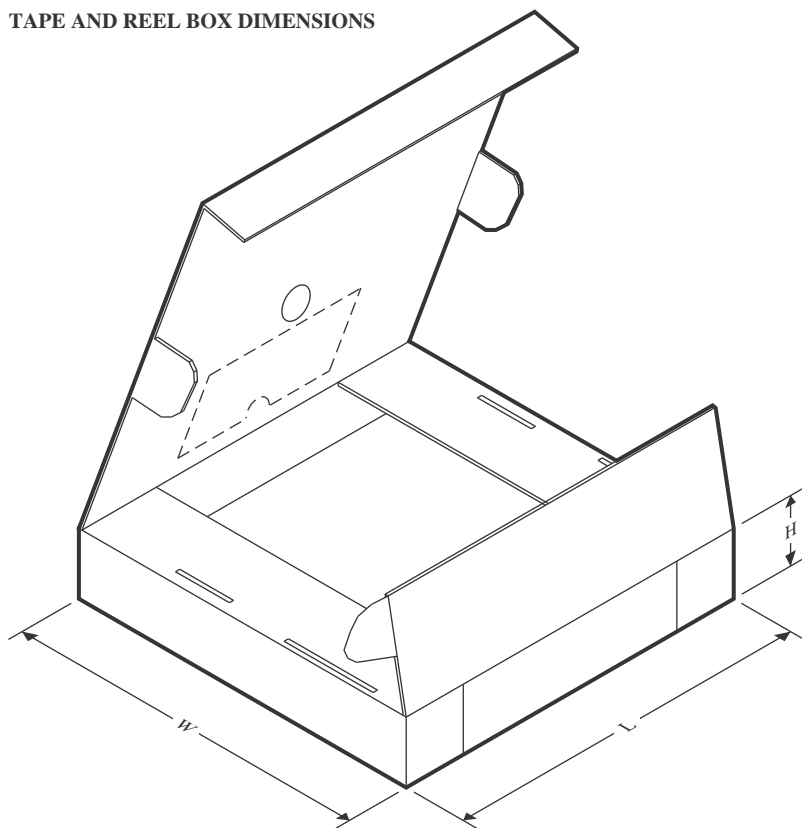
## TAPE AND REEL INFORMATION



\*All dimensions are nominal

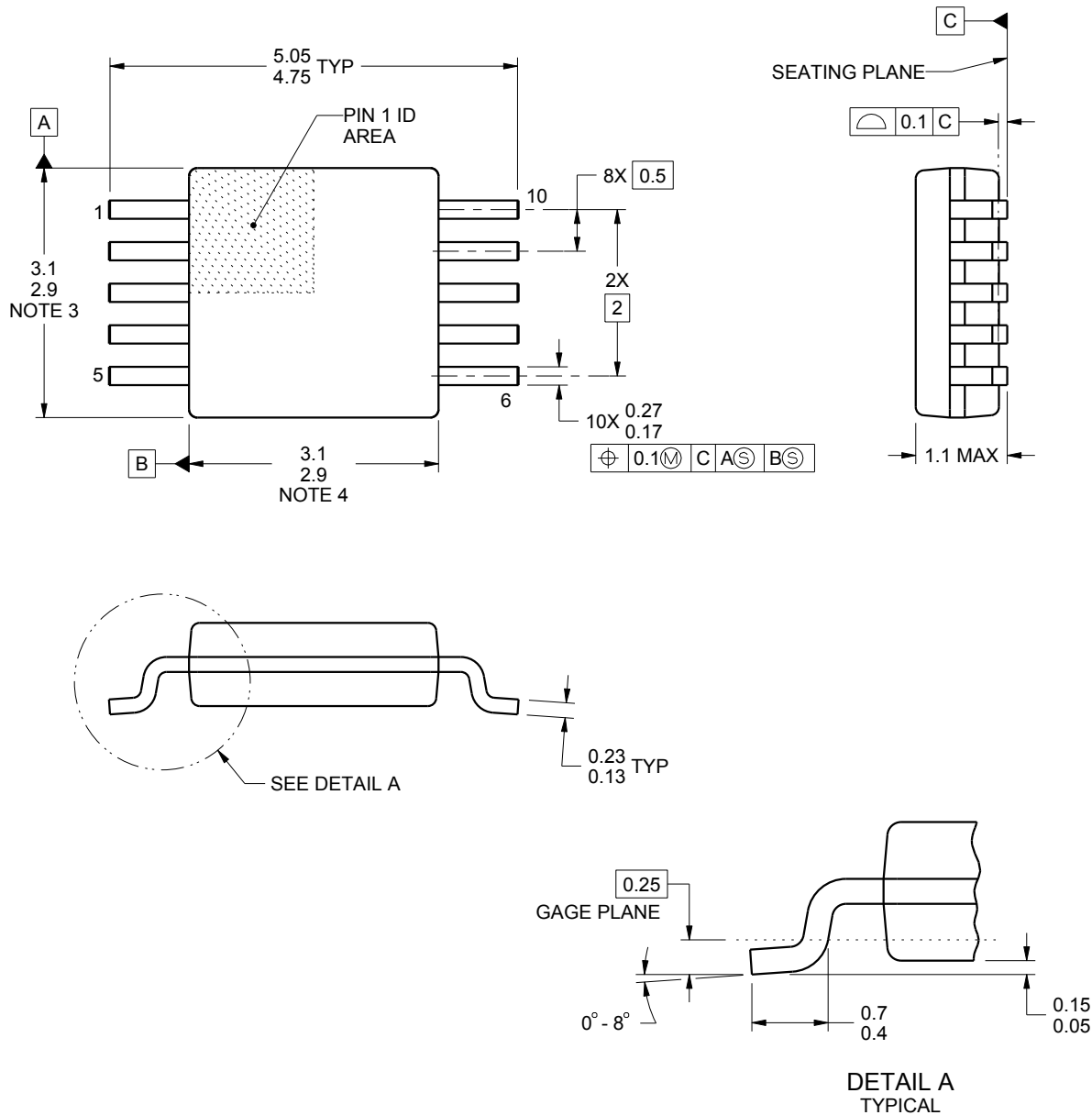
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DAC082S085C1MM/NOPB	VSSOP	DGS	10	1000	177.8	12.4	5.3	3.4	1.4	8.0	12.0	Q1
DAC082S085C1MMX/NOPB	VSSOP	DGS	10	3500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
DAC082S085C1SD/NOPB	WSOP	DSC	10	1000	177.8	12.4	3.3	3.3	1.0	8.0	12.0	Q1
DAC082S085C1SDX/NOPB	WSOP	DSC	10	4500	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q1

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DAC082S085C1MM/NOPB	VSSOP	DGS	10	1000	210.0	185.0	35.0
DAC082S085C1MMX/ NOPB	VSSOP	DGS	10	3500	367.0	367.0	35.0
DAC082S085C1SD/NOPB	WSO	DSC	10	1000	210.0	185.0	35.0
DAC082S085C1SDX/ NOPB	WSO	DSC	10	4500	367.0	367.0	35.0



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**NOTES:**

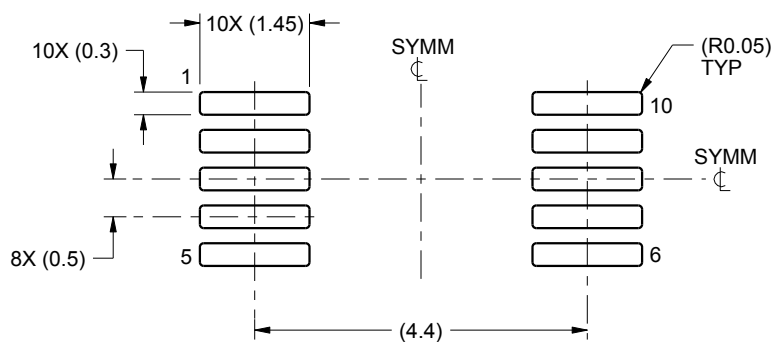
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
5. Reference JEDEC registration MO-187, variation BA.

# EXAMPLE BOARD LAYOUT

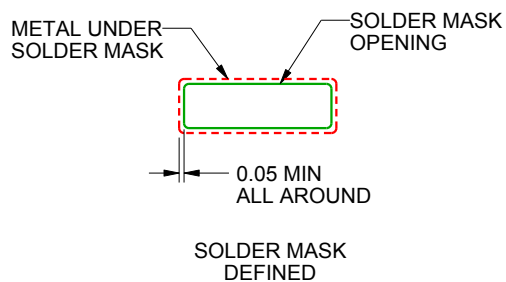
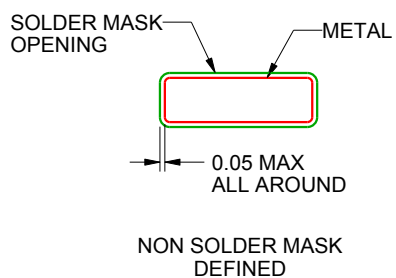
DGS0010A

VSSOP - 1.1 mm max height

SMALL OUTLINE PACKAGE



LAND PATTERN EXAMPLE  
SCALE:10X



SOLDER MASK DETAILS  
NOT TO SCALE

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NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

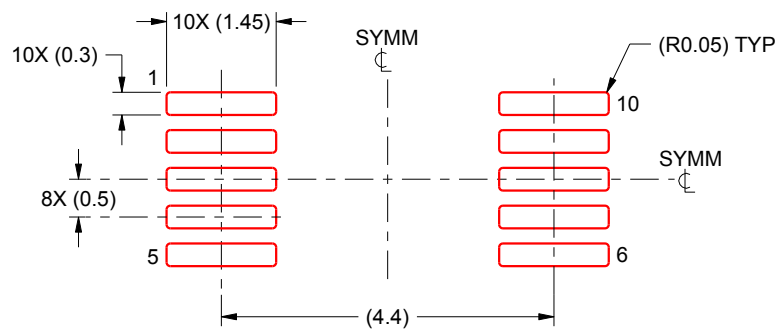
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

## EXAMPLE STENCIL DESIGN

DGS0010A

VSSOP - 1.1 mm max height

SMALL OUTLINE PACKAGE

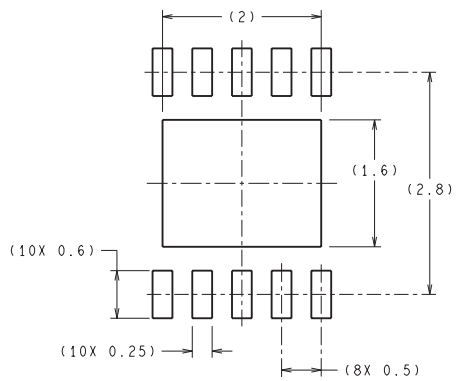


SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE:10X

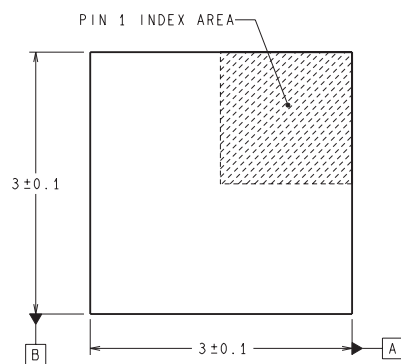
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NOTES: (continued)

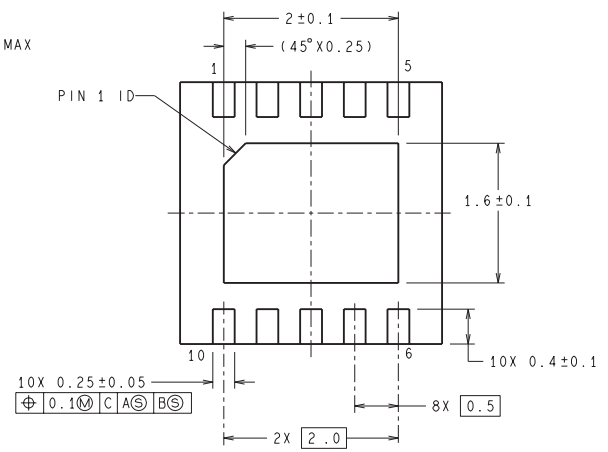
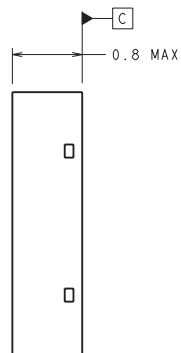
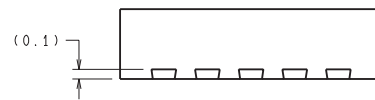
8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.



## RECOMMENDED LAND PATTERN



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DIMENSIONS IN ( ) FOR REFERENCE ONLY



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