

# CC2652R7 SimpleLink™ Multiprotocol 2.4 GHz Wireless MCU

## 1 Features

### Wireless microcontroller

- Powerful 48-MHz Arm® Cortex®-M4F processor
- 704KB flash program memory
- 256KB of ROM for protocols and library functions
- 8KB of cache SRAM
- 144KB of ultra-low leakage SRAM with parity for high-reliability operation
- Dynamic multiprotocol manager (DMM) driver
- Programmable radio includes support for 2-(G)FSK, 4-(G)FSK, MSK, *Bluetooth*® 5.2 Low Energy, IEEE 802.15.4 PHY and MAC
- Supports over-the-air upgrade (OTA)

### Ultra-low power sensor controller

- Autonomous MCU with 4KB of SRAM
- Sample, store, and process sensor data
- Fast wake-up for low-power operation
- Software defined peripherals; capacitive touch, flow meter, LCD

### Low power consumption

- MCU consumption:
  - 3.10 mA active mode, CoreMark
  - 65 µA/MHz running CoreMark
  - 0.9 µA standby mode, RTC, 144KB RAM
  - 0.1 µA shutdown mode, wake-up on pin
- Ultra low-power sensor controller consumption:
  - 29.2 µA in 2 MHz mode
  - 799 µA in 24 MHz mode
- Radio Consumption:
  - 6.4 mA RX
  - 7.3 mA TX at 0 dBm
  - 9.7 mA TX at +5 dBm

### Wireless protocol support

- [Thread](#), [Zigbee](#)®, [Matter](#)
- [Bluetooth](#)® 5.2 Low Energy
- [SimpleLink](#)™ TI 15.4-stack
- 6LoWPAN
- Proprietary systems

### High performance radio

- -104 dBm for *Bluetooth*® Low Energy 125-kbps
- Output power up to +5 dBm with temperature compensation

### Regulatory compliance

- Suitable for systems targeting compliance with these standards:
  - ETSI EN 300 328, EN 300 440 Cat. 2 and 3
  - FCC CFR47 Part 15
  - ARIB STD-T66

### MCU peripherals

- Digital peripherals can be routed to any GPIO
- Four 32-bit or eight 16-bit general-purpose timers
- 12-bit ADC, 200 kSamples/s, 8 channels
- 8-bit DAC
- Two comparators
- Programmable current source
- Two UART, two SSI, I<sup>2</sup>C, I<sup>2</sup>S
- Real-time clock (RTC)
- Integrated temperature and battery monitor

### Security enablers

- AES 128- and 256-bit cryptographic accelerator
- ECC and RSA public key hardware accelerator
- SHA2 Accelerator (full suite up to SHA-512)
- True random number generator (TRNG)

### Development tools and software

- [LP-CC2652R7 Development Kit](#)
- [SimpleLink™ CC13xx and CC26xx Software Development Kit \(SDK\)](#)
- [SmartRF™ Studio](#) for simple radio configuration
- [Sensor Controller Studio](#) for building low-power sensing applications
- [SysConfig](#) system configuration tool

### Operating range

- On-chip buck DC/DC converter
- 1.8-V to 3.8-V single supply voltage
- 1.7-V to 1.95-V external regulator mode
- -40 to +105°C

### Package

- 7-mm × 7-mm RGZ VQFN48 (31 GPIOs)
- RoHS-compliant package



## 2 Applications

- 2400 to 2500 MHz ISM and SRD systems <sup>1</sup> with down to 4 kHz of receive bandwidth
- **Building automation**
  - Building security systems – [motion detector](#), [electronic smart lock](#), [door and window sensor](#), [garage door system](#), [gateway](#)
  - HVAC – [thermostat](#), [wireless environmental sensor](#), [HVAC system controller](#), [gateway](#)
  - Fire safety system – [smoke and heat detector](#), [fire alarm control panel \(FACP\)](#)
  - Video surveillance – [IP network camera](#)
  - Elevators and escalators – [elevator main control panel for elevators and escalators](#)
- **Industrial transport – asset tracking**
- **Factory automation and control**
- **Medical**
- **Electronic point of sale (EPOS) – Electronic Shelf Label (ESL)**
- **Communication equipment**
  - **Wired networking** – [wireless LAN or Wi-Fi access points](#), [edge router](#), [small business router](#)
- **Personal electronics**
  - **Home theater & entertainment** – [smart speakers](#), [smart display](#), [set-top box](#)
  - **Wearables (non-medical)** – [smart trackers](#), [smart clothing](#)

## 3 Description

The SimpleLink™ CC2652R7 device is a multiprotocol 2.4-GHz wireless microcontroller (MCU) supporting [Thread](#), [Zigbee®](#), [Matter](#), [Bluetooth® 5.2 Low Energy](#), IEEE 802.15.4g, IPv6-enabled smart objects (6LoWPAN), [TI 15.4-Stack](#) (2.4 GHz), and concurrent multiprotocol through a Dynamic Multiprotocol Manager (DMM) driver. The CC2652R7 is based on an Arm® Cortex® M4F main processor and optimized for low-power wireless communication and advanced sensing in [grid infrastructure](#), [building automation](#), [retail automation](#), [personal electronics](#) and [medical applications](#).

The CC2652R7 has a software defined radio powered by an Arm® Cortex® M0, which allows support for multiple physical layers and RF standards. The device supports operation in the 2360 to 2500-MHz frequency band. PHY and frequency switching can be done runtime through a dynamic multiprotocol manager (DMM) driver. The CC2652R7 supports +5 dBm TX at 9.7 mA in the 2.4-GHz band. CC2652R7 has a receive sensitivity of -104 dBm for 125-kbps Bluetooth® Low Energy Coded PHY.

The CC2652R7 has a low sleep current of 0.9 µA with RTC and 144KB RAM retention. In addition to the main Cortex® M4F processor, the device also has an autonomous ultra-low power Sensor Controller CPU with fast wake-up capability. As an example, the sensor controller is capable of 1-Hz ADC sampling at 1-µA system current.

The CC2652R7 has [Low SER \(Soft Error Rate\) FIT \(Failure-in-time\)](#) for long operational lifetime. Always-on SRAM parity minimizes risk for corruption due to potential radiation events. Consistent with many customers' 10 to 15 years or longer life cycle requirements, TI has a [product life cycle policy](#) with a commitment to product longevity and continuity of supply.

The CC2652R7 device is part of the SimpleLink™ MCU platform, which consists of Wi-Fi®, [Bluetooth® Low Energy](#), [Thread](#), [Zigbee](#), [Wi-SUN®](#), [Amazon Sidewalk](#), [mioty®](#), Sub-1 GHz MCUs, and host MCUs. CC2652R7 is part of a scalable portfolio with flash sizes from 32KB to 704KB with pin-to-pin compatible package options. The common [SimpleLink™CC13xx and CC26xx Software Development Kit \(SDK\)](#) and [SysConfig](#) system configuration tool supports migration between devices in the portfolio. A comprehensive number of software stacks, application examples and SimpleLink™ Academy training sessions are included in the SDK. For more information, visit [wireless connectivity](#).

### Device Information

PART NUMBER <sup>(1)</sup>	PACKAGE	BODY SIZE (NOM)
CC2652R74T0RGZR	VQFN (48)	7.00 mm × 7.00 mm

(1) For the most current part, package, and ordering information for all available devices, see the Package Option Addendum in [Section 11](#), or see the [TI website](#).

<sup>1</sup> See [RF Core](#) for additional details on supported protocol standards, modulation formats, and data rates.

### 3.1 Functional Block Diagram

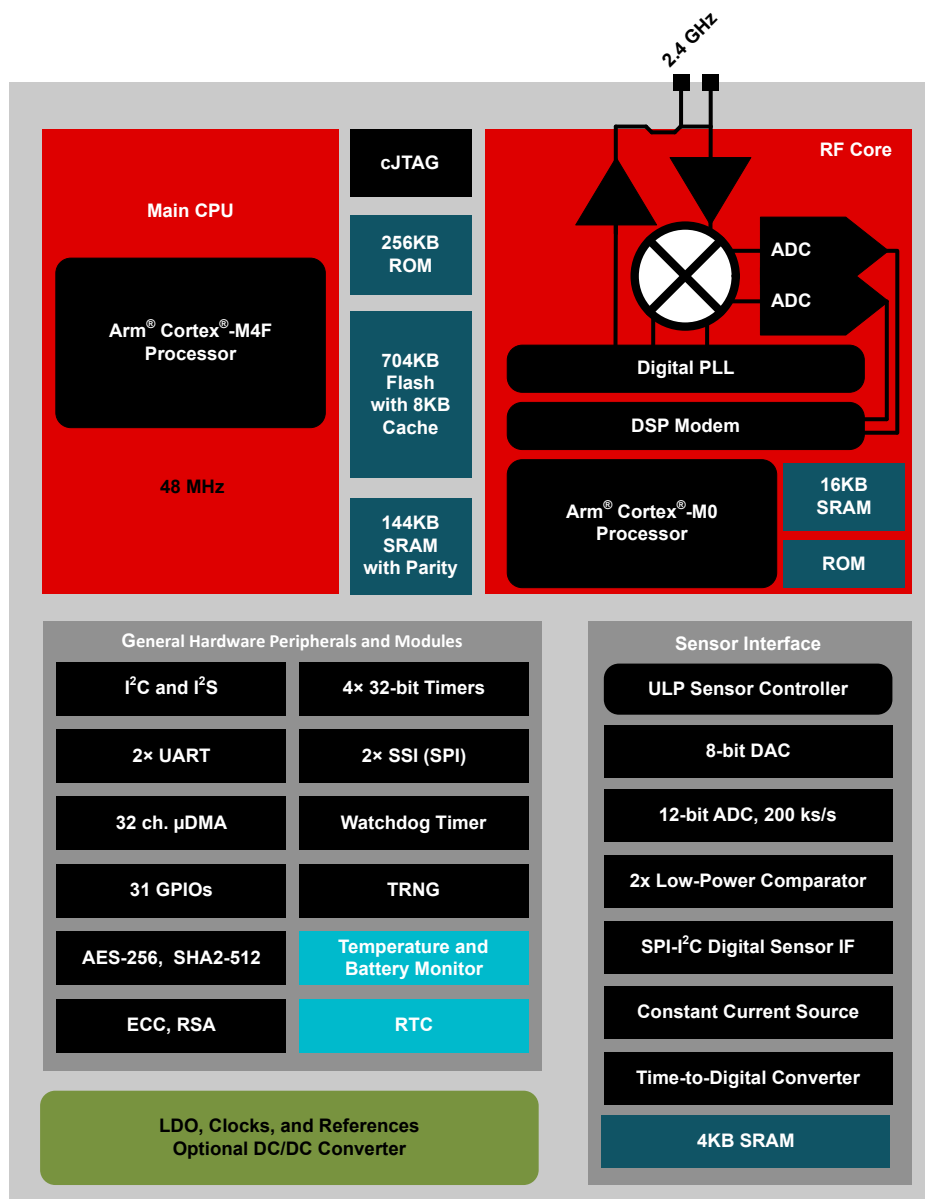


Figure 3-1. CC2652R7 Block Diagram

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## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

### Changes from November 30, 2021 to March 10, 2023 (from Revision A (November 2021) to Revision B (March 2023))

	Page
• Added External Regulator Mode to Operating Range in <a href="#">Section 1</a> .....	1
• Added External Regulator Mode to <a href="#">Section 6.2</a> .....	7
• Added External Regulator Mode to <a href="#">Section 6.3</a> .....	8
• Added External Regulator Mode added to <a href="#">Section 7.1</a> , <a href="#">Section 7.3</a> , and <a href="#">Section 7.4</a> .....	9

## 5 Device Comparison

**Table 5-1. Device Family Overview**

DEVICE	RADIO SUPPORT	FLASH (KB)	RAM (KB)	GPIO	PACKAGE SIZE
CC1310	Sub-1 GHz Wireless M-Bus	32-128	16-20	10-30	RGZ (7-mm × 7-mm VQFN48) RHB (5 mm × 5 mm VQFN32) RSM (4 mm × 4 mm VQFN32)
CC1312R	Sub-1 GHz Wi-SUN® Amazon Sidewalk Wireless M-Bus	352-704	80-144	30	RGZ (7-mm × 7-mm VQFN48)
CC1352P	Multiprotocol Sub-1 GHz Wi-SUN® Amazon Sidewalk Wireless M-Bus Bluetooth 5.2 Low Energy Zigbee Thread 2.4 GHz proprietary FSK-based formats +20-dBm high-power amplifier	352-704	80-144	26	RGZ (7-mm × 7-mm VQFN48)
CC1352R	Multiprotocol Sub-1 GHz Wi-SUN® Wireless M-Bus Bluetooth 5.2 Low Energy Zigbee Thread 2.4 GHz proprietary FSK-based formats	352	80	28	RGZ (7-mm × 7-mm VQFN48)
CC2642R	Bluetooth 5.2 Low Energy 2.4 GHz proprietary FSK-based formats	352	80	31	RGZ (7-mm × 7-mm VQFN48)
CC2642R-Q1	Bluetooth 5.2 Low Energy	352	80	31	RTC (7-mm × 7-mm VQFN48)
CC2652R	Multiprotocol Bluetooth 5.2 Low Energy Zigbee Thread 2.4 GHz proprietary FSK-based formats	352-704	80-144	31	RGZ (7-mm × 7-mm VQFN48)
CC2652RB	Multiprotocol Bluetooth 5.2 Low Energy Zigbee Thread	352	80	31	RGZ (7-mm × 7-mm VQFN48)
CC2652P	Multiprotocol Bluetooth 5.2 Low Energy Zigbee Thread 2.4 GHz proprietary FSK-based formats +19.5-dBm high-power amplifier	352-704	80-144	26	RGZ (7-mm × 7-mm VQFN48)

## 6 Terminal Configuration and Functions

### 6.1 Pin Diagram – RGZ Package (Top View)

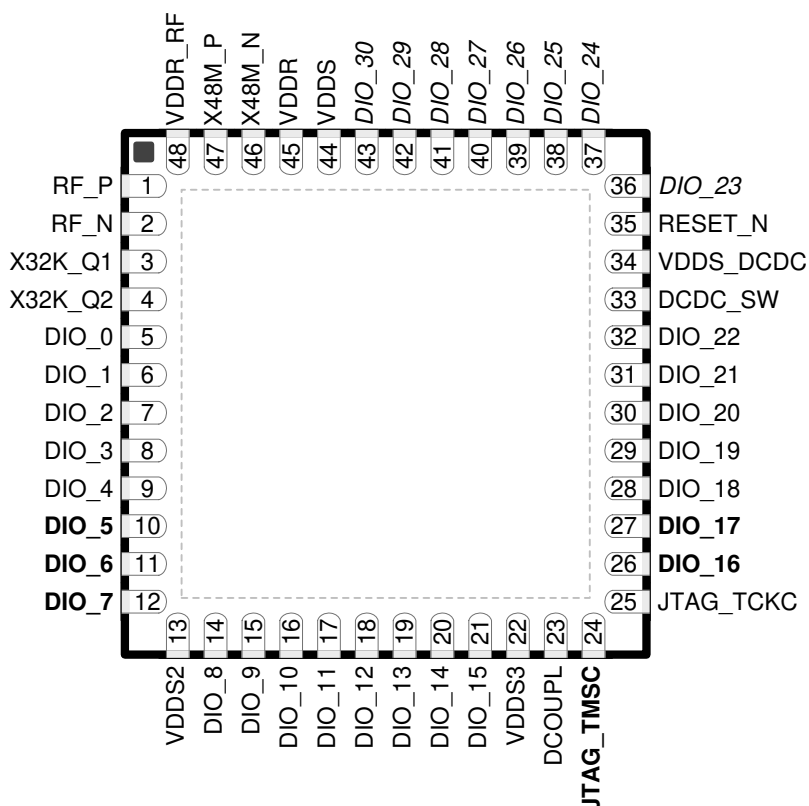


Figure 6-1. RGZ (7-mm × 7-mm) Pinout, 0.5-mm Pitch (Top View)

The following I/O pins marked in [Figure 6-1](#) in **bold** have high-drive capabilities:

- Pin 10, **DIO\_5**
- Pin 11, **DIO\_6**
- Pin 12, **DIO\_7**
- Pin 24, **JTAG\_TMSC**
- Pin 26, **DIO\_16**
- Pin 27, **DIO\_17**

The following I/O pins marked in [Figure 6-1](#) in *italics* have analog capabilities:

- Pin 36, *DIO\_23*
- Pin 37, *DIO\_24*
- Pin 38, *DIO\_25*
- Pin 39, *DIO\_26*
- Pin 40, *DIO\_27*
- Pin 41, *DIO\_28*
- Pin 42, *DIO\_29*
- Pin 43, *DIO\_30*

## 6.2 Signal Descriptions – RGZ Package

**Table 6-1. Signal Descriptions – RGZ Package**

PIN		I/O	TYPE	DESCRIPTION
NAME	NO.			
DCDC_SW	33	—	Power	Output from internal DC/DC converter. Tie to ground for external regulator model (1.7-V to 1.95-V operation). <sup>(1)</sup>
DCOUPPL	23	—	Power	For decoupling of internal 1.27-V regulated digital supply <sup>(2)</sup>
DIO_0	5	I/O	Digital	GPIO
DIO_1	6	I/O	Digital	GPIO
DIO_2	7	I/O	Digital	GPIO
DIO_3	8	I/O	Digital	GPIO
DIO_4	9	I/O	Digital	GPIO
DIO_5	10	I/O	Digital	GPIO, high-drive capability
DIO_6	11	I/O	Digital	GPIO, high-drive capability
DIO_7	12	I/O	Digital	GPIO, high-drive capability
DIO_8	14	I/O	Digital	GPIO
DIO_9	15	I/O	Digital	GPIO
DIO_10	16	I/O	Digital	GPIO
DIO_11	17	I/O	Digital	GPIO
DIO_12	18	I/O	Digital	GPIO
DIO_13	19	I/O	Digital	GPIO
DIO_14	20	I/O	Digital	GPIO
DIO_15	21	I/O	Digital	GPIO
DIO_16	26	I/O	Digital	GPIO, JTAG_TDO, high-drive capability
DIO_17	27	I/O	Digital	GPIO, JTAG_TDI, high-drive capability
DIO_18	28	I/O	Digital	GPIO
DIO_19	29	I/O	Digital	GPIO
DIO_20	30	I/O	Digital	GPIO
DIO_21	31	I/O	Digital	GPIO
DIO_22	32	I/O	Digital	GPIO
DIO_23	36	I/O	Digital or Analog	GPIO, analog capability
DIO_24	37	I/O	Digital or Analog	GPIO, analog capability
DIO_25	38	I/O	Digital or Analog	GPIO, analog capability
DIO_26	39	I/O	Digital or Analog	GPIO, analog capability
DIO_27	40	I/O	Digital or Analog	GPIO, analog capability
DIO_28	41	I/O	Digital or Analog	GPIO, analog capability
DIO_29	42	I/O	Digital or Analog	GPIO, analog capability
DIO_30	43	I/O	Digital or Analog	GPIO, analog capability
EGP	—	—	GND	Ground – exposed ground pad <sup>(3)</sup>
JTAG_TMSC	24	I/O	Digital	JTAG TMS, high-drive capability
JTAG_TCKC	25	I	Digital	JTAG TCKC
RESET_N	35	I	Digital	Reset, active low. No internal pullup resistor
RF_P	1	—	RF	Positive RF input signal to LNA during RX Positive RF output signal from PA during TX
RF_N	2	—	RF	Negative RF input signal to LNA during RX Negative RF output signal from PA during TX

**Table 6-1. Signal Descriptions – RGZ Package (continued)**

PIN		I/O	TYPE	DESCRIPTION
NAME	NO.			
VDDR	45	—	Power	Internal supply, must be powered from the internal DC/DC converter or the internal LDO. For external regulator mode (1.7-V to 1.95-V operation, connect to external regulator and internal DC-DC cannot be used. <sup>(2)</sup> <sup>(4)</sup> <sup>(6)</sup>
VDDR_RF	48	—	Power	Internal supply, must be powered from the internal DC/DC converter or the internal LDO. For external regulator mode (1.7-V to 1.95-V operation, connect to external regulator and internal DC-DC cannot be used. <sup>(2)</sup> <sup>(5)</sup> <sup>(6)</sup>
VDDS	44	—	Power	1.8-V to 3.8-V main chip supply. For external regulator mode (1.7-V to 1.95-V operation, connect to external regulator and internal DC-DC cannot be used. <sup>(1)</sup>
VDDS2	13	—	Power	1.8-V to 3.8-V DIO supply. For external regulator mode (1.7-V to 1.95-V operation, connect to external regulator and internal DC-DC cannot be used. <sup>(1)</sup>
VDDS3	22	—	Power	1.8-V to 3.8-V DIO supply. For external regulator mode (1.7-V to 1.95-V operation, connect to external regulator and internal DC-DC cannot be used. <sup>(1)</sup>
VDDS_DCDC	34	—	Power	1.8-V to 3.8-V DC/DC converter supply. Tie to ground for external regulator mode (1.7-V to 1.95-V operation).
X48M_N	46	—	Analog	48-MHz crystal oscillator pin 1
X48M_P	47	—	Analog	48-MHz crystal oscillator pin 2
X32K_Q1	3	—	Analog	32-kHz crystal oscillator pin 1
X32K_Q2	4	—	Analog	32-kHz crystal oscillator pin 2

(1) For more details, see technical reference manual listed in [Section 10.3](#).

(2) Do not supply external circuitry from this pin.

(3) EGP is the only ground connection for the device. Good electrical connection to device ground on printed circuit board (PCB) is imperative for proper device operation.

(4) If internal DC/DC converter is not used, this pin is supplied internally from the main LDO.

(5) If internal DC/DC converter is not used, this pin must be connected to VDDR for supply from the main LDO.

(6) Output from internal DC/DC and LDO is trimmed to 1.68 V.

## 6.3 Connections for Unused Pins and Modules

**Table 6-2. Connections for Unused Pins – RGZ Package**

FUNCTION	SIGNAL NAME	PIN NUMBER	ACCEPTABLE PRACTICE <sup>(1)</sup>	PREFERRED PRACTICE <sup>(1)</sup>
GPIO	DIO_n	5–12 14–21 26–32 36–43	NC or GND	NC
32.768-kHz crystal	X32K_Q1	3	NC or GND	NC
	X32K_Q2	4		
DC/DC converter <sup>(2)</sup>	DCDC_SW	33	NC (GND) <sup>(3)</sup>	NC (GND) <sup>(3)</sup>
	VDDS_DCDC	34	VDDS (GND) <sup>(3)</sup>	VDDS (GND) <sup>(3)</sup>

(1) NC = No connect

(2) When the DC/DC converter is not used, the inductor between DCDC\_SW and VDDR can be removed. VDDR and VDDR\_RF must still be connected and the 22 uF DCDC capacitor must be kept on the VDDR net.

(3) When operating in external regulator mode.



## 7 Specifications

### 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1) (2)</sup>

		MIN	MAX	UNIT
V <sub>DD</sub> S <sup>(3)</sup>	Supply voltage	−0.3	4.1	V
V <sub>DD</sub> R <sup>(4)</sup>	Supply voltage (External regulator mode)	−0.3	2.25	V
	Voltage on any digital pin <sup>(5) (6)</sup>	−0.3	V <sub>DD</sub> S + 0.3, max 4.1	V
	Voltage on crystal oscillator pins, X32K_Q1, X32K_Q2, X48M_N and X48M_P	−0.3	V <sub>DD</sub> R + 0.3, max 2.25	V
V <sub>in</sub>	Voltage on ADC input	Voltage scaling enabled	V <sub>DD</sub> S	V
		Voltage scaling disabled, internal reference	1.49	
		Voltage scaling disabled, V <sub>DD</sub> S as reference	V <sub>DD</sub> S / 2.9	
	Input level, RF pins (RF_P and RF_N)		5	dBm
T <sub>stg</sub>	Storage temperature	−40	150	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime
- (2) All voltage values are with respect to ground, unless otherwise noted.
- (3) V<sub>DD</sub>S\_DCDC, V<sub>DD</sub>S2 and V<sub>DD</sub>S3 must be at the same potential as V<sub>DD</sub>S.
- (4) V<sub>DD</sub>R, V<sub>DD</sub>S, V<sub>DD</sub>S2 and V<sub>DD</sub>S3 must be at the same potential.
- (5) Including analog capable DIOs.
- (6) Injection current is not supported on any GPIO pin

### 7.2 ESD Ratings

				VALUE	UNIT
V <sub>ESD</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	All pins	±2000	V
		Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup>	All pins	±500	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process

### 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
	Operating ambient temperature <sup>(1) (3)</sup>	−40	105	°C
	Operating junction temperature <sup>(1) (3)</sup>	−40	115	°C
	Operating supply voltage (V <sub>DD</sub> S and V <sub>DD</sub> R), external regulator mode	For operation in 1.8-V systems (V <sub>DD</sub> S and V <sub>DD</sub> R pins connected on PCB, internal DC-DC cannot be used)		V
		1.7	1.95	
	Operating supply voltage (V <sub>DD</sub> S)	1.8	3.8	V
	Rising supply voltage slew rate	0	100	mV/μs
	Falling supply voltage slew rate <sup>(2)</sup>	0	20	mV/μs

- (1) Operation at or near maximum operating temperature for extended durations will result in a reduction in lifetime.
- (2) For small coin-cell batteries, with high worst-case end-of-life equivalent source resistance, a 22-μF V<sub>DD</sub>S input capacitor must be used to ensure compliance with this slew rate.
- (3) For thermal resistance characteristics refer to [Section 7.8](#).

### 7.4 Power Supply and Modules

over operating free-air temperature range (unless otherwise noted)

PARAMETER		MIN	TYP	MAX	UNIT
V <sub>DD</sub> S Power-on-Reset (POR) threshold		1.1 - 1.55			V
V <sub>DD</sub> S Brown-out Detector (BOD) <sup>(1)</sup>	Rising threshold	1.77			V

## 7.4 Power Supply and Modules (continued)

over operating free-air temperature range (unless otherwise noted)

PARAMETER		MIN	TYP	MAX	UNIT
VDDS Brown-out Detector (BOD) External regulator mode	Rising threshold		1.64		V
VDDS Brown-out Detector (BOD), before initial boot <sup>(2)</sup>	Rising threshold		1.70		V
VDDS Brown-out Detector (BOD) <sup>(1)</sup>	Falling threshold		1.75		V
VDDS Brown-out Detector (BOD) External regulator mode	Falling threshold		1.63		V

(1) For boost mode (VDDR = 1.95 V), TI drivers software initialization will trim VDDS BOD limits to maximum (approximately 2.0 V)

(2) Brown-out Detector is trimmed at initial boot, value is kept until device is reset by a POR reset or the RESET\_N pin

## 7.5 Power Consumption - Power Modes

When measured on the CC26x2-R7EM-7ID reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{\text{DDS}} = 3.0\text{ V}$  with DC/DC enabled unless otherwise noted.

PARAMETER		TEST CONDITIONS	TYP	UNIT
Core Current Consumption				
I <sub>core</sub>	Reset and Shutdown	Reset. RESET_N pin asserted or VDDS below power-on-reset threshold	100	nA
		Shutdown. No clocks running, no retention	100	
	Standby without cache retention	RTC running, CPU, 144KB RAM and (partial) register retention. RCOSC_LF	0.9	μA
		RTC running, CPU, 64KB RAM and (partial) register retention. RCOSC_LF	0.8	μA
		RTC running, CPU, 144KB RAM and (partial) register retention XOSC_LF	1.0	μA
	Standby with cache retention	RTC running, CPU, 144KB RAM and (partial) register retention. RCOSC_LF	2.3	μA
		RTC running, CPU, 144KB RAM and (partial) register retention. XOSC_LF	2.4	μA
	Idle	Supply Systems and RAM powered RCOSC_HF	669	μA
I <sub>core</sub>	Active	MCU running CoreMark at 48 MHz RCOSC_HF	3.1	mA
Peripheral Current Consumption				
I <sub>peri</sub>	Peripheral power domain	Delta current with domain enabled	49	μA
	Serial power domain	Delta current with domain enabled	3.6	
	RF Core	Delta current with power domain enabled, clock enabled, RF core idle	109	
	μDMA	Delta current with clock enabled, module is idle	69	
	Timers	Delta current with clock enabled, module is idle <sup>(3)</sup>	115	
	I2C	Delta current with clock enabled, module is idle	11.6	
	I2S	Delta current with clock enabled, module is idle	27.6	
	SSI	Delta current with clock enabled, module is idle	61	
	UART	Delta current with clock enabled, module is idle <sup>(1)</sup>	131	
	CRYPTO (AES)	Delta current with clock enabled, module is idle <sup>(2)</sup>	19.5	
	PKA	Delta current with clock enabled, module is idle	70	
	TRNG	Delta current with clock enabled, module is idle	25	
Sensor Controller Engine Consumption				
I <sub>SCE</sub>	Active mode	24 MHz, infinite loop	799	μA
	Low-power mode	2 MHz, infinite loop	29.2	

- (1) Only one UART running  
 (2) Only one SSI running  
 (3) Only one GPTimer running

## 7.6 Power Consumption - Radio Modes

When measured on the CC26x2-R7EM-7ID reference design with  $T_c = 25\text{ }^{\circ}\text{C}$ ,  $V_{\text{DDS}} = 3.0\text{ V}$  with DC/DC enabled unless otherwise noted.

PARAMETER	TEST CONDITIONS	TYP	UNIT
Radio receive current	2440 MHz	6.4	mA
Radio transmit current 2.4 GHz PA (Bluetooth Low Energy)	0 dBm output power setting 2440 MHz	7.3	mA
	+5 dBm output power setting 2440 MHz	9.7	mA

## 7.7 Nonvolatile (Flash) Memory Characteristics

Over operating free-air temperature range and  $V_{\text{DDS}} = 3.0\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Flash sector size			8		KB
Supported flash erase cycles before failure, single-bank <sup>(1) (5)</sup>		30			k Cycles
Supported flash erase cycles before failure, single sector <sup>(2)</sup>		60			k Cycles
Maximum number of write operations per row before sector erase <sup>(3)</sup>				83	Write Operations
Flash retention	105 $^{\circ}\text{C}$	11.4			Years
Flash sector erase current	Average delta current		9.5		mA
Flash sector erase time <sup>(4)</sup>	Zero cycles		10		ms
	30k cycles			4000	ms
Flash write current	Average delta current, 4 bytes at a time		5.2		mA
Flash write time <sup>(4)</sup>	4 bytes at a time		21.6		$\mu\text{s}$

- (1) A full bank erase is counted as a single erase cycle on each sector. If both flash banks are always cycled simultaneously they can be cycled 30K times each. Alternatively, the banks can be cycled a total of 30K times, e.g. the main bank X times and the second bank Y times ( $X+Y=30K$ )
- (2) Up to 4 customer-designated sectors can be individually erased an additional 30k times beyond the baseline bank limitation of 30k cycles
- (3) Each wordline is 2048 bits (or 256 bytes) wide. This limitation corresponds to sequential memory writes of 4 (3.1) bytes minimum per write over a whole wordline. If additional writes to the same wordline are required, a sector erase is required once the maximum number of write operations per row is reached.
- (4) This number is dependent on Flash aging and increases over time and erase cycles
- (5) Aborting flash during erase or program modes is not a safe operation.

## 7.8 Thermal Resistance Characteristics

THERMAL METRIC <sup>(1)</sup>		PACKAGE	UNIT
		RGZ (VQFN)	
		48 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	23.7	°C/W <sup>(2)</sup>
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	13.0	°C/W <sup>(2)</sup>
R <sub>θJB</sub>	Junction-to-board thermal resistance	7.7	°C/W <sup>(2)</sup>
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	0.1	°C/W <sup>(2)</sup>
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	7.6	°C/W <sup>(2)</sup>
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	1.9	°C/W <sup>(2)</sup>

- (1) For more information about traditional and new thermal metrics, see [Semiconductor and IC Package Thermal Metrics](#).
- (2)  $^{\circ}\text{C/W}$  = degrees Celsius per watt.

## 7.9 RF Frequency Bands

Over operating free-air temperature range (unless otherwise noted).

PARAMETER	MIN	TYP	MAX	UNIT
Frequency bands	2360		2500	MHz

## 7.10 Bluetooth Low Energy - Receive (RX)

When measured on the CC26x2R-7EM-7ID reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ ,  $f_{RF} = 2440\text{ MHz}$  with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>125 kbps (LE Coded)</b>					
Receiver sensitivity	Differential mode. BER = $10^{-3}$		-104		dBm
Receiver saturation	Differential mode. BER = $10^{-3}$		>5		dBm
Frequency error tolerance	Difference between the incoming carrier frequency and the internally generated carrier frequency		> (-300 / 300)		kHz
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (37-byte packets)		> (-320 / 240)		ppm
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (255-byte packets)		> (-125 / 100)		ppm
Co-channel rejection <sup>(1)</sup>	Wanted signal at -79 dBm, modulated interferer in channel, BER = $10^{-3}$		-1.5		dB
Selectivity, $\pm 1\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -79 dBm, modulated interferer at $\pm 1\text{ MHz}$ , BER = $10^{-3}$		8 / 4.5 <sup>(2)</sup>		dB
Selectivity, $\pm 2\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -79 dBm, modulated interferer at $\pm 2\text{ MHz}$ , BER = $10^{-3}$		44 / 37 <sup>(2)</sup>		dB
Selectivity, $\pm 3\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -79 dBm, modulated interferer at $\pm 3\text{ MHz}$ , BER = $10^{-3}$		46 / 44 <sup>(2)</sup>		dB
Selectivity, $\pm 4\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -79 dBm, modulated interferer at $\pm 4\text{ MHz}$ , BER = $10^{-3}$		44 / 46 <sup>(2)</sup>		dB
Selectivity, $\pm 6\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -79 dBm, modulated interferer at $\pm 6\text{ MHz}$ , BER = $10^{-3}$		48 / 44 <sup>(2)</sup>		dB
Selectivity, $\pm 7\text{ MHz}$	Wanted signal at -79 dBm, modulated interferer at $\pm 7\text{ MHz}$ , BER = $10^{-3}$		51 / 45 <sup>(2)</sup>		dB
Selectivity, Image frequency <sup>(1)</sup>	Wanted signal at -79 dBm, modulated interferer at image frequency, BER = $10^{-3}$		37		dB
Selectivity, Image frequency $\pm 1\text{ MHz}$ <sup>(1)</sup>	Note that Image frequency + 1 MHz is the Co- channel -1 MHz. Wanted signal at -79 dBm, modulated interferer at $\pm 1\text{ MHz}$ from image frequency, BER = $10^{-3}$		4.5 / 44 <sup>(2)</sup>		dB
RSSI Range			89		dB
RSSI Accuracy (+/-)			$\pm 4$		dB
<b>500 kbps (LE Coded)</b>					
Receiver sensitivity	Differential mode. BER = $10^{-3}$		-100		dBm
Receiver saturation	Differential mode. BER = $10^{-3}$		> 5		dBm
Frequency error tolerance	Difference between the incoming carrier frequency and the internally generated carrier frequency		> (-300 / 300)		kHz
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (37-byte packets)		> (-450 / 450)		ppm
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (255-byte packets)		> (-150 / 175)		ppm
Co-channel rejection <sup>(1)</sup>	Wanted signal at -72 dBm, modulated interferer in channel, BER = $10^{-3}$		-3.5		dB
Selectivity, $\pm 1\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -72 dBm, modulated interferer at $\pm 1\text{ MHz}$ , BER = $10^{-3}$		8 / 4 <sup>(2)</sup>		dB
Selectivity, $\pm 2\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -72 dBm, modulated interferer at $\pm 2\text{ MHz}$ , BER = $10^{-3}$		43 / 35 <sup>(2)</sup>		dB
Selectivity, $\pm 3\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -72 dBm, modulated interferer at $\pm 3\text{ MHz}$ , BER = $10^{-3}$		46 / 46 <sup>(2)</sup>		dB
Selectivity, $\pm 4\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -72 dBm, modulated interferer at $\pm 4\text{ MHz}$ , BER = $10^{-3}$		45 / 47 <sup>(2)</sup>		dB
Selectivity, $\pm 6\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -72 dBm, modulated interferer at $\pm 6\text{ MHz}$ , BER = $10^{-3}$		46 / 45 <sup>(2)</sup>		dB
Selectivity, $\pm 7\text{ MHz}$	Wanted signal at -72 dBm, modulated interferer at $\pm 7\text{ MHz}$ , BER = $10^{-3}$		49 / 45 <sup>(2)</sup>		dB

## 7.10 Bluetooth Low Energy - Receive (RX) (continued)

When measured on the CC26x2R-7EM-7ID reference design with  $T_c = 25\text{ }^\circ\text{C}$ ,  $V_{DDs} = 3.0\text{ V}$ ,  $f_{RF} = 2440\text{ MHz}$  with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Selectivity, Image frequency <sup>(1)</sup>	Wanted signal at $-72\text{ dBm}$ , modulated interferer at image frequency, $BER = 10^{-3}$		35		dB
Selectivity, Image frequency $\pm 1\text{ MHz}$ <sup>(1)</sup>	Note that Image frequency + 1 MHz is the Co- channel $-1\text{ MHz}$ . Wanted signal at $-72\text{ dBm}$ , modulated interferer at $\pm 1\text{ MHz}$ from image frequency, $BER = 10^{-3}$		4 / 46 <sup>(2)</sup>		dB
RSSI Range			90		dB
RSSI Accuracy (+/-)			$\pm 4$		dB
<b>1 Mbps (LE 1M)</b>					
Receiver sensitivity	Differential mode. $BER = 10^{-3}$		$-97$		dBm
Receiver saturation	Differential mode. $BER = 10^{-3}$		$> 5$		dBm
Frequency error tolerance	Difference between the incoming carrier frequency and the internally generated carrier frequency		$> (-350 / 350)$		kHz
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (37-byte packets)		$> (-650 / 750)$		ppm
Co-channel rejection <sup>(1)</sup>	Wanted signal at $-67\text{ dBm}$ , modulated interferer in channel, $BER = 10^{-3}$		$-6$		dB
Selectivity, $\pm 1\text{ MHz}$ <sup>(1)</sup>	Wanted signal at $-67\text{ dBm}$ , modulated interferer at $\pm 1\text{ MHz}$ , $BER = 10^{-3}$		7 / 4 <sup>(2)</sup>		dB
Selectivity, $\pm 2\text{ MHz}$ <sup>(1)</sup>	Wanted signal at $-67\text{ dBm}$ , modulated interferer at $\pm 2\text{ MHz}$ , $BER = 10^{-3}$		39 / 33 <sup>(2)</sup>		dB
Selectivity, $\pm 3\text{ MHz}$ <sup>(1)</sup>	Wanted signal at $-67\text{ dBm}$ , modulated interferer at $\pm 3\text{ MHz}$ , $BER = 10^{-3}$		36 / 40 <sup>(2)</sup>		dB
Selectivity, $\pm 4\text{ MHz}$ <sup>(1)</sup>	Wanted signal at $-67\text{ dBm}$ , modulated interferer at $\pm 4\text{ MHz}$ , $BER = 10^{-3}$		36 / 45 <sup>(2)</sup>		dB
Selectivity, $\pm 5\text{ MHz}$ or more <sup>(1)</sup>	Wanted signal at $-67\text{ dBm}$ , modulated interferer at $\geq \pm 5\text{ MHz}$ , $BER = 10^{-3}$		40		dB
Selectivity, image frequency <sup>(1)</sup>	Wanted signal at $-67\text{ dBm}$ , modulated interferer at image frequency, $BER = 10^{-3}$		33		dB
Selectivity, image frequency $\pm 1\text{ MHz}$ <sup>(1)</sup>	Note that Image frequency + 1 MHz is the Co- channel $-1\text{ MHz}$ . Wanted signal at $-67\text{ dBm}$ , modulated interferer at $\pm 1\text{ MHz}$ from image frequency, $BER = 10^{-3}$		4 / 41 <sup>(2)</sup>		dB
Out-of-band blocking <sup>(3)</sup>	30 MHz to 2000 MHz		$-10$		dBm
Out-of-band blocking	2003 MHz to 2399 MHz		$-18$		dBm
Out-of-band blocking	2484 MHz to 2997 MHz		$-12$		dBm
Out-of-band blocking	3000 MHz to 12.75 GHz		$-2$		dBm
Intermodulation	Wanted signal at 2402 MHz, $-64\text{ dBm}$ . Two interferers at 2405 and 2408 MHz respectively, at the given power level		$-42$		dBm
Spurious emissions, 30 to 1000 MHz	Measurement in a 50- $\Omega$ single-ended load.		$< -59$		dBm
Spurious emissions, 1 to 12.75 GHz	Measurement in a 50- $\Omega$ single-ended load.		$< -47$		dBm
RSSI dynamic range			70		dB
RSSI accuracy			$\pm 4$		dB
<b>2 Mbps (LE 2M)</b>					
Receiver sensitivity	Differential mode. Measured at SMA connector, $BER = 10^{-3}$		$-91$		dBm
Receiver saturation	Differential mode. Measured at SMA connector, $BER = 10^{-3}$		$> 5$		dBm
Frequency error tolerance	Difference between the incoming carrier frequency and the internally generated carrier frequency		$> (-500 / 500)$		kHz
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (37-byte packets)		$> (-700 / 750)$		ppm

## 7.10 Bluetooth Low Energy - Receive (RX) (continued)

When measured on the CC26x2R-7EM-7ID reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ ,  $f_{RF} = 2440\text{ MHz}$  with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Co-channel rejection <sup>(1)</sup>	Wanted signal at -67 dBm, modulated interferer in channel, BER = $10^{-3}$		-7		dB
Selectivity, $\pm 2\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -67 dBm, modulated interferer at $\pm 2\text{ MHz}$ , Image frequency is at -2 MHz, BER = $10^{-3}$		8 / 4 <sup>(2)</sup>		dB
Selectivity, $\pm 4\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -67 dBm, modulated interferer at $\pm 4\text{ MHz}$ , BER = $10^{-3}$		36 / 34 <sup>(2)</sup>		dB
Selectivity, $\pm 6\text{ MHz}$ <sup>(1)</sup>	Wanted signal at -67 dBm, modulated interferer at $\pm 6\text{ MHz}$ , BER = $10^{-3}$		37 / 36 <sup>(2)</sup>		dB
Selectivity, image frequency <sup>(1)</sup>	Wanted signal at -67 dBm, modulated interferer at image frequency, BER = $10^{-3}$		4		dB
Selectivity, image frequency $\pm 2\text{ MHz}$ <sup>(1)</sup>	Note that Image frequency + 2 MHz is the Co-channel. Wanted signal at -67 dBm, modulated interferer at $\pm 2\text{ MHz}$ from image frequency, BER = $10^{-3}$		-7 / 36 <sup>(2)</sup>		dB
Out-of-band blocking <sup>(3)</sup>	30 MHz to 2000 MHz		-16		dBm
Out-of-band blocking	2003 MHz to 2399 MHz		-21		dBm
Out-of-band blocking	2484 MHz to 2997 MHz		-15		dBm
Out-of-band blocking	3000 MHz to 12.75 GHz		-12		dBm
Intermodulation	Wanted signal at 2402 MHz, -64 dBm. Two interferers at 2408 and 2414 MHz respectively, at the given power level		-38		dBm
RSSI Range			60		dB
RSSI Accuracy (+/-)			$\pm 4$		dB

(1) Numbers given as I/C dB

(2) X / Y, where X is +N MHz and Y is -N MHz

(3) Excluding one exception at  $F_{\text{wanted}} / 2$ , per Bluetooth Specification



## 7.11 Bluetooth Low Energy - Transmit (TX)

When measured on the CC26x2-R7EM-7ID reference design with  $T_c = 25\text{ }^{\circ}\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ ,  $f_{RF} = 2440\text{ MHz}$  with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>General Parameters</b>					
Max output power	Differential mode, delivered to a single-ended 50 $\Omega$ load through a balun		5		dBm
Output power programmable range	Differential mode, delivered to a single-ended 50 $\Omega$ load through a balun		26		dB
<b>Spurious emissions and harmonics</b>					
Spurious emissions	f < 1 GHz, outside restricted bands	+5 dBm setting	< -36		dBm
	f < 1 GHz, restricted bands ETSI		< -54		dBm
	f < 1 GHz, restricted bands FCC		< -55		dBm
	f > 1 GHz, including harmonics		< -42		dBm
Harmonics	Second harmonic		< -42		dBm
	Third harmonic		< -42		dBm

## 7.12 Zigbee and Thread - IEEE 802.15.4-2006 2.4 GHz (OQPSK DSSS1:8, 250 kbps) - RX

When measured on the CC26x2-R7EM-7ID reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{\text{DDS}} = 3.0\text{ V}$ ,  $f_{\text{RF}} = 2440\text{ MHz}$  with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>General Parameters</b>					
Receiver sensitivity	PER = 1%		–99		dBm
Receiver saturation	PER = 1%		> 5		dBm
Adjacent channel rejection	Wanted signal at –82 dBm, modulated interferer at $\pm 5\text{ MHz}$ , PER = 1%		36		dB
Alternate channel rejection	Wanted signal at –82 dBm, modulated interferer at $\pm 10\text{ MHz}$ , PER = 1%		57		dB
Channel rejection, $\pm 15\text{ MHz}$ or more	Wanted signal at –82 dBm, undesired signal is IEEE 802.15.4 modulated channel, stepped through all channels 2405 to 2480 MHz, PER = 1%		59		dB
Blocking and desensitization, 5 MHz from upper band edge	Wanted signal at –97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%		57		dB
Blocking and desensitization, 10 MHz from upper band edge	Wanted signal at –97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%		62		dB
Blocking and desensitization, 20 MHz from upper band edge	Wanted signal at –97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%		62		dB
Blocking and desensitization, 50 MHz from upper band edge	Wanted signal at –97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%		65		dB
Blocking and desensitization, –5 MHz from lower band edge	Wanted signal at –97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%		59		dB
Blocking and desensitization, –10 MHz from lower band edge	Wanted signal at –97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%		59		dB
Blocking and desensitization, –20 MHz from lower band edge	Wanted signal at –97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%		63		dB
Blocking and desensitization, –50 MHz from lower band edge	Wanted signal at –97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%		65		dB
Spurious emissions, 30 MHz to 1000 MHz	Measurement in a 50- $\Omega$ single-ended load		–66		dBm
Spurious emissions, 1 GHz to 12.75 GHz	Measurement in a 50- $\Omega$ single-ended load		–53		dBm
Frequency error tolerance	Difference between the incoming carrier frequency and the internally generated carrier frequency		> 350		ppm
Symbol rate error tolerance	Difference between incoming symbol rate and the internally generated symbol rate		> 1000		ppm
RSSI dynamic range			95		dB
RSSI accuracy			$\pm 4$		dB

## 7.13 Zigbee and Thread - IEEE 802.15.4-2006 2.4 GHz (OQPSK DSSS1:8, 250 kbps) - TX

When measured on the CC26x2-R7EM-7ID reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ ,  $f_{RF} = 2440\text{ MHz}$  with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNIT
General Parameters						
Max output power	Differential mode, delivered to a single-ended 50-Ω load through a balun		5			dBm
Output power programmable range	Differential mode, delivered to a single-ended 50-Ω load through a balun		26			dB
Spurious emissions and harmonics						
Spurious emissions <sup>(1)</sup>	f < 1 GHz, outside restricted bands	+5 dBm setting	< -36			dBm
	f < 1 GHz, restricted bands ETSI		< -47			dBm
	f < 1 GHz, restricted bands FCC		< -55			dBm
	f > 1 GHz, including harmonics		< -42			dBm
Harmonics	Second harmonic		< -42			dBm
	Third harmonic		< -42			dBm
IEEE 802.15.4-2006 2.4 GHz (OQPSK DSSS1:8, 250 kbps)						
Error vector magnitude	+5 dBm setting		2			%

- (1) To ensure margins for passing FCC band edge requirements at 2483.5 MHz, a lower than maximum output-power setting or less than 100% duty cycle may be used when operating at 2480 MHz.

## 7.14 Timing and Switching Characteristics

### 7.14.1 Reset Timing

PARAMETER	MIN	TYP	MAX	UNIT
RESET_N low duration	1			μs

### 7.14.2 Wakeup Timing

Measured over operating free-air temperature with  $V_{DD5} = 3.0\text{ V}$  (unless otherwise noted). The times listed here do not include software overhead.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
MCU, Reset to Active <sup>(1)</sup>		850 - 4000			μs
MCU, Shutdown to Active <sup>(1)</sup>		850 - 4000			μs
MCU, Standby to Active		165			μs
MCU, Active to Standby		39			μs
MCU, Idle to Active		15			μs

- (1) The wakeup time is dependent on remaining charge on VDDR capacitor when starting the device, and thus how long the device has been in Reset or Shutdown before starting up again. The wake up time increases with a higher capacitor value.

### 7.14.3 Clock Specifications

#### 7.14.3.1 48 MHz Crystal Oscillator (XOSC\_HF)

Measured on a Texas Instruments reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.<sup>(1)</sup>

	PARAMETER	MIN	TYP	MAX	UNIT
	Crystal frequency		48		MHz
ESR	Equivalent series resistance $6\text{ pF} < C_L \leq 9\text{ pF}$		20	60	$\Omega$
ESR	Equivalent series resistance $5\text{ pF} < C_L \leq 6\text{ pF}$			80	$\Omega$
$L_M$	Motional inductance, relates to the load capacitance that is used for the crystal ( $C_L$ in Farads) <sup>(5)</sup>		$< 3 \times 10^{-25} / C_L^2$		H
$C_L$	Crystal load capacitance <sup>(4)</sup>	5	7 <sup>(3)</sup>	9	pF
	Start-up time <sup>(2)</sup>		200		$\mu\text{s}$

- (1) Probing or otherwise stopping the crystal while the DC/DC converter is enabled may cause permanent damage to the device.
- (2) Start-up time using the TI-provided power driver. Start-up time may increase if driver is not used.
- (3) On-chip default connected capacitance including reference design parasitic capacitance. Connected internal capacitance is changed through software in the Customer Configuration section (CCFG).
- (4) Adjustable load capacitance is integrated into the device.
- (5) The crystal manufacturer's specification must satisfy this requirement for proper operation.

#### 7.14.3.2 48 MHz RC Oscillator (RCOSC\_HF)

Measured on a Texas Instruments reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.

	MIN	TYP	MAX	UNIT
Frequency		48		MHz
Uncalibrated frequency accuracy		$\pm 1$		%
Calibrated frequency accuracy <sup>(1)</sup>		$\pm 0.25$		%
Start-up time		5		$\mu\text{s}$

- (1) Accuracy relative to the calibration source (XOSC\_HF)

#### 7.14.3.3 2 MHz RC Oscillator (RCOSC\_MF)

Measured on a Texas Instruments reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.

	MIN	TYP	MAX	UNIT
Calibrated frequency		2		MHz
Start-up time		5		$\mu\text{s}$

#### 7.14.3.4 32.768 kHz Crystal Oscillator (XOSC\_LF)

Measured on a Texas Instruments reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.

	MIN	TYP	MAX	UNIT
		32.768		kHz
ESR		30	100	k $\Omega$
$C_L$	6	7 <sup>(1)</sup>	12	pF

- (1) Default load capacitance using TI reference designs including parasitic capacitance. Crystals with different load capacitance may be used.

#### 7.14.3.5 32 kHz RC Oscillator (RCOSC\_LF)

Measured on a Texas Instruments reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.

	MIN	TYP	MAX	UNIT
Frequency		32.8		kHz
Calibrated RTC variation <sup>(1)</sup>		$\pm 600$ <sup>(3)</sup>		ppm

Calibrated periodically against XOSC\_HF<sup>(2)</sup>

### 7.14.3.5 32 kHz RC Oscillator (RCOSC\_LF) (continued)

Measured on a Texas Instruments reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.

	MIN	TYP	MAX	UNIT
Temperature coefficient		50		ppm/ $^\circ\text{C}$

- (1) When using RCOSC\_LF as source for the low frequency system clock (SCLK\_LF), the accuracy of the SCLK\_LF-derived Real Time Clock (RTC) can be improved by measuring RCOSC\_LF relative to XOSC\_HF and compensating for the RTC tick speed. This functionality is available through the TI-provided Power driver.
- (2) TI driver software calibrates the RTC every time XOSC\_HF is enabled.
- (3) Some device's variation can exceed 1000 ppm. Further calibration will not improve variation.

## 7.14.4 Synchronous Serial Interface (SSI) Characteristics

### 7.14.4.1 Synchronous Serial Interface (SSI) Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER NO.	PARAMETER	MIN	TYP	MAX	UNIT
S1	$t_{\text{clk\_per}}$ SSIClk cycle time	12		65024	System Clocks <sup>(2)</sup>
S2 <sup>(1)</sup>	$t_{\text{clk\_high}}$ SSIClk high time		0.5		$t_{\text{clk\_per}}$
S3 <sup>(1)</sup>	$t_{\text{clk\_low}}$ SSIClk low time		0.5		$t_{\text{clk\_per}}$

- (1) Refer to SSI timing diagrams [Figure 7-1](#), [Figure 7-2](#) and [Figure 7-3](#).
- (2) When using the TI-provided Power driver, the SSI system clock is always 48 MHz.

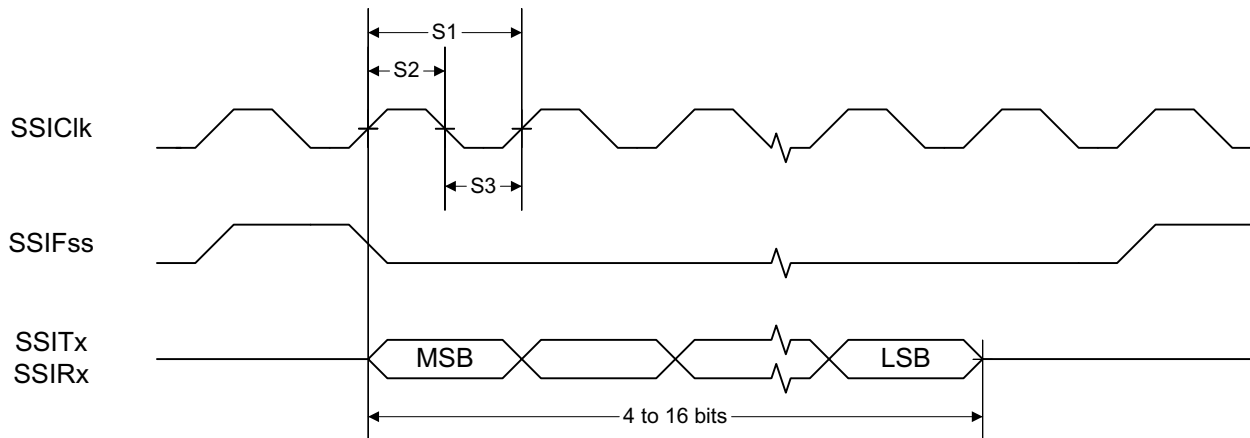
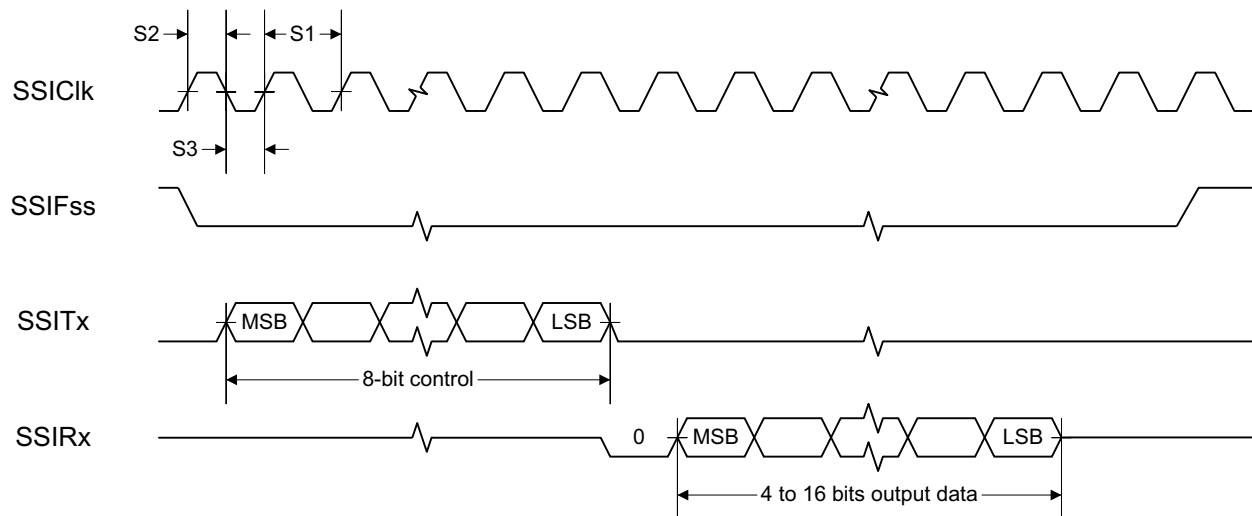
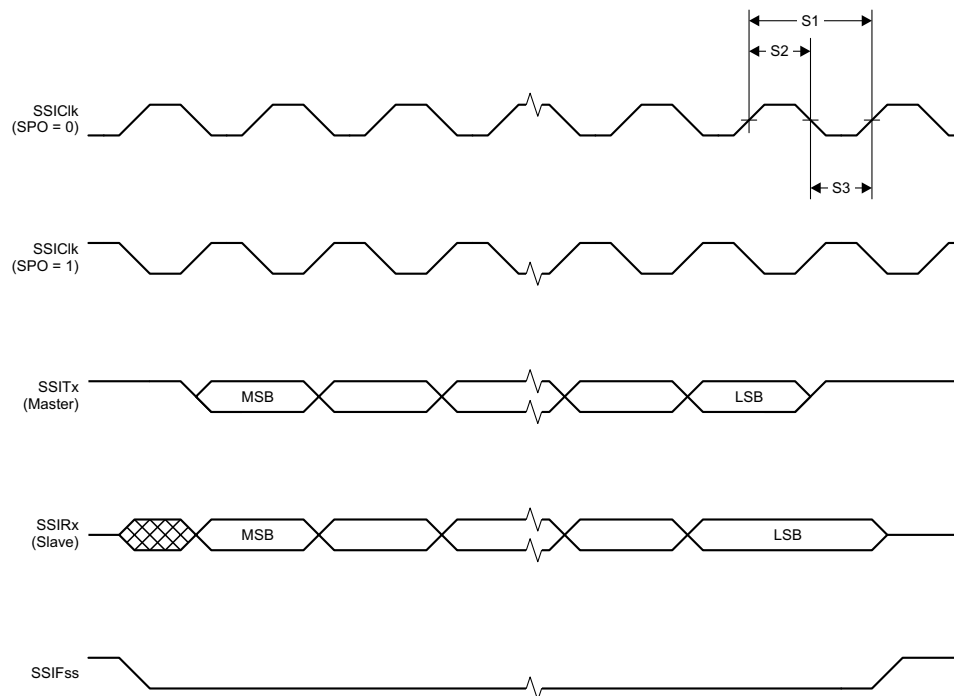


Figure 7-1. SSI Timing for TI Frame Format (FRF = 01), Single Transfer Timing Measurement



**Figure 7-2. SSI Timing for MICROWIRE Frame Format (FRF = 10), Single Transfer**



**Figure 7-3. SSI Timing for SPI Frame Format (FRF = 00), With SPH = 1**

## 7.14.5 UART

### 7.14.5.1 UART Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER	MIN	TYP	MAX	UNIT
UART rate			2.89	MBaud

## 7.15 Peripheral Characteristics

### 7.15.1 ADC

#### 7.15.1.1 Analog-to-Digital Converter (ADC) Characteristics

$T_c = 25^\circ\text{C}$ ,  $V_{\text{DDS}} = 3.0\text{ V}$  and voltage scaling enabled, unless otherwise noted.<sup>(1)</sup>

Performance numbers require use of offset and gain adjustments in software by TI-provided ADC drivers.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Input voltage range		0		V <sub>DDS</sub>	V
	Resolution			12		Bits
	Sample Rate				200	ksps
	Offset	Internal 4.3 V equivalent reference <sup>(2)</sup>		±2		LSB
	Gain error	Internal 4.3 V equivalent reference <sup>(2)</sup>		±7		LSB
DNL <sup>(4)</sup>	Differential nonlinearity			>−1		LSB
INL	Integral nonlinearity			±4		LSB
ENOB	Effective number of bits	Internal 4.3 V equivalent reference <sup>(2)</sup> , 200 kSamples/s, 9.6 kHz input tone		9.8		Bits
		Internal 4.3 V equivalent reference <sup>(2)</sup> , 200 kSamples/s, 9.6 kHz input tone, DC/DC enabled		9.8		
		V <sub>DDS</sub> as reference, 200 kSamples/s, 9.6 kHz input tone		10.1		
		Internal reference, voltage scaling disabled, 32 samples average, 200 kSamples/s, 300 Hz input tone		11.1		
		Internal reference, voltage scaling disabled, 14-bit mode, 200 kSamples/s, 600 Hz input tone <sup>(5)</sup>		11.3		
		Internal reference, voltage scaling disabled, 15-bit mode, 200 kSamples/s, 150 Hz input tone <sup>(5)</sup>		11.6		
THD	Total harmonic distortion	Internal 4.3 V equivalent reference <sup>(2)</sup> , 200 kSamples/s, 9.6 kHz input tone		−65		dB
		V <sub>DDS</sub> as reference, 200 kSamples/s, 9.6 kHz input tone		−70		
		Internal reference, voltage scaling disabled, 32 samples average, 200 kSamples/s, 300 Hz input tone		−72		
SINAD, SNDR	Signal-to-noise and distortion ratio	Internal 4.3 V equivalent reference <sup>(2)</sup> , 200 kSamples/s, 9.6 kHz input tone		60		dB
		V <sub>DDS</sub> as reference, 200 kSamples/s, 9.6 kHz input tone		63		
		Internal reference, voltage scaling disabled, 32 samples average, 200 kSamples/s, 300 Hz input tone		68		
SFDR	Spurious-free dynamic range	Internal 4.3 V equivalent reference <sup>(2)</sup> , 200 kSamples/s, 9.6 kHz input tone		70		dB
		V <sub>DDS</sub> as reference, 200 kSamples/s, 9.6 kHz input tone		73		
		Internal reference, voltage scaling disabled, 32 samples average, 200 kSamples/s, 300 Hz input tone		75		
	Conversion time	Serial conversion, time-to-output, 24 MHz clock		50		Clock Cycles
	Current consumption	Internal 4.3 V equivalent reference <sup>(2)</sup>		0.40		mA
	Current consumption	V <sub>DDS</sub> as reference		0.57		mA
	Reference voltage	Equivalent fixed internal reference (input voltage scaling enabled). For best accuracy, the ADC conversion should be initiated through the TI-RTOS API in order to include the gain/offset compensation factors stored in FCFG1		4.3 <sup>(2)</sup> <sup>(3)</sup>		V
	Reference voltage	Fixed internal reference (input voltage scaling disabled). For best accuracy, the ADC conversion should be initiated through the TI-RTOS API in order to include the gain/offset compensation factors stored in FCFG1. This value is derived from the scaled value (4.3 V) as follows: $V_{\text{ref}} = 4.3\text{ V} \times 1408 / 4095$		1.48		V
	Reference voltage	V <sub>DDS</sub> as reference, input voltage scaling enabled		V <sub>DDS</sub>		V
	Reference voltage	V <sub>DDS</sub> as reference, input voltage scaling disabled		V <sub>DDS</sub> / 2.82 <sup>(3)</sup>		V

### 7.15.1.1 Analog-to-Digital Converter (ADC) Characteristics (continued)

$T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$  and voltage scaling enabled, unless otherwise noted.<sup>(1)</sup>

Performance numbers require use of offset and gain adjustments in software by TI-provided ADC drivers.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input impedance	200 kSamples/s, voltage scaling enabled. Capacitive input, Input impedance depends on sampling frequency and sampling time		>1		MΩ

- (1) Using IEEE Std 1241-2010 for terminology and test methods
- (2) Input signal scaled down internally before conversion, as if voltage range was 0 to 4.3 V
- (3) Applied voltage must be within [Absolute Maximum Ratings](#) at all times
- (4) No missing codes
- (5)  $\text{ADC\_output} = \sum(4^n \text{ samples}) \gg n$ ,  $n$  = desired extra bits

## 7.15.2 DAC

### 7.15.2.1 Digital-to-Analog Converter (DAC) Characteristics

$T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
General Parameters						
	Resolution		8			Bits
V <sub>DDS</sub>	Supply voltage	Any load, any V <sub>REF</sub> , pre-charge OFF, DAC charge-pump ON	1.8		3.8	V
		External Load <sup>(4)</sup> , any V <sub>REF</sub> , pre-charge OFF, DAC charge-pump OFF	2.0		3.8	
		Any load, V <sub>REF</sub> = DCOUPL, pre-charge ON	2.6		3.8	
F <sub>DAC</sub>	Clock frequency	Buffer ON (recommended for external load)	16		250	kHz
		Buffer OFF (internal load)	16		1000	
	Voltage output settling time	V <sub>REF</sub> = V <sub>DDS</sub> , buffer OFF, internal load		13		1 / F <sub>DAC</sub>
		V <sub>REF</sub> = V <sub>DDS</sub> , buffer ON, external capacitive load = 20 pF <sup>(3)</sup>		13.8		
	External capacitive load			20	200	pF
	External resistive load		10			MΩ
	Short circuit current				400	μA
Z <sub>MAX</sub>	Max output impedance Vref = V <sub>DDS</sub> , buffer ON, CLK 250 kHz	V <sub>DDS</sub> = 3.8 V, DAC charge-pump OFF		50.8		kΩ
		V <sub>DDS</sub> = 3.0 V, DAC charge-pump ON		51.7		
		V <sub>DDS</sub> = 3.0 V, DAC charge-pump OFF		53.2		
		V <sub>DDS</sub> = 2.0 V, DAC charge-pump ON		48.7		
		V <sub>DDS</sub> = 2.0 V, DAC charge-pump OFF		70.2		
		V <sub>DDS</sub> = 1.8 V, DAC charge-pump ON		46.3		
		V <sub>DDS</sub> = 1.8 V, DAC charge-pump OFF		88.9		
Internal Load - Continuous Time Comparator / Low Power Clocked Comparator						
DNL	Differential nonlinearity	V <sub>REF</sub> = V <sub>DDS</sub> , load = Continuous Time Comparator or Low Power Clocked Comparator F <sub>DAC</sub> = 250 kHz		±1		LSB <sup>(1)</sup>
	Differential nonlinearity	V <sub>REF</sub> = V <sub>DDS</sub> , load = Continuous Time Comparator or Low Power Clocked Comparator F <sub>DAC</sub> = 16 kHz		±1.2		
	Offset error <sup>(2)</sup> Load = Continuous Time Comparator	V <sub>REF</sub> = V <sub>DDS</sub> = 3.8 V		±0.64		LSB <sup>(1)</sup>
V <sub>REF</sub> = V <sub>DDS</sub> = 3.0 V			±0.81			
V <sub>REF</sub> = V <sub>DDS</sub> = 1.8 V			±1.27			
V <sub>REF</sub> = DCOUPL, pre-charge ON			±3.43			
V <sub>REF</sub> = DCOUPL, pre-charge OFF			±2.88			
V <sub>REF</sub> = ADCREF			±2.37			



### 7.15.2.1 Digital-to-Analog Converter (DAC) Characteristics (continued)

T<sub>c</sub> = 25 °C, V<sub>DD</sub>S = 3.0 V, unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Offset error <sup>(2)</sup> Load = Low Power Clocked Comparator	V <sub>REF</sub> = V <sub>DD</sub> S = 3.8 V		±0.78		LSB <sup>(1)</sup>
		V <sub>REF</sub> = V <sub>DD</sub> S = 3.0 V		±0.77		
		V <sub>REF</sub> = V <sub>DD</sub> S = 1.8 V		±3.46		
		V <sub>REF</sub> = DCOUPL, pre-charge ON		±3.44		
		V <sub>REF</sub> = DCOUPL, pre-charge OFF		±4.70		
		V <sub>REF</sub> = ADCREF		±4.11		
	Max code output voltage variation <sup>(2)</sup> Load = Continuous Time Comparator	V <sub>REF</sub> = V <sub>DD</sub> S = 3.8 V		±1.53		LSB <sup>(1)</sup>
		V <sub>REF</sub> = V <sub>DD</sub> S = 3.0 V		±1.71		
		V <sub>REF</sub> = V <sub>DD</sub> S = 1.8 V		±2.10		
		V <sub>REF</sub> = DCOUPL, pre-charge ON		±6.00		
		V <sub>REF</sub> = DCOUPL, pre-charge OFF		±3.85		
		V <sub>REF</sub> = ADCREF		±5.84		
	Max code output voltage variation <sup>(2)</sup> Load = Low Power Clocked Comparator	V <sub>REF</sub> = V <sub>DD</sub> S = 3.8 V		±2.92		LSB <sup>(1)</sup>
		V <sub>REF</sub> = V <sub>DD</sub> S = 3.0 V		±3.06		
		V <sub>REF</sub> = V <sub>DD</sub> S = 1.8 V		±3.91		
		V <sub>REF</sub> = DCOUPL, pre-charge ON		±7.84		
		V <sub>REF</sub> = DCOUPL, pre-charge OFF		±4.06		
		V <sub>REF</sub> = ADCREF		±6.94		
	Output voltage range <sup>(2)</sup> Load = Continuous Time Comparator	V <sub>REF</sub> = V <sub>DD</sub> S = 3.8 V, code 1		0.03		V
		V <sub>REF</sub> = V <sub>DD</sub> S = 3.8 V, code 255		3.62		
		V <sub>REF</sub> = V <sub>DD</sub> S = 3.0 V, code 1		0.02		
		V <sub>REF</sub> = V <sub>DD</sub> S = 3.0 V, code 255		2.86		
		V <sub>REF</sub> = V <sub>DD</sub> S = 1.8 V, code 1		0.01		
		V <sub>REF</sub> = V <sub>DD</sub> S = 1.8 V, code 255		1.71		
		V <sub>REF</sub> = DCOUPL, pre-charge OFF, code 1		0.01		
		V <sub>REF</sub> = DCOUPL, pre-charge OFF, code 255		1.21		
		V <sub>REF</sub> = DCOUPL, pre-charge ON, code 1		1.27		
		V <sub>REF</sub> = DCOUPL, pre-charge ON, code 255		2.46		
		V <sub>REF</sub> = ADCREF, code 1		0.01		
		V <sub>REF</sub> = ADCREF, code 255		1.41		
	Output voltage range <sup>(2)</sup> Load = Low Power Clocked Comparator	V <sub>REF</sub> = V <sub>DD</sub> S = 3.8 V, code 1		0.03		V
		V <sub>REF</sub> = V <sub>DD</sub> S = 3.8 V, code 255		3.61		
		V <sub>REF</sub> = V <sub>DD</sub> S = 3.0 V, code 1		0.02		
		V <sub>REF</sub> = V <sub>DD</sub> S = 3.0 V, code 255		2.85		
		V <sub>REF</sub> = V <sub>DD</sub> S = 1.8 V, code 1		0.01		
		V <sub>REF</sub> = V <sub>DD</sub> S = 1.8 V, code 255		1.71		
		V <sub>REF</sub> = DCOUPL, pre-charge OFF, code 1		0.01		
		V <sub>REF</sub> = DCOUPL, pre-charge OFF, code 255		1.21		
		V <sub>REF</sub> = DCOUPL, pre-charge ON, code 1		1.27		
		V <sub>REF</sub> = DCOUPL, pre-charge ON, code 255		2.46		
		V <sub>REF</sub> = ADCREF, code 1		0.01		
		V <sub>REF</sub> = ADCREF, code 255		1.41		
		External Load				
INL	Integral nonlinearity	V <sub>REF</sub> = V <sub>DD</sub> S, F <sub>DAC</sub> = 250 kHz		±1		LSB <sup>(1)</sup>
		V <sub>REF</sub> = DCOUPL, F <sub>DAC</sub> = 250 kHz		±2		
		V <sub>REF</sub> = ADCREF, F <sub>DAC</sub> = 250 kHz		±1		
DNL	Differential nonlinearity	V <sub>REF</sub> = V <sub>DD</sub> S, F <sub>DAC</sub> = 250 kHz		±1		LSB <sup>(1)</sup>

### 7.15.2.1 Digital-to-Analog Converter (DAC) Characteristics (continued)

$T_c = 25^\circ\text{C}$ ,  $V_{\text{DDS}} = 3.0\text{ V}$ , unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Offset error	$V_{\text{REF}} = V_{\text{DDS}} = 3.8\text{ V}$		$\pm 0.40$		LSB <sup>(1)</sup>
	$V_{\text{REF}} = V_{\text{DDS}} = 3.0\text{ V}$		$\pm 0.50$		
	$V_{\text{REF}} = V_{\text{DDS}} = 1.8\text{ V}$		$\pm 0.75$		
	$V_{\text{REF}} = \text{DCOUP}, \text{pre-charge ON}$		$\pm 1.55$		
	$V_{\text{REF}} = \text{DCOUP}, \text{pre-charge OFF}$		$\pm 1.30$		
	$V_{\text{REF}} = \text{ADCREF}$		$\pm 1.10$		
Max code output voltage variation	$V_{\text{REF}} = V_{\text{DDS}} = 3.8\text{ V}$		$\pm 1.00$		LSB <sup>(1)</sup>
	$V_{\text{REF}} = V_{\text{DDS}} = 3.0\text{ V}$		$\pm 1.00$		
	$V_{\text{REF}} = V_{\text{DDS}} = 1.8\text{ V}$		$\pm 1.00$		
	$V_{\text{REF}} = \text{DCOUP}, \text{pre-charge ON}$		$\pm 3.45$		
	$V_{\text{REF}} = \text{DCOUP}, \text{pre-charge OFF}$		$\pm 2.10$		
	$V_{\text{REF}} = \text{ADCREF}$		$\pm 1.90$		
Output voltage range Load = Low Power Clocked Comparator	$V_{\text{REF}} = V_{\text{DDS}} = 3.8\text{ V}$ , code 1		0.03		V
	$V_{\text{REF}} = V_{\text{DDS}} = 3.8\text{ V}$ , code 255		3.61		
	$V_{\text{REF}} = V_{\text{DDS}} = 3.0\text{ V}$ , code 1		0.02		
	$V_{\text{REF}} = V_{\text{DDS}} = 3.0\text{ V}$ , code 255		2.85		
	$V_{\text{REF}} = V_{\text{DDS}} = 1.8\text{ V}$ , code 1		0.02		
	$V_{\text{REF}} = V_{\text{DDS}} = 1.8\text{ V}$ , code 255		1.71		
	$V_{\text{REF}} = \text{DCOUP}, \text{pre-charge OFF}$ , code 1		0.02		
	$V_{\text{REF}} = \text{DCOUP}, \text{pre-charge OFF}$ , code 255		1.20		
	$V_{\text{REF}} = \text{DCOUP}, \text{pre-charge ON}$ , code 1		1.27		
	$V_{\text{REF}} = \text{DCOUP}, \text{pre-charge ON}$ , code 255		2.46		
	$V_{\text{REF}} = \text{ADCREF}$ , code 1		0.02		
	$V_{\text{REF}} = \text{ADCREF}$ , code 255		1.42		

(1) 1 LSB ( $V_{\text{REF}} = 3.8\text{ V}/3.0\text{ V}/1.8\text{ V}/\text{DCOUP}/\text{ADCREF}$ ) = 14.10 mV/11.13 mV/6.68 mV/4.67 mV/5.48 mV

(2) Includes comparator offset

(3) A load > 20 pF will increase the settling time

(4) Keysight 34401A Multimeter

## 7.15.3 Temperature and Battery Monitor

### 7.15.3.1 Temperature Sensor

Measured on a Texas Instruments reference design with  $T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Resolution			2		$^\circ\text{C}$
Accuracy	$-40^\circ\text{C}$ to $0^\circ\text{C}$		$\pm 4.0$		$^\circ\text{C}$
Accuracy	$0^\circ\text{C}$ to $105^\circ\text{C}$		$\pm 2.5$		$^\circ\text{C}$
Supply voltage coefficient <sup>(1)</sup>			3.6		$^\circ\text{C/V}$

(1) The temperature sensor is automatically compensated for  $V_{DD5}$  variation when using the TI-provided temperature driver.

### 7.15.3.2 Battery Monitor

Measured on a Texas Instruments reference design with  $T_c = 25^\circ\text{C}$ , unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Resolution			25		mV
Range		1.8		3.8	V
Integral nonlinearity (max)			23		mV
Accuracy	$V_{DD5} = 3.0\text{ V}$		22.5		mV
Offset error			-32		mV
Gain error			-1		%

## 7.15.4 Comparators

### 7.15.4.1 Low-Power Clocked Comparator

$T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input voltage range		0		$V_{DD5}$	V
Clock frequency			SCLK_LF		
Internal reference voltage <sup>(1)</sup>	Using internal DAC with $V_{DD5}$ as reference voltage, DAC code = 0 - 255		0.024 - 2.865		V
Offset	Measured at $V_{DD5} / 2$ , includes error from internal DAC		$\pm 5$		mV
Decision time	Step from $-50\text{ mV}$ to $50\text{ mV}$		1		Clock Cycle

(1) The comparator can use an internal 8 bits DAC as its reference. The DAC output voltage range depends on the reference voltage selected. See [#none#](#)

### 7.15.4.2 Continuous Time Comparator

$T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input voltage range <sup>(1)</sup>		0		$V_{DD5}$	V
Offset	Measured at $V_{DD5} / 2$		$\pm 5$		mV
Decision time	Step from $-10\text{ mV}$ to $10\text{ mV}$		0.70		$\mu\text{s}$
Current consumption	Internal reference		8.0		$\mu\text{A}$

(1) The input voltages can be generated externally and connected throughout I/Os or an internal reference voltage can be generated using the DAC

## 7.15.5 Current Source

### 7.15.5.1 Programmable Current Source

$T_c = 25^\circ\text{C}$ ,  $V_{DD5} = 3.0\text{ V}$ , unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Current source programmable output range (logarithmic range)			0.25 - 20		$\mu\text{A}$
Resolution			0.25		$\mu\text{A}$

## 7.15.6 GPIO

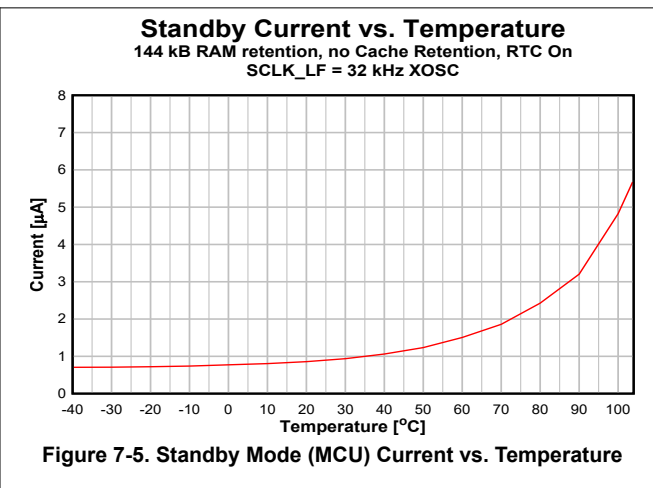
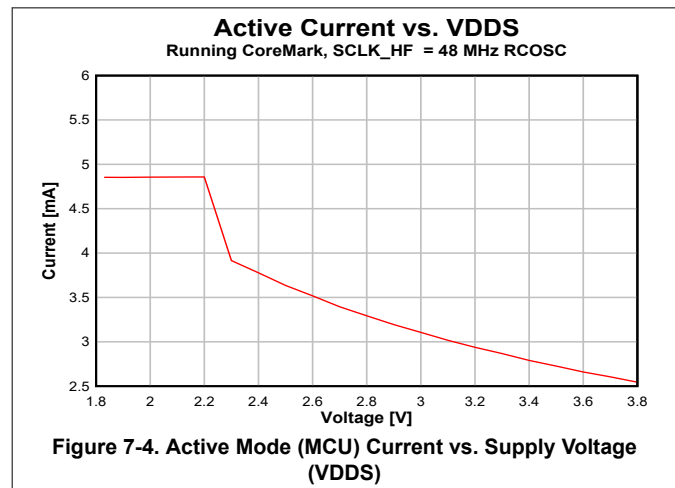
### 7.15.6.1 GPIO DC Characteristics

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b><math>T_A = 25^\circ\text{C}</math>, <math>V_{DD5} = 1.8\text{ V}</math></b>					
GPIO VOH at 8 mA load	IOCURR = 2, high-drive GPIOs only		1.56		V
GPIO VOL at 8 mA load	IOCURR = 2, high-drive GPIOs only		0.24		V
GPIO VOH at 4 mA load	IOCURR = 1		1.59		V
GPIO VOL at 4 mA load	IOCURR = 1		0.21		V
GPIO pullup current	Input mode, pullup enabled, $V_{pad} = 0\text{ V}$		73		$\mu\text{A}$
GPIO pulldown current	Input mode, pulldown enabled, $V_{pad} = V_{DD5}$		19		$\mu\text{A}$
GPIO low-to-high input transition, with hysteresis	IH = 1, transition voltage for input read as 0 $\rightarrow$ 1		1.08		V
GPIO high-to-low input transition, with hysteresis	IH = 1, transition voltage for input read as 1 $\rightarrow$ 0		0.73		V
GPIO input hysteresis	IH = 1, difference between 0 $\rightarrow$ 1 and 1 $\rightarrow$ 0 points		0.35		V
<b><math>T_A = 25^\circ\text{C}</math>, <math>V_{DD5} = 3.0\text{ V}</math></b>					
GPIO VOH at 8 mA load	IOCURR = 2, high-drive GPIOs only		2.59		V
GPIO VOL at 8 mA load	IOCURR = 2, high-drive GPIOs only		0.42		V
GPIO VOH at 4 mA load	IOCURR = 1		2.63		V
GPIO VOL at 4 mA load	IOCURR = 1		0.40		V
<b><math>T_A = 25^\circ\text{C}</math>, <math>V_{DD5} = 3.8\text{ V}</math></b>					
GPIO pullup current	Input mode, pullup enabled, $V_{pad} = 0\text{ V}$		282		$\mu\text{A}$
GPIO pulldown current	Input mode, pulldown enabled, $V_{pad} = V_{DD5}$		110		$\mu\text{A}$
GPIO low-to-high input transition, with hysteresis	IH = 1, transition voltage for input read as 0 $\rightarrow$ 1		1.97		V
GPIO high-to-low input transition, with hysteresis	IH = 1, transition voltage for input read as 1 $\rightarrow$ 0		1.55		V
GPIO input hysteresis	IH = 1, difference between 0 $\rightarrow$ 1 and 1 $\rightarrow$ 0 points		0.42		V
<b><math>T_A = 25^\circ\text{C}</math></b>					
VIH	Lowest GPIO input voltage reliably interpreted as a <i>High</i>	$0.8 \cdot V_{DD5}$			V
VIL	Highest GPIO input voltage reliably interpreted as a <i>Low</i>	$0.2 \cdot V_{DD5}$			V

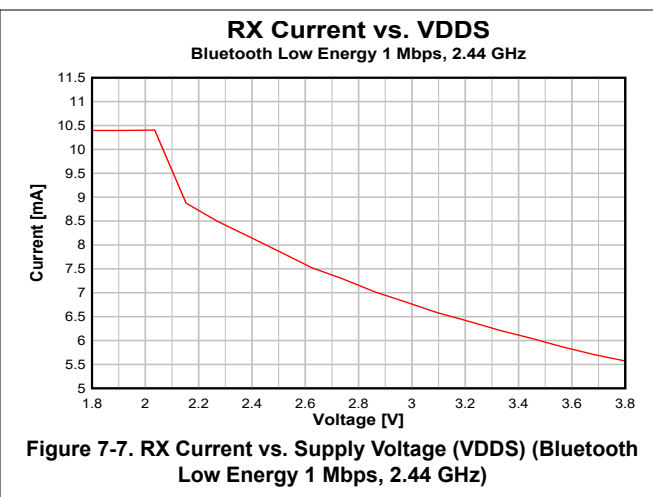
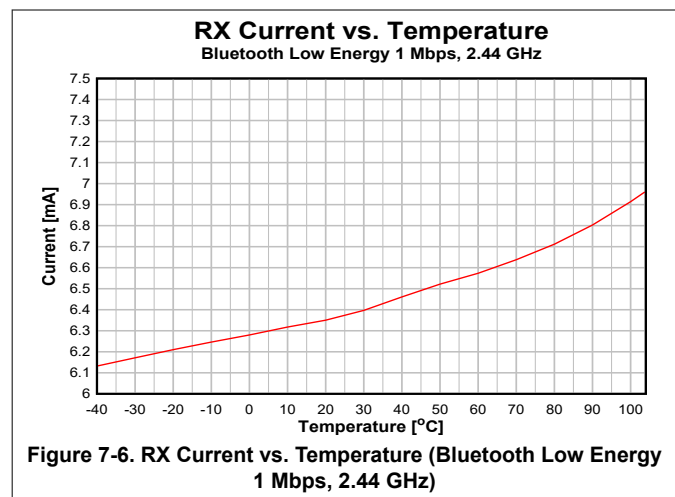
## 7.16 Typical Characteristics

All measurements in this section are done with  $T_c = 25\text{ }^\circ\text{C}$  and  $V_{DDS} = 3.0\text{ V}$ , unless otherwise noted. See [Section 7.3](#) for device limits. Values exceeding these limits are for reference only.

### 7.16.1 MCU Current



### 7.16.2 RX Current



### 7.16.3 TX Current

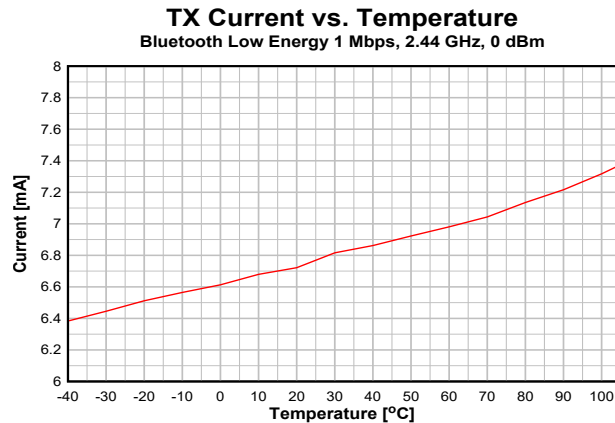


Figure 7-8. TX Current vs. Temperature (Bluetooth Low Energy 1 Mbps, 2.44 GHz)

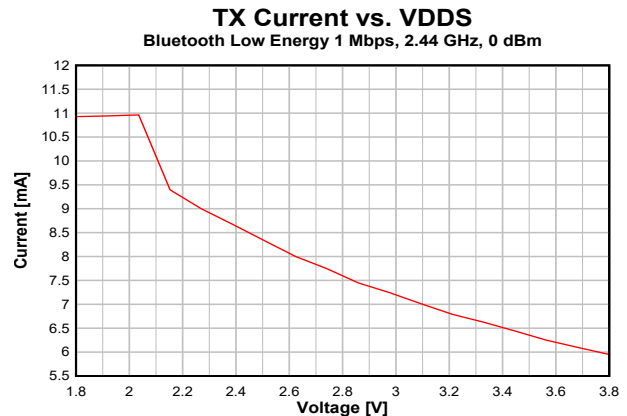


Figure 7-9. TX Current vs. Supply Voltage (VDD5) (Bluetooth Low Energy 1 Mbps, 2.44 GHz)

**Table 7-1. Typical TX Current and Output Power**

CC2652R at 2.4 GHz, VDD5 = 3.0 V <sup>(1)</sup> (Measured on CC2652-R7EM-7ID)

txPower	TX Power Setting (SmartRF Studio)	Typical Output Power [dBm]	Typical Current Consumption [mA]
0x701F	5	4.8	10
0x3A17	4	3.8	9
0x3A64	3	2.7	8
0x325F	2	1.7	8
0x2C5C	1	1.0	8
0x2659	0	0.1	7
0x1697	-3	-2.8	7
0x1693	-5	-4.8	6
0x1292	-6	-5.4	6
0x0CD3	-9	-8.9	5
0x0AD1	-10	-10.2	5
0x0ACF	-12	-11.8	5
0x06CD	-15	-13.7	5
0x06CA	-18	-16.9	5
0x04C8	-20	-19.6	5

(1) Internal regulated voltage powers the PA, therefore the output power is not affected by variation in VDD5 voltage.

## 7.16.4 RX Performance

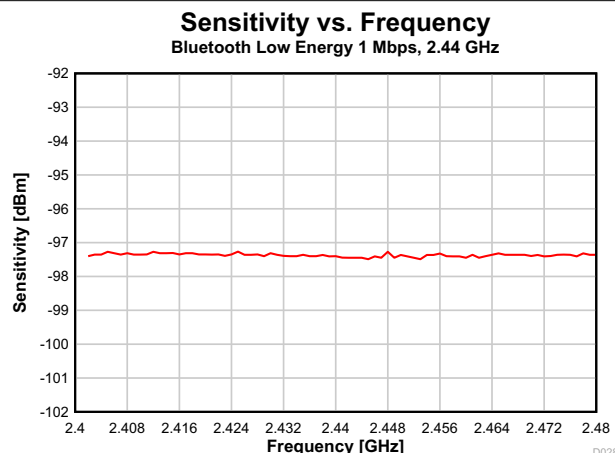


Figure 7-10. Sensitivity vs. Frequency (Bluetooth Low Energy 1 Mbps, 2.44 GHz)

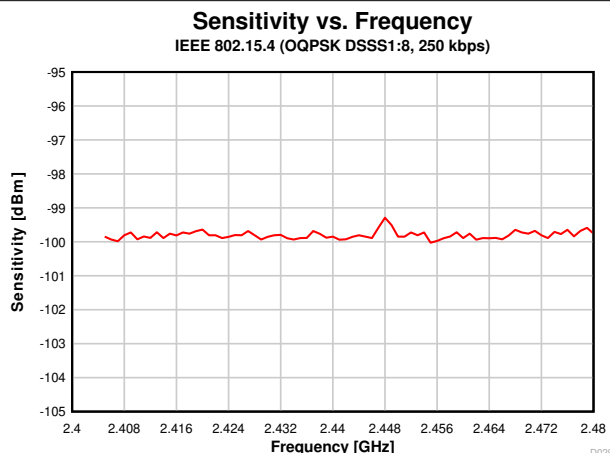


Figure 7-11. Sensitivity vs. Frequency (250 kbps, 2.44 GHz)

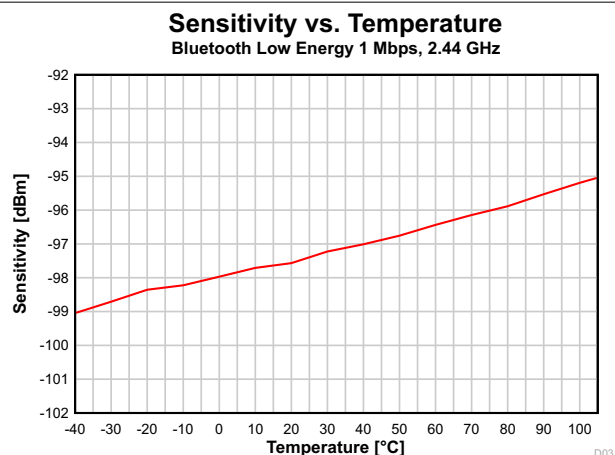


Figure 7-12. Sensitivity vs. Temperature (Bluetooth Low Energy 1 Mbps, 2.44 GHz)

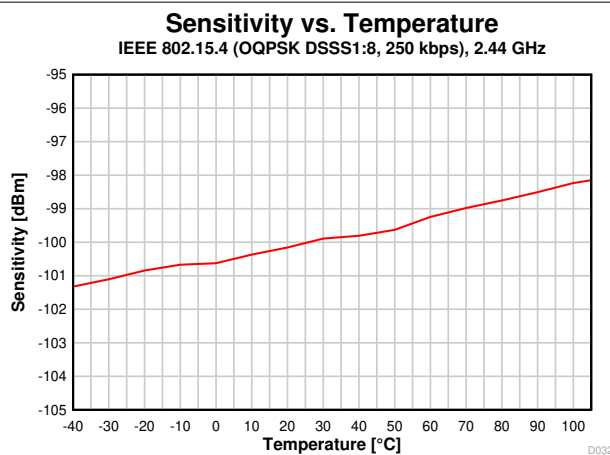


Figure 7-13. Sensitivity vs. Temperature (250 kbps, 2.44 GHz)

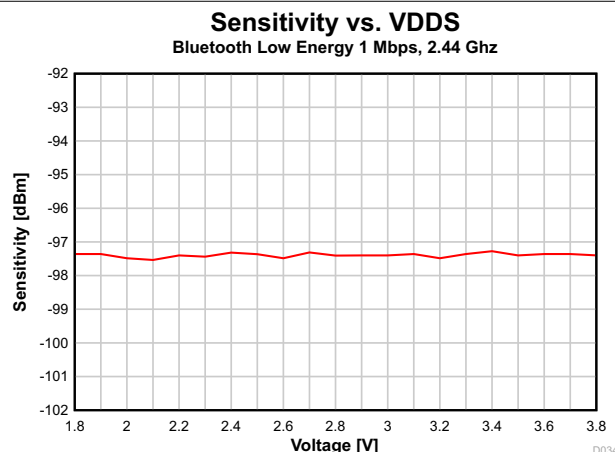


Figure 7-14. Sensitivity vs. Supply Voltage (VDD) (Bluetooth Low Energy 1 Mbps, 2.44 GHz)

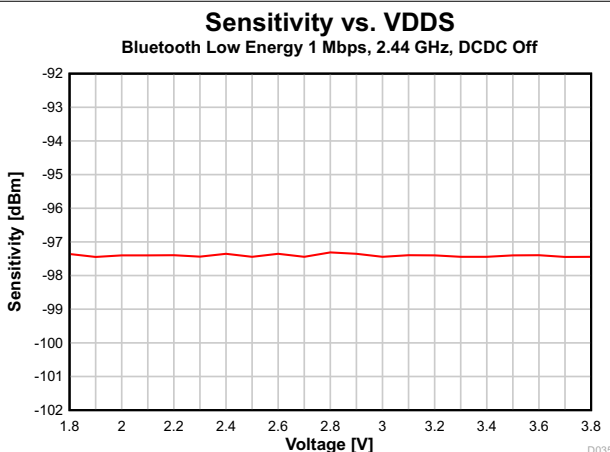
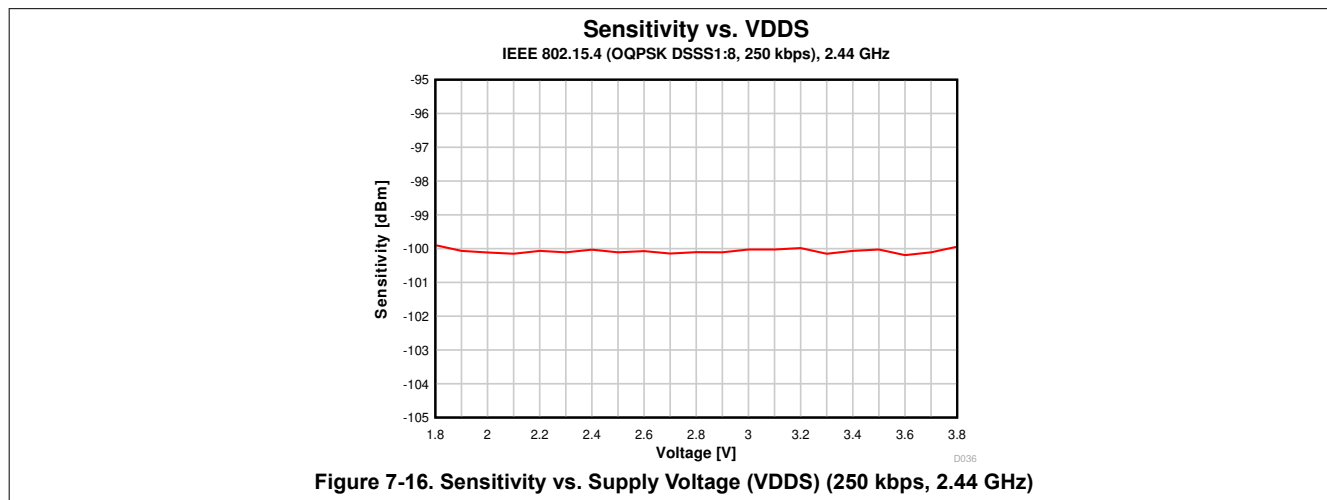


Figure 7-15. Sensitivity vs. Supply Voltage (VDD) (Bluetooth Low Energy 1 Mbps, 2.44 GHz, DCDC Off)

## 7.16.4 RX Performance (continued)





## 7.16.5 TX Performance

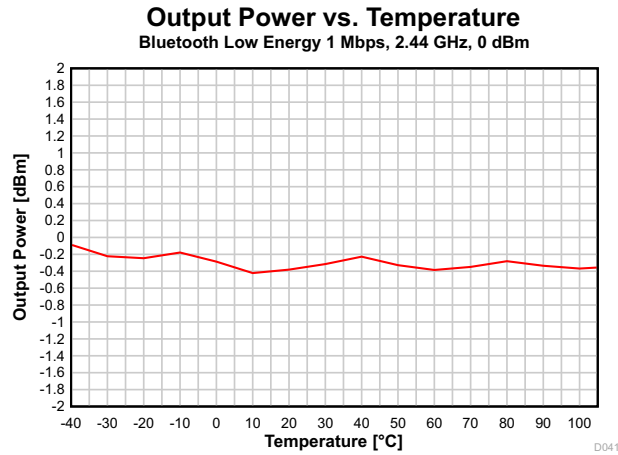


Figure 7-17. Output Power vs. Temperature (Bluetooth Low Energy 1 Mbps, 2.44 GHz)

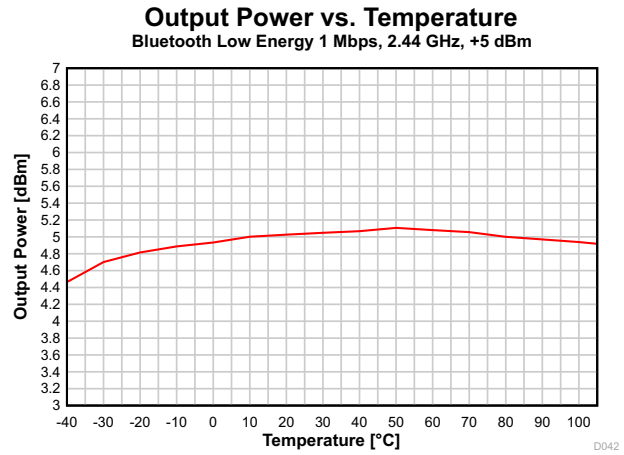


Figure 7-18. Output Power vs. Temperature (Bluetooth Low Energy 1 Mbps, 2.44 GHz, +5 dBm)

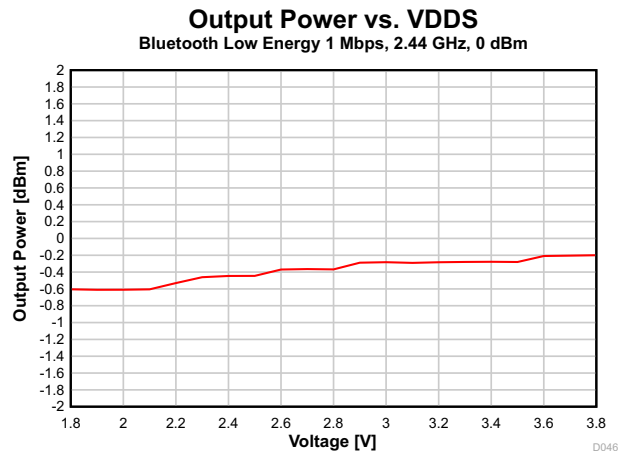


Figure 7-19. Output Power vs. Supply Voltage (VDD5) (Bluetooth Low Energy 1 Mbps, 2.44 GHz)

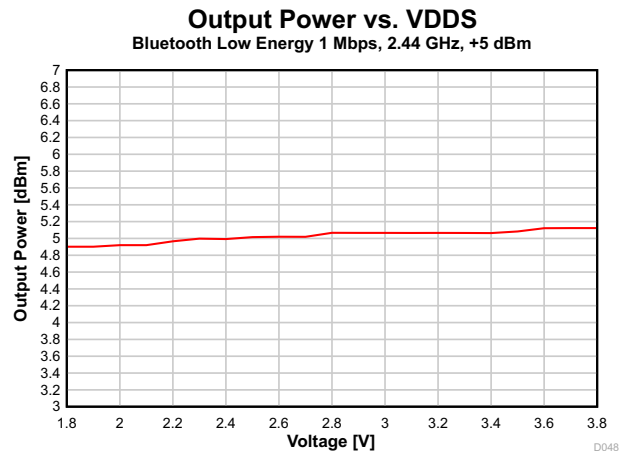


Figure 7-20. Output Power vs. Supply Voltage (VDD5) (Bluetooth Low Energy 1 Mbps, 2.44 GHz, +5 dBm)

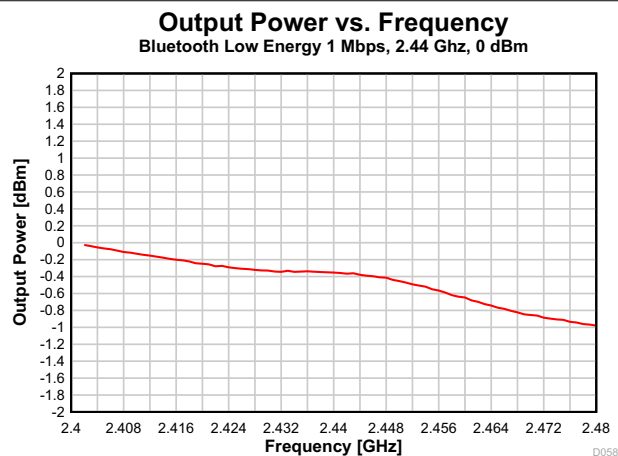


Figure 7-21. Output Power vs. Frequency (Bluetooth Low Energy 1 Mbps, 2.44 GHz)

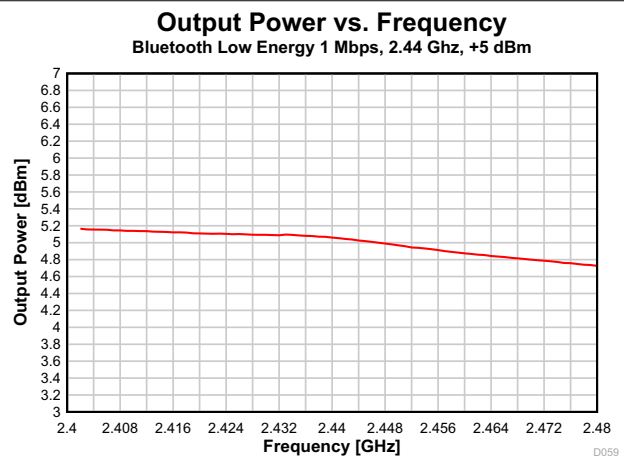


Figure 7-22. Output Power vs. Frequency (Bluetooth Low Energy 1 Mbps, 2.44 GHz, +5 dBm)

## 7.16.6 ADC Performance

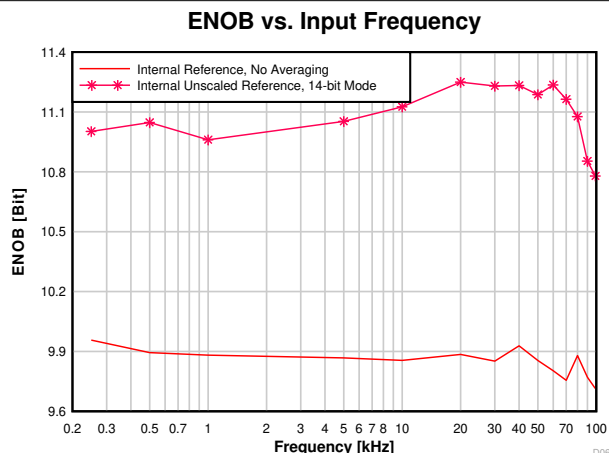


Figure 7-23. ENOB vs. Input Frequency

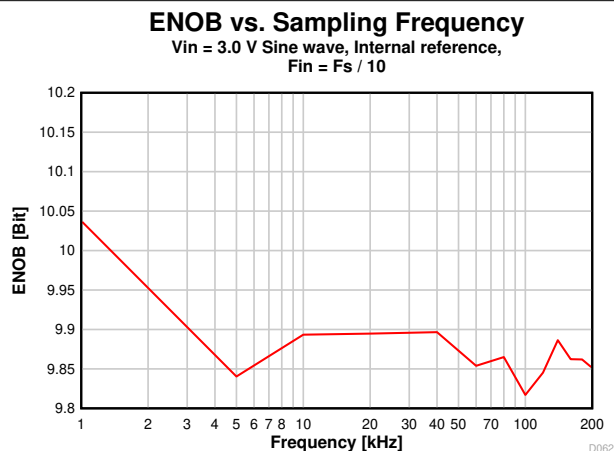


Figure 7-24. ENOB vs. Sampling Frequency

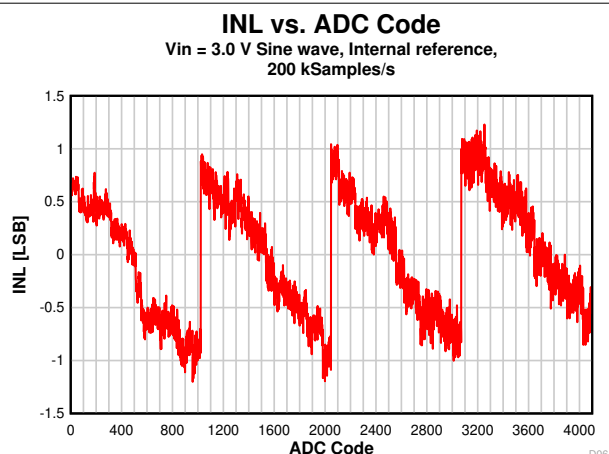


Figure 7-25. INL vs. ADC Code

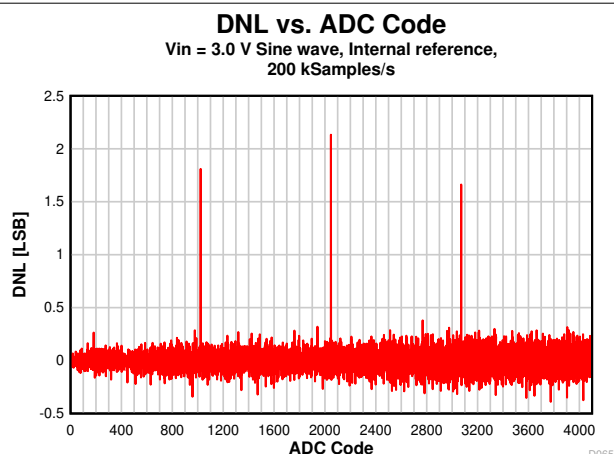


Figure 7-26. DNL vs. ADC Code

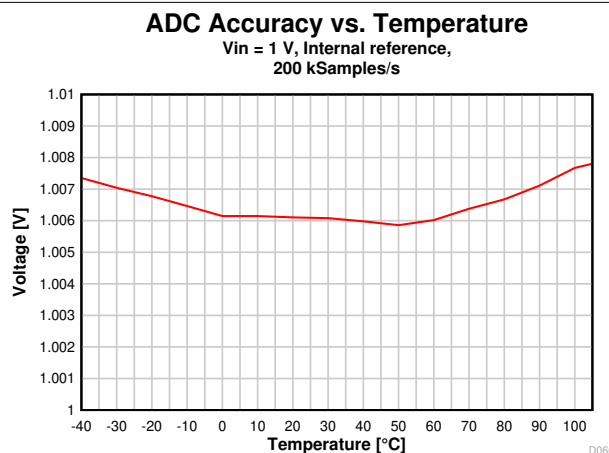


Figure 7-27. ADC Accuracy vs. Temperature

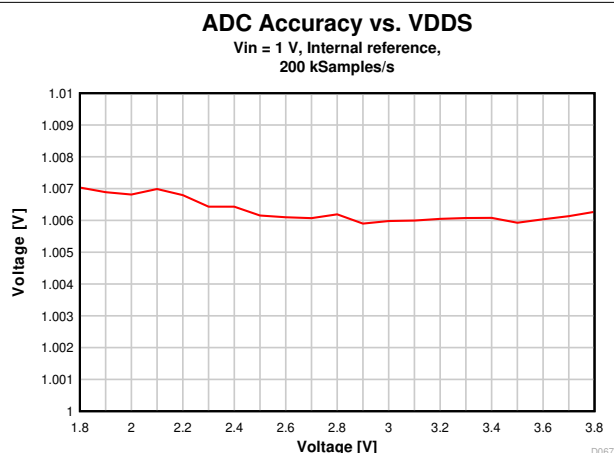


Figure 7-28. ADC Accuracy vs. Supply Voltage (VDD)

## 8 Detailed Description

### 8.1 Overview

[Section 3.1](#) shows the core modules of the CC2652R7 device.

### 8.2 System CPU

The CC2652R7 SimpleLink™ Wireless MCU contains an Arm® Cortex®-M4F system CPU, which runs the application and the higher layers of radio protocol stacks.

The system CPU is the foundation of a high-performance, low-cost platform that meets the system requirements of minimal memory implementation, and low-power consumption, while delivering outstanding computational performance and exceptional system response to interrupts.

Its features include the following:

- ARMv7-M architecture optimized for small-footprint embedded applications
- Arm Thumb®-2 mixed 16- and 32-bit instruction set delivers the high performance expected of a 32-bit Arm core in a compact memory size
- Fast code execution permits increased sleep mode time
- Deterministic, high-performance interrupt handling for time-critical applications
- Single-cycle multiply instruction and hardware divide
- Hardware division and fast digital-signal-processing oriented multiply accumulate
- Saturating arithmetic for signal processing
- IEEE 754-compliant single-precision Floating Point Unit (FPU)
- Memory Protection Unit (MPU) for safety-critical applications
- Full debug with data matching for watchpoint generation
  - Data Watchpoint and Trace Unit (DWT)
  - JTAG Debug Access Port (DAP)
  - Flash Patch and Breakpoint Unit (FPB)
- Trace support reduces the number of pins required for debugging and tracing
  - Instrumentation Trace Macrocell Unit (ITM)
  - Trace Port Interface Unit (TPIU) with asynchronous serial wire output (SWO)
- Optimized for single-cycle flash memory access
- Tightly connected to 8-KB 4-way random replacement cache for minimal active power consumption and wait states
- Ultra-low-power consumption with integrated sleep modes
- 48 MHz operation
- 1.25 DMIPS per MHz

## 8.3 Radio (RF Core)

The RF Core is a highly flexible and future proof radio module which contains an Arm Cortex-M0 processor that interfaces the analog RF and base-band circuitry, handles data to and from the system CPU side, and assembles the information bits in a given packet structure. The RF core offers a high level, command-based API to the main CPU that configurations and data are passed through. The Arm Cortex-M0 processor is not programmable by customers and is interfaced through the TI-provided RF driver that is included with the SimpleLink Software Development Kit (SDK).

The RF core can autonomously handle the time-critical aspects of the radio protocols, thus offloading the main CPU, which reduces power and leaves more resources for the user application. Several signals are also available to control external circuitry such as RF switches or range extenders autonomously.

Multiprotocol solutions are enabled through time-sliced access of the radio, handled transparently for the application through the TI-provided RF driver and dual-mode manager.

The various physical layer radio formats are partly built as a software defined radio where the radio behavior is either defined by radio ROM contents or by non-ROM radio formats delivered in form of firmware patches with the SimpleLink SDKs. This allows the radio platform to be updated for support of future versions of standards even with over-the-air (OTA) updates while still using the same silicon.

### 8.3.1 Bluetooth 5.2 Low Energy

The RF Core offers full support for Bluetooth 5.2 Low Energy, including the high-speed 2-Mbps physical layer and the 500-kbps and 125-kbps long range PHYs (Coded PHY) through the TI provided Bluetooth 5.2 stack or through a high-level Bluetooth API. The Bluetooth 5.2 PHY and part of the controller are in radio and system ROM, providing significant savings in memory usage and more space available for applications.

The new high-speed mode allows data transfers up to 2 Mbps, twice the speed of Bluetooth 4.2 and five times the speed of Bluetooth 4.0, without increasing power consumption. In addition to faster speeds, this mode offers significant improvements for energy efficiency and wireless coexistence with reduced radio communication time.

Bluetooth 5.2 also enables unparalleled flexibility for adjustment of speed and range based on application needs, which capitalizes on the high-speed or long-range modes respectively. Data transfers are now possible at 2 Mbps, enabling development of applications using voice, audio, imaging, and data logging that were not previously an option using Bluetooth Low Energy. With high-speed mode, existing applications deliver faster responses, richer engagement, and longer battery life. Bluetooth 5.2 enables fast, reliable firmware updates.

### 8.3.2 802.15.4 (Thread, Zigbee, 6LoWPAN)

Through a dedicated IEEE radio API, the RF Core supports the 2.4-GHz IEEE 802.15.4-2011 physical layer (2 Mcps per second Offset-QPSK with DSSS 1:8), used in Thread, Zigbee, and 6LoWPAN protocols. The 802.15.4 PHY and MAC are in radio and system ROM. TI also provides royalty-free protocol stacks for Thread and Zigbee as part of the SimpleLink SDK, enabling a robust end-to-end solution.

## 8.4 Memory

The up to 704KB nonvolatile (flash) memory provides storage for code and data. The flash memory is in-system programmable and erasable. The last flash memory sector must contain a Customer Configuration section (CCFG) that is used by boot ROM and TI provided drivers to configure the device. This configuration is done through the `ccfg.c` source file that is included in all TI provided examples.

The ultra-low leakage system static RAM (SRAM) is split into four 32KB and one 16KB blocks and can be used for both storage of data and execution of code. Retention of SRAM contents in Standby power mode is enabled by default and included in Standby mode power consumption numbers. Parity checking for detection of bit errors in memory is built-in, which reduces chip-level soft errors and thereby increases reliability. System SRAM is always initialized to zeroes upon code execution from boot.

To improve code execution speed and lower power when executing code from nonvolatile memory, a 4-way nonassociative 8-KB cache is enabled by default to cache and prefetch instructions read by the system CPU. The cache can be used as a general-purpose RAM by enabling this feature in the Customer Configuration Area (CCFG).

There is a 4KB ultra-low leakage SRAM available for use with the Sensor Controller Engine which is typically used for storing Sensor Controller programs, data and configuration parameters. This RAM is also accessible by the system CPU. The Sensor Controller RAM is not cleared to zeroes between system resets.

The ROM includes a TI-RTOS kernel and low-level drivers, as well as significant parts of selected radio stacks, which frees up flash memory for the application. The ROM also contains a serial (SPI and UART) bootloader that can be used for initial programming of the device.

## 8.5 Sensor Controller

The Sensor Controller contains circuitry that can be selectively enabled in both Standby and Active power modes. The peripherals in this domain can be controlled by the Sensor Controller Engine, which is a proprietary power-optimized CPU. This CPU can read and monitor sensors or perform other tasks autonomously; thereby significantly reducing power consumption and offloading the system CPU.

The Sensor Controller Engine is user programmable with a simple programming language that has syntax similar to C. This programmability allows for sensor polling and other tasks to be specified as sequential algorithms rather than static configuration of complex peripheral modules, timers, DMA, register programmable state machines, or event routing.

The main advantages are:

- Flexibility - data can be read and processed in unlimited manners while still [ensuring ultra-low power](#)
- 2 MHz low-power mode enables lowest possible handling of digital sensors
- Dynamic reuse of hardware resources
- 40-bit accumulator supporting multiplication, addition and shift
- Observability and debugging options

[Sensor Controller Studio](#) is used to write, test, and debug code for the Sensor Controller. The tool produces C driver source code, which the System CPU application uses to control and exchange data with the Sensor Controller. Typical use cases may be (but are not limited to) the following:

- Read analog sensors using integrated ADC or comparators
- Interface digital sensors using GPIOs, SPI, UART, or I<sup>2</sup>C (UART and I<sup>2</sup>C are bit-banged)
- Capacitive sensing
- Waveform generation
- Very low-power pulse counting (flow metering)
- Key scan

The peripherals in the Sensor Controller include the following:

- The low-power clocked comparator can be used to wake the system CPU from any state in which the comparator is active. A configurable internal reference DAC can be used in conjunction with the comparator. The output of the comparator can also be used to trigger an interrupt or the ADC.
- Capacitive sensing functionality is implemented through the use of a constant current source, a time-to-digital converter, and a comparator. The continuous time comparator in this block can also be used as a higher-accuracy alternative to the low-power clocked comparator. The Sensor Controller takes care of baseline tracking, hysteresis, filtering, and other related functions when these modules are used for capacitive sensing.
- The ADC is a 12-bit, 200-ksamples/s ADC with eight inputs and a built-in voltage reference. The ADC can be triggered by many different sources including timers, I/O pins, software, and comparators.
- The analog modules can connect to up to eight different GPIOs
- Dedicated SPI master with up to 6 MHz clock speed

The peripherals in the Sensor Controller can also be controlled from the main application processor.

## 8.6 Cryptography

The CC2652R7 device comes with a wide set of modern cryptography-related hardware accelerators, drastically reducing code footprint and execution time for cryptographic operations. It also has the benefit of being lower power and improves availability and responsiveness of the system because the cryptography operations runs in a background hardware thread.

Together with a large selection of open-source cryptography libraries provided with the Software Development Kit (SDK), this allows for secure and future proof IoT applications to be easily built on top of the platform. The hardware accelerator modules are:

- **True Random Number Generator (TRNG)** module provides a true, nondeterministic noise source for the purpose of generating keys, initialization vectors (IVs), and other random number requirements. The TRNG is built on 24 ring oscillators that create unpredictable output to feed a complex nonlinear-combinatorial circuit.
- **Secure Hash Algorithm 2 (SHA-2)** with support for SHA224, SHA256, SHA384, and SHA512
- **Advanced Encryption Standard (AES)** with 128 and 256 bit key lengths
- **Public Key Accelerator** - Hardware accelerator supporting mathematical operations needed for elliptic curves up to 512 bits and RSA key pair generation up to 1024 bits.

Through use of these modules and the TI provided cryptography drivers, the following capabilities are available for an application or stack:

- **Key Agreement Schemes**
  - Elliptic curve Diffie–Hellman with static or ephemeral keys (ECDH and ECDHE)
  - Elliptic curve Password Authenticated Key Exchange by Juggling (ECJ-PAKE)
- **Signature Generation**
  - Elliptic curve Diffie-Hellman Digital Signature Algorithm (ECDSA)
- **Curve Support**
  - Short Weierstrass form (full hardware support), such as:
    - NIST-P224, NIST-P256, NIST-P384, NIST-P521
    - Brainpool-256R1, Brainpool-384R1, Brainpool-512R1
    - secp256r1
  - Montgomery form (hardware support for multiplication), such as:
    - Curve25519
- **SHA2 based MACs**
  - HMAC with SHA224, SHA256, SHA384, or SHA512
- Block cipher mode of operation
  - AESCCM
  - AESGCM
  - AESECB
  - AESCBC
  - AESCBC-MAC
- **True random number generation**

Other capabilities, such as RSA encryption and signatures as well as Edwards type of elliptic curves such as Curve1174 or Ed25519, can also be implemented using the provided hardware accelerators but are not part of the TI SimpleLink SDK for the CC2652R7 device.

## 8.7 Timers

A large selection of timers are available as part of the CC2652R7 device. These timers are:

- **Real-Time Clock (RTC)**

A 70-bit 3-channel timer running on the 32 kHz low frequency system clock (SCLK\_LF). This timer is available in all power modes except Shutdown. The timer can be calibrated to compensate for frequency drift when using the RCOSC\_LF as the low frequency system clock. If an external LF clock with frequency different from 32.768 kHz is used, the RTC tick speed can be adjusted to compensate for this. When using TI-RTOS, the RTC is used as the base timer in the operating system and should thus only be accessed through the kernel APIs such as the Clock module. The real time clock can also be read by the Sensor Controller Engine to timestamp sensor data and also has dedicated capture channels. By default, the RTC halts when a debugger halts the device.

- **General Purpose Timers (GPTIMER)**

The four flexible GPTIMERS can be used as either 4× 32 bit timers or 8× 16 bit timers, all running on up to 48 MHz. Each of the 16- or 32-bit timers support a wide range of features such as one-shot or periodic counting, pulse width modulation (PWM), time counting between edges and edge counting. The inputs and outputs of the timer are connected to the device event fabric, which allows the timers to interact with signals such as GPIO inputs, other timers, DMA and ADC. The GPTIMERS are available in Active and Idle power modes.

- **Sensor Controller Timers**

The Sensor Controller contains 3 timers:

AUX Timer 0 and 1 are 16-bit timers with a  $2^N$  prescaler. Timers can either increment on a clock or on each edge of a selected tick source. Both one-shot and periodical timer modes are available.

AUX Timer 2 is a 16-bit timer that can operate at 24 MHz, 2 MHz or 32 kHz independent of the Sensor Controller functionality. There are 4 capture or compare channels, which can be operated in one-shot or periodical modes. The timer can be used to generate events for the Sensor Controller Engine or the ADC, as well as for PWM output or waveform generation.

- **Radio Timer**

A multichannel 32-bit timer running at 4 MHz is available as part of the device radio. The radio timer is typically used as the timing base in wireless network communication using the 32-bit timing word as the network time. The radio timer is synchronized with the RTC by using a dedicated radio API when the device radio is turned on or off. This ensures that for a network stack, the radio timer seems to always be running when the radio is enabled. The radio timer is in most cases used indirectly through the trigger time fields in the radio APIs and should only be used when the accurate 48 MHz high frequency crystal is the source of SCLK\_HF.

- **Watchdog timer**

The watchdog timer is used to regain control if the system operates incorrectly due to software errors. It is typically used to generate an interrupt to and reset of the device for the case where periodic monitoring of the system components and tasks fails to verify proper functionality. The watchdog timer runs on a 1.5 MHz clock rate and cannot be stopped once enabled. The watchdog timer pauses to run in Standby power mode and when a debugger halts the device.



## 8.8 Serial Peripherals and I/O

The SSIs are synchronous serial interfaces that are compatible with SPI, MICROWIRE, and TI's synchronous serial interfaces. The SSIs support both SPI master and slave up to 4 MHz. The SSI modules support configurable phase and polarity.

The UARTs implement universal asynchronous receiver and transmitter functions. They support flexible baud-rate generation up to a maximum of 3 Mbps.

The I<sup>2</sup>S interface is used to handle digital audio and can also be used to interface pulse-density modulation microphones (PDM).

The I<sup>2</sup>C interface is used to communicate with devices compatible with the I<sup>2</sup>C standard. The I<sup>2</sup>C interface can handle 100 kHz and 400 kHz operation, and can serve as both master and slave.

The I/O controller (IOC) controls the digital I/O pins and contains multiplexer circuitry to allow a set of peripherals to be assigned to I/O pins in a flexible manner. All digital I/Os are interrupt and wake-up capable, have a programmable pullup and pulldown function, and can generate an interrupt on a negative or positive edge (configurable). When configured as an output, pins can function as either push-pull or open-drain. Five GPIOs have high-drive capabilities, which are marked in **bold** in [Section 6](#). All digital peripherals can be connected to any digital pin on the device.

For more information, see the [CC13x2x7, CC26x2x7 SimpleLink™ Wireless MCU Technical Reference Manual](#).

## 8.9 Battery and Temperature Monitor

A combined temperature and battery voltage monitor is available in the CC2652R7 device. The battery and temperature monitor allows an application to continuously monitor on-chip temperature and supply voltage and respond to changes in environmental conditions as needed. The module contains window comparators to interrupt the system CPU when temperature or supply voltage go outside defined windows. These events can also be used to wake up the device from Standby mode through the Always-On (AON) event fabric.

## 8.10 $\mu$ DMA

The device includes a direct memory access ( $\mu$ DMA) controller. The  $\mu$ DMA controller provides a way to offload data-transfer tasks from the system CPU, thus allowing for more efficient use of the processor and the available bus bandwidth. The  $\mu$ DMA controller can perform a transfer between memory and peripherals. The  $\mu$ DMA controller has dedicated channels for each supported on-chip module and can be programmed to automatically perform transfers between peripherals and memory when the peripheral is ready to transfer more data.

Some features of the  $\mu$ DMA controller include the following (this is not an exhaustive list):

- Highly flexible and configurable channel operation of up to 32 channels
- Transfer modes: memory-to-memory, memory-to-peripheral, peripheral-to-memory, and peripheral-to-peripheral
- Data sizes of 8, 16, and 32 bits
- Ping-pong mode for continuous streaming of data

## 8.11 Debug

The on-chip debug support is done through a dedicated cJTAG (IEEE 1149.7) or JTAG (IEEE 1149.1) interface. The device boots by default into cJTAG mode and must be reconfigured to use 4-pin JTAG.



## 8.12 Power Management

To minimize power consumption, the CC2652R7 supports a number of power modes and power management features (see [Table 8-1](#)).

**Table 8-1. Power Modes**

MODE	SOFTWARE CONFIGURABLE POWER MODES				RESET PIN HELD
	ACTIVE	IDLE	STANDBY	SHUTDOWN	
<b>CPU</b>	Active	Off	Off	Off	Off
<b>Flash</b>	On	Available	Off	Off	Off
<b>SRAM</b>	On	On	Retention	Off	Off
<b>Supply System</b>	On	On	Duty Cycled	Off	Off
Register and CPU retention	Full	Full	Partial	No	No
SRAM retention	Full	Full	Full	No	No
48 MHz high-speed clock (SCLK_HF)	XOSC_HF or RCOSC_HF	XOSC_HF or RCOSC_HF	Off	Off	Off
2 MHz medium-speed clock (SCLK_MF)	RCOSC_MF	RCOSC_MF	Available	Off	Off
32 kHz low-speed clock (SCLK_LF)	XOSC_LF or RCOSC_LF	XOSC_LF or RCOSC_LF	XOSC_LF or RCOSC_LF	Off	Off
Peripherals	Available	Available	Off	Off	Off
Sensor Controller	Available	Available	Available	Off	Off
Wake-up on RTC	Available	Available	Available	Off	Off
Wake-up on pin edge	Available	Available	Available	Available	Off
Wake-up on reset pin	On	On	On	On	On
Brownout detector (BOD)	On	On	Duty Cycled	Off	Off
Power-on reset (POR)	On	On	On	Off	Off
Watchdog timer (WDT)	Available	Available	Paused	Off	Off

In **Active** mode, the application system CPU is actively executing code. Active mode provides normal operation of the processor and all of the peripherals that are currently enabled. The system clock can be any available clock source (see [Table 8-1](#)).

In **Idle** mode, all active peripherals can be clocked, but the Application CPU core and memory are not clocked and no code is executed. Any interrupt event brings the processor back into active mode.

In **Standby** mode, only the always-on (AON) domain is active. An external wake-up event, RTC event, or Sensor Controller event is required to bring the device back to active mode. MCU peripherals with retention do not need to be reconfigured when waking up again, and the CPU continues execution from where it went into standby mode. All GPIOs are latched in standby mode.

In **Shutdown** mode, the device is entirely turned off (including the AON domain and Sensor Controller), and the I/Os are latched with the value they had before entering shutdown mode. A change of state on any I/O pin defined as a *wake from shutdown pin* wakes up the device and functions as a reset trigger. The CPU can differentiate between reset in this way and reset-by-reset pin or power-on reset by reading the reset status register. The only state retained in this mode is the latched I/O state and the flash memory contents.

The Sensor Controller is an autonomous processor that can control the peripherals in the Sensor Controller independently of the system CPU. This means that the system CPU does not have to wake up, for example to perform an ADC sampling or poll a digital sensor over SPI, thus saving both current and wake-up time that would otherwise be wasted. The [Sensor Controller Studio](#) tool enables the user to program the Sensor Controller, control its peripherals, and wake up the system CPU as needed. All Sensor Controller peripherals can also be controlled by the system CPU.

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#### Note

The power, RF and clock management for the CC2652R7 device require specific configuration and handling by software for optimized performance. This configuration and handling is implemented in the TI-provided drivers that are part of the [SimpleLink™ CC13xx and CC26xx software development kit \(SDK\)](#). Therefore, TI highly recommends using this software framework for all application development on the device. The complete SDK with TI-RTOS (optional), device drivers, and examples are offered free of charge in source code.

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### 8.13 Clock Systems

The CC2652R7 device has several internal system clocks.

The 48 MHz SCLK\_HF is used as the main system (MCU and peripherals) clock. This can be driven by the internal 48 MHz RC Oscillator (RCOSC\_HF) or an external 48 MHz crystal (XOSC\_HF). Radio operation requires an external 48 MHz crystal.

SCLK\_MF is an internal 2 MHz clock that is used by the Sensor Controller in low-power mode and also for internal power management circuitry. The SCLK\_MF clock is always driven by the internal 2 MHz RC Oscillator (RCOSC\_MF).

SCLK\_LF is the 32.768 kHz internal low-frequency system clock. It can be used by the Sensor Controller for ultra-low-power operation and is also used for the RTC and to synchronize the radio timer before or after Standby power mode. SCLK\_LF can be driven by the internal 32.8 kHz RC Oscillator (RCOSC\_LF), a 32.768 kHz watch-type crystal, or a clock input on any digital IO.

When using a crystal or the internal RC oscillator, the device can output the 32 kHz SCLK\_LF signal to other devices, thereby reducing the overall system cost.

### 8.14 Network Processor

Depending on the product configuration, the CC2652R7 device can function as a wireless network processor (WNP - a device running the wireless protocol stack with the application running on a separate host MCU), or as a system-on-chip (SoC) with the application and protocol stack running on the device's system CPU inside the device.

In the first case, the external host MCU communicates with the device using SPI or UART. In the second case, the application must be written according to the application framework supplied with the wireless protocol stack.

## 9 Application, Implementation, and Layout

### Note

Information in the following Applications section is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

For general design guidelines and hardware configuration guidelines, refer to [CC13xx/CC26xx Hardware Configuration and PCB Design Considerations Application Report](#).

### 9.1 Reference Designs

The following reference designs should be followed closely when implementing designs using the CC2652R7 device.

Special attention must be paid to RF component placement, decoupling capacitors and DCDC regulator components, as well as ground connections for all of these.

#### [CC26x2-R7EM-7ID Design Files](#)

The differential CC26x2-R7EM-7ID reference design provides schematic, layout and production files for the characterization board used for deriving the performance number found in this document.

#### [LP-CC2652R7 Design Files](#)

The CC26X2R LaunchPad Design Files contain detailed schematics and layouts to build application specific boards using the CC2652R7 device. This design applies to both the CC2642R and CC2652R devices.

#### [Sub-1 GHz and 2.4 GHz Antenna Kit for LaunchPad™ Development Kit and SensorTag](#)

The antenna kit allows real-life testing to identify the optimal antenna for your application. The antenna kit includes 16 antennas for frequencies from 169 MHz to 2.4 GHz, including:

- PCB antennas
- Helical antennas
- Chip antennas
- Dual-band antennas for 868 MHz and 915 MHz combined with 2.4 GHz

The antenna kit includes a JSC cable to connect to the Wireless MCU LaunchPad Development Kits and SensorTags.

### 9.2 Junction Temperature Calculation

This section shows the different techniques for calculating the junction temperature under various operating conditions. For more details, see [Semiconductor and IC Package Thermal Metrics](#).

There are three recommended ways to derive the junction temperature from other measured temperatures:

1. From package temperature:

$$T_J = \psi_{JT} \times P + T_{\text{case}} \quad (1)$$

2. From board temperature:

$$T_J = \psi_{JB} \times P + T_{\text{board}} \quad (2)$$

3. From ambient temperature:

$$T_J = R_{\theta JA} \times P + T_A \quad (3)$$

P is the power dissipated from the device and can be calculated by multiplying current consumption with supply voltage. Thermal resistance coefficients are found in [Section 7.8](#).

#### Example:

Using [Equation 3](#), the temperature difference between ambient temperature and junction temperature is calculated. In this example, we assume a simple use case where the radio is transmitting continuously at 0dBm output power. Let us assume the ambient temperature is 105 °C and the supply voltage is 3.0 V. To calculate P, we need to look up the current consumption for Tx at 105 °C in [Figure 7-8](#). From the plot, we see that the current consumption is 8.1 mA. This means that P is 3.0 V × 8.1 mA = 194.4 mW.

The junction temperature is then calculated as:

$$T_J = 23.4^{\circ}\text{C}/\text{W} \times 194.4\text{mW} + T_A = 4.5^{\circ}\text{C} + T_A \quad (4)$$

As can be seen from the example, the junction temperature is 4.5 °C higher than the ambient temperature when running continuous Tx at 105 °C and, thus, well within the recommended operating conditions of 115 °C.

For various application use cases current consumption for other modules may have to be added to calculate the appropriate power dissipation. For example, the MCU may be running simultaneously as the radio, peripheral modules may be enabled, etc. Typically, the easiest way to find the peak current consumption, and thus the peak power dissipation in the device, is to measure as described in [Measuring CC13xx and CC26xx Current Consumption](#).

## 10 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed as follows.

### 10.1 Device Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to all part numbers and/or date-code. Each device has one of three prefixes/identifications: X, P, or null (no prefix) (for example, XCC2652R7 is in preview; therefore, an X prefix/identification is assigned).

Device development evolutionary flow:

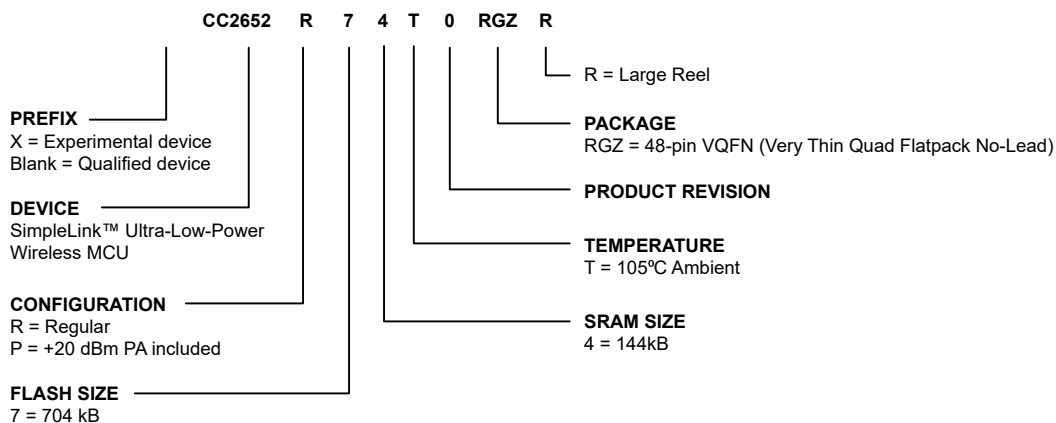
- X** Experimental device that is not necessarily representative of the final device's electrical specifications and may not use production assembly flow.
- P** Prototype device that is not necessarily the final silicon die and may not necessarily meet final electrical specifications.
- null** Production version of the silicon die that is fully qualified.

Production devices have been characterized fully, and the quality and reliability of the device have been demonstrated fully. TI's standard warranty applies.

Predictions show that prototype devices (X or P) have a greater failure rate than the standard production devices. Texas Instruments recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

TI device nomenclature also includes a suffix with the device family name. This suffix indicates the package type (for example, RGZ).

For orderable part numbers of CC2652R7 devices in the RGZ (7-mm x 7-mm) package type, see the *Package Option Addendum* of this document, the Device Information in [Section 3](#), the TI website ([www.ti.com](http://www.ti.com)), or contact your TI sales representative.



**Figure 10-1. Device Nomenclature**

### 10.2 Tools and Software

The CC2652R7 device is supported by a variety of software and hardware development tools.

#### Development Kit

##### CC2652R7 LaunchPad™ Development Kit

The CC2652R7 LaunchPad™ Development Kit enables development of high-performance wireless applications that benefit from low-power operation. The kit features the CC2652R7 SimpleLink Wireless MCU, which allows you to quickly evaluate and prototype 2.4-GHz wireless applications such as Bluetooth 5 Low Energy, Zigbee and Thread, plus

combinations of these. The kit works with the LaunchPad ecosystem, easily enabling additional functionality like sensors, display and more. The built-in EnergyTrace™ software is an energy-based code analysis tool that measures and displays the application's energy profile and helps to optimize it for ultra-low-power consumption. See [Table 5-1](#) for guidance in selecting the correct device for single-protocol products.

## Software

### SimpleLink™ CC13XX- CC26XX SDK

The SimpleLink CC13xx and CC26xx Software Development Kit (SDK) provides a complete package for the development of wireless applications on the CC13XX / CC26XX family of devices. The SDK includes a comprehensive software package for the CC2652R7 device, including the following protocol stacks:

- Bluetooth Low Energy 4 and 5.2
- Thread (based on OpenThread)
- Zigbee 3.0
- Wi-SUN®
- TI 15.4-Stack - an IEEE 802.15.4-based star networking solution for Sub-1 GHz and 2.4 GHz
- Proprietary RF - a large set of building blocks for building proprietary RF software
- Multiprotocol support - concurrent operation between stacks using the Dynamic Multiprotocol Manager (DMM)

The SimpleLink CC13XX-CC26XX SDK is part of TI's SimpleLink MCU platform, offering a single development environment that delivers flexible hardware, software and tool options for customers developing wired and wireless applications. For more information about the SimpleLink MCU Platform, visit <http://www.ti.com/simplelink>.

## Development Tools

### Code Composer Studio™ Integrated Development Environment (IDE)

Code Composer Studio is an integrated development environment (IDE) that supports TI's Microcontroller and Embedded Processors portfolio. Code Composer Studio comprises a suite of tools used to develop and debug embedded applications. It includes an optimizing C/C++ compiler, source code editor, project build environment, debugger, profiler, and many other features. The intuitive IDE provides a single user interface taking you through each step of the application development flow. Familiar tools and interfaces allow users to get started faster than ever before. Code Composer Studio combines the advantages of the Eclipse® software framework with advanced embedded debug capabilities from TI resulting in a compelling feature-rich development environment for embedded developers.

CCS has support for all SimpleLink Wireless MCUs and includes support for EnergyTrace™ software (application energy usage profiling). A real-time object viewer plugin is available for TI-RTOS, part of the SimpleLink SDK.

Code Composer Studio is provided free of charge when used in conjunction with the XDS debuggers included on a LaunchPad Development Kit.

### Code Composer Studio™ Cloud IDE

Code Composer Studio (CCS) Cloud is a web-based IDE that allows you to create, edit and build CCS and Energia™ projects. After you have successfully built your project, you can download and run on your connected LaunchPad. Basic debugging, including features like setting breakpoints and viewing variable values is now supported with CCS Cloud.

### IAR Embedded Workbench® for Arm®

IAR Embedded Workbench® is a set of development tools for building and debugging embedded system applications using assembler, C and C++. It provides a completely integrated development environment that includes a project manager, editor, and build tools. IAR has support for all SimpleLink Wireless MCUs. It offers broad debugger support, including XDS110, IAR I-jet™ and Segger J-Link™. A real-time object viewer plugin is available for TI-RTOS, part of the SimpleLink SDK. IAR is also supported out-of-the-box on most software examples provided as part of the SimpleLink SDK.

A 30-day evaluation or a 32 KB size-limited version is available through [iar.com](http://iar.com).

### SmartRF™ Studio

SmartRF™ Studio is a Windows® application that can be used to evaluate and configure SimpleLink Wireless MCUs from Texas Instruments. The application will help designers of RF systems to easily evaluate the radio at an early stage in the design process. It is especially useful for generation of configuration register values and for practical testing and debugging of the RF system. SmartRF Studio can be used either as a standalone application or together with applicable evaluation boards or debug probes for the RF device. Features of the SmartRF Studio include:

- Link tests - transmit and receive packets between nodes
- Antenna and radiation tests - set the radio in continuous wave TX and RX states
- Export radio configuration code for use with the TI SimpleLink SDK RF driver
- Custom GPIO configuration for signaling and control of external switches

### Sensor Controller Studio

Sensor Controller Studio is used to write, test and debug code for the Sensor Controller peripheral. The tool generates a Sensor Controller Interface driver, which is a set of C source files that are compiled into the System CPU application. These source files also contain the Sensor Controller binary image and allow the System CPU application to control and exchange data with the Sensor Controller. Features of the Sensor Controller Studio include:

- Ready-to-use examples for several common use cases
- Full toolchain with built-in compiler and assembler for programming in a C-like programming language

- Provides rapid development by using the integrated sensor controller task testing and debugging functionality, including visualization of sensor data and verification of algorithms

#### CCS UniFlash

CCS UniFlash is a standalone tool used to program on-chip flash memory on TI MCUs. UniFlash has a GUI, command line, and scripting interface. CCS UniFlash is available free of charge.

### 10.2.1 SimpleLink™ Microcontroller Platform

The SimpleLink microcontroller platform sets a new standard for developers with the broadest portfolio of wired and wireless Arm® MCUs (System-on-Chip) in a single software development environment. Delivering flexible hardware, software and tool options for your IoT applications. Invest once in the SimpleLink software development kit and use throughout your entire portfolio. Learn more on [ti.com/simplelink](https://ti.com/simplelink).

### 10.3 Documentation Support

To receive notification of documentation updates on data sheets, errata, application notes and similar, navigate to the device product folder on [ti.com/product/CC2652R7](https://ti.com/product/CC2652R7). In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

The current documentation that describes the MCU, related peripherals, and other technical collateral is listed as follows.

#### TI Resource Explorer

[TI Resource Explorer](#) Software examples, libraries, executables, and documentation are available for your device and development board.

#### Errata

##### [CC2652R7 Silicon Errata](#)

The silicon errata describes the known exceptions to the functional specifications for each silicon revision of the device and description on how to recognize a device revision.

#### Application Reports

All application reports for the CC2652R7 device are found on the device product folder at: [ti.com/product/CC2652R7/#tech-docs](https://ti.com/product/CC2652R7/#tech-docs).

#### Technical Reference Manual (TRM)

##### [CC13x2x7, CC26x2x7 SimpleLink™ Wireless MCU TRM](#)

The TRM provides a detailed description of all modules and peripherals available in the device family.

### 10.4 Support Resources

[TI E2E™ support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

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## 10.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## 10.7 Glossary

### TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

## 11 Mechanical, Packaging, and Orderable Information

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">CC2652R74T0RGZR</a>	Active	Production	VQFN (RGZ)   48	2500   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2652 R74
CC2652R74T0RGZR.A	Active	Production	VQFN (RGZ)   48	2500   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2652 R74
CC2652R74T0RGZR.B	Active	Production	VQFN (RGZ)   48	2500   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2652 R74

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
CC2652R74T0RGZR	VQFN	RGZ	48	2500	330.0	16.4	7.3	7.3	1.1	12.0	16.0	Q2

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
CC2652R74T0RGZR	VQFN	RGZ	48	2500	367.0	367.0	35.0

## GENERIC PACKAGE VIEW

**RGZ 48**

**VQFN - 1 mm max height**

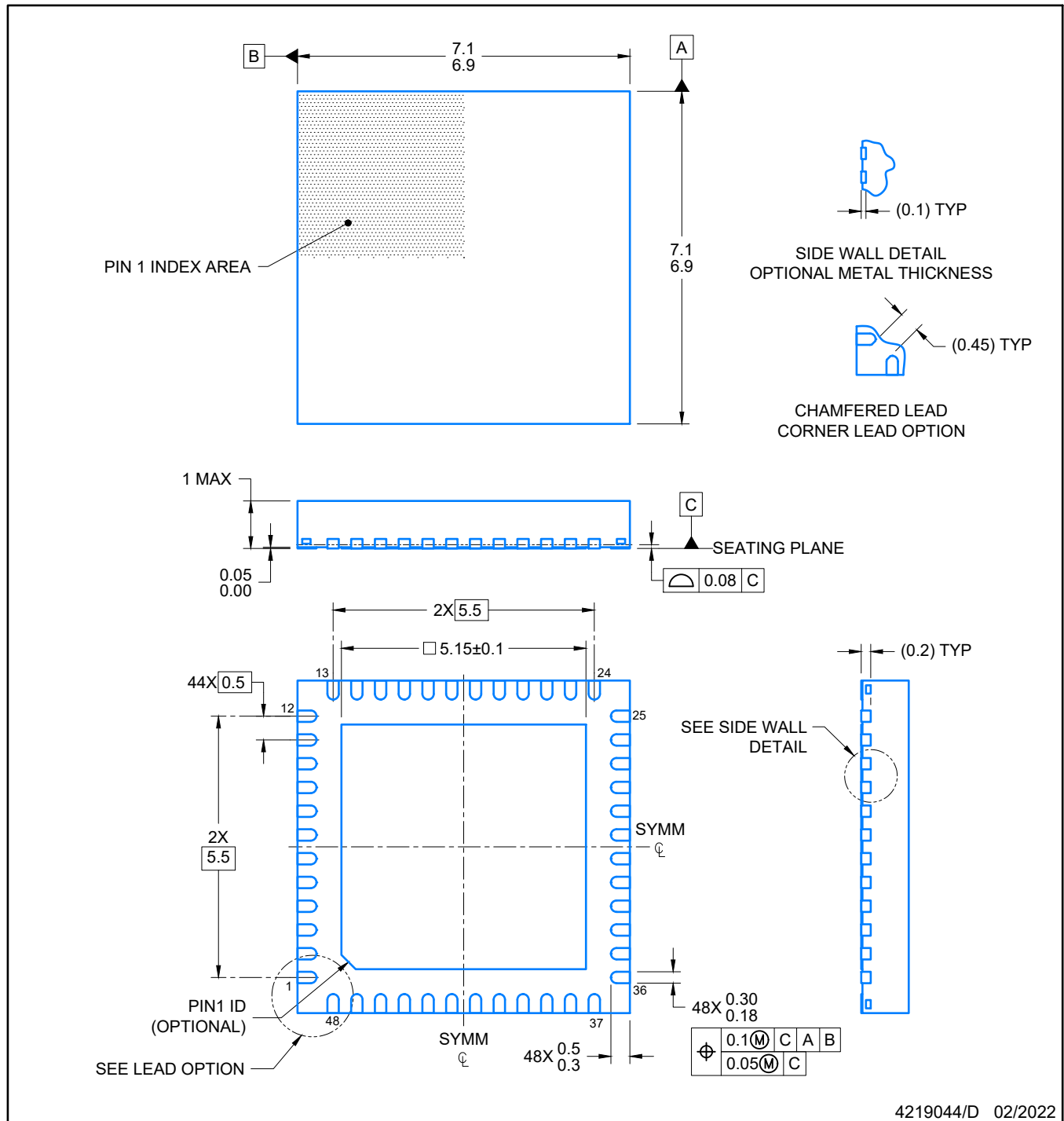
7 x 7, 0.5 mm pitch

PLASTIC QUADFLAT PACK- NO LEAD



Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

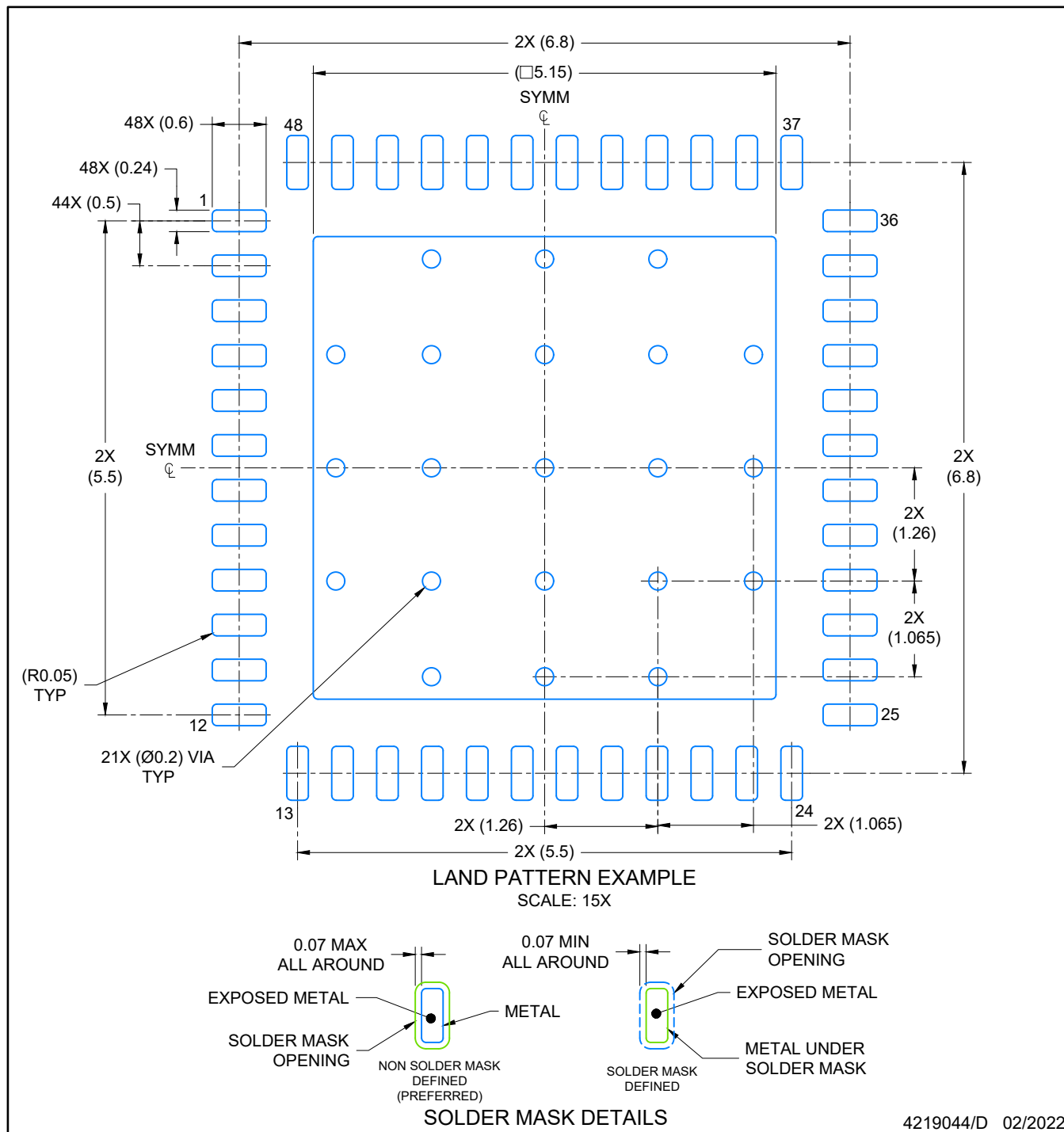
4224671/A



4219044/D 02/2022

## NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.

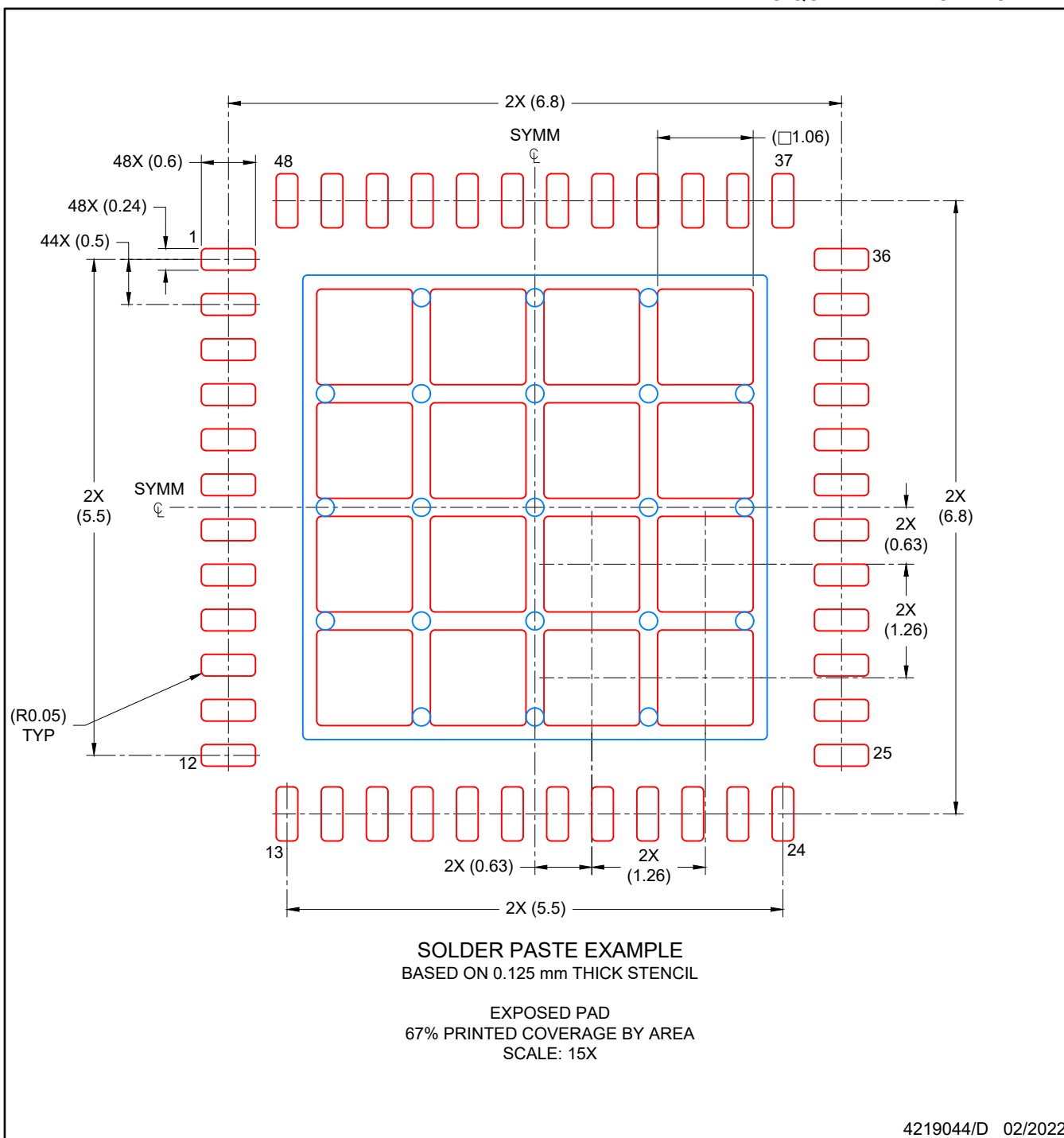


4219044/D 02/2022

## NOTES: (continued)

- This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/sluea271](http://www.ti.com/lit/sluea271)).
- Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.





NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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