Burr-Brown Products
from Texas Instruments

ADS8472

16-BIT, 1-MSPS, PSEUDO-BIPOLAR, FULLY DIFFERENTIAL INPUT, MICROPOWER SAMPLING ANALOG-TO-DIGITAL CONVERTER WITH PARALLEL INTERFACE, REFERENCE

FEATURES

- 0 to 1-MHz Sample Rate
- ±0.4 LSB Typ, ±0.65 LSB Max INL
- ±0.3 LSB Typ, ±0.5 LSB Max DNL
- 16-Bit NMC Ensured Over Temperature
- ±0.1-mV Offset Error
- ±0.05-PPM/°C Offset Error Drift
- ±0.035 %FSR Gain Error
- ±0.4-PPM/°C Gain Error Drift
- 95dB SNR, -120dB THD, 123dB SFDR
- Zero Latency
- Low Power: 225 mW at 1 MSPS
- Unipolar Differential Input Range: V_{ref} to $-V_{ref}$
- Onboard Reference with 6 PPM/°C Drift
- Onboard Reference Buffer
- High-Speed Parallel Interface
- Wide Digital Supply 2.7 V to 5.25 V
- 8-/16-Bit Bus Transfer
- 48-Pin 7x7 QFN Package

APPLICATIONS

- Medical Instruments
- Optical Networking
- Transducer Interface
- High Accuracy Data Acquisition Systems
- Magnetometers

DESCRIPTION

The ADS8472 is an 16-bit, 1-MSPS A/C converter with an internal 4.096-V reference and a pseudo-bipolar, fully differential input. The device includes a 16-bit capacitor-based SAR A/D converter with inherent sample and hold. The ADS8472 offers a full 16-bit interface or an 8-bit bus option using two read cycles.

The ADS8472 is available in a 48-lead 7x7 QFN package and is characterized over the industrial –40°C to 85°C temperature range.

HIGH SPEED SAR CONVERTER FAMILY

TYPE/SPEED	500 kHz	~600 kHz	750 kHz	1 MHz	1.25 MHz	2 MHz	3 MHz	4MHz
18-Bit Pseudo-Diff	ADS8383	ADS8381		ADS8481				
		ADS8380 (s)						
18-Bit Pseudo-Bipolar, Fully Diff		ADS8382 (s)		ADS8482				
16-Bit Pseudo-Diff	ADS8327	ADS8370 (s)	ADS8371	ADS8471	ADS8401	ADS8411		
	ADS8328	ADS8372 (s)			ADS8405	ADS8410 (s)		
16-Bit Pseudo-Bipolar, Fully Diff				ADS8472	ADS8402	ADS8412		ADS8422
					ADS8406	ADS8413 (s)		
14-Bit Pseudo-Diff					ADS7890 (s)		ADS7891	
12-Bit Pseudo-Diff				ADS7886		ADS7883		ADS7881
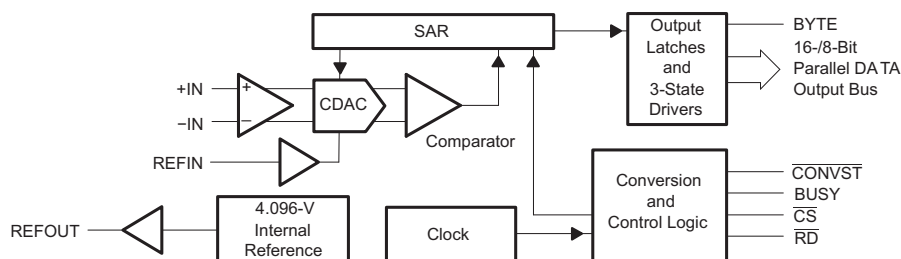
ADS8472

ORDERING INFORMATION[1]

MODEL	MAXIMUM INTEGRAL LINEARITY (LSB)	MAXIMUM DIFFERENTIAL LINEARITY (LSB)	NO MISSING CODES RESOLUTION (BIT)	PACKAGE TYPE	PACKAGE DESIGNATOR	TEMPER-ATURE RANGE	ORDERING INFORMATION	TRANS-PORT MEDIA QTY.
ADS8472I	±1	±0.75	16	7x7 48 Pin QFN	RGZ	−40°C to 85°C	ADS8472IRGZT	Tape and reel 250
							ADS8472IRGZR	Tape and reel 1000
ADS8472IB	±0.65	±0.5	16	7x7 48 Pin QFN	RGZ	−40°C to 85°C	ADS8472IBRGZT	Tape and reel 250
							ADS8472IBRGZR	Tape and reel 1000

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

ABSOLUTE MAXIMUM RATINGS[1]

over operating free-air temperature range (unless otherwise noted)

		VALUE	UNIT
Voltage	+IN to AGND	−0.4 to +VA + 0.1	V
	−IN to AGND	−0.4 to +VA + 0.1	V
	+VA to AGND	−0.3 to 7	V
	+VBD to BDGND	−0.3 to 7	V
	+VA to +VBD	−0.3 to 2.55	V
Digital input voltage to BDGND		−0.3 to +VBD + 0.3	V
Digital output voltage to BDGND		−0.3 to +VBD + 0.3	V
T_A Operating free-air temperature range		−40 to 85	°C
T_{stg} Storage temperature range		−65 to 150	°C
Junction temperature (T_J max)		150	°C
QFN package	Power dissipation	$(T_J Max − T_A)/\theta_{JA}$	
	θ_{JA} thermal impedance	22	°C/W
Lead temperature, soldering	Vapor phase (60 sec)	215	°C
	Infrared (15 sec)	220	°C

(1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

SPECIFICATIONS

T_A = −40°C to 85°C, +VA = 5 V, +VBD = 3 V or 5 V, V_{ref} = 4.096 V, f_{SAMPLE} = 1 MSPS (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
ANALOG INPUT						
Full-scale input voltage[1]		+IN − (−IN)	$-V_{ref}$		V_{ref}	V
Absolute input voltage	+IN		−0.2		V_{ref} + 0.2	V
	−IN		−0.2		V_{ref} + 0.2	
Common-mode input range			$(V_{ref})/2 - 0.2$	$(V_{ref})/2$	$(V_{ref})/2 + 0.2$	V
Input capacitance				65		pF
Input leakage current				1		nA
SYSTEM PERFORMANCE						
Resolution				16		Bits
No missing codes	ADS8472I		16			Bits
	ADS8472IB		16			
Integral linearity [2]	ADS8472I		−1	±0.4	1	LSB (16 bit)[3]
	ADS8472IB		−0.65	±0.4	0.65	
Differential linearity	ADS8472I		−0.75	±0.3	0.75	LSB (16 bit)
	ADS8472IB		−0.5	±0.3	0.5	
Offset error[4]	ADS8472I		−0.5	±0.1	0.5	mV
	ADS8472IB		−0.5	±0.1	0.5	
Offset error temperature drift	ADS8472I			±0.05		ppm/°C
	ADS8472IB			±0.05		
Gain error[4][5]	ADS8472I	V_{ref} = 4.096 V	−0.1	±0.035	0.1	%FS
	ADS8472IB	V_{ref} = 4.096 V	−0.1	±0.035	0.1	%FS
Gain error temperature drift	ADS8472I			±0.4		ppm/°C
	ADS8472IB			±0.4		
Common-mode rejection ratio		At dc (±0.2 V around V_{ref}/2)		65		dB
		+IN − (−IN) = 1 Vpp at 1 MHz		55		
Noise				25		µV RMS
Power supply rejection ratio		At 1FFFFh output code		60		dB
SAMPLING DYNAMICS						
Conversion time				625	650	ns
Acquisition time			320	350		ns
Throughput rate					1	MHz
Aperture delay				4		ns
Aperture jitter				5		ps
Step response				150		ns
Over voltage recovery				150		ns

(1) Ideal input span, does not include gain or offset error.
(2) This is endpoint INL, not best fit.
(3) LSB means least significant bit
(4) Measured relative to an ideal full-scale input [+IN − (−IN)] of 8.192 V
(5) This specification does not include the internal reference voltage error and drift.

SPECIFICATIONS (Continued)

$T_A = -40°C$ to $85°C$, $+VA = 5$ V, $+VBD = 3$ V or 5 V, $V_{ref} = 4.096$ V, $f_{SAMPLE} = 1$ MSPS (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
DYNAMIC CHARACTERISTICS						
Total harmonic distortion (THD)[1]	ADS8472I	$V_{IN} = 8$ V_{pp} at 2 kHz		−120		dB
	ADS8472IB			−121		
	ADS8472I	$V_{IN} = 8$ V_{pp} at 20 kHz		-105		
	ADS8472IB			-110		
	ADS8472I	$V_{IN} = 8$ V_{pp} at 100 kHz		-100		
	ADS8472IB			-103		
Signal to noise ratio (SNR)[1]	ADS8472I	$V_{IN} = 8$ V_{pp} at 2 kHz	94	95.1		dB
	ADS8472IB		94	95.3		
	ADS8472I	$V_{IN} = 8$ V_{pp} at 20 kHz		95		
	ADS8472IB			95.1		
	ADS8472I	$V_{IN} = 8$ V_{pp} at 100 kHz		93		
	ADS8472IB			94.5		
Signal to noise + distortion (SINAD)[1]	ADS8472I	$V_{IN} = 8$ V_{pp} at 2 kHz	94	95		dB
	ADS8472IB		94	95.2		
	ADS8472I	$V_{IN} = 8$ V_{pp} at 20 kHz		94.5		
	ADS8472IB			95		
	ADS8472I	$V_{IN} = 8$ V_{pp} at 100 kHz		92		
	ADS8472IB			94		
Spurious free dynamic range (SFDR)[1]	ADS8472I	$V_{IN} = 8$ V_{pp} at 2 kHz		120		dB
	ADS8472IB			123		
	ADS8472I	$V_{IN} = 8$ V_{pp} at 20 kHz		107		
	ADS8472IB			113		
	ADS8472I	$V_{IN} = 8$ V_{pp} at 100 kHz		102		
	ADS8472IB			105		
−3dB Small signal bandwidth				15		MHz

(1)   Calculated on the first nine harmonics of the input frequency.

SPECIFICATIONS (Continued)

T_A = −40°C to 85°C, +VA = 5 V, +VBD = 3 V or 5 V, V_{ref} = 4.096 V, f_{SAMPLE} = 1 MSPS (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
VOLTAGE REFERENCE INPUT						
Reference voltage at REFIN, V_{ref}			3.0	4.096	+VA − 0.8	V
Reference resistance[1]				500		kΩ
Reference current drain		f_s = 1 MHz			1	mA
INTERNAL REFERENCE OUTPUT						
Internal reference start-up time		From 95% (+VA), with 1-µF storage capacitor			120	ms
Reference voltage range, V_{ref}		I_O = 0	4.081	4.096	4.111	V
Source current		Static load			10	µA
Line regulation		+VA = 4.75 V ~ 5.25 V		60		µV
Drift		I_O = 0		±6		PPM/°C
DIGITAL INPUT/OUTPUT						
Logic family −CMOS						
Logic level	V_{IH}	I_{IH} = 5 µA	+VBD − 1		+VBD + 0.3	V
	V_{IL}	I_{IL} = 5 µA	−0.3		0.8	
	V_{OH}	I_{OH} = 2 TTL loads	+VBD − 0.6			
	V_{OL}	I_{OL} = 2 TTL loads				
Data format − Straight Binary						
POWER SUPPLY REQUIREMENTS						
Power supply voltage	+VBD		2.7	3.3	5.25	V
	+VA		4.75	5	5.25	V
Supply current[2]		f_s = 1 MHz		45	50	mA
Power dissipation[2]		f_s = 1 MHz		225	250	mW
TEMPERATURE RANGE						
Operating free-air			−40		85	°C

(1) Can vary ±20%
(2) This includes only +VA current. +VBD current is typical 1 mA with 5 pF load capacitance on all output pins.

TIMING CHARACTERISTICS

All specifications typical at −40°C to 85°C, +VA =+VBD = 5 V [1][2][3]

PARAMETER		MIN	TYP	MAX	UNIT
$t_{(CONV)}$	Conversion time		625	650	ns
$t_{(ACQ)}$	Acquisition time	320	350		ns
$t_{(HOLD)}$	Sample capacitor hold time			25	ns
t_{pd1}	$\overline{CONVST}$ low to BUSY high			40	ns
t_{pd2}	Propagation delay time, end of conversion to BUSY low			15	ns
t_{pd3}	Propagation delay time, start of convert state to rising edge of BUSY			15	ns
t_{w1}	Pulse duration, $\overline{CONVST}$ low	40			ns
t_{su1}	Setup time, $\overline{CS}$ low to $\overline{CONVST}$ low	20			ns
t_{w2}	Pulse duration, $\overline{CONVST}$ high	20			ns
	$\overline{CONVST}$ falling edge jitter			10	ps
t_{w3}	Pulse duration, BUSY signal low	$t_{(ACQ)}$min			ns
t_{w4}	Pulse duration, BUSY signal high			650	ns
t_{h1}	Hold time, first data bus transition ($\overline{RD}$ low, or $\overline{CS}$ low for read cycle, or BYTE input changes) after $\overline{CONVST}$ low	40			ns
t_{d1}	Delay time, $\overline{CS}$ low to $\overline{RD}$ low	0			ns
t_{su2}	Setup time, $\overline{RD}$ high to $\overline{CS}$ high	0			ns
t_{w5}	Pulse duration, $\overline{RD}$ low	50			ns
t_{en}	Enable time, $\overline{RD}$ low (or $\overline{CS}$ low for read cycle) to data valid			20	ns
t_{d2}	Delay time, data hold from $\overline{RD}$ high	5			ns
t_{d3}	Delay time, BYTE rising edge or falling edge to data valid	10		20	ns
t_{w6}	Pulse duration, $\overline{RD}$ high	20			ns
t_{w7}	Pulse duration, $\overline{CS}$ high	20			ns
t_{h2}	Hold time, last $\overline{RD}$ (or $\overline{CS}$ for read cycle) rising edge to $\overline{CONVST}$ falling edge	50			ns
t_{pd4}	Propagation delay time, BUSY falling edge to next $\overline{RD}$ (or $\overline{CS}$ for read cycle) falling edge	0			ns
t_{d4}	Delay time, BYTE edge to edge skew	0			ns
t_{su3}	Setup time, BYTE transition to $\overline{RD}$ falling edge	10			ns
t_{h3}	Hold time, BYTE transition to $\overline{RD}$ falling edge	10			ns
t_{dis}	Disable time, $\overline{RD}$ high ($\overline{CS}$ high for read cycle) to 3-stated data bus			20	ns
t_{d5}	Delay time, BUSY low to MSB data valid delay			0	ns
t_{d6}	Delay time, $\overline{CS}$ rising edge to BUSY falling edge	50			ns
t_{d7}	Delay time, BUSY falling edge to $\overline{CS}$ rising edge	50			ns
t_{su5}	BYTE transition setup time, from BYTE transition to next BYTE transition.	50			ns
$t_{su(ABORT)}$	Setup time from the falling edge of $\overline{CONVST}$ (used to start the valid conversion) to the next falling edge of $\overline{CONVST}$ (when CS = 0 and $\overline{CONVST}$ are used to abort) or to the next falling edge of $\overline{CS}$ (when $\overline{CS}$ is used to abort).	60		550	ns

(1) All input signals are specified with t_r = t_f = 5 ns (10% to 90% of +VBD) and timed from a voltage level of $(V_{IL} + V_{IH})/2$.
(2) See timing diagrams.
(3) All timing are measured with 20 pF equivalent loads on all data bits and BUSY pins.

TIMING CHARACTERISTICS

All specifications typical at −40°C to 85°C, +VA = 5 V +VBD = 3 V [1][2][3]

PARAMETER		MIN	TYP	MAX	UNIT
$t_{(CONV)}$	Conversion time		625	650	ns
$t_{(ACQ)}$	Acquisition time	320	350		ns
$t_{(HOLD)}$	Sample capacitor hold time			25	ns
t_{pd1}	$\overline{CONVST}$ low to BUSY high			40	ns
t_{pd2}	Propagation delay time, end of conversion to BUSY low			25	ns
t_{pd3}	Propagation delay time, start of convert state to rising edge of BUSY			25	ns
t_{w1}	Pulse duration, $\overline{CONVST}$ low	40			ns
t_{su1}	Setup time, $\overline{CS}$ low to $\overline{CONVST}$ low	20			ns
t_{w2}	Pulse duration, CONVST high	20			ns
	$\overline{CONVST}$ falling edge jitter			10	ps
t_{w3}	Pulse duration, BUSY signal low	$t_{(ACQ)}$min			ns
t_{w4}	Pulse duration, BUSY signal high			650	ns
t_{h1}	Hold time, first data bus transition ($\overline{RD}$ low, or $\overline{CS}$ low for read cycle, or BYTE input changes) after $\overline{CONVST}$ low	40			ns
t_{d1}	Delay time, $\overline{CS}$ low to $\overline{RD}$ low	0			ns
t_{su2}	Setup time, $\overline{RD}$ high to $\overline{CS}$ high	0			ns
t_{w5}	Pulse duration, $\overline{RD}$ low	50			ns
t_{en}	Enable time, $\overline{RD}$ low (or $\overline{CS}$ low for read cycle) to data valid			30	ns
t_{d2}	Delay time, data hold from $\overline{RD}$ high	5			ns
t_{d3}	Delay time, BYTE rising edge or falling edge to data valid	10		30	ns
t_{w6}	Pulse duration, $\overline{RD}$ high	20			ns
t_{w7}	Pulse duration, $\overline{CS}$ high	20			ns
t_{h2}	Hold time, last $\overline{RD}$ (or $\overline{CS}$ for read cycle) rising edge to $\overline{CONVST}$ falling edge	50			ns
t_{pd4}	Propagation delay time, BUSY falling edge to next $\overline{RD}$ (or $\overline{CS}$ for read cycle) falling edge	0			ns
t_{d4}	Delay time, BYTE edge to edge skew	0			ns
t_{su3}	Setup time, BYTE transition to $\overline{RD}$ falling edge	10			ns
t_{h3}	Hold time, BYTE transition to $\overline{RD}$ falling edge	10			ns
t_{dis}	Disable time, $\overline{RD}$ high ($\overline{CS}$ high for read cycle) to 3-stated data bus			30	ns
t_{d5}	Delay time, BUSY low to MSB data valid delay			0	ns
t_{d6}	Delay time, $\overline{CS}$ rising edge to BUSY falling edge	50			ns
t_{d7}	Delay time, BUSY falling edge to $\overline{CS}$ rising edge	50			ns
t_{su5}	BYTE transition setup time, from BYTE transition to next BYTE transition.	50			ns
$t_{su(ABORT)}$	Setup time from the falling edge of $\overline{CONVST}$ (used to start the valid conversion) to the next falling edge of $\overline{CONVST}$ (when CS = 0 and $\overline{CONVST}$ are used to abort) or to the next falling edge of $\overline{CS}$ (when $\overline{CS}$ is used to abort).	70		550	ns

(1) All input signals are specified with $t_r = t_f = 5$ ns (10% to 90% of +VBD) and timed from a voltage level of $(V_{IL} + V_{IH})/2$.
(2) See timing diagrams.
(3) All timing are measured with 20 pF equivalent loads on all data bits and BUSY pins.

PIN ASSIGNMENTS

RGZ PACKAGE
(TOP VIEW)
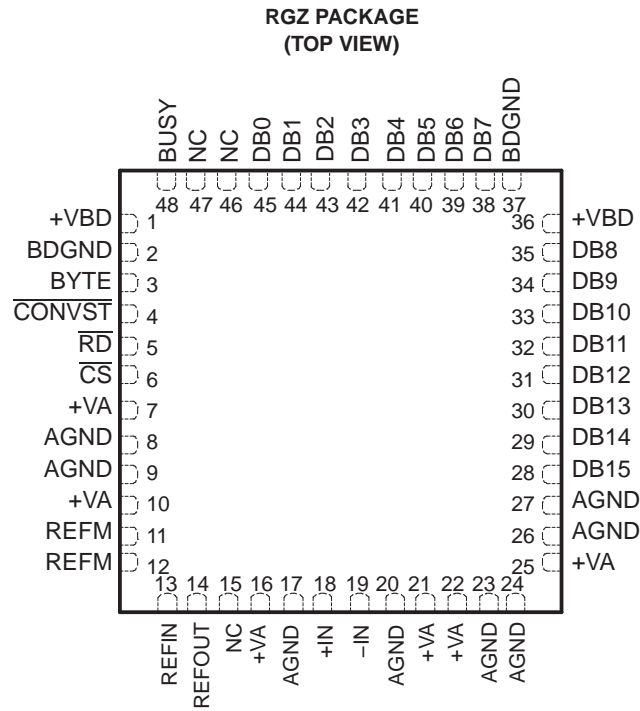
NC – No internal connection

NOTE: The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

TERMINAL FUNCTIONS

NAME	NO	I/O	DESCRIPTION
AGND	8, 9, 17, 20, 23, 24, 26, 27	–	Analog ground
BDGND	2, 37	–	Digital ground for bus interface digital supply
BUSY	48	O	Status output. High when a conversion is in progress.
BYTE	3	I	Byte select input. Used for 8-bit bus reading. 0: No fold back 1: Low byte D[9:2] of the 16 most significant bits is folded back to high byte of the 16 most significant pins DB[17:10].
$\overline{\text{CONVST}}$	4	I	Convert start. The falling edge of this input ends the acquisition period and starts the hold period.
$\overline{\text{CS}}$	6	I	Chip select. The falling edge of this input starts the acquisition period.

Data Bus			8-BIT BUS		16-BIT BUS
			BYTE = 0	BYTE = 1	BYTE = 0
DB15	28	O	D15 (MSB)	D7	D15(MSB)
DB14	29	O	D14	D6	D14
DB13	30	O	D13	D5	D13
DB12	31	O	D12	D4	D12
DB11	32	O	D11	D3	D11
DB10	33	O	D10	D2	D10
DB9	34	O	D9	All ones	D9
DB8	35	O	D8	All ones	D8
DB7	38	O	D7	All ones	D7
DB6	39	O	D6	All ones	D6
DB5	40	O	D5	All ones	D5
DB4	41	O	D4	All ones	D4
DB3	42	O	D3	All ones	D3

TERMINAL FUNCTIONS (continued)

NAME	NO	I/O	DESCRIPTION		
DB2	43	O	D2	All ones	D2
DB1	44	O	D1	All ones	D1
DB0	45	O	D0 (LSB)	All ones	D0 (LSB)
−IN	19	I	Inverting input channel		
+IN	18	I	Noninverting input channel		
NC	15, 46, 47		No connection		
REFIN	13	I	Reference input		
REFOUT	14	O	Reference output. Add 1-µF capacitor between the REFOUT pin and REFM pin when internal reference is used.		
REFM	11, 12	I	Reference ground		
$\overline{RD}$	5	I	Synchronization pulse for the parallel output. When $\overline{CS}$ is low, this serves as output enable and puts the previous conversion results on the bus.		
+VA	7, 10, 16, 21, 22, 25	−	Analog power supplies, 5-V DC		
+VBD	1, 36	−	Digital power supply for bus		

TYPICAL CHARACTERISTICS

DC HISTOGRAM
(8192 Conversion Outputs, Code Transition)
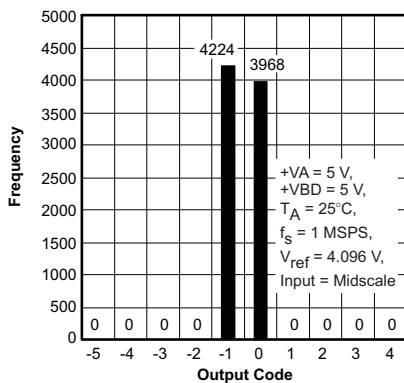
Figure 1.

DC HISTOGRAM
(8192 Conversion Outputs, Center of Code)
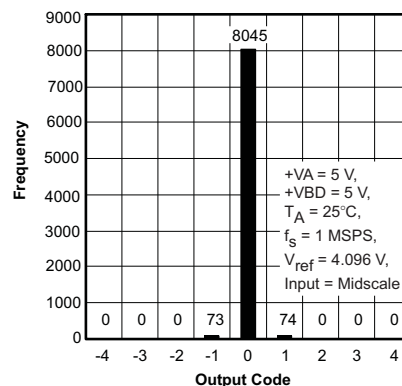
Figure 2.

INTERNAL REFERENCE VOLTAGE
vs
FREE-AIR TEMPERATURE
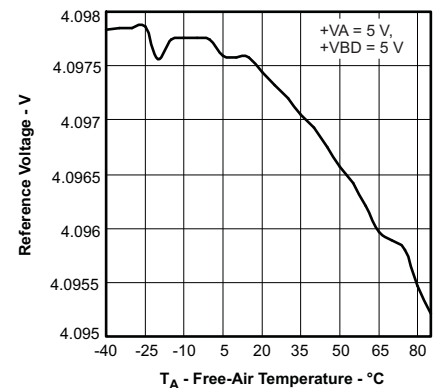
Figure 3.

INTERNAL REFERENCE VOLTAGE
vs
SUPPLY VOLTAGE
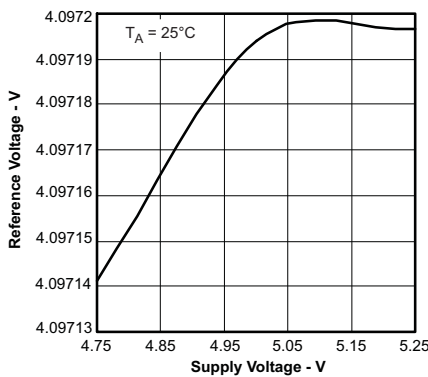
Figure 4.

SUPPLY CURRENT
vs
FREE-AIR TEM PERATURE
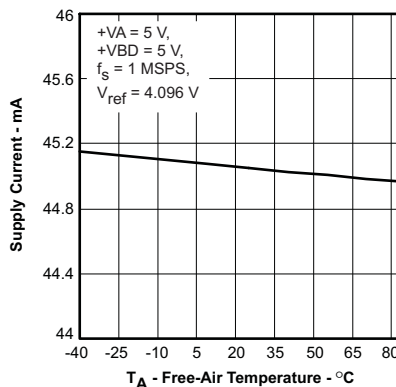
Figure 5.

SUPPLY CURRENT
vs
SUPPLY VOLTAGE
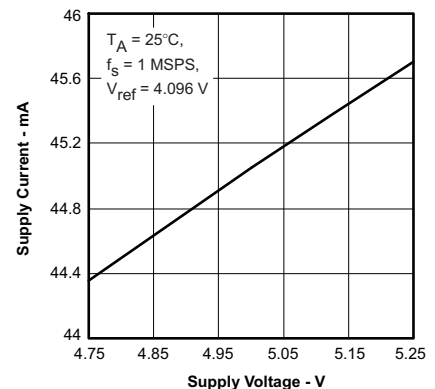
Figure 6.

TYPICAL CHARACTERISTICS (continued)
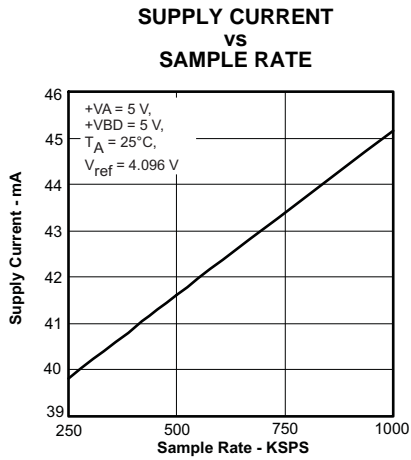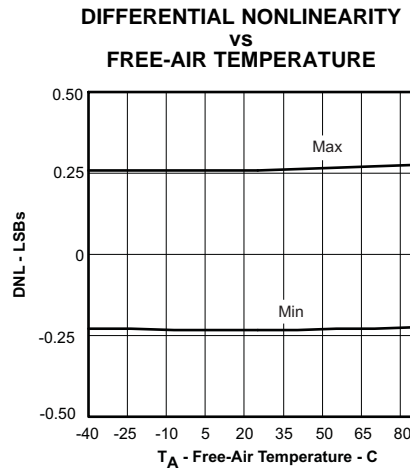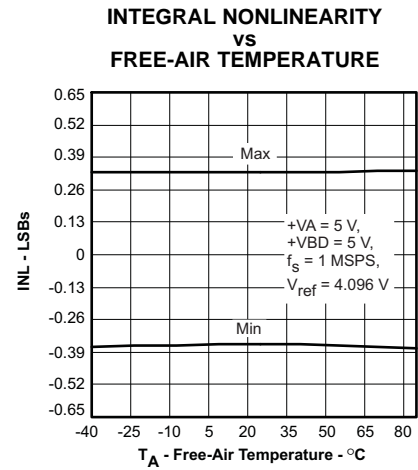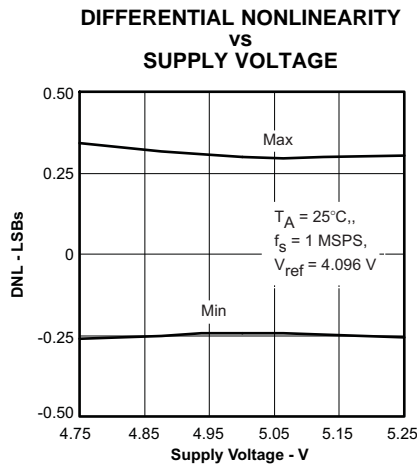
**SUPPLY CURRENT
vs
SAMPLE RATE**

Figure 7.

**DIFFERENTIAL NONLINEARITY
vs
FREE-AIR TEMPERATURE**

Figure 8.

**INTEGRAL NONLINEARITY
vs
FREE-AIR TEMPERATURE**

Figure 9.

**DIFFERENTIAL NONLINEARITY
vs
SUPPLY VOLTAGE**

Figure 10.

**INTEGRAL NONLINEARITY
vs
SUPPLY VOLTAGE**

Figure 11.

**DIFFERENTIAL NONLINEARITY
vs
REFERENCE VOLTAGE**

Figure 12.

**INTEGRAL NONLINEARITY
vs
REFERENCE VOLTAGE**

Figure 13.

**OFFSET ERROR
vs
FREE-AIR TEMPERATURE**

Figure 14.

**OFFSET ERROR
vs
SUPPLY VOLTAGE**

Figure 15.

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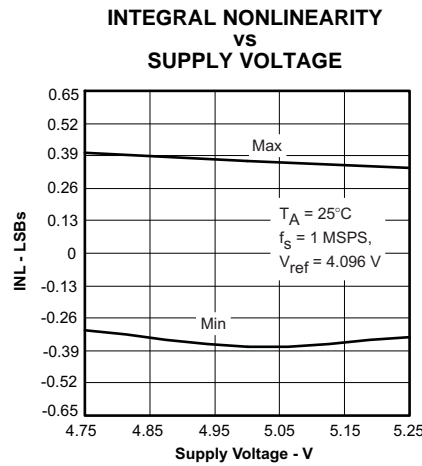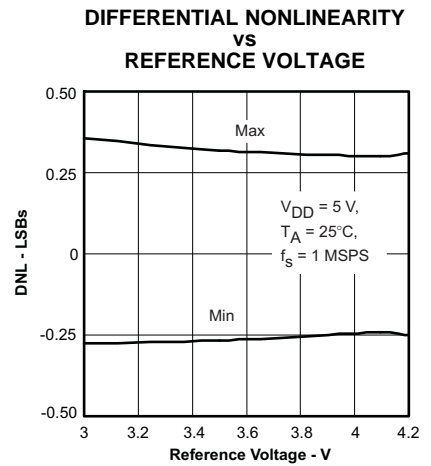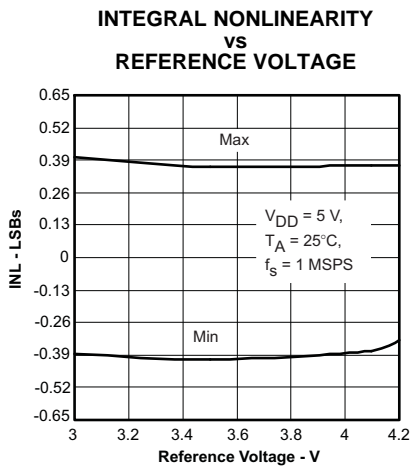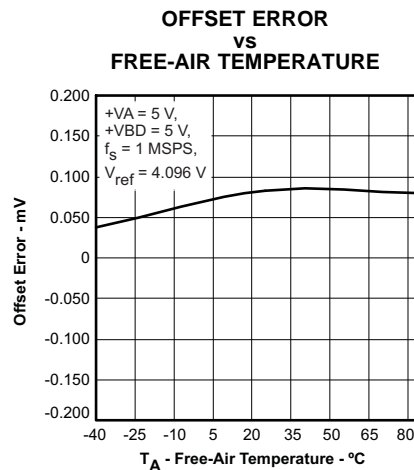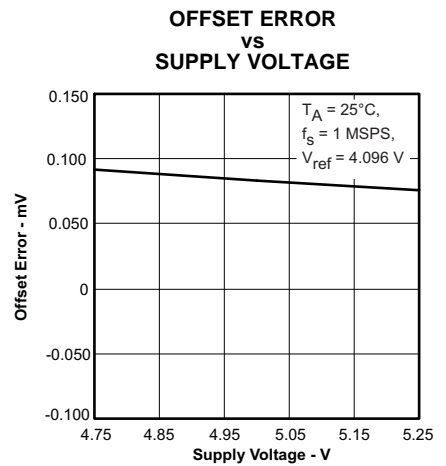
TYPICAL CHARACTERISTICS (continued)

OFFSET ERROR
vs
REFERENCE VOLTAGE

$T_A = 25\,°C$,
$f_S = 1$ MSPS,
$V_{DD} = 5$ V
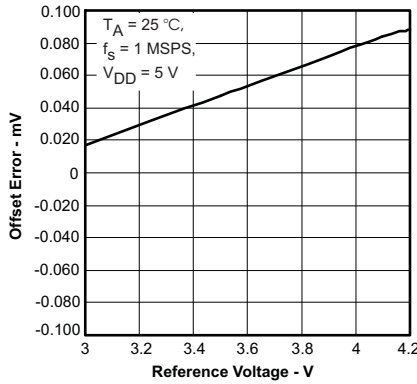
Figure 16.

GAIN ERROR
vs
SUPPLY VOLTAGE

$T_A = 25°C$,
$f_i = 1$ MSPS,
$V_{ref} = 4.096$
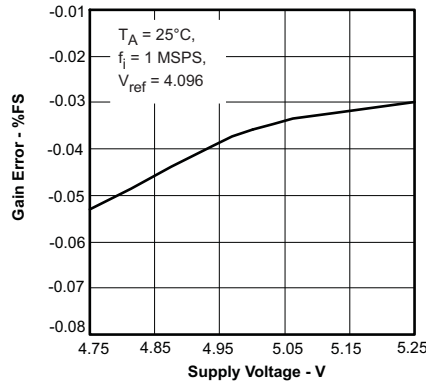
Figure 17.

GAIN ERROR
vs
FREE-AIR TEMPERATURE

+VA = 5 V,
+VBD = 5 V,
$f_S = 1$ MSPS,
$V_{ref} = 4.096$ V
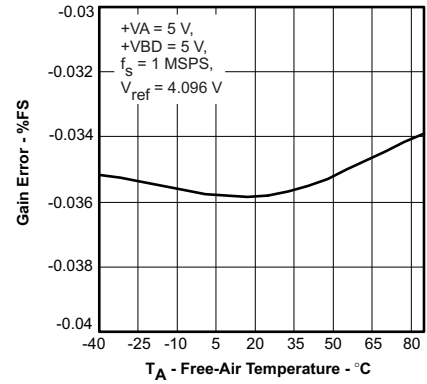
Figure 18.

GAIN ERROR
vs
REFERENCE VOLTAGE

$V_{DD} = 5$ V,
$T_A = 25°C$,
$f_S = 1$ MSPS
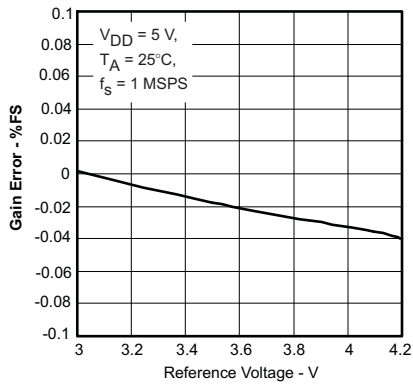
Figure 19.

OFFSET ERROR TEMPERATURE
DRIFT DISTRIBUTION (35 Samples)

+VA = 5 V,
+VBD = 5 V,
$f_i = 1$ MSPS,
$V_{ref} = 4.096$ V
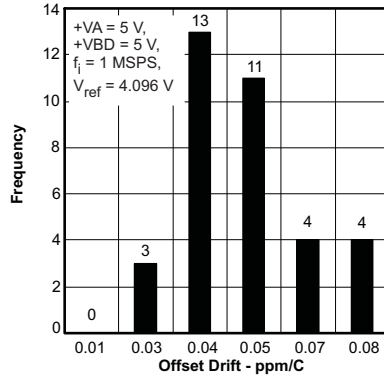
Figure 20.

GAIN ERROR TEMPERATURE
DRIFT DISTRIBUTION (35 Samples)

+VA = 5 V,
+VBD = 5 V,
$f_i = 1$ MSPS,
$V_{ref} = 4.096$ V
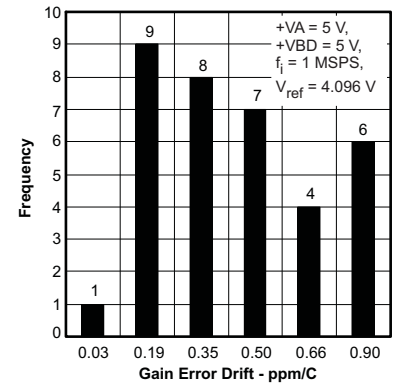
Figure 21.

TOTAL HARMONIC DISTORTION
vs
REFERENCE VOLTAGE

+VA = 5 V,
+VBD = 5 V,
$f_S = 1$ MSPS,
$T_A = 25°C$,
$f_i = 2$ kHz
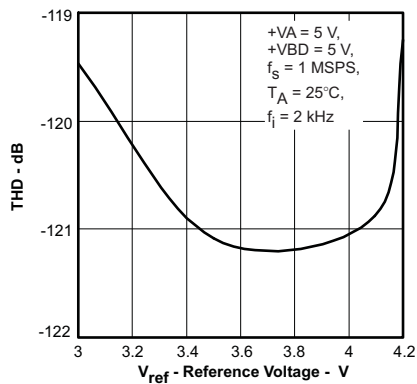
Figure 22.

SIGNAL-TO-NOISE RATIO
vs
REFERENCE VOLTAGE

+VA = 5 V,
+VBD = 5 V,
$f_S = 1$ MSPS,
$T_A = 25°C$,
$f_i = 2$ kHz
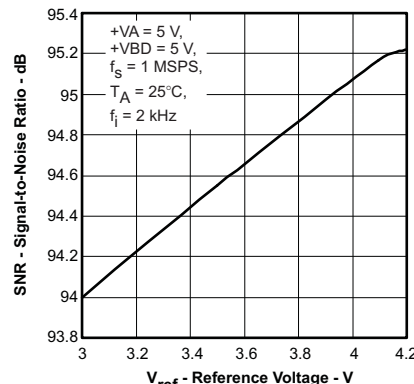
Figure 23.

SIGNAL-TO-NOISE + DISTORTION
vs
REFERENCE VOLTAGE

+VA = 5 V,
+VBD = 5 V,
$f_S = 1$ MSPS,
$T_A = 25°C$,
$f_i = 2$ kHz

Figure 24.

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TYPICAL CHARACTERISTICS (continued)

**TOTAL HARMONIC DISTORTION
vs
FREE-AIR TEMPERATURE**

+VA = 5 V,
+VBD = 5 V,
f_S = 1 MSPS,
V_{ref} = 4.096 V,
f_i = 2 kHz

THD - Total Harmonic Distortion - dB

T_A - Free-Air Temperature - °C

Figure 25.

**SPURIOUS FREE DYNAMIC RANGE
vs
FREE-AIR TEMPERATURE**

+VA = 5 V,
+VBD = 5 V,
f_S = 1 MSPS,
T_A = 25°C,
f_i = 2 kHz

SFDR - Spurious Free Dynamic Range - dB

T_A - Free-Air Temperature - °C

Figure 26.

**SIGNAL-TO-NOISE RATIO
vs
FREE-AIR TEMPERATURE**

+VA = 5 V,
+VBD = 5 V,
f_S = 1 MSPS,
V_{ref} = 4.096 V,
f_i = 2 kHz

SNR - Signal-to-Noise Ratio - dB

T_A - Free-Air Temperature - °C

Figure 27.

**SIGNAL-TO-NOISE + DISTORTION
vs
FREE-AIR TEMPERATURE**

+VA = 5 V,
+VBD = 5 V,
f_S = 1 MSPS,
V_{ref} = 4.096 V,
f_i = 2 kHz

SINAD - Signal-to-Noise + Distortion - dB

T_A - Free-Air Temperature - °C

Figure 28.

DNL

+VA = 5 V, +VBD = 5 V, T_A = 25°C, f_S = 1 MSPS, V_{ref} = 4.096 V

DNL - LSBs

Output Code

Figure 29.

TYPICAL CHARACTERISTICS (continued)

INL

+VA = 5 V, +VBD = 5 V, T_A = 25°C, f_s = 1 MSPS, V_{ref} = 4.096 V

INL - LSBs

Output Code

Figure 30.

FFT

+VA = 5 V, +VBD = 5 V, T_A = 25°C, f_s = 1 MSPS, V_{ref} = 4.096 V, f_i = 20 kHz, 65536 Points, G = 8 V_{PP}

Amplitude - dB

f - Frequency - Hz
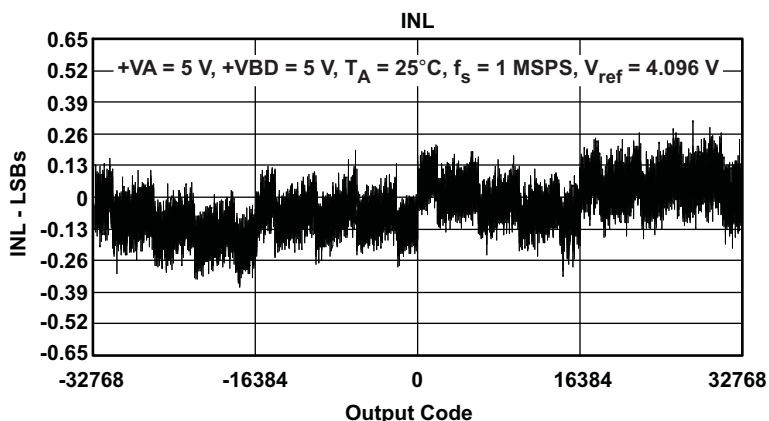
Figure 31.

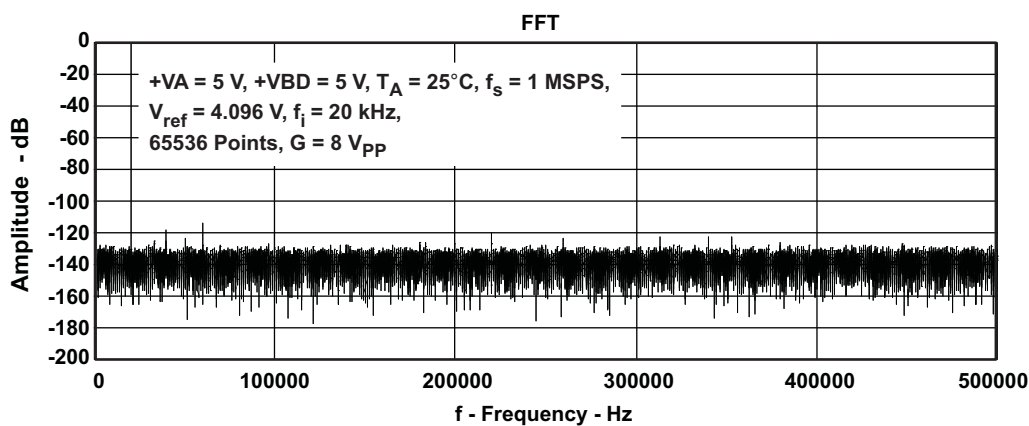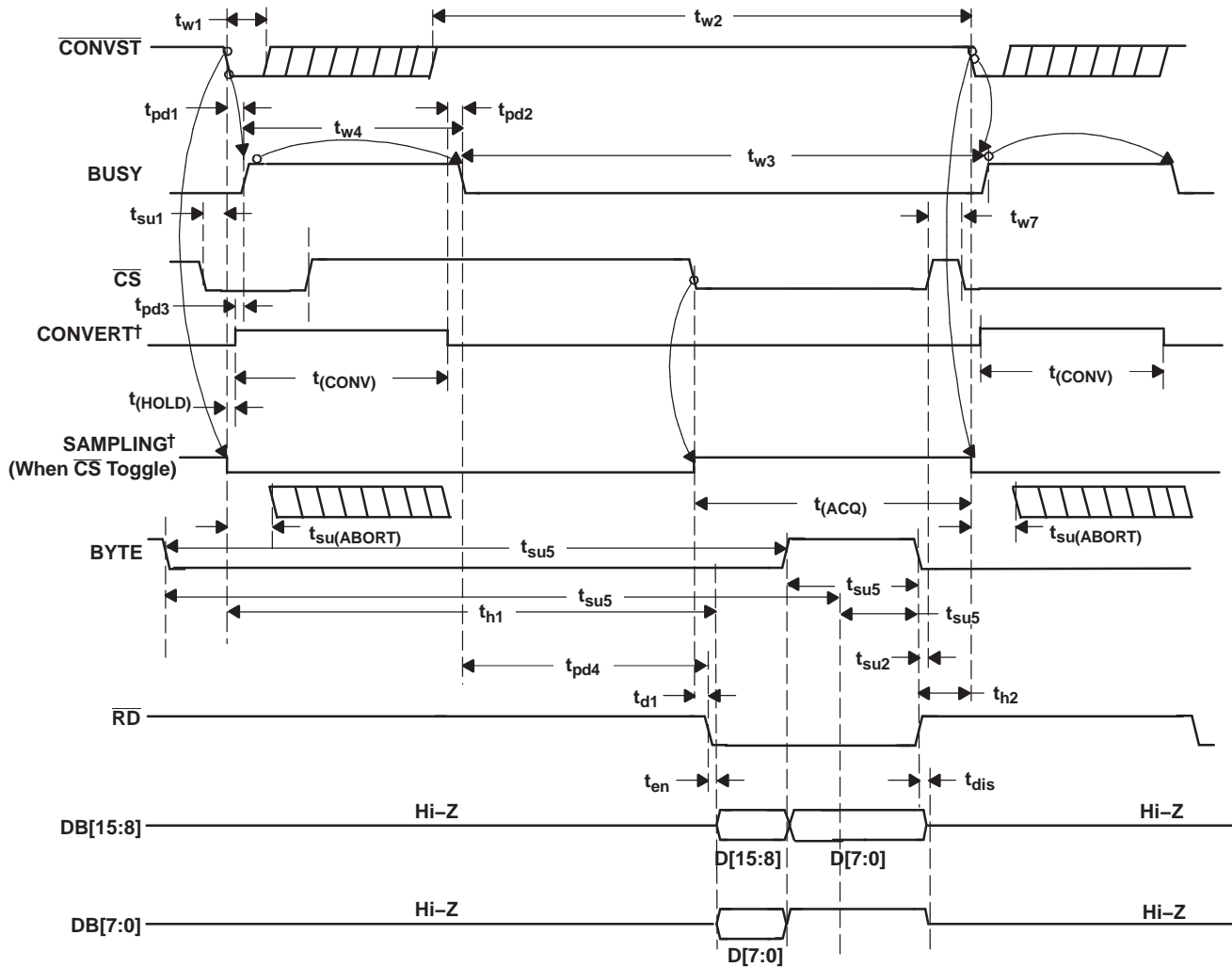## TYPICAL CHARACTERISTICS (continued)

TIMING DIAGRAMS

†Signal internal to device

Figure 32. Timing for Conversion and Acquisition Cycles With $\overline{CS}$ and $\overline{RD}$ Toggling

TYPICAL CHARACTERISTICS (continued)

†Signal internal to device

Figure 33. Timing for Conversion and Acquisition Cycles With $\overline{CS}$ Toggling, $\overline{RD}$ Tied to BDGND

TYPICAL CHARACTERISTICS (continued)

†Signal internal to device

Figure 34. Timing for Conversion and Acquisition Cycles With $\overline{CS}$ Tied to BDGND, $\overline{RD}$ Toggling
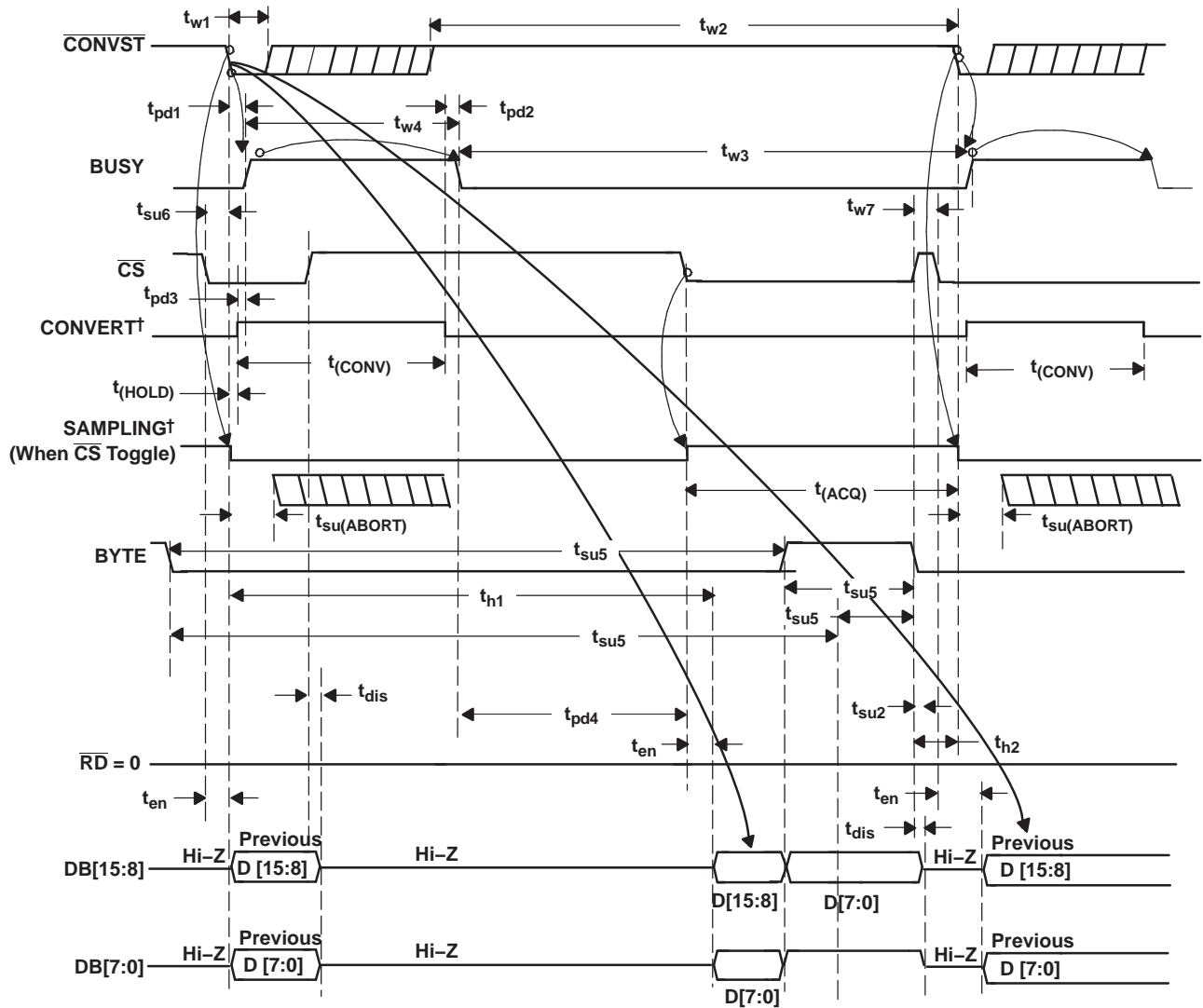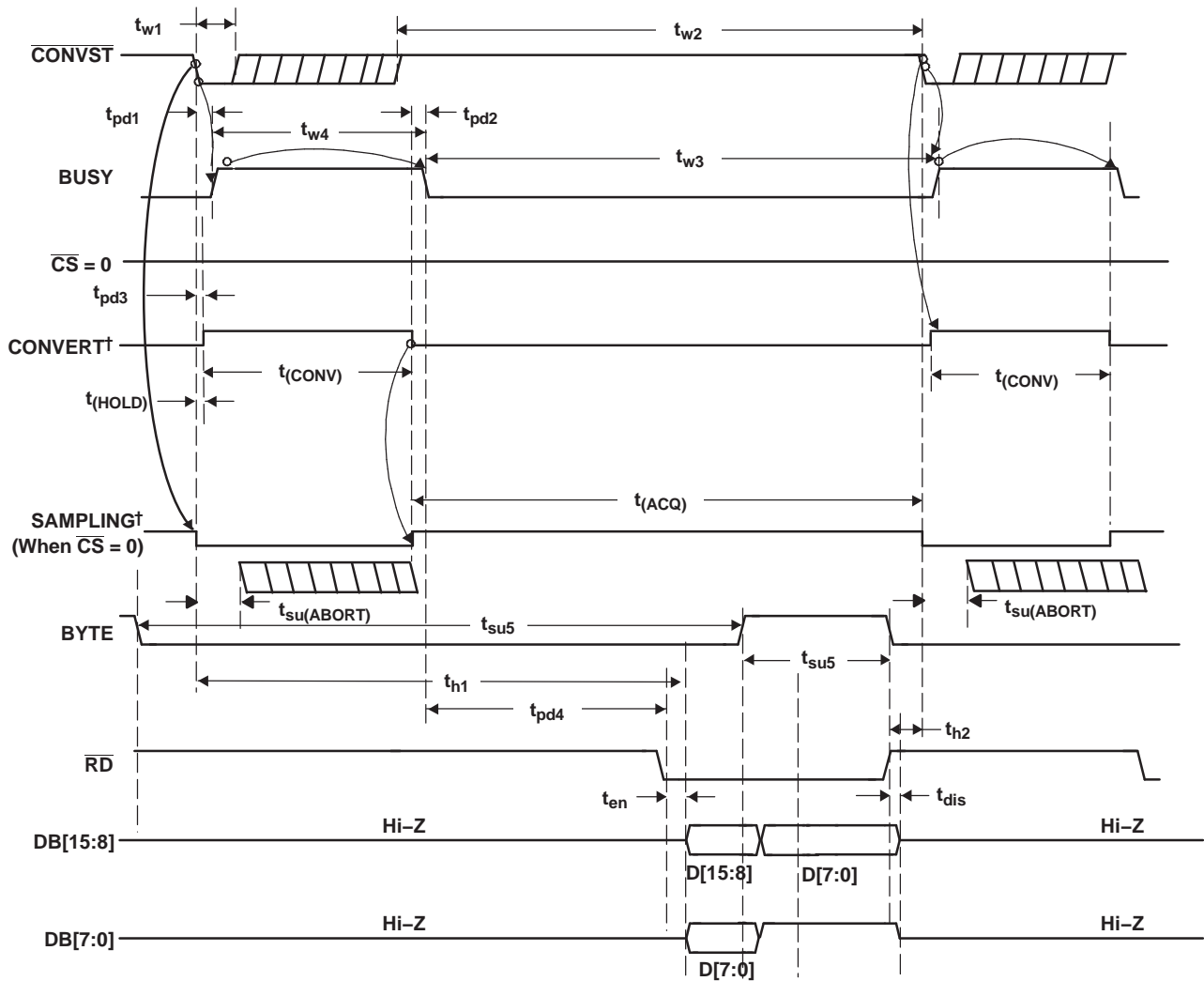
TYPICAL CHARACTERISTICS (continued)
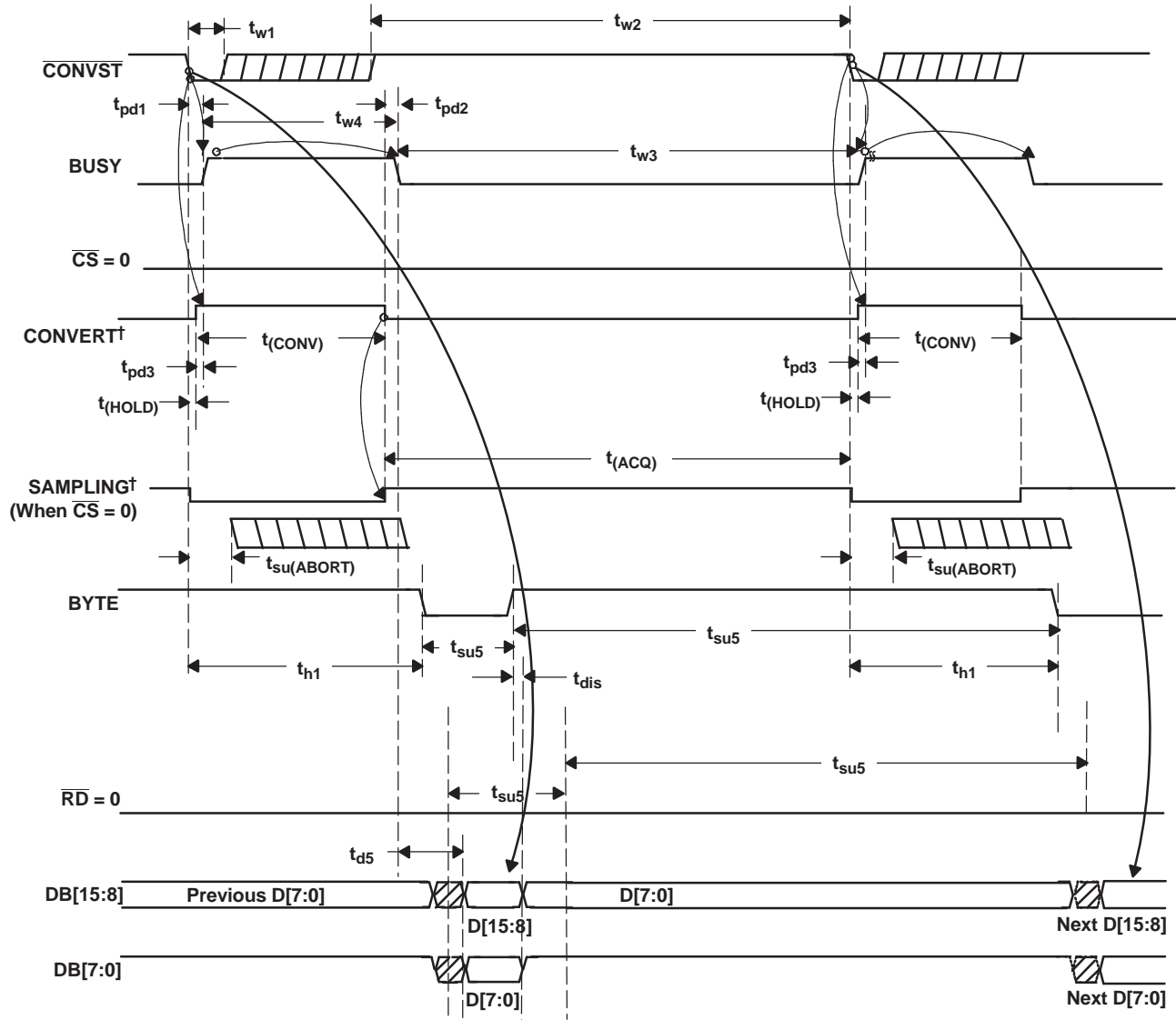

†Signal internal to device

Figure 35. Timing for Conversion and Acquisition Cycles With $\overline{CS}$ and $\overline{RD}$ Tied to BDGND - Auto Read

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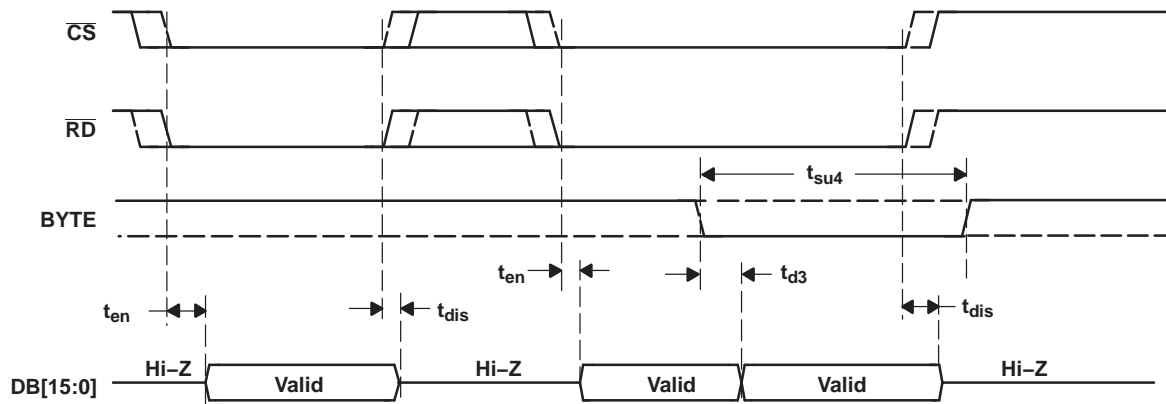www.ti.com

TYPICAL CHARACTERISTICS (continued)

Figure 36. Detailed Timing for Read Cycles

APPLICATION INFORMATION

ADS8472 TO A HIGH PERFORMANCE DSP INTERFACE

Figure 37 shows a parallel interface between the ADS8472 and a Texas instruments high performance DSP such as the TMS320C6713 using the full 16-bit bus. The ADS8472 is mapped onto the $\overline{CE2}$ memory space of the TMS320C6713 DSP. The read and reset signals are generated by using a 3-to-8 decoder. A read operation from the address 0xA000C000 generates a pulse on the $\overline{RD}$ pin of the data converter, wheras a read operation form word address 0xA0014000 generates a pulse on the $\overline{RESET}/\overline{PD1}$ pin. The $\overline{CE2}$ signal of the DSP acts as $\overline{CS}$ (chip select) for the converter. As the TMS320C6713 features a 32-bit external memory interface, the BYTE input of the converter can be tied permanently low, disabling the foldback of the data bus. The BUSY signal of the ADS8472 is appiled to the $\overline{EXT\_INT6}$ interrupt input of the DSP, enabling the EDMA controller to react on the falling edge of this signal and to collect the conversion result. The TOUT1 (timer out 1) pin of the TMS320C6713 is used to source the $\overline{CONVST}$ signal of the converter.
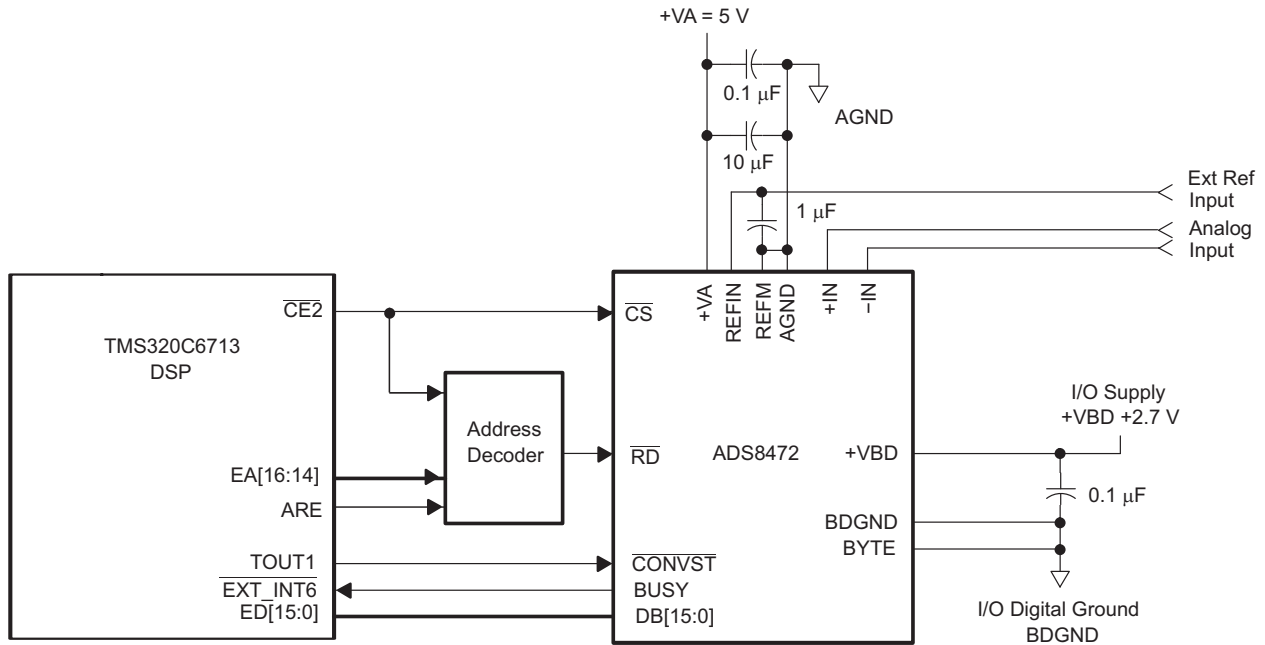
Figure 37. ADS8472 Application Circuitry
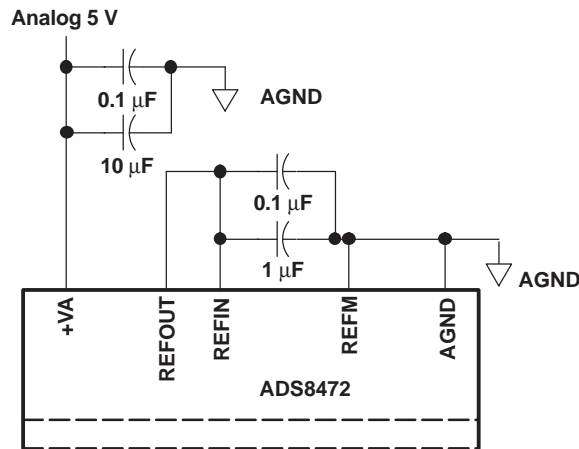
Figure 38. ADS8472 Using Internal Reference

PRINCIPLES OF OPERATION

The ADS8472 is a high-speed successive approximation register (SAR) analog-to-digital converter (ADC). The architecture is based on charge redistribution which inherently includes a sample/hold function. See Figure 37 for the application circuit for the ADS8472.

The conversion clock is generated internally. The conversion time of 650 ns is capable of sustaining a 1 MHz throughput.

The analog input is provided to two input pins: +IN and –IN. When a conversion is initiated, the differential input on these pins is sampled on the internal capacitor array. While a conversion is in progress, both inputs are disconnected from any internal function.

REFERENCE

The ADS8472 can operate with an external reference with a range from 3.0 V to 4.2 V. The reference voltage on the input pin #13 (REFIN) of the converter is internally buffered. A clean, low noise, well-decoupled reference voltage on this pin is required to ensure good performance of the converter. A low noise band-gap reference like the REF3240 can be used to drive this pin. A 0.1-μF decoupling capacitor is required between REFIN and REFM pins (pin #13 and pin #12) of the converter. This capacitor should be placed as close as possible to the pins of the device. Designers should strive to minimize the routing length of the traces that connect the terminals of the capacitor to the pins of the converter. An RC network can also be used to filter the reference voltage. A 100-Ω series resistor and a 0.1-μF capacitor, which can also serve as the decoupling capacitor can be used to filter the reference voltage.
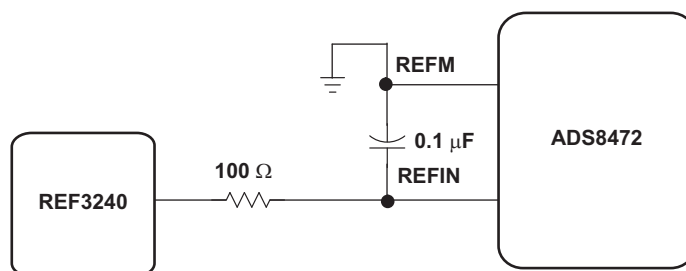
Figure 39. ADS8472 Using External Reference

The ADS8472 also has limited low pass filtering capability built into the converter. The equivalent circuitry on the REFIN input ia as shown in Figure 40.
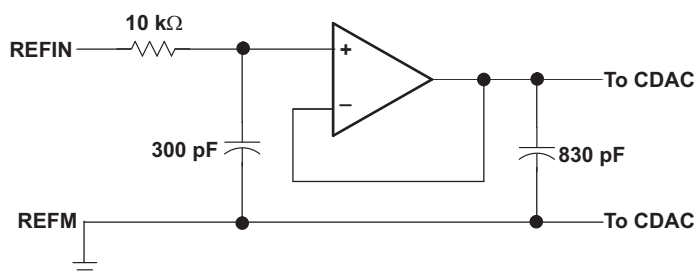
Figure 40. Simplified Reference Input Circuit

The REFM input of the ADS8472 should always be shorted to AGND. A 4.096-V internal reference is included. When internal reference is used, pin 14 (REFOUT) is connected to pin 13 (REFIN) with an 0.1-μF decoupling capacitor and 1-μF storage capacitor between pin 14 (REFOUT) and pins 11 and 12 (REFM) (see Figure 38). The internal reference of the converter is double buffered. If an external reference is used, the second buffer provides isolation between the external reference and the CDAC. This buffer is also used to recharge all of the capacitors of the CDAC during conversion. Pin 14 (REFOUT) can be left unconnected (floating) if external reference is used.

PRINCIPLES OF OPERATION (continued)

ANALOG INPUT

When the converter enters the hold mode, the voltage difference between the +IN and −IN inputs is captured on the internal capacitor array. Both +IN and −IN input has a range of −0.2 V to Vref + 0.2 V. The input span [+IN − (−IN)] is limited to −V_{ref} to V_{ref}.

The input current on the analog inputs depends upon a number of factors: sample rate, input voltage, and source impedance. Essentially, the current into the ADS8472 charges the internal capacitor array during the sample period. After this capacitance has been fully charged, there is no further input current. The source of the analog input must be able to charge the input capacitance (65 pF) to an 16-bit settling level within the acquisition time (320 ns) of the device. When the converter goes into the hold mode, the input impedance is greater than 1 GΩ.

Care must be taken regarding the absolute analog input voltage. To maintain the linearity of the converter, the +IN and −IN inputs and the span [+IN − (−IN)] must be within the limits specified. Outside of these ranges, the converter's linearity may not meet specifications. To minimize noise, low bandwidth input signals with low-pass filters are used.

Care must be taken to ensure that the output impedance of the sources driving the +IN and −IN inputs are matched. If this is not observed, the two inputs could have different setting times. This may result in offset error, gain error, and linearity error which varies with temperature and input voltage.

The analog input to the converter needs to be driven with a low noise, high-speed op-amp like the THS4031. An RC filter is recommended at the input pins to low-pass filter the noise from the source. The input to the converter is a uni-polar input voltage in the range 0 to V_{ref}. The THS4031 can be used in the source follower configuration to drive the converter.

PRINCIPLES OF OPERATION (continued)
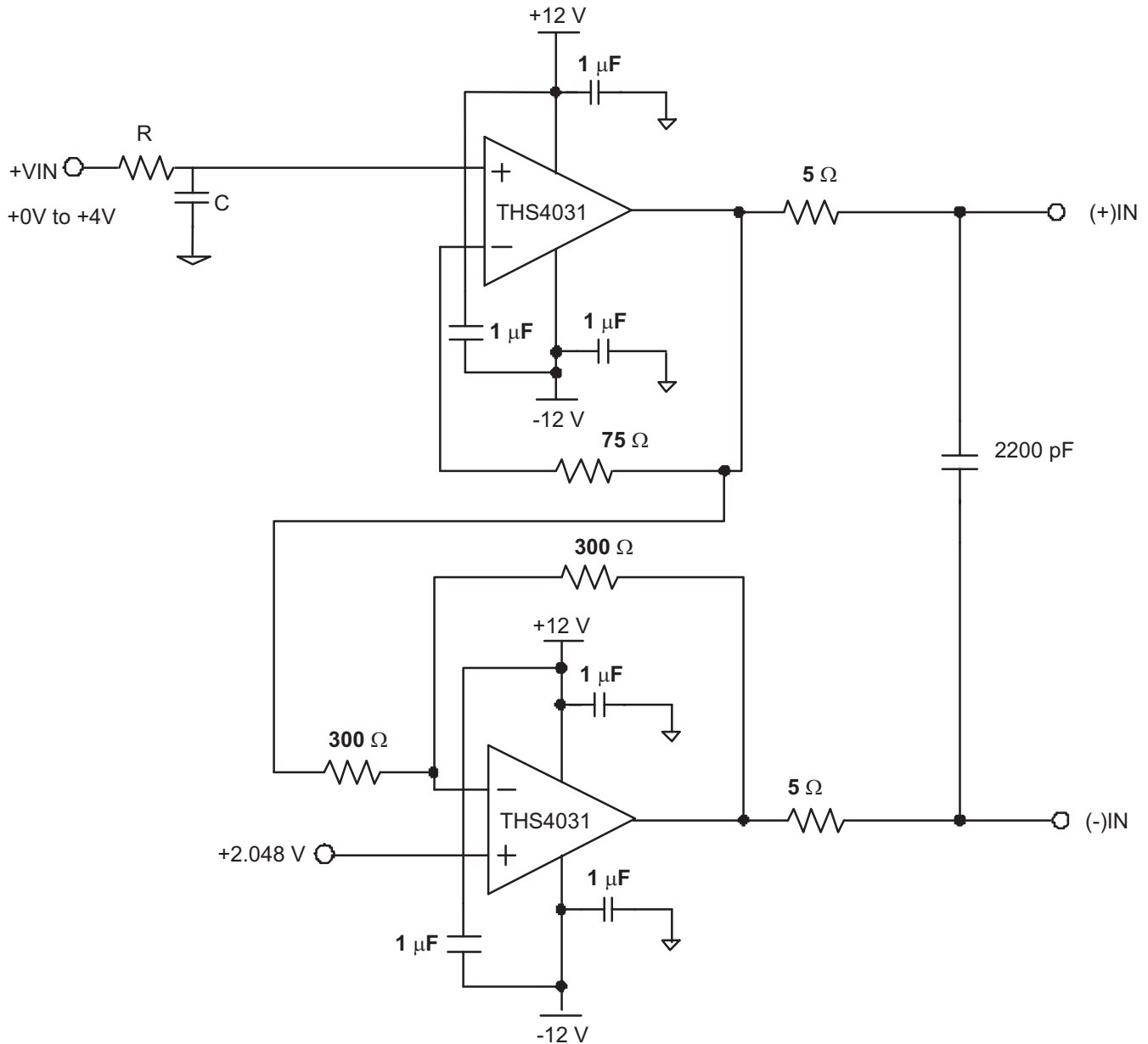
Figure 41. Single-Ended Input, Differential Output Configuration

In systems, where the input is differential, the THS4031 can be used in the inverting configuration with an additional DC bias applied to its + input so as to keep the input to the ADS8472 within its rated operating voltage range. The DC bias can be derived from the REF3220 or the REF3240 reference voltage ICs. The input configuration shown below is capable of delivering better than 97dB SNR and -103db THD at an input frequency of 100 kHz. In case band-pass filters are used to filter the input, care should be taken to ensure that the signal swing at the input of the band-pass filter is small so as to keep the distortion introduced by the filter minimal. In such cases, the gain of the circuit shown below can be increased to keep the input to the ADS8472 large to keep the SNR of the system high. Note that the gain of the system from the + input to the output of the THS4031 in such a configuration is a function of the gain of the AC signal. A resistor divider can be used to scale the output of the REF3220 or REF3240 to reduce the voltage at the DC input to THS4031 to keep the voltage at the input of the converter within its rated operating range.

PRINCIPLES OF OPERATION (continued)

Figure 42. Differential Input, Differential Output Configuration

DIGITAL INTERFACE

Timing and Control

See the timing diagrams in the specifications section for detailed information on timing signals and their requirements.

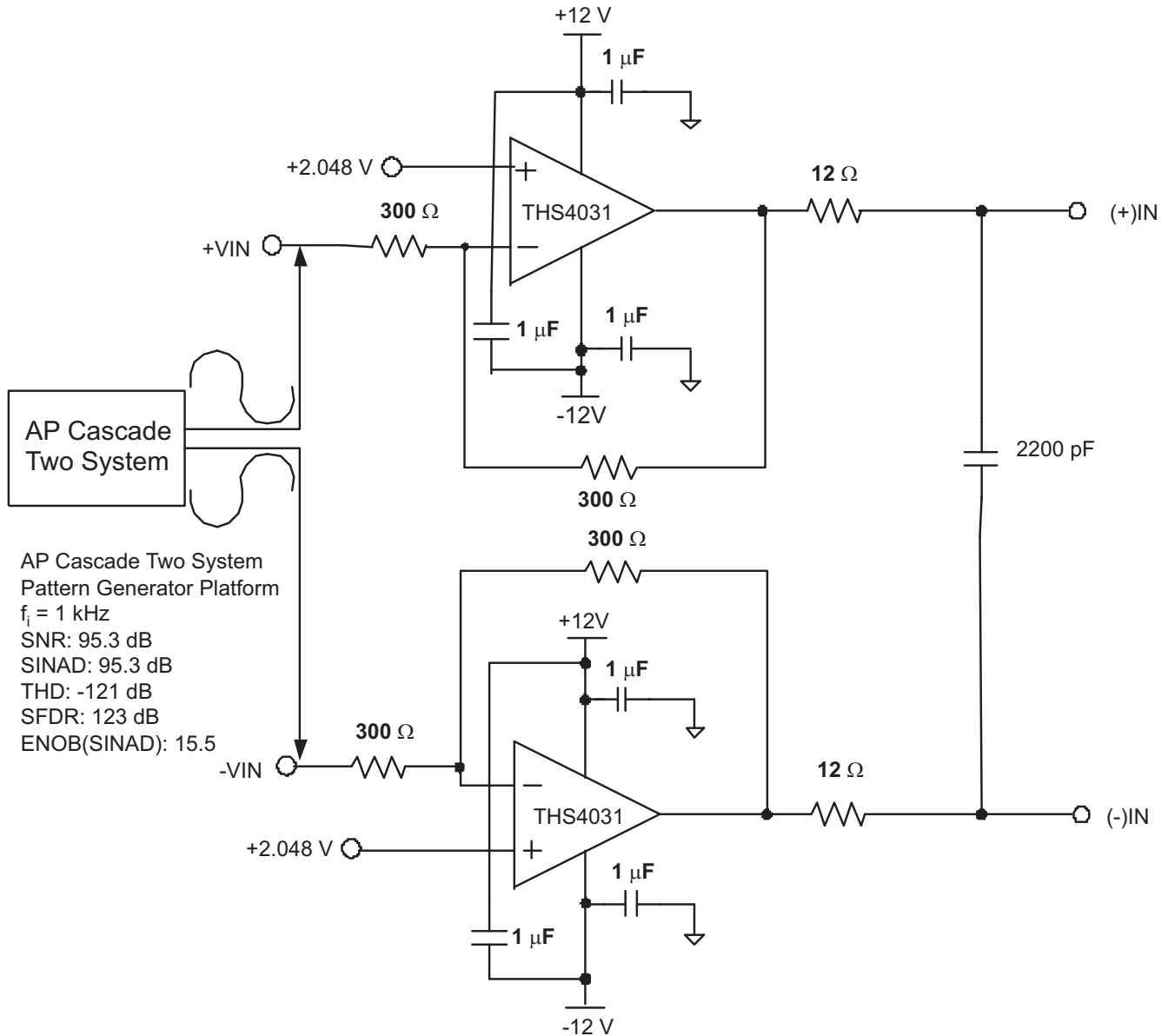The ADS8472 uses an internal oscillator generated clock which controls the conversion rate and in turn the throughput of the converter. No external clock input is required.

PRINCIPLES OF OPERATION (continued)

Conversions are initiated by bringing the $\overline{\text{CONVST}}$ pin low for a minimum of 20 ns (after the 20 ns minimum requirement has been met, the $\overline{\text{CONVST}}$ pin can be brought high), while $\overline{\text{CS}}$ is low. The ADS8472 switches from the sample to the hold mode on the falling edge of the $\overline{\text{CONVST}}$ command. A clean and low jitter falling edge of this signal is important to the performance of the converter. The BUSY output is brought high immediately following $\overline{\text{CONVST}}$ going low. BUSY stays high throughout the conversion process and returns low when the conversion has ended.

Sampling starts with the falling edge of the BUSY signal when $\overline{\text{CS}}$ is tied low or starts with the falling edge of $\overline{\text{CS}}$ when BUSY is low.

Both $\overline{\text{RD}}$ and $\overline{\text{CS}}$ can be high during and before a conversion with one exception ($\overline{\text{CS}}$ must be low when $\overline{\text{CONVST}}$ goes low to initiate a conversion). Both the $\overline{\text{RD}}$ and $\overline{\text{CS}}$ pins are brought low in order to enable the parallel output bus with the conversion.

Reading Data

The ADS8472 outputs full parallel data in straight binary format as shown in Table 1. The parallel output is active when $\overline{\text{CS}}$ and $\overline{\text{RD}}$ are both low. There is a minimal quiet zone requirement around the falling edge of $\overline{\text{CONVST}}$. This is 50 ns prior to the falling edge of $\overline{\text{CONVST}}$ and 40 ns after the falling edge. No data read should attempted within this zone. Any other combination of $\overline{\text{CS}}$ and $\overline{\text{RD}}$ sets the parallel output to 3-state. BYTE is used for multiword read operations. BYTE is used whenever lower bits on the bus are output on the higher byte of the bus. Refer to Table 1 for ideal output codes.

Table 1. Ideal Input Voltages and Output Codes

DESCRIPTION	ANALOG VALUE	DIGITAL OUTPUT STRAIGHT BINARY	
Full scale range	$+V_{ref}$		
Least significant bit (LSB)	$2 \times (+V_{ref})/65536$	**BINARY CODE**	**HEX CODE**
+Full scale	$(+V_{ref}) - 1$ LSB	0111 1111 1111 1111	1FFF
Midscale	0 V	0000 0000 0000 0000	0000
Midscale − 1 LSB	0 V − 1 LSB	1111 1111 1111 1111	3FFF
Zero	$-V_{ref}$	1000 0000 0000 0000	2000

The output data is a full 16-bit word (D15–D0) on DB15–DB0 pins (MSB–LSB) if BYTE is low.

The result may also be read on an 8-bit bus for convenience. This is done by using only pins DB15–DB8. In this case two reads are necessary: the first as before, leaving BYTE low and reading the 8 most significant bits on pins DB15–DB8, then bringing BYTE high. When BYTE is high, the low bits (D7–D0) appear on pins DB15–DB8.

All of these multiword read operations can be performed with multiple active $\overline{\text{RD}}$ (toggling) or with $\overline{\text{RD}}$ held low for simplicity. This is referred to as the AUTO READ operation.

Table 2. Conversion Data Read Out

BYTE	DATA READ OUT	
	PINS DB15–DB8	**PINS DB7–DB0**
High	D7–D0	All One's
Low	D15–D8	D7–D0

RESET

On power-up, internal POWER-ON RESET circuitry generates the reset required for the device. The first three conversions after power-up are used to load factory trimming data for a specific device to assure high accuracy of the converter. The results of the first three conversions are invalid and should be discarded.

The device can also be reset through the use of the combination fo $\overline{\text{CS}}$ and $\overline{\text{CONVST}}$. Since the BUSY signal is held at high during the conversion, either one of these conditions triggers an internal self-clear reset to the converter.

- Issue a $\overline{\text{CONVST}}$ when $\overline{\text{CS}}$ is low and the internal convert state is high. The falling edge of $\overline{\text{CONVST}}$ starts a reset.
- Issue a $\overline{\text{CS}}$ (select the device) while the internal convert state is high. The falling edge of $\overline{\text{CS}}$ causes a reset.

Once the device is reset, all output latches are cleared (set to zeroes) and the BUSY signal is brought low. A new sampling period is started at the falling edge of the BUSY signal immediately after the instant of the internal reset.

LAYOUT

For optimum performance, care must be taken with the physical layout of the ADS8472 circuitry.

As the ADS8472 offers single-supply operation, it is often used in close proximity with digital logic, microcontrollers, microprocessors, and digital signal processors. The more digital logic present in the design and the higher the switching speed, the more difficult it is to achieve good performance from the converter.

The basic SAR architecture is sensitive to glitches or sudden changes on the power supply, reference, ground connections and digital inputs that occur just prior to latching the output of the analog comparator. Thus, driving any single conversion for an n-bit SAR converter, there are at least n windows in which large external transient voltages can affect the conversion result. Such glitches might originate from switching power supplies, nearby digital logic, or high power devices.

The degree of error in the digital output depends on the reference voltage, layout, and the exact timing of the external event.

On average, the ADS8472 draws very little current from an external reference as the reference voltage is internally buffered. If the reference voltage is external and originates from an op amp, make sure that it can drive the bypass capacitor or capacitors without oscillation. A 0.1-µF capacitor is recommended from pin 13 (REFIN) directly to pin 12 (REFM). REFM and AGND must be shorted on the same ground plane under the device.

The AGND and BDGND pins should be connected to a clean ground point. In all cases, this should be the analog ground. Avoid connections which are too close to the grounding point of a microcontroller or digital signal processor. If required, run a ground trace directly from the converter to the power supply entry point. The ideal layout consists of an analog ground plane dedicated to the converter and associated analog circuitry.

As with the AGND connections, +VA should be connected to a 5-V power supply plane or trace that is separate from the connection for digital logic until they are connected at the power entry point. Power to the ADS8472 should be clean and well bypassed. A 0.1-µF ceramic bypass capacitor should be placed as close to the device as possible. See Table 3 for the placement of the capacitor. In addition, a 1-µF to 10-µF capacitor is recommended. In some situations, additional bypassing may be required, such as a 100-µF electrolytic capacitor or even a Pi filter made up of inductors and capacitors-all designed to essentially low-pass filter the 5-V supply, removing the high frequency noise.

Table 3. Power Supply Decoupling Capacitor Placement

POWER SUPPLY PLANE SUPPLY PINS	CONVERTER ANALOG SIDE	CONVERTER DIGITAL SIDE
Pin pairs that require shortest path to decoupling capacitors	(7,8), (9,10), (16,17), (20,21), (22,23), (25,26)	(36,37)
Pins that require no decoupling	24, 26	(1,2)

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
ADS8472IBRGZT	NRND	Production	VQFN (RGZ) | 48	250 | SMALL T&R	Yes	Call TI	Level-2-260C-1 YEAR	-40 to 85	ADS 8472I B
ADS8472IBRGZT.A	NRND	Production	VQFN (RGZ) | 48	250 | SMALL T&R	Yes	Call TI	Level-2-260C-1 YEAR	-40 to 85	ADS 8472I B

(1) Status: For more details on status, see our product life cycle.

(2) Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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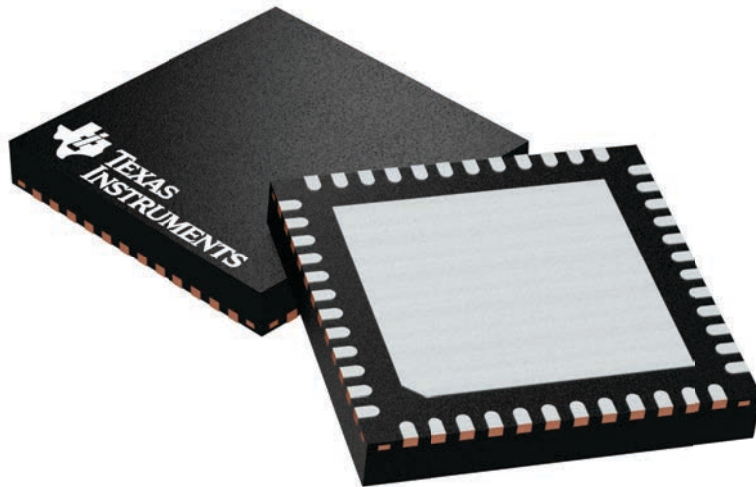
Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4224671/A

B

7.1
6.9

A

PIN 1 INDEX AREA

(0.1) TYP

SIDE WALL DETAIL
OPTIONAL METAL THICKNESS

7.1
6.9

(0.45) TYP

CHAMFERED LEAD
CORNER LEAD OPTION

1 MAX

C

SEATING PLANE

0.05
0.00

⌒ 0.08 C

2X 5.5

☐ 5.15±0.1

(0.2) TYP

44X 0.5

13

24

12

25

SEE SIDE WALL
DETAIL

2X
5.5

SYMM
℄

1

PIN1 ID
(OPTIONAL)

48

36

48X 0.30
0.18

SEE LEAD OPTION

SYMM
℄

37

⊕ 0.1 Ⓜ C A B
0.05 Ⓜ C

48X 0.5
0.3

4219044/D   02/2022

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.

2X (6.8)

(□5.15)
SYMM

48X (0.6)

48X (0.24)

44X (0.5)

48 37

1

36

2X (5.5)

SYMM

2X (6.8)

2X (1.26)

(R0.05) TYP

2X (1.065)

12

25

21X (Ø0.2) VIA TYP

13 24 2X (1.065)

2X (1.26)

2X (5.5)

LAND PATTERN EXAMPLE
SCALE: 15X

0.07 MAX
ALL AROUND

0.07 MIN
ALL AROUND

SOLDER MASK
OPENING

EXPOSED METAL

METAL

EXPOSED METAL

SOLDER MASK
OPENING

NON SOLDER MASK
DEFINED
(PREFERRED)

METAL UNDER
SOLDER MASK

SOLDER MASK
DEFINED

SOLDER MASK DETAILS

4219044/D   02/2022

NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD
67% PRINTED COVERAGE BY AREA
SCALE: 15X

4219044/D   02/2022

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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