

Technical documentation



Support & training

ADC3681, ADC3682, ADC3683 SBAS872B - DECEMBER 2020 - REVISED OCTOBER 2022

# ADC368x 18-bit 0.5 to 65-MSPS Low Noise Ultra-low Power Dual Channel ADC

# 1 Features

Texas

**Dual channel ADC** 

INSTRUMENTS

- 18-bit 10, 25, 65 MSPS ADC
- Noise floor: -160 dBFS/Hz
- Low power and optimized power scaling: ٠ 53 mW/ch (10 MSPS) to 94 mW/ch (65 MSPS)
- Latency: 1-2 clock cycles
- 18-bit, no missing codes •
- INL/DNL: ±7/ ±0.7 LSB (typical) •
- Reference: external or internal
- Input bandwidth: 900 MHz (3-dB)
- Industrial temperature range: -40 to +105°C
- On-chip digital filter (optional)
  - Decimation by 2, 4, 8, 16, 32
  - \_ 32-bit NCO
- Serial LVDS digital interface (2-, 1- and 1/2-wire)
- Small footprint: 40-QFN (5x5 mm) package
- Spectral performance ( $f_{IN} = 5 \text{ MHz}$ ):
  - SNR: 83.8 dBFS
  - SFDR: 89 dBc HD2, HD3
  - SFDR: 101 dBFS Worst spur
- Spectral performance ( $f_{IN} = 20 \text{ MHz}$ ):
  - SNR: 82.6 dBFS
  - SFDR: 85 dBc HD2, HD3
  - SFDR: 97 dBFS Worst spur

# 2 Applications

- ٠ High-speed data acquisition
- Industrial monitoring
- Software defined radio •
- Power quality analyzer ٠
- Source measurement unit (SMU)
- **Communications infrastructure**
- Spectrum analyzer
- Control loops •
- Instrumentation •
- Imaging
- Spectroscopy
- Radar

# **3 Description**

The ADC3681, 82, 83 (ADC368x) is a low noise, ultralow power 18-bit 65 MSPS high-speed dual channel ADC family. Designed for lowest noise performance, it delivers a noise spectral density of -160 dBFS/Hz combined with excellent linearity and dynamic range. The ADC368x offers excellent DC precision together with IF sampling support which makes it suited for a wide range of applications. High-speed control loops benefit from the short latency as low as only 1 clock cycle. The ADC consumes only 94 mW/ch at 65 Msps and its power consumption scales well with lower sampling rates.

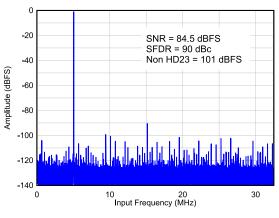
The ADC368x uses a serial LVDS (SLVDS) interface to output the data which minimizes the number of digital interconnects. The device supports two-lane, one-lane and half-lane options. The ADC36xx is a pin to pin compatible family of ADCs with 16 and 18-bit resolution and different speed grades. It comes in a 40-pin QFN package (5 x 5mm) and supports the extended industrial temperature range from -40 to +105°C.

#### **Package Information**

PART NUMBER	PACKAGE <sup>(1)</sup>	BODY SIZE (NOM)
ADC368x	VQFN (40)	5.00 mm x 5.00 mm

For all available packages, see the orderable addendum at (1) the end of the data sheet.

#### PART NUMBER RESOLUTION SAMPLING RATE ADC3683 18 BIT 65 MSPS ADC3682 18 BIT 25 MSPS ADC3681 18 BIT 10 MSPS



FFT: Fs = 65 MSPS, Fin = 5 MHz

**Device Comparison** 



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# **4 Revision History**

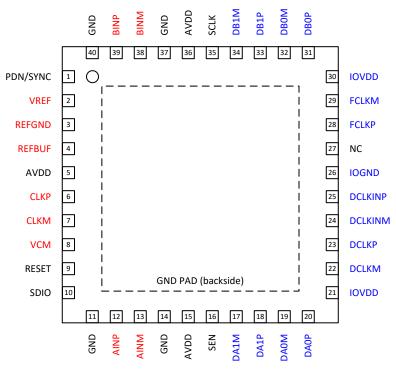
NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	hanges from Revision A (December 2021) to Revision B (October 2022)	Page
•	Removed the Product Preview note from part number ADC3681 in the Device Comparison table	1
•	Added the Typical Characteristics - ADC3681 graphs	14
	Added the Typical Characteristics - ADC3682 graphs	
	Added GND symbol to REFGND pin for all voltage reference option diagrams	
	Added the Output Bit Mapper section.	
	Added Table 8-11	
•	Changed Figure 9-6 diagram with correct indexing	72

С	hanges from Revision * (December 2020) to Revision A (December 2021)	Page
•	Removed the Product Preview note from part number ADC3682 in the Device Comparison table	1
•	Changed Sample N+1 position in Figure 7-2 and Figure 7-3	26
•	Added condition to resynch during operation to the SYNC section	41



# **5** Pin Configuration and Functions



### Figure 5-1. RSB (WQQFN) Package, 40-Pin (Top View)

### Table 5-1. Pin Descriptions

PI	N	I/O	Description
Name	No.		Description
INPUT/REFER	ENCE		
AINP	12	I	Positive analog input, channel A
AINM	13	I	Negative analog input, channel A
BINP	39	I	Positive analog input, channel B
BINM	38	I	Negative analog input, channel B
VCM	8	0	Common-mode voltage output for the analog inputs, 0.95V
VREF	2	I	External voltage reference input, 1.6V
REFBUF	4 I 1.2V external voltage reference input for use with internal reference buffer. Internal 100 kG pull-up resistor to AVDD. This pin is also used to configure default operating conditions.		
REFGND	3	I	Reference ground input, 0V
CLOCK			
CLKP	6	I	Positive differential sampling clock input for the ADC
CLKM	7	I	Negative differential sampling clock input for the ADC
CONFIGURATI	ON		
PDN/SYNC	1	I	Power down/Synchronization input. This pin can be configured via the SPI interface. Active high. This pin has an internal 21 k $\Omega$ pull-down resistor.
RESET	9	I	Hardware reset. Active high. This pin has an internal 21 k $\Omega$ pull-down resistor.
SEN	16	I	Serial interface enable. Active low. This pin has an internal 21 k $\Omega$ pull-up resistor to AVDD.
SCLK	35	I	Serial interface clock input. This pin has an internal 21 k $\Omega$ pull-down resistor.
SDIO	10	I/O	Serial interface data input and output. This pin has an internal 21 k $\Omega$ pull-down resistor.
NC	27	-	Do not connect



### Table 5-1. Pin Descriptions (continued)

I	PIN	I/O	Description	
Name	No.	1/0	Description	
DIGITAL INTI	ERFACE			
DA0P	20	0	Positive differential serial LVDS output for lane 0, channel A	
DA0M	19	0	Negative differential serial LVDS output for lane 0, channel A	
DA1P	18	0	Positive differential serial LVDS output for lane 1, channel A	
DA1M	17	0	Negative differential serial LVDS output for lane 1, channel A	
DB0P	31	0	Positive differential serial LVDS output for lane 0, channel B	
DB0M	32	0	Negative differential serial LVDS output for lane 0, channel B	
DB1P	33	0	Positive differential serial LVDS output for lane 1, channel B	
DB1M	34	0	Negative differential serial LVDS output for lane 1, channel B	
DCLKP	23	0	Positive differential serial LVDS bit clock output.	
DCLKM	22	0	Negative differential serial LVDS bit clock output.	
FCLKP	28	0	Positive differential serial LVDS frame clock output.	
FCLKM	29	0	Negative differential serial LVDS frame clock output.	
DCLKINP	25	I	Positive differential serial LVDS bit clock input. Internal 100 $\Omega$ differential termination.	
DCLKINM	24	I	Negative differential serial LVDS bit clock input. Internal 100 $\Omega$ differential termination.	
POWER SUP	PLY			
AVDD	5,15,36	I	Analog 1.8V power supply	
GND 11,14,37,40, PowerPad I Ground, 0V		Ground, 0V		
IOVDD	21,30	I	1.8V power supply for digital interface	
IOGND	26	I	Ground, 0V for digital interface	



# **6** Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
Supply voltage range	y voltage range, AVDD, IOVDD		2.1	V
Supply voltage range, GND, IOGND, REFGND		-0.3	0.3	V
	AINP/M, BINP/M, CLKP/M, VREF, REFBUF	-0.3	MIN(2.1, AVDD+0.3)	V
Voltage applied to input pins	PDN/SYNC, RESET, SCLK, SEN, SDIO	-0.3	MIN(2.1, AVDD+0.3)	
	DCLKINP/M	-0.3	MIN(2.1, IOVDD+0.3)	
Junction temperature, T <sub>J</sub>			105	°C
Storage temperature	e, T <sub>stg</sub>	-65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

# 6.2 ESD Ratings

			VALUE	UNIT
V	Electrostatic	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	2500	V
V <sub>(ESD)</sub>	discharge	Charged device model (CDM), per JEDEC specification JESD22-C101, all pins <sup>(2)</sup>	1000	v

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

# 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Supply	AVDD <sup>(1)</sup>	1.75	1.8	1.85	V
voltage range	IOVDD <sup>(1)</sup>	1.75	1.8	1.85	V
T <sub>A</sub>	Operating free-air temperature	-40		105	°C
TJ	Operating junction temperature			105 <mark>(2)</mark>	°C

(1) Measured to GND.

(2) Prolonged use above this junction temperature may increase the device failure-in-time (FIT) rate.

### **6.4 Thermal Information**

		ADC368x	
	THERMAL METRIC <sup>(1)</sup>	RSB (QFN)	UNIT
		40 Pins	
R <sub>OJA</sub>	Junction-to-ambient thermal resistance	30.7	°C/W
R <sub>OJC(top)</sub>	Junction-to-case (top) thermal resistance	16.4	°C/W
R <sub>ØJB</sub>	Junction-to-board thermal resistance	10.5	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	0.2	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	10.5	°C/W
R <sub>OJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	2.0	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

# 6.5 Electrical Characteristics - Power Consumption

	PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
ADC3681:	10 MSPS				
I <sub>AVDD</sub>	Analog supply current	External reference	30	46	m۸
IIOVDD	I/O supply current	SLVDS 1-wire	29	46	mA
P <sub>DIS</sub>	Power dissipation	External reference, 1-wire	106	166	mW
		1-wire, 1/2-swing	22		
		2-wire	36		
IIOVDD	I/O supply current	1/2-wire	26		mA
		4x real decimation, 1-wire	30		
		4x real decimation, 1/2-wire	27		
ADC3682:	25 MSPS		L	I	
I <sub>AVDD</sub>	Analog supply current	External reference	34	46	
IIOVDD	I/O supply current	1-wire	32	46	mA
P <sub>DIS</sub>	Power dissipation	External reference, 1-wire	119	166	mW
		1-wire, 1/2-swing	24		
		2-wire	38		
IIOVDD	I/O supply current	1/2-wire	28		mA
		4x real decimation, 1-wire	33		
		4x real decimation, 1/2-wire	30		
ADC3683:	65 MSPS				
I <sub>AVDD</sub>	Analog supply current	External reference	63	82	
IIOVDD	I/O supply current	2-wire	41	47	mA
P <sub>DIS</sub>	Power dissipation	External reference, 2-wire	187	232	mW
		2-wire, 1/2-swing	30		
		4x real decimation, 1-wire	39		
		4x real decimation, 1/2-wire	36		
		16x real decimation, 1-wire	37		
IIOVDD	I/O supply current	16x real decimation, 1/2-wire	33		mA
		4x complex decimation, 1-wire	44		
		16x complex decimation, 1-wire	40		
		16x complex decimation, 1/2-wire	36		
MISCELLA	ANEOUS		I	I	
	Internal reference, additional analog supply current		3		
I <sub>AVDD</sub>	External 1.2V reference (REFBUF), additional analog supply current		0.3		mA
	Single ended clock input, reduces analog supply current by	Enabled via SPI	0.7		
D	Power consumption in global power	Default mask settings, internal reference	5		m\//
P <sub>DIS</sub>	down mode	Default mask settings, external reference	9		mW



### 6.6 Electrical Characteristics - DC Specifications

	PARAMETER	TEST CONDITIONS	MIN	ГҮР МА	X UNIT
DC ACCUR	ACY				
No missing c	odes		18		bits
PSRR		F <sub>IN</sub> = 1 MHz		50	dB
ADC3681: 1	0 MSPS				
DNL	Differential nonlinearity	F <sub>IN</sub> = 5 MHz	±	0.7 ± 0.8	35 LSB
INL	Integral nonlinearity	F <sub>IN</sub> = 5 MHz		±7 ±	16 LSB
V <sub>OS_ERR</sub>	Offset error		:	± 10 ± 4	10 LSB
V <sub>OS_DRIFT</sub>	Offset drift over temperature		-(	).04	LSB/ºC
GAIN <sub>ERR</sub>	Gain error	External 1.6V Reference		0.9	%FSR
GAIN <sub>DRIFT</sub>	Gain drift over temperature	External 1.6V Reference		2	ppm/⁰C
GAIN <sub>ERR</sub>	Gain error	Internal Reference	(	).64	%FSR
GAIN <sub>DRIFT</sub>	Gain drift over temperature	Internal Reference		109	ppm/ºC
Transition No	bise			5	LSB
ADC3682: 2	5 MSPS				
DNL	Differential nonlinearity	F <sub>IN</sub> = 5 MHz	±	0.7 ± 0.8	35 LSB
INL	Integral nonlinearity	F <sub>IN</sub> = 5 MHz		±7 ±	16 LSB
V <sub>OS_ERR</sub>	Offset error		=	±40 ±4	10 LSB
V <sub>OS_DRIFT</sub>	Offset drift over temperature		-(	).02	LSB/ºC
GAIN <sub>ERR</sub>	Gain error	External 1.6V Reference	0.	001	%FSR
GAIN <sub>DRIFT</sub>	Gain drift over temperature	External 1.6V Reference		1.5	ppm/ºC
GAIN <sub>ERR</sub>	Gain error	Internal Reference	-(	).26	%FSR
GAIN <sub>DRIFT</sub>	Gain drift over temperature	Internal Reference		106	ppm/⁰C
Transition No	bise			5	LSB
ADC3683: 6	5 MSPS				
DNL	Differential nonlinearity	F <sub>IN</sub> = 5 MHz	±	0.7 ± 0	.9 LSB
INL	Integral nonlinearity	F <sub>IN</sub> = 5 MHz		±7 ±'	19 LSB
V <sub>OS_ERR</sub>	Offset error		±	130 ± 5	10 LSB
V <sub>OS_DRIFT</sub>	Offset drift over temperature		±	0.2	LSB/ºC
GAIN <sub>ERR</sub>	Gain error	External 1.6V Reference	±	2.3	%FSR
GAIN <sub>DRIFT</sub>	Gain drift over temperature	External 1.6V Reference		68	ppm/ºC
GAIN <sub>ERR</sub>	Gain error	Internal Reference	±	3.5	%FSR
GAIN <sub>DRIFT</sub>	Gain drift over temperature	Internal Reference		242	ppm/ºC
Transition No	bise			5	LSB



# 6.6 Electrical Characteristics - DC Specifications (continued)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
ADC ANA	LOG INPUT (AINP/M, BINP/M)					
FS	Input full scale	Differential		3.2		Vpp
V <sub>CM</sub>	Input common model voltage		0.9	0.95	1.0	V
R <sub>IN</sub>	Differential input resistance	F <sub>IN</sub> = 100 kHz		8		kΩ
C <sub>IN</sub>	Differential input Capacitance	F <sub>IN</sub> = 100 kHz		7		pF
V <sub>OCM</sub>	Output common mode voltage			0.95		V
BW	Analog Input Bandwidth (-3dB)			900		MHz
Internal Ve	oltage Reference					
V <sub>REF</sub>	Internal reference voltage			1.6		V
	ut Impedance			8		Ω
	Input Buffer (REFBUF)					
	ference voltage			1.2		V
	oltage reference (VREF)			· · · · ·		
V <sub>REF</sub>	External voltage reference			1.6		V
Input Curre				0.3		mA
Input impe	dance			5.3		kΩ
	ut (CLKP/M)					
-	frequency		0.5		65	MHz
V <sub>ID</sub>	Differential input voltage			1	3.6	Vpp
V <sub>CM</sub>	Input common mode voltage			0.9		V
R <sub>IN</sub>	Single ended input resistance to common mode			5		kΩ
C <sub>IN</sub>	Single ended input capacitance			1.5		pF
Clock duty	cycle		40	50	60	%
Digital Inp	outs (RESET, PDN, SCLK, SEN, SDIO)					
V <sub>IH</sub>	High level input voltage		1.4			V
V <sub>IL</sub>	Low level input voltage				0.4	V
I <sub>IH</sub>	High level input current		-	90	150	uA
IIL	Low level input current		-150	-90		uA
CI	Input capacitance			1.5		pF
Digital Ou	tput (SDOUT)		<u> </u>			
V <sub>OH</sub>	High level output voltage	I <sub>LOAD</sub> = -400 uA	IOVDD - 0.1	IOVDD		V
V <sub>OL</sub>	Low level output voltage	I <sub>LOAD</sub> = 400 uA			0.1	V
SLVDS Int	erface	1	I			
Output dat	a rate	per differential SLVDS output pair			1000	Mbps
V <sub>ID</sub>	Differential input voltage		200	350	650	mVpp
V <sub>CM</sub>	Input common mode voltage	DCLKIN	1	1.2	1.3	V
V <sub>OD</sub>	Differential output voltage		500	700	850	mVpp
V <sub>CM</sub>	Output common mode voltage			1.0		V



# 6.7 Electrical Characteristics - AC Specifications

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
ADC3681 - 1	0 MSPS:					
NSD	Noise Spectral Density	f <sub>IN</sub> = 1.1 MHz, A <sub>IN</sub> = -20 dBFS		-151.7		dBFS/Hz
		f <sub>IN</sub> = 1.1 MHz, A <sub>IN</sub> = -20 dBFS		84.7		
	Circulto noire notio	f <sub>IN</sub> = 1.1 MHz		84.4		dBFS
SNR	Signal to noise ratio	f <sub>IN</sub> = 4.9 MHz	81.5	83.9		
		f <sub>IN</sub> = 9.9 MHz		82.8		dBFS
		f <sub>IN</sub> = 1.1 MHz		84.4		
SINAD	Signal to noise and distortion ratio	f <sub>IN</sub> = 4.9 MHz	80.0	83.9		dBFS
		f <sub>IN</sub> = 9.9 MHz		82.8		
	Effective number of bits	f <sub>IN</sub> = 1.1 MHz		13.7		
ENOB		f <sub>IN</sub> = 4.9 MHz	13.0	13.6		bits
		f <sub>IN</sub> = 9.9 MHz		13.5		
		f <sub>IN</sub> = 1.1 MHz		86		
THD	Total Harmonic Distortion (First five harmonics)	f <sub>IN</sub> = 4.9 MHz	82	86		dBc
		f <sub>IN</sub> = 9.9 MHz		83		
	Spur free dynamic range	f <sub>IN</sub> = 1.1 MHz		87		
SFDR	including second and third harmonic distortion	f <sub>IN</sub> = 4.9 MHz	82	86		dBc
		f <sub>IN</sub> = 9.9 MHz		83		
Non HD2,3		f <sub>IN</sub> = 1.1 MHz		100		
	Spur free dynamic range (excluding HD2 and HD3)	f <sub>IN</sub> = 4.9 MHz	92	98		dBFS
		f <sub>IN</sub> = 9.9 MHz		99		
IMD3	Two tone inter-modulation distortion	$f_1 = 3 \text{ MHz}, f_2 = 4 \text{ MHz}, A_{IN} = -7 \text{ dBFS/tone}$		89		dBc



# 6.7 Electrical Characteristics - AC Specifications (continued)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
ADC3682 - 2	5 MSPS:					
NSD	Noise Spectral Density	f <sub>IN</sub> = 1.1 MHz, A <sub>IN</sub> = -20 dBFS		-156.1		dBFS/Hz
		f <sub>IN</sub> = 1.1 MHz, A <sub>IN</sub> = -20 dBFS		85.1		
		f <sub>IN</sub> = 1.1 MHz		84.7		
SNR	Signal to noise ratio	f <sub>IN</sub> = 5 MHz	81.5	84.5		dBFS
		f <sub>IN</sub> = 10 MHz		84.0		
		f <sub>IN</sub> = 20 MHz		82.3		
		f <sub>IN</sub> = 1.1 MHz		84.7		
SINAD	Signal to noise and	f <sub>IN</sub> = 5 MHz	80.0	84.5		dBFS
SINAD	distortion ratio	f <sub>IN</sub> = 10 MHz		84.0		UDF3
		f <sub>IN</sub> = 20 MHz		82.3		
	Effective number of bits	f <sub>IN</sub> = 1.1 MHz		13.8		
ENOB		f <sub>IN</sub> = 5 MHz	13.0	13.7		bits
ENUD		f <sub>IN</sub> = 10 MHz		13.7		DIIS
		f <sub>IN</sub> = 20 MHz		13.4		
	Total Harmonic Distortion (First five harmonics)	f <sub>IN</sub> = 1.1 MHz		85		
THD		f <sub>IN</sub> = 5 MHz	82	89		dBc
שווו		f <sub>IN</sub> = 10 MHz		88		UDC
		f <sub>IN</sub> = 20 MHz		83		
		f <sub>IN</sub> = 1.1 MHz		86		
SFDR	Spur free dynamic range including second and third	f <sub>IN</sub> = 5 MHz	82	90		dBc
SPDR	harmonic distortion	f <sub>IN</sub> = 10 MHz		89		UDC
		f <sub>IN</sub> = 20 MHz		83		
		f <sub>IN</sub> = 1.1 MHz		102		
Non HD2,3	Spur free dynamic range	f <sub>IN</sub> = 5 MHz	92	101		dBFS
11011102,3	(excluding HD2 and HD3)	f <sub>IN</sub> = 10 MHz		103		ubr3
		f <sub>IN</sub> = 20 MHz		100		
IMD3	Two tone inter-modulation	$f_1 = 3 \text{ MHz}, f_2 = 4 \text{ MHz}, A_{IN} = -7 \text{ dBFS/tone}$		84		dBc
	distortion	f <sub>1</sub> = 10 MHz, f <sub>2</sub> = 12 MHz, A <sub>IN</sub> = -7 dBFS/tone		87		UDC



### 6.7 Electrical Characteristics - AC Specifications (continued)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
ADC3683 - 6	5 MSPS:					
NSD	Noise Spectral Density	f <sub>IN</sub> = 1.1 MHz, A <sub>IN</sub> = -20 dBFS		-160		dBFS/H
		f <sub>IN</sub> = 1.1 MHz, A <sub>IN</sub> = –20 dBFS	÷	84.8		
		f <sub>IN</sub> = 1.1 MHz	·	84.2		
		f <sub>IN</sub> = 5 MHz	81.0	83.8		
SNR	Signal to noise ratio	f <sub>IN</sub> = 10 MHz		83.6		dBFS
		f <sub>IN</sub> = 20 MHz		82.6		
		f <sub>IN</sub> = 40 MHz		81.0		
		f <sub>IN</sub> = 70 MHz		77.3		
		f <sub>IN</sub> = 1.1 MHz		80.0		
		f <sub>IN</sub> = 5 MHz		82.7		
	Signal to noise and	f <sub>IN</sub> = 10 MHz		82.7		
SINAD	distortion ratio	f <sub>IN</sub> = 20 MHz		80.2		dBFS
		f <sub>IN</sub> = 40 MHz		78.7		
		f <sub>IN</sub> = 70 MHz		75.8		
	Effective number of bits	f <sub>IN</sub> = 1.1 MHz		13.7		
		f <sub>IN</sub> = 5 MHz		13.6		
		f <sub>IN</sub> = 10 MHz		13.6		
ENOB		f <sub>IN</sub> = 20 MHz		13.4		bits
		f <sub>IN</sub> = 40 MHz		13.2		
		f <sub>IN</sub> = 70 MHz		12.5		
		f <sub>IN</sub> = 1.1 MHz		81		
		f <sub>IN</sub> = 5 MHz	80.5	88		
	Total Harmonic Distortion	f <sub>IN</sub> = 10 MHz		89		
THD	(First five harmonics)	f <sub>IN</sub> = 20 MHz		83		dBc
		f <sub>IN</sub> = 40 MHz		82		
		f <sub>IN</sub> = 70 MHz		80		
		f <sub>IN</sub> = 1.1 MHz		82		
		f <sub>IN</sub> = 5 MHz	81.5	89		
	Spur free dynamic range	f <sub>IN</sub> = 10 MHz		92		
SFDR	including second and third harmonic distortion	f <sub>IN</sub> = 20 MHz		85		dBc
		f <sub>IN</sub> = 40 MHz		84		
		f <sub>IN</sub> = 70 MHz		82		
		f <sub>IN</sub> = 1.1 MHz		101		
		f <sub>IN</sub> = 5 MHz	90	101		
	Spur free dynamic range	f <sub>IN</sub> = 10 MHz		100		
Non HD2,3	(excluding HD2 and HD3)	f <sub>IN</sub> = 20 MHz		97		dBFS
		f <sub>IN</sub> = 40 MHz		91		
		f <sub>IN</sub> = 70 MHz		88		
	Two tone inter-modulation	$f_1 = 10 \text{ MHz}, f_2 = 12 \text{ MHz}, A_{IN} = -7 \text{ dBFS/tone}$		83		
IMD3	distortion	$f_1 = 40 \text{ MHz}, f_2 = 45 \text{ MHz}, A_{IN} = -7 \text{ dBFS/tone}$		78		dBc



# 6.8 Timing Requirements

	PARAMETER	TEST CONDITIONS	MIN NOM	MAX	UNIT
ADC Timi	ng Specifications	1			
t <sub>AD</sub>	Aperture Delay		0.85		ns
t <sub>A</sub>	Aperture Jitter	Square wave clock with fast edges	180		fs
tj	Jitter on DCLKIN			± 50	ps
		F <sub>S</sub> = 10 Msps	-T <sub>S</sub> /2		Sampling
t <sub>ACQ</sub>	Signal acquisition period, referenced to sampling clock falling edge	F <sub>S</sub> = 25 Msps	-T <sub>S</sub> /2		Clock
		F <sub>S</sub> = 65 Msps	-T <sub>S</sub> /4		Period
		F <sub>S</sub> = 10 Msps	+T <sub>S</sub> × 1/5		
t <sub>CONV</sub>	Signal conversion period, referenced to sampling clock falling edge	F <sub>S</sub> = 25 Msps	+T <sub>S</sub> × 3/8		Sampling Clock Period
		F <sub>S</sub> = 65 Msps	+T <sub>S</sub> × 5/8		i onou
	Time to valid data after coming out of power down. Internal reference.	Bandgap reference enabled, single ended clock		17.6	
		Bandgap reference enabled, differential clock		12.9	us
		Bandgap reference disabled, single ended clock		2.2	ms
Wake up		Bandgap reference disabled, differential clock		2.2	1115
time	Time to valid data after coming out of power down. External 1.6V reference.	Bandgap reference enabled, single ended clock		15.9	us
		Bandgap reference enabled, differential clock		12.9	us
		Bandgap reference disabled, single ended clock		1.7	ms
		Bandgap reference disabled, differential clock		1.7	1115
t <sub>S,SYNC</sub>	Setup time for SYNC input signal	Referenced to sampling clock rising edge	500		ps
t <sub>H,SYNC</sub>	Hold time for SYNC input signal		600		μs
ADC Latency		SLVDS 2-wire	2		ADC
	Signal input to data output	SLVDS 1-wire	1		clock
		SLVDS 1/2-wire	1		cycles
A .1.1	Real decimation by 2		21		Output
Add Latency	Complex decimation by 2		22		clock
Latency	Real or complex decimation by 4, 8, 1	6, 32	23		cycles

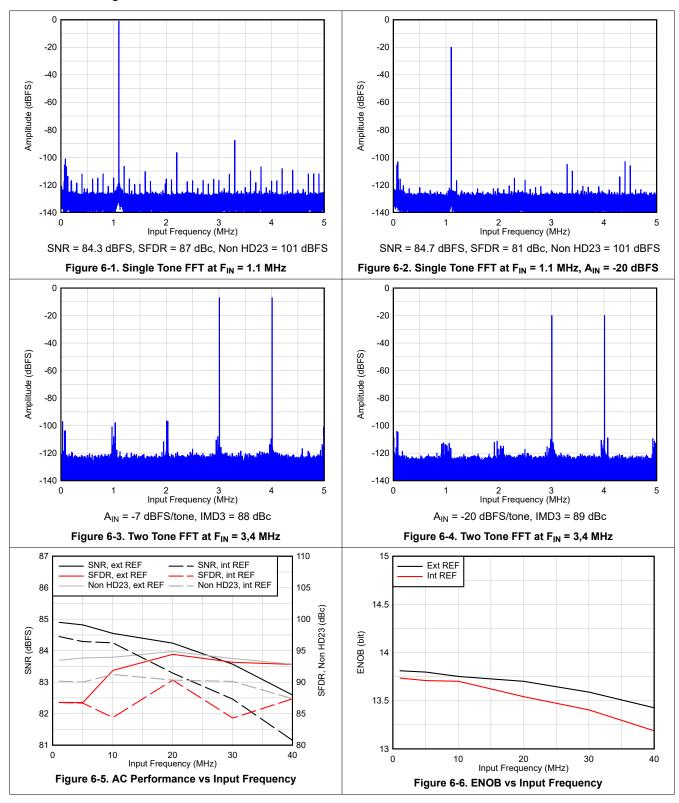


# 6.8 Timing Requirements (continued)

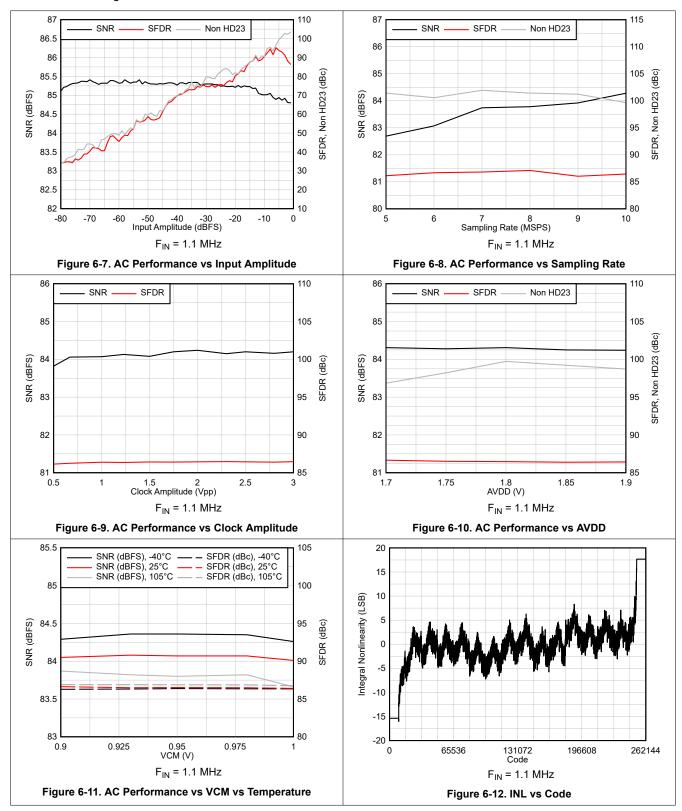
	PARAMETER	TEST CONDITIONS	MIN	NOM	MAX	UNIT
Interface 1	Timing: Serial LVDS Interface					
	Propagation delay: sampling clock	Delay between sampling clock falling edge to DCLKIN falling edge < 2.5ns. T <sub>DCLK</sub> = DCLK period t <sub>CDCLK</sub> = Sampling clock falling edge to DCLKIN falling edge	+	3 + T <sub>DCLK</sub> + t <sub>CDCLK</sub>	+	ns
	falling edge to DCLK rising edge	$\begin{array}{llllllllllllllllllllllllllllllllllll$	2 + t <sub>CDCLK</sub>	3 + t <sub>CDCLK</sub>	4 + t <sub>CDCLK</sub>	ns
	DCLK rising edge to output data	Fout = 10 MSPS, DA/B0,1 = 90 MBPS	0	0.1		
	delay,	Fout = 25 MSPS, DA/B0,1 = 225 MBPS	0	0.1		
	2-wire SLVDS	Fout = 65 MSPS, DA/B0,1 = 585 MBPS	0	0.1		
	DCLK rising edge to output data	Fout = 10 MSPS, DA/B0 = 180 MBPS	0.1	0.2		
t <sub>CD</sub>	delay,	Fout = 25 MSPS, DA/B0 = 450 MBPS	0	0.1		ns
	1-wire SLVDS	Fout = 55 MSPS, DA/B0 = 990 MBPS	-0.4	0.1		1
	DCLK rising edge to output data delay, 1/2-wire SLVDS	Fout = 5 MSPS, DA0 = 180 MBPS	0	0.1		
		Fout = 10 MSPS, DA0 = 360 MBPS	0	0.1		
		Fout = 25 MSPS, DA0 = 720 MBPS	0	0.1		
	Data valid, 2-wire SLVDS Data valid, 1-wire SLVDS	Fout = 10 MSPS, DA/B0,1 = 90 MBPS	10.5	10.7		-
		Fout = 25 MSPS, DA/B0,1 = 225 MBPS	4.0	4.1		
		Fout = 65 MSPS, DA/B0,1 = 585 MBPS	1.3	1.4		
		Fout = 10 MSPS, DA/B0 = 180 MBPS	4.7	4.8		
t <sub>DV</sub>		Fout = 25 MSPS, DA/B0 = 450 MBPS	1.8	1.9		ns
		Fout = 55 MSPS, DA/B0 = 990 MBPS	0.5	0.6		
	Data valid, 1/2-wire SLVDS	Fout = 5 MSPS, DA0 = 180 MBPS	4.7	4.8		
		Fout = 10 MSPS, DA0 = 360 MBPS	2.4	2.5		
		Fout = 25 MSPS, DA0 = 900 MBPS	0.6	0.7		
SERIAL P	ROGRAMMING INTERFACE (SCLK, S	SEN, SDIO) - Input				
fCLK(SCLK)	Serial clock frequency				20	MHz
t <sub>SU(SEN)</sub>	SEN to rising edge of SCLK		10			ns
t <sub>H(SEN)</sub>	SEN from rising edge of SCLK		9			ns
t <sub>SU(SDIO)</sub>	SDIO to rising edge of SCLK		17			ns
t <sub>H(SDIO)</sub>	SDIO from rising edge of SCLK		9			ns
SERIAL P	ROGRAMMING INTERFACE (SDIO) -	Output				
t <sub>(OZD)</sub>	SDIO tri-state to driven		3.9		10.8	ns
t <sub>(ODZ)</sub>	SDIO data to tri-state		3.4		14	ns
t <sub>(OD)</sub>	SDIO valid from falling edge of SCLK		3.9		10.8	ns



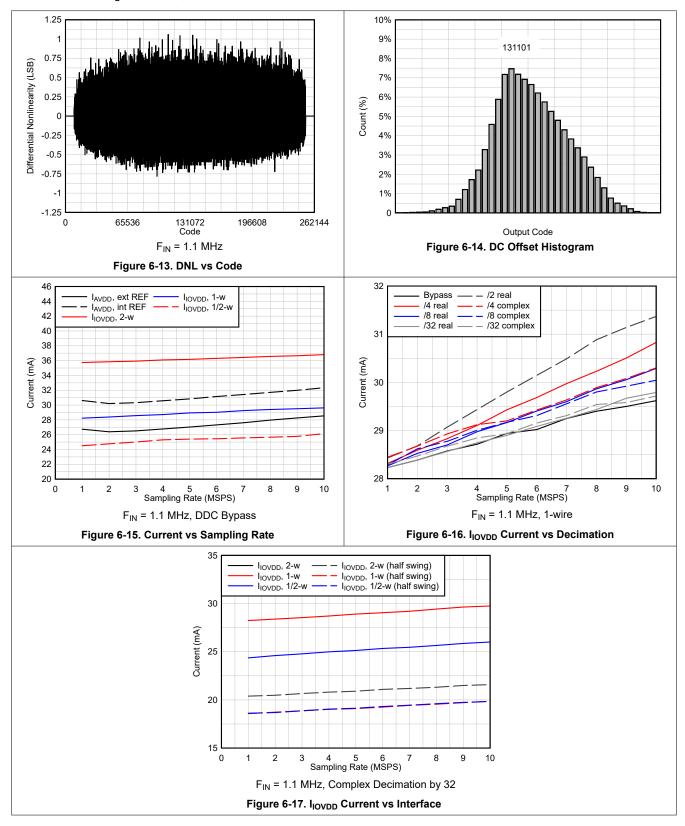
# 6.9 Typical Characteristics - ADC3681







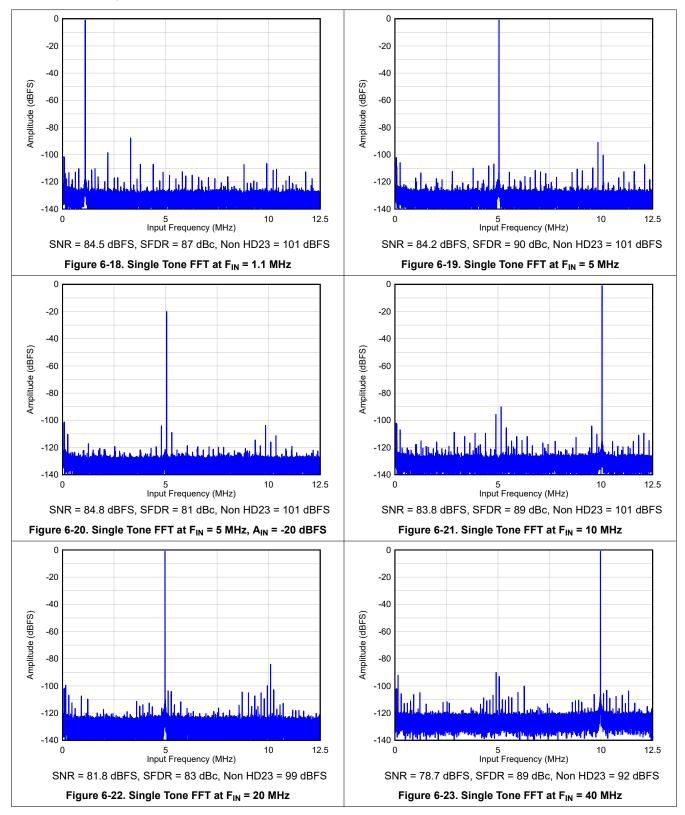






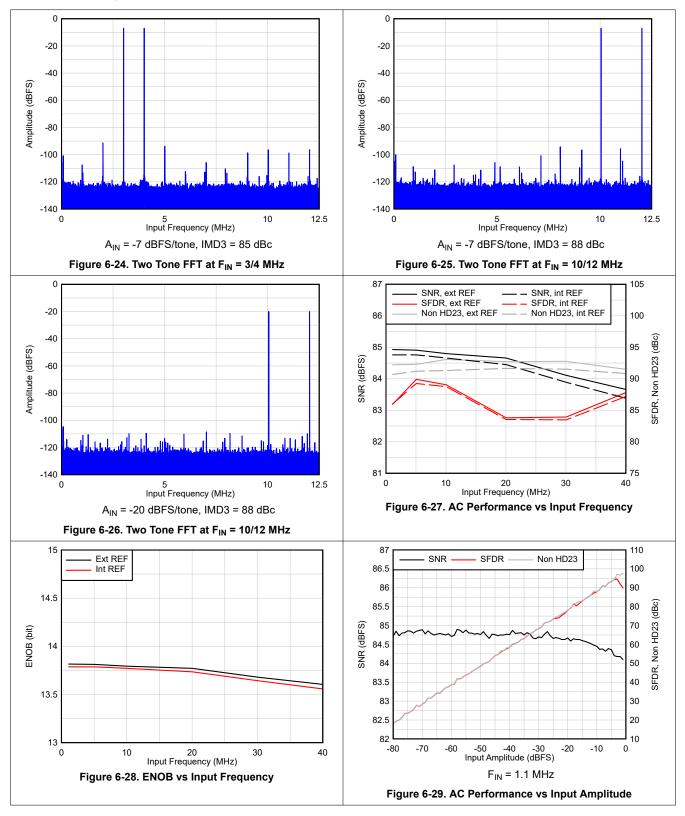
# 6.10 Typical Characteristics - ADC3682

Typical values at  $T_A = 25$  °C, ADC sampling rate = 25 MSPS,  $A_{IN} = -1$  dBFS differential input, AVDD = IOVDD = 1.8 V, external 1.6 V voltage reference, unless otherwise noted.



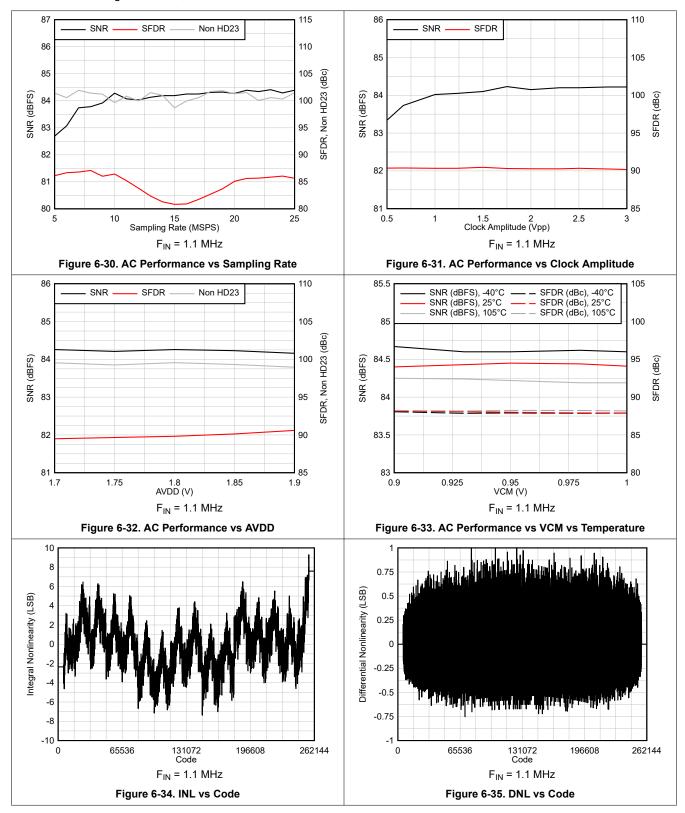


Typical values at  $T_A = 25$  °C, ADC sampling rate = 25 MSPS,  $A_{IN} = -1$  dBFS differential input, AVDD = IOVDD = 1.8 V, external 1.6 V voltage reference, unless otherwise noted.

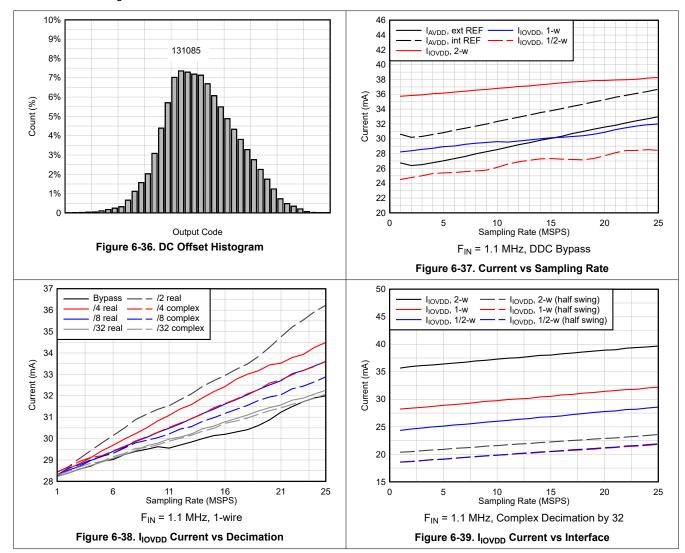




Typical values at  $T_A = 25$  °C, ADC sampling rate = 25 MSPS,  $A_{IN} = -1$  dBFS differential input, AVDD = IOVDD = 1.8 V, external 1.6 V voltage reference, unless otherwise noted.

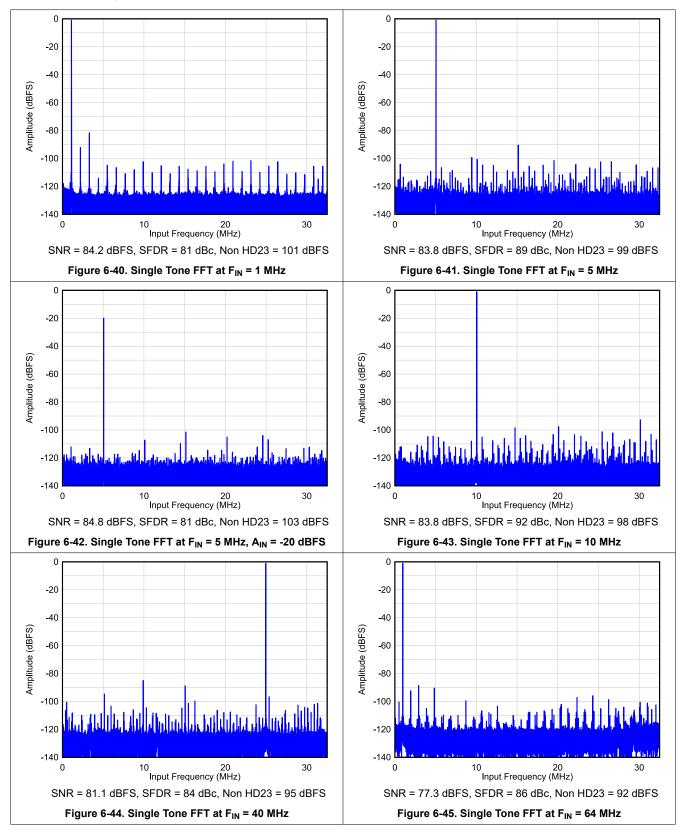






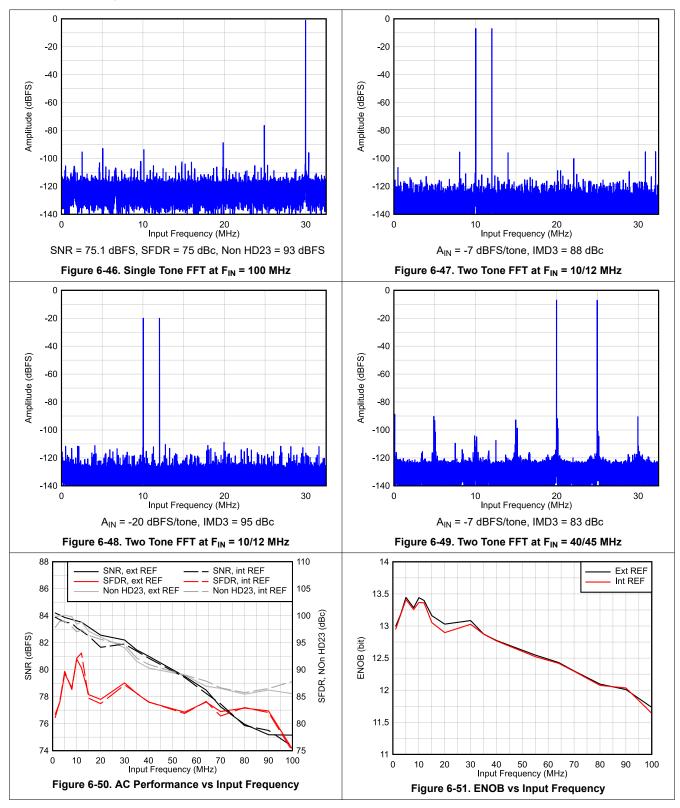


# 6.11 Typical Characteristics - ADC3683

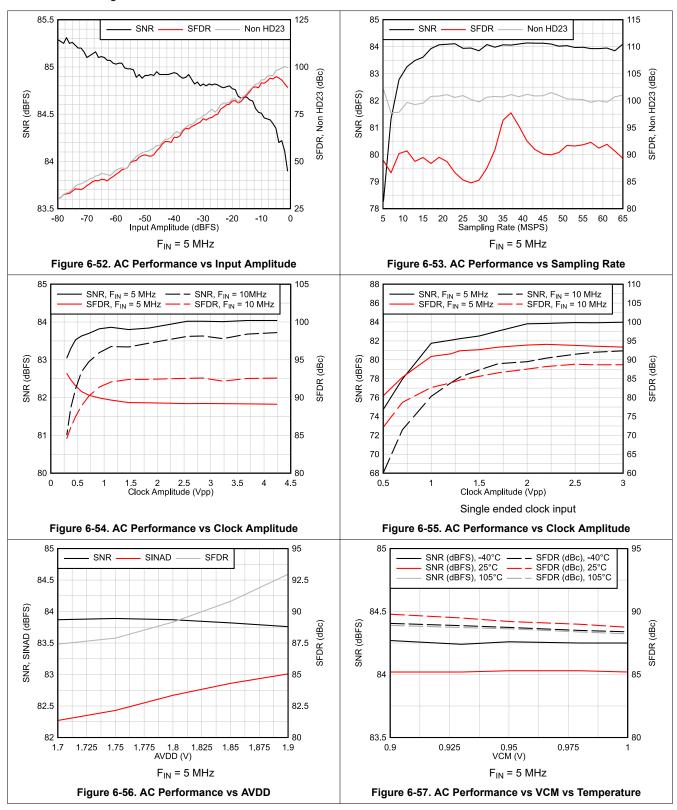


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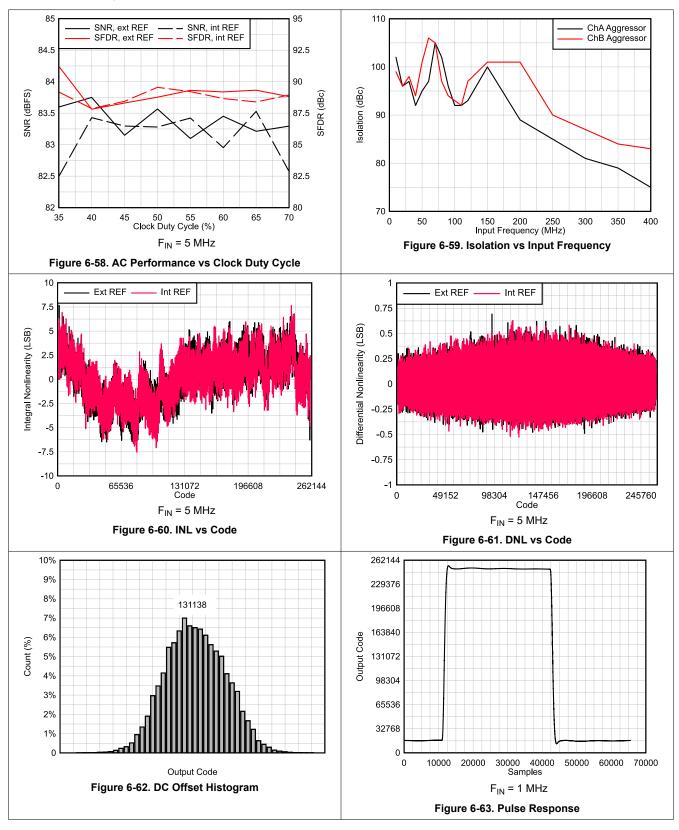




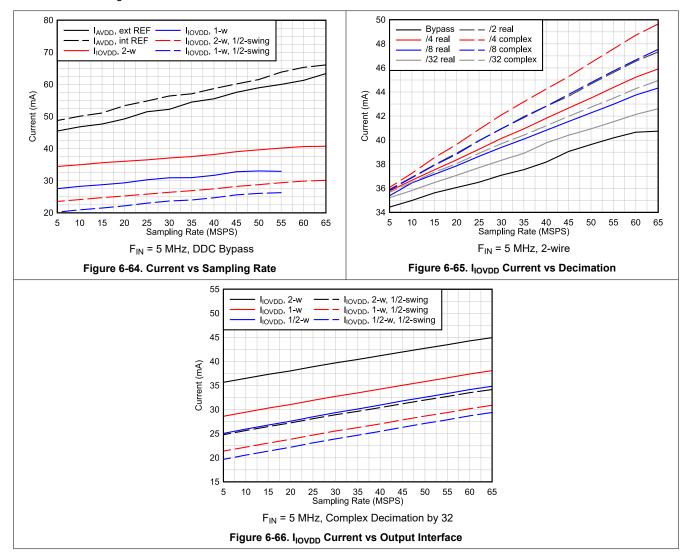




Typical values at  $T_A = 25$  °C, ADC sampling rate = 65 MSPS,  $A_{IN} = -1$  dBFS differential input, AVDD = IOVDD = 1.8 V, external 1.6 V voltage reference, unless otherwise noted.

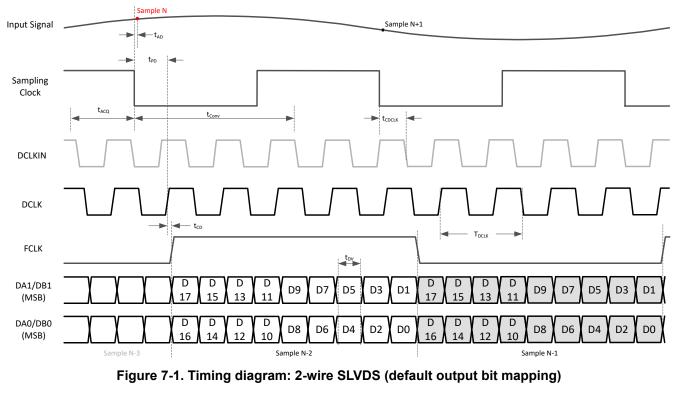


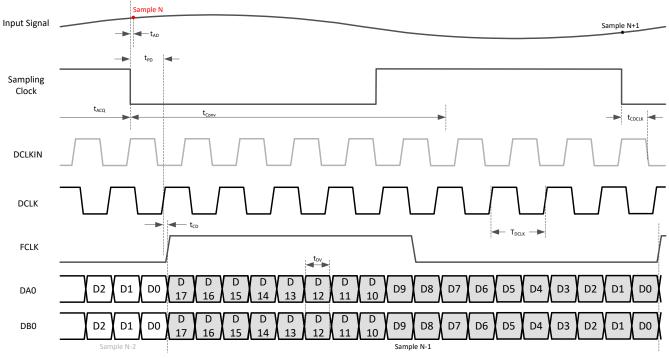






### 7 Parameter Measurement Information









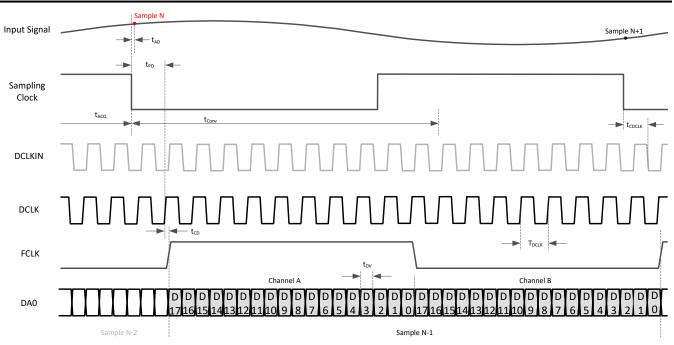


Figure 7-3. Timing diagram: 1/2-wire SLVDS (default output bit mapping)



# 8 Detailed Description

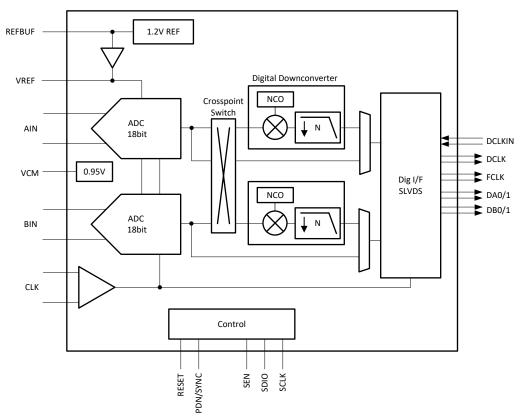
# 8.1 Overview

The ADC368x is a low noise, ultra-low power 18-bit high-speed dual channel ADC family supporting sampling rates up to 65 MSPS. It offers excellent DC precision together with IF sampling support which makes it ideally suited for a wide range of applications. The ADC368x is equipped with an internal reference option but it also supports the use of an external, high precision 1.6 V voltage reference or an external 1.2 V reference which is buffered and gained up internally. Because of the inherent low latency architecture, the digital output result is available after only one or two clock cycles depending on the digital output interface.

An optional programmable digital down converter enables external anti-alias filter relaxation as well as output data rate reduction. The digital filter provides a 32-bit programmable NCO and supports both real or complex decimation.

The ADC368x uses a serial LVDS (SLVDS) interface to output the data which minimizes the number of digital interconnects. The device supports a two-lane (2-wire), a one-lane (1-wire) and a half-lane (1/2-wire) option. The ADC368x includes a digital output formatter which supports output resolutions from 14 to 20-bit.

The device features and control options can be set up either through pin configurations or via SPI register writes.



### 8.2 Functional Block Diagram



### 8.3 Feature Description

### 8.3.1 Analog Input

The analog inputs of ADC368x are intended to be driven differentially. Both AC coupling and DC coupling of the analog inputs is supported. The analog inputs are designed for an input common mode voltage of 0.95 V which must be provided externally on each input pin. DC-coupled input signals must have a common mode voltage that meets the device input common mode voltage range.

The equivalent input network diagram is shown in Figure 8-1. All four sampling switches, on-resistance shown in red are in same position (open or closed) simultaneously.

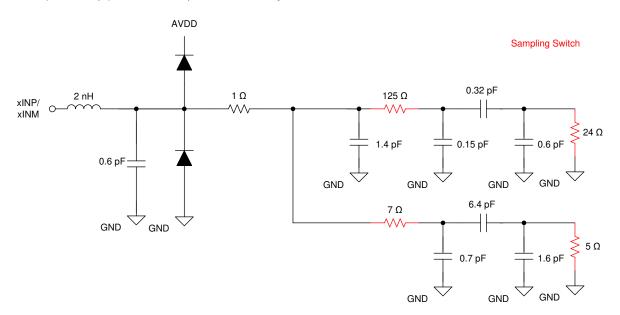
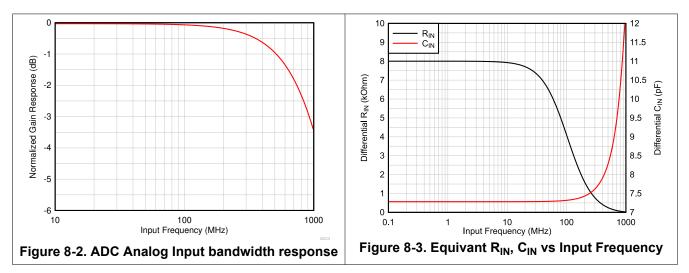


Figure 8-1. Equivalent input network

#### 8.3.1.1 Analog Input Bandwidth

Figure 8-2 shows the analog full power input bandwidth of the ADC368x with a 50  $\Omega$  differential termination. The -3 dB bandwidth is approximately 900 MHz and the useful input bandwidth with good AC performance is approximately 120 MHz.

The equivalent differential input resistance R<sub>IN</sub> and input capacitance C<sub>IN</sub> vs frequency are shown in Figure 8-3.





### 8.3.1.2 Analog Front End Design

The ADC368x is an unbuffered ADC and thus a passive kick-back filter is recommended to absorb the glitch from the sampling operation. Depending on if the input is driven by a balun or a differential amplifier with low output impedance, a termination network may be needed. Additionally a passive DC bias circuit is needed in AC-coupled applications which can be combined with the termination network.

#### 8.3.1.2.1 Sampling Glitch Filter Design

The front end sampling glitch filter is designed to optimize the SNR and HD3 performance of the ADC. The filter performance is dependent on input frequency and therefore the following filter designs are recommended for different input frequency ranges as shown in Figure 8-4 and Figure 8-5 (assuming a 50  $\Omega$  source impedance).

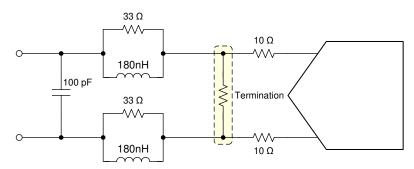


Figure 8-4. Sampling glitch filter example for input frequencies from DC to 30 MHz

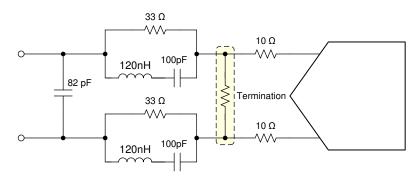


Figure 8-5. Sampling glitch filter example for input frequencies from 30 to 70 MHz



#### 8.3.1.2.2 Analog Input Termination and DC Bias

Depending on the input drive circuitry, a termination network and/or DC biasing needs to be provided.

#### 8.3.1.2.2.1 AC-Coupling

The ADC368x requires external DC bias using the common mode output voltage (VCM) of the ADC together with the termination network as shown in Figure 8-6. The termination is located within the glitch filter network. When using a balun on the input, the termination impedance has to be adjusted to account for the turns ratio of the transformer. When using an amplifier, the termination impedance can be adjusted to optimize the amplifier performance.

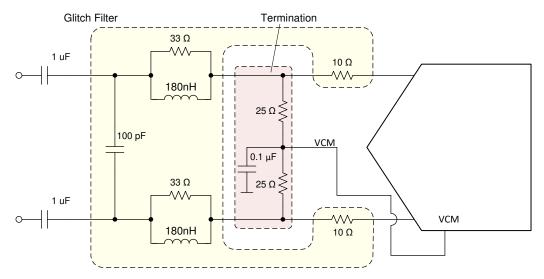
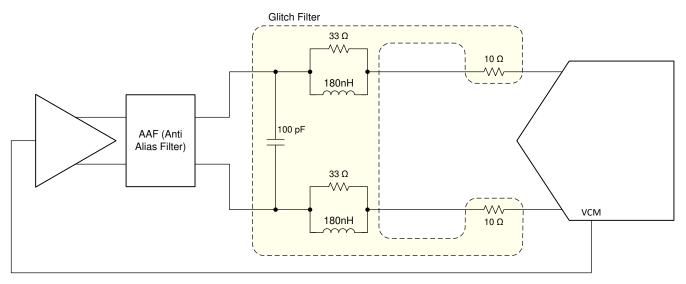
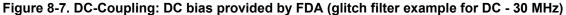


Figure 8-6. AC-Coupling: termination network provides DC bias (glitch filter example for DC - 30 MHz)

#### 8.3.1.2.2.2 DC-Coupling

In DC coupled applications the DC bias needs to be provided from the fully differential amplifier (FDA) using VCM output of the ADC as shown in Figure 8-7. The glitch filter in this case is located between the anti-alias filter and the ADC. No termination may be needed if amplifier is located close to the ADC or if the termination is part of the anti-alias filter.

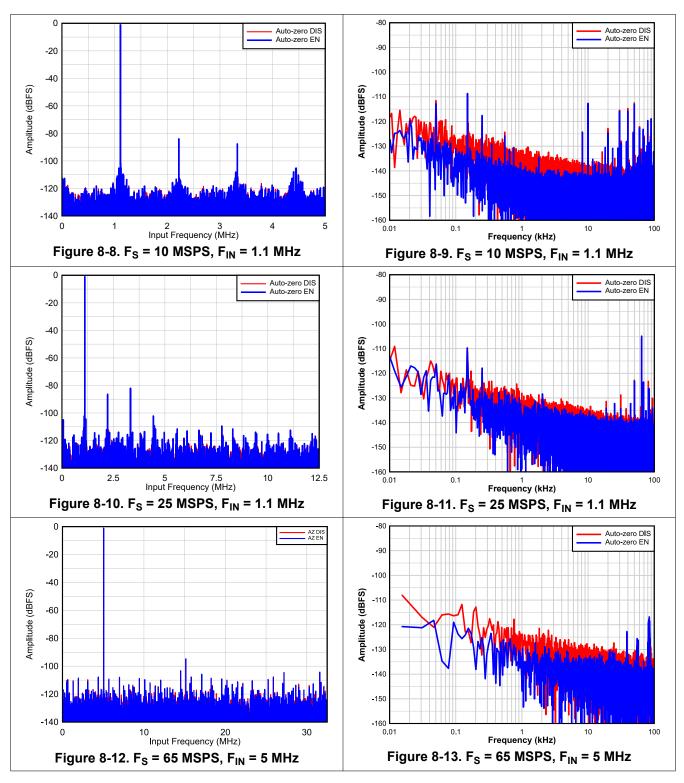






### 8.3.1.3 Auto-Zero Feature

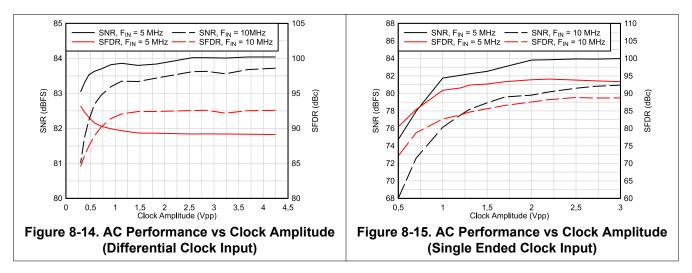
The ADC368x includes an internal auto-zero front end amplifier circuit which improves the 1/f flicker noise. This auto-zero feature is enabled by default for the ADC3681/2 and can be enabled using SPI register writes for the ADC3683 (register 0x11, D0). The 4M point FFTs below show the autozero feature enabled vs disabled.





### 8.3.2 Clock Input

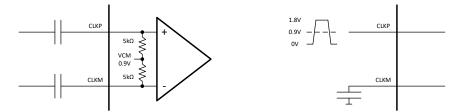
In order to maximize the ADC SNR performance, the external sampling clock should be low jitter and differential signaling with a high slew rate. This is especially important in IF sampling applications (Figure 8-14 and Figure 8-15). For less jitter sensitive applications, the ADC368x provides the option to operate with single ended signaling which saves additional power consumption.

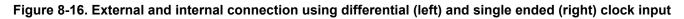


### 8.3.2.1 Single Ended vs Differential Clock Input

The ADC368x can be operated using a differential or a single ended clock input where the single ended clock consumes less power consumption. However clock amplitude impacts the ADC aperture jitter and consequently the SNR. For maximum SNR performance, a large clock signal with fast slew rates needs to be provided.

- Differential Clock Input: The clock input can be AC coupled externally. The ADC368x provides internal bias.
- Single Ended Clock Input: This mode needs to be configured using SPI register (0x0E, D2 and D0) or with the REFBUF pin. In this mode there is no internal clock biasing and thus the clock input needs to be DC coupled around a 0.9V center. The unused input needs to be AC coupled to ground.





### 8.3.2.2 Signal Acquisition Time Adjust

The ADC368x includes a register (DLL PDN (0x11, D2) which increases the signal acquisition time window for clock rates below 40 MSPS from 25% to 50% of the clock period. Increasing the sampling time provides a longer time for the driving amplifier to settle out the signal which can improve the SNR performance of the system. This register should only be used for the 65 MSPS speed grade (ADC3683) For the 10 and 25 MSPS device speed grades the sampling time is already set to  $T_S/2$ . When powering down the DLL, the acquisition time will track the clock duty cycle (50% is recommended).

SAMPLING CLOCK F <sub>S</sub> (MSPS)	DLL PDN (0x11, D2)	ACQUISITION TIME (t <sub>ACQ</sub> )
65	0	T <sub>S</sub> / 4
≤ 40	1	T <sub>S</sub> / 2

#### Table 8-1. Acquisition time vs DLL PDN setting



#### 8.3.3 Voltage Reference

The ADC368x provides three different options for supplying the voltage reference to the ADC. An external 1.6 V reference can be directly connected to the VREF input; a voltage 1.2 V reference can be connected to the REFBUF input using the internal gain buffer or the internal 1.2 V reference can be enabled to generate a 1.6 V reference voltage. For best performance, the reference noise should be filtered by connecting a 10 uF and a 0.1 uF ceramic bypass capacitor to the VREF pin. The internal reference circuitry of the ADC368x is shown in Figure 8-17.

#### Note

The voltage reference mode can be selected using SPI writes or by using the REFBUF pin (default) as a control pin (Section 8.5.1). If the REFBUF pin is not used for configuration, the REFBUF pin should be connected to AVDD (even though the REFBUF pin has a weak internal pullup to AVDD) and the voltage reference option has to be selected using the SPI interface.

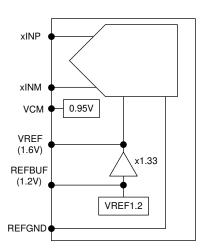


Figure 8-17. Different voltage reference options for ADC368x

### 8.3.3.1 Internal voltage reference

The 1.6 V reference for the ADC can be generated internal using the on-chip 1.2V bandgap reference along with the internal gain buffer. A 10 uF and a 0.1 uF ceramic bypass capacitor ( $C_{VREF}$ ) should be connected between the VREF and REFGND pins as close to the pins as possible.

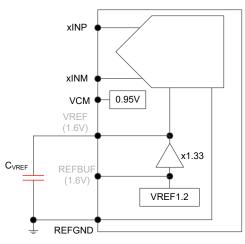


Figure 8-18. Internal reference



### 8.3.3.2 External voltage reference (VREF)

For highest accuracy and lowest temperature drift, the VREF input can be directly connected to an external 1.6 V reference. A 10 uF and a 0.1 uF ceramic bypass capacitor ( $C_{VREF}$ ) connected between the VREF and REFGND pins and placed as close to the pins as possible is recommended. The load current from the external reference is about 1mA.

Note: The internal reference is also used for other functions inside the device, therefore the reference amplifier should only be powered down in power down state but not during normal operation.

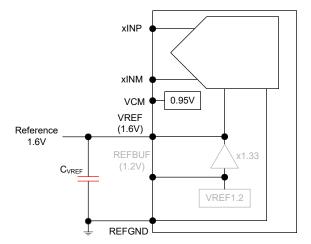


Figure 8-19. External 1.6 V reference

#### 8.3.3.3 External voltage reference with internal buffer (REFBUF)

The ADC368x is equipped with an on-chip reference buffer that also includes gain to generate the 1.6 V reference voltage from an external 1.2V reference. A 10 uF and a 0.1 uF ceramic bypass capacitor ( $C_{VREF}$ ) between the VREF and REFGND pins and a 10 uF and a 0.1 uF ceramic bypass capacitor between the REFBUF and REFGND pins are recommended. Both capacitors should be placed as close to the pins as possible. The load current from the external reference is less than 100uA.

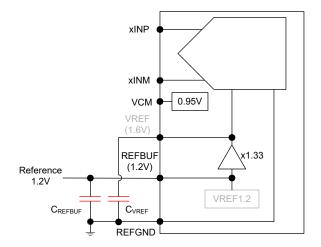


Figure 8-20. External 1.2V reference using internal reference buffer



#### 8.3.4 Digital Down Converter

The ADC368x includes an optional on-chip digital down conversion (DDC) decimation filter that can be enabled via SPI register settings. It supports complex decimation by 2, 4, 8, 16 and 32 using a digital mixer and a 32-bit numerically controlled oscillator (NCO) as shown in Figure 8-21.

Furthermore it supports a mode with real decimation where the complex mixer is bypassed (NCO should be set to 0 for lowest power consumption) and the digital filter acts as a low pass filter.

Internally the decimation filter calculations are performed with a 20-bit resolution in order to avoid any SNR degradation due to quantization noise limitation. The Section 8.3.5.1 truncates to the selected resolution prior to outputting the data on the digital interface.

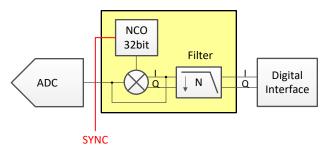


Figure 8-21. Internal Digital Decimation Filter

### 8.3.4.1 DDC MUX

The ADC368x contains a MUX in front of the digital decimation filter which allows ADC ChA to be connected to DDC ChB and vice versa. This feature is enabled and controlled using the SPI interface. Subsequently the output interface corresponds to the DDC channel A and B.

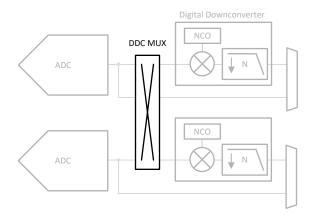
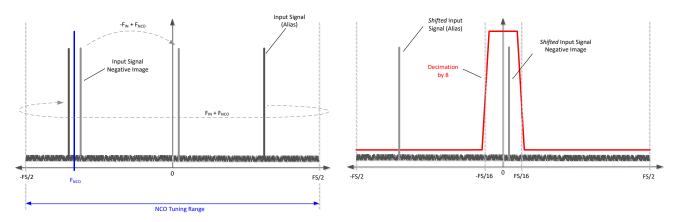


Figure 8-22. DDC MUX



## 8.3.4.2 Digital Filter Operation

The complex decimation operation is illustrated with an example in Figure 8-23. First the input signal (and the negative image) are frequency shifted by the NCO frequency as shown on the left. Next a digital filter is applied (centered around 0 Hz) and the output data rate is decimated by 8 complex - in this example the output data rate  $F_{S,OUT} = F_S/8$  with a Nyquist zone of  $F_S/16$ . During the complex mixing the spectrum (signal and noise) is split into real and complex parts and thus the amplitude is reduced by 6-dB. In order to compensate this loss, there is a 6-dB digital gain option in the decimation filter block that can be enabled via SPI write.





The real decimation operation is illustrated with an example in Figure 8-24. There is no frequency shift happening and only the real portion of the complex digital filter is exercised. The output data rate is decimated - a decimation of 8 would result in an output data rate  $F_{S,OUT} = F_S/8$  with a Nyquist zone of  $F_S/16$ .

During the real mixing the spectrum (signal and noise) amplitude is reduced by 3-dB. In order to compensate this loss, there is a 3-dB digital gain option in the decimation filter block that can be enabled via SPI write.

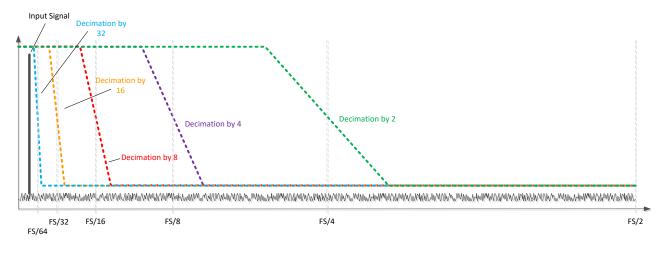


Figure 8-24. Real decimation illustration



#### 8.3.4.3 FS/4 Mixing with Real Output

In this mode, the output after complex decimation gets mixed with FS/4 (FS = output data rate in this case). Instead of a complex output with the input signal centered around 0 Hz, the output is transmitted as a real output at twice the data rate and the signal is centered around FS/4 (Fout/4) as illustrated in Figure 8-25.

In this example, complex decimation by 8 is used. The output data is transmitted as a real output with an output rate of Fout = FS'/4 (FS' = ADC sampling rate). The input signal is now centered around FS/4 (Fout/4) or FS'/16.

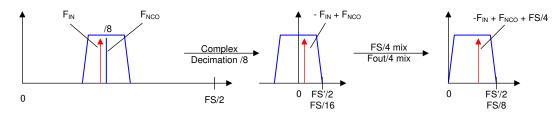


Figure 8-25. FS/4 Mixing with real output

## 8.3.4.4 Numerically Controlled Oscillator (NCO) and Digital Mixer

The decimation block is equipped with a 32-bit NCO and a digital mixer to fine tune the frequency placement prior to the digital filtering. The oscillator generates a complex exponential sequence of:

 $e^{j\omega n}$  (default) or  $e^{-j\omega n}$ 

(1)

where: frequency ( $\omega$ ) is specified as a signed number by the 32-bit register setting

The complex exponential sequence is multiplied with the real input from the ADC to mix the desired carrier to a frequency equal to  $f_{IN} + f_{NCO}$ . The NCO frequency can be tuned from  $-F_S/2$  to  $+F_S/2$  and is processed as a signed, 2s complement number. After programming a new NCO frequency, the MIXER RESTART register bit or SYNC pin has to be toggled for the new frequency to get active. Additionally the ADC368x provides the option via SPI to invert the mixer phase.

The NCO frequency setting is set by the 32-bit register value given and calculated as:

NCO frequency = 0 to +  $F_S/2$ : NCO =  $f_{NCO} \times 2^{32} / F_S$ 

NCO frequency =  $-F_S/2$  to 0: NCO =  $(f_{NCO} + F_S) \times 2^{32} / F_S$ 

where:

- NCO = NCO register setting (decimal value)
- f<sub>NCO</sub> = Desired NCO frequency (MHz)
- F<sub>S</sub> = ADC sampling rate (MSPS)

The NCO programming is further illustrated with this example:

- ADC sampling rate F<sub>S</sub> = 65 MSPS
- Input signal f<sub>IN</sub> = 10 MHz
- Desired output frequency f<sub>OUT</sub> = 0 MHz

For this example there are actually four ways to program the NCO and achieve the desired output frequency as shown in Table 8-2.

Alias or negative image f <sub>NCO</sub>		CO NCO Value Mixer Phase		Frequency translation for f <sub>OUT</sub>						
f <sub>IN</sub> = –10 MHz	f <sub>NCO</sub> = 10 MHz	660764199	as is	$f_{OUT} = f_{IN} + f_{NCO} = -10 \text{ MHz} + 10 \text{ MHz} = 0 \text{ MHz}$						
f <sub>IN</sub> = 10 MHz	f <sub>NCO</sub> = -10 MHz	3634203097	as is	$f_{OUT} = f_{IN} + f_{NCO} = 10 \text{ MHz} + (-10 \text{ MHz}) = 0 \text{ MHz}$						
f <sub>IN</sub> = 10 MHz	f <sub>NCO</sub> = 10 MHz	660764199	inverted	$f_{OUT} = f_{IN} - f_{NCO} = 10 \text{ MHz} - 10 \text{ MHz} = 0 \text{ MHz}$						
f <sub>IN</sub> = –10 MHz	f <sub>NCO</sub> = -10 MHz	3634203097	invented	$f_{OUT} = f_{IN} - f_{NCO} = -10 \text{ MHz} - (-10 \text{ MHz}) = 0 \text{ MHz}$						

Table 8-2. NCC	value	calculations	example
----------------	-------	--------------	---------





# 8.3.4.5 Decimation Filter

The ADC368x supports complex decimation by 2, 4, 8, 16 and 32 with a stopband rejection of at least 85 dB and a pass-band bandwidth of ~ 80%. Table 8-3 gives an overview of the pass-band bandwidth of the different decimation settings with respect to ADC sampling rate  $F_S$ . In real decimation mode the output bandwidth is half of the complex bandwidth.

REAL/COMPLEX DECIMATION	DECIMATION SETTING N	OUTPUT RATE	OUTPUT BANDWIDTH	OUTPUT RATE (F <sub>S</sub> = 65 MSPS)	OUTPUT BANDWIDTH (F <sub>S</sub> = 65 MSPS)
	2	F <sub>S</sub> / 2 complex	0.8 × F <sub>S</sub> / 2	32.5 MSPS complex	26 MHz
	4	F <sub>S</sub> / 4 complex	0.8 × F <sub>S</sub> / 4	16.25 MSPS complex	13 MHz
Complex	8	F <sub>S</sub> / 8 complex	0.8 × F <sub>S</sub> / 8	8.125 MSPS complex	6.5 MHz
	16	F <sub>S</sub> / 16 complex	0.8 × F <sub>S</sub> / 16	4.0625 MSPS complex	3.25 MHz
	32	F <sub>S</sub> / 32 complex	0.8 × F <sub>S</sub> / 32	2.03125 MSPS complex	1.625 MHz
	2	F <sub>S</sub> / 2 real	0.4 × F <sub>S</sub> / 2	32.5 MSPS	13 MHz
	4	F <sub>S</sub> / 4 real	$0.4 \times F_{S} / 4$	16.25 MSPS	6.5 MHz
Real	8	F <sub>S</sub> / 8 real	0.4 × F <sub>S</sub> / 8	8.125 MSPS	3.25 MHz
	16	F <sub>S</sub> / 16 real	0.4 × F <sub>S</sub> / 16	4.0625 MSPS	1.625 MHz
	32	F <sub>S</sub> / 32 real	0.4 × F <sub>S</sub> / 32	2.03125 MSPS	0.8125 MHz

#### Table 8-3. Decimation Filter Summary and Maximum Available Output Bandwidth

The decimation filter responses are normalized to the ADC sampling clock frequency  $F_S$  and illustrated in Figure 8-27 to Figure 8-36. They are interpreted as follows:

Each figure contains the filter pass-band, transition band(s) and alias or stop-band(s) as shown in Figure 8-26. The x-axis shows the offset frequency (after the NCO frequency shift) normalized to the ADC sampling rate  $F_S$ .

For example, in the divide-by-4 complex setup, the output data rate is  $F_S / 4$  complex with a Nyquist zone of  $F_S / 8$  or  $0.125 \times F_S$ . The transition band (colored in blue) is centered around  $0.125 \times F_S$  and the alias transition band is centered at  $0.375 \times F_S$ . The stop-bands (colored in red), which alias on top of the pass-band, are centered at  $0.25 \times F_S$  and  $0.5 \times F_S$ . The stop-band attenuation is greater than 85 dB.

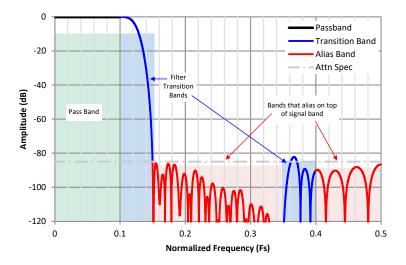
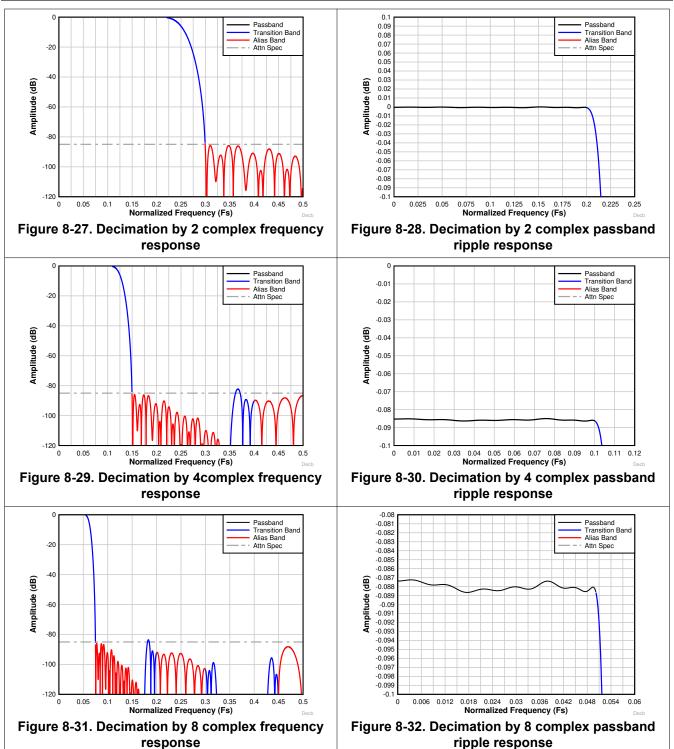
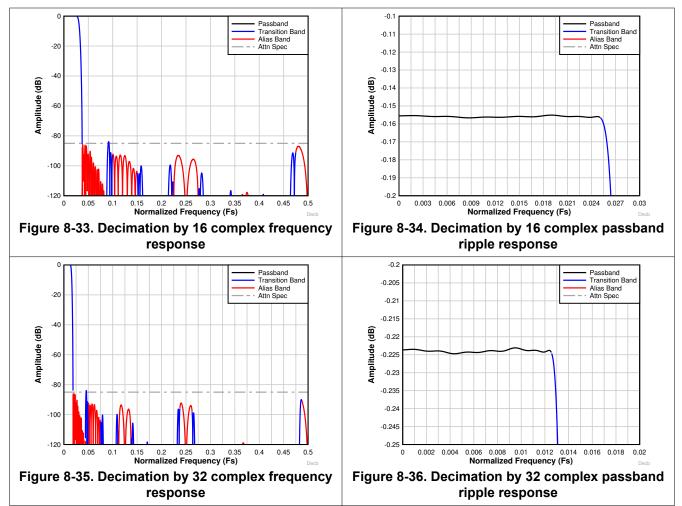


Figure 8-26. Interpretation of the Decimation Filter Plots









# 8.3.4.6 SYNC

The PDN/SYNC pin can be used to synchronize multiple devices using an external SYNC signal. The PDN/ SYNC pin can be configured via SPI (SYNC EN bit) from power down to synchronization functionality and is latched in by the rising edge of the sampling clock as shown in Figure 8-37.

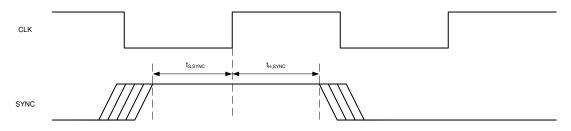


Figure 8-37. External SYNC timing diagram

The synchronization signal is only required when using the decimation filter - either using the SPI SYNC register or the PDN/SYNC pin. It resets internal clock dividers used in the decimation filter and aligns the internal clocks as well as I and Q data within the same sample. If no SYNC signal is given, the internal clock dividers is not be synchronized, which can lead to a fractional delay across different devices. The SYNC signal also resets the NCO phase and loads the new NCO frequency (same as the MIXER RESTART bit).

When trying to resynchronize during operation, the SYNC toggle should occur at 64\*K clock cycles, where K is an integer. This provids the phase continuity of the clock divider.

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#### 8.3.4.7 Output Formatting with Decimation

When using decimation, the digital output data is formatted as shown in Figure 8-38 (complex decimation) and Figure 8-39 (real decimation). The output format is illustrated for 18-bit output resolution.

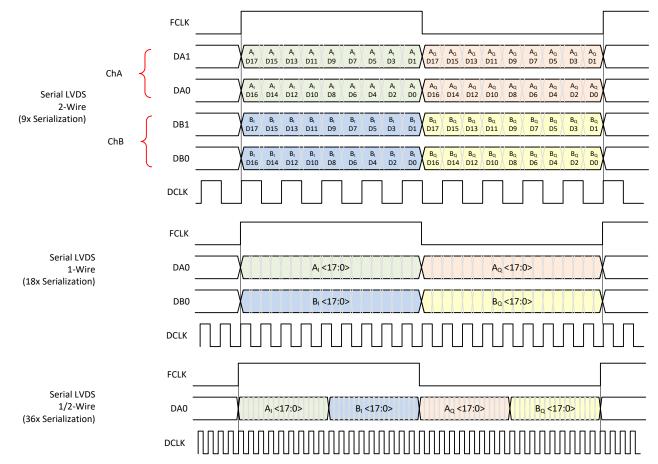


Figure 8-38. Output Data Format in Complex Decimation (18-bit Output Resolution)

Table 8-4 illustrates the output interface data rate along with the corresponding DCLK/DCLKIN and FCLK frequencies based on output resolution (R), number of SLVDS lanes (L) and complex decimation setting (N).

Furthermore the table shows an actual lane rate example for the 2-, 1- and 1/2-wire interface, 18-bit output resolution and complex decimation by 4.

DECIMATION SETTING	ADC SAMPLING RATE RESOLUT		# of WIRES	FCLK	DCLKIN, DCLK	DA/B0,1
N	Fs	R	L	F <sub>S</sub> / N	[DA/B0,1] / 2	F <sub>S</sub> x2xR/L/N
	65 MSPS		2	16.25 MHz	146.25 MHz	292.5 MHz
4		18	1	10.23 10112	292.5 MHz	585 MHz
	55 MSPS		1/2	13.75 MHz	495 MHz	990 MHz



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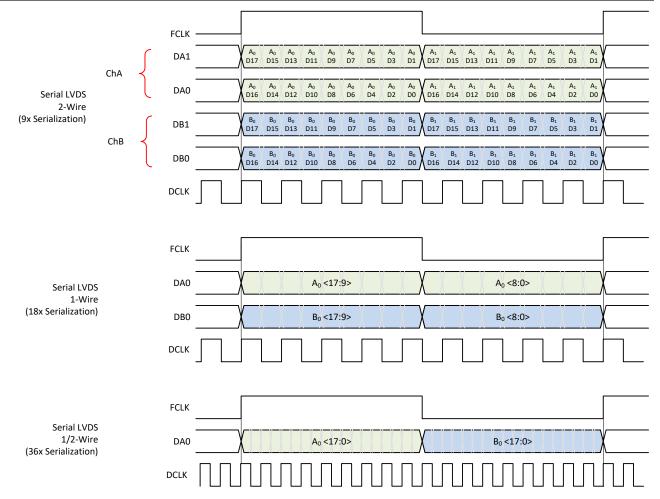


Figure 8-39. Output Data Format in Real Decimation (18-bit Output Resolution)

Table 8-5 illustrates the output interface data rate along with the corresponding DCLK/DCLKIN and FCLK frequencies based on output resolution (R), number of SLVDS lanes (L) and real decimation setting (M).

Furthermore the table shows an actual lane rate example for the 2-, 1- and 1/2-wire interface, 18-bit output resolution and real decimation by 4.

Table 0-5.	Table 0-5. Serial LVDS Lane Rate Examples with Real Decimation and To-bit Odiput Resolution										
DECIMATION SETTING	ADC SAMPLING RATE	OUTPUT RESOLUTION	# of WIRES	FCLK	DCLKIN, DCLK	DA/B0,1					
М	Fs	R	L	$F_S / M / 2 (L = 2)$ $F_S / M (L = 1, 1/2)$	[DA/B0,1] / 2	F <sub>S</sub> x R / L / M					
			2	8.125 MHz	73.125 MHz	146.25 MHz					
4	65 MSPS	18	1	16.25 MHz	146.25 MHz	292.5 MHz					
			1/2		292.5 MHz	585 MHz					

#### Table 8-5. Serial LVDS Lane Rate Examples with Real Decimation and 18-bit Output Resolution



## 8.3.5 Digital Interface

The serial LVDS interface supports the data output with 2-wire, 1-wire and 1/2-wire operation. The actual data output rate depends on the output resolution and number of lanes used.

The ADC368x requires an external serial LVDS clock input (DCLKIN), which is used to transmit the data out of the ADC along with the data clock (DCLK). The phase relationship between DCLKIN and the sampling clock is irrelevant but both clocks need to be frequency locked. The SLVDS interface is configured using SPI register writes.

#### 8.3.5.1 Output Formatter

The digital output interface uses a flexible output bit mapper (Figure 8-40). The bit mapper takes the 18-bit output directly from the ADC or from the digital decimation filter block and reformats it to a resolution of 14,16,18 or 20-bit. The output serialization factor is adjusted accordingly for 2-, 1- and 1/2-wire interface modes. The maximum SLVDS interface output data rate can not be exceeded independent of output resolution or serialization factor.

For 14 and 16-bit output resolution, the LSBs are truncated during the reformatting. With 20-bit output, in bypass mode two 0s are added in place of the two LSBs while in decimation mode and the digital averaging mode the full 20-bit output is used.

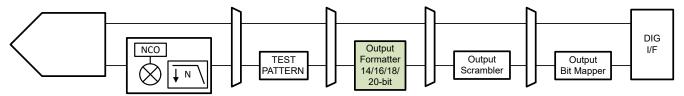


Figure 8-40. Interface output bit mapper

Table 8-6 provides an overview for the resulting serialization factor depending on output resolution and output modes. Note that the DCLKIN frequency needs to be adjusted accordingly as well. Changing the output resolution to 16-bit, 2-wire mode for example results in DCLKIN =  $F_S * 4$  instead of \* 4.5.

OUTPUT RESOLUTION	Interface	SERIALIZATION	FCLK	DCLKIN	DCLK	D0/D1
	2-Wire	7x	F <sub>S</sub> /2	F <sub>S</sub> * 3.5	F <sub>S</sub> * 3.5	F <sub>S</sub> * 7
14-bit	1-Wire	14x	F <sub>S</sub>	F <sub>S</sub> * 7	F <sub>S</sub> * 7	F <sub>S</sub> * 14
	1/2-Wire	28x	F <sub>S</sub>	F <sub>S</sub> * 14	F <sub>S</sub> * 14	F <sub>S</sub> * 28
	2-Wire	8x	F <sub>S</sub> /2	F <sub>S</sub> * 4	F <sub>S</sub> * 4	F <sub>S</sub> * 8
16-bit	1-Wire	16x	F <sub>S</sub>	F <sub>S</sub> * 8	F <sub>S</sub> * 8	F <sub>S</sub> * 16
	1/2-Wire	32x	F <sub>S</sub>	F <sub>S</sub> * 16	F <sub>S</sub> * 16	F <sub>S</sub> * 32
	2-Wire	9x	F <sub>S</sub> /2	F <sub>S</sub> * 4.5	F <sub>S</sub> * 4.5	F <sub>S</sub> * 9
18-bit (default)	1-Wire	18x	F <sub>S</sub>	F <sub>S</sub> * 9	F <sub>S</sub> * 9	F <sub>S</sub> * 18
	1/2-Wire	36x	F <sub>S</sub>	F <sub>S</sub> * 18	F <sub>S</sub> * 18	F <sub>S</sub> * 36
	2-Wire	10x	F <sub>S</sub> /2	F <sub>S</sub> * 5	F <sub>S</sub> * 5	F <sub>S</sub> * 10
20-bit	1-Wire	20x	Fs	F <sub>S</sub> * 10	F <sub>S</sub> * 10	F <sub>S</sub> * 20
	1/2-Wire	40x	F <sub>S</sub>	F <sub>S</sub> * 20	F <sub>S</sub> * 20	F <sub>S</sub> * 40

 Table 8-6. Serialization factor vs output resolution for different output modes

The programming sequence to change the output interface and/or resolution from default settings is shown in Section 8.3.5.4.



#### 8.3.5.2 Output Scrambler

The device includes an optional output scrambler feature. Scrambling is performed on each serial output lane independently. When enabled, the serial output bit stream is scrambled where each output bit is XOR-ed with 2 previous bits (k-14 and k-15) as shown in Figure 8-42. For descrambling, note that the output bit mapper is located after the scrambler.

On the external receiver, the incoming serial data stream can be descrambled by XOR-ing each incoming bit with 2 previous bits (k-14 and k-15).

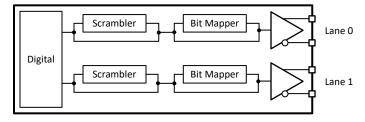
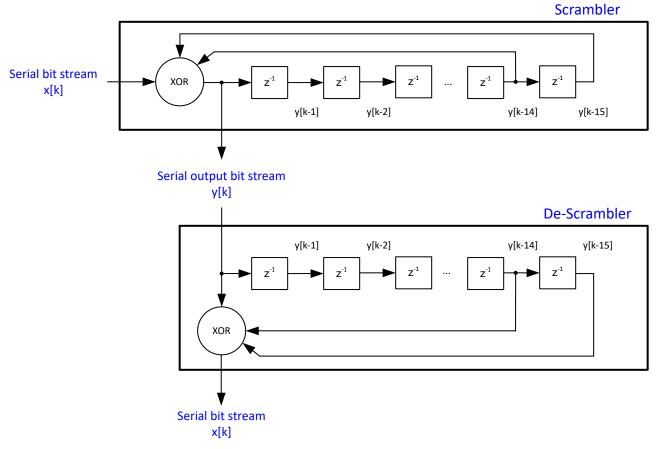


Figure 8-41. Output scrambling per lane



# Figure 8-42. Output scrambler and descrambler operation

Scrambling is enabled by disabling digital bypass (register 0x24, D2) and enabling scrambling (register 0x22, D6).



# 8.3.5.3 Output Bit Mapper

The output bit mapper allows change to the output bit order for any selected interface mode.

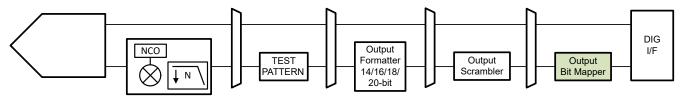


Figure 8-43. Output Bit Mapper

There is a two step process to change the output bit mapping and assemble the output data bus:

- 1. Both channel A and B can have up to 20-bit output. Each output bit of either channel has a unique identifier bit as shown in Table 8-7. The MSB starts with bit D19, depending on output resolution chosen, the LSB is D6 (14-bit) to D0 (20-bit). The *previous sample* is only needed in 2-w mode.
- 2. The bit mapper is then used to assemble the output sample. The following sections detail how to remap the serial output format.

Bit	Chan	nel A	Channel B		
	Previous sample (2w only)	Current sample	Previous sample (2w only)	Current sample	
D19 (MSB)	0x2D	0x6D	0x29	0x69	
D18	0x2C	0x6C	0x28	0x68	
D17	0x27	0x67	0x23	0x63	
D16	0x26	0x66	0x22	0x62	
D15	0x25	0x65	0x21	0x61	
D14	0x24	0x64	0x20	0x60	
D13	0x1F	0x5F	0x1B	0x5B	
D12	0x1E	0x5E	0x1A	0x5A	
D11	0x1D	0x5D	0x19	0x59	
D10	0x1C	0x5C	0x18	0x58	
D9	0x17	0x57	0x13	0x53	
D8	0x16	0x56	0x12	0x52	
D7	0x15	0x55	0x11	0x51	
D6	0x14	0x54	0x10	0x50	
D5	0x0F	0x4F	0x0B	0x4B	
D4	0x0E	0x4E	0x0A	0x4A	
D3	0x0D	0x4D	0x09	0x49	
D2	0x0C	0x4C	0x08	0x48	
D1	0x07	0x47	0x03	0x43	
D0 (LSB)	0x06	0x46	0x02	0x42	

Table 8-7. Unique identifier of each data bit

In the serial output mode, a data bit (with unique identifier) needs to be assigned to each location within the serial output stream. There are a total of 40 addresses available per channel. Channel A spans from address 0x39 to 0x60 and channel B from address 0x61 to 0x88. When using complex decimation, the output bit mapper is applied to both the "I" and the "Q" sample.



**2-wire mode**: in this mode, both the current and the previous sample have to be used in the address space as shown in Figure 8-44. The address order is different for 14/18-bit and 16/20-bit. Note: there are unused addresses between samples for resolution less than 20-bit (grey back ground), which can be skipped if not used.

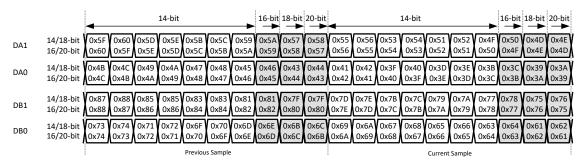


Figure 8-44. 2-wire output bit mapper

In the following example (Figure 8-45), the 16-bit 2-wire serial output is reordered to where lane DA1/DB1 carries the 8 MSB and lane DA0/DB0 carries 8 LSBs.

	Previous Sample					Current Sample										
DA1	D19 <sub>A</sub>	D18 <sub>A</sub>	D17 <sub>A</sub>	D16 <sub>A</sub>	D15 <sub>A</sub>	D14 <sub>A</sub>	D13 <sub>A</sub>	D12 <sub>A</sub>	D19 <sub>A</sub>	D18 <sub>A</sub>	D17 <sub>A</sub>	D16 <sub>A</sub>	D15 <sub>A</sub>	D14 <sub>A</sub>	D13 <sub>A</sub>	D12 <sub>A</sub>
	(0x60	(0x5F	(0x5E	(0x5D	(0x5C	(0x5B	(0x5A	(0x59	(0x56	(0x55	(0x54	(0x53	(0x52	(0x51	(0x50	(0x4F
	0x2D)	0x2C)	0x27)	0x26)	0x25)	0x24)	0x1F)	0x1E)	0x6D)	0x6C)	0x67)	0x66)	0x65)	0x64)	0x5F)	0x5E)
DA0	D11 <sub>A</sub>	D10 <sub>A</sub>	D9 <sub>A</sub>	D8 <sub>A</sub>	D7 <sub>A</sub>	D6 <sub>A</sub>	D5 <sub>A</sub>	D4 <sub>A</sub>	D11 <sub>A</sub>	D10 <sub>A</sub>	D9 <sub>A</sub>	D8 <sub>A</sub>	D7 <sub>A</sub>	D6 <sub>A</sub>	D5 <sub>A</sub>	D4 <sub>A</sub>
	(0x4C	(0x4B	(0x4A	(0x49	(0x48	(0x47	(0x46	(0x45	(0x42	(0x41	(0x40	(0x39	(0x38	(0x37	(0x36	(0x35
	0x1D)	0x1C)	0x17)	0x16)	0x15)	0x14)	0x0F)	0x0E)	0x5D)	0x5C)	0x57)	0x56)	0x55)	0x54)	0x4F)	0x4E)
DB1	D19 <sub>B</sub>	D18 <sub>B</sub>	D17 <sub>B</sub>	D16 <sub>B</sub>	D15 <sub>B</sub>	D14 <sub>B</sub>	D13 <sub>B</sub>	D12 <sub>B</sub>	D19 <sub>B</sub>	D18 <sub>B</sub>	D17 <sub>B</sub>	D16 <sub>B</sub>	D15 <sub>B</sub>	D14 <sub>B</sub>	D13 <sub>B</sub>	D12 <sub>B</sub>
	(0x88	(0x87	(0x86	(0x85	(0x84	(0x83	(0x82	(0x81	(0x7E	(0x7D	(0x7C	(0x7B	(0x7A	(0x79	(0x78	(0x77
	0x29)	0x28)	0x23)	0x22)	0x21)	0x20)	0x1B)	0x1A)	0x69)	0x68)	0x63)	0x62)	0x61)	0x60)	0x5B)	0x5A)
DB0	D11 <sub>B</sub>	D10 <sub>B</sub>	D9 <sub>B</sub>	D8 <sub>B</sub>	D7 <sub>B</sub>	D6 <sub>8</sub>	D5 <sub>B</sub>	D4 <sub>B</sub>	D11 <sub>B</sub>	D10 <sub>B</sub>	D9 <sub>8</sub>	D8 <sub>B</sub>	D7 <sub>B</sub>	D6 <sub>B</sub>	D5 <sub>B</sub>	D4 <sub>B</sub>
	(0x74	(0x73	(0x72	(0x71	(0x70	(0x6F	(0x6E	(0x6D	(0x6A	(0x69	(0x68	(0x67	(0x66	(0x65	(0x64	(0x63
	0x19)	0x18)	0x13)	0x12)	0x11)	0x10)	0x0B)	0x0A)	0x59)	0x58)	0x53)	0x52)	0x51)	0x50)	0x4B)	0x4A)

Figure 8-45. Example: 2-wire output bit mapping

**1-wire mode**: Only the 'current' sample needs to programmed in the address space. A duplicated can be created on DA1/DB1 as well (using addresses shown below) to have a redundant output. Lane DA1/DB1 needs to be powered up.

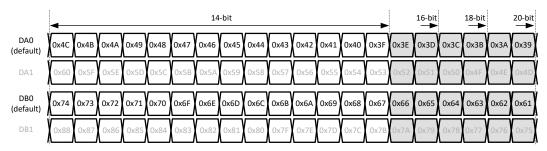


Figure 8-46. 1-wire output bit mapping

<sup>1</sup>/<sub>2</sub>-wire mode: The output is only lane DA0 and the sample order is programmed into the 40 addresses of chA (from 0x39 to 0x60). This covers 2 samples (one for chA, one for chB) as shown below. A duplicate can be created on DB0 as well (using addresses shown in Figure 8-47) to have a redundant output. Lane DB0 must be powered up.

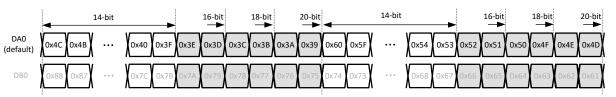


Figure 8-47. 1/2-wire output bit mapping



# 8.3.5.4 Output Interface/Mode Configuration

The following sequence summarizes all the relevant registers for changing the output interface and/or enabling the decimation filter. Steps 1 and 2 must come first since the E-Fuse load reset the SPI writes, the remaining steps can come in any order.

STEP	FEATURE	ADDRESS		steps for chang	DESCRIPTION	avenuen				
			Select the output int	terface bit mapping d	ion and output interfa	ice.				
			Output R	esolution	2-wire	1-wire	1/2-wire			
			14	-bit	0x2B					
1		0x07	16-bit 0x4B							
			18	-bit	0x2B	0x6C	0x8D			
			20	-bit	0x4B					
2		0x13	Load the output interface bit mapping usin 0x01, wait ~ 1ms so that bit mapping is load				n register 0x13 to			
	-		Configure the FCLK	frequency based on	bypass/decimation	and number of lanes	used.			
			Bypass/Dec	SLVDS	FCLK SRC (D7)	FCLK DIV (D4)	TOG FCLK (D0)			
				2-wire	0	1	0			
3		0x19	Bypass/ Real Decimation	1-wire	0	0	0			
			Beennauon	1/2-wire	0	0	0			
				2-wire	1	0	0			
	Output					Complex Decimation	1-wire	1	0	0
	Interface			Decimation	1/2-wire	0	0	1		
4	-	0x1B	Select the output in	terface resolution usi	ng the bit mapper (D	95-D3).				
	-		Select the FCLK pa	output of the frame o	lock.					
				Output Resolution	2-wire	1-wire	1/2-wire			
			Real Decimation	14-bit		0xFE000				
				16-bit	- use default -	0xFF000	use default			
5		0x20 0x21		18-bit		0xFF800				
0		0x22		20-bit		0xFFC00				
				14-bit		0xFFFF				
			Complex	16-bit			0xFFFFF			
			Decimation	18-bit		UXI I I I	UXI I I I			
				20-bit						
6		0x390x60 0x610x88	Change output bit n selection.	napping for chA and	chB if desired. This v	vorks also with the de	efault interface			
7		0x24 0x22	Enable scrambling							
8		0x24	Enable the decimation	ion filter						
9		0x25	Configure the decim	nation filter						
10		0x2A/B/C/D 0x31/2/3/4	Program the NCO f	requency for complex	x decimation (can be	skipped for real dec	imation)			
	Decimation		Configure the complex output data stream (set both bits to 0 for real decimation)							
	Filter	0.0-	SLVDS			OP-Order (D4)	Q-Delay (D3)			
11		0x27 0x2E	2-wire			1	0			
		0x2E 1-wire				0	1			
			1/2-wire			1	1			
12		0x26	Set the mixer gain a	and toggle the mixer	reset bit to update th	e NCO frequency.				

# Table 8-8. Configuration steps for changing interface or decimation



#### 8.3.5.4.1 Configuration Example

The following is a step by step programming example to configure the ADC368x to complex decimation by 8 with 1-wire SLVDS and 16-bit output.

- 1. 0x07 (address) 0x6C (load bit mapper configuration for 16-bit output with 1-wire SLVDS)
- 2. 0x13 0x01, wait 1 ms, 0x13 0x00 (load e-fuse)
- 3. 0x19 0x80 (configure FCLK)
- 4. 0x1B 0x88 (select 16-bit output resolution)
- 5. 0x20 0xFF, 0x21 0xFF, 0x22 0x0F (configure FCLK pattern)
- 6. 0x24 0x06 (enable decimation filter)
- 7. 0x25 0x30 (configure complex decimation by 8)
- 8. 0x2A/B/C/D and 0x31/32/33/34 (program NCO frequency)
- 9. 0x27/0x2E 0x08 (configure Q-delay register bit)
- 10. 0x26 0xAA, 0x26 0x88 (set digital mixer gain to 6-dB and toggle the mixer update)

## 8.3.5.5 Output Data Format

The output data can be configured to two's complement (default) or offset binary formatting using SPI register writes (register 0x8F and 0x92). Table 8-9 provides an overview for minimum and maximum output codes for the two formatting options. The actual output resolution is set by the output bit mapper.

#### Table 8-9. Overview of minimum and maximum output codes vs output resolution for different formatting

	٦	ſwo's Comple	ment (default	t)	Offset Binary			
RESOLUTION (BIT)	14 16 18			20	14	16	18	20
V <sub>IN,MAX</sub>	0x1FFF	0x7FFF	0x1FFFF	0x7FFFF	0x3FFF	0xFFFF	0x3FFFF	0xFFFFF
0	0x0000		0x00000		0x2000	0x8000	0x20000	0x80000
V <sub>IN,MIN</sub>	0x2000	0x8000	0x20000 0x80000		0x0000		0x00000	

#### 8.3.6 Test Pattern

In order to enable in-circuit testing of the digital interface, the following test patterns are supported and enabled via SPI register writes (0x14/0x15/0x16). The test pattern generator is located after the decimation filter as shown in Figure 8-48. In decimation mode (real and complex), the test patterns replace the output data of the DDC - however channel A controls the test patterns for both channels.

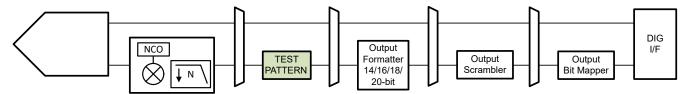


Figure 8-48. Test Pattern Generator

- RAMP Pattern: The step size needs to be configured in the CUSTOM PAT register according to the native resolution of the ADC. When selecting a higher output resolution then the additional LSBs will still be 0 in RAMP pattern mode.
  - 00001: 18-bit output resolution
  - 00100: 16-bit output resolution
  - 10000: 14-bit output resolution
- Custom Pattern: Configured in the CUSTOM PAT register



# 8.4 Device Functional Modes

### 8.4.1 Normal Operation

In normal operating mode, the entire ADC full-scale range gets converted to a digital output with 18-bit resolution.

## 8.4.2 Power Down Options

A global power down mode can be enabled via SPI as well as using the power down pin (PDN/SYNC). There is an internal pull-down 21 k $\Omega$  resistor on the PDN/SYNC input pin and the pin is active high - so the pin needs to be pulled high externally to enter global power down mode.

The SPI register map provides the capability to enable/disable individual blocks directly or via PDN pin mask in order to trade off power consumption vs wake up time as shown in Table 8-10.

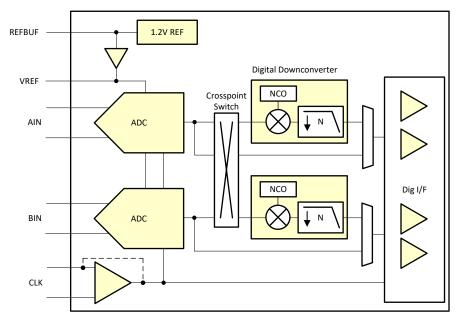


Figure 8-49. Power Down Configurations

<b>Table 8-10</b>	. Overview	of Power	Down	Options
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Function/ Register	PDN via SPI	Mask for Global PDN	Feature - Default	Power Impact	Wake-up time	Comment
ADC	Yes	-	Enabled			Both ADC channels are included in Global PDN automatically
Reference gain amplifier	Yes		Enabled	~ 0.4 mA	~3 us	Should only be powered down in power down state.
Internal 1.2V reference	Yes	Yes	External ref	~ 1-3.5 mA	~3 ms	Internal/external reference selection is available through SPI and REFBUF pin.
Clock buffer	Yes		Differential clock	~ 1 mA	n/a	Single ended clock input saves ~ 1mA compared to differential. Some programmability is available through the REFBUF pin.
Output interface drivers	Yes	-	Enabled varies n/a unused output driv		Depending on output interface mode, unused output drivers can be powered down for maximum power savings	
Decimation filter	Yes	-	Disabled	see electrical table	n/a	



#### 8.4.3 Digital Channel Averaging

The ADC368x includes a digital channel averaging feature which enables improvement of the ADC dynamic range (see Figure 8-50). The same input signal is given to both ADC inputs externally and the output of the two ADCs is averaged internally. By averaging, uncorrelated noise (e.g. ADC thermal noise) improves 3-dB while correlated noise (e.g. jitter in the clock path, reference noise) is unaffected. Therefore the averaging gives close to 3-dB improvement at low input frequencies but less at high input frequencies where clock jitter dominates the SNR.

The output from the digital averaging block is given out on the digital outputs of channel A or alternatively can be routed to the digital decimation filters using the digital mux.

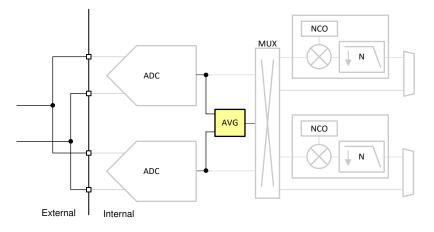


Figure 8-50. Digital Channel Averaging Diagram



# 8.5 Programming

The device is primarily configured and controlled using the serial programming interface (SPI); however, the device can operate in a default configuration without requiring the SPI interface. Also, the power down function and internal or external reference configuration is possible via pin control (PDN/SYNC and REFBUF pin).

Note

The power down command (via PIN or SPI) only goes in effect with the ADC sampling clock present.

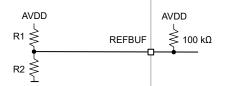
After initial power up, the default operating configuration for each device is shown in Table 8-11.

 Table 8-11. Default device configuration after power up

1	Table 0-11. Delaut device configuration after power up								
FEATURE	ADC3681	1 ADC3682							
Signal Input	Differential								
Auto-zero	Enabled	Enabled	Disabled						
Clock Input	Differential								
Reference		External							
Decimation		DDC bypass							
Interface	1-wire 1-wire 2-wire								
Output Format		2s complement							

# 8.5.1 Configuration using PINs only

The ADC voltage reference can be selected using the REFBUF pin. Even though there is an internal 100 k $\Omega$  pull-up resistor to AVDD, the REFBUF pin should be set to a voltage externally and not left floating. When using a voltage divider to set the REFBUF voltage (R1 and R2 in Figure 8-51), resistor values < 5 k $\Omega$  should be used.



#### Figure 8-51. Configuration of external voltage on REFBUF pin

Table 8-1	2. REFBUE voltage levels control voltage reference s	selection

REFBUF VOLTAGE	VOLTAGE REFERENCE OPTION	CLOCKING OPTION
> 1.7 V (Default)	External reference	Differential clock input
1.2 V (1.15-1.25V)	External 1.2V input on REFBUF pin using internal gain buffer	Differential clock input
0.5 - 0.7V	Internal reference	Differential clock input
< 0.1V	Internal reference	Single ended clock input

# 8.5.2 Configuration using the SPI interface

The device has a set of internal registers that can be accessed by the serial interface formed by the SEN (serial interface enable), SCLK (serial interface clock) and SDIO (serial interface data input/output) pins. Serially shifting bits into the device is enabled when SEN is low. Serial data input are latched at every SCLK rising edge when SEN is active (low). The serial data are loaded into the register at every 24th SCLK rising edge when SEN is low. When the word length exceeds a multiple of 24 bits, the excess bits are ignored. Data can be loaded in multiples of 24-bit words within a single active SEN pulse. The interface can function with SCLK frequencies from 12 MHz down to very low speeds (of a few hertz) and also with a non-50% SCLK duty cycle.

# 8.5.2.1 Register Write

The internal registers can be programmed following these steps:



- 1. Drive the SEN pin low
- 2. Set the R/W bit to 0 (bit A15 of the 16-bit address) and bits A[14:12] in address field to 0.
- 3. Initiate a serial interface cycle by specifying the address of the register (A[11:0]) whose content is written and
- 4. Write the 8-bit data that are latched in on the SCLK rising edges

Figure 8-52 shows the timing requirements for the serial register write operation.

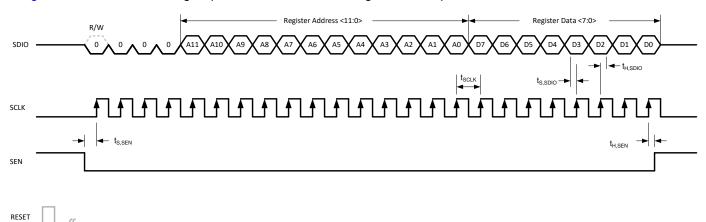


Figure 8-52. Serial Register Write Timing Diagram

#### 8.5.2.2 Register Read

The device includes a mode where the contents of the internal registers can be read back using the SDIO pin. This readback mode can be useful as a diagnostic check to verify the serial interface communication between the external controller and the ADC. The procedure to read the contents of the serial registers is as follows:

- 1. Drive the SEN pin low
- 2. Set the R/W bit (A15) to 1. This setting disables any further writes to the registers. Set A[14:12] in address field to 0.
- 3. Initiate a serial interface cycle specifying the address of the register (A[11:0]) whose content must be read
- 4. The device launches the contents (D[7:0]) of the selected register on the SDIO pin on SCLK falling edge
- 5. The external controller can capture the contents on the SCLK rising edge

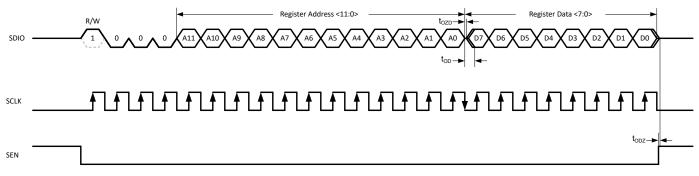


Figure 8-53. Serial Register Read Timing Diagram



# 8.6 Register Map

# Table 8-13. Register Map Summary

REGISTER ADDRESS				REGISTE				
A[11:0]	D7	D6	D5	D4	D3	D2	D1	D0
0x00	0	0	0	0	0	0	0	RESET
0x07		OP IF MAPPEF	ł	0	OP IF EN		OP IF SEL	
0x08	0	0	PDN CLKBUF	PDN REFAMP	0	PDN A	PDN B	PDN GLOBAL
0x09	0	0	PDN FCLKOUT	PDN DCLKOUT	PDN DA1	PDN DA0	PDN DB1	PDN DB0
0x0D	0	0	0	0	MASK CLKBUF	MASK REFAMP	MASK BG DIS	0
0x0E	SYNC PIN EN	SPI SYNC	SPI SYNC EN	0	REF CTRL	REF	SEL	SE CLK EN
0x11	0	0	0	0	0	DLL PDN	0	AZ EN
0x13	0	0	0	0	0	0	0	E-FUSE LD
0x14				CUSTOM	PAT [7:0]			
0x15				CUSTOM	PAT [15:8]			
0x16		TEST PAT B			TEST PAT A		CUSTOM	PAT [17:16]
0x19	FCLK SRC	0	0	FCLK DIV	0	0	0	TOG FCLK
0x1A	0	LVDS ½ SWING	0	0	0	0	0	0
0x1B	0x1B MAPPER EN 20B EN			IT MAPPER RE	S	0	0	0
0x1E	0	0	0	0	LVDS D	ATA DEL	LVDS D	CLK DEL
0x20				FCLK P	AT [7:0]			
0x21				FCLK PA	AT [15:8]			
0x22	0	SCR EN	0	0		FCLK PA	T [19:16]	
0x24	0	0	CH AVG EN	DDC	MUX	DIG BYP	DDC EN	0
0x25	DDC MUX EN		DECIMATION		REAL OUT	0	0	MIX PHASE
0x26	MIX G	AIN A	MIX RES A	FS/4 MIX A	MIX G	SAIN B	MIX RES B	FS/4 MIX B
0x27	0	0	0	OP ORDER A	Q-DEL A	FS/4 MIX PH A	0	0
0x2A				NCO /	A [7:0]			
0x2B				NCO A	[15:8]			
0x2C				NCO A	[23:16]			
0x2D				NCO A	[31:24]			
0x2E	0	0	0	OP ORDER B	Q-DEL B	FS/4 MIX PH B	0	0
0x31				NCO I	3 [7:0]	]		
0x32				NCO E	[15:8]			
0x33				NCO B	[23:16]			
0x34				NCO B	[31:24]			
0x390x60				OUTPUT BIT I				
0x610x88				OUTPUT BIT I	MAPPER CHB			
0x8F	0	0	0	0	0	0	FORMAT A	0
0x92	0	0	0	0	0	0	FORMAT B	0



# 8.6.1 Detailed Register Description

Figure 8-54. Register 0x00									
7	6	5	4	3	2	1	0		
0	0	0	0	0	0	0	RESET		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		

# Table 8-14. Register 0x00 Field Descriptions

Bit	Field	Туре	Reset	Description	
7-1	0	R/W	0	Must write 0	
0	RESET	R/W	0	This bit resets all internal registers to the default values and self clears to 0.	

#### Figure 8-55. Register 0x07

7	6	5	4	3	2	1	0
	OP IF MAPPER		0	OP IF EN		OP IF SEL	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

	Iable	e 8-15. Re	gister Ux	07 Field Descriptions
Bit	Field	Туре	Reset	Description
7-5	OP IF MAPPER	R/W	000	Output interface mapper. This register contains the proper output interface bit mapping for the different interfaces. The interface bit mapping is internally loaded from e-fuses and also requires a fuse load command to go into effect (0x13, D0). Register 0x07 along with the E-Fuse Load (0x13, D0) needs to be loaded first in the programming sequence since the E-Fuse load resets the SPI writes. After initial reset the default output interface variant is loaded automatically from fuse internally. However when reading back this register reads 000 until a value is written using SPI. 001: 2-wire, 18 and 14-bit 010: 2-wire, 16-bit 011: 1-wire 100: 0.5-wire others: not used
4	0	R/W	0	Must write 0
3	OP IF EN	R/W	0	Enables changing the default output interface mode (D2-D0).
2-0	OP IF SEL	R/W	000	Selection of the output interface mode. OP IF EN (D3) needs to be enabled also. After initial reset the default output interface is loaded automatically from fuse internally. However when reading back this register reads 000 until a value is written using SPI. 011: 2-wire 100: 1-wire 101: 0.5-wire others: not used

## Table 8-15. Register 0x07 Field Descriptions



#### Figure 8-56. Register 0x08

7	6 5		4 3		2	1	0	
0	0	PDN CLKBUF	PDN REFAMP	0	PDN A	PDN B	PDN GLOBAL	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	

## Table 8-16. Register 0x08 Field Descriptions

Bit	Field	Туре	Reset	Description		
7-6	0	R/W	0	Must write 0		
5	PDN CLKBUF	R/W	Powers down sampling clock buffer 0: Clock buffer enabled 1: Clock buffer powered down			
4	PDN REFAMP	R/W	N         0         Powers down internal reference gain amplifier         0: REFAMP enabled         1: REFAMP powered down         1: REFA			
3	0	R/W	0	Must write 0		
2	PDN B	R/W	0	Powers down ADC channel A 0: ADC channel A enabled 1: ADC channel A powered down		
1	PDN A	R/W	0	Powers down ADC channel B 0: ADC channel B enabled 1: ADC channel B powered down		
0	PDN GLOBAL	R/W	0	<ul> <li>Global power down via SPI</li> <li>0: Global power disabled</li> <li>1: Global power down enabled. Power down mask (register 0x0D) determines which internal blocks are powered down.</li> </ul>		

## Figure 8-57. Register 0x09

7	6	5	4	3	2	1	0
0	0	PDN FCLKOUT	PDN DCLKOUT	PDN DA1	PDN DA0	PDN DB1	PDN DB0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

## Table 8-17. Register 0x09 Field Descriptions

Bit	Field	Туре	Reset	Description				
7-6	0	R/W	0	Must write 0				
5	PDN FCLKOUT	R/W	0	Powers down frame clock (FCLK) LVDS output buffer 0: FCLK output buffer enabled 1: FCLK output buffer powered down				
4	PDN DCLKOUT	R/W	0	Powers down DCLK LVDS output buffer 0: DCLK output buffer enabled 1: DCLK output buffer powered down				
3	PDN DA1	R/W	0	Powers down LVDS output buffer for channel A, lane 1. NOT powered down automatically in 1-wire and 1/2-wire mode. 0: DA1 LVDS output buffer enabled 1: DA1 LVDS output buffer powered down				
2	PDN DA0	R/W	0	Powers down LVDS output buffer for channel A, lane 0. 0: DA0 LVDS output buffer enabled 1: DA0 LVDS output buffer powered down				
1	PDN DB1	R/W	0	Powers down LVDS output buffer for channel B, lane 1. NOT powered down automatically in 1-wire and 1/2-wire mode. 0: DB1 LVDS output buffer enabled 1: DB1 LVDS output buffer powered down				
0	PDN DB0	R/W	0	Powers down LVDS output buffer for channel B, lane 0. NOT powered down automatically in 1/2-wire mode. 0: DB0 LVDS output buffer enabled 1: DB0 LVDS output buffer powered down				



Figure 8-58. Register 0x0D (PDN GLOBAL MASK)									
7	6	5	4	3	2	1	0		
0	0	0	0	MASK CLKBUF	MASK REFAMP	MASK BG DIS	0		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		

# Table 8-18. Register 0x0D Field Descriptions

Bit	Field	Туре	Reset	Description
7-4	0	R/W	0	Must write 0
3	MASK CLKBUF	R/W	0	<ul> <li>Global power down mask control for sampling clock input buffer.</li> <li>0: Clock buffer will get powered down when global power down is exercised.</li> <li>1: Clock buffer will NOT get powered down when global power down is exercised.</li> </ul>
2	MASK REFAMP	R/W	0	<ul> <li>Global power down mask control for reference amplifier.</li> <li>0: Reference amplifier will get powered down when global power down is exercised.</li> <li>1: Reference amplifier will NOT get powered down when global power down is exercised.</li> </ul>
1	MASK BG DIS	R/W	0	<ul> <li>Global power down mask control for internal 1.2V bandgap voltage reference. Setting this bit reduces power consumption in global power down mode but increases the wake up time. See the power down option overview.</li> <li>0: Internal 1.2V bandgap voltage reference will NOT get powered down when global power down is exercised.</li> <li>1: Internal 1.2V bandgap voltage reference will get powered down when global power down is exercised.</li> </ul>
0	0	R/W	0	Must write 0



## Figure 8-59. Register 0x0E

7	6	5	4	3	2	1	0	
SYNC PIN EN	SPI SYNC	SPI SYNC EN	0	REF CTL	REF	SEL	SE CLK EN	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	

# Table 8-19. Register 0x0E Field Descriptions

Bit	Field	Туре	Reset	Description
7	SYNC PIN EN	R/W	0	<ul> <li>This bit controls the functionality of the SYNC/PDN pin.</li> <li>0: SYNC/PDN pin exercises global power down mode when pin is pulled high.</li> <li>1: SYNC/PDN pin issues the SYNC command when pin is pulled high.</li> </ul>
6	SPI SYNC	R/W	0	Toggling this bit issues the SYNC command using the SPI register write. SYNC using SPI must be enabled as well (D5). This bit doesn't self reset to 0. 0: Normal operation 1: SYNC command issued.
5	SPI SYNC EN	R/W	0	This bit enables synchronization using SPI instead of the SYNC/PDN pin. 0: Synchronization using SPI register bit disabled. 1: Synchronization using SPI register bit enabled.
4	0	R/W	0	Must write 0
3	REF CTL	R/W	0	<ul> <li>This bit determines if the REFBUF pin controls the voltage reference selection or the SPI register (D2-D1).</li> <li>0: The REFBUF pin selects the voltage reference option.</li> <li>1: Voltage reference is selected using SPI (D2-D1) and single ended clock using D0.</li> </ul>
2-1	REF SEL	R/W	00	Selects of the voltage reference option. REF CTRL (D3) must be set to 1. 00: Internal reference 01: External voltage reference (1.2V) using internal reference buffer (REFBUF) 10: External voltage reference 11: not used
0	SE CLK EN	R/W	0	Selects single ended clock input and powers down the differential sampling clock input buffer. REF CRTL (D3) must be set to 1. 0: Differential clock input 1: Single ended clock input



Figure 8-60. Register 0x11									
7	6	5	4	3	2	1	0		
0	0	0	0	0	DLL PDN	0	AZ EN		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		

# Table 8-20. Register 0x11 Field Descriptions

Bit	Field	Туре	Reset	Description
7-3	0	R/W	0	Must write 0
2	DLL PDN	R/W	0	This register applies ONLY to the ADC3683. It powers down the internal DLL, which is used to adjust the sampling time. This register must only be enabled when operating at sampling rates below 40 MSPS. When DLL PDN bit is enabled the sampling time is directly dependent on sampling clock duty cycle (with a 50/50 duty the sampling time is $T_S/2$ ). 0: Sampling time is $T_S/4$ 1: Sampling time is $T_S/2$ (only for sampling rates below 40 MSPS).
1	0	R/W	0	Must write 0
0	AZ EN	R/W	0	This bit enables the internal auto-zero circuitry. It is enabled by default for the ADC3681/82 and disabled for the ADC3683. ADC3681/82: 0: Auto-zero enabled 1: Auto-zero disabled ADC3683: 0: Auto-zero disabled 1: Auto-zero enabled

## Figure 8-61. Register 0x13

7	6	5	4	3	2	1	0
0	0	0	0	0	0		E-FUSE LD
R/W-0							

# Table 8-21. Register 0x13 Field Descriptions

Bit	Field	Туре	Reset	Description				
7-1	0	R/W	0	Must write 0				
0	E-FUSE LD	R/W	0	This register bit loads the internal bit mapping for different interfaces. After setting the interface in register 0x07, this E- FUSE LD bit needs to be set to 1 and reset to 0 for loading to go into effect. Register 0x07 along with the E-Fuse Load (0x13, D0) needs to be loaded first in the programming sequence since the E-Fuse load resets the SPI writes. 0: E-FUSE LOAD set 1: E-FUSE LOAD reset				



	Figure 8-62. Register 0x14/15/16							
7 6 5 4 3 2 1 0						0		
	CUSTOM PAT [7:0]							
				CUSTOM	PAT [15:8]			
TEST PAT B TEST PAT A CUSTOM PAT						PAT [17:16]		
	R/W-0	R/W-0	R/W-0	R/W-0 R/W-0 R/W-0 R/W-0 R/W-0				R/W-0

## Table 8-22. Register 0x14/15/16 Field Descriptions

Bit	Field	Туре	Reset	Description
7-0	CUSTOM PAT [17:0]	R/W	0000000	<ul> <li>This register is used for two purposes:</li> <li>It sets the constant custom pattern starting from MSB</li> <li>It sets the RAMP pattern increment step size.</li> <li>00001: Ramp pattern for 18-bit ADC</li> <li>00100: Ramp pattern for 16-bit ADC</li> <li>10000: Ramp pattern for 14-bit ADC</li> </ul>
7-5	TEST PAT B	R/W	000	Enables test pattern output mode for channel B (NOTE: The test pattern is set prior to the bit mapper and is based on native resolution of the ADC starting from the MSB). These work in either output format. 000: Normal output mode (test pattern output disabled)
				010: Ramp pattern: need to set proper increment using CUSTOM PAT register 011: Constant Pattern using CUSTOM PAT [17:0] in register 0x14/15/16. others: not used
4-2	TEST PAT A	R/W	000	Enables test pattern output mode for channel A (NOTE: The test pattern is set prior to the bit mapper and is based on native resolution of the ADC starting from the MSB). These work in either output format.
				000: Normal output mode (test pattern output disabled) 010: Ramp pattern: need to set proper increment using CUSTOM PAT register 011: Constant Pattern using CUSTOM PAT [17:0] in register 0x14/15/16. others: not used



#### Figure 8-63. Register 0x19 7 5 0 6 4 2 3 1 FCLK SRC 0 0 FCLK DIV 0 0 0 TOG FCLK R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0

# Table 8-23. Register 0x19 Field Descriptions

Bit	Field	Туре	Reset	Description
7	FCLK SRC	R/W	0	User has to select if FCLK signal comes from ADC or from DDC block. Here real decimation is treated same as bypass mode 0: FCLK generated from ADC. FCLK SRC set to 0 for DDC bypass, real decimation mode and 1/2-w complex decimation mode. 1: FCLK generated from DDC block. In complex decimation mode only this bit needs to be set for 2-w and 1-w output interface mode but NOT for 1/2-w mode.
6-5	0	R/W	0	Must write 0
4	FCLK DIV	R/W	0	<ul> <li>This bit needs to be set to 1 for 2-w output mode in bypass/real decimation mode only .</li> <li>0: All output interface modes except 2-w decimation bypass and real decimation mode.</li> <li>1: 2-w output interface mode for decimation bypass and real decimation.</li> </ul>
3-1	0	R/W	0	Must write 0
0	TOG FCLK	R/W	0	<ul> <li>This bit adjusts the FCLK signal appropriately for 1/2-wire mode where FCLK is stretched to cover channel A and channel B.</li> <li>This bit ONLY needs to be set in 1/2-wire mode with complex decimation mode.</li> <li>0: all other modes.</li> <li>1: FCLK for 1/2-wire complex decimation mode.</li> </ul>

# Table 8-24. Configuration of FCLK SRC and FCLK DIV Register Bits vs Serial Interface

BYPASS/DECIMATION	SERIAL INTERFACE	FCLK SRC	FCLK DIV	TOG FCLK
	2-wire	0	1	0
Decimation Bypass/ Real Decimation	1-wire	0	0	0
	1/2-wire	0	0	0
	2-wire	1	0	0
Complex Decimation	1-wire	1	0	0
	1/2-wire	0	0	1



#### Figure 8-64. Register 0x1A

				- J			
7	6	5	4	3	2	1	0
0	LVDS ½ SWING	0	0	0	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

# Table 8-25. Register 0x1A Field Descriptions

Bit	Field	Туре	Reset	Description
7	0	R/W	0	Must write 0
6	LVDS ½ SWING	R/W	0	This bit reduces the LVDS output current from 3.5mA to 1.75mA which reduces power consumption.
5-0	0	R/W	0	Must write 0

# Figure 8-65. Register 0x1B

7	6	5	4	3	2	1	0
MAPPER EN	20B EN	E	BIT MAPPER RES	3	0	0	0
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

	т	able 8-26. Re	gister 0x <sup>,</sup>	1B Field Descriptions
Bit	Field	Туре	Reset	Description
7	MAPPER EN	R/W	0	This bit enables changing the resolution of the output (including output serialization factor) in bypass mode only. This bit is not needed for 20-bit resolution output. 0: Output bit mapper disabled. 1: Output bit mapper enabled.
6	20B EN	R/W	0	This bit enables 20-bit output resolution which can be useful for very high decimation settings so that quantization noise doesn't impact the ADC performance. 0: 20-bit output resolution disabled. 1: 20-bit output resolution enabled.
5-3	BIT MAPPER RES	R/W	000	Sets the output resolution using the bit mapper. MAPPER EN bit (D6) needs to be enabled when operating in bypass mode 000: 18 bit 001: 16 bit 010: 14 bit all others, n/a
2-0	0	R/W	0	Must write 0

## Table 8-27. Register Settings for Output Bit Mapper vs Operating Mode

BYPASS/DECIMATION	OUTPUT RESOLUTION	MAPPER EN (D7)	BIT MAPPER RES (D5-D3)
Decimation Bypass	Resolution Change	1	000: 18-bit
Real Decimation	Resolution Change (default 18-bit)	0	001: 16-bit
Complex Decimation	Resolution Change (delaut To-bit)	0	010: 14-bit



#### Figure 8-66. Register 0x1E

7	6	5	4	3	2	1	0		
0	0	0	0	LVDS DATA DEL		LVDS DO	CLK DEL		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		

#### Table 8-28. Register 0x1E Field Descriptions

Bit	Field	Туре	Reset	Description
7-4	0	R/W 0		Must write 0
3-2	LVDS DATA DEL	R/W	00	These bits adjust the output timing of the SLVDS output data. 00: no delay 01: Data advanced by 50 ps 10: Data delayed by 50 ps 11: Data delayed by 100 ps
1-0	LVDS DCLK DEL	R/W	00	These bits adjust the output timing of the SLVDS DCLK output. 00: no delay 01: DCLK advanced by 50 ps 10: DCLK delayed by 50 ps 11: DCLK delayed by 100 ps

## Figure 8-67. Register 0x20/21/22

7	6	5	4	3	2	1	0		
FCLK PAT [7:0]									
	FCLK PAT [15:8]								
0	0 SCR EN 0 0 FCLK PAT [19:16]								
R/W-0	R/W-0	R/W-0	-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0						

#### Table 8-29. Register 0x20/21/22 Field Descriptions

		U U		
Bit	Field	Туре	Reset	Description
7-0	FCLK PAT [19:0]	R/W	0xFFC00	These bits can adjust the duty cycle of the FCLK. In decimation bypass mode the FCLK pattern gets adjusted automatically for the different output resolutions. Table 8-30 shows the proper FCLK pattern values for 1-wire and 1/2-wire in real/complex decimation.
6	SCR EN	R/W	0	This bit enables the output data scrambler. Digital bypass (0x24, D2) needs to be set as well. 0: Output scrambling disabled 1: Output scrambling enabled

# Table 8-30. FCLK Pattern for different resolution based on interface

DECIMATION	OUTPUT RESOLUTION	2-WIRE	1-WIRE	1/2-WIRE
	14-bit		0xFE000	
REAL DECIMATION	16-bit		0xFF000	Lieo Dofouit
REAL DECIMATION	18-bit		0xFF800	Use Default
	20-bit	Use Default	0xFFC00	
	14-bit			0.55555
COMPLEX	16-bit			
DECIMATION	18-bit		0xFFFFF	0xFFFFF
	20-bit			



# Figure 8-68. Register 0x24

7	6	5	4	3	2	1	0		
0	0	CH AVG EN	DDC MUX		DIG BYP	DDC EN	0		
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		

## Table 8-31. Register 0x24 Field Descriptions

Bit	Field	Туре	Reset	Description
7-6	0	R/W	0	Must write 0
5	CH AVG EN	R/W	0	<ul> <li>Averages the output of ADC channel A and channel B together.</li> <li>The DDC MUX has to be enabled and set to '11'. The decimation filter needs to be enabled and set to bypass (fullrate output) or decimation and DIG BYP set to 1.</li> <li>0: Channel averaging feature disabled</li> <li>1: Output of channel A and channel B are averaged: (A+B)/2.</li> </ul>
4-3	DDC MUX	R/W	0	Configures DDC MUX in front of the decimation filter. 00: ADC channel A connected to DDC A; ADC Channel B connected to DDC B 01: ADC channel A connected to DDC A and DDC B. 10: ADC channel B connected to DDC A and DDC B. 11: Output of ADC averaging block (see CH AVG EN) given to DDC A and DDC B.
2	DIG BYP	R/W	0	<ul> <li>This bit needs to be set to enable digital features block which includes decimation and scrambling.</li> <li>0: Digital feature block bypassed - lowest latency</li> <li>1: Data path includes digital features</li> </ul>
1	DDC EN	R/W	0	Enables internal decimation filter for both channels 0: DDC disabled. 1: DDC enabled.
0	0	R/W	0	Must write 0

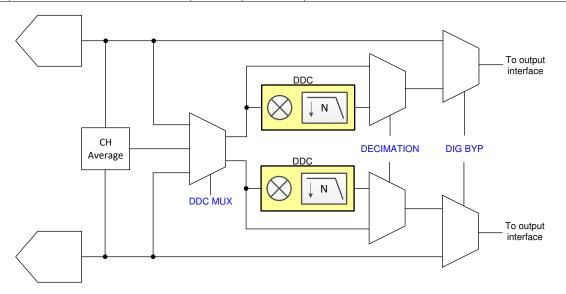


Figure 8-69. Register control for digital features



	Figure 8-70. Register 0x25											
7	6	5	4	3	2	1	0					
DDC MUX EN		DECIMATION		REAL OUT	0	0	MIX PHASE					
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0					

## Table 8-32. Register 0x25 Field Descriptions

Bit	Field Type Reset			Description
7	DDC MUX EN	R/W	0	Enables the digital mux between ADCs and decimation filters. This bit is required for DDC mux settings in register 0x24 (D4, D3) to go into effect. 0: DDC mux disabled 1: DDC mux enabled
6-4	DECIMATION	R/W	000	Complex decimation setting. This applies to both channels.
				000: Bypass mode (no decimation)100: Decimation by 16001: Decimation by 2101: Decimation by 32010: Decimation by 4others: not used011: Decimation by 8
3	REAL OUT	R/W	0	This bit selects real output decimation. This mode applies to both channels. In this mode, the decimation filter is a low pass filter and no complex mixing is performed to reduce power consumption. For maximum power savings the NCO in this case should be set to 0. 0: Complex decimation 1: Real decimation
2-1	0	R/W	0	Must write 0
0	MIX PHASE	R/W	0	This bit used to invert the NCO phase 0: NCO phase as is. 1: NCO phase inverted.

# Figure 8-71. Register 0x26

7	7 6 5		4	3	2	1	0
MIX G	GAIN A	MIX RES A	FS/4 MIX A	MIX G	AIN B	MIX RES B	FS/4 MIX B
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0 R/W-0		R/W-0	R/W-0

#### Table 8-33. Register 0x26 Field Descriptions

Bit	Field	Туре	Reset	Description
7-6	MIX GAIN A	R/W	00	This bit applies a 0, 3 or 6-dB digital gain to the output of digital mixer to compensate for the mixing loss for channel A.00: no digital gain added01: 3-dB digital gain added (should be enabled with real decimation)10: 6-dB digital gain added (should be enabled with complex decimation)11: not used
5	MIX RES A	R/W	0	Toggling this bit resets the NCO phase of channel A and loads the new NCO frequency. This bit does not self reset.
4	FS/4 MIX A	R/W	0	Enables FS/4 mixing for DDC A (complex decimation only). 0: FS/4 mixing disabled. 1: FS/4 mixing enabled.
3-2	MIX GAIN B	R/W	00	This bit applies a 0, 3 or 6-dB digital gain to the output of digitalmixer to compensate for the mixing loss for channel B.00: no digital gain added01: 3-dB digital gain added (should be enabled with realdecimation)10: 6-dB digital gain added (should be enabled with complexdecimation)11: not used
1	MIX RES B	R/W	0	Toggling this bit resets the NCO phase of channel B and loads the new NCO frequency. This bit does not self reset.



	Table 8-33. Register 0x26 Field Descriptions (continued)									
Bit Field Type Reset Description										
0	FS/4 MIX B	R/W	0	Enables FS/4 mixing for DDC B (complex decimation only). 0: FS/4 mixing disabled. 1: FS/4 mixing enabled.						

#### Figure 8-72. Register 0x27

_					<u> </u>			
	7	6	5	4	3	2	1	0
	0	0	0	OP ORDER A	Q-DEL A	FS/4 MIX PH A	0	0
	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

## Table 8-34. Register 0x27 Field Descriptions

Bit	Field	Туре	Reset	Description	
7-5	0	R/W	0	Must write 0	
4	OP ORDER A	R/W       0       Swaps the I and Q output order for channel A. See Table for recommended settings. Only used with complex decines to 0 with real decimation.         0: Output order is I[n], Q[n]       1: Output order is swapped: Q[n], I[n]			
3	Q-DEL A	R/W	0	This delays the Q-sample output of channel A by one. See Table 8-35 for recommended settings. Only used with complex decimation. Set to 0 with real decimation. 0: Output order is I[n], Q[n] 1: Q-sample is delayed by 1 sample: I[n], Q[n+1], I[n+1], Q[n+2]	
2	FS/4 MIX PH A	R/W	0	Inverts the mixer phase for channel A when using FS/4 mixer. 0: Mixer phase is non-inverted 1: Mixer phase is inverted	
1-0	0	R/W	0	Must write 0	

## Table 8-35. OP-ORDER and Q-DELAY Register Settings for Complex Decimation

SLVDS INTERFACE	OP-ORDER	Q-DELAY
2-wire	1	0
1-wire	0	1
1/2-wire	1	1

#### Figure 8-73. Register 0x2A/B/C/D

7 6 5 4 3 2 1 0												
NCO A [7:0]												
	NCO A [15:8]											
			NCO A	[23:16]								
	NCO A [31:24]											
R/W-0	R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0											

## Table 8-36. Register 0x2A/2B/2C/2D Field Descriptions

Bit	Field	Туре	Reset	Description
7-0	NCO A [31:0]	R/W	-	Sets the 32 bit NCO value for decimation filter channel A. The NCO value is $f_{NCO} \times 2^{32}$ / F <sub>S</sub> . In real decimation mode these registers are automatically set to 0.



	Figure 8-74. Register 0x2E											
7	6	5	4	3	2	1	0					
0	0	0	OP ORDER B	Q-DEL B	FS/4 MIX PH B	0	0					
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0					

# Table 8-37. Register 0x2E Field Descriptions

Bit	Field	Туре	Reset	Description
7-5	0	R/W	0	Must write 0
4	OP ORDER B	R/W	0	Swaps the I and Q output order for channel B. See Table 8-35 for recommended settings. Only used with complex decimation. Set to 0 with real decimation. 0: Output order is I[n], Q[n] 1: Output order is swapped: Q[n], I[n]
3	Q-DEL B	R/W	0	This delays the Q-sample output of channel B by one. See Table 8-35 for recommended settings. Only used with complex decimation. Set to 0 with real decimation. 0: Output order is I[n], Q[n] 1: Q-sample is delayed by 1 sample: I[n], Q[n+1], I[n+1], Q[n+2]
2	FS/4 MIX PH B	R/W	0	Inverts the mixer phase for channel B when using FS/4 mixer. 0: Mixer phase is non-inverted 1: Mixer phase is inverted
1-0	0	R/W	0	Must write 0

# Figure 8-75. Register 0x31/32/33/34

7	6	5	4	3	2	1	0				
	NCO B [7:0]										
	NCO B [15:8]										
			NCO B	[23:16]							
	NCO B [31:24]										
R/W-0	R/W-0	R/W-0	R/W-0 R/W-0 R/W-0 R/W-0								

#### Table 8-38. Register 0x31/32/33/34 Field Descriptions

Bit	Field	Туре	Reset	Description
7-0	NCO B [31:0]	R/W		Sets the 32 bit NCO value for decimation filter channel B. The NCO value is $f_{NCO} \times 2^{32}$ / $F_S$ . In real decimation mode these registers are automatically set to 0.

# Figure 8-76. Register 0x39..0x60

7	6	5	4	3	2	1	0	
	OUTPUT BIT MAPPER CHA							
R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0							R/W-0	

#### Table 8-39. Register 0x39..0x60 Field Descriptions

Bit	Field	Туре	Reset	Description					
7-0	OUTPUT BIT MAPPER CHA	R/W		These registers are used to reorder the output data bus. See the Section 8.3.5.3 on how to program it.					



	Figure 8-77. Register 0x610x88											
7 6 5 4 3 2 1 0												
			OUTPUT BIT I	MAPPER CHB								
R/W-0	R/W-0	R/W-0 R/W-0 R/W-0 R/W-0					R/W-0					

#### Table 8-40. Register 0x61..0x88 Field Descriptions

Bit	Field	Туре	Reset	Description
7-0	OUTPUT BIT MAPPER CHB	R/W		These registers are used to reorder the output data bus. See the Section 8.3.5.3 on how to program it.

#### Figure 8-78. Register 0x8F

7	6	5	4	3	2	1	0
0	0	0	0	0	0	FORMAT A	0
R/W-0	R/W-0						

#### Table 8-41. Register 0x8F Field Descriptions

Bit	Field	Туре	De Reset Description						
7-2	0	R/W	0	Must write 0					
1	FORMAT A	R/W		This bit sets the output data format for channel A. Digital bypass register bit (0x24, D2) needs to be enabled as well. 0: 2s complement 1: Offset binary					
0	0	R/W	0	Must write 0					

#### Figure 8-79. Register 0x92

7	6	5	4	3	2	1	0
0	0	0	0	0	0	FORMAT B	0
R/W-0	R/W-0						

#### Table 8-42. Register 0x92 Field Descriptions

Bit	Field	Туре	Reset Description					
7-2	0	R/W	0	Must write 0				
1	FORMAT B	R/W	0	This bit sets the output data format for channel B. Digital bypass register bit (0x24, D2) needs to be enabled as well. 0: 2s complement 1: Offset binary				
0	0	R/W	0	Must write 0				



# **9** Application Information Disclaimer

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

# 9.1 Typical Application

A spectrum analyzer is a typical frequency domain application for the ADC368x and its front end circuitry is very similar to several other systems such as software defined radio (SDR), sonar, radar or communications. Some applications require frequency coverage including DC or near DC (such as, sonar), so it is included in this example.

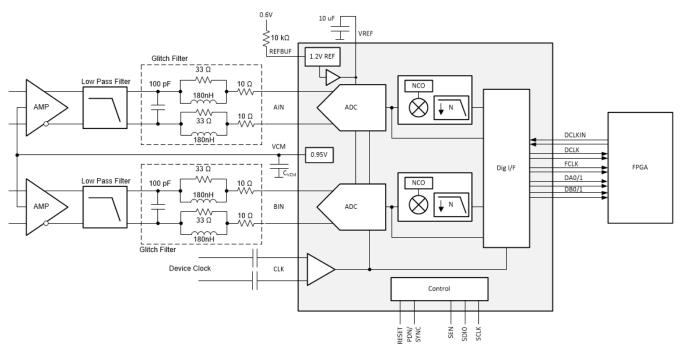


Figure 9-1. Typical configuration for a spectrum analyzer with DC support

# 9.1.1 Design Requirements

Frequency domain applications cover a wide range of frequencies from low input frequencies at or near DC in the 1st Nyquist zone to undersampling in higher Nyquist zones. If very low input frequency is supported then the input has to be DC coupled and the ADC driven by a fully differential amplifier (FDA). If low frequency support is not needed then AC coupling and use of a balun may be more suitable.

The internal reference is used since DC precision is not needed. However the ADC AC performance is highly dependent on the quality of the external clock source. If in-band interferers can be present then the ADC SFDR performance will be a key care about as well. A higher ADC sampling rate is desirable in order to relax the external anti-aliasing filter – an internal decimation filter can be used to reduce the digital output rate afterwards.

Table 9-1. Design key care-abouts						
FEATURE         DESCRIPTION						
Signal Bandwidth	DC to 20 MHz					
Input Driver	Single ended to differential signal conversion and DC coupling					

# Table 9-1. Design key care-abouts

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#### Table 9-1. Design key care-abouts (continued)

FEATURE	DESCRIPTION
Clock Source	External clock with low jitter

When designing the amplifier/filter driving circuit, the ADC input full-scale voltage needs to be taken into consideration. For example, the ADC368x input full-scale is 3.2 Vpp. When factoring in ~ 1 dB for insertion loss of the filter, then the amplifier needs to deliver close to 3.6 Vpp. The amplifier distortion performance will degrade with a larger output swing and considering the ADC common mode input voltage the amplifier may not be able to deliver the full swing. The ADC368x provides an output common mode voltage of 0.95V and the THS4541 for example can only swing within 250 mV of its negative supply. A unipolar 3.3 V amplifier power supply will thus limit the maximum voltage swing to ~ 2.8 Vpp. Hence if a larger output swing is required (factoring in filter insertion loss) then a negative supply for the amplifier is needed in order to eliminate that limitation. Additionally input voltage protection diodes may be needed to protect the ADC from over-voltage events.

# Table 9-2. Output voltage swing of THS4541 vs power supply

DEVICE	MIN OUTPUT VOLTAGE	MAX SWING WITH 3.3 V/ 0 V SUPPLY	MAX SWING WITH 3.3 V/ -1.0 V SUPPLY
THS4541	VS- + 250 mV	2.8 Vpp	6.8 Vpp

## 9.1.2 Detailed Design Procedure

#### 9.1.2.1 Input Signal Path

Depending on desired input signal frequency range the THS4551 and THS4541 provide very good low power options to drive the ADC inputs. Table 9-3 provides a comparison between the THS4551 and THS4541 and the power consumption vs usable frequency trade off.

DEVICE	CURRENT (IQ) PER CHANNEL	USABLE FREQUENCY RANGE
THS4561	0.8 mA	< 3 MHz
THS4551	1.4 mA	< 10 MHz
THS4541	10 mA	< 70 MHz

#### Table 9-3. Fully Differential Amplifier Options

The low pass filter design (topology, filter order) is driven by the application itself. However, when designing the low pass filter, the optimum load impedance for the amplifier should be taken into consideration as well. Between the low pass filter and the ADC input the sampling glitch filter needs to added as well as shown in Section 8.3.1.2.1. In this example the DC - 30 MHz glitch filter is selected.

#### 9.1.2.2 Sampling Clock

Applications operating with low input frequencies (such as DC to 20 MHz) typically are less sensitive to performance degradation due to clock jitter. The internal ADC aperture jitter improves with faster rise and fall times (i.e. square wave vs sine wave). Table 9-4 provides an overview of the estimated SNR performance of the ADC368x based on different amounts of jitter of the external clock source. The SNR is estimated based on ADC368x thermal noise of 84.2dBFS and input signal at -1dBFS.

#### Table 9-4. ADC SNR performance across vs input frequency for different amounts of external clock jitter

INPUT FREQUENCY	T <sub>J,EXT</sub> = 100 fs	s T <sub>J,EXT</sub> = 250 fs T <sub>J,EXT</sub> = 5		T <sub>J,EXT</sub> = 1 ps	
5 MHz	84.2	84.1	83.9	83.4	
10 MHz	84.0	83.9	83.3	81.5	
20 MHz	83.6	83.0	81.3	77.8	

Termination of the clock input should be considered for long clock traces.

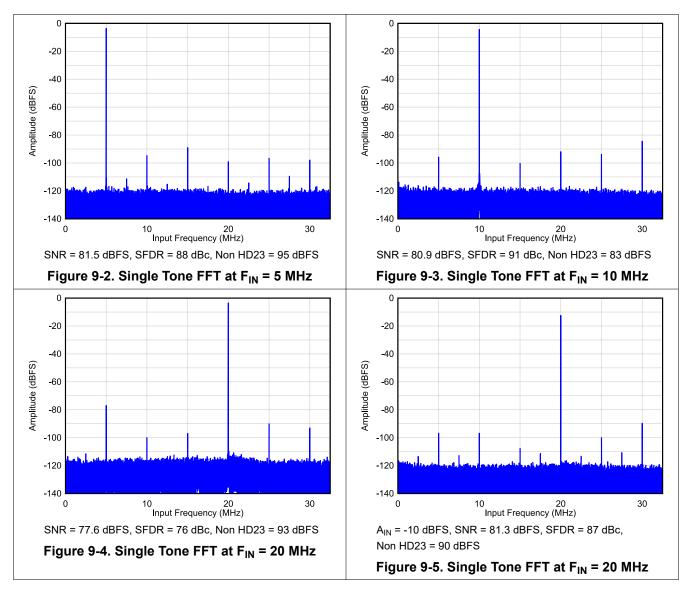
#### 9.1.2.3 Voltage Reference

The ADC368x is configured to internal reference operation by applying 0.6 V to the REFBUF pin.



# 9.1.3 Application Curves

The following FFT plots show the performance of THS4541 driving the ADC3683 operated at 65 MSPS with a full-scale input at -1 dBFS and input frequencies of 5, 10 and 20 MHz.





# 9.2 Initialization Set Up

After power-up, the internal registers must be initialized to their default values through a hardware reset by applying a high pulse on the RESET pin, as shown in Figure 9-6.

- 1. Apply AVDD and IOVDD (no specific sequence required). After AVDD is applied the internal bandgap reference will power up and settle out in ~ 2ms.
- 2. Configure REFBUF pin (pull high or low even if configured via SPI later on) and apply the sampling clock.
- 3. Apply hardware reset. After hardware reset is released, the default registers are loaded from internal fuses and the internal power up capacitor calibration is initiated. The calibration takes approximately 200000 clock cycles.
- 4. Begin programming using SPI interface.

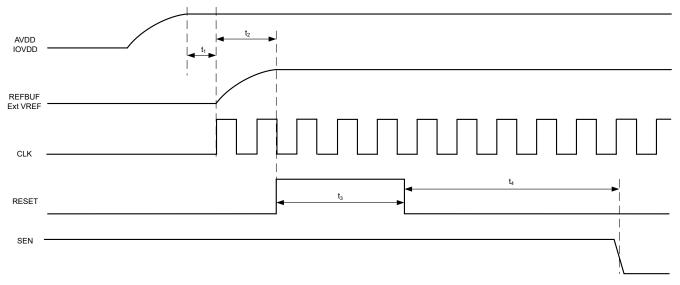


Figure 9-6. Initialization of serial registers after power up

#### Table 9-5. Power-up timing

		MIN	TYP	MAX	UNIT
t <sub>1</sub>	Power-on delay: delay from power up to logic level of REFBUF pin	2			ms
t <sub>2</sub>	Delay from REFBUF pin logic level to RESET rising edge	100			ns
t <sub>3</sub>	RESET pulse width	1			us
t <sub>4</sub>	Delay from RESET disable to SEN active	~ 200000			clock cycles

# 9.2.1 Register Initialization During Operation

If required, the serial interface registers can be cleared and reset to default settings during operation either:

- through a hardware reset or
- by applying a software reset. When using the serial interface, set the RESET bit (D0 in register address 0x00) high. This setting initializes the internal registers to the default values and then self-resets the RESET bit low. In this case, the RESET pin is kept low.

After hardware or software reset the wait time is also ~ 200000 clock cycles before the SPI registers can be programmed.



#### 9.3 Power Supply Recommendations

The ADC368x requires two different power-supplies. The AVDD rail provides power for the internal analog circuits and the ADC itself while the IOVDD rail powers the digital interface and the internal digital circuits like decimation filter or output interface mapper. Power sequencing is not required.

The AVDD power supply must be low noise in order to achieve data sheet performance. In applications operating near DC, the 1/f noise contribution of the power supply needs to be considered as well. The ADC is designed for very good PSRR which aides with the power supply filter design.

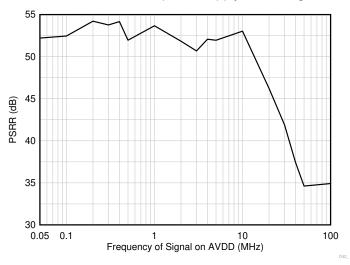


Figure 9-7. Power supply rejection ratio (PSRR) vs frequency

There are two recommended power-supply architectures:

- 1. 1. Step down using high-efficiency switching converters, followed by a second stage of regulation using a low noise LDO to provide switching noise reduction and improved voltage accuracy.
- 2. 2. Directly step down the final ADC supply voltage using high-efficiency switching converters. This approach provides the best efficiency, but care must be taken to ensure switching noise is minimized to prevent degraded ADC performance.

TI WEBENCH® Power Designer can be used to select and design the individual power-supply elements needed: see the WEBENCH® Power Designer

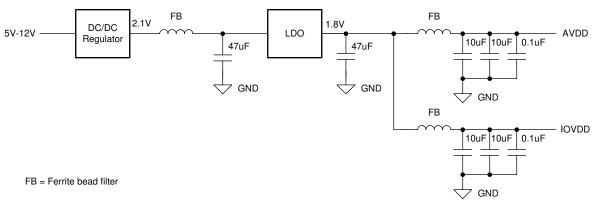
Recommended switching regulators for the first stage include the TPS62821, and similar devices.

Recommended low dropout (LDO) linear regulators include the TPS7A4701, TPS7A90, LP5901, and similar devices.

For the switch regulator only approach, the ripple filter must be designed with a notch frequency that aligns with the switching ripple frequency of the DC/DC converter. Note the switching frequency reported from WEBENCH® and design the EMI filter and capacitor combination to have the notch frequency centered as needed. Figure 9-8 and Figure 9-9 illustrate the two approaches.

AVDD and IOVDD supply voltages should not be shared in order to prevent digital switching noise from coupling into the analog signal chain.







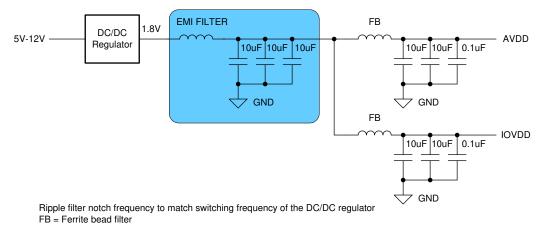


Figure 9-9. Example Switcher-Only Approach

## 9.4 Layout

## 9.4.1 Layout Guidelines

There are several critical signals which require specific care during board design:

- 1. Analog input and clock signals
  - Traces should be as short as possible and vias should be avoided where possible to minimize impedance discontinuities.
  - Traces should be routed using loosely coupled  $100-\Omega$  differential traces.
  - Differential trace lengths should be matched as close as possible to minimize phase imbalance and HD2 degradation.
- 2. Digital output interface
  - Traces should be routed using tightly coupled  $100-\Omega$  differential traces.
- 3. Voltage reference
  - The bypass capacitor should be placed as close to the device pins as possible and connected between VREF and REFGND on top layer avoiding vias.
  - Depending on configuration an additional bypass capacitor between REFBUF and REFGND may be recommended and should also be placed as close to pins as possible on top layer.
- 4. Power and ground connections
  - Provide low resistance connection paths to all power and ground pins.
  - Use power and ground planes instead of traces.
  - Avoid narrow, isolated paths which increase the connection resistance.
  - Use a signal/ground/power circuit board stackup to maximize coupling between the ground and power plane.



#### 9.4.2 Layout Example

The following screen shot shows the top layer of the ADC368x EVM.

- Signal and clock inputs are routed as differential signals on the top layer avoiding vias.
- SLVDS output interface lanes are routed differential and length matched
- Bypass caps are close to the VREF pin on the top layer avoiding vias.

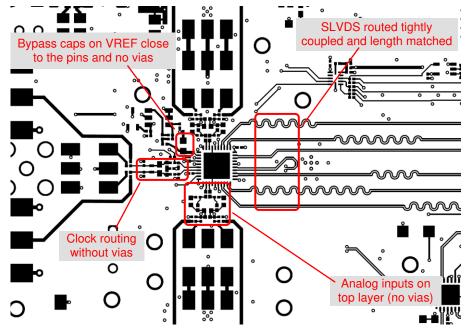


Figure 9-10. Layout example: top layer of ADC368x EVM



## 10 Device and Documentation Support

## **10.1 Receiving Notification of Documentation Updates**

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### **10.2 Support Resources**

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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#### 10.3 Trademarks

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#### **10.4 Electrostatic Discharge Caution**



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 10.5 Glossary

TI Glossary This glossary lists and explains terms, acronyms, and definitions.

## 11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
						(4)	(5)		
ADC3681IRSBR	Active	Production	WQFN (RSB)   40	3000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	AZ3681
ADC3681IRSBT	Active	Production	WQFN (RSB)   40	250   SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	AZ3681
ADC3682IRSBR	Active	Production	WQFN (RSB)   40	3000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	AZ3682
ADC3682IRSBT	Active	Production	WQFN (RSB)   40	250   SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	AZ3682
ADC3683IRSBR	Active	Production	WQFN (RSB)   40	3000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	AZ3683
ADC3683IRSBT	Active	Production	WQFN (RSB)   40	250   SMALL T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	AZ3683

<sup>(1)</sup> **Status:** For more details on status, see our product life cycle.

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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#### OTHER QUALIFIED VERSIONS OF ADC3683 :

• Space : ADC3683-SP

NOTE: Qualified Version Definitions:

• Space - Radiation tolerant, ceramic packaging and qualified for use in Space-based application



Texas

STRUMENTS

## TAPE AND REEL INFORMATION





#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



All dimensions are nominal												
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADC3681IRSBR	WQFN	RSB	40	3000	330.0	12.4	5.3	5.3	1.5	8.0	12.0	Q2
ADC3682IRSBR	WQFN	RSB	40	3000	330.0	12.4	5.3	5.3	1.5	8.0	12.0	Q2
ADC3683IRSBR	WQFN	RSB	40	3000	330.0	12.4	5.3	5.3	1.5	8.0	12.0	Q2



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# PACKAGE MATERIALS INFORMATION

5-Dec-2023



\*All dimensions are nominal

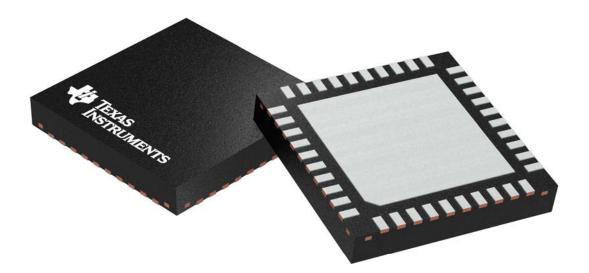
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADC3681IRSBR	WQFN	RSB	40	3000	350.0	350.0	43.0
ADC3682IRSBR	WQFN	RSB	40	3000	350.0	350.0	43.0
ADC3683IRSBR	WQFN	RSB	40	3000	350.0	350.0	43.0

## **RSB 40**

5 x 5 mm, 0.4 mm pitch

# **GENERIC PACKAGE VIEW**

# WQFN - 0.8 mm max height PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



4207182/D

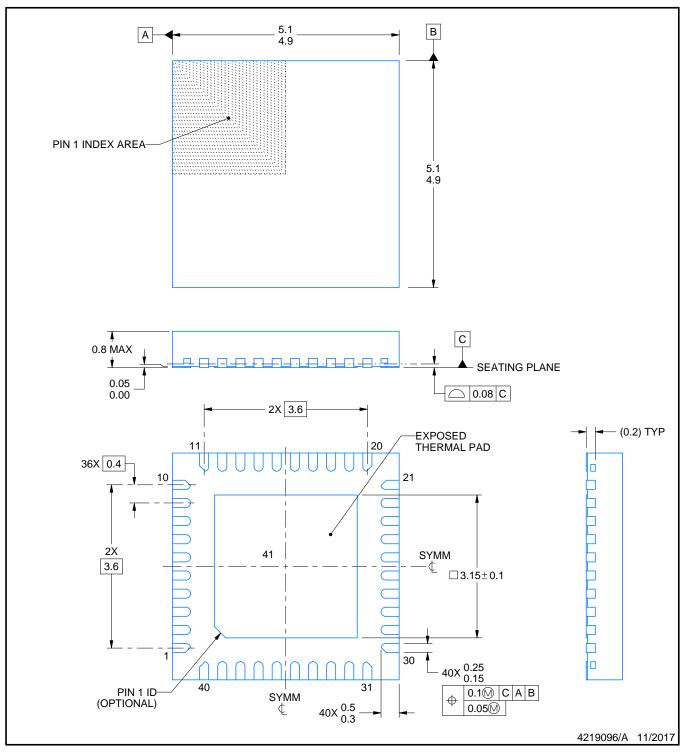
# **RSB0040E**



## **PACKAGE OUTLINE**

## WQFN - 0.8 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

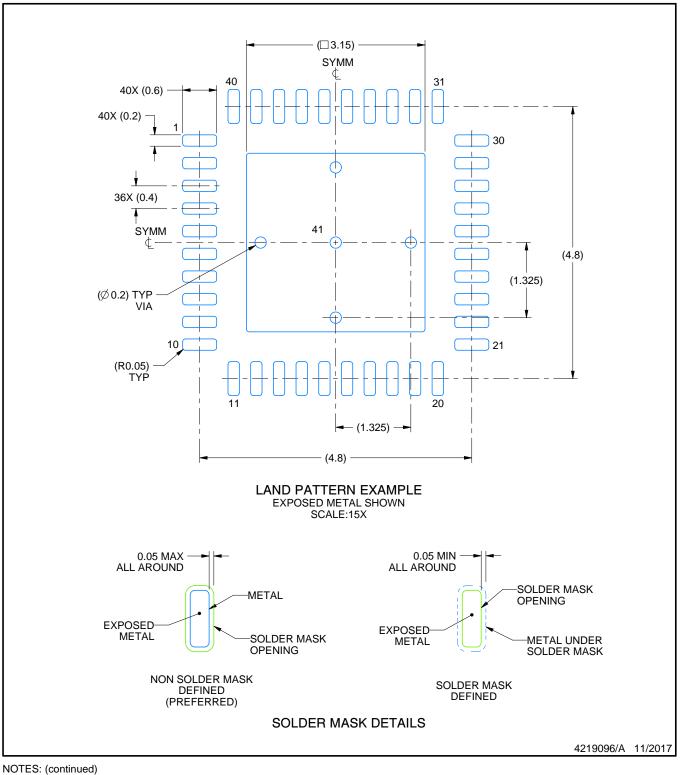


# **RSB0040E**

# **EXAMPLE BOARD LAYOUT**

## WQFN - 0.8 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

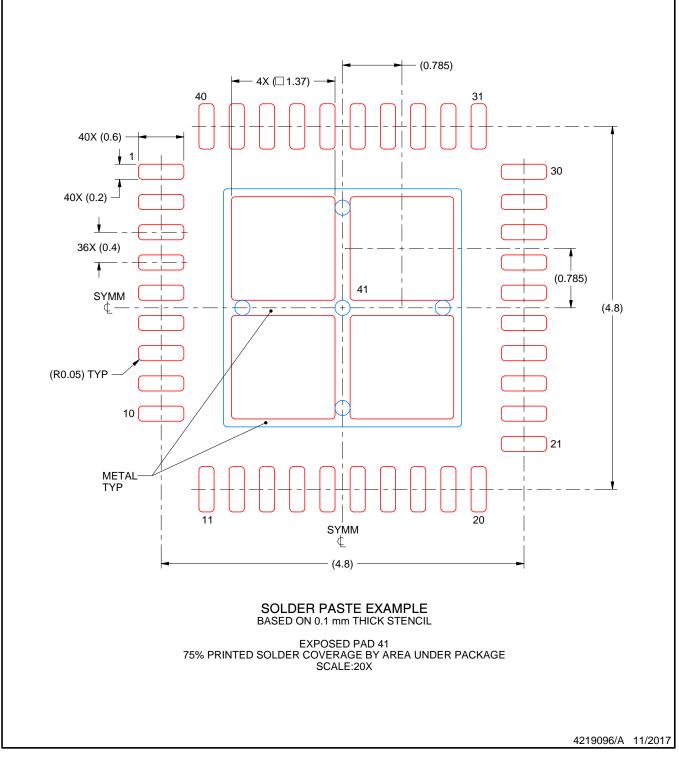


# **RSB0040E**

# **EXAMPLE STENCIL DESIGN**

## WQFN - 0.8 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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