

ADC3568, ADC3569 Single-Channel, 16-Bit 250MSPS and 500MSPS Analog-to-Digital **Converter (ADC)**

1 Features

- 16-bit, single channel 250 and 500MSPS ADC
- Noise spectral density: -160.4dBFS/Hz
- Thermal Noise: 76.4dBFS
- Single core (non-interleaved) ADC architecture
- Power consumption:
 - 435mW (500MSPS)
 - 369mW (250MSPS)
- Aperture jitter: 75fs
- Buffered analog inputs
 - Programmable 100Ω and 200Ω termination
- Input fullscale: 2V_{PP}
- Full power input bandwidth (-3dB): 1.4GHz
- Spectral performance ($f_{IN} = 70MHz$, -1dBFS):
 - SNR: 75.6dBFS
 - SFDR HD2,3: 80dBc
 - SFDR worst spur: 94dBFS
- INL: ±2 LSB (typical)
- DNL: ±0.5 LSB (typical)
- Digital down-converters (DDCs)
 - Up to four independent DDCs
 - Complex and real decimation
 - Decimation: /2, /4 to /32768 decimation
 - 48-bit NCO phase coherent frequency hopping
- Parallel/ Serial LVDS interface
 - 16-bit Parallel SDR, DDR LVDS for DDC bypass
 - Serial LVDS for decimation
 - 32-bit output option for high decimation

2 Applications

- Software defined radio
- Spectrum analyzer
- Radar
- Spectroscopy
- Power amplifier linearization
- Communications infrastructure

3 Description

The ADC3568 and ADC3569 (ADC356x) are 16-bit, 250MSPS and 500MSPS, single channel analog to digital converters (ADC). The devices are designed for high signal-to-noise ratio (SNR) and deliver a noise spectral density of -160dBFS/Hz (500MSPS).

The power efficient ADC architecture consumes 435mW at 500MSPS and provides power scaling with lower sampling rates (369mW at 250MSPS).

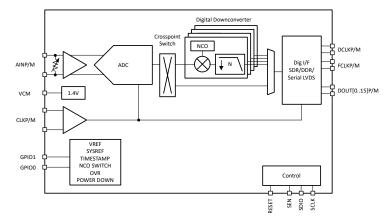
The ADC356x includes an optional quad band digital down-converter (DDC) supporting wide band decimation by 2 to narrow band decimation by 32768. The DDC uses a 48-bit NCO which supports phase coherent and phase continuous frequency hopping.

The ADC356x is outfitted with a flexible LVDS interface. In decimation bypass mode, the device uses a parallel SDR or DDR LVDS interface. When using decimation, the output data is transmitted using a serial LVDS interface reducing the number of lanes needed as decimation increases. For high decimation ratios, the output resolution can be increased to 32bit.

Device Information

PART NUMBER	PACKAGE(!)	MAXIMUM SAMPLING RATE
ADC3569	64 QFN	500MSPS
ADC3568	64 QFN	250MSPS

For more information, see Section 12.



Block Diagram



Table of Contents

1 Features1	8.1 Overview	24
2 Applications1	8.2 Functional Block Diagram	24
3 Description1	8.3 Feature Description	2
4 Device Comparison2	8.4 Device Functional Modes	48
5 Pin Configuration and Functions3	8.5 Programming	49
6 Specifications 5	9 Application and Implementation	
6.1 Absolute Maximum Ratings5	9.1 Application Information	6
6.2 ESD Ratings5	9.2 Typical Application	6
6.3 Recommended Operating Conditions5	9.3 Power Supply Recommendations	7
6.4 Thermal Information6	9.4 Layout	72
6.5 Electrical Characteristics - Power Consumption6	10 Device and Documentation Support	7:
6.6 Electrical Characteristics - DC Specifications6	10.1 Documentation Support	73
6.7 Electrical Characteristics - AC Specifications	10.2 Receiving Notification of Documentation Updates	73
(ADC3568 - 250 MSPS)8	10.3 Support Resources	73
6.8 Electrical Characteristics - AC Specifications	10.4 Trademarks	73
(ADC3569 - 500 MSPS)9	10.5 Electrostatic Discharge Caution	73
6.9 Timing Requirements10	10.6 Glossary	73
6.10 Typical Characteristics, ADC356811	11 Revision History	73
6.11 Typical Characteristics, ADC356916	12 Mechanical, Packaging, and Orderable	
7 Parameter Measurement Information22	Information	74
8 Detailed Description24		

4 Device Comparison

Table 4-1. Device Comparison Table

	14400 1 11 2 0 11 0 0 11 14400					
Part Number	Maximum Sampling Rate	Resolution	No. of Channels			
ADC3669	500MSPS	16 bit	2			
ADC3668	250MSPS	16 bit	2			
ADC3569	500MSPS	16 bit	1			
ADC3568	250MSPS	16 bit	1			
ADC3649	500MSPS	14 bit	2			
ADC3648	250MSPS	14 bit	2			
ADC3549	500MSPS	14 bit	1			
ADC3548	250MSPS	14 bit	1			



5 Pin Configuration and Functions

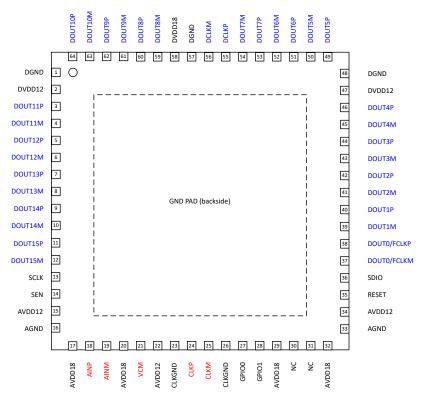


Figure 5-1. RTD Package, 64 Pin VQFNP (Top View)

Table 5-1. Pin Functions

PIN		TYPE(1)	DESCRIPTION
NAME	NO.	ITPE	DESCRIPTION
AGND	16, 33	I	Analog ground, 0V
AINM	19	I	Channel A differential signal input, negative connection. The differential input has programmable internal termination $(100\Omega \text{ or } 200\Omega)$ and is self biased.
AINP	18	I	Channel A differential signal input, positive connection.
AVDD12	15, 22, 34	1	Analog 1.2V supply
AVDD18	17, 20, 29, 32	I	Analog 1.8V supply
CLKGND	23, 26	I	Clock ground, 0V
CLKP	24	I	Device sampling clock differential input. AC coupling and terminating the clock signal externally for best AC
CLKM	25	I	performance is recommended. The differential input is self biased to the input common-mode voltage (0.75V).
DCLKP	55	0	Differential LVDC data hit alack output
DCLKM	56	0	- Differential LVDS data bit clock output.
DGND	1, 48, 57	I	Digital ground, 0V
DOUT0/FCLKM	37	0	Differential LVDS data bit output lane 0. In decimation mode this pin turns to the differential SLVDS frame clock
DOUT0/FCLKP	38	0	output, replacing the LSB.
DOUT1M	39	0	Differential LV/DC data bit autout land 4. One had before and accounted days are CDI if and used
DOUT1P	40	0	Differential LVDS data bit output lane 1. Can be left floating and powered down via SPI if not used.
DOUT2M	41	0	Differential LVDC data hit autaut lane 2. Can be left floating and naugrad days via CDI if t d
DOUT2P	42	0	Differential LVDS data bit output lane 2. Can be left floating and powered down via SPI if not used.
DOUT3M	43	0	Differential LVDC data hit autaut lane 2. Can be left floating and naugard days via CDI if not used
DOUT3P	44	0	Differential LVDS data bit output lane 3. Can be left floating and powered down via SPI if not used.



Table 5-1. Pin Functions (continued)

PIN			Table 5-1. Fill Fullctions (continued)
NAME	NO.	TYPE ⁽¹⁾	DESCRIPTION
DOUT4M	45	0	
DOUT4P	46	0	Differential LVDS data bit output lane 4. Can be left floating and powered down via SPI if not used.
DOUT5P	49	0	
DOUT5M	50	0	Differential LVDS data bit output lane 5. Can be left floating and powered down via SPI if not used.
DOUT6P	51	0	
DOUT6M	52	0	Differential LVDS data bit output lane 6. Can be left floating and powered down via SPI if not used.
DOUT7P	53	0	DIT (111/PO 14.17 + 11 7.0 1 1 1/1 1/1 1 1 1 1 1 1 1 1 1 1 1 1 1
DOUT7M	54	0	Differential LVDS data bit output lane 7. Can be left floating and powered down via SPI if not used.
DOUT8M	59	0	D.W. 1. H.V.D.O. 14 1.1. 14 1.0. 0.0. 14 1.1. 1.1. 1.1.
DOUT8P	60	0	Differential LVDS data bit output lane 8. Can be left floating and powered down via SPI if not used.
DOUT9M	61	0	Differential LVDO data bit autout lane O. Comba laft florition and account design of CDI if a tour
DOUT9P	62	0	Differential LVDS data bit output lane 9. Can be left floating and powered down via SPI if not used.
DOUT10M	63	0	Differential IV/DO data bit autout lane 40. Comba laft florida and a susceed down in CDI if autous
DOUT10P	64	0	Differential LVDS data bit output lane 10. Can be left floating and powered down via SPI if not used.
DOUT11P	3	0	Differential IV/DC data hit output lane 44. Can be left fleating and neuronal days via CDI if not used
DOUT11M	4	0	Differential LVDS data bit output lane 11. Can be left floating and powered down via SPI if not used.
DOUT12P	5	0	Differential LVDS data bit output lane 12. Can be left floating and powered down via SPI if not used.
DOUT12M	6	0	Differential LVDS data bit output lane 12. Can be left floating and powered down via SF1 if flot used.
DOUT13P	7	0	Differential LVDS data bit output lane 13. Can be left floating and powered down via SPI if not used.
DOUT13M	8	0	Differential EVDS data bit output lane 13. Can be left floating and powered down via 3F1 if flot used.
DOUT14P	9	0	Differential LVDS data bit output lane 14. Can be left floating and powered down via SPI if not used.
DOUT14M	10	0	Differential LVD3 data bit output fame 14. Can be left floating and powered down via 3F1 if flot used.
DOUT15P	11	0	Differential LVDS data bit output lane 15. Can be left floating and powered down via SPI if not used.
DOUT15M	12	0	Differential LVDO data bit output faire 15. Gail be left floating and powered down via of 11 flot used.
DVDD12	2, 47	I	Digital 1.2V supply
DVDD18	58	I	Digital 1.8V supply
GPIO0	27	I/O	Synchronization or control input or status output. Can be left floating if not used.
GPIO1	28	I/O	Control input or status output or external voltage reference (1.2V). Can be left floating if not used.
NC	30,31	-	Do not connect
RESET	35	I	Hardware reset. Active high. This pin has an internal 21kΩ pull-down resistor to DGND.
SCLK	13	I	Serial interface clock for the serial interface programming. This pin has an internal $21k\Omega$ pull-up resistor to DVDD18.
SDIO	36	I/O	Serial interface data input/output. This pin has an internal 21kΩ pull-up resistor to DVDD18.
SEN	14	I	Serial interface chip select. This pin has an internal 21kΩ pull-up resistor to DVDD18.
VCM	21	0	Common mode voltage output (1.4V)

⁽¹⁾ I = Input, O = Output, I/O = Input or Output, G = Ground, P = Power.

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1)

PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
Supply voltage range, AVDD18		-0.3	2.1	V
Supply voltage range, AVDD12		-0.3	1.4	V
Supply voltage range, DVDD18		-0.3	2.1	V
Supply voltage range, DVDD12		-0.3	1.4	V
	AINP/M	-0.3	2.1	V
Voltage applied to input pins	CLKP/M	-0.3	1.4	V
	GPIO0/1, RESET, SCLK, SEN, SDIO	-0.3	DVDD18 + 0.2	V
Peak RF input power (AINP/M)	Differential 100 Ω termination		10	dBm
Junction temperature, T _J			125	°C
Storage temperature, T _{stg}		-65	150	C

⁽¹⁾ Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

			VALUE	UNIT
V	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	1500	V
V(ESD)	Liectiostatic discriarge	Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002 ⁽²⁾	750	V

⁽¹⁾ JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
AVDD18	1.8 V analog supply	1.75	1.8	1.85	
AVDD12	1.2 V analog supply	1.15	1.2	1.225	V
DVDD18	1.8 V digital supply	1.75	1.8	1.85	V
DVDD12	1.2 V digital supply	1.15	1.2	1.225	
T _A	Operating free-air temperature	-40		105	°C
T_J	Operating junction temperature			115 ⁽¹⁾	

(1) Prolonged use above this junction temperature may increase the device failure-in-time (FIT) rate.

⁽²⁾ JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



6.4 Thermal Information

		ADC3568/69	
	THERMAL METRIC(1)	RTD (QFN)	UNIT
		64 Pins	
$R_{\Theta JA}$	Junction-to-ambient thermal resistance	22.3	°C/W
$R_{\Theta JC(top)}$	Junction-to-case (top) thermal resistance	11.4	°C/W
$R_{\Theta JB}$	Junction-to-board thermal resistance	7.4	°C/W
Ψ_{JT}	Junction-to-top characterization parameter	0.1	°C/W
Ψ_{JB}	Junction-to-board characterization parameter	7.3	°C/W
R _{ΘJC(bot)}	Junction-to-case (bottom) thermal resistance	1.1	°C/W

⁽¹⁾ For more information about thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

6.5 Electrical Characteristics - Power Consumption

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at T_A = 25°C, ADC sampling rate = 500 MSPS, DDC Bypass mode, 50% clock duty cycle, nominal supply voltages and -1-dBFS differential input, unless otherwise noted

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
ADC3568	250 MSPS					
I _{AVDD18}	Supply current, 1.8 V analog supply			60	85	
I _{AVDD12}	Supply current, 1.2 V analog supply			45	90	А
I _{DVDD18}	Supply current, 1.8 V digital supply	DDR LVDS		75	105	mA
I _{DVDD12}	Supply current, 1.2 V digital supply			60	126	
P _{DIS}	Power dissipation			369		mW
ADC3569	500 MSPS				'	
I _{AVDD18}	Supply current, 1.8 V analog supply			66	85	
I _{AVDD12}	Supply current, 1.2 V analog supply			65	115	А
I _{DVDD18}	Supply current, 1.8 V digital supply	DDR LVDS		76	105	mA
I _{DVDD12}	Supply current, 1.2 V digital supply			85	155	
P _{DIS}	Power dissipation			435		mW
POWER D	OWN MODE				'	
P _{DIS}	Power down mode power consumption	Global power down		31		mW
	1					

6.6 Electrical Characteristics - DC Specifications

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at T_A = 25°C, ADC sampling rate = 500 MSPS, DDC Bypass mode, 50% clock duty cycle, nominal supply voltages and -1-dBFS differential input, internal reference, unless otherwise noted

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DC ACCUR	ACY				'	
No missing of	codes		16			bits
ADC3568: 2	50 MSPS					
DNL	Differential nonlinearity	F _{IN} = 70 MHz	-0.9	± 0.5		LSB
INL	Integral nonlinearity	F _{IN} = 70 MHz		± 2		LSB
V _{OS_ERR}	Offset error			10		LSB
V _{OS_DRIFT}	Offset drift over temprature			10		LSB
	Gain error	External Reference		± 1		0/ ESD
GAIN _{ERR}	Gain end	Internal Reference		± 3		%FSR

Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated



6.6 Electrical Characteristics - DC Specifications (continued)

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at T_A = 25°C, ADC sampling rate = 500 MSPS, DDC Bypass mode, 50% clock duty cycle, nominal supply voltages and -1-dBFS differential input, internal reference, unless otherwise noted

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
CAIN	Gain drift over temperature	External Reference		± 0.5		%FSR
GAIN _{DRIFT}	Gain drift over temperature	Internal Reference		± 1		70F3K
ADC3569: 5	000 MSPS					
DNL	Differential nonlinearity	F _{IN} = 70 MHz	-0.9	± 0.5		LSB
INL	Integral nonlinearity	F _{IN} = 70 MHz		± 2		LSB
V _{OS_ERR}	Offset error			10		LSB
V _{OS_DRIFT}	Offset drift over temprature			10		LSB
CAIN	Gain error	External Reference		± 1		%FSR
GAIN _{ERR}	Gain error	Internal Reference		± 3		%F3K
CAIN	Cain drift over temperature	External Reference		± 0.5		%FSR
GAIN _{DRIFT}	Gain drift over temperature	Internal Reference		± 1		70F3R
ADC ANAL	OG INPUTS (AINP/M)		•			
FS	Input full scale	Differential		2.0		Vpp
V _{ICM}	Input common model voltage		1.3	1.4	1.5	V
Z _{IN}	Differential input impedance	Differential at 100 MHz		100		Ω
V _{CM}	Output common mode voltage			1.4		V
BW	Analog Input Bandwidth (-3dB)			1.4		GHz
CLOCK INP	PUT (CLKP/M)				·	
Input clock frequency		ADC3569	100		500	MHz
		ADC3568	100		250	MHz
V _{ID}	Differential input voltage		0.5	2	2.4	Vpp
V _{ICM}	Input common mode voltage			0.75		V
Z _{IN}	Differential input impedance	Differential at 500 MHz		5		kΩ
Clock duty of	ycle		35	50	65	%
EXTERNAL	REFERENCE INPUT (GPIO1)		•		·	
VREF	External voltage reference		1.175	1.2	1.225	V
I _{VREF}	Input current, external voltage refer	ence input		10		uA
DIGITAL IN	PUTS (GPIO0, GPIO1, RESET, SCLK	, SEN, SDIO)			·	
V _{IH}	High level input voltage		1.4	1.8		V
V _{IL}	Low level input voltage			0	0.4	V
I _{IH}	High level input current			90	150	uA
I _{IL}	Low level input current		-150	-90		uA
Cı	Input capacitance			1.5		pF
DIGITAL OU	JTPUTS (GPIO0, GPIO1, SDIO)					
V _{OH}	High level output voltage	I _{LOAD} = -400 uA	AVDD18 - 0.1	AVDD18		V
V _{OL}	Low level output voltage	I _{LOAD} = 400 uA			0.1	V
LVDS/SLVD	S INTERFACE (DOUT[015]P/M, DC	LKP/M)	•		1	
Output data	format (default)		2s c	omplemer	nt	
V _{OD}	Differential output voltage	differential peak-peak	500	700	850	mVpp



6.7 Electrical Characteristics - AC Specifications (ADC3568 - 250 MSPS)

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at T_A = 25°C, ADC sampling rate = 250 MSPS, DDC Bypass mode, 50% clock duty cycle, nominal supply voltages and -1-dBFS differential input, internal reference, unless otherwise noted

	PARAMETER	TEST CONDITIONS	MIN ⁽¹⁾ TYP	MAX	UNIT	
AC ACCURA	ACY					
NSD	Noise Spectral Density	f _{IN} = 100 MHz, A _{IN} = -20 dBFS	-157.4		dBFS/Hz	
NF	Noise Figure	f _{IN} = 100 MHz, A _{IN} = -20 dBFS	23.6		dB	
		f _{IN} = 10 MHz	75.5			
		f _{IN} = 70 MHz	70 75.2			
SNR	Signal to noise ratio	f _{IN} = 170 MHz	74.6		dBFS	
		f _{IN} = 300 MHz	72.9			
		f _{IN} = 450 MHz	71.4			
		f _{IN} = 10 MHz	73.6			
		f _{IN} = 70 MHz	74.1			
SINAD	Signal to noise and distortion ratio	f _{IN} = 170 MHz	72.2		dBFS	
		f _{IN} = 300 MHz	68.5			
		f _{IN} = 450 MHz	64.7			
		f _{IN} = 10 MHz	11.9			
		f _{IN} = 70 MHz	12.0			
ENOB	Effective number of bits	f _{IN} = 170 MHz	11.7		Bits	
		f _{IN} = 300 MHz	11.1			
		f _{IN} = 450 MHz	10.4			
	Total Harmonic Distortion (First five harmonics)	f _{IN} = 10 MHz	77			
		f _{IN} = 70 MHz	80			
THD		f _{IN} = 170 MHz	75		dBc	
		f _{IN} = 300 MHz	71			
		f _{IN} = 450 MHz	65			
		f _{IN} = 10 MHz	79			
	Second Harmonic Distortion	f _{IN} = 70 MHz	69 85		ĺ	
HD2		f _{IN} = 170 MHz	78		dBc	
		f _{IN} = 300 MHz	76			
		f _{IN} = 450 MHz	68			
		f _{IN} = 10 MHz	83			
		f _{IN} = 70 MHz	71 81			
HD3	Third Harmonic Distortion	f _{IN} = 170 MHz	81		dBc	
		f _{IN} = 300 MHz	79			
		f _{IN} = 450 MHz	74			
		f _{IN} = 10 MHz	96			
	Spur free dynamic range (excluding HD2 and HD3)	f _{IN} = 70 MHz	96			
Non HD2,3		f _{IN} = 170 MHz	95		dBFS	
		f _{IN} = 300 MHz	88			
		f _{IN} = 450 MHz	81			
IMD3	Two tone inter-modulation distortion	$f_1 = 100 \text{ MHz}, f_2 = 120 \text{ MHz}, A_{IN} = -7 \text{ dBFS/tone}$	83		dBc	
	1	1	l			

⁽¹⁾ SNR and HD3 minimum values are specified by ATE; HD2 is specified by bench characterization.



6.8 Electrical Characteristics - AC Specifications (ADC3569 - 500 MSPS)

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at T_A = 25°C, ADC sampling rate = 500 MSPS, DDC Bypass mode, 50% clock duty cycle, nominal supply voltages and -1-dBFS differential input, internal reference, unless otherwise noted

	PARAMETER	TEST CONDITIONS	MIN ⁽¹⁾	TYP	MAX	UNIT	
AC ACCURA	ACY						
NSD	Noise Spectral Density	f _{IN} = 100 MHz, A _{IN} = -20 dBFS		-160.4		dBFS/Hz	
NF	Noise Figure	f _{IN} = 100 MHz, A _{IN} = -20 dBFS		20.6		dB	
		f _{IN} = 10 MHz		75.8			
		f _{IN} = 70 MHz	70	75.6			
SNR	Signal to noise ratio	f _{IN} = 170 MHz		74.9		dBFS	
		f _{IN} = 300 MHz		72.6			
		f _{IN} = 450 MHz		71.5			
		f _{IN} = 10 MHz		72.6			
		f _{IN} = 70 MHz		73.7			
SINAD	Signal to noise and distortion ratio	f _{IN} = 170 MHz		72.4		dBFS	
		f _{IN} = 300 MHz		68.2			
		f _{IN} = 450 MHz		64.4			
		f _{IN} = 10 MHz		11.8			
		f _{IN} = 70 MHz		11.9			
ENOB	Effective number of bits	f _{IN} = 170 MHz		11.7		Bits	
		f _{IN} = 300 MHz		11.0			
		f _{IN} = 450 MHz		10.4			
		f _{IN} = 10 MHz		74			
		f _{IN} = 70 MHz		77			
THD	Total Harmonic Distortion (First five	f _{IN} = 170 MHz		74		dBc	
	harmonics)	f _{IN} = 300 MHz		68			
		f _{IN} = 450 MHz		63			
		f _{IN} = 10 MHz		76			
		f _{IN} = 70 MHz	69	82			
HD2	Second Harmonic Distortion	f _{IN} = 170 MHz		77		dBc	
		f _{IN} = 300 MHz		81			
		f _{IN} = 450 MHz		76			
		f _{IN} = 10 MHz		88			
	Third Harmonic Distortion	f _{IN} = 70 MHz	71	80			
HD3		f _{IN} = 170 MHz		83		dBc	
		f _{IN} = 300 MHz		71			
		f _{IN} = 450 MHz		65			
		f _{IN} = 10 MHz		94			
		f _{IN} = 70 MHz		94			
Non HD2,3	Spur free dynamic range (excluding	f _{IN} = 170 MHz		90		dBFS	
-	HD2 and HD3)	f _{IN} = 300 MHz		86			
		f _{IN} = 450 MHz		87			
IMD3	Two tone inter-modulation distortion	f ₁ = 100 MHz, f ₂ = 120 MHz, A _{IN} = -7 dBFS/tone		86		dBc	

⁽¹⁾ SNR and HD3 minimum values are specified by ATE; HD2 is specified by bench characterization.



6.9 Timing Requirements

Maximum and minimum values are specified over the operating free-air temperature range and nominal supply voltages. Typical values are specified at T_A = 25°C, ADC sampling rate = 500 MSPS, DDC Bypass mode, 50% clock duty cycle, nominal supply voltages and -1-dBFS differential input, unless otherwise noted

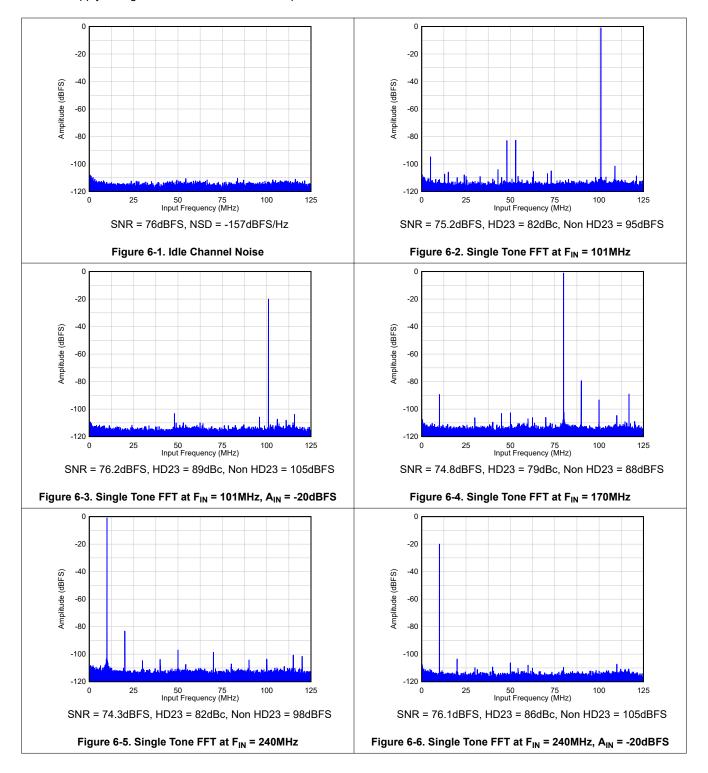
	PARAMETER	TEST CONDITIONS	MIN	NOM	MAX	UNIT	
ADC TIMI	NG SPECIFICATIONS						
T _{AD}	Aperture Delay			200		ps	
T _A	Aperture Jitter			75		fs	
		F _S = 500 MSPS, Error > 64 codes		1E-10			
CER	Code error rate	F _S = 500 MSPS, Error > 128 codes		3E-13		errors/ sample	
		F _S = 250 MSPS, Error > 64 codes		1E-11		Sample	
Wake up t	ime	time to valid data after coming out of global power down mode (internal voltage reference OFF)		3		ms	
LATENCY	: t _{PD} + t _{ADC} + t _{DIG}						
t _{PD}	Propagation delay: sampling clock falling edge to DCLK rising edge	Propagation delay: sampling clock falling edge to DCLK rising edge	1.4 + T _S /4	1.7 + T _S /4	2 + T _S /4	ns	
	ADOLES	SDR/DDR LVDS, normal mode		38		ADC	
t _{ADC}	ADC latency	DDR LVDS, low latency mode		4		clock	
	Time stamp: input to LVDS output	SDR/DDR LVDS		8	cycles		
		DDC bypass		5		Output clock cycles	
	Digital latency: interface and decimation	Decimation by 2 (real or complex)		24			
t _{DIG}		Decimation by 4,8 (real or complex)		49			
			50		-,		
SERIAL P	ROGRAMMING INTERFACE (SCLK, SEN, SD	NO) - Input					
f _{CLK(SCLK)}	Serial clock frequency		1		20	MHz	
t _{SLOADS}	Setup time from SEN falling edge to SCLK rising edge					ns	
t _{SLOADH}	Hold time from SCLK rising edge to SEN rising edge		10			ns	
t _{DSU}	Setup time from SDIO to rising edge of SCLK	10			ns		
t _{DH}	Hold time from rising edge of SCLK to SDIO					ns	
SERIAL P	ROGRAMMING INTERFACE (SDIO) - Output						
t _(OZD)	SDIO tri-state to driven				10	ns	
t _(ODZ)	SDIO data to tri-state				14	ns	
t _(OD)	SDIO valid from falling edge of SCLK		-		10	ns	
TIMING: S	SYSREF						
t _{s(SYSREF)}	Setup time: SYSREF valid to rising edge of Cl	LKP/M	100			ps	
t _{h(SYSREF)}	Hold time: Rising edge of CLKP/M to SYSREF	- invalid	100			ps	
INTERFA	CE TIMING: SDR LVDS						
t _{DV}	Time Data Valid: data transition to DCLK rising edge	$F_S = 500 \text{ MSPS}$ $F_S = 250 \text{ MSPS}$	0.465 0.905		0.905 1.415	ns ns	
		F _S = 500 MSPS	1.095		1.415		
t _{DI}	Time Data Invalid : DCLK rising edge to data transition					ns	
INTEREA	CE TIMING: DDR AND SLVDS	F _S = 250 MSPS	2.615	2.04	3.015	ns	
IIN I EKFA		E 500 MSDS	0.465	0.60	0.905	no	
t _{DV}	Time Data Valid: data transition to DCLK transition	$F_S = 500 \text{ MSPS}$ $F_S = 250 \text{ MSPS}$				ns	
			0.905		1.415	ns	
t _{DI}	Time Data Invalid : DCLK transition to data transition	F _S = 500 MSPS	0.095		0.535	ns	
tı	u di lota OTI	F _S = 250 MSPS	0.615	0.84	1.065	ns	

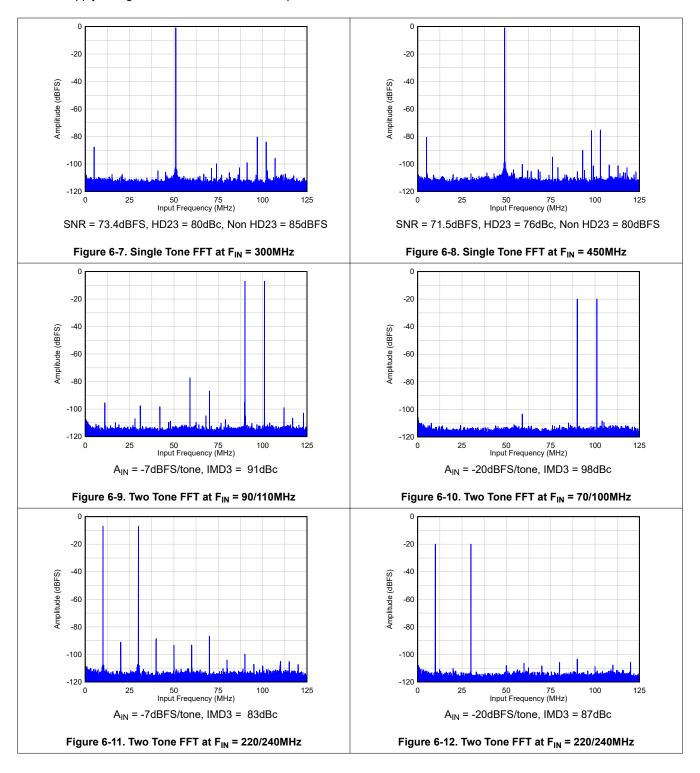
Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated

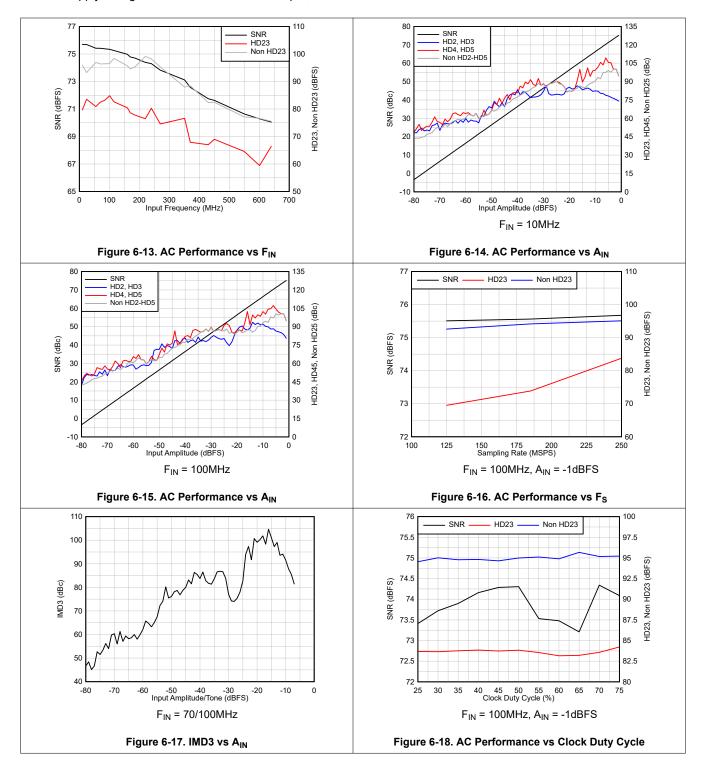


6.10 Typical Characteristics, ADC3568

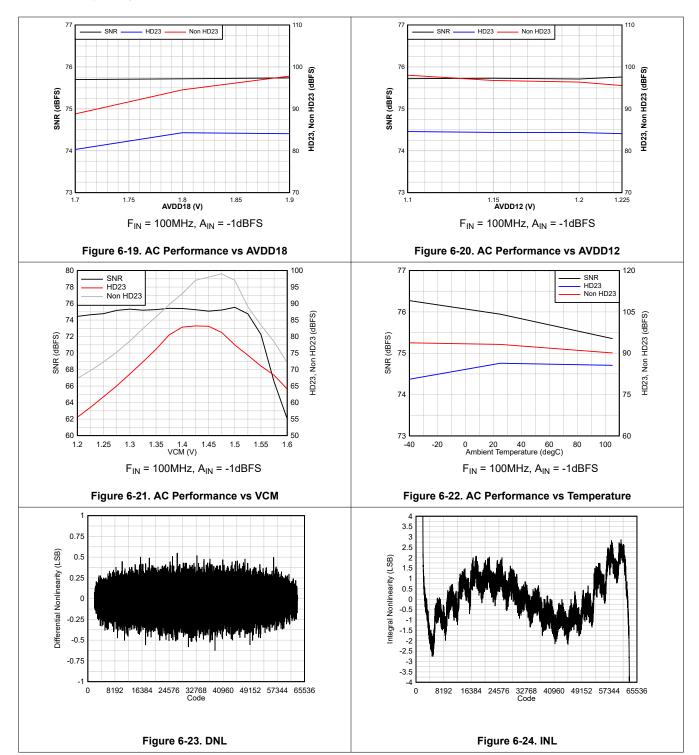




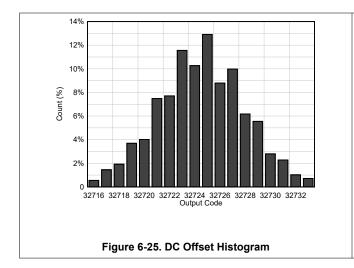


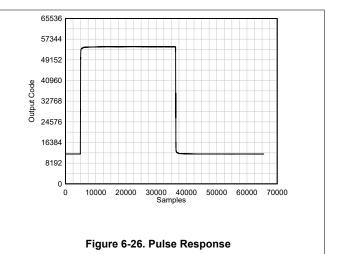






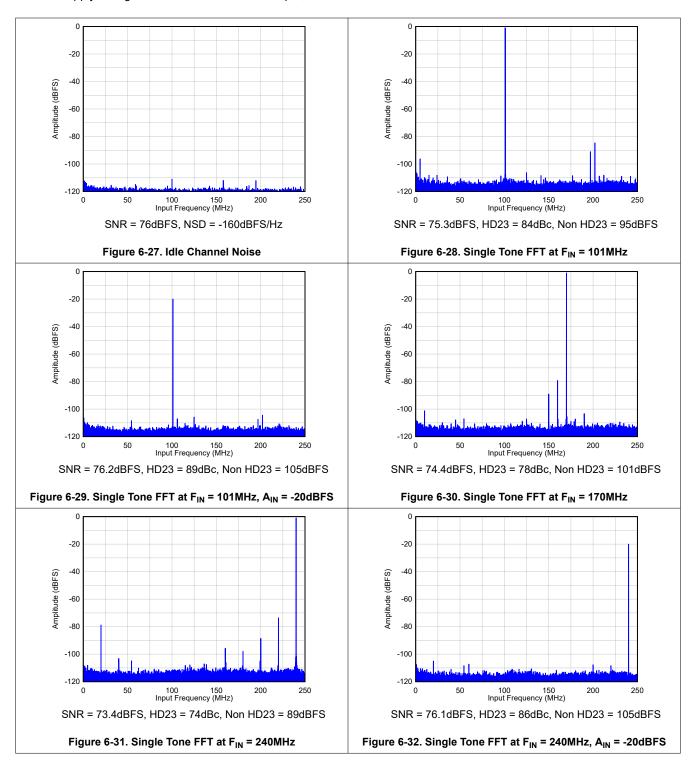


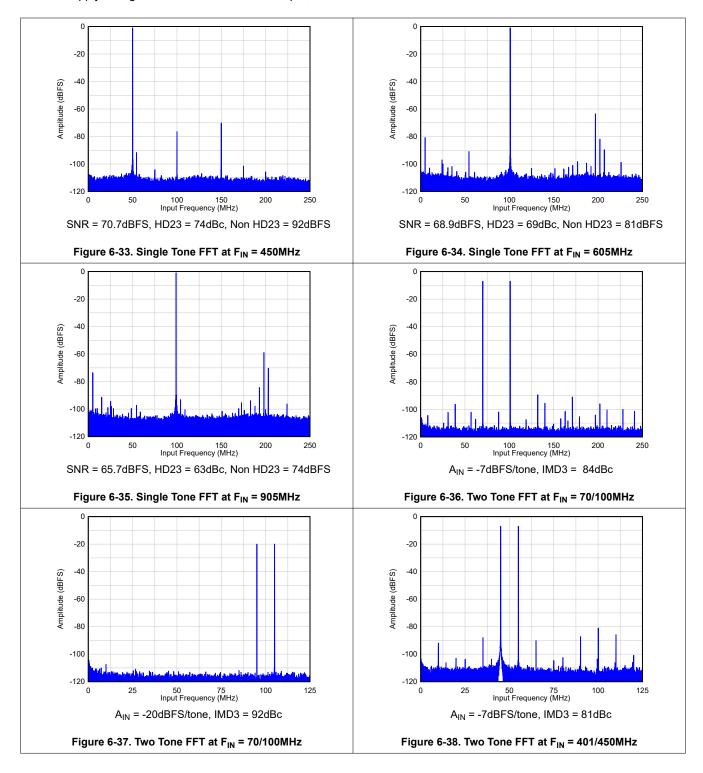




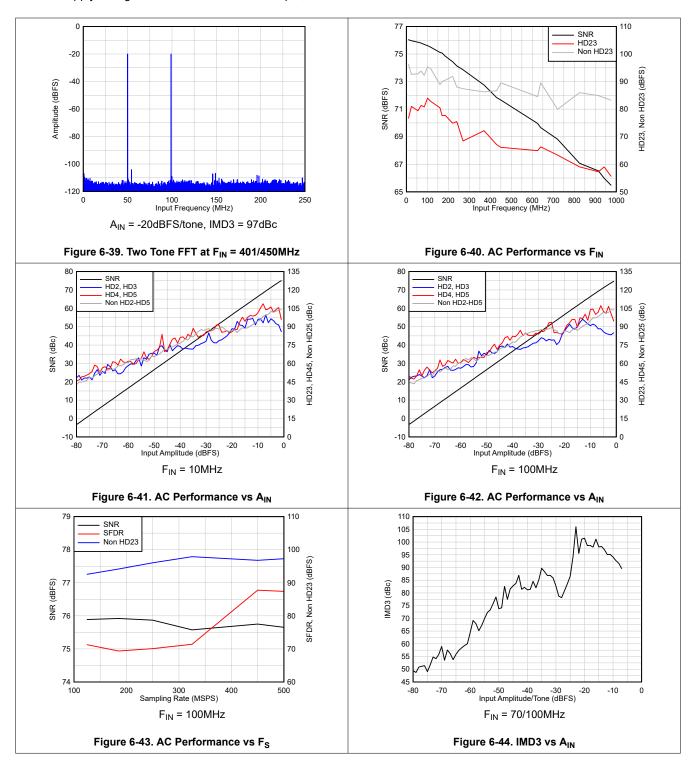


6.11 Typical Characteristics, ADC3569

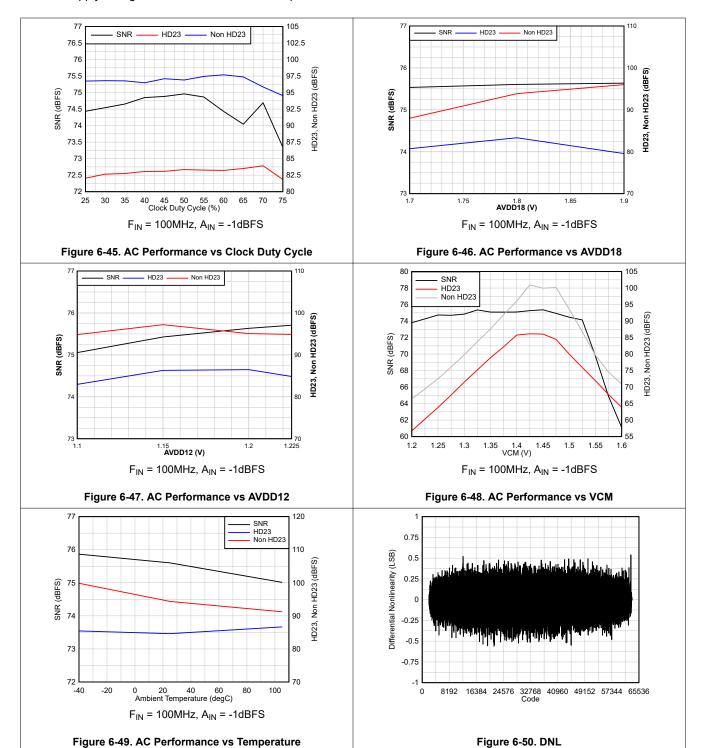




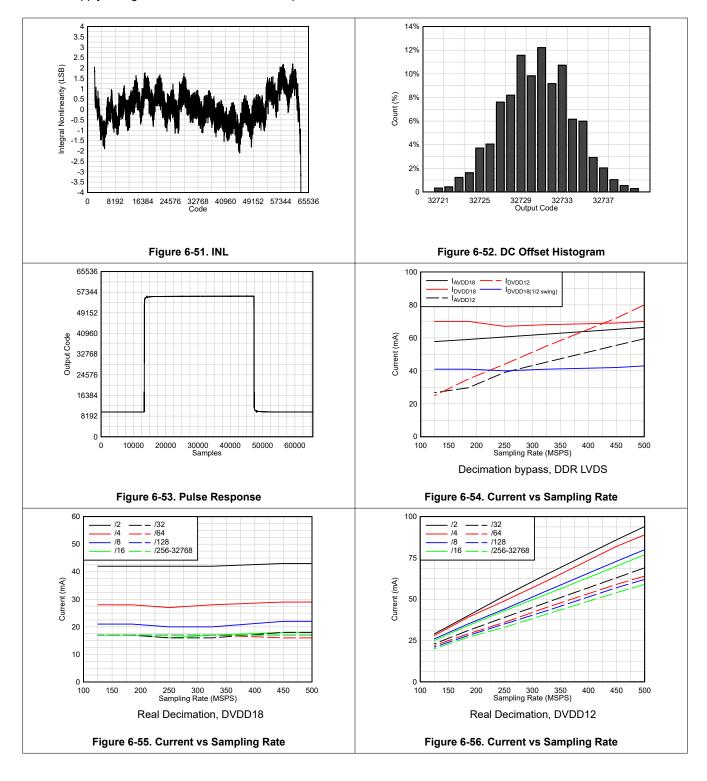




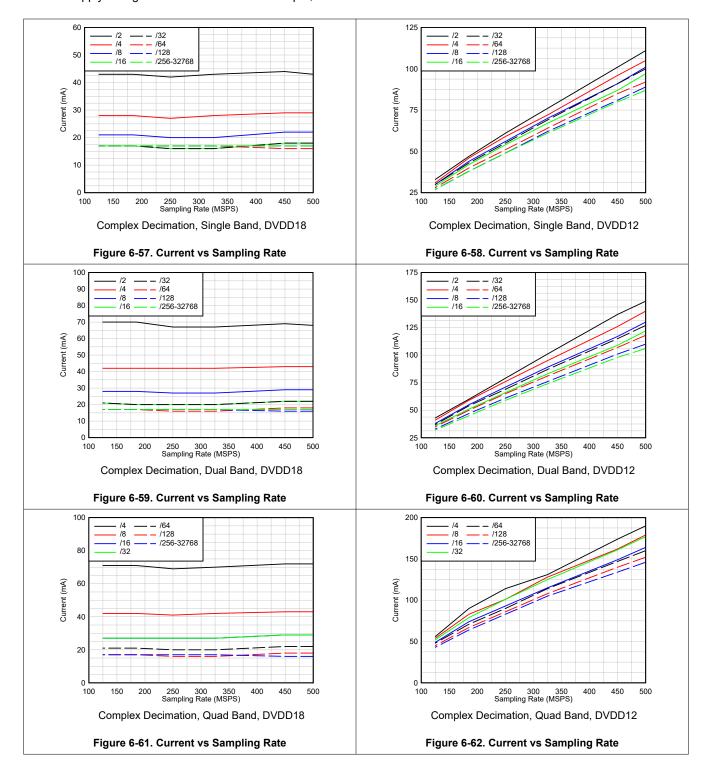














7 Parameter Measurement Information

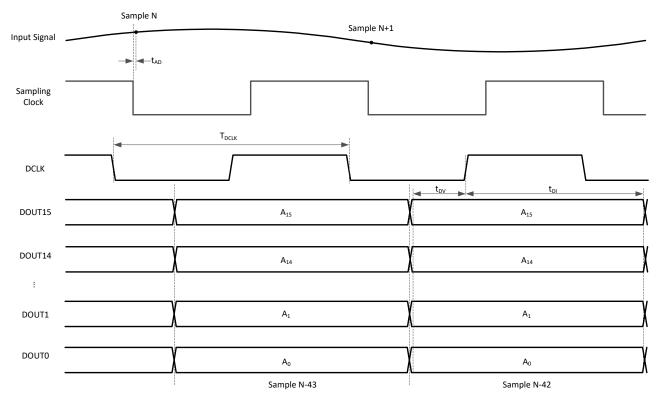


Figure 7-1. Timing Diagram - Parallel SDR LVDS (default)

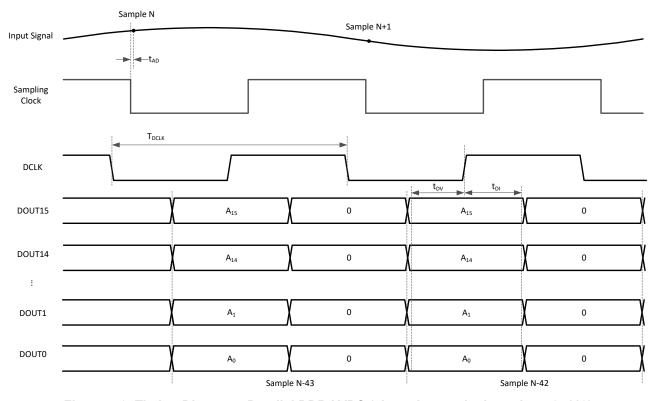


Figure 7-2. Timing Diagram - Parallel DDR LVDS (via register write in register 0x110)

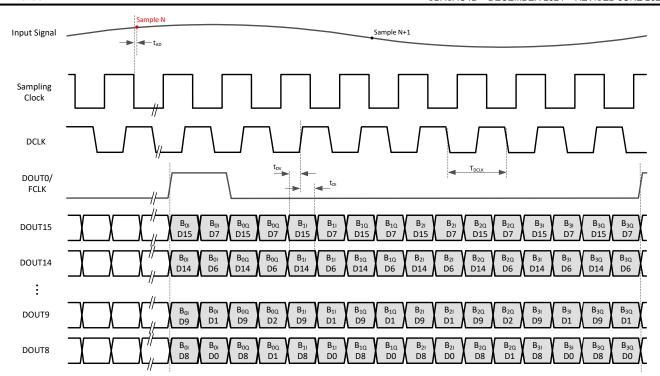


Figure 7-3. Timing Diagram - Serial LVDS (example: quad band, 16-bit, complex decimation by 8)



8 Detailed Description

8.1 Overview

The ADC356x is a 16-bit, 250MSPS and 500MSPS, single channel analog to digital converter (ADC). The device is designed for highest signal-to-noise ratio (SNR) and delivers a noise spectral density as low as -160dBFS/Hz. The buffered analog inputs support a programmable internal termination impedance of 100Ω and 200Ω with a full power input bandwidth of 1.4GHz (-3dB).

The ADC356x includes a quad band digital down-converter (DDC) supporting wideband decimation by 2 to narrow band decimation by 32768. The DDC uses a 48-bit NCO which supports phase coherent and phase continuous frequency hopping.

The ADC356x is outfitted with a flexible LVDS interface. In decimation bypass mode, the output data is transmitted 16 LVDS pairs with a SDR or DDR clock. When using real or complex decimation, the output data is transmitted using a serial LVDS interface. Reducing the number of lanes used as decimation increases.

The power efficient ADC architecture consumes 435mW at 500MSPS and provides power scaling with lower sampling rates (369mW at 250MSPS).

8.2 Functional Block Diagram

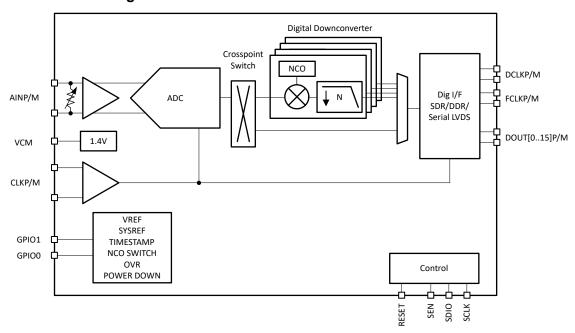


Figure 8-1. Block Diagram

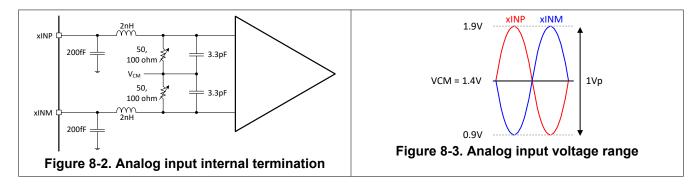


8.3 Feature Description

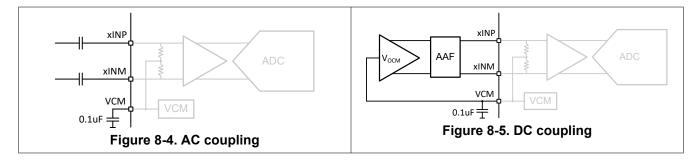
8.3.1 Analog Input

The analog inputs of the ADC366x have internal buffers which isolate the sampling capacitor glitch noise from the external input circuitry. The analog inputs have a differential 100Ω split termination with internal biasing to V_{CM} as illustrated in the representative input model in Figure 8-2. This can be changed to differential 200Ω termination via SPI register write.

The input fullscale is 2Vpp and the VCM is 1.4V; thus, the voltage on the analog inputs swing between 0.9 and 1.9V. The ADC inputs are reliably designed to support 1.9V for normal operation.



The device supports both AC and DC coupling of the analog inputs as shown in Figure 8-4 and Figure 8-5.



The input bandwidth (-3 dB) for internal 100Ω and 200Ω termination are shown in Figure 8-6.

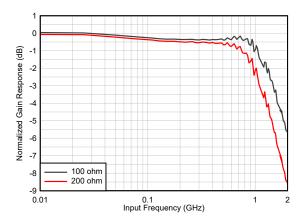


Figure 8-6. Full power input bandwidth for 100Ω and 200Ω internal termination

8.3.1.1 Nyquist Zone Selection

The ADC includes a digital error correction which is optimized based on which Nyquist zone the signal of interest is in. For optimum performance the correct input frequency range (register 0x132) and Nyquist zone have to be selected in the SPI register map (register 0x16B). By default the first Nyquist zone is selected.

8.3.1.2 Analog Front End Design

To optimize SNR and HD3 performance of the ADC, the recommendation is to add a RCR circuitry directly in front of the analog input. Figure 8-7 shows the recommended RCR circuitry for input frequencies less and greater than 500MHz (example shows AC coupling but same applies to DC coupling), assuming a 50Ω source impedance. If the ADC is driven by an external amplifier, the RCR circuitry may not be needed.

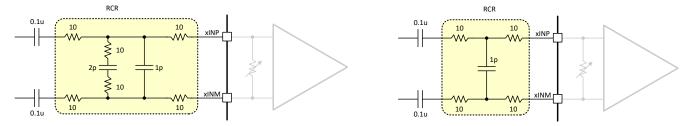


Figure 8-7. External RCR for F_{IN} < 500MHz (left) and F_{IN} > 500MHz (right)

8.3.2 Sampling Clock

The sampling clock input is designed to be driven differentially with external AC coupling and termination. The ADC provides internal common mode voltage biasing as shown in Figure 8-8.

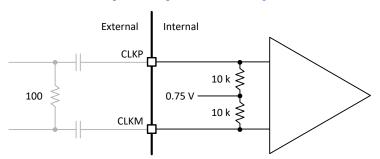


Figure 8-8. Sampling Clock Input Circuitry

The internal sampling clock path was designed for low residual phase noise contribution. The sampling clock circuitry requires a dedicated, low noise power supply for best phase noise and jitter performance. The internal residual clock phase noise is also sensitive to clock amplitude.

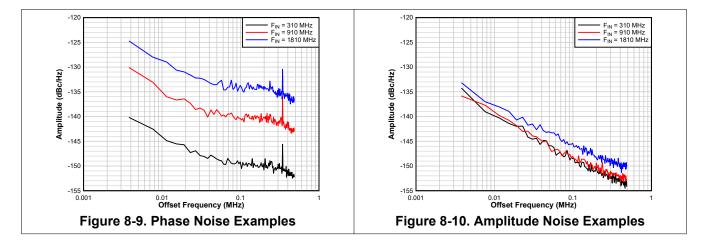
The internal residual clock noise consists of two components: phase noise and amplitude noise as shown in Table 8-1. The phase noise scales with input frequency and sampling rate $(20*log(f_{IN}/F_S))$ while the amplitude noise does not scale.

Frequency Offset (MHz) Phase Noise (dBc/Hz) Amplitude Noise (dBc/Hz) 0.001 -130 -129 0.01 -140 -139 0.1 -150 -149 1 -160 -159 3 -165 -164 10 -165 -164

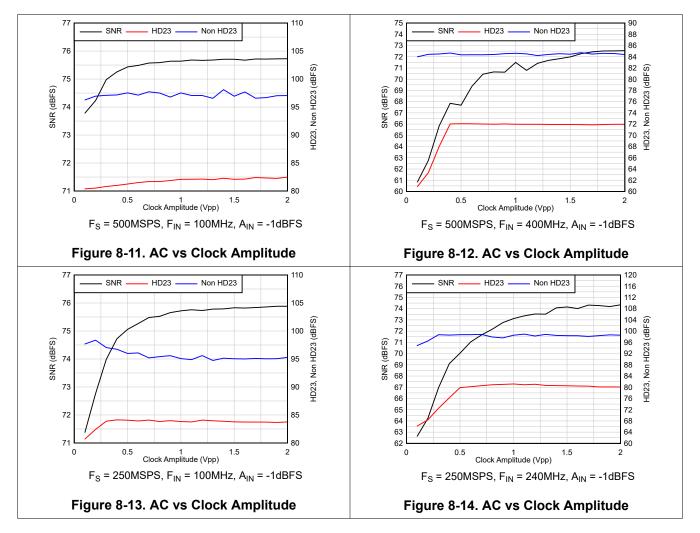
Table 8-1. Phase and Amplitude Noise at $F_S = 500MHz$



Figure 8-9 and Figure 8-10 show the phase and amplitude noise at three different input frequencies.



The internal clock noise is also dependent on the external clock amplitude. Figure 8-11 to Figure 8-14 show the expected AC performance at different input frequencies across clock amplitude.



8.3.3 Multi-Chip Synchronization

The device provides an option to achieve deterministic latency to ease synchronization across multiple devices, depending on operating mode:

- DDC Bypass mode: The device inherently already has deterministic latency. External multi-chip synchronization is accomplished by matching clock traces across devices. However, the internal RAMP test pattern can be reset using the SYSREF signal.
- DDC mode: Internal blocks related to the decimation filter (clock dividers, NCO phase, and so on) are reset to a deterministic state using the SYSREF signal. External multi-chip synchronization is accomplished by matching both clock and SYSREF signal traces (blue lines) across devices as shown in Figure 8-15.

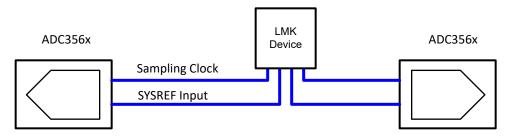


Figure 8-15. Synchronization example of 2 devices

The GPIO0 pin can be configured as a synchronization input. A single pulse can be applied for multi-chip synchronization as shown in Figure 8-16.

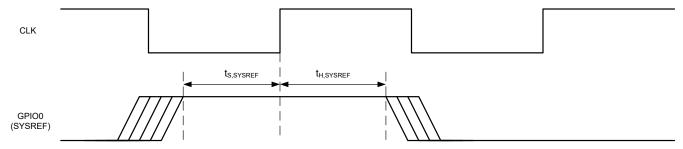


Figure 8-16. Timing: external synchronization input

In the SPI register map there are several different synchronization masks available to reset only specific blocks such as the NCO phase.

Table 8-2. Example register writes for external SYSREF config

ADDR	DATA	DESCRIPTION
0x146	0x00	Configure pin GPIO0 as SYSREF input

8.3.3.1 SYSREF Monitor

The SYSREF input signal rising edge should be edge aligned with the falling edge of the sampling clock to maximize the setup and hold times. The SYSREF signal is internally sampled on the rising edge of the sampling clock plus 60ps.

The ADC356x includes an internal SYSREF monitoring circuitry to detect a possible SYSREF logic level metastability close to the sampling instant of SYSREF which can lead to misalignment across devices. The SYSREF monitoring circuitry provides insights into SYSREF/clock misalignment by detecting whether a SYSREF logic state transition is within -60 to +140ps of the sampling clock rising edge. This circuitry detects and raises one of the SYSREF XOR flags corresponding to the matching SYSREF window below:

- Window XOR1: SYSREF leading sample clock by 20 to 60ps
- Window XOR2: SYSREF leading sample clock by 20ps to 0ps or SYSREF lagging sample clock by 0 to 20ps
- Window XOR3: SYSREF lagging sample clock by up to 20 to 60ps
- Window XOR4: SYSREF lagging sample clock by 60 to 100ps
- Window XOR5: SYSREF lagging sample clock by 100 to 140ps

The SYSREF monitor registers are updated at every rising edge of SYSREF. The <SYSREF DET> register (D6) is sticky (indicating a SYSREF edge was detected) and needs to be cleared manually.

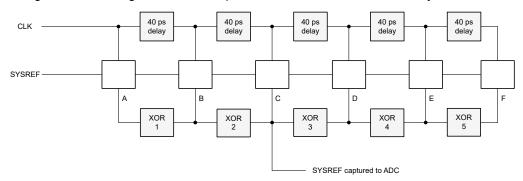


Figure 8-17. SYSREF Detection Circuitry

The example in Figure 8-18 shows a misaligned SYSREF signal where the SYSREF signal arrives much later than the sampling clock falling edge. In this example, the delayed SYSREF signal transitions between the "B" and "C" flip flop which raises the XOR2 flag. The XOR flags get reported in register 0x140. In this example, Register 0x140 reads back 0x62, as shown in Table 8-3.

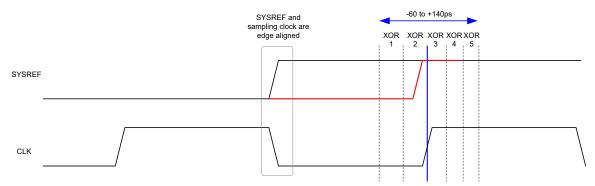


Figure 8-18. Detection of SYSREF Transition Within Capture Window

Table 8-3. SYSREF Window Register Example (0x140)

					- 10: — 21 0 :::: p:	• (•):::-/		
ADDR	D7	D6	D5	D4	D3	D2	D1	D0
0x140	0	SYSREF DET	SYSREF OR	SYSREF X5	SYSREF X4	SYSREF X3	SYSREF X2	SYSREF X1
0.00.140	0	1	1	0	0	0	1	0

8.3.4 Time-Stamp

The ADC356x includes a time-stamp feature which enables tagging a specific sample on the analog input in DDC bypass mode. When enabling the feature (via SPI write), a logic low-to-high transition on the GPIO/SYSREF pin is registered on the rising edge of the sampling clock. The time stamp signal is output on the lane DOUT0 (LSB) however it is not latency matched with the output data. The time-stamp feature is available with SDR and DDR LVDS.

As shown in Figure 8-19 the time stamp signal is indicated 35 clock cycles ahead of the output data:

- Latency output data: 43 clock cycles
- Latency time stamp output: 8 clock cycles

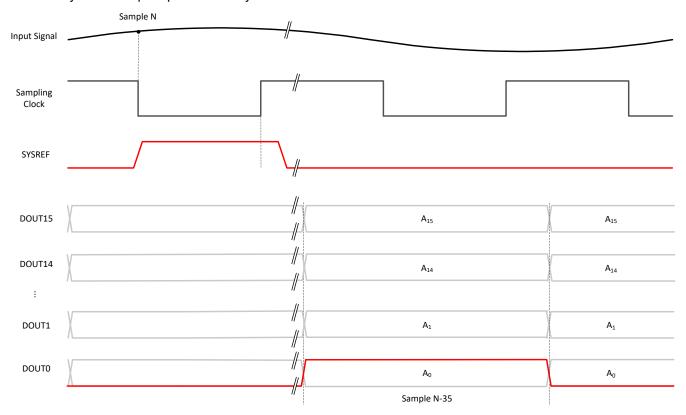


Figure 8-19. Timing Diagram - Time-Stamp Output with SDR LVDS

Table 8-4. Example register writes to enable time stamp on pin GPIO0

ADDR	DATA	DESCRIPTION	
0x146	0x00	Enable SYSREF on pin GPIO0.	
0x162	0xC0	Enable time stamp function replacing the LSB.	

8.3.5 Overrange

The device triggers the overrange indicator when the signal crosses the representable digital range. The overrange output can be configured in registers 0x10A/0x10B. The latency of the OVR indication is equal or less than the data latency.

The OVR can be indicated in two different ways:

- GPIO pin: can be configured using register 0x146
- LSB data: the OVR signal replaces the LSB of the output data (register 0x116). In decimation mode the OVR signal replaces the LSB in every DDC output stream.

Submit Document Feedback



8.3.6 External Voltage Reference

For highest accuracy and lowest temperature drift, an external 1.2V voltage reference can be supplied to the ADC. The external reference can be supplied through pin GPIO1 (configured via SPI). The recommendation is to connect a 10uF and a 0.1uF ceramic bypass capacitor (CVREF) between the GPIO0/1 and AGND pins and placed as close to the pins as possible.

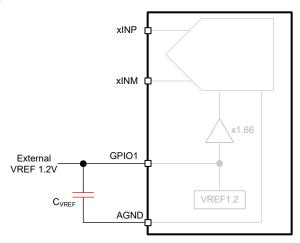


Figure 8-20. External Voltage Reference

8.3.7 Digital Gain

The device includes a programmable digital gain. The gain is programmed in registers 0x15B. The 8-bit register field is 7 bit with a sign bit (2s complement).

The actual gain in dB is: 20 x log (1+ (7 bit gain / 128))

For example a register value of 0x7F corresponds to a digital gain of 6dB, a value of 0xC0 corresponds to a digital gain of -6dB.



8.3.8 Decimation Filter

The ADC3568 and ADC3569 provide up to four digital down converters as shown in Figure 8-21. Using the crosspoint switch with SPI register writes, any of the four DDCs can be connected. In single band mode (1 DDC), decimation from /2 to /32768 is supported. While in 4 DDC mode, the lowest decimation possible is /8 as shown in Table 8-5. Real (single band only) and complex decimation are supported. In real decimation, the passband is approximately 40% and in complex decimation the passband is approximately 80% as illustrated in Table 8-6.

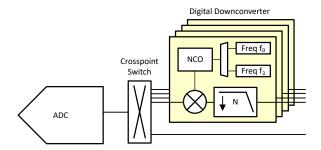


Figure 8-21. Internal digital down converter

Table 8-5. Summary of different decimation filter band options

# of DDCs	Min Decimation	Max Decimation
1	/2	/32768
2	/4	/32768
4	/8	/32768

Table 8-6. Complex decimation and real decimation vs output bandwidth

Decimation Factor (complex)	Complex Output Bandwidth per DDC	Real Output Bandwidth per DDC
N	0.8 x F _S / N	0.4 x F _S / N

Decimation is enabled by setting the <COMMON DECIMATION> SPI register (0x169, D3-D0). By default, the register is set to 'real' decimation. 'Complex' decimation is enabled with register <COMPLEX EN> (0x162, D2).

8.3.8.1 Uncommon Decimation Ratios

The DDCs can be programmed to have unequal, independent decimation ratios. The output data rate is based on the decimation filter with the lowest decimation ratio. The output samples of the DDCs with higher decimation factors are repeated in the output data stream. For example if DDC0 is set to /4 and DDC1 to /8, then the output data rate of DDC0 is twice as fast as of DDC1 ($F_{out0} = F_S/4$ vs $F_{out1} = F_S/8$). Therefore; the output samples of DDC1 are repeated once as illustrated in Figure 8-22.

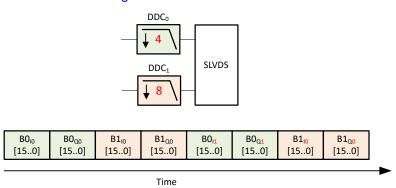


Figure 8-22. Unequal Decimation Factors

8.3.8.2 Decimation Filter Response

This section provides the different decimation filter responses with a normalized ADC sampling rate. The complex filter pass band is approximately 80% (-1dB) with a minimum of 85dB stop band rejection.

The decimation filter responses are normalized to the ADC sampling clock frequency FS and illustrated in Figure 8-24 to Figure 8-52. Each figure contains the filter pass-band, transition band and alias or stop-band as shown in Figure 8-23. The x-axis shows the offset frequency (after the NCO frequency shift) normalized to the ADC sampling rate F_S .

For example, in the divide-by-4 complex setup, the output data rate is F_S / 4 complex with a Nyquist zone of F_S / 8 or 0.125 × F_S . The transition band (colored in blue) is centered around 0.125 × F_S and the alias transition band is centered at 0.375 × F_S . The stop-bands (colored in red), which alias on top of the pass-band, are centered at 0.25 × F_S and 0.5 × F_S . The stop-band attenuation is greater than 85dB.

Note

For higher decimation ratios (/32 onward), the far out transition and stop-bands exceeds -120dB, so the decimation filter plots show only the relevant closer in response with attenuation less than -120dB.

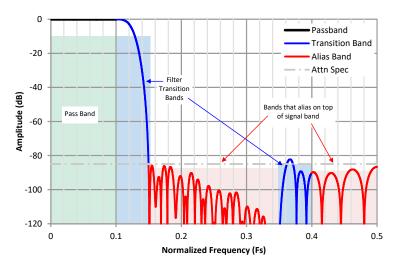
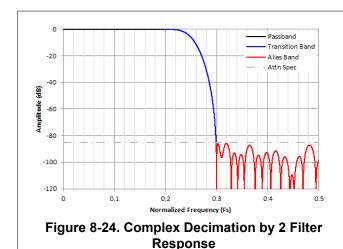


Figure 8-23. Interpretation of the Decimation Filter Plots



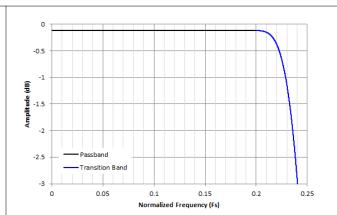
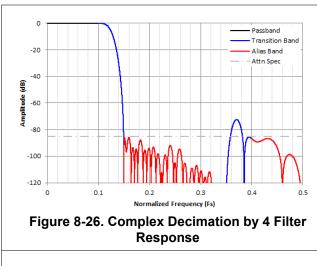


Figure 8-25. Decimation by 2 Passband Ripple Response





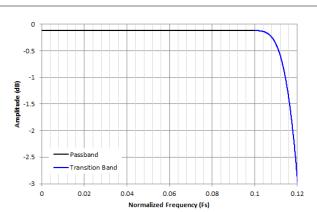
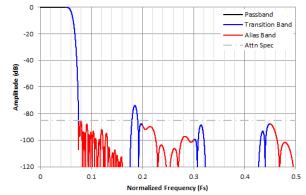


Figure 8-27. Decimation by 4 Passband Ripple Response



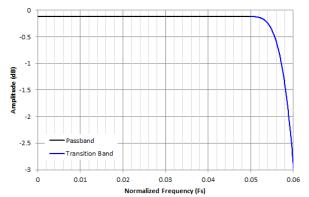
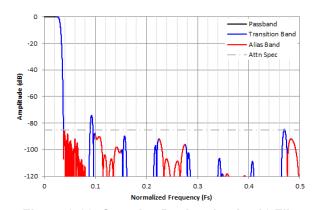


Figure 8-28. Complex Decimation by 8 Filter Response

Figure 8-29. Decimation by 8 Passband Ripple Response



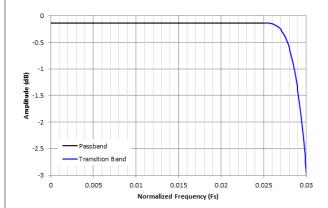


Figure 8-30. Complex Decimation by 16 Filter Response

Figure 8-31. Decimation by 16 Passband Ripple Response



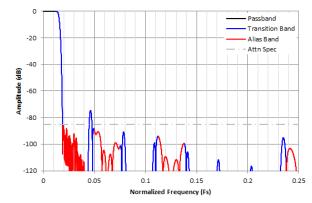


Figure 8-32. Complex Decimation by 32 Filter Response

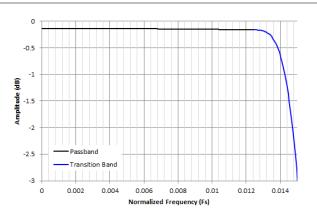


Figure 8-33. Decimation by 32 Passband Ripple Response

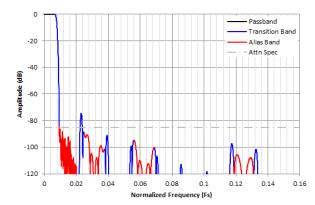


Figure 8-34. Complex Decimation by 64 Filter Response

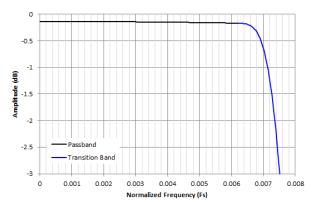


Figure 8-35. Complex Decimation by 64 Filter Ripple Response

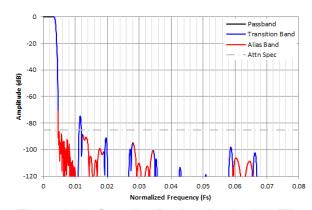


Figure 8-36. Complex Decimation by 128 Filter Response

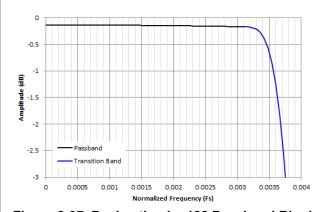
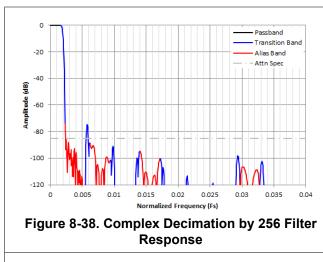


Figure 8-37. Decimation by 128 Passband Ripple Response





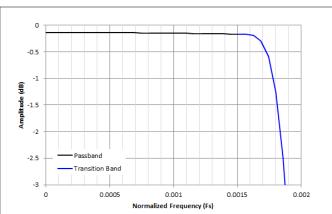
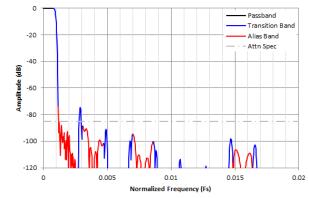


Figure 8-39. Decimation by 256 Passband Ripple Response



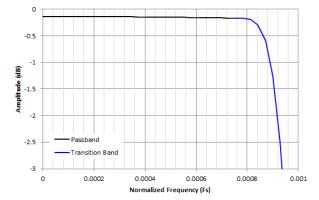
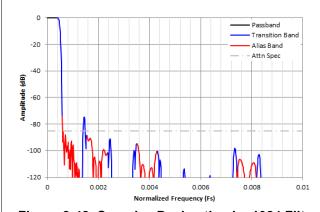


Figure 8-40. Complex Decimation by 512 Filter Response

Figure 8-41. Decimation by 512 Passband Ripple Response



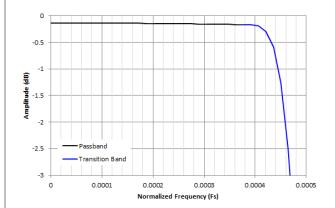


Figure 8-42. Complex Decimation by 1024 Filter Response

Figure 8-43. Decimation by 1024 Passband Ripple Response

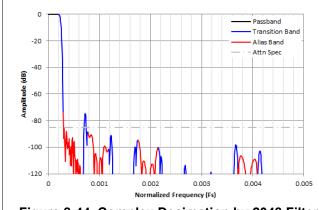


Figure 8-44. Complex Decimation by 2048 Filter Response

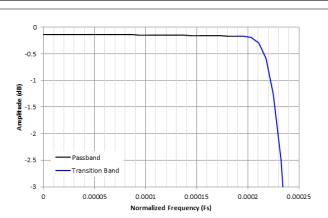


Figure 8-45. Decimation by 2048 Passband Ripple Response

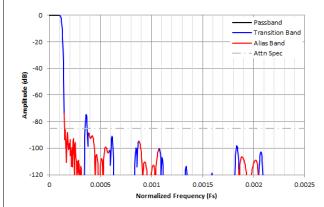


Figure 8-46. Complex Decimation by 4096 Filter Response

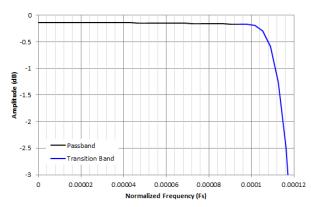


Figure 8-47. Decimation by 4096 Passband Ripple Response

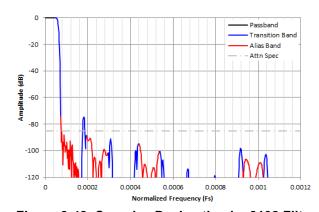


Figure 8-48. Complex Decimation by 8192 Filter Response

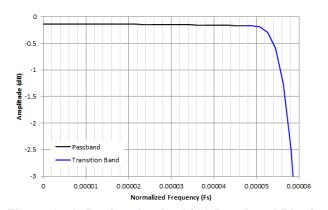
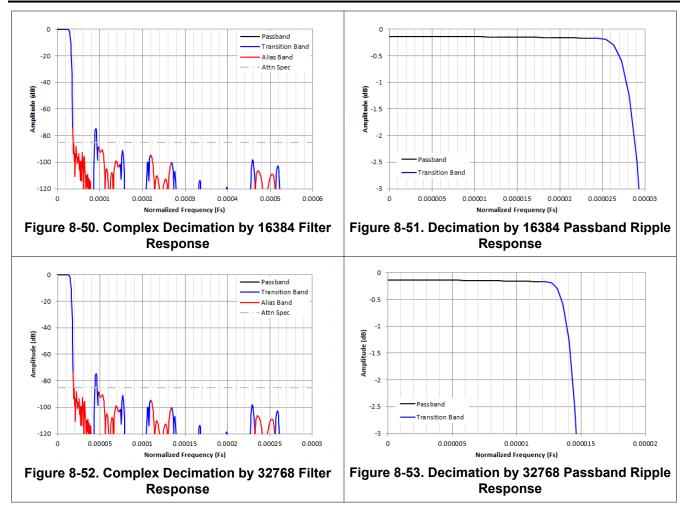


Figure 8-49. Decimation by 8192 Passband Ripple Response





8.3.8.3 Decimation Filter Configuration

The operation of the digital decimation filter can be controlled using registers 0x163 to 0x169. The NCO frequencies are mapped to registers 0x200..0x2DF. The DDC is versatile and can support many operating modes.

Table 8-7. Configuration of the DDC

ADDR	DESCRIPTION			
0x163 Connect ADC ChA to desired DDC. By default the ADC is connected to two DDCs.				
0x164 Select NCO mode and update NCO frequencies				
0x165	0x165 Configure NCO frequency update			
0x166 Assign NCO frequency 03 to each NCO				
0x167/168 Select Decimation for each DDC if unequal decimation factors are used				
0x169	Configure # of DDCs and common decimation factor			

The following sequence can be used to configure the DDC for a static operating mode (either fixed NCO/slow changing NCO frequencies): Complex decimation /1024, quad band 32-bit output

Table 8-8. DDC Example Configuration

	· · · · · · · · · · · · · · · · · · ·		
	ADDR	DATA	DESCRIPTION
	0x162	0x06	Select complex decimation, 32-bit output resolution.
	0x169	0x1A	Configuration to 4x DDC (quad band) with common decimation of 1024.



8.3.8.4 Numerically Controlled Oscillator (NCO)

Each digital down-converter (DDC) uses a 48-bit numerically controlled oscillator (NCO) to fine tune the frequency placement prior to the digital filtering. Up to four different NCO frequencies for each DDC are programmed using SPI register writes. The digital NCOs are designed to have a SFDR of at least 100dB.

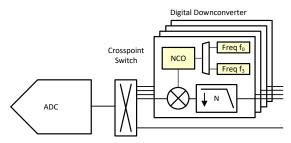


Figure 8-54. NCO Block Diagram

There are two different NCO operating modes - phase continuous and infinite phase coherent.

- 1. Phase Continuous NCO: During a NCO frequency change, the NCO phase gradually adjusts to the new frequency as shown in Figure 8-55 (left). The 'dashed' line shows the phase of original f₁ frequency.
- 2. Infinite Phase Coherent NCO: With a phase coherent NCO, all frequencies are synchronized to a single event using SYSREF. This enables an infinite amount of frequency hops without the need to reset the NCO as phase coherency is maintained between frequency hops. This is illustrated in Figure 8-55 (right). When returning to the original frequency f₁ the NCO phase appears as if the NCO had never changed frequencies.

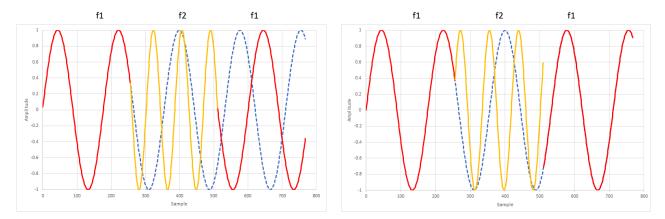


Figure 8-55. Phase Continuous (left) and Infinite Phase Coherent (right) NCO Frequency Switching



The oscillator generates a complex exponential sequence of:

$$e^{j\omega n}$$
 (default) or $e^{-j\omega n}$ (1)

where: frequency (ω) is specified as a signed number by the 48-bit register setting

The complex exponential sequence is multiplied with the real input from the ADC to mix the desired carrier to a frequency equal to f_{IN} + f_{NCO} . The NCO frequency can be tuned from $-F_S/2$ to $+F_S/2$ and is processed as a signed, 2s complement number.

The NCO frequency setting is set by the 48-bit register value given and calculated as:

NCO frequency (0 to +
$$F_S/2$$
): NCO = $f_{NCO} \times 2^{48} / F_S$ (2)

NCO frequency (-F_S/2 to 0): NCO =
$$(f_{NCO} + F_S) \times 2^{48} / F_S$$
 (3)

where:

- NCO = NCO register setting (decimal value)
- f_{NCO} = Desired NCO frequency (MHz)
- F_S = ADC sampling rate (MSPS)

The NCO programming is illustrated with this example:

- ADC sampling rate F_S = 500MSPS
- Desired NCO frequency = 120MHz

NCO frequency setting =
$$f_{NCO} \times 2^{48} / F_S = 120 \text{MHz} \times 2^{48} / 500 \text{ MSPS} = 67,553,994,410,557$$
 (4)

Table 8-9 shows the register writes to set frequency 0 of the NCO of DDC0 to that frequency:

Table 8-9. Example register writes to change NCO frequency

ADDR	DATA	DESCRIPTION
0x200	0x3D	
0x201	0x0A	
0x202	0xD7	Set the NCO0 frequency to 120MHz (67,553,994,410,557)
0x203	0xA3	which is 0x3D70 A3D7 0A3D starting LSB in 0x200.
0x204	0x70	
0x205	0x3D	
0x165	0x00	
0x165	0x01	Load and update all NCOs with the new frequencies.
0x165	0x00	
0x160	0x00	
0x160	0x04	Issue a manual SYSREF (via pin or SPI SYSREF) to update the NCO frequencies.
0x160	0x00	



8.3.9 Digital Interface

The ADC356x supports 3 different LVDS interfaces depending on operating mode:

- 1. SDR LVDS (default): The data is output using a 16-bit wide LVDS bus where each bit uses one output lane on the rising edge of the output clock.
- 2. DDR LVDS: The data is output using a 16-bit wide LVDS bus using both rising and falling edge of the output clock. Data is output on rising edge of the clock while 0s are output on falling edge of the clock.
- 3. Serial LVDS (SLVDS): When using decimation (real or complex) the output data is serialized and output on fewer lanes.

8.3.9.1 Parallel LVDS (SDR) - Default

Parallel LVDS is used in decimation bypass mode. In SDR LVDS all 16 bits are transmitted on 16 LVDS lanes using the rising edge of DCLK as shown in Figure 8-56.

The output data on lanes DOUT0/1/2 can be replaced with:

- Overrange output OVR on lanes DOUT0/1/2, configured in register 0x116
- PRBS bit in output scrambling mode on lanes DOUT0/1/2, configured in register 0x116
- TIME-STAMP on lane DOUT0 only, configured in register 0x162. TIME-STAMP takes precedence over OVR and SCR when configured to DOUT0.

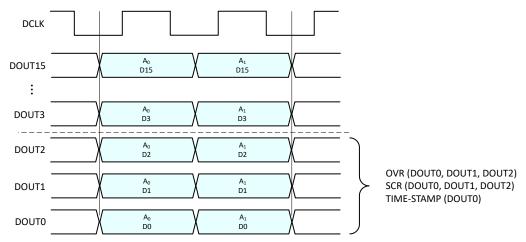


Figure 8-56. Output data format in SDR LVDS mode

8.3.9.2 Parallel LVDS (DDR)

Parallel LVDS is used in decimation bypass mode. The data are transmitted on the rising edge of DCLK while 0s are transmitted on the falling edge of DCLK as shown in Figure 8-57.

The output data of ChA on lanes DOUT0/1/2 can be replaced with:

- Overrange output OVR on lanes DOUT0/1/2, configured in register 0x116
- PRBS bit in output scrambling mode on lanes DOUT0/1/2, configured in register 0x116
- TIME-STAMP on lane DOUT0 only, configured in register 0x162. TIME-STAMP takes precedence over OVR and SCR when configured to DOUT0.



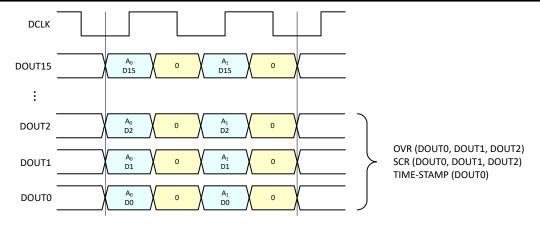


Figure 8-57. Output data format in DDR LVDS mode

8.3.9.3 SLVDS with Decimation

When using real or complex decimation, the output data is serialized and transmitted using fewer LVDS transmitters. A frame clock (FCLK) marks the start and stop of the sample while the data bits are clocked out on the rising and falling edge of the data clock (DCLK). The frame clock is output on DOUT0 and there are a maximum number of 15 LVDS lanes available for data output. The output interface mapping always starts on lane DOUT15.

In real decimation only single band is supported.

The # of lanes and output data rates can be calculated with the following parameters:

- R: Output Resolution: 16-bit = 1, 32-bit = 2
- B: Total number of bands
- C: Real or complex decimation: real = 1, complex = 2
- D: Decimation factor
- FS: ADC sampling clock frequency
- K = R x B x C
- L = 8 x K / D

For L < 1, the DCLK output divider needs to be enabled (0x590, D1)

Table 8-10. SLVDS clock and data rate calculations

Parameter	L ≥1	L<1		
Frame Clock (FCLK) Frequency	e Clock (FCLK) Frequency FS / D			
Data Bit Clock (DCLK) Frequency	FS	DOUT / 2		
Data output rate DOUT per Lane (DOUT/L)	FS x 2	FS / D x 16 x K		

The SLVDS frame assembly is automatically performed by the ADC and follows this scheme, starting on lane DOUT0 and with the MSB of each channel:

Table 8-11. SLVDS frame assembly

Decimation	Output Resolution	Band order		
Real	16-bit	В		
Real	32-bit			
Complex	16-bit			
Complex	32-bit	B _{0I} , B _{0Q} ,B _{1I} , B _{1Q} , B _{2I} , B _{2Q} ,B _{2I} , B _{2Q}		

Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated



Following details the frame assembly and calculations for four different examples.

Example 1: Single band, real decimation by 8, 16-bit output resolution, FS = 500MSPS

- K = 1 (R = 1, B = 1, C = 1)
- L = 8 x K / D = 8 x 1 / 8 = 1
- FCLK = FS / D = 500MSPS / 8 = 62.5MHz
- DCLK = 500MHz
- DOUT/Lane = 1Gbps

The SLVDS frame assembly for example 1 is shown in Figure 8-58. A single lane is used to output the data.

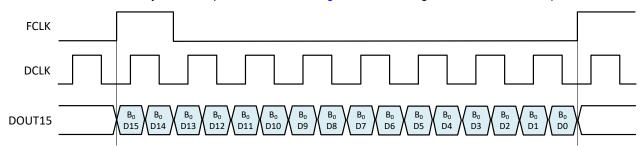


Figure 8-58. SLVDS frame assembly for example 1

Example 2: Single band, real decimation by 128, 32-bit output resolution, FS = 500MSPS

- K = 2 (R = 2, B = 1, C = 1)
- L = 8 x K / D = 8 x 2 / 128 = 1/8 => One lane is used.
- FCLK = FS / D = 500MSPS / 128 = 3.91MHz
- DCLK = 62.5MHz
- DOUT/Lane = 125Mbps

The SLVDS frame assembly for example 2 is shown in Figure 8-59. A single lane is used to transmit the 32 bit.

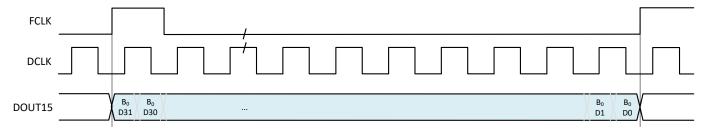


Figure 8-59. SLVDS frame assembly for example 2



Example 3: Dual band, complex decimation by 8, 16-bit output resolution, FS = 500MSPS

- K = 4 (R = 1, B = 2, C = 2)
- $L = 8 \times K / D = 8 \times 4 / 8 = 4$
- FCLK = FS / D = 500MSPS / 8 = 62.5MHz
- DCLK = 500MHz
- DOUT/Lane = 1Gbps

The SLVDS frame assembly for example 3 is shown in Figure 8-60. The frame assembly starts on DOUT15 with the 4 MSB of the 'I'-sample of band 0. Each sample is spread across 4 lanes.

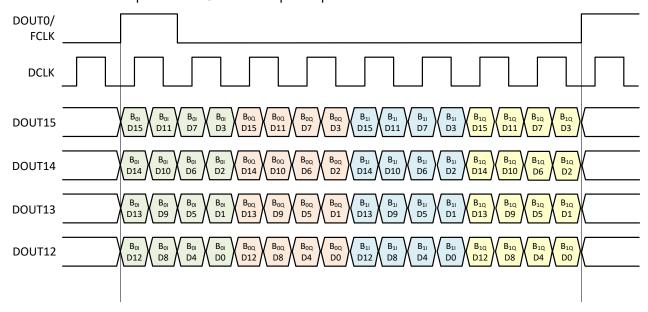


Figure 8-60. SLVDS frame assembly for example 3

Example 4: Dual band, complex decimation by 256, 32-bit output resolution, FS = 500MSPS

- K = 8 (R = 2, B = 2, C = 2)
- $L = 8 \times K / D = 8 \times 8 / 256 = 1/4 => One lane is used.$
- FCLK = FS / D = 500MSPS / 256 = 1.95MHz
- DOUT/Lane = FS / D x 16 x K = 500 MSPS / 256 x 16 x 8 = 250Mbps
- DCLK = 125MHz

The SLVDS frame assembly for example 4 is shown in Figure 8-61. The frame assembly uses only DOUT15 starting with the 32-bit 'I'-sample of band 0 and ending with the 32-bit 'Q'-sample of band 1.

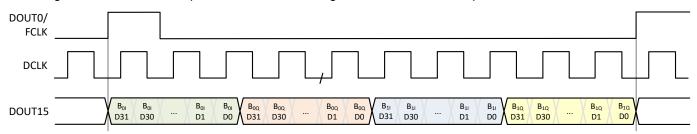


Figure 8-61. SLVDS frame assembly for example 4



8.3.9.3.1 SLVDS - Status Bit Insertion

In serial LVDS with decimation, the output data can also be substituted with the overrange or the PRBS scrambling bit (SCR). Note that the FCLK already is using output lane DOUT0.

When using 16 SLVDS lanes, the OVR or PRBS (SCR) bit can be substituted for LSB+1 (DOUT1) and/or LSB+2 (DOUT2) as shown in the quad band example in Figure 8-62.

When using less than 16 SLVDS lanes, the OVR or PRBS (SCR) bit can be substituted for LSB and/or LSB+1 as shown in the dual band example in Figure 8-63.

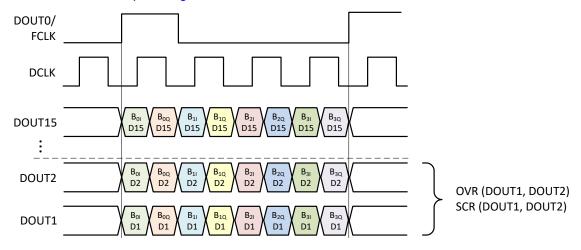


Figure 8-62. Output Data Substitution: 16 SLVDS Lanes

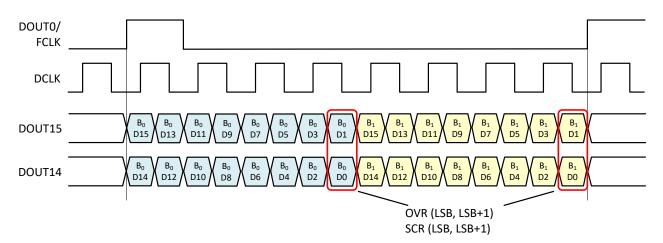


Figure 8-63. Output Data Substitution: <16 SLVDS Lanes

8.3.9.4 Output Data Format

The output data can be configured to two's complement (default) or offset binary formatting using SPI register writes (register 0x162). Table 8-12 provides an overview for minimum and maximum output codes for the two formatting options and 16 or 32-bit output resolution.

Table 8-12. Overview of minimum and maximum output codes vs resolution for different formatting

	Two's Comple	ment (default)	Offset Binary		
RESOLUTION (BIT)	16	32	16	32	
$V_{IN,MAX}$	0x7FFF	0x7FFF FFFF	0xFFFF	0xFFFF FFFF	
0	0x0000	0x0000 0000	0x8000	0x8000 0000	
V _{IN,MIN}	0x8000	0x8000 0000	0x0000	0x0000 0000	

8.3.9.5 32-bit Output Resolution

The ADC356x supports both 16-bit and 32-bit output resolutions. The 32-bit output resolution is recommended for higher decimation factors (decimation by 16 real/by 32 complex and higher) to avoid SNR degradation due to quantization noise limitation as shown in Table 8-13.

The output resolution can be changed with SPI register write in register 0x162.

Table 8-13. Output SNR: Decimation vs Output Resolution

Baseline SNR (dBFS)	Real Decimation	SNR with 3dB per /2 (dBFS)	SNR with 16-bit output resolution (dBFS)	SNR with 32-bit output resolution (dBFS)
76	/16	88.0	87.6	88.0
76	/32	91.1	90.3	91.1
76	/256	100.1	96.0	100.1
76	/32768	121.1	98.0	121.1

8.3.9.6 Output Scrambler

The ADC includes an optional output scrambler. In the ADC, the internal PRBS generator generates a PRBS pattern. Each data bit gets XOR-ed with the PRBS bit stream. The scrambled output data is transmitted (via parallel or serial LVDS) along with the PRBS bit (replacing the LSB, LSB-1 or LSB-2 output data, configured in 0x146).

The receiving logic device extracts the PRBS bit stream and decodes to received data by XOR-ing each data bit with the recovered PRBS-bit.

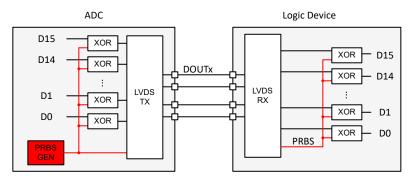
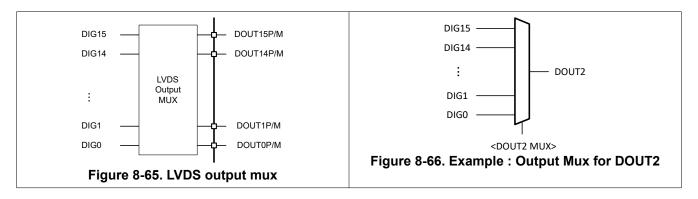


Figure 8-64. Output Scrambler

8.3.9.7 Output MUX

The LVDS output interface includes an output mux which allows rerouting of any internal digital lane to any LVDS output lane as shown in Figure 8-65. This provides lane mapping flexibility which can be used for link redundancy or link repair. The LVDS Output Mux can be enabled by setting <LVDS MUX EN> (Register 0x116, Bit 7). The mux configuration can be controlled by writing to <DOUTxMUX> registers (0x117 to 0x11E). The mux configuration can be described mathematically as DOUTk=DIG[DOUTk_MUX], where k denotes the lane number. For example, setting a value of 2 for <DOUT2 MUX> redirects DIG2 to DOUT2. Figure 8-66 shows an example mux structure that is used for all DOUT pins.

Furthermore, when using serial LVDS (decimation only) this output mux can be used to generate duplicate, redundant outputs by connecting the same internal digital lane to multiple LVDS output lanes.



8.3.9.8 Test Pattern

The device has a built-in test pattern generator for simplifying the debugging and/or calibrating of the LVDS outputs. The test pattern generator is located after the DDC as show in Figure 8-67.

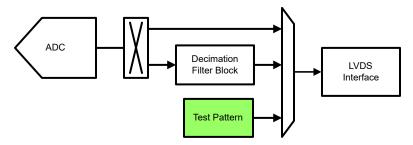


Figure 8-67. Test Pattern Generator

Enabling the test pattern generator (register <TEST PATTERN> in 0x14A) replaces all current output data samples - normal ADC or decimation data. The test pattern is the same for all channels. The test pattern block generates a 20 bit test pattern and the pattern itself is controlled by the value of the <TEST PATTERN> field.

In decimation, the test pattern block operates on the decimated clock by default and can be switched to run on the Fs clock by setting the <PATTERN CLK> field of register 0x14A. The test pattern feature can not be enabled in low latency operation mode.

The following register writes can be used to configure a ramp pattern with a step size of 1 with 16 bit output resolution.

Table 8-14. Example configuration for RAMP pattern with custom step size

ADDR DATA		DESCRIPTION
0x14A 0x02		Enable ramp pattern with customer step size
0x14B	0x10	Step size is 16 LSB (at 20 bit resolution) equivalent to 1 LSB at 16 bit resolution

8.4 Device Functional Modes

Besides normal operation (DDC bypass and DDC) the device supports several additional operating modes.

8.4.1 Low Latency Mode

The device provides a low latency mode of operation by bypassing the Digital Error Correction and all other digital features such as the decimation filter, test pattern or SDR LVDS for example. This operating mode achieves a latency of 9 clock cycles and can be used in applications such as low latency control loops. However, the AC performance can degrade since the Digital Error Correction block is bypassed. The following FFT plots compare the spectrum in Low Latency Mode and Normal operating mode. The Low Latency Mode can be enabled in the <LOW LATENCY EN> register (0x165).

The low latency mode is only available in DDR LVDS interface operation.

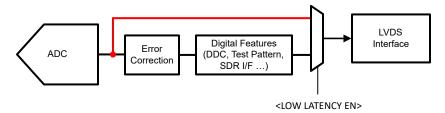
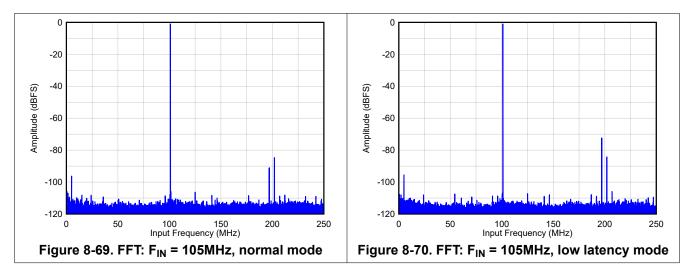


Figure 8-68. Low Latency Mode



8.4.2 Power Down Mode

The global power down mode can be exercised using SPI writes or GPIO pins.

Table 8-15. Power Down Mode Options

Power Down Mode	Pd (typ, mW)	Wake up time (typ)	
Global power down	30	3ms	

The global power down can be assigned to either GPIO0 or GPIO1 using SPI writes in register 0x146.

Table 8-16. GPIO Pin Configuration for Power Down in Register 0x146

	<u> </u>	
GPIO CONFIG	GPIO1	GPIO0
00011	GLOBAL POWER DOWN	
01010		GLOBAL POWER DOWN
01011		GLOBAL POWER DOWN

Submit Document Feedback

8.5 Programming

The device is primarily configured and controlled using the serial programming interface (SPI) however it can operate in a default configuration without requiring the SPI interface. Furthermore the power down function as well as internal/external reference configuration is possible via pin control (GPIO0/1 pins).

Note

The power down command (via PIN or SPI) only goes in effect with the ADC sampling clock present.

8.5.1 GPIO Programming

The device has two GPIO pins that can be configured independently to obtain various functional modes. In the default state, the GPIO0 is configured to act as a SYSREF pin and the GPIO1 is unused. Table 8-37 gives a complete mapping of the GPIO functions. The GPIO functionality can be switched by setting the <GPIO CONFIG> in register 0x146.

The following modes are available for the GPIO pins:

- SYSREF input
- Time stamp input
- · External voltage reference
- NCO switch
- · Global power down
- Overrange

8.5.2 Register Write

The internal registers can be programmed following these steps:

- 1. Drive the SEN pin low
- 2. Set the R/W bit to 0 (bit A15 of the 16-bit address) and bits A[14:12] in address field to 0.
- 3. Initiate a serial interface cycle by specifying the address of the register (A[11:0]) whose content is written and
- 4. Write the 8-bit data that are latched in on the SCLK rising edges

Figure 8-71 show the timing requirements for the serial register write operation.

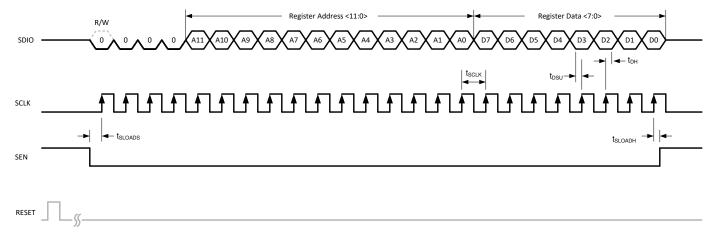


Figure 8-71. Serial Register Write Timing Diagram

8.5.3 Register Read

The device includes a mode where the contents of the internal registers can be read back using the SDIO pin. This readback mode can be useful as a diagnostic check to verify the serial interface communication between the external controller and the ADC. The procedure to read the contents of the serial registers is as follows:

- 1. Drive the SEN pin low
- 2. Set the R/W bit (A15) to 1. This setting disables any further writes to the registers. Set A[14:12] in address field to 0.
- 3. Initiate a serial interface cycle specifying the address of the register (A[11:0]) whose content must be read
- 4. The device launches the contents (D[7:0]) of the selected register on the SDIO pin on SCLK falling edge
- 5. The external controller can capture the contents on the SCLK rising edge

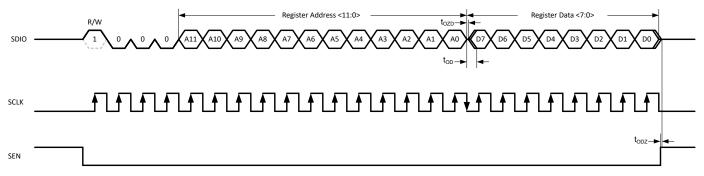


Figure 8-72. Serial Register Read Timing Diagram

8.5.4 Device Programming

All the registers of the device can be programmed using an API (library of functions, written in python). The API has functions for every field in the register map, as well as some macro functions. Macro functions use multiple low level API functions to perform a more complex operation, such as setting the decimation mode (factor, real/complex, number of bands, and so on) and setting an NCO frequency word from an input frequency.

The API user's guide is included when downloading the API from ti.com.



8.5.5 Register Map

Table 8-17. Register Map Summary

REGISTER ADDRESS				REGISTI	ER DATA			
A[11:0]	D7	D6	D5	D4	D3	D2	D1	D0
0x025	0	0	0	CFG RDY	0	0	0	0
0x100	0	0	0	0	0	0	0	RESET
0x101	0	0	0	GBL PDN	0	0	0	0
0x102	0	SYSREF DET CLR	0	0	0	0	0	0
0x104	0	0	0	0	0	0	0	CHA TERM
0x10A	0	0	0	0	0	OVR	CLR	OVR STICKY
0x10B				OVR L	ENGTH			
0x110	LVDS TERM	0	LVDS ½ SWING	0	0	SDR/DDR	SWAP CH	0
0x111				LVDS DAT	A INV [7:0]	1		
0x112				LVDS DATA	A INV [15:8]			
0x113			L	VDS PDN [14:8	3]			0
0x114	0	0	0	0	0	0	0	LVDS PDN [15]
0x115	0	0	0	0	FCLK DC	FCLK DIS	0	0
0x116	LVDS MUX EN	LVDS SWAP RISE/FALL	0	0	0		LVDS SCR	
0x117		DOUT1 MUX				DOUT	0 MUX	
0x118		DOUT3 MUX				DOUT2 MUX		
0x119		DOUT	5 MUX		DOUT4 MUX			
0x11A		DOUT	7 MUX			DOUT	6 MUX	
0x11B		DOUT	9 MUX			DOUT	8 MUX	
0x11C		DOUT	11 MUX			DOUT	10 MUX	
0x11D		DOUT ²	13 MUX			DOUT	12 MUX	
0x11E		DOUT ²	15 MUX			DOUT	14 MUX	
0x132	HIGH FIN	0	0	0	0	0	0	0
0x140	0	SYSREF DET	SYSREF OR	SYSREF X5	SYSREF X4	SYSREF X3	SYSREF X2	SYSREF X1
0x146	0	0	0			GPIO CONFIG		
0x14A	0	0	0	PATTERN CLK	0		TEST PATTERI	N
0x14B				CUSTOM PA	ATTERN [7:0]	1		
0x14C				CUSTOM PA	TTERN [15:8]			
0x14D	0	0	0	0		CUSTOM PAT	TTERN [19:16]	
0x15B				DIGITAL (GAIN CHA			
0x160	0	0	0	0	0	0	SYSRE	F MODE
0x161	LVDS SYS	REF MASK	DDC SYSF	REF MASK	NCO SYSI	REF MASK	TIMER SYS	SREF MASK
0x162	SYSREF T	IME STAMP	0	6dB GAIN	OVERRIDE COMPLEX OUTPUT OUTPUT DDC EN RES FORMAT			
0x163	DDC3	3 MUX	DDC2	MUX	DDC1	MUX	DDC	MUX
0x164	NCO3 UPDATE	NCO2 UPDATE	NCO1 UPDATE	NCO0 UPDATE	SEL NEG IM	0	0	NCO MODE



Table 8-17. Register Map Summary (continued)

REGISTER ADDRESS		REGISTER DATA						
A[11:0]	D7	D6	D5	D4	D3	D2	D1	D0
0x165	0	0	0	LOW LATENCY EN	0	DIS NCO AUTO UPDATE	NCO SEL EN	NCO COMMON UPDATE
0x166	DDC3 N	CO SEL	DDC2 N	ICO SEL	DDC1 N	ICO SEL	DDC0 N	CO SEL
0x167		DDC1 DE	CIMATION			DDC0 DE	CIMATION	
0x168		DDC3 DE	CIMATION			DDC2 DE	CIMATION	
0x169	UNEQUAL DECIMATION	0	# OF	DDCS		COMMON [DECIMATION	
0x16B			UPDATE NYQUIST ZONE			1	NYQUIST_ZONE	Ξ
0x2050x200			D	DC0 NCO FRE	QUENCY0 [47	:0]		
0x20B0x206			D	DC0 NCO FRE	QUENCY1 [47	:0]		
0x2110x20C			D	DC0 NCO FRE	QUENCY2 [47	:0]		
0x2170x212			D	DC0 NCO FRE	QUENCY3 [47	:0]		
0x219/0x218				DDC0 NCO P	HASE0 [15:0]			
0x21B/0x21A				DDC0 NCO P	HASE1 [15:0]			
0x21D/0x21C				DDC0 NCO P	HASE2 [15:0]			
0x21F/0x21E				DDC0 NCO P	HASE3 [15:0]			
0x2450x240			D	DC1 NCO FRE	QUENCY0 [47	:0]		
0x24B0x246			D	DC1 NCO FRE	QUENCY1 [47	:0]		
0x2510x24C			D	DC1 NCO FRE	QUENCY2 [47	:0]		
0x2570x252			D	DC1 NCO FRE	QUENCY3 [47	:0]		
0x259/0x258				DDC1 NCO P	HASE0 [15:0]			
0x25B/0x25A				DDC1 NCO P	HASE1 [15:0]			
0x25D/0x25C				DDC1 NCO P	HASE2 [15:0]			
0x25F/0x25E				DDC1 NCO P	HASE3 [15:0]			
0x2850x280			D	DC2 NCO FRE	QUENCY0 [47	[0]		
0x28B0x286			D	DC2 NCO FRE	QUENCY1 [47	:0]		
0x2910x28C			D	DC2 NCO FRE	QUENCY2 [47	:0]		
0x2970x292			D	DC2 NCO FRE	QUENCY3 [47	:0]		
0x299/0x298				DDC2 NCO P	HASE0 [15:0]			
0x29B/0x29A				DDC2 NCO P	HASE1 [15:0]			
0x29D/0x29C				DDC2 NCO P	HASE2 [15:0]			
0x29F/0x29E				DDC2 NCO P	HASE3 [15:0]			
0x2C50x2C0				DC3 NCO FRE				
0x2CB0x2C6				DC3 NCO FRE				
0x2D10x2CC				DC3 NCO FRE				
0x2D70x2D2			D	DC3 NCO FRE	<u>-</u>	:0]		
0x2D9/0x2D8	DDC3 NCO PHASE0 [15:0]							
0x2DB/0x2DA		DDC3 NCO PHASE1 [15:0]						
0x2DD/0x2DC	DDC3 NCO PHASE1 [15:0]							
0x2DF/0x2DE				DDC3 NCO P	HASE3 [15:0]	1		
0x590	0	0	0	0	0	0	ENABLE DCLK DIVIDER	0

Table 8-17. Register Map Summary (continued)

REGISTER ADDRESS		REGISTER DATA						
A[11:0]	D7	D6	D5	D4	D3	D2	D1	D0
0x691		LVDS PDN [5:7]	DCLK PD	0	0	0	0
0x692	0	0	0			LVDS PDN [0:4]	

8.5.6 Detailed Register Description

Figure 8-73. Register 0x025

			J · · · ·	- J			
7	6	5	4	3	2	1	0
0	0	0	CFG RDY	0	0	0	0

Table 8-18. Register 0x025 Field Descriptions

Bit	Field	Туре	Reset	Description
7-5	0	R/W	0	Must write 0
0	CFG RDY	R/W	0	This bit indicates the status of the internal fuse load after HW reset. 0: Fuse load not complete 1: Fuses are loaded, applied and device ready for programming.
3-0	0	R/W	0	Must write 0

Figure 8-74. Register 0x100

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	RESET

Table 8-19. Register 0x100 Field Descriptions

Bit	Field	Туре	Reset	Description
7-1	0	R/W	0	Must write 0
0	RESET	R/W	0	This bit resets all internal registers to the default values and self clears to 0.

Figure 8-75. Register 0x101

			•	•			
7	6	5	4	3	2	1	0
0	0	0	GBL PDN	0	0	0	0

Table 8-20. Register 0x101 Field Descriptions

Bit	Field	Туре	Reset	Description
7-5	0	R/W	0	Must write 0
4	GBL PDN	R/W	0	Global power down. This bit powers down the entire device. This feature is also available using GPIO pins. 0: normal operation 1: Device in global power down mode
3-0	0	R/W	0	Must write 0



Figure 8-76. Reg	ister 0x102
------------------	-------------

7	6	5	4	3	2	1	0
0	SYSREF DET CLR	0	0	0	0	0	0

Table 8-21. Register 0x102 Field Descriptions

Bit	Field	Туре	Reset	Description
7	0	R/W	0	Must write 0
6	SYSREF DET CLR	R/W		This bit resets the SYSREF DET flag (0x140, D6) 0: normal operation 1: SYSREF DET flag gets reset.
5-0	0	R/W	0	Must write 0

Figure 8-77. Register 0x104

7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	CHA TERM

Table 8-22. Register 0x104 Field Descriptions

Bit	Field	Туре	Reset	Description
7-1	0	R/W	0	Must write 0
0	CHA TERM	R/W		ChA internal termination. This bit sets the internal termination on channel A. 0: 100Ω differential termination 1: 200Ω differential termination

Table 8-23. Register 0x10A

7	6	5	4	3	2	1	0
0	0	0	0	0	OVR	CLR	OVR STICKY

Table 8-24. Register 0x10A Field Descriptions

Bit	Field	Туре	Reset	Description				
7-3	0	R/W	0	Must write 0				
2-1	OVR CLR	R/W	0	This is useful for clearing the sticky bit. Setting a value of 0x2 clears the sticky OVR				
0	OVR STICKY	R/W	0	This bit makes the OVR sticky. 0: OVR is non-sticky (updated based on <ovr length="">) 1: OVR is sticky (use <ovr clr=""> to reset)</ovr></ovr>				

Table 8-25. Register 0x10B

7	7 6 5		4	4 3		1	0			
OVR LENGTH										

Table 8-26. Register 0x10B Field Descriptions

Bit	Field	Туре	Reset	Description
7-0	OVR LENGTH	R/W		This controls the OVR pulse expansion. This field species the expansion width in terms of the number of clock cycles. For example 0x0F sets the OVR length to 16 clock cycles.

Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated



INSTRUMENTS www.ti.com

Figure 8-78. Register 0x110

7	6	5	4	3	2	1	0
LVDS TERM	0	LVDS ½ SWING	0	0	SDR/DDR	0	0

Table 8-27. Register 0x110 Field Descriptions

Bit	Field	Туре	Reset	Description				
7	LVDS TERM	R/W	0	This bit configures the LVDS termination resistance. Setting this bit enables 100 Ohm termination. The default termination resistance is 50Ω				
6	0	R/W	0	Must write 0				
5	LVDS 1/2 SWING	consur 0: Nori		This bit reduces the LVDS output swing by 50% to save power consumption. 0: Normal output swing 1: Reduced output swing				
4-3	0	R/W	0	Must write 0				
2	SDR/DDR R/W		1	This bit configures the parallel LVDS output interface. When only a single channel is output, SDR LVDS can be enabled. 0: DDR LVDS 1: SDR LVDS				
1-0	0	R/W	0	Must write 0				

Figure 8-79. Register 0x111/0x112

7	6	5	4	3	2	1	0				
	LVDS DATA INV [7:0]										
	LVDS DATA INV [15:8]										

Table 8-28. Register 0x111/0x112 Field Descriptions

Bit	Field	Туре	Reset	Description
7-0	LVDS DATA INV [15:0]	R/W	0	These bits allow inversion of the polarity of individual LVDS output lanes as shown in Table 8-29. 0: Polarity as shown in pin diagram. 1: Polarity inverted

Table 8-29. LVDS data inversion register lane assignment

REG ADDR	G ADDR 0x112							0x111								
REG BIT D7 D6 D5 D4 D3				D2	D1	D0	D7	D6	D5	D4	D3	D2	D1	D0		
LVDS OUTPUT LANE	8	9	10	11	12	13	14	15	7	6	5	4	3	2	1	0

Figure 8-80. Register 0x113/0x114

7	6	5	4	3	2	1	0			
LVDS PDN [14:8]										
0 0 0 0 0 0										

Table 8-30. Register 0x113/0x114 Field Descriptions

Bit	Field	Туре	Reset	Description
7-0	LVDS PDN [15:8]	R/W		These register bits power down the individual LVDS output lanes with LVDS pins into high impedance state (e.g. 0x113, D7 powers down output lane 14). The remaining LVDS lane (0-7) power down registers are in registers 0x691/0x692. 0: Normal operation 1: LVDS output lane powered down
7-0	0	R/W	0	Must write 0



Figure 8-81. Register 0x115

7	6	5	4	3	2	1	0		
0	0	0	0	FCLK DC	FCLK DIS	0	LVDS SCR EN		

Table 8-31. Register 0x115 Field Descriptions

Bit	Field	Type Reset I		Description
7-4	0	R/W	0	Must write 0
3	FCLK DC	R/W	0	This bit allows adjusting the FCLK duty cycle. 0: FCLK stays high for one DCLK cycle at the beginning of the output sample 1: FCLK stays high for 50% of the output sample
2	FCLK DIS	R/W	0	This bit disables the output FCLK. FCLK is transmitted on lane DOUT0. In decimation modes where all 16 lanes are used, FCLK replaces the LSB. 0: FCLK replaces the LSB data and is transmitted on DOUT0 1: FCLK is disabled and the LSB data is transmitted on DOUT0.
1	0	R/W	0	Must write 0
0	0	R/W	0	Must write 0

Figure 8-82. Register 0x116

7	6	5	4	3	2	1	0
LVDS MUX EN	LVDS SWAP RISE/FALL	0	0	0		LVDS SCR	

Table 8-32. Register 0x116 Field Descriptions

Bit	Field	Туре	Reset	Description
7	LVDS MUX EN	R/W	0	This bit enables use of the LVDS output mux in registers 0x1170x11E. 0: LVDS output mux disabled 1: LVDS output mux enabled
6	LVDS SWAP RISE/FALL	R/W	0	This bit swaps the output data bits transmitted on rising and falling edge of DCLK. 0: Normal operation 1: Output bits on rising and falling edge are swapped.
5-3	0	R/W	0	Must write 0
2-0	LVDS SCR	R/W	0	This field controls the scrambling and Isb insertion config on the output data 000: Default operation 001: Data is XOR'ed with a PRBS bit. This PRBS is inserted on the LSB position. The PRBS is generated using a large LFSR and can be treated as random for all practical scenarios 010: OVR is inserted on the LSB position 011: OVR is inserted on the LSB+1 position 100: Data is XOR'ed with a PRBS bit, and the PRBS is inserted on LSB+1 position 101: OVR is inserted on LSB+1 position, PRBS is insetted on LSB position. Data is XOR'ed with PRBS 110: OVR is inserted on LSB+2 position, PRBS is insetted on LSB+1 position. Data is XOR'ed with PRBS 111: Unused

Submit Document Feedback



www.ti.com

Figure 8-83. Register 0x117...0x11E

7	6	5	4	3	2	1	0
	DOUT1/3/5/7/9	/11/13/15 MUX			DOUT0/2/4/6/8	/10/12/14 MUX	

Table 8-33. Register 0x117...0x11E Field Descriptions

					• · · · · · · · · · · · · · · · · · · ·
	Bit	Field	Туре	Reset	Description
	7-4	DOUT1/3/5/7/9/11/13/15 MUX	R/W	0000	These bits configure the data bus assignment for the individual
	3-0	DOUT0/2/4/6/8/10/12/14 MUX	R/W	0000	output lanes. 0000: LVDS lane DOUTx carries data of internal digital bus lane DIG0 0001: LVDS lane DOUTx carries data of internal digital bus lane DIG1 1111: LVDS lane DOUTx carries data of internal digital bus lane DIG15

Figure 8-84. Register 0x132

7	6	5	4	3	2	1	0
HIGH FIN	0	0	0	0	0	0	0

Table 8-34. Register 0x132 Field Descriptions

		•		
Bit	Bit Field Type		Reset	Description
7	HIGH FIN	R/W		This bit must be set for best AC performance for input frequencies greater than 500 MHz 0: Input frequencies < 500 MHz 1: Input frequencies > 500 MHz
6-0	0	R/W	0	Must write 0



Figure 8-85. Register 0x140

7	6	5	4	3	2	1	0
0	SYSREF EN	SYSREF OR	SYSREF X5	SYSREF X4	SYSREF X3	SYSREF X2	SYSREF X1

Table 8-35. Register 0x140 Field Descriptions

Bit	Field	Туре	Reset	Description
7	0	R/W	0	Must write 0
6	SYSREF DET	R/W	0	This register indicates if a SYSREF signal is detected. Upon detection this bit stays high until it gets reset (0x102, D6) or a device reset is issued. 0: no SYSREF signal detected 1: SYSREF signal detected
5	SYSREF OR	R/W	0	This bit is the output of the five SYSREF XOR flags logically OR'ed together. 0: no SYSREF flag raised 1: one of the five SYSREF XOR flags is raised.
4-0	SYSREF X5X1	R/W	0	These bits are the XOR flags from the SYSREF window monitoring circuitry. The sampling clock falling edge is used to capture the SYSREF signal. If a SYSREF signal transition happens within -60/+140 ps of the SYSREF capture, the appropriate XOR flag gets raised. These bits are updated on every SYSREF rising edge. X1: SYSREF leading sample clock by 20 to 60ps X2: SYSREF leading sample clock by 20ps to 0ps or SYSREF lagging sample clock by 0 to 20ps X3: SYSREF lagging sample clock by up to 20 to 60ps X4: SYSREF lagging sample clock by 60 to 100ps X5: SYSREF lagging sample clock by 100 to 140ps 0: No SYSREF transition detected 1: SYSREF transition detected within given window

Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated



Figure 8-86. Register 0x146

			•	•			
7	6	5	4	3	2	1	0
0	0	0			GPIO CONFIG		

Table 8-36. Register 0x146 Field Descriptions

Bit	Field	Type Reset		Description
7-5	0	R/W	0	Must write 0
4-0	GPIO CONFIG	R/W	0	These register bits configure the functionality of the two GPIO pins as shown in Table 8-37.

Table 8-37. GPIO pin configuration

GPIO CONFIG	GPIO1	GPIO0	
00000	NOT USED	SYSREF	
00011	GLOBAL POWER DOWN	SYSREF	
00100	EXTERNAL REFERENCE	SYSREF	
00101	NCO SWITCH1	NCO SWITCH0	
01000	NOT USED	SYSREF	
01001	OVR CHA	SYSREF	
01010	NOT USED	GLOBAL POWER DOWN	
01011	OVR CHA	GLOBAL POWER DOWN	
10010	NOT USED	OVR CHA	
all others	NOT	USED	



Figure 8-87. Register 0x14A

			•	•			
7	6	5	4	3	2	1	0
0	0	0	PATTERN CLK	0	TEST PATTERN		

Table 8-38. Register 0x14A Field Descriptions

Bit	Field	Туре	Reset	Description
7-5	0	R/W	0	Must write 0
4	PATTERN CLK	R/W	0	This controls the clock of the pattern signal generator. Setting this bit switches the pattern generator clock to decimation clock. 0: Pattern clock uses the ADC sampling clock 1: Pattern clock uses the DDC clock
3	0	R/W	0	Must write 0
2-0	TEST PATTERN	R/W	0	This field controls the type of pattern injected. Default value is 0 and indicates that the pattern generator is off. The generated pattern is 20 bit wide. In 16 bit resolution mode, MSB 16 bits of the pattern mode are sent out. In 32 bit resolution mode, 12 zero bits are padded to the generated pattern and sent out. 000: Test pattern is disabled 001: Ramp pattern with a step of 1 (at 20 bit level, which is equivalent to 1/16 at 16 bit level) 010: Ramp pattern with a step value set by CUSTOM PATTERN. For example, to configure a ramp pattern with unit step in 16 bit mode, the CUSTOM PATTERN must be set to 0x010 011: Unused 100: Static pattern set by CUSTOM PATTERN 101: Pattern toggles between CUSTOM PATTERN and invert of CUSTOM PATTERN 110: Pattern toggles between CUSTOM PATTERN and 0 111: Unused

Figure 8-88. Register 0x14B/0x14C/0x14D

7 6 5		4	3	2	1	0		
CUSTOM PATTERN [7:0]								
			CUSTOM PA	TTERN [15:8]				
0	0 0 0 CUSTOM PATTERN [19:16]							

Table 8-39. Register 0x14B/0x14C/0x14D Field Descriptions

Bit	Field	Туре	Reset	Description
7-0	CUSTOM PATTERN [19:0]	R/W	0	This filed controls the pattern generator. This controls different
				functions depending on the TEST PATTERN setting

Figure 8-89. Register 0x15B

7	6	5	4	3	2	1	0
			DIGITAL GA				

Table 8-40. Register 0x15B Field Descriptions

Bit	Field	Туре	Reset	Description
7-0	DIGITAL GAIN CHA [7:0]	R/W		This register controls digital gain for channel A and is interpreted as a 2's complement number. Maximum gain is 6dB 20 x log (1+(DIGITAL GAIN CHA / 128))

Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated



Figure 8-90. Register 0x160

			•	•			
7	6	5	4	3	2	1	0
0	0	0	0	0	SPI SYSREF	SYSREI	MODE

Table 8-41. Register 0x160 Field Descriptions

Bit	Field	Туре	Reset	Description
7-3	0	R/W	0	Must write 0
2	SPI SYSREF	R/W	0	Must write 0
1-0	SYSREF MODE	R/W		This controls the global SYSREF mask 00: Pass all SYSREF pulses 01: Pass the first SYSREF pulse and gates subsequent pulses 10: Gate all SYSREF pulses 11: Issue new SYSREF pulse. The pulse is issued when the state transitions to 11

Figure 8-91. Register 0x161

7	6	5	4	3	2	1	0
LVDS SYS	REF MASK	DEC SYSF	REF MASK	NCO SYSREF MASK		TIMER SYSREF MASK	

Table 8-42. Register 0x161 Field Descriptions

	Table 0-42. Register 0x1011 leid Descriptions										
Bit	Field	Туре	Reset	Description							
7-6	LVDS SYSREF MASK	R/W	0	This controls the SYSREF pulse going to the LVDS block. Default setting is 0 and passes all SYSREF pulses. 00: Pass all SYSREF pulses 01: Pass the first SYSREF pulse and gates subsequent pulses 10: Gate all SYSREF pulses 11: Issue new SYSREF pulse. The pulse is issued when the state transitions to 11							
5-4	DDC SYSREF MASK	R/W	0	This controls the SYSREF pulse of DDC block. The value - function map is same as LVDS SYSREF MASK							
3-2	NCO SYSREF MASK	R/W	0	This controls the SYSREF pulse of NCO block. The value - function map is same as LVDS SYSREF MASK							
1-0	TIMER SYSREF MASK	R/W	0	This controls the SYSREF pulse of TIMER block. The value - function map is same as LVDS SYSREF MASK							



Figure 8-92. Register 0x162

7	6	5	4	3	2	1	0
SYSREF TI	ME STAMP	0	6dB GAIN	OVERRIDE	COMPLEX DDC EN	OUTPUT RES	OUTPUT FORMAT

Table 8-43. Register 0x162 Field Descriptions

Bit	Field	Туре	Reset	Description
7-6	SYSREF TIME STAMP	R/W	0	Setting this field to 0x3 allows the SYSREF to replace the LSB. OVR_ON_LSB setting takes precedence
5	0	R/W	0	Must write 0
4-3	6dB GAIN OVERRIDE	R/W	0	This field controls 6dB gain setting of the DDC. The 6dB gain is applied in COMPLEX DDC mode by default. Setting this to 0x3 forces 6dB gain on the DDC output, irrespective of the DDC mode. Setting this to 0x2 forces unity gain irrespective of the DDC mode.
2	COMPLEX DDC EN	R/W	0	This bit enables complex decimation for all DDCs. The decimation factor is set in 0x1670x169 0: Real decimation 1: Complex decimation
1	OUTPUT RES	R/W	0	This bit increases the output resolution from 16-bit to 32-bit 0: 16-bit output resolution 1: 32-bit output resolution
0	OUTPUT FORMAT	R/W	0	This bit selects the output format 0: Output format is 2s complement 1: Output format is offset binary

Figure 8-93. Register 0x163

7	6	5	4	3	2	1	0
DDC3 MUX DDC2 M		MUX	DDC1	MUX	DDC0	MUX	

Table 8-44. Register 0x163 Field Descriptions

Bit	Field	Туре	Reset	Description
7-6	DDC3 MUX	R/W	0	These register bits set the input data source to the individual decimation filters. 00: unconnected 01: Channel A others: not used
5-4	DDC2 MUX	R/W	0	These register bits set the input data source to the individual decimation filters. 00: Channel A 01: unconnected others: not used
3-2	DDC1 MUX	R/W	0	These register bits set the input data source to the individual decimation filters. 00: unconnected 01: Channel A others: not used
1-0	DDC0 MUX	R/W	0	These register bits set the input data source to the individual decimation filters. 00: Channel A 01: unconnected others: not used

Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated

INSTRUMENTS

Figure 8-94. Register 0x164

	7	6	5	4	3	2	1	0
NC	O3 UPDATE	NCO2 UPDATE	NCO1 UPDATE	NCO0 UPDATE	SEL NEG IM	0	0	NCO MODE

Table 8-45. Register 0x164 Field Descriptions

Bit	Field	Туре	Reset	Description
7	NCO3 UPDATE	R/W	0	A '0' to '1' transition in these register bits updates the four NCO
6	NCO2 UPDATE	R/W	0	frequencies of the respective NCOs.
5	NCO1 UPDATE	R/W	0	
4	NCO0 UPDATE	R/W	0	
3	SEL NEG IM	R/W	0	This field contols the selection of negative frequency image, and is applicable only in COMPLEX DDC model.
2-1	0	R/W	0	Must write 0
0	NCO MODE	R/W	0	This register configures the NCOs operating mode. 0: Phase continuous 1: Infinite phase coherent

Figure 8-95. Register 0x165

7	6	5	4	3	2	1	0
0	0	0	LOW LATENCY	0	DIS NCO AUTO	NCO SEL EN	NCO COMMON
			EN		UPDATE		UPDATE

Table 8-46. Register 0x165 Field Descriptions

D:4	Field			Pagarintian
Bit	Field	Type	Reset	Description
7-5	0	R/W	0	Must write 0
4	LOW LATENCY EN	R/W	0	This bit enables low latency mode by bypassing all digital features. 0: Normal operation 1: Enables low latency mode
3	0	R/W	0	Must write 0
2	DIS NCO AUTO UPDATE	R/W	0	This register bit disables the automatic update when switching the NCOs using GPIO pins 0: Normal operation 1: Automatic switch disabled
1	NCO SEL EN	R/W	0	This bit enables NCO frequency selection via SPI register 0x166 instead of GPIO pins. 0: NCO frequency selection via GPIO pins 1: NCO frequency selection via register 0x166.
0	NCO COMMON UPDATE	R/W	0	A '0' to '1' transition in this register bit updates the four NCO frequencies of all NCOs.

Figure 8-96. Register 0x166

7	6	5	4	3	2	1	0
DDC3 NCO SEL DDC2 NCO SE		CO SEL	DDC1 N	ICO SEL	DDC0 N	ICO SEL	

Table 8-47. Register 0x166 Field Descriptions

	Bit	Field	Туре	Reset	Description
	7-6	DDC3 NCO SEL	R/W	0	These bits select which of the 4 frequencies are active in the
Γ	5-4	DDC2 NCO SEL	R/W	1()	respective DDCs/NCOs. The <nco en="" sel=""> bit in register 0x165 (D1) has to be set also.</nco>
Γ	3-2	DDC1 NCO SEL	R/W	0	ONTO (Bir) had to be detailed.
Ī	1-0	DDC0 NCO SEL	R/W	0	



Figure 8-97. Register 0x167/168

	7	6	5	4	3	2	1	0
Ī		DDC1/3 DE	CIMATION			DDC0/2 DE	CIMATION	

Table 8-48. Register 0x167/0x168 Field Descriptions

Bit	Field	Туре	Reset	Description
7-4	DDC1/3 DECIMATION	R/W	0	These bits set the decimation filter factors for the respective
3-0	DDC0/2 DECIMATION	R/W	0	DDCs when using unequal decimation factors. Register <unequal decimation=""> in register 0x169 (D7) has to be set also. 0000: DDC bypass 0001: Decimation by 2 0010: Decimation by 4 1110: Decimation by 16384 1111: Decimation by 32768</unequal>

Figure 8-98. Register 0x169

7	6	5	4	3	2	1	0
UNEQUAL DECIMATION	0	# OF	DDCS		COMMON D	ECIMATION	

Table 8-49. Register 0x169 Field Descriptions

Bit	Field	Туре	Reset	Description
7	UNEQUAL DECIMATION	R/W	0	This bit enables configuration of DDC03 to have unequad decimation factors. 0: Common decimation factor for all DDCs 1: Unequal decimation factors
6	0	R/W	0	Must write 0
5-4	# OF DDCS	R/W	00	This register configures the # of active DDCs 00: Dual DDC Mode 01: Quad DDC Mode 10: Single DDC Mode 11: not used
3-0	COMMON DECIMATION	R/W	0000	This register bit set the decimation filter factors for all active DDCs. 0000: DDC bypass 0001: Decimation by 2 0010: Decimation by 4 1110: Decimation by 16384 1111: Decimation by 32768

Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated

INSTRUMENTS www.ti.com

Figure 8-99. Register 0x16B

7	6	5	4	3	2	1	0
0	0	0	UPDATE NYQUIST ZONE	0		NYQUIST ZONE	

Table 8-50. Register 0x16B Field Descriptions

Bit	Field	Туре	Reset	Description				
7-5	0	R/W	0	Must write 0				
4	UPDATE NYQUIST ZONE	R/W	0	This field must be pulsed after the Nyquist zone if programme A 0 to 1 transition on this bit copies the NYQUIST ZONE filed an internal register.				
3	0	R/W	0	Must write 0				
2-0	NYQUIST ZONE	R/W	000	This field controls the nyquist zone of operation. The internal calibration of the device depends on the NYQUIST ZONE of the signal being sampled. This field must be programmed based on the operating Nyquist zone 000: First Nyquist zone (from 0 to Fs/2) 001: Second Nyquist (from Fs/2 to Fs) 010: Third Nyquist (from Fs to 3Fs/2) 011:Fourth Nyquist (from 3Fs/2 to 2Fs) 100: Fifth Nyquist (from 2Fs to 5Fs/2) 101: Sixth Nyquist (from 5Fs/2 to 3Fs) 110,111: not used				

Figure 8-100. Register 0x200..0x2DF

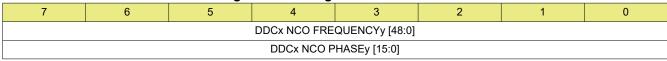


Table 8-51. Register 0x200..0x2DF Field Descriptions

Bit	Field	Туре	Reset	Description
7-0	DDCx NCO FREQUENCYy [48:0]	R/W	0	These register bits configure the 48-bit frequency words for the four DDCs/NCOs. The format is little endian.
7-0	DDCx NCO PHASEy [15:0]	R/W	0	These register bits configure the starting phase of the four frequency words for the four DDCs/NCOs. The format is little endian. The phase value is: 90° / <16-bit register>

Figure 8-101. Register 0x590

7	6	5	4	3	2	1	0
0	0	0	0	0	0	ENABLE DCLK	0
						DIVIDER	

Table 8-52. Register 0x590 Field Descriptions

Bit	Field	Туре	Type Reset Description				
7-2	0	R/W	0	Must write 0			
1	ENABLE DCLK DIVIDER	R/W		Setting this bit enables the DCLK divider. This is required for high decimation factors when the bit clock of the LVDS is lower than the ADC clk.			



Figure 8-102. Register 0x691/0x692

7 6 5		4	3	2	1	0	
	LVDS PDN [5:7]		DCLK PDN	0	0	0	0
0	0	0	LVDS PDN [0:4]				

Table 8-53. Register 0x691/0x692 Field Descriptions

Bit	Field	Туре	Reset	Description					
7-0	LVDS PDN [0:7]	R/W	0	These register bits power down the individual LVDS output lanes with LVDS pins in high impedance state as shown in Table 8-54. The remaining LVDS bus power down registers are in registers 0x113/0x114. 0: Normal operation 1: LVDS output lane powered down					
4	DCLK PDN	R/W	0	This bit powers down the LVDS output clock. 0: Normal operation 1: DCLK powered down					

Table 8-54. LVDS power down register lane assignment

						•		_			-					
REG ADDR		0x113					0x114		0x691				0x692			
REG BIT	D7	D6	D5	D4	D3	D2	D1	D0	D7	D6	D5	D4	D3	D2	D1	D0
LVDS OUTPUT LANE	14	13	12	11	10	9	8	15	5	6	7	0	1	2	3	4

Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated



9 Application and Implementation

Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

9.1 Application Information

The ADC356x can be used in a wide range of applications including RADAR, frequency domain digitizer, spectrum analyzer, test and communications equipment and software-defined radios (SDRs). The Typical Applications section describes one general purpose configuration that meets the needs of a number of these applications.

9.2 Typical Application

9.2.1 Wideband Spectrum Analyzer

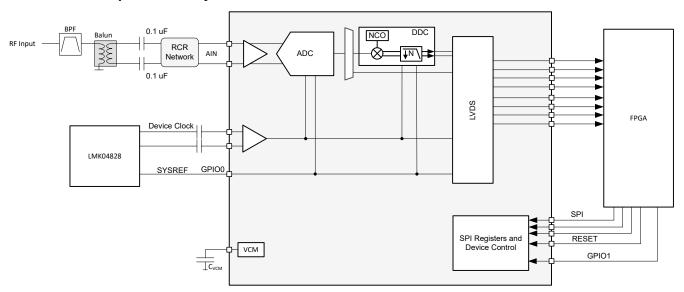


Figure 9-1. Typical Configuration for Wideband Spectrum Analyzer

9.2.2 Design Requirements

9.2.2.1 Input Signal Path

Appropriate band limiting filters must be used to reject unwanted frequencies in the receive signal path.

A 1:2 (for 100Ω effective termination impedance) or a 1:1 (for 50Ω effective termination impedance) balun transformer is needed to convert the single ended RF input to differential for input to the ADC. The balun outputs must be AC coupled with 100pF capacitors. A back-to-back balun configuration often times gives better SFDR performance. Table 9-1 lists a number of recommended baluns for different impedance ratios and frequency ranges.

The S-parameters of the ADC input can be used to design the front end matching network.

PART NUMBER MANURACTURER(1) **IMPEDANCE AMPLITUDE** PHASE FREQUENCY RANGE **RATIO BALANCE (dB)** BALANCE (°) BAL-0009SMG 1:2 0.5MHz to 9GHz Marki Microwave 0.6 5 TCM2-43X+ Minicircuits 1:2 0.5 7 10MHz to 4GHz TCM2-33WX+ Minicircuits 1:2 0.7 4 10MHz to 3GHz 2-3 TC1-1-13M+ Minicircuits 1:1 0.5 10MHz to 3GHz

Table 9-1. Recommended Baluns

9.2.2.2 Clocking

The device clock inputs must be AC-coupled to the device to provide the rated performance. The clock source must have low jitter (integrated phase noise) for the ADC to meet the stated SNR performance, especially when operating at higher input frequencies. The clock signal can be filtered with a band pass filter to remove some of the broad band clock noise. In multi-channel systems the SYSREF signal can be generated using a LMK04828 or LMK04832 device. The LMK device can also be used as a system clock synthesizer.

9.2.3 Detailed Design Procedure

9.2.3.1 Sampling Clock

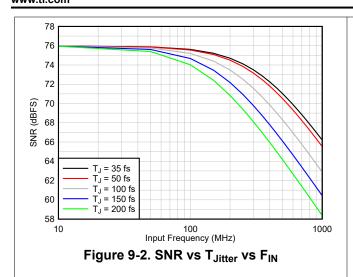
To maximize the SNR performance of the ADC a very low jitter (< 75fs) sampling clock is required. Figure 9-2 shows the estimated SNR performance vs input frequency vs external clock jitter. The internal ADC aperture jitter also has some dependence to the clock amplitude (gets more sensitive with higher input frequency) as shown in Figure 9-3.

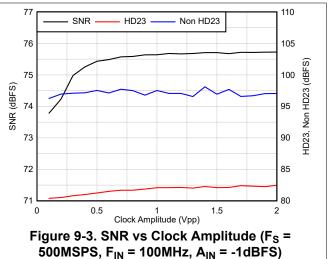
When using averaging and/or decimation, the SNR for a single ADC core must be estimated first before adding the SNR improvement from internal averaging and/or decimation.

Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated

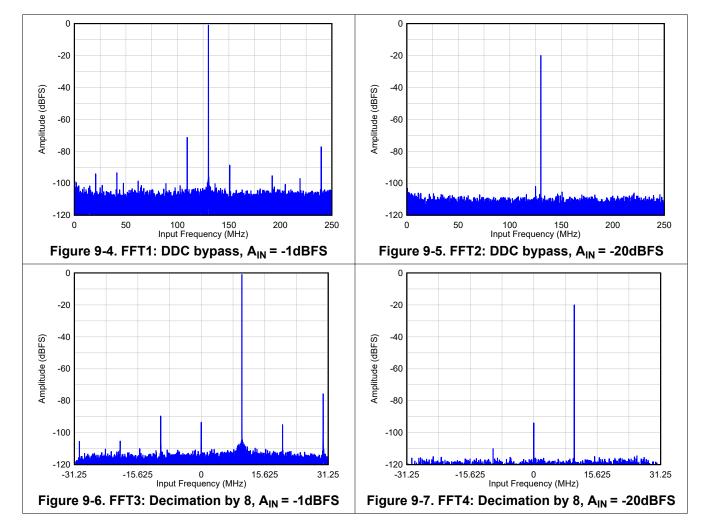
⁽¹⁾ See the Third-Party Products Disclaimer.





9.2.4 Application Performance Plots

The following application curves demonstrate performance and results only of the ADC using a balun front end. The input frequency is 370 MHz (F_S = 500 MSPS) and input amplitudes of -1 and -20dBFS are shown. Operating modes are DDC bypass and complex decimation by 8 (NCO = 360 MHz).





9.2.5 Initialization Set Up

After power-up, the internal registers must be initialized to the default values through a hardware reset by applying a high pulse on the RESET pin, as shown in Figure 9-8.

- 1. Apply 1.2V DVDD12 digital power supply
- 2. Apply 1.2V AVDD12 analog power supply
- 3. Apply 1.8V power supplies (AVDD18, DVDD18), in no specific order
- 4. Apply external voltage reference and/or GPIO pin assignments (optional)
- 5. Apply external sampling clock
- 6. Apply hardware reset. After hardware reset is released, the default registers are loaded from internal fuses.
- 7. Read back 'CFG RDY register' (0x25, D4) to check if internal load is complete (< 10k clock cycles).
- 8. If needed, begin programming the internal registers using the SPI.
- 9. Full ADC performance is available after approximately 5M clock cycles.

For power down, the inverse of this sequence can be followed.

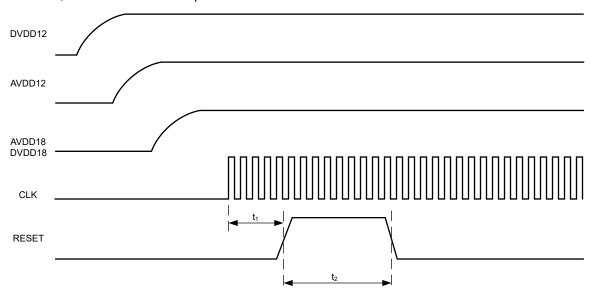


Figure 9-8. Initialization of Serial Registers After Power-Up

Table 9-2. Power-Up Timing

		MIN	TYP	MAX	UNIT
t ₁	Power-on delay: delay from power up to active high RESET pulse	1			us
t ₂	Reset pulse width: active high RESET pulse width	100			ns

Submit Document Feedback

9.3 Power Supply Recommendations

The ADC356x requires four different power-supplies. The AVDD18 and AVDD12 rails provide power for the internal analog and clocking circuits of the ADC. The DVDD18 and DVDD12 rail powers the digital logic (including averaging and decimation filter) and the LVDS digital interface.

Power sequencing is required as shown in Section 9.2.5. The AVDD18 and AVDD12 power supplies must be low noise to achieve data sheet performance. For applications operating near DC, the 1/f noise contribution of the power supply must also be considered.

Power supply decoupling capacitors (0.1µF) as close to the pins as possible on the top layer are recommended.

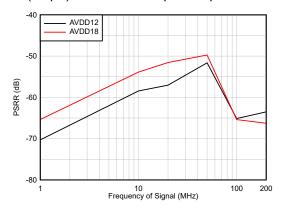


Figure 9-9. Power Supply Rejection Ratio (PSRR) vs Frequency

The recommended power supply architecture for a low noise design is to first use a high-efficiency step down switching regular, followed by a second stage of regulation using a low noise LDO for each power rail as shown in Figure 9-10. This provides additional switching noise reduction and improved voltage accuracy.

TI WEBENCH® Power Designer can be used to select and design the individual power-supply elements. Recommended switching regulators for the first stage include the LMS3635, and similar devices. Recommended low dropout (LDO) linear regulators include the TPS7A8400, and similar devices.

AVDD18 or AVDD12 must not be shared with the DVDD18/12 to prevent digital switching noise from coupling into the analog domain.

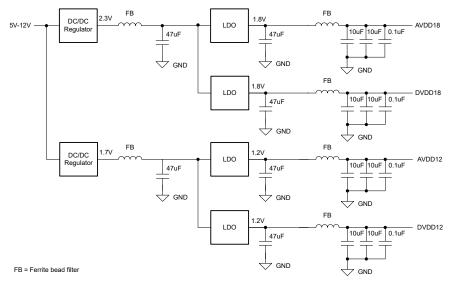


Figure 9-10. Power Supply Design Example

9.4 Layout

9.4.1 Layout Guidelines

There are several critical signals which require specific care during board design:

- 1. Analog input and clock signals
 - Make the traces as short as possible, and avoid vias where possible to minimize impedance discontinuities.
 - Traces can be routed using loosely coupled 100Ω differential traces.
 - Match differential trace lengths as close as possible to minimize phase imbalance and HD2 degradation.
- 2. Digital LVDS output interface
 - Route traces using tightly coupled 100Ω differential traces.
- 3. Power and ground connections
 - Provide low resistance connection paths to all power and ground pins.
 - Use power and ground planes instead of traces.
 - · Avoid narrow, isolated paths which increase the connection resistance.
 - Use a signal, ground, power circuit board stackup to maximize coupling between the ground and power plane.

9.4.2 Layout Example

The following screen shot shows the top layer of the ADC366x EVM. ADC354x/6x (single channel 14/16bit) and ADC364x/6x (dual channel 14/16bit) share the same EVM.

- The input signal traces are routed as loosely coupled, differential signals on the top layer avoiding vias. Figure 9-11 shows the layout example of the top layer.
- The LVDS output interface lanes are routed differential, tightly coupled and length matched.
- Bypass caps are close to the power pins on the top layer avoiding vias.

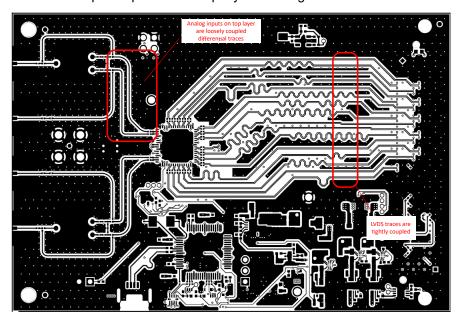


Figure 9-11. Layout example: top layer of ADC366x EVM



10 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed below.

10.1 Documentation Support

10.1.1 Third-Party Products Disclaimer

TI'S PUBLICATION OF INFORMATION REGARDING THIRD-PARTY PRODUCTS OR SERVICES DOES NOT CONSTITUTE AN ENDORSEMENT REGARDING THE SUITABILITY OF SUCH PRODUCTS OR SERVICES OR A WARRANTY, REPRESENTATION OR ENDORSEMENT OF SUCH PRODUCTS OR SERVICES, EITHER ALONE OR IN COMBINATION WITH ANY TI PRODUCT OR SERVICE.

10.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

10.3 Support Resources

TI E2E[™] support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

10.4 Trademarks

TI E2E[™] is a trademark of Texas Instruments.

WEBENCH® is a registered trademark of Texas Instruments.

All trademarks are the property of their respective owners.

10.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

10.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

11 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	hanges from Revision A (January 2025) to Revision B (June 2025)	Page
•	Updated pins SCLK and SDIO from pull-up to DGND to pull-up to DVDD18 in the Pin Functions	3
•	Changed min sampling rate from 125MSPS to 100MSPS in the CLOCK INPUT (CLKP/M) section	6
•	Updated internal equivalent input circuitry with more detailed model in Figure 8-2	25
•	Added GPIO pin assignment in step 4 of the power up sequence and added power down sequence	70

Changes from Revision * (December 2024) to Revision A (January 2025) Changed the ADC3568 from Product Preview to Production



12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

Submit Document Feedback

Copyright © 2025 Texas Instruments Incorporated

www.ti.com 30-Jun-2025

PACKAGING INFORMATION

Orderable part number	Status	Material type	Package Pins	Package qty Carrier	RoHS	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking
	(1)	(2)			(3)	(4)	(5)		(6)
ADC3568IRTD	Active	Production	VQFN (RTD) 64	260 JEDEC TRAY (5+1)	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 85	AZ3568
ADC3568IRTD.A	Active	Production	VQFN (RTD) 64	260 JEDEC TRAY (5+1)	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 85	AZ3568
ADC3568IRTDT	Active	Production	VQFN (RTD) 64	250 SMALL T&R	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 85	AZ3568
ADC3568IRTDT.A	Active	Production	VQFN (RTD) 64	250 SMALL T&R	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 85	AZ3568
ADC3569IRTD	Active	Production	VQFN (RTD) 64	260 JEDEC TRAY (5+1)	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 85	AZ3569
ADC3569IRTD.A	Active	Production	VQFN (RTD) 64	260 JEDEC TRAY (5+1)	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 85	AZ3569
ADC3569IRTDT	Active	Production	VQFN (RTD) 64	250 SMALL T&R	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 105	AZ3569
ADC3569IRTDT.A	Active	Production	VQFN (RTD) 64	250 SMALL T&R	Yes	NIPDAUAG	Level-3-260C-168 HR	-40 to 105	AZ3569

⁽¹⁾ Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

⁽²⁾ Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

⁽⁴⁾ Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.



PACKAGE OPTION ADDENDUM

www.ti.com 30-Jun-2025

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

PACKAGE MATERIALS INFORMATION

www.ti.com 16-May-2025

TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width							
В0	Dimension designed to accommodate the component length							
K0	Dimension designed to accommodate the component thickness							
W	Overall width of the carrier tape							
P1	Pitch between successive cavity centers							

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADC3568IRTDT	VQFN	RTD	64	250	180.0	16.4	9.3	9.3	1.5	12.0	16.0	Q2
ADC3569IRTDT	VQFN	RTD	64	250	180.0	16.4	9.3	9.3	1.5	12.0	16.0	Q2

www.ti.com 16-May-2025



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADC3568IRTDT	VQFN	RTD	64	250	213.0	191.0	55.0
ADC3569IRTDT	VQFN	RTD	64	250	213.0	191.0	55.0

VQFNP - 0.9 mm max height PLASTIC QUAD FLATPACK - NO LEAD



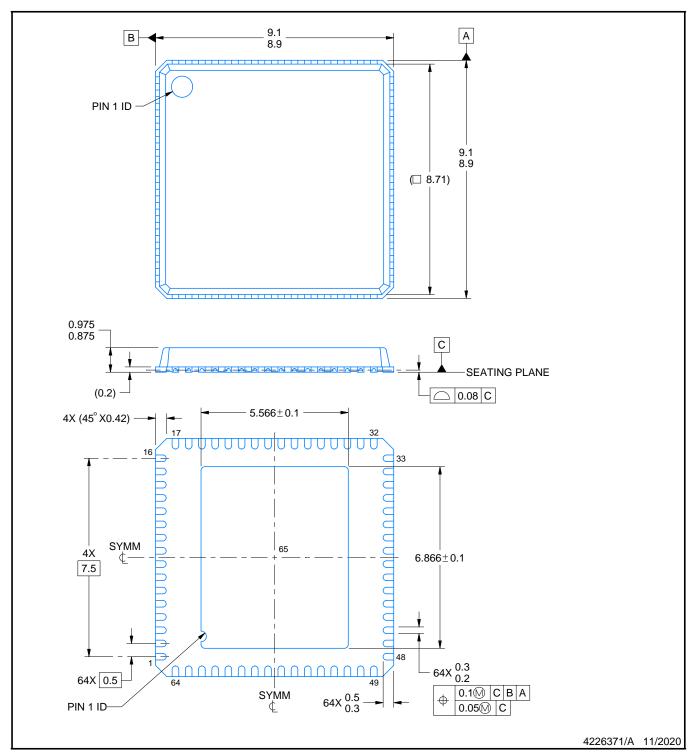
Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.

4205146/D





PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

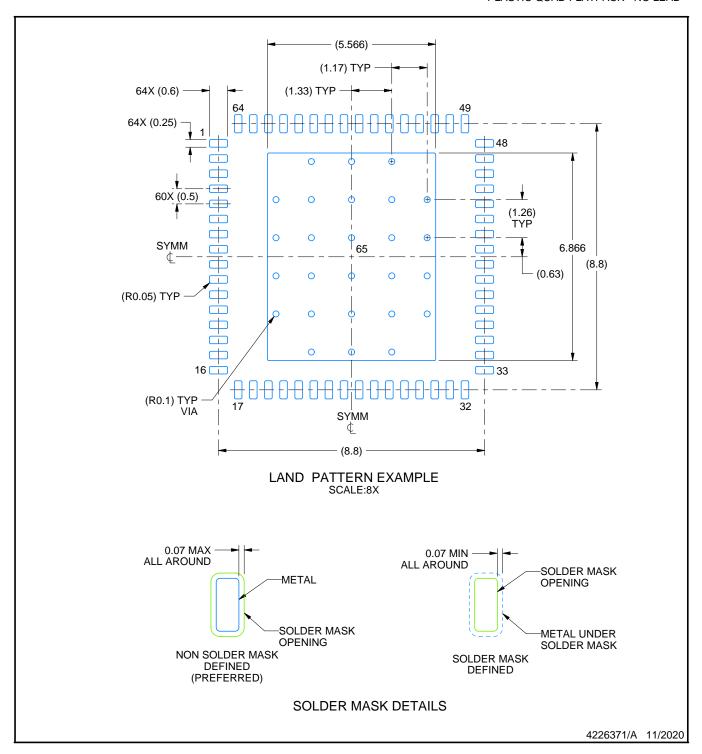
- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

 2. This drawing is subject to change without notice.

 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



PLASTIC QUAD FLATPACK - NO LEAD

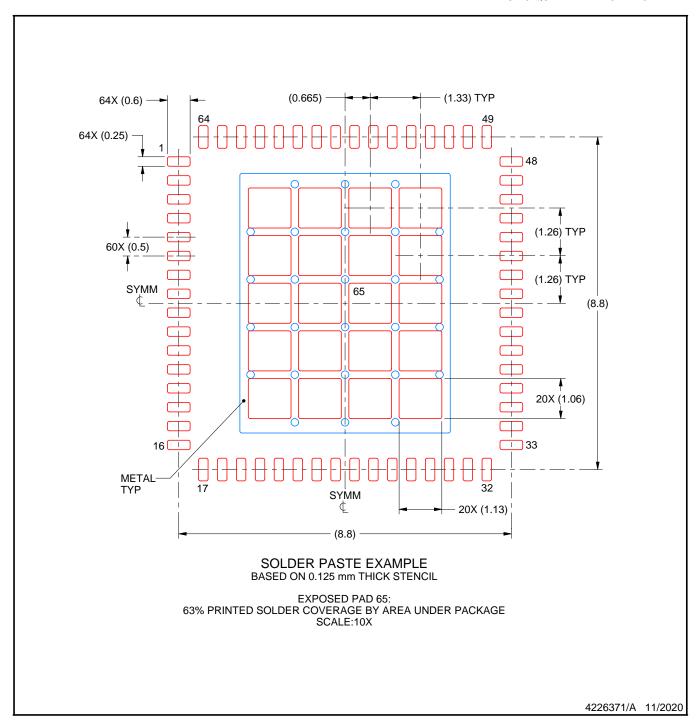


NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2025. Texas Instruments Incorporated