

## Test Report: PMP30602

# Tiny -60 V cuk reference design for automotive applications



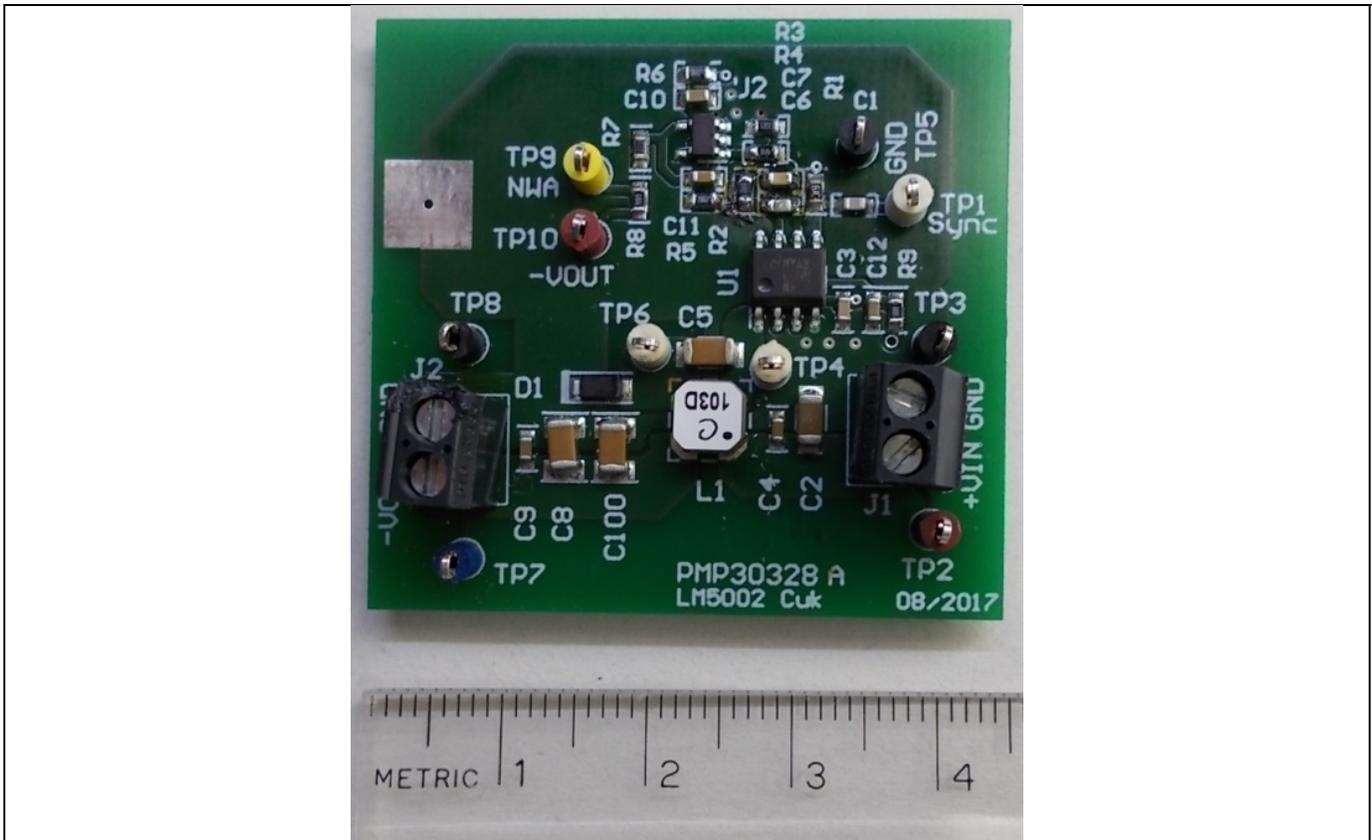
### Description

This tiny reference design delivers -60 V output voltage from an input voltage around 5V typically generated by an automotive pre regulator. The LM5001-Q1 is the controller, TLV271-Q1 converts the negative output voltage to be suitable for positive feedback (FB) input of the LM5001.

In general this converter is used as auxiliary supply for LiDAR applications. Due to duty cycle limitations some controllers are limited inverting 5V input to -60V output - PMP30602 and PMP30603 are offering cost effective solution to do so.

### Features PMP30602:

- Small board space 30mm x 30mm, two layers, single side assembly
- Cost effective boost controller LM5001 with integrated low side FET
- Peak efficiency 75% despite large duty cycle, total power losses <500mW
- Fine thermal behavior, temperature rise less than +20K at full load
- Load regulation less than 30mV means less than 0.05%
- Output ripple around 200mVpp
- Low reflected ripple (=conducted emissions) by Cuk topology (=inverting SEPIC)
- Tiny dual inductor 5mm x 5mm from stock



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## 1 Test Prerequisites

### 1.1 Voltage and Current Requirements

**Table 1. Voltage and Current Requirements**

PARAMETER	SPECIFICATIONS
Input Voltage Range	4.5 V to 5.5 V
Output Voltage	-60 V
Maximum Output Current	20 mA

### 1.2 Considerations

The measured switching frequency is around 285 kHz.

Unless otherwise mentioned, all measurements were done with 5 V input voltage and 20 mA.

**UVLO:** The circuit starts with switching with 2.9 V (with an output voltage of -50 V) and stops with switching around 2.8 V.

Resistors were used as load.

## 2 Testing and Results

### 2.1 Efficiency Graphs

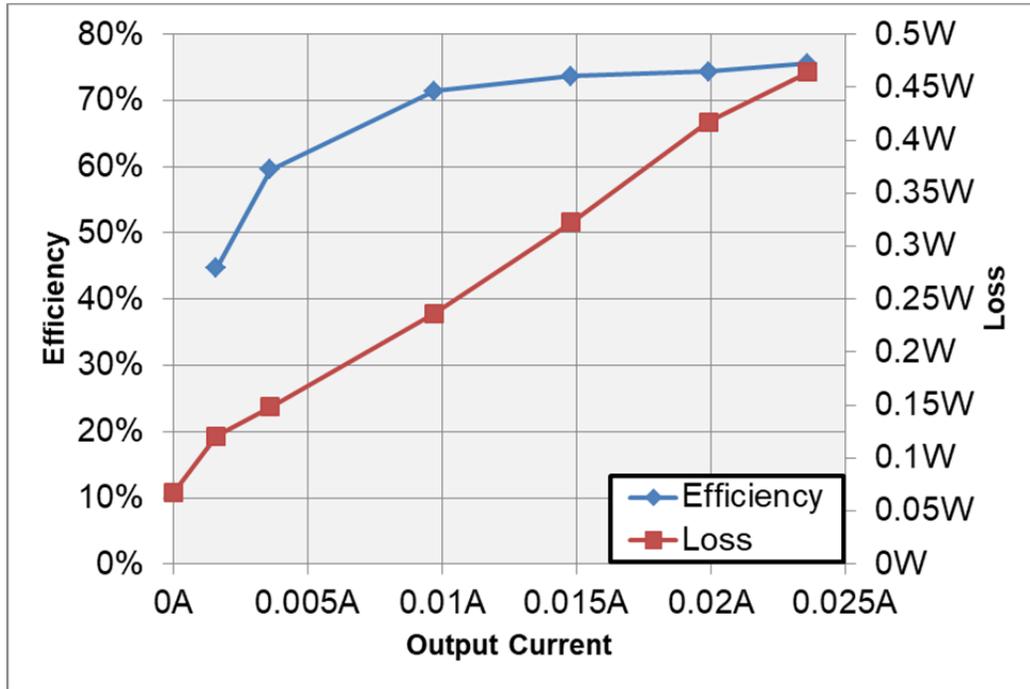


Figure 1 Efficiency and Loss vs Output Current

### 2.2 Load Regulation

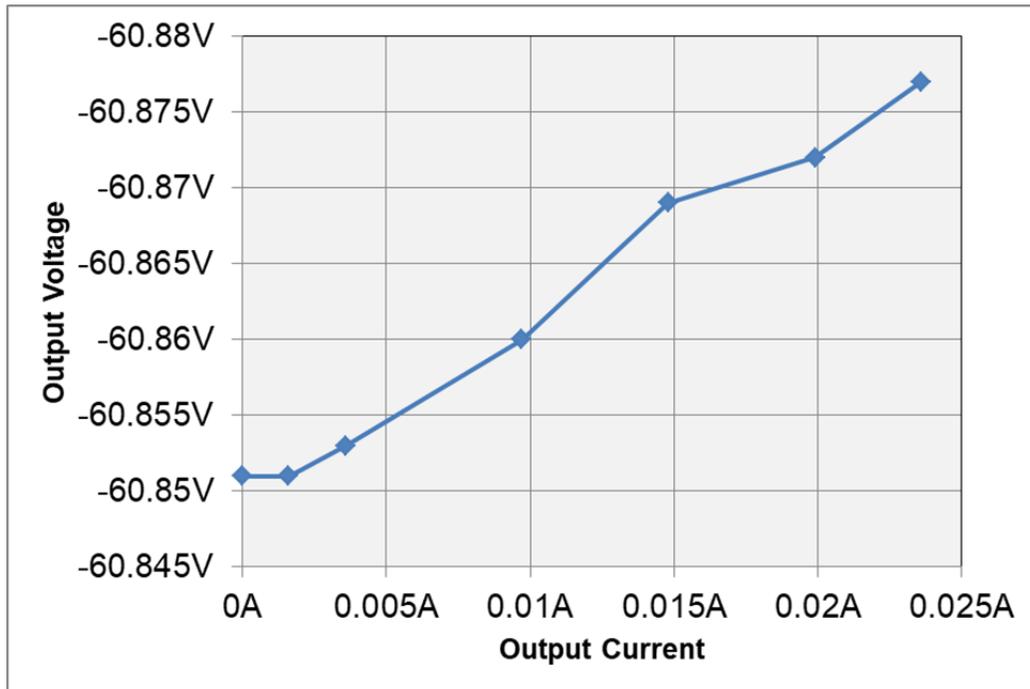


Figure 2 Output Voltage vs Output Current

### 2.3 Thermal Images

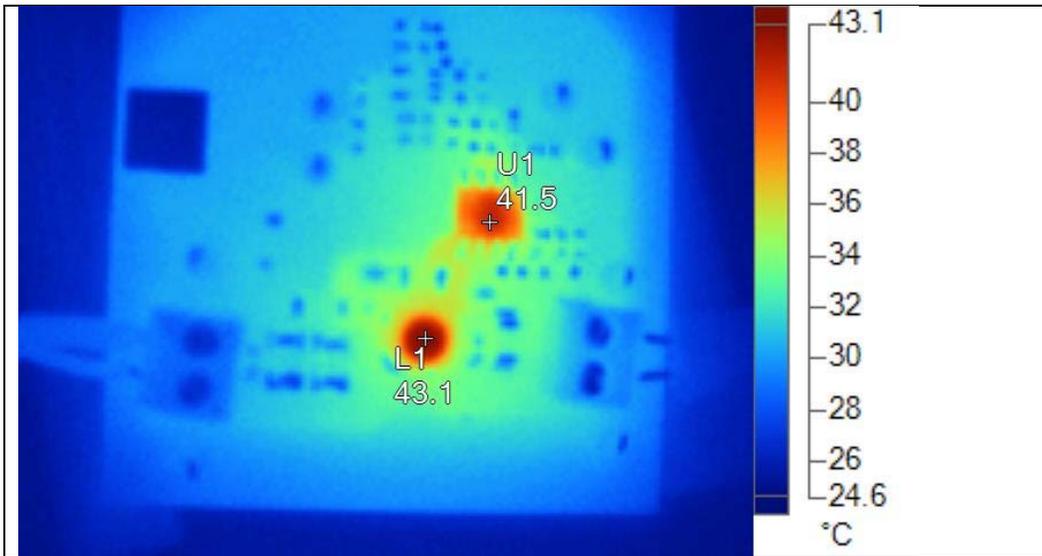


Figure 3 thermal IR-Foto

Name	Temperature
L1	43.1°C
U1	41.5°C

### 3 Waveforms – converter is in discontinuous mode DCM

#### 3.1 Switching

##### 3.1.1 TP4 to GND

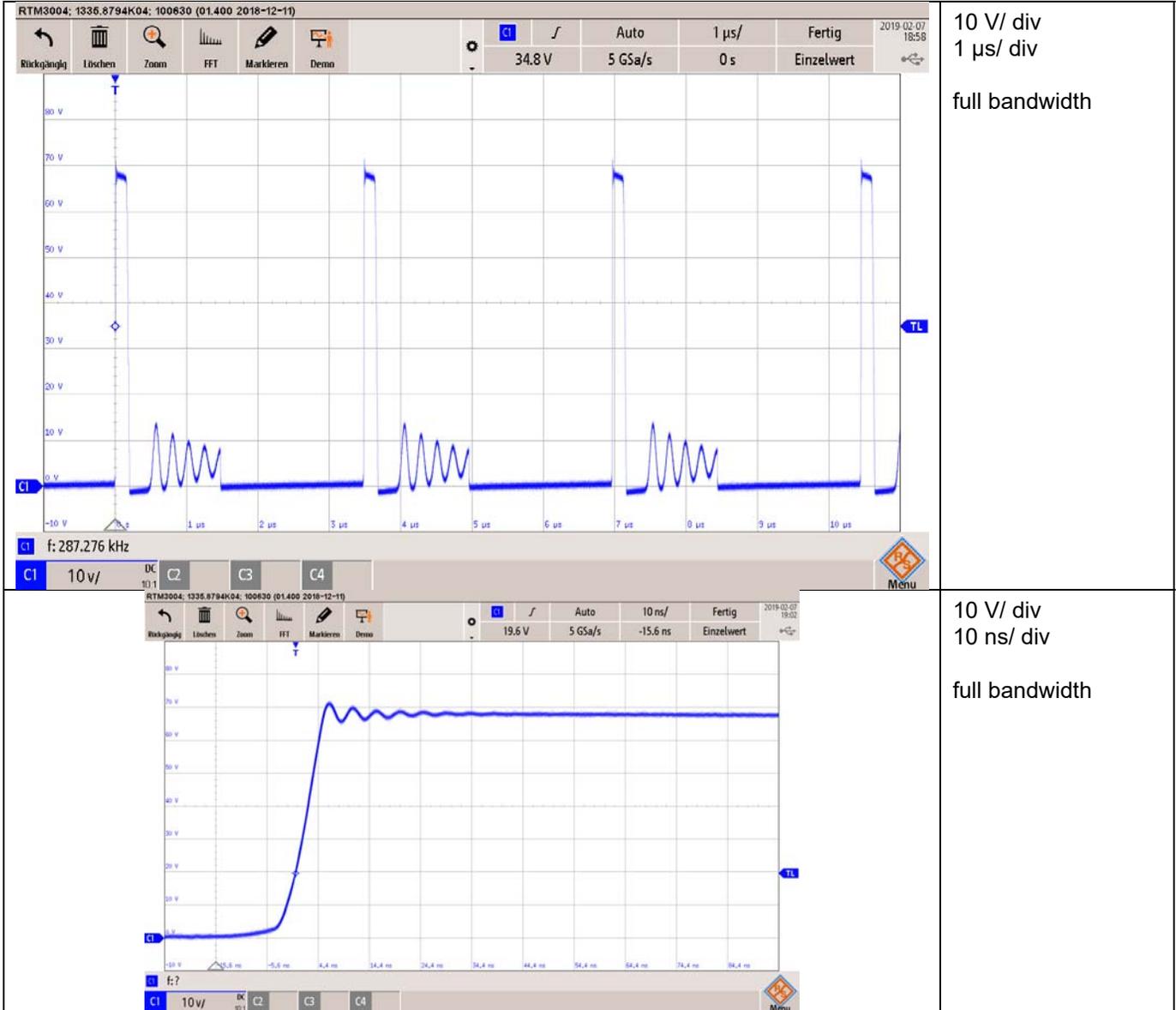


Figure 4 Switchnode (TP4)

### 3.1.2 Diode D1

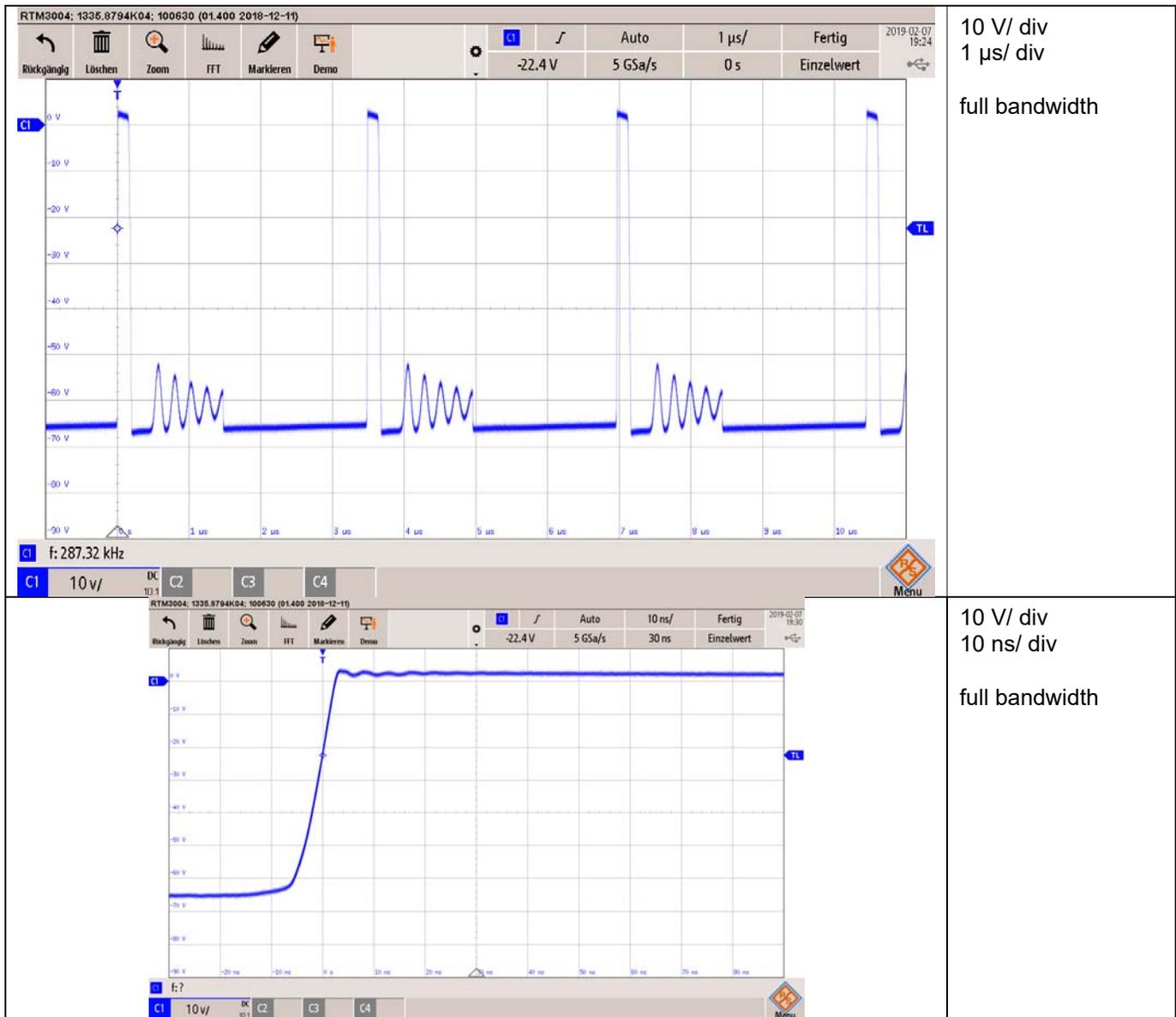


Figure 5 Diode D1

### 3.2 Output Voltage Ripple

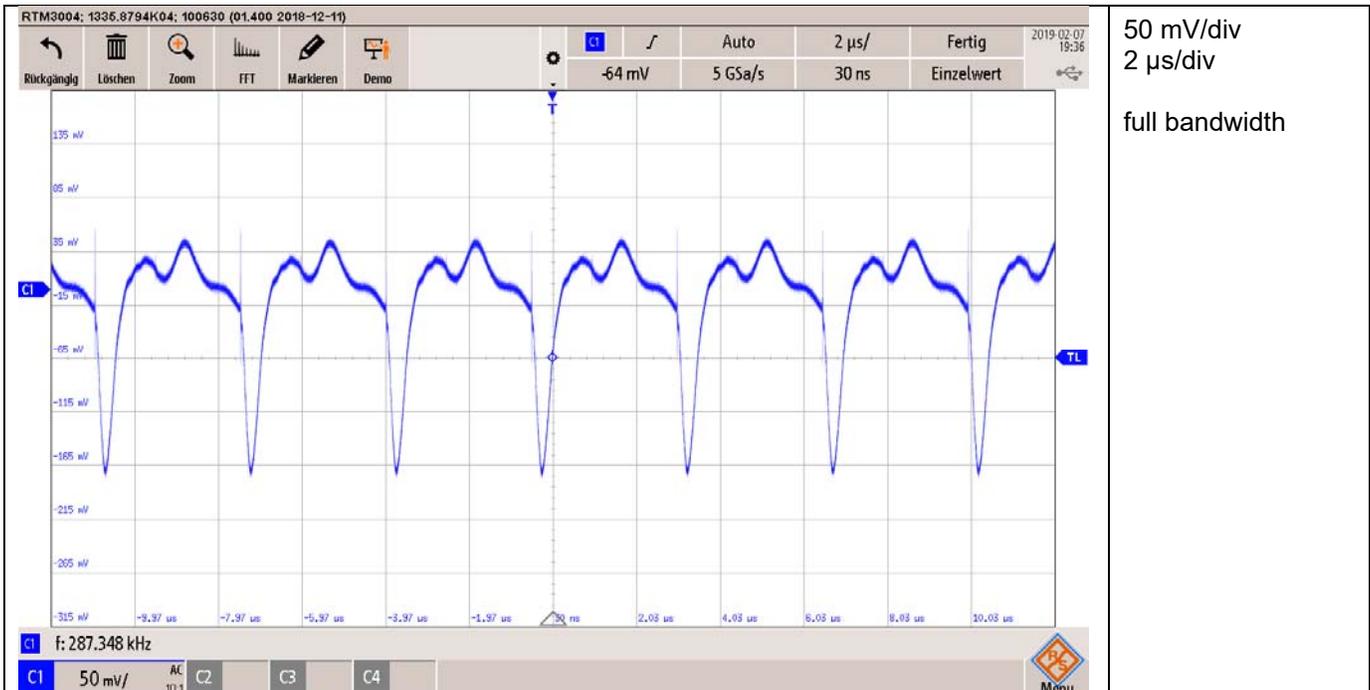


Figure 6 Output Voltage Ripple

### 3.3 Input Voltage Ripple

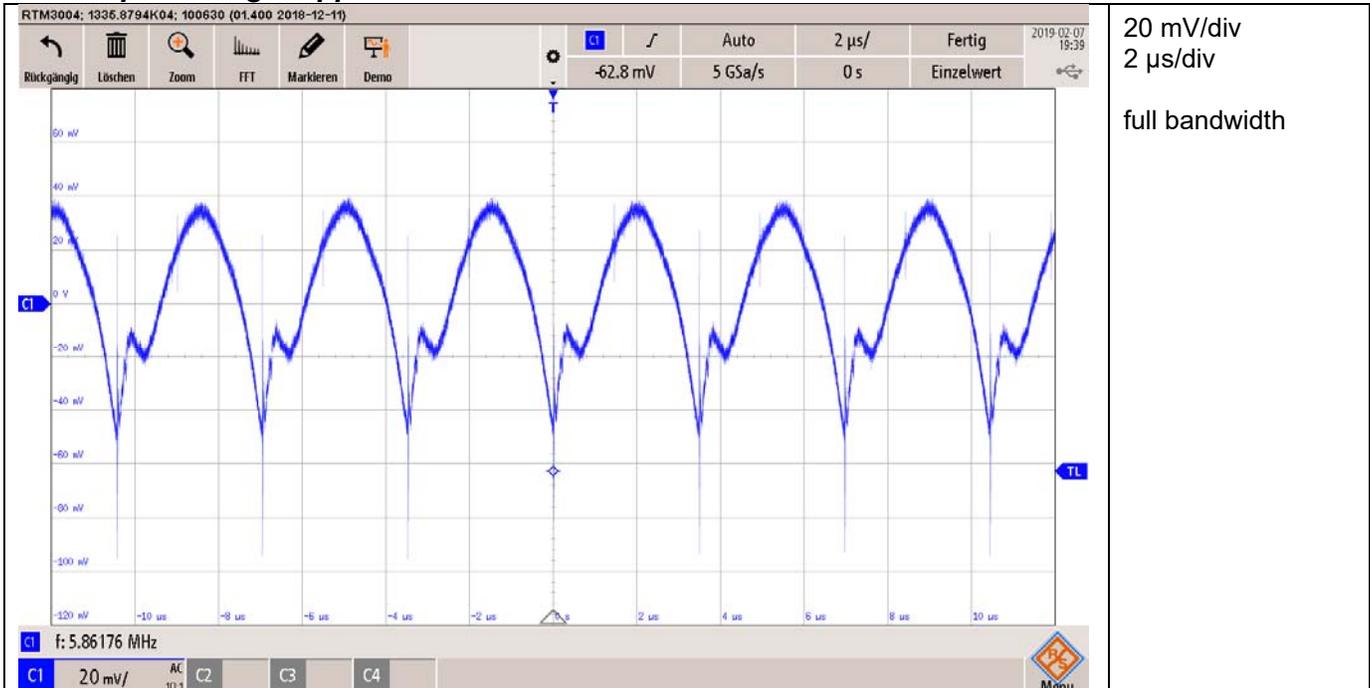


Figure 7 Input Voltage Ripple

### 3.4 Bode Plot

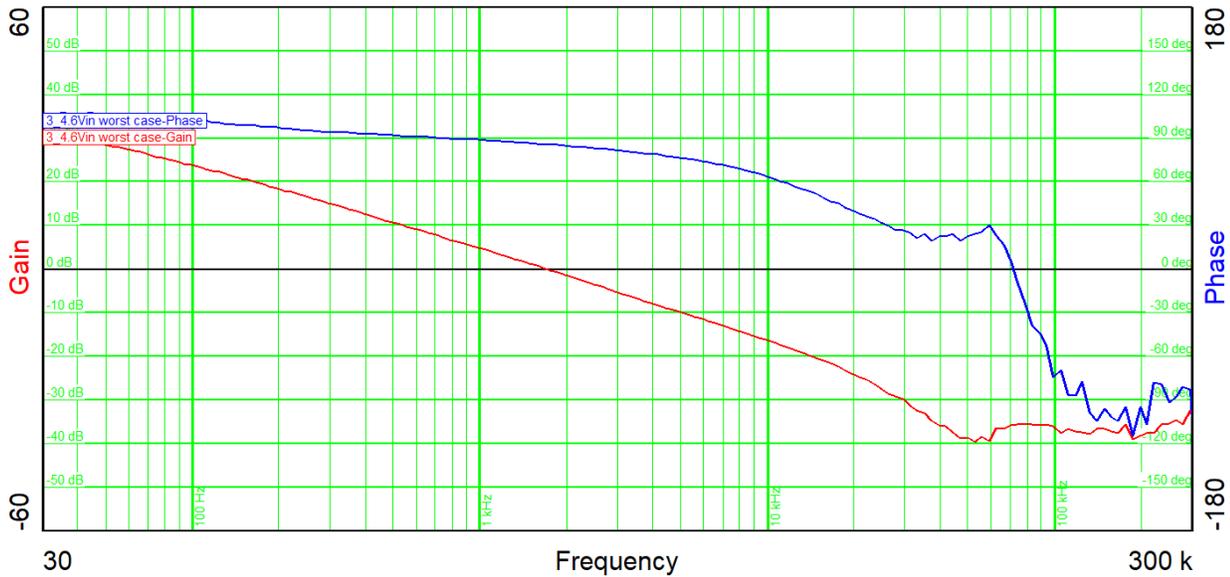


Figure 8 Bode Plot (4.5 V Input Voltage)

	4.5 Vin
Bandwidth (kHz)	1.7
Phasemargin	85.6°
slope (20dB/decade)	-1.0
gain margin (dB)	-36
slope (20dB/decade)	+0.25
freq (kHz)	72

Table 1 Bode Plot Values

### 3.5 Start-up Sequence

Power supply was plugged in.



Figure 9 Start-up Sequence

### 3.6 Shutdown Sequence

Power supply was disconnected.

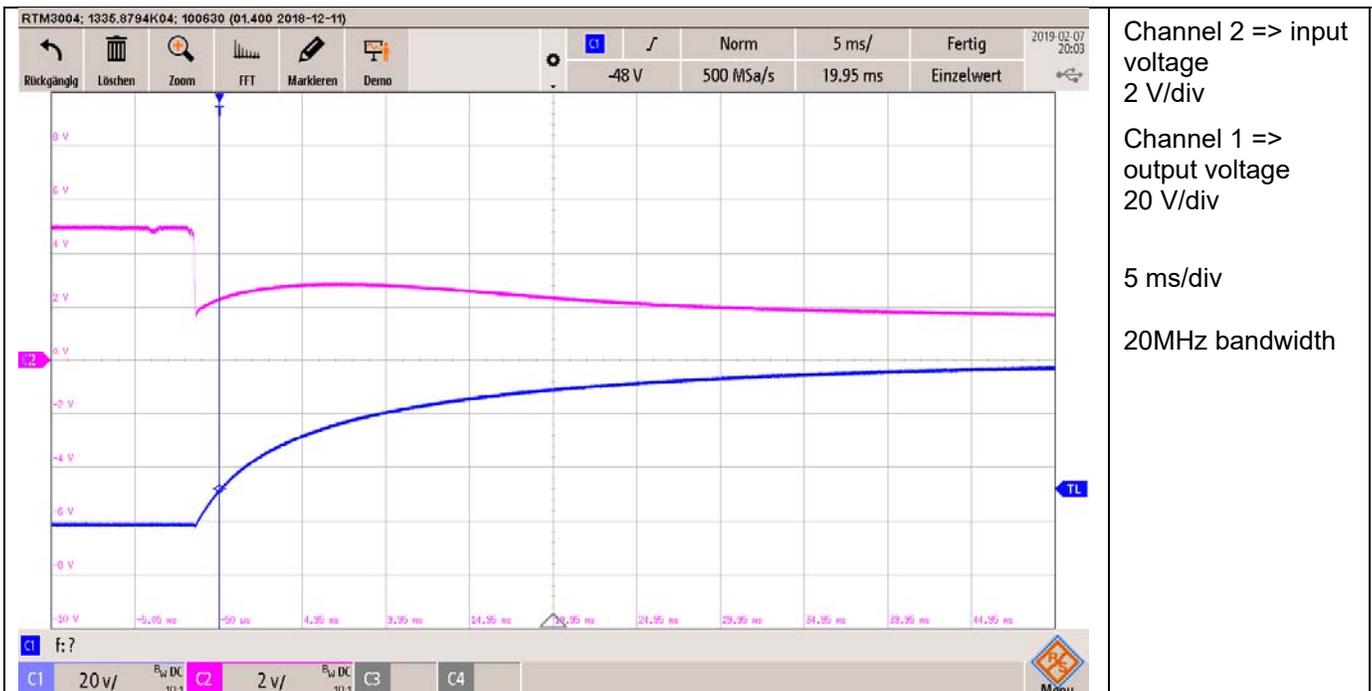


Figure 10 Shutdown Sequence

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