



# TRS3122E 1.8V低電力デュアルRS-232トランシーバ

## 1 特長

- 拡張されたV<sub>CC</sub>動作ノード: 1.8V、3.3V、5.0V
  - 独自のトリプラー・チャージ・ポンプ・アーキテクチャにより、1.8Vの低いV<sub>CC</sub>が可能になり、同時に3.3Vおよび5V電源との互換性も維持
- レベルシフト機能が統合されているため、外部電源や追加のレベル・シフタが不要になり、低電圧MCUとの接続も可能
- RIN入力とDOUT出力のESD保護機能を強化
  - ±15kV IEC 61000-4-2空中放電
  - ±8kV IEC 61000-4-2接触放電
  - ±15kV人体モデル
- データ転送速度1000kbpsを指定
- Auto Powerdown Plus機能
- シャットダウン時消費電流がわずか0.5μA
- RS-232インターフェイスの互換性要件に準拠またはそれ以上
- 2.5Vの単一電源アプリケーションには、最適化されたソリューションとしてTRS3318Eを検討してください

## 2 アプリケーション

- リモート無線ユニット(RRU)
- ベースバンド・ユニット(BBU)
- 電子POS (EPOS)
- 診断とデータ送信
- バッテリー駆動機器

## 3 概要

TRS3122Eは、2ドライバ、2レシーバのRS-232インターフェイス・デバイスで、多電圧動作に別々の電源ピンが搭載されています。すべてのRS-232入力および出力は、IEC 61000-4-2空中放電で±15kV、IEC 61000-4-2接触放電で±8kV、人体モデルで±15kVまで保護されます。

チャージ・ポンプは、1.8Vの低電圧電源で動作するために、5個の小型0.1μFコンデンサが必要です。TRS3122Eは1000kbpsまでのデータ転送速度で動作でき、RS-232互換の出力レベルを維持します。

TRS3122Eには独自のV<sub>L</sub>ピンが搭載されており、混合ロジック電圧システムで動作可能です。ドライバ入力(DIN)とレシーバ出力(ROUT)のロジック・レベルは、いずれもV<sub>L</sub>ピンによりプログラム可能です。このため、電圧レベル・シフタを追加する必要なく、低電圧のマイクロコントローラやUARTと接続できます。

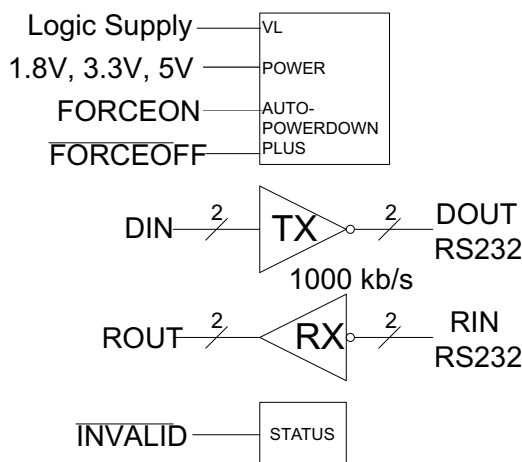
Auto Powerdown Plusにより、デバイスが30秒以上データの送受信を行わないと、自動的に低電力モードへ移行します。この機能により、バッテリー駆動のアプリケーションや、その他消費電力に制約のあるアプリケーションに最適です。

### 製品情報<sup>(1)</sup>

型番	パッケージ (ピン数)	本体サイズ(公称)
TRS3122ERGER	RGE (24)	4.00mm×4.00mm

(1) 提供されているすべてのパッケージについては、巻末の注文情報を参照してください。

### 機能図



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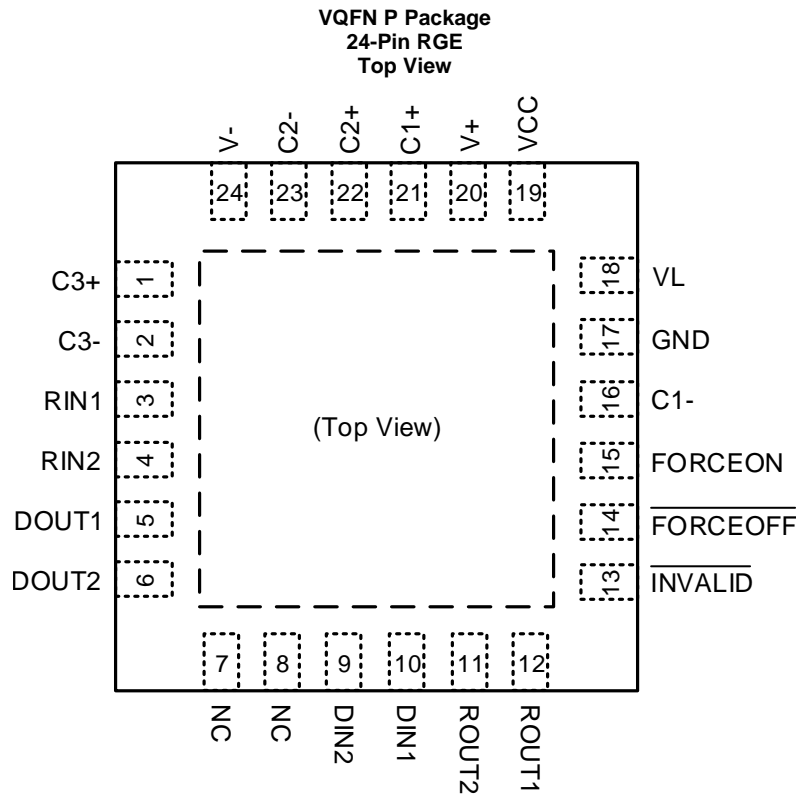
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## 4 改訂履歴

Revision B (May 2016) から Revision C に変更		Page
• 「特長」セクションの箇条書きを優先度順に並べ替え .....	1	1
• フロント・ページに画像を入れるため、フロント・ページの「アプリケーション」セクションから、データテーブルを削除 .....	1	1
• 説明文で入れ替わっていたESDレベルを正しく変更 .....	1	1
Revision A (May 2016) から Revision B に変更		Page
• Updated ESD ratings values to reflect current device specifications .....	4	4
• 追加 all Typical Characteristic graphs and schematics to the <i>Typical Characteristics</i> section .....	8	8
• 追加 Application Curve image to <i>Application Curves</i> section .....	18	18
2014年6月発行のものから更新		Page
• Added Pin Functions table. ....	3	3

## 5 Pin Configuration and Functions



**Pin Functions**

Pin		I/O	DESCRIPTION
NAME	NO.		
C1+, C2+	21, 22	-	Positive terminals of voltage-doubler charge-pump capacitors (required)
C3+	1	-	Positive terminal of voltage-tripler charge-pump capacitor (Not needed for VCC 3V to 5.5V)
C1-, C2-	16, 23	-	Negative terminals of voltage-doubler charge-pump capacitors (required)
C3-	2	-	Negative terminal of voltage-tripler charge-pump capacitor (Not needed for VCC 3V to 5.5V)
V+	20	-	Positive charge pump storage capacitor (required)
V-	24	-	Negative charge pump storage capacitor (required)
GND	17	-	Ground
V <sub>CC</sub>	19	-	1.8-V or 3-V to 5-V supply voltage
V <sub>L</sub>	18	-	Logic-level supply. All CMOS inputs (DIN) and outputs (ROUT) are referenced to this supply.
$\overline{\text{FORCEOFF}}$	14	I	Auto Powerdown Control input (Refer to Truth Table)
FORCEON	15	I	Auto Powerdown Control input (Refer to Truth Table)
$\overline{\text{INVALID}}$	13	O	Invalid Output Pin
DIN1, DIN2	10, 9	I	Driver inputs
DOUT1, DOUT2	5, 6	O	RS-232 driver outputs
RIN1, RIN2	3, 4	I	RS-232 receiver inputs
ROUT1, ROUT2	12, 11	O	Receiver outputs; swing between 0 and V <sub>L</sub>
NC	7, 8	I	Factory pins, can be unconnected or connected to GND

## 6 Specifications

### 6.1 Absolute Maximum Ratings<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
V <sub>CC</sub>	Charge pump power supply	–0.3	6	V
V <sub>L</sub>	Logic power supply	–0.3	6	V
V <sub>+</sub>	Positive storage capacitor voltage	–0.3	7	V
V <sub>–</sub>	Negative storage capacitor voltage	0.3	–7	V
V <sub>+</sub> +  V <sub>–</sub>   <sup>(2)</sup>			13	V
V <sub>I</sub>	FORCEOFF, FORCEON	–0.3	6	V
	DIN	–0.3	V <sub>L</sub> + 0.3	
	RIN (0Ω series resistance)		±20	
	RIN (≥250Ω series resistance)		±25	
V <sub>O</sub>	DOUT		±13.2	V
	ROUT	–0.3	V <sub>L</sub> + 0.3	
T <sub>J</sub>	Junction temperature		150	°C
T <sub>stg</sub>	Storage temperature range	–65	150	°C

- (1) Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.
- (2) V<sub>+</sub> and V<sub>–</sub> can have maximum magnitudes of 7 V, but their absolute difference cannot exceed 13 V.

### 6.2 ESD Ratings

				VALUE	UNIT	
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	All pins except RS-232 bus	±2000	V	
			RS-232 bus pins	±15000		
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins <sup>(2)</sup>	All pins	±500		
			IEC 61000-4-2 Air-Gap Discharge	RS-232 bus pins		±15000
			IEC 61000-4-2 Contact Discharge			±8000

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

				MIN	TYP	MAX	UNIT
V <sub>CC</sub>	Charge pump power supply	Tripler Mode		1.65	1.8	2	V
		Doubler Mode		3	3.3	3.6	
				4.5	5	5.5	
V <sub>L</sub>	Logic power supply			1.65	V <sub>CC</sub>		V
R <sub>IN</sub>	RS-232 Receiver interface			-15	15		V
D <sub>OUT</sub>	RS-232 Transmitter interface			-12	12		V
V <sub>IL</sub>	GPIO Input logic threshold low	DIN, $\overline{\text{FORCEOFF}}$ , FORCEON	V <sub>L</sub> = 5.0 V	0	1.7		V
			V <sub>L</sub> = 3.3V	0	1.1		
			V <sub>L</sub> = 1.8 V	0	0.6		
V <sub>IH</sub>	GPIO Input logic threshold high	DIN, $\overline{\text{FORCEOFF}}$ , FORCEON	V <sub>L</sub> = 5.0V	3.3	V <sub>L</sub>		V
			V <sub>L</sub> = 3.3V	2.2	V <sub>L</sub>		
			V <sub>L</sub> = 1.8V	1.2	V <sub>L</sub>		
V <sub>OZ</sub>	ROUT disabled		$\overline{\text{FORCEOFF}}$ = 0V	0	V <sub>L</sub>		V
Operating temperature				-40	85		°C

### 6.4 Thermal Characteristics

THERMAL METRIC		TRS3122E	UNIT
		RGE	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	34.2	°C/W
R <sub>θJCTop</sub>	Junction-to-case (top) thermal resistance	27.2	
R <sub>θJB</sub>	Junction-to-board thermal resistance	11.4	
ψ <sub>JT</sub>	Junction-to-top characterization parameter	0.4	
ψ <sub>JB</sub>	Junction-to-board characterization parameter	11.4	
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	3.6	

### 6.5 Power and Status Electrical Characteristics

V<sub>CC</sub> = V<sub>L</sub> = (1.65 V to 2.0 V) & (3.0V to 5.5V), T<sub>A</sub> = -40°C to 85°C (unless otherwise noted). Typical data is T<sub>A</sub> = 25°C, V<sub>CC</sub> = V<sub>L</sub> = 3.3V unless otherwise noted.

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
I <sub>CC</sub> (Static)		DIN1 = GND or V <sub>L</sub> ; DIN2 = GND or V <sub>L</sub> ; FORCEOFF = V <sub>L</sub> FORCEON = V <sub>L</sub>	No load	V <sub>CC</sub> = 1.65V to 2.0V	1.0	1.9	mA
				V <sub>CC</sub> = 3.0V to 3.6V	0.7	1.4	
				V <sub>CC</sub> = 4.5V to 5.5V	0.8	1.9	
I <sub>CC</sub> (off)		FORCEOFF = GND			0.4	10	μA
V <sub>IT+</sub>	RIN postive voltage threshold for INVALID output change	RIN1 = RIN2		0.3		2.4	V
V <sub>IT-</sub>	RIN negative voltage threshold for INVALID output change			-2.4		-0.3	
V <sub>OH</sub>	INVALID high-level output voltage	I <sub>OH</sub> = -1 mA, FORCEON = GND, FORCEOFF = V <sub>L</sub>		V <sub>L</sub> -0.4	V <sub>L</sub> -0.08	V <sub>L</sub>	V
V <sub>OL</sub>	INVALID low-level output voltage	I <sub>OL</sub> = 1.6 mA, FORCEON = GND, FORCEOFF = V <sub>L</sub>		0	0.06	0.4	V

## 6.6 Driver Electrical Characteristics

$V_{CC} = V_L = (1.65 \text{ V to } 2.0 \text{ V}) \text{ \& } (3.0 \text{ V to } 5.5 \text{ V})$ ,  $T_A = -40^\circ\text{C to } 85^\circ\text{C}$  (unless otherwise noted). Typical data is  $T_A = 25^\circ\text{C}$ ,  $V_{CC} = V_L = 3.3 \text{ V}$  unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{OUT}$ Output voltage swing	All driver outputs loaded with 3 k $\Omega$ to ground C3 = 100 nF, $V_{CC} = 1.8 \text{ V}$	$\pm 4.25$	$\pm 4.7$		V
	All driver outputs loaded with 3 k $\Omega$ to ground C3 = 0 F, $V_{CC} = 3.3 \text{ V}$ or 5 V	$\pm 5$	$\pm 5.4$		
$r_O$ Output resistance	( $V_{CC} = V_+ = V_- = 0$ ); Driver output = $\pm 2 \text{ V}$	300	10M		$\Omega$
$I_{OS}$ Output short-circuit current	$V_{DOUT} = 0$			$\pm 60$	mA
$I_{OZ}$ Output leakage current	$V_{DOUT} = \pm 12 \text{ V}$ , $\overline{\text{FORCEOFF}} = \text{GND}$	0		$\pm 25$	$\mu\text{A}$
Driver input hysteresis			0.5	1	V
Input leakage current	DIN = GND to $V_L$ ; $\overline{\text{FORCEOFF}} = \text{GND to } V_L$ ; $\text{FORCEON} = \text{GND to } V_L$		0	$\pm 5$	$\mu\text{A}$

## 6.7 Receiver Electrical Characteristics

$V_{CC} = V_L = (1.65 \text{ V to } 2.0 \text{ V}) \text{ \& } (3.0 \text{ V to } 5.5 \text{ V})$ ,  $T_A = -40^\circ\text{C to } 85^\circ\text{C}$  (unless otherwise noted). Typical data is  $T_A = 25^\circ\text{C}$ ,  $V_{CC} = V_L = 3.3 \text{ V}$  unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{off}$ Output leakage current	ROUT, receivers disabled		$\pm 0.01$	$\pm 10$	$\mu\text{A}$
$V_{OL}$ Output voltage low	$I_{OUT} = 2.0 \text{ mA}$		0.04	0.3	V
$V_{OH}$ Output voltage high	$I_{OUT} = -2.0 \text{ mA}$	$V_L - 0.3$	$V_L - 0.04$		V
$V_{IT-}$ Input threshold low	$T_A = 25^\circ\text{C}$	$V_L = 5 \text{ V}$	0.8	1.5	V
		$V_L = 3.3 \text{ V}$	0.7	1.1	
		$V_L = 1.8 \text{ V}$	0.6	0.7	
$V_{IT+}$ Input threshold high	$T_A = 25^\circ\text{C}$	$V_L = 5 \text{ V}$		2.0 2.4	V
		$V_L = 3.3 \text{ V}$		1.5 2.4	
		$V_L = 1.8 \text{ V}$		0.9 1.4	
$V_{hys}$ Input hysteresis	$T_A = 25^\circ\text{C}$	$V_L = 5 \text{ V}$		0.45	V
		$V_L = 3.3 \text{ V}$		0.35	
		$V_L = 1.8 \text{ V}$		0.26	
Input resistance	$T_A = -40 \text{ to } 85^\circ\text{C}$	3	5	7	k $\Omega$

## 6.8 Driver Switching Characteristics

$V_{CC} = V_L = (1.65 \text{ V to } 2.0 \text{ V}) \text{ \& } (3.0 \text{ V to } 5.5 \text{ V})$ ,  $T_A = -40^\circ\text{C to } 85^\circ\text{C}$  (unless otherwise noted). Typical data is  $T_A = 25^\circ\text{C}$ ,  $V_{CC} = V_L = 3.3 \text{ V}$  unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Maximum data rate	$R_L = 3 \text{ k}\Omega$ , $C_L = 500 \text{ pF}$ (one driver)	1000			kbps
	$R_L = 3 \text{ k}\Omega$ , $C_L = 1000 \text{ pF}$ (one driver)	500			
Time-to-exit powerdown	$ V_{DOUT}  > 3.7 \text{ V}$		30	150	$\mu\text{s}$
$ t_{PHL} - t_{PLH} $ Driver skew <sup>(1)</sup>	$R_L = 3 \text{ k}\Omega$	0	50	100	ns
Transition-region slew rate	$R_L = 3 \text{ k}\Omega \text{ to } 7 \text{ k}\Omega$ , $T_A = 25^\circ\text{C}$ Measured from 3 V to $-3 \text{ V}$ or $-3 \text{ V}$ to 3 V	$V_{CC} = 1.8 \text{ V}$ , $C_L = 200 \text{ pF}$	33		V/ $\mu\text{s}$
		$V_{CC} = 1.8 \text{ V}$ , $C_L = 1000 \text{ pF}$	25		
		$V_{CC} = 3.3 \text{ V}$ , $C_L = 200 \text{ pF}$	38		
		$V_{CC} = 3.3 \text{ V}$ , $C_L = 1000 \text{ pF}$	28		
		$V_{CC} = 5 \text{ V}$ , $C_L = 200 \text{ pF}$	41		
		$V_{CC} = 5 \text{ V}$ , $C_L = 1000 \text{ pF}$	30		

(1) Driver skew is measured at the driver zero crosspoint.

## 6.9 Receiver Switching Characteristics

$V_{CC} = V_L = (1.65\text{ V to }2.0\text{ V}) \text{ \& } (3.0\text{ V to }5.5\text{ V})$ ,  $T_A = -40^\circ\text{C to }85^\circ\text{C}$  (unless otherwise noted). Typical data is  $T_A = 25^\circ\text{C}$ ,  $V_{CC} = V_L = 3.3\text{ V}$  unless otherwise noted.

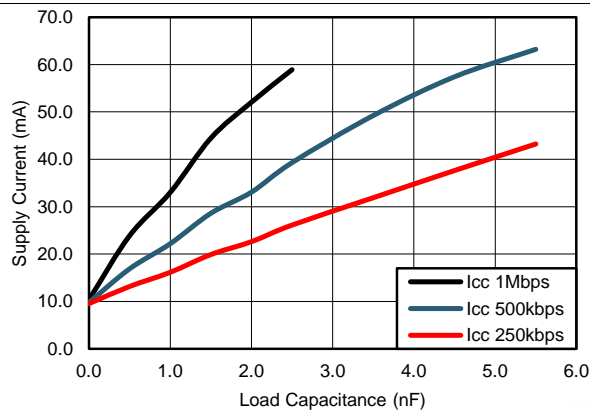
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{PHL}$	Receiver propagation delay, high to low	Receiver input to receiver output $C_L = 150\text{ pF}$		0.15	0.4	$\mu\text{s}$
$t_{PLH}$	Receiver propagation delay, low to high			0.15	0.4	
$t_{PHL} - t_{PLH}$	Receiver skew			50	300	ns
$t_{en}$	Receiver output enable time	From $\overline{\text{FORCEOFF}}$ to $R_{OUT} = V_L/2$ $C_L = 150\text{ pF}$ , $R_L = 3\text{ k}\Omega$		200	400	ns
$t_{dis}$	Receiver output disable time			200	400	ns

## 6.10 Power and Status Switching Characteristics

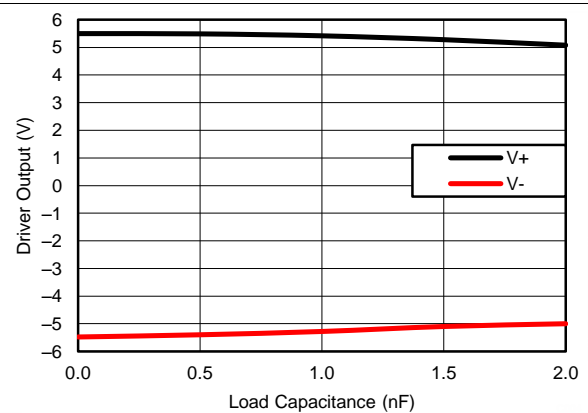
$V_{CC} = V_L = (1.65\text{ V to }2.0\text{ V}) \text{ \& } (3.0\text{ V to }5.5\text{ V})$ ,  $T_A = -40^\circ\text{C to }85^\circ\text{C}$  (unless otherwise noted). Typical data is  $T_A = 25^\circ\text{C}$ ,  $V_{CC} = V_L = 3.3\text{ V}$  unless otherwise noted.

PARAMETER		MIN	TYP	MAX	UNIT
$t_{valid}$	Propagation delay time, low- to high-level output		1		$\mu\text{s}$
$t_{invalid}$	Propagation delay time, high- to low-level output		30		$\mu\text{s}$
$t_{dis}$	Receiver or driver edge to auto-powerdown plus	15	30	60	s

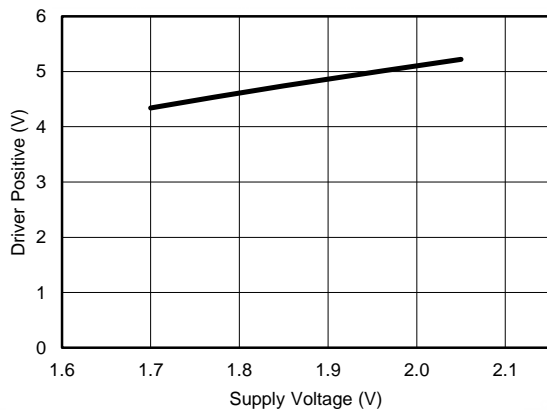
## 6.11 Typical Characteristics



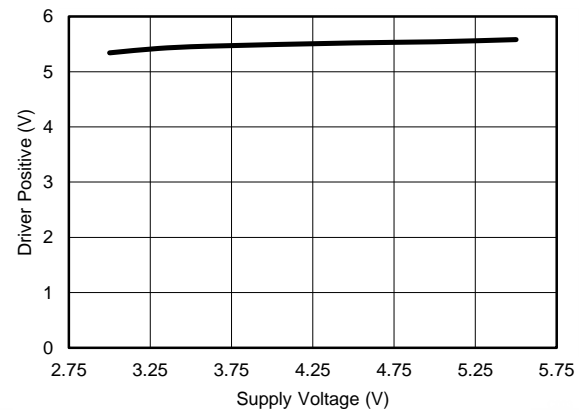
**FIG 1. Supply Current vs. Load Capacitance**  
 $V_{CC} = 3.3\text{ V}$ ,  $V_L = 1.8\text{ V}$ ,  $R_{LOAD} = 3\text{ k}\Omega$ ,  $CH2 = 32\text{ kbps}$



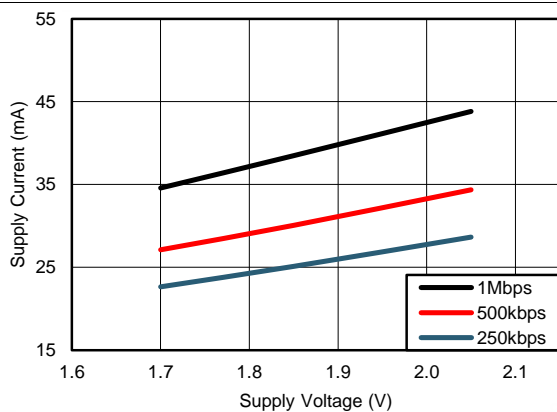
**FIG 2. Driver Output vs. Load Capacitance,  $V_{CC} = 3.3\text{ V}$**   
 $V_L = 1.8\text{ V}$ ,  $R_{LOAD} = 3\text{ k}\Omega$ ,  $CH1 = 1\text{ Mbps}$ ,  $CH2 = 32\text{ kbps}$



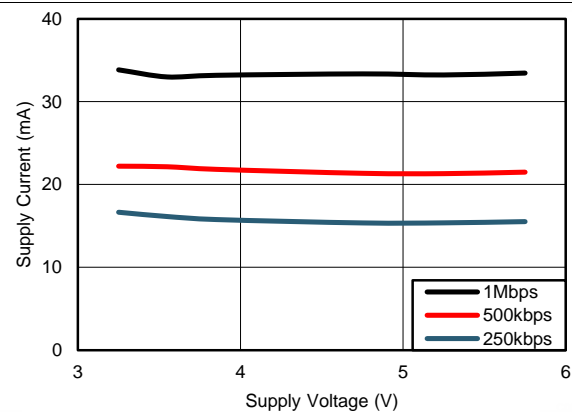
**FIG 3. Driver Positive vs. Supply Voltage (Tripler Mode)**  
 $1\text{ Mbps}$ ,  $R_{LOAD} = 3\text{ k}\Omega$ ,  $C_{LOAD} = 560\text{ pF}$



**FIG 4. Driver Positive vs. Supply Voltage (Doubler Mode)**  
 $1\text{ Mbps}$ ,  $R_{LOAD} = 3\text{ k}\Omega$ ,  $C_{LOAD} = 560\text{ pF}$



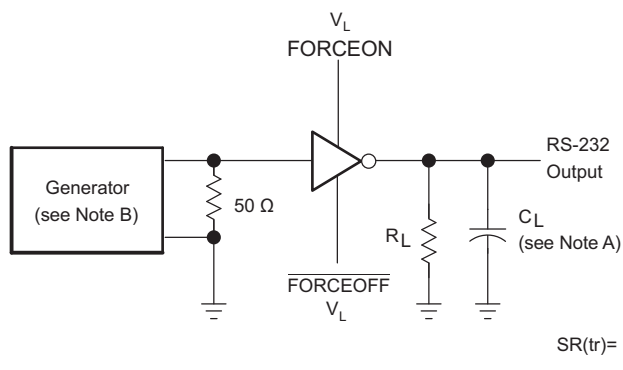
**FIG 5. Supply Current vs. Supply Voltage (Tripler Mode)**  
 $V_L = 1.8\text{ V}$ ,  $R_{LOAD} = 3\text{ k}\Omega$ ,  $C_{LOAD} = 1\text{ nF}$ ,  $CH2 = 32\text{ kbps}$



**FIG 6. Supply Current vs. Supply Voltage (Doubler Mode)**  
 $V_L = 1.8\text{ V}$ ,  $R_{LOAD} = 3\text{ k}\Omega$ ,  $C_{LOAD} = 1\text{ nF}$ ,  $CH2 = 32\text{ kbps}$

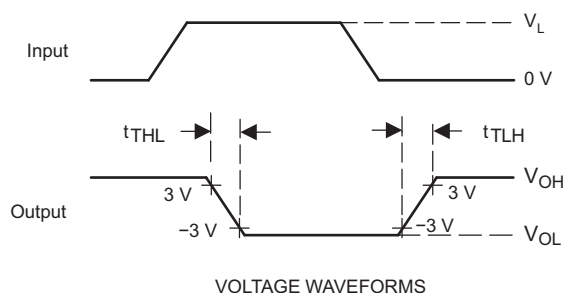


## 7 Parameter Measurement Information

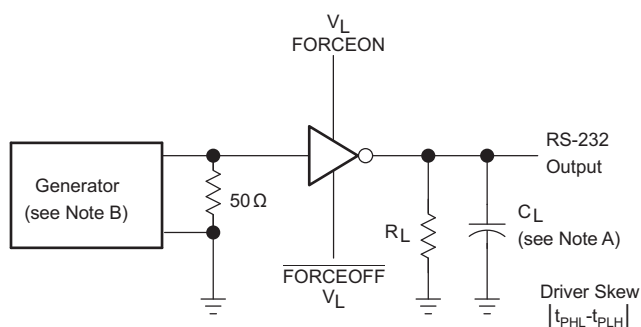


TEST CIRCUIT

- A.  $C_L$  includes probe and jig capacitance.
- B. The pulse generator has the following characteristics: PRR = 1000 kbit/s,  $Z_O = 50\ \Omega$ , 50% duty cycle,  $t_r \leq 10\text{ ns}$ ,  $t_f \leq 10\text{ ns}$ .

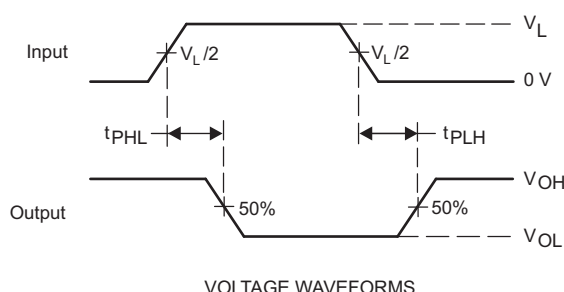


### 7. Driver Slew Rate

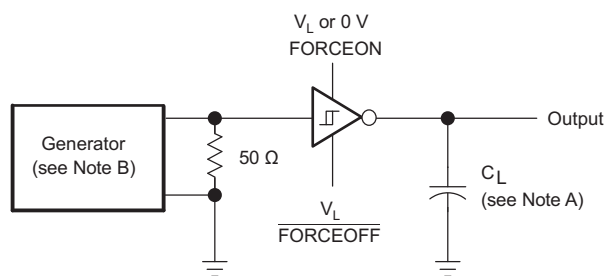


TEST CIRCUIT

- A.  $C_L$  includes probe and jig capacitance.
- B. The pulse generator has the following characteristics: PRR = 1000 kbit/s,  $Z_O = 50\ \Omega$ , 50% duty cycle,  $t_r \leq 10\text{ ns}$ ,  $t_f \leq 10\text{ ns}$ .

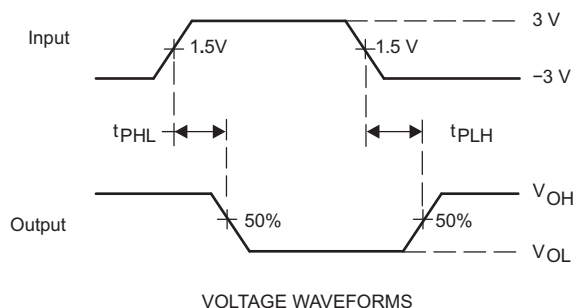


### 8. Driver Pulse Skew



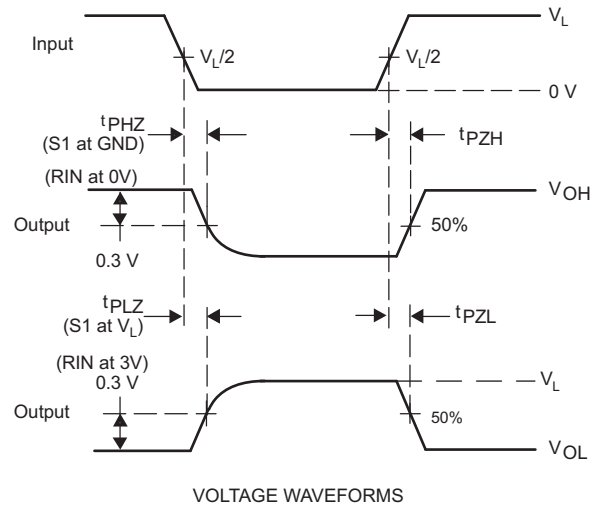
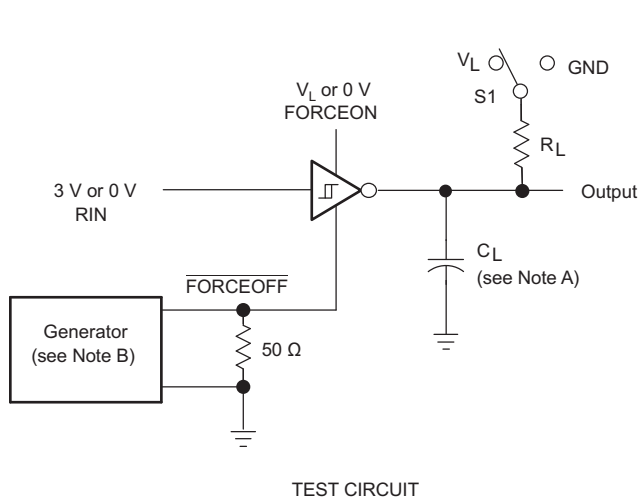
TEST CIRCUIT

- A.  $C_L$  includes probe and jig capacitance.
- B. The pulse generator has the following characteristics:  $Z_O = 50\ \Omega$ , 50% duty cycle,  $t_r \leq 10\text{ ns}$ ,  $t_f \leq 10\text{ ns}$ .



### 9. Receiver Propagation Delay Times

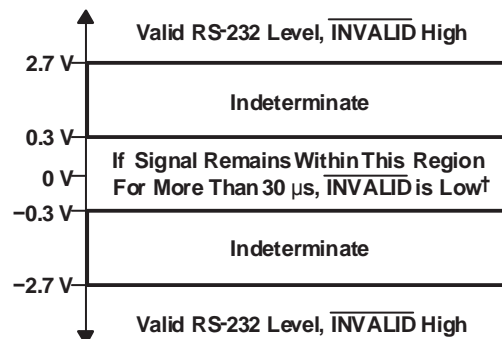
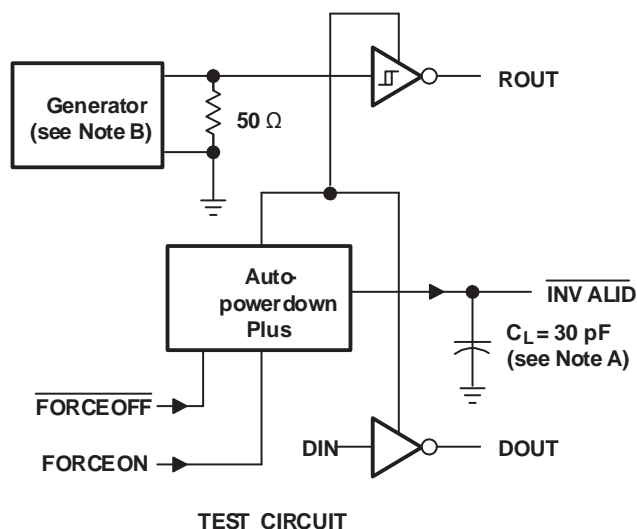
## Parameter Measurement Information (continued)



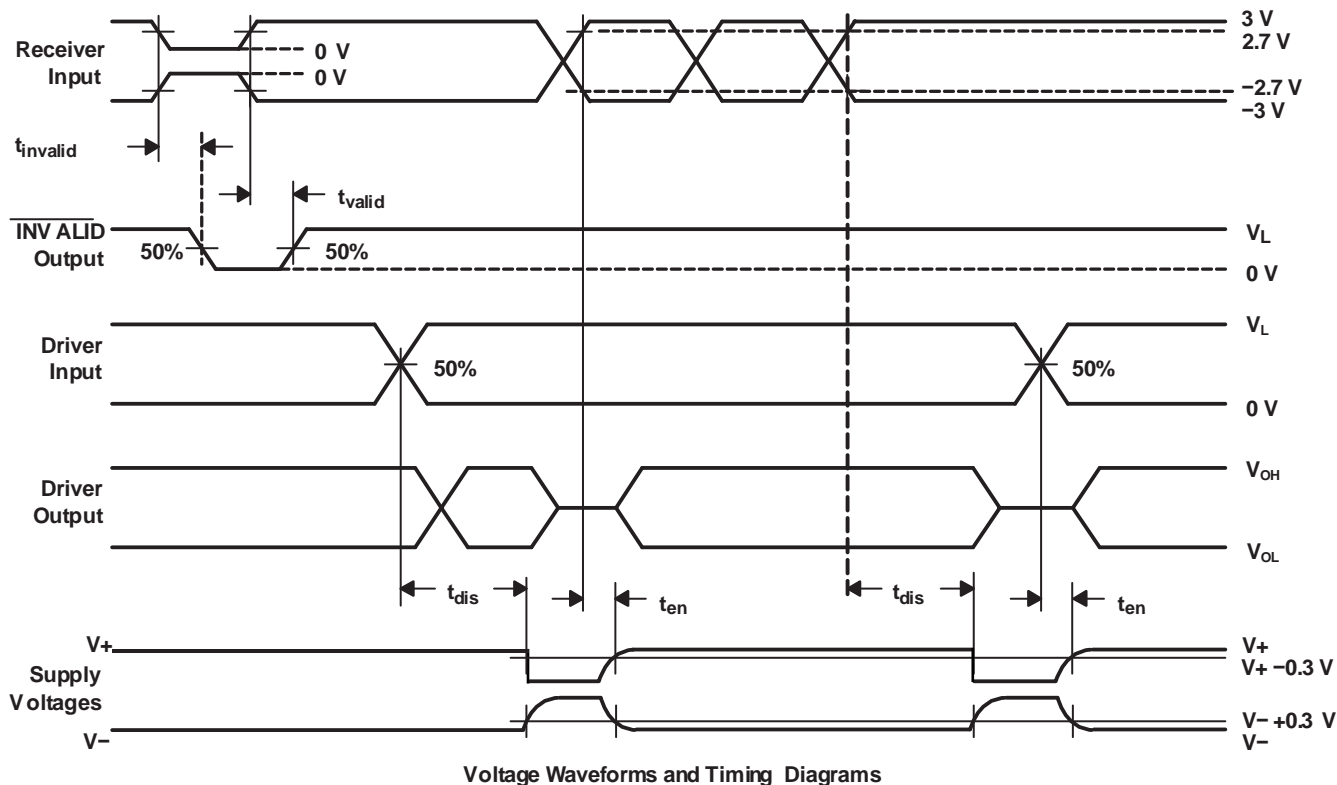
- A.  $C_L$  includes probe and jig capacitance.
- B. The pulse generator has the following characteristics:  $Z_O = 50\ \Omega$ , 50% duty cycle,  $t_r \leq 10\text{ ns}$ ,  $t_f \leq 10\text{ ns}$ .
- C.  $t_{PLZ}$  and  $t_{PHZ}$  are the same as  $t_{dis}$ .
- D.  $t_{PZL}$  and  $t_{PZH}$  are the same as  $t_{en}$ .

### 10. Receiver Enable and Disable Times

# Parameter Measurement Information (continued)



<sup>†</sup> Auto-powerdown plus disables drivers and reduces supply current to 1  $\mu\text{A}$ .



✎ 11.  $\overline{\text{INVALID}}$  Propagation-Delay Times and Supply-Enabling Time

## 8 Detailed Description

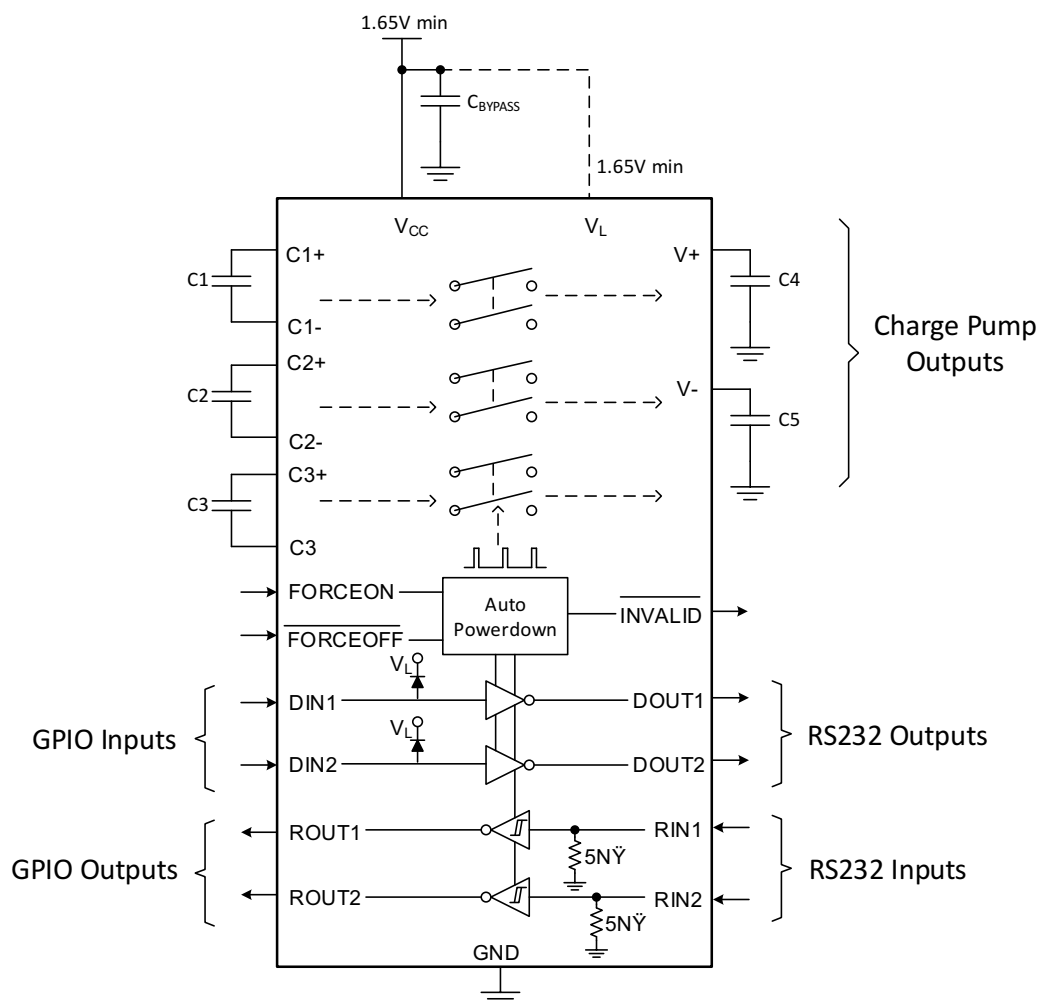
### 8.1 Overview

The TRS3122E is an upgrade to standard RS232 transceivers, offering compatibility with modern system needs like 1.8-V GPIO capability, enhanced ESD & ultra low stand-by current. The majority of RS-232 transceivers with 1.8-V GPIO compatibility require a logic supply pin for the I/O translation, in addition to a minimum 3.3 V  $V_{CC}$  for all of the other active circuitry on the chip. Unlike these transceivers, TRS3122E can operate with both  $V_L$  and  $V_{CC}$  equal to 1.8 V. When  $V_{CC}$  = 3.0 V to 5.5 V, the charge pump will sense  $V_{CC}$  and switch to doubler mode. C1 & C2 are the necessary flying capacitors, C3 is not needed, and the charge pump outputs V+ & V- will regulate to  $\sim\pm 5.4$  V. When  $V_{CC}$  = 1.65 V to 2.0 V, the charge pump will sense  $V_{CC}$  and switch to tripler mode. C1, C2 & C3 are all necessary, and the charge pump outputs V+ & V- will regulate to  $\sim\pm 2.65 \cdot V_{CC}$  from  $V_{CC}$  = 1.65 V to 2.0 V.

With many modern applications expanding into products that use RS232 as a backup communication protocol, it is important for the transceiver to have efficient standby operation. In order to accommodate this, Auto Powerdown Plus has been integrated to shut-off all active circuitry, allowing TRS3122E to achieve an  $I_{off}$  of 1  $\mu$ A.

In order to comply with common interface system needs and environments, the RS-232 receive and transmit I/O pins comply with IEC 61000-4-2 ratings.

### 8.2 Functional Block Diagram



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**图 12. Schematic**

## 8.3 Feature Description

### 8.3.1 Charge Pump

The internal power supply consists of a regulated auto-sensing charge pump that provides RS-232 compatible output voltages, over the 1.65 V to 2.0 V and 3.0 V to 5.5 V  $V_{CC}$  ranges. The charge pump operates in two modes to efficiently accommodate low voltage (1.8 V) and higher voltage (3.3 V & 5.0 V) supplies.

#### 8.3.1.1 Doubler Mode

The charge pump requires two flying capacitors (C1, C2) and reservoir capacitors (C4, C5) to generate the  $V_+$  and  $V_-$  supplies of approximately  $\pm 5.4$  V when  $V_{CC}$  is greater than 3 V. When  $V_{CC}$  is  $>2.9$  V, TRS3122E will sense the supply voltage level and switch the charge pump to a doubler. Hence, no need for a third flying capacitor. C3+ & C3- pins can be left open for proper operation. If a capacitor is placed between C3+ & C3-, the charge pump will ignore this capacitor and still behave as a doubler.

For capacitor choice recommendations, please refer to [表 1](#).

#### 8.3.1.2 Tripler Mode

The charge pump requires three flying capacitors (C1, C2 & C3) and reservoir capacitors (C4, C5) to generate the  $V_+$  and  $V_-$  supplies of approximately  $\pm 2.65 * V_{CC}$  when  $V_{CC}$  is greater than 1.65 V. When  $V_{CC}$  is  $<2.1$  V, TRS3122E will sense the supply voltage level and switch the charge pump to a tripler.

For capacitor choice recommendations, please refer to [表 1](#).

### 8.3.2 Drivers

The drivers are inverting level transmitters that convert TTL or CMOS logic levels to RS-232 levels. For  $V_{CC}=3.0$  V to 5.0 V, the RS-232 output voltage swing is typically  $\pm 5.4$  V fully loaded and  $\pm 5$  V minimum fully loaded. For  $V_{CC} = 1.8$  V, the RS-232 output voltage swing is typically  $\pm 4.7$  V fully loaded and  $\pm 4.25$  V minimum fully loaded.

The driver outputs are protected against indefinite short-circuits to ground without degradation in reliability. These drivers are compatible with RS-232 logic levels and all previous RS-232 versions. Unused driver inputs should be connected to GND or VCC.

### 8.3.3 Receivers

The receivers convert EIA/TIA-232 levels to TTL or CMOS logic output levels. Receivers have an inverting output that can be disabled by using the FORCEOFF pin. Receivers remain active when the Auto Powerdown Plus circuitry autonomously enters a low power state. See [Auto Powerdown Plus](#) for more information on the Auto Powerdown mode. If the FORCEOFF pin is manually set low, the receivers will be disabled and put into 3-state mode. In either of these powerdown modes, the device will typically consume about 0.5  $\mu$ A. The truth table logic of the TRS3122E driver and receiver outputs can be found in [Device Functional Modes](#). Since receiver input is usually from a transmission line where long cable lengths and system interference can degrade the signal, the inputs have a typical hysteresis margin of 300 mV. This ensures that the receiver is virtually immune to noisy transmission lines. Should an input be left unconnected, an internal 5k $\Omega$  pull-down resistor to ground will commit the output of the receiver to a HIGH state.

### 8.3.4 ESD Protection

ESD protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The bus pins (driver outputs and receiver inputs) have extra protection structures, which have been tested up to  $\pm 15$  kV.

ESD protection is tested in various ways. TI uses the following standards to qualify the ESD structures designed into TRS3122E:

- $\pm 8$  kV using IEC 61000-4-2 Contact Discharge (on RINx and DOUTx pins)
- $\pm 15$  kV using IEC 61000-4-2 Airgap Discharge (on RINx and DOUTx pins)
- $\pm 15$  kV using the Human Body Model (HBM) (on RINx and DOUTx pins)
- $\pm 2$  kV using the Human Body Model (HBM) (on all pins except RINx and DOUTx pins)
- $\pm 0.5$  kV using the Charged Device Model (CDM) (on all pins)

## Feature Description (continued)

The IEC 61000-4-2 standard is more rigorous than HBM, resulting in lower voltage levels compared with HBM for the same level of ESD protection. Because IEC 61000-4-2 specifies a lower series resistance, the peak current is higher than HBM. The TRS3122E has passed both HBM and IEC 61000-4-2 testing.

### 8.3.5 Auto Powerdown Plus

Powerdown is engaged in two separate cases: automatically, when no activity has occurred for a period of time, and manually, using the  $\overline{\text{FORCEOFF}}$  device pin.

#### 8.3.5.1 Automatic Powerdown

Auto Powerdown Plus is enabled when FORCEON is set LOW and  $\overline{\text{FORCEOFF}}$  is set HIGH. Using TRS3122E's integrated edge detection circuitry and timer, the device can sense when there is no activity on the driver or receiver inputs for 30 seconds. When this condition is sensed by the device, it automatically shuts the charge pump off, reducing supply current to 0.5 uA. When a valid transition is sensed on one of the driver or receiver inputs, the charge pump turns back on and TRS3122E exits powerdown. The typical time to exit powerdown is typically in 30 us, but can be as long as 150 us. As a result, the system saves power without requiring any software control. [Device Functional Modes](#) summarizes the operating modes in truth table form.

While in the low power mode with Automatic Powerdown enabled ( $\overline{\text{FORCEOFF}}$  = HIGH and FORCEON = LOW), the receiver inputs are still enabled.

#### 8.3.5.2 Manual Powerdown

The device can be manually powered down by externally setting  $\overline{\text{FORCEOFF}}$  pin to low logic level. Both the drivers and receivers will be powered off. [Device Functional Modes](#) summarizes the operating modes in truth table form.

#### 8.3.5.3 Forced On

If the  $\overline{\text{FORCEOFF}}$  and FORCEON pins are both set HIGH, the device will power on with Auto Powerdown Plus disabled. Both the drivers and receiver will be active regardless of inactivity. Because powerdown is autonomous, FORCEON can be used ensure drivers are ready for new data transmission if the time since last transmission (or receive data) was more than 15 seconds. [Device Functional Modes](#) summarizes the operating modes in truth table form.

## 8.4 Device Functional Modes

### 8.4.1 Each Driver<sup>(1)</sup>

INPUTS				OUTPUT	DRIVER STATUS
DIN	FORCEON	$\overline{\text{FORCEOFF}}$	TIME ELAPSED SINCE LAST RIN OR DIN TRANSITION	DOUT	
X	X	L	X	Z	Powered off
L	H	H	X	H	Normal operation with auto-powerdown plus disabled
H	H	H	X	L	
L	L	H	<30 s	H	Normal operation with auto-powerdown plus enabled
H	L	H	<30 s	L	
L	L	H	>30 s	Z	Powered off by auto-powerdown plus feature
H	L	H	>30 s	Z	

(1) H = high level, L = low level, X = irrelevant, Z = high impedance (off), 30s is typical inactivity time

### 8.4.2 Each Receiver<sup>(1)</sup>

INPUTS			OUTPUTS	RECEIVER STATUS
RIN	$\overline{\text{FORCEOFF}}$	TIME ELAPSED SINCE LAST RIN OR DIN TRANSITION	ROUT	
X	L	X	Z	Powered off
L	H	X	H	Normal operation with auto-powerdown plus disabled/enabled
H	H	X	L	
Open	H	X	H	

(1) H = high level, L = low level, X = irrelevant, Z = high impedance (off), Open = input disconnected or connected driver off

### 8.4.3 $\overline{\text{INVALID}}$ Status Truth Table<sup>(1)</sup>

INPUTS				OUTPUT
RIN1, RIN2	FORCEON	$\overline{\text{FORCEOFF}}$	TIME ELAPSED SINCE LAST RIN OR DIN TRANSITION	$\overline{\text{INVALID}}$
Any L or H	X	X	X	H
All Open	X	X	X	L

(1) H = high level, L = low level, X = irrelevant, Z = high impedance (off), Open = input disconnected or connected driver off

### 8.4.4 Capacitor Selection Table

表 1. Capacitor Selection

$V_{CC} = V_L$	C1 Capacitor Value	C2 Capacitor Value	C3 Capacitor Value	C4 Capacitor Value	C5 Capacitor Value
1.65 V to 2 V <sup>(1)</sup>	100 nF				
3.0 V to 3.6 V <sup>(1)</sup>	100 nF		100 nF or open	100 nF	
4.5 V to 5.5 V <sup>(1)</sup>	47 nF	330 nF	100 nF or open	330 nF	
3 V to 5.5 V <sup>(2)</sup>	47 nF	470 nF	100 nF or open	470 nF	

(1) For optimized performance, we recommend using these configurations.

(2) For applications where the Vcc variation is larger, this configuration is acceptable.

## 9 Application and Implementation

### 注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 9.1 Application Information

RS232 is used to communicate between two electrical units on separate PCBs across cables <40 ft. Common RS232 cables are RJ45, DB9 & DB25.

### 9.2 Typical 1.8-V Application

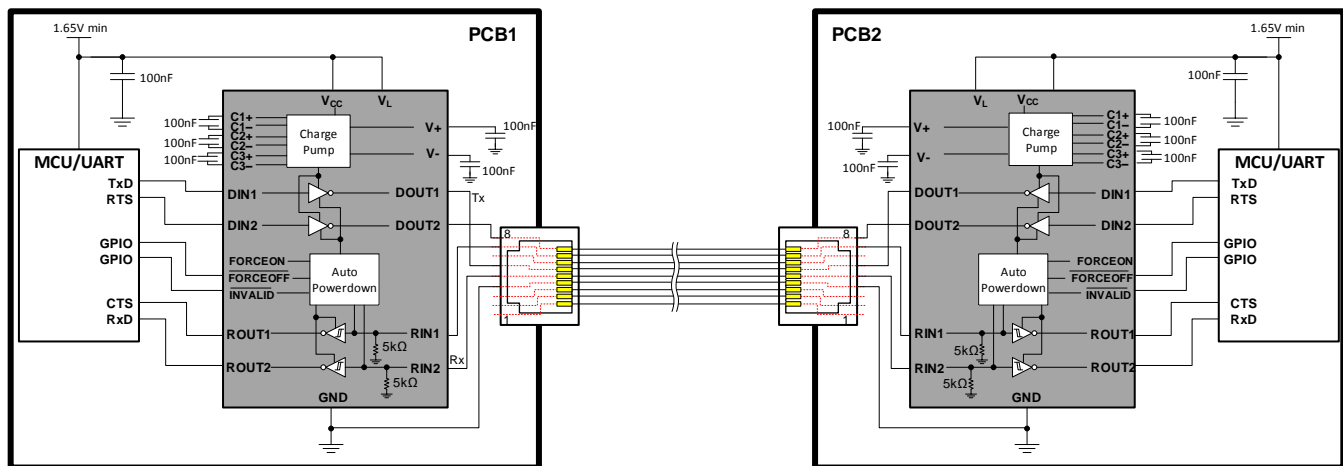


图 13. TRS3122E Typical Application

#### 9.2.1 Design Requirements

For this design example, use the parameters listed in 表 2 as the input parameters.

表 2. Design Parameters

DESIGN PARAMETER	EXAMPLE VALUE
MCU GPIO Supply Voltage	1.8 V
Transmission Voltage	+/-4.7 V
Data-rate	1 Mbps
Number of Transmitters / Receivers	2
Charge Pump Capacitor Values	100nF (see 表 3)

#### 9.2.2 Detailed Design Procedure

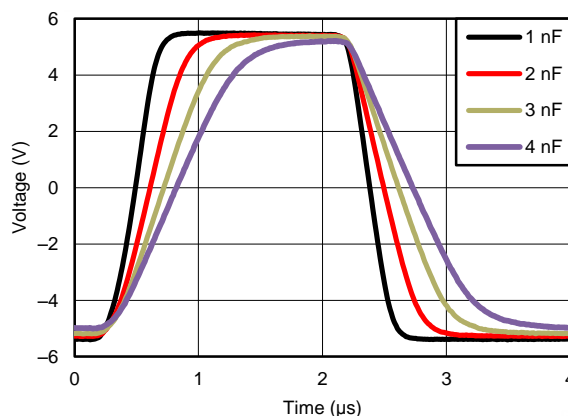
When using TRS3122E, determine the following:

- All DIN, FORCEOFF, and FORCEON inputs must be connected to valid low or high logic levels.
- Select capacitor values based on  $V_{CC}$  level for best performance. (see 表 3)



### 9.2.2.1 Data-Rate and Cable Length

RS-232 intended is for short range data transmission. The rise time for RS-232 driver edges is slow enough that the data cable appears as a capacitor instead of a transmission line impedance. The elapsed time for one bit of data far exceeds the transit time of any practical RS-232 cable length. The capacitance of the cable is the limiting factor. Therefore the capacitance per foot (or meter) of the cable is important if long data cables are used. Capacitance slows the rise and fall time of the signal. For low data rates, the delay is insignificant. However, high data rates will have reduced percentage of time that the output is at  $V_{OL}$  or  $V_{OH}$  and more time in the transitions. The timing of the UART (universal asynchronous receiver/transmitter) must sample the signal at the right time to coincide with  $V_{OL}$  and  $V_{OH}$  plateaus. At some point data reliability will be impacted. There are no hard limits for cable capacitance and data rate.



**图 14. Typical Waveform with Capacitive Load**  
 $V_{CC} = 3.3\text{ V}$ ,  $R_{LOAD} = 3\text{ k}\Omega$ , Data Rate = 500kbps

The maximum cable length depends on the cable used (pf/ft), data rate, timing of receiving UART, system tolerance to data errors.

### 9.2.2.2 Capacitor Selection

The capacitor type used for C1–C5 is not critical for proper operation; polarized or non-polarized capacitors can be used, though lower ESR capacitors are preferred. The charge pump requires 0.1  $\mu\text{F}$  capacitors for  $V_{CC} = 1.8\text{ V}$  or  $V_{CC} = 3.3\text{ V}$  operation. For other supply voltages, see 表 1 for required capacitor values. Do not use values smaller than those listed in 表 1. Increasing the capacitor values(e.g., by a factor of 2), except for C1, reduces ripple on the transmitter outputs and slightly reduces power consumption. C2, C3, C4 and C5 can be increased without changing C1's value. However, do not increase C1 without also increasing the values of C2, C3, C4, C5,  $C_{BYPASS1}$ , and  $C_{BYPASS2}$  to maintain the proper ratios (C1 to the other capacitors). When using the minimum required capacitor values, make sure the capacitor value does not degrade excessively with temperature. If in doubt, use capacitors with a larger nominal value. The capacitor's equivalent series resistance (ESR) usually increases at low temperatures.

For best charge pump efficiency locate the charge pump and bypass capacitors as close as possible to the IC. Surface mount capacitors are best for this purpose. Using capacitors with lower equivalent series resistance (ESR) and self-inductance, along with minimizing parasitic PCB trace inductance will optimize charge pump operation. Designers are also advised to consider that capacitor values may shift over time and operating temperature.

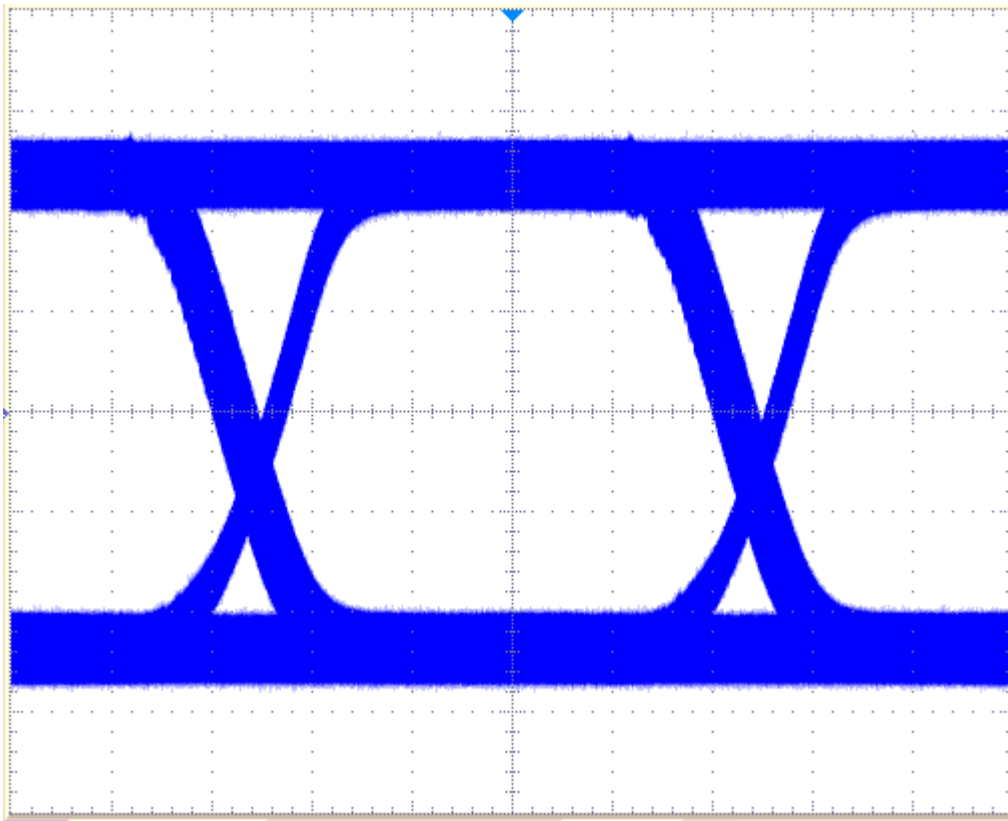
**表 3. Capacitor Selection**

$V_{CC} = V_L$	C1 Capacitor Value	C2 Capacitor Value	C3 Capacitor Value	C4 Capacitor Value	C5 Capacitor Value
1.65 V to 2 V <sup>(1)</sup>	100 nF				
3.0 V to 3.6 V <sup>(1)</sup>	100 nF		100 nF or open	100 nF	
4.5 V to 5.5 V <sup>(1)</sup>	47 nF	330 nF	100 nF or open	330 nF	
3 V to 5.5 V <sup>(2)</sup>	47 nF	470 nF	100 nF or open	470 nF	

(1) For optimized performance, we recommend using these configurations.

(2) For applications where the  $V_{CC}$  variation is larger, this configuration is acceptable.

### 9.2.3 Application Curves



15. 1 Mbps Eye Diagram, 2 V/div, 200 ns/ div  
 $V_{CC} = 1.8\text{ V}$ ,  $C_{LOAD} = 500\text{ pF}$ ,  $R_{LOAD} = 3\text{ k}\Omega$

## 10 Power Supply Recommendations

In most circumstances, a  $0.1\text{-}\mu\text{F}$   $V_{CC}$  bypass capacitor and a  $1\text{-}\mu\text{F}$   $V_L$  bypass capacitor are adequate. In applications that are sensitive to power-supply noise, use larger value  $V_{CC}$  bypass capacitor. There is no maximum limit for bypass capacitor. Place bypass capacitors as close to the IC as possible.

It is not recommended to use this device when  $V_{CC}$  is powered and  $V_L = 0\text{ V}$  or floating for an extended period of time because operation is undefined.  $V_{CC}$  and  $V_L$  must be powered to guarantee charge pump operation.

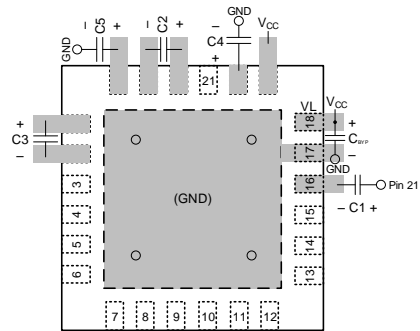
Also, to achieve full functionality as described in [Specifications](#), it is recommended to not use a higher voltage on  $V_L$  than  $V_{CC}$ . Full functionality can be achieved when  $V_{CC}$  is greater than or equal to  $V_L$ .

## 11 Layout

### 11.1 Layout Guidelines

Minimize the length of all capacitor traces to ensure the device can maintain quick rising and falling transitions. Vias are recommended to accommodate layouts for the capacitors.

### 11.2 Layout Example



✎ 16. TRS3122E Typical Layout

## 12 デバイスおよびドキュメントのサポート

### 12.1 デバイス・サポート

#### 12.1.1 デベロッパー・ネットワークの製品に関する免責事項

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**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

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### 12.5 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 13 メカニカル、パッケージ、および注文情報

以降のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。これらの情報は、指定のデバイスに対して提供されている最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もあります。本データシートのブラウザ版を使用されている場合は、画面左側の説明をご覧ください。

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">TRS3122ERGER</a>	Active	Production	VQFN (RGE)   24	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TRS3122
TRS3122ERGER.A	Active	Production	VQFN (RGE)   24	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TRS3122
TRS3122ERGERG4	Active	Production	VQFN (RGE)   24	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TRS3122
TRS3122ERGERG4.A	Active	Production	VQFN (RGE)   24	3000   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TRS3122
<a href="#">TRS3122ERGET</a>	Active	Production	VQFN (RGE)   24	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TRS3122
TRS3122ERGET.A	Active	Production	VQFN (RGE)   24	250   SMALL T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	TRS3122

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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**RGE 24**

**GENERIC PACKAGE VIEW**

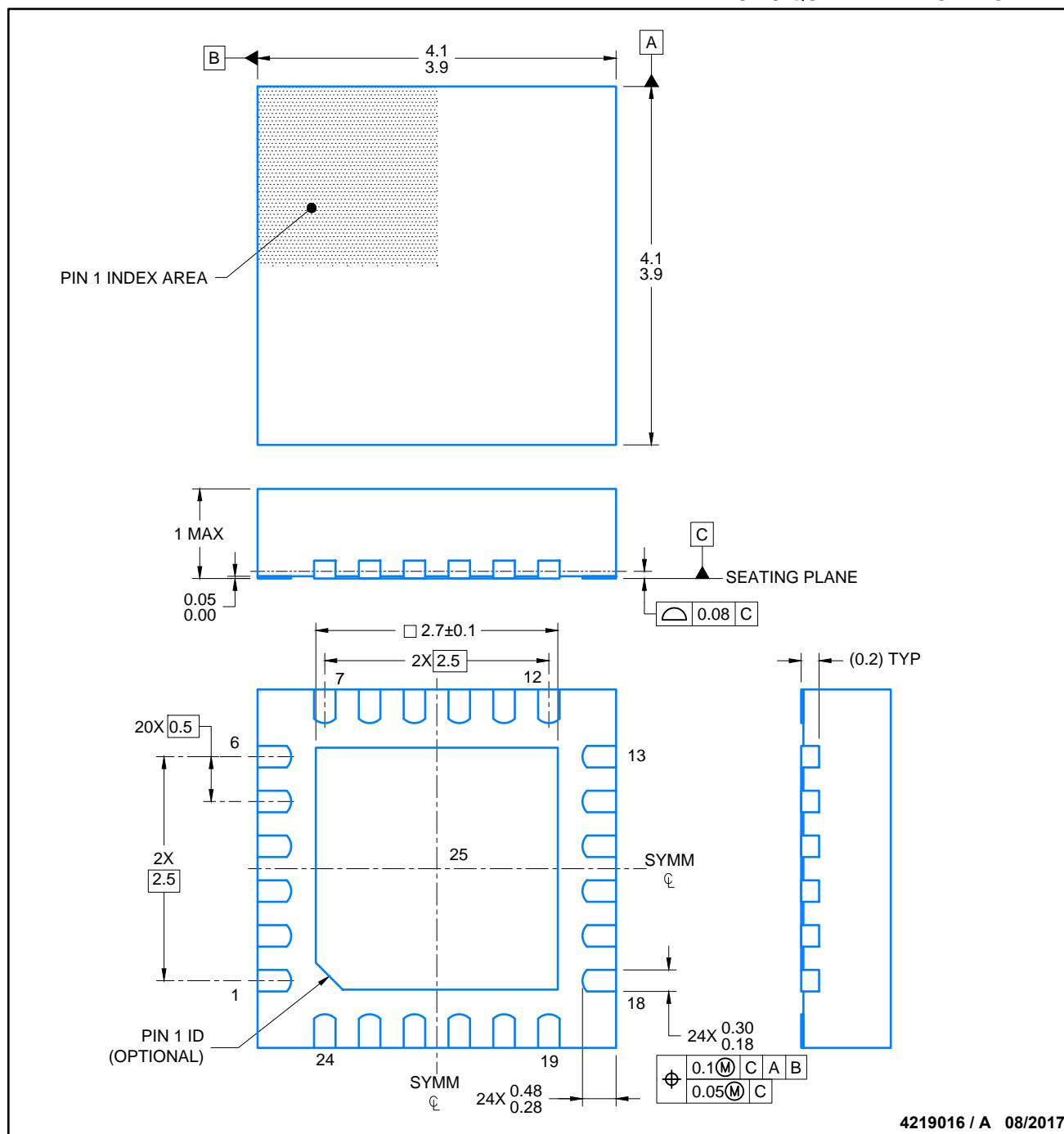
**VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

4204104/H



## NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



### VQFN - 1 mm max height

[illegible]

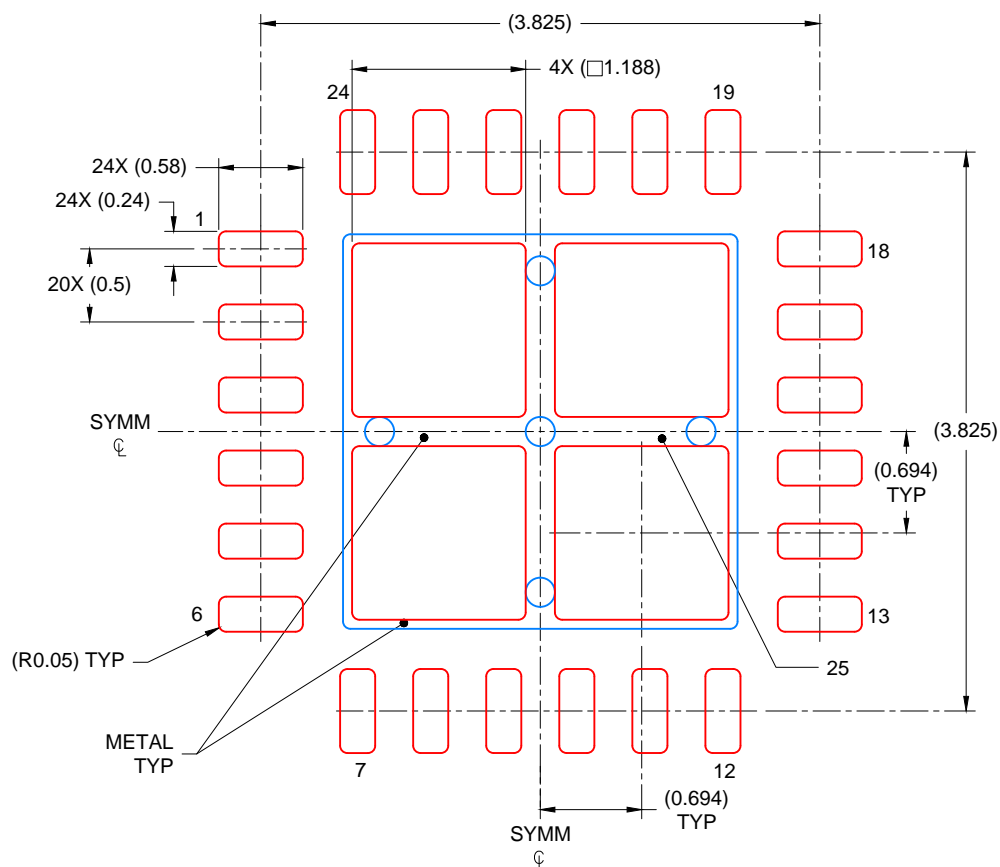
The diagram illustrates two methods for defining a solder mask opening on a metal pad:

- NON SOLDER MASK DEFINED (PREFERRED):** This method shows a metal pad (blue outline) with a solder mask opening (red outline). The dimension is specified as **0.07 MAX ALL AROUND**, indicating the maximum clearance between the metal and the solder mask.
- SOLDER MASK DEFINED:** This method shows a metal pad (blue outline) with a solder mask opening (red outline). The dimension is specified as **0.07 MIN ALL AROUND**, indicating the minimum clearance between the metal and the solder mask.

**SOLDER MASK DETAILS**



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SOLDER PASTE EXAMPLE  
 BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD  
 78% PRINTED COVERAGE BY AREA  
 SCALE: 20X

4219016 / A 08/2017

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations..

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