

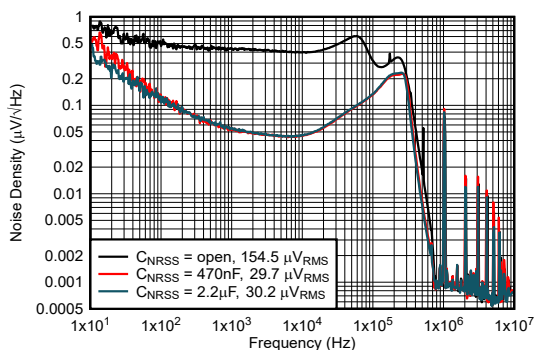
TPS6291x 3V~17V、4.5A/6A/8A、低ノイズ、低リップルの降圧コンバータ、フェライトビーズフィルタ補償機能内蔵

1 特長

- 小さい出力 $1/f$ ノイズ: $20\mu\text{V}_{\text{RMS}}$ 未満 (100Hz~100kHz)
- 小さい出力電圧リップル: $10\mu\text{V}_{\text{RMS}}$ 未満 (フェライトビーズの後)
- 優れた PSRR: 65dB 超 (最大 100kHz)
- 2.2MHz、1.4MHz、または 1.0MHz の固定周波数ピーク電流モード制御
- 外部クロックと同期可能 (オプション)
- 2 段目 L-C フィルタとしてフェライトビーズ (オプション) を使用できる内蔵ループ補償機能 (30dB 減衰)
- スペクトラム拡散変調 (オプション)
- 入力電圧範囲: 3.0V~17V
- 出力電圧範囲: 0.8V~5.5V
- $25\text{m}\Omega/7\text{m}\Omega$ の R_{DSon}
- $\pm 1\%$ の出力電圧精度 (全温度範囲)
- 高精度のイネーブル入力により以下を実現
 - ユーザー定義の低電圧誤動作防止機能
 - 正確なシーケンシング
- 可変ソフトスタート
- パワー グッド出力
- 出力放電 (オプション)
- -40°C ~ 150°C の接合部温度範囲
- 2.0mm × 3.0mm QFN、0.5mm ピッチ
- **WEBENCH® Power Designer** により、TPS6291x を使用するカスタム設計を作成

2 アプリケーション

- 通信インフラ
- 試験および測定機器
- 航空宇宙および防衛 (レーダー、航空電子機器)
- 医療用



出力ノイズと周波数との関係

3 概要

TPS6291x デバイスは、高効率、低ノイズ、低リップルの電流モード同期整流降圧コンバータのファミリーです。これらのデバイスは、通常はポストレギュレーションに LDO を使用するような、ノイズの影響を受けやすいアプリケーション (たとえば、高速 ADC、クロックおよびジッタ クリーナ、シリアルライザ、デシリアルライザ、レーダー) 向けに設計されています。

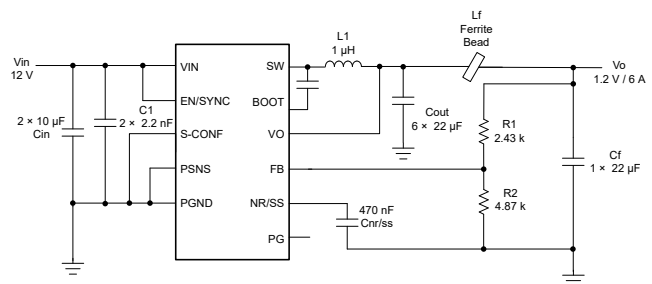
出力電圧リップルを低減するため、本デバイスのループ補償は、オプションの 2 段目フェライトビーズ L-C フィルタを使用して動作するように設計されています。NR/SS ピンに接続されたコンデンサで内部基準電圧をフィルタ処理することで、低ノイズ LDO と同様の低い周波数ノイズレベルをさらに達成しています。これらの機能を組み合わせることで、出力電圧リップルを $10\mu\text{V}_{\text{RMS}}$ 未満に抑えることができます。

本デバイスは 2.2MHz、1.4MHz または 1MHz の固定スイッチング周波数で動作し、外部クロックにも同期できます。オプションのスペクトラム拡散変調方式を使用すると、DC/DC スwitchング周波数をより広い範囲にわたって拡散できるため、ミキシング スプリアスを低減できます。

製品情報

型番	出力電流	パッケージ ⁽¹⁾	パッケージ サイズ ⁽²⁾
TPS62916	6A	RPY (VQFN-HR, 14)	2.5mm × 3.0mm
TPS62914	4.5A		
TPS62918	8A		

- (1) 詳細については、**セクション 10** を参照してください。
- (2) パッケージ サイズ (長さ × 幅) は公称値であり、該当する場合はピンも含まれます。



代表的なアプリケーション



Table of Contents

1 特長	1	7 Application and Implementation	17
2 アプリケーション	1	7.1 Application Information.....	17
3 概要	1	7.2 Typical Applications.....	17
4 Pin Configuration and Functions	3	7.3 Power Supply Recommendations.....	26
5 Specifications	4	7.4 Layout.....	26
5.1 Absolute Maximum Ratings.....	4	8 Device and Documentation Support	29
5.2 ESD Ratings.....	4	8.1 Device Support.....	29
5.3 Recommended Operating Conditions.....	4	8.2 Documentation Support.....	29
5.4 Thermal Information.....	5	8.3 ドキュメントの更新通知を受け取る方法.....	29
5.5 Electrical Characteristics.....	5	8.4 サポート・リソース.....	29
5.6 Typical Characteristics.....	7	8.5 Trademarks.....	29
6 Detailed Description	10	8.6 静電気放電に関する注意事項.....	30
6.1 Overview.....	10	8.7 用語集.....	30
6.2 Functional Block Diagram.....	11	9 Revision History	30
6.3 Feature Description.....	12	10 Mechanical, Packaging, and Orderable Information	30
6.4 Device Functional Modes.....	15		

4 Pin Configuration and Functions

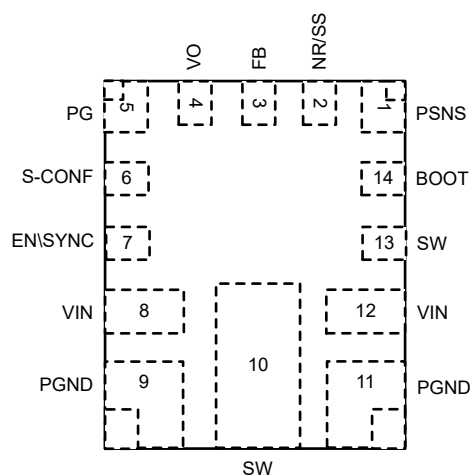


図 4-1. 14-Pin VQFN-HR, RPY Package (Top View)

表 4-1. Pin Functions

PIN		TYPE (1)	DESCRIPTION
NO.	NAME		
2	NR/SS	O	A capacitor connected to this pin sets the soft-start time and low frequency noise level of the device.
4	VO	I	Output voltage sense pin. This pin must be connected directly after the first inductor.
8, 12	VIN	I	Power supply input voltage pin
9, 11	PGND	—	Power ground connection
10	SW	O	Switch pin of the power stage. Connect this pin to the start winding of the output inductor .
13	SW	O	Switch pin. Connect a capacitor from this pin to the BOOT pin.
7	EN/SYNC	I	Enable, Disable pin including threshold-comparator. Connect to logic low to disable the device. Pull high to enable the device. This pin has an internal pulldown resistor of typically 500 kΩ when the device is disabled. Apply a clock to this pin to synchronize the device
14	BOOT	I	Supply for the internal high-side MOSFET gate driver. Connect a capacitor from this pin to SW.
1	PSNS	—	Power sense ground, connect directly to GND plane
3	FB	O	Feedback pin of the device
5	PG	O	Open-drain power-good output. This pin is pulled to GND when V_{OUT} is below the power-good threshold. this pin requires a pullup resistor to output a logic high. This pin can be left open or tied to GND if not used.
6	S-CONF	O	Smart Configuration pin. This pin configures the operation modes of the device. See 表 6-1.

(1) I = input, O = output

5 Specifications

5.1 Absolute Maximum Ratings

over operating junction temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
Voltage ⁽²⁾	VIN, EN/SYNC, PG, S-CONF	−0.3	18	V
	SW (DC)	−0.3	V _{IN} + 0.3	V
	SW (AC, less than 10 ns) ⁽³⁾	−2.5	21	V
	BOOT	−0.3	V _{IN} + 6	
	BOOT to SW	−0.3	6	
	VO, FB, NR/SS	−0.3	6	V
	VSNS−	−0.3	0.3	V
Sink Current	PG		10	mA
T _J	Junction temperature	−40	150	°C
T _{stg}	Storage temperature	−65	150	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.
- (2) All voltage values are with respect to the network ground terminal.
- (3) While switching.

5.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾	±2000	V
		Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002, all pins ⁽²⁾	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

5.3 Recommended Operating Conditions

over operating junction temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V _{IN}	Input voltage	3.0		17	V
V _{OUT}	Output voltage	0.8		5.5	V
C _{IN}	Effective input capacitance	5	10		μF
L ₁	Effective output inductance	−30%	1	20%	μH
C _{OUT}	Effective output capacitance	80	120	200	μF
L _f	Effective filter inductance	0	10	50	nH
C _f	Effective filter capacitance	20	40	160	μF
C _{OUT} + C _f	Effective total output capacitance, including first and second L-C filter	80		400	μF
I _{OUT}	Output current for TPS62914	0		4.5	A
I _{OUT}	Output current for TPS62916	0		6	A
I _{OUT}	Output current for TPS62918	0		8	A
f _{SYNC}	Synchronization Range (2.2 MHz setting)	1.9	2.2	2.4	MHz
f _{SYNC}	Synchronization Range (1.4 MHz setting)	1.2	1.4	1.6	MHz
f _{SYNC}	Synchronization Range (1.0 MHz setting)	0.8	1.0	1.2	MHz

5.3 Recommended Operating Conditions (続き)

over operating junction temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
T_J ⁽¹⁾	Junction temperature	–40		150	°C

(1) Operating lifetime is derated at junction temperatures above 125°C.

5.4 Thermal Information

THERMAL METRIC ⁽¹⁾		TPS6291 x		UNIT
		RPY 14-pin QFN		
		JEDEC 51-7 PCB	TPS6291 xEVM	
R _{θJA}	Junction-to-ambient thermal resistance	58.9	29.1	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	37.8	n/a ⁽²⁾	°C/W
R _{θJB}	Junction-to-board thermal resistance	7.3	n/a ⁽²⁾	°C/W
Ψ _{JT}	Junction-to-top characterization parameter	0.9	1.8	°C/W
Y _{JB}	Junction-to-board characterization parameter	7.2	13.4	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application note.

(2) Not applicable to an EVM.

5.5 Electrical Characteristics

Over recommended input voltage range, $T_J = -40^{\circ}\text{C}$ to 150°C . Typical values are at $V_{IN} = 12\text{ V}$ and $T_J = 25^{\circ}\text{C}$ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY						
I_Q	Quiescent current	EN = High, no load, device switching, fsw = 1 MHz		5		mA
I_{SD}	Shutdown current	EN = GND, $T_J = -40^{\circ}\text{C}$ to 125°C		0.3	70	μA
V_{UVLO}	Undervoltage lockout	V_{IN} rising, $T_J = -40^{\circ}\text{C}$ to 125°C	2.85	2.92	3.0	V
V_{HYS}	Undervoltage lockout hysteresis			200		mV
T_{JSD}	Thermal shutdown threshold	T_J rising		170		°C
	Thermal shutdown hysteresis	T_J falling		20		°C
CONTROL and INTERFACE						
V_{H_EN}	High-level input-threshold voltage at EN/ SYNC		0.97	1.01	1.04	V
V_{L_EN}	Low-level input-threshold voltage at EN/ SYNC		0.87	0.9	0.93	V
V_{H_SYNC}	High-level input-threshold clock signal on EN/ SYNC	EN/ SYNC = clock	1.1			V
V_{L_SYNC}	Low-level input-threshold clock signal on EN/ SYNC	EN/ SYNC = clock			0.4	V
$I_{EN,LKG}$	Input leakage current into EN/ SYNC	EN/ SYNC = GND or V_{IN} , $-40^{\circ}\text{C} \leq T_J \leq 125^{\circ}\text{C}$		5	160	nA
R_{PD}	Pulldown resistor on EN/ SYNC	EN/ SYNC = Low	330	500		kΩ
t_{delay}	Enable delay time	Time from EN/ SYNC high to device starts switching, $R_{S_CONF} = 80.6\text{ k}\Omega$		1		ms
$I_{NR/SS}$	NR/SS source current		67.5	75	82.5	μA
R_{S_CONF}	S-CONF resistor step range accuracy	R_{S_CONF} tolerance for all settings according to S-CONF Table	–4		+4	%
V_{PG}	Power-good threshold	V_{FB} rising, referenced to V_{FB} nominal	93	95	98	%

5.5 Electrical Characteristics (続き)

Over recommended input voltage range, $T_J = -40^\circ\text{C}$ to 150°C . Typical values are at $V_{IN} = 12\text{ V}$ and $T_J = 25^\circ\text{C}$ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_{PG}	Power-good threshold	V_{FB} falling, referenced to V_{FB} nominal	88	90	93	%
$V_{PG,OL}$	Low-level output voltage at PG pin	$I_{SINK} = 1\text{ mA}$			0.4	V
$I_{PG,LKG}$	Input leakage current into PG pin	$V_{PG} = 5\text{ V}$; $-40^\circ\text{C} \leq T_J \leq 125^\circ\text{C}$		5	500	nA
$t_{PG,DLY}$	Power-good delay time	V_{FB} falling		9		μs
OUTPUT						
t_{on}	Minimum on-time	$V_{IN} \geq 5\text{ V}$, $I_{out} = 1\text{ A}$		35		ns
t_{off}	Minimum off-time	$V_{IN} \geq 5\text{ V}$, $I_{out} = 1\text{ A}$		50		ns
V_{FB}	Feedback regulation accuracy	$-40^\circ\text{C} \leq T_J \leq 150^\circ\text{C}$	0.792	0.8	0.808	V
$I_{FB,LKG}$	Input leakage current into FB	$V_{FB} = 0.8\text{ V}$, $-40^\circ\text{C} \leq T_J \leq 125^\circ\text{C}$		1	70	nA
$I_{VO,LKG}$	Input leakage current into VO	$V_{VO} = 1.2\text{ V}$, $-40^\circ\text{C} \leq T_J \leq 125^\circ\text{C}$		0.01	30	μA
PSRR	Power supply rejection ratio	$V_{IN} = 12\text{ V}$, 1.2 V_{OUT} , 1 A , $C_{NR/SS} = 470\text{ nF}$, $f_{sw} = 1\text{ MHz}$, $C_{FF} = \text{open}$, $L_1 = 1\text{ }\mu\text{H}$, $C_{OUT} = 4 \times 22\text{ }\mu\text{F}$, $f \leq 100\text{ kHz}$		65		dB
PSRR	Power supply rejection ratio	$V_{IN} = 5\text{ V}$, 1.2 V_{OUT} , 1 A , $C_{NR/SS} = 470\text{ nF}$, $f_{sw} = 2.2\text{ MHz}$, $C_{FF} = \text{open}$, $L_1 = 1\text{ }\mu\text{H}$, $C_{OUT} = 4 \times 22\text{ }\mu\text{F}$, $f \leq 100\text{ kHz}$		70		dB
V_{NRMS}	Output voltage RMS noise	$V_{IN} = 12\text{ V}$, $BW = 100\text{ Hz to }100\text{ kHz}$, $C_{NR/SS} = 470\text{ nF}$, $f_{sw} = 1\text{ MHz}$, $V_{OUT} = 1.2\text{ V}$, $C_{FF} = \text{open}$, $L_1 = 1\text{ }\mu\text{H}$, $C_{OUT} = 4 \times 22\text{ }\mu\text{F}$		24.4		μV_{RMS}
V_{NRMS}	Output voltage RMS noise	$V_{IN} = 5\text{ V}$, $BW = 100\text{ Hz to }100\text{ kHz}$, $C_{NR/SS} = 470\text{ nF}$, $f_{sw} = 2.2\text{ MHz}$, $V_{OUT} = 1.2\text{ V}$, $C_{FF} = \text{open}$, $L_1 = 1\text{ }\mu\text{H}$, $C_{OUT} = 4 \times 22\text{ }\mu\text{F}$		16.5		μV_{RMS}
V_{opp}	Output ripple voltage at f_{sw}	$V_{IN} = 12\text{ V}$, $f_{sw} = 1\text{ MHz}$, $V_{OUT} = 1.2\text{ V}$, $L_1 = 1\text{ }\mu\text{H}$, $C_{OUT} = 4 \times 22\text{ }\mu\text{F}$, $L_f = 10\text{ nH}$, $C_f = 22\text{ }\mu\text{F}$		36		μV_{RMS}
V_{opp}	Output ripple voltage at f_{sw}	$V_{IN} = 5\text{ V}$, $f_{sw} = 2.2\text{ MHz}$, $V_{OUT} = 1.2\text{ V}$, $L_1 = 2.2\text{ }\mu\text{H}$, $C_{OUT} = 3 \times 22\text{ }\mu\text{F}$, $L_f = 10\text{ nH}$, $C_f = 22\text{ }\mu\text{F}$		13		μV_{RMS}
R_{DIS}	Output discharge resistance	$EN/SYNC = \text{GND}$, $V_{OUT} = 1.2\text{ V}$, $V_{IN} \geq 5\text{ V}$		4		Ω
R_{DIS}	Output discharge resistance	$EN/SYNC = \text{GND}$, $V_{OUT} = 5\text{ V}$, $V_{IN} \geq 5\text{ V}$		16		Ω
f_{sw}	Switching frequency	2.2 MHz setting	1.98	2.2	2.42	MHz
f_{sw}	Switching frequency	1.4 MHz setting	1.26	1.4	1.54	MHz
f_{sw}	Switching frequency	1 MHz setting	0.9	1	1.18	MHz
D_{SYNC}	Synchronization duty cycle		45		55	%
t_{sync_elay}	Synchronization phase delay	Phase delay from EN/SYNC rising edge to SW rising edge		90		ns
I_{SWpeak}	Peak switch current limit	TPS62914	6.4	7.3	8.1	A
$I_{SWvalley}$	Valley switch current limit	TPS62914		7.1		A
I_{SWpeak}	Peak switch current limit	TPS62916	8.6	9	9.6	A
$I_{SWvalley}$	Valley switch current limit	TPS62916		8.8		A
I_{SWpeak}	Peak switch current limit	TPS62918	11	11.75	12.5	A
$I_{SWvalley}$	Valley switch current limit	TPS62918		10.8		A
$I_{negvalley}$	Negative valley current limit			-2.9	-2	A
$R_{DS(ON)}$	High-side FET on-resistance	$V_{IN} \geq 5\text{ V}$		25		m Ω
	Low-side FET on-resistance	$V_{IN} \geq 5\text{ V}$		7		m Ω

5.6 Typical Characteristics

$V_{IN} = 12\text{ V}$, $V_{OUT} = 1.2\text{ V}$, $T_A = 25^\circ\text{C}$, BOM = 表 7-1, (unless otherwise noted)

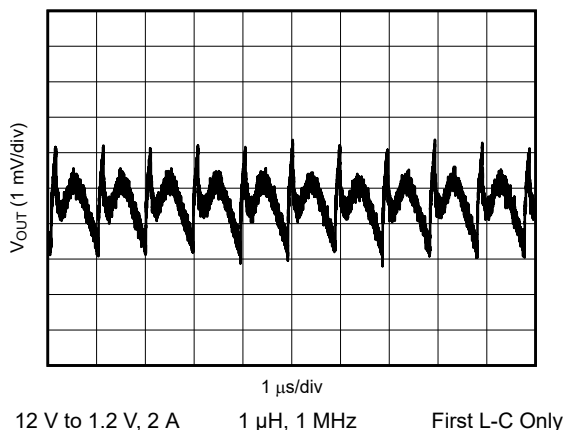


図 5-1. V_{OUT} Ripple After the First L-C Filter

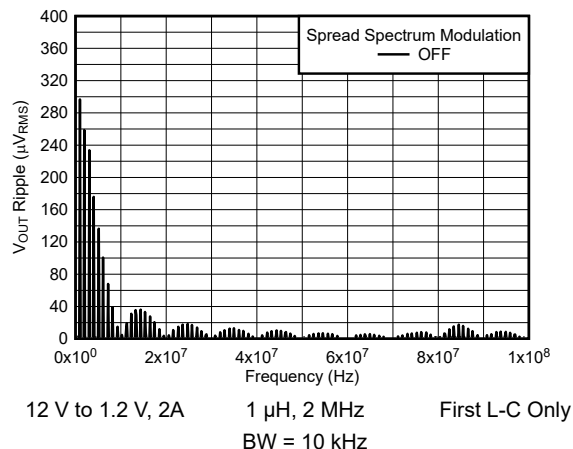


図 5-2. V_{OUT} Ripple FFT After the First L-C Filter

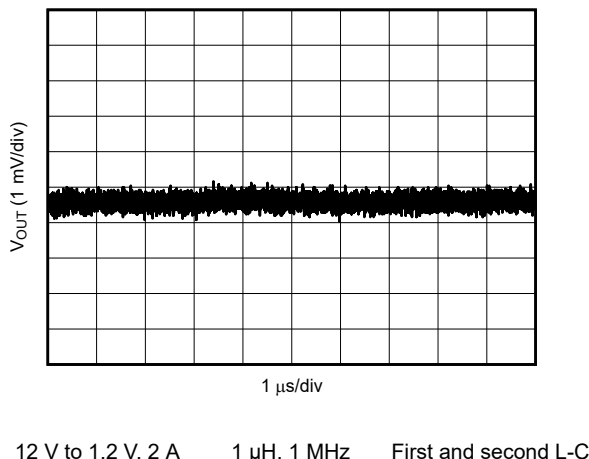


図 5-3. V_{OUT} Ripple After the Second L-C Filter

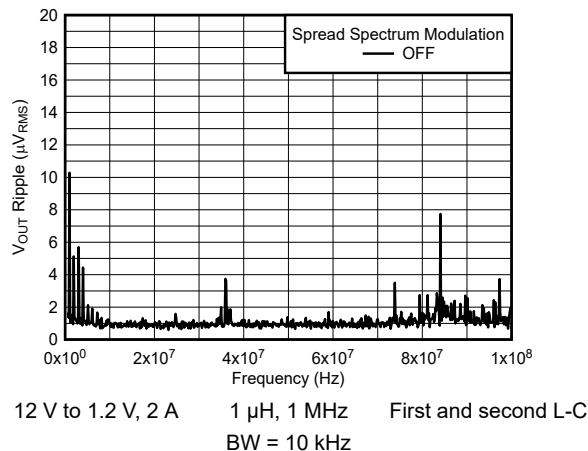


図 5-4. V_{OUT} Ripple FFT After the Second L-C Filter

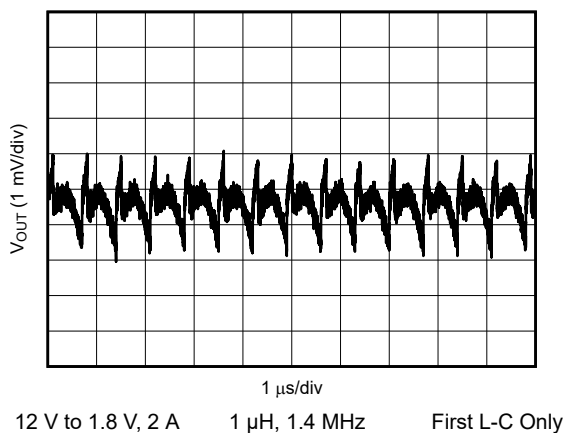


図 5-5. V_{OUT} Ripple After the First L-C Filter

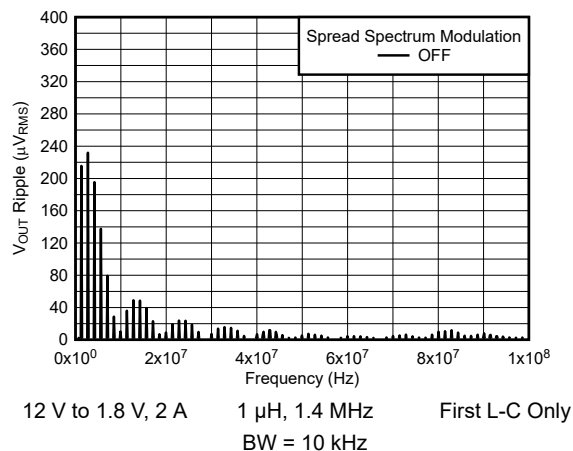
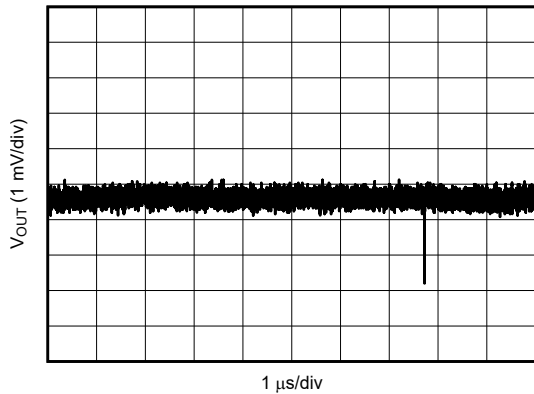


図 5-6. V_{OUT} Ripple FFT After the First L-C Filter

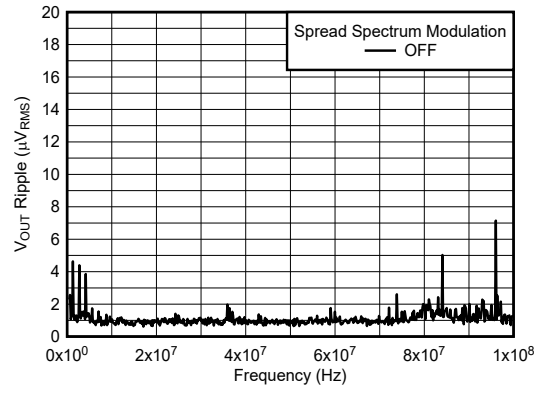
5.6 Typical Characteristics (continued)

$V_{IN} = 12\text{ V}$, $V_{OUT} = 1.2\text{ V}$, $T_A = 25^\circ\text{C}$, BOM = 表 7-1, (unless otherwise noted)



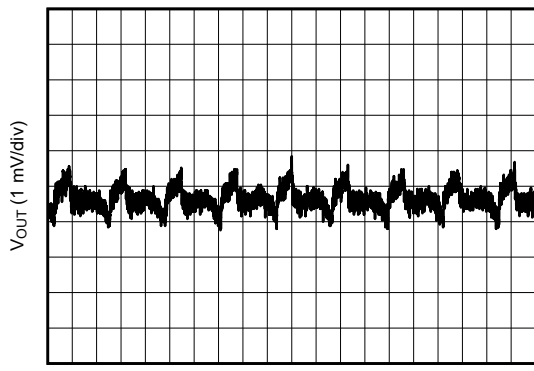
12 V to 1.8 V, 2 A 1 μH , 1.4 MHz First and second L-C

図 5-7. V_{OUT} Ripple After the Second L-C Filter



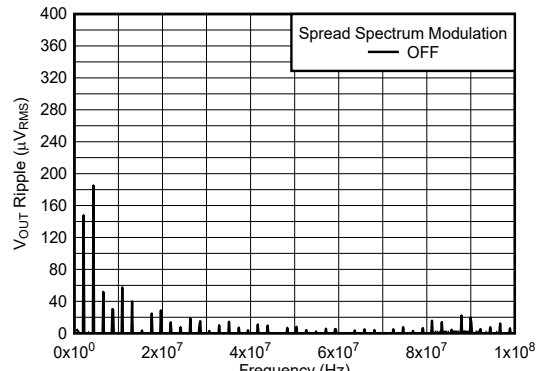
12 V to 1.8 V, 2 A 1 μH , 1.4 MHz First and second L-C
BW = 10 kHz

図 5-8. V_{OUT} Ripple FFT After the Second L-C Filter



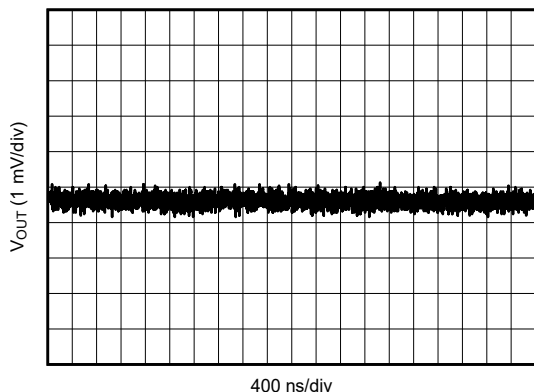
12 V to 3.3 V, 2 A 1 μH , 2.2 MHz First L-C Only

図 5-9. V_{OUT} Ripple After the First L-C Filter



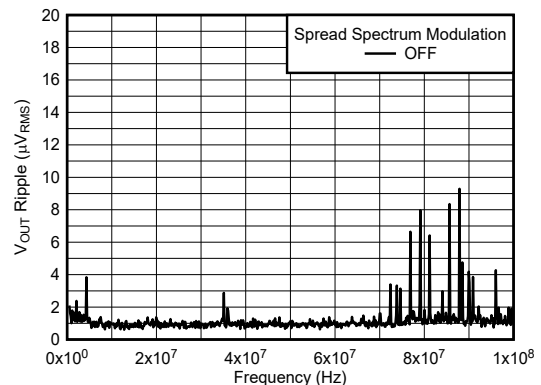
12 V to 3.3 V, 2 A 1 μH , 2.2 MHz First L-C Only
BW = 10 kHz

図 5-10. V_{OUT} Ripple FFT After the First L-C Filter



12 V to 3.3 V, 2 A 1 μH , 2.2 MHz First and second L-C

図 5-11. V_{OUT} Ripple After the Second L-C Filter

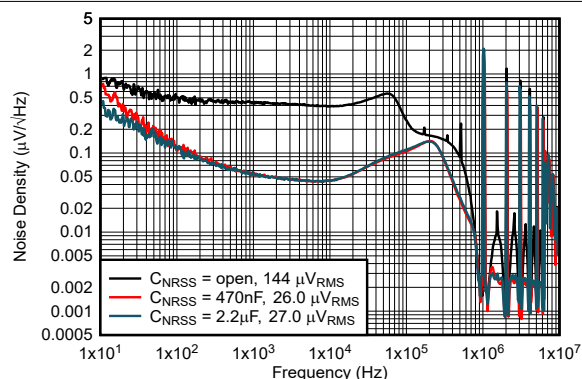


12 V to 3.3 V, 2 A 1 μH , 2.2 MHz First and second L-C
BW = 10 kHz

図 5-12. V_{OUT} Ripple FFT After the Second L-C Filter

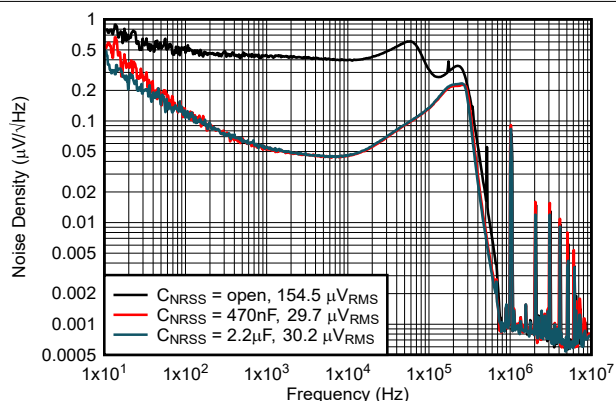
5.6 Typical Characteristics (continued)

$I_N = 12\text{ V}$, $V_{OUT} = 1.2\text{ V}$, $T_A = 25^\circ\text{C}$, BOM = 表 7-1, (unless otherwise noted)



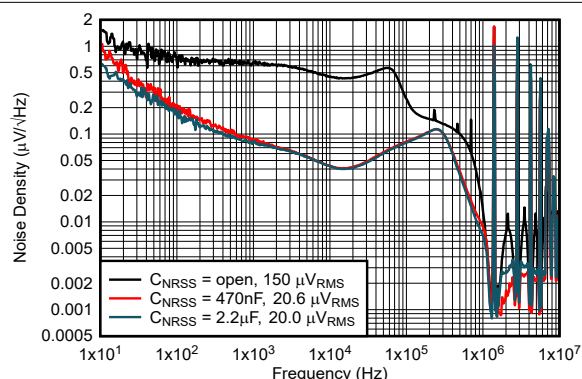
12 V to 1.2 V 1 μH , 1 MHz First L-C Only
NR/SS = Open, 470 nF, 2.2 μF , BW = 100 Hz to 100 kHz

図 5-13. Output Noise Density vs Frequency



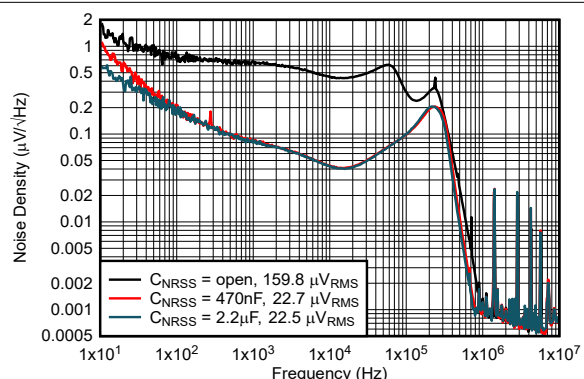
12 V to 1.2 V 1 μH , 1 MHz After ferrite bead filter
NR/SS = Open, 470 nF, 2.2 μF , BW = 100 Hz to 100 kHz

図 5-14. Output Noise Density vs Frequency



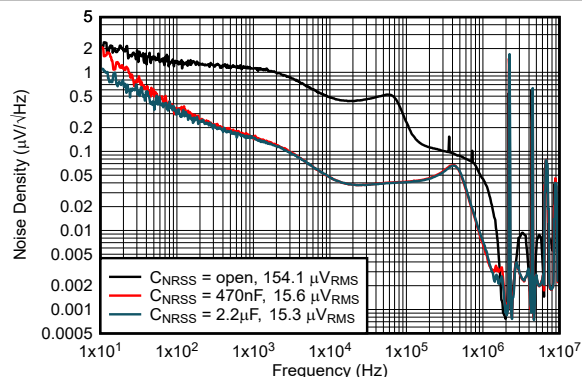
12 V to 1.8 V 1 μH , 1.4 MHz First L-C Only
NR/SS = Open, 470 nF, 2.2 μF , BW = 100 Hz to 100 kHz

図 5-15. Output Noise Density vs Frequency



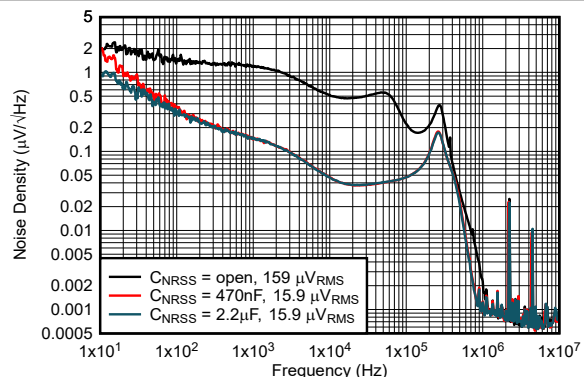
12 V to 1.8 V 1 μH , 1.4 MHz After ferrite bead filter
NR/SS = Open, 470 nF, 2.2 μF , BW = 100 Hz to 100 kHz

図 5-16. Output Noise Density vs Frequency



12 V to 3.3 V 1 μH , 2.2 MHz First L-C Only
NR/SS = Open, 470 nF, 2.2 μF , BW = 100 Hz to 100 kHz

図 5-17. Output Noise Density vs Frequency



12 V to 3.3 V 1 μH , 2.2 MHz After ferrite bead filter
NR/SS = Open, 470 nF, 2.2 μF , BW = 100 Hz to 100 kHz

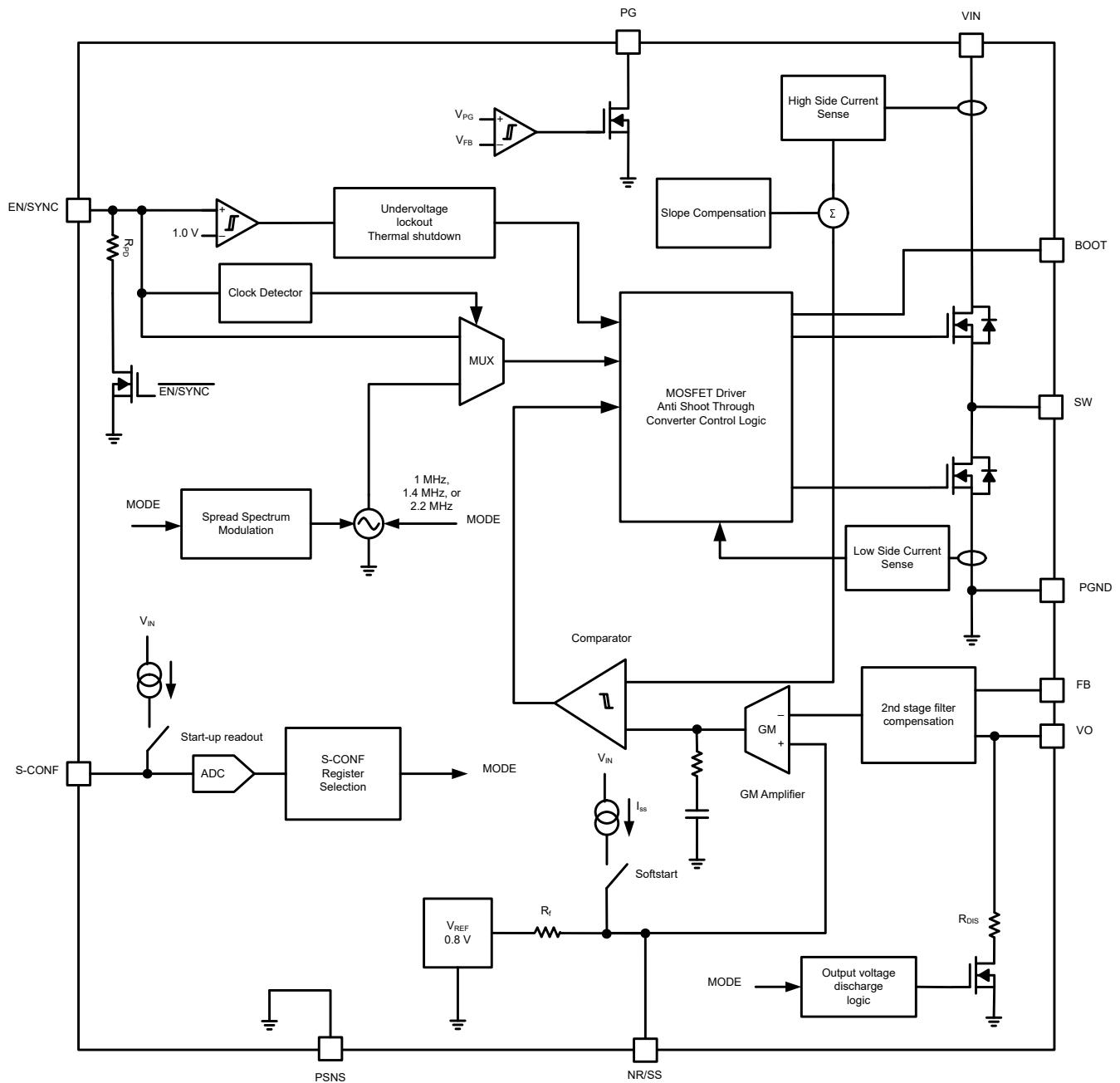
図 5-18. Output Noise Density vs Frequency

6 Detailed Description

6.1 Overview

The TPS6291x low-noise, low-ripple synchronous buck converter is a fixed frequency current mode converter. The converter has a filtered internal reference to achieve a low-noise output similar to low noise LDOs. The converter achieves lower output voltage ripple by using a switching frequency of either 2.2 MHz, 1.4 MHz, or 1 MHz and a larger inductance. The output voltage ripple can be further reduced by adding a small second stage L-C filter to the output. This can be a ferrite bead or a small inductor, followed by an output capacitor. Internal compensation maintains stability with an external filter inductor up to 50 nH. To avoid voltage drops across this second stage filter, the device regulates the output voltage after the filter. The TPS6291x family supports an optional spread spectrum modulation. When powering ADCs, for example, spread spectrum modulation reduces the mixing spurs. Switching frequency, spread spectrum modulation, and output discharge are set using the S-CONF pin.

6.2 Functional Block Diagram



6.3 Feature Description

6.3.1 Smart Config (S-CONF)

This S-CONF pin configures the device based on the resistor value. This pin is read after EN/SYNC goes high. The device configuration cannot be changed during operation. The S-CONF value is re-read if EN is pulled below 200 mV or if VIN falls below UVLO. 表 6-1 shows the configuration options of switching frequency, spread spectrum modulation, output discharge, and synchronization.

To make sure the internal circuit detects the resistor value correctly, minimize the distance between the resistor and the S-CONF pin and do not place any capacitors on the S-CONF pin.

表 6-1. S-CONF Device Configuration Modes

S-CONF	SWITCHING FREQUENCY	SPREAD SPECTRUM	OUTPUT DISCHARGE	SYNC
VIN	2.2 MHz	OFF	OFF	No
GND	1 MHz	OFF	OFF	No
4.87 kΩ	1.4 MHz	OFF	OFF	No
6.04kΩ	1.4 MHz	OFF	OFF	1.2 MHz to 1.6 MHz
7.5 kΩ	2.2 MHz	OFF	OFF	1.9 MHz to 2.42 MHz
9.31 kΩ	1 MHz	OFF	OFF	0.9 MHz to 1.2 MHz
11.5kΩ	1 MHz	Random	OFF	No
14.3 kΩ	1.4 MHz	Random	OFF	No
18.2 kΩ	2.2 MHz	Random	OFF	No
22.1 kΩ	1 MHz	OFF	ON	No
27.4 kΩ	1.4 MHz	OFF	ON	No
34kΩ	2.2 MHz	OFF	ON	No
42.2 kΩ	1 MHz	OFF	ON	0.9 MHz to 1.2 MHz
52.3 kΩ	1.4 MHz	OFF	ON	1.2 MHz to 1.6 MHz
64.9kΩ	2.2 MHz	OFF	ON	1.9 MHz to 2.42 MHz
80.6 kΩ	1 MHz	Random	ON	No
100 kΩ	1.4 MHz	Random	ON	No
124 kΩ	2.2 MHz	Random	ON	No

6.3.2 Device Enable (EN/SYNC)

The device is enabled by pulling the EN/SYNC pin high, and has an accurate rising threshold voltage of typically 1.01 V. After the device is enabled, the operation mode is set by the configuration of the S-CONF pin. This action occurs during the device start-up delay time t_{delay} . After t_{delay} expires, the internal soft-start circuitry ramps up the output voltage over the soft-start time set by the $C_{\text{NR/SS}}$ capacitor. The start-up delay time t_{delay} varies depending on the selected S-CONF value. The start-up delay time is shortest with smaller S-CONF resistors.

The EN/SYNC pin has an active pulldown resistor R_{PD} . This resistor prevents an uncontrolled start-up of the device, in case the EN/SYNC pin cannot be driven to a low level. The pulldown resistor is disconnected after start-up. With EN set to a low level, the device enters shutdown and the pulldown resistor is activated again.

6.3.3 Device Synchronization (EN/SYNC)

The EN/SYNC pin is also used for device synchronization. After a clock signal is applied to this pin, the device is enabled and reads the configuration of the S-CONF pin. The external clock frequency must be within the clock synchronization frequency range set by the S-CONF pin. When the clock signal changes from a clock to a static high, then the device switches from external clock to internal clock. To shutdown the device when using an external clock, EN/SYNC must go low for at least 10 μs .

The clock signal can be a logic signal with a logic level as specified in the electrical table, and can be applied directly to the EN/SYNC pin. External logic, such as an AND gate, can be used to combine separate enable and clock inputs, as shown in [Figure 6-1](#).

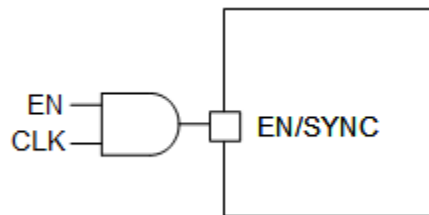


Figure 6-1. Synchronization with Separate Enable Signal (Optional)

6.3.4 Spread Spectrum Modulation

Using the S-CONF pin enables or disables spread spectrum modulation. DC/DC converter generate an output voltage ripple at the switching frequency. When powering ADCs or an analog front-end (AFE), the switching frequency generates high frequency mixing spurs as well as a low frequency spur in the output frequency spectrum. Using the optional second stage L-C filter reduces the ripple of the converter and spurs by up to 30 dB.

The device has an integrated random spread spectrum modulation (SSM) scheme, selected by the resistor connected to the S-CONF pin according to [Table 6-1](#). Selecting random modulation to spread the switching frequency over a larger frequency range is possible. The modulation spread is $\pm 10\%$ of the device switching frequency. This SSM provides high attenuation when the receiver bandwidth is $\leq$ the modulation frequency, typically the case for systems using Fast Fourier Transforms (FFT) post processing as in high speed ADC applications. For applications sensitive to noise at the modulation frequency, random SSM is used. Using a random spread spectrum modulation also reduces the spurs in the output spectrum as shown in [Figure 5-2](#). The randomized modulation uses a Fibonacci Linear-Feedback Shift Register (LFSR) so that every tone is generated once during the pseudo-random generation period. The frequency spreading is shown in [Figure 6-2](#).

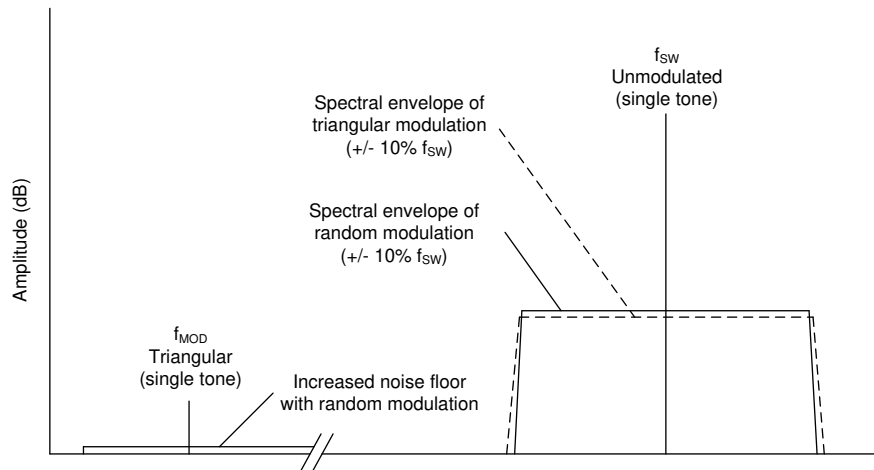


図 6-2. Spread Spectrum Modulation

6.3.5 Output Discharge

Output discharge is enabled or disabled, depending on the S-CONF setting. With output discharge enabled, the output voltage is pulled low by a discharge resistor R_{DIS} of typically 7 Ω. The output discharge function is enabled during thermal shutdown, UVLO, or when EN/SYNC is pulled low.

6.3.6 Undervoltage Lockout (UVLO)

To avoid mis-operation of the device at low input voltages, the device is enabled after the input voltage is above the undervoltage lockout threshold. The device is disabled after the input voltage falls below the undervoltage threshold.

6.3.7 Power-Good Output

The device has a power-good output. The PG pin goes high impedance after the FB pin voltage is above 95% of the nominal voltage, and is driven low after the voltage falls below typically 90% of the nominal voltage. 表 6-2 shows the typical PG pin logic. The PG pin is an open-drain output and is specified to sink up to 10 mA. The power-good output requires a pullup resistor connecting to any voltage rail less than 18 V. The PG signal can be used for sequencing of multiple rails by connecting to the EN pin of other converters. If not used, the PG pin can be left floating or connected to GND. PG has a deglitch time of typically 8 μs before going low.

表 6-2. Power-Good Pin Logic

DEVICE STATE		PG LOGIC STATUS	
		HIGH IMPEDANCE	LOW
Enabled (EN/SYNC = High)	$V_{FB} \geq V_{PG}$	√	
	$V_{FB} < V_{PG}$ after t _{PG}		√
Shutdown (EN/SYNC = Low)			√
UVLO	$0.7 V < V_{IN} < V_{UVLO}$		√
Thermal shutdown	$T_J > T_{JSD}$		√
Power supply removal	$V_{IN} < 0.7 V$	√	

6.3.8 Noise Reduction and Soft-Start Capacitor (NR/SS)

A capacitor connected to this pin reduces the low frequency noise of the converter and sets the soft-start time. The larger the capacitor, the lower the noise and the longer the start-up time of the converter. A 470 nF capacitor is typically connected to this pin for a start-up time of 5 ms, although longer and shorter start-up times can be used. During soft start with a light load, the device skips switching pulses as needed to not discharge the output voltage. The device can start into a prebiased output voltage.

The device achieves low noise by adding an R-C filter to the reference voltage, as shown in [セクション 6.2](#). During start-up, the NR/SS capacitor is charged with a constant current of 75 µA (typical) to 0.8 V. Larger NR/SS capacitors provide for lower low frequency noise. The maximum NR/SS cap is 3.3 µF for a start-up time of 35 ms. The minimum start-up time is set internally to 0.7 ms, which occurs when there is a small NR/SS capacitor or no NR/SS capacitor.

6.3.9 Current Limit and Short-Circuit Protection

The device is protected against short circuits and overcurrent. The switch current limit prevents the device from high inductor current and from drawing excessive current from the input voltage rail. Excessive current can occur with a shorted, saturated inductor or a heavy load, shorted output circuit condition. If the inductor current reaches the threshold I_{SWpeak} , the high-side MOSFET is turned off and the low-side MOSFET is turned on to ramp down the inductor current. The high-side MOSFET is turned on again only when the low-side current is below the low-side sourcing current limit $I_{SWvalley}$.

Due to internal propagation delay, the actual current can exceed the static current limit, especially if the input voltage is high and very small inductances are used. The dynamic current limit is calculated as follows in [式 1](#):

$$I_{PEAK(typ)} = I_{SWpeak} + \left(\frac{V_L}{L} \right) \times t_{PD} \quad (1)$$

where

- I_{SWpeak} is the static current limit, specified in [Electrical Characteristics](#)
- L is the inductance
- V_L is the voltage across the inductor ($V_{IN} - V_{OUT}$)
- t_{PD} is the internal propagation delay, typically 50 ns

The low-side MOSFET also contains a negative current limit to prevent excessive current from flowing back through the inductor to the input. If the low-side sinking current limit is exceeded, the low-side MOSFET is turned off. In this scenario, both MOSFETs are off until the start of the next cycle.

6.3.10 Thermal Shutdown

The device goes into thermal shutdown after the junction temperature exceeds typically 170°C with a 20°C hysteresis.

6.4 Device Functional Modes

6.4.1 Fixed Frequency Pulse Width Modulation

To minimize output voltage ripple, the device operates in fixed frequency PWM operation down to no load. The switching frequency of 1 MHz, 1.4 MHz, or 2.2 MHz is selected using the S-CONF pin.

6.4.2 Low Duty Cycle Operation

For high input voltages or low output voltages, the 70 ns minimum on-time limits the maximum input to output voltage difference and the switching frequency selected. When the minimum on-time is reached, the output voltage rises above the regulation point. Refer to [表 7-2](#) for detailed design recommendations.

6.4.3 High Duty Cycle Operation (100% Duty Cycle)

The device offers a low input-to-output voltage differential by entering 100% duty cycle mode. In this mode, the high-side MOSFET switch is constantly turned on. The minimum input voltage to maintain output voltage regulation, depending on the load current and the output voltage level, is calculated as:

$$V_{IN(min)} = V_{OUT(min)} + I_{OUT} \times (R_{DS(ON)} + R_L) \quad (2)$$

where

- $V_{OUT(min)}$ is the minimum output voltage the load can accept

- I_{OUT} is the output current
- $R_{DS(ON)}$ is the $R_{DS(ON)}$ of the high-side MOSFET
- R_L is the DC resistance of the inductor used

To maintain fixed frequency switching, the device requires a minimum off-time of 50 ns (typical), 60 ns (maximum). If this limit is reached during a switching pulse, the device skips switching pulses to maintain output voltage regulation. If the input voltage decreases further, the device enters 100% mode.

6.4.4 Second Stage L-C Filter Compensation (Optional)

Most low-noise and low-ripple applications use a ferrite bead and bypass capacitor before the load. Using a second L-C filter is especially useful for low-noise and low-ripple applications with constant load current such as ADCs, DACs, and Jitter Cleaner. The second stage L-C filter is optional, and the device can be used without this filter. Without the filter, the device has a low output voltage noise of typically 16.9 μV_{RMS} with an output voltage ripple of 280 μV_{RMS} shown in [Figure 5-10](#). The second stage L-C filter attenuates the output voltage ripple by another approximately 30 dB shown in [Figure 5-12](#). To improve load regulation, the device can remote sense the output voltage after the second stage L-C filter and is internally compensated for the additional double pole generated by the L-C filter.

To keep the second stage L-C filter as small as possible, the internal compensation is optimized for a 10 nH to 50 nH inductance. A small ferrite bead or even a PCB trace provides sufficient inductance for output voltage ripple filtering. See [Section 7.2.2.2.4](#) for details.

7 Application and Implementation

注

以下のアプリケーション情報は、TI の製品仕様に含まれるものではなく、TI ではその正確性または完全性を保証いたしません。個々の目的に対する製品の適合性については、お客様の責任で判断していただくことになります。お客様は自身の設計実装を検証しテストすることで、システムの機能を確認する必要があります。

7.1 Application Information

The TPS6291x family of devices are designed for low noise and low output voltage ripple.

7.2 Typical Applications

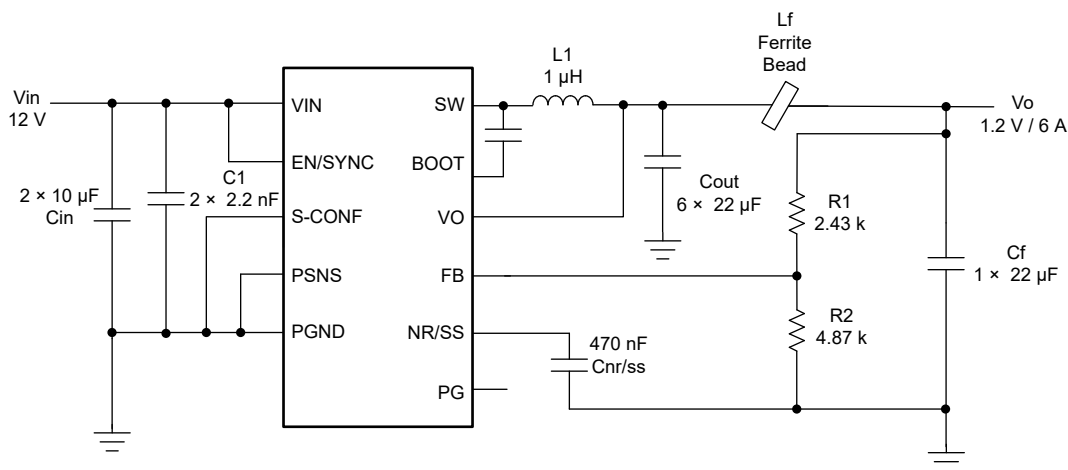


Figure 7-1. Typical Schematic

表 7-1 shows the list of recommended components for most applications.

表 7-1. List of Components

REFERENCE	PART NUMBER	DESCRIPTION	MANUFACTURER
TPS6291x	TPS6291x	Low noise and low ripple buck converter	Texas Instruments
L ₁	XGL4030-102MEC or XGL5030-102MEC	Inductor: 1.0 µH	Coilcraft
C _{IN}	C2012X7S1E106K125AC	Ceramic capacitors: 2 × 10 µF ±10% 25-V Ceramic Capacitor X7S 0805	TDK
C _{OUT}	C2012X7S1A226M125AC	Ceramic capacitors: 6 × 22 µF, 10 V, ±20%, X7S, 0805	TDK
L _f	BLE32SN120SN1L	Ferrite Bead	MuRata
C _f	C2012X7S1A226M125AC	Ceramic capacitor: 1 × 22 µF, 10 V, ±20%, X7S, 0805	TDK
C ₁	GRM155R71H222KA01D	Ceramic capacitor: 2 × 2200 pF, 50 V, ±10%, X7R, 0402	MuRata
C _{NR/SS} , C _{FF}		Ceramic capacitor	Standard
R1, R2, R3, R4		Resistor	Standard

7.2.1 Design Requirements

The external components have to fulfill the needs of the application, but also meet the stability criteria of the control loop of the device. The device is designed to work within a range of external components, and can be optimized for efficiency, output ripple, component count, or lowest 1/f noise.

Typical applications that have input voltages of ≤ 6 V use a 1 μ H inductor with a 2.2 MHz switching frequency. Applications that have input voltages > 6 V can be optimized for efficiency using a 1 μ H inductor with a 1 MHz or 1.4 MHz switching frequency depending on the output voltage. Optimization for powering clock and PLL circuits that need a 3.3 V output use a 1 μ H inductor with 2.2 MHz switching frequency, minimizing output voltage ripple and low frequency noise.

For the application cases that are not found in 表 7-2, there are two methods to design the TPS6291x circuit. セクション 7.2.2.1 uses WEBENCH to design the circuit automatically or the calculations in セクション 7.2.2.2 can be used instead.

表 7-2. Typical Single L-C Filter Design Recommendations

DESIGN GOAL	V _{IN}	V _{OUT}	F _{sw}	INDUCTOR ⁽²⁾	OUTPUT CAPACITORS ⁽³⁾
Typical	12 V ⁽¹⁾	≤ 1.4 V ⁽¹⁾	1 MHz	1 μ H	6 $\times$ 22 μ F, 10 V, 0805
Typical	12 V	1.4 V $< V_{OUT} \leq 2.2$ V	1.4 MHz	1 μ H	6 $\times$ 22 μ F, 10 V, 0805
Typical	12 V	> 2.2 V	2.2 MHz	1 μ H	8 $\times$ 22 μ F, 10 V, 0805
Typical	5 V	≤ 3.3 V	2.2 MHz	1 μ H	6 $\times$ 22 μ F, 10 V, 0805
Typical	5 V	> 3.3 V	2.2 MHz	1 μ H	8 $\times$ 22 μ F, 10 V, 0805

- (1) The maximum input to output voltage difference is limited by the device maximum minimum on-time of 70 ns. This limit is especially important for input voltages above 12 V or output voltages below 1 V. See セクション 7.2.2.2.1.
- (2) For inductor part numbers, see 表 7-4.
- (3) For output capacitor part numbers, see 表 7-5.

The second stage L-C filter is optional, as the device can be used without this filter to achieve below 20 μ V_{RMS} noise typically. A second stage filter is added to provide additional attenuation of the output ripple voltage. The output voltage is sensed after the second L-C filter by connecting the FB resistors to the second stage L-C filter capacitor. This action provides remote sense, minimizing output voltage drop due to the ferrite bead. Refer to 表 7-3 for second stage L-C filter recommendations based on the output voltage.

表 7-3. Second Stage L-C (Ferrite Bead) Filter Design Recommendations

V _{OUT} (V)	FERRITE BEAD IMPEDANCE (AT 100 MHZ) ⁽²⁾	OUTPUT CAPACITORS ⁽¹⁾
≤ 2.2 V	8 to 20 Ω	1 $\times$ 22 μ F, 10 V, 0805
> 2.2 V	8 to 20 Ω	2 $\times$ 22 μ F, 10 V, 0805

- (1) For output capacitor part numbers, see 表 7-5.
- (2) For second stage L-C filter part numbers, see 表 7-6.

7.2.2 Detailed Design Procedure

If the specific design is not found in 表 7-2, TI recommends WEBENCH to generate the design. Alternatively, follow the manual design procedure in [External Component Selection](#).

7.2.2.1 Custom Design With WEBENCH® Tools

[Click here](#) to create a custom design using the TPS6291x device with the WEBENCH Power Designer.

1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost.
3. Open the advanced tab to optimize for output voltage ripple.
4. After in a TPS6291x design, you can enable the second stage L-C filter and change other settings from the drop-down on the left.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

7.2.2.2 External Component Selection

7.2.2.2.1 Switching Frequency Selection

The switching frequency can be chosen to optimize efficiency (lower) or ripple noise (higher). Using the higher 1.4 MHz or 2.2 MHz setting increases the gain of the feedback loop and can result in lower output noise. However, additional considerations for minimum on-time and duty cycle must also be considered. First, calculate the duty cycle using 式 3. Higher efficiency results in a shorter on-time, so a conservative approach is to use a higher efficiency than expected in the application.

$$D = \frac{V_{OUT}}{V_{IN} \times \eta} \quad (3)$$

where:

- η = estimated efficiency (use the value from the efficiency curves or 0.9 as an conservative assumption)

Then, calculate the on-time with 1 MHz, 1.4 Mhz, and 2.2 MHz using 式 4. The on-time must always remain above the minimum on-time of 70 ns. Use the maximum input voltage and maximum efficiency to determine the minimum duty cycle, D_{min} . Use the maximum switching frequency for f_{SW} .

$$T_{ON} = \frac{D_{min}}{f_{SW_min}} \quad (4)$$

then

- If t_{ON_min} minimum < 70 ns with 2.2 MHz, use 1.4 MHz.
- If t_{ON_min} minimum < 70 ns with 1.4 MHz, use 1 MHz
- If t_{ON_min} minimum < 70 ns with 1 MHz, reduce the maximum input voltage.
- If t_{ON_min} minimum $\geq$ 70 ns, use a lower frequency for highest efficiency, or the highest frequency for the lowest noise and ripple.

7.2.2.2.2 Inductor Selection for the First L-C Filter

The inductor must be rated for the appropriate saturation current. 式 5 and 式 6 calculate the maximum inductor current under static load conditions. The formula takes the converter efficiency into account. The calculation must be done for the maximum input voltage where the peak switch current is highest.

$$\Delta I_L = \frac{\frac{V_{OUT}}{\eta} \times \left(1 - \frac{V_{OUT}}{V_{IN} \times \eta}\right)}{f_{SW} \times L} \quad (5)$$

$$I_{PEAK} = I_{OUT} + \frac{\Delta I_L}{2} \quad (6)$$

where:

- f_{SW} is the switching frequency (1 MHz, 1.4 MHz, or 2.2 MHz)
- L = inductance
- η = estimated efficiency (use the value from the efficiency curves or 0.9 as an conservative assumption)

注

The calculation must be done for the maximum input voltage of the application.

Calculating the maximum inductor current using the actual operating conditions gives the minimum saturation current. TI recommends a margin of 20% be added to cover for load transients during operation.

See 表 7-4 for typical inductors.

表 7-4. Inductor Selection

INDUCTOR VALUE	MANUFACTURER	PART NUMBER	SIZE (L × W × H IN mm)	ISAT/DCR (30% DROP)
1 µH	Coilcraft	XGL4020-102	4 × 4 × 2.1	8.8 A / 8.2 mΩ
1 µH	Coilcraft	XGL4030-102	4 × 4 × 3.1	10.3 A / 6.5 mΩ
1 µH	Würth Elektronik	74438356010	4.1 × 4.1 × 2.1	9 A / 12 mΩ
1 µH	Würth Elektronik	74438357010	4.1 × 4.1 × 3.1	9.6 / 11.6 mΩ
1 µH	Coilcraft	XGL5020-102	5 × 5 × 2.1	11.4 A / 7.5 mΩ
1 µH	Coilcraft	XGL5030-102	5 × 5 × 3.1	14 A / 4.8 mΩ

7.2.2.2.3 Output Capacitor Selection

The effective output capacitance can range from 80 µF (minimum) up to 400 µF (maximum) for a single L-C system design. When using a second L-C filter, the first L-C filter must have output capacitance between 80 µF and 160 µF, the second stage L-C filter (if used) must have at least 20 µF of capacitance, and the total capacitance for both L-C filters must be less than 400 µF. Load transient testing and measuring the bode plot are good ways to verify stability.

注

For designs requiring cold temperature (< -10°C) operation, TI recommends to use a minimum effective output capacitance of 120 µF for a single L-C system design or within the first L-C filter when using a second L-C filter design.

TI recommends ceramic capacitors (X5R or X7R). Ceramic capacitors have a DC-Bias effect, which has a strong influence on the final effective capacitance. Choose the right capacitor carefully in combination with considering the package size and voltage rating. The ESR and ESL of the output capacitor are also important considerations in selecting the output capacitors for low noise applications. Smaller package sizes typically have lower ESL and ESR. TI recommends 0805 or smaller packages, as long as the packages provide the required capacitance and voltage rating for stable operation. 表 7-5 lists recommended output capacitors.

表 7-5. Recommended Output Capacitors

CAPACITOR TYPE	CAPACITOR VALUE	MANUFACTURER	VOLTAGE (V)	PACKAGE
Bulk Capacitor	22 µF, X7S	TDK C2012X7S1A226M125AC	10	0805
Bulk Capacitor	47 µF, X7R	Murata GRM32ER71A476ME15L	10	1210

7.2.2.2.4 Ferrite Bead Selection for Second L-C Filter

Using a ferrite bead for the second stage L-C filter minimizes the external component count because most of the noise sensitive circuits use a RF bead for high frequency attenuation as a default component at their inputs.

Make sure to select a ferrite bead with sufficiently high inductance at full load, and with low DC resistance (below 10 mΩ) to keep the converter efficiency as high as possible. The ferrite bead inductance decreases with increased load current. Therefore, the ferrite bead must have a current rating much higher than the desired load current.

The recommendation is to choose a ferrite bead with an impedance of 8 Ω to 20 Ω at 100 MHz. Ferrite beads can be used in parallel if higher current is needed, however this can halve the inductance and filtering. Refer to 表 7-6 for possible ferrite beads.

表 7-6. Recommended Ferrite Beads

PART NUMBER	MANUFACTURER	SIZE	IMPEDANCE AT 100 MHz	INDUCTANCE AT 100 MHz (CALCULATED)	DC RESISTANCE	CURRENT RATING
BLE18PS080SN1	MuRata	0603	8.5 Ω	13.5 nH	4 mΩ	5 A
BLE32SN120SN1L	MuRata	1210	12 Ω	18 nH	0.78 mΩ	20 A
74279221100	Würth Elektronik	1206	10 Ω	15.9 nH	3 mΩ	10.5 A
7427922808	Würth Elektronik	0603	8 Ω	12.7 nH	5 mΩ	9.5 A

The internal compensation has been designed to be stable with up to 50 nH of inductance in the second stage filter. To achieve low ripple, the second L-C filter requires only 5-nH to 10-nH inductance. The inductance can be estimated from the ferrite bead impedance specification at 100 MHz, with the assumption that the inductance is similar at the selected converter switching frequency of 1 MHz, 1.4 MHz, or 2.2 MHz, and can be verified through tools available on some manufacturer websites. Use 式 7 to calculate the inductance of a ferrite bead:

$$L = \frac{Z}{2\pi \times f} \quad (7)$$

where

- Z is the impedance of the ferrite bead in ohms at the specified frequency (usually 100 MHz)
- f is the specified frequency (usually 100 MHz)

7.2.2.2.5 Input Capacitor Selection

For the best output and input voltage filtering, TI recommends X5R or X7R ceramic capacitors. The input bulk capacitor minimizes input voltage ripple, suppresses input voltage spikes, and provides a stable system rail for the device. TI recommends a 10-μF or larger input capacitor. Having two in parallel further improves the input voltage ripple filtering, minimizing noise coupling into adjacent circuits. The voltage rating of the cap must also be taken into consideration, and must provide the required 5-μF minimum effective capacitance after DC bias derating.

In addition to the bulk input cap, a smaller cap must be placed directly from the VIN pin to the PGND pin to minimize input loop parasitic inductance, thereby minimizing the high frequency noise of the device. The input cap placement affects the output noise, so care needs to be taken in placing both the bulk cap and bypass caps as shown in セクション 7.4.2. 表 7-7 lists recommended input capacitors.

表 7-7. Recommended Input Capacitors

INPUT CAP TYPE	CAPACITOR VALUE	MANUFACTURER	VOLTAGE RATING (V)	PACKAGE SIZE
Bulk Cap	10 μF, X7S	TDK C2012X7S1E106K125AC	25	0805
Bypass Cap	2.2 nF, X7R	Murata GRM155R71E222KA01D	25	0402

7.2.2.2.6 Setting the Output Voltage

Choose resistors R1 and R2 to set the output voltage within a range of 0.8 V to 5.5 V, according to 式 8. To keep the feedback network robust from noise, and to reduce the self-generated noise of resistors, set R2 equal to or lower than 5 kΩ. Lower values of FB resistors achieve better noise immunity, and lower light load efficiency, as explained in the [Design Considerations for a Resistive Feedback Divider in a DC/DC Converter analog design journal](#).

$$R_1 = R_2 \times \left(\frac{V_{OUT}}{V_{FB}} - 1 \right) = R_2 \times \left(\frac{V_{OUT}}{0.8V} - 1 \right) \quad (8)$$

VOUT (V)	R1	R2
0.9	604 Ω	4.87 kΩ
1.0	1.21 kΩ	4.87 kΩ
1.2	2.43 kΩ	4.87 kΩ
1.8	6.04 kΩ	4.87 kΩ
2.5	10.4 kΩ	4.87 kΩ
3.3	15.2 kΩ	4.87 kΩ
5	25.5 kΩ	4.87 kΩ

A feedforward capacitor (C_{FF}) is not required for proper operation, but can further improve output noise. However, care must be taken in choosing the C_{FF} because the power-good (PG) function can not be valid with a large C_{FF} during start-up, and can cause spurious triggering of the PG pin during a large load transient. Refer to the [Pros and Cons Using a Feedforward Capacitor with a Low Dropout Regulator application report](#) for a discussion of the pros and cons of using a feedforward capacitor.

7.2.2.2.7 Bootstrap Capacitor Selection

A 0.1-μF ceramic capacitor must be connected between the BOOT and SW pins for proper operation. The capacitor must be rated for at least 10 V to minimize DC bias derating.

A resistor must be added in series with the BOOT capacitor to slow down the turn-on of the high-side MOSFET and rising edge overshoot on the SW pin for applications with input voltage greater than 13.5 V, which comes with the trade off of more power loss and lower efficiency. As a best practice, include a 0-Ω placeholder in all prototype designs in case parasitic inductance in the PCB layout results in more voltage overshoot at the SW pin than is normal, which helps keep the voltage within the ratings of the device and reduces the high frequency noise on the SW node. The recommended BOOT resistor value to decrease the SW pin overshoot is 2.2 Ω.

7.2.2.2.8 NR/SS Capacitor Selection

As described in [セクション 6.3.8](#), the NR/SS cap affects both the total noise and the soft-start time. The recommended value for a 5-ms soft-start time and good noise performance is 470 nF. The maximum NR/SS cap is 3.3 μF for a start-up time of 35 ms. Values greater than 1 μF have minimal improvement in noise performance. Use [式 9](#) and [式 10](#) to calculate the soft-start time based on desired soft-start time or the chosen capacitor value.

$$t_{ss} (s) = \frac{C_{NRSS} \times 0.8 V}{I_{NRSS}} \quad (9)$$

$$C_{NRSS} (F) = \frac{I_{NRSS} \times t_{ss}}{0.8 V} \quad (10)$$

7.2.3 Application Curves

$V_{IN} = 12\text{ V}$, $V_{OUT} = 1.2\text{ V}$, $T_A = 25^\circ\text{C}$, BOM = 表 7-1

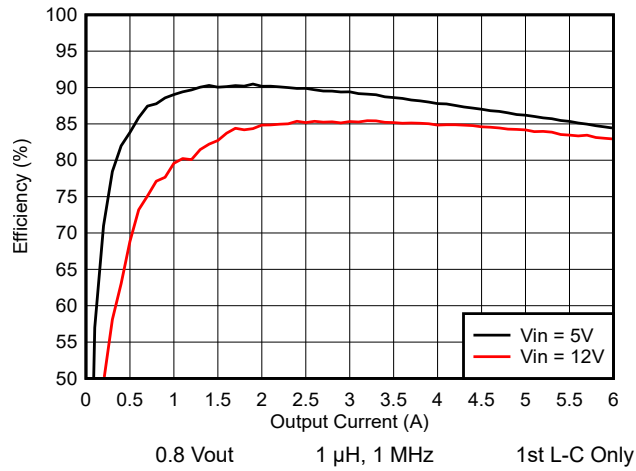


図 7-2. Efficiency vs Load Current

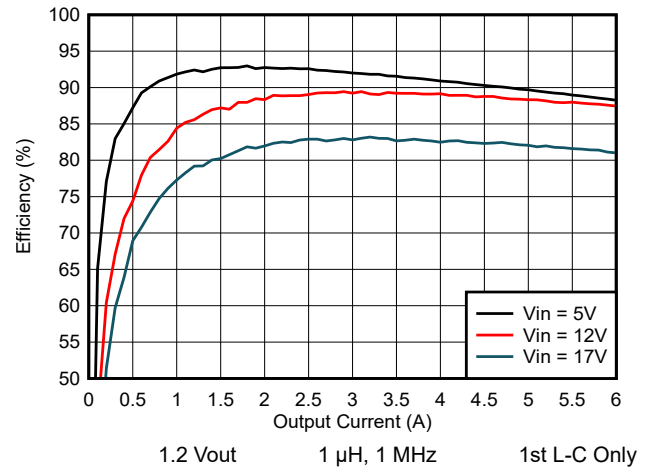


図 7-3. Efficiency vs Load Current

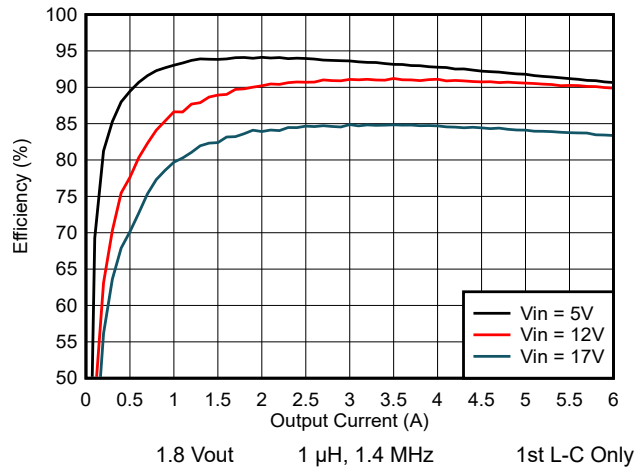


図 7-4. Efficiency vs Load Current

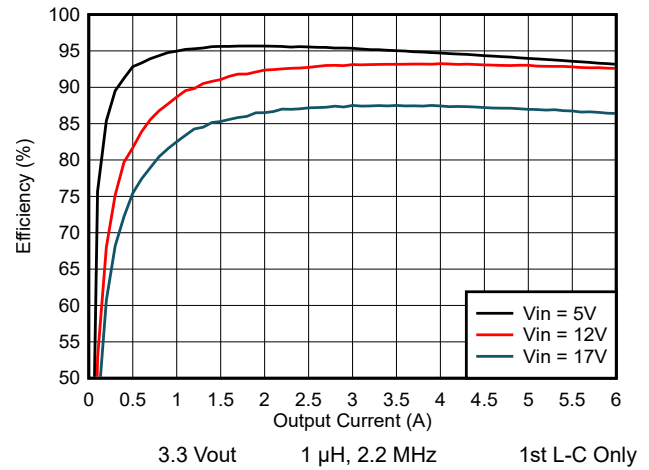


図 7-5. Efficiency vs Load Current

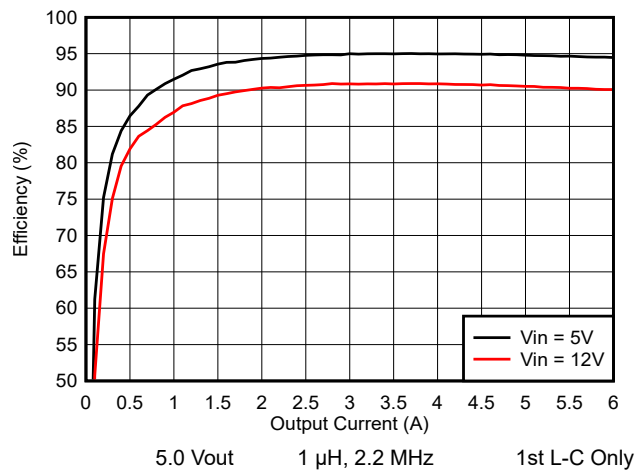


図 7-6. Efficiency vs Load Current

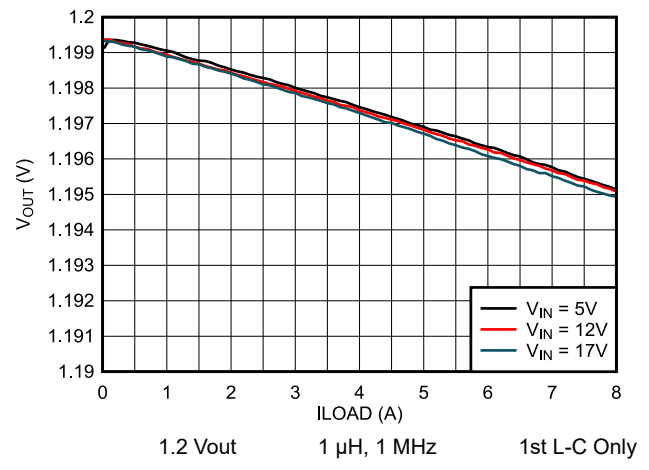


図 7-7. Output Voltage vs Load Current

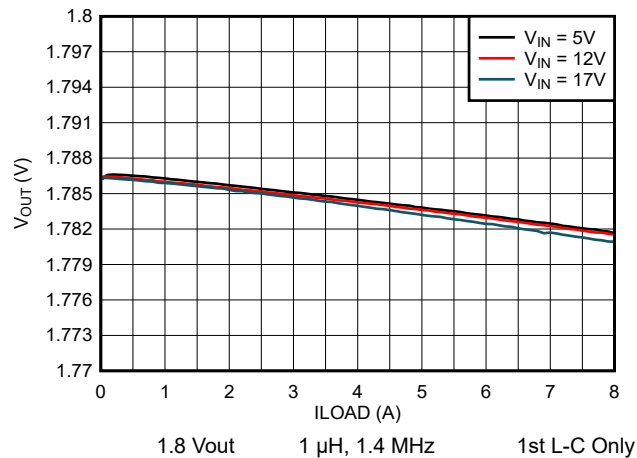


Figure 7-8. Output Voltage vs Load Current

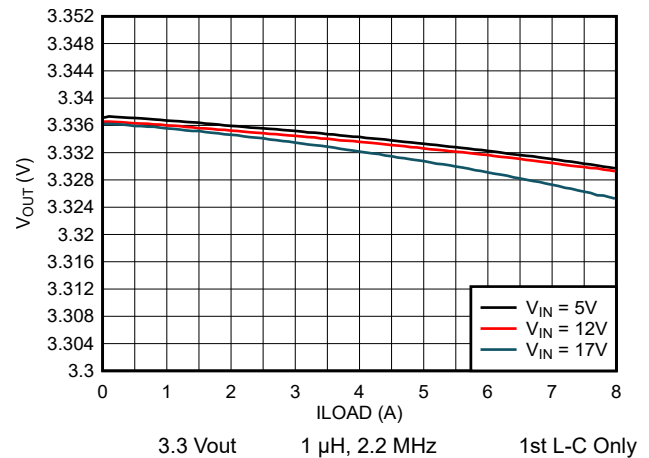


Figure 7-9. Output Voltage vs Load Current

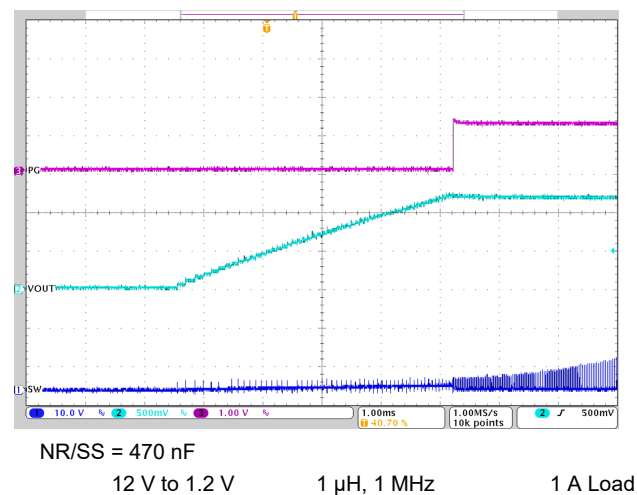


Figure 7-10. Start-up

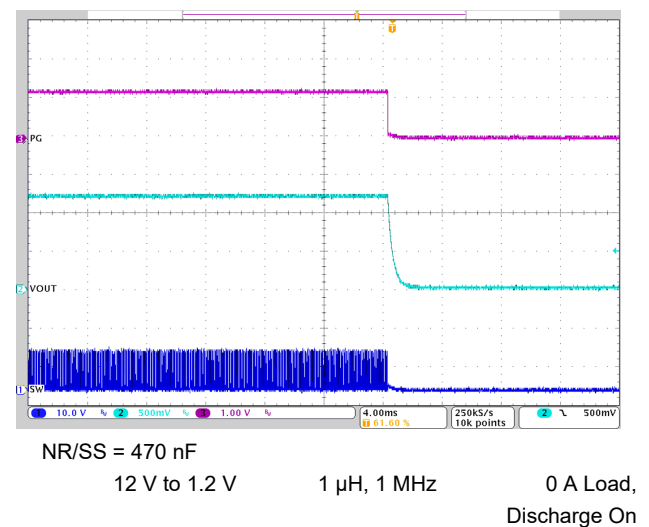


Figure 7-11. Shutdown

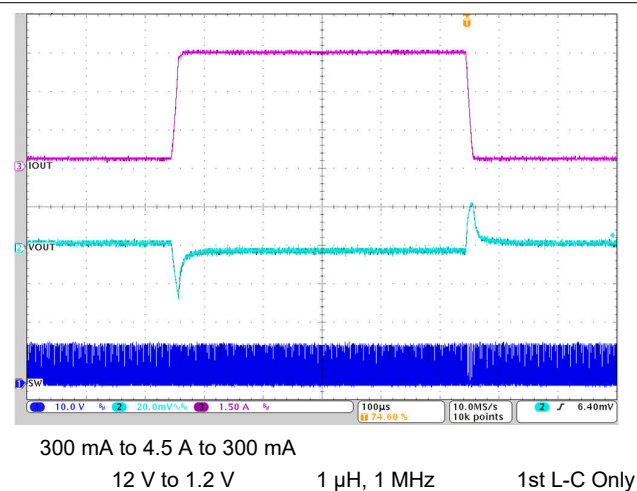


Figure 7-12. Load Transient

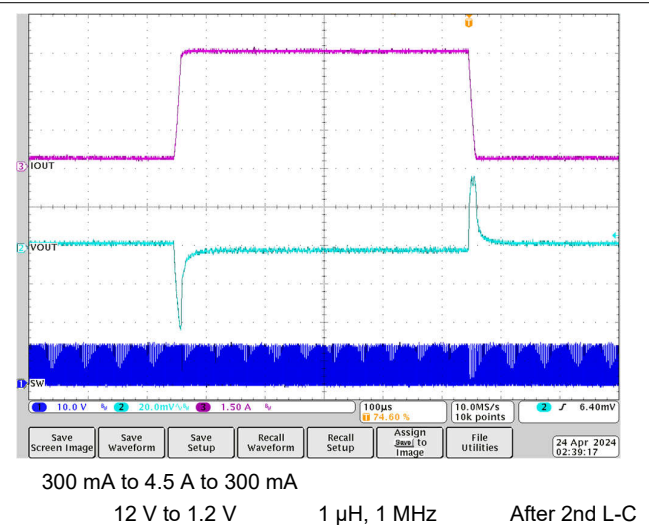
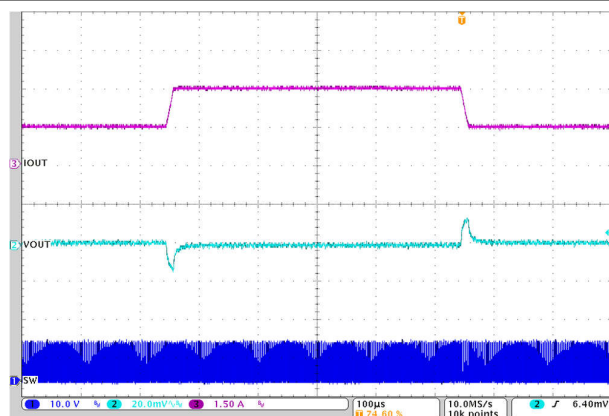
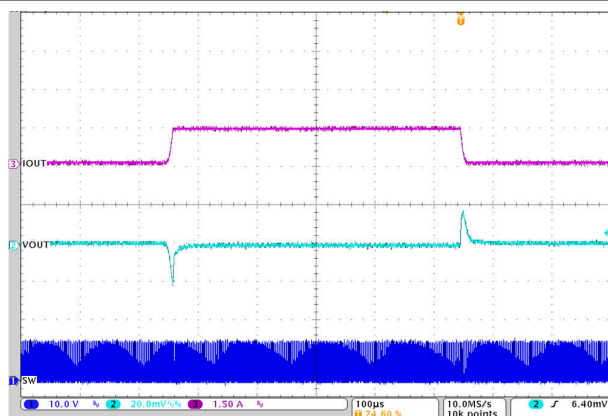


Figure 7-13. Load Transient



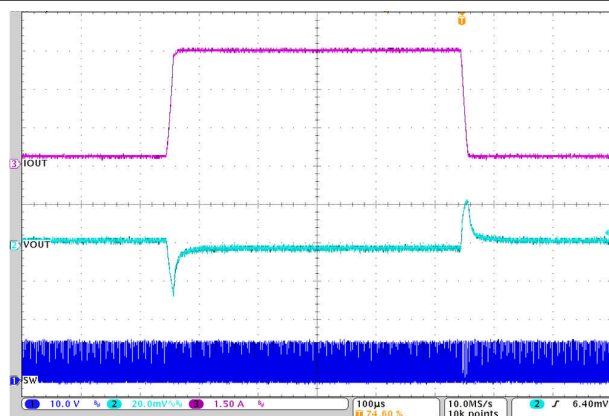
1.5 A to 3 A to 1.5 A
12 V to 1.2 V 1 μ H, 1 MHz After 2nd L-C

図 7-14. Load Transient



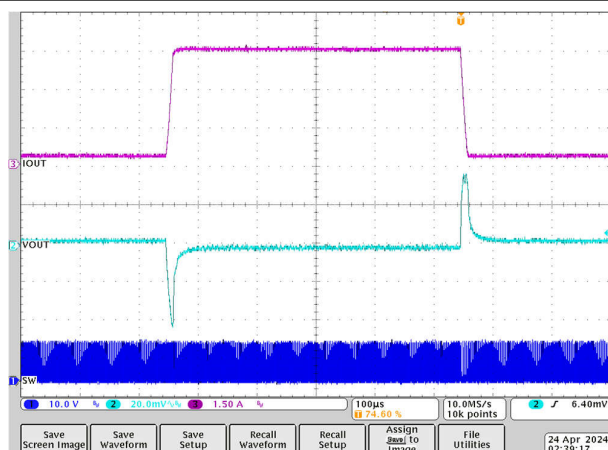
30 mA to 1.5 A to 30 mA
12 V to 1.2 V 1 μ H, 1 MHz After 2nd L-C

図 7-15. Load Transient



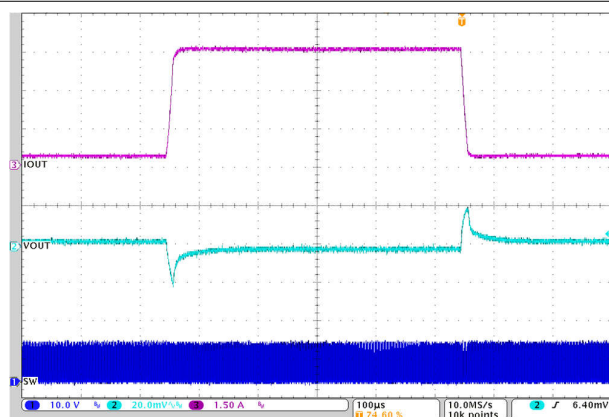
300 mA to 4.5 A to 300 mA
12 V to 1.2 V 1 μ H, 1 MHz 1st L-C Only

図 7-16. Load Transient



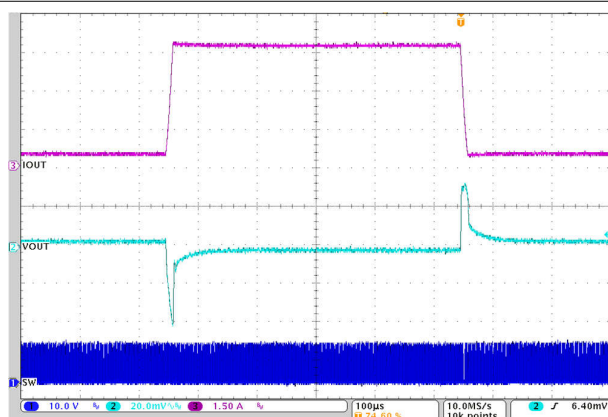
300 mA to 4.5 A to 300 mA
12 V to 1.2 V 1 μ H, 1 MHz After 2nd L-C

図 7-17. Load Transient



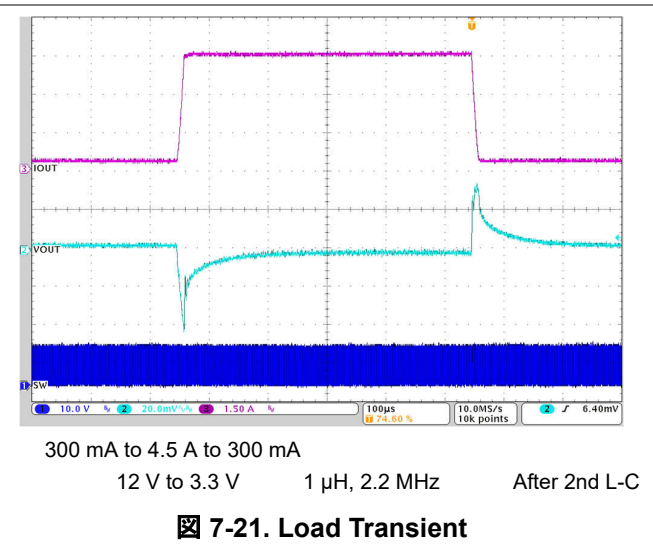
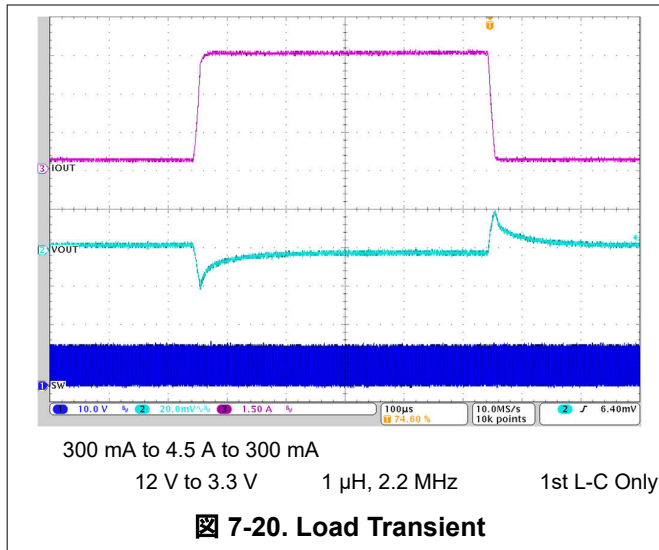
300 mA to 4.5 A to 300 mA
12 V to 1.8 V 1 μ H, 1 MHz 1st L-C Only

図 7-18. Load Transient



300 mA to 4.5 A to 300 mA
12 V to 1.8 V 1 μ H, 1 MHz After 2nd L-C

図 7-19. Load Transient



7.3 Power Supply Recommendations

The power supply to the TPS6291x must have a current rating according to the supply voltage, output voltage, and output current of the TPS6291x.

7.4 Layout

7.4.1 Layout Guidelines

A proper layout is critical for the operation of any switched mode power supply, especially at high switching frequencies. Therefore, the PCB layout of the TPS6291x demands careful attention to make sure of best performance. A poor layout can lead to issues like bad line and load regulation, instability, increased EMI radiation, and noise sensitivity. Refer to the [Five Steps to a Great PCB Layout for a Step-Down Converter analog design journal](#) for a detailed discussion of general best practices. Specific recommendations for the device are listed below.

- Place the input capacitor or capacitors as close as possible to the VIN and PGND pins of the device. This placement is the most critical component placement. Route the input capacitors directly to the VIN and PGND pins avoiding vias.
- Place the inductor close to the SW pin. Minimize the copper area at the switch node.
- Place the output capacitor ground close to the PGND pin and route directly avoiding vias. Minimize the length of the connection from the inductor to the output capacitor.
- Connect the VO pin directly to the first output capacitor, C_{OUT} .
- Connect sensitive traces, such as the connections to the NR/SS, VO, and FB pins with short traces and be routed away from any noise source, such as the SW pin.
- Connect the PSNS pin directly to the system GND plane with a via.
- Place the second L-C filter, L_f and C_f , near the load to reduce any radiated coupling around the second L-C filter
- Avoid placing the ferrite bead in the keep out region as shown in [図 7-23](#)
- Place the FB resistors, R1 and R2, close to the FB pin and route the VOUT connection from R1 to the load as a remote sense trace. If a second L-C filter is used, this connection must be made after L_f .
- See the recommended layout implemented on the EVM and shown in the EVM user's guide, [TPS62916EVM Evaluation Module](#), as well as in [図 7-23](#).

7.4.2 Layout Example

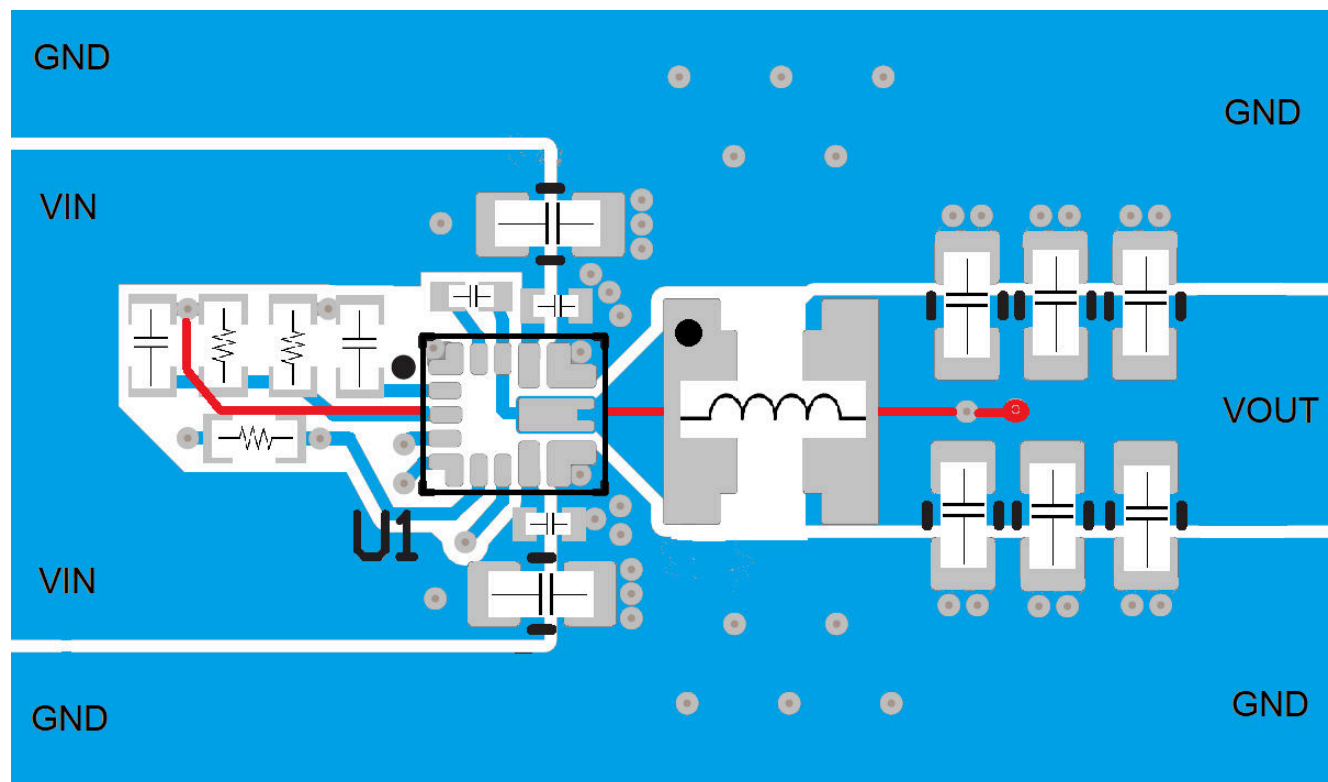


図 7-22. Recommended Layout for Single L-C Filter

注

The start winding of the inductor, as shown in the figures as a black dot, must be connected to the DC/DC converter switch pin, SW, to minimize capacitive coupling to the surrounding area.

注

The red dot indicates where the feedback sense must be placed for the best DC regulation. For a single L-C configuration, the feedback sense is placed near the VOUT capacitors. For a second L-C filter design, the feedback sense is placed near the load after the VOUT_FILT capacitors.

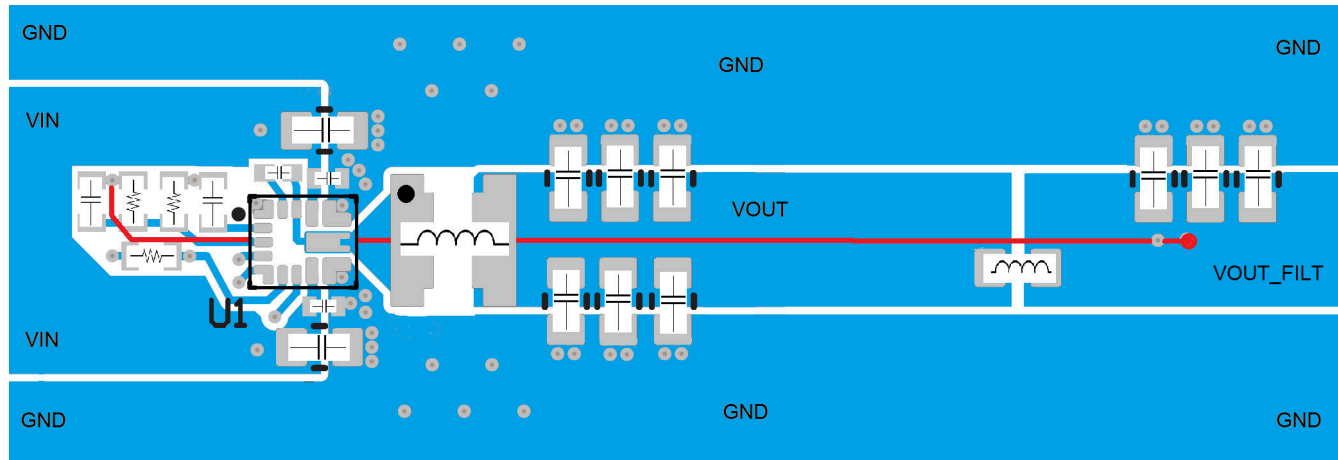


図 7-23. Recommended Layout for Design with Second L-C Filter

注

The ferrite bead can be placed closer to the device as long as it is *not* placed between the inductor and output capacitors. Placing the ferrite bead further away avoids capacitive and electromagnetic coupling to the output of the ferrite bead. If the ferrite bead is placed in the keep out area, the filtering effect of the ferrite bead is greatly reduced. If the ferrite bead is routed through a via to the back side of the board, make sure adequate ground plane between the layers if the ferrite bead are in this area.

8 Device and Documentation Support

8.1 Device Support

8.1.1 サード・パーティ製品に関する免責事項

サード・パーティ製品またはサービスに関するテキサス・インスツルメンツの出版物は、単独またはテキサス・インスツルメンツの製品、サービスと一緒に提供される場合に関係なく、サード・パーティ製品またはサービスの適合性に関する是認、サード・パーティ製品またはサービスの是認の表明を意味するものではありません。

8.1.2 Development Support

8.1.2.1 Custom Design With WEBENCH® Tools

[Click here](#) to create a custom design using the TPS6291x device with the WEBENCH Power Designer.

1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost.
3. Open the advanced tab to optimize for output voltage ripple.
4. After in a TPS6291x design, you can enable the second stage L-C filter and change other settings from the drop-down on the left.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

8.2 Documentation Support

8.2.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, [Pros and Cons Using a Feedforward Capacitor with a Low Dropout Regulator application report](#)
- Texas Instruments, [TPS62916EVM Evaluation Module EVM user's guide](#)
- Texas Instruments, [Five Steps to a Great PCB Layout for a Step-Down Converter analog design journal](#)
- Texas Instruments, [Design Considerations for a Resistive Feedback Divider in a DC/DC Converter analog design journal](#)

8.3 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、www.tij.co.jp のデバイス製品フォルダを開いてください。[通知] をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取ることができます。変更の詳細については、改訂されたドキュメントに含まれている改訂履歴をご覧ください。

8.4 サポート・リソース

テキサス・インスツルメンツ E2E™ サポート・フォーラムは、エンジニアが検証済みの回答と設計に関するヒントをエキスパートから迅速かつ直接得ることができる場所です。既存の回答を検索したり、独自の質問をしたりすることで、設計に必要な支援を迅速に得ることができます。

リンクされているコンテンツは、各寄稿者により「現状のまま」提供されるものです。これらはテキサス・インスツルメンツの仕様を構成するものではなく、必ずしもテキサス・インスツルメンツの見解を反映したものではありません。テキサス・インスツルメンツの[使用条件](#)を参照してください。

8.5 Trademarks

テキサス・インスツルメンツ E2E™ is a trademark of Texas Instruments.

WEBENCH® is a registered trademark of Texas Instruments.

すべての商標は、それぞれの所有者に帰属します。

8.6 静電気放電に関する注意事項



この IC は、ESD によって破損する可能性があります。テキサス・インスツルメンツは、IC を取り扱う際には常に適切な注意を払うことを推奨します。正しい取り扱いおよび設置手順に従わない場合、デバイスを破損するおそれがあります。

ESD による破損は、わずかな性能低下からデバイスの完全な故障まで多岐にわたります。精密な IC の場合、パラメータがわずかに変化するだけで公表されている仕様から外れる可能性があるため、破損が発生しやすくなっています。

8.7 用語集

[テキサス・インスツルメンツ用語集](#) この用語集には、用語や略語の一覧および定義が記載されています。

9 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from Revision B (April 2024) to Revision C (June 2024)	Page
--	------

- | | |
|--|---|
| • TPS62918 および TPS62914 から事前情報の注を削除..... | 1 |
|--|---|

Changes from Revision A (December 2023) to Revision B (April 2024)	Page
--	------

- | | |
|--|---|
| • ドキュメントのステータスを「事前情報」から「量産データ」に変更..... | 1 |
|--|---|

Changes from Revision * (November 2023) to Revision A (December 2023)	Page
---	------

- | | |
|---|---|
| • TPS62918 および TPS62914 からプレビューの注を削除..... | 1 |
|---|---|

10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

重要なお知らせと免責事項

テキサス・インスツルメンツは、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス デザインを含みます)、アプリケーションや設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供しており、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的にかかわらず拒否します。

これらのリソースは、テキサス・インスツルメンツ製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した テキサス・インスツルメンツ製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあらゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとします。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている テキサス・インスツルメンツ製品を使用するアプリケーションの開発の目的でのみ、テキサス・インスツルメンツはその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載することは禁止されています。テキサス・インスツルメンツや第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、テキサス・インスツルメンツおよびその代理人を完全に補償するものとし、テキサス・インスツルメンツは一切の責任を拒否します。

テキサス・インスツルメンツの製品は、[テキサス・インスツルメンツの販売条件](#)、または [ti.com](https://www.ti.com) やかかる テキサス・インスツルメンツ製品の関連資料などのいずれかを通じて提供する適用可能な条項の下で提供されています。テキサス・インスツルメンツがこれらのリソースを提供することは、適用されるテキサス・インスツルメンツの保証または他の保証の放棄の拡大や変更を意味するものではありません。

お客様がいかなる追加条項または代替条項を提案した場合でも、テキサス・インスツルメンツはそれらに異議を唱え、拒否します。

郵送先住所: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2024, Texas Instruments Incorporated

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TPS62914RPYR	Active	Production	VQFN-HR (RPY) 14	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 150	T62914
TPS62914RPYR.A	Active	Production	VQFN-HR (RPY) 14	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 150	T62914
TPS62916RPYR	Active	Production	VQFN-HR (RPY) 14	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 150	T62916
TPS62916RPYR.A	Active	Production	VQFN-HR (RPY) 14	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 150	T62916
TPS62918RPYR	Active	Production	VQFN-HR (RPY) 14	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 150	T62918
TPS62918RPYR.A	Active	Production	VQFN-HR (RPY) 14	3000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 150	T62918

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

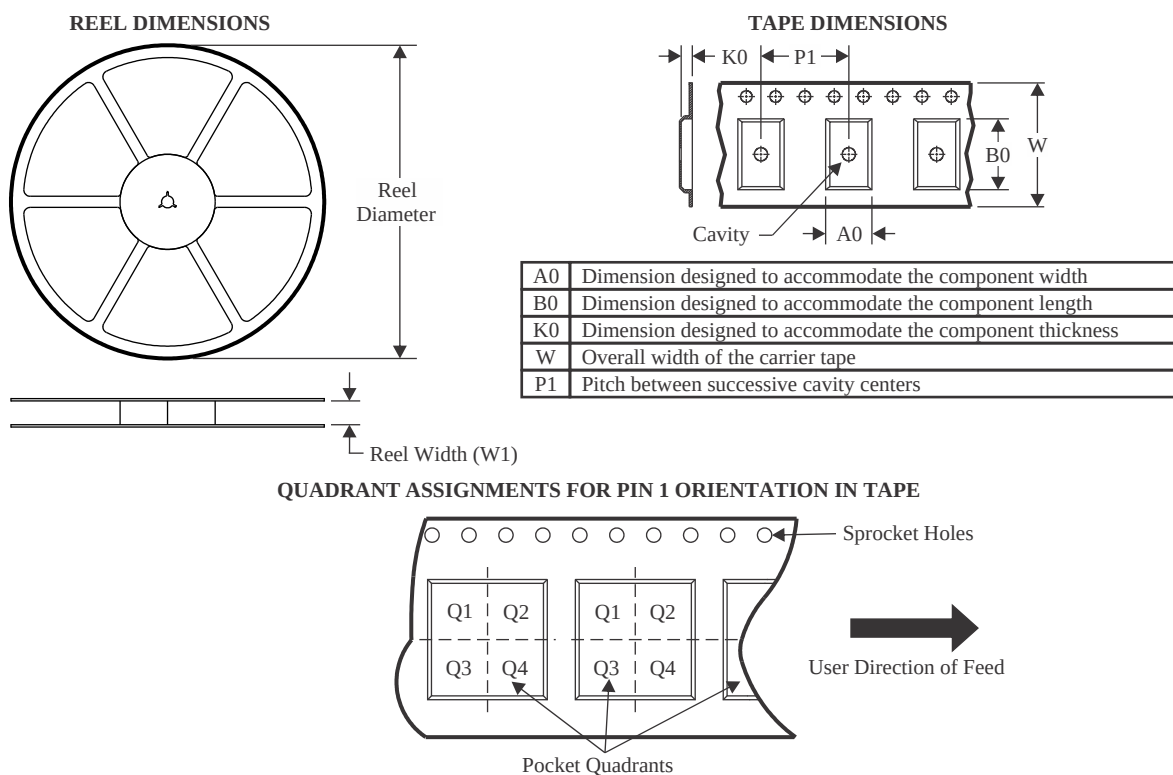
OTHER QUALIFIED VERSIONS OF TPS62914, TPS62916, TPS62918 :

- Automotive : [TPS62914-Q1](#), [TPS62916-Q1](#), [TPS62918-Q1](#)

NOTE: Qualified Version Definitions:

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

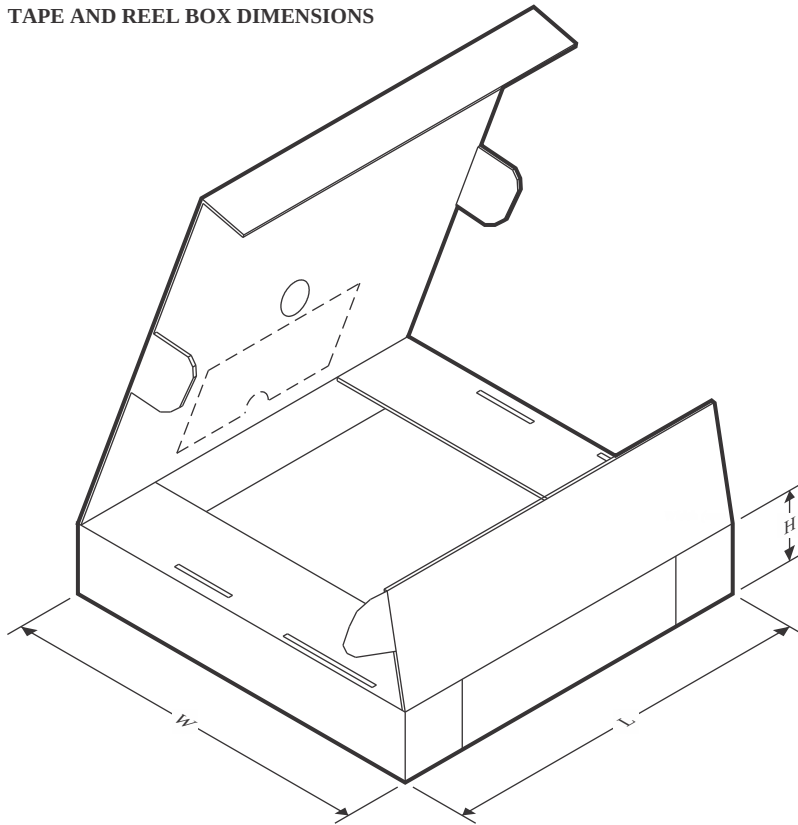
TAPE AND REEL INFORMATION



*All dimensions are nominal

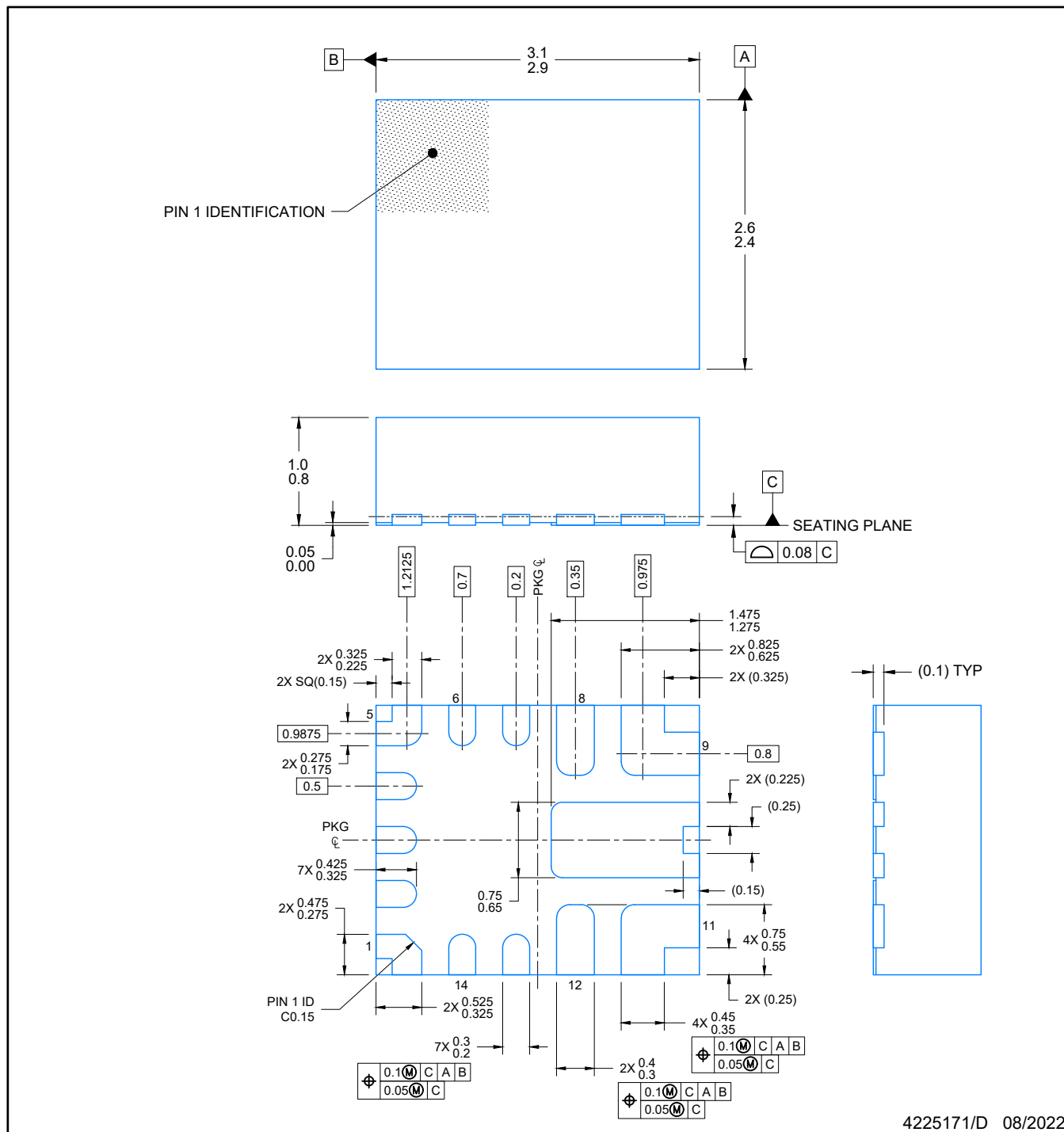
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS62914RPYR	VQFN-HR	RPY	14	3000	180.0	12.4	2.8	3.3	1.1	4.0	12.0	Q2
TPS62916RPYR	VQFN-HR	RPY	14	3000	180.0	12.4	2.8	3.3	1.1	4.0	12.0	Q2
TPS62918RPYR	VQFN-HR	RPY	14	3000	180.0	12.4	2.8	3.3	1.1	4.0	12.0	Q2

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

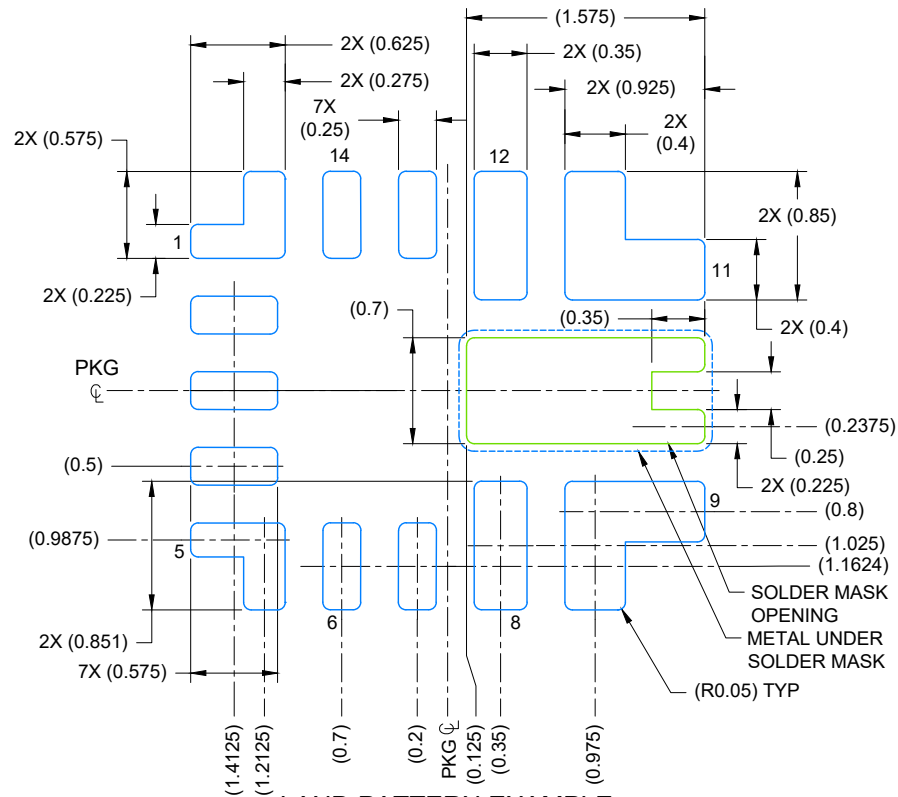
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS62914RPYR	VQFN-HR	RPY	14	3000	210.0	185.0	35.0
TPS62916RPYR	VQFN-HR	RPY	14	3000	210.0	185.0	35.0
TPS62918RPYR	VQFN-HR	RPY	14	3000	210.0	185.0	35.0



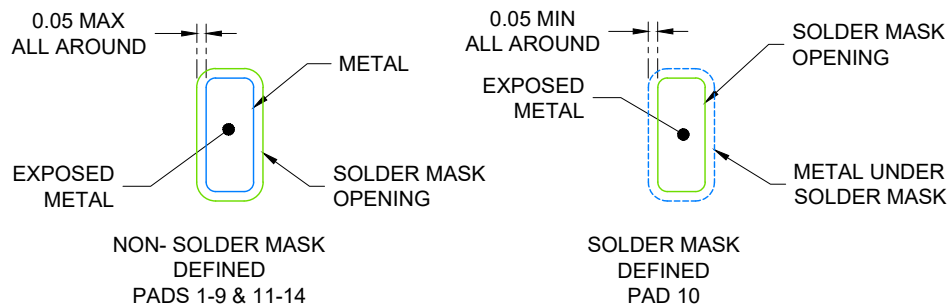
4225171/D 08/2022

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 20X



SOLDER MASK DETAILS
NOT TO SCALE

4225171/D 08/2022

NOTES: (continued)

3. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/sluea271).
4. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

SOLDER PASTE COVERAGE:
PIN 1 & 5: 93%; PIN 9 & 11: 91%; PIN 10: 96%
SCALE: 20X

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

重要なお知らせと免責事項

テキサス・インスツルメンツは、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス デザインを含みます)、アプリケーションや設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供しており、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的にかかわらず拒否します。

これらのリソースは、テキサス・インスツルメンツ製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した テキサス・インスツルメンツ製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあらゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとします。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている テキサス・インスツルメンツ製品を使用するアプリケーションの開発の目的でのみ、テキサス・インスツルメンツはその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載することは禁止されています。テキサス・インスツルメンツや第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、テキサス・インスツルメンツおよびその代理人を完全に補償するものとし、テキサス・インスツルメンツは一切の責任を拒否します。

テキサス・インスツルメンツの製品は、[テキサス・インスツルメンツの販売条件](#)、または [ti.com](https://www.ti.com) やかかる テキサス・インスツルメンツ製品の関連資料などのいずれかを通じて提供する適用可能な条項の下で提供されています。テキサス・インスツルメンツがこれらのリソースを提供することは、適用される テキサス・インスツルメンツの保証または他の保証の放棄の拡大や変更を意味するものではありません。

お客様がいかなる追加条項または代替条項を提案した場合でも、テキサス・インスツルメンツはそれらに異議を唱え、拒否します。

郵送先住所：Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2025, Texas Instruments Incorporated