

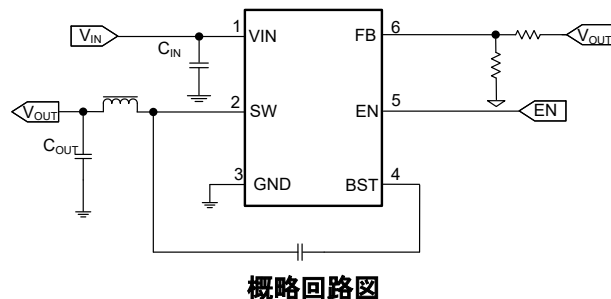
TPS56124x 4.2V~17V 入力、1A、同期整流型降圧コンバータ、SOT563 パッケージ

1 特長

- 多様なアプリケーションに適した構成
 - 入力電圧範囲: 4.2V~17V
 - 出力電圧範囲: 0.6V~7V
 - 基準電圧: 0.6V
 - 基準電圧精度: $\pm 1.5\%$
 - FET 内蔵: 100m Ω 、55m Ω
 - TPS561243 の低静止時電流: 110 μ A
 - スイッチング周波数: 1280kHz
 - 最大 95% の高デューティ サイクル動作
 - 固定ソフトスタート時間: 1.4ms
- 使いやすく小さい設計サイズ
 - TPS561243 Eco モード、TPS561246 FCCM モード (軽負荷時)
 - 高速過渡応答の D-CAP3™ 制御モード
 - あらかじめ出力にバイアスが印加された状態でのスタートアップをサポート
 - ラッチなしの OT および UVLO 保護
 - サイクル単位の過電流制限
 - ヒカップ モードによる UV 保護
 - 動作時の接合部温度範囲: -40°C~125°C
 - SOT563 パッケージ: 1.6mm × 1.6mm
- WEBENCH® Power Designer により、TPS56124x を使用するカスタム設計を作成

2 アプリケーション

- WLAN / Wi-Fi アクセス ポイント
- モデム (ケーブル/DSL/GFAST)
- 小規模企業向けルータ
- 電気メータ
- STV および DVR
- 電化製品



3 概要

TPS56124x はシンプルで使いやすい、同期整流降圧コンバータであり、入力電圧範囲は 4.2V~17V で、最大 1A の連続電流に対応しています。

最小の外付け部品数で動作し、スタンバイ電流が小さくなるよう設計されています。

このスイッチ モード電源 (SMPS) デバイスは、D-CAP3 制御モードを採用し、高速の過渡応答を実現します。また、特殊ポリマーなど ESR (等価直列抵抗) の低い出力コンデンサと、超低 ESR のセラミック コンデンサの両方を、外部補償部品なしでサポートします。

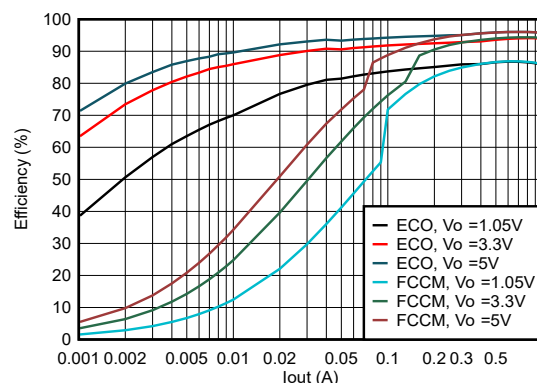
TPS561243 は Eco モードで動作し、軽負荷での動作時にも高い効率を維持します。TPS561246 は FCCM モードで動作することで、すべての負荷条件で同じ周波数と小さい出力リップルを維持します。TPS56124x は、OCP、UVLO、OTP、UVP (ヒカップ機能付き) による完全な保護機能を備えています。

TPS56124x は 6 ピン、1.6mm × 1.6mm の SOT563 (DRL) パッケージで供給されます。接合部温度の仕様は -40°C~125°C です。

製品情報

部品番号	モード	パッケージ ⁽¹⁾	パッケージ サイズ ⁽²⁾
TPS561243	ECO モード	DRL (SOT563, 6)	1.60mm × 1.60mm
TPS561246	FCCM モード		

- 詳細については、[セクション 10](#) を参照してください。
- パッケージ サイズ (長さ × 幅) は公称値であり、該当する場合はピンも含まれます。



TPS56124x の効率 (Vin = 12V)



Table of Contents

1 特長	1	7 Application and Implementation	13
2 アプリケーション	1	7.1 Application Information.....	13
3 概要	1	7.2 Typical Application.....	13
4 Pin Configuration and Functions	3	7.3 Power Supply Recommendations.....	18
5 Specifications	4	7.4 Layout.....	18
5.1 Absolute Maximum Ratings.....	4	8 Device and Documentation Support	20
5.2 ESD Ratings.....	4	8.1 Device Support.....	20
5.3 Recommended Operating Conditions.....	4	8.2 ドキュメントの更新通知を受け取る方法.....	20
5.4 Thermal Information.....	5	8.3 サポート・リソース.....	20
5.5 Electrical Characteristics.....	5	8.4 Trademarks.....	20
5.6 Typical Characteristics.....	7	8.5 静電気放電に関する注意事項.....	20
6 Detailed Description	9	8.6 用語集.....	20
6.1 Overview.....	9	9 Revision History	20
6.2 Functional Block Diagram.....	9	10 Mechanical, Packaging, and Orderable Information	21
6.3 Feature Description.....	9		
6.4 Device Functional Modes.....	12		

4 Pin Configuration and Functions

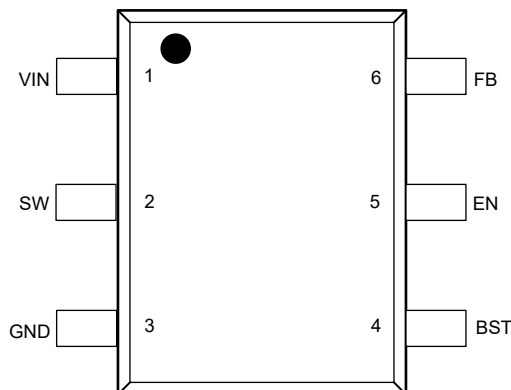


図 4-1. 6-Pin SOT563 DRL Package (Top View)

表 4-1. Pin Functions

PIN		TYPE ⁽¹⁾	DESCRIPTION
NAME	NO.		
VIN	1	I	Input voltage supply pin
SW	2	O	Switch node connection between high-side NFET and low-side NFET
GND	3	—	Ground pin source terminal of low-side power NFET, as well as the ground terminal for the control circuit. Connect sensitive FB to this GND at a single point.
BST	4	O	Supply input for the high-side NFET gate drive circuit. Connect a 0.1μF capacitor between the BST and SW pin.
EN	5	I	Enable input control. Active high and must be pulled up to enable the device.
FB	6	I	Converter feedback input. Connect to the output voltage with feedback resistor divider.

(1) I = input, O = output

5 Specifications

5.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
Input voltage	VIN	−0.3	19	V
Input voltage	FB, EN	−0.3	6	V
Input voltage	GND	−0.3	0.3	V
Output voltage	BST	−0.3	25	V
Output voltage	BST (< 20ns)	−0.3	27	V
Output voltage	SW	−2	19	V
Output voltage	SW (< 20ns)	−6.5	21	V
Operating junction temperature range, T _J		−40	150	°C
Storage temperature, T _{stg}	Storage temperature, T _{stg}	−55	150	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

5.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±2000	V
		Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002 ⁽²⁾	±500	

- (1) JEDEC document JEP155 states that 500V HBM allows safe manufacturing with a standard ESD control process.

- (2) JEDEC document JEP157 states that 250V CDM allows safe manufacturing with a standard ESD control process.

5.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Input voltage	VIN	4.2		17	V
Input voltage	FB, EN	−0.1		5.5	V
Input voltage	GND	−0.1		0.1	V
Output voltage	BST	−0.1		23	V
Output voltage	BST (< 20ns)	−0.1		25	V
Output voltage	SW	−1		17	V
Output voltage	SW (< 20ns)	−6		19	V
Output Current	IO	0		1	A
T _J	Operating junction temperature	−40		125	°C
T _{stg}	Storage temperature	−40		150	°C

5.4 Thermal Information

THERMAL METRIC ⁽¹⁾		DRL (SOT-563)	UNIT
		6 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	147.4	°C/W
$R_{\theta JA_effective}$	Junction-to-ambient thermal resistance on EVM board	73 ⁽²⁾	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	75.7	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	32.2	°C/W
Ψ_{JT}	Junction-to-top characterization parameter	2.1	°C/W
Y_{JB}	Junction-to-board characterization parameter	31.8	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application note.
- (2) This $R_{\theta JA_effective}$ is tested on TPS562243EVM board (2 layer, copper thickness of top and bottom layer are 2oz) at $T_A = 25^{\circ}\text{C}$.

5.5 Electrical Characteristics

Over operating $T_J = -40^{\circ}\text{C} - 125^{\circ}\text{C}$, $V_{IN} = 12\text{ V}$ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
INPUT SUPPLY VOLTAGE						
V_{IN}	Input voltage range		4.2		17	V
I_{VIN}	VIN supply current	No load, $V_{EN} = 1.5\text{ V}$, non-switching, ECO version		110		μA
		No load, $V_{EN} = 1.5\text{ V}$, $V_{FB} = 0.9\text{ V}$, FCCM version ⁽¹⁾		350		μA
I_{INSDN}	VIN shutdown current	$V_{EN} = 0\text{ V}$		7		μA
UVLO						
UVLO	VIN undervoltage lockout	Wake up VIN voltage	3.6	3.8	4	V
UVLO	VIN undervoltage lockout	Shut down VIN voltage	3.2	3.4	3.6	V
UVLO	VIN undervoltage lockout	Hysteresis VIN voltage		400		mV
FEEDBACK VOLTAGE						
V_{FB}	FB voltage	$T_J = 25^{\circ}\text{C}$, $V_{in} = 4.2 - 17\text{ V}$	591	600	609	mV
V_{FB}	FB voltage	$T_J = -40^{\circ}\text{C}$ to 125°C , $V_{in} = 4.2 - 17\text{ V}$	588	600	612	mV
MOSFET						
$R_{DS(ON)HI}$	High-side MOSFET $R_{ds(on)}$	$T_J = 25^{\circ}\text{C}$		100		m Ω
$R_{DS(ON)LO}$	Low-side MOSFET $R_{ds(on)}$	$T_J = 25^{\circ}\text{C}$		55		m Ω
DUTY CYCLE and FREQUENCY CONTROL						
F_{SW}	Switching frequency	$V_{OUT} = 3.3\text{ V}$		1280		kHz
$T_{OFF(MIN)}$	Minimum off-time ⁽¹⁾	$V_{FB} = 0.5\text{ V}$		100		ns
$T_{ON(MIN)}$	Minimum on-time ⁽¹⁾			55		ns
CURRENT LIMIT						
I_{OCL_LS}	Over current threshold	Valley current set point	1.2	2.8	3.6	A
I_{NOCL}	Negative over current threshold	Valley current set point	1	1.8	2.5	A
LOGIC THRESHOLD						
$V_{EN(ON)}$	EN threshold high-level		1.15	1.2	1.28	V
$V_{EN(OFF)}$	EN threshold low-level		0.93	1	1.05	V
V_{ENHYS}	EN hysteresis			200		mV

5.5 Electrical Characteristics (続き)

Over operating $T_J = -40^{\circ}\text{C} - 125^{\circ}\text{C}$, $V_{IN} = 12\text{ V}$ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
OUTPUT DISCHARGE and SOFT START						
I_{EN}	EN pulldown current	$V_{EN} = 1.5\text{ V}$		1		μA
t_{SS}	Internal soft start time	V_{OUT} from 0 to target value.		1.4		ms
OUTPUT UNDERVOLTAGE AND OVERVOLTAGE PROTECTION						
V_{UVP}	UVP trip threshold		55	60	65	%
t_{UVPDLY}	UVP prop deglitch			256		μs
t_{UVPON}	In continus hiccup mode, the switching time	Hard short, UVP detect		1.5		ms
t_{UVPOFF}	In continus hiccup mode, non switching time	Hard short, UVP detect		13		ms
THERMAL PROTECTION						
T_{OTP}	OTP trip threshold			155		$^{\circ}\text{C}$
T_{OTPHSY}	OTP hysteresis			20		$^{\circ}\text{C}$

(1) Specified by design

5.6 Typical Characteristics

$V_{IN} = 12V$ (unless otherwise noted)

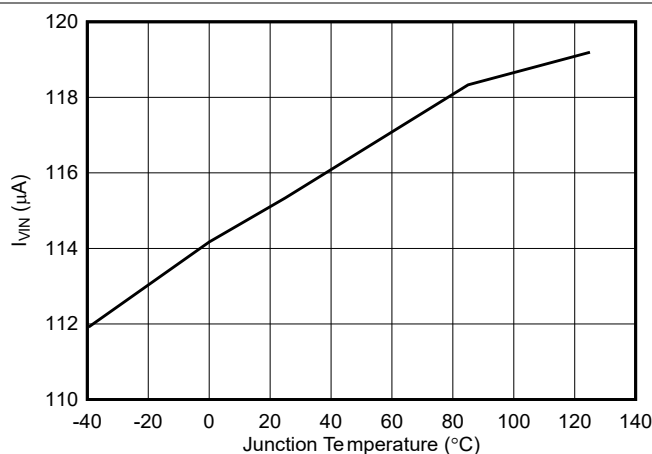


図 5-1. TPS561243 Quiescent Current

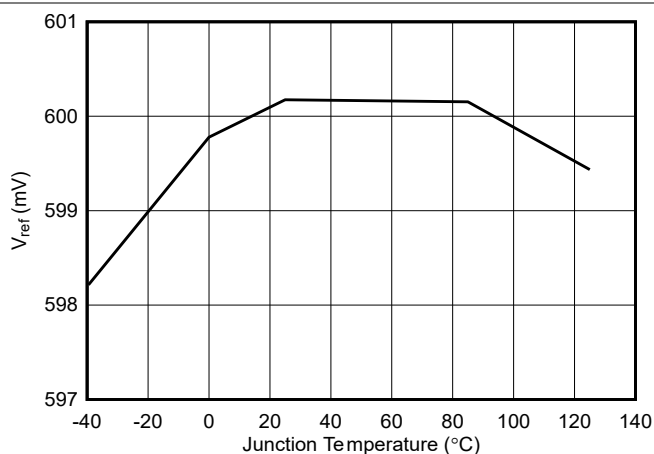


図 5-2. Vref Voltage

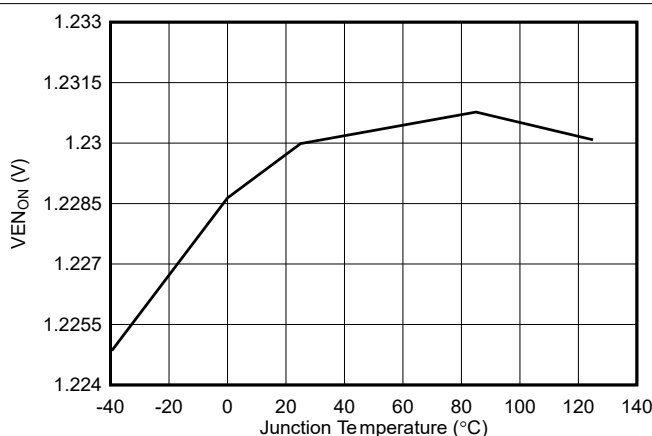


図 5-3. Enable On Threshold Voltage

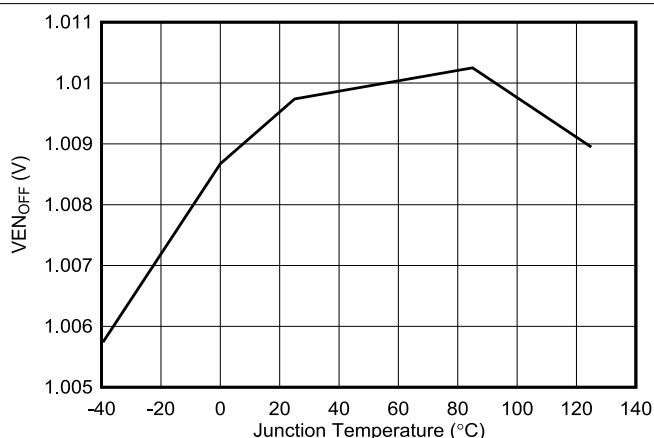


図 5-4. Enable Off Threshold Voltage

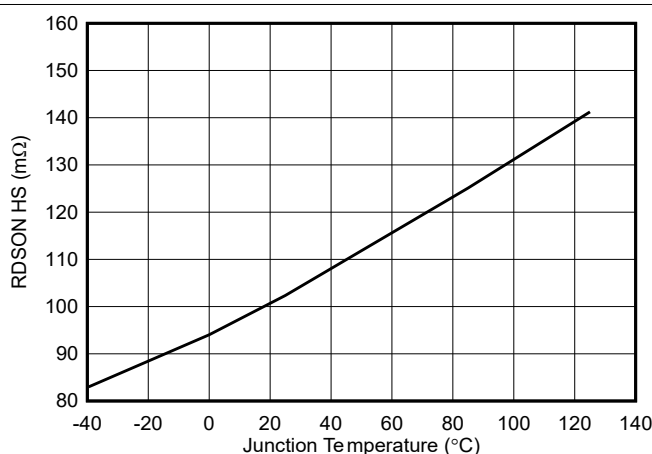


図 5-5. Low-Side Rdson

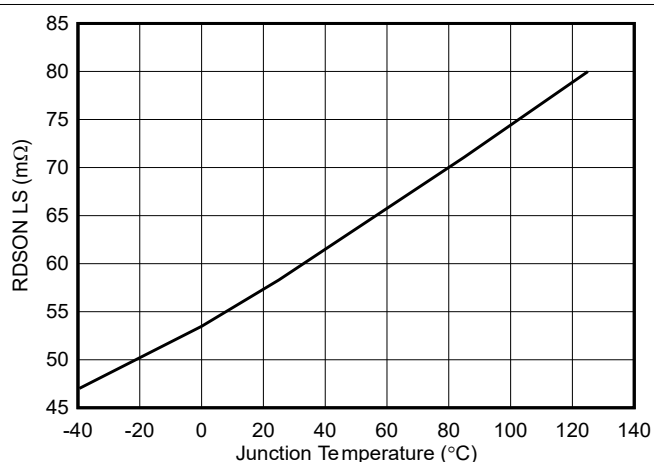


図 5-6. High-Side Rdson

5.6 Typical Characteristics (continued)

$V_{IN} = 12V$ (unless otherwise noted)

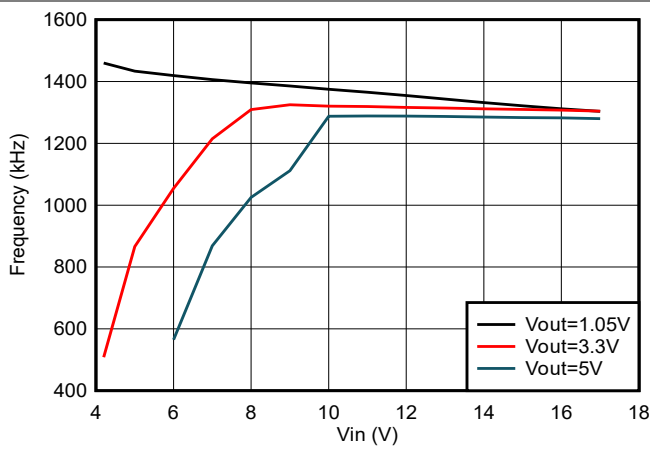


図 5-7. Frequency vs Input Voltage at 1A Loading

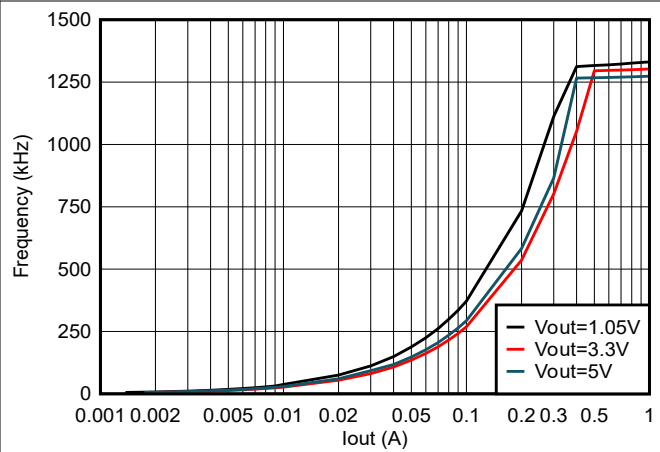


図 5-8. TPS561243 Frequency vs Loading

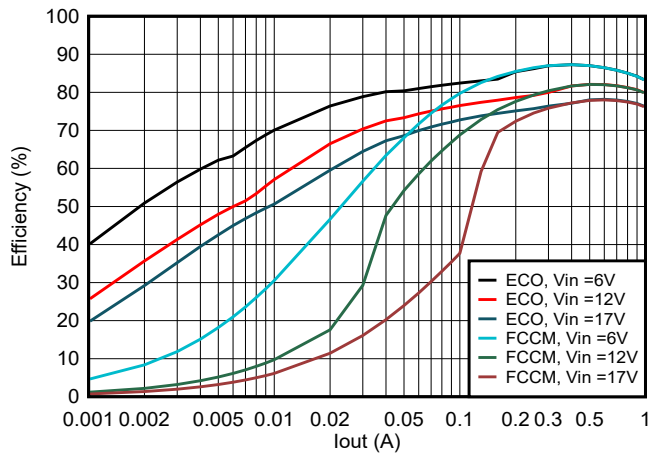


図 5-9. TPS56124x Efficiency at 0.6 Vout With 1uH inductor

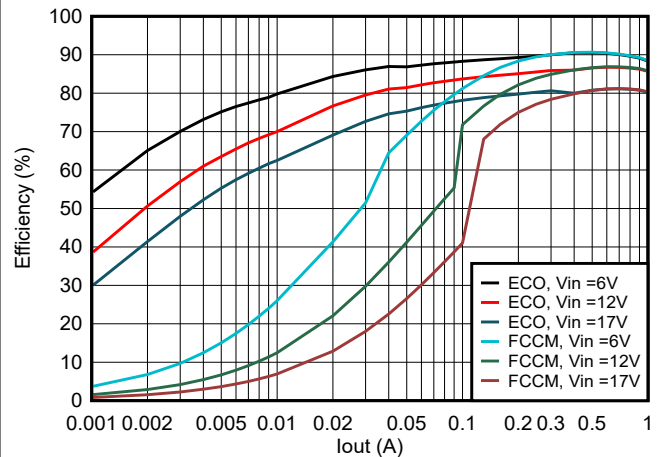


図 5-10. TPS56124x Efficiency at 1.05 Vout With 1.2uH Inductor

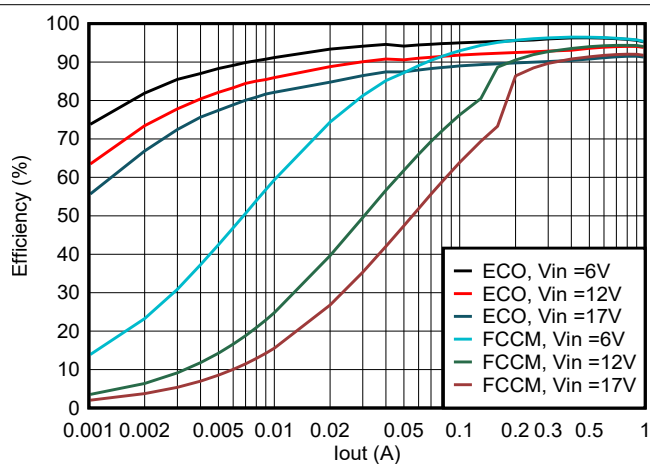


図 5-11. TPS56124x Efficiency at 3.3 Vout With 2.2uH Inductor

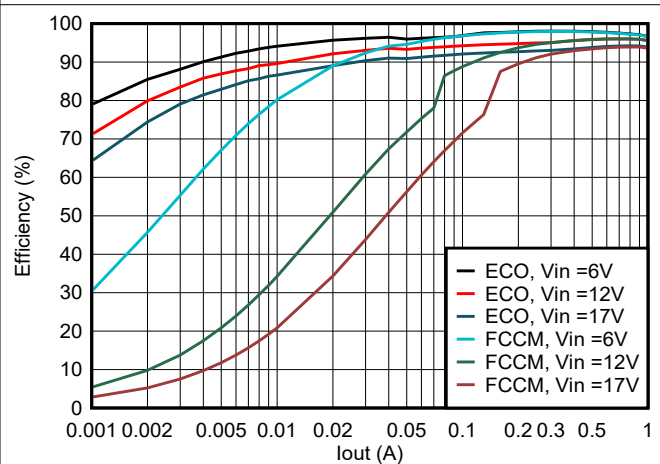


図 5-12. TPS56124x Efficiency at 5 Vout With 3.3uH Inductor

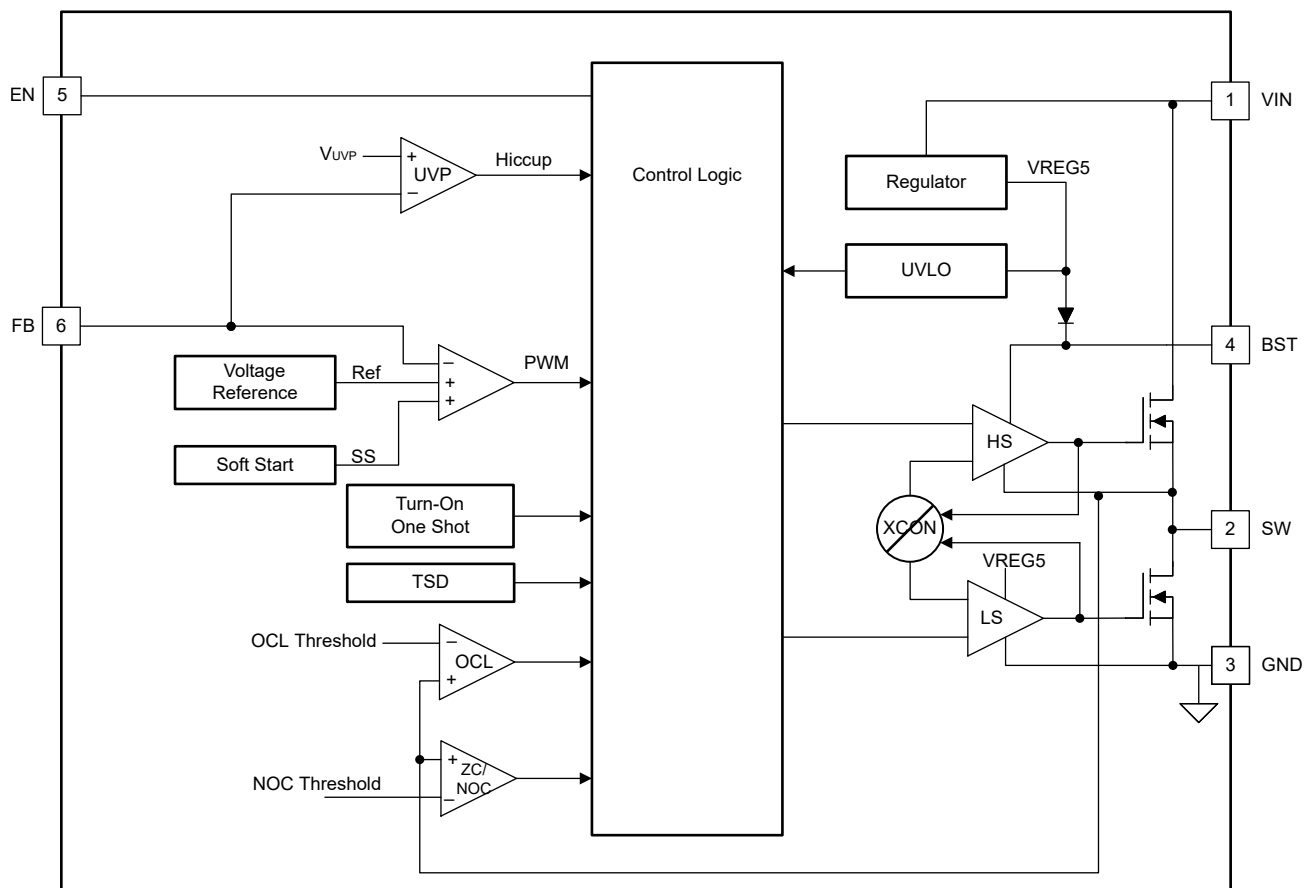
6 Detailed Description

6.1 Overview

The TPS56124x is a 1A, integrated FETs, synchronous step-down buck converter that can operate from 4.2V to 17V input voltage and 0.6V to 7V output voltage. The device employs D-CAP3 control mode that provides an accurate feedback voltage and a fast transient response with no external compensation components. The proprietary D-CAP3 control mode enables low external component count, ease of design, and optimization of the power design for cost, size, and efficiency. The topology provides a seamless transition between CCM operating mode at higher load condition and DCM operation at lighter load condition.

The Eco-mode version allows the TPS561243 to maintain high efficiency at light load. The FCCM mode version allows the TPS561246 to maintain a fixed switching frequency and lower output voltage ripple. The TPS56124x is able to adapt to both low equivalent series resistance (ESR) output capacitors such as POSCAP or SP-CAP and ultra-low ESR ceramic capacitors.

6.2 Functional Block Diagram



6.3 Feature Description

6.3.1 Adaptive On-Time Control and PWM Operation

The TPS56124x implements D-CAP3 control scheme that supports adaptive on-time pulse width modulation (PWM) control with an internal compensation circuit for pseudo-fixed frequency and low external component count configuration, with both low-ESR and ceramic output capacitors. The D-CAP3 control scheme is stable even with virtually no ripple at the output. The TPS56124x also includes an error amplifier that makes the output voltage very accurate.

At the beginning of each cycle, the high-side MOSFET is turned on. This MOSFET is turned off after the internal one shot timer expires. This one shot duration is set proportional to the output voltage, V_O , and inversely proportional to the converter input voltage, V_{IN} , to maintain a pseudo-fixed frequency over the input voltage range, hence called adaptive on-time control. The one-shot timer is reset and the high-side MOSFET is turned on again when the feedback voltage falls below the reference voltage. An internal ramp is added to reference voltage to simulate output ripple, eliminating the need for ESR induced output ripple from D-CAP3 control scheme.

6.3.2 Eco-mode Control

The TPS561243 is designed with advanced Eco-mode to maintain high light load efficiency. As the output current decreases from heavy load condition, the inductor current is also reduced and eventually comes to a point that the ripple valley touches zero level, which is the boundary between continuous conduction and discontinuous conduction modes. The rectifying MOSFET is turned off when the zero inductor current is detected. As the load current further decreases, the converter runs into discontinuous conduction mode. The on-time is kept almost the same as in the continuous conduction mode so that discharging the output capacitor with smaller load current to the level of the reference voltage takes a longer time. This action makes the switching frequency lower, proportional to the load current, and keeps the light load efficiency high. Use 式 1 to calculate the transition point to the light load operation $I_{OUT(LL)}$ current.

$$I_{out(LL)} = \frac{1}{2 \times L \times f_{SW}} \times \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{V_{IN}} \quad (1)$$

6.3.3 Soft Start and Prebiased Soft Start

The TPS56124x has an internal 1.4ms soft start. When the EN pin becomes high, the internal soft start function begins ramping up the reference voltage to the PWM comparator.

If the output capacitor is prebiased at start-up, the device initiates switching and start ramping up only after the internal reference voltage becomes greater than the feedback voltage V_{FB} . This scheme makes sure that the converters ramp up smoothly into the regulation point.

6.3.4 Large Duty Operation

The TPS56124x can support large duty operations up to 95% by smoothly dropping down the switching frequency. When input voltage $V_{IN} < 7V$ and V_{FB} is lower than internal reference voltage, the switching frequency is allowed to smoothly drop to make T_{ON} extended to keep output voltage and improve the load transient performance. The minimum switching frequency is limited to about 400kHz.

6.3.5 Current Protection

The output overcurrent limit (OCL) is implemented using a cycle-by-cycle valley detect control circuit. The switch current is monitored during the OFF state by measuring the low side FET drain to source voltage. This voltage is proportional to the switch current. To improve the accuracy, the voltage sensing is temperature compensated.

During the on time of the high side FET switch, the switch current increases with a linear rate determined by V_{IN} , V_{OUT} , the on-time and the output inductor value. During the on time of the low side FET switch, this current decreases linearly. The average value of the switch current is the load current I_{out} . If the monitored current is above the OCL level, the converter maintains low side FET on and delays the creation of a new set pulse, even the voltage feedback loop requires one, until the current level becomes OCL level or lower. In subsequent switching cycles, the on-time is set to a fixed value and the current is monitored in the same manner.

There are some important considerations for this type of overcurrent protection. The load current is higher than the overcurrent threshold by one half of the peak-to-peak inductor ripple current. Also, when the current is being limited, the output voltage tends to fall as the demanded load current can be higher than the current available from the converter. This event can even cause the output voltage to fall. When the FB voltage falls below the UVP threshold voltage, the UVP comparator detects the fall. Then, the device shuts down after the UVP delay time and re-starts after the hiccup time.

When the overcurrent condition is removed, the output voltage returns to the regulated value.

The TPS561246 is an FCCM mode part. In this mode, the device has negative inductor current at light load. The device has NOC (negative overcurrent) protection to avoid too large negative current. NOC protection detects the valley of inductor current. When the valley value of inductor current exceeds the NOC threshold, the IC turns off the low side then turns on the high side. When NOC protection is triggered eight times continuously, IC turns off both high side FET and low side FET. When the NOC condition is removed and output voltage returns to the target value, the device returns to normal switching.

Because the TPS561246 is an FCCM mode part, if the inductance is so small that the device triggers NOC, the output voltage becomes higher than the target value. The minimum inductance is identified as 式 2.

$$L = \frac{V_{out} \times \left(1 - \frac{V_{out}}{V_{in}}\right)}{2 \times \text{Frequency} \times \text{NOC}_{min}} \quad (2)$$

6.3.6 Enable Circuit

The EN pin controls the turn-on and turn-off of the device. When the EN pin voltage is above the turn-on threshold, the device starts switching. When the EN pin voltage falls below the turn-off threshold, the device stops switching. The default status is low because there is a 1uA pulldown current in internal IC.

EN can be controlled by a typical resistor divider circuit from Vin or by a voltage of lower than 5.5V.

The TPS56124x also allows EN to connect to Vin with a pullup resistor only. TI suggests the value of the pullup resistor be 100kohm as EN voltage is clamped by a Zener diode and this Zener diode is not allowed to go through large current. The pullup resistor R1 is not allowed to be smaller than 80kohm, and TI suggests R1 also not be too large to avoid EN not being able to turn on. The recommended value range for the pullup resistor R1 is 80kohm to 3Mohm and 100kohm is the best recommended choice.

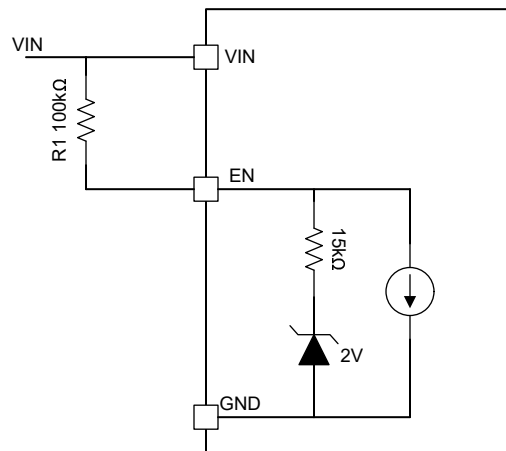


図 6-1. EN Block Circuit

6.3.7 Undervoltage Lockout (UVLO) Protection

UVLO protection monitors the internal regulator voltage. When the voltage is lower than UVLO threshold voltage, the device is shut off. This protection is non-latching.

6.3.8 Thermal Shutdown

The device monitors the temperature of the device. If the temperature exceeds the threshold value (typically 155°C), the device is shut off. This protection is a non-latch protection.

6.4 Device Functional Modes

6.4.1 Eco-mode Operation

The TPS561243 operates in Eco-mode, which maintains high efficiency at light load. As the output current decreases from heavy load conditions, the inductor current is also reduced and eventually comes to a point where the rippled valley touches zero level, which is the boundary between continuous conduction and discontinuous conduction modes. The rectifying MOSFET is turned off when the zero inductor current is detected. As the load current further decreases, the converter runs into discontinuous conduction mode. The on time is kept almost the same as in continuous conduction mode so that discharging the output capacitor with smaller load current to the level of the reference voltage takes longer. This fact makes the switching frequency lower, proportional to the load current, and keeps the light load efficiency high.

6.4.2 FCCM Mode Operation

The TPS561246 operates in forced CCM (FCCM) mode, which keeps the converter operating in continuous current mode during light load condition and allows the inductor current to become negative. During FCCM mode, the switching frequency (F_{SW}) is maintained at an almost constant level over the entire load range, which is designed for applications requiring tight control of the switching frequency and output voltage ripple at the cost of lower efficiency under light load.

7 Application and Implementation

注

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

7.1 Application Information

The TPS56124x device is a typical buck DC/DC converter to convert a higher DC voltage to a lower DC voltage with a maximum available output current of 1A. The following design procedure can be used to select component values for TPS56124x. Alternately, the WEBENCH® software can be used to generate a complete design. The WEBENCH software uses an iterative design procedure and accesses a comprehensive database of components when generating a design. This section presents a simplified discussion of the design process.

7.2 Typical Application

The TPS56124x application schematic in 図 7-1 was developed to meet the requirements in 表 7-1. This section provides the design procedure.

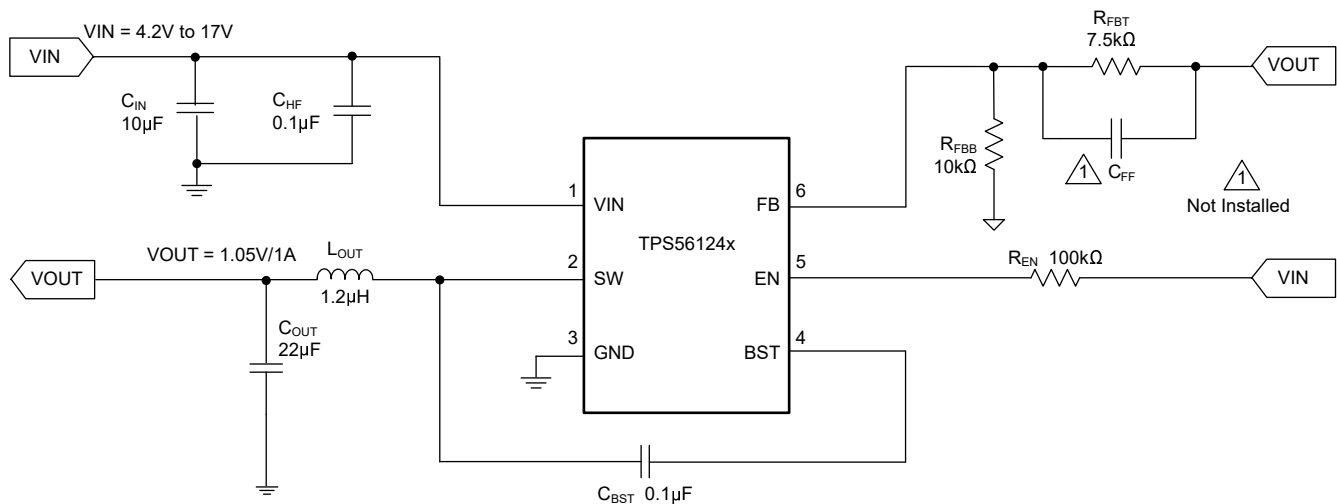


図 7-1. TPS56124x 1.05V/1A Reference Design

7.2.1 Design Requirements

表 7-1 shows the design parameters for this application.

表 7-1. Design Parameters

Parameter	Conditions	MIN	TYP	MAX	Unit
V _{OUT}	Output voltage		1.05		V
I _{OUT}	Output current		1		A
ΔV _{OUT}	Transient response	0.1A – 0.9A load step, 0.8A/μs slew rate	±2% × V _{OUT}		V
V _{IN}	Input voltage	4.2	12	17	V
V _{OUT(ripple)}	Output voltage ripple	CCM condition	8		mV
F _{SW}	Switching frequency		1.28		MHz
T _A	Ambient temperature		25		°C

7.2.2 Detailed Design Procedure

7.2.2.1 Custom Design With WEBENCH® Tools

[Click here](#) to create a custom design using the TPS56124x device with the WEBENCH Power Designer.

1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

7.2.2.2 Output Voltage Resistors Selection

The output voltage is set with a resistor divider from the output node to the FB pin. TI recommends to use 1% tolerance or better divider resistors. Start by using 式 3 to calculate V_{OUT}.

To improve the efficiency at very light loads, consider using larger value resistors. Too high of the resistance can make the circuit more susceptible to noise and voltage errors introduced from the FB input current are more noticeable.

$$V_{OUT} = 0.6 \times \left(1 + \frac{R_{FBT}}{R_{FBB}} \right) \quad (3)$$

7.2.2.3 Output Filter Selection

The LC filter used as the output filter has a double pole at 式 4. In this equation, C_{OUT} must use effective value after derating, not nominal value.

$$Frequency_{doublepole} = \frac{1}{2 \times \pi \times \sqrt{L_{OUT} \times C_{OUT}}} \quad (4)$$

For any control topology that is compensated internally, there is a range of the output filter that the control topology can support. At low frequency, the overall loop gain is set by the output set point resistor divider network and the internal gain of the device. The low frequency phase is 180°. At the output filter pole frequency, the gain rolls off with a rate of –40dB per decade and the phase has a 180 degree drop. The internal ripple

generation network introduces a high-frequency zero that reduces the gain roll off from –40dB to –20dB per decade and leads to the 90 degree phase boost. The high frequency zero brought by the internal ripple injection circuit is about 160kHz. TI recommends the double pole frequency brought by the selected inductor and capacitor to be located at about 40kHz, so that the phase boost provided by this high frequency zero provides adequate phase margin for the stability requirement. For output voltage higher than 2V, TI suggests to add a C_{FF} capacitor to increase the bandwidth and the phase margin. The C_{FF} range suggested is from 10pF to 100pF. The crossover frequency of the overall system must usually be targeted to be less than one-third of the switching frequency.

表 7-2. Recommended Component Values

OUTPUT VOLTAGE (V)	L _{OUT} (μH)	C _{OUT} (μF)	C _{OUT} (μF) ⁽¹⁾ Range	R _{FBT} (kΩ)	R _{FBB} (kΩ)	C _{FF} (pF)
0.6	1	22 (10V Rated)	20-90	0	10.0	-
1.05	1.2	22 (10V Rated)	10-45	7.5	10.0	-
3.3	3.3	22 (25V Rated)	15-60	135.0	30.0	47
5	3.3	22 (25V Rated)	15-60	220.0	30.0	47
7	3.3	22x2 (25V Rated)	15-60	320.0	30.0	47

(1) A ceramic capacitor is used in this table. All the C_{OUT} values are after derating.

The inductor peak-to-peak ripple current, peak current and RMS current are calculated using 式 5, 式 6, and 式 7. The inductor saturation current rating must be greater than the calculated peak current and the RMS or heating current rating must be greater than the calculated RMS current.

$$I_{P-P} = \frac{V_{OUT}}{V_{IN(Max)}} \times \frac{V_{IN(Max)} - V_{OUT}}{L_{OUT} \times f_{SW}} \quad (5)$$

$$I_{PEAK} = I_O + \frac{I_{P-P}}{2} \quad (6)$$

$$I_{LO(RMS)} = \sqrt{I_O^2 + \frac{1}{12} \times I_{P-P}^2} \quad (7)$$

For this design example, the calculated peak current is 1.32A and the calculated RMS current is 1.02A. The inductor used is WE 74438357012.

The capacitor value and ESR determines the amount of output voltage ripple. The TPS56124x is intended for use with ceramic or other low ESR capacitors. TI recommends to use 1× 22μF output cap. Use 式 8 to determine the required RMS current rating for the output capacitor.

$$I_{CO(RMS)} = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{\sqrt{12} \times V_{IN} \times L_{OUT} \times f_{SW}} \quad (8)$$

For this design, one MuRata GRM21BR61A226ME44L 22μF output capacitor can be used. The typical ESR is 2mΩ each. The calculated RMS current is 0.2A and each output capacitor is rated for 4A.

7.2.2.4 Input Capacitor Selection

The TPS56124x requires an input decoupling capacitor and a bulk capacitor is needed depending on the application. TI recommends a ceramic capacitor over 10μF for the decoupling capacitor. An additional 0.1μF capacitor C_{HF} from V_{IN} to ground is optional to provide additional high frequency filtering. The capacitor voltage rating must be greater than the maximum input voltage.

7.2.2.5 Bootstrap Capacitor Selection

A 0.1μF ceramic capacitor must be connected between the BST to SW pin for proper operation. TI recommends to use a ceramic capacitor.

7.2.3 Application Curves

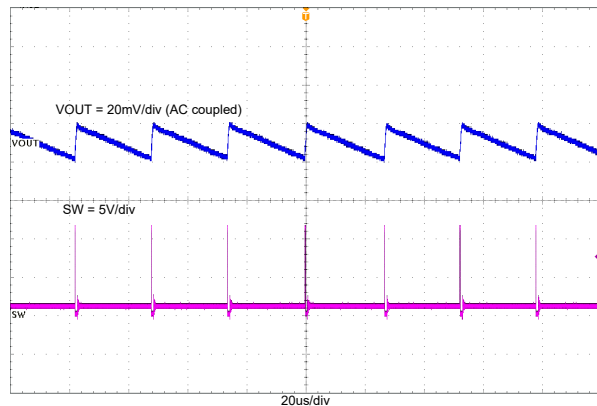


図 7-2. TPS561243 Output Voltage Ripple With 0.01A Loading

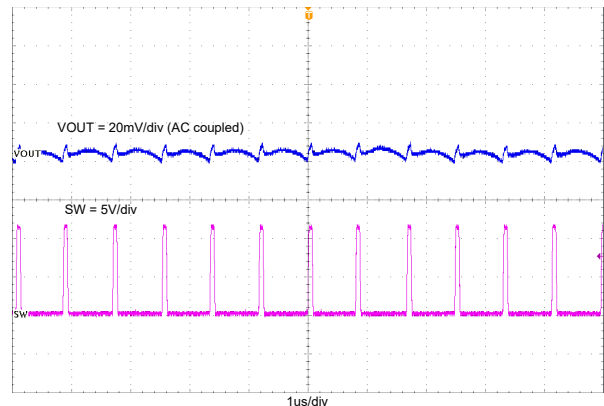


図 7-3. TPS561246 Output Voltage Ripple With 0.01A Loading

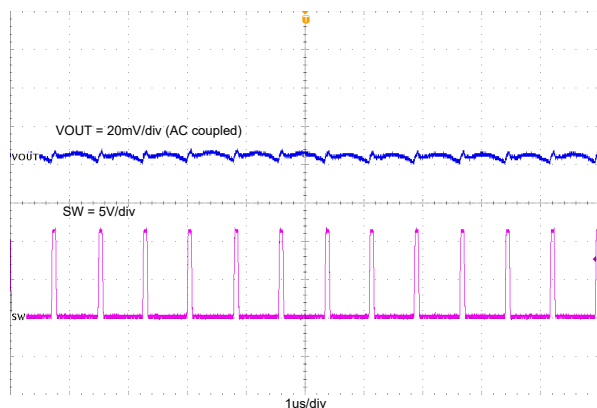


図 7-4. TPS561243 Output Voltage Ripple With 1A Loading

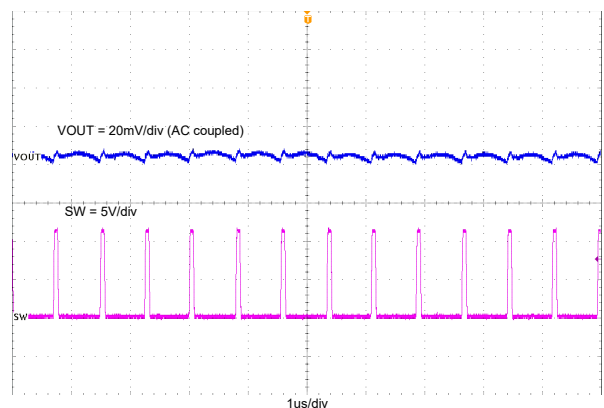


図 7-5. TPS561246 Output Voltage Ripple With 1A Loading

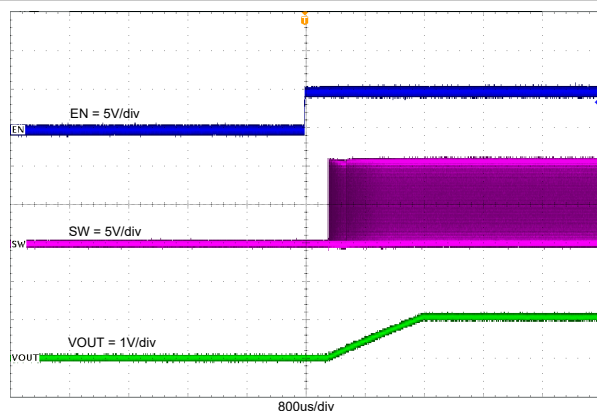


図 7-6. TPS561243 Enable On With 1A Loading

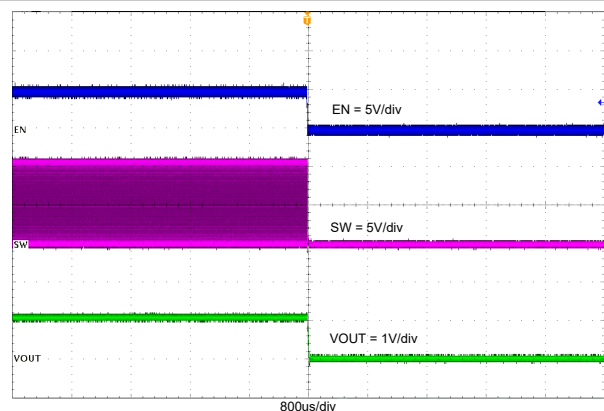


図 7-7. TPS561243 Enable Off With 1A Loading

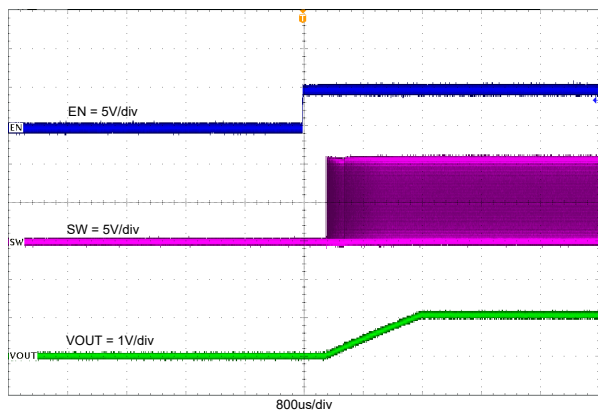


図 7-8. TPS561246 Enable On With 1A Loading

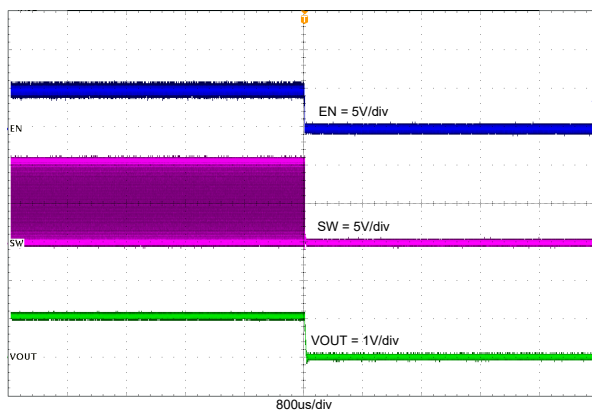


図 7-9. TPS561246 Enable Off With 1A Loading

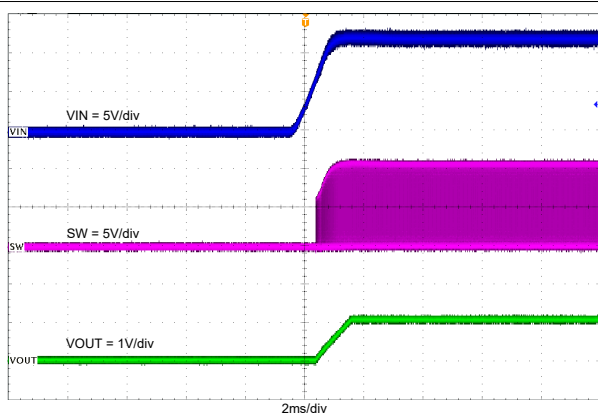


図 7-10. TPS561243 Power On With 1A Loading

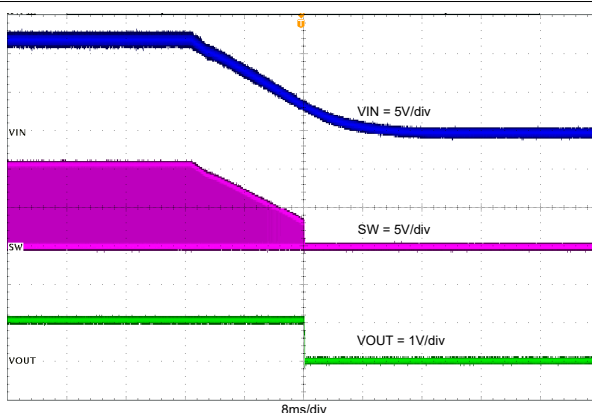


図 7-11. TPS561243 Power Off With 1A Loading

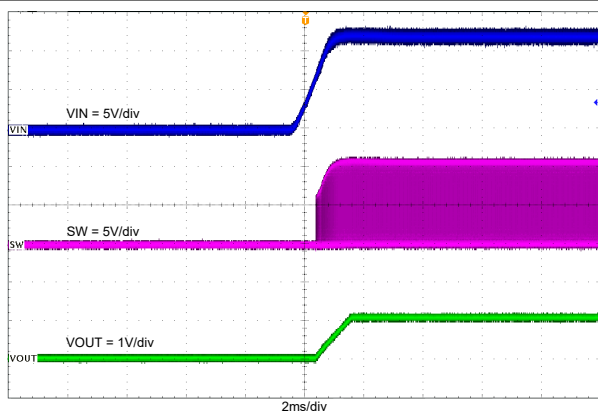


図 7-12. TPS561246 Power On With 1A Loading

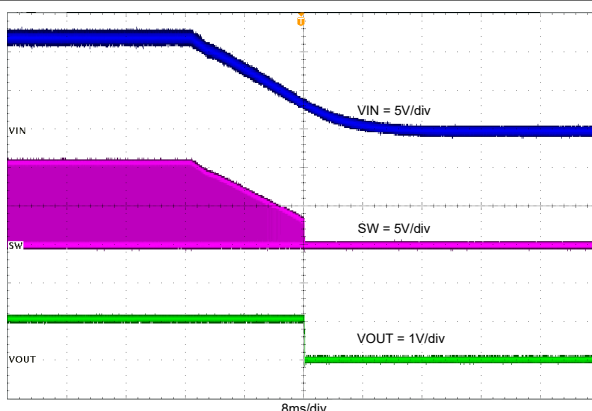
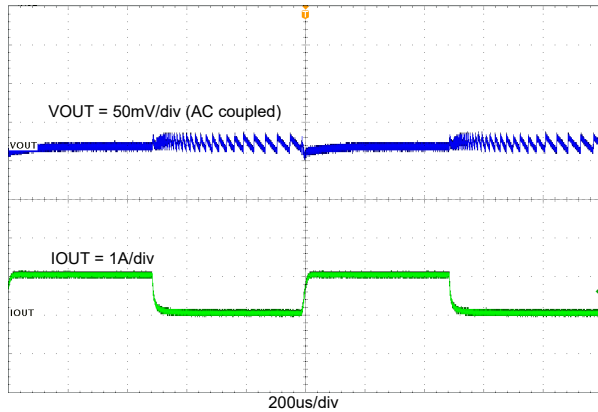
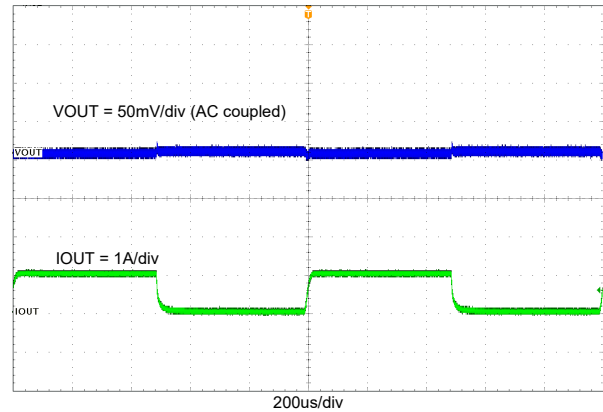
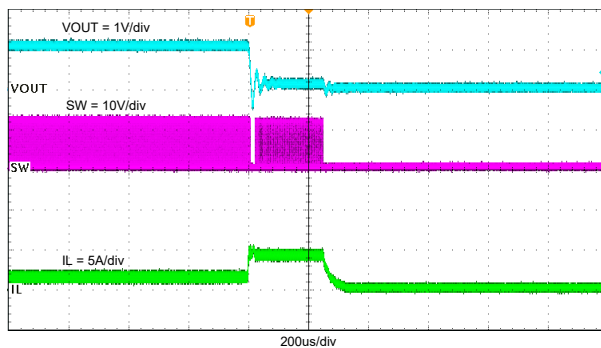
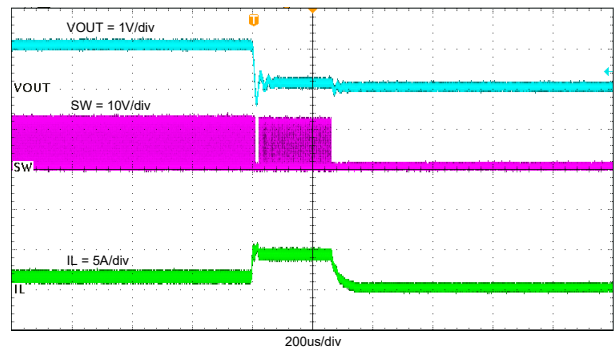


図 7-13. TPS561246 Power Off With 1A Loading


図 7-14. TPS561243 Load Transient With 0A to 1A

図 7-15. TPS561246 Load Transient With 0A to 1A

図 7-16. TPS561243 Normal Operation to Output Hardshort

図 7-17. TPS561246 Normal Operation to Output Hardshort

7.3 Power Supply Recommendations

The TPS56124x is designed to operate from input supply voltages in the range of 4.2V to 17V. Buck converters require the input voltage to be higher than the output voltage for proper operation. The maximum duty is 95%.

7.4 Layout

7.4.1 Layout Guidelines

1. Make V_{IN} and GND traces as wide as possible to reduce trace impedance. The wide areas can also benefit for heat dissipation.
2. Place the input capacitor and output capacitor as close to the device as possible to minimize trace impedance.
3. Provide sufficient vias for the input capacitor and output capacitor.
4. Keep the SW trace as physically short and wide as practical to minimize radiated emissions.
5. Do not allow switching current to flow under the device.
6. Connect a separate VOUT path to the upper feedback resistor.
7. Make a Kelvin connection to the GND pin for the feedback path.
8. Place a voltage feedback loop away from the high voltage switching trace, and preferably with ground shield.
9. Make the trace of the FB node as small as possible to avoid noise coupling.
10. Make the GND trace between the output capacitor and the GND pin as wide as possible to minimize trace impedance.

7.4.2 Layout Example

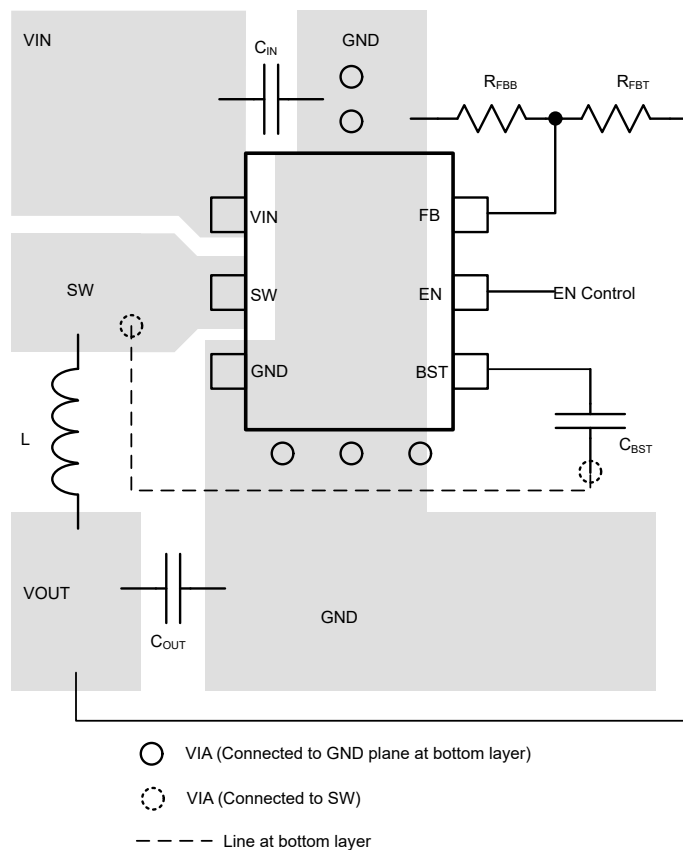


図 7-18. TPS56124x Layout

8 Device and Documentation Support

8.1 Device Support

8.1.1 Development Support

8.1.1.1 Custom Design With WEBENCH® Tools

[Click here](#) to create a custom design using the TPS56124x device with the WEBENCH Power Designer.

1. Start by entering the input voltage (V_{IN}), output voltage (V_{OUT}), and output current (I_{OUT}) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at www.ti.com/WEBENCH.

8.2 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、www.tij.co.jp のデバイス製品フォルダを開いてください。[通知] をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取ることができます。変更の詳細については、改訂されたドキュメントに含まれている改訂履歴をご覧ください。

8.3 サポート・リソース

テキサス・インスツルメンツ E2E™ サポート・フォーラムは、エンジニアが検証済みの回答と設計に関するヒントをエキスパートから迅速かつ直接得ることができる場所です。既存の回答を検索したり、独自の質問をしたりすることで、設計に必要な支援を迅速に得ることができます。

リンクされているコンテンツは、各寄稿者により「現状のまま」提供されるものです。これらはテキサス・インスツルメンツの仕様を構成するものではなく、必ずしもテキサス・インスツルメンツの見解を反映したものではありません。テキサス・インスツルメンツの[使用条件](#)を参照してください。

8.4 Trademarks

D-CAP3™ and テキサス・インスツルメンツ E2E™ are trademarks of Texas Instruments.

WEBENCH® is a registered trademark of Texas Instruments.

すべての商標は、それぞれの所有者に帰属します。

8.5 静電気放電に関する注意事項



この IC は、ESD によって破損する可能性があります。テキサス・インスツルメンツは、IC を取り扱う際には常に適切な注意を払うことを推奨します。正しい取り扱いおよび設置手順に従わない場合、デバイスを破損するおそれがあります。

ESD による破損は、わずかな性能低下からデバイスの完全な故障まで多岐にわたります。精密な IC の場合、パラメータがわずかに変化するだけで公表されている仕様から外れる可能性があるため、破損が発生しやすくなっています。

8.6 用語集

[テキサス・インスツルメンツ用語集](#)

この用語集には、用語や略語の一覧および定義が記載されています。

9 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from Revision * (April 2024) to Revision A (June 2024)
Page

- ドキュメントのステータスを「事前情報」から「量産データ」に変更..... **1**

10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

重要なお知らせと免責事項

テキサス・インスツルメンツは、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス デザインを含みます)、アプリケーションや設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供しており、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的にかかわらず拒否します。

これらのリソースは、テキサス・インスツルメンツ製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した テキサス・インスツルメンツ製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあらゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとします。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている テキサス・インスツルメンツ製品を使用するアプリケーションの開発の目的でのみ、テキサス・インスツルメンツはその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載することは禁止されています。テキサス・インスツルメンツや第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、テキサス・インスツルメンツおよびその代理人を完全に補償するものとし、テキサス・インスツルメンツは一切の責任を拒否します。

テキサス・インスツルメンツの製品は、[テキサス・インスツルメンツの販売条件](#)、または [ti.com](https://www.ti.com) やかかる テキサス・インスツルメンツ製品の関連資料などのいずれかを通じて提供する適用可能な条項の下で提供されています。テキサス・インスツルメンツがこれらのリソースを提供することは、適用されるテキサス・インスツルメンツの保証または他の保証の放棄の拡大や変更を意味するものではありません。

お客様がいかなる追加条項または代替条項を提案した場合でも、テキサス・インスツルメンツはそれらに異議を唱え、拒否します。

郵送先住所: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2024, Texas Instruments Incorporated

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TPS561243DRLR	Active	Production	SOT-5X3 (DRL) 6	4000 LARGE T&R	Yes	Call TI Sn	Level-1-260C-UNLIM	-40 to 125	1243
TPS561243DRLR.A	Active	Production	SOT-5X3 (DRL) 6	4000 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	1243
TPS561243DRLR.B	Active	Production	SOT-5X3 (DRL) 6	4000 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	1243
TPS561246DRLR	Active	Production	SOT-5X3 (DRL) 6	4000 LARGE T&R	Yes	Call TI Sn	Level-1-260C-UNLIM	-40 to 125	1246
TPS561246DRLR.A	Active	Production	SOT-5X3 (DRL) 6	4000 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	1246
TPS561246DRLR.B	Active	Production	SOT-5X3 (DRL) 6	4000 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	1246

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

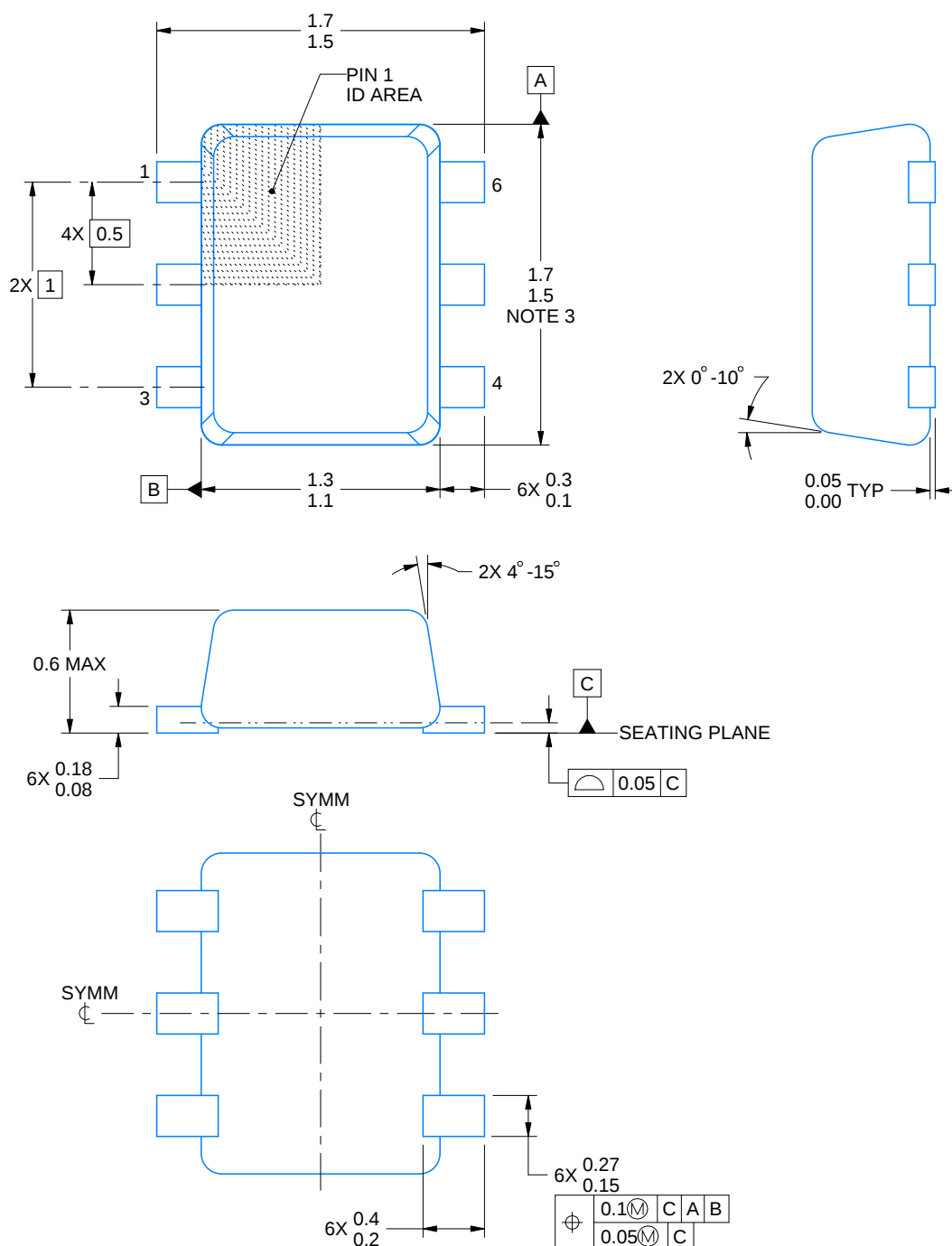
Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



SOT - 0.6 mm max height

PLASTIC SMALL OUTLINE



4223266/F 11/2024

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. Reference JEDEC registration MO-293 Variation UAAD

EXAMPLE BOARD LAYOUT

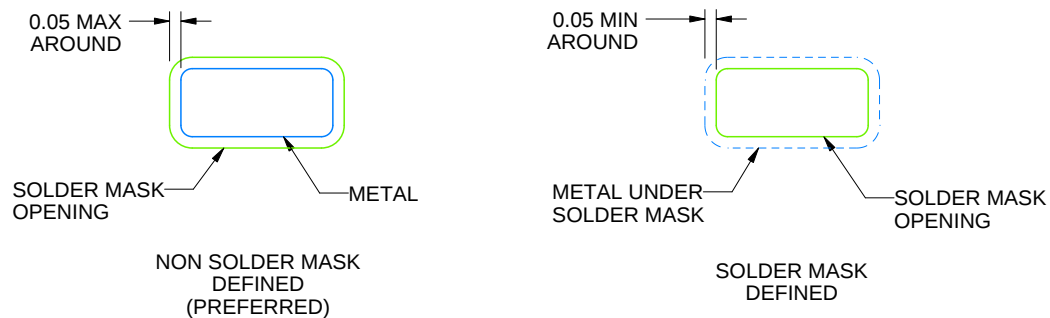
DRL0006A

SOT - 0.6 mm max height

PLASTIC SMALL OUTLINE



LAND PATTERN EXAMPLE
SCALE:30X



SOLDERMASK DETAILS

4223266/F 11/2024

NOTES: (continued)

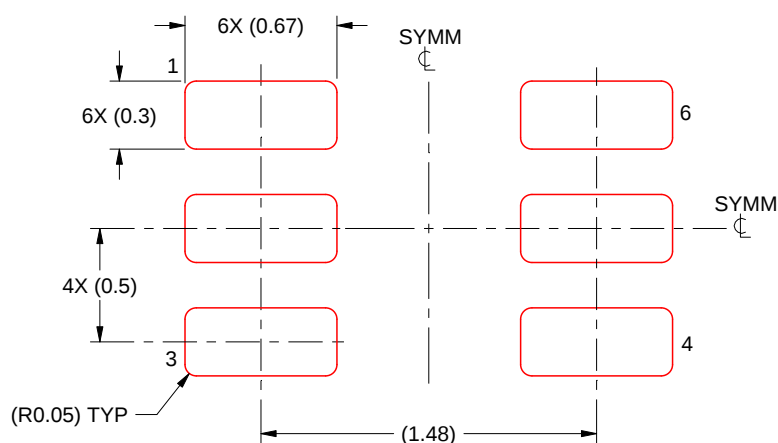
5. Publication IPC-7351 may have alternate designs.
6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
7. Land pattern design aligns to IPC-610, Bottom Termination Component (BTC) solder joint inspection criteria.

EXAMPLE STENCIL DESIGN

DRL0006A

SOT - 0.6 mm max height

PLASTIC SMALL OUTLINE



SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE:30X

4223266/F 11/2024

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

重要なお知らせと免責事項

テキサス・インスツルメンツは、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス デザインを含みます)、アプリケーションや設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供しており、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的にかかわらず拒否します。

これらのリソースは、テキサス・インスツルメンツ製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した テキサス・インスツルメンツ製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあらゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとします。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている テキサス・インスツルメンツ製品を使用するアプリケーションの開発の目的でのみ、テキサス・インスツルメンツはその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載することは禁止されています。テキサス・インスツルメンツや第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、テキサス・インスツルメンツおよびその代理人を完全に補償するものとし、テキサス・インスツルメンツは一切の責任を拒否します。

テキサス・インスツルメンツの製品は、[テキサス・インスツルメンツの販売条件](#)、または [ti.com](https://www.ti.com) やかかる テキサス・インスツルメンツ製品の関連資料などのいずれかを通じて提供する適用可能な条項の下で提供されています。テキサス・インスツルメンツがこれらのリソースを提供することは、適用される テキサス・インスツルメンツの保証または他の保証の放棄の拡大や変更を意味するものではありません。

お客様がいかなる追加条項または代替条項を提案した場合でも、テキサス・インスツルメンツはそれらに異議を唱え、拒否します。

郵送先住所：Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2025, Texas Instruments Incorporated