

# TPS53819A 3V~28V 入力、40A、Eco-Mode™、D-CAP2™ PMBus™ 搭載の同期整流降圧コントローラ

## 1 特長

- 変換入力電圧範囲：3V~28V
- VDD 入力電圧範囲：4.5V~28V
- 出力電圧：0.6V~5.5V
- すべての出力コンデンサにセラミック・コンデンサの使用をサポート
- 基準電圧：600mV、公差±0.5%
- ±9% の電圧調整：PMBus™
- 5V LDO を内蔵
- D-CAP2™モード (負荷ステップ応答 100ns)
- 自動スキップ Eco-mode™によって軽負荷時の効率を向上
- PMBus で選択可能な 8つの周波数による適応型オン時間制御アーキテクチャ
- PMBus により電圧マーギングをサポート
- PMBus によりソフトスタート時間をプログラム可能
- PMBus により電源オン遅延をプログラム可能
- PMBus により VDD UVLO レベルをプログラム可能
- PMBus によるフォルト報告
- プリチャージ・スタートアップ機能
- 出力放電機能を内蔵
- 遅延をプログラム可能なパワー・グッド出力
- 過電圧、低電圧、過電流制限保護機能を内蔵
- サーマル・シャットダウン (非ラッチ)
- 3mm x 3mm、16 ピンの QFN パッケージ
- WEBENCH® Power Designer により、TPS53819A を使用するカスタム設計を作成

## 2 アプリケーション

- 次の用途でのポイント・オブ・ロード電源
  - ストレージ・コンピュータ
  - サーバー・コンピュータ
  - 多機能プリンタ
  - 組み込みコンピューティング

## 3 概要

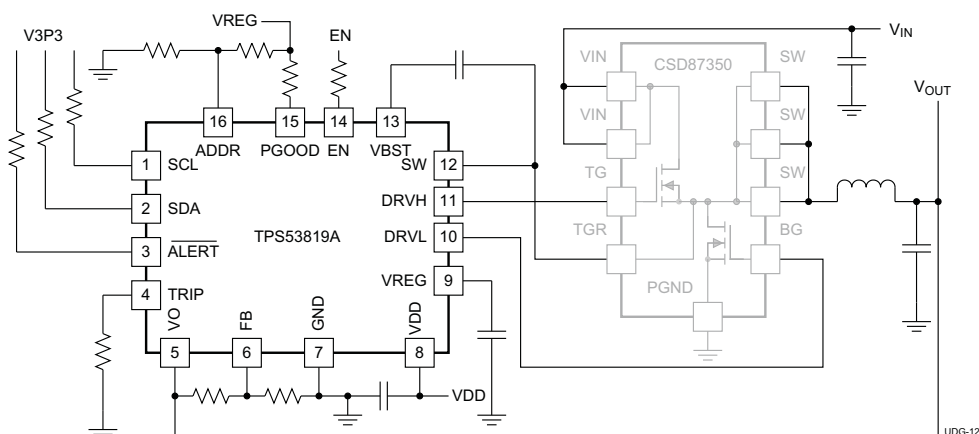
TPS53819A デバイスは、適応型オン時間 D-CAP2 モード制御と PMBus を搭載した、小型のシングル降圧コントローラです。このデバイスは、低出力電圧で高電流のシステム電源レールや、民生用デジタル機器で使用される同様のポイント・オブ・ロード (POL) 電源に適しています。PMBus によるプログラム性とフォルト報告が電源の設計を簡単にすると同時に、最小限のピン数の小型パッケージが PCB 面積を節約します。軽負荷状況でのスキップ・モードと、強力なゲート・ドライバおよびローサイド FET オン抵抗 ( $R_{DS(on)}$ ) 電流センシングの組み合わせにより、広範な負荷範囲にわたって低損失かつ高効率の動作が可能です。変換入力電圧はハイサイド FET ドレイン電圧と同じで、3V~28V の範囲です。電源電圧 (VDD) は 4.5V~28V です。出力電圧は 0.6V~5.5V の範囲です。このデバイスは、16 ピンの QFN パッケージで供給され、-40°C~+85°C で動作が規定されています。

### 製品情報<sup>(1)</sup>

型番	パッケージ	本体サイズ(公称)
TPS53819A	QFN (16)	3.00mmx3.00mm

(1) 利用可能なすべてのパッケージについては、このデータシートの末尾にある注文情報を参照してください。

### アプリケーション概略図



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## 4 改訂履歴

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

### Revision A (October 2015) から Revision B に変更

**Page**

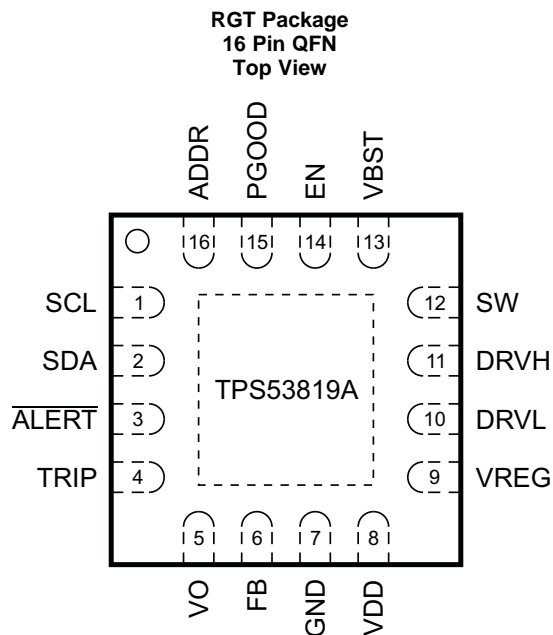
- 編集上の更新 - 技術データの変更なし、WEBENCH 用のリンクを追加 ..... 1

### 2012年11月発行のものから更新

**Page**

- 「ESD 定格」表、「機能説明」セクション、「デバイスの機能モード」セクション、「アプリケーションと実装」セクション、「電源に関する推奨事項」セクション、「レイアウト」セクション、「デバイスおよびドキュメントのサポート」セクション、「メカニカル、パッケージ、および注文情報」セクション 追加 ..... 1

## 5 Pin Configuration and Functions



**Pin Functions**

PIN		I/O <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
ADDR	16	I	PMBus address configuration. Connect this pin to a resistor divider between VREG and GND to program different address settings. (See <a href="#">Table 2</a> for details.)
$\overline{\text{ALERT}}$	3	O	Open-drain alert output for the PMBus interface.
DRVH	11	O	High-side MOSFET floating driver output that is referenced to SW node. The gate drive voltage is defined by the voltage across bootstrap capacitor between VBST and SW.
DRVL	10	O	Synchronous MOSFET driver output that is referenced to GND. The gate drive voltage is defined by VREG voltage.
EN	14	I	Enable pin that can turn on the DC/DC switching converter. EN pin works in conjunction with the CP bit in PMBus ON_OFF_CONFIG register.
FB	6	I	Output voltage feedback input. Connect this pin to a resistor divider between output voltage and GND.
GND	7	G	Ground pin.
PGOOD	15	O	Open drain power good status signal. Provides start-up delay time after FB voltage falls within specified limits. After FB voltage goes out of specified limits, PGOOD goes low within 2 $\mu\text{s}$ .
SCL	1	I	Clock input for the PMBus interface.
SDA	2	I/O	Data I/O for the PMBus interface.
SW	12	P	Output switching terminal of power converter. Connect this pin to the output inductor.
TRIP	4	I/O	OCL detection threshold setting pin. A 10- $\mu\text{A}$ current with a $T_C$ of 4700ppm/ $^\circ\text{C}$ is sourced out of the TRIP pin and is used to set the OCL trip voltage as follows: $V_{\text{OCL}} = V_{\text{TRIP}}/8$ ( $V_{\text{TRIP}} \leq 3 \text{ V}$ , $V_{\text{OCL}} \leq 375 \text{ mV}$ )
VBST	13	P	Supply rail for high-side gate driver (boost terminal). Connect bootstrap capacitor from this pin to SW node. Internally connected to VREG via bootstrap PMOS switch.
VDD	8	P	Controller power supply input.
VO	5	I	Output voltage.
VREG	9	P	5-V low-drop-out (LDO) output. Supplies the internal analog and driver circuitry.

(1) I=Input, O=Output, P=Power, G=Ground

## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT	
Input voltage <sup>(2)</sup>	VBST	-0.3	38	V	
	VBST <sup>(3)</sup>	-0.3	6		
	EN	-0.3	7.7		
	VO, FB, SCL, SDA, ADDR	-0.3	6		
	VDD	-0.3	30		
	SW	DC	-3		32
	Pulse < 30% of the repetitive period	-5	32		
Output voltage <sup>(2)</sup>	DRVH	DC	-3	38	V
		Pulse < 30% of the repetitive period	-5	38	
	DRVH <sup>(3)</sup> , DRVL	-0.3	6		
	ALERT, VREG, TRIP	-0.3	6		
	PGOOD	-0.3	7.7		
Junction temperature, T <sub>J</sub>			150	°C	
Storage temperature, T <sub>stg</sub>		-55	150	°C	

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to the network ground terminal unless otherwise noted.
- (3) Voltage values are with respect to the SW terminal.

### 6.2 ESD Ratings

		VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000
		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
Input voltage range	VBST	-0.1		35.5	V
	VBST <sup>(1)</sup>	-0.1		5.5	
	EN	-0.1		6.5	
	VO, FB, SCL, SDA, ADDR	-0.1		5.5	
	VDD	4.5		28	V
	SW	DC	-3	30	
	Pulse < 30% of the repetitive period	-4.5		30	
Output voltage range	DRVH	DC		35.5	V
		Pulse < 30% of the repetitive period		35.5	
	DRVH <sup>(1)</sup> , DRVL	-0.1		5.5	V
	ALERT, VREG	-0.1		5.5	V
	PGOOD	-0.1		6.5	V
Operating free-air temperature, T <sub>A</sub>		-40		85	°C

- (1) Voltage values are with respect to the SW terminal.

## 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		TPS53819A	UNIT
		RGT (QFN)	
		16 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	51.3	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	85.4	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	20.1	°C/W
$\psi_{JT}$	Junction-to-top characterization parameter	1.3	°C/W
$\psi_{JB}$	Junction-to-board characterization parameter	19.4	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	6.0	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953](#).

## 6.5 Electrical Characteristics

over operating free-air temperature range,  $V_{REG} = 5\text{ V}$ ,  $V_{EN} = 5\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>SUPPLY CURRENT</b>					
$I_{VDD}$	VDD bias current	$T_A = 25^\circ\text{C}$ , no load, power conversion enabled (no switching)		920	$\mu\text{A}$
$I_{VDDSTBY}$	VDD standby current	$T_A = 25^\circ\text{C}$ , no load, power conversion disabled		610	$\mu\text{A}$
<b>INTERNAL REFERENCE AND FEEDBACK REGULATION VOLTAGE</b>					
$V_{FB}$	Feedback regulation voltage	FB w/r/t GND, CCM condition		600	mV
$V_{FBTOL}$	Feedback voltage tolerance	FB w/r/t GND, $0^\circ\text{C} \leq T_J \leq 85^\circ\text{C}$		597      600      603	mV
$V_{DACTOL1}$	DAC voltage tolerance 1	FB w/r/t GND, $0^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ , all settings with VOUT_ADJUSTMENT only		-4.8      4.8	mV
$V_{DACTOL2}$	DAC voltage tolerance 2	FB w/r/t GND, $0^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ , all settings with VOUT_MARGIN only		-4.8      4.8	mV
$V_{DACTOL3}$	DAC voltage tolerance 3	FB w/r/t GND, $0^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ , with VOUT_ADJUSTMENT = 0Dh and VOUT_MARGIN = 70h for +5%		-4.8      4.8	mV
$V_{DACTOL4}$	DAC voltage tolerance 4	FB w/r/t GND, $0^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ , with VOUT_ADJUSTMENT = 13h and VOUT_MARGIN = 07h for -5%		-4.8      4.8	mV
$V_{IOS\_LPCMP}$	Loop comparator input offset voltage	$V_{REF}$ to $V_{FB}$ , $T_A = 25^\circ\text{C}$		-2.5      2.5	mV
$I_{FB}$	FB pin input current	$V_{FB} = 600\text{ mV}$		-1      1	$\mu\text{A}$
<b>OUTPUT VOLTAGE</b>					
$I_{VODIS}$	VO discharge current	$V_{VO} = 0.5\text{ V}$ , power conversion disabled		10      12	mA
<b>DRIVER</b>					
$R_{DRVH}$	DRVH resistance	Source, $I_{DRVH} = 50\text{ mA}$		1.6	$\Omega$
		Sink, $I_{DRVH} = 50\text{ mA}$		0.6	
$R_{DRVL}$	DRVL resistance	Source, $I_{DRVL} = 50\text{ mA}$		0.9	
		Sink, $I_{DRVL} = 50\text{ mA}$		0.5	

**Electrical Characteristics (continued)**

 over operating free-air temperature range,  $V_{VREG} = 5\text{ V}$ ,  $V_{EN} = 5\text{ V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>INTERNAL BOOT STRAP SWITCH</b>						
$V_F$	Forward voltage	$V_{VREG-VBST}$ , $T_A = 25^\circ\text{C}$ , $I_F = 10\text{ mA}$		0.1	0.2	V
$I_{VBST}$	VBST leakage current	$T_A = 25^\circ\text{C}$ , $V_{VBST} = 33\text{ V}$ , $V_{SW} = 28\text{ V}$		0.01	1.5	$\mu\text{A}$
<b>ENABLE LOGIC THRESHOLD</b>						
$V_L$	EN low-level voltage				0.5	V
$V_H$	EN high-level voltage		1.8			V
$V_{HYST}$	EN hysteresis voltage			0.22		V
$I_{LEAK}$	EN input leakage current		-1	0	1	$\mu\text{A}$
<b>POWER GOOD COMPARATOR</b>						
$V_{PGTH}$	Powergood threshold	PGOOD in from higher	105%	108%	111%	
		PGOOD in from lower	89%	92%	95%	
		PGOOD out to higher	113%	116%	119%	
		PGOOD out to lower	81%	84%	87%	
$I_{PG}$	PGOOD sink current	$V_{PGOOD} = 0.5\text{ V}$		6.9		mA
$I_{PGLK}$	PGOOD leakage current	$V_{PGOOD} = 5.0\text{ V}$	-1	0	1	$\mu\text{A}$
<b>CURRENT DETECTION</b>						
$I_{TRIP}$	TRIP source current	$T_A = 25^\circ\text{C}$ , $V_{TRIP} = 0.4\text{ V}$ , $R_{DS(on)}$ sensing	9	10	11	$\mu\text{A}$
$T_{CITRIP}$	TRIP source current temperature coefficient <sup>(1)</sup>	$R_{DS(on)}$ sensing		4700		ppm/°C
$V_{TRIP}$	TRIP voltage range	$R_{DS(on)}$ sensing	0.2		3	V
$V_{OCLP}$	Positive current limit threshold	$V_{TRIP} = 3.0\text{ V}$ , $R_{DS(on)}$ sensing	360	375	390	mV
		$V_{TRIP} = 1.6\text{ V}$ , $R_{DS(on)}$ sensing	190	200	210	
		$V_{TRIP} = 0.2\text{ V}$ , $R_{DS(on)}$ sensing	20	25	30	
$V_{OCLN}$	Negative current limit threshold	$V_{TRIP} = 3.0\text{ V}$ , $R_{DS(on)}$ sensing	-390	-375	-360	mV
		$V_{TRIP} = 1.6\text{ V}$ , $R_{DS(on)}$ sensing	-212	-200	-188	
		$V_{TRIP} = 0.2\text{ V}$ , $R_{DS(on)}$ sensing	-30	-25	-20	
$V_{ZC}$	Zero cross detection offset			0		mV
<b>PROTECTIONS</b>						
$V_{VREGUVLO}$	VREG UVLO threshold voltage	Wake-up		3.32		V
		Shutdown		3.11		
$V_{OVP}$	OVP threshold voltage	OVP detect voltage	117%	120%	123%	
$t_{OVPDLY}$	OVP propagation delay time	With 100-mV overdrive		430		ns
$V_{UVP}$	UVP threshold voltage	UVP detect voltage	65%	68%	71%	
<b>THERMAL SHUTDOWN</b>						
$T_{SDN}$	Thermal shutdown threshold	Shutdown temperature		140		°C
		Hysteresis		40		
<b>LDO VOLTAGE</b>						
$V_{REG}$	LDO output voltage	$V_{IN} = 12\text{ V}$ , $I_{LOAD} = 10\text{ mA}$	4.5	5	5.5	V
$V_{DOVREG}$	LDO low droop drop-out voltage	$V_{IN} = 4.5\text{ V}$ , $I_{LOAD} = 30\text{ mA}$ , $T_A = 25^\circ\text{C}$			365	mV
$I_{LDO(max)}$	LDO overcurrent limit <sup>(1)</sup>	$V_{IN} = 12\text{ V}$ , $T_A = 25^\circ\text{C}$		152		mA

(1) Specified by design. Not production tested.

**Electrical Characteristics (continued)**

over operating free-air temperature range,  $V_{VREG} = 5\text{ V}$ ,  $V_{EN} = 5\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
<b>VDD UVLO VOLTAGE</b>						
VDD <sub>UVLO</sub>	VDD UVLO voltage	VDDINUVLO<2:0> = 0xx	10.2		V	
		VDDINUVLO<2:0> = 101	4.1	4.25		4.4
		VDDINUVLO<2:0> = 110	6.0			
		VDDINUVLO<2:0> = 111	8.1			
VDD <sub>HY-UVLO</sub>	VDD UVLO hysteresis voltage	0°C ≤ T <sub>J</sub> ≤ 85°C		0.2	V	
<b>PMBus SCL and SDA INPUT BUFFER LOGIC THRESHOLDS</b>						
V <sub>IL-PMBUS</sub>	SCL and SDA low-level input voltage <sup>(1)</sup>	0°C ≤ T <sub>J</sub> ≤ 85°C		0.8	V	
V <sub>IH-PMBUS</sub>	SCL and SDA high-level input voltage <sup>(1)</sup>	0°C ≤ T <sub>J</sub> ≤ 85°C		2.1	V	
V <sub>HY-PMBUS</sub>	SCL and SDA hysteresis voltage <sup>(1)</sup>	0°C ≤ T <sub>J</sub> ≤ 85°C		240	mV	
<b>PMBus SDA and <math>\overline{\text{ALERT}}</math> OUTPUT PULLDOWN</b>						
V <sub>OL1-PMBUS</sub>	SDA and $\overline{\text{ALERT}}$ low-level output voltage <sup>(1)</sup>	V <sub>DDPMBUS</sub> = 5.5 V, R <sub>PULLUP</sub> = 1.1 kΩ, 0°C ≤ T <sub>J</sub> ≤ 85°C		0.4	V	
V <sub>OL2-PMBUS</sub>	SDA and $\overline{\text{ALERT}}$ low-level output voltage <sup>(1)</sup>	V <sub>DDPMBUS</sub> = 3.6 V, R <sub>PULLUP</sub> = 0.7 kΩ, 0°C ≤ T <sub>J</sub> ≤ 85°C		0.4	V	

## 6.6 Timing Requirements

			MIN	NOM	MAX	UNIT
<b>POWER-ON DELAY</b>						
$t_{\text{PODLY}}$	Power-on delay time	Delay from enable to switching POD<2:0> = 000		356		$\mu\text{s}$
		Delay from enable to switching POD<2:0> = 001		612		$\mu\text{s}$
		Delay from enable to switching POD<2:0> = 010		1.124		ms
		Delay from enable to switching POD<2:0> = 011		2.148		ms
		Delay from enable to switching POD<2:0> = 100		4.196		ms
		Delay from enable to switching POD<2:0> = 101		8.292		ms
		Delay from enable to switching POD<2:0> = 110		16.48		ms
		Delay from enable to switching POD<2:0> = 111		32.86		ms
<b>PGOOD DELAY</b>						
$t_{\text{PGDLY}}$	PGOOD delay time	Delay for PGOOD going in PGD<2:0> = 000	165	256	320	$\mu\text{s}$
		Delay for PGOOD going in PGD<2:0> = 001	409	512	614	$\mu\text{s}$
		Delay for PGOOD going in PGD<2:0> = 010	0.819	1.024	1.228	ms
		Delay for PGOOD going in PGD<2:0> = 011	1.638	2.048	2.458	ms
		Delay for PGOOD going in PGD<2:0> = 100	3.276	4.096	4.915	ms
		Delay for PGOOD going in PGD<2:0> = 101	6.553	8.192	9.83	ms
		Delay for PGOOD going in PGD<2:0> = 110	13.104	16.38	19.656	ms
		Delay for PGOOD going in PGD<2:0> = 111	105	131	157	ms
	Delay for PGOOD coming out			2	$\mu\text{s}$	
<b>SOFT START TIME</b>						
$t_{\text{SS}}$	Soft-start time	SST<1:0> = 00		1.0		ms
		SST<1:0> = 01		2.0		
		SST<1:0> = 10		4.0		
		SST<1:0> = 11		8.0		
<b>FREQUENCY CONTROL</b>						
$t_{\text{OFF(min)}}$	Minimum off-time	DRVH falling to rising		320		ns
$t_{\text{ON(min)}}$	Minimum on-time <sup>(1)</sup>	DRVH rising to falling		60		ns
<b>PROTECTIONS</b>						
$t_{\text{UVPDLY}}$	UVP filterdelay time			1		ms
<b>DRIVER</b>						
$t_{\text{DEAD}}$	Dead time	DRVH-off to DRVL-on		10		ns
		DRVL-off to DRVH-on		20		

(1) Specified by design. Not production tested.



## 6.7 Switching Characteristics

over operating free-air temperature range  $V_{IN} = 12\text{ V}$ ,  $V_{VO} = 3.3\text{ V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>FREQUENCY CONTROL</b>						
$f_{sw}$	VO pin switching frequency	FS <2:0> = 000		275		kHz
		FS <2:0> = 001		325		
		FS <2:0> = 010		425		
		FS <2:0> = 011		525		
		FS <2:0> = 100		625		
		FS <2:0> = 101		750		
		FS <2:0> = 110		850		
		FS <2:0> = 111		1000		

### 6.8 Typical Characteristics

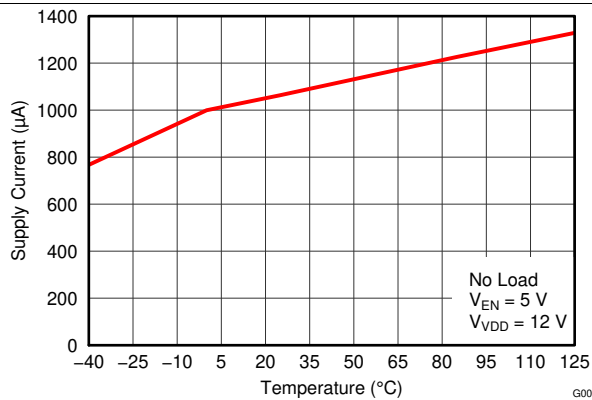


Figure 1. VDD Supply Current vs Temperature

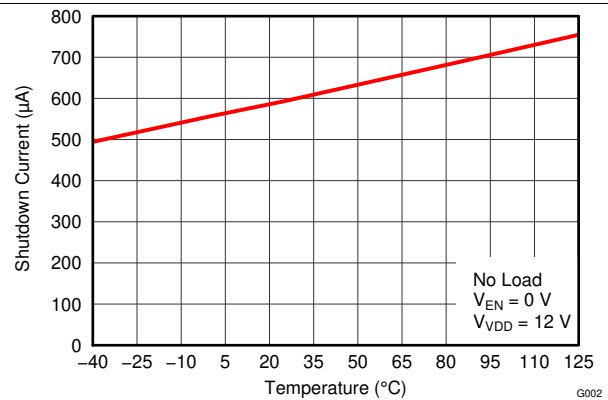


Figure 2. VDD Shutdown Current vs Temperature

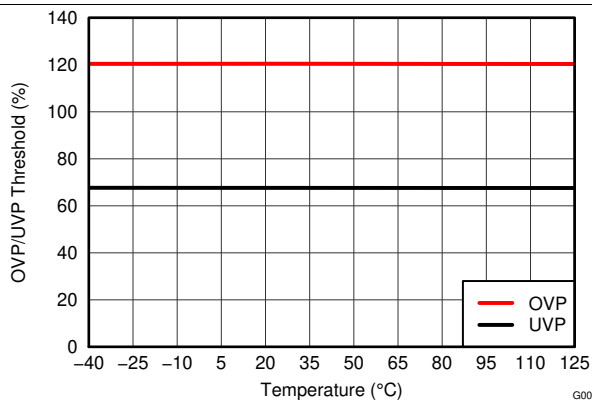


Figure 3. OVP/UVP Thresholds vs Temperature

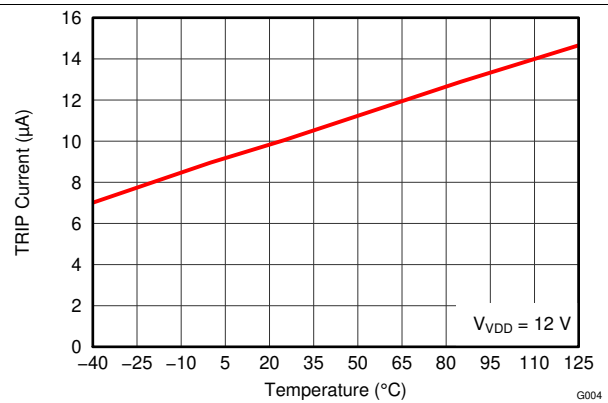


Figure 4. TRIP Pin Current vs Temperature

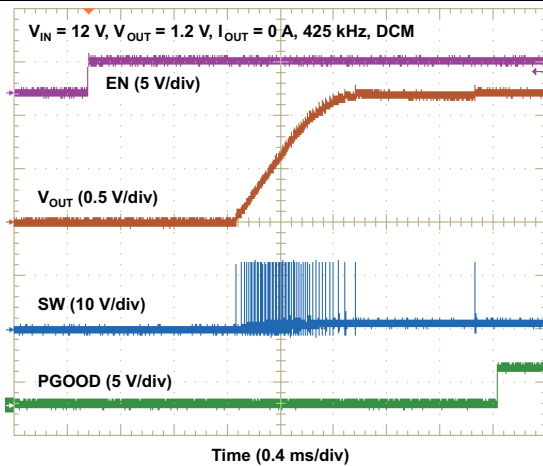


Figure 5. No-Load Start-Up Waveforms with DCM

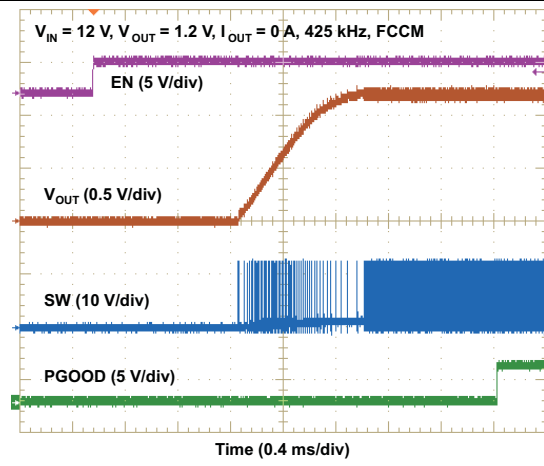


Figure 6. No-Load Start-Up Waveforms with FCCM

Typical Characteristics (continued)

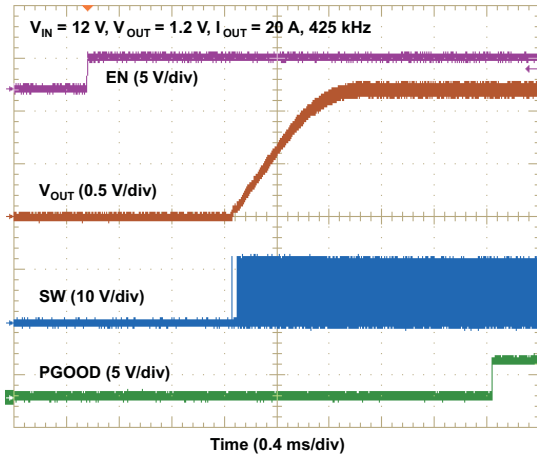


Figure 7. Full-Load Start-Up Waveforms

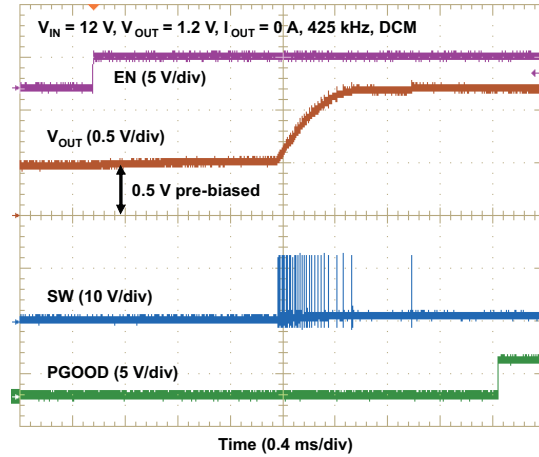


Figure 8. Pre-Bias Start-Up Waveforms with DCM

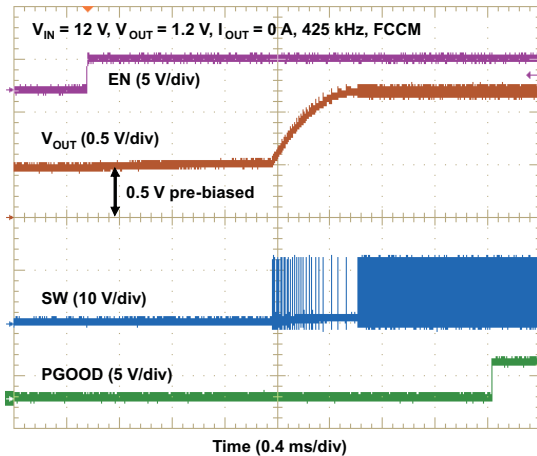


Figure 9. Pre-Bias Start-Up Waveforms with FCCM

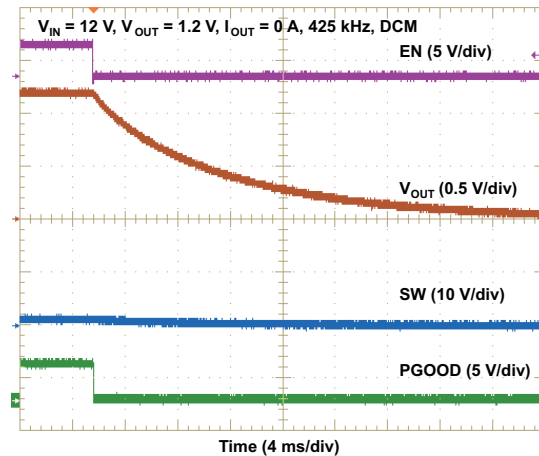


Figure 10. No-Load Shutdown Waveforms with DCM

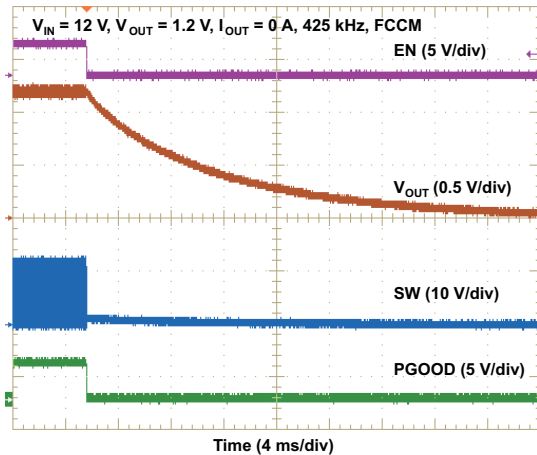


Figure 11. No-Load Shutdown Waveforms with FCCM

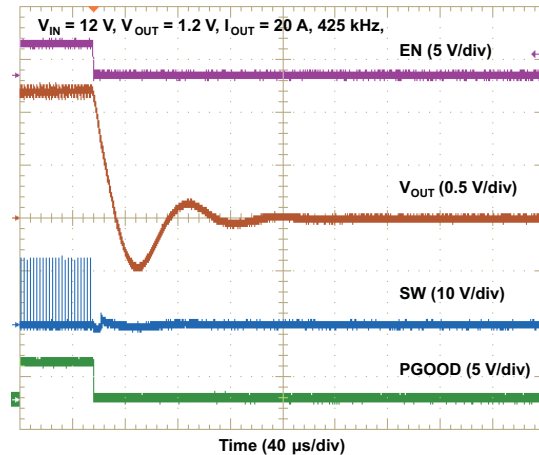


Figure 12. Full-Load Shutdown Waveforms

Typical Characteristics (continued)

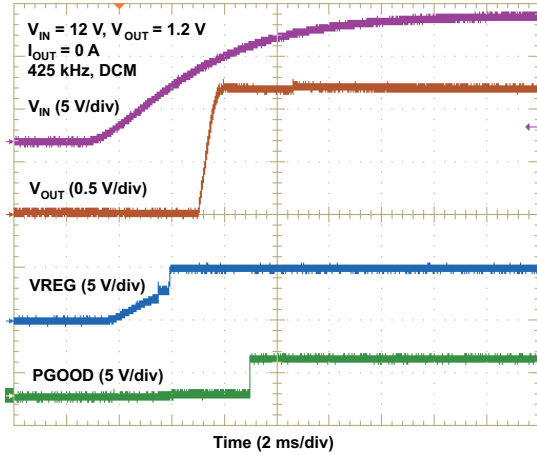


Figure 13. No-Load UVLO Start-Up Waveforms

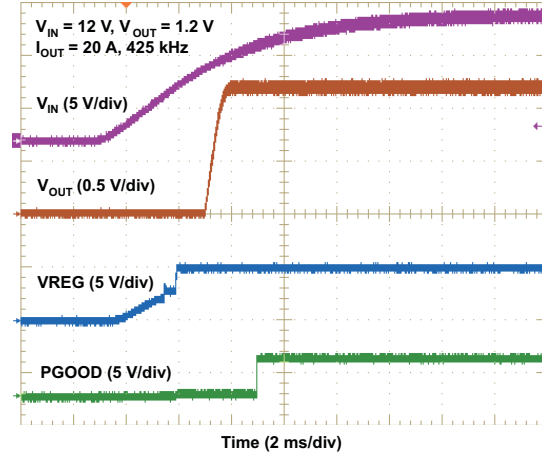


Figure 14. Full-Load UVLO Start-Up Waveforms

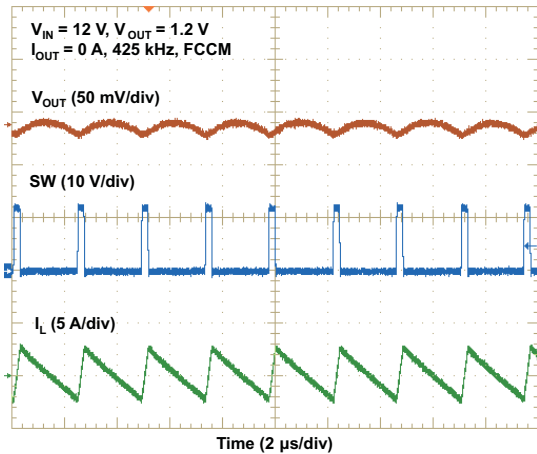


Figure 15. 1.2-V Output Ripple with FCCM

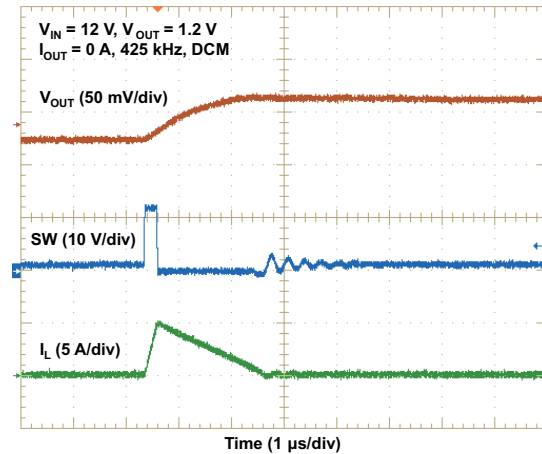


Figure 16. 1.2-V Output Ripple with DCM

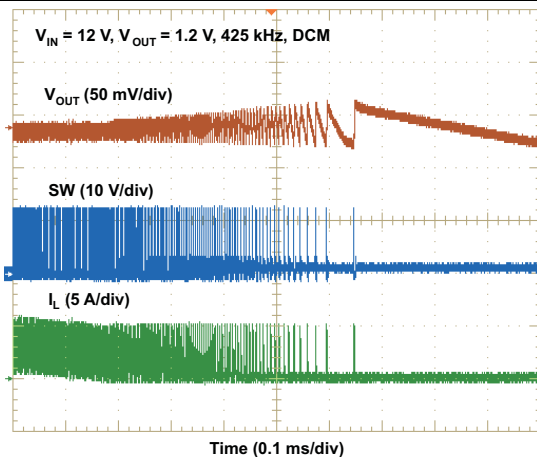


Figure 17. CCM to DCM Transitions

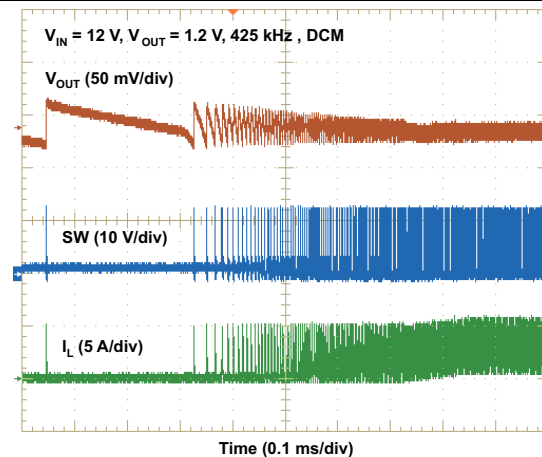


Figure 18. DCM to CCM Transitions

Typical Characteristics (continued)

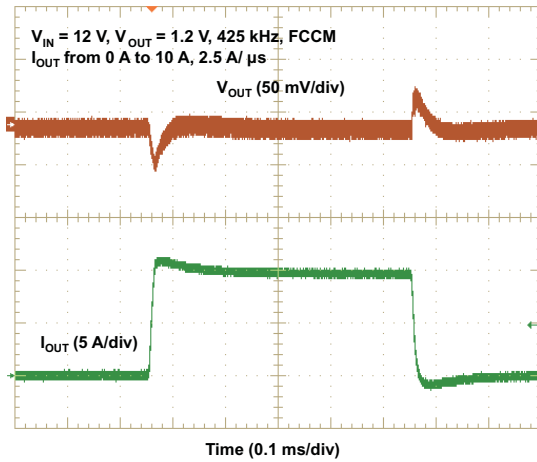


Figure 19. FCCM Load Transients

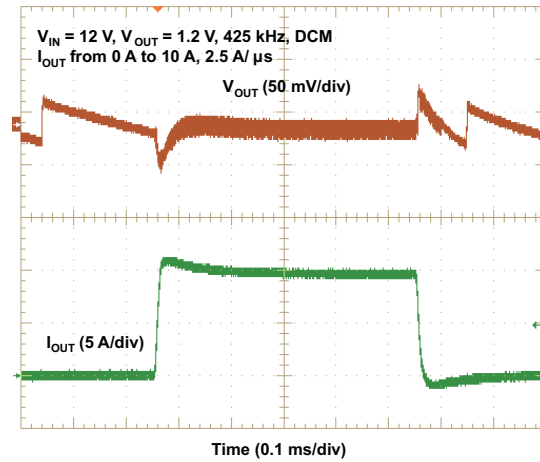


Figure 20. DCM Load Transients

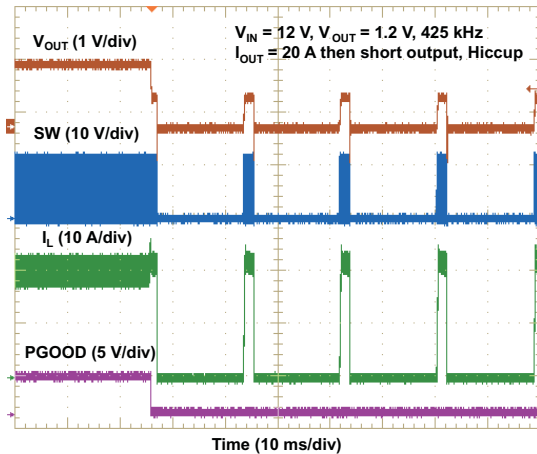


Figure 21. Output Short Circuit Protection with Hiccup

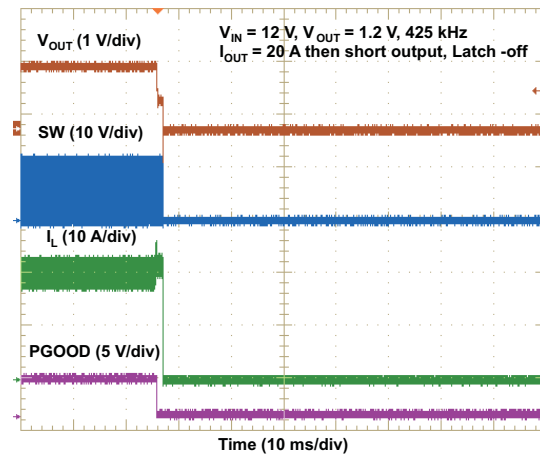


Figure 22. Output Short Circuit Protection with Latch-off

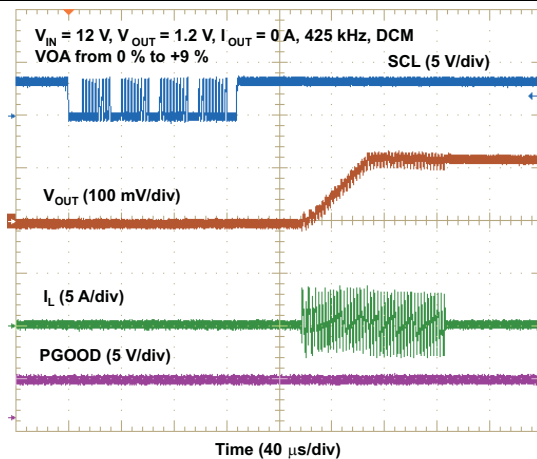


Figure 23. No-Load  $V_{OUT}$  Adjustment Waveforms

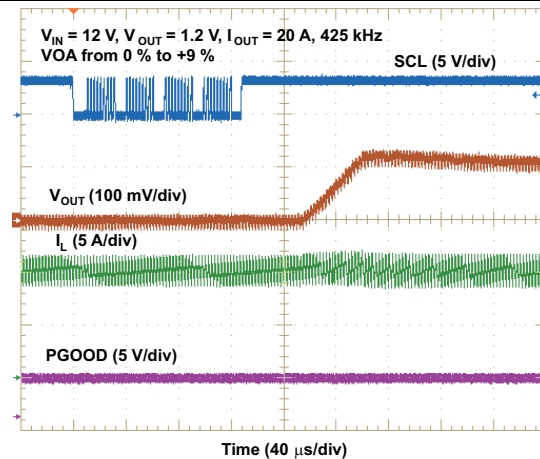


Figure 24. Full-Load  $V_{OUT}$  Adjustment Waveforms

Typical Characteristics (continued)

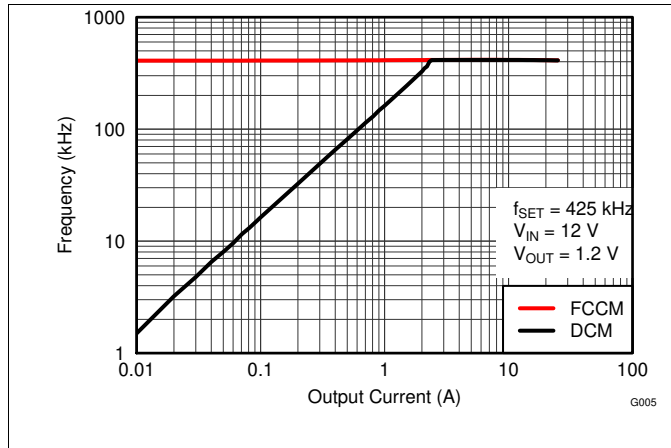


Figure 25. Switching Frequency vs. Output Current

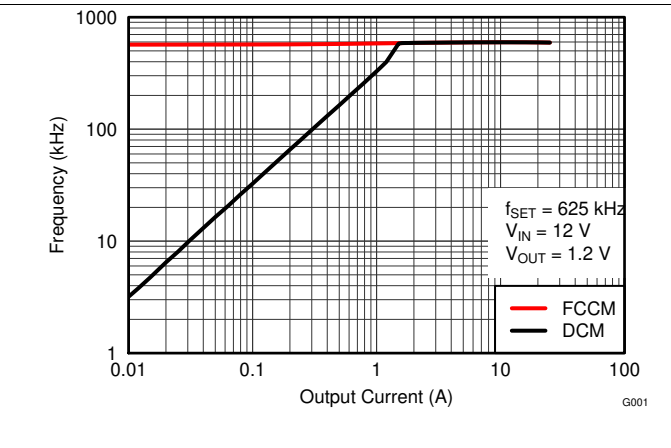


Figure 26. Switching Frequency vs. Output Current

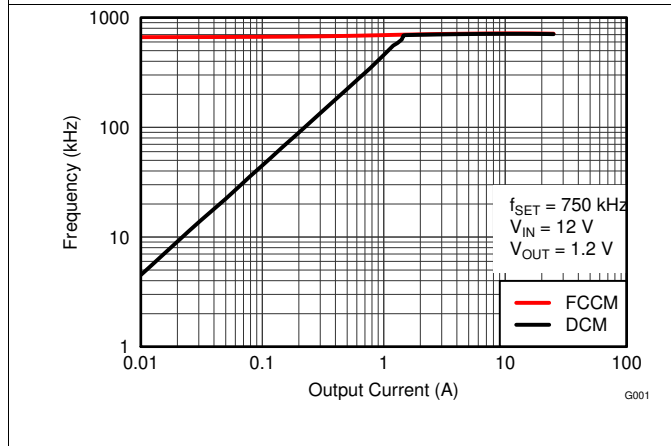


Figure 27. Switching Frequency vs. Output Current

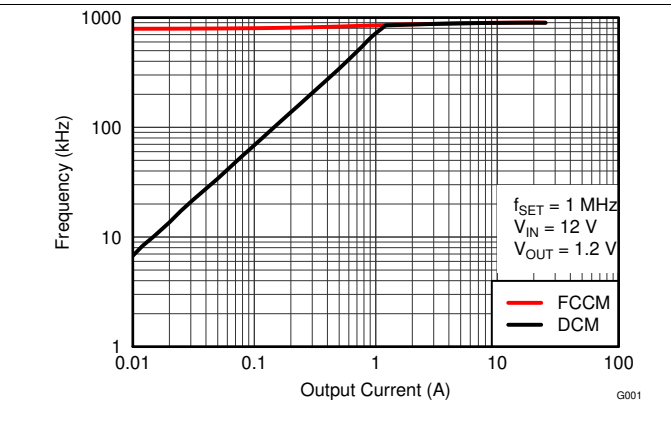


Figure 28. Switching Frequency vs. Output Current

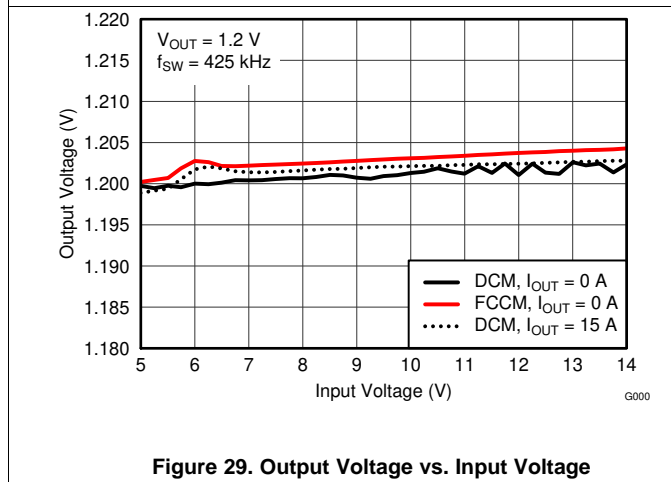


Figure 29. Output Voltage vs. Input Voltage

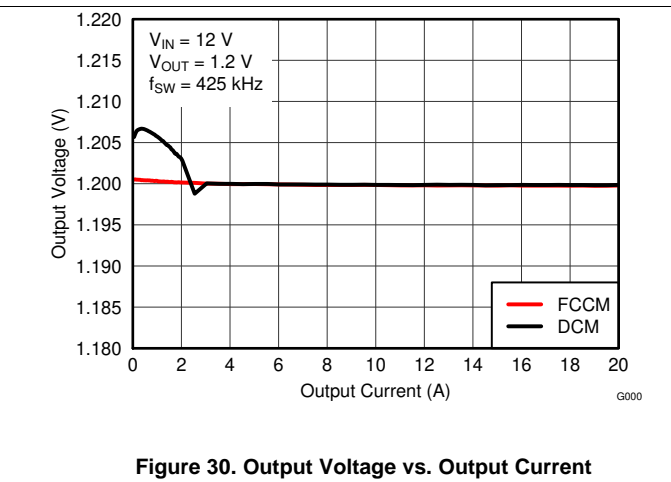
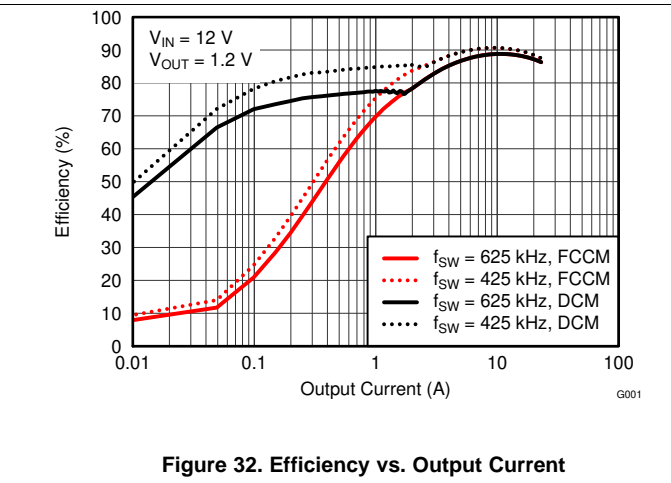
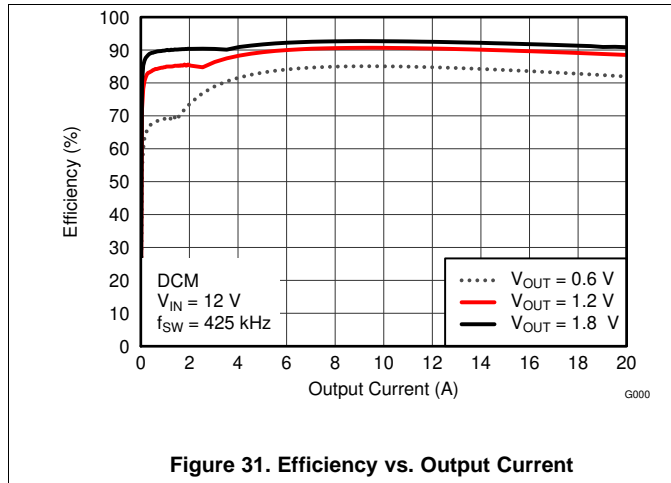


Figure 30. Output Voltage vs. Output Current

**Typical Characteristics (continued)**

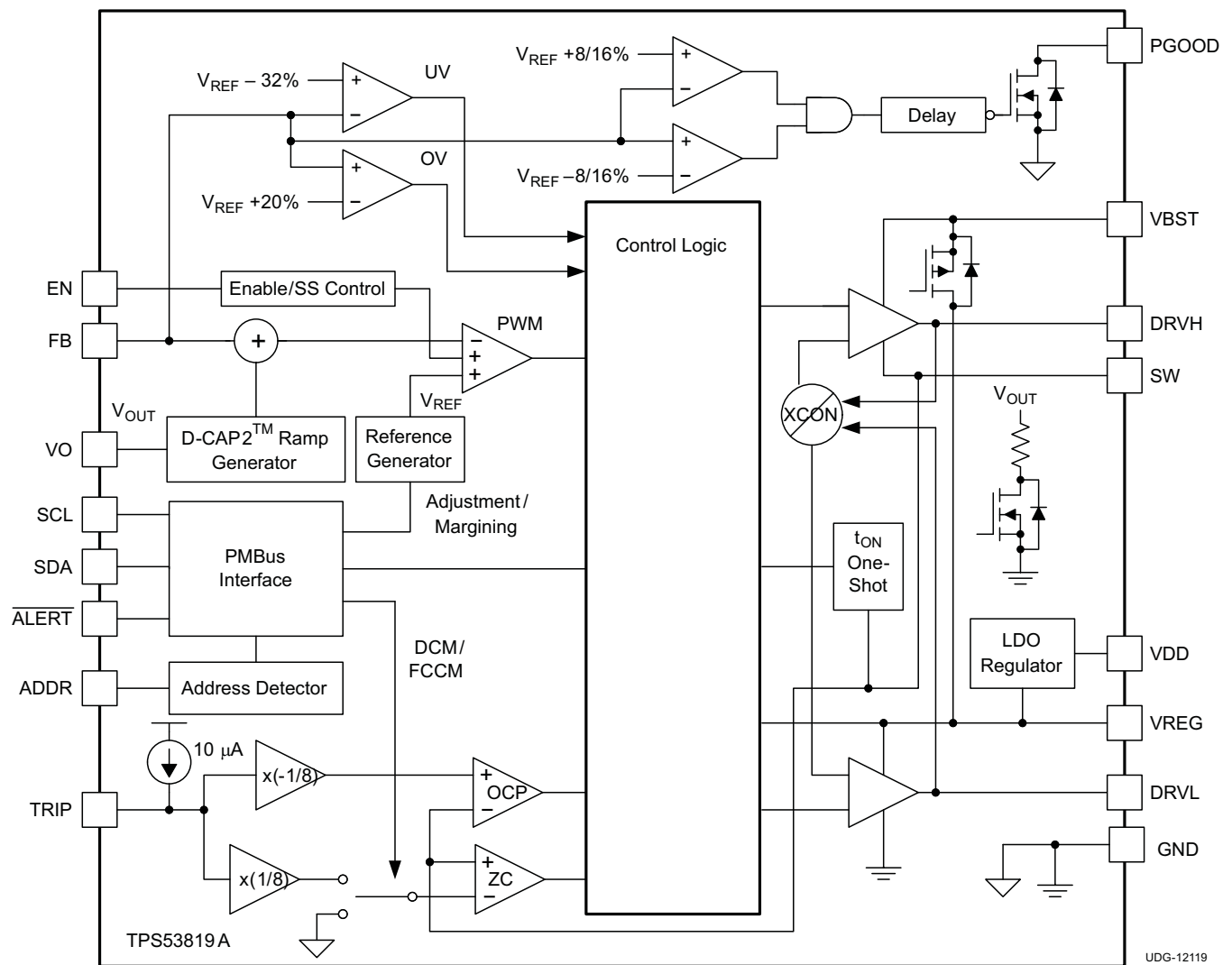


## 7 Detailed Description

### 7.1 Overview

The TPS53819A is a high-efficiency, single-channel, synchronous buck regulator controller that uses the PMBus protocol. It is suitable for low output voltage, point-of-load applications in computing and similar digital consumer applications. The device features proprietary D-CAP2 mode control combined with adaptive on-time architecture. This combination is ideal for building modern low duty-ratio and ultra-fast load step response DC-DC converters. The output voltage ranges from 0.6 V to 5.5 V. The conversion input voltage range is from 3 V to 28 V. The D-CAP2 mode uses emulated current information to control the loop modulation. One advantage of this control scheme is that it does not require an external phase compensation network, which makes it easy to use. It also allows for a low external component count. The switching frequency is selectable from eight preset values through the PMBus interface. Adaptive on-time control tracks the preset switching frequency over a wide range of input and output voltages while increasing the switching frequency as needed during load step transient.

### 7.2 Functional Block Diagram





## 7.3 Feature Description

### 7.3.1 Enable and Soft-Start

When the EN pin voltage rises above the enable threshold voltage and/or ON\_OFF bit is set via PMBus according to the setting in OPERATION command, the controller enters a start-up sequence. After a programmed power-on-delay duration from 0.35 ms to 32.86 ms, the internal DAC starts ramping up the reference voltage from 0 V to a target voltage (typically 0.6 V) with the programmed soft-start time from 1 ms to 8 ms. The device maintains a smooth and constant output voltage ramp-up during start-up regardless of load current.

### 7.3.2 Adaptive On-Time Control

The TPS53819A does not have a dedicated oscillator. The device operates with a pseudo-constant frequency by feed-forwarding the input and output voltages into the on-time one-shot timer. The adaptive on-time control adjusts the on-time to be inversely proportional to the input voltage and proportional to the output voltage ( $t_{ON} \propto V_{OUT}/V_{IN}$ ). This makes the switching frequency fairly constant in steady state conditions over a wide input voltage range. The switching frequency is selectable from 275 kHz to 1 MHz via PMBus (FREQUENCY\_CONFIG).

### 7.3.3 Zero Crossing Detection

The TPS53819A uses a low offset comparator to detect SW node zero crossing event in order to optimize turn-off timing of low-side MOSFET.

### 7.3.4 Output Discharge Control

When the EN pin voltage falls below the enable threshold voltage and/or ON\_OFF bit is reset via PMBus according to the setting in OPERATION command, the TPS53819A discharges output capacitor using internal MOSFET connected between the VOUT pin and the GND pin while the high-side and low-side MOSFETs are maintained in the OFF state. The typical discharge resistance is 40  $\Omega$ .

### 7.3.5 Low-Side Driver

The low-side driver is designed to drive high-current, low- $R_{DS(on)}$ , N-channel MOSFETs. The drive capability is represented by the internal resistance, which is 0.9  $\Omega$  for VREG to DRV\_L and 0.5  $\Omega$  for DRV\_L to GND. A dead-time period to prevent shoot through is internally generated between high-side MOSFET OFF to low-side MOSFET ON, and low-side MOSFET OFF to high-side MOSFET ON. The 5-V, VREG supply voltage delivers the bias voltage. A bypass capacitor connected between the VREG and GND pins supplies the instantaneous drive current. Equation 1 shows the average low-side gate drive current.

$$I_{GL} = C_{GL} \times V_{VDRV} \times f_{SW} \quad (1)$$

### 7.3.6 High-Side Driver

The high-side driver drives high current, low  $R_{DS(on)}$ , N-channel MOSFETs. When configured as a floating driver, the VREG pin supply delivers the bias voltage. Equation 2 shows the average high-side gate current.

$$I_{GH} = C_{GH} \times V_{VDRV} \times f_{SW} \quad (2)$$

The flying capacitor between the VBST and SW pins supplies the instantaneous drive current. The internal resistance, which is 1.6  $\Omega$  for VBST to DRV\_H and 0.6  $\Omega$  for DRV\_H to SW represents the drive capability. Equation 3 calculates the driver power dissipation required for the TPS53819A

$$P_{DRV} = (I_{GL} + I_{GH}) \times V_{VDRV} \quad (3)$$

### 7.3.7 Power Good

The TPS53819A indicates the switcher output is within the target range when the power-good output is high. The power-good function activates after the soft-start operation has finished. If the output voltage comes within  $\pm 8\%$  of the target value, internal comparators detect power-good state and the power-good signal becomes high after a programmed delay time between 0.25 ms and 131 ms. If the output voltage goes outside of  $\pm 16\%$  of the target value, the power-good signal becomes low after a 2- $\mu$ s internal delay. The power-good output is an open drain output and must be pulled up externally.

## Feature Description (continued)

### 7.3.8 Current Sense and Overcurrent Protection

TPS53819A has cycle-by-cycle overcurrent limiting control. The inductor current is monitored during the OFF state and the controller maintains the OFF state during the period when inductor current is larger than the overcurrent trip level. In order to provide both good accuracy and cost effective solution, TPS53819A supports temperature compensated MOSFET on-resistance ( $R_{DS(on)}$ ) sensing. The TRIP pin should be connected to GND through the trip voltage setting resistor,  $R_{TRIP}$ . The TRIP terminal sources  $I_{TRIP}$  current, which is 10  $\mu$ A typically at room temperature, and the trip level is set to the OCL trip voltage  $V_{TRIP}$  as shown in Equation 4. Note that the  $V_{TRIP}$  is limited up to approximately 3 V internally.

$$V_{TRIP} \text{ (mV)} = R_{TRIP} \text{ (k}\Omega\text{)} \times I_{TRIP} \text{ (\mu A)} \quad (4)$$

The inductor current is monitored by the voltage between GND pin and SW pin so that SW pin should be properly connected to the drain terminal of the low-side MOSFET. The TRIP current has a 4700-ppm/ $^{\circ}$ C temperature slope to compensate the temperature dependency of the on-resistance. The device uses the GND pin as the positive current sensing node. As the comparison occurs during the OFF state,  $V_{TRIP}$  sets the valley level of the inductor current. Thus, the average load current at the overcurrent threshold,  $I_{OCP}$ , is calculated as shown in Equation 5.

$$I_{OCP} = \frac{V_{TRIP}}{(8 \times R_{DS(on)})} + \frac{I_{IND(ripple)}}{2} = \frac{V_{TRIP}}{(8 \times R_{DS(on)})} + \frac{1}{2 \times L \times f_{SW}} \times \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{V_{IN}} \quad (5)$$

In an overcurrent condition, the load current exceeds the inductor current delivered to the output capacitor, thus the output voltage tends to fall. Eventually, it crosses the undervoltage protection threshold and the device shuts down. If hiccup mode is selected, then after a hiccup delay time (8.96 ms + 7x programmed soft-start time), the controller restarts. If the overcurrent condition remains, the procedure is repeated and the device enters hiccup mode. During the CCM, the negative current limit (NCL) protects the external FET from carrying too much current. The OCLN detect threshold is set at the same absolute value as positive current limit (OCLP) but with negative polarity. Note that the threshold still represents the valley value of the inductor current. When an OCLP or OCLN event occurs, the corresponding fault signals (IOUT\_OC and IOUT) of the STATUS\_WORD register is latched to indicate the faults and can be read via PMBus.

### 7.3.9 Overvoltage and Undervoltage Protection

TPS53819A monitors a resistor divided feedback voltage to detect overvoltage and undervoltage conditions. When the feedback voltage becomes lower than 68% of the target voltage, the undervoltage protection (UVP) comparator output goes high and an internal UVP delay time counter begins counting. After 1 ms, the device turns OFF both high-side and low-side MOSFETs drivers. If the hiccup mode is selected, then the controller restarts after a hiccup delay time (8.96 ms + 7 x programmed soft-start time). This function is enabled after the soft-start operation is completed. When the feedback voltage becomes higher than 120% of the target voltage, the overvoltage protection (OVP) comparator output goes high and the circuit latches OFF the high-side MOSFET driver and latches ON the low-side MOSFET driver. If the sensed inductor current reaches the negative current limit, then the low-side MOSFET driver is turned OFF, and high-side MOSFET driver is turned ON with an appropriate on-time to limit the inductor current while the output voltage discharges.

### 7.3.10 Out-of-Bound Protection

TPS53819A has an out-of-bound (OOB) overvoltage protection that tries to protect the output load at a much lower overvoltage threshold of 8% above the target voltage. OOB protection does not trigger an overvoltage fault, so the device is not latched off after an OOB event. OOB protection is intended as an early no-fault overvoltage protection mechanism, in addition to the official overvoltage protection as described in the [Overvoltage and Undervoltage Protection](#) section.

### 7.3.11 UVLO Protection

The TPS53819A has VDD undervoltage lockout protection (UVLO). When the VDD voltage is lower than the programmed UVLO threshold voltage, the switch mode power supply shuts OFF. This is a non-latch protection, but if VDD UVLO occurs when the switcher is enabled by either EN pin or ON\_OFF bit via PMBus, the corresponding fault signals (VIN\_UV and INPUT) of the STATUS\_WORD register latch off to indicate the fault condition, and can be read via PMBus.

## Feature Description (continued)

### 7.3.12 Thermal Shutdown

The TPS53819A has an over-temperature protection feature. If the temperature exceeds the threshold value (typically 140°C), the device is shut OFF. This is a non-latch protection, but when the temperature exceeds the threshold value, the corresponding fault signal (TEMP) of the STATUS\_WORD register latches off to indicate the fault condition, and can be read via PMBus.

## 7.4 Device Functional Modes

### 7.4.1 Light-Load Condition in Auto-Skip Operation (Eco-mode)

If the discontinuous conduction mode (DCM) is selected via PMBus (MODE\_SOFT\_START\_CONFIG), TPS53819A automatically reduces the switching frequency at light-load conditions to maintain high efficiency. Specifically, as the output current decreases from heavy load condition, the inductor current is also reduced and eventually comes to the point that its ripple valley current touches zero level, which is the boundary between continuous conduction mode (CCM) and discontinuous conduction mode (DCM). The synchronous MOSFET is turned OFF when this zero inductor current is detected. As the load current further decreases, the converter runs into DCM.

---

#### NOTE

The zero current must be detected for at least 16 switching cycles to switch from CCM to DCM.

---

The on-time remains almost the same as continuous conduction mode so that it takes longer time to discharge the output capacitor with smaller load current to the reference voltage level. The transition point to the light-load operation  $I_{OUT(LL)}$  (i.e., the threshold between continuous and discontinuous conduction mode) is calculated in [Equation 6](#).

$$I_{OUT(LL)} = \frac{1}{2 \times L \times f_{SW}} \times \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{V_{IN}}$$

where

- $f_{SW}$  is the PWM switching frequency (6)

Switching frequency versus output current in the light-load condition is a function of  $L$ ,  $V_{IN}$  and  $V_{OUT}$ , but it decreases almost proportionally to the output current when below the  $I_{OUT(LL)}$  given in [Equation 6](#). For example, it is 65 kHz at  $I_{O(LL)}/5$  if the frequency setting is 325 kHz.

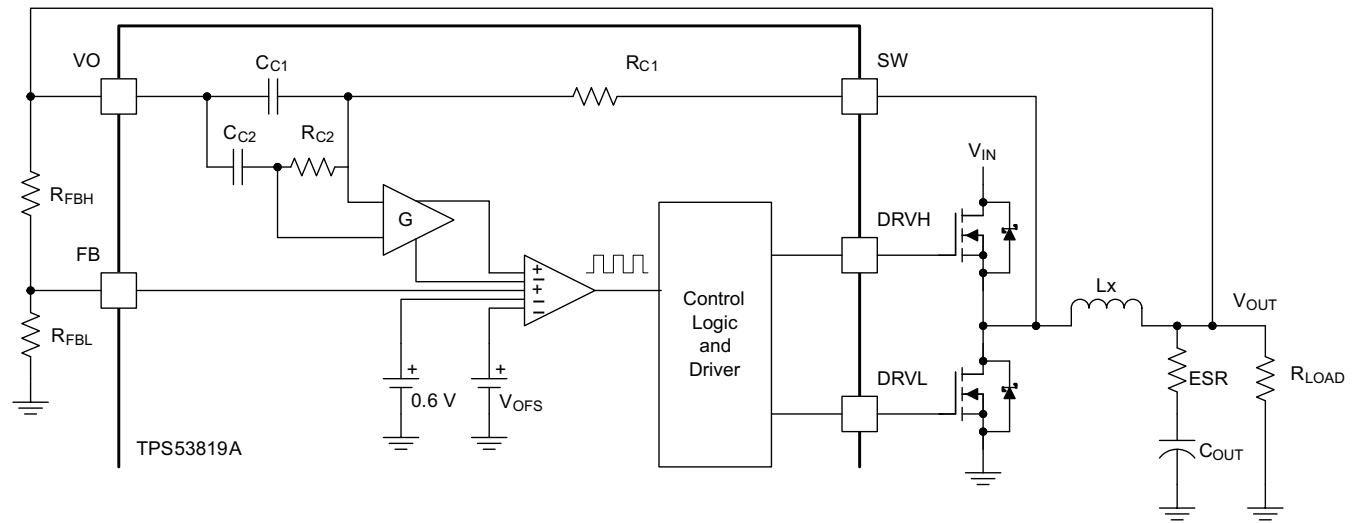
### 7.4.2 Forced Continuous Conduction Mode

When the forced continuous conduction mode (FCCM) is selected via PMBus (MODE\_SOFT\_START\_CONFIG), the controller maintains continuous conduction mode even in light-load condition. In FCCM mode, switching frequency maintains a constant level over the entire load range which is suitable for applications that need tight control of the switching frequency at a cost of lower efficiency. During the soft-start time, the controller maintains discontinuous conduction mode, and then switches to continuous conduction mode if FCCM is selected after the soft-start operation is completed.

### 7.4.3 D-CAP2™ Mode

From small-signal loop analysis, a buck converter using D-CAP2™ mode control architecture can be simplified as shown in [Figure 33](#).

Device Functional Modes (continued)



UDG-12120

Figure 33. Simplified Modulator Using D-CAP2™ Control Architecture

The D-CAP2 control architecture in TPS53819A includes an internal ripple generation network enabling the use of very low-ESR output capacitors such as multi-layer ceramic capacitors (MLCC). No external current sensing networks or compensators are required with D-CAP2 control architecture in order to simplify the power supply design. The role of the internal ripple generation network is to emulate the ripple component of the inductor current information and then combine it with the voltage feedback signal.  $V_{OFS}$  is the internal offset to compensate the offset caused by the internal ripple, and the typical  $V_{OFS}$  value is 4 mV. The 0-dB frequency of the D-CAP2 architecture can be approximated as shown in Equation 7.

$$f_0 = \frac{R_{C1} \times C_{C1} \times 0.6 \times (0.67 + D)}{2\pi \times G \times L_X \times C_{OUT} \times V_{OUT}}$$

where

- G is gain of the amplifier which amplifies the ripple current information generated by the network
- D is the duty ratio

(7)

The typical G value is 0.25. The  $R_{C1}C_{C1}$  time constant value varies according to the selected switching frequency as shown in Table 1.

Table 1. Switching Frequency Selection

SWITCHING FREQUENCY (kHz)	$R_{C1}C_{C1}$ TIME CONSTANT ( $\mu$ s)
275	75
325	
425	62
525	
625	48
750	
850	36
1000	

In order to secure enough phase margin, consider that  $f_0$  should be lower than 1/3 of the switching frequency, but is also higher than 5 times the  $f_{C2}$  as shown in [Equation 8](#).

$$5 \times f_{C2} \leq f_0 \leq \frac{f_{SW}}{3}$$

where

- $f_{C2}$  is determined by the internal network of  $R_{C2}$  and  $C_{C2}$  (1.4 kHz typ) (8)

This example describes a DC-DC converter with an input voltage range of 12-V and an output voltage of 1.2-V. If the switching frequency is 525 kHz and the inductor is given as 0.44μH, then  $C_{OUT}$  should be larger than 197 μF, and also be smaller than 4.9 mF based on the design requirements. The characteristics of the capacitors should be also taken into considerations. For MLCC, use X5R or better dielectric and take into account derating of the capacitance by both DC bias and AC bias. When derating by DC bias and AC bias are 80% and 50%, respectively, the effective derating is 40% because  $0.8 \times 0.5 = 0.4$ . The capacitance of specialty polymer capacitors may change depending on the operating frequency. Consult capacitor manufacturers for specific characteristics.

## 7.5 Programming

### 7.5.1 PMBus General Descriptions

The TPS53819A has seven internal custom user-accessible 8-bit registers. The PMBus interface has been designed for program flexibility, supporting a direct format for write operation. Read operations are supported for both combined format and stop separated format. While there is no auto increment or decrement capability in the TPS53819A PMBus logic, a tight software loop can be designed to randomly access the next register, regardless of which register was accessed first. The START and STOP commands frame the data packet and the REPEAT START condition is allowed when necessary.

The device can operate in either standard mode (100 kb/s) or fast mode (400 kb/s).

### 7.5.2 PMBus Slave Address Selection

The seven-bit slave address is  $001A_3A_2A_1A_0x$ , where  $A_3A_2A_1A_0$  is set by the ADDR pin on the device. Bit 0 is the data direction bit, i.e.,  $001A_3A_2A_1A_00$  is used for write operation and  $001A_3A_2A_1A_01$  is used for read operation.

### 7.5.3 PMBus Address Selection

The TPS53819A allows up to 16 different chip addresses for PMBus communication, with the first three bits fixed as 001. The address selection process is defined by the resistor divider ratio from VREG pin to ADDR pin, and the address detection circuit starts to work only after VDD input supply has risen above its UVLO threshold. The table below lists the divider ratio and some example resistor values. The 1% tolerance resistors with typical temperature coefficient of  $\pm 100\text{ppm}/^\circ\text{C}$  are recommended. Higher performance resistors can be used if tighter noise margin is required for more reliable address detection, as shown in [Table 2](#).

**Table 2. PMBus Address Selection Settings**

PMBus ADDRESS	RESISTOR DIVIDER RATIO	DIVIDER RATIO RANGE		HIGH-SIDE RESISTANCE (k $\Omega$ )	LOW-SIDE RESISTANCE (k $\Omega$ )
		LOW	HIGH		
00111111	> 0.557	—		1	300
00111110	0.509	0.4958	0.5247	160	165
00111101	0.461	0.4482	0.4772	180	154
00111100	0.416	0.4073	0.4294	200	143
00110111	0.375	0.3662	0.3886	200	120
00110110	0.334	0.3249	0.3476	220	110
00110011	0.297	0.2905	0.3067	249	105
00110010	0.263	0.2560	0.2725	249	88.7
00101111	0.229	0.2215	0.2385	240	71.5
00101110	0.195	0.1870	0.2044	249	60.4
00101101	0.160	0.1524	0.1703	249	47.5
00101100	0.126	0.1179	0.1363	249	36.0
00100111	0.096	0.0900	0.1024	255	27.0
00100110	0.068	0.0622	0.0752	255	18.7
00100011	0.041	0.0340	0.0480	270	11.5
00100010	< 0.013	—		300	1

## 7.5.4 Supported Formats

The supported formats are described in this section.

### 7.5.4.1 Direct Format: Write

The simplest format for a PMBus write is direct format. After the start condition [S], the slave chip address is sent, followed by an eighth bit indicating a write. The TPS53819A then acknowledges that it is being addressed, and the master responds with an 8-bit register address byte. The slave acknowledges and the master sends the appropriate 8-bit data byte. Again the slave acknowledges and the master terminates the transfer with the stop condition [P].

### 7.5.4.2 Combined Format: Read

After the start condition [S], the slave chip address is sent, followed by an eighth bit indicating a write. The TPS53819A then acknowledges that it is being addressed, and the master responds with an 8-bit register address byte. The slave acknowledges and the master sends the repeated start condition [Sr]. Again the slave chip address is sent, followed by an eighth bit indicating a read. The slave responds with an acknowledge followed by previously addressed 8 bit data byte. The master then sends a non-acknowledge (NACK) and finally terminates the transfer with the stop condition [P].

### 7.5.4.3 Stop-Separated Reads

Stop-separated read features are also available. This format allows a master to initialize the register address pointer for a read and return to that slave at a later time to read the data. In this format the slave chip address followed by a write bit are sent after a start [S] condition. The TPS53819A then acknowledges it is being addressed, and the master responds with the 8-bit register address byte. The master then sends a stop or restart condition and may then address another slave. After performing other tasks, the master can send a start or restart condition to the device with a read command. The device acknowledges this request and returns the data from the register location that had been set up previously.

## 7.5.5 Supported PMBus Commands

The TPS53819A supports the PMBus commands shown in [Table 1](#) only. Not all features of each PMBus command are supported. The CLEAR\_FAULTS, STORE\_DEFAULT\_ALL and RESTORE\_DEFAULT\_ALL commands have no data bytes. The non-volatile memory (NVM) cells inside the TPS53819A can permanently store some registers.

**Table 3. Supported PMBus Commands**

COMMAND	NOTES
OPERATION	Turn on or turn off switching converter only
ON_OFF_CONFIG	ON/OFF configuration
CLEAR_FAULTS	Clear all latched status flags
WRITE_PROTECT	Control writing to the PMBus device
STORE_DEFAULT_ALL	Store contents of user-accessible registers to non-volatile memory cells
RESTORE_DEFAULT_ALL	Copy contents of non-volatile memory cells to user-accessible registers
STATUS_WORD	PMBus read-only status and flag bits
CUSTOM_REG	MFR_SPECIFIC_00 (Custom Register 0): Custom register
DELAY_CONTROL	MFR_SPECIFIC_01 (Custom Register 1): Power on and power good delay times
MODE_SOFT_START_CONFIG	MFR_SPECIFIC_02 (Custom Register 2): Mode and soft-start time
FREQUENCY_CONFIG	MFR_SPECIFIC_03 (Custom Register 3): Switching frequency control
VOUT_ADJUSTMENT	MFR_SPECIFIC_04 (Custom Register 4): Output voltage adjustment control
VOUT_MARGIN	MFR_SPECIFIC_05 (Custom Register 5): Output voltage margin levels
UVLO_THRESHOLD	MFR_SPECIFIC_06 (Custom Register 6): Turn-on input voltage UVLO threshold

### 7.5.6 Unsupported PMBus Commands

Do not send any unsupported commands to the TPS53819A. Even though the device receives an unsupported commands, it can acknowledge the unsupported commands and any related data bytes by properly sending the ACK bits. However, the device ignores the unsupported commands and any related data bytes, which means they do not affect the device operation in any way. Although the TPS53819A may acknowledge but ignore unsupported commands and data bytes, it can however, set the CML bit in the STATUS\_BYTE register and then pull down the ALERT pin to notify the host. For this reason, unsupported commands and data bytes should not be sent to TPS53819A.

## 7.6 Register Maps

### 7.6.1 OPERATION [01h] (R/W Byte)

The TPS53819A supports only the functions of the OPERATION command shown in [Table 4](#).

**Table 4. OPERATION Command Supported Functions**

COMMAND	DEFINITION	DESCRIPTION	NVM
OPERATION<7>	ON_OFF	0: turn off switching converter 1: turn on switching converter	—
OPERATION<6>	—	not supported and don't care	—
OPERATION<5:2>	OPMARGIN<3:0>	00xx: turn off output voltage margin function 0101: turn on output voltage margin low and ignore fault 0110: turn on output voltage margin low and act on fault 1001: turn on output voltage margin high and ignore fault 1010: turn on output voltage margin high and act on fault	—
OPERATION<1>	—	not supported and don't care	—
OPERATION<0>	—	not supported and don't care	—

### 7.6.2 ON\_OFF\_CONFIG [02h] (R/W Byte)

The TPS53819A supports only the functions of the ON\_OFF\_CONFIG command shown in [Table 5](#).

**Table 5. ON\_OFF\_CONFIG Command Supported Functions**

COMMAND	DEFINITION	DESCRIPTION	NVM
ON_OFF_CONFIG<7>	—	not supported and don't care	—
ON_OFF_CONFIG<6>	—	not supported and don't care	—
ON_OFF_CONFIG<5>	—	not supported and don't care	—
ON_OFF_CONFIG<4>	PU	not supported and always set to 1	—
ON_OFF_CONFIG<3>	CMD	0: ignore ON_OFF bit (OPERATION<7>) <sup>(1)</sup> 1: act on ON_OFF bit (OPERATION<7>)	Yes
ON_OFF_CONFIG<2>	CP	0: ignore EN pin 1: act on EN pin <sup>(1)</sup>	Yes
ON_OFF_CONFIG<1>	PL	not supported and always set to 1	—
ON_OFF_CONFIG<0>	SP	not supported and always set to 1	—

(1) TI default.

Conditions required to enable the switcher:

- If CMD is cleared and CP is set, then the switcher can be enabled only by the EN pin.
- If CMD is set and CP is cleared, then the switcher can be enabled only by the ON\_OFF bit (OPERATION<7>) via PMBus.
- If both CMD and CP are set, then the switcher can be enabled only when both the ON\_OFF bit (OPERATION<7>) and the EN pin are commanding to enable the device.
- If both CMD and CP are cleared, then the switcher is automatically enabled after the ADDR detection sequence completes, regardless of EN pin and ON\_OFF bit polarities.



### 7.6.3 WRITE\_PROTECT [10h] (R/W Byte)

The WRITE\_PROTECT command is used to control writing to the PMBus device. The intent of this command is to provide protection against accidental changes. This command has one data byte as described in [Table 6](#).

**Table 6. WRITE\_PROTECT Command Supported Functions**

COMMAND	DEFINITION	DESCRIPTION	NVM	
WRITE_PROTECT<7:0>	WP<7:0>	10000000:	Disable all writes, except the WRITE_PROTECT command.	—
		01000000:	Disable all writes, except the WRITE_PROTECT and OPERATION commands.	—
		00100000:	Disable all writes, except the WRITE_PROTECT, OPERATION, and ON_OFF_CONFIG commands.	—
		00000000:	Enable writes to all commands.	—
		Others:	Fault data	—

### 7.6.4 CLEAR\_FAULTS [03h] (Send Byte)

The CLEAR\_FAULTS command is used to clear any fault bits in the STATUS\_WORD and STATUS\_BYTE registers that have been set. This command clears all bits in all status registers. Simultaneously, the TPS53819A releases its ALERT signal output if the device is asserting the ALERT signal. If the fault condition is still present when the bit is cleared, the fault bits shall immediately be set again, and the ALERT signal should also be re-asserted.

The CLEAR\_FAULTS does not cause a unit that has latched off for a fault condition to restart. Units that have been shut down for a fault condition can be restarted with one of the following conditions.

- The output is commanded through the EN pin and/or ON\_OFF bit based on the ON\_OFF\_CONFIG setting to turn off and then to turn back on.
- VDD power is cycled for TPS53819A

The CLEAR\_FAULT command is used to clear the fault bits in the STATUS\_WORD and STATUS\_BYTE commands, and to release the ALERT pin. It is recommended not to send CLEAR\_FAULT command when there is no fault to cause the ALERT pin to pull down.

### 7.6.5 STORE\_DEFAULT\_ALL [11h] (Send Byte)

The STORE\_DEFAULT\_ALL command instructs TPS53819A to copy the entire contents of the operating memory to the corresponding locations in the NVM. The updated contents in the non-volatile memory (NVM)s become the new default values. The STORE\_DEFAULT\_ALL command can be used while the device is operating. However, the device may be unresponsive during the copy operation with unpredictable results. (see *PMBus Power System Management Protocol Specification, Part II - Command Language, Revision, 1.2, 6 Sept. 2010. [www.powerSIG.org](http://www.powerSIG.org)*). It is recommended not to exceed 1000 write/erase cycles for non-volatile memory (NVM).

### 7.6.6 RESTORE\_DEFAULT\_ALL [12h] (Send Byte)

The RESTORE\_DEFAULT\_ALL command instructs TPS53819A to copy the entire contents of the NVMs to the corresponding locations in the operating memory. The values in the operating memory are overwritten by the value retrieved from the NVM. It is permitted to use the RESTORE\_DEFAULT\_ALL command while the device is operating. However, the device may be unresponsive during the copy operation with unpredictable results.

### 7.6.7 STATUS\_WORD [79h] (Read Word)

The TPS53819A does not support all functions of the STATUS\_WORD command. A list of supported functions appears in Table 7. A status bit reflects the current state of the converter. Status bit becomes high when the specified condition has occurred and goes low when the specified condition has disappeared. A flag bit is a latched bit that becomes high when the specified condition has occurred and does not go back low when the specified condition has disappeared. STATUS\_BYTE command is a subset of the STATUS\_WORD command, or more specifically the lower byte of the STATUS\_WORD.

**Table 7. STATUS\_WORD Command Supported Functions**

COMMAND	DEFINITION	DESCRIPTION
<b>LOW BYTE: STATUS_BYTE [78h]</b>		
Low STATUS_WORD<7>	BUSY	not supported and always set to 0
Low STATUS_WORD<6>	OFF	0: raw status indicating device is providing power to output voltage 1: raw status indicating device is not providing power to output voltage
Low STATUS_WORD<5>	VOUT_OV	0: latched flag indicating no output voltage overvoltage fault has occurred 1: latched flag indicating an output voltage overvoltage fault has occurred
Low STATUS_WORD<4>	IOUT_OC	0: latched flag indicating no output current overcurrent fault has occurred 1: latched flag indicating an output current overcurrent fault has occurred
Low STATUS_WORD<3>	VIN_UV	0: latched flag indicating input voltage is above the UVLO turn-on threshold 1: latched flag indicating input voltage is below the UVLO turn-on threshold
Low STATUS_WORD<2>	TEMP	0: latched flag indicating no OT fault has occurred 1: latched flag indicating an OT fault has occurred
Low STATUS_WORD<1>	CML	0: latched flag indicating no communication, memory or logic fault has occurred 1: latched flag indicating a communication, memory or logic fault has occurred
Low STATUS_WORD<0>	OTHER	not supported and always set to 0
<b>HIGH BYTE</b>		
High STATUS_WORD<7>	VOUT	0: latched flag indicating no output voltage fault or warning has occurred 1: latched flag indicating a output voltage fault or warning has occurred
High STATUS_WORD<6>	IOUT	0: latched flag indicating no output current fault or warning has occurred 1: latched flag indicating an output current fault or warning has occurred
High STATUS_WORD<5>	INPUT	0: latched flag indicating no input voltage fault or warning has occurred 1: latched flag indicating a input voltage fault or warning has occurred
High STATUS_WORD<4>	MFR	not supported and always set to 0
High STATUS_WORD<3>	$\overline{\text{PGOOD}}$	0: raw status indicating PGOOD pin is at logic high 1: raw status indicating PGOOD pin is at logic low
High STATUS_WORD<2>	FANS	not supported and always set to 0
High STATUS_WORD<1>	OTHER	not supported and always set to 0
High STATUS_WORD<0>	UNKNOWN	not supported and always set to 0

The latched flags of faults can be removed or corrected only until **one** of the following conditions occurs:

- The device receives a CLEAR\_FAULTS command.
- The output is commanded through the EN pin and/or ON\_OFF bit based on the ON\_OFF\_CONFIG setting to turn off and then to turn back on
- VDD power is cycled for TPS53819A

If the fault condition remains present when the bit is cleared, the fault bits are immediately set again, and the ALERT signal is re-asserted.

TPS53819A supports the  $\overline{\text{ALERT}}$  pin to notify the host of fault conditions. Therefore, the best practice for monitoring the fault conditions from the host is to treat the  $\overline{\text{ALERT}}$  pin as an interrupt source for triggering the corresponding interrupt service routine. It is recommended not to keep polling the STATUS\_WORD or STATUS\_BYTE registers from the host to reduce the firmware overhead of the host.

### 7.6.8 CUSTOM\_REG (MFR\_SPECIFIC\_00) [D0h] (R/W Byte)

Custom register 0 provides the flexibility for users to store any desired non-volatile information. For example, users can program this register to track versions of implementation or other soft identification information. The details of each setting are listed in [Table 8](#).

**Table 8. CUSTOM\_REG (MFR\_SPECIFIC\_00) Settings**

COMMAND	DEFINITION	DESCRIPTION	NVM
CUSTOM_REG<7>	—	not supported and don't care	—
CUSTOM_REG<6>	—	not supported and don't care	—
CUSTOM_REG<5:0>	CUSTOMWORD <5:0>	00000: <sup>(1)</sup> can be used to store any desired non-volatile information.	Yes

(1) TI default

### 7.6.9 DELAY\_CONTROL (MFR\_SPECIFIC\_01) [D1h] (R/W Byte)

Custom register 1 provides software control over key timing parameters of the controller: Power-on delay (POD) time and power-good delay (PGD) time. The details of each setting are listed in [Table 9](#).

**Table 9. DELAY\_CONTROL (MFR\_SPECIFIC\_01) Settings**

COMMAND	DEFINITION	DESCRIPTION	NVM
DELAY_CONTROL<7>	—	not supported and don't care	—
DELAY_CONTROL<6>	—	not supported and don't care	—
DELAY_CONTROL<5:3>	PGD<2:0>	000: 256 $\mu$ s 001: 512 $\mu$ s 010: 1.024 ms <sup>(1)</sup> 011: 2.048 ms 100: 4.096 ms 101: 8.192 ms 110: 16.384 ms 111: 131.072 ms	Yes
DELAY_CONTROL<2:0>	POD<2:0>	000: 356 $\mu$ s 001: 612 $\mu$ s 010: 1.124 ms <sup>(1)</sup> 011: 2.148 ms 100: 4.196 ms 101: 8.292 ms 110: 16.484 ms 111: 32.868 ms	Yes

(1) TI default

### 7.6.10 MODE\_SOFT\_START\_CONFIG (MFR\_SPECIFIC\_02) [D2h] (R/W Byte)

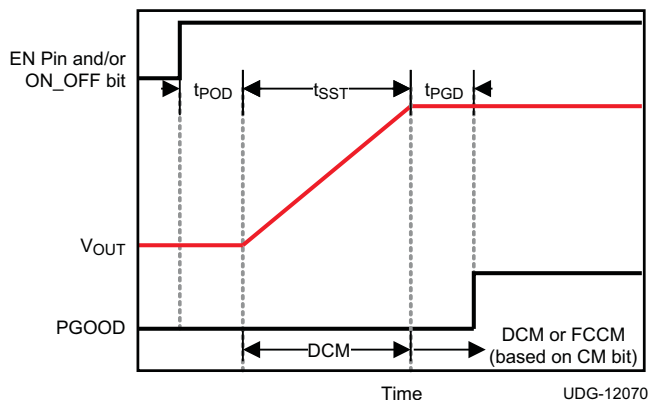
Custom register 2 provides software control over mode selection and soft-start time ( $t_{SS}$ ). The details of each setting are listed in Table 10.

**Table 10. MODE\_SOFT\_START\_CONFIG (MFR\_SPECIFIC\_02) Settings**

COMMAND	DEFINITION	DESCRIPTION	NVM
MODE_SOFT_START_CONFIG<7>	—	not supported and don't care	—
MODE_SOFT_START_CONFIG<6>	—	not supported and don't care	—
MODE_SOFT_START_CONFIG<5>	—	not supported and don't care	—
MODE_SOFT_START_CONFIG<4>	—	not supported and don't care	—
MODE_SOFT_START_CONFIG<3:2>	SST<1:0>	00: 1 ms <sup>(1)</sup> 01: 2 ms 10: 4 ms 11: 8 ms	Yes
MODE_SOFT_START_CONFIG<1>	HICLOFF	0: hiccup after UV <sup>(1)</sup> Hiccup interval is (8.96 ms + soft-start time × 7) 1: latch-off after UV	Yes
MODE_SOFT_START_CONFIG<0>	CM	0: DCM <sup>(1)</sup> 1: FCCM	Yes

(1) TI Default

Figure 34 shows the soft-start timing diagram of TPS53819A with the programmable power-on delay time ( $t_{POD}$ ), soft-start time ( $t_{SST}$ ), and PGOOD delay time ( $t_{PGD}$ ). During the soft-start time, the controller remains in discontinuous conduction mode (DCM), and then switches to forced continuous conduction mode (FCCM) at the end of soft-start if CM bit (MODE\_SOFT\_START\_CONFIG<0>) is set.



**Figure 34. Programmable Soft-Start Timing**

**7.6.11 FREQUENCY\_CONFIG (MFR\_SPECIFIC\_03) [D3h] (R/W Byte)**

Custom register 3 provides software control over frequency setting (FS). The details of FS setting are listed in [Table 11](#).

**Table 11. FREQUENCY\_CONFIG (MFR\_SPECIFIC\_03) Settings**

COMMAND	DEFINITION	DESCRIPTION	NVM
FREQUENCY_CONFIG<7>	—	not supported and don't care	—
FREQUENCY_CONFIG<6>	—	not supported and don't care	—
FREQUENCY_CONFIG<5>	—	not supported and don't care	—
FREQUENCY_CONFIG<4>	—	not supported and don't care	—
FREQUENCY_CONFIG<3>	—	not supported and don't care	—
FREQUENCY_CONFIG<2:0>	FS<2:0>	000: 275 kHz 001: 325 kHz 010: 425 kHz <sup>(1)</sup> 011: 525 kHz 100: 625 kHz 101: 750 kHz 110: 850 kHz 111: 1 MHz	Yes

(1) TI default.

### 7.6.12 VOUT\_ADJUSTMENT (MFR\_SPECIFIC\_04) [D4h] (R/W Byte)

Custom register 4 provides output voltage adjustment (VOA) in  $\pm 0.75\%$  steps, with a total range of  $\pm 9\%$ . When fine adjustment is used together with the margin setting, the change in the output voltage is determined by the multiplication of the two settings.

**Table 12. VOUT\_ADJUSTMENT (MFR\_SPECIFIC\_04) Settings**

COMMAND	DEFINITION	DESCRIPTION	NVM
VOUT_ADJUSTMENT<7>	—	not supported and don't care	—
VOUT_ADJUSTMENT<6>	—	not supported and don't care	—
VOUT_ADJUSTMENT<5>	—	not supported and don't care	—
VOUT_ADJUSTMENT<4:0>	VOA<4:0>	111xx: +9.00% 11011: +8.25% 11010: +7.50% 11001: +6.75% 11000: +6.00% 10111: +5.25% 10110: +4.50% 10101: +3.75% 10100: +3.00% 10011: +2.25% 10010: +1.50% 10001: +0.75% 10000: +0% <sup>(1)</sup> 01111: -0% 01110: -0.75% 01101: -1.50% 01100: -2.25% 01011: -3.00% 01010: -3.75% 01001: -4.50% 01000: -5.25% 00111: -6.00% 00110: -6.75% 00101: -7.50% 00100: -8.25% 000xx: -9.00%	Yes

(1) TI default.

### 7.6.13 Output Voltage Fine Adjustment Soft Slew Rate

To prevent sudden buildup of voltage across inductor, output voltage fine adjustment setting cannot change output voltage instantaneously. The internal reference voltage must slew slowly to its final target, and SST<1:0> is used to provide further programmability. The details of output voltage fine adjustment slew rate are shown in [Table 13](#).

**Table 13. Output Voltage Fine Adjustment Soft Slew Rate Settings**

COMMAND	DEFINITION	DESCRIPTION	NVM
MODE_SOFT_START_CONFIG<3:2>	SST<1:0>	00: 1 step per 4 $\mu\text{s}$ <sup>(1)</sup> 01: 1 step per 8 $\mu\text{s}$ 10: 1 step per 16 $\mu\text{s}$ 11: 1 step per 32 $\mu\text{s}$	Yes

(1) TI default.

**7.6.14 VOUT\_MARGIN (MFR\_SPECIFIC\_05) [D5h] (R/W Byte)**

Custom register 5 provides output voltage margin high (VOMH) and output voltage margin low (VOML) settings. This register works in conjunction with PMBus OPERATION command to raise or lower the output voltage by a specified amount. This register settings described in [Table 14](#) are also used together with the fine adjustment setting described in [Table 12](#). For example, setting fine adjustment to +9% and margin to +12% changes the output by +22.08%, whereas setting fine adjustment to –9% and margin to –9% change the output by –17.19%

**Table 14. VOUT\_MARGIN (MFR\_SPECIFIC\_05) Settings**

COMMAND	DEFINITION	DESCRIPTION	NVM
VOUT_MARGIN<7:4>	VOMH<3:0>	11xx: +12.0% 1011: +10.9% 1010: +9.9% 1001: +8.8% 1000: +7.7% 0111: +6.7% 0110: +5.7% 0101: +4.7% <sup>(1)</sup> 0100: +3.7% 0011: +2.8% 0010: +1.8% 0001: +0.9% 0000: +0%	Yes
VOUT_MARGIN<3:0>	VOML<3:0>	0000: –0% 0001: –1.1% 0010: –2.1% 0011: –3.2% 0100: –4.2% 0101: –5.2% <sup>(1)</sup> 0110: –6.2% 0111: –7.1% 1000: –8.1% 1001: –9.0% 1010: –9.9% 1011: –10.7% 11xx: –11.6%	Yes

(1) TI default.

### 7.6.15 Output Voltage Margin Adjustment Soft-Slew Rate

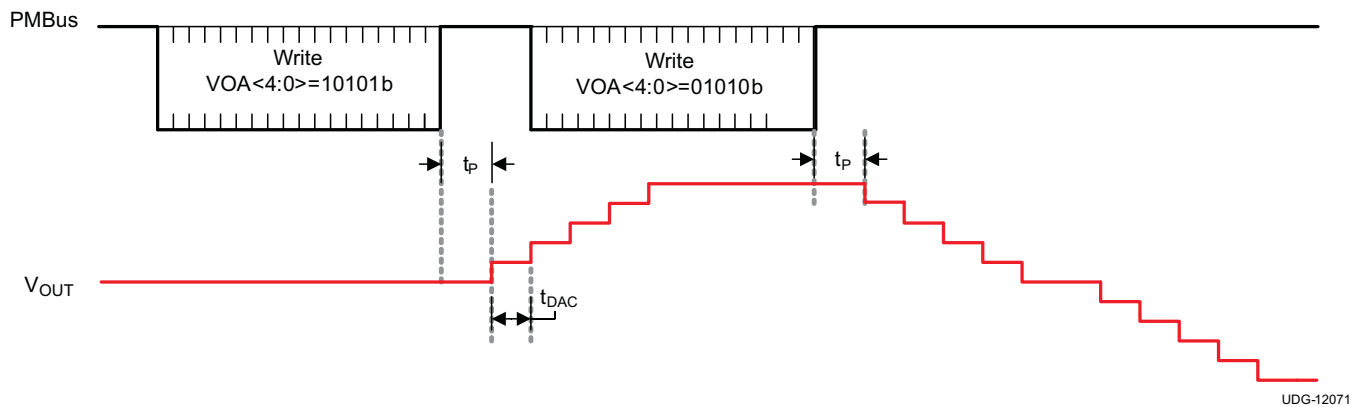
Similar to the output voltage fine adjustment, margin adjustment also cannot change output voltage instantaneously. The soft-slew rate of margin adjustment is also programmed by SST<1:0>. The details are listed in Table 15.

**Table 15. Output Voltage Margin Adjustment Soft-Slew Rate Settings**

COMMAND	DEFINITION	DESCRIPTION	NVM
MODE_SOFT_START_CONFIG<3:2>	SST<1:0>	00: 1 step per 4 $\mu$ s <sup>(1)</sup> 01: 1 step per 8 $\mu$ s 10: 1 step per 16 $\mu$ s 11: 1 step per 32 $\mu$ s	Yes

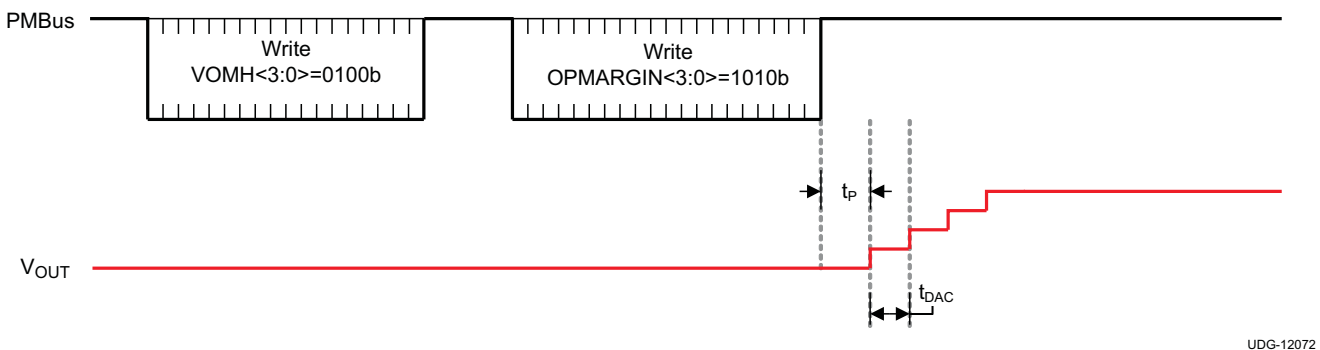
(1) TI default.

Figure 35 shows the timing diagram of the output voltage adjustment via PMBus. After receiving the write command of VOUT\_ADJUSTMENT (MFR\_SPECIFIC\_04), the output voltage starts to be adjusted after  $t_p$  delay time (about 50  $\mu$ s). The time duration  $t_{DAC}$  for each DAC step change can be controlled by SST bits (MODE\_SOFT\_START\_CONFIG<3:2> from 4  $\mu$ s to 32  $\mu$ s).



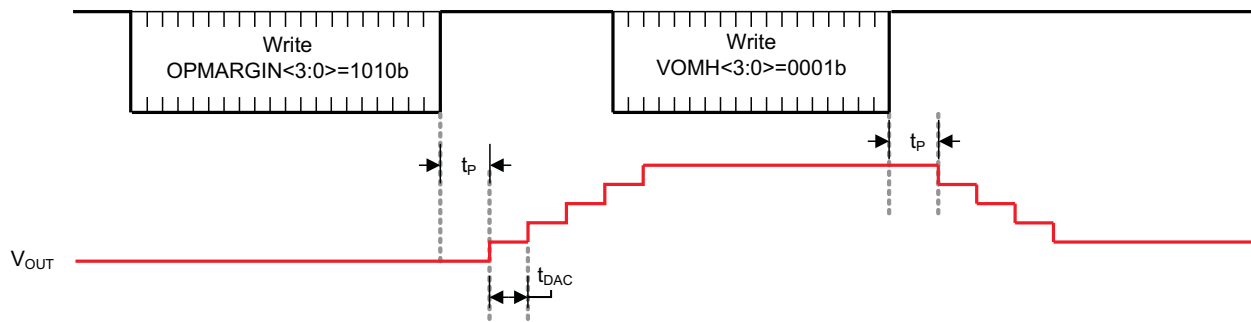
**Figure 35. Output Voltage Adjustment via PMBus**

The margining function is enabled by setting the OPERATION command, and the margining level is determined by the VOUT\_MARGIN (MFR\_SPECIFIC\_05) command. Figure 36 and Figure 37 illustrate the timing diagrams of the output voltage margining via PMBus. Figure 36 shows setting the margining level first, and then enabling margining by writing OPERATION command. After the OPERATION margin high command enables the margin high setting (VOMH<3:0>), the output voltage starts to be adjusted after  $t_p$  delay time (about 50  $\mu$ s). The time duration  $t_{DAC}$  for each DAC step change can be controlled by SST bits (MODE\_SOFT\_START\_CONFIG<3:2>) from 4  $\mu$ s to 32  $\mu$ s.



**Figure 36. Setting the Margining Level First**





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Figure 37. Enabling Margining First

As shown in Figure 37, the margining function is enabled first by a write command of OPERATION. The output voltage starts to be adjusted toward the default margin high level after  $t_P$  delay. Since the margining function has been enabled, the output voltage can be adjusted again by sending a different margin high level with a write command of VOUT\_MARGIN. The time duration  $t_{DAC}$  for each DAC step change can be also controlled by SST bits (MODE\_SOFT\_START\_CONFIG<3:2>) from 4  $\mu$ s to 32  $\mu$ s.

#### 7.6.16 UVLO\_THRESHOLD (MFR\_SPECIFIC\_06) [D6h]

Custom register 6 provides some limited programmability of input supply UVLO threshold, as described in Table 16. The default turn-on UVLO threshold is 4.25 V.

Table 16. UVLO\_THRESHOLD (MFR\_SPECIFIC\_06) Settings

COMMAND	DEFINITION	DESCRIPTION	NVM
UVLO_THRESHOLD<7>	—	not supported and don't care	—
UVLO_THRESHOLD<6>	—	not supported and don't care	—
UVLO_THRESHOLD<5>	—	not supported and don't care	—
UVLO_THRESHOLD<4>	—	not supported and don't care	—
UVLO_THRESHOLD<3>	—	not supported and don't care	—
UVLO_THRESHOLD<2:0>	VDDINUVLO<2:0>	0xx: 10.2 V 100: not supported and should not be used 101: 4.25 V <sup>(1)</sup> 110: 6.0 V 111: 8.1 V	Yes

(1) TI default.

## 8 Application and Implementation

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### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

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### 8.1 Application Information

The TPS53819A device is a small-sized, single buck controller with adaptive on-time D-CAP2 mode control and PMBus.

### 8.2 Typical Application

The following application shows a TPS53819A 12-V to 1.2-V point-of-load synchronous buck regulator.

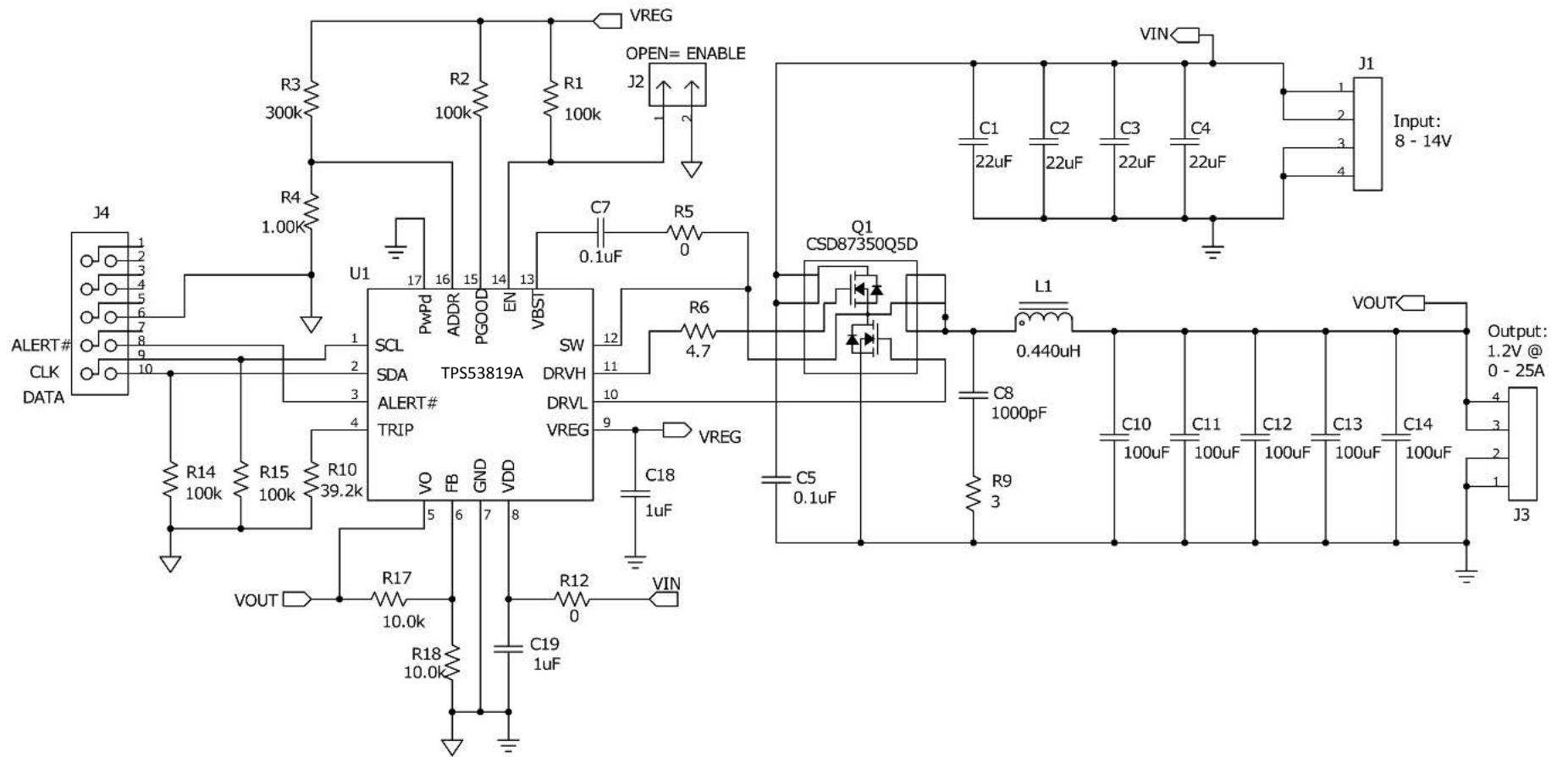


Figure 38. Typical Application Schematic, TPS53819A

## 8.2.1 Design Requirements

**Table 17. Design Example Specifications**

PARAMETER		MIN	TYP	MAX	UNIT
V <sub>VIN</sub>	Input voltage range	8	12	14	V
V <sub>VIN(ripple)</sub>	Input voltage ripple			240	mV <sub>PP</sub>
V <sub>OUT</sub>	Output voltage		1.2		V
V <sub>RIPPLE</sub>	Output voltage ripple			12	mV <sub>PP</sub>
I <sub>OUT</sub>	Output load current	0		20	A
I <sub>OCL</sub>	Output overcurrent		25		A
f <sub>SW</sub>	Switching frequency		425		kHz

## 8.2.2 Detailed Design Procedure

Selecting external components is a simple process using D-CAP2™ Mode

### 8.2.2.1 Custom Design With WEBENCH® Tools

[Click here](#) to create a custom design using the TPS53819A device with the WEBENCH® Power Designer.

1. Start by entering the input voltage (V<sub>VIN</sub>), output voltage (V<sub>OUT</sub>), and output current (I<sub>OUT</sub>) requirements.
2. Optimize the design for key parameters such as efficiency, footprint, and cost using the optimizer dial.
3. Compare the generated design with other possible solutions from Texas Instruments.

The WEBENCH Power Designer provides a customized schematic along with a list of materials with real-time pricing and component availability.

In most cases, these actions are available:

- Run electrical simulations to see important waveforms and circuit performance
- Run thermal simulations to understand board thermal performance
- Export customized schematic and layout into popular CAD formats
- Print PDF reports for the design, and share the design with colleagues

Get more information about WEBENCH tools at [www.ti.com/WEBENCH](http://www.ti.com/WEBENCH).

### 8.2.2.2 Switching Frequency

The switching frequency must first be decided on and is set using the PMBus. When deciding on a frequency a tradeoff between component size and efficiency must be made. A lower frequency reduces the switching losses in the MOSFETs improving efficiency but a larger inductance and/or output capacitance is required for low output voltage ripple. This example uses the TI default PMBus setting, 425 kHz.

### 8.2.2.3 Inductor (L1)

Determined the inductance to yield a ripple current (I<sub>IND(ripple)</sub>) of approximately ¼ to ½ of maximum output current. Larger ripple current increases output ripple voltage, improves the signal-to-noise ratio and helps stable operation. Maximum current ripple occurs with the maximum input voltage. [Equation 9](#) calculates the recommended inductance. After choosing the inductance, use [Equation 10](#) to calculate the ripple.

$$L = \frac{1}{I_{IND(ripple)} \times f_{SW}} \times \frac{(V_{IN(max)} - V_{OUT}) \times V_{OUT}}{V_{IN(max)}} = \frac{3}{I_{OUT(max)} \times f_{SW}} \times \frac{(V_{IN(max)} - V_{OUT}) \times V_{OUT}}{V_{IN(max)}} \quad (9)$$

$$I_{IND(ripple)} = \frac{1}{L \times f_{SW}} \times \frac{(V_{IN(max)} - V_{OUT}) \times V_{OUT}}{V_{IN(max)}} \quad (10)$$

The inductor requires a low DCR to achieve good efficiency. The inductor also requires enough margin above the peak inductor current before saturation. The peak inductor current can be estimated in [Equation 11](#).

$$I_{IND(peak)} = I_{OCL} + I_{IND(ripple)} \quad (11)$$

Using Equation 9 the recommended inductance for the example is 0.329  $\mu\text{H}$ . An inductor supplied by Pulse Electronics (PA0513.441NLT) is selected with an inductance of 0.440  $\mu\text{H}$  at 0 A and 0.363  $\mu\text{H}$  at its 30 A rated current. The saturation current is 35 A and the DCR is 0.32 m $\Omega$ . Using Equation 10 with the selected inductance and maximum input voltage, the current ripple is estimated to be 6.23 A. Equation 11 calculates the peak current to be 31.3 A, well below the saturation current of the inductor. The output current threshold when the supply operates in DCM or CCM can also be estimated as half the estimated current ripple. With the maximum 14 V input in this design the output current threshold is 3.12 A. With lower input voltages, ripple decreases and so does the threshold.

### 8.2.2.4 Output Capacitors (C10, C11, C12, C13, C14)

Determine the output capacitance to meet the load transient, ripple requirements, and to meet small-signal stability as shown in Equation 12.

$$5 \times f_{C2} \leq \frac{R_{C1} \times C_{C1} \times 0.6 \times (0.67 + D)}{2\pi \times G \times L \times C_{OUT} \times V_{OUT}} \leq \frac{f_{SW}}{3}$$

where

- $G = 0.25$
- $R_{C1} \times C_{C1}$  time constant can be referred to Table 1
- $D$  is the duty cycle

Based on Equation 12, the value of  $C_{OUT}$  to ensure small signal stability can be calculated using Equation 13 and Equation 14. These equations assume MLCC are used and the ESR effects are negligible. If a high ESR output capacitor is used, the effects may reduce the minimum and maximum capacitance. In the design example using Table 1 for 425-kHz switching frequency, the time constant is 62  $\mu\text{s}$ . The recommended minimum capacitance for a design with an 8-V minimum input voltage is 260  $\mu\text{F}$ . The recommended maximum capacitance for design with a 14-V maximum input voltage is 4842  $\mu\text{F}$ .

$$C_{OUT} \leq \frac{R_{C1} \times C_{C1} \times 0.6 \times \left( 0.67 + \frac{V_{OUT}}{V_{IN(max)}} \right)}{2\pi \times G \times L \times 5 \times f_{C2} \times V_{OUT}} \tag{13}$$

$$C_{OUT} \geq \frac{R_{C1} \times C_{C1} \times 0.6 \times \left( 0.67 + \frac{V_{OUT}}{V_{IN(min)}} \right)}{2\pi \times G \times L \times \frac{f_{SW}}{3} \times V_{OUT}} \tag{14}$$

Select a larger output capacitance to decrease the output voltage change that occurs during a load transient and the output voltage ripple.

The minimum output capacitance to meet an output voltage ripple requirement can be calculated with Equation 15. In the example the minimum output capacitance for 12 mV<sub>PP</sub> ripple is 162  $\mu\text{F}$ . If non ceramic capacitors are used Equation 16 calculates the maximum equivalent series resistance (ESR) of the output capacitor to meet the ripple requirement. Equation 17 calculates the required RMS current rating for the output capacitor. In this example with 12-V nominal input voltage it is 1.77 A. Finally the output capacitor must be rated for the output voltage.

$$C_{OUT} \geq \frac{I_{IND(ripple)}}{8 \times V_{RIPPLE} \times f_{SW}} \tag{15}$$

$$ESR \leq \frac{V_{RIPPLE} - \left( \frac{I_{IND(ripple)}}{8 \times C_{OUT} \times f_{SW}} \right)}{I_{IND(ripple)}} \tag{16}$$

$$I_{COUT(RMS)} = \frac{I_{IND(ripple)}}{\sqrt{12}} \tag{17}$$

This example uses five 1210, 100- $\mu$ F, 6.3-V, X5R ceramic capacitors with 2 m $\Omega$  of ESR. From the data sheet the estimated DC derating of 95% and AC derating of 70% for a total of 66.5% at room temperature. The total output capacitance is approximately 332.5  $\mu$ F.

### 8.2.2.5 Input Capacitors (C1, C2, C3, C4, C5)

Choose an input capacitance that reduces the input voltage ripple. Equation 18 calculates the minimum input capacitance. In the example design to limit the input ripple to 240 mV, assuming all ceramic and ignoring ESR ripple, the minimum input capacitance is 27.8  $\mu$ F. The input capacitor must also be rated for the input RMS current calculated in Equation 19. For this design example this current is 8.95 A with the minimum 8-V input voltage. Also, the input capacitors must be rated for the maximum input voltage.

$$C_{IN} \geq \frac{\Delta L}{8 \times V_{INRIPPLE} \times f_{SW}} \quad (18)$$

$$I_{CIN(RMS)} = I_{OUT} \times \sqrt{\frac{V_{OUT}}{V_{IN(min)}} \times \frac{(V_{IN(min)} - V_{OUT})}{V_{IN(min)}}} \quad (19)$$

This example uses four 1206, 22  $\mu$ F, 16 V, X5R ceramic capacitors with 3 m $\Omega$  of ESR. An additional 0.1- $\mu$ F capacitor is placed close to the drain of the high-side MOSFET and the source of the low-side MOSFET.

### 8.2.2.6 MOSFET (Q1, Q2)

The TPS53819A uses two external N-channel MOSFETs. The  $V_{DS}$  rating should be greater than the maximum input voltage and include some tolerance for ringing on the switching node. It must also be rated for the DC current. The high-side MOSFET conducts the input current and the low-side MOSFET conducts the output current. The gate drive voltage is set by the VREG voltage of 5 V typical. The gate capacitance should be reduced to minimize the current required to turn on the MOSFETs and switching losses. However it is recommended the low-side MOSFET have a higher gate capacitance to avoid unintentional shoot-through caused by the high dv/dt on the switching node during the high-side turn-on. A reduction in current also reduces power dissipation in TPS53819A. Choose a low  $R_{DS(on)}$  to reduce conduction losses especially for the low-side MOSFET because it conducts the output current.

This design uses the CSD87350Q5D, 30-V, 40-A, NexFET power block with integrated low-side and high-side MOSFETs. This is optimized for applications with a 5 V gate drive. The typical gate to source capacitance of the high-side and low-side MOSFETs is 1341 pF and 2900 pF respectively. Using Equation 1 and Equation 2 the average drive currents are 2.7 mA and 5.9 mA. With Equation 3 the power dissipated in the driver is estimated to 42.4 mW. The  $R_{DS(on)}$  of the high-side and low-side MOSFETs with a 5 V gate drive voltage is 5 m $\Omega$  and 2.2 m $\Omega$  respectively.

A small, 4.7- $\Omega$  resistance from R6, is added in series between DRVH and the gate of the high-side MOSFET. This slows down the turn-on time of the high-side MOSFET dv/dt and reduces rising edge ringing on the switching node to help prevent shoot-through. This value should be kept small and if it is too large it may lead to too large of a delay time in the turn-on time of the high-side switch.

### 8.2.2.7 VREG Bypass Capacitor (C18)

A ceramic capacitor with a recommended value between 0.47- $\mu$ F and 2.2- $\mu$ F is required on the VREG pin for proper operation. The example uses a 1- $\mu$ F capacitor. Choose one rated for the VREG 5.5-V maximum voltage in order to supply the instantaneous drive current of the low-side MOSFET.

### 8.2.2.8 VDD Bypass Capacitor (C19)

A 1- $\mu$ F capacitor should be placed at the VDD pin rated for the maximum input voltage. If power stage switching noise is causing faults, a small resistor (R12) can be added between VDD and all the input capacitors (C1-C5). This creates an R-C filter and reduces any switching noise in the device input.

### 8.2.2.9 VBST Capacitor (C7)

The bootstrap capacitor is required to generate the high-side gate drive bias voltage and provide the instantaneous drive current for DRVH. A 0.1- $\mu$ F ceramic capacitor is recommended to limit the ripple voltage.

R5 (0- $\Omega$ ) resistance, is added in series with the bootstrap capacitor. This resistor can be used to slow down the turn-on time of the high-side MOSFET dv/dt and reduces rising edge ringing on the SW node to help prevent shoot-through. Keep the value small because a higher value may increase the the turn-on delay time of the high-side switch.

### 8.2.2.10 Snubber (C8 and R9)

Fast-switching edges and parasitic inductance and capacitance cause voltage ringing on the SW node . If the ringing results in excessive voltage on the SW node or erratic operation an R-C snubber can be used to reduce ringing on the SW node and ensure proper operation in all operating conditions.

### 8.2.2.11 Feedback Resistance, $R_{FBH}$ and $R_{FBL}$ (R17 and R18)

The values of the voltage-divider resistors,  $R_{FBH}$  and  $R_{FBL}$  determine the output voltage as shown in [Figure 38](#).  $R_{FBH}$  is connected between the FB pin and the output, and  $R_{FBL}$  is connected between the FB pin and GND. The recommended  $R_{FBH}$  value is between 10 k $\Omega$  and 20 k $\Omega$ . Determine  $R_{FBL}$  using [Equation 20](#).

$$R_{FBL} = \frac{R_{FBH}}{\left[ \frac{V_{OUT} - \frac{1}{2} \times \left( I_{IND(ripple)} \times \left( ESR + \frac{1}{8 \times C_{OUT} \times f_{SW}} \right) \right)}{0.6 - \left( \frac{1}{2} \times \left( I_{IND(ripple)} \times \frac{L}{4 \times R_{C1} \times C_{C1}} \right) - V_{OFS} \right)} \right] - 1}$$

where

- $V_{OFS}$  is the internal offset voltage (4 mV)
- ESR is the from the output capacitors

In this example R17 has a value of 10-k $\Omega$ . R18 is calculated to be 9.91 k $\Omega$ . The nearest standard value of 10 k $\Omega$  is used for R18.

### 8.2.2.12 Overcurrent Limit (OCL) Setting Resistance (R10)

Combining [Equation 7](#) and [Equation 8](#), [Equation 21](#) calculates  $R_{TRIP}$ .

$$R_{TRIP} = \frac{8 \times \left( I_{OCL} - \left( \frac{(V_{IN} - V_{OUT})}{(2 \times L_X)} \right) \times \frac{V_{OUT}}{(f_{SW} \times V_{IN})} \right) \times R_{DS(on)}}{I_{TRIP}}$$

In this example for a 25-A current limit,  $R_{TRIP}$  is calculated as 38.5 k $\Omega$  and is rounded up to the nearest standard value of 39.2 k $\Omega$ .

### 8.2.2.13 PMBus Device Address (R3 and R4)

The PMBus address is selected using a resistive divider as shown in [Table 2](#). In this example the address is set to 0010000 with a 300-k $\Omega$  resistor (R3) and a 1.00-k $\Omega$  (R4).

### 8.2.2.14 PGOOD Pullup Resistor (R2)

A pullup resistor is required because the PGOOD pin is an open-drain output. Use a value between 10 k $\Omega$  to 100 k $\Omega$ . The recommended max 100 k $\Omega$  resistor is used.

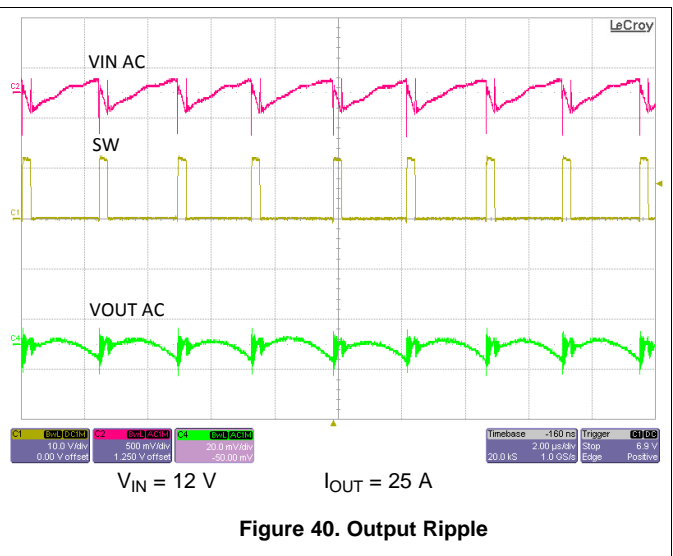
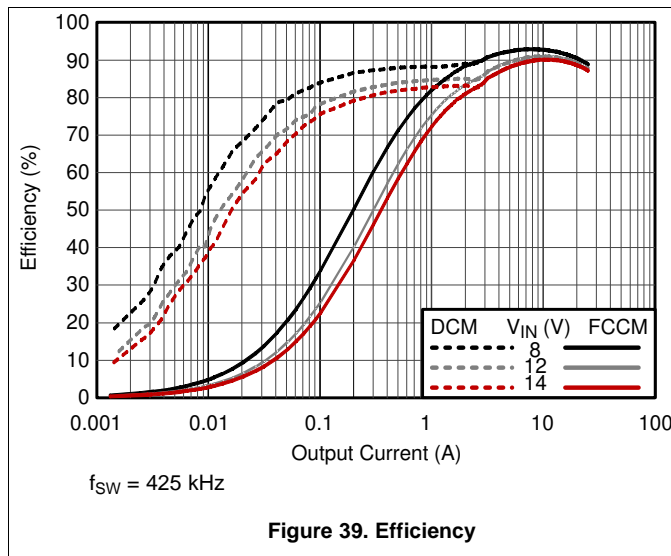
### 8.2.2.15 SCL and SDA Pulldown Resistors (R14 and R15)

If there is no PMBus (I<sup>2</sup>C) needed in the system, pull these two pins down to ground. If a PMBus interface is always present, then these resistors are not needed. This example design uses 100-kΩ of resistance to pull these pins down to ground, allowing it to operate with or without a PMBus interface.

### 8.2.2.16 PMBus Pullup Resistors

Due to the limited drive strength of pulldown MOSFETs on SDA and  $\overline{\text{ALERT}}$  pins, the external PMBus pullup resistors must be kept within certain ranges. For example, if the external PMBus supply is 3.3 V, then use a pullup resistance of 1-kΩ. If the external PMBus supply is 5 V, then use a pullup resistance of 1.5 kΩ.

## 8.2.3 Application Curves



## 9 Power Supply Recommendations

The TPS53819A device operates using an input voltage supply range between 3 V and 28 V (4.5-V to 28-V biased). This input supply must be well regulated. Proper bypassing of input supplies and internal regulators is also critical for noise performance, as is PCB layout and grounding scheme.



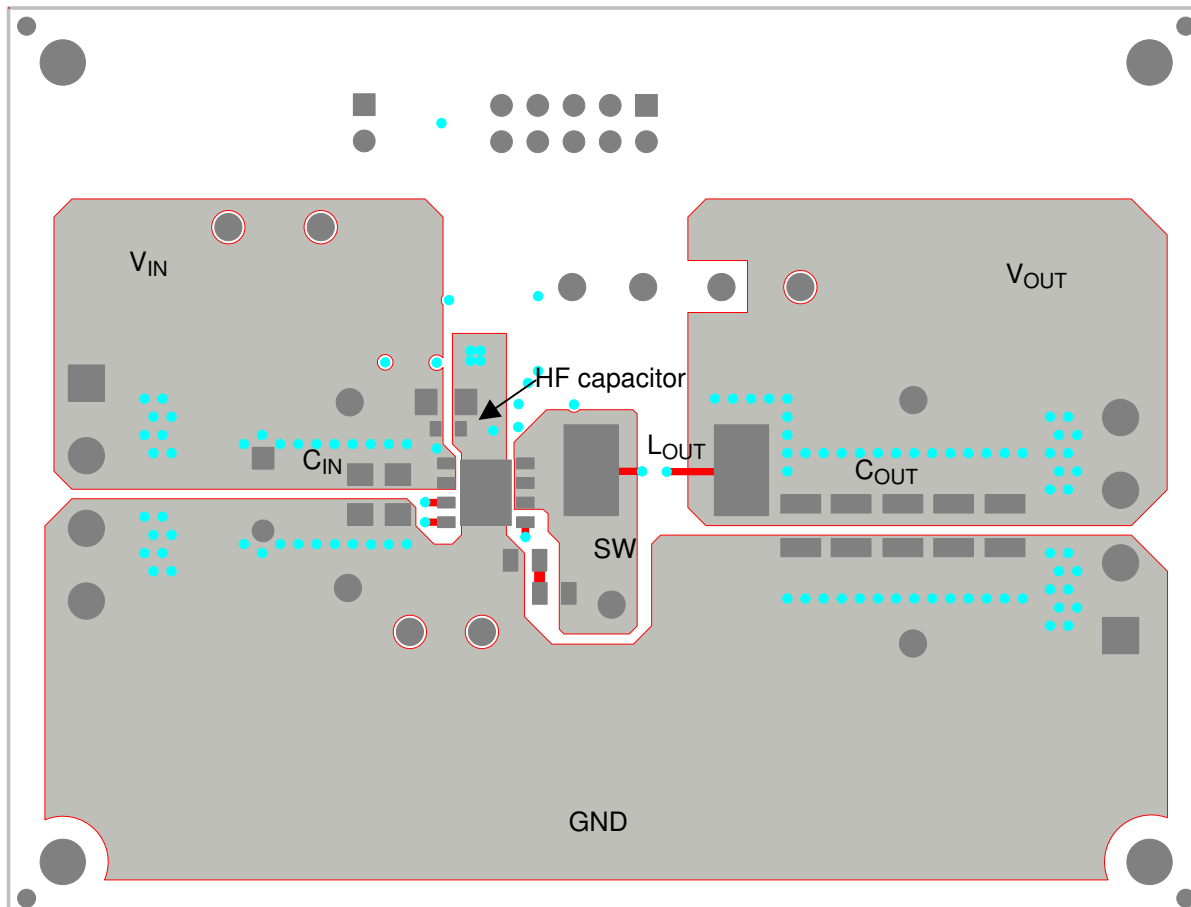
## 10 Layout

### 10.1 Layout Guidelines

Note these design considerations before starting a layout work using TPS53819A

- Inductor,  $V_{IN}$  capacitors,  $V_{OUT}$  capacitors and MOSFETs are the power components and should be placed on one side of the PCB (solder side). Other small signal components can be placed on another side (component side). At least one inner plane should be inserted, connected to ground, in order to shield and isolate the small signal traces from noisy power lines.
- Place all sensitive analog traces and components such as FB, VO, TRIP, PGOOD, and EN away from high-voltage switching nodes such as SW, DRV\_L, DRV\_H or VBST to avoid coupling. Use internal layers as ground planes and shield feedback trace from power traces and components.
- Keep PMBus interfacing signals away from the sensitive analog traces.
- The DC/DC converter has several high-current loops. Minimize the area of these loops in order to suppress switching noise.
  - The path from the  $V_{IN}$  capacitors through the high and low-side MOSFETs and back to the capacitors through ground, is the most important loop area to minimize. Connect the negative node of the  $V_{IN}$  capacitors and the source of the low-side MOSFET at ground as close as possible.
  - The second important loop is the path from the low-side MOSFET through inductor and  $V_{OUT}$  capacitors, and back to source of the low-side MOSFET through ground. Connect source of the low-side MOSFET and negative node of  $V_{OUT}$  capacitors at ground as close as possible.
  - The third important loop is that of the gate driving system for the low-side MOSFET. To turn on the low-side MOSFET, high current flows from the VDRV capacitor through the gate driver and the low-side MOSFET, and back to negative node of the capacitor through ground. To turn off the low-side MOSFET, high current flows from gate of the low-side MOSFET through the gate driver and PGND of the device, and back to source of the low-side MOSFET through ground. Connect the negative node of the VREG capacitor, source of the low-side MOSFET and PGND of the device at ground as close as possible.
- A separate AGND from the high-current loop PGND should be used for the return of the sensitive analog circuitry. The two grounds should connect at a single point as close to the GND pin as possible.
- Minimize the current loop from the VDD and VREG pins through their respective capacitors to the GND pin.
- Because the TPS53819A controls the output voltage referring to voltage across  $V_{OUT}$  capacitor, the top-side resistor of the voltage divider should be connected to the positive node of the  $V_{OUT}$  capacitor. In a same manner both bottom side resistor and GND of the device should be connected to the negative node of  $V_{OUT}$  capacitor. The trace from these resistors to the VFB pin should be short and thin. Place on the component side and avoid vias between these resistors and the device.
- Connect the overcurrent setting resistor from the TRIP pin to ground and make the connections as close as possible to the device. Avoid coupling a high-voltage switching node to the trace from the TRIP pin to  $R_{TRIP}$  and from  $R_{TRIP}$  to ground .
- Connections from gate drivers to the respective gate of the high-side or the low-side MOSFET should be as short as possible to reduce stray inductance. Use 0.65 mm (25 mils) or wider trace and vias of at least 0.5 mm (20 mils) diameter along this trace.
- The PCB trace defined as switch node, which connects to source of high-side MOSFET, drain of low-side MOSFET and high-voltage side of the inductor, should be as short and wide as possible.
- Follow any layout considerations for the MOSFET provided by the MOSFET manufacturer.

## 10.2 Layout Example



**Figure 41. Top Layer**

### Layout Example (continued)

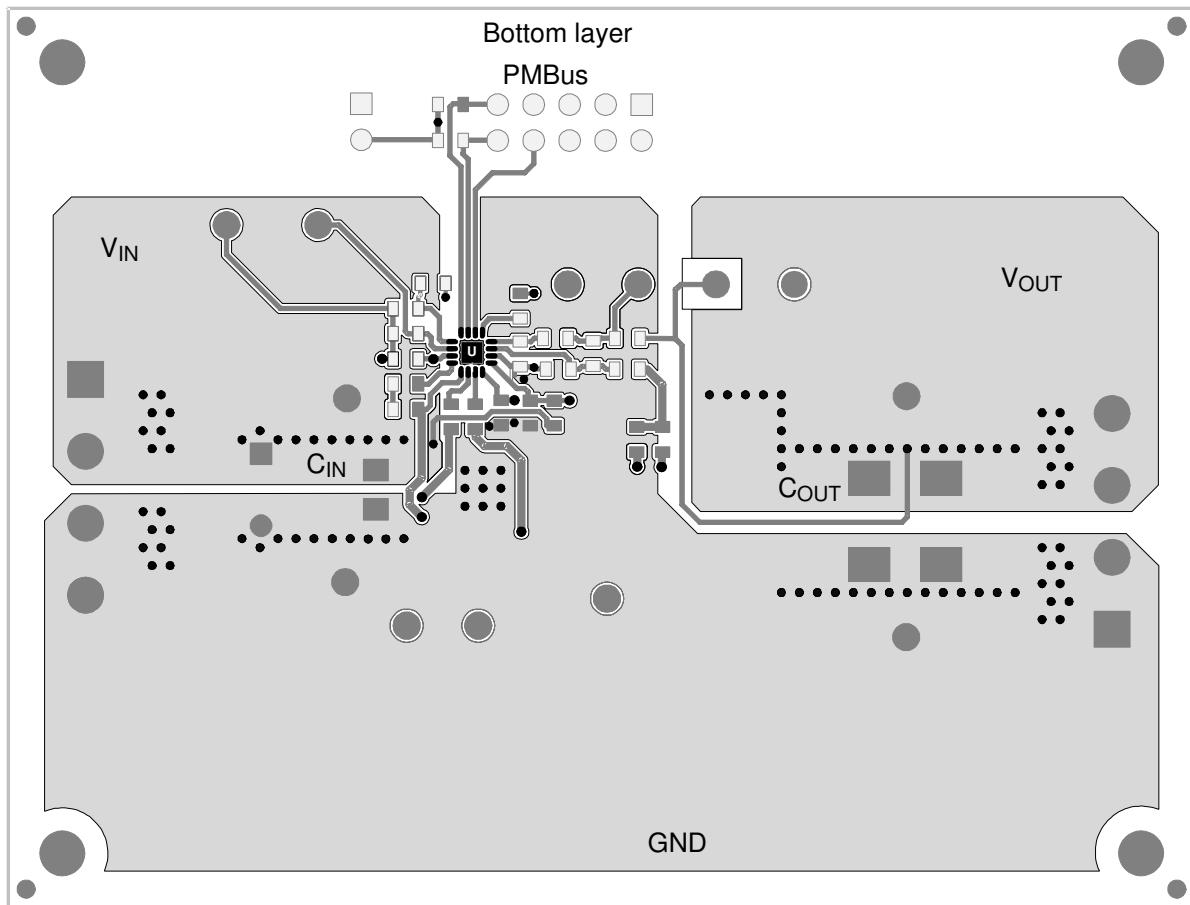


Figure 42. Bottom Layer

## 11 デバイスおよびドキュメントのサポート

### 11.1 デバイス・サポート

#### 11.1.1 開発サポート

##### 11.1.1.1 WEBENCH®ツールによるカスタム設計

ここをクリックすると、WEBENCH® Power Designer により、TPS53819A デバイスを使用するカスタム設計を作成できます。

1. 最初に、入力電圧( $V_{IN}$ )、出力電圧( $V_{OUT}$ )、出力電流( $I_{OUT}$ )の要件を入力します。
2. オプティマイザのダイヤルを使用して、効率、占有面積、コストなどの主要なパラメータについて設計を最適化します。
3. 生成された設計を、テキサス・インスツルメンツが提供する他の方式と比較します。

WEBENCH Power Designerでは、カスタマイズされた回路図と部品リストを、リアルタイムの価格と部品の在庫情報と併せて参照できます。

通常、次の操作を実行可能です。

- 電氣的なシミュレーションを実行し、重要な波形と回路の性能を確認する。
- 熱シミュレーションを実行し、基板の熱特性を把握する。
- カスタマイズされた回路図やレイアウトを、一般的なCADフォーマットで出力する。
- 設計のレポートをPDFで印刷し、設計を共有する。

WEBENCHツールの詳細は、[www.ti.com/WEBENCH](http://www.ti.com/WEBENCH)でご覧になれます。

### 11.2 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、[ti.com](http://ti.com)のデバイス製品フォルダを開いてください。右上の「アラートを受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

### 11.3 コミュニティ・リソース

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

**TI E2E™ Online Community** *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At [e2e.ti.com](http://e2e.ti.com), you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

### 11.4 商標

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 WEBENCH is a registered trademark of Texas Instruments.  
 PMBus is a trademark of SMIF, Inc.  
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### 11.6 Glossary

**SLYZ022** — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 12 メカニカル、パッケージ、および注文情報

以降のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。この情報は、そのデバイスについて利用可能な最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もあります。本データシートのブラウザ版を使用されている場合は、画面左側の説明をご覧ください。

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">TPS53819ARGTR</a>	Active	Production	VQFN (RGT)   16	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	3819A
TPS53819ARGTR.B	Active	Production	VQFN (RGT)   16	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	3819A
<a href="#">TPS53819ARGTT</a>	Active	Production	VQFN (RGT)   16	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	3819A
TPS53819ARGTT.B	Active	Production	VQFN (RGT)   16	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	3819A

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS53819ARGTR	VQFN	RGT	16	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
TPS53819ARGTT	VQFN	RGT	16	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS53819ARGTR	VQFN	RGT	16	3000	346.0	346.0	33.0
TPS53819ARGTT	VQFN	RGT	16	250	210.0	185.0	35.0

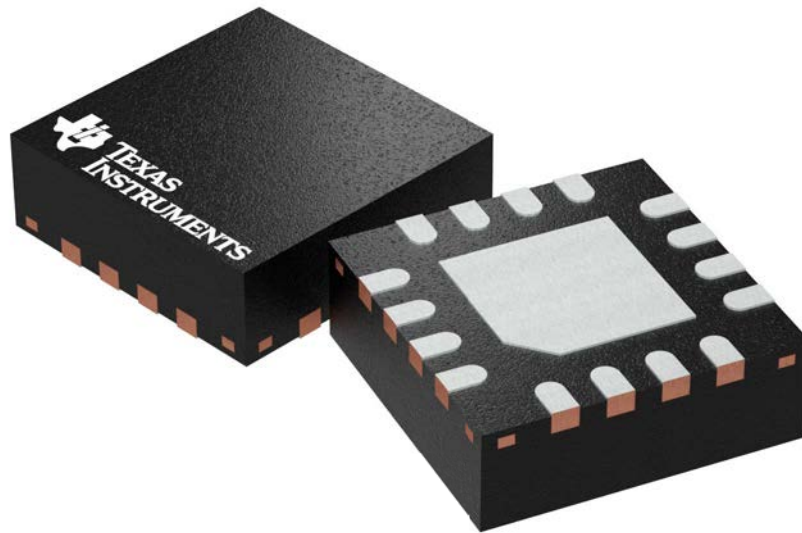


**RGT 16**

**GENERIC PACKAGE VIEW**

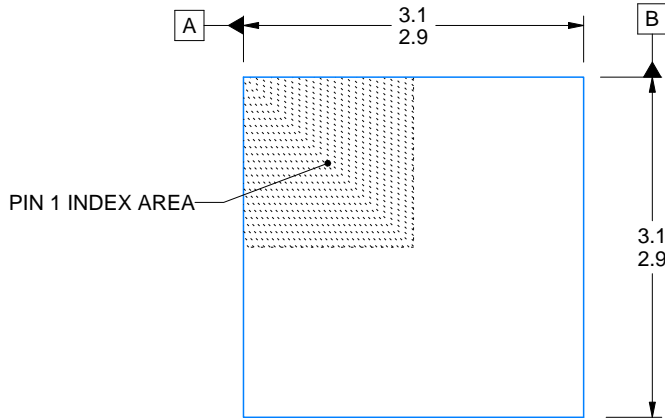
**VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD

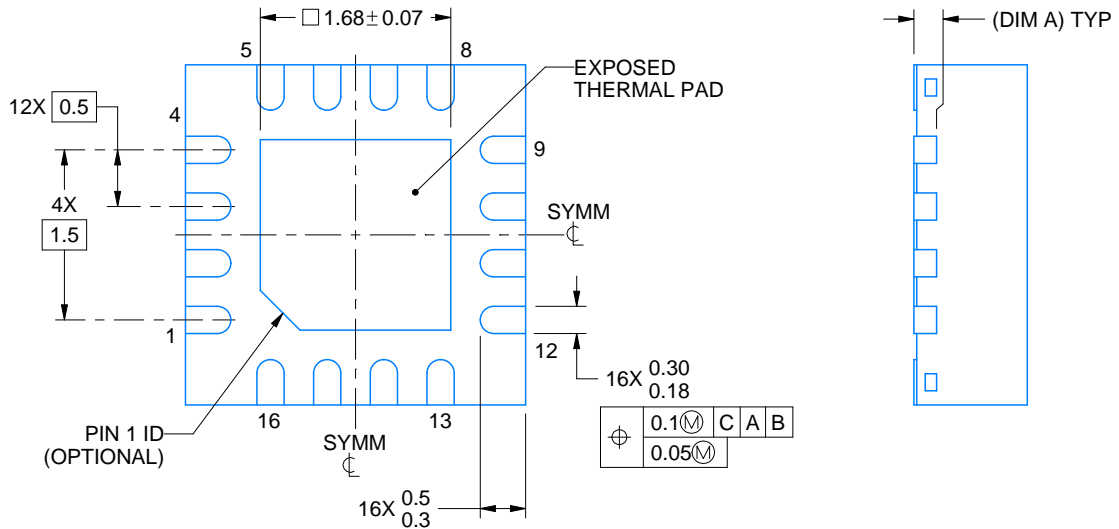


Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

4203495/1



SIDE WALL METAL THICKNESS DIM A	
OPTION 1	OPTION 2
0.1	0.2



4222419/D 04/2022

NOTES:

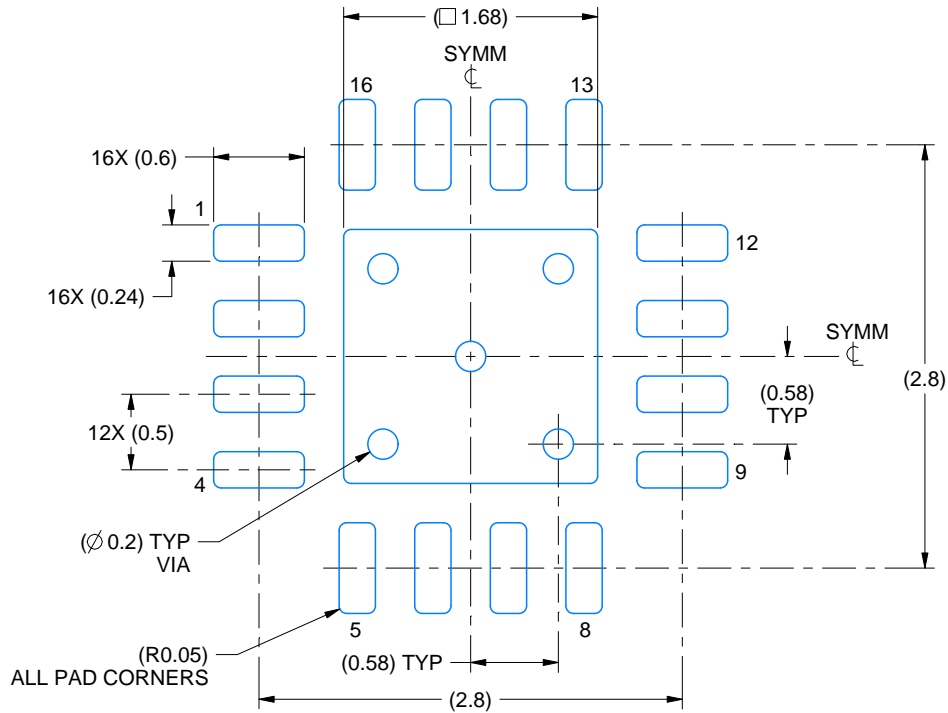
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

# EXAMPLE BOARD LAYOUT

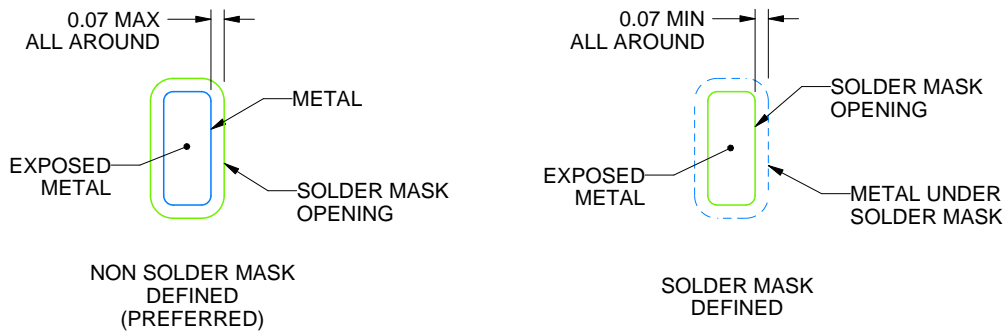
RGT0016C

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:20X



SOLDER MASK DETAILS

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NOTES: (continued)

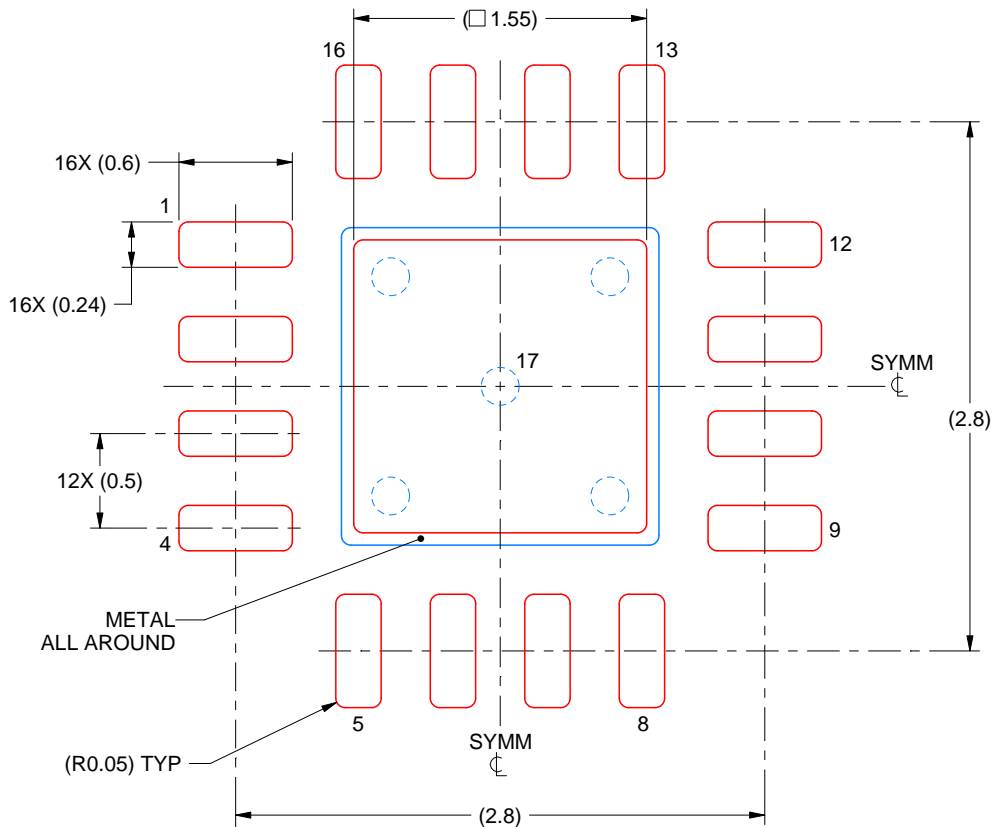
- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/sluea271](http://www.ti.com/lit/sluea271)).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

# EXAMPLE STENCIL DESIGN

RGT0016C

VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



**SOLDER PASTE EXAMPLE**  
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 17:  
85% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE  
SCALE:25X

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NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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