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SLAS592C-MARCH 2008-REVISED NOVEMBER 2008

# 24 V, EIGHT-CHANNEL DIGITAL-INPUT SERIALIZER

### **FEATURES**

- Eight Sensor Inputs
  - High Input Voltage up to 30 V
  - Selectable Debounce Filters From 0 ms to 3 ms
  - Adjustable Current Limits From 0.2 mA to 5.2 mA
  - Field Inputs and Supply Lines Protected to 15-kV HBM
- Output Drivers for External Status LEDs
- Cascadable for More Inputs in Multiples of Eight

- SPI-Compatible Interface
- Regulated 5-V Output for External Digital Isolator
- Over-Temperature and Low-Supply Voltage Indicator

### **APPLICATIONS**

- Sensor Inputs for Industrial Automation and Process Control
  - IEC61131-2 Type 1, 2, or 3 Switches
  - EN60947-5-2 Proximity Switches
- High Channel Count Digital Input Modules for PC and PLC Systems
- Decentralized I/O Modules

#### DESCRIPTION

The SN65HVS880 is a 24-V, eight-channel, digital-input serializer for high-channel density digital input modules of PC and PLC based systems in industrial automation. In combination with galvanic isolators the device completes the interface between the 24-V sensor outputs of the field-side and the low-voltage controller inputs at the control-side. Input signals provided by EN60947-5-2 compliant 2- and 3-wire proximity switches are current-limited and then validated by internal debounce filters. The input switching characteristic is in accordance with IEC61131-2 for Type 1, 2, and 3 sensor switches.

Upon the application of load and clock signals, input data is latched in parallel into the shift register and afterwards clocked out serially via a subsequent isolator into a serial PLC input.

Cascading of multiple SN65HVS880 is possible by connecting the serial output of the leading device with the serial input of the following device, enabling the design of high-channel count input modules. Input status is indicated via 3-mA constant current LED outputs. An external precision resistor is required to set the internal reference current. The integrated voltage regulator provides a 5-V output to supply low-power isolators. An on-chip temperature sensor together with an internal supply voltage monitor provides a chip-okay (CHOK) indication.

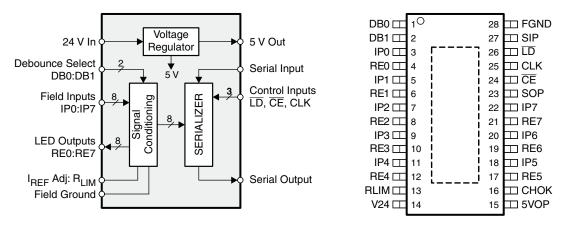
The SN65HVS880 comes in a 28-pin PWP PowerPAD™ package allowing for efficient heat dissipation. The device is specified for operation at temperatures from –40°C to 85°C.

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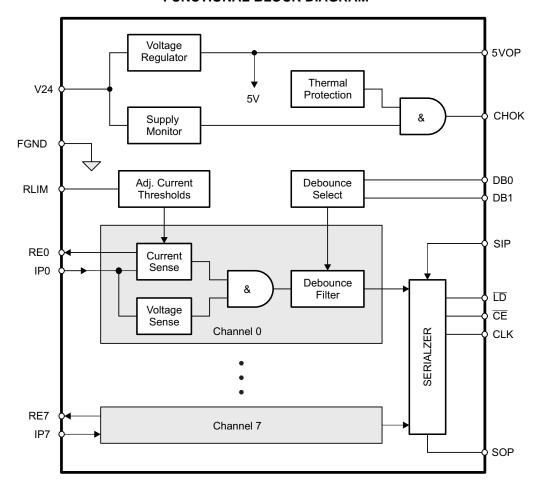
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### **FUNCTIONAL BLOCK DIAGRAM**





## **TERMINAL FUNCTIONS**

TERM	INAL	DESCRIPTION
PIN NO.	NAME	DESCRIPTION
1, 2	DB0, DB1	Debounce select inputs
3, 5, 7, 9, 11, 18, 20, 22	IPx	Input channel x
4, 6, 8, 10, 12, 17, 19, 21	REx	Return path x (LED drive)
13	RLIM	Current limiting resistor
14	V24	24 VDC field supply
15	5VOP	5 V output to supply low-power isolators
16	CHOK	Chip okay indicator output
23	SOP	Serial data output
24	CE	Clock enable input
25	CLK	Serial clock input
26	LD	Load pulse input
27	SIP	Serial data input
28	FGND	Field ground



### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted)

				MIN	MAX	UNIT
V24	Field power input		V24	-0.3	35	V
$V_{IPx}$	Field digital inputs		IPx	-0.3	35	V
$V_{ID}$	Voltage at any logic input		DB0, DB1, CLK, SIP, $\overline{\text{CE}}$ , $\overline{\text{LD}}$	-0.5	6	V
Io	Output current		CHOK, SOP		±8	mA
		Human-Body Model <sup>(1)</sup>	All pins		±4 kV	
.,		numan-body Model	IPx,V24		±15	ΚV
V <sub>ESD</sub>	Electrostatic discharge	Charged-Device Model (2)	All pins		±1	kV
		Machine Model <sup>(3)</sup>	All pins		±100	V
P <sub>TOT</sub>	Continuous total power dissipation		See Thermal Characteristics table	Э		
TJ	Junction temperature				170	°C

<sup>(1)</sup> JEDEC Standard 22, Method A114-A.

## THERMAL CHARACTERISTICS

	PARAMETER	PARAMETER TEST CONDITIONS				UNIT
$\theta_{JA}$	Junction-to-air thermal resistance	High-K thermal resistance		35		°C/W
$\theta_{JB}$	Junction-to-board thermal resistance			15		°C/W
$\theta_{\text{JC}}$	Junction-to-case thermal resistance			4.27		°C/W
PD	Device power dissipation	$\begin{split} I_{LOAD} = 50 \text{ mA, } R_{IN} = 0, IPO-IP7 = V24 = 30 \text{ V,} \\ RE7 = FGND, f_{CLK} = 100 \text{ MHz,} \\ I_{IP\text{-}LIM} \text{ and } I_{CC} = \text{worst case with } R_{LIM} = 25 \text{ k}\Omega \end{split}$			2591	mW

## RECOMMENDED OPERATING CONDITIONS

		MIN	TYP	MAX	UNIT
V <sub>24</sub>	Field supply voltage	18	24	30	V
V <sub>IPL</sub>	Field input low-state input voltage <sup>(1)</sup>	0		6	V
$V_{IPH}$	Field input high-state input voltage (1)	10		30	V
V <sub>IL</sub>	Logic low-state input voltage	0		0.8	V
$V_{IH}$	Logic high-state input voltage	2		5.5	V
R <sub>LIM</sub>	Current limiter resistor	17	25	500	kΩ
$f_{IP}$	Input data rate <sup>(2)</sup>	0		1	Mbps
$T_J$				150	°C
T <sub>A</sub>		-40		85	°C

<sup>(2)</sup> JEDEC Standard 22, Method C101

JEDEC Standard 22, Method A115-A

<sup>(1)</sup> Field input voltages correspond to an input resistor of  $R_{IN}$  = 1.2 k $\Omega$  (2) Maximum data rate corresponds to 0 ms debounce time, (DB0 = open, DB1 = FGND), and  $R_{IN}$  = 0  $\Omega$ 



## **ELECTRICAL CHARACTERISTICS**

all voltages measured against FGND unless otherwise stated, see Figure 12

SYMBOL	PARAMETER	TERMINAL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>TH-(IP)</sub>	Low-level device input threshold voltage			4	4.3		V
V <sub>TH+(IP)</sub>	High-level device input threshold voltage	IP0-IP7	18 V < V24 < 30 V, $R_{IN} = 0 \Omega$		5.2	5.5	V
V <sub>HYS(IP)</sub>	Device input hysteresis		11(N = 0 12		0.9		V
V <sub>TH-(IN)</sub>	Low-level field input threshold voltage		18 V < V24 < 30 V,	6	8.4		V
V <sub>TH+(IN)</sub>	High-level field input threshold voltage	measured at field side of R <sub>IN</sub>	$R_{IN} = 1.2 \text{ k}\Omega \pm 5\%$		9.4	10	V
V <sub>HYS(IN)</sub>	Field input hysteresis	I licia diac di T(IN	$R_{LIM} = 25 \text{ k}\Omega$		1		V
V <sub>TH-(V24)</sub>	Low-level V24-monitor threshold voltage			15	16.05		V
V <sub>TH+(V24)</sub>	High-level V24-monitor threshold voltage	V24			16.8	18	V
V <sub>HYS(V24)</sub>	V24-monitor hysteresis				0.75		V
R <sub>IP</sub>	Input resistance	IP0-IP7	$3 \text{ V} < \text{V}_{\text{IPx}} < 6 \text{ V},$ $R_{\text{IN}} = 1.2 \text{ k}\Omega \pm 5\%,$ $R_{\text{LIM}} = 25 \text{ k}\Omega$	1.4	1.83	2.3	kΩ
I <sub>IP-LIM</sub>	Input current limit		$10 \text{ V} < \text{V}_{\text{IPx}} < 30 \text{ V},$ $\text{R}_{\text{LIM}} = 25 \text{ k}Ω$	3.15	3.6	4	mA
V <sub>OL</sub>	Logic low-level output voltage	COD CHOK	I <sub>OL</sub> = 20 μA			0.4	V
V <sub>OH</sub>	Logic high-level output voltage	SOP, CHOK	I <sub>OH</sub> = -20 μA	4			V
I <sub>IL</sub>	Logic input leakage current	DB0, DB1, SIP, LD, CE, CLK		-50		50	μΑ
I <sub>RE-on</sub>	RE on-state current	RE0-RE7	$R_{LIM} = 25 \text{ k}\Omega,$ $RE_X = FGND$	2.8	3.15	3.5	mA
I <sub>CC(V24)</sub>	Supply current	V24	IP0 to IP7 = V24, 5VOP = open, RE <sub>X</sub> = FGND, All logic inputs open			8.7	mA
V <sub>O(5V)</sub>	Linear regulator output voltage		18 V < V24 < 30 V, no load	4.5	5	5.5	V
VO(5V)	Linear regulator output voltage	5VOP	18 V < V24 < 30 V, I <sub>L</sub> = 50 mA	4.5	5	5.5	V
I <sub>LIM(5V)</sub>	Linear regulator output current limit				115		mA
$\Delta V_5/\Delta V_{24}$	Line regulation	5VOP, V24	18 V < V24 < 30 V, I <sub>L</sub> = 5 mA			2	mV/V
			DB0 = open, DB1 = FGND		0		
t <sub>DB</sub>	Debounce times of input channels	IP0-IP7	DB0 = FGND, DB1 = open		1		ms
			DB0 = DB1 = open		3		
t <sub>DB-HL</sub>	Voltage monitor debounce time after V24 < 15 V (CHOK turns low)	V24 CHOY			1		ms
t <sub>DB-LH</sub>	Voltage monitor debounce time after V24 > 18 V (CHOK turns high)	V24, CHOK			6		ms
T <sub>OVER</sub>	Over-temperature indication				150		°C
T <sub>SHDN</sub>	Shutdown temperature				170		°C



## **TIMING REQUIREMENTS**

over operating free-air temperature range (unless otherwise noted)

SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT	
t <sub>W1</sub>	CLK pulse width	See Figure 6	4			ns
t <sub>W2</sub>	LD pulse width	See Figure 4	6			ns
t <sub>SU1</sub>	SIP to CLK setup time	See Figure 7	4			ns
t <sub>H1</sub>	SIP to CLK hold time	See Figure 7	2			ns
t <sub>SU2</sub>	Falling edge to rising edge (CE to CLK) setup time	See Figure 8	4			ns
t <sub>REC</sub>	LD to CLK recovery time	See Figure 5	2			ns
f <sub>CLK</sub>	Clock pulse frequency	See Figure 6	DC		100	MHz

## **SWITCHING CHARACTERISTICS**

over operating free-air temperature range (unless otherwise noted)

SYMBOL	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>PLH1</sub> , t <sub>PHL1</sub>	CLK to SOP	C <sub>L</sub> = 15 pF, see Figure 6			10	ns
t <sub>PLH2</sub> , t <sub>PHL2</sub>	LD to SOP	C <sub>L</sub> = 15 pF, see Figure 4			14	ns
t <sub>r</sub> , t <sub>f</sub>	Rise and fall times	C <sub>L</sub> = 15 pF, see Figure 6			5	ns



### INPUT CHARACTERISTICS

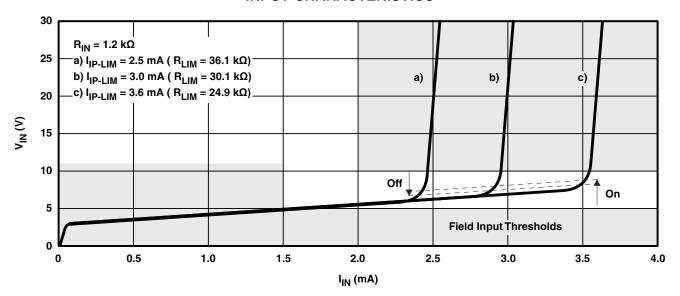


Figure 1. Typical Input Characteristics

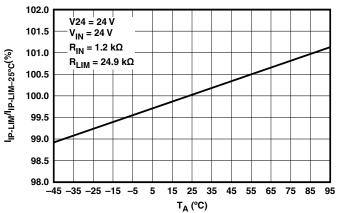


Figure 2. Typical Current Limiter Variation vs Ambient Temperature

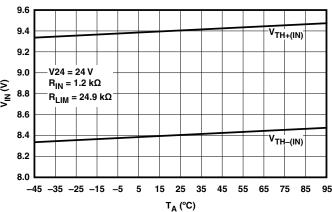


Figure 3. Typical Limiter Threshold Voltage Variation vs Ambient Temperature



## PARAMETER MEASUREMENT INFORMATION

## Waveforms

For the complete serial interface timing, refer to Figure 21.

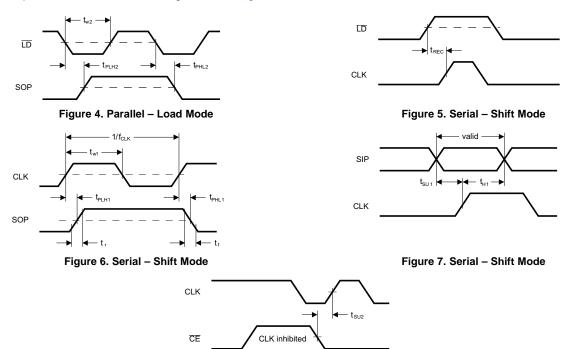
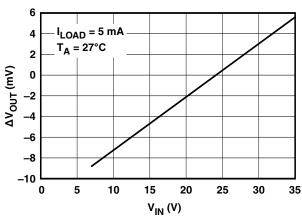


Figure 8. Serial - Shift Clock Inhibit Mode



## **VOLTAGE REGULATOR PERFORMANCE CHARACTERISTICS**



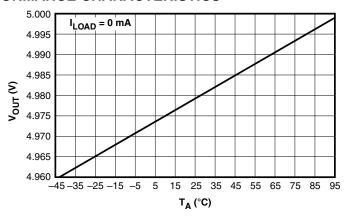


Figure 9. Line Regulation

Figure 10. Output Voltage vs Ambient Temperature

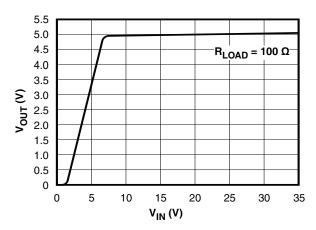


Figure 11. Output Voltage vs Input Voltage

## **SIGNAL CONVENTIONS**

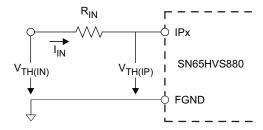


Figure 12. On/Off Threshold Voltage Measurements

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#### **DEVICE INFORMATION**

### **Digital Inputs**

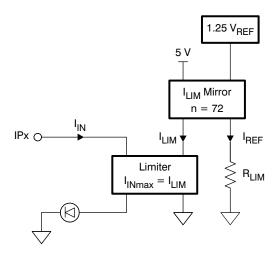


Figure 13. Digital Input Stage

Each digital input operates as a controlled current sink limiting the input current to a maximum value of  $I_{LIM}$ . The current limit is derived from the reference current via  $I_{LIM} = n \times I_{REF}$ , and  $I_{REF}$  is determined by  $I_{REF} = V_{REF}/R_{LIM}$ . Thus, changing the current limit requires the change of  $R_{LIM}$  to a different value via:  $R_{LIM} = n \times V_{REF}/I_{LIM}$ .

Inserting the actual values for n and  $V_{REF}$  gives:  $R_{LIM} = 90 \text{ V} / I_{LIM}$ .

While the device is specified for a current limit of **3.6 mA**, (via  $R_{LIM} = 25 \text{ k}\Omega$ ), it is easy to lower the current limit to further reduce the power consumption. For example, for a current limit of **2.5 mA** simply calculate:

$$R_{LIM} = \frac{90 \text{ V}}{I_{LIM}} = \frac{90 \text{ V}}{2.5 \text{ mA}} = 36 \text{ k}\Omega$$

### **Debounce Filter**

The HVS880 applies a simple analog/digital filtering technique to remove unintended signal transitions due to contact bounce or other mechanical effects. Any new input (either low or high) must be present for the duration of the selected debounce time to be latched into the shift register as a valid state.

The logic signal levels at the control inputs, DB0 and DB1 of the internal Debounce-Select logic determine the different debounce times listed in the following truth table.

**Table 1. Debounce Times** 

DB1	DB0	FUNCTION
Open	Open	3 ms delay
Open	FGND	1 ms delay
FGND	Open	0 ms delay (Filter bypassed)
FGND	FGND	Reserved



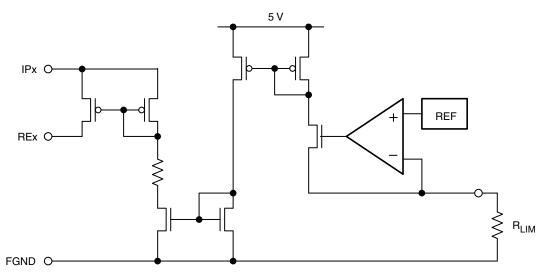


Figure 14. Equivalent Input Diagram

## **Shift Register**

The conversion from parallel input to serial output data is performed by an eight-channel, parallel-in serial-out shift register. Parallel-in access is provided by the internal inputs, PIP0–PIP7, that are enabled by a low level at the load input (LD). When clocked, the latched input data shift towards the serial output (SOP). The shift register also provides a clock-enable function.

Clocking is accomplished by a low-to-high transition of the clock (CLK) input while  $\overline{LD}$  is held high and the clock enable (CE) input is held low. Parallel loading is inhibited when  $\overline{LD}$  is held high. The parallel inputs to the register are enabled while  $\overline{LD}$  is low independently of the levels of the CLK,  $\overline{CE}$ , or serial (SIP) inputs.

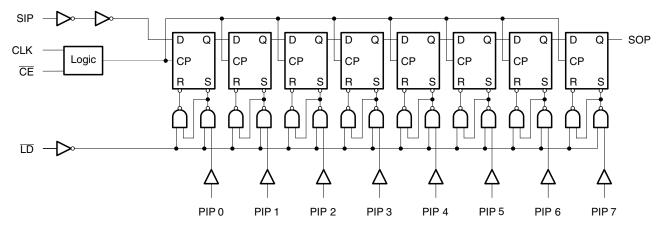


Figure 15. Shift Register Logic Structure



**Table 2. Function Table** 

	INPUTS		FUNCTION			
LD	CLK	CE	FUNCTION			
L	Х	Х	Parallel load			
Н	Х	Н	No change			
Н	1	L	Shift <sup>(1)</sup>			

Shift = content of each internal register shifts towards serial outputs.
 Data at SIP is shifted into first register.

### **Voltage Regulator**

The on-chip linear voltage regulator provides a 5 V supply to the internal- and external circuitry, such as digital isolators, with an output drive capability of 50 mA and a typical current limit of 115 mA. The regulator accepts input voltages from 30 V down to 10 V. Because the regulator output is intended to supply external digital isolator circuits proper output voltage decoupling is required. For best results connect a 1  $\mu$ F and a 0.1  $\mu$ F ceramic capacitor as close as possible to the 5VOP-output. For longer traces between the SN65HVS880 and isolators of the ISO72xx family use additional 0.1  $\mu$ F and 10 pF capacitors next to the isolator supply pins. Make sure, however, that the total load capacitance does not exceed 4.7  $\mu$ F.

For good stability the voltage regulator requires a minimum load current,  $I_{L-MIN}$ . Ensure that under any operating condition the ratio of the minimum load current in mA to the total load capacitance in  $\mu F$  is larger than 1:

$$\frac{I_{L-MIN}}{C_I} > \frac{1 \text{ mA}}{1 \text{ }\mu\text{F}}$$

### **Supply Voltage Monitor**

The integrated supply voltage monitor senses the supply voltage of the SN65HVS880 at the V24-pin. If this voltage drops below 15 V but stays within the regulator's operating range, i.e., 15 V > V24 > 10 V, the output CHOK goes low 1 ms later. When the supply voltage returns to 24 V, the CHOK output turns logic high after 6 ms. Should the supply voltage drop below 10 V, the device ceases operation. Upon the supply returning to above 18 V, the CHOK output turns high again after 6 ms.

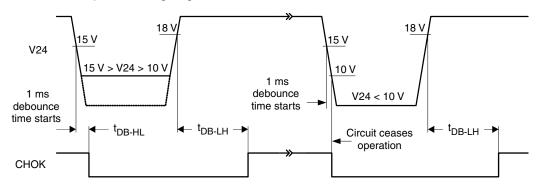


Figure 16. CHOK Output Timing as a Function of Supply Voltage Drop at V24

### **Temperature Sensor**

An on-chip temperature sensor monitors the device temperature and signals a fault condition if the device becomes too hot. A first trip point exists at 150°C. If the junction temperature exceeds this trip point, the sensor output, being active low, presents a low to the input of the AND gate forcing the CHOK output to go low. If the junction temperature continues to rise, passing a second trip point at 170°C, all device outputs assume tri-state.



## Chip Okay (CHOK) Output

The CHOK output is the Boolean AND-function of the two, active-low fault conditions: temperature failure and supply failure. As such CHOK is a device health indicator, assuming logic high in the absence of any fault condition. If either one of the two or both fault conditions occur, CHOK becomes logic low.

A special condition occurs, however, when the chip temperature exceeds the second temperature trip point due to an output short. Then the CHOK output buffer becomes tri-state, thus separating the buffer from the external circuitry. An internal 100  $k\Omega$  pulldown resistor, connecting the CHOK-pin to ground, is used as a "cooling down" resistor, which continues to provide a logic low level to the external circuitry.



#### APPLICATION INFORMATION

### System-Level EMC

The SN65HVS880 must operate reliably in harsh industrial environments. At a system level, the device is tested according to several international electromagnetic compatibility (EMC) standards.

In addition to the device internal ESD structures, external protection circuitry, such as the one in Figure 17, is needed to absorb as much energy from burst- and surge-transients as possible.

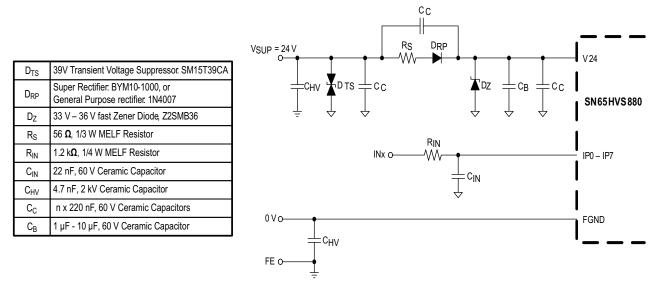


Figure 17. Typical EMC Protection Circuitry for Supply and Signal Inputs

## **Input Channel Switching Characteristics**

The input stage of the HVS880 is so designed, that for an input resistor  $R_{IN} = 1.2 \text{ k}\Omega$  the trip point for signalling an ON-condition is at 9.4 V at 3.6 mA. This trip point satisfies the switching requirements of IEC61131-2 Type 1 and Type 3 switches.

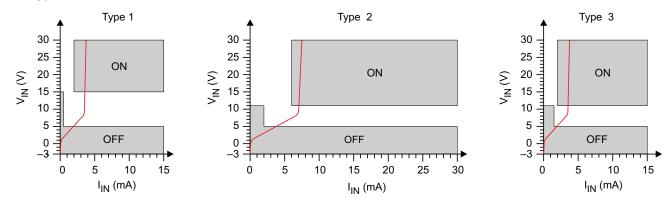


Figure 18. Switching Characteristics for IEC61131-2 Type 1, 2, and 3 Proximity Switches

For a Type 2 switch application, two inputs are connected in parallel. The current limiters then add to a total maximum current of 7.2 mA. While the return-path (RE-pin), of one input might be used to drive an indicator LED, the RE-pin of the other input channel should be connected to ground (FGND).

Paralleling input channels reduces the number of available input channels from an octal Type 1 or Type 3 input to a quad Type 2 input device. Note, that in this configuration output data of an input channel is represented by two shift register bits.



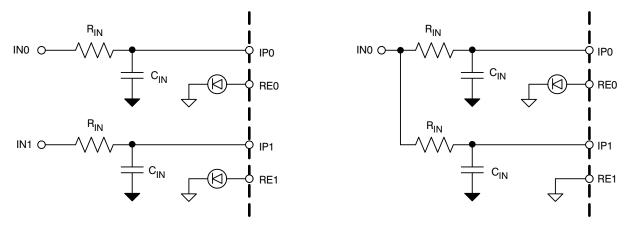


Figure 19. Paralleling Two Type 1 or Type 3 Inputs Into One Type 2 Input

### **Digital Interface Timing**

The digital interface of the SN65HVS880 is SPI compatible and interfaces, isolated or non-isolated, to a wide variety of standard micro controllers.

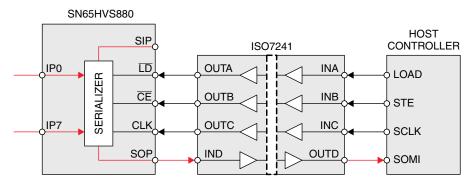


Figure 20. Simple Isolation of the Shift Register Interface

Upon a low-level at the load input,  $\overline{\text{LD}}$ , the information of the field inputs, IP0 to IP7 is latched into the shift register. Taking /LD high again blocks the parallel inputs of the shift register from the field inputs. A low-level at the clock-enable input,  $\overline{\text{CE}}$ , enables the clock signal, CLK, to serially shift the data to the serial output, SOP. Data is clocked at the rising edge of CLK. Thus after eight consecutive clock cycles all field input data have been clocked out of the shift register and the information of the serial input, SIP, appears at the serial output, SOP.



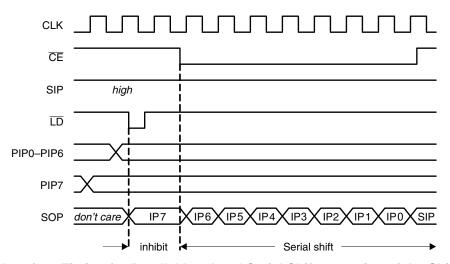


Figure 21. Interface Timing for Parallel-Load and Serial-Shift Operation of the Shift Register

## **Cascading for High Channel Count Input Modules**

Designing high-channel count modules require cascading multiple SN65HVS880 devices. Simply connect the serial output (SOP) of a leading device with the serial input (SIP) of a following device without changing the processor interface.

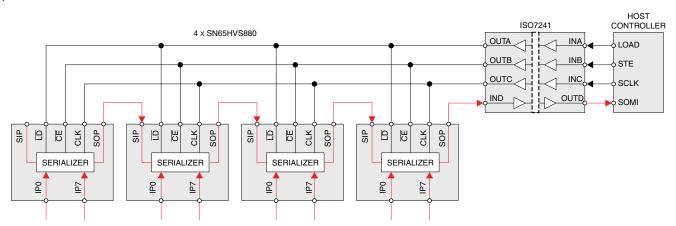


Figure 22. Cascading Four SN65HVS880 for a 32-Channel Input Module



## **Typical Digital Input Module Application**

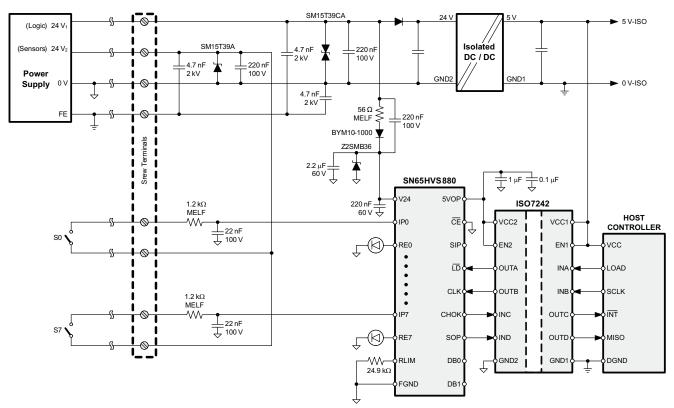


Figure 23. Typical Digital Input Module Application

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### PACKAGING INFORMATION

Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/	MSL rating/	Op temp (°C)	Part marking
	(1)	(2)			(3)	Ball material	Peak reflow		(6)
						(4)	(5)		
SN65HVS880PWPR	Active	Production	HTSSOP (PWP)   28	2000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	HVS880
SN65HVS880PWPR.A	Active	Production	HTSSOP (PWP)   28	2000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	HVS880
SN65HVS880PWPRG4	Active	Production	HTSSOP (PWP)   28	2000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	HVS880
SN65HVS880PWPRG4.A	Active	Production	HTSSOP (PWP)   28	2000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	HVS880

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

# **PACKAGE MATERIALS INFORMATION**

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## TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing	l .	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
SN65HVS880PWPR	HTSSOP	PWP	28	2000	330.0	16.4	6.9	10.2	1.8	12.0	16.0	Q1
SN65HVS880PWPRG4	HTSSOP	PWP	28	2000	330.0	16.4	6.9	10.2	1.8	12.0	16.0	Q1

**PACKAGE MATERIALS INFORMATION** 

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## \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
SN65HVS880PWPR	HTSSOP	PWP	28	2000	350.0	350.0	43.0
SN65HVS880PWPRG4	HTSSOP	PWP	28	2000	350.0	350.0	43.0

4.4 x 9.7, 0.65 mm pitch

SMALL OUTLINE PACKAGE

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



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