

SN65HVD3x、3.3V、全二重 RS-485 ドライバとレシーバ

1 特長

- 1/8 ユニット負荷オプション使用可能
(バス上に最大 256 個のノード)
- 15kV HBM を超えるバス・ピンの ESD 保護
- 1Mbps、5Mbps、26Mbps の信号速度に対応する、オプションのドライバ出力遷移時間
 - ラインの信号レートとは、1 秒あたりの電圧遷移回数を bps (ビット/秒) 単位で表したものです
- 低電流のスタンバイ・モード: 1 μ A 未満
- 電源オンおよび電源オフ時のグリッチ・フリー保護によりホットプラグ・アプリケーションに対応
- 5V 許容の入力
- バス・アイドル、開路、短絡のフェイルセーフ
- ドライバ電流制限および過熱保護
- RS-422 および RS-485 ネットワーク用に設計されています
- 5V デバイスが利用可能、SN65HVD50-55

2 アプリケーション

- ユーティリティ・メーター
- DTE および DCE インターフェイス
- 産業用、プロセス、およびビル・オートメーション
- 販売時点情報管理 (POS) ピンとネットワーク

3 概要

SN65HVD3x デバイスは、3.3V 電源で動作する 3 ステート差動ライン・ドライバおよび差動入力ライン・レシーバです。

各ドライバおよびレシーバは、全二重バス通信設計用に、独立した入力および出力ピンを備えています。これらの製品は、最大 1500m のケーブル長で RS-422 と RS-485 のデータ転送を行うように設計されています。

SN65HVD30、SN65HVD31、SN65HVD32 デバイスは、外部イネーブル・ピンなしで完全にイネーブルになります。

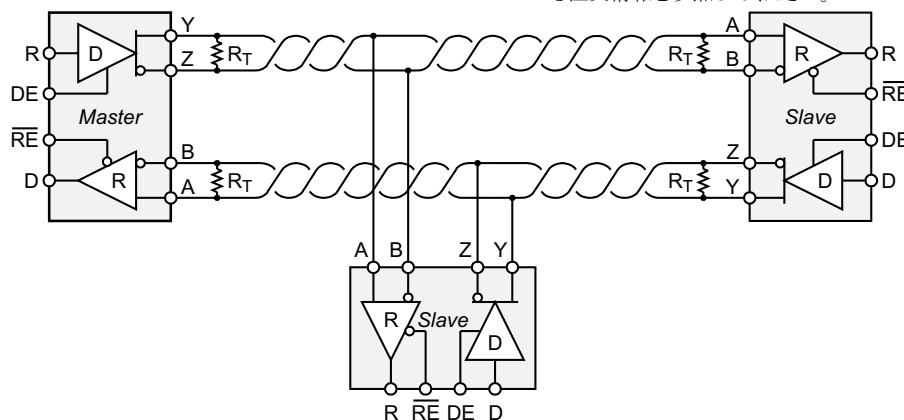
SN65HVD33、SN65HVD34、SN65HVD35 デバイスは、アクティブ HIGH のドライバ・イネーブルと、アクティブ LOW のレシーバ・イネーブルを備えています。ドライバとレシーバの両方をディセーブルにすると、1 μ A 未満の低いスタンバイ電流が得られます。

すべてのデバイスは、-40°C~85°C の周囲温度で動作が規定されています。消費電力が低いため、パッケージ・オプションに応じて、105°C または 125°C までの温度で動作できます。

パッケージ情報

部品番号	パッケージ (1)	本体サイズ (公称)
SN65HVD30	SOIC (8)	4.90mm × 3.91mm
SN65HVD31		
SN65HVD32		
SN65HVD33	SOIC (14)	8.65mm × 3.91mm
	VQFN (20)	4.50mm × 3.50mm
SN65HVD34	SOIC (14)	8.65mm × 3.91mm
SN65HVD35		

(1) 利用可能なパッケージについては、このデータシートの末尾にある注文情報を参照してください。



Copyright © 2017, Texas Instruments Incorporated

代表的なアプリケーション回路図



英語版の TI 製品についての情報を翻訳したこの資料は、製品の概要を確認する目的で便宜的に提供しているものです。該当する正式な英語版の最新情報は、www.ti.com で閲覧でき、その内容が常に優先されます。TI では翻訳の正確性および妥当性につきましては一切保証いたしません。実際の設計などの前には、必ず最新版の英語版をご参照くださいますようお願いいたします。

English Data Sheet: [SLLS665](#)

Table of Contents

1 特長	1	Parameter Measurement Information	16
2 アプリケーション	1	8 Detailed Description	20
3 概要	1	8.1 Overview.....	20
4 Revision History	2	8.2 Functional Block Diagram.....	20
5 Device Comparison	4	8.3 Feature Description.....	20
6 Pin Configuration and Functions	4	8.4 Device Functional Modes.....	24
7 Specifications	7	9 Application and Implementation	26
7.1 Absolute Maximum Ratings.....	7	9.1 Application Information.....	26
7.2 ESD Ratings.....	7	9.2 Typical Application.....	26
7.3 Recommended Operating Conditions.....	8	9.3 Power Supply Recommendations.....	30
7.4 Thermal Information.....	8	9.4 Layout.....	30
7.5 Electrical Characteristics: Driver.....	9	10 Device and Documentation Support	31
7.6 Electrical Characteristics: Receiver.....	10	10.1 ドキュメントの更新通知を受け取る方法.....	31
7.7 Device Power Dissipation – P_D	10	10.2 サポート・リソース.....	31
7.8 Supply Current Characteristics.....	11	10.3 Trademarks.....	31
7.9 Switching Characteristics: Driver.....	11	10.4 静電気放電に関する注意事項.....	31
7.10 Switching Characteristics: Receiver.....	12	10.5 用語集.....	31
7.11 Dissipation Ratings.....	13	11 Mechanical, Packaging, and Orderable Information	31
7.12 Typical Characteristics.....	13		

4 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from Revision L (January 2017) to Revision M (February 2023) Page

- Changed the D package values the *Thermal Information* **8**

Changes from Revision K (October 2015) to Revision L (January 2017) Page

- Changed text From: "defaults to Y high and Z low" To: "defaults to Y low and Z high" in the *Low-Power Standby Mode* section..... **20**

Changes from Revision J (July 2015) to Revision K (October 2015) Page

- 「デバイス情報」の表にあるデバイス・リストを、「パッケージ・オプションの付録」のリストと一致するよう変更。 **1**
- Changed device listing in the *Pinout Configuration* section to match the *Package Option Addendum* listing..... **4**
- Changed device listing in the *Thermal Information* table to match the *Package Option Addendum* listing..... **8**

Changes from Revision I (April 2010) to Revision J (July 2015) Page

- 「ピン構成および機能」セクション、「ESD 定格」表、「機能説明」セクション、「デバイスの機能モード」セクション、「アプリケーションと実装」セクション、「電源に関する推奨事項」セクション、「レイアウト」セクション、「デバイスおよびドキュメントのサポート」セクション、「メカニカル、パッケージ、および注文情報」セクションを追加..... **1**

Changes from Revision H (May 2009) to Revision I (April 2010) Page

- 「概要」の 3 番目の文の表現を変更..... **1**
- Changed the labels in the *SN65HVD3x Drivers Operate Correctly After Bus Contention Faults* image..... **22**

Changes from Revision G (December 2008) to Revision H (May 2009) Page

- Added explanatory notes for pin 6 and pin 13 to the 14-Pin SOIC..... **4**
- Added explanatory notes for pin 1 and pin 10 to the 20-Pin VQFN..... **4**

• Added Supply current typical value of 3.8 mA for SN65HVD31, SN65HVD3 in the <i>Supply Current Characteristics</i> table.....	11
• Changed characteristic graph for 図 7-6	13
• Changed characteristic graph for 図 7-7	13
• Added subsection <i>Safe Operation With Bus Contention</i>	22

Changes from Revision F (July 2008) to Revision G (December 2008)	Page
• 次のように変更:「特長」で「5V デバイスが利用可能、SN65HVD50-59」から「5V デバイスが利用可能、SN65HVD50-55」へ。	1
• 「概要」から SN65HVD36 および SN65HVD37 を削除.....	1
• 「概要」から SN65HVD38 および SN65HVD39 を削除.....	1
• 「概要」の最後の 2 つの段落を削除.....	1
• Deleted SN65HVD36, SN65HVD37 from the 8-Pin SOIC.....	4
• Deleted SN65HVD36, SN65HVD37 from the the 14-Pin SOIC.....	4
• Deleted devices SN65HVD36, SN65HVD38 from the <i>Recommended Operating Conditions</i>	8
• Deleted devices SN65HVD37, SN65HVD39 from the <i>Recommended Operating Conditions</i>	8
• Deleted all HVD36, HVD38, HVD37, HVD39 from the <i>Electrical Characteristics: Driver</i> table.....	9
• Added added last sentence to note 4 in the <i>Electrical Characteristics: Driver</i> table.....	9
• Deleted all HVD36, HVD38, HVD37, HVD39 from the <i>Electrical Characteristics: Receiver</i> table.....	10
• Deleted all HVD36, HVD38, HVD37, HVD39 rows from the <i>Supply Current Characteristics</i> table.....	11
• Deleted all HVD36, HVD38, HVD37, HVD39 from the <i>Switching Characteristics: Driver</i> table.....	11
• Deleted HVD36, HVD38, HVD37, and HVD39 from the <i>Switching Characteristics: Receiver</i> table.....	11
• Deleted <i>Receiver Equalization Characteristics</i> table.....	13
• Added subsection <i>Driver Output Current Limiting</i>	21
• Added subsection <i>Hot-Plugging</i>	21
• Added subsection <i>Receiver Failsafe</i>	22
• Deleted SN65HVD38 and SN65HVD39 from 表 8-1 title.....	24
• Deleted SN65HVD38 and SN65HVD39 from 表 8-2 title.....	24
• Deleted SN65HVD36 and SN65HVD37 from 表 8-3 title.....	24
• Deleted SN65HVD36 and SN65HVD37 from 表 8-4 title.....	24
• Deleted SN65HVD36 and SN65HVD37 from first row of 表 8-5	24
• Deleted SN65HVD37, SN65HVD38 and SN65HVD39 from second row of 表 8-5	24

Changes from Revision E (March 2008) to Revision F (July 2008)	Page
• 次のように変更:「特長」で「ANSI TIA/EIA-485-A と RS-422 互換の要件を満たす、または超える性能」から「RS-422 および RS-485 ネットワーク用に設計」へ。	1
• Added Table Note 4 in the <i>Electrical Characteristics: Driver</i> table.....	9

Changes from Revision D (January 2008) to Revision E (March 2008)	Page
• スペルを「temperatures」から「temperatures」に変更.....	1

5 Device Comparison

表 5-1. Device Features

BASE PART NUMBER	SIGNALING RATE	UNIT LOADS	ENABLES
SN65HVD30	26 Mbps	1/2	No
SN65HVD31	5 Mbps	1/8	No
SN65HVD32	1 Mbps	1/8	No
SN65HVD33	26 Mbps	1/2	Yes
SN65HVD34	5 Mbps	1/8	Yes
SN65HVD35	1 Mbps	1/8	Yes

表 5-2. Improved Replacement for Devices

PART NUMBER	REPLACE WITH	BENEFITS
MAX3491 MAX3490	SN65HVD33 SN65HVD30	Better ESD protection (15 kV versus 2 kV, or not specified) Higher Signaling Rate (26 Mbps versus 10 Mbps) Fractional Unit Load (64 Nodes versus 32)
MAX3491E MAX3490E	SN65HVD33 SN65HVD30	Higher Signaling Rate (26 Mbps versus 12 Mbps) Fractional Unit Load (64 Nodes versus 32)
MAX3076E MAX3077E	SN65HVD33 SN65HVD30	Higher Signaling Rate (26 Mbps versus 16 Mbps) Lower Standby Current (1 μ A versus 10 μ A)
MAX3073E MAX3074E	SN65HVD34 SN65HVD31	Higher Signaling Rate (5 Mbps versus 500 kbps) Lower Standby Current (1 μ A versus 10 μ A)
MAX3070E MAX3071E	SN65HVD35 SN65HVD32	Higher Signaling Rate (1 Mbps versus 250 kbps) Lower Standby Current (1 μ A versus 10 μ A)

6 Pin Configuration and Functions

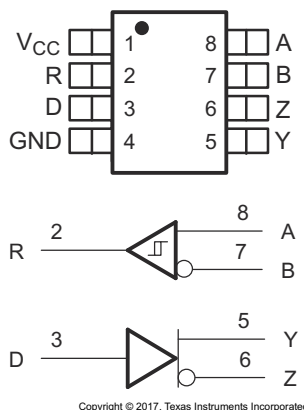
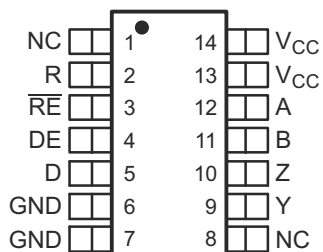
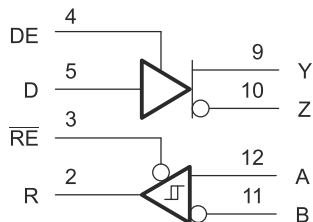


图 6-1. SN65HVD30, SN65HVD31, SN65HVD32, D Package 8-Pin SOIC Top View

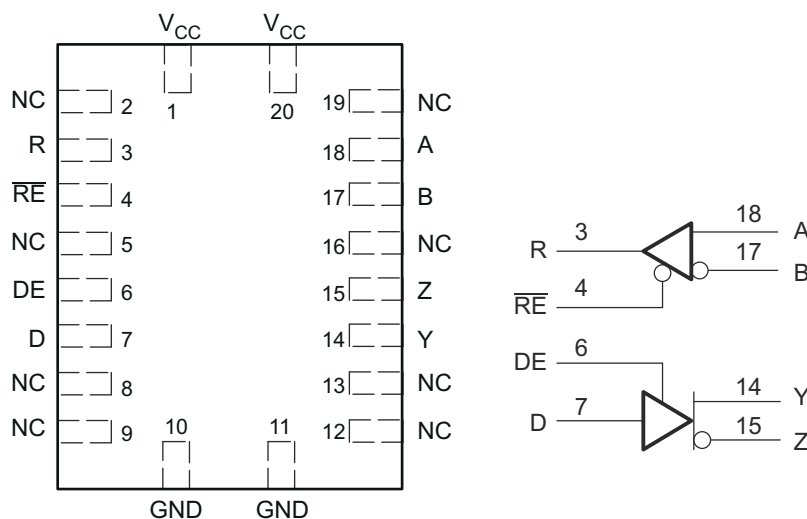


NC - No internal connection
Pins 6 and 7 are connected together internally
Pins 13 and 14 are connected together internally



Copyright © 2017, Texas Instruments Incorporated

图 6-2. SN65HVD33, SN65HVD34, SN65HVD35 D Package 14-Pin SOIC Top View



NC - No internal connection
Pins 10 and 11 are connected together internally
Pins 1 and 20 are connected together internally

Copyright © 2017, Texas Instruments Incorporated

图 6-3. SN65HVD33 RHL Package 20-Pin VQFN Top View

表 6-1. Pin Functions

NAME	PIN			TYPE	DESCRIPTION
	D (8-Pins)	D (14-Pins)	RHL (20-Pins)		
A	8	12	18	Bus input	Receiver input (complementary to B)
B	7	11	17	Bus input	Receiver input (complementary to A)
D	3	5	7	Digital input	Driver data input
DE	—	4	6	Digital input	Driver enable, active high
GND	4	6, 7	10, 11	Reference potential	Local device ground
NC	—	1, 8	2, 5, 8, 9, 12, 13, 16, 19	No connect	No connect; must be left floating
R	2	2	3	Digital output	Receive data output
$\overline{RE}$	—	3	4	Digital output	Receiver enable, active low
V _{CC}	1	13, 14	1, 20	Supply	3-V to 3.6-V supply
Y	5	9	14	Bus output	Driver output (complementary to Z)
Z	6	10	15	Bus output	Driver output (complementary to Y)

7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range unless otherwise noted^{(1) (2)}

		MIN	MAX	UNIT
V_{CC}	Supply voltage	−0.3	6	V
$V_{(A)}, V_{(B)}, V_{(Y)}, V_{(Z)}$	Voltage at any bus terminal (A, B, Y, Z)	−9	14	V
$V_{(TRANS)}$	Voltage input, transient pulse through 100 Ω . See Figure 8-13 (A, B, Y, Z) ⁽³⁾	−50	50	V
V_I	Input voltage (D, DE, $\overline{RE}$)	−0.5	7	V
I_O	Output current (receiver output only, R)		11	mA
T_{stg}	Storage Temperature		125	°C

- (1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under [セクション 7.3](#) is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values, except differential I/O bus voltages, are with respect to network ground terminal.
- (3) This tests survivability only and the output state of the receiver is not specified.

7.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	Bus pins and GND	±16000
			All pins	±4000
		Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾		±1000

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range unless otherwise noted

			MIN	NOM	MAX	UNIT
V _{CC}	Supply voltage		3		3.6	V
V _I or V _{IC}	Voltage at any bus pin (separately or common mode)		–7 ⁽¹⁾		12	V
1/t _{UI}	Signaling rate	SN65HVD30, SN65HVD33			26	Mbps
		SN65HVD31, SN65HVD34			5	
		SN65HVD32, SN65HVD35			1	
R _L	Differential load resistance		54	60		Ω
V _{IH}	High-level input voltage	D, DE, RE	2		V _{CC}	V
V _{IL}	Low-level input voltage	D, DE, RE	0		0.8	V
V _{ID}	Differential input voltage		–12		12	V
I _{OH}	High-level output current	Driver	–60			mA
		Receiver	–8			
I _{OL}	Low-level output current	Driver			60	mA
		Receiver			8	
T _J	Junction temperature		–40		150	°C

(1) The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.

7.4 Thermal Information

THERMAL METRIC ⁽¹⁾		SN65HVD30, SN65HVD31, SN65HVD32	SN65HVD33, SN65HVD34, SN65HVD35	SN65HVD33	UNIT
		D (SOIC)	D (SOIC)	R _{HL} (VQFN)	
		8 PINS	14 PINS	20 PINS	
R _{θJA}	Junction-to-ambient thermal resistance	116.7	93.2	73	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	56.3	47.5	14	°C/W
R _{θJB}	Junction-to-board thermal resistance	63.4	49.4	13.7	°C/W
ψ _{JT}	Junction-to-top characterization parameter	8.8	11.2	0.5	°C/W
ψ _{JB}	Junction-to-board characterization parameter	62.6	48.9	13.7	°C/W
R _{θJC(bot)}	Junction-to-case (bottom) thermal resistance	—	—	2.8	°C/W

(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

7.5 Electrical Characteristics: Driver

over recommended operating conditions unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
$V_{I(K)}$	Input clamp voltage	$I_I = -18 \text{ mA}$	-1.5			V
$ V_{OD(SS)} $	Steady-state differential output voltage	$I_O = 0$	2.5		V_{CC}	V
		$R_L = 54 \Omega$, See § 8-2 (RS-485)	1.5	2		
		$R_L = 100 \Omega$, See § 8-2 , ⁽²⁾ (RS-422)	2	2.3		
		$V_{test} = -7 \text{ V to } 12 \text{ V}$, See § 8-3	1.5			
$\Delta V_{OD(SS)} $	Change in magnitude of steady-state differential output voltage between states	$R_L = 54 \Omega$, See § 8-2 and § 8-3	-0.2		0.2	V
$V_{OD(RING)}$	Differential Output Voltage overshoot and undershoot	$R_L = 54 \Omega$, $C_L = 50 \text{ pF}$, See § 8-6 and § 8-4			10% ⁽³⁾	V
$V_{OC(PP)}$	Peak-to-peak common-mode output voltage	SN65HVD30, SN65HVD33	See § 8-5		0.5	V
		SN65HVD31, SN65HVD34, SN65HVD32, SN65HVD35	See § 8-5		0.25	
$V_{OC(SS)}$	Steady-state common-mode output voltage	See § 8-5	1.6		2.3	V
$\Delta V_{OC(SS)}$	Change in steady-state common-mode output voltage	See § 8-5	-0.05		0.05	V
$I_{Z(Z)}$ or $I_{Y(Z)}$	High-impedance state output current	SN65HVD30, SN65HVD31, SN65HVD32	$V_{CC} = 0 \text{ V}$, V_Z or $V_Y = 12 \text{ V}$, Other input at 0 V		90	μA
			$V_{CC} = 0 \text{ V}$, V_Z or $V_Y = -7 \text{ V}$, Other input at 0 V		-10	
		SN65HVD33, SN65HVD34, SN65HVD35	$V_{CC} = 3 \text{ V or } 0 \text{ V}$, $DE = 0 \text{ V}$, V_Z or $V_Y = 12 \text{ V}$, Other input at 0 V		90	
			$V_{CC} = 3 \text{ V or } 0 \text{ V}$, $DE = 0 \text{ V}$, V_Z or $V_Y = -7 \text{ V}$, Other input at 0 V		-10	
$I_{Z(S)}$ or $I_{Y(S)}$	Short Circuit output current ⁽⁴⁾		V_Z or $V_Y = -7 \text{ V}$, Other input at 0 V		-250	mA
			V_Z or $V_Y = 12 \text{ V}$, Other input at 0 V		250	
I_I	Input current	D, DE	0		100	μA
$C_{(OD)}$	Differential output capacitance	$V_{OD} = 0.4 \sin(4E6\pi t) + 0.5 \text{ V}$, DE at 0 V		16		pF

(1) All typical values are at 25°C and with a 3.3-V supply.

(2) V_{CC} is $3.3 V_{DC} \pm 5\%$.

(3) 10% of the peak-to-peak differential output voltage swing, per TIA/EIA-485.

(4) Under some conditions of short-circuit to negative voltages, output currents exceeding the ANSI TIA/EIA-485-A maximum current of 250 mA may occur. Continuous exposure can affect device reliability. This applies to the SN65HVD30, SN65HVD31, SN65HVD33, and SN65HVD34.

7.6 Electrical Characteristics: Receiver

over recommended operating conditions unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
V_{IT+}	Positive-going differential input threshold voltage	$I_O = -8$ mA			-0.02	V
V_{IT-}	Negative-going differential input threshold voltage	$I_O = 8$ mA	-0.20			V
V_{hys}	Hysteresis voltage ($V_{IT+} - V_{IT-}$)			50		mV
V_{IK}	Enable-input clamp voltage	$I_I = -18$ mA	-1.5			V
V_O	Output voltage	$V_{ID} = 200$ mV, $I_O = -8$ mA, See 8-9	2.4			V
		$V_{ID} = -200$ mV, $I_O = 8$ mA, See 8-9			0.4	
$I_{O(Z)}$	High-impedance-state output current	$V_O = 0$ or V_{CC} , $\overline{RE}$ at V_{CC}	-1		1	μ A
I_A or I_B	Bus input current	SN65HVD31, SN65HVD32, SN65HVD34, SN65HVD35 V_A or $V_B = 12$ V Other input at 0 V		0.05	0.1	mA
		V_A or $V_B = 12$ V, $V_{CC} = 0$ V Other input at 0 V		0.06	0.1	
		V_A or $V_B = -7$ V Other input at 0 V	-0.10	-0.04		
		V_A or $V_B = -7$ V, $V_{CC} = 0$ V Other input at 0 V	-0.10	-0.03		
	SN65HVD30, SN65HVD33	V_A or $V_B = 12$ V Other input at 0 V		0.20	0.35	mA
		V_A or $V_B = 12$ V, $V_{CC} = 0$ V Other input at 0 V		0.24	0.4	
		V_A or $V_B = -7$ V Other input at 0 V	-0.35	-0.18		
		V_A or $V_B = -7$ V, $V_{CC} = 0$ V Other input at 0 V	-0.25	-0.13		
I_{IH}	Input current, $\overline{RE}$	$V_{IH} = 0.8$ V or 2 V	-60			μ A
C_{ID}	Differential input capacitance	$V_{ID} = 0.4 \sin(4E6\pi t) + 0.5$ V, DE at 0 V		15		pF

(1) All typical values are at 25°C and with a 3.3-V supply.

7.7 Device Power Dissipation – P_D

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
P_D	Power Dissipation (worst case) Driver and receiver enabled, 50% duty cycle square-wave signal at signaling rate: SN65HVD30, SN65HVD33 at 25 Mbps, SN65HVD31, SN65HVD34 at 5 Mbps, SN65HVD32, SN65HVD35 at 1 Mbps	SN65HVD30, SN65HVD33 $V_{CC} = 3.6$ V, $T_J = 140^\circ\text{C}$, $R_L = 54 \Omega$, $C_L = 50$ pF (driver), $C_L = 15$ pF (receiver)			197	mW
		SN65HVD31, SN65HVD34 $V_{CC} = 3.6$ V, $T_J = 140^\circ\text{C}$, $R_L = 54 \Omega$, $C_L = 50$ pF (driver), $C_L = 15$ pF (receiver)			213	
		SN65HVD32, SN65HVD35 $V_{CC} = 3.6$ V, $T_J = 140^\circ\text{C}$, $R_L = 54 \Omega$, $C_L = 50$ pF (driver), $C_L = 15$ pF (receiver)			248	
T_{SD}	Thermal Shut-down Junction Temperature			170		$^\circ\text{C}$

7.8 Supply Current Characteristics

over recommended operating conditions unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
I _{CC} Supply current	SN65HVD30	D at 0 V or V _{CC} and No Load			2.1	mA
	SN65HVD31, SN65HVD32			3.8	6.4	
	SN65HVD33	RE at 0 V, D at 0 V or V _{CC} , DE at 0 V, No load (Receiver enabled and driver disabled)			1.8	mA
	SN65HVD34, SN65HVD35				2.2	
	SN65HVD33, SN65HVD34, SN65HVD35	RE at V _{CC} , D at V _{CC} , DE at 0 V, No load (Receiver disabled and driver disabled)		0.022	1	μA
	SN65HVD33	RE at 0 V, D at 0 V or V _{CC} , DE at V _{CC} , No load (Receiver enabled and driver enabled)			2.1	mA
	SN65HVD34, SN65HVD35				6.5	
	SN65HVD33	RE at V _{CC} , D at 0 V or V _{CC} , DE at V _{CC} No load (Receiver disabled and driver enabled)			1.8	mA
	SN65HVD34, SN65HVD35				6.2	

(1) All typical values are at 25°C and with a 3.3-V supply.

7.9 Switching Characteristics: Driver

over recommended operating conditions unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
t _{PLH} Propagation delay time, low-to-high-level output	SN65HVD30, SN65HVD33	R _L = 54 Ω, C _L = 50 pF, See FIG 8-6	4	10	18	ns
	SN65HVD31, SN65HVD34		25	38	65	
	SN65HVD32, SN65HVD35		120	175	305	
t _{PHL} Propagation delay time, high-to-low-level output	SN65HVD30, SN65HVD33		4	9	18	ns
	SN65HVD31, SN65HVD34		25	38	65	
	SN65HVD32, SN65HVD35		120	175	305	
t _r Differential output signal rise time	SN65HVD30, SN65HVD33		2.5	5	12	ns
	SN65HVD31, SN65HVD34		20	37	60	
	SN65HVD32, SN65HVD35		120	185	300	
t _f Differential output signal fall time	SN65HVD30, SN65HVD33		2.5	5	12	ns
	SN65HVD31, SN65HVD34		20	35	60	
	SN65HVD32, SN65HVD35		120	180	300	
t _{sk(p)} Pulse skew (t _{PHL} – t _{PLH})	SN65HVD30, SN65HVD33			0.6		ns
	SN65HVD31, SN65HVD34			2.0		
	SN65HVD32, SN65HVD35			5.1		

7.9 Switching Characteristics: Driver (continued)

over recommended operating conditions unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
t _{PZH1}	Propagation delay time, high-impedance-to-high-level output	SN65HVD33			45	ns
		SN65HVD34			235	
		SN65HVD35			490	
t _{PHZ}	Propagation delay time, high-level-to-high-impedance output	SN65HVD33			25	ns
		SN65HVD34			65	
		SN65HVD35			165	
t _{PZL1}	Propagation delay time, high-impedance-to-low-level output	SN65HVD33			35	ns
		SN65HVD34			190	
		SN65HVD35			490	
t _{PLZ}	Propagation delay time, low-level-to-high-impedance output	SN65HVD33			30	ns
		SN65HVD34			120	
		SN65HVD35			290	
t _{PZH1} , t _{PZL1}	Driver enable delay with bus voltage offset	V _O = 2 V (Typ)		500	900	ns
t _{PZH2}	Propagation delay time, standby-to-high-level output	R _L = 110 Ω, $\overline{RE}$ at 0 V, D = 3 V and S1 = Y, or D = 0 V and S1 = Z See 8-7			4000	ns
t _{PZL2}	Propagation delay time, standby-to-low-level output	R _L = 110 Ω, $\overline{RE}$ at 3 V, D = 3 V and S1 = Z, or D = 0 V and S1 = Y See 8-8			4000	ns

(1) All typical values are at 25°C and with a 3.3-V supply.

7.10 Switching Characteristics: Receiver

over recommended operating conditions unless otherwise noted

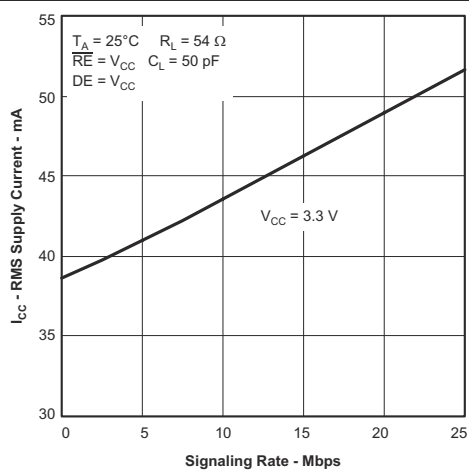
PARAMETER		TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
t _{PLH}	Propagation delay time, low-to-high-level output	SN65HVD30, SN65HVD33		26	45	ns
		SN65HVD31, SN65HVD32, SN65HVD34, SN65HVD35		47	70	ns
t _{PHL}	Propagation delay time, high-to-low-level output	SN65HVD30, SN65HVD33		29	45	ns
		SN65HVD31, SN65HVD32, SN65HVD34, SN65HVD35		49	70	ns
t _{sk(p)}	Pulse skew (t _{PHL} – t _{PLH})	SN65HVD30, SN65HVD33			7	ns
		SN65HVD31, SN65HVD34, SN65HVD32, SN65HVD35			10	ns
t _r	Output signal rise time				5	ns
t _f	Output signal fall time				6	ns
t _{PHZ}	Output disable time from high level	DE at 3 V			20	ns
t _{PZH1}	Output enable time to high level	DE at 0 V			20	ns
t _{PZH2}	Propagation delay time, standby-to-high-level output	DE at 0 V			4000	ns
t _{PLZ}	Output disable time from low level	DE at 3 V			20	ns
t _{PZL1}	Output enable time to low level	DE at 0 V			20	ns
t _{PZL2}	Propagation delay time, standby-to-low-level output	DE at 0 V			4000	ns

(1) All typical values are at 25°C and with a 3.3-V supply.

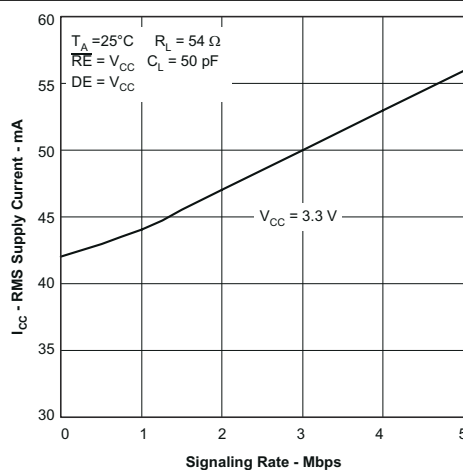
7.11 Dissipation Ratings

PACKAGE	JEDEC THERMAL MODEL	T _A < 25°C RATING	DERATING FACTOR ABOVE T _A = 25°C	T _A = 85°C RATING	T _A = 105°C RATING	T _A = 125°C RATING
8-pin D (SOIC)	Low k	625 mW	5 mW/°C	325 mW		
	High k	1000 mW	8 mW/°C	520 mW	360 mW	
14-pin D (SOIC)	Low k	765 mW	6.1 mW/°C	400 mW	275 mW	
	High k	1350 mW	10.8 mW/°C	705 mW	485 mW	270 mW
20-pin RHL (VQFN)	High k	1710 mW	13.7 mW/°C	890 mW	6150 mW	340 mW

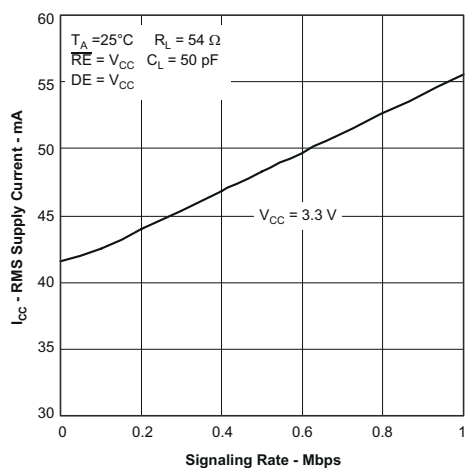
7.12 Typical Characteristics



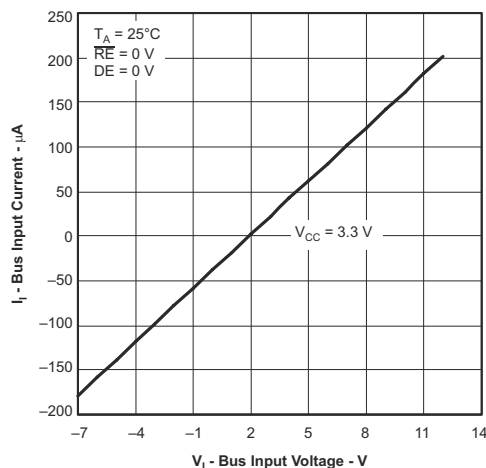
7-1. SN65HVD30, SN65HVD33 RMS Supply Current vs Signaling Rate



7-2. SN65HVD31, SN65HVD34 RMS Supply Current vs Signaling Rate

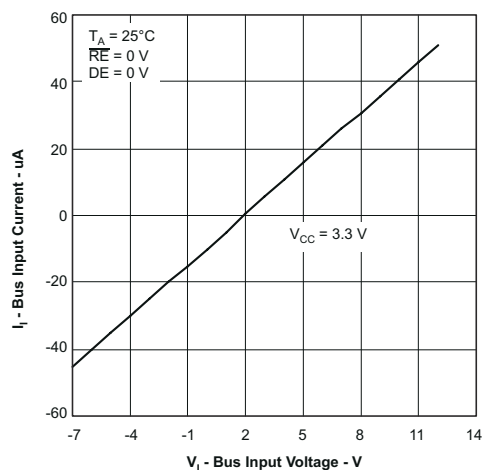


7-3. SN65HVD32, SN65HVD35 RMS Supply Current vs Signaling Rate

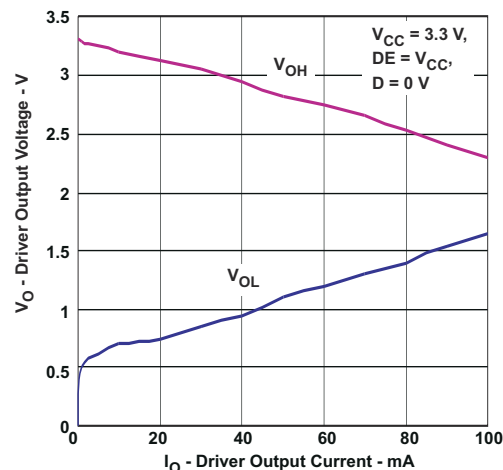


7-4. SN65HVD30, SN65HVD33 Bus Input Current vs Input Voltage

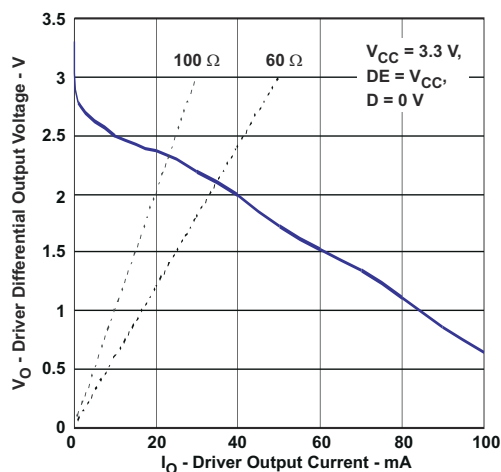
7.12 Typical Characteristics (continued)



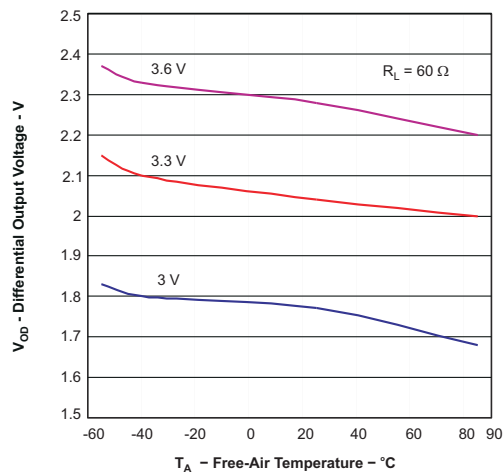
7-5. SN65HVD31, SN65HVD32, SN65HVD34, SN65HVD35 Bus Input Current vs Input Voltage



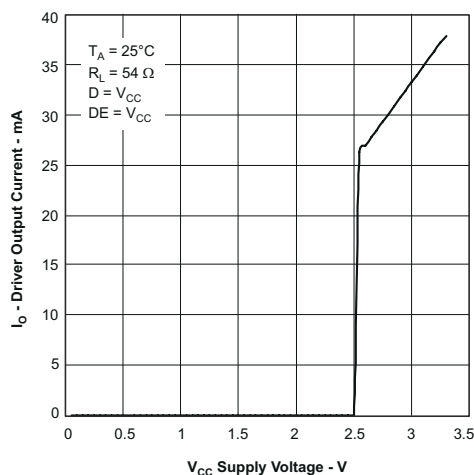
7-6. Driver Output Voltage vs Driver Output Current



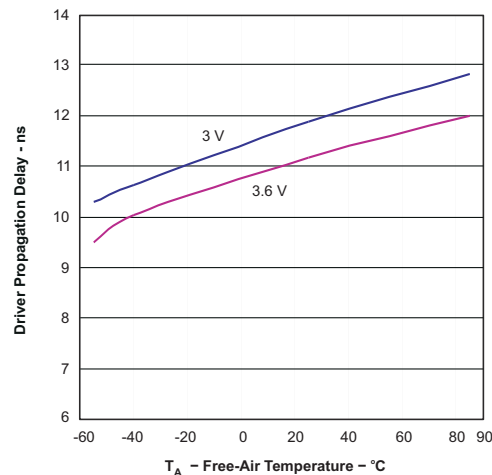
7-7. Driver Differential Output Voltage vs Driver Output Current



7-8. Driver Differential Output Voltage vs Free-Air Temperature

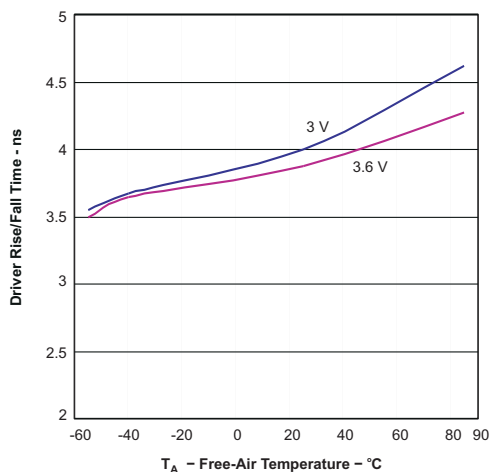


7-9. Driver Output Current vs Supply Voltage

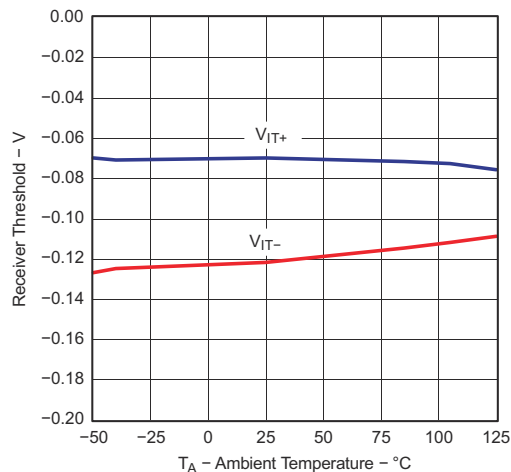


7-10. SN65HVD30, SN65HVD33 Driver Propagation Delay vs Free-Air Temperature

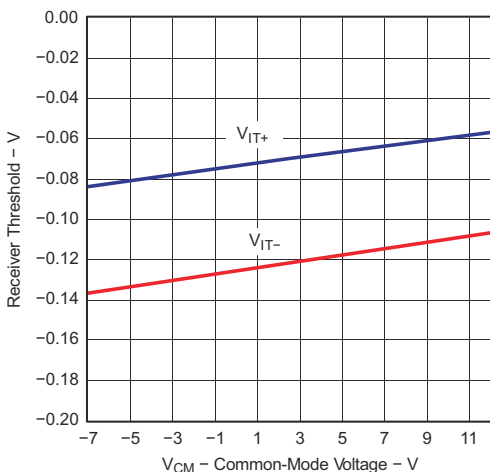
7.12 Typical Characteristics (continued)



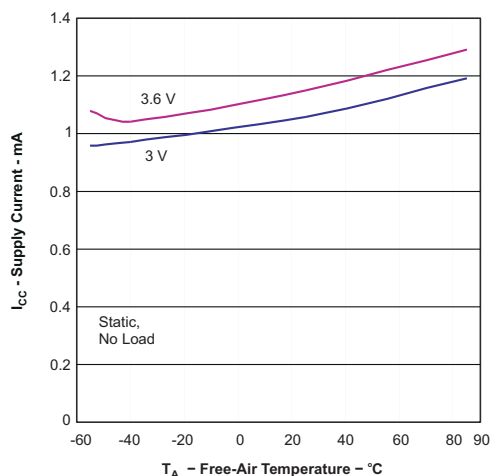
7-11. SN65HVD30, SN65HVD33 Driver Rise and Fall Time vs Free-Air Temperature



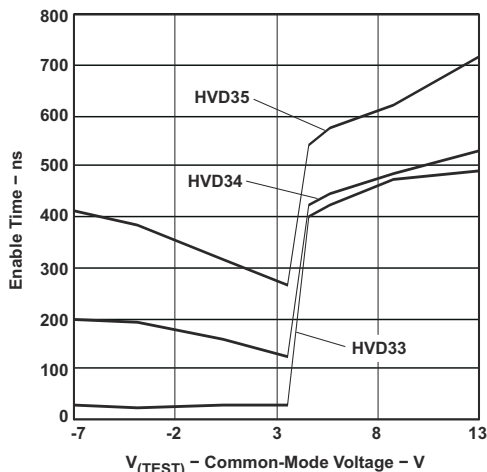
7-12. Receiver Threshold vs Ambient Temperature



7-13. Receiver Threshold vs Common-Mode Voltage

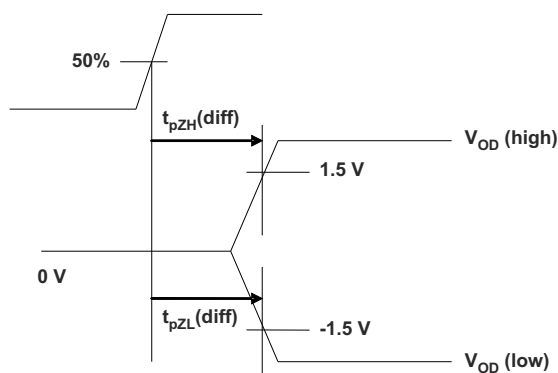
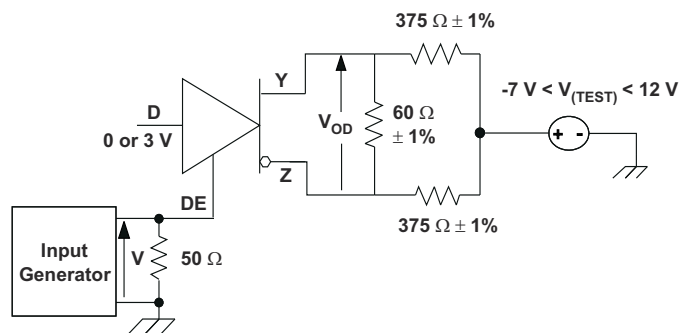


7-14. Supply Current vs Free-Air Temperature



7-15. Enable Time vs Common-Mode Voltage (see 8-1)

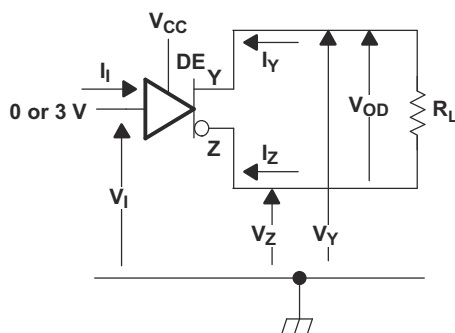
Parameter Measurement Information



Copyright © 2017, Texas Instruments Incorporated

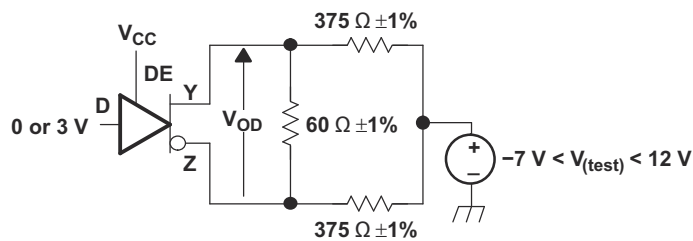
The time $t_{pZL}(x)$ is the measure from DE to $V_{OD}(x)$. V_{OD} is valid when it is greater than 1.5 V.

8-1. Driver Enable Time From DE to V_{OD}



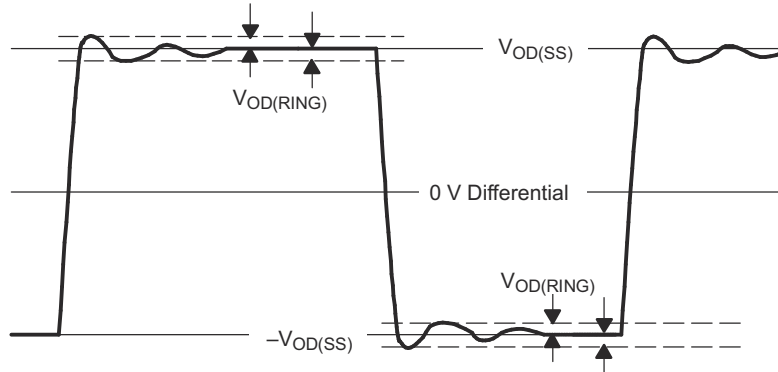
Copyright © 2017, Texas Instruments Incorporated

8-2. Driver V_{OD} Test Circuit and Voltage and Current Definitions



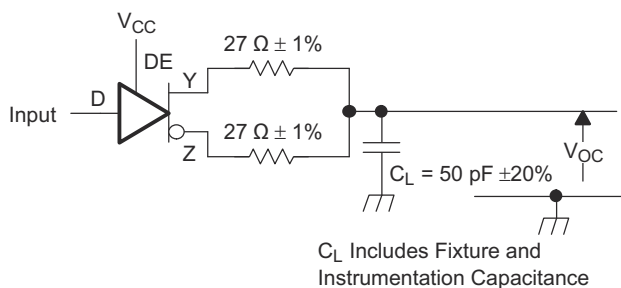
Copyright © 2017, Texas Instruments Incorporated

8-3. Driver V_{OD} With Common-Mode Loading Test Circuit

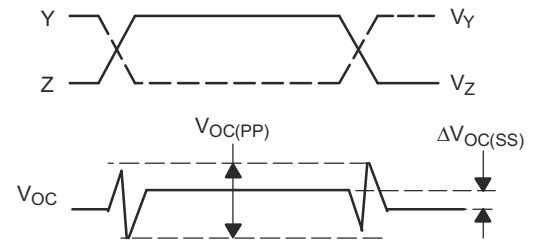


8-4. $V_{OD(RING)}$ Waveform and Definitions

$V_{OD(RING)}$ is measured at four points on the output waveform, corresponding to overshoot and undershoot from the $V_{OD(H)}$ and $V_{OD(L)}$ steady state values.

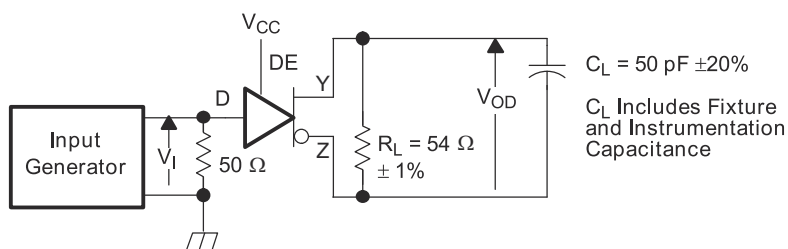


Input: PRR = 500 kHz, 50% Duty Cycle, $t_r < 6\text{ns}$, $t_f < 6\text{ns}$, $Z_O = 50\ \Omega$

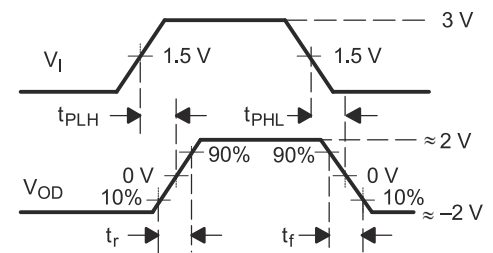


Copyright © 2017, Texas Instruments Incorporated

8-5. Test Circuit and Definitions for the Driver Common-Mode Output Voltage

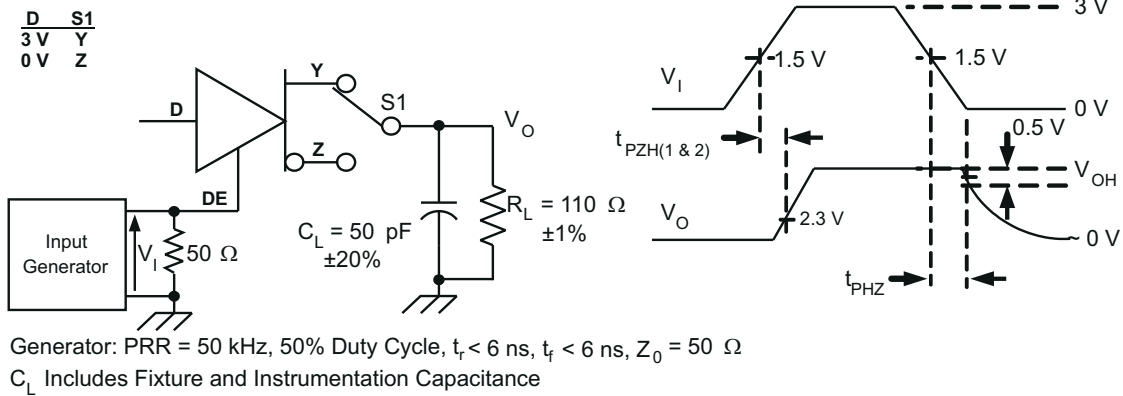


Generator: PRR = 500 kHz, 50% Duty Cycle, $t_r < 6\text{ ns}$, $t_f < 6\text{ ns}$, $Z_O = 50\ \Omega$

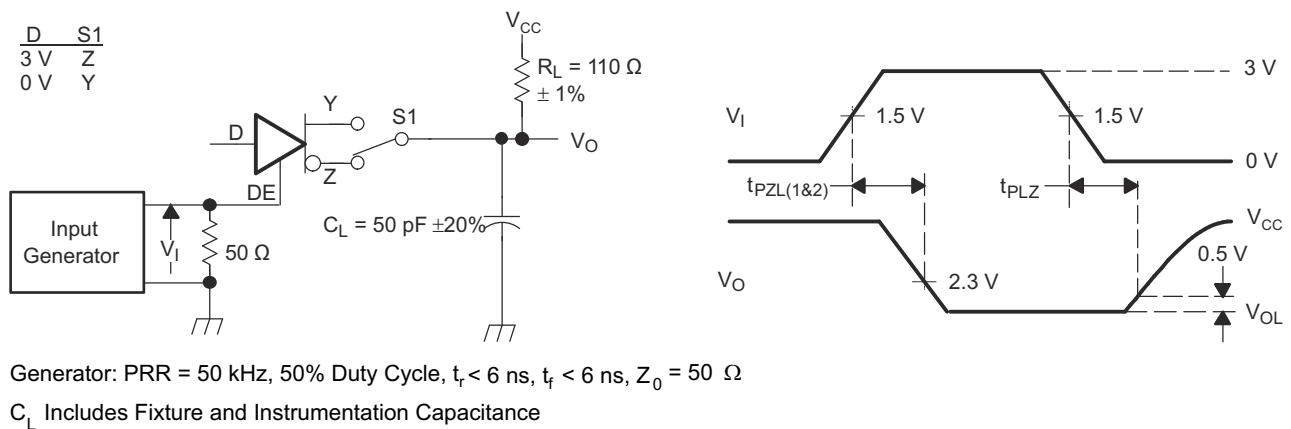


Copyright © 2017, Texas Instruments Incorporated

8-6. Driver Switching Test Circuit and Voltage Waveforms

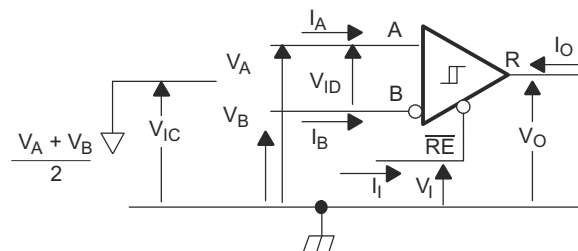


8-7. Driver High-Level Output Enable and Disable Time Test Circuit and Voltage Waveforms



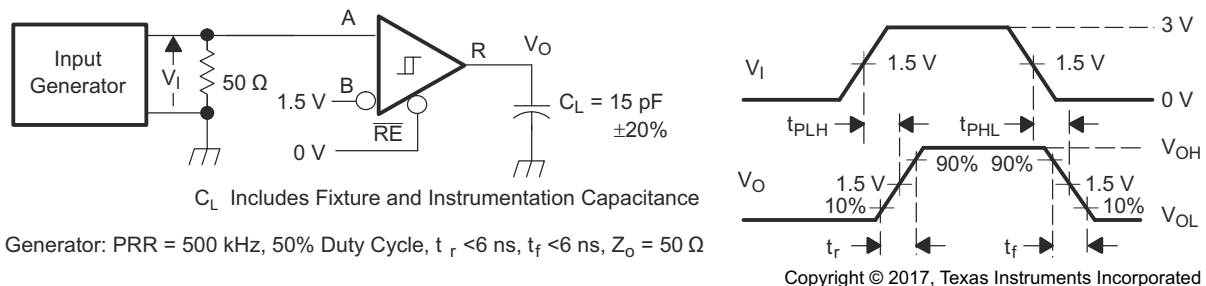
Copyright © 2017, Texas Instruments Incorporated

8-8. Driver Low-Level Output Enable and Disable Time Test Circuit and Voltage Waveforms



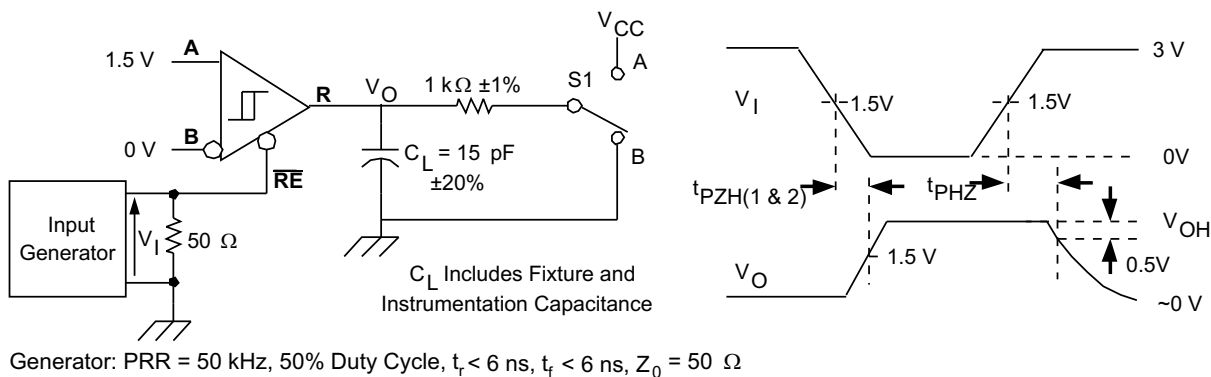
Copyright © 2017, Texas Instruments Incorporated

8-9. Receiver Voltage and Current Definitions



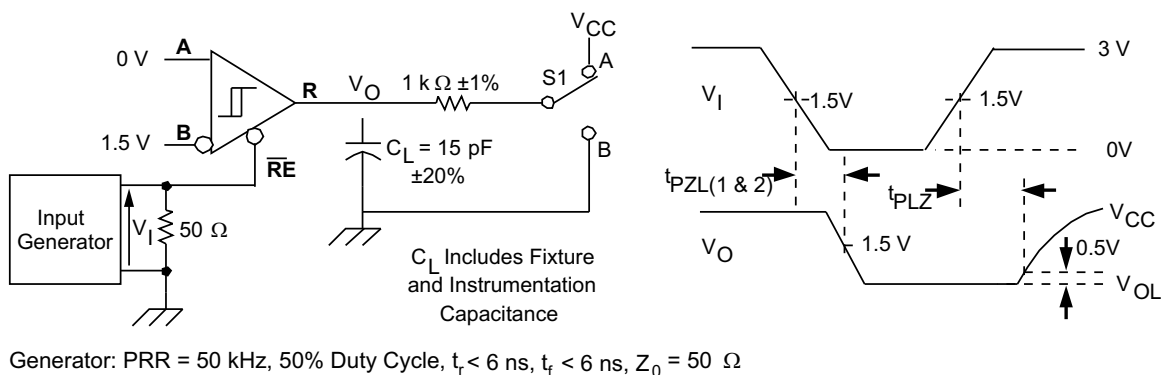
Copyright © 2017, Texas Instruments Incorporated

8-10. Receiver Switching Test Circuit and Voltage Waveforms



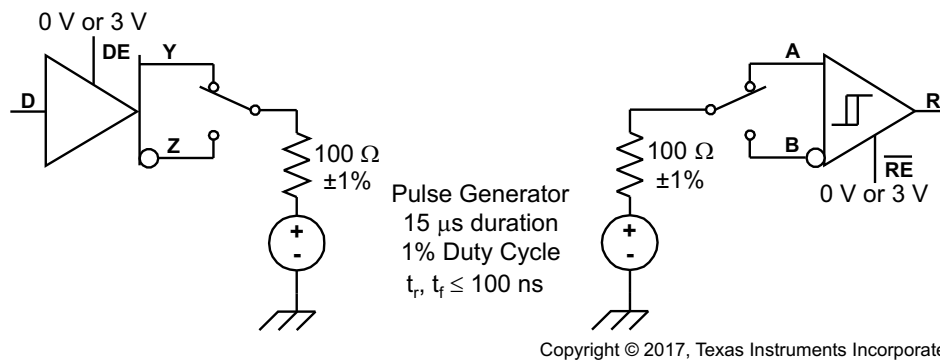
Copyright © 2017, Texas Instruments Incorporated

8-11. Receiver High-Level Enable and Disable Time Test Circuit and Voltage Waveforms



Copyright © 2017, Texas Instruments Incorporated

8-12. Receiver Enable Time From Standby (Driver Disabled)



Copyright © 2017, Texas Instruments Incorporated

8-13. Test Circuit, Transient Over Voltage Test

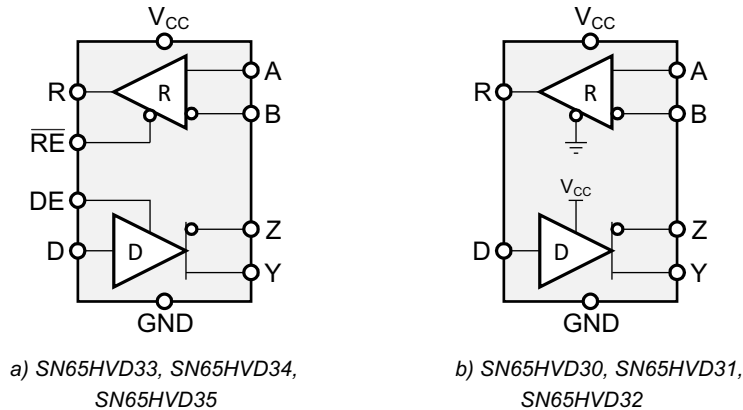
8 Detailed Description

8.1 Overview

The SN65HVD3x devices are low-power, full-duplex RS-485 transceivers available in three speed grades suitable for data transmission of 1 Mbps, 5 Mbps, and 50 Mbps.

The SN65HVD30, SN65HVD31, and SN65HVD32 devices are fully enabled with no external enabling pins. The SN65HVD33, SN65HVD34, and SN65HVD35 devices have active-high driver enables and active-low receiver enables. A standby current of less than 1 μ A can be achieved by disabling both driver and receiver.

8.2 Functional Block Diagram

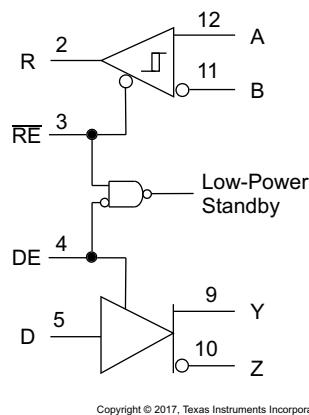


Copyright © 2017, Texas Instruments Incorporated

8.3 Feature Description

8.3.1 Low-Power Standby Mode

When both the driver and receiver are disabled (DE is low and $\overline{RE}$ is high), the device is in standby mode. If the enable inputs are in this state for less than 60 ns, the device does not enter standby mode. This guards against inadvertently entering standby mode during driver or receiver enabling. The device in standby mode only when the enable inputs are held in this state for 300 ns or more. In this low-power standby mode, most internal circuitry is powered down, and the supply current is typically less than 1 nA. When either the driver or the receiver is re-enabled, the internal circuitry becomes active.



Copyright © 2017, Texas Instruments Incorporated

8-1. Low-Power Standby Logic Diagram

If only the driver is re-enabled (DE transitions to high) the driver outputs are driven according to the D input after the enable times given by t_{PZH2} and t_{PZL2} in the driver switching characteristics. If the D input is open when the driver is enabled, the driver output defaults to Y low and Z high, in accordance with the driver-failsafe feature.

If only the receiver is re-enabled ($\overline{RE}$ transitions to low) the receiver output is driven according to the state of the bus inputs (A and B) after the enable times given by t_{PZH2} and t_{PZL2} in the receiver switching characteristics. If there is no valid state on the bus the receiver responds as described in the failsafe operation section.

If both the receiver and driver are re-enabled simultaneously, the receiver output is driven according to the state of the bus inputs (A and B) and the driver output is driven according to the D input. Note that the state of the active driver affects the inputs to the receiver. Therefore, the receiver outputs are valid as soon as the driver outputs are valid.

8.3.2 Driver Output Current Limiting

The RS-485 standard (ANSI/TIA/EIA-485-A or equivalently ISO 8482) specifies a 250-mA driver output current limit to prevent damage caused by data contention on the bus. That applies in the event that two or more transceivers drive the bus to opposing states at the same time. The SN65HVD3x family of devices includes current-limiting circuitry that prevents damage under these conditions.

注

This current limit prevents damage during the bus contention, but the logic state of the bus can be indeterminate as specified by the standard, so communication errors can occur.

In a specific combination of circumstances, a condition can occur in which current through the bus pin exceeds the 250-mA limit. This combination of conditions is not normally included in RS-485 applications:

- Loading capacitance on the pin is less than 500 pF
- The bus pin is directly connected to a voltage more negative than -1 V
- The device is supplied with V_{CC} equal to or greater than 3.3 V
- The driver is enabled
- The bus pin is driving to the logic high state

In these specific conditions, the normal current-limit circuitry and thermal-shutdown circuitry does not limit or shutdown the current flow. If the current is allowed to continue, the device heats up in a localized area near the driver outputs, and the device can be damaged.

Typical RS-485 twisted-pair cable has a capacitance of approximately 50 pF/meter. Therefore, it is expected that 10 meters of cable can provide sufficient capacitance to prevent this latch-up condition.

The -7 to $+12$ -V common mode range specified by RS-485 is intended to allow communication between transceivers separated by significant distances when ground offsets may occur due to temporary current surges, electrical noise, and so on. Under those circumstances, the inherent cable needed to connect separated transceivers ensures that the conditions previously listed do not occur. For a transceiver separated by only a short cable length or backplane applications, it is unusual for there to be a steady-state negative common-mode voltage. It is possible for a negative power supply to be shorted to the bus lines due to miswiring or cable damage; however, this is a different root cause fault, and robust devices such as the SN65HVD178x family should be used for surviving power supply or miswiring faults.

The 250-mA current limit in the RS-485 standard is intended to prevent damage caused by data contention on the bus; that is, in the event that two or more transceivers drive the bus to different states at the same time. These devices are not damaged under these conditions because all RS-485 drivers have output impedance sufficient to prevent the direct connection condition stated previously. Typical RS-485 driver output impedance is on the order of $10\ \Omega$ to $30\ \Omega$.

8.3.3 Hot-Plugging

These devices are designed to operate in *hot swap* or *hot pluggable* applications. Key features for hot-pluggable applications are:

- Power-up
- Power-down glitch-free operation
- Default disabled input/output pins

- Receiver failsafe

As shown in [図 7-9](#), an internal power-on reset circuit keeps the driver outputs in a high-impedance state until the supply voltage has reached a level at which the device reliably operates. This ensures that no spurious bits are transmitted on the bus pin outputs as the power supply turns on or turns off.

As shown in the [セクション 8.4](#), the enable inputs have the feature of default disable on both the driver enable and receiver enable. This ensures that the device neither drives the bus nor reports data on the R pin until the associated controller actively drives the enable pins.

8.3.4 Receiver Failsafe

The differential receivers of the SN65HVD3x family are failsafe to invalid bus states caused by:

- Open bus conditions such as a disconnected connector
- Shorted bus conditions such as cable damage shorting the twisted-pair together
- Idle bus conditions that occur when no driver on the bus is actively driving

In any of these cases, the differential receiver outputs a failsafe logic high state so that the output of the receiver is not indeterminate.

Receiver failsafe is accomplished by offsetting the receiver thresholds such that the input indeterminate range does not include zero volts differential. In order to comply with the RS-422 and RS-485 standards, the receiver output must output a high when the differential input V_{ID} is more positive than 200 mV, and must output a low when V_{ID} is more negative than -200 mV. The receiver parameters which determine the failsafe performance are V_{IT+} , V_{IT-} , and V_{HYS} (the separation between V_{IT+} and V_{IT-}). As shown in the [Electrical Characteristics](#) table, differential signals more negative than -200 mV always cause a low receiver output, and differential signals more positive than 200 mV always cause a high receiver output.

When the differential input signal is close to zero, it is still above the V_{IT+} threshold, and the receiver output is high. Only when the differential input is more than V_{HYS} below V_{IT+} does the receiver output transition to a low state. Therefore, the noise immunity of the receiver inputs during a bus fault conditions includes the receiver hysteresis value (V_{HYS}) as well as the value of V_{IT+} .

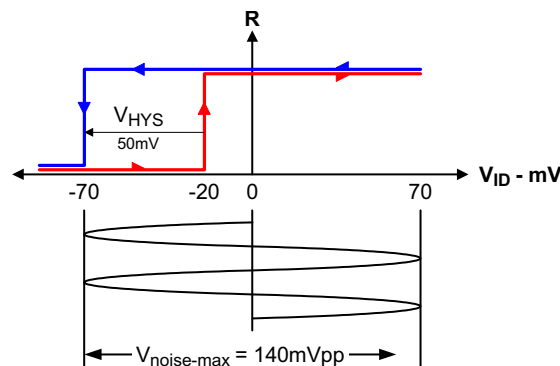


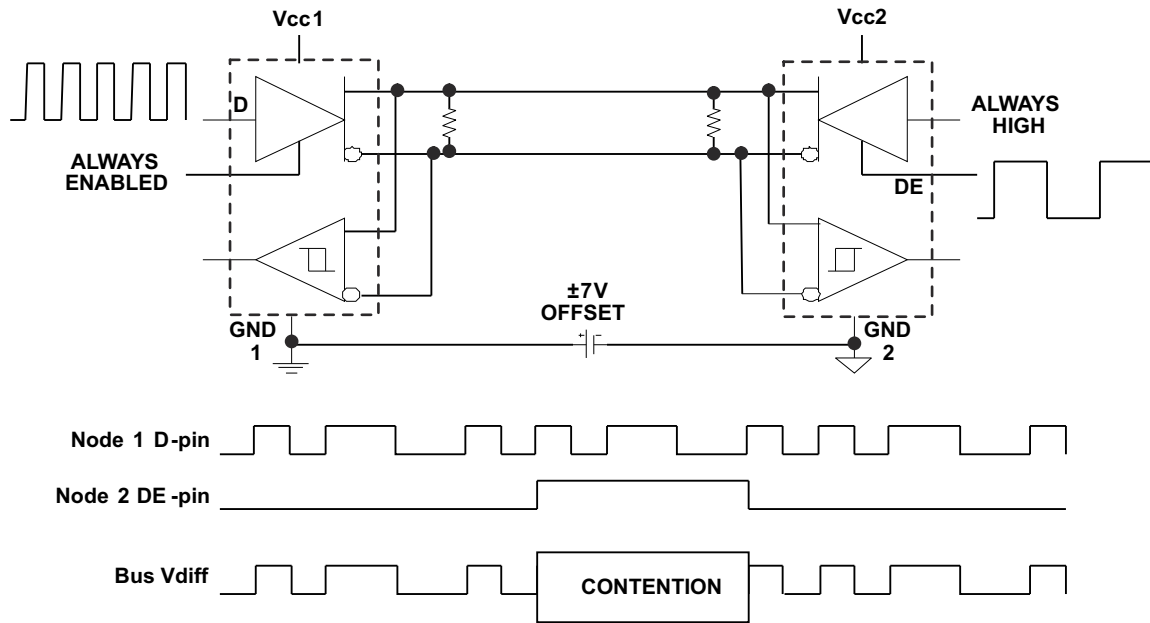
図 8-2. SN65HVD30-35 Noise Immunity Under Bus Fault Conditions

8.3.5 Safe Operation With Bus Contention

These devices incorporate a driver current limit of 250 mA across the RS-485 common-mode range of -7 V to +12 V. As stated in the *Application Guidelines for TIA/EIA-485-A*¹, this sets a practical limitation to prevent damage during bus contention events. Contention can occur during system initialization, during system faults, or whenever two or more drivers are active at the same time.

¹ TIA/EIA Telecommunications System Bulletin TSB89, *Application Guidelines for TIA/EIA-485-A*

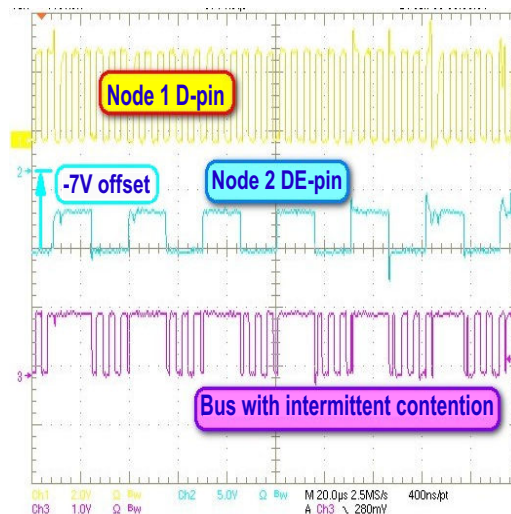
8-3 shows a 2-node system to demonstrate bus contention by forcing both drivers to be active in opposing states.



Copyright © 2017, Texas Instruments Incorporated

8-3. Bus Contention Example

8-4 shows typical operation in a bus contention event. The bottom trace illustrates how the SN65HVD33 device at Node 1 continues normal operation after a contention event between the two drivers with a $-7V$ ground offset on Node 2. This illustrates how the SN65HVD3x family of devices operates robustly in spite of bus contention faults, even with large common-mode offsets.



8-4. SN65HVD3x Drivers Operate Correctly After Bus Contention Faults

8.4 Device Functional Modes

表 8-1. SN65HVD33, SN65HVD34, SN65HVD35 Driver

INPUTS		OUTPUTS	
D	DE	Y	Z
H	H	H	L
L	H	L	H
X	L or open	Z	Z
Open	H	L	H

**表 8-2. SN65HVD33, SN65HVD34, SN65HVD35
Receiver**

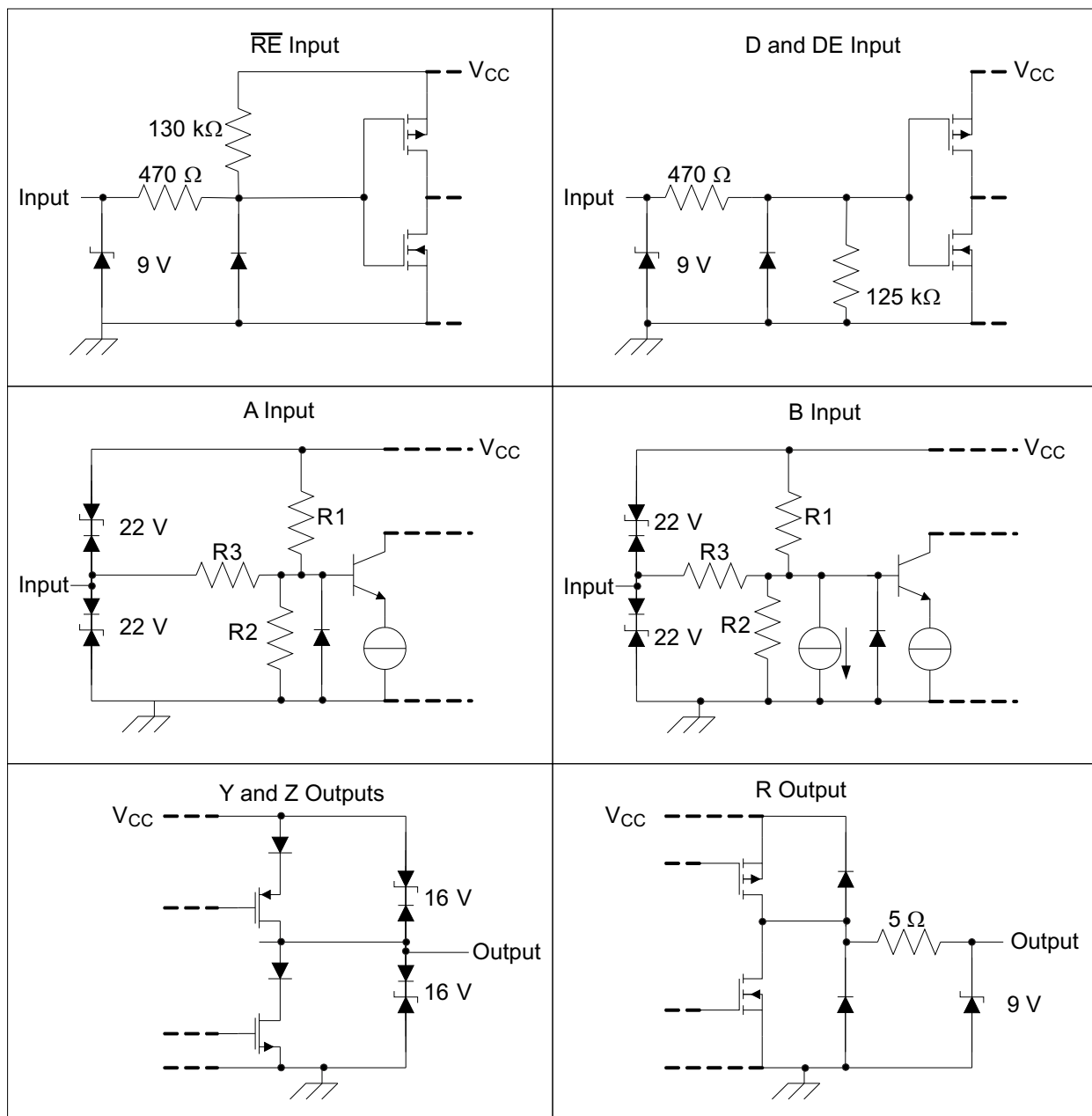
DIFFERENTIAL INPUTS $V_{ID} = V_{(A)} - V_{(B)}$	ENABLE RE	OUTPUT R
$V_{ID} \leq -0.2 \text{ V}$	L	L
$-0.2 \text{ V} < V_{ID} < -0.02 \text{ V}$	L	?
$-0.02 \text{ V} \leq V_{ID}$	L	H
X	H or open	Z
Open Circuit	L	H
Idle circuit	L	H
Short Circuit, $V_{(A)} = V_{(B)}$	L	H

表 8-3. SN65HVD30, SN65HVD31, SN65HVD32 Driver

INPUT D	OUTPUTS	
	Y	Z
H	H	L
L	L	H
Open	L	H

**表 8-4. SN65HVD30, SN65HVD31, SN65HVD32
Receiver**

DIFFERENTIAL INPUTS $V_{ID} = V_{(A)} - V_{(B)}$	OUTPUT R
$V_{ID} \leq -0.2 \text{ V}$	L
$-0.2 \text{ V} < V_{ID} < -0.02 \text{ V}$	?
$-0.02 \text{ V} \leq V_{ID}$	H
Open Circuit	H
Idle circuit	H
Short Circuit, $V_{(A)} = V_{(B)}$	H



Copyright © 2017, Texas Instruments Incorporated

图 8-5. Equivalent Input and Output Schematic Diagrams

表 8-5. Input Attenuator Resistance Values

PART NUMBER	R1, R2	R3
SN65HVD30, SN65HVD33	9 kΩ	45 kΩ
SN65HVD31, SN65HVD32, SN65HVD34, SN65HVD35	36 kΩ	180 kΩ

9 Application and Implementation

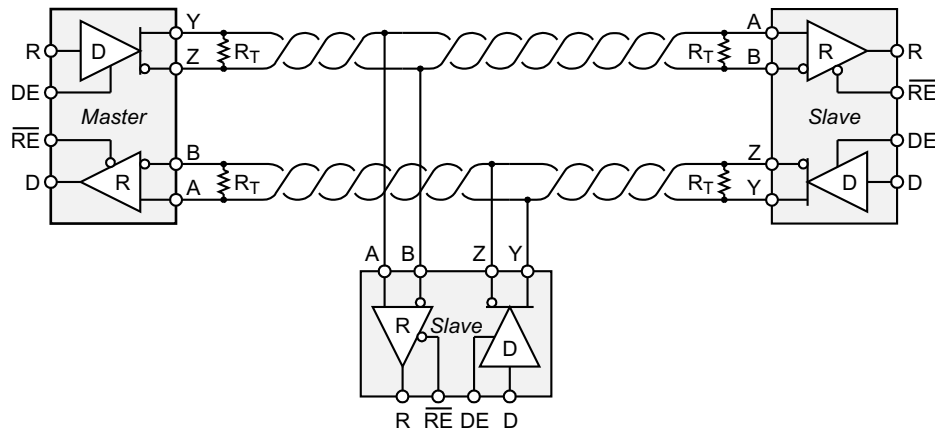
注

以下のアプリケーション情報は、TI の製品仕様に含まれるものではなく、TI ではその正確性または完全性を保証いたしません。個々の目的に対する製品の適合性については、お客様の責任で判断していただくことになります。お客様は自身の設計実装を検証しテストすることで、システムの機能を確認する必要があります。

9.1 Application Information

The SN65HVD3x family consists of full-duplex RS-485 transceivers commonly used for asynchronous data transmissions. Full-duplex implementation requires two signal pairs (four wires), and allows each node to transmit data on one pair while simultaneously receiving data on the other pair.

To eliminate line reflections, each cable end is terminated with a termination resistor (R_T) whose value matches the characteristic impedance (Z_0) of the cable. This method, known as parallel termination, allows for higher data rates over longer cable length.



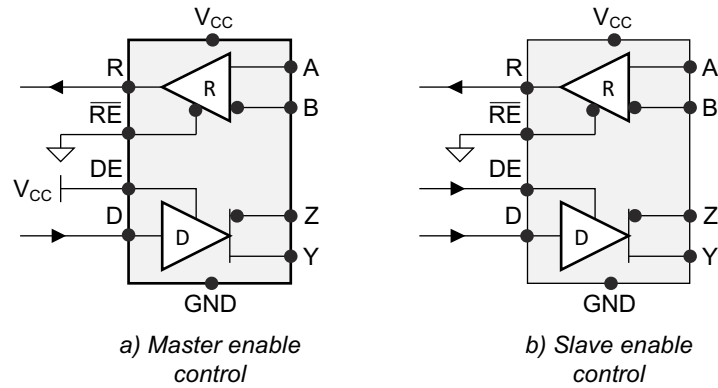
Copyright © 2017, Texas Instruments Incorporated

図 9-1. Typical RS-485 Network With Full-Duplex Transceivers

9.2 Typical Application

A full-duplex RS-485 network consists of multiple transceivers connecting in parallel to two bus cables. On one signal pair, a master driver transmits data to multiple slave receivers. The master driver and slave receivers can remain fully enabled at all times. On the other signal pair, multiple slave drivers transmit data to the master receiver. To avoid bus contention, the slave drivers must be intermittently enabled and disabled such that only one driver is enabled at any time, as in half-duplex communication. The master receiver can remain fully enabled at all times.

Because the driver cannot be disabled, only connect one driver to the bus when using the SN65HVD30, SN65HVD31, or SN65HVD32 devices.



Copyright © 2017, Texas Instruments Incorporated

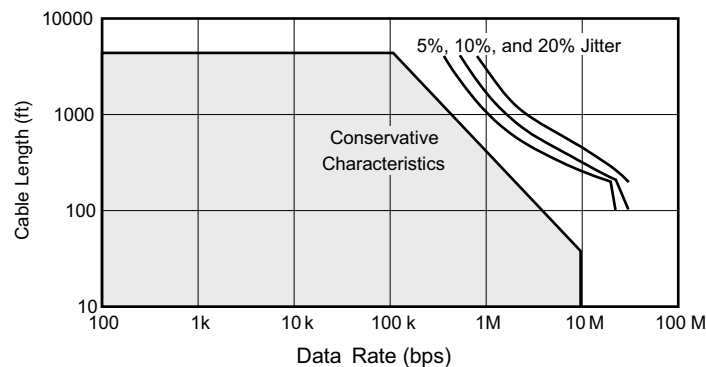
9-2. Full-Duplex Transceiver Configurations

9.2.1 Design Requirements

RS-485 is a robust electrical standard suitable for long-distance networking that may be used in a wide range of applications with varying requirements, such as distance, data rate, and number of nodes.

9.2.1.1 Data Rate and Bus Length

There is an inverse relationship between data rate and bus length, meaning the higher the data rate, the shorter the cable length; and conversely, the lower the data rate, the longer the cable can be without introducing data errors. While most RS-485 systems use data rates between 10 kbps and 100 kbps, some applications require data rates up to 250 kbps at distances of 4000 feet and longer. Longer distances are possible by allowing for small signal jitter of up to 5 or 10%.



9-3. Cable Length vs Data Rate Characteristic

Even higher data rates are achievable (such as 26 Mbps for the SN65HVD30 and SN65HVD33 devices) in cases where the interconnect is short enough (or has suitably low attenuation at signal frequencies) to not degrade the data.

9.2.1.2 Stub Length

When connecting a node to the bus, the distance between the transceiver inputs and the cable trunk, known as the stub, must be as short as possible. Stubs present a nonterminated piece of bus line that can introduce reflections as the length of the stub increases. As a general guideline, the electrical length, or round-trip delay, of a stub must be less than one-tenth of the rise time of the driver; thus giving a maximum physical stub length as shown in 式 1.

$$L_{\text{stub}} \leq 0.1 \times t_r \times v \times c \quad (1)$$

where:

- t_r is the 10/90 rise time of the driver
- c is the speed of light (3×10^8 m/s)
- v is the signal velocity of the cable or trace as a factor of c

Per 式 1, 表 9-1 shows the maximum cable-stub lengths for the minimum driver output rise times of the SN65HVD3x full-duplex family of transceivers for a signal velocity of 78%.

表 9-1. Maximum Stub Length

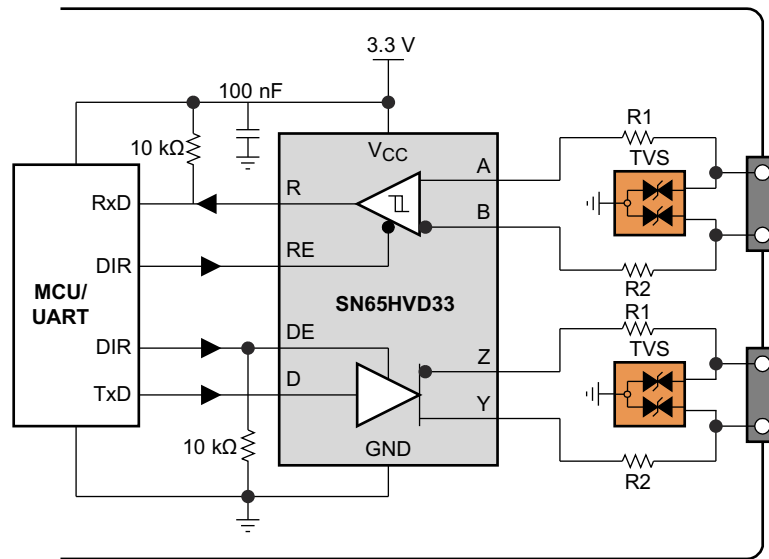
DEVICE	MINIMUM DRIVER OUTPUT RISE TIME (ns)	MAXIMUM STUB LENGTH	
		(m)	(ft)
SN65HVD30	4	0.1	0.3
SN65HVD31	25	0.6	1.9
SN65HVD32	120	2.8	9.2
SN65HVD33	4	0.1	0.3
SN65HVD34	25	0.6	1.9
SN65HVD35	120	2.8	9.2

9.2.1.3 Bus Loading

The RS-485 standard specifies that a compliant driver must be able to driver 32 unit loads (UL), where 1 unit load represents a load impedance of approximately 12 kΩ. Because the SN65HVD30 and SN65HVD33 devices are 1/2 UL transceivers, it is possible to connect up to 64 receivers to the bus. Likewise, the SN65HVD31, SN65HVD32, SN65HVD34, and SN65HVD35 devices are 1/8 UL transceivers that can support up to 256 receivers.

9.2.2 Detailed Design Procedure

To protect bus nodes against high-energy transients, the implementation of external transient protection devices is necessary (see [Figure 9-4](#)).



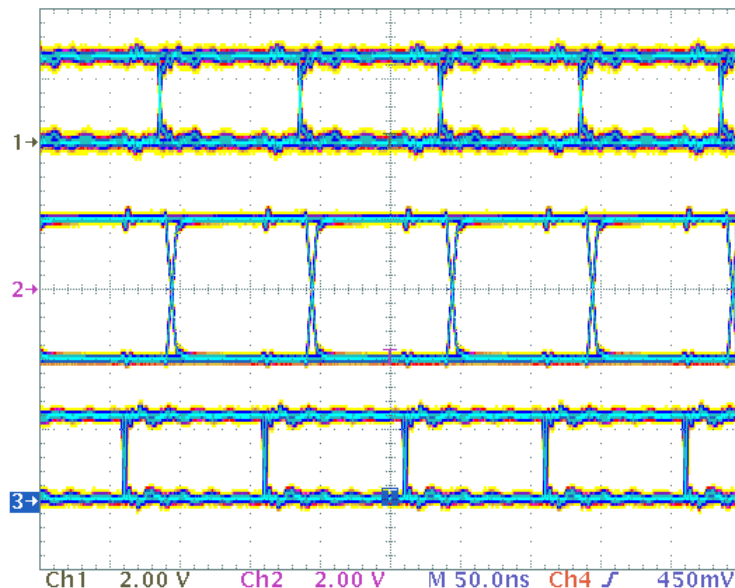
Copyright © 2017, Texas Instruments Incorporated

Figure 9-4. Transient Protection Against ESD, EFT, and Surge Transients

Table 9-2. Bill of Materials

DEVICE	FUNCTION	ORDER NUMBER	MANUFACTURER
XCVR	3.3-V Full-Duplex RS-485 Transceiver	SN65HVD33	TI
R1, R2	10-Ω, Pulse-Proof Thick-Film Resistor	CRCW060310RJNEAHP	Vishay
TVS	Bidirectional 400-W Transient Suppressor	CDSOT23-SM712	Bourns

9.2.3 Application Curve



Signals from top to bottom: D, Y, Z, VOD

Figure 9-5. SN65HVD33 Transient Waveform

9.3 Power Supply Recommendations

To ensure reliable operation at all data rates and supply voltages, each supply must be decoupled with a 100-nF ceramic capacitor located as close as possible to the supply pins. This helps to reduce supply voltage ripple present on the outputs of switched-mode power supplies and also helps compensate for the resistance and inductance of the PCB power planes.

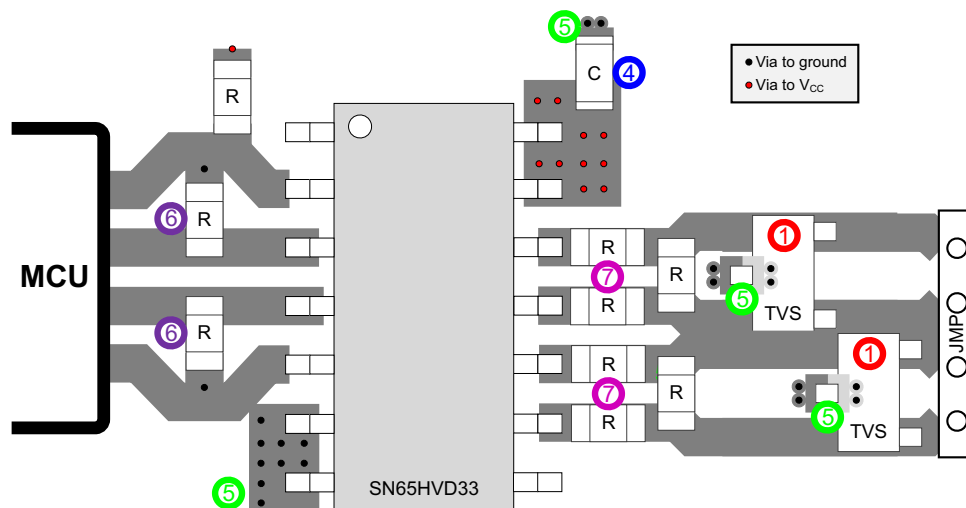
9.4 Layout

9.4.1 Layout Guidelines

Robust and reliable bus-node design often requires the use of external transient protection devices to protect against EFT and surge transients that can occur in industrial environments. Because these transients have a wide frequency bandwidth (from approximately 3 MHz to 3 GHz), high-frequency layout techniques must be applied during PCB design.

- Place the protection circuitry close to the bus connector to prevent noise transients from entering the board.
- Use V_{CC} and ground planes to provide low-inductance. High-frequency currents follow the path of least inductance and not the path of least impedance.
- Design the protection components into the direction of the signal path. Do not force the transients currents to divert from the signal path to reach the protection device.
- Apply 100-nF to 220-nF bypass capacitors as close as possible to the V_{CC} pins of transceiver, UART, and controller ICs on the board.
- Use at least two vias for V_{CC} and ground connections of bypass capacitors and protection devices to minimize effective via inductance.
- Use 1-k Ω to 10-k Ω pullup or pulldown resistors for enable lines to limit noise currents in these lines during transient events.
- Insert series pulse-proof resistors into the A and B bus lines if the TVS clamping voltage is higher than the specified maximum voltage of the transceiver bus pins. These resistors limit the residual clamping current into the transceiver and prevent it from latching up.
- While pure TVS protection is sufficient for surge transients up to 1 kV, higher transients require metal-oxide varistors (MOVs), which reduces the transients to a few hundred volts of clamping voltage and transient blocking units (TBUs) that limit transient current to 200 mA.

9.4.2 Layout Example



9-6. SN65HVD33 Layout Example

10 Device and Documentation Support

10.1 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、ti.com のデバイス製品フォルダを開いてください。「更新の通知を受け取る」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

10.2 サポート・リソース

TI E2E™ サポート・フォーラムは、エンジニアが検証済みの回答と設計に関するヒントをエキスパートから迅速かつ直接得ることができる場所です。既存の回答を検索したり、独自の質問をしたりすることで、設計に必要な支援を迅速に得ることができます。

リンクされているコンテンツは、該当する貢献者により、現状のまま提供されるものです。これらは TI の仕様を構成するものではなく、必ずしも TI の見解を反映したものではありません。TI の[使用条件](#)を参照してください。

10.3 Trademarks

TI E2E™ is a trademark of Texas Instruments.

すべての商標は、それぞれの所有者に帰属します。

10.4 静電気放電に関する注意事項



この IC は、ESD によって破損する可能性があります。テキサス・インスツルメンツは、IC を取り扱う際には常に適切な注意を払うことを推奨します。正しい取り扱いおよび設置手順に従わない場合、デバイスを破損するおそれがあります。

ESD による破損は、わずかな性能低下からデバイスの完全な故障まで多岐にわたります。精密な IC の場合、パラメータがわずかに変化するだけで公表されている仕様から外れる可能性があるため、破損が発生しやすくなっています。

10.5 用語集

[テキサス・インスツルメンツ用語集](#) この用語集には、用語や略語の一覧および定義が記載されています。

11 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
SN65HVD30D	Obsolete	Production	SOIC (D) 8	-	-	Call TI	Call TI	-40 to 85	VP30
SN65HVD30DR	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	VP30
SN65HVD30DR.A	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	VP30
SN65HVD30DRG4	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	VP30
SN65HVD31D	Obsolete	Production	SOIC (D) 8	-	-	Call TI	Call TI	-40 to 85	VP31
SN65HVD31DR	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	VP31
SN65HVD31DR.A	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	VP31
SN65HVD31DRG4.A	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	VP31
SN65HVD32DR	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	VP32
SN65HVD32DR.A	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	VP32
SN65HVD32DRG4.A	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	VP32
SN65HVD33DR	Active	Production	SOIC (D) 14	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	65HVD33
SN65HVD33DR.A	Active	Production	SOIC (D) 14	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	65HVD33
SN65HVD33DRG4	Active	Production	SOIC (D) 14	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	65HVD33
SN65HVD33RHRL	Active	Production	VQFN (RHL) 20	3000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	65HVD33
SN65HVD33RHRL.A	Active	Production	VQFN (RHL) 20	3000 LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	65HVD33
SN65HVD33RHRLT	Active	Production	VQFN (RHL) 20	250 SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	65HVD33
SN65HVD33RHRLT.A	Active	Production	VQFN (RHL) 20	250 SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	65HVD33
SN65HVD33RHRLTG4.A	Active	Production	VQFN (RHL) 20	250 SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 85	65HVD33
SN65HVD34D	Obsolete	Production	SOIC (D) 14	-	-	Call TI	Call TI	-40 to 85	65HVD34
SN65HVD34DR	Active	Production	SOIC (D) 14	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	65HVD34
SN65HVD34DR.A	Active	Production	SOIC (D) 14	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	65HVD34
SN65HVD34DRG4.A	Active	Production	SOIC (D) 14	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	65HVD34
SN65HVD35DR	Active	Production	SOIC (D) 14	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	65HVD35
SN65HVD35DR.A	Active	Production	SOIC (D) 14	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	65HVD35
SN65HVD35DRG4	Active	Production	SOIC (D) 14	2500 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	65HVD35

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

(2) Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) RoHS values: Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF SN65HVD30, SN65HVD33 :

- Enhanced Product : [SN65HVD30-EP](#), [SN65HVD33-EP](#)

NOTE: Qualified Version Definitions:

- Enhanced Product - Supports Defense, Aerospace and Medical Applications

TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
SN65HVD30DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65HVD30DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65HVD31DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65HVD31DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65HVD32DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65HVD32DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
SN65HVD33DR	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1
SN65HVD33RHLLR	VQFN	RHL	20	3000	330.0	12.4	3.8	4.8	1.6	8.0	12.0	Q1
SN65HVD33RHLLT	VQFN	RHL	20	250	180.0	12.4	3.8	4.8	1.6	8.0	12.0	Q1
SN65HVD34DR	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1
SN65HVD35DR	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
SN65HVD30DR	SOIC	D	8	2500	356.0	356.0	35.0
SN65HVD30DR	SOIC	D	8	2500	356.0	356.0	35.0
SN65HVD31DR	SOIC	D	8	2500	356.0	356.0	35.0
SN65HVD31DR	SOIC	D	8	2500	356.0	356.0	35.0
SN65HVD32DR	SOIC	D	8	2500	356.0	356.0	35.0
SN65HVD32DR	SOIC	D	8	2500	356.0	356.0	35.0
SN65HVD33DR	SOIC	D	14	2500	356.0	356.0	35.0
SN65HVD33RHLLR	VQFN	RHL	20	3000	356.0	356.0	35.0
SN65HVD33RHLLT	VQFN	RHL	20	250	210.0	185.0	35.0
SN65HVD34DR	SOIC	D	14	2500	356.0	356.0	35.0
SN65HVD35DR	SOIC	D	14	2500	356.0	356.0	35.0

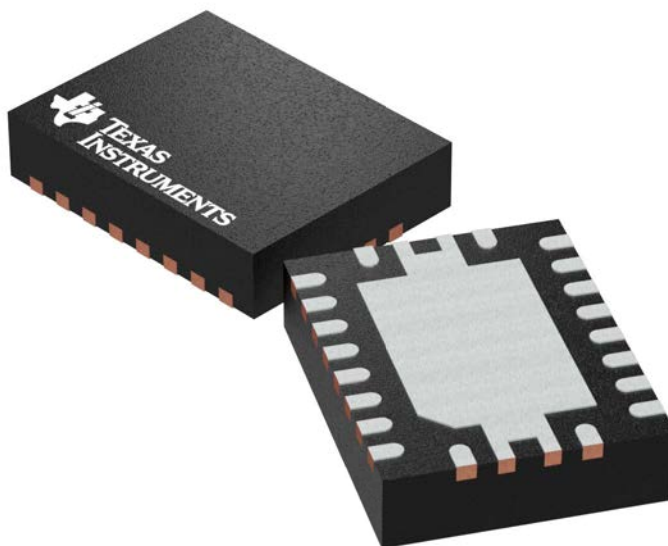
GENERIC PACKAGE VIEW

RHL 20

VQFN - 1 mm max height

3.5 x 4.5 mm, 0.5 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4205346/L

VQFN - 1 mm max height

[illegible]

NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

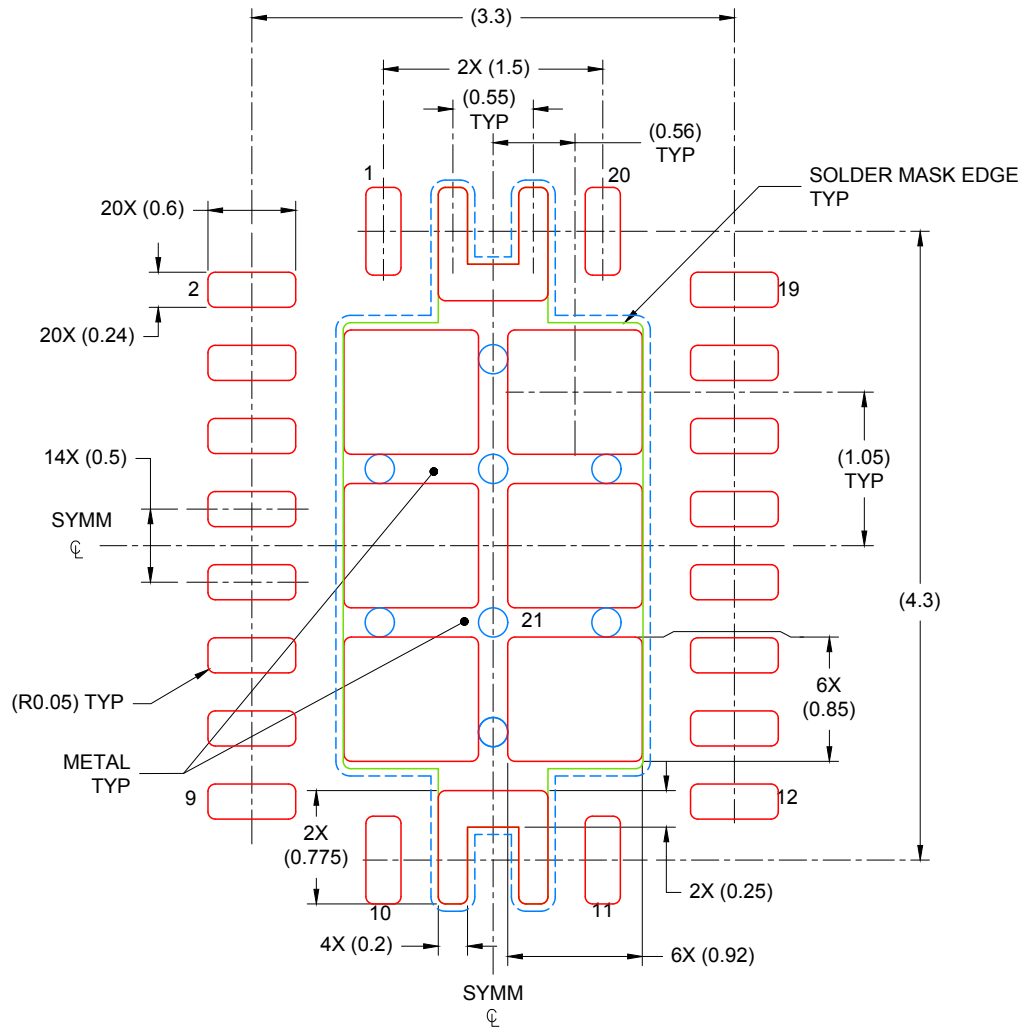
VQFN - 1 mm max height

The diagram compares two PCB pad designs for a through-hole component:

- NON SOLDER MASK DEFINED (PREFERRED):** This design shows a central circular pad of **EXPOSED METAL** surrounded by a ring of **METAL**. The entire area is covered by a **SOLDER MASK**, with a **SOLDER MASK OPENING** in the center. The distance between the metal ring and the solder mask edge is specified as **0.07 MAX ALL AROUND**.
- SOLDER MASK DEFINED:** This design shows a central circular pad of **EXPOSED METAL** surrounded by a ring of **METAL UNDER SOLDER MASK**. The entire area is covered by a **SOLDER MASK**, with a **SOLDER MASK OPENING** in the center. The distance between the metal ring and the solder mask edge is specified as **0.07 MIN ALL AROUND**.

4219071 / A 05/2017

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271) .
5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
6. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



SOLDER PASTE EXAMPLE
 BASED ON 0.1mm THICK STENCIL

EXPOSED PAD
 75% PRINTED COVERAGE BY AREA
 SCALE: 20X

4219071 / A 05/2017

NOTES: (continued)

7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations..

D0014A**PACKAGE OUTLINE****SOIC - 1.75 mm max height**

SMALL OUTLINE INTEGRATED CIRCUIT



4220718/A 09/2016

NOTES:

1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm, per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.43 mm, per side.
5. Reference JEDEC registration MS-012, variation AB.

EXAMPLE BOARD LAYOUT

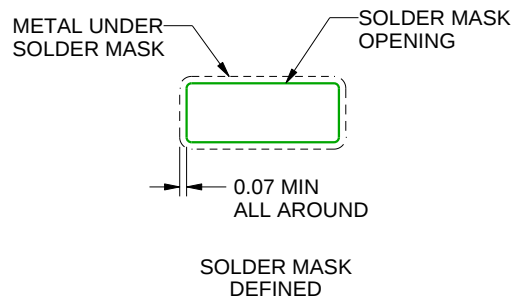
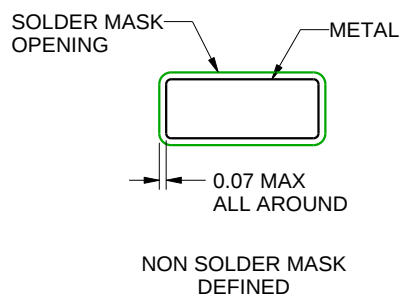
D0014A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE
SCALE:8X



SOLDER MASK DETAILS

4220718/A 09/2016

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

D0014A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE:8X

4220718/A 09/2016

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

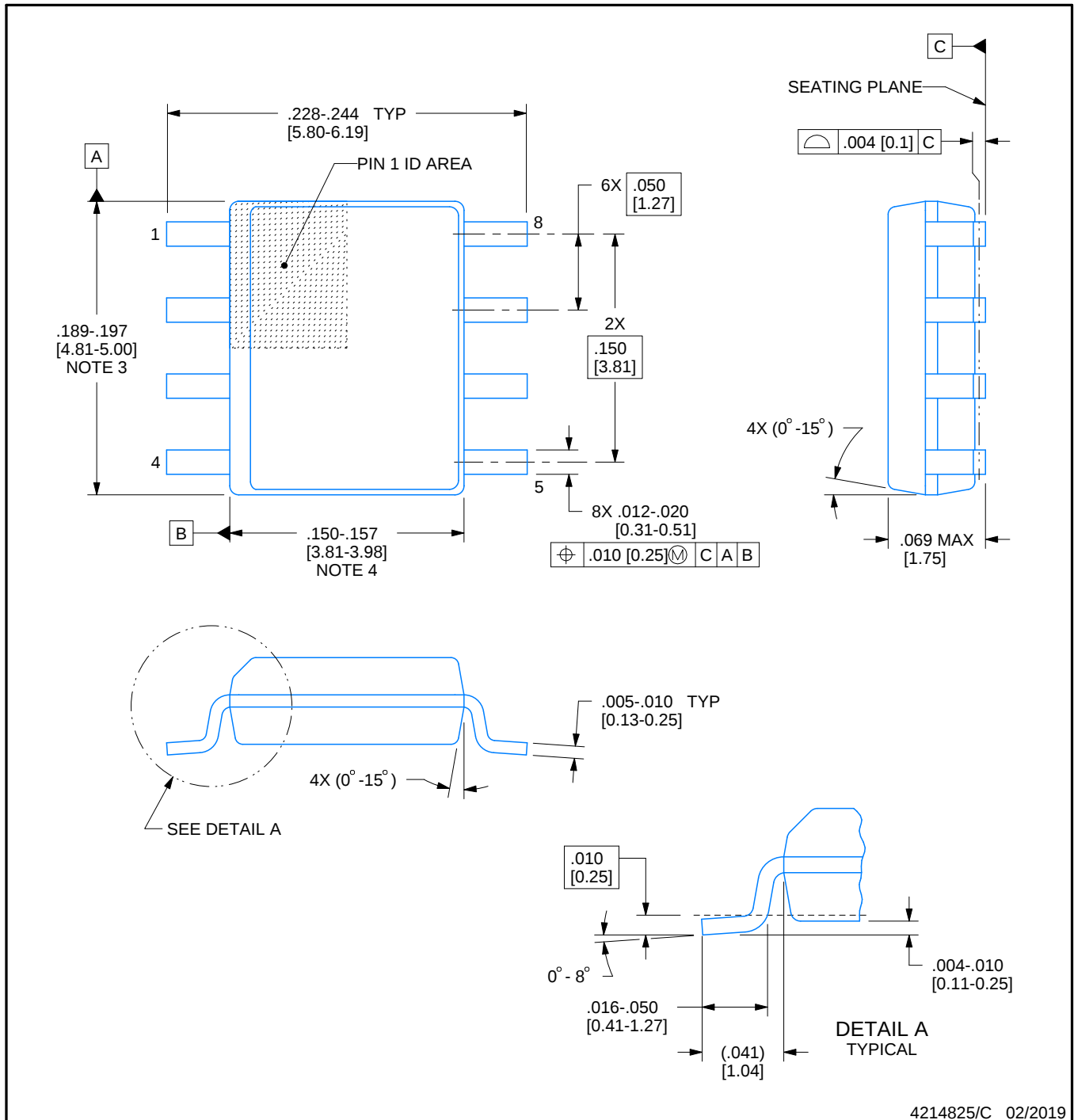


D0008A

PACKAGE OUTLINE

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



4214825/C 02/2019

NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

EXAMPLE BOARD LAYOUT

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



4214825/C 02/2019

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE
BASED ON .005 INCH [0.125 MM] THICK STENCIL
SCALE:8X

4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

重要なお知らせと免責事項

テキサス・インスツルメンツは、技術データと信頼性データ (データシートを含みます)、設計リソース (リファレンス デザインを含みます)、アプリケーションや設計に関する各種アドバイス、Web ツール、安全性情報、その他のリソースを、欠陥が存在する可能性のある「現状のまま」提供しており、商品性および特定目的に対する適合性の黙示保証、第三者の知的財産権の非侵害保証を含むいかなる保証も、明示的または黙示的にかかわらず拒否します。

これらのリソースは、テキサス・インスツルメンツ製品を使用する設計の経験を積んだ開発者への提供を意図したものです。(1) お客様のアプリケーションに適した テキサス・インスツルメンツ製品の選定、(2) お客様のアプリケーションの設計、検証、試験、(3) お客様のアプリケーションに該当する各種規格や、その他のあらゆる安全性、セキュリティ、規制、または他の要件への確実な適合に関する責任を、お客様のみが単独で負うものとします。

上記の各種リソースは、予告なく変更される可能性があります。これらのリソースは、リソースで説明されている テキサス・インスツルメンツ製品を使用するアプリケーションの開発の目的でのみ、テキサス・インスツルメンツはその使用をお客様に許諾します。これらのリソースに関して、他の目的で複製することや掲載することは禁止されています。テキサス・インスツルメンツや第三者の知的財産権のライセンスが付与されている訳ではありません。お客様は、これらのリソースを自身で使用した結果発生するあらゆる申し立て、損害、費用、損失、責任について、テキサス・インスツルメンツおよびその代理人を完全に補償するものとし、テキサス・インスツルメンツは一切の責任を拒否します。

テキサス・インスツルメンツの製品は、[テキサス・インスツルメンツの販売条件](#)、または [ti.com](https://www.ti.com) やかかる テキサス・インスツルメンツ製品の関連資料などのいずれかを通じて提供する適用可能な条項の下で提供されています。テキサス・インスツルメンツがこれらのリソースを提供することは、適用される テキサス・インスツルメンツの保証または他の保証の放棄の拡大や変更を意味するものではありません。

お客様がいかなる追加条項または代替条項を提案した場合でも、テキサス・インスツルメンツはそれらに異議を唱え、拒否します。

郵送先住所：Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2025, Texas Instruments Incorporated