TEXAS INSTRUMENTS

LP8758-E0

JAJSG84B – JANUARY 2016 – REVISED JUNE 2018

LP8758-E0 4出力の同期整流降圧型DC-DCコンバータ

1 特長

- 完全に統合されたクワッド降圧コンバータ、降圧コンバータ・コアごとに最大4Aの最大出力電流をプログラム可能
  - PWM-PFM自動切換え動作と強制PWM動作
  - 出力電圧スルー・レートを30mV/µs～0.5mV/µsの範囲でプログラム可能
  - 入力電圧範囲: 2.5V～5.5V
  - V_{OUT}範囲:0.5V～3.36V（DVS付き）
- プログラム可能なスタートアップおよびシャットダウン・シーケンス（イネーブル信号に同期）
- I^2C互換インターフェイスのStandard (100kHz)、Fast (400kHz)、Fast+ (1MHz)、High-Speed (3.4MHz)モードをサポート
- マスクをプログラム可能な割り込み機能
- 負荷電流測定
- 出力短絡および過負荷保護
- 拡散スペクトラム・モードによるEMI低減
- 4つの降圧コアは互いに90°異なる位相で動作するため、入力リップル電流が減少
- 過熱警告および保護
- 低電圧誤動作防止(UVLO)

2 アプリケーション

- スマートフォン、電子書籍、タブレット
- ネットワーク・プロセッサ・カード(NPC)、ワイヤレスおよびDSLモデム
- ソリッド・ステート・ドライブ
- ゲーム機

3 概要

LP8758-E0デバイスは、携帯電話やネットワーク・カードなどのアプリケーションで使用される低消費電力プロセッサの電力管理要件を満たすよう設計されています。このデバイスには、4つの降圧DC-DCコンバータ・コアが内蔵されており、4つの出力電圧レールを供給します。このデバイスは、I^2C互換のシリアル・インターフェイスにより制御されます。

PWM-PFMの自動切換え（AUTOモード）動作により、広い出力電流範囲にわたって効率を最大化します。

LP8758-E0は、ハードウェア・イネーブル入力信号に同期したプログラム可能なスタートアップおよびシャットダウン・シーケンスをサポートしています。

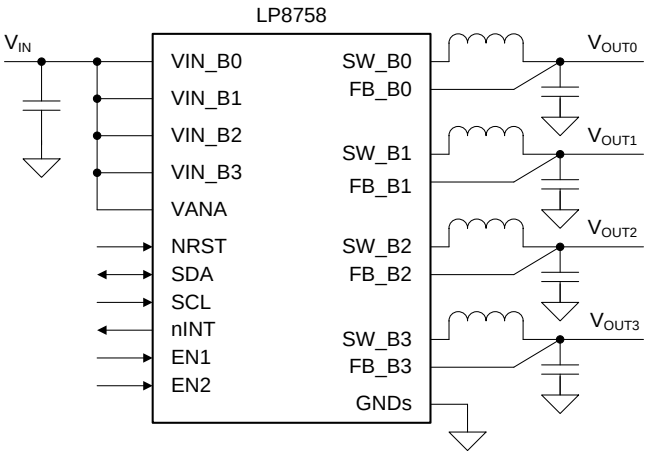
保護機能として、短絡保護、電流制限、入力電源UVLO、温度警告およびシャットダウン機能が搭載されています。デバイスのステータス情報のための複数のエラー・フラグが用意されています。さらに、LP8758-E0デバイスは、外付けの電流検出抵抗を追加しないで負荷電流を測定できます。スタートアップ中と電圧変化時に、本デバイスは出力スルー・レートを制御し、出力電圧のオーバーシュートと突入電流を最小化します。

表 1. 製品情報(1)

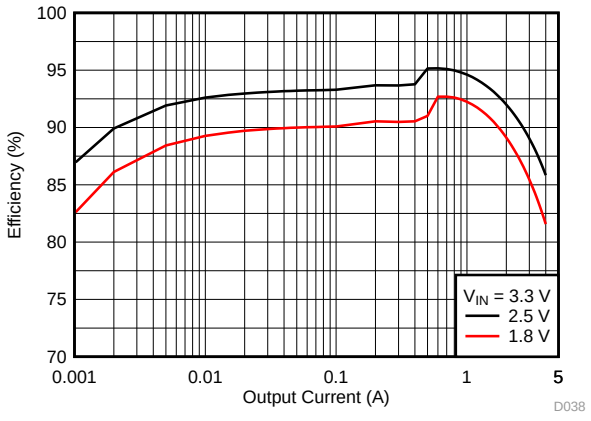
型番	デフォルト出力電圧	
LP8758-E0	V_{OUT0}	1000 mV
	V_{OUT1}	2500 mV
	V_{OUT2}	1200 mV
	V_{OUT3}	1800 mV

(1) 利用可能なすべてのパッケージについては、このデータシートの末尾にある注文情報を参照してください。

概略回路図



効率と出力電流との関係



V_{OUT}設定 = 1.8Vおよび2.5V

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4 改訂履歴

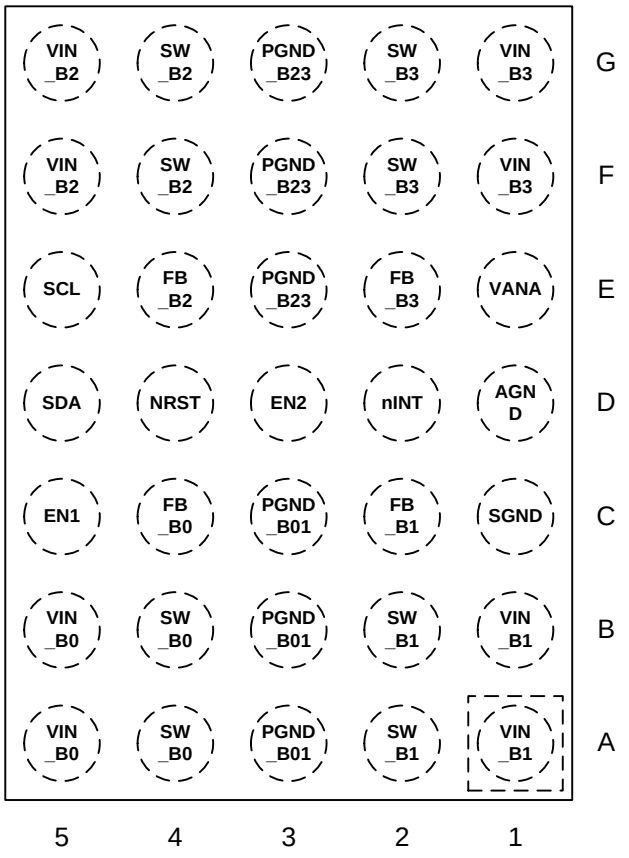
資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Revision A (January 2016) から **Revision B** に変更 **Page**

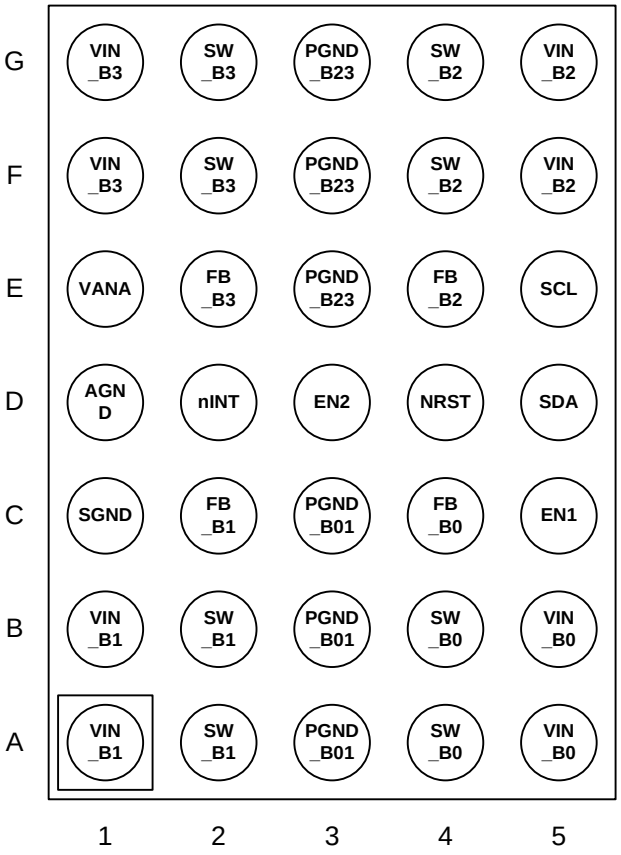
- Changed NRST MIN value from "1.65 V" to "0 V"; and NRST and ENx, SDA, SCL, nINT MAX values in *Recommended Operating Conditions* from "1.95 V" to "3.3 V", changed back to 1.65 V and separated I2C max bus speed only for 1.8 V ... 5

5 Pin Configuration and Functions

YFF Package
35-Pin DSBGA
Top View



YFF Package
35-Pin DSBGA
Bottom View



Pin Functions

PIN		TYPE	DESCRIPTION
NUMBER	NAME		
A1, B1	VIN_B1	P	Input for Buck1. The separate power pins VIN_Bx are not connected together internally – VIN_Bx pins must be connected together in the application and be locally bypassed.
A2, B2	SW_B1	A	Buck1 switch node.
A3, B3, C3	PGND_B01	G	Power Ground for Buck0 and Buck1.
A4, B4	SW_B0	A	Buck0 switch node.
A5, B5	VIN_B0	P	Input for Buck0. The separate power pins VIN_Bx are not connected together internally – VIN_Bx pins must be connected together in the application and be locally bypassed.
C1	SGND	G	Substrate Ground.
C2	FB_B1	A	Output voltage feedback for Buck1.
C4	FB_B0	A	Output voltage feedback for Buck0.
C5	EN1	D/I	Programmable Enable signal for Buck converter core(s). Can be also configured to switch between two output voltage levels.
D1	AGND	G	Ground.
D2	nINT	D/O	Open-drain interrupt output. Active LOW.
D3	EN2	D/I	Programmable Enable signal for Buck converter core(s). Can be also configured to switch between two output voltage levels.
D4	NRST	D/I	Reset signal for the device. Can be also used to enable the regulator.
D5	SDA	D/I/O	Serial interface data input and output for system access. Connect a pullup resistor.
E1	VANA	P	Supply voltage for Analog and Digital blocks.
E2	FB_B3	A	Output voltage feedback for Buck3.
E4	FB_B2	A	Output voltage feedback for Buck2.
E5	SCL	D/I	Serial interface clock input for system access. Connect a pullup resistor.
F1, G1	VIN_B3	P	Input for Buck3. The separate power pins VIN_Bx are not connected together internally – VIN_Bx pins must be connected together in the application and be locally bypassed.
F2, G2	SW_B3	A	Buck3 switch node.
E3, F3, G3	PGND_B23	G	Power Ground for Buck2 and Buck3.
F4, G4	SW_B2	A	Buck2 switch node.
F5, G5	VIN_B2	P	Input for Buck2. The separate power pins VIN_Bx are not connected together internally - VIN_Bx pins must be connected together in the application and be locally bypassed.
A: Analog Pin, D: Digital Pin, G: Ground Pin, P: Power Pin, I: Input Pin, O: Output Pin			

6 Specifications

6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)(1)(2)

		MIN	MAX	UNIT
INPUT VOLTAGE				
VIN_Bx, VANA	Voltage on power connections	–0.3	6	V
SW_Bx	Voltage on buck switch nodes	–0.3	(VIN_Bx + 0.3 V) with 6 V maximum	V
FB_Bx	Voltage on buck voltage sense nodes	–0.3	(VANA + 0.3 V) with 6 V maximum	V
NRST	Voltage on NRST input	–0.3	3.6	V
ENx, SDA, SCL, nINT	Voltage on logic pins (input or output pins)	–0.3	3.6	
CURRENT				
VIN_Bx, SW_Bx, PGND_Bx	Current on power pins (average current over 100k hour lifetime, T_J = 125°C)		0.62	A/pin
TEMPERATURE				
T_{J-MAX}	Junction temperature	−40	150	°C
Maximum lead temperature (soldering, 10 seconds)(3)			260	°C
T_{stg}	Storage temperature	–65	150	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) All voltage values are with respect to network ground.
(3) For detailed soldering specifications and information, please refer to *DSBGA Wafer Level Chip Scale Package*.

6.2 ESD Ratings

			VALUE	UNIT
$V_{(ESD)}$	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001(1)	±2000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101(2)	±500	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
INPUT VOLTAGE				
VIN_Bx, VANA	Voltage on power connections	2.5	5.5	V
NRST	Voltage on NRST	0	VANA with 3.6 V maximum	V
ENx, nINT	Voltage on logic pins (input or output pins)	0	VANA with 3.6 V maximum	V
SCL, SDA	Voltage on I^2C interface, standard (100 kHz), fast (400 khz), fast+ (1 MHz), and high-speed (3.4 MHz) modes	0	1.95	V
	Voltage on I^2C interface, standard (100 kHz), fast (400 kHz), and fast+ (1 MHz) modes	0	VANA with 3.6 V maximum	V
TEMPERATURE				
T_J	Junction temperature	–40	125	°C
T_A	Ambient temperature	–40	85	°C

6.4 Thermal Information

THERMAL METRIC(1)		LP8758 YFF (DSBGA) 35 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	56.1	°C/W
$R_{\theta JCtop}$	Junction-to-case (top) thermal resistance	0.2	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	8.5	°C/W
ψ_{JT}	Junction-to-top characterization parameter	0.9	°C/W
ψ_{JB}	Junction-to-board characterization parameter	8.4	°C/W
$R_{\theta JCbot}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report.

6.5 Electrical Characteristics

Limits apply over the junction temperature range –40°C ≤ T_J ≤ +125°C, specified $V_{(VANA)}$, V_{IN} , $V_{(NRST)}$, V_{OUT} and I_{OUT} range, unless otherwise noted. Typical values are at T_J = 25°C, f_{SW} = 3 MHz, $V_{(VANA)}$ = V_{IN} = 3.7 V and V_{OUT} = 1 V, unless otherwise noted.(1)(2)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
EXTERNAL COMPONENTS						
C_{IN}	Input filtering capacitance	Connected from VIN_Bx to PGND_Bx	1.9	10		µF
C_{OUT}	Output filtering capacitance, local	Capacitance per output voltage rail	10	22		µF
$C_{OUT-TOTAL}$	Output capacitance, total (local and remote)	Total output capacitance			50	µF
ESR_C	Input and output capacitor ESR	[1-10] MHz		2	10	mΩ
L	Inductor	Inductance of the inductor		0.47		µH
			–30%		30%	
DCR_L	Inductor DCR	TDK, VLS252010HBX-R47M		29		mΩ
BUCK REGULATORS						
V_{IN}	Input voltage range	Voltage between VIN_Bx and ground terminals. VANA must be connected to the same supply as VIN_Bx.	2.5	3.7	5.5	V
V_{OUT}	Output voltage	Programmable voltage range	0.5	1	3.36	V
		Step size, 0.5 V ≤ V_{OUT} < 0.73 V		10		mV
		Step size, 0.73 V ≤ V_{OUT} < 1.4 V		5		
		Step size, 1.4 V ≤ V_{OUT} ≤ 3.36 V		20		
I_{OUT}	Output current	Output current, V_{IN} ≤ 3 V			3(3)	A
		Output current, V_{IN} > 3 V, V_{OUT} ≤ 2 V			4(3)	
		Output current, V_{IN} > 3 V, V_{OUT} > 2 V			3.5(3)	
	Dropout voltage	V_{IN} – V_{OUT}	0.7			V
	DC output voltage accuracy, includes voltage reference, DC load and line regulations, process and temperature	Force PWM mode	min (–2%, –20 mV)		max (2%, 20 mV)	
		PFM mode, the average output voltage level is increased by max. 20 mV	min (–2%, –20 mV)		max (2%, 20 mV) + 20 mV	
	Ripple	PWM mode, L = 0.47 µH		10		mV_{p-p}
		PFM mode, L = 0.47 µH		20		
DC_{LNR}	DC line regulation	I_{OUT} = 1 A		±0.05		%/V

(1) All voltage values are with respect to network ground.
(2) Minimum (MIN) and maximum (MAX) limits are specified by design, test, or statistical analysis. Typical (TYP) numbers are not verified, but do represent the most likely norm.
(3) The maximum output current can be limited by the forward current limit, $I_{LIM\ FWD}$. The maximum output current is available with 5-A forward current limit setting.

Electrical Characteristics (continued)

Limits apply over the junction temperature range –40°C ≤ T_J ≤ +125°C, specified $V_{(VANA)}$, V_{IN} , $V_{(NRST)}$, V_{OUT} and I_{OUT} range, unless otherwise noted. Typical values are at T_J = 25°C, f_{SW} = 3 MHz, $V_{(VANA)}$ = V_{IN} = 3.7 V and V_{OUT} = 1 V, unless otherwise noted.(1)(2)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
DC_{LDR}	DC load regulation in PWM mode	I_{OUT} from 0 to $I_{OUT(max)}$		0.3%		
T_{LDSR}	Transient load step response	I_{OUT} = 0 A to 2 A, T_R = T_F = 400 ns, PWM mode, C_{OUT} = 44 µF, L = 0.47 µH		±55		mV
T_{LNSR}	Transient line response	V_{IN} stepping 3.3 V ↔ 3.8 V, T_R = T_F = 10 µs, I_{OUT} = $I_{OUT(max)}$		±15		mV
$I_{LIM\ FWD}$	Forward current limit (peak for every switching cycle), per phase	Programmable range	2.5		5	A
		Step size		0.5		
		Accuracy, 3 V ≤ V_{IN} ≤ 5.5 V, $I_{LIM\ FWD}$ = 5 A	-5%	7.5%	20%	
		Accuracy, 2.5 V ≤ V_{IN} ≤ 3 V, $I_{LIM\ FWD}$ = 5 A	-20%	7.5%	20%	
$I_{LIM\ NEG}$	Negative current limit		1.6	2	2.4	A
$R_{DS(ON)\ HS\ FET}$	On-resistance, high-side FET	Between VIN_Bx and SW_Bx pins (I = 1 A)		40	90	mΩ
$R_{DS(ON)\ LS\ FET}$	On-resistance, low-side FET	Between SW_Bx and PGND_Bx pins (I = 1 A)		33	50	mΩ
	Overshoot during start-up	Slew-rate = 10 mV/µs		< 50		mV
$I_{PFM-PWM}$	PFM-to-PWM switch - current threshold(4)			600		mA
$I_{PWM-PFM}$	PWM-to-PFM switch - current threshold(4)			240		mA
	Output pulldown resistance	Regulator disabled	150	250	350	Ω
	Powergood threshold for interrupt BUCKx_INT(BUCKx_SC_INT), difference from final voltage	Rising ramp voltage, enable or voltage change	–23	–17	–10	mV
		Falling ramp, voltage change	10	17	23	
	Powergood threshold for status signal BUCKx_STAT(BUCKx_PG_STAT)	During operation, status signal is forced to 0 during voltage change	–23	–17	–10	mV
PROTECTION FEATURES						
	Thermal warning	Temperature rising, CONFIG(TDIE_WARN_LEVEL) = 0		125		°C
		Temperature rising, CONFIG(TDIE_WARN_LEVEL) = 1		105		
		Hysteresis		15		
	Thermal shutdown	Temperature rising		150		°C
		Hysteresis		15		
$VANA_{UVLO}$	VANA undervoltage lockout	Voltage falling	2.3	2.4	2.5	V
		Hysteresis		50		mV
LOAD CURRENT MEASUREMENT						
	Current measurement range	Maximum code		20.46		A
	Resolution	LSB		20		mA
	Measurement accuracy	I_{OUT} ≥ 1 A		< 10%		
CURRENT CONSUMPTION						
	Shutdown current consumption	$V_{(NRST)}$ = 0 V		1		µA

(4) The final PFM-to-PWM and PWM-to-PFM switchover current varies slightly and is dependant on the output voltage, input voltage and the magnitude of inductor's ripple current.

Electrical Characteristics (continued)

Limits apply over the junction temperature range –40°C ≤ T_J ≤ +125°C, specified $V_{(VANA)}$, V_{IN} , $V_{(NRST)}$, V_{OUT} and I_{OUT} range, unless otherwise noted. Typical values are at T_J = 25°C, f_{SW} = 3 MHz, $V_{(VANA)}$ = V_{IN} = 3.7 V and V_{OUT} = 1 V, unless otherwise noted.(1)(2)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Standby current consumption, converter cores disabled	$V_{(NRST)}$ = 1.8 V		6		µA
	Active current consumption during PFM operation, one converter core enabled	$V_{(NRST)}$ = 1.8 V, I_{OUT} = 0 mA, not switching		55		µA
	Active current consumption during PWM operation, per converter core	$V_{(NRST)}$ = 1.8 V, I_{OUT} = 0 mA, L = 0.47 µH		14.5		mA
DIGITAL INPUT SIGNALS NRST, ENx, SCL, SDA						
V_{IL}	Input low level				0.4	V
V_{IH}	Input high level		1.2			V
V_{HYS}	Hysteresis of Schmitt trigger inputs (SCL, SDA)		10	80	160	mV
	ENx pulldown resistance	ENx_PD = 1	350	500	720	kΩ
	NRST pulldown resistance	Always present	800	1200	1700	kΩ
DIGITAL OUTPUT SIGNALS nINT, SDA						
V_{OL}	Output low level	I_{SOURCE} = 2 mA,			0.4	V
R_P	External pullup resistor for nINT	To VIO Supply		10		kΩ
ALL DIGITAL INPUTS						
I_{LEAK}	Input current	All logic inputs over pin voltage range	−1		1	µA

6.6 I²C Serial Bus Timing Requirements

See(1)(2)

			MIN	MAX	UNIT
f_{SCL}	Serial clock frequency	Standard mode		100	kHz
		Fast mode		400	kHz
		Fast mode +		1	MHz
		High-speed mode, C_b = 100 pF		3.4	MHz
		High-speed mode, C_b = 400 pF		1.7	MHz
t_{LOW}	SCL low time	Standard mode	4.7		µs
		Fast mode	1.3		
		Fast mode +	0.5		
		High-speed mode, C_b = 100 pF	160		ns
		High-speed mode, C_b = 400 pF	320		
t_{HIGH}	SCL high time	Standard mode	4		µs
		Fast mode	0.6		
		Fast mode +	0.26		
		High-speed mode, C_b = 100 pF	60		ns
		High-speed mode, C_b = 400 pF	120		
$t_{SU;DAT}$	Data setup time	Standard mode	250		ns
		Fast mode	100		
		Fast mode +	50		
		High-speed mode	10		

(1) See Figure 1 for timing diagram.
(2) C_b refers to the capacitance of one bus line. C_b is expressed in pF units.

I²C Serial Bus Timing Requirements (continued)

See(1)(2)

			MIN	MAX	UNIT
$t_{HD;DAT}$	Data hold time	Standard mode	0	3.45	µs
		Fast mode	0	0.9	
		Fast mode +	0		
		High-speed mode, C_b = 100 pF	0	70	ns
		High-speed mode, C_b = 400 pF	0	150	
$t_{SU;STA}$	Setup time for a start or a repeated start condition	Standard mode	4.7		µs
		Fast mode	0.6		
		Fast mode +	0.26		
		High-speed mode	160		ns
$t_{HD;STA}$	Hold time for a start or a repeated start condition	Standard mode	4		µs
		Fast mode	0.6		
		Fast mode +	0.26		
		High-speed mode	160		ns
t_{BUF}	Bus free time between a stop and start condition	Standard mode	4.7		µs
		Fast mode	1.3		
		Fast mode +	0.5		
$t_{SU;STO}$	Setup time for a stop condition	Standard mode	4		µs
		Fast mode	0.6		
		Fast mode +	0.26		
		High-speed mode	160		ns
t_{rDA}	Rise time of SDA signal	Standard mode		1000	ns
		Fast mode		300	
		Fast mode +		120	
		High-speed mode, C_b = 100 pF		80	
		High-speed mode, C_b = 400 pF		160	
t_{fDA}	Fall time of SDA signal	Standard mode		250	ns
		Fast mode		250	
		Fast mode +		120	
		High-speed mode, C_b = 100 pF		80	
		High-speed mode, C_b = 400 pF		160	
t_{rCL}	Rise time of SCL signal	Standard mode		1000	ns
		Fast mode		300	
		Fast mode +		120	
		High-speed Mode, C_b = 100 pF		40	
		High-speed Mode, C_b = 400 pF		80	
t_{rCL1}	Rise time of SCL signal after a repeated start condition and after an acknowledge bit	Standard mode		1000	ns
		Fast mode		300	
		Fast mode +		120	
		High-speed mode, C_b = 100 pF		80	
		High-speed mode, C_b = 400 pF		160	
t_{fCL}	Fall time of a SCL signal	Standard mode		300	ns
		Fast mode		300	
		Fast mode +		120	
		High-speed mode, C_b = 100 pF		40	
		High-speed mode, C_b = 400 pF		80	

I²C Serial Bus Timing Requirements (continued)

See(1)(2)

			MIN	MAX	UNIT
C_b	Capacitive load for each bus line (SCL and SDA)			400	pF
t_{SP}	Pulse width of spike suppressed in SCL and SDA lines (spikes that are less than the indicated width are suppressed)	Fast mode, fast mode +		50	ns
		High-speed mode		10	

6.7 Switching Characteristics

Limits apply over the junction temperature range –40°C ≤ T_J ≤ +125°C, specified $V_{(VANA)}$, V_{IN} , $V_{(NRST)}$, V_{OUT} and I_{OUT} range, unless otherwise noted. Typical values are at T_J = 25°C, f_{SW} = 3 MHz, $V_{(VANA)}$ = V_{IN} = 3.7 V and V_{OUT} = 1 V, unless otherwise noted.(1)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
f_{SW}	Switching frequency, PWM mode	V_{OUT} ≥ 0.6 V	2.7	3	3.3	MHz
		V_{OUT} < 0.6 V	1.8	2	2.2	
	Start-up time (soft start)	From ENx to V_{OUT} = 0.225 V (slew-rate control begins), $C_{OUT-TOTAL}$ = 44 µF, no load		110		µs
	Output voltage slew-rate(2)	SLEW_RATEx[2:0] = 000, V_{OUT} ≥ 0.5 V	–15%	30	15%	mV/µs
		SLEW_RATEx[2:0] = 001, V_{OUT} ≥ 0.5 V	–15%	15	15%	
		SLEW_RATEx[2:0] = 010, V_{OUT} ≥ 0.5 V	–15%	10	15%	
		SLEW_RATEx[2:0] = 011, V_{OUT} ≥ 0.5 V	–15%	7.5	15%	
		SLEW_RATEx[2:0] = 100, V_{OUT} ≥ 0.5 V	–15%	3.8	15%	
		SLEW_RATEx[2:0] = 101, V_{OUT} ≥ 0.5 V	–15%	1.9	15%	
		SLEW_RATEx[2:0] = 110, V_{OUT} ≥ 0.5 V	–15%	0.94	15%	
		SLEW_RATEx[2:0] = 111, V_{OUT} ≥ 0.5 V	–15%	0.4	15%	
	Load current measurement time	PFM mode (automatically changing to PWM mode for the measurement)		50		µs
		PWM mode		4		

(1) Minimum (MIN) and maximum (MAX) limits are specified by design, test, or statistical analysis. Typical (TYP) numbers are not verified, but do represent the most likely norm.
(2) Specified by design without testing. The slew-rate can be limited by the current limit (forward or negative current limit), output capacitance, and load current.

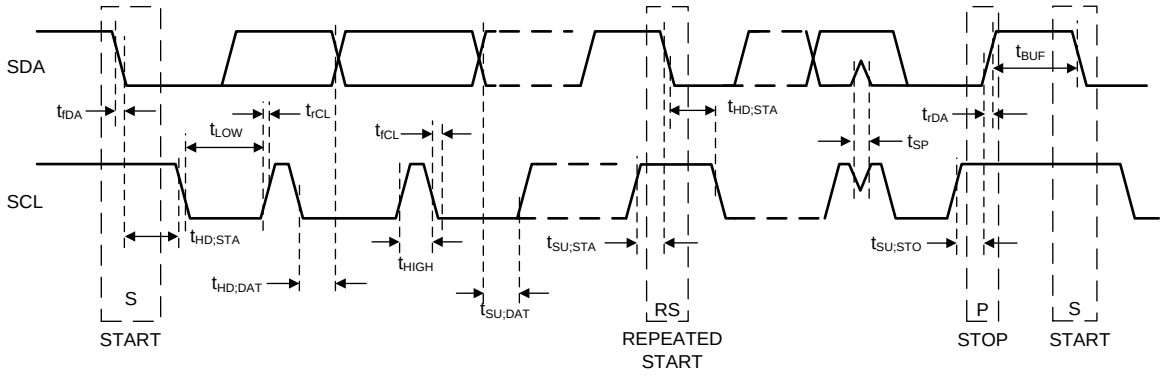
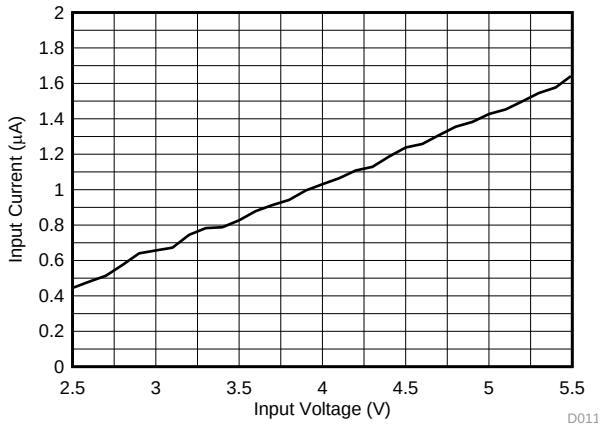


Figure 1. I²C Timing

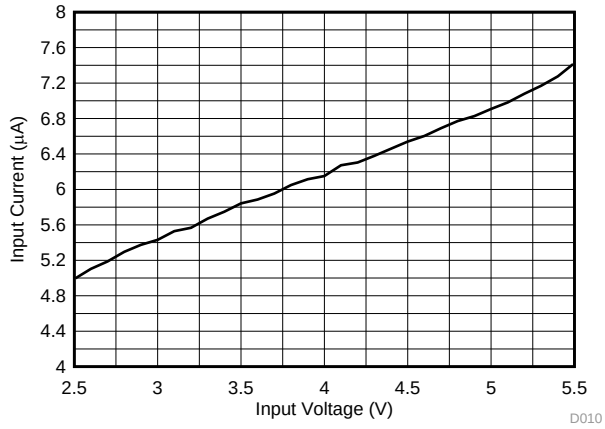
6.8 Typical Characteristics

Unless otherwise specified: T_A = 25°C, V_{IN} = 3.7 V, f_{SW} = 3 MHz, L = 470 nH



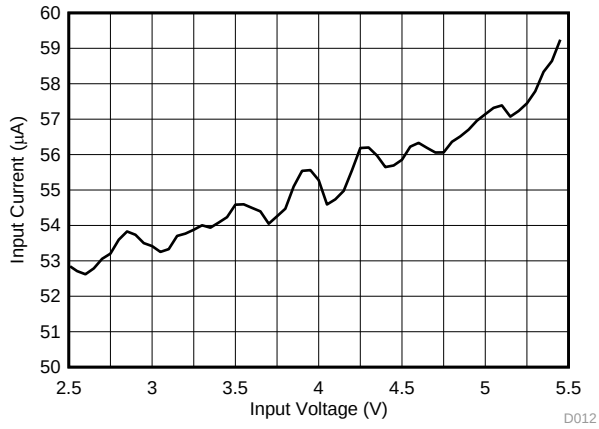
$V_{(NRST)}$ = 0 V

Figure 2. Shutdown Current Consumption vs Input Voltage



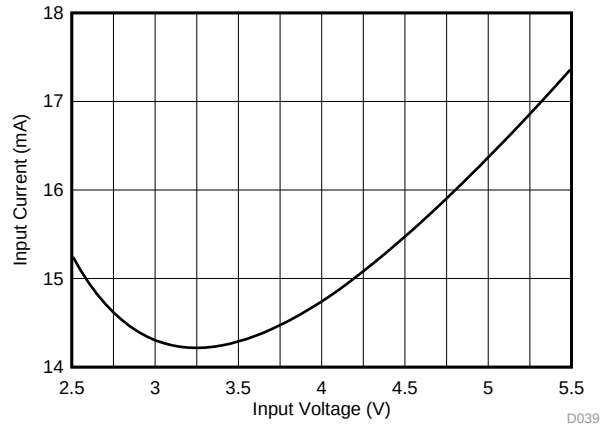
$V_{(NRST)}$ = 1.8 V All converter cores disabled

Figure 3. Standby Current Consumption vs Input Voltage



$V_{(NRST)}$ = 1.8 V Load = 0 mA V_{OUT} setting = 1000 mV

Figure 4. PFM Mode Current Consumption vs Input Voltage —One Output Enabled



$V_{(NRST)}$ = 1.8 V Load = 0 mA V_{OUT} setting = 1000 mV

Figure 5. PWM Mode Current Consumption vs Input Voltage — One Output Enable

7 Detailed Description

7.1 Overview

The LP8758-xx devices are a family of configurable step-down DC-DC converters with four converter cores. The LP8758-xx devices are ideally suited for systems powered from 2.5-V to 5.5-V supply voltage. In LP8758-E0 the cores are configured for a four single-phase configuration. The LP8758-E0 is well suited for space-constrained applications where high efficiency is required at low output voltages. Typical applications include network interface cards, modem cards, smart phones and mobile devices, solid-state drives (SSDs), systems-on-a-chip (SoCs), ASICs, and low power processors.

There are two modes of operation for the converter cores, depending on the output current required: pulse-width modulation (PWM) and pulse-frequency modulation (PFM). The cores operate in PWM mode at high load currents of approximately 400 mA or higher. Lighter output current loads cause the converter cores to automatically switch into PFM mode for reduced current consumption and a longer battery life when forced PWM mode is disabled. Additional features include soft-start, undervoltage lockout, overload protection, thermal warning, and thermal shutdown.

7.1.1 Buck Information

The LP8758-E0 has four integrated high-efficiency buck converter cores. The cores are designed for flexibility; most of the functions are programmable, thus giving a possibility to optimize the regulator operation for each application.

7.1.1.1 Operating Modes

- OFF: Output is isolated from the input voltage rail in this mode. Output has an optional pulldown resistor.
- PWM: Converter operates in buck configuration with fixed switching frequency.
- PFM: Converter switches only when output voltage decreases below programmed threshold. Inductor current is discontinuous.

7.1.1.2 Programmability

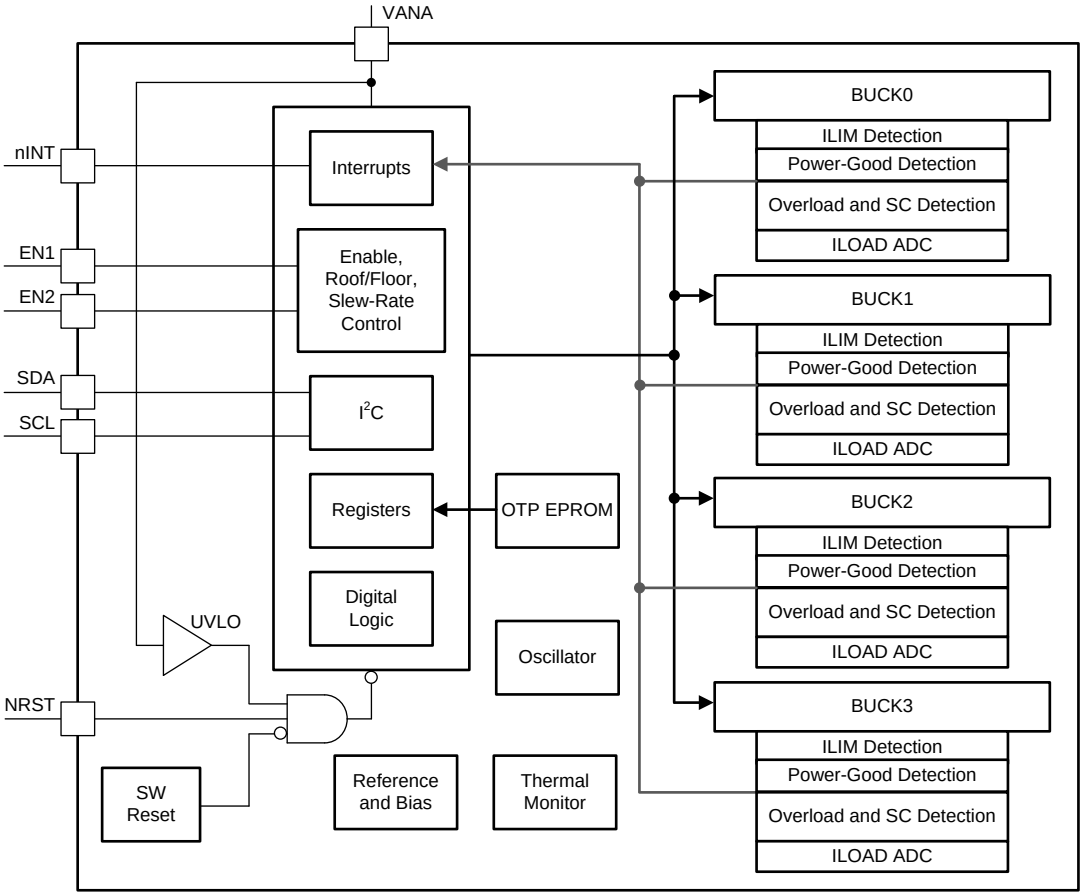
The following parameters can be programmed via registers:

- Output voltage
- Forced PWM operation
- Switch current limit
- Output voltage slew rate
- Enable and disable delays

7.1.1.3 Features

- Dynamic voltage scaling (DVS) support with programmable slew-rate
- Automatic mode control based on the loading
- Synchronous rectification
- Current mode loop with PI compensator
- Optional spread spectrum technique to reduce EMI
- Soft start
- Power-good flag with maskable interrupt
- Phase control for optimized EMI: The four cores operate 90° out of phase thereby reducing input ripple current
- Average output current sensing (for PFM entry and load current measurement)
- Voltage sensing from point of the load

7.2 Functional Block Diagram



7.3 Feature Description

7.3.1 Overview

A block diagram of a single core is shown in Figure 6.

Interleaving switching action of the converters is illustrated in Figure 7. The LP8758-E0 regulator switches each core 90° apart, reducing input ripple current.

Feature Description (continued)

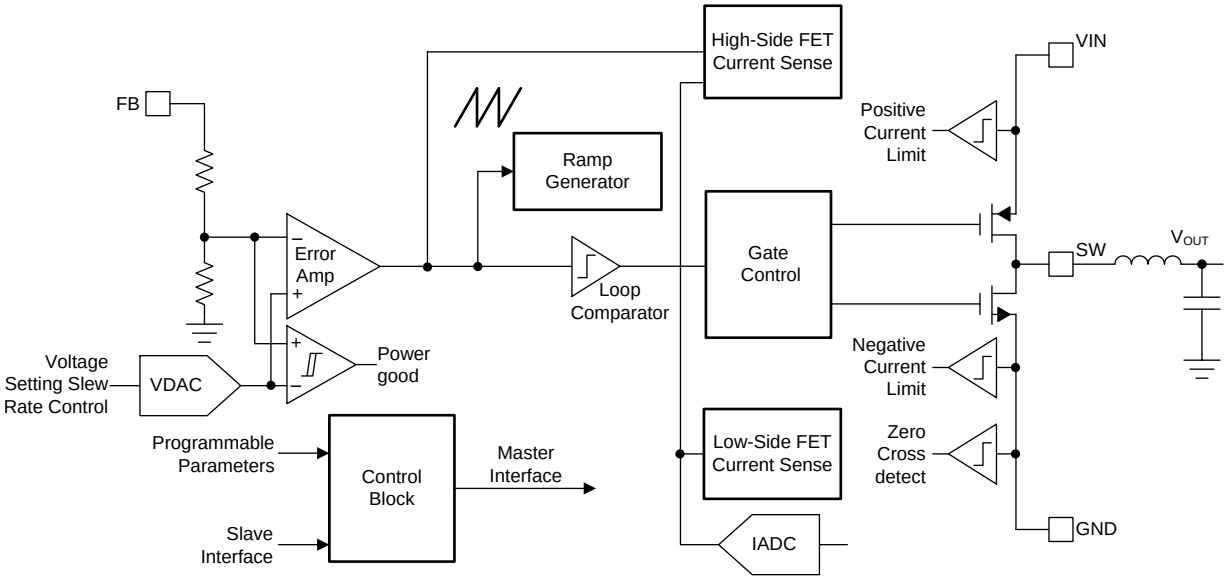


Figure 6. Detailed Block Diagram Showing One Core

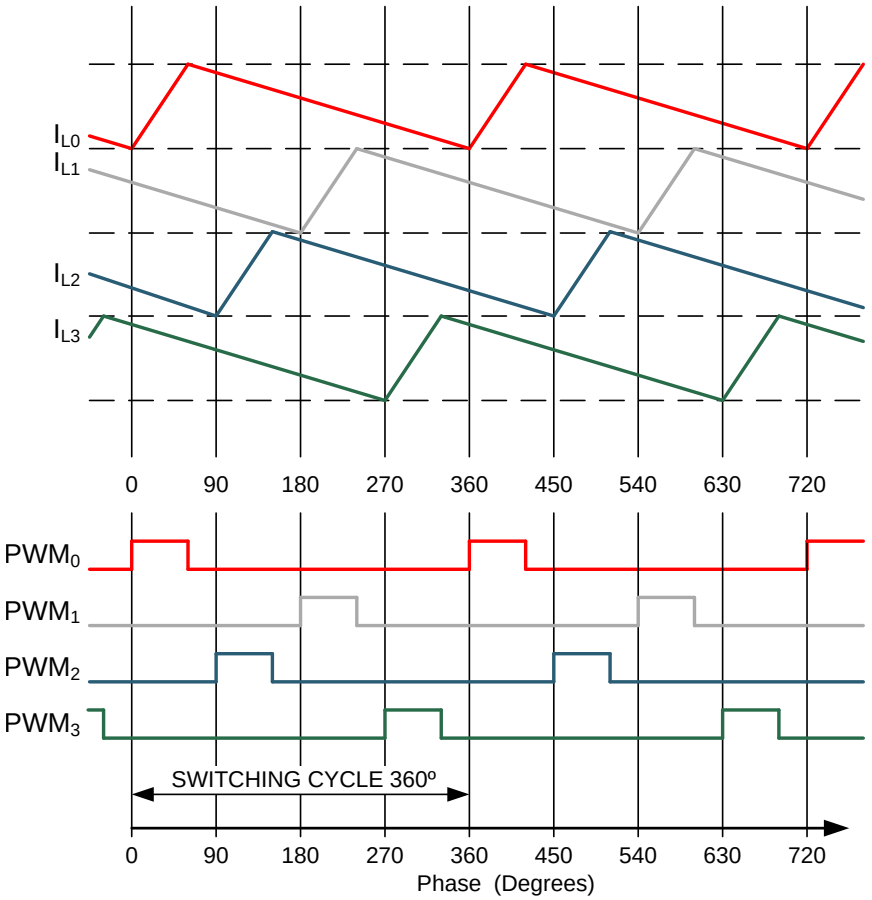


Figure 7. PWM Timings and Inductor Current Waveforms (1)

(1) Graph is not in scale and is for illustrative purposes only.

Feature Description (continued)

7.3.1.1 Transition between PWM and PFM Modes

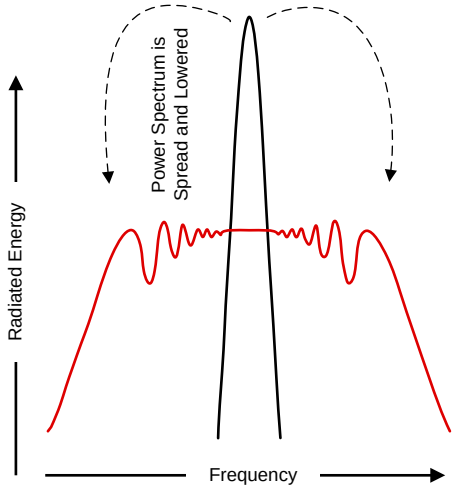
The LP8758-E0 converter cores operate in PWM mode at load current of about 400 mA or higher. At lighter load current levels the cores automatically switches into PFM mode for reduced current consumption when Forced PWM mode is disabled (AUTO mode operation). By combining the PFM and the PWM modes a high efficiency is achieved over a wide output-load current range.

7.3.1.2 Buck Converter Load Current Measurement

Buck load current can be monitored via I^2C registers. The monitored buck converter core is selected with the SEL_I_LOAD.LOAD_CURRENT_BUCK_SELECT[1:0] register bits. A write to this selection register starts a current measurement sequence. The measurement sequence is typically 50 µs long. The LP8758-E0 device can be configured to give out an interrupt INT_TOP.I_LOAD_READY after the load current measurement sequence is finished. Load current measurement interrupt can be masked with TOP_MASK.I_LOAD_READY_MASK bit. The measurement result can be read from registers I_LOAD_1 and I_LOAD_2. Register I_LOAD_1 bits BUCK_LOAD_CURRENT[7:0] give out the LSB bits and register I_LOAD_2 bits BUCK_LOAD_CURRENT[9:8] the MSB bits. The measurement result BUCK_LOAD_CURRENT[9:0] LSB is 20 mA, and maximum value of the measurement is 20.46 A.

7.3.1.3 Spread-Spectrum Mode

Systems with periodic switching signals may generate a large amount of switching noise in a set of narrowband frequencies (the switching frequency and its harmonics). The usual solution to reduce noise coupling is to add EMI-filters and shields to the boards. The register-selectable spread-spectrum mode of the device minimizes the need for output filters, ferrite beads, or chokes. In spread-spectrum mode, the switching frequency varies randomly by ±5% about the center frequency, reducing the EMI emissions radiated by the converter and associated passive components and PCB traces (see Figure 8). This feature is enabled with the CONFIG.EN_SPREAD_SPEC bit, and it affects all the buck converter cores.



Where a fixed frequency converter exhibits large amounts of spectral energy at the switching frequency, the spread spectrum architecture of the v spreads that energy over a large bandwidth.

Figure 8. Spread-Spectrum Modulation

7.3.2 Power-Up

The power-up sequence for the LP8758-E0 is as follows:

- VANA (and VIN_Bx) reach minimum recommended levels ($V_{(VANA)}$ > $VANA_{UVLO}$).
- NRST is set to high level. This initiates power-on-reset (POR), OTP reading and enables the system I/O interface. The I^2C host must allow at least 1.2 ms before writing or reading data to the LP8758-E0.
- The device enters STANDBY mode.
- The host can change the default register setting by I^2C if needed.

Feature Description (continued)

- The converter core(s) can be enabled/disabled by ENx pin(s) and by I^2C interface.

7.3.3 Regulator Control

7.3.3.1 Enabling and Disabling

The buck converter cores can be enabled when the device is in STANDBY or ACTIVE state. There are two ways for enable and disable the buck converter core cores:

- Using BUCKx_CTRL1.EN_BUCKx register bit (when BUCKx_CTRL1.EN_PIN_CTRLx register bit is 0).
- Using EN1/2 control pins (BUCKx_CTRL1.EN_BUCKx register bit is 1 *and* BUCKx_CTRL1.EN_PIN_CTRLx register bit is 1).

If the EN1/2 control pins are used for enable and disable, the delay from the control signal rising edge to start-up is set by BUCKx_DELAY.BUCKx_STARTUP_DELAY[3:0] bits and the delay from control signal falling edge to shutdown is set by BUCKx_DELAY.BUCKx_SHUTDOWN_DELAY[3:0] bits. The delays are valid only for EN1/2 signal and not for control with BUCKx_CTRL1.EN_BUCKx bit. The delay time implemented by EN1/2 has overall +/-10% timing accuracy.

The control of the converter cores (with 0 ms delays) is shown in Table 2.

Table 2. Regulator Control

CONTROL METHOD	ROW	EN_BUCKx	BUCKx_CTRL1 EN_PIN_CTRLx	BUCKx_CTRL1 EN_PIN_SELECTx	BUCKx_CTRL1 EN_ROOF_FLOORx	EN1 PIN	EN2 PIN	BUCKx OUTPUT VOLTAGE
Enable/disable control with EN_BUCKx bit	1	0	Don't Care	Don't Care	Don't Care	Don't Care	Don't Care	Disabled
	2	1	0	Don't Care	Don't Care	Don't Care	Don't Care	BUCKx_VOUT.BUCKx_VSET[7:0]
Enable/disable control with EN1 pin	3	1	1	0	0	Low	Don't Care	Disabled
	4	1	1	0	0	High	Don't Care	BUCKx_VOUT.BUCKx_VSET[7:0]
Enable/disable control with EN2 pin	5	1	1	1	0	Don't Care	Low	Disabled
	6	1	1	1	0	Don't Care	High	BUCKx_VOUT.BUCKx_VSET[7:0]
Roof/floor control with EN1 pin	7	1	1	0	1	Low	Don't Care	BUCKx_FLOOR_VOUT.BUCKx_FLOOR_VSET[7:0]
	8	1	1	0	1	High	Don't Care	BUCKx_VOUT.BUCKx_VSET[7:0]
Roof/floor control with EN2 pin	9	1	1	1	1	Don't Care	Low	BUCKx_FLOOR_VOUT.BUCKx_FLOOR_VSET[7:0]
	10	1	1	1	1	Don't Care	High	BUCKx_VOUT.BUCKx_VSET[7:0]

The following configuration allows the enable/disable control using ENx pin:

- BUCKx_CTRL1.EN_BUCKx = 1
- BUCKx_CTRL1.EN_PIN_CTRLx = 1
- BUCKx_CTRL1.EN_ROOF_FLOORx = 0
- BUCKx_VOUT.BUCKx_VSET[7:0] = Required voltage when ENx is high
- The enable pin for control is selected with BUCKx_CTRL1.EN_PIN_SELECTx

When the ENx pin is low, Table 2 row 3 (or 5) is valid, and the converter core is disabled. By setting ENx pin high, Table 2 row 4 (or 6) is valid, and the converter core is enabled with required voltage.

If a converter core is enabled all the time, and the ENx pin controls selection between two voltage level, the following configuration is used:

- BUCKx_CTRL1.EN_BUCKx = 1
- BUCKx_CTRL1.EN_PIN_CTRLx = 1
- BUCKx_CTRL1.EN_ROOF_FLOORx = 1
- BUCKx_VOUT.BUCKx_VSET[7:0] = Required voltage when ENx is high
- The enable pin for control is selected with BUCKx_CTRL1.EN_PIN_SELECTx

When the ENx pin is low, Table 2 row 7 (or 9) is valid, and the core is enabled with a voltage defined by BUCKx_FLOOR_VOUT.BUCKx_FLOOR_VSET[7:0] bits. Setting the ENx pin high, Table 2 row 8 (or 10) is valid, and the core is enabled with a voltage defined by BUCKx_VOUT.BUCKx_VSET[7:0] bits.

If the core is controlled by I^{2}C writings, the BUCKx_CTRL1.EN_PIN_CTRLx bit is set to 0. The enable/disable is controlled by the BUCKx_CTRL1.EN_BUCKx bit, and when the regulator is enabled, the output voltage is defined by the BUCKx_VOUT.BUCKx_VSET[7:0] bits. The Table 2 rows 1 and 2 are valid for I^{2}C controlled operation (ENx pins are ignored).

The buck converter core is enabled by the ENx pin or by I^{2}C writing as shown in Figure 9. The soft-start circuit limits the in-rush current during start-up. Output voltage increase rate is around 5 mV/µsec during soft-start. When the output voltage rises to approximately 0.3 V, the output voltage becomes slew-rate controlled. If there is a short circuit at the output, and the output voltage does not increase above a 0.35-V level in 1 ms, the converter core is disabled, and interrupt is set. When the output voltage reaches the powergood threshold level the INT_BUCK_x.BUCKx_PG_INT interrupt flag is set. The powergood interrupt flag can be masked using BUCK_x_MASK.BUCKx_PG_MASK bit.

The ENx input pins have integrated pull-down resistors. The pull-down resistors are enabled by default and host can disable those with CONFIG.ENx_PD bits.

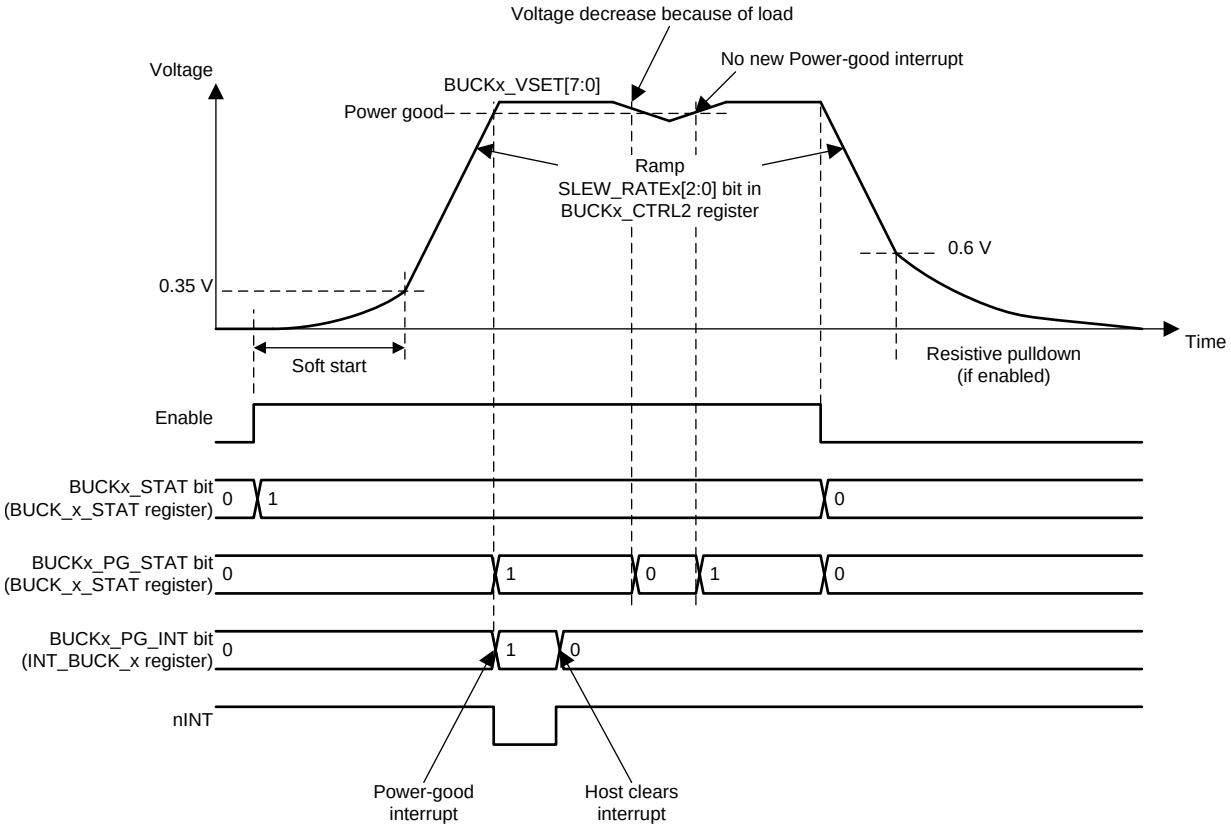


Figure 9. Converter Core Enable and Disable

7.3.3.2 Changing Output Voltage

The converter core's output voltage can be changed by the ENx pin (voltage levels defined by the BUCKx_VOUT and BUCKx_FLOOR_VOUT registers) or by writing to the BUCKx_VOUT and BUCKx_FLOOR_VOUT registers. The voltage change is always slew-rate controlled, and the slew-rate is defined by the BUCKx_CTRL2.SLEW_RATEx[2:0] bits. During voltage change the Forced PWM mode is used automatically. When the programmed output voltage is achieved, the mode becomes the one defined by load current, and the BUCKx_CTRL1.BUCKx_FPWM bit.

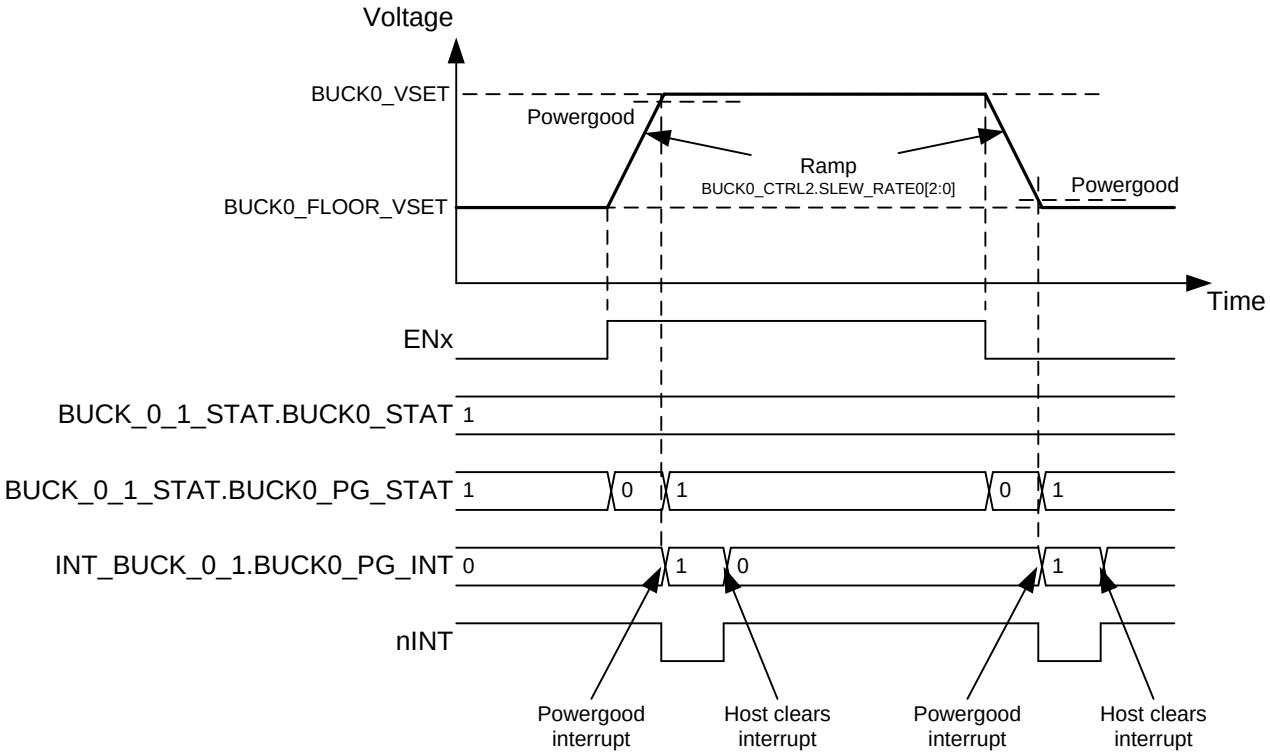


Figure 10. Output Voltage Change

7.3.4 Device Reset Scenarios

There are three reset methods implemented on the LP8758-E0:

- Software reset with RESET.SW_RESET register bit
- Reset from low logic level of NRST signal
- Undervoltage lockout (UVLO) reset from VANA supply

A SW-reset occurs when RESET.SW_RESET bit is written 1. The bit is automatically cleared after writing. This event disables all the buck converter cores immediately, resets all the register bits to the default values and OTP bits are loaded (see Figure 12). I^2C interface is not reset during software reset.

If VANA supply voltage falls below UVLO threshold level or NRST signal is set low, then all the converter cores are disabled immediately, and all the register bits are reset to the default values. When the VANA supply voltage is above UVLO threshold level and NRST signal rises above threshold level an internal power-on reset (POR) occurs. OTP bits are loaded to the registers, and a start-up is initiated according to the register settings.

7.3.5 Diagnosis and Protection Features

The LP8758-E0 is capable of providing three levels of protection features:

- Warnings for diagnosis which sets interrupt;
- Protection events which are disabling converter core(s); and
- Faults which are causing the device to shutdown.

When the device detects warning or protection condition(s), the LP8758-E0 sets the flag bits indicating what protection or warning conditions have occurred, and the nINT pin is pulled low. nINT is released again after a clear of flags is complete. The nINT signal stays low until all the pending interrupts are cleared.

When a fault is detected, it is indicated by a INT_TOP.RESET_REG interrupt flag after next start-up.

Table 3. Summary of Interrupt Signals

EVENT	RESULT	INTERRUPT REGISTER AND BIT	INTERRUPT MASK	STATUS BIT	RECOVERY / INTERRUPT CLEAR
Current limit triggered (20 µs debounce)	No effect	INT_TOP.INT_BUCKx = 1 INT_BUCKx.BUCKx_ILIM_INT = 1	BUCKx_MASK.BUCKx_ILIM_MASK	BUCKx_STAT.BUCKx_ILIM_STAT	Write 1 to INT_BUCKx.BUCKx_ILIM_INT bit Interrupt is not cleared if current limit is active
Short circuit (V_{OUT} < 0.35 V at 1 ms after enable) or Overload (V_{OUT} decreasing below 0.35V during operation, 1 ms debounce)	Converter core disable	INT_TOP.INT_BUCKx = 1 INT_BUCK_0_1.BUCKx_SC_INT = 1 or INT_BUCK_2_3.BUCKx_SC_INT = 1	N/A	N/A	Write 1 to INT_BUCK_0_1.BUCKx_SC_INT or to INT_BUCK_2_3.BUCKx_SC_INTbit
Thermal Warning	No effect	INT_TOP.TDIE_WARN = 1	TOP_MASK.TDIE_WARN_MASK	TOP_STAT.TDIE_WARN_STAT	Write 1 to INT_TOP.TDIE_WARN bit Interrupt is not cleared if temperature is above thermal warning level
Thermal Shutdown	All converter cores disabled	INT_TOP.TDIE_SD = 1	N/A	TOP_STAT.TDIE_SD_STAT	Write 1 to INT_TOP.TDIE_SD bit Interrupt is not cleared if temperature is above thermal shutdown level
Powergood, output voltage reaches the programmed value	No effect	INT_TOP.INT_BUCKx = 1 INT_BUCK_0_1.BUCKx_PG_INT = 1 or INT_BUCK_2_3.BUCKx_PG_INT = 1	BUCK_0_1_MASK.BUCKx_PG_MASK BUCK_2_3_MASK.BUCKx_PG_MASK	BUCK_0_1_STAT.BUCKx_PG_STAT BUCK_2_3_STAT.BUCKx_PG_STAT	Write 1 to INT_BUCK_0_1.BUCKx_PG_INT bit or to INT_BUCK_2_3.BUCKx_PG_INT bit
Load current measurement ready	No effect	INT_TOP.I_LOAD_READY = 1	TOP_MASK.I_LOAD_READY_MASK	N/A	Write 1 to INT_TOP.I_LOAD_READY bit
Start-up (NRST rising edge)	Device ready for operation, registers reset to default values	INT_TOP.RESET_REG = 1	TOP_MASK.RESET_REG_MASK	N/A	Write 1 to INT_TOP.RESET_REG bit
Glitch on supply voltage and UVLO triggered (VANA falling and rising)	Immediate shutdown followed by powerup, registers reset to default values	INT_TOP.RESET_REG = 1	TOP_MASK.RESET_REG_MASK	N/A	Write 1 to INT_TOP.RESET_REG bit
Software requested reset	Immediate shutdown followed by powerup, registers reset to default values	INT_TOP.RESET_REG = 1	TOP_MASK.RESET_REG_MASK	N/A	Write 1 to INT_TOP.RESET_REG bit

7.3.5.1 Warnings for Diagnosis (Interrupt)

7.3.5.1.1 Output Current Limit

The converter cores have programmable output peak current limits. The limits are individually programmed for all buck converter cores with BUCKx_CTRL2.ILIMx[2:0] bits. If the load current is increased so that the current limit is triggered, the regulator continues to regulate to the limit current level (current peak regulation). The voltage may decrease if the load current is higher than limit current. If the current regulation continues for 20 µs, the LP8758-E0 device sets the INT_BUCKx.BUCKx_ILIM_INT bit and pulls the nINT pin low. The host processor can read BUCKx_STAT.BUCKx_ILIM_STAT bits to see if the converter cores is still in peak current regulation mode.

For example, if the load on Buck0 output is so high that the output voltage V_{OUT} decreases below a 350-mV level, the LP8758-E0 device disables the converter core Buck0 and sets the INT_BUCK_0_1.BUCK0_SC_INT bit. In addition the BUCK_0_1_STAT.BUCK0_STAT bit is set to 0. The interrupt is cleared when the host processor writes 1 to INT_BUCK_0_1.BUCK0_SC_INT bit. The overload situation is shown in Figure 11.

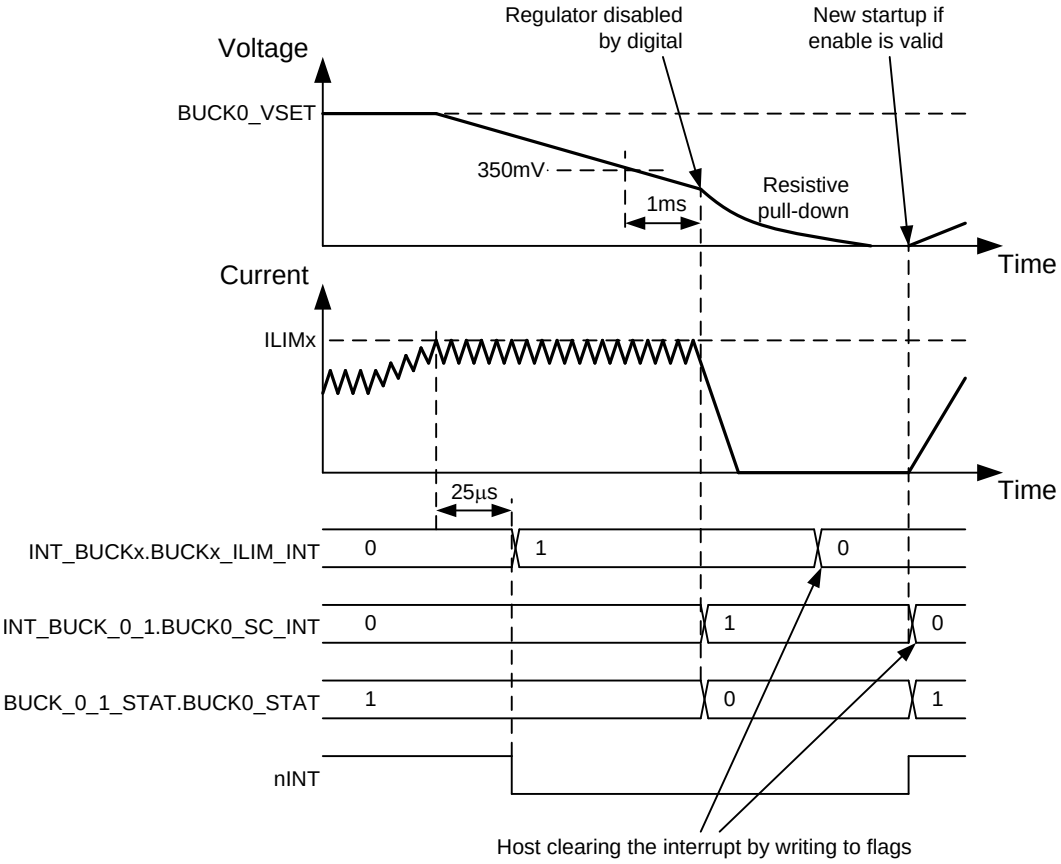


Figure 11. Overload Situation

7.3.5.1.2 Thermal Warning

The LP8758-E0 device includes protection features against overtemperature by setting an interrupt for host processor. The threshold level of the thermal warning is selected with CONFIG.TDIE_WARN_LEVEL bit.

If the LP8758-E0 device temperature increases above the thermal warning level, the device sets INT_TOP.TDIE_WARN bit and pulls nINT pin low. The status of the thermal warning can be read from TOP_STAT.TDIE_WARN_STAT bit, and the interrupt is cleared by writing 1 to INT_TOP.TDIE_WARN bit.

7.3.5.2 Protection (Regulator Disable)

If the regulator is disabled because of protection or fault (short-circuit protection, overload protection, thermal shutdown, or undervoltage lockout), the output power FETs are set to high-impedance mode, and the output pulldown resistor is enabled (if enabled with BUCKx_CTRL1.EN_RDISx bits). The turnoff time of the output voltage is defined by the output capacitance, load current, and the resistance of the integrated pulldown resistor.

7.3.5.2.1 Short-Circuit and Overload Protection

A short-circuit protection feature allows the LP8758-E0 to protect itself and external components against short circuit at the output or against overload during start-up. The fault threshold is 350 mV, and the protection is triggered and the converter core is disabled if the output voltage is still below the threshold level 1 ms after the converter core was enabled.

In a similar way the overload situation is protected during normal operation. If a feedback-pin voltage falls below 0.35 V, and remains below the threshold level for 1 ms, the respective converter core is disabled.

For example, if the Buck core 0 output is overloaded, the INT_BUCK_0_1.BUCK0_SC_INT and the INT_TOP.INT_BUCK0 bits are set to 1, the BUCK_0_1_STAT.BUCK0_STAT bit is set to 0 and the nINT signal is pulled low. The host processor clears the interrupt by writing 1 to the INT_BUCK_0_1.BUCK0_SC_INT bit. Upon clearing the interrupt the regulator makes a new start-up attempt if the enable register bits and/or ENx control signal is valid.

7.3.5.2.2 Thermal Shutdown

The LP8758-E0 has an over-temperature protection function that operates to protect itself from short-term misuse and overload conditions. When the junction temperature exceeds around 150°C, the cores are disabled, the INT_TOP.TDIE_SD bit is set to 1, the nINT signal is pulled low, and the device enters STANDBY. nINT is cleared by writing 1 to the INT_TOP.TDIE_SD bit. If the temperature is above thermal shutdown level the interrupt is not cleared. The host can read the status of the thermal shutdown from the TOP_STAT.TDIE_SD_STAT bit. Converter cores cannot be enabled as long as the junction temperature is above thermal shutdown level or the thermal shutdown interrupt is pending.

7.3.5.3 Fault (Power Down)

7.3.5.3.1 Undervoltage Lockout

When the input voltage falls below $VANA_{UVLO}$ at the VANA pin, the converter cores are disabled immediately, and the output capacitors are discharged using the pulldown resistors and the LP8758-E0 device enters SHUTDOWN. When VANA voltage is above UVLO threshold level and NRST signal is high, the device powers up to STANDBY state.

If the reset interrupt is unmasked by default (TOP_MASK.RESET_REG_MASK = 0) the INT_TOP.RESET_REG interrupt indicates that the device has been in SHUTDOWN. The host processor must clear the interrupt by writing 1 to the INT_TOP.RESET_REG bit. If the host processor reads the INT_TOP.RESET_REG flag after detecting an nINT low signal, it knows that the input supply voltage has been below UVLO level (or the host has requested reset), and the registers are reset to default values.

7.3.6 Digital Signal Filtering

The digital signals have debounce filtering. The signal/supply is sampled with a clock signal and a counter. This results as an accuracy of one clock period for the debounce window.

Table 4. Digital Signal Filtering

EVENT	SIGNAL / SUPPLY	RISING EDGE LENGTH	FALLING EDGE LENGTH
Enable/disable/voltage Select for BUCKx	ENx	3 µs(1)	3 µs(1)
VANA undervoltage lockout	VANA	Immediate	Immediate
Thermal warning	TDIE_WARN	20 µs	20 µs
Thermal shutdown	TDIE_SD	20 µs	20 µs
Current limit	VOUTx_ILIM	20 µs	20 µs
Overload	FB_B0, FB_B1, FB_B2, FB_F3	1 ms	1 ms
Power-good	FB_B0, FB_B1, FB_B2, FB_F3	20 µs	20 µs

(1) No glitch filtering, only synchronization.

7.4 Device Functional Modes

7.4.1 Modes of Operation

SHUTDOWN: The $V_{(NRST)}$ voltage is below threshold level. All switch, reference, control and bias circuitry of the LP8758-E0 device are turned off.

WAIT-ON: The $V_{(NRST)}$ voltage is above threshold level. The reference and bias circuitry are enabled. The converter cores of the LP8758-E0 device are turned off.

READ OTP: The main supply voltage $V_{(VANA)}$ is above $VANA_{UVLO}$ level and $V_{(NRST)}$ voltage is above threshold level. The converter cores are disabled and the reference and bias circuitry of the LP8758-E0 are enabled. The OTP bits are loaded to registers.

STANDBY: The main supply voltage $V_{(VANA)}$ is above $VANA_{UVLO}$ level and $V_{(NRST)}$ voltage is above threshold level. The converter cores are disabled and the reference, control and bias circuitry of the LP8758-E0 are enabled. All registers can be read or written by the host processor via the system serial interface. The converter cores can be enabled if needed.

ACTIVE: The main supply voltage $V_{(VANA)}$ is above $VANA_{UVLO}$ level and $V_{(NRST)}$ voltage is above threshold level. At least one converter core is enabled. All registers can be read or written by the host processor via the system serial interface.

The operating modes and transitions between the modes are shown in Figure 12.

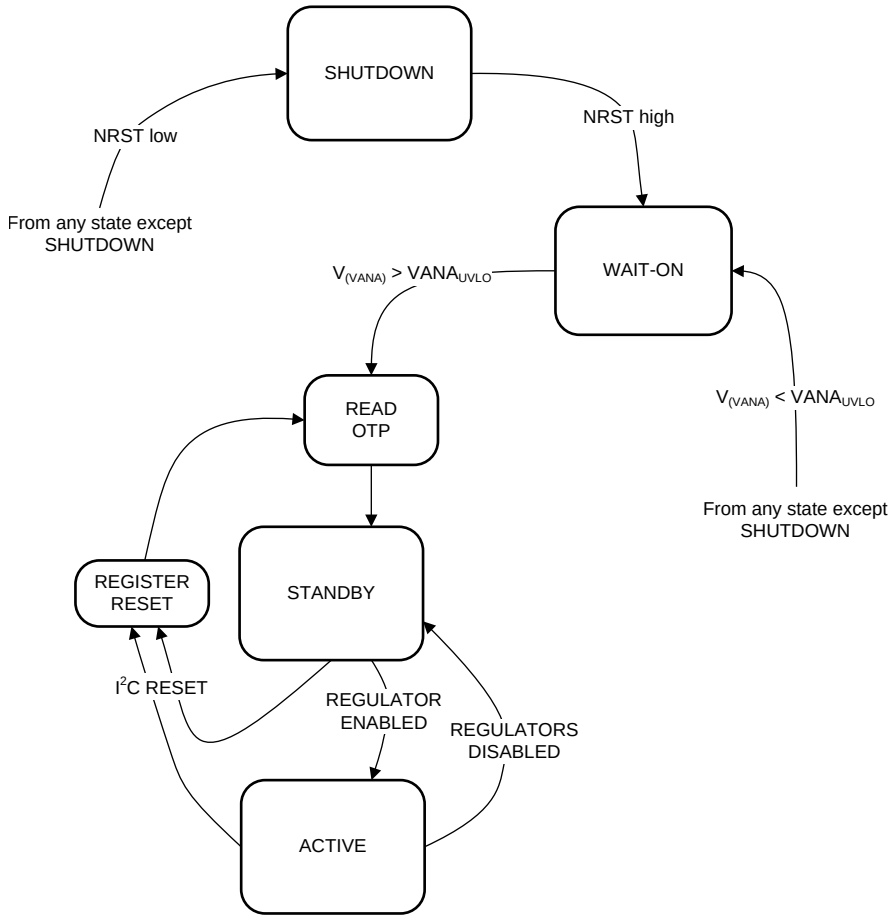


Figure 12. Device Operation Modes

7.5 Programming

7.5.1 I²C-Compatible Interface

The I²C-compatible synchronous serial interface provides access to the programmable functions and registers on the device. This protocol uses a two-wire interface for bidirectional communications between the devices connected to the bus. The two interface lines are the Serial Data Line (SDA), and the Serial Clock Line (SCL). Every device on the bus is assigned a unique address and acts as either a master or a slave depending on whether it generates or receives the serial clock SCL. The SCL and SDA lines must each have a pullup resistor placed somewhere on the line and remain HIGH even when the bus is idle. The LP8758-E0 supports standard mode (100 kHz), fast mode (400 kHz), fast mode plus (1 MHz), and high-speed mode (3.4 MHz).

7.5.1.1 Data Validity

The data on the SDA line must be stable during the HIGH period of the clock signal (SCL). In other words, the state of the data line can only be changed when clock signal is LOW.

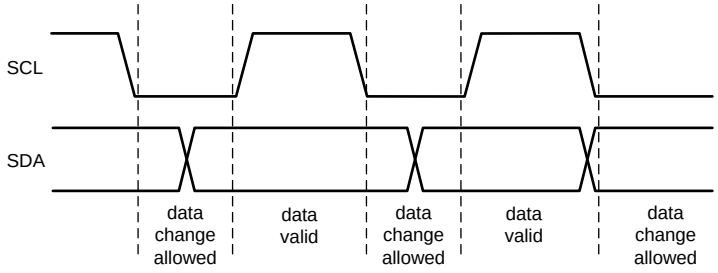


Figure 13. Data Validity Diagram

7.5.1.2 Start and Stop Conditions

The LP8758-E0 is controlled via an I²C-compatible interface. START and STOP conditions classify the beginning and end of the I²C session. A START condition is defined as SDA transitions from HIGH to LOW while SCL is HIGH. A STOP condition is defined as SDA transition from LOW to HIGH while SCL is HIGH. The I²C master always generates the START and STOP conditions.

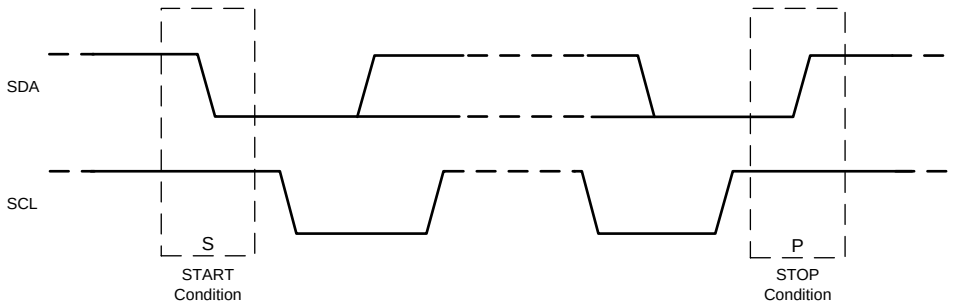


Figure 14. Start and Stop Sequences

The I²C bus is considered busy after a START condition and free after a STOP condition. During data transmission the I²C master can generate repeated START conditions. A START and a repeated START condition are equivalent function-wise. The data on SDA must be stable during the HIGH period of the clock signal (SCL). In other words, the state of SDA can only be changed when SCL is LOW. Figure 15 shows the SDA and SCL signal timing for the I²C-Compatible Bus. See the *I²C Serial Bus Timing Requirements* for timing values.

Programming (continued)

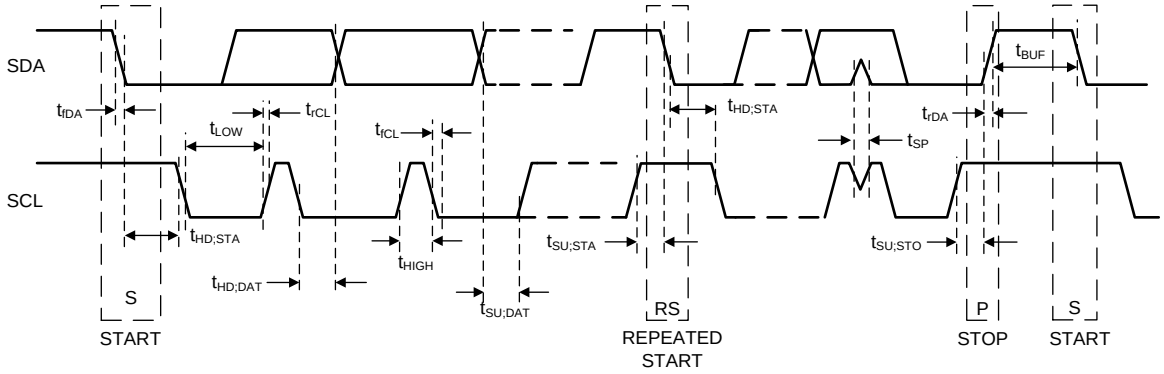


Figure 15. I²C-Compatible Timing

7.5.1.3 Transferring Data

Every byte put on the SDA line must be eight bits long, with the most significant bit (MSB) being transferred first. Each byte of data has to be followed by an acknowledge bit. The acknowledge related clock pulse is generated by the master. The master releases the SDA line (HIGH) during the acknowledge clock pulse. The LP8758-E0 pulls down the SDA line during the 9th clock pulse, signifying an acknowledge. The LP8758-E0 generates an acknowledge after each byte has been received.

There is one exception to the *acknowledge after every byte* rule. When the master is the receiver, it must indicate to the transmitter an end of data by not-acknowledging ("negative acknowledge") the last byte clocked out of the slave. This *negative acknowledge* still includes the acknowledge clock pulse (generated by the master), but the SDA line is not pulled down.

NOTE

If the NRST signal is low during I²C communication the LP8758-E0 device does not drive SDA line. The ACK signal and data transfer to the master is disabled at that time.

After the START condition, the bus master sends a chip address. This address is seven bits long followed by an eighth bit which is a data direction bit (READ or WRITE). For the eighth bit, a 0 indicates a WRITE, and a 1 indicates a READ. The second byte selects the register to which the data is written. The third byte contains data to write to the selected register.

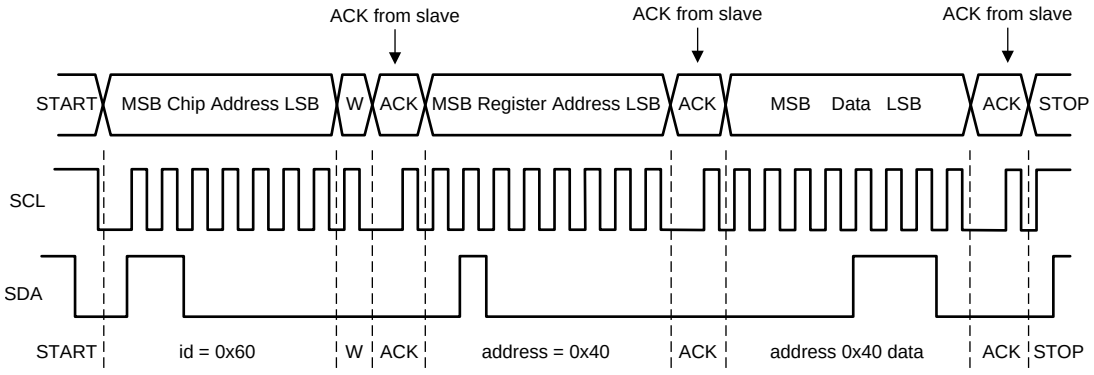
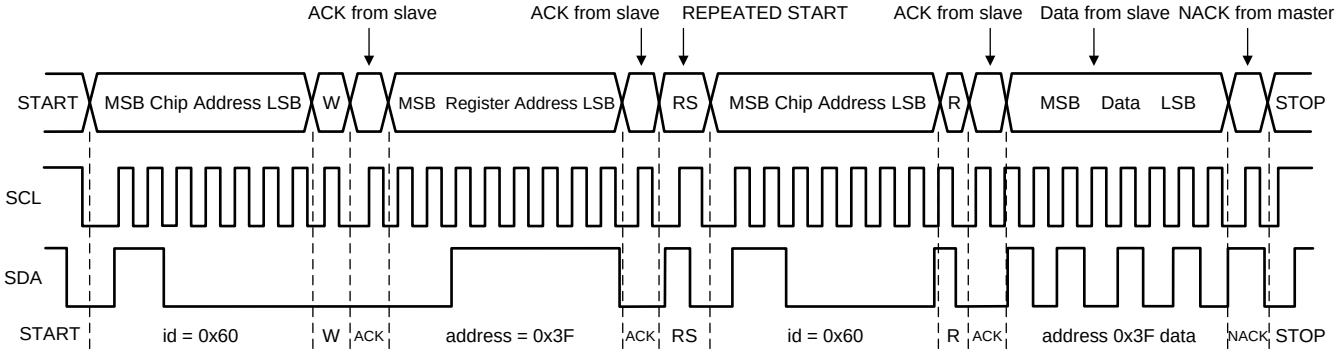


Figure 16. Write Cycle (w = write; SDA = 0), id = Device Address = 60Hex for LP8758-E0

Programming (continued)

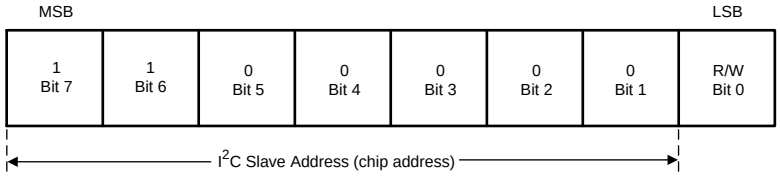


When READ function is to be accomplished, a WRITE function must precede the READ function as shown above.

Figure 17. Read Cycle (r = read; SDA = 1), id = Device Address = 60Hex for LP8758-E0

7.5.1.4 I²C-Compatible Chip Address

The device address for the LP8758-E0 is 0x60. After the START condition, the I²C master sends the 7-bit address followed by an eighth bit, read or write (R/W). R/W = 0 indicates a WRITE and R/W = 1 indicates a READ. The second byte following the device address selects the register address to which the data will be written. The third byte contains the data for the selected register.



Here device address is 110 0000Bin = 60Hex.

Figure 18. Device Address

7.5.1.5 Auto Increment Feature

The auto-increment feature allows writing several consecutive registers within one transmission. Every time an 8-bit word is sent to the LP8758-E0, the internal address index counter is incremented by one and the next register is written. Table 5 below shows writing sequence to two consecutive registers. Note that the auto-increment feature does not work for read.

Table 5. Auto-Increment Example

Master Action	Start	Device Address = 60H	Write		Register Address		Data		Data		Stop
LP8758-E0 Action				ACK		ACK		ACK		ACK	

7.6 Register Maps

7.6.1 Register Descriptions

The LP8758-E0 is controlled by a set of registers through the serial interface port. The device registers, their addresses and their abbreviations are listed in Table 6. A more detailed description is given in sections *OTP_REV* to *I_LOAD_1*.

The asterisk (*) marking indicates register bits which are updated from OTP memory during READ OTP state.

Table 6. Summary of LP8758-E0 Control Registers

Addr	Register	Read / Write	D7	D6	D5	D4	D3	D2	D1	D0
0x01	OTP_REV	R	OTP_ID[7:0]							
0x02	BUCK0_CTRL1	R/W	EN_BUCK0	EN_PIN_CTRL0	EN_PIN_SELECT0	EN_ROOF_FLOOR0	EN_RDIS0	Reserved	BUCK0_FPWM	Reserved
0x03	BUCK0_CTRL2	R/W	Reserved		ILIM0[2:0]			SLEW_RATE0[2:0]		
0x04	BUCK1_CTRL1	R/W	EN_BUCK1	EN_PIN_CTRL1	EN_PIN_SELECT1	EN_ROOF_FLOOR1	EN_RDIS1	Reserved	BUCK1_FPWM	Reserved
0x05	BUCK1_CTRL2	R/W	Reserved		ILIM1[2:0]			SLEW_RATE1[2:0]		
0x06	BUCK2_CTRL1	R/W	EN_BUCK2	EN_PIN_CTRL2	EN_PIN_SELECT2	EN_ROOF_FLOOR2	EN_RDIS2	Reserved	BUCK2_FPWM	Reserved
0x07	BUCK2_CTRL2	R/W	Reserved		ILIM2[2:0]			SLEW_RATE2[2:0]		
0x08	BUCK3_CTRL1	R/W	EN_BUCK3	EN_PIN_CTRL3	EN_PIN_SELECT3	EN_ROOF_FLOOR3	EN_RDIS3	Reserved	BUCK3_FPWM	Reserved
0x09	BUCK3_CTRL2	R/W	Reserved		ILIM3[2:0]			SLEW_RATE3[2:0]		
0x0A	BUCK0_VOUT	R/W	BUCK0_VSET[7:0]							
0x0B	BUCK0_FLOOR_VOUT	R/W	BUCK0_FLOOR_VSET[7:0]							
0x0C	BUCK1_VOUT	R/W	BUCK1_VSET[7:0]							
0x0D	BUCK1_FLOOR_VOUT	R/W	BUCK1_FLOOR_VSET[7:0]							
0x0E	BUCK2_VOUT	R/W	BUCK2_VSET[7:0]							
0x0F	BUCK2_FLOOR_VOUT	R/W	BUCK2_FLOOR_VSET[7:0]							
0x10	BUCK3_VOUT	R/W	BUCK3_VSET[7:0]							
0x11	BUCK3_FLOOR_VOUT	R/W	BUCK3_FLOOR_VSET[7:0]							
0x12	BUCK0_DELAY	R/W	BUCK0_SHUTDOWN_DELAY[3:0]				BUCK0_STARTUP_DELAY[3:0]			
0x13	BUCK1_DELAY	R/W	BUCK1_SHUTDOWN_DELAY[3:0]				BUCK1_STARTUP_DELAY[3:0]			
0x14	BUCK2_DELAY	R/W	BUCK2_SHUTDOWN_DELAY[3:0]				BUCK2_STARTUP_DELAY[3:0]			
0x15	BUCK3_DELAY	R/W	BUCK3_SHUTDOWN_DELAY[3:0]				BUCK3_STARTUP_DELAY[3:0]			
0x16	RESET	R/W	Reserved							SW_RESET
0x17	CONFIG	R/W	Reserved				TDIE_WARN_LEVEL	EN2_PD	EN1_PD	EN_SPREAD_SPEC
0x18	INT_TOP	R/W	INT_BUCK3	INT_BUCK2	INT_BUCK1	INT_BUCK0	TDIE_SD	TDIE_WARN	RESET_REG	I_LOAD_READY

Register Maps (continued)

Table 6. Summary of LP8758-E0 Control Registers (continued)

Addr	Register	Read / Write	D7	D6	D5	D4	D3	D2	D1	D0
0x19	INT_BUCK_0_1	R/W	Reserved	BUCK1_PG_INT	BUCK1_SC_INT	BUCK1_ILIM_INT	Reserved	BUCK0_PG_INT	BUCK0_SC_INT	BUCK0_ILIM_INT
0x1A	INT_BUCK_2_3	R/W	Reserved	BUCK3_PG_INT	BUCK3_SC_INT	BUCK3_ILIM_INT	Reserved	BUCK2_PG_INT	BUCK2_SC_INT	BUCK2_ILIM_INT
0x1B	TOP_STAT	R	Reserved				TDIE_SD_STAT	TDIE_WARN_STAT	Reserved	
0x1C	BUCK_0_1_STAT	R	BUCK1_STAT	BUCK1_PG_STAT	Reserved	BUCK1_ILIM_STAT	BUCK0_STAT	BUCK0_PG_STAT	Reserved	BUCK0_ILIM_STAT
0x1D	BUCK_2_3_STAT	R	BUCK3_STAT	BUCK3_PG_STAT	Reserved	BUCK3_ILIM_STAT	BUCK2_STAT	BUCK2_PG_STAT	Reserved	BUCK2_ILIM_STAT
0x1E	TOP_MASK	R/W	Reserved					TDIE_WARN_MASK	RESET_REG_MASK	I_LOAD_READY_MASK
0x1F	BUCK_0_1_MASK	R/W	Reserved	BUCK1_PG_MASK	Reserved	BUCK1_ILIM_MASK	Reserved	BUCK0_PG_MASK	Reserved	BUCK0_ILIM_MASK
0x20	BUCK_2_3_MASK	R/W	Reserved	BUCK3_PG_MASK	Reserved	BUCK3_ILIM_MASK	Reserved	BUCK2_PG_MASK	Reserved	BUCK2_ILIM_MASK
0x21	SEL_I_LOAD	R/W	Reserved						LOAD_CURRENT_BUCK_SELECT[1:0]	
0x22	I_LOAD_2	R/W	Reserved						BUCK_LOAD_CURRENT[9:8]	
0x23	I_LOAD_1	R/W	BUCK_LOAD_CURRENT[7:0]							

7.6.1.1 OTP_REV

Address: 0x01

D7	D6	D5	D4	D3	D2	D1	D0
OTP_ID[7:0]							

Bits	Field	Type	Default	Description
7:0	OTP_ID[7:0]	R	0xE0 *	Identification code of the OTP EPROM version.

7.6.1.2 BUCK0_CTRL1

Address: 0x02

D7	D6	D5	D4	D3	D2	D1	D0
EN_BUCK0	EN_PIN_CTRL0	EN_PIN_SELECT0	EN_ROOF_FLOOR0	EN_RDIS0	Reserved	BUCK0_FPWM	Reserved

Bits	Field	Type	Default	Description
7	EN_BUCK0	R/W	1 *	Enable BUCK0 converter core: 0 - BUCK0 converter core is disabled 1 - BUCK0 converter core is enabled.
6	EN_PIN_CTRL0	R/W	1 *	Enable EN1/2 pin control for BUCK0: 0 - only EN_BUCK0 bit controls BUCK0 1 - EN_BUCK0 bit AND EN1/2 pin control BUCK0.
5	EN_PIN_SELECT0	R/W	0 *	Select which ENx pin controls BUCK0 if EN_PIN_CTRL0 = 1: 0 - EN1 pin 1 - EN2 pin.
4	EN_ROOF_FLOOR0	R/W	0	Enable Roof/Floor control of EN1/2 pin if EN_PIN_CTRL0 = 1: 0 - Enable/Disable (1/0) control 1 - Roof/Floor (1/0) control.
3	EN_RDIS0	R/W	1	Enable output discharge resistor when BUCK0 is disabled: 0 - Discharge resistor disabled 1 - Discharge resistor enabled.
2	Reserved	R/W	0	
1	BUCK0_FPWM	R/W	0 *	Forces the BUCK0 converter core to operate in PWM mode: 0 - Automatic transitions between PFM and PWM modes (AUTO mode). 1 - Forced to PWM operation.
0	Reserved	R/W	0	

7.6.1.3 BUCK0_CTRL2

Address: 0x03

D7	D6	D5	D4	D3	D2	D1	D0
Reserved			ILIM0[2:0]			SLEW_RATE0[2:0]	

Bits	Field	Type	Default	Description
7:6	Reserved	R/W	00	
5:3	ILIM0[2:0]	R/W	0x2 *	Sets the switch current limit of BUCK0. Can be programmed at any time during operation: 0x2 - 2.5 A 0x3 - 3.0 A 0x4 - 3.5 A 0x5 - 4.0 A 0x6 - 4.5 A 0x7 - 5.0 A

Bits	Field	Type	Default	Description
2:0	SLEW_RATE0[2:0]	R/W	0x2 *	Sets the output voltage slew rate for BUCK0 converter core (rising and falling edges): 0x0 - 30 mV/µs 0x1 - 15 mV/µs 0x2 - 10 mV/µs 0x3 - 7.5 mV/µs 0x4 - 3.8 mV/µs 0x5 - 1.9 mV/µs 0x6 - 0.94 mV/µs 0x7 - 0.4 mV/µs

7.6.1.4 BUCK1_CTRL1

Address: 0x04

D7	D6	D5	D4	D3	D2	D1	D0
EN_BUCK1	EN_PIN_CTRL1	EN_PIN_SELECT1	EN_ROOF_FLOOR1	EN_RDIS1	Reserved	BUCK1_FPWM	Reserved

Bits	Field	Type	Default	Description
7	EN_BUCK1	R/W	1 *	Enable BUCK1 converter core: 0 - BUCK1 converter core is disabled 1 - BUCK1 converter core is enabled.
6	EN_PIN_CTRL1	R/W	1 *	Enable EN1/2 pin control for BUCK1: 0 - only EN_BUCK1 bit controls BUCK1 1 - EN_BUCK1 bit AND EN1/2 pin control BUCK1.
5	EN_PIN_SELECT1	R/W	0 *	Select which ENx pin controls BUCK1 if EN_PIN_CTRL1 = 1: 0 - EN1 pin 1 - EN2 pin.
4	EN_ROOF_FLOOR1	R/W	0	Enable Roof/Floor control of EN1/2 pin if EN_PIN_CTRL1 = 1: 0 - Enable/Disable (1/0) control 1 - Roof/Floor (1/0) control.
3	EN_RDIS1	R/W	1	Enable output discharge resistor when BUCK1 is disabled: 0 - Discharge resistor disabled 1 - Discharge resistor enabled.
2	Reserved	R/W	0	
1	BUCK1_FPWM	R/W	0 *	Forces the BUCK1 converter core to operate in PWM mode: 0 - Automatic transitions between PFM and PWM modes (AUTO mode). 1 - Forced to PWM operation.
0	Reserved	R/W	0	

7.6.1.5 BUCK1_CTRL2

Address: 0x05

D7	D6	D5	D4	D3	D2	D1	D0
Reserved		ILIM1[2:0]			SLEW_RATE1[2:0]		

Bits	Field	Type	Default	Description
7:6	Reserved	R/W	00	
5:3	ILIM1[2:0]	R/W	0x6 *	Sets the switch current limit of BUCK1. Can be programmed at any time during operation: 0x2 - 2.5 A 0x3 - 3.0 A 0x4 - 3.5 A 0x5 - 4.0 A 0x6 - 4.5 A 0x7 - 5.0 A
2:0	SLEW_RATE1[2:0]	R/W	0x2 *	Sets the output voltage slew rate for BUCK1 converter core (rising and falling edges): 0x0 - 30 mV/µs 0x1 - 15 mV/µs 0x2 - 10 mV/µs 0x3 - 7.5 mV/µs 0x4 - 3.8 mV/µs 0x5 - 1.9 mV/µs 0x6 - 0.94 mV/µs 0x7 - 0.4 mV/µs

7.6.1.6 BUCK2_CTRL1

Address: 0x06

D7	D6	D5	D4	D3	D2	D1	D0
EN_BUCK2	EN_PIN_CTRL2	EN_PIN_SELECT2	EN_ROOF_FLOOR2	EN_RDIS2	Reserved	BUCK2_FPWM	Reserved

Bits	Field	Type	Default	Description
7	EN_BUCK2	R/W	1 *	Enable BUCK2 converter core: 0 - BUCK2 converter core is disabled 1 - BUCK2 converter core is enabled.
6	EN_PIN_CTRL2	R/W	1 *	Enable EN1/2 pin control for BUCK2: 0 - only EN_BUCK2 bit controls BUCK2 1 - EN_BUCK2 bit AND EN1/2 pin control BUCK2.
5	EN_PIN_SELECT2	R/W	0 *	Select which ENx pin controls BUCK2 if EN_PIN_CTRL2 = 1: 0 - EN1 pin 1 - EN2 pin.
4	EN_ROOF_FLOOR2	R/W	0	Enable Roof/Floor control of EN1/2 pin if EN_PIN_CTRL2 = 1: 0 - Enable/Disable (1/0) control 1 - Roof/Floor (1/0) control.
3	EN_RDIS2	R/W	1	Enable output discharge resistor when BUCK2 is disabled: 0 - Discharge resistor disabled 1 - Discharge resistor enabled.
2	Reserved	R/W	0	
1	BUCK2_FPWM	R/W	0 *	Forces the BUCK2 converter core to operate in PWM mode: 0 - Automatic transitions between PFM and PWM modes (AUTO mode). 1 - Forced to PWM operation.
0	Reserved	R/W	0	

7.6.1.7 BUCK2_CTRL2

Address: 0x07

D7	D6	D5	D4	D3	D2	D1	D0
Reserved		ILIM2[2:0]			SLEW_RATE2[2:0]		

Bits	Field	Type	Default	Description
7:6	Reserved	R/W	00	
5:3	ILIM2[2:0]	R/W	0x4 *	Sets the switch current limit of BUCK2. Can be programmed at any time during operation: 0x2 - 2.5 A 0x3 - 3.0 A 0x4 - 3.5 A 0x5 - 4.0 A 0x6 - 4.5 A 0x7 - 5.0 A
2:0	SLEW_RATE2[2:0]	R/W	0x2 *	Sets the output voltage slew rate for BUCK2 converter core (rising and falling edges): 0x0 - 30 mV/µs 0x1 - 15 mV/µs 0x2 - 10 mV/µs 0x3 - 7.5 mV/µs 0x4 - 3.8 mV/µs 0x5 - 1.9 mV/µs 0x6 - 0.94 mV/µs 0x7 - 0.4 mV/µs

7.6.1.8 BUCK3_CTRL1

Address: 0x08

D7	D6	D5	D4	D3	D2	D1	D0
EN_BUCK3	EN_PIN_CTRL3	EN_PIN_SELECT3	EN_ROOF_FLOOR3	EN_RDIS3	Reserved	BUCK3_FPWM	Reserved

Bits	Field	Type	Default	Description
7	EN_BUCK3	R/W	1 *	Enable BUCK3 converter core: 0 - BUCK3 converter core is disabled 1 - BUCK3 converter core is enabled.
6	EN_PIN_CTRL3	R/W	1 *	Enable EN1/2 pin control for BUCK3: 0 - only EN_BUCK3 bit controls BUCK3 1 - EN_BUCK3 bit AND EN1/2 pin control BUCK3.
5	EN_PIN_SELECT3	R/W	0 *	Select which ENx pin controls BUCK3 if EN_PIN_CTRL3 = 1: 0 - EN1 pin 1 - EN2 pin.
4	EN_ROOF_FLOOR3	R/W	0	Enable Roof/Floor control of EN1/2 pin if EN_PIN_CTRL3 = 1: 0 - Enable/Disable (1/0) control 1 - Roof/Floor (1/0) control.
3	EN_RDIS3	R/W	1	Enable output discharge resistor when BUCK3 is disabled: 0 - Discharge resistor disabled 1 - Discharge resistor enabled.
2	Reserved	R/W	0	
1	BUCK3_FPWM	R/W	0 *	Forces the BUCK3 converter core to operate in PWM mode: 0 - Automatic transitions between PFM and PWM modes (AUTO mode). 1 - Forced to PWM operation.
0	Reserved	R/W	0	

7.6.1.9 BUCK3_CTRL2

Address: 0x09

D7	D6	D5	D4	D3	D2	D1	D0
Reserved		ILIM3[2:0]			SLEW_RATE3[2:0]		

Bits	Field	Type	Default	Description
7:6	Reserved	R/W	00	
5:3	ILIM3[2:0]	R/W	0x6 *	Sets the switch current limit of BUCK3. Can be programmed at any time during operation: 0x2 - 2.5 A 0x3 - 3.0 A 0x4 - 3.5 A 0x5 - 4.0 A 0x6 - 4.5 A 0x7 - 5.0 A
2:0	SLEW_RATE3[2:0]	R/W	0x2 *	Sets the output voltage slew rate for BUCK3 converter core (rising and falling edges): 0x0 - 30 mV/µs 0x1 - 15 mV/µs 0x2 - 10 mV/µs 0x3 - 7.5 mV/µs 0x4 - 3.8 mV/µs 0x5 - 1.9 mV/µs 0x6 - 0.94 mV/µs 0x7 - 0.4 mV/µs

7.6.1.10 BUCK0_VOUT

Address: 0x0A

D7	D6	D5	D4	D3	D2	D1	D0
BUCK0_VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK0_VSET[7:0]	R/W	0x4D *	Sets the output voltage of BUCK0 converter core (Default 1000 mV) **0.5 V - 0.73 V, 10 mV steps** 0x00 - 0.5V ... 0x17 - 0.73 V **0.73 V - 1.4 V, 5 mV steps** 0x18 - 0.735 V ... 0x9D - 1.4 V **1.4 V - 3.36 V, 20 mV steps** 0x9E - 1.42 V ... 0xFF - 3.36 V

7.6.1.11 BUCK0_FLOOR_VOUT

Address: 0x0B

D7	D6	D5	D4	D3	D2	D1	D0
BUCK0_FLOOR_VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK0_FLOOR_VSET[7:0]	R/W	0x00	Sets the output voltage of BUCK0 converter core when Floor state is used **0.5 V - 0.73 V, 10 mV steps** 0x00 - 0.5V ... 0x17 - 0.73 V **0.73 V - 1.4 V, 5 mV steps** 0x18 - 0.735 V ... 0x9D - 1.4 V **1.4 V - 3.36 V, 20 mV steps** 0x9E - 1.42 V ... 0xFF - 3.36 V

7.6.1.12 BUCK1_VOUT

Address: 0x0C

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK1_VSET[7:0]	R/W	0xD4 *	Sets the output voltage of BUCK1 converter core (Default 2500 mV) **0.5 V - 0.73 V, 10 mV steps** 0x00 - 0.5V ... 0x17 - 0.73 V **0.73 V - 1.4 V, 5 mV steps** 0x18 - 0.735 V ... 0x9D - 1.4 V **1.4 V - 3.36 V, 20 mV steps** 0x9E - 1.42 V ... 0xFF - 3.36 V

7.6.1.13 BUCK1_FLOOR_VOUT

Address: 0x0D

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_FLOOR_VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK1_FLOOR_VSET[7:0]	R/W	0x00	Sets the output voltage of BUCK1 converter core when Floor state is used **0.5 V - 0.73 V, 10 mV steps** 0x00 - 0.5V ... 0x17 - 0.73 V **0.73 V - 1.4 V, 5 mV steps** 0x18 - 0.735 V ... 0x9D - 1.4 V **1.4 V - 3.36 V, 20 mV steps** 0x9E - 1.42 V ... 0xFF - 3.36 V

7.6.1.14 BUCK2_VOUT

Address: 0x0E

D7	D6	D5	D4	D3	D2	D1	D0
BUCK2_VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK2_VSET[7:0]	R/W	0x75 *	Sets the output voltage of BUCK2 converter core (Default 1200 mV) **0.5 V - 0.73 V, 10 mV steps** 0x00 - 0.5V ... 0x17 - 0.73 V **0.73 V - 1.4 V, 5 mV steps** 0x18 - 0.735 V ... 0x9D - 1.4 V **1.4 V - 3.36 V, 20 mV steps** 0x9E - 1.42 V ... 0xFF - 3.36 V

7.6.1.15 BUCK2_FLOOR_VOUT

Address: 0x0F

D7	D6	D5	D4	D3	D2	D1	D0
BUCK2_FLOOR _VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK2_FLOOR _VSET[7:0]	R/W	0x00	Sets the output voltage of BUCK2 converter core when Floor state is used **0.5 V - 0.73 V, 10 mV steps** 0x00 - 0.5V ... 0x17 - 0.73 V **0.73 V - 1.4 V, 5 mV steps** 0x18 - 0.735 V ... 0x9D - 1.4 V **1.4 V - 3.36 V, 20 mV steps** 0x9E - 1.42 V ... 0xFF - 3.36 V

7.6.1.16 BUCK3_VOUT

Address: 0x10

D7	D6	D5	D4	D3	D2	D1	D0
BUCK3_VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK3_VSET[7:0]	R/W	0xB1 *	Sets the output voltage of BUCK3 converter core (Default 1800 mV) **0.5 V - 0.73 V, 10 mV steps** 0x00 - 0.5V ... 0x17 - 0.73 V **0.73 V - 1.4 V, 5 mV steps** 0x18 - 0.735 V ... 0x9D - 1.4 V **1.4 V - 3.36 V, 20 mV steps** 0x9E - 1.42 V ... 0xFF - 3.36 V

7.6.1.17 BUCK3_FLOOR_VOUT

Address: 0x11

D7	D6	D5	D4	D3	D2	D1	D0
BUCK3_FLOOR_VSET[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK3_FLOOR_VSET[7:0]	R/W	0x00	Sets the output voltage of BUCK3 converter core when Floor state is used **0.5 V - 0.73 V, 10 mV steps** 0x00 - 0.5V ... 0x17 - 0.73 V **0.73 V - 1.4 V, 5 mV steps** 0x18 - 0.735 V ... 0x9D - 1.4 V **1.4 V - 3.36 V, 20 mV steps** 0x9E - 1.42 V ... 0xFF - 3.36 V

7.6.1.18 BUCK0_DELAY

Address: 0x12

D7	D6	D5	D4	D3	D2	D1	D0
BUCK0_SHUTDOWN_DELAY[3:0]				BUCK0_STARTUP_DELAY[3:0]			

Bits	Field	Type	Default	Description
7:4	BUCK0_SHUTDOWN_DELAY[3:0]	R/W	0x5 *	Shutdown delay of BUCK0 from falling edge of ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms
3:0	BUCK0_STARTUP_DELAY[3:0]	R/W	0x0 *	Startup delay of BUCK0 from rising edge of ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms

7.6.1.19 BUCK1_DELAY

Address: 0x13

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_SHUTDOWN_DELAY[3:0]				BUCK1_STARTUP_DELAY[3:0]			

Bits	Field	Type	Default	Description
7:4	BUCK1_SHUTDOWN_DELAY[3:0]	R/W	0x5 *	Shutdown delay of BUCK1 from falling edge of ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms
3:0	BUCK1_STARTUP_DELAY[3:0]	R/W	0x0 *	Startup delay of BUCK1 from rising edge of ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms

7.6.1.20 BUCK2_DELAY

Address: 0x14

D7	D6	D5	D4	D3	D2	D1	D0
BUCK2_SHUTDOWN_DELAY[3:0]				BUCK2_STARTUP_DELAY[3:0]			

Bits	Field	Type	Default	Description
7:4	BUCK2_ SHUTDOWN_ DELAY[3:0]	R/W	0x0 *	Shutdown delay of BUCK2 from falling edge of ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms
3:0	BUCK2_ STARTUP_ DELAY[3:0]	R/W	0x5 *	Start-up delay of BUCK2 from rising edge of ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms

7.6.1.21 BUCK3_DELAY

Address: 0x15

D7	D6	D5	D4	D3	D2	D1	D0
BUCK3_SHUTDOWN_DELAY[3:0]				BUCK3_STARTUP_DELAY[3:0]			

Bits	Field	Type	Default	Description
7:4	BUCK3_ SHUTDOWN_ DELAY[3:0]	R/W	0x5 *	Shutdown delay of BUCK3 from falling edge of ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms
3:0	BUCK3_ STARTUP_ DELAY[3:0]	R/W	0x0 *	Start-up delay of BUCK3 from rising edge of ENx signal: 0x0 - 0 ms 0x1 - 1 ms ... 0xF - 15 ms

7.6.1.22 RESET

Address: 0x16

D7	D6	D5	D4	D3	D2	D1	D0
Reserved							SW_RESET

Bits	Field	Type	Default	Description
7:1	Reserved	R/W	0000 000	
0	SW_RESET	R/W	0	Software commanded reset. When written to 1, the registers are reset to default values, OTP memory is read, and the I^2C interface is reset. The bit is automatically cleared.

7.6.1.23 CONFIG

Address: 0x17

D7	D6	D5	D4	D3	D2	D1	D0
Reserved				TDIE_WARN_LEVEL	EN2_PD	EN1_PD	EN_SPREAD_SPEC

Bits	Field	Type	Default	Description
7:4	Reserved	R/W	0000	
3	TDIE_WARN_LEVEL	R/W	0	Thermal warning threshold level. 0 - 125°C 1 - 105°C.
2	EN2_PD	R/W	1	Selects the pulldown resistor on the EN2 input pin. 0 - Pulldown resistor is disabled. 1 - Pulldown resistor is enabled.
1	EN1_PD	R/W	1	Selects the pull down resistor on the EN1 input pin. 0 - Pulldown resistor is disabled. 1 - Pulldown resistor is enabled.
0	EN_SPREAD_SPEC	R/W	0	Enable spread-spectrum feature: 0 - Disabled 1 - Enabled

7.6.1.24 INT_TOP

Address: 0x18

D7	D6	D5	D4	D3	D2	D1	D0
INT_BUCK3	INT_BUCK2	INT_BUCK1	INT_BUCK0	TDIE_SD	TDIE_WARN	RESET_REG	I_LOAD_READY

Bits	Field	Type	Default	Description
7	INT_BUCK3	R	0	Interrupt indicating that output BUCK3 has a pending interrupt. The reason for the interrupt is indicated in INT_BUCK3 register. This bit is cleared automatically when INT_BUCK3 register is cleared to 0x00.
6	INT_BUCK2	R	0	Interrupt indicating that output BUCK2 has a pending interrupt. The reason for the interrupt is indicated in INT_BUCK2 register. This bit is cleared automatically when INT_BUCK2 register is cleared to 0x00.
5	INT_BUCK1	R	0	Interrupt indicating that output BUCK1 has a pending interrupt. The reason for the interrupt is indicated in INT_BUCK1 register. This bit is cleared automatically when INT_BUCK1 register is cleared to 0x00.
4	INT_BUCK0	R	0	Interrupt indicating that output BUCK0 has a pending interrupt. The reason for the interrupt is indicated in INT_BUCK0 register. This bit is cleared automatically when INT_BUCK0 register is cleared to 0x00.
3	TDIE_SD	R/W	0	Latched status bit indicating that the die junction temperature has exceeded the thermal shutdown level. The converter cores have been disabled if they were enabled. The converter cores cannot be enabled if this bit is active. The actual status of the thermal warning is indicated by TOP_STAT.TDIE_SD_STAT bit. Write 1 to clear interrupt.
2	TDIE_WARN	R/W	0	Latched status bit indicating that the die junction temperature has exceeded the thermal warning level. The actual status of the thermal warning is indicated by TOP_STAT.TDIE_WARN_STAT bit. Write 1 to clear interrupt.
1	RESET_REG	R/W	0	Latched status bit indicating that either startup (NRST rising edge) has done, VANA supply voltage has been below undervoltage threshold level or the host has requested a reset (RESET.SW_RESET). The converter cores have been disabled, and registers are reset to default values and the normal startup procedure is done. Write 1 to clear interrupt.
0	I_LOAD_READY	R/W	0	Latched status bit indicating that the load current measurement result is available in I_LOAD_1 and I_LOAD_2 registers. Write 1 to clear interrupt.

7.6.1.25 INT_BUCK_0_1

Address: 0x19

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	BUCK1_PG_INT	BUCK1_SC_INT	BUCK1_ILIM_INT	Reserved	BUCK0_PG_INT	BUCK0_SC_INT	BUCK0_ILIM_INT

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	BUCK1_PG_INT	R/W	0	Latched status bit indicating that BUCK1 output voltage has reached power-good threshold level. Write 1 to clear.
5	BUCK1_SC_INT	R/W	0	Latched status bit indicating that the BUCK1 output voltage has fallen below 0.35-V level during operation or BUCK1 output didn't reach 0.35-V level in 1 ms from enable. Write 1 to clear.
4	BUCK1_ILIM_INT	R/W	0	Latched status bit indicating that output current limit has been active. Write 1 to clear.
3	Reserved	R/W	0	
2	BUCK0_PG_INT	R/W	0	Latched status bit indicating that BUCK0 output voltage has reached powergood threshold level. Write 1 to clear.
1	BUCK0_SC_INT	R/W	0	Latched status bit indicating that the BUCK0 output voltage has fallen below 0.35-V level during operation or BUCK0 output didn't reach 0.35-V level in 1 ms from enable. Write 1 to clear.
0	BUCK0_ILIM_INT	R/W	0	Latched status bit indicating that output current limit has been active. Write 1 to clear.

7.6.1.26 INT_BUCK_2_3

Address: 0x1A

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	BUCK3_PG_INT	BUCK3_SC_INT	BUCK3_ILIM_INT	Reserved	BUCK2_PG_INT	BUCK2_SC_INT	BUCK2_ILIM_INT

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	BUCK3_PG_INT	R/W	0	Latched status bit indicating that BUCK3 output voltage has reached power-good threshold level. Write 1 to clear.
5	BUCK3_SC_INT	R/W	0	Latched status bit indicating that the BUCK3 output voltage has fallen below 0.35-V level during operation or BUCK3 output didn't reach 0.35-V level in 1 ms from enable. Write 1 to clear.
4	BUCK3_ILIM_INT	R/W	0	Latched status bit indicating that output current limit has been active. Write 1 to clear.
3	Reserved	R/W	0	
2	BUCK2_PG_INT	R/W	0	Latched status bit indicating that BUCK2 output voltage has reached powergood threshold level. Write 1 to clear.
1	BUCK2_SC_INT	R/W	0	Latched status bit indicating that the BUCK2 output voltage has fallen below 0.35V level during operation or BUCK2 output didn't reach 0.35-V level in 1 ms from enable. Write 1 to clear.
0	BUCK2_ILIM_INT	R/W	0	Latched status bit indicating that output current limit has been active. Write 1 to clear.

7.6.1.27 TOP_STAT

Address: 0x1B

D7	D6	D5	D4	D3	D2	D1	D0
Reserved				TDIE_SD_STAT	TDIE_WARN_STAT	Reserved	

Bits	Field	Type	Default	Description
7:4	Reserved	R	0000	
3	TDIE_SD_STAT	R	0	Status bit indicating the status of thermal shutdown: 0 - Die temperature below thermal shutdown level 1 - Die temperature above thermal shutdown level.
2	TDIE_WARN_STAT	R	0	Status bit indicating the status of thermal warning: 0 - Die temperature below thermal warning level 1 - Die temperature above thermal warning level.
1:0	Reserved	R	00	

7.6.1.28 BUCK_0_1_STAT

Address: 0x1C

D7	D6	D5	D4	D3	D2	D1	D0
BUCK1_STAT	BUCK1_PG_STAT	Reserved	BUCK1_ILIM_STAT	BUCK0_STAT	BUCK0_PG_STAT	Reserved	BUCK0_ILIM_STAT

Bits	Field	Type	Default	Description
7	BUCK1_STAT	R	0	Status bit indicating the enable/disable status of BUCK1: 0 - BUCK1 converter core is disabled 1 - BUCK1 converter core is enabled.
6	BUCK1_PG_STAT	R	0	Status bit indicating BUCK1 output voltage validity (raw status) 0 - BUCK1 output is above power-good threshold level 1 - BUCK1 output is below power-good threshold level.
5	Reserved	R	0	
4	BUCK1_ILIM_STAT	R	0	Status bit indicating BUCK1 current limit status (raw status) 0 - BUCK1 output current is below current limit level 1 - BUCK1 output current limit is active.
3	BUCK0_STAT	R	0	Status bit indicating the enable/disable status of BUCK0: 0 - BUCK0 converter core is disabled 1 - BUCK0 converter core is enabled.
2	BUCK0_PG_STAT	R	0	Status bit indicating BUCK0 output voltage validity (raw status) 0 - BUCK0 output is above power-good threshold level 1 - BUCK0 output is below power-good threshold level.
1	Reserved	R	0	
0	BUCK0_ILIM_STAT	R	0	Status bit indicating BUCK0 current limit status (raw status) 0 - BUCK0 output current is below current limit level 1 - BUCK0 output current limit is active.

7.6.1.29 BUCK_2_3_STAT

Address: 0x1D

D7	D6	D5	D4	D3	D2	D1	D0
BUCK3_STAT	BUCK3_PG _STAT	Reserved	BUCK3_ILIM _STAT	BUCK2_STAT	BUCK2_PG _STAT	Reserved	BUCK2_ILIM _STAT

Bits	Field	Type	Default	Description
7	BUCK3_STAT	R	0	Status bit indicating the enable/disable status of BUCK3: 0 - BUCK3 converter core is disabled 1 - BUCK3 converter core is enabled.
6	BUCK3_PG_STAT	R	0	Status bit indicating BUCK3 output voltage validity (raw status) 0 - BUCK3 output is above power-good threshold level 1 - BUCK3 output is below power-good threshold level.
5	Reserved	R	0	
4	BUCK3_ILIM _STAT	R	0	Status bit indicating BUCK3 current limit status (raw status) 0 - BUCK3 output current is below current limit level 1 - BUCK3 output current limit is active.
3	BUCK2_STAT	R	0	Status bit indicating the enable/disable status of BUCK2: 0 - BUCK2 converter core is disabled 1 - BUCK2 converter core is enabled.
2	BUCK2_PG_STAT	R	0	Status bit indicating BUCK2 output voltage validity (raw status) 0 - BUCK2 output is above power-good threshold level 1 - BUCK2 output is below power-good threshold level.
1	Reserved	R	0	
0	BUCK2_ILIM _STAT	R	0	Status bit indicating BUCK2 current limit status (raw status) 0 - BUCK2 output current is below current limit level 1 - BUCK2 output current limit is active.

7.6.1.30 TOP_MASK

Address: 0x1E

D7	D6	D5	D4	D3	D2	D1	D0
Reserved					TDIE_WARN _MASK	RESET_REG _MASK	I_LOAD_ READY_MASK

Bits	Field	Type	Default	Description
7:3	Reserved	R/W	0000 0	
2	TDIE_WARN _MASK	R/W	0 *	Masking for thermal warning interrupt INT_TOP.TDIE_WARN: 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect TOP_STAT.TDIE_WARN_STAT status bit.
1	RESET_REG _MASK	R/W	1 *	Masking for register reset interrupt INT_TOP.RESET_REG: 0 - Interrupt generated 1 - Interrupt not generated.
0	I_LOAD_ READY_MASK	R/W	0 *	Masking for load current measurement ready interrupt INT_TOP.I_LOAD_READY. 0 - Interrupt generated 1 - Interrupt not generated.

7.6.1.31 BUCK_0_1_MASK

Address: 0x1F

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	BUCK1_PG_MASK	Reserved	BUCK1_ILIM_MASK	Reserved	BUCK0_PG_MASK	Reserved	BUCK0_ILIM_MASK

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	BUCK1_PG_MASK	R/W	1 *	Masking for BUCK1 power-good interrupt INT_BUCK_0_1.BUCK1_PG_INT.: 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK_0_1_STAT.BUCK1_PG_STAT status bit.
5	Reserved	R	0	
4	BUCK1_ILIM_MASK	R/W	1 *	Masking for BUCK1 current limit detection interrupt INT_BUCK_0_1.BUCK1_ILIM_INT: 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK_0_1_STAT.BUCK1_ILIM_STAT status bit.
3	Reserved	R/W	0	
2	BUCK0_PG_MASK	R/W	1 *	Masking for BUCK0 power-good interrupt INT_BUCK_0_1.BUCK0_PG_INT: 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK_0_1_STAT.BUCK1_PG_STAT status bit.
1	Reserved	R	0	
0	BUCK0_ILIM_MASK	R/W	1 *	Masking for BUCK0 current limit detection interrupt INT_BUCK_0_1.BUCK0_ILIM_INT: 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK_0_1_STAT.BUCK1_ILIM_STAT status bit.

7.6.1.32 BUCK_2_3_MASK

Address: 0x20

D7	D6	D5	D4	D3	D2	D1	D0
Reserved	BUCK3_PG_MASK	Reserved	BUCK3_ILIM_MASK	Reserved	BUCK2_PG_MASK	Reserved	BUCK2_ILIM_MASK

Bits	Field	Type	Default	Description
7	Reserved	R/W	0	
6	BUCK3_PG_MASK	R/W	1 *	Masking for BUCK3 power-good interrupt INT_BUCK_2_3.BUCK3_PG_INT: 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK_2_3_STAT.BUCK3_PG_STAT status bit.
5	Reserved	R	0	
4	BUCK3_ILIM_MASK	R/W	1 *	Masking for BUCK3 current limit detection interrupt INT_BUCK_2_3.BUCK3_ILIM_INT: 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK_2_3_STAT.BUCK3_ILIM_STAT status bit.
3	Reserved	R/W	0	
2	BUCK2_PG_MASK	R/W	1 *	Masking for BUCK2 power-good interrupt INT_BUCK_2_3.BUCK2_PG_INT: 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK_2_3_STAT.BUCK1_PG_STAT status bit.
1	Reserved	R	0	
0	BUCK2_ILIM_MASK	R/W	1 *	Masking for BUCK2 current limit detection interrupt INT_BUCK_2_3.BUCK2_ILIM_INT: 0 - Interrupt generated 1 - Interrupt not generated. This bit does not affect BUCK_2_3_STAT.BUCK1_ILIM_STAT status bit.

7.6.1.33 SEL_I_LOAD

Address: 0x21

D7	D6	D5	D4	D3	D2	D1	D0
Reserved						LOAD_CURRENT_BUCK_SELECT[1:0]	

Bits	Field	Type	Default	Description
7:2	Reserved	R/W	00 0000	
1:0	LOAD_CURRENT_BUCK_SELECT[1:0]	R/W	0x0	Start the current measurement on the selected converter core: 0x0 - BUCK0 0x1 - BUCK1 0x2 - BUCK2 0x3 - BUCK3 The measurement is started when register is written.

7.6.1.34 I_LOAD_2

Address: 0x22

D7	D6	D5	D4	D3	D2	D1	D0
Reserved						BUCK_LOAD_CURRENT[9:8]	

Bits	Field	Type	Default	Description
7:2	Reserved	R	00 0000	
1:0	BUCK_LOAD_CURRENT[9:8]	R	0x0	This register describes 2 MSB bits of the average load current on selected converter core with a resolution of 20 mA per LSB and maximum 20 A current.

7.6.1.35 I_LOAD_1

Address: 0x23

D7	D6	D5	D4	D3	D2	D1	D0
BUCK_LOAD_CURRENT[7:0]							

Bits	Field	Type	Default	Description
7:0	BUCK_LOAD_CURRENT[7:0]	R	0x0	This register describes 8 LSB bits of the average load current on selected converter core with a resolution of 20 mA per LSB and maximum 20-A current.

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The LP8758-E0 is designed for applications powered from a 2.5-V to 5.5-V input supply that require multiple power rails. The device provides four step-down converters. All the step-down converters support dynamic voltage scaling through I^2C interface to provide optimum power savings. The power sequencing of the four output voltage rails is programmable.

8.2 Typical Application

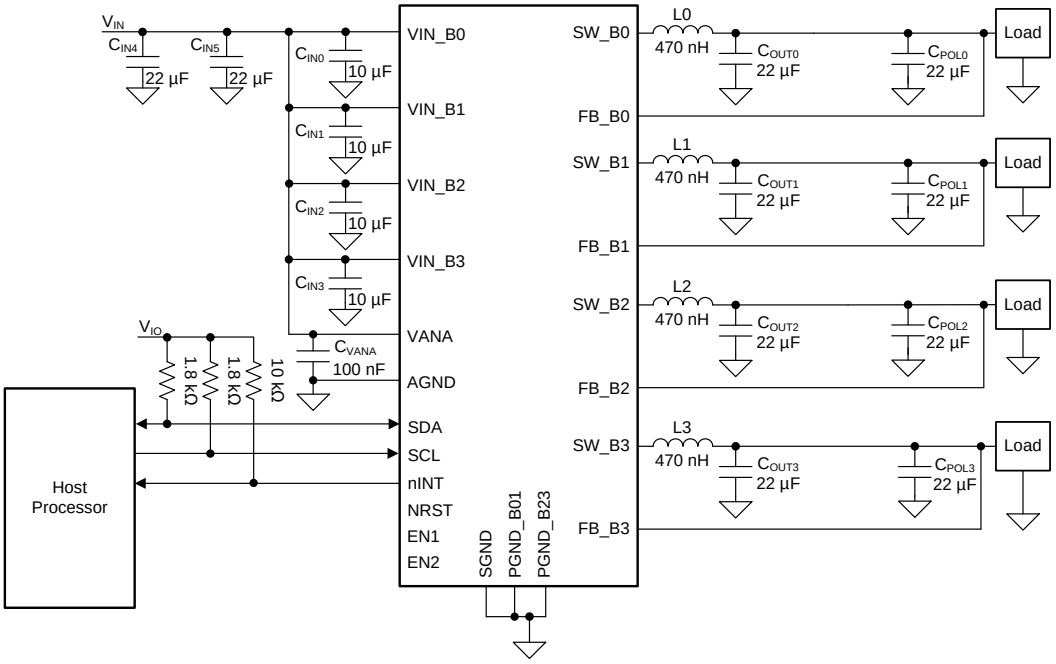


Figure 19. LP8758-E0 Typical Application Circuit

8.2.1 Design Requirements

Table 7. Design Parameters

DESIGN PARAMETER	EXAMPLE VALUE
Input voltage	3.3 V
Output voltages	1000 mV, 1200 mV, 1800 mV and 2500 mV
Converter operation mode	Auto mode (PWM-PFM)
Maximum load currents	1.5 A, 2.25 A, 3 A, 3 A
Inductor current limits	2.5 A, 3.5 A, 4.5 A, 4.5 A

In order to evenly distribute power dissipation in the device, it is best to assign the voltage rails as follows: Buck0 – 1000 mV, 2.5 A; Buck1 – 2500 mV, 4.5 A; Buck2 – 1200 mV, 3.5 A; and Buck3 – 1800 mV, 4.5 A. The default LP8758-E0 register settings are planned for this use-case. Start-up and shutdown with default values is shown in Figure 32.

8.2.2 Detailed Design Procedure

The performance of the LP8758-E0 device depends greatly on the care taken in designing the printed circuit board (PCB). The use of low-inductance and low serial-resistance ceramic capacitors is strongly recommended, while proper grounding is crucial. Attention must be given to decoupling the power supplies. Decoupling capacitors must be connected close to the device and between the power and ground pins to support high peak currents being drawn from system power rail during turnon of the switching MOSFETs. Keep input and output traces as short as possible, because trace inductance, resistance, and capacitance can easily become the performance limiting items. The separate power pins VIN_Bx are not connected together internally. The VIN_Bx power connections must be connected together outside the package using power plane construction.

8.2.2.1 Application Components

8.2.2.1.1 Inductor Selection

DC bias current characteristics of inductors must be considered. Different manufacturers follow different saturation current rating specifications, so attention must be given to details. DC bias curves should be requested from manufacturers as part of the inductor selection process. Minimum effective value of inductance to ensure good performance is 0.33 µH at 4.5 A (Buck3 and Buck1 default ILIMITP typical) bias current over the operating temperature range of the inductor. The DC resistance of the inductor must be less than 0.05 Ω for good efficiency at high-current condition. The inductor AC loss (resistance) also affects conversion efficiency. Higher Q factor at switching frequency usually gives better efficiency at light load to middle load. See Table 8. Shielded inductors are preferred as they radiate less noise.

Table 8. Recommended Inductors

MANUFACTURER	PART NUMBER	VALUE (µH)	DIMENSIONS L × W × H (mm)	DCR (mΩ)
MURATA	DFE201610E-R47M=P2	0.47	2 × 1.6 × 1	26 (typical), 32 (maximum)
TDK	VLS252010HBX-R47M	0.47	2.5 × 2 × 1	29 (typical), 35 (maximum)
TDK	TFM2016GHM-0R47M	0.47	2 × 1.6 × 1	46 (maximum)
TOKO	DFE322512C R47	0.47	3.2 × 2.5 × 1.2	21 (typical), 31 (maximum)

8.2.2.1.2 Input Capacitor Selection

A ceramic input capacitor of 10 µF, 6.3 V is sufficient for most applications. Place the power input capacitor as close as possible to the VIN_Bx pin and PGND_Bx pin of the device. A larger value or higher voltage rating may be used to improve input voltage filtering. Use X7R or X5R types; do not use Y5V or F. DC bias characteristics of ceramic capacitors must be considered when selecting case sizes like 0402. Minimum effective input capacitance to ensure good performance is 1.9 µF per buck input at maximum input voltage DC bias including tolerances and over ambient temp range, assuming that there are at least 22 µF of additional capacitance common for all the power input pins on the system power rail. See Table 9.

The input filter capacitor supplies current to the high-side FET switch in the first half of each cycle and reduces voltage ripple imposed on the input power source. A ceramic capacitor's low equivalent series resistance (ESR) provides the best noise filtering of the input voltage spikes due to this rapidly changing current. Select an input filter capacitor with sufficient ripple current rating.

The VANA input is used to supply analog and digital circuits in the device. See recommended components from Table 10 for VANA input supply filtering.

Table 9. Recommended Power Input Capacitors (X5R Dielectric)

MANUFACTURER	PART NUMBER	VALUE	CASE SIZE	DIMENSIONS L × W × H (mm)	VOLTAGE RATING (V)
Murata	GRM188R60J106ME47	10 µF (20%)	0603	1.6 × 0.8 × 0.8	6.3

Table 10. Recommended VANA Supply Filtering Components

MANUFACTURER	PART NUMBER	VALUE	CASE SIZE	DIMENSIONS L × W × H (mm)	VOLTAGE RATING (V)
Samsung	CL03A104KP3NNNC	100 nF (10%)	0201	0.6 × 0.3 × 0.3	10
Murata	GRM033R61A104KE84	100 nF (10%)	0201	0.6 × 0.3 × 0.3	6.3

8.2.2.1.3 Output Capacitor Selection

Use ceramic capacitors, X7R or X5R types; do not use Y5V or F. DC bias voltage characteristics of ceramic capacitors must be considered. DC bias characteristics vary from manufacturer to manufacturer, and DC bias curves should be requested from them as part of the capacitor selection process. The output filter capacitor smooths out current flow from the inductor to the load, helps maintain a steady output voltage during transient load changes and reduces output voltage ripple. These capacitors must be selected with sufficient capacitance and sufficiently low ESR and ESL to perform these functions. Minimum effective output capacitance to ensure good performance is 10 µF per output voltage rail at the output voltage DC bias, including tolerances and over ambient temp range.

The output voltage ripple is caused by the charging and discharging of the output capacitor and also due to its R_{ESR}. The R_{ESR} is frequency dependent (as well as temperature dependent); make sure the value used for selection process is at the switching frequency of the part. See Table 11.

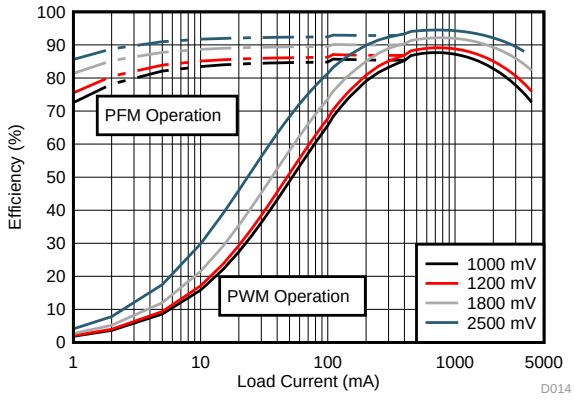
A higher output capacitance improves the load step behavior and reduces the output voltage ripple as well as decreases the PFM switching frequency. For most applications one 22-µF 0603 capacitor for C_{OUT} per voltage rail is suitable. A point-of-load (POL) capacitance C_{POL} can be added as shown in Figure 19. Although the loop compensation of the converter can be programmed to adapt to virtually several hundreds of microfarads C_{OUT}, it is preferable for C_{OUT} to be < 50 µF . Choosing higher than that is not necessarily of any benefit. Note that the output capacitor may be the limiting factor in the output voltage ramp, especially for very large (> 100 µF) output capacitors. For large output capacitors, the output voltage might be slower than the programmed ramp rate at voltage transitions, because of the higher energy stored on the output capacitance. Also at start-up, the time required to charge the output capacitor to target value might be longer. At shutdown, if the output capacitor is discharged by the internal discharge resistor, more time is required to settle V_{OUT} down as a consequence of the increased time constant.

Table 11. Recommended Output Capacitors (X5R Dielectric)

MANUFACTURER	PART NUMBER	VALUE	CASE SIZE	DIMENSIONS L × W × H (mm)	VOLTAGE RATING (V)
Samsung	CL10A226MP8NUNE	22 µF (20%)	0603	1.6 × 0.8 × 0.8	10
Murata	GRM188R60J226MEA0	22 µF (20%)	0603	1.6 × 0.8 × 0.8	6.3

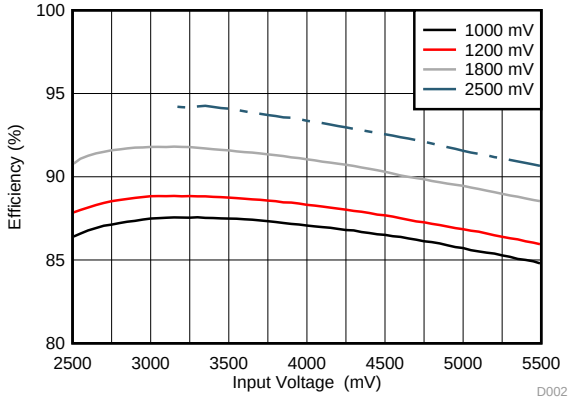
8.2.3 Application Curves

Measurements are done using typical application set up with connections shown in Figure 19. Graphs may not reflect the OTP default settings. Unless otherwise specified: V_{IN} = 3.7 V, $V_{(NRST)}$ = 1.8 V, T_A = 25 °C, f_{SW} = 3 MHz, L = 470 nH (TDK VLS252010HBX-R47M), $I_{LIM\ FWD}$ set to maximum 5 A.



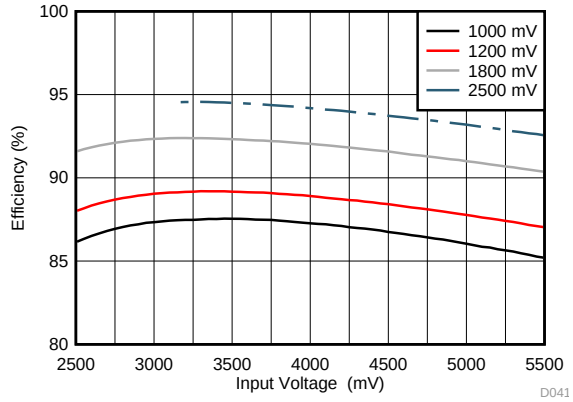
V_{IN} = 3.7 V
V_{OUT} settings = 1000 mV, 1200 mV, 1800 mV, and 2500 mV

Figure 20. Efficiency vs Load Current



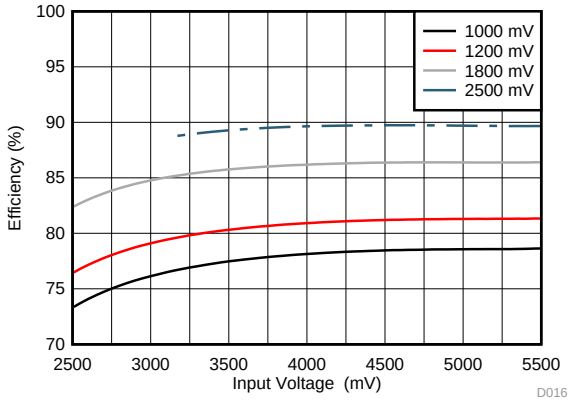
Load = 100 mA
V_{OUT} settings = 1000 mV, 1200 mV, 1800 mV and 2500 mV

Figure 21. Efficiency vs Input Voltage in PFM Mode



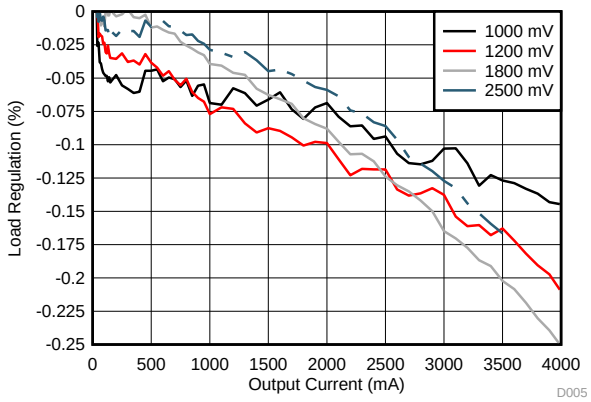
Load = 1A
V_{OUT} settings = 1000 mV, 1200 mV, 1800 mV and 2500 mV

Figure 22. Efficiency vs Input Voltage in PWM Mode



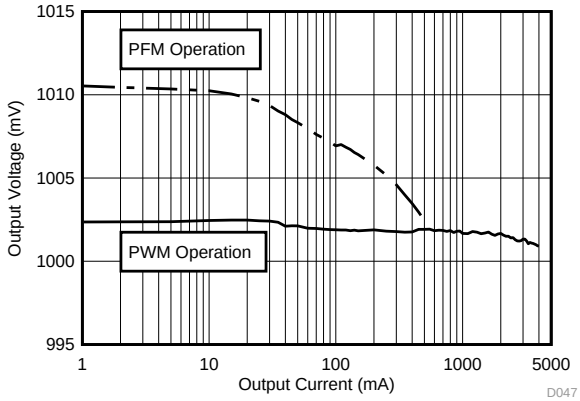
Load = 3A
V_{OUT} settings = 1000 mV, 1200 mV, 1800 mV and 2500 mV

Figure 23. Efficiency vs Input Voltage in PWM Mode



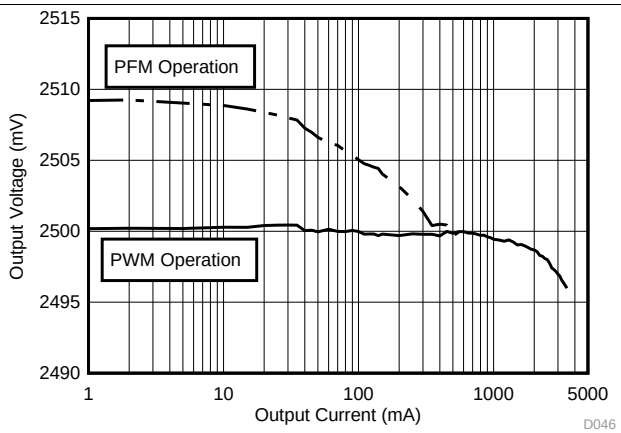
Change in Output Voltage from Zero Load (%)
V_{OUT} settings = 1000 mV, 1200 mV, 1800 mV and 2500 mV

Figure 24. DC Load Regulation in PWM mode



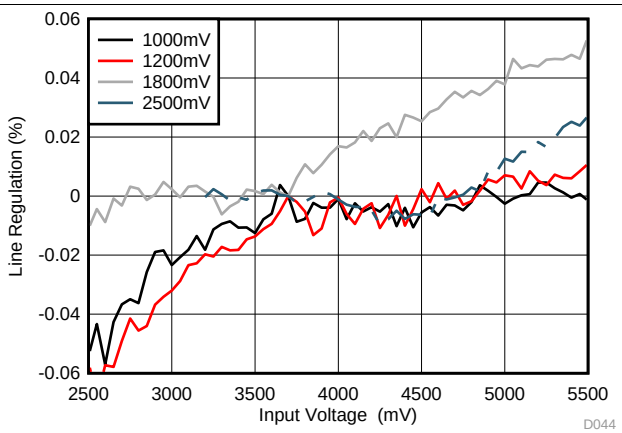
V_{OUT} setting = 1000 mV

Figure 25. Output Voltage vs Load Current in PWM-PFM Mode



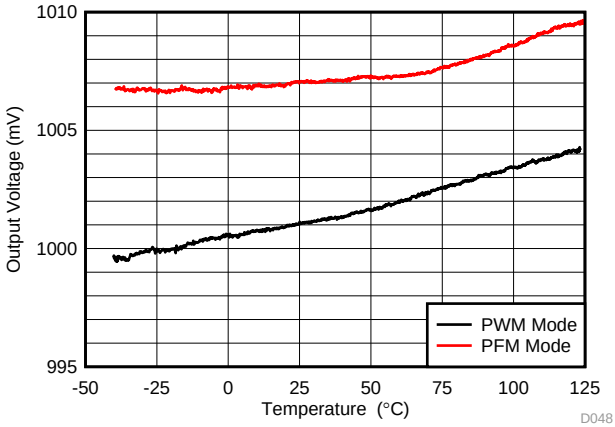
V_{OUT} setting = 2500 mV

Figure 26. Output Voltage vs Load Current in PWM-PFM Mode



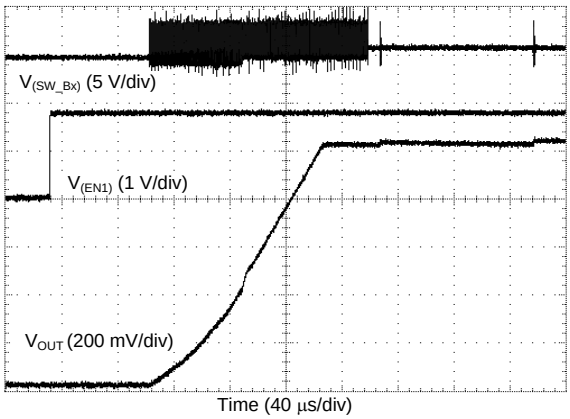
Change in Output Voltage from V_{IN} = 3.7 V (%) Load = 1 A
V_{OUT} settings = 1000 mV, 1200 mV, 1800 mV and 2500 mV

Figure 27. DC Line Regulation in PWM Mode



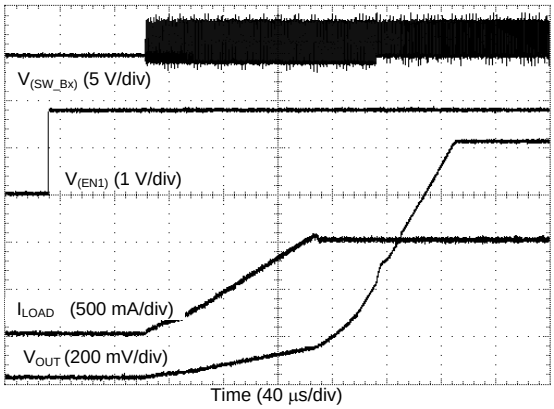
V_{OUT} setting = 1000 mV
Load = 1 A (PWM Mode) and 100 mA (PFM Mode)

Figure 28. Output Voltage vs Temperature



Load = 0 A

Figure 29. Start-up with EN1



Load = 1 A

Figure 30. Start-up with EN1

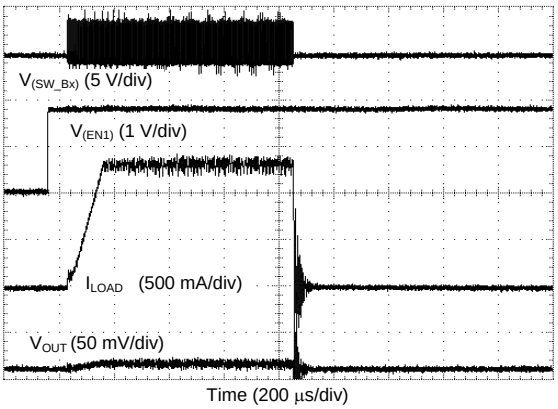
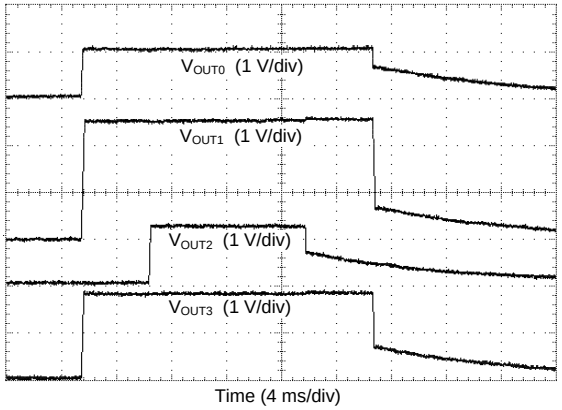


Figure 31. Start-up With Short on Output

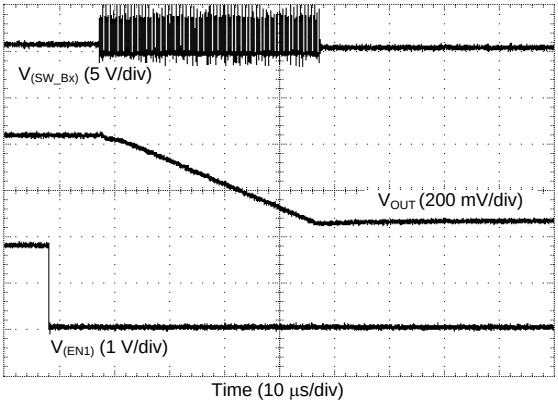


Load = 0 A

Enable and disable delays = default

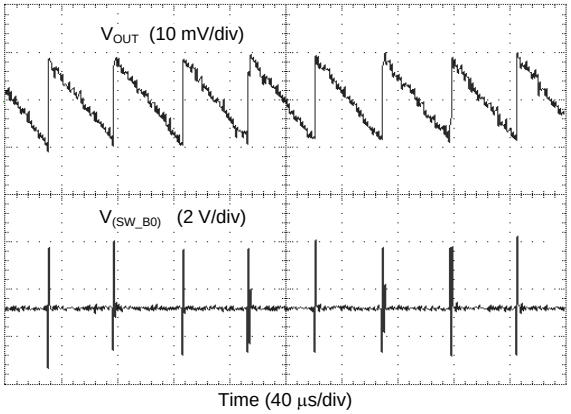
V_{OUT} settings = default

Figure 32. $V_{OUT0,1,2,3}$: Start-up and Shutdown with Default Register Settings, triggered by EN1.



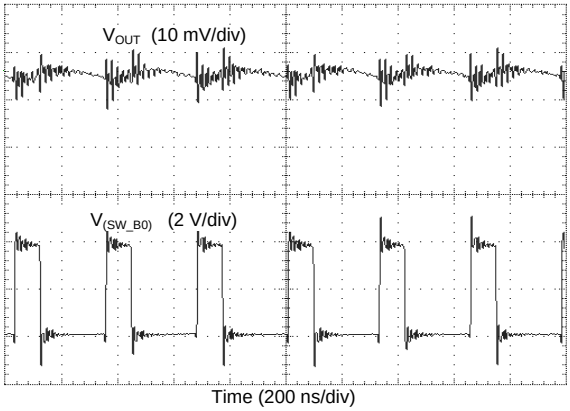
Load = 0 A

Figure 33. Shutdown with EN1



Load = 10 mA

Figure 34. Output Voltage Ripple, PFM Mode



Load = 200 mA

Figure 35. Output Voltage Ripple, Forced PWM Mode

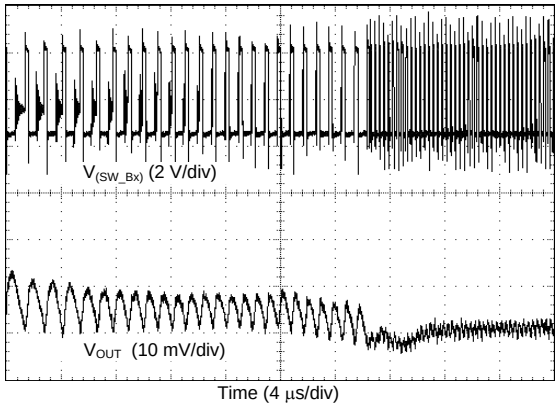


Figure 36. Transient from PFM-to-PWM Mode

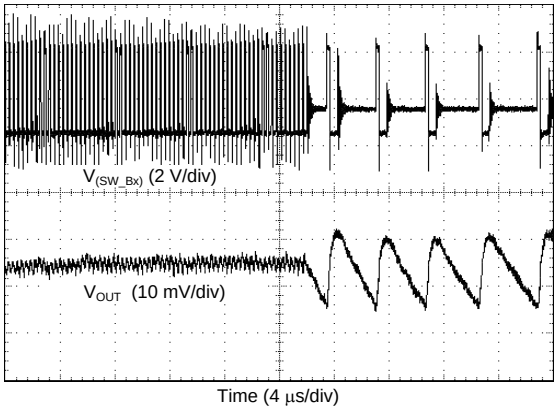
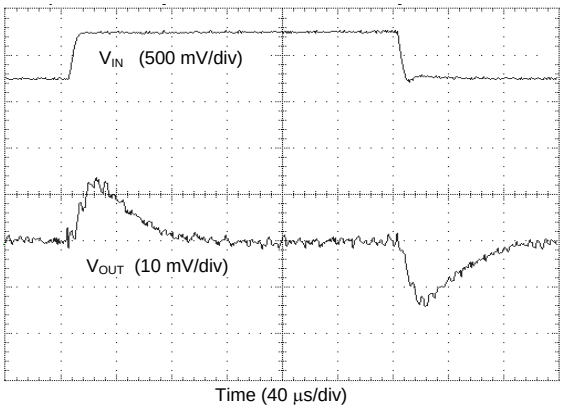


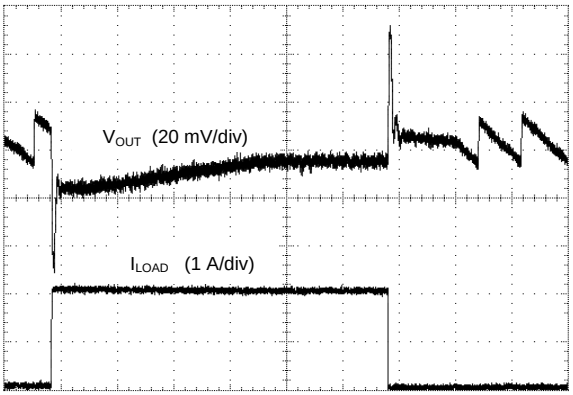
Figure 37. Transient from PWM-to-PFM Mode



Load = 4 A V_{OUT} = 1000 mV

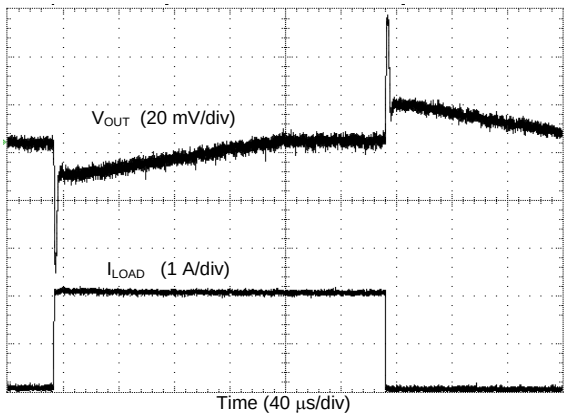
V_{IN} stepping 3.3 V ↔ 3.8 V, $T_R = T_F$ = 10 µs

Figure 38. Transient Line Response



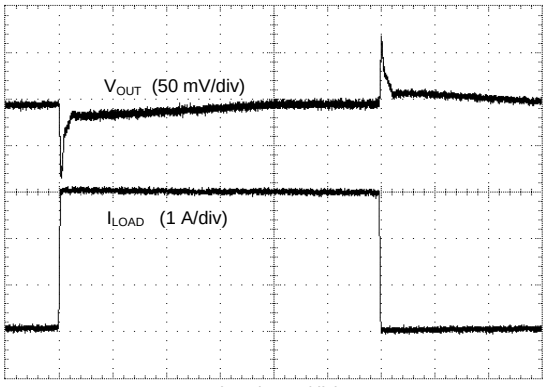
Load = 0 A → 2 A → 0 A $T_R = T_F$ = 400 ns V_{OUT} = 1 V

Figure 39. Transient Load Step Response, AUTO Mode



Load = 0 A → 2 A → 0 A $T_R = T_F$ = 400 ns V_{OUT} = 1 V

Figure 40. Transient Load Step Response, Forced PWM Mode



Load = 1A → 4 A → 1A $T_R = T_F$ = 1 µs V_{OUT} = 1 V

Figure 41. Transient Load Step Response, Forced PWM Mode

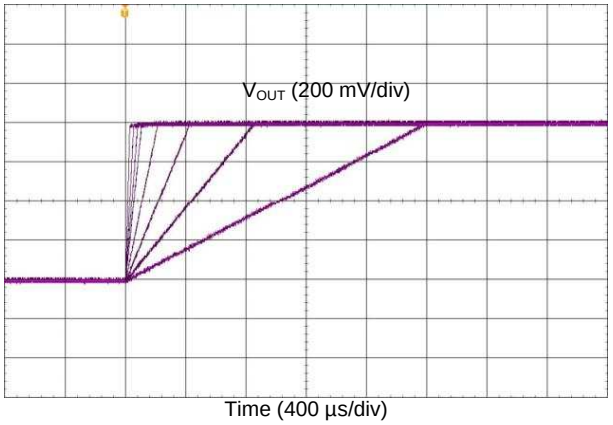


Figure 42. V_{OUT} Transition From 0.6 V to 1.4 V With Different Slew Rate Settings

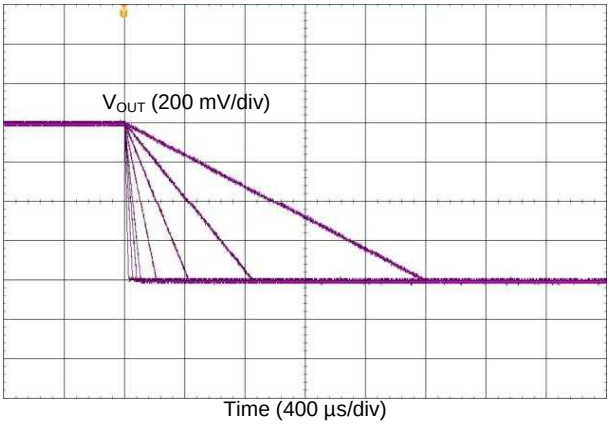


Figure 43. V_{OUT} Transition From 1.4 V to 0.6 V With Different Slew Rate Settings

9 Power Supply Recommendations

The device is designed to operate from an input voltage supply range between 2.5 V and 5.5 V. This input supply must be well-regulated and able to withstand maximum input current and maintain stable voltage without voltage drop even at load transition condition. The resistance of the input supply rail must be low enough that the input current transient does not cause too high drop in the LP8758-E0 supply voltage that can cause false UVLO fault triggering. If the input supply is located more than a few inches from the LP8758-E0 additional bulk capacitance may be required in addition to the ceramic bypass capacitors.

10 Layout

10.1 Layout Guidelines

The high frequency and large switching currents of the LP8758-E0 make the choice of layout important. Good power supply results only occur when care is given to proper design and layout. Layout affects noise pickup and generation and can cause a good design to perform with less-than-expected results. With a range of output currents from milliamps to 4 A per converter core, good power supply layout is much more difficult than most general PCB design. The following steps should be used as a reference to ensure the device is stable and maintains proper voltage and current regulation across its intended operating voltage and current range.

1. Place C_{IN} as close as possible to the VIN_Bx pin and the PGND_Bxx pin. Route the V_{IN} trace wide and thick to avoid IR drops. The trace between the positive node of the input capacitor and the LP8758-E0 VIN_Bx pin(s), as well as the trace between the input capacitor's negative node and power PGND_Bxx pin(s), must be kept as short as possible. The input capacitance provides a low-impedance voltage source for the switching converter. The inductance of the connection is the most important parameter of a local decoupling capacitor — parasitic inductance on these traces must be kept as tiny as possible for proper device operation.
2. The output filter, consisting of L_x and C_{OUTx}, converts the switching signal at SW_Bx to the noiseless output voltage. It must be placed as close as possible to the device keeping the switch node small, for best EMI behavior. Route the traces between the output capacitors of the device and the load (or input capacitors of the load) direct and wide to avoid losses due to the IR drop.
3. Input for analog blocks (VANA and AGND) must be isolated from noisy signals. Connect VANA directly to a quiet system voltage node and AGND to a quiet ground point where no IR drop occurs. Place the decoupling capacitor as close to the VANA pin as possible. VANA must be connected to the same power node as VIN_Bx pins.
4. If the load supports remote voltage sensing, connect the feedback pins FB_Bx of the device to the respective sense pins on the load. The sense lines are susceptible to noise. They must be kept away from noisy signals such as PGND_Bxx, VIN_Bx, and SW_Bx, as well as high bandwidth signals such as the I^2C. Avoid both capacitive as well as inductive coupling by keeping the sense lines short and direct. Run the lines in a quiet layer. Isolate them from noisy signals by a voltage or ground plane if possible.
5. PGND_Bxx, VIN_Bx and SW_Bx must be routed on thick layers. They must not surround inner signal layers which are not able to withstand interference from noisy PGND_Bxx, VIN_Bx and SW_Bx.

Due to the small package of this converter and the overall small solution size, the thermal performance of the PCB layout is important. Many system-dependent issues such as thermal coupling, airflow, added heat sinks and convection surfaces, and the presence of other heat-generating components affect the power dissipation limits of a given component. Proper PCB layout, focusing on thermal performance, results in lower die temperatures. Wide power traces come with the ability to sink dissipated heat. This can be improved further on multi-layer PCB designs with vias to different planes. This results in reduced junction-to-ambient ($R_{\theta JA}$) and junction-to-board ($R_{\theta JB}$) thermal resistances and thereby reduces the device junction temperature, T_J. Performing a careful system-level 2D or full 3D dynamic thermal analysis at the beginning product design process is strongly recommended, using a thermal modeling analysis software.

10.2 Layout Example

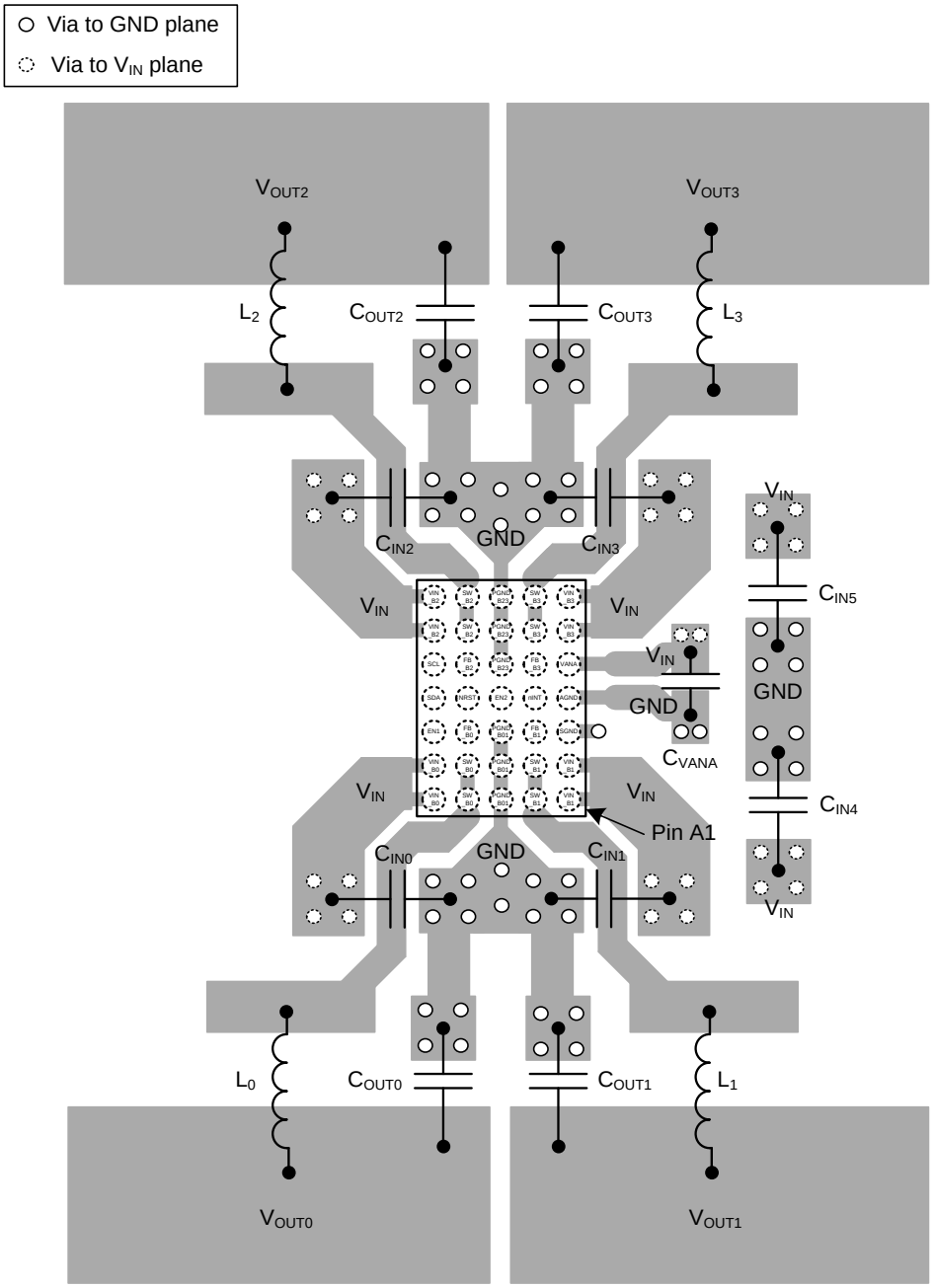


Figure 44. LP8758-E0 Board Layout

11 デバイスおよびドキュメントのサポート

11.1 デバイス・サポート

11.1.1 デベロッパー・ネットワークの製品に関する免責事項

デベロッパー・ネットワークの製品またはサービスに関するTIの出版物は、単独またはTIの製品、サービスと一緒に提供される場合に関係なく、デベロッパー・ネットワークの製品またはサービスの適合性に関する是認、デベロッパー・ネットワークの製品またはサービスの是認の表明を意味するものではありません。

11.2 ドキュメントのサポート

11.2.1 関連資料

関連資料については、以下を参照してください。

- テキサス・インスツルメンツ、*『DSBGAウェハー・レベルのチップ・スケール・パッケージ』アプリケーション・レポート*
- テキサス・インスツルメンツ、*『LP8758EVM評価モジュールの使用法』ユーザー・ガイド*

11.3 ドキュメントの更新通知を受け取る方法

ドキュメントの更新についての通知を受け取るには、ti.comのデバイス製品フォルダを開いてください。右上の隅にある「*通知を受け取る*」をクリックして登録すると、変更されたすべての製品情報に関するダイジェストを毎週受け取れます。変更の詳細については、修正されたドキュメントに含まれている改訂履歴をご覧ください。

11.4 コミュニティ・リソース

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™オンライン・コミュニティ ***TIのE2E（Engineer-to-Engineer）コミュニティ。エンジニア間の共同作業を促進するために開設されたものです。e2e.ti.comでは、他のエンジニアに質問し、知識を共有し、アイディアを検討して、問題解決に役立てることができます。***

設計サポート ***TIの設計サポート*** **役に立つE2Eフォーラムや、設計サポート・ ツールをすばやく見つけることができます。技術サポート用の連絡先情報も参照できます。**

11.5 商標

E2E is a trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

11.6 静電気放電に関する注意事項

すべての集積回路は、適切なESD保護方法を用いて、取扱いと保存を行うようにして下さい。

静電気放電はわずかな性能の低下から完全なデバイスの故障に至るまで、様々な損傷を与えます。高精度の集積回路は、損傷に対して敏感であり、極めてわずかなパラメータの変化により、デバイスに規定された仕様に適合しなくなる場合があります。

11.7 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 メカニカル、パッケージ、および注文情報

以降のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。この情報は、そのデバイスについて利用可能な最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もあります。本データシートのブラウザ版を使用されている場合は、画面左側の説明をご覧ください。

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package | Pins	Package qty | Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
LP8758A1E0YFFR	Active	Production	DSBGA (YFF) | 35	3000 | LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	8758A1E0
LP8758A1E0YFFR.A	Active	Production	DSBGA (YFF) | 35	3000 | LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	8758A1E0

(1) **Status:** For more details on status, see our product life cycle.

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

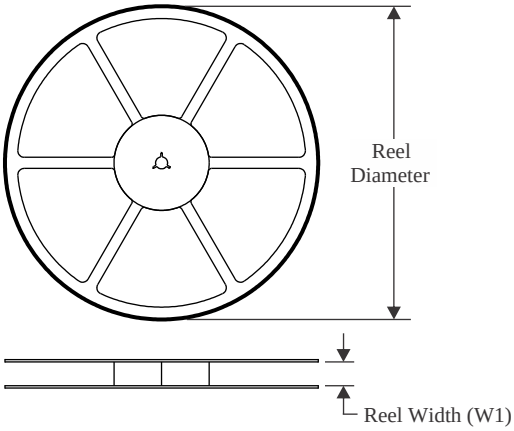
(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

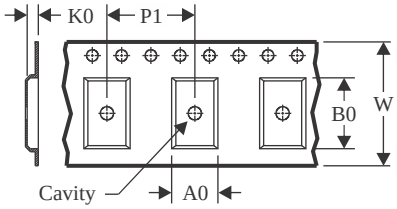
Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

TAPE AND REEL INFORMATION

REEL DIMENSIONS

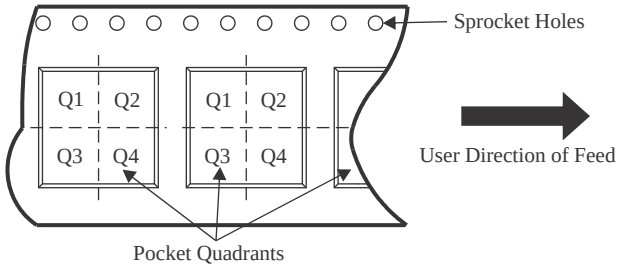


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

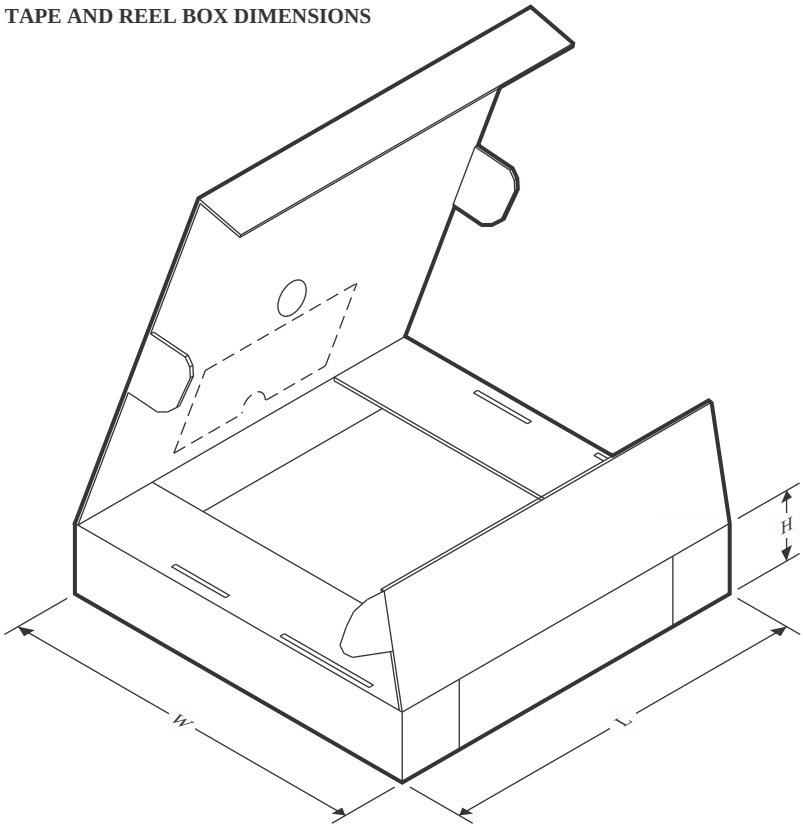
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LP8758A1E0YFFR	DSBGA	YFF	35	3000	180.0	8.4	2.28	3.03	0.74	4.0	8.0	Q1

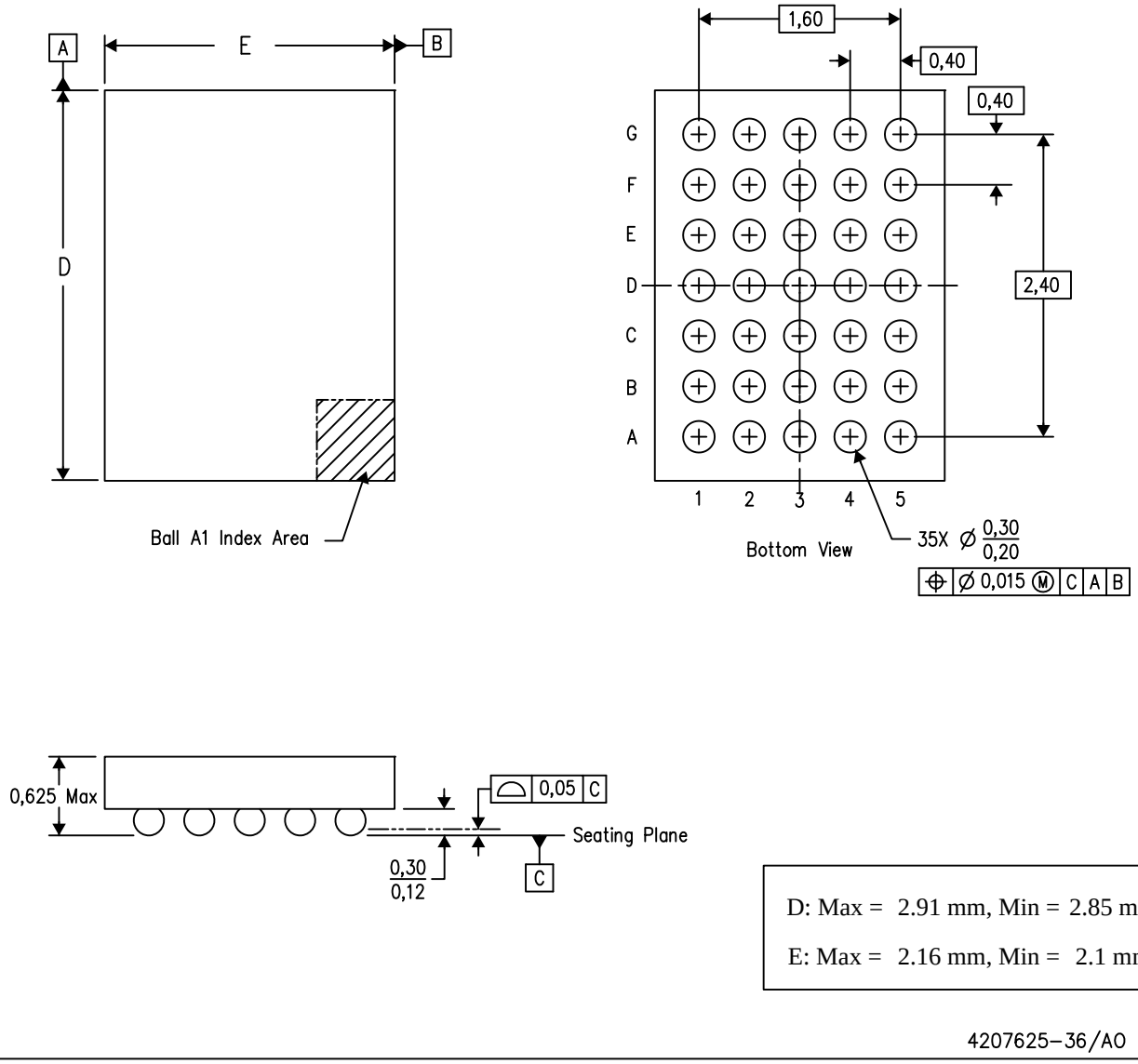
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LP8758A1E0YFFR	DSBGA	YFF	35	3000	182.0	182.0	20.0

YFF (R–XBGA–N35) DIE–SIZE BALL GRID ARRAY



D: Max = 2.91 mm, Min = 2.85 mm

E: Max = 2.16 mm, Min = 2.1 mm

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NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M–1994.
B. This drawing is subject to change without notice.
C. NanoFree™ package configuration.

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