





I MG1205 JAJSD27B - MARCH 2017 - REVISED APRIL 2023

# LMG1205 ブートストラップ・ダイオード内蔵の 80V、1.2A~5A、ハー リッジ GaN ドライバ

### 1 特長

- ハイサイドとローサイドで独立した TTL ロジック入力
- ピーク・ソース 1.2A、シンク電流 5A
- ハイサイドのフローティング・バイアス電圧レールは 最高 DC 100V で動作可能
- 内部ブートストラップ電源電圧クランプ
- 出力の分割により、ターンオンおよび ターンオフの強度を調整可能
- プルダウン 0.6Ω、プルアップ 2.1Ω の抵抗
- 短い伝播遅延 (標準値 35ns)
- 優れた伝搬遅延マッチング (標準値 1.5ns)
- 電源レールの低電圧誤動作防止
- 低消費電力

# 2 アプリケーション

- 電流供給プッシュプル・コンバータ
- ハーフおよびフルブリッジ・コンバータ
- 同期整流降圧コンバータ
- 2 スイッチ・フォワード・コンバータ
- アクティブ・クランプ型フォワード・コンバータ

### 3 概要

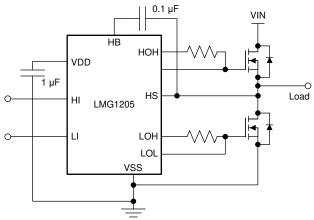
LMG1205 は、同期整流降圧、昇圧、またはハーフブリッ ジ構成で、ハイサイドとローサイドの両方のエンハンスメン ト・モード窒化ガリウム (GaN) FET を駆動できるように設 計されています。このデバイスには 100V のブートストラッ プ・ダイオード、およびハイサイドとローサイド出力用に独 立した入力が内蔵され、最大の柔軟性で制御が可能で す。ハイサイドのバイアス電圧はブートストラップ技法を使 用して生成され、内部で 5V にクランプされます。これによ って、ゲート電圧がエンハンスメント・モード GaN FET の 最大ゲート・ソース電圧定格を超過しなくなります。 LMG1205 の入力は TTL ロジック互換で、VDD 電圧に 関係なく最大 14V の入力電圧に耐えることができます。 LMG1205 には分割ゲート出力があり、ターンオンとター ンオフの強度を別々に調整可能な柔軟性があります。

さらに、LM1205 の強力なシンク能力によりゲートが LOW 状態で維持され、スイッチング時に意図しないターンオン が防止されます。LMG1205 の最大動作周波数は数 MHz です。LMG1205 は、占有面積が小さく、パッケージ のインダクタンスが最小化された、12 ピンの DSBGA パッ ケージで供給されます。

#### デバイス情報(1)

部品番号	パッケージ	本体サイズ (公称)
LMG1205	DSBGA (12)	2.00mm × 2.00mm

利用可能なすべてのパッケージについては、このデータシートの 末尾にある注文情報を参照してください。



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アプリケーション概略図



# **Table of Contents**

1 特長	1	7.4 Device Functional Modes	12
2 アプリケーション		8 Application and Implementation	13
3 概要		8.1 Application Information	13
4 Revision History		8.2 Typical Application	13
5 Pin Configuration and Functions		9 Power Supply Recommendations	17
6 Specifications		10 Layout	18
6.1 Absolute Maximum Ratings		10.1 Layout Guidelines	18
6.2 ESD Ratings		10.2 Layout Examples	18
6.3 Recommended Operating Conditions		11 Device and Documentation Support	19
6.4 Thermal Information		11.1 Device Support	19
6.5 Electrical Characteristics		11.2 Documentation Support	19
6.6 Switching Characteristics		11.3ドキュメントの更新通知を受け取る方法	19
6.7 Typical Characteristics		11.4 サポート・リソース	19
7 Detailed Description		11.5 Trademarks	
7.1 Overview		11.6 静電気放電に関する注意事項	19
7.2 Functional Block Diagram		11.7 用語集	
7.3 Feature Description			

# **4 Revision History**

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Page
1
12
14
Page
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# **5 Pin Configuration and Functions**

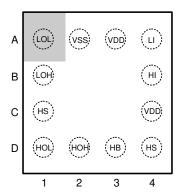


図 5-1. YFX Package 12-Pin DSBGA Top View

表 5-1. Pin Functions

PIN		TYPE (2)	DESCRIPTION		
NUMBER	NAME	11175	DESCRIPTION		
A1	LOL	0	Low-side gate driver sink-current output: connect to the gate of the low-side GaN FET with a short, low inductance path. A gate resistor can be used to adjust the turnoff speed.		
A2	VSS	G	Ground return: all signals are referenced to this ground.		
A3, C4 <sup>(1)</sup>	VDD	Р	5-V positive gate drive supply: locally decouple to VSS using low ESR/ESL capacitor located as close as possible to the IC.		
A4	LI	I	Low-side driver control input. The LMG1205 inputs have TTL type thresholds. Unused inputs must be tied to ground and not left open.		
B1	LOH	0	Low-side gate driver source-current output: connect to the gate of low-side GaN FET with short, low inductance path. A gate resistor can be used to adjust the turnon speed.		
B4	НІ	I	High-side driver control input. The LMG1205 inputs have TTL type thresholds. Unused inputs must be tied to ground and not left open.		
C1, D4 <sup>(1)</sup>	HS	Р	High-side GaN FET source connection: connect to the bootstrap capacitor negative terminal and the source of the high-side GaN FET.		
D1	HOL	0	High-side gate driver turnoff output: connect to the gate of high-side GaN FET with a short, low inductance path. A gate resistor can be used to adjust the turnoff speed.		
D2	нон	0	High-side gate driver turnon output: connect to the gate of high-side GaN FET with a short, low inductance path. A gate resistor can be used to adjust the turnon speed.		
D3	НВ	Р	High-side gate driver bootstrap rail: connect the positive terminal of the bootstrap capacitor to HB and the negative terminal to HS. The bootstrap capacitor must be placed as close as possible to the IC.		

<sup>(1)</sup> A3 and C4, C1 and D4 are internally connected

<sup>(2)</sup> I = Input, O = Output, G = Ground, P = Power



# **6 Specifications**

# **6.1 Absolute Maximum Ratings**

over operating free-air temperature range (unless otherwise noted)(1)

	MIN	MAX	UNIT
VDD to VSS	-0.3	7	V
HB to HS	-0.3	7	V
LI or HI input	-0.3	15	V
LOH, LOL output	-0.3	VDD +0.3	V
HOH, HOL output	V <sub>HS</sub> - 0.3	V <sub>HB</sub> +0.3	V
HS to VSS	<b>-</b> 5	93	V
HS to VSS (2)	-5	100	V
HB to VSS	0	100	V
HB to VSS <sup>(2)</sup>	0	107	V
Operating junction temperature		150	°C
Storage temperature, T <sub>stg</sub>	<b>–</b> 55	150	°C

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

# 6.2 ESD Ratings

			VALUE	UNIT
V		Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±1000	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
V <sub>(E</sub>	SD) Liectrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500	V

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

### **6.3 Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted)

	MIN	NOM MAX	UNIT
VDD	4.5	5.5	V
LI or HI input	0	14	V
HS	<b>-</b> 5	90	V
НВ	V <sub>HS</sub> + 4	V <sub>HS</sub> + 5.5	V
HS slew rate		50	V/ns
Operating junction temperature	-40	125	°C

#### 6.4 Thermal Information

		LMG1205	
	THERMAL METRIC <sup>(1)</sup>	YFX (DSBGA)	UNIT
		12 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	76.8	°C/W
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	0.6	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	12.0	°C/W
ΨЈТ	Junction-to-top characterization parameter	1.6	°C/W

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<sup>(2)</sup> Device can withstand 1000 pulses up to the value indicated in the table of 100-ms duration and less than 1% duty cycle over its lifetime.

<sup>(2)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



# 6.4 Thermal Information (continued)

	LMG1205	
THERMAL METRIC(1)	YFX (DSBGA)	UNIT
	12 PINS	
$\psi_{JB}$ Junction-to-board characterization parameter	12.0	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.



### **6.5 Electrical Characteristics**

Specifications are  $T_J$  = 25°C. Unless otherwise specified:  $V_{DD}$  =  $V_{HB}$  = 5 V,  $V_{SS}$  =  $V_{HS}$  = 0 V. No load on LOL and HOL or HOH and HOL<sup>(1)</sup>.

	PARAMETER	TEST CON	DITIONS	MIN	TYP	MAX	UNIT
SUPPL	Y CURRENTS						
	1/00	LI = HI = 0 V, V <sub>DD</sub> = V <sub>HB</sub> =	T <sub>J</sub> = 25°C		0.09		
I <sub>DD</sub>	VDD quiescent current	4 V	T <sub>J</sub> = -40°C to 125°C			0.12	mA
			T <sub>J</sub> = 25°C		2		
I <sub>DDO</sub>	VDD operating current	f = 500 kHz	T <sub>J</sub> = -40°C to 125°C			3	mA
	T-A-LUD	LI = HI = 0 V, V <sub>DD</sub> = V <sub>HB</sub> =	T <sub>J</sub> = 25°C		0.10		1
I <sub>HB</sub>	Total HB quiescent current	4 V	T <sub>J</sub> = -40°C to 125°C			0.12	mA
	T-A-LUD	£ 500 H.L.	T <sub>J</sub> = 25°C	,	1.5		4
Інво	Total HB operating current	f = 500 kHz	T <sub>J</sub> = -40°C to 125°C			2.5	mA
	LID to MOO mails and assess	110 110 001/	T <sub>J</sub> = 25°C		0.1		
I <sub>HBS</sub>	HB to VSS quiescent current	HS = HB = 80 V	T <sub>J</sub> = -40°C to 125°C			8	μA
	LID to MOO on another an arrant	£ 500 H.L.	T <sub>J</sub> = 25°C	,	0.4		4
I <sub>HBSO</sub>	HB to VSS operating current	f = 500 kHz	T <sub>J</sub> = -40°C to 125°C	,		1	mA
INPUT	PINS						
		B	T <sub>J</sub> = 25°C		2.06		V
$V_{IR}$	Input voltage threshold	Rising edge	T <sub>J</sub> = -40°C to 125°C	1.89		2.18	
. ,			T <sub>J</sub> = 25°C		1.66		
$V_{IF}$	Input voltage threshold	Falling edge	T <sub>J</sub> = -40°C to 125°C	1.48		1.76	V
V <sub>IHYS</sub>	Input voltage hysteresis				400		mV
		T <sub>J</sub> = 25°C			200		
R <sub>I</sub>	Input pulldown resistance	$T_J = -40^{\circ}\text{C to } 125^{\circ}\text{C}$		100		300	kΩ
UNDE	RVOLTAGE PROTECTION		I				
		T <sub>J</sub> = 25°C			3.8		
$V_{DDR}$	VDD rising threshold	T <sub>J</sub> = -40°C to 125°C		3.2		4.5	V
V <sub>DDH</sub>	VDD threshold hysteresis				0.2		V
		T <sub>J</sub> = 25°C			3.2		
$V_{HBR}$	HB rising threshold	$T_J = -40^{\circ}\text{C to } 125^{\circ}\text{C}$		2.5		3.9	V
V <sub>HBH</sub>	HB threshold hysteresis				0.2		V
воот	STRAP DIODE AND CLAMP						
			T <sub>J</sub> = 25°C		0.45		
$V_{DL}$	Low-current forward voltage	I <sub>VDD-HB</sub> = 100 μA	T <sub>J</sub> = -40°C to 125°C			0.65	V
			T <sub>J</sub> = 25°C		0.9		
$V_{DH}$	High-current forward voltage	I <sub>VDD-HB</sub> = 100 mA	T <sub>J</sub> = -40°C to 125°C	,		1	V
		1	T <sub>J</sub> = 25°C		1.85		
$R_D$	Dynamic resistance	$I_{VDD-HB} = 100 \text{ mA}$	T <sub>J</sub> = -40°C to 125°C			3.6	Ω
			T <sub>J</sub> = 25°C		5		
	HB-HS clamp regulation voltage		T <sub>J</sub> = -40°C to 125°C	4.5		5.25	V

# **6.5 Electrical Characteristics (continued)**

Specifications are  $T_J$  = 25°C. Unless otherwise specified:  $V_{DD}$  =  $V_{HB}$  = 5 V,  $V_{SS}$  =  $V_{HS}$  = 0 V. No load on LOL and HOL or HOH and HOL<sup>(1)</sup>.

	PARAMETER	TEST CO	NDITIONS	MIN	TYP	MAX	UNIT
LOW-	and HIGH-SIDE GATE DRIVER						
V <sub>OL</sub>	Low-level output voltage	1 -1 -100 mA	T <sub>J</sub> = 25°C		0.06		V
		$I_{HOL} = I_{LOL} = 100 \text{ mA}$	$T_J = -40^{\circ}\text{C to } 125^{\circ}\text{C}$			0.1	
	High-level output voltage		T <sub>J</sub> = 25°C		0.21		
V <sub>OH</sub>	V <sub>OH</sub> = VDD – LOH or V <sub>OH</sub> = HB – HOH	$I_{HOH} = I_{LOH} = 100 \text{ mA}$	$T_J = -40^{\circ}\text{C to } 125^{\circ}\text{C}$			0.31	V
I <sub>OHL</sub>	Peak source current	HOH, LOH = 0 V			1.2		Α
I <sub>OLL</sub>	Peak sink current	HOL, LOL = 5 V			5		Α

# **6.6 Switching Characteristics**

over operating free-air temperature range (unless otherwise noted)

	PARAMETER	TEST CON	DITIONS	MIN	TYP	MAX	UNIT	
t <sub>LPHL</sub>	LO turnoff propagation delay	LI falling to LOL falling	T <sub>J</sub> = 25°C		33.5			
			$T_J = -40^{\circ}\text{C to } 125^{\circ}\text{C}$			50	ns	
t <sub>LPLH</sub>	LO turnon propagation delay	LI rising to LOH rising	T <sub>J</sub> = 25°C		35		ns	
			$T_J = -40^{\circ}\text{C to } 125^{\circ}\text{C}$			50	115	
t <sub>HPHL</sub>	HO turnoff propagation delay	HI falling to HOL falling	T <sub>J</sub> = 25°C		33.5		ns	
			$T_J = -40^{\circ}\text{C to } 125^{\circ}\text{C}$			50	113	
t <sub>HPLH</sub>	HO turnon propagation delay	HI rising to HOH rising	T <sub>J</sub> = 25°C		35		ns	
			$T_J = -40^{\circ}\text{C to } 125^{\circ}\text{C}$			50	113	
t <sub>MON</sub>	Delay matching	T <sub>J</sub> = 25°C			1.5		ns	
	LO on and HO off	T <sub>J</sub> = -40°C to 125°C			8	8	115	
t <sub>MOFF</sub>	Delay matching	T <sub>J</sub> = 25°C			1.5		ns	
	LO off and HO on	T <sub>J</sub> = -40°C to 125°C				8	115	
t <sub>HRC</sub>	HO rise time (0.5 V – 4.5 V)	C <sub>L</sub> = 1000 pF			7		ns	
t <sub>LRC</sub>	LO rise time (0.5 V – 4.5 V)	C <sub>L</sub> = 1000 pF			7		ns	
t <sub>HFC</sub>	HO fall time (0.5 V – 4.5 V)	C <sub>L</sub> = 1000 pF			3.5		ns	
t <sub>LFC</sub>	LO fall time (0.5 V – 4.5 V)	C <sub>L</sub> = 1000 pF			3.5		ns	
t <sub>PW</sub>	Minimum input pulse width that changes the output				10		ns	
t <sub>BS</sub>	Bootstrap diode reverse recovery time	I <sub>F</sub> = 100 mA, I <sub>R</sub> = 100 mA			40		ns	

<sup>(1)</sup> Parameters that show only a typical value are ensured by design and may not be tested in production.



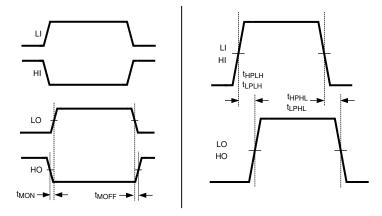
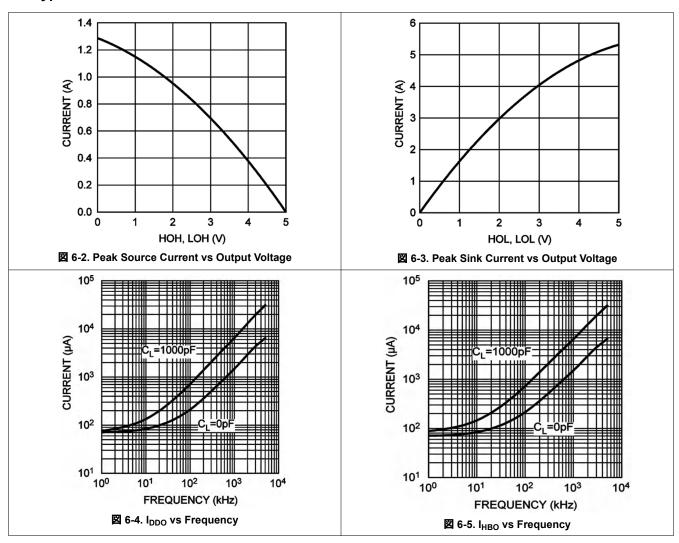


図 6-1. Timing Diagram

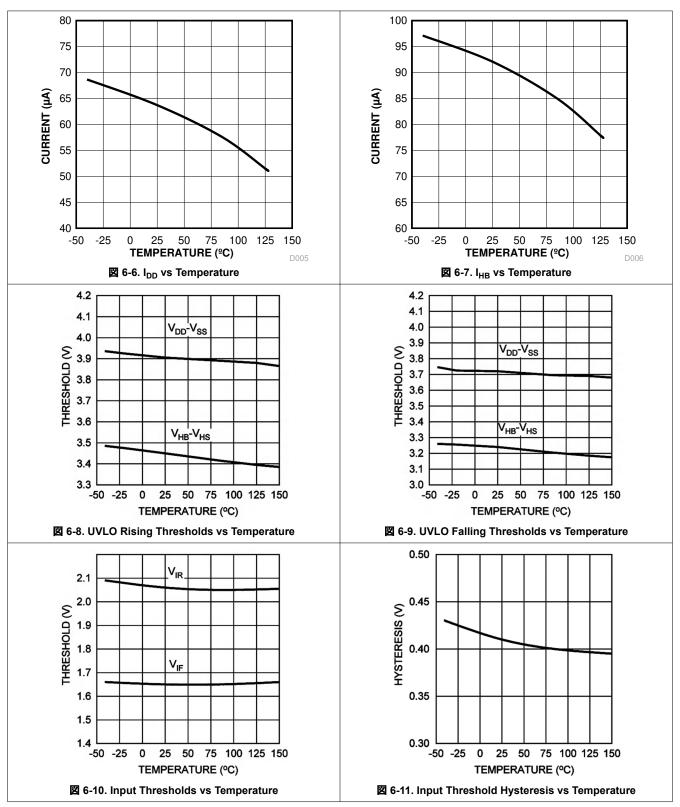
# **6.7 Typical Characteristics**



English Data Sheet: SNOSD37

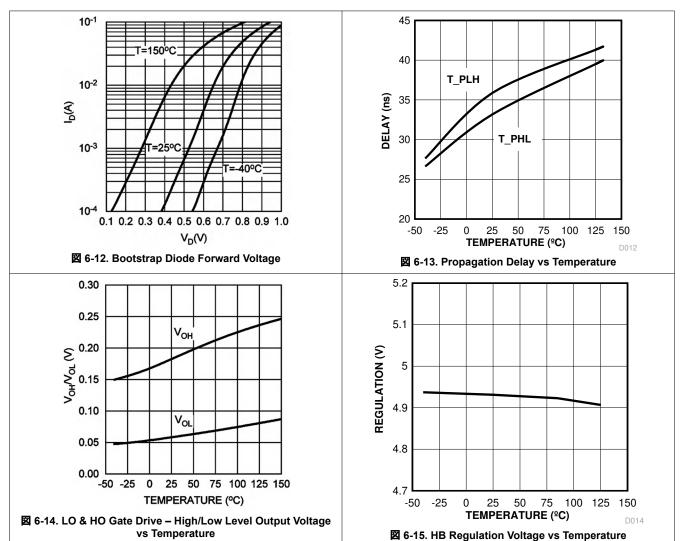


# **6.7 Typical Characteristics (continued)**





# 6.7 Typical Characteristics (continued)



English Data Sheet: SNOSD37

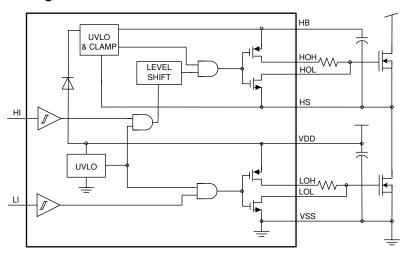
# 7 Detailed Description

### 7.1 Overview

The LMG1205 is a high frequency high- and low- side gate driver for enhancement mode Gallium Nitride (GaN) FETs in a synchronous buck, boost, or half-bridge configuration. The high-side bias voltage is generated using a bootstrap technique and is internally clamped at 5 V, which prevents the gate voltage from exceeding the maximum gate-source voltage rating of enhancement mode GaN FETs. The LMG1205 has split-gate outputs with strong sink capability, providing flexibility to adjust the turnon and turnoff strength independently.

The LMG1205 can operate up to several MHz, and is available in a 12-pin DSBGA package that offers a compact footprint and minimized package inductance.

### 7.2 Functional Block Diagram



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# 7.3 Feature Description

## 7.3.1 Input and Output

The input pins of the LMG1205 are independently controlled with TTL input thresholds and can withstand voltages up to 12 V regardless of the VDD voltage. This allows the inputs to be directly connected to the outputs of an analog PWM controller with up to 12-V power supply, eliminating the need for a buffer stage.

The output pulldown and pullup resistance of LMG1205 is optimized for enhancement mode GaN FETs to achieve high frequency and efficient operation. The 0.6- $\Omega$  pulldown resistance provides a robust low impedance turnoff path necessary to eliminate undesired turnon induced by high dv/dt or high di/dt. The 2.1- $\Omega$  pullup resistance helps reduce the ringing and over-shoot of the switch node voltage. The split outputs of the LMG1205 offers flexibility to adjust the turnon and turnoff speed by independently adding additional impedance in either the turnon path and/or the turnoff path.

If the input signal for either of the two channels, HI or LI, is not used, the control pin must be tied to either VDD or VSS. These inputs must not be left floating.

### 7.3.2 Start-up and UVLO

The LMG1205 has an undervoltage lockout (UVLO) on both the VDD and bootstrap supplies. When the VDD voltage is below the threshold voltage of 3.8 V, both the HI and LI inputs are ignored, to prevent the GaN FETs from being partially turned on. Also, if there is insufficient VDD voltage, the UVLO actively pulls the LOL and HOL low. When the VDD voltage is above its UVLO threshold, but the HB to HS bootstrap voltage is below the UVLO threshold of 3.2 V, only HOL is pulled low. Both UVLO threshold voltages have 200 mV of hysteresis to avoid chattering.



表 7-1. VDD UVLO Feature Logic Operation

CONDITION (V <sub>HB-HS</sub> > V <sub>HBR</sub> for all cases below)	HI	LI	НО	LO
V <sub>DD</sub> - V <sub>SS</sub> < V <sub>DDR</sub> during device start-up	Н	L	L	L
V <sub>DD</sub> - V <sub>SS</sub> < V <sub>DDR</sub> during device start-up	L	Н	L	L
V <sub>DD</sub> - V <sub>SS</sub> < V <sub>DDR</sub> during device start-up	Н	Н	L	L
V <sub>DD</sub> - V <sub>SS</sub> < V <sub>DDR</sub> during device start-up	L	L	L	L
V <sub>DD</sub> - V <sub>SS</sub> < V <sub>DDR</sub> - V <sub>DDH</sub> after device start-up	Н	L	L	L
V <sub>DD</sub> - V <sub>SS</sub> < V <sub>DDR</sub> - V <sub>DDH</sub> after device start-up	L	Н	L	L
V <sub>DD</sub> - V <sub>SS</sub> < V <sub>DDR</sub> - V <sub>DDH</sub> after device start-up	Н	Н	L	L
V <sub>DD</sub> - V <sub>SS</sub> < V <sub>DDR</sub> - V <sub>DDH</sub> after device start-up	L	L	L	L

表 7-2. V<sub>HB-HS</sub> UVLO Feature Logic Operation

CONDITION (V <sub>DD</sub> > V <sub>DDR</sub> for all cases below)	HI	LI	НО	LO
V <sub>HB-HS</sub> < V <sub>HBR</sub> during device start-up	Н	L	L	L
V <sub>HB-HS</sub> < V <sub>HBR</sub> during device start-up	L	Н	L	Н
V <sub>HB-HS</sub> < V <sub>HBR</sub> during device start-up	Н	Н	L	Н
V <sub>HB-HS</sub> < V <sub>HBR</sub> during device start-up	L	L	L	L
V <sub>HB-HS</sub> < V <sub>HBR</sub> - V <sub>HBH</sub> after device start-up	Н	L	L	L
V <sub>HB-HS</sub> < V <sub>HBR</sub> - V <sub>HBH</sub> after device start-up	L	Н	L	Н
V <sub>HB-HS</sub> < V <sub>HBR</sub> - V <sub>HBH</sub> after device start-up	Н	Н	L	Н
V <sub>HB-HS</sub> < V <sub>HBR</sub> - V <sub>HBH</sub> after device start-up	L	L	L	L

### 7.3.3 HS Negative Voltage and Bootstrap Supply Voltage Clamping

Due to the intrinsic nature of enhancement mode GaN FETs, the source-to-drain voltage of the bottom switch is usually higher than a diode forward voltage drop when the gate is pulled low. This causes negative voltage on HS pin. Moreover, this negative voltage transient may become even more pronounced due to the effects of board layout and device drain/source parasitic inductances. With high-side driver using the floating bootstrap configuration, negative HS voltage can lead to an excessive bootstrap voltage, which can damage the high-side GaN FET. The LMG1205 solves this problem with an internal clamping circuit that prevents the bootstrap voltage from exceeding 5 V typical. The clamping circuit works by opening an internal switch in series with the internal bootstrap diode when the bootstrap voltage exceeds the threshold, preventing further charging. The clamping circuit has a delay of about 270 ns between the threshold being exceeded and charging being stopped. In addition, the clamping circuit is bypassed if an external bootstrap diode is used.

#### 7.3.4 Level Shift

The level-shift circuit is the interface from the high-side input to the high-side driver stage which is referenced to the switch node (HS). The level shift allows control of the HO output, which is referenced to the HS pin and provides excellent delay matching with the low-side driver. Typical delay matching between LO and HO is around 1.5 ns.

#### 7.4 Device Functional Modes

表 7-3 shows the device truth table.

表 7-3. Truth Table

HI	LI	нон	HOL	LOH	LOL
L	L	Open	L	Open	L
L	Н	Open	L	Н	Open
Н	L	Н	Open	Open	L
Н	Н	Н	Open	Н	Open

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# 8 Application and Implementation

注

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### 8.1 Application Information

To operate GaN transistors at very high switching frequencies and to reduce associated switching losses, a powerful gate driver is employed between the PWM output of controller and the gates of the GaN transistor. Also, gate drivers are indispensable when the outputs of the PWM controller do not meet the voltage or current levels needed to directly drive the gates of the switching devices. With the advent of digital power, this situation is often encountered because the PWM signal from the digital controller is often a 3.3-V logic signal, which cannot effectively turn on a power switch. A level-shift circuit is needed to boost the 3.3 V signal to the gate-drive voltage (such as 12 V) in order to fully turn on the power device and minimize conduction losses.

Traditional buffer drive circuits based on NPN/PNP bipolar transistors in totem-pole arrangement prove inadequate with digital power because they lack level-shifting capability. Gate drivers effectively combine both the level-shifting and buffer-drive functions. Gate drivers also address other needs such as minimizing the effect of high-frequency switching noise (by placing the high-current driver IC physically close to the power switch), driving gate-drive transformers and controlling floating power-device gates, reducing power dissipation and thermal stress in controllers by moving gate charge power losses from the controller into the driver.

The LMG1205 is a MHz high- and low-side gate driver for enhancement mode GaN FETs in a synchronous buck, boost, or half-bridge configuration. The high-side bias voltage is generated using a bootstrap technique and is internally clamped at 5 V, which prevents the gate voltage from exceeding the maximum gate-source voltage rating of enhancement mode GaN FETs. The LMG1205 has split-gate outputs with strong sink capability, providing flexibility to adjust the turnon and turnoff strength independently.

# 8.2 Typical Application

The circuit in 図 8-1 shows a synchronous buck converter to evaluate LMG1205. Detailed synchronous buck converter specifications are listed in セクション 8.2.1. Optimization of he power loop (loop impedance from VIN capacitor to PGND) is critical to the performance of the design. Having a high power loop inductance causes significant ringing in the SW node and also causes an associated power loss. For more information, please refer to セクション 11.2.1.

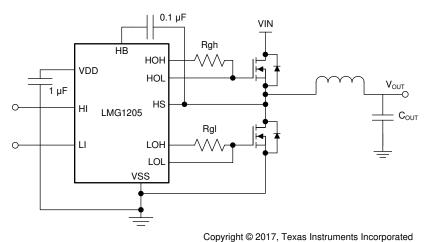


図 8-1. Application Circuit

Product Folder Links: LMG1205



### 8.2.1 Design Requirements

When designing a synchronous buck converter application that incorporates the LMG1205 gate driver and GaN power FETs, some design considerations must be evaluated first to make the most appropriate selection. Among these considerations are the input voltages, passive components, operating frequency, and controller selection. 表 8-1 shows some sample values for a typical application. See セクション 9, セクション 10, and セクション 8.2.2.3 for other key design considerations for the LMG1205.

表 8-1. Design Parameters

PARAMETER	SAMPLE VALUE
Half-bridge input supply voltage, V <sub>IN</sub>	48 V
Output voltage, V <sub>OUT</sub>	12 V
Output current	8 A
Dead time	8 ns
Inductor	4.7 μH
Switching frequency	1 MHz

### 8.2.2 Detailed Design Procedure

This procedure outlines the design considerations of LMG1205 in a synchronous buck converter with enhancement mode GaN FET. For additional design help, see セクション 11.2.1.

### 8.2.2.1 VDD Bypass Capacitor

The VDD bypass capacitor provides the gate charge for the low-side and high-side transistors and to absorb the reverse recovery charge of the bootstrap diode. The required bypass capacitance can be calculated with  $\pm$  1.

$$C_{VDD} > \frac{Q_{gH} + Q_{gL} + Q_{rr}}{\Delta V}$$
(1)

#### where

- Q<sub>qH</sub> and Q<sub>qL</sub> are gate charge of the high-side and low-side transistors, respectively
- Q<sub>rr</sub> is the reverse recovery charge of the bootstrap diode, which is typically around 4nC
- ΔV is the maximum allowable voltage drop across the bypass capacitor

TI recommends a 0.1–µF or larger value, good-quality ceramic capacitor. The bypass capacitor must be placed as close as possible to the device pins to minimize the parasitic inductance.

#### 8.2.2.2 Bootstrap Capacitor

The bootstrap capacitor provides the gate charge for the high-side switch, DC bias power for HB undervoltage lockout circuit, and the reverse recovery charge of the bootstrap diode. The required bypass capacitance can be calculated with 式 2.

$$C_{BST} > \frac{Q_{gH} + (I_{HB} + I_{GSS}) \times T_{ON} + Q_{rr}}{\Delta V}$$
 (2)

#### where

- · IHB is the quiescent current of the high-side driver
- · Ton is the maximum on-time period of the high-side transistor
- I<sub>GSS</sub> is the gate leakage current of the high-side transistor

A good-quality ceramic capacitor must be used for the bootstrap capacitor. TI recommends placing the bootstrap capacitor as close as possible to the HB and HS pins.

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### 8.2.2.3 Power Dissipation

The power consumption of the driver is an important measure that determines the maximum achievable operating frequency of the driver. It must be kept below the maximum power dissipation limit of the package at the operating temperature. The total power dissipation of the LMG1205 is the sum of the gate driver losses and the bootstrap diode power loss.

The gate driver losses are incurred by charge and discharge of the capacitive load. It can be approximated as

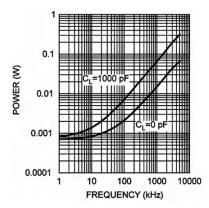
$$P = (C_{LoadH} + C_{LoadL}) \times V_{DD}^{2} \times f_{SW}$$
(3)

where

C<sub>LoadH</sub> and C<sub>LoadL</sub> are the high-side and the low-side capacitive loads, respectively
 It can also be calculated with the total input gate charge of the high-side and the low-side transistors as

$$P = (Q_{gH} + Q_{gL}) \times V_{DD} \times f_{SW}$$
(4)

There are some additional losses in the gate drivers due to the internal CMOS stages used to buffer the LO and HO outputs.  $\boxtimes$  8-2 shows the measured gate driver power dissipation versus frequency and load capacitance. At higher frequencies and load capacitance values, the power dissipation is dominated by the power losses driving the output loads and agrees well with the above equations.  $\boxtimes$  8-2 can be used to approximate the power losses due to the gate drivers.



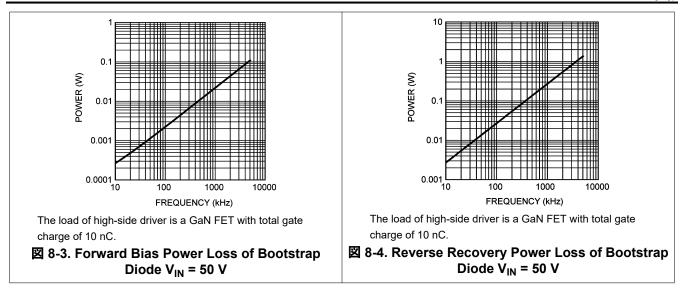
Gate driver power dissipation (LO+HO), VDD = 5 V

#### 図 8-2. Neglecting Bootstrap Diode Losses

The bootstrap diode power loss is the sum of the forward bias power loss that occurs while charging the bootstrap capacitor and the reverse bias power loss that occurs during reverse recovery. Because each of these events happens once per cycle, the diode power loss is proportional to the operating frequency. Larger capacitive loads require more energy to recharge the bootstrap capacitor resulting in more losses. Higher input voltages (V<sub>IN</sub>) to the half bridge also result in higher reverse recovery losses.

図 8-3 and 図 8-4 show the forward bias power loss and the reverse bias power loss of the bootstrap diode respectively. The plots are generated based on calculations and lab measurements of the diode reverse time and current under several operating conditions. 図 8-3 and 図 8-4 can be used to predict the bootstrap diode power loss under different operating conditions.

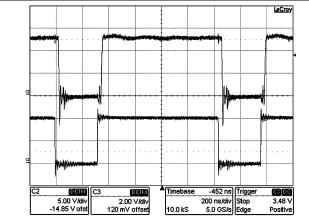
Product Folder Links: LMG1205



The sum of the driver loss and the bootstrap diode loss is the total power loss of the IC. For a given ambient temperature, the maximum allowable power loss of the IC can be defined as  $\pm 5$ .

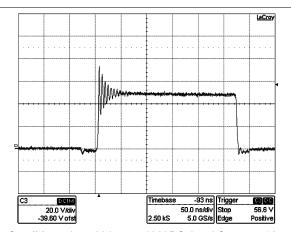
$$P = \frac{(T_J - T_A)}{\theta_{JA}} \tag{5}$$

### 8.2.3 Application Curves



Conditions: Input Voltage = 48 V DC, Load Current = 5
ATraces: Top Trace: Gate of Low-Side eGaN FET, Volt/div = 2
V Bottom Trace: LI of LMG1205, Volt/div = 5 V Bandwidth Limit
= 600 MHz Horizontal Resolution = 0.2 µs/div

図 8-5. Low-Side Driver Input and Output



Conditions: Input Voltage = 48 V DC, Load Current = 10
ATraces: Trace: Switch-Node Voltage, Volts/div = 20 V
Bandwidth Limit = 600 MHz Horizontal Resolution = 50 ns/div

図 8-6. Switch-Node Voltage

# 9 Power Supply Recommendations

The recommended bias supply voltage range for LMG1205 is from 4.5 V to 5.5 V. The lower end of this range is governed by the internal UVLO protection feature of the VDD supply circuit. TI recommends keeping proper margin to allow for transient voltage spikes while not violating the LMG1205 absolute maximum VDD voltage rating and the GaN transistor gate breakdown voltage limit.

The UVLO protection feature also involves a hysteresis function. This means that once the device is operating in normal mode, if the VDD voltage drops, the device continues to operate in normal mode as far as the voltage drop does not exceeds the hysteresis specification, VDDH. If the voltage drop is more than hysteresis specification, the device shuts down. Therefore, while operating at or near the 4.5-V range, the voltage ripple on the VDD power supply output must be smaller than the hysteresis specification of LMG1205 UVLO to avoid triggering device shutdown.

A local bypass capacitor must be placed between the VDD and VSS pins. This capacitor must be located as close as possible to the device. TI recommends a low-ESR, ceramic, surface-mount capacitor. TI also recommends using 2 capacitors across VDD and GND: a 100-nF ceramic surface-mount capacitor for high frequency filtering placed very close to VDD and GND pin, and another surface-mount capacitor, 220 nF to 10  $\mu$ F, for IC bias requirements.



# 10 Layout

# 10.1 Layout Guidelines

Small gate capacitance and Miller capacitance enable enhancement mode GaN FETs to operate with fast switching speed. The induced high dv/dt and di/dt, coupled with a low gate threshold voltage and limited headroom of enhancement mode GaN FETs gate voltage, make the circuit layout crucial to the optimum performance. Following are some recommendations:

- The first priority in designing the layout of the driver is to confine the high peak currents that charge and discharge the GaN FETs gate into a minimal physical area. This decreases the loop inductance and minimize noise issues on the gate terminal of the GaN FETs. The GaN FETs must be placed close to the driver.
- 2. The second high current path includes the bootstrap capacitor, the local ground referenced VDD bypass capacitor and low-side GaN FET. The bootstrap capacitor is recharged on a cycle-by-cycle basis through the bootstrap diode from the ground referenced VDD capacitor. The recharging occurs in a short time interval and involves high peak current. Minimizing this loop length and area on the circuit board is important to ensure reliable operation.
- 3. The parasitic inductance in series with the source of the high-side FET and the low-side FET can impose excessive negative voltage transients on the driver. TI recommends connecting the HS pin and VSS pin to the respective source of the high-side and low-side transistors with a short and low-inductance path.
- 4. The parasitic source inductance, along with the gate capacitor and the driver pull-down path, can form an LCR resonant tank, resulting in gate voltage oscillations. An optional resistor or ferrite bead can be used to damp the ringing.
- 5. Low ESR/ESL capacitors must be connected close to the IC, between VDD and VSS pins and between the HB and HS pins to support the high peak current being drawn from VDD during turnon of the FETs. Keeping bullet #1 (minimized GaN FETs gate driver loop) as the first priority, it is also desirable to place the VDD decoupling capacitor and the HB to HS bootstrap capacitor on the same side of the PC board as the driver. The inductance of vias can impose excessive ringing on the IC pins.
- 6. To prevent excessive ringing on the input power bus, good decoupling practices are required by placing low-ESR ceramic capacitors adjacent to the GaN FETs.

図 10-1 and 図 10-2 show recommended layout patterns for the LMG1205. Two cases are considered: (1) without any gate resistors, and (2) with an optional turnon gate resistor. Note that 0402 surface mount package is assumed for the passive components in the drawings. For information on DSBGA package assembly, refer to セクション 11.2.1.

### 10.2 Layout Examples

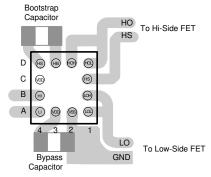


図 10-1. Layout Example Without Gate Resistors

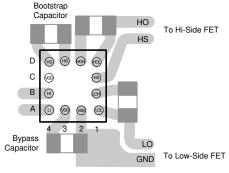


図 10-2. Layout Example with HOH and LOH Gate Resistors

# 11 Device and Documentation Support

## 11.1 Device Support

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### 11.2 Documentation Support

#### 11.2.1 Related Documentation

For related documentation see the following:

- AN-1112 DSBGA Wafer Level Chip Scale Package
- Using the LMG1205HBEVM GaN Half-Bridge EVM

### 11.3 ドキュメントの更新通知を受け取る方法

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www.ti.com 23-May-2025

### PACKAGING INFORMATION

Orderable part number	Status	Material type	Package   Pins	Package qty   Carrier	RoHS	Lead finish/	MSL rating/	Op temp (°C)	Part marking
	(1)	(2)			(3)	Ball material	Peak reflow		(6)
						(4)	(5)		
LMG1205YFXR	Active	Production	DSBGA (YFX)   12	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	1205
LMG1205YFXR.A	Active	Production	DSBGA (YFX)   12	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	1205
LMG1205YFXT	Active	Production	DSBGA (YFX)   12	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	1205
LMG1205YFXT.A	Active	Production	DSBGA (YFX)   12	250   SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 125	1205

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

# **PACKAGE MATERIALS INFORMATION**

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## TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device		Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMG1205YFXR	DSBGA	YFX	12	3000	178.0	8.4	1.85	2.01	0.76	4.0	8.0	Q1
LMG1205YFXT	DSBGA	YFX	12	250	178.0	8.4	1.85	2.01	0.76	4.0	8.0	Q1

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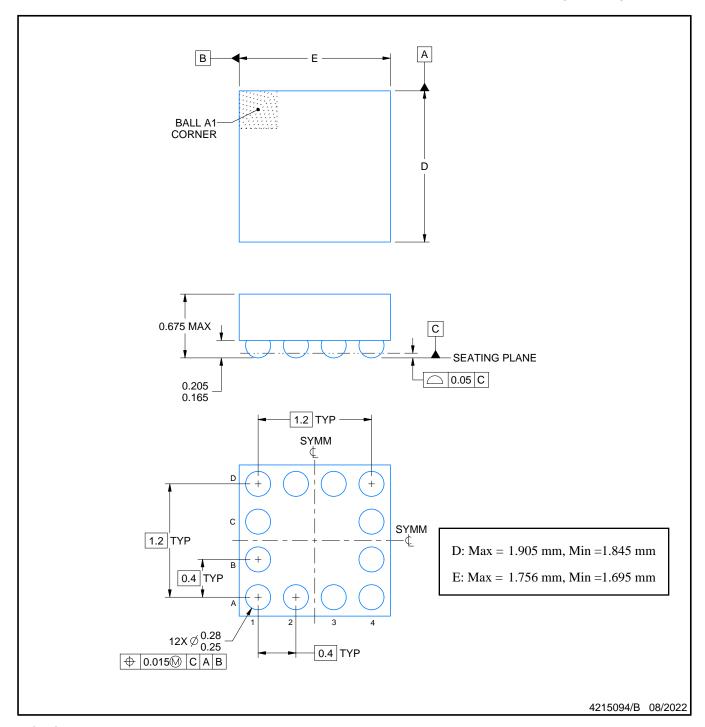


## \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMG1205YFXR	DSBGA	YFX	12	3000	208.0	191.0	35.0
LMG1205YFXT	DSBGA	YFX	12	250	208.0	191.0	35.0



DIE SIZE BALL GRID ARRAY



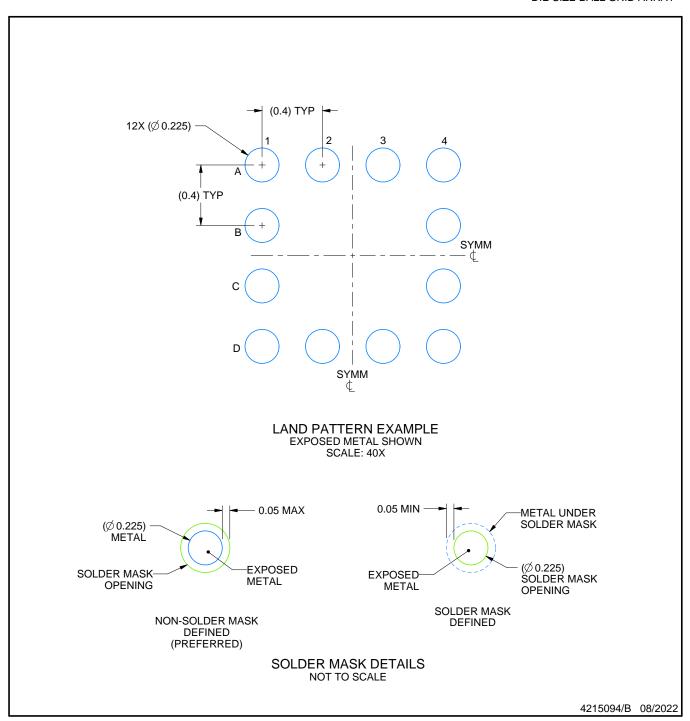
# NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.



DIE SIZE BALL GRID ARRAY

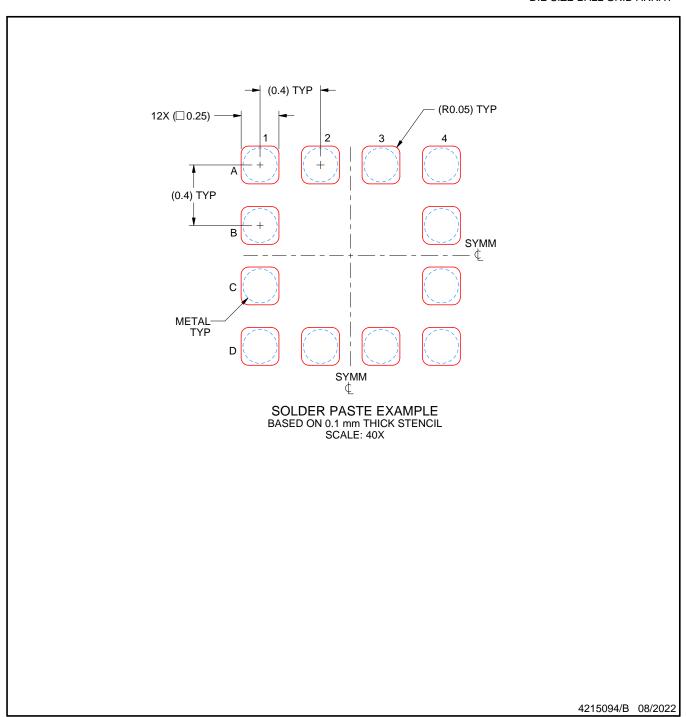


NOTES: (continued)

Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. See Texas Instruments Literature No. SNVA009 (www.ti.com/lit/snva009).



DIE SIZE BALL GRID ARRAY



NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.



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