

# LDC3114 4 チャンネル・ハイブリッド誘導性タッチおよびインダクタンス / デジタル・コンバータ

## 1 特長

- 各種動作モード:
  - 生データ・モード: リニア・センシングのための先進のアルゴリズムを MCU で実現するため、前処理されたインダクタンス測定データを利用します。
  - ボタン・モード: ベースライン・トラッキングと先進のオンチップ後処理によってボタンの押下を検出します。
  - タッチ・ボタンの圧力レベル測定
- LDC2114** とピンおよびレジスタ互換
- 堅牢な EMI 性能により CISPR 22 および CISPR 24 準拠が可能
- 4 つの独立したチャンネル動作
- スキャン・レートを設定可能:
  - 0.625SPS ~ 160SPS
  - 連続スキャン・オプション
- 先進のボタン押下検出アルゴリズム:
  - ボタンごとの圧カスレッシュヨルド調整
  - 環境シフトの補償
  - ボタンの同時押し検出
- 低消費電流:
  - 1 つのボタン: 0.625SPS で 6 $\mu$ A
  - 2 つのボタン: 20SPS で 72 $\mu$ A
- 温度範囲
  - TSSOP (16): -40 $^{\circ}$ C ~ +125 $^{\circ}$ C
- インターフェイス:
  - 1.8V および 3.3V 互換 I<sup>2</sup>C および INTB
  - ボタン用チャンネルごとの 1.8V ロジック出力

## 2 アプリケーション

- 消費者向け電子機器
  - ウェアラブル
  - スマート・スピーカ
  - サウンド・バー
- 産業用アプリケーション
  - HMI パネルおよびキーパッド
  - 家電製品

## 3 概要

LDC3114 は、各種の材料の上にヒューマン・マシン・インターフェイス (HMI) 用タッチ・ボタンを設計できる誘導性センシング・デバイスです。このタッチ・ボタンのオン / オフの状態は、パネルの裏に配置した小さいプリント基板 (PCB) 上に実装できるコイルを使って導電性ターゲットの微小なたわみを測定することで知ることができます。この技術を使うと、インダクタンス値を表す生データを得ることができるため、車載、民生、産業用途での金属ターゲットの高精度リニア位置検出に使えます。誘導性センシング・ソリューションは、湿気にも非導電性汚染物質 (油、汚れなど) にも反応しません。

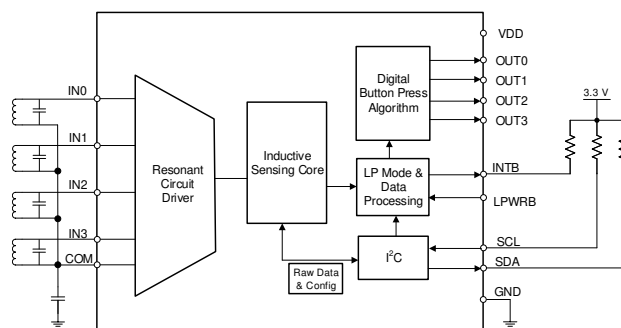
LDC3114 のボタン・モードは導電性ターゲットの変形を自動修正できます。LDC3114 は、よく整合されたチャンネルを備えているため、温度および機械的ドリフトなどの環境および経時的条件を補償できる差動およびレシオメトリック測定が可能です。LDC3114 は、バッテリー駆動アプリケーションの電源オン / オフ・ボタンまたは位置センサ用の超低消費電力モードをサポートしています。

LDC3114 は、I<sup>2</sup>C インターフェイスにより簡単に設定できます。LDC3114 は、16 ピンの TSSOP パッケージで供給されます。

### 製品情報(1)

部品番号	パッケージ	本体サイズ (公称)
LDC3114	TSSOP (16)	5.00mm × 4.40mm

- (1) 利用可能なパッケージについては、このデータシートの末尾にある注文情報を参照してください。



LDC3114 概略回路図



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## 4 Revision History

DATE	VERSION	NOTES
December 2021	*	Initial release.

## 5 Pin Configuration and Functions

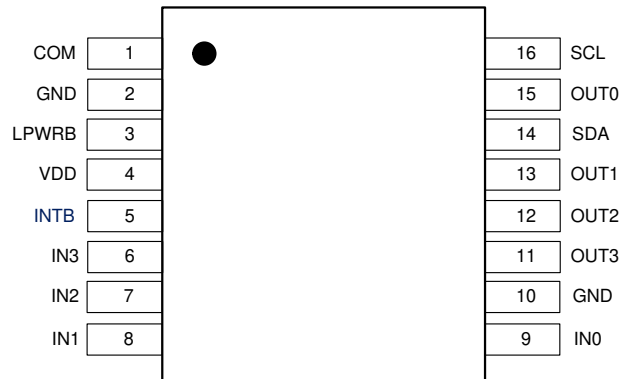


图 5-1. LDC3114 PW Package 16-Pin TSSOP Top View

表 5-1. Pin Functions

PIN		I/O <sup>(1)</sup>	DESCRIPTION
NAME	NO.		
VDD	4	P	Power supply
GND	2	G	Ground <sup>(2)</sup>
	10		
INTB	5	O	Interrupt output Polarity can be configured in Register 0x11.
LPWRB	3	I	Normal / Low Power Mode select Set LPWRB to V <sub>DD</sub> for Normal Power Mode or ground for Low Power Mode.
COM	1	A	Common return current path for all LC resonator sensors A capacitor should be connected from this pin to GND. Refer to <a href="#">Setting COM Pin Capacitor</a> .
IN0	9	A	Channel 0 LC sensor input
IN1	8	A	Channel 1 LC sensor input
IN2	7	A	Channel 2 LC sensor input
IN3	6	A	Channel 3 LC sensor input
OUT0	15	O	Channel 0 logic output Polarity can be configured in Register 0x1C.
OUT1	13	O	Channel 1 logic output Polarity can be configured in Register 0x1C.
OUT2	12	O	Channel 2 logic output Polarity can be configured in Register 0x1C.
OUT3	11	O	Channel 3 logic output Polarity can be configured in Register 0x1C.
SCL	16	I	I <sup>2</sup> C clock
SDA	14	I/O	I <sup>2</sup> C data I <sup>2</sup> C address = 0x2A.

- (1) I = Input, O = Output, P=Power, G=Ground, A=Analog  
 (2) Both pins should be connected to the system ground on the PCB.

## 6 Specifications

### 6.1 Absolute Maximum Ratings

Over operating temperature range unless otherwise noted.<sup>(1)</sup>

		MIN	MAX	UNIT
V <sub>DD</sub>	Supply voltage		2.2	V
V <sub>I</sub>	Voltage on SCL, SDA, INTB	-0.3	3.6	V
	Voltage on any other pin	-0.3	2.2 <sup>(2)</sup>	V
T <sub>J</sub>	Junction temperature	-40	135	°C
T <sub>STG</sub>	Storage temperature	-65	125	°C

- (1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) Maximum voltage across any two pins (not including SCL or SDA) is V<sub>DD</sub> + 0.3 V.

### 6.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±1000	V
		Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup>	±250	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 6.3 Recommended Operating Conditions

Over operating temperature range unless otherwise noted.

		MIN	NOM	MAX	UNIT
V <sub>DD</sub>	Supply voltage	1.71		1.89	V
T <sub>A</sub>	Ambient temperature (TSSOP Package)	-40		125	°C

### 6.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		LDC3114	UNIT
		TSSOP	
		16 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	105.1	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	40.3	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	50.2	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	3.6	°C/W
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	49.6	°C/W

- (1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

### 6.5 Electrical Characteristics

Over operating temperature range unless otherwise noted.

Over operating V<sub>DD</sub> range unless otherwise noted.

PARAMETER		TEST CONDITIONS			MIN	TYP	MAX	UNIT
<b>POWER</b>								
V <sub>DD</sub>	Supply voltage				1.71	1.8	1.89	V

Over operating temperature range unless otherwise noted.  
Over operating  $V_{DD}$  range unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{DDNP}$	Normal power mode supply current (4 channels) <sup>(1) (2)</sup>	4 channels, 40 SPS per channel, 1 ms sampling window per channel, LPWRB = $V_{DD}$ $-40^{\circ}\text{C} \leq T_A \leq 125^{\circ}\text{C}$		0.46	2	mA
	Normal power mode supply current (2 channels) <sup>(1) (2)</sup>	2 channels, 40 SPS per channel, 1 ms sampling window per channel, LPWRB = $V_{DD}$ $-40^{\circ}\text{C} \leq T_A \leq 125^{\circ}\text{C}$		0.31	1	mA
$I_{DDL P}$	Low power mode supply current <sup>(1) (2)</sup>	1 channel, 1.25 SPS per channel, 1 ms sampling window per channel, LPWRB = Ground $-40^{\circ}\text{C} \leq T_A \leq 125^{\circ}\text{C}$		10	35	$\mu\text{A}$
$I_{DDSB}$	Standby supply current	No button active (EN = 0x00) $-40^{\circ}\text{C} \leq T_A \leq 125^{\circ}\text{C}$		7	22	$\mu\text{A}$
<b>SENSOR</b>						
$I_{\text{SENSOR, MAX}}$	Maximum sensor current drive	Registers $\text{SENSOR}_n\text{\_CONFIG}$ : $\text{RP}_n = 0$ <sup>(3)</sup>		2.5		mA
$R_{P, \text{MIN}}$	Minimum sensor parallel resonant impedance			350		$\Omega$
$R_{P, \text{MAX}}$	Maximum sensor parallel resonant impedance			10		k $\Omega$
$f_{\text{SENSOR}}$	Sensor resonant frequency <sup>(4)</sup>		5		30	MHz
$Q_{\text{SENSOR, MIN}}$	Minimum sensor quality factor			5		
$Q_{\text{SENSOR, MAX}}$	Maximum sensor quality factor			30		
$V_{\text{SENSOR, PP}}$	Sensor oscillation peak-to-peak voltage	Measured on the $\text{IN}_n$ <sup>(3)</sup> pins with reference to COM.		0.9		V
$C_{\text{IN}}$	Sensor input pin capacitance			17		pF
<b>CONVERTER</b>						
$\text{SR}_{\text{NP, MIN}}$	Minimum normal power mode scan rate <sup>(5)</sup>	LPWRB = $V_{DD}$	7	10	13	SPS
$\text{SR}_{\text{NP, MAX}}$	Maximum normal power mode scan rate <sup>(5)</sup>	LPWRB = $V_{DD}$	56	80	104	SPS
$\text{SR}_{\text{LP, MIN}}$	Minimum low power mode scan rate <sup>(5)</sup>	LPWRB = Ground	0.438	0.625	0.813	SPS
$\text{SR}_{\text{LP, MAX}}$	Maximum low power mode scan rate <sup>(5)</sup>	LPWRB = Ground	3.5	5	6.5	SPS
$f_{\text{REF\_CLK}}$	Internal Reference clock frequency	$T_A = 25^{\circ}\text{C}$		44		MHz
$f_{\text{REF\_CLK\_TC}}$	Internal Reference clock frequency variation from $T_A = 25^{\circ}\text{C}$ to over temperature	$-40^{\circ}\text{C} \leq T_A \leq 125^{\circ}\text{C}$		3		%

(1) Sensor configuration:  $L_{\text{SENSOR}} = 0.85 \mu\text{H}$ ,  $C_{\text{SENSOR}} = 58 \text{ pF}$ ,  $Q_{\text{SENSOR}} = 11$ ,  $R_P = 0.7 \text{ k}\Omega$ .

(2) I<sup>2</sup>C communication and pull-up resistors current is not included.

(3) The italic  $n$  is the channel index,  $n = 0, 1, 2$ , or  $3$  for LDC3114.

(4) For optimal performance, configure the sensor frequency to be greater than 3 MHz

(5) For typical distribution of the scan rates, refer to [Figure 6-9](#).

## 6.6 Digital Interface

Over operating temperature range unless otherwise noted. Pins: LPWRB, INT\_DR, OUT0, OUT1, OUT2, OUT3, and ADDR.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>VOLTAGE LEVELS</b>					
$V_{\text{IH}}$	Input high voltage, LPWRB pin		$0.8 \times V_{DD}$		V
$V_{\text{IL}}$	Input low voltage, LPWRB pin			$0.2 \times V_{DD}$	V

Over operating temperature range unless otherwise noted. Pins: LPWRB, INT\_DR, OUT0, OUT1, OUT2, OUT3, and ADDR.

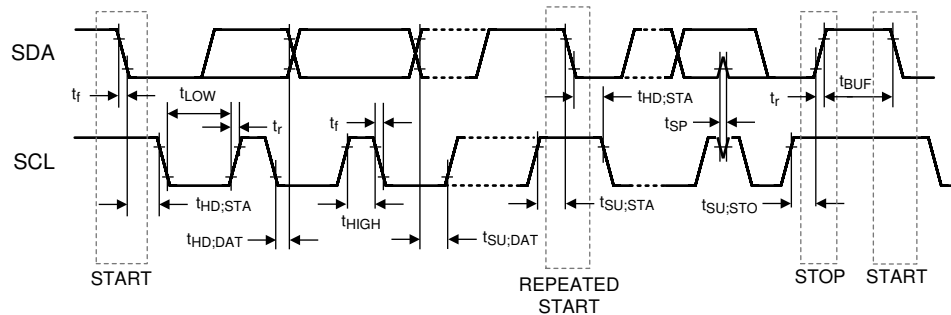
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{OH}$	Output high voltage, OUTx pins	$I_{SOURCE} = 400 \mu A$	$0.8 \times V_{DD}$			V
$V_{OL}$	Output low voltage, OUTx pins	$I_{SINK} = 400 \mu A$			$0.2 \times V_{DD}$	V
$I_L$	Digital input leakage current		-500		500	nA
$V_{OL\_INTB}$	Output low voltage, INTB pin	3 mA sink current			0.4	V

## 6.7 I<sup>2</sup>C Interface

		MIN	TYP	MAX	UNIT
<b>VOLTAGE LEVELS</b>					
$V_{IH\_I2C}$	Input high voltage		$0.7 \times V_{DD}$		V
$V_{IL\_I2C}$	Input low voltage			$0.3 \times V_{DD}$	V
$V_{OL\_I2C}$	Output low voltage	3 mA sink current		$0.2 \times V_{DD}$	V
$HYS_{I2C}$	Hysteresis		$0.05 \times V_{DD}$		V
<b>I<sup>2</sup>C TIMING CHARACTERISTICS</b>					
$f_{SCL}$	Clock frequency			400	kHz
$t_{LOW}$	Clock low time		1.3		$\mu s$
$t_{HIGH}$	Clock high time		0.6		$\mu s$
$t_{HD,STA}$	Hold time repeated START condition	After this period, the first clock pulse is generated.	0.6		$\mu s$
$t_{SU,STA}$	Set-up time for a repeated START condition		0.6		$\mu s$
$t_{HD,DAT}$	Data hold time		0		$\mu s$
$t_{SU,DAT}$	Data set-up time		100		ns
$t_{SU,STO}$	Set-up time for STOP condition		0.6		$\mu s$
$t_{BUF}$	Bus free time between a STOP and START condition		1.3		$\mu s$
$t_{VD,DAT}$	Data valid time			0.9	$\mu s$
$t_{VD,ACK}$	Data valid acknowledge time			0.9	$\mu s$
$t_{SP}$	Pulse width of spikes that must be suppressed by the input filter <sup>(1)</sup>			50	ns

(1) This parameter is specified by design and/or characterization and is not tested in production.

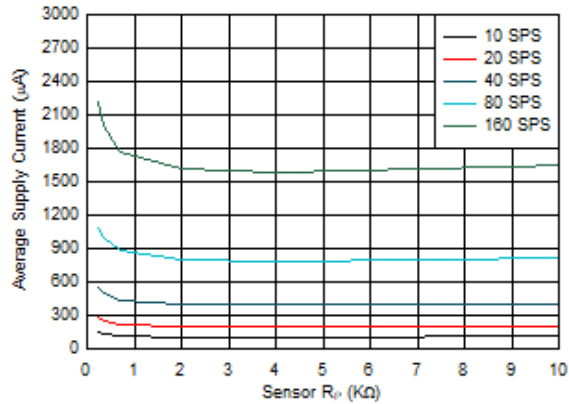
## 6.8 Timing Diagram



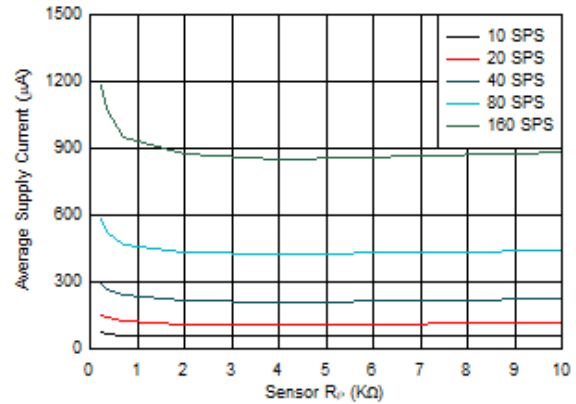
6-1. I<sup>2</sup>C Timing Diagram

## 6.9 Typical Characteristics

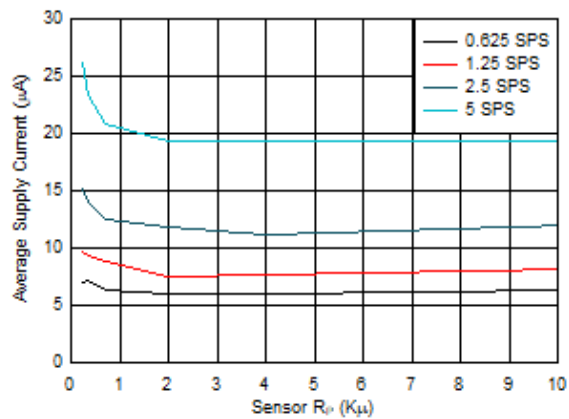
Over recommended operating conditions unless specified otherwise.  $V_{DD} = 1.8\text{ V}$ ,  $T_J = 25^\circ\text{C}$ . One channel enabled with a [button sampling window](#) of 1 ms unless specified otherwise.



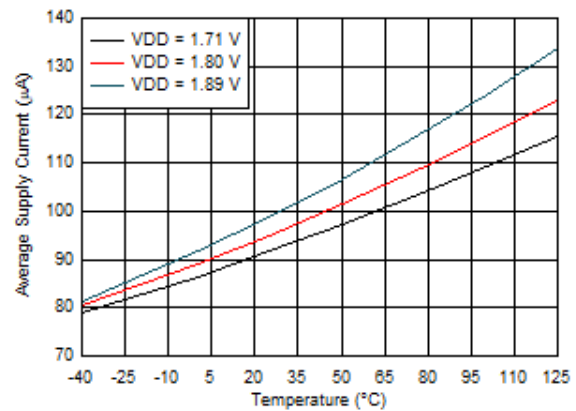
**6-2. Supply Current vs Sensor  $R_p$  for Normal Power Mode. Sensor Frequency = 10 MHz. Sampling Window = 2mS. Four Channels Enabled.**



**6-3. Supply Current vs Sensor  $R_p$  for Normal Power Mode. Sensor Frequency = 10 MHz. Sampling Window = 2mS. Two Channels Enabled.**



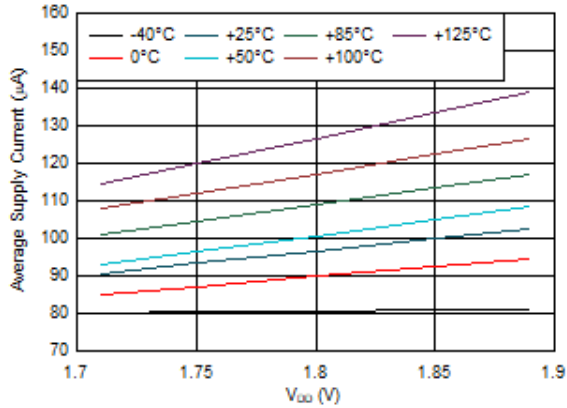
**6-4. Supply Current vs Sensor  $R_p$  for Low Power Mode. Sensor Frequency = 10 MHz.**



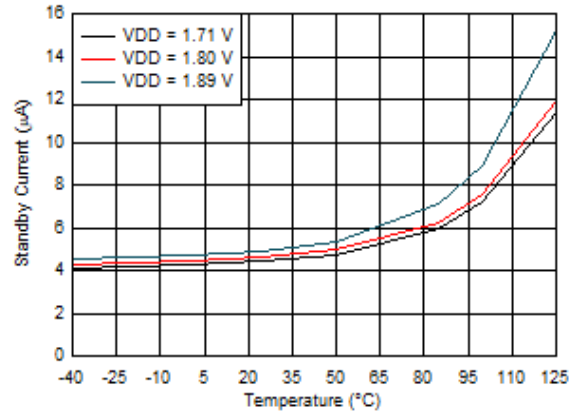
**6-5. Supply Current vs Temperature. Sensor  $R_p = 720\ \Omega$ , Scan Rate = 40 SPS, Sensor Frequency = 20 MHz.**

### 6.9 Typical Characteristics (continued)

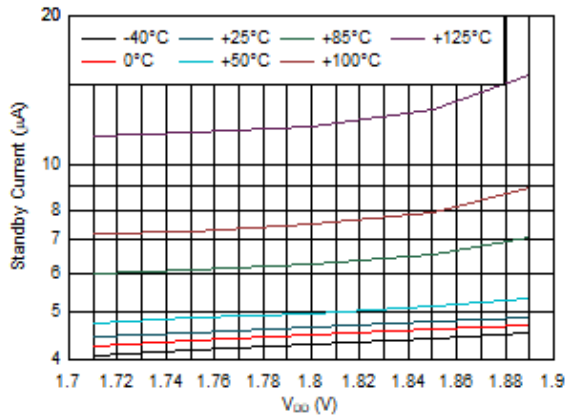
Over recommended operating conditions unless specified otherwise.  $V_{DD} = 1.8\text{ V}$ ,  $T_J = 25^\circ\text{C}$ . One channel enabled with a [button sampling window](#) of 1 ms unless specified otherwise.



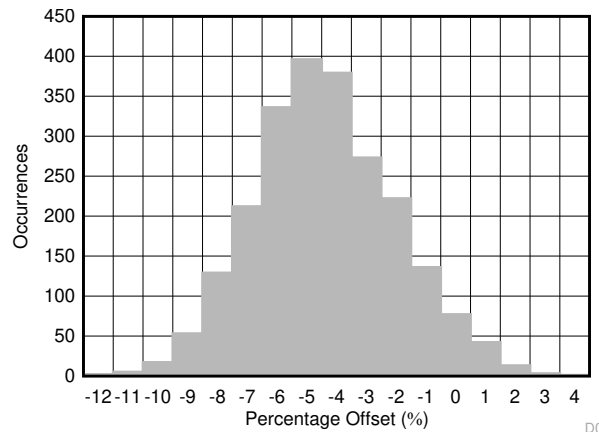
6-6. Supply Current vs.  $V_{DD}$ . Sensor  $R_P = 720\ \Omega$ , Scan Rate = 40 SPS, Sensor Frequency = 20 MHz.



6-7. Standby Current vs. Temperature



6-8. Standby Current vs  $V_{DD}$



6-9. Scan Rate Distribution at 30°C

D007



## 7 Detailed Description

### 7.1 Overview

The LDC3114 is a hybrid multichannel, low-noise, high-resolution inductance-to-digital converter (LDC) optimized for inductive touch applications as well as linear position sensing. Button presses form micro-deflections in the conductive targets which cause frequency shifts in the resonant sensors. The LDC3114 can measure such frequency shifts and determine when button presses occur. With adjustable sensitivity per input channel, the LDC3114 can reliably operate with a wide range of physical button structures and materials. The high resolution measurement enables the implementation of force level buttons. The LDC3114 incorporates customizable post-processing algorithms for enhanced robustness.

The LDC3114 additionally implements a raw data access mode. The MCU can read directly the data representing the effective inductance of the sensor and implement further post processing. In this mode, additional post processing features such as baseline tracking and algorithms for false button detection are ignored. This mode is useful for linear or rotary position sensing with inductive sensors while having excellent EMI performance across wide range of applications. This mode can also be used to measure the micro-deflection for button-like applications as well.

The LDC3114 can operate in an ultra-low power mode for optimal battery life, or can be toggled into a higher scan rate for more responsive button press detection for game play or other low latency applications. The LDC3114 is operational from  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$  with a  $1.8\text{ V} \pm 5\%$  power supply voltage.

The LDC3114 is configured through 400-kHz I<sup>2</sup>C. Button presses can be reported through the I<sup>2</sup>C interface or with configurable polarity dedicated push-pull outputs. Besides the LC resonant sensors, the only external components necessary for operation are supply bypassing capacitors and a COM pin capacitor to ground.

### 7.2 Functional Block Diagram

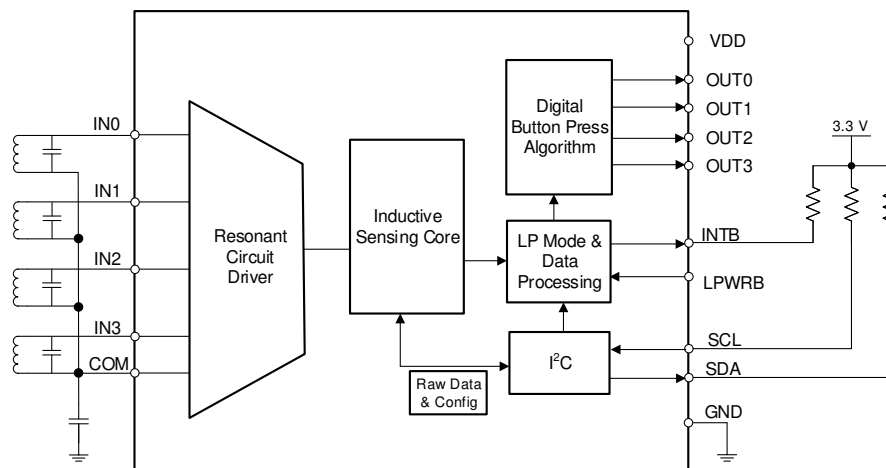


FIG 7-1. Block Diagram of LDC3114

### 7.3 Feature Description

#### 7.3.1 Multimode Operation

LDC3114 offers two main modes of operations: raw data access mode and button algorithm mode which is controlled by the *BTN\_ALG\_EN* field in Register *INTPOL* Address *0x11*. FIG 7-2 shows conceptually how these two modes are implemented.

Raw data access mode allows an external MCU to extract data from the signal after the inductance-to-digital converter from registers through I<sup>2</sup>C (see [Raw Data Output](#)). There is no further processing on this raw data such as baseline tracking, integrated button algorithms and button thresholding. This mode gives MCU full control over the measured raw data to implement algorithms for linear position sensing, rotational encoder

applications, metal presence/deflection applications, smart button algorithms and for multimodal sensor fusion applications.

The second mode is button algorithm mode. Here further processing with parameters defined by the user (see [Baseline Tracking](#) and [Integrated Button Algorithms](#)) is done on the data and a button thresholding as defined by the user is applied. The processed data are available in separate registers to be read by I<sup>2</sup>C and any button press detection is indicated on the OUTx pins (see [Button Output Interfaces](#)) This mode is used to implement button press functionality and can also be used to implement the measurement of force applied for button press along with detection to implement multilevel button press.

For register settings that are applicable to button mode versus raw access data mode are clearly identified in the descriptions of the registers (see [Register Maps](#)).

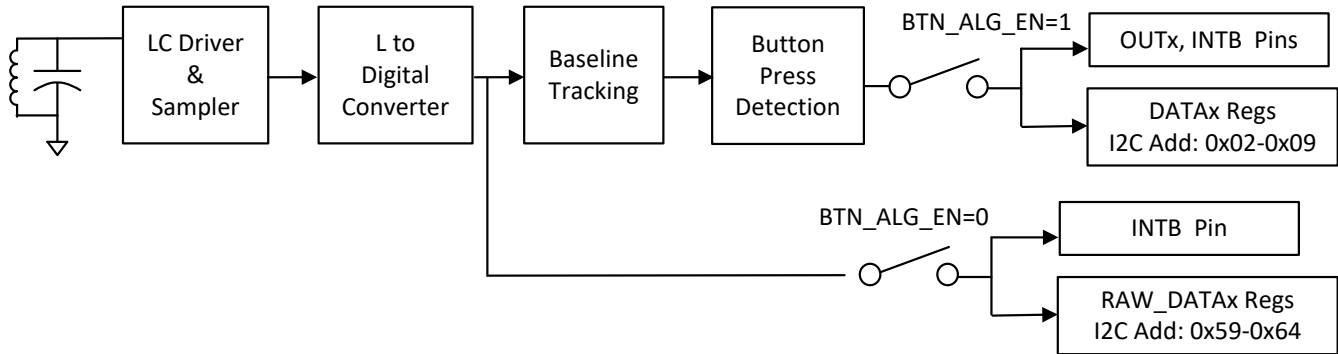


FIG 7-2. Multimode Operation in LDC3114

### 7.3.2 Multichannel and Single-Channel Operation

The LDC3114 provides four independent sensing channels. In the following sections, some parameters, such as DATA<sub>n</sub> and SENSOR<sub>n</sub>\_CONFIG, contain a channel index *n*.

Any of the four channels available in the LDC3114 can be independently enabled by setting the EN<sub>n</sub> and LPEN<sub>n</sub> (*n* = 0, 1, 2, or 3) bit fields in *Register EN* (Address 0x0C). The low-power-enable bit LPEN<sub>n</sub> only takes effect if the corresponding EN<sub>n</sub> bit is also set. If only one channel is set active, the LDC3114 periodically samples the single active channel at the configured scan rate. When several channels are set active, the LDC3114 operates in multichannel mode, and the device sequentially samples the active channels at the configured scan rate. Each channel of the LDC3114 can be independently enabled in Low Power Mode and Normal Power Mode.

### 7.3.3 Raw Data Output

Raw data mode is enabled by setting *BTN\_ALG\_EN=0x0* field in *Register INTPOL* Address 0x11. FIG 7-2 shows that this operation will extract data directly from the output of the inductance-to-digital converter.

The data is read from the I<sup>2</sup>C interface of the LDC3114. The *DATA\_RDY* field in *Register OUT* (Address 0x01) indicates when new data is available for reading. In the raw data mode, the INTB pin also asserted when new data is available and can be used by the MCU as an interrupt. The raw data can be extracted by reading, the output RAW\_DATA<sub>n</sub>\_x registers (*n* = 0, 1, 2, or 3, for each channel, *x* = 1, 2, or 3 splitting 24-bit data over 3 8-bit register fields). 式 1 shows the relationship between 24-bit data and the sensor frequency.

$$f_{\text{SENSOR}} = \frac{30 \times W \times f_{\text{REF\_CLK}}}{\text{raw\_data}} \quad (1)$$

where:

- $f_{\text{sensor}}$  is the instantaneous frequency of the inductive sensor
- $f_{\text{REF\_CLK}}$  is the internal reference clock frequency as specified in [Electrical Characteristics](#)
- *raw\_data* is the decimal representation of 24-bit binary data read from the RAW\_DATA<sub>n</sub>\_x for a particular channel
- *W* calculated in 式 2 (see [Programming Button or Raw Data Sampling Window](#) for details):

$$W = 128 \times (1 + \text{SENCY}_n) \times 2^{\text{LCDIV}} \quad (2)$$

### 7.3.4 Button Output Interfaces

Button events may be reported by using two methods. The first method is to monitor the  $\text{OUT}_n$  pins ( $n = 0, 1, 2,$  or  $3$ ), which are push-pull outputs and can be used as interrupts to a microcontroller. The polarities of these pins are programmable through *Register OPOL\_DPOL (Address 0x1C)*. Any button press or error condition is also reported by the open-drain pin, INTB. The INTB pin polarity is configurable through *Register INTPOL (Address 0x11)*. Any assertion of INTB is cleared upon reading *Register STATUS (Address 0x00)*. Each push-pull output must be assigned to a dedicated general-purpose input pin on the microcontroller to avoid potential current fights.

The second method is through the I<sup>2</sup>C interface. The *Register OUT (Address 0x01)* contains the fields OUT0, OUT1, OUT2, and OUT3, which indicate when a button press has been detected. For more advanced button press measurements, the output  $\text{DATA}_n$  registers ( $n = 0, 1, 2,$  or  $3$ , *Register DATA0\_LSB - Address 0x02*), which are 12-bit two's complements, can be retrieved for all active buttons, and processed on a microcontroller. A valid button push is represented by a positive value. The polarity is configurable in *Register OPOL\_DPOL (Address 0x1C)*. The  $\text{DATA}_n$  values can be used to implement multilevel buttons, where the data value is correlated to the amount of force applied to the button.

### 7.3.5 Programmable Button Sensitivity

The  $\text{GAIN}_n$  registers (Addresses *0x0E, 0x10, 0x12,* and *0x14*) enable sensitivity enhancement of individual buttons to ensure consistent behavior of different mechanical structures. The sensitivity has a 64-level gain factor for a normalized gain between 1 and 232. Each gain step increases the gain by an average of 9%.

The gain required for an application is primarily determined by the mechanical rigidity of each individual button. The individual gain steps are listed in the [Gain Table](#).

### 7.3.6 Baseline Tracking

The LDC3114 incorporates a baseline tracking algorithm to automatically compensate for any slow change in the sensor output caused by environmental variations, such as temperature drift. The baseline tracking is configured independently for Normal Power Mode and Low Power Mode. For more information, refer to [Tracking Baseline](#).

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#### Note

The baseline tracking feature is applicable only for button algorithm functionality and cannot be bypassed. To disable baseline tracking, LDC3114 must be used in raw data access mode. See [Multimode Operation](#) for details.

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### 7.3.7 Integrated Button Algorithms

The LDC3114 features several algorithms that can mitigate false button detections due to mechanical non-idealities. The algorithms look for correlated button responses, such as similar or opposite responses between two neighboring buttons, to determine if there is any undesirable mechanical crosstalk. For more information, refer to [Mitigating False Button Detections](#).

### 7.3.8 I<sup>2</sup>C Interface

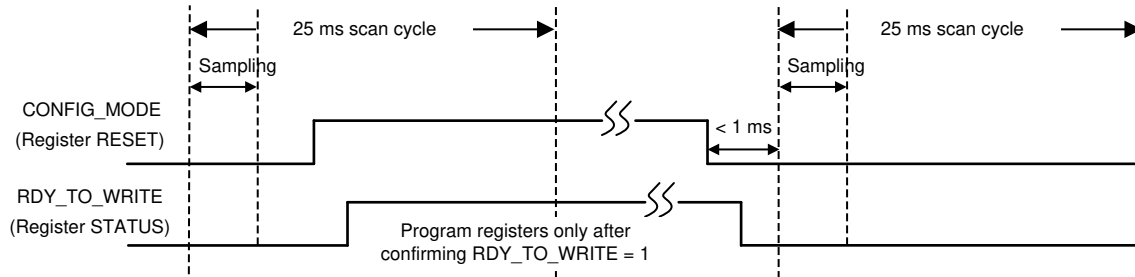
The LDC3114 features an I<sup>2</sup>C Interface that can be used to program the internal registers and read channel data. Before reading the OUT (Address 0x01) or channel  $\text{DATA}_n$  ( $n = 0, 1, 2$  or  $3$ , Addresses 0x02 through 0x09) registers for button press data or raw channel data,  $\text{RAW\_DATA}_n_x$  ( $n = 0, 1, 2,$  or  $3$ , for each channel,  $x = 1, 2,$  or  $3$  splitting 24-bit data over 3 8-bit register fields), the user should always read *Register STATUS (Address 0x00)* first to lock the data. The LDC3114 supports burst mode with auto-incrementing register addresses. The LDC3114 has a fixed I<sup>2</sup>C address of 0x2A.

For the write sequence, there is a special handshake process that has to take place to ensure data integrity. The sequence of register writes is:

- Set  $\text{CONFIG\_MODE}$  (*Register RESET, Address 0x0A*) bit = 1 to start the register write session.
- Poll for  $\text{RDY\_TO\_WRITE}$  (*Register STATUS, Address 0x00*) bit = 1.

- Perform I<sup>2</sup>C write to configure registers.
- Set CONFIG\_MODE (Register RESET, Address 0x0A) bit = 0 to terminate the register write session.

After CONFIG\_MODE is de-asserted, the new scan cycle will start in less than 1 ms. [7-3](#) shows the waveform of the above process.



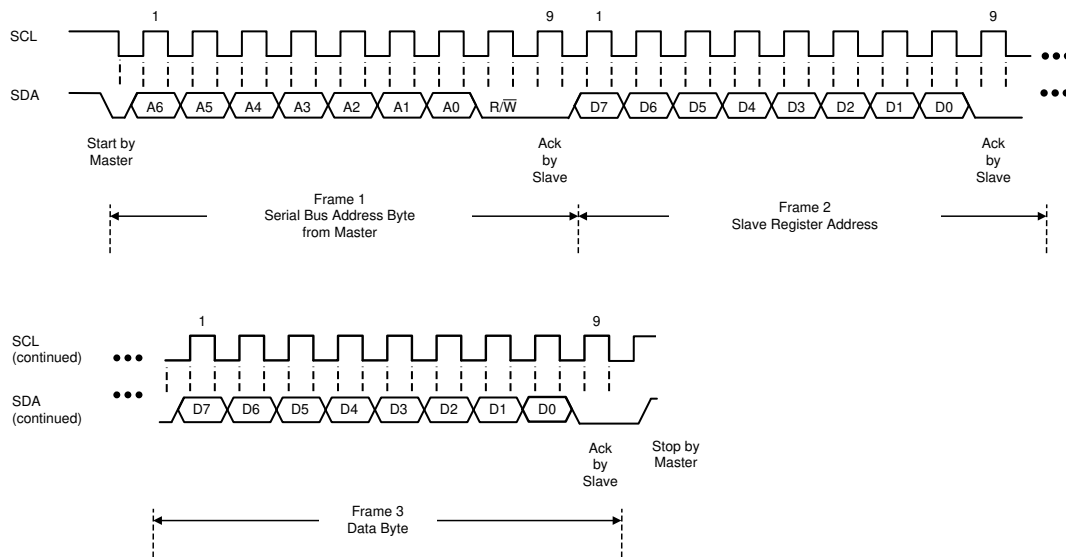
**7-3. Timing Diagram Representing the States of the CONFIG\_MODE and RDY\_TO\_WRITE Bits for an I<sup>2</sup>C Write Handshake**

#### Note

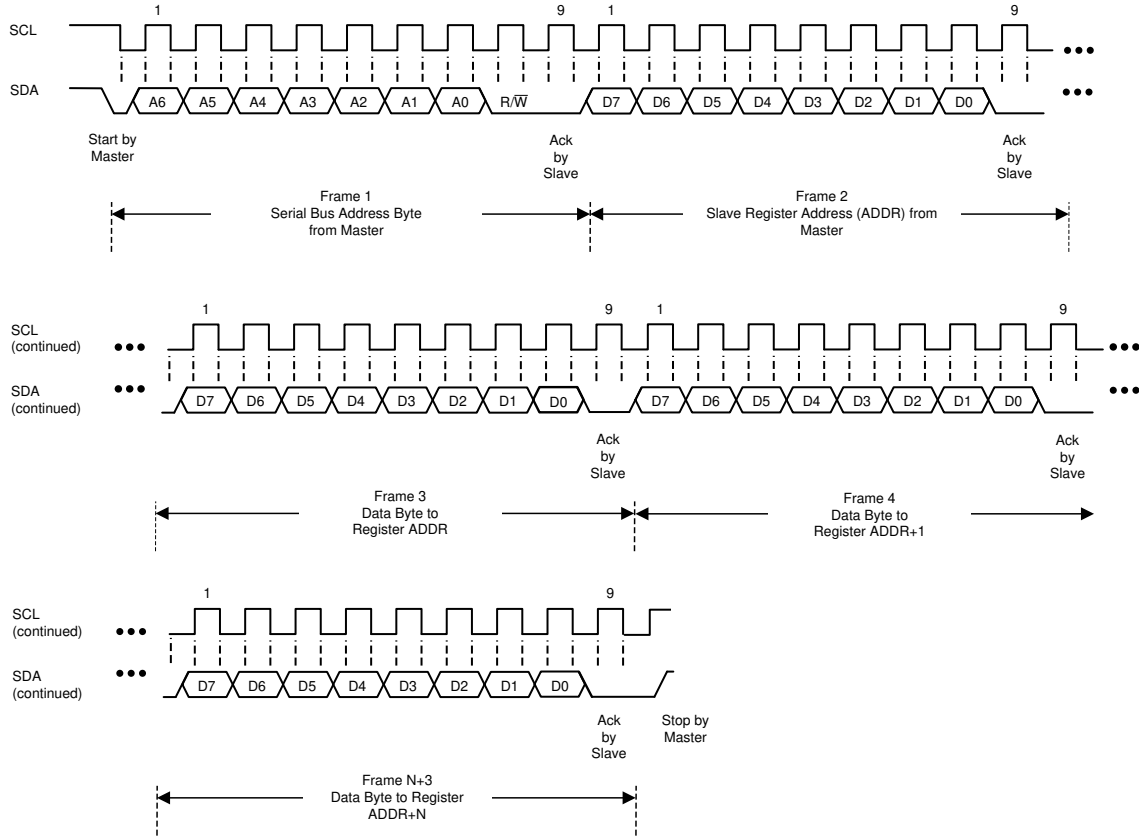
The I<sup>2</sup>C interface pin, the SDA, the SCL, and the INTB pins are all open-drain and 3.3-V compatible. These pins can be used to connect to an MCU which is supplied by 3.3-V supply without requiring voltage level translation between LDC3114 and the MCU.

#### 7.3.8.1 I<sup>2</sup>C Interface Specifications

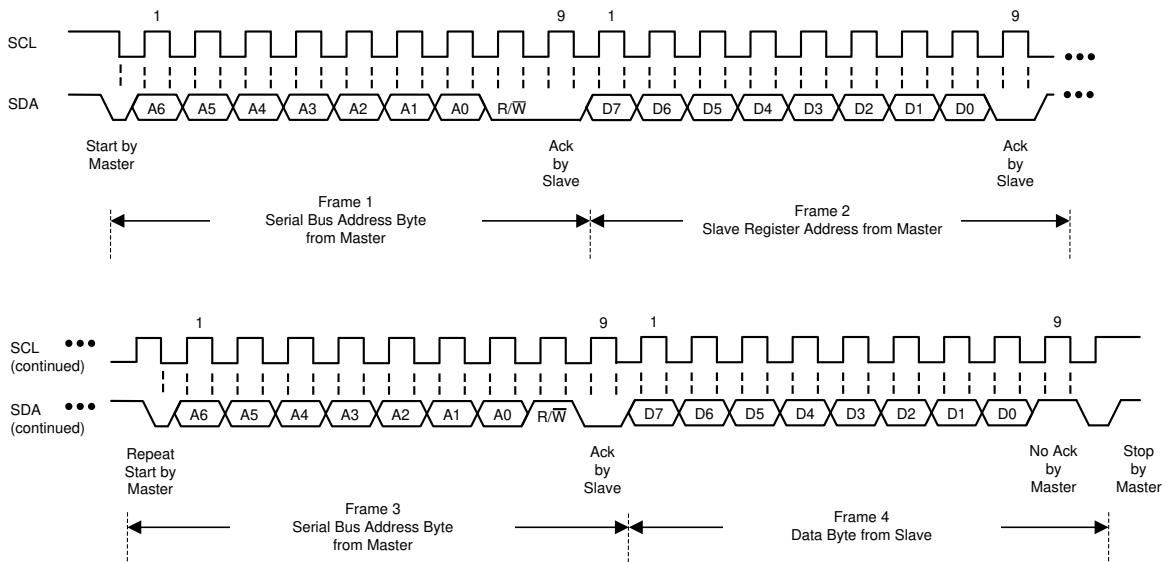
The maximum speed of the I<sup>2</sup>C interface is 400 kHz. This sequence uses the standard I<sup>2</sup>C 7-bit target address followed by an 8-bit pointer to set the register address. For both write and read, the address pointer will auto-increment as long as the controller acknowledges.



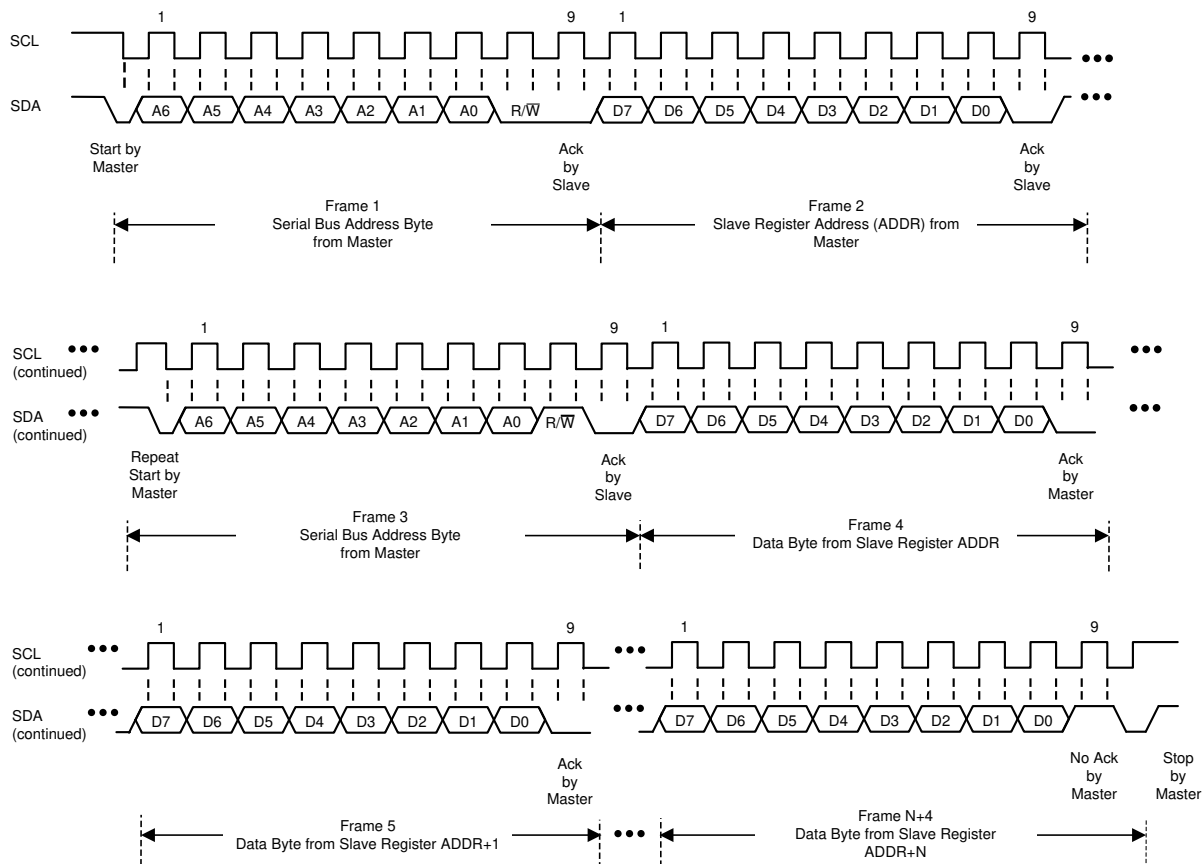
**7-4. I<sup>2</sup>C Sequence of Writing a Single Register**



**7-5. I<sup>2</sup>C Sequence of Writing Consecutive Registers**



**7-6. I<sup>2</sup>C Sequence of Reading a Single Register**



**7-7. I<sup>2</sup>C Sequence of Reading Consecutive Registers**

### 7.3.8.2 I<sup>2</sup>C Bus Control

The LDC3114 cannot drive the I<sup>2</sup>C clock (SCL), that is the device does not support clock stretching. In the unlikely event where the SCL is stuck LOW, power cycle any device that is holding the SCL to activate its internal Power-On Reset (POR) circuit. If the LDC is connected to the same power supply as that device, there will be about 66-ms setup time before the LDC becomes active again. For more information, refer to [Defining Power-On Timing](#). If the data line (SDA) is stuck LOW, the I<sup>2</sup>C controller should send nine clock pulses. The device that is holding the bus LOW should release the bus sometime within those nine clocks. If not, then power cycle to clear the bus.

The LDC3114 has built-in monitors to check that the device is currently working. In the unlikely event of a device fault, the device state will be reset internally, and all the registers will be reset with default settings. For system robustness, TI recommends to check the value of a modified register periodically to monitor the device status and reload the register settings, if needed.

## 7.4 Device Functional Modes

The LDC3114 supports two power modes of operation: a Normal Power Mode for active sampling at 10, 20, 40, or 80 SPS, and a Low Power Mode for reduced current consumption at 0.625, 1.25, 2.5, or 5 SPS. The device can also be configured in Normal Power Mode for additional faster sampling rate of 160 SPS or for a continuous sampling rate. Refer to [Configuring Button or Raw Data Scan Rate](#) for details.

### 7.4.1 Normal Power Mode

When the LPWRB input pin is set to V<sub>DD</sub>, all enabled channels operate in Normal Power Mode. Each channel can be enabled independently through *Register EN (Address 0x0C)*. For the electrical specification of Normal Power Mode Scan Rate, refer to the [Electrical Characteristics](#) table.

## 7.4.2 Low Power Mode

When the LPWRB input pin is set to ground, only the low-power-enabled channels are active. Each channel can be enabled independently to operate in Low Power Mode through *Register EN (Address 0x0C)*. For a channel to operate in the Low Power Mode, both the LPEN $n$  and EN $n$  bits ( $n$  is the channel index) must be set to 1. The Low Power Mode allows for energy-saving monitoring of button activity. In this mode, the device is in an inactive power-saving state for the majority of the time. Lower scan rates correspond to lower current consumption. In addition, the individual button sampling window should be set to the lowest effective setting (this is system dependent, but typically 0.8 ms to 1 ms). For the electrical specification of the configurable Low Power Mode Scan Rate, refer to the [Electrical Characteristics](#) table.

If a channel is operational in both Low Power Mode and Normal Power Mode, TI recommends to toggle the LPWRB pin only after the button associated with that channel is released.

The Low Power Mode is also applicable for raw data access mode.

## 7.4.3 Configuration Mode

Before configuring any register settings, the device must be put into the configuration mode first. Setting CONFIG\_MODE = 1 through *Register RESET (Address 0x0A)* stops data conversion and holds the device in configuration mode. Any device configuration changes can then be made. The current consumption in this mode is typically 0.3 mA. After all changes have been written, set CONFIG\_MODE = 0 for normal operation. Refer to [I<sup>2</sup>C Interface](#) for more information.

## 7.5 Register Maps

### 7.5.1 LDC3114 Registers

[LDC3114 Registers](#) lists the memory-mapped registers for the LDC3114 registers. All register offset addresses not listed in [LDC3114 Registers](#) should be considered as reserved locations and the register contents should not be modified.

**表 7-1. LDC3114 Registers**

Offset	Acronym	Register Name	Section
0h	STATUS	Device status	<a href="#">セクション 7.5.1.1</a>
1h	OUT	Channel output logic states	<a href="#">セクション 7.5.1.2</a>
2h	DATA0_LSB	The lower 8 bits of the Button 0 data (Two's complement)	<a href="#">セクション 7.5.1.3</a>
3h	DATA0_MSB	The upper 4 bits of the Button 0 data (Two's complement)	<a href="#">セクション 7.5.1.4</a>
4h	DATA1_LSB	The lower 8 bits of the Button 1 data (Two's complement)	<a href="#">セクション 7.5.1.5</a>
5h	DATA1_MSB	The upper 4 bits of the Button 1 data (Two's complement)	<a href="#">セクション 7.5.1.6</a>
6h	DATA2_LSB	The lower 8 bits of the Button 2 data (Two's complement)	<a href="#">セクション 7.5.1.7</a>
7h	DATA2_MSB	The upper 4 bits of the Button 2 data (Two's complement)	<a href="#">セクション 7.5.1.8</a>
8h	DATA3_LSB	The lower 8 bits of the Button 3 data (Two's complement)	<a href="#">セクション 7.5.1.9</a>
9h	DATA3_MSB	The upper 4 bits of the Button 3 data (Two's complement)	<a href="#">セクション 7.5.1.10</a>
Ah	RESET	Reset device and register configurations	<a href="#">セクション 7.5.1.11</a>
Ch	EN	Enable channels and low power modes	<a href="#">セクション 7.5.1.12</a>
Dh	NP_SCAN_RATE	Normal Power Mode scan rate	<a href="#">セクション 7.5.1.13</a>
Eh	GAIN0	Gain for Channel 0 sensitivity adjustment for button algorithm	<a href="#">セクション 7.5.1.14</a>
Fh	LP_SCAN_RATE	Low Power Mode scan rate	<a href="#">セクション 7.5.1.15</a>

表 7-1. LDC3114 Registers (continued)

Offset	Acronym	Register Name	Section
10h	GAIN1	Gain for Channel 1 sensitivity adjustment for button algorithm	<a href="#">セクション 7.5.1.16</a>
11h	INTPOL	Interrupt polarity	<a href="#">セクション 7.5.1.17</a>
12h	GAIN2	Gain for Channel 2 sensitivity adjustment for button algorithm	<a href="#">セクション 7.5.1.18</a>
13h	LP_BASE_INC	Low power base increment for button algorithm	<a href="#">セクション 7.5.1.19</a>
14h	GAIN3	Gain for Channel 3 sensitivity adjustment for button algorithm	<a href="#">セクション 7.5.1.20</a>
15h	NP_BASE_INC	Normal power base increment for button algorithm	<a href="#">セクション 7.5.1.21</a>
16h	BTPAUSE_MAXWIN	Baseline tracking pause and Max-win for button algorithm	<a href="#">セクション 7.5.1.22</a>
17h	LC_DIVIDER	LC oscillation frequency divider	<a href="#">セクション 7.5.1.23</a>
18h	HYST	Hysteresis for threshold for button algorithm	<a href="#">セクション 7.5.1.24</a>
19h	TWIST	Anti-twist for button algorithm	<a href="#">セクション 7.5.1.25</a>
1Ah	COMMON_DEFORM	Anti-common and anti-deformation for button algorithm	<a href="#">セクション 7.5.1.26</a>
1Ch	OPOL_DPOL	Output polarity for button data and output	<a href="#">セクション 7.5.1.27</a>
1Eh	CNTSC	Counter scale	<a href="#">セクション 7.5.1.28</a>
20h	SENSOR0_CONFIG	Sensor 0 cycle count, frequency, RP range	<a href="#">セクション 7.5.1.29</a>
22h	SENSOR1_CONFIG	Sensor 1 cycle count, frequency, RP range	<a href="#">セクション 7.5.1.30</a>
24h	SENSOR2_CONFIG	Sensor 2 cycle count, frequency, RP range	<a href="#">セクション 7.5.1.31</a>
25h	FTF0	Sensor 0 fast tracking factor for button algorithm	<a href="#">セクション 7.5.1.32</a>
26h	SENSOR3_CONFIG	Sensor3 cycle count, frequency, RP range	<a href="#">セクション 7.5.1.33</a>
28h	FTF1_2	Sensors 1 and 2 fast tracking factors for button algorithm	<a href="#">セクション 7.5.1.34</a>
2Bh	FTF3	Sensor 3 fast tracking factor for button algorithm	<a href="#">セクション 7.5.1.35</a>
59h	RAW_DATA0_3	Sensor 0 pre-processed raw data	<a href="#">セクション 7.5.1.36</a>
5Ah	RAW_DATA0_2	Sensor 0 pre-processed raw data	<a href="#">セクション 7.5.1.37</a>
5Bh	RAW_DATA0_1	Sensor 0 pre-processed raw data	<a href="#">セクション 7.5.1.38</a>
5Ch	RAW_DATA1_3	Sensor 1 pre-processed raw data	<a href="#">セクション 7.5.1.39</a>
5Dh	RAW_DATA1_2	Sensor 1 pre-processed raw data	<a href="#">セクション 7.5.1.40</a>
5Eh	RAW_DATA1_1	Sensor 1 pre-processed raw data	<a href="#">セクション 7.5.1.41</a>
5Fh	RAW_DATA2_3	Sensor 2 pre-processed raw data	<a href="#">セクション 7.5.1.42</a>
60h	RAW_DATA2_2	Sensor 2 pre-processed raw data	<a href="#">セクション 7.5.1.43</a>
61h	RAW_DATA2_1	Sensor 2 pre-processed raw data	<a href="#">セクション 7.5.1.44</a>
62h	RAW_DATA3_3	Sensor 3 pre-processed raw data	<a href="#">セクション 7.5.1.45</a>
63h	RAW_DATA3_2	Sensor 3 pre-processed raw data	<a href="#">セクション 7.5.1.46</a>
64h	RAW_DATA3_1	Sensor 3 pre-processed raw data	<a href="#">セクション 7.5.1.47</a>
FCh	MANUFACTURER_ID_LSB	Manufacturer ID lower byte	<a href="#">セクション 7.5.1.48</a>
FDh	MANUFACTURER_ID_MSB	Manufacturer ID upper byte	<a href="#">セクション 7.5.1.49</a>
FEh	DEVICE_ID_LSB	Device ID lower byte	<a href="#">セクション 7.5.1.50</a>
FFh	DEVICE_ID_MSB	Device ID upper byte	<a href="#">セクション 7.5.1.51</a>



Complex bit access types are encoded to fit into small table cells. [LDC3114 Access Type Codes](#) shows the codes that are used for access types in this section.

**表 7-2. LDC3114 Access Type Codes**

Access Type	Code	Description
<b>Read Type</b>		
R	R	Read
<b>Write Type</b>		
W	W	Write
<b>Reset or Default Value</b>		
-n		Value after reset or the default value

### 7.5.1.1 STATUS Register (Offset = 0h) [Reset = 40h]

STATUS is shown in [STATUS Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Device status

**表 7-3. STATUS Register Field Descriptions**

Bit	Field	Type	Reset	Description
7	OUT_STATUS	R	0h	<b>Output Status</b> Logic OR of output OUTx bits. This field is cleared by reading this register.
6	CHIP_READY	R	1h	<b>Chip Ready Status</b> 0h = Chip not ready after internal reset 1h = Chip ready after internal reset
5	RDY_TO_WRITE	R	0h	<b>Ready to Write</b> Indicates if registers are ready to be written. See I2C Interface section for more information. 0h = Registers not ready 1h = Registers ready
4	MAXOUT	R	0h	<b>Maximum Output Code</b> Indicates if any channel button output data reaches the maximum value (+0x7FF or -0x800). Cleared by a read of the status register. 0h = No maximum output code 1h = Maximum output code
3	FSM_WD	R	0h	<b>Finite-State Machine Watchdog Error</b> Reports an error has occurred and conversions have been halted. Cleared by a read of the status register. 0h = No error in finite-state machine 1h = Error in finite-state machine
2	LC_WD	R	0h	<b>LC Sensor Watchdog Error</b> Reports an error when any LC oscillator fails to start. Cleared by a read of the status register. 0h = No error in LC oscillator initialization 1h = Error in LC oscillator initialization
1	TIMEOUT	R	0h	<b>Button Timeout</b> Reports when any button is asserted for more than 50 seconds. Cleared by a read of the status register. When DIS_BTN_TO is set, no timeout is asserted 0h = no timeout error 1h = timeout error

表 7-3. STATUS Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
0	REGISTER_FLAG	R	0h	<b>Register Integrity Flag</b> Reports if any register's value has an unexpected change. Cleared by a read of the status register. 0h = No unexpected register change 1h = Unexpected register change

### 7.5.1.2 OUT Register (Offset = 1h) [Reset = 00h]

OUT is shown in [OUT Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Channel output logic states

表 7-4. OUT Register Field Descriptions

Bit	Field	Type	Reset	Description
7-5	RESERVED	R	0h	Reserved
4	DATA_RDY	R	0h	Output Logic State for pre-processed data capture for any enabled channel. Bit cleared on read. 0h = Data Capture in progress 1h = New Data available
3	OUT3	R	0h	<b>Button output Logic State for Channel 3</b> 0h = No button press detected on Channel 3 1h = Button press detected on Channel 3
2	OUT2	R	0h	<b>Button output Logic State for Channel 2</b> 0h = No button press detected on Channel 2 1h = Button press detected on Channel 2
1	OUT1	R	0h	<b>Button output Logic State for Channel 1</b> 0h = No button press detected on Channel 1 1h = Button press detected on Channel 1
0	OUT0	R	0h	<b>Button output Logic State for Channel 0</b> 0h = No button press detected on Channel 0 1h = Button press detected on Channel 0.

### 7.5.1.3 DATA0\_LSB Register (Offset = 2h) [Reset = 00h]

DATA0\_LSB is shown in [DATA0\\_LSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

The lower 8 bits of the Button 0 data (Two's complement)

表 7-5. DATA0\_LSB Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	DATA0[7:0]	R	0h	The lower 8 bits of Channel 0 button data (Two's complement).

### 7.5.1.4 DATA0\_MSB Register (Offset = 3h) [Reset = 00h]

DATA0\_MSB is shown in [DATA0\\_MSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

The upper 4 bits of the Button 0 data (Two's complement)

**表 7-6. DATA0\_MSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	RESERVED	R	0h	Reserved
3-0	DATA0[11:8]	R	0h	The upper 4 bits of Channel 0 button data (Two's complement).

#### 7.5.1.5 DATA1\_LSB Register (Offset = 4h) [Reset = 00h]

DATA1\_LSB is shown in [DATA1\\_LSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

The lower 8 bits of the Button 1 data (Two's complement)

**表 7-7. DATA1\_LSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	DATA1[7:0]	R	0h	The lower 8 bits of Channel 1 button data (Two's complement).

#### 7.5.1.6 DATA1\_MSB Register (Offset = 5h) [Reset = 00h]

DATA1\_MSB is shown in [DATA1\\_MSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

The upper 4 bits of the Button 1 data (Two's complement)

**表 7-8. DATA1\_MSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	RESERVED	R	0h	Reserved
3-0	DATA1[11:8]	R	0h	The upper 4 bits of Channel 1 button data (Two's complement).

#### 7.5.1.7 DATA2\_LSB Register (Offset = 6h) [Reset = 00h]

DATA2\_LSB is shown in [DATA2\\_LSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

The lower 8 bits of the Button 2 data (Two's complement)

**表 7-9. DATA2\_LSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	DATA2[7:0]	R	0h	The lower 8 bits of Channel 2 button data (Two's complement).

#### 7.5.1.8 DATA2\_MSB Register (Offset = 7h) [Reset = 00h]

DATA2\_MSB is shown in [DATA2\\_MSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

The upper 4 bits of the Button 2 data (Two's complement)

**表 7-10. DATA2\_MSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	RESERVED	R	0h	Reserved
3-0	DATA2[11:8]	R	0h	The upper 4 bits of Channel 2 button data (Two's complement).

### 7.5.1.9 DATA3\_LSB Register (Offset = 8h) [Reset = 00h]

DATA3\_LSB is shown in [DATA3\\_LSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

The lower 8 bits of the Button 3 data (Two's complement)

**表 7-11. DATA3\_LSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	DATA3[7:0]	R	0h	The lower 8 bits of Channel 3 button data (Two's complement).

### 7.5.1.10 DATA3\_MSB Register (Offset = 9h) [Reset = 00h]

DATA3\_MSB is shown in [DATA3\\_MSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

The upper 4 bits of the Button 3 data (Two's complement)

**表 7-12. DATA3\_MSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	RESERVED	R	0h	Reserved
3-0	DATA3[11:8]	R	0h	The upper 4 bits of Channel 3 button data (Two's complement).

### 7.5.1.11 RESET Register (Offset = Ah) [Reset = 00h]

RESET is shown in [RESET Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Reset device and register configurations

**表 7-13. RESET Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-5	RESERVED	R/W	0h	Reserved
4	FULL_RESET	R/W	0h	<b>Device Reset</b> 0h = Normal operation 1h = Resets the device and register configurations. All registers will be returned to default values. Normal operation will not resume until STATUS:CHIP_READY = 1.
3-1	RESERVED	R/W	0h	Reserved
0	CONFIG_MODE	R/W	0h	<b>Configuration Mode</b> Any device configuration changes should be made with this bit set to 1. After all configuration changes have been written, set this bit to 0 for normal operation. 0h = Normal operation 1h = Holds the device in configuration mode (no data conversion), but maintains current register configurations.

### 7.5.1.12 EN Register (Offset = Ch) [Reset = 1Fh]

EN is shown in [EN Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Enable channels and low power modes

**表 7-14. EN Register Field Descriptions**

Bit	Field	Type	Reset	Description
7	LPEN3	R/W	0h	<b>Channel 3 Low-Power-Enable</b> 0h = Disable Channel 3 in Low Power Mode 1h = Enable Channel 3 in Low Power Mode. EN3 must also be set to 1.
6	LPEN2	R/W	0h	<b>Channel 2 Low-Power-Enable</b> 0h = Disable Channel 2 in Low Power Mode 1h = Enable Channel 2 in Low Power Mode. EN2 must also be set to 1.
5	LPEN1	R/W	0h	<b>Channel 1 Low-Power-Enable</b> 0h = Disable Channel 1 in Low Power Mode 1h = Enable Channel 1 in Low Power Mode. EN1 must also be set to 1.
4	LPEN0	R/W	1h	<b>Channel 0 Low-Power-Enable</b> 0h = Disable Channel 0 in Low Power Mode 1h = Enable Channel 0 in Low Power Mode. EN0 must also be set to 1.
3	EN3	R/W	1h	<b>Channel 3 Enable</b> 0h = Disable Channel 2 1h = Enable Channel 2
2	EN2	R/W	1h	<b>Channel 2 Enable</b> 0h = Disable Channel 2 1h = Enable Channel 2
1	EN1	R/W	1h	<b>Channel 1 Enable</b> 0h = Disable Channel 1 1h = Enable Channel 1
0	EN0	R/W	1h	<b>Channel 0 Enable</b> 0h = Disable Channel 0 1h = Enable Channel 0

#### 7.5.1.13 NP\_SCAN\_RATE Register (Offset = Dh) [Reset = 01h]

NP\_SCAN\_RATE is shown in [NP\\_SCAN\\_RATE Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Normal Power Mode scan rate

**表 7-15. NP\_SCAN\_RATE Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-4	RESERVED	R/W	0h	Reserved
3	NPFSR	R/W	0h	Normal Power Mode Fast Scan Rate of 160SPS. When set, this bit will override setting in NPSR only and not NPCS.
2	NPCS	R/W	0h	Continuous key scan in Normal Power mode When set, the scan cycle is continuous without delay in the Normal Power mode. The base increment value is fixed. This bit has no effect if the chip is in Low Power mode. This bit will override the setting in NPSR and NPFSR registers.

表 7-15. NP\_SCAN\_RATE Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
1-0	NPSR	R/W	1h	<b>Normal Power Mode Scan Rate</b> Refer to Configuring Button Scan Rate section for more information. 0h = 80 SPS 1h = 40 SPS (Default) 2h = 20 SPS 3h = 10 SPS

#### 7.5.1.14 GAIN0 Register (Offset = Eh) [Reset = 28h]

GAIN0 is shown in [GAIN0 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Gain for Channel 0 sensitivity adjustment for button algorithm

表 7-16. GAIN0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R/W	0h	Reserved
5-0	GAIN0	R/W	28h	<b>Gain for Button Data for Channel 0</b> Refer to the Gain Table for detailed configuration.

#### 7.5.1.15 LP\_SCAN\_RATE Register (Offset = Fh) [Reset = 10h]

LP\_SCAN\_RATE is shown in [LP\\_SCAN\\_RATE Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Low Power Mode scan rate

表 7-17. LP\_SCAN\_RATE Register Field Descriptions

Bit	Field	Type	Reset	Description
7-2	RESERVED	R/W	4h	Reserved
1-0	LPSR	R/W	0h	<b>Low Power Mode Scan Rate</b> Refer to Configuring Button Scan Rate section for more information. 0h = 5 SPS 1h = 2.5 SPS 2h = 1.25 SPS (Default) 3h = 0.625 SPS

#### 7.5.1.16 GAIN1 Register (Offset = 10h) [Reset = 28h]

GAIN1 is shown in [GAIN1 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Gain for Channel 1 sensitivity adjustment for button algorithm

表 7-18. GAIN1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R/W	0h	Reserved
5-0	GAIN1	R/W	28h	<b>Gain for Button Data for Channel 1</b> Refer to the Gain Table for detailed configuration.

### 7.5.1.17 INTPOL Register (Offset = 11h) [Reset = 18h]

INTPOL is shown in [INTPOL Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Interrupt polarity

**表 7-19. INTPOL Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-5	RESERVED	R/W	0h	Reserved
4	BTSRT_EN	R/W	1h	<b>Enable reset of button algorithm baseline tracking value</b> When this bit is not set, during transition between normal power mode to low power mode and back to normal power mode <b>only baseline tracking value</b> for enabled channels not reset. Other values in the button algorithm for calculating button press are reset even if this bit is not set. 0h = Disable Button Algorithm Restart 1h = Enable Button Algorithm Restart
3	BTN_ALG_EN	R/W	1h	<b>Enable button press detection algorithm to assert events on OUT_x pins</b> When disabled, raw pre-processed data can be accessed via RAW_DATAx registers. When disabled, interrupt on INTB pin is asserted when pre-processed data capture is complete after active window period completion for any of the enabled channels or for error events. When disabled, events on OUT_x pins pins are ignored to assert interrupt on INTB pin 0h = Disable Button Algorithm 1h = Enable Button Algorithm
2	INTPOL	R/W	0h	<b>Interrupt Polarity</b> 0h = Set INTB pin polarity to active low 1h = Set INTB pin polarity to active high.
1	DIS_BTN_TO	R/W	0h	Disable Button time-out if if button pressed for more than 50s. 0h = Enable Button Timeout 1h = Disable Button Timeout
0	DIS_BTBT_MO	R/W	0h	Disable setting MAXOUT bit if button algorithm generates codes outside maximum range. 0h = Enable MAXOUT check 1h = Disable MAXOUT check

### 7.5.1.18 GAIN2 Register (Offset = 12h) [Reset = 28h]

GAIN2 is shown in [GAIN2 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Gain for Channel 2 sensitivity adjustment for button algorithm

**表 7-20. GAIN2 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	RESERVED	R/W	0h	Reserved
5-0	GAIN2	R/W	28h	<b>Gain for Button Data for Channel 2</b> Refer to the Gain Table for detailed configuration.

### 7.5.1.19 LP\_BASE\_INC Register (Offset = 13h) [Reset = 05h]

LP\_BASE\_INC is shown in [LP\\_BASE\\_INC Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Low power base increment for button algorithm

**表 7-21. LP\_BASE\_INC Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-3	RESERVED	R/W	0h	Reserved
2-0	LPBI	R/W	5h	<b>Baseline Tracking Increment for button algorithm in Low Power Mode</b>

#### 7.5.1.20 GAIN3 Register (Offset = 14h) [Reset = 28h]

GAIN3 is shown in [GAIN3 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Gain for Channel 3 sensitivity adjustment for button algorithm

**表 7-22. GAIN3 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	RESERVED	R/W	0h	Reserved
5-0	GAIN3	R/W	28h	<b>Gain for Button Data for Channel 3</b> Refer to the Gain Table for detailed configuration.

#### 7.5.1.21 NP\_BASE\_INC Register (Offset = 15h) [Reset = 03h]

NP\_BASE\_INC is shown in [NP\\_BASE\\_INC Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Normal power base increment for button algorithm

**表 7-23. NP\_BASE\_INC Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-3	RESERVED	R/W	0h	Reserved
2-0	NPBI	R/W	3h	<b>Baseline Tracking Increment in Normal Power Mode for button algorithm</b> Refer to Tracking Baseline section for more information.

#### 7.5.1.22 BTPAUSE\_MAXWIN Register (Offset = 16h) [Reset = 00h]

BTPAUSE\_MAXWIN is shown in [BTPAUSE\\_MAXWIN Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Baseline tracking pause and Max-win for button algorithm

**表 7-24. BTPAUSE\_MAXWIN Register Field Descriptions**

Bit	Field	Type	Reset	Description
7	BTPAUSE3	R/W	0h	<b>Baseline Tracking Pause for Channel 3</b> Pauses baseline tracking for button algorithm for Channel 3 when OUT3 is asserted. Refer to Tracking Baseline section for more information. 0h = Normal baseline tracking for Channel 1 regardless of OUT3 status. 1h = Pauses baseline tracking for Channel 1 when OUT3 is asserted.



**表 7-24. BTPAUSE\_MAXWIN Register Field Descriptions (continued)**

Bit	Field	Type	Reset	Description
6	BTPAUSE2	R/W	0h	<b>Baseline Tracking Pause for Channel 2</b> Pauses baseline tracking for button algorithm for Channel 2 when OUT2 is asserted. Refer to Tracking Baseline section for more information. 0h = Normal baseline tracking for Channel 1 regardless of OUT2 status. 1h = Pauses baseline tracking for Channel 1 when OUT2 is asserted.
5	BTPAUSE1	R/W	0h	<b>Baseline Tracking Pause for Channel 1</b> Pauses baseline tracking for button algorithm for Channel 1 when OUT1 is asserted. Refer to Tracking Baseline section for more information. 0h = Normal baseline tracking for Channel 1 regardless of OUT1 status. 1h = Pauses baseline tracking for Channel 1 when OUT1 is asserted.
4	BTPAUSE0	R/W	0h	<b>Baseline Tracking Pause for Channel 0</b> Pauses baseline tracking for button algorithm for Channel 0 when OUT0 is asserted. Refer to Tracking Baseline section for more information. 0h = Normal baseline tracking for Channel 0 regardless of OUT0 status. 1h = Pauses baseline tracking for Channel 0 when OUT0 is asserted.
3	MAXWIN3	R/W	0h	<b>Max-Win Button Algorithm Setting for Channel 3</b> Refer to Resolving Simultaneous Button Presses (Max-Win) section for more information. 0h = Exclude Channel 3 from the max-win group 1h = Include Channel 3 in the max-win group
2	MAXWIN2	R/W	0h	<b>Max-Win Button Algorithm Setting for Channel 2</b> Refer to Resolving Simultaneous Button Presses (Max-Win) section for more information. 0h = Exclude Channel 2 from the max-win group 1h = Include Channel 2 in the max-win group
1	MAXWIN1	R/W	0h	<b>Max-Win Button Algorithm Setting for Channel 1</b> Refer to Resolving Simultaneous Button Presses (Max-Win) section for more information. 0h = Exclude Channel 1 from the max-win group 1h = Include Channel 1 in the max-win group
0	MAXWIN0	R/W	0h	<b>Max-Win Button Algorithm Setting for Channel 0</b> Refer to Resolving Simultaneous Button Presses (Max-Win) section for more information. 0h = Exclude Channel 0 from the max-win group 1h = Include Channel 0 in the max-win group

### 7.5.1.23 LC\_DIVIDER Register (Offset = 17h) [Reset = 03h]

LC\_DIVIDER is shown in [LC\\_DIVIDER Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

LC oscillation frequency divider

**表 7-25. LC\_DIVIDER Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-3	RESERVED	R/W	0h	Reserved

表 7-25. LC\_DIVIDER Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
2-0	LCDIV	R/W	3h	<b>LC Oscillation Frequency Divider</b> The frequency divider sets the button sampling window in conjunction with SENCYCn

**7.5.1.24 HYST Register (Offset = 18h) [Reset = 08h]**

HYST is shown in [HYST Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Hysteresis for threshold for button algorithm

表 7-26. HYST Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	RESERVED	R/W	0h	Reserved
3-0	HYST	R/W	8h	<b>Hysteresis</b> Defines the hysteresis for button triggering threshold. Hysteresis = HYST * 4 Refer to Setting Button Triggering Threshold section for more information.

**7.5.1.25 TWIST Register (Offset = 19h) [Reset = 00h]**

TWIST is shown in [TWIST Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Anti-twist for button algorithm

表 7-27. TWIST Register Field Descriptions

Bit	Field	Type	Reset	Description
7-3	RESERVED	R/W	0h	Reserved
2-0	ANTITWIST	R/W	0h	<b>Anti-Twist</b> When set to 0, the anti-twist for button algorithm is not enabled. When greater than 0, all buttons are enabled for the anti-twist button algorithm. The validation of all buttons is void if any button's BTN_DATA is negative by a threshold. Anti-twist Threshold = ANTITWIST * 4. Refer to Overcoming Case Twisting (Anti-Twist) section for more information.

**7.5.1.26 COMMON\_DEFORM Register (Offset = 1Ah) [Reset = 00h]**

COMMON\_DEFORM is shown in [COMMON\\_DEFORM Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Anti-common and anti-deformation for button algorithm

表 7-28. COMMON\_DEFORM Register Field Descriptions

Bit	Field	Type	Reset	Description
7	ANTICOM3	R/W	0h	<b>Anti-Common Button Algorithm Setting for Channel 3</b> Refer to Eliminating Common-Mode Change (Anti-Common) section for more information. 0h = Exclude Channel 3 from the anti-common group. 1h = Include Channel 3 in the anti-common group.

**表 7-28. COMMON\_DEFORM Register Field Descriptions (continued)**

Bit	Field	Type	Reset	Description
6	ANTICOM2	R/W	0h	<b>Anti-Common Button Algorithm Setting for Channel 2</b> Refer to Eliminating Common-Mode Change (Anti-Common) section for more information. 0h = Exclude Channel 2 from the anti-common group. 1h = Include Channel 2 in the anti-common group.
5	ANTICOM1	R/W	0h	<b>Anti-Common Button Algorithm Setting for Channel 1</b> Refer to Eliminating Common-Mode Change (Anti-Common) section for more information. 0h = Exclude Channel 1 from the anti-common group. 1h = Include Channel 1 in the anti-common group.
4	ANTICOM0	R/W	0h	<b>Anti-Common Button Algorithm Setting for Channel 0</b> Refer to Eliminating Common-Mode Change (Anti-Common) section for more information. 0h = Exclude Channel 0 from the anti-common group. 1h = Include Channel 0 in the anti-common group.
3	ANTIDFORM3	R/W	0h	<b>Anti-Deform Button Algorithm Setting for Channel 3</b> Refer to Mitigating Metal Deformation (Anti-Deform) section for more information. 0h = Exclude Channel 3 from the anti-deform group. 1h = Include Channel 3 in the anti-deform group.
2	ANTIDFORM2	R/W	0h	<b>Anti-Deform Button Algorithm Setting for Channel 2</b> Refer to Mitigating Metal Deformation (Anti-Deform) section for more information. 0h = Exclude Channel 2 from the anti-deform group. 1h = Include Channel 2 in the anti-deform group.
1	ANTIDFORM1	R/W	0h	<b>Anti-Deform Button Algorithm Setting for Channel 1</b> Refer to Mitigating Metal Deformation (Anti-Deform) section for more information. 0h = Exclude Channel 1 from the anti-deform group. 1h = Include Channel 1 in the anti-deform group.
0	ANTIDFORM0	R/W	0h	<b>Anti-Deform Button Algorithm Setting for Channel 0</b> Refer to Mitigating Metal Deformation (Anti-Deform) section for more information. 0h = Exclude Channel 0 from the anti-deform group. 1h = Include Channel 0 in the anti-deform group.

### 7.5.1.27 OPOL\_DPOL Register (Offset = 1Ch) [Reset = 0Fh]

OPOL\_DPOL is shown in [OPOL\\_DPOL Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Output polarity for button data and output

**表 7-29. OPOL\_DPOL Register Field Descriptions**

Bit	Field	Type	Reset	Description
7	OPOL3	R/W	0h	<b>Button Output Polarity for OUT3 Pin</b> 0h = Active low (Default) 1h = Active high
6	OPOL2	R/W	0h	<b>Button Output Polarity for OUT2 Pin</b> 0h = Active low (Default) 1h = Active high
5	OPOL1	R/W	0h	<b>Button Output Polarity for OUT1 Pin</b> 0h = Active low (Default) 1h = Active high

表 7-29. OPOL\_DPOL Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
4	OPOL0	R/W	0h	<b>Button Output Polarity for OUT0 Pin</b> 0h = Active low (Default) 1h = Active high
3	DPOL3	R/W	1h	<b>Processed Button Algorithm Data Polarity for Channel 3</b> 0h = BTN_DATA3 decreases as fSENSOR3 increases 1h = DATA3 increases as fSENSOR3 increases.
2	DPOL2	R/W	1h	<b>Processed Button Algorithm Data Polarity for Channel 2</b> 0h = BTN_DATA2 decreases as fSENSOR2 increases 1h = DATA2 increases as fSENSOR2 increases.
1	DPOL1	R/W	1h	<b>Processed Button Algorithm Data Polarity for Channel 1</b> 0h = BTN_DATA1 decreases as fSENSOR1 increases 1h = DATA1 increases as fSENSOR1 increases.
0	DPOL0	R/W	1h	<b>Processed Button Algorithm Data Polarity for Channel 0</b> 0h = BTN_DATA0 decreases as fSENSOR0 increases 1h = DATA0 increases as fSENSOR0 increases.

#### 7.5.1.28 CNTSC Register (Offset = 1Eh) [Reset = 55h]

CNTSC is shown in [CNTSC Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Counter scale

表 7-30. CNTSC Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	CNTSC3	R/W	1h	<b>Counter Scale for Channel 3</b> Refer to Scaling Frequency Counter Output section for more information. 0h = CNTSC3 is 0 1h = CNTSC3 is 1 2h = CNTSC3 is 2 3h = CNTSC3 is 3
5-4	CNTSC2	R/W	1h	<b>Counter Scale for Channel 2</b> Refer to Scaling Frequency Counter Output section for more information. 0h = CNTSC2 is 0 1h = CNTSC2 is 1 2h = CNTSC2 is 2 3h = CNTSC2 is 3
3-2	CNTSC1	R/W	1h	<b>Counter Scale for Channel 1</b> Refer to Scaling Frequency Counter Output section for more information. 0h = CNTSC1 is 0 1h = CNTSC1 is 1 2h = CNTSC1 is 2 3h = CNTSC1 is 3

**表 7-30. CNTSC Register Field Descriptions (continued)**

Bit	Field	Type	Reset	Description
1-0	CNTSC0	R/W	1h	<b>Counter Scale for Channel 0</b> Refer to Scaling Frequency Counter Output section for more information. 0h = CNTSC0 is 0 1h = CNTSC0 is 1 2h = CNTSC0 is 2 3h = CNTSC0 is 3

#### 7.5.1.29 SENSOR0\_CONFIG Register (Offset = 20h) [Reset = 04h]

SENSOR0\_CONFIG is shown in [SENSOR0\\_CONFIG Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 0 cycle count, frequency, RP range

**表 7-31. SENSOR0\_CONFIG Register Field Descriptions**

Bit	Field	Type	Reset	Description
7	RP0	R/W	0h	<b>Channel 0 Sensor Rp Range Select</b> Set based on the actual sensor Rp physical parameter. Refer to Designing Sensor Parameters section for more information. 0h = $50 \Omega \leq R_p \leq 4 \text{ k}\Omega$ (Default) 1h = $800 \Omega \leq R_p \leq 10 \text{ k}\Omega$
6-5	FREQ0	R/W	0h	<b>Channel 0 Sensor Frequency Range Select</b> Refer to Designing Sensor Parameters section for more information. 0h = 1 MHz to 3.3 MHz 1h = 3.3 MHz to 10 MHz 2h = 10 MHz to 30 MHz 3h = Reserved
4-0	SENCYC0	R/W	4h	<b>Channel 0 Sensor Cycle Count</b> SENCYC0 sets the Channel 0 button sampling window in conjunction with LCDIV. Refer to Programming Button Sampling Window section for more information.

#### 7.5.1.30 SENSOR1\_CONFIG Register (Offset = 22h) [Reset = 04h]

SENSOR1\_CONFIG is shown in [SENSOR1\\_CONFIG Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 1 cycle count, frequency, RP range

**表 7-32. SENSOR1\_CONFIG Register Field Descriptions**

Bit	Field	Type	Reset	Description
7	RP1	R/W	0h	<b>Channel 1 Sensor Rp Range Select</b> Set based on the actual sensor Rp physical parameter. Refer to Designing Sensor Parameters section for more information. 0h = $50 \Omega \leq R_p \leq 4 \text{ k}\Omega$ (Default) 1h = $800 \Omega \leq R_p \leq 10 \text{ k}\Omega$
6-5	FREQ1	R/W	0h	<b>Channel 1 Sensor Frequency Range Select</b> Refer to Designing Sensor Parameters section for more information. 0h = 1 MHz to 3.3 MHz 1h = 3.3 MHz to 10 MHz 2h = 10 MHz to 30 MHz 3h = Reserved

表 7-32. SENSOR1\_CONFIG Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
4-0	SENCYC1	R/W	4h	<b>Channel 1 Sensor Cycle Count</b> SENCYC1 sets the Channel 1 button sampling window in conjunction with LCDIV. Refer to Programming Button Sampling Window section for more information.

### 7.5.1.31 SENSOR2\_CONFIG Register (Offset = 24h) [Reset = 04h]

SENSOR2\_CONFIG is shown in [SENSOR2\\_CONFIG Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 2 cycle count, frequency, RP range

表 7-33. SENSOR2\_CONFIG Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RP2	R/W	0h	<b>Channel 2 Sensor Rp Range Select</b> Set based on the actual sensor Rp physical parameter. Refer to Designing Sensor Parameters section for more information. 0h = $50 \Omega \leq R_p \leq 4 \text{ k}\Omega$ (Default) 1h = $800 \Omega \leq R_p \leq 10 \text{ k}\Omega$
6-5	FREQ2	R/W	0h	<b>Channel 2 Sensor Frequency Range Select</b> Refer to Designing Sensor Parameters section for more information. 0h = 1 MHz to 3.3 MHz 1h = 3.3 MHz to 10 MHz 2h = 10 MHz to 30 MHz 3h = Reserved
4-0	SENCYC2	R/W	4h	<b>Channel 2 Sensor Cycle Count</b> SENCYC2 sets the Channel 2 button sampling window in conjunction with LCDIV. Refer to Programming Button Sampling Window section for more information.

### 7.5.1.32 FTF0 Register (Offset = 25h) [Reset = DAh]

FTF0 is shown in [FTF0 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 0 fast tracking factor for button algorithm

表 7-34. FTF0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-3	RESERVED	R/W	1Bh	Reserved
2-1	FTF0	R/W	1h	<b>Fast Tracking Factor for Channel 0</b> Defines baseline tracking for button algorithm speed for negative values of DATA0. Refer to Tracking Baseline section for more information. 0h = FTF0 is 0 1h = FTF0 is 1 2h = FTF0 is 2 3h = FTF0 is 3
0	RESERVED	R/W	0h	Reserved

### 7.5.1.33 SENSOR3\_CONFIG Register (Offset = 26h) [Reset = 04h]

SENSOR3\_CONFIG is shown in [SENSOR3\\_CONFIG Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor3 cycle count, frequency, RP range

**表 7-35. SENSOR3\_CONFIG Register Field Descriptions**

Bit	Field	Type	Reset	Description
7	RP3	R/W	0h	<b>Channel 3 Sensor Rp Range Select</b> Set based on the actual sensor Rp physical parameter. Refer to Designing Sensor Parameters section for more information. 0h = $50 \Omega \leq R_p \leq 4 \text{ k}\Omega$ (Default) 1h = $800 \Omega \leq R_p \leq 10 \text{ k}\Omega$
6-5	FREQ3	R/W	0h	<b>Channel 3 Sensor Frequency Range Select</b> Refer to Designing Sensor Parameters section for more information. 0h = 1 MHz to 3.3 MHz 1h = 3.3 MHz to 10 MHz 2h = 10 MHz to 30 MHz 3h = Reserved
4-0	SENCYC3	R/W	4h	<b>Channel 3 Sensor Cycle Count</b> SENCYC3 sets the Channel 3 button sampling window in conjunction with LCDIV. Refer to Programming Button Sampling Window section for more information.

#### 7.5.1.34 FTF1\_2 Register (Offset = 28h) [Reset = 50h]

FTF1\_2 is shown in [FTF1\\_2 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensors 1 and 2 fast tracking factors for button algorithm

**表 7-36. FTF1\_2 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-6	FTF2	R/W	1h	<b>Fast Tracking Factor for Channel 2</b> Defines baseline tracking for button algorithm speed for negative values of DATA2. Refer to Tracking Baseline section for more information. 0h = FTF2 is 0 1h = FTF2 is 1 2h = FTF2 is 2 3h = FTF2 is 3
5-4	FTF1	R/W	1h	<b>Fast Tracking Factor for Channel 0</b> Defines baseline tracking for button algorithm speed for negative values of DATA1. Refer to Tracking Baseline section for more information. 0h = FTF1 is 0 1h = FTF1 is 1 2h = FTF1 is 2 3h = FTF1 is 3
3-0	RESERVED	R/W	0h	Reserved

#### 7.5.1.35 FTF3 Register (Offset = 2Bh) [Reset = 01h]

FTF3 is shown in [FTF3 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 3 fast tracking factor for button algorithm

表 7-37. FTF3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-2	RESERVED	R/W	0h	Reserved
1-0	FTF3	R/W	1h	<b>Fast Tracking Factor for Channel 3</b> Defines baseline tracking for button algorithm speed for negative values of DATA3. Refer to Tracking Baseline section for more information. 0h = FTF3 is 0 1h = FTF3 is 1 2h = FTF3 is 2 3h = FTF3 is 3

#### 7.5.1.36 RAW\_DATA0\_3 Register (Offset = 59h) [Reset = 00h]

RAW\_DATA0\_3 is shown in [RAW\\_DATA0\\_3 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 0 pre-processed raw data

表 7-38. RAW\_DATA0\_3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	RAW_DATA0[7:0]	R	0h	Sensor 0 pre-processed raw data

#### 7.5.1.37 RAW\_DATA0\_2 Register (Offset = 5Ah) [Reset = 00h]

RAW\_DATA0\_2 is shown in [RAW\\_DATA0\\_2 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 0 pre-processed raw data

表 7-39. RAW\_DATA0\_2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	RAW_DATA0[15:8]	R	0h	Sensor 0 pre-processed raw data

#### 7.5.1.38 RAW\_DATA0\_1 Register (Offset = 5Bh) [Reset = 00h]

RAW\_DATA0\_1 is shown in [RAW\\_DATA0\\_1 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 0 pre-processed raw data

表 7-40. RAW\_DATA0\_1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	RAW_DATA0[23:16]	R	0h	Sensor 0 pre-processed raw data

#### 7.5.1.39 RAW\_DATA1\_3 Register (Offset = 5Ch) [Reset = 00h]

RAW\_DATA1\_3 is shown in [RAW\\_DATA1\\_3 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 1 pre-processed raw data



**表 7-41. RAW\_DATA1\_3 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	RAW_DATA1[7:0]	R	0h	Sensor 1 pre-processed raw data

#### 7.5.1.40 RAW\_DATA1\_2 Register (Offset = 5Dh) [Reset = 00h]

RAW\_DATA1\_2 is shown in [RAW\\_DATA1\\_2 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 1 pre-processed raw data

**表 7-42. RAW\_DATA1\_2 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	RAW_DATA1[15:8]	R	0h	Sensor 1 pre-processed raw data

#### 7.5.1.41 RAW\_DATA1\_1 Register (Offset = 5Eh) [Reset = 00h]

RAW\_DATA1\_1 is shown in [RAW\\_DATA1\\_1 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 1 pre-processed raw data

**表 7-43. RAW\_DATA1\_1 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	RAW_DATA1[23:16]	R	0h	Sensor 1 pre-processed raw data

#### 7.5.1.42 RAW\_DATA2\_3 Register (Offset = 5Fh) [Reset = 00h]

RAW\_DATA2\_3 is shown in [RAW\\_DATA2\\_3 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 2 pre-processed raw data

**表 7-44. RAW\_DATA2\_3 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	RAW_DATA2[7:0]	R	0h	Sensor 2 pre-processed raw data

#### 7.5.1.43 RAW\_DATA2\_2 Register (Offset = 60h) [Reset = 00h]

RAW\_DATA2\_2 is shown in [RAW\\_DATA2\\_2 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 2 pre-processed raw data

**表 7-45. RAW\_DATA2\_2 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	RAW_DATA2[15:8]	R	0h	Sensor 2 pre-processed raw data

#### 7.5.1.44 RAW\_DATA2\_1 Register (Offset = 61h) [Reset = 00h]

RAW\_DATA2\_1 is shown in [RAW\\_DATA2\\_1 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 2 pre-processed raw data

**表 7-46. RAW\_DATA2\_1 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	RAW_DATA2[23:16]	R	0h	Sensor 2 pre-processed raw data

#### 7.5.1.45 RAW\_DATA3\_3 Register (Offset = 62h) [Reset = 00h]

RAW\_DATA3\_3 is shown in [RAW\\_DATA3\\_3 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 3 pre-processed raw data

**表 7-47. RAW\_DATA3\_3 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	RAW_DATA3[7:0]	R	0h	Sensor 3 pre-processed raw data

#### 7.5.1.46 RAW\_DATA3\_2 Register (Offset = 63h) [Reset = 00h]

RAW\_DATA3\_2 is shown in [RAW\\_DATA3\\_2 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 3 pre-processed raw data

**表 7-48. RAW\_DATA3\_2 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	RAW_DATA3[15:8]	R	0h	Sensor 3 pre-processed raw data

#### 7.5.1.47 RAW\_DATA3\_1 Register (Offset = 64h) [Reset = 00h]

RAW\_DATA3\_1 is shown in [RAW\\_DATA3\\_1 Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Sensor 3 pre-processed raw data

**表 7-49. RAW\_DATA3\_1 Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	RAW_DATA3[23:16]	R	0h	Sensor 3 pre-processed raw data

#### 7.5.1.48 MANUFACTURER\_ID\_LSB Register (Offset = FCh) [Reset = 49h]

MANUFACTURER\_ID\_LSB is shown in [MANUFACTURER\\_ID\\_LSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Manufacturer ID lower byte

**表 7-50. MANUFACTURER\_ID\_LSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	MANUFACTURER_ID_[7:0]	R	49h	Manufacturer ID [7:0]

### 7.5.1.49 MANUFACTURER\_ID\_MSB Register (Offset = FDh) [Reset = 54h]

MANUFACTURER\_ID\_MSB is shown in [MANUFACTURER\\_ID\\_MSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Manufacturer ID upper byte

**表 7-51. MANUFACTURER\_ID\_MSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	MANUFACTURER_ID_[15:8]	R	54h	Manufacturer ID [15:8]

### 7.5.1.50 DEVICE\_ID\_LSB Register (Offset = FEh) [Reset = 00h]

DEVICE\_ID\_LSB is shown in [DEVICE\\_ID\\_LSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Device ID lower byte

**表 7-52. DEVICE\_ID\_LSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	DEVICE_ID_[7:0]	R	0h	Device ID [7:0]

### 7.5.1.51 DEVICE\_ID\_MSB Register (Offset = FFh) [Reset = 40h]

DEVICE\_ID\_MSB is shown in [DEVICE\\_ID\\_MSB Register Field Descriptions](#).

Return to the [LDC3114 Registers](#).

Device ID upper byte

**表 7-53. DEVICE\_ID\_MSB Register Field Descriptions**

Bit	Field	Type	Reset	Description
7-0	DEVICE_ID_[15:8]	R	40h	Device ID [15:8]

## 7.5.2 Gain Table for Registers GAIN0, GAIN1, GAIN2, and GAIN3

**表 7-54. GAIN $n$  Bit Values in Decimal and Corresponding Normalized Gain Factors**

BIT VALUE IN DECIMAL	NORMALIZED GAIN FACTOR	BIT VALUE IN DECIMAL	NORMALIZED GAIN FACTOR
0	1.0	32	16
1	1.0625	33	17
2	1.1875	34	19
3	1.3125	35	21
4	1.4375	36	23
5	1.5625	37	25
6	1.6875	38	27
7	1.8125	39	29
8	2.0	40	32
9	2.125	41	34
10	2.375	42	38
11	2.625	43	42
12	2.875	44	46
13	3.125	45	50
14	3.375	46	54
15	3.625	47	58
16	4.0	48	64
17	4.25	49	68
18	4.75	50	76
19	5.25	51	84
20	5.75	52	92
21	6.25	53	100
22	6.75	54	108
23	7.25	55	116
24	8.0	56	128
25	8.5	57	136
26	9.5	58	152
27	10.5	59	168
28	11.5	60	184
29	12.5	61	200
30	13.5	62	216
31	14.5	63	232

## 8 Application and Implementation

### Note

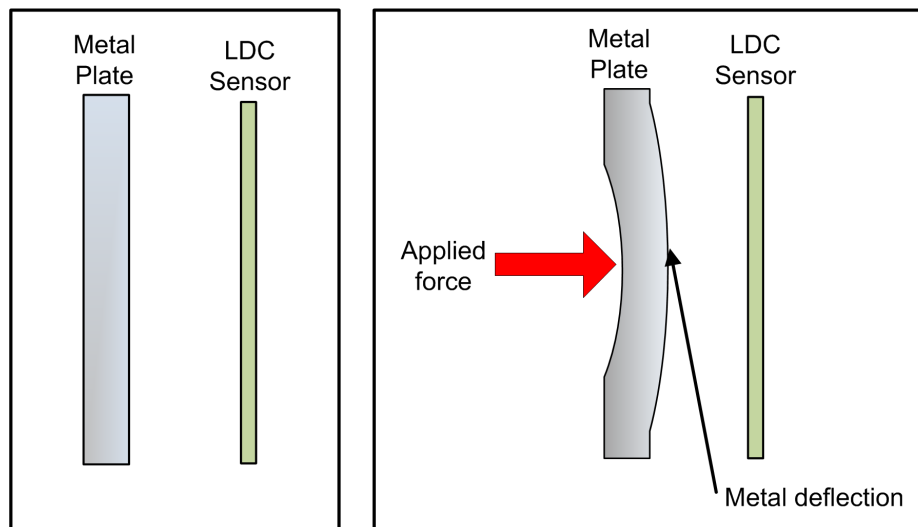
以下のアプリケーション情報は、TI の製品仕様に含まれるものではなく、TI ではその正確性または完全性を保証いたしません。個々の目的に対する製品の適合性については、お客様の責任で判断していただくこととなります。お客様は自身の設計実装を検証しテストすることで、システムの機能を確認する必要があります。

### 8.1 Application Information

The LDC3114 supports multiple buttons. Each button can be configured in various ways for optimal operation.

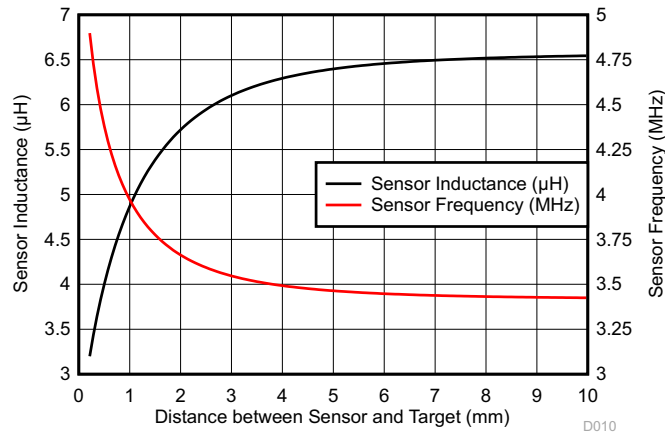
#### 8.1.1 Theory of Operation

An AC current flowing through an inductor will generate an AC magnetic field. If a conductive material, such as a metal object, is in close proximity to the inductor, the magnetic field will induce circulating eddy currents on the surface of the conductor. The eddy currents are a function of the distance, size, and composition of the conductor. If the conductor is deflected toward the inductor as shown in [Figure 8-1](#), more eddy currents will be generated.



**Figure 8-1. Metal Deflection**

The eddy currents create their own magnetic field, which opposes the original field generated by the inductor. This effect reduces the effective inductance of the system, resulting in an increase in sensor frequency. [Figure 8-2](#) shows the inductance and frequency response of an example sensor with a diameter of 14 mm. As the sensitivity of an inductive sensor increases with closer targets, the conductive plate should be placed quite close to the sensor—typically 10% of the sensor diameter for circular coils. For rectangular or race-track-shaped coils, the target to sensor distance should typically be less than 10% of the shorter side of the coil.

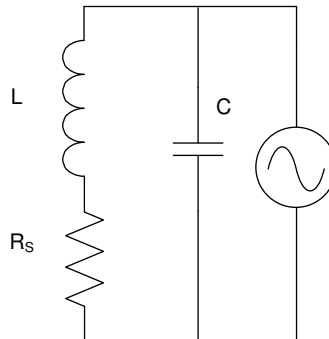


**Figure 8-2. Sensor Inductance and Frequency vs. Target Distance. Sensor Diameter = 14 mm**

The output  $DATA_n$  registers (Addresses 0x02 through 0x09) of the LDC3114 contain the processed values of the changes in sensor frequencies.

### 8.1.2 Designing Sensor Parameters

Figure 8-3 shows that each inductive touch button uses an LC resonator sensor, where L is the inductor, C is the capacitor, and  $R_S$  is the AC series resistance of the sensor at the frequency of operation. The key parameters of the LC sensor include frequency, effective parallel resistance  $R_P$ , and quality factor Q. These parameters must be within the ranges as specified in the *Sensor* section of the *Electrical Characteristics* table. Note that the effective  $R_P$  and Q changes when the conductive target is in place.



**Figure 8-3. LC Resonator**

The LC sensor frequency defined in Equation 3 must be between 1 MHz and 30 MHz. For optimal performance, configure the sensor frequency to be greater than 3 MHz.

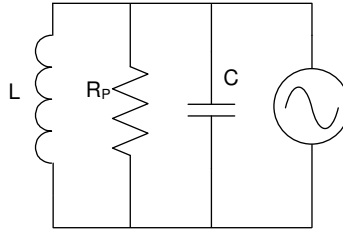
$$f_{\text{SENSOR}} = \frac{1}{2\pi\sqrt{LC}} \quad (3)$$

The sensor quality factor defined in Equation 4 must be between 5 and 30.

$$Q_{\text{SENSOR}} = \frac{1}{R_S} \sqrt{\frac{L}{C}} \quad (4)$$

The series resistance defined in Equation 5 can be represented as an equivalent parallel resistance,  $R_P$ .

$$R_P = \frac{L}{R_S C} \quad (5)$$



8-4. Equivalent Parallel Circuit

$R_P$  can be viewed as the load on the sensor driver. This load corresponds to the current drive required to maintain the oscillation amplitude.  $R_P$  must be between  $350\ \Omega$  and  $10\ \text{k}\Omega$ .

In summary, the LDC3114 requires that the sensor parameters are within the following ranges when the conductive target is present:

- $1\ \text{MHz} \leq f_{\text{SENSOR}} \leq 30\ \text{MHz}$
- $5 \leq Q \leq 30$
- $350\ \Omega \leq R_P \leq 10\ \text{k}\Omega$

### 8.1.3 Setting COM Pin Capacitor

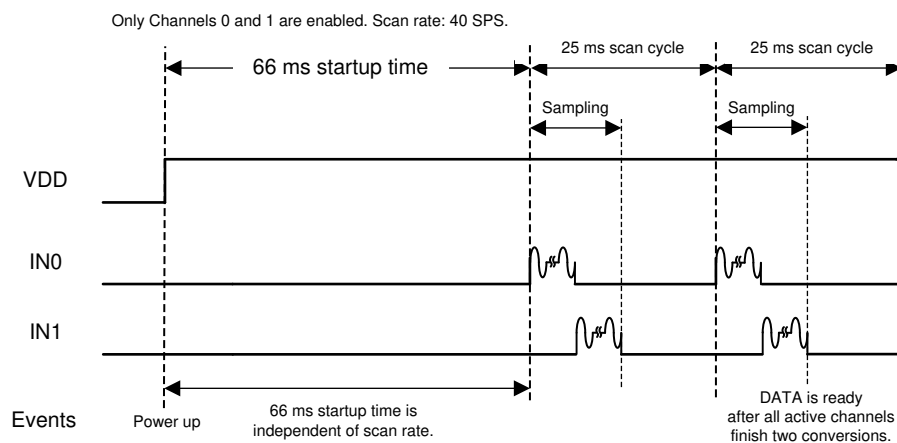
The COM pin requires a bypass capacitor to ground. The capacitor should be a low-ESL, low-ESR type.  $C_{\text{COM}}$  must be sized so that the following relationship is valid for all channels.

$$100 \times C_{\text{SENSOR}n} / Q_{\text{SENSOR}n} < C_{\text{COM}} < 1250 \times C_{\text{SENSOR}n} / Q_{\text{SENSOR}n} \quad (6)$$

The value of  $Q_{\text{SENSOR}n}$  when the sensor is at the minimum target distance should be used. The maximum acceptable value for  $C_{\text{COM}}$  is  $20\ \text{nF}$ . The  $C_{\text{COM}}$  range for a particular sensor configuration can be obtained with the *Spiral\_Inductor\_Designer* tab of the [LDC Calculations Tool](#).

### 8.1.4 Defining Power-On Timing

The low power architecture of the LDC3114 makes it possible for the device to be active all the time. When not being used, the LDC3114 can operate in Low Power Mode with a single standby power button, which typically consumes less than  $10\ \mu\text{A}$ . If additional power-saving is desired, or in the rare event where a power-on reset becomes necessary (see [I<sup>2</sup>C Interface](#)), the output data will become ready after 50-ms start-up time, about 1-ms optional register loading time, and two sampling windows for all active channels. 8-5 shows the power-on timing of the LDC3114.



8-5. Power-On Timing

### 8.1.5 Configuring Button or Raw Data Scan Rate

The LDC3114 periodically samples all active channels at the selected scan rate. The device can operate at eight different scan rates to meet various power consumption requirements, where a lower scan rate achieves lower power consumption.

In Normal Power Mode, the scan rate can be programmed to 80, 40, 20, or 10 SPS through *Register NP\_SCAN\_RATE (Address 0x0D)*. Additionally through NPFSR bit field in the same register 160 SPS rate can be enabled which overrides the setting of NPSR but not the NPSC bit fields. The NPSC bit field allows to set the part in continuous sampling mode in Normal Power Mode only. When NPSC is set then the settings for NPSR and NPFSR are ignored.

In Low Power Mode, the scan rate can be programmed to 5, 2.5, 1.25, or 0.625 SPS through *Register LP\_SCAN\_RATE (Address 0x0F)*. The mode is selected by setting the LPWRB pin to VDD (Normal Power) or ground (Low Power). In either mode, each button can be independently enabled through a bit in *Register EN (Address 0x0C)*. [Figure 6-9](#) shows the typical distribution of the scan rates.

**表 8-1. Scan Rates**

SCAN RATE (SPS)	LPSR (0x0F) SETTING	NPSR (0x0D) SETTING	NPSC (0x0D) SETTING	NPFSR (0x0D) SETTING	LPWRB PIN SETTING
0.625	b11	Not Applicable	Not Applicable	Not Applicable	Ground
1.25	b10	Not Applicable	Not Applicable	Not Applicable	Ground
2.5	b01	Not Applicable	Not Applicable	Not Applicable	Ground
5	b00	Not Applicable	Not Applicable	Not Applicable	Ground
10	Not Applicable	b11	b0	b0	V <sub>DD</sub>
20	Not Applicable	b10	b0	b0	V <sub>DD</sub>
40	Not Applicable	b01	b0	b0	V <sub>DD</sub>
80	Not Applicable	b00	b0	b0	V <sub>DD</sub>
160	Not Applicable	Not Applicable	b0	b1	V <sub>DD</sub>
Continuous	Not Applicable	Not Applicable	b1	Not Applicable	V <sub>DD</sub>

### 8.1.6 Programming Button or Raw Data Sampling Window

The sampling window is the actual duration per scan cycle for active data sampling of the sensor frequency. It is programmed with the exponential parameter, LCDIV, in *Register LC\_DIVIDER (Address 0x17)*, and the individual linear sensor cycle counter SENCYC<sub>n</sub> ( $n = 0, 1, 2, \text{ or } 3$ ) in Registers SENSOR<sub>n</sub>\_CONFIG ( $n = 0, 1, 2, \text{ or } 3$ , Addresses 0x20, 0x22, 0x24, 0x26). For most touch button applications, the button sampling window should be set to between 1 ms and 8 ms. For sampling rate of 160 SPS, the window has to be less than 6.25 ms. For continuous sampling, the data becomes available at the configured sampling window period rate. The recommended minimum sensor conversion time is 1 ms. Longer conversion time can be used to achieve better signal-to-noise ratio, if needed. The active channels in [Figure 8-6](#) will sample sequentially if multiple channels are enabled.



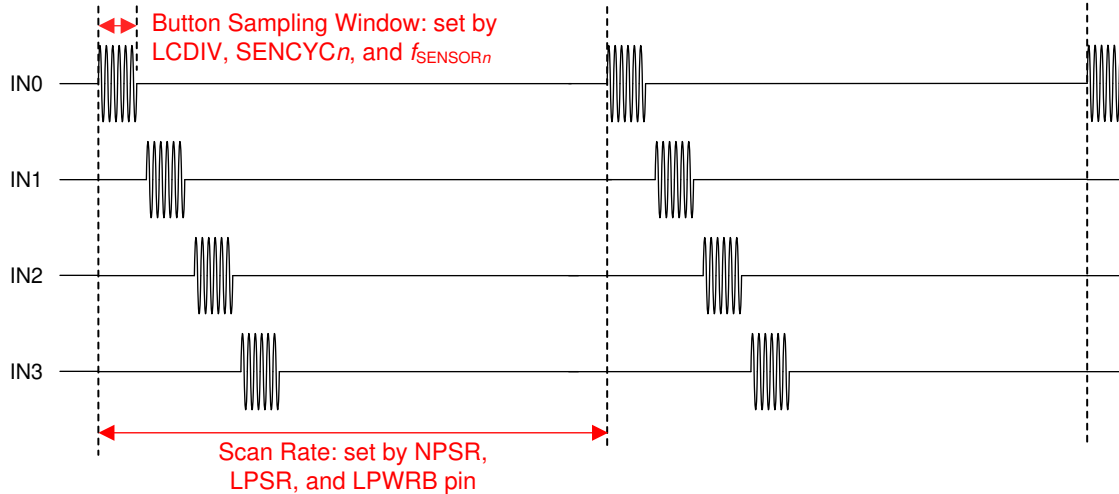


图 8-6. Configurable Scan Rate and Sampling Window

The LDC3114 is designed to work with LC resonator sensors with oscillation frequencies ranging from 1 MHz to 30 MHz. 式 7 calculates the exact definition of the sampling window.

$$\text{Button Sampling Window} = \frac{\text{Number of Sensor Oscillation Cycles}}{\text{Sensor Frequency}}$$

$$t_{\text{SAMPLE}} = \frac{128 \times (\text{SENCYC}n + 1) \times 2^{\text{LCDIV}}}{f_{\text{SENSOR}n}}, n = 0, 1, 2, \text{ or } 3 \quad (7)$$

where:

- $t_{\text{SAMPLE}}$  is the sampling window in  $\mu\text{s}$
- SENCYCn and LCDIV are the linear and exponential scalers that set the number of sensor oscillation cycles
- $f_{\text{SENSOR}n}$  is the sensor frequency in MHz

In 式 7, LCDIV (0 to 7, default 3) is the exponential LC divider that sets the approximate ranges for all channels, and SENCYCn (0 to 31, default 4) is the linear sensor cycle scaler that fine-tunes each individual channel. Together they set the number of sensor oscillation cycles used to determine the sampling window.

For example, if the LC sensor frequency is 9.2 MHz, and it is desirable to get 1-ms sampling window, then this can be achieved by setting SENCYCn = 17 and LCDIV = 2.

Alternatively, from the sampling window and sensor frequency, the LCDIV can be read off from [LCDIV as a Function of Sensor Frequency and Button Sampling Window](#) 图 8-7. For example, 1-ms sampling window and 9.2-MHz sensor frequency intersect in the region closest to where LCDIV = 2. Then SENCYCn can be calculated accordingly.

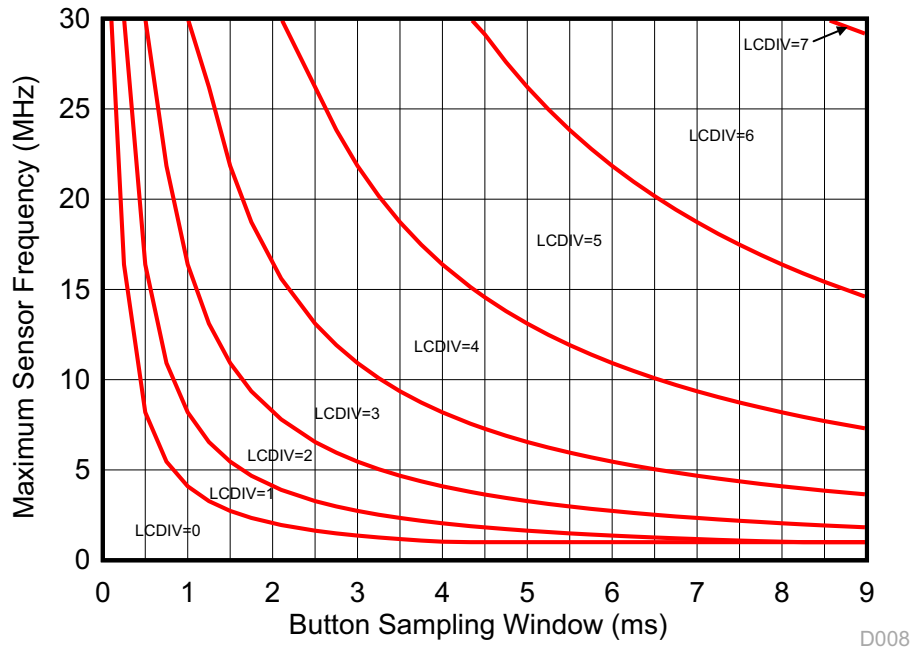


图 8-7. LCDIV as a Function of Sensor Frequency and Button Sampling Window

### 8.1.7 Scaling Frequency Counter Output

The LDC3114 requires this internal frequency counter scaler to be set based on the button sampling window to avoid data overflow. Use 式 8 to set the scaler in *Register CNTSC* (Address 0x1E):

$$CNTSC_n = LCDIV + \text{ceiling} \left( \log_2 \frac{0.0861 \times (SENCYC_n + 1)}{f_{\text{SENSOR}_n}} \right), \quad (n = 0, 1, 2, \text{ or } 3) \quad (8)$$

where:

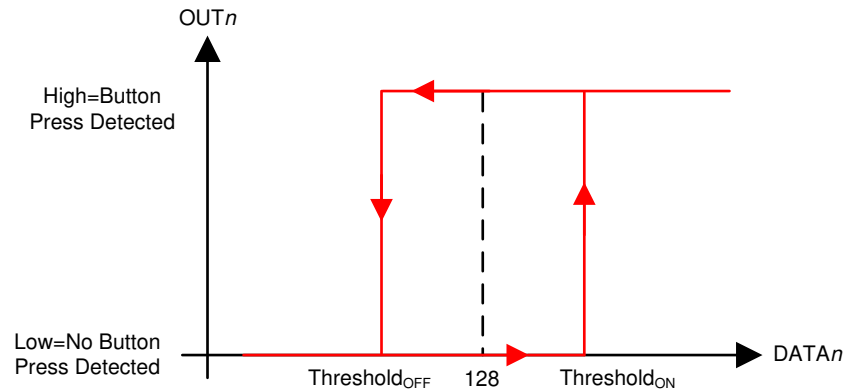
- $CNTSC_n$  is the internal frequency counter scaler
- $SENCYC_n$  and  $LCDIV$  are the linear and exponential scalers that set the number of sensor oscillation cycles
- $f_{\text{SENSOR}_n}$  is the sensor frequency in MHz

### 8.1.8 Setting Button Triggering Threshold

Every material shows some hysteresis when the material deforms then returns to the original state. The amount of hysteresis is a function of material properties and physical parameters, such as size and thickness. This feature modifies the hysteresis of the button signal threshold according to different materials and various button shapes and sizes. Hysteresis can be programmed in *Register HYST* (Address 0x18). By default, the button triggering hysteresis is set to 32. The nominal button triggering threshold is 128. With hysteresis, the effective on-threshold is  $128 + 32 = 160$ . This means if the  $DATA_n$  ( $n = 0, 1, 2, \text{ or } 3$ ) reaches 160, the LDC3114 considers that as a button press. When the  $DATA_n$  decreases to  $128 - 32 = 96$ , the LDC considers the button to be released.

$$\text{Threshold}_{\text{ON}} = 128 + \text{Hysteresis} \quad (9)$$

$$\text{Threshold}_{\text{OFF}} = 128 - \text{Hysteresis} \quad (10)$$



8-8. Button Triggering Threshold with Hysteresis. Output Polarity: Active High

### 8.1.9 Tracking Baseline

The LDC3114 automatically tracks slow changes in the baseline signal and compensates for environmental drifts and variations. The baseline tracking is only applicable for the button algorithm mode and not for raw data access mode. See [Multimode Operation](#) for details. In Normal Power Mode, use [式 11](#) to determine the effective baseline increment per scan cycle ( $BINC_{NP}$ ):

$$BINC_{NP} = \frac{2^{NPBI}}{72} \quad (11)$$

where:

- NPBI is the Normal Power Baseline Increment index that can be configured in *Register NP\_BASE\_INC (Address 0x15)*

In Low Power Mode, use [式 12](#) to determine the effective baseline increment per scan cycle ( $BINC_{LP}$ ):

$$BINC_{LP} = \frac{2^{LPBI}}{9} \quad (12)$$

where:

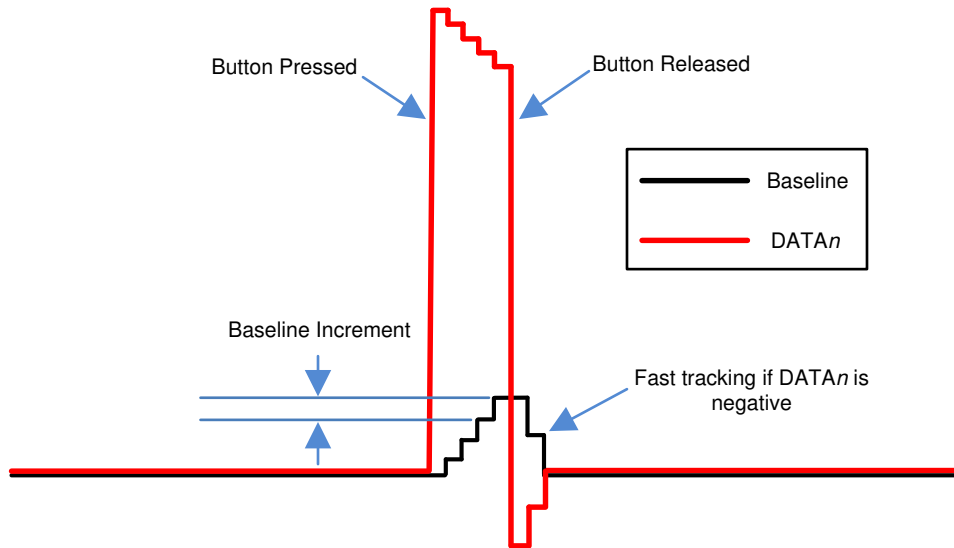
- LPBI the Low Power Baseline Increment index that can be configured in *Register LP\_BASE\_INC (Address 0x13)*

As a result of baseline tracking, a button press with a constant force only lasts for a finite amount of time. [式 13](#) defines the duration of a button press ( $DATAn > Threshold_{ON}$ ).

$$\text{Duration of Button Press} = \frac{DATAn - Threshold_{OFF}}{BINC} \quad (13)$$

where:

- Duration of Button Press is the number of scan cycles that the channel is asserted
- $DATAn$  is the button signal at the beginning of a press
- BINC is the baseline increment per scan cycle



**图 8-9. Baseline Tracking in the Presence of a Button Press**

The baseline tracking for a particular channel can be paused when the channel output is asserted. This is achieved by setting the corresponding BTPAUSE bit in *Register BTPAUSE\_MAXWIN (Address 0x16)* to b1.

If  $DATA_n$  is negative, the tracking speed will be scaled by the fast tracking factor as specified in *Registers FTF0 (Address 0x25)*, *FTF1\_2 (Address 0x28)*, or *FTF3 (Address 0x2B)*. 表 8-2 shows the scaling factors for various  $FTF_n$  settings.

$$BINC (DATA_n < 0) = Fast\_Tracking\_Factor\_n \times BINC (DATA_n > 0) \quad (14)$$

**表 8-2. Fast Tracking Factor Settings**

FTF <sub>n</sub> Setting	Fast Tracking Factor
b00	1
b01	4
b10	8
b11	16

**Note**

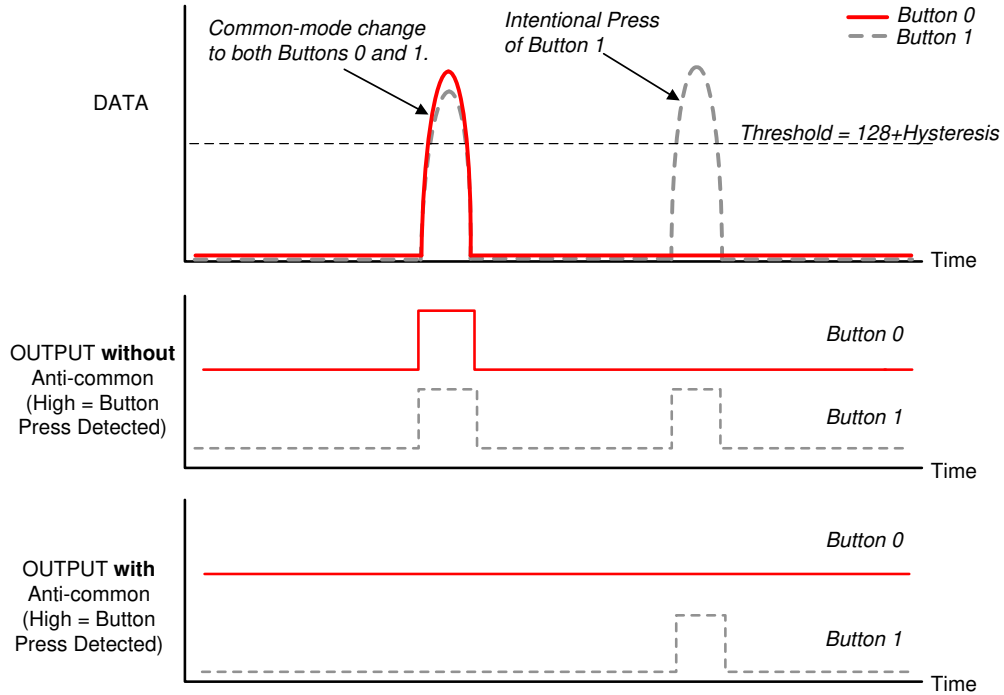
When the continuous sampling rate using NPCS bit is set, the baseline tracking increment is a fixed value.

**8.1.10 Mitigating False Button Detections**

The LDC3114 offers several algorithms that can mitigate false button detections due to mechanical non-idealities associated with groups of buttons. These are listed below.

**8.1.10.1 Eliminating Common-Mode Change (Anti-Common)**

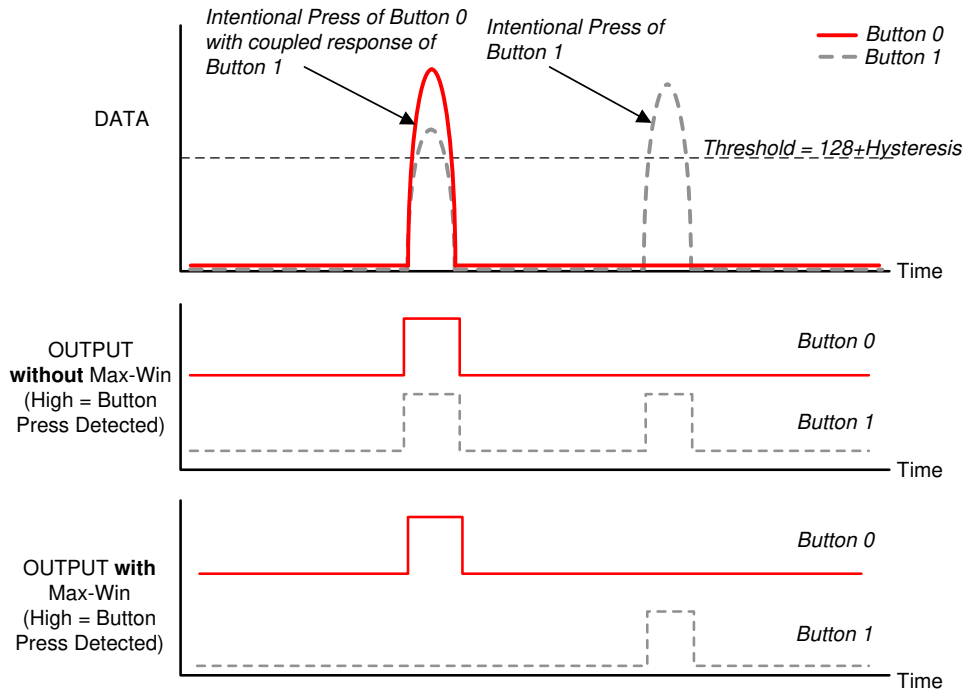
This algorithm eliminates false detection when a user presses the middle of two or more buttons, which could lead to a common-mode response on multiple buttons. All the buttons can be individually enabled to have this feature by programming *Register COMMON\_DEFORM (Address 0x1A)*.



8-10. Illustration of the Anti-Common Feature

### 8.1.10.2 Resolving Simultaneous Button Presses (Max-Win)

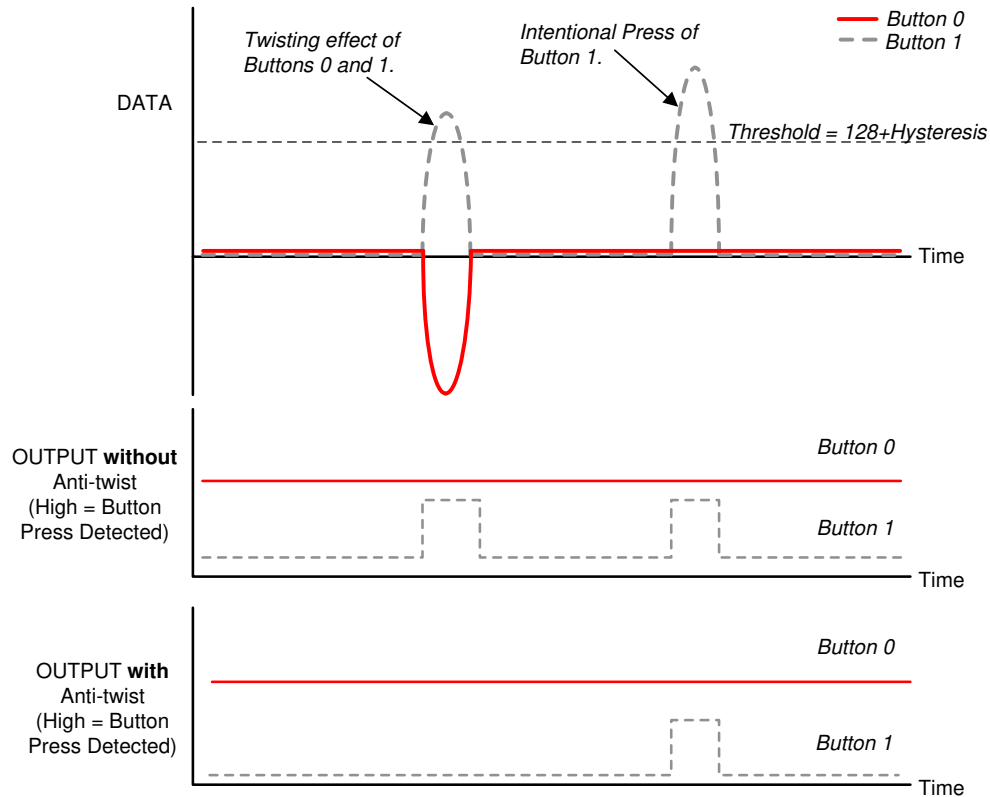
This algorithm enables the system to select the button pressed with maximum force when multiple buttons are pressed at the same time. This could happen when two buttons are physically very close to each other, and pressing one causes a residual reaction on the other. Buttons can be individually enabled to join the “max-win” group by configuring Register *BTPAUSE\_MAXWIN* (Address 0x16).



8-11. Illustration of the Max-Win Feature

### 8.1.10.3 Overcoming Case Twisting (Anti-Twist)

The anti-twist algorithm reduces the likelihood of false detection when the case is twisted, which could cause unintended mechanical activation of the buttons, or an opposite reaction in two adjacent buttons. When this algorithm is enabled, detection of button presses is suppressed if any button's output data is negative by a configurable threshold. The anti-twist algorithm can be enabled by configuring *Register TWIST (Address 0x19)*.



✎ 8-12. Illustration of the Anti-Twist Feature

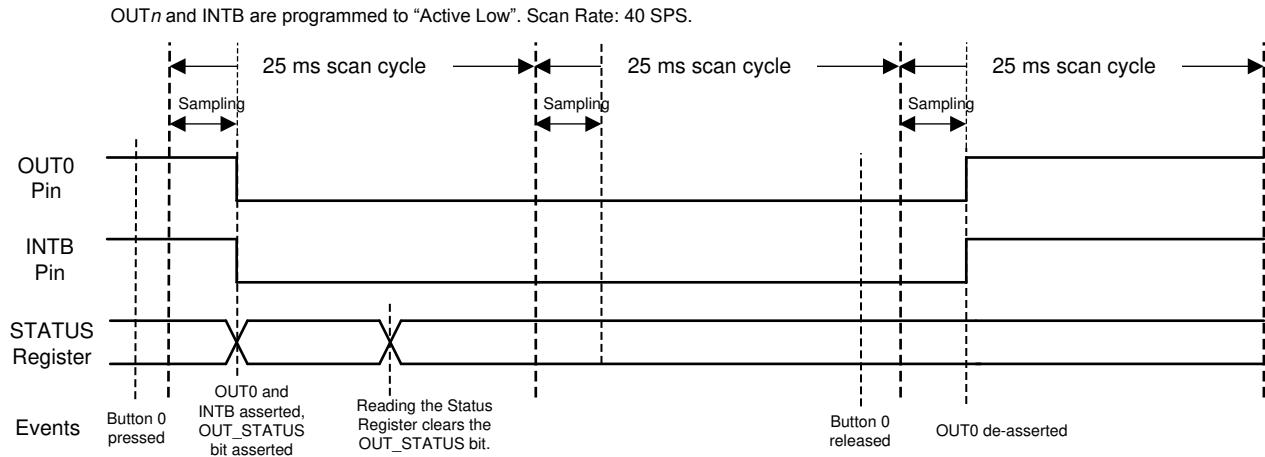
### 8.1.10.4 Mitigating Metal Deformation (Anti-Deform)

This function filters changes due to metal deformation in the vicinity of one or more buttons. Such metal deformation can be accidentally caused by pressing a neighboring button that does not have sufficient mechanical isolation. The user can specify which buttons to join the anti-deform group by configuring *Register COMMON\_DEFORM (Address 0x1A)*.

### 8.1.11 Reporting Interrupts for Button Presses, Raw Data Ready and Error Conditions

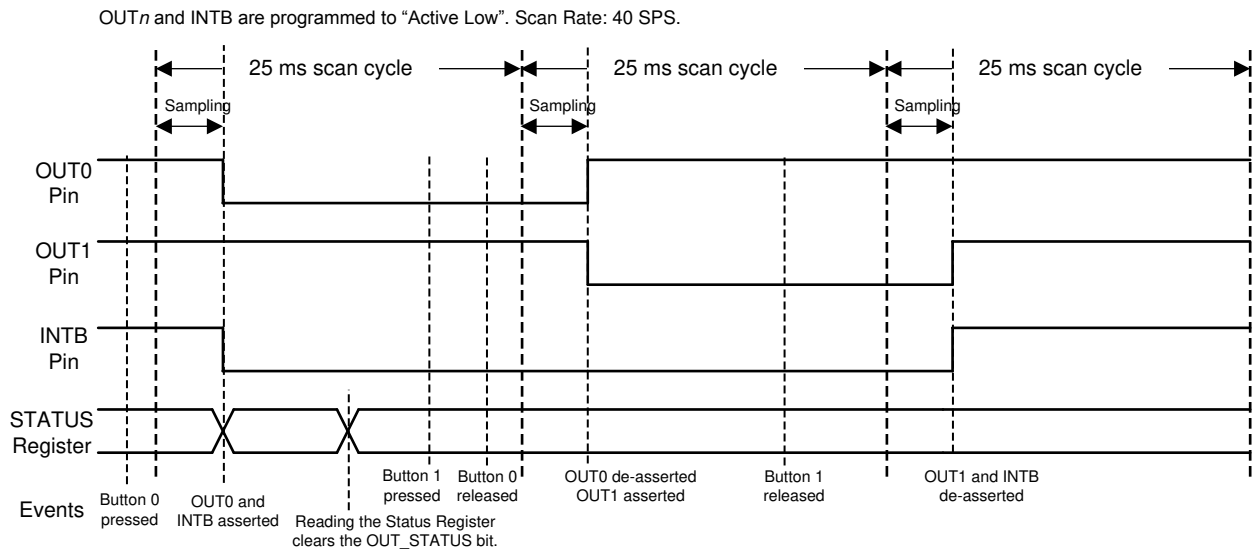
INTB, the LDC3114 interrupt pin, is asserted when a button press or an error condition occurs. The default polarity is active low and can be configured through *Register INTPOL (Address 0x11)*.

✎ 8-13 shows the LDC3114 response to a single button press on Channel 0. At the end of the button sampling window following a press of Button 0, the OUT0 pin and INTB pin are asserted. The OUT\_STATUS bit changes from 0 to 1, and remains so until a read of the STATUS register clears it. The OUT<sub>n</sub> ( $n = 0, 1, 2, \text{ or } 3$ ) and INTB pins are asserted until the end of the button sampling window following the release of the button.



8-13. Timing Diagram of a Single Button Press

8-14 shows the LDC3114 response to multiple button presses. In this example, after Button 0 is pressed, the OUT<sub>0</sub> pin is asserted. After that, Button 1 is also pressed, following which Button 0 is released. The OUT<sub>0</sub> pin is de-asserted and OUT<sub>1</sub> pin asserted at the end of the next button sampling window. The INTB pin remains continuously asserted as long as at least one of the buttons is pressed. The OUT\_STATUS bit only changes from 0 to 1 after the first button assertion.



8-14. Timing Diagram of Multiple Button Presses

The INTB pin also reports any error event. If an error occurs, the INTB pin is asserted and the error is reported in the STATUS register (Address 0x00). Refer to the [Register Maps](#) section for possible error events.

For Raw data access mode, the OUT<sub>x</sub> pins are not used and INTB pin along with error is also used to assert when the sampling cycle is complete and data is available for all channels.

### 8.1.12 Estimating Supply Current

When the LDC3114 is active (in either Normal Power Mode or Low Power Mode), use [式 15](#) to determine the current:

$$I_{ACTIVE_n} = 1.6 + \frac{12}{1 + 16 \times R_{Pn}^{1.21}} + 0.011 \times f_{SENSOR_n} \quad (15)$$

where

- $I_{ACTIVE_n}$  is the supply current in mA during active sampling
- $R_{Pn}$  is the sensor parallel resonant impedance in k $\Omega$
- $f_{SENSOR_n}$  is the sensor frequency in MHz
- $n$  is the channel index, that is,  $n = 0, 1, 2,$  or  $3$  for LDC3114

The LDC3114 is only actively sampling the enabled channels during a fraction of the scan window. [式 16](#) determines the average supply current:

$$I_{DD} = \frac{1}{t_{SCAN}} \times \left( \sum_n I_{ACTIVE_n} \times t_{SAMPLE_n} \right) + 0.005 \quad (16)$$

where

- $I_{DD}$  is the average supply current in mA
- $t_{SCAN}$  is the scan window (set by the [scan rate](#)) in ms
- $I_{ACTIVE_n}$  is the supply current when the device is active as defined by [式 15](#)
- $t_{SAMPLE}$  is the [button sampling window](#) in ms


## 8.2 Typical Application

### 8.2.1 Touch Button Design

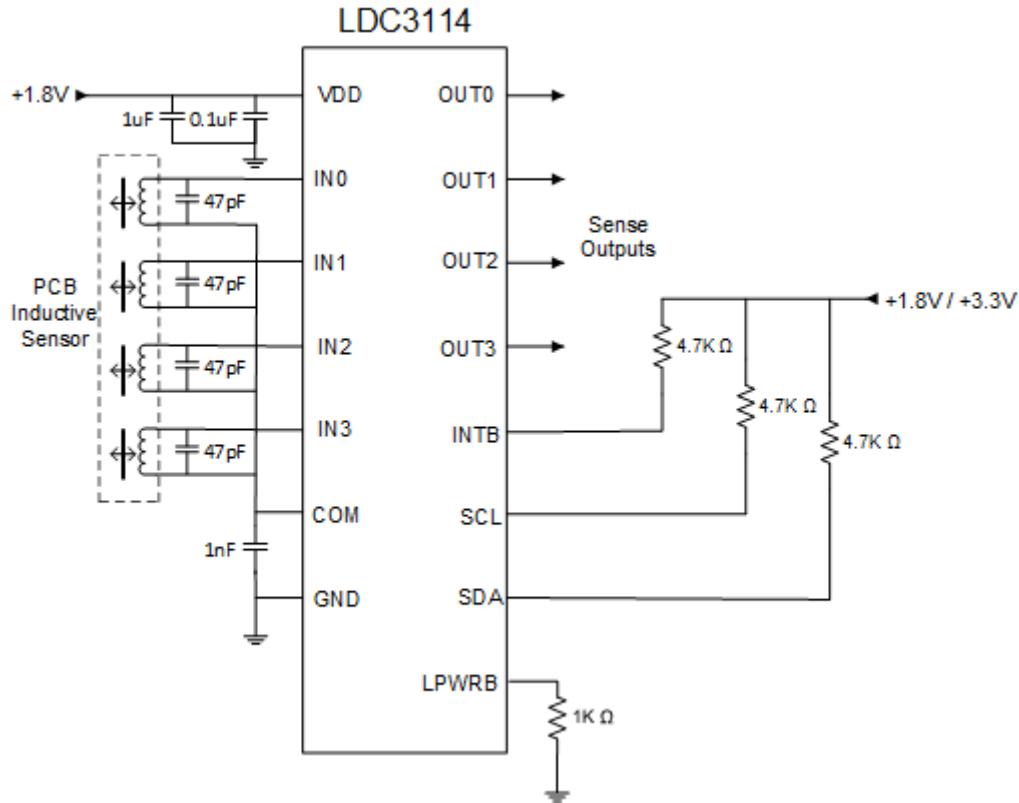
The low power architecture of LDC3114 makes them suitable for driving button sensors in consumer electronics, such as mobile phones. Most mobile phones today have three buttons along the edges, namely the power button, volume up, and volume down.

On a typical smartphone, the two volume buttons are next to each other, so they may be susceptible to false detections such as simultaneous button presses. To prevent such mis-triggers, they can be grouped together to take advantage of the various features that mitigate false detections as explained in [Mitigating False Button Detections](#). For example, if Max-win is applied to the two volume buttons, only the one with the greater force will be triggered.

The inductive touch solution does not require any mechanical cutouts at the button locations. This can support reduced manufacturing cost for the phone case and enhance the case resistance to moisture, dust, and dirt. This is a great advantage compared to mechanical buttons in the market today.

 [8-15](#) shows a typical touch button application.





8-15. Application Schematic

### 8.2.1.1 Design Requirements

The sensor parameters, including frequency,  $R_p$ , and Q factor have to be within the design space of the LDC3114 as specified in the [Electrical Characteristics](#) table.

### 8.2.1.2 Detailed Design Procedure


The LDC3114 is a multichannel device. The italic  $n$  in the parameters below refers to the channel index:

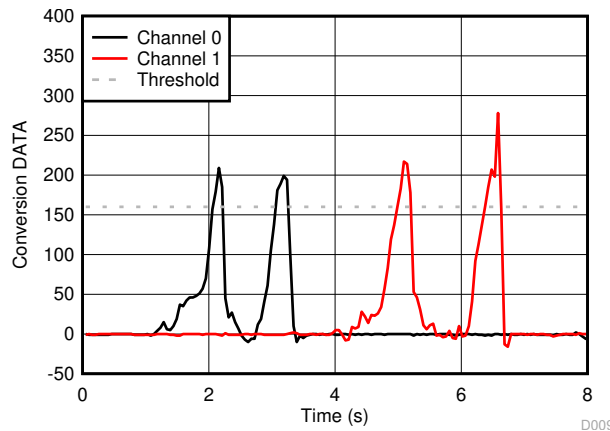
- Select system-based options:
  - Select Normal or Low Power Mode of operation by setting the LPWRB pin to  $V_{DD}$  or ground, respectively. Configure the enable bits for all channels in *Register EN (Address 0x0C)*.
  - Select the polarities of  $OUT_n$  and INTB pins by configuring *Register OPOL\_DPOL (Address 0x1C)* and *Register INTPOL (Address 0x11)*.
  - Configure the sensor frequency setting in Registers  $SENSOR_n\_CONFIG$  (Addresses *0x20, 0x22, 0x24, 0x26*).
- Choose the sampling rate (80, 40, 20, 10, 5, 2.5, 1.25, or 0.625 SPS) based on system power consumption requirement, and configure *Register NP\_SCAN\_RATE (Address 0x0D)* or *Register LP\_SCAN\_RATE (Address 0x0F)*.
- Choose the button sampling window based on power consumption and noise requirements (recommended: 1 ms to 8 ms). While a longer button sampling window provides better noise performance, 1 ms is typically sufficient for most applications. Set  $SENCYC_n$  and LCDIV in Registers  $SENSOR_n\_CONFIG$  (Addresses *0x20, 0x22, 0x24, 0x26*) and *Register LC\_DIVIDER (Address 0x17)* in the following steps:
  - Calculate  $LCDIV = \text{ceiling}(\log_2(f_{SENSOR_n} \times t_{SAMPLE_n}) - 12)$ , where  $f_{SENSOR_n}$  is the sensor frequency in MHz,  $t_{SAMPLE_n}$  is the button sampling window in  $\mu s$ .
  - If  $LCDIV < 0$ , set it to 0.
  - Adjust  $SENCYC_n$  to get desired  $t_{SAMPLE_n}$  according to  $t_{SAMPLE_n} = 128 \times (SENCYC_n + 1) \times 2^{LCDIV} / f_{SENSOR_n}$ .

4. Calibrate gain in the appropriate Registers  $GAIN_n$  (Addresses  $0x0E$ ,  $0x10$ ,  $0x12$ ,  $0x14$ ). The gain setting can be used to tune the sensitivity of the touch button.  $GAIN_n$  is a 6-bit field with 64 different gain levels corresponding to normalized gains between 1 and 232. A good mechanical and sensor design typically requires a gain level of around 32 to 50, corresponding to relative gains of 16 to 76 (normalized to gain level of 0). Use the following sequence to determine the appropriate gain for each button:
  - Apply minimum desired force to the button.
  - Read initial  $DATA_n$  value after the button press. Note that the baseline tracking will affect this value.
  - Calculate gain factor required to increase  $DATA_n$  to the programmed threshold (default is 160).
  - Look up the [Gain Table](#) to find the required gain setting.
5. Enable special features to mitigate button interference if there is any, in Registers  $BTPAUSE\_MAXWIN$ ,  $TWIST$ ,  $COMMON\_DEFORM$  (Addresses  $0x16$ ,  $0x19$ ,  $0x1A$ ).

For more information on inductive touch system design, including mechanical design and sensor electrical design, refer to [Inductive Touch System Design Guide](#).

### 8.2.1.3 Application Curves

 8-16 shows a sequence of button presses of 150 grams force, two presses to Channel 0, then two presses to Channel 1. Each button press response is greater than the threshold.



 8-16. Conversion DATA vs Time for Channels 0 and 1

## 9 Power Supply Recommendations

The LDC3114 power supply should be bypassed with a 1- $\mu\text{F}$  and a 0.1- $\mu\text{F}$  pair of capacitors in parallel to ground. The capacitors should be placed as close to the LDC as possible. The smaller value 0.1- $\mu\text{F}$  capacitor should be placed closer to the VDD pin than the 1- $\mu\text{F}$  capacitor. The capacitors should be a low-ESL, low-ESR type.

Refer to [Recommended Operating Conditions](#) for more details.

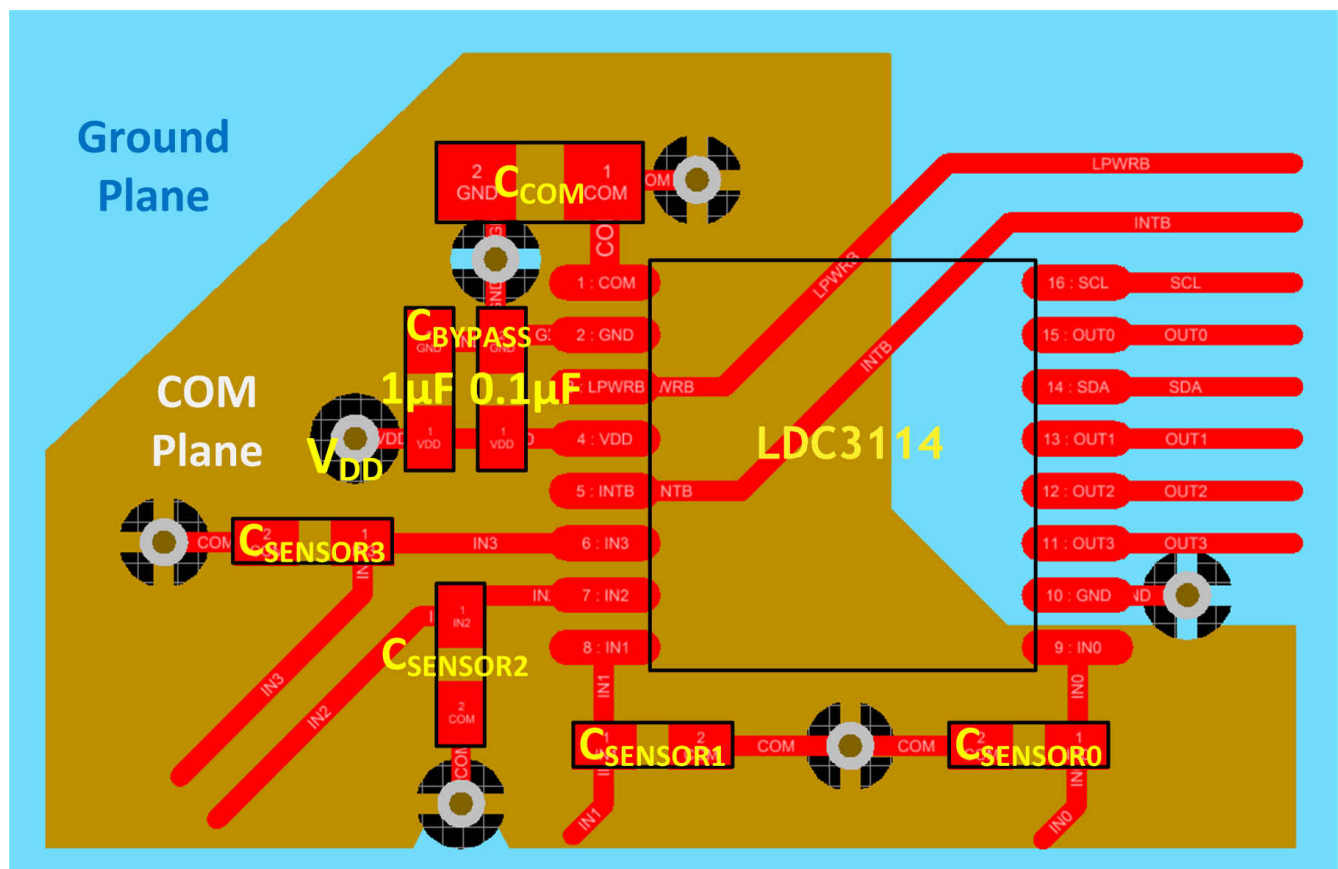
## 10 Layout

### 10.1 Layout Guidelines

The COM pin must be bypassed to ground with an appropriate value capacitor. For details of how to choose the capacitor value, refer to [Setting COM Pin Capacitor](#).  $C_{\text{COM}}$  should be placed as close as possible to the COM pin. The COM signal should be tied to a small copper fill placed underneath the  $\text{IN}_n$  signals. The  $\text{IN}_n$  signals should stay clear of other high frequency traces.

Each active channel needs to have an LC resonator connected to the corresponding  $\text{IN}_n$  pins. The sensor capacitor should be placed within 10 mm of the corresponding  $\text{IN}_n$  pin, and the inductor should be placed at the appropriate location next to (but not touching) the metal target. The  $\text{IN}_n$  traces should be at least 6 mil (0.15 mm) wide to minimize parasitic inductances.

### 10.2 Layout Example



10-1. Layout of LDC3114 (TSSOP-16) With Decoupling Capacitors and Sensor Capacitors

## 11 Device and Documentation Support

### 11.1 Documentation Support

#### 11.1.1 Related Documentation

For related documentation see the following:

- [LDC Calculations Tool](#)
- [Inductive Touch System Design Guide](#)

### 11.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](http://ti.com). Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 11.3 サポート・リソース

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### 11.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 11.6 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

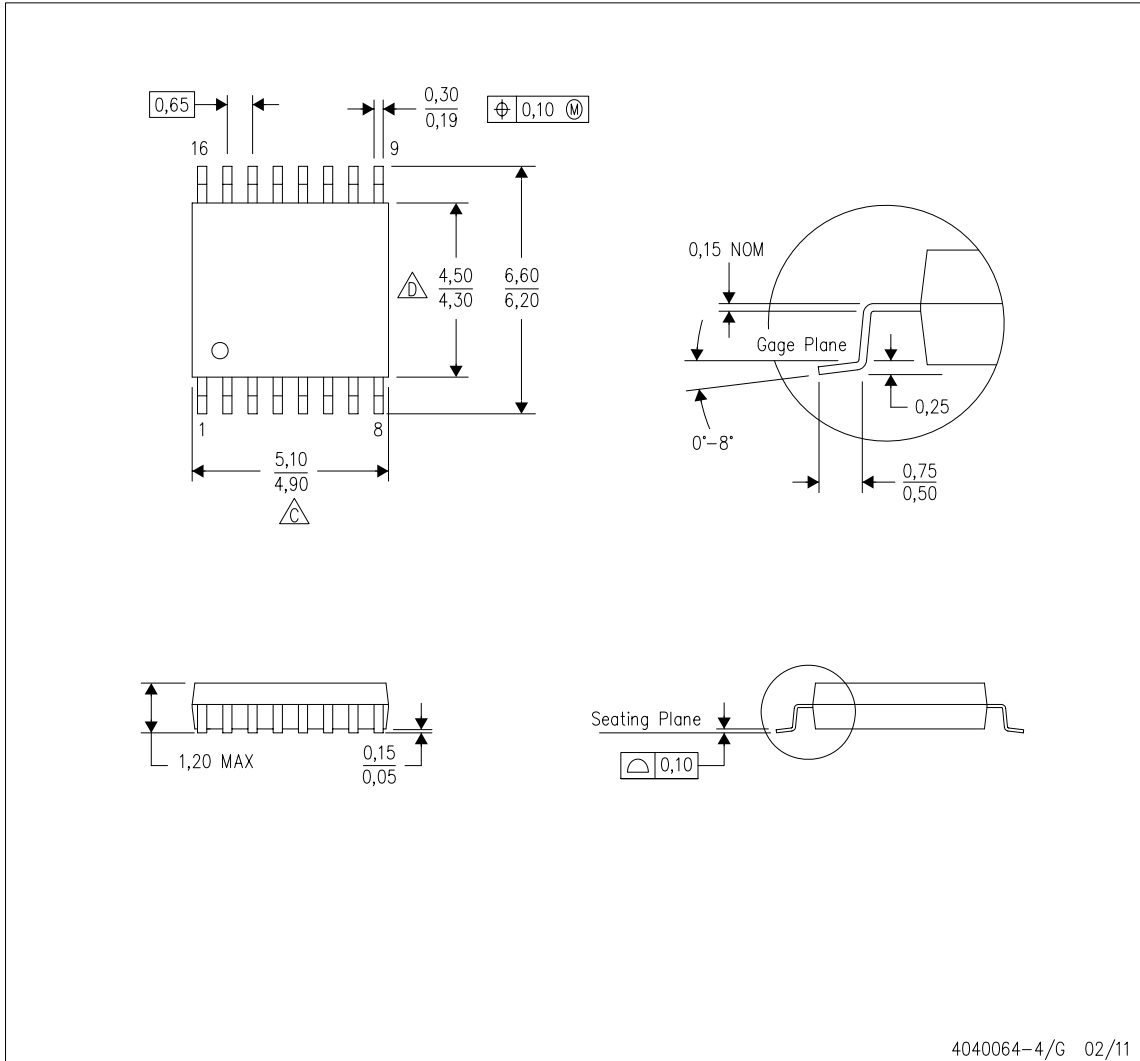
## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## MECHANICAL DATA

PW (R-PDSO-G16)

PLASTIC SMALL OUTLINE



- NOTES:
- All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
  - This drawing is subject to change without notice.
  - Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.
  - Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.
  - Falls within JEDEC MO-153

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**PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">LDC3114QPWR</a>	Active	Production	TSSOP (PW)   16	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	LDC3114
LDC3114QPWR.A	Active	Production	TSSOP (PW)   16	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	LDC3114

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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**OTHER QUALIFIED VERSIONS OF LDC3114 :**

- Automotive : [LDC3114-Q1](#)

**NOTE: Qualified Version Definitions:**

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects





# EXAMPLE BOARD LAYOUT

PW0016A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE: 10X



SOLDER MASK DETAILS

4220204/A 02/2017

NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

# EXAMPLE STENCIL DESIGN

PW0016A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE: 10X

4220204/A 02/2017

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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