



DS90LV028A 3V、LVDSデュアルCMOS差動入力ライン・レシーバ

1 特長

- 400Mbps (200MHz)を超えるスイッチング速度
- 差動スキュー: 50ps (標準値)
- チャネル間スキュー: 0.1ns (標準値)
- 最大伝搬遅延: 2.5ns
- 3.3V電源の設計
- フロースルーのピン配置
- パワーダウン時高インピーダンスのLVDS入力
- 低消費電力の設計(3.3V静的で18mW)
- 既存の5V LVDSネットワークと相互運用可能
- 小振幅(標準値350mV)差動信号レベルを許容
- 開放、短絡、終端の入力フェイルセーフに対応
- ANSI/TIA/EIA-644規格に準拠
- 工業用温度範囲: -40°C~85°C
- SOICおよび省スペースのWSOONパッケージで供給

2 アプリケーション

- 多機能プリンタ
- LVDS-LVCMOS間の変換
- ビル・オートメーションとファクトリ・オートメーション
- グリッド・インフラストラクチャ

3 概要

DS90LV028AはデュアルCMOS差動ライン・レシーバで、超低消費電力、低ノイズ、高いデータ速度を必要とするアプリケーション用に設計されています。このデバイスは、低電圧差動信号(LVDS)テクノロジーを活用し、400Mbps (200MHz)を超えるデータ速度をサポートするように設計されています。

DS90LV028Aは低電圧(標準値350mV)の差動入力信号を受信し、3V CMOS出力レベルへ変換します。また、レシーバは開放、短絡、終端(100Ω)の入力フェイルセーフもサポートします。すべてのフェイルセーフ条件において、レシーバの出力はHIGHになります。DS90LV028Aにはフロースルー設計が採用されているため、PCBレイアウトが容易です。

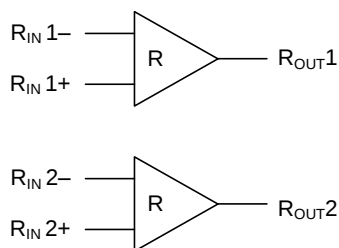
DS90LV028Aと、対になるLVDSライン・ドライバは、消費電力の大きいPECL/ECLデバイスの代替として、高速のポイント・ツー・ポイント・インターフェイス・アプリケーションに使用できます。

製品情報⁽¹⁾

型番	パッケージ	本体サイズ(公称)
DS90LV028A	SOIC (8)	4.90mm×3.91mm
	WSOON (8)	4.00mm×4.00mm

(1) 提供されているすべてのパッケージについては、巻末の注文情報を参照してください。

機能図



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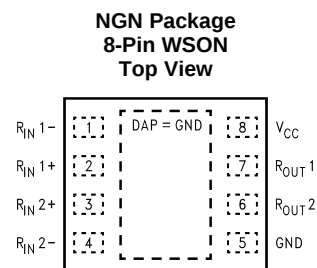
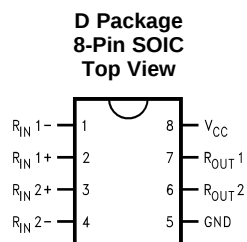
4 改訂履歴

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Revision E (April 2013) から Revision F に変更	Page
• 「ESD 定格」の表、「機能説明」セクション、「デバイスの機能モード」セクション、「アプリケーションと実装」セクション、「電源に関する推奨事項」セクション、「レイアウト」セクション、「デバイスおよびドキュメントのサポート」セクション、「メカニカル、パッケージ、および注文情報」セクションを追加	1
• Added Thermal Information values	4

Revision D (April 2013) から Revision E に変更	Page
• ナショナル・セミコンダクターのデータシートのレイアウトをTIフォーマットへ 変更	1

5 Pin Configuration and Functions



Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
GND	5	—	Ground pin
R _{IN} ⁺	2, 3	I	Noninverting receiver input pin
R _{IN} [−]	1, 4	I	Inverting receiver input pin
R _{OUT}	6, 7	O	Receiver output pin
V _{CC}	8	—	Power supply pin, 3.3 V ±0.3 V

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
Supply voltage, V_{CC}		–0.3	4	V
Input voltage, R_{IN+} , R_{IN-}		–0.3	3.9	V
Output voltage, R_{OUT}		–0.3	$V_{CC} + 0.3$	V
Maximum package power dissipation at 25°C	D package		1025	mW
	Derate D package		8.2 mW/°C above 25°C	°C
	NGN package		3.3	W
	Derate NGN package		25.6 mW/°C above 25°C	°C
Lead temperature range, soldering (4 s)			260	°C
Junction temperature, T_J			150	°C
Storage temperature, T_{stg}		–65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

		VALUE	UNIT
$V_{(ESD)}$ Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±7000	V
	Machine model (MM) ⁽²⁾	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

- (2) EIAJ, 0 Ω , 200 pF

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V_{CC}	Supply voltage	3	3.3	3.6	V
	Receiver input voltage	GND		3	V
T_A	Operating free-air temperature	–40	25	85	°C

6.4 Thermal Information

THERMAL METRIC ⁽¹⁾			DS90LV028A		UNIT
			D (SOIC)	NGN (WSON)	
			8 PINS	8 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance		—	35.9	°C/W
	Low-K thermal resistance		212	—	
	High-K thermal resistance		122	—	
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance		69.1	24.2	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance		47.7	13.2	°C/W
Ψ_{JT}	Junction-to-top characterization parameter		15.2	0.2	°C/W
Ψ_{JB}	Junction-to-board characterization parameter		47.2	13.3	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance		—	2.9	°C/W

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

6.5 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

PARAMETER		TEST CONDITIONS		MIN	TYP ⁽²⁾	MAX	UNIT
V _{TH}	Differential input high threshold	V _{CM} = 1.2 V, 0 V, 3 V, R _{IN} ⁺ , R _{IN} [−] pins ⁽³⁾				100	mV
V _{TL}	Differential input low threshold	V _{CM} = 1.2 V, 0 V, 3 V, R _{IN} ⁺ , R _{IN} [−] pins ⁽³⁾		−100			mV
I _{IN}	Input current	V _{CC} = 3.6 V or 0 V, R _{IN} ⁺ , R _{IN} [−] pins	V _{IN} = 2.8 V	−10	±1	10	μA
			V _{IN} = 0 V	−10	±1	10	
		V _{CC} = 0 V, V _{IN} = 3.6 V, R _{IN} ⁺ , R _{IN} [−] pins		−20		20	
V _{OH}	Output high voltage	I _{OH} = −0.4 mA, V _{ID} = 200 mV, R _{OUT} pin		2.7	3.1		V
		I _{OH} = −0.4 mA, inputs terminated, R _{OUT} pin		2.7	3.1		
		I _{OH} = −0.4 mA, inputs shorted, R _{OUT} pin		2.7	3.1		
V _{OL}	Output low voltage	I _{OL} = 2 mA, V _{ID} = −200 mV, R _{OUT} pin			0.3	0.5	V
I _{OS}	Output short-circuit current	V _{OUT} = 0 V, R _{OUT} pin ⁽⁴⁾		−15	−50	−100	mA
V _{CL}	Input clamp voltage	I _{CL} = −18 mA, R _{OUT} pin		−1.5	−0.8		V
I _{CC}	No load supply current	V _{CC} pin, inputs open			5.4	9	mA

- (1) Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground unless otherwise specified (such as V_{ID}).
- (2) All typicals are given for: V_{CC} = 3.3 V and T_A = 25°C.
- (3) V_{CC} is always higher than R_{IN+} and R_{IN-} voltage. R_{IN+} and R_{IN-} are allowed to have voltage range -0.05 V to 3.05 V. V_{ID} is not allowed to be greater than 100 mV when V_{CM} = 0 V or 3 V.
- (4) Output short circuit current (I_{OS}) is specified as magnitude only, minus sign indicates direction only. Only one output must be shorted at a time, do not exceed maximum junction temperature specification.

6.6 Switching Characteristics

V_{CC} = 3.3 V ±10%, and T_A = -40°C to 85°C (unless otherwise noted)⁽¹⁾⁽²⁾

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
t _{PHLD}	Differential propagation delay high to low	C _L = 15 pF	1	1.6	2.5	ns
t _{PLHD}	Differential propagation delay low to high	V _{ID} = 200 mV	1	1.7	2.5	ns
t _{SKD1}	Differential pulse skew t _{PHLD} - t _{PLHD} ⁽³⁾	See Figure 18 and Figure 19	0	50	400	ps
t _{SKD2}	Differential channel-to-channel skew-same device ⁽⁴⁾		0	0.1	0.5	ns
t _{SKD3}	Differential part to part skew ⁽⁵⁾		0		1	ns
t _{SKD4}	Differential part to part skew ⁽⁶⁾		0		1.5	ns
t _{TLH}	Rise Time			325	800	ps
t _{THL}	Fall Time			225	800	ps
f _{MAX}	Maximum operating frequency ⁽⁷⁾		200	250		MHz

- (1) C_L includes probe and jig capacitance.
- (2) Generator waveform for all tests unless otherwise specified: f = 1 MHz, Z_O = 50 Ω, t_r and t_f (0% to 100%) ≤ 3 ns for R_{IN-}.
- (3) t_{SKD1} is the magnitude difference in differential propagation delay time between the positive-going-edge and the negative-going-edge of the same channel.
- (4) t_{SKD2} is the differential channel-to-channel skew of any event on the same device. This specification applies to devices having multiple receivers within the integrated circuit.
- (5) t_{SKD3}, part to part skew, is the differential channel-to-channel skew of any event between devices. This specification applies to devices at the same V_{CC} and within 5°C of each other within the operating temperature range.
- (6) t_{SKD4}, part to part skew, is the differential channel-to-channel skew of any event between devices. This specification applies to devices over the recommended operating temperature and voltage ranges, and across process distribution. t_{SKD4} is defined as |Maximum - Minimum| differential propagation delay.
- (7) f_{MAX} generator input conditions: t_r = t_f < 1 ns (0% to 100%), 50% duty cycle, differential (1.05V to 1.35 peak to peak). Output criteria: 60%/40% duty cycle, V_{OL} (max 0.4V), V_{OH} (min 2.7V), load = 15 pF (stray plus probes).

6.7 Typical Characteristics

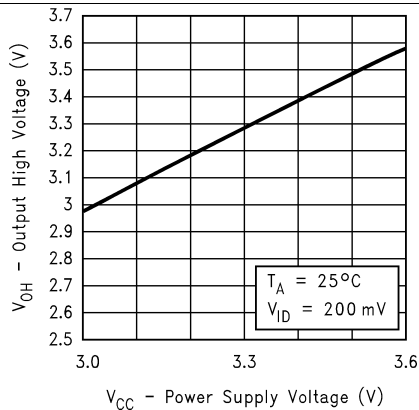


Figure 1. Output High Voltage vs Power Supply Voltage

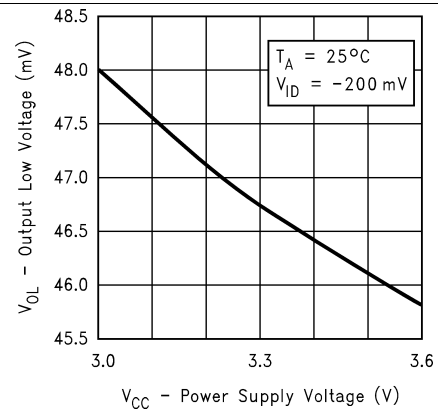


Figure 2. Output Low Voltage vs Power Supply Voltage

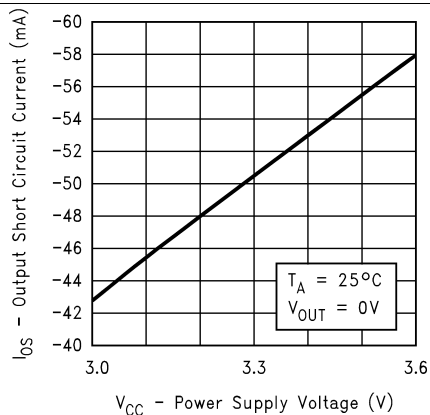


Figure 3. Output Short Circuit Current vs Power Supply Voltage

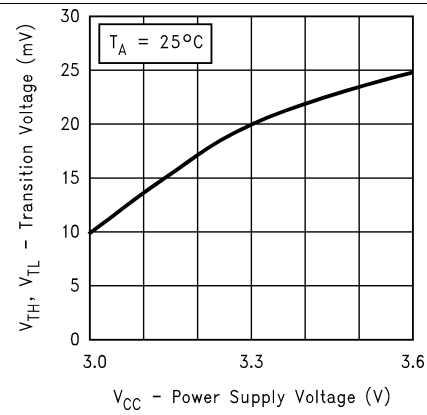


Figure 4. Differential Transition Voltage vs Power Supply Voltage

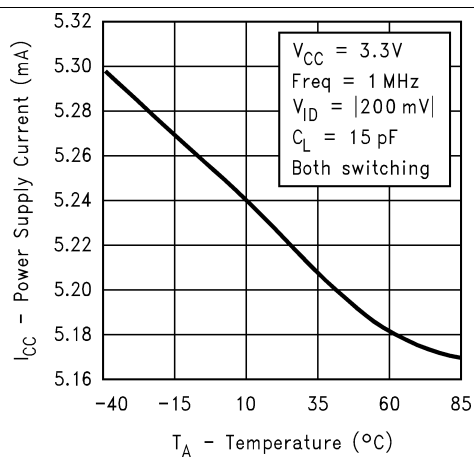


Figure 5. Power Supply Current vs Ambient Temperature

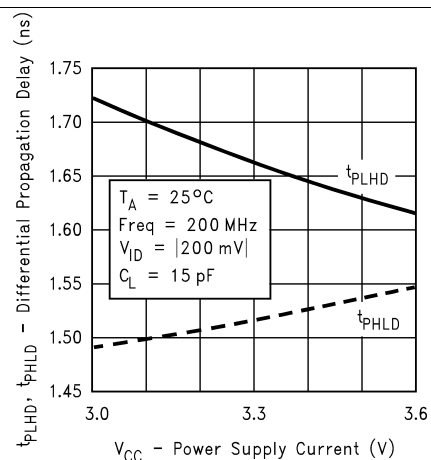


Figure 6. Differential Propagation Delay vs Power Supply Voltage

Typical Characteristics (continued)

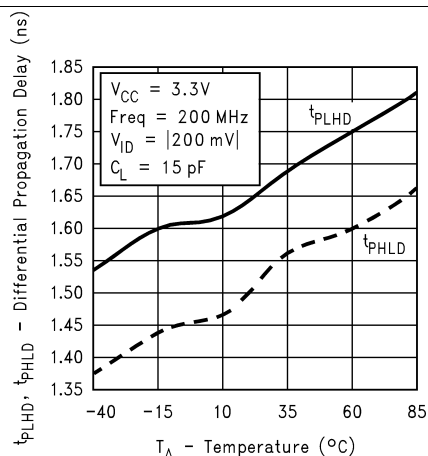


Figure 7. Differential Propagation Delay vs Ambient Temperature

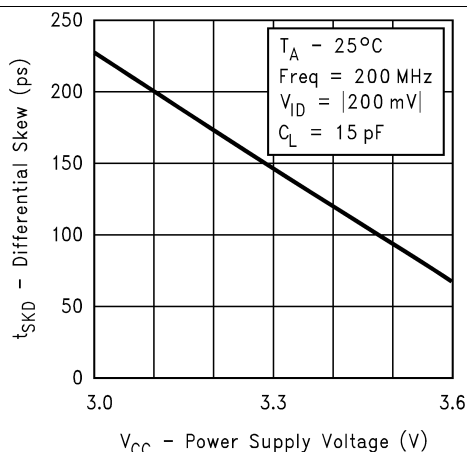


Figure 8. Differential Skew vs Power Supply Voltage

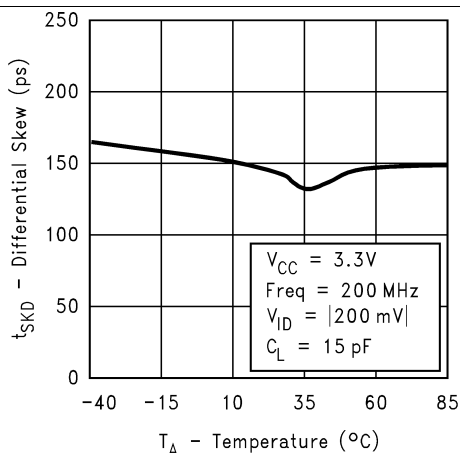


Figure 9. Differential Skew vs Ambient Temperature

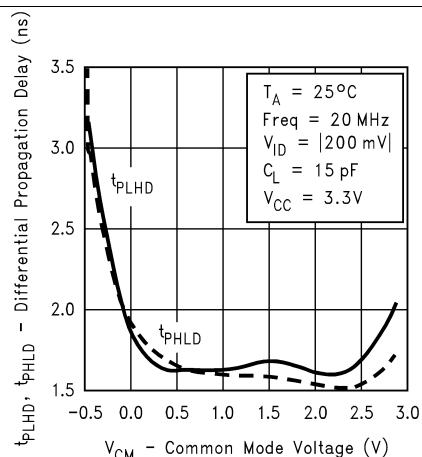


Figure 10. Differential Propagation Delay vs Common Mode Voltage

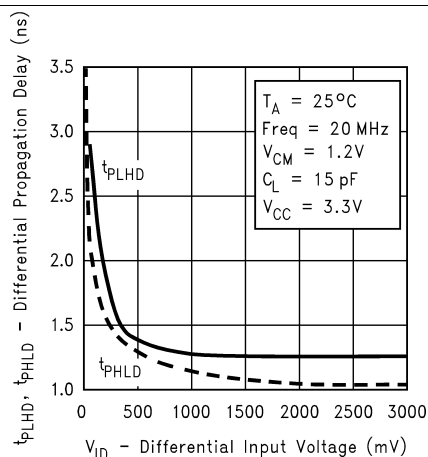


Figure 11. Differential Propagation Delay vs Differential Input Voltage

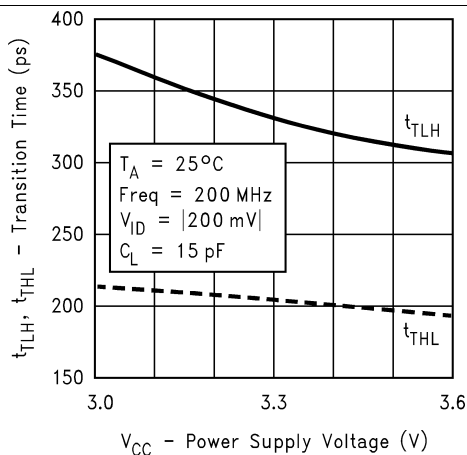
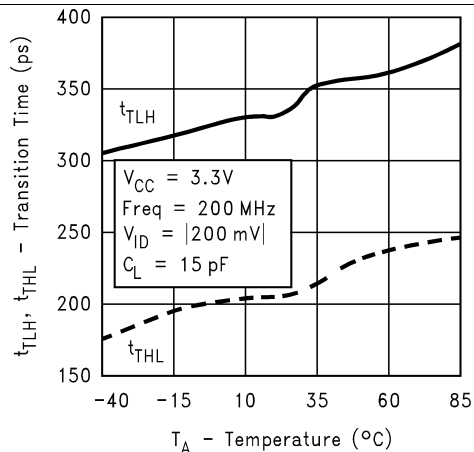
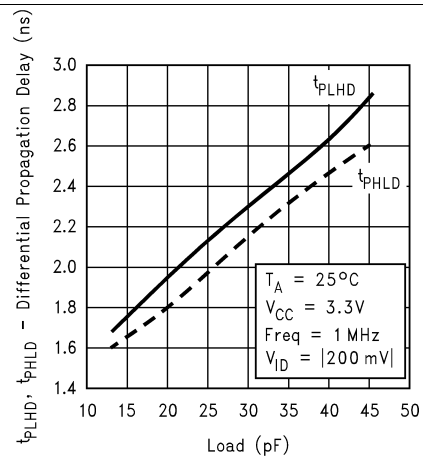
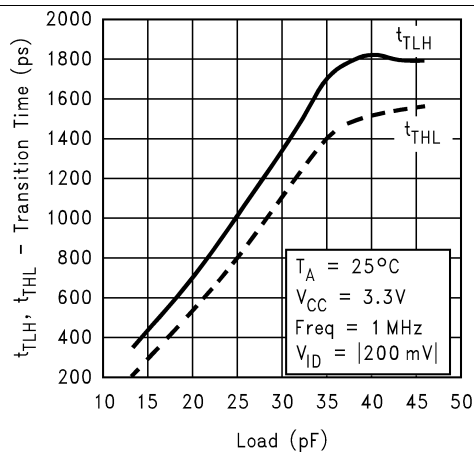
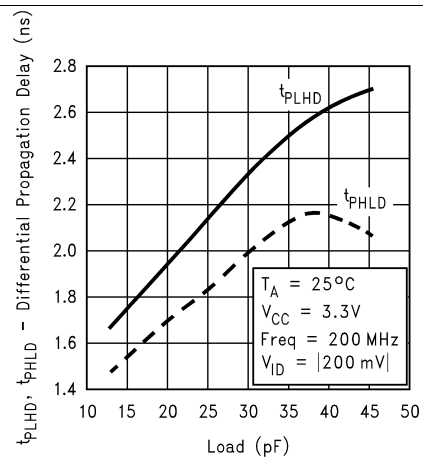
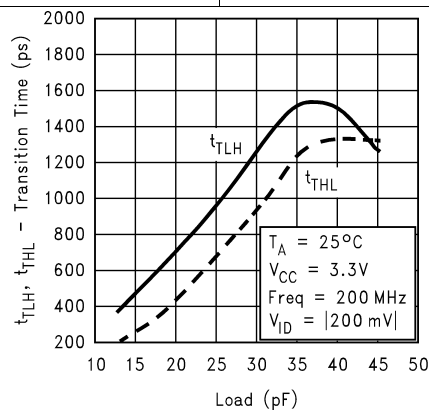


Figure 12. Transition Time vs Power Supply Voltage

Typical Characteristics (continued)

Figure 13. Transition Time vs Ambient Temperature

Figure 14. Differential Propagation Delay vs Load

Figure 15. Transition Time vs Load

Figure 16. Differential Propagation Delay vs Load

Figure 17. Transition Time vs Load

7 Parameter Measurement Information

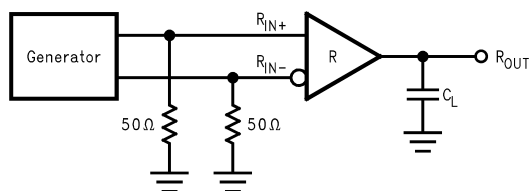


Figure 18. Receiver Propagation Delay and Transition Time Test Circuit

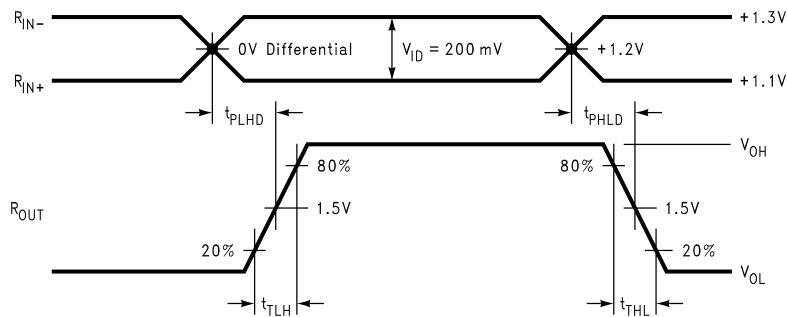


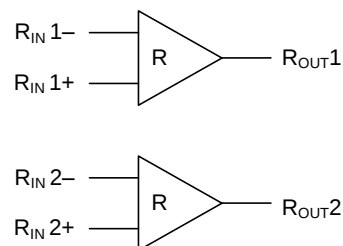
Figure 19. Receiver Propagation Delay and Transition Time Waveforms

8 Detailed Description

8.1 Overview

LVDS drivers and receivers are intended to be primarily used in an uncomplicated point-to-point configuration as is shown in [Figure 20](#). This configuration provides a clean signaling environment for the fast edge rates of the drivers. The receiver is connected to the driver through a balanced media which may be a standard twisted pair cable, a parallel pair cable, or simply PCB traces. Typically, the characteristic impedance of the media is in the range of 100 Ω . A termination resistor of 100 Ω (selected to match the media), and is placed as close to the receiver input pins as possible. The termination resistor converts the driver output (current mode) into a voltage that is detected by the receiver. Other configurations are possible such as a multi-receiver configuration, but the effects of a mid-stream connector(s), cable stub(s), and other impedance discontinuities as well as ground shifting, noise margin limits, and total termination loading must be considered.

8.2 Functional Block Diagram



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8.3 Feature Description

The DS90LV028A differential line receiver is capable of detecting signals as low as 100 mV, over a ± 1 -V common mode range centered around 1.2 V. This is related to the driver offset voltage which is typically 1.2 V. The driven signal is centered around this voltage and may shift ± 1 V around this center point. The ± 1 -V shifting may be the result of a ground potential difference between the driver's ground reference and the receiver's ground reference, the common mode effects of coupled noise, or a combination of the two. The AC parameters of both receiver input pins are optimized for a recommended operating input voltage range of 0 V to 2.4 V (measured from each pin to ground). The device operates for receiver input voltages up to V_{CC} , but exceeding V_{CC} turns on the ESD protection circuitry which clamps the bus voltages.

Feature Description (continued)

8.3.1 Fail-Safe Feature

The LVDS receiver is a high gain, high speed device that amplifies a small differential signal (20 mV) to CMOS logic levels. Due to the high gain and tight threshold of the receiver, take care to prevent noise from appearing as a valid signal.

The internal fail-safe circuitry of the receiver is designed to source or sink a small amount of current, providing fail-safe protection (a stable known state of HIGH output voltage) for floating, terminated or shorted receiver inputs.

1. **Open Input Pins:** The DS90LV028A is a dual receiver device, and if an application requires only 1 receiver, the unused channel inputs must be left OPEN. Do not tie unused receiver inputs to ground or any other voltages. The input is biased by internal high value pull up and pull down resistors to set the output to a HIGH state. This internal circuitry ensures a HIGH, stable output state for open inputs.
2. **Terminated Input:** If the driver is disconnected (cable unplugged), or if the driver is in a power-off condition, the receiver output is again in a HIGH state, even with the end of cable 100Ω termination resistor across the input pins. The unplugged cable can become a floating antenna which can pick up noise. If the cable picks up more than 10 mV of differential noise, the receiver may see the noise as a valid signal and switch. To insure that any noise is seen as common mode and not differential, a balanced interconnect must be used. Twisted pair cable offers better balance than flat ribbon cable.
3. **Shorted Inputs:** If a fault condition occurs that shorts the receiver inputs together, thus resulting in a 0 V differential input voltage, the receiver output remains in a HIGH state. Shorted input fail-safe is not supported across the common mode range of the device (GND to 2.4 V). It is only supported with inputs shorted and no external common mode voltage applied.

External lower value pull up and pull down resistors (for a stronger bias) may be used to boost fail-safe in the presence of higher noise levels. The pull up and pull down resistors must be in the 5-kΩ to 15-kΩ range to minimize loading and waveform distortion to the driver. The common mode bias point must be set to approximately 1.2 V (less than 1.75 V) to be compatible with the internal circuitry. Refer to [AN-1194 Failsafe Biasing of LVDS Interfaces](#) (SNLA051) for more information.

8.3.2 Cables and Connectors

When choosing cable and connectors for LVDS it is important to remember:

Use controlled impedance media. The cables and connectors you use must have a matched differential impedance of about 100 Ω. They must not introduce major impedance discontinuities.

Balanced cables (for example, twisted pair) are usually better than unbalanced cables (ribbon cable, simple coax) for noise reduction and signal quality. Balanced cables tend to generate less EMI due to field canceling effects and also tend to pick up electromagnetic radiation a common mode (not differential mode) noise which is rejected by the receiver.

For cable distances < 0.5 M, most cables can be made to work effectively. For distances 0.5 M ≤ d ≤ 10 M, CAT 3 (category 3) twisted pair cable works well, is readily available, and relatively inexpensive.

8.4 Device Functional Modes

[Table 1](#) lists the functional modes of the DS90LV028A.

Table 1. Truth Table

INPUTS	OUTPUT
$[R_{IN+}] - [R_{IN-}]$	R_{OUT}
$V_{ID} \geq 0.1 \text{ V}$	H
$V_{ID} \leq -0.1 \text{ V}$	L
Full fail-safe OPEN/SHORT or Terminated	H

9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The DS90LV028A has a flow-through pinout that allows for easy PCB layout. The LVDS signals on one side of the device easily allows for matching electrical lengths of the differential pair trace lines between the driver and the receiver as well as allowing the trace lines to be close together to couple noise as common mode. Noise isolation is achieved with the LVDS signals on one side of the device and the TTL signals on the other side.

9.2 Typical Application

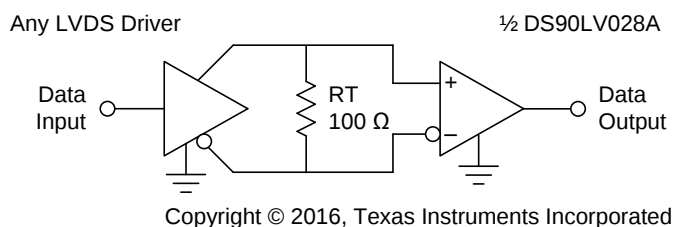


Figure 20. Point-to-Point Application

9.2.1 Design Requirements

When using LVDS devices, it is important to remember to specify controlled impedance PCB traces, cable assemblies, and connectors. All components of the transmission media must have a matched differential impedance of about 100 Ω. They must not introduce major impedance discontinuities.

Balanced cables (for example, twisted pair) are usually better than unbalanced cables (ribbon cable) for noise reduction and signal quality. Balanced cables tend to generate less EMI due to field canceling effects and also tend to pick up electromagnetic radiation as common mode (not differential mode) noise which is rejected by the LVDS receiver.

For cable distances < 0.5 M, most cables can be made to work effectively. For distances $0.5 \text{ M} \leq d \leq 10 \text{ M}$, CAT5 (Category 5) twisted pair cable works well, is readily available, and relatively inexpensive.

9.2.2 Detailed Design Procedure

9.2.2.1 Probing LVDS Transmission Lines

Always use high impedance ($>100 \text{ k}\Omega$), low capacitance ($<2 \text{ pF}$) scope probes with a wide bandwidth (1 GHz) scope. Improper probing gives deceiving results.

9.2.2.2 Threshold

The LVDS Standard (ANSI/TIA/EIA-644) specifies a maximum threshold of $\pm 100 \text{ mV}$ for the LVDS receiver. The DS90LV028A supports an enhanced threshold region of -100 mV to 0 V . This is useful for fail-safe biasing. The threshold region is shown in the Voltage Transfer Curve (VTC) in [Figure 21](#). The typical DS90LV028A LVDS receiver switches at about -35 mV .

NOTE

With $V_{ID} = 0 \text{ V}$, the output is in a HIGH state. With an external fail-safe bias of 25 mV applied, the typical differential noise margin is now the difference from the switch point to the bias point.

Typical Application (continued)

In the following example, this would be 60 mV of Differential Noise Margin (25 mV – (–35 mV)). With the enhanced threshold region of –100 mV to 0 V, this small external fail-safe biasing of 25 mV (with respect to 0 V) gives a DNM of a comfortable 60 mV. With the standard threshold region of ± 100 mV, the external fail-safe biasing would require 25 mV with respect to 100 mV or 125 mV, giving a DNM of 160 mV which is stronger fail-safe biasing than is necessary for the DS90LV028A. If more differential noise margin (DNM) is required, then a stronger fail-safe bias point can be set by changing resistor values.

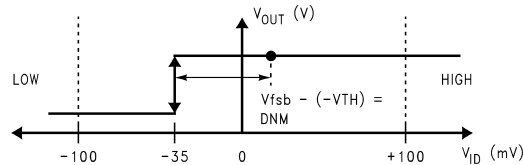


Figure 21. VTC of the DS90LV028A

9.2.3 Application Curve

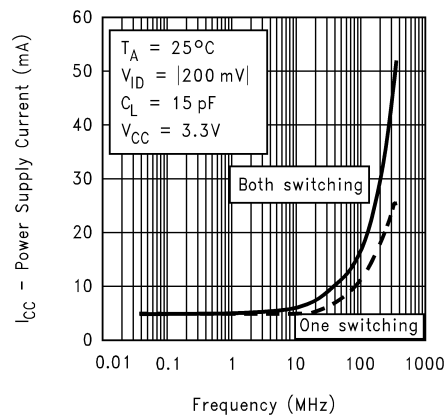


Figure 22. Power Supply Current vs Frequency

10 Power Supply Recommendations

Bypass capacitors must be used on power pins. TI recommends using high-frequency, ceramic, 0.1- μ F and 0.01- μ F capacitors in parallel at the power supply pin with the smallest value capacitor closest to the device supply pin. Additional scattered capacitors over the printed-circuit board improves decoupling. Multiple vias must be used to connect the decoupling capacitors to the power planes. A 10- μ F, 35-V (or greater) solid tantalum capacitor must be connected at the power entry point on the printed-circuit board between the supply and ground.

11 Layout

11.1 Layout Guidelines

Use at least 4 PCB board layers (top to bottom): LVDS signals, ground, power, and TTL signals.

Isolate TTL signals from LVDS signals, otherwise the TTL signals may couple onto the LVDS lines. Best practice places TTL and LVDS on different layers which are isolated by a power or ground plane(s).

Keep drivers and receivers as close to the (LVDS port side) connectors as possible.

For PC board considerations for the WSON package, please refer to [AN-1187, Leadless Leadframe Package \(SNOA401\)](#). It is important to note that to optimize signal integrity (minimize jitter and noise coupling), the WSON thermal land pad, which is a metal (normally copper) rectangular region placed under the package as seen in [Figure 23](#), must be attached to ground and match the dimensions of the exposed pad on the PCB (1:1 ratio).

11.1.1 Differential Traces

Use controlled impedance traces which match the differential impedance of your transmission medium (that is, cable) and termination resistor. Run the differential pair trace lines as close together as possible as soon as they leave the IC (stubs must be <10 mm long). This helps eliminate reflections and ensure noise is coupled as common mode. In fact, we have seen that differential signals which are 1mm apart radiate far less noise than traces 3 mm apart because magnetic field cancellation is much better with the closer traces. In addition, noise induced on the differential lines is much more likely to appear as common mode which is rejected by the receiver.

Match electrical lengths between traces to reduce skew. Skew between the signals of a pair means a phase difference between signals which destroys the magnetic field cancellation benefits of differential signals and the EMI result. The velocity of propagation, $v = c/E$, where c (the speed of light) = 0.2997 mm/ps or 0.0118 in/ps. Do not rely solely on the autoroute function for differential traces. Carefully review dimensions to match differential impedance and provide isolation for the differential lines. Minimize the number of vias and other discontinuities on the line.

Avoid 90° turns (these cause impedance discontinuities). Use arcs or 45° bevels.

Within a pair of traces, the distance between the two traces must be minimized to maintain common mode rejection of the receivers. On the printed-circuit board, this distance must remain constant to avoid discontinuities in differential impedance. Minor violations at connection points are allowable.

11.1.2 Termination

Use a termination resistor which best matches the differential impedance or your transmission line. The resistor must be between 90 Ω and 130 Ω . Remember that the current mode outputs require the termination resistor to generate the differential voltage. LVDS does not work correctly without resistor termination. Typically, connecting a single resistor across the pair at the receiver end will suffice.

Surface mount 1% to 2% resistors are the best. PCB stubs, component lead, and the distance from the termination to the receiver inputs must be minimized. The distance between the termination resistor and the receiver must be <10 mm (12 mm maximum).

11.2 Layout Examples

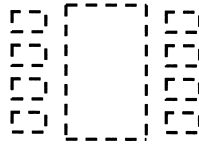


Figure 23. WSON Thermal Land Pad and Pin Pads

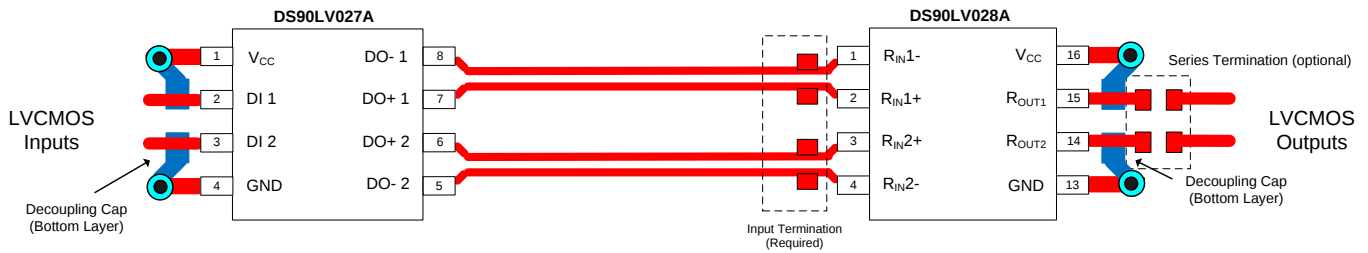


Figure 24. Simplified DS90LV027A and DS90LV028A Layout

12 デバイスおよびドキュメントのサポート

12.1 ドキュメントのサポート

12.1.1 関連資料

関連資料については、以下を参照してください。

- 『LVDSオーナー・マニュアル』(SNLA187)
- 『AN-808、長い伝送ラインとデータ信号の品質』(SNLA028)
- 『AN-977、LVDS信号の品質: アイ・パターンのテスト・レポートを使用するジッタ測定』(SNLA166)
- 『AN-971、LVDSテクノロジーの概要』(SNLA165)
- 『AN-916、ケーブル選択の実践的ガイド』(SNLA219)
- 『AN-805、差動ライン・ドライバの消費電力の計算』(SNOA233)
- 『AN-903、差動終端技法の比較』(SNLA034)
- 『AN-1194、LVDSインターフェイスのフェイルセーフ・バイアス法』(SNLA051)
- 『AN-1187、リードレス・リードフレーム・パッケージ』(SNOA401)

12.2 ドキュメントの更新通知を受け取る方法

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12.3 コミュニティ・リソース

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

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Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

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12.6 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 メカニカル、パッケージ、および注文情報

以降のページには、メカニカル、パッケージ、および注文に関する情報が記載されています。これらの情報は、指定のデバイスに対して提供されている最新のデータです。このデータは予告なく変更されることがあり、ドキュメントが改訂される場合もあります。本データシートのブラウザ版を使用されている場合は、画面左側の説明をご覧ください。

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
DS90LV028ATLD/NOPB	Active	Production	WSON (NGN) 8	1000 SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 85	LV028AT
DS90LV028ATLD/NOPB.B	Active	Production	WSON (NGN) 8	1000 SMALL T&R	Yes	SN	Level-3-260C-168 HR	-40 to 85	LV028AT
DS90LV028ATM/NOPB	Active	Production	SOIC (D) 8	95 TUBE	Yes	SN	Level-1-260C-UNLIM	-40 to 85	90LV0 28ATM
DS90LV028ATM/NOPB.B	Active	Production	SOIC (D) 8	95 TUBE	Yes	SN	Level-1-260C-UNLIM	-40 to 85	90LV0 28ATM
DS90LV028ATMX/NOPB	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 85	90LV0 28ATM
DS90LV028ATMX/NOPB.B	Active	Production	SOIC (D) 8	2500 LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 85	90LV0 28ATM

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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OTHER QUALIFIED VERSIONS OF DS90LV028A :

- Automotive : [DS90LV028A-Q1](#)

NOTE: Qualified Version Definitions:

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DS90LV028ATLD/NOPB	WSOIC	NGN	8	1000	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
DS90LV028ATMX/NOPB	SOIC	D	8	2500	330.0	12.4	6.5	5.4	2.0	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

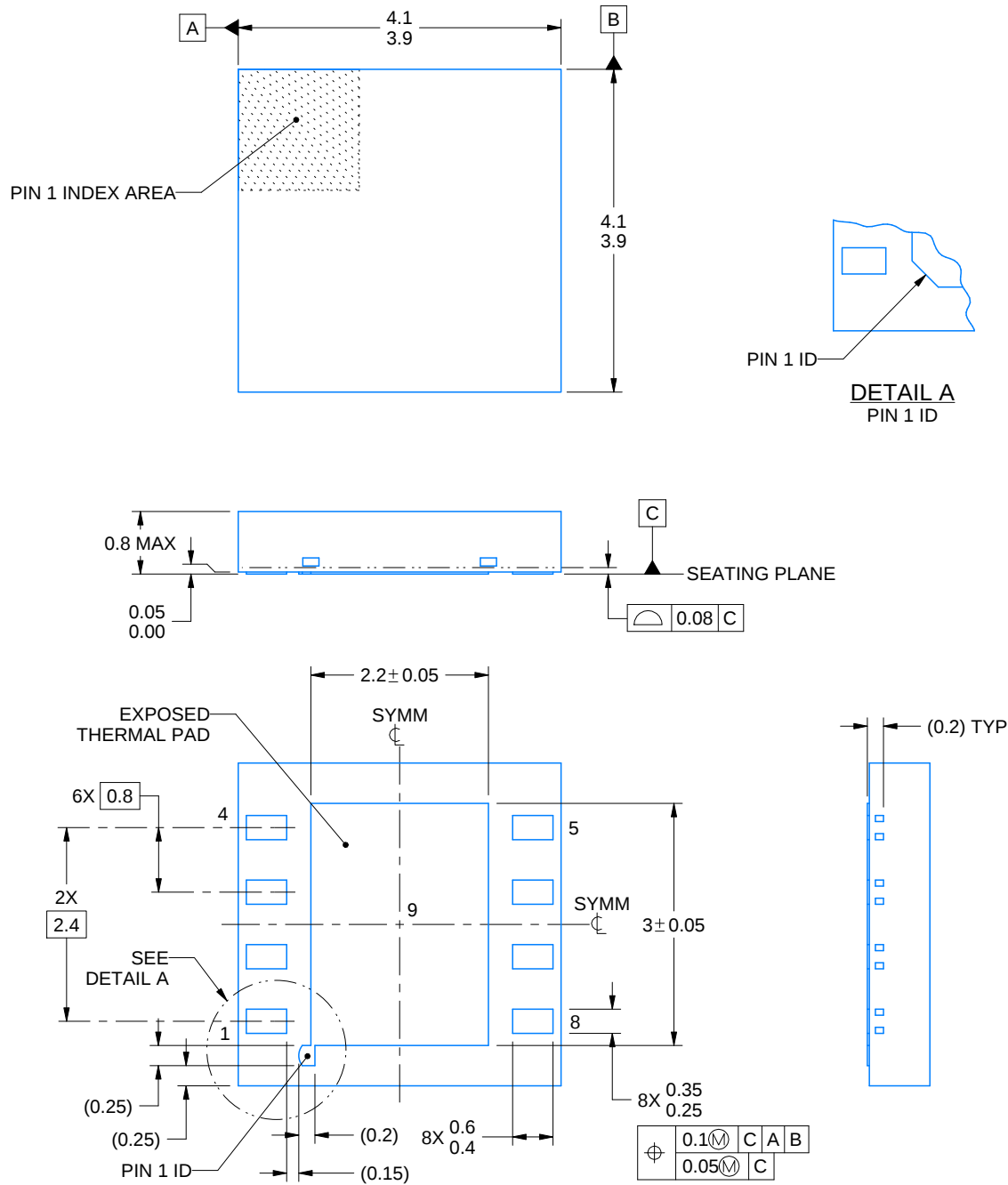
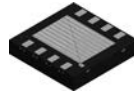
Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DS90LV028ATLD/NOPB	WSO	NGN	8	1000	208.0	191.0	35.0
DS90LV028ATMX/NOPB	SOIC	D	8	2500	367.0	367.0	35.0

TUBE



*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
DS90LV028ATM/NOPB	D	SOIC	8	95	495	8	4064	3.05
DS90LV028ATM/NOPB.B	D	SOIC	8	95	495	8	4064	3.05



4214794/A 11/2019

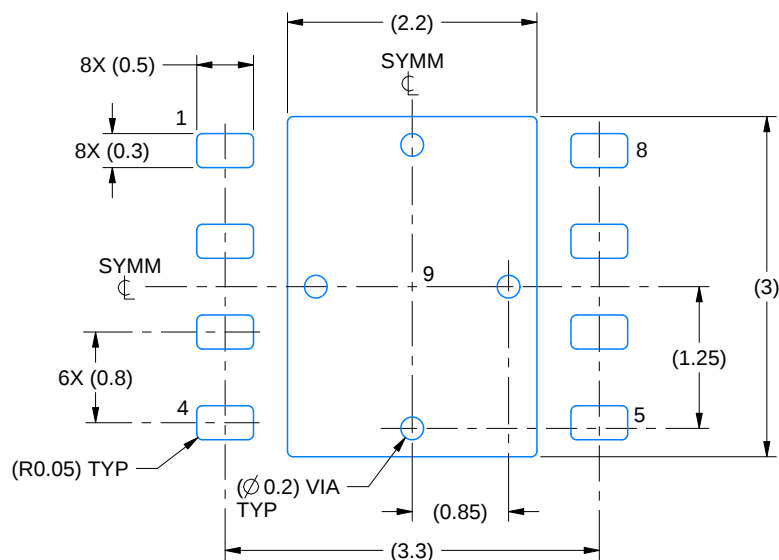
NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

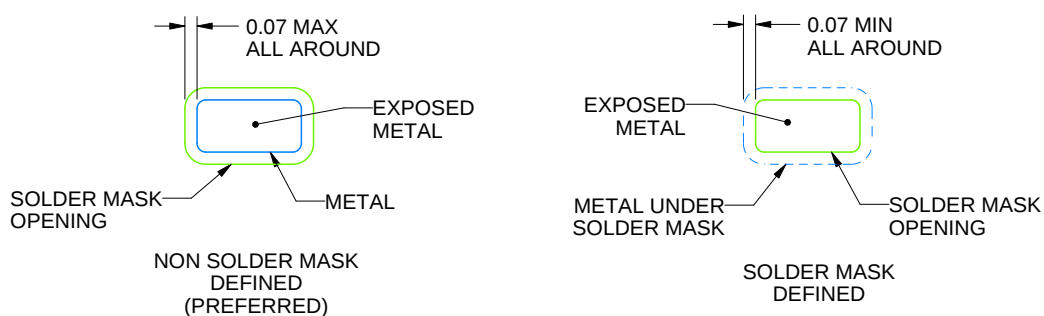
NGN0008A

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:15X



SOLDER MASK DETAILS

4214794/A 11/2019

NOTES: (continued)

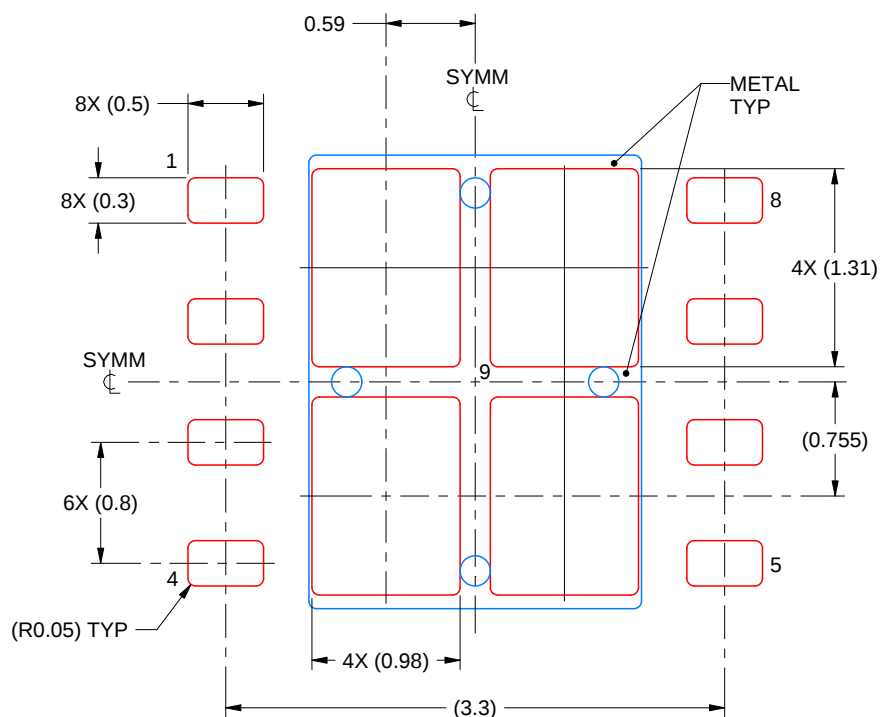
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

EXAMPLE STENCIL DESIGN

NGN0008A

WSN - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 9:
78% PRINTED SOLDER COVERAGE BY AREA UNDER PACKAGE
SCALE:20X

4214794/A 11/2019

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



PACKAGE OUTLINE

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:8X



SOLDER MASK DETAILS

4214825/C 02/2019

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE
BASED ON .005 INCH [0.125 MM] THICK STENCIL
SCALE:8X

4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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