

BQ25150 I²C 制御 1 セル 500mA リニア・チャージャ、10nA シップ・モード、高度なパワー・パス管理および制御、ADC、LDO 付き

1 特長

- 1.25mA～500mA の高速充電電流範囲に対応したリニア・バッテリー充電器
 - 0.5% 精度の I²C プログラム可能なバッテリー・レギュレーション電圧 (3.6V～4.6V の範囲で 10mV 刻み)
 - 終了電流を最小 0.5mA に設定可能
 - 入力耐圧 20V で、標準的な入力電圧動作範囲は 3.4V～5.5V
 - 熱充電プロファイルをプログラム可能、ホット、ウォーム、クール、コールドの各スレッショルドを設定可能
- システム電源およびバッテリー充電用のパワー・パスの管理
 - 動的なパワー・パス管理により、弱いアダプタからの充電を最適化
 - 高度な I²C 制御により、ホストは必要に応じてバッテリーまたはアダプタを切り離し可能
- I²C により負荷スイッチまたは最大 150mA の LDO 出力を設定可能
 - 0.6V～3.7V の範囲で 100mV 刻みでプログラム可能
- 非常に低い I_{ddq} によりバッテリー駆動時間を延長
 - シップ・モードのバッテリー I_q: 10nA
 - システム駆動時 (PMID および VDD がオン) の I_q: 400nA
- 押しボタン 1 つによる可変タイマ付きウェイクアップおよびリセット入力
 - システム電源サイクルおよび HW リセットをサポート
- 16 ビット ADC
 - 充電電流、バッテリー・サーミスタ、バッテリー電圧、入力電圧、システム (PMID) 電圧の監視
 - 汎用 ADC 入力
- 常時オンの 1.8V VDD LDO で最大 10mA の負荷をサポート
- 20 ピンの 2mm x 1.6mm CSP パッケージ
- ソリューション全体のサイズ: 12mm²

2 アプリケーション

- ヘッドセット、イヤホン、補聴器
- スマート・ウォッチおよびフィットネス機器
- 患者モニタおよび携帯用医療機器

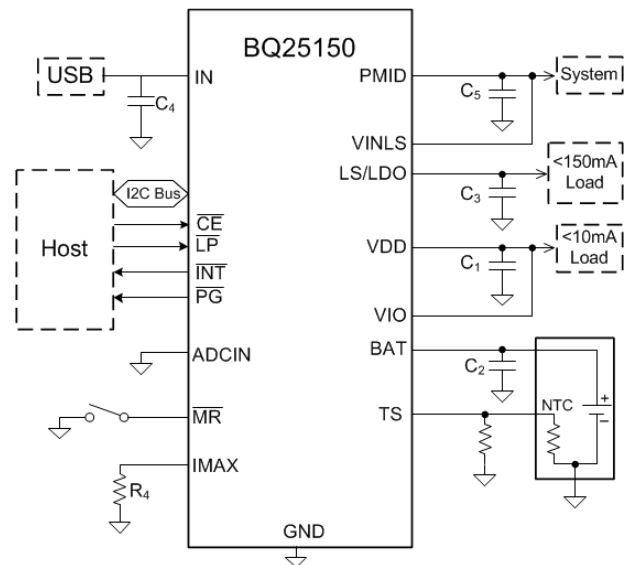
3 概要

BQ25150 は高度に統合されたバッテリー充電管理 IC で、充電器、出力電圧レール、バッテリーおよびシステム監視用の ADC、押しボタン・コントローラなど、ウェアラブル・デバイスの最も一般的な機能を内蔵しています。

製品情報

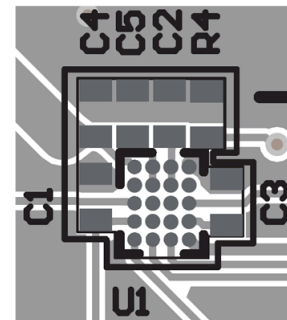
部品番号 (1)	パッケージ	本体サイズ (公称)
BQ25150	DSBGA (20)	2.00mm × 1.60mm

- (1) 利用可能なすべてのパッケージについては、データシートの末尾にある注文情報を参照してください。



簡略回路図

12 mm² Solution Size



- 0402 Component footprint with 0.2mm pitch
- Pull up and TS resistors not included

ソリューション面積



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4 Revision History

資料番号末尾の英字は改訂を表しています。その改訂履歴は英語版に準じています。

Changes from Revision B (February 2019) to Revision C (April 2023)	Page
• タイトル説明を変更.....	1
• Added Key Device Default Settings Table.....	5
• Added clarification to $\overline{\text{P}}$ pin description.....	6
• Added clarification to ADCIN pin description.....	6
• Changed maximum recommended PMID output current.....	8
• Changed maximum $R_{\text{ON}}(\text{BAT-PMID})$ in Electrical Characteristics.....	9
• Changed $t_{\text{HW_RESET_WD}}$ test conditions and MAX value.....	12
• Changed $t_{\text{RESET_WARN}}$ and $t_{\text{HW_RESET}}$ parameters.....	12
• Changed Input Voltage Based Dynamic Power Management (VINDPM) and Dynamic Power Path Management (DPPM) section to simplify description.....	20
• Added clarification to ADC functionality when VIN is present.....	23
• Added clarification to ADC %ICHARGE reading.....	23
• Added more details to the ADC Programmable Comparator description.....	24
• Deleted incorrect reference to LS_CTRL pin and updated description.....	25
• Added clarification on LDO voltage programmability.....	25
• Updated 図 9-3	26
• Changed $t_{\text{HW_RESET_WARN}}$ to $t_{\text{RESET_WARN}}$ and VIN presence to valid VIN presence in セクション 9.3.7.2	27
• Added clarification to TS biasing operation.....	32
• Deleted as well from セクション 9.4.1 description.....	36
• Added link to BQ25150 Setup Guide and Setup Guide Tool.....	40
• Changed registers 0x42 to 0x4F from R/W-X to R-X and R/W to R for type.....	40
• Changed IBAT_OCP_ILIM 2b10 setting description from 1500 mA to Disabled.....	40
• Added clarification to TS_EN bit functionality.....	40
• Changed from TS to ground to from IMAX to ground in セクション 10.2.2.3	96
• Added TS Biasing Figure.....	97
• Added VINLS bypass capacitor layout guideline.....	102

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• タイトルから 12 ビットを削除.....	1
• 制限付きから公開に変更.....	1
• Changed ADC reported resolution TYP value from 12 to 16	9
• Changed T _{SHUTDOWN} TYP value from 115°C to 125°C	9
• Changed PUSHBUTTON TIMERS (/MR) number of decimal points in MIN/MAX from 3 to 2.....	12
• Deleted t _{DGL_SC} parameter.....	12
• Deleted t _{LP_ENTRY} parameter	12
• Changed default state description for watchdog in セクション 9.3.2.2	21
• Deleted 12-Bit from セクション 9.3.3	23
• Changed LS/LDO1 to V _{LSLDO} in セクション 9.3.5	25
• Added セクション 9.3.8	29
• Changed THERM_REG_2:0 reset value in セクション 9.5.1.18	40
• Changed 1_ADCALARM_ABOVE in 表 9-51	40
• Changed 2_ADCALARM_ABOVE in 表 9-53	40
• Changed 3_ADCALARM_ABOVE in 表 9-55	40

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• 「事前情報」から「量産データ」に変更.....	1
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5 概要 (続き)

BQ25150 IC にはリニア充電器が内蔵されており、小型のバッテリーを迅速かつ正確に充電できます。最大 500mA の充電電流と、最小 0.5mA の終了電流をサポートしており、最大限の充電が可能です。バッテリーは、標準のリチウムイオン充電プロファイルを使用して、プリチャージ、定電流、定電圧レギュレーションの 3 つのフェーズで充電されます。

デバイスには高度なパワー・パス管理および制御機能が内蔵されているため、貧弱なアダプタでも、システムへ電力を供給すると同時に、バッテリーを充電できます。また、ホストは I²C 経由でパワー・パスを制御でき、物理的な取り外しを行わずに、入力アダプタやバッテリーからホストを切断できます。単一の押しボタン入力により、ボタン・コントローラ IC を別個に追加する必要がなくなり、ソリューションの合計フットプリントが小さくなります。この押しボタン入力は、ウェイク機能やシステムのリセットにも使用できます。実効 12 ビットの ADC により、正確なバッテリー電圧監視が可能であり、バッテリーの健全性を監視するための低 I_q 測定に使えます。また、TS ピンに接続されるサーミスタや、ADCIN ピン経由の外部システムの信号を使用して、バッテリー温度を測定することもできます。動作時およびシャットダウン時の静止電流が小さいため、最大のバッテリー駆動時間が得られます。入力電流制限、充電電流、LDO 出力電圧、その他のパラメータは、I²C インターフェイスによりプログラム可能なため、BQ25150 は非常に柔軟な充電ソリューションとなっています。電圧ベースの JEITA 互換 (または標準の HOT/COLD) バッテリーパック・サーミスタ監視入力 (TS) が含まれており、バッテリーの温度を監視しながら、バッテリーが充電中に安全な温度範囲を逸脱しないよう、充電パラメータを自動的に変更します。温度スレッショルドは I²C からでもプログラム可能なため、ホストは熱充電プロファイルをカスタマイズ可能です。充電器は 5V USB 入力に対して最適化されており、ラインの過渡電圧に耐えられるように耐圧の絶対最大定格は 20V です。また、デバイスにはリニア・レギュレータも内蔵されており、無線やプロセッサ用に低ノイズのレールを提供し、I²C 経由で独立にソースおよび制御が可能です。

6 Device Key Default Settings

DEFAULT SETTING	BQ25150	BQ25155
Fast Charge Current (I_{CHARGE})	10 mA	10 mA
Pre-Charge Current ($I_{PRECHARGE}$)	2.5 mA	2.5 mA
Termination Current (I_{TERM})	10% of I_{CHARGE}	10% of I_{CHARGE}
Input Current Limit (I_{LIM})	100 mA	500 mA
VIN DPM	Enabled	Disabled
LDO Output Voltage (V_{LDO})	1.8 V	1.8 V
Ship Mode Wake Timer	2 seconds	0.125 seconds
DEVICE_ID	0x20h	0x35h

7 Pin Configuration and Functions

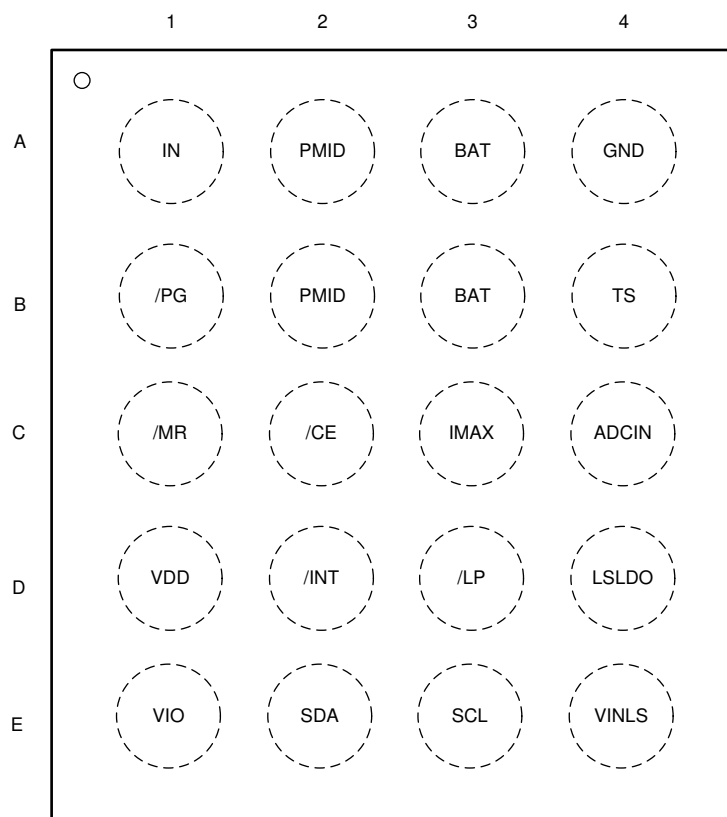


图 7-1. YFP Package 20-Pin DSBGA Top View

表 7-1. Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
IN	A1	I	DC Input Power Supply. IN is connected to the external DC supply. Bypass IN to GND with at least 1 μ F of capacitance using a ceramic capacitor.
PMID	A2, B2	I/O	High Side Bypass Connection. Connect at least 10- μ F ceramic capacitor (at least 3 μ F of ceramic capacitance with DC bias de-rating) from PMID to GND as close to the PMID and GND pins as possible. Note: Shorting PMID to IN pin is not recommended as it may cause large discharge current from battery to IN if IN pin is not truly floating.
GND	A4	PWR	Ground connection. Connect to the ground plane of the circuit.
VDD	D1	O	Digital supply LDO. Connect at least 4.7- μ F capacitor to ground.
$\overline{\text{CE}}$	C2	I	Charge Enable. Drive $\overline{\text{CE}}$ low or leave disconnected to enable charging when VIN is valid. Drive $\overline{\text{CE}}$ high to disable charge when VIN is present. $\overline{\text{CE}}$ is pulled low internally with 900-k Ω resistor. $\overline{\text{CE}}$ has no effect when VIN is not present.
SCL	E3	I/O	I ² C Interface Clock. Connect SCL to the logic rail through a 10-k Ω resistor.
SDA	E2	I	I ² C Interface Data. Connect SDA to the logic rail through a 10-k Ω resistor.
$\overline{\text{LP}}$	D3	I	Low Power Mode Enable. Drive this pin low to set the device in low power mode when powered by the battery. This pin must be driven high to allow I ² C communication when VIN is not present. $\overline{\text{LP}}$ is pulled low internally with 900-k Ω resistor. This pin has no effect when VIN is present.
IMAX	C3	I	Connect a 10-k Ω or lower resistor to this pin to set the maximum allowable fast charge current. Must not be left floating.
INT	D2	O	INT is an open-drain output that signals fault interrupts. When a fault occurs, a 128- μ s pulse is sent out as an interrupt for the host. INT is enabled/disabled using the MASK_INT bit in the control register.

表 7-1. Pin Functions (continued)

PIN		I/O	DESCRIPTION
NAME	NO.		
ADCIN	C4	I	Input Channel to the ADC. Maximum ADC range 1.2 V. Leave floating or connect to ground if not used.
MR	C1	I	Manual Reset Input. MR is a general purpose input that must be held low for greater than $t_{HWRESET}$ to go into HW Reset and power cycle the output rails. If MR is also used to wake up the device out of Ship Mode when pressed for at least t_{WAKE2} . MR has in internal 125-kΩ pull-up resistor to BAT.
LS/LDO	D4	O	Load Switch or LDO output. Connect 2.2 μF of ceramic capacitance to this pin to assure stability. Be sure to account for capacitance bias voltage derating when selecting the capacitor. If LDO is not to be used,, the pin may be shorted to VINLS
VINLS	E4	I	Input to the Load Switch / LDO output. Connect at least 1 μF of ceramic capacitance from this pin to ground.
BAT	A3, B3	I/O	Battery Connection. Connect to the positive terminal of the battery. Bypass BAT to GND with at least 1 μF of ceramic capacitance.
TS	B4	I	Battery Pack NTC Monitor. Connect TS to a 10-kΩ NTC Thermistor in parallel to a 10-kΩ resistor. If TS function is not to be used connect a 5-kΩ resistor from TS to ground.
PG	B1	O	Open-drain Power Good status indication output. PG is pulled to GND when VIN is above $V_{BAT} + V_{SLP}$ and less than V_{OVP} . PG is high-impedance when the input power is not within specified limits. Connect PG to the desired logic voltage rail using a 1-kΩ to 100-kΩ resistor, or use with an LED for visual indication. PG can also be configured through I ² C as a push-button level shifted output (MR), where the output of the PG pin reflects the status of the MR input, but pulled up to the desired logic voltage rail using a 1-kΩ to 100-kΩ resistor. The PG pin can also be configured as a general purpose open drain output.
VIO	E1	I	System IO supply. Connect to system IO supply to allow level shifting of input signals (SDA, SCL, LP and CE) to the device internal digital domain. Connect to VDD when external IO supply is not available.

8 Specifications

8.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
Voltage	IN	−0.3	20	V
	TS, ADCIN, IMAX, VDD	−0.3	1.95	V
	All other pins	−0.3	5.5	V
Current	IN	0	800	mA
	BAT, PMID	−0.5	1.5	A
	INT, ADCIN, PG	0	10	mA
Junction temperature, T _J		−40	125	°C
Storage temperature, T _{stg}		−55	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Rating* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Condition*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

8.2 ESD Ratings

		VALUE	UNIT
V _(ESD) Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽¹⁾	±2000	V
	Charged device model (CDM), per JEDEC specification JESD22-C101, all pins ⁽²⁾	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
 (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

8.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V _{BAT}	Battery voltage range	2.4		4.6	V
V _{IN}	Input voltage range	3.15		5.25 ⁽¹⁾	V
V _{INLS}	LDO input voltage range	2.2		5.25 ⁽¹⁾	V
V _{IO}	IO supply voltage range	1.2		3.6	V
V _{ADCIN}	ADC input voltage range	0		1.2	V
I _{LDO}	LDO output current	0		100	mA
I _{PMID}	PMID output current	0		1	A
T _A	Operating free-air temperature range	−40		85	°C

- (1) Based on minimum V_{OVP} value. 5.5V under typical conditions

8.4 Thermal Information

THERMAL METRIC ⁽¹⁾		BQ25152/56	UNIT
		YFP (DSBGA)	
		20-PIN	
R _{θJA}	Junction-to-ambient thermal resistance ⁽²⁾	36.1	°C/W
R _{θJA}	Junction-to-ambient thermal resistance	74.4	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	0.5	°C/W
R _{θJB}	Junction-to-board thermal resistance	17.6	°C/W

8.4 Thermal Information (continued)

THERMAL METRIC ⁽¹⁾		BQ25152/56	UNIT
		YFP (DSBGA)	
		20-PIN	
Ψ_{JT}	Junction-to-top characterization parameter	0.3	°C/W
Ψ_{JB}	Junction-to-board characterization parameter	17.7	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	N/A	°C/W

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.
- (2) Measured in BQ25150EVM board

8.5 Electrical Characteristics

$V_{IN} = 5V$, $V_{BAT} = 3.6V$. $-40^{\circ}C < T_J < 125^{\circ}C$ unless otherwise noted. Typical data at $T_J = 25^{\circ}C$

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
INPUT CURRENTS						
I _{IN}	Input supply current	PMID_MODE= 01, V _{IN} = 5V, V _{BAT} = 3.6V			500	μA
		0°C <T _J < 85°C , V _{IN} = 5V, V _{BAT} = 3.6V Charge Disabled		0.78	1.5	mA
I _{BAT_SHIP}	Battery Discharge Current in Ship Mode	0°C <T _J < 60°C ,V _{IN} = 0V , V _{BAT} = 3.6V		10	150	nA
I _{BAT_LP}	Battery Quiescent Current in Low-power Mode	0°C <T _J < 60°C ,V _{IN} = 0V , V _{BAT} = 3.6V, LDO Disabled		0.46	1.2	μA
		0°C <T _J < 60°C ,V _{IN} = 0V , V _{BAT} = 3.6V, LDO Enabled		1.7	3.5	μA
I _{BAT_ACTIVE}	Battery Quiescent Current in Active Mode	0°C <T _J < 85°C ,V _{IN} = 0V , V _{BAT} = 3.6V, LDO Disabled		18	25	μA
		0°C <T _J < 85°C ,V _{IN} = 0V , V _{BAT} = 3.6V, LDO Enabled		21	27	μA
POWER PATH MANAGEMENT AND INPUT CURRENT LIMIT						
R _{ON(IN-PMID)}	Input FET ON resistance	I _{LIM} = 500mA (I _{LIM} = 110), V _{IN} = 5V, I _{IN} = 150mA		280	520	mΩ
V _{BSUP1}	Enter supplements mode threshold	V _{BAT} > V _{BATUVLO} ,		V _{PMID} < V _{BAT} – 40mV		mV
V _{BSUP2}	Exit supplements mode threshold	V _{BAT} > V _{BATUVLO}		V _{PMID} < V _{BAT} – 20mV		mV
I _{LIM}	Input Current Limit	Programmable Range		50	600	mA
		I _{LIM} = 50mA		45	50	mA
		I _{LIM} = 100mA		90	100	mA
		I _{LIM} = 150mA		135	150	mA
		I _{LIM} = 500mA		450	500	mA
V _{IN_DPM}	Input DPM voltage threshold where current is reduced	Programmable Range		4.2	4.9	V
	Accuracy			–3	3	%
BATTERY CHARGER						
V _{DPPM}	PMID voltage threshold when charge current is reduced	V _{PMID} - V _{BAT}		200		mV
R _{ON(BAT-PMID)}	Battery Discharge FET On Resistance	V _{BAT} = 4.35V, I _{BAT} = 100mA		100	135	mΩ
V _{BATREG}	Charge Voltage	Programmable charge voltage range		3.6	4.6	V
	Voltage Regulation Accuracy	T _J = 25°C		0.5	0.5	%

8.5 Electrical Characteristics (continued)

$V_{IN} = 5V$, $V_{BAT} = 3.6V$. $-40^{\circ}C < T_J < 125^{\circ}C$ unless otherwise noted. Typical data at $T_J = 25^{\circ}C$

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
I_{CHARGE}	Fast Charge Programmable Current Range	$V_{LOWV} < V_{BAT} < V_{BATREG}$	1.25		500	mA
	Fast Charge Current Accuracy	$T_J = 25^{\circ}C$, $I_{CHARGE} > 5mA$	-5		5	%
$I_{PRECHARGE}$	Precharge current	Precharge current programmable range	1.25		77.5	mA
	Precharge Current Accuracy	$-40^{\circ}C < T_J < 85^{\circ}C$	-10		10	%
I_{TERM}	Termination Charge Current	Termination Current Programmable Range	1		31	%
	Accuracy	$T_J = 25^{\circ}C$, $I_{TERM} = 10\% I_{CHARGE}$, $I_{CHARGE} = 100mA$	-5 ⁽¹⁾		5 ⁽¹⁾	%
		$-10^{\circ}C < T_J < 85^{\circ}C$, $I_{TERM} = 10\% I_{CHARGE}$, $I_{CHARGE} = 100mA$	-10 ⁽¹⁾		10 ⁽¹⁾	%
V_{LOWV}	Programmable voltage threshold for pre-charge to fast charge transitions	V_{BAT} rising. Programmable Range	2.8		3	V
V_{SHORT}	Battery voltage threshold for short detection	V_{BAT} falling, $V_{IN} = 5V$	2.41	2.54	2.67	V
I_{SHORT}	Charge Current in Battery Short Condition	$V_{BAT} < V_{SHORT}$		$I_{PRECHARGE}$		mA
V_{RCH}	Recharge Threshold voltage	V_{BAT} falling, $V_{BATREG} = 4.2V$, $V_{RCH} = 140mV$ setting		140		mV
		V_{BAT} falling, $V_{BATREG} = 4.2V$, $V_{RCH} = 200mV$ setting		200		mV
R_{PMID_PD}	PMID pull-down resistance	$V_{PMID} = 3.6V$		25		Ω
VDD						
V_{DD}	VDD LDO output voltage	$V_{BAT} = 3.6V$, $V_{IN} = 0V$, $0 < I_{LOAD_VDD} < 10mA$		1.8		V
I_{LOAD_VDD}	Maximum VDD External load capability	$V_{PMID} > 3V$			10	mA
LS/LDO						
V_{INLS}	Input voltage range for Load switch Mode		0.8		5.5	V
	Input voltage range for LDO Mode		2.2 or $V_{LDO} + 500mV$		5.5	V
V_{LDO}	LDO programmable output voltage range		0.6		3.7	V
	LDO output accuracy	$T_J = 25^{\circ}C$	-2		2	%
		$V_{LDO} = 1.8V$, $V_{INLS} = 3.6V$, $I_{LOAD} = 1mA$	-3		3	%
$\Delta V_{OUT}/\Delta I_{OUT}$	DC Load Regulation	$0^{\circ}C < T_J < 85^{\circ}C$, $1mA < I_{OUT} < 150mA$, $V_{LDO} = 1.8V$		1.2		%
$\Delta V_{OUT}/\Delta V_{IN}$	DC Line Regulation	$0^{\circ}C < T_J < 85^{\circ}C$, Over V_{INLS} range, $I_{OUT} = 100mA$, $V_{LDO} = 1.8V$		0.5		%
R_{DOSN_LDO}	Switch On resistance	$V_{INLS} = 3.6V$		250	450	m Ω
$R_{DSCH_LS_LDO}$	Discharge FET On-resistance for LS	$V_{INLS} = 3.6V$		40		Ω
I_{OCL_LDO}	Output Current Limit	$V_{LS/LDO} = 0V$	200	300		mA
I_{IN_LDO}	LDO VINLS quiescent current in LDO mode	$V_{BAT} = V_{INLS} = 3.6V$		0.9		μA
	OFF State Supply Current	$V_{BAT} = V_{INLS} = 3.6V$		0.25		μA
ADC						

8.5 Electrical Characteristics (continued)

$V_{IN} = 5V$, $V_{BAT} = 3.6V$. $-40^{\circ}C < T_J < 125^{\circ}C$ unless otherwise noted. Typical data at $T_J = 25^{\circ}C$

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
Resolution	Bits reported by ADC			16		Bits
t_{ADC_CONV}	Conversion-time	ADC_SPEED = 00		24		ms
		ADC_SPEED = 01		12		ms
		ADC_SPEED = 10		6		ms
		ADC_SPEED = 11		3		ms
Resolution	Effective Resolution	ADC_SPEED = 00		12		Bits
		ADC_SPEED = 10		10		Bits
Accuracy	ADC TS Accuracy	ADC_SPEED = 00, $V_{TS} = 0.4V$, $-10^{\circ}C < T_J < 85^{\circ}C$	-1 ⁽¹⁾		1 ⁽¹⁾	%
	ADC ADCIN Accuracy	ADC_SPEED = 00, $V_{ADCIN} = 0.4V$, $-10^{\circ}C < T_J < 85^{\circ}C$	-1 ⁽¹⁾		1 ⁽¹⁾	%
	ADC VBAT Accuracy	ADC_SPEED = 00, $V_{BAT} = 4.2V$, $-10^{\circ}C < T_J < 85^{\circ}C$	-0.4		0.4	%
BATTERY PACK NTC MONITOR						
V_{HOT}	High temperature threshold	V_{TS} falling, $-10^{\circ}C < T_J < 85^{\circ}C$	0.182 ⁽¹⁾	0.185	0.189 ⁽¹⁾	V
V_{WARM}	Warm temperature threshold	V_{TS} falling, $-10^{\circ}C < T_J < 85^{\circ}C$	0.262 ⁽¹⁾	0.265	0.268 ⁽¹⁾	V
V_{COOL}	Cool temperature threshold	V_{TS} rising, $-10^{\circ}C < T_J < 85^{\circ}C$	0.510 ⁽¹⁾	0.514	0.518 ⁽¹⁾	V
V_{COLD}	Cold temperature threshold	V_{TS} rising, $-10^{\circ}C < T_J < 85^{\circ}C$	0.581 ⁽¹⁾	0.585	0.589 ⁽¹⁾	V
V_{OPEN}	TS Open threshold	V_{TS} rising, $-10^{\circ}C < T_J < 85^{\circ}C$		0.9		V
V_{HYS}	Threshold hysteresis			4.7		mV
I_{TS_BIAS}	TS bias current	$-10^{\circ}C < T_J < 85^{\circ}C$	78.4	80	81.6	μA
PROTECTION						
V_{UVLO}	IN active threshold voltage	V_{IN} rising		3.4		V
		V_{IN} falling		3.25		V
$V_{BATUVLO}$	Battery undervoltage Lockout Threhshold Voltage	Programmable range, 150 mV Hysteresis	2.4		3	V
	Accuracy		-3		3	%
	Battery undervoltage Lockout Threhshold Voltage at Power Up	V_{BAT} rising, $V_{IN} = 0V$, $T_J = 25^{\circ}C$		3.15		V
V_{SLP_ENTRY}	Sleep Entry Threshold ($V_{IN} - V_{BAT}$)	$2.0V < V_{BAT} < V_{BATREG}$, V_{IN} falling		80		mV
V_{SLP_EXIT}	Sleep Exit Threshold ($V_{IN} - V_{BAT}$)	$2.0V < V_{BAT} < V_{BATREG}$		130		mV
V_{OVP}	Input Supply Over Voltage Threshold	V_{IN} rising	5.35	5.5	5.8	V
		V_{IN} falling (125mV hysteresis)		5.4		V
I_{BAT_OCP}	Batery Over Current Threshold Programmable range	I_{BAT_OCP} increasing	1200		1600	mA
	Current Limit Accuracy		-30		30	%
$T_{SHUTDOWN}$	Thermal shutdown trip point			125		$^{\circ}C$
T_{HYS}	Thermal shutdown trip point hysteresis			15		$^{\circ}C$
I²C INTERFACE (SCL and SDA)						
I2C Frequency			100		400	kHz
V_{IL}	Input Low threshold level	$V_{PULLUP} = V_{IO} = 1.8V$			0.25 * V_{IO}	V

8.5 Electrical Characteristics (continued)

$V_{IN} = 5V$, $V_{BAT} = 3.6V$. $-40^{\circ}C < T_J < 125^{\circ}C$ unless otherwise noted. Typical data at $T_J = 25^{\circ}C$

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V_{IH} Input High Threshold level	$V_{PULLUP} = V_{IO} = 1.8V$	0.75 * V_{IO}			V
V_{OL} Output Low threshold level	$V_{PULLUP} = V_{IO} = 1.8V$, $I_{LOAD} = 5mA$			0.25 * V_{IO}	V
I_{LKG} High-level leakage Current	$V_{PULLUP} = V_{IO} = 1.8V$			1	μA
/MR INPUT					
R_{PU} Internal pull up resistance		90	125	170	k Ω
V_{IL} /MR Input Low threshold level	$V_{BAT} > V_{BUVLO}$			0.3	V
/INT, /PG OUTPUTS					
V_{OL} Output Low threshold level	$V_{PULLUP} = V_{IO} = 1.8V$, $I_{LOAD} = 5mA$			0.25 * V_{IO}	V
I_{LKG} /INT Hi level leakage Current	High Impedance, $V_{PULLUP} = V_{IO} = 1.8V$			1	μA
/CE, /LP INPUTS					
R_{PDOWN} /CE pull down resistance			900		k Ω
V_{IL} Input Low threshold level	$V_{IO} = 1.8V$			0.45	V
V_{IH} /CE Input High Threshold level	$V_{IO} = 1.8V$	1.35			V

(1) Based on Characterization Data

8.6 Timing Requirements

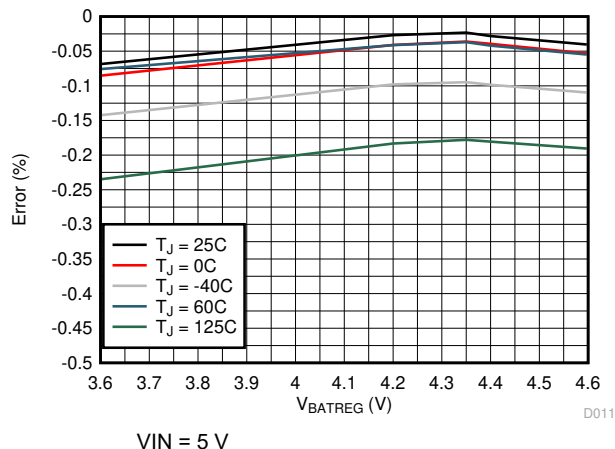
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
BATTERY CHARGE TIMERS					
t_{MAXCHG} Charge safety timer	Programmable range	180		720	min
t_{PRECHG} Precharge safety timer			0.25 * t_{MAXCHG}		
WATCHDOG TIMERS					
$t_{WATCHDOG_SW}$ SW Watchdog timer		25	50		s
$t_{HW_RESET_WD}$ HW reset watchdog timer	HWRESET_14S_WD = 1			14	s
LDO					
t_{ON_LDO} Turn ON time	100mA load, to 90% V_{LDO}		500		μs
t_{OFF_LDO} Turn OFF time	100mA load, to 10% V_{LDO}		30		μs
$t_{PMID_LDO_DELAY}$ Delay between PMID and LDO enable during power up	Startup		20		ms
PUSHBUTTON TIMERS (/MR)					
t_{WAKE1} WAKE1 Timer. Time from /MR falling edge to INT being asserted.	MR_WAKE1_TIMER = 0	106	125	144	ms
	MR_WAKE1_TIMER = 1	425	500	575	ms
t_{WAKE2} WAKE2 Timer. Time from /MR falling edge to INT being asserted.	MR_WAKE2_TIMER = 0	0.85	1	1.15	s
	MR_WAKE2_TIMER = 1	1.7	2	2.3	s
t_{RESET_WARN} RESET_WARN Timer. Time prior to HW RESET or entering shipmode with MR press	MR_RESET_WARN = 00	0.42	0.5	0.58	s
	MR_RESET_WARN = 01	0.85	1	1.15	s
	MR_RESET_WARN = 10	1.27	1.5	1.73	s
	MR_RESET_WARN = 11	1.7	2	2.3	s
$t_{HW_RESET_T}$ HW RESET Timer. Time from /MR falling edge to HW Reset or PMID falling for shipmode entry	MR_HW_RESET = 00	3.4	4	4.6	s
	MR_HW_RESET = 01	6.8	8	9.2	s
	MR_HW_RESET = 10	8.5	10	11.5	s
	MR_HW_RESET = 11	11.9	14	16.1	s

8.6 Timing Requirements (continued)

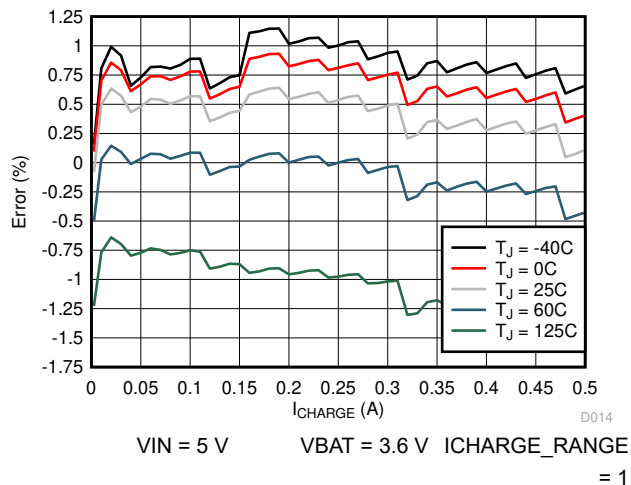
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t _{RESTART(AUTOWAKE)} RESTART Timer. Time from /MR HW Reset to PMID power up	AUTOWAKE = 00	0.52	0.6	0.68	s
	AUTOWAKE = 01	1.05	1.2	1.35	s
	AUTOWAKE = 10	2.11	2.4	2.69	s
	AUTOWAKE = 11	4.4	5	5.6	s
PROTECTION					
t _{DGL_SLP} Deglitch time for supply rising above V _{SLP} + V _{SLP_HYS}			120		μs
t _{DGL_OVP} Deglitch time for V _{OVP} Threshold	VIN falling below V _{OVP}		32		ms
t _{DGL_OCP} Battery OCP deglitch time			30		μs
t _{REC_SC} Recovery time, BAT Short Circuit during Discharge Mode			250		ms
t _{RETRY_SC} Retry window for PMID or BAT short circuit recovery			2		s
t _{DGL_SHTDWN} Deglitch time, Thermal shutdown	T _J rising above T _{SHUTDOWN}		10		μs
I2C INTERFACE					
t _{WATCHDOG} I2C interface reset timer for host	When enabled		50		s
t _{I2CRESET} I2C interface inactive reset timer			500		ms
INPUT PINS (/CE and /LP)					
t _{LP_EXIT_I2C} Time for device to exit Low-power mode and allow I ² C communication	V _{IN} = 0V.			1	ms

8.7 Typical Characteristics

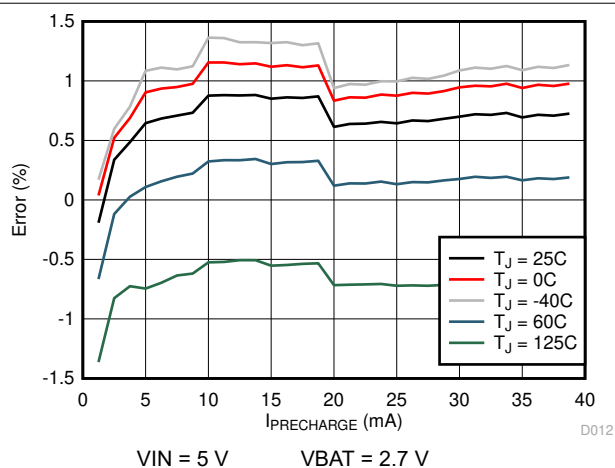
$C_{IN} = 1 \mu F$, $C_{PMID} = 10 \mu F$, $C_{LSLDO} = 2.2 \mu F$, $C_{BAT} = 1 \mu F$ (unless otherwise specified)



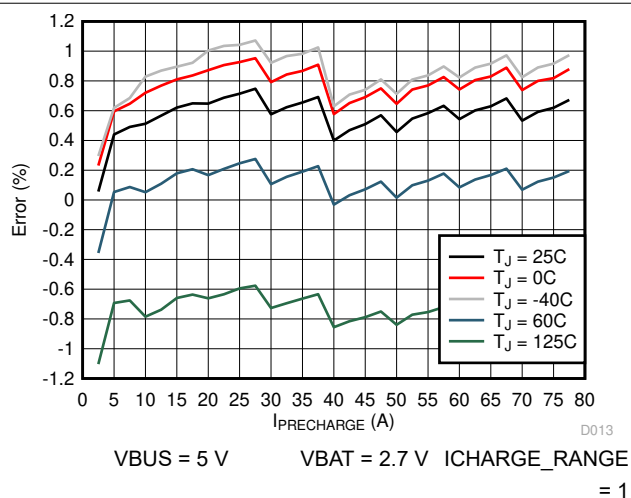
8-1. Battery Regulation Voltage Accuracy vs. VBATREG Setting



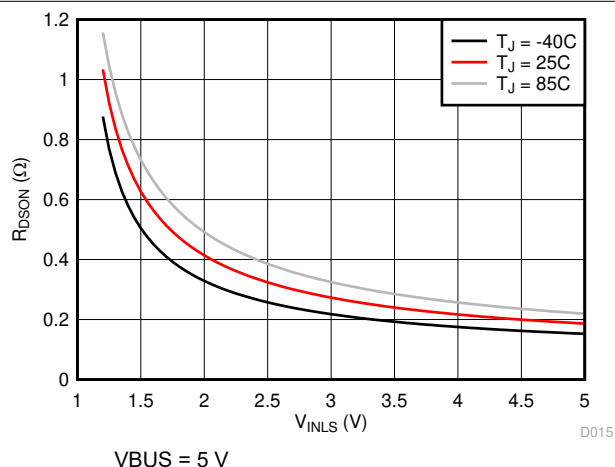
8-2. Charge Current Accuracy vs. ICHARGE Setting



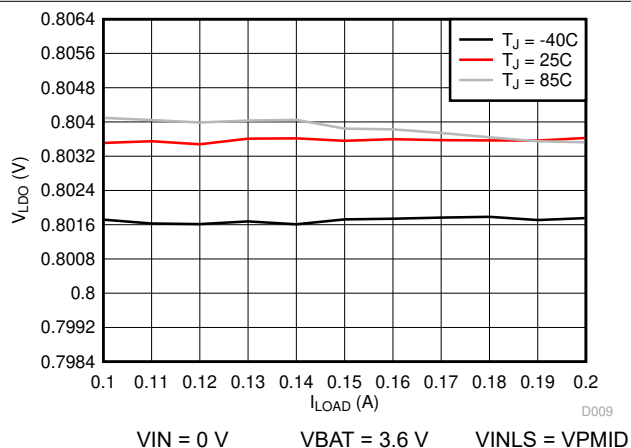
8-3. Pre-Charge Current Accuracy vs. IPRECHARGE Setting (ICHARGE_RANGE = 0)



8-4. Pre-Charge Current Accuracy vs. IPRECHARGE Setting (ICHARGE_RANGE = 1)



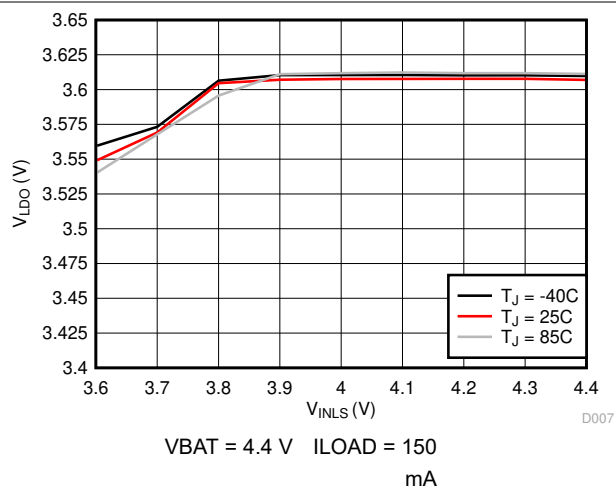
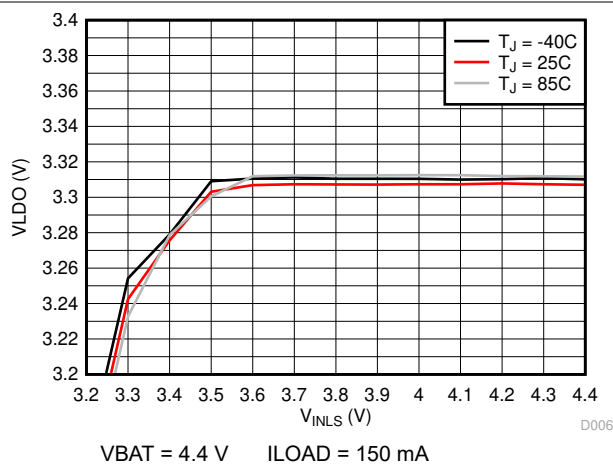
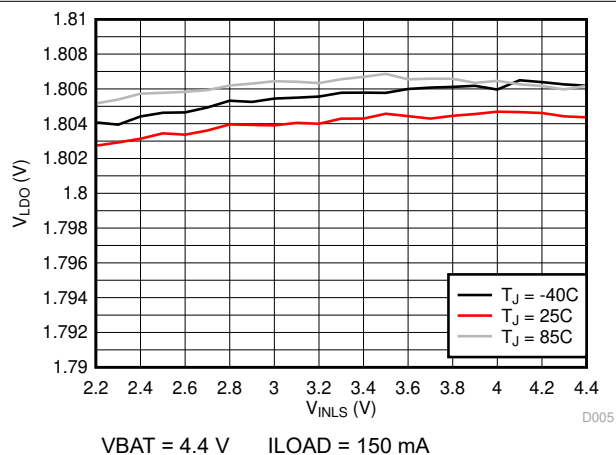
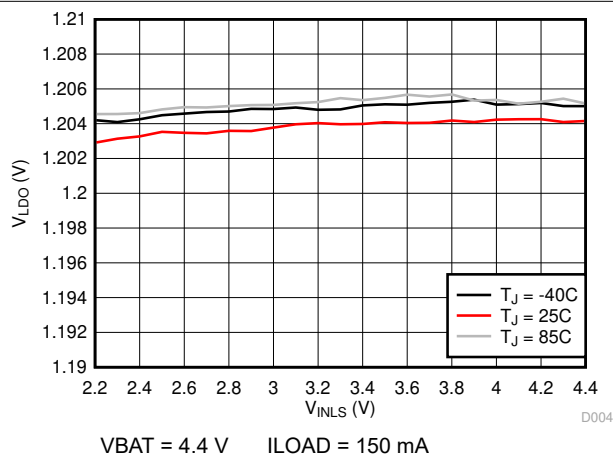
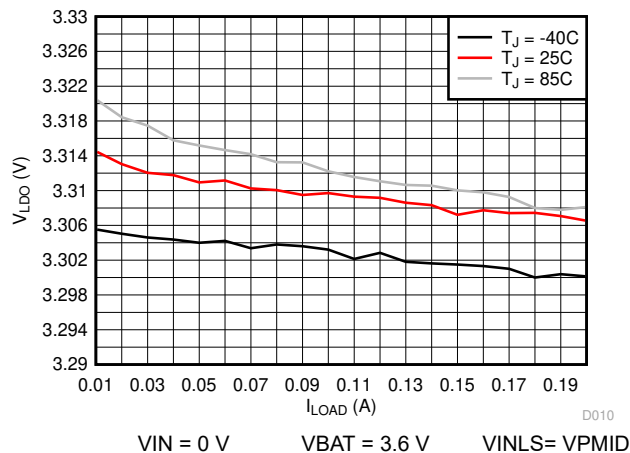
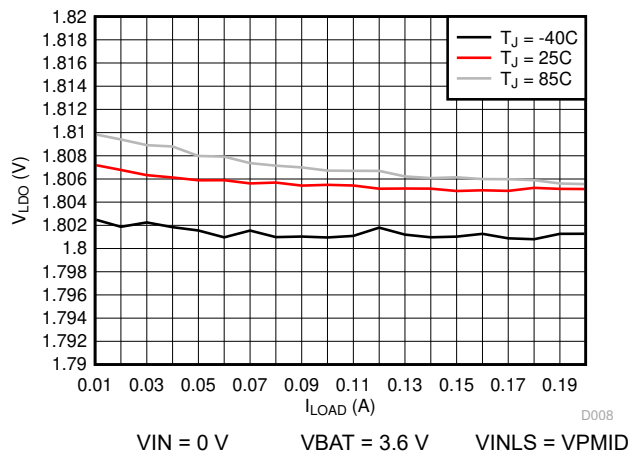
8-5. LS/LDO Switch On Resistance vs. VINLS



8-6. LDO Load Regulation (VLDO = 0.8 V)

8.7 Typical Characteristics (continued)

$C_{IN} = 1 \mu F$, $C_{PMID} = 10 \mu F$, $C_{LSLDO} = 2.2 \mu F$, $C_{BAT} = 1 \mu F$ (unless otherwise specified)

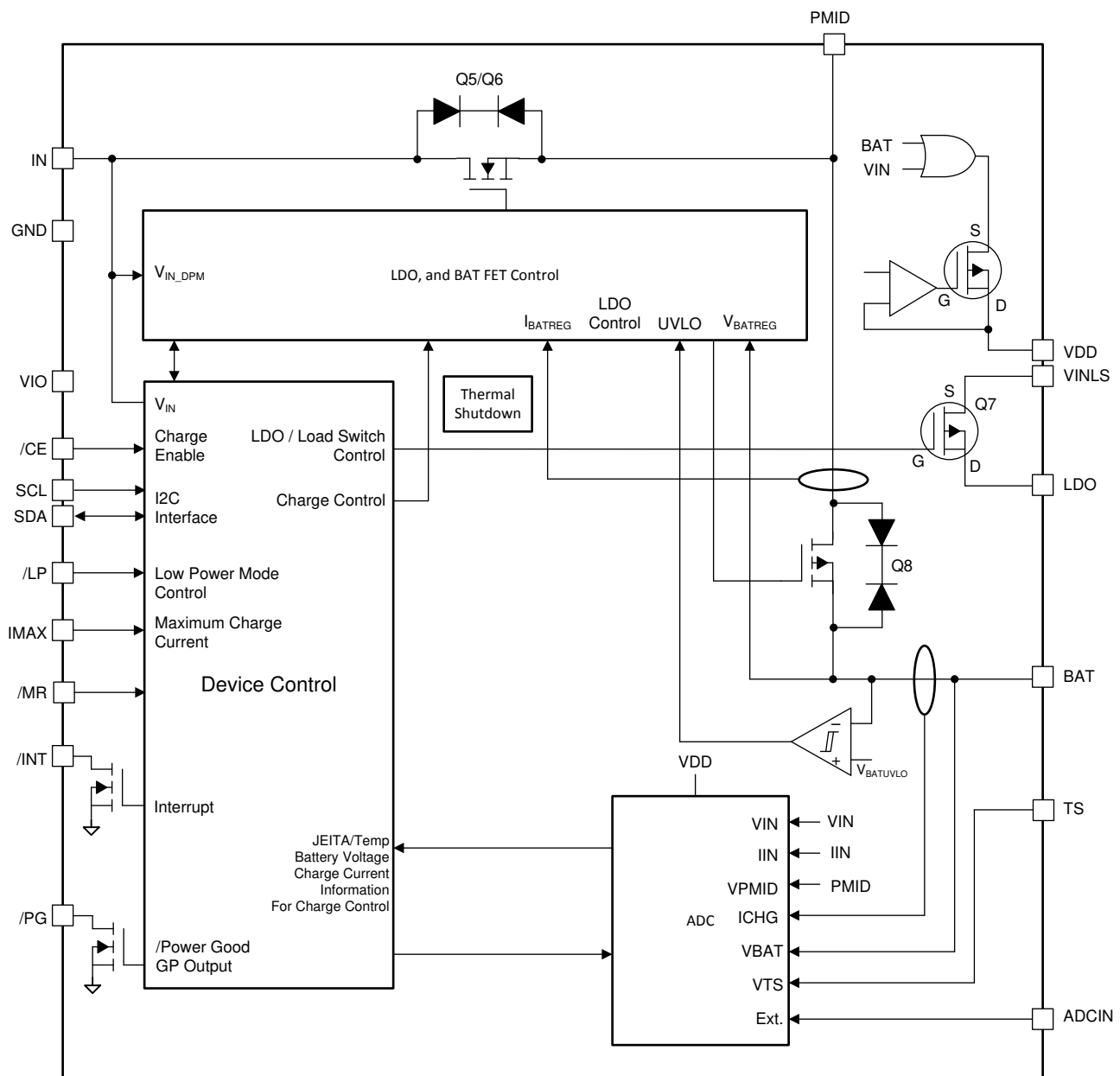


9 Detailed Description

9.1 Overview

The BQ25150 IC is a highly programmable battery management device that integrates a 500mA linear charger for single cell Li-Ion batteries, a 12-bit effective ADC, a general purpose LDO that may be configured as a load switch, and a push-button controller. Through its I²C interface the host may change charging parameters such as battery regulation voltage and charge current, and obtain detailed device status and fault information. The host may also read ADC measurements for battery and input voltage among other parameters, including the ADCIN pin voltage. The push-button controller allows the user to reset the system without any intervention from the host and wake up the device from Ship Mode.

9.2 Functional Block Diagram



9.3 Feature Description

9.3.1 Linear Charger and Power Path

The BQ25150 IC integrates a linear charger that allows the battery to be charged with a programmable charge current of up to 500 mA. In addition to the charge current, other charging parameters can be programmed through I²C such as the battery regulation voltage, pre-charge current, termination current, and input current limit current.

The power path allows the system to be powered from PMID, even when the battery is dead or charging, by drawing power from IN pin. It also prioritizes the system load connected to PMID, reducing the charging current, if necessary, in order to support the load when input power is limited. If the input supply is removed and the battery voltage level is above $V_{BATUVLO}$, PMID will automatically and seamlessly switch to battery power.

There are several control loops that influence the charge current: constant current loop (CC), constant voltage loop (CV), VDPPM, VINDPM, and input current limit. During the charging process, all loops are enabled and the one that is dominant takes control regulating the charge current as needed. The charger input has back to back blocking FETs to prevent reverse current flow from PMID to IN. They also integrate control circuitry regulating the input current and prevents excessive currents from being drawn from the IN power supply for more reliable operation.

The device supports multiple battery regulation voltage regulation settings (V_{BATREG}) and charge current (I_{CHARGE}) options to support multiple battery chemistries for single-cell applications.

A more detailed description of the charger functionality is presented in the following sections of this document.

9.3.1.1 Battery Charging Process

☒ 9-1 summarizes the charging process of the BQ25150 charger.

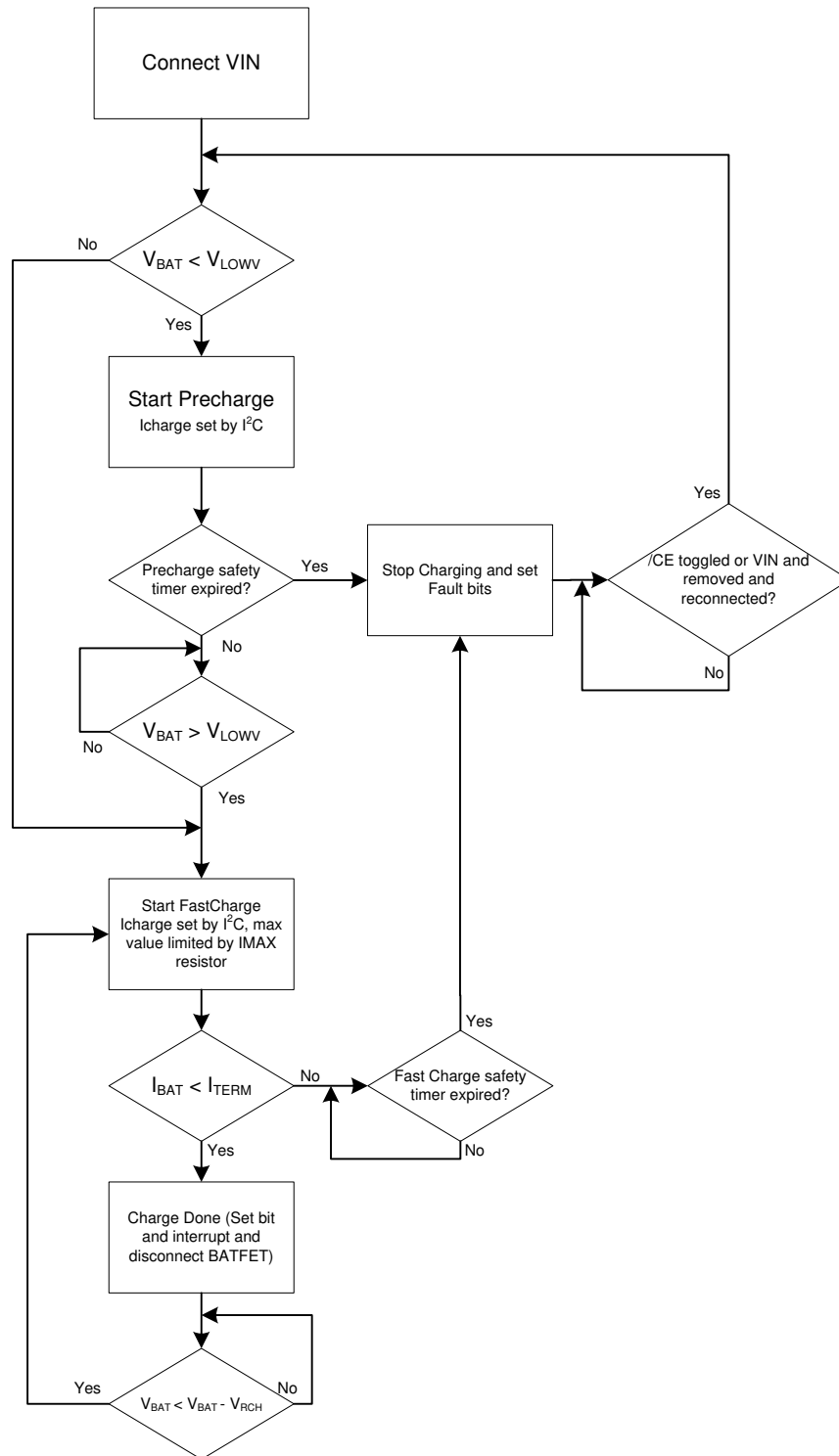


图 9-1. BQ25150 Charger Flow Diagram

When a valid input source is connected ($V_{IN} > V_{UVLO}$ and $V_{BAT} + V_{SLP} < V_{IN} < V_{OVP}$), the state of the \overline{CE} pin determines whether a charge cycle is initiated. When the \overline{CE} input is high and a valid input source is connected, the battery charge FET is turned off, preventing any kind of charging of the battery. A charge cycle is initiated when the CHARGE_DISABLE bit is written to 0 and \overline{CE} pin in low. 表 9-1 shows the \overline{CE} pin and bit priority to enable/disable charging.

表 9-1. Charge Enable Function Through $\overline{\text{CE}}$ Pin and $\overline{\text{CE}}$ Bit

/CE PIN	CHARGE_DISABLE BIT	CHARGING
0	0	Enabled
0	1	Disabled
1	0	Disabled
1	1	Disabled

The following figure shows a typical charge cycle.

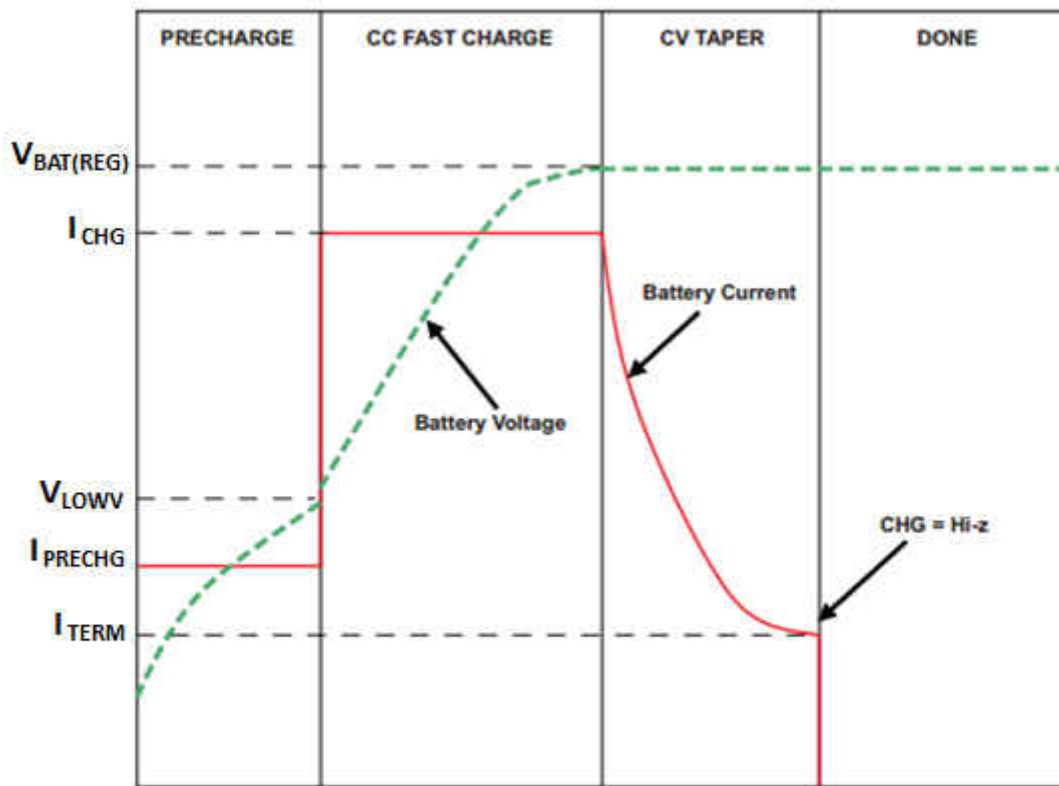


図 9-2. BQ25150 Typical Charge Cycle

9.3.1.1.1 Pre-Charge

In order to prevent damage to the battery, the device will charge the battery at a much lower current level when the battery voltage (V_{BAT}) is below the V_{LOWV} level. The pre-charge current ($I_{\text{PRECHARGE}}$) can be programmed through $I^2\text{C}$. Once the battery voltage reaches V_{LOWV} , the charger will then operate in Fast Charge Mode, charging the battery at I_{CHARGE} .

During pre-charge, the safety timer is set to 25% of the safety timer value during fast charge.

9.3.1.1.2 Fast Charge

The charger has two main control loops that control charging when $V_{\text{BAT}} > V_{\text{LOWV}}$: the Constant Current (CC) and Constant Voltage (CV) loops. When the CC loop is dominant, typically when $V_{\text{BAT}} < V_{\text{BATREG}} - 50 \text{ mV}$, the battery is charged at the maximum charge current level I_{CHARGE} , unless there is a TS fault condition (JEITA operation), VINDPM is active, DPPM is active, or thermal charge current foldback is active. (See respective sections for details on these modes of operation). Once the battery voltage approaches the V_{BATREG} level, the

CV loop becomes more dominant and the charging current starts tapering off as shown in [Figure 9-2](#). Once the charging current reaches the termination current (I_{TERM}) charging is stopped.

The maximum fast charge current is limited by the IMAX resistor setting, even if a higher I^2C value is programmed. See [Section 9.3.2.6](#) for details on IMAX function.

9.3.1.1.3 Pre-Charge to Fast Charge Transitions and Charge Current Ramping

Whenever a change in the charge current setting is triggered, whether it occurs due to I^2C programming by the host, Pre-Charge/Fast Charge transition or JEITA TS control, the device will temporarily disable charging (for ~ 1 ms) before updating the charge current value.

9.3.1.1.4 Termination

The device will automatically terminate charging once the charge current reaches I_{TERM} , which is programmable through I^2C .

After termination the charger will operate in high impedance mode, disabling the BATFET to disconnect the battery. Power is provided to the system (PMID) by IN supply as long and $V_{IN} > V_{UVLO}$ and $V_{BAT} + V_{SLP} < V_{IN} < V_{OVP}$.

Termination is only enabled when the charger CV loop is active in fast charge operation. No termination will occur if the charge current reaches I_{TERM} while VINDPM or DPPM is active as well as the thermal regulation loop. Termination is also disabled when operating in the TS WARM region. The charger only goes to termination when the current drops to I_{TERM} due to the battery reaching the target voltage and not due to the charge current limitation imposed by the previously mentioned control loops.

9.3.1.2 JEITA and Battery Temperature Dependent Charging

The charger can be configured through I^2C setting to provide JEITA support, automatically reducing the charging current and voltage depending on the battery temperature as monitored by an NTC thermistor connected to the BQ25150 TS pin. See [Section 9.3.11](#) for details.

9.3.1.3 Input Voltage Based Dynamic Power Management (VINDPM) and Dynamic Power Path Management (DPPM)

The VINDPM loop prevents the input voltage from collapsing to a point where charging would be interrupted by reducing the current drawn by charger in order to keep V_{IN} from dropping below V_{IN_DPM} . Once the IN voltage drops to V_{IN_DPM} , the VINDPM loops will reduce the input current through the blocking FETs, to prevent the further drop of the supply voltage. The VINDPM function is enabled by default and may be disabled through I^2C command. The V_{IN_DPM} threshold is programmable through the I^2C register from 4.2 V to 4.9 V in 100-mV steps.

On the other hand, the DPPM loop prevents the system output (PMID) from dropping below $V_{BAT} + 200mV$ when the sum of the charge current and system load exceeds the BQ21061 input current limit setting. If PMID drops below the DPPM voltage threshold, the charging current is reduced. If PMID continues to drop after BATFET charging current is reduced to zero, the part will enter supplement mode when PMID falls below the supplement mode threshold ($V_{BAT} - V_{BSUP1}$). Note that DPPM function is disabled when PMID regulation is set to battery tracking.

When the device enters these modes, the charge current may be lower than the set value and the corresponding status bits and flags are set. If the 2X timer is set, the safety timer is extended while the loops are active. Additionally, termination is disabled.

9.3.1.4 Battery Supplement Mode

While in DPPM mode, if the charging current falls to zero and the system load current increases beyond the programmed input current limit, the voltage at PMID reduces further. When the PMID voltage drops below the battery voltage by V_{BSUP1} , the battery supplements the system load. The battery stops supplementing the system load when the voltage on the PMID pin rises above the battery voltage by V_{BSUP2} . During supplement mode, the battery supplement current is not regulated, however, the Battery Over-Current Protection mechanism is active. Battery charge termination is disabled while in supplement mode.

9.3.2 Protection Mechanisms

9.3.2.1 Input Over-Voltage Protection

The input over-voltage protection protects the device and downstream components connected to PMID, and BAT against damage from over-voltage on the input supply. When $V_{IN} > V_{OVP}$ an OVP fault is determined to exist. During the OVP fault, the device turns the input FET off, sends a single 128-μs pulse on \overline{INT} , and the VIN_OVP_FAULT FLAG and STAT bits are updated over I²C. Once the OVP fault is removed, the STAT bit is cleared and the device returns to normal operation. The FLAG bit is not cleared until it is read through I²C after the OVP condition no longer exists. The OVP threshold for the device is 5.5 V to allow operation from standard USB sources.

9.3.2.2 Safety Timer and I²C Watchdog Timer

At the beginning of the charge cycle, the device starts the safety timer. If charging has not terminated before the programmed safety time, t_{MAXCHG} , expires, charging is disabled. The pre-charge safety time, t_{PRECHG} , is 25% of t_{MAXCHG} . When a safety timer fault occurs, a single 128-μs pulse is sent on the \overline{INT} pin and the SAFETY_TMR_FAULT_FLAG bit in the FLAG3 register is updated over I²C. The \overline{CE} pin or input power must be toggled in order to reset the safety timer and exit the fault condition. Note that the flag bit will be reset when the bit is read by the host even if the fault has not been cleared. The safety timer duration is programmable using the SAFETY_TIMER bits. When the safety timer is active, changing the safety timer duration resets the safety timer. The device also contains a 2X_TIMER bit that doubles the timer duration to prevent premature safety timer expiration when the charge current is reduced by a high load on PMID (DPPM operation), VIN DPM, thermal regulation, or a NTC (JEITA) condition. When 2X_TIMER function is enabled, the timer is allowed to run at half speed when any loop is active other than CC or CV.

In addition to the safety timer, the device contains a 50-second I²C watchdog timer that monitors the host through the I²C interface. The watchdog timer is enabled by default and may be disabled by the host through I²C. Once the watchdog timer is enabled, the watchdog timer is started. The watchdog timer is reset by any transaction by the host using the I²C interface. If the watchdog timer expires without a reset from the I²C interface, all charger parameters registers (ICHARGE, IPRECHARGE, ITERM, VLOWV, etc) are reset to the default values.

9.3.2.3 Thermal Protection and Thermal Charge Current Foldback

During operation, to protect the device from damage due to overheating, the junction temperature of the die, T_J , is monitored. When T_J reaches $T_{SHUTDOWN}$ the device stops operation and is turned off. The device resumes operation when T_J falls below $T_{SHUTDOWN}$ by T_{HYS} .

During the charging process, to prevent overheating in the device, the device monitors the junction temperature of the die and reduces the charging current at a rate of $(0.04 \times I_{CHARGE})/^{\circ}\text{C}$ once T_J exceeds the thermal foldback threshold, T_{REG} . If the charge current is reduced to 0, the battery supplies the current needed to supply the PMID output. The thermal regulation threshold may be set through I²C by setting the THERM_REG bits to the desired value.

To ensure that the system power dissipation is under the limits of the device. The power dissipated by the device can be calculated using 式 1:

$$P_{DISS} = P_{PMID} + P_{LS/LDO} + P_{BAT} \quad (1)$$

Where:

$$P_{PMID} = (V_{IN} - V_{PMID}) \times I_{IN} \quad (2)$$

$$P_{LS/LDO} = (V_{INLS} - V_{LS/LDO}) \times I_{LS/LDO} \quad (3)$$

$$P_{BAT} = (V_{PMID} - V_{BAT}) \times I_{BAT} \quad (4)$$

The die junction temperature, T_J , can be estimated based on the expected board performance using the following equation:

$$T_J = T_A + \theta_{JA} \times P_{DISS} \quad (5)$$

The θ_{JA} is largely driven by the board layout. For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics Application Report](#). Under typical conditions, the time spent in this state is very short.

9.3.2.4 Battery Short and Over Current Protection

In order to protect the device from over current and prevent excessive battery discharge current, BQ25150 detects if the current on the battery FET exceeds I_{BAT_OCP} . If the short circuit limit is reached for the deglitch time (t_{DGL_OCP}), the battery discharge FET is turned off and start operating in hiccup mode, re-enabling the BATFET t_{REC_SC} (250 ms) after being turned off by the over-current condition. If the over-current condition is triggered upon retry for 3 to 7 consecutive times, the BATFET will then remain off until the part is reset or until V_{IN} is connected and valid. If the over-current condition and hiccup operation occurs while in supplement mode where V_{IN} is already present, V_{IN} must be toggled in order for BATFET to be enabled and start another detection cycle.

This process protects the internal FET from over current. During this event PMID will likely droop and cause the system to shut down. It is recommended that the host read the Faults Register after waking up to determine the cause of the event.

In the case where the battery is suddenly shorted while charging and V_{BAT} drops below V_{SHORT} , a fast comparator quickly reduces the charge current to $I_{PRECHARGE}$ preventing fast charge current to be momentarily injected to the battery while shorted.

9.3.2.5 PMID Short Circuit

A short on the PMID pin is detected when the PMID voltage drops below 1.6 V (PMID short threshold). PMID short threshold has a 200-mV hysteresis. When this occurs, the input FET temporarily disconnects IN for up to 200 μ s to prevent stress on the device if a sudden short condition happens, before allowing a softstart on the PMID output.

9.3.2.6 Maximum Allowable Charging Current (IMAX)

The device allows the system designer to limit the maximum programmable charge current through hardware by connecting a resistor to the IMAX pin. The value of this resistor will determine the maximum Fast Charge I^2C code that BQ25150 would let the host program to the device. Upon Power-On-Reset (POR) the ADC will measure the voltage at the IMAX pin, which is biased by a 80- μ A biasing current. This measurement is used to determine the R_{IMAX} value and the maximum charging current. Once the value is measured, the device determines the maximum allowable Fast Charge I^2C code and prevents the host from programming any value higher than that. If the host tries to program it to a higher value, the IMAX_ACTIVE flag will be set and the Fast Charge Current Register will reflect the maximum charge current setting instead of the value programmed by the host. Note that even though the pre-charge current is also limited by IMAX if set higher than the IMAX value, the IMAX_ACTIVE flag is not set as it is only asserted for fast charge. 式 6 shows the maximum ICHG_CTRL register value (decimal) for a given R_{IMAX} .

$$ICHRG_CTRL_{(CODE_IN_DECIMAL)} = \frac{2 \times R_{IMAX} \times 80\mu}{1.2} \times 2^8 \quad (6)$$

Note that the IMAX function has no effect on the charge current step size set by the ICHARGE_RANGE bit, so if R_{IMAX} is selected based on the fast charge current when ICHARGE_RANGE = 0 (1.25-mA step), changing the ICHARGE_RANGE bit to 1 will double the maximum allowable current. In case where the IMAX pin is left floating ($R_{IMAX} > 14\text{ K}\Omega$), the device will disable charging so that in the case the IMAX resistor connection is not done properly during manufacturing or breaks afterwards it prevents charging with a current above the desired IMAX level. If the measurement indicates that the IMAX pin is floating, the device repeats the measurement for a second time to confirm. If the floating pin measurement is confirmed then, charge is disabled permanently and the IMAX_FAULT flag is set. Note that a Power-On-Reset (POR) would be needed in order to repeat the IMAX measurement so both IN and BAT supplies must be removed before powering up the device again to update the IMAX state.

9.3.3 ADC

The device uses a 12-bit effective ADC to report information on the input voltage, input current, PMID voltage, battery voltage, battery charge current, and TS pin voltage of the device. It can also make measurements from an external source through the ADCIN pin.

The host may select the function desired, perform an ADC read, and then read the values in the ADC registers. The details for the register functions are in the [セクション 9.5](#).

9.3.3.1 ADC Operation in Active Battery Mode and Low Power Mode

When the device is powered by the battery it is imperative that power consumption is minimized in order to maximize battery life. In order to limit the number of ADC conversions, and hence power consumption, the ADC conversions when in Active Battery Mode may be limited to a period determined by the ADC_READ_RATE bits. On the case where the ADC_READ_RATE is set to Manual Mode, the host will have to set the ADC_CONV_START bit to initiate the ADC conversion. Once the ADC conversion is completed and the data is ready, the ADC_READY flag will be set and an interrupt will be sent to the host. In Low Power Mode the ADC remains OFF for minimal IC power consumption. The host will need to switch to Active Battery Mode (set \overline{LP} high) before performing an ADC measurement.

9.3.3.2 ADC Operation When VIN Present

When VIN is present and VDD is powered from VIN, the ADC is constantly active, performing conversions continuously on all channels in a round-robin (each channel being converted once every ~225ms). The device will not send an interrupt after a conversion is complete since this would force the device to constantly send ADC_READY interrupts that would overwhelm the host. The host will be able to read the ADC results registers at any time. This is true even when $V_{IN} > V_{OVP}$.

9.3.3.3 ADC Measurements

[表 9-2](#) lists the ADC measurements done by the ADC.

表 9-2. ADC Measurement Channels

MEASUREMENT	FULL SCALE RANGE (ABSOLUTE MAX CODE)	FULL LINEAR RANGE (RECOMMENDED OPERATING RANGE)	FORMULA
VIN	6 V	2 V - 5 V	$V_{IN} = \frac{ADCDATA_VIN^{16bit}}{2^{16}} \times 6V$ (7)

表 9-2. ADC Measurement Channels (continued)

MEASUREMENT	FULL SCALE RANGE (ABSOLUTE MAX CODE)	FULL LINEAR RANGE (RECOMMENDED OPERATING RANGE)	FORMULA
PMID	6 V	2 V - 5 V	$V_{PMID} = \frac{ADCDATA_PMID^{16bit}}{2^{16}} \times 6V$ (8)
IIN	750 mA	0 - 600 mA	<p>For ILIM ≤ 150mA:</p> $I_{IN} = \frac{ADCDATA_IIN^{16bit}}{2^{16}} \times 375mA$ (9) <p>For ILIM > 150mA:</p> $I_{IN} = \frac{ADCDATA_IIN^{16bit}}{2^{16}} \times 750mA$ (10) <p>Note: IIN reading only valid when $V_{IN} > V_{UVLO}$ and $V_{IN} < V_{OVP}$</p>
VBAT	6 V	2 V - 5 V	$VBAT = \frac{ADCDATA_VBAT^{16bit}}{2^{16}} \times 6V$ (11)
TS	1.2 V	0 - 1 V	$V_{TS} = \frac{ADCDATA_TS^{16bit}}{2^{16}} \times 1.2V$ (12)
ADCIN	1.2 V	0 - 1 V	$V_{ADCIN} = \frac{ADCDATA_ADCIN^{16bit}}{2^{16}} \times 1.2V$ (13)
% ICHARGE	-	-	$\%I_{CHARGE} = \frac{ADCDATA_ICHG^{16bit}}{0.8 \times 2^{16}} \times 100$ (14) <p>where I_{CHARGE} is the fast charge current set by ICHG_CTRL register and ICHARGE_RANGE bit. Note that if the device is in pre-charge or in the TS COLD region, ICHARGE will be the current set by the IPRECHRG and TS_ICHRG bits respectively.</p>

9.3.3.4 ADC Programmable Comparators

The BQ25150 has three programmable ADC comparators that may be used to monitor any of the ADC channels. The comparators will send an interrupt whenever the ADC measurement the comparator is monitoring crosses the thresholds programmed in their respective ADC_ALARM_COMPx registers in the direction indicated by the x_ADCALARM_ABOVE bit. The comparators are only 12 bit compared to the 16 bits reported by the ADC, so only the first 12 bits of the ADC measurements are used to make the comparison. Note that the interrupts are masked by default and must be unmasked by the host to use this function.

When configuring the ADC comparators, it is recommended to first disable the comparator through the ADCCTRLx registers and allow the ADC to complete a measurement on the desired channel before enabling or reconfiguring the comparator by setting the ADC_COMPx_2:0 bits to the desired channel. This would prevent the comparator from sending an interrupt based on an outdated ADC reading when the comparator is enabled or reconfigured, especially in battery only operation where the ADC is not continuously performing measurements in all the channels.

ADC_COMP1 may be used to monitor critical conditions that need continuous and autonomous monitoring after a condition is detected. This comparator will force continuous ADC readings when the condition the ADC comparator is detecting is true regardless of ADC_READ_RATE setting until the condition is no longer present.

Note that the continuous ADC reading will cause an increase in quiescent current, so it is recommended to disable ADC_COMP1 by setting the ADC_COMP1 bits to 000 if this function is not to be used.

9.3.4 VDD LDO

The device integrates a low current always on LDO that serves as the digital I/O supply to the device. This LDO is supplied by VIN or by BAT. The end user may be able to draw up to 10 mA of current through the VDD pin to power a status LED or provide an IO supply. The VDD LDO will remain on through all power states with the exception of Ship Mode.

9.3.5 Load Switch / LDO Output and Control

The device integrates a low Iq load switch which can also be used as a regulated output. The LDO/LS has a dedicated input pin VINLS and can support up to 150 mA of load current.

The LS/LDO may be enabled/disabled through I²C. To limit voltage drop or voltage transients, a small ceramic capacitor must be placed close to VINLS pin.

The output voltage can be dynamically programmed using the LS_LDO bits in the registers. The LS/LDO voltage is calculated using the following equation: $V_{LSLDO} = 0.6 \text{ V} + \text{LS_LDOCODE} \times 100 \text{ mV}$ up to 3.7 V. All higher codes will set the output to 3.7 V.

表 9-3. LDO Mode Control

I2C EN_LS_LDO	LS_CONFIG	LS/LDO OUTPUT
0	0	Pulldown
0	1	Pulldown
1	0	LDO
1	1	Load Switch

The current capability of the LDO will depend on the VINLS input voltage and the programmed output voltage. When the LS/LDO output is disabled through the register, an internal pull-down will discharge the output.

The LDO has output current limit protection, limiting the output current in the event of a short in the output. When the LDO output current limit trips and is active for at least 1ms, the device will set a flag and send an interrupt to the host. The LDO may be set to operate as a load switch by setting the LS_SWITCH_CONFIG bit. Note that in order to change the configuration between load switch and LDO, the LDO must be disabled first, then the LS_SWITCH_CONFIG bit is set for it to take effect. This is not the case when updating the LDO output voltage which can be done on the fly without the need of disabling the LDO first.

9.3.6 PMID Power Control

BQ25150 offers the option to control PMID through the I²C PMID_MODE bits. These bits can force PMID to be supplied by BAT instead of IN, even if $V_{IN} > V_{BAT} + V_{SLP}$. They can also disconnect PMID, pulling it down or leaving it floating. 表 9-4 shows the expected device behavior based on PMID_MODE setting.

表 9-4. PMID_MODE Control

PMID_MODE	DESCRIPTION	PMID SUPPLY	PMID PULL-DOWN
00	Normal Operation	IN or BAT	Off
01	Force BAT Power	BAT	Off
10	PMID Off - Floating	None	Off
11	PMID Off - Pulled Down	None	On

PMID_MODE = 00

This is the default state/normal operation of the device. PMID will be powered from IN if VIN is valid or it will be powered by BAT. PMID will only be disconnected from IN or BAT and pulled down when a HW Reset occurs or the device goes into Ship Mode.

PMID_MODE = 01

When this configuration is set, PMID will be powered by BAT if $V_{BAT} > V_{BATUVLO}$ regardless of VIN or \overline{CE} state. This allows the host to minimize the current draw from the adapter while it is still connected to the system. If PMID_MODE = 01 is set while $V_{BAT} < V_{BATUVLO}$, the PMID_MODE = 01 setting will be ignored and the device will go to PMID_MODE = 00. If VBAT drops below VBATUVLO while PMID_MODE = 01 the device will automatically switch to PMID_MODE = 00. This prevents the device from needing a POR in order to restore power to the system and allow battery charging. If PMID_MODE = 01 is set during charging, charging will be stopped and the battery will start to provide power to PMID as needed.

PMID_MODE = 10

When this configuration is set, PMID will be disconnected from the supply (IN or BAT) and left floating. VDD and the digital remain on and active. The LDO will be disabled. When floating, PMID can only be forced to a voltage up to VBAT level. Note that this mode can only be exited through I²C or \overline{MR} HW Reset.

PMID_MODE = 11

When this configuration is set, PMID will be disconnected from the supply (IN or BAT) and pulled down to ground. VDD and the digital remain on and active. The LDO will be disabled. Note that this mode can only be exited through I²C or \overline{MR} HW Reset.

9.3.7 MR Wake and Reset Input

The \overline{MR} input has three main functions in BQ25150. First, it serves as a means to wake the device from Ship Mode. Second, it serves as a short button press detector, sending an interrupt to the host when the button driving the \overline{MR} pin has been pressed for a given period of time. This allows the implementation of different functions in the end application such as menu selection and control. And finally it serves as a means to get the BQ25150 to reset the system by performing a power cycle (shut down PMID and automatically powering it back on) or go to Ship Mode after detecting a long button press. The timing for the short and long button press duration is programmable through I²C for added flexibility and allow system designers to customize the end user experience of a specific application. Note that if a specific timer duration is changed through I²C while that timer is active and has not expired, the new programmed value will be ignored until the timer expires and/or is reset by \overline{MR} . The \overline{MR} input has an internal pull-up to BAT.

9.3.7.1 \overline{MR} Wake or Short Button Press Functions

There are two programmable wake or short button press timers, WAKE1 and WAKE2. When the \overline{MR} pin is held low for t_{WAKE1} the device sends an interrupt (128 μ s active low pulse in the \overline{INT} pin) and sets the MRWAKE1_TIMEOUT flag when it expires. If the \overline{MR} pin continues to be driven low after WAKE1 and the WAKE2 timer expires, the BQ25150 sends a second interrupt and sets the MRWAKE2_TIMEOUT flag. WAKE2 is used as the timer to wake the device from ship mode. WAKE1's only function is to send the interrupt and has no effect on other BQ25150 functions. These flags are not cleared until they have been read by the host. Note that interrupts are only sent when the flags are set and the flags must be cleared in order for another interrupt to be sent upon \overline{MR} press. The timer durations can be set through the MR_WAKEx_TIMER bits in the [MRCTRL Register](#).

One of the main \overline{MR} functions is to wake the device from Ship Mode when the \overline{MR} is asserted. The device will exit the Ship Mode when the \overline{MR} pin is held low for at least t_{WAKE2} . Immediately after the \overline{MR} is asserted, VDD will be enabled and the digital will start the WAKE counter. If the \overline{MR} signal remains low until after the WAKE2 timer expires, the device will power up PMID and LDO (If enabled) completing the exit from the ship mode. If the \overline{MR} signal goes high before the WAKE2 timer expires, the device will go back to the Ship Mode operation, never powering up PMID or the LDO. Note that if the \overline{MR} pin remains low after exiting Ship Mode the wake interrupts will not be sent and the long button press functions like HW reset will not occur until the \overline{MR} pin is toggled. In the case where a valid V_{IN} ($V_{IN} > V_{UVLO}$) is connected prior to WAKE2 timer expiring, the device will exit the ship mode immediately regardless of the \overline{MR} or wake timer state. [Figure 9-3](#) and [Figure 9-4](#) show these different scenarios.

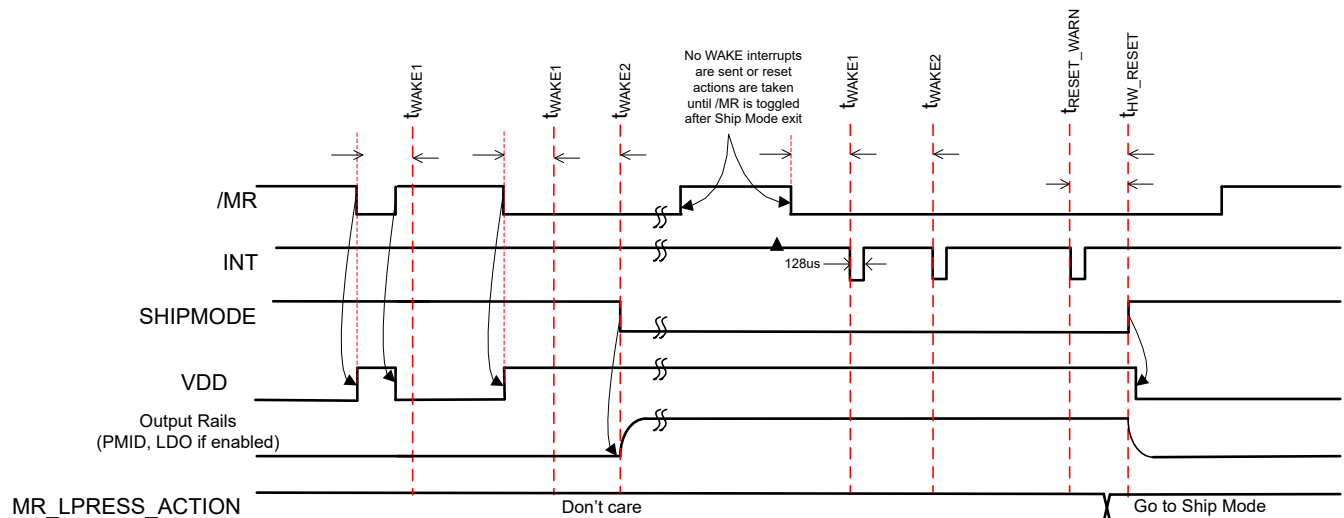


图 9-3. MR Wake From Ship Mode (MR_LPRESS_ACTION = Ship Mode, VIN not valid)

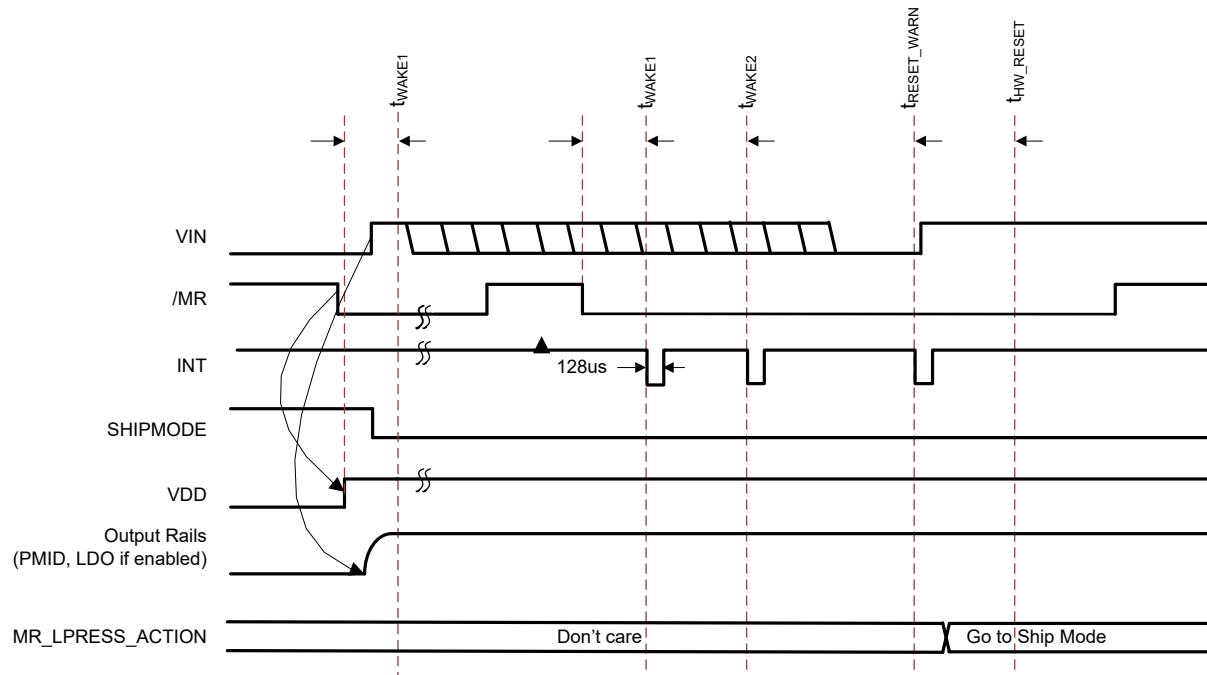


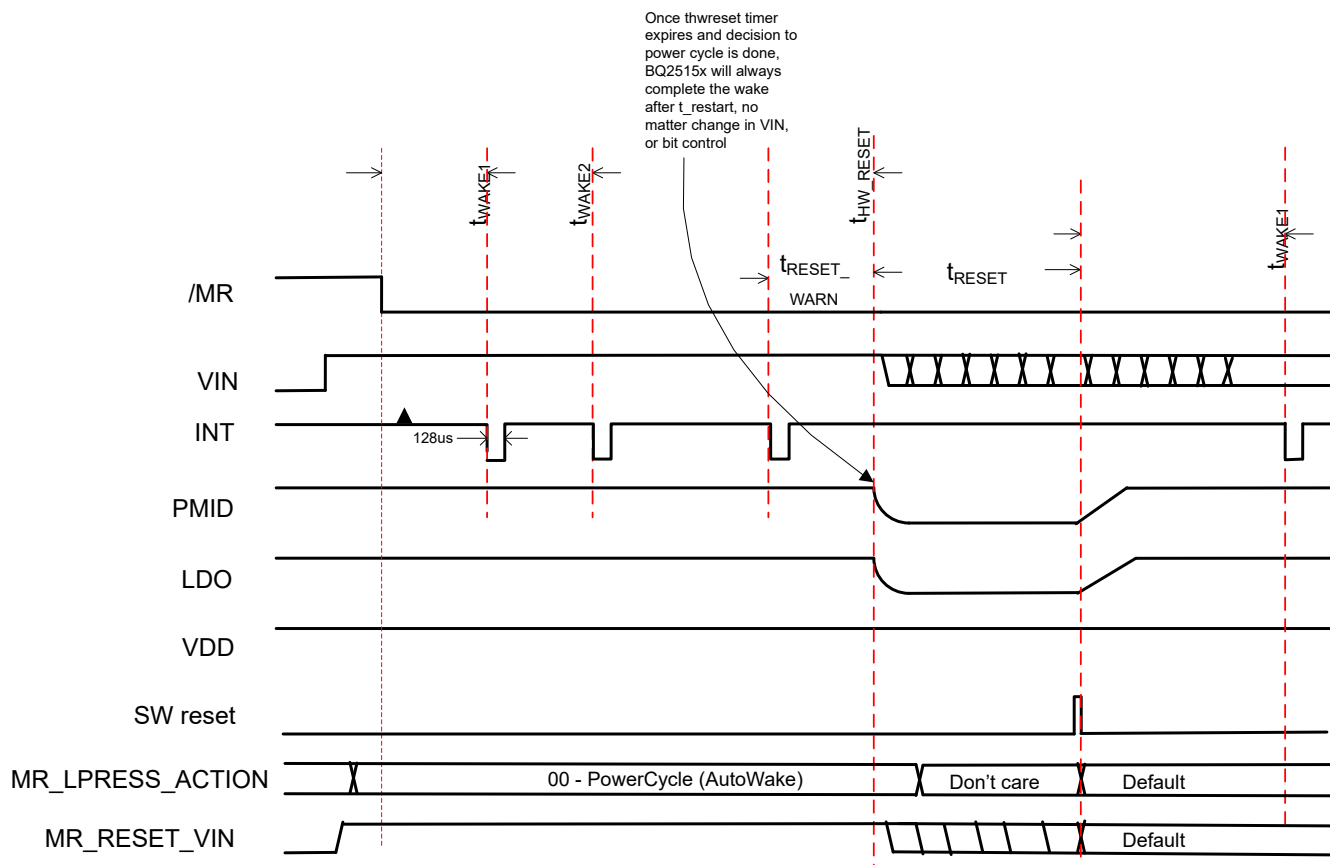
图 9-4. MR Wake From Ship Mode – VIN Dependencies

9.3.7.2 $\overline{\text{MR}}$ Reset or Long Button Press Functions

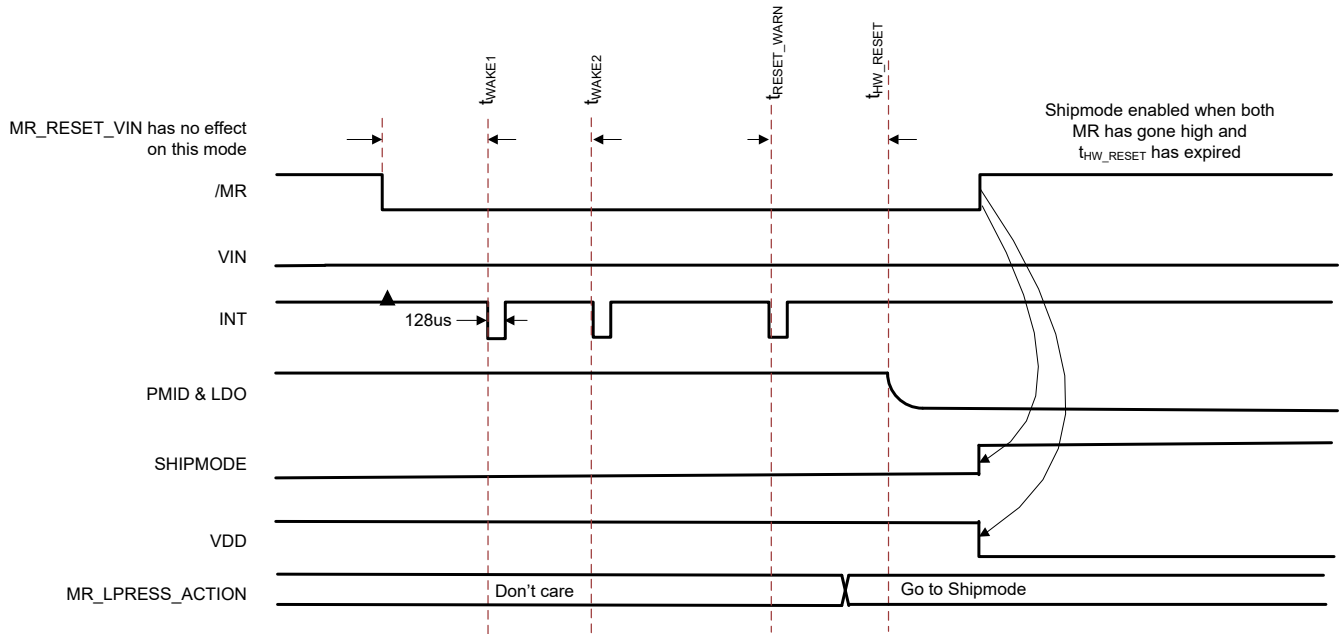
The BQ25150 device may be configured to perform a system hardware reset (Power Cycle/Autowake), go into Ship Mode, or simply do nothing after a long button press (for example, when the $\overline{\text{MR}}$ pin is driven low until the MR_HW_RESET timer expires). The action taken by the device when the timer expires is configured through the MR_LPRESS_ACTION bits in the [ICCTRL1 Register](#). Once the MR_HW_RESET timer expires the device immediately performs the operation set by the MR_LPRESS_ACTION bits. The BQ25150 sends an interrupt to the host when the device detects that $\overline{\text{MR}}$ has been pressed for a period that is within $t_{\text{RESET_WARN}}$ from reaching $t_{\text{HW_RESET}}$. This may warn the host that the button has been pressed for a period close to $t_{\text{HW_RESET}}$ which would trigger a HW Reset or used as another button press timer interrupt like the WAKE1 and WAKE2 timers. This interrupt is sent before the MR_HW_RESET timer expires and sets the MRRESET_WARN flag. The $t_{\text{RESET_WARN}}$ may be set through I²C by the MR_RESET_WARN bits in the MRCTRL register. The host may

change the reset behavior at any time after $\overline{\text{MR}}$ going low and prior to the MR_HW_RESET timer expiring. It may not change it however from another behavior to a HW reset (Power Cycle/Autowake) since a HW reset can be gated by other condition requirements, such as valid VIN presence (controlled by MR_RESET_VIN bit), throughout the whole duration of the button press. This flexibility allows the host to abort any reset or power shutdown to the system by overriding a long button press command.

A HW reset may also be started by setting the HW_RESET bit. Note that during a HW reset, VDD remains on.



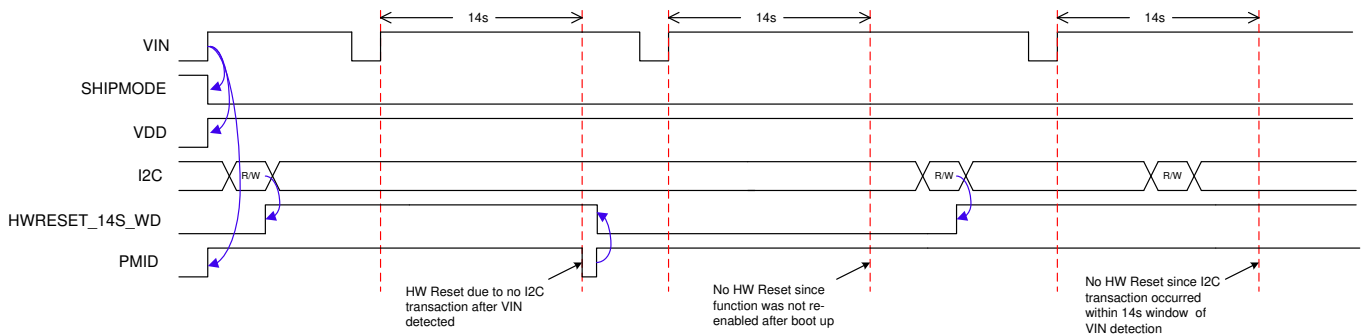
9-5. MR Wake and Reset Timing with VIN Present or BAT Active Mode When MR_LPRESS_ACTION = 00



9-6. MR Wake and Reset Timing Active Mode When MR_LPRESS_ACTION = 1x (Ship Mode) and Only BAT is Present

9.3.8 14-Second Watchdog for HW Reset

The BQ25150 integrates 14-second watchdog timer makes the BQ25150 to perform a HW reset/power cycle if no I²C transaction is detected within 14 seconds of a valid adapter being connected. If the adapter is connected and the host responds with an I²C transaction before the 14-second watchdog window expires, the part continues in normal operation. The 14-second watchdog is disabled by default may be enabled through I²C by setting the HWRESET_14S_WD bit. 9-7 shows the basic functionality of this feature.



9-7. 14-Second Watchdog for HW Reset Behavior

9.3.9 Faults Conditions and Interrupts (INT)

The device contains an open-drain output that signals an interrupt and is valid only after the device has completed start-up into a valid state. If the part starts into a fault, interrupts will not be sent. The INT pin is normally in high impedance and is pulled low for 128 μ s when an interrupt condition occurs. When a fault or status change occurs or any other condition that generates an interrupt such as ADC DATA READY, a 128- μ s pulse (interrupt) is sent on INT to notify the host. All interrupts may be masked through I²C. If the interrupt condition occurs while the interrupt is masked an interrupt pulse will not be sent. If the interrupt is unmasked while the fault condition is still present, an interrupt pulse will not be sent until the INT trigger condition occurs while unmasked.

9.3.9.1 Flags and Fault Condition Response

表 9-5 details the BQ25150 behavior when a fault conditions occurs.

表 9-5. Interrupt Triggers and Fault Condition Response

FAULT / FLAG	DESCRIPTION	INTERRUPT TRIGGER BASED ON STATUS BIT CHANGE	CHARGER BEHAVIOR	CHARGER SAFETY TIMER	LS/LDO BEHAVIOR	PMID BEHAVIOR	NOTES
CHRG_CV_FLAG	Set when charger enters Constant Voltage operation	Rising Edge	Enabled	No effect	N/A	IN powered if V_{IN} is valid	
CHARGE_DONE_FLAG	Set when charger reaches termination	Rising Edge	Paused-Charging resumes with V_{IN} or \overline{CE} toggle or when V_{RCH} is reached	Reset	N/A	IN powered if V_{IN} is valid	
IINLIM_ACTIVE_FLAG	Set when Input Current Limit loop is active	Rising Edge	Enabled. Reduced charge current.	Doubled if option is enabled	N/A	IN powered V_{IN} powered unless supplement mode condition is met.	
VDPPM_ACTIVE_FLAG	Set when DPPM loop is active	Rising Edge	Enabled. Reduced charge current.	Doubled if option is enabled	N/A	V_{IN} powered unless supplement mode condition is met.	
VINDPM_ACTIVE_FLAG	Set when VINDPM loop is active	Rising Edge	Enabled. Reduced charge current.	Doubled if option is enabled	N/A	V_{IN} powered unless supplement mode condition is met.	
THERMREG_ACTIVE	Set when Thermal Charge Current Foldback (Thermal Regulation) loop is active	Rising Edge	Enabled. Reduced charge current.	Doubled if option is enabled	N/A	V_{IN} powered unless supplement mode condition is met.	
VIN_PGOOD_FLAG	Set when V_{IN} changes PGOOD status	Rising and Falling Edge	If VIN_PGOOD_STAT is low, charging is disabled.	Reset	N/A	V_{IN} powered (if $VIN_PGOOD_STAT=1$) unless $PMID_MODE$ is not 00.	Interrupt will not be sent if device powers up with VIN_PGOOD condition and $V_{BAT} < V_{BATUVLO}$
VIN_OVP_FAULT_FLAG	Set when $V_{IN} > V_{OVP}$	Rising Edge	Charging is paused until condition disappears	Reset	N/A	BAT powered	
BAT_OCP_FAULT_FLAG	Set when $I_{BAT} > I_{BATOC}$	Rising Edge	Disabled (BAT only condition)	N/A	N/A	Disconnect BAT	
BAT_UVLO_FAULT_FLAG	Set when $V_{BAT} < V_{BATUVLO}$	Rising Edge	Enabled	No effect	N/A	IN powered if V_{IN} is valid	
TS_COLD_FLAG	Set when $V_{TS} > V_{TS_COLD}$	Rising Edge	Charging paused until condition is cleared	Paused	N/A	IN powered if V_{IN} is valid	
TS_COOL_FLAG	Set when $V_{TS_COLD} > V_{TS} > V_{TS_COOL}$	Rising Edge	Enabled. Reduced charge current.	Doubled if option is enabled	N/A	IN powered if V_{IN} is valid	

表 9-5. Interrupt Triggers and Fault Condition Response (continued)

FAULT / FLAG	DESCRIPTION	INTERRUPT TRIGGER BASED ON STATUS BIT CHANGE	CHARGER BEHAVIOR	CHARGER SAFETY TIMER	LS/LDO BEHAVIOR	PMID BEHAVIOR	NOTES
TS_WARM_FLAG	Set when $V_{TS_HOT} < V_{TS} < V_{TS_WARM}$	Rising Edge	Enabled. Reduce battery regulation voltage.	No effect	N/A	IN powered of V_{IN} is valid	
TS_HOT_FLAG	Set when $V_{TS} < V_{HOT}$	Rising Edge	Charging paused until condition is cleared	Paused	N/A	IN powered of V_{IN} is valid	
ADC_READY_FLAG	Set when ADC conversion is completed	Rising Edge	N/A	N/A	N/A	N/A	
COMP1_ALARM_FLAG	Set when ADC measurement meets programmed condition	Rising Edge	N/A	N/A	N/A	N/A	
COMP2_ALARM_FLAG	Set when ADC measurement meets programmed condition	Rising Edge	N/A	N/A	N/A	N/A	
COMP3_ALARM_FLAG	Set when ADC measurement meets programmed condition	Rising Edge	N/A	N/A	N/A	N/A	
IMAX_ACTIVE_FLAG	Set when charge current is programmed above the IMAX setting	Rising Edge	Enabled	N/A	N/A	N/A	
TS_OPEN_FLAG	Set when $V_{TS} > V_{TS_OPEN}$	Rising Edge	Charging is paused until condition disappears	Paused	N/A	N/A	
WD_FAULT_FLAG	Set when I ² C watchdog timer expires	Rising Edge	Enabled	N/A	N/A	N/A	
SAFETY_TMR_FAULT_FLAG	Set when safety Timer expires. Cleared after V_{IN} or \overline{CE} toggle	Rising Edge	Disabled until V_{IN} or \overline{CE} toggle	Reset after flag is cleared	N/A	IN powered of V_{IN} is valid	
LS_LDO_OCP_FAULT_FLAG	Set when LDO output current exceeds OCP condition	Rising Edge	N/A	N/A	Enabled (host must take action to disable the LDO if desired)	N/A	
IMAX_FAULT_FLAG	Set when an open is detected on IMAX pin	Rising Edge	Chareg disabled until Power-On-Reset	N/A	N/A	N/A	
MRWAKE1_TIME_OUT_FLAG	Set when \overline{MR} is low for at least t_{WAKE1}	Rising Edge	N/A	N/A	N/A	N/A	
MRWAKE2_TIME_OUT_FLAG	Set when \overline{MR} is low for at least t_{WAKE2}	Rising Edge	N/A	N/A	N/A	N/A	

表 9-5. Interrupt Triggers and Fault Condition Response (continued)

FAULT / FLAG	DESCRIPTION	INTERRUPT TRIGGER BASED ON STATUS BIT CHANGE	CHARGER BEHAVIOR	CHARGER SAFETY TIMER	LS/LDO BEHAVIOR	PMID BEHAVIOR	NOTES
MRRESET_WAR N_FLAG	Set when MR is low for at least $t_{RESETWARN}$	Rising Edge	N/A	N/A	N/A	N/A	
TSHUT	No flag. Die temperature exceeds thermal shutdown threshold is reached	N/A	Disabled	Disabled	Disabled	Disabled	

9.3.10 Power Good (\overline{PG}) Pin

The \overline{PG} pin is an open-drain output that by default indicates when a valid IN supply is present. It may also be configured to be a general purpose output (GPO) controlled through I²C or to be a level shifted version of the \overline{MR} input signal. Connect \overline{PG} to the desired logic voltage rail using a 1-k Ω to 100-k Ω resistor, or use with an LED for visual indication. Below is the description for each configuration:

- In its default state, \overline{PG} pulls to GND when the following conditions are met: $V_{IN} > V_{UVLO}$, $V_{IN} > V_{BAT} + V_{SLP}$ and $V_{IN} < V_{IN_OVP}$. \overline{PG} is high impedance when the input power is not within specified limits.
- \overline{MR} shifted (MRS) output when the PG_MODE bits are set to 01. \overline{PG} is high impedance when the \overline{MR} input is high, and \overline{PG} pulls to GND when the \overline{MR} input is low.
- General purpose open drain output when setting the PG_MODE bits to 1x. The state of the \overline{PG} pin is then controlled through the GPO_PG bit, where if GPO_PG is 0, the \overline{PG} pin is pulled to GND and if it is 1, the \overline{PG} pin is in high impedance.

9.3.11 External NTC Monitoring (TS)

The I²C interface allows the user to easily implement the JEITA standard for systems where the battery pack thermistor is monitored by the host. Additionally, the device provides a flexible voltage based TS input for monitoring the battery pack NTC thermistor. The NTC resistor is biased by the device with I_{TS_BIAS} and the resulting voltage at TS is monitored to determine that the battery is at a safe temperature during charging. The TS pin is not biased continuously, instead it is biased only when the voltage at the pin is sampled for about 25ms in 225ms intervals when VIN is present. Note that the TS biasing cannot be disabled when VIN is present.

The part can be configured to meet JEITA requirements or a simpler HOT/COLD function only. Additionally, the TS charger control function can be disabled. To satisfy the JEITA requirements, four temperature thresholds are monitored: the cold battery threshold, the cool battery threshold, the warm battery threshold, and the hot battery threshold. These temperatures correspond to the V_{COLD} , V_{COOL} , V_{WARM} , and V_{HOT} thresholds in the Electrical Characteristics table. Charging and safety timers are suspended when $V_{TS} < V_{HOT}$ or $V_{TS} > V_{COLD}$. When $V_{COOL} < V_{TS} < V_{COLD}$, the charging current is reduced to the value programmed in the [TS_FASTCHGCTRL](#) register. Note that the current steps for fast charge in the COOL region, just as those in normal fast charge, are multiples of the fast charge LSB value (1.25 mA by default). So in the case where the calculated scaled down current for the COOL region falls in between charge current steps, the device will round down the charge current to the nearest step. For example, if the fast charge current is set for 15 mA ($ICHG = 1100$) and $TS_FASTCHARGE = 111$ ($0.125 \times ICHG$), the charge current in the COOL region will be 1.25 mA instead of the calculated 1.85 mA.

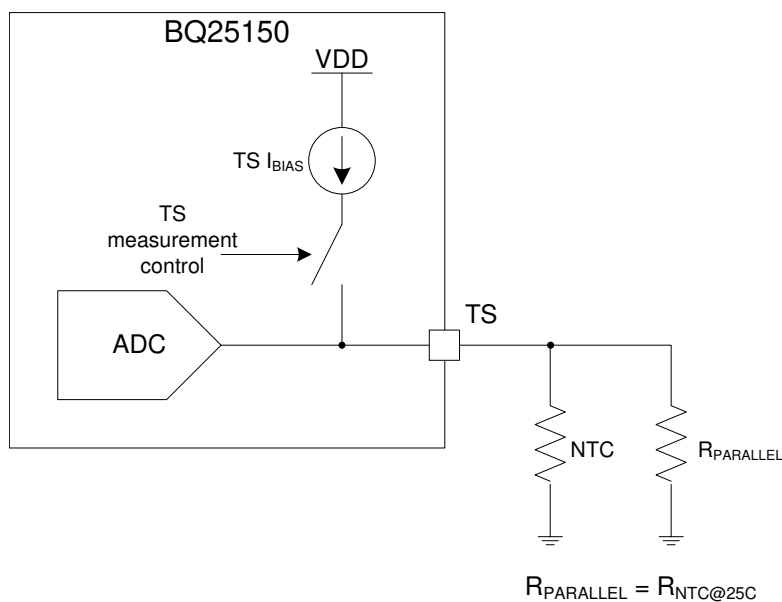
When $V_{HOT} < V_{TS} < V_{WARM}$, the battery regulation voltage is reduced to the value programmed in the [TS_FASTCHGCTRL](#) register.

Regardless of whether the part is configured for JEITA, HOT/COLD, or disabled, when a TS fault occurs, a 128- μ s pulse is sent on the INT output, and the FAULT bits of the register are updated over I²C. The FAULT bits are not cleared until they are read over I²C. This allows the host processor to take action if a different behavior than the pre-set function is needed. Alternately, the TS pin voltage can be read by the host if VIN is present or when BAT is present, so the appropriate action can be taken by the host.

9.3.11.1 TS Thresholds

The BQ25150 monitors the TS voltage and sends an interrupt to the host whenever it crosses the V_{HOT} , V_{WARM} , V_{COOL} and V_{COLD} thresholds which correspond to different temperature thresholds based on the NTC resistance and biasing. These thresholds may be adjusted through I²C by the host. The device will also disable charging if TS pin exceeds the V_{TS_OPEN} threshold.

The TS biasing circuit is shown in 9-8. The ADC range is set to 1.2 V. Note that the respective V_{TS} and hence ADC reading for T_{COLD} (0°C), T_{COOL} (10°C), T_{WARM} (45°C) and T_{HOT} (60°C) changes for every NTC, therefore the threshold values may need to be adjusted through I²C based on the supported NTC type.



9-8. TS Bias Functional Diagram

The BQ25150 supports by default the following thresholds for a 10-KΩ NTC.

表 9-6. TS Thresholds for 10-KΩ Thermistor

THRESHOLD	TEMPERATURE (°C)	VTS (V)
Open	--	>0.9
Cold	0	0.585
Cool	10	0.514
Warm	45	0.265
Hot	60	0.185

For accurate temperature thresholds a 10-KΩ NTC with a 3380 B-constant should be used (Murata NCP03XH103F05RL for example) with a parallel 10-KΩ resistor. Each threshold can be programmed via I²C through the TS_COLD, TS_COOL, TS_WARM and TS_HOT registers. The value in the registers corresponds to the 8 MSBs in the TS ADC output code.

9.3.12 External NTC Monitoring (ADCIN)

The ADCIN pin can be configured through I²C to support NTC measurements without the need of an external biasing circuit. In this mode, the ADCIN pin is biased and monitored in the same manner as the TS pin. Measurement data can be read by selecting one of the ADC data slots to read the ADCIN.

9.3.13 I²C Interface

The BQ25150 device uses a fully compliant I²C interface to program and read control parameters, status bits, and so forth. I²C is a 2-wire serial interface developed by Philips Semiconductor (see I²C-Bus Specification, Version 2.1, January 2000). The bus consists of a data line (SDA) and a clock line (SCL) with pull-up structures. When the bus is idle, both SDA and SCL lines are pulled high. All the I²C compatible devices connect to the I²C bus through open drain I/O pins, SDA and SCL. A master device, usually a microcontroller or a digital signal processor, controls the bus. The master is responsible for generating the SCL signal and device addresses. The master also generates specific conditions that indicate the START and STOP of data transfer. A slave device receives and/or transmits data on the bus under control of the master device.

The BQ25150 works as a slave and supports the following data transfer modes, as defined in the I²C Bus Specification: standard mode (100 kbps) and fast mode (400 kbps). The interface adds flexibility to the battery charge solution, enabling most functions to be programmed to new values depending on the instantaneous application requirements.

Register contents remain intact as long as VBAT or VIN voltages remains above their respective UVLO levels.

The data transfer protocol for standard and fast modes is exactly the same; therefore, they are referred to as the F/S-mode in this document. The BQ25150 device 7-bit address is 0x6B (shifted 8-bit address is 0xD6).

9.3.13.1 F/S Mode Protocol

The master initiates data transfer by generating a start condition. The start condition is when a high-to-low transition occurs on the SDA line while SCL is high, as shown in [Figure 9-9](#). All I²C-compatible devices should recognize a start condition.

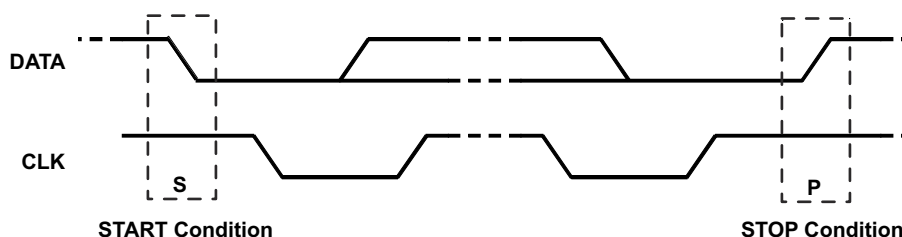


Figure 9-9. START and STOP Condition

The master then generates the SCL pulses, and transmits the 8-bit address and the read/write direction bit R/W on the SDA line. During all transmissions, the master ensures that data is valid. A valid data condition requires the SDA line to be stable during the entire high period of the clock pulse (see [Figure 9-10](#)). All devices recognize the address sent by the master and compare it to their internal fixed addresses. Only the slave device with a matching address generates an acknowledge (see [Figure 9-11](#)) by pulling the SDA line low during the entire high period of the ninth SCL cycle. Upon detecting this acknowledge, the master knows that communication link with a slave has been established.

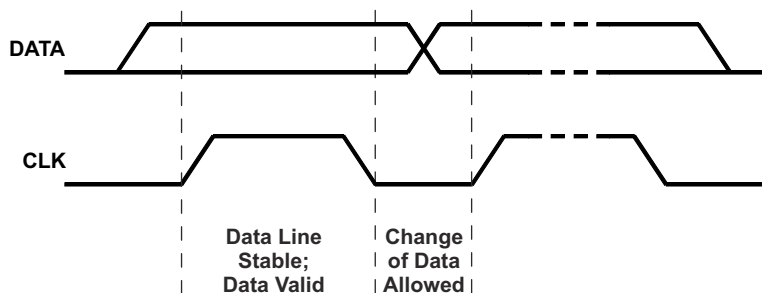


Figure 9-10. Bit Transfer on the Serial Interface

The master generates further SCL cycles to either transmit data to the slave (R/W bit 1) or receive data from the slave (R/W bit 0). In either case, the receiver needs to acknowledge the data sent by the transmitter. So an

acknowledge signal can either be generated by the master or by the slave, depending on which one is the receiver. The 9-bit valid data sequences consisting of 8-bit data and 1-bit acknowledge can continue as long as necessary. To signal the end of the data transfer, the master generates a stop condition by pulling the SDA line from low to high while the SCL line is high (see [Figure 9-9](#)). This releases the bus and stops the communication link with the addressed slave. All I²C compatible devices must recognize the stop condition. Upon the receipt of a stop condition, all devices know that the bus is released, and wait for a start condition followed by a matching address. If a transaction is terminated prematurely, the master needs to send a STOP condition to prevent the slave I²C logic from remaining in an incorrect state. Attempting to read data from register addresses not listed in this section will result in FFh being read out.

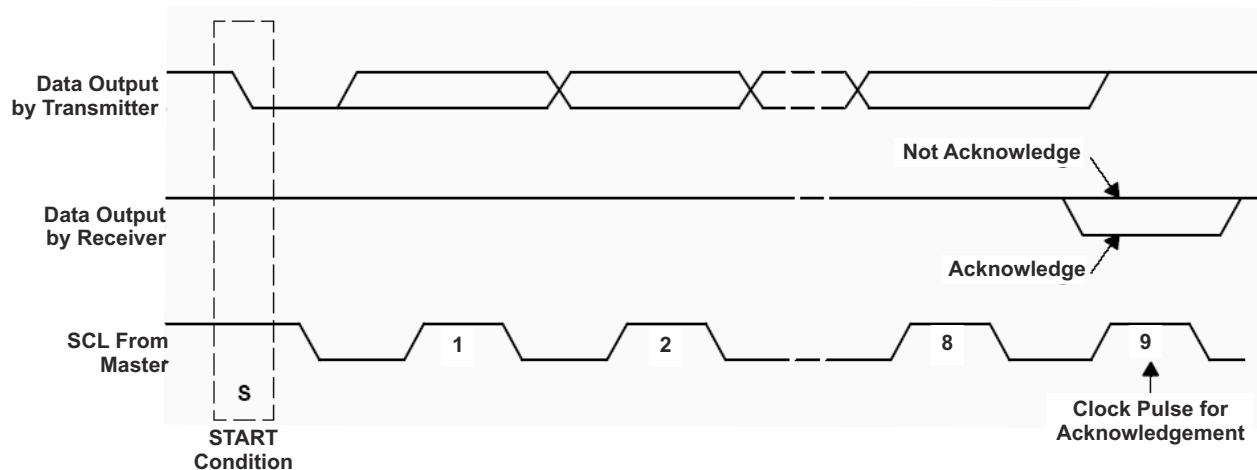


Figure 9-11. Acknowledge on the I²C Bus

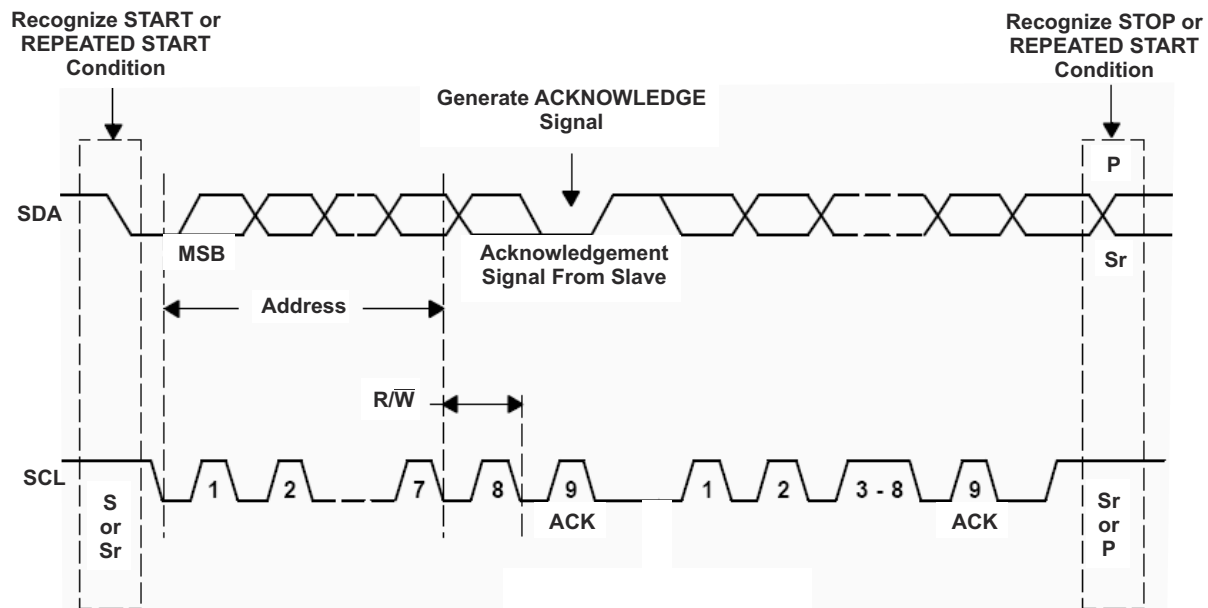


Figure 9-12. Bus Protocol

9.4 Device Functional Modes

The BQ25150 has four main modes of operation: Active Battery Mode, Low Power Mode and Ship Mode which are battery only modes and Charge/Adapter Mode when a supply is connected to IN. 表 9-7 summarizes the functions that are active for each operation mode. Each mode is discussed in further detail in the following sections in addition to the device's power-up/down sequences.

表 9-7. Function Availability Based on Primary Mode of Operation

FUNCTION	CHARGE/ ADAPTER MODE	SHIP MODE	LOW POWER MODE	ACTIVE BATTERY MODE
VOVP	Yes	No	Yes	Yes
VUVLO	Yes	Yes	Yes	Yes
BATOCP	Yes	No	No	Yes
BATUVLO	Yes	No	Yes	Yes
VINDPM	If enabled	No	No	No
DPPM	If enabled	No	No	No
VDD	Yes	No	Yes	Yes
LS/LDO	Yes	No	If enabled	If enabled
BATFET	Yes	No	Yes	Yes
TS Measurement	Yes	No	No	If enabled
Battery Changing	If enabled	No	No	No
ILIM	Yes (Register Value)	No	No	No
MR input	Yes	Yes	Yes	Yes
LP input	No	No	Yes	Yes
INT output	Yes	No	No	Yes
I ² C	Yes	No	No	Yes
CE input	Yes	No	No	No
ADC	Yes	No	No	Yes

9.4.1 Ship Mode

Ship Mode is the lowest quiescent current state for the device. Ship Mode latches off the device and BAT FET until $V_{IN} > V_{UVLO}$ or the MR button is depressed for t_{WAKE2} and released. Ship mode can be entered regardless of the state of CE. The device will also enter Ship Mode upon battery insertion when no valid VIN is present. If the EN_SHIPMODE is written to a 1 while a valid input supply is connected, the device will wait until the IN supply is removed to enter ship mode. If the MR pin is held low when the EN_SHIPMODE bit is set, the device will wait until the MR pin goes high before entering Ship Mode. shows this behavior. The battery voltage must be above the maximum programmable $V_{BATUVLO}$ threshold in order to exit Ship Mode with MR press. The EN_SHIPMODE bit can be cleared using the I²C interface while the VIN input is valid. The EN_SHIPMODE bit is not cleared upon the I²C watchdog expiring, this means that if watchdog timer fault occurs while the EN_SHIPMODE bit is set and the device is waiting to go into Ship Mode because V_{IN} is present or MR is low, the device will still proceed to go into Ship Mode once those conditions are cleared. The following list shows the functions that are active during Ship Mode:

- VIN_UVLO Comparator
- MR Input

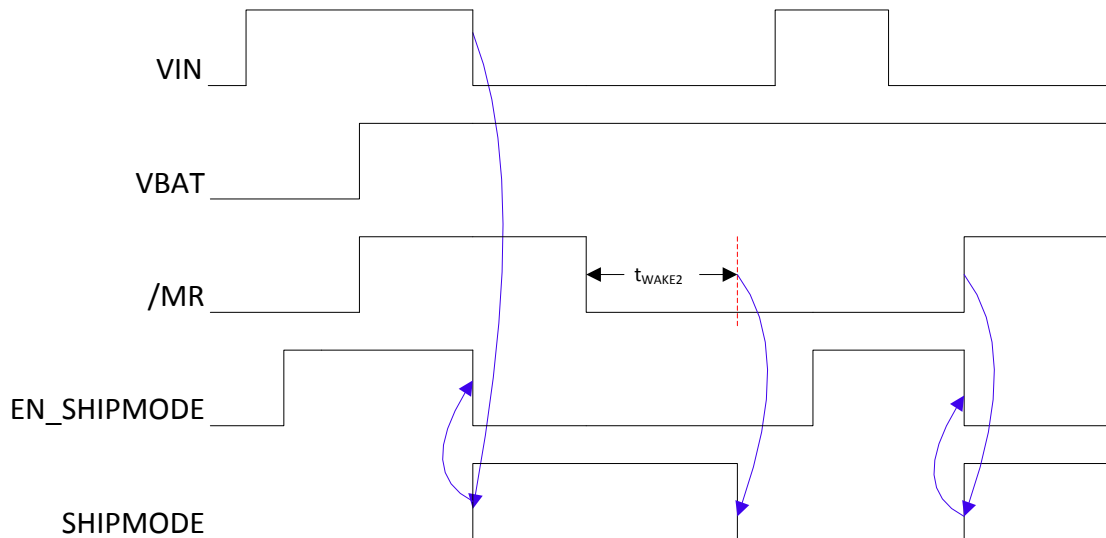


図 9-13. Ship Mode Entry Based on EN_SHIPMODE Bit

9.4.2 Low Power

Low Power mode is a low quiescent current state while operating from the battery. The device will operate in low power mode when the \overline{LP} pin is set low, $V_{IN} < V_{UVLO}$, \overline{MR} pin is high and all I²C transactions and interrupts that started while in the Active Battery or Charging Modes have been completed and sent. During LP mode the VDD output is powered by BAT, the \overline{MR} inputs are active and the I²C and ADC are disabled. All other circuits, such as oscillators, are in a low power or off state. The LS/LDO outputs will remain in the state set by the EN_LS_LDO bit prior to entering Low Power Mode. The device exits LP Mode when the \overline{LP} pin is set high or $V_{IN} > V_{UVLO}$.

In the case that a faulty adapter with $V_{IN} > V_{OVP}$ is connected to the device while \overline{LP} pin is low, the device will be powered from the battery, but will operate in Active battery mode instead of Low Power mode regardless of the \overline{LP} pin state.

When \overline{MR} is held low while \overline{LP} is low, the device will enter Active Battery Mode, this allows for the internal clocks of the device to be running and allow the \overline{MR} long button press HW reset. I²C operation is also possible during this condition. Note that as soon as the \overline{MR} input is released and goes high, the device will go back to LP Mode tuning off all clocks. Note that if a HW reset has occurred while \overline{LP} is low, \overline{MR} must remain low until the power cycle has completed (PMID and LDO enable) to allow completion of the power up sequence.

9.4.3 Active Battery

When the device is out of Ship Mode and battery is above $V_{BATUVLO}$ with no valid input source, the battery discharge FET is turned on connecting PMID to the battery. The current flowing from BAT to PMID is not regulated, but it is monitored by the battery over-current protection (OCP) circuitry. If the battery discharge current exceed the OCP threshold, the battery discharge FET will be turned off as detailed in セクション 9.3.2.4.

If only battery is connected and the battery voltage goes below $V_{BATUVLO}$, the battery discharge FET is turned off. To provide designers the most flexibility in optimizing their system, an adjustable BATUVLO is provided. Deeper discharge of the battery enables longer times between charging, but may shorten the battery life. The BATUVLO is adjustable with a fixed 150-mV hysteresis.

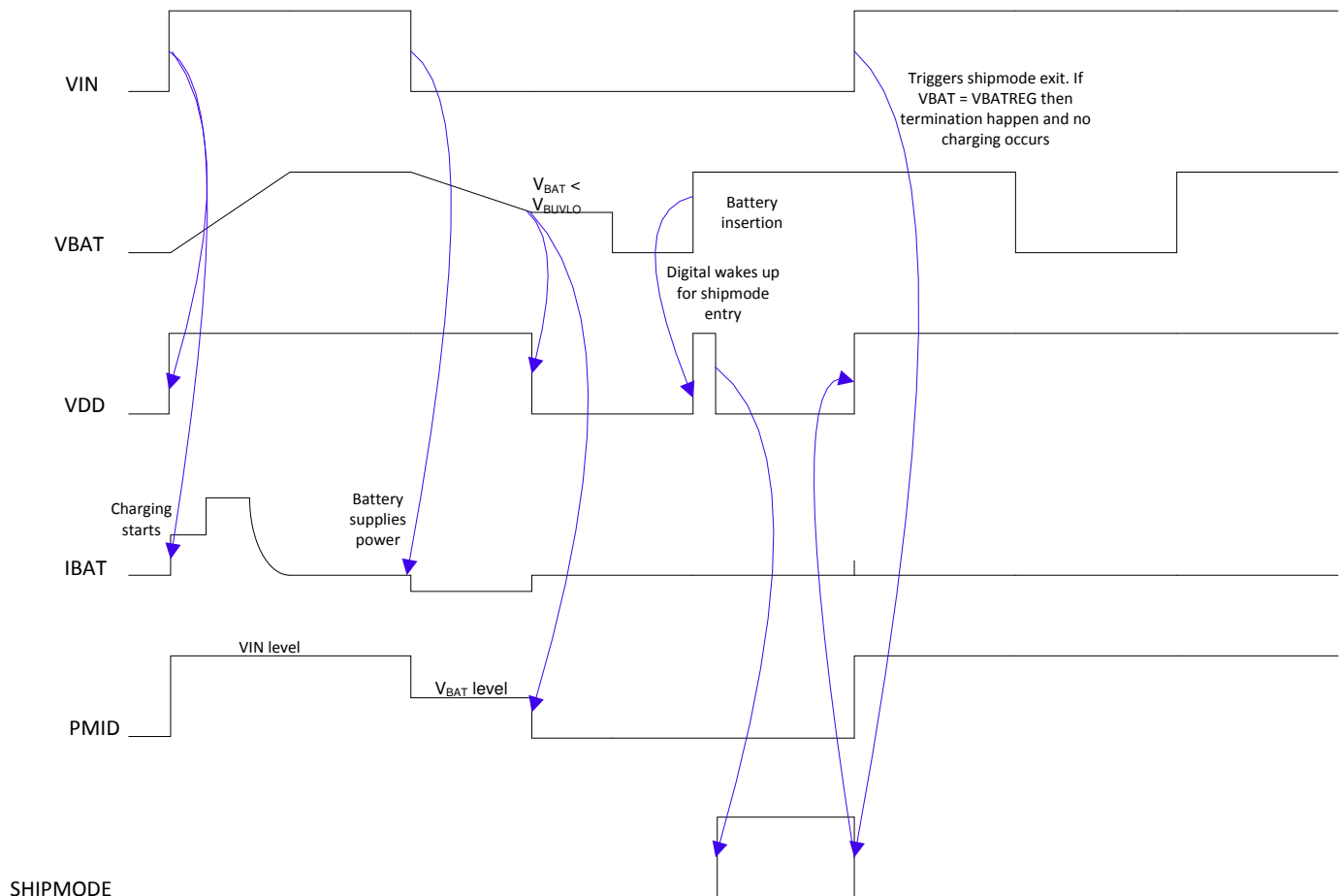
9.4.4 Charger/Adapter Mode

This mode is active when $V_{IN} > V_{UVLO}$. In this mode the ADC is enabled and continuously running conversions on all channels. If the supply at IN is valid and above the V_{IN_DPM} level, PMID will be powered by the supply connected to IN. The device will charge the battery, if charging is enabled, until termination has occurred.

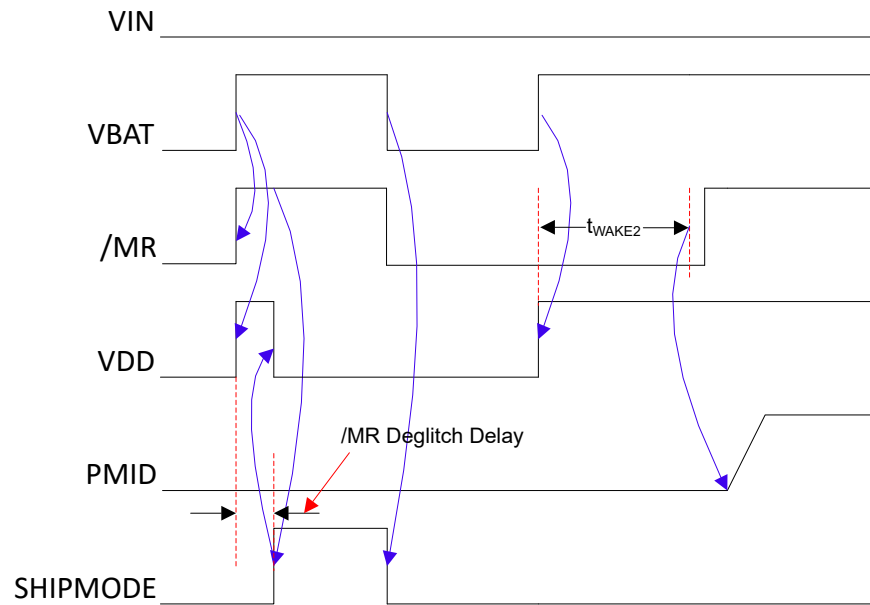
9.4.5 Power-Up/Down Sequencing

The power-up and power-down sequences for the BQ25150 are shown below. Upon V_{IN} insertion, $V_{IN} > V_{UVLO}$, the device wakes up, powering the VDD rail. If $V_{IN} > V_{BAT} + V_{SLP}$ and $V_{IN} < V_{OVP}$, PMID will be powered by V_{IN} and if $V_{IN} > V_{IN_DPM}$ charging will start if enabled.

In the case where $V_{IN} < V_{UVLO}$ and the battery is inserted ($V_{BAT} > V_{BATUVLO}$), the device will immediately enter Ship Mode unless \overline{MR} is held low. Upon battery insertion the VDD rail will come up to allow the device to check the \overline{MR} state and if \overline{MR} is high VDD will immediately be disabled and the device will enter Ship Mode. If \overline{MR} is low, the device will start the WAKE timer and power up PMID and other rails if \overline{MR} is held low for longer than t_{WAKE2} .



9-14. BQ25150 Wake-Up Upon Supply Insertion




9-15. BQ25150 Wake-Up Upon Battery Insertion

9.5 Register Map

Device 7-bit address I²C is 0x6B (shifted 8-bit address is 0xD6). For easy configuration use of the [BQ25150 Setup Guide](#) and [BQ25150 Setup Guide Tool](#) is recommended.

9.5.1 I2C Registers

表 9-8 lists the memory-mapped registers for the I2C registers. All register offset addresses not listed in 表 9-8 should be considered as reserved locations and the register contents should not be modified.

表 9-8. I2C Registers

Address	Acronym	Register Name	Section
0x0	STAT0	Charger Status 0	Go
0x1	STAT1	Charger Status 1	Go
0x2	STAT2	ADC Status	Go
0x3	FLAG0	Charger Flags 0	Go
0x4	FLAG1	Charger Flags 1	Go
0x5	FLAG2	ADC Flags	Go
0x6	FLAG3	Timer Flags	Go
0x7	MASK0	Interrupt Masks 0	Go
0x8	MASK1	Interrupt Masks 1	Go
0x9	MASK2	Interrupt Masks 2	Go
0xA	MASK3	Interrupt Masks 3	Go
0x12	VBAT_CTRL	Battery Voltage Control	Go
0x13	ICHG_CTRL	Fast Charge Current Control	Go
0x14	PCHRGCTRL	Pre-Charge Current Control	Go
0x15	TERMCTRL	Termination Current Control	Go
0x16	BUVLO	Battery UVLO and Current Limit Control	Go
0x17	CHARGERCTRL0	Charger Control 0	Go
0x18	CHARGERCTRL1	Charger Control 1	Go
0x19	ILIMCTRL	Input Corrent Limit Control	Go
0x1D	LDOCTRL	LDO Control	Go
0x30	MRCTRL	MR Control	Go
0x35	ICCTRL0	IC Control 0	Go
0x36	ICCTRL1	IC Control 1	Go
0x37	ICCTRL2	IC Control 2	Go
0x40	ADCCTRL0	ADC Control 0	Go
0x41	ADCCTRL1	ADC Control 1	Go
0x42	ADC_DATA_VBAT_M	ADC VBAT Measurement MSB	Go
0x43	ADC_DATA_VBAT_L	ADC VBAT Measurement LSB	Go
0x44	ADC_DATA_TS_M	ADC TS Measurement MSB	Go
0x45	ADC_DATA_TS_L	ADC TS Measurement LSB	Go
0x46	ADC_DATA_ICHG_M	ADC ICHG Measurement MSB	Go
0x47	ADC_DATA_ICHG_L	ADC ICHG Measurement LSB	Go
0x48	ADC_DATA_ADCIN_M	ADC ADCIN Measurement MSB	Go
0x49	ADC_DATA_ADCIN_L	ADC ADCIN Measurement LSB	Go
0x4A	ADC_DATA_VIN_M	ADC VIN Measurement MSB	Go
0x4B	ADC_DATA_VIN_L	ADC VIN Measurement LSB	Go
0x4C	ADC_DATA_P MID_M	ADC VPMID Measurement MSB	Go
0x4D	ADC_DATA_P MID_L	ADC VPMID Measurement LSB	Go

表 9-8. I2C Registers (continued)

Address	Acronym	Register Name	Section
0x4E	ADC_DATA_IIN_M	ADC IIN Measurement MSB	Go
0x4F	ADC_DATA_IIN_L	ADC IIN Measurement LSB	Go
0x52	ADCALARM_COMP1_M	ADC Comparator 1 Threshold MSB	Go
0x53	ADCALARM_COMP1_L	ADC Comparator 1 Threshold LSB	Go
0x54	ADCALARM_COMP2_M	ADC Comparator 2 Threshold MSB	Go
0x55	ADCALARM_COMP2_L	ADC Comparator 2 Threshold LSB	Go
0x56	ADCALARM_COMP3_M	ADC Comparator 3 Threshold MSB	Go
0x57	ADCALARM_COMP3_L	ADC Comparator 3 Threshold LSB	Go
0x58	ADC_READ_EN	ADC Channel Enable	Go
0x61	TS_FASTCHGCTRL	TS Charge Control	Go
0x62	TS_COLD	TS Cold Threshold	Go
0x63	TS_COOL	TS Cool Threshold	Go
0x64	TS_WARM	TS Warm Threshold	Go
0x65	TS_HOT	TS Hot Threshold	Go
0x6F	DEVICE_ID	Device ID	Go

Complex bit access types are encoded to fit into small table cells. 表 9-9 shows the codes that are used for access types in this section.

表 9-9. I2C Access Type Codes

Access Type	Code	Description
Read Type		
R	R	Read
RC	C R	to Clear Read
Write Type		
W	W	Write
Reset or Default Value		
-n		Value after reset or the default value

9.5.1.1 STAT0 Register (Address = 0x0) [reset = X]

STAT0 is shown in [Figure 9-16](#) and described in [Table 9-10](#).

Return to [Summary Table](#).

Figure 9-16. STAT0 Register

7	6	5	4	3	2	1	0
RESERVED	CHRG_CV_STAT	CHARGE_DONE_STAT	IINLIM_ACTIVE_STAT	VDPPM_ACTIVE_STAT	VINDPM_ACTIVE_STAT	THERMREG_ACTIVE_STAT	VIN_PGOOD_STAT
R-X	R-X	R-X	R-X	R-X	R-X	R-X	R-X

Table 9-10. STAT0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RESERVED	R	X	Reserved
6	CHRG_CV_STAT	R	X	Constant Voltage Charging Mode (Taper Mode) Status 1b0 = Not Active 1b1 = Active
5	CHARGE_DONE_STAT	R	X	Charge Done Status 1b0 = Not Active 1b1 = Active
4	IINLIM_ACTIVE_STAT	R	X	Input Current Limit Status 1b0 = Not Active 1b1 = Active
3	VDPPM_ACTIVE_STAT	R	X	DPPM Status 1b0 = Not Active 1b1 = Active
2	VINDPM_ACTIVE_STAT	R	X	VINDPM Status 1b0 = Not Active 1b1 = Active
1	THERMREG_ACTIVE_STAT	R	X	Thermal Regulation Status 1b0 = Not Active 1b1 = Active
0	VIN_PGOOD_STAT	R	X	VIN Power Good Status 1b0 = Not Good 1b1 = $V_{IN} > V_{UVLO}$ and $V_{IN} > V_{BAT} + V_{SLP}$ and $V_{IN} < V_{OVP}$

9.5.1.2 STAT1 Register (Address = 0x1) [reset = X]

STAT1 is shown in [図 9-17](#) and described in [表 9-11](#).

Return to [Summary Table](#).

図 9-17. STAT1 Register

7	6	5	4	3	2	1	0
VIN_OVP_FAULT_STAT	RESERVED	BAT_OCP_FAULT_STAT	BAT_UVLO_FAULT_STAT	TS_COLD_STAT	TS_COOL_STAT	TS_WARM_STAT	TS_HOT_STAT
R-X	R-X	R-X	R-X	R-X	R-X	R-X	R-X

表 9-11. STAT1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	VIN_OVP_FAULT_STAT	R	X	VIN Overvoltage Status 1b0 = Not Active 1b1 = Active
6	RESERVED	R	X	Reserved
5	BAT_OCP_FAULT_STAT	R	X	Battery Over-Current Protection Status 1b0 = Not Active 1b1 = Active
4	BAT_UVLO_FAULT_STAT	R	X	Battery voltage below BATUVLO Level Status 1b0 = $V_{BAT} > V_{BATUVLO}$ 1b1 = $V_{BAT} < V_{BATUVLO}$
3	TS_COLD_STAT	R	X	TS Cold Status - $V_{TS} > V_{COLD}$ (Charging suspended) 1b0 = Not Active 1b1 = Active
2	TS_COOL_STAT	R	X	TS Cool Status - $V_{COOL} < V_{TS} < V_{COLD}$ (Charging current reduced by value set by TS_Registers) 1b0 = Not Active 1b1 = Active
1	TS_WARM_STAT	R	X	TS Warm - $V_{WARM} > V_{TS} > V_{HOT}$ (Charging voltage reduced by value set by TS_Registers) 1b0 = Not Active 1b1 = Active
0	TS_HOT_STAT	R	X	TS Hot Status - $V_{TS} < V_{HOT}$ (charging suspended) 1b0 = Not Active 1b1 = Active

9.5.1.3 STAT2 Register (Address = 0x2) [reset = X]

STAT2 is shown in [图 9-18](#) and described in [表 9-12](#).

Return to [Summary Table](#).

图 9-18. STAT2 Register

7	6	5	4	3	2	1	0
RESERVED	COMP1_ALAR M_STAT	COMP2_ALAR M_STAT	COMP3_ALAR M_STAT	RESERVED		TS_OPEN_STA T	
R-X	R-X	R-X	R-X	R-X		R-X	

表 9-12. STAT2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RESERVED	R	X	Reserved
6	COMP1_ALARM_STAT	R	X	COMP1 Status 1b0 = Selected ADC measurement does not meet condition set by 1_ADCALARM_ABOVE bit 1b1 = Selected ADC measurement meets condition set by 1_ADCALARM_ABOVE bit
5	COMP2_ALARM_STAT	R	X	COMP2 Status 1b0 = Selected ADC measurement does not meet condition set by 2_ADCALARM_ABOVE bit 1b1 = Selected ADC measurement meets condition set by 2_ADCALARM_ABOVE bit
4	COMP3_ALARM_STAT	R	X	COMP3 Status 1b0 = Selected ADC measurement does not meet condition set by 1_ADCALARM_ABOVE bit 1b1 = Selected ADC measurement meets condition set by 2_ADCALARM_ABOVE bit
3-1	RESERVED	R	X	Reserved
0	TS_OPEN_STAT	R	X	TS Open Status 1b0 = $V_{TS} < V_{OPEN}$ 1b1 = $V_{TS} > V_{OPEN}$

9.5.1.4 FLAG0 Register (Address = 0x3) [reset = 0x0]

FLAG0 is shown in [図 9-19](#) and described in [表 9-13](#).

Return to [Summary Table](#).

Clear on Read

図 9-19. FLAG0 Register

7	6	5	4	3	2	1	0
RESERVED	CHRG_CV_FL AG	CHARGE_DON E_FLAG	IINLIM_ACTIVE _FLAG	VDPPM_ACTIV E_FLAG	VINDPM_ACTI VE_FLAG	THERMREG_A CTIVE_FLAG	VIN_PGOOD_F LAG
RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0

表 9-13. FLAG0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RESERVED	RC	1b0	Reserved
6	CHRG_CV_FLAG	RC	1b0	Constant Voltage Charging Mode (Taper Mode) Flag 1b0 = CV Mode Entry not detected 1b1 = CV Mode Entry detected
5	CHARGE_DONE_FLAG	RC	1b0	Charge Done Flag 1b0 = Charge Done (Termination) not detected 1b1 = Charge Done (Termination) detected
4	IINLIM_ACTIVE_FLAG	RC	1b0	Input Current Limit Flag 1b0 = Input Current Limit not detected 1b1 = Input Current Limit detected
3	VDPPM_ACTIVE_FLAG	RC	1b0	DPPM Flag 1b0 = DPPM operation not detected 1b1 = DPPM operation detected
2	VINDPM_ACTIVE_FLAG	RC	1b0	VINDPM Flag 1b0 = VINDPM operation not detected 1b1 = VIINDPM operation detected
1	THERMREG_ACTIVE_FL AG	RC	1b0	Thermal Regulation Flag 1b0 = Thermal Regulation not detected 1b1 = Thermal Regulation detected
0	VIN_PGOOD_FLAG	RC	1b0	VIN Power Good Flag 1b0 = No change in VIN Power Good Status 1b1 = Change in VIN Power Good Status detected.

9.5.1.5 FLAG1 Register (Address = 0x4) [reset = 0x0]

FLAG1 is shown in [图 9-20](#) and described in [表 9-14](#).

Return to [Summary Table](#).

Clear on Read

图 9-20. FLAG1 Register

7	6	5	4	3	2	1	0
VIN_OVP_FAULT_FLAG	RESERVED	BAT_OCP_FAULT_FLAG	BAT_UVLO_FAULT_FLAG	TS_COLD_FLAG	TS_COOL_FLAG	TS_WARM_FLAG	TS_HOT_FLAG
RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0

表 9-14. FLAG1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	VIN_OVP_FAULT_FLAG	RC	1b0	VIN Over Voltage Fault Flag 1b0 = No overvoltage condition detected 1b1 = VIN overvoltage condition detected
6	RESERVED	RC	1b0	Reserved
5	BAT_OCP_FAULT_FLAG	RC	1b0	Battery Over Current Protection Flag 1b0 = No Battery Over Current condition detected 1b1 = Battery Over Current condition detected
4	BAT_UVLO_FAULT_FLAG	RC	1b0	Battery Under Voltage Flag 1b0 = Battery below BATUVLO condition detected 1b1 = No Battery below BATUVLO condition detected
3	TS_COLD_FLAG	RC	1b0	TS Cold Region Entry Flag 1b0 = TS Cold Region Entry not detected 1b1 = TS Cold Region Entry detected
2	TS_COOL_FLAG	RC	1b0	TS Cool Region Entry Flag 1b0 = TS Cool Region Entry not detected 1b1 = TS Cool Region Entry detected
1	TS_WARM_FLAG	RC	1b0	TS Warm Region Entry Flag 1b0 = TS Warm Region Entry not detected 1b1 = TS Warm Region Entry detected
0	TS_HOT_FLAG	RC	1b0	TS Hot Region Entry Flag 1b0 = TS Hot Region Entry not detected 1b1 = TS Hot Region Entry detected

9.5.1.6 FLAG2 Register (Address = 0x5) [reset = 0x0]

FLAG2 is shown in [図 9-21](#) and described in [表 9-15](#).

Return to [Summary Table](#).

Clear on Read

図 9-21. FLAG2 Register

7	6	5	4	3	2	1	0
ADC_READY_FLAG	COMP1_ALARM_FLAG	COMP2_ALARM_FLAG	COMP3_ALARM_FLAG	RESERVED			TS_OPEN_FLAG
RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-3b000			RC-1b0

表 9-15. FLAG2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	ADC_READY_FLAG	RC	1b0	ADC Ready Flag 1b0 = No ADC conversion completed since last flag read 1b1 = ADC Conversion Completed
6	COMP1_ALARM_FLAG	RC	1b0	ADC COMP1 Threshold Flag 1b0 = No threshold crossing detected 1b1 = Selected ADC measurement crossed condition set by 1_ADCALARM_ABOVE bit
5	COMP2_ALARM_FLAG	RC	1b0	ADC COMP2 Threshold Flag 1b0 = No threshold crossing detected 1b1 = Selected ADC measurement crossed condition set by 2_ADCALARM_ABOVE bit
4	COMP3_ALARM_FLAG	RC	1b0	ADC COMP3 Threshold Flag 1b0 = No threshold crossing detected 1b1 = Selected ADC measurement crossed condition set by 3_ADCALARM_ABOVE bit
3-1	RESERVED	RC	3b000	Reserved
0	TS_OPEN_FLAG	RC	1b0	TS Open Flag 1b0 = No TS Open fault detected 1b1 = TS Open fault detected

9.5.1.7 FLAG3 Register (Address = 0x6) [reset = 0x0]

FLAG3 is shown in [图 9-22](#) and described in [表 9-16](#).

Return to [Summary Table](#).

Clear on Read

图 9-22. FLAG3 Register

7	6	5	4	3	2	1	0
RESERVED	WD_FAULT_FLAG	SAFETY_TMR_FAULT_FLAG	LDO_OCP_FAULT_FLAG	IMAX_FAULT_FLAG	MRWAKE1_TIMEOUT_FLAG	MRWAKE2_TIMEOUT_FLAG	MRRESET_WARN_FLAG
RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0	RC-1b0

表 9-16. FLAG3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RESERVED	RC	1b0	Reserved
6	WD_FAULT_FLAG	RC	1b0	Watchdog Fault Flag 1b0 = Watchdog Timer not expired 1b1 = Watchdog Timer expired
5	SAFETY_TMR_FAULT_FLAG	RC	1b0	Safety Timer Fault Flag 1b0 = Safety Timer not expired 1b1 = Safety Timer Expired
4	LDO_OCP_FAULT_FLAG	RC	1b0	LDO Over Current Fault 1b0 = LDO Normal 1b1 = LDO Over current fault detected
3	IMAX_FAULT_FLAG	RC	1b0	IMAX Open Fault Flag 1b0 = No IMAX open fault detected 1b1 = IMAX open fault detected
2	MRWAKE1_TIMEOUT_FLAG	RC	1b0	MR Wake 1 Timer Flag 1b0 = MR Wake 1 timer not expired 1b1 = MR Wake 1 timer expired
1	MRWAKE2_TIMEOUT_FLAG	RC	1b0	MR Wake 2 Timer Flag 1b0 = MR Wake 2 timer not expired 1b1 = MR Wake 2 timer expired
0	MRRESET_WARN_FLAG	RC	1b0	MR Reset Warn Timer Flag 1b0 = MR Reset Warn timer not expired 1b1 = MR Reset Warn timer expired

9.5.1.8 MASK0 Register (Address = 0x7) [reset = 0x0]

MASK0 is shown in [Figure 9-23](#) and described in [Table 9-17](#).

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Figure 9-23. MASK0 Register

7	6	5	4	3	2	1	0
RESERVED	CHRG_CV_MASK	CHARGE_DONE_MASK	IINLIM_ACTIVE_MASK	VDPPM_ACTIVE_MASK	VINDPM_ACTIVE_MASK	THERMREG_ACTIVE_MASK	VIN_PGOOD_MASK
R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0

Table 9-17. MASK0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RESERVED	R/W	1b0	Reserved 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
6	CHRG_CV_MASK	R/W	1b0	Mask for CHRG_CV interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
5	CHARGE_DONE_MASK	R/W	1b0	Mask for CHARGE_DONE interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
4	IINLIM_ACTIVE_MASK	R/W	1b0	Mask for IINLIM_ACTIVE interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
3	VDPPM_ACTIVE_MASK	R/W	1b0	Mask for VDPPM_ACTIVE interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
2	VINDPM_ACTIVE_MASK	R/W	1b0	Mask for VINDPM_ACTIVE interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
1	THERMREG_ACTIVE_MASK	R/W	1b0	Mask for THERMREG_ACTIVE interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
0	VIN_PGOOD_MASK	R/W	1b0	Mask for VIN_PGOOD interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked

9.5.1.9 MASK1 Register (Address = 0x8) [reset = 0x0]

MASK1 is shown in [图 9-24](#) and described in [表 9-18](#).

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图 9-24. MASK1 Register

7	6	5	4	3	2	1	0
VIN_OVP_FAULT_MASK	RESERVED	BAT_OCP_FAULT_MASK	BAT_UVLO_FAULT_MASK	TS_COLD_MASK	TS_COOL_MASK	TS_WARM_MASK	TS_HOT_MASK
R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0

表 9-18. MASK1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	VIN_OVP_FAULT_MASK	R/W	1b0	Mask for VIN_OVP_FAULT interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
6	RESERVED	R/W	1b0	Reserved
5	BAT_OCP_FAULT_MASK	R/W	1b0	Mask for BAT_OCP_FAULT interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
4	BAT_UVLO_FAULT_MASK	R/W	1b0	Mask for BAT_UVLO_FAULT interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
3	TS_COLD_MASK	R/W	1b0	Mask for TS_COLD interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
2	TS_COOL_MASK	R/W	1b0	Mask for TS_COOL interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
1	TS_WARM_MASK	R/W	1b0	Mask for TS_WARM interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
0	TS_HOT_MASK	R/W	1b0	Mask for TS_HOT interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked

9.5.1.10 MASK2 Register (Address = 0x9) [reset = 0x71]

MASK2 is shown in [Figure 9-25](#) and described in [Table 9-19](#).

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Figure 9-25. MASK2 Register

7	6	5	4	3	2	1	0
ADC_READY_FLAG	COMP1_ALARM_FLAG	COMP2_ALARM_FLAG	COMP3_ALARM_FLAG	RESERVED			TS_OPEN_MASK
R/W-1b0	R/W-1b1	R/W-1b1	R/W-1b1	R/W-3b000			R/W-1b1

Table 9-19. MASK2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	ADC_READY_FLAG	R/W	1b0	Mask for ADC_READY Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
6	COMP1_ALARM_FLAG	R/W	1b1	Mask for COMP1_ALARM Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
5	COMP2_ALARM_FLAG	R/W	1b1	Mask for COMP2_ALARM Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
4	COMP3_ALARM_FLAG	R/W	1b1	Mask for COMP3_ALARM Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
3-1	RESERVED	R/W	3b000	Reserved 3b000 = Interrupt Not Masked 3b001 = Interrupt Masked
0	TS_OPEN_MASK	R/W	1b1	Mask for TS_OPEN Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked

9.5.1.11 MASK3 Register (Address = 0xA) [reset = 0x0]

MASK3 is shown in [Figure 9-26](#) and described in [Table 9-20](#).

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Figure 9-26. MASK3 Register

7	6	5	4	3	2	1	0
RESERVED	WD_FAULT_MASK	SAFETY_TMR_FAULT_MASK	LDO_OCP_FAULT_MASK	IMAX_FAULT_MASK	MRWAKE1_TIMEOUT_MASK	MRWAKE2_TIMEOUT_MASK	MRRESET_WARN_MASK
R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0

Table 9-20. MASK3 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RESERVED	R/W	1b0	Reserved
6	WD_FAULT_MASK	R/W	1b0	Mask for WD_FAULT Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
5	SAFETY_TMR_FAULT_MASK	R/W	1b0	Mask for SAFETY_TIMER_FAULT Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
4	LDO_OCP_FAULT_MASK	R/W	1b0	Mask for LDO_OCP_FAULT Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
3	IMAX_FAULT_MASK	R/W	1b0	Mask for IMAX_FAULT Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
2	MRWAKE1_TIMEOUT_MASK	R/W	1b0	Mask for MRWAKE1_TIMEOUT Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
1	MRWAKE2_TIMEOUT_MASK	R/W	1b0	Mask for MRWAKE2_TIMEOUT Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked
0	MRRESET_WARN_MASK	R/W	1b0	Mask for MRRESET_WARN Interrupt 1b0 = Interrupt Not Masked 1b1 = Interrupt Masked

9.5.1.12 VBAT_CTRL Register (Address = 0x12) [reset = 0x3C]

VBAT_CTRL is shown in [图 9-27](#) and described in [表 9-21](#).

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图 9-27. VBAT_CTRL Register

7	6	5	4	3	2	1	0
RESERVED	VBAT_REG_6:0						
R/W-1b0	R/W-7b0111100						

表 9-21. VBAT_CTRL Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RESERVED	R/W	1b0	Reserved
6-0	VBAT_REG_6:0	R/W	7b0111100	Battery Regulation Voltage VBATREG = 3.6V + VBAT_REG code x 10mV If a value greater than 4.6V is written, the setting will go to 4.6V

9.5.1.13 ICHG_CTRL Register (Address = 0x13) [reset = 0x8]

ICHG_CTRL is shown in [图 9-28](#) and described in [表 9-22](#).

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图 9-28. ICHG_CTRL Register

7	6	5	4	3	2	1	0
ICHG_7:0							
R/W-8b00001000							

表 9-22. ICHG_CTRL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	ICHG_7:0	R/W	8b00001000	Fast Charge Current Fast Charge Current = 1.25mA x ICHG code (ICHARGE_RANGE =0) Fast Charge Current = 2.5mA x ICHG code (ICHARGE_RANGE =1)

9.5.1.14 PCHRGCTRL Register (Address = 0x14) [reset = 0x2]

PCHRGCTRL is shown in [図 9-29](#) and described in [表 9-23](#).

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図 9-29. PCHRGCTRL Register

7	6	5	4	3	2	1	0
ICHARGE_RANGE	RESERVED		IPRECHG_4:0				
R/W-1b0	R/W-2b00		R/W-5b00010				

表 9-23. PCHRGCTRL Register Field Descriptions

Bit	Field	Type	Reset	Description
7	ICHARGE_RANGE	R/W	1b0	Charge Current Step 1b0 = 1.25mA step (318.75mA max charge current) 1b1 = 2.5mA step (500mA max charge current)
6-5	RESERVED	R/W	2b00	Reserved
4-0	IPRECHG_4:0	R/W	5b00010	Pre-Charge Current Pre-Charge Current = 1.25mA x IPRECHG code (ICHARGE_RANGE =0) Pre-Charge Current = 2.5mA x IPRECHG code (ICHARGE_RANGE =1)

9.5.1.15 TERMCTRL Register (Address = 0x15) [reset = 0x14]

TERMCTRL is shown in [图 9-30](#) and described in [表 9-24](#).

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图 9-30. TERMCTRL Register

7	6	5	4	3	2	1	0
RESERVED		ITERM_4:0					TERM_DISABLE
R/W-2b00		R/W-5b01010					R/W-1b0

表 9-24. TERMCTRL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R/W	2b00	Reserved
5-1	ITERM_4:0	R/W	5b01010	Termination Current Programmable Range = 1% to 31% of ICHRG 5b00000 = Do not Use 5b00001 = 1% of ICHRG 5b00010 = 2% of ICHRG 5b00100 = 4% of ICHRG 5b01000 = 8% of ICHRG 5b10000 = 16% of ICHRG
0	TERM_DISABLE	R/W	1b0	Termination Disable 1b0 = Termination Enabled 1b1 = Termination Disabled

9.5.1.16 BUVLO Register (Address = 0x16) [reset = 0x0]

BUVLO is shown in [Figure 9-31](#) and described in [Table 9-25](#).

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Figure 9-31. BUVLO Register

7	6	5	4	3	2	1	0
RESERVED		VLOWV_SEL	IBAT_OCP_ILIM_1:0		BUVLO_2:0		
R/W-2b00		R/W-1b0	R/W-2b00		R/W-3b000		

Table 9-25. BUVLO Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	RESERVED	R/W	2b00	Reserved
5	VLOWV_SEL	R/W	1b0	Pre-charge to Fast Charge Threshold 1b0 = 3.0V 1b1 = 2.8V
4-3	IBAT_OCP_ILIM_1:0	R/W	2b00	Battery Over-Current Protection Threshold 2b00 = 1200mA 2b01 = 1500mA 2b10 = Disabled 2b11 = Disabled
2-0	BUVLO_2:0	R/W	3b000	Battery UVLO Voltage 3b000 = 3.0V 3b001 = 3.0V 3b010 = 3.0V 3b011 = 2.8V 3b100 = 2.6V 3b101 = 2.4V 3b110 = 2.2V 3b111 = Disabled

9.5.1.17 CHARGERCTRL0 Register (Address = 0x17) [reset = 0x82]

CHARGERCTRL0 is shown in [图 9-32](#) and described in [表 9-26](#).

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图 9-32. CHARGERCTRL0 Register

7	6	5	4	3	2	1	0
TS_EN	TS_CONTROL_MODE	VRH_THRESH	WATCHDOG_DISABLE	2XTMR_EN	SAFETY_TIMER_LIMIT_1:0	RESERVED	
R/W-1b1	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-2b01		R/W-1b0

表 9-26. CHARGERCTRL0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	TS_EN	R/W	1b1	TS Function Enable 1b0 = TS function disabled (Only charge control is disabled. TS_OPEN detection and TS ADC monitoring remain enabled) 1b1 = TS function enabled
6	TS_CONTROL_MODE	R/W	1b0	TS Function Control Mode 1b0 = Custom (JEITA) 1b1 = Disable charging on HOT/COLD Only
5	VRH_THRESH	R/W	1b0	Recharge Voltage Threshold 1b0 = 140mV 1b1 = 200mV
4	WATCHDOG_DISABLE	R/W	1b0	Watchdog Timer Disable 1b0 = Watchdog timer enabled 1b1 = Watchdog timer disabled
3	2XTMR_EN	R/W	1b0	Enable 2X Safety Timer 1b0 = The timer is not slowed at any time 1b1 = The timer is slowed by 2x when in any control other than CC or CV
2-1	SAFETY_TIMER_LIMIT_1:0	R/W	2b01	Charger Safety Timer 2b00 = 3 Hr Fast Charge 2b01 = 6 Hr Fast Charge 2b10 = 12 Hr Fast Charge 2b11 = Disabled
0	RESERVED	R/W	1b0	Reserved

9.5.1.18 CHARGERCTRL1 Register (Address = 0x18) [reset = 0x42]

CHARGERCTRL1 is shown in [图 9-33](#) and described in [表 9-27](#).

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图 9-33. CHARGERCTRL1 Register

7	6	5	4	3	2	1	0
VINDPM_DIS	VINPDM_2:0			DPPM_DIS	THERM_REG_2:0		
R/W-1b0	R/W-3b100			R/W-1b0	R/W-3b010		

表 9-27. CHARGERCTRL1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	VINDPM_DIS	R/W	1b0	Disable VINDPM Function 1b0 = VINDPM Enabled 1b1 = VINDPM Disabled
6-4	VINPDM_2:0	R/W	3b100	VINDPM Level Selection 3b000 = 4.2V 3b001 = 4.3V 3b010 = 4.4V 3b011 = 4.5V 3b100 = 4.6V 3b101 = 4.7V 3b110 = 4.8V 3b111 = 4.9V
3	DPPM_DIS	R/W	1b0	DPPM Disable 1b0 = DPPM function enabled 1b1 = DPPM function disabled
2-0	THERM_REG_2:0	R/W	3b010	Thermal Charge Current Foldback Threshold (Thermal Regulation) . Note: Threshold accuracy $\pm 20^{\circ}\text{C}$ 3b000 = 70°C 3b001 = 75°C 3b010 = 80°C 3b011 = 85°C 3b100 = 90°C 3b101 = Reserved 3b110 = Reserved 3b111 = Disabled

9.5.1.19 ILIMCTRL Register (Address = 0x19) [reset = 0x1]

ILIMCTRL is shown in [Figure 9-34](#) and described in [Table 9-28](#).

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Figure 9-34. ILIMCTRL Register

7	6	5	4	3	2	1	0
RESERVED					ILIM_2:0		
R/W-5b00000					R/W-3b001		

Table 9-28. ILIMCTRL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-3	RESERVED	R/W	5b00000	Reserved
2-0	ILIM_2:0	R/W	3b001	Input Current Limit Level Selection 3b000 = 50mA 3b001 = 100mA 3b010 = 150mA 3b011 = 200mA 3b100 = 300mA 3b101 = 400mA 3b110 = 500mA 3b111 = 600mA

9.5.1.20 LDOCTRL Register (Address = 0x1D) [reset = 0xB0]

LDOCTRL is shown in [図 9-35](#) and described in [表 9-29](#).

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図 9-35. LDOCTRL Register

7	6	5	4	3	2	1	0
EN_LS_LDO	VLDO_4:0					LDO_SWITCH_CONFIG	RESERVED
R/W-1b1	R/W-5b01100					R/W-1b0	R/W-1b0

表 9-29. LDOCTRL Register Field Descriptions

Bit	Field	Type	Reset	Description
7	EN_LS_LDO	R/W	1b1	LS/LDO Enable 1b0 = Disable LS/LDO 1b1 = Enable LS/LDO
6-2	VLDO_4:0	R/W	5b01100	LDO output voltage setting LDO Voltage = 600mV + VLDO Code x 100mV
1	LDO_SWITCH_CONFIG	R/W	1b0	LDO / Load Switch Configuration Select 1b0 = LDO 1b1 = Load Switch
0	RESERVED	R/W	1b0	Reserved

9.5.1.21 MRCTRL Register (Address = 0x30) [reset = 0x2A]

MRCTRL is shown in [图 9-36](#) and described in [表 9-30](#).

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图 9-36. MRCTRL Register

7	6	5	4	3	2	1	0
MR_RESET_VIN	MR_WAKE1_TIMER	MR_WAKE2_TIMER	MR_RESET_WARN_1:0		MR_HW_RESET_1:0		RESERVED
R/W-1b0	R/W-1b0	R/W-1b1	R/W-2b01		R/W-2b01		R/W-1b0

表 9-30. MRCTRL Register Field Descriptions

Bit	Field	Type	Reset	Description
7	MR_RESET_VIN	R/W	1b0	VIN Power Good gated MR Reset Enable 1b0 = Reset sent when /MR reset time is met regardless of VIN state 1b1 = Reset sent when MR reset is met and Vin is valid
6	MR_WAKE1_TIMER	R/W	1b0	Wake 1 Timer setting 1b0 = 125ms 1b1 = 500ms
5	MR_WAKE2_TIMER	R/W	1b1	Wake 2 Timer setting 1b0 = 1s 1b1 = 2s
4-3	MR_RESET_WARN_1:0	R/W	2b01	MR Reset Warn Timer setting 2b00 = MR_HW_RESET - 0.5s 2b01 = MR_HW_RESET - 1.0s 2b10 = MR_HW_RESET - 1.5s 2b11 = MR_HW_RESET - 2.0s
2-1	MR_HW_RESET_1:0	R/W	2b01	MR HW Reset Timer setting 2b00 = 4s 2b01 = 8s 2b10 = 10s 2b11 = 14s
0	RESERVED	R/W	1b0	Reserved

9.5.1.22 ICCTRL0 Register (Address = 0x35) [reset = 0x10]

ICCTRL0 is shown in [図 9-37](#) and described in [表 9-31](#).

Return to [Summary Table](#).

図 9-37. ICCTRL0 Register

7	6	5	4	3	2	1	0
EN_SHIP_MODE	RESERVED	AUTOWAKE_1:0		RESERVED	GLOBAL_INT_MASK	HW_RESET	SW_RESET
R/W-1b0	R/W-1b0	R/W-2b01		R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0

表 9-31. ICCTRL0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7	EN_SHIP_MODE	R/W	1b0	Ship Mode Enable 1b0 = Normal operation 1b1 = Enter Ship Mode when VIN is not valid and /MR is high
6	RESERVED	R/W	1b0	Reserved
5-4	AUTOWAKE_1:0	R/W	2b01	Auto-wakeup Timer (TRESTART) for /MR HW Reset 2b00 = 0.6s 2b01 = 1.2s 2b10 = 2.4s 2b11 = 5s
3	RESERVED	R/W	1b0	Reserved
2	GLOBAL_INT_MASK	R/W	1b0	Global Interrupt Mask 1b0 = Normal Operation 1b1 = Mask all interrupts
1	HW_RESET	R/W	1b0	HW Reset 1b0 = Normal operation 1b1 = HW Reset. Temporarily power down all power rails, except VDD. I ² C Register go to default settings.
0	SW_RESET	R/W	1b0	SW_Reset 1b0 = Normal operation 1b1 = SW Reset. I ² C Registers go to default settings.

9.5.1.23 ICCTRL1 Register (Address = 0x36) [reset = 0x0]

ICCTRL1 is shown in [图 9-38](#) and described in [表 9-32](#).

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图 9-38. ICCTRL1 Register

7	6	5	4	3	2	1	0
MR_LPRESS_ACTION_1:0		ADCIN_MODE	RESERVED	PG_MODE_1:0		PMID_MODE_1:0	
R/W-2b00		R/W-1b0	R/W-1b0	R/W-2b00		R/W-2b00	

表 9-32. ICCTRL1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	MR_LPRESS_ACTION_1:0	R/W	2b00	MR Long Press Action 2b00 = HW Reset (Power Cycle) 2b01 = Do nothing 2b10 = Enter Ship Mode 2b11 = Enter Ship Mode
5	ADCIN_MODE	R/W	1b0	ADCIN Pin Mode of Operation 1b0 = General Purpose ADC input (no Internal biasing) 1b1 = 10K NTC ADC input (80uA biasing)
4	RESERVED	R/W	1b0	Reserved
3-2	PG_MODE_1:0	R/W	2b00	PG Pin Mode of Operation 2b00 = VIN Power Good 2b01 = Deglitched Level Shifted /MR 2b10 = General Purpose Open Drain Output 2b11 = General Purpose Open Drain Output
1-0	PMID_MODE_1:0	R/W	2b00	PMID Control Sets how PMID is powered in any state, except Ship Mode. 2b00 = PMID powered from BAT or VIN if present 2b01 = PMID powered from BAT only, even if VIN is present 2b10 = PMID disconnected and left floating 2b11 = PMID disconnected and pulled down.

9.5.1.24 ICCTRL2 Register (Address = 0x37) [reset = 0x0]

ICCTRL2 is shown in [図 9-39](#) and described in [表 9-33](#).

Return to [Summary Table](#).

図 9-39. ICCTRL2 Register

7	6	5	4	3	2	1	0
RESERVED			GPO_PG	RESERVED		HWRESET_14 S_WD	CHARGER_DIS ABLE
R/W-3b000			R/W-1b0	R/W-2b00		R/W-1b0	R/W-1b0

表 9-33. ICCTRL2 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-5	RESERVED	R/W	3b000	Reserved
4	GPO_PG	R/W	1b0	/PG General Purpose Output State Control 1b0 = Pulled Down 1b1 = High Z
3-2	RESERVED	R/W	2b00	Reserved
1	HWRESET_14S_WD	R/W	1b0	Enable for 14-second I2C watchdog timer for HW Reset after VIN connection 1b0 = Timer disabled 1b1 = Device will perform HW reset if no I2C transaction is done within 14s after VIN is present
0	CHARGER_DISABLE	R/W	1b0	Charge Disable 1b0 = Charge enabled if /CE pin is low 1b1 = Charge disabled

9.5.1.25 ADCCTRL0 Register (Address = 0x40) [reset = 0x2]

ADCCTRL0 is shown in [Figure 9-40](#) and described in [Table 9-34](#).

Return to [Summary Table](#).

Figure 9-40. ADCCTRL0 Register

7	6	5	4	3	2	1	0
ADC_READ_RATE_1:0		ADC_CONV_START	ADC_CONV_SPEED_1:0		ADC_COMP1_2:0		
R/W-2b00		R/W-1b0	R/W-2b00		R/W-3b010		

Table 9-34. ADCCTRL0 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-6	ADC_READ_RATE_1:0	R/W	2b00	Read rate for ADC measurements in BAT Only operation 2b00 = Manual Read (Measurement done when ADC_CONV_START is set) 2b01 = Continuous 2b10 = Every 1 second 2b11 = Every 1 minute
5	ADC_CONV_START	R/W	1b0	ADC Conversion Start Trigger Bit goes back to 0 when conversion is complete 1b0 = No ADC conversion 1b1 = Initiates ADC measurement in Manual Read operation
4-3	ADC_CONV_SPEED_1:0	R/W	2b00	ADC Conversion Speed 2b00 = 24ms (Highest accuracy) 2b01 = 12ms 2b10 = 6ms 2b11 = 3ms
2-0	ADC_COMP1_2:0	R/W	3b010	ADC Channel for Comparator 1 3b000 = Disabled 3b001 = ADCIN 3b010 = TS 3b011 = VBAT 3b100 = ICHARGE 3b101 = VIN 3b110 = PMID 3b111 = IIN

9.5.1.26 ADCCTRL1 Register (Address = 0x41) [reset = 0x40]

ADCCTRL1 is shown in [図 9-41](#) and described in [表 9-35](#).

Return to [Summary Table](#).

図 9-41. ADCCTRL1 Register

7	6	5	4	3	2	1	0
ADC_COMP2_2:0			ADC_COMP3_2:0			RESERVED	
R/W-3b010			R/W-3b000			R/W-2b00	

表 9-35. ADCCTRL1 Register Field Descriptions

Bit	Field	Type	Reset	Description
7-5	ADC_COMP2_2:0	R/W	3b010	ADC Channel for Comparator 2 3b000 = Disabled 3b001 = ADCIN 3b010 = TS 3b011 = VBAT 3b100 = ICHARGE 3b101 = VIN 3b110 = PMID 3b111 = IIN
4-2	ADC_COMP3_2:0	R/W	3b000	ADC Channel for Comparator 3 3b000 = Disabled 3b001 = ADCIN 3b010 = TS 3b011 = VBAT 3b100 = ICHARGE 3b101 = VIN 3b110 = PMID 3b111 = IIN
1-0	RESERVED	R/W	2b00	Reserved

9.5.1.27 ADC_DATA_VBAT_M Register (Address = 0x42) [reset = X]

ADC_DATA_VBAT_M is shown in [図 9-42](#) and described in [表 9-36](#).

Return to [Summary Table](#).

図 9-42. ADC_DATA_VBAT_M Register

7	6	5	4	3	2	1	0
VBAT_ADC_15:8							
R-X							

表 9-36. ADC_DATA_VBAT_M Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	VBAT_ADC_15:8	R	X	ADC VBAT Measurement MSB

9.5.1.28 ADC_DATA_VBAT_L Register (Address = 0x43) [reset = X]

ADC_DATA_VBAT_L is shown in [図 9-43](#) and described in [表 9-37](#).

Return to [Summary Table](#).

図 9-43. ADC_DATA_VBAT_L Register

7	6	5	4	3	2	1	0
VBAT_ADC_7:0							
R-X							

表 9-37. ADC_DATA_VBAT_L Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	VBAT_ADC_7:0	R	X	ADC VBAT Measurement LSB

9.5.1.29 ADC_DATA_TS_M Register (Address = 0x44) [reset = X]

ADC_DATA_TS_M is shown in [图 9-44](#) and described in [表 9-38](#).

Return to [Summary Table](#).

图 9-44. ADC_DATA_TS_M Register

7	6	5	4	3	2	1	0
TS_ADC_15:8							
R-X							

表 9-38. ADC_DATA_TS_M Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	TS_ADC_15:8	R	X	ADC TS Measurement MSB

9.5.1.30 ADC_DATA_TS_L Register (Address = 0x45) [reset = X]

ADC_DATA_TS_L is shown in [図 9-45](#) and described in [表 9-39](#).

Return to [Summary Table](#).

図 9-45. ADC_DATA_TS_L Register

7	6	5	4	3	2	1	0
TS_ADC_7:0							
R-X							

表 9-39. ADC_DATA_TS_L Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	TS_ADC_7:0	R	X	ADC TS Measurement LSB

9.5.1.31 ADC_DATA_ICHG_M Register (Address = 0x46) [reset = X]

ADC_DATA_ICHG_M is shown in [図 9-46](#) and described in [表 9-40](#).

Return to [Summary Table](#).

図 9-46. ADC_DATA_ICHG_M Register

7	6	5	4	3	2	1	0
ICHG_ADC_15:8							
R-X							

表 9-40. ADC_DATA_ICHG_M Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	ICHG_ADC_15:8	R	X	ADC ICHG Measurement MSB

9.5.1.32 ADC_DATA_ICHG_L Register (Address = 0x47) [reset = X]

ADC_DATA_ICHG_L is shown in [図 9-47](#) and described in [表 9-41](#).

Return to [Summary Table](#).

図 9-47. ADC_DATA_ICHG_L Register

7	6	5	4	3	2	1	0
ICHG_ADC_7:0							
R-X							

表 9-41. ADC_DATA_ICHG_L Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	ICHG_ADC_7:0	R	X	ADC ICHG Measurement LSB

9.5.1.33 ADC_DATA_ADCIN_M Register (Address = 0x48) [reset = X]

ADC_DATA_ADCIN_M is shown in [図 9-48](#) and described in [表 9-42](#).

Return to [Summary Table](#).

図 9-48. ADC_DATA_ADCIN_M Register

7	6	5	4	3	2	1	0
ADCIN_ADC_15:8							
R-X							

表 9-42. ADC_DATA_ADCIN_M Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	ADCIN_ADC_15:8	R	X	ADC ADCIN Measurement MSB

9.5.1.34 ADC_DATA_ADCIN_L Register (Address = 0x49) [reset = X]

ADC_DATA_ADCIN_L is shown in [図 9-49](#) and described in [表 9-43](#).

Return to [Summary Table](#).

図 9-49. ADC_DATA_ADCIN_L Register

7	6	5	4	3	2	1	0
ADCIN_ADC_7:0							
R-X							

表 9-43. ADC_DATA_ADCIN_L Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	ADCIN_ADC_7:0	R	X	ADC ADCIN Measurement LSB

9.5.1.35 ADC_DATA_VIN_M Register (Address = 0x4A) [reset = X]

ADC_DATA_VIN_M is shown in [Figure 9-50](#) and described in [Table 9-44](#).

Return to [Summary Table](#).

Figure 9-50. ADC_DATA_VIN_M Register

7	6	5	4	3	2	1	0
VIN_ADC_15:8							
R-X							

Table 9-44. ADC_DATA_VIN_M Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	VIN_ADC_15:8	R	X	ADC VIN Measurement MSB

9.5.1.36 ADC_DATA_VIN_L Register (Address = 0x4B) [reset = X]

ADC_DATA_VIN_L is shown in [図 9-51](#) and described in [表 9-45](#).

Return to [Summary Table](#).

図 9-51. ADC_DATA_VIN_L Register

7	6	5	4	3	2	1	0
VIN_ADC_7:0							
R-X							

表 9-45. ADC_DATA_VIN_L Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	VIN_ADC_7:0	R	X	ADC VIN Measurement LSB

9.5.1.37 ADC_DATA_P MID_M Register (Address = 0x4C) [reset = X]

ADC_DATA_P MID_M is shown in [图 9-52](#) and described in [表 9-46](#).

Return to [Summary Table](#).

图 9-52. ADC_DATA_P MID_M Register

7	6	5	4	3	2	1	0
P MID_ADC_15:8							
R-X							

表 9-46. ADC_DATA_P MID_M Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	P MID_ADC_15:8	R	X	ADC P MID Measurement MSB

9.5.1.38 ADC_DATA_P MID_L Register (Address = 0x4D) [reset = X]

ADC_DATA_P MID_L is shown in [図 9-53](#) and described in [表 9-47](#).

Return to [Summary Table](#).

図 9-53. ADC_DATA_P MID_L Register

7	6	5	4	3	2	1	0
P MID_ADC_7:0							
R-X							

表 9-47. ADC_DATA_P MID_L Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	P MID_ADC_7:0	R	X	ADC P MID Measurement LSB

9.5.1.39 ADC_DATA_IIN_M Register (Address = 0x4E) [reset = X]

ADC_DATA_IIN_M is shown in [图 9-54](#) and described in [表 9-48](#).

Return to [Summary Table](#).

图 9-54. ADC_DATA_IIN_M Register

7	6	5	4	3	2	1	0
IIN_ADC_15:8							
R-X							

表 9-48. ADC_DATA_IIN_M Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	IIN_ADC_15:8	R	X	ADC IIN Measurement MSB

9.5.1.40 ADC_DATA_IIN_L Register (Address = 0x4F) [reset = X]

ADC_DATA_IIN_L is shown in [図 9-55](#) and described in [表 9-49](#).

Return to [Summary Table](#).

図 9-55. ADC_DATA_IIN_L Register

7	6	5	4	3	2	1	0
IIN_ADC_7:0							
R-X							

表 9-49. ADC_DATA_IIN_L Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	IIN_ADC_7:0	R	X	ADC IIN Measurement LSB

9.5.1.41 ADCALARM_COMP1_M Register (Address = 0x52) [reset = 0x23]

ADCALARM_COMP1_M is shown in [図 9-56](#) and described in [表 9-50](#).

Return to [Summary Table](#).

図 9-56. ADCALARM_COMP1_M Register

7	6	5	4	3	2	1	0
1_ADCALARM_15:8							
R/W-8b00100011							

表 9-50. ADCALARM_COMP1_M Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	1_ADCALARM_15:8	R/W	8b00100011	ADC Comparator 1 Threshold MSB

9.5.1.42 ADCALARM_COMP1_L Register (Address = 0x53) [reset = 0x20]

ADCALARM_COMP1_L is shown in [图 9-57](#) and described in [表 9-51](#).

Return to [Summary Table](#).

图 9-57. ADCALARM_COMP1_L Register

7	6	5	4	3	2	1	0
1_ADCALARM_7:4				1_ADCALARM_ABOVE	RESERVED		
R/W-4b0010				R/W-1b0	R/W-3b000		

表 9-51. ADCALARM_COMP1_L Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	1_ADCALARM_7:4	R/W	4b0010	ADC Comparator 1 Threshold LSB
3	1_ADCALARM_ABOVE	R/W	1b0	ADC Comparator1 Polarity 1b0 = Set Flag and send interrupt if ADC measurement becomes lower than comparator threshold 1b1 = Set Flag and send interrupt if ADC measurement is becomes higher than comparator threshold
2-0	RESERVED	R/W	3b000	Reserved

9.5.1.43 ADCALARM_COMP2_M Register (Address = 0x54) [reset = 0x38]

ADCALARM_COMP2_M is shown in [図 9-58](#) and described in [表 9-52](#).

Return to [Summary Table](#).

図 9-58. ADCALARM_COMP2_M Register

7	6	5	4	3	2	1	0
2_ADCALARM_15:8							
R/W-8b00111000							

表 9-52. ADCALARM_COMP2_M Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	2_ADCALARM_15:8	R/W	8b00111000	ADC Comparator 2 Threshold MSB

9.5.1.44 ADCALARM_COMP2_L Register (Address = 0x55) [reset = 0x90]

ADCALARM_COMP2_L is shown in [図 9-59](#) and described in [表 9-53](#).

Return to [Summary Table](#).

図 9-59. ADCALARM_COMP2_L Register

7	6	5	4	3	2	1	0
2_ADCALARM_7:4				2_ADCALARM_ABOVE	RESERVED		
R/W-4b1001				R/W-1b0	R/W-3b000		

表 9-53. ADCALARM_COMP2_L Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	2_ADCALARM_7:4	R/W	4b1001	ADC Comparator 2 Threshold LSB
3	2_ADCALARM_ABOVE	R/W	1b0	ADC Comparator 2 Polarity 1b0 = Set Flag and send interrupt if ADC measurement becomes lower than comparator threshold 1b1 = Set Flag and send interrupt if ADC measurement is becomes higher than comparator threshold
2-0	RESERVED	R/W	3b000	Reserved

9.5.1.45 ADCALARM_COMP3_M Register (Address = 0x56) [reset = 0x0]

ADCALARM_COMP3_M is shown in [图 9-60](#) and described in [表 9-54](#).

Return to [Summary Table](#).

图 9-60. ADCALARM_COMP3_M Register

7	6	5	4	3	2	1	0
3_ADCALARM_15:8							
R/W-8b00000000							

表 9-54. ADCALARM_COMP3_M Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	3_ADCALARM_15:8	R/W	8b00000000	ADC Comparator 3 Threshold MSB

9.5.1.46 ADCALARM_COMP3_L Register (Address = 0x57) [reset = 0x0]

ADCALARM_COMP3_L is shown in [図 9-61](#) and described in [表 9-55](#).

Return to [Summary Table](#).

図 9-61. ADCALARM_COMP3_L Register

7	6	5	4	3	2	1	0
3_ADCALARM_7:4				3_ADCALARM_ABOVE	RESERVED		
R/W-4b0000				R/W-1b0	R/W-3b000		

表 9-55. ADCALARM_COMP3_L Register Field Descriptions

Bit	Field	Type	Reset	Description
7-4	3_ADCALARM_7:4	R/W	4b0000	ADC Comparator 3 Threshold LSB
3	3_ADCALARM_ABOVE	R/W	1b0	ADC Comparator 3 Polarity 1b0 = Set Flag and send interrupt if ADC measurement becomes lower than comparator threshold 1b1 = Set Flag and send interrupt if ADC measurement is becomes higher than comparator threshold
2-0	RESERVED	R/W	3b000	Reserved

9.5.1.47 ADC_READ_EN Register (Address = 0x58) [reset = 0x0]

ADC_READ_EN is shown in [图 9-62](#) and described in [表 9-56](#).

Return to [Summary Table](#).

图 9-62. ADC_READ_EN Register

7	6	5	4	3	2	1	0
EN_IIN_READ	EN_PMIID_READ	EN_ICHG_READ	EN_VIN_READ	EN_VBAT_READ	EN_TS_READ	EN_ADCIN_READ	RESERVED
R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0	R/W-1b0

表 9-56. ADC_READ_EN Register Field Descriptions

Bit	Field	Type	Reset	Description
7	EN_IIN_READ	R/W	1b0	Enable measurement for Input Current (IIN) Channel 1b0 = ADC measurement disabled 1b1 = ADC measurement enabled
6	EN_PMIID_READ	R/W	1b0	Enable measurement for PMID Channel 1b0 = ADC measurement disabled 1b1 = ADC measurement enabled
5	EN_ICHG_READ	R/W	1b0	Enable measurement for Charge Current Channel 1b0 = ADC measurement disabled 1b1 = ADC measurement enabled
4	EN_VIN_READ	R/W	1b0	Enable measurement for Input Voltage (VIN) Channel 1b0 = ADC measurement disabled 1b1 = ADC measurement enabled
3	EN_VBAT_READ	R/W	1b0	Enable measurement for Battery Voltage (VBAT) Channel 1b0 = ADC measurement disabled 1b1 = ADC measurement enabled
2	EN_TS_READ	R/W	1b0	Enable measurement for TS Channel 1b0 = ADC measurement disabled 1b1 = ADC measurement enabled
1	EN_ADCIN_READ	R/W	1b0	Enable measurement for ADCIN Channel 1b0 = ADC measurement disabled 1b1 = ADC measurement enabled
0	RESERVED	R/W	1b0	Reserved

9.5.1.48 TS_FASTCHGCTRL Register (Address = 0x61) [reset = 0x34]

TS_FASTCHGCTRL is shown in [図 9-63](#) and described in [表 9-57](#).

Return to [Summary Table](#).

図 9-63. TS_FASTCHGCTRL Register

7	6	5	4	3	2	1	0
RESERVED	TS_VBAT_REG__2:0			RESERVED	TS_ICHRG_2:0		
R/W-1b0	R/W-3b011			R/W-1b0	R/W-3b100		

表 9-57. TS_FASTCHGCTRL Register Field Descriptions

Bit	Field	Type	Reset	Description
7	RESERVED	R/W	1b0	Reserved
6-4	TS_VBAT_REG__2:0	R/W	3b011	Reduced target battery voltage during Warm 3b000 = No reduction 3b001 = VBAT_REG - 50mV 3b010 = VBAT_REG - 100mV 3b011 = VBAT_REG - 150mV 3b100 = VBAT_REG - 200mV 3b101 = VBAT_REG - 250mV 3b110 = VBAT_REG - 300mV 3b111 = VBAT_REG - 350mV
3	RESERVED	R/W	1b0	Reserved
2-0	TS_ICHRG_2:0	R/W	3b100	Fast charge current when decreased by TS function 3b000 = No reduction 3b001 = 0.875 x ICHG 3b010 = 0.750 x ICHG 3b011 = 0.625 x ICHG 3b100 = 0.500 x ICHG 3b101 = 0.375 x ICHG 3b110 = 0.250 x ICHG 3b111 = 0.125 x ICHG

9.5.1.49 TS_COLD Register (Address = 0x62) [reset = 0x7C]

TS_COLD is shown in [Figure 9-64](#) and described in [Table 9-58](#).

Return to [Summary Table](#).

Figure 9-64. TS_COLD Register

7	6	5	4	3	2	1	0
TS_COLD_7:0							
R/W-8b01111100							

Table 9-58. TS_COLD Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	TS_COLD_7:0	R/W	8b01111100	TS Cold Threshold 1b = 4.688 mV 10b = 9.375 mV 100b = 18.75 mV 1000b = 37.5 mV 10000b = 75 mV 100000b = 150 mV 1000000b = 300 mV 10000000b = 600mV

9.5.1.50 TS_COOL Register (Address = 0x63) [reset = 0x6D]

TS_COOL is shown in [図 9-65](#) and described in [表 9-59](#).

Return to [Summary Table](#).

図 9-65. TS_COOL Register

7	6	5	4	3	2	1	0
TS_COOL_7:0							
R/W-8b01101101							

表 9-59. TS_COOL Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	TS_COOL_7:0	R/W	8b01101101	TS Cool Threshold 1b = 4.688 mV 10b = 9.375 mV 100b = 18.75 mV 1000b = 37.5 mV 10000b = 75 mV 100000b = 150 mV 1000000b = 300 mV 10000000b = 600mV

9.5.1.51 TS_WARM Register (Address = 0x64) [reset = 0x38]

TS_WARM is shown in [图 9-66](#) and described in [表 9-60](#).

Return to [Summary Table](#).

图 9-66. TS_WARM Register

7	6	5	4	3	2	1	0
TS_WARM_7:0							
R/W-8b00111000							

表 9-60. TS_WARM Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	TS_WARM_7:0	R/W	8b00111000	TS Warm Threshold 1b = 4.688 mV 10b = 9.375 mV 100b = 18.75 mV 1000b = 37.5 mV 10000b = 75 mV 100000b = 150 mV 1000000b = 300 mV 10000000b = 600mV

9.5.1.52 TS_HOT Register (Address = 0x65) [reset = 0x27]

TS_HOT is shown in [図 9-67](#) and described in [表 9-61](#).

Return to [Summary Table](#).

図 9-67. TS_HOT Register

7	6	5	4	3	2	1	0
TS_HOT_7:0							
R/W-8b00100111							

表 9-61. TS_HOT Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	TS_HOT_7:0	R/W	8b00100111	TS Hot Threshold 1b = 4.688 mV 10b = 9.375 mV 100b = 18.75 mV 1000b = 37.5 mV 10000b = 75 mV 100000b = 150 mV 1000000b = 300 mV 10000000b = 600 mV

9.5.1.53 DEVICE_ID Register (Address = 0x6F) [reset = 0x20]

DEVICE_ID is shown in [图 9-68](#) and described in [表 9-62](#).

Return to [Summary Table](#).

图 9-68. DEVICE_ID Register

7	6	5	4	3	2	1	0
DEVICE_ID_7:0							
R-8b00100000							

表 9-62. DEVICE_ID Register Field Descriptions

Bit	Field	Type	Reset	Description
7-0	DEVICE_ID_7:0	R	8b00100000	Device ID 100000b = BQ25150

10 Application and Implementation

注

以下のアプリケーション情報は、TI の製品仕様に含まれるものではなく、TI ではその正確性または完全性を保証いたしません。個々の目的に対する製品の適合性については、お客様の責任で判断していただくことになります。お客様は自身の設計実装を検証しテストすることで、システムの機能を確認する必要があります。

10.1 Application Information

A typical application of the BQ25150 consists of the device configured as an I²C controlled single cell Li-ion battery charger and power path manager or small battery applications such as smart-watches and wireless headsets. A battery thermistor may be connected to the TS pin to allow the device to monitor the battery temperature and control charging as desired. A resistor must be connected to the IMAX pin to set the maximum allowable charge current and must not be left floating.

The system designer may connect the $\overline{\text{MR}}$ input to a push-button to send interrupts to the host as the button is pressed or to allow the application's end user to reset the system. If not used this pin must be left floating or tied to BAT.

The ADCIN pin may be tied to ground or be connected to a signal which the system designer desires to measure using the integrated ADC. The signal must be scaled down to not exceed the 0 to 1.2-V range of the ADCIN input range.

10.2 Typical Application

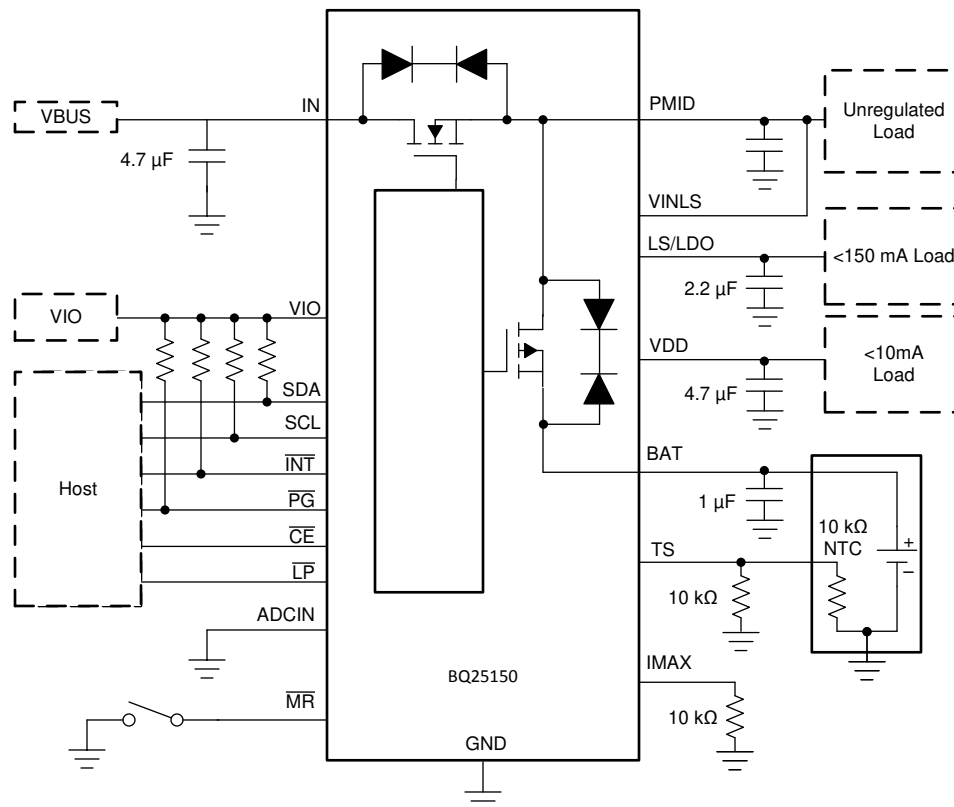


図 10-1. Typical Application Diagram

10.2.1 Design Requirements

The design parameters for the following design example are shown in 表 10-1.

表 10-1. Design Parameters

PARAMETER	VALUE
IN Supply Voltage	5 V
Battery Regulation Voltage	4.2 V
LDO Output Voltage	LDO (1.8 V)
Maximum Allowed Fast Charge Charge Current (IMAX)	300 mA

10.2.2 Detailed Design Procedure

10.2.2.1 Input (IN/PMID) Capacitors

Low ESR ceramic capacitors such as X7R or X5R is preferred for input decoupling capacitors and should be placed as close as possible to the supply and ground pins for the IC. Due to the voltage derating of the capacitors it is recommended that 25-V rated capacitors are used for IN and PMID pins which can normally operate at 5 V. After derating the minimum capacitance must be higher than 1 μ F.

10.2.2.2 VDD, LDO Input and Output Capacitors

A low ESR ceramic capacitor such as X7R or X5R is recommended for the LDO decoupling capacitor. A 4.7- μ F capacitor is recommended for VDD output. For the LDO output a 2.2- μ F capacitor is recommended. The minimum supported capacitance after derating must be higher than 1 μ F to ensure stability. The VINLS input bypass capacitor value should match or exceed the LDO output capacitor value.

10.2.2.3 TS

A 10-K Ω NTC should be connected in parallel to a 10-K Ω biasing resistor connected to ground. The ground connection of both the NTC and biasing resistor must be done as close as possible to the GND pin of the device or kelvin connected to it to minimize any error in TS measurement due to IR drops on the board ground lines.

If the system designer does not wish to use the TS function for charging control, a 5-K Ω resistor from IMAX to ground must be connected.

10.2.2.4 IMAX Selection

For a 300-mA maximum allowable charge current, the desired maximum FAST_CHARGE register code (decimal) is 120 when ICHARGE_STEP = 1 (2.5 mA). Using 式 6, the calculated R_{IMAX} value is 3.52 K Ω . Note that if ICHARGE_STEP is set to 0 (1.25 mA), the I_{MAX} value is reduced by half to 150 mA.

If the system designer does not wish to use the IMAX function to limit the maximum charge current, 10-K Ω resistor from IMAX to ground must be connected.

For easy configuration use of the [BQ25150 Setup Guide](#) and [BQ25150 Setup Guide Tool](#) is recommended.

10.2.2.5 Recommended Passive Components

表 10-2. Recommended Passive Components

		MIN	NOM	MAX	UNIT
C _{PMID}	Capacitance in PMID pin	1	10	47	μ F
C _{LDO}	LDO output capacitance	1	2.2	4.7	μ F
C _{VDD}	VDD output capacitance	1	4.7	4.7	μ F
C _{BAT}	BAT pin capacitance	1		–	μ F
C _{IN}	IN input bypass capacitance	1	4.7	10	μ F
C _{INLS}	VINLS input bypass capacitance	1		–	μ F
C _{TS}	Capacitance from TS pin to ground	0	0	1	nF

10.2.3 Application Curves

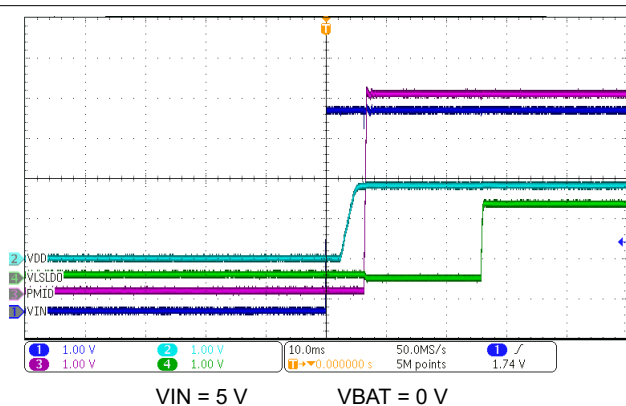


图 10-2. Power Up From IN Supply Insertion with No Battery

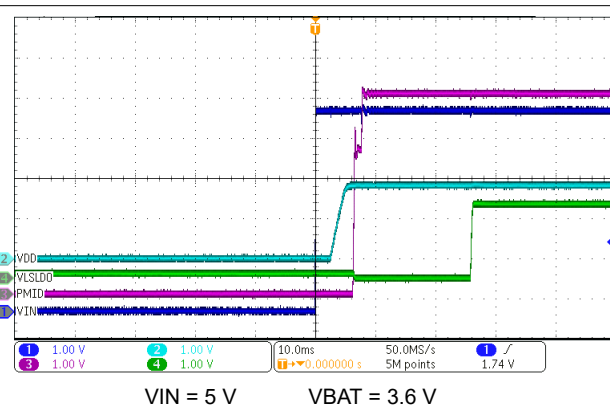


图 10-3. Power Up From Ship Mode with IN Supply Insertion

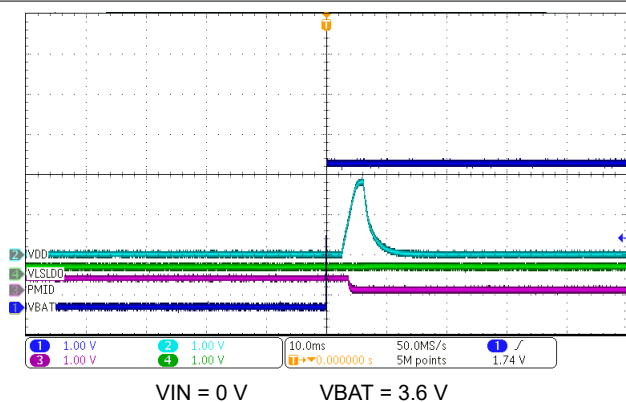


图 10-4. Wake In To Ship Mode on Battery Insertion with No IN Supply

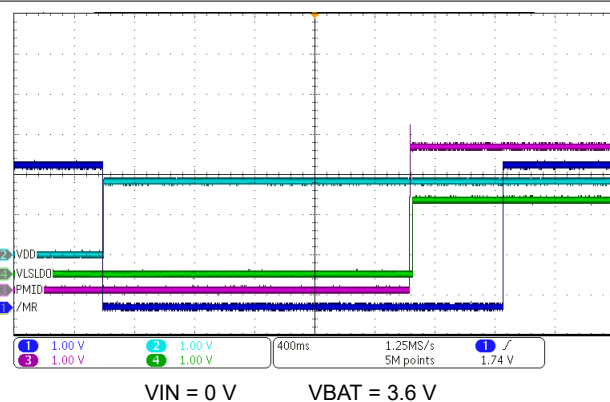


图 10-5. Power Up From Ship Mode with $\overline{\text{MR}}$ Press

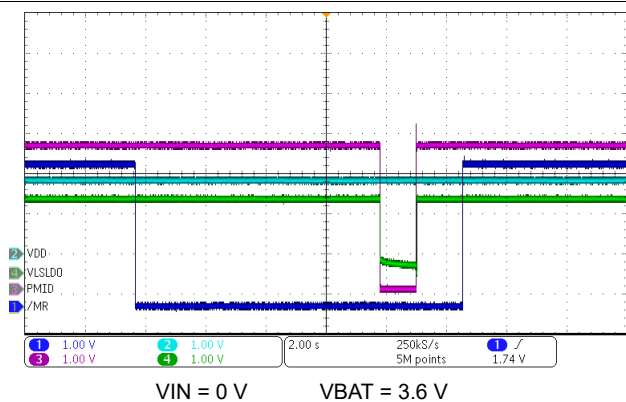


图 10-6. HW Reset on $\overline{\text{MR}}$ Long Button Press

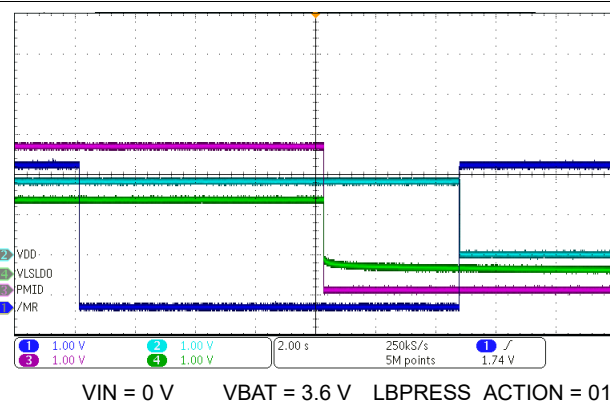
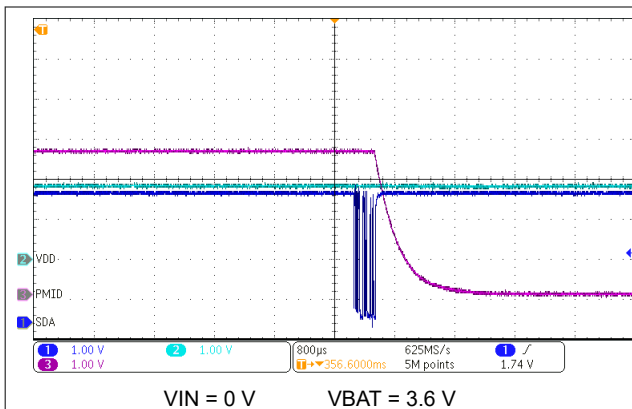
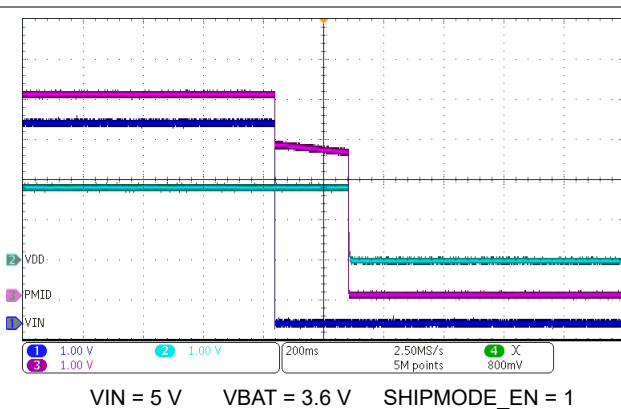
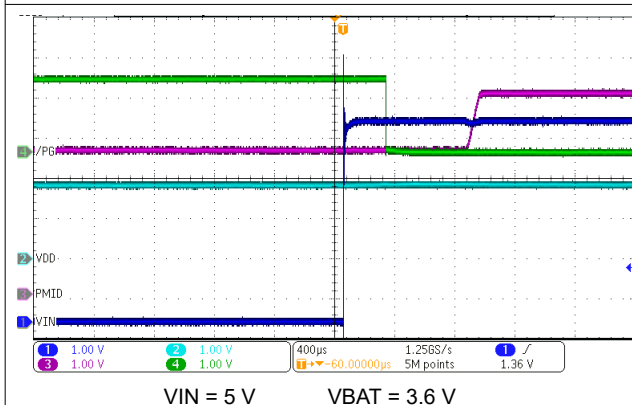
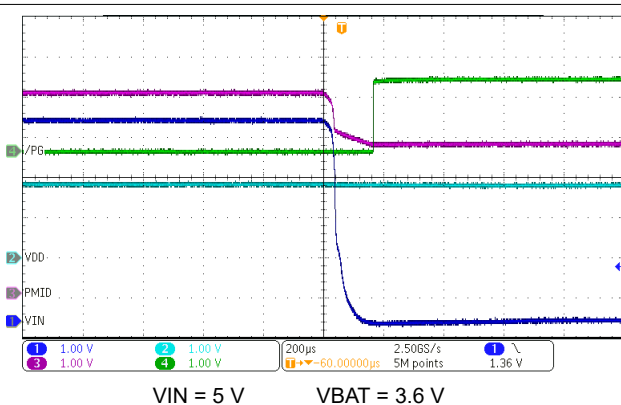
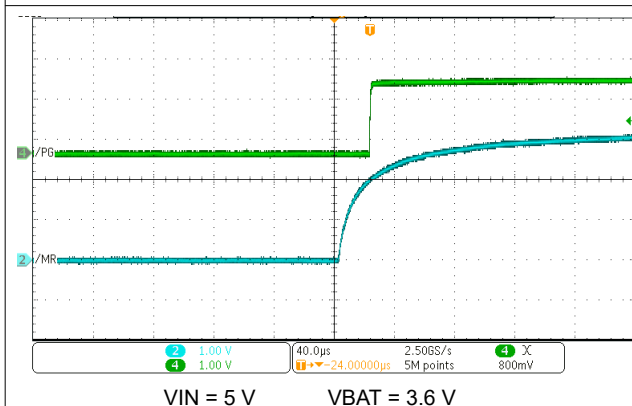
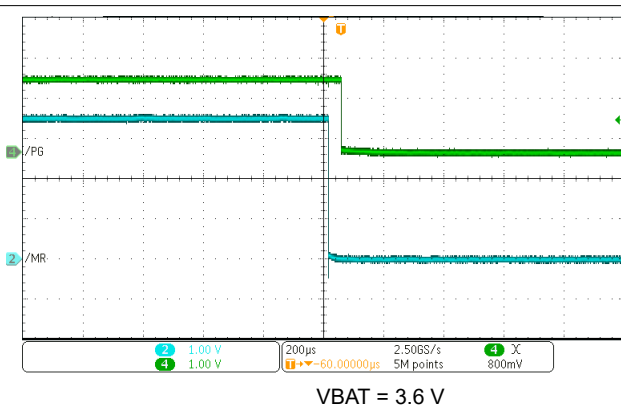
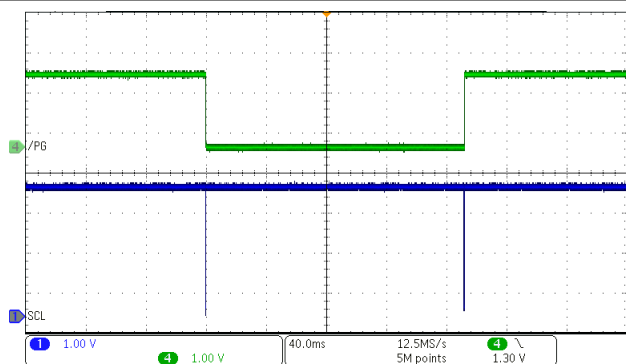


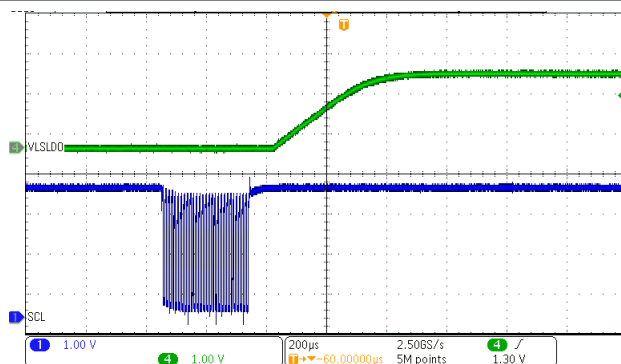
图 10-7. Ship Mode Entry with $\overline{\text{MR}}$ Long Button Press


 10-8. HW Reset Through I²C Command

 10-9. Ship Mode Entry on IN Supply Removal

 10-10. $\overline{\text{PG}}$ Power Good Function - IN Supply Insertion

 10-11. $\overline{\text{PG}}$ Power Good Function - IN Supply Removal

 10-12. $\overline{\text{PG}}$ $\overline{\text{MR}}$ Level Shift Function - $\overline{\text{MR}}$ Rising

 10-13. $\overline{\text{PG}}$ $\overline{\text{MR}}$ Level Shift Function - $\overline{\text{MR}}$ Falling



VBAT = 3.6 V

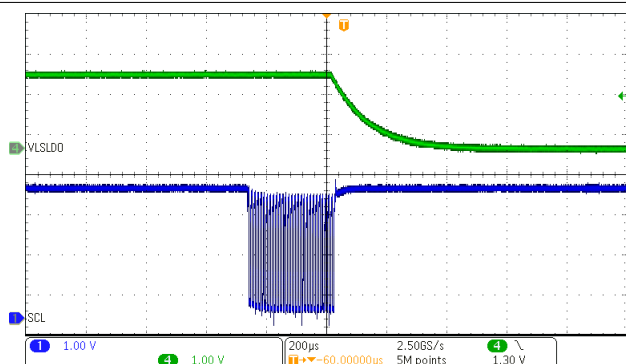
10-14. PG General Purpose Output Function - GPO_PG Bit Toggle



VBAT = 3.6 V

No load

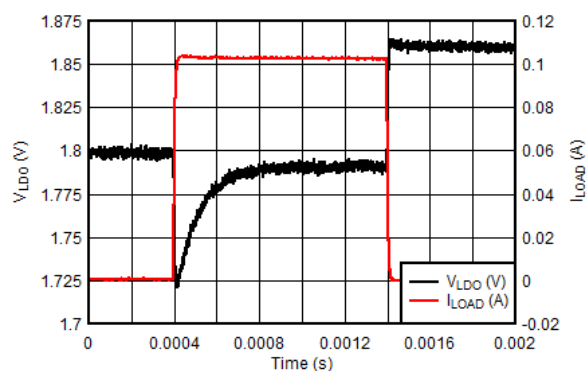
10-15. LDO Enable Through I²C (EN_LS_LDO)



VBAT = 3.6 V

No load

10-16. LDO Disable Through I²C (EN_LS_LDO)

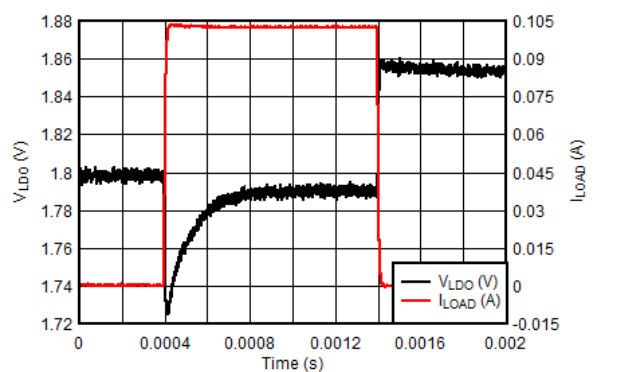


VIN = 0 V

VBAT = 3.6 V

VINLS = VPMID

10-17. LDO Load Transient - VLDO = 1.8 V

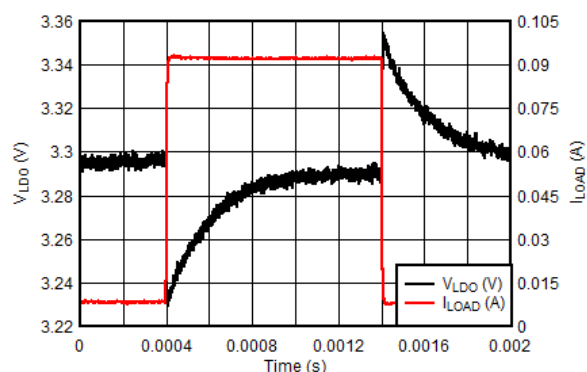


VIN = 0 V

VBAT = 2.4 V

VINLS = VPMID

10-18. LDO Load Transient - VLDO = 1.8 V

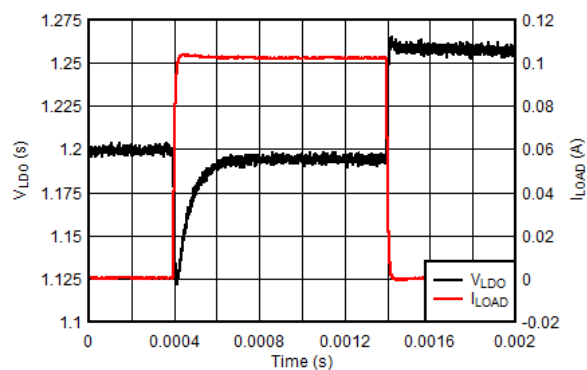


VIN = 0 V

VBAT = 3.8 V

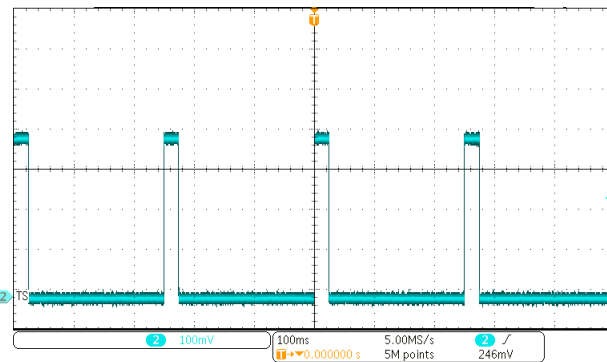
VINLS = VPMID

10-19. LDO Load Transient - VLDO = 3.3 V



VIN = 0 V VBAT = 3.6 V VINLS = VPMID

10-20. LDO Load Transient - VLDO = 1.2 V



VIN = 5V

10-21. TS Biasing and Voltage Behavior when VIN is Present

11 Power Supply Recommendations

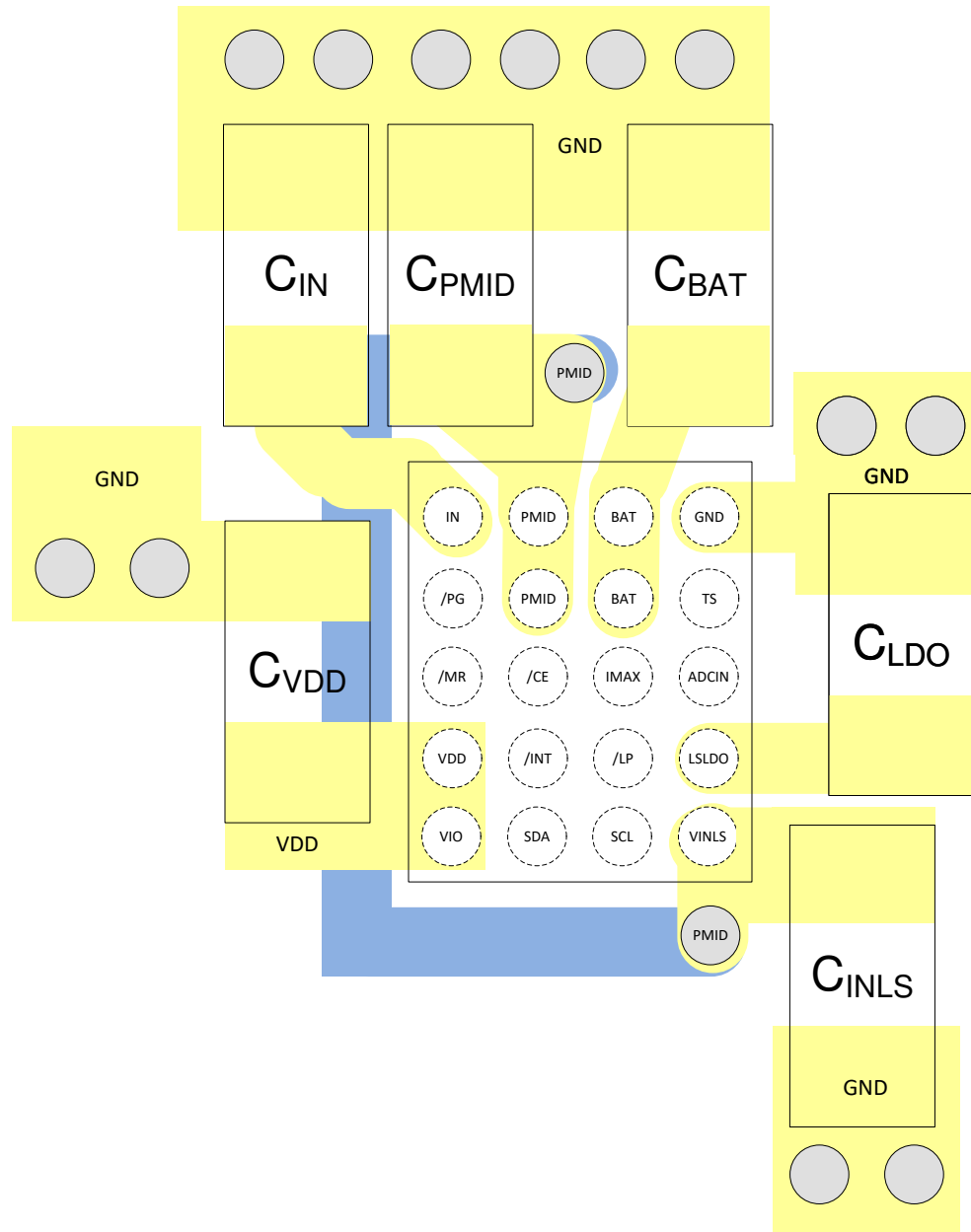
The BQ25150 requires the adapter or IN supply to be between 3.4 V and 5.5 V with at least 600-mA rating. The battery voltage must be higher than 2.4 V or $V_{BATUVLO}$ to ensure proper operation.

12 Layout

12.1 Layout Guidelines

- Have solid ground plane that is tied to the GND bump.
- Place LDO and VDD output capacitors as close as possible to the respective bumps and GND or ground plane with short copper trace connection.
- Place PMID capacitor as close to the PMID bump as possible and GND or ground plane.
- A bypass capacitor from VINLS to GND is recommended to be placed as close as possible to the VINLS bump.

12.2 Layout Example



 **12-1. Layout Example**

13 Device and Documentation Support

13.1 Device Support

13.1.1 サード・パーティ製品に関する免責事項

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13.2 Documentation Support

13.2.1 Related Documentation

For related documentation see the following: [BQ25150EVM Evaluation Module User's Guide](#), [BQ25150 Setup Guide](#) and [BQ25150 Setup Guide Tool](#)

13.3 ドキュメントの更新通知を受け取る方法

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13.7 用語集

[テキサス・インスツルメンツ用語集](#) この用語集には、用語や略語の一覧および定義が記載されています。

14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
BQ25150YFPR	Active	Production	DSBGA (YFP) 20	3000 LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25150
BQ25150YFPR.A	Active	Production	DSBGA (YFP) 20	3000 LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25150
BQ25150YFPT	Active	Production	DSBGA (YFP) 20	250 SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25150
BQ25150YFPT.A	Active	Production	DSBGA (YFP) 20	250 SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ25150

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ25150YFPR	DSBGA	YFP	20	3000	180.0	8.4	1.77	2.17	0.62	4.0	8.0	Q1
BQ25150YFPT	DSBGA	YFP	20	250	180.0	8.4	1.77	2.17	0.62	4.0	8.0	Q1

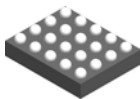
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ25150YFPR	DSBGA	YFP	20	3000	182.0	182.0	20.0
BQ25150YFPT	DSBGA	YFP	20	250	182.0	182.0	20.0

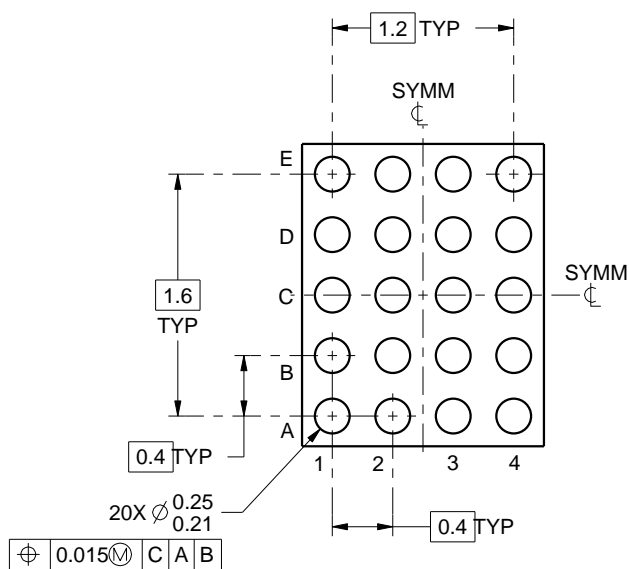
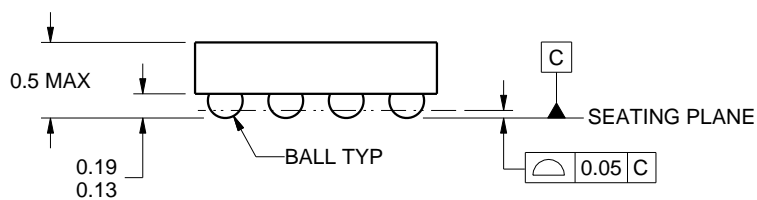
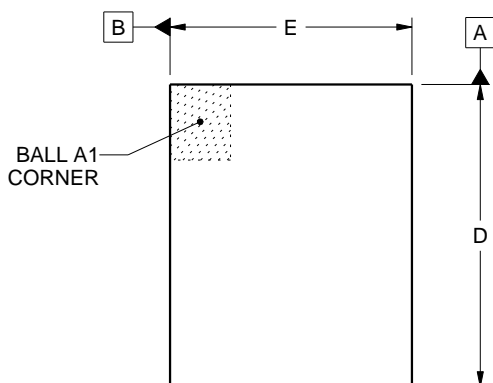
YFP0020



PACKAGE OUTLINE

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



D: Max = 2.045 mm, Min = 1.985 mm

E: Max = 1.645 mm, Min = 1.585 mm

4222895/A 04/2016

NOTES:

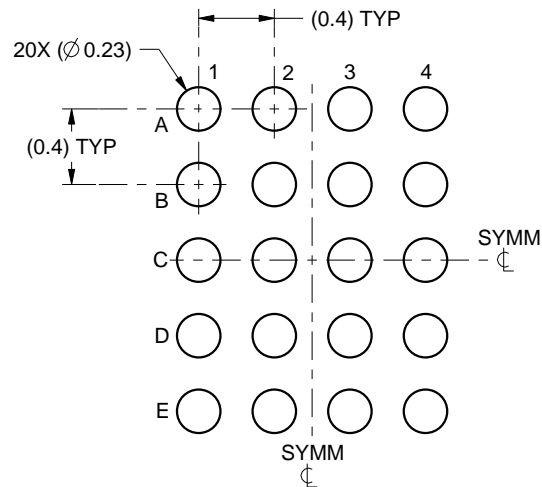
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

EXAMPLE BOARD LAYOUT

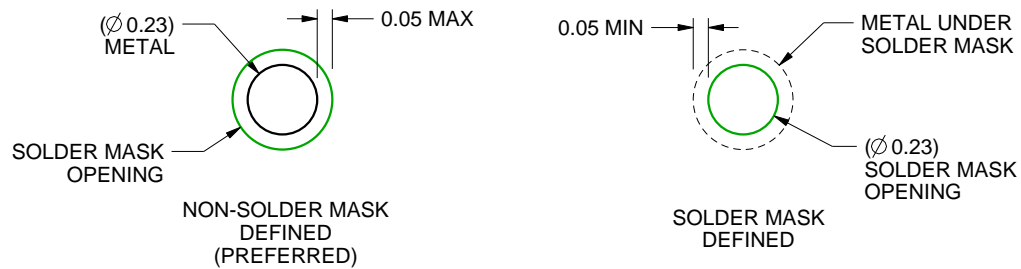
YFP0020

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



LAND PATTERN EXAMPLE
SCALE:25X



SOLDER MASK DETAILS
NOT TO SCALE

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NOTES: (continued)

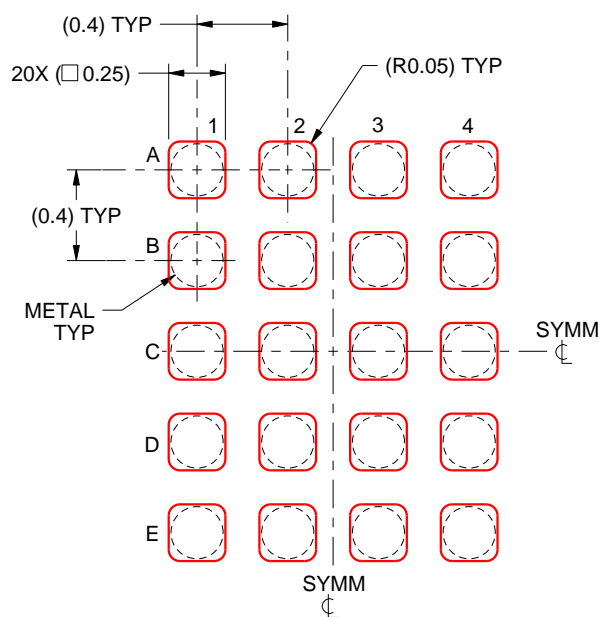
- Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. For more information, see Texas Instruments literature number SNVA009 (www.ti.com/lit/snva009).

EXAMPLE STENCIL DESIGN

YFP0020

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE:30X

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NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

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