

🕳 Sample &

🖥 Buy





Reference

Design

ADS7042

ZHCSD00C -JUNE 2014-REVISED DECEMBER 2015

Support &

Community

2.2

ADS7042 超低功耗、超小尺寸、12 位、 1MSPS、SAR ADC

Technical

Documents

特性 1

- 业界第一款具有毫微瓦功耗的逐次逼近寄存器 (SAR) 模数转换器 (ADC):
 - 1MSPS 和 1.8V AVDD 时为 234µW
 - 1MSPS 和 3V AVDD 时为 690µW
 - 100kSPS 和 3V AVDD 时为 69µW
 - 1kSPS 和 3V AVDD 时低于 1µW
- 业界最小的 SAR ADC: - 采用 X2QFN-8 封装, 封装尺寸为 2.25mm²
- 1MSPS 吞吐量目零延迟
- 宽工作范围:
 - AVDD: 1.65V 到 3.6V
 - DVDD: 1.65V 至 3.6V (与 AVDD 无关)
 - 温度范围: -40℃ 至 125℃
- 出色的性能:
 - 12 位分辨率且无丟码 (NMC)
 - 最大 ±1 最低有效位 (LSB) 的差分非线性 (DNL) 和积分非线性 (INL)
 - 70dB 的信噪比 (SNR) (3V AVDD 时)
 - - 80dB 的总谐波失真 (THD) (3V AVDD 时)
- 单极输入范围: 0V 至 AVDD
- 集成偏移校准
- 串行外设接口 (SPI)™- 兼容串口: 16MHz
- 符合 JESD8-7A 标准的数字 I/O •

2 应用

- 低功耗数据采集
- 电池供电类手持设备
- 液位传感器
- 超声波流量计
- 电机控制
- 可穿戴健身器
- 便携式医疗设备
- 硬盘 •
- 血糖仪

3 说明

Tools &

Software

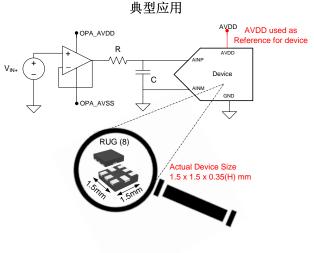
ADS7042 是一款 12 位、1MSPS、模数转换器 (ADC)。该器件支持较宽的模拟输入电压范围(1.65V 到 3.6V),并包含一个基于电容且内置采样保持电路 的逐次逼近寄存器 (SAR) ADC。串行外设接口 (SPI) 兼容串口由 CS 和 SCLK 信号控制。输入信号在 CS 下降沿进行采样,SCLK 用于转换和串行数据输出。此 器件支持宽范围的数字电源(1.65V 至 3.6V),可直 接连接到各类主机控制器。ADS7042 符合 JESD8-7A 标准的标称 DVDD 范围(1.65V 至 1.95V)。

ADS7042 采用 8 引脚微型引线 X2QFN 封装, 额定工 作温度范围为 -40℃ 至 125℃。此器件尺寸微小且功 耗极低,非常适合空间受限类电池供电 应用。

哭件信息(1)

| 部件名称 | 封装 | 封装尺寸(标称值) | | | | |
|---------|-------------------------|-----------------|--|--|--|--|
| | X2QFN (8) | 1.50mm x 1.50mm | | | | |
| ADS7042 | 超薄小外形尺寸封装 (VSSOP)(8) | 2.30mm x 2.00mm | | | | |

(1) 要了解所有可用封装,请见数据表末尾的可订购产品附录。



注: ADS7042 比 0805 (2012 公制) SMD 元件小。





目录

9

| 1 | 特性 | |
|---|------|-----------------------------------|
| 2 | 应用 | 1 |
| 3 | 说明 | |
| 4 | 修订 | 历史记录 |
| 5 | | Configuration and Functions 4 |
| 6 | | cifications |
| | 6.1 | Absolute Maximum Ratings5 |
| | 6.2 | ESD Ratings5 |
| | 6.3 | Recommended Operating Conditions5 |
| | 6.4 | Thermal Information 5 |
| | 6.5 | Electrical Characteristics 6 |
| | 6.6 | Timing Characteristics |
| | 6.7 | Typical Characteristics 9 |
| 7 | Para | ameter Measurement Information 14 |
| | 7.1 | Digital Voltage Levels 14 |
| 8 | Deta | ailed Description 15 |
| | 8.1 | Overview 15 |
| | 8.2 | Functional Block Diagram 15 |
| | 8.3 | Feature Description 16 |

4 修订历史记录

注: 之前版本的页码可能与当前版本有所不同。

| C | Changes from Revision B (February 2015) to Revision C | Page |
|---|---|------|
| • | Updated Figure 1 | 8 |
| • | Changed Serial Interface section: changed last half of first paragraph, changed Figure 34 | 19 |
| • | Changed Figure 37 | 22 |
| • | 添加了 <i>社区资源</i> 部分 | 33 |

Changes from Revision A (August 2014) to Revision B

| • | 已更改 宽工作电压范围 特性 要点: 已将 AVDD 的值从 1.8V 改为 1.65V | . 1 |
|---|---|------------------|
| • | 已更改 宽模拟输入电压范围下限至 1.65V (说明部分第 1 段) | . 1 |
| • | Changed ESD Ratings table to latest standards | 5 |
| • | Changed AVDD parameter minimum specification in Recommended Operating Conditions table to 1.65 V | . <mark>5</mark> |
| • | Changed E ₀ parameter uncalibrated test conditions in <i>Electrical Characteristics</i> table | 6 |
| • | Changed Maximum throughput rate parameter test conditions in <i>Electrical Characteristics</i> table | . <mark>6</mark> |
| • | Changed AVDD parameter minimum specification in <i>Electrical Characteristics</i> table | . 7 |
| • | Changed conditions for <i>Timing Characteristics</i> table: changed range of AVDD and added C _{LOAD} condition | . 8 |
| • | Changed t _{D_CKDO} parameter in <i>Timing Characteristics</i> table | 8 |
| • | Added f _{SCLK} minimum specification to <i>Timing Characteristics</i> table | 8 |
| • | Changed titles of Figure 26 to Figure 29 | |
| • | Changed Reference sub-section in Feature Description section | 16 |
| • | Changed range of second f _{CLK-CAL} parameter description in Table 2 | 21 |
| • | Changed range of second f _{CLK-CAL} parameter description in Table 3 | |
| • | Changed Reference Circuit section in Application Information | 25 |
| • | Added last two sentences to AVDD and DVDD Supply Recommendations section | 31 |



9.1 Application Information...... 23 9.2 Typical Applications 23 10 Power-Supply Recommendations 31 10.1 AVDD and DVDD Supply Recommendations...... 31 10.3 Optimizing Power Consumed by the Device 31 11 Layout...... 32 11.1 Layout Guidelines 32 11.2 Layout Example 32 12 器件和文档支持...... 33 12.4 静电放电警告...... 33 13 机械、封装和可订购信息...... 34

www.ti.com.cn

Page



Page

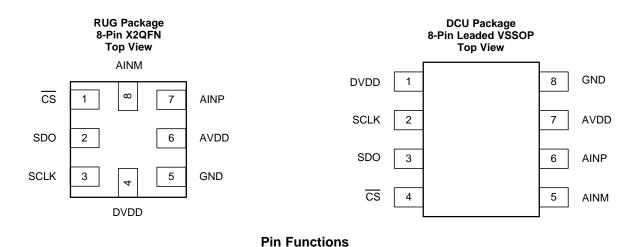
Changes from Original (June 2014) to Revision A

| • | 已更改产品预览数据表 | 1 |
|---|-------------|---|
| • | 已添加 TI 参考设计 | 1 |

TEXAS INSTRUMENTS

www.ti.com.cn

5 Pin Configuration and Functions



| PIN | | | | |
|-----------------|-------------------|---------------|---|--|
| NO. | | | | |
| NAME | RUG | DCU | I/O | DESCRIPTION |
| AINM | 8 | 5 | Analog input | Analog signal input, negative |
| AINP | 7 | 6 | Analog input | Analog signal input, positive |
| AVDD 6 7 | | Supply | Analog power-supply input, also provides the reference voltage to the ADC | |
| CS | CS 1 4 Digital in | | Digital input | Chip-select signal, active low |
| DVDD | 4 | 1 | Supply | Digital I/O supply voltage |
| GND | 5 | 8 | Supply | Ground for power supply, all analog and digital signals are referred to this pin |
| SCLK 3 2 Digita | | Digital input | Serial clock | |
| SDO | 2 | 3 | Digital output | Serial data out |



6 Specifications

6.1 Absolute Maximum Ratings⁽¹⁾

| | MIN | MAX | UNIT |
|---------------------------------------|------|------------|------|
| AVDD to GND | -0.3 | 3.9 | V |
| DVDD to GND | -0.3 | 3.9 | V |
| AINP to GND | -0.3 | AVDD + 0.3 | V |
| AINM to GND | -0.3 | 0.3 | V |
| Digital input voltage to GND | -0.3 | DVDD + 0.3 | V |
| Storage temperature, T _{stg} | -60 | 150 | °C |

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

| | | | VALUE | UNIT |
|--------------------|-------------------------|--|-------|------|
| V | Electrostatia discharge | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾ | ±2000 | V |
| V _(ESD) | Electrostatic discharge | Charged device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾ | ±1000 | V |

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

| | | MIN | MAX | UNIT |
|----------------|--------------------------------|------|-----|------|
| AVDD | Analog supply voltage range | 1.65 | 3.6 | V |
| DVDD | Digital supply voltage range | 1.65 | 3.6 | V |
| T _A | Operating free-air temperature | -40 | 125 | °C |

6.4 Thermal Information

| THERMAL METRIC ⁽¹⁾ | | ADS7042 | | | |
|-------------------------------|--|-------------|-------------|------|--|
| | THERMAL METRIC ⁽¹⁾ | RUG (X2QFN) | DCU (VSSOP) | UNIT | |
| | | 8 PINS | 8 PINS | | |
| R_{\thetaJA} | Junction-to-ambient thermal resistance | 177.5 | 235.8 | °C/W | |
| R _{0JC(top)} | Junction-to-case (top) thermal resistance | 51.5 | 79.8 | °C/W | |
| $R_{	extsf{	heta}JB}$ | Junction-to-board thermal resistance | 76.7 | 117.6 | °C/W | |
| ΨJT | Junction-to-top characterization parameter | 1.0 | 8.9 | °C/W | |
| Ψ _{JB} | Junction-to-board characterization parameter | 76.7 | 116.5 | °C/W | |
| R _{0JC(bot)} | Junction-to-case (bottom) thermal resistance | N/A | N/A | °C/W | |

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

ZHCSD00C – JUNE 2014-REVISED DECEMBER 2015

ISTRUMENTS www.ti.com.cn

EXAS

6.5 Electrical Characteristics

| | PARAMETER | 1 | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|----------------------|---|---------------------------|--|-------|-------|------------|--------------------|
| ANALOG I | NPUT | | | | | | |
| | Full-scale input voltage | je span ⁽¹⁾ | | 0 | | AVDD | V |
| | Absolute input | AINP to GND | | -0.1 | | AVDD + 0.1 | ., |
| | voltage range | AINM to GND | | -0.1 | | 0.1 | V |
| Cs | Sampling capacitance | e | | | 15 | | pF |
| SYSTEM F | PERFORMANCE | | | | | | |
| | Resolution | | | | 12 | | Bits |
| NMC | No missing codes | | | 12 | | | Bits |
| | late and a solid society. | | AVDD = 3 V | -1 | ±0.7 | 1 | LSB ⁽²⁾ |
| INL | Integral nonlinearity | | AVDD = 1.8 V | -2 | ±1 | 2 | 2 |
| | | | AVDD = 3 V | -0.99 | ±0.5 | 1 | |
| DNL | Differential nonlineari | ty | AVDD = 1.8 V | -0.99 | ±0.7 | 2 | LSB |
| | | Uncalibrated | AVDD = 1.65 V to 3.6 V | | ±12 | | LSB |
| Eo | Offset error | Calibrated ⁽³⁾ | AVDD = 3 V | -3 | ±0.5 | 3 | |
| | | Calibrated | AVDD = 1.8 V | -4 | ±1 | 4 | |
| dV _{OS} /dT | Offset error drift with | temperature | | | 5 | | ppm/°C |
| _ | Gain error | | AVDD = 3 V | -0.1 | ±0.05 | 0.1 | %FS |
| E _G | | | AVDD = 1.8 V | -0.2 | ±0.1 | 0.2 | %F3 |
| | Gain error drift with te | emperature | | | 2 | | ppm/°C |
| SAMPLING | G DYNAMICS | | | | | | |
| t _{ACQ} | Acquisition time | | | 200 | | | ns |
| | Maximum throughput | rate | 16-MHz SCLK, AVDD = 1.65 V to 3.6 V | | | 1 | MHz |
| DYNAMIC | CHARACTERISTICS | | | | | | |
| SNR | Signal-to-noise ratio ⁽⁴ | l) | f _{IN} = 2 kHz, AVDD = 3 V | 69 | 70 | | dB |
| SINK | Signal-to-hoise ratio | - | $f_{IN} = 2 \text{ kHz}, \text{ AVDD} = 1.8 \text{ V}$ | | 68 | | uВ |
| THD | Total harmonic distortion ⁽⁴⁾⁽⁵⁾ | | $f_{IN} = 2 \text{ kHz}, \text{ AVDD} = 3 \text{ V}$ | | -80 | | dB |
| SINAD | Signal-to-noise and d | istortion ⁽⁴⁾ | $f_{IN} = 2 \text{ kHz}, \text{ AVDD} = 3 \text{ V}$ | 68 | 69.5 | | dB |
| | Signal-to-noise and distortion ⁽⁴⁾ | | f_{IN} = 2 kHz, AVDD = 1.8 V | | 67.5 | | uD |
| SFDR | Spurious-free dynami | c range ⁽⁴⁾ | $f_{IN} = 2 \text{ kHz}, \text{ AVDD} = 3 \text{ V}$ | | 80 | | dB |
| BW _(fp) | Full-power bandwidth | | At -3 dB, AVDD = 3 V | | 25 | | MHz |

Ideal input span; does not include gain or offset error.
 LSB means least significant bit.

(2) (3) (4) Refer to the Offset Calibration section for more details. All specifications expressed in decibels (dB) refer to the full-scale input (FSR) and are tested with an input signal 0.5 dB below full-scale, unless otherwise specified..

Calculated on the first nine harmonics of the input frequency. (5)



ADS7042 ZHCSD00C – JUNE 2014–REVISED DECEMBER 2015

www.ti.com.cn

Electrical Characteristics (continued)

At $T_A = -40^{\circ}$ C to 125°C, AVDD = 3 V, DVDD = 1.65 V to 3.6 V, $f_{SAMPLE} = 1$ MSPS, and $V_{AINM} = 0$ V, unless otherwise noted.

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-------------------|--|---------------------------------|-------------|-----|------------|------|
| DIGITAL | INPUT/OUTPUT (CMOS Logic Family) | | | | | |
| VIH | High-level input voltage ⁽⁶⁾ | | 0.65 DVDD | | DVDD + 0.3 | V |
| V _{IL} | Low-level input voltage ⁽⁶⁾ | | -0.3 | | 0.35 DVDD | V |
| V | High-level output voltage ⁽⁶⁾ | At I _{source} = 500 µA | 0.8 DVDD | | DVDD | V |
| V _{OH} | | At I _{source} = 2 mA | DVDD - 0.45 | | DVDD | v |
| V _{OL} | Low-level output voltage ⁽⁶⁾ | At I _{sink} = 500 μA | 0 | | 0.2 DVDD | V |
| | Low-level output voltage | At I _{sink} = 2 mA | 0 | | 0.45 | v |
| POWER-S | SUPPLY REQUIREMENTS | | | | | |
| AVDD | Analog supply voltage | | 1.65 | 3 | 3.6 | V |
| DVDD | Digital I/O supply voltage | | 1.65 | 3 | 3.6 | V |
| | | At 1 MSPS with AVDD = 3 V | | | 230 | |
| I _{AVDD} | Analog supply current | At 100 kSPS with AVDD = 3 V | | | 23 | μΑ |
| | | At 1 MSPS with AVDD = 1.8 V | | 130 | | |
| | | At 1 MSPS with AVDD = 3 V | | | 690 | |
| PD | Power dissipation | At 100 kSPS with AVDD = 3 V | | | 69 | μW |
| | | At 1 MSPS with AVDD = 1.8 V | | 234 | | |

(6) Digital voltage levels comply with the JESD8-7A standard for DVDD from 1.65 V to 1.95 V. See the *Digital Voltage Levels* section for more details.

TEXAS INSTRUMENTS

www.ti.com.cn

ADS7042

ZHCSD00C-JUNE 2014-REVISED DECEMBER 2015

6.6 Timing Characteristics

All specifications are at $T_A = -40^{\circ}$ C to 125°C, AVDD = 1.65 V to 3.6 V, DVDD = 1.65 V to 3.6 V, and C_{LOAD} on SDO = 20 pF, unless otherwise specified.

| | | MIN | TYP MAX | UNIT |
|-------------------------|---|-------|---|-------------------|
| TIMING SPECI | FICATIONS | | | |
| f _{THROUGHPUT} | Throughput | | 1 | MSPS |
| t _{CYCLE} | Cycle time | 1 | | μs |
| t _{CONV} | Conversion time | | 12.5 × t _{SCLK} + t _{SU_CSCK} | ns |
| t _{DV_CSDO} | Delay time: CS falling to data enable | | 10 | ns |
| | Delay time: SCLK falling to (next) data valid on DOUT, AVDD = 1.8 V to 3.6 V | | 30 | ns |
| t _{D_CKDO} | Delay time: SCLK falling to (next) data valid on DOUT, AVDD = 1.65 V to 1.8 V | | 50 | ns |
| t _{DZ_CSDO} | Delay time: CS rising to DOUT going to 3-state | 5 | | ns |
| TIMING REQUI | REMENTS | | | |
| t _{ACQ} | Acquisition time | 200 | | ns |
| f _{SCLK} | SCLK frequency | 0.016 | 16 | MHz |
| t _{SCLK} | SCLK period | 62.5 | | ns |
| t _{PH_CK} | SCLK high time | 0.45 | 0.55 | t _{SCLK} |
| t _{PL_CK} | SCLK low time | 0.45 | 0.55 | t _{SCLK} |
| t _{PH_CS} | CS high time | 60 | | ns |
| t _{su_cscк} | Setup time: CS falling to SCLK falling | 15 | | ns |
| t _{D_CKCS} | Delay time: last SCLK falling to CS rising | 10 | | ns |

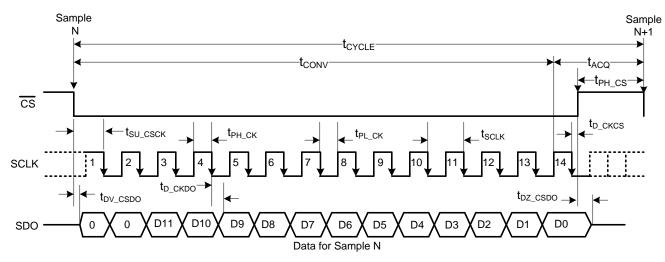
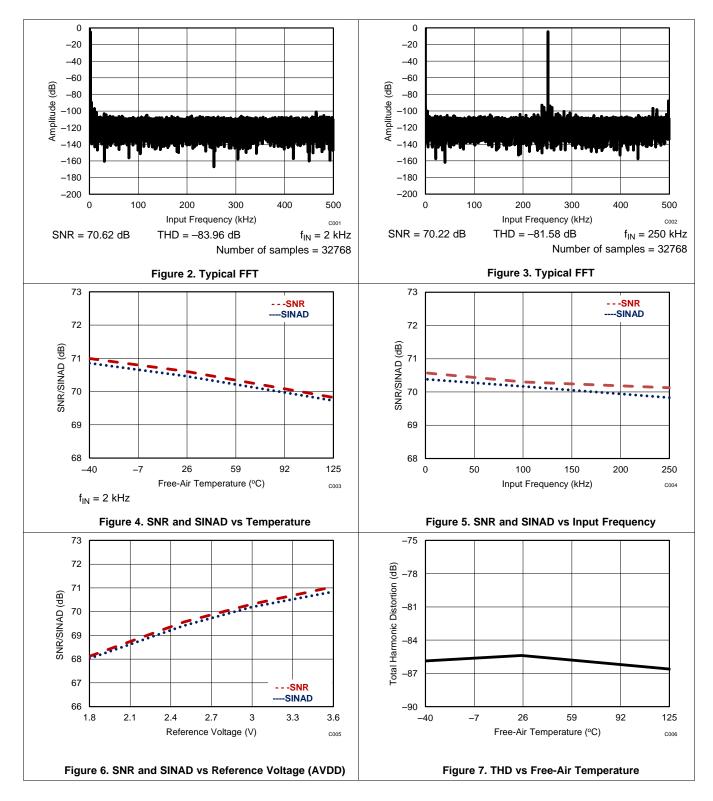


Figure 1. Timing Diagram



6.7 Typical Characteristics



ADS7042

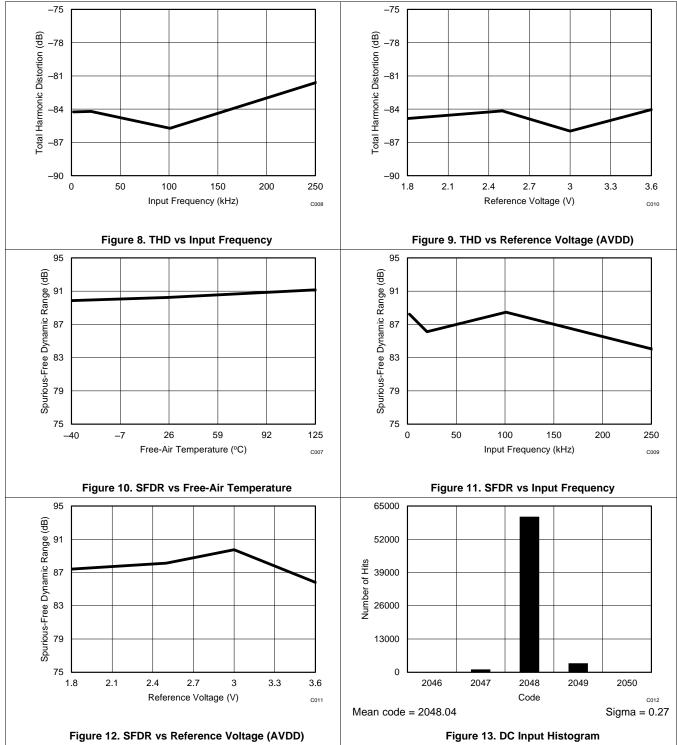
ZHCSD00C-JUNE 2014-REVISED DECEMBER 2015

www.ti.com.cn

ISTRUMENTS

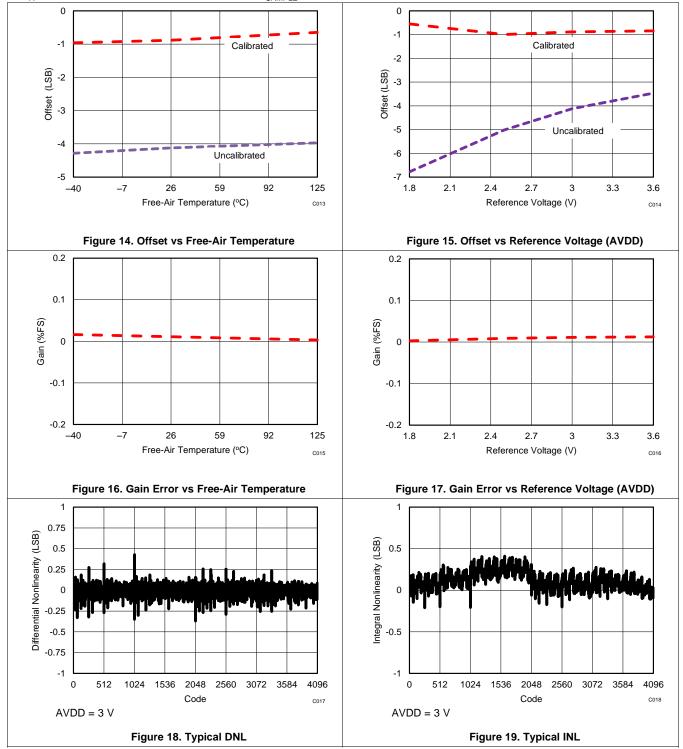
EXAS

Typical Characteristics (continued)





Typical Characteristics (continued)



ADS7042

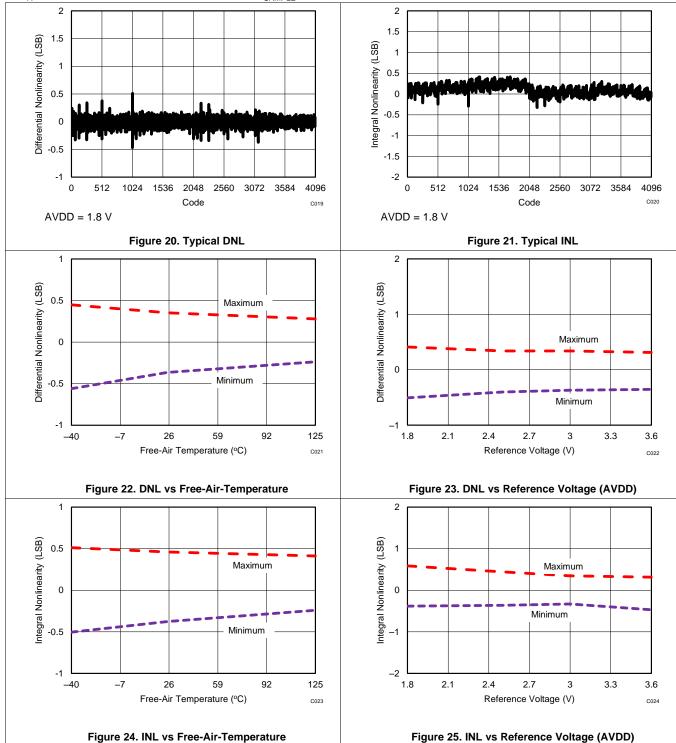
ZHCSD00C -JUNE 2014-REVISED DECEMBER 2015

www.ti.com.cn

STRUMENTS

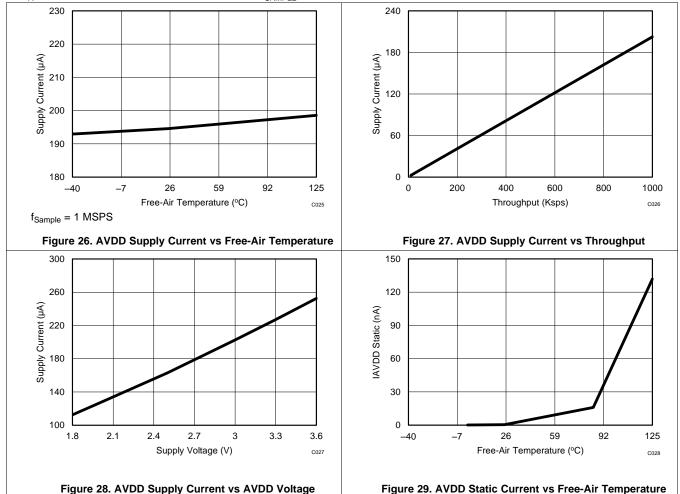
XAS

Typical Characteristics (continued)





Typical Characteristics (continued)



7 Parameter Measurement Information

7.1 Digital Voltage Levels

The device complies with the JESD8-7A standard for DVDD from 1.65 V to 1.95 V. Figure 30 shows voltage levels for the digital input and output pins.

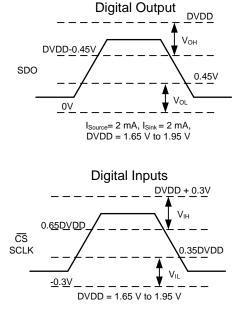


Figure 30. Digital Voltage Levels as per the JESD8-7A Standard





8 Detailed Description

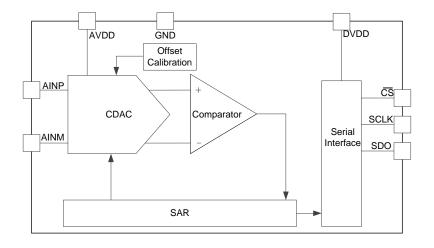
8.1 Overview

The ADS7042 is an ultralow-power, ultra-small analog-to-digital converter (ADC) that supports a wide analog input range. The analog input range for the device is defined by the AVDD supply voltage. The device samples the input voltage across the AINP and AINM pins on the CS falling edge and starts the conversion. The clock provided on the SCLK pin is used for conversion and data transfer. During conversions, both the AINP and AINM pins are disconnected from the sampling circuit. After the conversion completes, the sampling capacitors are reconnected across the AINP and AINM pins and the ADS7042 enters acquisition phase.

The device has an internal offset calibration. The offset calibration can be initiated by the user either on power-up or during normal operation; see the *Offset Calibration* section for more details.

The device also provides a simple serial interface to the host controller and operates over a wide range of digital power supplies. The ADS7042 requires only a 16-MHz SCLK for supporting a throughput of 1 MSPS. The digital interface also complies with the JESD8-7A (normal range) standard. The *Functional Block Diagram* section provides a block diagram of the device.

8.2 Functional Block Diagram



ADS7042 ZHCSD00C – JUNE 2014 – REVISED DECEMBER 2015



www.ti.com.cn

8.3 Feature Description

8.3.1 Reference

The device uses the analog supply voltage (AVDD) as a reference, as shown in Figure 31. TI recommends decoupling the AVDD pin with a 1- μ F, low equivalent series resistance (ESR) ceramic capacitor. The minimum capacitor value required for AVDD is 200 nF. The AVDD pin functions as a switched capacitor load to the source powering AVDD. The decoupling capacitor provides the instantaneous charge required by the internal circuit and helps in maintaining a stable dc voltage on the AVDD pin. TI recommends powering the AVDD pin with a low output impedance and low-noise regulator (such as the TPS79101).

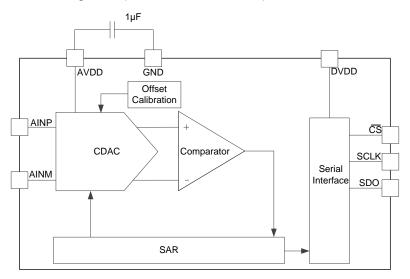


Figure 31. Reference for the Device



Feature Description (continued)

8.3.2 Analog Input

The device supports single-ended analog inputs. The ADC samples the difference between AINP and AINM and converts for this voltage. The device is capable of accepting a signal from –100 mV to 100 mV on the AINM input and is useful in systems where the sensor or signal-conditioning block is far from the ADC. In such a scenario, there can be a difference between the ground potential of the sensor or signal conditioner and the ADC ground. In such cases, use separate wires to connect the ground of the sensor or signal conditioner to the AINM pin. The AINP input is capable of accepting signals from 0 V to AVDD. Figure 32 represents the equivalent analog input circuits for the sampling stage. The device has a low-pass filter followed by the sampling switch and sampling capacitor. The sampling switch is represented by an R_s (typically 50 Ω) resistor in series with an ideal switch and C_s (typically 15 pF) is the sampling capacitor. The ESD diodes are connected from both analog inputs to AVDD and ground.

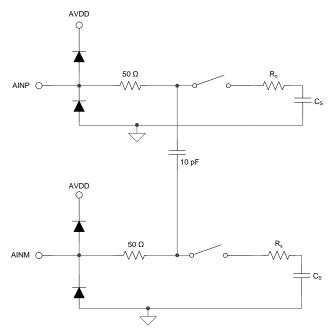


Figure 32. Equivalent Input Circuit for the Sampling Stage

The analog input full-scale range (FSR) is equal to the reference voltage of the ADC. The reference voltage for the device is equal to the analog supply voltage (AVDD). Thus, the device FSR can be determined by Equation 1:

$$FSR = V_{REF} = AVDD$$

8.3.3 ADC Transfer Function

The device output is in straight binary format. The device resolution for a single-ended input can be computed by Equation 2:

$$1 \text{ LSB} = V_{\text{REF}} / 2^{\text{N}}$$

where:

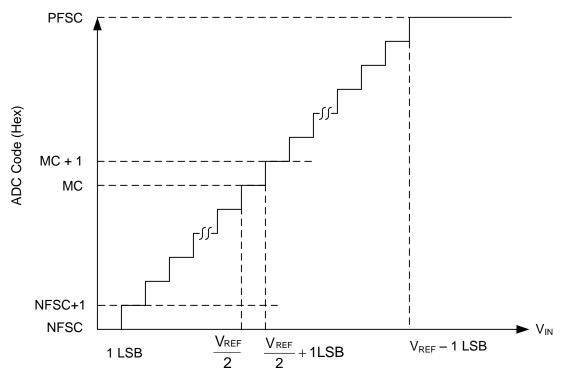
- V_{REF} = AVDD and
- N = 12

(2)

(1)

Feature Description (continued)

Figure 33 and Table 1 show the ideal transfer characteristics for the device.



Single-Ended Analog Input (AINP – AINM)



| INPUT VOLTAGE (AINP – AINM) | CODE | DESCRIPTION | IDEAL OUTPUT CODE |
|---|----------|--------------------------|-------------------|
| ≤1 LSB | NFSC | Negative full-scale code | 000 |
| 1 LSB to 2 LSBs | NFSC + 1 | — | 001 |
| $(V_{REF} / 2)$ to $(V_{REF} / 2)$ + 1 LSB | MC | Mid code | 800 |
| (V _{REF} / 2) + 1 LSB to (V _{REF} / 2) + 2 LSBs | MC + 1 | _ | 801 |
| ≥ V _{REF} – 1 LSB | PFSC | Positive full-scale code | FFF |

Table 1. Transfer Characteristics



8.3.4 Serial Interface

ADS7042

The device supports a simple, SPI-compatible interface to the external host. The \overline{CS} signal defines one conversion and serial transfer frame. A frame starts with a \overline{CS} falling edge and ends with a \overline{CS} rising edge. The SDO pin outputs the ADC conversion results. Figure 34 shows a detailed timing diagram for the serial interface. A minimum delay of t_{SU_CSCK} must elapse between the \overline{CS} falling edge and the first SCLK falling edge. The device uses the clock provided on the SCLK pin for conversion and data transfer. The conversion result is available on the SDO pin on the \overline{CS} falling edge. Subsequent bits (starting with another 0 followed by the conversion result) are launched on the SDO pin on subsequent SCLK falling edges. The SDO output remains low after 14 SCLKs. A \overline{CS} rising edge ends the frame and brings the serial data bus to 3-state. For acquisition of the next sample, a minimum time of t_{ACQ} must be provided after the conversion of the current sample is completed. For details on timing specifications, see the *Timing Characteristics* table.

The device initiates an offset calibration on the first \overline{CS} falling edge after power-up and the SDO output remains low during the first serial transfer frame after power-up. For further details, refer to the *Offset Calibration* section.

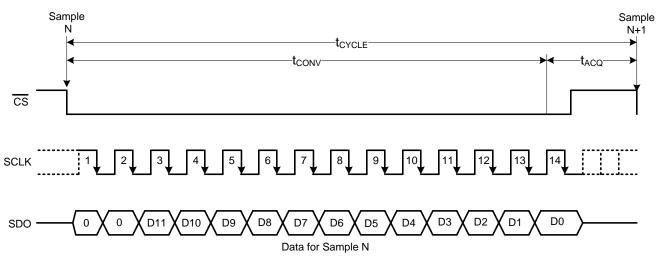


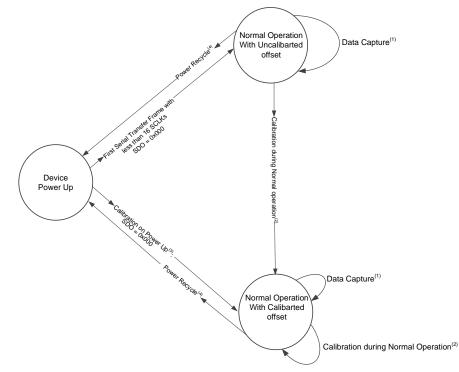
Figure 34. Serial Interface Timing Diagram



8.4 Device Functional Modes

8.4.1 Offset Calibration

The ADS7042 includes a feature to calibrate the device internal offset. During offset calibration, the analog input pins (AINP and AINM) are disconnected from the sampling stage. The device includes an internal offset calibration register (OCR) that stores the offset calibration result. The OCR is an internal register and cannot be accessed by the user through the serial interface. The OCR is reset to zero on power-up. Therefore, TI recommends calibrating the offset on power-up to bring the offset within the specified limits. If the operating temperature or analog supply voltage reflect a significant change, the offset can be recalibrated during normal operation. Figure 35 shows the offset calibration process.



- (1) See the *Timing Characteristics* section for timing specifications.
- (2) See the Offset Calibration During Normal Operation section for details.
- (3) See the Offset Calibration on Power-Up section for details.
- (4) The power recycle on the AVDD supply is required to reset the offset calibration and to bring the device to a power-up state.

Figure 35. Offset Calibration



Device Functional Modes (continued)

8.4.1.1 Offset Calibration on Power-Up

The device initiates offset calibration on the first \overline{CS} falling edge after <u>power-up</u> and calibration completes if the \overline{CS} pin remains low for at least 16 SCLK falling edges after the first \overline{CS} falling edge. The SDO output remains low during calibration. The minimum acquisition time must be provided after calibration for acquiring the first sample. If the device is not provided with at least 16 SCLKs during the first serial transfer frame after power-up, the OCR is not updated. Table 2 provides the timing parameters for offset calibration on power-up.

For subsequent samples, the device adjusts the conversion results with the value stored in the OCR. The conversion result adjusted with the value stored in OCR is provided by the device on the SDO output. Figure 36 shows the timing diagram for offset calibration on power-up.

| | | MIN | TYP | MAX | UNIT |
|--------------------------|---|----------------------|-----|-----|------|
| f _{CLK-CAL} | SCLK frequency for calibration for 2.25 V < AVDD < 3.6 V | | | 16 | MHz |
| f _{CLK-CAL} | SCLK frequency for calibration for 1.65 V < AVDD < 2.25 V | | | 12 | MHz |
| t _{POWERUP-CAL} | Calibration time at power-up | 15 t _{SCLK} | | | ns |
| t _{ACQ} | Acquisition time | 200 | | | ns |
| t _{PH_CS} | CS high time | t _{ACQ} | | | ns |
| t _{su_cscк} | Setup time: CS falling to SCLK falling | 15 | | | ns |
| t _{D_CKCS} | Delay time: last SCLK falling to \overline{CS} rising | 10 | | | ns |



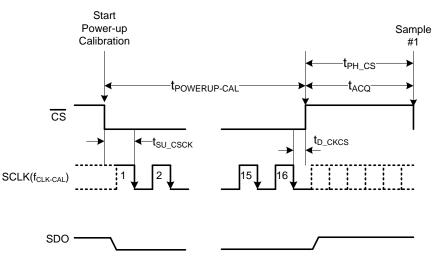


Figure 36. Offset Calibration on Power-Up Timing Diagram



8.4.1.2 Offset Calibration During Normal Operation

Offset calibration can be done during normal device operation if at least 32 SCLK falling edges are provided in one serial transfer frame. During the first 14 SCLKs, the device converts the sample acquired on the CS falling edge and provides data on the SDO output. The device initiates the offset calibration on the 17th SCLK falling edge and calibration completes on the 32nd SCLK falling edge. The SDO output remains low after the 14th SCLK falling edge and SDO goes to 3-state after CS goes high. If the device is provided with less than 32 SCLKs during a serial transfer frame, the OCR is not updated. Table 3 provides the timing parameters for offset calibration during normal operation.

For subsequent samples, the device adjusts the conversion results with the value stored in the OCR. The conversion result adjusted with the value stored in the OCR is provided by the device on the SDO output. Figure 37 shows the timing diagram for offset calibration during normal operation.

| | | MIN | TYP | MAX | UNIT |
|----------------------|---|----------------------|-----|-----|------|
| f _{CLK-CAL} | SCLK frequency for calibration for 2.25 V < AVDD < 3.6 V | | | 16 | MHz |
| f _{CLK-CAL} | SCLK frequency for calibration for 1.65 V < AVDD < 2.25 V | | | 12 | MHz |
| t _{CAL} | Calibration time during normal operation | 15 t _{SCLK} | | | ns |
| t _{ACQ} | Acquisition time | 200 | | | ns |
| t _{PH_CS} | CS high time | t _{ACQ} | | | ns |
| t _{SU_CSCK} | Setup time: CS falling to SCLK falling | 15 | | | ns |
| t _{D_CKCS} | Delay time: last SCLK falling to \overline{CS} rising | 10 | | | ns |

Table 3. Offset Calibration During Normal Operation

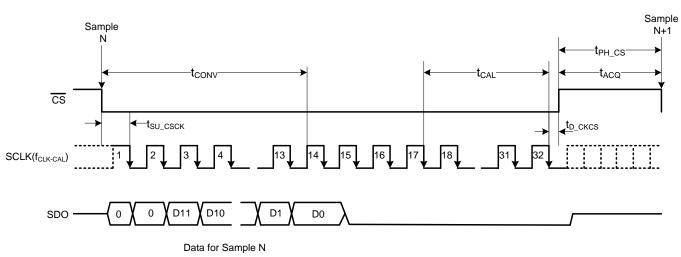


Figure 37. Offset Calibration During Normal Operation Timing Diagram



9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The two primary circuits required to maximize the performance of a high-precision, successive approximation register (SAR), analog-to-digital converter (ADC) are the input driver and the reference driver circuits. This section details some general principles for designing the input driver circuit, reference driver circuit, and provides some application circuits designed for the ADS7042.

9.2 Typical Applications

9.2.1 Single-Supply DAQ with the ADS7042

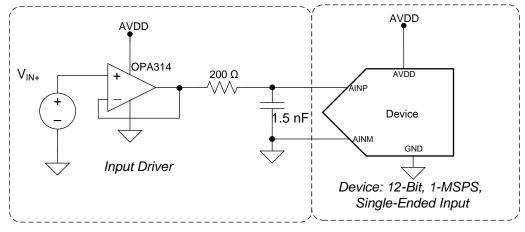


Figure 38. DAQ Circuit: Single-Supply DAQ

9.2.1.1 Design Requirements

The goal of this application is to design a single-supply digital acquisition (DAQ) circuit based on the ADS7042 with SNR greater than 68 dB and THD less than -80 dB for input frequencies of 2.5 kHz at a throughput of 1 MSPS.

9.2.1.2 Detailed Design Procedure

The input driver circuit for a high-precision ADC mainly consists of two parts: a driving amplifier and an antialiasing filter. Careful design of the front-end circuit is critical to meet the linearity and noise performance of a high-precision ADC.

ADS7042 ZHCSD00C – JUNE 2014 – REVISED DECEMBER 2015



Typical Applications (continued)

9.2.1.2.1 Antialiasing Filter

Converting analog-to-digital signals requires sampling an input signal at a rate greater than or equal to the Nyquist rate. Any higher frequency content in the input signal beyond half the sampling frequency is digitized and folded back into the low-frequency spectrum. This process is called *aliasing*. Therefore, an external, antialiasing filter must be used to remove the harmonic content from the input signal before being sampled by the ADC. An antialiasing filter is designed as a low-pass RC filter, for which the 3-dB bandwidth is optimized for noise, response time, and throughput. For dc signals with fast transients (including multiplexed input signals), a high-bandwidth filter is designed to allow accurately settling the signal at the ADC inputs during the small acquisition time window. Figure 39 provides the equation for determining the bandwidth of the antialiasing filter.

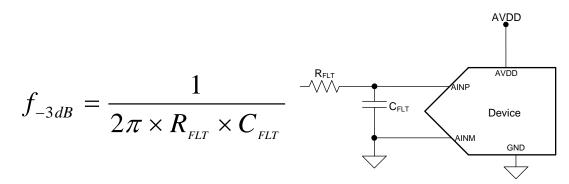


Figure 39. Antialiasing Filter

For ac signals, the filter bandwidth must be kept low to band limit the noise fed into the ADC input, thereby increasing the signal-to-noise ratio (SNR) of the system. Besides filtering the noise from the front-end drive circuitry, the RC filter also helps attenuate the sampling charge injection from the switched-capacitor input stage of the ADC. A filter capacitor, C_{FLT} , is connected across the ADC inputs. This capacitor helps reduce the sampling charge injection and provides a charge bucket to quickly charge the internal sample-and-hold capacitors during the acquisition process. As a rule of thumb, the value of this capacitor is at least 20 times the specified value of the ADC sampling capacitance. For this device, the input sampling capacitance is equal to 15 pF. Thus, the value of C_{FLT} is greater than 300 pF. Select a COG- or NPO-type capacitor because these capacitor types have a high-Q, low-temperature coefficient, and stable electrical characteristics under varying voltages, frequency, and time.

Note that driving capacitive loads can degrade the phase margin of the input amplifiers, thus making the amplifier marginally unstable. To avoid amplifier stability issues, series isolation resistors (R_{FLT}) are used at the output of the amplifiers. A higher value of R_{FLT} is helpful from the amplifier stability perspective, but adds distortion as a result of interactions with the nonlinear input impedance of the ADC. Distortion increases with source impedance, input signal frequency, and input signal amplitude. Therefore, the selection of R_{FLT} requires balancing the stability and distortion of the design.

The input amplifier bandwidth is typically much higher than the cutoff frequency of the antialiasing filter. Thus, TI strongly recommends performing a SPICE simulation to confirm that the amplifier has more than 40° phase margin with the selected filter. Simulation is critical because even with high-bandwidth amplifiers, some amplifiers can require more bandwidth than others to drive similar filters.



Typical Applications (continued)

9.2.1.2.2 Input Amplifier Selection

Selection criteria for the input amplifiers is highly dependent on the input signal type and the performance goals of the data acquisition system. Some key amplifier specifications to consider when selecting an appropriate amplifier to drive the inputs of the ADC are:

• Small-signal bandwidth: Select the small-signal bandwidth of the input amplifiers to be high enough to settle the input signal in the acquisition time of the ADC. Higher bandwidth reduces the closed-loop output impedance of the amplifier, thus allowing the amplifier to more easily drive the low cutoff frequency RC filter at the ADC inputs. Higher bandwidth also minimizes the harmonic distortion at higher input frequencies. In order to maintain the overall stability of the input driver circuit, the select the amplifier bandwidth as described in Equation 3.

$$GBW \geq 4 \times \frac{1}{2\pi \times R_{\text{FLT} \times} C_{\text{FLT}}}$$

where:

- GBW = unity gain bandwidth
- Noise: Noise contribution of the front-end amplifiers must be low enough to prevent any degradation in SNR performance of the system. As a rule of thumb, to ensure that the noise performance of the data acquisition system is not limited by the front-end circuit, keep the total noise contribution from the front-end circuit below 20% of the input-referred noise of the ADC. Noise from the input driver circuit is band limited by designing a low cutoff frequency RC filter, as explained in Equation 4.

$$N_{G} \times \sqrt{\left(\frac{V_{1/f}_AMP_PP}{6.6}\right)^{2} + e^{2}n_RMS} \times \frac{\pi}{2} \times f_{-3dB}} \le \frac{1}{5} \times \frac{V_{REF}}{2\sqrt{2}} \times 10^{-\left(\frac{SNR(dB)}{20}\right)}$$

where:

- V_{1/f AMP PP} is the peak-to-peak flicker noise in μVRMS,
- en RMS is the amplifier broadband noise,
- f_{-3dB} is the -3-dB bandwidth of the RC filter, and
- N_G is the noise gain of the front-end circuit, which is equal to 1 in the buffer configuration.
- Settling time: For dc signals with fast transients that are common in a multiplexed application, the input signal must settle to the desired accuracy at the inputs of the ADC during the acquisition time window. This condition is critical to maintain the overall linearity performance of the ADC. Typically, the amplifier data sheets specify the output settling performance only up to 0.1% to 0.001%, which may not be sufficient for the desired accuracy. Therefore, always verify the settling behavior of the input driver with TINA[™]-SPICE simulations before selecting the amplifier.

The OPA314 is selected for this application for its rail-to-rail input and output swing, low-noise (14 nV/ \sqrt{Hz}), and low-power (150 µA) performance to support a single-supply data acquisition circuit.

9.2.1.2.3 Reference Circuit

The analog supply voltage of the device is also used as a voltage reference for conversion. TI recommends decoupling the AVDD pin with a 1- μ F, low-ESR ceramic capacitor. The minimum capacitor value required for AVDD is 200 nF.

ZHCSD00C-JUNE 2014-REVISED DECEMBER 2015

ADS7042

(3)

(4)

25

TEXAS INSTRUMENTS

www.ti.com.cn

Typical Applications (continued)

9.2.1.3 Application Curve

Figure 40 shows the FFT plot for the ADS7042 with a 2.5-kHz input frequency used for the circuit in Figure 38.

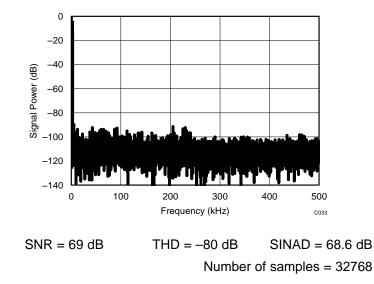


Figure 40. Test Results for the ADS7042 and OPA314 for a 2.5-kHz Input



Typical Applications (continued)

9.2.2 DAQ Circuit with the ADS7042 for Maximum SINAD

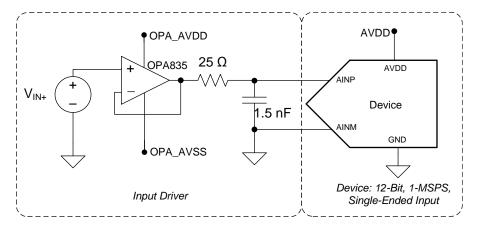


Figure 41. ADS7042 DAQ Circuit: Maximum SINAD for Input Frequencies up to 250 kHz

9.2.2.1 Design Requirements

The goal of this application is to design a data acquisition circuit based on the ADS7042 with SINAD greater than 69.5 dB for input frequencies up to 250 kHz.

9.2.2.2 Detailed Design Procedure

To achieve a SINAD of 69.5 dB, the operational amplifier must have high bandwidth in order to settle the input signal within the acquisition time of the ADC. The operational amplifier must have low noise to keep the total system noise below 20% of the input-referred noise of the ADC. For the application circuit shown in Figure 41, the OPA835 is selected for its high bandwidth (56 MHz) and low noise (9.3 nV/ \sqrt{Hz}).



For a step-by-step design procedure, circuit schematics, bill of materials, PCB files, simulation results, and test results, refer to TI Precision Design TIPD168, *Three 12-Bit Data Acquisition Reference Designs Optimized for Low Power and Ultra-Small Form Factor* (TIDU390).

ADS7042

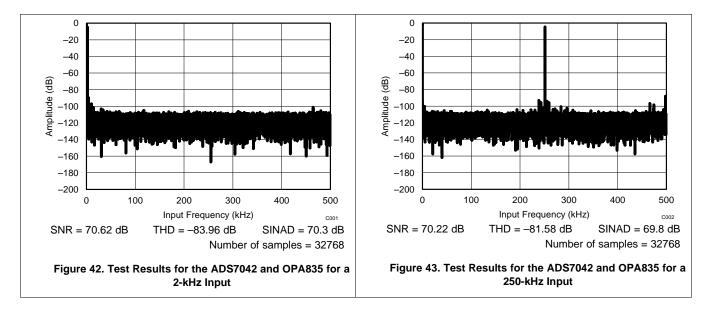
ZHCSD00C-JUNE 2014-REVISED DECEMBER 2015



www.ti.com.cn

9.2.2.3 Application Curves

Figure 42 shows the FFT plot for the ADS7042 with a 2-kHz input frequency used for the circuit in Figure 41. Figure 43 shows the FFT plot for the ADS7042 with a 250-kHz input frequency used for the circuit in Figure 41.





9.2.3 12-Bit, 10-kSPS DAQ Circuit Optimized for DC Sensor Measurements

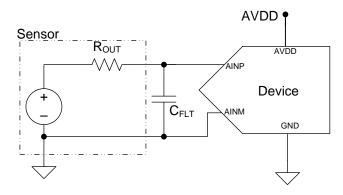


Figure 44. Interfacing the Device Directly with Sensors

In applications where the input is very slow moving and the overall system ENOB is not a critical parameter, a DAQ circuit can be designed without the input driver for the ADC. This type of a use case is of particular interest for applications in which the primary goal is to achieve the absolute lowest power possible. Typical applications that fall into this category are low-power sensor applications (such as temperature, pressure, humidity, gas, and chemical).

9.2.3.1 Design Requirements

For this design example, use the parameters listed in Table 4 as the input parameters.

| Table 4. Design Parameter | ers |
|---------------------------|-----|
|---------------------------|-----|

| DESIGN PARAMETER | GOAL VALUE |
|------------------|------------|
| Throughput | 10 kSPS |
| SNR at 100 Hz | 70 dB |
| THD at 100 Hz | 75dB |
| SINAD at 100 Hz | 69 dB |
| ENOB | 11 |
| Power | 10 µW |

9.2.3.2 Detailed Design Procedure

The ADS7042 can be directly interfaced with sensors at lower throughputs without the need of an amplifier buffer. The analog input source drive must be capable of driving the switched capacitor load of a SAR ADC and settling the analog input signal within the acquisition time of the SAR ADC. However, the output impedance of the sensor must be taken into account when interfacing a SAR ADC directly with sensors. Drive the analog input of the SAR ADC with a low impedance source. The input signal requires more acquisition time to settle to the desired accuracy because of the higher output impedance of the sensor. The simplified circuit for a sensor as a voltage source with output impedance (R_{OUT}) is shown in Figure 44.

The acquisition time of a SAR ADC (such as the ADS7042) can be increased by reducing throughput in the following ways:

- 1. Reducing the SCLK frequency to reduce the throughput, or
- 2. <u>Keeping the SCLK fixed at the highest permissible value (that is, 16 MHz for the device) and increasing the CS high time.</u>

NSTRUMENTS

XAS

www.ti.com.cn

Table 5 lists the acquisition time for the above two cases for a throughput of 100 kSPS. Clearly, case 2 provides more acquisition time for the input signal to settle.

| CASE | SCLK | t _{cycle} | CONVERSION TIME (= 12.5 × t _{SCLK} + t _{SU_CSCK}) | ACQUISITION TIME (= t _{cycle} - t _{conv}) |
|------|---------|--------------------|---|---|
| 1 | 1.6 MHz | 10 µs | 7.8125 μs | 2.1875 µs |
| 2 | 16 MHz | 10 µs | 0.78125 µs | 9.21875 µs |



For a step-by-step design procedure, circuit schematics, bill of materials, PCB files, simulation results, and test results, refer to TI Precision Design TIPD168, *Three 12-Bit Data Acquisition Reference Designs Optimized for Low Power and Ultra-Small Form Factor* (TIDU390).

9.2.3.3 Application Curve

When the output impedance of the sensor increases, the time required for the input signal to settle increases and the performance of the SAR ADC starts degrading if the input signal does not settle within the acquisition time of the ADC. The performance of the SAR ADC can be improved by reducing the throughput to provide enough time for the input signal to settle. Figure 45 provides the results for ENOB achieved from the ADS7042 for case 2 at different throughputs with different input impedances at the device input.

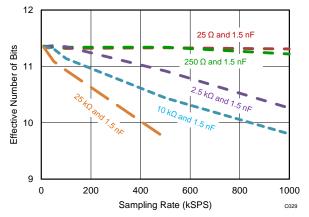


Figure 45. ENOB (Effective Number of Bits) Achieved from the ADS7042 at Different Throughputs

Table 6 shows the results and performance summary for this 12-bit, 10-kSPS DAQ circuit application.

 Table 6. Results and Performance Summary for 12-Bit, 10-kSPS DAQ Circuit for DC Sensor

 Measurements

| DESIGN PARAMETER | GOAL VALUE | ACHIEVED RESULT |
|------------------|------------|-----------------|
| Throughput | 10 kSPS | 10 kSPS |
| SNR at 100 Hz | 70 dB | 70.6 dB |
| THD at 100 Hz | 75dB | 83.5 dB |
| SINAD at 100 Hz | 69dB | 70.4 dB |
| ENOB | 11 | 11.4 |
| Power 10 μW | | 7 μW |



10 Power-Supply Recommendations

10.1 AVDD and DVDD Supply Recommendations

The ADS7042 has two separate power supplies: AVDD and DVDD. The device operates on AVDD; DVDD is used for the interface circuits. AVDD and DVDD can be independently set to any value within the permissible ranges. The AVDD supply also defines the full-scale input range of the device. Always set the AVDD supply to be greater than or equal to the maximum input signal to avoid saturation of codes. Decouple the AVDD and DVDD pins individually with 1-µF ceramic decoupling capacitors, as shown in Figure 46. The minimum capacitor value required for AVDD and DVDD is 200 nF and 20 nF, respectively. If both supplies are powered from the same source, a minimum capacitor value of 220 nF is required for decoupling.

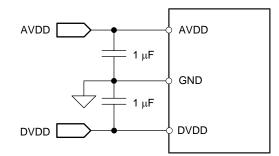


Figure 46. Power-Supply Decoupling

10.2 Estimating Digital Power Consumption

The current consumption from the DVDD supply depends on the DVDD voltage, load capacitance on the SDO line, and the output code. The load capacitance on the SDO line is charged by the current from the SDO pin on every rising edge of the data output and is discharged on every falling edge of the data output. The current consumed by the device from the DVDD supply can be calculated by Equation 5:

 $\mathsf{I}_{\mathsf{DVDD}} = \mathsf{C} \times \mathsf{V} \times \mathsf{f}$

where:

- C = Load capacitance on the SDO line,
- V = DVDD supply voltage, and
- f = Number of transitions on the SDO output.

(5)

The number of transitions on the SDO output depends on the output code, and thus changes with the analog input. The maximum value of f occurs when data output on the SDO change on every SCLK. SDO changing on every SCLK results in an output code of AAAh or 555h. For an output code of AAAh or 555h at a 1-MSPS throughput, the frequency of transitions on the SDO output is 6MHz.

For the current consumption to remain at the lowest possible value, keep the DVDD supply at the lowest permissible value and keep the capacitance on the SDO line as low as possible.

10.3 Optimizing Power Consumed by the Device

- Keep the analog supply voltage (AVDD) as close as possible to the analog input voltage. Set AVDD to be greater than or equal to the analog input voltage of the device.
- Keep the digital supply voltage (DVDD) at the lowest permissible value.
- Reduce the load capacitance on the SDO output.
- Run the device at the optimum throughput. Power consumption reduces with throughput.



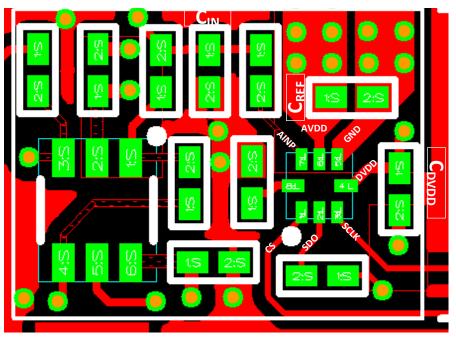
11 Layout

11.1 Layout Guidelines

Figure 47 shows a board layout example for the ADS7042. Use a ground plane underneath the device and partition the PCB into analog and digital sections. Avoid crossing digital lines with the analog signal path and keep the analog input signals and the reference input signals away from noise sources. In Figure 47, the analog input and reference signals are routed on the top and left side of the device and the digital connections are routed on the bottom and right side of the device.

The power sources to the device must be clean and well-bypassed. Use $1-\mu F$ ceramic bypass capacitors in close proximity to the analog (AVDD) and digital (DVDD) power-supply pins. Avoid placing vias between the AVDD and DVDD pins and the bypass capacitors. Connect all ground pins to the ground plane using short, low-impedance paths. The AVDD supply voltage for the ADS7042 also functions as a reference for the device. Place the decoupling capacitor (C_{REF}) for AVDD close to the device AVDD and GND pins and connect C_{REF} to the device pins with thick copper tracks, as shown in Figure 47.

The fly-wheel RC filters are placed close to the device. Among ceramic surface-mount capacitors, COG (NPO) ceramic capacitors provide the best capacitance precision. The type of dielectric used in COG (NPO) ceramic capacitors provides the most stable electrical properties over voltage, frequency, and temperature changes.



11.2 Layout Example

Figure 47. Example Layout



12 器件和文档支持

12.1 文档支持

12.1.1 相关文档

相关文档如下:

- 《OPA314 数据表》(文献编号 SBOS563)
- 《OPA835 数据表》(文献编号 SLOS713)
- 《TPS79101 数据表》(文献编号 SLVS325)
- 《TIPD168 参考指南》(文献编号 TIDU390)

12.2 社区资源

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E[™] Online Community *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support TI's Design Support Quickly find helpful E2E forums along with design support tools and contact information for technical support.

12.3 商标

E2E is a trademark of Texas Instruments. TINA is a trademark of Texas Instruments, Inc. 串行外设接口 (SPI) is a trademark of Motorola. All other trademarks are the property of their respective owners.

12.4 静电放电警告



ESD 可能会损坏该集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理措施和安装程序,可能会损坏集成电路。

ESD 的损坏小至导致微小的性能降级,大至整个器件故障。 精密的集成电路可能更容易受到损坏,这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

12.5 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

ZHCSD00C-JUNE 2014-REVISED DECEMBER 2015



www.ti.com.cn

13 机械、封装和可订购信息

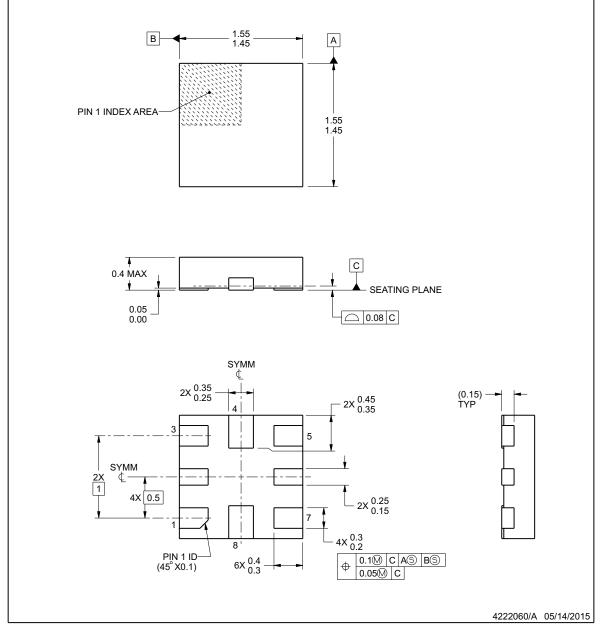
以下页中包括机械、封装和可订购信息。这些信息是针对指定器件可提供的最新数据。这些数据会在无通知且不对 本文档进行修订的情况下发生改变。欲获得该数据表的浏览器版本,请查阅左侧的导航栏。



PACKAGE OUTLINE

X2QFN - 0.4 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing

per ASME Y14.5M. 2. This drawing is subject to change without notice.





RUG0008A

www.ti.com.cn

RUG0008A

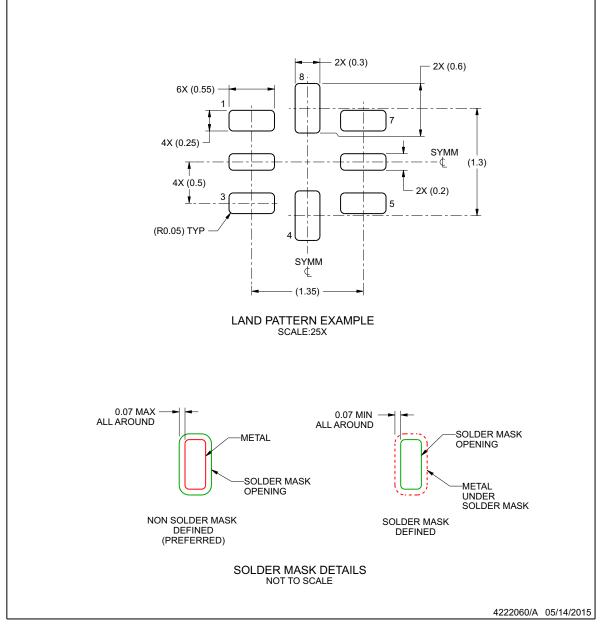


www.ti.com.cn

EXAMPLE BOARD LAYOUT

X2QFN - 0.4 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



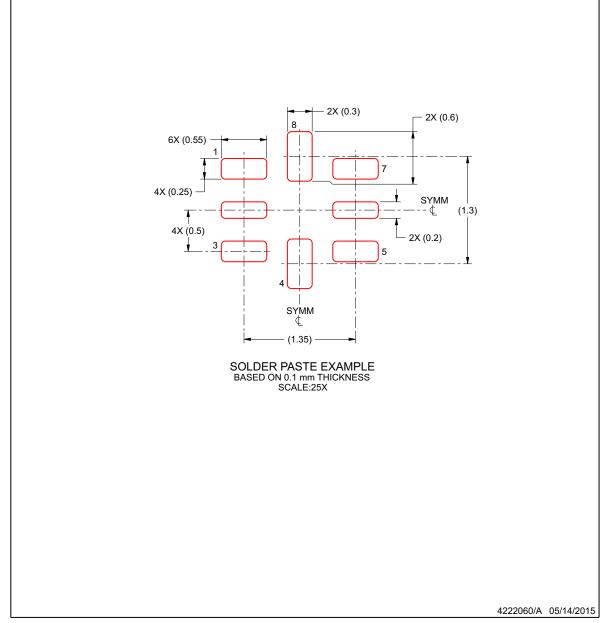
NOTES: (continued)

3. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

EXAMPLE STENCIL DESIGN

X2QFN - 0.4 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

www.ti.com



RUG0008A

www.ti.com.cn



PACKAGING INFORMATION

| Orderable part number | Status | Material type | Package Pins | Package qty Carrier | RoHS | Lead finish/ | MSL rating/ | Op temp (°C) | Part marking |
|-----------------------|--------|---------------|-----------------|-----------------------|------|---------------|--------------------|--------------|--------------|
| | (1) | (2) | | | (3) | Ball material | Peak reflow | | (6) |
| | | | | | | (4) | (5) | | |
| ADS7042IDCUR | Active | Production | VSSOP (DCU) 8 | 3000 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 7042 |
| ADS7042IDCUR.A | Active | Production | VSSOP (DCU) 8 | 3000 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 7042 |
| ADS7042IDCURG4.A | Active | Production | VSSOP (DCU) 8 | 3000 LARGE T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 7042 |
| ADS7042IDCUT | Active | Production | VSSOP (DCU) 8 | 250 SMALL T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 7042 |
| ADS7042IDCUT.A | Active | Production | VSSOP (DCU) 8 | 250 SMALL T&R | Yes | NIPDAU | Level-1-260C-UNLIM | -40 to 125 | 7042 |
| ADS7042IRUGR | Active | Production | X2QFN (RUG) 8 | 3000 LARGE T&R | Yes | NIPDAUAG | Level-1-260C-UNLIM | -40 to 125 | FV |
| ADS7042IRUGR.A | Active | Production | X2QFN (RUG) 8 | 3000 LARGE T&R | Yes | NIPDAUAG | Level-1-260C-UNLIM | -40 to 125 | FV |

⁽¹⁾ **Status:** For more details on status, see our product life cycle.

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

⁽⁴⁾ Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



www.ti.com

PACKAGE OPTION ADDENDUM

23-May-2025

PACKAGE MATERIALS INFORMATION

www.ti.com

Texas Instruments

TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



| *All dimensions are nominal | | | | | | | | | | | | |
|-----------------------------|-----------------|--------------------|---|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| Device | Package Type | Package Drawing | | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
| ADS7042IDCUR | VSSOP | DCU | 8 | 3000 | 180.0 | 8.4 | 2.25 | 3.35 | 1.05 | 4.0 | 8.0 | Q3 |
| ADS7042IDCUT | VSSOP | DCU | 8 | 250 | 180.0 | 8.4 | 2.25 | 3.35 | 1.05 | 4.0 | 8.0 | Q3 |
| ADS7042IRUGR | X2QFN | RUG | 8 | 3000 | 180.0 | 8.4 | 1.6 | 1.6 | 0.66 | 4.0 | 8.0 | Q2 |

TEXAS INSTRUMENTS

www.ti.com

PACKAGE MATERIALS INFORMATION

3-Aug-2017



*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|--------------|--------------|-----------------|------|------|-------------|------------|-------------|
| ADS7042IDCUR | VSSOP | DCU | 8 | 3000 | 202.0 | 201.0 | 28.0 |
| ADS7042IDCUT | VSSOP | DCU | 8 | 250 | 202.0 | 201.0 | 28.0 |
| ADS7042IRUGR | X2QFN | RUG | 8 | 3000 | 202.0 | 201.0 | 28.0 |

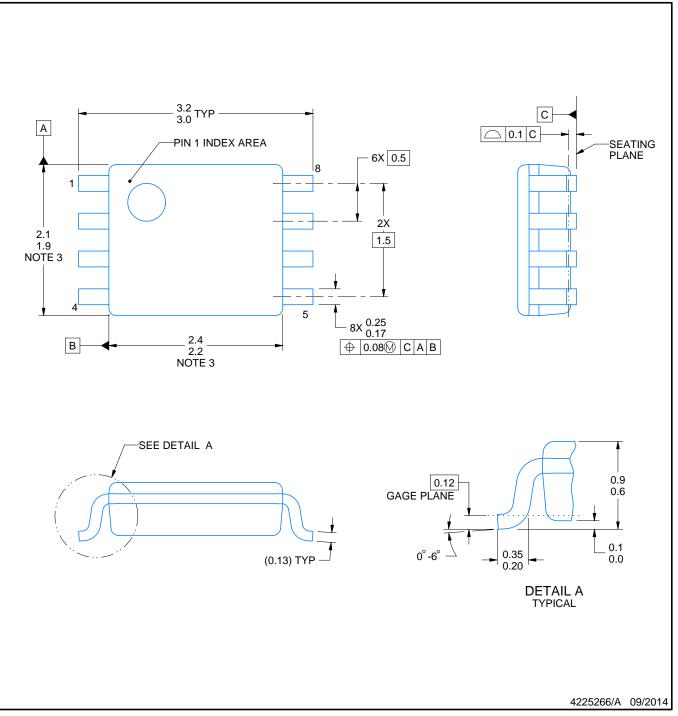
DCU0008A



PACKAGE OUTLINE

VSSOP - 0.9 mm max height

SMALL OUTLINE PACKAGE



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice. 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side. 4. Reference JEDEC registration MO-187 variation CA.



DCU0008A

EXAMPLE BOARD LAYOUT

VSSOP - 0.9 mm max height

SMALL OUTLINE PACKAGE



NOTES: (continued)

5. Publication IPC-7351 may have alternate designs.

6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



DCU0008A

EXAMPLE STENCIL DESIGN

VSSOP - 0.9 mm max height

SMALL OUTLINE PACKAGE



NOTES: (continued)

8. Board assembly site may have different recommendations for stencil design.



^{7.} Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

重要通知和免责声明

TI"按原样"提供技术和可靠性数据(包括数据表)、设计资源(包括参考设计)、应用或其他设计建议、网络工具、安全信息和其他资源, 不保证没有瑕疵且不做出任何明示或暗示的担保,包括但不限于对适销性、某特定用途方面的适用性或不侵犯任何第三方知识产权的暗示担 保。

这些资源可供使用 TI 产品进行设计的熟练开发人员使用。您将自行承担以下全部责任:(1) 针对您的应用选择合适的 TI 产品,(2) 设计、验 证并测试您的应用,(3) 确保您的应用满足相应标准以及任何其他功能安全、信息安全、监管或其他要求。

这些资源如有变更,恕不另行通知。TI 授权您仅可将这些资源用于研发本资源所述的 TI 产品的相关应用。 严禁以其他方式对这些资源进行 复制或展示。您无权使用任何其他 TI 知识产权或任何第三方知识产权。您应全额赔偿因在这些资源的使用中对 TI 及其代表造成的任何索 赔、损害、成本、损失和债务,TI 对此概不负责。

TI 提供的产品受 TI 的销售条款或 ti.com 上其他适用条款/TI 产品随附的其他适用条款的约束。TI 提供这些资源并不会扩展或以其他方式更改 TI 针对 TI 产品发布的适用的担保或担保免责声明。

TI 反对并拒绝您可能提出的任何其他或不同的条款。

邮寄地址:Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 版权所有 © 2025,德州仪器 (TI) 公司