

# **EVM TEST PROCEDURE**

## **SN65HVD257D CAN EVM**

**CAN Transceivers with Fast Loop Times for Highly Loaded Networks and Features For Functional Safety Networks**

REVISION: A

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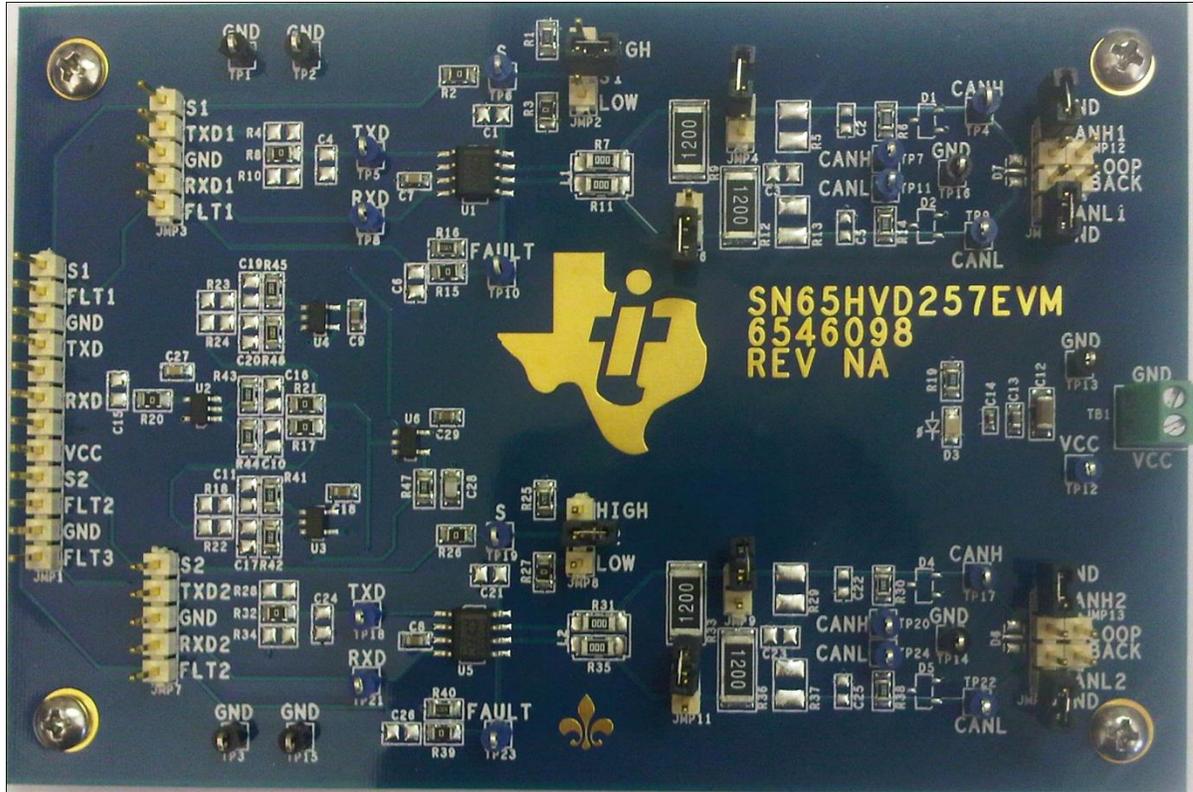
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**1.0 Parameter:** Installation Checkout

Verify the SN65HVD257D devices (U1 & U6) and supporting logic gates (U2, U3, U4, U5) are installed correctly. (All passive components were inspected prior to device installation)

**1.1 Definition:** Component Verification

Inspect the markings on the SN65HVD257D devices to insure it is the correct component with production symbolization. Inspect the other logic gates symbolization for correct installation and component.



**FIGURE 1. Top side of SN65HVD257 CAN EVM**

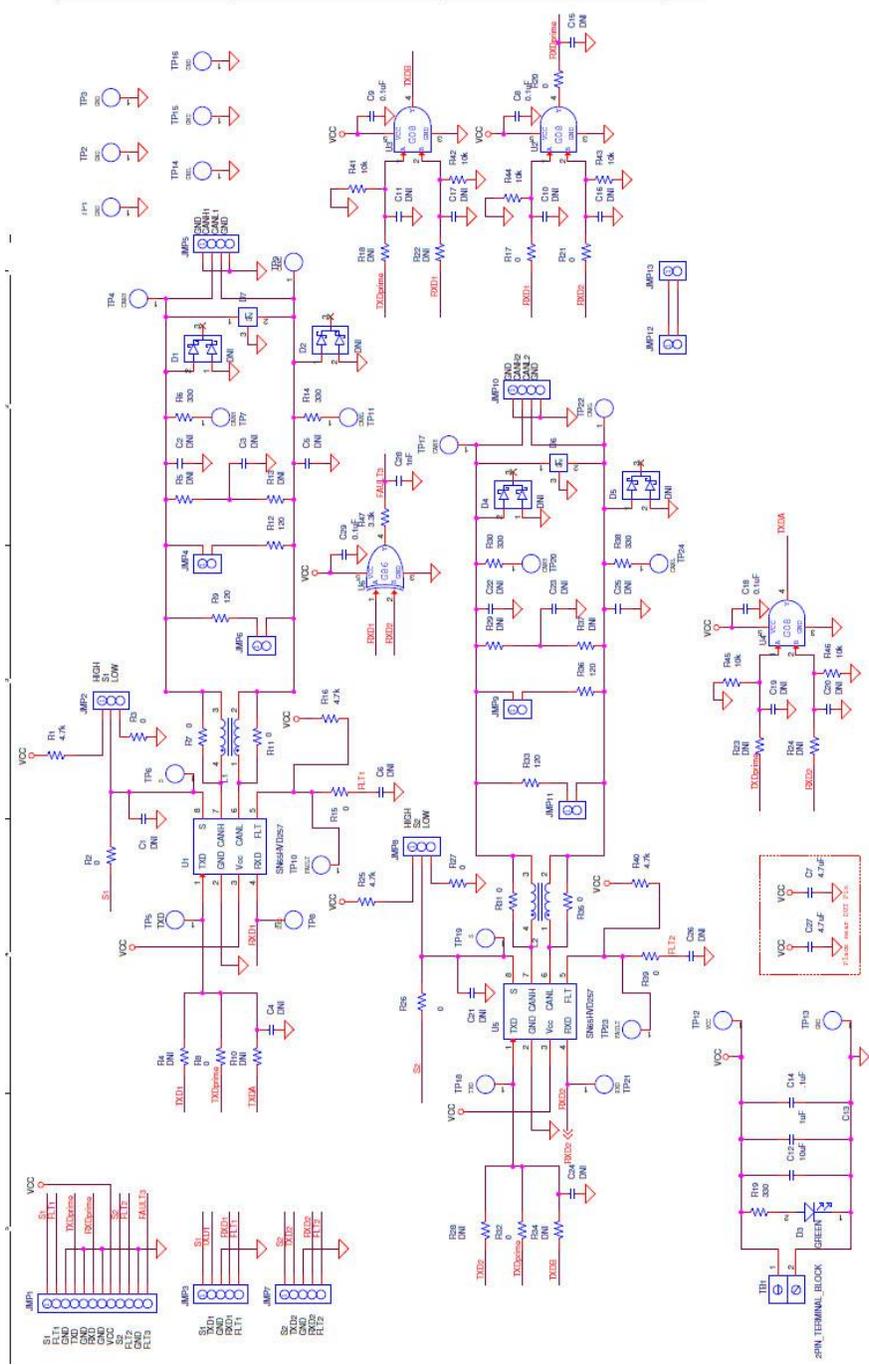


Figure 1. SN65HVD257 CAN EVM Schematic

# Bill of Material (BOM)

Item	Quantity	Reference	Part	Footprint	Manufacturer
1	23	C1,C3,R4,C4,C6,R10,C10,C11,C15,C16,C17,R18,C19,C20,C21,R22,R23,C23,R24,C24,C26,R28,R34	DNI	805	ANY
2	4	C2,C5,C22,C25	DNI	603	ANY
3	2	C7,C27	4.7uF	603	ANY
4	4	C8,C9,C18,C29	0.1uF	603	ANY
5	1	C12	10uF	1206	ANY
6	1	C13	1uF	603	ANY
7	1	C14	.1uF	402	ANY
8	1	C28	1nF	805	ANY
9	4	D1,D2,D4,D5	DNI	SOT_3DBZ	ANY
10	1	D3	GREEN	C170	ANY
11	2	D6,D7	DNI	CA05M2S10T100HG	EPCOS
12	1	JMP1	Header 1x12	HDR_THVT_1X12_100	ANY
13	2	JMP2,JMP8	Header 1x3	HDR_THVT_1X3_100	ANY
14	2	JMP3,JMP7	Header 1x5	HDR_THVT_1X5_100	ANY
15	6	JMP4,JMP6,JMP9,JMP11,JMP12,JMP13	Header 1x2	HDR_THVT_1X2_100	ANY
16	2	JMP5,JMP10	Header 1x4	HDR_THVT_1X4_100	ANY
17	2	L1,L2	DNI	M2022_Common-Mode_Choke	TDK / EPCOS
18	4	R1,R16,R25,R40	4.7k	805	ANY
19	11	R2,R3,R8,R15,R17,R20,R21,R26,R27,R32,R39	0	805	ANY
20	4	R5,R13,R29,R37	DNI	1210	ANY
21	5	R6,R14,R19,R30,R38	330	805	ANY
22	4	R7,R11,R31,R35	0	1206	ANY
23	4	R9,R12,R33,R36	120	2512	ANY
24	6	R41,R42,R43,R44,R45,R46	10k	805	ANY
25	1	R47	3.3k	805	ANY
26	1	TB1	2PIN_TERMINAL_BLOCK	TB_THRTSCR_1x2_100	ANY
27	18	TP4,TP5,TP6,TP7,TP8,TP9,TP10,TP11,TP12,TP13,TP17,TP18,TP19,TP20,TP21,TP22,TP23,TP24	Test Point	HDR_THVT_1x1_100	ANY
28	6	TP1,TP2,TP3,TP14,TP15,TP16	Test Point	HDR_THVT_1x1_100	ANY
29	2	U1,U5	SN65HVD257D	SOIC_8D	TI
30	3	U2,U3,U4	SN74AHC1G08DBV	SOT_5DBV	TI
31	1	U6	SN74AHC1G86DBV	SOT_5DBV	TI

**2.0 Parameter:** Functionality**2.1 Definition:** Basic Operation

**2.2 Purpose:** To verify basic operation of the CAN Transceivers and the preconfigured logic for combining the signals to create a redundant CAN network and fault outputs.

**2.3 Sequence:****a. Set EVM jumpers and Check Termination Resistances:**

- Set the CAN Bus 1 termination for standard loading of 60 ohms:
  - Jump JMP6 – check resistance between CANH1 (TP4) and CANL1 (TP6) is 120 ohms
  - Jump JMP4 – check resistance between CANH1 (TP4) and CANL1 (TP6) is now 60 ohms
  - Leave both JMP6 and JMP4 jumped
- Set the CAN Bus 2 termination for standard loading of 60 ohms:
  - Jump JMP11 – check resistance between CANH2 (TP17) and CANL2 (TP22) is 120 ohms
  - Jump JMP9 – check resistance between CANH2 (TP17) and CANL2 (TP22) is now 60 ohms
  - Leave both JMP11 and JMP9 jumped
- Set HVD257 U1 for normal mode: jumper JMP2, S1 to LOW.
- Set HVD257 U5 for normal mode: jumper JMP8, S1 to LOW.

**b. Set Up Scope:** Use a 4 channel scope with 4 Single-Ended Probes

Set Trigger to Ch.1 Rising Edge

Set Horizontal Scale to 1 $\mu$ s per division

Set Ch.1: Vertical Position = 2.5, Vertical Scale = 5V per division

Set Ch.2: Vertical Position = -2.5, Vertical Scale = 1V per division

Set Ch.3: Vertical Position = -2.5, Vertical Scale = 1V per division

Set Ch.4: Vertical Position = -3.5, Vertical Scale = 5V per division

Connect Ch.1 to TXD U1 (TP5)

Connect Ch.2 to CANH1 (TP4 or JMP5)

Connect Ch.3 to CANL1 (TP9 or JMP5)

Connect Ch.4 to RXD1 U1 (TP8)

**c. Connect power supply to TB1 pins.**

Program supply to 5V, 250mA. Enable Power Supply.

**d. Check Power:** Observe current and D3 (LED).

Current should not be excessive (~32mA).

D3 (LED) should be on.

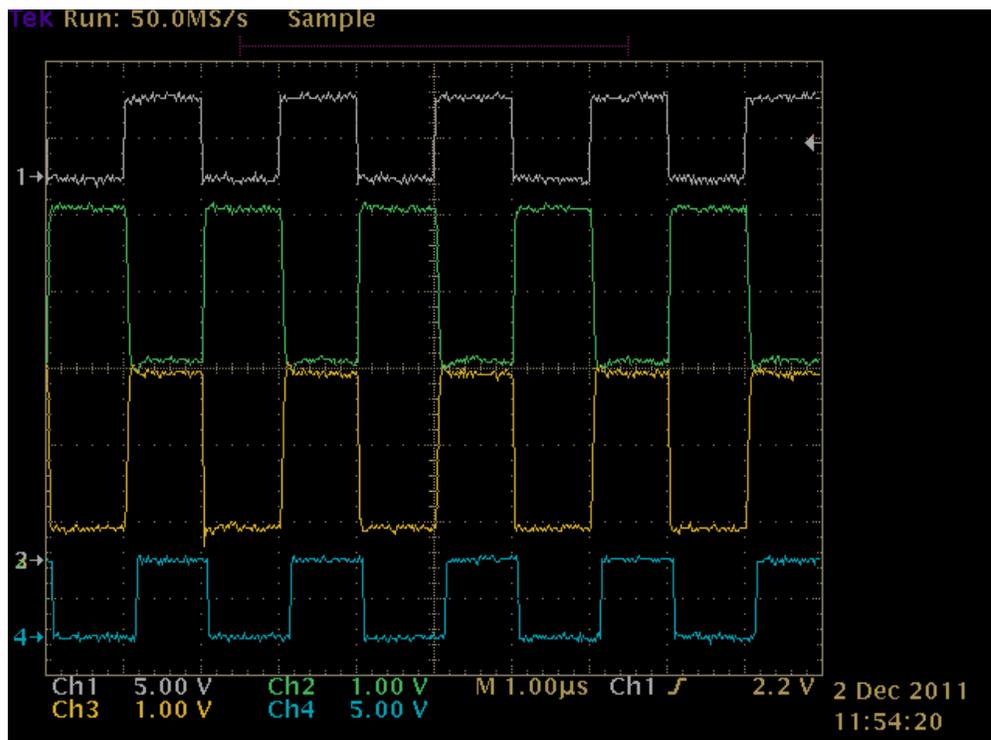
**e. Connect a signal generator to TXD pin on JMP1.**

Program generator to 500 kHz, 50% Duty Cycle,  $V_{ih} = 2.5V$ ,  $V_{il} = 0V$ .

Enable Signal Generator.

[NOTE: TXD is not 50Ω terminated; therefore to achieve 5V using the HFS9000, Vih is set 2.5V]

- f. Observe current and scope display.  
Current should not be excessive (~32mA).  
Scope display should look like Figure 2 below.
- g. Disable Signal Generator and Power Supply
- h. Use same scope settings but check 2<sup>nd</sup> HVD257 CAN bus.  
Connect Ch.1 to TXD U2 (TP18)  
Connect Ch.2 to CANH2 (TP17 or JMP10)  
Connect Ch.3 to CANL2 (TP22 or JMP10)  
Connect Ch.4 to RXD U2 (TP721)
- i. Enable Power Supply and function generator.
- j. Observe current and scope display.  
Current should not be excessive (~85mA).  
Scope display should look like Figure 2 below.



**FIGURE 2. Scope Screen Shot**

- k.** Use same scope settings but check combining logic of both HVD257 CAN buses.
  - Connect Ch.1 to TXD U2 (TP18)
  - Connect Ch.2 to CANH2 (TP17)
  - Connect Ch.3 to CANL2 (TP22)
  - Connect Ch.4 to RXD (JMP1)
  
- l.** Observe scope display.
  - Scope display should look like Figure 2 above
  
- m.** Check for loss of HVD257 1 (U1), same scope settings.
  - Move JMP2 (S1) to High.
  
- n.** Observe scope display.
  - Scope display should look like Figure 2 above.
  
- o.** Check Bus 1 transmission is disabled.
  - Connect Ch.2 to CANH1 (TP4 or JMP5)
  - Connect Ch.3 to CANL1 (TP9 or JMP5)
  
- p.** Observe scope display.
  - Scope display should look like Figure 2 above except CANH and L should be 2.5V steady.
  
- q.** Check for loss of HVD257 2 (U5), same scope settings.
  - Move JMP2 (S1) to LOW
  - Move JMP8 (S2) to HIGH
  
- r.** Observe scope display.
  - Scope display should look like Figure 2 above
  
- s.** Check Bus 2 transmission is disabled.
  - Connect Ch.2 to CANH2 (TP17)
  - Connect Ch.3 to CANL2 (TP22)
  
- t.** Observe scope display.
  - Scope display should look like Figure 2 above except CANH and L should be 2.5V steady.
  
- u.** Disable Signal Generator and Power Supply
  
- v.** Use same scope settings to check fault logic outputs of both HVD257 CAN buses.
  - Set Ch.1: Vertical Position = 2, Vertical Scale = 5V per division
  - Set Ch.2: Vertical Position = 0, Vertical Scale = 5V per division

Set Ch.3: Vertical Position = -2, Vertical Scale = 5V per division  
Set Ch.4: Vertical Position = -3, Vertical Scale = 5V per division  
Connect Ch.1 to RXD (JMP1)  
Connect Ch.2 to FLT1 (JMP1)  
Connect Ch.3 to FLT2 (JMP1)  
Connect Ch.4 to FLT3 (JMP1)  
Set horizontal scale to 5 $\mu$ s per division

- w. Check Bus Dominant Faults (FLT1) from CAN1 being shorted Dominant  
Connect CANH1 to Vcc (TP4 or JMP5)  
Connect CANL1 to GND (TP9 or JMP5)  
Move JMP2 (S1) to HIGH  
Move JMP8 (S2) to LOW
- x. Set the frequency of the function generator to 50kHz. All other settings stay the same.
- y. Enable Power Supply and function generator.
- z. Observe scope display.  
Scope display should look like Figure 3 (below)

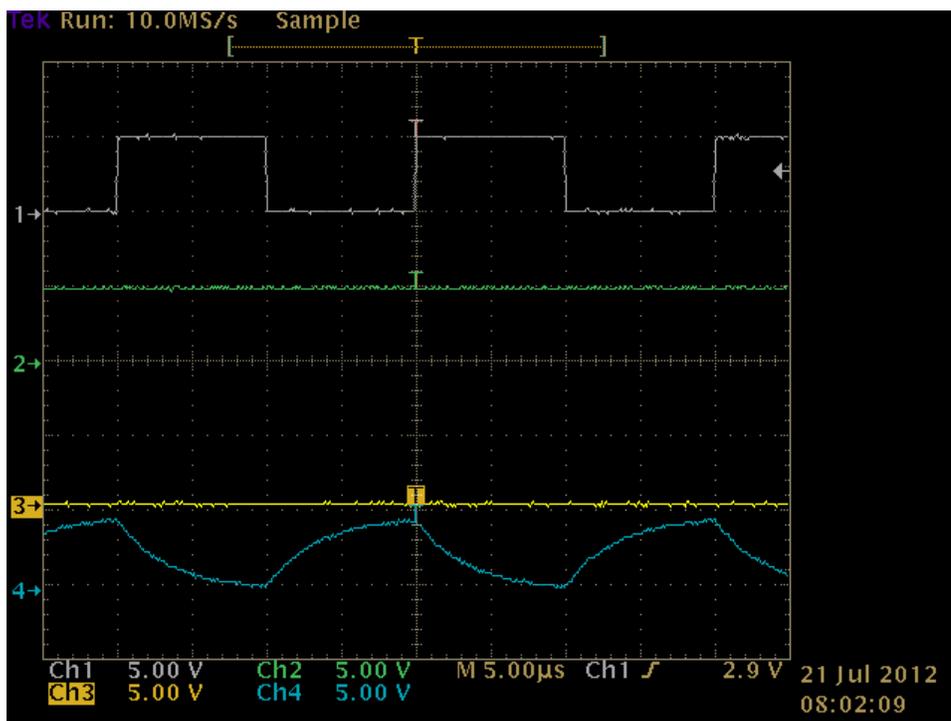


FIGURE 3. Scope Screen Shot

- aa. Disable Power Supply and Function Generator
- bb. Check Bus Dominant Faults (FLT2) from CAN2 being shorted Dominant  
Connect CANH2 to Vcc (TP17 or JMP10)  
Connect CANL1 to GND (TP22 or JMP10)  
Move JMP2 (S1) to LOW  
Move JMP8 (S2) to HIGH  
Remove connection from CANH1 to Vcc (TP4 or JMP5)  
Remove connection from CANL1 to GND (TP9 or JMP5)
- cc. Enable Power Supply and function generator.
- dd. Observe scope display.  
Scope display should look like Figure 4 (below)

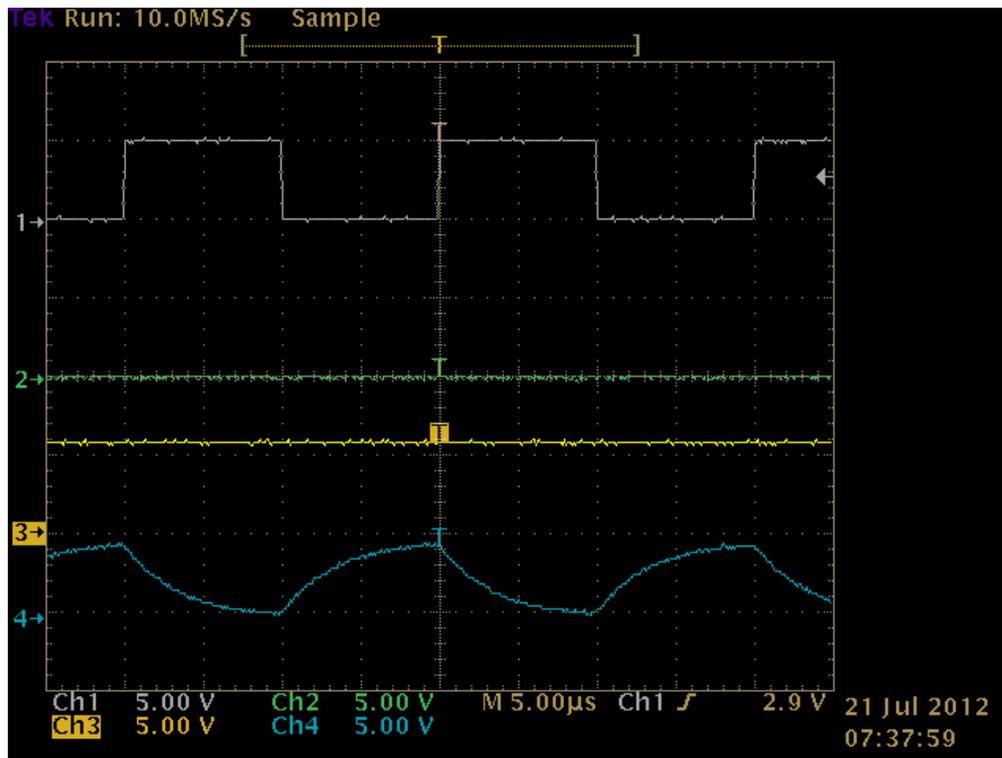


FIGURE 4. Scope Screen Shot

ee. Disable Power Supply and Function Generator

ff. If all these check out good then the EVM may be considered good.

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