

# AN-2220 Precision Current Limiting with the LMP8646 and LMZ12003

# ABSTRACT

This application report discusses how to design the Texas Instruments LMP8646 with the LMZ12003 voltage regulator and a resistive load application.

#### Contents

1		Ξ.
2	Example	2
	List of Figures	

1	Resistive Load Application with LMZ12003 Regulator and LMP8646 Precision Current Limiter	2
2	SuperCap Application with LMZ12003 Regulator Plot	3

All trademarks are the property of their respective owners.

#### Overview

# 1 Overview

The LMP8646 is a precision current limiter used to improve the current limit accuracy of any switching or linear regulator with an available feedback node. Many regulators might have an internal current limiter, but its output accuracy is often as high as 30%. The output accuracy of the LMP8646 can be as low as 3%, making it a preferred current limiter for many regulator applications. The resistive load application with LMZ12003 regulator and LMP8646 precision current limiter is shown in Figure 1.

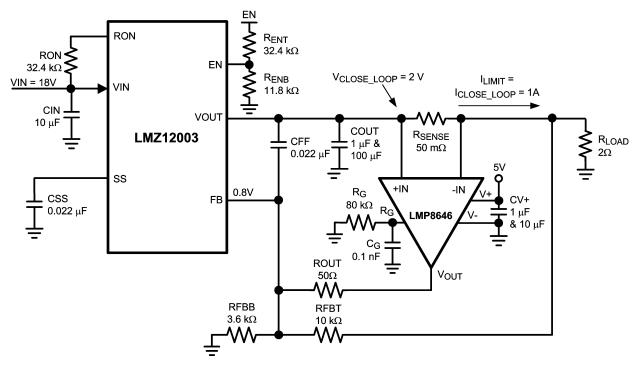


Figure 1. Resistive Load Application with LMZ12003 Regulator and LMP8646 Precision Current Limiter

# 2 Example

To see the current limiting capability of the LMP8646, the open-loop current must be greater than the close-loop current. An open-loop occurs when the LMP8646 output is not connected the LMZ12003's feedback pin. For this example, the open-loop current is 1.5A and the close-loop current, I<sub>LIMIT</sub>, is 1A.

# Step 1: Choose the components for the Regulator.

To select the appropriate components for the LMZ12003 voltage regulator, see *AN-2031 LMZ12003 3A Demo Board SIMPLE SWITCHER Power Module Quick Start Guide* (SNVA427). The LMZ12003 components chosen for this example can be seen in Figure 1.

# Step 2: Step 2: Choose the sense resistor, R<sub>SENSE</sub>

 $R_{\mbox{\tiny SENSE}}$  sets the voltage  $V_{\mbox{\tiny SENSE}}$  between +IN and -IN and has the following equation:

 $R_{SENSE} = V_{OUT} / [(I_{LIMIT}) \times (R_G / 5kOhm)]$ 

(1)

In general,  $R_{SENSE}$  depends on the output voltage, limit current, and gain. To choose the appropriate  $R_{SENSE}$  value, see the Selection of the Sense Resistor,  $R_{SENSE}$  section in *LMP8646 Precision Current Limiter* (SNOSC63). Typically,  $R_{SENSE}$  is a power resistor in the mOhm range. In this example, use 50 mOhm.

2

#### www.ti.com

#### Step 3: Choose the gain resistor, R<sub>G</sub>, for LMP8646

 $R_{G}$  is chosen from  $I_{LIMIT}$ . As stated in Equation 1, since  $V_{OUT} = V_{FB} = 0.8V$ ,  $I_{LIMIT} = 1A$ , and  $R_{SENSE} =$ 50 mOhm, R<sub>G</sub> can be calculated as:

 $R_{G} = (V_{OUT} \times 5 \text{ kOhm}) / (R_{SENSE} \times I_{LIMIT})$ 

 $R_G = (0.8 \times 5 \text{ kOhm}) / (50 \text{ mOhm} \times 1A) = 80 \text{ kOhm} (approximate)$ 

## Step 4: Choose the Bandwidth Capacitance, C<sub>G</sub>.

The product of  $C_{G}$  and  $R_{G}$  determines the bandwidth for the LMP8646. To see the range for the LMP8646 bandwidth and gain, see the Typical Performance Characteristics plots in LMP8646 Precision Current Limiter (SNOSC63). Since each application is very unique, the LMP8646 bandwidth capacitance, C<sub>G</sub>, needs to be adjusted to fit the appropriate application.

Bench data has been collected for the supercap application with the LMZ12003 regulator; it was discovered that this application works best for a bandwidth of 2 kHz to 30 kHz. Operating anything less than this recommended bandwidth might prevent the LMP8646 from quickly limiting the current. Choosing a bandwidth that is in the middle of this range is recommended and using the equation:

 $C_G = 1/(2 \times pi \times R_G \times Bandwidth)$ 

(3)

to find  $C_G$  (this example uses a  $C_G$  value of 0.1nF).

After selecting an initial C<sub>G</sub> value, capture the plot for I<sub>LIMIT</sub> and adjust C<sub>G</sub> until a desired load current plot is obtained.

## Step 5: Choose the Output Resistor, ROUT

ROUT plays a very small role in the overall system performance for the resistive load application. ROUT is more important for a supercap load because the initial current error is typically large with a capacitive load. Because current is directly proportional to voltage for a resistive load, the output current is not large at startup. The bigger the ROUT, the longer it takes for the output voltage to reach its final value. It is recommended that the value for ROUT is at least 50  $\Omega$ , which is the value used for this example.

## Step 6: Adjusting the Components

Capture the output current and output voltage plots and adjust the components as necessary. The most common components to adjust is C<sub>G</sub> for the bandwidth. An example output current and voltage plot can be seen in Figure 2

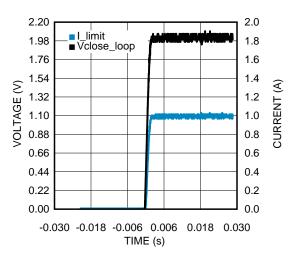


Figure 2. SuperCap Application with LMZ12003 Regulator Plot

(2)

#### **IMPORTANT NOTICE**

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, enhancements, improvements and other changes to its semiconductor products and services per JESD46, latest issue, and to discontinue any product or service per JESD48, latest issue. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products (also referred to herein as "components") are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its components to the specifications applicable at the time of sale, in accordance with the warranty in TI's terms and conditions of sale of semiconductor products. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by applicable law, testing of all parameters of each component is not necessarily performed.

TI assumes no liability for applications assistance or the design of Buyers' products. Buyers are responsible for their products and applications using TI components. To minimize the risks associated with Buyers' products and applications, Buyers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right relating to any combination, machine, or process in which TI components or services are used. Information published by TI regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of significant portions of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI components or services with statements different from or beyond the parameters stated by TI for that component or service voids all express and any implied warranties for the associated TI component or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Buyer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of TI components in its applications, notwithstanding any applications-related information or support that may be provided by TI. Buyer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Buyer will fully indemnify TI and its representatives against any damages arising out of the use of any TI components in safety-critical applications.

In some cases, TI components may be promoted specifically to facilitate safety-related applications. With such components, TI's goal is to help enable customers to design and create their own end-product solutions that meet applicable functional safety standards and requirements. Nonetheless, such components are subject to these terms.

No TI components are authorized for use in FDA Class III (or similar life-critical medical equipment) unless authorized officers of the parties have executed a special agreement specifically governing such use.

Only those TI components which TI has specifically designated as military grade or "enhanced plastic" are designed and intended for use in military/aerospace applications or environments. Buyer acknowledges and agrees that any military or aerospace use of TI components which have *not* been so designated is solely at the Buyer's risk, and that Buyer is solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI has specifically designated certain components as meeting ISO/TS16949 requirements, mainly for automotive use. In any case of use of non-designated products, TI will not be responsible for any failure to meet ISO/TS16949.

Products		Applications		
Audio	www.ti.com/audio	Automotive and Transportation	www.ti.com/automotive	
Amplifiers	amplifier.ti.com	Communications and Telecom	www.ti.com/communications	
Data Converters	dataconverter.ti.com	Computers and Peripherals	www.ti.com/computers	
DLP® Products	www.dlp.com	Consumer Electronics	www.ti.com/consumer-apps	
DSP	dsp.ti.com	Energy and Lighting	www.ti.com/energy	
Clocks and Timers	www.ti.com/clocks	Industrial	www.ti.com/industrial	
Interface	interface.ti.com	Medical	www.ti.com/medical	
Logic	logic.ti.com	Security	www.ti.com/security	
Power Mgmt	power.ti.com	Space, Avionics and Defense	www.ti.com/space-avionics-defense	
Microcontrollers	microcontroller.ti.com	Video and Imaging	www.ti.com/video	
RFID	www.ti-rfid.com			
OMAP Applications Processors	www.ti.com/omap	TI E2E Community	e2e.ti.com	
Wireless Connectivity	www.ti.com/wirelessconnectivity			

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2013, Texas Instruments Incorporated