

Troubleshooting I²C Bus Protocol

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ABSTRACT

When using the I²C™ bus protocol, the designer must ensure that the hardware complies with the I²C standard. This application report describes the I²C protocol and provides guidelines on debugging a missing acknowledgment, selecting the pullup resistors, or meeting the maximum capacitance load of an I²C bus. A conflict occurs if devices sharing the I²C bus have the same slave address. This document provides solutions to this conflict by using the devices' features or external components.

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1 Introduction

Inter-integrated circuit (I²C) (NPX) is a two-wired protocol that can operate at different speeds (standard mode, fast mode, and high-speed mode). Although other protocols are simpler and do not have speed limitation (such as SPI), the scalability offered by I²C™ made it attractive as an interface for some of TI's CDC products.

I²C prevents data corruption by performing a wired-AND operation as the I²C interface has open-drain or open-collector output. When the SDA line is low that translates in the I²C bus as being busy.

Also, this interface allows the master to check the bus status. By pulling the master SDA line high, it can verify the status of the bus: busy if the line stays low (as some device is pulling the line low), or free if the line is high.

2 I²C Communication

2.1 Protocol Description

The I²C protocol is generated by SDA (bidirectional line: receives I²C pattern and transmits acknowledgment when communication was successful) and SCL (one-direction line).

As the I²C protocol allows multiple slave devices connected to a single I²C bus, each of them is identified with a different address. To address the slave device, seven bits are used.

Transfers are initiated by a start condition (SDA falling edge while SCL is high), and transfers end when a stop condition occurs (rising edge on SDA while SCL is high).

An instruction is sent through the SDA in blocks of one byte, where the first bit is the most-significant bit (MSB). SDA bits must be stable while SCL is high, and they must change while the SCL line is low. If SDA bits are not stable while SCL is high, it is understood as a stop or start condition, a typical cause for a corrupted message or missing acknowledgment.

The number of bytes transmitted is unlimited; each byte must be followed by an acknowledgment bit from the slave confirming the successful reception of the byte. In its absence, the level remains high during the ninth SCL pulse.

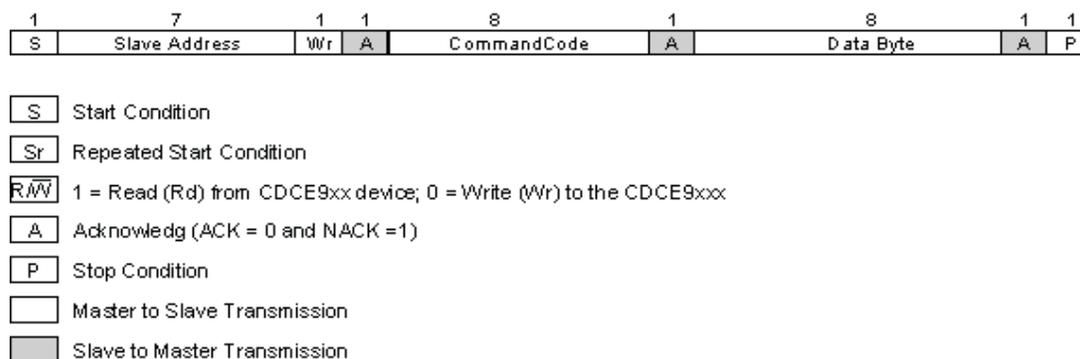
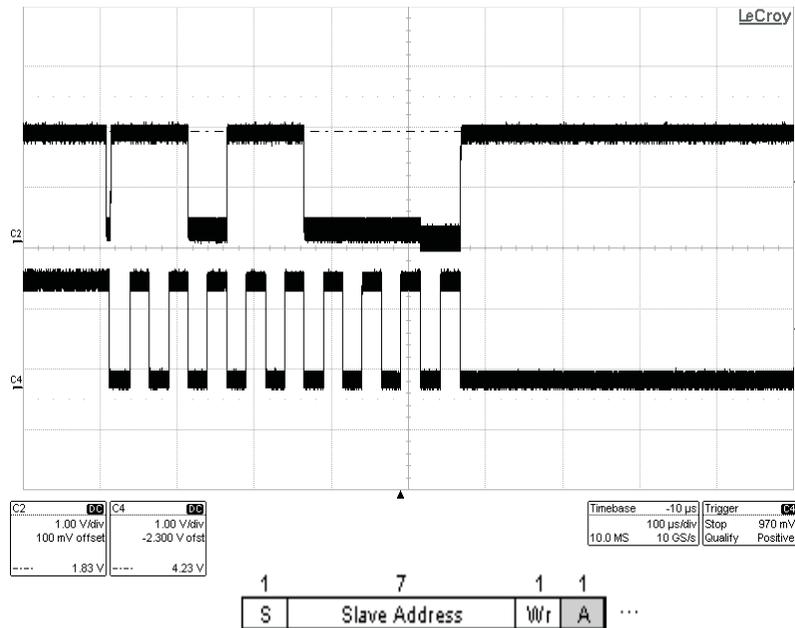


Figure 1. I²C Programming Sequence for the CDCE949

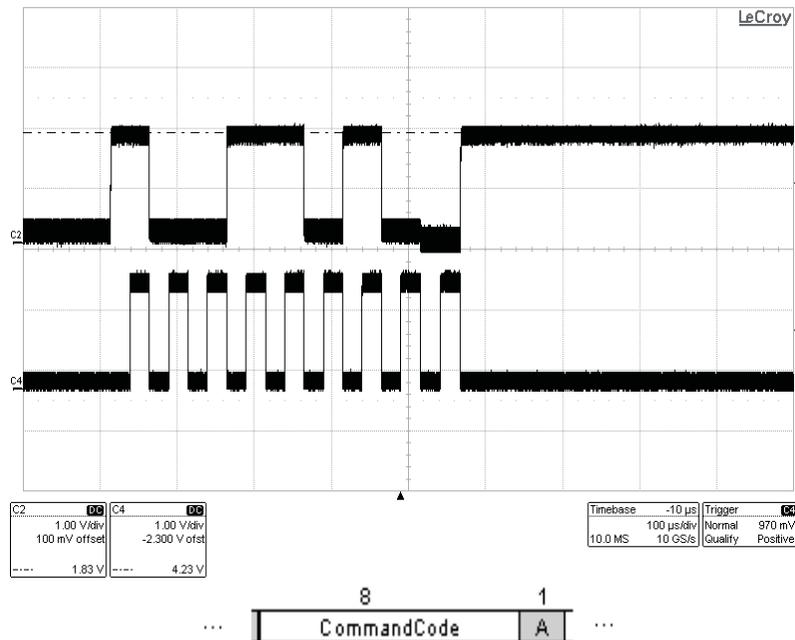
2.2 I²C Protocol Screen Shots for CDC(L)949, CDC(L)937, CDC(L)925, CDC(L)913, and CDCE906/907

The I²C pattern writes in the register's address A1xh the data A6xh on the CDC(L)949 (slave) whose address is '1101100'xb. Screen shots of the protocol can be found in [Figure 2](#), [Figure 3](#), and [Figure 4](#).



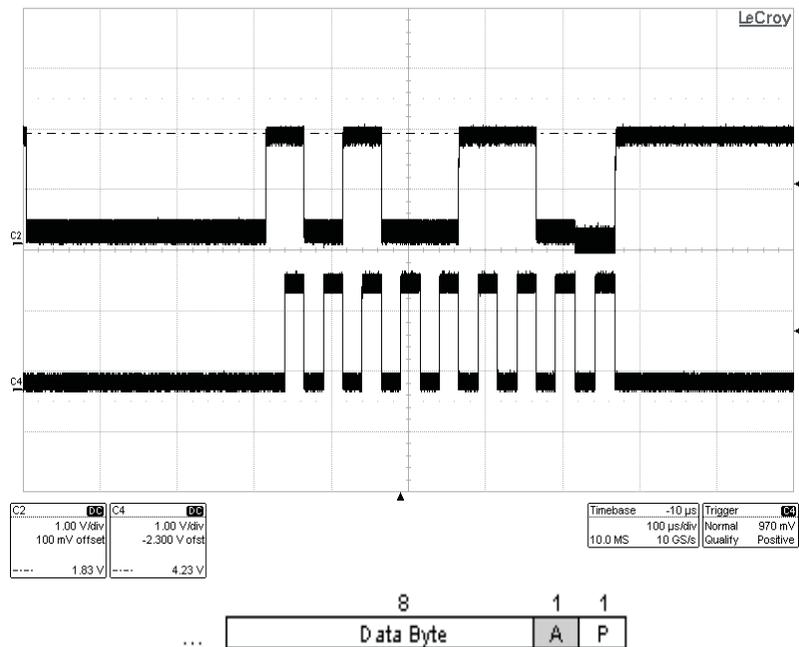
The first byte of the I²C protocol contains the device's slave address (1101100xb) and type of operation (0 = write). C2 is SDA and C4 is SCL. The CDCE949 (slave) gives back acknowledgment after the last bit was patterned; only after the SCL last falling edge, the I²C bus is released to handle the next block of communication.

Figure 2. First Eight Bits of the I²C Pattern: Slave Address and R/W



The second byte of I²C protocol contains the type of write/read (byte write) and register's address (1axh) where the operation is performed. C2 is SDA and C4 is SCL. The CDCE949 (slave) gives back acknowledgment after the last bit was patterned; only after the SCL last falling edge, the I²C bus is released to handle the next block of communication.

Figure 3. Second Set of 8 Bits of the I²C Pattern: Command Code



Data byte contains byte to write/read (A6xh).

C2 is SDA and C4 is SCL.

The CDCE949 (slave) gives back acknowledgment after the last bit was patterned; only after the SCL last falling edge, the I²C bus is released to handle the next block of communication.

Figure 4. Third Set of 8 Bits of the I²C Pattern Contains Byte to Write/Read (A6xh)

2.3 Troubleshooting I²C Communication. Reasons for Missing Acknowledgment

2.3.1 Timing

Even when using a processor that generates a two-wired interface sequence, timing still must be checked. It is possible that the delay between SCL and SDA is not compliant or too marginal with the defined timing. In those cases, unwanted START or STOP conditions can occur in the middle of the I²C pattern sent, causing the slave to get a different message or resulting in a missing acknowledgment.

2.3.2 Missing/Unexpected SCL Pulses

An unsuccessful execution occurs when missing or unexpected SCL pulses are within the protocol. If something unexpected happens, it is assured by design that a START condition discards the previous incomplete or erroneous message, and the device is ready to receive the new message.

2.3.3 Incomplete 8-Bit Block

When less than eight bits are sent, the slave waits for the rest of the data. Unless the eighth bit is sent, the slave does not generate an acknowledgment. A way to restart the transmission is starting the new message with a start condition, to send the new I²C pattern.

2.3.4 Missing Bytes

When a block operation is performed, the amount of bytes to be sent or received may already be fixed in another register. If the number of bytes sent or received is less than the number expected, the state machine waits for the rest of the message. The start condition can be patterned in order to skip the waiting state.

Caveats when "block read" is patterned on CDCE(L)949, CDCE(L)937, CDCE(L)925 and CDCE(L)913:

BCOUNT located in the register's address 08xh bits 7:1 sets the number of bytes that are read when performing a block read. A missing acknowledgment or misunderstood message can occur while performing a block read if the BCOUNT is set to a greater value than the bytes available from the offset set on the command code.

2.3.5 False Slave Address

Each I²C slave device connected to the I²C bus has its own slave address and responds only to that address when an I²C protocol is being patterned.

When the slave device identifies itself with the address being broadcasted in the I²C bus, it ties the SDA signal to ground as can be seen in [Figure 2](#). For that reason, SDA is bidirectional, so that it can handle the acknowledgment received from the slave.

2.3.6 Missing Acknowledgment After Changing the Address

Caveats when programming via I²C the CDCE(L)949, CDCE(L)937, CDCE(L)925, and CDCE(L)913:

During a write instruction (block or byte), each byte change is effective when the last bit of the data byte is patterned.

After changing bits 1:0 from register address 01xh, the slave address changes; therefore, the next I²C message starts with the new slave address. Using the old slave address causes a missing acknowledgment due to a false slave address received.

If during a block write the value of bits 1:0 from register address 01xh change, this translates into a different slave address, but this does not impact the communication as the slave address is only checked in the first byte of the block write message.

Caveats when programming via I²C the CDCE906 and CDCE706:

The CDCE906 and CDCE706 slave address is 1101001. When a byte write is performed to set register's address 10xh last 4 bits to 1111, then A0 and A1 control pins overwrite the last two bits of the slave address. When A0 and A1 pins are left floating the pulled up resistors set their value to 1. After that byte write, the slave address is defined by 11010, A0 and A1. If the slave address in the next I²C message is not the new one, then a missing acknowledgment occurs.

If the last two bits of the slave address are set by A0 and A1, and the A0 or A1 pins change, it does not impact the communication as long as this change occurred after the first block of the I²C message (that contains the slave address) was patterned.

If the slave address changes during a block write, the communication is still successful as the connection with the device was already established during the first block of the I²C message.

3 Solving Address Conflict When Sharing I²C Bus

A conflict occurs when more than one device with the same slave address is connected to the same I²C bus.

CDCE(L)949, CDCE(L)937, CDCE(L)925, and CDCE(L)913 belong to the same family of products with the same performance but having different outputs. Their slave address has one part fixed/hardwired and one part programmable. CDCE(L)949 and CDCE(L)937 share the same hardwired address. The same situation applies to CDCE(L)925 and CDCE(L)913. For this reason, if the slave address programmable part changes within each of the defined groups, it is possible to reprogram them to have the same slave address. That is, CDCE(L)949 can be programmed to have the same address as that of the CDCE(L)937. But in this situation, when connected to the same I²C bus, a conflict arises.

The CDCE(L)949, CDCE(L)937, CDCE(L)925, and CDCE(L)913 can re-program the last two bits of their default slave address. Therefore, up to four devices of each can be plugged into the I²C bus.

Each of these devices default setups are set to have different slave address. Therefore, with the default setup, one of each of them has to be able to share the same I²C bus with no conflict.

Some devices offer the possibility to fix the slave address with control signals. Thus, the same device can overwrite its slave address with control pins, and it is unnecessary to preprogram the device.

The CDCE906 and CDCE706 offer the possibility to overwrite the last two bits of their slave address with external control pins 1 and 2. As pins 1 (S0/A0/CLK_SEL) and 2 (S1/A1) are shared with other functionalities, these pins act as A0 and A1 when setting the four lower bits of the internal register 10xh to 1111xb. When A1 and A0 are left floating, the effective slave address is 11, as each of them has internal pullups of 150 k Ω .

A programming EVM board can be used in order to change the setup of all these devices:

<http://focus.ti.com/docs/toolsw/folders/print/cdcel9xxprogevm.html>

If the slave device has a fixed address or if the preceding options are not preferred, then an I²C multiplexor or I²C buffers can be used.

I²C multiplexors split the I²C bus into several subbranches and allow the I²C master to select and address one of multiple identical devices, thus resolving address conflict. The multiplexor connects the main I²C bus to the selected slave device and removes electrically the nonselected devices. This device is programmable via I²C protocol, therefore, no additional pins or control logic are required. TI's PCA9544A can multiplex up to four slave devices with the same slave address, as can be seen in [Figure 5](#).

If an I²C buffer is chosen, then additional lines (and optional control logic) is needed to enable/disable the I²C bus branch corresponding to the addressed/nonaddressed slave device. This solution (see [Figure 6](#)) can be achieved by using TI's PCA9515A I²C buffer or the PCA9517 I²C buffer; the latter one offers additional voltage translation.

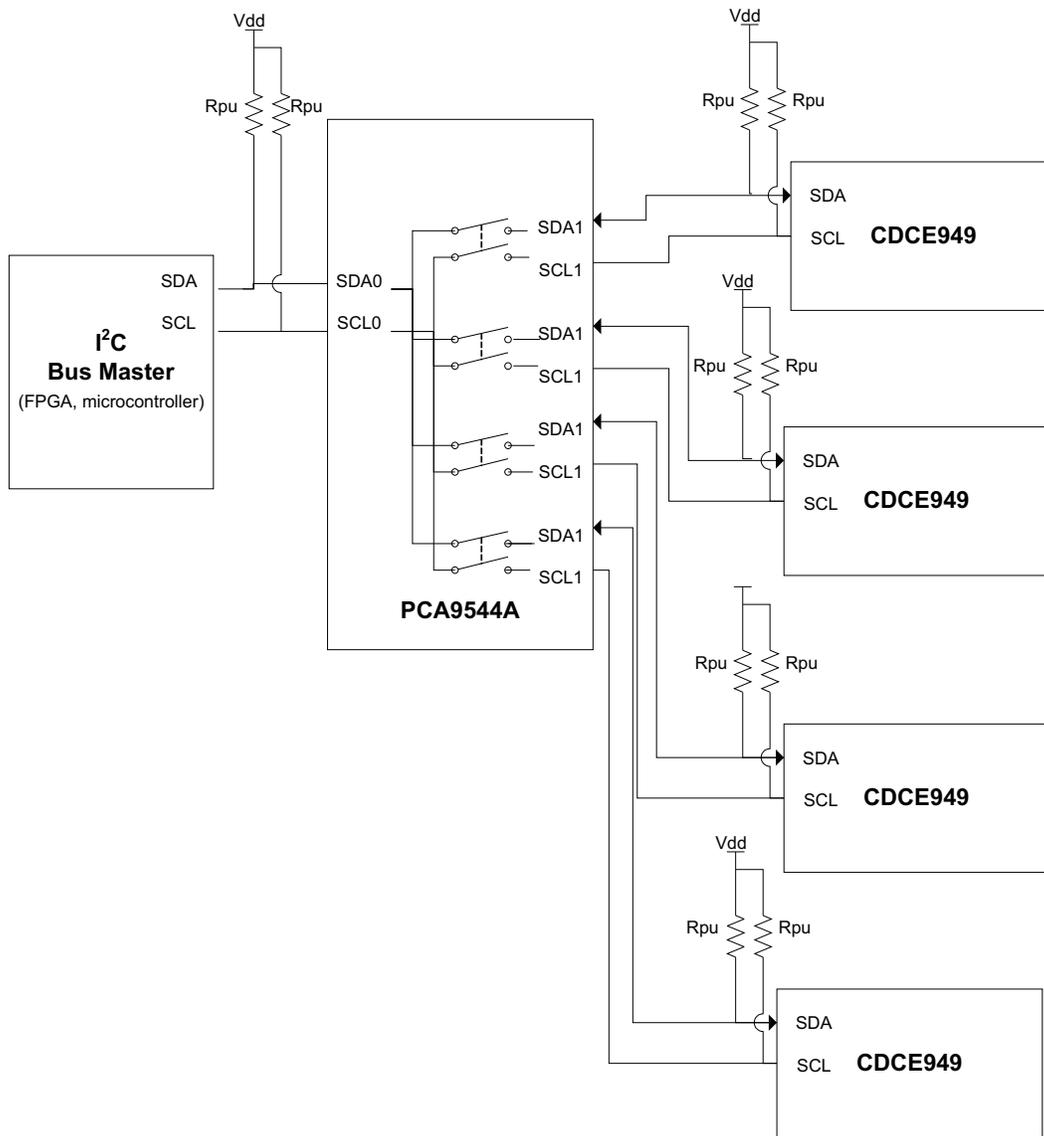


Figure 5. Slave Address Conflict Solved With I²C Multiplexor

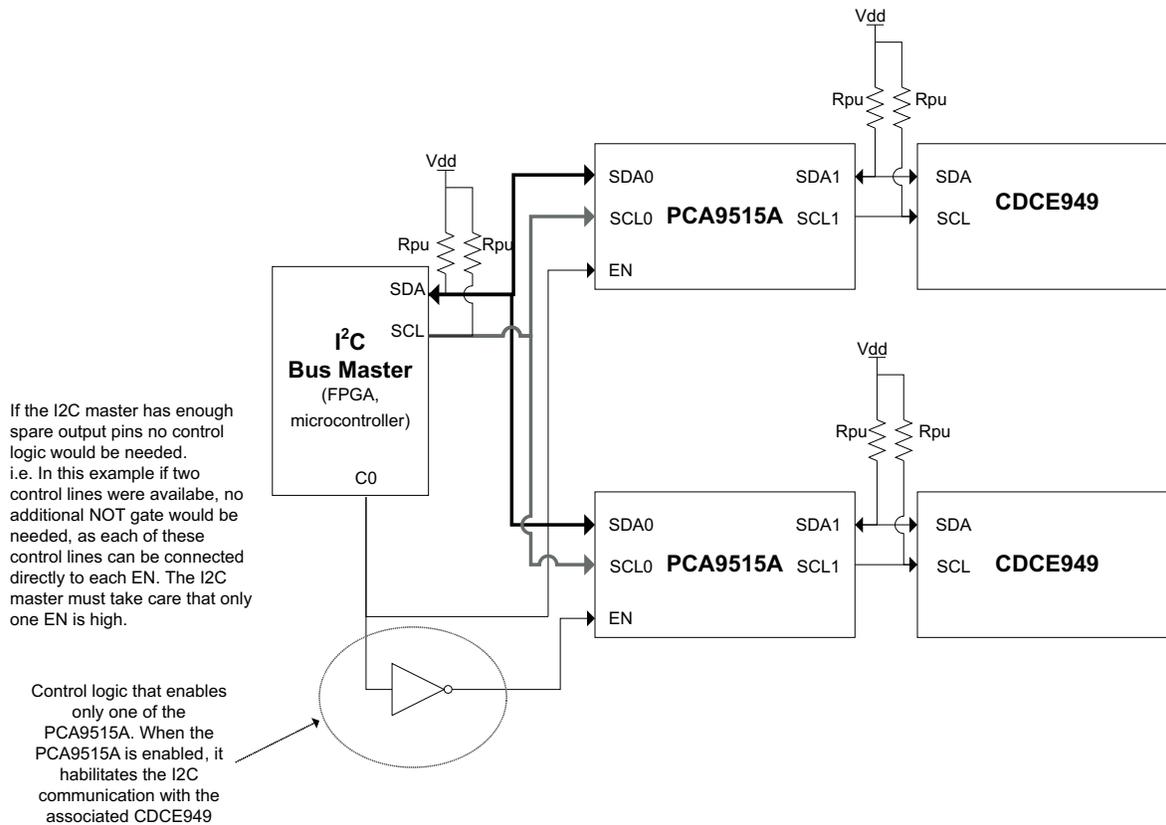


Figure 6. Slave Address Conflict Solved With Bidirectional I²C Buffer

4 Hardware

4.1 Pullup Resistor

The interval of the valid pullup resistors for SDA and SCL is down-limited by the static load specifications and up-limited by the rising and falling edge specification.

The minimum resistor value is determined by the maximum current load the output transistor can handle. The I²C specification limit of 3 mA (for standard and fast mode) or 20 mA (for fast mode plus).

$$R = \frac{(V_{ddmax} - V_{olmax})}{0.003 \text{ A}}$$

when $V_{dd} = 1.8 \text{ V}$ and $V_{olmax} = 0.4 \text{ V}$ $R_{min} = 466 \Omega$

The maximum value is calculated from the rise time specifications of the I²C bus:

$$V(t1) = 0.3 \times V_{dd} = V_{dd} \times \left(1 - e^{-\frac{t1}{RC}}\right)$$

$$t1 = 0.3566749RC$$

$$V(t2) = 0.7 \times V_{dd} = V_{dd} \times \left(1 - e^{-\frac{t2}{RC}}\right)$$

$$t2 = 1.2039729RC$$

$$t = t2 - t1 = 0.8472979RC$$

For standard-mode I²C-bus: $t = \text{rise time} = 1000 \text{ ns}$ ($1 \mu\text{s}$), so $RC = 1180.2 \text{ ns}$

Example: at a maximum I²C bus load of 400 pF: $R_{\text{max}} = 2.95 \text{ k}\Omega$. For fast-mode: I²C-bus rise time = 300 ns at 400 pF: $R_{\text{max}} = 885 \Omega$

4.2 Overcoming Maximum Capacitance Load

Adding more I²C and SMBus devices on the bus may exceed the 400-pF limitation. I²C multiplexors, I²C switches, and I²C buffers and repeaters can isolate slave devices that are not currently needed to reduce the overall system loading, and then meet the maximum load capacitance specification.

The I²C multiplexor splits the I²C bus in I²C bus subbranches. I²C multiplexors allow the I²C master to communicate with only one of the multiple devices connected. Although I²C multiplexors are used to solve address conflicts, they can also be used to reduce the load capacitance. They isolate devices that are not needed to reduce the overall system loading. When one of the connected devices is selected, the I²C multiplexor acts as a wire. The cumulative capacitive loading of the main I²C bus and the other active I²C subbranches must be considered; so, care must be taken that each branch does not exceed the 400 pF specified (beyond this, the rising and falling times specifications would be violated).

I²C switches are like I²C multiplexors but more than one device can be selected simultaneously.

I²C buffers/repeaters provide capacitive isolation from the I²C bus, so they are used to go beyond the maximum capacitive load allowed in the bus 400 pF (specified for standard and fast I²C mode)

5 References

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