

# 用于笔记本个人电脑、平板电脑和显示器，支持集成伽马基准的液晶显示器 (LCD) 偏置电压

查询样品: [TPS65642](#)

## 1 介绍

### 1.1 特性

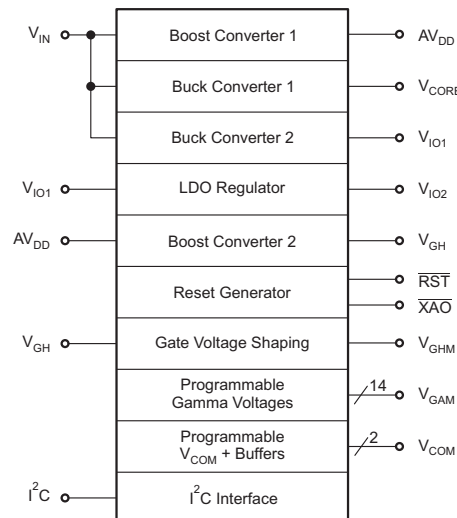
- 2.6V 至 6V 输入电压范围
- 同步升压转换器 ( $AV_{DD}$ )
- 支持温度补偿的非同步升压转化器 ( $V_{GH}$ )
- 同步降压转换器 ( $V_{IO1}$ )
- 同步降压转换器 ( $V_{IO2}$ )
- 低压降线性稳压器 ( $V_{IO2}$ )
- 带有两个集成型缓冲放大器的可编程  $V_{COM}$  校准器
- 栅极电压整形
- 面板放电信号 ( $\overline{XAO}$ )
- 系统复位信号 ( $RST$ )
- 14 通道, 10 位可编程伽马电压校正
- 支持写入保护的片载 **EEPROM**
- $I^2C$ ™ 接口
- 热关断
- 支持 **GIP** 和非 **GIP** 显示
- 56 焊球, 3.16mm x 3.45mm 0.4mm 焊球间距, 芯片尺寸球栅阵列封装 (**DSBGA**)

### 1.2 应用范围

- 笔记本电脑
- 平板电脑
- 显示器

### 1.3 说明

TPS65642 是一款紧凑型 LCD 偏置电压解决方案，此解决方案主要用于笔记本电脑和平板电脑。此器件包含两个升压转换器来为 LCD 面板的源极驱动器和栅极驱动器/电平位移器供电，两个降压转换器以及一个为系统提供逻辑电压的低压降 (LDO) 线性稳压器；一个具有两个高速放大器的可编程  $V_{COM}$  发生器；14 通道伽马电压校正；和一个栅极电压整形功能。



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

## 2 Electrical Specifications

### 2.1 ORDERING INFORMATION<sup>(1)</sup>

T <sub>A</sub>	ORDERING	PACKAGE	PACKAGE MARKING
–40°C to 85°C	TPS65642YFF	3.16 mm x 3.45 mm DSBGA, 0.4 mm pitch	TPS65642

(1) The device is supplied taped and reeled, with 3000 devices per reel.

### 2.2 ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
Pin voltage	VIN, SW2, VCORE, SW3, VIO1, VIO2 RSET, COMP, SCL, SDA, EN, FLK, WP, TCOMP, $\overline{\text{XAO}}$ , $\overline{\text{RST}}$	–0.3	7	V
	AVDD, SW1, OUT1, OUT2, OUTA-OUTN	–0.3	12	V
	SW4	–0.3	36 <sup>(2)</sup>	V
	POS1, NEG1, POS2, NEG2	–0.3	12 <sup>(3)</sup>	V
	POS1-NEG1  <sup>(4)</sup> ,  POS2-NEG2  <sup>(4)</sup>		2	V
	VGH, VGHM, RE	–0.3	40 <sup>(5)</sup>	V
ESD Rating	Human Body Model		2000	V
	Machine Model		200	V
	Charged Device Model		700	V
Ambient temperature, T <sub>A</sub>		–40	85	°C
Junction temperature, T <sub>J</sub>		–40	150	°C
Storage temperature, T <sub>STG</sub>		–65	150	°C

- (1) Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) V<sub>GH</sub> supplies up to 40 V can be generated, but require an external cascode transistor or charge pump.
- (3) For supply voltages less than 12 V, the absolute maximum input voltage is equal to the supply voltage.
- (4) Differential input voltage.
- (5) The combination of low temperatures and high V<sub>GH</sub> voltages can cause increased leakage current through the RE pin. In GIP applications that do not use the gate-voltage shaping function it is recommended to leave the RE pin open to minimize this effect.

### 2.3 THERMAL INFORMATION<sup>(1)</sup>

THERMAL METRIC		TPS65642	UNITS
		YFF	
		56 PINS	
θ <sub>JA</sub>	Junction-to-ambient thermal resistance	45	°C/W
θ <sub>JCtop</sub>	Junction-to-case (top) thermal resistance	0.2	
θ <sub>JB</sub>	Junction-to-board thermal resistance	6.4	
ψ <sub>JT</sub>	Junction-to-top characterization parameter	0.8	
ψ <sub>JB</sub>	Junction-to-board characterization parameter	6.1	
θ <sub>JCbot</sub>	Junction-to-case (bottom) thermal resistance	N/A	

- (1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, [SPRA953](#).

## 2.4 RECOMMENDED OPERATING CONDITIONS

		MIN	TYP	MAX	UNIT
$V_{IN}$	Input voltage range	2.6		6	V
<b>BOOST CONVERTER 1</b>					
$AV_{DD}$	Boost converter 1 output voltage range	6		9.1	V
$IAV_{DD}$	Boost converter 1 output current when $6\text{ V} \geq V_{IN} \geq 4\text{ V}$			700 <sup>(1)</sup>	mA
	Boost converter 1 output current when $3.63\text{ V} \geq V_{IN} \geq 2.64\text{ V}$			400 <sup>(1)</sup>	mA
L	Boost converter 1 inductor range	2.2	4.7	10	$\mu\text{H}$
$C_{OUT}$	Boost converter 1 output capacitance	10			$\mu\text{F}$
<b>BOOST CONVERTER 2</b>					
$AV_{DD}$	Input voltage range	6	8.1	9.1 <sup>(2)</sup>	V
$V_{GH}$	Output voltage range	16	24	40 <sup>(3)</sup>	V
$I_{GH}$	Output current		15	40	mA
L	Inductor	10	15		$\mu\text{H}$
$C_{OUT}$	Output capacitance	1	4.7		$\mu\text{F}$
$R_{NTC}$	Thermistor resistance at 25°C		10		k $\Omega$
<b>BUCK CONVERTER 1 (<math>V_{CORE}</math>)</b>					
$V_{CORE}$	Output voltage	1	1.1	1.3	V
$I_{CORE}$	Output current			600	mA
L	Inductor	1	2.2	4.7	$\mu\text{H}$
$C_{OUT}$	Output capacitance	4.7	10	22	$\mu\text{F}$
<b>BUCK CONVERTER 2 (<math>V_{IO1}</math>)</b>					
$V_{IO1}$	Output voltage	1.7		2.5	V
$I_{IO1}$	Output current			200 <sup>(4)</sup>	mA
L	Inductor	1	2.2	4.7	$\mu\text{H}$
$C_{OUT}$	Output capacitance	4.7	10	22	$\mu\text{F}$
<b>LDO Regulator (<math>V_{IO2}</math>)</b>					
$V_{IO2}$	Output voltage	1.7		1.8	V
$I_{IO}$	Output current			200	mA
$C_{OUT}$	Output capacitance		4.7	10	$\mu\text{F}$
<b>PROGRAMMABLE VCOM</b>					
$I_{SET}$	Programmable $V_{COM}$ set current		50		$\mu\text{A}$
<b>PROGRAMMABLE GAMMA CORRECTION</b>					
$I_{GAM}$	Output current per channel	-100		100	$\mu\text{A}$
$C_{GAM}$	Output capacitance			50	pF

(1) This value includes the current that must be supplied to the input of boost converter 2.

(2)  $V_{GH} - AV_{DD}$  must be greater than 9 V.

(3) Output voltages greater than 36 V require an external cascode transistor.

(4) This value includes the current supplied to the input of the linear regulator.

## 2.5 ELECTRICAL CHARACTERISTICS

$V_{IN} = 3.3\text{ V}$ ,  $V_{CORE} = 1.1\text{ V}$ ,  $V_{IO1} = 1.7\text{ V}$ ,  $V_{IO2} = 1.8\text{ V}$ <sup>(1)</sup>,  $AV_{DD} = 8.1\text{ V}$ ,  $V_{GH} = 24\text{ V}$ ,  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$ . Typical values are at  $25^\circ\text{C}$  (unless otherwise noted).

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
POWER SUPPLY							
I <sub>IN</sub>	Supply current into VIN pins	Converters not switching			1.9	3	mA
	Supply current into AVDD pins	Pin G5.			0.1	1	mA
		Pin B7. No load on gamma reference outputs			4.3	6	
		Pin F4. No load on op-amp outputs			4.0	7.5	
	Supply current into VGH	No load on VGHM			0.1	1	mA
UNDERVOLTAGE LOCKOUT							
V <sub>UVLO</sub>	Undervoltage lockout threshold	V <sub>IN</sub> rising		2.3	2.42	2.5	V
		V <sub>IN</sub> falling		2.1	2.19	2.4	
	Hysteresis				0.23		
CONTROL PINS (EN, FLK, WP)							
V <sub>IH</sub>	EN high-level input voltage threshold	EN rising	V <sub>IN</sub> = 2.64 V		1.0	1.8	V
			V <sub>IN</sub> = 3.3 V		1.1	1.8	
			V <sub>IN</sub> = 6 V		1.7	1.8	
V <sub>IL</sub>	EN low-level input voltage threshold	EN falling	V <sub>IN</sub> = 2.64 V	0.7	0.9		V
			V <sub>IN</sub> = 3.3 V	0.7	1.0		
			V <sub>IN</sub> = 6 V	0.7	1.6		
I <sub>IH</sub>	EN high-level input current	EN = 2.5 V		−100		100	nA
I <sub>IL</sub>	EN low-level input current	EN = 0 V		−100		100	nA
V <sub>IH</sub>	FLK high-level input voltage threshold	FLK rising	V <sub>IN</sub> = 2.64 V		0.9	1.8	V
			V <sub>IN</sub> = 3.3 V		1	1.8	
			V <sub>IN</sub> = 6 V		1.4	1.8	
V <sub>IL</sub>	FLK low-level input voltage threshold	FLK falling	V <sub>IN</sub> = 2.64 V	0.6	0.8		V
			V <sub>IN</sub> = 3.3 V	0.6	0.9		
			V <sub>IN</sub> = 6 V	0.6	1.3		
I <sub>IH</sub>	FLK high-level input current	FLK = 2.5 V		−100		100	nA
I <sub>IL</sub>	FLK-low-level input current	FLK = 0 V		−100		100	nA
V <sub>IH</sub>	WP high-level input voltage threshold	WP rising	V <sub>IN</sub> = 2.64 V		1	1.8	V
			V <sub>IN</sub> = 3.3 V		1.1	1.8	
			V <sub>IN</sub> = 6 V		1.7	1.8	
V <sub>IL</sub>	WP low-level input voltage threshold	WP falling	V <sub>IN</sub> = 2.64 V	0.7	0.9		V
			V <sub>IN</sub> = 3.3 V	0.7	1		
			V <sub>IN</sub> = 6 V	0.7	1.6		
R <sub>PULL-UP</sub>	WP internal pull-up resistance			30	52	75	kΩ
BOOST CONVERTER 1 (AV <sub>DD</sub> )							
AV <sub>DD</sub>	Output voltage range			6		9.1	V
	Tolerance			−1%		1%	
V <sub>UVP</sub>	Undervoltage protection threshold	AV <sub>DD</sub> falling		65	70	75	% of AV <sub>DD</sub>
V <sub>SCP</sub>	Short-circuit threshold	AV <sub>DD</sub> falling		25	30	35	% of AV <sub>DD</sub>
I <sub>LK</sub>	Switch leakage current	V <sub>SW</sub> = V <sub>IN</sub> = 3.3 V, EN = 0 V, T <sub>J</sub> = −40°C to 85°C				10	μA
r <sub>DS(ON)</sub>	Switch ON resistance	I <sub>SW</sub> = 1 A			114	250	mΩ
I <sub>LIM</sub>	Switch current limit			2.5	3.0	3.5	A
r <sub>DS(ON)</sub>	Rectifier ON resistance	I <sub>SW</sub> = 1 A			242	400	mΩ
f <sub>SW</sub>	Switching frequency (see Figure 4-15)	FREQ = 0			750		kHz
		FREQ = 1			1200		
r <sub>DS(ON)</sub>	Discharge ON resistance	I <sub>AVDD</sub> = 10 mA			76	100	Ω

(1) When  $V_{IO1} = 1.7\text{ V}$  or  $1.8\text{ V}$ , the LDO regulator is disabled. When  $V_{IO1} = 2.5\text{ V}$ , the LDO regulator is enabled.

**ELECTRICAL CHARACTERISTICS (continued)**

$V_{IN} = 3.3\text{ V}$ ,  $V_{CORE} = 1.1\text{ V}$ ,  $V_{IO1} = 1.7\text{ V}$ ,  $V_{IO2} = 1.8\text{ V}^{(1)}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $V_{GH} = 24\text{ V}$ ,  $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ . Typical values are at  $25^{\circ}\text{C}$  (unless otherwise noted).

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
BUCK CONVERTER 1 (V <sub>CORE</sub> )							
V <sub>CORE</sub>	Output voltage			1	1.1	1.3	V
	Tolerance			−3%		3%	
V <sub>UVP</sub>	Undervoltage protection threshold	V <sub>CORE</sub> falling		65	70	75	% of V <sub>CORE</sub>
V <sub>SCP</sub>	Short-circuit threshold	V <sub>CORE</sub> falling		25	30	35	% of V <sub>CORE</sub>
I <sub>LIM</sub>	Switch current limit	I <sub>SW</sub> ramps from 0 A to 2 A		0.8	1.0	1.2	A
r <sub>DS(ON)</sub>	Switch ON resistance	High-side, I <sub>SW</sub> = I <sub>LIM</sub>			183	310	mΩ
		Low-side, I <sub>SW</sub> = 1 A			95	150	
t <sub>OFF</sub>	Off time	V <sub>IN</sub> = 3.3 V		260	370	480	ns
		V <sub>IN</sub> = 5 V		380	560	750	
BUCK CONVERTER 2 (V <sub>IO1</sub> )							
V <sub>IO1</sub>	Output voltage			1.7	1.8	2.5	V
	Tolerance			−3%		3%	
V <sub>UVP</sub>	Undervoltage protection threshold	V <sub>IO1</sub> falling		65	70	75	% of V <sub>IO1</sub>
V <sub>SCP</sub>	Short-circuit threshold	V <sub>IO1</sub> falling		25	30	35	% of V <sub>IO1</sub>
I <sub>LIM</sub>	High-side switch current limit	High-side, I <sub>SW</sub> ramps from 0 A to 2 A		0.8	1	1.2	A
r <sub>DS(ON)</sub>	High-side switch ON resistance	I <sub>SW</sub> = I <sub>LIM</sub>			183	350	mΩ
	Low-side switch ON resistance	I <sub>SW</sub> = 1 A			255	400	
t <sub>OFF</sub>	Off time	V <sub>IN</sub> = 3.3		170	250	330	μs
		V <sub>IN</sub> = 5 V		250	370	500	
r <sub>DS(ON)</sub>	Discharge ON resistance	Measured with 10 mA			14.6	50	Ω
LINEAR REGULATOR (V <sub>IO2</sub> ) <sup>(2)</sup>							
V <sub>IO2</sub>	Output voltage	I <sub>IO2</sub> = 1 mA		1.7	1.8	1.8	V
	Tolerance			−3%		3%	
V <sub>UVP</sub>	Undervoltage protection threshold	V <sub>IO2</sub> falling		65	70	75	% of V <sub>IO2</sub>
V <sub>SCP</sub>	Short circuit threshold	V <sub>IO2</sub> falling		25	30	35	% of V <sub>IO2</sub>
BOOST CONVERTER 2 (V <sub>GH</sub> )							
V <sub>GH</sub>	Output voltage range			16		40 <sup>(3)</sup>	V
	Tolerance			−3%		3%	
V <sub>UVP</sub>	Undervoltage protection threshold	V <sub>GH</sub> falling		65	70	75	% of V <sub>GH</sub>
V <sub>SCP</sub>	Short-circuit threshold	V <sub>GH</sub> falling		25	30	35	% of V <sub>GH</sub>
I <sub>LK</sub>	Switch leakage current	V <sub>EN</sub> =0 V; V <sub>SW4</sub> =36 V				10	μA
r <sub>DS(ON)</sub>	Switch ON resistance	I <sub>SW</sub> =1 A			0.41	1	Ω
t <sub>ON(MAX)</sub>	Maximum t <sub>ON</sub> time			1	1.67	2.5	μs
t <sub>OFF</sub>	t <sub>OFF</sub> time			1.5	2.11	3	μs
I <sub>TCOMP</sub>	Thermistor reference current	I <sub>SET</sub> = 50 μA, V <sub>TCOMP</sub> = 1 V	85°C	48		54	μA
			25 °C		50		
RESET (RST)							
t <sub>RESET</sub>	Reset pulse duration range	Measured from end of V <sub>CORE</sub> 's ramp to 50% of RST's rising edge with a 10k pull-up resistor.		2		16	ms
	Tolerance			−20%		30%	
V <sub>OL</sub>	Low output voltage	I <sub>RST</sub> = 1 mA (sinking)			0.27	0.5	V
I <sub>OH</sub>	High output current	V <sub>RST</sub> =2.5 V		−1		1	μA
PROGRAMMABLE GAMMA CORRECTION							
V <sub>DROPH</sub>	High-side output voltage drop	Code = 1023; load = 10 μA, sourcing			5.6	100	mV
		Code = 1023; load = 100 μA, sourcing			44.2	200	
V <sub>DROPL</sub>	Low-side output voltage drop	Code = 0; load = 10 μA, sinking			49.1	100	mV
		Code = 0; load = 100 μA, sinking			65.5	200	

(2) LDO is enabled, when  $V_{IO1} = 2.5\text{ V}$ .

(3) Output voltages greater than 36V require an external cascode transistor or charge pump circuit.

**ELECTRICAL CHARACTERISTICS (continued)**

$V_{IN} = 3.3\text{ V}$ ,  $V_{CORE} = 1.1\text{ V}$ ,  $V_{IO1} = 1.7\text{ V}$ ,  $V_{IO2} = 1.8\text{ V}^{(1)}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $V_{GH} = 24\text{ V}$ ,  $T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$ . Typical values are at  $25^\circ\text{C}$  (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
	Offset	Code = 512	−25		25	mV
INL	Integral nonlinearity	No load, $V_{GAMH} = AV_{DD} - 0.25\text{ V}$ , $V_{GAML} = 0.25\text{ V}$	−3.6		5.9	LSB
DNL	Differential nonlinearity	No load, $V_{GAMH} = AV_{DD} - 0.25\text{ V}$ , $V_{GAML} = 0.25\text{ V}$	−1		1.5	LSB
PROGRAMMABLE $V_{COM}$ CALIBRATOR						
SET <sub>ZSE</sub>	Set zero-scale error		−1		1	LSB
SET <sub>FSE</sub>	Set full-scale error		−7		7	LSB
V <sub>RSET</sub>	Voltage on RSET pin	I <sub>RSET</sub> =50 $\mu$ A	−2%	1.25	2%	V
DNL	Differential nonlinearity		−1		1.5	LSB
A <sub>VOL</sub>	Open loop gain	$V_{CM} = AV_{DD}/2$ , $V_{OUT1} = 2\text{ V}$ , $V_{OUT2} = AV_{DD} - 2\text{ V}$ , $R_L = \infty$	70	91		dB
V <sub>IO</sub>	Input offset voltage	$V_{CM} = AV_{DD}/2$ , $V_{OUT} = AV_{DD}/2$	−15		15	mV
I <sub>B</sub>	Input bias current	$V_{CM} = AV_{DD}/2$ , $V_{OUT} = AV_{DD}/2$	−150		150	nA
V <sub>DROPH</sub>	High-side voltage drop	$V_{POS} = AV_{DD}/2$ , $V_{NEG} = AV_{DD}/2 - 1\text{ V}$ , $I_{OUT} = 10\text{ mA}$ sourcing		0.05	0.1	V
V <sub>DROPL</sub>	Low-side voltage drop	$V_{POS} = AV_{DD}/2$ , $V_{NEG} = AV_{DD}/2 + 1\text{ V}$ , $I_{OUT} = 10\text{ mA}$ sinking		0.03	0.1	V
I <sub>PK</sub>	High-side peak output current	$V_{CM} = AV_{DD}/2$ , $V_{SIGNAL} = 2\text{ V}_{PP}$ , open-loop, $R_L = \infty$ , $C_L = 1\text{ }\mu\text{F}$	200	294		mA
	Low-side peak output current			−349	−200	
CMRR	Common-mode rejection ratio	$V_{CM1} = 2\text{ V}$ , $V_{CM2} = AV_{DD} - 2\text{ V}$ , $V_{OUT} = AV_{DD}/2$	40	78		dB
PSRR	Power supply rejection ratio	$AV_{DD1} = 6\text{ V}$ , $AV_{DD2} = 9.1\text{ V}$ , $V_{CM} = 3\text{ V}$ , $V_{OUT} = 3\text{ V}$	40	110		dB
SR	Slew rate	Open-loop, $V_{POS} = AV_{DD}/2 \pm 1\text{ V}$	$T_A = -40^{\circ}\text{C}$	18	30	V/ $\mu$ s
			$T_A = 25^{\circ}\text{C}$ to $85^{\circ}\text{C}$	25	38	
GATE VOLTAGE SHAPING						
$r_{DS(ON)}$	V <sub>GH</sub> to V <sub>GHM</sub> ON resistance	$V_{GH} = 24\text{ V}$ , $I_{GHM} = 10\text{ mA}$ , $FLK = 2.5\text{ V}$		12	25	$\Omega$
	V <sub>GHM</sub> to RE ON resistance	$V_{GHM} = 24\text{ V}$ , $I_{GHM} = 10\text{ mA}$ , $FLK = 0\text{ V}$		12	25	
			$V_{GHM} = 6\text{ V}$ , $I_{GHM} = 10\text{ mA}$ , $FLK = 0\text{ V}$		12	
t <sub>PLH</sub>	Propagation delay	$V_{GHM}$ rising, 2.5 V, 50% thresholds, $C_{OUT} = 150\text{ pF}$ , $R_E = 0\text{ }\Omega$		72	175	ns
t <sub>PHL</sub>		$V_{GHM}$ falling, 2.5 V, 50% thresholds, $C_{OUT} = 150\text{ pF}$ , $R_E = 0\text{ }\Omega$		81	200	
PANEL RESET / LCD BIAS READY ( $\overline{XAO}$ )						
V <sub>OL</sub>	Low output voltage	$I_{\overline{XAO}} = 1\text{ mA}$ (sinking)		0.23	0.5	V
I <sub>OH</sub>	High output current	$V_{\overline{XAO}} = 2.5\text{ V}$			1	$\mu$ A
V <sub>DET</sub>	$\overline{XAO}$ threshold voltage	$\overline{XAO}$ falling	2.2		3.9	V
	Tolerance		−2.5%		2.5%	
	Hysteresis	$\overline{XAO}$ rising	3%	6.3%	11%	
TIMING						
t <sub>DLY1</sub>	Boost converter 1 delay range		0		70	ms
	Tolerance		−20%		30%	
t <sub>DLY6</sub>	Gate voltage shaping / LCD bias ready delay range		0		35	ms
	Tolerance		−20%		30%	
t <sub>SS1</sub>	Soft-start ramp time	$V_{CORE}$ , $V_{IO1}$ , $V_{IO2}$	0.5		4	ms
	Tolerance		−20%		30%	
t <sub>SS2</sub>	Soft-start ramp time	$AV_{DD}$ , $V_{GH}$	4.0		7.5	ms
	Tolerance		−20%		30%	
t <sub>UVP</sub>	Undervoltage protection timeout		40	50	65	ms
I <sup>2</sup> C INTERFACE						
ADDR	Configuration parameters slave address			74h		
	Programmable VCOM slave address			4Fh		
V <sub>IL</sub>	Low level input voltage	Rising Edge, standard and fast mode			0.75	V

**ELECTRICAL CHARACTERISTICS (continued)**

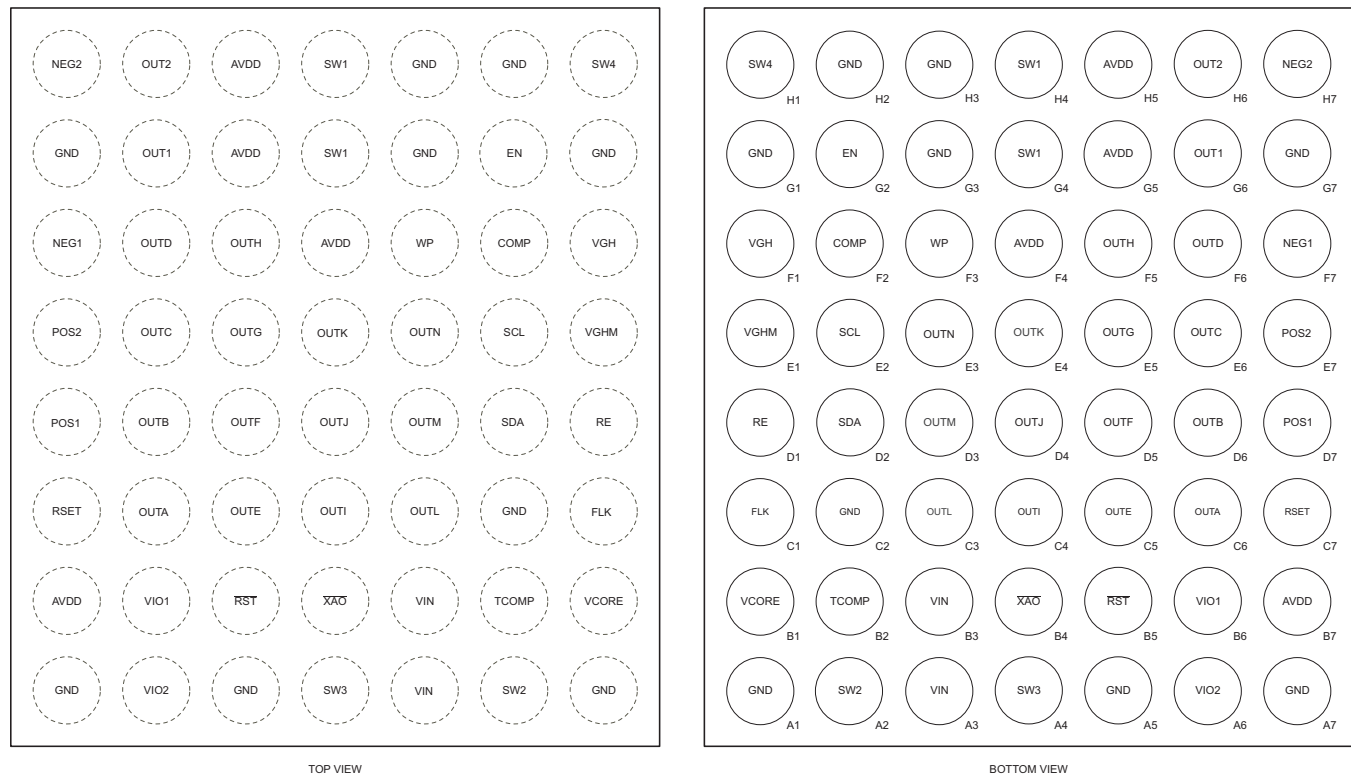
$V_{IN} = 3.3\text{ V}$ ,  $V_{CORE} = 1.1\text{ V}$ ,  $V_{IO1} = 1.7\text{ V}$ ,  $V_{IO2} = 1.8\text{ V}^{(1)}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $V_{GH} = 24\text{ V}$ ,  $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ . Typical values are at  $25^{\circ}\text{C}$  (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>IH</sub>	High level input voltage	Rising edge, standard and fast modes	1.75			V
V <sub>HYS</sub>	Hysteresis	Applicable to fast mode only	125			mV
V <sub>OL</sub>	Low level output voltage	Sinking 3 mA			500	mV
C <sub>I</sub>	Input capacitance				10	pF
f <sub>SCL</sub>	Clock frequency	Standard mode			100	kHz
		Fast mode			400	
t <sub>LOW</sub>	Clock low period	Standard mode	4.7			μs
		Fast mode	1.3			
t <sub>HIGH</sub>	Clock high period	Standard mode	4.0			μs
		Fast mode	0.6			
t <sub>BUF</sub>	Bus free time between a STOP and a START condition	Standard mode	4.7			μs
		Fast mode	1.3			
t <sub>hd:STA</sub>	Hold time for a repeated START condition	Standard mode	4			μs
		Fast mode	0.6			
t <sub>su:STA</sub>	Set-up time for a repeated START condition	Standard mode	4			μs
		Fast mode	0.6			
t <sub>su:DAT</sub>	Data set-up time	Standard mode	250			ns
		Fast mode	100			
t <sub>hd:DAT</sub>	Data hold time	Standard mode	0.05		3.45	μs
		Fast mode	0.05		0.9	
t <sub>RCL1</sub>	Rise time of SCL after a repeated START condition and after an ACK bit	Standard mode	20+0.1C <sub>B</sub>		1000	ns
		Fast mode	20+0.1C <sub>B</sub>		1000	
t <sub>RCL</sub>	Rise time of SCL	Standard mode	20+0.1C <sub>B</sub>		1000	ns
		Fast mode	20+0.1C <sub>B</sub>		300	
t <sub>FCL</sub>	Fall time of SCL	Standard mode	20+0.1C <sub>B</sub>		300	ns
		Fast mode	20+0.1C <sub>B</sub>		300	
t <sub>RDA</sub>	Rise time of SDA	Standard mode	20+0.1C <sub>B</sub>		1000	ns
		Fast mode	20+0.1C <sub>B</sub>		300	
t <sub>FDA</sub>	Fall time of SDA	Standard mode	20+0.1C <sub>B</sub>		300	ns
		Fast mode	20+0.1C <sub>B</sub>		300	
t <sub>su:STO</sub>	Set-up time for STOP condition	Standard mode	4.0			μs
		Fast mode	0.6			
C <sub>B</sub>	Capacitive load on SDA and SCL	Standard mode			400	pF
		Fast mode			400	
EEPROM						
N <sub>WRITE</sub>	Number of write cycles		1000			
t <sub>WRITE</sub>	Write time				100	ms
	Data retention	Storage temperature=150 °C	100			1000 hrs
THERMAL SHUTDOWN						
T <sub>SD</sub> <sup>(4)</sup>	Thermal shutdown threshold		120	150	180	°C

(4) Once triggered, thermal shutdown will remain in the shutdown state until the device is powered down.

## 3 Pin Description

### 3.1 Pin Assignment



### 3.2 Pin Assignment

**Table 3-1. PIN DESCRIPTIONS**

PIN		I/O	DESCRIPTION
NAME	NO.		
GND	A1	P	Ground.
SW2	A2	O	Buck converter 1 ( $V_{CORE}$ ) switch pin.
VIN	A3	P	Supply voltage.
SW3	A4	O	Buck converter 2 ( $V_{IO1}$ ) switch pin.
GND	A5	P	Ground.
VIO2	A6	O	Linear regulator ( $V_{IO2}$ ) output and output sense.
GND	A7	P	Ground.
VCORE	B1	I	Buck converter 1 ( $V_{CORE}$ ) output sense.
TCOMP	B2	I	Boost converter 2 ( $V_{GH}$ ) thermistor network connection.
VIN	B3	P	Supply voltage.
$\overline{XAO}$	B4	O	Panel discharge.
$\overline{RST}$	B5	O	System reset.
VIO1	B6	I	Buck converter 2 ( $V_{IO1}$ ) output sense. (Internally connected as supply voltage for LDO regulator.)
AVDD	B7	I	Boost converter 1 ( $AV_{DD}$ ) output sense. (Internally connected as supply voltage for programmable gamma correction.)
FLK	C1	I	Gate voltage shaping flicker clock.
GND	C2	P	Ground.
OUTL	C3	O	Gamma correction.



**Table 3-1. PIN DESCRIPTIONS (continued)**

PIN		I/O	DESCRIPTION
NAME	NO.		
OUTI	C4	O	Gamma correction.
OUTE	C5	O	Gamma correction.
OUTA	C6	O	Gamma correction.
RSET	C7	O	Reference current-setting resistor connection.
RE	D1	O	Gate voltage shaping discharge resistor connection.
SDA	D2	I/O	I <sup>2</sup> C serial data.
OUTM	D3	O	Gamma correction.
OUTJ	D4	O	Gamma correction.
OUTF	D5	O	Gamma correction.
OUTB	D6	O	Gamma correction.
POS1	D7	I	V <sub>COM1</sub> non-inverting input.
VGHM	E1	O	Gate voltage shaping output.
SCL	E2	I/O	I <sup>2</sup> C serial clock.
OUTN	E3	O	Gamma correction.
OUTK	E4	O	Gamma correction.
OUTG	E5	O	Gamma correction.
OUTC	E6	O	Gamma correction.
POS2	E7	I	V <sub>COM2</sub> non-inverting input.
VGH	F1	I	Boost converter 2 (V <sub>GH</sub> ) output sense. (Internally connected as supply voltage for the gate voltage shaping.)
COMP	F2	O	Boost converter 1 (AV <sub>DD</sub> ) compensation network connection.
WP	F3	I	EEPROM write protect.
AVDD	F4	I	V <sub>COM1</sub> and V <sub>COM2</sub> supply voltage.
OUTH	F5	O	Gamma correction.
OUTD	F6	O	Gamma correction.
NEG1	F7	I	V <sub>COM1</sub> inverting input.
GND	G1	P	Ground.
EN	G2	I	Boost converter 1 (AV <sub>DD</sub> ) enable.
GND	G3	P	Ground.
SW1	G4	O	Boost converter 1 (AV <sub>DD</sub> ) switch pin.
AVDD	G5	O	Boost converter 1 (AV <sub>DD</sub> ) rectifier output.
OUT1	G6	O	V <sub>COM1</sub> output.
GND	G7	P	Ground.
SW4	H1	O	Boost converter 2 (V <sub>GH</sub> ) switch pin.
GND	H2	P	Ground
GND	H3	P	Ground.
SW1	H4	O	Boost converter 1 (AV <sub>DD</sub> ) switch pin.
AVDD	H5	O	Boost converter 1 (AV <sub>DD</sub> ) rectifier output.
OUT2	H6	O	V <sub>COM2</sub> output.
NEG2	H7	I	V <sub>COM2</sub> inverting input.

## 4 Typical Characteristics

### 4.1 Table of Graphs

PARAMETER		TEST CONDITIONS		FIGURE
Boost Converter 1 ( $AV_{DD}$ )	Efficiency	$AV_{DD} = 6\text{ V}, 8\text{ V}, 9.1\text{ V}$ $FREQ = 0, FREQ = 1$	$V_{IN} = 3.3\text{ V}$	Figure 4-1
			$V_{IN} = 5\text{ V}$	Figure 4-2
	Line Regulation	$V_{IN} = 2.6\text{ V to } 6.0\text{ V}, AV_{DD} = 8\text{ V}, I_{AV_{DD}} = 100\text{ mA}$		Figure 4-3
	Load Regulation	$V_{IN} = 3.4\text{ V}, 5.0\text{ V}, AV_{DD} = 8\text{ V}, I_{AV_{DD}} = 1\text{ mA to } 500\text{ mA}$		Figure 4-4
	Line Transient Response	$V_{IN} = 3\text{ V to } 4.8\text{ V (dV/dt = 7.5 V/ms)}, AV_{DD} = 8.1\text{ V}$	$R_L = 82\ \Omega$	Figure 4-5
			$R_L = 33\ \Omega$	Figure 4-6
	Load Transient Response	$AV_{DD} = 8.1\text{ V}, I_{AV_{DD}} = 20\text{ mA} - 200\text{ mA}$	$V_{IN} = 3.3\text{ V}$	Figure 4-7
			$V_{IN} = 5.0\text{ V}$	Figure 4-8
	Output Voltage Ripple	$AV_{DD} = 8.1\text{ V}, R_L = 82\ \Omega$	$V_{IN} = 3.3\text{ V}$	Figure 4-9
			$V_{IN} = 5.0\text{ V}$	Figure 4-10
	Switching Waveforms	$V_{IN} = 3.3\text{ V}, AV_{DD} = 8.1\text{ V}$ $FREQ = 0$	$R_L = 820\ \Omega$	Figure 4-11
			$R_L = 82\ \Omega$	Figure 4-12
		$V_{IN} = 3.3\text{ V}, AV_{DD} = 8.1\text{ V}$ $FREQ = 1$	$R_L = 820\ \Omega$	Figure 4-13
			$R_L = 82\ \Omega$	Figure 4-14
	Switching Frequency	$V_{IN} = 2.6\text{ V to } 6\text{ V}, AV_{DD} = 6\text{ V}, 8\text{ V}, 9.1\text{ V}$	$R_L = 82\ \Omega$	Figure 4-15
Buck Converter 1 ( $V_{CORE}$ )	Efficiency	$V_{CORE} = 1\text{ V}, 1.1\text{ V}, 1.2\text{ V}, 1.3\text{ V}, I_{CORE} = 1\text{ mA to } 500\text{ mA}$	$V_{IN} = 3.4\text{ V}$	Figure 4-16
			$V_{IN} = 5.0\text{ V}$	Figure 4-17
	Line Regulation	$V_{IN} = 2.6\text{ V to } 6\text{ V}, V_{CORE} = 1.1\text{ V}, I_{CORE} = 300\text{ mA}$		Figure 4-18
	Load Regulation	$V_{IN} = 3.4\text{ V}, 5\text{ V}, V_{CORE} = 1.1\text{ V}, I_{CORE} = 1\text{ mA to } 700\text{ mA}$		Figure 4-19
	Line Transient Response	$V_{IN} = 3\text{ V to } 4.8\text{ V (dV/dt = 7.5 V/ms)}, V_{CORE} = 1.1\text{ V}, \text{Load} = 3.9\ \Omega$		Figure 4-20
	Load Transient Response	$V_{CORE} = 1.1\text{ V}, I_{CORE} = 50\text{ mA to } 200\text{ mA}$	$V_{IN} = 3.3\text{ V}$	Figure 4-20
			$V_{IN} = 5\text{ V}$	Figure 4-22
	Output Voltage Ripple	$V_{CORE} = 1.1\text{ V}, R_L = 3.9\ \Omega$	$V_{IN} = 3.3\text{ V}$	Figure 4-23
			$V_{IN} = 5\text{ V}$	Figure 4-24
	Switching Waveforms	$V_{IN} = 3.3\text{ V}, V_{CORE} = 1.1\text{ V}$	$R_L = 120\ \Omega$	Figure 4-25
			$R_L = 3.9\ \Omega$	Figure 4-26
	Switching Frequency	$V_{IN} = 2.6\text{ V to } 6\text{ V}, V_{CORE} = 1.1\text{ V}$	$R_L = 12\ \Omega$	Figure 4-27
Buck Converter 2 ( $V_{IO1}$ )	Efficiency	$V_{IO1} = 1.7\text{ V}, 1.8\text{ V}, 2.5\text{ V}, I_{IO1} = 1\text{ mA to } 500\text{ mA}$	$V_{IN} = 3.3\text{ V}$	Figure 4-28
			$V_{IN} = 5\text{ V}$	Figure 4-29
	Line Regulation	$V_{IN} = 2.6\text{ V to } 6\text{ V}, V_{IO1} = 1.7\text{ V}, I_{IO1} = 100\text{ mA}$		Figure 4-30
	Load Regulation	$V_{IN} = 3.4\text{ V}, 5\text{ V}, V_{IO1} = 1.7\text{ V}, I_{IO1} = 1\text{ mA to } 400\text{ mA}$		Figure 4-31
	Line Transient Response	$V_{IN} = 3\text{ V to } 4.8\text{ V (dV/dt = 7.5 V/ms)}, V_{IO1} = 1.7\text{ V}, R_L = 27\ \Omega$		Figure 4-32
	Load Transient Response	$V_{IO1} = 1.7\text{ V}, I_{IO1} = 50\text{ mA to } 100\text{ mA}$	$V_{IN} = 3.3\text{ V}$	Figure 4-33
			$V_{IN} = 5\text{ V}$	Figure 4-34
	Output Voltage Ripple	$V_{IO1} = 1.7\text{ V}, R_L = 27\ \Omega$	$V_{IN} = 3.3\text{ V}$	Figure 4-35
			$V_{IN} = 5\text{ V}$	Figure 4-36
	Switching Waveforms	$V_{IN} = 3.3\text{ V}, V_{IO1} = 1.7\text{ V}$	$R_L = 270\ \Omega$	Figure 4-37
			$R_L = 27\ \Omega$	Figure 4-38
	Switching Frequency	$V_{IN} = 2.6\text{ V to } 6\text{ V}, V_{IO1} = 1.7\text{ V}$	$R_L = 27\ \Omega$	Figure 4-39
LDO Regulator ( $V_{IO2}$ )	Load Regulation	$V_{IO1} = 2.5\text{ V}, V_{IO2} = 1.8\text{ V}, I_{IO2} = 1\text{ mA to } 100\text{ mA}$		Figure 4-40
	Line Transient Response	$V_{IN} = 3\text{ V to } 4.8\text{ V (dV/dt = 7.5 V/ms)}, V_{IO1} = 2.5\text{ V}, V_{IO2} = 1.8\text{ V}, R_L = 27\ \Omega$		Figure 4-41
	Load Transient Response	$V_{IN} = 3.3\text{ V}, V_{IO1} = 2.5\text{ V}, V_{IO2} = 1.8\text{ V}, I_{IO2} = 50\text{ mA to } 150\text{ mA}$		Figure 4-42
	Output Voltage Ripple	$V_{IN} = 3.3\text{ V}, V_{IO1} = 2.5\text{ V}, V_{IO2} = 1.8\text{ V}, R_L = 27\ \Omega$		Figure 4-43

PARAMETER		TEST CONDITIONS	FIGURE
Boost Converter 2 (V <sub>GH</sub> )	Efficiency	AV <sub>DD</sub> = 8.1 V, V <sub>GH</sub> = 20 V, 24 V, 28 V, 31 V	Figure 4-44
	Line Regulation	AV <sub>DD</sub> = 6 V to 9.1 V, I <sub>GH</sub> = 10 mA	Figure 4-45
	Load Regulation	AV <sub>DD</sub> = 8.1 V, V <sub>GH</sub> = 24 V, I <sub>GH</sub> = 1 mA to 50 mA	Figure 4-46
	Line Transient Response	V <sub>IN</sub> = 3V to 4.8 V (dV/dt = 7.5 V/ms), V <sub>GH</sub> = 24 V	R <sub>L</sub> = 4.8 kΩ Figure 4-47
			R <sub>L</sub> = 1.2 kΩ Figure 4-48
	Load Transient Response	V <sub>IN</sub> = 5 V, AV <sub>DD</sub> = 8.1 V, V <sub>GH</sub> = 24 V	I <sub>GH</sub> = 5 mA to 10 mA Figure 4-49
			I <sub>GH</sub> = 10 mA to 30 mA Figure 4-50
	Output Voltage Ripple	V <sub>IN</sub> = 3.3 V, AV <sub>DD</sub> = 8.1 V, R <sub>L</sub> = 82 Ω, V <sub>GH</sub> = 24 V	R <sub>L</sub> = 4.8 kΩ Figure 4-51
			R <sub>L</sub> = 1.2 kΩ Figure 4-52
Power-Up Behavior	Switching Waveforms	V <sub>IN</sub> = 3.3 V, AV <sub>DD</sub> = 8.1 V, Load = 82 Ω, V <sub>GH</sub> = 24 V	R <sub>L</sub> = 4.8 kΩ Figure 4-53
			R <sub>L</sub> = 1.2 kΩ Figure 4-54
	Switching Frequency	V <sub>IN</sub> = 3.3 V, AV <sub>DD</sub> = 7 V, 8 V, 9 V, V <sub>GH</sub> = 16 V to 31 V	Figure 4-55
	V <sub>IN</sub> , V <sub>IO1</sub> , V <sub>IO2</sub> , V <sub>CORE</sub>	V <sub>IN</sub> = 3.3 V, t <sub>SS1</sub> = 0.5 ms, V <sub>IO1</sub> = 2.5 V, R <sub>L</sub> = 27 Ω, V <sub>IO2</sub> = 1.8 V, R <sub>L</sub> = ∞, V <sub>CORE</sub> = 1.1 V	R <sub>L</sub> = 3.9 Ω Figure 4-56
	EN, AV <sub>DD</sub> , V <sub>GH</sub>	V <sub>IN</sub> = 3.3 V, t <sub>SS2</sub> = 4.0 ms, AV <sub>DD</sub> = 8.1 V, R <sub>L</sub> = 33 Ω, V <sub>GH</sub> = 24 V, 1.2 kΩ	t <sub>DLY1</sub> = 0 ms Figure 4-57
			t <sub>DLY1</sub> = 10 ms Figure 4-58
	$\overline{\text{XAO}}$ , AV <sub>DD</sub> , V <sub>GH</sub> , V <sub>GHM</sub>	V <sub>IN</sub> = 3.3 V, AV <sub>DD</sub> = 8.1 V, R <sub>L</sub> = 33 Ω, V <sub>GH</sub> = 24 V, R <sub>L</sub> = 1.2 kΩ, GIP = 0	t <sub>DLY6</sub> = 0 ms Figure 4-59
			t <sub>DLY6</sub> = 10 ms Figure 4-60
	$\overline{\text{XAO}}$ , AV <sub>DD</sub> , V <sub>GH</sub> , V <sub>GHM</sub>	V <sub>IN</sub> = 3.3 V, AV <sub>DD</sub> = 8.1 V, R <sub>L</sub> = 33 Ω, V <sub>GH</sub> = 24 V, R <sub>L</sub> = 1.2 kΩ, GIP = 1	t <sub>DLY6</sub> = 0 ms Figure 4-61
			t <sub>DLY6</sub> = 10 ms Figure 4-62
Power-Down Behavior	AV <sub>DD</sub> , V <sub>GH</sub> , V <sub>COM</sub> , V <sub>GAMA</sub>	V <sub>IN</sub> = 3.3 V, AV <sub>DD</sub> = 8.1 V, V <sub>GH</sub> = 24 V, V <sub>COM</sub> = 4.05 V, V <sub>GAMA</sub> = 4.05 V	Figure 4-63
	$\overline{\text{RST}}$ , V <sub>IO1</sub> , V <sub>IO2</sub> , V <sub>CORE</sub>	V <sub>DET</sub> = 2.5 V	R <sub>MODE</sub> = 0 Figure 4-64
			R <sub>MODE</sub> = 1 Figure 4-65
	V <sub>IN</sub> , $\overline{\text{XAO}}$ , AV <sub>DD</sub> , V <sub>GHM</sub>	GIP = 0	Figure 4-66
	AV <sub>DD</sub> , V <sub>GH</sub> , V <sub>COM</sub> , V <sub>GAMA</sub>		SMODE = 0 Figure 4-67
			SMODE = 1 Figure 4-68
Gate Voltage Shaping	FLK, V <sub>GHM</sub>	V <sub>IN</sub> = 3.3 V, R <sub>E</sub> = 1 kΩ, C <sub>L</sub> = 10 nF, AV <sub>DD</sub> = 8.1 V, R <sub>L</sub> = 33 Ω, V <sub>GH</sub> = 24 V, R <sub>L</sub> = 1.2 kΩ	Figure 4-69
Op-Amp	Large-Signal Response	V <sub>POS</sub> = 3.8 V ± 0.5 V	Figure 4-70
	Small-Signal Bandwidth	AV <sub>DD</sub> = 8.1 V, V <sub>POS2</sub> = 63 mV <sub>PP</sub> , A <sub>V</sub> = +1, R <sub>F</sub> = 0 Ω	Figure 4-71
	Gain Bandwidth	AV <sub>DD</sub> = 8.1 V, V <sub>POS2</sub> = 63 mV <sub>PP</sub> , A <sub>V</sub> = +1, R <sub>F</sub> = 0 Ω	Figure 4-72
	Peak Output Current	AV <sub>DD</sub> = 8.1 V, R <sub>L</sub> = 2 kΩ to AV <sub>DD</sub> /2, C <sub>L</sub> = 1 μF	Figure 4-73
	Line Transient Response	V <sub>IN</sub> = 3.0 V to 4.8 V (dV/dt = 7.5 V/ms), AV <sub>DD</sub> = 8.1 V, V <sub>COM</sub> = 4 V, R <sub>L</sub> = ∞	Figure 4-74
	Output Voltage Ripple and Noise	V <sub>IN</sub> = 3.3 V, 8.1 V, R <sub>L</sub> = 82 Ω, V <sub>COM</sub> = 4 V, R <sub>L</sub> = ∞	Figure 4-75
Programmable Gamma	Dynamic Response	AV <sub>DD</sub> = 8.1 V, R <sub>L</sub> = 909 kΩ, C <sub>L</sub> = 55 pF	GAMA = 0x0ff/0x2ff Figure 4-76
			GAMA = 0x2ff/0x0ff Figure 4-77
	Line Transient Response	V <sub>IN</sub> = 3.0 V to 4.8 V (dV/dt = 7.5 V/ms), AV <sub>DD</sub> = 8.1 V	GAMA = 0x0ff Figure 4-78
			GAMA = 0x1ff Figure 4-79
			GAMA = 0x2ff Figure 4-80
	Output Voltage Ripple and Noise	V <sub>IN</sub> = 3.3 V, 8.1 V, R <sub>L</sub> = 82 Ω	GAMA = 0x1ff Figure 4-81

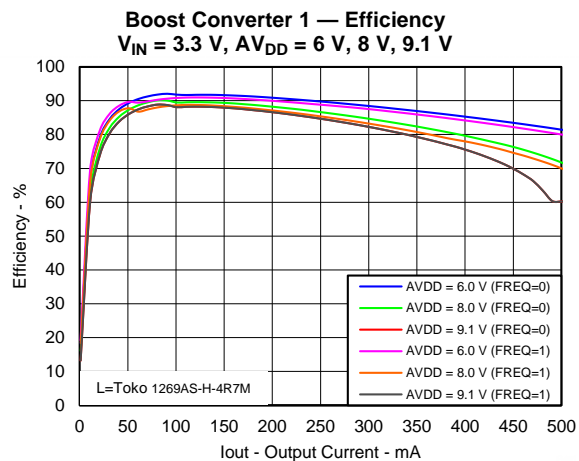


Figure 4-1.

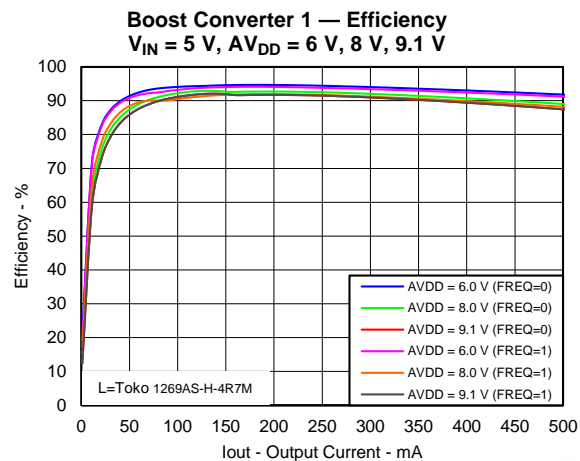


Figure 4-2.

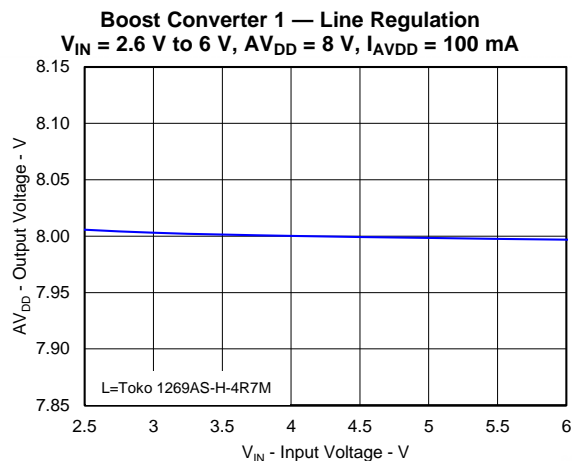


Figure 4-3.

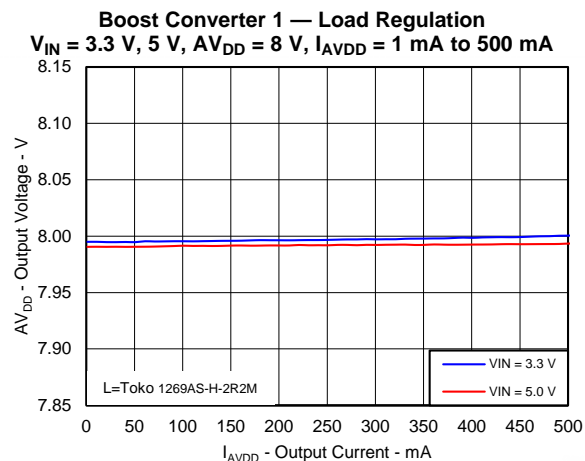


Figure 4-4.

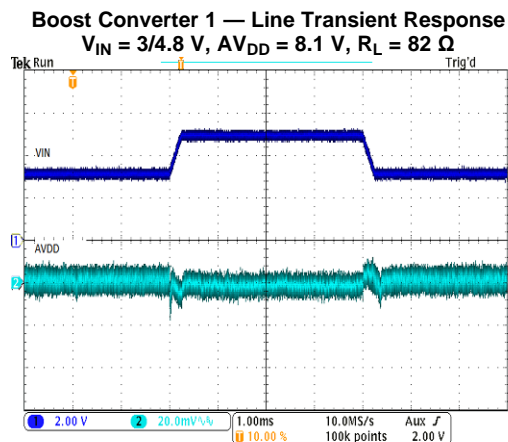


Figure 4-5.

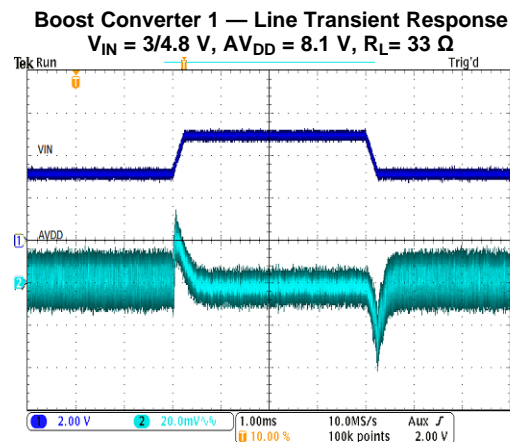


Figure 4-6.

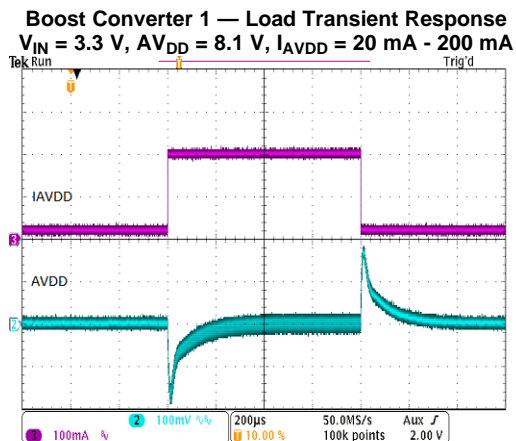


Figure 4-7.

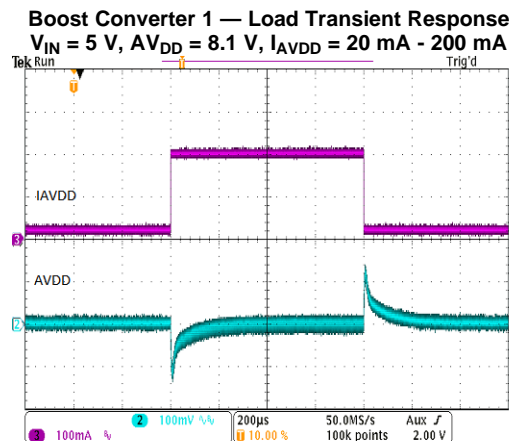


Figure 4-8.

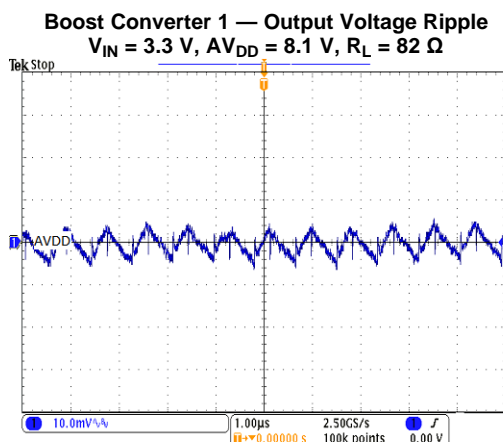


Figure 4-9.

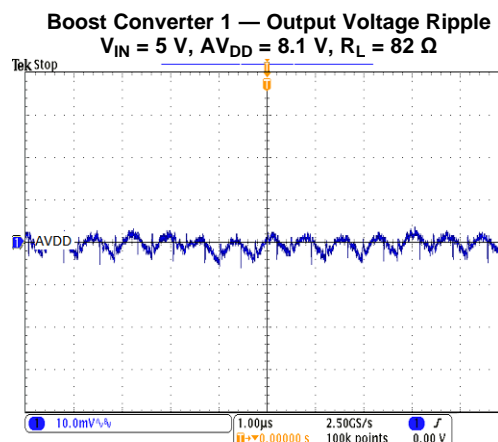


Figure 4-10.

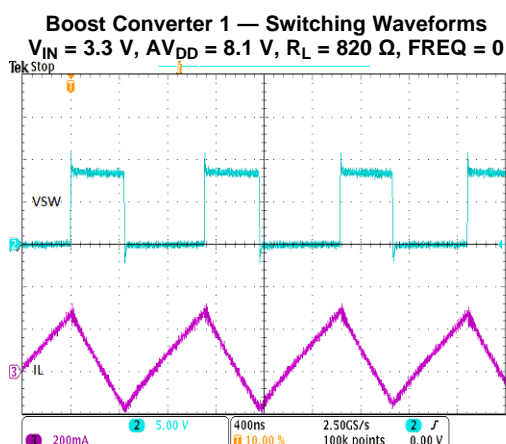


Figure 4-11.

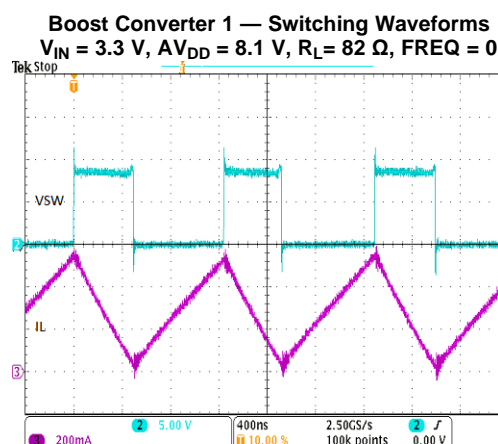


Figure 4-12.

**Boost Converter 1 — Switching Waveforms**  
 $V_{IN} = 3.3\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 820\ \Omega$ ,  $FREQ = 1$

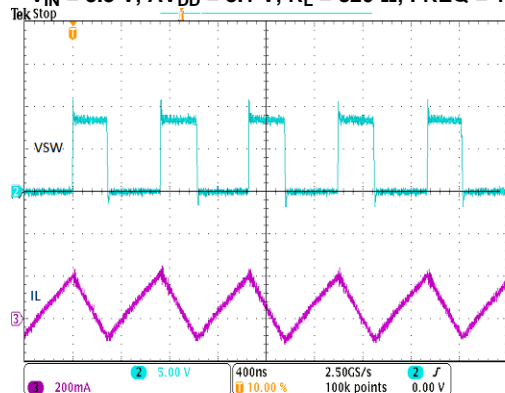


Figure 4-13.

**Boost Converter 1 — Switching Waveforms**  
 $V_{IN} = 3.3\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 82\ \Omega$ ,  $FREQ = 1$

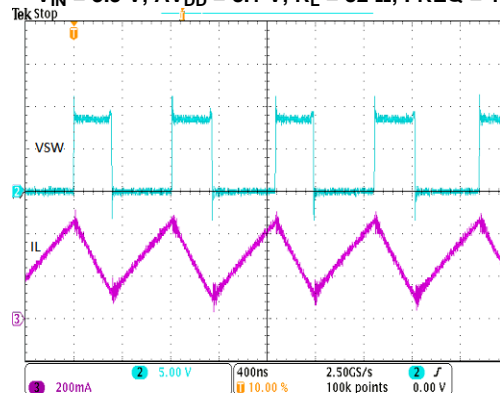


Figure 4-14.

**Boost Converter 1 — Switching Frequency**  
 $V_{IN} = 2.6\text{ V to } 6\text{ V}$ ,  $AV_{DD} = 6\text{ V, } 8\text{ V, } 9.1\text{ V}$ ,  $R_L = 82\ \Omega$

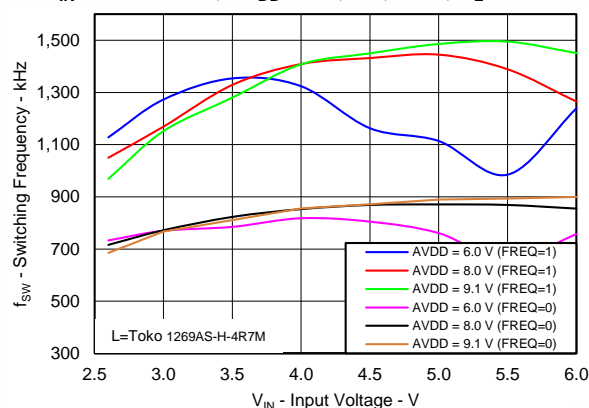


Figure 4-15.

**Buck Converter 1 — Efficiency**  
 $V_{IN} = 3.4\text{ V}$ ,  $V_{CORE} = 1\text{ V, } 1.1\text{ V, } 1.2\text{ V, } 1.3\text{ V}$ ,  $I_{CORE} = 1\text{ mA to } 500\text{ mA}$

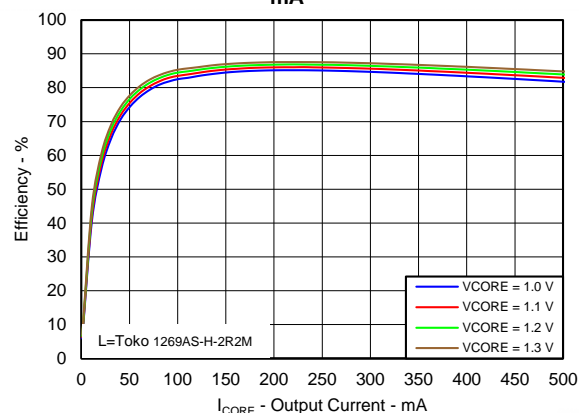


Figure 4-16.

**Buck Converter 1 — Efficiency**  
 $V_{IN} = 5\text{ V}$ ,  $V_{CORE} = 1\text{ V, } 1.1\text{ V, } 1.2\text{ V, } 1.3\text{ V}$ ,  $I_{CORE} = 1\text{ mA to } 500\text{ mA}$

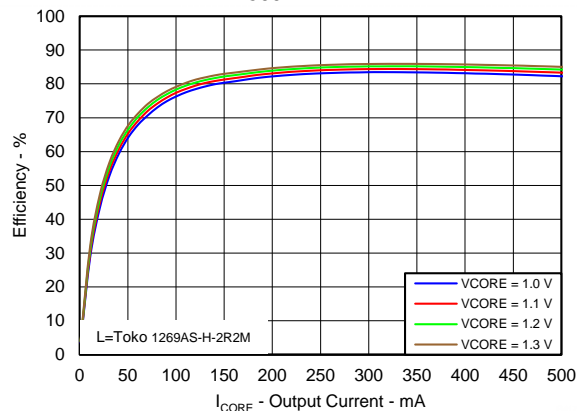


Figure 4-17.

**Buck Converter 1 — Line Regulation**  
 $V_{IN} = 2.6\text{ V to } 6\text{ V}$ ,  $V_{CORE} = 1.1\text{ V}$ ,  $I_{CORE} = 300\text{ mA}$

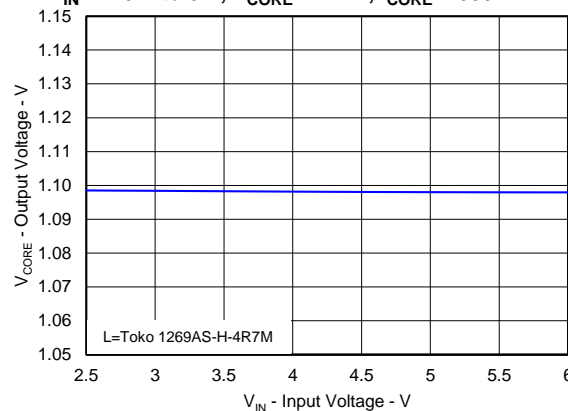


Figure 4-18.

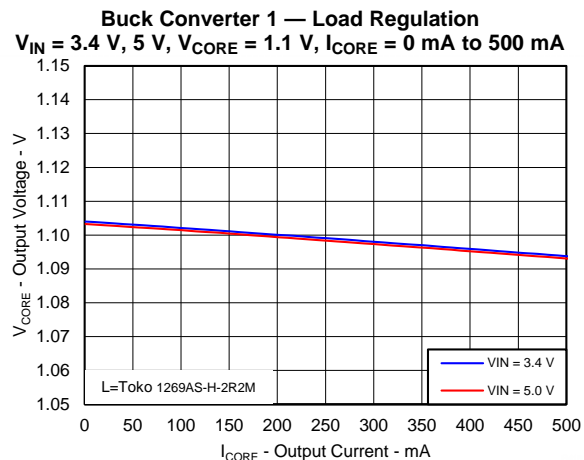


Figure 4-19.

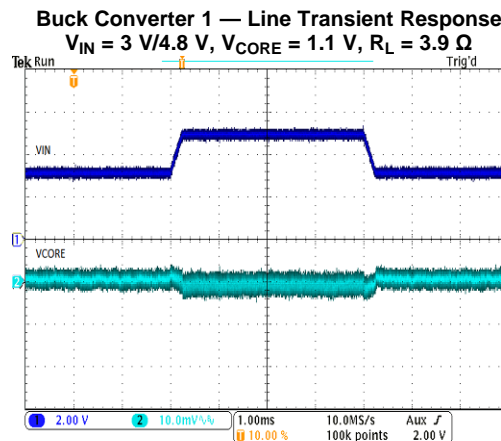


Figure 4-20.

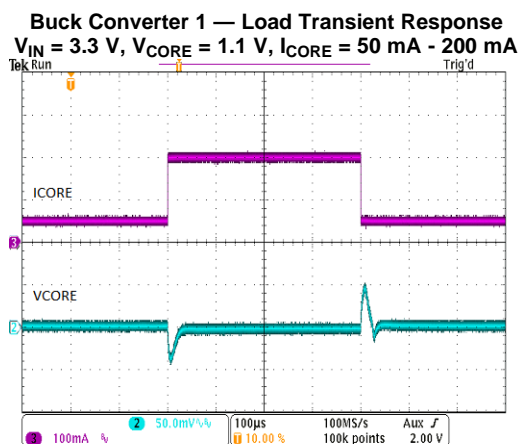


Figure 4-21.

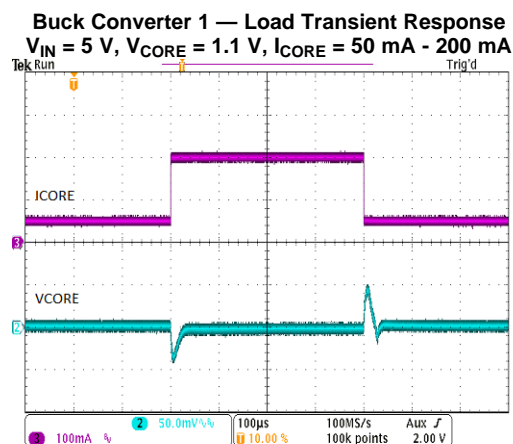


Figure 4-22.

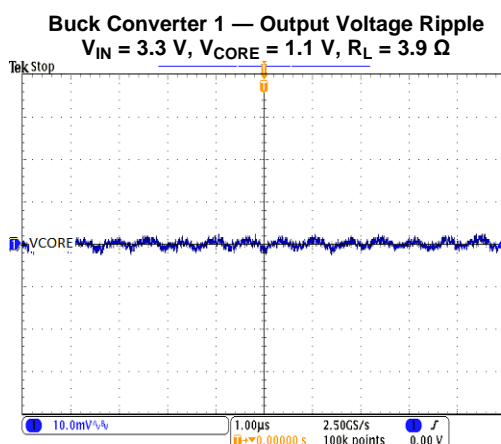


Figure 4-23.

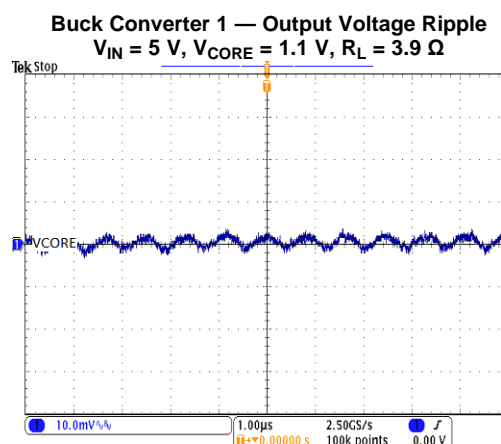


Figure 4-24.

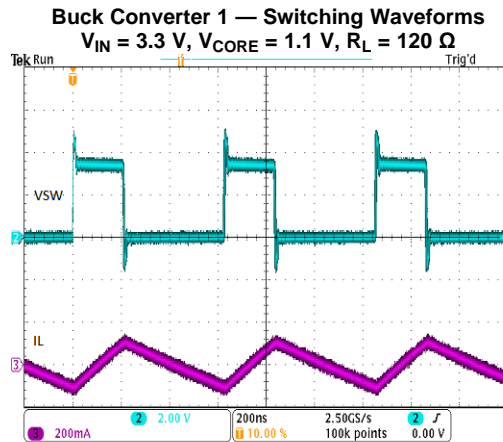


Figure 4-25.

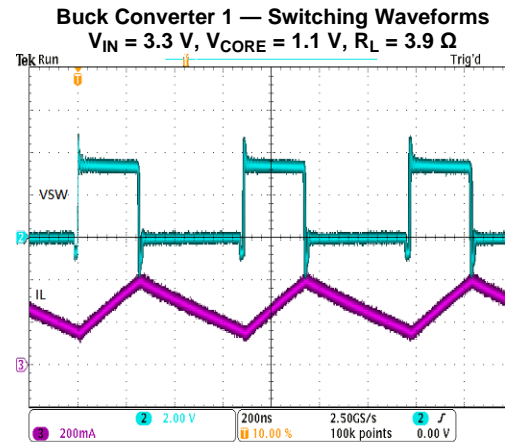


Figure 4-26.

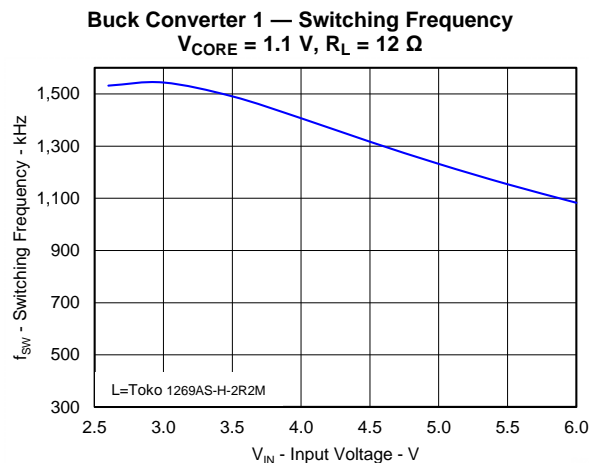


Figure 4-27.

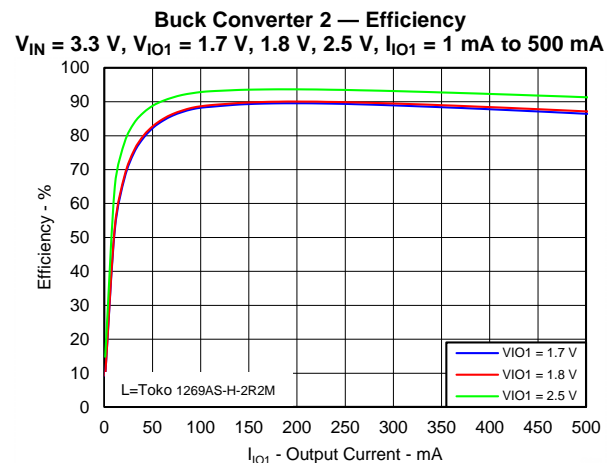


Figure 4-28.

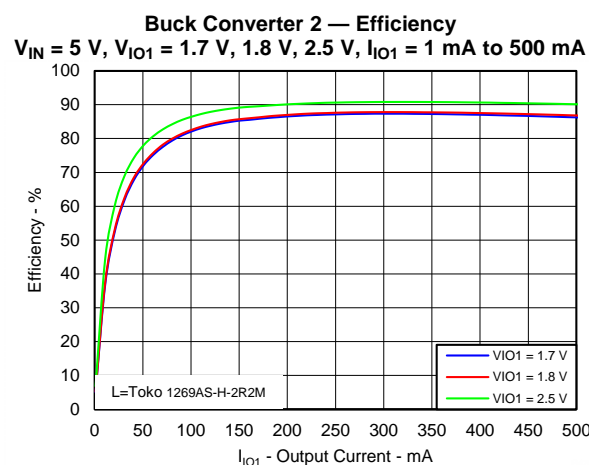


Figure 4-29.

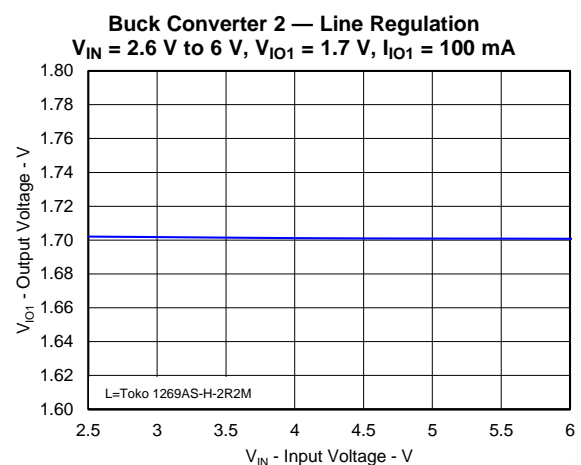


Figure 4-30.



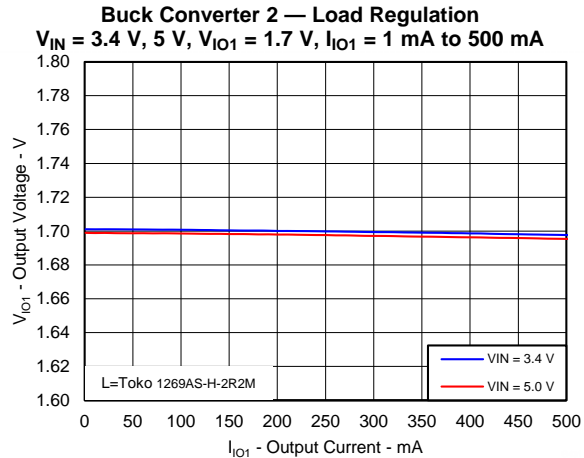


Figure 4-31.

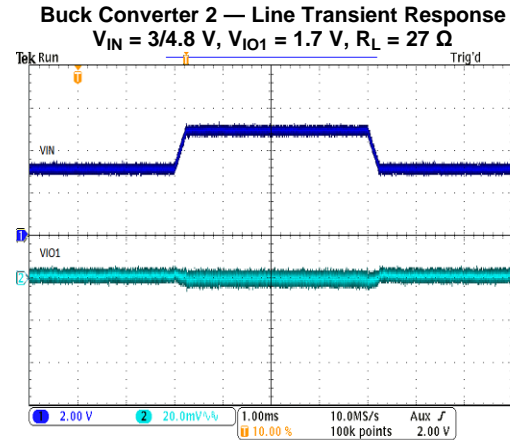


Figure 4-32.

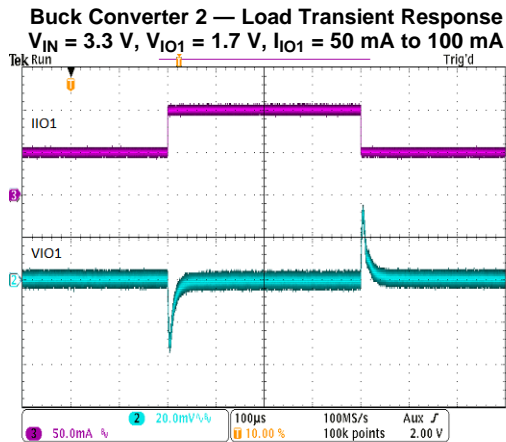


Figure 4-33.

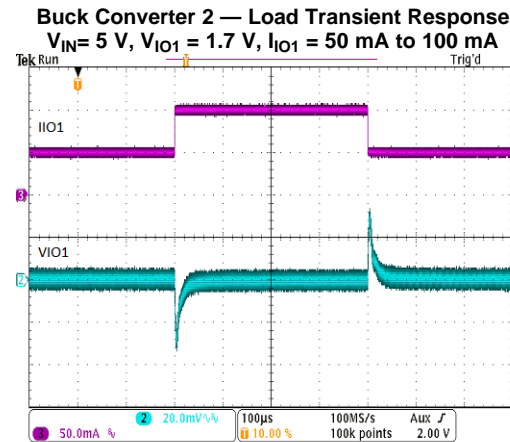


Figure 4-34.

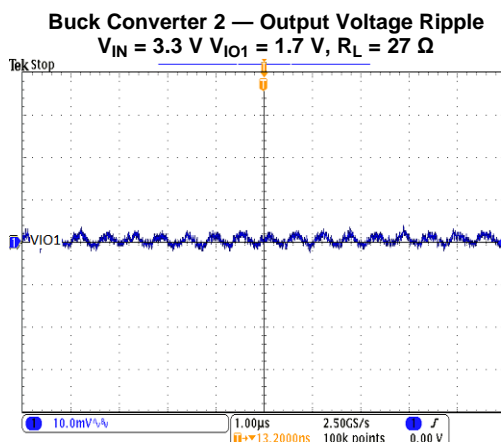


Figure 4-35.

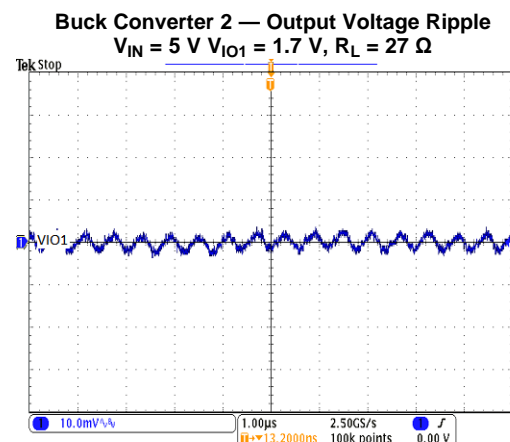


Figure 4-36.

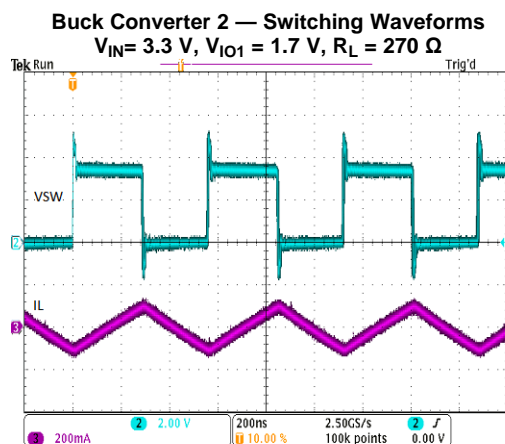


Figure 4-37.

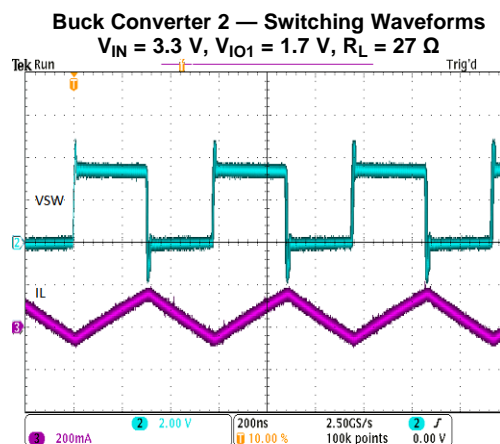


Figure 4-38.

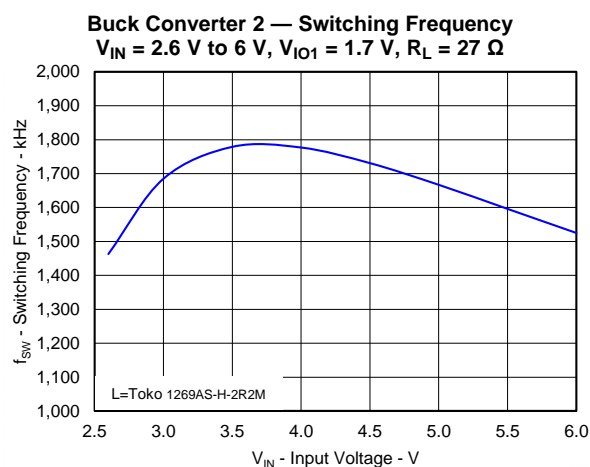


Figure 4-39.

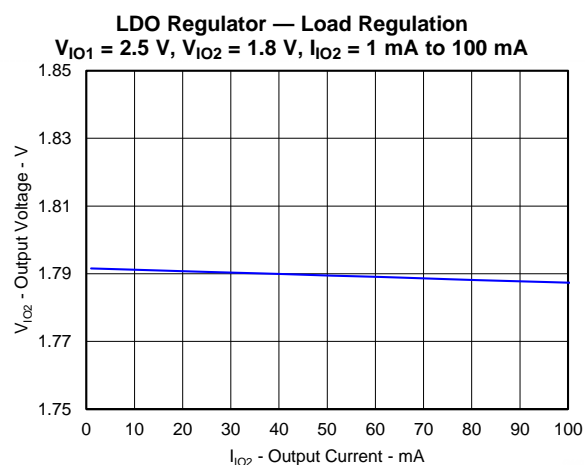


Figure 4-40.

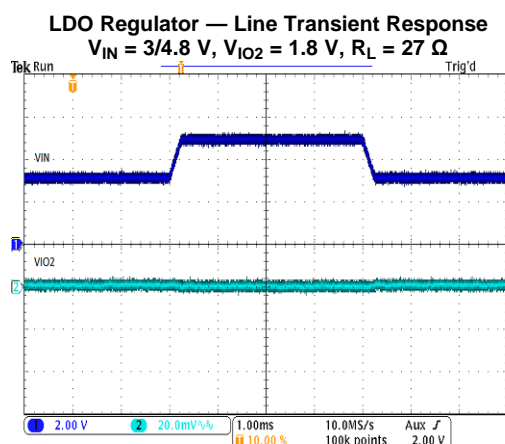


Figure 4-41.

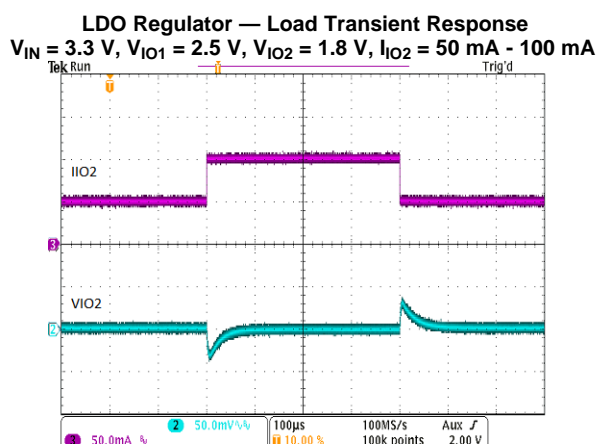


Figure 4-42.

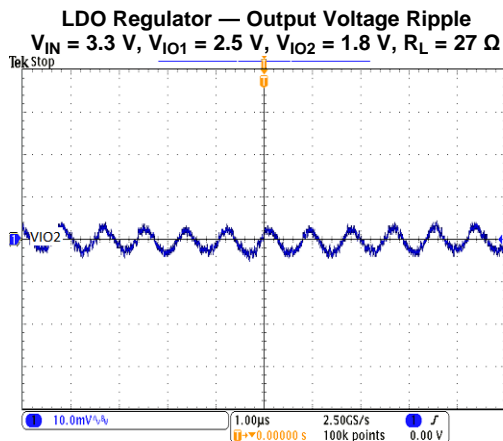


Figure 4-43.

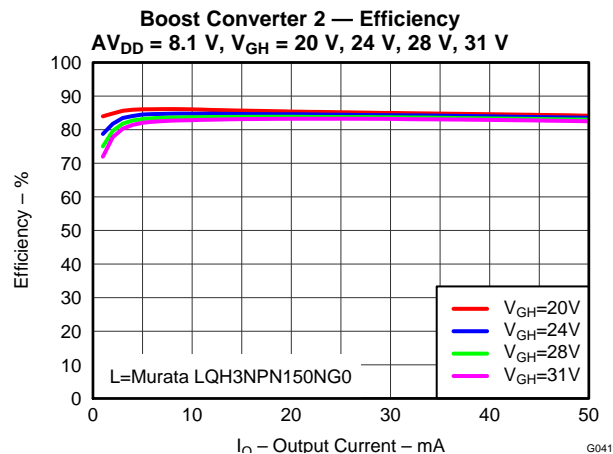


Figure 4-44.

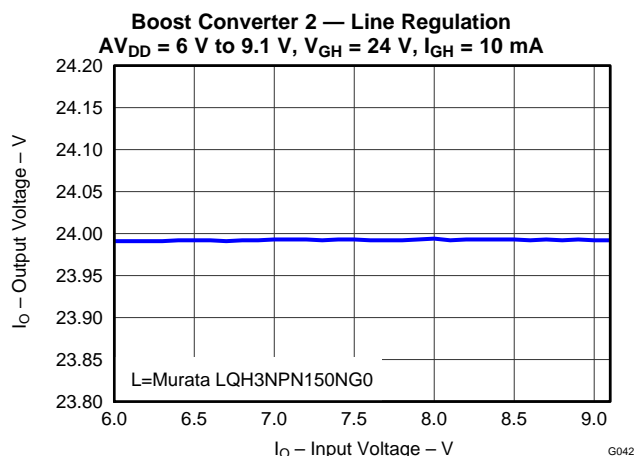


Figure 4-45.

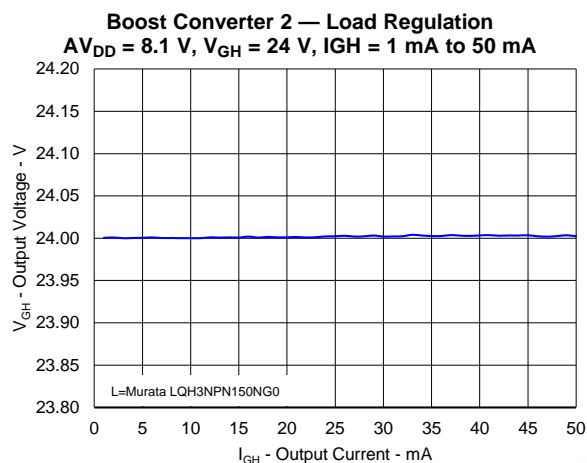


Figure 4-46.

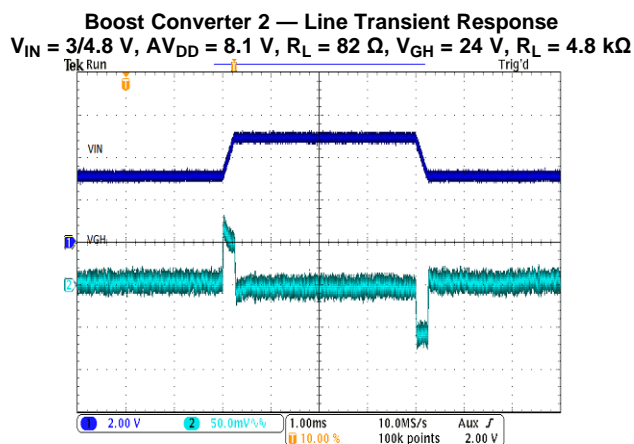


Figure 4-47.

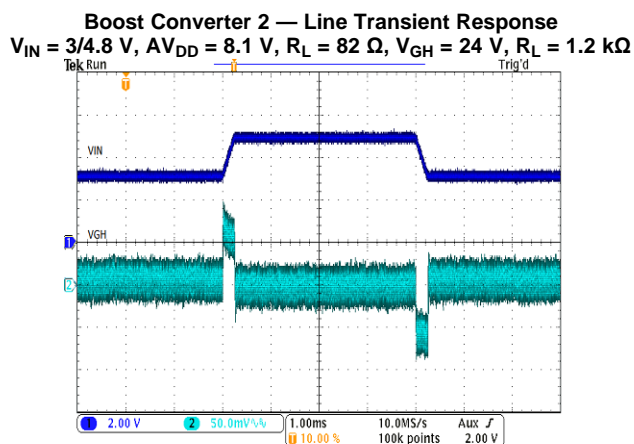


Figure 4-48.

**Boost Converter 2 — Load Transient Response**  
 $V_{IN} = 3.3\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 82\ \Omega$ ,  $V_{GH} = 24\text{ V}$ ,  $I_{GH} = 5\text{--}10\text{ mA}$

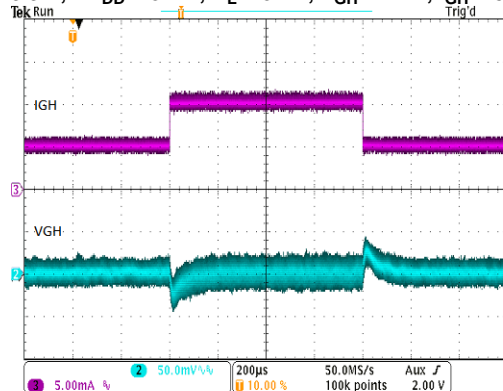


Figure 4-49.

**Boost Converter 2 — Load Transient Response**  
 $V_{IN} = 3.3\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 82\ \Omega$ ,  $V_{GH} = 24\text{ V}$ ,  $I_{GH} = 10\text{--}30\text{ mA}$

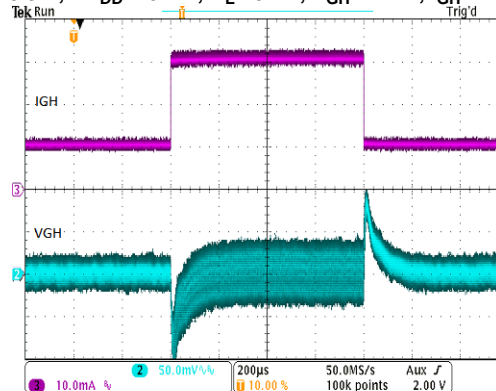


Figure 4-50.

**Boost Converter 2 – Output Voltage Ripple**  
 $V_{IN} = 3.3\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 82\ \Omega$ ,  $V_{GH} = 24\text{ V}$ ,  $R_L = 4.8\text{ k}\Omega$

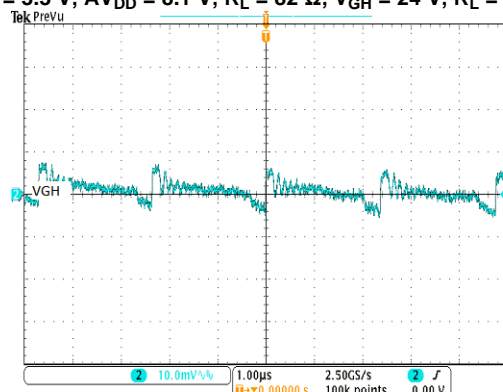


Figure 4-51.

**Boost Converter 2 – Output Voltage Ripple**  
 $V_{IN} = 3.3\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 82\ \Omega$ ,  $V_{GH} = 24\text{ V}$ ,  $R_L = 1.2\text{ k}\Omega$

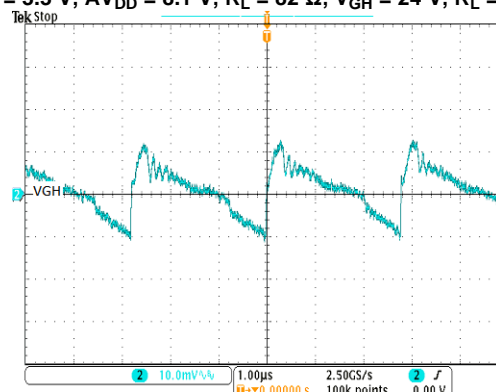


Figure 4-52.

**Boost Converter 2 – Switching Waveforms**  
 $V_{IN} = 3.3\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 82\ \Omega$ ,  $V_{GH} = 24\text{ V}$ ,  $R_L = 4.8\text{ k}\Omega$

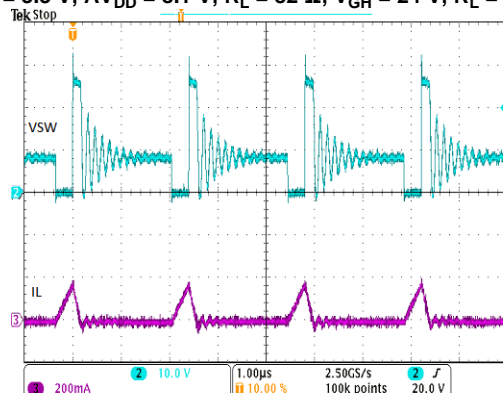


Figure 4-53.

**Boost Converter 2 – Switching Waveforms**  
 $V_{IN} = 3.3\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 82\ \Omega$ ,  $V_{GH} = 24\text{ V}$ ,  $R_L = 1.2\text{ k}\Omega$

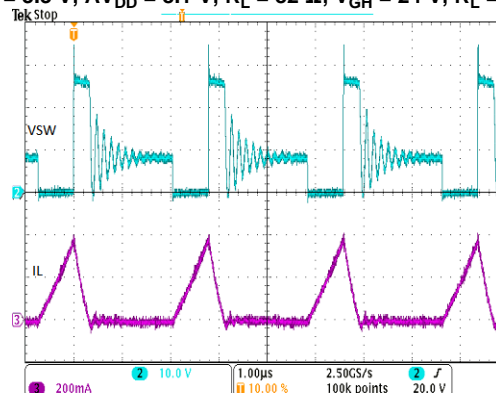


Figure 4-54.

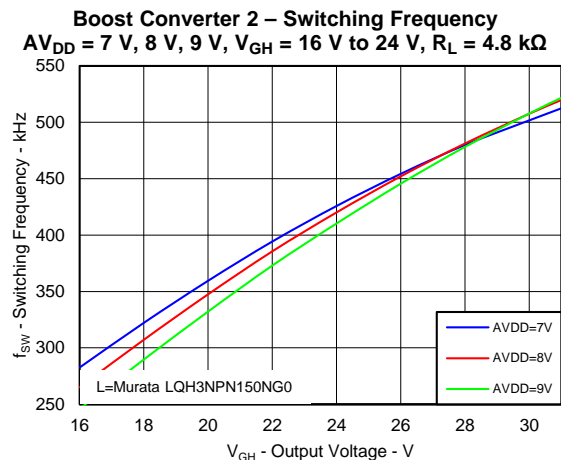


Figure 4-55.

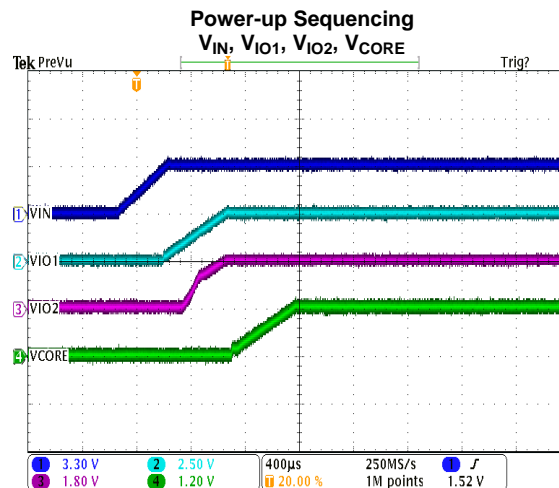


Figure 4-56.

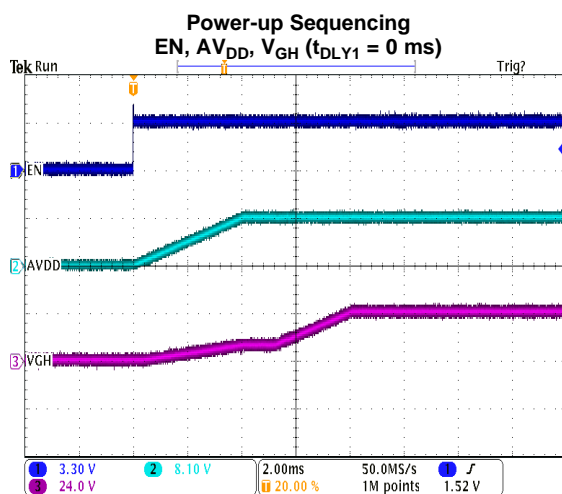


Figure 4-57.

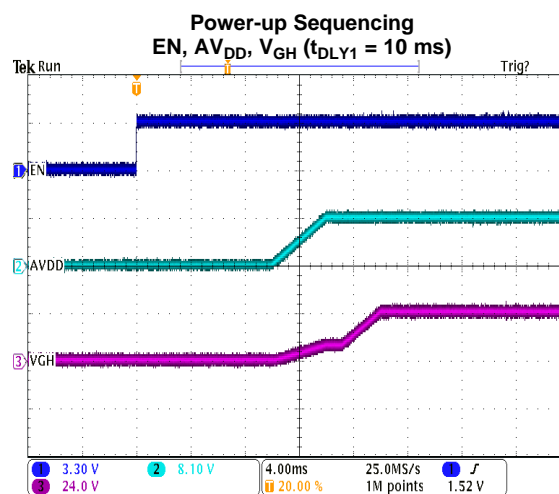


Figure 4-58.

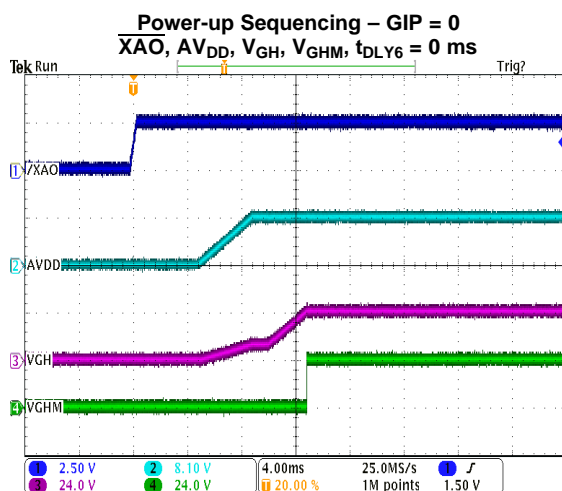


Figure 4-59.

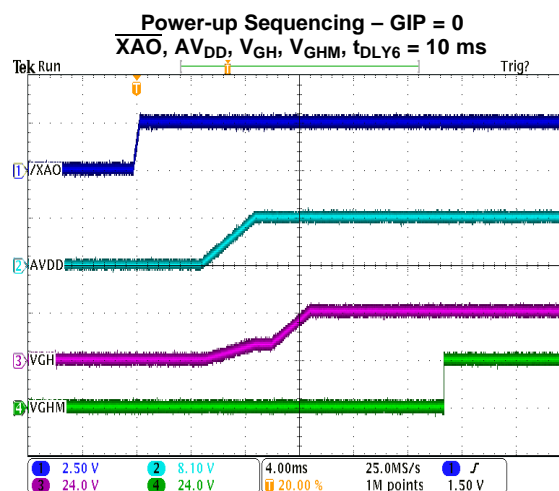


Figure 4-60.

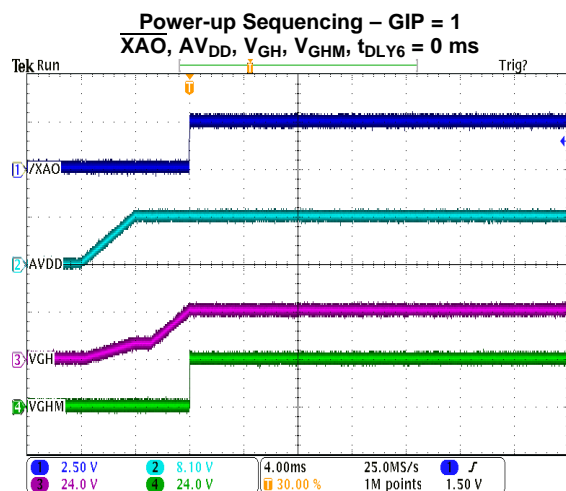


Figure 4-61.

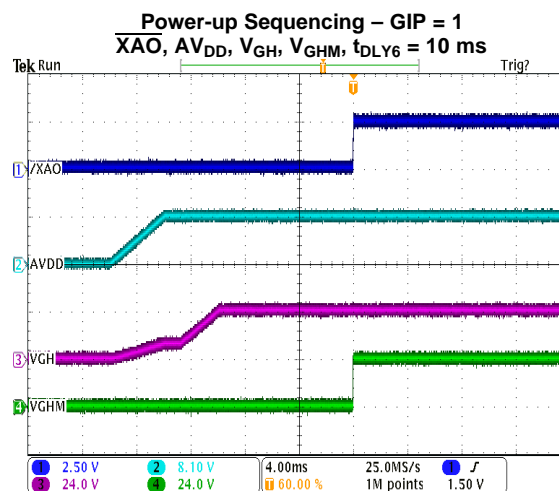


Figure 4-62.

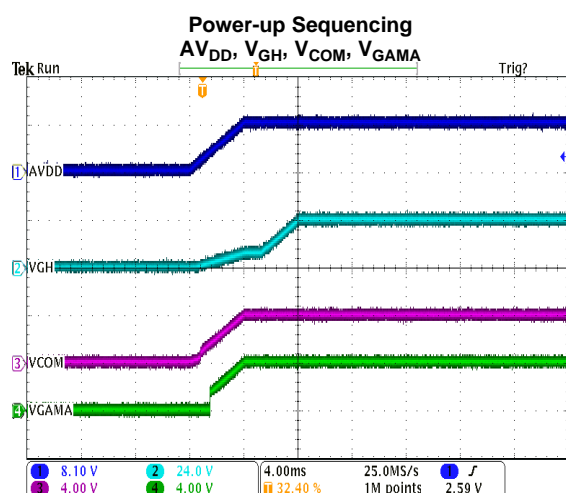


Figure 4-63.

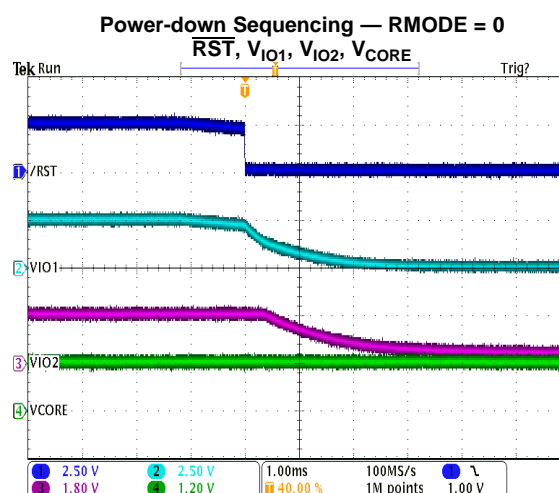


Figure 4-64.

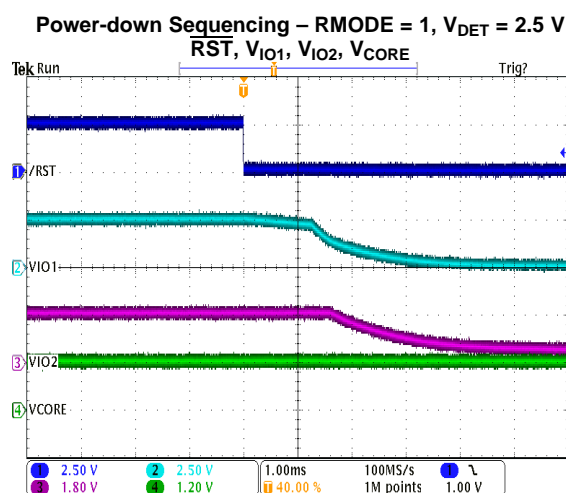


Figure 4-65.

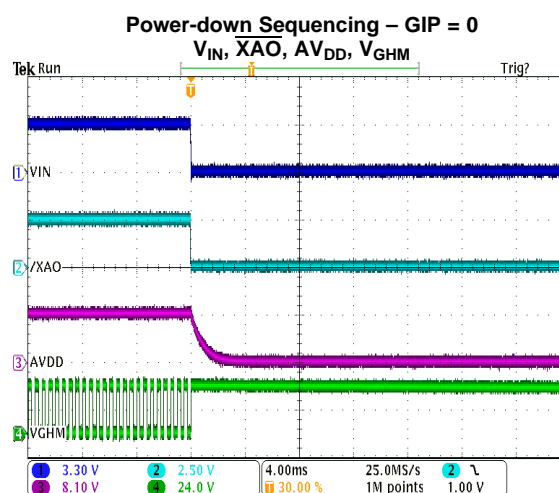


Figure 4-66.

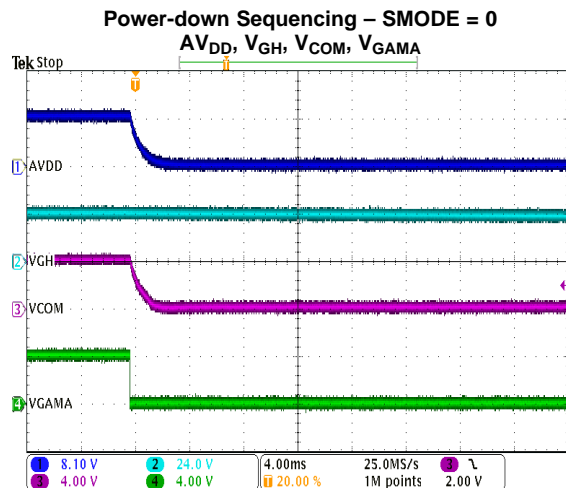


Figure 4-67.

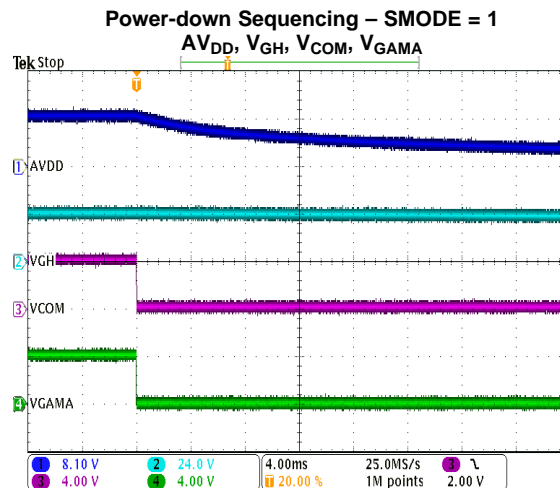


Figure 4-68.

**Gate Voltage Shaping — FLK, V<sub>GHM</sub>**  
AV<sub>DD</sub> = 8.1 V, R<sub>L</sub> = 33 Ω, V<sub>GH</sub> = 24 V, R<sub>L</sub> = 1.2 kΩ, R<sub>E</sub> = 1 kΩ, C<sub>L</sub> = 10 nF

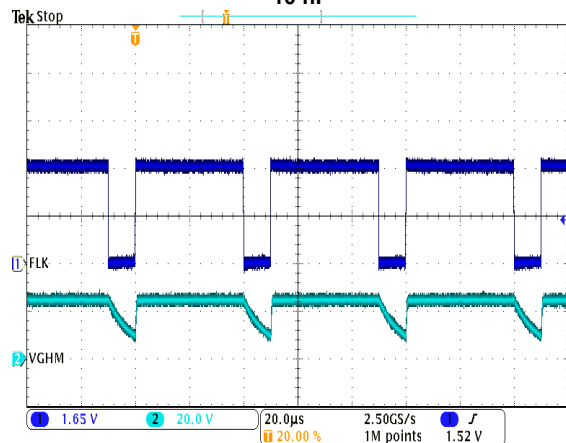


Figure 4-69.

**VCOM Buffer — Large Signal Response**  
AV<sub>DD</sub> = 7.6 V, R<sub>L</sub> = 82 Ω, V<sub>POS</sub> = 3.8 V + 0.5 V<sub>PP</sub>

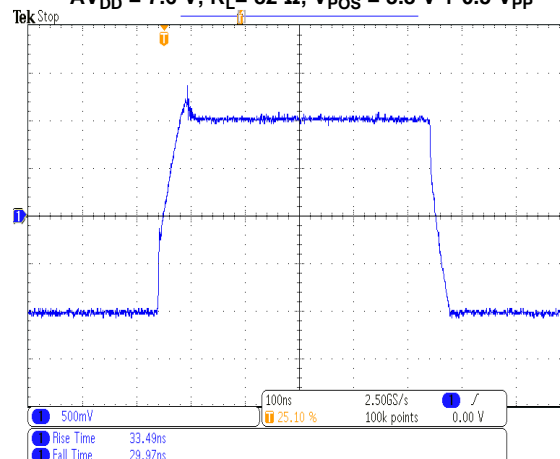


Figure 4-70.

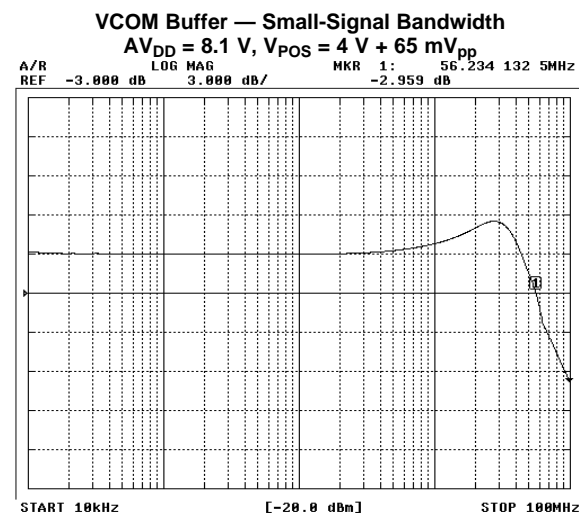


Figure 4-71.

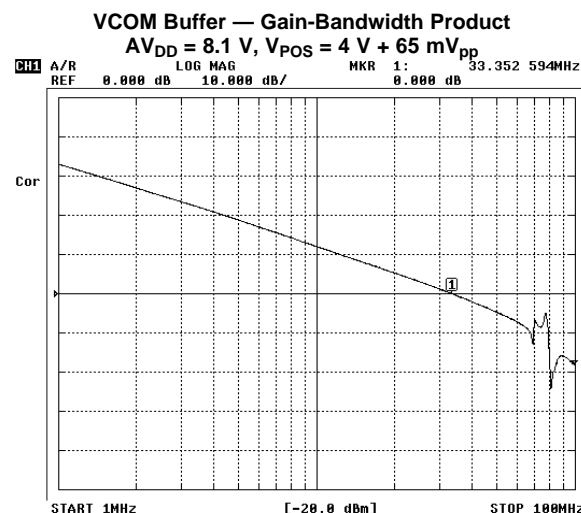


Figure 4-72.



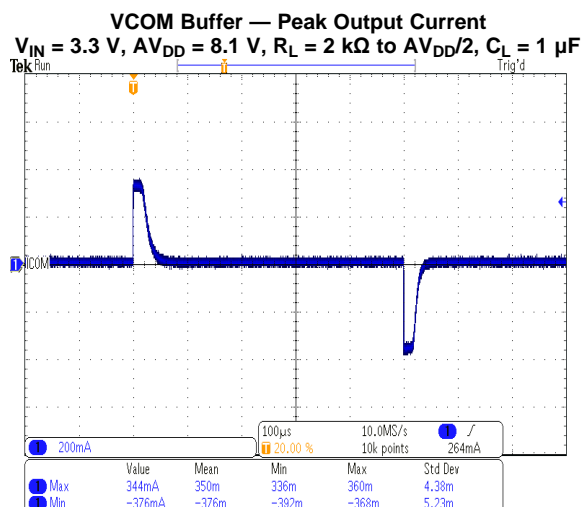


Figure 4-73.

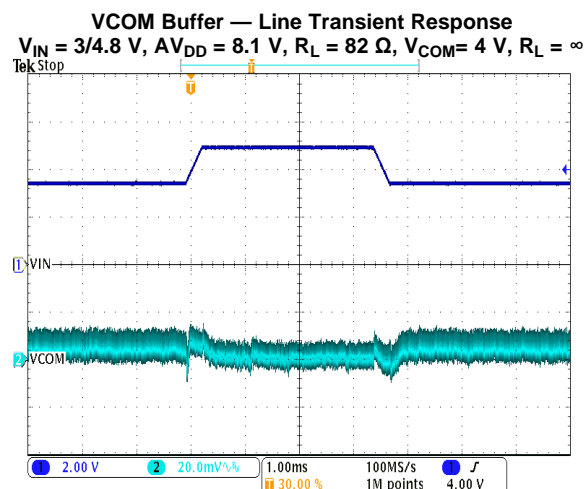


Figure 4-74.

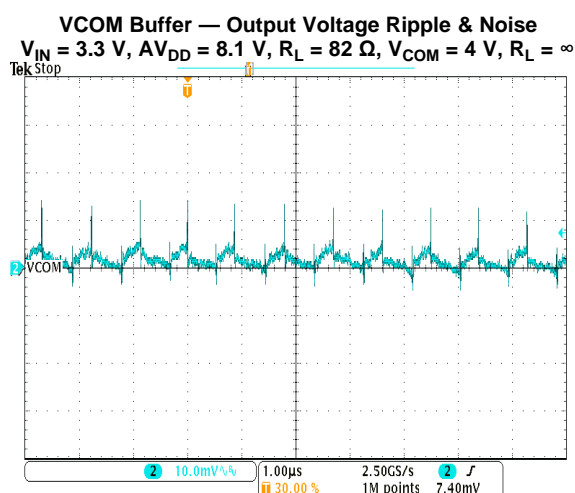


Figure 4-75.

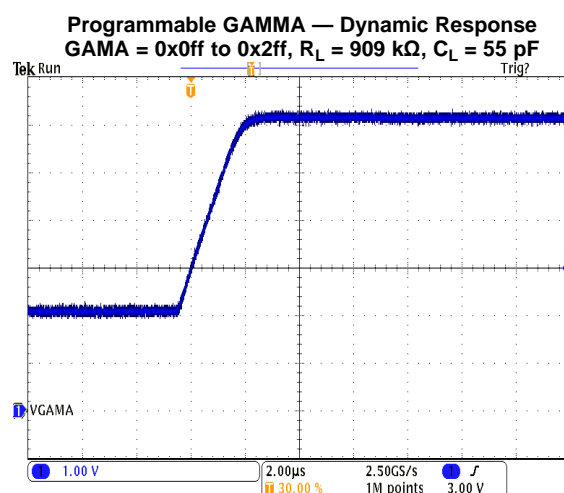


Figure 4-76.

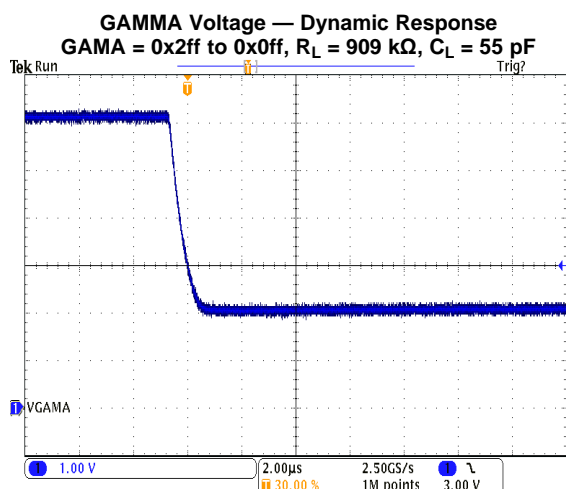


Figure 4-77.

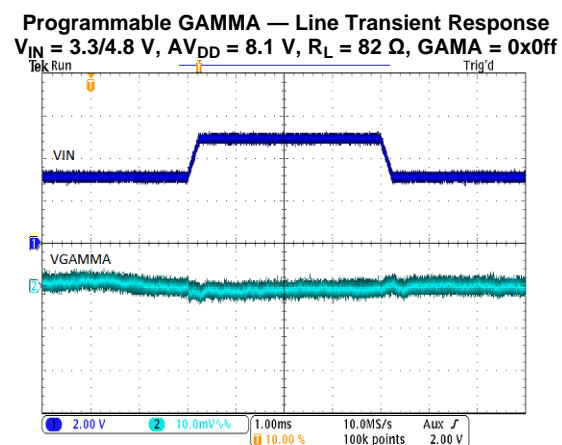
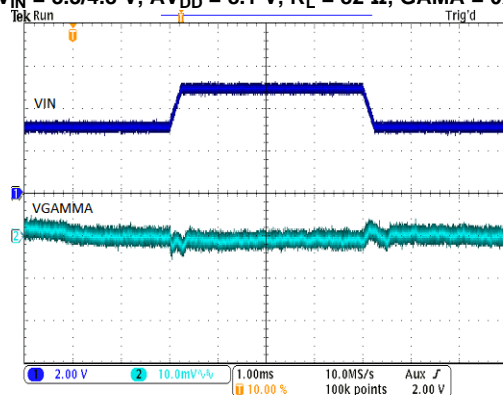


Figure 4-78.

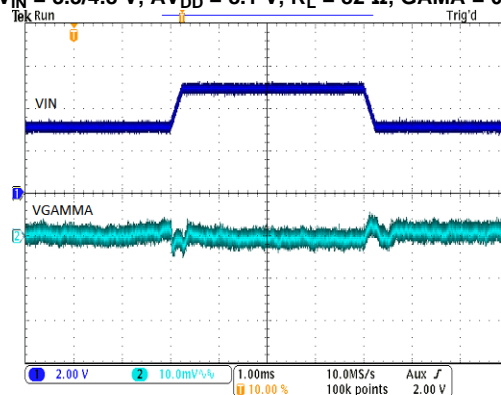


**Programmable GAMMA — Line Transient Response**  
 $V_{IN} = 3.3/4.8\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 82\ \Omega$ ,  $GAMA = 0x1ff$



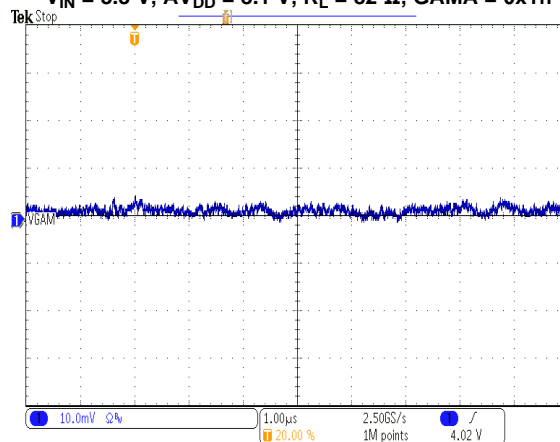
**Figure 4-79.**

**Programmable GAMMA — Line Transient Response**  
 $V_{IN} = 3.3/4.8\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 82\ \Omega$ ,  $GAMA = 0x2ff$



**Figure 4-80.**

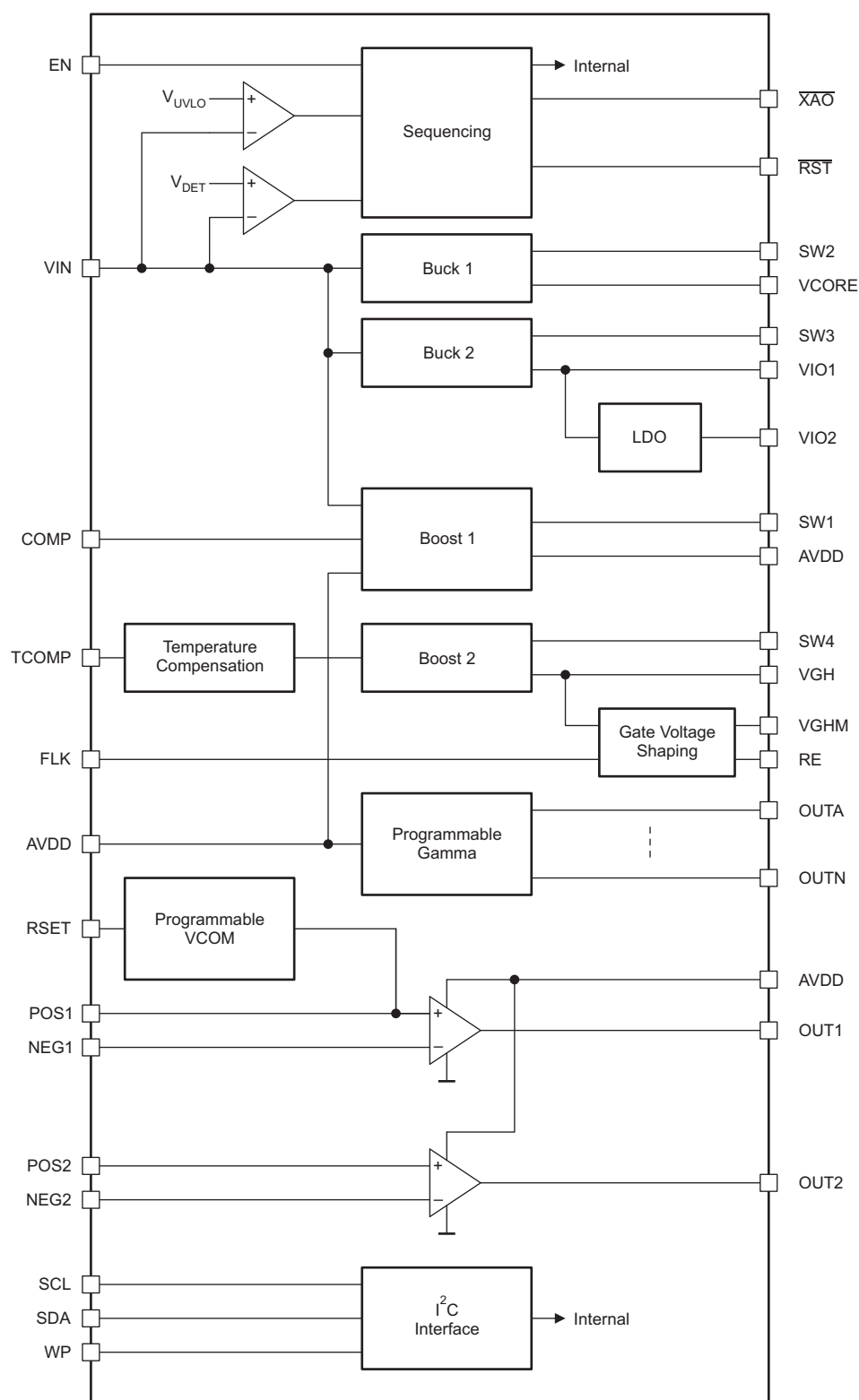
**Programmable GAMMA — Output Voltage Ripple & Noise**  
 $V_{IN} = 3.3\text{ V}$ ,  $AV_{DD} = 8.1\text{ V}$ ,  $R_L = 82\ \Omega$ ,  $GAMA = 0x1ff$



**Figure 4-81.**

## 5 Detailed Description

An internal block diagram of the TPS65642 is shown in [Figure 5-1](#).



**Figure 5-1. Internal Block Diagram**

## 5.1 BOOST CONVERTER 1 ( $AV_{DD}$ )

Boost converter 1 is synchronous and uses a virtual current mode topology that:

- achieves high efficiencies
- allows the converter to work in continuous conduction mode under all operating conditions, simplifying compensation
- provides a better drive signal for the negative charge pump connected to the switch node (because the converter always runs in continuous conduction mode, even at low output currents)
- provides true input-output isolation when the boost converter is disabled

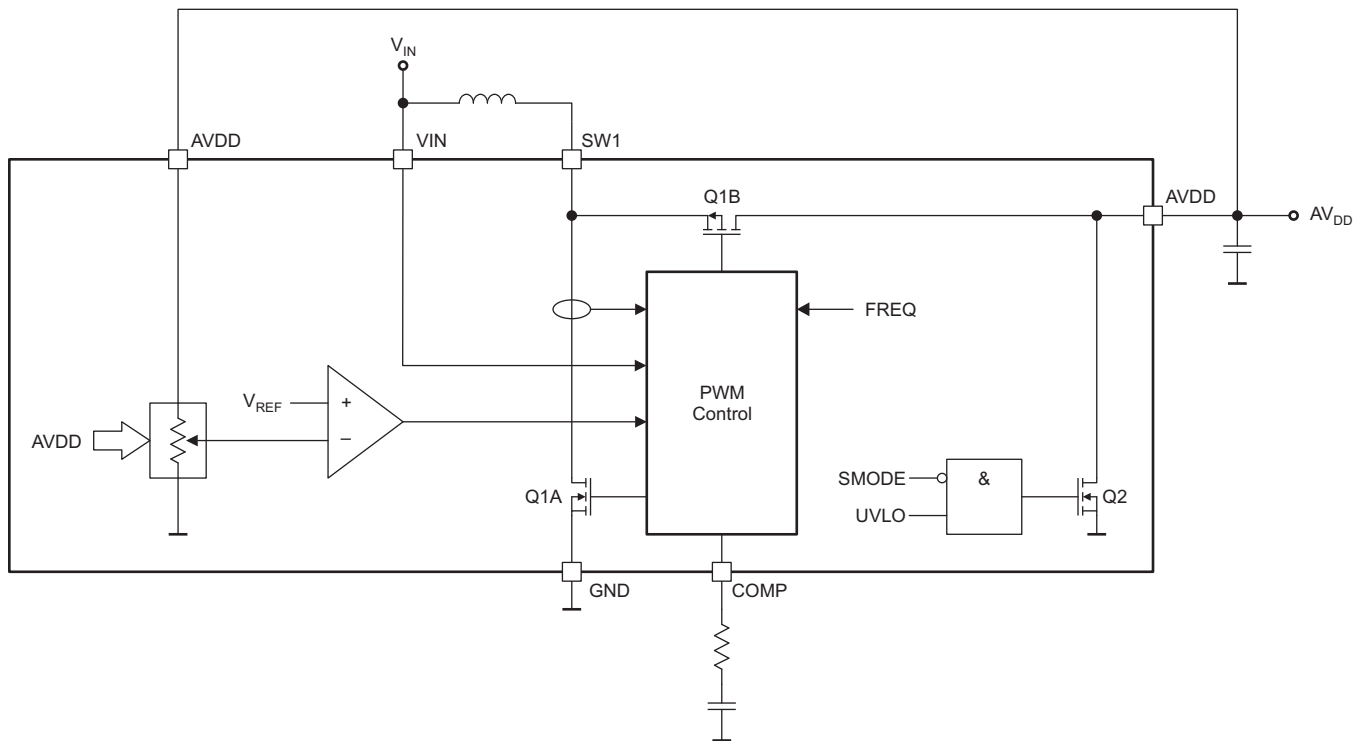


Figure 5-2. Boost Converter 1 Internal Block Diagram

### 5.1.1 Switching Frequency (Boost Converter 1)

Boost converter 1's nominal switching frequency can be programmed to 750 kHz or 1200 kHz using the FREQ bit in the MISC register.

### 5.1.2 Compensation (Boost Converter 1)

Boost converter 1 uses an external compensation network connected to the COMP pin to stabilize its feedback loop. A simple series R-C network connected between the COMP pin and ground is sufficient to achieve good performance, that is, stable and with good transient response. Good starting values, which will work for most applications, are 100 k $\Omega$  and 1 nF for 1200 MHz  $AV_{DD}$  switching frequency and 56 k $\Omega$  and 1.5 nF for 750 kHz  $AV_{DD}$  switching frequency.

In some applications (e.g. those using electrolytic output capacitors), it may be necessary to include a second compensation capacitor between the COMP pin and ground (typically 22 pF). This has the effect of adding an additional pole in the feedback loop's frequency response, which cancels the zero introduced by the output capacitor's ESR.

The COMP pin is directly connected to the input of the converter's current comparator, which means that any noise present on this pin can directly affect converter operation. In practical applications the most likely source of noise is the converter's switch pin, and for proper operation it is essential that the stray capacitance between the SW1 and the COMP pins is minimized. This can be ensured using good PCB layout practices, such as:

- locating the compensation components close to the COMP pin
- removing the GND plane from underneath the SW1 PCB tracks (to prevent this high dV/dt signal from inducing currents locally in the GND plane)
- connecting the ground side of the compensation components to a noise-free GND location, that is, away from noisy power ground signals

For the most robust operation, it is recommended to ensure that the parasitic capacitance between the SW1 and COMP is below 0.1 pF.

### 5.1.3 Power-Up (Boost Converter 1)

Boost converter 1 starts  $t_{DLY1}$  milliseconds after EN or  $\overline{RST}$  goes high, whichever occurs later. Delay time  $t_{DLY1}$  can be programmed from 0 ms to 70 ms using the DLY1 register. Once asserted, the EN signal must remain high to ensure normal device operation. Once disabled (EN = 0), boost converter 1 remains disabled until the device is powered down (even if EN is re-asserted).

To minimize inrush current during start-up, boost converter 1 ramps its output voltage in  $t_{SS2}$  milliseconds. Start-up time  $t_{SS2}$  can be programmed from 4 ms to 7.5 ms using the SS2 register. Longer soft-start times generate lower inrush currents.

The same ramp rate is also used for boost converter 2 – changing the SS2 register affects both boost converters.

The soft-start function is not implemented if boost converter 1's output voltage is re-programmed during operation. This is not a problem during normal operation (when  $AV_{DD}$  remains constant), however, it may cause problems during production if  $AV_{DD}$  is changed while the converter is enabled. Problems can occur under such conditions because, without a soft-start, the converter draws a high inrush current when its output voltage is changed. If the converter is supplied from a high-impedance source, this inrush current can, under certain circumstances, pull  $V_{IN}$  below the UVLO threshold, disabling the IC and interrupting the writing of the configuration parameters. One or more of the following recommendations can be used to ensure trouble-free configuration during production:

- program the configuration parameters before the IC is soldered to the PCB
- supply the PCB with a voltage high enough to ensure that the voltage on the VIN pin remains above the UVLO threshold when the value of  $AV_{DD}$  is changed
- ensure that the supply impedance is low enough to ensure that the voltage on the VIN pin remains above the UVLO threshold when the value of  $AV_{DD}$  is changed
- disable boost converter 1 while the value of  $AV_{DD}$  is changed

### 5.1.4 Power-Down (Boost Converter 1)

Boost converter 1 is disabled when EN=0 or  $V_{IN} < V_{UVLO}$ . When disabled, boost converter 2 actively discharges  $AV_{DD}$  by turning on Q2. The active discharge feature can be disabled by setting SMODE=1 in the CONFIG register. Once disabled (EN = 0), boost converter 1 remains disabled until the device is powered down (even if EN is re-asserted).

### 5.1.5 Isolation (Boost Converter 1)

The synchronous topology of boost converter 1 ensures that  $AV_{DD}$  is fully isolated from  $V_{IN}$  when the converter is disabled.

### 5.1.6 Output Voltage (Boost Converter 1)

Boost converter 1's output voltage can be programmed from 6.0 V to 9.1 V in 100 mV steps using the AVDD register.

### 5.1.7 Input Supply Characteristics

Boost converter 1 exhibits a fast response with excellent line transient performance. Its fast reaction to changes in input voltage means that excessive input impedance can cause the converter to become unstable. This can happen, for example, if  $V_{IN}$  is supplied via an excessively long cable, in which case the cable's parasitic inductance forms a resonant circuit with the IC's input capacitance. The following guidelines help avoid such problems and ensure proper operation:

- minimize supply cable inductance
- minimize supply cable resistance
- maximize input capacitance
- avoid using ceramic types for the bulk input capacitance - capacitors with higher ESR help to damp any tendency to ring on the part of the input cable

## 5.2 BUCK CONVERTER 1 ( $V_{CORE}$ )

Buck converter 1 is synchronous and uses a constant off-time topology that offers high efficiency, fast transient response, and constant ripple current amplitude under all operating conditions. The output voltage  $V_{CORE}$  can be programmed by the user. The converter's off-time is inversely proportional to its output voltage, and therefore constant when the converter is in regulation. Thus for a given  $V_{IN}$  the converter operates at a constant frequency that changes temporarily when the converter reacts to load changes.

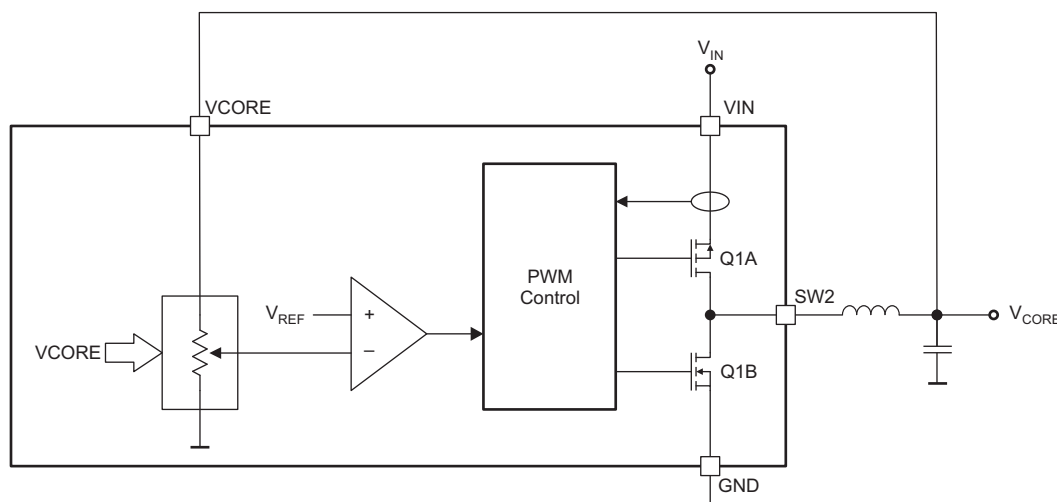


Figure 5-3. Buck Converter 1 Block Diagram

### 5.2.1 Output Voltage (Buck Converter 1)

Buck converter 1's output voltage can be programmed from 1 V to 1.3 V in 100 mV steps.

### 5.2.2 Power-Up (Buck Converter 1)

Buck converter 1 starts as soon as buck converter 2 and the LDO regulator have finished ramping up.

To minimize inrush current during start-up, buck converter 1 ramps  $V_{CORE}$  from zero to its final value in  $t_{SS1}$  milliseconds. Soft-start time  $t_{SS1}$  can be programmed from 0.5 ms to 4 ms using the SS1 register.

The same ramp rate is used for both buck converters and the linear regulator. Changing SS1 affects all three regulators.

### 5.2.3 Power-Down (Buck Converter 1)

Buck converter 1 is disabled when  $V_{IN} < V_{UVLO}$ . Its output is not actively discharged.

## 5.3 BUCK CONVERTER 2 ( $V_{IO1}$ )

Buck converter 2 is a low-power synchronous buck converter that in typical applications generates the I/O supply voltage for the timing controller and source drivers. It is essentially the same as buck converter 1, also the output voltage  $V_{IO1}$  can be programmed by the user but the output is actively discharged during power-down.

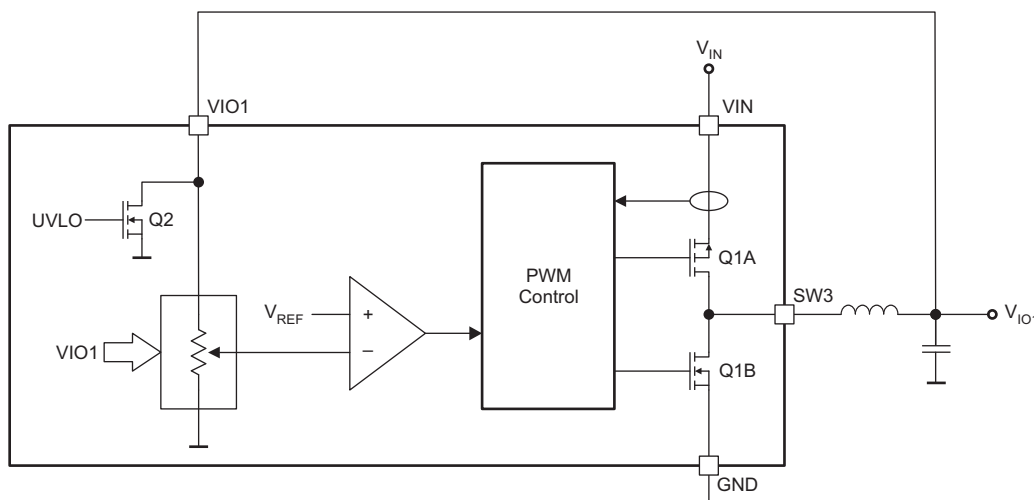


Figure 5-4. Buck Converter 2 Internal Block Diagram

### 5.3.1 Output Voltage (Buck Converter 2)

Buck converter 2's output voltage can be programmed to 1.7 V, 1.8 V, or 2.5 V using the VIO register. When  $V_{IO1} = 1.7$  V or 1.8 V, the LDO regulator is disabled.

### 5.3.2 Power-Up (Buck Converter 2)

Buck converter 2 starts as soon as  $V_{IN} > V_{UVLO}$  (the same time the LDO regulator starts), and implements the same voltage ramping as buck converter 1.

### 5.3.3 Power-Down (Buck Converter 2)

Buck converter 2 is disabled and actively discharges its output when  $V_{IN} < V_{UVLO}$ .

## 5.4 LDO REGULATOR ( $V_{IO2}$ )

In applications in which the timing controller and source drivers use different I/O voltages, the LDO regulator can be used to generate the lower I/O supply voltage  $V_{IO2}$ . The LDO regulator is supplied from the VIO1 pin, which is the output of buck converter 2.

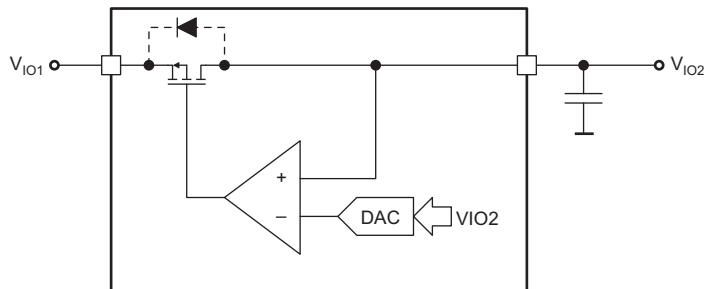


Figure 5-5. Linear Regulator Block Diagram

#### 5.4.1 Output Voltage (LDO Regulator)

When  $V_{IO1} = 2.5\text{ V}$ , the LDO regulator's output voltage can be programmed to 1.7 V or 1.8 V using the VIO register. To ensure reliable LDO programming, EN has to be "high" and the power-up sequence must be over ( $t_{DLV6}$ ). When  $V_{IO1} = 1.7\text{ V}$  or 1.8 V, the LDO regulator is disabled.

#### 5.4.2 Power-Up (LDO Regulator)

At power up, the LDO regulator starts as soon as  $V_{IN} > V_{UVLO}$  (the same time buck converter 1 and buck converter 2 starts). It ramps its output linearly from zero to  $V_{IO2}$  in  $t_{SS1}$  milliseconds. Soft-start time  $t_{SS1}$  can be programmed from 0.5 ms to 4 ms using the SS1 register.

The same ramp rate is used for both buck converters and the LDO regulator. Changing the SS1 register affects all three regulators.

When the LDO is turned on/off during normal device operation (that is, programming  $V_{IO1}$  from 1.7V to 2.5V or vice versa), the ramp or discharge characteristic is defined by the load connected.

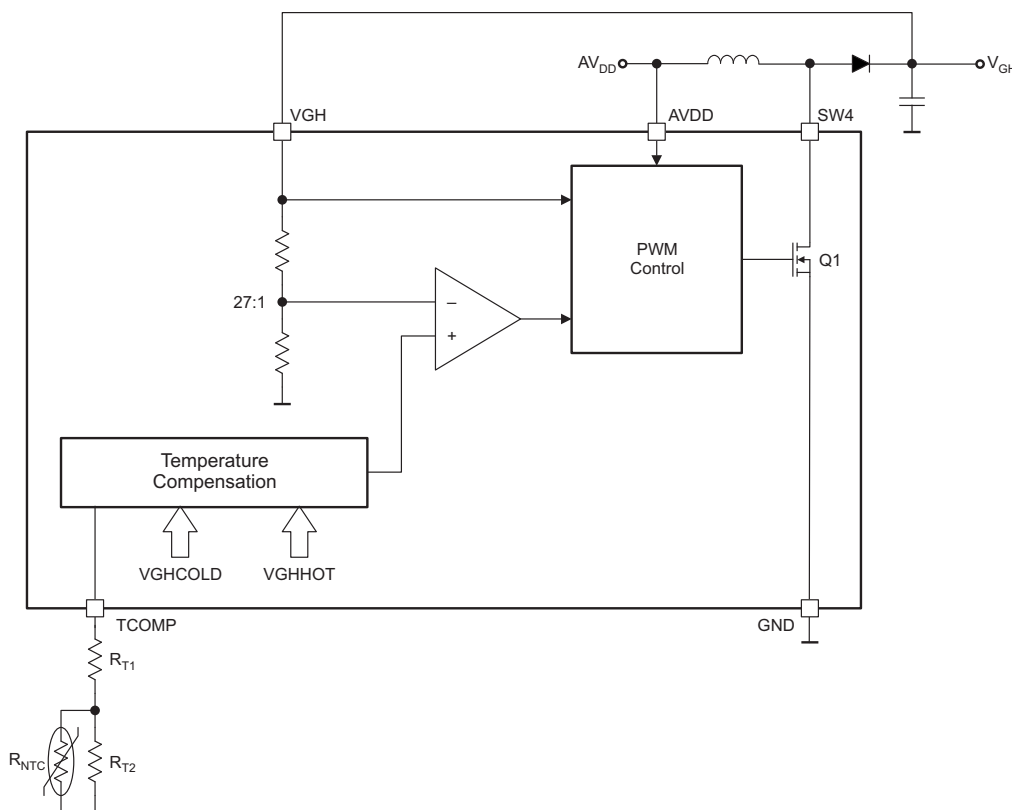
#### 5.4.3 Power-Down (LDO Regulator)

The LDO regulator is supplied from the VIO1 pin, which is actively discharged during power-down. The LDO regulator's output therefore discharges through transistor Q1's body diode as long as VIO2 is high enough to forward bias it. Thereafter,  $V_{IO2}$  continues to discharge through the load connected to it.

### 5.5 BOOST CONVERTER 2 ( $V_{GH}$ )

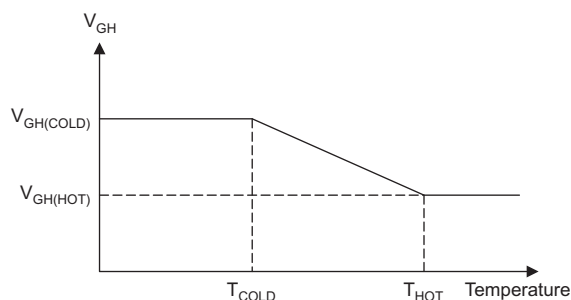
Boost converter 2 is non-synchronous, and uses a constant off-time topology. The converter's switching frequency is not constant, but adapts itself to  $V_{IN}$  and  $V_{GH}$ . Boost converter 2 uses peak current control and is designed to operate permanently in discontinuous conduction mode (DCM), thereby allowing the internal compensation circuit to achieve stable operation over a wide range of output voltages and currents, that is, when temperature compensation is used.

A simplified block diagram of boost converter 2 is shown in [Figure 5-6](#).



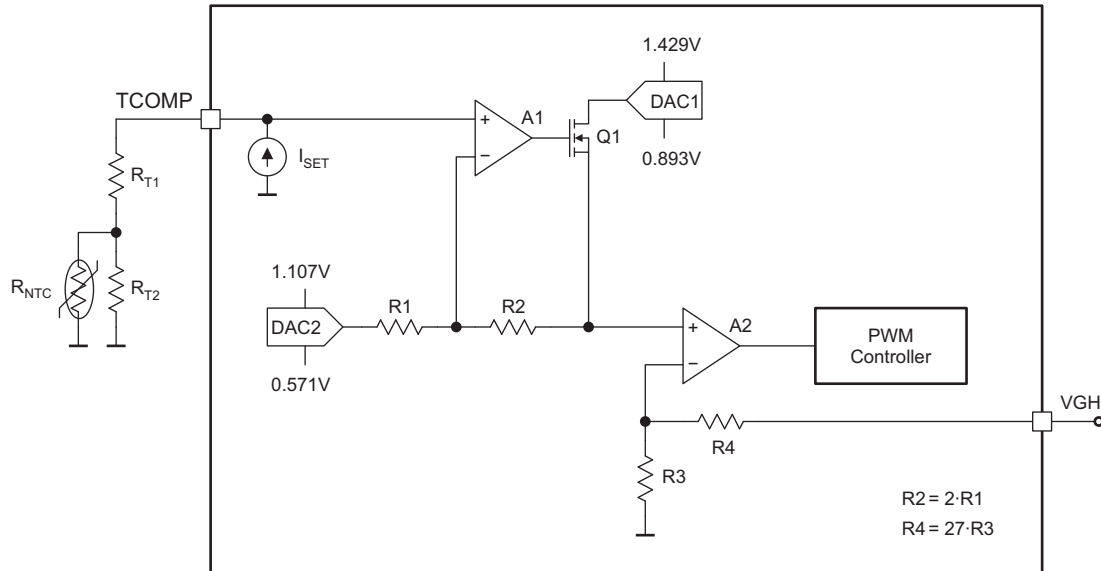
**Figure 5-6. Boost Converter 2 Block Diagram**

Boost converter 2 can be temperature compensated, allowing its output voltage to transition from a higher voltage at low temperatures  $V_{GH(COLD)}$  to a lower voltage at high temperatures  $V_{GH(HOT)}$  (see [Figure 5-7](#) and [Figure 5-8](#)). The values of  $V_{GH(HOT)}$  and  $V_{GH(COLD)}$  are programmed using the V\_GHHOT and V\_GHCOLD registers. The values of  $T_{HOT}$  and  $T_{COLD}$  are programmed by selecting the appropriate resistor values for the thermistor network connected to the TCAMP pin.



**Figure 5-7. Boost Converter 2 Temperature Compensation Characteristic**





**Figure 5-8. Boost Converter 2 Temperature Compensation Block Diagram**

Referring to [Figure 5-8](#), temperature compensation works as follows:

The thermistor network formed by  $R_{T1}$ ,  $R_{T2}$  and  $R_{NTC}$  <sup>(1)</sup> generates a voltage at the TCOMP pin whose value decreases with increasing temperature.

With proper selection of the external components  $R_{T1}$ ,  $R_{T2}$  and  $R_{NTC}$ , temperatures  $T_{HOT}$  and  $T_{COLD}$  can be configured to suit each display's characteristics. A Microsoft Excel® spreadsheet allowing easy calculation of component values is available from Texas Instruments free of charge.

### 5.5.1 Power-Up (Boost Converter 2)

Boost converter 2 is enabled when  $AV_{DD}$  has finished ramping up. To minimize inrush current during start-up, boost converter 2 ramps  $V_{GH}$  linearly to its programmed value in  $t_{SS2}$  seconds. Soft-start time  $t_{SS2}$  can be programmed from 4 ms to 7.5 ms using the SS2 register. The same ramp rate is also used for boost converter 1. Changing SS2 affects both boost converters.

### 5.5.2 Power-Down (Boost Converter 2)

Boost converter 2 is disabled when  $EN = 0$  or  $V_{IN} < V_{UVLO}$ . The converter's output is not actively discharged when the converter is disabled. Once disabled ( $EN = 0$ ), boost converter 1 remains disabled until the device is powered down (even if  $EN$  is re-asserted).

### 5.5.3 Setting the Output Voltage (Boost Converter 2)

The output voltage of boost converter 2 at cold temperatures can be programmed from 25 V to 40 V <sup>(2)</sup> using the VGHCOLD register. The output voltage of boost converter 2 at hot temperatures can be programmed from 16 V to 31 V using the VGHHOT register.

Note that if the VGHCOLD register is programmed with a lower voltage than the VGHHOT register, the output voltage  $V_{GH}$  will be regulated at  $V_{GH(HOT)}$ , regardless of the temperature.

In applications that do not require temperature compensation, the TCOMP pin should be tied to ground and the VGHHOT register used to set the voltage of  $V_{GH}$ .

From [Figure 5-8](#), it can be seen that, between  $V_{GH(HOT)}$  and  $V_{GH(COLD)}$ , boost converter 2's output voltage is given by

$$V_{GH} = 28 \times (V_{DAC2} + 3 \times (V_{TCOMP} - V_{DAC2})) \quad (1)$$

(1)  $R_T$  should be a negative temperature coefficient (NTC) type whose resistance at 25°C is 10 kΩ.

(2) Output voltages greater than 36 V require an external cascode transistor.

Equation 1 can be used to calculate the voltage required on the TCOMP pin at temperatures  $T_{HOT}$  and  $T_{COLD}$ .

$$V_{TCOMPHOT} = \frac{V_{GHHOT}}{28} \quad (2)$$

$$V_{TCOMPCOLD} = \frac{2 \times V_{GHHOT} + V_{GHCOLD}}{84} \quad (3)$$

Equation 4 can be used to calculate the appropriate value for  $R_{T2}$

$$R_{T2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \quad (4)$$

Where

$$a = R_{NTCCOLD} - R_{NTCHOT} - \frac{V_{TCOMPCOLD} - V_{TCOMPHOT}}{I_{SET}} \quad (5)$$

$$b = (R_{NTCCOLD} + R_{NTCHOT}) \times \left( \frac{V_{TCOMPCOLD} - V_{TCOMPHOT}}{I_{SET}} \right) \quad (6)$$

$$c = (R_{NTCCOLD} \times R_{NTCHOT}) \times \left( \frac{V_{TCOMPCOLD} - V_{TCOMPHOT}}{I_{SET}} \right) \quad (7)$$

and  $R_{NTCCOLD}$  and  $R_{NTCHOT}$  are the resistances of the thermistor at temperatures  $T_{COLD}$  and  $T_{HOT}$  respectively.

Once the value of  $R_{T2}$  has been calculated, Equation 8 can be used to calculate the appropriate value of  $R_{T1}$ .

$$R_{RT1} = \times \left( \frac{V_{TCOMPCOLD}}{I_{SET}} \right) - \left( \frac{R_{NTCCOLD} \times R_{T2}}{R_{NTCCOLD} + R_{T2}} \right) \quad (8)$$

#### 5.5.4 Protection ( $AV_{DD}$ , $V_{CORE}$ , $V_{IO1}$ , $V_{IO2}$ , $V_{GH}$ )

Each voltage regulator is protected against short-circuits and undervoltage conditions. An undervoltage condition is detected if a regulator output falls below 70% of its programmed voltage for longer than 50 ms, in which case the IC is disabled. To recover normal operation following an undervoltage condition, the cause of the error condition must be removed and the supply voltage  $V_{IN}$  cycled. A short-circuit condition is detected if a regulator output falls below 30% of its programmed voltage, in which case the IC is disabled immediately. To recover normal operation following a short-circuit condition, the cause of the error must be removed and the supply voltage  $V_{IN}$  cycled.

## 5.6 RESET GENERATOR

The  $\overline{RST}$  pin generates an active-low reset signal for the timing controller. During power-up, the reset timer starts when  $V_{CORE}$  has finished ramping. The reset pulse duration  $t_{RESET}$  can be programmed from 2 ms to 16 ms using the RESET register. The  $\overline{RST}$  signal is latched when it goes high and will not be taken low again until the device is powered down (even if  $V_{CORE}$  temporarily falls out of regulation). The active power-down threshold ( $V_{UVLO}$  or  $V_{DET}$ ) can be selected using the RMODE bit in the CONFIG register.

The  $\overline{RST}$  output is an open-drain type that requires an external pull-up resistor. Pull-up resistor values in the range 10 k $\Omega$  to 100 k $\Omega$  are recommended for most applications.

## 5.7 GATE VOLTAGE SHAPING

The gate voltage shaping function can be used to reduce image sticking in LCD panels by modulating the LCD panel's gate ON voltage ( $V_{GH}$ ). Figure 5-9 shows a block diagram of the gate voltage shaping function and Figure 5-10 shows the typical waveforms during operation.

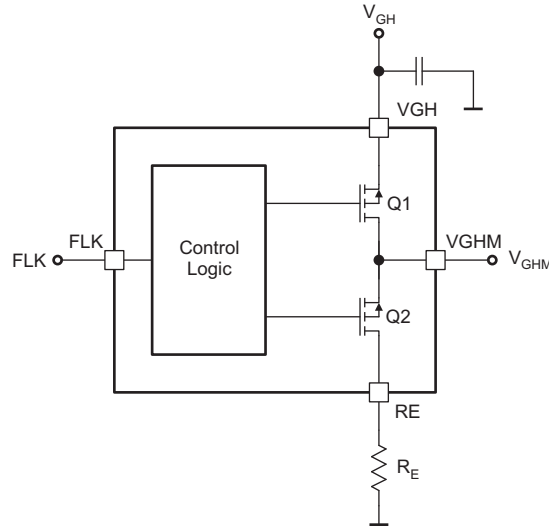


Figure 5-9. Gate Voltage Shaping Block Diagram

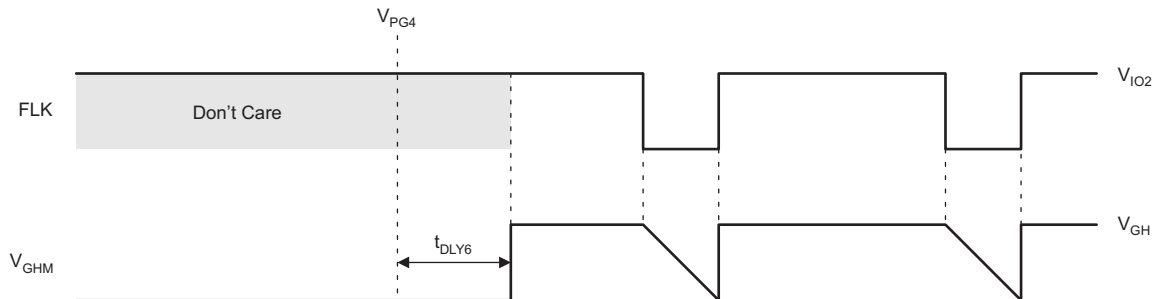


Figure 5-10. Gate Voltage Shaping Waveforms

Gate voltage shaping is controlled by the FLK input. When FLK is high, Q1 is on, Q2 is off, and  $V_{GHM}$  is equal to  $V_{GH}$ . On the falling edge of FLK, Q1 is turned off, Q2 is turned on, and the LCD panel load connected to the VGHM pin discharges through the external resistor connected to the RE pin.

During power-up Q2 is held permanently on and Q1 permanently off, regardless of the state of the FLK signal, until  $t_{DLY6}$  milliseconds after boost converter 2 ( $V_{GH}$ ) has finished ramping. The value of  $t_{DLY6}$  can be programmed from 0ms to 35ms using the DLY6 register.

During power-down Q1 is held permanently on and Q2 permanently off, regardless of the state of the FLK signal.

### 5.7.1 Recommended Connection when Gate Voltage Shaping not Used

Non-GIP/Non-ASG panels that do not use the gate voltage shaping function should leave the RE pin floating and connect the FLK pin to either  $V_{IN}$  or GND.

## 5.8 PANEL RESET / LCD BIAS READY ( $\overline{XAO}$ )

The TPS65642 provides an output signal via its  $\overline{XAO}$  pin that can be used to reset a level shifter or gate driver IC during power-up and power-down. The GIP bit in the CONFIG register defines whether the  $\overline{XAO}$  pin works in GIP mode or non-GIP mode.

The primary purpose of the  $\overline{XAO}$  signal in non-GIP applications is to drive the outputs of the display panel's gate driver IC high during power-down by generating an active-low signal. When the GIP = 0, the  $\overline{XAO}$  pin is pulled low whenever  $V_{IN} < V_{DET}$ . The  $V_{DET}$  threshold voltage can be configured using the VDET register.

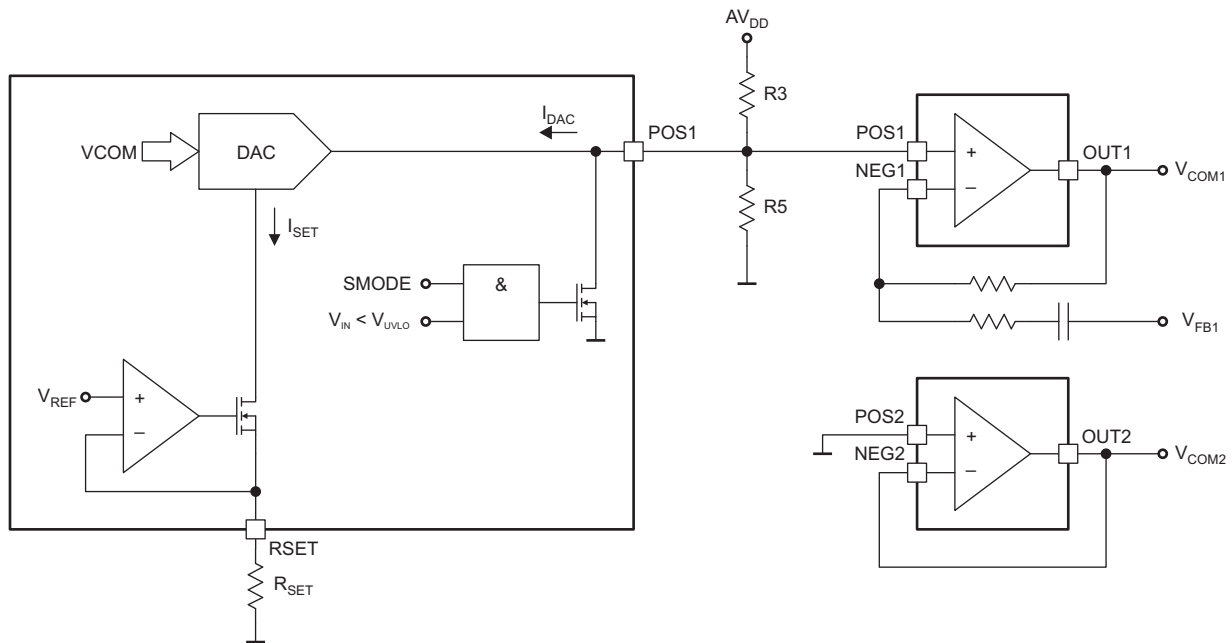
When the  $GIP = 1$ , the  $\overline{XAO}$  output is used to delay the start of level shifter activity during power-up. The delay time  $t_{DLY6}$  starts when  $V_{GH}$  has finished ramping up, and can be configured using the DLY6 register.

The  $\overline{XAO}$  output is an open-drain type and requires an external pull-up, typically in the range 10 k $\Omega$  to 100 k $\Omega$ .

## 5.9 PROGRAMMABLE VCOM CALIBRATOR ( $V_{COM}$ )

The programmable VCOM calibrator uses a digital-to-analog converter (DAC) to generate an offset current  $I_{DAC}$  for an external resistor divider connected to  $AV_{DD}$  (see Figure 5-11 and Figure 5-12). Higher values of the 7-bit digital word N written to the DAC generate higher  $I_{DAC}$  sink currents, and therefore lower  $V_{COM}$  voltages.

Figure 5-11 shows the recommended circuit for the most commonly used application, when the LCD panel requires only one  $V_{COM}$  supply voltage. The second op-amp is shown wired as a unity-gain buffer whose input is tied to GND (the recommended configuration if it is not used), however, it is perfectly acceptable to use it for other things, such as generating a half- $AV_{DD}$  supply rail.



**Figure 5-11. Single Programmable  $V_{COM}$  Supply**

The external resistor  $R_{SET}$  generates a reference current  $I_{SET}$  for the DAC. Since this reference current is also used by boost converter 2's temperature compensation function, care should be taken to ensure that a suitable value is chosen. For most applications, a value of 24.9 k $\Omega$  is recommended, which generates a reference current given by

$$I_{SET} = \frac{V_{REF}}{R_{SET}}$$

$$I_{SET} = \frac{1.25\text{ V}}{24.9\text{ k}\Omega} = 50.2\mu\text{A} \quad (9)$$

The output current  $I_{DAC}$  sunk by the DAC is given by:

$$I_{DAC} = \frac{(N+1) \times I_{SET}}{128} \quad (10)$$

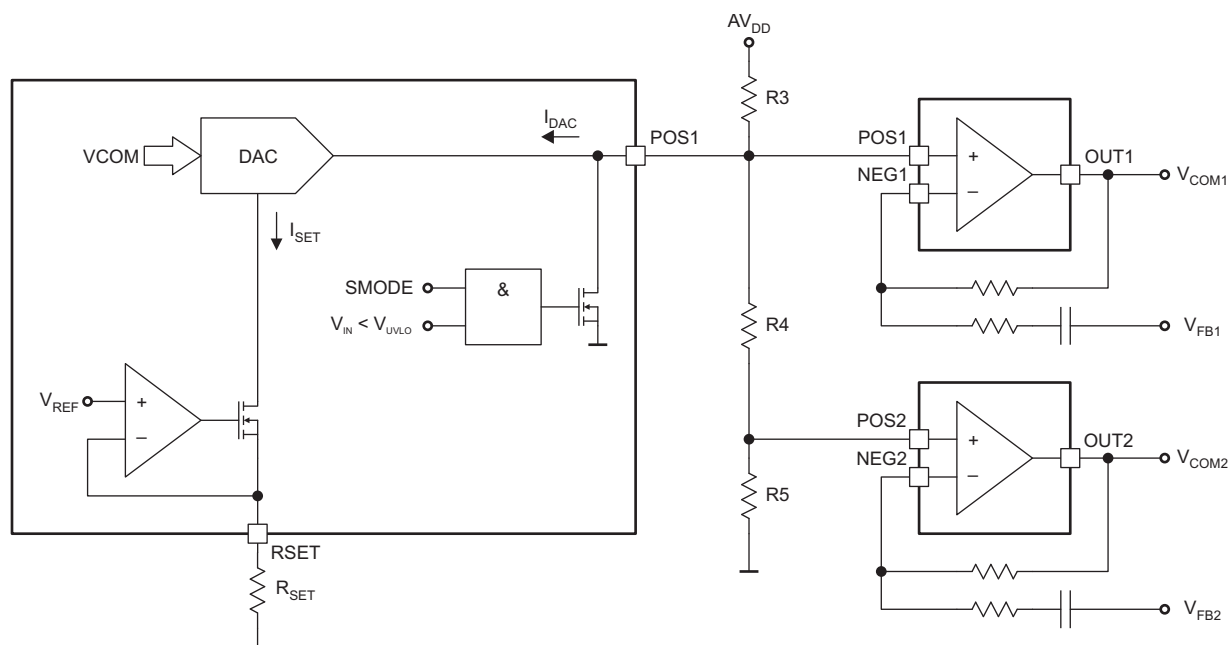
where N is the 7-bit word written to the DAC, and ranges from 0 to 127.

Equation 11 and Equation 12 can be used to select appropriate values for R3 and R5.

$$R3 = \frac{128 \times \Delta V_{COM} \times A V_{DD}}{I_{SET} \times (127 \times V_{COM(MAX)} + \Delta V_{COM})} \quad (11)$$

$$R5 = \frac{128 \times \Delta V_{COM} \times R3}{(127 \times I_{SET} \times R3) - (128 \times \Delta V_{COM})} \quad (12)$$

Figure 5-12 shows the recommended connection for the case when two  $V_{COM}$  supplies  $V_{COM1}$  and  $V_{COM2}$  are to be generated.



### Figure 5-12. Dual Programmable $V_{COM}$ Supplies

In [Figure 5-12](#), the voltage  $V_{COM2}$  generated by the second op-amp is slightly lower than  $V_{COM1}$ . If two identical  $V_{COM}$  supplies are required, these can be generated by setting  $R4=0$ .

Equation 13 through Equation 15 can be used to calculate the correct values for R3 through R5 for the case when two (slightly different)  $V_{COM}$  voltages are required:

$$R3 = \frac{128 \times \Delta V_{COM} \times AV_{DD}}{I_{SET} \times (127 \times V_{COM1(MAX)} + \Delta V_{COM})} \quad (13)$$

$$R4 = \left( \frac{V_{COM2(MAX)}}{V_{COM1(MAX)}} \right) \times \left( \frac{128 \times \Delta V_{COM} \times R3}{(127 \times I_{SET} \times R3) - (128 \times \Delta V_{COM})} \right) \quad (14)$$

$$R5 = \left( \frac{V_{COM1(MAX)} - V_{COM2(MAX)}}{V_{COM1(MAX)}} \right) \times \left( \frac{128 \times \Delta V_{COM} \times R3}{(127 \times I_{SET} \times R3) - (128 \times \Delta V_{COM})} \right) \quad (15)$$

A Microsoft Excel® spreadsheet is available free of charge that calculates the values of R3, R4 and R5 – contact your local sales representative for a copy.

### 5.9.1 Operational Amplifier Performance

Like most op amps, the  $V_{COM}$  op amps are not designed to drive purely capacitive loads, so it is not recommended to connect a capacitor directly to their outputs in an attempt to increase performance; however, the amplifiers are capable of delivering high peak currents that make such capacitors unnecessary.

High-speed op amps such as those in the TPS65642 require care when using them. The most common problem is when parasitic capacitance at the inverting input creates a pole with the feedback resistor, reducing amplifier stability. Two things can be done to minimize the likelihood of this happening. Both of these work by shifting the pole (which can never be completely eliminated) to a frequency outside the op amp's bandwidth, where it has no effect.

- Reduce the value of the feedback resistor. In applications where no feedback from the panel is used, the feedback resistor can be made zero. In applications where a non-zero feedback resistor has to be used, a small capacitor (10pF–100pF) across the feedback resistor will minimize ringing.
- Minimize the parasitic capacitance at the op amp's inverting input. This is achieved by using short PCB traces between the feedback resistor and the inverting input, and by removing ground planes and other copper areas above and below this PCB trace.

### 5.9.2 Power-Up (Programmable VCOM)

The programmable  $V_{COM}$  is enabled when  $AV_{DD} > \approx 3\text{ V}$ .

### 5.9.3 Power-Down (Programmable VCOM)

The programmable  $V_{COM}$  supports two kinds of power-down behavior, and the SMODE bit in the CONFIG register determines which one is active (see [Figure 5-41](#) and [Figure 5-42](#)).

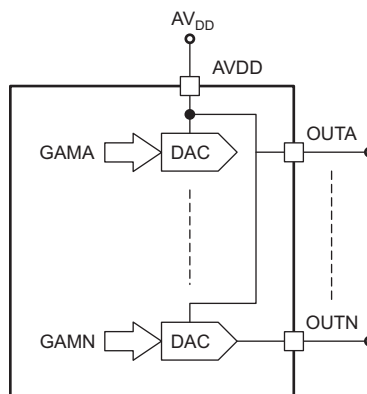
If  $SMODE = 0$ , the active discharge transistor Q1 is permanently disabled; during power-down,  $V_{COM}$  tracks  $AV_{DD}$  until it is too low to support operation. If  $SMODE = 1$ , Q1 turns on when  $V_{IN} < V_{UVLO}$ , actively pulling  $V_{COM}$  low.

## 5.10 PROGRAMMABLE GAMMA VOLTAGE GENERATOR

The gamma voltage correction supplies fourteen reference voltages that can be used by the system's source driver IC to match the LCD panel's luminance characteristics more closely to the response of the human eye.

The gamma correction voltages can be programmed individually using the I<sup>2</sup>C interface. During power-up, the default gamma voltage for each channel is loaded from EEPROM into the corresponding DAC.

During operation, the DACs' output voltages can be changed by programming new values via the I<sup>2</sup>C interface. Values programmed to the DACs but not transferred to EEPROM will be lost when power is removed from the device – the next time the device is powered up, the DACs will be programmed with whatever values are stored in the EEPROM. The current DAC settings can be transferred to EEPROM (thereby becoming the new default values used during power-up) at any time by sending the appropriate command to the Control Register via the I<sup>2</sup>C interface.



**Figure 5-13. Gamma Correction Block Diagram**

The output stages of the gamma correction block are capable of extending close to the supply rails ( $AV_{DD}$  and ground); however, they can only achieve this rail-to-rail performance with the specified accuracy if the outputs are lightly loaded. The gamma reference outputs are only intended to drive high impedance loads such as those presented by a gamma buffer or a high impedance source driver input.

The output voltage  $V_{GAM}$  of each channel is given by:

$$V_{GAM} = \frac{N}{1024} \cdot AV_{DD} \quad (16)$$

Where N is the 10-bit digital word programmed to the gamma register and ranges from 0 to 1023.

Any non-used output can be left open and should, to save power, be programmed to their maximum voltage (~ 180  $\mu$ A saving per output).

## 5.11 Configuration

The TPS65642 divides the configuration parameters into two categories:

- $V_{COM}$
- all other configuration parameters

In typical applications, all configuration parameters except  $V_{COM}$  are programmed by the subcontractor during PCB assembly, and  $V_{COM}$  is programmed by the display manufacturer during display calibration.

### 5.11.1 RAM, EEPROM, and Write Protect

Configuration parameters can be changed by writing the desired values to the appropriate RAM register(s). The RAM registers are volatile and their contents are lost when power is removed from the device. By writing to the Control Register, it is possible to store the active configuration in non-volatile EEPROM; during power-up, the contents of the EEPROM are copied into the RAM registers and used to configure the device.

An active high Write Protect (WP) pin prevents the configuration parameters from being changed by accident. This pin is internally pulled high and must be actively pulled low to access to the EEPROM or RAM registers. Note that the WP pin disables all I<sup>2</sup>C traffic to/from the TPS65642, and must also be pulled low during read operations. This is to ensure that noise present on the I<sup>2</sup>C lines does not erroneously overwrite the active configuration stored in RAM (which would not be protected by a simple EEPROM write-protect scheme).

### 5.11.2 Configuration Parameters (Excluding VCOM)

Table 5 shows the memory map of the configuration parameters.

**Table 5-1. Configuration Memory Map**

REGISTER ADDRESS	REGISTER NAME	FACTORY DEFAULT	DESCRIPTION
00h	CONFIG	00h	Sets miscellaneous configuration bits
01h	AVDD	10h	Sets the output voltage of boost converter 1
02h	VGHHOT	00h	Sets the output voltage of boost converter 2 at high temperatures
03h	VGHCOLD	00h	Sets the output voltage of boost converter 2 at low temperatures
04h	VIO	00h	Sets the output voltage of buck converter 2 and the LDO regulator
05h	MISC	05h	Sets the output voltage of buck converter 1 ( $V_{CORE}$ ) and the switching frequency of boost converter 1 ( $AV_{DD}$ )
06h	SS1	03h	Sets the soft-start time for buck converters 1 and 2 and the linear regulator
07h	SS2	00h	Sets the soft-start time for boost converters 1 and 2
08h	RESET	01h	Sets the reset pulse duration
09h	DLY1	02h	Sets the boost converter 1 start-up delay

**Table 5-1. Configuration Memory Map (continued)**

REGISTER ADDRESS	REGISTER NAME	FACTORY DEFAULT	DESCRIPTION
0Ah	DLY6	04h	Sets the gate voltage shaping / LCD ready start-up delay
0Bh	VDET	00h	Sets the threshold of the /RST and /XAO signals
0Ch	GAMMA-A	02h	Contains the 2 MSBs of the 10-bit gamma voltage A
0Dh		00h	Contains the 8 LSBs of the 10-bit gamma voltage A
0Eh	GAMMA-B	02h	Contains the 2 MSBs of the 10-bit gamma voltage B
0Fh		00h	Contains the 8 LSBs of the 10-bit gamma voltage B
10h	GAMMA-C	02h	Contains the 2 MSBs of the 10-bit gamma voltage C
11h		00h	Contains the 8 LSBs of the 10-bit gamma voltage C
12h	GAMMA-D	02h	Contains the 2 MSBs of the 10-bit gamma voltage D
13h		00h	Contains the 8 LSBs of the 10-bit gamma voltage D
14h	GAMMA-E	02h	Contains the 2 MSBs of the 10-bit gamma voltage E
15h		00h	Contains the 8 LSBs of the 10-bit gamma voltage E
16h	GAMMA-F	02h	Contains the 2 MSBs of the 10-bit gamma voltage F
17h		00h	Contains the 8 LSBs of the 10-bit gamma voltage F
18h	GAMMA-G	02h	Contains the 2 MSBs of the 10-bit gamma voltage G
19h		00h	Contains the 8 LSBs of the 10-bit gamma voltage G
1Ah	GAMMA-H	02h	Contains the 2 MSBs of the 10-bit gamma voltage H
1Bh		00h	Contains the 8 LSBs of the 10-bit gamma voltage H
1Ch	GAMMA-I	02h	Contains the 2 MSBs of the 10-bit gamma voltage I
1Dh		00h	Contains the 8 LSBs of the 10-bit gamma voltage I
1Eh	GAMMA-J	02h	Contains the 2 MSBs of the 10-bit gamma voltage J
1Fh		00h	Contains the 8 LSBs of the 10-bit gamma voltage J
20h	GAMMA-K	02h	Contains the 2 MSBs of the 10-bit gamma voltage K
21h		00h	Contains the 8 LSBs of the 10-bit gamma voltage K
22h	GAMMA-L	02h	Contains the 2 MSBs of the 10-bit gamma voltage L
23h		00h	Contains the 8 LSBs of the 10-bit gamma voltage L
24h	GAMMA-M	02h	Contains the 2 MSBs of the 10-bit gamma voltage M
25h		00h	Contains the 8 LSBs of the 10-bit gamma voltage M
26h	GAMMA-N	02h	Contains the 2 MSBs of the 10-bit gamma voltage N
27h		00h	Contains the 8 LSBs of the 10-bit gamma voltage N
FFh	Control	00h	Controls whether read and write operations access RAM or EEPROM registers



### 5.11.3 CONFIG (00h)

**Figure 5-14. CONFIG Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented					RMODE	SMODE	GIP
					R/W-0	R/W-0	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-2. CONFIG Register Field Descriptions**

Bit	Field	Value	Description
7–3	Not implemented.	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
2	RMODE	0 1	Configures the $\overline{\text{RST}}$ power-down threshold voltage. <b>0</b> $V_{\text{UVLO}}$ threshold used. <b>1</b> $V_{\text{DET}}$ Threshold used.
1	SMODE	0 1	Configures the power-down behavior of $\text{AV}_{\text{DD}}$ and $V_{\text{COM}}$ . <b>0</b> $\text{AV}_{\text{DD}}$ is actively discharged (but not $V_{\text{COM}}$ ). <b>1</b> $V_{\text{COM}}$ is actively discharged (but not $\text{AV}_{\text{DD}}$ ).
0	GIP	0 1	This bit configures the device for use with either GIP or non-GIP LCD panels. <b>0</b> <b>The device operates in non-GIP mode, and XAO functions as a panel reset during power-down.</b> <b>1</b> The device operates in GIP mode, and the $\overline{\text{XAO}}$ functions as an enable for the panel's level shifter

### 5.11.4 AVDD (01h)

**Figure 5-15. AVDD Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented			AVDD				
			R/W-1	R/W-0	R/W-0	R/W-0	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = **factory default**

**Table 5-3. AVDD Register Field Descriptions**

Bit	Field	Value	Description
7–4	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
4–0	AVDD	00h 6.0 V 01h 6.1 V 02h 6.2 V 03h 6.3 V 04h 6.4 V 05h 6.5 V 06h 6.6 V 07h 6.7 V 08h 6.8 V 09h 6.9 V 0Ah 7.0 V 0Bh 7.1 V 0Ch 7.2 V 0Dh 7.3 V 0Eh 7.4 V 0Fh 7.5 V <b>10h 7.6 V</b> 11h 7.7 V 12h 7.8 V 13h 7.9 V 14h 8.0 V 15h 8.1 V 16h 8.2 V 17h 8.3 V 18h 8.4 V 19h 8.5 V 1Ah 8.6 V 1Bh 8.7 V 1Ch 8.8 V 1Dh 8.9 V 1Eh 9.0 V 1Fh 9.1 V	These bits configure boost converter 1's output voltage (AV <sub>DD</sub> ).

### 5.11.5 VGHHOT (02h)

**Figure 5-16. VGHHOT Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented				VGHHOT			
				R/W-0	R/W-0	R/W-0	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = **factory default**

**Table 5-4. VGHHOT Register Field Descriptions**

Bit	Field	Value	Description
7–4	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
3–0	VGHHOT	<b>0h 16 V</b> 1h 17 V 2h 18 V 3h 19 V 4h 20 V 5h 21 V 6h 22 V 7h 23 V 8h 24 V 9h 25 V Ah 26 V Bh 27 V Ch 28 V Dh 29 V Eh 30 V Fh 31 V	These bits configure boost converter 2's output voltage ( $V_{GH}$ ) at high temperatures.

### 5.11.6 VGHCOLD (03h)

**Figure 5-17. VGHCOLD Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented				VGHCOLD			
				R/W-0	R/W-0	R/W-0	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-5. VGHCOLD Register Field Descriptions**

Bit	Field	Value	Description
7–4	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
3–0	VGHCOLD	<b>0h 25 V</b> 1h 26 V 2h 27 V 3h 28 V 4h 29 V 5h 30 V 6h 31 V 7h 32 V 8h 33 V 9h 34 V Ah 35 V Bh 36 V Ch 37 V Dh 38 V Eh 39 V Fh 40 V	These bits configure boost converter 2's output voltage ( $V_{GH}$ ) at low temperatures.

### 5.11.7 VIO (04h)

**Figure 5-18. VIO Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented						VIO	
						R/W-0	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-6. VIO Register Field Descriptions**

Bit	Field	Value	Description
7–2	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
1–0	VIO	<b>0h</b> <b>V<sub>IO1</sub>=1.7 V, LDO regulator disabled.</b> <b>1h</b> V <sub>IO1</sub> =1.8 V, LDO regulator disabled. <b>2h</b> V <sub>IO1</sub> =2.5 V, V <sub>IO2</sub> =1.7 V. <b>3h</b> V <sub>IO1</sub> =2.5 V, V <sub>IO2</sub> =1.8 V.	These bits configure the output voltage of buck converter 2 (V <sub>IO1</sub> ) and the LDO regulator (V <sub>IO2</sub> ). To ensure reliable LDO programming, EN has to be "high" and the power-up sequence must be over (t <sub>DLY6</sub> ).

### 5.11.8 MISC (05h)

**Figure 5-19. MISC Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented					FREQ	VCORE	
					R/W-1	R/W-0	R/W-1

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-7. MISC Register Field Descriptions**

Bit	Field	Value	Description
7–3	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
2	FREQ	<b>0h</b> 750 kHz <b>1h</b> <b>1200 kHz</b>	This bit configures the switching frequency of boost converter 1 (AV <sub>DD</sub> ).
1–0	VCORE	<b>0h</b> 1.0 V <b>1h</b> <b>1.1 V</b> <b>2h</b> 1.2 V <b>3h</b> 1.3 V	These bits configure the output voltage of buck converter 1 (V <sub>CORE</sub> ).

### 5.11.9 SS1 (06h)

**Figure 5-20. SS1 Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented					SS1		
					R/W-0	R/W-1	R/W-1

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-8. SS1 Register Field Descriptions**

Bit	Field	Value	Description
7–3	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
2–0	SS1	0h 0.5 ms 1h 1.0 ms 2h 1.5 ms <b>3h 2.0 ms</b> 4h 2.5 ms 5h 3.0 ms 6h 3.5 ms 7h 4.0 ms	These bits configure the soft-start time for buck converter 1 ( $V_{CORE}$ ), buck converter 2 ( $V_{IO1}$ ) and the LDO linear regulator ( $V_{IO2}$ ).

### 5.11.10 SS2 (07h)

**Figure 5-21. SS2 Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented					SS2		
					R/W-0	R/W-0	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-9. SS2 Register Field Descriptions**

Bit	Field	Value	Description
7–3	Not Implemented	N/A 0 1	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
2–0	SS2	<b>0h 4.0 ms</b> 1h 4.5 ms 2h 5.0 ms 3h 5.5 ms 4h 6.0 ms 5h 6.5 ms 6h 7.0 ms 7h 7.5 ms	These bits configure the soft-start time for boost converter 1 ( $AV_{DD}$ ) and boost converter 2 ( $V_{GH}$ ).

### 5.11.11 RESET (08h)

**Figure 5-22. RESET Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented						RESET	
						R/W-0	R/W-1

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-10. RESET Register Field Descriptions**

Bit	Field	Value	Description
7–2	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
1–0	RESET	0h 2 ms <b>1h 4 ms</b> 2h 8 ms 3h 16 ms	These bits configure the duration of the reset pulse during start-up.

### 5.11.12 DLY1 (09h)

**Figure 5-23. DLY1 Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented						DLY1	
						R/W-0	R/W-1
							R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-11. DLY1 Register Field Descriptions**

Bit	Field	Value	Description
7–3	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
2–0	DLY1	0h 0 ms 1h 10 ms <b>2h 20 ms</b> 3h 30 ms 4h 40 ms 5h 50 ms 6h 60 ms 7h 70 ms	These bits configure the start-up delay for boost converter 1 ( $AV_{DD}$ ).

### 5.11.13 DLY6 (0Ah)

**Figure 5-24. DLY6 Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented					DLY6		
					R/W-1	R/W-0	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-12. DLY6 Register Field Descriptions**

Bit	Field	Value	Description
7–3	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
2–0	DLY6	0h 0 ms 1h 5 ms 2h 10 ms 3h 15 ms <b>4h 20 ms</b> 5h 25 ms 6h 30 ms 7h 35 ms	These bits configure the delay between $V_{GH}$ reaching its final value and gate voltage shaping or $\overline{XAO}$ being enabled.

### 5.11.14 VDET (0Bh)

**Figure 5-25. VDET Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented					VDET		
					R/W-0	R/W-0	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-13. VDET Register Field Descriptions**

Bit	Field	Value	Description
7–3	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
2–0	VDET	<b>0h 2.2 V</b> 1h 2.3 V 2h 2.4 V 3h 2.5 V 4h 3.6 V 5h 3.7 V 6h 3.8 V 7h 3.9 V	These bits configure the threshold for $\overline{XAO}$ and $\overline{RST}$ (if RMODE is "1" in the CONFIG register).



### 5.11.15 GAMxHI (0Ch, 0Eh...26h)

**Figure 5-26. GAMxHI Register Bit Allocation**

7	6	5	4	3	2	1	0
Not Implemented						GAMxHI	
						R/W-1	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-14. GAMxHI Register Field Descriptions**

Bit	Field	Value	Description
7–2	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
1–0	GAMxHI	0h–3h	These bits form the two most significant bits of the 10-bit GAMx value used to program the gamma correction voltage for channel x.

### 5.11.16 GAMxLO (0Dh, 0Fh...27h)

**Figure 5-27. GAMxLO Register Bit Allocation**

7	6	5	4	3	2	1	0
GAMxLO							
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-15. GAMxLO Register Field Descriptions**

Bit	Field	Value	Description
7–0	GAMxLO	00h–FFh	These bits form the least significant eight bits of the 10-bit value used to program the gamma correction voltage for channel x.

### 5.11.17 Control (FFh)

**Figure 5-28. CONTROL Register Bit Allocation**

7	6	5	4	3	2	1	0
WED	Not Implemented						RED
R/W-0							R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = factory default

**Table 5-16. CONTROL Register Field Descriptions**

Bit	Field	Value	Description
7	RED	<b>0</b> 1	This bit configures the data returned by read operations. <b>Read operations return the contents of the DAC registers.</b> Read operations return the content of the EEPROM registers.
6–1	Not Implemented	N/A	These bits are not implemented in hardware. During write operations data for these bits is ignored, and during read operations 0 is returned.
0	WED	<b>0</b> 1	Setting this bit forces the contents of all DAC registers to be copied to the EEPROM, thereby making them the default values during power-up. <b>0 Not used. This bit is automatically reset to 0 when the contents of the DAC registers have been copied to EEPROM.</b> The contents of all DAC registers are copied to the EEPROM, making them the new default values following power-up.

### 5.11.18 Example – Writing to a Single RAM Register

1. Bus master sends START condition
2. Bus master sends 7-bit slave address plus low R/W bit (E8h)
3. TPS65642 acknowledges
4. Bus master sends address of RAM register (00h)
5. TPS65642 acknowledges
6. Bus master sends data to be written
7. TPS65642 acknowledges
8. Bus master sends STOP condition

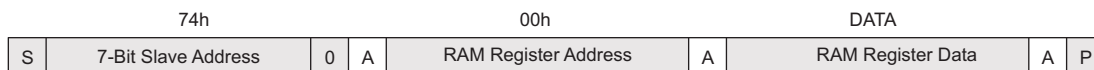


Figure 5-29. Writing to a Single RAM Register

### 5.11.19 Example – Writing to Multiple RAM Registers

1. Bus master sends START condition
2. Bus master sends 7-bit slave address plus low R/W bit (E8h).
3. TPS65642 acknowledges
4. Bus master sends address of first RAM register to be written to (00h)
5. TPS65642 acknowledges
6. Bus master sends data to be written to first RAM register
7. TPS65642 acknowledges
8. Bus master sends data to be written to RAM register at next higher address (auto-increment)
9. TPS65642 acknowledges
10. Steps (8) and (9) repeated until data for final RAM register has been sent
11. TPS65642 acknowledges
12. Bus master sends STOP condition

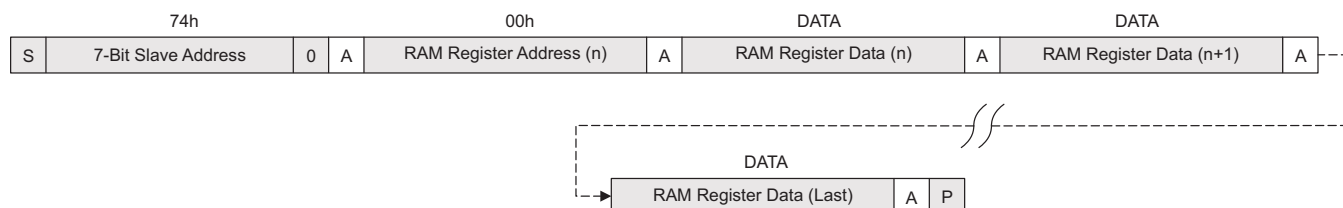
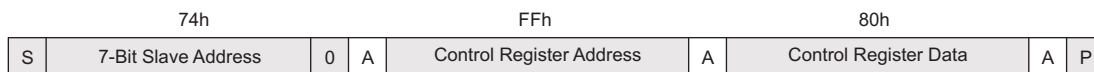


Figure 5-30. Writing to Multiple RAM Registers

### 5.11.20 Example – Saving Contents of all RAM Registers to EEPROM

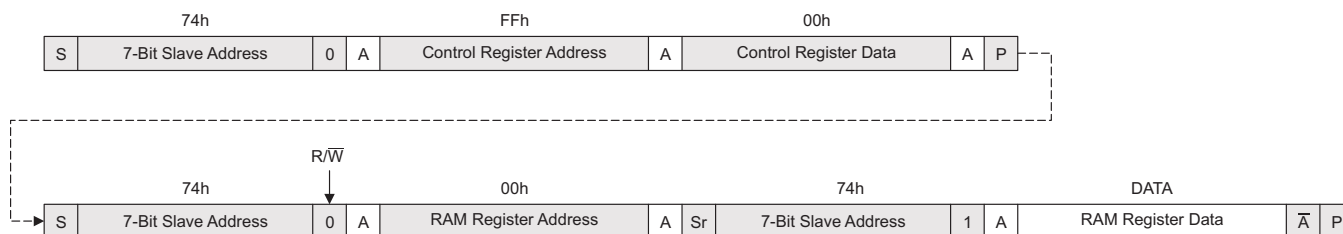
1. Bus master sends START condition
2. Bus master sends 7-bit slave address plus low R/W bit (E8h)
3. TPS65642 acknowledges
4. Bus master sends address of Control Register (FFh)
5. TPS65642 acknowledges
6. Bus master sends data to be written to the Control Register (80h)
7. TPS65642 acknowledges
8. Bus master sends STOP condition



**Figure 5-31. Saving Contents of all RAM Registers to E<sup>2</sup>PROM**

### 5.11.21 Example – Reading from a Single RAM Register

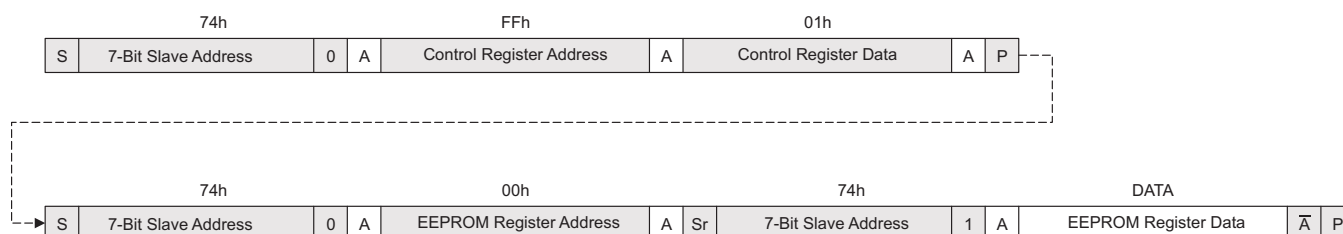
1. Bus master sends START condition
2. Bus master sends 7-bit slave address plus low R/W bit (E8h)
3. TPS65642 acknowledges
4. Bus master sends address of Control Register (FFh)
5. TPS65642 acknowledges
6. Bus master sends data for Control Register (00h)
7. TPS65642 acknowledges
8. Bus master sends STOP condition
9. Bus master sends START condition
10. Bus master sends 7-bit slave address plus low R/W bit (E8h)
11. TPS65642 acknowledges
12. Bus master sends address of RAM register (00h)
13. TPS65642 acknowledges
14. Bus master sends REPEATED START condition
15. Bus master sends 7-bit slave address plus high R/W bit (E9h)
16. TPS65642 acknowledges
17. TPS65642 sends RAM register data
18. Bus master does not acknowledge
19. Bus master sends STOP condition



**Figure 5-32. Reading from a Single RAM Register**

### 5.11.22 Example – Reading from a Single EEPROM Register

1. Bus master sends START condition
2. Bus master sends 7-bit slave address plus low R/W bit (E8h)
3. TPS65642 acknowledges
4. Bus master sends address of Control Register (FFh)
5. TPS65642 acknowledges
6. Bus master sends data for Control Register (01h)
7. TPS65642 acknowledges
8. Bus master sends STOP condition
9. Bus master sends START condition
10. Bus master sends 7-bit slave address plus low R/W bit (E8h)
11. TPS65642 acknowledges
12. Bus master sends address of EEPROM register (00h)
13. TPS65642 acknowledges
14. Bus master sends REPEATED START condition
15. Bus master sends 7-bit slave address plus high R/W bit (E9h)
16. TPS65642 acknowledges
17. TPS65642 sends EEPROM register data
18. Bus master does not acknowledge
19. Bus master sends STOP condition



**Figure 5-33. Reading from a Single EEPROM Register**

### 5.11.23 Example – Reading from Multiple RAM Registers

1. Bus master sends START condition
2. Bus master sends 7-bit slave address plus low R/W bit (E8h)
3. TPS65642 acknowledges
4. Bus master sends address of Control Register (FFh)
5. TPS65642 acknowledges
6. Bus master sends data for Control Register (00h)
7. TPS65642 acknowledges
8. Bus master sends STOP condition
9. Bus master sends START condition
10. Bus master sends 7-bit slave address plus low R/W bit (E8h)
11. TPS65642 acknowledges
12. Bus master sends address of first register to be read (00h)
13. TPS65642 acknowledges
14. Bus master sends REPEATED START condition
15. Bus master sends 7-bit slave address plus high R/W bit (E9h)
16. TPS65642 acknowledges
17. TPS65642 sends contents of first RAM register to be read
18. Bus master acknowledges
19. TPS65642 sends contents of second RAM register to be read
20. Bus master acknowledges
21. TPS65642 sends contents of third (last) RAM register to be read
22. Bus master does not acknowledge
23. Bus master sends STOP condition

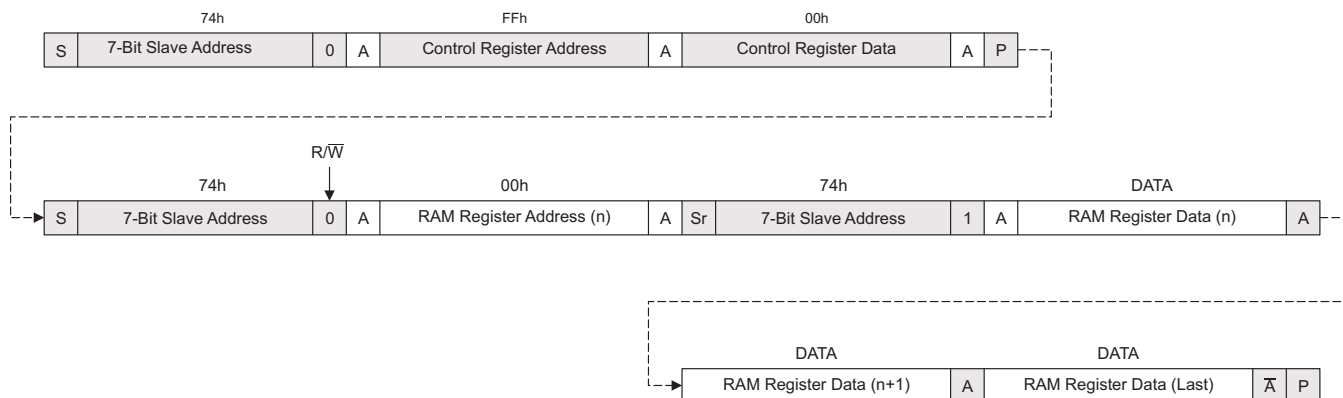
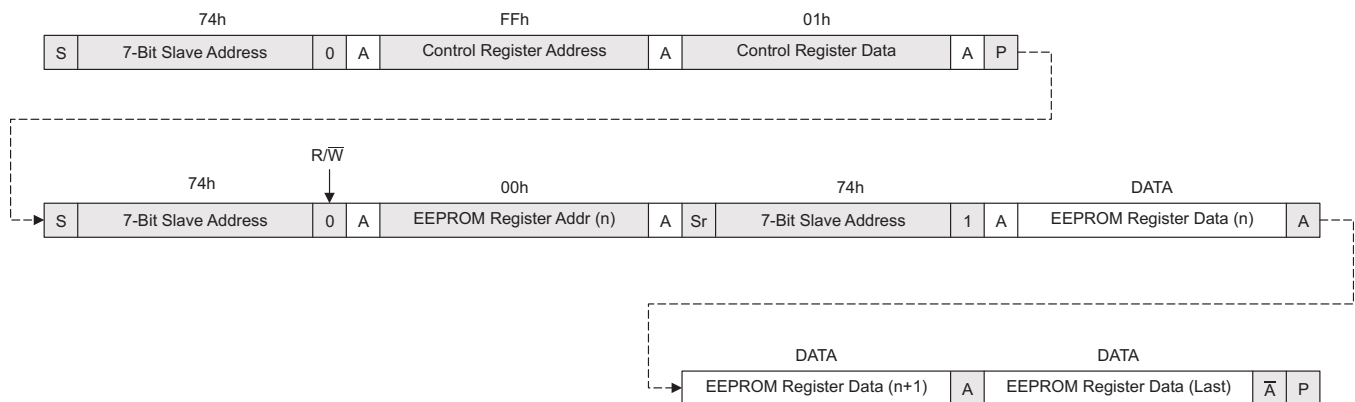


Figure 5-34. Reading from Multiple RAM Registers

### 5.11.24 Example – Reading from Multiple EEPROM Registers

1. Bus master sends START condition
2. Bus master sends 7-bit slave address plus low R/W bit (E8h)
3. TPS65642 acknowledges
4. Bus master sends address of Control Register (FFh)
5. TPS65642 acknowledges
6. Bus master sends data for Control Register (01h)
7. TPS65642 acknowledges
8. Bus master sends STOP condition
9. Bus master sends START condition
10. Bus master sends 7-bit slave address plus low R/W bit (E8h)
11. TPS65642 acknowledges
12. Bus master sends address of first EEPROM register to be read (00h)
13. TPS65642 acknowledges
14. Bus master sends REPEATED START condition
15. Bus master sends 7-bit slave address plus high R/W bit (E9h)
16. TPS65642 acknowledges
17. TPS65642 sends contents of first EEPROM register to be read
18. Bus master acknowledges
19. TPS65642 sends contents of second EEPROM register to be read
20. Bus master acknowledges
21. TPS65642 sends contents of third (last) EEPROM register to be read
22. Bus master does not acknowledge
23. Bus master sends STOP condition



**Figure 5-35. Reading from Multiple EEPROM Registers**



### 5.11.25 Configuration Parameter VCOM

**Figure 5-36. VCOM Register Bit Allocation**

7	6	5	4	3	2	1	0
VCOM							P
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

LEGEND: R/W = Read/Write; R = Read only; -n = **factory default**

**Table 5-17. VCOM Register Field Descriptions**

Bit	Field	Value	Description
7–1	VCOM	00h–7F <sub>h</sub>	During write operations these bits contain the data to be written. During read operations these bits contain the contents of the EEPROM register. $I_{OUT} = \frac{V_{REF}}{R_{SET}} \times \frac{VCOM + 1}{128}$
0	P	0	During write operations this bit configures the destination for data. <b>Data is written to the DAC register and EEPROM.</b>
		1	Data is written to the DAC register only.
		0	During read operations this bit indicates whether the contents of the RAM register and EEPROM are the same or not. <b>DAC register and EEPROM contents are the same.</b>
		1	DAC register and EEPROM contents are different.

### 5.11.26 Example – Writing a VCOM Value of 77h to RAM Register Only

1. Bus master sends a START condition.
2. Bus master sends 9E hexadecimal (7-bit slave address plus low R/W bit).
3. TPS65642 slave acknowledges.
4. Bus master sends EF hexadecimal (data to be written plus LSB = '1').
5. TPS65642 slave acknowledges.
6. Bus master sends a STOP condition.

4Fh				77h			
S	7-Bit Slave Address	0	A	Data to be Written	1	A	P

**Figure 5-37. Writing a VCOM Value of 77h to RAM Only**

### 5.11.27 Example – Writing a VCOM Value of 77h to EEPROM and RAM

1. Bus master sends a START condition.
2. Bus master sends 9E hexadecimal (7-bit slave address plus low R/W bit).
3. TPS65642 slave acknowledges.
4. Bus master sends EE hexadecimal (data to be written plus LSB = '0').
5. TPS65642 slave acknowledges.
6. Bus master sends a STOP condition.



**Figure 5-38. Writing a VCOM Value of 77h to EEPROM and RAM**

### 5.11.28 Example – Reading a VCOM Value of 77h from EEPROM when RAM Contents are Identical

1. Bus master sends a START condition.
2. Bus master sends 9F hexadecimal (7-bit slave address plus high R/W bit).
3. TPS65642 slave acknowledges.
4. TPS65642 sends EE hexadecimal from EEPROM (data to be read plus LSB = '0').
5. Bus master does not acknowledge.
6. Bus master sends a STOP condition.



**Figure 5-39. Reading 77h from EEPROM when RAM Contents are Identical**

### 5.11.29 Example – Reading a VCOM Value of 77h from EEPROM when RAM Contents are Different

1. Bus master sends a START condition.
2. Bus master sends 9F hexadecimal (7-bit slave address plus high R/W bit).
3. TPS65642 slave acknowledges.
4. TPS65642 sends EF hexadecimal from RAM (data to be read plus LSB = '0').
5. Bus master does not acknowledge.
6. Bus master sends a STOP condition.



Figure 5-40. Reading 77h from EEPROM when RAM Contents are Different

### 5.11.30 I<sup>2</sup>C Interface

Configuration parameters and the  $V_{COM}$  voltage setting are programmed via an industry standard I<sup>2</sup>C serial interface. The TPS65642 always works as a slave device and supports standard (100 kbps) and fast (400 kbps) modes of operation. During write operations, all further attempts to access its slave addresses are ignored until the current write operation has completed.

**The I<sup>2</sup>C interface contains a known bug. If a new start condition appears on the bus before transfer of the slave address byte from a previously initiated read/write operation is complete, the I<sup>2</sup>C interface may hang. Normal operation is recovered after cycling  $V_{IN}$ .**

## 5.12 Power Sequencing

Buck converter 2 ( $V_{IO1}$ ) and the linear regulator ( $V_{IO2}$ ) start as soon as  $V_{IN} > V_{UVLO}$ .

Buck converter 1 ( $V_{CORE}$ ) starts as soon as  $V_{IO1}$  and  $V_{IO2}$  have finished ramping up.

The reset generator holds  $\overline{RST}$  low until  $t_{RESET}$  seconds after  $V_{CORE}$  has reached power good status.

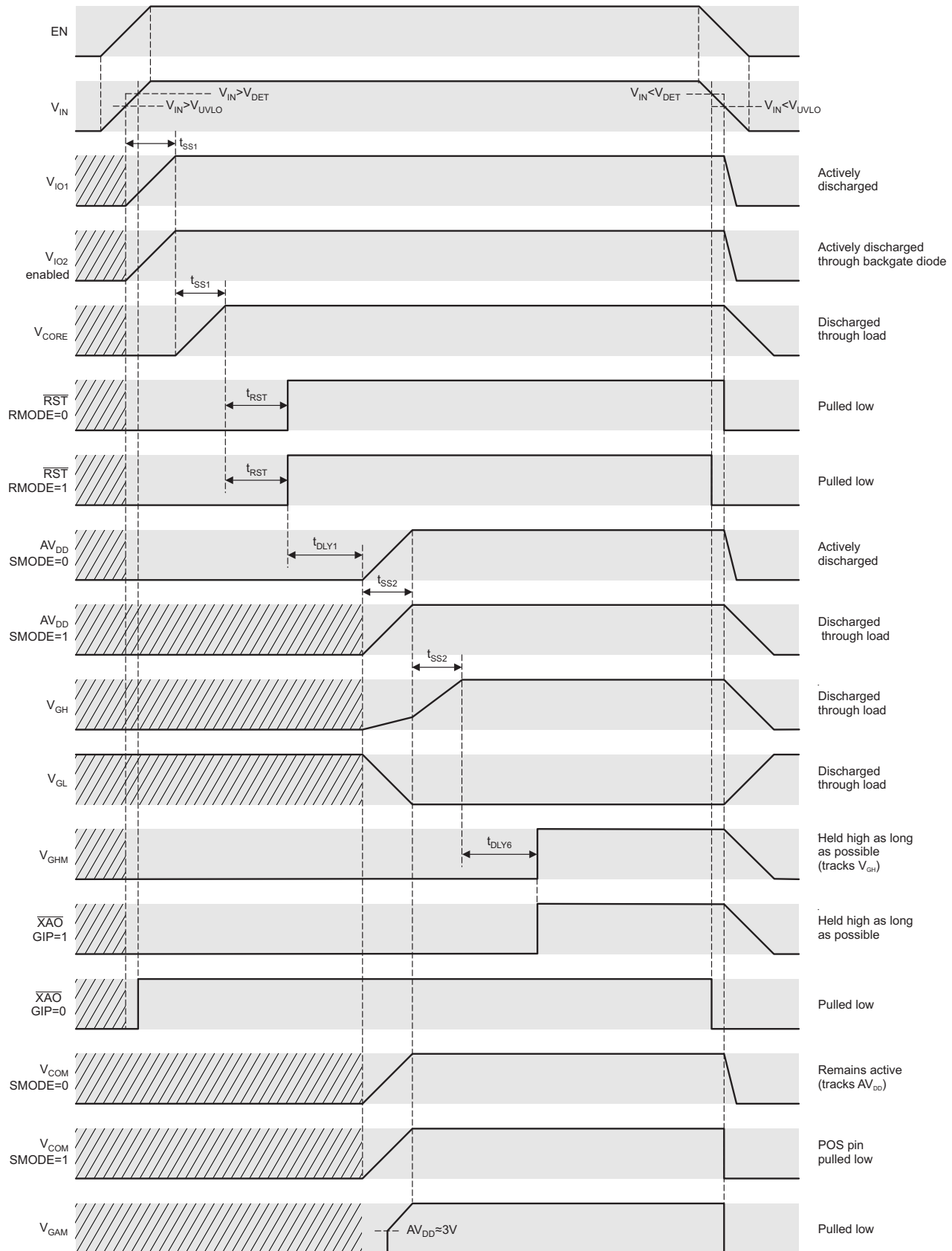
Boost converter 1 starts  $t_{DLY1}$  milliseconds after EN goes high (or  $\overline{RST}$  has gone high, whichever occurs later). Once asserted, the EN signal must remain high to ensure normal device operation. Once disabled ( $EN = 0$ ), boost converter 1 remains disabled until the device is powered down (even if EN is re-asserted).

Boost converter 2 starts as soon as  $AV_{DD}$  has reached power good status.

In non-GIP mode,  $V_{GHM}$  is held high impedance until  $t_{DLY6}$  milliseconds after  $V_{GH}$  reaches power good status;  $\overline{XAO}$  goes high when  $V_{IN} > V_{DET}$  and low when  $V_{IN} < V_{DET}$ .

In GIP mode,  $\overline{XAO}$  is held low until  $t_{DLY6}$  milliseconds after  $V_{GH}$  reaches power good status.

Figure 5-41 and Figure 5-42 show the typical power-up/down characteristic of the TPS65642.

Figure 5-41. Power Up/Down Sequencing with EN Connected to V<sub>IN</sub>

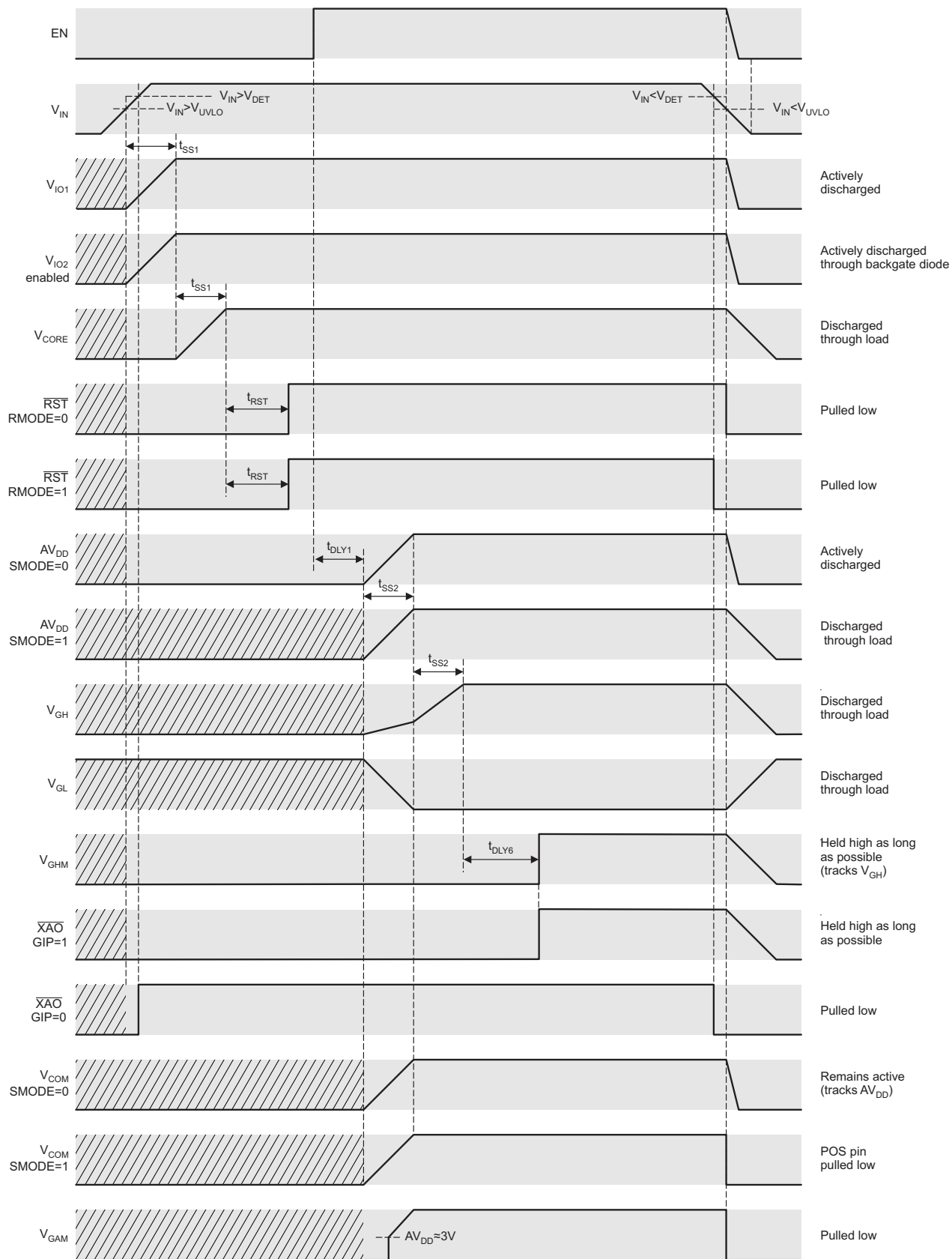


Figure 5-42. Power Up/Down Sequencing with EN Connected to T-CON Ready

## 5.13 Undervoltage Lockout

An undervoltage lockout function disables the TPS65642 when the supply voltage is too low for proper operation.

# 6 Application Information

## 6.1 External Component Selection

Care should be applied to the choice of external components since they greatly affect overall performance. The TPS65642 was developed with the twin goals of high performance and small/low-profile solution size. Since these two goals are often in direct opposition to one another (e.g. larger inductors tend to achieve higher efficiencies), some trade-off is always necessary.

Inductors must have adequate current capability so that they do not saturate under worst-case conditions. For high efficiency, they should also have low dc resistance (DCR).

Capacitors must have adequate *effective* capacitance under the applicable dc bias conditions they experience in the application. MLCC capacitors typically exhibit only a fraction of their nominal capacitance under real-world conditions and this must be taken into consideration when selecting them. This problem is especially acute in low profile capacitors, in which the dielectric field strength is higher than in taller components. In general, the capacitance values shown in circuit diagrams in this data sheet refer to the *effective* capacitance after dc bias effects have been taken into consideration. Reputable capacitor manufacturers provide capacitance versus dc bias curves that greatly simplify component selection.

The following tables list some components suitable for use with the TPS65642. The list is not exhaustive – other components may exist that are equally suitable (or better), however, these components have been proven to work well and were used extensively during the development of the TPS65642.

**Table 6-1. Boost Converter 1 External Components**

REF.	DESCRIPTION	PART NUMBER	MANUFACTURER	THICKNESS
L	Chip Inductor, 4.7 $\mu$ H, $\pm 20\%$	1269AS-H-4R7N	Toko	<1.0mm
C <sub>IN</sub>	Ceramic Capacitor, X5R, 10 $\mu$ F, 16 V, $\pm 20\%$	GRM319R61H475MA12	Murata	<0.85mm
C <sub>OUT</sub>				

**Table 6-2. Buck Converter 1 External Component Recommendations**

REF.	DESCRIPTION	PART NUMBER	MANUFACTURER	THICKNESS
L	Chip Inductor	1269AS-H-2R2N	Toko	<1.0mm
C <sub>OUT</sub>	Ceramic Capacitor, X5R, 10 $\mu$ F, 6.3 V, $\pm 20\%$	GRM319R61H475MA12	Murata	<0.85mm

**Table 6-3. Buck Converter 2 External Component Recommendations**

REF.	DESCRIPTION	PART NUMBER	MANUFACTURER	THICKNESS
L	Chip Inductor	1269AS-H-2R2	Toko	<1.0mm
C <sub>OUT</sub>	Ceramic Capacitor, X5R, 10 $\mu$ F, 6.3 V, $\pm 20\%$	GRM319R61H475MA12	Murata	<0.85mm

**Table 6-4. LDO Regulator External Component Recommendations**

REF.	DESCRIPTION	PART NUMBER	MANUFACTURER	THICKNESS
C <sub>OUT</sub>	Ceramic Capacitor, X5R, 10 $\mu$ F, 6.3 V, $\pm 20\%$	GRM319R61H475MA12	Murata	<0.85mm

**Table 6-5. Boost Converter 2 External Components**

REF.	DESCRIPTION	PART NUMBER	MANUFACTURER	THICKNESS
L	Wirewound Inductor, 15 $\mu$ H, $\pm$ 20%	1156AS-150M	Toko	<1.0mm
L	Wirewound Inductor, 15 $\mu$ H, $\pm$ 20%	LQH3NPN150NG0	Murata	<1.0mm
C <sub>OUT</sub>	Ceramic Capacitor, X5R, 4.7 $\mu$ F, 50 V, $\pm$ 20%	GRM319R61H475MA12	Murata	<0.85mm
D	Switching Diode, 150 mA, 75 V, 350 mW	BAS16W	Infineon	<1.0mm

## 6.2 Typical Application Circuit

Figure 6-1 and Figure 6-2 show the recommended application circuits for non-GIP and GIP displays respectively. Minor changes may be needed to optimize the circuit for a specific application, however, the basic circuit is unlikely to change significantly.

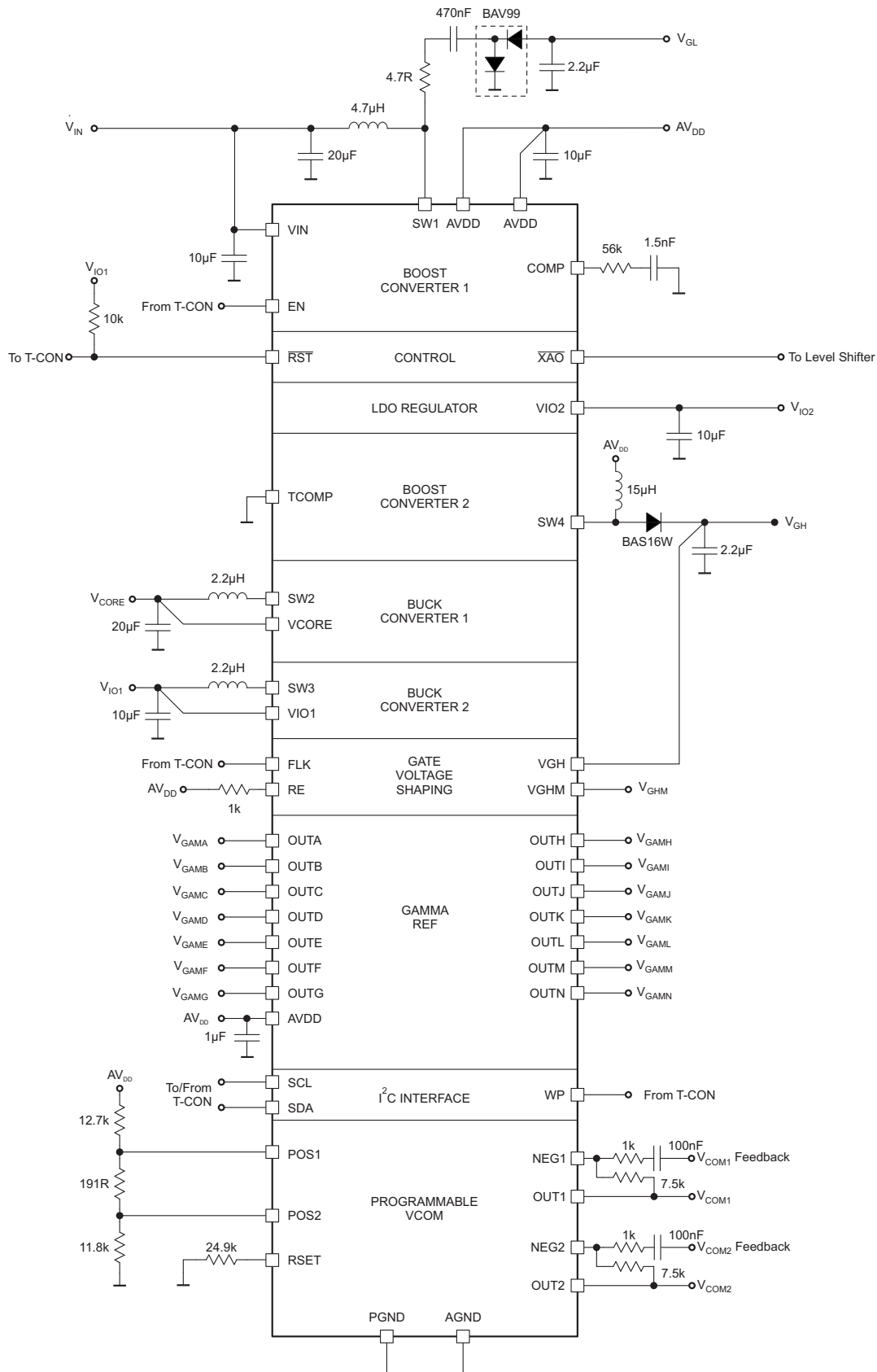


Figure 6-1. Typical Application Circuit for Non-GIP Displays



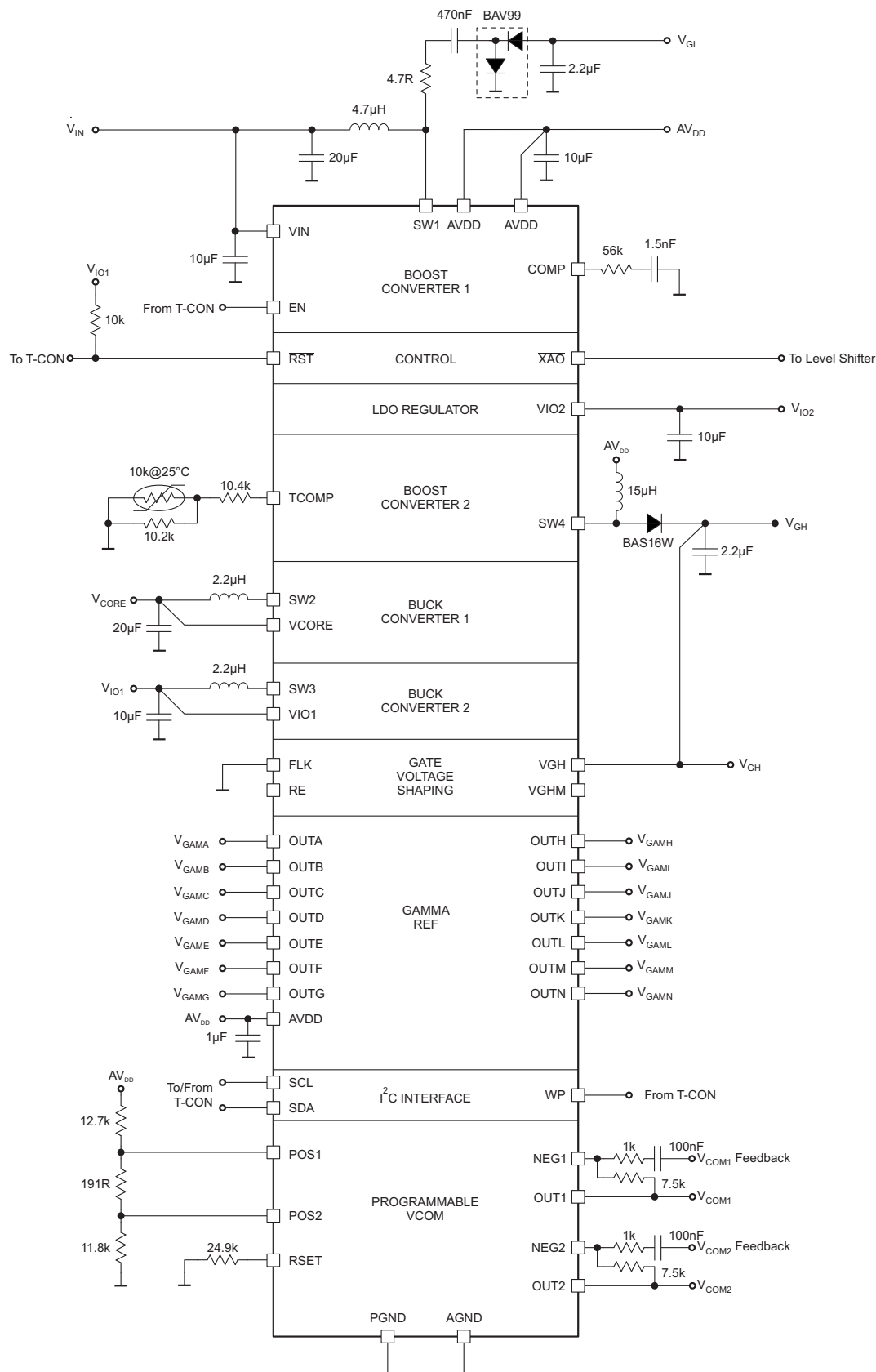


Figure 6-2. Typical Application Circuit for GIP Displays

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">TPS65642YFFR</a>	Active	Production	DSBGA (YFF)   56	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	TPS65642
TPS65642YFFR.A	Active	Production	DSBGA (YFF)   56	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	TPS65642

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

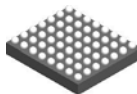
<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

**Important Information and Disclaimer:**The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

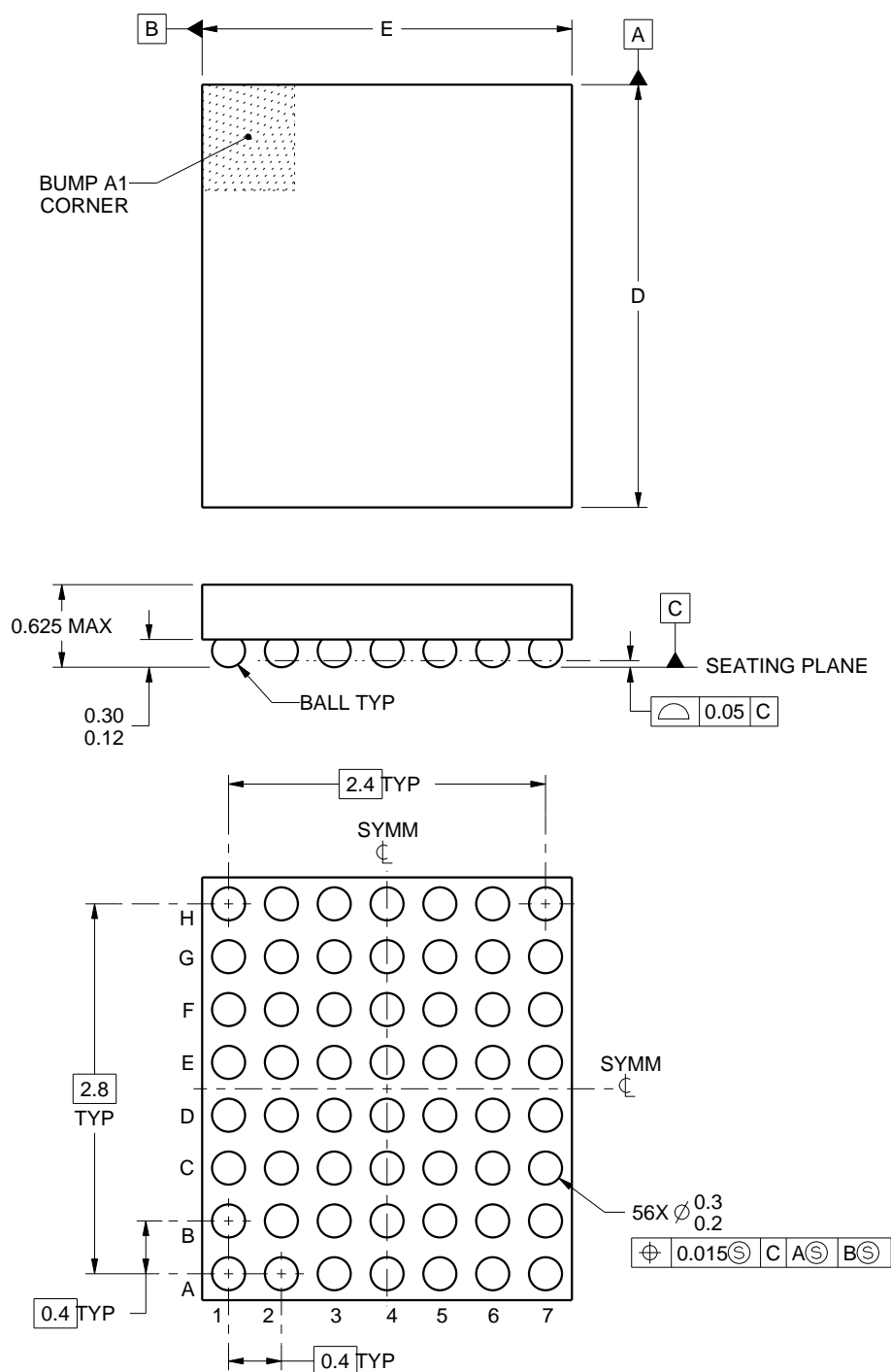
YFF0056



# PACKAGE OUTLINE

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



4219481/A 10/2014

## NOTES:

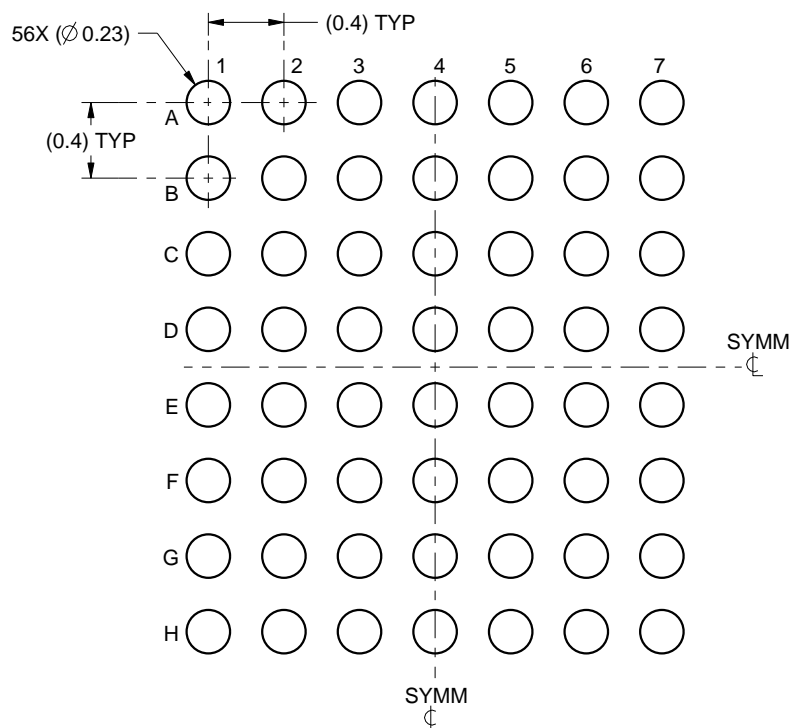
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

# EXAMPLE BOARD LAYOUT

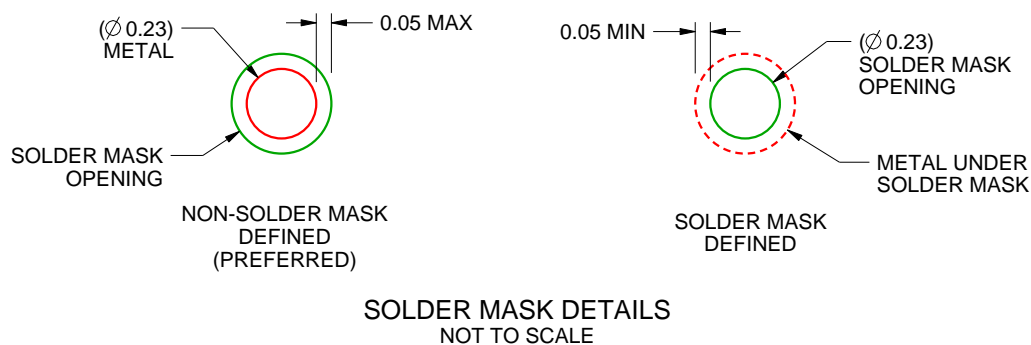
YFF0056

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



LAND PATTERN EXAMPLE  
SCALE:25X



4219481/A 10/2014

NOTES: (continued)

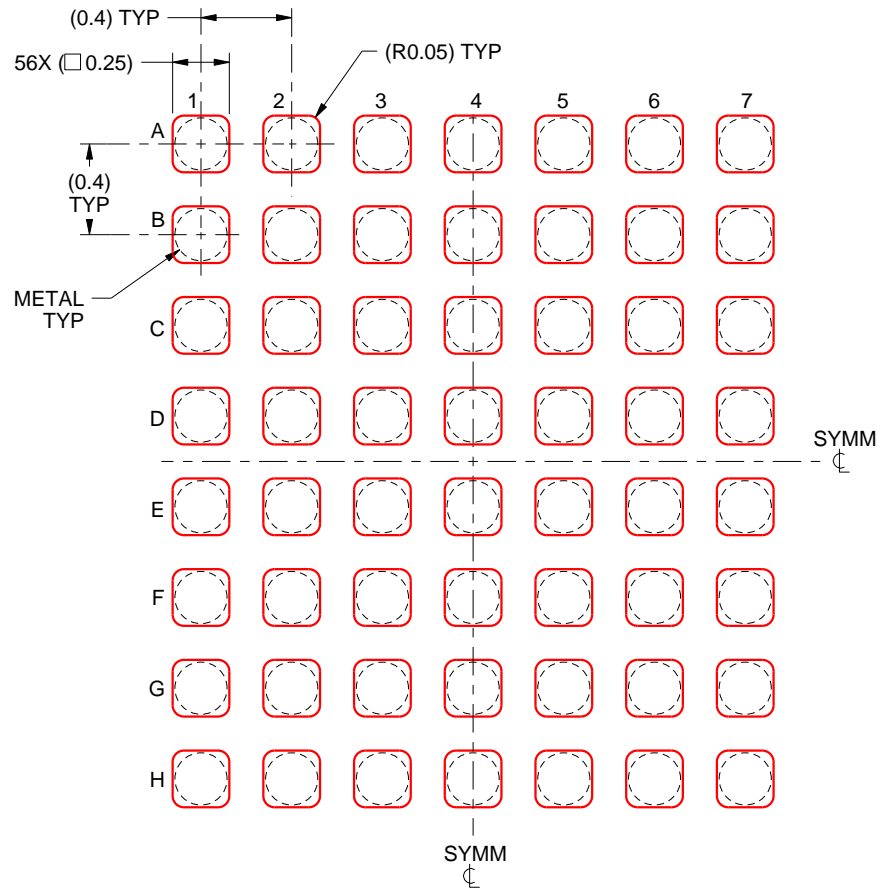
- Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. For more information, see Texas Instruments literature number SBVA017 ([www.ti.com/lit/sbva017](http://www.ti.com/lit/sbva017)).

# EXAMPLE STENCIL DESIGN

YFF0056

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



SOLDER PASTE EXAMPLE  
BASED ON 0.1 mm THICK STENCIL  
SCALE:30X

4219481/A 10/2014

NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

## 重要通知和免责声明

TI“按原样”提供技术和可靠性数据（包括数据表）、设计资源（包括参考设计）、应用或其他设计建议、网络工具、安全信息和其他资源，不保证没有瑕疵且不做任何明示或暗示的担保，包括但不限于对适销性、与某特定用途的适用性或不侵犯任何第三方知识产权的暗示担保。

这些资源可供使用 TI 产品进行设计的熟练开发人员使用。您将自行承担以下全部责任：(1) 针对您的应用选择合适的 TI 产品，(2) 设计、验证并测试您的应用，(3) 确保您的应用满足相应标准以及任何其他安全、安保法规或其他要求。

这些资源如有变更，恕不另行通知。TI 授权您仅可将这些资源用于研发本资源所述的 TI 产品的相关应用。严禁以其他方式对这些资源进行复制或展示。您无权使用任何其他 TI 知识产权或任何第三方知识产权。对于因您对这些资源的使用而对 TI 及其代表造成的任何索赔、损害、成本、损失和债务，您将全额赔偿，TI 对此概不负责。

TI 提供的产品受 [TI 销售条款](#)、[TI 通用质量指南](#) 或 [ti.com](#) 上其他适用条款或 TI 产品随附的其他适用条款的约束。TI 提供这些资源并不会扩展或以其他方式更改 TI 针对 TI 产品发布的适用的担保或担保免责声明。除非德州仪器 (TI) 明确将某产品指定为定制产品或客户特定产品，否则其产品均为按确定价格收入目录的标准通用器件。

TI 反对并拒绝您可能提出的任何其他或不同的条款。

版权所有 © 2025，德州仪器 (TI) 公司

最后更新日期：2025 年 10 月