



# TPS54233 2A, 28V Input, Step Down DC/DC Converter With Eco-mode™

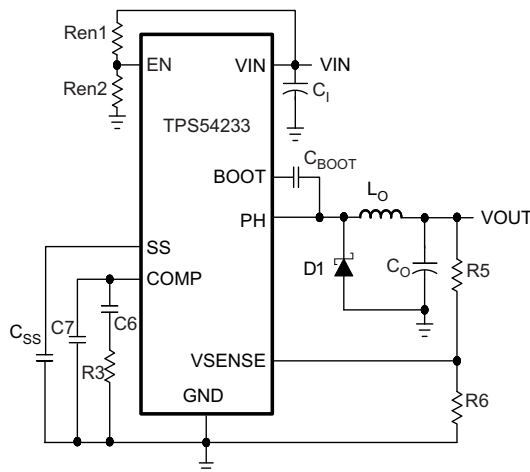
## 1 Features

- 3.5 V to 28 V Input Voltage Range
- Adjustable Output Voltage Down to 0.8 V
- Integrated 80 mΩ High Side MOSFET Supports up to 2A Continuous Output Current
- High Efficiency at Light Loads with a Pulse Skipping Eco-mode™
- Fixed 300 kHz Switching Frequency
- Typical 1 μA Shutdown Quiescent Current
- Adjustable Slow Start Limits Inrush Currents
- Programmable UVLO Threshold
- Overvoltage Transient Protection
- Cycle by Cycle Current Limit, Frequency Fold Back and Thermal Shutdown Protection
- Available in Easy-to-Use SOIC8 Package
- Supported by WEBENCH® Software Tool ([www.ti.com/WEBENCH](http://www.ti.com/WEBENCH))

## 2 Applications

- Consumer Applications such as Set-Top Boxes, CPE Equipment, LCD Displays, Peripherals, and Battery Chargers
- Industrial and Car Audio Power Supplies
- 5V, 12V and 24V Distributed Power Systems

## 4 Simplified Schematic



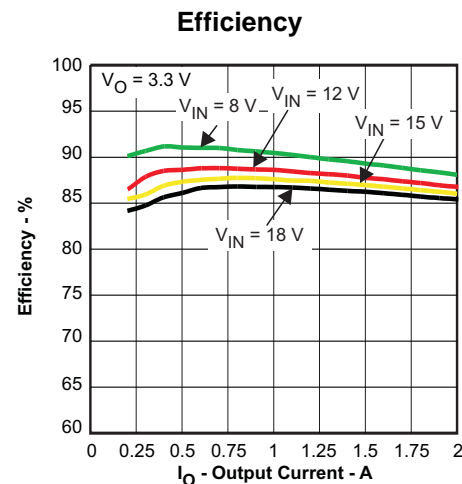
## 3 Description

The TPS54233 is a 28 V, 2 A non-synchronous buck converter that integrates a low  $R_{DS(on)}$  high side MOSFET. To increase efficiency at light loads, a pulse skipping Eco-mode™ feature is automatically activated. Furthermore, the 1 μA shutdown supply current allows the device to be used in battery powered applications. Current mode control with internal slope compensation simplifies the external compensation calculations and reduces component count while allowing the use of ceramic output capacitors. A resistor divider programs the Hysteresis of the input under-voltage lockout. An overvoltage transient protection circuit limits voltage overshoots during startup and transient conditions. A cycle by cycle current limit scheme, frequency fold back and thermal shutdown protect the device and the load in the event of an overload condition. The TPS54233 is available in an 8-pin SOIC package that has been internally optimized to improve thermal performance.

### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPS54233	SOIC (8)	4.90 mm x 3.90 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.



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## 5 Revision History

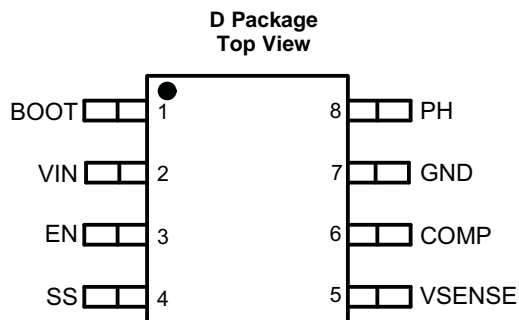
NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision B (February 2011) to Revision C	Page
• Removed Swift™ from the data sheet title .....	<b>1</b>
• Added <i>ESD Rating</i> table, <i>Thermal Information</i> table, <i>Feature Description</i> section, <i>Device Functional Modes</i> , <i>Application and Implementation</i> section, <i>Power Supply Recommendations</i> section, <i>Device and Documentation</i> <i>Support</i> section, and <i>Mechanical, Packaging</i> sections. ....	<b>1</b>
• Deleted <i>Features</i> Item: For SWIFT™ Documentation, See the TI Website at www.ti.com/swift.....	<b>1</b>
• Changed <i>Features</i> item: Supported by SwitcherPro™ To: Supported by WEBENCH®.....	<b>1</b>
• Changed R <sub>O1</sub> To: R5, R <sub>O2</sub> To R6, C <sub>1</sub> To C6, and C <sub>2</sub> To C7 in the <i>Simplified Schematic</i> .....	<b>1</b>
• Changed SwitcherPro™ Software tool To: WEBENCH Software tool in the <i>Current Mode Compensation Design</i> section .....	<b>10</b>
• Changed R <sub>O1</sub> To: R5, R <sub>O2</sub> To R6, C <sub>1</sub> To C6, and C <sub>2</sub> To C7 in the <i>Table 1</i> .....	<b>10</b>
• Changed the <i>Output Voltage Set Point</i> section. Updated the paragraph following <i>Equation 5</i> . ....	<b>13</b>

Changes from Revision A (March 2010) to Revision B	Page
• <i>Figure 14</i> , Changed V <sub>IN</sub> = 18 V on the top (blue) curve To: V <sub>IN</sub> = 8 V .....	<b>20</b>

Changes from Original (October 2008) to Revision A	Page
• Changed the <i>Absolute Maximum Ratings</i> <sup>(1)</sup> table, Input Voltage - EN pin max value From: 5V to 6V .....	<b>4</b>
• Added A table to the <i>Description</i> - with text "For additional design needs, see.." .....	<b>12</b>

## 6 Pin Configuration and Functions



### Pin Functions

PIN		DESCRIPTION
NAME	NO.	
BOOT	1	A 0.1 $\mu$ F bootstrap capacitor is required between BOOT and PH. If the voltage on this capacitor falls below the minimum requirement, the high-side MOSFET is forced to switch off until the capacitor is refreshed.
VIN	2	Input supply voltage, 3.5 V to 28 V.
EN	3	Enable pin. Pull below 1.25V to disable. Float to enable. Programming the input undervoltage lockout with two resistors is recommended.
SS	4	Slow start pin. An external capacitor connected to this pin sets the output rise time.
VSENSE	5	Inverting node of the gm error amplifier.
COMP	6	Error amplifier output, and input to the PWM comparator. Connect frequency compensation components to this pin.
GND	7	Ground.
PH	8	The source of the internal high-side power MOSFET.

## 7 Specifications

### 7.1 Absolute Maximum Ratings<sup>(1)</sup>

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
Input Voltage	VIN	−0.3	30	V
	EN	−0.3	6	
	BOOT		38	
	VSENSE	−0.3	3	
	COMP	−0.3	3	
	SS	−0.3	3	
Output Voltage	BOOT-PH		8	V
	PH	−0.6	30	
	PH (10 ns transient from ground to negative peak)		−5	
Source Current	EN		100	μA
	BOOT		100	mA
	VSENSE		10	μA
	PH		6	A
Sink Current	VIN		6	A
	COMP		100	μA
	SS		200	
Operating Junction Temperature		−40	150	°C
Storage Temperature		−65	150	°C

- (1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 7.2 ESD Ratings

		VALUE	UNIT
V <sub>(ESD)</sub> Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±2000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	TYP	MAX	UNIT
Operating Input Voltage on (VIN pin)	3.5		28	V
Operating junction temperature, T <sub>J</sub>	−40		150	°C

### 7.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		D	UNIT
		8 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	116.7	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	62.4	
R <sub>θJB</sub>	Junction-to-board thermal resistance	57.0	
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	14.5	
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	56.5	
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	N/A	

- (1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).

## 7.5 Electrical Characteristics

$T_J = -40^{\circ}\text{C}$  to  $150^{\circ}\text{C}$ ,  $V_{IN} = 3.5\text{V}$  to  $28\text{V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY VOLTAGE (VIN PIN)					
Internal undervoltage lockout threshold	Rising and Falling			3.5	V
Shutdown supply current	EN = 0V, VIN = 12V, −40°C to 85°C		1	4	μA
Operating – non switching supply current	VSENSE = 0.85 V		75	110	μA
ENABLE AND UVLO (EN PIN)					
Enable threshold	Rising and Falling		1.25	1.35	V
Input current	Enable threshold – 50 mV		-1		μA
Input current	Enable threshold + 50 mV		-4		μA
VOLTAGE REFERENCE					
Voltage reference		0.772	0.8	0.828	V
HIGH-SIDE MOSFET					
On resistance	BOOT-PH = 3 V, VIN = 3.5 V		115	200	mΩ
	BOOT-PH = 6 V, VIN = 12 V		80	150	
ERROR AMPLIFIER					
Error amplifier transconductance (gm)	−2 μA < I <sub>(COMP)</sub> < 2 μA, V <sub>(COMP)</sub> = 1 V		92		μmhos
Error amplifier DC gain <sup>(1)</sup>	VSENSE = 0.8 V		800		V/V
Error amplifier unity gain bandwidth <sup>(1)</sup>	5 pF capacitance from COMP to GND pins		2.7		MHz
Error amplifier source/sink current	V <sub>(COMP)</sub> = 1 V, 100 mV overdrive		±7		μA
Switch current to COMP transconductance	VIN = 12 V		9		A/V
PULSE SKIPPING Eco-mode™					
Pulse skipping Eco-mode™ switch current threshold			100		mA
CURRENT LIMIT					
Current limit threshold	VIN = 12 V	2.3	3.5		A
THERMAL SHUTDOWN					
Thermal Shutdown			165		°C
SLOW START (SS PIN)					
Charge current	V <sub>(SS)</sub> = 0.4 V		2		μA
SS to VSENSE matching	V <sub>(SS)</sub> = 0.4 V		10		mV

(1) Specified by design

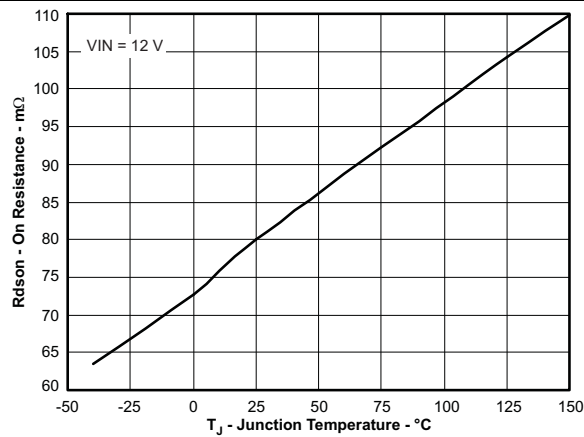
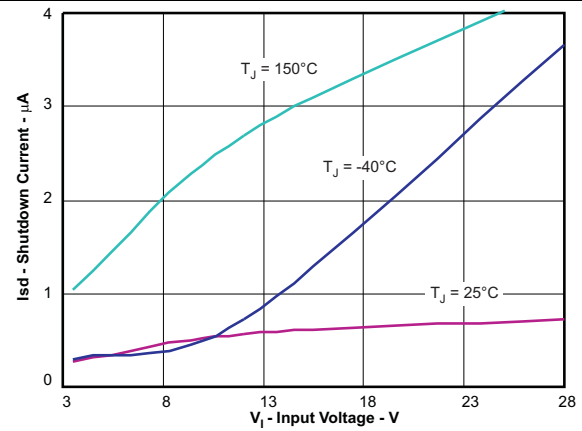
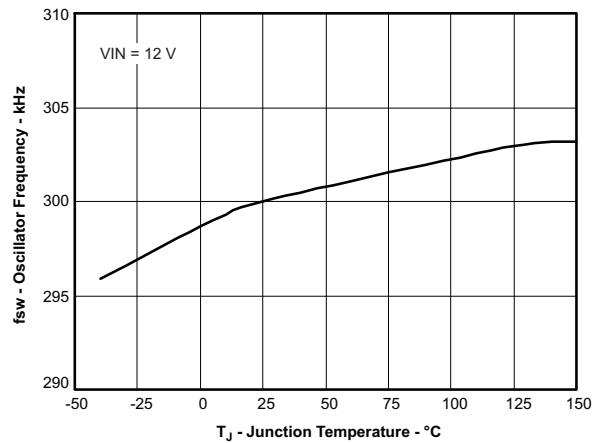
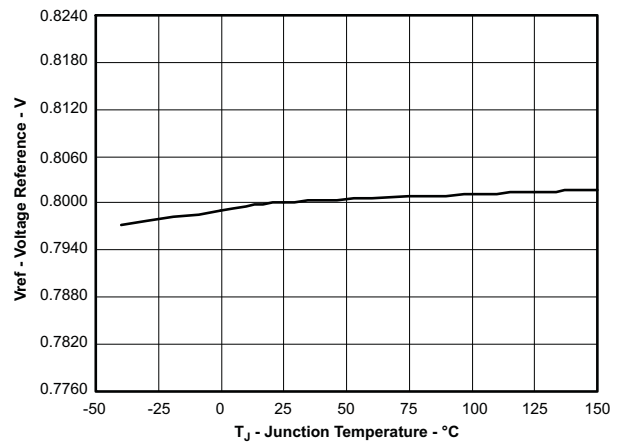
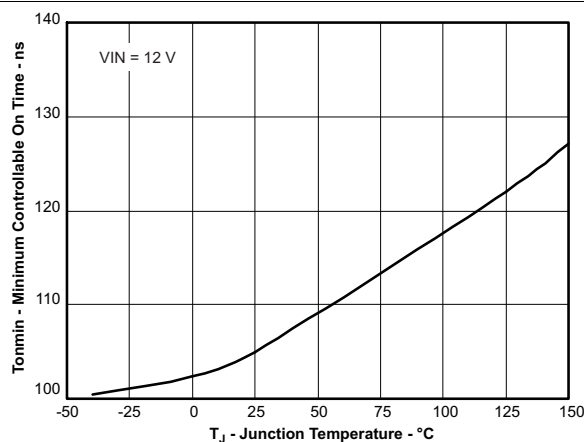
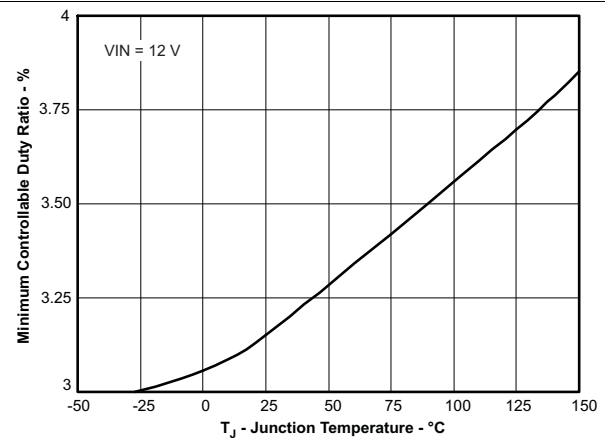
## 7.6 Switching Characteristics

$T_J = -40^{\circ}\text{C}$  to  $150^{\circ}\text{C}$ ,  $V_{IN} = 3.5$  to  $28\text{ V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>SWITCHING FREQUENCY</b>					
Device switching frequency	$V_{IN} = 12\text{ V}$	210	300	390	kHz
Minimum controllable on time	$V_{IN} = 12\text{ V}$ , $25^{\circ}\text{C}$		105	130	ns
Maximum controllable duty ratio <sup>(1)</sup>	BOOT-PH = 6 V	90%	93%		

(1) Specified by design.

## 7.7 Typical Characteristics


**Figure 1. On Resistance vs Junction Temperature**

**Figure 2. Shutdown Quiescent Current vs Input Voltage**

**Figure 3. Switching Frequency vs Junction Temperature**

**Figure 4. Voltage Reference vs Junction Temperature**

**Figure 5. Minimum Controllable On Time vs Junction Temperature**

**Figure 6. Minimum Controllable Duty Ratio vs Junction Temperature**

## Typical Characteristics (continued)

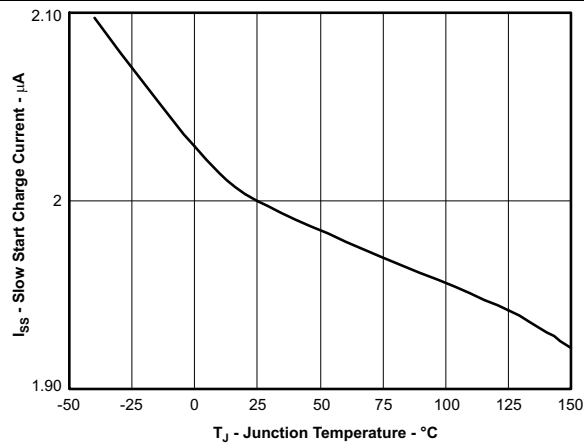


Figure 7. SS Charge Current vs Junction Temperature

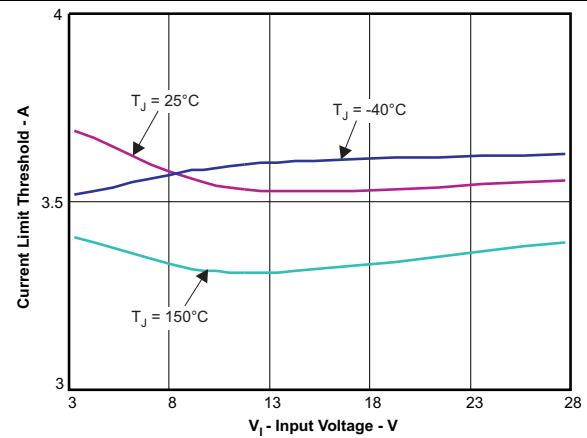


Figure 8. Current Limit Threshold vs Input Voltage

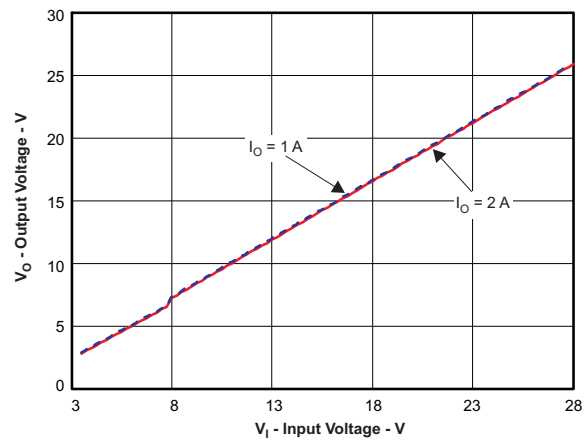


Figure 9. Typical Maximum Output Voltage vs Input Voltage

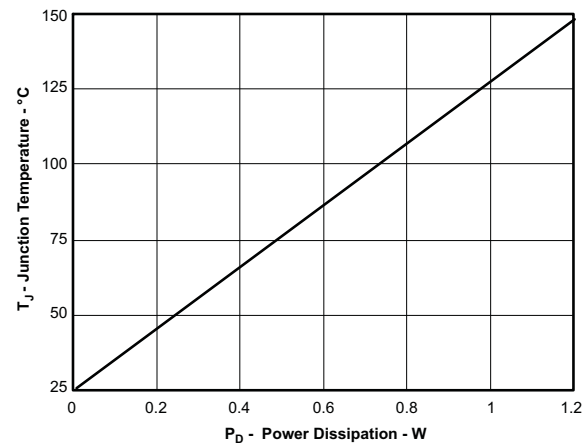


Figure 10. Maximum Power Dissipation vs Junction Temperature

## 8 Detailed Description

### 8.1 Overview

The TPS54233 is a 28 V, 2 A, step-down (buck) converter with an integrated high-side n-channel MOSFET. To improve performance during line and load transients, the device implements a constant frequency, current mode control which reduces output capacitance and simplifies external frequency compensation design. The TPS54233 has a pre-set switching frequency of 300 kHz.

The TPS54233 needs a minimum input voltage of 3.5 V to operate normally. The EN pin has an internal pull-up current source that can be used to adjust the input voltage under-voltage lockout (UVLO) with two external resistors. In addition, the pull-up current provides a default condition when the EN pin is floating for the device to operate. The operating current is 75  $\mu$ A typically when not switching and under no load. When the device is disabled, the supply current is 1  $\mu$ A typically.

The integrated 80 m $\Omega$  high-side MOSFET allows for high efficiency power supply designs with continuous output currents up to 2 A.

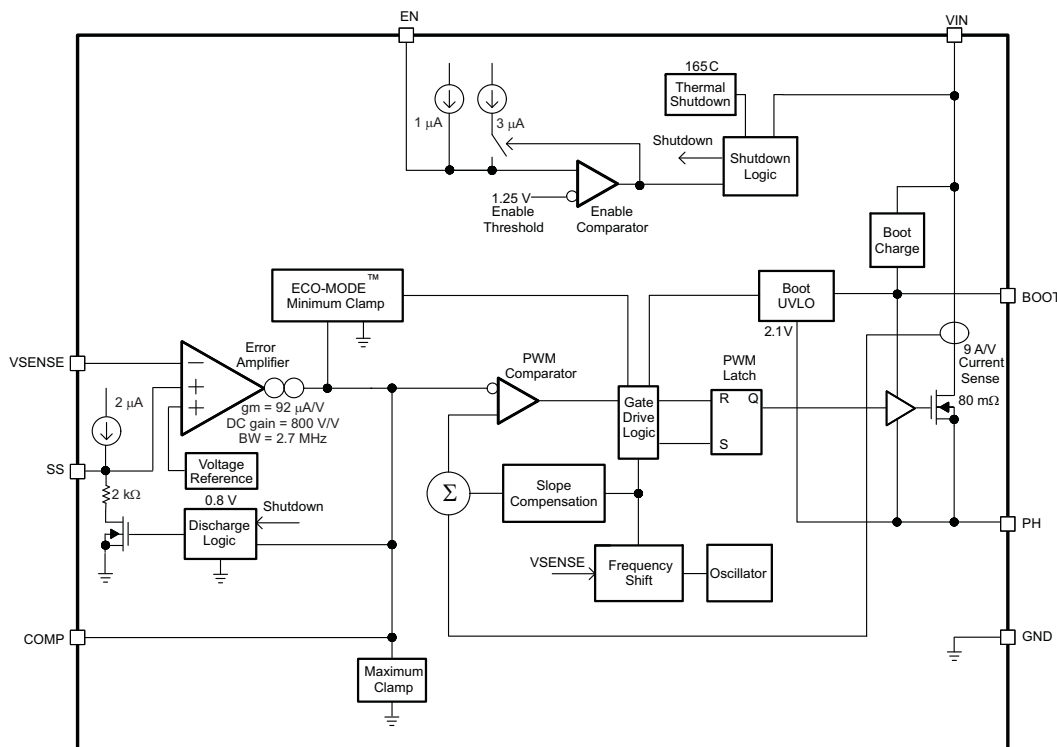
The TPS54233 reduces the external component count by integrating the boot recharge diode. The bias voltage for the integrated high-side MOSFET is supplied by an external capacitor on the BOOT to PH pin. The boot capacitor voltage is monitored by an UVLO circuit and will turn the high-side MOSFET off when the voltage falls below a preset threshold of 2.1 V typically. The output voltage can be stepped down to as low as the reference voltage.

By adding an external capacitor, the slow start time of the TPS54233 can be adjustable which enables flexible output filter selection.

To improve the efficiency at light load conditions, the TPS54233 enters a special pulse skipping Eco-mode™ when the peak inductor current drops below 100 mA typically.

The frequency foldback reduces the switching frequency during startup and over current conditions to help control the inductor current. The thermal shut down gives the additional protection under fault conditions.

### 8.2 Functional Block Diagram





## 8.3 Feature Description

### 8.3.1 Fixed Frequency PWM Control

The TPS54233 uses a fixed frequency, peak current mode control. The internal switching frequency of the TPS54233 is fixed at 300kHz.

### 8.3.2 Voltage Reference ( $V_{ref}$ )

The voltage reference system produces a  $\pm 2\%$  initial accuracy voltage reference ( $\pm 3.5\%$  over temperature) by scaling the output of a temperature stable bandgap circuit. The typical voltage reference is designed at 0.8V.

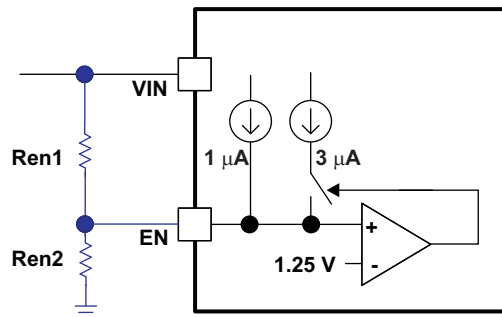
### 8.3.3 Bootstrap Voltage (BOOT)

The TPS54233 has an integrated boot regulator and requires a 0.1  $\mu\text{F}$  ceramic capacitor between the BOOT and PH pin to provide the gate drive voltage for the high-side MOSFET. A ceramic capacitor with an X7R or X5R grade dielectric is recommended because of the stable characteristics over temperature and voltage. To improve drop out, the TPS54233 is designed to operate at 100% duty cycle as long as the BOOT to PH pin voltage is greater than 2.1V typically.

### 8.3.4 Enable and Adjustable Input Under-Voltage Lockout (VIN UVLO)

The EN pin has an internal pull-up current source that provides the default condition of the TPS54233 operating when the EN pin floats.

The TPS54233 is disabled when the VIN pin voltage falls below internal VIN UVLO threshold. It is recommended to use an external VIN UVLO to add Hysteresis unless VIN is greater than ( $V_{OUT} + 2\text{V}$ ). To adjust the VIN UVLO with Hysteresis, use the external circuitry connected to the EN pin as shown in Figure 11. Once the EN pin voltage exceeds 1.25V, an additional 3  $\mu\text{A}$  of hysteresis is added. Use Equation 1 and Equation 2 to calculate the resistor values needed for the desired VIN UVLO threshold voltages. The  $V_{START}$  is the input start threshold voltage, the  $V_{STOP}$  is the input stop threshold voltage and the  $V_{EN}$  is the enable threshold voltage of 1.25 V. The  $V_{STOP}$  should always be greater than 3.5 V.



**Figure 11. Adjustable Input Undervoltage Lockout**

$$\text{Ren1} = \frac{V_{\text{START}} - V_{\text{STOP}}}{3 \mu\text{A}} \quad (1)$$

$$\text{Ren2} = \frac{V_{\text{EN}}}{\frac{V_{\text{START}} - V_{\text{EN}}}{\text{Ren1}} + 1 \mu\text{A}} \quad (2)$$

## Feature Description (continued)

### 8.3.5 Programmable Slow Start Using SS PIN

It is recommended to program the slow start time externally because no slow start time is implemented internally. The TPS54233 effectively uses the lower voltage of the internal voltage reference or the SS pin voltage as the power supply's reference voltage fed into the error amplifier and will regulate the output accordingly. A capacitor ( $C_{SS}$ ) on the SS pin to ground implements a slow start time. The TPS54233 has an internal pull-up current source of 2  $\mu$ A that charges the external slow start capacitor. The equation for the slow start time (10% to 90%) is shown in Equation 3. The  $V_{ref}$  is 0.8 V and the  $I_{SS}$  current is 2  $\mu$ A.

$$T_{SS} \text{ (ms)} = \frac{C_{SS} \text{ (nF)} \times V_{ref} \text{ (V)}}{I_{SS} \text{ (\mu A)}} \quad (3)$$

The slow start time should be set between 1ms to 10ms to ensure good start-up behavior. The slow start capacitor should be no more than 27 nF.

If during normal operation, the input voltage drops below the VIN UVLO threshold, or the EN pin is pulled below 1.25 V, or a thermal shutdown event occurs, the TPS54233 stops switching.

### 8.3.6 Error Amplifier

The TPS54233 has a transconductance amplifier for the error amplifier. The error amplifier compares the VSENSE voltage to the internal effective voltage reference presented at the input of the error amplifier. The transconductance of the error amplifier is 92  $\mu$ A/V during normal operation. Frequency compensation components are connected between the COMP pin and ground.

### 8.3.7 Slope Compensation

To prevent the sub-harmonic oscillations when operating the device at duty cycles greater than 50%, the TPS54233 adds a built-in slope compensation which is a compensating ramp to the switch current signal.

### 8.3.8 Current Mode Compensation Design

To simplify design efforts using the TPS54233, the typical designs for common applications are listed in Table 1. For designs using ceramic output capacitors, proper derating of ceramic output capacitance is recommended when doing the stability analysis. This is because the actual ceramic capacitance drops considerably from the nominal value when the applied voltage increases. See the [Detailed Design Procedure](#) section for the detailed guidelines or use the WEBENCH Software tool ([www.TI.com/WEBENCH](http://www.TI.com/WEBENCH)).

**Table 1. Typical Designs (Refer to [Section 4: Simplified Schematic](#))**

VIN (V)	VOUT (V)	F <sub>sw</sub> (kHz)	L <sub>O</sub> ( $\mu$ H)	C <sub>O</sub>	R5 (k $\Omega$ )	R6 (k $\Omega$ )	C7 (pF)	C6 (pF)	R3 (k $\Omega$ )
12	5	300	22	Ceramic 47 $\mu$ F	10	1.91	68	1800	21
12	3.3	300	15	Ceramic 47 $\mu$ F	10.2	3.24	47	4700	21
12	1.8	300	10	Ceramic 100 $\mu$ F x 2	10	8.06	100	4700	21
12	0.9	300	6.8	Ceramic 100 $\mu$ Fx2	10	80.6	100	4700	21
12	5	300	22	Aluminum 330 $\mu$ F/160 m $\Omega$	10	1.91	56	220	40.2
12	3.3	300	15	Aluminum 470 $\mu$ F/160 m $\Omega$	10.2	3.24	220	220	30.9
12	1.8	300	10	SP 220 $\mu$ F/12 m $\Omega$	10	8.06	100	4700	40.2
12	0.9	300	6.8	SP 220 $\mu$ F/12 m $\Omega$	10	80.6	100	1800	21

### 8.3.9 Overcurrent Protection and Frequency Shift

The TPS54233 implements current mode control that uses the COMP pin voltage to turn off the high-side MOSFET on a cycle by cycle basis. Every cycle the switch current and the COMP pin voltage are compared; when the peak inductor current intersects the COMP pin voltage, the high-side switch is turned off. During overcurrent conditions that pull the output voltage low, the error amplifier responds by driving the COMP pin high, causing the switch current to increase. The COMP pin has a maximum clamp internally, which limit the output current.

The TPS54233 provides robust protection during short circuits. There is potential for overcurrent runaway in the output inductor during a short circuit at the output. The TPS54233 solves this issue by increasing the off time during short circuit conditions by lowering the switching frequency. The switching frequency is divided by 8, 4, 2, and 1 as the voltage ramps from 0 V to 0.8 V on VSENSE pin. The relationship between the switching frequency and the VSENSE pin voltage is shown in [Table 2](#).

**Table 2. Switching Frequency Conditions**

SWITCHING FREQUENCY	VSENSE PIN VOLTAGE
300 kHz	$V_{SENSE} \geq 0.6 \text{ V}$
300 kHz / 2	$0.6 \text{ V} > V_{SENSE} \geq 0.4 \text{ V}$
300 kHz / 4	$0.4 \text{ V} > V_{SENSE} \geq 0.2 \text{ V}$
300 kHz / 8	$0.2 \text{ V} > V_{SENSE}$

### 8.3.10 Overvoltage Transient Protection

The TPS54233 incorporates an overvoltage transient protection (OVTP) circuit to minimize output voltage overshoot when recovering from output fault conditions or strong unload transients. The OVTP circuit includes an overvoltage comparator to compare the VSENSE pin voltage and internal thresholds. When the VSENSE pin voltage goes above  $109\% \times V_{ref}$ , the high-side MOSFET will be forced off. When the VSENSE pin voltage falls below  $107\% \times V_{ref}$ , the high-side MOSFET will be enabled again.

### 8.3.11 Thermal Shutdown

The device implements an internal thermal shutdown to protect itself if the junction temperature exceeds 165°C. The thermal shutdown forces the device to stop switching when the junction temperature exceeds the thermal trip threshold. Once the die temperature decreases below 165°C, the device reinitiates the power up sequence.

## 8.4 Device Functional Modes

### 8.4.1 Eco-mode™

The TPS54233 is designed to operate in pulse skipping Eco-mode™ at light load currents to boost light load efficiency. When the peak inductor current is lower than 100 mA typically, the COMP pin voltage falls to 0.5V typically and the device enters Eco-mode™. When the device is in Eco-mode™, the COMP pin voltage is clamped at 0.5V internally which prevents the high side integrated MOSFET from switching. The peak inductor current must rise above 100mA for the COMP pin voltage to rise above 0.5V and exit Eco-mode™. Since the integrated current comparator catches the peak inductor current only, the average load current entering Eco-mode™ varies with the applications and external output filters.

## 9 Application and Implementation

### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 9.1 Application Information

The TPS54233 device is typically used as a step-down converter, which converts a voltage from 3.5 V to 28 V to a lower voltage. WEBENCH software is available to aid in the design and analysis of circuits.

For additional design needs, see the following devices.

	TPS54231	TPS54232	TPS54233	TPS54331	TPS54332
I <sub>O</sub> (Max)	2A	2A	2A	3A	3.5A
Input Voltage Range	3.5V - 28V	3.5V - 28V	3.5V - 28V	3.5V - 28V	3.5V - 28V
Switching Freq. (Typ)	570kHz	1000kHz	285kHz	570kHz	1000kHz
Switch Current Limit (Min)	2.3A	2.3A	2.3A	3.5A	4.2A
Pin/Package	8SOIC	8SOIC	8SOIC	8SOIC	8SO PowerPAD™

### 9.2 Typical Application

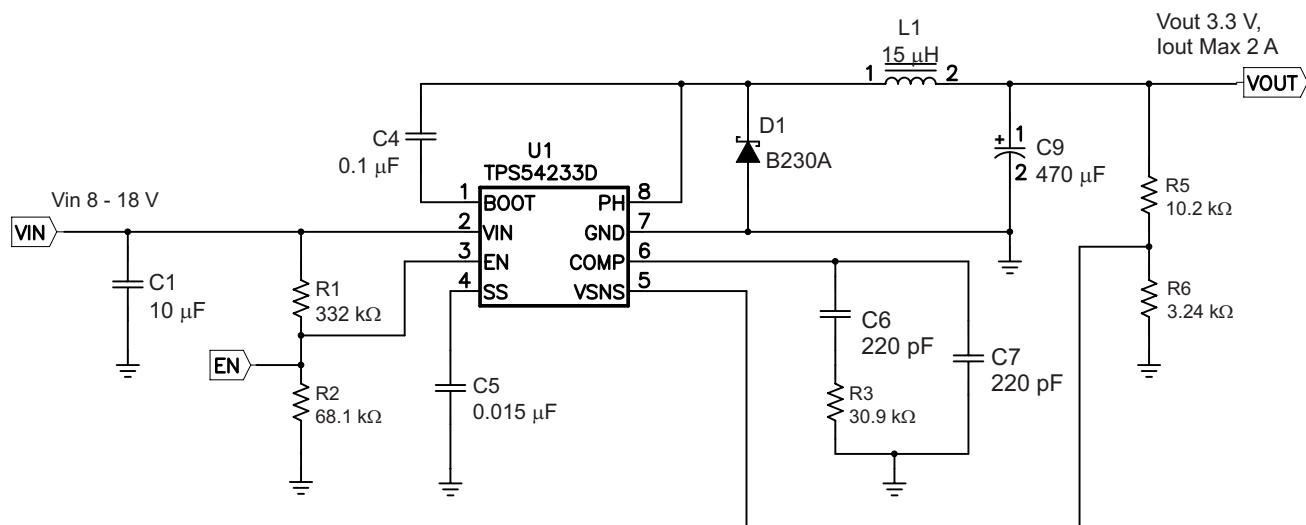


Figure 12. Typical Application Schematic

#### 9.2.1 Design Requirements

For this design example, use the input parameters in Table 3.

Table 3. Design Parameters

DESIGN PARAMETER	EXAMPLE VALUE
Input voltage range	8 V to 18 V
Output voltage	3.3 V
Input ripple voltage	300 mV
Output ripple voltage	100 mV
Output current rating	2 A
Operating Frequency	300 kHz

## 9.2.2 Detailed Design Procedure

The following design procedure can be used to select component values for the TPS54233. Alternately, the WEBENCH Software can be used to generate a complete design. The WEBENCH Software uses an iterative design procedure and accesses a comprehensive database of components when generating a design. This section presents a simplified discussion of the design process.

### 9.2.2.1 Switching Frequency

The switching frequency for the TPS54233 is fixed at 300 kHz.

### 9.2.2.2 Output Voltage Set Point

The output voltage of the TPS54233 is externally adjustable using a resistor divider network. In the application circuit of [Figure 12](#), this divider network is comprised of R5 and R6. The relationship of the output voltage to the resistor divider is given by [Equation 4](#) and [Equation 5](#):

$$R6 = \frac{R5 \times V_{REF}}{V_{OUT} - V_{REF}} \quad (4)$$

$$V_{OUT} = V_{REF} \times \left[ \frac{R5}{R6} + 1 \right] \quad (5)$$

Choose R5 to be approximately 10 kΩ. Slightly increasing or decreasing R5 can result in closer output voltage matching when using standard value resistors. In this design, R5 = 10.2 kΩ and R6 = 3.24 kΩ, resulting in a 3.31 V output voltage.

### 9.2.2.3 Input Capacitors

The TPS54233 requires an input decoupling capacitor and depending on the application, a bulk input capacitor. The typical recommended value for the decoupling capacitor is 10 μF. A high-quality ceramic type X5R or X7R is recommended. The voltage rating should be greater than the maximum input voltage. A smaller value may be used as long as all other requirements are met; however 10 μF has been shown to work well in a wide variety of circuits. Additionally, some bulk capacitance may be needed, especially if the TPS54233 circuit is not located within about 2 inches from the input voltage source. The value for this capacitor is not critical but should be rated to handle the maximum input voltage including ripple voltage, and should filter the output so that input ripple voltage is acceptable. For this design two 4.7 μF capacitors are used for the input decoupling capacitor. They are X7R dielectric rated for 50 V. The equivalent series resistance (ESR) is approximately 2 mΩ, and the current rating is 3 A. Additionally, a small 0.01 μF capacitor is included for high frequency filtering.

This input ripple voltage can be approximated by [Equation 6](#)

$$\Delta V_{IN} = \frac{I_{OUT(MAX)} \times 0.25}{C_{BULK} \times f_{SW}} + (I_{OUT(MAX)} \times ESR_{MAX}) \quad (6)$$

Where  $I_{OUT(MAX)}$  is the maximum load current,  $f_{SW}$  is the switching frequency,  $C_{BULK}$  is the bulk capacitor value and  $ESR_{MAX}$  is the maximum series resistance of the bulk capacitor.

The maximum RMS ripple current also needs to be checked. For worst case conditions, this can be approximated by [Equation 7](#)

$$I_{CIN} = \frac{I_{OUT(MAX)}}{2} \quad (7)$$

In this case, the input ripple voltage would be 143 mV and the RMS ripple current would be 1.5 A. It is also important to note that the actual input voltage ripple will be greatly affected by parasitics associated with the layout and the output impedance of the voltage source. The actual input voltage ripple for this circuit is shown in [Design Parameters](#) and is larger than the calculated value. This measured value is still below the specified input limit of 300 mV. The maximum voltage across the input capacitors would be  $V_{IN\ max} + \Delta V_{IN}/2$ . The chosen bulk and bypass capacitors are each rated for 50 V and the ripple current capacity is greater than 3 A, both providing ample margin. It is important that the maximum ratings for voltage and current are not exceeded under any circumstance.

### 9.2.2.4 Output Filter Components

Two components need to be selected for the output filter, L1 and C9. Since the TPS54233 is an externally compensated device, a wide range of filter component types and values can be supported.

#### 9.2.2.4.1 Inductor Selection

To calculate the minimum value of the output inductor, use [Equation 8](#)

$$L_{\text{MIN}} = \frac{V_{\text{OUT(MAX)}} \times (V_{\text{IN(MAX)}} - V_{\text{OUT}})}{V_{\text{IN(MAX)}} \times K_{\text{IND}} \times I_{\text{OUT}} \times F_{\text{SW}}} \quad (8)$$

$K_{\text{IND}}$  is a coefficient that represents the amount of inductor ripple current relative to the maximum output current. This value is at the discretion of the designer; however, the following guidelines may be used. For designs using low ESR output capacitors such as ceramics, a value as high as  $K_{\text{IND}} = 0.3$  may be used. When using higher ESR output capacitors,  $K_{\text{IND}} = 0.2$  yields better results.

For this design example, use  $K_{\text{IND}} = 0.3$  and the minimum inductor value is calculated to be 14.97µH. For this design, the closest value 15µH was chosen.

For the output filter inductor, it is important that the RMS current and saturation current ratings not be exceeded. The RMS inductor current can be found from [Equation 9](#)

$$I_{\text{L(RMS)}} = \sqrt{I_{\text{OUT(MAX)}}^2 + \frac{1}{12} \times \left( \frac{V_{\text{OUT}} \times (V_{\text{IN(MAX)}} - V_{\text{OUT}})}{V_{\text{IN(MAX)}} \times L_{\text{OUT}} \times F_{\text{SW}} \times 0.7} \right)^2} \quad (9)$$

and the peak inductor current can be determined with [Equation 10](#)

$$I_{\text{L(PK)}} = I_{\text{OUT(MAX)}} + \frac{V_{\text{OUT}} \times (V_{\text{IN(MAX)}} - V_{\text{OUT}})}{1.4 \times V_{\text{IN(MAX)}} \times L_{\text{OUT}} \times F_{\text{SW}}} \quad (10)$$

For this design, the RMS inductor current is 2.02 A and the peak inductor current is 2.43 A. The chosen inductor is a Coilcraft MSS1038-153ML 15 µH. It has a saturation current rating of 3.86 A and an RMS current rating of 3.8 A, meeting these requirements. Smaller or larger inductor values can be used depending on the amount of ripple current the designer wishes to allow so long as the other design requirements are met. Larger value inductors will have lower ac current and result in lower output voltage ripple, while smaller inductor values will increase ac current and output voltage ripple. Inductor values for use with the TPS54233 are in the range of 6.8 µH to 47 µH.

#### 9.2.2.4.2 Capacitor Selection

The important design factors for the output capacitor are dc voltage rating, ripple current rating, and equivalent series resistance (ESR). The dc voltage and ripple current ratings cannot be exceeded. The ESR is important because along with the inductor current it determines the amount of output ripple voltage. The actual value of the output capacitor is not critical, but some practical limits do exist. Consider the relationship between the desired closed loop crossover frequency of the design and LC corner frequency of the output filter. In general, it is desirable to keep the closed loop crossover frequency at less than 1/5 of the switching frequency. With high switching frequencies such as the 300 kHz frequency of this design, internal circuit limitations of the TPS54233 limit the practical maximum crossover frequency to about 25 kHz. In general, the closed loop crossover frequency should be higher than the corner frequency determined by the load impedance and the output capacitor. This limits the minimum capacitor value for the output filter to:

$$C_{O\_min} = 1 / (2 \times \pi \times R_O \times F_{CO\_max}) \quad (11)$$

Where  $R_O$  is the output load impedance ( $V_O/I_O$ ) and  $f_{CO}$  is the desired crossover frequency. For a desired maximum crossover of 25 kHz the minimum value for the output capacitor is around 3.8µF. This may not satisfy the output ripple voltage requirement. The output ripple voltage consists of two components; the voltage change due to the charge and discharge of the output filter capacitance and the voltage change due to the ripple current times the ESR of the output filter capacitor. The output ripple voltage can be estimated by:

$$V_{OPP} = I_{LPP} \left[ \frac{(D - 0.5)}{4 \times F_{SW} \times C_O} + R_{ESR} \right] \quad (12)$$

Where  $N_C$  is the number of output capacitors in parallel.

The maximum ESR of the output capacitor is determined by the amount of allowable output ripple as specified in the initial design parameters; so the maximum specified ESR as listed in the capacitor data sheet is given by [Equation 13](#):

$$ESR_{max} = \frac{V_{OPPMAX}}{I_{LPP}} - \frac{(D - 0.5)}{4 \times F_{SW} \times C_O} \quad (13)$$

Where  $\Delta V_{p-p}$  is the desired peak-to-peak output ripple.

To meet the 100 mV p-p ripple requirement, a single 470  $\mu$ F aluminum electrolytic output capacitor is chosen for C9. This is a Panasonic, EEVFK1A471P rated at 10 V with a maximum ESR of 160 m $\Omega$  and a ripple current rating of 600 mA.

The maximum RMS output ripple current can be calculated using [Equation 14](#)

$$I_{COUT(RMS)} = \frac{1}{\sqrt{12}} \times \left( \frac{V_{OUT} \times (V_{IN(MAX)} - V_{OUT})}{V_{IN(MAX)} \times L_{OUT} \times F_{SW} \times N_C} \right) \quad (14)$$

The calculated total RMS ripple current is 216 mA and the maximum total ESR required is 43 m $\Omega$ . These output capacitors exceed the requirements by a wide margin and will result in a reliable, high-performance design. The selected output capacitor must be rated for a voltage greater than the desired output voltage plus = the ripple voltage. Any derating amount must also be included.

Other capacitor types work well with the TPS54233, depending on the needs of the application.

### 9.2.2.5 Compensation Components

The external compensation used with the TPS54233 allows for a wide range of output filter configurations. A large range of capacitor values and types of dielectric are supported. The design example uses ceramic X5R dielectric output capacitors, but other types are supported.

A Type II compensation scheme is recommended for the TPS54233. The compensation components are chosen to set the desired closed loop cross over frequency and phase margin for output filter components. The type II compensation has the following characteristics; a dc gain component, a low frequency pole, and a mid frequency zero / pole pair.

The dc gain is determined by [Equation 15](#):

$$G_{DC} = \frac{V_{ggm} \times V_{REF}}{V_O} \quad (15)$$

Where:

$$\begin{aligned} V_{ggm} &= 800 \\ V_{REF} &= 0.8 \text{ V} \end{aligned}$$

The low-frequency pole is determined by [Equation 16](#):

$$V_{PO} = 1/(2 \times \pi \times R_{OO} \times C_Z) \quad (16)$$

The mid-frequency zero is determined by [Equation 17](#):

$$F_{Z1} = 1/(2 \times \pi \times R_Z \times C_Z) \quad (17)$$

And, the mid-frequency pole is given by [Equation 18](#):

$$F_{P1} = 1/(2 \times \pi \times R_Z \times C_P) \quad (18)$$



The first step is to choose the closed loop crossover frequency. In general, the closed-loop crossover frequency should be less than 1/8 of the minimum operating frequency, but for the TPS54233 it is recommended that the maximum closed loop crossover frequency be not greater than 25 kHz. Next, the required gain and phase boost of the crossover network needs to be calculated. By definition, the gain of the compensation network must be the inverse of the gain of the modulator and output filter. For this design example, where the ESR zero is less than the closed loop crossover frequency, the gain of the modulator and output filter can be approximated by [Equation 19](#):

$$\text{Gain} = 20 \log \left( \frac{R_O}{R_{\text{SENSE}}} \right) - 20 \log \left( \frac{R_O}{R_{\text{ESR}}} \right) \quad (19)$$

Where:

$$R_{\text{SENSE}} = 1\Omega/9$$

$$R_O = V_O/I_O$$

$$R_{\text{ESR}} = \text{Equivalent series resistance of the output capacitor}$$

The phase loss is given by [Equation 20](#):

$$PL = a \tan(2 \times \pi \times F_{\text{CO}} \times R_{\text{ESR}} \times C_O) - a \tan(2 \times \pi \times F_{\text{CO}} \times R_O \times C_O) \quad (20)$$

Where:

$$R_{\text{ESR}} = \text{Equivalent series resistance of the output capacitor}$$

$$R_O = V_O/I_O$$

Now that the phase loss is known the required amount of phase boost to meet the phase margin requirement can be determined. The required phase boost is given by [Equation 21](#):

$$PB = (PM - 90 \text{ deg}) - PL \quad (21)$$

Where PM = the desired phase margin.

A zero / pole pair of the compensation network will be placed symmetrically around the intended closed loop frequency to provide maximum phase boost at the crossover point. The amount of separation can be determined by [Equation 22](#) and the resultant zero and pole frequencies are given by [Equation 23](#) and [Equation 24](#)

$$k = \tan \left( \frac{PB}{2} + 45 \text{ deg} \right) \quad (22)$$

$$F_{Z1} = \frac{F_{CO}}{k} \quad (23)$$

$$F_{P1} = F_{CO} \times k \quad (24)$$

The low-frequency pole is set so that the gain at the crossover frequency is equal to the inverse of the gain of the modulator and output filter. Due to the relationships established by the pole and zero relationships, the value of  $R_Z$  can be derived directly by [Equation 25](#) :

$$R_Z = \frac{V_O \times R_{OA} \times 0.98}{GM_{\text{COMP}} \times V_{\text{gsm}} \times V_{\text{REF}} \times R_{\text{ESR}}} \quad (25)$$

Where:

$$V_O = \text{Output voltage}$$

$$R_{OA} = 8.696 \text{ M}\Omega$$

$$GM_{\text{COMP}} = 9 \text{ A/V}$$

$$V_{\text{gsm}} = 800$$

$$V_{\text{REF}} = 0.8 \text{ V}$$

$$R_{\text{ESR}} = \text{Equivalent series resistance of the output capacitor}$$

With  $R_Z$  known,  $C_Z$  and  $C_P$  can be calculated using [Equation 26](#) and [Equation 27](#):



$$C_z = \frac{1}{2 \times \pi \times F_{Z1} \times R_z} \quad (26)$$

$$C_p = \frac{1}{2 \times \pi \times F_{P1} \times R_z} \quad (27)$$

For this design, a single 470  $\mu$ F output capacitor is used. The ESR is approximately .160  $\Omega$ . The desired closed loop crossover frequency is 22000 Hz.

Using Equation 19 and Equation 20, the output stage gain and phase loss are equivalent as:

Gain = -3.114 dB

and

PL = -4.96 degrees

For 60 degrees of phase margin, Equation 21 requires no additional phase boost, so K can be set equal to 1.

Equation 22, Equation 23, and Equation 24 are used to find the zero and pole frequencies of:

$F_{Z1} = 22000$  Hz

And

$F_{P1} = 22000$  Hz

$R_z$ ,  $C_z$ , and  $C_p$  are calculated using Equation 25, Equation 26, and Equation 27:

$$R_z = \frac{2.5 \times 8.696 \times 10^6 \times 0.98}{9 \times 800 \times 0.8 \times 0.160} = 30.5 \text{ k}\Omega \quad (28)$$

$$C_z = \frac{1}{2 \times \pi \times 22000 \times 30500} = 237 \text{ pF} \quad (29)$$

$$C_p = \frac{1}{2 \times \pi \times 22000 \times 30500} = 237 \text{ pF} \quad (30)$$

Using standard values for  $R_3$ ,  $C_6$ , and  $C_7$  in the application schematic of Figure 12:

$R_3 = 30.9 \text{ k}\Omega$

$C_6 = 220 \text{ pF}$

$C_7 = 220 \text{ pF}$

The measured overall loop response for the circuit is given in Figure 12. Note that the actual closed loop crossover frequency is higher than intended at about 25 kHz. This is primarily due to variation in the actual values of the output filter components and tolerance variation of the internal feed-forward gain circuitry. Overall the design has greater than 60 degrees of phase margin and will be completely stable over all combinations of line and load variability.

#### 9.2.2.6 Bootstrap Capacitor

Every TPS54233 design requires a bootstrap capacitor,  $C_4$ . The bootstrap capacitor must be 0.1  $\mu$ F. The bootstrap capacitor is located between the PH pins and BOOT pin. The bootstrap capacitor should be a high-quality ceramic type with X7R or X5R grade dielectric for temperature stability.

### 9.2.2.7 Catch Diode

The TPS54233 is designed to operate using an external catch diode between PH and GND. The selected diode must meet the absolute maximum ratings for the application: Reverse voltage must be higher than the maximum voltage at the PH pin, which is  $V_{INMAX} + 0.5$  V. Peak current must be greater than  $I_{OUTMAX}$  plus on half the peak to peak inductor current. Forward voltage drop should be small for higher efficiencies. It is important to note that the catch diode conduction time is typically longer than the high-side FET on time, so attention paid to diode parameters can make a marked improvement in overall efficiency. Additionally, check that the device chosen is capable of dissipating the power losses. For this design, a Diodes, Inc. B340A is chosen, with a reverse voltage of 40 V, forward current of 3 A, and a forward voltage drop of 0.5 V.

### 9.2.2.8 Output Voltage Limitations

Due to the internal design of the TPS54233, there are both upper and lower output voltage limits for any given input voltage. The upper limit of the output voltage set point is constrained by the maximum duty cycle of 91% and is given by [Equation 31](#):

$$V_{Omax} = 0.91 \times ((V_{INmin} - I_{Omax} \times R_{DS(on)max}) + V_D) - (I_{Omax} \times R_L) - V_D \quad (31)$$

Where:

- $V_{INmin}$  = Minimum input voltage
- $I_{Omax}$  = Maximum load current
- $V_D$  = Catch diode forward voltage
- $R_L$  = Output inductor series resistance

The equation assumes maximum on resistance for the internal high-side FET.

The lower limit is constrained by the minimum controllable on time which may be as high as 160 ns. The approximate minimum output voltage for a given input voltage and minimum load current is given by [Equation 32](#):

$$V_{Omin} = 0.051 \times ((V_{INmax} - I_{Omin} \times R_{in}) + V_D) - (I_{Omin} \times R_L) - V_D \quad (32)$$

Where:

- $V_{INmax}$  = Maximum input voltage
- $I_{Omin}$  = Minimum load current
- $V_D$  = Catch diode forward voltage
- $R_L$  = Output inductor series resistance

This equation assumes nominal on-resistance for the high-side FET and accounts for worst case variation of operating frequency set point. Any design operating near the operational limits of the device should be carefully checked to assure proper functionality.

### 9.2.2.9 Power Dissipation Estimate

The following formulas show how to estimate the device power dissipation under continuous conduction mode operations. They should not be used if the device is working in the discontinuous conduction mode (DCM) or pulse skipping Eco-mode™.

The device power dissipation includes:

- 1) Conduction loss:  $P_{con} = I_{OUT}^2 \times R_{DS(on)} \times V_{OUT}/V_{IN}$
- 2) Switching loss:  $P_{sw} = 0.5 \times 10^{-9} \times V_{IN}^2 \times I_{OUT} \times F_{sw}$
- 3) Gate charge loss:  $P_{gc} = 22.8 \times 10^{-9} \times F_{sw}$
- 4) Quiescent current loss:  $P_q = 0.075 \times 10^{-3} \times V_{IN}$

Where:

$I_{OUT}$  is the output current (A).

$R_{DS(on)}$  is the on-resistance of the high-side MOSFET ( $\Omega$ ).

$V_{OUT}$  is the output voltage (V).

$V_{IN}$  is the input voltage (V).

$F_{sw}$  is the switching frequency (Hz).

So

$$P_{tot} = P_{con} + P_{sw} + P_{gc} + P_q$$

For given  $T_A$ ,  $T_J = T_A + R_{th} \times P_{tot}$ .

For given  $T_{JMAX} = 150^\circ\text{C}$ ,  $T_{AMAX} = T_{JMAX} - R_{th} \times P_{tot}$ .

Where:

$P_{tot}$  is the total device power dissipation (W).

$T_A$  is the ambient temperature ( $^\circ\text{C}$ ).

$T_J$  is the junction temperature ( $^\circ\text{C}$ ).

$R_{th}$  is the thermal resistance of the package ( $^\circ\text{C}/\text{W}$ ).

$T_{JMAX}$  is maximum junction temperature ( $^\circ\text{C}$ ).

$T_{AMAX}$  is maximum ambient temperature ( $^\circ\text{C}$ ).

## 9.2.3 Application Curves

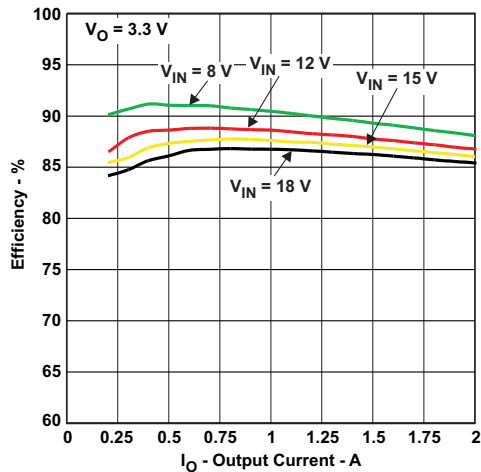


Figure 13. TPS54233 Efficiency

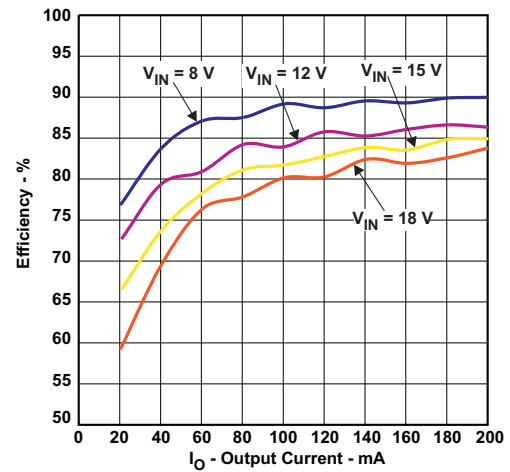


Figure 14. TPS54233 Low Current Efficiency

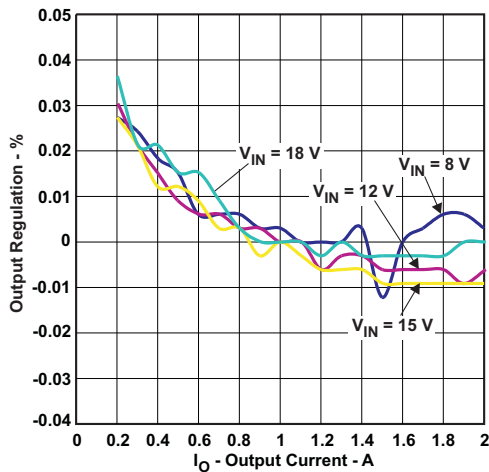


Figure 15. TPS54233 Load Regulation

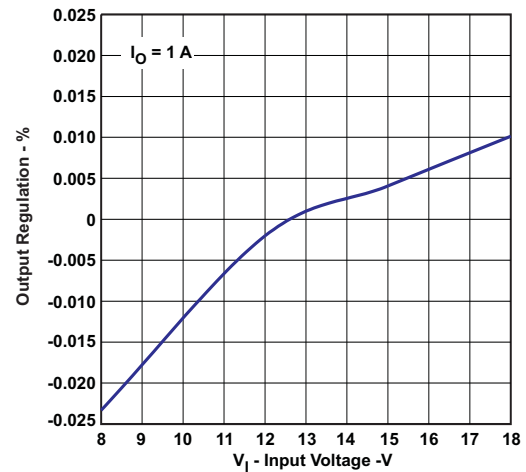


Figure 16. TPS54233 Line Regulation

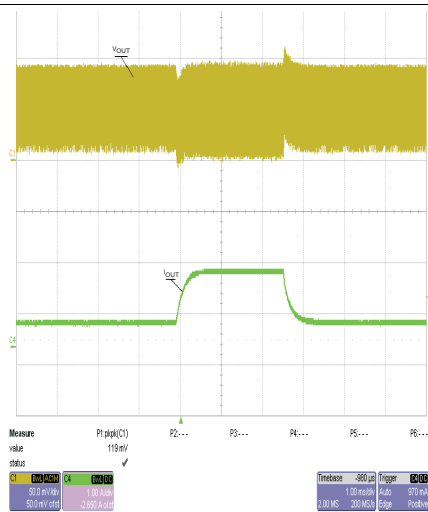


Figure 17. TPS54233 Transient Response

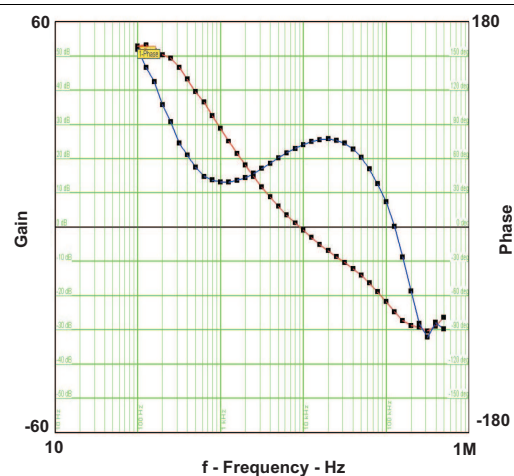
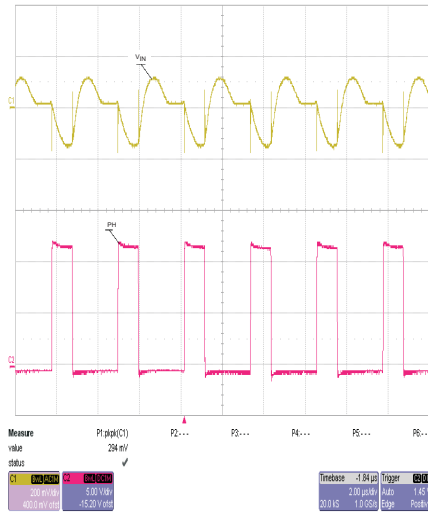
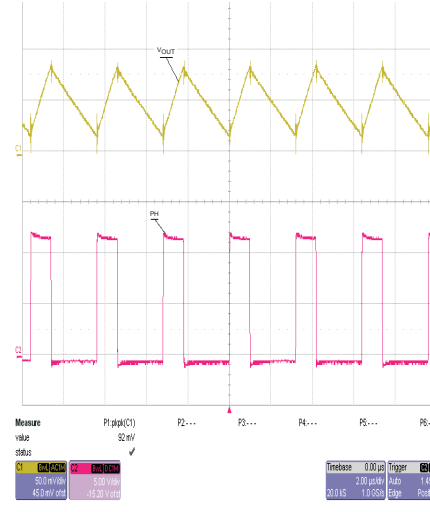


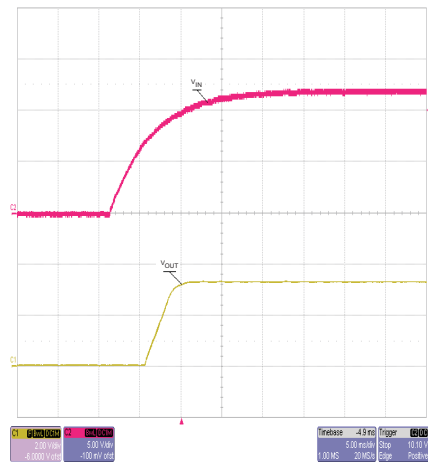
Figure 18. TPS54233 Loop Response



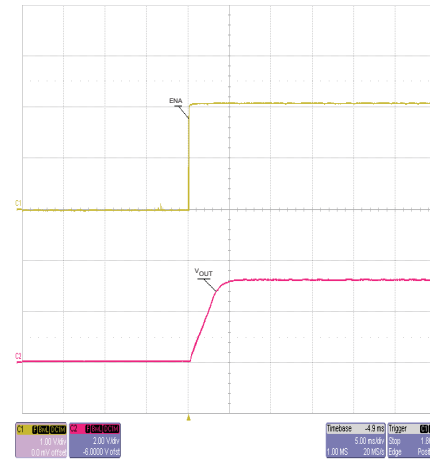
**Figure 19. TPS54233 Input Ripple**



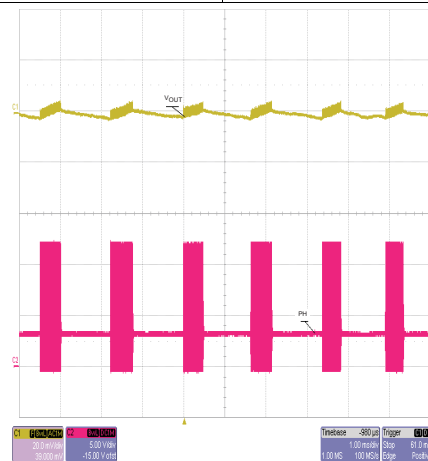
**Figure 20. TPS54233 Output Ripple**



**Figure 21. TPS54233 Start Up**



**Figure 22. TPS54233 Start-up Relative to Enable**



**Figure 23. TPS54233 Eco-mode™ Operation**

## 10 Power Supply Recommendations

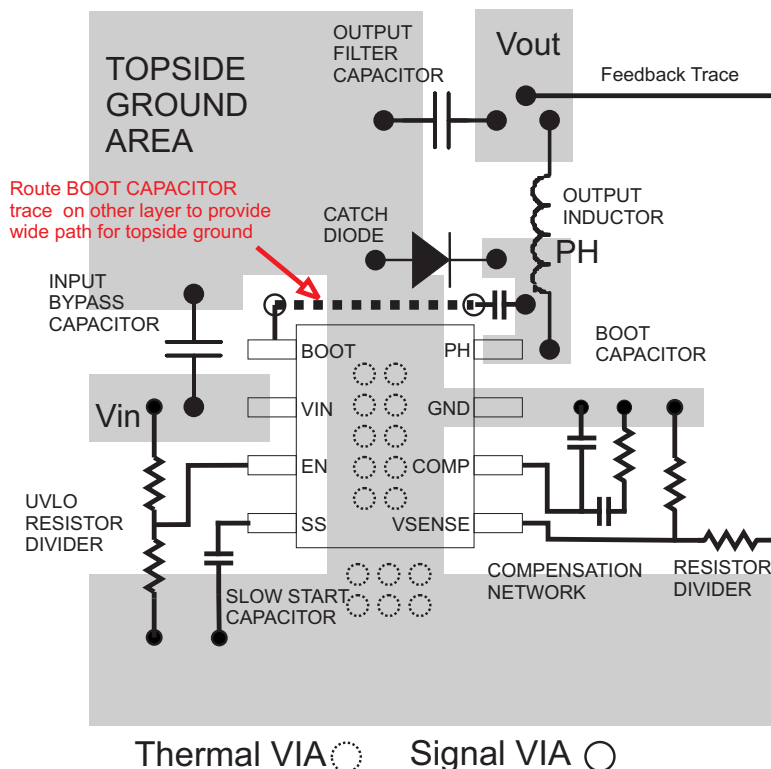
The device is designed to operate from an input-voltage supply range between 3.5 V and 28 V. This input supply should be well regulated. If the input supply is located more than a few inches from the converter additional bulk capacitance may be required in addition to the ceramic bypass capacitors. An electrolytic capacitor with a value of 100  $\mu\text{F}$  is a typical choice.

## 11 Layout

### 11.1 Layout Guidelines

The VIN pin should be bypassed to ground with a low ESR ceramic bypass capacitor. Care should be taken to minimize the loop area formed by the bypass capacitor connections, the VIN pin, and the anode of the catch diode. The typical recommended bypass capacitance is 10  $\mu\text{F}$  ceramic with a X5R or X7R dielectric and the optimum placement is closest to the VIN pins and the source of the anode of the catch diode. See Figure 24 for a PCB layout example. The GND D pin should be tied to the PCB ground plane at the pin of the IC. The source of the low-side MOSFET should be connected directly to the top side PCB ground area used to tie together the ground sides of the input and output capacitors as well as the anode of the catch diode. The PH pin should be routed to the cathode of the catch diode and to the output inductor. Since the PH connection is the switching node, the catch diode and output inductor should be located very close to the PH pins, and the area of the PCB conductor minimized to prevent excessive capacitive coupling. For operation at full rated load, the top side ground area must provide adequate heat dissipating area. The TPS54233 uses a fused lead frame so that the GND pin acts as a conductive path for heat dissipation from the die. Many applications have larger areas of internal or back side ground plane available, and the top side ground area can be connected to these areas using multiple vias under or adjacent to the device to help dissipate heat. The additional external components can be placed approximately as shown. It may be possible to obtain acceptable performance with alternate layout schemes, however this layout has been shown to produce good results and is intended as a guideline.

### 11.2 Layout Example



**Figure 24. TPS54233 Board Layout**

### 11.3 Estimated Circuit Area

The estimated printed circuit board area for the components used in the design of [Figure 12](#) is 0.72 in<sup>2</sup>. This area does not include test points or connectors.

### 11.4 Electromagnetic Interference (EMI) Considerations

As EMI becomes a rising concern in more and more applications, the internal design of the TPS54233 takes measures to reduce the EMI. The high-side MOSFET gate drive is designed to reduce the PH pin voltage ringing. The internal IC rails are isolated to decrease the noise sensitivity. A package bond wire scheme is used to lower the parasitics effects.

To achieve the best EMI performance, external component selection and board layout are equally important. Follow the [Detailed Design Procedure](#) above to prevent potential EMI issues.

## 12 Device and Documentation Support

### 12.1 Device Support

#### 12.1.1 Development Support

For the WEBENCH Software Tool, go to [www.TI.com/WEBENCH](http://www.TI.com/WEBENCH).

### 12.2 Trademarks

Eco-mode, PowerPAD are trademarks of Texas Instruments.  
WEBENCH is a registered trademark of Texas Instruments.  
All other trademarks are the property of their respective owners.

### 12.3 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### 12.4 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">TPS54233D</a>	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 150	54233
TPS54233D.A	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 150	54233
<a href="#">TPS54233DR</a>	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 150	54233
TPS54233DR.A	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 150	54233
TPS54233DRG4	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 150	54233

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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**OTHER QUALIFIED VERSIONS OF TPS54233 :**

- Automotive : [TPS54233-Q1](#)

NOTE: Qualified Version Definitions:

- Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS54233DR	SOIC	D	8	2500	330.0	12.5	6.4	5.2	2.1	8.0	12.0	Q1

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS54233DR	SOIC	D	8	2500	353.0	353.0	32.0

## TUBE



\*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
TPS54233D	D	SOIC	8	75	507	8	3940	4.32
TPS54233D.A	D	SOIC	8	75	507	8	3940	4.32

**D0008A****PACKAGE OUTLINE****SOIC - 1.75 mm max height**

SMALL OUTLINE INTEGRATED CIRCUIT



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**NOTES:**

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

# EXAMPLE BOARD LAYOUT

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



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NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

## EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE  
BASED ON .005 INCH [0.125 MM] THICK STENCIL  
SCALE:8X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.



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