

具有低于 1GHz 收发器和 3D 低频 (LF) 唤醒和应答器接口的 MSP430™ 系统级封装

特性

- 此系统级封装真正基于 MSP430™ 具有低于 1GHz 收发器片上系统 (SoC) 和额外的 3D LF 唤醒和应答器接口
- 宽电源电压范围：**3.6V 到低至 1.8V**
- 超低功耗
 - CPU 激活模式 (AM): **160µA/MHz**
 - 待机模式 (LPM3 实时时钟 (RTC) 模式): **2.0µA**
 - 关闭模式 (LPM4 RAM 保持): **1.0µA**
 - 接收射频: **15mA, 250kbps, 915MHz**
- MSP430 系统和外设
 - **16 位精简指令集 (RISC) 架构、扩展内存、高达 20MHz 的系统时钟**
 - 在少于 **6µs** 的时间内从待机模式中唤醒
 - 带有电源电压监视 (SVS) 和临时限电的灵活电源管理系统
 - 配有的锁频环 (FLL) 的统一系统时钟
 - 具有 5 个捕捉/比较寄存器的 **16 位定时器 TA0, Timer_A**
 - 具有 3 个捕获/比较寄存器的 **16 位定时器 TA1, Timer_A**
 - 硬件实时时钟
 - 2 个通用串行通信接口
 - **USCI_A0 支持通用异步收发器 (UART), 红外数据通讯接口 (IrDA), 串行外设接口 (SPI)**
 - **USCI_B0 支持 I²C™, SPI**
 - 带内部基准、采样与保持以及自动扫描特性的 **12 位 模数转换器**
 - 比较器
 - **128 位高级加密标准 (AES) 安全加密和解密协处理器**
 - **32 位硬件乘法器**
 - **3 通道内部直接内存访问 (DMA)**
 - 串行板上编程, 无需外部编程电压
 - 内嵌式仿真模块 (EEM)
- 高性能低于 1GHz 的射频 (RF) 收发器内核
 - 与 CC1101 中的内核一致
 - 宽电源电压范围: **2V 至 3.6V**
 - 频带范围: **300MHz 至 348MHz, 389MHz 至 464MHz, 和 779MHz 至 928MHz**
 - 从 **0.6 千波特率 (kbaud) 至 500 kbaud** 间的可编程数据传输速率
 - 高灵敏度 (**0.6kbaud** 时为 **-117dBm**, **1.2kbaud** 时为 **-111dBm**, **315 MHz, 1%数据包错误率**)
 - 出色的接收器可选择性和阻断性能
 - 对于所有支持的频率, 可编程输出功率高达 **+12dBm**
 - 支持 **2-频移键控 (FSK), 2-高斯频移键控 (GFSK) 和最小频移键控 (MSK)** 以及开关键控 (OOK) 和灵活振幅偏移键控 (ASK) 整形
 - 针对面向数据包系统的灵活支持: 用于同步字检测、地址检查、灵活数据包长度、和自动循环冗余校验码处理的片载支持
 - 支持传输前的自动空闲信道评估 (CCA) (针对对话前监听系统)
 - 接收到的信号强度指示器 (RSSI) 数字输出
 - 适合于符合 **EN 300 220** (欧洲) 和 **FCC CFR 部分 15** (美国) 标准的系统
 - 适合于符合无线 M 总线标准 **EN 13757-4:2005** 的系统
 - 为了向后兼容现有的无线电通信协议, 支持异步和同步串行接收和发射模式



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- 高性能低频 (LF) 接口
 - 3D 唤醒接收器
 - 低待机功耗: 4.4µA
 - 常规灵敏度模式: 3.7mVpp → 接近 3 米的唤醒范围
 - 高灵敏度模式: 0.5mVpp → 接近 6 米的唤醒范围
 - 低灵敏度变化
 - 数字已接收信号强度指示 (RSSI) 72dB, 8 位对数
 - 2 个独立的唤醒模式, 0 位至 24 位长度
 - 针对两个唤醒模式的专用灵敏度水平
 - 集成型 LF 比特流数据解码和数字数据输出
 - AES-128 硬件加密协处理器
 - 谐振频率: 134.2kHz
 - 针对所有 3 个谐振电路的嵌入式谐振调节
 - 3D 应答器接口
 - 应答器读取范围高达 4 英寸 (10cm), 由 LF RF 场供电
 - 半双工 (HDX) 通信协议
 - 可选查询/应答强度: 32/32, 64/64 或 96/64 位
 - 针对所有具有 32 位读取器签名的命令的相互认证
 - 突发读取模式
 - 防碰撞加密
 - 2048 字节的 EEPROM 存储器尺寸
 - 用户可用的 EEPROM 为 1776 字节
 - 加密密钥 4x 128 位
 - 针对可选访问授权的可配置页类型
 - 所有页可锁定 (不能再编程)
 - 具有多达 8 个输入的开关接口
- 如需了解完整的模块说明, 请参阅《RF430F5978 用户指南》()

说明

德州仪器 (TI) RF430F5978 系统级封装添加了一个 3D 低频 (LF) 唤醒和应答器接口, 此接口与具有集成型低于 1GHz RF 收发器的 CC430 超低功耗微控制器片上系统 (SoC) 对接。为了在整个系统内延长电池的使用寿命, 这个架构可在一个专用且定义良好的区域内允许器件激活和关闭。此嵌入式 LF 应答器接口即使在没有电池供电的情况下仍可工作, 并且通过其 128 位 AES 加密为查询/应答和相互认证提供最高级别的安全保护, 它还在系统中添加了 2kB 的可编程 EEPROM 存储器。

CC430 超低功耗微控制器片上系统 (SoC) 将 CC1101 低于 1GHz RF 收发器与功能强大的 16 位精简指令集计算机 (RISC) CPU 组合在一起。16 位寄存器和常数发生器以实现最大代码效率。它特有 MSP430 CPUXV2, 32kB 系统内可编程闪存存储器, 4kB RAM, 2 个 16 位定时器, 一个高性能 12 位 模数 (A/D) 转换器, 此转换器具有 6 个外部输入加上内部温度和电池传感器、比较器、通用串行通信接口 (USCI), 128 位 AES 安全加速器, 硬件乘法器, DMA, 支持闹铃功能的实时时钟模块。

RF430F5978 在微控制器内核、用于唤醒和应答器接口的外设、软件和集成型低于 1GHz RF 收发器和 3D LF 收发器之间提供一个紧密集成, 这使得这些解决方案在提升性能的同时易于使用。

这些器件的典型应用包括无线模拟和数字传感器系统、访问控制、资产跟踪和智能电网无线网络。

如需了解完整的模块说明, 请查阅《RF430F5978 系列用户指南》(文献编号: SLAU378)。

表 1. 系列产品

器件	程序 (KB)	SRAM (KB)	EEPROM (字节)	Timer_A ⁽¹⁾	LF 接口		USCI		ADC12_A ⁽²⁾ 通道	Comp_B 通道	I/O	封装类型
					应答器通道	唤醒接收器通道	通道 A: UART, IrDA, SPI	通道 B: SPI, I ² C				
RF430F5978	32	4	1776	5, 3	3	3	1	1	8 个外部通道, 4 个内部通道	8	27	64 RGC

- (1) 序列中的每个数代表 Timer_A 的一个示例，表示其可使用的捕获比较寄存器及脉宽调制 (PWM) 输出发生器的相关数量。例如：一个 (5, 3) 数列将代表 Timer_A 的两个示例，第一个示例和第二个示例分别具有 5 个捕获比较寄存器和 3 个 PWM 输出发生器。
- (2) n/a = 不可用

表 2. 订购信息⁽¹⁾

T _A	封装的器件 ⁽²⁾
	塑料 64 引脚四方扁平无引线封装 (QFN)(RGC)
-40°C 至 85°C	RF430F5978IRGC

- (1) 要获得最新的封装和订购信息，请参阅本文档末尾的封装选项附录，或者浏览 TI 网站 www.ti.com。
- (2) 封装图样、热数据和符号可从网站 www.ti.com/packaging 中获取。

FUNCTIONAL BLOCK DIAGRAM

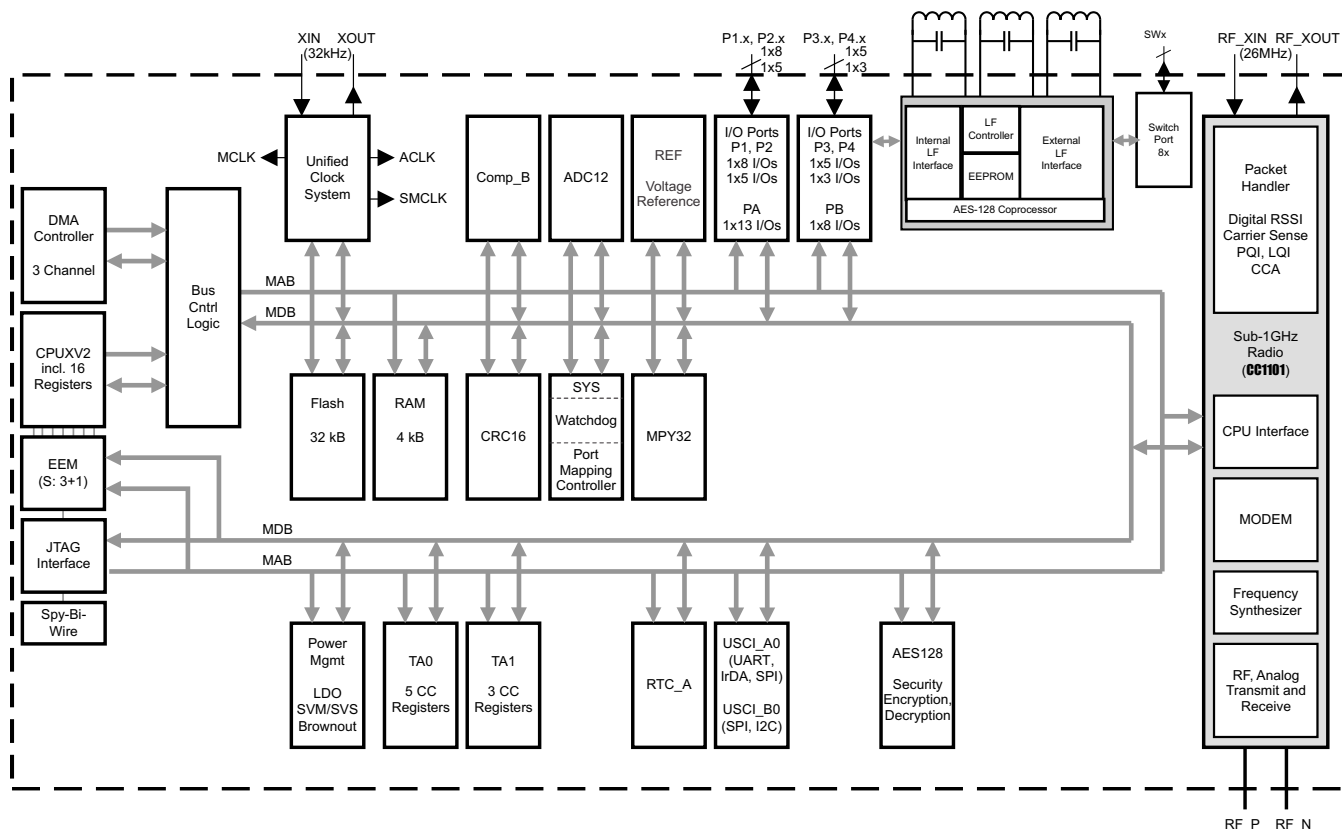
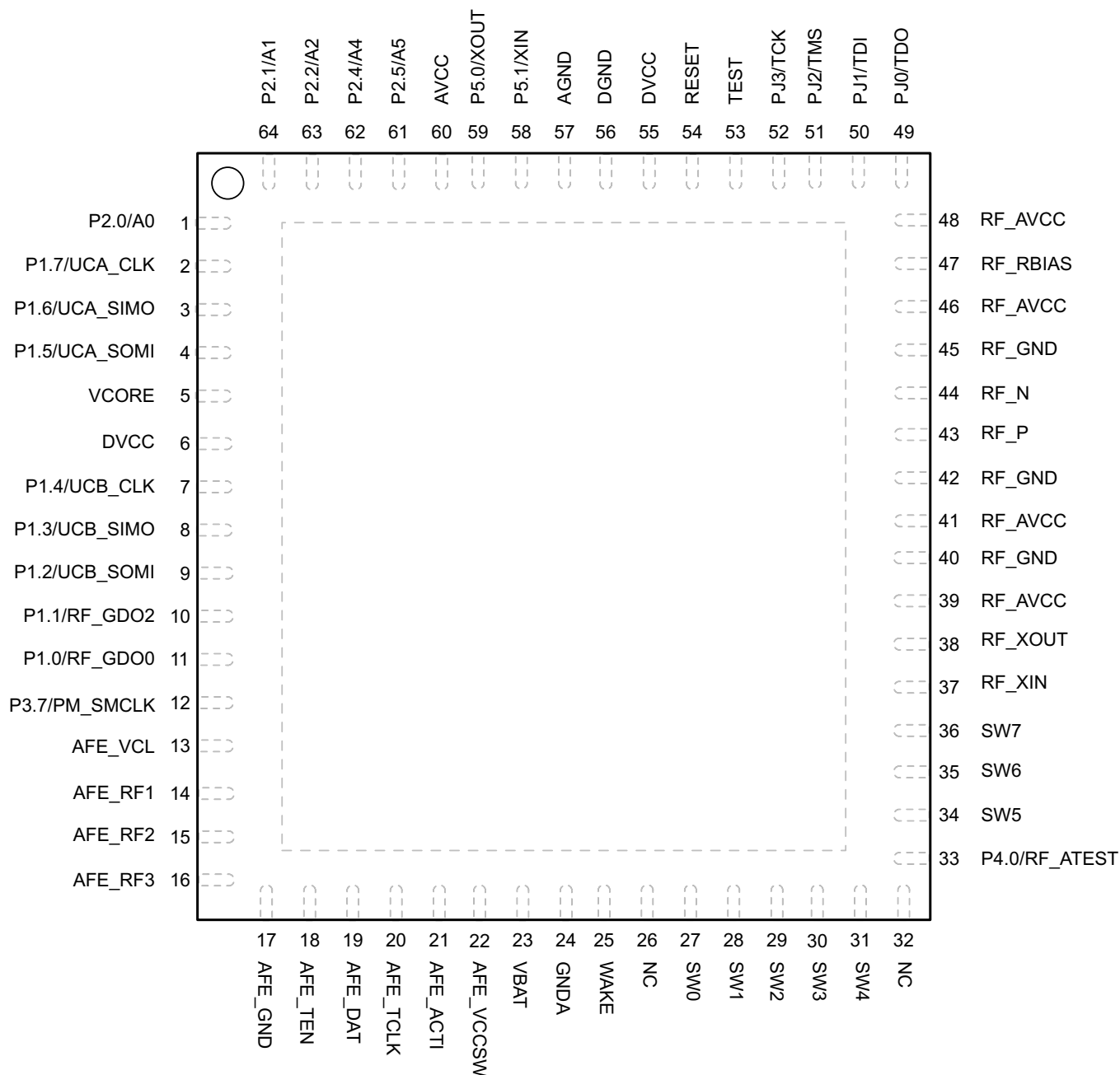


Figure 1. Functional Block Diagram

DEVICE PINOUT

**RGC PACKAGE
(TOP VIEW)**



The secondary digital functions on ports P1, P2, and P3 are fully mappable. This pinout shows the default mapping. See [Table 11](#) for details.

TERMINAL FUNCTIONS

Table 3. Terminal Functions

TERMINAL		I/O ⁽¹⁾	DESCRIPTION
NAME	NO.		
P2.0/PM_CBOUT1/PM_TA1CLK/ CB0/A0	1	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: Comparator_B output Default mapping: Timer1_A3 clock input Comparator input CB0 Analog input A0 – 12-bit ADC
P1.7/ PM_UCA0CLK/PM_UCB0STE	2	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: USCI_A0 clock input/output Default mapping: USCI_B0 SPI slave transmit enable
P1.6/ PM_UCA0TXD/PM_UCA0SIMO	3	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: USCI_A0 UART transmit data Default mapping: USCI_A0 SPI slave in master out
P1.5/ PM_UCA0RXD/PM_UCA0SOMI	4	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: USCI_A0 UART receive data Default mapping: USCI_A0 SPI slave out master in
VCORE	5	S	Regulated core power supply
DVCC	6	S	Digital power supply
P1.4/ PM_UCB0CLK/PM_UCA0STE	7	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: USCI_B0 clock input/output Default mapping: USCI_A0 SPI slave transmit enable
P1.3/ PM_UCB0SIMO/PM_UCB0SDA	8	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: USCI_B0 SPI slave in master out Default mapping: USCI_B0 I2C data
P1.2/ PM_UCB0SOMI/PM_UCB0SCL	9	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: USCI_B0 SPI slave out master in Default mapping: USCI_B0 I2C clock
P1.1/PM_RFGDO2	10	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: Radio GDO2 output
P1.0/PM_RFGDO0	11	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: Radio GDO0 output
P3.7/PM_SMCLK	12	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: SMCLK output
AFE_VCL	13	A	Charge capacitor and supply voltage for immobilizer mode
AFE_RF1	14	A	Connection for resonant circuit 1
AFE_RF2	15	A	Connection for resonant circuit 2
AFE_RF3	16	A	Connection for resonant circuit 3
AFE_GND	17		Analog LF front end GND
AFE_TEN	18	I	Test interface enable of analog LF front end
AFE_TDAT	19	I/O	Test interface data of analog LF front end
AFE_TCLK	20	I	Test interface clock of analog LF front end
AFE_ACTI	21	A	Test interface output of analog front end

(1) I = input, O = output, S = supply, G = ground

Table 3. Terminal Functions (continued)

TERMINAL		I/O ⁽¹⁾	DESCRIPTION
NAME	NO.		
AFE_VCCSW	22	A	Switched power supply buffer (external capacitor)
VBAT	23	S	Supply voltage analog front end
GNDA	24	G	Analog ground
WAKE	25	O	Analog ground
NC	26		Not connected
SW0	27	I	Switch input with internal pullup resistor
SW1	28	I	Switch input with internal pullup resistor
SW2	29	I	Switch input with internal pullup resistor
SW3	30	I	Switch input with internal pullup resistor
SW4	31	I	Switch input with internal pullup resistor
NC	32		Not connected
P4.0	33	I/O	General-purpose digital I/O
SW5	34	I	Switch input with internal pullup resistor
SW6	35	I	Switch input with internal pullup resistor
SW7	36	I	Switch input with internal pullup resistor
RF_XIN	37	I	Input terminal for RF crystal oscillator or external clock input
RF_XOUT	38	O	Output terminal for RF crystal oscillator
RF_AVCC	39	S	Radio analog power supply
RF_GND	40	G	Radio ground
RF_AVCC	41	S	Radio analog power supply
RF_GND	42	G	Radio ground
RF_P	43	RF I/O	Positive RF input to LNA in receive mode Positive RF output from PA in transmit mode
RF_N	44	RF I/O	Negative RF input to LNA in receive mode Negative RF output from PA in transmit mode
RF_GND	45	G	Radio ground
RF_AVCC	46	S	Radio analog power supply
RF_RBIAS	47		External bias resistor for radio reference current
RF_AVCC	48	I/O	Radio analog power supply
PJ.0/TDO	49	I/O	General-purpose digital I/O or test data output port
PJ.1/TDI/TCLK	50	I/O	General-purpose digital I/O or test data input or test clock input
PJ.2/TMS	51	I/O	General-purpose digital I/O or test mode select
PJ.3/TCK	52	I/O	General-purpose digital I/O or test clock
TEST/SBWTCK	53	I	Test mode pin – select digital I/O on JTAG pins or Spy-Bi-Wire input clock
$\overline{\text{RST}}$ /NMI/SBWDIO	54	I/O	Reset input active low Non-maskable interrupt input Spy-Bi-Wire data input/output
DVCC	55	S	Digital power supply
DGND	56	G	Digital ground supply

Table 3. Terminal Functions (continued)

TERMINAL		I/O ⁽¹⁾	DESCRIPTION
NAME	NO.		
AGND	57	G	Analog ground supply
P5.1/XOUT	58	I/O	General-purpose digital I/O Output terminal of crystal oscillator XT1
P5.0/XIN	59	I/O	General-purpose digital I/O Input terminal for crystal oscillator XT1
AVCC	60	S	Analog power supply
P2.5/PM_SVMOUT/CB5/A5/ VREF+/VeREF+	61	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: SVM output Comparator input CB5 Analog input A5 – ADC Output of positive reference voltage Input for an external positive reference voltage to the ADC
P2.4/PM_RTCCLK/CB4/A4/ VREF- /VeREF-	62	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: RTCCLK output Comparator input CB4 Analog input A4 – ADC Output of negative reference voltage Input for an external negative reference voltage to the ADC
P2.2/PM_TA1CCR1A/CB2/A2	63	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: TA1 CCR1 compare output/capture input Comparator input CB2 Analog input A2 – ADC
P2.1/PM_TA1CCR0A/CB1/A1	64	I/O	General-purpose digital I/O with port interrupt and mappable secondary function Default mapping: TA1 CCR0 compare output/capture input Comparator input CB1 Analog input A1 – ADC
Exposed die attach pad			Ground supply The exposed die attach pad must be connected to a solid ground plane as this is the ground connection for the chip.

SHORT-FORM DESCRIPTION

3D LF Wake-Up Receiver and 3D Transponder Interface

3D RFID Transponder Front End TMS37206

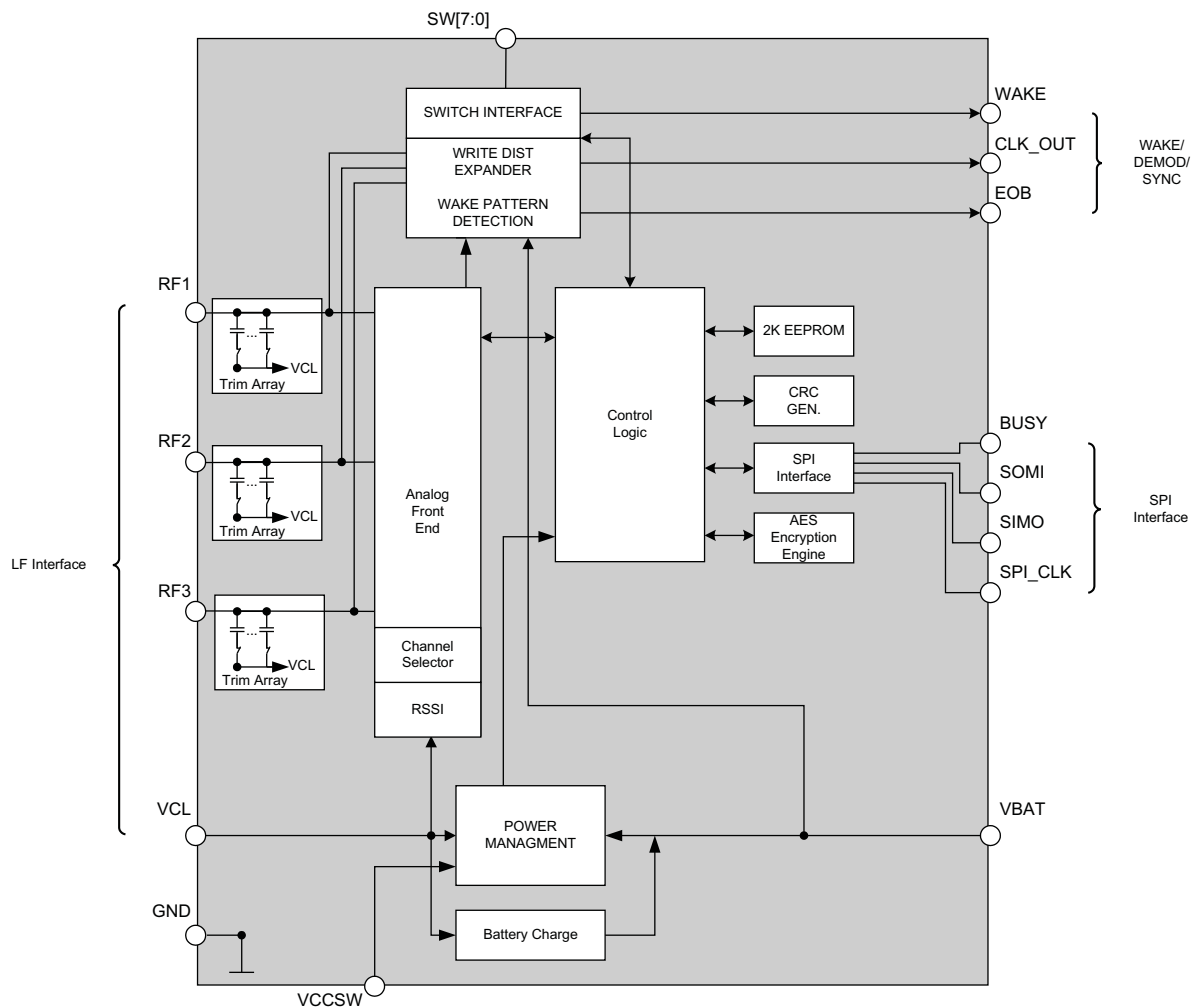


Figure 2. LF Interface Block Diagram

The LF front end provides a SPI interface which is used for the communication with the CPU core. Data access, configuration and status query the MSP430 is executed with predefined commands over this interface which is internally connected to IO ports.

Table 4. Intermodule Connections for RF430F59xx

MICROCONTROLLER PORT		LF FRONT END MODULE PORT
P3.1	Input	SPI_SOMI
P3.2	Output	SPI_SIMO
P3.3	Output	SPI_CLK
P3.5	Input	CLK_OUT
P4.1	Input	EOB
P4.2	Input	SPI_BUSY

3D LF Front End

The 3D LF front end provides two basic operation modes: transponder mode and wake-up receiver mode.

The LF front end provides an external trigger to wake up the microcontroller on LF reception. Data received by the LF interface and status of the device can be read via SPI communication.

Features of the LF front end include:

- Resonant frequency: 134.2 kHz
 - Embedded resonant trimming for all three resonant circuits
- Quality factor range: 10 to 60
- Antenna Inductance 2.66 mH, 4.5 mH, or 7.6 mH
- AES-128 hardware-encryption coprocessor
- 3D wake-up receiver
 - Fixed downlink start pattern S10
 - Downlink data rate up to 4kBps, bit-length coding
 - Two independent wake patterns WP A or WP B with 0-, 4-, 8-, 12-, 16-, 20-, or 24-bit length
 - Dedicated sensitivity levels for both WP
 - Digital RSSI 72dB, 8-bit logarithmic
 - Accuracy $\pm 8\%$ in near distance (<16 mVpp)
 - Accuracy $\pm 20\%$ in far distance (>16 mVpp)
- 3D RFID Transponder interface
 - Batteryless operation
 - Fixed downlink start pattern S01
 - Transponder read range up to 4 in (10 cm)
 - Half duplex communication protocol
 - Adaptive downlink data rate: up to 4 kBaud with ASK, bit-length coding
 - Uplink data rate: up to 8 kBaud with FSK
 - Selectable challenge/response length of 32/32, 64/64, or 96/64 bit
 - Mutual authentication for all commands with 32-bit reader signature
 - Selective addressing mode, 8-bit
 - Burst read mode
 - Anticollision encryption

EEPROM Memory

The EEPROM memory can be accessed by SPI commands. Features of the EEPROM memory include:

- Total memory size: 2048 Bytes
- User memory size : 1776 Bytes
 - User memory has up to 4 banks
 - User memory is organized in 64 pages per bank of 8 bytes each
- EEPROM has one system memory bank organized in 64 pages of 4 bytes each.
 - System memory is organized in 64 pages of 4 bytes each
 - System memory is used for special information (configuration, 4 x 128-bit encryption keys, counter values)
- The memory pages are configurable and provide different access modes
 - General-purpose memory (general read, program, and lock)
 - System only data (mutual only access)
 - Microcontroller only data (no access over LF interface)
 - Secured data (mutual program and lock, general read)
- All pages can be locked separately (no reprogramming possible)

The EEPROM organization is shown in [Table 5](#).

Switch Interface

The switch interface provides eight inputs. Features of the switch interface include:

- Internal pullups to minimize external components
- Embedded stuck button handling
- Embedded debouncing for each switch debounce time: 10, 20, 40, or 80 ms

Table 5. LF Front End EEPROM Memory Map

EEPROM (MEM)										
BANK	BYTE								PAGE	
	7	6	5	4	3	2	1	0		
0	User Data								0	
	⋮								⋮	
	User Data								7	
	⋮								⋮	
	User Data								63	
1	User Data								0	
	⋮								⋮	
	User Data								7	
	⋮								⋮	
	User Data								63	
2	User Data								0	
	⋮								⋮	
	User Data								7	
	⋮								⋮	
	User Data								63	
3	User Data								0	
	⋮								⋮	
	User Data								7	
	⋮								⋮	
	User Data								29	
7	Configuration Data				Configuration Data				1	0
									3	2
									5	4
									7	6
									9	8
									11	10
									13	12
									15	14
	Encryption Keys				Encryption Keys				17	16
									19	18
									21	20
									23	22
									25	24
									27	26
									29	28
									31	30

Sub 1-GHz Radio

The sub 1-GHz radio module is based on the industry-leading CC1101 and requires very few external components. Figure 3 shows a high-level block diagram of the implemented radio.

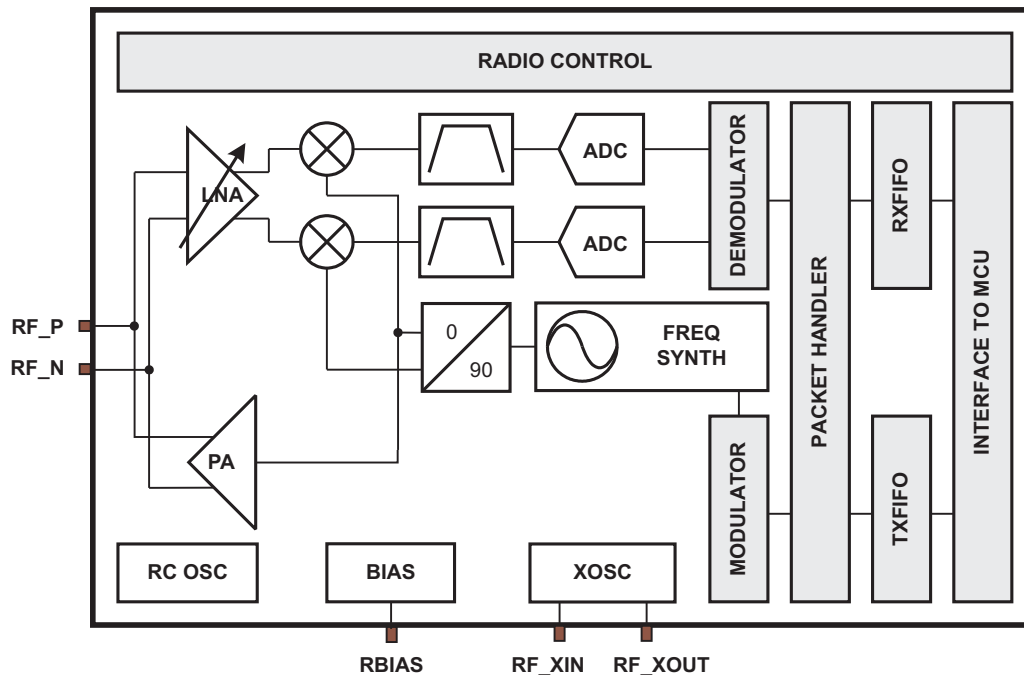


Figure 3. Sub 1-GHz Radio Block Diagram

The radio features a low intermediate frequency (IF) receiver. The received RF signal is amplified by a low-noise amplifier (LNA) and down-converted in quadrature to the IF. At the IF, the I/Q signals are digitized. Automatic gain control (AGC), fine channel filtering, and demodulation bit and packet synchronization are performed digitally.

The transmitter is based on direct synthesis of the RF frequency. The frequency synthesizer includes a completely on-chip LC VCO and a 90-degree phase shifter for generating the I and Q LO signals to the down-conversion mixers in receive mode.

The 26-MHz crystal oscillator generates the reference frequency for the synthesizer. It also generates the clocks for the ADC and the digital part.

A memory mapped register interface is used for data access, configuration, and status request by the CPU.

The digital baseband includes support for channel configuration, packet handling, and data buffering.

For complete module descriptions, see the *RF430F5978 User's Guide* (SLAU378).

CPU

The MSP430 CPU has a 16-bit RISC architecture that is highly transparent to the application. All operations, other than program-flow instructions, are performed as register operations in conjunction with seven addressing modes for source operand and four addressing modes for destination operand.

The CPU is integrated with 16 registers that provide reduced instruction execution time. The register-to-register operation execution time is one cycle of the CPU clock.

Four of the registers, R0 to R3, are dedicated as program counter, stack pointer, status register, and constant generator, respectively. The remaining registers are general-purpose registers.

Peripherals are connected to the CPU using data, address, and control buses, and can be handled with all instructions.

The instruction set consists of the original 51 instructions with three formats and seven address modes and additional instructions for the expanded address range. Each instruction can operate on word and byte data.

Operating Modes

The CC430 has one active mode and five software-selectable low-power modes of operation. An interrupt event can wake up the device from any of the low-power modes, service the request, and restore back to the low-power mode on return from the interrupt program.

The following six operating modes can be configured by software:

- Active mode (AM)
 - All clocks are active
- Low-power mode 0 (LPM0)
 - CPU is disabled
 - ACLK and SMCLK remain active, MCLK is disabled
 - FLL loop control remains active
- Low-power mode 1 (LPM1)
 - CPU is disabled
 - FLL loop control is disabled
 - ACLK and SMCLK remain active, MCLK is disabled
- Low-power mode 2 (LPM2)
 - CPU is disabled
 - MCLK and FLL loop control and DCOCLK are disabled
- Low-power mode 3 (LPM3)
 - DCO's dc-generator remains enabled
 - ACLK remains active
- Low-power mode 4 (LPM4)
 - CPU is disabled
 - ACLK is disabled
 - MCLK, FLL loop control, and DCOCLK are disabled
 - DCO's dc-generator is disabled
 - Crystal oscillator is stopped
 - Complete data retention

Interrupt Vector Addresses

The interrupt vectors and the power-up start address are located in the address range 0FFFFh to 0FF80h. The vector contains the 16-bit address of the appropriate interrupt-handler instruction sequence.

Table 6. Interrupt Sources, Flags, and Vectors

INTERRUPT SOURCE	INTERRUPT FLAG	SYSTEM INTERRUPT	WORD ADDRESS	PRIORITY
System Reset Power-Up External Reset Watchdog Timeout, Password Violation Flash Memory Password Violation	WDTIFG, KEYV (SYSRSTIV) ^{(1) (2)}	Reset	0FFFEh	63, highest
System NMI PMM Vacant Memory Access JTAG Mailbox	SVMLIFG, SVMHIFG, DLYLIFG, DLYHIFG, VLRLIFG, VLRHIFG, VMAIFG, JMBNIFG, JMBOUTIFG (SYSSNIV) ^{(1) (3)}	(Non)maskable	0FFFCh	62
User NMI NMI Oscillator Fault Flash Memory Access Violation	NMIIFG, OFIFG, ACCVIFG (SYSUNIV) ^{(1) (3)}	(Non)maskable	0FFFAh	61
Comparator_B	Comparator_B Interrupt Flags (CBIV) ⁽¹⁾	Maskable	0FFF8h	60
Watchdog Interval Timer Mode	WDTIFG	Maskable	0FFF6h	59
USCI_A0 Receive or Transmit	UCA0RXIFG, UCA0TXIFG (UCA0IV) ⁽¹⁾	Maskable	0FFF4h	58
USCI_B0 Receive or Transmit	UCB0RXIFG, UCB0TXIFG, I2C Status Interrupt Flags (UCB0IV) ⁽¹⁾	Maskable	0FFF2h	57
ADC12_A	ADC12IFG0 ... ADC12IFG15 (ADC12IV) ⁽¹⁾	Maskable	0FFF0h	56
TA0	TA0CCR0 CCIFG0	Maskable	0FFEEh	55
TA0	TA0CCR1 CCIFG1 ... TA0CCR4 CCIFG4, TA0IFG (TA0IV) ⁽¹⁾	Maskable	0FFECCh	54
RF1A CC1101-based Radio	Radio Interface Interrupt Flags (RF1AIFIV) Radio Core Interrupt Flags (RF1AIV)	Maskable	0FFEAh	53
DMA	DMA0IFG, DMA1IFG, DMA2IFG (DMAIV) ⁽¹⁾	Maskable	0FFE8h	52
TA1	TA1CCR0 CCIFG0	Maskable	0FFE6h	51
TA1	TA1CCR1 CCIFG1 ... TA1CCR2 CCIFG2, TA1IFG (TA1IV) ⁽¹⁾	Maskable	0FFE4h	50
I/O Port P1	P1IFG.0 to P1IFG.7 (P1IV) ⁽¹⁾	Maskable	0FFE2h	49
I/O Port P2	P2IFG.0 to P2IFG.7 (P2IV) ⁽¹⁾	Maskable	0FFE0h	48
Reserved	Reserved ⁽⁴⁾		0FFDEh	47
RTC_A	RTCRDYIFG, RTCTEVIFG, RTCAIFG, RT0PSIFG, RT1PSIFG (RTCIV) ⁽¹⁾	Maskable	0FFDCh	46
AES	AESRDYIFG	Maskable	0FFDAh	45
Reserved	Reserved ⁽⁴⁾		0FFD8h	44
			⋮	⋮
			0FF80h	0, lowest

(1) Multiple source flags

(2) A reset is generated if the CPU tries to fetch instructions from within peripheral space.

(3) (Non)maskable: the individual interrupt-enable bit can disable an interrupt event, but the general interrupt enable cannot disable it.

(4) Reserved interrupt vectors at addresses are not used in this device and can be used for regular program code if necessary. To maintain compatibility with other devices, it is recommended to reserve these locations.

Memory Organization

Table 7. Memory Organization

		RF430F5978⁽¹⁾
Main Memory (flash)	Total Size	32kB
Main: Interrupt vector		00FFFFh to 00FF80h
Main: code memory	Bank 0	32kB 00FFFFh to 008000h
RAM	Total Size	4kB
	Sect 1	2kB 002BFFh to 002400h
	Sect 0	2kB 0023FFh to 001C00h
Device descriptor		128 B 001AFFh to 001A80h
		128 B 001A7Fh to 001A00h
Information memory (flash)	Info A	128 B 0019FFh to 001980h
	Info B	128 B 00197Fh to 001900h
	Info C	128 B 0018FFh to 001880h
	Info D	128 B 00187Fh to 001800h
Bootstrap loader (BSL) memory (flash)	BSL 3	512 B 0017FFh to 001600h
	BSL 2	512 B 0015FFh to 001400h
	BSL 1	512 B 0013FFh to 001200h
	BSL 0	512 B 0011FFh to 001000h
Peripherals		4 KB 000FFFh to 0h

(1) All memory regions not specified here are vacant memory, and any access to them causes a Vacant Memory Interrupt.

Bootstrap Loader (BSL)

The BSL enables users to program the flash memory or RAM using various serial interfaces. Access to the device memory via the BSL is protected by an user-defined password. BSL entry requires a specific entry sequence on the $\overline{\text{RST}}/\text{NMI}/\text{SBWTDIO}$ and $\text{TEST}/\text{SBWTCK}$ pins. For complete description of the features of the BSL and its implementation, see the *MSP430 Programming Via the Bootstrap Loader User's Guide* ([SLAU319](#)).

Table 8. UART BSL Pin Requirements and Functions

DEVICE SIGNAL	BSL FUNCTION
$\overline{\text{RST}}/\text{NMI}/\text{SBWTDIO}$	Entry sequence signal
$\text{TEST}/\text{SBWTCK}$	Entry sequence signal
P1.6	Data transmit
P1.5	Data receive
VCC	Power supply
VSS	Ground supply

JTAG Operation

JTAG Standard Interface

The RF430F5978 supports the standard JTAG interface, which requires four signals for sending and receiving data. The JTAG signals are shared with general-purpose I/O. The TEST/SBWTCK pin is used to enable the JTAG signals. In addition to these signals, the $\overline{\text{RST}}/\text{NMI}/\text{SBWTDIO}$ is required to interface with MSP430 development tools and device programmers. The JTAG pin requirements are shown in [Table 9](#). For further details on interfacing to development tools and device programmers, see the *MSP430 Hardware Tools User's Guide* ([SLAU278](#)). For a complete description of the features of the JTAG interface and its implementation, see *MSP430 Programming Via the JTAG Interface* ([SLAU320](#)).

Table 9. JTAG Pin Requirements and Functions

DEVICE SIGNAL	DIRECTION	FUNCTION
PJ.3/TCK	IN	JTAG clock input
PJ.2/TMS	IN	JTAG state control
PJ.1/TDI/TCLK	IN	JTAG data input, TCLK input
PJ.0/TDO	OUT	JTAG data output
TEST/SBWTCK	IN	Enable JTAG pins
$\overline{\text{RST}}/\text{NMI}/\text{SBWTDIO}$	IN	External reset
VCC		Power supply
VSS		Ground supply

Spy-Bi-Wire Interface

In addition to the standard JTAG interface, the RF430F5978 supports the two-wire Spy-Bi-Wire interface. Spy-Bi-Wire can be used to interface with MSP430 development tools and device programmers. The Spy-Bi-Wire interface pin requirements are shown in [Table 10](#). For further details on interfacing to development tools and device programmers, see the *MSP430 Hardware Tools User's Guide* ([SLAU278](#)). For a complete description of the features of the JTAG interface and its implementation, see *MSP430 Programming Via the JTAG Interface* ([SLAU320](#)).

Table 10. Spy-Bi-Wire Pin Requirements and Functions

DEVICE SIGNAL	DIRECTION	FUNCTION
TEST/SBWTCK	IN	Spy-Bi-Wire clock input
$\overline{\text{RST}}/\text{NMI}/\text{SBWTDIO}$	IN, OUT	Spy-Bi-Wire data input/output
VCC		Power supply
VSS		Ground supply

Flash Memory

The flash memory can be programmed via the JTAG port, Spy-Bi-Wire (SBW), or in-system by the CPU. The CPU can perform single-byte, single-word, and long-word writes to the flash memory. Features of the flash memory include:

- Flash memory has n segments of main memory and four segments of information memory (Info A to Info D) of 128 bytes each. Each segment in main memory is 512 bytes in size.
- Segments 0 to n may be erased in one step, or each segment may be individually erased.
- Segments Info A to Info D can be erased individually, or as a group with the main memory segments. Segments Info A to Info D are also called *information memory*.
- Segment A can be locked separately.

RAM Memory

The RAM memory is made up of n sectors. Each sector can be completely powered down to save leakage, however, all data is lost. Features of the RAM memory include:

- RAM memory has n sectors of 2k bytes each.
- Each sector 0 to n can be complete disabled, however data retention is lost.
- Each sector 0 to n automatically enters low power retention mode when possible.

Peripherals

Peripherals are connected to the CPU through data, address, and control busses and can be handled using all instructions. For complete module descriptions, see the *RF430F5978 User's Guide* (SLAU378).

Oscillator and System Clock

The Unified Clock System (UCS) module includes support for a 32768-Hz watch crystal oscillator, an internal very-low-power low-frequency oscillator (VLO), an internal trimmed low-frequency oscillator (REFO), an integrated internal digitally controlled oscillator (DCO), and a high-frequency crystal oscillator. The UCS module is designed to meet the requirements of both low system cost and low power consumption. The UCS module features digital frequency locked loop (FLL) hardware that, in conjunction with a digital modulator, stabilizes the DCO frequency to a programmable multiple of the watch crystal frequency. The internal DCO provides a fast turn-on clock source and stabilizes in less than 5 μ s. The UCS module provides the following clock signals:

- Auxiliary clock (ACLK), sourced from a 32768-Hz watch crystal, a high-frequency crystal, the internal low-frequency oscillator (VLO), or the trimmed low-frequency oscillator (REFO).
- Main clock (MCLK), the system clock used by the CPU. MCLK can be sourced by same sources made available to ACLK.
- Sub-Main clock (SMCLK), the subsystem clock used by the peripheral modules. SMCLK can be sourced by same sources made available to ACLK.
- ACLK/ n , the buffered output of ACLK, ACLK/2, ACLK/4, ACLK/8, ACLK/16, ACLK/32.

Power Management Module (PMM)

The PMM includes an integrated voltage regulator that supplies the core voltage to the device and contains programmable output levels to provide for power optimization. The PMM also includes supply voltage supervisor (SVS) and supply voltage monitor (SVM) circuitry, as well as brownout protection. The brownout circuit is implemented to provide the proper internal reset signal to the device during power-on and power-off. The SVS and SVM circuitry detects if the supply voltage drops below a user-selectable level and supports both supply voltage supervision (the device is automatically reset) and supply voltage monitoring (the device is not automatically reset). SVS and SVM circuitry is available on the primary supply and core supply.

Digital I/O

There are five I/O ports implemented: ports P1 through P3 are 8 bit, P4 is 1 bit, and P5 is 2 bit.

- All individual I/O bits are independently programmable.
- Any combination of input, output, and interrupt conditions is possible.
- Programmable pullup or pulldown on all ports.
- Programmable drive strength on all ports.
- Edge-selectable interrupt input capability for all the eight bits of ports P1 and P2.
- Read and write access to port-control registers is supported by all instructions.
- Ports can be accessed byte-wise (P1 through P3) or word-wise in pairs (PA and PB).

Port Mapping Controller

The port mapping controller allows the flexible and re-configurable mapping of digital functions to port pins of ports P1 through P3.

Table 11. Port Mapping Mnemonics and Functions

VALUE	PxMAPy MNEMONIC	INPUT PIN FUNCTION (PxDIR.y = 0)	OUTPUT PIN FUNCTION (PxDIR.y = 1)
0	PM_NONE	None	DVSS
1 ⁽¹⁾	PM_CBOUT0		Comparator_B output (on TA0 clock input)
	PM_TA0CLK	TA0 clock input	-
2 ⁽¹⁾	PM_CBOUT1	-	Comparator_B output (on TA1 clock input)
	PM_TA1CLK	TA1 clock input	-
3	PM_ACLK	None	ACLK output
4	PM_MCLK	None	MCLK output
5	PM_SMCLK	None	SMCLK output
6	PM_RTCCLK	None	RTCCLK output
7 ⁽¹⁾	PM_ADC12CLK	-	ADC12CLK output
	PM_DMAE0	DMA external trigger input	-
8	PM_SVMOUT	None	SVM output
9	PM_TA0CCR0A	TA0 CCR0 capture input CCI0A	TA0 CCR0 compare output Out0
10	PM_TA0CCR1A	TA0 CCR1 capture input CCI1A	TA0 CCR1 compare output Out1
11	PM_TA0CCR2A	TA0 CCR2 capture input CCI2A	TA0 CCR2 compare output Out2
12	PM_TA0CCR3A	TA0 CCR3 capture input CCI3A	TA0 CCR3 compare output Out3
13	PM_TA0CCR4A	TA0 CCR4 capture input CCI4A	TA0 CCR4 compare output Out4
14	PM_TA1CCR0A	TA1 CCR0 capture input CCI0A	TA1 CCR0 compare output Out0
15	PM_TA1CCR1A	TA1 CCR1 capture input CCI1A	TA1 CCR1 compare output Out1
16	PM_TA1CCR2A	TA1 CCR2 capture input CCI2A	TA1 CCR2 compare output Out2
17 ⁽²⁾	PM_UCA0RXD	USCI_A0 UART RXD (Direction controlled by USCI - input)	
	PM_UCA0SOMI	USCI_A0 SPI slave out master in (direction controlled by USCI)	
18 ⁽²⁾	PM_UCA0TXD	USCI_A0 UART TXD (Direction controlled by USCI - output)	
	PM_UCA0SIMO	USCI_A0 SPI slave in master out (direction controlled by USCI)	
19 ⁽³⁾	PM_UCA0CLK	USCI_A0 clock input/output (direction controlled by USCI)	
	PM_UCB0STE	USCI_B0 SPI slave transmit enable (direction controlled by USCI - input)	
20 ⁽⁴⁾	PM_UCB0SOMI	USCI_B0 SPI slave out master in (direction controlled by USCI)	
	PM_UCB0SCL	USCI_B0 I2C clock (open drain and direction controlled by USCI)	
21 ⁽⁴⁾	PM_UCB0SIMO	USCI_B0 SPI slave in master out (direction controlled by USCI)	
	PM_UCB0SDA	USCI_B0 I2C data (open drain and direction controlled by USCI)	
22 ⁽⁵⁾	PM_UCB0CLK	USCI_B0 clock input/output (direction controlled by USCI)	
	PM_UCA0STE	USCI_A0 SPI slave transmit enable (direction controlled by USCI - input)	
23	PM_RFGDO0	Radio GDO0 (direction controlled by Radio)	
24	PM_RFGDO1	Radio GDO1 (direction controlled by Radio)	
25	PM_RFGDO2	Radio GDO2 (direction controlled by Radio)	
26	Reserved	None	DVSS

- (1) Input or output function is selected by the corresponding setting in the port direction register PxDIR.
- (2) UART or SPI functionality is determined by the selected USCI mode.
- (3) UCA0CLK function takes precedence over UCB0STE function. If the mapped pin is required as UCA0CLK input or output USCI_B0 will be forced to 3-wire SPI mode even if 4-wire mode is selected.
- (4) SPI or I2C functionality is determined by the selected USCI mode. In case the I2C functionality is selected the output of the mapped pin drives only the logical 0 to V_{SS} level.
- (5) UCB0CLK function takes precedence over UCA0STE function. If the mapped pin is required as UCB0CLK input or output USCI_A0 will be forced to 3-wire SPI mode even if 4-wire mode is selected.

Table 11. Port Mapping Mnemonics and Functions (continued)

VALUE	PxMAPy MNEMONIC	INPUT PIN FUNCTION (PxDIR.y = 0)	OUTPUT PIN FUNCTION (PxDIR.y = 1)
27	Reserved	None	DVSS
28	Reserved	None	DVSS
29	Reserved	None	DVSS
30	Reserved	None	DVSS
31 (0FFh) ⁽⁶⁾	PM_ANALOG	Disables the output driver and the input Schmitt-trigger to prevent parasitic cross currents when applying analog signals.	

(6) The value of the PM_ANALOG mnemonic is set to 0FFh. The port mapping registers are 5 bits wide and the upper bits are ignored, which results in a read out value of 31.

Table 12. Default Mapping

PIN	PxMAPy MNEMONIC	INPUT PIN FUNCTION (PxDIR.y = 0)	OUTPUT PIN FUNCTION (PxDIR.y = 1)
P1.0/P1MAP0	PM_RFGDO0	None	Radio GDO0
P1.1/P1MAP1	PM_RFGDO2	None	Radio GDO2
P1.2/P1MAP2	PM_UCB0SOMI/PM_UCB0SCL	USCI_B0 SPI slave out master in (direction controlled by USCI) USCI_B0 I2C clock (open drain and direction controlled by USCI)	
P1.3/P1MAP3	PM_UCB0SIMO/PM_UCB0SDA	USCI_B0 SPI slave in master out (direction controlled by USCI) USCI_B0 I2C data (open drain and direction controlled by USCI)	
P1.4/P1MAP4	PM_UCB0CLK/PM_UCA0STE	USCI_B0 clock input/output (direction controlled by USCI) USCI_A0 SPI slave transmit enable (direction controlled by USCI - input)	
P1.5/P1MAP5	PM_UCA0RXD/PM_UCA0SOMI	USCI_A0 UART RXD (Direction controlled by USCI - input) USCI_A0 SPI slave out master in (direction controlled by USCI)	
P1.6/P1MAP6	PM_UCA0TXD/PM_UCA0SIMO	USCI_A0 UART TXD (Direction controlled by USCI - output) USCI_A0 SPI slave in master out (direction controlled by USCI)	
P1.7/P1MAP7	PM_UCA0CLK/PM_UCB0STE	USCI_A0 clock input/output (direction controlled by USCI) USCI_B0 SPI slave transmit enable (direction controlled by USCI - input)	
P2.0/P2MAP0	PM_CBOU1/PM_TA1CLK	TA1 clock input	Comparator_B output
P2.1/P2MAP1	PM_TA1CCR0A	TA1 CCR0 capture input CCI0A	TA1 CCR0 compare output Out0
P2.2/P2MAP2	PM_TA1CCR1A	TA1 CCR1 capture input CCI1A	TA1 CCR1 compare output Out1
P2.3/P2MAP3	PM_TA1CCR2A	TA1 CCR2 capture input CCI2A	TA1 CCR2 compare output Out2
P2.4/P2MAP4	PM_RTCCLK	None	RTCCLK output
P2.5/P2MAP5	PM_SVMOUT	None	SVM output
P2.6/P2MAP6	PM_ACLK	None	ACLK output
P2.7/P2MAP7	PM_ADC12CLK/PM_DMAE0	DMA external trigger input	ADC12CLK output
P3.0/P3MAP0	PM_CBOU0/PM_TA0CLK	TA0 clock input	Comparator_B output
P3.1/P3MAP1	PM_TA0CCR0A	TA0 CCR0 capture input CCI0A	TA0 CCR0 compare output Out0
P3.2/P3MAP2	PM_TA0CCR1A	TA0 CCR1 capture input CCI1A	TA0 CCR1 compare output Out1
P3.3/P3MAP3	PM_TA0CCR2A	TA0 CCR2 capture input CCI2A	TA0 CCR2 compare output Out2
P3.4/P3MAP4	PM_TA0CCR3A	TA0 CCR3 capture input CCI3A	TA0 CCR3 compare output Out3
P3.5/P3MAP5	PM_TA0CCR4A	TA0 CCR4 capture input CCI4A	TA0 CCR4 compare output Out4
P3.6/P3MAP6	PM_RFGDO1	None	Radio GDO1
P3.7/P3MAP7	PM_SMCLK	None	SMCLK output

System Module (SYS)

The SYS module handles many of the system functions within the device. These include power on reset and power up clear handling, NMI source selection and management, reset interrupt vector generators, boot strap loader entry mechanisms, as well as, configuration management (device descriptors). It also includes a data exchange mechanism via JTAG called a JTAG mailbox that can be used in the application.

Table 13. System Module Interrupt Vector Registers

INTERRUPT VECTOR REGISTER	ADDRESS	INTERRUPT EVENT	VALUE	PRIORITY
SYSRSTIV, System Reset	019Eh	No interrupt pending	00h	
		Brownout (BOR)	02h	Highest
		RST/NMI (POR)	04h	
		DoBOR (BOR)	06h	
		Reserved	08h	
		Security violation (BOR)	0Ah	
		SVSL (POR)	0Ch	
		SVSH (POR)	0Eh	
		SVML_OVP (POR)	10h	
		SVMH_OVP (POR)	12h	
		DoPOR (POR)	14h	
		WDT timeout (PUC)	16h	
		WDT password violation (PUC)	18h	
		KEYV flash password violation (PUC)	1Ah	
		Reserved	1Ch	
		Peripheral area fetch (PUC)	1Eh	
		PMM password violation (PUC)	20h	
		Reserved	22h to 3Eh	Lowest
SYSSNIV, System NMI	019Ch	No interrupt pending	00h	
		SVMLIFG	02h	Highest
		SVMHIFG	04h	
		DLYLIFG	06h	
		DLYHIFG	08h	
		VMAIFG	0Ah	
		JMBINIFG	0Ch	
		JMBOUTIFG	0Eh	
		VLRIFG	10h	
		VLRHIFG	12h	
		Reserved	14h to 1Eh	Lowest
SYSUNIV, User NMI	019Ah	No interrupt pending	00h	
		NMIFG	02h	Highest
		OFIFG	04h	
		ACCVIFG	06h	
		Reserved	08h to 1Eh	Lowest

DMA Controller

The DMA controller allows movement of data from one memory address to another without CPU intervention. Using the DMA controller can increase the throughput of peripheral modules. The DMA controller reduces system power consumption by allowing the CPU to remain in sleep mode, without having to awaken to move data to or from a peripheral.

Table 14. DMA Trigger Assignments⁽¹⁾

TRIGGER	CHANNEL		
	0	1	2
0	DMAREQ	DMAREQ	DMAREQ
1	TA0CCR0 CCIFG	TA0CCR0 CCIFG	TA0CCR0 CCIFG
2	TA0CCR2 CCIFG	TA0CCR2 CCIFG	TA0CCR2 CCIFG
3	TA1CCR0 CCIFG	TA1CCR0 CCIFG	TA1CCR0 CCIFG
4	TA1CCR2 CCIFG	TA1CCR2 CCIFG	TA1CCR2 CCIFG
5	Reserved	Reserved	Reserved
6	Reserved	Reserved	Reserved
7	Reserved	Reserved	Reserved
8	Reserved	Reserved	Reserved
9	Reserved	Reserved	Reserved
10	Reserved	Reserved	Reserved
11	Reserved	Reserved	Reserved
12	Reserved	Reserved	Reserved
13	Reserved	Reserved	Reserved
14	Reserved	Reserved	Reserved
15	Reserved	Reserved	Reserved
16	UCA0RXIFG	UCA0RXIFG	UCA0RXIFG
17	UCA0TXIFG	UCA0TXIFG	UCA0TXIFG
18	UCB0RXIFG	UCB0RXIFG	UCB0RXIFG
19	UCB0TXIFG	UCB0TXIFG	UCB0TXIFG
20	Reserved	Reserved	Reserved
21	Reserved	Reserved	Reserved
22	Reserved	Reserved	Reserved
23	Reserved	Reserved	Reserved
24	ADC12IFGx	ADC12IFGx	ADC12IFGx
25	Reserved	Reserved	Reserved
26	Reserved	Reserved	Reserved
27	Reserved	Reserved	Reserved
28	Reserved	Reserved	Reserved
29	MPY ready	MPY ready	MPY ready
30	DMA2IFG	DMA0IFG	DMA1IFG
31	DMAE0	DMAE0	DMAE0

(1) Reserved DMA triggers may be used by other devices in the family. Reserved DMA triggers do not cause any DMA trigger event when selected.

Watchdog Timer (WDT_A)

The primary function of the watchdog timer is to perform a controlled system restart after a software problem occurs. If the selected time interval expires, a system reset is generated. If the watchdog function is not needed in an application, the timer can be configured as an interval timer and can generate interrupts at selected time intervals.

CRC16

The CRC16 module produces a signature based on a sequence of entered data values and can be used for data checking purposes. The CRC16 module signature is based on the CRC-CCITT standard.

Hardware Multiplier

The multiplication operation is supported by a dedicated peripheral module. The module performs operations with 32-bit, 24-bit, 16-bit, and 8-bit operands. The module is capable of supporting signed and unsigned multiplication as well as signed and unsigned multiply and accumulate operations.

AES128 Accelerator

The AES accelerator module performs encryption and decryption of 128-bit data with 128-bit keys according to the Advanced Encryption Standard (AES) (FIPS PUB 197) in hardware.

Universal Serial Communication Interface (USCI)

The USCI module is used for serial data communication. The USCI module supports synchronous communication protocols such as SPI (3 or 4 pin) and I²C, and asynchronous communication protocols such as UART, enhanced UART with automatic baudrate detection, and IrDA.

The USCI_An module provides support for SPI (3 or 4 pin), UART, enhanced UART, and IrDA.

The USCI_Bn module provides support for SPI (3 or 4 pin) and I2C.

A USCI_A0 and USCI_B0 module are implemented.

TA0

TA0 is a 16-bit timer/counter (Timer_A type) with five capture/compare registers. TA0 can support multiple capture/compares, PWM outputs, and interval timing. TA0 also has extensive interrupt capabilities. Interrupts may be generated from the counter on overflow conditions and from each of the capture/compare registers.

Table 15. TA0 Signal Connections

DEVICE INPUT SIGNAL	MODULE INPUT NAME	MODULE BLOCK	MODULE OUTPUT SIGNAL	DEVICE OUTPUT SIGNAL
PM_TA0CLK	TACLK	Timer	NA	
ACLK (internal)	ACLK			
SMCLK (internal)	SMCLK			
RFCLK/192 ⁽¹⁾	INCLK			
PM_TA0CCR0A	CCI0A	CCR0	TA0	PM_TA0CCR0A
DV _{SS}	CCI0B			
DV _{SS}	GND			
DV _{CC}	V _{CC}			
PM_TA0CCR1A	CCI1A	CCR1	TA1	PM_TA0CCR1A
CBOU _T (internal)	CCI1B			ADC12 (internal) ADC12SHS _x = {1}
DV _{SS}	GND			
DV _{CC}	V _{CC}			
PM_TA0CCR2A	CCI2A	CCR2	TA2	PM_TA0CCR2A
ACLK (internal)	CCI2B			
DV _{SS}	GND			
DV _{CC}	V _{CC}			
PM_TA0CCR3A	CCI3A	CCR3	TA3	PM_TA0CCR3A
GDO1 from Radio (internal)	CCI3B			
DV _{SS}	GND			
DV _{CC}	V _{CC}			
PM_TA0CCR4A	CCI4A	CCR4	TA4	PM_TA0CCR4A
GDO2 from Radio (internal)	CCI4B			
DV _{SS}	GND			
DV _{CC}	V _{CC}			

(1) If a different RFCLK divider setting is selected for a radio GDO output, this divider setting is also used for the Timer_A INCLK.

TA1

TA1 is a 16-bit timer/counter (Timer_A type) with three capture/compare registers. TA1 can support multiple capture/compares, PWM outputs, and interval timing. TA1 also has extensive interrupt capabilities. Interrupts may be generated from the counter on overflow conditions and from each of the capture/compare registers.

Table 16. TA1 Signal Connections

DEVICE INPUT SIGNAL	MODULE INPUT NAME	MODULE BLOCK	MODULE OUTPUT SIGNAL	DEVICE OUTPUT SIGNAL
				PZ
PM_TA1CLK	TACLK	Timer	NA	
ACLK (internal)	ACLK			
SMCLK (internal)	SMCLK			
RFCLK/192 ⁽¹⁾	INCLK			
PM_TA1CCR0A	CCI0A	CCR0	TA0	PM_TA1CCR0A
RF Async. Output (internal)	CCI0B			RF Async. Input (internal)
DV _{SS}	GND			
DV _{CC}	V _{CC}			
PM_TA1CCR1A	CCI1A	CCR1	TA1	PM_TA1CCR1A
CBOU _T (internal)	CCI1B			
DV _{SS}	GND			
DV _{CC}	V _{CC}			
PM_TA1CCR2A	CCI2A	CCR2	TA2	PM_TA1CCR2A
ACLK (internal)	CCI2B			
DV _{SS}	GND			
DV _{CC}	V _{CC}			

(1) If a different RFCLK divider setting is selected for a radio GDO output, this divider setting is also used for the Timer_A INCLK.

Real-Time Clock (RTC_A)

The RTC_A module can be used as a general-purpose 32-bit counter (counter mode) or as an integrated real-time clock (RTC) (calendar mode). In counter mode, the RTC_A also includes two independent 8-bit timers that can be cascaded to form a 16-bit timer/counter. Both timers can be read and written by software. Calendar mode integrates an internal calendar which compensates for months with less than 31 days and includes leap year correction. The RTC_A also supports flexible alarm functions and offset-calibration hardware.

REF Voltage Reference

The reference module (REF) is responsible for generation of all critical reference voltages that can be used by the various analog peripherals in the device. These include the ADC12_A, LCD_B, and COMP_B modules.

Comparator_B

The primary function of the Comparator_B module is to support precision slope analog-to-digital conversions, battery voltage supervision, and monitoring of external analog signals.

ADC12_A

The ADC12_A module supports fast, 12-bit analog-to-digital conversions. The module implements a 12-bit SAR core, sample select control, reference generator and a 16 word conversion-and-control buffer. The conversion-and-control buffer allows up to 16 independent ADC samples to be converted and stored without any CPU intervention.

Embedded Emulation Module (EEM) (S Version)

The Embedded Emulation Module (EEM) supports real-time in-system debugging. The S version of the EEM implemented on all devices has the following features:

- Three hardware triggers or breakpoints on memory access
- One hardware trigger or breakpoint on CPU register write access
- Up to four hardware triggers can be combined to form complex triggers or breakpoints
- One cycle counter
- Clock control on module level

Peripheral File Map

Table 17. Peripherals

MODULE NAME	BASE ADDRESS	OFFSET ADDRESS RANGE
Special Functions (see Table 18)	0100h	000h-01Fh
PMM (see Table 19)	0120h	000h-00Fh
Flash Control (see Table 20)	0140h	000h-00Fh
CRC16 (see Table 21)	0150h	000h-007h
RAM Control (see Table 22)	0158h	000h-001h
Watchdog (see Table 23)	015Ch	000h-001h
UCS (see Table 24)	0160h	000h-01Fh
SYS (see Table 25)	0180h	000h-01Fh
Shared Reference (see Table 26)	01B0h	000h-001h
Port Mapping Control (see Table 27)	01C0h	000h-007h
Port Mapping Port P1 (see Table 28)	01C8h	000h-007h
Port Mapping Port P2 (see Table 29)	01D0h	000h-007h
Port Mapping Port P3 (see Table 30)	01D8h	000h-007h
Port P1, P2 (see Table 31)	0200h	000h-01Fh
Port P3, P4 (see Table 32)	0220h	000h-01Fh
Port P5 (see Table 33)	0240h	000h-01Fh
Port PJ (see Table 34)	0320h	000h-01Fh
TA0 (see Table 35)	0340h	000h-03Fh
TA1 (see Table 36)	0380h	000h-03Fh
RTC_A (see Table 37)	04A0h	000h-01Fh
32-Bit Hardware Multiplier (see Table 38)	04C0h	000h-02Fh
DMA Module Control (see Table 39)	0500h	000h-00Fh
DMA Channel 0 (see Table 40)	0510h	000h-00Fh
DMA Channel 1 (see Table 41)	0520h	000h-00Fh
DMA Channel 2 (see Table 42)	0530h	000h-00Fh
USCI_A0 (see Table 43)	05C0h	000h-01Fh
USCI_B0 (see Table 44)	05E0h	000h-01Fh
ADC12 (see Table 45)	0700h	000h-03Fh
Comparator_B (see Table 46)	08C0h	000h-00Fh
AES Accelerator (see Table 47)	09C0h	000h-00Fh
Radio Interface (see Table 48)	0F00h	000h-03Fh

Table 18. Special Function Registers (Base Address: 0100h)

REGISTER DESCRIPTION	REGISTER	OFFSET
SFR interrupt enable	SFRIE1	00h
SFR interrupt flag	SFRIFG1	02h
SFR reset pin control	SFRRPCR	04h

Table 19. PMM Registers (Base Address: 0120h)

REGISTER DESCRIPTION	REGISTER	OFFSET
PMM Control 0	PMMCTL0	00h
PMM control 1	PMMCTL1	02h
SVS high side control	SVSMHCTL	04h
SVS low side control	SVSMLCTL	06h
PMM interrupt flags	PMMIFG	0Ch
PMM interrupt enable	PMMIE	0Eh
PMM power mode 5 control	PM5CTL0	10h

Table 20. Flash Control Registers (Base Address: 0140h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Flash control 1	FCTL1	00h
Flash control 3	FCTL3	04h
Flash control 4	FCTL4	06h

Table 21. CRC16 Registers (Base Address: 0150h)

REGISTER DESCRIPTION	REGISTER	OFFSET
CRC data input	CRC16DI	00h
CRC data input reverse byte	CRCDIRB	02h
CRC initialization and result	CRCINIRES	04h
CRC result reverse byte	CRCRESR	06h

Table 22. RAM Control Registers (Base Address: 0158h)

REGISTER DESCRIPTION	REGISTER	OFFSET
RAM control 0	RCCTL0	00h

Table 23. Watchdog Registers (Base Address: 015Ch)

REGISTER DESCRIPTION	REGISTER	OFFSET
Watchdog timer control	WDTCTL	00h

Table 24. UCS Registers (Base Address: 0160h)

REGISTER DESCRIPTION	REGISTER	OFFSET
UCS control 0	UCSCTL0	00h
UCS control 1	UCSCTL1	02h
UCS control 2	UCSCTL2	04h
UCS control 3	UCSCTL3	06h
UCS control 4	UCSCTL4	08h
UCS control 5	UCSCTL5	0Ah
UCS control 6	UCSCTL6	0Ch
UCS control 7	UCSCTL7	0Eh
UCS control 8	UCSCTL8	10h

Table 25. SYS Registers (Base Address: 0180h)

REGISTER DESCRIPTION	REGISTER	OFFSET
System control	SYSCTL	00h
Bootstrap loader configuration area	SYSBSLC	02h
JTAG mailbox control	SYSJMBC	06h
JTAG mailbox input 0	SYSJMBI0	08h
JTAG mailbox input 1	SYSJMBI1	0Ah
JTAG mailbox output 0	SYSJMBO0	0Ch
JTAG mailbox output 1	SYSJMBO1	0Eh
Bus Error vector generator	SYSBERRIV	18h
User NMI vector generator	SYSUNIV	1Ah
System NMI vector generator	SYSSNIV	1Ch
Reset vector generator	SYSRSTIV	1Eh

Table 26. Shared Reference Registers (Base Address: 01B0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Shared reference control	REFCTL	00h

Table 27. Port Mapping Control Registers (Base Address: 01C0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port mapping key register	PMAPKEYID	00h
Port mapping control register	PMAPCTL	02h

Table 28. Port Mapping Port P1 Registers (Base Address: 01C8h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P1.0 mapping register	P1MAP0	00h
Port P1.1 mapping register	P1MAP1	01h
Port P1.2 mapping register	P1MAP2	02h
Port P1.3 mapping register	P1MAP3	03h
Port P1.4 mapping register	P1MAP4	04h
Port P1.5 mapping register	P1MAP5	05h
Port P1.6 mapping register	P1MAP6	06h
Port P1.7 mapping register	P1MAP7	07h

Table 29. Port Mapping Port P2 Registers (Base Address: 01D0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P2.0 mapping register	P2MAP0	00h
Port P2.1 mapping register	P2MAP2	01h
Port P2.2 mapping register	P2MAP2	02h
Port P2.3 mapping register	P2MAP3	03h
Port P2.4 mapping register	P2MAP4	04h
Port P2.5 mapping register	P2MAP5	05h
Port P2.6 mapping register	P2MAP6	06h
Port P2.7 mapping register	P2MAP7	07h

Table 30. Port Mapping Port P3 Registers (Base Address: 01D8h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P3.0 mapping register	P3MAP0	00h
Port P3.1 mapping register	P3MAP3	01h
Port P3.2 mapping register	P3MAP2	02h
Port P3.3 mapping register	P3MAP3	03h
Port P3.4 mapping register	P3MAP4	04h
Port P3.5 mapping register	P3MAP5	05h
Port P3.6 mapping register	P3MAP6	06h
Port P3.7 mapping register	P3MAP7	07h

Table 31. Port P1, P2 Registers (Base Address: 0200h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P1 input	P1IN	00h
Port P1 output	P1OUT	02h
Port P1 direction	P1DIR	04h
Port P1 pullup or pulldown enable	P1REN	06h
Port P1 drive strength	P1DS	08h
Port P1 selection	P1SEL	0Ah
Port P1 interrupt vector word	P1IV	0Eh
Port P1 interrupt edge select	P1IES	18h
Port P1 interrupt enable	P1IE	1Ah
Port P1 interrupt flag	P1IFG	1Ch
Port P2 input	P2IN	01h
Port P2 output	P2OUT	03h
Port P2 direction	P2DIR	05h
Port P2 pullup or pulldown enable	P2REN	07h
Port P2 drive strength	P2DS	09h
Port P2 selection	P2SEL	0Bh
Port P2 interrupt vector word	P2IV	1Eh
Port P2 interrupt edge select	P2IES	19h
Port P2 interrupt enable	P2IE	1Bh
Port P2 interrupt flag	P2IFG	1Dh

Table 32. Port P3, P4 Registers (Base Address: 0220h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P3 input	P3IN	00h
Port P3 output	P3OUT	02h
Port P3 direction	P3DIR	04h
Port P3 pullup or pulldown enable	P3REN	06h
Port P3 drive strength	P3DS	08h
Port P3 selection	P3SEL	0Ah

Table 33. Port P5 Registers (Base Address: 0240h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P5 input	P5IN	00h
Port P5 output	P5OUT	02h
Port P5 direction	P5DIR	04h
Port P5 pullup or pulldown enable	P5REN	06h

Table 33. Port P5 Registers (Base Address: 0240h) (continued)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port P5 drive strength	P5DS	08h
Port P5 selection	P5SEL	0Ah

Table 34. Port J Registers (Base Address: 0320h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Port PJ input	PJIN	00h
Port PJ output	PJOUT	02h
Port PJ direction	PJDIR	04h
Port PJ pullup or pulldown enable	PJREN	06h
Port PJ drive strength	PJDS	08h

Table 35. TA0 Registers (Base Address: 0340h)

REGISTER DESCRIPTION	REGISTER	OFFSET
TA0 control	TA0CTL	00h
Capture/compare control 0	TA0CCTL0	02h
Capture/compare control 1	TA0CCTL1	04h
Capture/compare control 2	TA0CCTL2	06h
Capture/compare control 3	TA0CCTL3	08h
Capture/compare control 4	TA0CCTL4	0Ah
TA0 counter register	TA0R	10h
Capture/compare register 0	TA0CCR0	12h
Capture/compare register 1	TA0CCR1	14h
Capture/compare register 2	TA0CCR2	16h
Capture/compare register 3	TA0CCR3	18h
Capture/compare register 4	TA0CCR4	1Ah
TA0 expansion register 0	TA0EX0	20h
TA0 interrupt vector	TA0IV	2Eh

Table 36. TA1 Registers (Base Address: 0380h)

REGISTER DESCRIPTION	REGISTER	OFFSET
TA1 control	TA1CTL	00h
Capture/compare control 0	TA1CCTL0	02h
Capture/compare control 1	TA1CCTL1	04h
Capture/compare control 2	TA1CCTL2	06h
TA1 counter register	TA1R	10h
Capture/compare register 0	TA1CCR0	12h
Capture/compare register 1	TA1CCR1	14h
Capture/compare register 2	TA1CCR2	16h
TA1 expansion register 0	TA1EX0	20h
TA1 interrupt vector	TA1IV	2Eh

Table 37. Real-Time Clock Registers (Base Address: 04A0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
RTC control 0	RTCCTL0	00h
RTC control 1	RTCCTL1	01h
RTC control 2	RTCCTL2	02h
RTC control 3	RTCCTL3	03h

Table 37. Real-Time Clock Registers (Base Address: 04A0h) (continued)

REGISTER DESCRIPTION	REGISTER	OFFSET
RTC prescaler 0 control	RTCPS0CTL	08h
RTC prescaler 1 control	RTCPS1CTL	0Ah
RTC prescaler 0	RTCPS0	0Ch
RTC prescaler 1	RTCPS1	0Dh
RTC interrupt vector word	RTCIV	0Eh
RTC seconds/counter register 1	RTCSEC/RTCNT1	10h
RTC minutes/counter register 2	RTCMIN/RTCNT2	11h
RTC hours/counter register 3	RTCHOUR/RTCNT3	12h
RTC day of week/counter register 4	RTCDOW/RTCNT4	13h
RTC days	RTCDAY	14h
RTC month	RTCMON	15h
RTC year low	RTCYEARL	16h
RTC year high	RTCYEARH	17h
RTC alarm minutes	RTCAMIN	18h
RTC alarm hours	RTCAHOUR	19h
RTC alarm day of week	RTCADOW	1Ah
RTC alarm days	RTCADAY	1Bh

Table 38. 32-Bit Hardware Multiplier Registers (Base Address: 04C0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
16-bit operand 1 – multiply	MPY	00h
16-bit operand 1 – signed multiply	MPYS	02h
16-bit operand 1 – multiply accumulate	MAC	04h
16-bit operand 1 – signed multiply accumulate	MACS	06h
16-bit operand 2	OP2	08h
16 × 16 result low word	RESLO	0Ah
16 × 16 result high word	RESHI	0Ch
16 × 16 sum extension register	SUMEXT	0Eh
32-bit operand 1 – multiply low word	MPY32L	10h
32-bit operand 1 – multiply high word	MPY32H	12h
32-bit operand 1 – signed multiply low word	MPYS32L	14h
32-bit operand 1 – signed multiply high word	MPYS32H	16h
32-bit operand 1 – multiply accumulate low word	MAC32L	18h
32-bit operand 1 – multiply accumulate high word	MAC32H	1Ah
32-bit operand 1 – signed multiply accumulate low word	MACS32L	1Ch
32-bit operand 1 – signed multiply accumulate high word	MACS32H	1Eh
32-bit operand 2 – low word	OP2L	20h
32-bit operand 2 – high word	OP2H	22h
32 × 32 result 0 – least significant word	RES0	24h
32 × 32 result 1	RES1	26h
32 × 32 result 2	RES2	28h
32 × 32 result 3 – most significant word	RES3	2Ah
MPY32 control register 0	MPY32CTL0	2Ch

Table 39. DMA Module Control Registers (Base Address: 0500h)

REGISTER DESCRIPTION	REGISTER	OFFSET
DMA module control 0	DMACTL0	00h
DMA module control 1	DMACTL1	02h
DMA module control 2	DMACTL2	04h
DMA module control 3	DMACTL3	06h
DMA module control 4	DMACTL4	08h
DMA interrupt vector	DMAIV	0Ah

Table 40. DMA Channel 0 Registers (Base Address: 0510h)

REGISTER DESCRIPTION	REGISTER	OFFSET
DMA channel 0 control	DMA0CTL	00h
DMA channel 0 source address low	DMA0SAL	02h
DMA channel 0 source address high	DMA0SAH	04h
DMA channel 0 destination address low	DMA0DAL	06h
DMA channel 0 destination address high	DMA0DAH	08h
DMA channel 0 transfer size	DMA0SZ	0Ah

Table 41. DMA Channel 1 Registers (Base Address: 0520h)

REGISTER DESCRIPTION	REGISTER	OFFSET
DMA channel 1 control	DMA1CTL	00h
DMA channel 1 source address low	DMA1SAL	02h
DMA channel 1 source address high	DMA1SAH	04h
DMA channel 1 destination address low	DMA1DAL	06h
DMA channel 1 destination address high	DMA1DAH	08h
DMA channel 1 transfer size	DMA1SZ	0Ah

Table 42. DMA Channel 2 Registers (Base Address: 0530h)

REGISTER DESCRIPTION	REGISTER	OFFSET
DMA channel 2 control	DMA2CTL	00h
DMA channel 2 source address low	DMA2SAL	02h
DMA channel 2 source address high	DMA2SAH	04h
DMA channel 2 destination address low	DMA2DAL	06h
DMA channel 2 destination address high	DMA2DAH	08h
DMA channel 2 transfer size	DMA2SZ	0Ah

Table 43. USCI_A0 Registers (Base Address: 05C0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
USCI control 1	UCA0CTL1	00h
USCI control 0	UCA0CTL0	01h
USCI baud rate 0	UCA0BR0	06h
USCI baud rate 1	UCA0BR1	07h
USCI modulation control	UCA0MCTL	08h
USCI status	UCA0STAT	0Ah
USCI receive buffer	UCA0RXBUF	0Ch
USCI transmit buffer	UCA0TXBUF	0Eh
USCI LIN control	UCA0ABCTL	10h
USCI IrDA transmit control	UCA0IRTCTL	12h
USCI IrDA receive control	UCA0IRRCTL	13h
USCI interrupt enable	UCA0IE	1Ch
USCI interrupt flags	UCA0IFG	1Dh
USCI interrupt vector word	UCA0IV	1Eh

Table 44. USCI_B0 Registers (Base Address: 05E0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
USCI synchronous control 1	UCB0CTL1	00h
USCI synchronous control 0	UCB0CTL0	01h
USCI synchronous bit rate 0	UCB0BR0	06h
USCI synchronous bit rate 1	UCB0BR1	07h
USCI synchronous status	UCB0STAT	0Ah
USCI synchronous receive buffer	UCB0RXBUF	0Ch
USCI synchronous transmit buffer	UCB0TXBUF	0Eh
USCI I2C own address	UCB0I2COA	10h
USCI I2C slave address	UCB0I2CSA	12h
USCI interrupt enable	UCB0IE	1Ch
USCI interrupt flags	UCB0IFG	1Dh
USCI interrupt vector word	UCB0IV	1Eh

Table 45. ADC12_A Registers (Base Address: 0700h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Control register 0	ADC12CTL0	00h
Control register 1	ADC12CTL1	02h
Control register 2	ADC12CTL2	04h
Interrupt-flag register	ADC12IFG	0Ah
Interrupt-enable register	ADC12IE	0Ch
Interrupt-vector-word register	ADC12IV	0Eh
ADC memory-control register 0	ADC12MCTL0	10h
ADC memory-control register 1	ADC12MCTL1	11h
ADC memory-control register 2	ADC12MCTL2	12h
ADC memory-control register 3	ADC12MCTL3	13h
ADC memory-control register 4	ADC12MCTL4	14h
ADC memory-control register 5	ADC12MCTL5	15h
ADC memory-control register 6	ADC12MCTL6	16h
ADC memory-control register 7	ADC12MCTL7	17h
ADC memory-control register 8	ADC12MCTL8	18h
ADC memory-control register 9	ADC12MCTL9	19h
ADC memory-control register 10	ADC12MCTL10	1Ah
ADC memory-control register 11	ADC12MCTL11	1Bh
ADC memory-control register 12	ADC12MCTL12	1Ch
ADC memory-control register 13	ADC12MCTL13	1Dh
ADC memory-control register 14	ADC12MCTL14	1Eh
ADC memory-control register 15	ADC12MCTL15	1Fh
Conversion memory 0	ADC12MEM0	20h
Conversion memory 1	ADC12MEM1	22h
Conversion memory 2	ADC12MEM2	24h
Conversion memory 3	ADC12MEM3	26h
Conversion memory 4	ADC12MEM4	28h
Conversion memory 5	ADC12MEM5	2Ah
Conversion memory 6	ADC12MEM6	2Ch
Conversion memory 7	ADC12MEM7	2Eh
Conversion memory 8	ADC12MEM8	30h
Conversion memory 9	ADC12MEM9	32h
Conversion memory 10	ADC12MEM10	34h
Conversion memory 11	ADC12MEM11	36h
Conversion memory 12	ADC12MEM12	38h
Conversion memory 13	ADC12MEM13	3Ah
Conversion memory 14	ADC12MEM14	3Ch
Conversion memory 15	ADC12MEM15	3Eh

Table 46. Comparator_B Registers (Base Address: 08C0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Comp_B control register 0	CBCTL0	00h
Comp_B control register 1	CBCTL1	02h
Comp_B control register 2	CBCTL2	04h
Comp_B control register 3	CBCTL3	06h
Comp_B interrupt register	CBINT	0Ch
Comp_B interrupt vector word	CBIV	0Eh

Table 47. AES Accelerator Registers (Base Address: 09C0h)

REGISTER DESCRIPTION	REGISTER	OFFSET
AES accelerator control register 0	AESACTL0	00h
Reserved		02h
AES accelerator status register	AESASTAT	04h
AES accelerator key register	AESAKEY	06h
AES accelerator data in register	AESADIN	008h
AES accelerator data out register	AESADOUT	00Ah

Table 48. Radio Interface Registers (Base Address: 0F00h)

REGISTER DESCRIPTION	REGISTER	OFFSET
Radio interface control register 0	RF1AIFCTL0	00h
Radio interface control register 1	RF1AIFCTL1	02h
Radio interface error flag register	RF1AIFERR	06h
Radio interface error vector word	RF1AIFERRV	0Ch
Radio interface interrupt vector word	RF1AIFIV	0Eh
Radio instruction word register	RF1AINSTRW	10h
Radio instruction word register, 1-byte auto-read	RF1AINSTR1W	12h
Radio instruction word register, 2-byte auto-read	RF1AINSTR2W	14h
Radio data in register	RF1ADINW	16h
Radio status word register	RF1ASTATW	20h
Radio status word register, 1-byte auto-read	RF1ASTAT1W	22h
Radio status word register, 2-byte auto-read	RF1AISTAT2W	24h
Radio data out register	RF1ADOUTW	28h
Radio data out register, 1-byte auto-read	RF1ADOUT1W	2Ah
Radio data out register, 2-byte auto-read	RF1ADOUT2W	2Ch
Radio core signal input register	RF1AIN	30h
Radio core interrupt flag register	RF1AIFG	32h
Radio core interrupt edge select register	RF1AIES	34h
Radio core interrupt enable register	RF1AIE	36h
Radio core interrupt vector word	RF1AIV	38h

Absolute Maximum Ratings⁽¹⁾

over operating free-air temperature range (unless otherwise noted)

Voltage applied at DVCC/VBAT and AVCC pins to V _{SS}	–0.3 V to 3.6 V
Voltage applied to any pin (excluding V _{CORE} , RF_P, RF_N, and R_BIAS) ⁽²⁾	–0.3 V to (V _{CC} + 0.3 V), 4.1 V Max
Voltage applied to V _{CORE} , RF_P, RF_N, and R_BIAS ⁽²⁾	–0.3 V to 2 V
Input RF level at pins RF_P and RF_N	10 dBm
Diode current at any device terminal	±2 mA
Storage temperature range ⁽³⁾ , T _{stg}	–55°C to 125°C
Maximum junction temperature, T _J	95°C

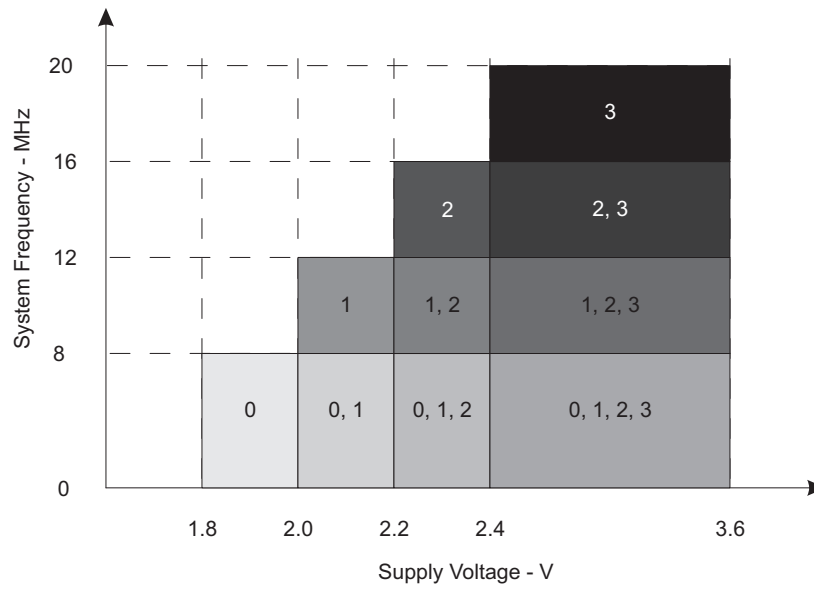
- (1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltages referenced to V_{SS}.
- (3) Higher temperature may be applied during board soldering according to the current JEDEC J-STD-020 specification with peak reflow temperatures not higher than classified on the device label on the shipping boxes or reels.

Recommended Operating Conditions

Typical values are specified at V_{CC} = 3.3 V and T_A = 25°C (unless otherwise noted)

			MIN	NOM	MAX	UNIT
V _{CC}	Supply voltage range applied at all DVCC and AVCC pins ⁽¹⁾ during program execution and flash programming with PMM default settings. Radio is not operational with PMMCOREVx = 0, 1. ⁽²⁾⁽³⁾	PMMCOREVx = 0 (default after POR)	1.8		3.6	V
		PMMCOREVx = 1	2.0		3.6	V
V _{CC}	Supply voltage range applied at all DVCC and AVCC pins ⁽¹⁾ during program execution, flash programming and radio operation with PMM default settings. ⁽²⁾⁽³⁾	PMMCOREVx = 2	2.2		3.6	V
		PMMCOREVx = 3	2.4		3.6	V
V _{CC}	Supply voltage range applied at all DVCC and AVCC pins ⁽¹⁾ during program execution, flash programming and radio operation with PMMCOREVx = 2, high-side SVS level lowered (SVSHRVLx = SVSHRRRLx = 1) or high-side SVS disabled (SVSHE = 0). ^{(4) (2)(3)}	PMMCOREVx = 2, SVSHRVLx = SVSHRRRLx = 1 or SVSHE = 0	2.0		3.6	V
V _{SS}	Supply voltage applied at the exposed die attach VSS and AVSS pin			0		V
T _A	Operating free-air temperature		–40		85	°C
T _J	Operating junction temperature		–40		85	°C
C _{VCORE}	Recommended capacitor at V _{CORE}			470		nF
C _{DVCC} / C _{VCORE}	Capacitor ratio of capacitor at DVCC to capacitor at V _{CORE}		10			
f _{SYSTEM}	Processor (MCLK) frequency ⁽⁵⁾ (see Figure 4)	PMMCOREVx = 0 (default condition)	0		8	MHz
		PMMCOREVx = 1	0		12	MHz
		PMMCOREVx = 2	0		16	MHz
		PMMCOREVx = 3	0		20	MHz
P _{INT}	Internal power dissipation		V _{CC} × I _(DVCC)			W
P _{IO}	I/O power dissipation of I/O pins powered by DVCC		(V _{CC} – V _{IOH}) × I _{IOH} + V _{IOH} × I _{IOL}			W
P _{MAX}	Maximum allowed power dissipation, P _{MAX} > P _{IO} + P _{INT}		(T _J – T _A) / θ _{JA}			W

- (1) It is recommended to power AVCC and DVCC from the same source. A maximum difference of 0.3 V between AVCC and DVCC can be tolerated during power up and operation.
- (2) Modules may have a different supply voltage range specification. See the specification of the respective module in this data sheet.
- (3) The minimum supply voltage is defined by the supervisor SVS levels when it is enabled. See the [PMM, SVS High Side](#) threshold parameters for the exact values and further details.
- (4) Lowering the high-side SVS level or disabling the high-side SVS might cause the LDO to operate out of regulation but the core voltage will still stay within its limits and is still supervised by the low-side SVS ensuring reliable operation.
- (5) Modules may have a different maximum input clock specification. See the specification of the respective module in this data sheet.



The numbers within the fields denote the supported PMMCOREVx settings.

Figure 4. Maximum System Frequency

Electrical Characteristics

Active Mode Supply Current Into V_{CC} Excluding External Current

over recommended operating free-air temperature (unless otherwise noted)^{(1) (2) (3)}

PARAMETER	EXECUTION MEMORY	V _{CC}	PMMCOREVx	FREQUENCY (f _{DCO} = f _{MCLK} = f _{SMCLK})								UNIT		
				1 MHz		8 MHz		12 MHz		16 MHz			20 MHz	
				TYP	MAX	TYP	MAX	TYP	MAX	TYP	MAX		TYP	MAX
I _{AM, Flash} ⁽⁴⁾	Flash	3 V	0	0.23	0.26	1.35	1.60						mA	
			1	0.25	0.28	1.55		2.30	2.65					
			2	0.27	0.30	1.75		2.60		3.45	3.90			
			3	0.28	0.32	1.85		2.75		3.65		4.55		5.10
I _{AM, RAM} ⁽⁵⁾	RAM	3 V	0	0.18	0.20	0.95	1.10						mA	
			1	0.20	0.22	1.10		1.60	1.85					
			2	0.21	0.24	1.20		1.80		2.40	2.70			
			3	0.22	0.25	1.30		1.90		2.50		3.10		3.60

(1) All inputs are tied to 0 V or to V_{CC} . Outputs do not source or sink any current.

(2) The currents are characterized with a Micro Crystal MS1V-T1K crystal with a load capacitance of 12.5 pF. The internal and external load capacitance are chosen to closely match the required 12.5 pF.

(3) Characterized with program executing typical data processing.

$f_{ACLK} = 32786 \text{ Hz}$, $f_{DCO} = f_{MCLK} = f_{SMCLK}$ at specified frequency.

$XTS = CPUOFF = SCG0 = SCG1 = OSCOFF = SMCLKOFF = 0$.

(4) Active mode supply current when program executes in flash at a nominal supply voltage of 3 V.

(5) Active mode supply current when program executes in RAM at a nominal supply voltage of 3 V.

Typical Characteristics - Active Mode Supply Currents

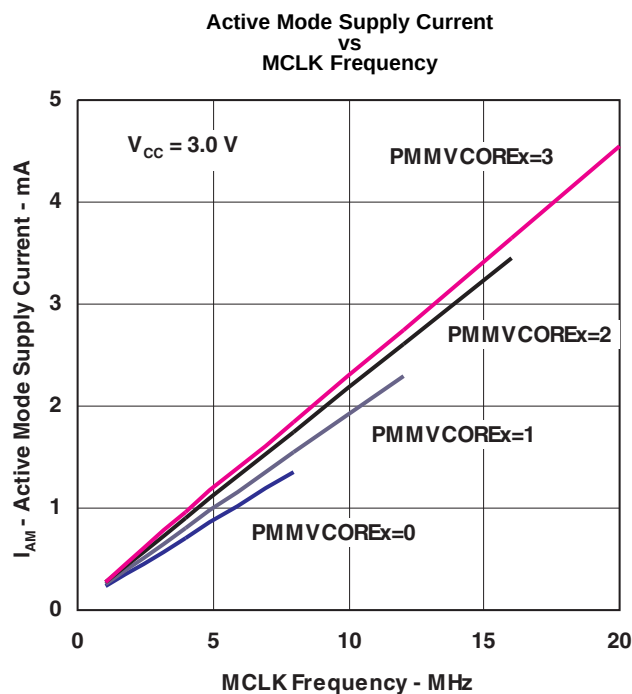


Figure 5.

Low-Power Mode Supply Currents (Into V_{CC}) Excluding External Current

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)^{(1) (2)}

PARAMETER	V _{CC}	PMMCOREVx	Temperature (T _A)								UNIT
			-40°C		25°C		60°C		85°C		
			TYP	MAX	TYP	MAX	TYP	MAX	TYP	MAX	
I _{LPM0,1MHz} Low-power mode 0 ^{(3) (4)}	2.2 V	0	80	100	80	100	80	100	80	100	μA
	3 V	3	90	110	90	110	90	110	90	110	
I _{LPM2} Low-power mode 2 ^{(5) (4)}	2.2 V	0	6.5	11	6.5	11	6.5	11	6.5	11	μA
	3 V	3	7.5	12	7.5	12	7.5	12	7.5	12	
I _{LPM3,XT1LF} Low-power mode 3, crystal mode ^{(6) (4)}	3 V	0	1.8		2.0	2.6	3.0	4.0	4.4	5.9	μA
		1	1.9		2.1		3.2		4.8		
		2	2.0		2.2		3.4		5.1		
		3	2.0		2.2	2.9	3.5	4.8	5.3	7.4	
I _{LPM3,VLO} Low-power mode 3, VLO mode ^{(7) (4)}	3 V	0	0.9		1.1	2.3	2.1	3.7	3.5	5.6	μA
		1	1.0		1.2		2.3		3.9		
		2	1.1		1.3		2.5		4.2		
		3	1.1		1.3	2.6	2.6	4.5	4.4	7.1	
I _{LPM4} Low-power mode 4 ^{(8) (4)}	3 V	0	0.8		1.0	2.2	2.0	3.6	3.4	5.5	μA
		1	0.9		1.1		2.2		3.8		
		2	1.0		1.2		2.4		4.1		
		3	1.0		1.2	2.5	2.5	4.4	4.3	7.0	

- (1) All inputs are tied to 0 V or to V_{CC} . Outputs do not source or sink any current.
- (2) The currents are characterized with a Micro Crystal MS1V-T1K crystal with a load capacitance of 12.5 pF. The internal and external load capacitance are chosen to closely match the required 12.5 pF.
- (3) Current for watchdog timer clocked by SMCLK included. ACLK = low frequency crystal operation (XTS = 0, XT1DRIVE_x = 0). CPUOFF = 1, SCG0 = 0, SCG1 = 0, OSCOFF = 0 (LPM0); f_{ACLK} = 32768 Hz, f_{MCLK} = 0 MHz, f_{SMCLK} = f_{DCO} = 1 MHz
- (4) Current for brownout, high side supervisor (SVSH) normal mode included. Low side supervisor and monitors disabled (SVSL, SVM_L). High side monitor disabled (SVM_H). RAM retention enabled.
- (5) Current for watchdog timer and RTC clocked by ACLK included. ACLK = low frequency crystal operation (XTS = 0, XT1DRIVE_x = 0). CPUOFF = 1, SCG0 = 0, SCG1 = 1, OSCOFF = 0 (LPM2); f_{ACLK} = 32768 Hz, f_{MCLK} = 0 MHz, f_{SMCLK} = f_{DCO} = 0 MHz; DCO setting = 1 MHz operation, DCO bias generator enabled.
- (6) Current for watchdog timer and RTC clocked by ACLK included. ACLK = low frequency crystal operation (XTS = 0, XT1DRIVE_x = 0). CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 0 (LPM3); f_{ACLK} = 32768 Hz, f_{MCLK} = f_{SMCLK} = f_{DCO} = 0 MHz
- (7) Current for watchdog timer and RTC clocked by ACLK included. ACLK = VLO. CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 0 (LPM3); f_{ACLK} = f_{VLO} , f_{MCLK} = f_{SMCLK} = f_{DCO} = 0 MHz
- (8) CPUOFF = 1, SCG0 = 1, SCG1 = 1, OSCOFF = 1 (LPM4); f_{DCO} = f_{ACLK} = f_{MCLK} = f_{SMCLK} = 0 MHz

Typical Characteristics - Low-Power Mode Supply Currents

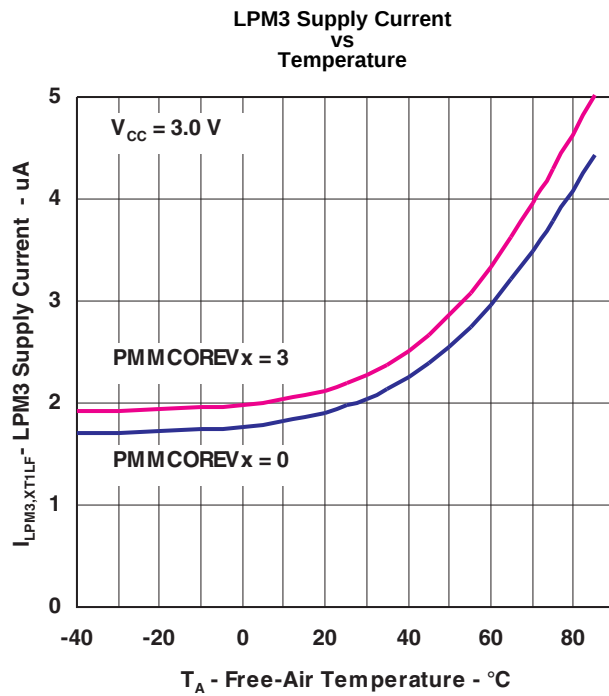


Figure 6.

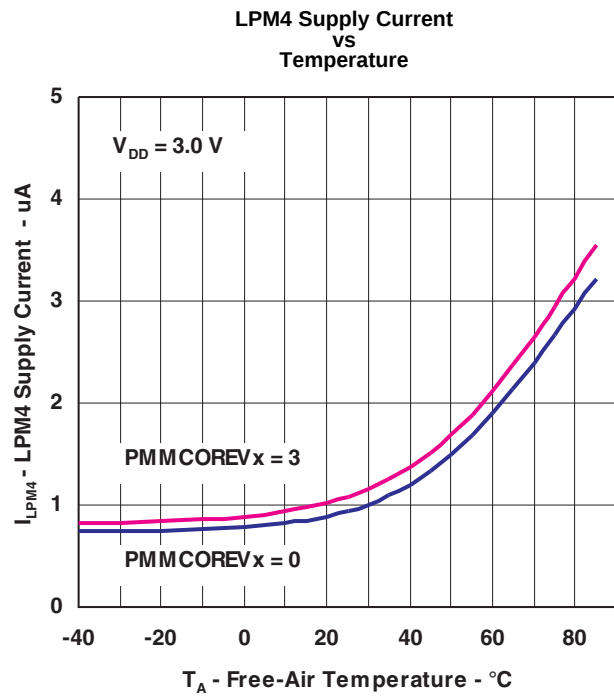


Figure 7.

Digital Inputs

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
V _{IT+} Positive-going input threshold voltage		1.8 V	0.80		1.40	V
		3 V	1.50		2.10	
V _{IT-} Negative-going input threshold voltage		1.8 V	0.45		1.00	V
		3 V	0.75		1.65	
V _{hys} Input voltage hysteresis (V _{IT+} – V _{IT-})		1.8 V	0.3		0.8	V
		3 V	0.4		1.0	
R _{Pull} Pullup or pulldown resistor	For pullup: V _{IN} = V _{SS} For pulldown: V _{IN} = V _{CC}		20	35	50	kΩ
C _I Input capacitance	V _{IN} = V _{SS} or V _{CC}			5		pF
I _{Ikg(Px.y)} High-impedance leakage current	(1) (2)	1.8 V, 3 V			±50	nA
t _(int) External interrupt timing (external trigger pulse duration to set interrupt flag) ⁽³⁾	Ports with interrupt capability (see block diagram and terminal function descriptions).	1.8 V, 3 V	20			ns

(1) The leakage current is measured with V_{SS} or V_{CC} applied to the corresponding pin(s), unless otherwise noted.

(2) The leakage of the digital port pins is measured individually. The port pin is selected for input and the pullup or pulldown resistor is disabled.

(3) An external signal sets the interrupt flag every time the minimum interrupt pulse duration t_(int) is met. It may be set by trigger signals shorter than t_(int).

Digital Outputs

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	MAX	UNIT
V _{OH} High-level output voltage, Reduced Drive Strength ⁽¹⁾	I _(OHmax) = –1 mA, PxDS.y = 0 ⁽²⁾	1.8 V	V _{CC} – 0.25	V _{CC}	V
	I _(OHmax) = –3 mA, PxDS.y = 0 ⁽³⁾		V _{CC} – 0.60	V _{CC}	
	I _(OHmax) = –2 mA, PxDS.y = 0 ⁽²⁾	3 V	V _{CC} – 0.25	V _{CC}	
	I _(OHmax) = –6 mA, PxDS.y = 0 ⁽³⁾		V _{CC} – 0.60	V _{CC}	
V _{OL} Low-level output voltage, Reduced Drive Strength ⁽¹⁾	I _(OLmax) = 1 mA, PxDS.y = 0 ⁽²⁾	1.8 V	V _{SS}	V _{SS} + 0.25	V
	I _(OLmax) = 3 mA, PxDS.y = 0 ⁽³⁾		V _{SS}	V _{SS} + 0.60	
	I _(OLmax) = 2 mA, PxDS.y = 0 ⁽²⁾	3 V	V _{SS}	V _{SS} + 0.25	
	I _(OLmax) = 6 mA, PxDS.y = 0 ⁽³⁾		V _{SS}	V _{SS} + 0.60	
V _{OH} High-level output voltage, Full Drive Strength	I _(OHmax) = –3 mA, PxDS.y = 1 ⁽²⁾	1.8 V	V _{CC} – 0.25	V _{CC}	V
	I _(OHmax) = –10 mA, PxDS.y = 1 ⁽³⁾		V _{CC} – 0.60	V _{CC}	
	I _(OHmax) = –5 mA, PxDS.y = 1 ⁽²⁾	3 V	V _{CC} – 0.25	V _{CC}	
	I _(OHmax) = –15 mA, PxDS.y = 1 ⁽³⁾		V _{CC} – 0.60	V _{CC}	
V _{OL} Low-level output voltage, Full Drive Strength	I _(OLmax) = 3 mA, PxDS.y = 1 ⁽²⁾	1.8 V	V _{SS}	V _{SS} + 0.25	V
	I _(OLmax) = 10 mA, PxDS.y = 1 ⁽³⁾		V _{SS}	V _{SS} + 0.60	
	I _(OLmax) = 5 mA, PxDS.y = 1 ⁽²⁾	3 V	V _{SS}	V _{SS} + 0.25	
	I _(OLmax) = 15 mA, PxDS.y = 1 ⁽³⁾		V _{SS}	V _{SS} + 0.60	
f _{Px.y} Port output frequency (with load)	C _L = 20 pF, R _L ⁽⁴⁾ ⁽⁵⁾	V _{CC} = 1.8 V PMMCOREVx = 0		16	MHz
		V _{CC} = 3 V PMMCOREVx = 2		25	
f _{Port_CLK} Clock output frequency	C _L = 20 pF ⁽⁵⁾	V _{CC} = 1.8 V PMMCOREVx = 0		16	MHz
		V _{CC} = 3 V PMMCOREVx = 2		25	

(1) Selecting reduced drive strength may reduce EMI.

(2) The maximum total current, I_(OHmax) and I_(OLmax), for all outputs combined should not exceed ±48 mA to hold the maximum voltage drop specified.

(3) The maximum total current, I_(OHmax) and I_(OLmax), for all outputs combined should not exceed ±100 mA to hold the maximum voltage drop specified.

(4) A resistive divider with 2 × R1 between V_{CC} and V_{SS} is used as load. The output is connected to the center tap of the divider. For full drive strength, R1 = 550 Ω. For reduced drive strength, R1 = 1.6 kΩ. C_L = 20 pF is connected to the output to V_{SS}.

(5) The output voltage reaches at least 10% and 90% V_{CC} at the specified toggle frequency.

Typical Characteristics - Outputs, Reduced Drive Strength (PxDS.y = 0)

TYPICAL LOW-LEVEL OUTPUT CURRENT
vs
LOW-LEVEL OUTPUT VOLTAGE

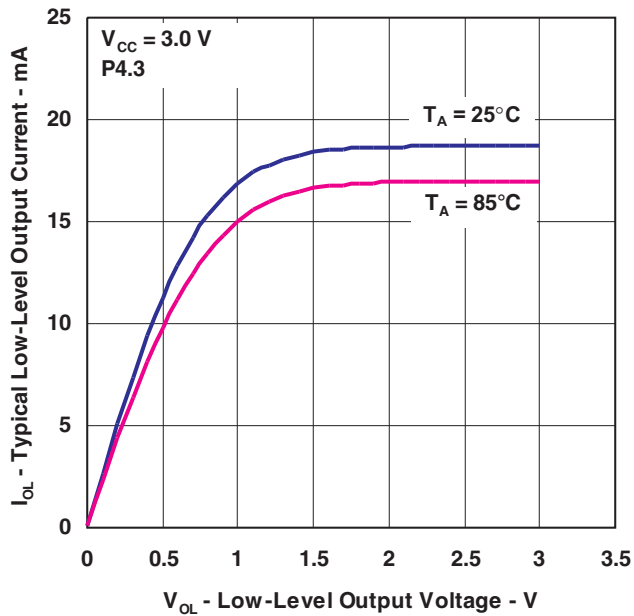


Figure 8.

TYPICAL LOW-LEVEL OUTPUT CURRENT
vs
LOW-LEVEL OUTPUT VOLTAGE

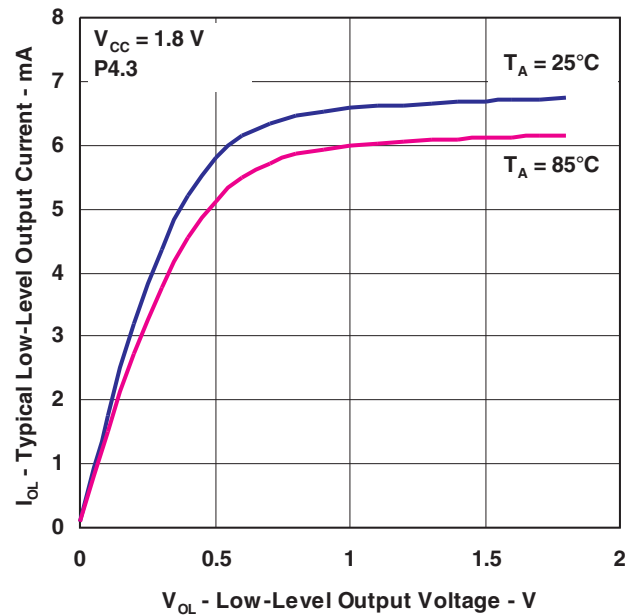


Figure 9.

TYPICAL HIGH-LEVEL OUTPUT CURRENT
vs
HIGH-LEVEL OUTPUT VOLTAGE

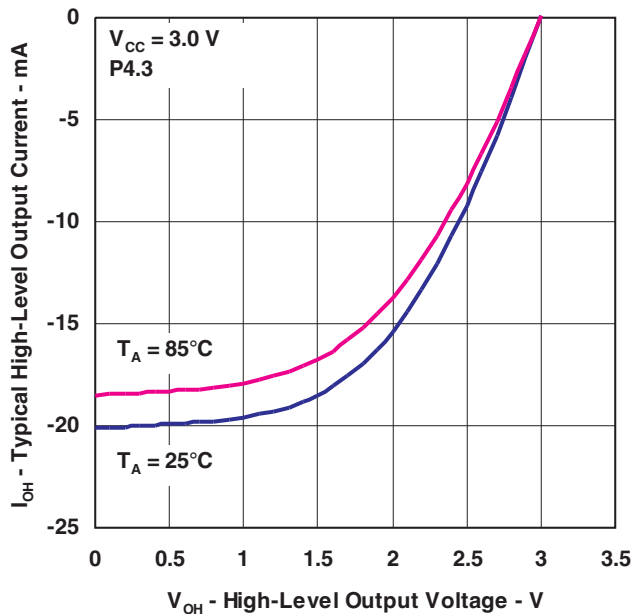


Figure 10.

TYPICAL HIGH-LEVEL OUTPUT CURRENT
vs
HIGH-LEVEL OUTPUT VOLTAGE

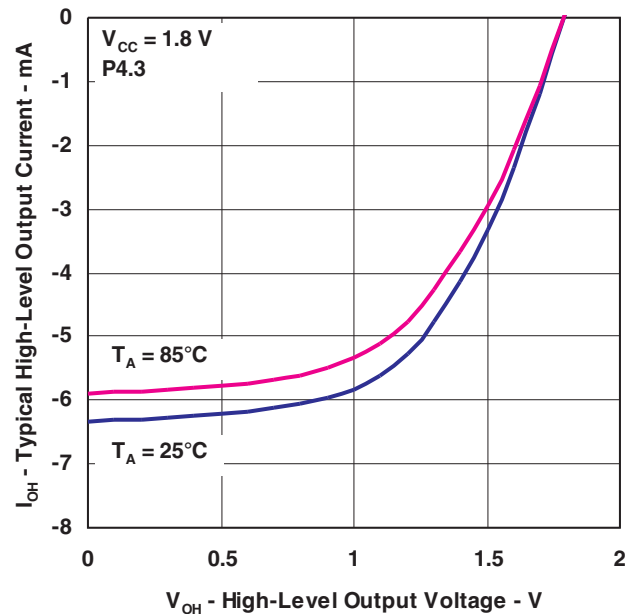


Figure 11.

Typical Characteristics - Outputs, Full Drive Strength (PxDS.y = 1)

TYPICAL LOW-LEVEL OUTPUT CURRENT
vs
LOW-LEVEL OUTPUT VOLTAGE

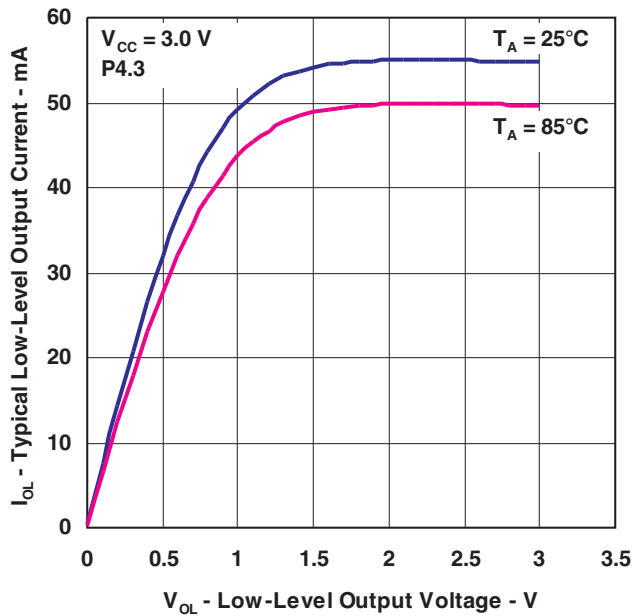


Figure 12.

TYPICAL LOW-LEVEL OUTPUT CURRENT
vs
LOW-LEVEL OUTPUT VOLTAGE

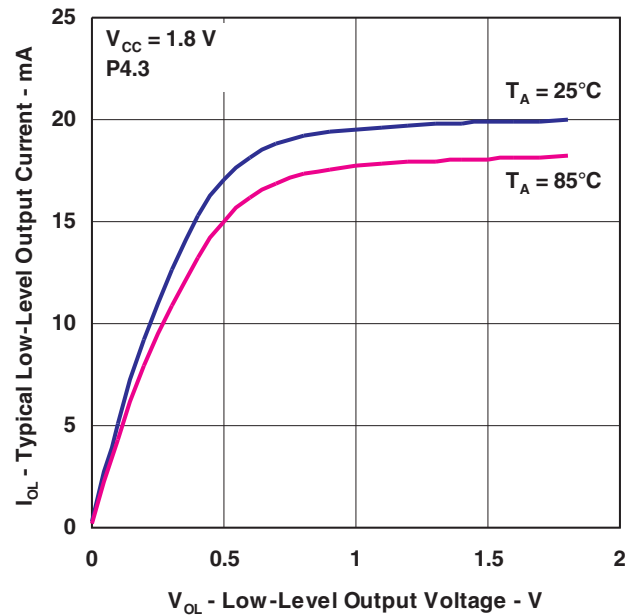


Figure 13.

TYPICAL HIGH-LEVEL OUTPUT CURRENT
vs
HIGH-LEVEL OUTPUT VOLTAGE

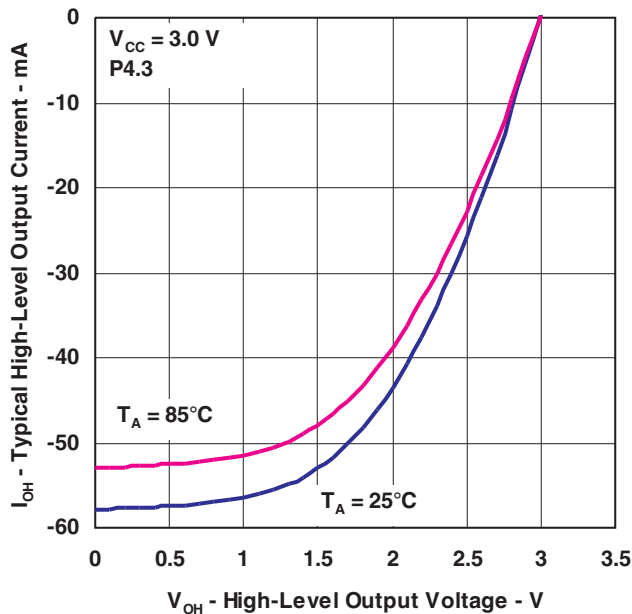


Figure 14.

TYPICAL HIGH-LEVEL OUTPUT CURRENT
vs
HIGH-LEVEL OUTPUT VOLTAGE

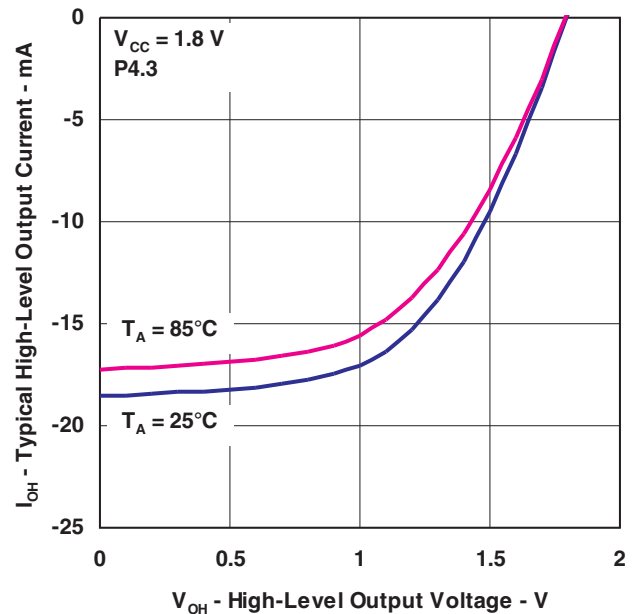


Figure 15.

Crystal Oscillator, XT1, Low-Frequency Mode⁽¹⁾

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
$\Delta I_{DVCC,LF}$	Differential XT1 oscillator crystal current consumption from lowest drive setting, LF mode	f _{OSC} = 32768 Hz, XTS = 0, XT1BYPASS = 0, XT1DRIVE _x = 1, T _A = 25°C	3 V	0.075			μA
		f _{OSC} = 32768 Hz, XTS = 0, XT1BYPASS = 0, XT1DRIVE _x = 2, T _A = 25°C		0.170			
		f _{OSC} = 32768 Hz, XTS = 0, XT1BYPASS = 0, XT1DRIVE _x = 3, T _A = 25°C		0.290			
f _{XT1,LF0}	XT1 oscillator crystal frequency, LF mode	XTS = 0, XT1BYPASS = 0		32768			Hz
f _{XT1,LF,SW}	XT1 oscillator logic-level square-wave input frequency, LF mode	XTS = 0, XT1BYPASS = 1 ⁽²⁾ ⁽³⁾		10	32.768	50	kHz
OA _{LF}	Oscillation allowance for LF crystals ⁽⁴⁾	XTS = 0, XT1BYPASS = 0, XT1DRIVE _x = 0, f _{XT1,LF} = 32768 Hz, C _{L,eff} = 6 pF		210			kΩ
		XTS = 0, XT1BYPASS = 0, XT1DRIVE _x = 1, f _{XT1,LF} = 32768 Hz, C _{L,eff} = 12 pF		300			
C _{L,eff}	Integrated effective load capacitance, LF mode ⁽⁵⁾	XTS = 0, XCAP _x = 0 ⁽⁶⁾		2			pF
		XTS = 0, XCAP _x = 1		5.5			
		XTS = 0, XCAP _x = 2		8.5			
		XTS = 0, XCAP _x = 3		12.0			
Duty cycle, LF mode		XTS = 0, Measured at ACLK, f _{XT1,LF} = 32768 Hz		30		70	%
f _{Fault,LF}	Oscillator fault frequency, LF mode ⁽⁷⁾	XTS = 0 ⁽⁸⁾		10		10000	Hz
t _{START,LF}	Startup time, LF mode	f _{OSC} = 32768 Hz, XTS = 0, XT1BYPASS = 0, XT1DRIVE _x = 0, T _A = 25°C, C _{L,eff} = 6 pF	3 V	1000			ms
		f _{OSC} = 32768 Hz, XTS = 0, XT1BYPASS = 0, XT1DRIVE _x = 3, T _A = 25°C, C _{L,eff} = 12 pF		500			

- (1) To improve EMI on the XT1 oscillator, the following guidelines should be observed.
 - (a) Keep the trace between the device and the crystal as short as possible.
 - (b) Design a good ground plane around the oscillator pins.
 - (c) Prevent crosstalk from other clock or data lines into oscillator pins XIN and XOUT.
 - (d) Avoid running PCB traces underneath or adjacent to the XIN and XOUT pins.
 - (e) Use assembly materials and praxis to avoid any parasitic load on the oscillator XIN and XOUT pins.
 - (f) If conformal coating is used, ensure that it does not induce capacitive or resistive leakage between the oscillator pins.
- (2) When XT1BYPASS is set, XT1 circuits are automatically powered down. Input signal is a digital square wave with parametrics defined in the Schmitt-trigger Inputs section of this datasheet.
- (3) Maximum frequency of operation of the entire device cannot be exceeded.
- (4) Oscillation allowance is based on a safety factor of 5 for recommended crystals. The oscillation allowance is a function of the XT1DRIVE_x settings and the effective load. In general, comparable oscillator allowance can be achieved based on the following guidelines, but should be evaluated based on the actual crystal selected for the application:
 - (a) For XT1DRIVE_x = 0, C_{L,eff} ≤ 6 pF
 - (b) For XT1DRIVE_x = 1, 6 pF ≤ C_{L,eff} ≤ 9 pF
 - (c) For XT1DRIVE_x = 2, 6 pF ≤ C_{L,eff} ≤ 10 pF
 - (d) For XT1DRIVE_x = 3, C_{L,eff} ≥ 6 pF
- (5) Includes parasitic bond and package capacitance (approximately 2 pF per pin).
Because the PCB adds additional capacitance, it is recommended to verify the correct load by measuring the ACLK frequency. For a correct setup, the effective load capacitance should always match the specification of the used crystal.
- (6) Requires external capacitors at both terminals. Values are specified by crystal manufacturers.
- (7) Frequencies below the MIN specification set the fault flag. Frequencies above the MAX specification do not set the fault flag. Frequencies in between might set the flag.
- (8) Measured with logic-level input frequency but also applies to operation with crystals.

Internal Very-Low-Power Low-Frequency Oscillator (VLO)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
f _{VLO} VLO frequency	Measured at ACLK	1.8 V to 3.6 V	6	9.4	14	kHz
df _{VLO} /dT VLO frequency temperature drift	Measured at ACLK ⁽¹⁾	1.8 V to 3.6 V		0.5		%/°C
df _{VLO} /dV _{CC} VLO frequency supply voltage drift	Measured at ACLK ⁽²⁾	1.8 V to 3.6 V		4		%/V
Duty cycle	Measured at ACLK	1.8 V to 3.6 V	40	50	60	%

(1) Calculated using the box method: (MAX(-40 to 85°C) – MIN(-40 to 85°C)) / MIN(-40 to 85°C) / (85°C – (–40°C))

(2) Calculated using the box method: (MAX(1.8 to 3.6 V) – MIN(1.8 to 3.6 V)) / MIN(1.8 to 3.6 V) / (3.6 V – 1.8 V)

Internal Reference, Low-Frequency Oscillator (REFO)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
I _{REFO} REFO oscillator current consumption	T _A = 25°C	1.8 V to 3.6 V		3		μA
f _{REFO} REFO frequency calibrated	Measured at ACLK	1.8 V to 3.6 V		32768		Hz
REFO absolute tolerance calibrated	Full temperature range	1.8 V to 3.6 V			±3.5	%
	T _A = 25°C	3 V			±1.5	
df _{REFO} /dT REFO frequency temperature drift	Measured at ACLK ⁽¹⁾	1.8 V to 3.6 V		0.01		%/°C
df _{REFO} /dV _{CC} REFO frequency supply voltage drift	Measured at ACLK ⁽²⁾	1.8 V to 3.6 V		1.0		%/V
Duty cycle	Measured at ACLK	1.8 V to 3.6 V	40	50	60	%
t _{START} REFO startup time	40%/60% duty cycle	1.8 V to 3.6 V		25		μs

(1) Calculated using the box method: (MAX(-40 to 85°C) – MIN(-40 to 85°C)) / MIN(-40 to 85°C) / (85°C – (–40°C))

(2) Calculated using the box method: (MAX(1.8 to 3.6 V) – MIN(1.8 to 3.6 V)) / MIN(1.8 to 3.6 V) / (3.6 V – 1.8 V)

DCO Frequency

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
f _{DCO(0,0)}	DCO frequency (0, 0) ⁽¹⁾	DCORSELx = 0, DCOx = 0, MODx = 0	0.07		0.20	MHz
f _{DCO(0,31)}	DCO frequency (0, 31) ⁽¹⁾	DCORSELx = 0, DCOx = 31, MODx = 0	0.70		1.70	MHz
f _{DCO(1,0)}	DCO frequency (1, 0) ⁽¹⁾	DCORSELx = 1, DCOx = 0, MODx = 0	0.15		0.36	MHz
f _{DCO(1,31)}	DCO frequency (1, 31) ⁽¹⁾	DCORSELx = 1, DCOx = 31, MODx = 0	1.47		3.45	MHz
f _{DCO(2,0)}	DCO frequency (2, 0) ⁽¹⁾	DCORSELx = 2, DCOx = 0, MODx = 0	0.32		0.75	MHz
f _{DCO(2,31)}	DCO frequency (2, 31) ⁽¹⁾	DCORSELx = 2, DCOx = 31, MODx = 0	3.17		7.38	MHz
f _{DCO(3,0)}	DCO frequency (3, 0) ⁽¹⁾	DCORSELx = 3, DCOx = 0, MODx = 0	0.64		1.51	MHz
f _{DCO(3,31)}	DCO frequency (3, 31) ⁽¹⁾	DCORSELx = 3, DCOx = 31, MODx = 0	6.07		14.0	MHz
f _{DCO(4,0)}	DCO frequency (4, 0) ⁽¹⁾	DCORSELx = 4, DCOx = 0, MODx = 0	1.3		3.2	MHz
f _{DCO(4,31)}	DCO frequency (4, 31) ⁽¹⁾	DCORSELx = 4, DCOx = 31, MODx = 0	12.3		28.2	MHz
f _{DCO(5,0)}	DCO frequency (5, 0) ⁽¹⁾	DCORSELx = 5, DCOx = 0, MODx = 0	2.5		6.0	MHz
f _{DCO(5,31)}	DCO frequency (5, 31) ⁽¹⁾	DCORSELx = 5, DCOx = 31, MODx = 0	23.7		54.1	MHz
f _{DCO(6,0)}	DCO frequency (6, 0) ⁽¹⁾	DCORSELx = 6, DCOx = 0, MODx = 0	4.6		10.7	MHz
f _{DCO(6,31)}	DCO frequency (6, 31) ⁽¹⁾	DCORSELx = 6, DCOx = 31, MODx = 0	39.0		88.0	MHz
f _{DCO(7,0)}	DCO frequency (7, 0) ⁽¹⁾	DCORSELx = 7, DCOx = 0, MODx = 0	8.5		19.6	MHz
f _{DCO(7,31)}	DCO frequency (7, 31) ⁽¹⁾	DCORSELx = 7, DCOx = 31, MODx = 0	60		135	MHz
S _{DCORSEL}	Frequency step between range DCORSEL and DCORSEL + 1	S _{RSEL} = f _{DCO(DCORSEL+1,DCO)} /f _{DCO(DCORSEL,DCO)}	1.2		2.3	ratio
S _{DCO}	Frequency step between tap DCO and DCO + 1	S _{DCO} = f _{DCO(DCORSEL,DCO+1)} /f _{DCO(DCORSEL,DCO)}	1.02		1.12	ratio
	Duty cycle	Measured at SMCLK	40	50	60	%
df _{DCO} /dT	DCO frequency temperature drift	f _{DCO} = 1 MHz		0.1		%/°C
df _{DCO} /dV _{CC}	DCO frequency voltage drift	f _{DCO} = 1 MHz		1.9		%/V

- (1) When selecting the proper DCO frequency range (DCORSELx), the target DCO frequency, f_{DCO} , should be set to reside within the range of $f_{\text{DCO}(n, 0), \text{MAX}} \leq f_{\text{DCO}} \leq f_{\text{DCO}(n, 31), \text{MIN}}$, where $f_{\text{DCO}(n, 0), \text{MAX}}$ represents the maximum frequency specified for the DCO frequency, range n, tap 0 (DCOx = 0) and $f_{\text{DCO}(n, 31), \text{MIN}}$ represents the minimum frequency specified for the DCO frequency, range n, tap 31 (DCOx = 31). This ensures that the target DCO frequency resides within the range selected. It should also be noted that if the actual f_{DCO} frequency for the selected range causes the FLL or the application to select tap 0 or 31, the DCO fault flag is set to report that the selected range is at its minimum or maximum tap setting.

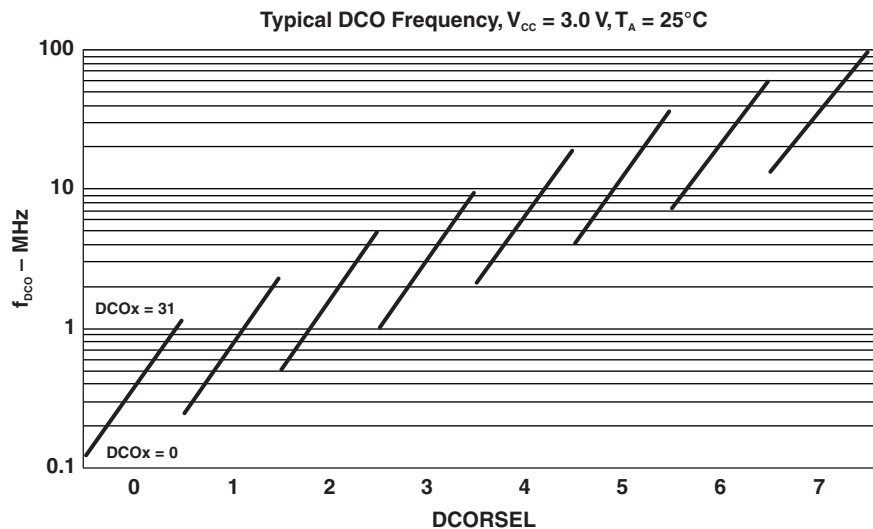


Figure 16. Typical DCO frequency

PMM, Brown-Out Reset (BOR)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V(DV _{CC} _BOR_IT-)	BOR _H on voltage, DV _{CC} falling level	dDV _{CC} /d _t < 3 V/s			1.45	V
V(DV _{CC} _BOR_IT+)	BOR _H off voltage, DV _{CC} rising level	dDV _{CC} /d _t < 3 V/s	0.80	1.30	1.50	V
V(DV _{CC} _BOR_hys)	BOR _H hysteresis		60		250	mV
t _{RESET}	Pulse duration required at RST/NMI pin to accept a reset		2			μs

PMM, Core Voltage

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{CORE3} (AM)	Core voltage, active mode, PMMCOREV = 3	2.4 V ≤ DV _{CC} ≤ 3.6 V		1.90		V
V _{CORE2} (AM)	Core voltage, active mode, PMMCOREV = 2	2.2 V ≤ DV _{CC} ≤ 3.6 V		1.80		V
V _{CORE1} (AM)	Core voltage, active mode, PMMCOREV = 1	2 V ≤ DV _{CC} ≤ 3.6 V		1.60		V
V _{CORE0} (AM)	Core voltage, active mode, PMMCOREV = 0	1.8 V ≤ DV _{CC} ≤ 3.6 V		1.40		V
V _{CORE3} (LPM)	Core voltage, low-current mode, PMMCOREV = 3	2.4 V ≤ DV _{CC} ≤ 3.6 V		1.94		V
V _{CORE2} (LPM)	Core voltage, low-current mode, PMMCOREV = 2	2.2 V ≤ DV _{CC} ≤ 3.6 V		1.84		V
V _{CORE1} (LPM)	Core voltage, low-current mode, PMMCOREV = 1	2 V ≤ DV _{CC} ≤ 3.6 V		1.64		V
V _{CORE0} (LPM)	Core voltage, low-current mode, PMMCOREV = 0	1.8 V ≤ DV _{CC} ≤ 3.6 V		1.44		V

PMM, SVS High Side

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{(SVSH)}$	SVS current consumption	SVSHE = 0, $DV_{CC} = 3.6\text{ V}$		0		nA
		SVSHE = 1, $DV_{CC} = 3.6\text{ V}$, SVSHFP = 0		200		
		SVSHE = 1, $DV_{CC} = 3.6\text{ V}$, SVSHFP = 1		1.5		μA
$V_{(SVSH_IT-)}$	SVS _H on voltage level ⁽¹⁾	SVSHE = 1, SVSHRVL = 0	1.53	1.60	1.67	V
		SVSHE = 1, SVSHRVL = 1	1.73	1.80	1.87	
		SVSHE = 1, SVSHRVL = 2	1.93	2.00	2.07	
		SVSHE = 1, SVSHRVL = 3	2.03	2.10	2.17	
$V_{(SVSH_IT+)}$	SVS _H off voltage level ⁽¹⁾	SVSHE = 1, SVSMHRRL = 0	1.60	1.70	1.80	V
		SVSHE = 1, SVSMHRRL = 1	1.80	1.90	2.00	
		SVSHE = 1, SVSMHRRL = 2	2.00	2.10	2.20	
		SVSHE = 1, SVSMHRRL = 3	2.10	2.20	2.30	
		SVSHE = 1, SVSMHRRL = 4	2.25	2.35	2.50	
		SVSHE = 1, SVSMHRRL = 5	2.52	2.65	2.78	
		SVSHE = 1, SVSMHRRL = 6	2.85	3.00	3.15	
		SVSHE = 1, SVSMHRRL = 7	2.85	3.00	3.15	
$t_{pd(SVSH)}$	SVS _H propagation delay	SVSHE = 1, $dV_{DVCC}/dt = 10\text{ mV}/\mu\text{s}$, SVSHFP = 1		2.5		μs
		SVSHE = 1, $dV_{DVCC}/dt = 1\text{ mV}/\mu\text{s}$, SVSHFP = 0		20		
$t_{(SVSH)}$	SVS _H on or off delay time	SVSHE = 0 → 1, $dV_{DVCC}/dt = 10\text{ mV}/\mu\text{s}$, SVSHFP = 1		12.5		μs
		SVSHE = 0 → 1, $dV_{DVCC}/dt = 1\text{ mV}/\mu\text{s}$, SVSHFP = 0		100		
dV_{DVCC}/dt	DV_{CC} rise time		0		1000	V/s

(1) The SVS_H settings available depend on the VCORE (PMMCOREVx) setting. See the *Power Management Module and Supply Voltage Supervisor* chapter in the *RF430F5978 User's Guide* (SLAU378) on recommended settings and usage.

PMM, SVM High Side

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{(SVMH)}$ SVM _H current consumption	SVMHE = 0, DV _{CC} = 3.6 V		0		nA
	SVMHE = 1, DV _{CC} = 3.6 V, SVMHFP = 0		200		
	SVMHE = 1, DV _{CC} = 3.6 V, SVMHFP = 1		1.5		μA
$V_{(SVMH)}$ SVM _H on or off voltage level ⁽¹⁾	SVMHE = 1, SVSMHRRL = 0	1.60	1.70	1.80	V
	SVMHE = 1, SVSMHRRL = 1	1.80	1.90	2.00	
	SVMHE = 1, SVSMHRRL = 2	2.00	2.10	2.20	
	SVMHE = 1, SVSMHRRL = 3	2.10	2.20	2.30	
	SVMHE = 1, SVSMHRRL = 4	2.25	2.35	2.50	
	SVMHE = 1, SVSMHRRL = 5	2.52	2.65	2.78	
	SVMHE = 1, SVSMHRRL = 6	2.85	3.00	3.15	
	SVMHE = 1, SVSMHRRL = 7	2.85	3.00	3.15	
$t_{pd(SVMH)}$ SVM _H propagation delay	SVMHE = 1, dV _{DVCC} /dt = 10 mV/μs, SVMHFP = 1		2.5		μs
	SVMHE = 1, dV _{DVCC} /dt = 1 mV/μs, SVMHFP = 0		20		
$t_{(SVMH)}$ SVM _H on or off delay time	SVMHE = 0 → 1, dV _{DVCC} /dt = 10 mV/μs, SVMHFP = 1		12.5		μs
	SVMHE = 0 → 1, dV _{DVCC} /dt = 1 mV/μs, SVMHFP = 0		100		

(1) The SVM_H settings available depend on the VCORE (PMMCOREVx) setting. See the *Power Management Module and Supply Voltage Supervisor* chapter in the *RF430F5978 User's Guide* (SLAU378) on recommended settings and usage.

PMM, SVS Low Side

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{(SVSL)}$ SVS _L current consumption	SVSLE = 0, PMMCOREV = 2		0		nA
	SVSLE = 1, PMMCOREV = 2, SVSLFP = 0		200		nA
	SVSLE = 1, PMMCOREV = 2, SVSLFP = 1		1.5		μA
$t_{pd(SVSL)}$ SVS _L propagation delay	SVSLE = 1, dV _{CORE} /dt = 10 mV/μs, SVSLFP = 1		2.5		μs
	SVSLE = 1, dV _{CORE} /dt = 1 mV/μs, SVSLFP = 0		20		
$t_{(SVSL)}$ SVS _L on or off delay time	SVSLE = 0 → 1, dV _{CORE} /dt = 10 mV/μs, SVSLFP = 1		12.5		μs
	SVSLE = 0 → 1, dV _{CORE} /dt = 1 mV/μs, SVSLFP = 0		100		

PMM, SVM Low Side

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{(SVM_L)}$	SVM _L current consumption	SVMLE = 0, PMMCOREV = 2		0		nA
		SVMLE = 1, PMMCOREV = 2, SVMLFP = 0		200		nA
		SVMLE = 1, PMMCOREV = 2, SVMLFP = 1		1.5		μA
$t_{pd(SVM_L)}$	SVM _L propagation delay	SVMLE = 1, $dV_{CORE}/dt = 10 \text{ mV}/\mu\text{s}$, SVMLFP = 1		2.5		μs
		SVMLE = 1, $dV_{CORE}/dt = 1 \text{ mV}/\mu\text{s}$, SVMLFP = 0		20		
$t_{l(SVM_L)}$	SVM _L on or off delay time	SVMLE = 0 → 1, $dV_{CORE}/dt = 10 \text{ mV}/\mu\text{s}$, SVMLFP = 1		12.5		μs
		SVMLE = 0 → 1, $dV_{CORE}/dt = 1 \text{ mV}/\mu\text{s}$, SVMLFP = 0		100		

Wake-up from Low Power Modes and Reset

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{\text{WAKE-UP-FAST}}$	Wake-up time from LPM2, LPM3, or LPM4 to active mode ⁽¹⁾	PMMCOREV = SVSMLRRL = n (where n = 0, 1, 2, or 3), SVSLFP = 1, $f_{\text{MCLK}} \geq 4.0 \text{ MHz}$			5	μs
		$f_{\text{MCLK}} < 4.0 \text{ MHz}$			6	
$t_{\text{WAKE-UP-SLOW}}$	Wake-up time from LPM2, LPM3 or LPM4 to active mode ⁽²⁾	PMMCOREV = SVSMLRRL = n (where n = 0, 1, 2, or 3), SVSLFP = 0		150	165	μs
$t_{\text{WAKE-UP-RESET}}$	Wake-up time from $\overline{\text{RST}}$ or BOR event to active mode ⁽³⁾			2	3	ms

- (1) This value represents the time from the wakeup event to the first active edge of MCLK. The wakeup time depends on the performance mode of the low side supervisor (SVS_L) and low side monitor (SVM_L). Fastest wakeup times are possible with SVS_L and SVM_L in full performance mode or disabled when operating in AM, LPM0, and LPM1. Various options are available for SVS_L and SVM_L while operating in LPM2, LPM3, and LPM4. See the *Power Management Module and Supply Voltage Supervisor* chapter in the *RF430F5978 User's Guide* (SLAU378).
- (2) This value represents the time from the wakeup event to the first active edge of MCLK. The wakeup time depends on the performance mode of the low side supervisor (SVS_L) and low side monitor (SVM_L). In this case, the SVS_L and SVM_L are in normal mode (low current) mode when operating in AM, LPM0, and LPM1. Various options are available for SVS_L and SVM_L while operating in LPM2, LPM3, and LPM4. See the *Power Management Module and Supply Voltage Supervisor* chapter in the *RF430F5978 User's Guide* (SLAU378).
- (3) This value represents the time from the wakeup event to the reset vector execution.

Timer_A

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
f_{TA}	Timer_A input clock frequency	Internal: SMCLK, ACLK External: TACLK Duty cycle = 50% ± 10%	1.8 V, 3 V			25	MHz
$t_{TA,cap}$	Timer_A capture timing	All capture inputs, Minimum pulse duration required for capture	1.8 V, 3 V	20			ns

USCI (UART Mode) Recommended Operating Conditions

PARAMETER	CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
f _{USCI} USCI input clock frequency	Internal: SMCLK, ACLK External: UCLK Duty cycle = 50% ± 10%			f _{SYSTEM}		MHz
f _{BITCLK} BITCLK clock frequency (equals baud rate in MBaud)				1		MHz

USCI (UART Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
t _r UART receive deglitch time ⁽¹⁾		2.2 V	50		600	ns
		3 V	50		600	

- (1) Pulses on the UART receive input (UCxRX) shorter than the UART receive deglitch time are suppressed. To ensure that pulses are correctly recognized their duration should exceed the maximum specification of the deglitch time.

USCI (SPI Master Mode) Recommended Operating Conditions

PARAMETER	CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
f _{USCI} USCI input clock frequency	Internal: SMCLK, ACLK Duty cycle = 50% ± 10%			f _{SYSTEM}		MHz

USCI (SPI Master Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

(see Note ⁽¹⁾, [Figure 17](#) and [Figure 18](#))

PARAMETER	TEST CONDITIONS	PMM COREV _x	V _{CC}	MIN	TYP	MAX	UNIT
t _{SU,MI} SOMI input data setup time		0	1.8 V	55			ns
			3 V	38			
		3	2.4 V	30			ns
			3 V	25			
t _{HD,MI} SOMI input data hold time		0	1.8 V	0			ns
			3 V	0			
		3	2.4 V	0			ns
			3 V	0			
t _{VALID,MO} SIMO output data valid time ⁽²⁾	UCLK edge to SIMO valid, C _L = 20 pF	0	1.8 V			20	ns
			3 V			18	
		3	2.4 V			16	ns
			3 V			15	
t _{HD,MO} SIMO output data hold time ⁽³⁾	C _L = 20 pF	0	1.8 V	-10			ns
			3 V	-8			
		3	2.4 V	-10			ns
			3 V	-8			

- (1) $f_{UCXCLK} = 1/2t_{LO/HI}$ with $t_{LO/HI} \geq \max(t_{VALID,MO}(USCI) + t_{SU,SI}(Slave), t_{SU,MI}(USCI) + t_{VALID,SO}(Slave))$. For the slave's parameters $t_{SU,SI}(Slave)$ and $t_{VALID,SO}(Slave)$ see the SPI parameters of the attached slave.
- (2) Specifies the time to drive the next valid data to the SIMO output after the output changing UCLK clock edge. See the timing diagrams in [Figure 17](#) and [Figure 18](#).
- (3) Specifies how long data on the SIMO output is valid after the output changing UCLK clock edge. Negative values indicate that the data on the SIMO output can become invalid before the output changing clock edge observed on UCLK. See the timing diagrams in [Figure 17](#) and [Figure 18](#).

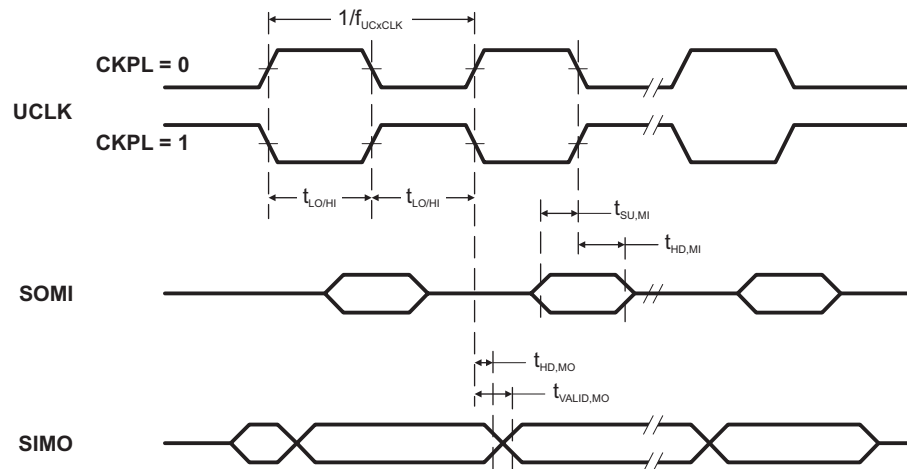


Figure 17. SPI Master Mode, CKPH = 0

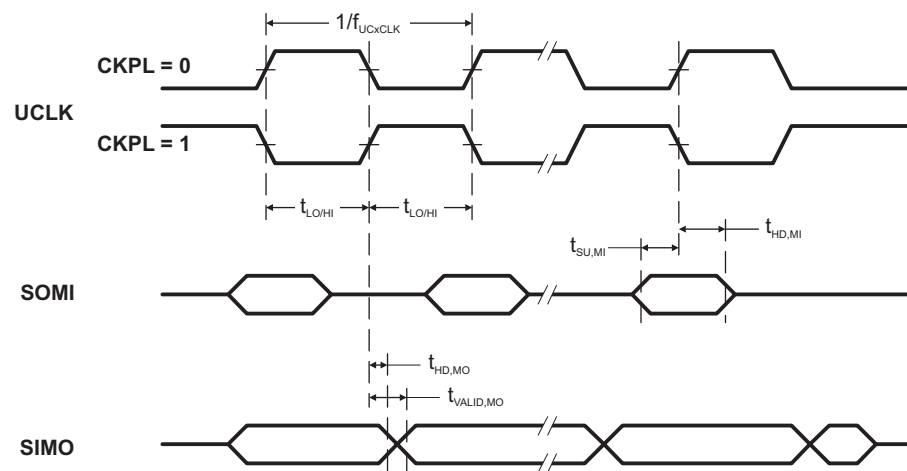


Figure 18. SPI Master Mode, CKPH = 1

USCI (SPI Slave Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)
(see Note ⁽¹⁾, [Figure 19](#) and [Figure 20](#))

PARAMETER	TEST CONDITIONS	PMMCOR EVx	V _{CC}	MIN	TYP	MAX	UNIT
t _{STE,LEAD} STE lead time, STE low to clock		0	1.8 V	11			ns
			3 V	8			
		3	2.4 V	7			
			3 V	6			
t _{STE,LAG} STE lag time, Last clock to STE high		0	1.8 V	3			ns
			3 V	3			
		3	2.4 V	3			
			3 V	3			
t _{STE,ACC} STE access time, STE low to SOMI data out		0	1.8 V			66	ns
			3 V			50	
		3	2.4 V			36	
			3 V			30	
t _{STE,DIS} STE disable time, STE high to SOMI high impedance		0	1.8 V			30	ns
			3 V			23	
		3	2.4 V			16	
			3 V			13	
t _{SU,SI} SIMO input data setup time		0	1.8 V	5			ns
			3 V	5			
		3	2.4 V	2			ns
			3 V	2			
t _{HD,SI} SIMO input data hold time		0	1.8 V	5			ns
			3 V	5			
		3	2.4 V	5			ns
			3 V	5			
t _{VALID,SO} SOMI output data valid time ⁽²⁾	UCLK edge to SOMI valid, C _L = 20 pF	0	1.8 V			76	ns
			3 V			60	
		3	2.4 V			44	ns
			3 V			40	
t _{HD,SO} SOMI output data hold time ⁽³⁾	C _L = 20 pF	0	1.8 V	18			ns
			3 V	12			
		3	2.4 V	10			ns
			3 V	8			

(1) $f_{UCXCLK} = 1/2t_{LO/HI}$ with $t_{LO/HI} \geq \max(t_{VALID,MO(Master)} + t_{SU,SI(USCI)}, t_{SU,MI(Master)} + t_{VALID,SO(USCI)})$.

For the master's parameters $t_{SU,MI(Master)}$ and $t_{VALID,MO(Master)}$ see the SPI parameters of the attached master.

(2) Specifies the time to drive the next valid data to the SOMI output after the output changing UCLK clock edge. See the timing diagrams in [Figure 17](#) and [Figure 18](#).

(3) Specifies how long data on the SOMI output is valid after the output changing UCLK clock edge. See the timing diagrams in [Figure 17](#) and [Figure 18](#).

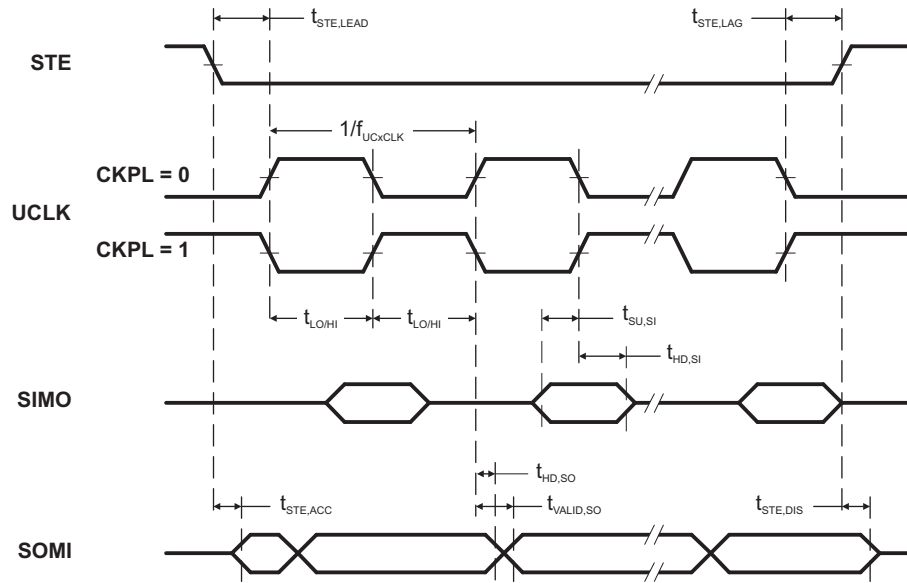


Figure 19. SPI Slave Mode, CKPH = 0

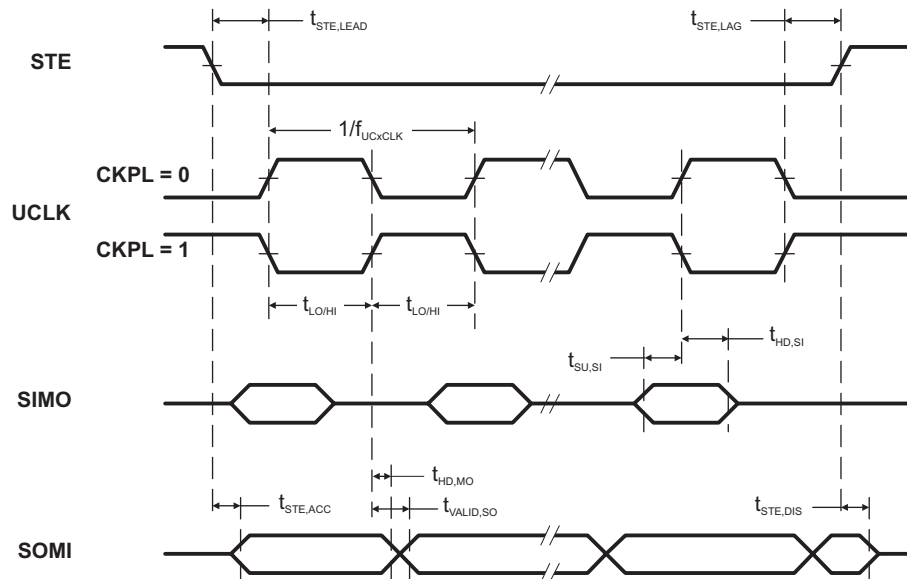


Figure 20. SPI Slave Mode, CKPH = 1

USCI (I2C Mode)

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see [Figure 21](#))

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
f _{USCI}	USCI input clock frequency	Internal: SMCLK, ACLK External: UCLK Duty cycle = 50% ± 10%			f _{SYSTEM}	MHz
f _{SCL}	SCL clock frequency	2.2 V, 3 V	0		400	kHz
t _{HD,STA}	Hold time (repeated) START	f _{SCL} ≤ 100 kHz f _{SCL} > 100 kHz	2.2 V, 3 V	4.0 0.6		μs
t _{SU,STA}	Setup time for a repeated START	f _{SCL} ≤ 100 kHz f _{SCL} > 100 kHz	2.2 V, 3 V	4.7 0.6		μs
t _{HD,DAT}	Data hold time		2.2 V, 3 V	0		ns
t _{SU,DAT}	Data setup time		2.2 V, 3 V	250		ns
t _{SU,STO}	Setup time for STOP	f _{SCL} ≤ 100 kHz f _{SCL} > 100 kHz	2.2 V, 3 V	4.0 0.6		μs
t _{SP}	Pulse duration of spikes suppressed by input filter	2.2 V 3 V	50 50		600 600	ns

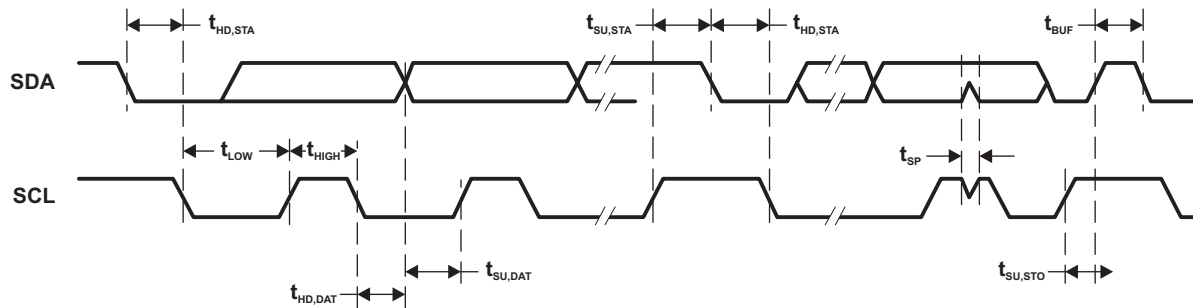


Figure 21. I2C Mode Timing

12-Bit ADC, Power Supply and Input Range Conditions

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)⁽¹⁾

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
AV _{CC}	Analog supply voltage, Full performance AVCC and DVCC are connected together, AVSS and DVSS are connected together, V _(AVSS) = V _(DVSS) = 0 V		2.2		3.6	V
V _(Ax)	Analog input voltage range ⁽²⁾ All ADC12 analog input pins Ax		0		AV _{CC}	V
I _{ADC12_A}	Operating supply current into AVCC terminal ⁽³⁾ f _{ADC12CLK} = 5.0 MHz, ADC12ON = 1, REFON = 0, SHT0 = 0, SHT1 = 0, ADC12DIV = 0	2.2 V		125	155	μA
		3 V		150	220	
C _I	Input capacitance Only one terminal Ax can be selected at one time	2.2 V		20	25	pF
R _I	Input MUX ON resistance 0 V ≤ V _{Ax} ≤ AV _{CC}		10	200	1900	Ω

(1) The leakage current is specified by the digital I/O input leakage.

(2) The analog input voltage range must be within the selected reference voltage range V_{R+} to V_{R-} for valid conversion results. If the reference voltage is supplied by an external source or if the internal reference voltage is used and REFOUT = 1, then decoupling capacitors are required. See [REF, External Reference](#) and [REF, Built-In Reference](#).

(3) The internal reference supply current is not included in current consumption parameter I_{ADC12_A}.

12-Bit ADC, Timing Parameters

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
f _{ADC12CLK}	For specified performance of ADC12 linearity parameters	2.2 V, 3 V	0.45	4.8	5.4	MHz
f _{ADC12OSC}	Internal ADC12 oscillator ⁽¹⁾ ADC12DIV = 0, f _{ADC12CLK} = f _{ADC12OSC}	2.2 V, 3 V	4.2	4.8	5.4	MHz
t _{CONVERT}	REFON = 0, Internal oscillator, f _{ADC12OSC} = 4.2 MHz to 5.4 MHz	2.2 V, 3 V	2.4		3.1	μs
	External f _{ADC12CLK} from ACLK, MCLK or SMCLK, ADC12SSEL ≠ 0			(2)		
t _{Sample}	R _S = 400 Ω, R _I = 1000 Ω, C _I = 30 pF, τ = [R _S + R _I] × C _I ⁽³⁾	2.2 V, 3 V	1000			ns

(1) The ADC12OSC is sourced directly from MODOSC inside the UCS.

(2) 13 × ADC12DIV × 1/f_{ADC12CLK}

(3) Approximately ten Tau (τ) are needed to get an error of less than ±0.5 LSB:

$$t_{\text{Sample}} = \ln(2^{n+1}) \times (R_S + R_I) \times C_I + 800 \text{ ns, where } n = \text{ADC resolution} = 12, R_S = \text{external source resistance}$$

12-Bit ADC, Linearity Parameters

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
E _I	1.4 V ≤ (V _{eREF+} - V _{REF-/V_{eREF-}})min ≤ 1.6 V	2.2 V, 3 V			±2	LSB
	1.6 V < (V _{eREF+} - V _{REF-/V_{eREF-}})min ≤ AV _{CC}				±1.7	
E _D	(V _{eREF+} - V _{REF-/V_{eREF-}})min ≤ (V _{eREF+} - V _{REF-/V_{eREF-}}), C _{VREF+} = 20 pF	2.2 V, 3 V			±1.0	LSB
E _O	(V _{eREF+} - V _{REF-/V_{eREF-}})min ≤ (V _{eREF+} - V _{REF-/V_{eREF-}}), Internal impedance of source R _S < 100 Ω, C _{VREF+} = 20 pF	2.2 V, 3 V		±1.0	±2.0	LSB
E _G	(V _{eREF+} - V _{REF-/V_{eREF-}})min ≤ (V _{eREF+} - V _{REF-/V_{eREF-}}), C _{VREF+} = 20 pF	2.2 V, 3 V		±1.0	±2.0	LSB
E _T	(V _{eREF+} - V _{REF-/V_{eREF-}})min ≤ (V _{eREF+} - V _{REF-/V_{eREF-}}), C _{VREF+} = 20 pF	2.2 V, 3 V		±1.4	±3.5	LSB

12-Bit ADC, Temperature Sensor and Built-In V_{MID} ⁽¹⁾

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
V _{SENSOR}	See ⁽²⁾ ⁽³⁾	ADC12ON = 1, INCH = 0Ah, T _A = 0°C	2.2 V	680			mV
			3 V	680			
TC _{SENSOR}	See ⁽³⁾	ADC12ON = 1, INCH = 0Ah	2.2 V	2.25			mV/°C
			3 V	2.25			
t _{SENSOR(sample)}	Sample time required if channel 10 is selected ⁽⁴⁾	ADC12ON = 1, INCH = 0Ah, Error of conversion result ≤ 1 LSB	2.2 V	100			μs
			3 V	100			
V _{MID}	AV _{CC} divider at channel 11, V _{AVCC} factor	ADC12ON = 1, INCH = 0Bh		0.48	0.5	0.52	V _{AVCC}
	AV _{CC} divider at channel 11	ADC12ON = 1, INCH = 0Bh	2.2 V	1.06	1.1	1.14	V
			3 V	1.44	1.5	1.56	
t _{VMID(sample)}	Sample time required if channel 11 is selected ⁽⁵⁾	ADC12ON = 1, INCH = 0Bh, Error of conversion result ≤ 1 LSB	2.2 V, 3 V	1000			ns

- (1) The temperature sensor is provided by the REF module. See the REF module parametric, I_{REF+} , regarding the current consumption of the temperature sensor.
- (2) The temperature sensor offset can be significant. A single-point calibration is recommended to minimize the offset error of the built-in temperature sensor.
- (3) The device descriptor structure contains calibration values for $30^\circ\text{C} \pm 3^\circ\text{C}$ and $85^\circ\text{C} \pm 3^\circ\text{C}$ for each of the available reference voltage levels. The sensor voltage can be computed as $V_{SENSE} = TC_{SENSOR} * (\text{Temperature}, ^\circ\text{C}) + V_{SENSOR}$, where TC_{SENSOR} and V_{SENSOR} can be computed from the calibration values for higher accuracy.
- (4) The typical equivalent impedance of the sensor is 51 k Ω . The sample time required includes the sensor-on time $t_{SENSOR(on)}$.
- (5) The on-time $t_{VMID(on)}$ is included in the sampling time $t_{VMID(sample)}$; no additional on time is needed.

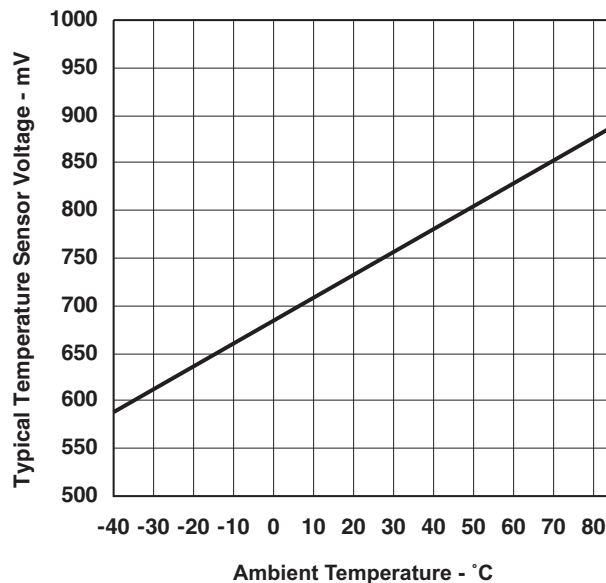


Figure 22. Typical Temperature Sensor Voltage

REF, External Reference

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)⁽¹⁾

PARAMETER		TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
V _{eREF+}	Positive external reference voltage input	V _{eREF+} > V _{REF-/V_{eREF-}} ⁽²⁾		1.4		AV _{CC}	V
V _{REF-/V_{eREF-}}	Negative external reference voltage input	V _{eREF+} > V _{REF-/V_{eREF-}} ⁽³⁾		0		1.2	V
(V _{eREF+} – V _{REF-/V_{eREF-}})	Differential external reference voltage input	V _{eREF+} > V _{REF-/V_{eREF-}} ⁽⁴⁾		1.4		AV _{CC}	V
I _{VeREF+} I _{VREF-/VeREF-}	Static input current	1.4 V ≤ V _{eREF+} ≤ V _{AVCC} , V _{eREF-} = 0 V, f _{ADC12CLK} = 5 MHz, ADC12SHTx = 1h, Conversion rate 200ksps	2.2 V, 3 V		±8.5	±26	μA
		1.4 V ≤ V _{eREF+} ≤ V _{AVCC} , V _{eREF-} = 0 V, f _{ADC12CLK} = 5 MHz, ADC12SHTx = 8h, Conversion rate 20ksps	2.2 V, 3 V			±1	μA
C _{VREF±}	Capacitance at VREF+ or VREF- terminal, external reference ⁽⁵⁾			10			μF

- (1) The external reference is used during ADC conversion to charge and discharge the capacitance array. The input capacitance, C_i, is also the dynamic load for an external reference during conversion. The dynamic impedance of the reference supply should follow the recommendations on analog-source impedance to allow the charge to settle for 12-bit accuracy.
- (2) The accuracy limits the minimum positive external reference voltage. Lower reference voltage levels may be applied with reduced accuracy requirements.
- (3) The accuracy limits the maximum negative external reference voltage. Higher reference voltage levels may be applied with reduced accuracy requirements.
- (4) The accuracy limits minimum external differential reference voltage. Lower differential reference voltage levels may be applied with reduced accuracy requirements.
- (5) Two decoupling capacitors, 10 μF and 100 nF, should be connected to VREF to decouple the dynamic current required for an external reference source if it is used for the ADC12_A. See also the *RF430F5978 User's Guide* (SLAU378).

REF, Built-In Reference

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)⁽¹⁾

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
V _{REF+}	REFVSEL = 2 for 2.5 V, REFON = REFOUT = 1, I _{VREF+} = 0 A	3 V		2.41	±1.5%	V
	REFVSEL = 1 for 2 V, REFON = REFOUT = 1, I _{VREF+} = 0 A	3 V		1.93	±1.5%	
	REFVSEL = 0 for 1.5 V, REFON = REFOUT = 1, I _{VREF+} = 0 A	2.2 V/ 3 V		1.45	±1.5%	
AV _{CC(min)}	REFVSEL = 0 for 1.5 V, reduced performance		1.8			V
	REFVSEL = 0 for 1.5 V		2.2			
	REFVSEL = 1 for 2 V		2.3			
	REFVSEL = 2 for 2.5 V		2.8			
I _{REF+}	REFON = 1, REFOUT = 0, REFBURST = 0	3 V		100	140	μA
	REFON = 1, REFOUT = 1, REFBURST = 0	3 V		0.9	1.5	mA
I _{L(VREF+)}	REFVSEL = 0, 1, or 2, I _{VREF+} = +10 μA–1000 μA, AV _{CC} = AV _{CC(min)} for each reference level, REFVSEL = 0, 1, 2; REFON = REFOUT = 1				2500	μV/mA
C _{VREF±}	Capacitance at VREF+ and VREF- terminals, internal reference	REFON = REFOUT = 1		20	100	pF
TC _{REF+}	Temperature coefficient of built-in reference ⁽⁵⁾	I _{VREF+} = 0 A, REFVSEL = 0, 1, or 2, REFON = 1, REFOUT = 0 or 1		30	50	ppm/°C
PSRR _{DC}	Power supply rejection ratio (DC)	AV _{CC} = AV _{CC(min)} - AV _{CC(max)} , T _A = 25 °C, REFVSEL = 0, 1, or 2, REFON = 1, REFOUT = 0 or 1		120	300	μV/V
PSRR _{AC}	Power supply rejection ratio (AC)	AV _{CC} = AV _{CC(min)} - AV _{CC(max)} , T _A = 25 °C, f = 1 kHz, ΔV _{pp} = 100 mV, REFVSEL = 0, 1, or 2, REFON = 1, REFOUT = 0 or 1		6.4		mV/V
t _{SETTLE}	AV _{CC} = AV _{CC(min)} - AV _{CC(max)} , REFVSEL = 0, 1, or 2, REFOUT = 0, REFON = 0 → 1			75		μs
	AV _{CC} = AV _{CC(min)} - AV _{CC(max)} , C _{VREF} = C _{VREF(max)} , REFVSEL = 0, 1, or 2, REFOUT = 1, REFON = 0 → 1			75		

- (1) The reference is supplied to the ADC by the REF module and is buffered locally inside the ADC. The ADC uses two internal buffers, one smaller and one larger for driving the V_{REF+} terminal. When REFOUT = 1, the reference is available at the V_{REF+} terminal, as well as, used as the reference for the conversion and utilizes the larger buffer. When REFOUT = 0, the reference is only used as the reference for the conversion and utilizes the smaller buffer.
- (2) The internal reference current is supplied via terminal AV_{CC}. Consumption is independent of the ADC12ON control bit, unless a conversion is active. The REFON bit enables to settle the built-in reference before starting an A/D conversion. REFOUT = 0 represents the current contribution of the smaller buffer. REFOUT = 1 represents the current contribution of the larger buffer without external load.
- (3) The temperature sensor is provided by the REF module. Its current is supplied via terminal AV_{CC} and is equivalent to I_{REF+} with REFON = 1 and REFOUT = 0.
- (4) Contribution only due to the reference and buffer including package. This does not include resistance due to PCB trace, etc.
- (5) Calculated using the box method: (MAX(-40 to 85°C) – MIN(-40 to 85°C)) / MIN(-40 to 85°C)/(85°C – (-40°C)).
- (6) The condition is that the error in a conversion started after t_{REFON} is less than ±0.5 LSB. The settling time depends on the external capacitive load when REFOUT = 1.

Comparator B

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER	TEST CONDITIONS	V _{CC}	MIN	TYP	MAX	UNIT
V _{CC}	Supply voltage		1.8		3.6	V
I _{AVCC_COMP}	Comparator operating supply current into AVCC, Excludes reference resistor ladder	CBPWRMD = 00	1.8 V		40	μA
			2.2 V	30	50	
			3 V	40	65	
	CBPWRMD = 01	2.2 V, 3 V		10	30	
	CBPWRMD = 10	2.2 V, 3 V		0.1	0.5	
I _{AVCC_REF}	Quiescent current of local reference voltage amplifier into AVCC	CBREFACC = 1, CBREFLx = 01			22	μA
V _{IC}	Common mode input range		0		V _{CC} -1	V
V _{OFFSET}	Input offset voltage	CBPWRMD = 00			±20	mV
		CBPWRMD = 01, 10			±10	mV
C _{IN}	Input capacitance			5		pF
R _{SIN}	Series input resistance	ON - switch closed		3	4	kΩ
		OFF - switch opened		30		MΩ
t _{PD}	Propagation delay, response time	CBPWRMD = 00, CBF = 0			450	ns
		CBPWRMD = 01, CBF = 0			600	ns
		CBPWRMD = 10, CBF = 0			50	μs
t _{PD,filter}	Propagation delay with filter active	CBPWRMD = 00, CBON = 1, CBF = 1, CBFDLY = 00	0.35	0.6	1.0	μs
		CBPWRMD = 00, CBON = 1, CBF = 1, CBFDLY = 01	0.6	1.0	1.8	μs
		CBPWRMD = 00, CBON = 1, CBF = 1, CBFDLY = 10	1.0	1.8	3.4	μs
		CBPWRMD = 00, CBON = 1, CBF = 1, CBFDLY = 11	1.8	3.4	6.5	μs
t _{EN_CMP}	Comparator enable time, settling time	CBON = 0 to CBON = 1, CBPWRMD = 00, 01, 10		1	2	μs
t _{EN_REF}	Resistor reference enable time	CBON = 0 to CBON = 1		0.3	1.5	μs
V _{CB_REF}	Reference voltage for a given tap	VIN = reference into resistor ladder, n = 0 to 31		VIN × (n+1) / 32		V

Flash Memory

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
DV _{CC(PGM/ERASE)}	Program and erase supply voltage		1.8		3.6	V
I _{PGM}	Average supply current from DVCC during program			3	5	mA
I _{ERASE}	Average supply current from DVCC during erase			2	6.5	mA
I _{MERASE} , I _{BANK}	Average supply current from DVCC during mass erase or bank erase			2	6.5	mA
t _{CPT}	Cumulative program time ⁽¹⁾				16	ms
	Program and erase endurance		10 ⁴	10 ⁵		cycles
t _{Retention}	Data retention duration	T _J = 25°C	100			years
t _{Word}	Word or byte program time ⁽²⁾		64		85	μs
t _{Block, 0}	Block program time for first byte or word ⁽²⁾		49		65	μs
t _{Block, 1–(N–1)}	Block program time for each additional byte or word, except for last byte or word ⁽²⁾		37		49	μs
t _{Block, N}	Block program time for last byte or word ⁽²⁾		55		73	μs
t _{Erase}	Erase time for segment erase, mass erase, and bank erase when available ⁽²⁾		23		32	ms
f _{MCLK,MGR}	MCLK frequency in marginal read mode (FCTL4.MGR0 = 1 or FCTL4.MGR1 = 1)		0		1	MHz

- (1) The cumulative program time must not be exceeded when writing to a 128-byte flash block. This parameter applies to all programming methods: individual word/byte write and block write modes.
- (2) These values are hardwired into the flash controller's state machine.

JTAG and Spy-Bi-Wire Interface

over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
f _{SBW}	Spy-Bi-Wire input frequency	2.2 V, 3 V	0		20	MHz
t _{SBW,Low}	Spy-Bi-Wire low clock pulse length	2.2 V, 3 V	0.025		15	μs
t _{SBW,En}	Spy-Bi-Wire enable time (TEST high to acceptance of first clock edge) ⁽¹⁾	2.2 V, 3 V			1	μs
t _{SBW,Rst}	Spy-Bi-Wire return to normal operation time		15		100	μs
f _{TCK}	TCK input frequency - 4-wire JTAG ⁽²⁾	2.2 V	0		5	MHz
		3 V	0		10	MHz
R _{Internal}	Internal pull-down resistance on TEST	2.2 V, 3 V	45	60	80	kΩ

- (1) Tools accessing the Spy-Bi-Wire interface need to wait for the minimum t_{SBW,En} time after pulling the TEST/SBWTCK pin high before applying the first SBWTCK clock edge.
- (2) f_{TCK} may be restricted to meet the timing requirements of the module selected.

RF1A CC1101 Radio Parameters

Recommended Operating Conditions

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{CC}	Supply voltage range during radio operation	2.0		3.6	V
PMMCOREVx	Core voltage range, PMMCOREVx setting during radio operation	2		3	
RF frequency range		300		348	MHz
		389 ⁽¹⁾		464	
		779		928	
Data rate	2-FSK	0.6		500	kBaud
	2-GFSK, OOK, and ASK	0.6		250	
	(Shaped) MSK (also known as differential offset QPSK) ⁽²⁾	26		500	
RF crystal frequency		26	26	27	MHz
RF crystal tolerance	Total tolerance including initial tolerance, crystal loading, aging and temperature dependency. ⁽³⁾		±40		ppm
RF crystal load capacitance		10	13	20	pF
RF crystal effective series resistance				100	Ω

(1) If using a 27-MHz crystal, the lower frequency limit for this band is 392 MHz.

(2) If using optional Manchester encoding, the data rate in kbps is half the baud rate.

(3) The acceptable crystal tolerance depends on frequency band, channel bandwidth, and spacing. Also see design note *DN005 -- CC11xx Sensitivity versus Frequency Offset and Crystal Accuracy (SWRA122)*.

RF Crystal Oscillator, XT2

T_A = 25°C, V_{CC} = 3 V (unless otherwise noted)⁽¹⁾

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Start-up time ⁽²⁾			150	810	μs
Duty cycle		45	50	55	%

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

(2) The start-up time depends to a very large degree on the used crystal.

Current Consumption, Reduced-Power Modes

T_A = 25°C, V_{CC} = 3 V (unless otherwise noted)⁽¹⁾

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Current consumption	RF crystal oscillator only (e.g., SLEEP state with MCSM0.OSC_FORCE_ON = 1)		100		μA
	IDLE state (including RF crystal oscillator)		1.7		mA
	FSTXON state (only the frequency synthesizer is running) ⁽²⁾		9.5		mA

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

(2) This current consumption is also representative of other intermediate states when going from IDLE to RX or TX, including the calibration state.

Current Consumption, Receive Mode

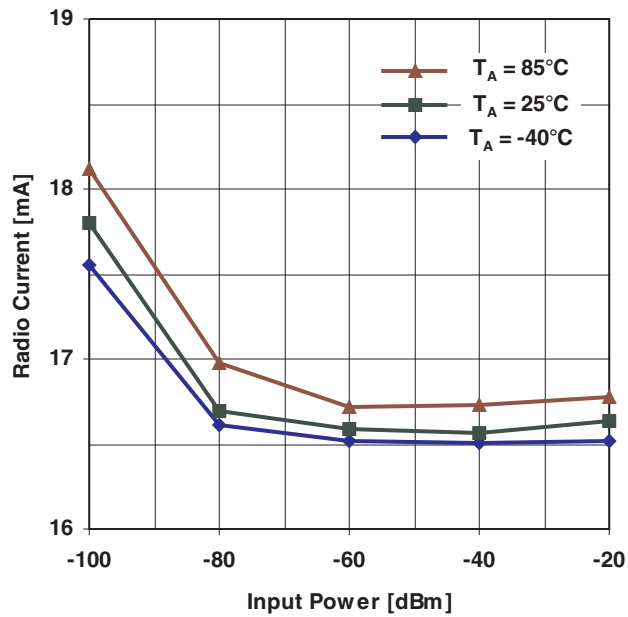
$T_A = 25^\circ\text{C}$, $V_{CC} = 3\text{ V}$ (unless otherwise noted)^{(1) (2)}

PARAMETER	FREQ (MHz)	DATA RATE (kBaud)	TEST CONDITIONS		MIN	TYP	MAX	UNIT
Current consumption, RX	315	1.2	Register settings optimized for reduced current	Input at -100 dBm (close to sensitivity limit)		17		mA
				Input at -40 dBm (well above sensitivity limit)		16		
		38.4		Input at -100 dBm (close to sensitivity limit)		17		
				Input at -40 dBm (well above sensitivity limit)		16		
		250		Input at -100 dBm (close to sensitivity limit)		18		
				Input at -40 dBm (well above sensitivity limit)		16.5		
	433	1.2	Register settings optimized for reduced current	Input at -100 dBm (close to sensitivity limit)		18		
				Input at -40 dBm (well above sensitivity limit)		17		
		38.4		Input at -100 dBm (close to sensitivity limit)		18		
				Input at -40 dBm (well above sensitivity limit)		17		
		250		Input at -100 dBm (close to sensitivity limit)		18.5		
				Input at -40 dBm (well above sensitivity limit)		17		
	868, 915	1.2	Register settings optimized for reduced current ⁽³⁾	Input at -100 dBm (close to sensitivity limit)		16		
				Input at -40 dBm (well above sensitivity limit)		15		
		38.4		Input at -100 dBm (close to sensitivity limit)		16		
				Input at -40 dBm (well above sensitivity limit)		15		
		250		Input at -100 dBm (close to sensitivity limit)		16		
				Input at -40 dBm (well above sensitivity limit)		15		

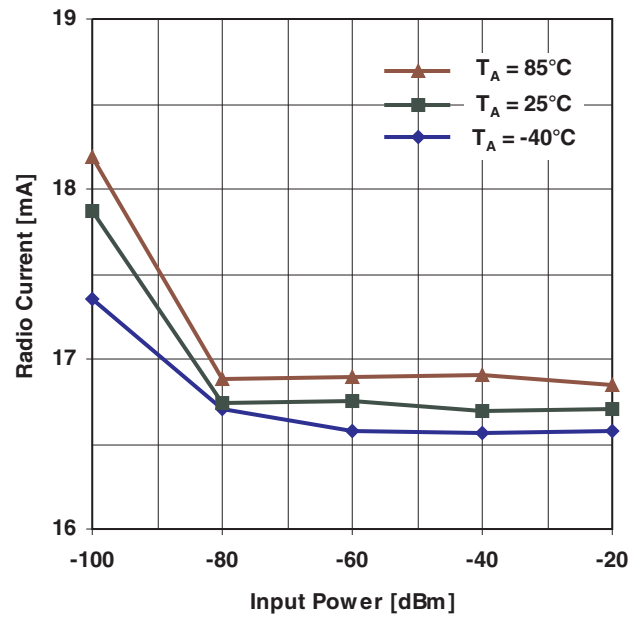
(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

(2) Reduced current setting (MDMCFG2.DEM_DCFILT_OFF = 1) gives a slightly lower current consumption at the cost of a reduction in sensitivity. See tables "RF Receive" for additional details on current consumption and sensitivity.

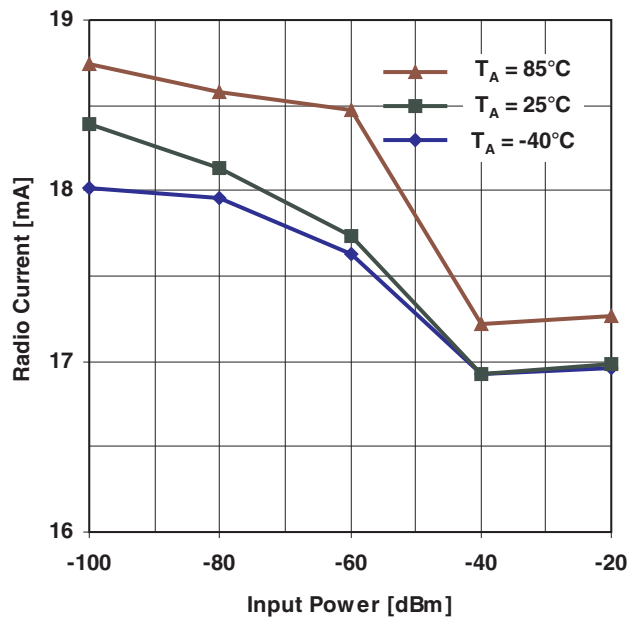
(3) For 868 or 915 MHz, see [Figure 23](#) for current consumption with register settings optimized for sensitivity.



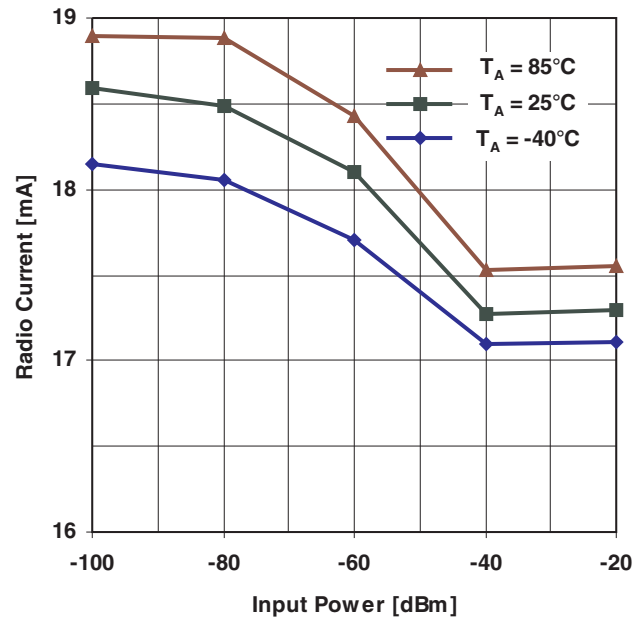
1.2 kBaud GFSK



38.4 kBaud GFSK



250 kBaud GFSK



500 kBaud MSK

Figure 23. Typical RX Current Consumption Over Temperature and Input Power Level, 868 MHz, Sensitivity-Optimized Setting

Current Consumption, Transmit Mode

$T_A = 25^\circ\text{C}$, $V_{CC} = 3\text{ V}$ (unless otherwise noted)⁽¹⁾ ⁽²⁾

PARAMETER	FREQUENCY [MHz]	PATABLE Setting	OUTPUT POWER [dBm]	MIN	TYP	MAX	UNIT
Current consumption, TX	315	0xC0	max.		26		mA
		0xC4	+10		25		mA
		0x51	0		15		mA
		0x29	-6		15		mA
	433	0xC0	max.		33		mA
		0xC6	+10		29		mA
		0x50	0		17		mA
		0x2D	-6		17		mA
	868	0xC0	max.		36		mA
		0xC3	+10		33		mA
		0x8D	0		18		mA
		0x2D	-6		18		mA
	915	0xC0	max.		35		mA
		0xC3	+10		32		mA
		0x8D	0		18		mA
		0x2D	-6		18		mA

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

(2) Reduced current setting (MDMCFG2.DEM_DCFILT_OFF = 1) gives a slightly lower current consumption at the cost of a reduction in sensitivity. See tables "RF Receive" for additional details on current consumption and sensitivity.

Typical TX Current Consumption, 315 MHz

PARAMETER	PATABLE Setting	Output Power [dBm]	V _{CC}	2 V	3 V	3.6 V	UNIT
			T _A	25°C	25°C	25°C	
Current consumption, TX	0xC0	max.		27.5	26.4	28.1	mA
	0xC4	+10		25.1	25.2	25.3	
	0x51	0		14.4	14.6	14.7	
	0x29	-6		14.2	14.7	15.0	

Typical TX Current Consumption, 433 MHz

PARAMETER	PATABLE Setting	Output Power [dBm]	V _{CC}	2 V	3 V	3.6 V	UNIT
			T _A	25°C	25°C	25°C	
Current consumption, TX	0xC0	max.		33.1	33.4	33.8	mA
	0xC6	+10		28.6	28.8	28.8	
	0x50	0		16.6	16.8	16.9	
	0x2D	-6		16.8	17.5	17.8	

Typical TX Current Consumption, 868 MHz

PARAMETER	PATABLE Setting	Output Power [dBm]	V _{CC}	2 V			3 V			3.6 V			UNIT
			T _A	-40°C	25°C	85°C	-40°C	25°C	85°C	-40°C	25°C	85°C	
Current consumption, TX	0xC0	max.		36.7	35.2	34.2	38.5	35.5	34.9	37.1	35.7	34.7	mA
	0xC3	+10		34.0	32.8	32.0	34.2	33.0	32.5	34.3	33.1	32.2	
	0x8D	0		18.0	17.6	17.5	18.3	17.8	18.1	18.4	18.0	17.7	
	0x2D	-6		17.1	17.0	17.2	17.8	17.8	18.3	18.2	18.1	18.1	

Typical TX Current Consumption, 915 MHz

PARAMETER	PATABLE Setting	Output Power [dBm]	V _{CC}	2 V			3 V			3.6 V			UNIT
			T _A	-40°C	25°C	85°C	-40°C	25°C	85°C	-40°C	25°C	85°C	
Current consumption, TX	0xC0	max.		35.5	33.8	33.2	36.2	34.8	33.6	36.3	35.0	33.8	mA
	0xC3	+10		33.2	32.0	31.0	33.4	32.1	31.2	33.5	32.3	31.3	
	0x8D	0		17.8	17.4	17.1	18.1	17.6	17.3	18.2	17.8	17.5	
	0x2D	-6		17.0	16.9	16.9	17.7	17.6	17.6	18.1	18.0	18.0	

RF Receive, Overall

$T_A = 25^\circ\text{C}$, $V_{CC} = 3\text{ V}$ (unless otherwise noted)⁽¹⁾

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Digital channel filter bandwidth ⁽²⁾		58		812	kHz
Spurious emissions ^{(3) (4)}	25 MHz to 1 GHz		-68	-57	dBm
	Above 1 GHz		-66	-47	
RX latency	Serial operation ⁽⁵⁾		9		bit

- (1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.
- (2) User programmable. The bandwidth limits are proportional to crystal frequency (given values assume a 26.0 MHz crystal)
- (3) Typical radiated spurious emission is -49 dBm measured at the VCO frequency
- (4) Maximum figure is the ETSI EN 300 220 limit
- (5) Time from start of reception until data is available on the receiver data output pin is equal to 9 bit.

RF Receive, 315 MHz

$T_A = 25^\circ\text{C}$, $V_{CC} = 3\text{ V}$ (unless otherwise noted)⁽¹⁾

2-FSK, 1% packet error rate, 20-byte packet length, Sensitivity optimized, MDMCFG2.DEM_DCFILT_OFF = 0 (unless otherwise noted)

PARAMETER	DATA RATE (kBaud)	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Receiver sensitivity	0.6	14.3kHz deviation, 58kHz digital channel filter bandwidth		-117		dBm
	1.2	5.2kHz deviation, 58kHz digital channel filter bandwidth ⁽²⁾		-111		
	38.4	20kHz deviation, 100kHz digital channel filter bandwidth ⁽³⁾		-103		
	250	127kHz deviation, 540kHz digital channel filter bandwidth ⁽⁴⁾		-95		
	500	MSK, 812kHz digital channel filter bandwidth ⁽⁴⁾		-86		

- (1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.
- (2) Sensitivity can be traded for current consumption by setting MDMCFG2.DEM_DCFILT_OFF = 1. The typical current consumption is then reduced by about 2mA close to the sensitivity limit. The sensitivity is typically reduced to -109dBm.
- (3) Sensitivity can be traded for current consumption by setting MDMCFG2.DEM_DCFILT_OFF = 1. The typical current consumption is then reduced by about 2mA close to the sensitivity limit. The sensitivity is typically reduced to -102dBm.
- (4) MDMCFG2.DEM_DCFILT_OFF = 1 can not be used for data rates $\geq 250\text{ kBaud}$.

RF Receive, 433 MHz

$T_A = 25^\circ\text{C}$, $V_{CC} = 3\text{ V}$ (unless otherwise noted)⁽¹⁾

2-FSK, 1% packet error rate, 20-byte packet length, Sensitivity optimized, MDMCFG2.DEM_DCFILT_OFF = 0 (unless otherwise noted)

PARAMETER	DATA RATE (kBaud)	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Receiver sensitivity	0.6	14.3kHz deviation, 58kHz digital channel filter bandwidth		-114		dBm
	1.2	5.2-kHz deviation, 58-kHz digital channel filter bandwidth ⁽²⁾		-111		
	38.4	20-kHz deviation, 100-kHz digital channel filter bandwidth ⁽³⁾		-104		
	250	127-kHz deviation, 540-kHz digital channel filter bandwidth ⁽⁴⁾		-93		
	500	MSK, 812kHz digital channel filter bandwidth ⁽⁴⁾		-85		

- (1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.
- (2) Sensitivity can be traded for current consumption by setting MDMCFG2.DEM_DCFILT_OFF = 1. The typical current consumption is then reduced by about 2mA close to the sensitivity limit. The sensitivity is typically reduced to -109dBm.
- (3) Sensitivity can be traded for current consumption by setting MDMCFG2.DEM_DCFILT_OFF = 1. The typical current consumption is then reduced by about 2mA close to the sensitivity limit. The sensitivity is typically reduced to -101dBm.
- (4) MDMCFG2.DEM_DCFILT_OFF = 1 can not be used for data rates $\geq 250\text{ kBaud}$.

RF Receive, 868 or 915 MHz

T_A = 25°C, V_{CC} = 3 V (unless otherwise noted)⁽¹⁾,

1% packet error rate, 20-byte packet length, Sensitivity optimized, MDMCFG2.DEM_DCFILT_OFF = 0 (unless otherwise noted)

PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNIT
0.6-kBaud data rate, 2-FSK, 14.3-kHz deviation, 58-kHz digital channel filter bandwidth (unless otherwise noted)						
Receiver sensitivity			-115			dBm
1.2-kBaud data rate, 2-FSK, 5.2-kHz deviation, 58-kHz digital channel filter bandwidth (unless otherwise noted)						
Receiver sensitivity ⁽²⁾			-109			dBm
	2-GFSK modulation by setting MDMCFG2.MOD_FORMAT = 2, Gaussian filter with BT = 0.5		-109			
Saturation	FIFOTHR.CLOSE_IN_RX = 0 ⁽³⁾		-28			dBm
Adjacent channel rejection	Desired channel 3 dB above the sensitivity limit, 100 kHz channel spacing ⁽⁴⁾	-100-kHz offset	39			dB
		+100-kHz offset	39			
Image channel rejection	IF frequency 152 kHz, desired channel 3 dB above the sensitivity limit		29			dB
Blocking	Desired channel 3 dB above the sensitivity limit ⁽⁵⁾	±2 MHz offset	-48			dBm
		±10 MHz offset	-40			dBm
38.4-kBaud data rate, 2-FSK, 20-kHz deviation, 100-kHz digital channel filter bandwidth (unless otherwise noted)						
Receiver sensitivity ⁽⁶⁾			-102			dBm
	2-GFSK modulation by setting MDMCFG2.MOD_FORMAT = 2, Gaussian filter with BT = 0.5		-101			
Saturation	FIFOTHR.CLOSE_IN_RX = 0 ⁽³⁾		-19			dBm
Adjacent channel rejection	Desired channel 3 dB above the sensitivity limit, 200 kHz channel spacing ⁽⁵⁾	-200-kHz offset	20			dB
		+200-kHz offset	25			
Image channel rejection	IF frequency 152 kHz, Desired channel 3 dB above the sensitivity limit		23			dB
Blocking	Desired channel 3 dB above the sensitivity limit ⁽⁵⁾	±2-MHz offset	-48			dBm
		±10-MHz offset	-40			dBm
250-kBaud data rate, 2-FSK, 127-kHz deviation, 540-kHz digital channel filter bandwidth (unless otherwise noted)						
Receiver sensitivity ⁽⁷⁾			-90			dBm
	2-GFSK modulation by setting MDMCFG2.MOD_FORMAT = 2, Gaussian filter with BT = 0.5		-90			
Saturation	FIFOTHR.CLOSE_IN_RX = 0 ⁽³⁾		-19			dBm
Adjacent channel rejection	Desired channel 3 dB above the sensitivity limit, 750-kHz channel spacing ⁽⁸⁾	-750-kHz offset	24			dB
		+750-kHz offset	30			
Image channel rejection	IF frequency 304 kHz, Desired channel 3 dB above the sensitivity limit		18			dB
Blocking	Desired channel 3 dB above the sensitivity limit ⁽⁸⁾	±2-MHz offset	-53			dBm
		±10-MHz offset	-39			dBm
500-kBaud data rate, MSK, 812-kHz digital channel filter bandwidth (unless otherwise noted)						
Receiver sensitivity ⁽⁷⁾			-84			dBm
Image channel rejection	IF frequency 355 kHz, Desired channel 3 dB above the sensitivity limit		-2			dB
Blocking	Desired channel 3 dB above the sensitivity limit ⁽⁹⁾	±2-MHz offset	-53			dBm
		±10-MHz offset	-38			dBm

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

(2) Sensitivity can be traded for current consumption by setting MDMCFG2.DEM_DCFILT_OFF = 1. The typical current consumption is then reduced by about 2mA close to the sensitivity limit. The sensitivity is typically reduced to -107dBm

(3) See design note *DN010 Close-in Reception with CC1101* (SWRA147).

(4) See Figure 24 for blocking performance at other offset frequencies.

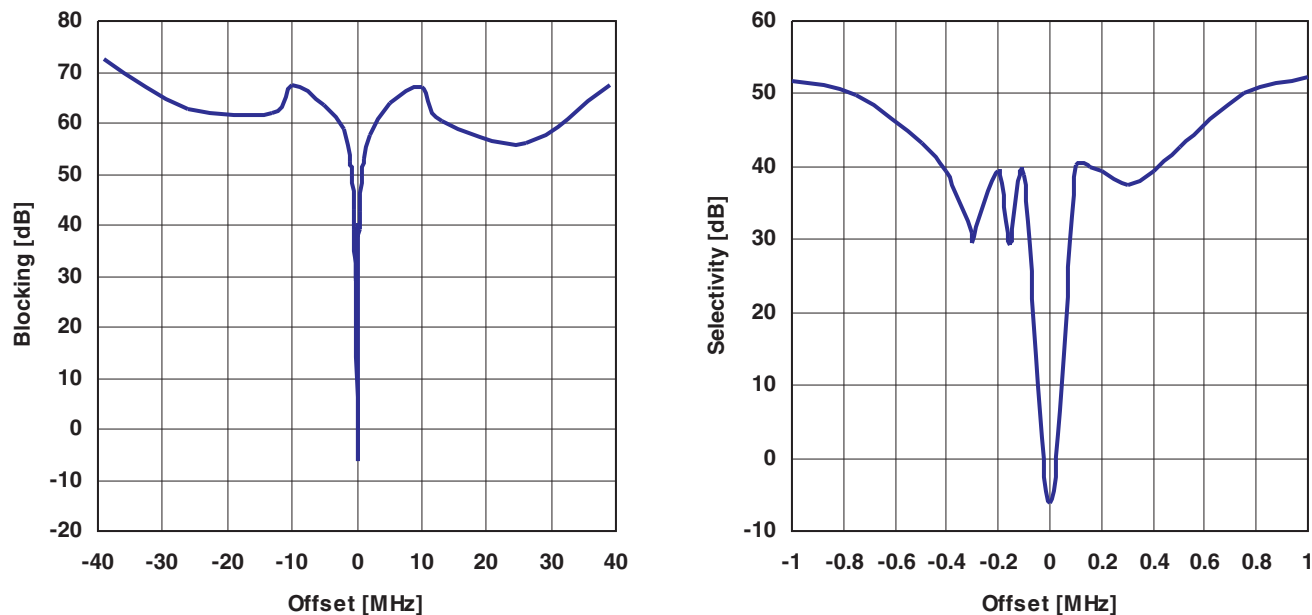
(5) See Figure 25 for blocking performance at other offset frequencies.

(6) Sensitivity can be traded for current consumption by setting MDMCFG2.DEM_DCFILT_OFF = 1. The typical current consumption is then reduced by about 2mA close to the sensitivity limit. The sensitivity is typically reduced to -100dBm.

(7) MDMCFG2.DEM_DCFILT_OFF = 1 cannot be used for data rates ≥ 250kBaud.

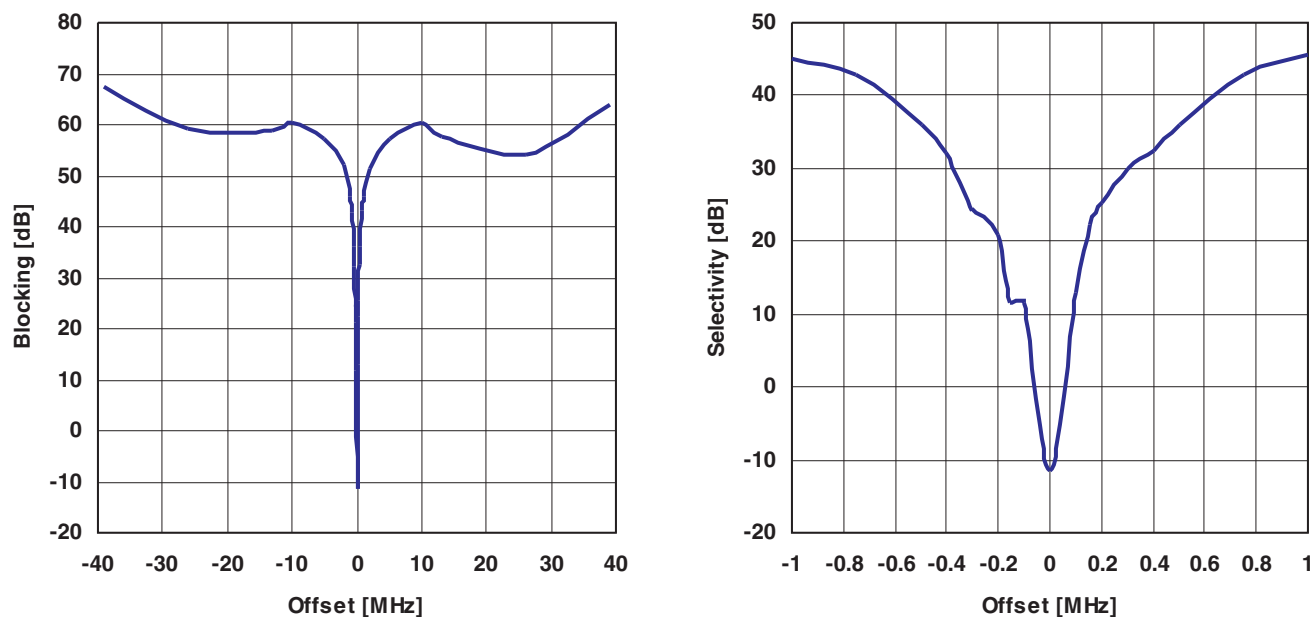
(8) See Figure 26 for blocking performance at other offset frequencies.

(9) See Figure 27 for blocking performance at other offset frequencies.



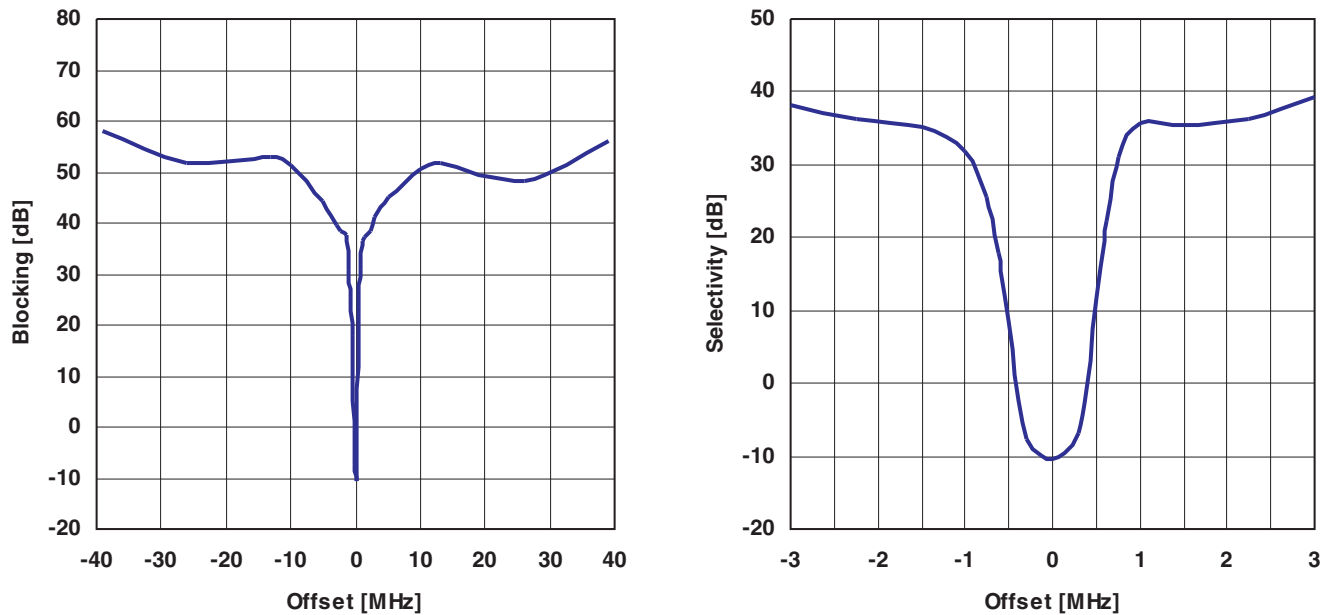
NOTE: 868.3 MHz, 2-FSK, 5.2-kHz deviation, IF frequency is 152.3 kHz, digital channel filter bandwidth is 58 kHz

Figure 24. Typical Selectivity at 1.2-kBaud Data Rate



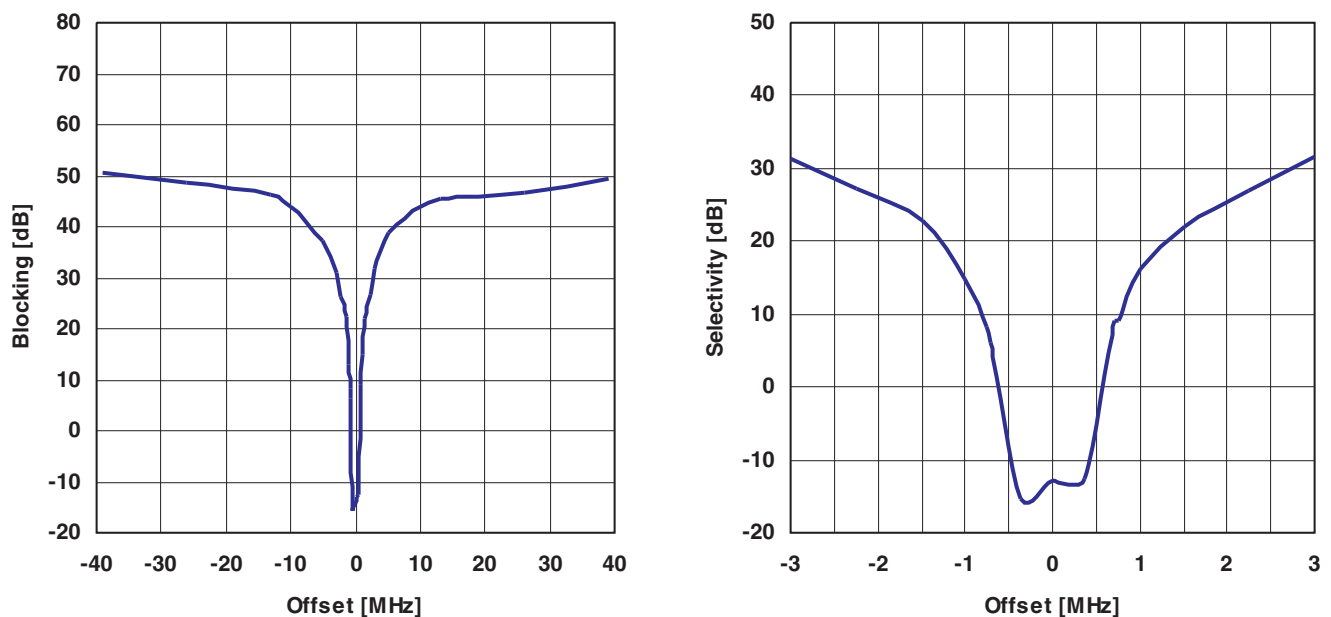
NOTE: 868 MHz, 2-FSK, 20 kHz deviation, IF frequency is 152.3 kHz, digital channel filter bandwidth is 100 kHz

Figure 25. Typical Selectivity at 38.4-kBaud Data Rate



NOTE: 868 MHz, 2-FSK, IF frequency is 304 kHz, digital channel filter bandwidth is 540 kHz

Figure 26. Typical Selectivity at 250-kBaud Data Rate



NOTE: 868 MHz, 2-FSK, IF frequency is 355 kHz, digital channel filter bandwidth is 812 kHz

Figure 27. Typical Selectivity at 500-kBaud Data Rate

Typical Sensitivity, 315 MHz, Sensitivity Optimized Setting

PARAMETER	DATA RATE (kBaud)	V _{CC}	2 V			3 V			3.6 V			UNIT
		T _A	-40°C	25°C	85°C	-40°C	25°C	85°C	-40°C	25°C	85°C	
Sensitivity, 315MHz	1.2		-112	-112	-110	-112	-111	-109	-112	-111	-108	dBm
	38.4		-105	-105	-104	-105	-103	-102	-105	-104	-102	
	250		-95	-95	-92	-94	-95	-92	-95	-94	-91	

Typical Sensitivity, 433 MHz, Sensitivity Optimized Setting

PARAMETER	DATA RATE (kBaud)	V _{CC}	2 V			3 V			3.6 V			UNIT
		T _A	-40°C	25°C	85°C	-40°C	25°C	85°C	-40°C	25°C	85°C	
Sensitivity, 433MHz	1.2		-111	-110	-108	-111	-111	-108	-111	-110	-107	dBm
	38.4		-104	-104	-101	-104	-104	-101	-104	-103	-101	
	250		-93	-94	-91	-93	-93	-90	-93	-93	-90	

Typical Sensitivity, 868 MHz, Sensitivity Optimized Setting

PARAMETER	DATA RATE (kBaud)	V _{CC}	2 V			3 V			3.6 V			UNIT
		T _A	-40°C	25°C	85°C	-40°C	25°C	85°C	-40°C	25°C	85°C	
Sensitivity, 868MHz	1.2		-109	-109	-107	-109	-109	-106	-109	-108	-106	dBm
	38.4		-102	-102	-100	-102	-102	-99	-102	-101	-99	
	250		-90	-90	-88	-89	-90	-87	-89	-90	-87	
	500		-84	-84	-81	-84	-84	-80	-84	-84	-80	

Typical Sensitivity, 915 MHz, Sensitivity Optimized Setting

PARAMETER	DATA RATE (kBaud)	V _{CC}	2 V			3 V			3.6 V			UNIT
		T _A	-40°C	25°C	85°C	-40°C	25°C	85°C	-40°C	25°C	85°C	
Sensitivity, 915MHz	1.2		-109	-109	-107	-109	-109	-106	-109	-108	-105	dBm
	38.4		-102	-102	-100	-102	-102	-99	-103	-102	-99	
	250		-92	-92	-89	-92	-92	-88	-92	-92	-88	
	500		-87	-86	-81	-86	-86	-81	-86	-85	-80	

RF Transmit

 $T_A = 25^\circ\text{C}$, $V_{CC} = 3\text{ V}$ (unless otherwise noted)⁽¹⁾, $P_{TX} = +10\text{ dBm}$ (unless otherwise noted)

PARAMETER	FREQUENCY (MHz)	TEST CONDITIONS		MIN	TYP	MAX	UNIT
Differential load impedance ⁽²⁾	315			122 + j31		Ω	
	433			116 + j41			
	868/915			86.5 + j43			
Output power, highest setting ⁽³⁾	315	Delivered to a 50Ω single-ended load via CC430 reference design's RF matching network		+12		dBm	
	433			+13			
	868			+11			
	915			+11			
Output power, lowest setting ⁽³⁾		Delivered to a 50Ω single-ended load via CC430 reference design's RF matching network		-30		dBm	
Harmonics, radiated ⁽⁴⁾⁽⁵⁾⁽⁶⁾	433	Second harmonic		-56		dBm	
		Third harmonic		-57			
		868	Second harmonic		-50		
	Third harmonic		-52				
	915		Second harmonic		-50		
		Third harmonic		-54			
Harmonics, conducted	315	Frequencies below 960 MHz	+10 dBm CW	< -38		dBm	
		Frequencies above 960 MHz		< -48			
	433	Frequencies below 1 GHz	+10 dBm CW	-45			
		Frequencies above 1 GHz		< -48			
	868	Second harmonic	+10 dBm CW	-59			
		Other harmonics		< -71			
	915	Second harmonic	+11 dBm CW ⁽⁷⁾	-53			
		Other harmonics		< -47			
Spurious emissions, conducted, harmonics not included ⁽⁸⁾	315	Frequencies below 960 MHz	+10 dBm CW	< -58		dBm	
		Frequencies above 960 MHz		< -53			
	433	Frequencies below 1 GHz	+10 dBm CW	< -54			
		Frequencies above 1 GHz		< -54			
		Frequencies within 47 to 74, 87.5 to 118, 174 to 230, 470 to 862 MHz		< -63			
	868	Frequencies below 1 GHz	+10 dBm CW	< -46			
		Frequencies above 1 GHz		< -59			
		Frequencies within 47 to 74, 87.5 to 118, 174 to 230, 470 to 862 MHz		< -56			
	915	Frequencies below 960 MHz	+11 dBm CW	< -49			
		Frequencies above 960 MHz		< -63			
TX latency ⁽⁹⁾		Serial operation		8		bits	

- (1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.
- (2) Differential impedance as seen from the RF-port (RF_P and RF_N) towards the antenna. Follow the CC430 reference designs available from the TI website.
- (3) Output power is programmable, and full range is available in all frequency bands. Output power may be restricted by regulatory limits. See also Application Note AN050 Using the CC1101 in the European 868MHz SRD Band (SWRA146) and design note DN013 Programming Output Power on CC1101 (SWRA168), which gives the output power and harmonics when using multi-layer inductors. The output power is then typically +10 dBm when operating at 868 or 915 MHz.
- (4) The antennas used during the radiated measurements (SMAFF-433 from R.W.Badland and Nearson S331 868/915) play a part in attenuating the harmonics.
- (5) Measured on EM430F6137RF900 with CW, maximum output power
- (6) All harmonics are below -41.2 dBm when operating in the 902 – 928 MHz band.
- (7) Requirement is -20 dBc under FCC 15.247
- (8) All radiated spurious emissions are within the limits of ETSI. Also see design note DN017 CC11xx 868 or 915 MHz RF Matching (SWRA168).
- (9) Time from sampling the data on the transmitter data input pin until it is observed on the RF output ports

Optimum PATABLE Settings for Various Output Power Levels and Frequency Bands

$T_A = 25^\circ\text{C}$, $V_{CC} = 3\text{ V}$ (unless otherwise noted)⁽¹⁾

Output Power [dBm]	PATABLE Setting			
	315 MHz	433 MHz	868 MHz	915 MHz
-30	0x12	0x05	0x03	0x03
-12	0x33	0x26	0x25	0x25
-6	0x29	0x2D	0x2D	0x2D
0	0x51	0x50	0x8D	0x8D
10	0xC4	0xC4	0xC3	0xC3
Maximum	0xC0	0xC0	0xC0	0xC0

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

Typical Output Power, 315 MHz⁽¹⁾

PARAMETER	PATABLE Setting	V _{CC}	2 V			3 V			3.6 V			UNIT
		T _A	-40°C	25°C	85°C	-40°C	25°C	85°C	-40°C	25°C	85°C	
Output power, 315 MHz	0xC0 (max)			11.9			11.8			11.8		dBm
	0xC4 (10 dBm)			10.3			10.3			10.3		
	0xC6 (default)						9.3					
	0x51 (0 dBm)			0.7			0.6			0.7		
	0x29 (-6 dBm)			-6.8			-5.6			-5.3		

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

Typical Output Power, 433 MHz⁽¹⁾

PARAMETER	PATABLE Setting	V _{CC}	2 V			3 V			3.6 V			UNIT
		T _A	-40°C	25°C	85°C	-40°C	25°C	85°C	-40°C	25°C	85°C	
Output power, 433 MHz	0xC0 (max)			12.6			12.6			12.6		dBm
	0xC4 (10 dBm)			10.3			10.2			10.2		
	0xC6 (default)						10.0					
	0x50 (0 dBm)			0.3			0.3			0.3		
	0x2D (-6 dBm)			-6.4			-5.4			-5.1		

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

Typical Output Power, 868 MHz⁽¹⁾

PARAMETER	PATABLE Setting	V _{CC}	2 V			3 V			3.6 V			UNIT
		T _A	-40°C	25°C	85°C	-40°C	25°C	85°C	-40°C	25°C	85°C	
Output power, 868 MHz	0xC0 (max)		11.9	11.2	10.5	11.9	11.2	10.5	11.9	11.2	10.5	dBm
	0xC3 (10 dBm)		10.8	10.1	9.4	10.8	10.1	9.4	10.7	10.1	9.4	
	0xC6 (default)						8.8					
	0x8D (0 dBm)		1.0	0.3	-0.3	1.1	0.3	-0.3	1.1	0.3	-0.3	
	0x2D (-6 dBm)		-6.5	-6.8	-7.3	-5.3	-5.8	-6.3	-4.9	-5.4	-6.0	

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

Typical Output Power, 915 MHz⁽¹⁾

PARAMETER	PATABLE Setting	V _{CC}	2 V			3 V			3.6 V			UNIT
		T _A	-40°C	25°C	85°C	-40°C	25°C	85°C	-40°C	25°C	85°C	
Output power, 915 MHz	0xC0 (max)		12.2	11.4	10.6	12.1	11.4	10.7	12.1	11.4	10.7	dBm
	0xC3 (10 dBm)		11.0	10.3	9.5	11.0	10.3	9.5	11.0	10.3	9.6	
	0xC6 (default)						8.8					
	0x8D (0 dBm)		1.9	1.0	0.3	1.9	1.0	0.3	1.9	1.1	0.3	
	0x2D (-6 dBm)		-5.5	-6.0	-6.5	-4.3	-4.8	-5.5	-3.9	-4.4	-5.1	

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

Frequency Synthesizer Characteristics

$T_A = 25^\circ\text{C}$, $V_{CC} = 3\text{ V}$ (unless otherwise noted)⁽¹⁾

MIN figures are given using a 27MHz crystal. TYP and MAX figures are given using a 26MHz crystal.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Programmed frequency resolution ⁽²⁾	26- to 27-MHz crystal	397	$f_{XOSC}/2^{16}$	412	Hz
Synthesizer frequency tolerance ⁽³⁾			±40		ppm
RF carrier phase noise	50-kHz offset from carrier		–95		dBc/Hz
	100-kHz offset from carrier		–94		
	200-kHz offset from carrier		–94		
	500-kHz offset from carrier		–98		
	1-MHz offset from carrier		–107		
	2-MHz offset from carrier		–112		
	5-MHz offset from carrier		–118		
	10-MHz offset from carrier		–129		
PLL turn-on / hop time ⁽⁴⁾	Crystal oscillator running	85.1	88.4	88.4	µs
PLL RX/TX settling time ⁽⁵⁾		9.3	9.6	9.6	µs
PLL TX/RX settling time ⁽⁶⁾		20.7	21.5	21.5	µs
PLL calibration time ⁽⁷⁾		694	721	721	µs

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

(2) The resolution (in Hz) is equal for all frequency bands.

(3) Depends on crystal used. Required accuracy (including temperature and aging) depends on frequency band and channel bandwidth / spacing.

(4) Time from leaving the IDLE state until arriving in the RX, FSTXON, or TX state, when not performing calibration.

(5) Settling time for the 1-IF frequency step from RX to TX

(6) Settling time for the 1-IF frequency step from TX to RX

(7) Calibration can be initiated manually or automatically before entering or after leaving RX/TX.

Typical RSSI_offset Values

$T_A = 25^\circ\text{C}$, $V_{CC} = 3\text{ V}$ (unless otherwise noted)⁽¹⁾

DATA RATE (kBaud)	RSSI_OFFSET (dB)	
	433 MHz	868 MHz
1.2	74	74
38.4	74	74
250	74	74
500	74	74

(1) All measurement results are obtained using the EM430F6137RF900 with BOM according to tested frequency range.

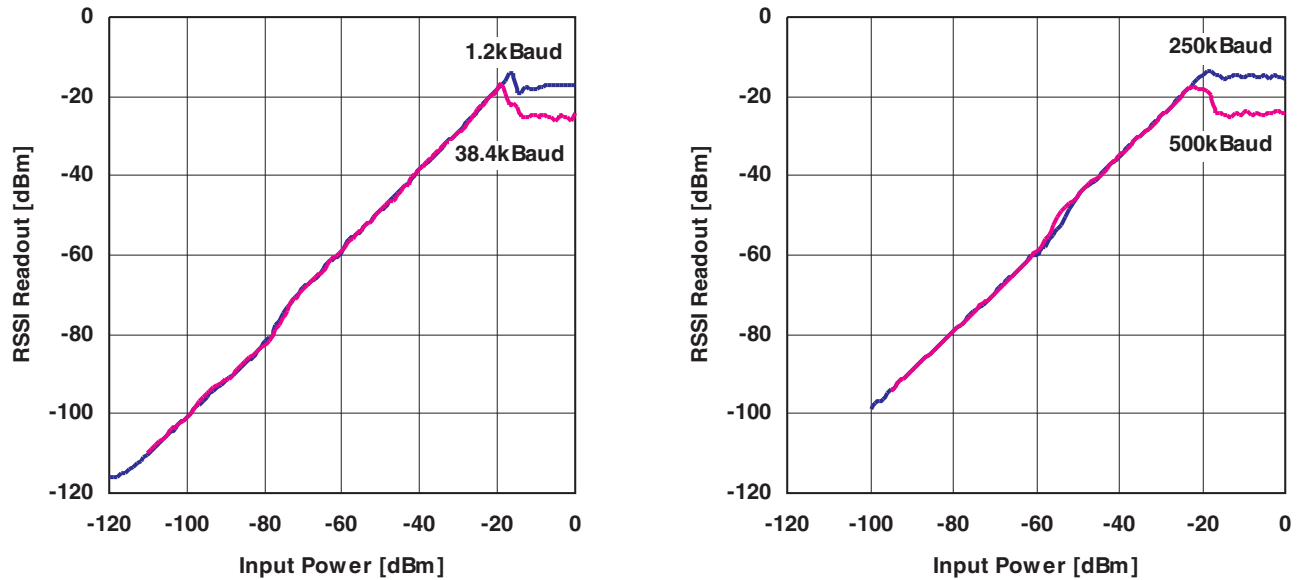


Figure 28. Typical RSSI Value vs Input Power Level for Different Data Rates at 868 MHz

3D LF Front End Parameters

Recommended Operating Conditions

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{BAT}	Supply voltage range during LF operation	2.0		3.6	V
RF crystal load capacitance		10	13	20	pF
RF crystal effective series resistance				100	Ω

Resonant Circuits - LF Front End

The resonance circuit quality factor Q_{OP} can have a wide range between 10 and 120. The resonance frequency can be trimmed by the embedded trimming capacitor array.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
f _{RES} Resonant circuit frequency	25°C	133.2	134.2	135.2	kHz
f _L Low bit transmit frequency	25°C, Q _{OP} = 10 to 120	133.2	134.2	135.2	
	-40°C to 85°C, Q _{OP} = 10 to 120	132.2	134.2	136.2	
f _H High bit transmit frequency	25°C, Q _{OP} = 10 to 120	123.2	134.2	125.2	
	-40°C to 85°C, Q _{OP} = 10 to 120	122.2	134.2	126.2	

External Antenna Coil - LF Front End

The antenna coil L_R, resonant capacitor C_R and charge capacitor C_L are external components with following recommended parameters

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
L _{R1} Equivalent inductance	25°C, f = 134.2 kHz	7.37	7.6	7.81	mH
L _{R2} Equivalent inductance	25°C, f = 134.2 kHz	4.37	4.5	4.63	mH
dL _R /L _R dT Temperature coefficient of L _R	-40°C to 85°C			250	ppm/°C
Q _{LRT} Quality factor of L _R	-40°C to 85°C	10		150	

Resonant Circuit Capacitor - LF Front End

The input capacitance of the RF pins C_{RF} is the sum of parasitic capacitances of circuit blocks connected to the RF pin. The Trim Capacitors are internal capacitances and can be programmed on or off. The resonance capacitor C_R is an external component and is not part of this IC.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
C _R Resonant circuit capacitor (option 1) (dCR = ±2.0%)	L _R = 7.6mH	147	150	153	pF
C _R Resonant circuit capacitor (option 2) (dCR = ±2.0%)	L _R = 4.5mH	264.6	270	275.4	pF
Dielectric of C _R	dL _R /L _R dT ≤ 250 ppm		NPO		
dC _R /C _R dT Temperature coefficient of C _R (NP0)	dL _R /L _R dT ≤ 250 ppm		±30	73	ppm/°C
Q _{CR} Quality factor		2000			
V _{RF} Operating voltage		20	50		V _{PP}
C _{RF} RF input capacitance	V _{CL} = 5 V CT = off	21.3	24	26.6	pF
Q _{RF} IC input quality factor (RF1, RF2, RF3)	V _{RF} = 0.1 V, CT = max, CM = on or off	250	350		
Capacitance voltage dependancy	V _{CL} = 0 to 5 V, CT = on or off		-1		%/V
T _{step} Trimming steps			128		
CT _{min} Minimum trimming capacitor			0		pF
CT Maximum trimming capacitor (CT = CT1 + CT2 + ... + CT7)	Calculated		0.6		pF
CT1 Trimming capacitor 1			1.2		pF
CT2 Trimming capacitor 2			2.4		pF
CT3 Trimming capacitor 3			4.7		pF

Resonant Circuit Capacitor - LF Front End (continued)

The input capacitance of the RF pins C_{RF} is the sum of parasitic capacitances of circuit blocks connected to the RF pin. The Trim Capacitors are internal capacitances and can be programmed on or off. The resonance capacitor C_R is an external component and is not part of this IC.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
CT4	Trimming capacitor 4			9.4		pF
CT5	Trimming capacitor 5			18.8		pF
CT6	Trimming capacitor 6			37.6		pF
CT7	Trimming capacitor 7		70.8	74.7	78.8	pF
dCT/dV	Voltage coefficient of CT				0.1	pF/V
dCT/dT	Temperature coefficient of CT				0.02	pF/K
CM1	Modulation capacitor 4.5 mH: CM1+ CM2 7.6 mH: CM1	Integrated capacitor	33.1	35.0	36.9	pF
CM2	Modulation capacitor	Integrated capacitor	17.0	18.0	19.0	pF
dCM/dV	Modulation capacitor voltage coefficient	25°C			0.1	%/V
dCM/dT	Modulation capacitor voltage coefficient				0.02	pF/K

Charge Capacitor - LF Front End

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
CL	Charge capacitor (dCL = ±10%)	25°C, $Q_{OP} = 134.2$ kHz	198	220	242	nF
dCL(T)	Temperature coefficient of CL	-40°C to 85°C	-10		10	%
	Dielectric of CL			XR7		
DCL(t)	Charge capacitor aging	100000 h	-10		0	%

LF Wake Receiver Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

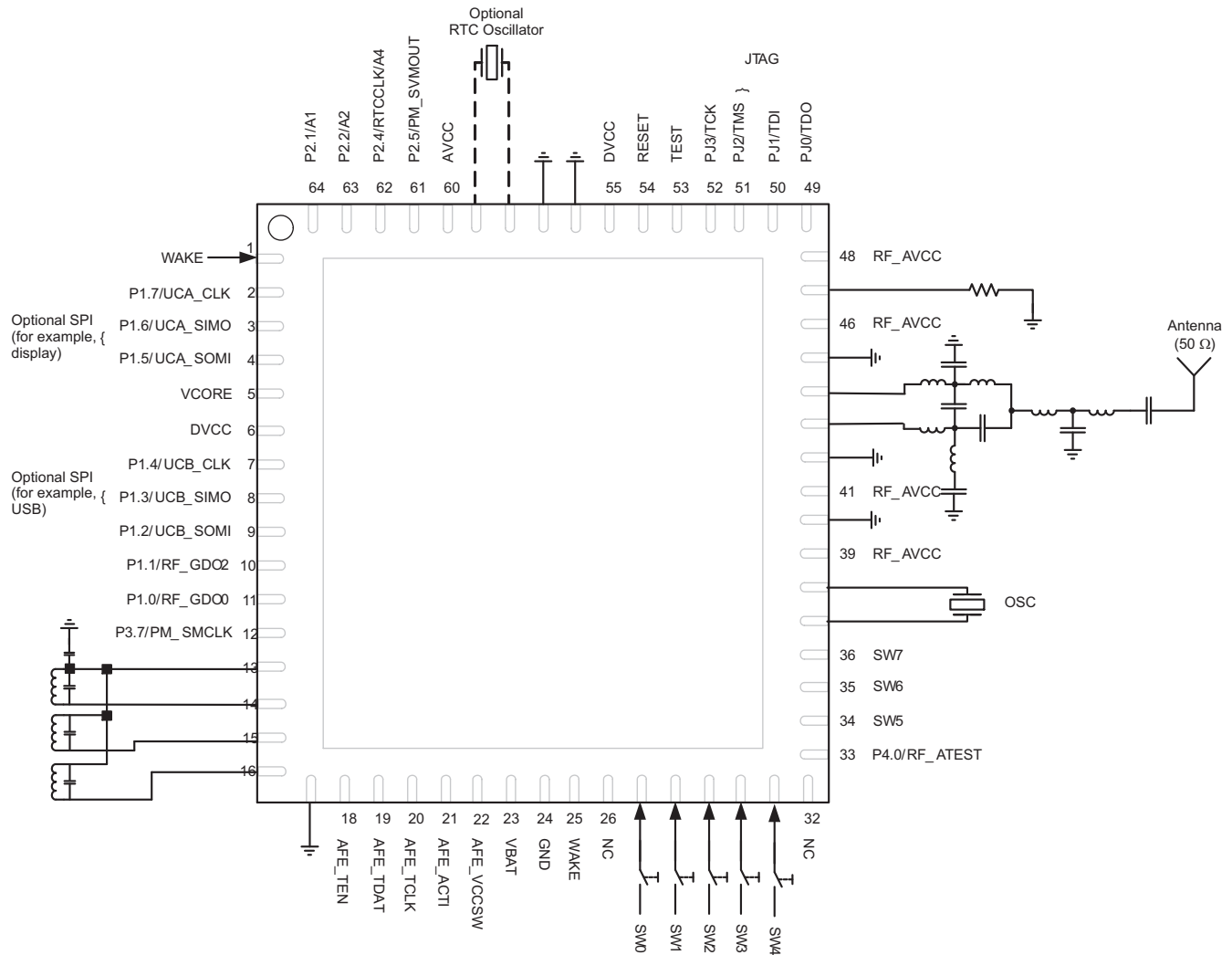
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$f_{RES,PE}$	Resonant circuit frequency	25°C	110		140	kHz
t_{WakeUp}	Wake-up time		500	560	1000	μs
I_{PESBWP}	Standby current	Wake pattern A active, wake pattern B off, regular sensitivity, $V_{BAT} = 3$ V		4.4		μA
V_{WAKEA}	Sensitivity A (regular)	Configured to highest sensitivity	2.6	3.7	6.2	mV _{pp}
V_{WAKEA}	Sensitivity A (regular)	Configured to lowest sensitivity	9	13.5	23	mV _{pp}
V_{WAKEA}	Sensitivity A (high sensitivity mode)	Configured to highest sensitivity and high sensitivity mode	0.3	0.5	0.9	mV _{pp}
V_{WAKEB}	Sensitivity B	Configured to highest sensitivity	2.3	4.2	7.5	mV _{pp}
V_{WAKEB}	Sensitivity B	Configured to lowest sensitivity	50	110	200	mV _{pp}
VRF	Maximum RF input voltage				10	V _{pp}
S/N	Wake pattern detection error rate (S/N)			10		dB
t_{sA}	WDE settling time (wake A, low sensitivity)				500	μs
t_{sAh}	WDE settling time (wake A, high sensitivity)				600	μs
t_{sB}	WDE settling time (wake B)				2000	μs
t_{resA}	WDE resetting time (strong burst recovery time)	Step VRF 2V _{pp} to 10mV _{pp}			3000	μs

RSSI - LF Wake Receiver Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
DR	Dynamic range			72		dB
VRF	Input voltage range		0.002		8	Vpp
A	RSSI linear coefficient			28		
B	RSSI constant coefficient			180		
#RSSI	Number of RSSI values			128		
Verr16mV	Absolute RSSI error at VRF = 16 mVpp		-1.28		1.28	mVpp
err16mV	Relative RSSI error VRF ≥ 16 mVpp		-8		8	%
Verr2mV	Absolute RSSI error at VRF = 2 mVpp		-0.4		0.4	mVpp
err2mV	Relative RSSI error at VRF = 2 mVpp		-20		20	%
Vmin	Resolution at VRF = 2 mVpp		0.14			mV
t	Measurement time (all three channels)				2	ms

APPLICATION CIRCUIT



For a complete reference design including layout, see the RF430 Wireless Development Tools and related documentation [*MSP430 Hardware Tools User's Guide* ([SLAU278](#))].

Figure 29. Typical Application Circuit RF430F5978

INPUT/OUTPUT SCHEMATICS

Port P1, P1.0 to P1.4, Input/Output With Schmitt Trigger

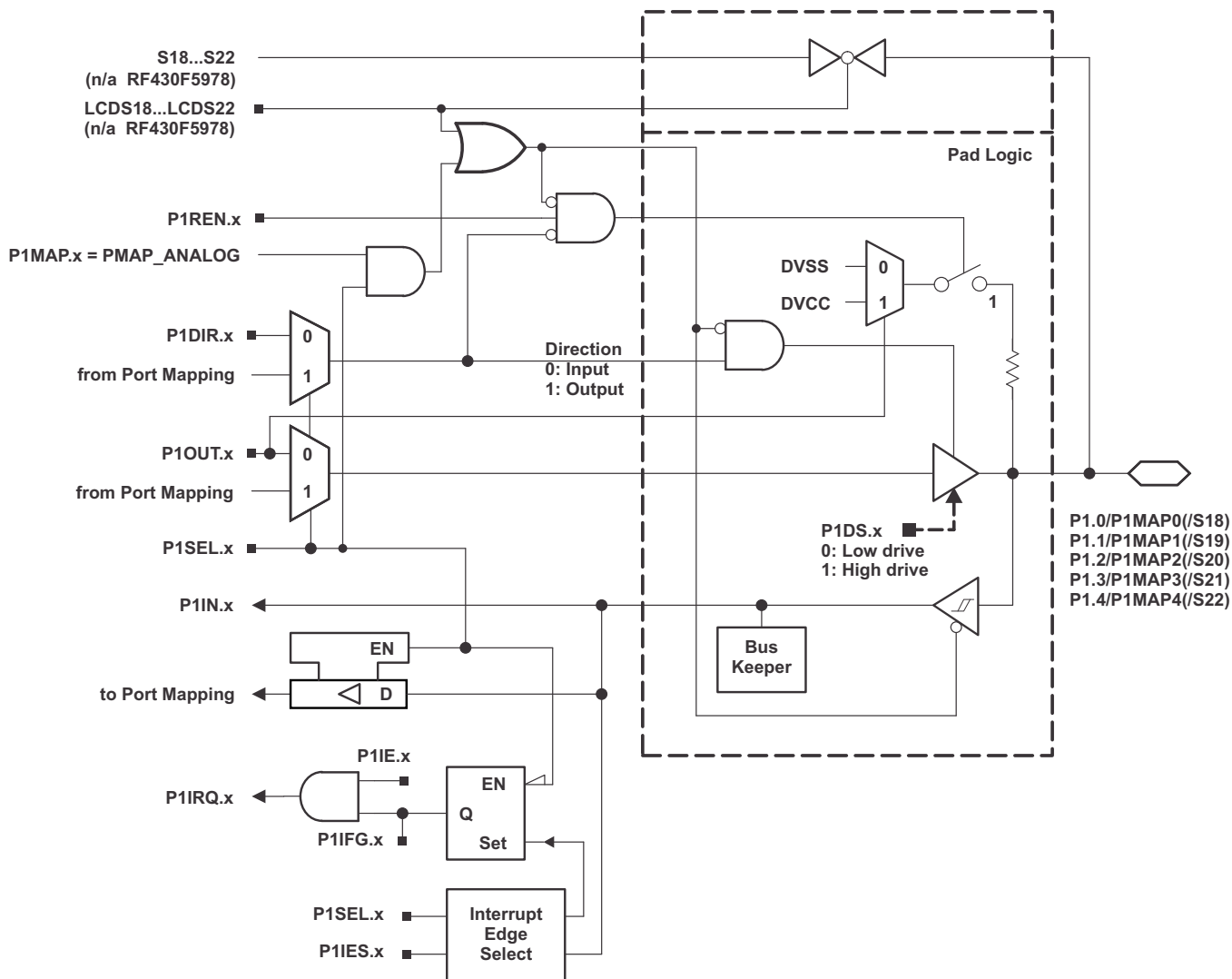


Table 49. Port P1 (P1.0 to P1.4) Pin Functions

PIN NAME (P1.x)	x	FUNCTION	CONTROL BITS/SIGNALS ⁽¹⁾			
			P1DIR.x	P1SEL.x	P1MAPx	LCDS19... 22
P1.0/P1MAP/S18	0	P1.0 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾	0
		Output driver and input Schmitt trigger disabled	X	1	= 31	0
		S18	X	X	X	1
P1.1/P1MAP1/S19	1	P1.1 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾	0
		Output driver and input Schmitt trigger disabled	X	1	= 31	0
		S19	X	X	X	1
P1.2/P1MAP2/S20	2	P1.2 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾	0
		Output driver and input Schmitt trigger disabled	X	1	= 31	0
		S22	X	X	X	1
P1.3/P1MAP3/S21	3	P1.3 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾	0
		Output driver and input Schmitt trigger disabled	X	1	= 31	0
		S21	X	X	X	1
P1.4/P1MAP4/S22	4	P1.4 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾	0
		Output driver and input Schmitt trigger disabled	X	1	= 31	0
		S22	X	X	X	1

(1) X = don't care

(2) According to mapped function - see [Table 11](#).

Port P1, P1.5 to P1.7, Input/Output With Schmitt Trigger

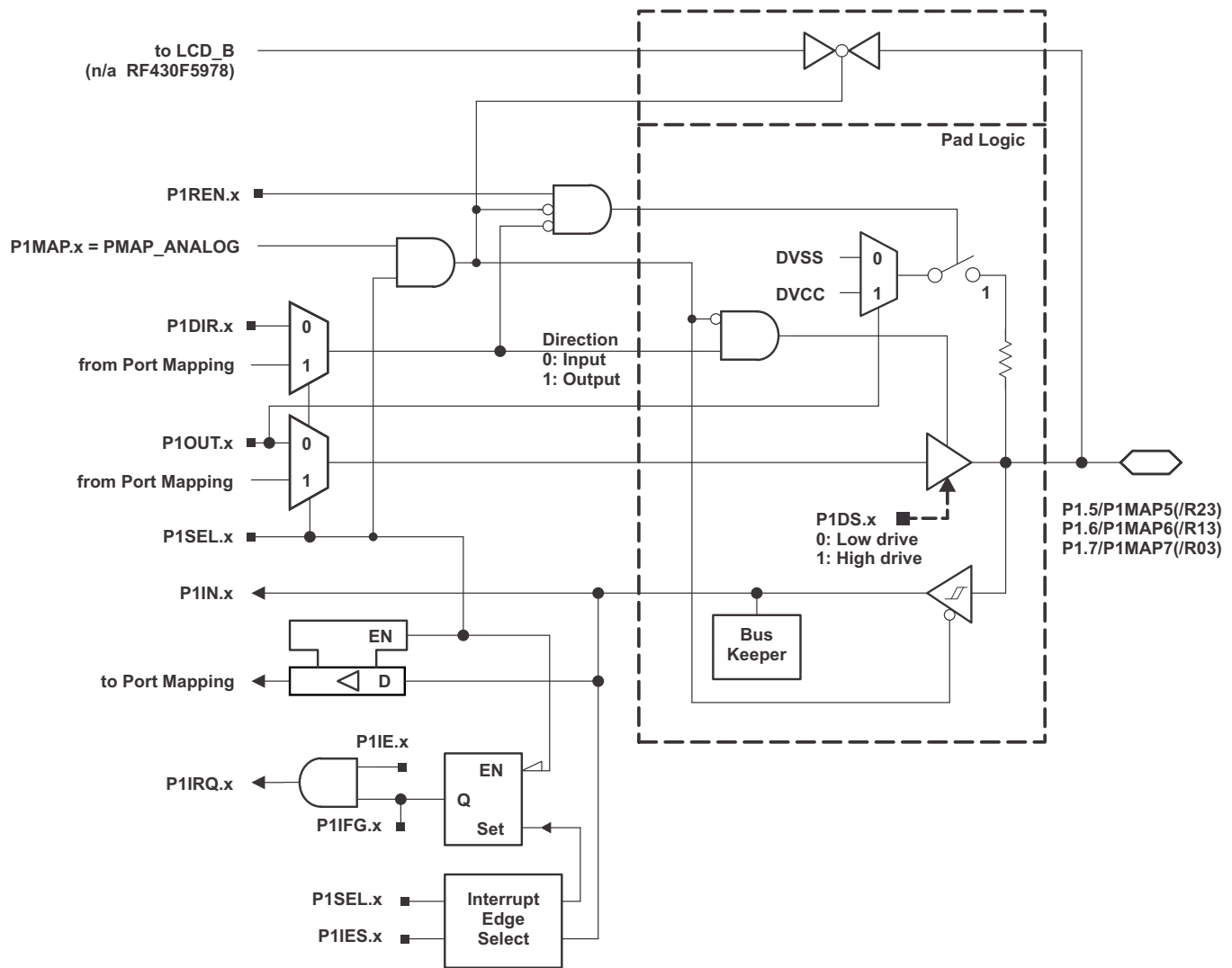


Table 50. Port P1 (P1.5 to P1.7) Pin Functions

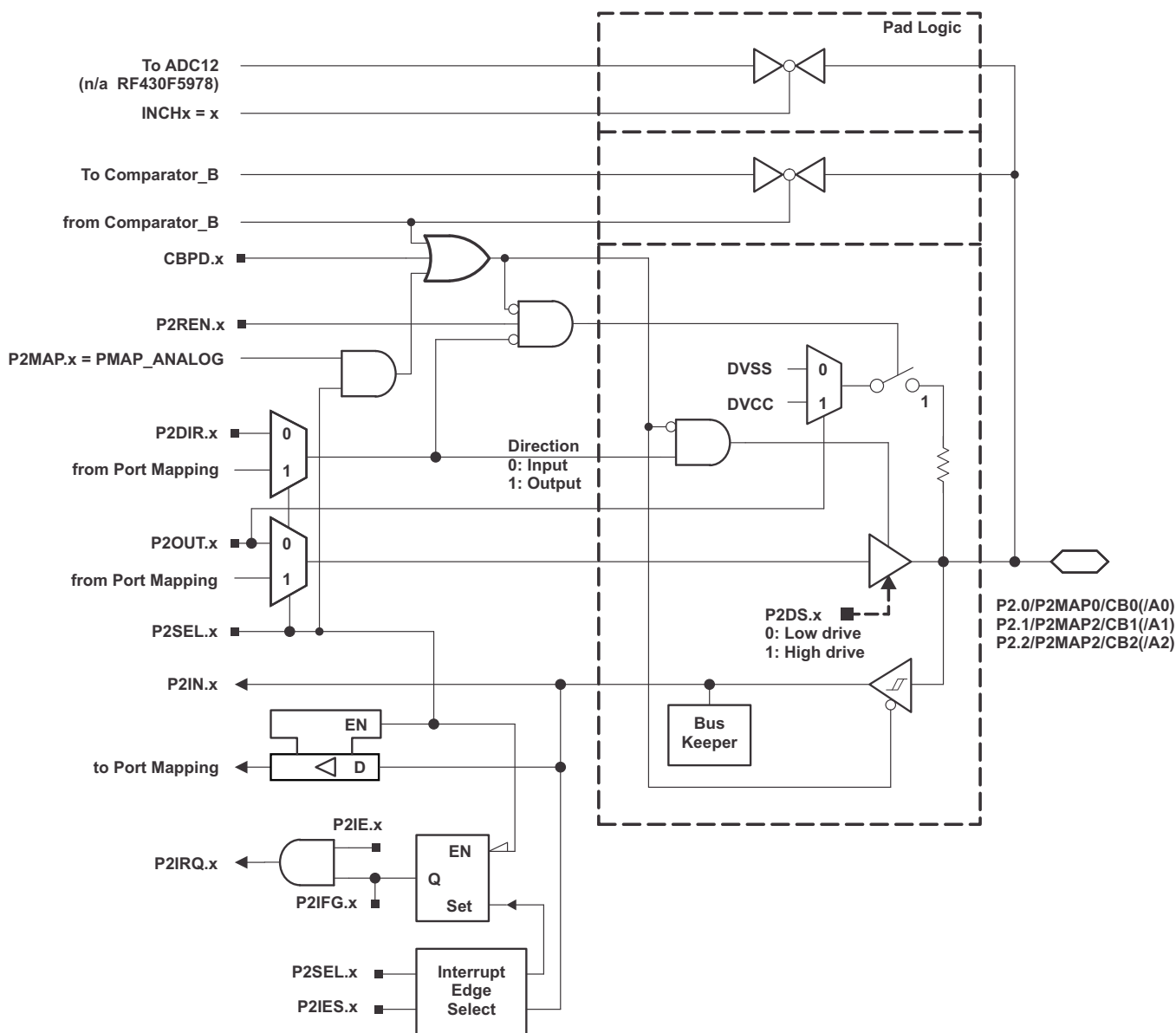
PIN NAME (P1.x)	x	FUNCTION	CONTROL BITS/SIGNALS ⁽¹⁾		
			P1DIR.x	P1SEL.x	P1MAPx
P1.5/P1MAP5/R23	5	P1.5 (I/O)	I: 0; O: 1	0	X
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾
		R23 ⁽³⁾	X	1	= 31
P1.6/P1MAP6/R13/ LCDREF	6	P1.6 (I/O)	I: 0; O: 1	0	X
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾
		R13/LCDREF ⁽³⁾	X	1	= 31
P1.7/P1MAP7/R03	7	P1.7 (I/O)	I: 0; O: 1	0	X
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾
		R03 ⁽³⁾	X	1	= 31

(1) X = don't care

(2) According to mapped function - see [Table 11](#).

(3) Setting P1SEL.x bit together with P1MAPx = PM_ANALOG disables the output driver and the input Schmitt trigger.

Port P2, P2.0 to P2.2, Input/Output With Schmitt Trigger



Port P2, P2.4 and P2.5, Input/Output With Schmitt Trigger

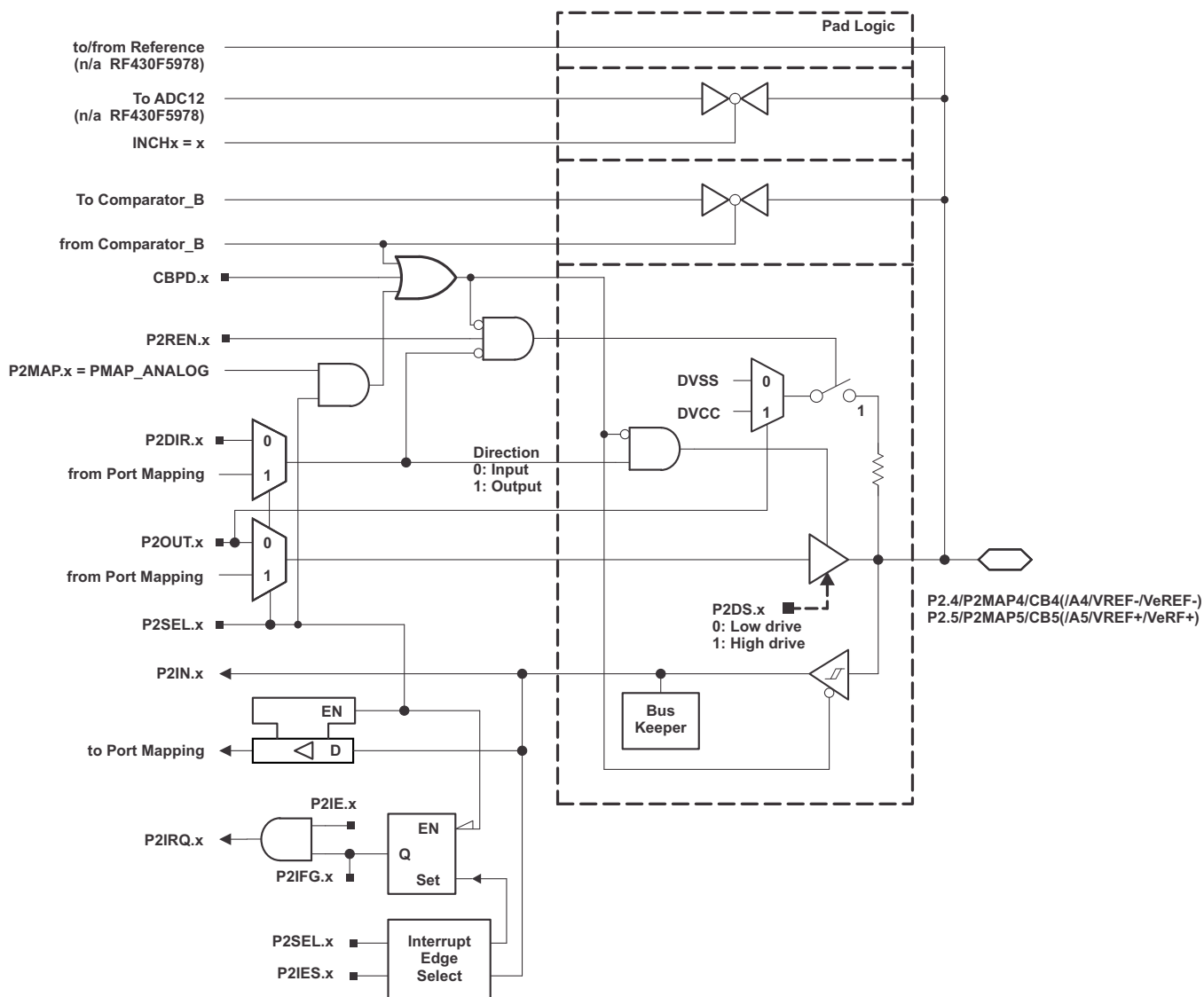


Table 51. Port P2 (P2.0 to P2.2, P2.4, and P2.5) Pin Functions

PIN NAME (P2.x)	x	FUNCTION	CONTROL BITS/SIGNALS ⁽¹⁾			
			P2DIR.x	P2SEL.x	P2MAPx	CBPD.x
P2.0/P2MAP0/CB0 (/A0)	0	P2.0 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾	0
		A0 ⁽³⁾	X	1	= 31	X
		CB0 ⁽⁴⁾	X	X	X	1
P2.1/P2MAP1/CB1 (/A1)	1	P2.1 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾	0
		A1 ⁽³⁾	X	1	= 31	X
		CB1 ⁽⁴⁾	X	X	X	1
P2.2/P2MAP2/CB2 (/A2)	2	P2.2 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾	0
		A2 ⁽³⁾	X	1	= 31	X
		CB2 ⁽⁴⁾	X	X	X	1
P2.4/P2MAP4/CB4 (/A4/VREF-/VeREF-)	4	P2.4 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾	0
		A4/VREF-/VeREF- ⁽³⁾	X	1	= 31	X
		CB4 ⁽⁴⁾	X	X	X	1
P2.5/P2MAP5/CB5 (/A5/VREF+/VeREF+)	5	P2.5 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽²⁾	1	≤ 30 ⁽²⁾	0
		A5/VREF+/VeREF+ ⁽³⁾	X	1	= 31	X
		CB5 ⁽⁴⁾	X	X	X	1

- (1) X = don't care
- (2) According to mapped function - see [Table 11](#).
- (3) Setting P2SEL.x bit together with P2MAPx = PM_ANALOG disables the output driver and the input Schmitt trigger.
- (4) Setting the CBPD.x bit disables the output driver and the input Schmitt trigger to prevent parasitic cross currents when applying analog signals. Selecting the CBx input pin to the comparator multiplexer with the CBx bits automatically disables output driver and input buffer for that pin, regardless of the state of the associated CBPD.x bit.

Port P3, P3.1 to P3.3, P3.5, and P3.7, Input/Output With Schmitt Trigger

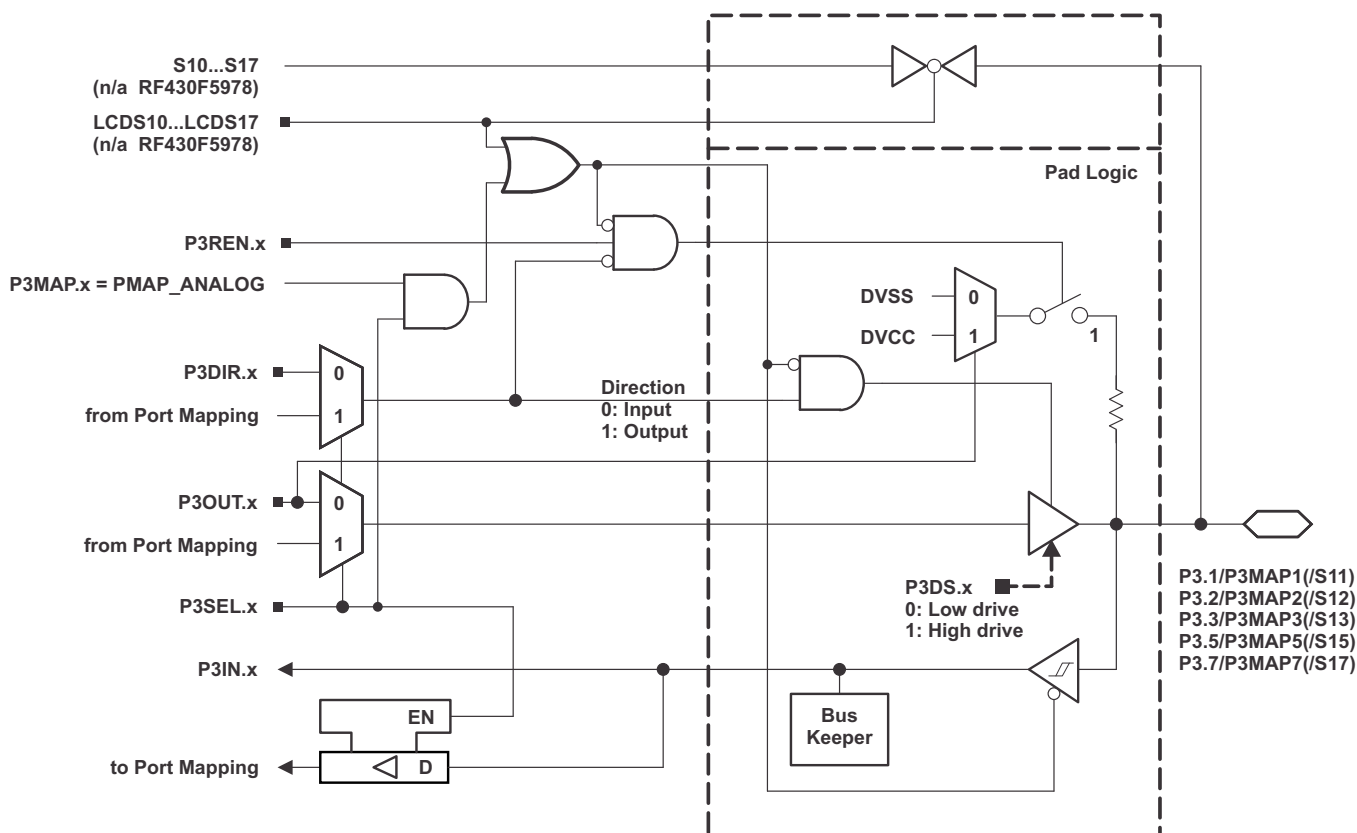


Table 52. Port P3 (P3.1 to P3.3, P3.5, and P3.7) Pin Functions

PIN NAME (P3.x)	x	FUNCTION	CONTROL BITS/SIGNALS ⁽¹⁾			
			P3DIR.x	P3SEL.x	P3MAPx	LCDS10... 17
P3.1/P3MAP1/S11 ⁽²⁾	1	P3.1 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽³⁾	1	≤ 30 ⁽³⁾	0
		Output driver and input Schmitt trigger disabled	X	1	= 31	0
		S11	X	X	X	1
P3.2/P3MAP7/S12 ⁽²⁾	2	P3.2 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽³⁾	1	≤ 30 ⁽³⁾	0
		Output driver and input Schmitt trigger disabled	X	1	= 31	0
		S12	X	X	X	1
P3.3/P3MAP3/S13 ⁽²⁾	3	P3.3 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽³⁾	1	≤ 30 ⁽³⁾	0
		Output driver and input Schmitt trigger disabled	X	1	= 31	0
		S13	X	X	X	1
P3.5/P3MAP5/S15 ⁽²⁾	5	P3.5 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽³⁾	1	≤ 30 ⁽³⁾	0
		Output driver and input Schmitt trigger disabled	X	1	= 31	0
		S15	X	X	X	1
		S16	X	X	X	1
P3.7/P3MAP7/S17	7	P3.7 (I/O)	I: 0; O: 1	0	X	0
		Mapped secondary digital function - see Table 11	0; 1 ⁽³⁾	1	≤ 30 ⁽³⁾	0
		Output driver and input Schmitt trigger disabled	X	1	= 31	0
		S17	X	X	X	1

- (1) X = don't care
(2) Internal connection to LF front end
(3) According to mapped function - see [Table 11](#).

Port P4, P4.0 to P4.2, Input/Output With Schmitt Trigger

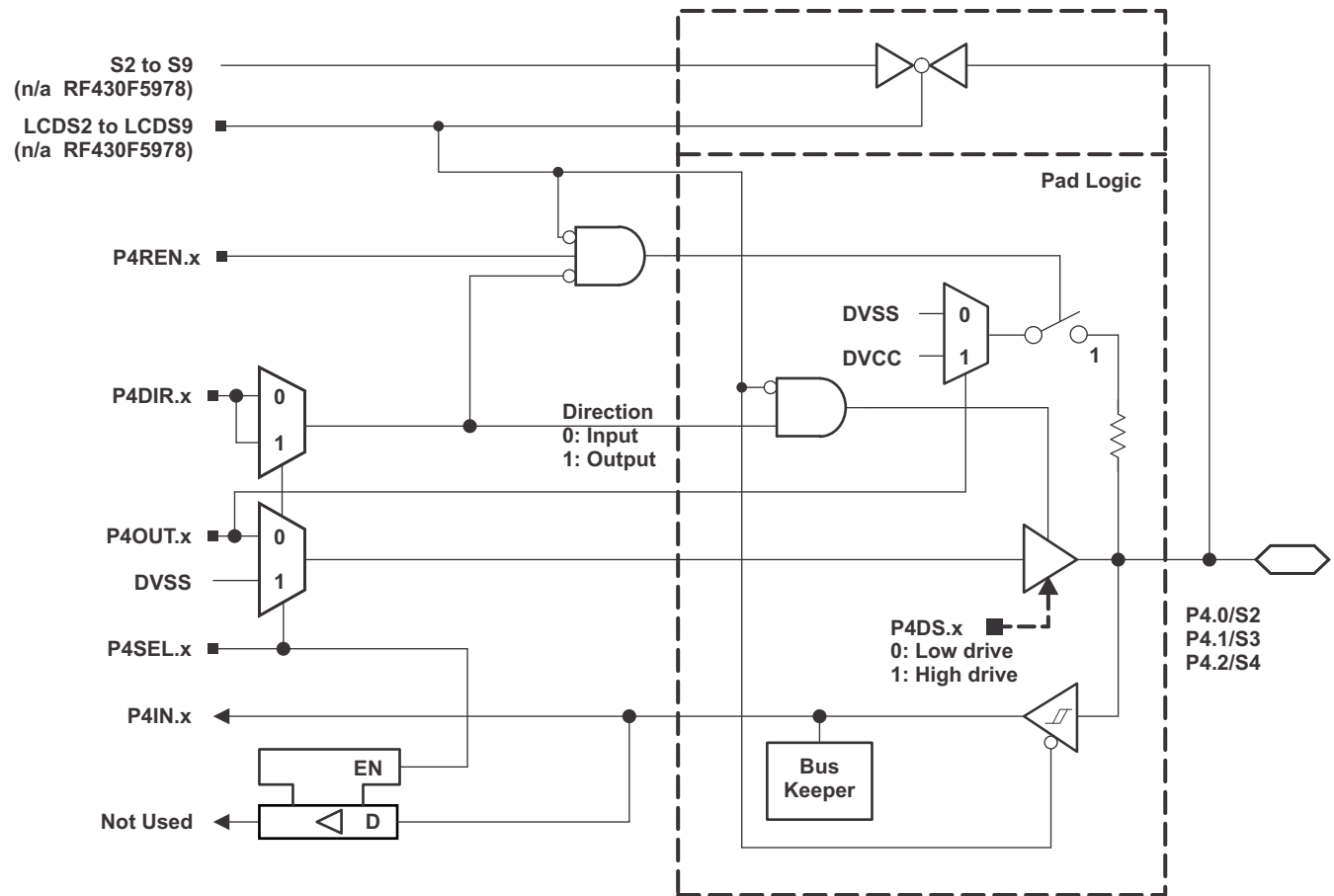


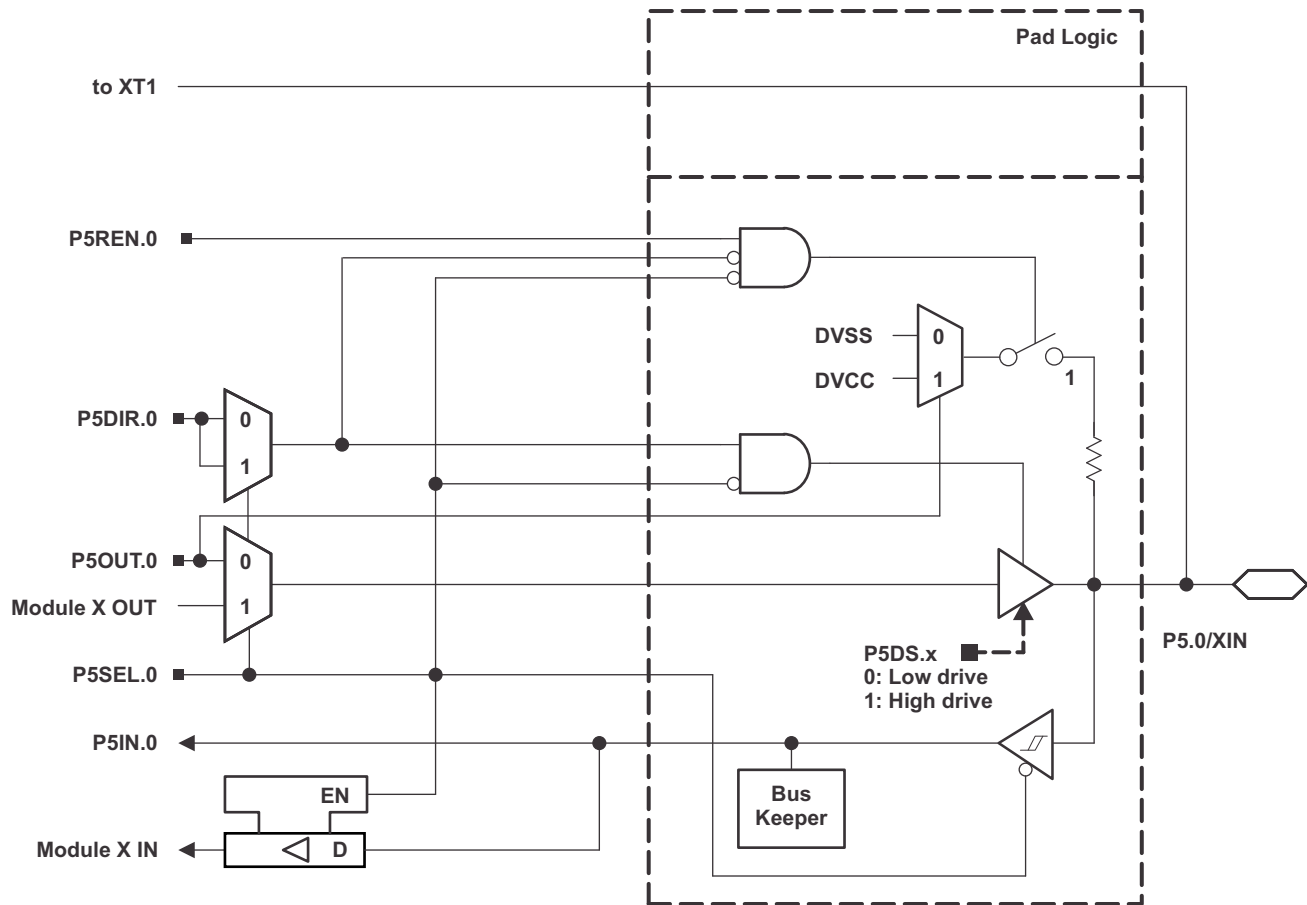
Table 53. Port P4 (P4.0 to P4.2) Pin Functions

PIN NAME (P4.x)	x	FUNCTION	CONTROL BITS/SIGNALS ⁽¹⁾		
			P4DIR.x	P4SEL.x	LCDS2...7
P4.0/P4MAP0/S2	0	P4.0 (I/O)	I: 0; O: 1	0	0
		N/A	0	1	0
		DVSS	1	1	0
		S2	X	X	1
P4.1/P4MAP1/S3 ⁽²⁾	1	P4.1 (I/O)	I: 0; O: 1	0	0
		N/A	0	1	0
		DVSS	1	1	0
		S3	X	X	1
P4.2/P4MAP7/S4 ⁽²⁾	2	P4.2 (I/O)	I: 0; O: 1	0	0
		N/A	0	1	0
		DVSS	1	1	0
		S4	X	X	1

(1) X = don't care

(2) Internal connection to LF front end

Port P5, P5.0, Input/Output With Schmitt Trigger



Port P5, P5.1, Input/Output With Schmitt Trigger

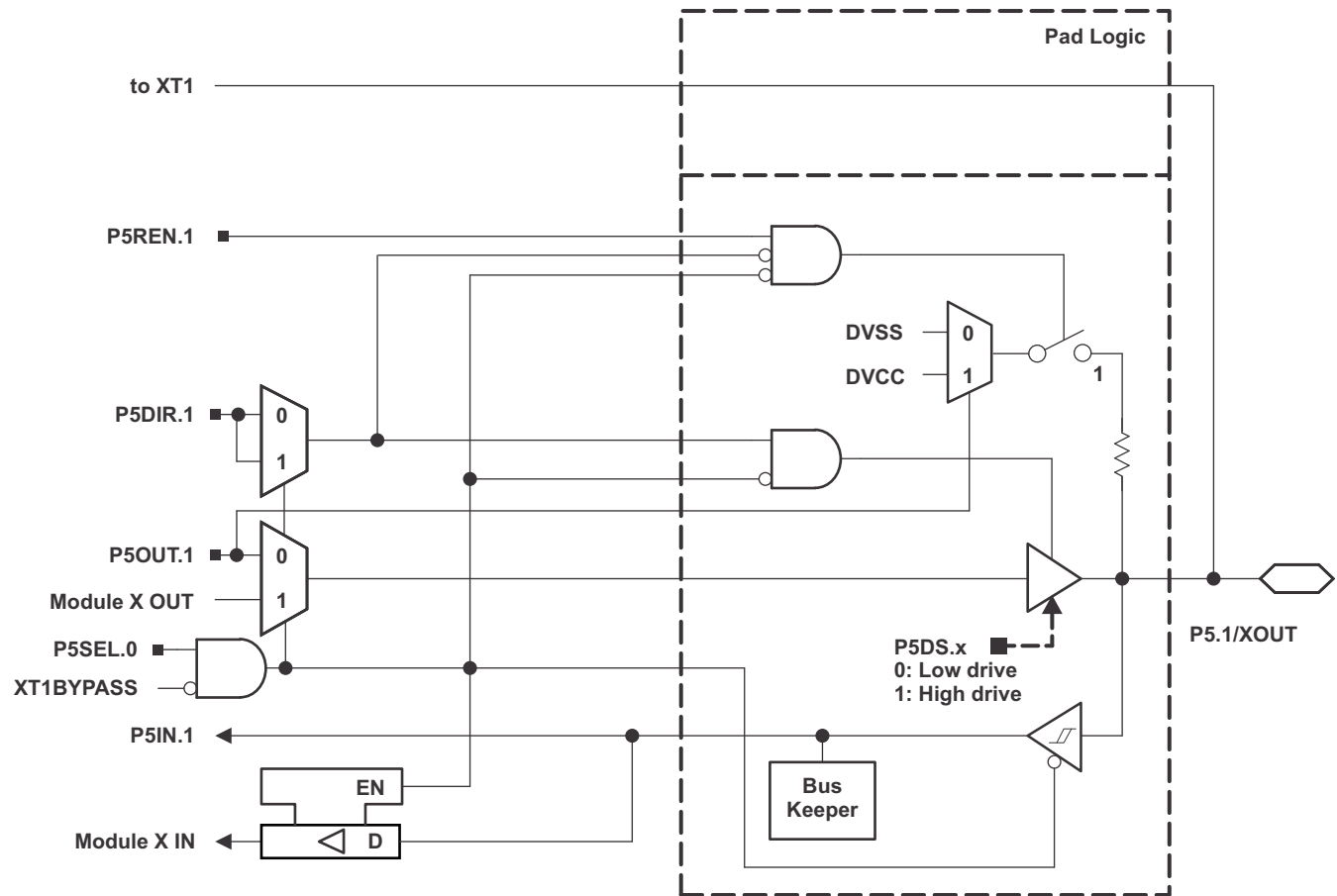


Table 54. Port P5 (P5.0 and P5.1) Pin Functions

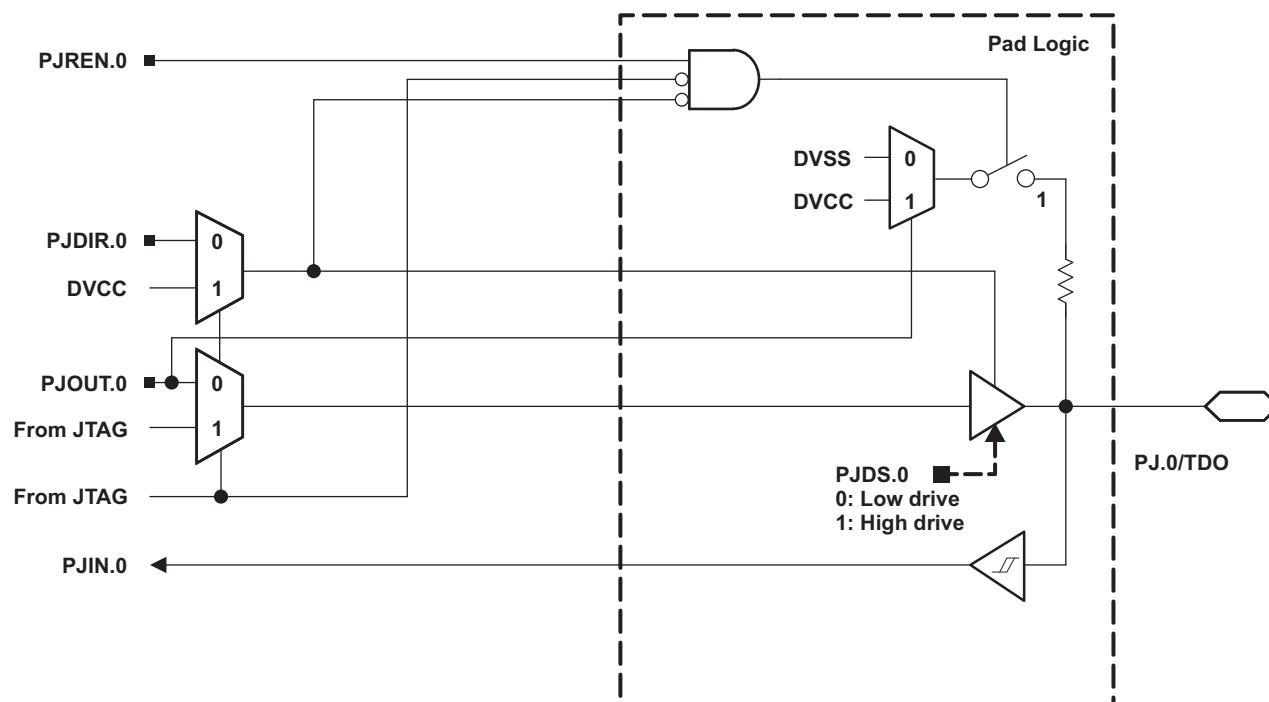
PIN NAME (P5.x)	x	FUNCTION	CONTROL BITS/SIGNALS ⁽¹⁾			
			P5DIR.x	P5SEL.0	P5SEL.1	XT1BYPASS
P5.0/XIN	0	P5.0 (I/O)	I: 0; O: 1	0	X	X
		XIN crystal mode ⁽²⁾	X	1	X	0
		XIN bypass mode ⁽²⁾	X	1	X	1
P5.1/XOUT	1	P5.1 (I/O)	I: 0; O: 1	0	X	X
		XOUT crystal mode ⁽³⁾	X	1	X	0
		P5.1 (I/O) ⁽³⁾	X	1	X	1

(1) X = don't care

(2) Setting P5SEL.0 causes the general-purpose I/O to be disabled. Pending the setting of XT1BYPASS, P5.0 is configured for crystal mode or bypass mode.

(3) Setting P5SEL.0 causes the general-purpose I/O to be disabled in crystal mode. When using bypass mode, P5.1 can be used as general-purpose I/O.

Port J, J.0 JTAG Pin TDO, Input/Output With Schmitt Trigger or Output



Port J, J.1 to J.3 JTAG Pins TMS, TCK, TDI/TCLK, Input/Output With Schmitt Trigger or Output

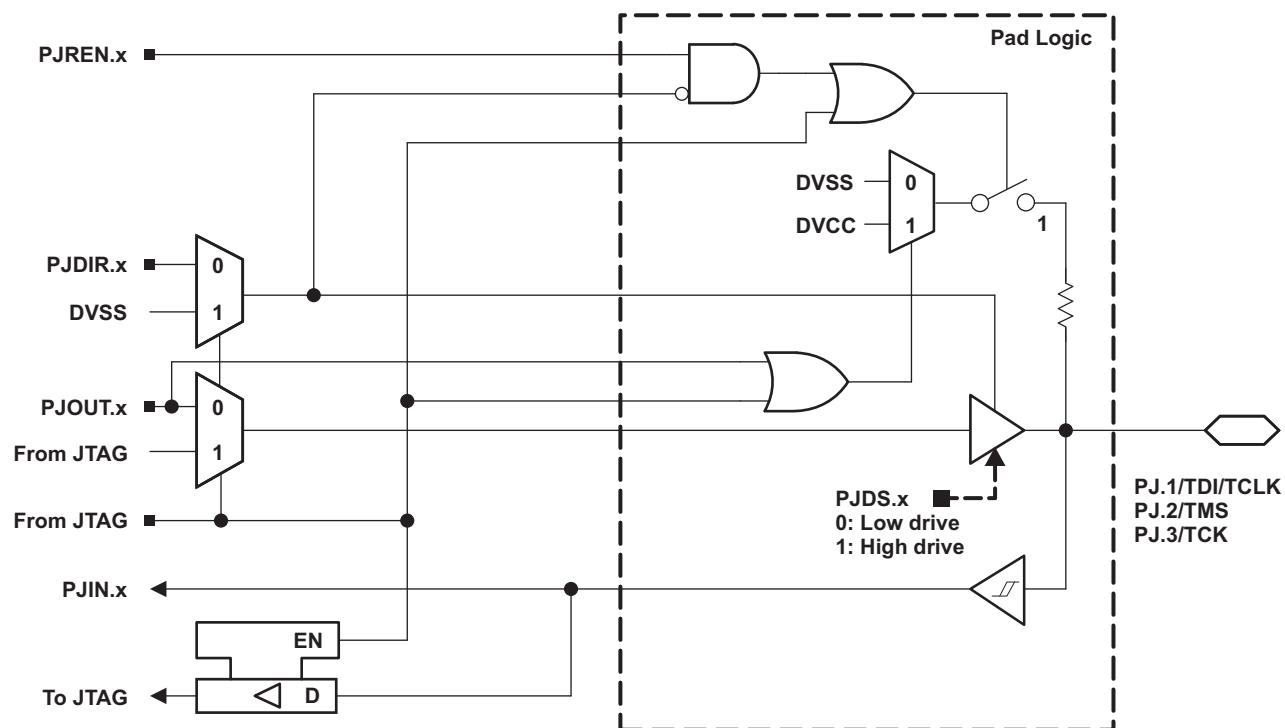


Table 55. Port PJ (PJ.0 to PJ.3) Pin Functions

PIN NAME (PJ.x)	x	FUNCTION	CONTROL BITS/ SIGNALS ⁽¹⁾
			PJDIR.x
PJ.0/TDO	0	PJ.0 (I/O) ⁽²⁾	I: 0; O: 1
		TDO ⁽³⁾	X
PJ.1/TDI/TCLK	1	PJ.1 (I/O) ⁽²⁾	I: 0; O: 1
		TDI/TCLK ^{(3) (4)}	X
PJ.2/TMS	2	PJ.2 (I/O) ⁽²⁾	I: 0; O: 1
		TMS ^{(3) (4)}	X
PJ.3/TCK	3	PJ.3 (I/O) ⁽²⁾	I: 0; O: 1
		TCK ^{(3) (4)}	X

(1) X = don't care

(2) Default condition

(3) The pin direction is controlled by the JTAG module.

(4) In JTAG mode, pullups are activated automatically on TMS, TCK, and TDI/TCLK. PJREN.x are do not care.

Device Descriptor Structures

Table 56 lists the content of the device descriptor tag-length-value (TLV) structure for RF430F5978.

Table 56. Device Descriptor Table

	Description	Address	Size bytes	RF430F5978
				Value
Info Block	Info length	01A00h	1	06h
	CRC length	01A01h	1	06h
	CRC value	01A02h	2	per unit
	Device ID	01A04h	1	61h
	Device ID	01A05h	1	37h
	Hardware revision	01A06h	1	per unit
	Firmware revision	01A07h	1	per unit
Die Record	Die Record Tag	01A08h	1	08h
	Die Record length	01A09h	1	0Ah
	Lot/Wafer ID	01A0Ah	4	per unit
	Die X position	01A0Eh	2	per unit
	Die Y position	01A10h	2	per unit
	Test results	01A12h	2	per unit
ADC12 Calibration	ADC12 Calibration Tag	01A14h	1	11h
	ADC12 Calibration length	01A15h	1	10h
	ADC Gain Factor	01A16h	2	per unit
	ADC Offset	01A18h	2	per unit
	ADC 1.5V Reference Temperature Sensor 30°C	01A1Ah	2	per unit
	ADC 1.5V Reference Temperature Sensor 85°C	01A1Ch	2	per unit
	ADC 2.0V Reference Temperature Sensor 30°C	01A1Eh	2	per unit
	ADC 2.0V Reference Temperature Sensor 85°C	01A20h	2	per unit
	ADC 2.5V Reference Temperature Sensor 30°C	01A22h	2	per unit
	ADC 2.5V Reference Temperature Sensor 85°C	01A24h	2	per unit
REF Calibration	REF Calibration Tag	01A26h	1	12h
	REF Calibration length	01A27h	1	06h
	1.5V Reference Factor	01A28h	2	per unit
	2.0V Reference Factor	01A2Ah	2	per unit
	2.5V Reference Factor	01A2Ch	2	per unit
Peripheral Descriptor (PD)	Peripheral Descriptor Tag	01A2Eh	1	02h
	Peripheral Descriptor Length	01A2Fh	1	57h
	Peripheral Descriptors	01A30h	PD Length	...

REVISION HISTORY

REVISION	DESCRIPTION
SLAS740	Production Data release

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
RF430F5978IRGCR	Active	Production	VQFN (RGC) 64	2000 LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 85	RF430F5978
RF430F5978IRGCR.B	Active	Production	VQFN (RGC) 64	2000 LARGE T&R	-	Call TI	Call TI	-40 to 85	

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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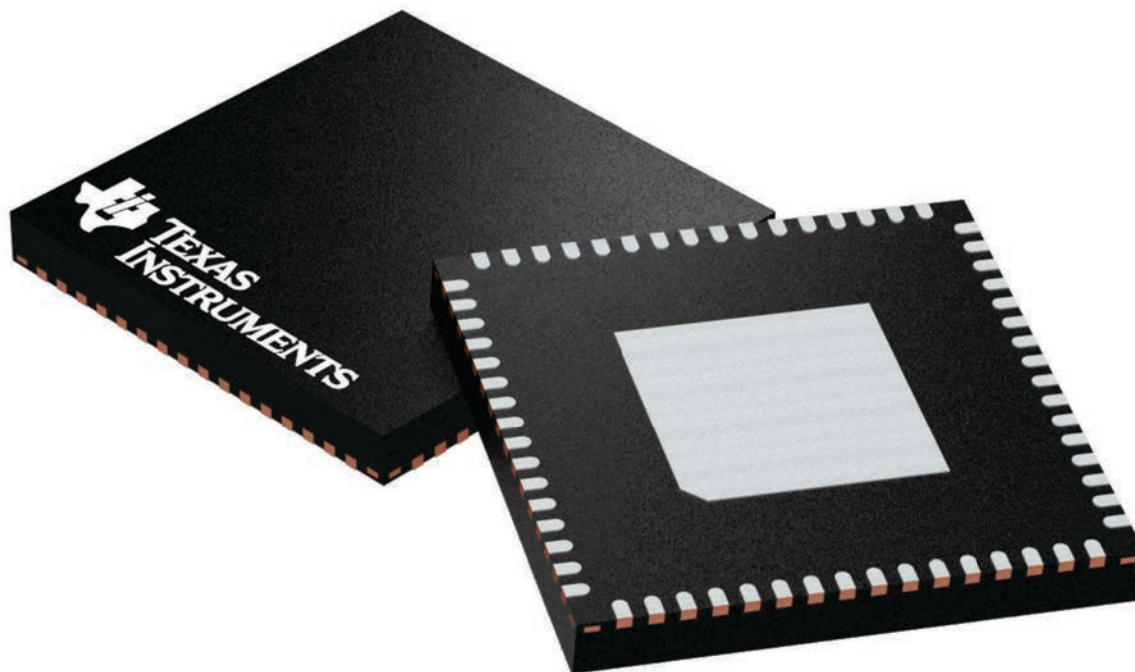
GENERIC PACKAGE VIEW

RGC 64

VQFN - 1 mm max height

9 x 9, 0.5 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.
Refer to the product data sheet for package details.

4224597/A

VQFN - 1 mm max height

9.15
8.85

B A

9.15
8.85

PIN 1 INDEX AREA

(0.1)TYP (0.2)TYP

DETAIL 'A' OPTION1

DETAIL 'A' OPTION2

1 MAX

0.05
0.00

2X
7.5

□ 7.25±0.1

EXPOSED THERMAL PAD

17 32

16 33

60X
0.5

2X
7.5

PIN1 ID (OPTIONAL)

64 65

SYMM

64X^{0.3}_{0.18}

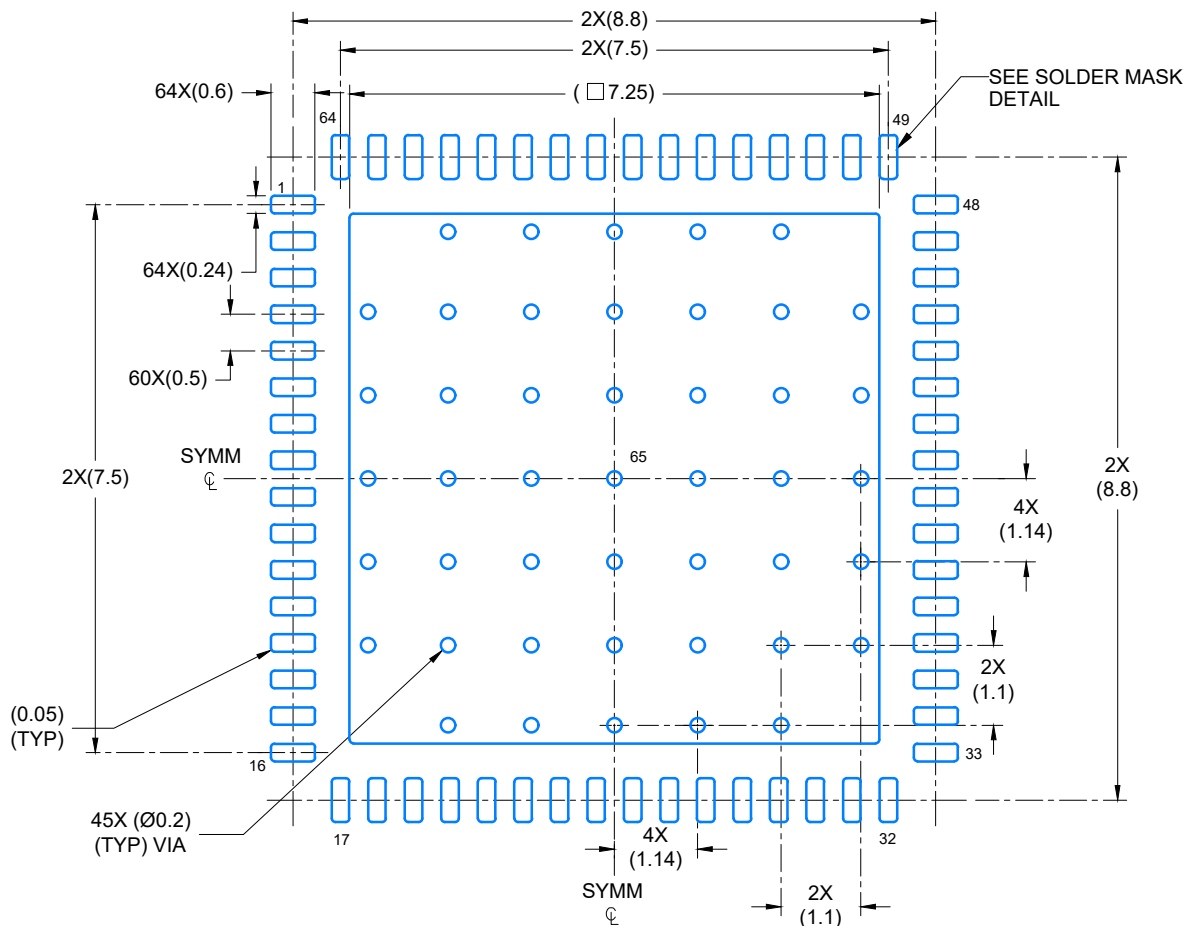
48 49

64X^{0.5}_{0.3}

SEE DETAIL 'A'

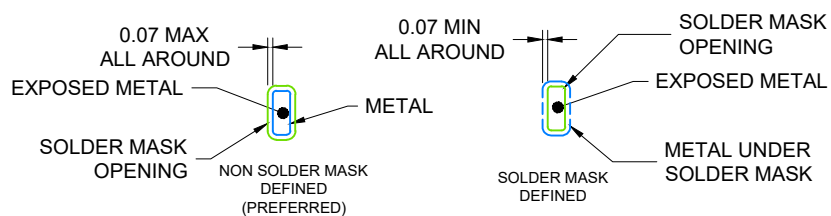
0.1(M)	C	A	B
0.05(M)	C		

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.



LAND PATTERN EXAMPLE

SCALE: 10X

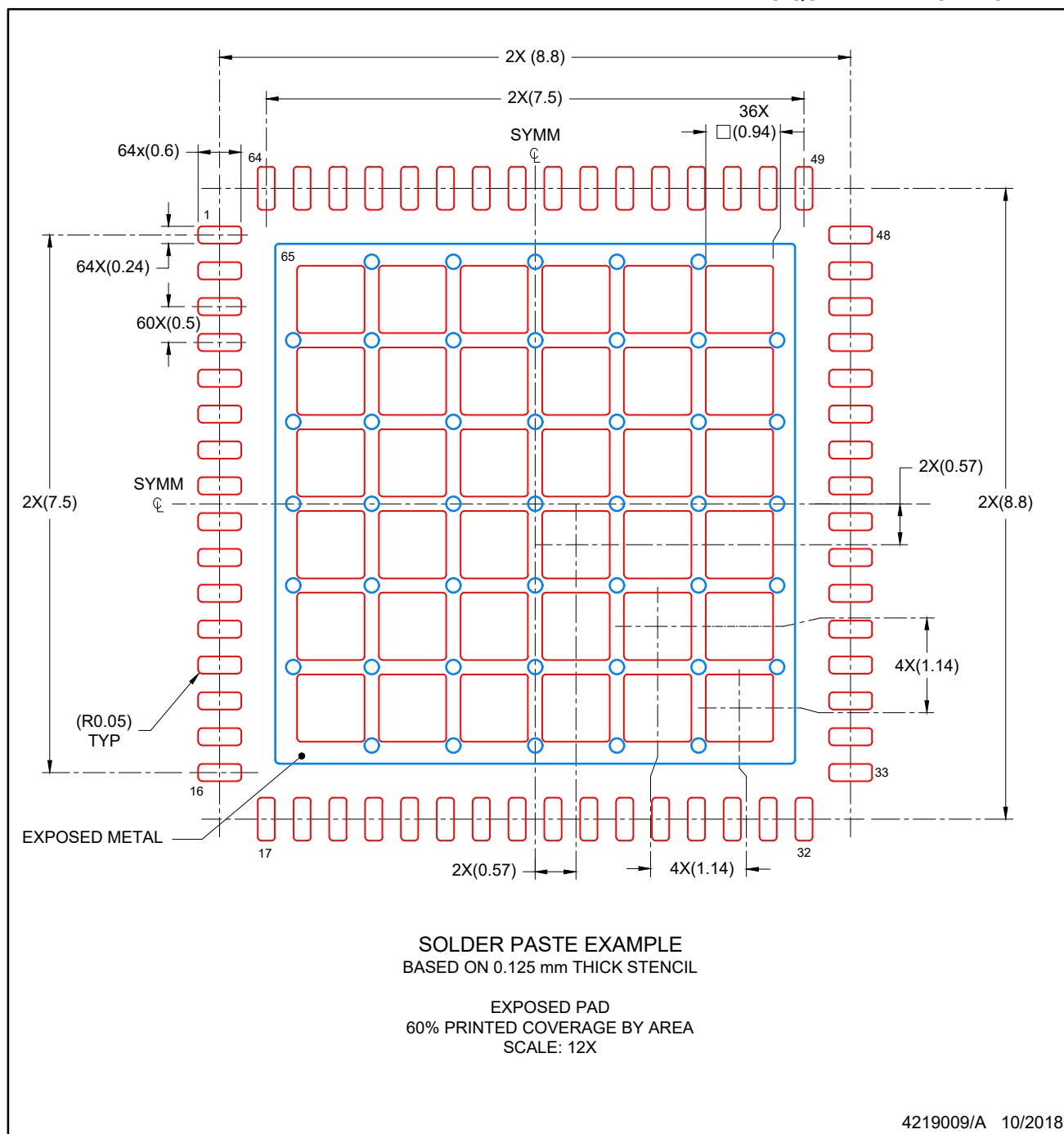


SOLDER MASK DETAILS

4219009/A 10/2018

NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/sluea271).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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