





**OPA836, OPA2836** 

ZHCS019J - JANUARY 2011 - REVISED MARCH 2021

OPAv836 极任功耗	劫到劫给山	<b>缶劫</b> 输λ	电压反馈运算放大器
UFAX0JU IXI IKI 切化、	北判北間山、	贝扎肋八、	电压区坝运异拟八硷

# 1 特性

• 低功耗:

Texas

INSTRUMENTS

- 电源电压: 2.5V 至 5.5V
- 静态电流:1mA(典型值)
- 断电模式: 0.5µA ( 典型值 )
- 带宽:205MHz
- 压摆率:560V/us
- 上升时间: 3ns (2VSTEP) ٠
- 稳定时间 (0.1%): 22ns (2VSTEP)
- 过驱恢复时间:60ns
- SNR:在1kHz (1VRMS)时为0.00013% (-117.6dBc)
- THD:在1kHz (1VRMS)时为0.00003% (-130dBc)
- HD2/HD3:在1MHz (2VPP)时为-85dBc/-105dBc
- 输入电压噪声: 4.6nV/ √ Hz (f = 100kHz)
- 输入失调电压:65µV(最大 ±400µV)
- CMRR : 116dB
- 输出电流驱动:50mA
- **RRO**: 轨到轨输出
- 输入电压范围: - 0.2V 到 +3.9V (5V 电源)
- 工作温度范围: - 40°C 至 +125°C

# 2 应用

- 低功耗信号调节
- 音频模数转换器 (ADC) 输入缓冲器
- 低功耗逐次逼近寄存器 (SAR) 和三角积分 (ΔΣ) ADC 驱动器
- • 便携式系统
- 低功耗系统
- 高密度系统

# 3 说明

OPA836 和 OPA2836 器件 (OPAx836) 为单通道和双 通道超低功耗、轨至轨输出、负电源轨输入、电压反馈 (VFB)运算放大器,依设计可由 2.5V 至 5.5V 范围内 的单电源或者 ±1.25V 至 ±2.75V 范围内的双电源供电 运行。这些轨至轨放大器每通道仅消耗 1mA 的电流, 单位增益带宽为 205MHz, 功耗/性能比处于先进水 平。

OPA836 和 OPA2836 器件同时拥有低功耗特性和出色 的高频性能,并且可提供其他同类器件所无法达到的性 能/功耗比,因此非常适合注重功耗的电池供电类便携 式应用。这些器件还具有节能模式,可将电流降至 1.5 µA以下,这对于电池供电类应用中的高频放大器 而言是极具吸引力的解决方案。

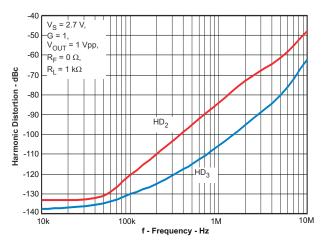
OPA836 RUN 封装选件包含集成的增益设置电阻器, 因此可在印刷电路板上实现超小的尺寸 (约 2.00mm × 2.00mm)。通过在 PCB 上添加电路迹线,可实现 +1, -1, -1.33, +2, +2.33, -3, +4, -4, +5、-5.33、+6.33、-7、+8的增益和-0.1429、-0.1875、-0.25、-0.33、-0.75的反相衰减。有关 详细信息,请参见表 9-1 和表 9-2。

OPA836 和 OPA2836 器件在 - 40°C 至 +125°C 的扩 展工业温度范围内运行。

**竖**件信息(1)

器件型号	封装	封装尺寸(标称值)
OPA836	SOT-23 (6)	2.90mm × 1.60mm
UFA030	WQFN (10)	2.00mm x 2.00mm
	SOIC (8)	4.90mm × 3.91mm
OPA2836	VSSOP (10)	3.00mm × 3.00mm
0FA2030	UQFN (10)	2.00mm x 2.00mm
	WQFN (10)	2.00mm x 2.00mm

(1) 如需了解所有可用封装,请参阅数据表末尾的封装选项附录。



谐波失真与频率间的关系



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**4 Revision History** 注:以前版本的页码可能与当前版本的页码不同

C	hanges from Revision I (October 2016) to Revision J (March 2021)	Page
•	更新了整个文档的表、图和交叉参考的编号格式	1
•	Changed the input impedance common mode conditions From: = 200    1.2 k Ω    pF (Typical) To	): 100    1.2
	M Ω    pF (Typical)	9
•	Changed the input impedance differential mode conditions From: = 200    1 k Ω    pF (Typical) To    pF (Typical)	
•	Changed the input impedance common mode conditions From: = 200    1.2 k Q    pF (Typical) To	
	M Ω    pF (Typical)	12
•	Changed the input impedance differential mode conditions From: = 200    1 k $\Omega$    pF (Typical) To	: 100    1 k Ω
	pF (Typical)	12
C	hanges from Revision H (September 2016) to Revision I (October 2016)	Page
	hanges from Revision H (September 2016) to Revision I (October 2016) 更改了整个数据表中各节的文本,使之更加清晰准确	
•	- · · · · ·	1
•	更改了整个数据表中各节的文本,使之更加清晰准确	
•	更改了整个数据表中各节的文本,使之更加清晰准确 Changed "R <sub>G</sub> = ∞ Ω (open)" to "R <sub>G</sub> = open"	
•	更改了整个数据表中各节的文本,使之更加清晰准确 Changed "R <sub>G</sub> = ∞ Ω (open)" to "R <sub>G</sub> = open" Changed "gain tracking is superior to using" to "gain drift is superior to the drift with"	
• • •	更改了整个数据表中各节的文本,使之更加清晰准确 Changed "R <sub>G</sub> = ∞ Ω (open)" to "R <sub>G</sub> = open" Changed "gain tracking is superior to using" to "gain drift is superior to the drift with" Changed "results in degraded harmonic distortion" to "increases the harmonic distortion"	
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•	Changed "Type" column header to "I/O" on <i>Pin Functions</i> table	. 6
•	Reformatted header rows in Thermal Information: OPA836 and Thermal Information: OPA2836 tables	<mark>8</mark>
•	Reformatted Thermal Information table note	8
•	Reformatted Thermal Information table note	9
•	Deleted the word "linear" from Output section parameters in <i>Electrical Characteristics</i> V <sub>S</sub> = 2.7 V table	9
•	Deleted the word "linear" from Output section parameters in <i>Electrical Characteristics</i> V <sub>S</sub> = 5 V table	.12
•	Reformatted Development Support subsection	44



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## Changes from Revision E (September 2013) to Revision F (June 2015)

C	hanges from Revision D (October 2011) to Revision E (September 2013)	Page
•	在文档中增加了 OPA2836 RMC 封装	1
	Added RMC pin definitions to Pin Functions table	
•	Deleted Packaging/Ordering Information table, leaving only note to POA	8
•	Added OPA2836 RMC package to Thermal Information table	9

С	hanges from Revision C (September 2011) to Revision D (September 2011)	Page
•	Removed Product Preview from OPA835IRUNT and OPA835IRUNR	5
•	Removed Product Preview from OPA836IRUNT and OPA836IRUNR	<mark>8</mark>
•	Changed typical value for resistor temperature coefficien parameter from TBD to < 10	9
•	Changed "quiescent operating current" parameter to "quiescent operating current per amplifier"	9
•	Changed resistor temperature coefficient typical value from TBD to < 10	12
•	Changed "quiescent operating current" to "quiescent operating current per amplifier"	12

## Changes from Revision B (May 2011) to Revision C (August 2011)

在"说明"中添加了"OPA836 RUN 封装..."文本.....1 • Changed typical value for channel to channel crosstalk (OPA2836) parameter from TBD to - 120 dB............9 Changed the quiescent operating current ( $T_A = 25^{\circ}C$ ) minimum value from 0.8 mA to 0.7 mA......9 • Changed the minimum value for power supply rejection (±PSRR) parameter from 95 dB to 91 dB......9 Changed the power-down quiescent current test condition from  $\overline{PD} = 0.7$  V to  $\overline{PD} = 0.5$  V......9 Changed typical value for channel to channel crosstalk (OPA2836) parameter from TBD to - 120 dB...... 12 ٠ Changed the Common-mode rejection ratio Min value From: 97 dB To: 94 dB..... 12 • Added GAIN SETTING RESISTORS (OPA836I RUN ONLY) parameter to *Electrical Characteristics* table....12 ٠ Changed the power supply rejection (±PSRR) minimum value from: 97 dB to 94 dB.....12 Changed the Power-down quiescent current CONDITIONS From: PD = 0.7 V To: PD = 0.5 V......12 ٠ Changed the Power-down quiescent current Conditions From: PD = 0.7 V To: PD = 0.5 V...... 12 Added Figure Crosstalk vs Frequency......15 



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# Changes from Revision A (March 2011) to Revision B (May 2011)

• 已将 OPA836 从"产品预发布"更改为"量产数据".....1



# **5** Device Comparison Table

DEVICE	BW (A <sub>V</sub> = 1) (MHz)	SLEW RATE (V/µs)	lq (+5 V) (mA)	INPUT NOISE (nV/ √ Hz)	RAIL-TO-RAIL IN/OUT	DUALS
OPA836	205	560	1	4.6	- VS/Out	OPA2836
OPA835	30	110	0.25	9.3	- VS/Out	OPA2835
OPA365	50	25	5	4.5	In/Out	OPA2365
THS4281	95	35	0.75	12.5	In/Out	
LMH6618	140	45	1.25	10	In/Out	LMH6619
OPA830	310	600	3.9	9.5	- VS/Out	OPA2830

# **6** Pin Configuration and Functions

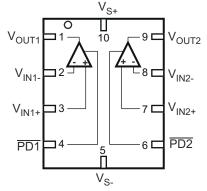


图 6-1. OPA2836 RUN, RMC Packages 10-Pin WQFN, UQFN Top View

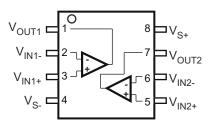


图 6-3. OPA2836 D Package 8-Pin SOIC Top View

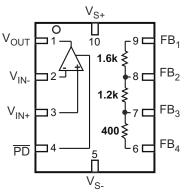


图 6-2. OPA836 RUN Package 10-Pin WQFN Top View

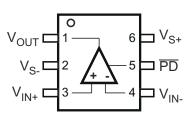


图 6-4. OPA836 DBV Package 6-Pin SOT-23 Top View

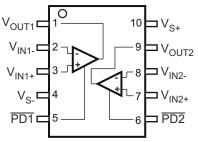


图 6-5. OPA2836 DGS Package 10-Pin VSSOP Top View



## 表 6-1. Pin Functions

PIN								
	OPA836		OPA2836		I/O	DESCRIPTION		
NAME	SOT-23	WQFN	SOIC	VSSOP	WQFN, UQFN			
FB <sub>1</sub>		9				I/O	Connection to top of 2.4-k $\Omega$ internal gain setting resistors	
FB <sub>2</sub>		8				I/O	Connection to junction of 1.8-k $\Omega$ and 2.4-k $\Omega$ internal gain setting resistors	
FB <sub>3</sub>		7		_	_	I/O	Connection to junction of 600- $\Omega$ and 1.8-k $\Omega$ internal gain setting resistors	
FB <sub>4</sub>		6				I/O	Connection to bottom of 600- $\Omega$ internal gain setting resistors	
PD	5	4			I	Amplifier Power Down, low = low-power mode, high = normal operation ( <b>PIN MUST BE DRIVEN</b> )		
PD1			5 4 I Amplifier 1 Power Down, low = low-power mode, high = normal operation (PIN MUST BE DRIVEN)					
PD2		_		6 6		I	Amplifier 2 Power Down, low = low-power mode, high = normal operation ( <b>PIN MUST BE DRIVEN</b> )	
V <sub>IN+</sub>	3	3				I	Amplifier noninverting input	
V <sub>IN</sub> –	4	2				I	Amplifier inverting input	
V <sub>IN1+</sub>			3	3	3	I	Amplifier 1 noninverting input	
V <sub>IN1</sub> -			2	2	2	I	Amplifier 1 inverting input	
V <sub>IN2+</sub>			5	7	7	I	Amplifier 2 noninverting input	
V <sub>IN2</sub> –	]		6	8	8	I	Amplifier 2 inverting input	
V <sub>OUT</sub>	1	1	_	—	—	0	Amplifier output	
V <sub>OUT1</sub>			1	1	1	0	Amplifier 1 output	
V <sub>OUT2</sub>	] _		7	9	9	0	Amplifier 2 output	
V <sub>S+</sub>	6	10	8	10	10	POW	Positive power supply input	
V <sub>S -</sub>	2	5	4	4	5	POW	Negative power supply input	



# 7 Specifications

# 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
$V_{S-}$ to $V_{S+}$	Supply voltage		5.5	V
VI	Input voltage	V <sub>S -</sub> - 0.7	V <sub>S+</sub> + 0.7	V
V <sub>ID</sub>	Differential input voltage		1	V
l <sub>l</sub>	Continuous input current		0.85	mA
lo	Continuous output current		60	mA
	Continuous power dissipation	See ∄ an #77	d	
TJ	Maximum junction temperature		150	°C
T <sub>A</sub>	Operating free-air temperature	- 40	125	°C
T <sub>stg</sub>	Storage temperature	- 65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

# 7.2 ESD Ratings

			VALUE	UNIT
		Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±6000	
V <sub>(ESD)</sub>	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±1000	V
		Machine model	±200	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

# 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V <sub>S+</sub>	Single supply voltage	2.5	5	5.5	V
T <sub>A</sub>	Ambient temperature	- 40	25	125	°C

# 7.4 Thermal Information: OPA836

		OP		
THERMAL METRIC <sup>(1)</sup>		DBV (SOT23-6)	RUN (WQFN-10)	UNIT
		6 PINS	10 PINS	
R <sub>θ JA</sub>	Junction-to-ambient thermal resistance	194	145.8	°C/W
R <sub>θ JC(top)</sub>	Junction-to-case (top) thermal resistance	129.2	75.1	°C/W
R <sub>0 JB</sub>	Junction-to-board thermal resistance	39.4	38.9	°C/W
ΨJT	Junction-to-top characterization parameter	25.6	13.5	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	38.9	104.5	°C/W

(1) For more information about traditional and new thermal metrics, see Semiconductor and IC Package Thermal Metrics (SPRA953).



# 7.5 Thermal Information: OPA2836

THERMAL METRIC <sup>(1)</sup>		D (SOIC-8)	(DGS) VSSOP, MSOP-10	(RUN) WQFN-10	RMC (UQFN-10)	UNIT
		8 PINS	10 PINS	10 PINS	10 PINS	
R <sub>0 JA</sub>	Junction-to-ambient thermal resistance	150.1	206	145.8	143.2	°C/W
R <sub>0</sub> JCtop	Junction-to-case (top) thermal resistance	83.8	75.3	75.1	49.0	°C/W
R <sub>0 JB</sub>	Junction-to-board thermal resistance	68.4	96.2	38.9	61.9	°C/W
ΨJT	Junction-to-top characterization parameter	33.0	12.9	13.5	3.3	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	67.9	94.6	104.5	61.9	°C/W

(1) For more information about traditional and new thermal metrics, see Semiconductor and IC Package Thermal Metrics (SPRA953).

# 7.6 Electrical Characteristics: V<sub>S</sub> = 2.7 V

at  $V_{S+}$  = +2.7 V,  $V_{S-}$  = 0 V,  $V_{OUT}$  = 1  $V_{PP}$ ,  $R_F$  = 0  $\Omega$ ,  $R_L$  = 2 k  $\Omega$ , G = 1 V/V, input and output referenced to mid-supply,  $V_{IN\_CM}$  = mid-supply - 0.5 V.  $T_A$  = 25°C, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN TYP M		TEST LEVEL <sup>(1)</sup>
AC PERFORMANCE		I		
	V <sub>OUT</sub> = 100 mV <sub>PP</sub> , G = 1	200		0
Small signal handwidth	V <sub>OUT</sub> = 100 mV <sub>PP</sub> , G = 2	100	MHz	
Small-signal bandwidth	V <sub>OUT</sub> = 100 mV <sub>PP</sub> , G = 5	26	MHZ	С
	V <sub>OUT</sub> = 100 mV <sub>PP</sub> , G = 10	11		
Gain-bandwidth product	V <sub>OUT</sub> = 100 mV <sub>PP</sub> , G = 10	110	MHz	С
Large-signal bandwidth	V <sub>OUT</sub> = 1 V <sub>PP</sub> , G = 2	60	MHz	С
Bandwidth for 0.1-dB flatness	V <sub>OUT</sub> = 1 V <sub>PP</sub> , G = 2	25	MHz	С
Slew rate, rise	V <sub>OUT</sub> = 1 V <sub>STEP</sub> , G = 2	260	V/µs	С
Slew rate, fall	$V_{OUT}$ = 1 $V_{STEP}$ , G = 2	240	V/µs	С
Rise time	V <sub>OUT</sub> = 1 V <sub>STEP</sub> , G = 2	4	ns	С
Fall time	V <sub>OUT</sub> = 1 V <sub>STEP</sub> , G = 2	4.5	ns	С
Settling time to 1%, rise	V <sub>OUT</sub> = 1 V <sub>STEP</sub> , G = 2	15	ns	С
Settling time to 1%, fall	V <sub>OUT</sub> = 1 V <sub>STEP</sub> , G = 2	15	ns	С
Settling time to 0.1%, rise	V <sub>OUT</sub> = 1 V <sub>STEP</sub> , G = 2	30	ns	С
Settling time to 0.1%, fall	V <sub>OUT</sub> = 1 V <sub>STEP</sub> , G = 2	25	ns	С
Settling time to 0.01%, rise	V <sub>OUT</sub> = 1 V <sub>STEP</sub> , G = 2	50	ns	С
Settling time to 0.01%, fall	V <sub>OUT</sub> = 1 V <sub>STEP</sub> , G = 2	45	ns	С
Overshoot/Undershoot	V <sub>OUT</sub> = 1 V <sub>STEP</sub> , G = 2	5%/3%		С
	f = 10 kHz, $V_{IN_{CM}}$ = mid-supply - 0.5 V	- 133		С
Second-order harmonic distortion	f = 100 kHz, $V_{IN\_CM}$ = mid-supply - 0.5 V	- 120	dBc	С
	$f = 1 \text{ MHz}, V_{IN\_CM} = \text{mid-supply} - 0.5 \text{ V}$	- 84		С
	f = 10 kHz, $V_{IN CM}$ = mid-supply - 0.5 V	- 137		С
Third-order harmonic distortion	f = 100 kHz, $V_{IN CM}$ = mid-supply - 0.5 V	- 130	dBc	С
	f = 1 MHz, V <sub>IN CM</sub> = mid-supply - 0.5 V	- 105		С
Second-order intermodulation distortion	f = 1 MHz, 200-kHz Tone Spacing, V <sub>OUT</sub> Envelope = 1 V <sub>PP</sub> V <sub>IN_CM</sub> = mid-supply - 0.5 V	- 90	dBc	С
Third-order intermodulation distortion	on distortion		dBc	С
Input voltage noise	f = 100 KHz	4.6	nV/√ Hz	С
Voltage noise 1/f corner frequency		215	Hz	С
Input current noise	f = 1 MHz	0.75	pA/ √ Hz	С

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# 7.6 Electrical Characteristics: V<sub>S</sub> = 2.7 V (continued)

PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT	TEST LEVEL <sup>(1</sup>
AC PERFORMANCE (continued)						
Current noise 1/f corner frequency			31.7		kHz	С
Overdrive recovery time, over/under	Overdrive = 0.5 V		55/60		ns	С
Closed-loop output impedance	f = 100 kHz		0.02		Ω	С
Channel-to-channel crosstalk (OPA2836)	f = 10 kHz		- 120		dB	С
DC PERFORMANCE						
Open-loop voltage gain (A <sub>OL</sub> )		100	125		dB	А
	T <sub>A</sub> = 25°C	- 400	±65	400		А
	$T_A = 0^{\circ}C$ to $70^{\circ}C$	- 680		680		
Input referred offset voltage	$T_A = -40^{\circ}C \text{ to } 85^{\circ}C$	- 760		760	μV	в
	$T_A = -40^{\circ}C$ to $125^{\circ}C$	- 1060		1060		
	$T_A = 0^{\circ}C$ to $70^{\circ}C$	- 6.2	±1	6.2		
Input offset voltage drift <sup>(2)</sup>	$T_A = -40^{\circ}C$ to $85^{\circ}C$	- 6	±1	6	µV/°C	В
	$T_{A} = -40^{\circ}$ C to 125°C	- 6.6	±1.1	6.6		
	$T_A = 25^{\circ}C$	300	650	1000		A
	$T_A = 0^{\circ}C$ to $70^{\circ}C$	190		1400		
Input bias current <sup>(3)</sup>	$T_A = -40^{\circ}C$ to $85^{\circ}C$	120		1500	nA	в
	T <sub>A</sub> = -40°C to 125°C	120		1800		
	T <sub>A</sub> = 0°C to 70°C	- 2	±0.33	2	- 1	
Input bias current drift <sup>(2)</sup>	$T_A = -40^{\circ}C$ to $85^{\circ}C$	- 1.9	±0.32	1.9		в
	$T_{A} = -40^{\circ}C \text{ to } 125^{\circ}C$	- 2.1	±0.37	2.1		
	T <sub>A</sub> = 25°C	- 180	±30	180		А
	T <sub>A</sub> = 0°C to 70°C	- 200	±30	200		
Input offset current	$T_A = -40^{\circ}C \text{ to } 85^{\circ}C$	- 215	±30	215	nA	в
	$T_{A} = -40^{\circ}C \text{ to } 125^{\circ}C$	- 240	±30	240		
	$T_A = 0^{\circ}C \text{ to } 70^{\circ}C$	- 460	±77	460		
Input offset current drift <sup>(2)</sup>	$T_{A} = -40^{\circ}C \text{ to } 85^{\circ}C$	- 575	±95	575	pA/°C	в
	$T_{A} = -40^{\circ}C \text{ to } 125^{\circ}C$	- 600	±100	600		
INPUT						
	T <sub>A</sub> = 25°C, < 3-dB degradation in CMRR limit		- 0.2	0	V	А
Common-mode input range low	$T_A = -40^{\circ}C$ to 125°C, < 3-dB degradation in CMRR limit		- 0.2	0	V	В
Common mode input renze hist	T <sub>A</sub> = 25°C, < 3-dB degradation in CMRR limit	1.5	1.6		V	A
Common-mode input range high	$T_A = -40^{\circ}$ C to 125°C, < 3-dB degradation in CMRR limit	1.5	1.6		V	В
nput operating voltage range	T <sub>A</sub> = 25°C, < 6-dB degradation in THD		- 0.3 to 1.75		V	С
Common-mode rejection ratio		91	114		dB	А
Input impedance common-mode			100    1.2		M Ω    pF	С
Input impedance differential mode			100    1		k Ω ∥ pF	С



# 7.6 Electrical Characteristics: V<sub>S</sub> = 2.7 V (continued)

at  $V_{S+}$  = +2.7 V,  $V_{S-}$  = 0 V,  $V_{OUT}$  = 1  $V_{PP}$ ,  $R_F$  = 0  $\Omega$ ,  $R_L$  = 2 k  $\Omega$ , G = 1 V/V, input and output referenced to mid-supply,  $V_{IN\_CM}$  = mid-supply - 0.5 V.  $T_A$  = 25°C, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT	TEST LEVEL <sup>(1)</sup>
ОИТРИТ	·					
Output voltage low	T <sub>A</sub> = 25°C, G = 5		0.15	0.2	V	A
Output voltage low	$T_A = -40^{\circ}C$ to 125°C, G = 5		0.15	0.2	V	В
	T <sub>A</sub> = 25°C, G = 5	2.45	2.5		V	А
Output voltage high	$T_A = -40^{\circ}C$ to 125°C, G = 5	2.45	2.5		V	В
Output saturation voltage, high/low	T <sub>A</sub> = 25°C, G = 5		80/40		mV	С
	T <sub>A</sub> = 25°C	±40	±45		mA	А
Output current drive	$T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	±40	±45		mA	В
GAIN SETTING RESISTORS (OPA836IRUN O	NLY)					
Resistor FB1 to FB2	DC resistance	1584	1600	1616	Ω	А
Resistor FB2 to FB3	DC resistance	1188	1200	1212	Ω	А
Resistor FB3 to FB4	DC resistance	396	400	404	Ω	А
Resistor tolerance	DC resistance	- 1%		1%		А
Resistor temperature coefficient	DC resistance		<10		PPM	С
POWER SUPPLY	· · · ·					
Specified operating voltage		2.5		5.5	V	В
	T <sub>A</sub> = 25°C	0.7	0.95	1.15	mA	А
Quiescent operating current per amplifier	$T_A = -40^{\circ}C$ to 125°C	0.6		1.4	mA	В
Power supply rejection (±PSRR)		91	108		dB	А
POWER DOWN	· · · · ·					
Enable voltage threshold	Specified "on" above V <sub>S -</sub> + 2.1 V			2.1	V	А
Disable voltage threshold	Specified "off" below V <sub>S -</sub> + 0.7 V	0.7			V	А
Power-down pin bias current	PD = 0.5 V		20	500	nA	А
Power-down quiescent current	PD = 0.5 V		0.5	1.5	μA	А
Turnon time delay	Time from PD = high to V <sub>OUT</sub> = 90% of final value		200		ns	С
Turnoff time delay	Time from PD = low to V <sub>OUT</sub> = 10% of original value		25		ns	С

(1) Test levels (all values set by characterization and simulation): (A) 100% tested at 25°C; over temperature limits by characterization and simulation. (B) Not tested in production; limits set by characterization and simulation. (C) Typical value only for information.

(2) Input Offset Voltage Drift, Input Bias Current Drift, and Input Offset Current Drift are average values calculated by taking data at the end points, computing the difference, and dividing by the temperature range.

(3) Current is considered positive out of the pin.



# 7.7 Electrical Characteristics: $V_S = 5 V$

PARAMETER	TEST CONDITIONS	MIN TYP N		TEST LEVEL <sup>(1)</sup>
AC PERFORMANCE				
	V <sub>OUT</sub> = 100 mV <sub>PP</sub> , G = 1	205		
	V <sub>OUT</sub> = 100 mV <sub>PP</sub> , G = 2	100		0
Small-signal bandwidth	V <sub>OUT</sub> = 100 mV <sub>PP</sub> , G = 5	28	MHz	С
	V <sub>OUT</sub> = 100 mV <sub>PP</sub> , G = 10	11.8		
Gain-bandwidth product	V <sub>OUT</sub> = 100 mV <sub>PP</sub> , G = 10	118	MHz	С
Large-signal bandwidth	V <sub>OUT</sub> = 2 V <sub>PP</sub> , G = 2	87	MHz	С
Bandwidth for 0.1-dB flatness	V <sub>OUT</sub> = 2 V <sub>PP</sub> , G = 2	29	MHz	С
Slew rate, rise	V <sub>OUT</sub> = 2-V Step, G = 2	560	V/µs	С
Slew rate, fall	V <sub>OUT</sub> = 2-V Step, G = 2	580	V/µs	С
Rise time	V <sub>OUT</sub> = 2-V Step, G = 2	3	ns	С
Fall time	V <sub>OUT</sub> = 2-V Step, G = 2	3	ns	С
AC PERFORMANCE (continued)				
Settling time to 1%, rise	V <sub>OUT</sub> = 2-V Step, G = 2	22	ns	С
Settling time to 1%, fall	V <sub>OUT</sub> = 2-V Step, G = 2	22	ns	С
Settling time to 0.1%, rise	V <sub>OUT</sub> = 2-V Step, G = 2	30	ns	С
Settling time to 0.1%, fall	V <sub>OUT</sub> = 2-V Step, G = 2	30	ns	С
Settling time to 0.01%, rise	V <sub>OUT</sub> = 2-V Step, G = 2	40	ns	С
Settling time to 0.01%, fall	V <sub>OUT</sub> = 2-V Step, G = 2	45	ns	С
Overshoot/Undershoot	V <sub>OUT</sub> = 2-V Step, G = 2	7.5%/5%		С
	f = 10 kHz	- 133		
Second-order harmonic distortion	f = 100 kHz	- 120	dBc	с
	f = 1 MHz	- 85		
	f = 10 kHz	- 140		
Third-order harmonic distortion	f = 100 kHz	- 130	dBc	с
	f = 1 MHz	- 105		
Second-order intermodulation distortion	f = 1 MHz, 200 kHz Tone Spacing, V <sub>OUT</sub> Envelope = 2 V <sub>PP</sub>	- 79	dBc	с
Third-order intermodulation distortion	f = 1 MHz, 200 kHz Tone Spacing, V <sub>OUT</sub> Envelope = 2 V <sub>PP</sub>	- 91	dBc	С
	f = 1 kHz, V <sub>OUT</sub> = 1 V <sub>RMS</sub> ,	0.00013%		0
Signal-to-noise ratio, SNR	22 kHz bandwidth	- 117.6	dBc	С
		0.00003%		
Total harmonic distortion, THD	$f = 1 \text{ kHz}, V_{OUT} = 1 V_{RMS}$	- 130	dBc	С
Input voltage noise	f = 100 KHz	4.6	nV/ √ Hz	С
Voltage noise 1/f corner frequency		215	Hz	С
Input current noise	f > 1 MHz	0.75	pA/ √ Hz	С
Current noise 1/f corner frequency		31.7	kHz	С
Overdrive recovery time, over/under	Overdrive = 0.5 V	55/60	ns	С
Closed-loop output impedance	f = 100 kHz	0.02	Ω	С
Channel to channel crosstalk (OPA2836)	f = 10 kHz	- 120	dB	С
DC PERFORMANCE	I	-		L
Open-loop voltage gain (A <sub>OL</sub> )		100 122	dB	A



# 7.7 Electrical Characteristics: V<sub>S</sub> = 5 V (continued)

PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT	TEST LEVEL <sup>(1)</sup>
	T <sub>A</sub> = 25°C	- 400	±65	400		A
Input referred offect velters	$T_A = 0^{\circ}C$ to $70^{\circ}C$	- 685		685		
Input referred offset voltage	$T_A = -40^{\circ}C \text{ to } 85^{\circ}C$	- 765		765	μV	В
	$T_A = -40^{\circ}C$ to $125^{\circ}C$	- 1080		1080		
	$T_A = 0^{\circ}C$ to $70^{\circ}C$	- 6.3	±1.05	6.3		
Input offset voltage drift <sup>(2)</sup>	$T_A = -40^{\circ}C \text{ to } 85^{\circ}C$	- 6.1	±1	6.1	µV/°C	В
	$T_A = -40^{\circ}C$ to $125^{\circ}C$	- 6.8	±1.1	6.8		
	T <sub>A</sub> = 25°C	300	650	1000		А
	$T_A = 0^{\circ}C$ to $70^{\circ}C$	190		1400		
Input bias current <sup>(3)</sup>	$T_A = -40^{\circ}C \text{ to } 85^{\circ}C$	120		1550	nA	В
	$T_A = -40^{\circ}C$ to $125^{\circ}C$	120		1850		
	$T_A = 0^{\circ}C$ to $70^{\circ}C$		±0.34	±2		
Input bias current drift <sup>(2)</sup>	$T_A = -40^{\circ}C \text{ to } 85^{\circ}C$		±0.34	±2	nA/°C	В
	$T_A = -40^{\circ}C$ to $125^{\circ}C$		±0.38	±2.3		
DC PERFORMANCE (continued)	I				II	
	T <sub>A</sub> = 25°C		±30	±180		А
Input offect ourrent	$T_A = 0^{\circ}C$ to $70^{\circ}C$		±30	±200	<b>n</b> A	
Input offset current	$T_A = -40^{\circ}C \text{ to } 85^{\circ}C$		±30	±215	nA	В
	$T_A = -40^{\circ}C$ to 125°C		±30	±250		
	$T_A = 0^{\circ}C$ to $70^{\circ}C$		±80	±480		
Input offset current drift <sup>(2)</sup>	$T_A = -40^{\circ}C \text{ to } 85^{\circ}C$		±100	±600	pA/°C	В
	$T_A = -40^{\circ}C$ to $125^{\circ}C$		±110	±660		
INPUT						
<b>6</b>	T <sub>A</sub> = 25°C, < 3-dB degradation in CMRR limit		- 0.2	0	V	А
Common-mode input range low	$T_A = -40^{\circ}$ C to 125°C, < 3-dB degradation in CMRR limit		- 0.2	0	V	В
Common-mode input range high	T <sub>A</sub> = 25°C, < 3-dB degradation in CMRR limit	3.8	3.9		V	А
	$T_A = -40^{\circ}$ C to 125°C, < 3-dB degradation in CMRR limit	3.8	3.9		V	В
Input linear operating voltage range	T <sub>A</sub> = 25°C, < 6-dB degradation in THD		- 0.3 to 4.05		v	С
Common-mode rejection ratio		94	116		dB	Α
Input impedance common mode			100    1.2		M Ω    pF	С
Input impedance differential mode			100    1		k Ω    pF	С
ОИТРИТ						
Output voltage low	T <sub>A</sub> = 25°C, G = 5		0.15	0.2	V	А
	$T_A = -40^{\circ}C$ to 125°C, G = 5		0.15	0.2	V	В
Output voltage high	T <sub>A</sub> = 25°C, G = 5	4.75	4.8		V	А
	$T_A = -40^{\circ}C$ to 125°C, G = 5	4.75	4.8		V	В
Output saturation voltage, high/low	T <sub>A</sub> = 25°C, G = 5		100/50		mV	С
Output current drive	T <sub>A</sub> = 25°C	±40	±50		mA	Α
	$T_A = -40^{\circ}C \text{ to } 125^{\circ}C$	±40	±50		mA	В
GAIN SETTING RESISTORS (OPA836IRUN	ONLY)					
Resistor FB1 to FB2	DC resistance	1584	1600	1616	Ω	А
Resistor FB2 to FB3	DC resistance	1188	1200	1212	Ω	A



# 7.7 Electrical Characteristics: V<sub>S</sub> = 5 V (continued)

at V<sub>S+</sub> = +5 V, V<sub>S-</sub> = 0 V, V<sub>OUT</sub> = 2 V<sub>PP</sub>, R<sub>F</sub> = 0  $\Omega$ , R<sub>L</sub> = 1 k $\Omega$ , G = 1 V/V, input and output referenced to mid-supply. T<sub>A</sub> = 25°C, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	ТҮР	MAX	UNIT	TEST LEVEL <sup>(1)</sup>
Resistor FB3 to FB4	DC resistance	396	400	404	Ω	A
Resistor tolerance	DC resistance	- 1		1%		А
Resistor temperature coefficient	DC resistance		<10		PPM	С
POWER SUPPLY	· · · ·					
Specified operating voltage		2.5		5.5	V	В
	T <sub>A</sub> = 25°C	0.8	1.0	1.2	mA	А
Quiescent operating current per amplifier	$T_{A} = -40^{\circ}C \text{ to } 125^{\circ}C$	0.65		1.5	mA	В
Power supply rejection (±PSRR)		94	108		dB	A
POWER DOWN	I					1
Enable voltage threshold	Specified "on" above V <sub>S -</sub> + 2.1 V			2.1	V	А
Disable voltage threshold	Specified "off" below V <sub>S -</sub> + 0.7 V	0.7			V	А
Power-down pin bias current	PD = 0.5 V		20	500	nA	А
Power-down quiescent current	PD = 0.5 V		0.5	1.5	μA	А
Turnon time delay	Time from $\overline{PD}$ = high to V <sub>OUT</sub> = 90% of final value		170		ns	С
Turnoff time delay	Time from $\overline{PD}$ = low to V <sub>OUT</sub> = 10% of original value		35		ns	С

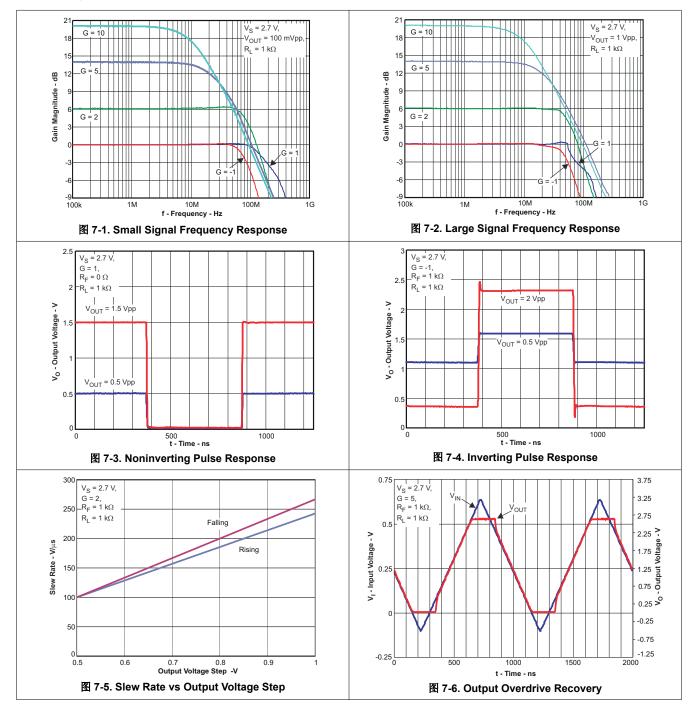
(1) Test levels (all values set by characterization and simulation): (A) 100% tested at 25°C; over temperature limits by characterization and simulation. (B) Not tested in production; limits set by characterization and simulation. (C) Typical value only for information.

(2) Input Offset Voltage Drift, Input Bias Current Drift, and Input Offset Current Drift are average values calculated by taking data at the end points, computing the difference, and dividing by the temperature range.

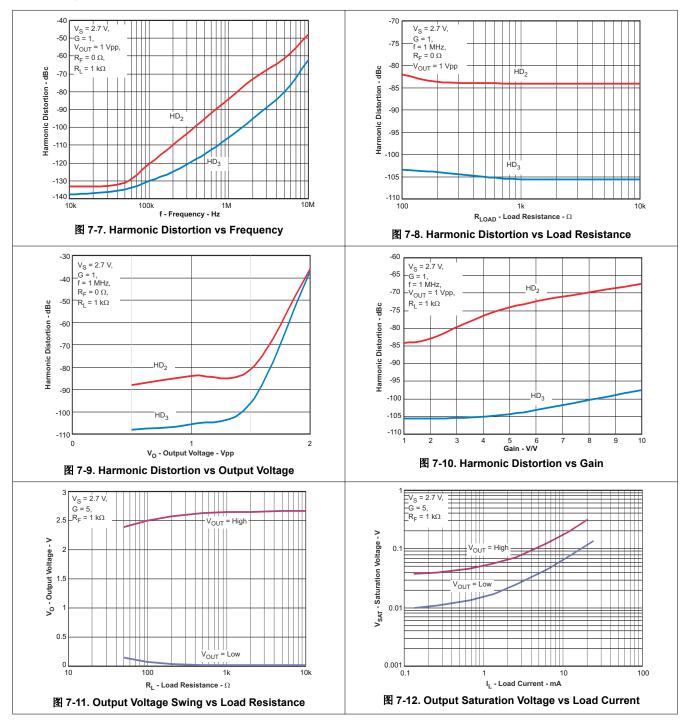
(3) Current is considered positive out of the pin.



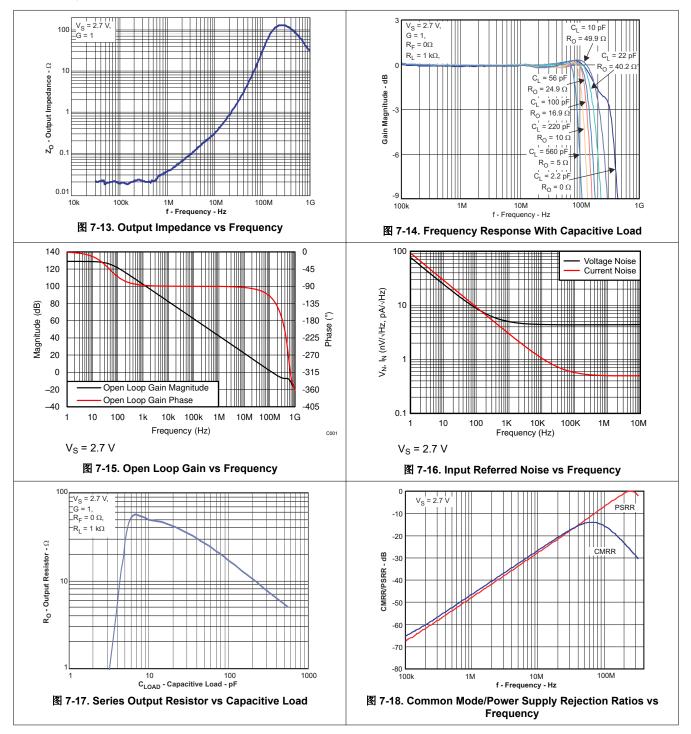




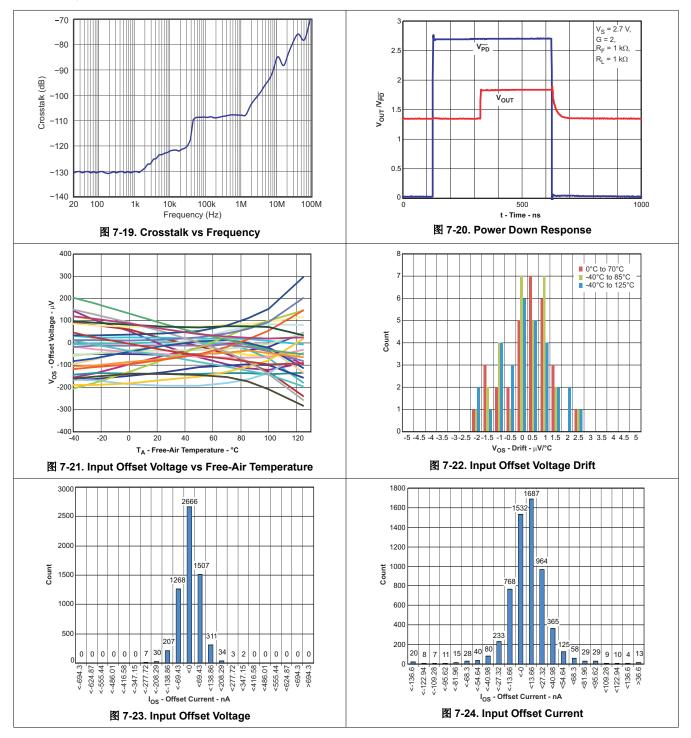






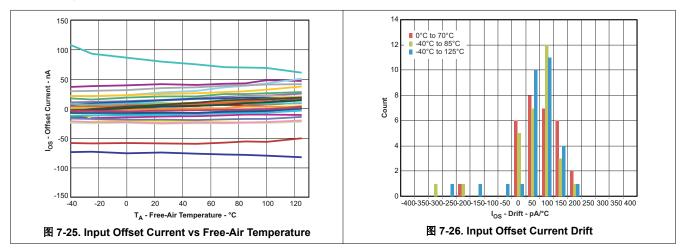






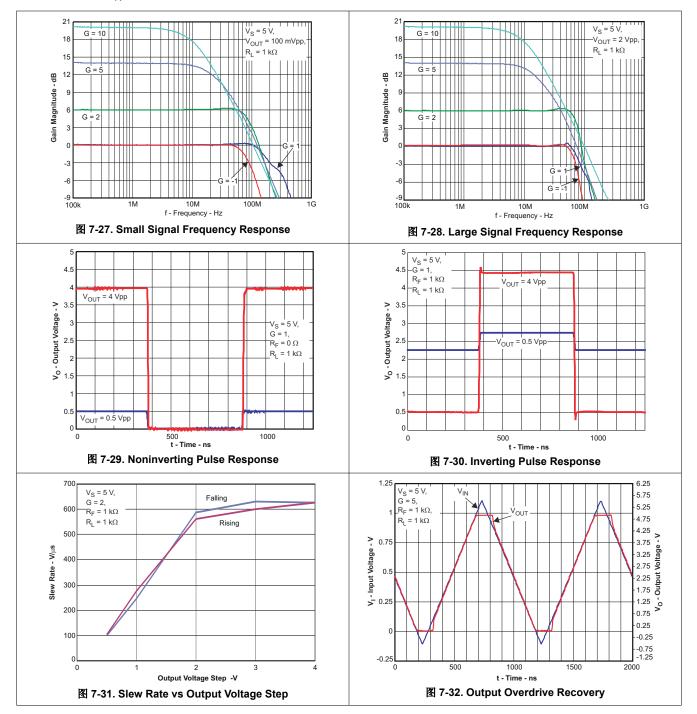


# 7.8 Typical Characteristics: V<sub>S</sub> = 2.7 V (continued)

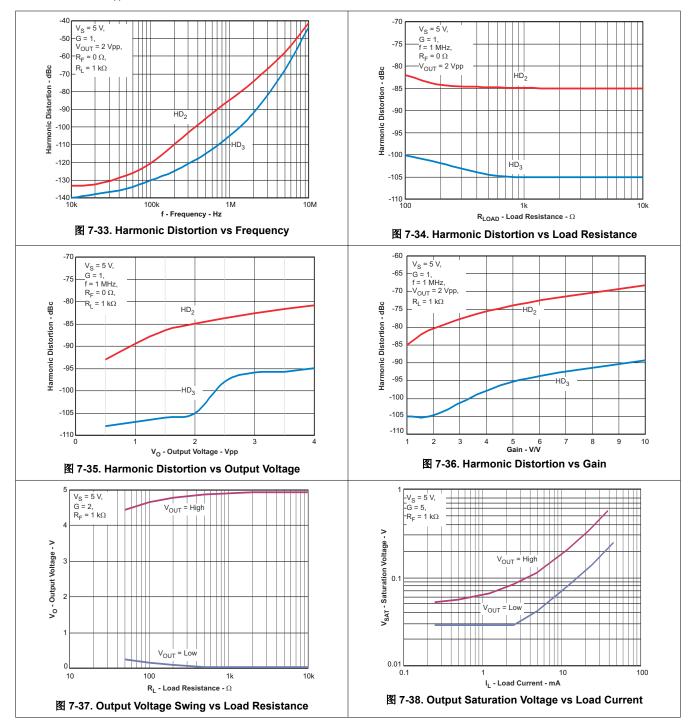




# 7.9 Typical Characteristics: $V_S = 5 V$

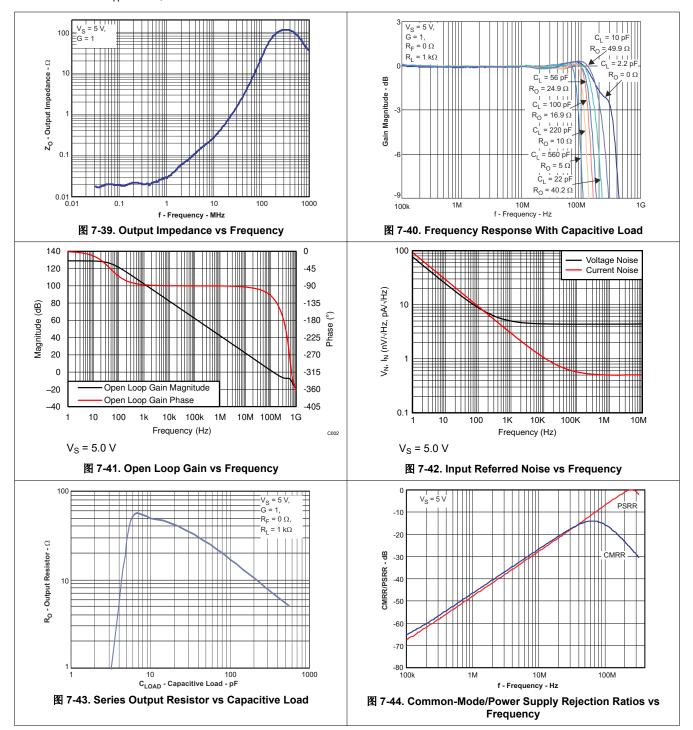




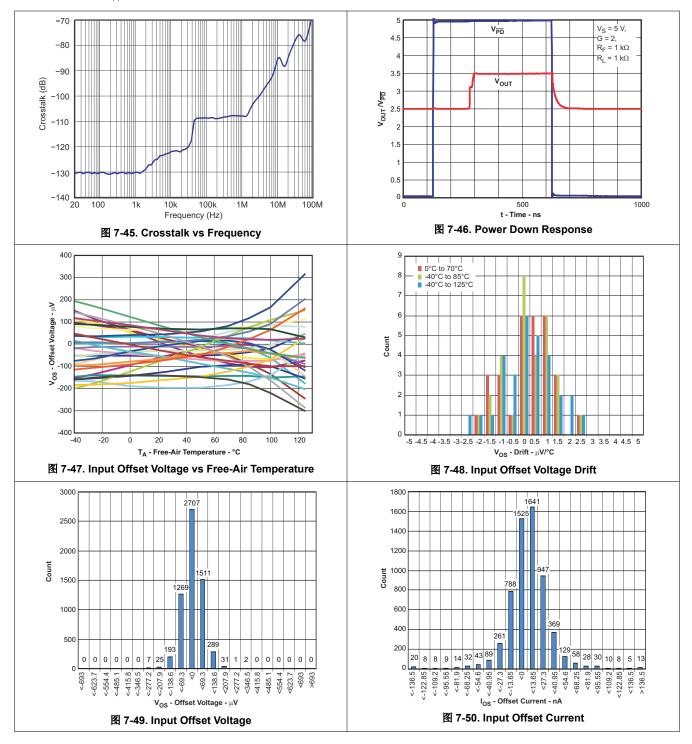




# 7.9 Typical Characteristics: $V_S = 5 V$

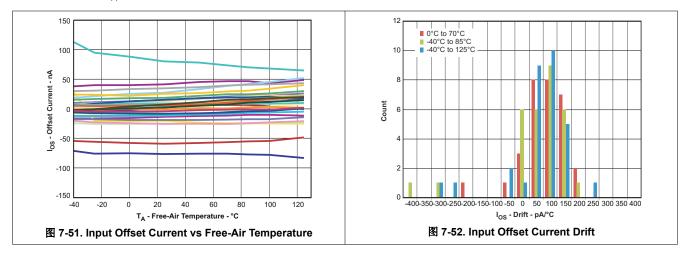








# 7.9 Typical Characteristics: V<sub>S</sub> = 5 V (continued)



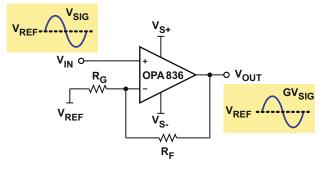


# 8 Detailed Description

## 8.1 Overview

The OPAx836 family of bipolar-input operational amplifiers offers excellent bandwidth of 205 MHz with ultra-low THD of 0.00003% at 1 kHz. The OPAx836 device can swing to within 200 mV of the supply rails while driving a 1-k $\Omega$  load. The input common-mode of the amplifier can swing to 200 mV below the negative supply rail. This level of performance is achieved at 1 mA of quiescent current per amplifier channel.

## 8.2 Functional Block Diagrams





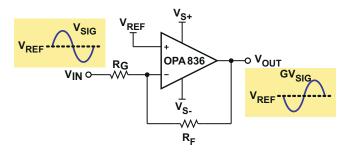


图 8-2. Inverting Amplifier

# 8.3 Feature Description

## 8.3.1 Input Common-Mode Voltage Range

When the primary design goal is a linear amplifier with high CMRR, it is important to not violate the input common-mode voltage range ( $V_{ICR}$ ) of an operational amplifier.

The common-mode input range specifications in the table data use CMRR to set the limit. The limits are selected to ensure CMRR will not degrade more than 3 dB below the CMRR limit if the input voltage is kept within the specified range. The limits cover all process variations and most parts will be better than specified. The typical specifications are from 0.2 V below the negative rail to 1.1 V below the positive rail.

Assuming the operational amplifier is in linear operation, the voltage difference between the input pins is small (ideally 0 V) and input common-mode voltage is analyzed at either input pin with the other input pin assumed to be at the same potential. The voltage at  $V_{IN+}$  is simple to evaluate. In noninverting configuration,  $\boxtimes$  8-1, the input signal,  $V_{IN}$ , must not violate the  $V_{ICR}$ . In inverting configuration,  $\boxtimes$  8-2, the reference voltage,  $V_{REF}$ , must be within the  $V_{ICR}$ .

The input voltage limits have fixed headroom to the power rails and track the power supply voltages. For one 5-V supply, the linear input voltage ranges from -0.2 V to 3.9 V and from -0.2 V to 1.6 V for a 2.7-V supply. The delta headroom from each power supply rail is the same in either case: -0.2 V and 1.1 V.



#### 8.3.2 Output Voltage Range

The OPA836 and OPA2836 devices are rail-to-rail output (RRO) operational amplifiers. Rail-to-rail output typically means the output voltage swings within a couple hundred millivolts of the supply rails. There are different ways to specify this: one is with the output still in linear operation and another is with the output saturated. Saturated output voltages are closer to the power supply rails than linear outputs, but the signal is not a linear representation of the input. Linear output is a better representation of how well a device performs when used as a linear amplifier. Saturation and linear operation limits are affected by the output current, where higher currents lead to more loss in the output transistors.

Output Voltage Swing vs Load Resistance and Output Voltage Swing vs Load Resistance show saturated voltage-swing limits versus output load resistance and Output Saturation Voltage vs Load Current and Output Saturation Voltage vs Load Current and Output Saturation Voltage vs Load Current show the output saturation voltage versus load current. Given a light load, the output voltage limits have nearly constant headroom to the power rails and track the power supply voltages. For example, with a 2-k $\Omega$  load and single 5-V supply, the linear output voltage ranges from 0.15 V to 4.8 V, and ranges from 0.15 V to 2.5 V for a 2.7-V supply. The delta from each power supply rail is the same in either case: 0.15 V and 0.2 V.

With devices like the OPA836 and OPA2836, where the input range is lower than the output range, typically the input will limit the available signal swing only in noninverting gain of 1. Signal swing in noninverting configurations in gains > +1 and inverting configurations in any gain is typically limited by the output voltage limits of the operational amplifier.

#### 8.3.3 Power-Down Operation

The OPA836 and OPA2836 devices include a power-down mode. Under logic control, the amplifiers can switch from normal operation to a standby current of < 1.5  $\mu$ A. When the  $\overline{PD}$  pin is connected high, the amplifier is active. Connecting  $\overline{PD}$  pin low disables the amplifier and places the output in a high-impedance state. When the amplifier is configured as a unity-gain buffer, the output stage is in a high dc-impedance state. To protect the input stage of the amplifier, the devices use internal, back-to-back ESD diodes between the inverting and noninverting input pins. This configuration creates a parallel low-impedance path from the amplifier output to the noninverting pin when the differential voltage between the pins exceeds a diode voltage drop. When the op amp is configured in other gains, the feedback (RF) and gain (RG) resistor network forms a parallel load.

The PD pin must be actively driven high or low and must not be left floating. If the power-down mode is not used, PD must be tied to the positive supply rail.

 $\overline{PD}$  logic states are TTL with reference to the negative supply rail and V<sub>S</sub><sub>-</sub>. When the operational amplifier is powered from single-supply and ground and driven from logic devices with similar V<sub>DD</sub>, voltages to the operational amplifier do not require any special consideration. When the operational amplifier is powered from a split supply, with V<sub>S</sub><sub>-</sub> below ground, an open-collector type of interface with pullup resistor is more appropriate. Pullup resistor values must be lower than 100 k  $\Omega$ . Additionally, the drive logic must be negated due to the inverting action of an open-collector gate.

#### 8.3.4 Low-Power Applications and the Effects of Resistor Values on Bandwidth

The OPA836 and OPA2836 devices are designed for the nominal value of R<sub>F</sub> to be 1 k  $\Omega$  in gains other than +1. This gives excellent distortion performance, maximum bandwidth, best flatness, and best pulse response, but it also loads the amplifier. For example; in gain of 2 with R<sub>F</sub> = R<sub>G</sub> = 1 k  $\Omega$ , R<sub>G</sub> to ground, and V<sub>OUT</sub> = 4 V, 2 mA of current will flow through the feedback path to ground. In gain of +1, R<sub>G</sub> is open and no current will flow to ground. In low-power applications, it is desirable to reduce the current in the feedback by increasing the gain-setting resistors values. Using larger value gain resistors has two primary side effects (other than lower power) due to their interaction with parasitic circuit capacitance:

- Lowers the bandwidth
- Lowers the phase margin
  - This causes peaking in the frequency response
  - This also causes overshoot and ringing in the pulse response



**8-3** shows the small-signal frequency response on OPA836EVM for noninverting gain of 2 with  $R_F$  and  $R_G$  equal to 1 k  $\Omega$ , 10 k  $\Omega$ , and 100 k  $\Omega$ . The test was done with  $R_L = 1 \text{ k} \Omega$ . Due to loading effects of  $R_L$ , lower  $R_L$  values may reduce the peaking, but higher values will not have a significant effect.

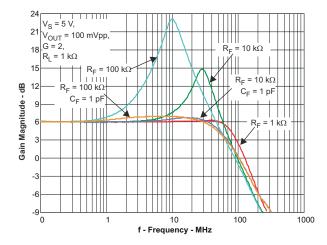


图 8-3. Frequency Response With Various Gain-Setting Resistor Values

As expected, larger value gain resistors cause lower bandwidth and peaking in the response (peaking in the frequency response is synonymous with overshoot and ringing in the pulse response). Adding 1-pF capacitors in parallel with  $R_F$  helps compensate the phase margin and restores flat frequency response.  $\boxtimes$  8-4 shows the test circuit.

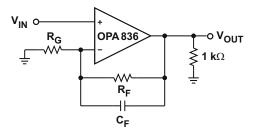


图 8-4. G = 2 Test Circuit for Various Gain-Setting Resistor Values

## 8.3.5 Driving Capacitive Loads

The OPA836 and OPA2836 devices can drive up to a nominal capacitive load of 2.2 pF on the output with no special consideration. When driving capacitive loads greater than 2.2 pF, TI recommends using a small resister ( $R_0$ ) in series with the output as close to the device as possible. Without  $R_0$ , capacitance on the output interacts with the output impedance of the amplifier causing phase shift in the loop gain of the amplifier that will reduce the phase margin. This will cause peaking in the frequency response and overshoot and ringing in the pulse response. Interaction with other parasitic elements may lead to instability or oscillation. Inserting  $R_0$  will isolate the phase shift from the feedback path and restore the phase margin; however,  $R_0$  can limit the bandwidth slightly.

 $\mathbb{R}$  8-5 shows the test circuit and Series Output Resistor vs Capacitive Load shows the recommended values of  $R_0$  versus capacitive loads,  $C_L$ . See Frequency Response With Capacitive Load for the frequency response with various values.



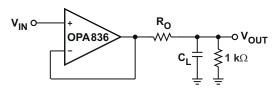


图 8-5. R<sub>O</sub> versus C<sub>L</sub> Test Circuit

## 8.4 Device Functional Modes

#### 8.4.1 Split-Supply Operation (±1.25 V to ±2.75 V)

To facilitate testing with common lab equipment, the OPA836 EVM (see *OPA835DBV, OPA836DBV EVM*, SLOU314) is built to allow for split-supply operation. This configuration eases lab testing because the mid-point between the power rails is ground, and most signal generators, network analyzers, oscilloscopes, spectrum analyzers and other lab equipment have inputs and outputs with a ground reference.

 $\mathbb{X}$  8-6 shows a simple noninverting configuration analogous to  $\mathbb{X}$  8-1 with ±2.5-V supply and V<sub>REF</sub> equal to ground. The input and output will swing symmetrically around ground. For ease of use, split supplies are preferred in systems where signals swing around ground.

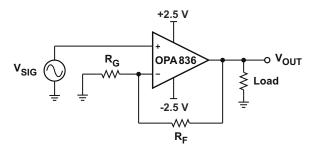


图 8-6. Split-Supply Operation

## 8.4.2 Single-Supply Operation (2.5 V to 5.5 V)

Often, newer systems use a single power supply to improve efficiency and reduce the cost of the power supply. The OPA836 and OPA2836 devices are designed for use with a single supply with no change in performance compared to a split supply, as long as the input and output are biased within the linear operation of the device.

To change the circuit from split supply to single supply, level shift of all voltages by half the difference between the power supply rails. For example, changing from  $\pm 2.5$ -V split supply to 5-V single supply is shown in  $\boxed{8}$  8-7.

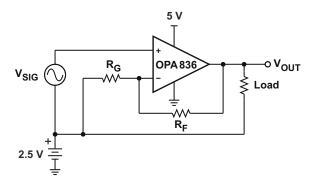


图 8-7. Single-Supply Concept

A practical circuit will have an amplifier or other circuit providing the bias voltage for the input, and the output of this amplifier stage provides the bias for the next stage.

 $\mathbb{R}$  8-8 shows a typical noninverting amplifiercircuit. With 5-V single-supply, a mid-supply reference generator is needed to bias the negative side through  $R_G$ . To cancel the voltage offset that would otherwise be caused by the



input bias currents,  $R_1$  is selected to be equal to  $R_F$  in parallel with  $R_G$ . For example, if gain of 2 is required and  $R_F = 1 \ k\Omega$ , select  $R_G = 1 \ k\Omega$  to set the gain and  $R_1 = 499 \ \Omega$  for bias-current cancellation. The value for C depends on the reference; TI recommends a value of at least 0.1 µF to limit noise.

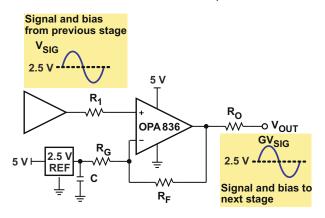


图 8-8. Noninverting Single Supply With Reference

8-9 shows a similar noninverting single-supply scenario with the reference generator replaced by the Thevenin equivalent using resistors and the positive supply.  $R_G'$  and  $R_G''$  form a resistor divider from the 5-V supply and are used to bias the negative side with their parallel sum equal to the equivalent  $R_G$  to set the gain. To cancel the voltage offset that would otherwise be caused by the input bias currents,  $R_1$  is selected to be equal to  $R_F$  in parallel with  $R_G''$  in parallel with  $R_G''' (R_1 = R_F || R_G' || R_G''')$ . For example, if gain of 2 is required and  $R_F = 1 \ k\Omega$ , selecting  $R_G'' = R_G''' = 2 \ k\Omega$  gives equivalent parallel sum of  $1 \ k\Omega$ , sets the gain to 2, and references the input to mid supply (2.5 V).  $R_1$  is then set to 499  $\Omega$  for bias-current cancellation. The resistor divider costs less than the 2.5 V reference in 8 8-8 but may increase the current from the 5-V supply.

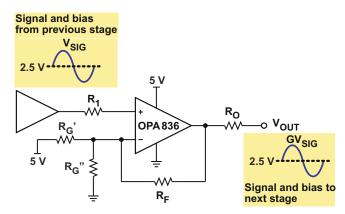
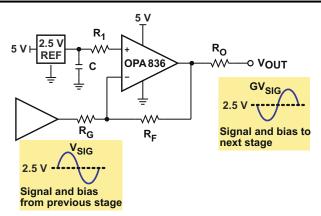
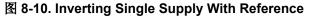


图 8-9. Noninverting Single Supply With Resistors

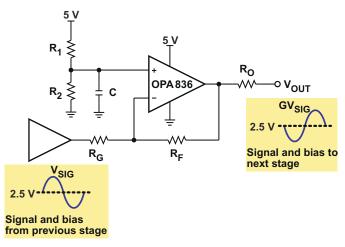
**8**-10 shows a typical inverting amplifier situation. With 5-V single supply, a mid-supply reference generator is needed to bias the positive side through  $R_1$ . To cancel the voltage offset that would otherwise be caused by the input bias currents,  $R_1$  is selected to be equal to  $R_F$  in parallel with  $R_G$ . For example if gain of -2 is required and  $R_F = 1 \ k\Omega$ , select  $R_G = 499 \ \Omega$  to set the gain and  $R_1 = 332 \ \Omega$  for bias-current cancellation. The value for C is dependent on the reference, but TI recommends a value of at least 0.1  $\mu$ F to limit noise into the operational amplifier.







[⊠ 8-11 shows a similar inverting single-supply scenario with the reference generator replaced by the Thevenin equivalent using resistors and the positive supply.  $R_1$  and  $R_2$  form a resistor divider from the 5-V supply and are used to bias the positive side. To cancel the voltage offset that would otherwise be caused by the input bias currents, set the parallel sum of  $R_1$  and  $R_2$  equal to the parallel sum of  $R_F$  and  $R_G$ . C must be added to limit coupling of noise into the positive input. For example if gain of −2 is required and  $R_F = 1 \text{ k} \Omega$ , select  $R_G = 499 \Omega$  to set the gain.  $R_1 = R_2 = 665 \Omega$  for mid-supply voltage bias and for operational amplifier input bias-current cancellation. A good value for C is 0.1 µF. The resistor divider costs less than the 2.5-V reference in [⊠ 8-10 but may increase the current from the 5-V supply.



## 图 8-11. Inverting Single Supply With Resistors



# 9 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

## **9.1 Application Information**

#### 9.1.1 Noninverting Amplifier

The OPA836 and OPA2836 devices can be used as noninverting amplifiers with signal input to the noninverting input,  $V_{IN+}$ . A basic block diagram of the circuit is shown in  $\mathbb{K}$  8-1.

If  $V_{IN} = V_{REF} + V_{SIG}$ , then the output of the amplifier may be calculated according to  $\overline{5}$  Reg 1.

$$V_{OUT} = V_{SIG} \left( 1 + \frac{R_F}{R_G} \right) + V_{REF}$$
(1)

G = 1 +  $\frac{R_F}{R_G}$ , and  $V_{REF}$  provides a reference around which the input and The signal gain of the circuit is set by output signals swing. Output signals are in-phase with the input signals.

The OPA836 and OPA2836 devices are designed for the nominal value of  $R_{\rm F}$  to be 1 k  $\Omega$  in gains other than +1. This gives excellent distortion performance, maximum bandwidth, best flatness, and best pulse response. R<sub>F</sub> = 1 k Ω must be used as a default unless other design goals require changing to other values. All test circuits used to collect data for this data sheet had  $R_F = 1 \ k\Omega$  for all gains other than +1. Gain of +1 is a special case where R<sub>F</sub> is shorted and R<sub>G</sub> is left open.

#### 9.1.2 Inverting Amplifier

The OPA836 and OPA2836 devices can be used as inverting amplifiers with signal input to the inverting input, V<sub>IN</sub> - , through the gain setting resistor R<sub>G</sub>. A basic block diagram of the circuit is shown in 8-2.

If  $V_{IN} = V_{REF} + V_{SIG}$ , then the output of the amplifier may be calculated according to  $\overline{5}$  Reg 2.

$$V_{OUT} = V_{SIG} \left( \frac{-R_F}{R_G} \right) + V_{REF}$$
(2)

 $G = \frac{-R_F}{-R_F}$  $R_{G}\;\;$  , and  $V_{REF}$  provides a reference point around which the input The signal gain of the circuit is set by and output signals swing. Output signals are 180° out-of-phase with the input signals. The nominal value of R<sub>F</sub> must be 1 k  $\Omega$  for inverting gains.

#### 9.1.3 Instrumentation Amplifier

🕙 9-1 is an instrumentation amplifier that combines the high input impedance of the differential-to-differential amplifier circuit and the common-mode rejection of the differential-to-single-ended amplifier circuit. This circuit is often used in applications where high input impedance is required (such as taps from a differential line) or in cases where the signal source has a high output impedance.

If  $V_{IN+} = V_{CM} + V_{SIG+}$  and  $V_{IN-} = V_{CM} + V_{SIG-}$ , then the output of the amplifier may be calculated according to 方程式 3.



(3)

$$V_{OUT} = \left(V_{IN+} - V_{IN-}\right) \times \left(1 + \frac{2R_{F1}}{R_{G1}}\right) \left(\frac{R_{F2}}{R_{G2}}\right) + V_{REF}$$

$$G = \left(1 + \frac{2R_{F1}}{R_{G1}}\right) \left(\frac{R_{F2}}{R_{G2}}\right)$$

The signal gain of the circuit is set by  $( {}^{K_{G1}}) ({}^{K_{G2}})$ . V<sub>CM</sub> is rejected, and V<sub>REF</sub> provides a level shift around which the output signal swings. The single-ended output signal is in-phase with the differential input signal.

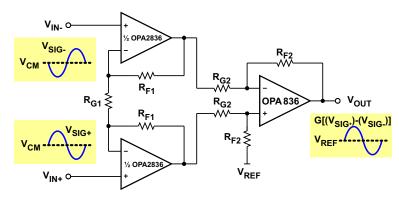


图 9-1. Instrumentation Amplifier

Integrated solutions are available, but the OPA836 device provides a much lower-power, high-frequency solution. For best CMRR performance, resistors must be matched. A good guideline to follow is CMRR  $\approx$  the resistor tolerance; so, 0.1% tolerance will provide approximately 60-dB CMRR.

#### 9.1.4 Attenuators

The noninverting circuit of [8] 8-1 has minimum gain of 1. To implement attenuation, a resistor divider can be placed in series with the positive input, and the amplifier set for gain of 1 by shorting V<sub>OUT</sub> to V<sub>IN</sub> - and removing R<sub>G</sub>. Because the operational amplifier input is high impedance, the resistor divider sets the attenuation.

The inverting circuit of  $\mathbb{R}$  8-2 can be used as an attenuator by making R<sub>G</sub> larger than R<sub>F</sub>. The attenuation is the resistor ratio. For example, a 10:1 attenuator can be implemented with R<sub>F</sub> = 1 k  $\Omega$  and R<sub>G</sub> = 10 k  $\Omega$ .

## 9.1.5 Single-Ended-to-Differential Amplifier

[2] 9-2 shows an amplifier circuit that is used to convert single-ended signals to differential, and provides gain and level shifting. This circuit can be used for converting signals to differential in applications like line drivers for Cat5 cabling or driving differential-input SAR and  $\Delta \Sigma$  ADCs.

With  $V_{IN} = V_{REF} + V_{SIG}$ , the output of the amplifier may be calculated according to  $\overline{5}$ 程式 4.

$$V_{OUT+} = G \times V_{IN} + V_{REF} \text{ and } V_{OUT-} = -G \times V_{IN} + V_{REF} \text{ Where: } G = 1 + \frac{R_F}{R_G}$$
(4)

The differential-signal gain of the circuit is  $2 \times G$ , and  $V_{REF}$  provides a reference around which the output signal swings. The differential output signal is in-phase with the single-ended input signal.



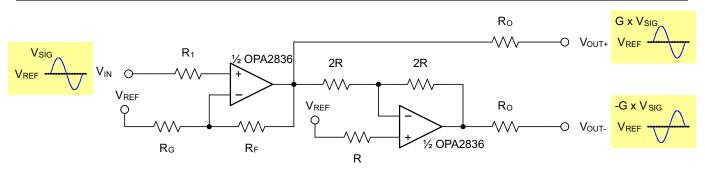


图 9-2. Single Ended to Differential Amplifier

Line termination on the output can be accomplished with resistors R<sub>O</sub>. The differential impedance seen from the line will be 2 × R<sub>0</sub>. For example, if 100- Ω Cat5 cable is used with double termination, the amplifier is typically set for a differential gain of 2 V/V (6 dB) with  $R_F = 0 \Omega$  (short),  $R_G = open$ ,  $2R = 1 k \Omega$ ,  $R1 = 0 \Omega$ ,  $R = 499 \Omega$  to balance the input bias currents, and  $R_0$  = 49.9  $\Omega$  for output line termination. This configuration is shown in 🖄 9-3.

For driving a differential-input ADC the situation is similar, but the output resistors, R<sub>O</sub> are selected with a capacitor across the ADC input for optimum filtering and settling-time performance.

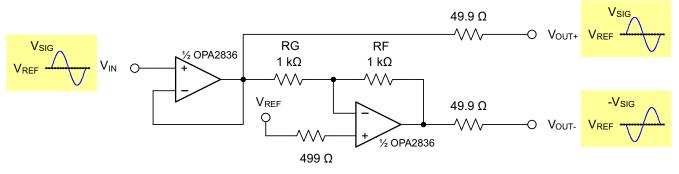


图 9-3. Cat5 Line Driver With Gain = 2 V/V (6 dB)

#### 9.1.6 Differential-to-Signal-Ended Amplifier

🕙 9-4 shows a differential amplifier that is used to convert differential signals to single-ended and provides gain (or attenuation) and level shifting. This circuit can be used in applications like a line receiver for converting a differential signal from a Cat5 cable to a single-ended signal.

If  $V_{IN+} = V_{CM} + V_{SIG+}$  and  $V_{IN-} = V_{CM} + V_{SIG-}$ , then the output of the amplifier may be calculated according to 方程式 5.

$$V_{OUT} = (V_{IN+} - V_{IN-}) \times \left(\frac{R_F}{R_G}\right) + V_{REF}$$

 $\mathsf{R}_{\mathsf{F}}$ 

(5)

G =  $\overline{R_G}$  ,  $V_{CM}$  is rejected, and  $V_{REF}$  provides a level shift around which the The signal gain of the circuit is output signal swings. The single ended output signal is in-phase with the differential input signal.



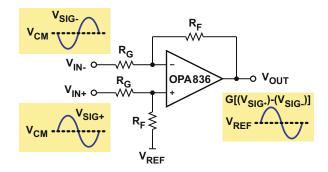


图 9-4. Differential to Single-Ended Amplifier

Line termination can be accomplished by adding a shunt resistor across the VIN+ and VIN- inputs. The differential impedance is the shunt resistance in parallel with the input impedance of the amplifier circuit, which is usually much higher. For low gain and low line impedance, the resistor value to add is approximately the impedance of the line. For example if 100- $\Omega$  Cat5 cable is used with a gain of 1 amplifier and R<sub>F</sub> = R<sub>G</sub> = 1 k  $\Omega$ , adding a 100- $\Omega$  shunt across the input will give a differential impedance of 98  $\Omega$ , which is adequate for most applications.

For best CMRR performance, resistors must be matched. Assuming CMRR  $\approx$  the resistor tolerance, a 0.1% tolerance will provide about 60-dB CMRR.

#### 9.1.7 Differential-to-Differential Amplifier

🕙 9-5 shows a differential amplifier that is used to amplify differential signals. This circuit has high input impedance and is used in differential line driver applications where the signal source is a high-impedance driver (for example, a differential DAC) that must drive a line.

If  $V_{INt} = V_{CM} + V_{SIGt}$ , then the output of the amplifier may be calculated according to  $5 R \pm 3.6$ .

$$V_{OUT \pm} = V_{IN\pm} \times \left(1 + \frac{2R_F}{R_G}\right) + V_{CM}$$
(6)

The signal gain of the circuit is set by

G = 1 +  $\frac{2R_F}{R_G}$ , and V<sub>CM</sub> passes with unity gain. The amplifier in essence combines two noninverting amplifiers into one differential amplifier that shares the R<sub>G</sub> resistor, which makes R<sub>G</sub> effectively half its value when calculating the gain. The output signals are in-phase with the input signals.

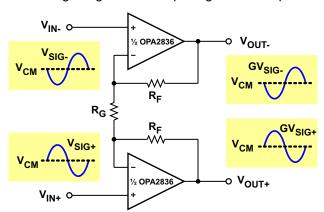


图 9-5. Differential to Differential Amplifier

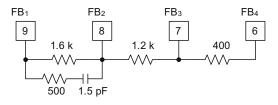


#### 9.1.8 Gain Setting With OPA836 RUN Integrated Resistors

The OPA836 RUN package option includes integrated gain-setting resistors for smallest possible footprint on a printed circuit board ( $\approx$  2.00 mm × 2.00 mm). By adding circuit traces on the PCB, gains of +1, -1, -1.33, +2, +2.33, -3, +4, -4, +5, -5.33, +6.33, -7, +8 and inverting attenuations of -0.1429, -0.1875, -0.25, -0.33, -0.75 can be achieved.

图 9-6 shows a simplified view of how the OPA836IRUN integrated gain-setting network is implemented. 表 9-1 lists the required pin connections for various noninverting and inverting gains (reference 图 8-1 and 图 8-2). 表 9-2 shows the required pin connections for various attenuations using the inverting-amplifier architecture (reference 图 8-2). Due to ESD protection devices being used on all pins, the absolute maximum and minimum input-voltage range,  $V_{S-} - 0.7$  V to  $V_{S+} + 0.7$  V, applies to the gain-setting resistors, so attenuation of large input voltages requires external resistors to implement.

The gain-setting resistors are laser trimmed to 1% tolerance with nominal values of 1.6 k $\Omega$ , 1.2 k $\Omega$ , and 400  $\Omega$ . The gain-setting resistors have excellent temperature coefficients, and gain drift is superior to the drift with external gain-setting resistors. The 500- $\Omega$  and 1.5-pF capacitor in parallel with the 1.6-k $\Omega$  gain-setting resistor provide compensation for best stability and pulse response.



#### 图 9-6. OPA836IRUN Gain-Setting Network

NONINVERTING GAIN (图 8-1)	INVERTING GAIN (图 8-2)	SHORT PINS	SHORT PINS	SHORT PINS	SHORT PINS
1 V/V (0 dB)	_	1 to 9			_
2 V/V (6.02 dB)	- 1 V/V (0 dB)	1 to 9	2 to 8	6 to GND	
2.33 V/V (7.36 dB)	- 1.33 V/V (2.5 dB)	1 to 9	2 to 8	7 to GND	
4 V/V (12.04 dB)	- 3 V/V (9.54 dB)	1 to 8	2 to 7	6 to GND	
5 V/V (13.98 dB)	- 4 V/V (12.04 dB)	1 to 9	2 to 7 or 8	7 to 8	6 to GND
6.33 V/V (16.03 dB)	- 5.33 V/V (14.54 dB)	1 to 9	2 to 6 or 8	6 to 8	7 to GND
8 V/V (18.06 dB)	- 7 V/V (16.90 dB)	1 to 9	2 to 7	6 to GND	

#### 表 9-1. Gain Settings

#### 表 9-2. Attenuator Settings

INVERTING GAIN (图 8-2)	SHORT PINS	SHORT PINS	SHORT PINS	SHORT PINS
- 0.75 V/V ( - 2.5 dB)	1 to 7	2 to 8	9 to GND	_
- 0.333 V/V ( - 9.54 dB)	1 to 6	2 to 7	8 to GND	—
- 0.25 V/V ( - 12.04 dB)	1 to 6	2 to 7 or 8	7 to 8	9 to GND
- 0.1875 V/V ( - 14.54 dB)	1 to 7	2 to 6 or 8	6 to 8	9 to GND
- 0.1429 V/V ( - 16.90 dB)	1 to 6	2 to 7	9 to GND	—



## 9.1.9 Pulse Application With Single-Supply

For pulsed applications, where the signal is at ground and pulses to a positive or negative voltage, the circuit bias-voltage considerations differ from those in an application with a signal that swings symmetrical about a reference point.  $\boxed{8}$  9-7 shows a circuit where the signal is at ground (0 V) and pulses to a positive value.

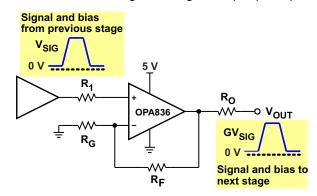


图 9-7. Noninverting Single Supply With Pulse

If the input signal pulses negative from ground, an inverting amplifier is more appropriate as shown in [8] 9-8. A key consideration in noninverting and inverting cases is that the input and output voltages are kept within the limits of the amplifier. Because the V<sub>ICR</sub> of the OPA836 device includes the negative supply rail, the OPA836 operational amplifier is well-suited to this application.

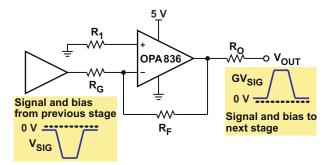


图 9-8. Inverting Single Supply With Pulse

## 9.1.10 ADC Driver Performance

The OPA836 device provides excellent performance when driving high-performance delta-sigma ( $\Delta \Sigma$ ) and successive-approximation-register (SAR) ADCs in low-power audio and industrial applications.

To show achievable performance, the OPA836 device is tested as the drive amplifier for the ADS8326. The ADS8326 is a 16-bit, micro power, SAR ADC with pseudodifferential inputs and sample rates up to 250 kSPS. The device offers excellent noise and distortion performance in a small 8-pin SOIC or VSSOP (MSOP) package. Low power and small size make the ADS8326 and OPA836 devices an ideal solution for portable and battery-operated systems, remote data-acquisition modules, simultaneous multichannel systems, and isolated data acquisition.

With the circuit shown in [8] 9-9 to test the performance, [8] 9-10 shows the FFT plot with a 10-kHz input signal. The tabulated AC analysis is in  $\frac{1}{5}$  9-3.



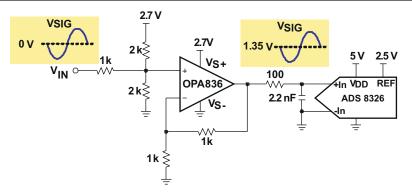
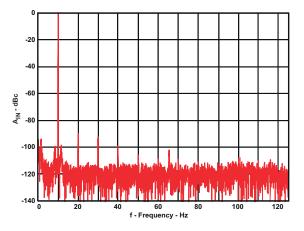


图 9-9. OPA836 and ADS8326 Test Circuit



#### 图 9-10. ADS8326 and OPA836 10-kHz FFT

寿	9-3.	AC	Ana	lysis
-11	5-0.	ЛV	Alla	19313

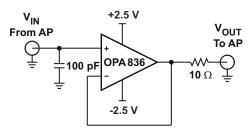
TONE (Hz)	SIGNAL (dBFS)	SNR (dBc)	THD (dBc)	SINAD (dBc)	SFDR (dBc)	
10k	- 0.85	83.3	- 86.6	81.65	88.9	

#### 9.2 Typical Applications

#### 9.2.1 Audio Frequency Performance

The OPA836 and OPA2836 devices provide excellent audio performance with low quiescent power. To show performance in the audio band, an audio analyzer from Audio Precision (2700 series) tests THD+N and FFT at 1  $V_{RMS}$  output voltage.

OPA836 Audio Precision Analyzer Test Circuit shows the circuit used for the audio-frequency performance test.



The 100-pF capacitor to ground on the input helped to decouple noise pick up in the lab and improved noise performance.

#### 图 9-11. OPA836 Audio Precision Analyzer Test Circuit



#### 9.2.1.1 Design Requirements

Design a low distortion, single-ended input to single-ended output audio amplifier using the OPA836 device. The 2700-series audio analyzer from Audio Precision is used as the signal source and also as the measurement system.

CONFIGURATION	INPUT EXCITATION	PERFORMANCE TARGET	R <sub>Load</sub>						
OPA836 Unity Gain Config.	1 KHz Tone Frequency	>110 dBc SFDR	300 Ω and 100 k Ω						

#### 表 9-4. Design Requirements

#### 9.2.1.2 Detailed Design Procedure

The OPA836 device is tested in this application in a unity-gain buffer configuration. A buffer configuration is selected for maximum loop gain of the amplifier circuit. At higher closed-loop gains, the loop gain of the circuit reduces, which increases the harmonic distortion. The relationship between distortion and closed-loop gain at a fixed input frequency is shown in Harmonic Distortion vs Gain in  $\ddagger$  7.9. The test was performed under using resistive loads of 300  $\Omega$  and 100 K $\Omega$ . Harmonic Distortion vs Load Resistance shows the distortion performance of the amplifier versus the resistive load. Output loading, output swing, and closed-loop gain play a key role in determining the distortion performance of the amplifier.

#### Note

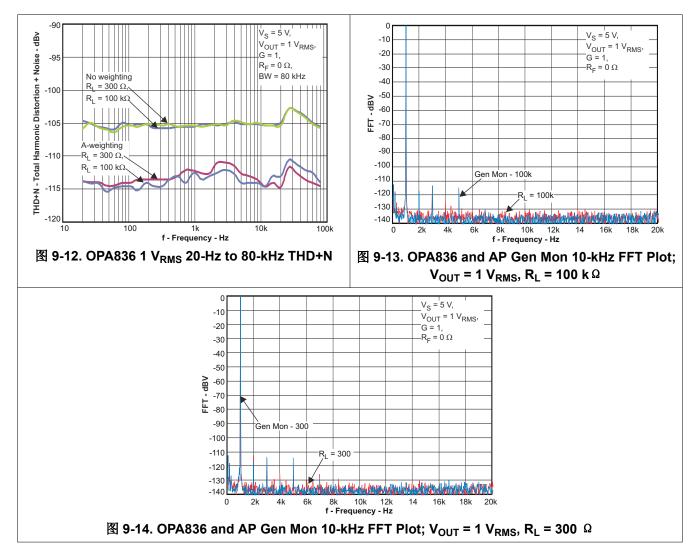
The 100-pF capacitor to ground on the input helped to decouple noise pickup in the lab and improved noise performance.

The Audio Precision was configured as a single-ended output in this application circuit. In applications where a differential output is available, the OPA836 device can be configured as a differential-to-single-ended amplifier as shown in [m] 9-4. Power-supply bypassing is critical to reject noise from the power supplies. A 2.2-  $\mu$  F supply decoupling capacitor must be placed within 2 inches of the device and can be shared with other operational amplifiers on the same board. A 0.1-  $\mu$  F supply decoupling capacitor must be placed within 0.1 inch. For a split supply, a capacitor is required for both supplies. A 0.1- $\mu$ F capacitor placed directly between the supplies is also beneficial for improving system noise performance. If the output load is heavy, such as 16  $\Omega$  to 32  $\Omega$ , performance of the amplifier could begin to degrade. To drive such heavy loads, both channels of the OPA2836 device can be paralleled with their outputs isolated with 1- $\Omega$  resistors to reduce the loading effects.



#### 9.2.1.3 Application Curves

Solution 9-12 shows the THD+N performance with 100-k  $\Omega$  and 300- $\Omega$  loads, and with A-weighting and with no weighting. Both loads show similar performance. With no weighting, the THD+N performance is dominated by the noise for both loads. A-weighting provides filtering that improves the noise, revealing the increased distortion with RL = 300  $\Omega$ .





#### 9.2.2 Active Filters

The OPA836 and OPA2836 devices are good choices for active filters.  $\boxed{8}$  9-15 and  $\boxed{8}$  9-16 show MFB and Sallen-Key circuits designed using the *WEBENCH*<sup>®</sup> *Filter Designer* to implement second-order low-pass Butterworth filter circuits.  $\boxed{8}$  9-17 shows the frequency response.

Other MFB and Sallen-Key filter circuits offer similar performance. The main difference is the MFB is an inverting amplifier in the pass-band and the Sallen-Key is noninverting. The primary advantage for each is the Sallen-Key in unity gain has no resistor gain-error term, and thus no sensitivity to gain error, while the MFB has better attenuation properties beyond the bandwidth of the operational amplifier.

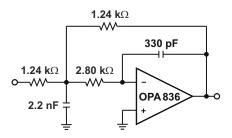


图 9-15. MFB 100-kHz Second-Order Low-Pass Butterworth Filter Circuit

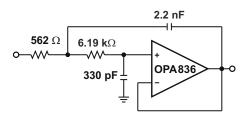


图 9-16. Sallen-Key 100-kHz Second-Order Low-Pass Butterworth Filter Circuit

#### 9.2.2.1 Application Curve

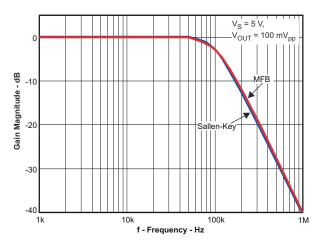


图 9-17. MFB and Sallen-Key Second Order Low-Pass Butterworth Filter Response



### **10 Power Supply Recommendations**

The OPAx836 devices are intended to work in a supply range of 2.7 V to 5 V. Supply-voltage tolerances are supported with the specified operating range of 2.5 V (7% on a 2.7-V supply) and 5.5 V (10% on a 5-V supply). Good power-supply bypassing is required. Minimize the distance (< 0.1 inch) from the power-supply pins to high frequency,  $0.1-\mu$  F decoupling capacitors. A larger capacitor (2.2  $\mu$ F is typical) is used along with a high frequency,  $0.1-\mu$ F supply decoupling capacitor at the device supply pins. For single-supply operation, only the positive supply has these capacitors. When a split supply is used, use these capacitors for each supply to ground. If necessary, place the larger capacitors farther from the device and share these capacitors among several devices in the same area of the PCB. Avoid narrow power and ground traces to minimize inductance between the pins and the decoupling capacitors. An optional supply decoupling capacitor across the two power supplies (for bipolar operation) reduces second harmonic distortion.



### 11 Layout

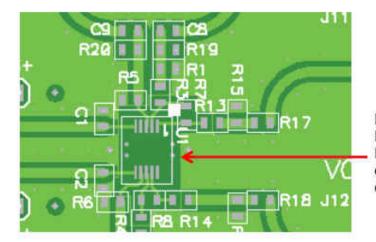
#### **11.1 Layout Guidelines**

The *OPA835DBV, OPA836DBV EVM* (SLOU314) can be used as a reference when designing the circuit board. TI recommends following the EVM layout of the external components near the amplifier, ground-plane construction, and power routing. General guidelines are listed as follows:

- 1. Signal routing must be direct and as short as possible into and out of the operational amplifier.
- 2. The feedback path must be short and direct avoiding vias if possible especially with G = +1.
- 3. Ground or power planes must be removed from directly under the negative input and output pins of the amplifier.
- 4. TI recommends placing a series output resistor as close to the output pin as possible. See *Series Output Resistor vs Capacitive Load* (Series Output Resistor vs Capacitive Load) for recommended values for the expected capacitive load.
- 5. A 2.2-µF power-supply decoupling capacitor must be placed within two inches of the device and can be shared with other operational amplifiers. For spit supply, a capacitor is required for both supplies.
- 6. A 0.1-µF power-supply decoupling capacitor must be placed as close to the power supply pins as possible, preferably within 0.1 inch. For split supply, a capacitor is required for both supplies.
- 7. The PD pin uses TTL logic levels. If the pin is not used, it must be tied to the positive supply to enable the amplifier. If the pin is used, it must be actively driven. A bypass capacitor is not necessary, but is used for robustness in noisy environments.

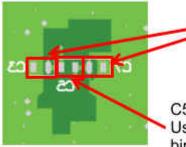


### 11.2 Layout Example



Dark green areas indicate regions of the PCB where the underlying Ground and Power Planes have been removed in order to minimize parasitic capacitance on the sensitive input and output nodes.

图 11-1. Top Layer



C3 and C7 are 0.1-µF bypass capacitors placed directly underneath the device power supply pins.

C5 is a bypass capacitor between the supply pins. Use this when configuring the amplifier with bipolar supplies to improve HD2 performance.

图 11-2. Bottom Layer



### 12 Device and Documentation Support

#### **12.1 Device Support**

#### 12.1.1 Development Support

WEBENCH® Filter Designer

#### 12.1.2 Related Documentation

For related documentation see the following:

• Texas Instruments, OPA835DBV, OPA836DBV EVM user's guide

#### 12.2 接收文档更新通知

要接收文档更新通知,请导航至 ti.com 上的器件产品文件夹。点击*订阅更新*进行注册,即可每周接收产品信息更改摘要。有关更改的详细信息,请查看任何已修订文档中包含的修订历史记录。

#### 12.3 支持资源

**TI E2E<sup>™</sup>** 支持论坛是工程师的重要参考资料,可直接从专家获得快速、经过验证的解答和设计帮助。搜索现有解 答或提出自己的问题可获得所需的快速设计帮助。

链接的内容由各个贡献者"按原样"提供。这些内容并不构成 TI 技术规范,并且不一定反映 TI 的观点;请参阅 TI 的《使用条款》。

#### 12.4 静电放电警告



静电放电 (ESD) 会损坏这个集成电路。德州仪器 (TI) 建议通过适当的预防措施处理所有集成电路。如果不遵守正确的处理和安装程序,可能会损坏集成电路。

ESD 的损坏小至导致微小的性能降级,大至整个器件故障。精密的集成电路可能更容易受到损坏,这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

#### 12.5 术语表

TI术语表 本术语表列出并解释了术语、首字母缩略词和定义。

#### 12.6 Trademarks

TI E2E<sup>™</sup> is a trademark of Texas Instruments. WEBENCH<sup>®</sup> is a registered trademark of Texas Instruments. 所有商标均为其各自所有者的财产。

#### 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



### **PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
OPA2836ID	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR -40 to 125		2836
OPA2836ID.B	Active	Production	SOIC (D)   8	75   TUBE	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IDGS	Active	Production	VSSOP (DGS)   10	80   TUBE	Yes	NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IDGS.B	Active	Production	VSSOP (DGS)   10	80   TUBE	Yes	NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IDGSR	Active	Production	VSSOP (DGS)   10	2500   LARGE T&R	Yes	NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IDGSR.B	Active	Production	VSSOP (DGS)   10	2500   LARGE T&R	Yes	NIPDAUAG	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IDR	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IDR.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IDRG4	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IDRG4.B	Active	Production	SOIC (D)   8	2500   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRMCR	Active	Production	UQFN (RMC)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRMCR.B	Active	Production	UQFN (RMC)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRMCRG4	Active	Production	UQFN (RMC)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRMCRG4.B	Active	Production	UQFN (RMC)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRMCT	Active	Production	UQFN (RMC)   10	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRMCT.B	Active	Production	UQFN (RMC)   10	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRUNR	Active	Production	QFN (RUN)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRUNR.B	Active	Production	QFN (RUN)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRUNRG4	Active	Production	QFN (RUN)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRUNRG4.B	Active	Production	QFN (RUN)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRUNT	Active	Production	QFN (RUN)   10	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA2836IRUNT.B	Active	Production	QFN (RUN)   10	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	2836
OPA836IDBVR	Active	Production	SOT-23 (DBV)   6	3000   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	QTL
OPA836IDBVR.B	Active	Production	SOT-23 (DBV)   6	3000   LARGE T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	QTL
OPA836IDBVT	Active	Production	SOT-23 (DBV)   6	250   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	QTL
OPA836IDBVT.B	Active	Production	SOT-23 (DBV)   6	250   SMALL T&R	Yes	SN	Level-1-260C-UNLIM	-40 to 125	QTL
OPA836IRUNR	Active	Production	QFN (RUN)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	836
OPA836IRUNR.B	Active	Production	QFN (RUN)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	836
OPA836IRUNRG4	Active	Production	QFN (RUN)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	836



Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
OPA836IRUNRG4.B	Active	Production	QFN (RUN)   10	3000   LARGE T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	836
OPA836IRUNT	Active	Production	QFN (RUN)   10	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	836
OPA836IRUNT.B	Active	Production	QFN (RUN)   10	250   SMALL T&R	Yes	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	836

<sup>(1)</sup> **Status:** For more details on status, see our product life cycle.

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

#### OTHER QUALIFIED VERSIONS OF OPA2836 :

• Automotive : OPA2836-Q1



NOTE: Qualified Version Definitions:

• Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

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STRUMENTS

#### TAPE AND REEL INFORMATION





#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
OPA2836IDGSR	VSSOP	DGS	10	2500	330.0	12.4	5.3	3.4	1.4	8.0	12.0	Q1
OPA2836IDR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
OPA2836IDRG4	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
OPA2836IRMCR	UQFN	RMC	10	3000	180.0	9.5	2.3	2.3	1.1	2.0	8.0	Q2
OPA2836IRMCRG4	UQFN	RMC	10	3000	180.0	9.5	2.3	2.3	1.1	2.0	8.0	Q2
OPA2836IRMCT	UQFN	RMC	10	250	180.0	9.5	2.3	2.3	1.1	2.0	8.0	Q2
OPA2836IRUNR	QFN	RUN	10	3000	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2
OPA2836IRUNRG4	QFN	RUN	10	3000	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2
OPA2836IRUNT	QFN	RUN	10	250	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2
OPA836IDBVR	SOT-23	DBV	6	3000	178.0	9.0	3.23	3.17	1.37	4.0	8.0	Q3
OPA836IDBVT	SOT-23	DBV	6	250	178.0	9.0	3.23	3.17	1.37	4.0	8.0	Q3
OPA836IRUNR	QFN	RUN	10	3000	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2
OPA836IRUNRG4	QFN	RUN	10	3000	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2
OPA836IRUNT	QFN	RUN	10	250	180.0	8.4	2.3	2.3	1.15	4.0	8.0	Q2



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## PACKAGE MATERIALS INFORMATION

23-Jul-2025



Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
OPA2836IDGSR	VSSOP	DGS	10	2500	366.0	364.0	50.0
OPA2836IDR	SOIC	D	8	2500	353.0	353.0	32.0
OPA2836IDRG4	SOIC	D	8	2500	353.0	353.0	32.0
OPA2836IRMCR	UQFN	RMC	10	3000	205.0	200.0	30.0
OPA2836IRMCRG4	UQFN	RMC	10	3000	205.0	200.0	30.0
OPA2836IRMCT	UQFN	RMC	10	250	205.0	200.0	30.0
OPA2836IRUNR	QFN	RUN	10	3000	213.0	191.0	35.0
OPA2836IRUNRG4	QFN	RUN	10	3000	213.0	191.0	35.0
OPA2836IRUNT	QFN	RUN	10	250	213.0	191.0	35.0
OPA836IDBVR	SOT-23	DBV	6	3000	180.0	180.0	18.0
OPA836IDBVT	SOT-23	DBV	6	250	180.0	180.0	18.0
OPA836IRUNR	QFN	RUN	10	3000	213.0	191.0	35.0
OPA836IRUNRG4	QFN	RUN	10	3000	213.0	191.0	35.0
OPA836IRUNT	QFN	RUN	10	250	213.0	191.0	35.0

### TEXAS INSTRUMENTS

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23-Jul-2025

### TUBE

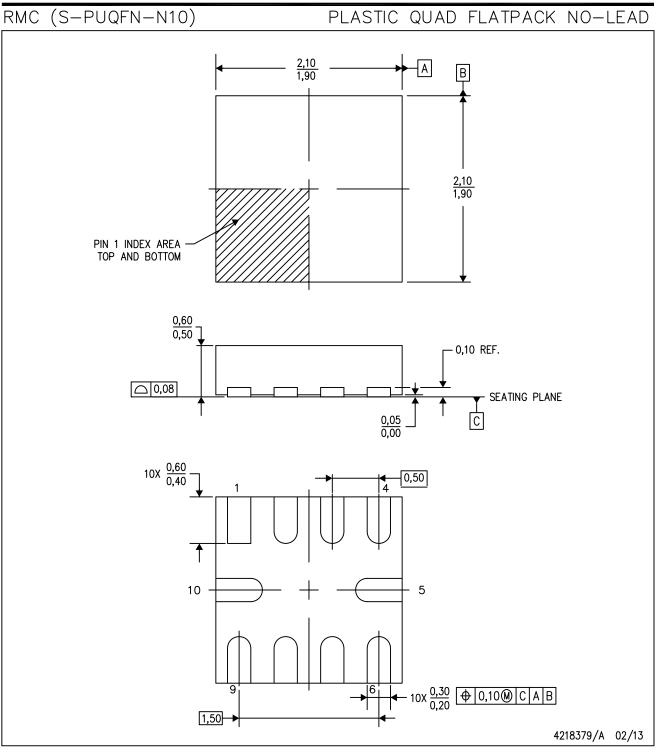


### - B - Alignment groove width

#### \*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	Τ (μm)	B (mm)
OPA2836ID	D	SOIC	8	75	507	8	3940	4.32
OPA2836ID.B	D	SOIC	8	75	507	8	3940	4.32
OPA2836IDGS	DGS	VSSOP	10	80	330	6.55	500	2.88
OPA2836IDGS.B	DGS	VSSOP	10	80	330	6.55	500	2.88

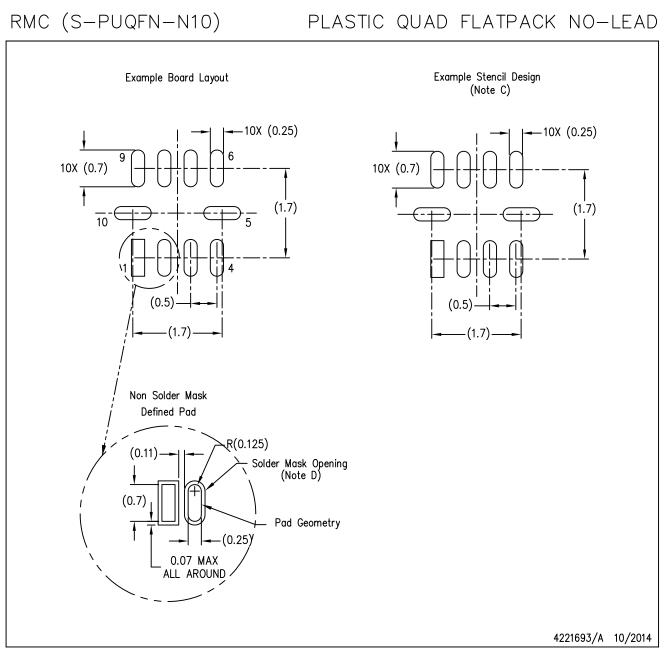
## **MECHANICAL DATA**



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. Quad Flatpack, No-Leads (QFN) package configuration.





NOTES: A. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only.

- B. This drawing is subject to change without notice.
- C. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
   D. Customers should contact their board fabrication site for minimum solder mask web tolerances between signal pads.



# **DGS0010A**



## **PACKAGE OUTLINE**

### VSSOP - 1.1 mm max height

SMALL OUTLINE PACKAGE



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice. 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-187, variation BA.



# DGS0010A

# **EXAMPLE BOARD LAYOUT**

## VSSOP - 1.1 mm max height

SMALL OUTLINE PACKAGE



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# DGS0010A

# **EXAMPLE STENCIL DESIGN**

## VSSOP - 1.1 mm max height

SMALL OUTLINE PACKAGE



NOTES: (continued)

9. Board assembly site may have different recommendations for stencil design.



<sup>8.</sup> Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

## **RUN 10**

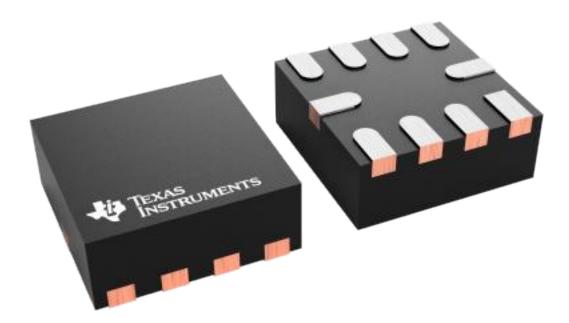
2 X 2, 0.5 mm pitch

# **GENERIC PACKAGE VIEW**

### WQFN - 0.8 mm max height

PLASTIC QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.





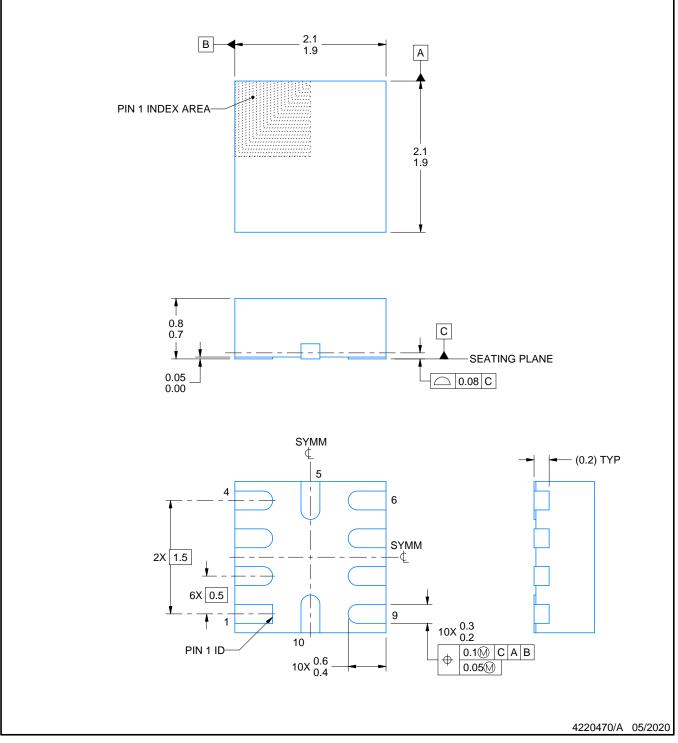
# **RUN0010A**



# **PACKAGE OUTLINE**

### WQFN - 0.8 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.

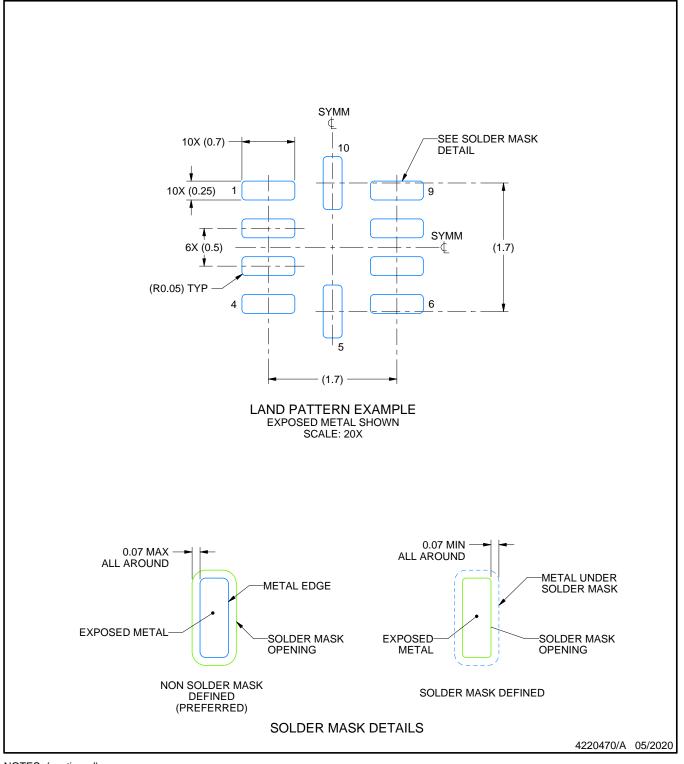


## **RUN0010A**

# **EXAMPLE BOARD LAYOUT**

### WQFN - 0.8 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

3. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

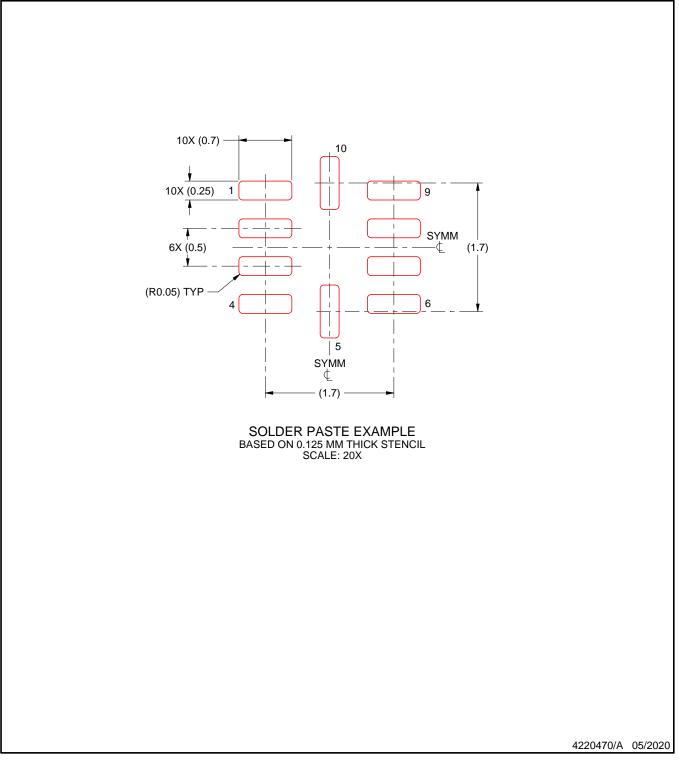


## **RUN0010A**

# **EXAMPLE STENCIL DESIGN**

## WQFN - 0.8 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



# D0008A



## **PACKAGE OUTLINE**

### SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



#### NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.

- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



## D0008A

# **EXAMPLE BOARD LAYOUT**

### SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



## D0008A

# **EXAMPLE STENCIL DESIGN**

## SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

9. Board assembly site may have different recommendations for stencil design.



# **DBV0006A**



## **PACKAGE OUTLINE**

## SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.2. This drawing is subject to change without notice.3. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.25 per side.

- 4. Leads 1,2,3 may be wider than leads 4,5,6 for package orientation.
- 5. Refernce JEDEC MO-178.



## **DBV0006A**

# **EXAMPLE BOARD LAYOUT**

## SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



## **DBV0006A**

# **EXAMPLE STENCIL DESIGN**

## SOT-23 - 1.45 mm max height

SMALL OUTLINE TRANSISTOR



NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

9. Board assembly site may have different recommendations for stencil design.



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