











DS80PCI810

ZHCSCW4-OCTOBER 2014

DS80PCI810 低功耗 **8Gbps 8** 通道线性中继器

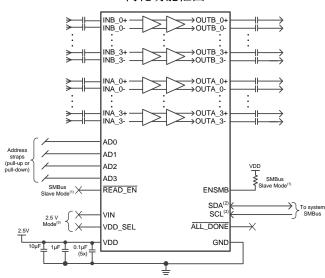
特性

- 每通道 70mW (典型值) 的低功耗, 可选择关闭不 使用的通道
- 支持无缝链路协商
- 高级可配置信号调节 I/O
 - 4GHz 时,接收高达约 10dB 的连续时间线性均 衡器 (CTLE)
 - 线性输出驱动器
 - 可变输出电压范围高达 1200mVp-p
- 自动接收器检测(热插拔)
- 输入至输出超低延迟: 80ps (典型值)
- 可通过引脚选择 EEPROM 或 SMBus 接口进行编
- 单电源电压: 2.5V 或 3.3V
- 4kV 人体模型 (HBM) 静电放电 (ESD) 额定电压
- -40°C 至 85°C 工作温度范围
- 10mm x 5.5mm 54 引脚超薄型四方扁平无引线 (WQFN) 封装内的直通引脚分配
- 与 DS80PCI800 引脚兼容

2 应用

- PCI Express 1代、2代和3代
- 其它速率高达 8Gbps 的专有高速接口

简化功能框图



3 说明

DS80PCI810 是一款超低功耗高性能中继器/转接驱动 器,专用于支持高速接口速率高达 8Gbps 的八个通 道,例如 PCle 1 代、2 代和 3 代。接收器的连续时间 线性均衡器 (CTLE) 后接一个线性输出驱动器,可在 4GHz (8Gbps) 时提供 2.7dB 至 9.5dB 的可编程高频 增强功能。 CTLE 接收器能够打开一个因码间干扰 (ISI)(由电路板迹线或铜质同轴电缆等互连介质引起) 而完全关闭的输入眼型状态。可编程的均衡能够可在 互连通道内的实体布局方面实现最大限度的灵活性并提 高通道的总体性能。

当在 PCIe 应用中运行时, DS80PCI810 保留发射信号 特性,从而使得主机控制器和端点能够协商发射均衡器 系数。 这个链路协商协议的透明管理有助于实现系统 级互用性并最大限度缩短延迟。

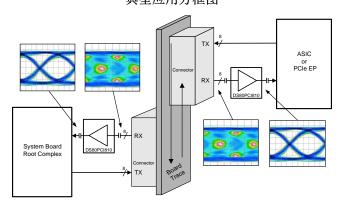
可通过引脚控制、软件(SMBus 或 I2C)来轻松应用 相关可编程设置,或者通过外部 EEPROM 直接加载设 置。 在 EEPROM 模式下,配置信息在加电时自动加 载,这样就免除了对于外部微控制器或软件驱动程序的 需要。

器件信息(1)

部件号	封装	封装尺寸 (标称值)
DS80PCI810	WQFN (54)	10mm x 5.5mm

(1) 如需了解所有可用封装,请见数据表末尾的可订购产品附录。

典型应用方框图





目录

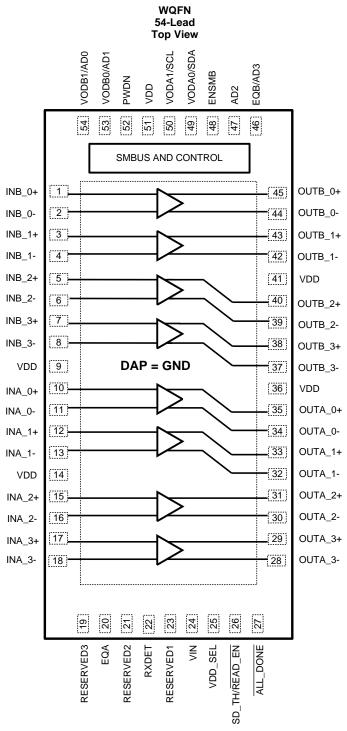
1	特性1		7.2 Functional Block Diagram	
2	应用 1		7.3 Feature Description	14
3	说明1		7.4 Device Functional Modes	14
4	修订历史记录		7.5 Programming	17
5	Pin Configuration and Functions		7.6 Register Maps	26
6	Specifications	8	Applications and Implementation	42
U	6.1 Absolute Maximum Ratings		8.1 Application Information	42
	6.2 Handling Ratings		8.2 Typical Applications	43
	6.3 Recommended Operating Conditions	9	Power Supply Recommendations	<u>5</u> 1
	6.4 Thermal Information	10	Layout	52
	6.5 Electrical Characteristics		10.1 Layout Guidelines	52
	6.6 Electrical Characteristics — Serial Management Bus		10.2 Layout Example	
	Interface	11	器件和文档支持	
	6.7 Timing Requirements Serial Bus Interface 10		11.1 商标	
	6.8 Typical Characteristics		11.2 静电放电警告	53
7	Detailed Description 13		11.3 术语表	53
	7.1 Overview	12	机械封装和可订购信息	53

4 修订历史记录

日期	修订版本	注释
2014年10月	*	最初发布。



5 Pin Configuration and Functions



NOTE: Above 54-lead WQFN graphic is a TOP VIEW, looking down through the package.



Pin Functions⁽¹⁾

	T	PIII I	Functions				
PIN NAME	PIN NUMBER	I/O, TYPE	DESCRIPTION				
DIFFERENTIAL HIGH SPI	EED I/O						
INB_0+, INB_0-, INB_1+, INB_1-, INB_2+, INB_2-, INB_3+, INB_3-	1, 2 3, 4 5, 6 7, 8	I, CML	Inverting and non-inverting CML differential inputs to the equalizer. On-chip 50 Ω termination resistor connects INB_n+ to VDD and INB_n-to VDD depending on the state of RXDET. See Table 2. AC coupling required on high-speed I/O				
OUTB_0+, OUTB_0-, OUTB_1+, OUTB_1-, OUTB_2+, OUTB_2-, OUTB_3+, OUTB_3-	45, 44 43, 42 41, 40 39, 38	O, CML	Inverting and non-inverting 50 Ω driver outputs. Compatible with AC coupled CML inputs. AC coupling required on high-speed I/O				
INA_0+, INA_0-, INA_1+, INA_1-, INA_2+, INA_2-, INA_3+, INA_3-	10, 11 12, 13 15, 16 17, 18	I, CML	Inverting and non-inverting CML differential inputs to the equalizer. On-chip 50 Ω termination resistor connects INA_n+ to VDD and INA_n-to VDD depending on the state of RXDET. See Table 2. AC coupling required on high-speed I/O				
OUTA_0+, OUTA_0-, OUTA_1+, OUTA_1-, OUTA_2+, OUTA_2-, OUTA_3+, OUTA_3-	35, 34 33, 32 31, 30 29, 28	O, CML	Inverting and non-inverting 50 Ω driver outputs. Compatible with AC coupled CML inputs. AC coupling required on high-speed I/O				
CONTROL PINS — SHAR	CONTROL PINS — SHARED (LVCMOS)						
ENSMB	48	I, LVCMOS	System Management Bus (SMBus) Enable Pin Tie 1 k Ω to VDD (2.5 V mode) or VIN (3.3 V mode) = Register Access SMBus Slave Mode FLOAT = Read External EEPROM (SMBus Master Mode) Tie 1 k Ω to GND = Pin Mode				
ENSMB = 1 (SMBus SLA)	VE MODE)						
SCL	50	I, LVCMOS, O, OPEN Drain	In SMBus Slave Mode, this pin is the SMBus clock I/O. Clock input or open drain output. External 2 k Ω to 5 k Ω pull-up resistor required as per SMBus interface standards (2)				
SDA	49	I, LVCMOS, O, OPEN Drain	In both SMBus Modes, this pin is the SMBus data I/O. Data input or open drain output. External 2 k Ω to 5 k Ω pull-up resistor required as per SMBus interface standards (2)				
AD0-AD3	54, 53, 47, 46	I, LVCMOS	SMBus Slave Address Inputs. In both SMBus Modes, these pins are the user set SMBus slave address inputs. External 1 k Ω pull-up or pull-down recommended. Note: In Pin Mode, AD2 must be tied via external 1 k Ω to GND.				
RESERVED2	21	I, 4-LEVEL, LVCMOS	Reserved For applications requiring Signal Detect status register read-back: • Leave Pin 21 floating. • Write Reg 0x08[2] = 1 if Pin 21 is floating. Otherwise, tie Pin 21 via external 1 kΩ to GND (External 1 kΩ to VDD (2.5 V mode) or VIN (3.3 V mode) is also acceptable).				
RESERVED3	19	I, 4-LEVEL, LVCMOS	Reserved This input may be left floating, tied via 1 k Ω to VDD (2.5 V mode) or VIN (3.3 V mode), or tied via 1 k Ω to GND.				

⁽¹⁾ LVCMOS inputs without the "Float" conditions must be driven to a logic low or high at all times or operation is not ensured. Input edge rate for LVCMOS/FLOAT inputs must be faster than 50 ns from 10–90%.

For 3.3 V mode operation, VIN pin input = 3.3 V and the logic "1" or "high" reference for the 4-level input is 3.3 V. For 2.5 V mode operation, VDD pin output= 2.5 V and the logic "1" or "high" reference for the 4-level input is 2.5 V.

⁽²⁾ SCL and SDA pins can be tied either to 3.3 V or 2.5 V, regardless of whether the device is operating in 2.5 V mode or 3.3 V mode.



Pin Functions⁽¹⁾ (continued)

	Fill Functions, (Continued)						
PIN NAME	PIN NUMBER	I/O, TYPE	DESCRIPTION				
ENSMB = Float (SMBus	MASTER MODE)	T					
SCL	50	I, LVCMOS, O, OPEN Drain	Clock output when loading EEPROM configuration, reverting to SMBus clock input when EEPROM load is complete ($\overline{ALL_DONE} = 0$). External 2 k Ω to 5 k Ω pull-up resistor required as per SMBus interface standards ⁽²⁾				
SDA	49	I, LVCMOS, O, OPEN Drain	In both SMBus Modes, this pin is the SMBus data I/O. Data input or open drain output. External 2 k Ω to 5 k Ω pull-up resistor required as per SMBus interface standards (2)				
AD0-AD3	54, 53, 47, 46	I, LVCMOS	SMBus Slave Address Inputs. In both SMBus Modes, these pins are the user set SMBus slave address inputs. External 1 k Ω pull-up or pull-down recommended. Note: In Pin Mode, AD2 must be tied via external 1 k Ω to GND.				
READ_EN	26	I, LVCMOS	A logic low on this pin starts the load from the external EEPROM $^{(3)}$. Once EEPROM load is complete (ALL_DONE = 0), this pin functionality remains as READ_EN. It does not revert to an SD_TH input.				
RESERVED2	21	I, 4-LEVEL, LVCMOS	Reserved For applications requiring Signal Detect status register read-back: • Leave Pin 21 floating. • Write Reg 0x08[2] = 1 if Pin 21 is floating. Otherwise, tie Pin 21 via external 1 kΩ to GND (External 1 kΩ to VDD (2.5 V mode) or VIN (3.3 V mode) is also acceptable).				
RESERVED3	19	I, 4-LEVEL, LVCMOS	Reserved This input may be left floating, tied via 1 k Ω to VDD (2.5 V mode) or VIN (3.3 V mode), or tied via 1 k Ω to GND.				
ENSMB = 0 (PIN MODE)							
EQA EQB	20 46	I, 4-LEVEL, LVCMOS	EQA and EQB pins control the level of equalization for the A-channels and B-channels, respectively. The pins are defined as EQA and EQB only when ENSMB is de-asserted (low). Each of the four A-channels have the same level unless controlled by the SMBus control registers. Likewise, each of the four B-channels have the same level unless controlled by the SMBus control registers. When the device operates in Slave or Master Mode, the SMBus registers independently control each lane, and the EQB pin is converted to an AD3 input. See Table 4.				
VODB0 VODB1	53 54	I, 4-LEVEL, LVCMOS	VODB[1:0] controls the output amplitude of the B-channels. The pins are defined as VODB[1:0] only when ENSMB is de-asserted (low). Each of the four B-channels have the same level unless controlled by the SMBus control registers. When the device operates in Slave or Master Mode, the SMBus registers provide independent control of each lane, and VODB[1:0] pins are converted to AD0, AD1 inputs. See Table 5.				
VODA0 VODA1	49 50	I, 4-LEVEL, LVCMOS	VODA[1:0] controls the output amplitude of the A-channels. The pins are defined as VODA[1:0] only when ENSMB is de-asserted (low). Each of the four A-channels have the same level unless controlled by the SMBus control registers. When the device operates in Slave or Master Mode, the SMBus registers provide independent control of each lane and the VODA[1:0] pins are converted to SCL and SDA. See Table 5.				
AD2	47	I, LVCMOS	Reserved in Pin Mode (ENSMB = 0) This input must be tied via external 1 k Ω to GND.				
SD_TH	26	I, 4-LEVEL, LVCMOS	Controls the internal Signal Detect Status Threshold value when in Pin Mode and SMBus Slave Mode. This pin is to be used for system debugging only, as the signal detect threshold has no impact on the data path. See Table 3 for more information. For final designs, input can be left floating, tied via 1 k Ω to VDD (2.5 V mode) or VIN (3.3 V mode), or tied via 1 k Ω to GND.				
RESERVED2	21	I, 4-LEVEL, LVCMOS	Reserved Tie via external 1 k Ω to GND (External 1 k Ω to VDD (2.5 V mode) or VIN (3.3 V mode) is also acceptable).				

⁽³⁾ When READ_EN is asserted low, the device attempts to load EEPROM. If EEPROM cannot be loaded successfully, for example due to an invalid or blank hex file, the DS80PCI810 waits indefinitely in an unknown state where SMBus access is not possible. ALL_DONE pin remains high in this situation.



Pin Functions⁽¹⁾ (continued)

PIN NAME	PIN NUMBER	I/O, TYPE	DESCRIPTION		
RESERVED3	19	I, 4-LEVEL, LVCMOS	Reserved This input must be tied via external 1 k Ω to GND.		
CONTROL PINS — BOTH	PIN AND SMBUS	MODES (LVCMOS	3)		
RXDET	22	I, 4-LEVEL, LVCMOS	The RXDET pin controls the RX detection function. Depending on the input level, a 50 Ω or >50 k Ω termination to the power rail is enabled. Keep this input floating for normal PCIe operation. See Table 2.		
RESERVED1 23 I, 4-LEVEL, Reserved This input must be left floating.			110001100		
VDD_SEL 25 I, FLOAT		I, FLOAT	Controls the internal regulator Float = 2.5 V mode Tie to GND = 3.3 V mode See Figure 31.		
PWDN	52	I, LVCMOS	Tie High = Low power - Power Down Tie to GND = Normal Operation See Table 2.		
ALL_DONE	27	O, LVCMOS	Valid Register Load Status Output HIGH = External EEPROM load failed or incomplete LOW = External EEPROM load passed		
POWER					
VIN	24	Power	In 3.3 V mode, feed 3.3 V to VIN In 2.5 V mode, leave floating.		
GND	DAP	Power	Ground pad (DAP - die attach pad).		



6 Specifications

www.ti.com.cn

6.1 Absolute Maximum Ratings⁽¹⁾

over operating free-air temperature range (unless otherwise noted)

	MIN	MAX	UNIT
Supply Voltage (VDD to GND, 2.5 V Mode)	-0.5	+2.75	V
Supply Voltage (VIN to GND, 3.3 V Mode)	-0.5	+4.0	V
LVCMOS Input/Output Voltage	-0.5	+4.0	V
CML Input Voltage	-0.5	VDD + 0.5	V
CML Input Current	-30	+30	mA

^{(1) &}quot;Absolute Maximum Ratings" indicate limits beyond which damage to the device may occur, including inoperability and degradation of device reliability and performance. Functional operation of the device and/or non-degradation at the Absolute Maximum Ratings or other conditions beyond those indicated in the Recommended Operating Conditions is not implied. The Recommended Operating Conditions indicate conditions at which the device is functional and the device should not be operated beyond such conditions. Absolute Maximum Numbers are ensured for a junction temperature range of -40°C to +125°C. Models are validated to Maximum Operating Voltages only.

6.2 Handling Ratings

			MIN	MAX	UNIT	
T _{stg}			-40	125	°C	
T _{solder}				260	°C	
V	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins ⁽²⁾	-4000	4000	V	
V _(ESD)		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins (3)	-1000	1000	V	

- (1) For soldering specifications: See application note SNOA549.
- (2) JEDEC document JEP155 states that 4000-V HBM allows safe manufacturing with a standard ESD control process.
- (3) JEDEC document JEP157 states that 1000-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	NOM	MAX	UNIT
Supply Voltage (2.5 V mode) ⁽¹⁾	2.37 5	2.5	2.625	V
Supply Voltage (3.3 V mode) ⁽¹⁾	3.0	3.3	3.6	V
Ambient Temperature	-40		+85	°C
SMBus (SDA, SCL)			3.6	V
Supply Noise up to 50 MHz ⁽²⁾		100		mVp-p

- (1) DC plus AC power should not exceed these limits.
- (2) Allowed supply noise (mVp-p sine wave) under typical conditions.

6.4 Thermal Information

		DS80PCI810	
	THERMAL METRIC ⁽¹⁾	WQFN	UNIT
		54 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	26.6	
$R_{\theta JCtop}$	Junction-to-case (top) thermal resistance	10.8	
$R_{\theta JB}$	Junction-to-board thermal resistance	4.4	°C/W
ΨЈТ	Junction-to-top characterization parameter	0.2	30/00
ΨЈВ	Junction-to-board characterization parameter	4.3	
R _{0JCbot}	Junction-to-case (bottom) thermal resistance	1.5	

⁽¹⁾ For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.



6.5 Electrical Characteristics

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
POWER					<u>'</u>	
	Current Consumption, 2.5 V Mode	EQ = Level 4, VOD = Level 6 RXDET = 1, PWDN = 0		220	280	mA
I_{DD}	Current Consumption, 3.3 V Mode	EQ = Level 4, VOD = Level 6 RXDET = 1, PWDN = 0		220	280	mA
	Power Down Current Consumption	PWDN = 1		14	27	mA
V_{DD}	Integrated LDO Regulator	V _{IN} = 3.0 - 3.6 V	2.375	2.5	2.625	V
LVCMOS / LVTT	L DC SPECIFICATIONS					
$V_{\text{IH}25}$	High Level Input Voltage	2.5 V Supply Mode	1.7		V_{DD}	V
V _{IH33}	High Level Input Voltage	3.3 V Supply Mode	1.7		V_{IN}	V
V _{IL}	Low Level Input Voltage		0		0.7	V
V _{OH}	High Level Output Voltage (ALL_DONE pin)	I _{OH} = −4mA	2.0			V
V _{OL}	Low Level Output Voltage (ALL_DONE pin)	I _{OL} = 4mA			0.4	V
I _{IH}	Input High Current (PWDN pin)	V _{IN} = 3.6 V, LVCMOS = 3.6 V	-15		+15	μΑ
I _{IL}	Input Low Current (PWDN pin)	V _{IN} = 3.6 V, LVCMOS = 0 V	-15		+15	μΑ
4-LEVEL INPUT	DC SPECIFICATIONS					
I _{IH}	Input High Current with internal resistors (4–level input pin)	V _{IN} = 3.6 V, LVCMOS = 3.6 V	+20		+150	μΑ
I _{IL}	Input Low Current with internal resistors (4–level input pin)	V _{IN} = 3.6 V, LVCMOS = 0 V	-160		-40	μΑ
	Voltage Threshold from Pin Mode Level 0 to R			0.50		
	Voltage Threshold from Pin Mode Level R to F	V _{DD} = 2.5 V (2.5 V supply mode) Internal LDO Disabled See Table 1 for details		1.25		V
V	Voltage Threshold from Pin Mode Level F to 1	occ rasic rior details		2.00		
V_{TH}	Voltage Threshold from Pin Mode Level 0 to R			0.66		
	Voltage Threshold from Pin Mode Level R to F	V _{IN} = 3.3 V (3.3 V supply mode) Internal LDO Enabled See Table 1 for details.		1.65		V
	Voltage Threshold from Pin Mode Level F to 1	Coo rabio r ioi dotalio.		2.64		
CML RECEIVER	INPUTS (IN_n+, IN_n-)					
Z _{Rx-DIFF-DC}	Rx DC differential mode impedance	Tested at VDD = 2.5 V	80	100	120	Ω
$Z_{Rx\text{-DC}}$	Rx DC single ended impedance	Tested at VDD = 2.5 V	40	50	60	Ω
		SDD11 10 MHz		-19		
RL _{Rx-DIFF}	Rx Differential Input return loss	SDD11 2 GHz		-14		dB
		SDD11 6-11.1 GHz		-8		
RL _{Rx-CM}	Rx Common mode return loss	SCC11 0.05 - 5 GHz		-10		dB
V _{Rx-ASSERT-DIFF-P}	Signal detect assert level for active data signal	SD_TH = F (float), 1010 pattern at 12 Gbps		57		mVp-p
V _{Rx-DEASSERT-DIFF} PP	Signal detect de-assert for inactive signal level	SD_TH = F (float), 1010 pattern at 12 Gbps		44		mVp-p



Electrical Characteristics (continued)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
HIGH SPEED OU	TPUTS					
		SDD22 10 MHz - 2 GHz		-15		٩D
RL _{Tx-DIFF}	Tx Differential return loss	SDD22 5.5 GHz		-12		dB
		SDD22 11.1 GHz		-10		dB
RL _{Tx-CM}	Tx Common mode return loss	SCC22 50 MHz- 2.5 GHz		-8		dB
Z _{Tx-DIFF-DC}	DC differential Tx impedance			100		Ω
I _{Tx-SHORT}	Transmitter short circuit current limit	Total current when output is shorted to VDD or GND		20		mA
V _{Tx-CM-DC-LINE-} DELTA	Absolute delta of DC common mode voltage between Tx+ and Tx-				25	mV
V _{Tx-DIFF1-PP}	Output Voltage Differential Swing	Differential measurement with OUT_n+ and OUT_n-, AC-Coupled and terminated by 50 Ω to GND, Inputs AC-Coupled, Measured with 8T Pattern at 12 Gbps ⁽¹⁾ VID = 600 mVp-p VOD = Level 6 ⁽²⁾ (3)		615		mVp-p
V _{Tx-DIFF2-PP}	Output Voltage Differential Swing	Differential measurement with OUT_n+ and OUT_n-, AC-Coupled and terminated by 50 Ω to GND, Inputs AC-Coupled, Measured with 8T Pattern at 12 Gbps ⁽¹⁾ VID = 1000 mVp-p VOD = Level $6^{(2)(3)}$		950		mVp-p
V _{Tx-DIFF3-PP}	Output Voltage Differential Swing	Differential measurement with OUT_n+ and OUT_n-, AC-Coupled and terminated by 50Ω to GND, Inputs AC-Coupled, Measured with 8T Pattern at 12 Gbps ⁽¹⁾ VID = 1200 mVp-p VOD = Level $6^{(2)(3)}$		1100		mVp-p
T _{PDEQ}	Differential propagation delay	EQ = Level 1 to Level 4		80		ps
V _{Tx-CM-AC-PP}	AC common mode voltage	EQ = Level 4, VOD = Level 6, PRBS-7, 8 Gbps Measured over >10 ⁶ bits using a low pass filter with a -3 dB corner frequency at 4 GHz ⁽⁴⁾		20		mVp-p
V _{DISABLE-OUT}	Tx disable output voltage	Driver disabled via PWDN		1		mVp-p
V _{Tx-IDLE-DIFF-AC-p}	Tx idle differential peak output voltage	Driver enabled, EQ = Level 4, VOD = Level 7 (Max) ⁽⁵⁾		8		mV
T _{Tx-IDLE-SET-TO-} IDLE	Time to transition to idle after differential signal	VID = 1.0 Vp-p, 1.5 Gbps		0.70		ns
T _{Tx-IDLE-TO-DIFF-} DATA	Time to transition to valid differential signal after idle	VID = 1.0 Vp-p, 1.5 Gbps		0.04		ns

^{(1) 8}T pattern is defined as a 1111111100000000'b pattern bit sequence.

ATE measurements for production are tested at DC.

In PCIe applications, the output VOD level is not fixed. It adjusts automatically based on the VID input amplitude level. The output VOD level set by VODA/B[1:0] depends on the VID level and the frequency content. The DS80PCI810 repeater is designed to be transparent in this mode, so the Tx-FIR (de-emphasis) is passed to the Rx to support the handshake negotiation link training.

Tx Common Mode AC noise decreases at lower levels of EQ gain.

⁽⁵⁾ Tested with a valid idle signal on the input with peak differential voltage of 6 mV.

TEXAS INSTRUMENTS

Electrical Characteristics (continued)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
RJ _{ADD}	Additive Random Jitter	Evaluation Module (EVM) Only, FR4, VID = 800 mVp-p, EQ = Level 1 PRBS15, 12 Gbps VOD = Level 6 All other channels active (6)		0.36		ps rms
EQUALIZATION						
DJE1	Residual deterministic jitter at 6 Gbps	5" Differential Stripline, 5mil trace width, FR4, VID = 800 mVp-p, PRBS15, EQ = Level 2, VOD = Level 6		0.06		Ulp-p
DJE2	Residual deterministic jitter at 12 Gbps	5" Differential Stripline, 5mil trace width, FR4, VID = 800 mVp-p, PRBS15, EQ = Level 2, VOD = Level 6		0.12		Ulp-p

⁽⁶⁾ Additive random jitter is given in RMS value by the following equation: RJ_{ADD} = √[(Output Jitter)² - (Input Jitter)²]. Typical input jitter for these measurements is 150 fs rms.

6.6 Electrical Characteristics — Serial Management Bus Interface

Over recommended operating supply and temperature ranges unless other specified.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SERIAL BU	JS INTERFACE DC SPECIFICATIONS					
V _{IL}	Data, Clock Input Low Voltage				0.8	V
V _{IH}	Data, Clock Input High Voltage		2.1		3.6	V
V _{OL}	Output Low Voltage	SDA or SCL, I _{OL} = 1.25 mA	0		0.36	V
V_{DD}	Nominal Bus Voltage		2.375		3.6	V
I _{IH-Pin}	Input Leakage Per Device Pin		+20		+150	μΑ
I _{IL-Pin}	Input Leakage Per Device Pin		-160		-40	μΑ
C _I	Capacitance for SDA and SCL	See ⁽¹⁾⁽²⁾		< 5		pF
	External Termination Resistance	Pullup $V_{DD} = 3.3 V^{(1)(2)(3)}$		2000		Ω
R _{TERM}	pull to $V_{DD} = 2.5 \text{ V} \pm 5\% \text{ OR } 3.3 \text{ V} \pm 10\%$	Pullup $V_{DD} = 2.5 V^{(1)(2)(3)}$		1000		Ω

⁽¹⁾ Recommended value.

6.7 Timing Requirements Serial Bus Interface

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT					
SERIAL BUS INTERFACE TIMING SPECIFICATIONS											
_	Due Operating Fraguency	ENSMB = VDD (Slave Mode)			400	kHz					
F _{SMB}	Bus Operating Frequency	ENSMB = FLOAT (Master Mode)	280	400	520	kHz					
t _{FALL}	SCL or SDA Fall Time	Read operation RPU = 4.7 kΩ, Cb < 50 pF		60		ns					
t _{RISE}	SCL or SDA Rise Time	Read operation RPU = 4.7 kΩ, Cb < 50 pF		140		ns					
t _F	Clock/Data Fall Time	See ⁽¹⁾			300	ns					
t _R	Clock/Data Rise Time	See ⁽¹⁾			1000	ns					
t _{POR}	Time in which a device must be operational after power-on reset	See ⁽¹⁾			500	ms					

Compliant to SMBus 2.0 physical layer specification. See System Management Bus (SMBus) Specification Version 2.0, section 3.1.1 SMBus common AC specifications for details.

⁽²⁾ Recommended maximum capacitance load per bus segment is 400 pF.

⁽³⁾ Maximum termination voltage should be identical to the device supply voltage.

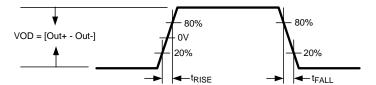


Figure 1. Output Rise And Fall Transition Time

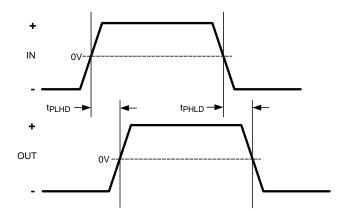


Figure 2. Propagation Delay Timing Diagram

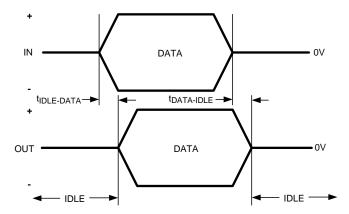


Figure 3. Transmit Idle-Data and Data-Idle Response Time

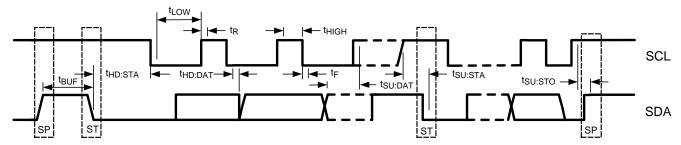
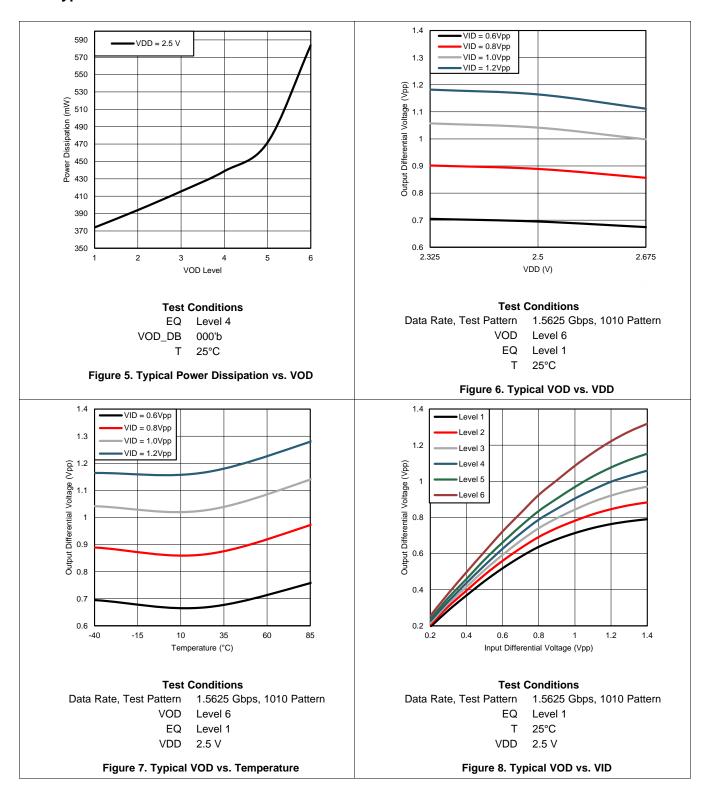


Figure 4. SMBus Timing Parameters

TEXAS INSTRUMENTS

6.8 Typical Characteristics





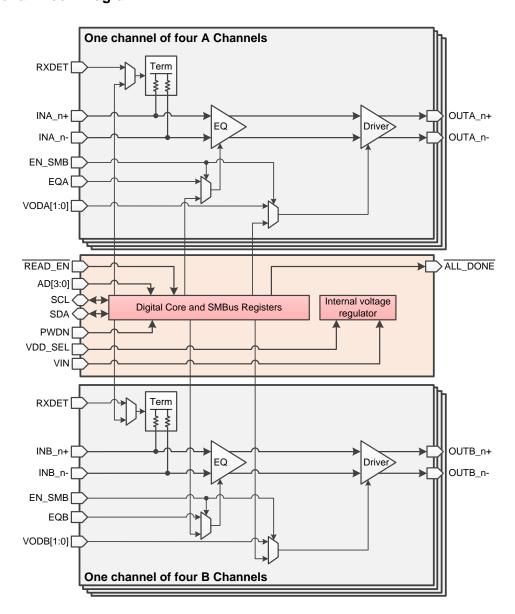
7 Detailed Description

7.1 Overview

www.ti.com.cn

The DS80PCI810 provides linear equalization for lossy printed circuit board backplanes and balanced cables. The DS80PCI810 operates in three modes: Pin Control Mode (ENSMB = 0), SMBus Slave Mode (ENSMB = 1), and SMBus Master Mode (ENSMB = Float) to load register information from external EEPROM.

7.2 Functional Block Diagram



7.2.1 Functional Datapath Blocks

In an increasing number of high speed applications, transparency between Tx and Rx endpoints is essential to ensure high signal integrity. The DS80PCl810 channel datapath uses one gain stage input equalization coupled with a linear output driver. This combination provides a high level of transparency, thereby achieving greater drive distance in PCle applications where Rx-Tx auto-negotiation and link-training are required. Refer to the *Typical Applications* section for more application information regarding recommended settings and placement.

7.3 Feature Description

The 4-level input pins use a resistor divider to set the four valid control levels and provide a wider range of control settings when ENSMB = 0. There is an internal 30 k Ω pull-up and a 60 k Ω pull-down connected to the package pin. These resistors, together with the external resistor connection, combine to achieve the desired voltage level. By using the 1 k Ω pull-down, 20 k Ω pull-down, no connect, and 1 k Ω pull-up, the optimal voltage levels for each of the four input states are achieved as shown in Table 1.

Table 1. 4-Level Control Pin Settings

		Resulting Pin Voltage				
LEVEL	SETTING	3.3-V MODE	2.5-V MODE			
0	Tie 1 kΩ to GND	0.10 V	0.08 V			
R	Tie 20 kΩ to GND	1/3 x V _{IN}	1/3 x V _{DD}			
F	Float (leave pin open)	2/3 x V _{IN}	2/3 x V _{DD}			
1	Tie 1 kΩ to V_{IN} or V_{DD}	V _{IN} - 0.05 V	V _{DD} - 0.04 V			

7.3.1 Typical 4-Level Input Thresholds

- Internal Threshold between 0 and R = 0.2 * V_{IN} or V_{DD}
- Internal Threshold between R and F = $0.5 * V_{IN}$ or V_{DD}
- Internal Threshold between F and 1 = 0.8 * V_{IN} or V_{DD}

In order to minimize the startup current associated with the integrated 2.5 V regulator, the 1 k Ω pull-up / pull-down resistors are recommended. If several 4-level inputs require the same setting, it is possible to combine two or more 1 k Ω resistors into a single lower value resistor. As an example, combining two inputs with a single 500 Ω resistor is a valid way to save board space.

7.4 Device Functional Modes

7.4.1 Pin Control Mode:

When in Pin Mode (ENSMB = 0), equalization and VOD (output amplitude) can be selected via pin control for both the A-channels and B-channels per Table 4 and Table 5. The RXDET pin provides either automatic or manual control for input termination (50 Ω or > 50 k Ω to VDD). The receiver electrical signal detect status threshold is adjustable via the SD_TH pin. By setting signal-detect threshold level via the SD_TH pin, status information about a valid signal detect assert/de-assert can be read back via SMBus registers. Pin control mode is ideal in situations where neither MCU or EEPROM is available to access the device via SMBus SDA/SCL lines.

7.4.2 Slave SMBus Mode:

When in Slave SMBus Mode (ENSMB = 1), the VOD (output amplitude), equalization, and termination disable features are all programmable on an individual channel basis, rather than in collective A-channel and B-channel groups. Upon assertion of ENSMB, the EQx and VODx settings are controlled by SMBus immediately. It is important to note that SMBus settings can only be changed from their defaults after asserting Register Enable by setting Reg 0x06[3] = 1. The EQx and VODx pins are subsequently converted to AD0-AD3 SMBus address inputs. The other external control pins (RXDET and SD_TH) remain active unless their respective registers are written to and the appropriate override bit is set. If the user overrides a pin control, the input voltage level of that control pin is ignored until ENSMB is driven low (Pin Mode). In the event that channels are powered down via the PWDN pin, the state of all register settings are not affected.



Device Functional Modes (continued)

Table 2. RX Detect Settings

PWDN ⁽¹⁾ (Pin 52)	RXDET (Pin 22)	SMBus REG Bit[3:2]	INPUT TERMINATION	RECOMMENDED USE	COMMENTS
0	0	00	Hi-Z		Manual Rx-Detect, input is Hi-Z
0	R	01	Pre Detect: Hi-Z Post Detect: 50 Ω	PCle	Auto Rx-Detect, outputs test every 12 ms for 600 ms then stops; termination is Hi-Z until Rx detection; once detected input termination is 50 Ω Reset function by pulsing PWDN high for 5 μs then low again
0	F (Default)	10	Pre Detect: Hi-Z Post Detect: 50 Ω	PCIe	Auto Rx-Detect, outputs test every 12 ms until detection occurs; termination is Hi-Z until Rx detection; once detected input termination is 50 Ω
0	1	11	50 Ω		Manual Rx-Detect, input is 50 Ω
1	X	×	Hi-Z		Power Down mode, input is Hi-Z, output drivers are disabled
1	X	^	111-2		Used to reset Rx-Detect State Machine when held high for 5 μs

⁽¹⁾ In SMBus Slave Mode, the Rx Detect State Machine can be manually reset in software by overriding the device PRSNT function. This is accomplished by setting the Override PRSNT bit (Reg 0x02[7]) and then toggling the PRSNT value bit (Reg 0x02[6]). See Table 9 for more information about resetting the Rx Detect State Machine.

Table 3. Signal Detect Status Threshold Level (1)(2)

LEVEL	SD_TH (PIN 26)	SMBus REG BIT[3:2] and[1:0]		ERT LEVEL /p-p)	[1:0] DE-ASSERT LEVEL (mVp-p)		
			3 Gbps 12 Gbps		3 Gbps	12 Gbps	
1	0	10	18	75	14	55	
2	R	01	12	40	8	22	
3	F (default)	00	15	50	11	37	
4	1	11	16	58	12	45	

⁽¹⁾ VDD = 2.5 V, 25°C, 1010 pattern at 1.5 Gbps and 101010 pattern at 12 Gbps

7.4.3 SMBus Master Mode

When in SMBus Master Mode (ENSMB = Float), the VOD (output amplitude), equalization, and termination disable features for multiple devices can be loaded via external EEPROM. By asserting a Float condition on the ENSMB pin, an external EEPROM writes register settings to each device in accordance with its SMBus slave address. The settings programmable by external EEPROM provide only a subset of all the register bits available via SMBus Slave Mode, and the bit-mapping between SMBus Slave Mode registers and EEPROM addresses can be referenced in Table 6. Once the EEPROM successfully finishes loading each device's register settings, the device reverts back to SMBus Slave Mode and releases SDA/SCL control to an external master MCU. If the EEPROM fails to load settings to a particular device, for example due to an invalid or blank hex file, the device waits indefinitely in an unknown state where access to the SMBus lines is not possible.

7.4.4 Signal Conditioning Settings

Equalization and VOD settings accessible via the pin controls are chosen to meet the needs of most high speed applications. These settings can also be controlled via the SMBus registers. Each pin input has a total of four possible voltage level settings. Table 4 and Table 5 show both the Pin Mode and SMBus Mode settings that are used in order to program the equalization and VOD gain for each DS80PCI810 channel.

⁽²⁾ Signal detect status threshold sets the value at which a signal detect status is flagged via SMBus Reg 0x0A. Regardless of the threshold level, the output always remains enabled unless manually powered down.



Table 4. Equalizer Settings (1)(2)

	EQUALIZATION BOOST RELATIVE TO DC										
LEVEL	EQA ⁽³⁾ EQB	EQ - 8 bits[7:0]	dB at 1.5 GHz	dB at 2.5 GHz	dB at 4 GHz						
1	0	xxxx xx00 = 0x00	2.1	2.5	2.7						
2	R	xxxx xx01 = 0x01	4.0	5.1	6.4						
3	F	xxxx xx10 = 0x02	5.5	7.0	8.3						
4	1	xxxx xx11 = 0x03	6.8	8.3	9.5						

- Optimal EQ setting should be determined via simulation and prototype verification.
- Equalization boost values are inclusive of package loss. To program EQ Level 1-4 correctly in Pin Mode, RESERVED3 and AD2 pins must be tied via 1 k Ω resistor to GND.

Table 5. Output Voltage Settings⁽¹⁾

LEVEL	VODA1 VODB1	VODA0 VODB0	VOD - 3 bits[2:0]	VOD_DB - 3 bits[2:0]	VID Vp-p	VOD/VID Ratio ⁽¹⁾
			000'b	000'b	1.2	0.57 ⁽²⁾
1	0	0	001'b	000'b	1.2	0.65
2	0	R	010'b	000'b	1.2	0.71
3	0	1	011'b	000'b	1.2	0.77
4	R	F	100'b	000'b	1.2	0.83
5	F	R	101'b	000'b	1.2	0.90
6	1	0	110'b	000'b	1.2	1.00
			111'b	000'b	1.2	1.04 ⁽²⁾⁽³⁾

⁽¹⁾ For PCIe operation, it is important to keep the output amplitude and dynamic range as large as possible. When operating in Pin Mode, it is recommended to use VODA[1:0] = VODB[1:0] = Level 6. In SMBus Mode, it is also recommended to use Level 6 (that is, VOD = 110'b and $VOD_DB = 000$ 'b).

- These VOD settings are only accessible via SMBus Modes.
- (3) VOD = 111'b setting in SMBus Mode is not recommended.



7.5 Programming

www.ti.com.cn

The DS80PCI810 device supports reading directly from an external EEPROM device by implementing SMBus Master Mode. When using SMBus Master Mode, the DS80PCI810 reads directly from specific location in the external EEPROM. When designing a system for using the external EEPROM, the user must follow these specific guidelines.

- Maximum EEPROM size is 8K (1024 x 8-bit).
- Set ENSMB = Float enable the SMBus Master Mode.
- The external EEPROM device address byte must be 0xA0 and capable of 1 MHz operation at 2.5 V and 3.3 V supply.
- Set the AD[3:0] inputs for SMBus address byte. When the AD[3:0] = 0000'b, the device address byte is 0xB0.

When tying multiple DS80PCI810 devices to the SDA and SCL bus, use these guidelines to configure the devices:

- Use SMBus AD[3:0] address bits so that each device can load its configuration from the EEPROM. Example
 below is for four devices. The first device in the sequence is conventionally address 0xB0, while subsequent
 devices follow the address order listed below.
 - U1: AD[3:0] = 0000 = 0xB0,
 - U2: AD[3:0] = 0001 = 0xB2,
 - U3: AD[3:0] = 0010 = 0xB4,
 - U4: AD[3:0] = 0011 = 0xB6
- Use a pull-up resistor on SDA and SCL; value = 2 kΩ to 5 kΩ
- Daisy-chain READ_EN (Pin 26) and ALL_DONE (Pin 27) from one device to the next device in the sequence so that they do not compete for the EEPROM at the same time.
 - 1. Tie READ EN of the first device in the chain (U1) to GND.
 - 2. Tie ALL DONE of U1 to READ EN of U2.
 - 3. Tie ALL_DONE of U2 to READ_EN of U3.
 - 4. Tie ALL DONE of U3 to READ EN of U4.
 - 5. Optional: Tie ALL_DONE output of U4 to a LED to show the devices have been loaded successfully.

Once the ALL_DONE status pin of the last device is flagged to indicate that all devices sharing the SMBus line have been successfully programmed, control of the SMBus line is released by the repeater and the device reverts back to SMBus Slave Mode. At this point, an external MCU can perform any additional Read or Write operations.

Below is an example of a 2 kbits (256 x 8-bit) EEPROM in hex format for the DS80PCI810 device. The first three bytes of the EEPROM always contain a base header common and necessary to control initialization of all devices connected to the I2C bus. The CRC enable flag is used to enable or disable CRC checking. If CRC checking is disabled, the CRC byte in each device's address map header is ignored to simplify control. There is a MAP bit to flag the presence of an address map that specifies the configuration data start address in the EEPROM. If the MAP bit is not present, the configuration data start address is assumed to follow the base header directly. Lastly, one bit in the base header is used to indicate whether EEPROM size > 256 bytes. This bit ensures that EEPROM slot addresses are formatted properly as one byte (EEPROM \leq 256 bytes) or two bytes (EEPROM > 256 bytes) for subsequent address map headers. There are 37 bytes of data for each DS80PCI810 device.

Note: The maximum EEPROM size supported is 8 kbits (1024 x 8 bits).

7.5.1 EEPROM Address Map for Single Device

A detailed EEPROM Address Map for a single device is shown in Table 6. For instances where multiple devices are written to EEPROM, the device starting address definitions align starting with Table 6 Address 0x03.

ZHCSCW4 – OCTOBER 2014

TEXAS INSTRUMENTS

EEPROM A	Address	s Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description		0x00	CRC_EN	Address Map Present	EEPROM > 256 Bytes	Reserved	DEVICE COUNT[3]	DEVICE COUNT[2]	DEVICE COUNT[1]	DEVICE COUNT[0]
Default Value	0x00	0,000	0	0	0	0	0	0	0	0
Description			Reserved							
Default Value	0x00	0x01	0	0	0	0	0	0	0	0
Description		0x02	Max EEPROM Burst size[7]	Max EEPROM Burst size[6]	Max EEPROM Burst size[5]	Max EEPROM Burst size[4]	Max EEPROM Burst size[3]	Max EEPROM Burst size[2]	Max EEPROM Burst size[1]	Max EEPROM Burst size[0]
Default Value	0x00	0.02	0	0	0	0	0	0	0	0
Description			PWDN_CH7	PWDN_CH6	PWDN_CH5	PWDN_CH4	PWDN_CH3	PWDN_CH2	PWDN_CH1	PWDN_CH0
SMBus Reg	jister	0x03	0x01[7]	0x01[6]	0x01[5]	0x01[4]	0x01[3]	0x01[2]	0x01[1]	0x01[0]
Default Value	0x00	OXOC	0	0	0	0	0	0	0	0
Description			Reserved	Reserved	Reserved	Reserved	Ovrd_PWDN	Reserved	Reserved	Reserved
SMBus Reg	jister	0x04	0x02[5]	0x02[4]	0x02[3]	0x02[2]	0x02[0]	0x04[7]	0x04[6]	0x04[5]
Default Value	0x00		0	0	0	0	0	0	0	0
Description			Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Ovrd_SD_TH	Reserved
SMBus Reg	jister	0x05	0x04[4]	0x04[3]	0x04[2]	0x04[1]	0x04[0]	0x06[4]	0x08[6]	0x08[5]
Default Value	0x04		0	0	0	0	0	1	0	0
Description			Reserved	Ovrd_RXDET	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
SMBus Reg	jister	0x06	0x08[4]	0x08[3]	0x08[2]	0x08[1]	0x08[0]	0x0B[6]	0x0B[5]	0x0B[4]
Default Value	0x07	0,100	0	0	0	0	0	1	1	1
Description			Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	CH0_RXDET_1	CH0_RXDET_0
SMBus Reg	jister	0x07	0x0B[3]	0x0B[2]	0x0B[1]	0x0B[0]	0x0E[5]	0x0E[4]	0x0E[3]	0x0E[2]
Default Value	0x00		0	0	0	0	0	0	0	0
Description			Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	CH0_EQ_1	CH0_EQ_0
SMBus Reg	jister	0x08	0x0F[7]	0x0F[6]	0x0F[5]	0x0F[4]	0x0F[3]	0x0F[2]	0x0F[1]	0x0F[0]
Default Value	0x2F	3,00	0	0	1	0	1	1	1	1



EEPROM Address	Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description		CH0_SCP	Reserved	Reserved	Reserved	Reserved	CH0_VOD_2	CH0_VOD_1	CH0_VOD_0
SMBus Register	0x09	0x10[7]	0x10[6]	0x10[5]	0x10[4]	0x10[3]	0x10[2]	0x10[1]	0x10[0]
Default Value 0xAD		1	0	1	0	1	1	0	1
Description		CH0_VOD_DB_2	CH0_VOD_DB_1	CH0_VOD_DB_0	Reserved	CH0_THa_1	CH0_THa_0	CH0_THd_1	CH0_THd_0
SMBus Register	0x0A	0x11[2]	0x11[1]	0x11[0]	0x12[7]	0x12[3]	0x12[2]	0x12[1]	0x12[0]
Default Value 0x40	OXO/ C	0	1	0	0	0	0	0	0
Description		Reserved	Reserved	CH1_RXDET_1	CH1_RXDET_0	Reserved	Reserved	Reserved	Reserved
SMBus Register	0x0B	0x15[5]	0x15[4]	0x15[3]	0x15[2]	0x16[7]	0x16[6]	0x16[5]	0x16[4]
Default Value 0x02	ОХОВ	0	0	0	0	0	0	1	0
Description		Reserved	Reserved	CH1_EQ_1	CH1_EQ_0	CH1_SCP	Reserved	Reserved	Reserved
SMBus Register	0x0C	0x16[3]	0x16[2]	0x16[1]	0x16[0]	0x17[7]	0x17[6]	0x17[5]	0x17[4]
Default Value 0xFA		1	1	1	1	1	0	1	0
Description		Reserved	CH1_VOD_2	CH1_VOD_1	CH1_VOD_0	CH1_VOD_DB_2	CH1_VOD_DB_1	CH1_VOD_DB_0	Reserved
SMBus Register	0x0D	0x17[3]	0x17[2]	0x17[1]	0x17[0]	0x18[2]	0x18[1]	0x18[0]	0x19[7]
Default Value 0xD4	0.02	1	1	0	1	0	1	0	0
Description		CH1_THa_1	CH1_THa_0	CH1_THd_1	CH1_THd_0	Reserved	Reserved	CH2_RXDET_1	CH2_RXDET_0
SMBus Register	0x0E	0x19[3]	0x19[2]	0x19[1]	0x19[0]	0x1C[5]	0x1C[4]	0x1C[3]	0x1C[2]
Default Value 0x00		0	0	0	0	0	0	0	0
Description		Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	CH2_EQ_1	CH2_EQ_0
SMBus Register	0x0F	0x1D[7]	0x1D[6]	0x1D[5]	0x1D[4]	0x1D[3]	0x1D[2]	0x1D[1]	0x1D[0]
Default Value 0x2F	3,01	0	0	1	0	1	1	1	1
Description		CH2_SCP	Reserved	Reserved	Reserved	Reserved	CH2_VOD_2	CH2_VOD_1	CH2_VOD_0
SMBus Register	0x10	0x1E[7]	0x1E[6]	0x1E[5]	0x1E[4]	0x1E[3]	0x1E[2]	0x1E[1]	0x1E[0]
Default Value 0xAD	0,10	1	0	1	0	1	1	0	1
L		1	1	1	1	1	1	1	1



EEPROM A	Address	Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description			CH2_VOD_DB_2	CH2_VOD_DB_1	CH2_VOD_DB_0	Reserved	CH2_THa_1	CH2_THa_0	CH2_THd_1	CH2_THd_0
SMBus Reg	ister	0x11	0x1F[2]	0x1F[1]	0x1F[0]	0x20[7]	0x20[3]	0x20[2]	0x20[1]	0x20[0]
Default Value	0x40	OX11	0	1	0	0	0	0	0	0
Description			Reserved	Reserved	CH3_RXDET_1	CH3_RXDET_0	Reserved	Reserved	Reserved	Reserved
SMBus Reg	ister	0x12	0x23[5]	0x23[4]	0x23[3]	0x23[2]	0x24[7]	0x24[6]	0x24[5]	0x24[4]
Default Value	0x02		0	0	0	0	0	0	1	0
Description			Reserved	Reserved	CH3_EQ_1	CH3_EQ_0	CH3_SCP	Reserved	Reserved	Reserved
SMBus Reg	ister	0x13	0x24[3]	0x24[2]	0x24[1]	0x24[0]	0x25[7]	0x25[6]	0x25[5]	0x25[4]
Default Value	0xFA	0.10	1	1	1	1	1	0	1	0
Description			Reserved	CH3_VOD_2	CH3_VOD_1	CH3_VOD_0	CH3_VOD_DB_2	CH3_VOD_DB_1	CH3_VOD_DB_0	Reserved
SMBus Reg	ister	0x14	0x25[3]	0x25[2]	0x25[1]	0x25[0]	0x26[2]	0x26[1]	0x26[0]	0x27[7]
Default Value	0xD4	OXIT	1	1	0	1	0	1	0	0
Description			CH3_THa_1	CH3_THa_0	CH3_THd_1	CH3_THd_0	Reserved	hi_idle_SD CH0-3	hi_idle_SD CH4-7	fast_SD CH0-3
SMBus Reg	ister	0x15	0x27[3]	0x27[2]	0x27[1]	0x27[0]	0x28[6]	0x28[5]	0x28[4]	0x28[3]
Default Value	0x09		0	0	0	0	1	0	0	1
Description			fast_SD CH4-7	lo_gain_SD CH0-3	lo_gain_SD CH4-7	Reserved	Reserved	CH4_RXDET_1	CH4_RXDET_0	Reserved
SMBus Reg	ister	0x16	0x28[2]	0x28[1]	0x28[0]	0x2B[5]	0x2B[4]	0x2B[3]	0x2B[2]	0x2C[7]
Default Value	0x80	0.00	1	0	0	0	0	0	0	0
Description			Reserved	Reserved	Reserved	Reserved	Reserved	CH4_EQ_1	CH4_EQ_0	CH4_SCP
SMBus Reg	ister	0x17	0x2C[6]	0x2C[5]	0x2C[4]	0x2C[3]	0x2C[2]	0x2C[1]	0x2C[0]	0x2D[7]
Default Value	0x5F	0.17	0	1	0	1	1	1	1	1
Description			Reserved	Reserved	Reserved	Reserved	CH4_VOD_2	CH4_VOD_1	CH4_VOD_0	CH4_VOD_DB_2
SMBus Reg	ister	0x18	0x2D[6]	0x2D[5]	0x2D[4]	0x2D[3]	0x2D[2]	0x2D[1]	0x2D[0]	0x2E[2]
Default Value	0x5A	5,10	0	1	0	1	1	0	1	0



EEPROM .	Address	Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description			CH4_VOD_DB_1	CH4_VOD_DB_0	Reserved	CH4_THa_1	CH4_THa_0	CH4_THd_1	CH4_THd_0	Reserved
SMBus Reg	gister	0x19	0x2E[1]	0x2E[0]	0x2F[7]	0x2F[3]	0x2F[2]	0x2F[1]	0x2F[0]	0x32[5]
Default Value	0x80	0.10	1	0	0	0	0	0	0	0
Description			Reserved	CH5_RXDET_1	CH5_RXDET_0	Reserved	Reserved	Reserved	Reserved	Reserved
SMBus Reg	gister	0x1A	0x32[4]	0x32[3]	0x32[2]	0x33[7]	0x33[6]	0x33[5]	0x33[4]	0x33[3]
Default Value	0x05	OXIII	0	0	0	0	0	1	0	1
Description			Reserved	CH5_EQ_1	CH5_EQ_0	CH5_SCP	Reserved	Reserved	Reserved	Reserved
SMBus Reg	gister	0x1B	0x33[2]	0x33[1]	0x33[0]	0x34[7]	0x34[6]	0x34[5]	0x34[4]	0x34[3]
Default Value	0xF5	OXID	1	1	1	1	0	1	0	1
Description			CH5_VOD_2	CH5_VOD_1	CH5_VOD_0	CH5_VOD_DB_2	CH5_VOD_DB_1	CH5_VOD_DB_0	Reserved	CH5_THa_1
SMBus Reg	gister	0x1C	0x34[2]	0x34[1]	0x34[0]	0x35[2]	0x35[1]	0x35[0]	0x36[7]	0x36[3]
Default Value	0xA8	0.10	1	0	1	0	1	0	0	0
Description	l		CH5_THa_0	CH5_THd_1	CH5_THd_0	Reserved	Reserved	CH6_RXDET_1	CH6_RXDET_0	Reserved
SMBus Re	gister	0x1D	0x36[2]	0x36[1]	0x36[0]	0x39[5]	0x39[4]	0x39[3]	0x39[2]	0x3A[7]
Default Value	0x00	02	0	0	0	0	0	0	0	0
Description			Reserved	Reserved	Reserved	Reserved	Reserved	CH6_EQ_1	CH6_EQ_0	CH6_SCP
SMBus Reg	gister	0x1E	0x3A[6]	0x3A[5]	0x3A[4]	0x3A[3]	0x3A[2]	0x3A[1]	0x3A[0]	0x3B[7]
Default Value	0x5F	OXIL	0	1	0	1	1	1	1	1
Description			Reserved	Reserved	Reserved	Reserved	CH6_VOD_2	CH6_VOD_1	CH6_VOD_0	CH6_VOD_DB_2
SMBus Reg	gister	0x1F	0x3B[6]	0x3B[5]	0x3B[4]	0x3B[3]	0x3B[2]	0x3B[1]	0x3B[0]	0x3C[2]
Default Value	0x5A	OXII	0	1	0	1	1	0	1	0
Description			CH6_VOD_DB_1	CH6_VOD_DB_0	Reserved	CH6_THa_1	CH6_THa_0	CH6_THd_1	CH6_THd_0	Reserved
SMBus Reg	gister	0x20	0x3C[1]	0x3C[0]	0x3D[7]	0x3D[3]	0x3D[2]	0x3D[1]	0x3D[0]	0x40[5]
Default Value	0x80	0,20	1	0	0	0	0	0	0	0



EEPROM Address	Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description		Reserved	CH7_RXDET_1	CH7_RXDET_0	Reserved	Reserved	Reserved	Reserved	Reserved
SMBus Register	0x21	0x40[4]	0x40[3]	0x40[2]	0x41[7]	0x41[6]	0x41[5]	0x41[4]	0x41[3]
Default Value 0x05	OX21	0	0	0	0	0	1	0	1
Description		Reserved	CH7_EQ_1	CH7_EQ_0	CH7_SCP	Reserved	Reserved	Reserved	Reserved
SMBus Register	0x22	0x41[2]	0x41[1]	0x41[0]	0x42[7]	0x42[6]	0x42[5]	0x42[4]	0x42[3]
Default Value 0xF5	OXLL	1	1	1	1	0	1	0	1
Description		CH7_VOD_2	CH7_VOD_1	CH7_VOD_0	CH7_VOD_DB_2	CH7_VOD_DB_1	CH7_VOD_DB_0	Reserved	CH7_THa_1
SMBus Register	0x23	0x42[2]	0x42[1]	0x42[0]	0x43[2]	0x43[1]	0x43[0]	0x44[7]	0x44[3]
Default Value 0xA8	0x23		0	1	0	1	0	0	0
Description		CH7_THa_0	CH7_THd_1	CH7_THd_0	Reserved	Reserved	Reserved	Reserved	Reserved
SMBus Register	0x24	0x44[2]	0x44[1]	0x44[0]	0x47[3]	0x47[2]	0x47[1]	0x47[0]	0x48[7]
Default Value 0x00	σ <i>λ</i> .Σ .	0	0	0	0	0	0	0	0
Description		Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
SMBus Register	0x25	0x48[6]	0x4C[7]	0x4C[6]	0x4C[5]	0x4C[4]	0x4C[3]	0x4C[0]	0x59[0]
Default Value 0x00	UNZU	0	0	0	0	0	0	0	0
Description		Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
SMBus Register	0x26	0x5A[7]	0x5A[6]	0x5A[5]	0x5A[4]	0x5A[3]	0x5A[2]	0x5A[1]	0x5A[0]
Default Value 0x54	UNZU	0	1	0	1	0	1	0	0
Description		Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
SMBus Register	0x27	0x5B[7]	0x5B[6]	0x5B[5]	0x5B[4]	0x5B[3]	0x5B[2]	0x5B[1]	0x5B[0]
Default Value 0x54	UNZI	0	1	0	1	0	1	0	0

Table 7. Example Of EEPROM For Four Devices Using Two Address Maps

EEPROM Address	Address (Hex)	EEPROM Data	Comments
0	00	0x43	CRC_EN = 0, Address Map = 1, >256 bytes = 0, Device Count[3:0] = 3
1	01	0x00	
2	02	0x10	EEPROM Burst Size
3	03	0x00	CRC not used
4	04	0x0B	Device 0 Address Location
5	05	0x00	CRC not used
6	06	0x0B	Device 1 Address Location
7	07	0x00	CRC not used
8	08	0x30	Device 2 Address Location
9	09	0x00	CRC not used
10	0A	0x30	Device 3 Address Location
11	0B	0x00	Begin Device 0, 1 - Address Offset 3
12	0C	0x00	
13	0D	0x04	
14	0E	0x07	
15	0F	0x00	
16	10	0x01	EQ CHB0 = 0x01
17	11	0xAD	VOD CHB0 = 101'b
18	12	0x00	VOD_DB CHB0 = 000'b
19	13	0x00	_
20	14	0x1A	EQ CHB1 = 0x01
21	15	0xD0	VOD CHB1 = 101'b, VOD_DB CHB1 = 000'b
22	16	0x00	
23	17	0x01	EQ CHB2 = 0x01
24	18	0xAD	VOD CHB2 = 101'b
25	19	0x00	VOD_DB CHB2 = 000'b
26	1A	0x00	_
27	1B	0x1A	EQ CHB3 = 0x01
28	1C	0xD0	VOD CHB3 = 101'b, VOD_DB CHB3 = 000'b
29	1D	0x09	Signal Detect Status Threshold Control
30	1E	0x80	Signal Detect Status Threshold Control
31	1F	0x07	EQ CHA0 = 0x03
32	20	0x5C	VOD CHA0 = 110'b
33	21	0x00	VOD_DB CHA0 = 000'b
34	22	0x00	
35	23	0x15	EQ CHA1 = 0x00
36	24	0xC0	VOD CHA1 = 110'b, VOD_DB CHA1 = 000'b
37	25	0x00	, = 1
38	26	0x07	EQ CHA2 = 0x03
39	27	0x5C	VOD CHA2 = 110'b
40	28	0x00	VOD_DB CHA2 = 000'b
41	29	0x00	_
42	2A	0x75	EQ CHA3 = 0x00
43	2B	0xC0	VOD CHA3 = 110'b, VOD_DB CHA3 = 000'b
44	2C	UXUU	
44 45	2C 2D	0x00 0x00	

Table 7. Example Of EEPROM For Four Devices Using Two Address Maps (continued)

EEPROM Address	Address (Hex)	EEPROM Data	Comments
47	2F	0x54	End Device 0, 1 - Address Offset 39
48	30	0x00	Begin Device 2, 3 - Address Offset 3
49	31	0x00	
50	32	0x04	
51	33	0x07	
52	34	0x00	
53	35	0x01	EQ CHB0 = 0x01
54	36	0xAB	VOD CHB0 = 011'b
55	37	0x00	VOD_DB CHB0 = 000'b
56	38	0x00	
57	39	0x1A	EQ CHB1 = 0x01
58	3A	0xB0	VOD CHB1 = 011'b, VOD_DB CHB1 = 000'b
59	3B	0x00	
60	3C	0x01	EQ CHB2 = 0x01
61	3D	0xAB	VOD CHB2 = 011'b
62	3E	0x00	VOD_DB CHB2 = 000'b
63	3F	0x00	
64	40	0x1A	EQ CHB3 = 0x01
65	41	0xB0	VOD CHB3 = 011'b, VOD_DB CHB3 = 000'b
66	42	0x09	Signal Detect Status Threshold Control
67	43	0x80	Signal Detect Status Threshold Control
68	44	0x07	EQ CHA0 = 0x03
69	45	0x5C	VOD CHA0 = 110'b
70	46	0x00	VOD_DB CHA0 = 000'b
71	47	0x00	
72	48	0x15	EQ CHA1 = 0x00
73	49	0xA0	VOD CHA1 = 101'b, VOD_DB CHA1 = 000'b
74	4A	0x00	
75	4B	0x07	EQ CHA2 = 0x03
76	4C	0x5C	VOD CHA2 = 110'b
77	4D	0x00	VOD_DB CHA2 = 000'b
78	4E	0x00	
79	4F	0x15	EQ CHA3 = 0x00
80	50	0xA0	VOD CHA3 = 101'b, VOD_DB CHA3 = 000'b
81	51	0x00	
82	52	0x00	
83	53	0x54	
84	54	0x54	End Device 2, 3 - Address Offset 39

Note: $CRC_EN = 0$, Address Map = 1, >256 byte = 0, Device Count[3:0] = 3. Multiple devices can point to the same address map. Maximum EEPROM size is 8 kbits (1024 x 8-bits).

7.5.2 SMBus

The System Management Bus interface is compatible to SMBus 2.0 physical layer specification. Tie ENSMB = 1 $k\Omega$ to VDD (2.5 V mode) or VIN (3.3 V mode) to enable SMBus Slave Mode and allow access to the configuration registers.

ZHCSCW4-OCTOBER 2014

The DS80PCI810 uses AD[3:0] inputs in both SMBus Modes. These AD[3:0] pins are the user set SMBus slave address inputs and have internal pull-downs. Based on the SMBus 2.0 specification, the DS80PCI810 has a 7-bit slave address. The LSB is set to 0'b (for a WRITE). When AD[3:0] pins are left floating or pulled low, AD[3:0] = 0000'b, and the device default address byte is 0xB0. The device supports up to 16 address bytes, as shown in Table 8:

Table 8. Device Slave Address Bytes

AD[3:0] Settings	Full Slave Address Byte (7-Bit Address + Write Bit)	7-Bit Slave Address (Hex)
0000	В0	58
0001	B2	59
0010	B4	5A
0011	B6	5B
0100	B8	5C
0101	BA	5D
0110	ВС	5E
0111	BE	5F
1000	CO	60
1001	C2	61
1010	C4	62
1011	C6	63
1100	C8	64
1101	CA	65
1110	CC	66
1111	CE	67

The SDA/SCL pins are 3.3 V tolerant, but are not 5 V tolerant. An external pull-up resistor is required on the SDA and SCL line. The resistor value can be from 2 k Ω to 5 k Ω depending on the voltage, loading, and speed.

7.5.3 Transfer Of Data Via The SMBus

During normal operation, the data on SDA must be stable during the time when SCL is High.

There are three unique states for the SMBus:

START: A High-to-Low transition on SDA while SCL is High indicates a message START condition.

STOP: A Low-to-High transition on SDA while SCL is High indicates a message STOP condition.

IDLE: If SCL and SDA are both High for a time exceeding t_{RUE} from the last detected STOP condition or if they are High for a total exceeding the maximum specification for t_{HIGH}, then the bus transfers to the IDLE state.

7.5.4 SMBus Transactions

The device supports WRITE and READ transactions. See Table 9 for register address, type (Read/Write, Read Only), default value, and function information.



7.6 Register Maps



Register Maps (continued)

7.6.1 Writing a Register

To write a register, the following protocol is used (see SMBus 2.0 specification).

- 1. The Host drives a START condition, the 7-bit SMBus address, and a "0" indicating a WRITE.
- 2. The Device (Slave) drives the ACK bit ("0").
- 3. The Host drives the 8-bit Register Address.
- 4. The Device drives an ACK bit ("0").
- 5. The Host drive the 8-bit data byte.
- 6. The Device drives an ACK bit ("0").
- 7. The Host drives a STOP condition.

The WRITE transaction is completed, the bus goes IDLE, and communication with other SMBus devices may now occur.

7.6.2 Reading a Register

To read a register, the following protocol is used (see SMBus 2.0 specification).

- 1. The Host drives a START condition, the 7-bit SMBus address, and a "0" indicating a WRITE.
- 2. The Device (Slave) drives the ACK bit ("0").
- 3. The Host drives the 8-bit Register Address.
- 4. The Device drives an ACK bit ("0").
- 5. The Host drives a START condition.
- 6. The Host drives the 7-bit SMBus Address, and a "1" indicating a READ.
- 7. The Device drives an ACK bit "0".
- 8. The Device drives the 8-bit data value (register contents).
- 9. The Host drives a NACK bit "1" indicating end of the READ transfer.
- 10. The Host drives a STOP condition.

The READ transaction is completed, the bus goes IDLE, and communication with other SMBus devices may now occur.



Register Maps (continued)

7.6.3 Detailed Register Map

Table 9. SMBus Slave Mode Register Map

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
		7	Reserved	R/W			Set bit to 0
0x00	Observation	6:3	Address Bit AD[3:0]	R	0x00		Observation of AD[3:0] bits [6]: AD3 [5]: AD2 [4]: AD1 [3]: AD0
		2	EEPROM Read Done	R			1 = Device completed the read from external EEPROM
		1	Reserved	R/W			Set bit to 0
		0	Reserved	R/W			Set bit to 0
0x01	PWDN Channels	7:0	PWDN CHx	R/W	0x00	Yes	Power Down per Channel [7]: CH7 – CHA_3 [6]: CH6 – CHA_2 [5]: CH5 – CHA_1 [4]: CH4 – CHA_0 [3]: CH3 – CHB_3 [2]: CH2 – CHB_2 [1]: CH1 – CHB_1 [0]: CH0 – CHB_0 0x00 = all channels enabled 0xFF = all channels disabled Note: Override PWDN pin and enable register control via Reg 0x02[0]
	Override PWDN, PRSNT	7	Override PRSNT	R/W			1 = Override Automatic Rx Detect State Machine Reset
		6	PRSNT Value				1 = Set Rx Detect State Machine Reset 0 = Clear Rx Detect State Machine Reset
0x02		5:2	Reserved		0x00	Yes	Set bits to 0
		1	Reserved				Set bit to 0
		0	Override PWDN			Yes	1 = Block PWDN pin control (Register control enabled) 0 = Allow PWDN pin control (Register control disabled)
0x03	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x04	Reserved	7:0	Reserved	R/W	0x00	Yes	Set bits to 0
0x05	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
		7:5	Reserved				Set bits to 0
		4	Reserved			Yes	Set bit to 1
0x06	Slave Register Control	3	Register Enable	R/W	0x10		1 = Enable SMBus Slave Mode Register Control Note: In order to change VOD, VOD_DB, and EQ of the channels in slave mode, this bit must be set to 1.
		2:0	Reserved				Set bits to 0
		7	Reserved				Set bit to 0
007	Digital Reset	6	Reset Registers	- R/W 0	0.24		1 = Self clearing reset for SMBus registers (register settings return to default values)
0x07	and Control	5	Reset SMBus Master		0x01		1 = Self clearing reset to SMBus master state machine
		4:0	Reserved				Set bits to 0 0001'b

Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
		7	Reserved				Set bit to 0
	Ou sa mid a	6	Override SD_TH			Yes	1 = Block SD_TH pin control (Register control enabled) 0 = Allow SD_TH pin control (Register control disabled)
80x0	Override Pin Control	5:4	Reserved	R/W	0x00	Yes	Set bits to 0
		3	Override RXDET			Yes	1 = Block RXDET pin control (Register control enabled) 0 = Allow RXDET pin control (Register control disabled)
		2:0	Reserved			Yes	Set bits to 0
0x09	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x0A	Signal Detect Monitor	7:0	SD_TH Status	R	0x00		CH7 - CH0 Internal Signal Detect Indicator [7]: CH7 - CHA_3 [6]: CH6 - CHA_2 [5]: CH5 - CHA_1 [4]: CH4 - CHA_0 [3]: CH3 - CHB_3 [2]: CH2 - CHB_2 [1]: CH1 - CHB_1 [0]: CH0 - CHB_0 0 = Signal detected at input 1 = Signal not detected at input Note: These bits only function when RESERVED2 pin = FLOAT
OVOD	Doggrand	7	Reserved	R/W	0x00		Set bit to 0
0x0B	Reserved	6:0	Reserved	R/W	0x70	Yes	Set bits to 111 0000'b
0x0C	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x0D	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
		7:6	Reserved				Set bits to 0
		5:4	Reserved			Yes	Set bits to 0
0x0E	CH0 - CHB_0 RXDET	3:2	RXDET	R/W	0x00	Yes	00'b = Input is Hi-Z impedance 01'b = Auto Rx-Detect, outputs test every 12 ms for 600 ms (50 times) then stops; termination is Hi-Z until detection; once detected input termination is 50 Ω 10'b = Auto Rx-Detect, outputs test every 12 ms until detection occurs; termination is Hi-Z until detection; once detected input termination is 50 Ω 11'b = Input is 50 Ω Note: Override RXDET pin and enable register control via Reg 0x08[3]
		1:0	Reserved				Set bits to 0
0x0F	CH0 - CHB_0 EQ	7:0	EQ Control	R/W	0x2F	Yes	INB_0 EQ Control - total of four levels. See Table 4.
		7	Short Circuit Protection			Yes	1 = Enable the short circuit protection 0 = Disable the short circuit protection
		6:3	Reserved			Yes	Set bits to 0101'b
0x10	CH0 - CHB_0 VOD	2:0	VOD Control	R/W	0xAD	Yes	OUTB_0 VOD Control: VOD / VID Ratio 000'b = 0.57 001'b = 0.65 010'b = 0.71 011'b = 0.77 100'b = 0.83 101'b = 0.90 (default) 110'b = 1.00 (recommended) 111'b = 1.04



Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
		7	RXDET Status	R			Observation bit for RXDET CH0 - CHB_0 1 = Input 50 Ω terminated to VDD 0 = Input is Hi-Z
		6:5	Reserved		0x02		Set bits to 0
		4:3	Reserved				Set bits to 0
0x11	CH0 - CHB_0 VOD_DB	2:0	VOD_DB Control	R/W		Yes	OUTB_0 VOD_DB Control 000'b = 0 dB (recommended) 001'b = -1.5 dB 010'b = -3.5 dB (default) 011'b = -5 dB 100'b = -6 dB 101'b = -8 dB 111'b = -9 dB 111'b = -12 dB Note: Changing VOD_DB bits effectively lowers the output VOD dynamic range by a factor of the corresponding amount of dB reduction.
		7	Reserved			Yes	Set bit to 0
		6:4	Reserved				Set bits to 0
0x12	CH0 - CHB_0 SD_TH	3:2	Signal Detect Status Assert Threshold	R/W	0x00	Yes	Status Assert threshold (1010 pattern 12 Gbps) 00'b = 50 mVp-p (default) 01'b = 40 mVp-p 10'b = 75 mVp-p 11'b = 58 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
		1:0	Signal Detect Status De-assert Threshold			Yes	Status De-assert threshold (1010 pattern 12 Gbps) 00'b = 37 mVp-p (default) 01'b = 22 mVp-p 10'b = 55 mVp-p 11'b = 45 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
0x13	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x14	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
		7:6	Reserved				Set bits to 0
		5:4	Reserved			Yes	Set bits to 0
0x15	CH1 - CHB_1 RXDET	3:2	RXDET	R/W	0x00	Yes	00'b = Input is Hi-Z impedance 01'b = Auto Rx-Detect, outputs test every 12 ms for 600 ms (50 times) then stops; termination is Hi-Z until detection; once detected input termination is 50 Ω 10'b = Auto Rx-Detect, outputs test every 12 ms until detection occurs; termination is Hi-Z until detection; once detected input termination is 50 Ω 11'b = Input is 50 Ω Note: Override RXDET pin and enable register control via Reg 0x08[3]
		1:0	Reserved				Set bits to 0
0x16	CH1 - CHB_1 EQ	7:0	EQ Control	R/W	0x2F	Yes	INB_1 EQ Control - total of four levels. See Table 4.



Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
		7	Short Circuit Protection			Yes	1 = Enable the short circuit protection 0 = Disable the short circuit protection
		6:3	Reserved		0xAD	Yes	Set bits to 0101'b
0x17	CH1 - CHB_1 VOD	2:0	VOD Control	R/W		Yes	OUTB_1 VOD Control: VOD / VID Ratio 000'b = 0.57 001'b = 0.65 010'b = 0.71 011'b = 0.77 100'b = 0.83 101'b = 0.90 (default) 110'b = 1.00 (recommended) 111'b = 1.04
		7	RXDET Status	R			Observation bit for RXDET CH1 - CHB_1 1 = Input 50 Ω terminated to VDD 0 = Input is Hi-Z
		6:5	Reserved		0x02		Set bits to 0
		4:3	Reserved	R/W			Set bits to 0
0x18	CH1 - CHB_1 VOD_DB	2:0	VOD_DB Control			Yes	OUTB_1 VOD_DB Control 000'b = 0 dB (recommended) 001'b = -1.5 dB 010'b = -3.5 dB (default) 011'b = -5 dB 100'b = -6 dB 101'b = -8 dB 111'b = -9 dB 111'b = -12 dB Note: Changing VOD_DB bits effectively lowers the output VOD dynamic range by a factor of the corresponding amount of dB reduction.
		7	Reserved			Yes	Set bit to 0
		6:4	Reserved				Set bits to 0
0x19	CH1 - CHB_1 SD_TH	3:2	Signal Detect Status Assert Threshold	R/W	0x00	Yes	Status Assert threshold (1010 pattern 12 Gbps) 00'b = 50 mVp-p (default) 01'b = 40 mVp-p 10'b = 75 mVp-p 11'b = 58 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
		1:0	Signal Detect Status De-assert Threshold			Yes	Status De-assert threshold (1010 pattern 12 Gbps) 00'b = 37 mVp-p (default) 01'b = 22 mVp-p 10'b = 55 mVp-p 11'b = 45 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
0x1A	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x1B	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0



Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
		7:6	Reserved				Set bits to 0
		5:4	Reserved		0x00	Yes	Set bits to 0
0x1C	CH2 - CHB_2 RXDET	3:2	RXDET	R/W		Yes	00'b = Input is Hi-Z impedance 01'b = Auto Rx-Detect, outputs test every 12 ms for 600 ms (50 times) then stops; termination is Hi-Z until detection; once detected input termination is 50 Ω 10'b = Auto Rx-Detect, outputs test every 12 ms until detection occurs; termination is Hi-Z until detection; once detected input termination is 50 Ω 11'b = Input is 50 Ω Note: Override RXDET pin and enable register control via Reg 0x08[3]
		1:0	Reserved				Set bits to 0
0x1D	CH2 - CHB_2 EQ	7:0	EQ Control	R/W	0x2F	Yes	INB_2 EQ Control - total of four levels. See Table 4.
		7	Short Circuit Protection	R/W	0xAD	Yes	1 = Enable the short circuit protection 0 = Disable the short circuit protection
0x1E		6:3	Reserved			Yes	Set bits to 0101'b
	CH2 - CHB_2 VOD	2:0	VOD Control			Yes	OUTB_2 VOD Control: VOD / VID Ratio 000'b = 0.57 001'b = 0.65 010'b = 0.71 011'b = 0.77 100'b = 0.83 101'b = 0.90 (default) 110'b = 1.00 (recommended) 111'b = 1.04
		7	RXDET Status	R			Observation bit for RXDET CH2 - CHB_2 1 = Input 50 Ω terminated to VDD 0 = Input is Hi-Z
		6:5	Reserved				Set bits to 0
		4:3	Reserved				Set bits to 0
0x1F	CH2 - CHB_2 VOD_DB	2:0	VOD_DB Control	R/W	0x02	Yes	OUTB_2 VOD_DB Control 000'b = 0 dB (recommended) 001'b = -1.5 dB 010'b = -3.5 dB (default) 011'b = -5 dB 100'b = -6 dB 101'b = -8 dB 111'b = -9 dB 111'b = -12 dB Note: Changing VOD_DB bits effectively lowers the output VOD dynamic range by a factor of the corresponding amount of dB reduction.

Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
		7	Reserved			Yes	Set bit to 0
		6:4	Reserved				Set bits to 0
0x20 C	CH2 - CHB_2 SD_TH	3:2	Signal Detect Status Assert Threshold	R/W	0x00	Yes	Status Assert threshold (1010 pattern 12 Gbps) 00'b = 50 mVp-p (default) 01'b = 40 mVp-p 10'b = 75 mVp-p 11'b = 58 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
		1:0	Signal Detect Status De-assert Threshold			Yes	Status De-assert threshold (1010 pattern 12 Gbps) 00'b = 37 mVp-p (default) 01'b = 22 mVp-p 10'b = 55 mVp-p 11'b = 45 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
0x21	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x22	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
		7:6	Reserved		0x00		Set bits to 0
		5:4	Reserved	R/W		Yes	Set bits to 0
0x23	CH3 - CHB_3 RXDET	3:2	RXDET			Yes	00'b = Input is Hi-Z impedance 01'b = Auto Rx-Detect, outputs test every 12 ms for 600 ms (50 times) then stops; termination is Hi-Z until detection; once detected input termination is 50 Ω 10'b = Auto Rx-Detect, outputs test every 12 ms until detection occurs; termination is Hi-Z until detection; once detected input termination is 50 Ω 11'b = Input is 50 Ω Note: Override RXDET pin and enable register control via Reg 0x08[3]
		1:0	Reserved				Set bits to 0
0x24	CH3 - CHB_3 EQ	7:0	EQ Control	R/W	0x2F	Yes	INB_3 EQ Control - total of four levels. See Table 4.
		7	Short Circuit Protection			Yes	1 = Enable the short circuit protection 0 = Disable the short circuit protection
		6:3	Reserved			Yes	Set bits to 0101'b
0x25	CH3 - CHB_3 VOD	2:0	VOD Control	R/W	0xAD	Yes	OUTB_3 VOD Control: VOD / VID Ratio 000'b = 0.57 001'b = 0.65 010'b = 0.71 011'b = 0.77 100'b = 0.83 101'b = 0.90 (default) 110'b = 1.00 (recommended) 111'b = 1.04



Register Maps (continued)

Address	Register	Bit	Field	Туре	Default	EEPROM	Description
Address	Name	ום	Tield	Type	Delault	Reg Bit	·
		7	RXDET Status	R			Observation bit for RXDET CH3 - CHB_3 1 = Input 50 Ω terminated to VDD 0 = Input is Hi-Z
		6:5	Reserved				Set bits to 0
		4:3	Reserved			Set bits to 0	
0x26	CH3 - CHB_3 VOD_DB	2:0	VOD_DB Control	R/W	0x02	Yes	OUTB_3 VOD_DB Control 000'b = 0 dB (recommended) 001'b = -1.5 dB 010'b = -3.5 dB (default) 011'b = -5 dB 100'b = -6 dB 101'b = -8 dB 110'b = -9 dB 111'b = -12 dB Note: Changing VOD_DB bits effectively lowers the output VOD dynamic range by a factor of the corresponding amount of dB reduction.
		7	Reserved			Yes	Set bit to 0
		6:4	Reserved	R/W	0x00		Set bits to 0
0x27	CH3 - CHB_3 SD_TH	3:2	Signal Detect Status Assert Threshold			Yes	Status Assert threshold (1010 pattern 12 Gbps) 00'b = 50 mVp-p (default) 01'b = 40 mVp-p 10'b = 75 mVp-p 11'b = 58 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
		1:0	Signal Detect Status De-assert Threshold			Yes	Status De-assert threshold (1010 pattern 12 Gbps) 00'b = 37 mVp-p (default) 01'b = 22 mVp-p 10'b = 55 mVp-p 11'b = 45 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
		7	Reserved				Set bit to 0
		6	Reserved			Yes	Set bit to 1
	.	5:4	High SD_TH Status			Yes	Enable Higher Range of Signal Detect Status Thresholds [5]: CH0 - CH3 [4]: CH4 - CH7
0x28	Signal Detect Status Control	3:2	Fast Signal Detect Status	R/W	0x4C	Yes	Enable Fast Signal Detect Status [3]: CH0 - CH3 [2]: CH4 - CH7 Note: In Fast Signal Detect, assert/de-assert response occurs after approximately 3-4 ns
		1:0	Reduced SD Status Gain			Yes	Enable Reduced Signal Detect Status Gain [1]: CH0 - CH3 [0]: CH4 - CH7
0x29	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x2A	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0



Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
		7:6	Reserved				Set bits to 0
		5:4	Reserved			Yes	Set bits to 0
0x2B	CH4 - CHA_0 RXDET	3:2	RXDET	R/W	0x00	Yes	00'b = Input is Hi-Z impedance 01'b = Auto Rx-Detect, outputs test every 12 ms for 600 ms (50 times) then stops; termination is Hi-Z until detection; once detected input termination is 50 Ω 10'b = Auto Rx-Detect, outputs test every 12 ms until detection occurs; termination is Hi-Z until detection; once detected input termination is 50 Ω 11'b = Input is 50 Ω Note: Override RXDET pin and enable register control via Reg 0x08[3]
		1:0	Reserved				Set bits to 0
0x2C	CH4 - CHA_0 EQ	7:0	EQ Control	R/W	0x2F	Yes	INA_0 EQ Control - total of four levels. See Table 4.
		7	Short Circuit Protection		0xAD	Yes	1 = Enable the short circuit protection0 = Disable the short circuit protection
0x2D		6:3	Reserved	R/W		Yes	Set bits to 0101'b
	CH4 - CHA_0 VOD	2:0	VOD Control			Yes	OUTA_0 VOD Control: VOD / VID Ratio 000'b = 0.57 001'b = 0.65 010'b = 0.71 011'b = 0.77 100'b = 0.83 101'b = 0.90 (default) 110'b = 1.00 (recommended) 111'b = 1.04
		7	RXDET Status	R			Observation bit for RXDET CH4 - CHA_0 1 = Input 50 Ω terminated to VDD 0 = Input is Hi-Z
		6:5	Reserved				Set bits to 0
		4:3	Reserved				Set bits to 0
0x2E	CH4 - CHA_0 VOD_DB	2:0	VOD_DB Control	R/W	0x02	Yes	OUTA_0 VOD_DB Control 000'b = 0 dB (recommended) 001'b = -1.5 dB 010'b = -3.5 dB (default) 011'b = -5 dB 100'b = -6 dB 100'b = -8 dB 110'b = -9 dB 111'b = -12 dB Note: Changing VOD_DB bits effectively lowers the output VOD dynamic range by a factor of the corresponding amount of dB reduction.



Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
0x2F	CH4 - CHA_0 SD_TH	7	Reserved	R/W	0x00	Yes	Set bit to 0
		6:4	Reserved				Set bits to 0
		3:2	Signal Detect Status Assert Threshold			Yes	Status Assert threshold (1010 pattern 12 Gbps) 00'b = 50 mVp-p (default) 01'b = 40 mVp-p 10'b = 75 mVp-p 11'b = 58 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
		1:0	Signal Detect Status De-assert Threshold			Yes	Status De-assert threshold (1010 pattern 12 Gbps) 00'b = 37 mVp-p (default) 01'b = 22 mVp-p 10'b = 55 mVp-p 11'b = 45 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
0x30	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x31	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x32	CH5 - CHA_1 RXDET	7:6	Reserved	R/W	0x00		Set bits to 0
		5:4	Reserved			Yes	Set bits to 0
		3:2	RXDET			Yes	00'b = Input is Hi-Z impedance 01'b = Auto Rx-Detect, outputs test every 12 ms for 600 ms (50 times) then stops; termination is Hi-Z until detection; once detected input termination is 50 Ω 10'b = Auto Rx-Detect, outputs test every 12 ms until detection occurs; termination is Hi-Z until detection; once detected input termination is 50 Ω 11'b = Input is 50 Ω Note: Override RXDET pin and enable register control via Reg 0x08[3]
		1:0	Reserved				Set bits to 0
0x33	CH5 - CHA_1 EQ	7:0	EQ Control	R/W	0x2F	Yes	INA_1 EQ Control - total of four levels. See Table 4.
0x34	CH5 - CHA_1 VOD	7	Short Circuit Protection	R/W	0xAD	Yes	1 = Enable the short circuit protection 0 = Disable the short circuit protection
		6:3	Reserved			Yes	Set bits to 0101'b
		2:0	VOD Control			Yes	OUTA_1 VOD Control: VOD / VID Ratio 000'b = 0.57 001'b = 0.65 010'b = 0.71 011'b = 0.77 100'b = 0.83 101'b = 0.90 (default) 110'b = 1.00 (recommended) 111'b = 1.04



Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
		7	RXDET Status	R			Observation bit for RXDET CH5 - CHA1 1 = Input 50 Ω terminated to VDD 0 = Input is Hi-Z
		6:5	Reserved				Set bits to 0
		4:3	Reserved		0x02		Set bits to 0
0x35	CH5 - CHA_1 VOD_DB	2:0	VOD_DB Control	R/W		Yes	OUTA_1 VOD_DB Control 000'b = 0 dB (recommended) 001'b = -1.5 dB 010'b = -3.5 dB (default) 011'b = -5 dB 100'b = -6 dB 101'b = -8 dB 111'b = -9 dB 111'b = -12 dB Note: Changing VOD_DB bits effectively lowers the output VOD dynamic range by a factor of the corresponding amount of dB reduction.
		7	Reserved			Yes	Set bit to 0
	CH5 - CHA_1 SD_TH	6:4	Reserved		0x00		Set bits to 0
0x36		3:2	Signal Detect Status Assert Threshold	R/W		Yes	Status Assert threshold (1010 pattern 12 Gbps) 00'b = 50 mVp-p (default) 01'b = 40 mVp-p 10'b = 75 mVp-p 11'b = 58 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
		1:0	Signal Detect Status De-assert Threshold			Yes	Status De-assert threshold (1010 pattern 12 Gbps) 00'b = 37 mVp-p (default) 01'b = 22 mVp-p 10'b = 55 mVp-p 11'b = 45 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
0x37	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x38	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
		7:6	Reserved				Set bits to 0
		5:4	Reserved			Yes	Set bits to 0
0x39	CH6 - CHA_2 RXDET			0x00	Yes	00'b = Input is Hi-Z impedance 01'b = Auto Rx-Detect, outputs test every 12 ms for 600 ms (50 times) then stops; termination is Hi-Z until detection; once detected input termination is 50 Ω 10'b = Auto Rx-Detect, outputs test every 12 ms until detection occurs; termination is Hi-Z until detection; once detected input termination is 50 Ω 11'b = Input is 50 Ω Note: Override RXDET pin and enable register control via Reg 0x08[3]	
		1:0	Reserved				Set bits to 0
0x3A	CH6 - CHA_2 EQ	7:0	EQ Control	R/W	0x2F	Yes	INA_2 EQ Control - total of four levels. See Table 4.



Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
		7	Short Circuit Protection		0xAD	Yes	1 = Enable the short circuit protection 0 = Disable the short circuit protection
		6:3	Reserved			Yes	Set bits to 0101'b
0x3B	CH6 - CHA_2 VOD	2:0	VOD Control	R/W		Yes	OUTA_2 VOD Control: VOD / VID Ratio 000'b = 0.57 001'b = 0.65 010'b = 0.71 011'b = 0.77 100'b = 0.83 101'b = 0.90 (default) 110'b = 1.00 (recommended) 111'b = 1.04
		7	RXDET Status	R			Observation bit for RXDET CH6 - CHA_2 1 = Input 50 Ω terminated to VDD 0 = Input is Hi-Z
0x3C		6:5	Reserved				Set bits to 0
		4:3	Reserved				Set bits to 0
	CH6 - CHA_2 VOD_DB	2:0	VOD_DB Control	R/W	0x02	Yes	OUTA_2 VOD_DB Control 000'b = 0 dB (recommended) 001'b = -1.5 dB 010'b = -3.5 dB (default) 011'b = -5 dB 100'b = -6 dB 100'b = -8 dB 111'b = -9 dB 111'b = -12 dB Note: Changing VOD_DB bits effectively lowers the output VOD dynamic range by a factor of the corresponding amount of dB reduction.
		7	Reserved			Yes	Set bit to 0
	0x3D CH6 - CHA_2 SD_TH	6:4	Reserved	R/W	0x00		Set bits to 0
0x3D		3:2	Signal Detect Status Assert Threshold			Yes	Status Assert threshold (1010 pattern 12 Gbps) 00'b = 50 mVp-p (default) 01'b = 40 mVp-p 10'b = 75 mVp-p 11'b = 58 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
		1:0	Signal Detect Status De-assert Threshold			Yes	Status De-assert threshold (1010 pattern 12 Gbps) 00'b = 37 mVp-p (default) 01'b = 22 mVp-p 10'b = 55 mVp-p 11'b = 45 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]
0x3E	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x3F	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0



Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description		
		7:6	Reserved				Set bits to 0		
		5:4	Reserved		0x00	Yes	Set bits to 0		
0x40	CH7 - CHA_3 RXDET	3:2	RXDET	R/W		Yes	00'b = Input is Hi-Z impedance 01'b = Auto Rx-Detect, outputs test every 12 ms for 600 ms (50 times) then stops; termination is Hi-Z until detection; once detected input termination is 50 Ω 10'b = Auto Rx-Detect, outputs test every 12 ms until detection occurs; termination is Hi-Z until detection; once detected input termination is 50 Ω 11'b = Input is 50 Ω Note: Override RXDET pin and enable register control via Reg 0x08[3]		
		1:0	Reserved				Set bits to 0		
0x41	CH7 - CHA_3 EQ	7:0	EQ Control	R/W	0x2F	Yes	INA_3 EQ Control - total of four levels. See Table 4.		
	CH7 - CHA_3 VOD	7	Short Circuit Protection		R/W 0xAD	Yes	1 = Enable the short circuit protection0 = Disable the short circuit protection		
		6:3	Reserved			Yes	Set bits to 0101'b		
0x42		2:0	VOD Control	R/W		Yes	OUTA_3 VOD Control: VOD / VID Ratio 000'b = 0.57 001'b = 0.65 010'b = 0.71 011'b = 0.77 100'b = 0.83 101'b = 0.90 (default) 110'b = 1.00 (recommended) 111'b = 1.04		
		7	RXDET Status	R			Observation bit for RXDET CH7 - CHA_3 1 = Input 50 Ω terminated to VDD 0 = Input is Hi-Z		
		6:5	Reserved				Set bits to 0		
		4:3	Reserved				Set bits to 0		
0x43	CH7 - CHA_3 VOD_DB	2:0	VOD_DB Control	R/W	0x02	Yes	OUTA_3 VOD_DB Control 000'b = 0 dB (recommended) 001'b = -1.5 dB 010'b = -3.5 dB (default) 011'b = -5 dB 100'b = -6 dB 100'b = -8 dB 110'b = -9 dB 111'b = -12 dB Note: Changing VOD_DB bits effectively lowers the output VOD dynamic range by a factor of the corresponding amount of dB reduction.		



Register Maps (continued)

		_							
Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description		
		7	Reserved			Yes	Set bit to 0		
		6:4	Reserved				Set bits to 0		
0x44	CH7 - CHA_3 SD_TH	3:2	Signal Detect Status Assert Threshold	R/W	0x00	Yes	Status Assert threshold (1010 pattern 12 Gbps) 00'b = 50 mVp-p (default) 01'b = 40 mVp-p 10'b = 75 mVp-p 11'b = 58 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]		
		1:0	Signal Detect Status De-assert Threshold			Yes	Status De-assert threshold (1010 pattern 12 Gbps) 00'b = 37 mVp-p (default) 01'b = 22 mVp-p 10'b = 55 mVp-p 11'b = 45 mVp-p Note: Override SD_TH pin and enable register control via Reg 0x08[6]		
0x45	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x46	Reserved	7:0	Reserved	R/W	0x38		Set bits to 0x38		
0x47	Reserved	7:4	Reserved	R/W	0x00		Set bits to 0		
0.47	Reserved	3:0 Reserved		17/11	Yes		Set bits to 0		
0x48	Reserved	7:6	Reserved	R/W	0x05	Yes	Set bits to 0		
0.40	reserved	5:0	Reserved	R/W	0.000		Set bits to 00 0101'b		
0x49	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x4A	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x4B	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
	Reserved	7:3	Reserved	R/W		Yes	Set bits to 0		
0x4C		2:1	Reserved	R/W	0x00		Set bits to 0		
			Reserved	R/W		Yes	Set bits to 0		
0x4D	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x4E	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x4F	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x50	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x51	Device ID	7:5	VERSION	R	0x85		100'b		
		4:0	ID				0 0101'b		
0x52	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x53	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x54	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x55	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x56	Reserved	7:0	Reserved	R/W	0x10		Set bits to 0x10		
0x57	Reserved	7:0	Reserved	R/W	0x64		Set bits to 0x64		
0x58	Reserved	7:0	Reserved	R/W	0x21		Set bits to 0x21		
0x59	Reserved	7:1	Reserved	R/W	0x00		Set bits to 0		
	322	0	Reserved			Yes	Set bit to 0		
0x5A	Reserved	7:0	Reserved	R/W	0x54	Yes	Set bits to 0x54		
0x5B	Reserved	7:0	Reserved	R/W	0x54	Yes	Set bits to 0x54		
0x5C	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x5D	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x5E	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		
0x5F	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0		



Register Maps (continued)

Address	Register Name	Bit	Field	Туре	Default	EEPROM Reg Bit	Description
0x60	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0
0x61	Reserved	7:0	Reserved	R/W	0x00		Set bits to 0

8 Applications and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

8.1.1 DS80PCI810 vs. DS80PCI800

The DS80PCI810 and DS80PCI800 are pin compatible, and both can be used for PCIe Gen-1, 2, and 3 applications. The DS80PCI810 features several design enhancements to improve PCIe system interoperability and performance over the previous generation DS80PCI800 design. The DS80PCI810 has a more linear input equalizer and output driver to enhance signal transparency for protocols requiring link training. This transparency is important, because it preserves subtle pre-cursor and post-cursor information from the Tx signal prior to the repeater. As a result of these enhancements, the DS80PCI810 is easier to tune and increases flexibility of IC placement along the signal path. The DS80PCI810 is ideal for open PCIe systems. An open system is defined as an environment where a PCIe connector accepts any compliant PCIe Add-In Card (AIC). The DS80PCI810 can extend the reach of a PCIe system by up to 10 dB beyond the max allowable PCIe channel loss.

The DS80PCI800 may still be used for closed PCIe systems where significant insertion losses (> -35 dB @ 4 GHz) are expected in the signal path. In contrast to open PCIe systems, a closed system is defined as a PCIe environment with a limited number of possible Host-to-Endpoint combinations. Due to larger CTLE gain, the DS80PCI800 is able to compensate insertion loss over longer transmission lines before the repeater. In addition, the DS80PCI800 is able to produce de-emphasis levels up to -12 dB to support significant trace losses after the repeater (> -15 dB @ 4 GHz).

8.1.2 Signal Integrity in PCle Applications

In PCIe Gen-3 applications, specifications require Rx-Tx link training to establish and optimize signal conditioning settings at 8 Gbps. In link training, the Rx partner requests a series of FIR coefficients from the Tx partner at speed. This training sequence is designed to pre-condition the signal path with an optimized link between the endpoints. Note that there is no link training with Tx FIR coefficients for PCIe Gen-1 (2.5 Gbps) or PCIe Gen-2 (5.0 Gbps) applications.

The DS80PCI810 works to extend the reach possible by using active linear equalization on the channel, boosting attenuated signals so that they can be more easily recovered at the Rx. The repeater outputs are specially designed to be transparent to Tx FIR signaling in order to pass information critical for optimal link training to the Rx. Suggested settings for the A-channels and B-channels are given in Table 10 and Table 11. Further adjustments to EQx and VODx settings may optimize signal margin on the link for different system applications:

Table 10. Suggested Device Settings in Pin Mode

CHANNEL SETTINGS	PIN MODE		
EQx	Level 4		
VODx[1:0]	Level 6 (1, 0)		

Table 11. Suggested Device Settings in SMBus Modes

CHANNEL SETTINGS	SMBus MODES
EQx	0x03
VODx	110'b
VOD_DB	000'b

ZHCSCW4-OCTOBER 2014 www.ti.com.cn

The SMBus Slave Mode code example in Table 12 may be used to program the DS80PCI810 with the recommended device settings.

Table 12. SMBus Example Sequence

REGISTER	WRITE VALUE	COMMENTS
0x06	0x18	Set SMBus Slave Mode Register Enable.
0x0F	0x03	Set CHB_0 EQ to 0x03.
0x10	0xAE	Set CHB_0 VOD to 110'b.
0x11	0x00	Set CHB_0 VOD_DB to 000'b.
0x16	0x03	Set CHB_1 EQ to 0x03.
0x17	0xAE	Set CHB_1 VOD to 110'b.
0x18	0x00	Set CHB_1 VOD_DB to 000'b.
0x1D	0x03	Set CHB_2 EQ to 0x03.
0x1E	0xAE	Set CHB_2 VOD to 110'b.
0x1F	0x00	Set CHB_2 VOD_DB to 000'b.
0x24	0x03	Set CHB_3 EQ to 0x03.
0x25	0xAE	Set CHB_3 VOD to 110'b.
0x26	0x00	Set CHB_3 VOD_DB to 000'b.
0x2C	0x03	Set CHA_0 EQ to 0x03.
0x2D	0xAE	Set CHA_0 VOD to 110'b.
0x2E	0x00	Set CHA_0 VOD_DB to 000'b.
0x33	0x03	Set CHA_1 EQ to 0x03.
0x34	0xAE	Set CHA_1 VOD to 110'b.
0x35	0x00	Set CHA_1 VOD_DB to 000'b.
0x3A	0x03	Set CHA_2 EQ to 0x03.
0x3B	0xAE	Set CHA_2 VOD to 110'b.
0x3C	0x00	Set CHA_2 VOD_DB to 000'b.
0x41	0x03	Set CHA_3 EQ to 0x03.
0x42	0xAE	Set CHA_3 VOD to 110'b.
0x43	0x00	Set CHA_3 VOD_DB to 000'b.

8.1.3 Rx Detect Functionality in PCIe Applications

In PCIe systems, specifications require the Tx to implement Rx detection in order to determine whether an Rx endpoint is present. Since the DS80PCI810 is designed for placement between an ASIC Tx and endpoint Rx, the DS80PCI810 implements automatic polling for valid Rx detection when the RXDET pin is left floating or tied low via 20 k Ω to GND. If 50 Ω impedances are seen on both positive and negative outputs of a DS80PCI810 channel, the Rx detect state machine asserts Rx detection, and a 50 Ω termination to VDD is provided at the respective channel's positive and negative input. For open PCle systems where users may swap multiple cards in and out of a given PCIe slot, it is recommended to keep the RXDET pin floating. For closed systems where an endpoint Rx is present in a PCIe slot at all times, the RXDET pin may be left floating or tied high via 1 k Ω to VDD (2.5 V mode) or VIN (3.3 V mode).

For more details about DS80PCI810 Rx detection, refer to Table 2.

Typical Applications

8.2.1 Generic High Speed Repeater

The DS80PCI810 extends PCB and cable reach in multiple applications by using active linear equalization. The high linearity of this device aids specifically in protocols requiring link training and can be used in line cards, backplanes, and motherboards, thereby improving margin and overall eve performance. The capability of the repeater can be explored across a range of data rates and ASIC-to-link-partner signaling, as shown in the following two test setup connections.

Typical Applications (continued)

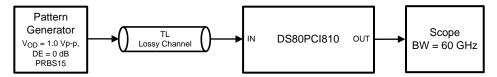


Figure 9. Test Setup Connections Diagram



Figure 10. Test Setup Connections Diagram

8.2.1.1 Design Requirements

As with any high speed design, there are many factors that influence the overall performance. Below are a list of critical areas for consideration and study during design.

- Use 100 Ω impedance traces. Generally these are very loosely coupled to ease routing length differences.
- Place AC-coupling capacitors near to the receiver end of each channel segment to minimize reflections.
- The maximum body size for AC-coupling capacitors is 0402.
- Back-drill connector vias and signal vias to minimize stub length.
- Use reference plane vias to ensure a low inductance path for the return current.

8.2.1.2 Detailed Design Procedure

The DS80PCI810 is designed to be placed at an offset location with respect to the overall channel attenuation. In order to optimize performance, the repeater requires tuning to extend the reach of the cable or trace length while also recovering a solid eye opening. To tune the repeater, the settings mentioned in Table 10 (for Pin Mode) and Table 11 (for SMBus Modes) are recommended as a default starting point for most applications. Once these settings are configured, additional tuning of the EQ and, to a lesser extent, VOD may be required to optimize the repeater performance for each specific application environment.

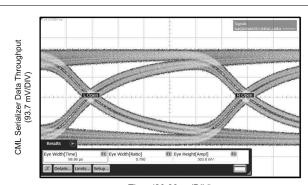
Examples of the repeater performance as a generic high speed datapath repeater are illustrated in the performance curves in the next section.



Typical Applications (continued)

8.2.1.3 Application Performance Plots

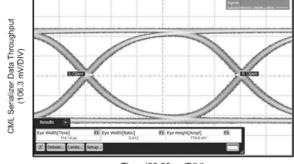
8.2.1.3.1 Pre-Channel Only Setup



Time (20.83 ps/DIV)

No Repeater Used TJ (1.0E-12) = 21.6 ps

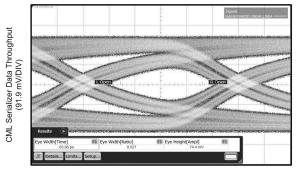
Figure 11. TL = 5 Inch 5-Mil FR4 Trace, No Repeater, 8 Gbps



Time (20.83 ps/DIV)

DS80PCI810 Settings: EQA = Level 2, VODA = Level 6 TJ (1.0E-12) = 13.6 ps

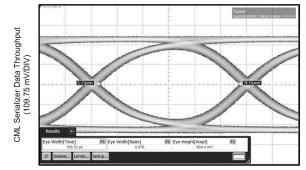
Figure 12. TL = 5 Inch 5-Mil FR4 Trace, DS80PCl810 CHA_0, 8 Gbps



Time (20.83 ps/DIV)

No Repeater Used TJ (1.0E-12) = 43.7 ps

Figure 13. TL = 10 Inch 5-Mil FR4 Trace, No Repeater, 8 Gbps



Time (20.83 ps/DIV)

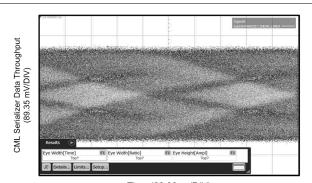
DS80PCI810 Settings: EQA = Level 3, VODA = Level 6 TJ (1.0E-12) = 18.1 ps

Figure 14. TL= 10 Inch 5-Mil FR4 Trace, DS80PCl810 CHA_0, 8 Gbps

ZHCSCW4 – OCTOBER 2014 www.ti.com.cn

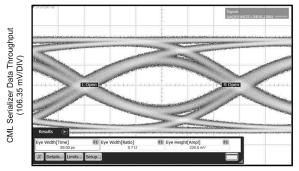
TEXAS INSTRUMENTS

Typical Applications (continued)



Time (20.83 ps/DIV)

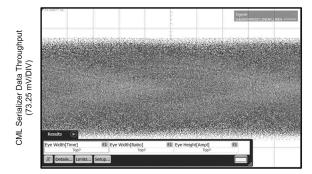
No Repeater Used
TJ (1.0E-12) = Not Available Due to Closed Eye
Figure 15. TL = 20 Inch 5-Mil FR4 Trace,
No Repeater, 8 Gbps



Time (20.83 ps/DIV)

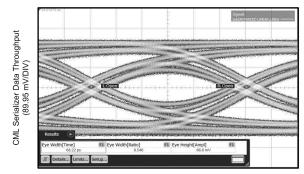
DS80PCl810 Settings: EQA = Level 4, VODA = Level 6 TJ (1.0E-12) = 35.5 ps

Figure 16. TL = 20 Inch 5-Mil FR4 Trace, DS80PCl810 CHA_0, 8 Gbps



Time (20.83 ps/DIV)

No Repeater
TJ (1.0E-12) = Not Available Due to Closed Eye
Figure 17. TL = 5-Meter 30-AWG 100 Ω Twin-Axial Cable,
No Repeater, 8 Gbps



Time (20.83 ps/DIV)

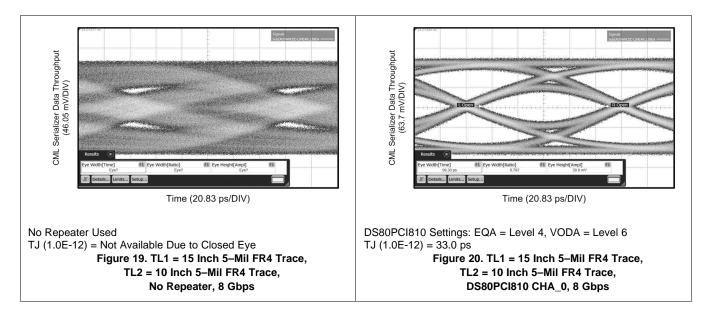
DS80PCI810 Settings: EQA = Level 4, VODA = Level 6 TJ (1.0E-12) = 41.4 ps

Figure 18. TL = 5-Meter 30-AWG 100 Ω Twin-Axial Cable, DS80PCI810 CHA_0, 8 Gbps



Typical Applications (continued)

8.2.1.3.2 Pre-Channel and Post-Channel Setup



8.2.2 PCle Board Applications (PCle Gen-3)

The DS80PCI810 can be used to extend trace length on motherboards and line cards in PCIe Gen-3 applications. The high linearity of the DS80PCI810 aids in the link training protocol required by PCIe Gen-3 at 8 Gbps in accordance with PCI-SIG standards. For PCIe Gen-3, preservation of the pre-cursor and post-cursor Tx FIR presets (P0-P10) is crucial to successful signal transmission from motherboard system root complex to line card ASIC or Embedded Processor. Below is a typical example of the DS80PCI810 used in a PCIe application:

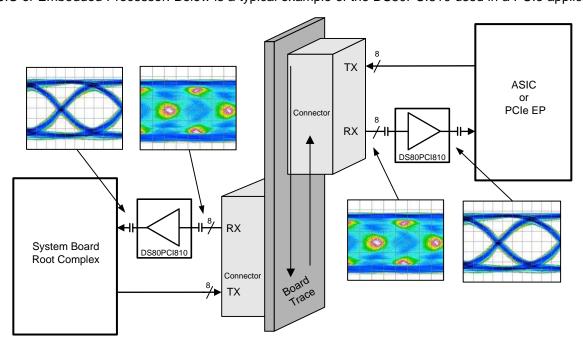


Figure 21. Typical PCle Gen-3 Configuration Diagram

ZHCSCW4 – OCTOBER 2014 www.ti.com.cn

TEXAS INSTRUMENTS

Typical Applications (continued)

8.2.2.1 Design Requirements

As with any high speed design, there are many factors that influence the overall performance. Please reference Design Requirements in the Generic High Speed Repeater application section for a list of critical areas for consideration and study during design.

8.2.2.2 Design Procedure

In PCIe Gen-3 applications, there is a large range of flexibility regarding the placement of the DS80PCI810 in the signal path due to the high linearity of the device. If the PCIe slot must also support lower speeds like PCIe Gen-1 (2.5 Gbps) and Gen-2 (5.0 Gbps), it is recommended to place the DS80PCI810 closer to the endpoint Rx. Once the DS80PCI810 is placed on the signal path, the repeater must be tuned. To tune the repeater, the settings mentioned in Table 10 (for Pin Mode) and Table 11 (for SMBus Modes) are recommended as a default starting point for most applications. Once these settings are configured, additional tuning of the EQ and, to a lesser extent, VOD may be required to optimize the repeater performance to pass link training preset requirements for PCIe Gen-3.

An example of a test configuration used to evaluate the DS80PCI810 in this application can be seen in Figure 22. For more information about DS80PCI810 PCIe applications, please refer to application note SNLA227.

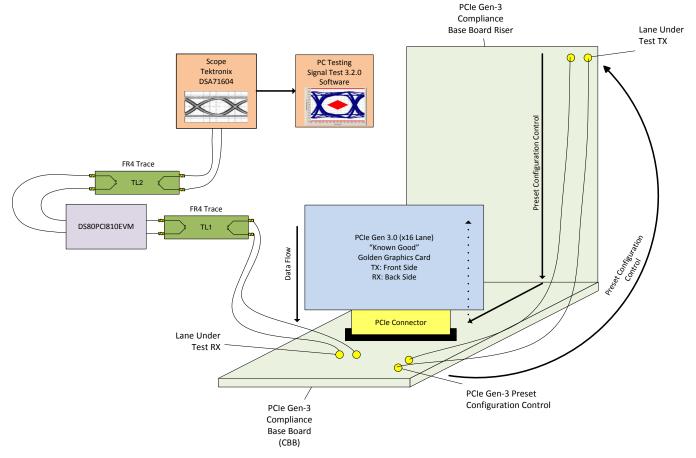
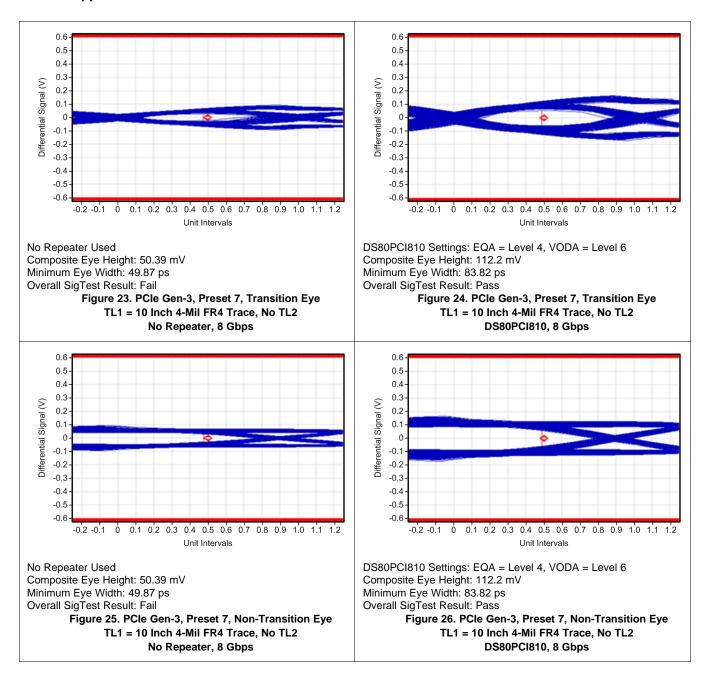


Figure 22. Typical PCIe Gen-3 Add-In Card Test Diagram



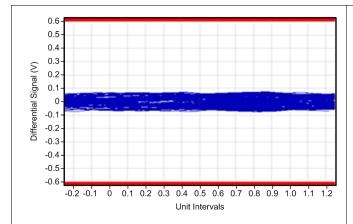
Typical Applications (continued)

8.2.2.3 Application Performance Plots



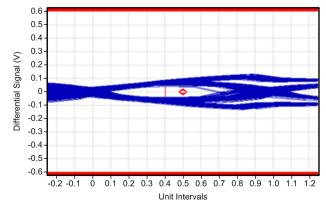
TEXAS INSTRUMENTS

Typical Applications (continued)



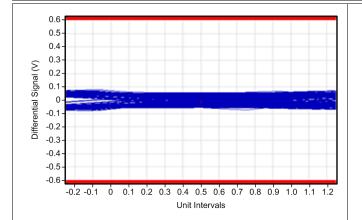
No Repeater Used Composite Eye Height: 0.057 mV Minimum Eye Width: 37.66 ps Overall SigTest Result: Fail

Figure 27. PCIe Gen-3, Preset 7, Transition Eye
TL1 = 10 Inch 4-Mil FR4 Trace,
TL2 = 5 Inch 4-Mil FR4 Trace
No Repeater, 8 Gbps



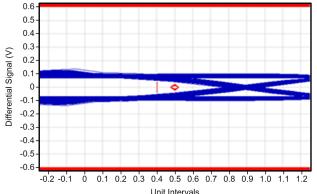
DS80PCI810 Settings: EQA = Level 4, VODA = Level 6 Composite Eye Height: 77.26 mV Minimum Eye Width: 78.24 ps Overall SigTest Result: Pass

Figure 28. PCle Gen-3, Preset 7, Transition Eye
TL1 = 10 Inch 4-Mil FR4 Trace,
TL2 = 5 Inch 4-Mil FR4 Trace
DS80PCl810, 8 Gbps



No Repeater Used Composite Eye Height: 0.057 mV Minimum Eye Width: 37.66 ps Overall SigTest Result: Fail

Figure 29. PCIe Gen-3, Preset 7, Non-Transition Eye
TL1 = 10 Inch 4-Mil FR4 Trace,
TL2 = 5 Inch 4-Mil FR4 Trace
No Repeater, 8 Gbps



DS80PCI810 Settings: EQA = Level 4, VODA = Level 6 Composite Eye Height: 77.26 mV Minimum Eye Width: 78.24 ps Overall SigTest Result: Pass

Figure 30. PCIe Gen-3, Preset 7, Non-Transition Eye
TL1 = 10 Inch 4-Mil FR4 Trace,
TL2 = 5 Inch 4-Mil FR4 Trace
DS80PCI810, 8 Gbps



9 Power Supply Recommendations

Two approaches are recommended to ensure that the DS80PCl810 is provided with an adequate power supply. First, the supply (VDD) and ground (GND) pins should be connected to power planes routed on adjacent layers of the printed circuit board. The layer thickness of the dielectric should be minimized so that the VDD and GND planes create a low inductance supply with distributed capacitance. Second, careful attention to supply bypassing through the proper use of bypass capacitors is required. A 0.1 μ F bypass capacitor should be connected to each VDD pin such that the capacitor is placed as close as possible to the DS80PCl810. Smaller body size capacitors can help facilitate proper component placement. Additionally, capacitor with capacitance in the range of 1 μ F to 10 μ F should be incorporated in the power supply bypassing design as well. These capacitors can be either tantalum or an ultra-low ESR ceramic.

The DS80PCl810 has an optional internal voltage regulator to provide the 2.5 V supply to the device. In 3.3 V mode operation, the VIN pin = 3.3 V is used to supply power to the device. The internal regulator then provides the 2.5 V to the VDD pins of the device, and a 0.1 μ F cap is needed at each of the five VDD pins for power supply de-coupling (total capacitance should equal 0.5 μ F). The VDD_SEL pin must be tied to GND to enable the internal regulator. In 2.5 V mode operation, the VIN pin should be left open and 2.5 V supply must be applied to the five VDD pins to power the device. The VDD_SEL pin must be left open (no connect) to disable the internal regulator.

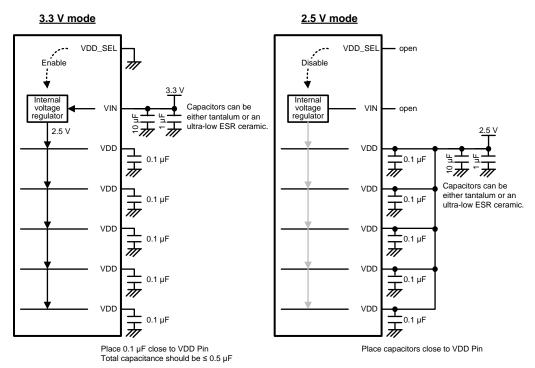


Figure 31. 3.3 V or 2.5 V Supply Connection Diagram

TEXAS INSTRUMENTS

10 Layout

10.1 Layout Guidelines

The CML inputs and outputs have been optimized to work with interconnects using a controlled differential impedance of $100~\Omega$. It is preferable to route differential lines exclusively on one layer of the board, particularly for the input traces. The use of vias should be avoided if possible. If vias must be used, they should be used sparingly and must be placed symmetrically for each side of a given differential pair. Whenever differential vias are used, the layout must also provide for a low inductance path for the return currents as well. Route the differential signals away from other signals and noise sources on the printed circuit board. To minimize the effects of crosstalk, a 5:1 ratio or greater should be maintained between inter-pair and intra-pair spacing. See AN-1187 "Leadless Leadframe Package (LLP) Application Report" (literature number SNOA401) for additional information on QFN (WQFN) packages.

10.2 Layout Example

Figure 32 depicts different transmission line topologies which can be used in various combinations to achieve the optimal system performance. Impedance discontinuities at the differential via can be minimized or eliminated by increasing the swell around each hole and by providing for a low inductance return current path. When the via structure is associated with a thick backplane PCB, further optimization such as back drilling is often used to reduce the detrimental high frequency effects of stubs on the signal path.

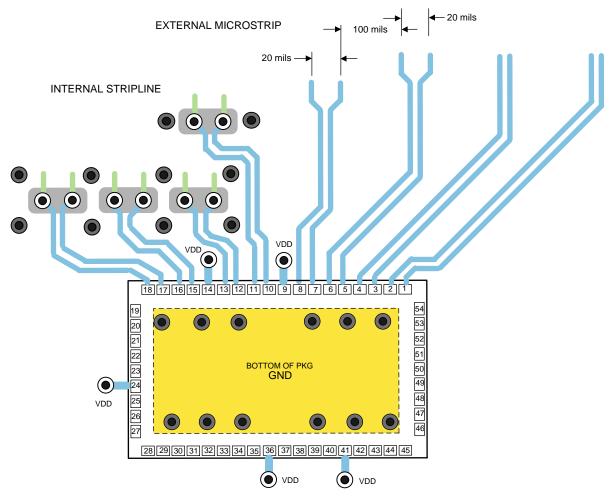


Figure 32. Typical Routing Options



11 器件和文档支持

11.1 商标

www.ti.com.cn

All trademarks are the property of their respective owners.

11.2 静电放电警告



这些装置包含有限的内置 ESD 保护。 存储或装卸时,应将导线一起截短或将装置放置于导电泡棉中,以防止 MOS 门极遭受静电损伤。

11.3 术语表

SLYZ022 — TI 术语表。

这份术语表列出并解释术语、首字母缩略词和定义。

12 机械封装和可订购信息

以下页中包括机械封装和可订购信息。 这些信息是针对指定器件可提供的最新数据。 这些数据会在无通知且不对本文档进行修订的情况下发生改变。 欲获得该数据表的浏览器版本,请查阅左侧的导航栏。

www.ti.com 10-Nov-2025

PACKAGING INFORMATION

Orderable part number	Status	Material type	Package Pins	Package qty Carrier	RoHS	Lead finish/	MSL rating/	Op temp (°C)	Part marking
	(1)	(2)			(3)	Ball material	Peak reflow		(6)
						(4)	(5)		
DS80PCI810NJYR	Active	Production	WQFN (NJY) 54	2000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 85	80PCI810A0
DS80PCI810NJYR.A	Active	Production	WQFN (NJY) 54	2000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 85	80PCI810A0
DS80PCI810NJYR.B	Active	Production	WQFN (NJY) 54	2000 LARGE T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 85	80PCI810A0
DS80PCI810NJYT	Active	Production	WQFN (NJY) 54	250 SMALL T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 85	80PCI810A0
DS80PCI810NJYT.A	Active	Production	WQFN (NJY) 54	250 SMALL T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 85	80PCI810A0
DS80PCI810NJYT.B	Active	Production	WQFN (NJY) 54	250 SMALL T&R	Yes	SN	Level-2-260C-1 YEAR	-40 to 85	80PCI810A0

⁽¹⁾ Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

⁽²⁾ Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

⁽⁴⁾ Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

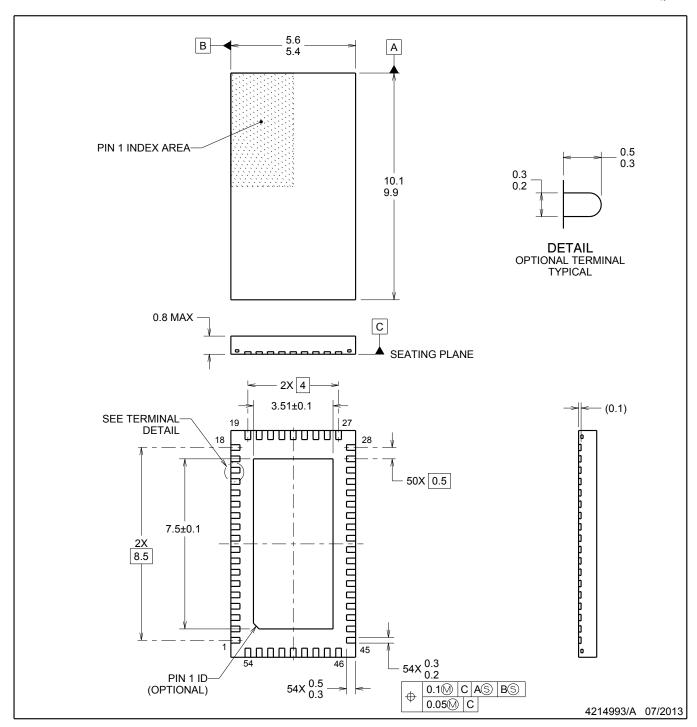


PACKAGE OPTION ADDENDUM

www.ti.com 10-Nov-2025

WQFN

WQFN



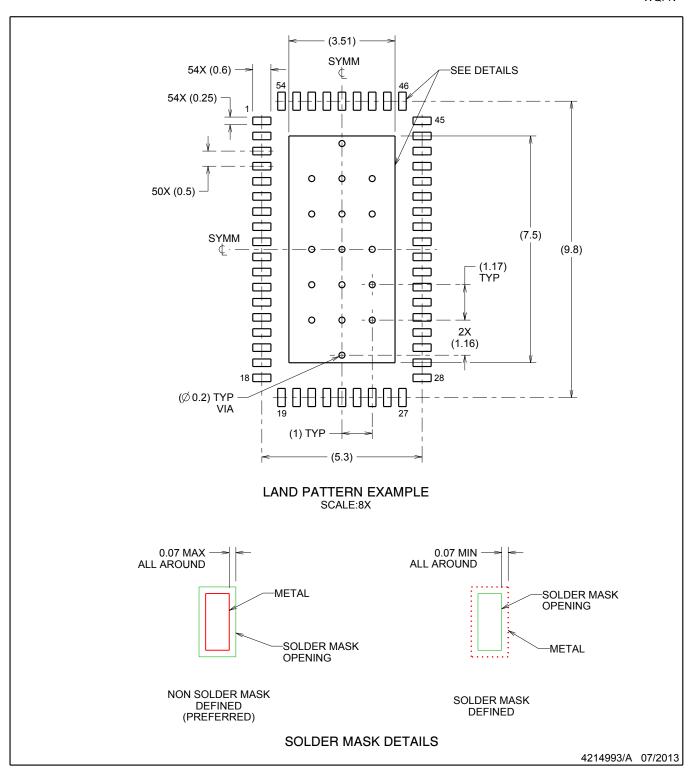
NOTES:

- 1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- This drawing is subject to change without notice.
 The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



NJY0054A WQFN

WQFN



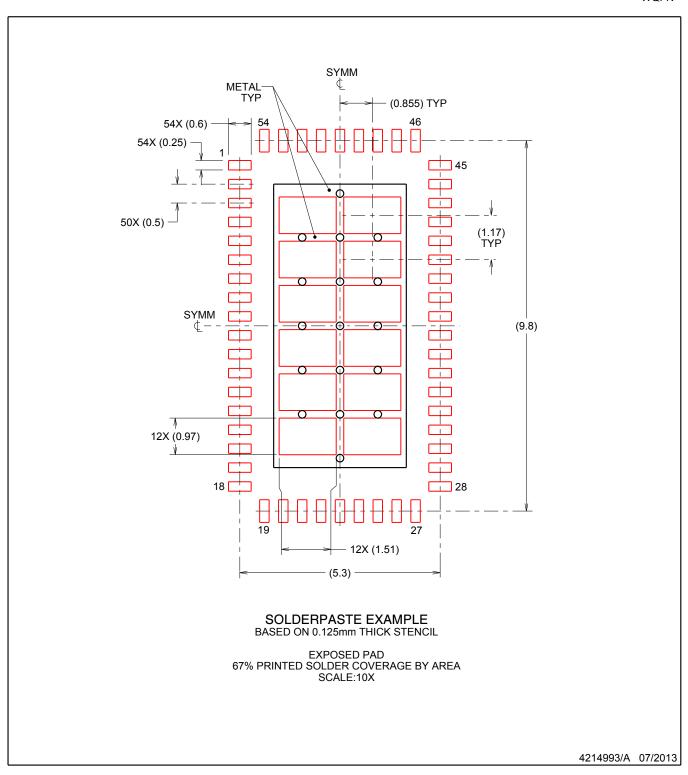
NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, refer to QFN/SON PCB application note in literature No. SLUA271 (www.ti.com/lit/slua271).



NJY0054A WQFN

WQFN



NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



重要通知和免责声明

TI"按原样"提供技术和可靠性数据(包括数据表)、设计资源(包括参考设计)、应用或其他设计建议、网络工具、安全信息和其他资源,不保证没有瑕疵且不做出任何明示或暗示的担保,包括但不限于对适销性、与某特定用途的适用性或不侵犯任何第三方知识产权的暗示担保。

这些资源可供使用 TI 产品进行设计的熟练开发人员使用。您将自行承担以下全部责任:(1) 针对您的应用选择合适的 TI 产品,(2) 设计、验证并测试您的应用,(3) 确保您的应用满足相应标准以及任何其他安全、安保法规或其他要求。

这些资源如有变更,恕不另行通知。TI 授权您仅可将这些资源用于研发本资源所述的 TI 产品的相关应用。严禁以其他方式对这些资源进行复制或展示。您无权使用任何其他 TI 知识产权或任何第三方知识产权。对于因您对这些资源的使用而对 TI 及其代表造成的任何索赔、损害、成本、损失和债务,您将全额赔偿,TI 对此概不负责。

TI 提供的产品受 TI 销售条款)、TI 通用质量指南 或 ti.com 上其他适用条款或 TI 产品随附的其他适用条款的约束。TI 提供这些资源并不会扩展或以其他方式更改 TI 针对 TI 产品发布的适用的担保或担保免责声明。 除非德州仪器 (TI) 明确将某产品指定为定制产品或客户特定产品,否则其产品均为按确定价格收入目录的标准通用器件。

TI 反对并拒绝您可能提出的任何其他或不同的条款。

版权所有 © 2025, 德州仪器 (TI) 公司

最后更新日期: 2025 年 10 月