







CC2651R3 ZHCSOX4B - SEPTEMBER 2021 - REVISED MARCH 2022

# CC2651R3 SimpleLink™ 单协议 2.4GHz 无线 MCU

# 1 特性

#### 无线微控制器

- 功能强大的 48 MHz Arm® Cortex®-M4 处理器
- 352KB 闪存程序存储器
- 32KB 超低泄漏 SRAM
- 8KB 缓存 SRAM (也可作为通用 RAM 提供)
- 可编程无线电包括对 2-(G)FSK、4-(G)FSK、 MSK、低功耗 Bluetooth® 5.2、IEEE 802.15.4 PHY 和 MAC 的支持
- 支持无线升级 (OTA)

## 低功耗

- MCU 功耗:
  - 2.91 mA 有源模式, CoreMark®
  - 61 µ A/MHz (运行 CoreMark 时)
  - 0.8 μA 待机模式, RTC, 32KB RAM
  - 0.1 μA 关断模式,引脚唤醒
- 无线电功耗:
  - RX: 6.4 mA
  - TX:7.1 mA(在0dBm条件下) - TX: 9.5 mA(在+5 dBm条件下)

#### 无线协议支持

- Zigbee®
- 低功耗 Bluetooth® 5.2
- SimpleLink™ TI 15.4-stack
- 专有系统

### 高性能无线电

- -104 dBm (在 125 kbps 低功耗 Bluetooth®下)
- 高达 +5 dBm 的输出功率,具有温度补偿

### 法规遵从性

- 适用于符合以下标准的系统:
  - ETSI EN 300 328、EN 300 440 类别 2 和 3
  - FCC CFR47 第 15 部分
  - ARIB STD-T66

#### MCU 外设

- 数字外设可连接至任何 GPIO
- 四个 32 位或八个 16 位通用计时器
- 12 位 ADC、200 ksps、8 通道
- 8位 DAC
- 模拟比较器
- UART、SSI、I<sup>2</sup>C、I<sup>2</sup>S
- 实时时钟 (RTC)
- 集成温度和电池监控器

## 安全驱动工具

- AES 128 位加密加速计
- 真随机数发生器 (TRNG)
- 软件开发套件 (SDK) 中提供了其他加密驱动器

#### 开发工具和软件

- LP-CC2651P3 开发套件
- SimpleLink™ CC13xx 和 CC26xx 软件开发套件 (SDK)
- 用于简单无线电配置的 SmartRF™ Studio
- SysConfig 系统配置工具

#### 工作温度范围

- 片上降压直流/直流转换器
- 1.8V 至 3.8V 单电源电压
- -40°C 至 +105°C

#### 封装

- 7mm×7mm RGZ VQFN48 (31 个 GPIO )
- 5mm×5mm RKP VQFN40 (23 个 GPIO )
- · 符合 RoHS 标准的封装

English Data Sheet: SWRS258



#### 2 应用

- 2400 至 2500 MHz ISM 和 SRD 系统, <sup>1</sup> 接收带宽低至 4kHz
- 楼宇自动化
  - 楼宇安防系统 运动检测器、电子智能锁、门 窗传感器、车库门系统、网关
  - HVAC 恒温器、无线环境传感器、HVAC 系统控制器、网关
  - 防火安全系统 烟雾和热量探测器、火警控制 面板 (FACP)
  - 视频监控 IP 网络摄像头
  - 升降机和自动扶梯 升降机和自动扶梯的电梯 主控板

- 工业运输 资产跟踪
- 工厂自动化和控制
- 医疗
- 电子销售终端 (EPOS) 电子货架标签 (ESL)
- 通信设备
  - 有线网络 无线 LAN 或 Wi-Fi 接入点、边缘路 由器、小型企业路由器
- 个人电子产品
  - 家庭影院和娱乐 智能扬声器、智能显示器、 机顶盒
  - 可穿戴设备(非医用) 智能追踪器、智能服 生

## 3 说明

SimpleLink™ CC2651R3 器件是一款单协议 2.4 GHz 无线微控制器 (MCU),支持以下协议:Zigbee®、低功耗 Bluetooth®5.2、IEEE 802.15.4g、TI 15.4-Stack (2.4 GHz)。CC2651R3 基于 Arm® Cortex® M4 主处理器,针对电网基础设施、楼宇自动化、零售自动化、个人电子产品和医疗应用中的低功耗无线通信和高级传感功能进行了优化。

CC2651R3 具有由 Arm® Cortex® M0 驱动的软件定义无线电,支持多个物理层和射频标准。该器件支持在 2360 MHz 至 2500 MHz 频带内运行。CC2651R3 在 2.4 GHz 频带中支持 +5 dBm (9.5 mA) 的 TX 功率。 CC2651R3 接收灵敏度为 -104 dBm (对于 125 kbps 的低功耗 Bluetooth® 编码 PHY)。

在采用 RTC 并保持 32KB RAM 时, CC2651R3 具有 0.8 μA 的低待机电流。

许多客户对产品生命周期的要求为 10 至 15 年或者更久,为了达到这一目标,TI 制定了产品生命周期政策,对产品的寿命和供货连续性作出承诺。

CC2651R3 器件是 SimpleLink™ MCU 平台的一部分,包括 Wi-Fi®、低功耗 *Bluetooth*®、Thread、Zigbee、Wi-SUN®、Amazon Sidewalk、mioty、Sub-1 GHz MCU 和主机 MCU。 CC2651R3 是可扩展产品系列(闪存为32KB 至 704KB)的一部分,具有引脚对引脚兼容的封装选项。通用 SimpleLink™ CC13xx 和 CC26xx 软件开发套件 (SDK) 及 SysConfig 系统配置工具支持产品系列中各器件之间的迁移。SDK 随附了丰富的软件栈、应用示例和 SimpleLink™ Academy 培训课程。如需了解更多相关信息,请访问无线连接。

## 器件信息

## 11 JH -0-									
<del>器件型号<sup>(1)</sup></del>	封装	封装尺寸 ( 标称值 )							
CC2651R31T0RGZR	VQFN (48)	7.00mm × 7.00mm							
CC2651R31T0RKPR	VQFN (40)	5.00mm × 5.00mm							

(1) 如需所有可用器件的最新器件、封装和订购信息,请参阅节 12 中的"封装选项附录"或访问 TI 网站。

<sup>1</sup> 请参阅*射频内核*,了解有关支持的协议标准、模块格式和数据速率的更多详细信息。

# 4 功能方框图

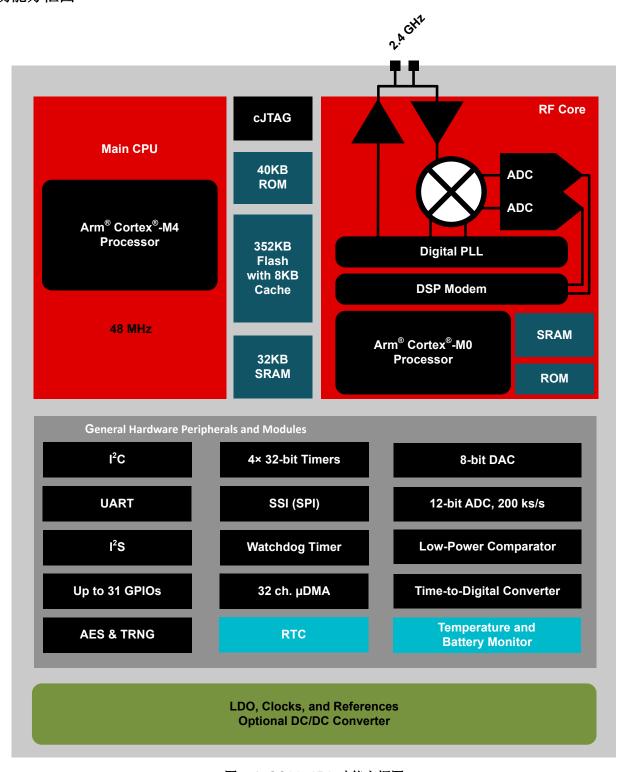


图 4-1. CC2651R3 功能方框图



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# **5 Revision History**

注:以前版本的页码可能与当前版本的页码不同

C	nanges nom rebruary 13, 2022 to April 1, 2022 (nom kevision A (rebruary 2022) to kevision	
В	(April 2022))	Page
•	Added RKP data	12



# **6 Device Comparison**

				ı	RADIC	SUPI	PORT	'							PA	CKA	GE SI	ZE
Device	Sub-1 GHz Prop.	2.4GHz Prop.	Wireless M-Bus	mioty	Wi-SUN®	Sidewalk	Bluetooth® 5.2 LE	ZigBee	Thread	Multiprotocol	+20 dBm PA	FLASH (KB)	RAM + Cache (KB)	GPIO	4 X 4 mm VQFN (32)	5 X 5 mm VQFN (32)	5 X 5 mm VQFN (40)	7 X 7 mm VQFN (48)
CC1310	Х		X	Х								32-128	16-20 + 8	10-30	Х	Х		X
CC1311R3	Х		Х	Х								352	32 + 8	22-30			Х	Х
CC1311P3	Х		Х	Х							Х	352	32 + 8	26				Х
CC1312R	Х		Х	Х	Х							352	80 + 8	30				Х
CC1312R7	Х		Х	Х	Х	Х				Х		704	144 + 8	30				Х
CC1352R	Х	Х	Х	Х	Х		Х	Х	Х	Х		352	80 + 8	28				Х
CC1352P	Х	Х	Х	Х	Х		Х	Х	Х	Х	Х	352	80 + 8	26				Х
CC1352P7	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	704	144 + 8	26				Х
CC2640R2F							Х					128	20 + 8	10-31	Х	Х		Х
CC2642R							Х					352	80 + 8	31				Х
CC2642R-Q1							Х					352	80 + 8	31				Х
CC2651R3		Х					Х	Х				352	32 + 8	23-31			Х	Х
CC2651P3		Х					Х	Х			Х	352	32 + 8	22-26			Х	Х
CC2652R		Х					Х	Х	Х	Х		352	80 + 8	31				Х
CC2652RB		Х					Х	Х	Х	Х		352	80 + 8	31				Х
CC2652R7		Х					Х	Х	Х	Х		704	144 + 8	31				Х
CC2652P		Х					Х	Х	Х	Х	Х	352	80 + 8	26				Х
CC2652P7		Х					Х	Х	Х	Х	Х	704	144 + 8	26				Х



# 7 Pin Configuration and Functions

## 7.1 Pin Diagram - RGZ Package (Top View)

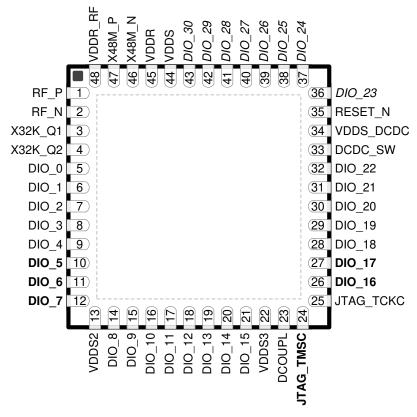


图 7-1. RGZ (7-mm × 7-mm) Pinout, 0.5-mm Pitch (Top View)

The following I/O pins marked in 图 7-1 in **bold** have high-drive capabilities:

- Pin 10, DIO 5
- Pin 11, DIO 6
- Pin 12, DIO 7
- · Pin 24, JTAG TMSC
- Pin 26, DIO 16
- Pin 27, DIO 17

The following I/O pins marked in \( \bar{2} \) 7-1 in *italics* have analog capabilities:

- Pin 36, DIO 23
- Pin 37, DIO\_24
- Pin 38, DIO\_25
- Pin 39, DIO 26
- Pin 40, DIO\_27
- Pin 41, DIO\_28
- Pin 42, DIO 29
- Pin 43, DIO\_30



# 7.2 Signal Descriptions - RGZ Package

# 表 7-1. Signal Descriptions - RGZ Package

PIN			TYPE			
NAME	NO.	I/O	TYPE	DESCRIPTION		
DCDC_SW	33	_	Power	Output from internal DC/DC converter <sup>(1)</sup>		
DCOUPL	23	_	Power	For decoupling of internal 1.27 V regulated digital-supply (2)		
DIO_0	5 I/O Digi		Digital	GPIO		
DIO_1	6	I/O	Digital	GPIO		
DIO_2	7	I/O	Digital	GPIO		
DIO_3	8	I/O	Digital	GPIO		
DIO_4	9	I/O	Digital	GPIO		
DIO_5	10	I/O	Digital	GPIO, high-drive capability		
DIO_6	11	I/O	Digital	GPIO, high-drive capability		
DIO_7	12	I/O	Digital	GPIO, high-drive capability		
DIO_8	14	I/O	Digital	GPIO		
DIO_9	15	I/O	Digital	GPIO		
DIO_10	16	I/O	Digital	GPIO		
DIO_11	17	I/O	Digital	GPIO		
DIO_12	18	I/O	Digital	GPIO		
DIO_13	19	I/O	Digital	GPIO		
DIO_14	20	I/O	Digital	GPIO		
DIO_15	21	I/O	Digital	GPIO		
DIO_16	26	I/O	Digital	GPIO, JTAG_TDO, high-drive capability		
DIO_17	27	I/O	Digital	GPIO, JTAG_TDI, high-drive capability		
DIO_18	28	I/O	Digital	GPIO		
DIO_19	29	I/O	Digital	GPIO		
DIO_20	30	I/O	Digital	GPIO		
DIO_21	31	I/O	Digital	GPIO		
DIO_22	32	I/O	Digital	GPIO		
DIO_23	36	I/O	Digital or Analog	GPIO, analog capability		
DIO_24	37	I/O	Digital or Analog	GPIO, analog capability		
DIO_25	38	I/O	Digital or Analog	GPIO, analog capability		
DIO_26	39	I/O	Digital or Analog	GPIO, analog capability		
DIO_27	40	I/O	Digital or Analog	GPIO, analog capability		
DIO_28	41	I/O	Digital or Analog	GPIO, analog capability		
DIO_29	42	I/O	Digital or Analog	GPIO, analog capability		
DIO_30	43	I/O	Digital or Analog	GPIO, analog capability		
EGP	_	_	GND	Ground - exposed ground pad <sup>(3)</sup>		
JTAG_TMSC	24	I/O	Digital	JTAG TMSC, high-drive capability		
JTAG_TCKC	25	I	Digital	JTAG TCKC		
RESET_N	35	I	Digital	Reset, active low. No internal pullup resistor		
RF_P	1	_	RF	Positive RF input signal to LNA during RX Positive RF output signal from PA during TX		
RF_N	2	_	RF	Negative RF input signal to LNA during RX Negative RF output signal from PA during TX		
VDDR	45	_	Power	Internal supply, must be powered from the internal DC/DC converter or the internal LDO <sup>(2)</sup> (4) (6)		



## 表 7-1. Signal Descriptions - RGZ Package (continued)

		•				
NAME NO.		I/O	TYPE	DESCRIPTION		
		"0	1117	DESCRIPTION		
VDDR_RF	48	_	Power	Internal supply, must be powered from the internal DC/DC converter or the internal LDO <sup>(2)</sup> (5) (6)		
VDDS	44	_	Power	1.8-V to 3.8-V main chip supply <sup>(1)</sup>		
VDDS2	13	_	Power	1.8-V to 3.8-V DIO supply <sup>(1)</sup>		
VDDS3	22	_	Power	1.8-V to 3.8-V DIO supply <sup>(1)</sup>		
VDDS_DCDC	34	_	Power	1.8-V to 3.8-V DC/DC converter supply		
X48M_N	46	_	Analog	48-MHz crystal oscillator pin 1		
X48M_P	47	_	Analog	48-MHz crystal oscillator pin 2		
X32K_Q1	3	_	Analog	32-kHz crystal oscillator pin 1		
X32K_Q2	4	_	Analog	32-kHz crystal oscillator pin 2		

- For more details, see the device technical reference manual listed in  $\ddagger$  11.3.
- (2) Do not supply external circuitry from this pin.
- EGP is the only ground connection for the device. Good electrical connection to device ground on printed circuit board (PCB) is imperative for proper device operation.
- If internal DC/DC converter is not used, this pin is supplied internally from the main LDO.

  If internal DC/DC converter is not used, this pin must be connected to VDDR for supply from the main LDO.
- Output from internal DC/DC and LDO is trimmed to 1.68 V. (6)

## 7.3 Pin Diagram - RKP Package (Top View)

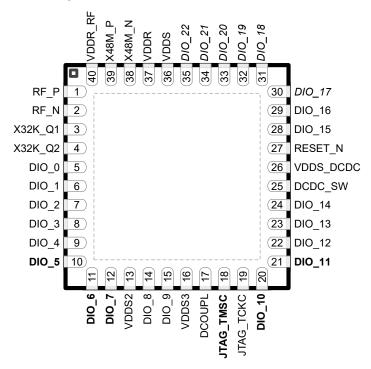


图 7-2. RKP (5-mm × 5-mm) Pinout, 0.4-mm Pitch (Top View)

The following I/O pins marked in 图 7-2 in **bold** have high-drive capabilities:

- Pin 10, DIO 5
- Pin 11, DIO 6
- Pin 12, DIO\_7
- · Pin 18, JTAG TMSC
- Pin 20, DIO\_10
- Pin 21, DIO\_11

The following I/O pins marked in \( \bar{2} \) 7-2 in *italics* have analog capabilities:

- Pin 28, DIO 15
- Pin 29, DIO 16
- Pin 30, DIO 17
- Pin 31, DIO\_18
- Pin 32, DIO\_19
- Pin 33, DIO 20
- Pin 34, DIO\_21
- Pin 35, DIO\_22

## 7.4 Signal Descriptions - RKP Package

表 7-2. Signal Descriptions - RKP Package

PIN		I/O	TYPE	DESCRIPTION		
NAME	NO.	"0	1175	DESCRIPTION		
DCDC_SW	25	_	Power	Output from internal DC/DC converter <sup>(1)</sup>		
DCOUPL	17	_	Power	For decoupling of internal 1.27 V regulated digital-supply (2)		
DIO_0	5	I/O	Digital	GPIO		
DIO_1	6	I/O	Digital	GPIO		



表 7-2. Signal Descriptions - RKP Package (continued)

	1	K 1-2. Olg	nai bescriptions	RKP Package (continued)
PIN		I/O TYPE		DESCRIPTION
NAME	NO.			220011111011
DIO_2	7	I/O	Digital	GPIO
DIO_3	8	I/O	Digital	GPIO
DIO_4	9	I/O	Digital	GPIO
DIO_5	10	I/O	Digital	GPIO, high-drive capability
DIO_6	11	I/O	Digital	GPIO, high-drive capability
DIO_7	12	I/O	Digital	GPIO, high-drive capability
DIO_8	14	I/O	Digital	GPIO
DIO_9	15	I/O	Digital	GPIO
DIO_10	20	I/O	Digital	GPIO, JTAG_TDO, high-drive capability
DIO_11	21	I/O	Digital	GPIO, JTAG_TDI, high-drive capability
DIO_12	22	I/O	Digital	GPIO
DIO_13	23	I/O	Digital	GPIO
DIO_14	24	I/O	Digital	GPIO
DIO_15	28	I/O	Digital	GPIO, analog capability
DIO_16	29	I/O	Digital	GPIO, analog capability
DIO_17	30	I/O	Digital	GPIO, analog capability
DIO_18	31	I/O	Digital	GPIO, analog capability
DIO_19	32	I/O	Digital	GPIO, analog capability
DIO_20	33	I/O	Digital	GPIO, analog capability
DIO_21	34	I/O	Digital	GPIO, analog capability
DIO_22	35	I/O	Digital	GPIO, analog capability
EGP	_	_	GND	Ground - exposed ground pad <sup>(3)</sup>
JTAG_TSMC	18	I/O	Digital	JTAG TMSC, high-drive capability
JTAG_TCKC	19	I	Digital	JTAG TCKC
RESET_N	27	I	Digital	Reset, active low. No internal pullup resistor
RF_P	1	_	RF	Positive RF input signal to LNA during RX Positive RF output signal from PA during TX
RF_N	2	_	RF	Negative RF input signal to LNA during RX Negative RF output signal from PA during TX
VDDR	37	_	Power	Internal supply, must be powered from the internal DC/DC converter or the internal LDO <sup>(2)</sup> (4) (6)
VDDR_RF	40	_	Power	Internal supply, must be powered from the internal DC/DC converter or the internal LDO <sup>(2)</sup> (5) (6)
VDDS	36	_	Power	1.8-V to 3.8-V main chip supply <sup>(1)</sup>
VDDS2	13	_	Power	1.8-V to 3.8-V DIO supply <sup>(1)</sup>
VDDS3	16	_	Power	1.8-V to 3.8-V DIO supply <sup>(1)</sup>
VDDS_DCDC	26	_	Power	1.8-V to 3.8-V DC/DC converter supply
X48M_N	38	_	Analog	48-MHz crystal oscillator pin 1
X48M_P	39	_	Analog	48-MHz crystal oscillator pin 2
X32K_Q1	3	_	Analog	32-kHz crystal oscillator pin 1
X32K_Q2	4	_	Analog	32-kHz crystal oscillator pin 2

- (1) For more details, see the device technical reference manual listed in  $\ddagger$  11.3.
- (2) Do not supply external circuitry from this pin.
- (3) EGP is the only ground connection for the device. Good electrical connection to device ground on printed circuit board (PCB) is imperative for proper device operation.
- (4) If internal DC/DC converter is not used, this pin is supplied internally from the main LDO.
- (5) If internal DC/DC converter is not used, this pin must be connected to VDDR for supply from the main LDO.

(6) Output from internal DC/DC and LDO is trimmed to 1.68 V.

## 7.5 Connections for Unused Pins and Modules

表 7-3. Connections for Unused Pins - RGZ Package

FUNCTION	SIGNAL NAME	PIN NUMBER	ACCEPTABLE PRACTICE(1)	PREFERRED PRACTICE <sup>(1)</sup>
GPIO	DIO_n	5 - 12 14 - 21 26 - 32 36 - 43	NC or GND	NC
32.768-kHz crystal	X32K_Q1	3	NC or GND	NC
32.700-Ki iz Ci ystai	X32K_Q2	4	INC OF GIND	NO
DC/DC converter <sup>(2)</sup>	DCDC_SW	33	NC	NC
DO/DO CONVENIENT	VDDS_DCDC	34	VDDS	VDDS

<sup>(1)</sup> NC = No connect

### 表 7-4. Connection for Unused Pins and Modules - RKP Package

2. Il comitodion for original modules 11.1. I define										
FUNCTION	SIGNAL NAME	PIN NUMBER	ACCEPTABLE PRACTICE	PREFERRED PRACTICE						
GPIO	DIO_n	5-12 14-15 20-24 28-35	NC or GND	NC						
32.768-kHz crystal	X32K_Q1	3	NC or GND	NC						
32.700-KHZ CIYSIAI	X32K_Q2	4	INC OF GND	INC						
No Connects	NC		NC	NC						
DC/DC converter	DCDC_SW	25	NC	NC						
DC/DC converter	VDDS_DCDC	26	VDDS	VDDS						

<sup>(2)</sup> When the DC/DC converter is not used, the inductor between DCDC\_SW and VDDR can be removed. VDDR and VDDR\_RF must still be connected and the 22 uF DCDC capacitor must be kept on the VDDR net.



## 8 Specifications

## 8.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)(1) (2)

			MIN	MAX	UNIT
VDDS <sup>(3)</sup>	Supply voltage		- 0.3	4.1	V
	Voltage on any digital pin	(4) (5)	- 0.3	VDDS + 0.3, max 4.1	V
	Voltage on crystal oscilla	tor pins, X32K_Q1, X32K_Q2, X48M_N and X48M_P	- 0.3	VDDR + 0.3, max 2.25	V
	Voltage on ADC input	Voltage scaling enabled	- 0.3	VDDS	
V <sub>in</sub>		Voltage scaling disabled, internal reference	- 0.3	1.49	V
		Voltage scaling disabled, VDDS as reference	- 0.3	VDDS / 2.9	
	Input level, RF pins (RF_	P and RF_N)		5	dBm
T <sub>stg</sub>	Storage temperature	·	- 40	150	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If used outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime
- (2) All voltage values are with respect to ground, unless otherwise noted.
- (3) VDDS\_DCDC, VDDS2 and VDDS3 must be at the same potential as VDDS.
- 4) Including analog capable DIOs.
- (5) Injection current is not supported on any GPIO pin

## 8.2 ESD Ratings

				VALUE	UNIT
V <sub>ESD</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	All pins	±2000	V
		Charged device model (CDM), per ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup>	All pins	±500	V

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process

#### 8.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

	MIN	MAX	UNIT
Operating ambient temperature <sup>(1) (2)</sup>	- 40	105	°C
Operating junction temperature <sup>(1) (2)</sup>	- 40	115	°C
Operating supply voltage (VDDS)	1.8	3.8	V
Rising supply voltage slew rate	0	100	mV/μs
Falling supply voltage slew rate <sup>(3)</sup>	0	20	mV/μs

- (1) Operation at or near maximum operating temperature for extended durations will result in lifetime reduction.
- (2) For thermal resistance characteristics refer to 节 8.8.
- (3) For small coin-cell batteries, with high worst-case end-of-life equivalent source resistance, a 22-μF VDDS input capacitor must be used to ensure compliance with this slew rate.

#### 8.4 Power Supply and Modules

over operating free-air temperature range (unless otherwise noted)

	<b>,</b>				
PARAMETER		MIN	TYP	MAX	UNIT
VDDS Power-on-Reset (POR) threshold		1.1	- 1.55		V
VDDS Brown-out Detector (BOD)	Rising threshold		1.77		V
VDDS Brown-out Detector (BOD), before initial boot (1)	Rising threshold		1.70		V
VDDS Brown-out Detector (BOD)	Falling threshold		1.75		V

(1) Brown-out Detector is trimmed at initial boot, value is kept until device is reset by a POR reset or the RESET\_N pin

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## 8.5 Power Consumption - Power Modes

When measured on the CC26x1-R3EM-7ID reference design with  $T_c$  = 25 °C,  $V_{DDS}$  = 3.0 V with DC/DC enabled unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Core Curr	ent Consumption					
	Reset and Shutdown	Reset. RESET_N pin asserted or VDDS below power-on-reset threshold		150		nA
	Shuldown	Shutdown. No clocks running, no retention		100		
	Standby without cache	RTC running, CPU, 32KB RAM and (partial) register retention. RCOSC_LF		0.8		μΑ
	retention	RTC running, CPU, 32KB RAM and (partial) register retention XOSC_LF		0.9		μΑ
I <sub>core</sub>	Standby	RTC running, CPU, 32KB RAM and (partial) register retention. RCOSC_LF		2.4		μΑ
	with cache retention	RTC running, CPU, 32KB RAM and (partial) register retention. XOSC_LF		2.6		μΑ
Idle Active	Idle	Supply Systems and RAM powered RCOSC_HF		650		μA
	Active	MCU running CoreMark at 48 MHz RCOSC_HF		2.91		mA
Periphera	l Current Consumption		,		".	
	Peripheral power domain	Delta current with domain enabled		56.0		
	Serial power domain	Delta current with domain enabled		5.0		
	RF Core	Delta current with power domain enabled, clock enabled, RF core idle		144		
	μDMA	Delta current with clock enabled, module is idle		68.6		
I <sub>peri</sub>	Timers	Delta current with clock enabled, module is idle <sup>(1)</sup>		102		μA
-реп	I2C	Delta current with clock enabled, module is idle		12.1		P** 1
	128	Delta current with clock enabled, module is idle		30.8		
	SSI	Delta current with clock enabled, module is idle		71.7		
	UART	Delta current with clock enabled, module is idle		147		
	CRYPTO (AES)	Delta current with clock enabled, module is idle		28.1		
	TRNG	Delta current with clock enabled, module is idle		27.1		

<sup>(1)</sup> Only one GPTimer running



#### 8.6 Power Consumption - Radio Modes

When measured on the CC26x1-R3EM-7ID reference design with  $T_c$  = 25 °C,  $V_{DDS}$  = 3.0 V with DC/DC enabled unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Radio receive current	2440 MHz		6.4		mA
Radio transmit current	0 dBm output power setting 2440 MHz		7.1		mA
2.4 GHz PA (Bluetooth Low Energy)	+5 dBm output power setting 2440 MHz		9.5		mA

## 8.7 Nonvolatile (Flash) Memory Characteristics

Over operating free-air temperature range and V<sub>DDS</sub> = 3.0 V (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Flash sector size			8		KB
Supported flash erase cycles before failure, full bank <sup>(1) (5)</sup>		30			k Cycles
Supported flash erase cycles before failure, single sector <sup>(2)</sup>		60			k Cycles
Maximum number of write operations per row before sector erase <sup>(3)</sup>				83	Write Operations
Flash retention	105 °C	11.4			Years
Flash sector erase current	Average delta current		9.7		mA
Flash sector erase time <sup>(4)</sup>	Zero cycles		10		ms
Flash sector erase time 17	30k cycles			4000	ms
Flash write current	Average delta current, 4 bytes at a time		5.3		mA
Flash write time <sup>(4)</sup>	4 bytes at a time		21.6		μs

- (1) A full bank erase is counted as a single erase cycle on each sector.
- (2) Up to 4 customer-designated sectors can be individually erased an additional 30k times beyond the baseline bank limitation of 30k cycles
- (3) Each wordline is 2048 bits (or 256 bytes) wide. This limitation corresponds to sequential memory writes of 4 (3.1) bytes minimum per write over a whole wordline. If additional writes to the same wordline are required, a sector erase is required once the maximum number of write operations per row is reached.
- (4) This number is dependent on Flash aging and increases over time and erase cycles
- (5) Aborting flash during erase or program modes is not a safe operation.

#### 8.8 Thermal Resistance Characteristics

		PACKAGE		
THERMAL METRIC(1)		RGZ (VQFN)	RKP (VQFN)	UNIT
		48 PINS	40 PINS	
R <sub>0</sub> JA	Junction-to-ambient thermal resistance	25.0	30.9	°C/W <sup>(2)</sup>
R <sub>θ JC(top)</sub>	Junction-to-case (top) thermal resistance	14.5	20.2	°C/W <sup>(2)</sup>
R <sub>0</sub> JB	Junction-to-board thermal resistance	8.7	10.3	°C/W <sup>(2)</sup>
ψJT	Junction-to-top characterization parameter	0.2	0.2	°C/W <sup>(2)</sup>
ψ ЈВ	Junction-to-board characterization parameter	8.6	10.3	°C/W <sup>(2)</sup>
R <sub>θ JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	2.1	2.1	°C/W <sup>(2)</sup>

- (1) For more information about traditional and new thermal metrics, see Semiconductor and IC Package Thermal Metrics.
- (2) °C/W = degrees Celsius per watt.

### 8.9 RF Frequency Bands

Over operating free-air temperature range (unless otherwise noted).

PARAMETER	MIN	TYP MAX	UNIT
Frequency bands	2360	2500	MHz

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# 8.10 Bluetooth Low Energy - Receive (RX)

path. All measurements are p	enormed conducted.  TEST CONDITIONS	MINI TVD	MAY	LINUT
	TEST CONDITIONS	MIN TYP	MAX	UNIT
125 kbps (LE Coded)				
Receiver sensitivity	Differential mode. BER = 10 <sup>-3</sup>	- 104		dBm
Receiver sensitivity	Single ended mode. Measured on CC26x1- P3EM-5XS24, at the SMA connector, BER = 10 <sup>-3</sup>	- 104		dBm
Receiver saturation	Differential mode. BER = 10 <sup>-3</sup>	>5		dBm
Frequency error tolerance	Difference between the incoming carrier frequency and the internally generated carrier frequency	> ( - 300 / 300)		kHz
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (37-byte packets)	> ( - 320 / 240)		ppm
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (255-byte packets)	> ( - 125 / 125)		ppm
Co-channel rejection <sup>(1)</sup>	Wanted signal at - 79 dBm, modulated interferer in channel, BER = 10 - 3	- 1.5		dB
Selectivity, ±1 MHz <sup>(1)</sup>	Wanted signal at - 79 dBm, modulated interferer at ±1 MHz, BER = 10 - 3	8 / 4.5 <sup>(2)</sup>		dB
Selectivity, ±2 MHz <sup>(1)</sup>	Wanted signal at - 79 dBm, modulated interferer at ±2 MHz, BER = 10 <sup>-3</sup>	44 / 39 <sup>(2)</sup>		dB
Selectivity, ±3 MHz <sup>(1)</sup>	Wanted signal at $-79$ dBm, modulated interferer at $\pm 3$ MHz, BER = $10^{-3}$	46 / 44 <sup>(2)</sup>		dB
Selectivity, ±4 MHz <sup>(1)</sup>	Wanted signal at $$ - 79 dBm, modulated interferer at $\pm 4$ MHz, BER = 10 $^{-3}$	44 / 46 <sup>(2)</sup>		dB
Selectivity, ±6 MHz <sup>(1)</sup>	Wanted signal at $$ – 79 dBm, modulated interferer at $ \geqslant \pm 6$ MHz, BER = 10 $^{-3}$	48 / 44 <sup>(2)</sup>		dB
Selectivity, ±7 MHz	Wanted signal at $-79$ dBm, modulated interferer at $\ge \pm 7$ MHz, BER = $10^{-3}$	51 / 45 <sup>(2)</sup>		dB
Selectivity, Image frequency <sup>(1)</sup>	Wanted signal at - 79 dBm, modulated interferer at image frequency, BER = 10 <sup>-3</sup>	39		dB
Selectivity, Image frequency ±1 MHz <sup>(1)</sup>	Note that Image frequency + 1 MHz is the Co- channel - 1 MHz. Wanted signal at - 79 dBm, modulated interferer at ±1 MHz from image frequency, BER = 10 <sup>-3</sup>	4.5 / 44 (2)		dB
500 kbps (LE Coded)				
Receiver sensitivity	Differential mode. BER = 10 <sup>-3</sup>	- 100		dBm
Receiver sensitivity	Single ended mode. Measured on CC26x1- P3EM-5XS24, at the SMA connector, BER = 10 <sup>-3</sup>	- 100		dBm
Receiver saturation	Differential mode. BER = 10 <sup>-3</sup>	> 5		dBm
Frequency error tolerance	Difference between the incoming carrier frequency and the internally generated carrier frequency	> ( - 300 / 300)		kHz
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (37-byte packets)	> ( - 450 / 450)		ppm
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (255-byte packets)	> ( - 175 / 175)		ppm
Co-channel rejection <sup>(1)</sup>	Wanted signal at - 72 dBm, modulated interferer in channel, BER = 10 - 3	- 3.5		dB
Selectivity, ±1 MHz <sup>(1)</sup>	Wanted signal at $$ - 72 dBm, modulated interferer at $\pm 1$ MHz, BER = $10^{-3}$	8 / 4 <sup>(2)</sup>		dB
Selectivity, ±2 MHz <sup>(1)</sup>	Wanted signal at $$ - 72 dBm, modulated interferer at $\pm 2$ MHz, BER = $10^{-3}$	44 / 37 <sup>(2)</sup>		dB
Selectivity, ±3 MHz <sup>(1)</sup>	Wanted signal at $$ - 72 dBm, modulated interferer at $\pm 3$ MHz, BER = 10 $^{-3}$	46 / 46 <sup>(2)</sup>		dB
Selectivity, ±4 MHz <sup>(1)</sup>	Wanted signal at $$ - 72 dBm, modulated interferer at $\pm 4$ MHz, BER = $10^{-3}$	45 / 47 <sup>(2)</sup>		dB
Selectivity, ±6 MHz <sup>(1)</sup>	Wanted signal at $$ – 72 dBm, modulated interferer at $\geqslant\pm6$ MHz, BER = 10 $^{-3}$	46 / 45 <sup>(2)</sup>		dB



# 8.10 Bluetooth Low Energy - Receive (RX) (continued)

When measured on the CC26x1-R3EM-7ID reference design with  $T_c$  = 25 °C,  $V_{DDS}$  = 3.0 V,  $f_{RF}$  = 2440 MHz with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

PARAMETER	TEST CONDITIONS	MIN TYP MA	AX UNIT
Selectivity, ±7 MHz	Wanted signal at $^-$ 72 dBm, modulated interferer at $\ge \pm 7$ MHz, BER = 10 $^-3$	49 / 45 <sup>(2)</sup>	dB
Selectivity, Image frequency <sup>(1)</sup>	Wanted signal at $^-$ 72 dBm, modulated interferer at image frequency, BER = $10^{-3}$	37	dB
Selectivity, Image frequency ±1 MHz <sup>(1)</sup>	Note that Image frequency + 1 MHz is the Co- channel – 1 MHz. Wanted signal at – 72 dBm, modulated interferer at ±1 MHz from image frequency, BER = 10 <sup>-3</sup>	4 / 46 <sup>(2)</sup>	dB
1 Mbps (LE 1M)			
Receiver sensitivity	Differential mode. BER = 10 <sup>-3</sup>	- 97	dBm
Receiver sensitivity	Single ended mode. Measured on CC26x1- P3EM-5XS24, at the SMA connector, BER = 10 - 3	- 97	dBm
Receiver saturation	Differential mode. BER = 10 <sup>-3</sup>	> 5	dBm
Frequency error tolerance	Difference between the incoming carrier frequency and the internally generated carrier frequency	> ( - 350 / 350)	kHz
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (37-byte packets)	> ( - 750 / 750)	ppm
Co-channel rejection <sup>(1)</sup>	Wanted signal at $^-$ 67 dBm, modulated interferer in channel, BER = $10^{-3}$	- 6	dB
Selectivity, ±1 MHz <sup>(1)</sup>	Wanted signal at $^-$ 67 dBm, modulated interferer at $\pm 1$ MHz, BER = $10^{-3}$	7 / 4 <sup>(2)</sup>	dB
Selectivity, ±2 MHz <sup>(1)</sup>	Wanted signal at $^-$ 67 dBm, modulated interferer at ±2 MHz,BER = 10 $^-$ 3	40 / 33 <sup>(2)</sup>	dB
Selectivity, ±3 MHz <sup>(1)</sup>	Wanted signal at $^-$ 67 dBm, modulated interferer at ±3 MHz, BER = $10^{-3}$	36 / 41 <sup>(2)</sup>	dB
Selectivity, ±4 MHz <sup>(1)</sup>	Wanted signal at $^-$ 67 dBm, modulated interferer at ±4 MHz, BER = $10^{-3}$	37 / 45 <sup>(2)</sup>	dB
Selectivity, ±5 MHz or more <sup>(1)</sup>	Wanted signal at $^-$ 67 dBm, modulated interferer at $\ge \pm 5$ MHz, BER = $10^{-3}$	40	dB
Selectivity, image frequency <sup>(1)</sup>	Wanted signal at $-67$ dBm, modulated interferer at image frequency, BER = $10^{-3}$	33	dB
Selectivity, image frequency ±1 MHz <sup>(1)</sup>	Note that Image frequency + 1 MHz is the Co- channel – 1 MHz. Wanted signal at – 67 dBm, modulated interferer at ±1 MHz from image frequency, BER = 10 <sup>-3</sup>	4 / 41 <sup>(2)</sup>	dB
Out-of-band blocking <sup>(3)</sup>	30 MHz to 2000 MHz	- 10	dBm
Out-of-band blocking	2003 MHz to 2399 MHz	- 18	dBm
Out-of-band blocking	2484 MHz to 2997 MHz	- 12	dBm
Out-of-band blocking	3000 MHz to 12.75 GHz	- 2	dBm
Intermodulation	Wanted signal at 2402 MHz, - 64 dBm. Two interferers at 2405 and 2408 MHz respectively, at the given power level	- 42	dBm
Spurious emissions, 30 to 1000 MHz	Measurement in a 50- $\Omega$ single-ended load.	< - 59	dBm
Spurious emissions, 1 to 12.75 GHz	Measurement in a 50- $\Omega$ single-ended load.	< -47	dBm
RSSI dynamic range		70	dB
RSSI accuracy		±4	dB
2 Mbps (LE 2M)			
Receiver sensitivity	Differential mode. Measured at SMA connector, BER = 10 <sup>-3</sup>	- 92	dBm
Receiver sensitivity	Single ended mode. Measured on CC26x1- P3EM-5XS24, at the SMA connector, BER = 10 <sup>-3</sup>	- 92	dBm
Receiver saturation	Differential mode. Measured at SMA connector, BER = 10 - 3	> 5	dBm

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# 8.10 Bluetooth Low Energy - Receive (RX) (continued)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Frequency error tolerance	Difference between the incoming carrier frequency and the internally generated carrier frequency		> ( - 500 / 500)		kHz
Data rate error tolerance	Difference between incoming data rate and the internally generated data rate (37-byte packets)		> ( - 700 / 750)		ppm
Co-channel rejection <sup>(1)</sup>	Wanted signal at - 67 dBm, modulated interferer in channel,BER = 10 <sup>-3</sup>		- 7		dB
Selectivity, ±2 MHz <sup>(1)</sup>	Wanted signal at $-67$ dBm, modulated interferer at $\pm 2$ MHz, Image frequency is at $-2$ MHz, BER = $10^{-3}$		8 / 4 <sup>(2)</sup>		dB
Selectivity, ±4 MHz <sup>(1)</sup>	Wanted signal at $^-$ 67 dBm, modulated interferer at $\pm 4$ MHz, BER = $10^{-3}$		36 / 31(2)		dB
Selectivity, ±6 MHz <sup>(1)</sup>	Wanted signal at $^-$ 67 dBm, modulated interferer at ±6 MHz, BER = 10 $^-$ 3		37 / 36 <sup>(2)</sup>		dB
Selectivity, image frequency <sup>(1)</sup>	Wanted signal at - 67 dBm, modulated interferer at image frequency, BER = 10 <sup>-3</sup>		4		dB
Selectivity, image frequency ±2 MHz <sup>(1)</sup>	Note that Image frequency + 2 MHz is the Co-channel. Wanted signal at - 67 dBm, modulated interferer at ±2 MHz from image frequency, BER = 10 <sup>-3</sup>		- 7 / 36 <sup>(2)</sup>		dB
Out-of-band blocking <sup>(3)</sup>	30 MHz to 2000 MHz		- 16		dBm
Out-of-band blocking	2003 MHz to 2399 MHz		- 21		dBm
Out-of-band blocking	2484 MHz to 2997 MHz		- 15		dBm
Out-of-band blocking	3000 MHz to 12.75 GHz		- 12		dBm
Intermodulation	Wanted signal at 2402 MHz, - 64 dBm. Two interferers at 2408 and 2414 MHz respectively, at the given power level		- 38		dBm

- (1) Numbers given as I/C dB
- (2) X / Y, where X is +N MHz and Y is N MHz
- (3) Excluding one exception at F<sub>wanted</sub> / 2, per Bluetooth Specification



## 8.11 Bluetooth Low Energy - Transmit (TX)

PARAMETER		TEST CONDITIONS	MIN TYP	MAX	UNIT
General Parameters					
Max output power	Differential mode, delivered to a sing	le-ended 50 $\Omega$ load through a balun	5		dBm
Max output power	Single-ended mode. Measured on Coload through a balun	Single-ended mode. Measured on CC26x1-P3EM-5XS24, delivered to a single-ended 50 $^{\Omega}$ load through a balun			dBm
Output power programmable range	Differential mode, delivered to a single-ended 50 $\Omega$ load through a balun		26		dB
Spurious emissions a	and harmonics				
	f < 1 GHz, outside restricted bands		< - 36		dBm
Spurious amissions	f < 1 GHz, restricted bands ETSI		< - 54		dBm
Spurious emissions	f < 1 GHz, restricted bands FCC	I.E. dDm cotting	< - 55		dBm
	f > 1 GHz, including harmonics	- +5 dBm setting	< -42		dBm
Harmaniaa	Second harmonic	< -42		dBm	
Harmonics	Third harmonic		< -42		dBm

# 8.12 Zigbee - IEEE 802.15.4-2006 2.4 GHz (OQPSK DSSS1:8, 250 kbps) - RX

PARAMETER	TEST CONDITIONS	MIN TYP MAX	UNIT
General Parameters			
Receiver sensitivity	Differential mode PER = 1%	- 100	dBm
Receiver sensitivity	Single-Ended mode. Measured on CC26x1-P3EM-5XS24 at the SMA connector. PER = 1%	-99	dBm
Receiver saturation	PER = 1%	> 5	dBm
Adjacent channel rejection	Wanted signal at - 82 dBm, modulated interferer at ±5 MHz, PER = 1%	36	dB
Alternate channel rejection	Wanted signal at - 82 dBm, modulated interferer at ±10 MHz, PER = 1%	57	dB
Channel rejection, ±15 MHz or more	Wanted signal at - 82 dBm, undesired signal is IEEE 802.15.4 modulated channel, stepped through all channels 2405 to 2480 MHz, PER = 1%	59	dB
Blocking and desensitization, 5 MHz from upper band edge	Wanted signal at - 97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%	57	dB
Blocking and desensitization, 10 MHz from upper band edge	Wanted signal at - 97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%	63	dB
Blocking and desensitization, 20 MHz from upper band edge	Wanted signal at - 97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%	63	dB
Blocking and desensitization, 50 MHz from upper band edge	Wanted signal at - 97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%	66	dB
Blocking and desensitization,  - 5 MHz from lower band edge	Wanted signal at - 97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%	60	dB
Blocking and desensitization,  - 10 MHz from lower band edge	Wanted signal at - 97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%	60	dB
Blocking and desensitization,  - 20 MHz from lower band edge	Wanted signal at - 97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%	63	dB
Blocking and desensitization,  - 50 MHz from lower band edge	Wanted signal at - 97 dBm (3 dB above the sensitivity level), CW jammer, PER = 1%	65	dB
Spurious emissions, 30 MHz to 1000 MHz	Measurement in a 50- $\Omega$ single-ended load <sup>(1)</sup>	- 66	dBm
Spurious emissions, 1 GHz to 12.75 GHz	Measurement in a 50- $\Omega$ single-ended load <sup>(1)</sup>	- 53	dBm
Frequency error tolerance	Difference between the incoming carrier frequency and the internally generated carrier frequency	> 350	ppm
Symbol rate error tolerance	Difference between incoming symbol rate and the internally generated symbol rate	> 1000	ppm
RSSI dynamic range		95	dB
RSSI accuracy		±4	dB

<sup>(1)</sup> Suitable for systems targeting compliance with EN 300 328, EN 300 440 class 2, FCC CFR47, Part 15 and ARIB STD-T-66

### 8.13 Zigbee - IEEE 802.15.4-2006 2.4 GHz (OQPSK DSSS1:8, 250 kbps) - TX

When measured on the CC26x1-R3EM-7ID reference design with  $T_c$  = 25 °C,  $V_{DDS}$  = 3.0 V,  $f_{RF}$  = 2440 MHz with DC/DC enabled unless otherwise noted. All measurements are performed at the antenna input with a combined RX and TX path. All measurements are performed conducted.

PARAMETER		TEST CONDITIONS	MIN TYP	MAX UNIT
General Parameters				
Max output power	Differential mode, delivered to a si	ingle-ended 50- $\Omega$ load through a balun	5	dBm
Output power programmable range	Differential mode, delivered to a si	ferential mode, delivered to a single-ended 50- $\Omega$ load through a balun		
Spurious emissions and	harmonics		•	
Spurious emissions (1)	f < 1 GHz, outside restricted bands		< -36	dBm
	f < 1 GHz, restricted bands ETSI		< -47	dBm
	f < 1 GHz, restricted bands FCC	+5 dBm setting	< -55	dBm
	f > 1 GHz, including harmonics		< -42	dBm
Harmaniaa	Second harmonic		< -42	dBm
Harmonics	Third harmonic		< -42	dBm
IEEE 802.15.4-2006 2.4 (	GHz (OQPSK DSSS1:8, 250 kbps)		'	
Error vector magnitude	+5 dBm setting		2	%

<sup>(1)</sup> To ensure margins for passing FCC band edge requirements at 2483.5 MHz, a lower than maximum output-power setting or less than 100% duty cycle may be used when operating at 2480 MHz.

## 8.14 Timing and Switching Characteristics

#### 8.14.1 Reset Timing

PARAMETER	MIN	TYP	MAX	UNIT
RESET_N low duration	1			μs

#### 8.14.2 Wakeup Timing

Measured over operating free-air temperature with  $V_{DDS}$  = 3.0 V (unless otherwise noted). The times listed here do not include software overhead.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
MCU, Reset to Active <sup>(1)</sup>		8:	50 - 4000		μs
MCU, Shutdown to Active <sup>(1)</sup>		8:	50 - 4000		μs
MCU, Standby to Active			160		μs
MCU, Active to Standby			36		μs
MCU, Idle to Active			14		μs

<sup>(1)</sup> The wakeup time is dependent on remaining charge on VDDR capacitor when starting the device, and thus how long the device has been in Reset or Shutdown before starting up again. The wake up time increases with a higher capacitor value.

### 8.14.3 Clock Specifications

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## 8.14.3.1 48 MHz Crystal Oscillator (XOSC\_HF)

Measured on a Texas Instruments reference design with T<sub>c</sub> = 25 °C, V<sub>DDS</sub> = 3.0 V, unless otherwise noted. (1)

moaca	od on d rokao modamento reference decign war 16 20 0, vDDS	0.0 1, 0	o dinor midd moldd.		
	PARAMETER	MIN	TYP	MAX	UNIT
	Crystal frequency		48		MHz
ESR	Equivalent series resistance 6 pF < $C_L \le 9$ pF		20	60	Ω
ESR	Equivalent series resistance $5 \text{ pF} < C_L \le 6 \text{ pF}$			80	Ω
L <sub>M</sub>	Motional inductance, relates to the load capacitance that is used for the crystal (C <sub>L</sub> in Farads) <sup>(5)</sup>		< 3 × 10 <sup>-25</sup> / C <sub>L</sub> <sup>2</sup>		Н
C <sub>L</sub>	Crystal load capacitance <sup>(4)</sup>	5	7 <sup>(3)</sup>	9	pF

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Measured on a Texas Instruments reference design with T<sub>c</sub> = 25 °C, V<sub>DDS</sub> = 3.0 V, unless otherwise noted. (1)

PARAMETER	MIN	TYP MAX	UNIT
Start-up time <sup>(2)</sup>		200	μs

- (1) Probing or otherwise stopping the crystal while the DC/DC converter is enabled may cause permanent damage to the device.
- Start-up time using the TI-provided power driver. Start-up time may increase if driver is not used. (2)
- On-chip default connected capacitance including reference design parasitic capacitance. Connected internal capacitance is changed through software in the Customer Configuration section (CCFG).
- Adjustable load capacitance is integrated into the device.
- The crystal manufacturer's specification must satisfy this requirement for proper operation.

#### 8.14.3.2 48 MHz RC Oscillator (RCOSC\_HF)

Measured on a Texas Instruments reference design with T<sub>c</sub> = 25 °C, V<sub>DDS</sub> = 3.0 V, unless otherwise noted.

	MIN	TYP	MAX	UNIT
Frequency		48		MHz
Uncalibrated frequency accuracy		±1		%
Calibrated frequency accuracy <sup>(1)</sup>		±0.25		%
Start-up time		5		μs

(1) Accuracy relative to the calibration source (XOSC HF)

#### 8.14.3.3 32.768 kHz Crystal Oscillator (XOSC LF)

Measured on a Texas Instruments reference design with T<sub>c</sub> = 25 °C, V<sub>DDS</sub> = 3.0 V, unless otherwise noted.

		MIN	TYP	MAX	UNIT
	Crystal frequency		32.768		kHz
ESR	Equivalent series resistance		30	100	kΩ
CL	Crystal load capacitance	6	7 <sup>(1)</sup>	12	pF

Default load capacitance using TI reference designs including parasitic capacitance. Crystals with different load capacitance may be

#### 8.14.3.4 32 kHz RC Oscillator (RCOSC\_LF)

Measured on a Texas Instruments reference design with T<sub>c</sub> = 25 °C, V<sub>DDS</sub> = 3.0 V, unless otherwise noted.

	······································	,			
		MIN	TYP	MAX	UNIT
Calibrated freq	uency		32.8		kHz
Calibrated RTC variation <sup>(1)</sup>	Calibrated periodically against XOSC_HF <sup>(2)</sup>		±600 <sup>(3)</sup>		ppm
Temperature co	pefficient.		50		ppm/°C

- When using RCOSC LF as source for the low frequency system clock (SCLK LF), the accuracy of the SCLK LF-derived Real Time Clock (RTC) can be improved by measuring RCOSC\_LF relative to XOSC\_HF and compensating for the RTC tick speed. This functionality is available through the TI-provided Power driver.
- TI driver software calibrates the RTC every time XOSC HF is enabled.
- (3) Some device's variation can exceed 1000 ppm. Further calibration will not improve variation.

#### 8.14.4 Synchronous Serial Interface (SSI) Characteristics

### 8.14.4.1 Synchronous Serial Interface (SSI) Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER NO.	PARAMETER		MIN	TYP	MAX	UNIT
S1	t <sub>clk_per</sub>	SSICIk cycle time	12		65024	System Clocks (2)
S2 <sup>(1)</sup>	t <sub>clk_high</sub>	SSICIk high time		0.5		t <sub>clk_per</sub>
S3 <sup>(1)</sup>	t <sub>clk_low</sub>	SSICIk low time		0.5		t <sub>clk_per</sub>

Refer to SSI timing diagrams 图 8-1, 图 8-2, and 图 8-3.

When using the TI-provided Power driver, the SSI system clock is always 48 MHz.



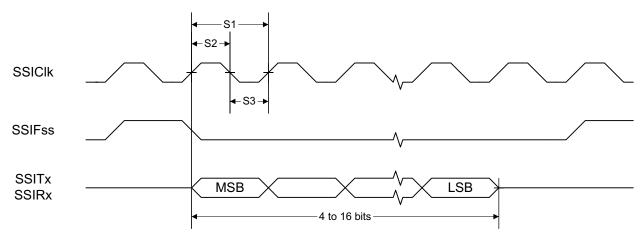


图 8-1. SSI Timing for TI Frame Format (FRF = 01), Single Transfer Timing Measurement

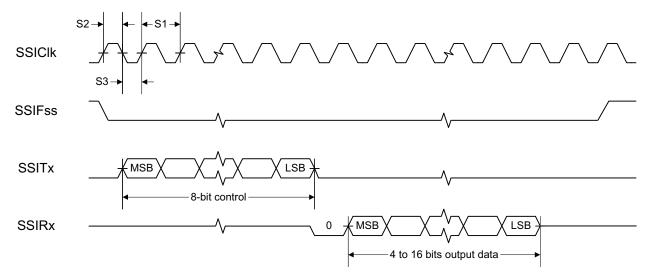


图 8-2. SSI Timing for MICROWIRE Frame Format (FRF = 10), Single Transfer

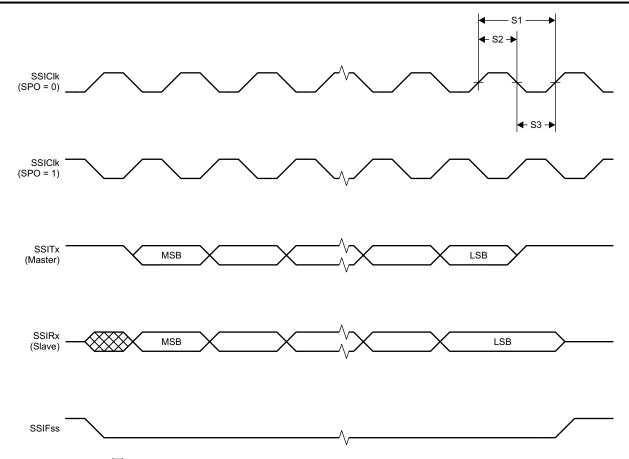


图 8-3. SSI Timing for SPI Frame Format (FRF = 00), With SPH = 1

#### 8.14.5 UART

#### 8.14.5.1 UART Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER	MIN	TYP	MAX	UNIT
UART rate			MBaud	



# 8.15 Peripheral Characteristics

## 8.15.1 ADC

## 8.15.1.1 Analog-to-Digital Converter (ADC) Characteristics

 $T_c$  = 25 °C,  $V_{DDS}$  = 3.0 V and voltage scaling enabled, unless otherwise noted.<sup>(1)</sup> Performance numbers require use of offset and gain adjustements in software by TI-provided ADC drivers.

	PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
	Input voltage range		0	VDDS	V
	Resolution		12		Bits
	Sample Rate			200	ksps
	Offset	Internal 4.3 V equivalent reference <sup>(2)</sup>	- 0.24		LSB
	Gain error	Internal 4.3 V equivalent reference <sup>(2)</sup>	7.14		LSB
DNL <sup>(4)</sup>	Differential nonlinearity		> - 1		LSB
INL	Integral nonlinearity		±4		LSB
		Internal 4.3 V equivalent reference <sup>(2)</sup> , 200 kSamples/s, 9.6 kHz input tone	9.8		
		Internal 4.3 V equivalent reference <sup>(2)</sup> , 200 kSamples/s, 9.6 kHz input tone, DC/DC enabled	9.8		
		VDDS as reference, 200 kSamples/s, 9.6 kHz input tone	10.1		
ENOB	Effective number of bits	Internal reference, voltage scaling disabled, 32 samples average (software), 200 kSamples/s, 300 Hz input tone	11.1		Bits
		Internal reference, voltage scaling disabled, 14-bit mode, 200 kSamples/s, 300 Hz input tone <sup>(5)</sup>	11.3		
		Internal reference, voltage scaling disabled, 15-bit mode, 200 kSamples/s, 300 Hz input tone <sup>(5)</sup>	11.6		
		Internal 4.3 V equivalent reference <sup>(2)</sup> , 200 kSamples/s, 9.6 kHz input tone	- 65		
THD	Total harmonic distortion	VDDS as reference, 200 kSamples/s, 9.6 kHz input tone	- 70		dB
		Internal reference, voltage scaling disabled, 32 samples average, 200 kSamples/s, 300 Hz input tone	- 72		
	Signal-to-noise and distortion ratio	Internal 4.3 V equivalent reference <sup>(2)</sup> , 200 kSamples/s, 9.6 kHz input tone	60		
SINAD,		VDDS as reference, 200 kSamples/s, 9.6 kHz input tone	63		dB
SNDR		Internal reference, voltage scaling disabled, 32 samples average (software), 200 kSamples/s, 300 Hz input tone	68		
		Internal 4.3 V equivalent reference <sup>(2)</sup> , 200 kSamples/s, 9.6 kHz input tone	70		
SFDR	Spurious-free dynamic range	VDDS as reference, 200 kSamples/s, 9.6 kHz input tone	73		dB
		Internal reference, voltage scaling disabled, 32 samples average (software), 200 kSamples/s, 300 Hz input tone	75		
	Conversion time	Serial conversion, time-to-output, 24 MHz clock	50		Clock Cycles
	Current consumption	Internal 4.3 V equivalent reference <sup>(2)</sup>	0.39		mA
	Current consumption	VDDS as reference	0.56		mA
	Reference voltage	Equivalent fixed internal reference (input voltage scaling enabled). For best accuracy, the ADC conversion should be initiated through the TI-RTOS API in order to include the gain/ offset compensation factors stored in FCFG1	4.3(2)(3)		V
	Reference voltage	Fixed internal reference (input voltage scaling disabled). For best accuracy, the ADC conversion should be initiated through the TI-RTOS API in order to include the gain/offset compensation factors stored in FCFG1. This value is derived from the scaled value (4.3 V) as follows: $V_{ref} = 4.3 \text{ V} \times 1408 / 4095$	1.48		V
	Reference voltage	VDDS as reference, input voltage scaling enabled	VDDS		V
			VDDS /		

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## 8.15.1.1 Analog-to-Digital Converter (ADC) Characteristics (continued)

 $T_c$  = 25 °C,  $V_{DDS}$  = 3.0 V and voltage scaling enabled, unless otherwise noted.<sup>(1)</sup>

Performance numbers require use of offset and gain adjustements in software by TI-provided ADC drivers.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Input impedance	200 kSamples/s, voltage scaling enabled. Capacitive input, Input impedance depends on sampling frequency and sampling time		>1		ΜΩ

- (1) Using IEEE Std 1241-2010 for terminology and test methods
- (2) Input signal scaled down internally before conversion, as if voltage range was 0 to 4.3 V
- (3) Applied voltage must be within Absolute Maximum Ratings at all times
- (4) No missing codes
- (5) ADC output =  $\Sigma$  (4<sup>n</sup> samples ) >> n, n = desired extra bits

#### 8.15.2 DAC

#### 8.15.2.1 Digital-to-Analog Converter (DAC) Characteristics

 $T_c$  = 25 °C,  $V_{DDS}$  = 3.0 V, unless otherwise noted

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Genera	Parameters					
	Resolution			8		Bits
		Any load, any V <sub>REF</sub> , pre-charge OFF, DAC charge-pump ON	1.8		3.8	
$V_{DDS}$	Supply voltage	External Load <sup>(4)</sup> , any V <sub>REF</sub> , pre-charge OFF, DAC charge-pump OFF	2.0		3.8	V
		Any load, V <sub>REF</sub> = DCOUPL, pre-charge ON	2.6		3.8	
	Clask fraguency	Buffer ON (recommended for external load)	16		250	kHz
DAC	Clock frequency	Buffer OFF (internal load)	16		1000	KHZ
	Valtage output settling time	V <sub>REF</sub> = VDDS, buffer OFF, internal load		13		4 / 5
	Voltage output settling time	V <sub>REF</sub> = VDDS, buffer ON, external capacitive load = 20 pF <sup>(3)</sup>		13.8		1 / F <sub>DAC</sub>
	External capacitive load			20	200	pF
	External resistive load		10			ΜΩ
	Short circuit current				400	μA
	Max output impedance Vref = VDDS, buffer ON, CLK 250 kHz	VDDS = 3.8 V, DAC charge-pump OFF		50.8		
		VDDS = 3.0 V, DAC charge-pump ON		51.7		kΩ
		VDDS = 3.0 V, DAC charge-pump OFF		53.2		
MAX		VDDS = 2.0 V, DAC charge-pump ON		48.7		
		VDDS = 2.0 V, DAC charge-pump OFF		70.2		
		VDDS = 1.8 V, DAC charge-pump ON		46.3		
		VDDS = 1.8 V, DAC charge-pump OFF		88.9		
nternal	Load - Continuous Time Com	parator / Low Power Clocked Comparator			'	
DNL	Differential nonlinearity	V <sub>REF</sub> = VDDS, load = Continuous Time Comparator or Low Power Clocked Comparator F <sub>DAC</sub> = 250 kHz		±1		L CD(1)
	Differential nonlinearity	V <sub>REF</sub> = VDDS, load = Continuous Time Comparator or Low Power Clocked Comparator F <sub>DAC</sub> = 16 kHz		±1.2		LSB <sup>(1)</sup>
		V <sub>REF</sub> = VDDS = 3.8 V		±0.64		
		V <sub>REF</sub> = VDDS= 3.0 V		±0.81		
	Offset error <sup>(2)</sup> Load = Continuous Time	V <sub>REF</sub> = VDDS = 1.8 V		±1.27		LSB <sup>(1)</sup>
	Comparator	V <sub>REF</sub> = DCOUPL, pre-charge ON		±3.43		LOD(1)
		V <sub>REF</sub> = DCOUPL, pre-charge OFF		±2.88		
		V <sub>REF</sub> = ADCREF		±2.37		



## 8.15.2.1 Digital-to-Analog Converter (DAC) Characteristics (continued)

 $T_c$  = 25 °C,  $V_{DDS}$  = 3.0 V, unless otherwise noted.

	PARAMETER	TEST CONDITIONS	MIN TYP MAX	UNIT
		V <sub>REF</sub> = VDDS= 3.8 V	±0.78	
		V <sub>REF</sub> = VDDS = 3.0 V	±0.77	
	Offset error <sup>(2)</sup> Load = Low Power Clocked	V <sub>REF</sub> = VDDS= 1.8 V	±3.46	LSB <sup>(1)</sup>
	Comparator	V <sub>REF</sub> = DCOUPL, pre-charge ON	±3.44	LOD
		V <sub>REF</sub> = DCOUPL, pre-charge OFF	±4.70	
		V <sub>REF</sub> = ADCREF	±4.11	
		V <sub>REF</sub> = VDDS = 3.8 V	±1.53	
	Max code output voltage	V <sub>REF</sub> = VDDS = 3.0 V	±1.71	
	variation <sup>(2)</sup>	V <sub>REF</sub> = VDDS= 1.8 V	±2.10	LSB <sup>(1)</sup>
	Load = Continuous Time Comparator	V <sub>REF</sub> = DCOUPL, pre-charge ON	±6.00	LODO
	Comparator	V <sub>REF</sub> = DCOUPL, pre-charge OFF	±3.85	
		V <sub>REF</sub> = ADCREF	±5.84	
		V <sub>REF</sub> = VDDS= 3.8 V	±2.92	
		V <sub>REF</sub> =VDDS= 3.0 V	±3.06	
	Max code output voltage variation <sup>(2)</sup>	V <sub>REF</sub> = VDDS= 1.8 V	±3.91	L OD(1)
	Load = Low Power Clocked	V <sub>REF</sub> = DCOUPL, pre-charge ON	±7.84	LSB <sup>(1)</sup>
	Comparator	V <sub>REF</sub> = DCOUPL, pre-charge OFF	±4.06	
		V <sub>REF</sub> = ADCREF	±6.94	
		V <sub>REF</sub> = VDDS = 3.8 V, code 1	0.03	
		V <sub>REF</sub> = VDDS = 3.8 V, code 255	3.62	
		V <sub>REF</sub> = VDDS= 3.0 V, code 1	0.02	
		V <sub>REF</sub> = VDDS= 3.0 V, code 255	2.86	
		V <sub>REF</sub> = VDDS= 1.8 V, code 1	0.01	
	Output voltage range <sup>(2)</sup>	V <sub>REF</sub> = VDDS = 1.8 V, code 255	1.71	
	Load = Continuous Time Comparator	V <sub>REF</sub> = DCOUPL, pre-charge OFF, code 1	0.01	V
		V <sub>REF</sub> = DCOUPL, pre-charge OFF, code 255	1.21	
		V <sub>REF</sub> = DCOUPL, pre-charge ON, code 1	1.27	
		V <sub>REF</sub> = DCOUPL, pre-charge ON, code 255	2.46	
		V <sub>REF</sub> = ADCREF, code 1	0.01	
		V <sub>REF</sub> = ADCREF, code 255	1.41	
		V <sub>REF</sub> = VDDS = 3.8 V, code 1	0.03	
		V <sub>REF</sub> = VDDS= 3.8 V, code 255	3.61	
		V <sub>REF</sub> = VDDS= 3.0 V, code 1	0.02	
		V <sub>REF</sub> = VDDS= 3.0 V, code 255	2.85	
		V <sub>REF</sub> = VDDS = 1.8 V, code 1	0.01	
	Output voltage range <sup>(2)</sup>	V <sub>REF</sub> = VDDS = 1.8 V, code 255	1.71	
	Load = Low Power Clocked Comparator	V <sub>REF</sub> = DCOUPL, pre-charge OFF, code 1	0.01	V
	Comparator	V <sub>REF</sub> = DCOUPL, pre-charge OFF, code 255	1.21	
		V <sub>REF</sub> = DCOUPL, pre-charge ON, code 1	1.27	
		V <sub>REF</sub> = DCOUPL, pre-charge ON, code 255	2.46	
		V <sub>REF</sub> = ADCREF, code 1	0.01	
		V <sub>REF</sub> = ADCREF, code 255	1.41	
erna	_	TIES .		
	The Conjugation of the Mark	V <sub>REF</sub> = VDDS, F <sub>DAC</sub> = 250 kHz	±1	
	Integral nonlinearity	$V_{REF} = V_{DAC} + V_{DAC} = 250 \text{ kHz}$	±1	LSB <sup>(1)</sup>
	og. aoounty	V <sub>REF</sub> = DOCREF, F <sub>DAC</sub> = 250 kHz	±1	_00
	Differential nonlinearity	V <sub>REF</sub> = VDDS, F <sub>DAC</sub> = 250 kHz	±1	LSB <sup>(1)</sup>

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## 8.15.2.1 Digital-to-Analog Converter (DAC) Characteristics (continued)

 $T_c = 25$  °C,  $V_{DDS} = 3.0$  V, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
	V <sub>REF</sub> = VDDS= 3.8 V	±0.20		
	V <sub>REF</sub> = VDDS= 3.0 V	±0.25		
Offset error	V <sub>REF</sub> = VDDS = 1.8 V	±0.45		LSB <sup>(1)</sup>
Oliset error	V <sub>REF</sub> = DCOUPL, pre-charge ON	±1.55		LSB(1)
	V <sub>REF</sub> = DCOUPL, pre-charge OFF	±1.30		
	V <sub>REF</sub> = ADCREF	±1.10		
	V <sub>REF</sub> = VDDS= 3.8 V	±0.60		
	V <sub>REF</sub> = VDDS= 3.0 V	±0.55		
Max code output voltage	V <sub>REF</sub> = VDDS= 1.8 V	±0.60		LSB <sup>(1)</sup>
variation	V <sub>REF</sub> = DCOUPL, pre-charge ON	±3.45		LSB(I)
	V <sub>REF</sub> = DCOUPL, pre-charge OFF	±2.10		
	V <sub>REF</sub> = ADCREF	±1.90		
	V <sub>REF</sub> = VDDS = 3.8 V, code 1	0.03		
	V <sub>REF</sub> = VDDS = 3.8 V, code 255	3.61		
	V <sub>REF</sub> = VDDS = 3.0 V, code 1	0.02		
	V <sub>REF</sub> = VDDS= 3.0 V, code 255	2.85		
	V <sub>REF</sub> = VDDS= 1.8 V, code 1	0.02		
Output voltage range Load = Low Power Clocked	V <sub>REF</sub> = VDDS = 1.8 V, code 255	1.71		V
Comparator	V <sub>REF</sub> = DCOUPL, pre-charge OFF, code 1	0.02		V
	V <sub>REF</sub> = DCOUPL, pre-charge OFF, code 255	1.20		
	V <sub>REF</sub> = DCOUPL, pre-charge ON, code 1	1.27		
	V <sub>REF</sub> = DCOUPL, pre-charge ON, code 255	2.46		
	V <sub>REF</sub> = ADCREF, code 1	0.02		
	V <sub>REF</sub> = ADCREF, code 255	1.42		

 $<sup>1 \;</sup> LSB \; (V_{REF} \; 3.8 \; V/3.0 \; V/1.8 \; V/DCOUPL/ADCREF) = 14.10 \; mV/11.13 \; mV/6.68 \; mV/4.67 \; mV/5.48 \; mV/11.12 \; mV/6.68 \; mV/4.67 \; mV/11.12 \; mV/11.12 \; mV/11.13 \; mV/111.13 \; mV/11.13 \; mV/11.13 \; mV/111.13 \; mV/11.13 \; mV/111.1$ (1)

<sup>(2)</sup> (3)

Includes comparator offset
A load > 20 pF will increases the settling time

<sup>(4)</sup> Keysight 34401A Multimeter



## 8.15.3 Temperature and Battery Monitor

#### 8.15.3.1 Temperature Sensor

Measured on a Texas Instruments reference design with T<sub>c</sub> = 25 °C, V<sub>DDS</sub> = 3.0 V, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Resolution			2		°C
Accuracy	-40 °C to 0 °C		±4.0		°C
Accuracy	0 °C to 105 °C		±2.5		°C
Supply voltage coefficient <sup>(1)</sup>			3.9		°C/V

(1) The temperature sensor is automatically compensated for VDDS variation when using the TI-provided driver.

#### 8.15.3.2 Battery Monitor

Measured on a Texas Instruments reference design with T<sub>c</sub> = 25 °C, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Resolution			25		mV
Range		1.8		3.8	V
Integral nonlinearity (max)			23		mV
Accuracy	VDDS = 3.0 V		22.5		mV
Offset error			-32		mV
Gain error			-1		%

## 8.15.4 Comparator

#### 8.15.4.1 Continuous Time Comparator

 $T_c = 25$ °C,  $V_{DDS} = 3.0$  V, unless otherwise noted.

TO TO STANDING THE PROPERTY OF							
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT		
Input voltage range <sup>(1)</sup>		0		$V_{DDS}$	V		
Offset	Measured at V <sub>DDS</sub> / 2		±5		mV		
Decision time	Step from - 10 mV to 10 mV		0.78		μs		
Current consumption	Internal reference		9.2		μΑ		

The input voltages can be generated externally and connected throughout I/Os or an internal reference voltage can be generated using the DAC

### 8.15.5 GPIO

## 8.15.5.1 GPIO DC Characteristics

PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
T <sub>A</sub> = 25 °C, V <sub>DDS</sub> = 1.8 V				
GPIO VOH at 8 mA load	IOCURR = 2, high-drive GPIOs only	1.56		V
GPIO VOL at 8 mA load	IOCURR = 2, high-drive GPIOs only	0.24		V
GPIO VOH at 4 mA load	IOCURR = 1	1.59		V
GPIO VOL at 4 mA load	IOCURR = 1	0.21		V
GPIO pullup current	Input mode, pullup enabled, Vpad = 0 V	73		μA
GPIO pulldown current	Input mode, pulldown enabled, Vpad = VDDS	19		μA
GPIO low-to-high input transition, with hysteresis	IH = 1, transition voltage for input read as 0 → 1	1.08		V
GPIO high-to-low input transition, with hysteresis	IH = 1, transition voltage for input read as 1 → 0	0.73		V
GPIO input hysteresis	IH = 1, difference between 0 → 1 and 1 → 0 points	0.35		V
T <sub>A</sub> = 25 °C, V <sub>DDS</sub> = 3.0 V				
GPIO VOH at 8 mA load	IOCURR = 2, high-drive GPIOs only	2.59		V
GPIO VOL at 8 mA load	IOCURR = 2, high-drive GPIOs only	0.42		V
GPIO VOH at 4 mA load	IOCURR = 1	2.63		٧
GPIO VOL at 4 mA load	IOCURR = 1	0.40		٧

Product Folder Links: CC2651R3

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## 8.15.5.1 GPIO DC Characteristics (continued)

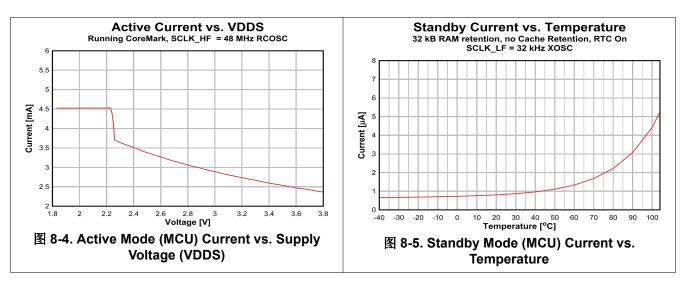
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
T <sub>A</sub> = 25 °C, V <sub>DDS</sub> = 3.8 V				•	
GPIO pullup current	Input mode, pullup enabled, Vpad = 0 V		282		μA
GPIO pulldown current	Input mode, pulldown enabled, Vpad = VDDS		110		μA
GPIO low-to-high input transition, with hysteresis	IH = 1, transition voltage for input read as 0 → 1		1.97		V
GPIO high-to-low input transition, with hysteresis	IH = 1, transition voltage for input read as 1 → 0		1.55		V
GPIO input hysteresis	IH = 1, difference between 0 → 1 and 1 → 0 points		0.42		V
T <sub>A</sub> = 25 °C					
VIH	Lowest GPIO input voltage reliably interpreted as a High	0.8*V <sub>DDS</sub>			V
VIL	Highest GPIO input voltage reliably interpreted as a Low			0.2*V <sub>DDS</sub>	٧



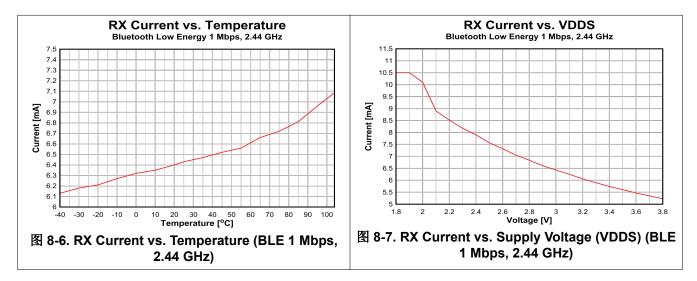
### 8.16 Typical Characteristics

All measurements in this section are done with  $T_c$  = 25 °C and  $V_{DDS}$  = 3.0 V, unless otherwise noted. See *Recommended Operating Conditions*,  $\ddagger$  8.3, for device limits. Values exceeding these limits are for reference only.

#### 8.16.1 MCU Current



#### 8.16.2 RX Current



#### 8.16.3 TX Current

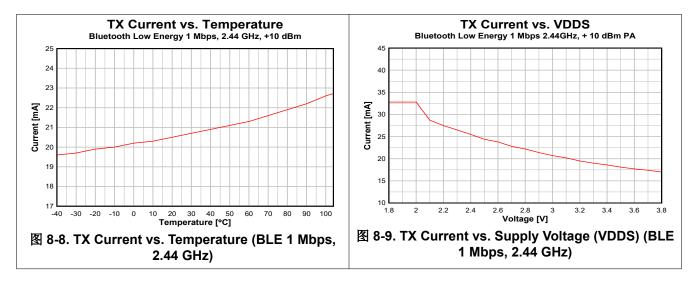


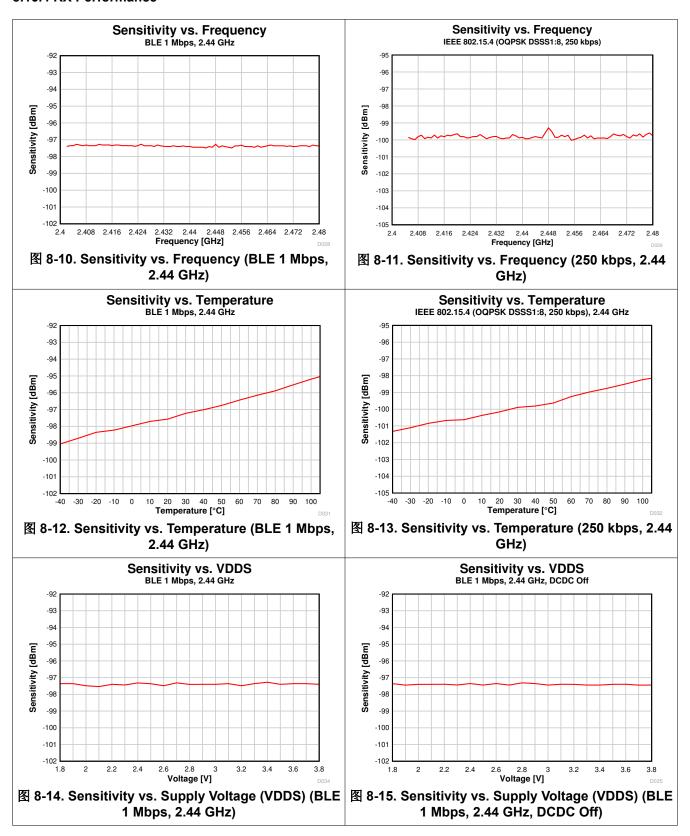
表 8-1 shows typical TX current and output power for different output power settings.

表 8-1. Typical TX Current and Output Power

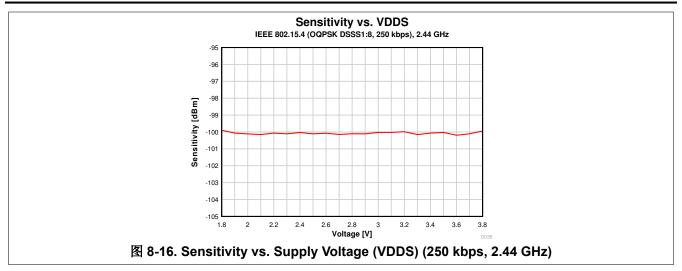
CC2651R3 at 2.4 GHz, VDDS = 3.0 V (Measured on CC26x1-R3EM-7ID)							
txPower							
0x701F	5	5.5	12.5				
0x3A17	4	4.5	11.9				
0x3A64	3	3.1	11.2				
0x325F	2	2.0	10.8				
0x2C5C	1	1.3	10.5				
0x2659	0	0.4	10.2				
0x1697	-3	-2.8	9.4				
0x1693	-5	-4.8	8.9				
0x1292	-6	-5.4	8.8				
0xCD3	-9	-9.0	8.4				
0xAD1	-10	-10.4	8.2				
0xACF	-12	-12.0	8.1				
0x6CD	-15	-13.7	7.9				
0x6CA	-18	-16.8	7.7				
0x4C8	-20	-19.3	7.6				



## 8.16.4 RX Performance

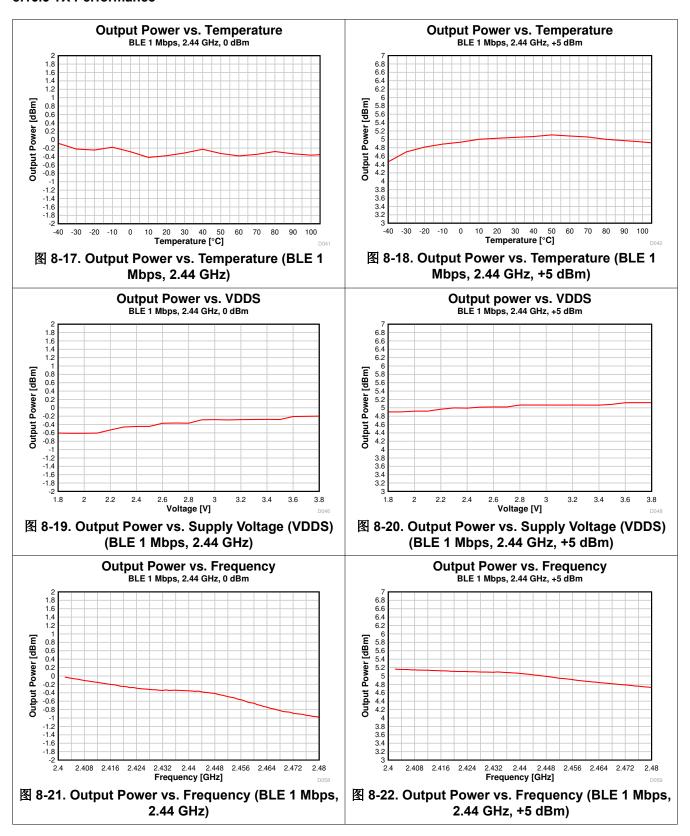




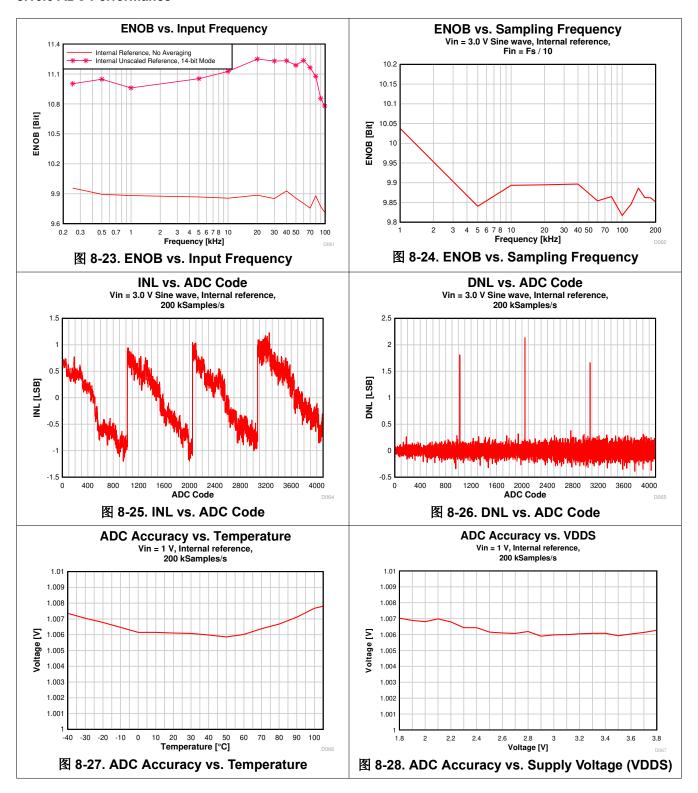




#### 8.16.5 TX Performance



#### 8.16.6 ADC Performance





## 9 Detailed Description

#### 9.1 Overview

节 4 shows the core modules of the CC2651R3 device.

## 9.2 System CPU

The CC2651R3 SimpleLink<sup>™</sup> Wireless MCU contains an Arm<sup>®</sup> Cortex<sup>®</sup>-M4 system CPU, which runs the application and the higher layers of radio protocol stacks.

The system CPU is the foundation of a high-performance, low-cost platform that meets the system requirements of minimal memory implementation, and low-power consumption, while delivering outstanding computational performance and exceptional system response to interrupts.

Its features include the following:

- ARMv7-M architecture optimized for small-footprint embedded applications
- Arm Thumb®-2 mixed 16- and 32-bit instruction set delivers the high performance expected of a 32-bit Arm core in a compact memory size
- · Fast code execution permits increased sleep mode time
- Deterministic, high-performance interrupt handling for time-critical applications
- · Single-cycle multiply instruction and hardware divide
- Hardware division and fast digital-signal-processing oriented multiply accumulate
- Saturating arithmetic for signal processing
- · Full debug with data matching for watchpoint generation
  - Data Watchpoint and Trace Unit (DWT)
  - JTAG Debug Access Port (DAP)
  - Flash Patch and Breakpoint Unit (FPB)
- Trace support reduces the number of pins required for debugging and tracing
  - Instrumentation Trace Macrocell Unit (ITM)
  - Trace Port Interface Unit (TPIU) with asynchronous serial wire output (SWO)
- Optimized for single-cycle flash memory access
- Tightly connected to 8-KB 4-way random replacement cache for minimal active power consumption and wait states
- Ultra-low-power consumption with integrated sleep modes
- 48 MHz operation
- 1.25 DMIPS per MHz

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# 9.3 Radio (RF Core)

The RF Core is a highly flexible and future proof radio module which contains an Arm Cortex-M0 processor that interfaces the analog RF and base-band circuitry, handles data to and from the system CPU side, and assembles the information bits in a given packet structure. The RF core offers a high level, command-based API to the main CPU that configurations and data are passed through. The Arm Cortex-M0 processor is not programmable by customers and is interfaced through the TI-provided RF driver that is included with the SimpleLink Software Development Kit (SDK).

The RF core can autonomously handle the time-critical aspects of the radio protocols, thus offloading the main CPU, which reduces power and leaves more resources for the user application. Several signals are also available to control external circuitry such as RF switches or range extenders autonomously.

The various physical layer radio formats are partly built as a software defined radio where the radio behavior is either defined by radio ROM contents or by non-ROM radio formats delivered in form of firmware patches with the SimpleLink SDKs. This allows the radio platform to be updated for support of future versions of standards even with over-the-air (OTA) updates while still using the same silicon.

## 9.3.1 Bluetooth 5.2 Low Energy

The RF Core offers full support for Bluetooth 5.2 Low Energy, including the high-sped 2-Mbps physical layer and the 500-kbps and 125-kbps long range PHYs (Coded PHY) through the TI provided Bluetooth 5.2 stack or through a high-level Bluetooth API. The Bluetooth 5.2 PHY and part of the controller are in radio and system ROM, providing significant savings in memory usage and more space available for applications.

The new high-speed mode allows data transfers up to 2 Mbps, twice the speed of Bluetooth 4.2 and five times the speed of Bluetooth 4.0, without increasing power consumption. In addition to faster speeds, this mode offers significant improvements for energy efficiency and wireless coexistence with reduced radio communication time.

Bluetooth 5.2 also enables unparalleled flexibility for adjustment of speed and range based on application needs, which capitalizes on the high-speed or long-range modes respectively. Data transfers are now possible at 2 Mbps, enabling development of applications using voice, audio, imaging, and data logging that were not previously an option using Bluetooth low energy. With high-speed mode, existing applications deliver faster responses, richer engagement, and longer battery life. Bluetooth 5.2 enables fast, reliable firmware updates.

## 9.3.2 802.15.4 (Zigbee and 6LoWPAN)

Through a dedicated IEEE radio API, the RF Core supports the 2.4-GHz IEEE 802.15.4-2011 physical layer (2 Mchips per second Offset-QPSK with DSSS 1:8), used in Zigbee and 6LoWPAN protocols. The 802.15.4 PHY and MAC are in radio and system ROM. TI also provides royalty-free protocol stacks for Zigbee as part of the SimpleLink SDK, enabling a robust end-to-end solution.

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## 9.4 Memory

The up to 352-KB nonvolatile (Flash) memory provides storage for code and data. The flash memory is insystem programmable and erasable. The last flash memory sector must contain a Customer Configuration section (CCFG) that is used by boot ROM and TI provided drivers to configure the device. This configuration is done through the ccfg.c source file that is included in all TI provided examples.

The ultra-low leakage system static RAM (SRAM) is a single 32-KB block and can be used for both storage of data and execution of code. Retention of SRAM contents in Standby power mode is enabled by default and included in Standby mode power consumption numbers.

To improve code execution speed and lower power when executing code from nonvolatile memory, a 4-way nonassociative 8-KB cache is enabled by default to cache and prefetch instructions read by the system CPU. The cache can be used as a general-purpose RAM by enabling this feature in the Customer Configuration Area (CCFG).

The ROM contains a serial (SPI and UART) bootloader that can be used for initial programming of the device.

## 9.5 Cryptography

The CC2651R3 device comes with a wide set of cryptography-related hardware accelerators, reducing code footprint and execution time for cryptographic operations. It also has the benefit of being lower power and improves availability and responsiveness of the system because the cryptography operations run in a background hardware thread.

The hardware accelerator modules are:

- True Random Number Generator (TRNG) module provides a true, nondeterministic noise source for the purpose of generating keys, initialization vectors (IVs), and other random number requirements. The TRNG is built on 24 ring oscillators that create unpredictable output to feed a complex nonlinear-combinatorial circuit.
- · Advanced Encryption Standard (AES) with 128 bit key lengths

Together with the hardware accelerator module, a large selection of open-source cryptography libraries provided with the Software Development Kit (SDK), this allows for secure and future proof IoT applications to be easily built on top of the platform. The TI provided cryptography drivers are:

## Key Agreement Schemes

- Elliptic curve Diffie - Hellman with static or ephemeral keys (ECDH and ECDHE)

## Signature Generation

Elliptic curve Diffie-Hellman Digital Signature Algorithm (ECDSA)

## Curve Support

- Short Weierstrass form (full hardware support), such as:
  - NIST-P256
- Montgomery form (hardware support for multiplication), such as:
  - Curve25519

#### Hash

- SHA256

#### MACs

- HMAC with SHA256
- AES CBC-MAC

#### Block ciphers

- AESECB
- AESCBC
- AESCTR

#### Authenticated Encryption

- AESCCM

#### Random number generation

- True Random Number Generator
- AES CTR DRBG



## 9.6 Timers

A large selection of timers are available as part of the CC2651R3 device. These timers are:

#### Real-Time Clock (RTC)

A 70-bit 3-channel timer running on the 32 kHz low frequency system clock (SCLK\_LF) This timer is available in all power modes except Shutdown. The timer can be calibrated to compensate for frequency drift when using the LF RCOSC as the low frequency system clock. If an external LF clock with frequency different from 32.768 kHz is used, the RTC tick speed can be adjusted to compensate for this. When using TI-RTOS, the RTC is used as the base timer in the operating system and should thus only be accessed through the kernel APIs such as the Clock module. By default, the RTC halts when a debugger halts the device.

# General Purpose Timers (GPTIMER)

The four flexible GPTIMERs can be used as either 4× 32 bit timers or 8× 16 bit timers, all running on up to 48 MHz. Each of the 16- or 32-bit timers support a wide range of features such as one-shot or periodic counting, pulse width modulation (PWM), time counting between edges and edge counting. The inputs and outputs of the timer are connected to the device event fabric, which allows the timers to interact with signals such as GPIO inputs, other timers, DMA and ADC. The GPTIMERs are available in Active and Idle power modes.

#### Radio Timer

A multichannel 32-bit timer running at 4 MHz is available as part of the device radio. The radio timer is typically used as the timing base in wireless network communication using the 32-bit timing word as the network time. The radio timer is synchronized with the RTC by using a dedicated radio API when the device radio is turned on or off. This ensures that for a network stack, the radio timer seems to always be running when the radio is enabled. The radio timer is in most cases used indirectly through the trigger time fields in the radio APIs and should only be used when running the accurate 48 MHz high frequency crystal is the source of SCLK HF.

#### Watchdog timer

The watchdog timer is used to regain control if the system operates incorrectly due to software errors. It is typically used to generate an interrupt to and reset of the device for the case where periodic monitoring of the system components and tasks fails to verify proper functionality. The watchdog timer runs on a 1.5 MHz clock rate and cannot be stopped once enabled. The watchdog timer pauses to run in Standby power mode and when a debugger halts the device.

Product Folder Links: CC2651R3

# 9.7 Serial Peripherals and I/O

The SSI is a synchronous serial interface that is compatible with SPI, MICROWIRE, and TI's synchronous serial interfaces. The SSI support both SPI master and slave up to 4 MHz. The SSI module support configurable phase and polarity.

The UART implement universal asynchronous receiver and transmitter functions. It support flexible baud-rate generation up to a maximum of 3 Mbps.

The I<sup>2</sup>S interface is used to handle digital audio and can also be used to interface pulse-density modulation microphones (PDM).

The I<sup>2</sup>C interface is also used to communicate with devices compatible with the I<sup>2</sup>C standard. The I<sup>2</sup>C interface can handle 100 kHz and 400 kHz operation, and can serve as both master and slave.

The I/O controller (IOC) controls the digital I/O pins and contains multiplexer circuitry to allow a set of peripherals to be assigned to I/O pins in a flexible manner. All digital I/Os are interrupt and wake-up capable, have a programmable pullup and pulldown function, and can generate an interrupt on a negative or positive edge (configurable). When configured as an output, pins can function as either push-pull or open-drain. Five GPIOs have high-drive capabilities, which are marked in **bold** in † 7. All digital peripherals can be connected to any digital pin on the device.

For more information, see the CC13x1x3, CC26x1x3 SimpleLink™ Wireless MCU Technical Reference Manual.

# 9.8 Battery and Temperature Monitor

A combined temperature and battery voltage monitor is available in the CC2651R3 device. The battery and temperature monitor allows an application to continuously monitor on-chip temperature and supply voltage and respond to changes in environmental conditions as needed. The module contains window comparators to interrupt the system CPU when temperature or supply voltage go outside defined windows. These events can also be used to wake up the device from Standby mode through the Always-On (AON) event fabric.

## 9.9 μDMA

The device includes a direct memory access ( $\mu$ DMA) controller. The  $\mu$ DMA controller provides a way to offload data-transfer tasks from the system CPU, thus allowing for more efficient use of the processor and the available bus bandwidth. The  $\mu$ DMA controller can perform a transfer between memory and peripherals. The  $\mu$ DMA controller has dedicated channels for each supported on-chip module and can be programmed to automatically perform transfers between peripherals and memory when the peripheral is ready to transfer more data.

Some features of the µDMA controller include the following (this is not an exhaustive list):

- Highly flexible and configurable channel operation of up to 32 channels
- Transfer modes: memory-to-memory, memory-to-peripheral, peripheral-to-memory, and peripheral-to-peripheral
- Data sizes of 8, 16, and 32 bits
- · Ping-pong mode for continuous streaming of data

## 9.10 Debug

The on-chip debug support is done through a dedicated cJTAG (IEEE 1149.7) or JTAG (IEEE 1149.1) interface. The device boots by default into cJTAG mode and must be reconfigured to use 4-pin JTAG.

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# 9.11 Power Management

To minimize power consumption, the CC2651R3 supports a number of power modes and power management features (see  $\frac{1}{8}$  9-1).

SOFTWARE CONFIGURABLE POWER MODES **RESET PIN** MODE HELD **ACTIVE IDLE STANDBY SHUTDOWN CPU** Off Off Off Active Off Flash Off On Available Off Off SRAM On On Retention Off Off Off Off Supply System On On **Duty Cycled** Register and CPU retention Full Full Partial Nο Nο SRAM retention Full Full Full No No 48 MHz high-speed clock XOSC HF or XOSC HF or Off Off Off RCOSC HF (SCLK HF) RCOSC HF 32 kHz low-speed clock XOSC LF or XOSC LF or XOSC LF or Off Off RCOSC LF RCOSC LF RCOSC LF (SCLK LF) Peripherals Available Available Off Off Off Wake-up on RTC Available Available Available Off Wake-up on pin edge Available Available Available Available Off Wake-up on reset pin On On On On On Brownout detector (BOD) On On **Duty Cycled** Off Off Power-on reset (POR) On On On Off Off Available Available Off Watchdog timer (WDT) Paused Off

表 9-1. Power Modes

In **Active** mode, the application system CPU is actively executing code. Active mode provides normal operation of the processor and all of the peripherals that are currently enabled. The system clock can be any available clock source (see 表 9-1).

In **Idle** mode, all active peripherals can be clocked, but the Application CPU core and memory are not clocked and no code is executed. Any interrupt event brings the processor back into active mode.

In **Standby** mode, only the always-on (AON) domain is active. An external wake-up event or RTC event is required to bring the device back to active mode. MCU peripherals with retention do not need to be reconfigured when waking up again, and the CPU continues execution from where it went into standby mode. All GPIOs are latched in standby mode.

In **Shutdown** mode, the device is entirely turned off (including the AON domain), and the I/Os are latched with the value they had before entering shutdown mode. A change of state on any I/O pin defined as a *wake from shutdown pin* wakes up the device and functions as a reset trigger. The CPU can differentiate between reset in this way and reset-by-reset pin or power-on reset by reading the reset status register. The only state retained in this mode is the latched I/O state and the flash memory contents.

#### 备注

The power, RF and clock management for the CC2651R3 device require specific configuration and handling by software for optimized performance. This configuration and handling is implemented in the TI-provided drivers that are part of the CC2651R3 software development kit (SDK). Therefore, TI highly recommends using this software framework for all application development on the device. The complete SDK with TI-RTOS (optional), device drivers, and examples are offered free of charge in source code.

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# 9.12 Clock Systems

The CC2651R3 device has several internal system clocks.

The 48 MHz SCLK\_HF is used as the main system (MCU and peripherals) clock. This can be driven by the internal 48 MHz RC Oscillator (RCOSC\_HF) or an external 48 MHz crystal (XOSC\_HF). Radio operation requires an external 48 MHz crystal.

SCLK\_LF is the 32.768 kHz internal low-frequency system clock. It can be used for the RTC and to synchronize the radio timer before or after Standby power mode. SCLK\_LF can be driven by the internal 32.8 kHz RC Oscillator (RCOSC LF), a 32.768 kHz watch-type crystal, or a clock input on any digital IO.

When using a crystal or the internal RC oscillator, the device can output the 32 kHz SCLK\_LF signal to other devices, thereby reducing the overall system cost.

#### 9.13 Network Processor

Depending on the product configuration, the CC2651R3 device can function as a wireless network processor (WNP - a device running the wireless protocol stack with the application running on a separate host MCU), or as a system-on-chip (SoC) with the application and protocol stack running on the system CPU inside the device.

In the first case, the external host MCU communicates with the device using SPI or UART. In the second case, the application must be written according to the application framework supplied with the wireless protocol stack.



# 10 Application, Implementation, and Layout

## 备注

以下应用部分中的信息不属于 TI 器件规格的范围, TI 不担保其准确性和完整性。TI 的客户应负责确定器件是否适用于其应用。客户应验证并测试其设计,以确保系统功能。

For general design guidelines and hardware configuration guidelines, refer to CC13xx/CC26xx Hardware Configuration and PCB Design Considerations Application Report.

# 10.1 Reference Designs

The following reference designs should be followed closely when implementing designs using the CC2651R3 device.

Special attention must be paid to RF component placement, decoupling capacitors and DCDC regulator components, as well as ground connections for all of these.

CC26x1-R3EM-7ID Design Files

The CC26x1-R3EM-7ID reference design provides schematic, layout and production files for the characterization board used for deriving the performance number found in this document.

CC26x1-P3EM-5XS24-PA24\_10dBm Design Files

The CC26x1PEM-5XS24-PA24\_10dBm reference design provides schematic, layout and production files for the characterization board used for deriving the performance number found in this document. This design is optimized for operating the high power PA at 10 dBm output power and is using a single-ended front-end configuration with external LNA bias for RX.

LP-CC2651P3 Design Files

The CC2651P3 LaunchPad Design Files contain detailed schematics and layouts to build application specific boards using the CC2651P3 device.

Sub-1 GHz and 2.4 GHz Antenna Kit for LaunchPad™ Development Kit and SensorTag

The antenna kit allows real-life testing to identify the optimal antenna for your application. The antenna kit includes 16 antennas for frequencies from 169 MHz to 2.4 GHz, including:

- · PCB antennas
- · Helical antennas
- · Chip antennas
- Dual-band antennas for 868 MHz and 915 MHz combined with 2.4 GHz

The antenna kit includes a JSC cable to connect to the Wireless MCU LaunchPad Development Kits and SensorTags.

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# **10.2 Junction Temperature Calculation**

This section shows the different techniques for calculating the junction temperature under various operating conditions. For more details, see Semiconductor and IC Package Thermal Metrics.

There are three recommended ways to derive the junction temperature from other measured temperatures:

1. From package temperature:

$$T_I = \psi_{\rm IT} \times P + T_{\rm case} \tag{1}$$

2. From board temperature:

$$T_I = \psi_{\rm IB} \times P + T_{\rm board} \tag{2}$$

3. From ambient temperature:

$$T_I = R_{\theta IA} \times P + T_A \tag{3}$$

P is the power dissipated from the device and can be calculated by multiplying current consumption with supply voltage. Thermal resistance coefficients are found in *Thermal Resistance Characteristics*.

#### **Example:**

Using 方程式 3, the temperature difference between ambient temperature and junction temperature is calculated. In this example, we assume a simple use case where the radio is transmitting continuously at 0 dBm output power. Let us assume the ambient temperature is 85°C and the supply voltage is 3 V. To calculate P, we need to look up the current consumption for Tx at 85°C in 88-8. From the plot, we see that the current consumption is 7.8 mA. This means that P is 7.8 mA × 3 V = 23.4 mW.

The junction temperature is then calculated as:

$$T_I = 23.4^{\circ} C/_W \times 23.4 mW + T_A = 0.6^{\circ} C + T_A$$
 (4)

As can be seen from the example, the junction temperature is 0.6 °C higher than the ambient temperature when running continuous Tx at 85°C and, thus, well within the recommended operating conditions.

For various application use cases current consumption for other modules may have to be added to calculate the appropriate power dissipation. For example, the MCU may be running simultaneously as the radio, peripheral modules may be enabled, etc. Typically, the easiest way to find the peak current consumption, and thus the peak power dissipation in the device, is to measure as described in Measuring CC13xx and CC26xx current consumption.

# 11 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed as follows.

## 11.1 Device Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to all part numbers and/or date-code. Each device has one of three prefixes/identifications: X, P, or null (no prefix) (for example, XCC2651R3 is in preview; therefore, an X prefix/identification is assigned).

Device development evolutionary flow:

- **X** Experimental device that is not necessarily representative of the final device's electrical specifications and may not use production assembly flow.
- **P** Prototype device that is not necessarily the final silicon die and may not necessarily meet final electrical specifications.

**null** Production version of the silicon die that is fully qualified.

Support tool development evolutionary flow:

**TMDX** Development-support product that has not yet completed Texas Instruments internal qualification testing.

**TMDS** Fully-qualified development-support product.

X and P devices and TMDX development-support tools are shipped against the following disclaimer:

"Developmental product is intended for internal evaluation purposes."

Production devices and TMDS development-support tools have been characterized fully, and the quality and reliability of the device have been demonstrated fully. Tl's standard warranty applies.

Predictions show that prototype devices (X or P) have a greater failure rate than the standard production devices. Texas Instruments recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

TI device nomenclature also includes a suffix with the device family name. This suffix indicates the package type (for example, *RGZ*).

For orderable part numbers of *CC2651R3* devices in the RGZ (7-mm x 7-mm) package type, see the *Package Option Addendum* of this document, the Device Information in † 3, the TI website (www.ti.com), or contact your TI sales representative.

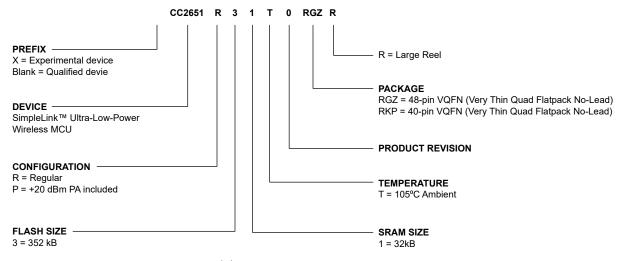


图 11-1. Device Nomenclature

#### 11.2 Tools and Software

The CC2651R3 device is supported by a variety of software and hardware development tools.

# **Development Kit**

CC2651P3 LaunchPad™ Development Kit

The CC2651P3 LaunchPad™ Development Kit enables development of high-performance wireless applications that benefit from low-power operation. The kit features the CC2651P3 SimpleLink Wireless MCU, which allows you to quickly evaluate and prototype 2.4-GHz wireless applications such as Bluetooth 5 Low Energy, Zigbee and Thread, plus combinations of these. The kit works with the LaunchPad ecosystem, easily enabling additional functionality like sensors, display and more.

#### **Software**

SimpleLink™ CC13XX-CC26XX SDK

The SimpleLink CC13xx and CC26xx Software Development Kit (SDK) provides a complete package for the development of wireless applications on the CC13XX / CC26XX family of devices. The SDK includes a comprehensive software package for the CC2651R3 device, including the following protocol stacks:

- Bluetooth Low Energy 4 and 5.2
- · Thread (based on OpenThread)
- Zigbee 3.0
- Wi-SUN®
- TI 15.4-Stack an IEEE 802.15.4-based star networking solution for Sub-1 GHz and 2.4 GHz
- Proprietary RF a large set of building blocks for building proprietary RF software
- Multiprotocol support concurrent operation between stacks using the Dynamic Multiprotocol Manager (DMM)

The SimpleLink CC13XX-CC26XX SDK is part of TI's SimpleLink MCU platform, offering a single development environment that delivers flexible hardware, software and tool options for customers developing wired and wireless applications. For more information about the SimpleLink MCU Platform, visit <a href="http://www.ti.com/simplelink">http://www.ti.com/simplelink</a>.

## **Development Tools**

Code Composer Studio™ Integrated Development Environment (IDE)

Code Composer Studio is an integrated development environment (IDE) that supports TI's Microcontroller and Embedded Processors portfolio. Code Composer Studio comprises a suite of tools used to develop and debug embedded applications. It includes an optimizing C/C++ compiler, source code editor, project build environment, debugger, profiler, and many other features. The intuitive IDE provides a single user interface taking you through each step of the application development flow. Familiar tools and interfaces allow users to get started faster than ever before. Code Composer Studio combines the advantages of the Eclipse® software framework with advanced embedded debug capabilities from TI resulting in a compelling feature-rich development environment for embedded developers.

CCS has support for all SimpleLink Wireless MCUs and includes support for EnergyTrace™ software (application energy usage profiling). A real-time object viewer plugin is available for TI-RTOS, part of the SimpleLink SDK.

Code Composer Studio is provided free of charge when used in conjunction with the XDS debuggers included on a LaunchPad Development Kit.

Code Composer Studio™ Cloud IDE

Code Composer Studio (CCS) Cloud is a web-based IDE that allows you to create, edit and build CCS and Energia™ projects. After you have successfully built your project, you can download and run on your connected LaunchPad. Basic debugging, including features like setting breakpoints and viewing variable values is now supported with CCS Cloud.

IAR Embedded Workbench® for Arm®

IAR Embedded Workbench® is a set of development tools for building and debugging embedded system applications using assembler, C and C++. It provides a completely integrated development environment that includes a project manager, editor, and build tools. IAR has support for all SimpleLink Wireless MCUs. It offers broad debugger support, including XDS110, IAR I-jet $^{\text{IM}}$  and Segger J-Link $^{\text{IM}}$ . A real-time object viewer plugin is available for TI-RTOS, part of the SimpleLink SDK. IAR is also supported out-of-the-box on most software examples provided as part of the SimpleLink SDK.

A 30-day evaluation or a 32 KB size-limited version is available through iar.com.

#### SmartRF™ Studio

SmartRF™ Studio is a Windows® application that can be used to evaluate and configure SimpleLink Wireless MCUs from Texas Instruments. The application will help designers of RF systems to easily evaluate the radio at an early stage in the design process. It is especially useful for generation of configuration register values and for practical testing and debugging of the RF system. SmartRF Studio can be used either as a standalone application or together with applicable evaluation boards or debug probes for the RF device. Features of the SmartRF Studio include:

- Link tests send and receive packets between nodes
- · Antenna and radiation tests set the radio in continuous wave TX and RX states
- Export radio configuration code for use with the TI SimpleLink SDK RF driver
- Custom GPIO configuration for signaling and control of external switches

# **CCS UniFlash**

CCS UniFlash is a standalone tool used to program on-chip flash memory on TI MCUs. UniFlash has a GUI, command line, and scripting interface. CCS UniFlash is available free of charge.

## 11.2.1 SimpleLink™ Microcontroller Platform

The SimpleLink microcontroller platform sets a new standard for developers with the broadest portfolio of wired and wireless Arm<sup>®</sup> MCUs (System-on-Chip) in a single software development environment. Delivering flexible hardware, software and tool options for your IoT applications. Invest once in the SimpleLink software development kit and use throughout your entire portfolio. Learn more on ti.com/simplelink.

## 11.3 Documentation Support

To receive notification of documentation updates on data sheets, errata, application notes and similar, navigate to the device product folder on ti.com/product/CC2651R3. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

The current documentation that describes the MCU, related peripherals, and other technical collateral is listed as follows.

## **TI Resource Explorer**

TI Resource Explorer

Software examples, libraries, executables, and documentation are available for your device and development board.

#### **Errata**

CC2651R3 Silicon Errata

The silicon errata describes the known exceptions to the functional specifications for each silicon revision of the device and description on how to recognize a device revision.

## **Application Reports**

All application reports for the CC2651R3 device are found on the device product folder at: ti.com/product/CC2651R3/#tech-docs.

#### **Technical Reference Manual (TRM)**

CC13x1x, CC26x1x SimpleLink™ Wireless MCU TRM

The TRM provides a detailed description of all modules and peripherals available in the device family.

## 11.4 支持资源

TI E2E<sup>™</sup> 支持论坛是工程师的重要参考资料,可直接从专家获得快速、经过验证的解答和设计帮助。搜索现有解答或提出自己的问题可获得所需的快速设计帮助。

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Arm Thumb® is a registered trademark of Arm Limited (or its subsidiaries).

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# 11.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

# 11.7 术语表

TI术语表

本术语表列出并解释了术语、首字母缩略词和定义。

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# 12 Mechanical, Packaging, and Orderable Information

www.ti.com 23-May-2025

## **PACKAGING INFORMATION**

Orderable part number	Status (1)	Material type	Package   Pins	Package qty   Carrier	<b>RoHS</b> (3)	Lead finish/ Ball material	MSL rating/ Peak reflow	Op temp (°C)	Part marking (6)
CC2651R31T0RGZR	Active	Production	VQFN (RGZ)   48	2500   LARGE T&R	Yes	NIPDAU	(5) Level-3-260C-168 HR	-40 to 105	CC2651 R31
CC2651R31T0RGZR.A	Active	Production	VQFN (RGZ)   48	2500   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2651 R31
CC2651R31T0RGZR.B	Active	Production	VQFN (RGZ)   48	2500   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2651 R31
CC2651R31T0RKPR	Active	Production	VQFN (RKP)   40	3000   LARGE T&R	Yes	NIPDAU   NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2651 R31
CC2651R31T0RKPR.A	Active	Production	VQFN (RKP)   40	3000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2651 R31
CC2651R31T0RKPR.B	Active	Production	VQFN (RKP)   40	3000   LARGE T&R	Yes	NIPDAU	Level-3-260C-168 HR	-40 to 105	CC2651 R31

<sup>(1)</sup> Status: For more details on status, see our product life cycle.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

<sup>(2)</sup> Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

<sup>(4)</sup> Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.



# PACKAGE OPTION ADDENDUM

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# **PACKAGE MATERIALS INFORMATION**

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# TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
CC2651R31T0RGZR	VQFN	RGZ	48	2500	330.0	16.4	7.3	7.3	1.1	12.0	16.0	Q2
CC2651R31T0RKPR	VQFN	RKP	40	3000	330.0	12.4	5.3	5.3	1.1	8.0	12.0	Q2

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# \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
CC2651R31T0RGZR	VQFN	RGZ	48	2500	367.0	367.0	35.0
CC2651R31T0RKPR	VQFN	RKP	40	3000	367.0	367.0	35.0

7 x 7, 0.5 mm pitch

PLASTIC QUADFLAT PACK- NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.

4224671/A



PLASTIC QUADFLAT PACK- NO LEAD



#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.



PLASTIC QUADFLAT PACK- NO LEAD



NOTES: (continued)

- 4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- 5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



PLASTIC QUADFLAT PACK- NO LEAD



NOTES: (continued)

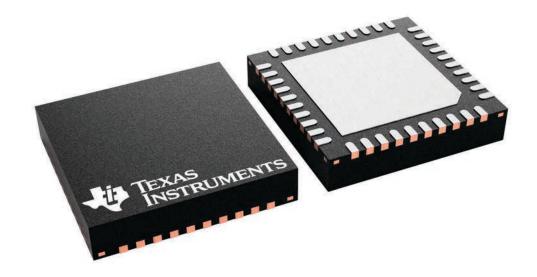
6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



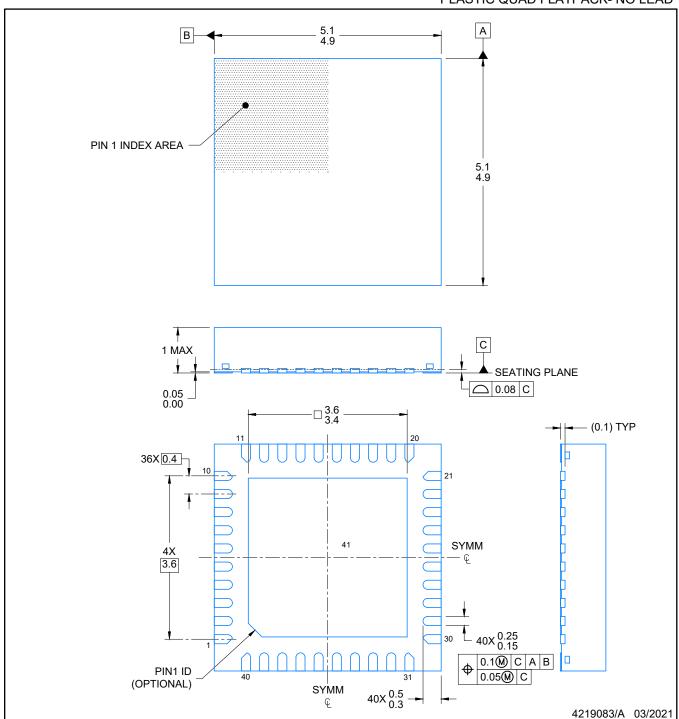
5 x 5, 0.4 mm pitch

PLASTIC QUAD FLATPACK - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



PLASTIC QUAD FLATPACK- NO LEAD

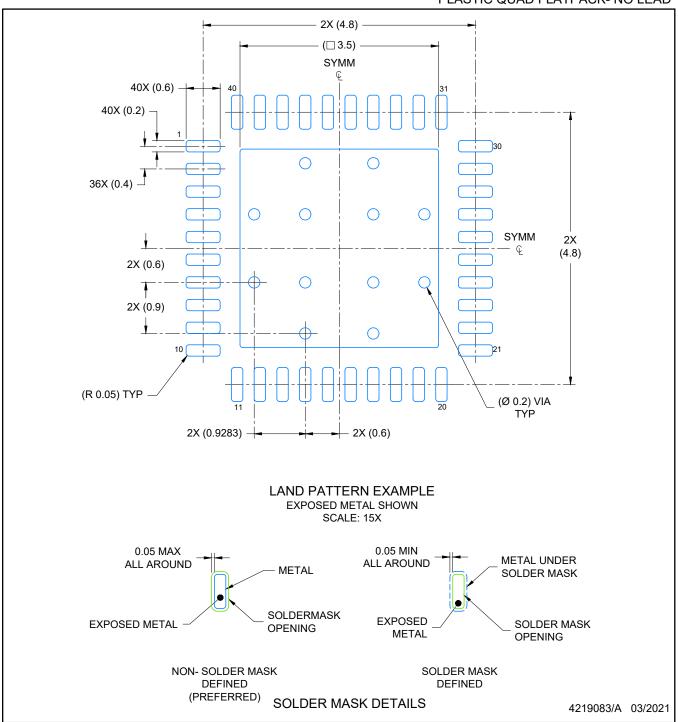


#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.



PLASTIC QUAD FLATPACK- NO LEAD

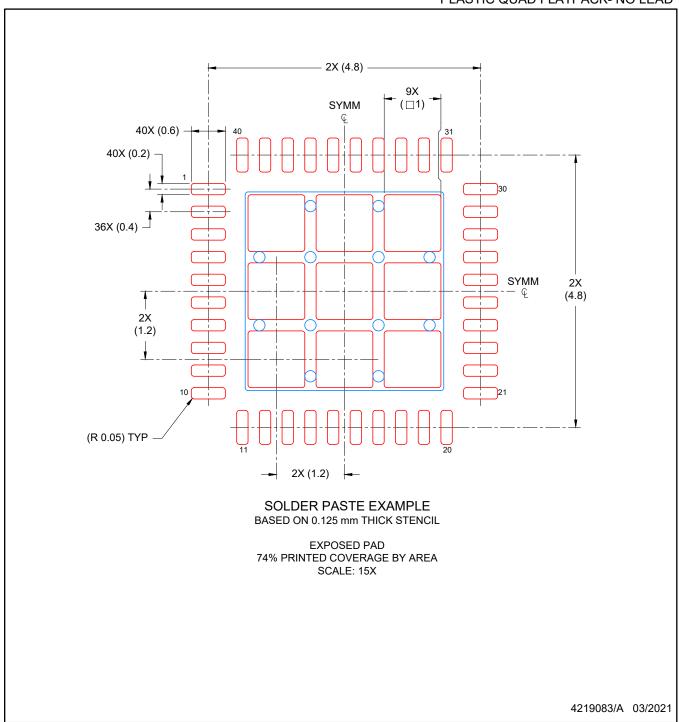


NOTES: (continued)

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PLASTIC QUAD FLATPACK- NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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