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ZHCSEX1A - MARCH 2016-REVISED APRIL 2016

bq27220 单节 CEDV 电量监测计

Technical

Documents

1 特性

- 单节串联锂离子电池电量监测计
 - 驻留在电池组或系统主板上
 - 支持嵌入式或可拆除电池
 - 由集成低压降稳压器 (LDO) 的电池直接供电
 - 支持低值 (10mΩ) 外部感测电阻
- 超低功耗:正常模式下为 50µA,休眠模式下为 9µA
- 基于补偿放电结束电压 (CEDV) 技术的电池电量监测
 - 用平滑滤波器报告剩余电量和充电状态 (SOC)
 - 针对电池老化、自放电以及温度和速率变化进行 自动调节
 - 提供电池健康(老化)状况的估计
- 微控制器外设支持:
 - 400kHz I²C™串行接口
 - 可配置的 SOC 中断或 电池低电量数字输出警告
 - 内部温度传感器、 主机报告的温度或 外部热敏电阻

2 应用

- 智能手机和功能手机
- 平板电脑
- 可穿戴产品
- 楼宇自动化
- 便携式医疗/工业手持终端
- 便携式音频设备
- 游戏机

3 说明

Tools &

Software

德州仪器 (TI) bq27220 电池电量监测计是一款单节电 池电量监测计,只需进行少量用户配置和系统微控制器 固件开发工作即可快速实现系统调通。 bq27220 器件 采用补偿放电结束电压 (CEDV) 算法进行电量检测, 可提供诸如剩余电量 (mAh)、充电状态 (%)、续航时间 (分钟)、电池电压 (mV)、温度 (℃) 和健康状况 (%) 等信息。

Support &

Community

2.2

bq27220 电池电量监测计在正常模式 (50μA) 和休眠模式 (9μA) 下均具有超低功耗,有助于延长电池运行时间。可配置中断有助于节省系统功耗,释放主机使其停止继续轮询。外部热敏电阻为精确温度感测提供支持。

客户可以使用 ROM 中预载的 CEDV 参数,或者使用 通过 TI 网络工具 GAUGEPARCAL 生成的定制化学参 数。生成的定制参数可在系统上电时通过主机编程到器 件 RAM 中,客户也可以将该参数编程到板载一次性可 编程 (OTP) 存储器中。

通过 bq27220 器件进行电池电量监测时,只需将 PACK+ (P+) 与 PACK- (P-) 连接至可拆卸电池组或嵌 入式电池电路即可。微型 9 焊球、1.62mm × 1.58mm、间距为 0.5mm 的 NanoFree™芯片级封装 (DSBGA),是空间受限类应用的 理想选择。

	器件信息 ⁽¹⁾	
器件型号	封装	封装尺寸 (标称值)
bq27220	YZF (9)	1.62mm x 1.58mm

(1) 要了解所有可用封装,请见数据表末尾的可订购产品附录。



An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.



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4 修订历史记录

日期	修订版本	注释
2016 年 4 月	А	"产品预览"至"量产数据"

www.ti.com.cn



5 Pin Configuration and Functions





Bottom View



Pin Functions

PIN		TYPE	DESCRIPTION		
NAME	NUMBER	ITPE	DESCRIPTION		
BAT	C3	PI, AI ⁽¹⁾	LDO regulator input and battery voltage measurement input. Kelvin sense connect to the positive battery terminal (PACKP). Connect a capacitor (1 μF) between BAT and V _{SS} . Place the capacitor close to the gauge.		
BIN	B1	DI	Battery insertion detection input. If OpConfig [BI_PU_EN] = 1 (default), a logic low on the pin is detected as battery insertion. For a removable pack, the BIN pin can be connected to V_{SS} through a pulldown resistor on the pack, typically the 10-k Ω thermistor; the system board should use a 1.8-M Ω pullup resistor to V_{DD} to ensure the BIN pin is high when a battery is removed. If the battery is embedded in the system or in the pack, it is recommended to leave [BI_PU_EN] = 1 and use a 10-k Ω pulldown resistor from BIN to V_{SS} . If [BI_PU_EN] = 0, then the host must inform the gauge of battery insertion and removal with the BAT_INSERT and BAT_REMOVE subcommands. A 10-k Ω pulldown resistor should be placed between BIN and V_{SS} , even if this pin is unused. NOTE: The BIN pin must not be shorted directly to V_{CC} or V_{SS} and any pullup resistor on the BIN pin must be connected only to V_{DD} and not an external voltage rail. If an external thermistor is used for temperature input, the thermistor should be connected between this pin and V_{SS} .		

(1) IO = Digital input-output, AI = Analog input, P = Power connection

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XAS

Pin Functions (continued)

PIN		TVDE	DESCRIPTION		
NAME	NUMBER	ITPE	DESCRIPTION		
GPOUT	A1	DO	This open-drain output can be configured to indicate BAT_LOW when the OpConfig [BATLOWEN] bit is set. By default [BATLOWEN] is cleared and this pin performs an interrupt function (SOC_INT) by pulsing for specific events, such as a change in state-of-charge. Signal polarity for these functions is controlled by the [GPIOPOL] configuration bit. This pin should not be left floating, even if unused; therefore, a 10-k Ω pullup resistor is recommended. If the device is in SHUTDOWN mode, toggling GPOUT makes the gauge exit SHUTDOWN. It is recommended to connect GPOUT to a GPIO of the host MCU so that in case of any inadvertent shutdown condition, the gauge can be commanded to come out of SHUTDOWN.		
SCL	A3	DIO	Slave I ² C serial bus for communication with system (Master). Open-drain pins. Use with external		
SDA A2		DIO	10-k Ω pullup resistors (typical) for each pin. If the external pullup resistors will be disconnected from these pins during normal operation, recommend using external 1-M Ω pulldown resistors to V _{SS} at each pin to avoid floating inputs.		
SRN	C2	AI	Coulomb counter differential inputs expecting an external 10-mΩ, 1% sense resistor. For system-		
SRP C1 AI side configurations, Kelvin sense co the external sense resistor. Kelvin sense resistor with the positive connection side sensing, connect SRP to PACK No calibration is required. The fuel or resistor		AI	side configurations, Kelvin sense connect SRP to the positive battery terminal (PACKP) side of the external sense resistor. Kelvin sense connect SRN to the other side of the external sense resistor with the positive connection to the system (VSYS). For pack-side configurations with low-side sensing, connect SRP to PACK– and SRN to Cell–. See the <i>Simplified Schematic</i> . No calibration is required. The fuel gauge is pre-calibrated for a standard 10-m Ω , 1% sense resistor.		
V _{DD}	B3	PO	1.8-V regulator output. Decouple with a 2.2- μ F ceramic capacitor to V _{SS} . This pin is not intended to provide power for other devices in the system.		
V _{SS}	B2	PI	Ground pin		

6 Specifications

6.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)⁽¹⁾

		MIN	MAX	UNIT
V _{BAT}	BAT pin input voltage range	-0.3	6	V
V	SRP and SRN pins input voltage range	-0.3	V _{BAT} + 0.3	V
VSR	Differential voltage across SRP and SRN. ABS(SRP - SRN)		2	V
V _{DD}	V _{DD} pin supply voltage range (LDO output)	-0.3	2	V
V _{IOD}	Open-drain IO pins (SDA, SCL)	-0.3	6	V
V _{IOPP}	Push-pull IO pins (BIN)	-0.3	V _{DD} + 0.3	V
T _A	Operating free-air temperature range	-40	85	°C
Storage te	mperature, T _{stg}	-65	150	°C

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 ESD Ratings

			VALUE	UNIT
V _(ESD) Electrostatic discharge	Electrostatic	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 ⁽¹⁾	±1500	M
	discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±250	v

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



6.3 Recommended Operating Conditions

$T_A = 30^{\circ}C$ and $V_{BAT} = 3.6$ V (unless otherwise noted)							
			MIN	NOM	MAX	UNIT	
C _{BAT} ⁽¹⁾	External input capacitor for internal LDO between BAT and V_{SS}	Nominal capacitor values specified.		0.1		μF	
C _{LDO18} ⁽¹⁾	External output capacitor for internal LDO between V_{DD} and V_{SS}	capacitor located close to the device.		2.2		μF	
$V_{PU}^{(1)}$	External pullup voltage for open-drain pins (SDA, SCL, GPOUT)		1.62		3.6	V	

(1) Specified by design. Not production tested.

6.4 Thermal Information

		bq27220	
	THERMAL METRIC ⁽¹⁾	YZF (DSBGA)	UNIT
		9 PINS	
R_{\thetaJA}	Junction-to-ambient thermal resistance	64.1	°C/W
R _{0JCtop}	Junction-to-case (top) thermal resistance	59.8	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	52.7	°C/W
ΨJT	Junction-to-top characterization parameter	0.3	°C/W
Ψ_{JB}	Junction-to-board characterization parameter	28.3	°C/W
R _{0JCbot}	Junction-to-case (bottom) thermal resistance	2.4	°C/W

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953

6.5 Supply Current

 $T_A = 30^{\circ}C$ and $V_{BAT} = 3.6 V$ (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{CC}^{(1)}$	NORMAL mode current	I _{LOAD} > Sleep Current ⁽²⁾		50		μA
I _{SLP} ⁽¹⁾	SLEEP mode current	I _{LOAD} < Sleep Current ⁽²⁾		9		μA
I _{SD} ⁽¹⁾	SHUTDOWN mode current	Fuel gauge in host commanded SHUTDOWN mode. (LDO regulator output disabled)		0.6		μA

(1) Specified by design. Not production tested.

(2) Wake Comparator Disabled.

6.6 Digital Input and Output DC Characteristics

 $T_A = -40^{\circ}$ C to 85°C, typical values at $T_A = 30^{\circ}$ C and $V_{BAT} = 3.6$ V (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{IH(OD)}	Input voltage, high ⁽²⁾	External pullup resistor to V_{PU}	V _{PU} × 0.7			V
V _{IH(PP)}	Input voltage, high ⁽³⁾		1.4			V
V _{IL}	Input voltage, low ^{(2) (3)}				0.6	V
V _{OL}	Output voltage, low ⁽²⁾				0.6	V
I _{OH}	Output source current, high ⁽²⁾				0.5	mA
I _{OL(OD)}	Output sink current, low ⁽²⁾				-3	mA
C _{IN} ⁽¹⁾	Input capacitance ⁽²⁾⁽³⁾				5	pF
l _{lkg}	Input leakage current (SCL, SDA, BIN, GPOUT)				1	μA

Specified by design. Not production tested.
 Open Drain pins: (SCL, SDA, GPOUT)

(3) Push-Pull pin: (BIN)

RUMENTS

6.7 LDO Regulator, Wake-up, and Auto-Shutdown DC Characteristics

 $T_A = -40^{\circ}$ C to 85°C, typical values at $T_A = 30^{\circ}$ C and $V_{BAT} = 3.6$ V (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{BAT}	BAT pin regulator input		2.45		4.5	V
V _{DD}	Regulator output voltage			1.85		V
UVLO _{IT+}	V _{BAT} undervoltage lock-out LDO wake-up rising threshold			2		V
UVLO _{IT-}	V _{BAT} undervoltage lock-out LDO auto-shutdown falling threshold			1.95		V
V _{WU+} ⁽¹⁾	GPOUT (input) LDO Wake-up rising edge threshold ⁽²⁾	LDO Wake-up from SHUTDOWN mode	1.2			V

(1) Specified by design. Not production tested.

(2) If the device is commanded to SHUTDOWN via I²C with V_{BAT} > UVLO_{IT+}, a wake-up rising edge trigger is required on GPOUT.

6.8 LDO Regulator, Wake-up, and Auto-shutdown AC Characteristics

$T_A = -40^{\circ}$ C to 85°C, typical values at $T_A = 30^{\circ}$ C and $V_{BAT} = 3.6$ V (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t _{SHDN} ⁽¹⁾	SHUTDOWN entry time	Time delay from SHUTDOWN command to LDO output disable.			250	ms
t _{SHUP} ⁽¹⁾	SHUTDOWN GPOUT low time	Minimum low time of GPOUT (input) in SHUTDOWN before WAKEUP	10			μs
$t_{VDD}^{(1)}$	Initial V _{DD} output delay			13		ms
t _{WUVDD} ⁽¹⁾	Wake-up V_{DD} output delay	Time delay from rising edge of GPOUT (input) to nominal V _{DD} output.		8		ms
t _{PUCD}	Power-up communication delay	Time delay from rising edge of BAT to the Active state. Includes firmware initialization time.		250		ms

(1) Specified by design. Not production tested.

6.9 ADC (Temperature and Cell Measurement) Characteristics

 $T_A = -40^{\circ}$ C to 85°C; typical values at $T_A = 30^{\circ}$ C and $V_{BAT} = 3.6$ V (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{IN(BAT)}	BAT pin voltage measurement range	Voltage divider enabled	2.45		4.5	V
t _{ADC_CONV}	Conversion time			125		ms
	Effective resolution			15		bits

(1) Specified by design. Not tested in production.

6.10 Integrating ADC (Coulomb Counter) Characteristics

 $T_A = -40^{\circ}$ C to 85°C; typical values at $T_A = 30^{\circ}$ C and $V_{BAT} = 3.6$ V (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
V _{SRCM}	Input voltage range of SRN, SRP pins		VSS		V_{BAT}	V
V _{SRDM}	Input differential voltage range of VSRP–VSRN			± 80		mV
t _{SR_CONV}	Conversion time	Single conversion		1		S
	Effective Resolution	Single conversion		16		bits

(1) Specified by design. Not tested in production.

TEXAS INSTRUMENTS

6.11 I²C-Compatible Interface Communication Timing Characteristics

 $T_A = -40^{\circ}$ C to 85°C; typical values at $T_A = 30^{\circ}$ C and $V_{BAT} = 3.6$ V (unless otherwise noted)

			MIN	NOM	MAX	UNIT
Standard	Mode (100 kHz)					
t _{d(STA)}	Start to first falling edge of SCL		4			μs
t _{w(L)}	SCL pulse duration (low)		4.7			μs
t _{w(H)}	SCL pulse duration (high)		4			μs
t _{su(STA)}	Setup for repeated start		4.7			μs
t _{su(DAT)}	Data setup time	Host drives SDA	250			ns
t _{h(DAT)}	Data hold time	Host drives SDA	0			ns
t _{su(STOP)}	Setup time for stop		4			μs
t _(BUF)	Bus free time between stop and start	Includes Command Waiting Time	66			μs
t _f	SCL or SDA fall time ⁽¹⁾				300	ns
t _r	SCL or SDA rise time ⁽¹⁾				300	ns
f _{SCL}	Clock frequency ⁽²⁾				100	kHz
Fast Mod	e (400 kHz)					
t _{d(STA)}	Start to first falling edge of SCL		600			ns
t _{w(L)}	SCL pulse duration (low)		1300			ns
t _{w(H)}	SCL pulse duration (high)		600			ns
t _{su(STA)}	Setup for repeated start		600			ns
t _{su(DAT)}	Data setup time	Host drives SDA	100			ns
t _{h(DAT)}	Data hold time	Host drives SDA	0			ns
t _{su(STOP)}	Setup time for stop		600			ns
t _(BUF)	Bus free time between stop and start	Includes Command Waiting Time	66			μs
t _f	SCL or SDA fall time ⁽¹⁾				300	ns
t _r	SCL or SDA rise time ⁽¹⁾				300	ns
f _{sci}	Clock frequency ⁽²⁾				400	kHz

(1) Specified by design. Not production tested.

(2) If the clock frequency (f_{SCL}) is > 100 kHz, use 1-byte write commands for proper operation. All other transactions types are supported at 400 kHz. (See $\frac{PC}{C}$ Interface and $\frac{PC}{C}$ Command Waiting Time.)



Figure 1. I²C-Compatible Interface Timing Diagram

6.12 SHUTDOWN and WAKE-UP Timing



* GPOUT is configured as an input for wakeup signaling.





6.13 Typical Characteristics



7 Detailed Description

7.1 Overview

The bq27220 fuel gauge accurately predicts the battery capacity and other operational characteristics of a single Li-based rechargeable cell. It can be interrogated by a system processor to provide cell information such as state-of-charge (SoC). The bq27220 monitors charge and discharge activity by sensing the voltage across a small value resistor (10 m Ω typical) between the SRP and SRN pins and in series with the battery. By integrating charge passing through the battery, the battery's SOC is adjusted during battery charge or discharge.

The fuel gauging is derived from the Compensated End of Discharge Voltage (CEDV) method, which uses a mathematical model to correlate remaining state of charge (RSOC) and voltage near to the end of discharge state. This requires a full discharge cycle for a single point FCC update. The implementation models cell voltage (OCV) as a function of battery state of charge (SOC), temperature, and current. The impedance is also a function of SOC and temperature, all of which can be satisfied by using seven parameters: EMF, C0, R0, T0, R1, TC, C1.

NOTE

The following formatting conventions are used in this document:

Commands: italics with parentheses() and no breaking spaces, for example, Control().

Data Flash: italics, bold, and breaking spaces, for example, Design Capacity.

Register bits and flags: italics with brackets [], for example, [TDA]

Data flash bits: italics, bold, and brackets [], for example, [LED1]

Modes and states: ALL CAPITALS, for example, UNSEALED mode.

7.2 Functional Block Diagram (System-Side Configuration)



7.3 Feature Description

Information is accessed through a series of commands called *Standard Commands*. Further capabilities are provided by the additional *Extended Commands* set. Both sets of commands, indicated by the general format *Command*), are used to read and write information within the control and status registers, as well as its data locations. Commands are sent from the system to the gauge using the I²C serial communications engine, and can be executed during application development, system manufacture, or end-equipment operation.

The fuel gauge measures the charging and discharging of the battery by monitoring the voltage across a smallvalue sense resistor. When a cell is attached to the fuel gauge, cell impedance is computed based on cell current, cell open-circuit voltage (OCV), and cell voltage under loading conditions.

The fuel gauge uses an integrated temperature sensor for estimating cell temperature. Alternatively, the host processor can provide temperature data for the fuel gauge.

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Feature Description (continued)

For more details, see the bq27220 Technical Reference Manual (SLUUBD4).

The external temperature sensing is optimized with the use of a high accuracy negative temperature coefficient (NTC) thermistor with R25 = $10.0 \text{ k}\Omega \pm 1\%$. B25/85 = $3435\text{K} \pm 1\%$ (such as Semitec NTC 103AT) on the BIN pin. Alternatively, the bq27220 can also be configured to use its internal temperature sensor or receive temperature data from the host processor. The bq27220 uses temperature to monitor the battery-pack environment, which is used for fuel gauging and cell protection functionality.

7.3.1 Communications

7.3.1.1 ^PC Interface

The fuel gauge supports the standard I²C read, incremental read, quick read, one-byte write, and incremental write functions. The 7-bit device address (ADDR) is the most significant 7 bits of the hex address and is fixed as 1010101. The first 8 bits of the I²C protocol are, therefore, 0xAA or 0xAB for write or read, respectively.



(e) incremental write

(S = Start, Sr = Repeated Start, A = Acknowledge, N = No Acknowledge, and P = Stop).

Figure 6. I²C Interface Read and Write Functions

The quick read returns data at the address indicated by the address pointer. The address pointer, a register internal to the I^2C communication engine, increments whenever data is acknowledged by the fuel gauge or the I^2C master. "Quick writes" function in the same manner and are a convenient means of sending multiple bytes to consecutive command locations (such as two-byte commands that require two bytes of data).

The following command sequences are not supported:

	, , , , , , , , , , , , , , , , , , , ,	1 1					<u> </u>
s	ADDR[6:0]	A 0	CMD[7:0]	A	DATA[7:0]	Ν	P
				1	r <i></i>		5-1

Figure 7. Attempt to Write a Read-Only Address (NACK After Data Sent By Master)

	~			1	
S ADDR[6:0]	0	A	CMD[7:0]	I N	ľР
	رتجا			1	K-I

Figure 8. Attempt to Read an Address Above 0x6B (NACK Command)

7.3.1.2 *P*C Time Out

The I^2C engine releases both SDA and SCL if the I^2C bus is held low for 2 seconds. If the fuel gauge is holding the lines, releasing them frees them for the master to drive the lines. If an external condition is holding either of the lines low, the I^2C engine enters the low-power SLEEP mode.



Feature Description (continued)

7.3.1.3 PC Command Waiting Time

To ensure proper operation at 400 kHz, a $t_{(BUF)} \ge 66 \ \mu s$ bus-free waiting time must be inserted between all packets addressed to the fuel gauge. In addition, if the SCL clock frequency (f_{SCL}) is > 100 kHz, use individual 1-byte write commands for proper data flow control. Figure 9 shows the standard waiting time required between issuing the control subcommand the reading the status result. For read-write standard commands, a minimum of 2 seconds is required to get the result updated. For read-only standard commands, there is no waiting time required, but the host must not issue any standard command more than two times per second. Otherwise, the gauge could result in a reset issue due to the expiration of the watchdog timer.

S	ADDR [6:0] 0	A	CMD [7:0]] A [DATA [7:0]	AP	<mark>66μs</mark>				
S	ADDR [6:0] 0	A	CMD [7:0]	A	DATA [7:0]	AP	<mark>66μs</mark>				
S	ADDR [6:0] 0	A	CMD [7:0]	AS	ADDR [6:0	0] 1 A	DATA [7:0]	A	DATA [7:0]	N P	66µs
	Wa	itina t	ime inserted bet	ween tw	vo 1-bvte write	packets for	a subcomman	d and rea	dina results		

(required for 100 kHz < $f_{scl} \le 400$ kHz)

S ADDR [6:0]	0 A	CMD [7:0]	А	DATA [7:0]	A	DATA [7:0]	ΑP	66µs		
S ADDR [6:0]	0 A	CMD [7:0]	A Sr	ADDR [6:0]	1	A DATA [7:0]] [A]	DATA [7:0)] N P	66µs

Waiting time inserted between incremental 2-byte write packet for a subcommand and reading results

(acceptable for $f_{SCL} \leq 100 \text{ kHz}$)

	S ADDR [6:0]	0 A	CMD [7:0]	AS	r ADDR	[6:0] , 1 A	DATA [7:0]	A	DATA [7:0]	A
ſ	DATA [7:0]	A	DATA [7:0]	N P	66µs					

Waiting time inserted after incremental read

Figure 9. Standard Waiting Time

7.3.1.4 $m \ell^2 C$ Clock Stretching

A clock stretch can occur during all modes of fuel gauge operation. In SLEEP mode, a short \leq 100-µs clock stretch occurs on all I²C traffic as the device must wake-up to process the packet. In the other modes (INITIALIZATION, NORMAL), a \leq 4-ms clock stretching period may occur within packets addressed for the fuel gauge as the I²C interface performs normal data flow control.

7.4 Device Functional Modes

To minimize power consumption, the fuel gauge has several power modes: INITIALIZATION, NORMAL, and SLEEP. The fuel gauge passes automatically between these modes, depending upon the occurrence of specific events, though a system processor can initiate some of these modes directly. For more details, see the *bq27220 Technical Reference Manual* (SLUUBD4).

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8 Application and Implementation

NOTE

Information in the following application section is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The bq27220 fuel gauge is a microcontroller peripheral that provides system-side or pack-side fuel gauging for single-cell Li-Ion batteries. The device requires minimal configuration and uses One-Time Programmable (OTP) Non-Volatile Memory (NVM). Battery fuel gauging with the fuel gauge requires connections only to PACK+ and PACK– for a removable battery pack or embedded battery circuit. To allow for optimal performance in the end application, special considerations must be taken to ensure minimization of measurement error through proper printed circuit board (PCB) board layout. Such requirements are detailed in *Design Requirements*.

8.2 Typical Applications



Figure 10. Typical Application for Pack-Side Using Low-Side Sensing

8.2.1 Design Requirements

As shipped from the Texas Instruments factory, many bq27220 parameters in OTP NVM are left in the unprogrammed state (zero). This partially programmed configuration facilitates customization for each end application. Upon device reset, the contents of OTP are copied to associated volatile RAM-based data memory blocks. For proper operation, all parameters in RAM-based data memory require initialization — either by updating data memory parameters in a lab/evaluation situation or by programming the OTP for customer production. The *bq27220 Technical Reference Manual* (SLUUBD4) shows the default value and a typically expected value appropriate for most of applications.



Typical Applications (continued)

8.2.2 Detailed Design Procedure

8.2.2.1 BAT Voltage Sense Input

A ceramic capacitor at the input to the BAT pin is used to bypass AC voltage ripple to ground, greatly reducing its influence on battery voltage measurements. It proves most effective in applications with load profiles that exhibit high-frequency current pulses (that is, cell phones) but is recommended for use in all applications to reduce noise on this sensitive high-impedance measurement node.

8.2.2.2 Integrated LDO Capacitor

The fuel gauge has an integrated LDO with an output on the V_{DD} pin of approximately 1.8 V. A capacitor with a value of at least 2.2 μ F should be connected between the V_{DD} pin and V_{SS} . The capacitor must be placed close to the gauge IC and have short traces to both the V_{DD} pin and V_{SS} . This regulator must not be used to provide power for other devices in the system.

8.2.2.3 Sense Resistor Selection

Any variation encountered in the resistance present between the SRP and SRN pins of the fuel gauge will affect the resulting differential voltage, and derived current, that it senses. As such, it is recommended to select a sense resistor with minimal tolerance and temperature coefficient of resistance (TCR) characteristics. The standard recommendation based on the best compromise between performance and price is a 1% tolerance, 50-ppm drift sense resistor with a 1-W power rating.

8.2.3 External Thermistor Support

The fuel gauge temperature sensing circuitry is designed to work with a negative temperature coefficient-type (NTC) thermistor with a characteristic 10-k Ω resistance at room temperature (25°C). The default curve-fitting coefficients configured in the fuel gauge specifically assume a Semitec 103AT type thermistor profile and so that is the default recommendation for thermistor selection purposes. Moving to a separate thermistor resistance profile (for example, JT-2 or others) requires an update to the default thermistor coefficients, which can be modified in RAM to ensure highest accuracy temperature measurement performance.

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Typical Applications (continued)

8.2.4 Application Curves





9 Power Supply Recommendation

9.1 Power Supply Decoupling

The battery connection on the BAT pin is used for two purposes:

- To supply power to the fuel gauge, and
- To provide an input for voltage measurement of the battery.

A capacitor of value of at least 1 μ F should be connected between BAT and V_{SS}. The capacitor must be placed close to the gauge IC and have short traces to both the BAT pin and V_{SS}.

The fuel gauge has an integrated LDO with an output on the V_{DD} pin of approximately 1.8 V. A capacitor of value of at least 2.2 μ F should be connected between the V_{DD} pin and V_{SS}. The capacitor must be placed close to the gauge IC and have short traces to both the V_{DD} pin and V_{SS}. This regulator must not be used to provide power for other devices in the system.

10 Layout

10.1 Layout Guidelines

- A capacitor of value of at least 2.2 µF is connected between the V_{DD} pin and V_{SS}. The capacitor must be
 placed close to the gauge IC and have short traces to both the V_{DD} pin and V_{SS}. This regulator must not be
 used to provide power for other devices in the system.
- It is required to have a capacitor of at least 1.0 µF connect between the BAT pin and V_{SS} if the connection between the battery pack and the gauge BAT pin has the potential to pick up noise. The capacitor should be placed close to the gauge IC and have short traces to both the BAT pin and V_{SS}.
- If the external pullup resistors on the SCL and SDA lines will be disconnected from the host during low-power operation, it is recommended to use external 1-MΩ pulldown resistors to V_{SS} to avoid floating inputs to the I²C engine.
- The value of the SCL and SDA pullup resistors should take into consideration the pullup voltage and the bus capacitance. Some recommended values, assuming a bus capacitance of 10 pF, can be seen in Table 1.

VPU	1.8 V		3.3 V		
P	Range	Typical	Range	Typical	
К _{РU}	$400 \ \Omega \leq R_PU \leq 37.6 \ k\Omega$	10 kΩ	900 $\Omega \le R_{PU} \le 29.2 \text{ k}\Omega$	5.1 kΩ	

Table 1. Recommended Values for SCL and SDA Pullup Resistors

- If the host is not using the GPOUT functionality, then it is recommended that GPOUT be connected to a GPIO of the host so that in the cases where the device is in SHUTDOWN, toggling GPOUT can wake the gauge from the SHUTDOWN state.
- If the battery pack thermistor is not connected to the BIN pin, the BIN pin should be pulled down to V_{SS} with a 10-k Ω resistor.
- The BIN pin should not be shorted directly to V_{DD} or V_{SS}.
- The actual device ground is pin B2 (V_{SS}).
- The SRP and SRN pins should be Kelvin connected to the R_{SENSE} terminals. SRP to the battery pack side of R_{SENSE} and SRN to the system side of the R_{SENSE}.
- Kelvin connect the BAT pin to the battery PACKP terminal.

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10.2 Layout Example







11 器件和文档支持

11.1 文档支持

11.1.1 相关文档

- 《bq27220 技术参考》手册(文献编号: SLUUBD4)
- 《bg27220 快速入门指南》(文献编号: SLUUAP7)
- 《单节电池电量监测计电路设计》(SLUA456)
- 《bq27500 和 bq27501 主要设计注意事项》(SLUA439)
- 《手持式电池电子产品中的 ESD 和 RF 迁移》(SLUA460)

11.2 社区资源

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

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Design Support TI's Design Support Quickly find helpful E2E forums along with design support tools and contact information for technical support.

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ESD 的损坏小至导致微小的性能降级,大至整个器件故障。精密的集成电路可能更容易受到损坏,这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

11.5 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

12 机械、封装和可订购信息

以下页中包括机械、封装和可订购信息。这些信息是针对指定器件可提供的最新数据。这些数据会在无通知且不对 本文档进行修订的情况下发生改变。欲获得该数据表的浏览器版本,请查阅左侧的导航栏。



PACKAGING INFORMATION

Orderable part number	Status	Material type	Package Pins	Package qty Carrier	RoHS	Lead finish/	MSL rating/	Op temp (°C)	Part marking
	(1)	(2)			(3)	Ball material	Peak reflow		(6)
						(4)	(5)		
BQ27220YZFR	Active	Production	DSBGA (YZF) 9	3000 LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ27220
BQ27220YZFR.A	Active	Production	DSBGA (YZF) 9	3000 LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ27220
BQ27220YZFT	Active	Production	DSBGA (YZF) 9	250 SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ27220
BQ27220YZFT.A	Active	Production	DSBGA (YZF) 9	250 SMALL T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ27220

⁽¹⁾ **Status:** For more details on status, see our product life cycle.

⁽²⁾ Material type: When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ RoHS values: Yes, No, RoHS Exempt. See the TI RoHS Statement for additional information and value definition.

⁽⁴⁾ Lead finish/Ball material: Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ MSL rating/Peak reflow: The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ Part marking: There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal													
	Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
	BQ27220YZFR	DSBGA	YZF	9	3000	180.0	8.4	1.78	1.78	0.69	4.0	8.0	Q1
ſ	BQ27220YZFT	DSBGA	YZF	9	250	180.0	8.4	1.78	1.78	0.69	4.0	8.0	Q1



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PACKAGE MATERIALS INFORMATION

31-Jul-2023



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ27220YZFR	DSBGA	YZF	9	3000	182.0	182.0	20.0
BQ27220YZFT	DSBGA	YZF	9	250	182.0	182.0	20.0

YZF0009



PACKAGE OUTLINE

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.



YZF0009

EXAMPLE BOARD LAYOUT

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



NOTES: (continued)

 Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. See Texas Instruments Literature No. SNVA009 (www.ti.com/lit/snva009).



YZF0009

EXAMPLE STENCIL DESIGN

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.



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